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Probing the galaxy-halo connection in UltraVISTA to $z \sim 2$

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ABSTRACT

We use percent-level precision photometric redshifts in the UltraVISTA-DR1 near-infrared survey to investigate the changing relationship between galaxy stellar mass and the dark matter haloes hosting them to $z \sim 2$. We achieve this by measuring the clustering properties and abundances of a series of volume-limited galaxy samples selected by stellar mass and star formation activity. We interpret these results in the framework of a phenomenological halo model and numerical simulations. Our measurements span a uniquely large range in stellar mass and redshift and reach below the characteristic stellar mass to $z \sim 2$. Our results are: (1) at fixed redshift and scale, clustering amplitude depends monotonically on sample stellar mass threshold; (2) at fixed angular scale, the projected clustering amplitude decreases with redshift but the comoving correlation length remains constant; (3) characteristic halo masses and galaxy bias increase with increasing median stellar mass of the sample; (4) the slope of these relationships is modified in lower mass haloes; (5) concerning the passive galaxy population, characteristic halo masses are consistent with a simply less-abundant version of the full galaxy sample, but at lower redshifts the fraction of satellite galaxies in the passive population is very different from the full galaxy sample; (6) finally, we find that the ratio between the characteristic halo mass and median stellar mass at each redshift bin reaches a peak at $\log{(M_h/M_{\odot})} \sim 12.2$ and the position of this peak remains constant out to $z \sim 2$. The behaviour of the full and passively evolving galaxy samples can be understood qualitatively by considering the slow evolution of the characteristic stellar mass in the redshift range probed by our survey.

Key words: methods: statistical – galaxies: evolution – galaxies: formation – large-scale structure of Universe.

1 INTRODUCTION

How are galaxies distributed in dark matter haloes? What is the relationship between visible galaxies and the invisible dark matter? How do the characteristics of these dark matter haloes control the process of galaxy formation? In recent years, considering the dark matter haloes hosting galaxies has provided an alternative perspective on the galaxy formation question by permitting a consideration of how halo mass can regulate star-formation activity.

Although galaxy–galaxy lensing, using the distortion of distant background objects, can measure foreground dark matter mass distributions (Leauthaud et al. 2010), and can provide direct information concerning dark matter halo masses and mass profiles, this technique is challenging observationally and can only probe a relatively narrow redshift baseline as the background galaxy population must be resolved. Even with space-based observations, it is challenging to apply this technique above z > 1 as foreground galaxies become unresolved.

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A simpler although more indirect approach is to compare the observed abundance and clustering properties of the galaxy samples with predictions of phenomenological 'halo' models (Neyman & Scott 1952; Peacock & Smith 2000; Seljak 2000; Scoccimarro et al. 2001). These models contain an empirical prescription describing how galaxies populate dark matter haloes (the 'halo occupation function' or halo occupation distribution (HOD)): their drawback is that they rely on an accurate knowledge of the halo mass function and halo profile, which must be calibrated using numerical simulations. Although there is some doubt over the applicable regime for these calibrations and the importance of second-order effects such as 'halo assembly bias' (Croton, Gao & White 2007; Zentner, Hearin & van den Bosch 2014), these techniques remain promising for highredshift observations where cosmic variances and sample errors are the most important source of uncertainty and systematic errors do not yet dominate. (It is worth mentioning that these assembly bias effects have been shown to be important only in catalogues several orders of magnitudes larger than this work.) A related technique involves comparing the abundances of dark matter haloes with those of high-resolution N-body simulations, the 'sub-halo abundancematching' technique (Conroy, Wechsler & Kravtsov 2006).

The principal advantage of these methods is that they may be applied over a relatively large redshift baseline and require as observations only abundance and clustering measurements. A considerable industry has developed in recent years (Conroy & Wechsler 2009; Moster et al. 2010; Behroozi, Wechsler & Conroy 2013) in applying variants of this model in different redshift ranges and samples and attempting to interpret these results in terms of models of galaxy formation and evolution of star formation activity. However, understanding the derived halo masses and halo occupation functions over large redshift baselines – at least to $z \sim 2$ – has been complicated by the difficulty of comparing diverse data sets with different selection functions. For example, not all samples are cleanly selected in stellar mass and may use either luminosity or even star formation rate selection (as is the case with colour-colour selected 'BzK' (Daddi et al. 2004) galaxies. A final difficulty is that until now most surveys are not deep enough to reach below the all-important characteristic halo mass M^* at least to $z \sim 1$, and for this reason have concentrated primarily on more massive galaxies (Foucaud et al. 2010); those that are deep enough have instead been unable to constrain the more massive end because of insufficient area (Bielby et al. 2014). Reaching below this mass limit is important to understand how the rapid build-up of the faint end of the mass function occurs at $z \sim 1$.

The COSMOS field (Scoville et al. 2007) provides a bridge between small, high-redshift surveys [like Great observatories origins deep survey (GOODS), Cosmic assembly near-infrared deep extragalactic legacy survey (CANDELS) and other HST deep legacy fields] and larger, intermediate and local surveys like the Canada-France Legacy Survey (Coupon et al. 2012) and the SDSS (Zehavi et al. 2011). One of its principal advantages is that it contains a unique collection of spectroscopic redshifts fully sampling 0.5 < z < 4 and multiband photometry (Capak et al. 2007) allowing a precise calibration of photometric redshifts, providing a precision better than 1 per cent for both passive and star-forming galaxies. By using broad-band COSMOS data, in combination with the DR1 UltraVISTA near-infrared YJHKs data (McCracken et al. 2012), we are able to accurately determine stellar masses at least until $z \sim 4$ for samples as faint as $K_{\rm s}$ < 24.0 (Ilbert et al. 2013). Although large local spectroscopic redshift surveys such as BOSS and SDSS have revolutionised our knowledge of the distribution of galaxies in the local Universe, together with more recent magnitude-selected

and colour-selected surveys such as VIPERS, VVDS and DEEP2 (Davis et al. 2003; Le Fèvre et al. 2005; Guzzo et al. 2014) which allowed measurements to be extended to $z \sim 1$, it is only photometric redshift surveys which can probe the distribution of the galaxy population over such a broad redshift baseline in a single sample to relatively uniform limits. The unique aspect of this work is our precise stellar mass measurements over a large redshift range.

Previous studies of the halo occupation distribution (the relationship between the number of galaxies in a given dark matter halo and the halo mass) have revealed that the evolution of the angular correlation function and the distribution of satellite galaxies can be adequately explained by an unchanging halo occupation distribution. Some evidence has also emerged that the host halo mass at which the mass in stars reaches a maximum moves slowly towards higher halo masses (Coupon et al. 2012; Leauthaud et al. 2012). In other words, over the lifetime of a halo, star formation processes occur more efficiently in more massive haloes, and it is tempting to draw a link between this relationship and the observed luminositydependant nature of galaxy star formation rate (Cowie et al. 1996).

Our aim in this work is to use the large, uniform, COSMOS-UltraVISTA photometric redshift catalogue to investigate the relationship between dark matter halo masses and the properties of the visible galaxy population. We will do this by comparing observations (clustering and abundances) of a series of mass-selected galaxy samples to predictions of a theoretical halo model and also to the results of the sub-halo abundance matching using a highresolution numerical simulation. In this paper we use a flat Λ cold dark matter (Λ CDM) cosmology ($\Omega_m = 0.27$, $\Omega_{\Lambda} = 0.73$, $H_0 = 100 h \text{ km s}^{-1} \text{ Mpc}^{-1}$ and $\sigma_8 = 0.8$) with h = 0.7. All magnitudes are in the 'AB' system (Oke 1974).

