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# LOGARITHMIC STABILITY OF PARABOLIC CAUCHY PROBLEMS 

MOURAD CHOULLI AND MASAHIRO YAMAMOTO $\dagger$


#### Abstract

The uniqueness of parabolic Cauchy problems is nowadays a classical problem and since Hadamard [6] these kind of problems are known to be ill-posed and even severely ill-posed. Until now there are only few partial results concerning the quantification of the stability for parabolic Cauchy problems. In the present article, we bring the complete answer to this issue, provided that the space domain has finite diameter with respect to the geodesic distance and assuming that solutions are sufficiently smooth.


Mathematics subject classification : 35R25, 35K99, 58J35
Key words : Parabolic Cauchy problems, logarithmic stability, Carleman inequality, Hardy inequality.

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## 1. Introduction

Throughout this article, $\Omega$ is a bounded domain of $\mathbb{R}^{n}$ with Lipschitz boundary $\Gamma$. We denote the geodesic distance on $\Omega$ associated to the round metric by $d_{g}$. That is

$$
d_{g}(x, y)=\inf \left\{\int_{0}^{1}|\dot{\psi}(t)| d t ; \psi:[0,1] \rightarrow \Omega \text { is a piecewise } C^{1} \text { path joining } x \text { to } y\right\}
$$

We denote by $\mathbf{d}_{g}$ the diameter of $\Omega$ with respect to the distance $d_{g}$ :

$$
\mathbf{d}_{g}=\sup \left\{d_{g}(x, y) ; x, y \in \Omega\right\}
$$

We consider the parabolic operator

$$
L=\operatorname{div}(A \nabla \cdot)-\partial_{t} .
$$

Here $A=\left(a^{i j}\right)$ is a symmetric matrix whose coefficients belong to $W^{1, \infty}(\Omega)$ and satisfy: there exist $\kappa>0$ and $K>0$ so that

$$
\begin{equation*}
A(x) \xi \cdot \xi \geq \kappa|\xi|^{2}, \quad x \in \Omega, \xi \in \mathbb{R}^{n} \tag{1.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|a^{i j}\right\|_{W^{1, \infty}(\Omega)} \leq K, \quad 1 \leq i, j \leq n \tag{1.2}
\end{equation*}
$$

We recall that $\Omega$ has the uniform exterior sphere property if there exists $\rho>0$ so that, to any $\widetilde{x} \in \Gamma$ corresponds $x_{0}=x_{0}(\widetilde{x}) \in \mathbb{R}^{n} \backslash \bar{\Omega}$ for which

$$
B\left(x_{0}, \rho\right) \cap \Omega=\emptyset \text { and } \overline{B\left(x_{0}, \rho\right)} \cap \bar{\Omega}=\{\widetilde{x}\}
$$

[^0]Let $t_{0}<t_{1}, Q=\Omega \times\left(t_{0}, t_{1}\right)$ and fix $0<\alpha<1$. For sake of simplicity, we use in the sequel the following notation:

$$
\mathscr{X}^{j}=C^{1+\alpha, \frac{1+\alpha}{2}}(\bar{Q}) \cap H^{j}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right), \quad j=1,2 .
$$

We endow $\mathscr{X}^{j}$ with its natural norm

$$
\|u\|_{\mathscr{X}^{j}}=\|u\|_{C^{1+\alpha, \frac{1+\alpha}{2}}(\bar{Q})}+\|u\|_{H^{j}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)} .
$$

From now on we assume that $t_{1}-t_{0} \leq T_{0}$, for some fixed $T_{0}>0$.
We are mainly concerned in the present work with the stability issue for the Cauchy problem associated to the parabolic operator $L$. Precisely we are going to prove

Theorem 1.1. Assume that $\Omega$ possesses the uniform exterior sphere property and $\mathbf{d}_{g}<\infty$. Let $\Gamma_{0}$ be a nonempty open subset of $\Gamma$. Then there exist two constant $C>0$ and $\gamma>0$ depending on $\Omega, \kappa, K, T_{0}, \alpha$ and $\Gamma_{0}$, so that, for any $u \in \mathscr{X}^{2}$ satisfying $L u=0$ in $Q$, we have

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\|u\|_{\mathscr{X}^{2}}\left[\ln \left(\frac{\|u\|_{\mathscr{X}^{2}}}{\mathcal{C}\left(u, \Gamma_{0}\right)}\right)\right]^{-\gamma}+\mathcal{C}\left(u, \Gamma_{0}\right),
$$

where

$$
\mathcal{C}\left(u, \Gamma_{0}\right)=\|u\|_{H^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)} .
$$

The stability estimate in Theorem 1.1 is of logarithmic type. Similarly to the elliptic case one can not reasonably expect Lipschitz or Hölder stability.

We observe that Theorem 1.1 remains valid if $L$ is substituted by $L$ plus an operator of first order in space variable whose coefficients are bounded.

The second author [10, Theorem 5.1, page 24] proved a Hölder stability in a proper subdomain of $Q$ depending on the part of the lateral boundary where the Cauchy data is given. In [9, Theorem 3.5.1, pages 45 and 46], Vessella establishes a local Hölder stability corresponding to the continuation of Cauchy data to an interior subdomain for solutions vanishing at the initial time. Recently, Bourgeois [1, Main theorem, page 2] proved a result similar to the one in Theorem 1.1 in the case where $L=\Delta-\partial_{t}, \Omega=D \backslash O, D$ and $O$ are two domains of class $C^{2}, O \Subset D$, and $\Gamma_{0}=\partial D$ or $\Gamma_{0}=\partial O$. His result is based on a global Carleman estimate in which the weight function is built from the distance to the boundary of the space variable.

The present work constitute an extension of the earlier result by Bourgeois [1], but for more regular solutions and some class of domains. The proof of the main result is inspired by that used in the elliptic case by the first author in [2]. Note however that there is a great difference between the elliptic and parabolic cases. The main difficulty in the parabolic case is that the initial time and the final time data are missing. So the proofs are more technical. The idea to overcome the fact that the initial time and the final time data are not known is to use a Hardy inequality with respect to time variable. This is explain why we need to work with sufficiently smooth solutions. The assumption that the domain must have finite diameter with respect to the geodesic distance is essential in our proof. We do not know whether this geometric assumption is necessary.

Althrought we used classical tools to establish our main result, the result itself is completely know. This is our modest contribution to stability issue for parabolic Cauchy problems.

A key tool in our analysis is a Carleman inequality (Theorem 2.2 below). We observe that Carleman inequalities are very useful tool in control theory or for establishing a unique continuation property for elliptic and parabolic partial differential equations. There is wide literature on the subject. We just quote here the few reference $[1,3,4,8]$.

The rest of this article is organized as follows. Section 2 is devoted to a three-cylinder interpolation inequality for the $H_{x}^{1}$ - $L_{t}^{2}$-norm. This inequality will be very useful for continuing the data on an interior subdomain to the lateral boundary data, and to continue the data from one subdomain to another subdomain. This is what we show in Section 3 and, as byproduct, we prove a logarithmic stability estimate corresponding
to the unique continuation from an interior data. The proof of Theorem 1.1 is completed in Section 4 by beforehand establishing a result which quantifies the stability from Cauchy data to an interior subdomain.

## 2. Three-Cylinder interpolation inequality

We prove in this section
Theorem 2.1. There exist $C>0$ and $0<\vartheta<1$ depending on $\kappa, K, \Omega$ and $T_{0}$, so that, for any $0<\epsilon<$ $\frac{t_{1}-t_{0}}{2}, u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q, y \in \Omega$ and $0<r<r_{y}(\epsilon)=\min \left(\frac{1}{3} \operatorname{dist}(y, \Gamma), \sqrt{\epsilon}\right)$, we have

$$
\begin{equation*}
r^{3}\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}(B(y, 2 r))\right)} \leq C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, r))\right)}^{\vartheta}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, 3 r))\right)}^{1-\vartheta} \tag{2.1}
\end{equation*}
$$

The proof of Theorem (2.1) is based on a Carleman inequality for a family of parabolic operators. To this end, let $\mathcal{I}$ be an arbitrary set and consider the family of operators

$$
L_{s}=\operatorname{div}\left(A_{s} \nabla \cdot\right)-\partial_{t}, \quad s \in \mathcal{I}
$$

where, for each $s \in \mathcal{I}, A_{s}=\left(a_{s}^{i j}\right)$ is a symmetric matrix with $W^{1, \infty}(\Omega)$ entries so that the following assumptions hold: there exist $\kappa>0$ and $K>0$ so that

$$
\begin{equation*}
A_{s}(x) \xi \cdot \xi \geq \kappa|\xi|^{2}, \quad x \in \Omega, \xi \in \mathbb{R}^{n} \text { and } s \in \mathcal{I} \tag{2.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|a_{s}^{i j}\right\|_{W^{1, \infty}(\Omega)} \leq K, \quad 1 \leq i, j \leq n, s \in \mathcal{I} \tag{2.3}
\end{equation*}
$$

Pick $\psi \in C^{2}(\bar{\Omega})$ without critical points in $\bar{\Omega}$ and set $\Sigma=\Gamma \times\left(t_{0}, t_{1}\right)$. Let

$$
g(t)=\frac{1}{\left(t-t_{0}\right)\left(t_{1}-t\right)}
$$

and

$$
\varphi(x, t)=g(t)\left(e^{4 \lambda\|\psi\|_{\infty}}-e^{\lambda\left(2\|\psi\|_{\infty}+\psi(x)\right)}\right), \quad \chi(x, t)=g(t) e^{\lambda\left(2\|\psi\|_{\infty}+\psi(x)\right)}
$$

Theorem 2.2. (Carleman inequality) There exist three positive constants $C, \lambda_{0}$ and $\tau_{0}$ depending only on $\psi, \Omega, \kappa, K$ and $T_{0}$, so that

$$
\begin{align*}
& C \int_{Q}\left(\lambda^{4} \tau^{3} \chi^{3} u^{2}+\lambda^{2} \tau \chi|\nabla u|^{2}\right) e^{-2 \tau \varphi} d x d t \\
& \left.\quad \leq \int_{Q}\left(L_{s} u\right)^{2} e^{-2 \tau \varphi} d x d t+\int_{\Sigma}\left(\lambda^{3} \tau^{3} \chi^{3} u^{2}+\lambda \tau \chi|\nabla u|^{2}+(\lambda \tau \chi)^{-1}\left|\partial_{t} u\right|^{2}\right)\right) e^{-2 \tau \varphi} d \sigma d t \tag{2.4}
\end{align*}
$$

for all $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right), s \in \mathcal{I}, \lambda \geq \lambda_{0}$ and $\tau \geq \tau_{0}$.
Proof. Since the dependance of the constants will be uniform with respect to $s \in \mathcal{I}$, we drop for simplicity the subscript $s$ in $L_{s}$ and its coefficients. On the other hand since $C^{\infty}(\bar{Q})$ is dense in $H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ it is enough to prove (2.4) when $u \in C^{\infty}(\bar{Q})$.

