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# Volume mean operator and differentiation results associated to root systems

Chaabane REJEB\*

#### Abstract

Let R be a root system in  $\mathbb{R}^d$  with Coxeter-Weyl group W and let k be a nonnegative multiplicity function on R. The generalized volume mean of a function  $f \in L^1_{loc}(\mathbb{R}^d, m_k)$ , with  $m_k$  the measure given by  $dm_k(x) := \omega_k(x)dx := \prod_{\alpha \in R} |\langle \alpha, x \rangle|^{k(\alpha)}dx$ , is defined by:  $\forall x \in \mathbb{R}^d, \forall r > 0$ ,  $M^r_B(f)(x) := \frac{1}{m_k[B(0,r)]} \int_{\mathbb{R}^d} f(y)h_k(r, x, y)\omega_k(y)dy$ , where  $h_k(r, x, .)$  is a compactly supported nonnegative explicit measurable function depending on R and k. In this paper, we prove that for almost every  $x \in \mathbb{R}^d$ ,  $\lim_{r\to 0} M^r_B(f)(x) = f(x)$ .

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Key words: Generalized volume mean value operator, harmonic kernel, Dunkl-Laplace operator, Dunkl transform.

### 1 Introduction and statement of the result

We consider the Euclidean space  $\mathbb{R}^d$  equipped with a reduced root system R i.e. R is a finite subset of  $\mathbb{R}^d \setminus \{0\}$  such that for any  $\alpha \in R$ ,  $R \cap \mathbb{R}\alpha = \{\pm \alpha\}$  et  $\sigma_\alpha(R) = R$ , where  $\sigma_\alpha$  is the reflection with respect to the hyperplane  $H_\alpha$  orthogonal to  $\alpha$  (see [9] and [11]). Let us denote by W the Coxeter-Weyl group generated by the reflections  $\sigma_\alpha$ ,  $\alpha \in R$  and by k a multiplicity function defined on R (i.e. W-invariant) which will be supposed nonnegative throughout this paper.

The Dunkl intertwining operator  $V_k$ , associated to the paire (R, k), is the topological isomorphism of  $\mathcal{C}^{\infty}(\mathbb{R}^d)$  onto itself given by

$$V_k(f)(x) := \int_{\mathbb{R}^d} f(y) d\mu_x^k(y), \quad x \in \mathbb{R}^d,$$
(1.1)

where  $\mu_x^k$  is a probability measure with compact support contained in the convex hull of W.x, the orbit of x under the W-action (see [4], [13], [14] et [17]). This operator satisfies

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the following intertwining relation  $\Delta_k V_k = V_k \Delta$ , where  $\Delta$  is the usual Laplacian and  $\Delta_k$  is the Dunkl Laplacian acting on  $C^2$ -functions as follows

$$\Delta_k f(x) := \Delta f(x) + 2 \sum_{\alpha \in R_+} k(\alpha) \Big( \frac{\langle \nabla f(x), \alpha \rangle}{\langle x, \alpha \rangle} - \frac{\|\alpha\|^2}{2} \frac{f(x) - f(\sigma_\alpha \cdot x)}{\langle x, \alpha \rangle^2} \Big),$$

with  $R_+$  a fixed positive subsystem of R.

In order to build a potential theory associated to reflection groups, a type volume mean operator has been introduced in [7] (see also [6]) as a crucial tool. In particular, it allowed us to characterize the notion of  $\Delta_k$ -harmonicity by the volume mean property (see [7] and [6] for more details).

The volume mean operator of  $f \in \mathcal{C}(\mathbb{R}^d)$  has the following form

$$\forall x \in \mathbb{R}^d, \ \forall r > 0, \quad M_B^r(f)(x) := \frac{1}{m_k[B(0,r)]} \int_{\mathbb{R}^d} f(y) h_k(r,x,y) \omega_k(y) dy, \tag{1.2}$$

where  $m_k$  is the measure

$$dm_k(x) := \omega_k(x)dx := \prod_{\alpha \in R_+} |\langle \alpha, x \rangle|^{2k(\alpha)}dx$$
(1.3)

and  $h_k$  is the so-called harmonic kernel ( its properties will be recalled in section 2) defined by

$$\forall r > 0, \quad \forall x, y \in \mathbb{R}^d, \quad h_k(r, x, y) = \int_{\mathbb{R}^d} \mathbf{1}_{[0, r]} \left( \sqrt{\|x\|^2 + \|y\|^2 - 2\langle x, z \rangle} \right) d\mu_y^k(z).$$
(1.4)

Note that if k is the zero function, the measure  $\mu_x^k$  is equal to  $\delta_x$  the Dirac measure at x, the Dunkl Laplacian coincides with  $\Delta$  and as  $h_k(r, x, y) = \mathbf{1}_{[0,r]}(||x-y||) = \mathbf{1}_{B(x,r)}(y)$ , the generalized volume operator is none other than the classical one.

