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Galaxy populations in massive galaxy clusters to $z = 1.1$: colour **distribution, concentration, halo occupation number and red sequence fraction**

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ABSTRACT

We study the galaxy populations in 74 Sunyaev–Zeldovich effect selected clusters from the South Pole Telescope survey, which have been imaged in the science verification phase of the Dark Energy Survey. The sample extends up to $z \sim 1.1$ with 4×10^{14} M_{$\odot \leq M_{200} \leq$} 3×10^{15} M. Using the band containing the 4000 Å break and its redward neighbour, we study the colour–magnitude distributions of cluster galaxies to ∼*m*[∗] + 2, finding that: (1)The intrinsic rest frame *g* − *r* colour width of the red sequence (RS) population is ∼0.03 out to *z* ∼ 0.85 with a preference for an increase to ∼0.07 at *z* = 1, and (2) the prominence of the RS declines beyond *z* ∼ 0.6. The spatial distribution of cluster galaxies is well described by the NFW profile out to $4R_{200}$ with a concentration of $c_g = 3.59_{-0.18}^{+0.20}$, $5.37_{-0.24}^{+0.27}$ and $1.38_{-0.19}^{+0.21}$ for the full, the RS and the blue non-RS populations, respectively, but with ∼40 per cent to 55 per cent cluster to cluster variation and no statistically significant redshift or mass trends. The number of galaxies within the virial region N_{200} exhibits a mass trend indicating that the number of galaxies per unit total mass is lower in the most massive clusters, and shows no significant redshift trend. The RS fraction within R_{200} is (68 \pm 3) per cent at $z = 0.46$, varies from ∼55 per cent at *z* = 1 to ∼80 per cent at *z* = 0.1 and exhibits intrinsic variation among clusters of ∼14 per cent. We discuss a model that suggests that the observed redshift trend in RS fraction favours a transformation time-scale for infalling field galaxies to become RS galaxies of 2–3 Gyr.

Key words: galaxies: clusters: general – galaxies: clusters: individual – galaxies: evolution – galaxies: formation – galaxies: luminosity function, mass function.

1 INTRODUCTION

Galaxy clusters were first systematically cataloged based on optical observations (Abell 1958; Zwicky et al. 1961). These clusters were primarily nearby systems, and they were mainly characterized by their richness, compactness and distance. Today, other techniques are widely used for detecting galaxy clusters. One of the most widely used techniques is based upon an observational signature that arises through the interaction of the hot intra-cluster medium with the low-energy cosmic-microwave-background (CMB) photons. This so-called thermal Sunyaev–Zel'dovich effect (SZE) is a spectral distortion of the CMB due to inverse-Compton scattering of CMB photons with the energetic galaxy cluster electrons (Sunyaev & Zel'dovich 1972). The surface brightness of the SZE is independent of redshift, and the integrated thermal SZE signature is expected to be tightly correlated with the cluster virial mass (e.g. Holder, Haiman & Mohr 2001; Andersson et al. 2011).

Using the SZE for cluster selection allows us to identify high purity, approximately mass-limited cluster samples that span the full redshift range over which galaxy clusters exist (Song et al. 2012b; Bleem et al. 2015). Together with the multiband optical data, these cluster samples enable studies of galaxy cluster properties, including the luminosity function of the cluster galaxies, the stellar mass fraction, the radial profile and the distribution of galaxy colour (e.g. Mancone et al. 2010; Zenteno et al. 2011; Mancone et al. 2012; Hilton et al. 2013; Chiu et al. 2016). These measurements allow us to gain insight into galaxy formation and evolution, and to assess the degree to which these processes are affected by environment and vary over cosmic time (e.g. Butcher & Oemler 1984; Stanford, Eisenhardt & Dickinson 1998; Lin et al. 2006; Brodwin et al. 2013; van der Burg et al. 2015).

A picture of the galaxy populations, inside and outside the clusters, has emerged where the stellar mass functions for the passive and star-forming galaxies are independent of environment, but the mix of these populations changes as one moves from the field to the cluster (e.g. Muzzin et al. 2012; see also Binggeli, Sandage & Tammann 1988; Jerjen & Tammann 1997; Andreon 1998). The redshift variation of the red fraction has been shown to provide constraints on the time-scales on which infalling field galaxies are transformed to red sequence (RS) galaxies (McGee et al. 2009). Moreover, the scatter of the RS and its variation with redshift has been used to constrain the variation in star formation histories and the time-scale since the formation of the bulk of stars within RS galaxies (e.g. Aragon-Salamanca et al. 1993; Stanford et al. 1998; Hilton et al. 2009; Mei et al. 2009; Papovich et al. 2010).

The use of a homogeneously selected cluster sample extending over a broad redshift range, which has a relatively uniform depth and multiband imaging, enables one to carry out a systematic study of the population variations as a function of redshift and cluster mass. This homogeneity allows us to compare high-*z* and low-*z* clusters without having to resort to combining our sample with those in the literature, an approach that is complicated by differences in analysis techniques and methods used to estimate cluster properties. Moreover, the selection of the cluster sample using a method that is independent of the galaxy populations makes for a more straightforward interpretation of the observed properties of the cluster galaxies and their evolution.

In this paper, we report on our analysis of the colour distribution and the radial profile of the cluster galaxy population through examination of the full population, the RS population and the non-RS or blue population. Our primary goal is to understand how the cluster galaxy populations change with redshift and cluster mass. We focus on magnitudes and colours that are extracted from similar portions of the rest-frame spectrum over the full redshift range.

Our sample arises from the overlap between the Dark Energy Survey (DES Collaboration 2005) science verification (DES-SV) data and the existing South Pole Telescope (SPT) 2500 deg^2 mmwave survey (SPT-SZ; e.g. Story et al. 2013). The sample of SPT-SZ cluster candidates overlapping the DES-SV data contains 74 clusters. Our analysis follows the optical study of the first four SZEselected clusters in Zenteno et al. (2011), and is complementary to the analysis of the 26 most massive clusters extracted from the full SPT survey (Zenteno et al. 2016).

This paper is organized as follows: Section 2 describes the DES-SV observations and data reduction as well as the SPT-selected cluster sample. In Section 3, we describe the cluster sample properties, presenting redshifts and masses. In Section 4, we present measurements of the radial and colour distributions. We end with the conclusions in Section 5.

In this work, unless otherwise specified, we assume a flat Λ cold dark matter cosmology. The cluster masses refer to M_{200c} , the mass enclosed within a virial sphere of radius R_{200} , in which the mean matter density is equal to 200 times the critical density at the observed cluster redshift. The critical density is $\rho_c(z) = 3H^2(z)/8\pi G$, where $H(z)$ is the Hubble parameter. We use the best-fitting cosmological parameters from Bocquet et al. (2015): $\Omega_{\rm m} = 0.292$ and $H_0 = 68.6 \text{ km s}^{-1} \text{Mpc}^{-1}$; these are derived through a combined analysis of the SPT cluster population, the *Wilkinson Microwave Anisotropy Probe* (*WMAP*) constraints on the CMB anisotropy, supernovae distance measurements and baryon acoustic oscillation distance measurements.

2 OBSERVATIONS AND DATA REDUCTION

There are 74 clusters detected by SPT with the signal-to-noise ratio $\xi > 4.5$, which are imaged within the DES-SV data and have deep photometric coverage around the cluster position. Below, we describe how the sample of 74 multiband co-adds, and associated calibrated galaxy catalogues are produced.

2.1 DECam data processing and calibration

The DES-SV observations were acquired between 2012 November 1 and 2013 February 22 using the Dark Energy Camera (DECam; Flaugher et al. 2015). The data were processed with an improved version of the pipeline used to process the Blanco Cosmology Survey Data (Desai et al. 2012), which has its heritage in the early DES data management system (Ngeow et al. 2006; Mohr et al. 2008, 2012). Following a data flow similar to that adopted for the BCS processing, we process data from every night using the single-epoch pipeline. The raw data from the telescope are first crosstalk-corrected. For DECam, the crosstalk matrix includes negative coefficients and also non-linear corrections for certain CCDs/amplifiers. Single-epoch images are then produced through a bias subtraction and dome flat correction. We implement a pixel scale correction to reduce the positional variation in the zero-point or, equivalently, to flatten the zero-point surface within the individual CCD detectors. No illumination or fringe corrections are applied; we adopt a star flat procedure to photometrically flatten the images. In particular, we stack DES-SV stellar photometry from photometric observations in detector coordinates and determine for each band the persistent photometric residual in stellar photometry as a function of position. We use this to create a position dependent photometric scalefactor that further flattens the zero-point surface within each detector and also brings all detectors to a common zero-point (see also Regnault et al. 2009; Schlafly et al. 2012).

First pass astrometric calibration is carried out exposure by exposure using the SCAMP Astromatic software (Bertin 2006) and by calibrating to the 2MASS catalogue (Skrutskie et al. 2006). In this approach, we use as input a high-quality distortion map for the detector that we determine through a SCAMP run of a large collection of overlapping exposures. The residual scatter of our first pass astrometry around 2MASS is approximately 200 milli-arcsec, which is dominated by the 2MASS positional uncertainties. In a second pass prior to the co-addition, we recalibrate the astrometry using SCAMP and the full collection of overlapping DECam images around a particular area of interest on the sky (i.e. where there is a known SPT cluster). This reduces the relative root mean square internal astrometric scatter around the best fit to 20 milliarcsec, which is a factor of a few improvements over the internal scatter in the first pass calibration. For the data used in these analyses, we find the first pass astrometric solution to be adequate for our needs.

Cataloguing is carried out using the model-fitting capabilities of SEXTRACTOR (Bertin & Arnouts 1996), where we create position dependent point spread function (PSF) models for each image using PSFEX, and then use these PSF models to evaluate a variety of customized, PSF-corrected model magnitudes, object positions, morphology measures and star–galaxy classifiers.

Once all the data from each night are processed using the singleepoch pipeline, we then photometrically calibrate the data and build co-adds centred around each of the SPT cluster candidates. We determine a relative photometric calibration using common stars within overlapping images. We create median-combined co-add images using PSF homogenization to a common Moffat profile (Moffat 1969) with a full width at half-maximum tuned to be the median of all the input single-epoch images for each band. For co-add cataloguing, we first create a chi-square detection image (Szalay, Connolly & Szokoly 1999) using the *i*- and *z*-band co-add images, and then we catalogue in dual image mode, using a common detection image across all bands. We use catalogues extracted from the PSF homogenized co-add images, because we have identified failure modes in the star–galaxy classification and in the centrally weighted galaxy colours in the non-homogenized co-adds that are caused by discontinuities in the spatial variation of the PSF.

For absolute photometric calibration of the final catalogue, we calibrate the colour differences among different band combinations using the DECam stellar locus, where we first calibrate $(g - r)$ versus($r - i$), and then keeping the $(r - i)$ offset fixed, we calibrate $(r - i)$ versus $(i - z)$. The absolute calibration comes from the 2MASS *J* band. We do not use any *Y*-band data for this analysis.

Figure 1. Distribution of single-epoch photometric repeatability scatter (left-hand panel) for multiple measurements of the same stars in our ensemble of 74 clusters. The bands *griz* have a median scatter of 7.6, 7.6, 7.7 and 8.3 mmag, respectively. The distribution of orthogonal scatter about the stellar locus is shown on the right for three colour–colour spaces. The scatter distributions for these three spaces have a median scatter of 17, 32 and 57 mmag.