Let $\Phi=e^{\tau \varphi}$ and $u \in C^{\infty}(\bar{Q})$, and set $w=\Phi^{-1} u$ extended by continuity at $t=0$ and $t=T$ by setting $w(\cdot, 0)=w(\cdot, T)=0$. Then straightforward computations give

$$
P w=\left[\Phi^{-1} L \Phi\right] w=P_{1} w+P_{2} w+c w
$$

where

$$
\begin{aligned}
& P_{1} w=a w+\operatorname{div}(A \nabla w)-\tau \partial_{t} \varphi w \\
& P_{2} w=B \cdot \nabla w+b w-\partial_{t} w
\end{aligned}
$$

with

$$
\begin{aligned}
& a=a(x, t, \lambda, \tau)=\lambda^{2} \tau^{2} \chi^{2}|\nabla \psi|_{A}^{2} \\
& B=B(x, t, \lambda, \tau)=-2 \lambda \tau \chi A \nabla \psi \\
& b=b(x, t, \lambda, \tau)=-2 \lambda^{2} \tau \chi|\nabla \psi|_{A}^{2} \\
& c=c(x, t, \lambda, \tau)=-\lambda \tau \chi \operatorname{div}(A \nabla \psi)+\lambda^{2} \tau \chi|\nabla \psi|_{A}^{2}
\end{aligned}
$$

Here

$$
|\nabla \psi|_{A}=\sqrt{A \nabla \psi \cdot \nabla \psi}=\left|A^{\frac{1}{2}} \nabla u\right|
$$

We obtain by making integrations by parts

$$
\begin{align*}
\int_{Q} a w B \cdot \nabla w d x d t & =\frac{1}{2} \int_{Q} a B \cdot \nabla w^{2} d x d t  \tag{2.5}\\
& =-\frac{1}{2} \int_{Q} \operatorname{div}(a B) w^{2} d x d t+\frac{1}{2} \int_{\Sigma} a B \cdot \nu w^{2} d \sigma d t
\end{align*}
$$

and

$$
\begin{align*}
& \int_{Q} \operatorname{div}(A \nabla w) B \cdot \nabla w d x d t=-\int_{Q} A \nabla w \cdot \nabla(B \cdot \nabla w) d x d t+\int_{\Sigma} B \cdot \nabla w A \nabla w \cdot \nu d \sigma d t  \tag{2.6}\\
& =-\int_{Q} B^{\prime} \nabla w \cdot A \nabla w d x d t \\
& \quad-\int_{Q} \nabla^{2} w B \cdot A \nabla w d x d t+\int_{\Sigma}(B \cdot \nabla w)(A \nabla w \cdot \nu) d \sigma d t
\end{align*}
$$

Here $B^{\prime}=\left(\partial_{i} B_{j}\right)$ is the Jacobian matrix of $B$ and $\nabla^{2} w=\left(\partial_{i j}^{2} w\right)$ is the Hessian matrix of $w$.
But

$$
\begin{aligned}
\int_{Q} B_{i} \partial_{i j}^{2} w a^{i k} \partial_{k} w d x d t=- & \int_{Q} B_{i} a^{i k} \partial_{i k}^{2} w \partial_{j} w d x d t \\
& -\int_{Q} \partial_{i}\left[B_{i} a^{i k}\right] \partial_{k} w \partial_{j} w d x d t+\int_{\Sigma} B_{i} \nu_{i} a^{j k} \partial_{k} w \partial_{j} w d \sigma d t
\end{aligned}
$$

Therefore

$$
\begin{align*}
\int_{Q} \nabla^{2} w B \cdot A \nabla w d x d t=-\frac{1}{2} \int_{Q} & ([\operatorname{div}(B) A+\widetilde{A}] \nabla w) \cdot \nabla w d x d t  \tag{2.7}\\
& +\frac{1}{2} \int_{\Sigma}|\nabla w|_{A}^{2} B \cdot \nu d \sigma d t
\end{align*}
$$

with $\widetilde{A}=\left(\widetilde{a}^{i j}\right), \widetilde{a}^{i j}=B \cdot \nabla a^{i j}$.
It follows from (2.6) and (2.7)

$$
\begin{align*}
& \int_{Q} \operatorname{div}(A \nabla w) B \cdot \nabla w d x d t=\frac{1}{2} \int_{Q}\left(-2 A B^{\prime}+\operatorname{div}(B) A+\widetilde{A}\right) \nabla w \cdot \nabla w d x d t  \tag{2.8}\\
& +\int_{\Sigma}(B \cdot \nabla w)(A \nabla w \cdot \nu) d \sigma d t-\frac{1}{2} \int_{\Sigma}|\nabla w|_{A}^{2} B \cdot \nu d \sigma d t .
\end{align*}
$$

A new integration by parts yields

$$
\int_{Q} \operatorname{div}(A \nabla w) b w d x d t=-\int_{Q} b|\nabla w|_{A}^{2} d x d t-\int_{Q} w \nabla b \cdot A \nabla w d x d t+\int_{\Sigma} b w A \nabla w \cdot \nu d \sigma d t
$$

This and the following inequality

$$
-\int_{Q} w \nabla b \cdot A \nabla w d x d t \geq-\int_{Q}\left(\lambda^{2} \chi\right)^{-1}|\nabla b|_{A}^{2} w^{2} d x d t-\int_{Q} \lambda^{2} \chi|\nabla w|_{A}^{2} d x d t
$$

imply

$$
\begin{align*}
& \int_{Q} \operatorname{div}(A \nabla w) b w d x d t \geq-\int_{Q}\left(b+\lambda^{2} \chi\right)|\nabla w|_{A}^{2} d x d t-\int_{Q}\left(\lambda^{2} \chi\right)^{-1}|\nabla b|_{A}^{2} w^{2} d x d t  \tag{2.9}\\
&+\int_{\Gamma} b w A \nabla w \cdot \nu d \sigma d t
\end{align*}
$$

One more time, integrations by parts entail

$$
\begin{align*}
\int_{Q} a w \partial_{t} w d x d t & =\frac{1}{2} \int_{Q} a \partial_{t} w^{2} d x d t=-\frac{1}{2} \int_{Q} \partial_{t} a w^{2} d x d t  \tag{2.10}\\
\int_{Q} \partial_{t} \varphi w \partial_{t} w d x d t & =\frac{1}{2} \int_{Q} \partial_{t} \varphi \partial_{t} w^{2} d x d t=-\frac{1}{2} \int_{Q} \partial_{t}^{2} \varphi w^{2} d x d t  \tag{2.11}\\
\int_{Q} \partial_{t} \varphi w B \cdot \nabla w d x d t & =\frac{1}{2} \int_{Q} \partial_{t} \varphi B \cdot \nabla w^{2} d x d t  \tag{2.12}\\
& =\frac{1}{2} \int_{Q} \operatorname{div}\left(\partial_{t} \varphi B\right) w^{2} d x d t+\frac{1}{2} \int_{\Sigma} \partial_{t} \varphi B \cdot \nu w^{2} d \sigma d t
\end{align*}
$$

Also

$$
\begin{equation*}
\int_{Q} \operatorname{div}(A \nabla w) \partial_{t} w d x d t=-\int_{Q} A \nabla w \cdot \nabla \partial_{t} w d x d t+\int_{\Sigma} A \nabla w \cdot \nu \partial_{t} w d \sigma d t \tag{2.13}
\end{equation*}
$$

But

$$
\int_{Q} A \nabla w \cdot \nabla \partial_{t} w d x d t=-\int_{Q} A \nabla \partial_{t} w \cdot \nabla w d x d t=-\int_{Q} \nabla \partial_{t} w \cdot A \nabla w d x d t
$$

Whence

$$
\int_{Q} A \nabla w \cdot \nabla \partial_{t} w d x d t=0
$$

This identity in (2.13) gives

$$
\begin{equation*}
\int_{Q} \operatorname{div}(A \nabla w) \partial_{t} w=\int_{\Sigma} A \nabla w \cdot \nu \partial_{t} w d \sigma d t . \tag{2.14}
\end{equation*}
$$

Now a combination of $(2.5),(2.8),(2.9)-(2.12)$ and (2.14) gives

$$
\begin{equation*}
\int_{Q} P_{1} w P_{2} w d x d t-\int_{Q} c^{2} w^{2} d x d t \geq \int_{Q} f w^{2} d x d t+\int_{Q} F \nabla w \cdot \nabla w d x d t+\int_{\Sigma} g(w) d \sigma d t \tag{2.15}
\end{equation*}
$$

where

$$
\begin{aligned}
& f=-\frac{1}{2} \operatorname{div}(a B)+a b-\left(\lambda^{2} \chi\right)^{-1}|\nabla b|_{A}^{2}-c^{2}+\frac{1}{2} \partial_{t} a-\frac{1}{2} \partial_{t}^{2} \varphi-\frac{1}{2} \operatorname{div}\left(\partial_{t} \varphi B\right), \\
& F=-A B^{\prime}+\frac{1}{2}(\operatorname{div}(B) A+\widetilde{A})-\left(b+\lambda^{2} \chi\right) A, \\
& g(w)=\frac{1}{2} a w^{2} B \cdot \nu-\frac{1}{2}|\nabla w|_{A}^{2} B \cdot \nu+B \cdot \nabla w A \nabla w \cdot \nu+b w A \nabla w \cdot \nu-\frac{1}{2} \partial_{t} \varphi B \cdot \nu w^{2}-A \nabla w \cdot \nu \partial_{t} w .
\end{aligned}
$$

We use the inequality $(\alpha-\beta)^{2} \geq \alpha^{2} / 2-\beta^{2}, \alpha>0, \beta>0$, in order to derive

$$
\begin{aligned}
\|P w\|_{2}^{2} & \geq\left(\left\|P_{1} w+P_{2} w\right\|_{2}-\|c w\|_{2}\right)^{2} \\
& \geq \frac{1}{2}\left\|P_{1} w+P_{2} w\right\|_{2}^{2}-\|c w\|_{2}^{2} \\
& \geq \int_{\Omega} P_{1} w P_{2} w d x-\int_{\Omega} c^{2} w^{2} d x .
\end{aligned}
$$

Whence (2.15) implies

$$
\begin{equation*}
\|P w\|_{2}^{2} \geq \int_{Q} f w^{2} d x d t+\int_{Q} F \nabla w \cdot \nabla w d x d t+\int_{\Sigma} g(w) d \sigma d t . \tag{2.16}
\end{equation*}
$$

In light of the following inequalities, where $c$ is a constant depending only on $T_{0}$ and $\psi$,

$$
\begin{aligned}
& \left|\partial_{t} \varphi\right| \leq c \chi^{2}, \quad\left|\partial_{t}^{2} \varphi\right|,\left|\nabla \partial_{t} \varphi\right| \leq c \chi^{3} \\
& \left|A \nabla w \cdot \nu \partial_{t} w\right| \leq \lambda \tau \chi|A \nabla w \cdot \nu|^{2}+(\lambda \tau \chi)^{-1}\left|\partial_{t} w\right|^{2}
\end{aligned}
$$

straightforward computations show that there exist four positive constants $C_{0}, C_{1}, \lambda_{0}$ and $\tau_{0}$, that can depend only on $\psi, \Omega, T_{0}, \kappa$ and $K$, such that for all $\lambda \geq \lambda_{0}$ and $\tau \geq \tau_{0}$,

$$
\begin{aligned}
& f \geq C_{0} \lambda^{4} \tau^{3} \chi^{3} \\
& F \xi \cdot \xi \geq C_{0} \lambda^{2} \tau \chi|\xi|^{2}, \text { for any } \xi \in \mathbb{R}^{n}, \\
& |g(w)| \leq C_{1}\left(\lambda^{3} \tau^{3} \chi^{3} w^{2}+\lambda \tau \chi|\nabla w|^{2}+(\lambda \tau \chi)^{-1}\left|\partial_{t} w\right|^{2}\right) .
\end{aligned}
$$

Hence

$$
\begin{align*}
C \int_{Q}\left(\lambda^{4} \tau^{3} \chi^{3} w^{2}+\lambda^{2} \tau \chi|\nabla w|^{2}\right) d x d t \leq & \int_{Q}(P w)^{2} d x d t  \tag{2.17}\\
& +\int_{\Sigma}\left(\lambda^{3} \tau^{3} \chi^{3} w^{2}+\lambda \tau \chi|\nabla w|^{2}+(\lambda \tau \chi)^{-1}\left|\partial_{t} w\right|^{2}\right) d \sigma d t
\end{align*}
$$

As $\nabla w=\Phi^{-1}(\nabla u+\lambda \tau u \nabla \psi)$,

$$
|\nabla w|^{2}=\Phi^{-2}\left(|\nabla u|^{2}+\lambda^{2} \tau^{2}|\nabla \psi|^{2}+2 \lambda \tau u \nabla u \cdot \nabla \psi\right) .
$$

Therefore, using an elementary inequality, we find

$$
|\nabla w|^{2} \geq \Phi^{-2}\left(|\nabla u|^{2}+\lambda^{2} \tau^{2}|\nabla \psi|^{2} u^{2}-4 \lambda^{2} \tau^{2} u^{2}|\nabla \psi|^{2}-\frac{1}{2}|\nabla u|^{2}\right)
$$

and then

$$
\begin{equation*}
|\nabla w|^{2} \geq \Phi^{-2}\left(\frac{1}{2}|\nabla u|^{2}-3 \lambda^{2} \tau^{2} u^{2}\|\nabla \psi\|_{\infty}^{2}\right) \tag{2.18}
\end{equation*}
$$

