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On the Ball-Marsden-Slemrod obstruction in bilinear control systems

Nabile Boussaïd
Laboratoire de Mathématiques de Besançon, UMR 6623
Université de Franche Comté, Besançon, France
Nabile.Boussaid@univ-fcomte.fr

Marco Caponigro Équipe M2N Conservatoire National des Arts et Métiers, Paris, France Marco.Caponigro@cnam.fr

Thomas Chambrion

Université de Lorraine, IECL, UMR 7502, Vandoeuvre-lès-Nancy, F-54506, France CNRS, IECL, UMR 7502, Vandoeuvre-lès-Nancy, F-54506, France Inria, Villers-lès-Nancy, F-54600, France Thomas.Chambrion@univ-lorraine.fr

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Abstract

This note presents an extension to the case of L^1 controls of a well-known obstruction to the controllability of bilinear control systems in infinite dimensional spaces.

1 Introduction

1.1 Bilinear control systems

Let X be a Banach space, $A: D(A) \to X$ a linear operator in X with domain D(A), $B: X \to X$ a linear bounded operator and ψ_0 an element in X. We consider the following bilinear control system

$$\begin{cases} \dot{\psi}(t) &= A\psi(t) + u(t)B\psi(t), \\ \psi(0) &= \psi_0, \end{cases}$$
 (1)

where $u:[0,+\infty)\to \mathbf{R}$ is a scalar function representing the control.

Assumption 1. The pair (A, B) of linear operators in X satisfies

- 1) the operator A generates a C^0 -semigroup of linear bounded operators on X.
- 2) the operator B is bounded.

Definition 1. Assume that (A, B) satisfies Assumption 1. Let T > 0. A function $\psi : [0, T] \to X$ is a mild solution of (1) if for every t in [0, T],

$$\psi(t) = e^{tA}\psi_0 + \int_0^t e^{(t-s)A} B\psi(s) u(s) ds$$
 (2)

Equation (2) is often called Duhamel formula.

Existence and uniqueness for equation (1) is given by the following result (see, for instance, Proposition 2.1 and Remark 2.7 in [BMS82]).

Proposition 1. Assume that (A, B) satisfies Assumption 1. Then, for every ψ_0 in X, for every u in $L^1_{loc}([0, +\infty), \mathbf{R})$, there exists a unique mild solution $t \mapsto \Upsilon^u_{t,0}\psi_0$ to the Cauchy problem (1). Moreover, for every ψ_0 in X, the end-point mapping $\Upsilon_{\cdot,0}\psi_0: [0, +\infty) \times L^1_{loc}([0, +\infty), \mathbf{R}) \to X$ is continuous.

Definition 2. Assume that (A, B) satisfies Assumption 1 and let \mathcal{U} be a subset of $L^1_{loc}([0, +\infty), \mathbf{R})$. For every ψ_0 in X, the attainable set from ψ_0 with controls in \mathcal{U} is defined as

$$\mathcal{A}(\psi_0, \mathcal{U}) = \bigcup_{T \ge 0} \bigcup_{u \in \mathcal{U}} \{\Upsilon_{T,0}^u \psi_0\}.$$

Our main result is the following property of the attainable set of system (1) with L^1 controls.

Theorem 2. Assume that (A, B) satisfies Assumption 1. Then, for every ψ_0 in X, the attainable set $\mathcal{A}(\psi_0, L^1_{loc}([0, +\infty), \mathbf{R}))$ from ψ_0 with L^1_{loc} controls is contained in a countable union of compacts subsets of X.

1.2 The Ball-Marsden-Slemrod obstruction

Our main result Theorem 2 is an extension of the well-known Ball-Marsden-Slemrod obstruction to controllability.

Theorem 3 (Theorem 3.6 in [BMS82]). Assume that (A, B) satisfies Assumption 1. Then, for every ψ_0 in X, the attainable set $\mathcal{A}(\psi_0, \cup_{r>1} L^r_{loc}([0, +\infty), \mathbf{R}))$ from ψ_0 with L^r_{loc} controls, r > 1, is contained in a countable union of compacts subsets of X.