To determine the stellar locus in the DECam system, we bootstrap from calibrated SDSS photometry. We do this by determining the colour terms between the DECam and SDSS systems using DECam observations of calibrated stars within the SDSS system. The firstorder colour terms we find are -0.088 , -0.1079 , -0.3080 and −0.0980 for *griz* bands, respectively, where we use the colour *g* − *r* for *g* and *r* bands, and $r - i$ for *i* and *z*. With these colour terms, we then use calibrated SDSS photometry to predict the DECam stellar locus. In this step, we restrict our analysis to those stars with colours that lie in the range where the linear colour correction is accurate at better than 1 per cent. We then use this predicted stellar locus to calibrate the offsets in an empirical DECam stellar locus that we extract from selected high quality observations of a portion of the survey.

For each calibrated tile, we evaluate the quality of the images and catalogues using the scatter around the stellar locus and the scatter obtained from photometric repeatability tests. Fig. 1 (righthand panel) contains a plot of the orthogonal scatter of stars about the stellar locus in three different colour–color spaces $r - i$ versus $i - z$, $g - r$ versus $r - i$, and $g - r$ versus $r - J$. The median scatter about the stellar locus in these three spaces is 17, 32 and 57 mmag, respectively. These values are comparable to the stellar locus scatter in a recent PS1 analysis (Liu et al. 2015) and better than values obtained from the BCS or SDSS data sets (Desai et al. 2012).

In the photometric repeatability tests, we compare the magnitude differences between multiple observations of the same object that are obtained from different single-epoch images that contribute to the co-add tile. Fig. 1 (left-hand panel) contains a plot of the distribution of repeatability scatter for our 74 clusters. We find that the median single-epoch photometry has a bright end repeatability scatter of 7.6, 7.6, 7.7 and 8.3 mmag in bands *griz*, respectively. This compares favourably with the PS1 repeatability scatter of 16– 19 mmag (Liu et al. 2015), and is better than the characteristic BCS scatter of 18–25 mmag (Desai et al. 2012). Co-add tiles with repeatability scatter larger than 20 mmag are re-examined and recalibrated to improve the photometry.

Given the large pointing offset strategy of the data acquisition for DES, each point on the sky is imaged from multiple independent portions of the focal plane. Thus, we expect the systematic floor in the co-add photometry to scale approximately as this single-epoch systematic floor divided by the square root of the number of layers contributing to the co-add. The goal in acquiring the SV data was for it to have full DES depth, corresponding to 10 layers of imaging.

In practice, the median number of exposures per band in the SV region is 6.5–7.5. Thus, in principle, we should expect to achieve a systematic error floor in the relative co-add photometry of around 3 mmag.

For the analyses presented below, we use mag_auto as our estimate of the total galaxy magnitude, and we use mag_detmodel for galaxy colours. The colour estimator mag_detmodel provides an enhanced signal-to-noise estimate of the galaxy colour, which is weighted over the same centrally concentrated and PSF-corrected region of the galaxy in each band. The shape-related systematic errors in measuring galaxy colours and photometry are large compared to the systematics floor in the stellar photometry discussed above.

2.2 Stargalaxy separation

Our photometric catalogues are produced using model fitting photometry on homogenized co-added images, and they therefore contain two different star–galaxy separators: class_star and spread model. To examine the reliability of the separation we look at the values of those two classifiers as a function of magnitude (Desai et al. 2012). class_star contains values between 0 and 1 representing a continuum between resolved and unresolved objects. At magnitudes of ∼20 in the DES data, the galaxy and stellar populations begin to merge, making classification with class_star quite noisy. spread_model values exhibit a strong stellar sequence at spread_model ∼0, whereas galaxies have more positive values. In the case of spread_model, the two sequences start merging at roughly ∼22 magnitude in each band, indicating that spread_model is effective at classifying objects that are approximately an order of magnitude fainter than those that are well classified by class_star. For this reason, we use a spread_model cut for the star/galaxy classification in the *z* band, as it is used as a detection band. Examining the catalogues and noting the location and width of the spread_model stellar sequence, we find that a reliable cut to exclude stars is spread_model >0.002.

2.3 Completeness estimates

Following Zenteno et al. (2011), we estimate the completeness of each DES-SV tile by comparing their *griz* count histograms for all objects against those from the Cosmic Evolution Survey (COSMOS; see e.g. Taniguchi et al. 2005). COSMOS surveyed a 2 deg² equatorial field ($\alpha = 150.1167$, $\delta = 2.2058$) with the Advanced Camera for Surveys from the *Hubble Space Telescope* (*HST*). These data have been supplemented by additional ground based images from the *Subaru Telescope*, and these are the data we use here. We extract a COSMOS source count histogram from the public photometric catalogue including SDSS *griz* bands that are transformed to our DES catalogue magnitudes and normalized to the appropriate survey area. The typical shifts in magnitude going from SDSS to DES are small compared to the size of the bins we employ to measure the count histogram. The COSMOS counts extend down to a 10 σ magnitude limit of around $g \sim 25.1$, $r \sim 24.9$, *i* ∼ 25 and *z* ∼ 24.1.

Because the analysed DES cluster tiles do not overlap with the COSMOS footprint, we measure the magnitude limits at 50 per cent and 90 per cent completeness levels by calculating the ratios between the DES and COSMOS area-renormalized number counts. First, we fit the DES number counts at intermediate magnitudes where both surveys are complete with a power law, whose slope is fixed to that obtained for COSMOS number counts within a similar

Figure 2. Completeness functions in each band for SPT-CL J0423-6143. We compare the object counts observed towards the cluster to the counts from deeper data from the COSMOS survey. The resulting completeness curve is fit by an error function, which we use to estimate 50 per cent and 90 per cent completeness.

magnitude range. Note here that we ensure that the fit is done over a magnitude range where completeness is \geq 95 per cent. The ratio between these two power laws is used for renormalizing the DES number counts, effectively accounting for field-to-field variance in the counts.

We then fit an error function to the ratio of the renormalized DES and COSMOS counts to estimate the 50 per cent and 90 per cent completeness depths (see Fig. 2). For the most part, this approach of estimating completeness works well, but due to mismatch between the power-law behaviour of the counts in the region where both surveys are complete and also due to noise in the counts, the completeness estimate for DES can, in some cases, scatter above 1. In particular, we have encountered some difficulties with greater stellar contamination in the DES regions that are closest to the Large Magellanic Cloud. Thus, we exclude four clusters with declination $\delta < -63^\circ$ from the fits analysis and mark them with different point styles in the figures. While the star–galaxy separation is effective at removing single stars, it fails for many binary stars that are present.

The analysis is performed using mag_auto and a magnitude error cut of 0.3. We use a magnitude error cut to exclude unreliable objects at the detection limit from our analysis, and we do the same thing in our analysis of the science frames. Cutting at even larger magnitude errors does not change the depths significantly. Furthermore, we exclude the cluster area within a projected distance of R_{200} from this analysis, because this region is particularly contaminated by the presence of cluster galaxies. The mean 50 per cent completeness magnitude limit for the DES photometry among all 74 confirmed clusters is 24.2, 23.9, 23.3 and 22.8 for *griz*, respectively, and the rms (root mean square) variation around the mean is 0.05, 0.05, 0.05 and 0.04. The variation in completeness depths is a reminder that not all SPT cluster fields have been observed to full depth.

3 GALAXY CLUSTER PROPERTIES

In our analysis, we focus on the galaxy population within the cluster virial regions of an SPT-selected sample of massive clusters. Because the properties of the galaxy populations are a function of radius, it is important to define consistent radii for clusters of different masses and redshifts. For the purposes of this study, we adopt the region defined by R_{200} the region where the enclosed mean density is 200 times the critical density at that redshift, and we then probe for redshift and mass trends in the ensemble within this consistently defined virial region. To calculate R_{200} , we require a redshift and a mass estimate for each system. In this section, we describe our method for measuring the cluster redshifts and for estimating the cluster masses.

3.1 Redshifts

For our cluster candidates, we use the RS galaxy population to estimate a photometric redshift. Our approach is similar to the one used in Song et al. $(2012a,b)$. The method is based on the RS overdensity in colour–magnitude space. We model the evolutionary change in colour of cluster member galaxies over a large redshift range by using a composite stellar population (CSP) model.

3.1.1 Stellar population evolutionary model

A range of previous studies has shown that early-type galaxies within clusters have stellar flux that is dominated by passively evolving stellar populations formed at redshifts $2 < z < 5$ (e.g. Bower, Lucey & Ellis 1992; Ellis et al. 1997; De Propris et al. 1999; Lin et al. 2006). We adopt a model consistent with these findings. Specifically, our star formation model is an exponentially decaying starburst at redshift $z = 3$ with a Chabrier initial mass function (IMF) and a decay time of 0.4 Gyr (Bruzual & Charlot 2003, hereafter BC03). We introduce tilt in the RS by using six different models, each with a different metallicity (Kodama & Arimoto 1997) adjusted to follow the luminosity–metallicity relation observed in Coma (Poggianti et al. 2001). Derived from the best-fitting metallicity–luminosity relation in Poggianti et al. (2001) for Z(Hg), the corresponding metallicities used are 0.0191 (3*L*∗), 0.0138 (2*L*∗), 0.0107 (*L*∗), 0.0084 (0.5*L*∗), 0.0070 (0.4*L*∗) and 0.0047 (0.3L^{*}).¹

We use DES filter transmission curves derived from the DECal system response curves that account for telescope, filters and CCDs, and that include atmospheric transmission. We use these filter transmission curves together with the *EzGal* PYTHON interface (Mancone et al. 2012) to create model galaxy magnitudes in the *griz* bands and within a luminosity range of $0.3L^* < L < 3L^*$.

In the analyses that follow, we measure quantities at a given redshift using the galaxy population that is brighter than $m_* + 2$, where the *m*[∗] is taken from this model. In a companion paper, we measure the $m_*(z)$ of the galaxy populations in this cluster sample, and use those measurements to calibrate the model used here. The *m*[∗](*z*) for each band is shown in Fig. 3. Thicker lines are used to note the redshift ranges over which the *m*[∗] is used for a particular band; we shift bands with redshift in an attempt to employ a similar portion of the rest-frame spectrum at all redshift.

3.1.2 Redshift measurements

A cluster is confirmed by identifying an excess of RS galaxies at a particular location in colour space corresponding to the redshift of the cluster. We scan through redshift examining the galaxy population within a particular projected region. Following the previous work on X-ray- and SZE-selected clusters (Song et al. 2012a,b), we define a search aperture for each cluster that is centred on the SPT candidate position and has a radius of 0.5[∗] R ₂₀₀, which is calculated using the SZE mass proxy (see the discussion in Section 3.2).

Figure 3. The characteristic magnitudes *m*∗(*z*) from the CSP model that are used for this study. In a companion paper, we use measurements of *m*[∗] for this cluster sample to test and calibrate this model, finding it to be an excellent description of the cluster galaxy population characteristic magnitude and its evolution with redshift. The bands are colour coded, and the solid lines mark the redshift ranges where each band, redward of the 4000 Å break, is used.

To measure the number of galaxies above background at each redshift, we adopt a magnitude cut of 0.4*L*[∗] together with a magnitude uncertainty cut $\sigma_{\text{mag}} < 0.1$ to exclude faint galaxies. Each galaxy within the radial aperture is assigned two different weighting factors: one accounting for the spatial position in the cluster area and one for the galaxy position in colour–magnitude space. The colour weighting *L*col accounts for the orthogonal distance *d* of each galaxy in colour–magnitude space from the tilted RS appropriate for the redshift being tested and has a Gaussian form:

$$
L_{\text{col}} = \exp\left(-\frac{d^2}{2\sigma_{\text{col}}^2}\right).
$$
 (1)

Here $\sigma_{\text{col}}^2 = \sigma_{\text{int}}^2 + \sigma_{\text{proj}}^2$, where we adopt $\sigma_{\text{int}} = 0.05$ as the intrinsic scatter in the RS (initially assumed to be fixed) and σ_{proj}^2 is the combined colour and magnitude measurement uncertainty projected on the orthogonal distance to the RS. The spatial weighting

$$
L_{\text{pos}} \sim \frac{1}{x^2 - 1} f(x) \tag{2}
$$

has the form of the projected NFW profile (Navarro, Frenk & White 1997), and the profile is described in detail in Section 4.2. The final weighting is the product of both factors.