(2.18) implies in a straightforward manner that

$$
\|\nabla \psi\|_{\infty}^{-2}|\nabla w|^{2} \geq \Phi^{-2}\left(\frac{\|\nabla \psi\|_{\infty}^{-2}}{12}|\nabla u|^{2}-\frac{1}{2} \lambda^{2} \tau^{2} u^{2}\right) .
$$

Consequently

$$
\begin{equation*}
\|\nabla \psi\|_{\infty}^{-2} \lambda^{2} \tau|\nabla w|^{2}+\lambda^{4} \tau^{3} w^{2} \geq \Phi^{-2}\left(\frac{\|\nabla \psi\|_{\infty}^{-2}}{12}|\nabla u|^{2}+\frac{1}{2} \lambda^{2} \tau^{2} u^{2}\right) \tag{2.19}
\end{equation*}
$$

On the other hand, it is not hard to establish the inequality

$$
\begin{equation*}
\left|\partial_{t} w\right|^{2} \leq \Phi^{-2}\left(\left|\partial_{t} u\right|^{2}+c \tau^{2} \chi^{2} u^{2}\right) \tag{2.20}
\end{equation*}
$$

The expected inequality follows by combining (2.17), (2.19) and (2.20).
Proof of Theorem 2.1. Let $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$, set

$$
Q(\mu)=B(0, \mu) \times(-1,1), \quad \mu>0
$$

Fix $(y, s) \in \Omega \times\left(t_{0}, t_{1}\right)$ and

$$
0<r<r_{(y, s)}=\min \left(\frac{1}{3} \operatorname{dist}(y, \Gamma), \sqrt{s-t_{0}}, \sqrt{t_{1}-s}\right) \leq r_{0}=r_{0}\left(\operatorname{diam}(\Omega), T_{0}\right)
$$

Let

$$
w(x, t)=u\left(r x+y, r^{2} t+s\right),(x, t) \in Q(3)
$$

Then $L_{r} w=\operatorname{div}\left(A_{r} \nabla w\right)-\partial_{t} w=0$ in $Q(3)$, where $A_{r}(x)=\left(a^{i j}(r x+y)\right)$.

Clearly, the family $\left(A_{r}\right)$ satisfies (2.2) and (2.3), uniformly with respect to $r \in\left(0, r_{(y, s)}\right)$.
Let $\chi \in C_{0}^{\infty}(U)$ satisfying $0 \leq \chi \leq 1$ and $\chi=1$ in $\mathcal{K}$, with

$$
U=\left\{x \in \mathbb{R}^{n} ; \frac{1}{2}<|x|<3\right\}, \quad \mathcal{K}=\left\{x \in \mathbb{R}^{n} ; 1 \leq|x| \leq \frac{5}{2}\right\}
$$

Theorem 2.2 applied to $\chi w$, when $\Omega$ is substituted by $U$, gives, for $\lambda \geq \lambda_{0}$ and $\tau \geq \tau_{0}$,

$$
\begin{align*}
C \int_{Q(2) \backslash Q(1)}\left(\lambda^{4} \tau^{3} \varphi^{3} w^{2}+\lambda^{2} \tau \varphi|\nabla w|^{2}\right) & e^{-2 \tau \varphi} d x d t  \tag{2.21}\\
& \leq \int_{Q(3)}\left(L_{r}(\chi w)\right)^{2} e^{-2 \tau \varphi} d x d t
\end{align*}
$$

But

$$
\operatorname{supp}\left(L_{r}(\chi w)\right) \subset\left[\left\{\frac{1}{2} \leq|x| \leq 1\right\} \cup\left\{\frac{5}{2} \leq|x| \leq 3\right\}\right] \times(-1,1)
$$

and

$$
\left(L_{r}(\chi w)\right)^{2} \leq \Lambda\left(w^{2}+|\nabla w|^{2}\right)
$$

where $\Lambda=\Lambda\left(r_{0}\right)$ is independent on $r$. Therefore, fixing $\lambda$ and changing $\tau_{0}$ if necessary, (2.21) implies, for $\tau \geq \tau_{0}$,

$$
\begin{align*}
C \int_{Q(2)}\left(w^{2}+|\nabla w|^{2}\right) e^{-2 \tau \varphi} d x d t \leq \int_{Q(1)}\left(w^{2}\right. & \left.+|\nabla w|^{2}\right) e^{-2 \tau \varphi} d x d t  \tag{2.22}\\
& +\int_{Q(3) \backslash Q(5 / 2)}\left(w^{2}+|\nabla w|^{2}\right) e^{-2 \tau \varphi} d x d t
\end{align*}
$$

Let $s^{\prime} \in(-1,0)$ and choose $\psi(x)=-|x|^{2}$ in (2.22) (without critical points in $U$ ). In that case

$$
\varphi(x, t)=g(t)\left(e^{36 \lambda}-e^{\lambda\left(18-|x|^{2}\right)}\right)
$$

We have, where $s^{\prime}=-1+\varrho$ for some $0<\varrho<1$,

$$
\begin{aligned}
& \varphi(x, t) \leq g\left(s^{\prime}\right)\left(e^{36 \lambda}-e^{14 \lambda}\right) \leq \frac{1}{\varrho}\left(e^{36 \lambda}-e^{14 \lambda}\right)=\frac{\alpha}{\varrho}, \quad(x, t) \in B(2) \times\left(s^{\prime},-s^{\prime}\right) \\
& \varphi(x, t) \geq g\left(t_{m}\right)\left(e^{36 \lambda}-e^{18 \lambda}\right)=\left(e^{36 \lambda}-e^{18 \lambda}\right)=\beta, \quad(x, t) \in Q(1) \\
& \varphi(x, t) \geq g\left(t_{m}\right)\left(e^{36 \lambda}-e^{\frac{47}{4} \lambda}\right)=\left(e^{36 \lambda}-e^{\frac{47}{4} \lambda}\right)=\gamma, \quad(x, t) \in Q(3) \backslash Q\left(\frac{5}{2}\right) .
\end{aligned}
$$

As $\frac{\beta}{\alpha}<1<\frac{\gamma}{\alpha}$, we can fix $\theta \in(0,1)$ so that

$$
\frac{1}{\varrho}=\theta \frac{\beta}{\alpha}+(1-\theta) \frac{\gamma}{\alpha}>1
$$

Set $a=2(1-\theta)(\gamma-\beta)$ and $b=2 \theta(\gamma-\beta)$ and $\widetilde{Q}(2)=B(0,2) \times(-1+\epsilon, 1-\epsilon)$. Then (2.22) yields

$$
C \int_{\widetilde{Q}(2)}\left(w^{2}+|\nabla w|^{2}\right) d x d t \leq e^{a \tau} \int_{Q(1)}\left(w^{2}+|\nabla w|^{2}\right) d x d t+e^{-b \tau} \int_{Q(3)}\left(w^{2}+|\nabla w|^{2}\right) d x d t
$$

As in the elliptic case (see [2, Theorem 2.17 and its proof, pages 19 to 21]), we derive from this inequality the following one

$$
C\|w\|_{L^{2}\left((-1+\varrho, 1-\varrho), H^{1}(B(2))\right)} \leq\|w\|_{L^{2}\left((-1,1), H^{1}(B(1))\right)}^{\vartheta}\|w\|_{L^{2}\left((-1,1), H^{1}(B(3))\right)}^{1-\vartheta}
$$

with $\vartheta=\frac{a}{a+b}$.
Making a change of variable we get, with $\tau=1-\varrho$,

$$
\begin{equation*}
r\|u\|_{L^{2}\left(\left(s-\tau r^{2}, s+\tau r^{2}\right), H^{1}(B(y, 2 r))\right)} \leq C\|u\|_{L^{2}\left(\left(s-r^{2}, s+r^{2}\right), H^{1}(B(y, r))\right)}^{\vartheta}\|u\|_{L^{2}\left(\left(s-r^{2}, s+r^{2}\right), H^{1}(B(y, 3 r))\right)}^{1-\vartheta} . \tag{2.23}
\end{equation*}
$$

We fix $0<\epsilon<\frac{t_{1}-t_{0}}{2}$ and let $s_{0}=t_{0}+\epsilon$ and $s_{k}=s_{k-1}+2 \tau r^{2}$. We consider $q$ the smallest integer so that $\left(t_{1}-\epsilon\right)-s_{q-1} \leq 2 \tau r^{2}$ or equivalently $\left(t_{1}-\epsilon\right)-s_{q-2}>2 \tau r^{2}$. Whence

$$
\begin{equation*}
q<\frac{t_{1}-t_{0}-2 \epsilon}{2 \tau r^{2}}+3<\frac{\delta}{2 \tau r^{2}}+\frac{3 \operatorname{diam}(\Omega)^{2}}{r^{2}}=\left(\frac{T_{0}}{2 \tau}+3 \operatorname{diam}(\Omega)^{2}\right) \frac{1}{r^{2}} . \tag{2.24}
\end{equation*}
$$

In light of $(2.23)$ we get, for $r<r_{y}(\epsilon)=\min \left(\frac{1}{3} \operatorname{dist}(y, \Gamma), \sqrt{\epsilon}\right)$,

$$
\begin{equation*}
r\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}(B(y, 2 r))\right)} \leq C q\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, r))\right)}^{\vartheta}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, 3 r))\right)}^{1-\vartheta} \tag{2.25}
\end{equation*}
$$

Estimate (2.24) in (2.25) yields

$$
\begin{equation*}
C r^{3}\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}(B(y, 2 r))\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, r))\right)}^{\vartheta}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(B(y, 3 r))\right)}^{1-\vartheta}, \quad r<r_{y}(\epsilon) . \tag{2.26}
\end{equation*}
$$

The proof is then complete.

## 3. Quantifying the uniqueness of continuation from an interior data

In the rest of this text, we will often use the following Hardy's inequality for vector valued function.
Lemma 3.1. Let $X$ be a Banach space and $s \in\left(0, \frac{1}{2}\right)$. There exists a constant $c>0$ so that for any $u \in H^{s}\left(\left(t_{0}, t_{1}\right), X\right)$, we have

$$
\left\|\frac{u}{\delta^{s}}\right\|_{L^{2}\left(\left(t_{0}, t_{1}\right), X\right)} \leq c\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), X\right)}
$$

Here $\delta=\delta(t)=\min \left\{\left|t-t_{0}\right|,\left|t-t_{1}\right|\right\}$.
Proof. For simplicity, we use the same symbol $\|\cdot\|$ for the norm of $X$ and its dual space dual $X^{*}$. The duality pairing between $X$ and $X^{*}$ is denoted by $\langle\cdot, \cdot\rangle$. Let $u \in H^{s}\left(\left(t_{0}, t_{1}\right), X\right)$ and pick $x^{*} \in X^{*}$ with $\left\|x^{*}\right\|=1$. From the usual Hardy's inequality in one dimension (see for instance [5]), we have

$$
\begin{equation*}
\int_{t_{0}}^{t_{1}} \frac{\left|\left\langle x^{*}, u(t)\right\rangle\right|^{2}}{\delta^{2 s}(t)} d t \leq c\left\|\left\langle x^{*}, u(\cdot)\right\rangle\right\|_{H^{s}\left(\left(t_{0}, t_{1}\right)\right)}^{2} \tag{3.1}
\end{equation*}
$$

But

$$
\begin{aligned}
\left\|\left\langle x^{*}, u(\cdot)\right\rangle\right\|_{H^{s}\left(\left(t_{0}, t_{1}\right)\right)}^{2} & =\left\|\left\langle x^{*}, u(\cdot)\right\rangle\right\|_{L^{2}\left(\left(t_{0}, t_{1}\right)\right)}^{2}+\int_{t_{0}}^{t_{1}} \int_{t_{0}}^{t_{1}} \frac{\left|\left\langle x^{*}, u(\tau)\right\rangle-\left\langle x^{*}, u(t)\right\rangle\right|^{2}}{|\tau-t|^{n+2 s}} d t d \tau \\
& \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), X\right)}^{2}+\int_{t_{0}}^{t_{1}} \int_{t_{0}}^{t_{1}} \frac{\|u(\tau)-u(t)\|^{2}}{|\tau-t|^{n+2 s}} d t d \tau=\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), X\right)}^{2}
\end{aligned}
$$