2 THE ULTRAVISTA-COSMOS SURVEY

2.1 Survey overview and photometric redshift estimation

We use the publicly available UltraVISTA-COSMOS photometric redshift catalogue. This is a near-infrared selected galaxy sample, where objects are detected on a very deep $YJHK_s$ 'chi-squared' (Szalay, Connolly & Szokoly 1999) detection image: the advantage compared to a simple K_s catalogue is that many more bluer sources are included. A complete description of the photometric redshifts derived from this catalogue, and their parent photometric catalogue can be found in Ilbert et al. (2013). The UltraVISTA DR1 release McCracken et al. (2012) covers 1.5 deg² of the COSMOS field with deep $YJHK_s$ data at least one or two magnitudes deeper than the previous (McCracken et al. 2010) COSMOS near-infrared data.

Photometric redshifts were derived using 'Le Phare'¹ (Ilbert et al. 2006; Coupon et al. 2009). 'Le Phare' is a standard template fitting procedure using 31 templates including elliptical and spiral galaxies from the Polletta et al. (2007) library and 12 templates of young blue star-forming galaxies from Bruzual & Charlot (2003) stellar population synthesis models. Following standard procedure, the templates are redshifted and integrated through the instrumental transmission curves. The opacity of the intragalactic medium is accounted for and internal extinction can be added as a free parameter to each galaxy. Photometric redshifts are derived by comparing the modelled fluxes and the observed fluxes with a χ^2 merit function. In addition, a probability distribution function is associated with each photometric redshift. A detailed exploration of the precision

¹ http://www.cfht.hawaii.edu/~arnouts/LEPHARE/lephare.html



Figure 1. The stellar mass–redshift plane for all UltraVISTA galaxies (left-hand panel) and for passive galaxies (right-hand panel) with $K_s < 24$. Green lines show our mass thresholds for each sample. The solid red line shows the completeness limits from Ilbert et al. (2013). Inset: the redshift distributions. (Note: the grey-scale for each pixel in the mass–redshift plane is 0–100 objects for the left-hand panel and 0–20 for the right-hand panel.)

of these photometric redshifts at intermediate redshifts has been carried out in Ilbert et al. using a unique, large sample of spectroscopic redshifts covering the redshift range 1 < z < 3.

We use the usual $\sigma_{\Delta_z}/(1 + z_s)$ estimator where z_p and z_s are the photometric and the spectroscopic redshifts, respectively, and $\Delta_z = z_p - z_s$. 'Catastrophic' redshift errors are defined as objects with $|z_p - z_s|/(1 + z_s) > 0.15$. The percentage of these objects is denoted by η . Errors were estimated using the normalized median absolute deviation: $1.48 \times \text{median}(|z_p - z_s|/(1 + z_s))$ (Hoaglin, Mosteller & Tukey 1983).

For our $K_s < 24$ cut at z < 1.5 our photometric redshifts have a precision of better than 1 per cent and with less than 1 per cent of catastrophic failures. At 1.5 < z < 2, the precision remains excellent at ~0.03 with the percentage of catastrophic failures less than ~1 per cent. Even at 1.5 < z < 4, the precision is approximately 3 per cent with around 7 per cent of catastrophic failures. We limit to our analysis to z < 2.5: above this redshift range, the number of sources becomes too small to reliably measure clustering or abundances and our cross-bin contamination becomes significant as we will see in Section 3.3, where we investigate the effect of photometric errors on our clustering measurements.

We also use stellar masses computed in Ilbert et al. (2013). The Bruzual & Charlot (2003) stellar population synthesis models with a Chabrier (2003) initial mass function is used to generate a library of synthetic spectra normalized at one solar mass, which are then fitted to the photometric measurements described above using 'Le Phare'. As explained in Ilbert et al., 'stellar mass' corresponds to the median of the stellar mass probability distribution marginalized over all other parameters. At z < 2, the uncertainties on the stellar masses are well represented by a Gaussian with $\sigma = 0.04(1 + z)$. However, we note that systematic uncertainties can reach 0.1 dex using different templates or as much as 0.2 dex for massive galaxies for two different attenuation curves (see fig. 7 in Ilbert et al. 2010).

2.2 Sample selection

We construct a series of volume-limited samples selected by stellar mass. We first select all galaxies with $K_s < 24$ outside masked regions giving a total of 213 165 objects. After masking, the field has an effective area of 1.5 deg². The mask was constructed from a combined COSMOS *B*, *i* and *V* mask together with a mask detailing the borders of the UltraVISTA chi2 image (all stars are masked when one considers the COSMOS masks).

Fig. 1 shows the number density of objects as a function of redshift, with the inset panels showing the redshift distribution. The red lines are our mass thresholds and the green ones the completeness limits, as calculated in Ilbert et al. (2013). To calculate this completeness limit, Ilbert et al. computed the lowest stellar mass which could be detected for a galaxy using the relation $\log (M_{\text{limit}}) = \log (M) + 0.4 \times (K_s - 24)$ given a sample at $K_s < 24$. Then, at a given redshift, the stellar mass completeness limit corresponds to the mass for which 90 per cent of the galaxies have their M_{limit} below the stellar mass completeness limit. The number of objects in each bin, as well as the mean stellar mass, are summarized in Tables 1 and 2. Our large bin widths ($\Delta_{z, \min} = 0.3$) ensures a low bin-to-bin contamination but still reduces substantially the mixing of physical scales at a given angular scale. Our selected redshift bins are the same as those used in Ilbert et al.

We also considered the quiescent population selected using the criterion M(NUV) - M(R) > 3.5 defined in Ilbert et al. (2013). After applying object masks, the passive sample is composed of 22 169 objects with, as before, a magnitude cut of $K_s < 24.0$. The characteristics of each sample are summarized in Tables 1 and 2. The right-hand panels of Fig. 1 show the redshift distribution of this population.

3 METHODS

3.1 The angular two-point correlation function

We measure the two-point angular correlation function $w(\theta)$ for our samples using the Landy & Szalay (1993) estimator,

$$w(\theta) = \frac{n_{\rm r}(n_{\rm r}-1)}{n_{\rm d}(n_{\rm d}-1)} \frac{DD}{RR} - \frac{n_{\rm r}-1}{n_{\rm d}} \frac{DR}{RR} + 1,$$
(1)

where, for a chosen bin from θ to $\theta + \delta \theta$, *DD* is the number of galaxy pairs of the catalogue in the bin, *RR* the number of pairs of

Threshold ^(a)	0.65 < z < 0.95		0.95 < z < 1.3		1.3 < z < 1.75		1.3 < z < 1.75		1.75 < z < 2.25	
	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}^{(a)}$
8.8	26 441	9.43	_	_	_	_	_	_	_	_
9.0	21 642	9.60	_	_	_	-	_	_	_	_
9.2	17 300	9.81	25 317	9.84	_	-	_	-	_	_
9.4	13 763	10.01	20 466	10.02	_	-	_	_	_	_
9.6	10 911	10.19	16 431	10.21	22 666	10.11	-	-	-	-
9.8	8752	10.34	13 201	10.36	17 361	10.29	16 877	10.25	_	_
10.0	7015	10.45	10 520	10.50	13 280	10.45	12 547	10.42	_	_
10.2	5398	10.57	8382	10.61	10 000	10.58	9227	10.57	5681	10.58
10.4	3944	10.70	6258	10.74	7242	10.70	6484	10.70	4087	10.71
10.6	2556	10.85	4297	10.85	4828	10.83	4247	10.84	2695	10.83
10.8	1479	11.00	2579	11.00	2698	10.98	2427	10.97	1535	10.98
11.0	742	11.15	1276	11.15	1232	11.14	1094	11.13	-	-

Table 1. Characteristics of each redshift bin for the full $K_s < 24.0$ galaxy sample. For each stellar mass threshold and redshift bin we report the number of galaxies and the median log stellar mass.

Note. ^(a) in log (M_*/M_{\bigcirc}) .

Table 2. Characteristics of each redshift bin for the passive $K_s < 24.0$ galaxy sample. For each stellar mass threshold and redshift bin we report the number of galaxies and the median log stellar mass.