In this way, all galaxies close to the cluster centre and with colours consistent with the RS at the redshift being tested are given a high weight, whereas galaxies in the cluster outskirts with colours inconsistent with the RS are given a small weight. We use a local background annulus within ∼1.5–3*R*200, depending on the extent of the tile, to define the background region for statistical background correction. The background measurement is obtained by applying for each galaxy the colour weight and a mean NFW weight derived from the cluster galaxies and then correcting for the difference in area.

We observe the colour–magnitude relation using the photometric band that contains the rest frame 4000 Å break and another band redward of this. The appropriate colours for low-redshift clusters $z < 0.35$ are $g - r$ and $g - i$, for intermediate-redshift clusters $0.35 < z < 0.75$ are $r - i$ and $r - z$, and for clusters at redshifts $z > 0.75$ are $r - z$ and $i - z$. These colours provide the best opportunity to separate red from blue galaxies as a proxy for passive and star-forming galaxies, respectively, given the depth constraints of our survey data. For each of these colour combinations, we construct histograms of the weighted number of galaxies as a function of redshift. The weighted number of galaxies is defined as the sum of all galaxy weights within the cluster search aperture that has been statistically background-subtracted. The cluster photometric redshift is then estimated from the most significant peak in the histogram. The photometric redshift uncertainty is the 1σ positional uncertainty of the peak, which is derived by fitting a Gaussian to the peak, and then dividing the σ width of the peak by the square root of the weighted galaxy number at the peak.

To test our photometric redshifts, we use a sample of 20 spectroscopic redshifts available in the literature (Song et al. 2012b; Ruel et al. 2014). A fit to the differences between the photometric and spectroscopic redshifts, which allows for a linear redshift dependence and offset, provides a slope that is consistent with unity; fitting only an offset indicates that the photometric redshifts are typically high by 0.019 ± 0.004 . The rms scatter of $\Delta z/(1 + z)$ using our small spectroscopic cluster sample is 0.02. Thus, the cluster photometric redshift performance is consistent with our expectation from studies of other SPT-selected cluster samples (Song et al. 2012b; Bleem et al. 2015). Given the scale of the bias in our photo-*z*s, we do not apply corrections. Photometric redshift biases at this level are not relevant for the analyses that follow.

The redshifts for all the confirmed clusters are listed in Table 1. The mean redshift of our cluster sample is 0.56, the median is 0.46, and the sample lies between 0.07 and 1.12. For redshifts $z > 1$, it is better to use the optical data in combination with NIR data to estimate reliable photometric redshifts; nevertheless, with the few clusters we have in this redshift range, our DES photometric redshifts provide no evidence for large errors.

3.2 Cluster masses

The SPT-SZ survey consists of mm-wave imaging of 2500 deg^2 of the southern sky in three frequencies (95, 150 and 220 GHz; e.g. Story et al. 2013). Details of the survey and data processing are published in Schaffer et al. (2011). Galaxy clusters are detected via their thermal SZE signature in the 95 and 150 GHz SPT maps using a multiscale and multifrequency matched-filter approach (Melin, Bartlett & Delabrouille 2006; Vanderlinde et al. 2010). This filtering produces a list of cluster candidates, each with a position and a detection significance ξ , which is chosen from the filter scale that maximizes the cluster significance. We use this selection observable also as our mass proxy.

Due to the observational noise and the noise biases associated with searching for peaks as a function of sky position and filter scale, we introduce a second unbiased SZE significance ζ , which is related to the mass M_{500} in the following manner:

$$
\zeta = A_{\rm SZ} \left(\frac{M_{\rm 500}}{3 \times 10^{14} \,\mathrm{M_{\odot}} h^{-1}} \right)^{B_{\rm SZ}} \left(\frac{E(z)}{E(0.6)} \right)^{\rm C_{\rm SZ}},\tag{3}
$$

where A_{SZ} is the normalization, B_{SZ} is the slope and C_{SZ} is the redshift evolution parameter. An additional parameter D_{SZ} describes the intrinsic lognormal scatter in ζ at fixed mass, which is assumed to be constant as a function of mass and redshift. For $\xi > 2$, the relationship between the observed ξ and the unbiased ζ is

$$
\zeta = \sqrt{\langle \xi \rangle^2 - 3}.\tag{4}
$$

For our analysis, we use the masses from the recent SPT mass calibration and cosmological analysis (Bocquet et al. 2015) that

sions (Ruel et al. 2014) and 16 X-ray Y_X measurements (Andersson et al. 2011; Benson et al. 2013). The Bocquet et al. (2015) analysis combines this SPT cluster data set with CMB anisotropy constraints from *WMAP*9 (Hinshaw et al. 2013), distance measurements from supernovae (Suzuki et al. 2012) and observations of baryon acoustic oscillations (Beutler et al. 2011; Anderson et al. 2012; Padmanabhan et al. 2012). In summary, the mass estimates (and associated uncertainties) for

each cluster include bias corrections associated with selection (the so-called Eddington bias) and are marginalized over cosmological and scaling relation parameters. The conversion from the M_{500} in equation (3) to the M_{200} used here assumes an NFW model (Navarro et al. 1997) with a concentration *c* sampled from structure formation simulations (Duffy et al. 2008). The cluster masses are listed in Table 1, and the mass–redshift distribution for the full cluster sample is shown in Fig. 4.

uses a 100 cluster sample together with 63 cluster velocity disper-

All the details of the mass calibration can be found in Bocquet et al. (2015). For the purposes of this work, we note that if we had adopted the *Planck* CMB anisotropy constraints instead of *WMAP*9. it would increase our masses by ∼6 per cent. Also, our characteristic cluster mass uncertainty is ∼20 per cent, corresponding to a virial radius uncertainty of ∼7 per cent.

4 GALAXY POPULATION PROPERTIES

In Section 4.1, we study the colour distributions of our cluster galaxies to test whether our fiducial CSP model is a good description of the data and to explore whether the RS population is evolving over cosmic time. In Sections 4.2 and 4.3, we examine the radial distribution of cluster galaxies and the halo occupation number, respectively. Section 4.4 contains a study of the red fraction and its dependence on mass and redshift.

4.1 RS selection and evolution

We wish to be able to study both the RS and non-RS galaxy populations as a function of redshift, and doing so means that we need to have a reliable way of selecting one or the other. In the simplest case, this means that we need to know the typical colour, tilt and width of the RS as a function of redshift. We have already shown in Section 3.1.2 that our fiducial CSP model produces photometric redshifts with small biases; this serves as a confirmation that the colour evolution of the RS in our CSP model is consistent with that in our cluster sample out to *z* ∼ 1.1. To test the RS tilt and measure any evolution in width, we combine information from subsamples of ∼10 clusters, each within redshift bins, and use these stacks to test our model. Stacking the clusters helps to overcome the Poisson noise in the colour–magnitude distribution of any single cluster, allowing the underlying colour distribution of the galaxies to be studied more precisely.

4.1.1 Galaxy colour distributions

Table 2 contains a description of the different redshift bins within which we stack the clusters. The table shows the redshift range of the clusters in the bin, the depth to which we are able to study the colour–magnitude distribution, the number of clusters in each bin and the colour and band combinations used. We attempt to study the colour distribution to a fixed depth corresponding to two magnitudes fainter than the characteristic magnitude *m*∗(*z*). However, given the **Table 1.** Properties of the SPT clusters: the cluster name, the mass M_{200} , the redshift *z* and then the concentration c_g and number of galaxies N_{200} within R_{200} for the full population, the RS population and the non-RS blue population. Results are not listed where the radial profile fit does not converge.