Whence

$$
\left\|\frac{u}{\delta^{s}}\right\|_{L^{2}\left(\left(t_{0}, t_{1}\right), X\right)}^{2}=\int_{t_{0}}^{t_{1}} \frac{\sup _{\left\|x^{*}\right\|=1}\left|\left\langle x^{*}, u(t)\right\rangle\right|^{2}}{\delta^{2 s}(t)} d t \leq c\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), X\right)}^{2}
$$

Next, we prove
Proposition 3.1. There exist $\omega \Subset \Omega$ and four constants $\mu>0, c>0, C>0$ and $0<\sigma_{0}<1$, that can depend on $\Omega, \kappa, K, T_{0}$ and $\alpha$, so that, for any $u \in \mathscr{X}^{1}$ satisfying $L u=0$ in $Q$ and $0<\sigma<\sigma_{0}$, we have

$$
\begin{equation*}
\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)} \leq C\left(\sigma^{\mu}\|u\|_{\mathscr{X}^{1}}+e^{\frac{c}{\sigma}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}\right) \tag{3.2}
\end{equation*}
$$

Proof. Since $\Omega$ is Lipschitz, it has the uniform interior cone property (see for instance [7]). That is there exist $R>0$ and $\theta \in] 0, \frac{\pi}{2}\left[\right.$ so that, to any $\widetilde{x} \in \Gamma$ corresponds $\xi=\xi(\widetilde{x}) \in \mathbb{S}^{n-1}$ for which

$$
\mathcal{C}(\widetilde{x})=\left\{x \in \mathbb{R}^{n} ;|x-\widetilde{x}|<R,(x-\widetilde{x}) \cdot \xi>|x-\widetilde{x}| \cos \theta\right\} \subset \Omega
$$

We fix $\widetilde{x} \in \Gamma$ and let $\xi=\xi(\widetilde{x})$ be as in the definition above. Let $x_{0}=x_{0}(\widetilde{x})=\widetilde{x}+\frac{R}{2} \xi, d_{0}=\left|x_{0}-\widetilde{x}\right|$ and $\rho_{0}=\left(d_{0} / 3\right) \sin \theta$.

Let $0<\epsilon<\epsilon_{0}$, where $\epsilon_{0}<\frac{t_{1}-t_{0}}{4}$ is chosen in such a way that

$$
\begin{equation*}
0<\delta=\delta(\epsilon)=\frac{\sqrt{\epsilon}}{4 \rho_{0}}<1, \quad 0<\epsilon<\epsilon_{0} \tag{3.3}
\end{equation*}
$$

By induction on $k$, we construct a sequence of balls ( $\left.B\left(x_{k}, 3 \delta \rho_{k}\right)\right)$ as follows

$$
\left\{\begin{array}{l}
x_{k+1}=x_{k}-\alpha_{k} \xi \\
\rho_{k+1}=\mu \rho_{k} \\
d_{k+1}=\mu d_{k}
\end{array}\right.
$$

where

$$
d_{k}=\left|x_{k}-\widetilde{x}\right|, \quad \rho_{k}=c d_{k}, \quad \alpha_{k}=(1-\mu) d_{k}
$$

with

$$
c=\frac{\sin \theta}{3}, \quad \mu=\frac{3-2 \sin \theta}{3-\sin \theta}
$$

This construction guaranties that, for each $k, B\left(x_{k}, 3 \delta \rho_{k}\right) \subset \mathcal{C}(\widetilde{x})$ and

$$
\begin{equation*}
B\left(x_{k+1}, \delta \rho_{k+1}\right) \subset B\left(x_{k}, 2 \delta \rho_{k}\right) \tag{3.4}
\end{equation*}
$$

Let $u \in \mathscr{X}^{1}$. In the sequel

$$
M=M(u)=\|u\|_{\mathscr{X}^{1}}
$$

From (2.1) we have

$$
\begin{equation*}
\left.\left.\left.\left(\delta \rho_{0}\right)^{3}\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}\left(B \left(x_{0}, 2 \delta\right.\right.\right.} \rho_{0}\right)\right)\right) \leq C M^{1-\vartheta}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}\left(B\left(x_{0}, \delta \rho_{0}\right)\right)\right)^{\vartheta} .} \tag{3.5}
\end{equation*}
$$

Since $B\left(x_{0}, 2 \delta \rho_{0}\right) \supset B\left(x_{1}, \delta \rho_{1}\right)$, (3.5) implies

$$
\begin{equation*}
\left(\delta \rho_{0}\right)^{3}\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}\left(B\left(x_{1}, \delta \rho_{1}\right)\right)\right)} \leq C M^{1-\vartheta}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}\left(B\left(x_{0}, \delta \rho_{0}\right)\right)\right)^{\vartheta} .} . \tag{3.6}
\end{equation*}
$$

Set

$$
I_{0}=\left(t_{0}, t_{1}\right), \quad I_{k}=\left(t_{0}+\epsilon \eta_{k}, t_{1}-\epsilon \eta_{k}\right) \text { with } \eta_{k}=\sum_{j=0}^{k-1} \frac{1}{2^{j}}, \quad k \geq 1
$$

With these notations (3.6) takes the form

$$
\begin{equation*}
\left(\delta \rho_{0}\right)^{3}\|u\|_{L^{2}\left(I_{1}, H^{1}\left(B\left(x_{1}, \delta \rho_{1}\right)\right)\right)} \leq C M^{1-\vartheta}\|u\|_{L^{2}\left(I_{0}, H^{1}\left(B\left(x_{0}, \delta \rho_{0}\right)\right)\right)}^{\vartheta} \tag{3.7}
\end{equation*}
$$

By induction in $k$, we see that

$$
\begin{equation*}
\left(\delta \rho_{k}\right)^{3}\|u\|_{L^{2}\left(I_{k+1}, H^{1}\left(B\left(x_{k+1}, \delta \rho_{k+1}\right)\right)\right)} \leq C M^{1-\vartheta}\|u\|_{L^{2}\left(I_{k}, H^{1}\left(B\left(x_{k}, \delta \rho_{k}\right)\right)\right)}^{\vartheta} \tag{3.8}
\end{equation*}
$$

Let $\Lambda_{k}=\|u\|_{L^{2}\left(I_{k}, H^{1}\left(B\left(x_{k}, \delta \rho_{k}\right)\right)\right)}$. Then (3.8) is rewritten as follows

$$
\left(\delta \rho_{k}\right)^{3} \Lambda_{k+1} \leq C M^{1-\vartheta} \Lambda_{k}^{\vartheta}
$$

Again, by induction in $k$, we obtain

$$
\Lambda_{k} \leq \frac{C^{1+\vartheta+\ldots+\vartheta^{k-1}}}{\left(\delta \rho_{k-1}\right)^{3}\left(\delta \rho_{k-2}\right)^{3 \vartheta} \ldots\left(\delta \rho_{0}\right)^{3 \vartheta^{(k-1)}}} M^{(1-\vartheta)\left(1+\vartheta+\ldots+\vartheta^{k-1}\right)} \Lambda_{0}^{\vartheta^{k}}
$$

From the following inequality, where we used $0<\mu<1$,

$$
\begin{aligned}
\left(\delta \rho_{k-1}\right)^{3}\left(\delta \rho_{k-2}\right)^{3 \vartheta} \ldots\left(\delta \rho_{0}\right)^{\vartheta^{3(k-1)}} & =\left(\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}\right)\left(\mu^{3(k-2)}\left(\delta \rho_{0}\right)^{3}\right)^{\vartheta} \ldots\left(\mu^{3} \rho_{0}^{3} \vartheta^{\vartheta^{k-2}} \rho_{0}^{\vartheta^{k-1}}\right. \\
& \geq\left(\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}\right)^{1+\vartheta+\ldots \vartheta^{k-1}}=\left(\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}\right)^{\frac{1-\vartheta^{k}}{1-\vartheta}}
\end{aligned}
$$

it follows

$$
\begin{equation*}
\Lambda_{k} \leq\left[\left(\frac{C}{\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}}\right)^{\frac{1}{1-\vartheta}} M\right]^{1-\vartheta^{k}} \Lambda_{0}^{\vartheta^{k}} \tag{3.9}
\end{equation*}
$$

Applying Young's inequality we obtain, for any $\varrho>0$,

$$
\begin{align*}
\Lambda_{k} & \leq\left(1-\vartheta^{k}\right) \varrho^{\frac{1}{1-\vartheta^{k}}}\left(\frac{C}{\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}}\right)^{\frac{1}{1-\vartheta}} M+\vartheta^{k} \varrho^{-\frac{1}{\vartheta^{k}}} \Lambda_{0} \\
& \leq \varrho^{\frac{1}{1-\vartheta^{k}}}\left(\frac{C}{\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}}\right)^{\frac{1}{1-\vartheta}} M+\varrho^{-\frac{1}{\vartheta^{k}}} \Lambda_{0} \tag{3.10}
\end{align*}
$$

Set $\widetilde{\Lambda}_{k}=\|u\|_{L^{2}\left(\left(t_{0}+2 \epsilon, t_{1}-2 \epsilon\right), H^{1}\left(B\left(x_{k}, \delta \rho_{k}\right)\right)\right)}$. As $I_{k} \supset J=\left(t_{0}-2 \epsilon, t_{1}-2 \epsilon\right)$ for any $k \geq 1$, (3.10) implies

$$
\begin{equation*}
\tilde{\Lambda}_{k} \leq \varrho^{\frac{1}{1-\vartheta^{k}}}\left(\frac{C}{\mu^{3(k-1)}\left(\delta \rho_{0}\right)^{3}}\right)^{\frac{1}{1-\vartheta}} M+\varrho^{-\frac{1}{\vartheta^{k}}} \Lambda_{0} \tag{3.11}
\end{equation*}
$$

Changing $C$ if necessary, we can always assume that $C \rho_{0}^{-3} \geq 1$. In that case (3.11) gives

$$
\begin{equation*}
\widetilde{\Lambda}_{k} \leq C \delta^{-\frac{3}{1-\vartheta}}\left(\varrho^{\frac{1}{1-\vartheta k}} \mu^{\frac{-3(k-1)}{1-\vartheta}} M+\varrho^{-\frac{1}{\vartheta^{k}}} \Lambda_{0}\right) \tag{3.12}
\end{equation*}
$$

On the other hand, since $u$ is Hölder continuous,

$$
|u(\widetilde{x}, t)| \leq[u]_{\alpha}|\widetilde{x}-x|^{\alpha}+|u(x, t)|, \quad x \in B\left(x_{k}, \delta \rho_{k}\right), t \in J
$$

Here and henceforth,

$$
[w]_{\alpha}=\sup _{\substack{\left(x_{1}, t_{1}\right),\left(x_{2}, t_{2}\right) \in \bar{Q} \\\left(x_{1}, t_{1}\right) \neq\left(x_{2}, t_{2}\right)}} \frac{\left|w\left(x_{1}, t_{1}\right)-w\left(x_{2}, t_{2}\right)\right|}{\left|x_{1}-x_{2}\right|^{\alpha}+\left|t_{1}-t_{2}\right|^{\frac{\alpha}{2}}}, \quad w \in C^{\alpha, \frac{\alpha}{2}}(\bar{Q})
$$

Whence

$$
\begin{equation*}
\left|\mathbb{S}^{n-1}\right| \delta^{n} \rho_{k}^{n} \int_{J}|u(\widetilde{x}, t)|^{2} d t \leq 2[u]_{\alpha}^{2} \int_{B\left(x_{k}, \delta \rho_{k}\right) \times J}|\widetilde{x}-x|^{2 \alpha} d x d t+2 \int_{B\left(x_{k}, \delta \rho_{k}\right) \times J}|u(x, t)|^{2} d x d t \tag{3.13}
\end{equation*}
$$