A consequence of Theorem 3 to the framework of the conservative bilinear Schrödinger equation is given by Turinici.

Theorem 4 (Theorem 1 in [Tur00]). Assume that (A, B) satisfies Assumption 1. Then, for every ψ_0 in X, the set $\bigcup_{\alpha>0} \alpha \mathcal{A}(\psi_0, \bigcup_{r>1} L^r_{loc}([0, +\infty), \mathbf{R}))$ is contained in a countable union of compacts subsets of X.

Theorems 2 and 3 are basically empty in the case in which X is finite dimensional, indeed, in this case, X itself is a countable union of compact sets. On the other hand, when X is infinite dimensional, these results represent a strong topological obstruction to the exact controllability. Indeed, compact subsets of an infinite dimensional Banach space have empty interiors and so is a countable union of closed subsets with empty interiors (as a consequence of Baire Theorem).

Let us recall briefly the method used in [BMS82] for the proof of Theorem 3. The first step is to write

$$\begin{split} \mathcal{A}(\psi_0, \cup_{r>1} L^r_{loc}([0, +\infty), \mathbf{R})) &= \bigcup_{T \geq 0} \bigcup_{r>1} \bigcup_{u \in L^r([0, T], \mathbf{R})} \{\Upsilon^u_{T, 0} \psi_0\} \\ &= \bigcup_{l \in \mathbf{N}} \bigcup_{m \in \mathbf{N}} \bigcup_{k \in \mathbf{N}} \bigcup_{0 \leq t \leq l} \left(\bigcup_{\|u\|_{L^{1+1/m}} \leq k} \{\Upsilon^u_{t, 0} \psi_0\} \right). \end{split}$$

Hence it is sufficient to prove that, for every (l, m, k) in \mathbb{N}^3 , the set

$$\mathcal{A}^{l,m,k} = \bigcup_{0 \leq t \leq l} \left(\bigcup_{\|u\|_{L^{1+1/m} \leq k}} \{\Upsilon^u_{t,0} \psi_0\} \right)$$

has compact closure in X. To this end, one considers a sequence $(\psi_n)_{n\in\mathbb{N}}$ in $\mathcal{A}^{l,m,k}$, associated with a sequence of times $(t_n)_{n\in\mathbb{N}}$ in [0,l] and a sequence of controls $(u_n)_{n\in\mathbb{N}}$ in the ball of radius k of $L^{1+1/m}([0,+\infty),\mathbf{R})$. By compactness of [0,l], up to extraction, one can assume that $(t_n)_{n\in\mathbb{N}}$ tends to t_∞ in [0,l]. By Banach-Alaoglu-Bourbaki Theorem, the balls of $L^{1+1/m}([0,+\infty),\mathbf{R})$ are weakly (sequentially) compact and, hence, up to extraction, one can assume that $(u_n)_{n\in\mathbb{N}}$ converges weakly in $L^{1+1/m}([0,+\infty),\mathbf{R})$ to some u_∞ . The hard point of the proof (Lemma 3.7 in [BMS82]) is then to show that $\Upsilon^{u_n}_{t_n,0}\psi_0$ tends to $\Upsilon^{u_\infty}_{t_\infty,0}$ as n tends to infinity.

A crucial point in the proof of Theorem 3 given in [BMS82] is the fact that the closed balls of L^p , p > 1 are weakly sequentially compact. This is no longer true for the balls of L^1 , and this prevents a direct extension of the proof of Theorem 3 to the proof of Theorem 2.

1.3 Content

In this note we present a simple and short proof of Theorem 2. However, historical reasons have made different communities use incompatible terminologies and, in order to avoid ambiguities, we present in Section 2 a quick reminder of basic facts in Banach topologies. Section 3 gives a short introduction to the classical Dyson expansion (Section 3.1) and the proof of an instrumental compactness property (Section 3.2). We conclude in Section 4 with the proof of Theorem 2.