Threshold ^(a)	0.65 < z < 0.95		0.95 < z < 1.3		1.3 < z < 1.75		1.3 < z < 1.75		1.75 < z < 2.25	
	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$	$N_{\rm gal}$	$M_{\rm med}{}^{(a)}$
9.0	3877	10.44	_	_	_	_	_	_	_	_
9.2	3705	10.45	_	_	_	_	_	_	_	_
9.4	3547	10.49	5526	10.59	_	_	_	_	_	_
9.8	3186	10.55	5132	10.64	3560	10.66	_	_	_	_
10.0	2910	10.60	4775	10.67	3342	10.69	1527	10.69	_	_
10.2	2522	10.67	4299	10.73	2998	10.73	1390	10.73	785	10.80
10.4	2041	10.76	3583	10.80	2585	10.79	1182	10.81	714	10.83
10.6	1440	10.88	2717	10.90	2023	10.88	902	10.91	576	10.91
10.8	910	11.04	1803	11.01	1266	11.01	600	11.02	_	_
11.0	498	11.19	939	11.15	_	-	_	-	-	_

Note. ^(a) in log (M_*/M_{\odot}) .

a random sample in the same bin, and *DR* the number of pairs in the bin between the catalogue and the random sample. n_d and n_r are the number of galaxies and random objects, respectively. A random catalogue is generated for each sample with the same geometry as the data catalogue using $n_r \sim 400\,000$ which is at the most more than 500 and at least 16 times the number of data at each bin. We measure *w* in each field using a fast two-dimensional tree code in the angular range $0.001 < \theta < 0.2$ deg divided into 15 logarithmically spaced bins.

The errors on the two-point correlation measurements are estimated from the data using the jackknife approach (see for example Norberg et al. 2011) using 128 sub-samples. Removing one subsample at a time, this allows us to compute the covariance matrix as

$$C(w_i, w_j) = \frac{N-1}{N} \sum_{l=1}^{N} \left(w_i^l - \overline{w}_i \right) \left(w_j^l - \overline{w}_j \right), \qquad (2)$$

where N is the total number of sub-samples, \overline{w} the mean correlation function and w^l the estimate of $w(\theta)$ with the *l*th sub-sample removed.

Finally, although one of the largest survey at these redshifts, the UltraVISTA field covers a relatively small area, and as a consequence the integral constraint (see Groth & Peebles 1977) is expected to have an impact on our clustering measurements leading

on an underestimation of the clustering strength by a constant factor w_c which can be estimated as follows:

$$w(\theta) = w_{\rm mes}(\theta) + w_{\rm c}.$$
(3)

Assuming that the two-point correlation function is described by a simple power with slope γ and amplitude *A* fitted on the data, it leads to

$$w_{\rm mes}(\theta) = A\theta^{1-\gamma} - w_{\rm c} \times A(\theta^{1-\gamma} - C).$$
⁽⁴⁾

We can derive C following Roche et al. (1999):

$$C = \frac{\sum \theta^{1-\gamma} RR(\theta)}{\sum RR(\theta)},$$
(5)

and then:

$$w(\theta) = w_{\rm mes}(\theta) \frac{\theta^{1-\gamma}}{\theta^{1-\gamma} - C}.$$
(6)

We find $C \sim 1.42$.

3.2 Halo model implementation and fitting

To connect galaxies to their hosting dark matter haloes, we use a phenomenological 'halo' model (for a review see Cooray & Sheth 2002). In this model, it is assumed that the number of galaxies in a given dark matter halo is a simple monotonic function of the

halo mass. By combining this function (the 'halo occupation distribution') with our knowledge of the halo mass function and mass profile, one may predict the abundance and clustering properties of the visible population.

The key underlying assumption is that the number of galaxies N within a halo depends only on the halo mass M and not on environment or formation history: we will address the extent to which these assumptions are reasonable in subsequent sections.

Our model follows closely Zheng et al. (2005) who, motivated by simulations, suggested that the total numbers of galaxies in dark matter halo, N(M) is a sum of two contributions: one from the central galaxy in the halo $N_c(M)$ and one coming from the satellites $N_s(M)$. Thus N(M) can be expressed as

$$N(M) = N_{\rm c}(M) \times [1 + N_{\rm s}(M)].$$
(7)

We follow Zheng, Coil & Zehavi (2007) in which the central galaxy is described as a step function with a smooth transition allowing some scatter in the stellar mass–halo mass relation:

$$N_{\rm c}(M) = \frac{1}{2} \left[1 + \operatorname{erf} \left(\frac{\log M - \log M_{\min}}{\sigma_{\log M}} \right) \right], \tag{8}$$

and a power law with a cut at low halo mass for the satellites:

$$N_{\rm s}(M) = \left(\frac{M - M_0}{M_1}\right)^{\alpha}.$$
(9)

Our model has five adjustable parameters: M_{\min} , M_1 , M_0 , α and $\sigma_{\log M}$. In this work, we will examine in particular M_{\min} , which represents the characteristic mass scale for which 50 per cent of haloes host a galaxy, and M_1 , which is the characteristic mass scale for haloes to host one satellite galaxy.

Thus the mean number density of galaxies is given by

$$n_{\rm gal}(z) = N(M)n(M, z) \,\mathrm{d}M, \tag{10}$$

where n(M, z) is the halo mass function for which we use the prescription from Sheth & Tormen (1999).

We use a Navarro–Frenk–White halo density profile (Navarro, Frenk & White 1997) and the halo bias parametrization $b_h(M, z)$ from Tinker et al. (2005) which has been calibrated on simulations.

We compute the following derived parameters: the mean halo mass

$$\langle M_{\rm halo} \rangle(z) = dMMn(M, z) \frac{N(M)}{n_{\rm gal}(z)},$$
 (11)

the mean galaxy bias

$$b_{gal}(z) = dMbh(M, z)n(M, z)\frac{N(M)}{n_{gal}(z)}$$
(12)

and the satellite fraction

$$f_{\rm s}(z) = 1 - f_{\rm c}(z) = 1 - {\rm d}Mn(M, z) \frac{N_{\rm c}(M)}{n_{\rm gal}(z)}.$$
 (13)

The implementation of the halo model we use is described fully in Coupon et al. (2012).

We derive the best-fitting halo models corresponding to our measurements using the 'Population Monte Carlo' (PMC) technique as implemented in the $COSMOPMC^2$ package to sample likelihood space (Wraith et al. 2009; Kilbinger et al. 2010). For each galaxy sample, we simultaneously fit both the two-point correlation function w and

² http://cosmopmc.info

the number density of galaxies n_{gal} , by summing both contributions to the total χ^2 :

$$\chi^{2} = \sum_{i,j} \left[w^{\text{obs}}(\theta_{i}) - w^{\text{model}}(\theta_{i}) (C^{-1})_{i,j} \left[w^{\text{obs}}(\theta_{j}) - w^{\text{model}}(\theta_{j}) + \frac{\left[n_{\text{gal}}^{\text{obs}} - n_{\text{gal}}^{\text{model}} \right]^{2}}{\sigma_{\text{gal}}^{2}},$$
(14)

where C is the data covariance matrix. The error on the galaxy number density σ_{gal} contains both Poisson noise and cosmic variance.