Similarly, where $1 \leq i \leq n$,

$$
\begin{equation*}
\left|\mathbb{S}^{n-1}\right| \delta^{n} \rho_{k}^{n} \int_{J}\left|\partial_{i} u(\widetilde{x}, t)\right|^{2} d t \leq 2\left[\partial_{i} u\right]_{\alpha}^{2} \int_{B\left(x_{k}, \delta \rho_{k}\right) \times J}|\widetilde{x}-x|^{2 \alpha} d x d t+2 \int_{B\left(x_{k}, \delta \rho_{k}\right) \times J}\left|\partial_{i} u(x, t)\right|^{2} d x d t \tag{3.14}
\end{equation*}
$$

A simple computation shows that $d_{k}=\mu^{k} d_{0}$ yielding

$$
\begin{equation*}
|\widetilde{x}-x| \leq\left|\widetilde{x}-x_{k}\right|+\left|x_{k}-x\right| \leq d_{k}+\delta \rho_{k}=(1+c) d_{k}=(1+c) \mu^{k} d_{0} \tag{3.15}
\end{equation*}
$$

Therefore, as a consequence of a combination of (3.13), (3.14) and (3.15),

$$
\int_{J}\left|\partial_{i} u(\widetilde{x}, t)\right|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-n}\left(M^{2} \mu^{2 \alpha k}+\mu^{-n k} \widetilde{\Lambda}_{k}^{2}\right)
$$

This and (3.12) imply, where $\varkappa=\max \left(n, \frac{3}{1-\vartheta}\right)$,

$$
\begin{equation*}
\int_{J}|u(\widetilde{x}, t)|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-\varkappa}\left(M^{2} \mu^{2 \alpha k}+\mu^{-n k}\left[\varrho^{\frac{2}{1-\vartheta^{k}}} \mu^{\frac{-6(k-1)}{1-\vartheta}} M^{2}+\varrho^{-\frac{2}{\vartheta^{k}}} \Lambda_{0}^{2}\right]\right) . \tag{3.16}
\end{equation*}
$$

We choose $\varrho>0$ so that

$$
\varrho^{\frac{2}{1-\vartheta k}} \mu^{\frac{-6(k-1)}{1-\vartheta}-n k}=\mu^{2 \alpha k} .
$$

That is to say $\varrho=\mu^{\phi(k)}$, with

$$
\phi(k)=\frac{[(2 \alpha+n)(1-\vartheta) k+6(k-1)]\left(1-\vartheta^{k}\right)}{2(1-\vartheta)} .
$$

Consequently, we have from (3.17)

$$
\begin{equation*}
\int_{J}|u(\widetilde{x}, t)|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-\varkappa}\left(M^{2} \mu^{2 \alpha k}+\mu^{-\psi(k)} \Lambda_{0}^{2}\right) \tag{3.17}
\end{equation*}
$$

where $\psi(k)=n k+\phi(k) / \vartheta^{k}$.

Let $t>0$ and $k$ be the integer so that $k \leq t<k+1$. Using that

$$
\psi(k) \leq\left[n+\frac{(2 \alpha+n)+6}{2(1-\vartheta)}\right] \frac{k}{\vartheta^{k}} \leq\left[n+\frac{(2 \alpha+n)+6}{2(1-\vartheta)}\right] e^{k(1+|\ln \vartheta|)} \leq\left[n+\frac{(2 \alpha+n)+6}{2(1-\vartheta)}\right] e^{t(1+|\ln \vartheta|)},
$$

we find

$$
\begin{equation*}
\int_{J}|u(\widetilde{x}, t)|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-\varkappa}\left(M^{2} \mu^{2 \alpha t}+\mu^{-\kappa e^{c t}} \Lambda_{0}^{2}\right) \tag{3.18}
\end{equation*}
$$

where $\kappa=n+\frac{(2 \alpha+n)+6}{2(1-\vartheta)}$ and $c=1+|\ln \vartheta|$.
Thus, for $\frac{1}{\sigma}=e^{c t}(>1)$,

$$
\begin{equation*}
\int_{J}|u(\widetilde{x}, t)|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-\varkappa}\left(M^{2} \sigma^{2 \gamma}+e^{\frac{\xi}{\sigma}} \Lambda_{0}^{2}\right) \tag{3.19}
\end{equation*}
$$

with $\gamma=\frac{\alpha|\ln \mu|}{c}$ and $\xi=|\ln \mu|^{\kappa}$.
Let $\left.\omega=\cup_{\widetilde{x} \in \Gamma} B\left(x_{0}(\widetilde{x}), \rho_{0}\right)\right)$ (independent on $u$ ) and $N=\|u\|_{L^{2}\left((0, T) ; H^{1}(\omega)\right)}$. Then (3.19) entails

$$
\begin{equation*}
\int_{J}|u(\widetilde{x}, t)|^{2} d t+\int_{J}|\nabla u(\widetilde{x}, t)|^{2} d t \leq C \delta^{-\varkappa}\left(M^{2} \sigma^{2 \gamma}+e^{\frac{\xi}{\sigma}} N^{2}\right) \tag{3.20}
\end{equation*}
$$

Integrating over $\Gamma$, we obtain in a straightforward manner

$$
\begin{equation*}
\|u\|_{L^{2}\left(J, L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(J, L^{2}(\Gamma)^{n}\right)} \leq C \delta^{-\frac{\varkappa}{2}}\left(M \sigma^{\gamma}+e^{\frac{c}{\sigma}} N\right) \tag{3.21}
\end{equation*}
$$

In light of (3.3), this inequality yields

$$
\begin{equation*}
\|u\|_{L^{2}\left(J, L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(J, L^{2}(\Gamma)^{n}\right)} \leq C \epsilon^{-\frac{\varkappa}{2}}\left(M \sigma^{\gamma}+e^{\frac{c}{\sigma}} N\right) . \tag{3.22}
\end{equation*}
$$

Applying Lemma 3.1 for some fixed $s \in\left(0, \frac{1}{2}\right)$, we obtain

$$
\begin{aligned}
& \|u\|_{L^{2}\left(\left(t_{0}, t_{0}+2 \epsilon\right), L^{2}(\Gamma)\right)},\|u\|_{L^{2}\left(\left(t_{1}-2 \epsilon, t_{1}\right), L^{2}(\Gamma)\right)} \leq 2^{1+s} c \epsilon^{s}\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}, \\
& \|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{0}+2 \epsilon\right), L^{2}(\Gamma)^{n}\right)},\|\nabla u\|_{L^{2}\left(\left(t_{1}-2 \epsilon, t_{1}\right), L^{2}(\Gamma)^{n}\right)} \leq 2^{1+s} c \epsilon^{s}\|\nabla u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)} .
\end{aligned}
$$

These estimates in (3.22) yields

$$
\begin{aligned}
C\left(\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{\left.L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)\right) \leq}\right. & \epsilon^{-\frac{\varkappa}{2}}\left(M \sigma^{\gamma}+e^{\frac{c}{\sigma}} N\right) \\
& +\epsilon^{s}\left(\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{\left.H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)\right)} .\right.
\end{aligned}
$$

We take $\epsilon=\sigma^{\frac{\gamma}{\varkappa}}$ in order to get

$$
\begin{aligned}
C\left(\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)}\right) \leq M \sigma^{\frac{\gamma}{2}} & +e^{\frac{c}{\sigma}} N \\
& +\sigma^{\frac{s \gamma}{\varkappa}}\left(\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{\left.H^{s}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)\right)}\right)
\end{aligned}
$$

provided that $0<\sigma<\sigma_{0}=\epsilon_{0}^{\frac{\varkappa}{\gamma}}(<1)$. Letting $\mu=\min \left(\frac{\gamma}{2}, \frac{s \gamma}{\varkappa}\right)$, we get

$$
C\left(\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)^{n}\right)}\right) \leq \sigma^{\mu} M+e^{\frac{c}{\sigma}} N
$$

which is the expected inequality.
The a priori estimate in the following lemma is well adapted to our purpose. It does not involve either the initial time data, nor the final time data.

Lemma 3.2. There exists a constant $C>0$, depending only on $\Omega, \kappa, K$ and $T_{0}$, so that, for any $u \in$ $H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$, we have

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)} . \tag{3.23}
\end{equation*}
$$

Proof. Let $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$ and set $v=e^{-t} u$. Then $v$ solves the following equation

$$
\begin{equation*}
\operatorname{div}(A \nabla v)-v-\partial_{t} v=0 \text { in } Q \tag{3.24}
\end{equation*}
$$

Choose $\chi \in C_{0}^{\infty}\left(t_{0}, t_{1}\right)$ satisfying $0 \leq \chi \leq 1, \chi=1$ in $\left(t_{0}+\epsilon, t_{1}-\epsilon\right)$ and, for some universal constant $c$, $\left|\chi^{\prime}\right| \leq c \epsilon$.

We multiply (3.24) by $\chi v$ and integrate over $Q$. We make then an integrate by parts in order to get

$$
-\int_{Q} \chi A \nabla v \cdot \nabla v d x d t-\int_{Q} \chi v^{2} d x d t+\int_{\Sigma} \chi u A \nabla u \cdot \nu d \sigma d t+\frac{1}{2} \int_{Q} v^{2} \chi^{\prime} d x d t
$$

from which we deduce in a straightforward manner

$$
\begin{equation*}
\int_{Q} \chi A \nabla u \cdot \nabla u d x d t+\int_{Q} \chi u^{2} d x d t \leq e^{2\left(t_{1}-t_{0}\right)}\left(C \int_{\Sigma}\left(u^{2}+|\nabla u|^{2}\right) d \sigma d x+\frac{1}{2} \int_{Q} u^{2}\left|\chi^{\prime}\right| d x d t\right) \tag{3.25}
\end{equation*}
$$

On the other hand, as $\operatorname{supp}\left(\chi^{\prime}\right) \subset\left(t_{0}, t_{1}\right) \backslash\left(t_{0}+\epsilon, t_{1}-\epsilon\right)$, we have

$$
\mathscr{J}_{\epsilon}^{2}=\int_{Q} u^{2}\left|\chi^{\prime}\right| d x d t \leq \frac{c}{\epsilon} \int_{t_{0}}^{t_{0}-\epsilon} \int_{\Omega} u^{2} d x d t+\int_{t_{1}-\epsilon}^{t_{1}} \int_{\Omega} u^{2} d x d t .
$$

Therefore

$$
\begin{equation*}
\limsup _{\epsilon \rightarrow 0} \mathscr{J}_{\epsilon}^{2} \leq \int_{\Omega} u^{2}\left(x, t_{0}\right) d x+\int_{\Omega} u^{2}\left(x, t_{1}\right) d x . \tag{3.26}
\end{equation*}
$$

We rewrite (3.25) in the form

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}+\epsilon, t_{1}-\epsilon\right), H^{1}(\Omega)\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\mathscr{J}_{\epsilon} . \tag{3.27}
\end{equation*}
$$

We apply Hardy's inequality in lemma 3.1. We obtain

$$
\|u\|_{L^{2}\left(\left(t_{0}, t_{0}+\epsilon\right), H^{1}(\Omega)\right)},\|u\|_{L^{2}\left(\left(t_{1}-\epsilon, t_{1}\right), H^{1}(\Omega)\right)} \leq c \epsilon^{s}\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} .
$$

This and (3.27) produce

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\epsilon^{s}\|u\|_{H^{s}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}+\mathscr{J}_{\epsilon} .
$$

Making $\epsilon \rightarrow 0$, we get by using (3.26)

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\left\|u\left(\cdot, t_{0}\right)\right\|_{L^{2}(\Omega)}+\left\|u\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)} .
$$

We complete the proof by using the following inequality

$$
C\left(\left\|u\left(\cdot, t_{0}\right)\right\|_{L^{2}(\Omega)}+\left\|u\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)}\right) \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)} .
$$

To prove this inequality, we proceed as in the proof of observability inequalities for parabolic equation. First, if $s_{0}=\frac{3 t_{0}+t_{1}}{4}$ and $s_{1}=\frac{t_{0}+3 t_{1}}{4}$, we get as a straightforward consequence of the Carleman inequality in Theorem 2.2