2 Basic facts on the topology in Banach spaces

2.1 Notations

The Banach space X is endowed with norm $\|\cdot\|$. For every ψ_c in X and every r > 0, $B_X(\psi_c, r)$ denotes the ball of center ψ_c and of radius r:

$$B_X(\psi_c, r) = \{ \psi \in X | \|\psi - \psi_c\| < r \}.$$

In the following, all we need to know about generators of C^0 -semigroup is the classical result stated in Proposition 5 (see Chapter VII of [HP57]).

Proposition 5. Assume that A generates a C^0 -semigroup. Then there exist $M, \omega > 0$ such that $||e^{At}|| \leq Me^{\omega t}$ for every $t \geq 0$.

2.2 Compact subset of Banach spaces

Definition 3. Let X be a Banach space and Y be a subset of X. A family $(O_i)_{i \in I}$ is an open cover of Y if O_i is open in X for every i in I and $Y \subset \bigcup_{i \in I} O_i$.

Definition 4. Let X be a Banach space. A subset Y of X is said to be compact if from any open cover of Y, it is possible to extract a finite cover of Y.

Definition 5. Let X be a Banach space. A subset Y of X is said to be sequentially compact if from any sequence $(\psi_n)_{n\in\mathbb{N}}$ taking value in Y, it is possible to extract a subsequence $(\psi_{\phi(n)})_{n\in\mathbb{N}}$ converging in Y.

Definition 6. Let X be a Banach space. A subset Y of X is said to be totally bounded if for every $\varepsilon > 0$, there exist $N \in \mathbb{N}$ and a finite family $(x_i)_{1 \leq i \leq N}$ in X such that

$$Y \subset \bigcup_{i=1}^{N} B_X(x_i, \varepsilon).$$

Proposition 6. Let X be a Banach space. For every subset Y of X, the following assertions are equivalent:

- 1. Y is compact.
- 2. Y is sequentially compact.
- 3. Y is complete and totally bounded.
- 4. Y is closed and totally bounded.

Proposition 7. Let X be a Banach space, N in **N** and $(Y_i)_{1 \leq i \leq N}$ a finite family of compact subsets of X. Then, the finite sum

$$\sum_{i=1}^{N} Y_i = \{ y_1 + y_2 + \ldots + y_N \mid y_i \in Y_i, i = 1, \ldots, N \}$$

is compact as well.

Proposition 8. Let X be a Banach space, N in N and $(Y_i)_{1 \leq i \leq N}$ a finite family of totally bounded subsets of X. Then, the finite sum

$$\sum_{i=1}^{N} Y_i = \{ y_1 + y_2 + \ldots + y_N \mid y_i \in Y_i, i = 1, \ldots, N \}$$

is totally bounded as well.

Proposition 9. Let X be a Banach space, T > 0 and (A, B) satisfies Assumption 1. Define the mapping

$$\begin{array}{cccc} F: & [0,T] \times [0,T] \times X & \to & X \\ & (s,t,\psi) & \mapsto & e^{|t-s|A}B\psi \end{array}$$

Then, for every totally bounded subset Y of X, the set $F([0,T] \times [0,T] \times Y)$ is totally bounded as well.

Proof. We claim that $G:(t,\psi)\mapsto e^{tA}\psi$ is jointly continuous in its two variables. Indeed, for every ψ,ψ_0 in X, for every $t,t_0\geq 0$,

$$||e^{tA}\psi - e^{t_0A}\psi_0|| \le ||e^{tA}(\psi - \psi_0)|| + ||(e^{tA} - e^{t_0A})\psi_0||$$

$$\le Me^{\omega t}||\psi - \psi_0|| + ||(e^{tA} - e^{t_0A})\psi_0||.$$

This last quantity tends to zero as (t, ψ) tends to (t_0, ψ_0) . As a consequence, F is continuous (as composition of continuous functions).