3.3 Estimating the effect of photometric redshift errors on clustering measurements

To independently quantify the number of catastrophic photometric redshift outliers, we analyse the spatial cross-correlation of galaxies between different redshift bins. The misidentification of photo-*z*'s create physical clustering between otherwise uncorrelated bins. We use the pairwise analysis introduced in Benjamin, Van Waerbeke, Ménard & Kilbinger (2010), which considers two redshift bins at a time. With w_{ij} denoting the angular correlation function between redshifts *i* and *j*, the following combination of cross- and auto-correlation function vanishes for all angular scales θ_t ,

$$d_{t} = w_{ij}(\theta_{t}) \left(f_{ii} f_{jj} + f_{ij} f_{ji} \right) - w_{ii}(\theta_{t}) \frac{N_{i}}{N_{j}} f_{ij} f_{ji}$$
$$- w_{jj}(\theta_{t}) \frac{N_{j}}{N_{i}} f_{ji} f_{ii}.$$
(15)

The number of observed galaxies per bin *i* is N_i . The contamination fraction of galaxies originating from the redshift range given by bin *i*, but misplaced into bin *j* due to catastrophic failure is denoted with f_{ij} . This pairwise approach neglects the contamination from other bins $k \neq i, j$. Therefore, the fraction of galaxies correctly identified in bin *i* is $f_{ii} = 1 - f_{ij}$. The approximation of the pairwise analysis is valid for contamination fractions up to 10 per cent.

We restrict our analysis to non-adjacent redshift bins $(|i - j| \le 1)$, since both the large-scale structure and the photo-*z* dispersion create correlations between galaxies from neighbouring bins that are easily larger than 10 per cent. We follow Coupon et al. and calculate the covariance of the data vector d_t using a Jackknife estimate. As in Coupon et al., we neglect the mixed terms in equation (15), which correlate different correlation functions, since these terms are subdominant (Benjamin et al. 2010). The expression for the covariance then becomes

$$C_{ts} = \langle \boldsymbol{d}_{t} \boldsymbol{d}_{s} \rangle$$

$$= \langle w_{ij}(\theta_{t})w(\theta_{s}) \rangle (f_{ii}f_{jj} + f_{ij}f_{ji})^{2}$$

$$+ \langle w_{ii}(\theta_{t})w_{ii}(\theta_{s}) \rangle \left(\frac{N_{i}}{N_{j}}f_{ij}f_{ji}\right)^{2}$$

$$+ \langle w_{ii}(\theta_{t})w_{ii}(\theta_{s}) \rangle \left(\frac{N_{j}}{N_{i}}f_{ji}f_{ii}\right)^{2}.$$
(16)

We calculate a χ^2 null test with $\chi^2 = \boldsymbol{d}_t C_{st}^{-1} \boldsymbol{d}_s$, and fit the two parameters f_{ij} and f_{ji} .

As an example, we consider the galaxy sample with $\log (M_*/M_{\odot}) \sim 10.8$. Here, we find the fraction of catastrophic outliers to be consistent with zero between all pairwise bins (see left-hand panel of Fig. 2 for an example), with the exception of the contamination f_{13} from bin 0.8 < z < 1.1 to 1.5 < z < 2.0, which is >3 per cent (1 σ , see right-hand panel of Fig. 2).

The pairwise analysis typically constrains a quadratic combination of the contaminations f_{ij} and f_{ji} , and does not provide an



Figure 2. Two examples of constraints contamination fraction f_{ij} obtained from spatial clustering between redshift bin pairs. The solid, dashed and dotted lines show 1σ , 2σ and 3σ contours, respectively. Left-hand panel: contamination fraction between bins [0.5; 0.8] and [1.5; 2]. Right-hand panel: contamination fraction between bins [0.8; 1.1] and [1.5; 2]. In both panels, the *x*-(*y*-)axis represents the scattering from high to low (low to high) redshifts.

independent estimate of the outlier rates. An upper limit of a contamination fraction f_{ij} therefore implies that f_{ji} is zero, or very small. All our upper limits are below 15 per cent (1 σ), with the exception of f_{41} and f_{42} , for which the upper limits are 24 per cent. The lowest redshift bin 0.5 < z < 0.8 is affected the least, with contamination fractions less than 8 per cent from other bins.

To summarize, the cross-correlation analysis independently confirms the very high quality our of photometric redshifts, and is consistent with the low catastrophic outlier rate discussed in Section 2.1.

4 MASS-SELECTED CLUSTERING MEASUREMENTS

We first consider our mass-selected galaxy clustering measurements. In Figs 3 and 4 we show the projected angular correlation function w as a function of angular scale θ (in degrees) and stellar mass threshold for two representative redshift bins, 0.5 < z < 0.8and 1.5 < z < 2.0. The left-hand panels show the full sample, whereas the right-hand panels show the passive galaxy sample. The dotted lines on all panels correspond to the fits on large scales (~0.1 deg) to the low-redshift (0.5 < z < 0.8) full galaxy sample with a fixed slope of -0.8. Finally, the top horizontal axes shows the comoving angular separation at the redshift of the sample.

Qualitatively, several trends are immediately apparent. First, at a given stellar mass threshold, for both galaxy types, the clustering amplitude decreases with increasing redshift. Secondly, at a given redshift, the clustering amplitude is higher for samples with higher stellar mass thresholds. Finally, at both redshifts and at the *same* stellar mass threshold, the clustering amplitude of the passive galaxy population is always higher than the full galaxy population. It is also interesting to note that the dependence of clustering strength on stellar mass threshold is less pronounced for the passive galaxy population at lower redshifts (although this is not the case in other redshift



Figure 3. Mass-selected galaxy clustering measurements as a function of angular scale in degrees in the UltraVISTA-COSMOS survey for the full sample (left-hand panel) and the passive galaxy sample (right-hand panel) at 0.5 < z < 0.8. The dashed lines correspond to the best-fitting large-scale power laws for the 0.5 < z < 0.8 sample (left-hand panel).



Figure 4. As in Fig. 3 but for the 1.5 < z < 2.0 bin. The dashed lines show the large-scale fit for the corresponding mass bins in the 0.5 < z < 0.8 sample.

bins not shown here). The explanation of this behaviour is quite straightforward: examining Fig. 1, we see that the bulk of the passive population at $z \sim 0.5$ has stellar masses of $10^{10.5}$ M_{\odot}: fainter thresholds do not appreciably change the bulk median stellar mass threshold and therefore the overall clustering amplitudes rest unchanged.

Some general comments can also be made concerning the *shape* of w. First, for intermediate stellar mass threshold samples $(M \sim 10^{10} \text{ M}_{\odot})$ in the lower redshift 0.5 < z < 0.8 bin, w follows closely a power law with a slope $\gamma \sim 1.8$. However, at higher stellar mass thresholds, the slope of w begins to steepen, whereas at lower stellar mass threshold $M \sim 10^9 \text{ M}_{\odot}$ the slope of w is shallower. At high redshifts, finally, the shape of w deviates from a simple power law: this is seen most clearly if one considers the $M \sim 10^{9.8} \text{ M}_{\odot}$ at low and high redshifts (filled pentagons in both cases). At high redshifts, a 'break' is clearly seen at angular scales of ~0.01 deg, whereas no such break is visible a lower redshifts.

It is interesting to consider these measurements in the context of previous clustering and mass-selected clustering measurements in the COSMOS field. In an early paper, Meneux et al. (2009) used the zCOSMOS 10k spectroscopic sample to create a series of mass-selected galaxy samples covering 0.2 < z < 0.5. Despite the use of spectroscopic redshifts, the comparatively small number of galaxies and the consequently limited dynamic range (only one decade in stellar mass) meant that they were not able to detect clearly the trends outlined here.

Given the complicated nature of the behaviour of w it is clear that fitting a simple power law (with a corresponding integral constraint correction) misses most of these complex features. In the following section we will fit our 'halo model' to these observed correlation functions and discuss in detail the behaviour of the corresponding derived parameters as a function of both redshift and stellar mass threshold.

5 HALO MODEL ANALYSIS

5.1 Fitting the two-point correlation function

In Figs 5 and 6 the solid lines show the best-fitting halo model for a range of stellar mass thresholds for two redshift bins for both pas-

sive and total samples. In each figure, the thick solid line in the inset panel shows the corresponding best-fitting halo occupation distribution for each mass threshold at each redshift. The contribution to the satellite and central term is shown by the dashed and dotted lines, respectively. The left-hand and right-hand panels show the measurements for the total and passive sample, respectively.