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(s_{0}, s_{1}\right) \times \Omega\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)} . \tag{3.28}
\end{equation*}
$$

Next, pick $\psi \in C^{\infty}\left(\left[t_{0}, t_{1}\right]\right)$ so that $0 \leq \psi \leq 1, \psi=0$ in $\left[t_{0}, s_{0}\right]$ and $\psi=1$ in $\left[s_{1}, t_{1}\right]$. Then $v=\psi u$ is the solution of the IBVP

$$
\begin{cases}\operatorname{div}(A \nabla v)-\partial_{t} v=-\psi^{\prime} u & \text { in } Q, \\ v=u & \text { in } \Sigma, \\ v\left(\cdot, t_{0}\right)=0 . & \end{cases}
$$

Hence

$$
\int_{Q} A \nabla v \cdot \nabla v d x d t+\int_{\Sigma} v A \nabla v \cdot \nu-\frac{1}{2} \int_{Q} \partial_{t} v^{2} d x d t=-\int_{Q} \psi^{\prime} u v d x d t
$$

But

$$
\int_{Q} \partial_{t} v^{2} d x d t=\int_{\Omega} v^{2}\left(x, t_{1}\right) d x
$$

That is we have

$$
\int_{Q} A \nabla v \cdot \nabla v d x d t+\int_{\Sigma} v A \nabla v \cdot \nu+\frac{1}{2} \int_{\Omega} v^{2}\left(x, t_{1}\right) d x .=-\int_{Q} \psi^{\prime} u v d x d t
$$

We derive from this identity

$$
\begin{equation*}
C\left(\left\|v\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)}^{2}+\|\nabla v\|_{L^{2}(Q)}^{2}\right) \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}^{2}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}^{2}+\left\|\psi^{\prime} u\right\|_{L^{2}(Q)}\|v\|_{L^{2}(Q)} \tag{3.29}
\end{equation*}
$$

Noting that

$$
w \rightarrow\left(\int_{\Omega}|\nabla w|^{2} d x+\int_{\Gamma} w^{2}(x) d \sigma(x)\right)^{\frac{1}{2}}
$$

defines an equivalent norm on $H^{1}(\Omega)$, we get

$$
\|v\|_{L^{2}(Q)}^{2} \leq c_{\Omega}\left(\|\nabla v\|_{L^{2}(Q)}^{2}+\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}^{2}\right) .
$$

Applying Young's inequality, we obtain

$$
\left\|\psi^{\prime} u\right\|_{L^{2}(Q)}\|v\|_{L^{2}(Q)} \leq \frac{1}{2 \epsilon}\left\|\psi^{\prime} u\right\|_{L^{2}(Q)}+\frac{c_{\Omega} \epsilon}{2}\|\nabla v\|_{L^{2}(Q)}^{2}+\frac{c_{\Omega} \epsilon}{2}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}^{2}
$$

This inequality in (3.29), with $\epsilon$ sufficiently small, yields

$$
\begin{equation*}
C\left\|u\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)}=C\left\|v\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\left\|\psi^{\prime} u\right\|_{L^{2}(Q)} . \tag{3.30}
\end{equation*}
$$

Bearing in mind that $\operatorname{supp}\left(\psi^{\prime}\right) \subset\left[s_{0}, s_{1}\right]$, we derive from (3.28)

$$
\begin{aligned}
\left\|\psi^{\prime} u\right\|_{L^{2}(Q)} & \leq C\|u\|_{L^{2}\left(\Omega \times\left(s_{0}, s_{1}\right)\right)} \\
& \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)} .
\end{aligned}
$$

This in (3.30) yields

$$
C\left\|u\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)}=C\left\|v\left(\cdot, t_{1}\right)\right\|_{L^{2}(\Omega)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}
$$

As the Carleman estimate in Theorem 2.2 still holds for the backward parabolic equation $\operatorname{div}(A \nabla u)+\partial_{t} u=0$, we have similarly

$$
C\left\|u\left(\cdot, t_{0}\right)\right\|_{L^{2}(\Omega)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}(\Gamma)\right)} .
$$

The proof is then complete.
In light of Proposition 3.1 and Lemma 3.2, we get
Corollary 3.1. There exist $\omega \Subset \Omega$ and four constants $\mu>0, c>0, C>0$ and $0<\sigma_{0}<1$, that can depend on $\Omega, \kappa, K, T_{0}$ and $\alpha$, so that, for any $u \in \mathscr{X}^{1}$ satisfying $L u=0$ in $Q$ and $0<\sigma<\sigma_{0}$, we have

$$
\begin{equation*}
\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq C\left(\sigma^{\mu}\|u\|_{\mathscr{X}^{1}}+e^{\frac{c}{\sigma}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}\right) . \tag{3.31}
\end{equation*}
$$

We now establish a result quantifying the uniqueness of continuation from a subdomain to an another subdomain. Precisely, we prove
Proposition 3.2. Let $\omega \Subset \Omega$ and $\widetilde{\omega} \Subset \Omega$ and $s \in\left(0, \frac{1}{2}\right)$. There exist three constants $\gamma>0, C>0$ and $0<\epsilon_{0}<1$, depending only on $\Omega, \kappa, K, T_{0}$, s $\omega$ and $\widetilde{\omega}$, so that, for any $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$ and $0<\epsilon<\epsilon_{0}$, we have

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\widetilde{\omega})\right)} \leq \epsilon^{2 s}\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}+e^{\frac{\kappa}{\epsilon}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} . \tag{3.32}
\end{equation*}
$$

Proof. Set $d_{0}=\operatorname{dist}(\bar{\omega} \cup \overline{\widetilde{\omega}}, \Gamma)$. Fix $0<\epsilon<\epsilon_{0}:=\min \left(\frac{d_{0}^{2}}{9}, 1\right)$ and let $0<\delta<\sqrt{\epsilon}$. Let $x_{0} \in \omega, x \in \overline{\widetilde{\omega}}$ and $\psi:[0,1] \rightarrow \Omega$ be a $C^{1}$-piecewise smooth path joining $x_{0}$ to $x$ so that $\ell(\psi) \leq d_{g}\left(x_{0}, x\right)+1$. Let $\tau_{0}=0$ and $\tau_{k+1}=\inf \left\{\tau \in\left[\tau_{k}, 1\right] ; \psi(\tau) \notin B\left(\psi\left(\tau_{k}\right), \delta\right)\right\}, k \geq 0$. We claim that there exists an integer $N \geq 1$ so that $\psi(1) \in B\left(\psi\left(\tau_{N}\right), \frac{\delta}{2}\right)$. If not, we would have $\psi(1) \notin B\left(\psi\left(\tau_{k}\right), \frac{\delta}{2}\right)$ for any $k \geq 0$. As the sequence $\left(\tau_{k}\right)$ is non decreasing and bounded from above by 1 , it converges to $\widehat{\tau} \leq 1$. In particular, there exists an integer $k_{0} \geq 1$ so that $\psi\left(t_{k}\right) \in B\left(\psi(\widehat{t}), \frac{\delta}{2}\right), k \geq k_{0}$. But this contradicts the fact that $\left|\psi\left(\tau_{k+1}\right)-\psi\left(\tau_{k}\right)\right|=\delta, k \geq 0$.

Let us check that $N \leq N_{0}$ where $N_{0}$ depends only on $\mathbf{d}_{g}$ and $\delta$. Pick $1 \leq j \leq n$ so that

$$
\max _{1 \leq i \leq n}\left|\psi_{i}\left(\tau_{k+1}\right)-\psi_{i}\left(\tau_{k}\right)\right|=\left|\psi_{j}\left(\tau_{k+1}\right)-\psi_{j}\left(\tau_{k}\right)\right|
$$

Then

$$
\delta \leq n\left|\psi_{j}\left(\tau_{k+1}\right)-\psi_{j}\left(\tau_{k}\right)\right|=n\left|\int_{\tau_{k}}^{\tau_{k+1}} \dot{\psi}_{j}(t) d t\right| \leq n \int_{\tau_{k}}^{\tau_{k+1}}|\dot{\psi}(t)| d t
$$

Consequently, where $\tau_{N+1}=1$,

$$
(N+1) \delta \leq n \sum_{k=0}^{N} \int_{\tau_{k}}^{\tau_{k+1}}|\dot{\psi}(\tau)| d \tau=n \ell(\psi) \leq n\left(\mathbf{d}_{g}+1\right)
$$

Therefore

$$
N \leq N_{0}=\left[\frac{n\left(\mathbf{d}_{g}+1\right)}{\delta}\right]
$$

Let $x_{k}=\psi\left(t_{k}\right), 0 \leq k \leq N$. If $\left|z-x_{k+1}\right|<\delta$, then $\left|z-x_{k}\right| \leq\left|z-x_{k+1}\right|+\left|x_{k+1}-x_{k}\right|<2 \delta$. In other words $B\left(x_{k+1}, \delta\right) \subset B\left(x_{k}, 2 \delta\right)$.

As above,

$$
I_{0}=\left(t_{0}, t_{1}\right), \quad I_{k}=\left(t_{0}+\epsilon \eta_{k}, t_{1}-\epsilon \eta_{k}\right) \text { with } \eta_{k}=\sum_{j=0}^{k-1} \frac{1}{2^{j}}, \quad k \geq 1
$$

Let $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$. In the rest of this proof

$$
M=M(u)=\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}
$$

From the three-cylinder inequality (2.1), we have

$$
\|u\|_{L^{2}\left(I_{k+1}, H^{1}\left(B\left(x_{k+1}, \delta\right)\right)\right)} \leq C_{0} \delta^{-3} M^{1-\vartheta}\|u\|_{L^{2}\left(I_{k}, H^{1}\left(B\left(x_{k}, \delta\right)\right)\right)}^{\vartheta}
$$

Setting $\Lambda_{k}=\|u\|_{L^{2}\left(I_{k}, H^{1}\left(B\left(x_{k}, \delta\right)\right)\right)}, 0 \leq k \leq N$ and $\Lambda_{N+1}=\|u\|_{L^{2}\left(I_{N+1}, H^{1}\left(B\left(x, \frac{\delta}{2}\right)\right)\right)}$, we can rewrite this inequality in the form

$$
\begin{equation*}
\Lambda_{k+1} \leq C_{0} M^{1-\vartheta} \Lambda_{k}^{\vartheta} \tag{3.33}
\end{equation*}
$$

Let $\beta=\vartheta^{N+1}$. We get in a straightforward manner from (3.33)

$$
\Lambda_{N+1} \leq\left(C_{0} \delta^{-3}\right)^{\frac{1-\vartheta}{} \frac{1-\vartheta+2}{1-\vartheta}} M^{1-\beta} \Lambda_{0}^{\beta}
$$

Since we can always assume, by changing $C_{0}$, that $C_{0} \delta^{-3} \geq 1$, the last inequality gives

$$
\Lambda_{N+1} \leq C \delta^{\frac{-3}{1-v}} M^{1-\beta} \Lambda_{0}^{\beta}
$$

This and Young's inequality lead, for $\sigma>0$,

$$
\Lambda_{N+1} \leq C \delta^{\frac{-3}{1-\vartheta}}\left((1-\beta) \sigma^{\frac{\beta}{1-\beta}} M+\beta \sigma^{-1} \Lambda_{0}\right) \leq C_{1}\left(\sigma^{\frac{\beta}{1-\beta}} M+\sigma^{-1} \Lambda_{0}\right)
$$

That is

$$
\Lambda_{N+1} \leq C \delta^{\frac{-3}{1-\vartheta}}\left(\sigma^{\frac{\beta}{1-\beta}} M+\sigma^{-1} \Lambda_{0}\right)
$$

If $\delta$ is sufficiently small $B\left(x_{0}, \delta\right) \subset \omega$. On the other hand $\overline{\widetilde{\omega}}$ can be recovred by $O\left(\delta^{-n}\right)$ balls of radius $\frac{\delta}{2}$. Whence, bearing in mind that $I_{N+1} \supset\left(t_{0}+2 \epsilon, t_{1}-2 \epsilon\right)$,

$$
\begin{equation*}
\|u\|_{L^{2}\left(\left(t_{0}+2 \epsilon, t_{1}-2 \epsilon\right), H^{1}(\widetilde{\omega})\right)} \leq \delta^{-\frac{3}{1-\vartheta}-n}\left(\sigma^{\frac{\beta}{1-\beta}} M+\sigma^{-1}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}\right) . \tag{3.34}
\end{equation*}
$$

Reducing $\epsilon_{0}$ if necessary, we can assume that $\delta<1$. Then we take $\sigma$ in (3.34) in order that

$$
\delta^{-\frac{3}{1-\vartheta}-n} \sigma^{\frac{\beta}{1-\beta}}=\delta .
$$

In that case

$$
\sigma^{-1} \leq \delta^{-\frac{m}{\beta}}
$$

with $m=\frac{4-\vartheta}{1-\vartheta}+n$.