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Table 1 – *continued*

| Cluster | M_{200} $(10^{14}\,\mathrm{M}_\bigodot)$ | z | $c_{\rm g}$ | N_{200} | $c_{\rm g,RS}$ | $N_{200,RS}$ | $c_{\rm g,nRS}$ | $N_{200,\text{nRS}}$ |
|-------------------|---|-----------------|-----------------------------------|------------------------------------|-------------------------|------------------------------------|------------------------|-----------------------------------|
| SPT-CL J0509-5342 | $9.1_{-2.2}^{+1.5}$ | 0.46 ± 0.02 | | | $3.71^{+1.77}_{-1.18}$ | $63.3^{+7.81}_{-7.95}$ | | |
| SPT-CL J0509-6118 | $11.4^{+1.9}_{-2.6}$ | 0.40 ± 0.03 | $5.83_{-1.94}^{+2.58}$ | $94.4^{+16.0}_{-13.1}$ | $4.55^{+1.87}_{-1.02}$ | $96.2^{+9.31}_{-11.7}$ | | |
| SPT-CL J0516-5430 | $12.3^{+2.0}_{-2.8}$ | 0.29 ± 0.02 | $2.09_{-0.30}^{+0.36}$ | $223.9^{+15.5}_{-13.8}$ | $3.59^{+0.75}_{-0.49}$ | $154.3^{+10.4}_{-10.8}$ | | |
| SPT-CL J0516-5755 | $5.8^{+1.3}_{-1.7}$ | 0.91 ± 0.02 | $5.73^{+2.56}_{-1.70}$ | $82.6^{+12.2}_{-12.9}$ | $10.64^{+5.75}_{-3.18}$ | $50.1^{+6.92}_{-7.24}$ | $1.36_{-1.11}^{+3.02}$ | $11.5^{+3.86}_{-2.86}$ -8.85 |
| SPT-CL J0516-6312 | $5.9^{+1.4}_{-2.0}$ | 0.18 ± 0.01 | $3.33_{-1.03}^{+1.58}$ | $84.2^{+14.0}_{-14.4}$ | $2.27^{+2.34}_{-1.00}$ | $19.6^{+4.69}_{-5.17}$ | $6.37^{+3.94}_{-2.65}$ | $70.8^{+15.5}_{-15.4}$ |
| SPT-CL J0517-6119 | $7.9^{+1.5}_{-2.0}$ | 0.81 ± 0.02 | $2.62_{-0.92}^{+1.51}$ | $89.7^{+12.4}_{-15.8}$ | $1.92^{+1.19}_{-0.71}$ | $47.9^{+6.25}_{-7.18}$ | $2.89^{+3.36}_{-1.66}$ | $36.0^{+10.0}_{-13.0}$ |
| SPT-CL J0517-6311 | $6.3^{+1.5}_{-2.0}$ | 0.33 ± 0.01 | | | $2.58^{+2.54}_{-1.43}$ | $17.6^{+6.34}_{-4.66}$ | | |
| SPT-CL J0529-6051 | $6.2^{+1.4}_{-1.9}$ | 0.75 ± 0.07 | $6.68^{+6.69}_{-3.75}$ | $65.8^{+15.9}_{-14.3}$ | $11.7^{+9.75}_{-5.38}$ | $37.1^{+8.88}_{-7.41}$ | | |
| SPT-CL J0534-5937 | $5.2^{+1.1}_{-1.7}$ | 0.58 ± 0.01 | $6.54_{-3.73}^{+7.18}$ | $37.3^{+10.5}_{-11.2}$ | $5.63_{-2.60}^{+2.85}$ | $31.4^{+6.49}_{-6.81}$ | | |
| SPT-CL J0539-6013 | $5.1^{+1.2}_{-1.7}$ | 0.85 ± 0.04 | | | | | | |
| SPT-CL J0540-5744 | $7.1^{+1.4}_{-1.8}$ | 0.75 ± 0.02 | $1.51^{+1.08}_{-0.7}$ -0.61 | $98.0^{+11.7}_{-12.9}$ | $6.90^{+4.03}_{-2.50}$ | $50.3^{+9.22}_{-7.48}$ | | |
| SPT-CL J0543-6219 | $9.5^{+1.6}_{-2.3}$ | 0.48 ± 0.01 | $1.74^{+2.21}_{-1.26}$ | $91.5_{-21.1}^{+20.4}$ | $6.35_{-2.18}^{+3.07}$ | $59.6^{+7.62}_{-8.63}$ | | |
| SPT-CL J0546-6040 | $5.2^{+1.2}_{-1.8}$ | 0.81 ± 0.03 | $8.46^{+10.5}_{-5.65}$ | $28.4^{+11.1}_{-9.49}$ | $5.43_{-2.66}^{+10.3}$ | $16.4^{+6.00}_{-4.80}$ | | |
| SPT-CL J0549-6205 | $21.1^{+3.6}_{-4.7}$ | 0.42 ± 0.02 | $3.11^{+0.91}_{-0.72}$ -0.79 | $261.1_{-26.5}^{+27.1}$ | $6.20^{+1.83}_{-1.28}$ | $136.9^{+12.3}_{-13.1}$ | $1.16_{-0.87}^{+1.10}$ | $113.2^{+31.7}_{-22.5}$ |
| SPT-CL J0550-6358 | $6.2^{+1.5}_{-1.9}$ | 0.74 ± 0.02 | | | $6.60_{-2.73}^{+5.94}$ | $29.9^{+6.69}$ -6.92 | | |
| SPT-CL J0555-6406 | $13.2^{+2.2}_{-3.0}$ | 0.40 ± 0.02 | | | $2.51^{+0.70}_{-0.53}$ | $163.0^{+12.1}_{-11.2}$ -14.0 | | |
| SPT-CL J0655-5541 | $7.0^{+1.6}_{-2.1}$ | 0.31 ± 0.01 | | | $6.82^{+3.03}_{-2.18}$ | $67.8^{+9.74}_{-8.67}$ | | |
| SPT-CL J0658-5556 | $28.0^{+5.0}_{-6.3}$ | 0.33 ± 0.01 | $2.59^{+0.77}_{-0.62}$ -0.62 | $145.3^{+18.5}_{-17.7}$ -17.7 | $2.52^{+0.78}_{-0.49}$ | $120.4^{+10.9}_{-10.5}$ | $1.04_{-0.50}^{+0.52}$ | $144.6^{+29.3}_{-22.2}$ |
| SPT-CL J2248-4431 | $28.9^{+5.2}_{-6.5}$ | 0.37 ± 0.02 | $12.54^{+4.50}_{-3.56}$ | $102.2^{+11.8}_{-13.3}$ | $9.37^{+4.95}_{-3.11}$ | $38.1^{+6.74}_{-6.15}$ | $1.76^{+1.50}_{-1.01}$ | $67.6^{+17.4}_{-17.5}$ |
| SPT-CL J2256-5414 | $4.7^{+1.0}_{-1.6}$ | 0.75 ± 0.04 | | | | | | |
| SPT-CL J2259-5431 | $5.8^{+1.4}_{-1.8}$ | 0.45 ± 0.01 | $7.11^{+4.49}_{-3.18}$ | $61.1_{-13.0}^{+11.4}$ | $8.70^{+7.58}_{-3.78}$ | $37.7^{+6.92}_{-7.80}$ | $2.39_{-1.52}^{+5.16}$ | $17.1^{+4.03}_{-9.67}$ |
| SPT-CL J2300-5616 | $6.5^{+1.6}_{-2.2}$ | 0.17 ± 0.01 | $8.13_{-2.38}^{+3.14}$ | $91.4_{-12.9}^{+11.0}$ | $10.07^{+4.42}_{-2.88}$ | $68.2^{+8.94}_{-7.73}$ | $4.48^{+5.70}_{-2.23}$ | $19.6^{+6.36}_{-6.98}$ |
| SPT-CL J2301-5546 | $5.0^{+1.2}_{-1.2}$ -1.7 | 0.76 ± 0.02 | $5.33_{-2.15}^{+3.28}$ | $57.1^{+10.2}_{-11.4}$ | $5.95^{+4.50}_{-2.54}$ | $35.7^{+6.67}_{-7.61}$ | $2.88^{+4.48}_{-1.75}$ | $14.2^{+5.72}_{-8.95}$ |
| SPT-CL J2332-5358 | $9.3^{+1.6}_{-2.2}$ | 0.42 ± 0.02 | $4.37^{+1.75}_{-1.34}$ | $97.5^{+13.3}_{-14.8}$ | $5.04^{+1.74}_{-1.34}$ | $78.9^{+8.54}_{-8.2}$ -10.5 | $3.36^{+4.22}_{-1.82}$ | $22.5^{+7.95}_{-10.5}$ |
| SPT-CL J2342-5411 | $7.7^{+1.4}_{-1.8}$ | 0.98 ± 0.05 | | | | | | |
| SPT-CL J2351-5452 | $6.8^{+1.4}_{-1.9}$ | 0.43 ± 0.01 | $7.26_{-1.92}^{+2.69}$ | $112.6^{+13.6}_{-12.9}$ | $9.53_{-2.39}^{+3.64}$ | $87.7^{+8.50}_{-10.8}$ | | |
| SPT-CL J2354-5633 | $6.1^{+1.3}_{-1.8}$ | 0.55 ± 0.01 | $4.94^{+1.59}_{-1.38}$ | $125.1^{+14.0}_{-14.9}$ | $5.11^{+2.30}_{-1.56}$ | $73.9^{+9.45}_{-9.16}$ | $4.15^{+2.40}_{-1.44}$ | $51.9^{+9.70}_{-10}$ -10.7 |

Table 2. Definition of redshift bins. We list the bin number, the redshift range, the depth in terms of *m*∗, the number of contributing clusters, as well as the bands used for the colour and the magnitude.

depth of the DES-SV data, we are only able to study galaxies to *m*[∗] + 1.7 at *z* > 0.7 and to *m*[∗] + 1.2 at *z* > 0.9.

We also wish to study the same portion of the spectral energy distribution (SED) in each redshift bin. Given the broad-band photometry at our disposal, this is not formally possible. Nevertheless, we attempt to minimize the impact of band shifts within the rest frame focusing in each bin on the band containing the 4000 Å break and the band redward of that band. Here again, in the highest

Figure 4. The cluster sample as a function of mass M_{200} . The error bars reflect the 1σ mass uncertainties. The median mass of the sample is 6×10^{14} M_C and the median redshift is $z = 0.46$. We adopt these median values as pivot points in our joint mass and redshift power law fits to the observed galaxy population properties. Note that the typical error for the photometric redshifts is ∼0.02.

Figure 5. Plots of the average relative throughput or quantum efficiency (QE) in the rest frame of the blue and red bands we use within the eight different redshift bins defined in Table 2. Redshifts and observed band combinations are noted in each panel, and 4000 Å is marked in cyan. By adopting different band combinations as a function of redshift, we are able to probe similar portions of the rest-frame SED over the full redshift range.

redshift bin, we have to compromise and use $i - z$ even though a more appropriate band combination would be $z - J$. Fig. 5 contains the effective rest-frame coverage of our bands as averaged over the specific clusters in that bin. It is clear that even when shifting band combinations with redshift, the rest-frame coverage varies considerably (e.g. compare bin 2 with bin 3 in Fig. 5). We account for this variation when interpreting the width of the RS in Section 4.1.3.

To construct the individual cluster colour–magnitude distributions, we measure the colour of each galaxy relative to the colour of the tilted RS at that redshift and its magnitude relative to the characteristic magnitude *m*∗(*z*). We combine all galaxies that lie within a projected radius R_{200} and make a statistical background correction using the local background region inside an annulus of $1.5-3R_{200}$. The stacked colour distribution is then the average of the colour distributions of the individual clusters in the bin; we normalize this distribution in each bin.

The resulting normalized and stacked colour–magnitude distributions are shown in Fig. 6. The locations of high cluster galaxy density are shown in black and of low density are in white. All eight redshift bins have the same grey scale colour range, allowing one to compare galaxy densities not only within a bin but also across bins. The location of the RS as defined by our CSP model lies along the line where the colour difference with the RS is zero. In all panels, there is a strong RS with an associated bluer non-RS galaxy population. The contrast of the RS drops with redshift (note here that this drop is not due to incompleteness at that depth, as we correct each individual cluster according to its completeness as described in Section 2.3). The observed contrast is sensitive both to the cluster galaxy population and the density of background galaxies in the relevant locations of colour–magnitude space. Beyond *z* ∼ 0.6, there appears to be a more significant blue population than in the lower redshift bins (see also Loh et al. 2008). This is due to possible evolution of the red fraction, which we come back to in Section 4.4. In addition, the RS population extends over a range of magnitude to $m_* + 2$ in the lower redshift bins but shows up less strongly at the faintest magnitudes in the higher redshift bins. Note that over the full redshift range, there is no apparent tilt of the

stacked colour–magnitude distribution with respect to the tilt of our CSP model. However, our ability to constrain any tilt is weaker at high redshift where the photometric uncertainties are the largest.

To further increase the signal-to-noise ratio to study the colour distribution of the cluster galaxies, we integrate these distributions over magnitude. Fig. 7 contains these projected galaxy colour distributions in each of the eight redshift bins. Points show the relative galaxy number density and the RS is modelled as a Gaussian in red. We find that the offset of the RS Gaussian is consistent with 0 within 1σ in all of the redshift bins. Thus, the RS Gaussian has a colour consistent with our CSP model (see Section 3.1.1). The observed width of the RS Gaussian increases to higher redshift, and its contrast relative to the non-RS galaxy population falls. As examined in Section 4.1.3, this growth in RS width is driven by the increased colour measurement uncertainty in the fainter galaxies together with some potential increase in its intrinsic width. The RS population is dominant at lower redshift, where the non-RS galaxies appear as an 'extended wing' to the RS population, and at redshifts $z \approx 0.77$, the non-RS and RS populations become less easily distinguishable.

4.1.2 RS selection

In the analyses that follow, we examine the RS and non-RS populations. When examining the RS population, we assign an individual galaxy *i* in the *j*th redshift bin a likelihood $P(c_i, z_i)$ of being an RS member that depends on its colour *ci* and on the colour distribution from the corresponding stack:

$$
P(c_i, z_j) = \frac{A(z_j)e^{-\frac{(c_i - c(z_j))^2}{2\sigma(z_j)^2}}}{P_{\text{obs}}(c_i, z_j)},
$$
\n(5)

where $A(z_i)$, $\sigma(z_i)$ and $c(z_i)$ denote the amplitude, width and colour offset of the best-fitting Gaussian to the RS in redshift bin z_i . $P_{obs}(c_i)$, *z*j) denotes the observed colour distribution at the given colour *c*ⁱ and in the *j*th redshift bin. The ratio in equation (5) goes to one where the galaxy colour distribution is dominated by the RS and falls to zero outside this colour range. In the analyses that follow,

Figure 6. Stacked cluster galaxy colour–magnitude distributions (left-hand panel) for the eight different redshift bins (see Table 2). The magnitude scale is defined relative to the $m_∗(z)$ of our passive evolution model, and the colour offset is defined with respect to our tilted RS model (see Section 3.1.1). A common grey scale across all bins represents the completeness-corrected and background-subtracted number density of galaxies per magnitude and colour bin. The RS is clearly apparent at all redshifts, extending cleanly to $m_* + 2$ in the lower redshift bins.