Qualitatively, the fits are good, in particular for the lower mass threshold bins (note, however, the visual inspection of the fits can be misleading as there is significant covariance between adjacent bins). In general, lower mass threshold bins are better fit by our halo model. In the following sections, we will consider the derived parameters based on these halo model fits.

It is interesting to compare, at the same redshift, the fits for the passive galaxy population and the full galaxy population. At a comparable mass threshold, the minimum halo masses are higher (inset panel on each figure). In addition, it is interesting to note that the fraction of satellite galaxies is higher for the passive galaxy sample. We will return to this point in later sections.

5.2 Comoving correlation lengths for mass-selected samples

Traditionally, the comoving correlating length, representing the amplitude of the real-space correlation function at 1 Mpc and denoted by r_0 has been used as a measure of the strength of galaxy clustering. Often, this amplitude has been estimated by fitting a power-law correlation function to the projected correlation function and using it to estimate (sometimes by extrapolation) the correlation function amplitude at 1 Mpc after deprojection using the Limber (1954) formula. This procedure can potentially be problematic: as we have seen, the correlation function is poorly fit by a simple power law, and often the fitted scales lie outside the range of the survey. In this work we adopt a different approach: by using our fitted halo model parameters, we can *directly* compute $\xi(r)$, the real-space correlation function, at each slice, and from this make a direct measurement of the value of the correlation amplitude at 1 Mpc. From the top axes of Figs 5 and 6 we note, furthermore, that this 1 Mpc scale falls within the survey area at all redshifts.

These fits are plotted in Fig. 7 which shows the comoving correlation length r_0 as a function of sample median stellar mass. Error bars are computed by measuring the standard deviation of r_0 over a



Figure 5. Mass-selected galaxy clustering measurements in the UltraVISTA-COSMOS survey for the full sample (left-hand panel) and the passive galaxy sample (right-hand panel) at 0.5 < z < 0.8. The solid lines correspond to the best-fitting halo model for each bin. The inset panel shows the corresponding halo occupation distribution for each of the best-fitting models. Total, satellite and central contributions are shown by the solid, dashed and dot–dashed lines, respectively. The top horizontal axis shows the comoving separation corresponding to the angular distance at the effective redshift of the slice.



Figure 6. As in Fig. 5 but for two samples at 1.5 < z < 2.0.

weighted set of 5 000 PMC realizations of our halo model fits. For reference, small symbols show the values derived by Marulli et al. (2013) in VIPERS, and within the error bars, our measurements are in agreement with this work.

We see that the amplitude of the comoving correlation length increases gradually for samples whose mean stellar masses are smaller than $\log (M_*/M_{\odot}) \sim 11.0$; for samples more massive than this, the amplitude increases steeply. The presence of this 'knee' amplitude has been seen previously in lower redshift samples, at least for luminosity-selected samples (see, for example Norberg et al. 2002). We also we also see that at *fixed* stellar mass threshold, the clustering amplitude is independent of redshift. Some hints of this behaviour have been seen in previous papers (Pollo et al. 2006; McCracken et al. 2008; Meneux et al. 2009), but this is the first time it has been

unambiguously detected over such a large redshift range. Finally, we note that the bin 1.1 < z < 1.5 is offset from the others: as we shall see in Section 5.8, this a consequence of the rich structures present at intermediate redshifts in the COSMOS field.

5.3 The characteristic halo mass-galaxy number density relationship

Fig. 8 shows M_{\min} as a function of galaxy number density (defined in equation 10) for the full and the quiescent samples (open red symbols, respectively). In general, rarer, less abundant objects reside in more massive haloes. Comparing the quiescent population with the full galaxy sample, we see that (within the error bars) for a given galaxy abundance both the quiescent and full galaxy populations lie



Figure 7. The comoving correlation length r_0 , in Mpc, computed from our halo model for each redshift slice as a function of stellar mass threshold. The small squares and diamonds show correlation lengths measured in samples thresholded in stellar mass in the VIPERS survey (taken from table 3 in Marulli et al. 2013).



Figure 8. M_{\min} as a function of log galaxy number density for each redshift and mass threshold slice (passive galaxy samples are shown by the red open symbols). The solid line corresponds to a fit to the low-mass end of the most abundant samples.

within haloes of the *same* dark matter haloes masses (with the exception of the 1.1 < z < 1.5 bin, to which we will return to later; this bin is systematically different from all the others). In other words, in the halo mass/stellar mass plane, nothing distinguishes the passive population from the full galaxy population.

The solid line shows a power law fitted on the five most abundant bins of the lowest-redshift sample 0.5 < z < 0.8. It is clear that *even*

for a given redshift slice, a simple power-law fit does not adequately describe the data. Both the 0.5 < z < 0.8 and 0.8 < z < 1.1 redshift bins, which have sufficient depth to cover a large range in abundances show an inflection point at log ~ -2.5 . Higher-redshift bins do not have sufficient depth to reach below this inflection point, so we cannot say definitively if this feature is also present in the higher redshift data. Concerning redshift evolution of this relation, although our volume-limited samples cover different mass ranges at different redshifts, there is some tentative evidence that at fixed abundances, minimum halo masses required to host galaxies are progressively lower at higher redshifts (the points at 1.5 < z < 2.0, for example, are below all the low-redshift points, and this trend continues to even higher redshifts).

Some previous authors have also considered this relationship. Coupon et al., in the CFHTLS, found no evidence for an inflection point in the M_{min} versus n_{gal} relationship between z = 0.2 and 1.2. However, it should be noted that their samples were only approximately mass-limited; our slope in Fig. 8 is steeper than they found. Similarly Guo et al. (2014) present a large literature compilation of such measurements, together with their own measurements in the Baryon Acoustic Oscillations Spectroscopic Survey (BOSS); however, most of these measurements are not mass-selected, so direct comparisons to our own work is not straightforward. In later sections we will discuss how this change in slope is related to the evolution of the global stellar mass function.

5.4 Characteristic halo mass scales as a function of stellar mass and redshift

We now consider the characteristic mass scales M_{\min} and M_1 , representing the minimum halo mass required to host one and two galaxies, respectively. These quantities are shown in the left-hand panel of Fig. 9 as a function of median sample stellar mass for each redshift bin and mass threshold (as before, red symbols represent passive galaxy samples). As we have seen in Figs 5 and 6, galaxies with higher stellar masses reside in progressively more massive dark matter haloes. In the log-log plane of Fig. 9, this is an approximately linear relationship with one important exception: the lowest mass bin in M_1 , which flattens out at lower mass thresholds. Some hint of this is also seen in the next-nearest mass threshold, suggesting that this is a generic feature of the lower mass threshold samples. There is some evidence in Fig. 9 that, at a fixed stellar mass threshold, at low redshifts, both M_{\min} and M_1 do not evolve: however, at $z \sim 1$ they increase sharply with redshift, as can be seen for the highest redshift bin 2.0 < z < 2.5.

We now consider the 'mass gap' between M_1 and M_{min} : the righthand panel of Fig. 9 shows the ratio M_{min}/M_1 . It is useful to fi rst consider the lowest redshift bin, 0.5 < z < 0.8, as this probes the largest stellar mass thresholds. We can clearly see that this ratio passes through a minimum at intermediate mass thresholds. For both low-mass and high-mass stellar masses, this ratio is ~20; at intermediate stellar mass thresholds, the ratio is ~10. This allows us to understand measurements in the literature: at high thresholds in absolute magnitude (corresponding to our most massive samples), Zehavi et al. (2011) using SDSS observations at z ~ 0.1 found ~20; on the other hand, Wake et al. (2011) in the NEWFIRM Medium band survey (NMBS) at z ~ 1.5 found much smaller values, ~10; however as we can see from Fig. 9 this is primarily because these observations probed a much smaller range in stellar mass thresholds; in Fig. 9, most of our observations are at this stellar mass thresholds.