But

$$
\beta=\vartheta^{N+1}=e^{-(N+1)|\ln \vartheta|} \geq \vartheta e^{-N_{0}|\ln \vartheta|} \geq \vartheta e^{-\frac{n|\ln \vartheta|\left(\mathbf{d}_{g}+1\right)}{\delta}}
$$

Hence

$$
\delta^{-\frac{3}{1-\vartheta}-n} \sigma^{-1} \leq e^{\frac{\kappa}{\delta}} .
$$

This inequality in (3.34) yields

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}+2 \epsilon, t_{1}-2 \epsilon\right), H^{1}(\widetilde{\omega})\right)} \leq \delta M+e^{\frac{\kappa}{\delta}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} . \tag{3.35}
\end{equation*}
$$

One more time Hardy's inequality in Lemma 3.1, for some fixed $s \in\left(0, \frac{1}{2}\right)$, yields

$$
\begin{equation*}
\|u\|_{L^{2}\left(\left(t_{0}, t_{0}+2 \epsilon\right), H^{1}(\widetilde{\omega})\right)},\|u\|_{L^{2}\left(\left(t_{1}-2 \epsilon, t_{1}\right), H^{1}(\widetilde{\omega})\right)} \leq 2^{s} c \epsilon^{s} M \tag{3.36}
\end{equation*}
$$

If $0<\epsilon \leq \epsilon_{0}$, for some sufficiently small $\epsilon_{0}$, we can take $\delta=\frac{\sqrt{\epsilon}}{2}$, then (3.35) and (3.36) entail

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\widetilde{\omega})\right)} \leq \epsilon^{s} M+e^{\frac{\kappa}{\sqrt{\epsilon}}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} .
$$

Substituting $\epsilon$ by $\epsilon^{2}$, we obtain

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\widetilde{\omega})\right)} \leq \epsilon^{2 s} M+e^{\frac{\kappa}{\epsilon}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} .
$$

This is the expected inequality.

We are now ready to prove the result showing how one can quantify the uniqueness of continuation from an interior data

Theorem 3.1. Let $\omega \Subset \Omega$. There exist two constants $C>0$ and $\gamma>0$, depending only on $\Omega, \kappa, K$, $\omega$ and $T_{0}$, so that, for any $u \in \mathscr{X}^{1}$ satisfying $L u=0$ in $Q$, we have

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\|u\|_{\mathscr{X}^{1}}\left|\ln \left(\frac{\|u\|_{\mathscr{X}^{1}}}{\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}}\right)\right|^{-\gamma}+\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} .
$$

Proof. Let $u \in \mathscr{X}^{1}$ satisfying $L u=0$ in $Q$. From Corollary 3.1, there exist $\widetilde{\omega} \Subset \Omega$ and four constants $\mu>0$, $c>0, C>0$ and $0<\sigma_{0}<1$ so that, for any $0<\sigma<\sigma_{0}$, we have

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq \sigma^{\mu}\|u\|_{\mathscr{X}^{1}}+e^{\frac{c}{\sigma}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\widetilde{\omega})\right)} .
$$

But according to Proposition 3.2, with fixed $s \in\left(0, \frac{1}{2}\right)$, there exist three constants $\gamma>0, C>0$ and $0<\epsilon_{0}<1$ so that, for any $0<\epsilon<\epsilon_{0}$,

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\widetilde{\omega})\right)} \leq \epsilon^{2 s}\|u\|_{\mathscr{X}^{1}}+e^{\frac{\kappa}{\epsilon}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} .
$$

The last two inequalities yield

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\left(\sigma^{\mu}+\epsilon^{2 s} e^{\frac{c}{\sigma}}\right)\|u\|_{\mathscr{X}}+e^{\frac{\kappa}{\epsilon}} e^{\frac{c}{\sigma}}\|u\|_{L^{2}\left((0, T), H^{1}(\omega)\right)}, \quad 0<\sigma<\sigma_{0}, 0<\epsilon<\epsilon_{0} \tag{3.37}
\end{equation*}
$$

Reducing $\sigma_{0}$ if necessary, we assume that $\sigma_{0}^{\mu} e^{-\frac{c}{\sigma_{0}}}<\epsilon_{0}^{\frac{1}{2 s}}$. In that case we can take in (3.37) $\epsilon$ so that $\epsilon^{2 s} e^{\frac{c}{\sigma}}=\sigma^{\mu}$. We get, by using that $\epsilon \geq \sigma^{p}$, with $p=\frac{\mu}{2 s}$,

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq \sigma^{\mu}\|u\|_{\mathscr{X}}+e^{\frac{\kappa}{\sigma^{p}}} e^{\frac{c}{\sigma}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}, \quad 0<\sigma<\sigma_{0}
$$

Whence, where $q=\max (1, p)$,

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq \sigma^{\mu}\|u\|_{\mathscr{X}}+e^{\frac{c}{\sigma^{4}}}\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)}, \quad 0<\sigma<\sigma_{0} \tag{3.38}
\end{equation*}
$$

We end up getting the expected inequality by minimizing with respect to $\sigma$.

## 4. Stability of parabolic Cauchy problems

In order to prove our stability estimate for the Cauchy problem, one additional step is necessary. It consists in quantifying the uniqueness of continuation from the Cauchy data to an interior subdomain. To do that we start with the following proposition.

Proposition 4.1. Let $\Gamma_{0}$ be a nonempty open subset of $\Gamma$ and $\nu \in\left(0, \frac{1}{2}\right)$. There exist $\omega \Subset \Omega$ and two constants $C>0$ and $c>0$, depending only on $\Omega, \kappa, K, \Gamma_{0}$, s and $T_{0}$, so that, for any $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$ and $0<\epsilon<\frac{t_{1}-t_{0}}{2}$, we have

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\omega \times\left(t_{0}, t_{1}\right)\right)} \leq \epsilon^{\nu}\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}+e^{\frac{c}{\epsilon^{2}}}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right) . \tag{4.1}
\end{equation*}
$$

Proof. Pick $0<\epsilon<\frac{t_{1}-t_{0}}{2}, 0<\eta<\epsilon$ and let $s \in\left[t_{0}+\epsilon, t_{1}-\epsilon\right]$. Let $\widetilde{x} \in \Gamma_{0}$ and $x_{0}=x_{0}(\widetilde{x})$ and $\rho$ be as in the definition of the uniform exterior sphere property. Fix $r>0$ in such a way that $B\left(x_{0}, \rho+r\right) \cap \Gamma \subset \Gamma_{0}$.

Let $\phi \in C_{0}^{\infty}(B(\widetilde{x}, \rho+r)), \phi=1$ on $B\left(\widetilde{x}, \rho+\frac{3 r}{4}\right)$ and $\left|\partial^{\alpha} \phi\right| \leq c r^{-|\alpha|},|\alpha| \leq 2$, where $c$ is a constant independent on $r$. Set, where $0<\delta<1$ is to be determined in the sequel,

$$
\begin{aligned}
& Q_{0}=\left[B\left(x_{0}, \rho+r\right) \cap \Omega\right] \times(s-\eta, s+\eta), \\
& Q_{1}=\left[B\left(x_{0}, \rho+r / 2\right) \cap \Omega\right] \times(s-\delta \eta, s+\delta \eta), \\
& Q_{2}=\left\{\left[B\left(x_{0}, \rho+r\right) \backslash B\left(x_{0}, \rho+3 r / 4\right)\right] \cap \Omega\right\} \times(s-\eta, s+\eta), \\
& \Sigma_{0}=\left[B\left(x_{0}, \rho+r\right) \cap \Gamma\right] \times(s-\eta, s+\eta) .
\end{aligned}
$$

We apply Theorem 2.2 , with $L_{s}=L, \lambda$ fixed and $\psi=(\rho+r)^{2}-\left|x-x_{0}\right|^{2}$, to $\phi u$ so that $u \in$ $H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfies $L u=0$ in $Q$ in order to obtain

$$
\begin{equation*}
C \int_{Q_{1}} u^{2} e^{-2 \tau \varphi} d x d t \leq \int_{Q_{0}}(L[\phi u])^{2} e^{-2 \tau \varphi} d x d t+\int_{\Sigma_{0}}\left(u^{2}+|\nabla u|^{2}+\left(\partial_{t} u\right)^{2}\right) e^{-2 \tau \varphi} d x d t . \tag{4.2}
\end{equation*}
$$

But

$$
L[\phi u]=L \phi u+2 A \nabla \phi \cdot \nabla u .
$$

Whence, $\operatorname{supp}(L[\phi u]) \cap Q_{0} \subset Q_{2}$ together with (4.2) yield

$$
\begin{equation*}
C \int_{Q_{1}} u^{2} e^{-2 \tau \varphi} d x d t \leq \int_{Q_{2}}\left(u^{2}+|\nabla u|^{2}\right) e^{-2 \tau \varphi} d x d t+\int_{\Sigma_{0}}\left(u^{2}+|\nabla u|^{2}+\left(\partial_{t} u\right)^{2}\right) e^{-2 \tau \varphi} d x d t \tag{4.3}
\end{equation*}
$$

Let

$$
\begin{aligned}
& \alpha=\eta^{-2}\left[e^{4 \lambda(\rho+r)^{2}}-e^{\lambda\left(2(\rho+r)^{2}-(\rho+r / 2)^{2}\right)}\right]:=\eta^{-2} \widetilde{\alpha} \\
& \beta=\eta^{-2}\left[e^{4 \lambda(\rho+r)^{2}}-e^{2 \lambda(\rho+r)^{2}}\right]:=\eta^{-2} \widetilde{\beta} \\
& \gamma=\eta^{-2}\left[e^{4 \lambda(\rho+r)^{2}}-e^{\lambda\left(2(\rho+r)^{2}-(\rho+3 r / 4)^{2}\right)}\right]:=\eta^{-2} \widetilde{\gamma}
\end{aligned}
$$

Then it is straightforward to check that

$$
\begin{aligned}
& \varphi(x, t) \leq \frac{\alpha}{1-\delta} \text { in } Q_{1}, \\
& \varphi(x, t) \geq \beta \text { in } \Sigma_{0} \\
& \varphi(x, t) \geq \gamma \text { in } Q_{2} .
\end{aligned}
$$

Noting $\frac{\beta}{\alpha}<1<\frac{\gamma}{\alpha}$, we can choose $0<\theta<1$ so that

$$
\frac{1}{1-\delta}=\theta \frac{\beta}{\alpha}+(1-\theta) \frac{\gamma}{\alpha}=\theta \frac{\widetilde{\beta}}{\widetilde{\alpha}}+(1-\theta) \frac{\widetilde{\gamma}}{\widetilde{\alpha}}>1
$$

With this choice of $\delta,(4.3)$ yields

$$
\begin{equation*}
C \int_{Q_{1}} u^{2} d x d t \leq e^{-4 b \eta^{-2} \tau} \int_{Q_{2}}\left(u^{2}+|\nabla u|^{2}\right) d x d t+e^{4 a \eta^{-2} \tau} \int_{\Sigma_{0}}\left(u^{2}+|\nabla u|^{2}+\left(\partial_{t} u\right)^{2}\right) d x d t . \tag{4.4}
\end{equation*}
$$