If Y is totally bounded, the topological closure \bar{Y} of Y is compact (because the ambient space X is complete). Hence $[0,T]\times[0,T]\times\bar{Y}$ is compact. By continuity, $F([0,T]\times[0,T]\times\bar{Y})$ is compact, hence is totally bounded. The set $F([0,T]\times[0,T]\times Y)$, which is contained in $F([0,T]\times[0,T]\times\bar{Y})$, is, therefore, totally bounded as well.

2.3 Partition of unity in Banach spaces

Definition 7. Let X a Banach space. A family $(x_i)_{i\in I}$ of points of X is locally finite if for every x in X and every R > 0, the cardinality of the set

$$\left(\bigcup_{i\in I} \{x_i\}\right) \cap B_X(x,R)$$

is finite.

Definition 8. Let X be a Banach space, Y be a subset of X, and $(O_i)_{i \in I}$ be an open cover of Y. A family $(\phi_i)_{i \in I}$ of continuous functions from Y to [0,1] is called a partition of the unity of Y adapted to the cover $(O_i)_{i \in I}$ if

- (i) for every $i \in I$, $\phi_i(x) = 0$ for every $x \notin O_i$;
- (ii) $\sum_{i \in I} \phi_i(x) = 1$ for every $x \in Y$.

Proposition 10. Let X be a Banach space, Y a subset of X, $\delta > 0$, $(x_j)_{j \in J}$ a locally finite family of points in Y such that $Y \subset \bigcup_{j \in J} B_X(x_j, \delta)$. Then, there exists $(\phi_j)_{j \in J}$ a partition of the unity adapted to the open cover $(B(x_j, 2\delta))_{j \in J}$ of Y.

Moreover, if a family $(\phi_j)_{j\in J}$ is a partition of the unity adapted to the open cover $(B_X(x_j, 2\delta))_{j\in J}$, then for every x in Y, $||x - \sum_{j\in J} \phi_j(x)x_j|| \leq 2\delta$.

Proof. We first prove the existence of a partition of the unity adapted to the open cover $(B_X(x_j, 2\delta))_{j \in J}$ of Y. To this end, we define, for every j in J, the continuous functions $\varphi_j : X \to [0, 1]$ by

$$\begin{cases} \varphi_{j}(x) = 1, & \text{if } ||x - x_{j}|| < \delta, \\ \phi_{j}(x) = 2 - ||x - x_{j}|| / \delta, & \text{if } \delta \leq ||x - x_{j}|| < 2\delta, \\ \varphi_{j}(x) = 0, & \text{if } 2\delta \leq ||x - x_{j}||. \end{cases}$$

Since the family $(x_j)_{j\in J}$ is locally finite, the sum $\sum_{j\in J} \varphi_j(x)$ converges for every x in Y. Moreover, since $Y\subset \bigcup_{j\in J} B(x_j,\delta)$, the function $x\mapsto \sum_{j\in J} \varphi_j(x)$ does not vanish on Y. For every j_0 in J, we define ϕ_{j_0} by

$$\phi_{j_0}(x) = \varphi_{j_0}(x) \frac{1}{\sum_{j \in J} \varphi_j(x)},$$

and the family $(\phi_j)_{j\in J}$ is a partition of the unity adapted to the open cover $(B_X(x_j, 2\delta))_{j\in J}$ of Y.

We now prove the second point of Proposition 10. Let $(\phi_j)_{j\in J}$ be a partition of unity of Y adapted to the cover $(B_X(x_j, 2\delta))_{j\in J}$. Then, for every x in Y,

$$\left\| x - \sum_{j \in J} \phi_j(x) x_j \right\| = \left\| \sum_{j \in J} \phi_j(x) x - \sum_{j \in J} \phi_j(x) x_j \right\|$$

$$= \left\| \sum_{j \in J} \phi_j(x) (x - x_j) \right\|$$

$$\leq \sum_{j \in J} \phi_j(x) \left\| x - x_j \right\|.$$

By construction, $\phi_i(x) = 0$ as soon as $||x - x_i|| \ge 2\delta$. Hence,

$$\left\| x - \sum_{j \in J} \phi_j(x) x_j \right\| \le 2\delta \sum_{j \in J} \phi_j(x) \le 2\delta,$$

which concludes the proof.