One interpretation of our results is that at high stellar mass thresholds, it becomes more difficult (it requires a more massive halo) to



Figure 9. Characteristic halo masses M_{\min} and M_1 (left-hand panel) and the ratio M_{\min}/M_1 (right-hand panel) as a function of sample median stellar mass threshold. Passive samples are shown in red open symbols.

form satellites as the material preferentially falls on to the central object. There is some evidence also that that ratio between M_1 and $M_{\rm min}$ decreases towards higher redshift as a consequence of the fact M_1 evolves less rapidly than $M_{\rm min}$, although our error bars are large in the high-redshift/high stellar mass bins. Kravtsov et al. (2004) used high-resolution dissipationless *N*-body simulations to investigate the halo occupation distribution and predicted that $M_1/M_{\rm min}$ should have 2/3 of its z = 0 value by z = 1. This prediction is consistent with what we find between our redshift bins 0.5 < z < 0.8 and 1.1 < z < 1.5. This means that, at higher redshifts, the difference between haloes containing several galaxies or only one becomes smaller which could be seen as an evidence that, at higher redshift, haloes may have more recently accreted satellites.

5.5 The stellar mass-halo mass relationship and comparisons with abundance-matching measurements

Previously, we have considered the relationship between the characteristic halo mass scales and each samples' stellar mass threshold. Another way to consider this relationship is to compute the ratio of stellar mass to halo mass as a function of either halo mass or stellar mass, known as the stellar mass–halo mass relationship, or SHMR. This has the advantage of explicitly showing what fraction of mass in stars is contained within a dark matter halo of given halo mass. One may then attempt to interpret this quantity in terms of the integrated star formation history over the lifetime of the halo, and in particular the star formation rate per stellar mass, or the specific star formation rate (sSFR). The implication is that present-day haloes which have a higher stellar mass to halo mass relationship are those in which star formation was more efficient than the past. Fig. 10 shows, for each redshift slice, the ratio of the median stellar mass to the characteristic halo mass M_{min} as a function of halo mass.

We fit this r atio to the widely u sed r elationship of Yang, Mo & van den Bosch (2003) which models the SHMR as a double power law with a different slope at high-mass and low-mass sides. Although it is has been suggested that this functional form may not be an optimal description of the SHMR (Leauthaud et al. 2011a), we consider it sufficient for this current data set, given the uncertainties which exist concerning the nature of dark matter haloes at high and intermediate redshifts which are currently not well constrained. The dashed lines show the fit to the Yang et al. relationship, where each point was weighted by the corresponding error in M_{\min} computed by PMC fitting procedure.

For most redshift bins, our COSMOS-UltraVISTA survey provides enough low-mass and high-mass haloes to constrain the SHMR on both sides of the peak. However, for the 2 < z < 2.5 bin we are not able to determine the peak location, given the challenging nature of correlation function measurements over sufficiently large stellar mass range at these redshifts. This is also the case for our 'outlier' bin 1 < z < 2 (which we already mentioned in Section 5.3) and is discussed further in Section 5.8) for which we are not able to determine the peak.

In order to constrain the peak position for *all* redshift bins, and to provide an additional check on the robustness of our results, we determine the peak position by using an alternative abundance-matching technique (Kravtsov et al. 2004; Conroy et al. 2006; Vale & Ostriker 2006). Essentially one matches the abundances of haloes selected in a certain way to galaxies selected in a (hopefully equivalent) way.

For our abundance-matching analysis, we use a series of snapshot outputs at each of our redshift slices from a large, highresolution N-body dark-matter-only simulation performed with GADGET-2 (Springel 2005) for a ACDM universe using Planck parameters (Planck Collaboration XVI 2014), namely $\Omega_{\rm M} = 0.307$, $\Omega_{\Lambda} = 0.693, h = 0.678$ and $\sigma_8 = 0.829$. The size of the simulation box is a cube of 80 h^{-1} Mpc on a side and contains in total 1024^3 particles with a mass resolution of $3 \times 10^7 \,\mathrm{M_{\odot}}$ per particle. Haloes and sub-haloes are identified using the halo-finding algorithm ADAPTAHOP (Aubert, Pichon & Colombi 2004) which uses an smoothed particle hydrodynamics (SPH)-like kernel to compute densities at the location of each particle and partitions the ensemble of particles into haloes and sub-haloes based on saddle points in the density field. The minimum number of particles per halo is 20: therefore, the least massive haloes in our survey ($\sim 10^{11} \, M_{\odot}$) are well resolved.

Next, circular velocities (v_{max}) and masses (M_{200}) are extracted for each halo and sub-halo. Circular velocities are defined as in the usual way, $V_{\text{max}} = \max(\sqrt{Gm(\leq r)/r})$, where $m(\leq r)$ is the mass enclosed at radius r. V_{max} can be estimated without any accurate estimate of the physical boundary of the objects which be difficult



Figure 10. The ratio between the median stellar mass in each sample and the halo mass at each redshift slice (filled coloured symbols). The dotted and solid lines show fit of the Yang et al. analytic expression to the HOD measurements and the abundance-matching results. The downward-pointing arrow in each redshift slice shows our approximate completeness limit in stellar mass, translated to the corresponding halo mass at that redshift.

in particular for sub-haloes. For each object, we define the radius R_{200} (and thus the mass M_{200}) as the radius where the enclosed mean density $M_V/(4\pi R_V^3/3)$ is 200 times the critical density, $\rho_c(z) = 3H(z)^2/8\pi G$, where $H(z) = H_0 \sqrt{\Omega_m(1+z)^3 + \Omega_\Lambda}$.

At each redshift bin, we determine the stellar mass threshold which matches the total abundance of galaxies selected by stellar mass *M* to the total abundances of haloes selected by v_{max} , i.e.

$$N_{\rm h}(>V_{\rm max}) = N_{\rm g}(>M).$$
 (17)

We compute our galaxy abundances by integrating the mass functions given in Ilbert et al. (2013). Then, at each redshift slice, we fit a simple linear function to the relationship between the median v_{max} and M_{200} for each bin of median halo mass. This allows us in turn to derive the characteristic halo masses at each abundance threshold, and, consequently, at the corresponding stellar mass threshold. The results from this procedure are shown as the solid lines in Fig. 10 (this line is actually the fit to the Yang et al. 2003 relation). At each redshift slice our simulation contains sufficient numbers of lowmass and high-mass haloes to reliably constrain the location of the position of the peak in the ratio M_*/M_h . The arrows on each panel shows the completeness limits in stellar mass threshold presented in Fig. 1. At z < 1 abundance-matching measurements agree with our halo model measurements for higher mass haloes: at the lower mass end there is a slight systematic offset. We note that the halo mass function used for our halo modelling is not the same as the halo mass function in our HOD model. As the dark matter halo mass function at these redshifts is not constrained by observations, it is difficult to choose between these two mass functions. We note that in the high-mass regime, the two methods are in good agreement, suggesting that M_{min} and M_{200} are equivalent estimates of halo mass.

As before, at each redshift bin, we fitted the position of the peak using the Yang et al. analytic expression. These points are shown as the open symbols in Fig. 11, slightly offset for clarity. Fig. 11 also includes a selection of literature measurements. We note the large scatter between previous measurements, which is probably related either to the measurement technique or the sample selection. Most lower redshift samples, with the exception of Leauthaud et al. (2011b), are luminosity selected and not mass selected, and the conversion to a reliable mass-selected sample is uncertain (see fig. 14. in Coupon et al. for an idea of the typical uncertainties).