Figure 7. The stacked galaxy colour distribution for the same redshift bins as in Fig. 6. All distributions are normalized to unit area, and in each case, the red line represents the best-fitting Gaussian for the RS. At higher redshift, the distribution of galaxies bluer than the RS grows more prominent, and the RS has lower contrast.

each galaxy is weighted with this probability, enabling us to carry out a meaningful study of the RS population over a broad redshift range accounting for variation in intrinsic scatter and changes in the colour measurement uncertainties.

To examine our RS selection, we create pseudo-colour images of our colour-selected galaxy population as shown in Fig. 8. The top row of Fig. 8 marks galaxies with likelihood $P(c_i, z_i) \ge 90$ per cent to be a part of the cluster RS population. These galaxies all have similar red colours. In contrast, the bottom row contains galaxies with a likelihood $P(c_i, z_j) \leq 20$ per cent of being RS members. These are typically blue spirals. The middle row contains galaxies with likelihoods of $P(c_i, z_j) \sim 40$ per cent of being RS galaxies.

Figure 8. Image gallery of galaxies at $R < R_{200}$ within the field of SPT-CL J2351-5452. The top row contains four examples of galaxies with a high likelihood (>90 per cent) of being RS members, and the second row shows galaxies with intermediate likelihood (∼40 per cent). We note that these constitute a population of galaxies whose colours lie between those of the RS and the bluer spirals. The third row contains galaxies with a low likelihood (\leq 20 per cent) of being RS members. The majority of these are bluer disc galaxies.

They have colours that place them between the RS and the newly infalling spirals from the field.

The behaviour seen in SPT-CL J2351-5452 (Fig. 8) is similar to that in other clusters in our sample. Thus, through visual inspection of our sample, we confirm that the colour selection based on the projected colour stacks in Section 4.1 is reasonably separating the RS population from the blue cluster population.

4.1.3 RS intrinsic width

The stacked colour distributions in Fig. 7 also provide constraints on the change of the intrinsic scatter of the RS with redshift. The RS width reflects the diversity of the stellar populations (metallicity, age and star formation history) and extinction within the passively evolving component of the cluster galaxy population. Often, the width of the RS is interpreted only in terms of constraints on the age variation in the stellar populations (e.g. Kodama & Arimoto 1997; Bernardi et al. 2005; Gallazzi et al. 2006).

To extract the intrinsic scatter, we determine the colour measurement uncertainty $\sigma_{\text{col,i}}$ to produce an estimate of the intrinsic width $\sigma_{\text{int},j}$ of the RS within the *j*th redshift bin

$$
\sigma_{\text{int},j}^2 = \sigma_j^2 - \sigma_{\text{col},j}^2,\tag{6}
$$

where σ_i is the observed RS width in redshift bin *j*. To calibrate the measurement error in mag_detmodel colours for our co-add catalogues and to calculate $\sigma_{\text{col},j}^2$, we examine how repeated colour measurements of the same objects compare. To do this, we create two approximately full depth co-add tiles at the same sky position using different sets of single-epoch exposures. Each of these co-add tiles has about 10 exposures in each band and is therefore consistent with a full depth DES tile like those available for our sample. Our test tiles draw upon the DES-SNe survey imaging data set, where fields have been repeatedly observed over long periods to identify new SNe. With two independent tiles of the same sky region, we then compare the mag_detmodel colours from the two tiles as a function of mag_auto (e.g. we compare the mag_detmodel colours $g - r$ as a function of mag_auto *r*). Fitting a simple power-law relation, we model the variance in the mag_detmodel measurements as a function of magnitude $\sigma_{mod}(mag_i)$.

Because the photometric depths of the co-add tiles in our cluster sample do vary somewhat, we determine the 10σ depth for the two co-add tiles as well as for all the cluster tiles. For this purpose,

Figure 9. Black points mark the colour measurement noise-corrected widths of the RS at each redshift using the band combinations in Table 2. The red points are the estimated RS widths in the rest frame $g - r$ colour, given the width in the observed band combination. There is no compelling evidence for RS width evolution within the rest-frame bands (see equation 8).

we adopt the magnitude at which the median magnitude error in mag_auto equals 0.1. To account for the depth difference between the SNe field and the typical cluster field, we fit the power law as a function of $m - m_{10\sigma}$, where $m_{10\sigma}$ denotes the 10 σ depth in the SNe field. Essentially, we are then measuring the mag_detmodel colour scatter with respect to the 10σ mag_auto depth in the SNe field and then applying that as a model of the colour scatter in each cluster field.

Because we are analysing colour stacks within redshift bins, we determine the mean 10σ depth of the clusters contributing in the bin. From the colour stacks in Fig. 7, we have a measure of the number of galaxies in magnitude bins within the magnitude range between $m_* - 2$ and $\sim m_* + 2$. We define this as $N(mag_i)$, where *mag*ⁱ is the magnitude associated with bin *i*. Then, we estimate the measurement contribution to the colour width as

$$
\sigma_{\text{col},j}^2 = \frac{\Sigma_i N(mag_i)\sigma_{\text{mod}}^2(mag_i - m_{10\sigma,j})}{\Sigma_i N(mag_i)},\tag{7}
$$

where $m_{10\sigma,i}$ denotes the mean 10σ depth of all clusters within the *j*th redshift bin. Thus, the final estimate of the colour measurement variance is basically a weighted sum of the colour measurement variances as a function of magnitude.

The colour measurement noise-corrected intrinsic widths of the RS are plotted as black points in Fig. 9. Note that we are measuring RS scatter in $g - r$, $r - i$ and $i - z$ over this redshift range, which allows us to probe similar but not identical portions of the restframe spectrum of these galaxies. To estimate the scatter within the rest frame $g - r$ colour, we build a library of model SEDs using the code GALAXEV from BC03. We use exponentially declining star formation histories with different decay times (see Chiu et al. 2016). For each model with a different decay time, we obtain predicted colours for ∼200 different stellar population ages. In total, our library contains around 5000 template SEDs. Then, for each redshift bin, we extract template SEDs in the observed frame colour, which reproduce the observed Gaussian of the RS with a mean *m*[∗] colour and intrinsic width. For this set of individual SEDs, we then extract the distribution of rest frame $g - r$ colour and fit this to a Gaussian. We mark the estimated rest frame $g - r$ scatter with red squares in Fig. 9. To simplify the figure, the measurement uncertainties are placed only on the black points.

We fit a power law to the RS width as a function of redshift and find

$$
\sigma_{\text{int, RS}} = (0.036 \pm 0.002) \left(\frac{1+z}{1+0.46} \right)^{(0.58 \pm 0.47)}.
$$
 (8)

Thus, our current sample indicates a characteristic RS width of (36 ± 2) mmag in the rest frame $g - r$ colour at the pivot redshift $z = 0.46$ of our sample and provides no statistically significant evidence of an increase in width as a function of redshift after increasing measurement uncertainties are accounted for.

RS scatter has been studied previously (e.g. Aragon-Salamanca et al. 1993; Stanford et al. 1998; Blakeslee et al. 2003; Mei et al. 2006 , 2009). As these studies correct to a rest frame $U - V$ colour and do not report a redshift trend on their individual cluster data, we restrict ourselves to a qualitative comparison. Summarized in Papovich et al. (2010), the RS scatter shows typical values of ∼25 mmag at *z* ∼ 0 and increases towards ∼140 mmag at redshift 1.62; this trend would be consistent with the observations we present above if much of the width increase occurs at redshifts $z > 0.9$.

4.2 Radial distribution of galaxies

We study the radial profile of the galaxy number density because it is a fundamental property of the population, but we also need the radial profile to enable a statistical correction for the cluster galaxies that are projected on to the cluster virial region but actually lie outside the virial sphere in front of or behind the cluster. In the following, we describe the profile fitting method and testing (Section 4.2.1), the method for constraining trends in mass and redshift (Section 4.2.2) and our results on the concentration (Section 4.2.3).

4.2.1 Fitting projected NFW profiles

To construct the radial profile, we measure the number of galaxies lying within annuli centred on the cluster. It has previously been shown that the offsets between SZE centres and BCG positions (Song et al. 2012b) are consistent with the offsets measured between X-ray centres and BCGs (Lin & Mohr 2004), but the SZE positional measurement uncertainties are large compared to the BCG positional uncertainties. Thus, for this analysis, we adopt the BCG position as the cluster centre. BCGs are selected manually through visual inspection of the pseudo-colour images. If there is no clear, centrally located BCG, we adopt the brightest galaxy within $0.5 \star R_{200}$, which has a colour within 0.22 mag of the RS colour at that redshift and is located closest to the SZE centre. In eight cases, this BCG definition leads to the selection of what is clearly a bright foreground galaxy, and in these cases, we exclude those galaxies and select a fainter BCG candidate.

The radial profile extends to between ∼4 R_{200} and ∼14 R_{200} , given the $1° \times 1°$ or $2° \times 2°$ tiles we prepare for each cluster. Thus, in all cases, it includes a background-dominated region. We correct the individual profiles for bright stars that contaminate the cluster and background areas. For each profile annulus, we calculate an effective area by subtracting off the star areas that are contaminating the bin. Bright stars are selected from the 2MASS survey using a magnitude cut of $J < 13.5$. We use an empirically calibrated relation between the *J*-band magnitude and the masking radius of the star to exclude spurious objects. For the profile analysis, we use galaxies that are brighter than ∼*m*[∗] + 2 in the band redward of the 4000 Å break, except again in the highest redshift bins where our imaging depth does not allow analysis to the full depth, and in the highest

redshift bin where *z* band contains the 4000 Å break. All profiles are completeness-corrected as described in Section 2.3.

We fit these profiles to the NFW (Navarro et al. 1997) density profile with the concentration as one of the free parameters. The three-dimensional NFW profile is given as

$$
\frac{\rho(r)}{\rho_c} = \frac{\delta_c}{(r/r_s)(1 + r/r_s)^2},\tag{9}
$$

where $\rho_c = 3H_0^2/8\pi G$ denotes the critical density of the Universe, δ_c is a characteristic density contrast and r_s is the typical profile scale radius. The concentration parameter for the NFW profile is defined as $c = R_{200}/r_s$. In our application, we measure the galaxy surface density profile, and therefore we use the projected and integral projected versions of the NFW model.

Our model profile is the superposition of the cluster profile $\Sigma_{\rm cl}$ and a constant background Σ_{back} :

$$
\Sigma(x) = \Sigma_{\rm cl} + \Sigma_{\rm back}.\tag{10}
$$

Consequently, the formula for the projected NFW profile has three free parameters: the normalization, the constant background and the scale radius r_s (or, equivalently, the concentration *c*). We follow Lin, Mohr & Stanford (2004) in adopting the integrated number of galaxies within R_{200} as the normalization. This avoids the parameter degeneracy between the concentration and the central density and results in improved constraints on the concentration. To fit the profile, we use the Cash (1979) statistic and the observed and predicted total counts per bin, rather than the number density per bin. To determine the predicted counts per bin, we evaluate the model as $N(R_{\text{up}}) - N(R_{\text{low}})$, where $N(R_{\text{up}})$ is the integrated number of galaxies inside a projected cylinder with an outer radius of R_{up} , and $N(R_{\text{low}})$ is the equivalent inside a cylinder of Radius R_{low} . This avoids biases introduced by binning in the inner regions of the profile where it is changing rapidly with radius.