3 The Dyson expansion

3.1 The Dyson Operators

For every u in $L^1_{loc}([0,+\infty),\mathbf{R})$, $p\in\mathbf{N}$, and $t\geq 0$ we define the linear bounded operator $W_p(t,u):X\to X$ recursively by

$$W_0(t,u)\psi = e^{(t-s)A}\psi$$

$$W_p(t,u)\psi = \int_0^t e^{(t-s)A}BW_{p-1}(s,u)\psi u(s)\mathrm{d}s, \quad \text{for } p \ge 1,$$

for every ψ in X. We have the following estimate on the norm of the operator.

Proposition 11. For every u in $L^1_{loc}([0,+\infty),\mathbf{R}), p \in \mathbf{N}$, and $t \geq 0$

$$||W_p(t,u)|| \le \frac{Me^{\omega t}||B||^p(\int_0^t |u(s)|ds)^p}{p!}.$$

Proof. We prove the result by induction on p in \mathbf{N} . For p=0 the result clearly follows from Proposition 5. Assume that the result holds for $p \geq 0$. Then, for every ψ in X,

$$||W_{p+1}(t,u)\psi|| \leq \int_0^t e^{(t-s)A} BW_p(s,u)\psi u(s) ds$$

$$\leq M \int_0^t e^{(t-s)\omega} ||B|| \frac{e^{\omega s} ||B||^p (\int_0^s |u(\tau)| d\tau)^p}{p!} u(s) ds$$

$$\leq M e^{\omega t} ||B||^{p+1} \frac{(\int_0^t |u(\tau)| d\tau)^{p+1}}{(p+1)!}.$$

The last inequality follows from Proposition 5. We conclude the proof by induction on p.

3.2 A compactness property

Lemma 12. For every j in \mathbb{N} , $T \geq 0$ and $K \geq 0$, and ψ in X the set

$$\mathcal{W}_{j}^{T,K} = \{ W_{j}(t, u)\psi \mid 0 \le t \le T, \|u\|_{L^{1}} \le K \}, \tag{3}$$

is totally bounded

Proof. We prove the result by induction on j in \mathbf{N} . For j=0, consider $\mathcal{W}_0^{T,K}=\{e^{tA}\psi, 0\leq t\leq T\}$ and let $(w_n)_{n\in\mathbf{N}}$ be a sequence in $\mathcal{W}_0^{T,K}$. Then there exists a sequence $(t_n)_{n\in\mathbf{N}}$ such that $w_n=e^{t_nA}\psi$ for every n. Up to extraction $\lim_{n\to\infty}t_n=t\in[0,T]$ since [0,T] is compact. By definition of C^0 semigroup, $\lim_{n\to\infty} e^{t_n A} \psi = e^{tA} \psi$. This proves that $\mathcal{W}_0^{T,K}$ is sequentially compact, hence compact and, in particular, totally bounded (Proposition 6). Assume that, for $j \geq 0$, $\mathcal{W}_{j}^{T,K}$ is totally bounded. By Proposition 9, the set

$$Z_j^{T,K} := \{e^{(t-s)A}B\psi, \psi \in W_j^{T,K}, 0 \le s \le t \le T\}$$

$$\subset F([0,T]^2 \times W_j^{T,K})$$

is totally bounded as well.