We should also note that in this work we compute the dark matter halo masses given a sample of galaxies selected by stellar mass. Works such as Leauthaud et al. (2012) actually calculate stellar mass content for a given halo mass. In the case of large scatter



Figure 11. Location of the maximum in M^*/M_h from the HOD fitting procedure (filled coloured symbols) and for the abundance matching (open red symbols). Also shown are a selection of literature results. For clarity, the abundance-matching measurements are slightly offset in redshift from the HOD points.

between stellar mass and halo mass, these two measurements may not be equivalent.

In this work, our measurements are always made for highly complete samples. Stellar mass errors can potentially have an effect on the derived SHMR. This effect has been treated in detail in Behroozi, Conroy & Wechsler (2010). The effect of stellar mass errors on derived mass function in the present data set has been described in detail in Ilbert et al. (2013). The most pernicious effect is the 'Eddington Bias' (Eddington 1913) which can affect the high-mass end of the stellar mass function. Figure A2 in Ilbert et al. shows that a simple Gaussian description of stellar mass errors $\sigma = 0.04(1 + z)$ results in at most a 0.1–0.2 dex overestimate in stellar mass functions due to only the most massive bins (log $(M_*/M_{\odot}) \sim 12)$ – and in these bins there are not sufficient numbers of galaxies to measure correlation functions.

In summary, neither our HOD measurements nor our abundance matching indicates an evolution in the position of M_{peak} as a function of redshift, as have been claimed by previous authors (although, of course, a small increase with redshift cannot be ruled out by our measurements). The implication of this result will be discussed in subsequent sections.

5.6 The satellite fraction and its evolution with redshift

The physical properties of satellite galaxies (i.e. galaxies less massive than the central galaxy but lying inside the same dark matter halo) can provide additional information concerning the evolutionary history of the host dark matter halo. It is now relatively well established from both numerical simulations and observations that physical processes can modify the number of satellite galaxies. Major or minor mergers also play a role in affecting the satellite fraction. Furthermore, it seems that at z < 1, galaxy evolution is mostly 'secular', and major mergers may not be significant (López-Sanjuan et al. 2011). At these lower redshifts however 'environmen-



Figure 12. The satellite fraction as a function of median stellar mass threshold for the full sample and for the passive galaxy sample (open symbols).

tal quenching' processes (Bundy, Ellis & Conselice 2005; Peng et al. 2010) may modify the low-mass end of the global mass function. However, the rapid evolution in the global normalization of the stellar mass functions between 1 < z < 2 indicates that merging is an important process at higher redshifts, and suggest that the satellite fractions in low-redshift and high-redshift regimes should be different. From our halo occupation distribution model, we can derive the fraction of galaxies in a given dark matter halo which are satellite galaxies (equation 13). It still remains to be seen what is the link between satellite fractions derived directly from spectroscopically identified groups Kovac et al. (2014) and measurements made such as these: it is only possible to compare these independent results to ours over a very limited range in halo mass.

Fig. 12 shows the satellite fraction f_s as a function of the stellar mass for each redshift bin for both the passive galaxy sample and the full sample. At all redshifts, the satellite fraction decreases as the stellar mass threshold increases. We also note that at lower redshift bins, at a fixed stellar mass threshold, the satellite fraction at intermediate stellar masses (log $(M_*/M_{\odot}) \sim 10.0-10.5$) is *higher* in the quiescent sample than in the full one. This trend is not seen at higher stellar masses, where the satellite fraction remains low, regardless of the galaxy type.

This trend is reversed above z > 1, where the fraction of satellites is *lower* in quiescent galaxies populations than in the full sample. The trends in satellite fractions seen here with selection by mass and star formation activity at low redshifts are broadly consistent with those seen in Coupon et al. (2012) and Tinker et al. (2013), although the former study made selections in 'corrected' luminosity and rest-frame colour. Our measurements are below those of Wake et al. (2011); they fixed α in equation (13) to one while in our case it is treated as a free parameter. This flattening in the satellite fraction was also observed by Wake et al. (2011), Zehavi et al. (2011) and Zheng et al. (2007).

Since we know the fraction of satellite galaxies for both the full population and the passive population, we can compute the fraction of the total galaxy population which is a 'passive satellite' and also (using the total number of galaxies) the fraction of passive



Figure 13. The fraction of the total galaxy population which are passive (filled symbols) compared with the fraction of the total galaxy population which are passive satellites (open red symbols).

galaxies. Fig. 13 shows the fraction of the total galaxy population which is passive (open red symbols) and the fraction of total galaxy population which are passive satellite galaxies (filled symbols). The dependence of the passive fraction on mass is simply a reflection of the well-known result that the peak in the number of quiescent galaxies is at $z \sim 0.8$. This is to some extent mirrored in the evolution of the fraction of passive satellite galaxies, which tracks the overall passive galaxy population. In all cases, the fraction of passive satellite galaxies drops steeply at higher redshifts. Taken together, these trends suggest that massive galaxies at high redshifts may have already accreted all their satellites.

5.7 Galaxy bias

Galaxies are not perfect tracers of the underlying dark matter distribution. (Depending on one's viewpoint, this may be regarded either as a 'nuisance parameter' or containing information concerning galaxy evolution.) A knowledge of galaxy bias has become important in calibrating accurately cosmological probes, and so we now turn to a determination of galaxy bias in our survey using the halo model.

The well-known dependence of galaxy bias on luminosity has been studied extensively both in the local Universe and at higher redshifts (Norberg et al. 2001; Pollo et al. 2006; Coil et al. 2008; Meneux et al. 2009; Zehavi et al. 2011; Marulli et al. 2013). Photometric surveys have also provided important information at higher redshifts (McCracken et al. 2008; Coupon et al. 2012). The consensus from these studies is that that bias is a weak function of luminosity for galaxies with $L < L_*$ (where L_* is the characteristic luminosity from the Schechter function) and increases steeply for $L > L_*$. Interpreting these bias measurements has not always been straightforward, because in luminosity-selected surveys substantial luminosity evolution with redshift complicates our understanding of the relationship between mass in stars and galaxy mass. It is only very recently that it has been possible to make bias measurements as a function of stellar mass for a statistically significant volume.



Figure 14. The galaxy bias for each redshift slice for the full and quiescent samples (filled and red open symbols, respectively) as a function of median stellar mass and for each redshift slice.

Fig. 14 shows the galaxy bias derived from our best-fitting halo model parameters (see equation 12) as a function of the stellar mass at each redshift bin. We see a monotonic trend that bias increases with redshift as in Arnalte-Mur et al. (2014), for example. For $z \le 1$, and for stellar masses less than $10^{10.7}$ M_{\odot} for the full sample and for $10^{10.7}$ M_{\odot} for the quiescent sample, the bias depends weakly on stellar mass. However at stellar masses $10^{10.7-10.9}$ M_{\odot} bias is a strong function of stellar mass. For low stellar mass threshold full galaxy samples selected at low redshift we find $b_{gal} \sim 1.3$; the quiescent population is more strongly biased $b_{gal} \sim 1.6$ in agreement with the CFHTLS and PRIMUS (Coupon et al. 2012; Skibba et al. 2014).

Our data provides the most reliable measurement to date of the bias of quiescent galaxy populations at high redshifts: at 2.0 < z < 2.5 we find $b_{gal} \sim 3.5$ for the quiescent galaxy population, and $b_{gal} \sim 3$ for the full galaxy population. We note also that the difference in bias between the full galaxy population and the quiescent population at the same stellar mass threshold increases at higher redshifts. This is almost certainly because the full galaxy population is dominated by star-forming galaxies at high redshifts, which are weakly clustered, a point to which we will return to in the discussion section.

