

Cost-Efficient Laparoscopic Haptic Trainer based on Affine Velocity Analysis.

Charles Barnouin, Benjamin de Witte, Richard Moreau, Arnaud Lelevé, Xavier Martin

▶ To cite this version:

Charles Barnouin, Benjamin de Witte, Richard Moreau, Arnaud Lelevé, Xavier Martin. Cost-Efficient Laparoscopic Haptic Trainer based on Affine Velocity Analysis.. Surgetica 2017, Nov 2017, Strasbourg, France. hal-01563262

HAL Id: hal-01563262 https://hal.science/hal-01563262v1

Submitted on 4 Feb 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



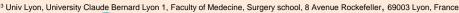
libm

Cost-Efficient Laparoscopic Haptic Trainer Based on Affine Velocity Analysis



Barnouin C.1, De Witte B.2, Moreau R.1, Leleve A.1, Martin X.3

¹ Univ Lyon, INSA Iyon, Ampère-UMR CNRS 5005, 25 av. Jean Capelle ouest-F- 69621 Villeurbanne Cedex, France. ² Univ Lyon, University Claude Bernard Lyon 1, Inter-University Laboratory of Human Movement Science. 27-29 Boulevard du 11 Novembre 1918, 69622, Villeurbanne cedex, France.









Surgetica 2017

sam€ei INTRODUCTION

- ❖ Learning minimal invasive surgery (MIS) skills is young surgeons' major concern.
- ❖ Cognitive load elicited by simulators' use and trainees' spatial abilities seem to impact efficient learning process⁽¹⁾.
- Objectives: design a basic skill training simulator which objectively evaluate trainees' level.
- ❖ Use of Affine velocity(2-3) as assessment variable.

Step 1 - Cognitive conception

Observation and analyses of surgeons in situ





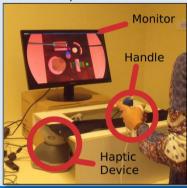
Inclusion of literatures' recommendations



METHODS

Step 2 - Simulator conception

Use of materials enabling haptic feedback and developing a VR environment (Phantom Omni, CHAI3D, laparoscopic devices...)



Step 3 - Simulator validation

Define assessment variables to evaluate the trajectory:

- Time taken to complete the level
- Number of errors (collisions)
- Affine Velocity



WHAT IS AFFINE VELOCITY

Relationship between geometry and kinematic first shown in 2D drawing:

$$v = v_a K^{-1/3}$$

With the curvature K



New power law for 3D movement:

$$v = v_a K^{\alpha} |\tau^{\beta}|$$

- \bullet With the torsion au
- α and β are exponents that depend of the studied movement

Logarithmic linearization to find α and β for laparoscopic gesture : $\alpha = -0.048$, $\beta = -0.0026$

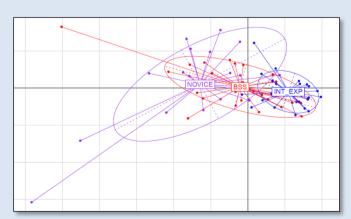
RESULTS

Panel of 77 subjects separated initially into 4 groups :

- Expert surgeon: more than 100 interventions
- Intermediate : between 5 and 20
- · Unexperienced intern (BSS): witnessed but never performed
- Novice

	Intern	Expert	Intermediate
Expert	P<0.05	-	-
Intermediate	P<0.05	0.43	-
Novice	P<0.05	P<0.05	P<0.05

Statistical test Kruskal and Wallis on affine velocity (above) can separate every groups but Experts and Intermediates, whereas collision alone could also not separate Novices from Unexperience Interns.



PCA with Expert and Intermediate fused with variables Collision, Time, and Affine Velocity

CONCLUSION

- A cognitive analysis of MIS enables to design a reliable and valid simulator.
- Affine velocity is a valid tool and another objective variable to evaluate a trainee skill on his trajectory.
- Once a certain level of skill is reached, it becomes harder to differentiate individuals.
- As feedback about skill level is displayed, the simulator should be effective in learning, this needs however to be confirmed by future investigations.

- J. J. Van Merriënboer and J. Sweller, "Cognitive load theory in health professional education: design principles and strategies," Medical education, vol. 44, no. 1, pp. 85–93, 2010.
 F. E. Pollick and G. Sapiro, "Constant affine velocity predicts the 13 power law of planar motion perception and generation," Vision research, vol. 37, no. 3, pp. 347–353, 1997.
 J. Cifuentes, P. Boulanger, M. T. Pham, R. Moreau, and F. Prieto, "Automatic gesture analysis using constant affine velocity," in Engineering in Medicine and Biology Society (EMBC), 2014 36th Annual International Conference of the IEEE, pp. 1826–1829, IEEE, 2014.