Let $\varepsilon > 0$ be given and define $\delta = \frac{\varepsilon}{2K+1} > 0$. Since $Z_j^{T,K}$ is totally bounded, there exists a finite family $(x_i)_{1 \leq i \leq N_\delta}$ in $Z_i^{T,K}$ such that

$$Z_j^{T,K} \subset \bigcup_{i=1}^{N_\delta} B_X(x_i, \delta).$$

Let $(\phi_i)_{\leq i \leq N_\delta}$ be a partition of the unity adapted to the cover $\bigcup_{i=1}^{N_\delta} B(x_i, 2\delta)$ of $Z_i^{T,K}$. Such a partition of the unity exists by Proposition 10, and moreover, for every x in $Z_j^{T,K}$, we have

$$\left\| x - \sum_{i=1}^{N_{\delta}} \phi_i(x) x_i \right\| \le 2\delta. \tag{4}$$

Applying the inequality (4) with $x = e^{(t-s)A}BW_i(s,u)\psi_0$, we get, for every u in L¹ and every (s,t)such that $0 \le s \le t$,

$$\left\| e^{(t-s)A}BW_j(s,u)\psi_0 - \sum_{i=1}^{N_\delta} \phi_i(e^{(t-s)A}BW_j(s,u)\psi_0)x_i \right\| \le 2\delta.$$

Multiplying by u(s) and integrating for s in [0,t], one gets for $||u||_{L^1} \leq K$

$$\left\| \int_0^t e^{(t-s)A} BW_j(s,u) \psi_0 u(s) ds - \sum_{i=1}^{N_{\delta}} \int_0^t \phi_i(e^{(t-s)A} BW_j(s,u) \psi_0) u(s) ds \, x_i \right\| \le 2\delta K. \tag{5}$$

The set $\sum_{i=1}^{N_{\delta}} [0, K] x_i$ is compact by Proposition 7 and, hence, totally bounded. Then there exists a finite family $(y_i)_{1 \leq i \leq N'_{\delta}}$ such that

$$\sum_{i=1}^{N_{\delta}} [0, K] x_i \subset \bigcup_{i=1}^{N_{\delta}'} B_X(y_i, \delta). \tag{6}$$

From (5) and (6), one deduces that

$$\mathcal{W}_{j+1}^{T,K} \subset \bigcup_{i=1}^{N_{\delta}'} B_X(y_i, (2K+1)\delta) = \bigcup_{i=1}^{N_{\delta}'} B_X(y_i, \varepsilon).$$

This proves that $\mathcal{W}_{j+1}^{T,K}$ is totally bounded and concludes the proof.

3.3 Convergence of the Dyson expansion

Proposition 13. For every u in $L^1([0,+\infty), \mathbf{R})$, $t \ge 0$, and $\psi_0 \in X$

$$\left\|\Upsilon_{t,0}^{u}\psi_{0}\right\| \leq Me^{\omega t}\|\psi_{0}\|\exp\left(Me^{\omega t}\|B\|\int_{0}^{t}|u(s)|\mathrm{d}s\right)$$

Proof. The proof follows the proof of [BMS82, Theorem 2.5]. By Duhamel formula (2) and Proposition 5,

$$\|\Upsilon_{t,0}^{u}\psi_{0}\| = \left\| e^{tA}\psi_{0} + \int_{0}^{t} e^{(t-s)A}B\Upsilon_{s,0}^{u}\psi_{0}u(s)ds \right\| e^{t\omega}\psi_{0}$$

$$\leq Me^{t\omega}\|\psi_{0}\| + \int_{0}^{t} Me^{\omega(t-s)}\|B\| \|\Upsilon_{s,0}^{u}\psi_{0}\| u(s)ds,$$

and the conclusion follows by Gronwall lemma (see [BMS82, Lemma 2.6]).

Proposition 14. For every u in $L^1([0,+\infty), \mathbf{R})$, p in \mathbf{N} , $t \geq 0$, and ψ_0 in X

$$\lim_{p \to \infty} \left\| \int_0^t e^{(t-s)A} BW_p(s,t) \Upsilon^u_{s,0} \psi_0 u(s) \mathrm{d}s \right\| = 0.$$

Proof. Consider

$$\left\| \int_0^t e^{(t-s)A} BW_p(s,t) \Upsilon^u_{s,0} \psi_0 u(s) \mathrm{d}s \right\| \leq \int_0^t \|e^{(t-s)A} \| \|B\| \|W_p(s,t) |\Upsilon^u_{s,0} \psi_0\| |u(s)| \mathrm{d}s$$

and recall that $||W_p(s,t)||$ tends to zero as p tends to infinity (Proposition 11).