According to [8], for r and x fixed and under the condition  $k(\alpha) > 0$  for all  $\alpha \in R$ , we have

supp 
$$h_k(r, x, .) = B^W(x, r) := \bigcup_{g \in W} B(g.x, r),$$
 (1.5)

where  $B(\xi, a)$  is the closed Euclidean ball centered at  $\xi$  and with radius a > 0. When the function k vanishes, the support of the function  $h_k(r, x, .)$  is contained in  $B^W(x, r)$  (see [7]) and contains B(x, r) (see [8]).

Our aim here is to prove the following result:

**Theorem:** Let  $\Omega$  be a *W*-invariant open subset of  $\mathbb{R}^d$  and let  $f \in L^1_{loc}(\Omega, m_k)$ . Then for almost every  $x \in \Omega$ , we have

$$\lim_{r \downarrow 0^+} M_B^r(f)(x) = f(x).$$
(1.6)

Using (1.5), the volume mean of  $f \in L^1_{loc}(\Omega, m_k)$  is well defined at (x, r) whenever  $B(x, r) \subset \Omega$ . Furthermore, by the formulas (1.3), we see that negligible sets for the

Lebesgue measure coincide with negligible sets for the measure  $m_k$ .

On other hand, an understood phenomena is that the relation (1.6) means that the function  $h_k(r, x, .), x$  is fixed, concentrates only in the neighborhood of x when  $r \to 0$  and not on other point gx of the orbit W.x as we can could think from (1.5).

### 2 Some basics from Dunkl analysis

In this section we will recall some results from Dunkl theory which will be useful for the sequel. These concern in particular the Dunkl transform, the Dunkl translation and the harmonic kernel.

#### 2.1 The Dunkl transform and Dunkl's translation operators

• The Dunkl transform of a function  $f \in L^1(\mathbb{R}^d, m_k)$  is defined by

$$\mathcal{F}_k(f)(\lambda) := \int_{\mathbb{R}^d} f(x) E_k(-i\lambda, x) \omega_k(x) dx, \quad \lambda \in \mathbb{R}^d,$$
(2.1)

where  $E_k(x,y) := V_k(e^{\langle x, \cdot \rangle})(y)$ ,  $x, y \in \mathbb{R}^d$ , is the Dunkl kernel which is analytically extendable to  $\mathbb{C}^d \times \mathbb{C}^d$  and satisfies the following properties (see [3], [5], [10] and [14]): for all  $x, y \in \mathbb{R}^d$ , all  $\lambda \in \mathbb{C}$  and all  $g \in W$ ,

$$E_k(x,y) = E_k(y,x), \quad E_k(x,\lambda y) = E_k(\lambda x,y), \quad E_k(gx,gy) = E_k(x,y).$$
 (2.2)

Moreover the following inequality holds

$$\forall x, y \in \mathbb{R}^d, \quad |E_k(-ix, y)| \le 1.$$
(2.3)

The Dunkl transform shares many properties with the usual Fourier transform (see [10], [14]). In particular, it is an isomorphism of  $\mathcal{S}(\mathbb{R}^d)$  (the Schwartz space) onto itself and its inverse is given by

$$\mathcal{F}_k^{-1}(f)(x) = c_k^{-2} \mathcal{F}_k(f)(-x) = c_k^{-2} \int_{\mathbb{R}^d} f(\lambda) E_k(ix,\lambda) \omega_k(\lambda) d\lambda, \quad x \in \mathbb{R}^d,$$

where  $c_k$  is the Macdonald-Mehta constant (see [12]) given by

$$c_k := \int_{\mathbb{R}^d} e^{-\frac{\|x\|^2}{2}} \omega_k(x) dx.$$
(2.4)