Due to the star-masking, we are missing galaxies inside the radial bin and so we correct the model number of galaxies with the ratio *A*eff/*A*true, where *A*eff is the effective bin area after star-masking, and $A_{\text{true}} = \pi (R_{\text{up}}^2 - R_{\text{low}}^2)$ represents the geometric bin area. As the measured number inside a radial bin is the sum of cluster galaxies and background galaxies, we add the background contribution to the model with $\Sigma_{\text{back}} \star A_{\text{eff}}$. In summary, within each annulus, we measure the number of observed galaxies, calculate the effective area and fit a model that reads

$$
N(r) = (N(R_{\text{up}}) - N(R_{\text{low}}))\frac{A_{\text{eff}}}{A_{\text{true}}} + \Sigma_{\text{back}}A_{\text{eff}}.
$$
 (11)

From integrating the surface density, *N*(*R*up) becomes

$$
N(R_{\rm up}) = 4\pi \rho_s r_s^3 g(x) \tag{12}
$$

$$
g(x) = \begin{cases} \frac{2}{\sqrt{(x)^2 - 1}} \arctan\sqrt{\frac{x-1}{x+1}} + \ln(\frac{x}{2}) & \text{if } x > 1, \\ \frac{2}{\sqrt{1-(x)^2}} \arctanh\sqrt{\frac{1-x}{1+x}} + \ln(\frac{x}{2}) & \text{if } x < 1, \\ 1 + \ln(\frac{x}{2}) & \text{if } x = 1 \end{cases}
$$

where $x = cR_{\text{up}}$. $N(R_{\text{low}})$ is calculated correspondingly (Bartelmann 1996). The profile fitting is done with the Markov chain Monte Carlo Ensemble sampler from Foreman-Mackey et al. (2013). Because the error distribution for the concentration parameter is closer to lognormal than to normal, we fit for $ln(c)$. Fig. 10 contains an example for the profile parameter constraints for a stacked cluster profile containing low-redshift systems.

Figure 10. Parameter constraints for the stacked cluster profile using the full population within the redshift range of $0.07 < z < 0.23$. We show the joint and fully marginalized constraints in ln(*c*), the background *bg* and the number of galaxies *norm* projected within *R*200. The best fit is marked with the vertical blue lines.

We test the profile generation and the fitting procedure on a sample of mock catalogues with a concentration of $c = 5$. We build a large mock catalogue with 500 000 galaxies within a projected region extending to $10R_{200}$ to first ensure that our code returns unbiased results in the high-signal-to-noise limit. We test first with no background and then create a new mock catalogue with the background adjusted to be comparable to what we see in the real data. We then draw 100 individual realizations with different numbers of cluster galaxies – i.e. 100, 500, 1000, 2000 and 4000 galaxies – to test behaviour in the limit where the Poisson noise is important. We find that even in the low-signal-to-noise regime with just 100 cluster galaxies (which is typical also for the SPT sample we probe here), we can fully recover the input concentration with an inverse variance-weighted mean of 4.95 ± 0.16 . The normalization is also recovered to within the 1σ statistical uncertainty.

With our fitting approach, the radial bins can be infinitesimally small. For our application, we use bins of 0.02 inside R_{200} , and increase the bin size outside this radius. Our tests show that an overestimation of the background leads to overestimated concentrations, and therefore it is very important to fit a region extending to large enough radius to constrain both the background and the cluster model. In particular, we find that it is important to have data extending to \sim 4 R ₂₀₀, and so we have ensured that our fits include data out to this radius for all clusters in the sample. Through these tests, we have demonstrated that our profile fitting code and approach are unbiased within the (small) statistical uncertainties in our tests.

4.2.2 Fitting trends in mass and redshift

We fit a simple power law to the log of the concentration parameter of the individual cluster profiles simultaneously in mass and redshift. Because this approach is used in the other observables examined below, we define the relation here for a generic observable $O(M_{200}, z)$ as

$$
O(M_{200}, z) = A \left(\frac{M_{200}}{M_{\text{piv}}}\right)^B \left(\frac{1+z}{1+z_{\text{piv}}}\right)^C,
$$
\n(13)

where *A* is the normalization, *B* is the mass power-law index and *C* is the redshift power-law index. We choose a mass pivot point $M_{\text{piv}} = 6 \times 10^{14} M_{\odot}$, which is the median mass of our sample, and a redshift pivot point $z_{\text{piv}} = 0.46$, which is the median redshift of our sample.

In addition to these three parameters, we constrain the intrinsic scatter σ_{int} of these relations. With this intrinsic scatter, the uncertainty on a given parameter measurement becomes the quadrature addition of the intrinsic and measurement uncertainties. We iterate our fit, adjusting the intrinsic scatter until the reduced χ^2 for the fit approaches 1.0. For all cases except for the RS fraction, the intrinsic scatter is evaluated as the fractional scatter. These best-fitting parameters and estimates of the intrinsic scatter for all observables considered are listed in Table 4.

Using the best-fitting parameters and parameter uncertainties, we use Gaussian error propagation to estimate the uncertainties on the best fit as

$$
\frac{\sigma_0^2}{O^2}(M_{200}, z) = \frac{\sigma_A^2}{A^2} + \left(\log \frac{M_{200}}{M_{\text{piv}}}\right)^2 \sigma_B^2 + \left(\log \frac{(1+z)}{(1+z_{\text{piv}})}\right)^2 \sigma_C^2,
$$
\n(14)

where the parameter errors are extracted from the covariance matrix of the fit and off-diagonal terms are ignored. We use this uncertainty to define a confidence region about the best-fitting relations (see Table 4) when they are presented in Figs 13–15.

4.2.3 Observed galaxy radial profile concentrations

We first present the radial profile of the stacked clusters for the full, the RS and the blue non-RS populations to provide for a comparison of the three populations. For the stacks, we sum the number of galaxies and the corresponding areas within each radial bin. This sum is then averaged by the number of contributing clusters inside the bins. The blue non-RS population is selected to have a colour that is blueward from the cluster RS, and each galaxy is weighted with $1 - P_{i,j}$ as in equation (5). These stacks are shown for the full cluster sample in Fig. 11 and for the eight different redshift bins in Fig. 12 with black, red and blue points, and best-fitting models for the full, RS and blue non-RS populations, respectively. All individual profiles extend out to $4R_{200}$.

We find that the full population is less concentrated with c_g = $3.59_{-0.18}^{+0.20}$ compared to the RS population with $c_{g,RS} = 5.37_{-0.24}^{+0.27}$. The blue, while clearly having a density that increases towards the cluster centre, is even less concentrated with $c_{\text{g,non-RS}} = 1.38_{-0.19}^{+0.21}$ (see Fig. 11). The same general picture arises in each redshift bin as seen in Fig. 12. Note also that the blue non-RS background is higher than the RS background, making the study of the blue non-RS population more challenging. In redshift bins 2 and 4, the concentration of the blue non-RS population was unconstrained due to large scatter, and therefore we show no model. Note that our data provide no convincing evidence of a departure from the NFW model out to 4*R*²⁰⁰ in any population; given the expected amplitude of the deviations due to neighbouring haloes in the dark matter (e.g. Hilbert & White 2010) and the scale of our measurement uncertainties, this is not surprising.

Figure 11. The black, red and blue points (and lines) show the stacked, background-subtracted radial profiles and their best-fitting NFW models for the full, RS and blue non-RS populations, respectively. We show the quantity $\Sigma = N/(A_{200})$, where A_{200} is the projected virial area. These stacks contain all clusters in the sample except for SPT-CL J0330-5228, which has no *i*-band coverage. All individual profiles extend to 4*R*200. The RS and blue non-RS populations are selected using the observed colour distributions in eight redshift bins (see equation 5). The RS population is strongly clustered, whereas the blue non-RS population is clustered but with a lower concentration.

The best-fitting parameter values for the cluster stacks are shown in Table 3, and the best-fitting mass and redshift trends (equation 13) of the concentration in the stacked sample is presented in Table 4. The characteristic value of the concentration for the full population at the pivot mass $M_{\text{piv}} = 6 \times 10^{14} \text{ M}_{\odot}$ and the pivot redshift

 $z_{\text{piv}} = 0.46$ is $c_{\text{g,st}} = 3.19 \pm 0.64$, and there are no statistically significant redshift trends, although there is 2.2σ and 2.4σ evidence for higher concentrations at higher redshift in the stacked full and RS populations, respectively. For the RS population, the characteristic value is $c_{g,RS,st} = 5.33 \pm 0.53$, also with no statistically significant trends. The blue non-RS population is even less concentrated with $c_{\varphi,\text{nRS,st}} = 1.59 \pm 0.53$. Similar to the other populations, there is no mass and redshift trend for the blue non-RS population. These fits to the concentrations from the stacks in the eight redshift bins are consistent with the stack of the entire cluster ensemble shown in Fig. 11.

We also measure concentrations for individual clusters and these are listed in Table 1. Fitting these individual cluster concentrations to the power-law trends in mass and redshift, we find that the characteristic concentration for the full population is $c_g = 3.89 \pm 0.52$, and that there is considerable cluster to cluster intrinsic scatter of 55 per cent. Consistent with the results from the stacks, there is no statistically significant evidence for a redshift or mass trend (see Table 4), although there is a preference at 1.8σ for more massive systems to have lower concentration.

Fig. 13 (lower panel) contains a plot of the galaxy population concentration for each cluster (black points) and for each stack (blue squares) versus redshift. Measurements from the literature are plotted in red with different point styles: Capozzi et al. (2012) (red filled circle), Popesso et al. (2006) (red cross), Lin et al. (2004) (red star), Carlberg et al. (1997) (red open square), Muzzin et al. (2007a) (red filled square) and van der Burg et al. (2015) (red open circles). There is good agreement among these previous results and our own. The considerable cluster to cluster variation in concentration

Figure 12. The colour coding is the same as in Fig. 11, but here the stacks without background subtraction are shown for the eight different redshift bins. Again, all profiles extend to $4R_{200}$. In each redshift bin, we find that the blue non-RS population is concentrated towards the cluster centre but with lower concentration than the RS population. The concentrations from the stacks show no statistically significant mass or redshift trends (see Table 4). No model is shown for the blue non-RS population in redshift bins 2 and 4, because the concentration is not constrained.

Figure 13. Redshift trend of the concentration parameter for the non-RS blue (top panel), RS (middle panel) and full (bottom panel) populations. The black points (blue) show the best-fitting NFW concentration for individual clusters (stacks). The line marks the best-fitting redshift trend and 1σ region (see Table 4). The characteristic concentrations for the non-RS, RS and full populations are 1.59 ± 0.53 , 5.47 ± 0.53 and 3.89 ± 0.52 , respectively. There are no statistically significant mass or redshift trends. Considerable cluster to cluster scatter at the 55 per cent–38 per cent level is apparent. The red points show various published results that are described in the text (Section 4.2.3). In addition, we mark the clusters close to the Large Magellanic Cloud ($\delta < -63°$) as black open diamonds.

of 55 per cent (listed for all fits in last column of Table 4) is clearly apparent in this figure.

We use the same technique to measure the concentrations for the RS galaxy population, where we assign each galaxy a probability of being an RS member as described in equation (5). The concentration trend with redshift is shown in Fig. 13 (middle panel). The characteristic concentration at our pivot mass and redshift is $c_{\rm g,RS} = 5.47 \pm 0.53$. Consistent with the results from the stacks, we do not find statistically significant mass and redshift trends. The somewhat lower cluster-to-cluster scatter of 38 per cent is also apparent in the figure.

We also study the concentrations of the blue non-RS population, although for more than two-thirds of the clusters, the blue non-RS concentrations are unconstrained. The characteristic value for this subset of cluster population is $c_{\text{g,nRS}} \sim 3.35 \pm 0.38$ (see Fig. 13, top panel), which is higher than the values seen in the stacks created within redshift bins. We note that an agreement between the stacks and the individual profiles is not guaranteed because the stacks contain all clusters in the sample and represent a galaxy number-weighted average, whereas we report concentrations for the individual profiles only in the cases where the fit converges. Because it requires higher signal to noise to constrain a fit to a galaxy distribution with lower concentration, it is preferentially the low concentrations that are unconstrained. This may lead to a tendency for the stacks, which represent the full population, to show lower concentrations than the fit to the individual measurements. Because such a small fraction of individual clusters leads to concentration measurements, we believe that in this case,, the stacks provide a more robust result.