Proposition 15. For every u in $L^1_{loc}([0,+\infty), \mathbf{R})$, p in \mathbf{N} , $t \geq 0$, and ψ_0 in X

$$\Upsilon_{t,0}^u \psi_0 = \sum_{p=0}^{\infty} W_p(t,0,u) \psi_0.$$

Proof. Applying iteratively p-times Duhamel formula (2), one gets

$$\Upsilon_{t,0}^{u}\psi_{0} = e^{tA}\psi_{0} + \int_{0}^{t} e^{(t-s)A}Bu(s)\Upsilon_{s,0}^{u}\psi_{0}ds$$

$$= e^{tA}\psi_{0} + \int_{0}^{t} e^{(t-s)A}Bu(s)e^{sA}\psi_{0}ds + \int_{0}^{t} e^{(t-s)A}BW_{1}(s,t)\Upsilon_{s,0}^{u}\psi_{0}u(s)u(s)ds$$

$$= \sum_{i=1}^{p} W_{p}(t,0)\psi_{0} + \int_{0}^{t} e^{(t-s)A}BW_{p}(s,t)\Upsilon_{s,0}^{u}\psi_{0}u(s)ds.$$

Hence, for every $p \geq 1$,

$$\Upsilon_{t,0}^{u}\psi_{0} - \sum_{i=0}^{p} W_{j}(t,0)\psi_{0} = \int_{0}^{t} e^{(t-s)A}BW_{p}(s,t)\Upsilon_{s,0}^{u}\psi_{0}u(s)ds$$

and the result follow from Proposition 14 as p tends to ∞ .

4 Proof of Theorem 2

We proceed now to the proof of Theorem 2. First of all, notice that, for every ψ_0 in X,

$$\mathcal{A}(\psi_0, L^1_{loc}([0, +\infty), \mathbf{R}))$$

$$= \bigcup_{l \in \mathbf{N}} \bigcup_{m \in \mathbf{N}} \{\Upsilon^u_{t,0} \psi_0, ||u||_{L^1} \le l, 0 \le t \le m\},$$

and it is enough to prove that, for every l and m in N, the set

$$\{\Upsilon_{t,0}^u \psi_0, \|u\|_{L^1} \le l, 0 \le t \le m\}$$

is totally bounded.

Let $\varepsilon > 0$. From the convergence of the Dyson expansion (Proposition 15) and the bound on the operators W_i (Proposition 11), there exists a integer N_{ε} such that

$$\left\| \sum_{p \ge N_{\varepsilon}} W_p(t, u) \psi_0 \right\| \le \frac{\varepsilon}{2}, \tag{7}$$

for every t in [0, m] and every u such that $||u||_{L^1} \leq l$. For each $j = 1, \ldots, N_{\varepsilon}$ the sets $\mathcal{W}_j^{m,l}$, defined by (3), are totally bounded (Lemma 12), hence their sum

$$\sum_{j=0}^{N_{\varepsilon}} \mathcal{W}_{j}^{m,l}$$

is totally bounded as well (Proposition 8). Hence there exists a family $(x_i)_{1 \leq i \leq N_1}$ of points of $\sum_{j=0}^{N_{\varepsilon}} \mathcal{W}_j^{m,l}$ such that

$$\sum_{i=0}^{N_{\varepsilon}} \mathcal{W}_{j}^{m,l} \subset \bigcup_{i=1}^{N_{1}} B_{X}\left(x_{i}, \frac{\varepsilon}{2}\right). \tag{8}$$

Gathering (7) and (8), one gets

$$\sum_{j=0}^{\infty} \mathcal{W}_{j}^{m,l} \subset \bigcup_{i=1}^{N_{1}} B_{X}\left(x_{i},\varepsilon\right),\,$$

which concludes the proof of Theorem 2.

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