Furthermore, the following Plancherel theorem holds: The transformation  $c_k^{-1} \mathcal{F}_k$  extends uniquely to an isometric isomorphism of  $L^2(\mathbb{R}^d, m_k)$  and we have the Plancherel formula:

$$\forall f \in L^2(\mathbb{R}^d, m_k), \quad \|c_k^{-1} \mathcal{F}_k(f)\|_{L^2(\mathbb{R}^d, m_k)} = \|f\|_{L^2(\mathbb{R}^d, m_k)}.$$
(2.5)

• The Dunkl translation operators  $\tau_x, x \in \mathbb{R}^d$ , are defined on  $\mathcal{C}^{\infty}(\mathbb{R}^d)$  by (see [18])

$$\forall y \in \mathbb{R}^d, \quad \tau_x f(y) = \int_{\mathbb{R}^d} V_k \circ T_z \circ V_k^{-1}(f)(y) d\mu_x(z), \tag{2.6}$$

where  $T_x$  is the classical translation operator given by  $T_x f(y) = f(x+y)$ . The Dunkl translation operators have the following properties:

$$\tau_0 f = f, \quad \tau_x f(y) = \tau_y f(x), \quad \tau_x(\Delta_k f) = \Delta_k(\tau_x f), \quad \tau_x E_k(.,z)(y) = E_k(x,z)E_k(y,z).$$

Note that if  $f \in \mathcal{S}(\mathbb{R}^d)$ , the function  $\tau_x f \in \mathcal{S}(\mathbb{R}^d)$  and it can be defined by means of the Dunkl transform as follows (see [18]):

$$\tau_x f(y) = \mathcal{F}_k^{-1}[E_k(ix, .)\mathcal{F}_k(f)](y) = c_k^{-2} \int_{\mathbb{R}^d} \mathcal{F}_k(f)(\lambda) E_k(ix, \lambda) E_k(iy, \lambda) \omega_k(\lambda) d\lambda, \quad y \in \mathbb{R}^d.$$
(2.7)

For  $x \in \mathbb{R}^d$ , the operator  $\tau_x$  can be extended to the space  $L^2(\mathbb{R}^d, m_k)$  as follows: Fix  $f \in L^2(\mathbb{R}^d, m_k)$ . Since  $|E_k(-ix, \xi)| \leq 1$ , the function  $\xi \mapsto E_k(ix, \xi)\mathcal{F}_k(f)(\xi)$  belongs to  $L^2(\mathbb{R}^d, m_k)$ . Hence, by Plancherel theorem, there exists a unique  $L^2(\mathbb{R}^d, m_k)$ -function denoted by  $\tau_x f$  and called the x-Dunkl translate function of f such that

$$\mathcal{F}_k(\tau_x f)(\xi) = E_k(ix,\xi)\mathcal{F}_k(f)(\xi).$$
(2.8)

For more properties on Dunkl translation operators when they act on  $L^2(\mathbb{R}^d, m_k)$  we can see ([16]).

#### 2.2 The harmonic kernel

In this section we recall some results of [7].

Let  $(r, x, y) \mapsto h_k(r, x, y)$  be the harmonic kernel defined by (1.4). It satisfies the following properties (see [7]):

- 1. For all r > 0 and  $x, y \in \mathbb{R}^d$ ,  $0 \le h_k(r, x, y) \le 1$ .
- 2. For all fixed  $x, y \in \mathbb{R}^d$ , the function  $r \mapsto h_k(r, x, y)$  is right-continuous and non decreasing on  $]0, +\infty[$ .
- 3. For all  $r > 0, x, y \in \mathbb{R}^d$  and  $g \in W$ , we have

$$h_k(r, x, y) = h_k(r, y, x)$$
 and  $h_k(r, gx, y) = h_k(r, x, g^{-1}y).$  (2.9)

4. For all r > 0 and  $x \in \mathbb{R}^d$ , we have

$$\|h_k(r,x,.)\|_{k,1} := \int_{\mathbb{R}^d} h_k(r,x,y)\omega_k(y)dy = m_k(B(0,r)) = \frac{d_k r^{d+2\gamma}}{d+2\gamma},$$
 (2.10)

where  $d_k$  is the constant

$$d_k := \int_{S^{d-1}} \omega_k(\xi) d\sigma(\xi) = \frac{c_k}{2^{d/2 + \gamma - 1} \Gamma(d/2 + \gamma)}.$$

Here  $d\sigma(\xi)$  is the surface measure of the unit sphere  $S^{d-1}$  of  $\mathbb{R}^d$  and  $c_k$  is the Macdonald-Mehta constant (2.4).