In summary, our data show that the red, early-type galaxies tend to have a more concentrated distribution than the blue non-RS and full populations, which is consistent with previous analyses where a higher concentration is seen in the red galaxy population (e.g. Goto et al. 2004). Spectroscopic studies of individual clusters also support this picture that there is a flatter distribution of emissionline galaxies centred on the cluster whose virial region is strongly marked by a more concentrated distribution of absorption line systems (e.g. Mohr et al. 1996). Our analysis clearly indicates that there is a clustered blue population with lower concentration associated with the clusters over the full redshift range. Moreover, our sample allows for a consistent study of the galaxy populations of these systems out to $z \sim 1.1$. Rather than indicating a clear redshift trend, the most salient feature of the concentrations for the sample is the large cluster to cluster scatter.

4.3 Halo occupation number

The halo occupation distribution (HON) describes the relation between galaxies and dark matter at the level of individual dark matter haloes (Zheng et al. 2005), providing insight into how baryonic matter is distributed within each of the dark matter haloes. A key feature here is the relation between the halo occupation number and $M_{200,c}$. A simple prediction based on galaxy formation efficiency is that the number of galaxies formed is proportional to the baryonic mass within the halo. The HON–mass relation becomes $N_g \sim M^B$ with $B > 1$ if galaxy formation is more efficient in the more massive haloes, or $B < 1$ the other way around. Reasons for $B < 1$ include that the gas, which is heated through the collapse of the halo,

Figure 14. The HON from measurements of N_{200} from the galaxy radial profiles is plotted versus mass (left-hand panels), and the HON normalized to a mass of 6 \times 10¹⁴ M_O is plotted versus redshift (right-hand panels). In both cases, the full (RS) population appears on bottom (top panel), and both populations have $N_g \propto M^B$, where $B < 1$ (see Table 4). We find no clear evidence of a redshift trend in the full population, but the RS population shows a 2.5 σ trend for falling HON with redshift. The 1 σ region (equation 14) for each fit is plotted in red. The clusters near the LMC ($\delta < -63^\circ$) are more contaminated by stars and are marked with black open diamonds.

may not effectively cool and collapse into galaxies in the higher mass haloes. In addition, dynamical friction and tidal stripping can have an impact on the HON, which is typically measured above a magnitude threshold (Lin et al. 2004; Rines et al. 2004).

Here we calculate the HON directly from the normalization N_{200} of the individual fits to the radial profile of the cluster galaxies – both the full sample and the RS-selected sample. We correct the measured N_{200} inside the virial cylinder to the virial sphere. Therefore, we calculate the correction factor f_c from the integration of the projected surface number density inside a cylinder and sphere as

$$
f_c = \frac{N_{\text{cyl}}(R_{200})}{N_{\text{sph}}(R_{200})}.
$$
 (15)

These integrals are simply a function of the concentration *c*. For a concentration $c = 3$, for example, the correction factor is $f_c \sim 1.3$. For each studied cluster, we use the measured concentration to correct N_{200} . In addition, in the highest redshift bins where the completeness does not extend completely to $m_∗ + 2$, we use the faint end slope measured for the individual cluster or the stack, as appropriate, to apply a correction to the N_{200} . In this way, all N_{200} measurements refer to the population within the virial sphere brighter than $m_* + 2$.

Fig. 14 is a plot of the measured N_{200} for each cluster versus mass (left-hand panel) and redshift (right-hand panel) for the full population (bottom panel) and RS population (top panel). The best-fitting power-law parameters (equation 13) describing these data appear in Table 4. The characteristic N_{200} at our pivot redshift $z_{\text{piv}} = 0.46$ and mass $M_{\text{piv}} = 6 \times 10^{14} M_{\odot}$ is 71.1 \pm 3.9 for the full population and 49.8 ± 2.9 for the RS population. This is an indication that the red fraction at the pivot mass and redshift to $m_* + 2$ is (70 ± 7) per cent for the galaxy population within the R_{200} virial sphere.

The mass trend for the full population $N_{200} \propto M^{(0.79 \pm 0.10)}$ is consistent with the RS population, where we find $N_{200,RS} \propto M^{(0.70 \pm 0.11)}$. The full population shows no statistically significant evidence of redshift variation $N_{200} \propto (1 + z)^{-0.42 \pm 0.31}$, but the RS population varies with redshift as $N_{200} \propto (1+z)^{-0.84 \pm 0.34}$, a trend that is statistically significant at 2.5σ . This difference in behaviour is suggestive of an increase in RS fraction over cosmic time.

As with the other power-law fits, we extract constraints on the variation of the N_{200} from cluster to cluster for both the RS and full populations. We find a 31 per cent intrinsic scatter in N_{200} around the best-fitting relation for the full population, and a 37 per cent intrinsic scatter for the RS population. This evidence of scatter is corrected for the Poisson sampling noise and background correction uncertainties that are included in the N_{200} measurements. Thus, both the concentration and number of galaxies vary significantly from cluster to cluster of a given mass and redshift. Our estimates of intrinsic scatter of N_{200} are larger by a factor of 1.5–2 in comparison to recent measurements of the intrinsic scatter in the richness measure λ of a sample of similar SZE-selected clusters (Saro et al. 2015). The richness measure λ is extracted from a somewhat smaller portion of the cluster virial region.

We do not fit mass and redshift trends for the stacked clusters (but results of all stack measurements are listed in Table 3), because the direct stacking approach we use leads to a noisy and biased estimate of N_{200} . Specifically, within the redshift bins, we create a stack by summing the individual cluster profiles. Within the limit of similar backgrounds, this leads to an N_{200} -weighted stack, where, naturally,

| # | Z. | $\langle M_{200} \rangle$ $(10^{14} M_{\odot})$ | $c_{\text{g,st}}$ | $N_{200,\text{st}}$ | $c_{g,RS,st}$ | $N_{200,RS,st}$ | $c_{\text{g,nRS,st}}$ | $N_{200,nRS,st}$ | $\sigma_{\text{int},g-r}$ |
|----------------|------|--|-------------------------|--------------------------|-------------------------|--------------------------|------------------------|-------------------------|---------------------------|
| | 0.15 | 6.10 | $5.19^{+0.78}_{-0.75}$ | $106.04^{+6.40}_{-6.17}$ | $5.16_{-0.69}^{+0.79}$ | $76.72_{-3.67}^{+3.77}$ | $4.03_{-1.08}^{+1.46}$ | $29.61_{-3.89}^{+4.07}$ | 0.033 ± 0.004 |
| 2 | 0.29 | 9.97 | $1.02_{-0.20}^{+0.22}$ | $157.90^{+9.45}_{-8.56}$ | $3.35^{+0.50}_{-0.47}$ | $79.50^{+3.80}_{-4.45}$ | | | 0.026 ± 0.006 |
| 3 | 0.38 | 10.40 | $2.52^{+0.26}_{-0.22}$ | $210.17^{+7.54}_{-7.12}$ | $4.48^{+0.47}_{-0.40}$ | $121.77^{+3.73}_{-4.13}$ | $0.79_{-0.18}^{+0.23}$ | $91.43_{-5.94}^{+6.24}$ | 0.040 ± 0.003 |
| $\overline{4}$ | 0.45 | 8.71 | $3.54^{+0.53}_{-0.41}$ | $135.58^{+6.57}_{-6.67}$ | $6.92^{+0.85}_{-0.79}$ | $80.23_{-3.52}^{+3.39}$ | $\qquad \qquad -$ | | 0.026 ± 0.006 |
| 5 | 0.62 | 6.12 | $3.39^{+0.46}_{-0.47}$ | $113.28^{+5.28}_{-5.88}$ | $4.82^{+0.70}_{-0.58}$ | $71.90_{-3.24}^{+3.24}$ | $1.80^{+0.56}_{-0.52}$ | $40.25_{-4.19}^{+4.77}$ | 0.037 ± 0.002 |
| 6 | 0.77 | 5.78 | $6.62^{+1.73}_{-1.25}$ | $70.04^{+6.91}_{-7.17}$ | $8.81^{+1.94}_{-1.53}$ | $45.25_{-3.43}^{+3.40}$ | $3.07^{+3.30}_{-2.18}$ | $22.04^{+8.22}_{-6.82}$ | 0.036 ± 0.029 |
| | 0.84 | 8.34 | $5.43_{-0.99}^{+1.16}$ | $75.23^{+6.75}_{-6.70}$ | $5.93_{-1.03}^{+1.17}$ | $49.44_{-3.57}^{+3.54}$ | $3.41^{+1.65}_{-1.25}$ | $26.11^{+5.10}_{-5.19}$ | 0.033 ± 0.007 |
| 8 | 1.01 | 5.37 | $10.30_{-2.55}^{+3.06}$ | $39.22_{-4.91}^{+4.21}$ | $11.40_{-2.61}^{+3.58}$ | $24.36^{+2.20}_{-2.51}$ | $7.48^{+6.50}_{-3.85}$ | $13.69^{+3.44}_{-4.13}$ | 0.070 ± 0.010 |

Table 3. Properties of the stacked profiles. We list the bin number, redshift and mean followed by the concentration and N_{200} for the full, RS and non-RS blue stacks. The last two columns contain the RS fraction and the intrinsic scatter of the RS.

those clusters with the most contributed galaxies have the largest impact on the stack. This leads to a noisy and biased estimator of N_{200} , which is approximately $\langle N_{200}^2 \rangle / \langle N_{200} \rangle$. This is a generic problem with stacking that is worse for our sample, because we have a large mass range in each redshift bin and too few clusters in each bin to subdivide into mass bins to create more similar subsamples. For the concentration c , this weighting is not as problematic because we see no mass dependence in the concentrations, and in the fit, the parameter concentration c_g and N_{200} are only weakly correlated.

We find agreement between our measured mass trend in the full population and previously published results: $B = 0.87 \pm 0.04$ (Lin et al. 2004), 0.70 ± 0.09 (Rines et al. 2004) and 0.92 ± 0.03 (Popesso et al. 2007). Comparing the normalization to the local sample at $z \sim 0.05$ of Lin et al. (2004), we first correct the $m_* + 3$ values used in the Lin et al. (2004) analysis to the $m_* + 2$ used in our analysis, adopting their faint end slope $\alpha = -1.1$. Our normalization is lower than that observed by Lin et al. (2004) with a low-redshift $z < 0.2$ sample (see Fig. 14, lower right panel), where we have few clusters in our sample.

4.4 RS fraction

For studying the evolution of the RS fraction f_{RS} , we look at the galaxy population brighter than ∼*m*[∗] + 2, which lies within the cluster virial sphere ($r < R_{200}$). Specifically, we calculate the ratio $f_{RS} = N_{200,RS}/N_{200}$, where the N_{200} are extracted for each cluster during the radial profile fitting (see Section 4.2.1). Note here that these measurements are corrected to the virial sphere using the appropriate individual concentration measurements for each population as clarified in equation (15). As described in Section 4.1.2, the RS galaxies are selected with a probabilistic approach based on the stacked colour distributions in eight redshift bins. We derive f_{RS} for the individual clusters, but, as discussed in the previous section, the stacks for our sample are not good estimators for N_{200} , and therefore we do not use them to estimate f_{RS} . Note that given the measurement noise, it is possible for the red fraction estimate for a single cluster to scatter above 1.