5.8 On the representativeness of the COSMOS field and a comparison with other results

It has already been noted that there are an overabundance of rich structures in the cosmos field (McCracken et al. 2007; Meneux et al. 2009), particularly at $z \sim 1$. In fact, some earlier studies such as Meneux et al. failed to find any significant dependence of clustering on stellar mass threshold, which is in all likelihood due to their relatively bright threshold in stellar mass, but also due to the overabundance of rich clusters in the field. More speculatively, the discovery of a 'quasar wall' a few degrees away from the COSMOS field which may in part give rise to the overall increase in density in the COSMOS field (Clowes et al. 2013). However, despite this

overall slightly elevated density increase, most of the relations presented in previous sections are qualitatively in agreement with what one expects, with the exception of the redshift bin at 1 < z < 1.5which deviates markedly and consistently from all trends presented in this paper.

To investigate further the discrepancy at 1 < z < 1.5, we used the 'WIRDS' data set (Bielby et al. 2012) to investigate the nature of the differences between COSMOS and other data. Although WIRDS is shallower than the present data set, it consists of four fields separated widely on the sky. We measured correlation functions in averaged mass-thresholded data in WIRDS and compared it to the COSMOS field. Interestingly, we find that the WIRDS data agrees with COSMOS on large scales, but at small scales there is *much* more power in COSMOS than in WIRDS. The implication which this has in the halo model fits can be seen in Fig. 8: for a given abundance, the derived halo masses are much lower than one would expect, essentially because of the much steeper one-halo term. This has implications for any study using the COSMOS field to measure small-scale clustering at 1 < z < 1.5. For example, the very steep two-point correlation function measured in McCracken et al. (2010) and Béthermin et al. (2014) at 1 < z < 1.5 seems now to be an artefact of very rich, small-scale clustering present at this redshift bin.

6 DISCUSSION: THE CHANGING RELATIONSHIP BETWEEN GALAXIES AND THE DARK MATTER HALOES THEY INHABIT

To understand the results presented in the previous sections they need to be considered in the general context of the evolution of the galaxy population from $z \sim 0$ to ~ 2 , some aspects of which are now quite well understood. Of course, the precise *mechanisms* which give rise to these changes is still debated, but we can at least consider how our abundance and halo mass measurements reflect these well-established changes in the global galaxy population.

It is worth starting by reminding ourselves of the evolution observed in the stellar mass function from $z \sim 0$ to ~ 2 for both passive and full galaxy populations. As described in Ilbert et al. (2013, based on measurements made in these data), the total normalization of the global mass function increases steadily from $z \sim 2$ to ~ 0 . However, for the passive galaxy population a rapid build-up is observed in the faint-end slope below $z \sim 1$. We may also consider the evolution of the amount of star formation per unit mass, the sSFR. At a given stellar mass, the sSFR declines steadily until $z \sim 0$ (Ilbert et al. 2013): stated another way, star formation at high redshift occurs preferentially in higher mass systems. The implications for the results presented here are several: first, at a fixed stellar mass threshold, the proportions of passive and star-forming galaxies is a strong function of redshift and stellar mass. At high redshifts ($z \sim 2$), our mass-selected samples are dominated by star-forming massive galaxies; at low redshifts, in contrast, the low-mass end becomes increasingly dominated by passively evolving galaxies. How may we understand our results in terms of these changes in the global galaxy population?

First, it is interesting to consider the dependence of clustering amplitude on stellar mass and redshift. Our measurements show clearly the dependence of galaxy clustering on stellar mass threshold. It is interesting to note that the weak dependence of clustering strength on stellar mass for the passive galaxy population in our threshold samples at $z \sim 0.8$ is entirely due to the large 'lump' of passively evolving galaxies at $M \sim 10^{10.5}$ M_{\odot} visible in the mass–redshift plane (Fig. 1): changes in the threshold do not change the

number of lower mass galaxies in the sample. Over the large redshift range of our survey, at a fixed stellar mass, the projected clustering amplitude at a fixed stellar mass threshold drops significantly. This is in due part a simple projection effect (and note also that at higher redshifts, our redshift bins are larger) as our comoving correlation lengths at fixed stellar mass, measured using our halo model, remain remarkably constant (Fig. 7). The increasingly biased nature of the galaxy population, (Fig. 14) is almost perfectly offset by the decreasing clustering amplitude of the underlying dark matter.

We fit our observations to a phenomenological halo model. Previously, Coupon et al. found that the fitted parameters of this model changed remarkably little from $z \sim 1$ to ~ 0 , reflecting the nature of the changes taking place in the galaxy population over this redshift range. This is certainly not the case with these data: above z > 1, many aspects of the fitted model parameters change radically. At fixed abundance, characteristic halo masses drop significantly above z > 1 (Fig. 8). The mass fraction of satellite galaxies contained in haloes drops almost to zero, and this effect is ever more pronounced for the passive galaxy population. In addition, the fraction of mass in satellite galaxies for faint passively evolving galaxies rises rapidly for faint galaxies (one sees almost exactly the same effect if one considers these quantities as a function of halo mass). It is challenging to compare the satellite fractions measured in previous works (Kovac et al. 2014) because of the different mass ranges probed with respect to spectroscopic surveys. However, qualitatively, this behaviour is in agreement with what one would expect from our current hierarchical models of galaxy evolution, where at high redshifts dark matter haloes are dominated by single massive galaxies. The rapid increase in the satellite fraction for faint passive galaxies happens exactly at the redshift range where the faint end of the mass function rises sharply and 'satellite quenching' processes become a dominant process in galaxy evolution (Peng et al. 2010).

Considering the differences between the passive and total galaxy population, it is interesting to note that passive galaxies and the full galaxy population lie on the same halo mass/abundance relationship (Fig. 8), and occupy the same region of parameter space as 'normal' galaxies. In almost all of the plots presented in this paper, the passive galaxy sample occupies the same region of parameter space as a less abundant, more clustered version of the full galaxy sample with one important exception: the satellite fraction, where the passive population is revealed as radically different from the full galaxy population.

We also consider the ratio between stellar mass and halo mass for a range of halo masses in each of our redshift slices. We find that the peak position shows only a weak dependence on redshift. This is a natural consequence of the fact that the shape of the overall stellar mass function and halo mass function evolves little from $z \sim 2$ to the present day. We compared our halo model measurements with the results of an abundance-matching technique and find approximately the same behaviour. The abundance-matching measurements allow us to estimate M^*/M_h ratios even for redshifts bins for which we are not able to fit our halo model results. In general, results are broadly in agreement with models which attempt to model jointly with the evolution of the stellar mass function over large redshift baseline. For example, Behroozi et al. 2013 find only a small increase in characteristic halo mass with redshift.

7 CONCLUSIONS

We have used highly precise photometric redshifts in the UltraVISTA-DR1 near-infrared survey to investigate the changing relationship between galaxy stellar mass and the dark matter haloes

We found the following results. (1) At fixed redshift and scale, clustering amplitude depends monotonically on sample stellar mass threshold. (2) At fixed angular scale, the projected clustering amplitude decreases with redshift but the comoving correlation length remains constant. (3) Characteristic halo masses and galaxy bias increase with increasing median stellar mass of the sample. (4) The slope of these relationships is modified in lower mass haloes. (5) Concerning the passive galaxy population, characteristic halo masses are consistent with a simply less-abundant version of the full galaxy sample, but at lower redshifts the fraction of satellite galaxies in the passive population is very different from the full galaxy sample. (6) Finally, we find that the ratio between the characteristic halo mass and median stellar mass at each redshift bin reaches a peak at $\log (M_{\rm h}/{\rm M_{\odot}}) \sim 12.2$ and the position of this peak remains constant out to $z \sim 2$. The behaviour of the full and passively evolving galaxy samples can be understood qualitatively by considering the slow evolution of the characteristic stellar mass in the redshift range covered by our survey.

The next step is to extend this analysis to higher redshifts (z > 4), where the discrepancy between models of galaxy formation and observations becomes even more acute. The new UltraVISTA DR2 data release, reaching several magnitudes deeper in all near-infrared bands, will enable for the first time this kind of study.

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