5. The harmonic kernel satisfies the following geometric inequality: if  $||a-b|| \le 2r$  with r > 0, then

$$\forall \xi \in \mathbb{R}^d, \quad h_k(r, a, \xi) \le h_k(4r, b, \xi)$$

(see [7], Lemma 4.1). In the classical case (i.e. k = 0), this inequality says that if  $||a - b|| \le 2r$ , then  $B(a, r) \subset B(b, 4r)$ .

6. Let r > 0 and  $x \in \mathbb{R}^d$ . Then the function  $h_k(r, x, .)$  is upper semi-continuous on  $\mathbb{R}^d$ .

Note that to prove the upper semi-continuity of  $h_k(r, x, .)$ , with r > 0 and  $x \in \mathbb{R}^d$ , the authors of [7] have constructed a decreasing sequence  $(\varphi_{\varepsilon}) \subset \mathcal{D}(\mathbb{R}^d)$  of radial functions such that for every  $\varepsilon > 0$ ,  $0 \le \varphi_{\varepsilon} \le 1$ ,  $\varphi_{\varepsilon} = 1$  on B(0, r) and for all  $y \in \mathbb{R}$ 

$$\lim_{\varepsilon \to 0} \varphi_{\varepsilon}(y) = \mathbf{1}_{B(0,r)}(y), \quad h_k(r, x, y) = \lim_{\varepsilon \to 0} \tau_{-x} \varphi_{\varepsilon}(y), \tag{2.11}$$

where  $\tau_x$  is the x-Dunkl translation operator.

In order to prove our result, we will need two lemmata. But, at first, we start by the following remark:

**Remark 2.1** Let r > 0. The function  $\mathbf{1}_{B(0,r)}$  is in  $L^2(\mathbb{R}^d, m_k)$ . For  $x \in \mathbb{R}^d$ , we can then define  $\tau_{-x}(\mathbf{1}_{B(0,r)})$  as being the  $L^2(\mathbb{R}^d, m_k)$ -function whose Dunkl transform is equal to

$$\mathcal{F}_k\left(\tau_{-x}(\mathbf{1}_{B(0,r)})\right)(\xi) = E_k(-ix,\xi)\mathcal{F}_k\left(\mathbf{1}_{B(0,r)}\right)(\xi).$$
(2.12)

(see (2.8)). This  $L^2(\mathbb{R}^d, m_k)$ -function (which coincides also with  $\mathbf{1}_{B(x,r)}$  when k = 0) has been used formally in ([16] and [1]) for studying the  $L^p(\mathbb{R}^d, m_k)$ -boundedness of the Dunkl-Hardy-Littlewood maximal operator. In the next result, we will show that this function coincides almost everywhere with  $h_k(r, x, .)$ . But, in contrast to the harmonic kernel, the  $L^2$ -definition (2.12) of the function  $\tau_{-x}(\mathbf{1}_{B(0,r)})$  does not give any precision neither on its support nor on some geometric properties like the geometric inequality mentioned above.

**Lemma 2.1** Let r > 0 and  $x \in \mathbb{R}^d$ . Then, for almost every  $y \in \mathbb{R}^d$ , we have

$$h_k(r, x, y) = \tau_{-x}(\mathbf{1}_{B(0,r)})(y).$$
(2.13)

*Proof:* We consider the sequence  $(\varphi_{\varepsilon})$  as in (2.11). By the monotone convergence theorem, we can see that  $\tau_{-x}\varphi_{\varepsilon} \longrightarrow h_k(r, x, .)$  in  $L^2(\mathbb{R}^d, m_k)$ . On the other hand, since  $\mathbf{1}_{B(0,r)} \in L^2_k(\mathbb{R}^d)$ , we have