Here $a=\frac{1}{2}(1-\theta)(\widetilde{\gamma}-\widetilde{\beta})$ and $b=\frac{1}{2} \theta(\widetilde{\gamma}-\widetilde{\beta})$.
Let $\eta=\frac{\epsilon}{2}, s_{0}=t_{0}+\epsilon-\frac{\epsilon}{2}, s_{1}=s_{0}+\delta \frac{\epsilon}{2} \ldots s_{k}=s_{0}+k \delta \frac{\epsilon}{2}$. Let $N=N(\epsilon)$ so that

$$
\bigcup_{k=0}^{N}\left[s_{k}-\delta \frac{\epsilon}{2}, s_{k}+\delta \frac{\epsilon}{2}\right] \supset\left[t_{0}+\epsilon, t_{1}-\epsilon\right] .
$$

If $Q_{j}^{k}\left(\right.$ resp. $\left.\Sigma_{0}^{k}\right)$ denotes $Q_{j}\left(\right.$ resp. $\left.\Sigma_{0}\right), j=1,2$, when $s$ is substituted by $s_{k}$, then it follows from (4.3)

$$
\sum_{k=0}^{N} C \int_{Q_{1}^{k}} u^{2} d x d t \leq e^{a \epsilon^{-2} \tau} \sum_{k=0}^{N} \int_{Q_{2}^{k}}\left(u^{2}+|\nabla u|^{2}\right) d x d t+e^{-b \epsilon^{-2} \tau} \sum_{k=0}^{N} \int_{\Sigma_{0}^{k}}\left(u^{2}+|\nabla u|^{2}+\left(\partial_{t} u\right)^{2}\right) d x d t
$$

Note that the intervals $\left[s_{k}-\frac{\epsilon}{2}, s_{k}+\frac{\epsilon}{2}\right]$ can overlap, but their union can cover at most two times a subdomain of $\left(t_{0}, t_{1}\right)$. Whence

$$
\begin{equation*}
C I \leq e^{a \epsilon^{-2} \tau} N+e^{-b \epsilon^{-2} \tau} M, \quad \tau \geq \tau_{0} \tag{4.5}
\end{equation*}
$$

where we used the following temporary notation

$$
\begin{aligned}
& I=\|u\|_{\left.L^{2}\left(\left[B\left(x_{0}, \rho+r / 2\right) \cap \Omega\right)\right] \times\left(t_{0}+\epsilon, t_{1}-\epsilon\right)\right)} \\
& M=\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \\
& N=\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}
\end{aligned}
$$

In (4.5), substituting $\tau$ by $\epsilon^{2} \tau$, we get

$$
\begin{equation*}
C I \leq e^{a \tau} M+e^{-b \tau} N, \quad \tau \geq \epsilon^{-2} \tau_{0} \tag{4.6}
\end{equation*}
$$

Set

$$
\tau_{1}=\frac{\ln \frac{N}{M}}{a+b}
$$

If $\tau_{1} \geq \epsilon^{-2} \tau_{0}$, then $\tau=\tau_{1}$ in (4.6) yields

$$
\begin{equation*}
C I \leq M^{\vartheta} N^{1-\vartheta} \tag{4.7}
\end{equation*}
$$

with $\vartheta=\frac{b}{a+b}$.
When $\tau_{1}<\epsilon^{-2} \tau_{0}$,

$$
M<e^{(a+b) \epsilon^{-2} \tau_{0}} N
$$

This inequality entails

$$
\begin{equation*}
I \leq M=M^{\vartheta} M^{1-\vartheta} \leq M^{\vartheta} e^{(1-\vartheta)(a+b) \epsilon^{-2} \tau_{0}} N^{1-\vartheta} \tag{4.8}
\end{equation*}
$$

So in any case one of estimates (4.7) and (4.8) holds. In other words, we proved

$$
\begin{aligned}
& e^{-\frac{c}{\epsilon^{2}}}\|u\|_{\left.L^{2}\left(\left[B\left(x_{0}, \rho+r / 2\right) \cap \Omega\right)\right] \times\left(t_{0}+\epsilon, t_{1}-\epsilon\right)\right)} \\
& \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right)^{1-\vartheta}
\end{aligned}
$$

Fix $\left.\omega \Subset B\left(x_{0}, \rho+r / 2\right) \cap \Omega\right)$. Then the last inequality implies

$$
e^{-\frac{c}{\epsilon^{2}}}\|u\|_{L^{2}\left(\omega \times\left(t_{0}+\epsilon, t_{1}-\epsilon\right)\right)} \leq\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}^{\vartheta}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right)^{1-\vartheta}
$$

$$
C\|u\|_{L^{2}\left(\omega \times\left(t_{0}+\epsilon, t_{1}-\epsilon\right)\right)} \leq \sigma^{\gamma} e^{\frac{c}{\epsilon^{2}}} M+\sigma^{-1} e^{\frac{c}{\epsilon^{2}}}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right)
$$

for $\sigma>0$, where $\gamma=\frac{1-\vartheta}{\vartheta}$.
Once again from Hardy's inequality in Lemma 3.1, where $M_{1}=\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}$,

$$
\|u\|_{L^{2}\left(\omega \times\left(t_{0}, t_{0}+\epsilon\right)\right)},\|u\|_{L^{2}\left(\omega \times\left(t_{1}-\epsilon, t_{1}\right)\right)} \leq c^{\prime} \epsilon^{\nu} M_{1} .
$$

Combined with (4.9), this inequality yields

$$
C\|u\|_{L^{2}\left(\omega \times\left(t_{0}, t_{1}\right)\right)} \leq\left(\sigma^{\gamma} e^{\frac{c}{\epsilon^{2}}}+\epsilon^{\nu}\right) M_{1}+\sigma^{-1} e^{\frac{c}{\epsilon^{2}}}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right) .
$$

In this inequality we take $\sigma$ so that $\sigma^{\gamma}=\epsilon^{\nu} e^{\frac{c}{\epsilon^{2}}}$. Noting that $\sigma^{-1} \leq \epsilon^{-\frac{\nu}{\gamma}}$, we find

$$
C\|u\|_{L^{2}\left(\omega \times\left(t_{0}, t_{1}\right)\right)} \leq \epsilon^{\nu} M_{1}+e^{\frac{c}{\epsilon^{2}}}\left(\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}\right) .
$$

The proof is then complete.
Proposition 4.1 gives an estimate only in $L^{2}\left(\omega \times\left(t_{0}, t_{1}\right)\right)$. But we can derive from it an estimate in $L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)$ by using the following Caccioppoli type inequality for the parabolic equation $L u=0$.

Lemma 4.1. Let $\omega_{0} \Subset \omega_{1} \Subset \Omega$. There exist a constant $C>0$, depending only on $\Omega, \kappa, K, T_{0}, \omega_{0}$ and $\omega_{1}$, so that, for $0<\epsilon<\frac{t_{1}-t_{0}}{4}$ and $u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$, we have

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}\left(\omega_{0}\right)\right)} \leq\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\omega_{1}\right)\right)} . \tag{4.10}
\end{equation*}
$$

Proof. Let $u \in H^{1}\left((0, T), H^{2}(\Omega)\right)$ satisfying $L u=0$ in $Q$. By Green's formula, for any $v \in L^{2}\left(\left(t_{0}, t_{1}\right), H_{0}^{1}(\Omega)\right)$, we have

$$
\begin{equation*}
\int_{t_{0}}^{t_{1}} \int_{\Omega} A \nabla u \cdot \nabla v d x d t-\int_{t_{0}}^{t_{1}} \int_{\Omega} \partial_{t} u v d x d t=0 \tag{4.11}
\end{equation*}
$$

Let $\phi \in C_{0}^{\infty}\left(\omega_{1}\right)$ satisfying $0 \leq \phi \leq 1$ and $\phi=1$ in $\omega_{0}$.
Taking $v=\phi^{2} u$ in (4.11), we get in straightforward manner

$$
\int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2} A \nabla u \cdot \nabla u d x d t=-2 \int_{t_{0}}^{t_{1}} \int_{\omega_{1}}(\phi \nabla u) \cdot(u A \nabla \phi) d x d t+\int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2} \partial_{t} u u d x d t .
$$

But

$$
\int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2} A \nabla u \cdot \nabla v d x d t \geq \kappa \int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2}|\nabla u|^{2} d x d t
$$

Therefore

$$
\begin{equation*}
\kappa \int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2}|\nabla u|^{2} d x d t \leq-2 \int_{t_{0}}^{t_{1}} \int_{\omega_{1}}(\phi \nabla u) \cdot(u A \nabla \phi) d x d t+\int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2} \partial_{t} u u d x d t . \tag{4.12}
\end{equation*}
$$

An elementary convexity inequality yields

$$
\begin{equation*}
2\left|\int_{t_{0}}^{t_{1}} \int_{\omega_{1}}(\phi \nabla u) \cdot(u A \nabla \phi) d x d t\right| \leq \frac{\kappa}{2} \int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2}|\nabla u|^{2} d x d t+C \int_{t_{0}}^{t_{1}} \int_{\omega_{1}} u^{2} d x d t \tag{4.13}
\end{equation*}
$$

On the other hand, we have

$$
\begin{equation*}
\left|\int_{t_{0}}^{t_{1}} \int_{\omega_{1}} \phi^{2} \partial_{t} u u d x d t\right| \leq \int_{t_{0}}^{t_{1}} \int_{\Omega} \phi^{2} u^{2} d x d t+\int_{t_{0}}^{t_{1}} \int_{\Omega} \phi^{2}\left(\partial_{t} u\right)^{2} d x d t \tag{4.14}
\end{equation*}
$$

We combine (4.12), (4.13) and (4.14) in order to get

$$
C\|\nabla u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\omega_{0}\right)\right)} \leq\|u\|_{L^{2}\left(\omega_{1} \times\left(t_{0}, t_{1}\right)\right)}+\left\|\partial_{t} u\right\|_{L^{2}\left(\omega_{1} \times\left(t_{0}, t_{1}\right)\right)} .
$$

Or equivalently

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}\left(\omega_{0}\right)\right)} \leq\|u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\omega_{1}\right)\right)} .
$$

We observe that if $u \in H^{2}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfies $L u=0$, then $\partial_{t} u \in H^{1}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfies $L \partial_{t} u=0$. Therefore, as an immediate consequence of Caccioppoli's type inequatity (4.10) and Proposition 4.1 (applied both to $u$ and $\partial_{t} u$ ), we have

Corollary 4.1. Let $\Gamma_{0}$ be a nonempty open subset of $\Gamma$ and $\nu \in\left(0, \frac{1}{2}\right)$. There exist $\omega \Subset \Omega$ and two constants $C>0$ and $c>0$, that can depend on $\Omega, \kappa, K, T_{0}$, s and $\Gamma_{0}$ so that, for any $u \in H^{2}\left(\left(t_{0}, t_{1}\right), H^{2}(\Omega)\right)$ satisfying $L u=0$ and $\sigma>0$, we have

$$
\begin{equation*}
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\omega)\right)} \leq \epsilon^{\nu}\|u\|_{H^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)}+e^{\frac{c}{\epsilon^{2}}}\left(\|u\|_{H^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{\left.H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)\right)}\right) . \tag{4.15}
\end{equation*}
$$

We are now in position to complete the proof of Theorem 1.1. We recall that

$$
\mathcal{C}\left(u, \Gamma_{0}\right)=\|u\|_{H^{2}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)}+\|\nabla u\|_{H^{1}\left(\left(t_{0}, t_{1}\right), L^{2}\left(\Gamma_{0}\right)\right)} .
$$

In light of inequality (3.38) in the end of the proof of Theorem 3.1 and inequality (4.15), we get

$$
C\|u\|_{L^{2}\left(\left(t_{0}, t_{1}\right), H^{1}(\Omega)\right)} \leq\left(\sigma^{\mu}+e^{\frac{c}{\sigma^{q}}} \epsilon^{\nu}\right) M+e^{\frac{c}{\sigma^{4}}} e^{\frac{c^{\prime}}{\epsilon^{2}}} \mathcal{C}\left(u, \Gamma_{0}\right)
$$

The rest of the proof in quite similar to that of the end of Theorem 3.1.

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