A plot of f_{RS} versus redshift appears in Fig. 15. The red area represents the best-fitting function to the individual cluster measurements, and the best-fitting parameters are given in Table 4. We find that at the pivot mass and redshift the RS fraction is $f_{RS} = (68 \pm 3)$ per cent, which is in agreement with the characteristic values of the N_{200} for the full and RS populations presented in Section 4.3. The RS fraction is decreasing with redshift $f_{RS} \propto (1 + z)^{-0.65 \pm 0.21}$ in the individual measurements with 3σ

Figure 15. RS fraction within the virial sphere of radius R_{200} as a function of redshift. The individual f_{RS} measurements are in black, and the best-fitting trend is shown in pink. The typical RS fraction is 68 ± 3 per cent at the pivot redshift $z = 0.46$ and mass $M = 6 \times 10^{14}$ M_(c) with intrinsic variation at the 14 per cent level. The best-fitting redshift trend $f_{RS} \propto (1+z)^{-0.65 \pm 0.21}$ has characteristic values around 55 per cent at $z = 1$ and 80 per cent at $z = 0.1$. One LMC cluster appears marked with an open diamond.

Table 4. Mass and redshift trends for the individual cluster properties using equation (13) with $M_{\text{piv}} = 6 \times 10^{14} \text{ M}_{\odot}$, $z_{\text{piv}} = 0.46$. The rows contain the best-fitting parameters for the galaxy concentration *c*, the number of galaxies N_{200} , the RS fraction and intrinsic width of the RS. All measurements are made within *R*200. Where possible, the results are shown for the full, RS and non-RS blue populations. The columns contain the observables, as well as the best-fitting normalization *A*, mass slope *B* and redshift slope *C*. The last column shows the intrinsic fractional scatter about the best-fitting relation.

| Obs | A | B | C | $\sigma_{\rm int}$ |
|--------------------|-------------------|---------------|---------------------------------------|--------------------|
| $c_{\rm g}$ | 3.89 ± 0.52 | | $-0.32 \pm 0.18 - 0.31 \pm 0.45$ 0.55 | |
| $c_{\rm g, RS}$ | 5.47 ± 0.53 | | -0.01 ± 0.10 0.15 \pm 0.30 0.38 | |
| $c_{\text{g,nRS}}$ | 3.35 ± 0.38 | | $-0.89 \pm 0.28 - 1.85 \pm 0.55$ 0.00 | |
| N_{200} | 71.1 ± 3.9 | | $0.79 \pm 0.10 - 0.42 \pm 0.31$ 0.31 | |
| $N_{200,RS}$ | 49.8 ± 2.9 | | $0.70 \pm 0.11 - 0.84 \pm 0.34 0.37$ | |
| f_{RS} | 0.68 ± 0.03 | | $-0.10 \pm 0.06 -0.65 \pm 0.21$ 0.14 | |
| σ int.RS | 0.036 ± 0.002 | \sim \sim | $0.58 \pm 0.47 -$ | |

significance. We find a decrease in RS fraction from ∼80 per cent at *z* ∼ 0.1 to ∼55 per cent at *z* ∼ 1.

Our result is in reasonably good agreement with previous studies at low redshifts. Studies of optically selected systems in SDSS at low redshift indicate red fractions within a projected R_{200} for clusters with $N_{200} > 50$ of ~82 per cent at 0.1 < *z* < 0.25 and ∼78 per cent at 0.25 < *z* < 0.35 (Hansen et al. 2009). These are projected rather than virial sphere RS fractions, and the RS fraction is defined with a flat colour bin rather than, as in our case, a probabilistic approach supported by the colour distribution of the data. A separate analysis of SDSS clusters that also relied upon optical mass indicators yielded RS fractions within a fixed metric aperture of ∼1 Mpc between ∼90 per cent and ∼70 per cent in the redshift range $z = 0.12{\text -}0.4$ (Zhang et al. 2013). Both results seem to be in good agreement with an earlier DPOSS-II study (Margoniner et al. 2001). At higher redshift, it is more difficult to compare published results to ours, because many of those RS fraction measurements have been made only in the central regions of the cluster, using a stellar mass cut rather than the $m_* + 2$ magnitude cut we adopt and relying on different definitions of the RS than ours. Nevertheless, we find that Loh et al. (2008) present a study of clusters selected in the Red Cluster Sequence survey to *m*[∗] + 1.5, which shows falling RS fraction with redshift, ending with ∼0.55 in their highest redshift bin (0.85 ≤ *z* ≤ 0.90) in good agreement with the trend we constrain over a somewhat different magnitude range with our SZE-selected cluster sample.

5 CONCLUSIONS

We present results from a study of 74 SZE-selected clusters with redshifts extending to $z \sim 1.1$ from within the overlapping regions of the SPT and DES-SV survey areas. The combination of the deep DES data and this SPT-selected cluster sample provides a unique opportunity to systematically study the galaxy population and its redshift and mass trends in high-mass clusters over a wide range of redshift. Each of these clusters has a robust mass estimate that derives from the cluster SZE detection significance and redshift; these masses include corrections for SZE selection effects and account for the remaining cosmological uncertainties and unresolved systematics in the combined X-ray and velocity dispersion mass calibration data set (Bocquet et al. 2015). Our masses lie in the range of 4.3 \times 10¹⁴ M_{\odot} $\leq M_{200} \leq 2.9 \times 10^{15}$ M_{\odot}. Within the cluster virial region R_{200} , we study the width of the RS as well as the redshift and mass dependences of the galaxy radial profiles, the HON and the RS fraction.

Our study of the radial distributions of galaxies in these clusters indicates that the blue, non-RS and full populations are consistent with NFW profiles of differing concentration out to $4R_{200}$ (see Fig. 11). There is no compelling evidence for systematic density jumps within this region (see the discussion in Patej & Loeb 2016). The blue, non-RS population has a much lower concentration than the RS population, leading to a red fraction that is a strong function of radius within the cluster. The presence of a clustered, blue, non-RS population in all the cluster stacks reinforces the accepted scenario of ongoing infall from the field, which provides a continuous supply of star-forming galaxies within the cluster virial region over the full redshift range of our sample.

In many of the clusters studied here, there are enough galaxies to enable a measure of their individual radial galaxy distributions (see Section 4.2.3). These individual cluster measurements exhibit no statistically significant mass or redshift trend. Our measurements indicate significant variation from cluster to cluster both in

the radial distributions of the galaxies and in the RS fractions, supporting a scenario where there is considerable stochasticity in the growth histories of galaxy clusters. Moreover, the variation in radial distributions both of the full and RS populations, undoubtedly, also reflects the overall youth of these systems and the variety of merger states in which we observe them; this result echoes those long before established at low redshift using both the galaxy distributions, galaxy dynamics and X-ray morphologies (e.g. Geller & Beers 1982; Dressler & Shectman 1988; Mohr et al. 1995).

The observed increase of RS fraction from ∼55 per cent at *z* ∼ 1 to ∼80 per cent at *z* = 0.1 in the individual galaxy measurements (see Section 4.4) constrains the time-scale for the transition of a galaxy on to the RS (McGee et al. 2009). A transition time-scale of the order of 2–3 Gyr appears to provide a reasonable description of the trends in our sample, but further work is needed both on the observational and theoretical sides of this problem. It must be emphasized that there have been studies where the redshift evolution of the red or blue fraction was either weaker or non-existent (e.g. Butcher & Oemler 1984; Smail et al. 1998; De Propris et al. 2003; Andreon et al. 2006; Haines et al. 2009; Raichoor & Andreon 2012), and various selection biases were considered as possible drivers for the trend. Cluster samples that are uniformly selected using a property that does not involve their galaxy populations, which span a large redshift range, and that come with reasonably precise virial mass estimates are therefore desirable to provide maximal leverage for evolutionary studies. In addition, precise and accurate cluster mass estimates are critical so that one is comparing similar portions of the cluster virial volume at different redshifts and masses. From this perspective, the SPT-selected sample we study here offers some advantages to our study. In addition, many current studies measure red fraction as a function of the stellar mass of the galaxies. Given the DES band coverage *griz* in our current data set, this is not an approach we can apply over the full redshift range of our sample, and so we adopt a magnitude based selection.

Our study shows that the intrinsic rest frame $g - r$ RS colour width has a characteristic value of ∼0.03 out to redshift *z* ∼ 0.8 and prefers a width of ∼0.07 at*z* ∼ 1 (see Section 4.1.3). Our constraints at *z* ∼ 1 are consistent with those from recent *HST*-based studies (Mei et al. 2009), and are likely also consistent with what appears to be a higher scatter of ∼0.074 seen in an earlier study of low-redshift clusters (e.g. López-Cruz, Barkhouse & Yee 2004) once those earlier results are corrected for measurement uncertainties. The RS width constrains the heterogeneity in age, metallicity and IMF at fixed galaxy luminosity of the old stellar populations that dominate RS galaxies. More extensive analyses will be required to extract detailed population constraints from the RS width measurements from a well-selected sample over this full redshift range, but the quite small intrinsic scatter out to *z* ∼ 1 underscores the homogeneity of the RS population.

Our sample provides no evidence for a significant redshift trend in N_{200} for the full population, in agreement with most previous analyses (Lin et al. 2006; Muzzin et al. 2007b; Andreon & Congdon 2014, but see Capozzi et al. 2012). Moreover, our study of the individual clusters indicates a characteristic intrinsic scatter of 31 per cent–37 per cent from cluster to cluster at fixed mass and redshift. This scatter is in addition to the Poisson noise and measurement uncertainties in N_{200} . We observe the same mass trend for *N*₂₀₀ seen in earlier studies of local cluster samples (Lin et al. 2004; Rines et al. 2004). This indicates that there are fewer galaxies per unit mass in high-mass clusters than in low-mass clusters over the full redshift range extending to $z \sim 1.1$. At first glance, this result seems strange – suggesting that massive clusters do not reflect the properties of their lower mass building blocks. However, within a hierarchical structure formation scenario, where the more massive the cluster, the larger the fraction of galaxies that have fallen in directly from the field – bypassing the group environment (e.g. McGee et al. 2009), it should, in principle, be possible to produce the observed falling galaxy number per unit mass with mass as long as the galaxy number density per unit mass is lower in the field (see also the discussion in Chiu et al. 2016). At *z* ∼ 1, indications are that the stellar mass fraction in the field is lower than in massive galaxy clusters (van der Burg et al. 2013; Chiu et al. 2016). If, as we expect, the galaxy number per unit mass is tracked well by the stellar mass fraction, then this suggests that a mix of accretion from the field and from subclusters results in the observed weak or absent redshift trend in N_{200} . Further study of this phenomena using galaxy formation simulations with enough volume to track galaxy populations in cluster mass haloes is warranted.

It has been suggested that the growth of the central dominant galaxy within clusters should lead to an observed reduction in the concentration of the galaxies over cosmic time as galaxies merge with the central galaxy (van der Burg et al. 2013). However, our SZE-selected sample of massive clusters does not provide statistically significant evidence for a systematic variation of the concentration with redshift in either the full or RS populations. Moreover, there is no statistically significant trend in the number of galaxies N_{200} within the virial region as a function of redshift (at fixed mass) for the full population. Thus, the picture for how the central galaxies are built up from the rest of the galaxy population is not yet fully clear. Perhaps, with a larger sample, we will be able to better discern these changes and measure the impact of the central galaxy growth on the full galaxy population within the virial region.

Overall, our study underscores the power of combining a large mm-wave survey from SPT that enables SZE cluster selection with the deep, multiband optical survey data set from DES. The selection of the sample is homogeneous and does not directly depend on properties of the galaxy population. Moreover, each cluster has a high-quality SZE mass proxy that has been calibrated to mass over the full redshift range (Bocquet et al. 2015). This, together with the deep and wide area DES data, allows us to study the galaxy populations present in the same portion of the virial region in massive galaxy clusters over the last ∼10 Gyr period in cosmic evolution. This initial examination of the galaxy populations within the SPT-selected clusters will benefit from expansion to the larger sample available today and from an increased focus on the transition of the population from the field to the cluster.

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