$$\begin{split} \left\| \tau_{-x} \varphi_{\varepsilon} - \tau_{-x} (\mathbf{1}_{B(0,r)}) \right\|_{L_{k}^{2}(\mathbb{R}^{d})} &= c_{k}^{-1} \left\| \mathcal{F}_{k} \left[ \tau_{-x} \varphi_{\varepsilon} \right] - \mathcal{F}_{k} \left[ \tau_{-x} (\mathbf{1}_{B(0,r)}) \right] \right\|_{L_{k}^{2}(\mathbb{R}^{d})} \\ &= c_{k}^{-1} \left\| E_{k}(-ix, .) \mathcal{F}_{k} \left[ \varphi_{\varepsilon} \right] - E_{k}(-ix, .) \mathcal{F}_{k} \left[ \mathbf{1}_{B(0,r)} \right] \right\|_{L_{k}^{2}(\mathbb{R}^{d})} \\ &\leq c_{k}^{-1} \left\| \mathcal{F}_{k} \left[ \varphi_{\varepsilon} \right] - \mathcal{F}_{k} \left[ \mathbf{1}_{B(0,r)} \right] \right\|_{L_{k}^{2}(\mathbb{R}^{d})} \\ &= \left\| \varphi_{\varepsilon} - \mathbf{1}_{B(0,r)} \right\|_{L_{k}^{2}(\mathbb{R}^{d})} \longrightarrow 0 \quad \text{as} \quad \varepsilon \to 0, \end{split}$$

where we have used Plancherel formula (2.5) for Dunkl's transform in the first and the last lines, the relations (2.7) and (2.12) in the second line, the inequality  $|E_k(-ix,\xi)| \leq 1$  in the third line and the monotone convergence theorem in the last line.

Thus, we get  $(\tau_{-x}\varphi_{\varepsilon})$  converges also to  $\tau_{-x}(\mathbf{1}_{B(0,r)})$  in  $L^2(\mathbb{R}^d, m_k)$ . This proves the desired equality.

Our second lemma, proved in [7], says that

**Lemma 2.2** Let  $x \in \mathbb{R}^d$ . Then the family of probability measures

$$d\eta_{x,r}^k(y) = \frac{1}{m_k[B(0,r)]} h_k(r,x,y)\omega_k(y)dy$$

is an approximation of the Dirac measure  $\delta_x$  as  $r \longrightarrow 0$ . More precisely

- **1.** For all  $\alpha > 0$ ,  $\lim_{r \to 0} \int_{||x-y|| > \alpha} d\eta_{x,r}^k(y) = 0$ .
- **2.** Let  $\Omega \subset \mathbb{R}^d$  be a W-invariant open set, f a locally bounded measurable function defined on  $\Omega$  and  $x \in \Omega$ . If f is continuous at x, then

$$\lim_{r \to 0} \int_{\mathbb{R}^d} f(y) d\eta_{x,r}^k = \lim_{r \to 0} M_B^r(f)(x) = f(x).$$
(2.14)

### 3 Proof of the result

Firstly, we will show the result when the W-invariant open set  $\Omega$  is the whole space  $\mathbb{R}^d$ .

**Theorem 3.1** Let  $f \in L^1_{loc}(\mathbb{R}^d, m_k)$ . Then, for almost every  $x \in \mathbb{R}^d$ , the relation (1.6) holds.

To prove this theorem, we will use the weak- $L^1(\mathbb{R}^d, m_k)$  estimates of the Dunkl-Hardy-Littlewood maximal function (see [1] and [16]). This idea has been taken from the classical case (see [15]).

*Proof:* Step 1: Suppose that f is a continuous function on  $\mathbb{R}^d$ . In this case, the result follows immediately from the relation (2.14).

Step 2: We will prove the result when  $f \in L^1(\mathbb{R}^d, m_k)$ . To do this, it suffices to show that

$$f^*(x) := \limsup_{r \to 0} M_B^r(|f - f(x)|)(x) = 0$$

for almost every  $x \in \mathbb{R}^d$ .

• At first, we claim that there exists a constant C > 0 such that

$$\forall t > 0, m_k\{f^* > t\} := m_k\{x \in \mathbb{R}^d, f^*(x) > t\} \le \frac{C}{t} \|f\|_{L^1_k(\mathbb{R}^d)}.$$
(3.1)

Indeed, we have

$$f^*(x) \le \sup_{r>0} M_B^r(|f - f(x)|)(x) \le M_k(|f|)(x) + |f(x)|,$$
(3.2)

where  $M_k(g)$  is the maximal function of  $g \in L^1(\mathbb{R}^d, m_k)$  defined by

$$M_k(g)(x) := \sup_{r>0} \frac{1}{m_k(B(0,r))} \left| \int_{\mathbb{R}^d} g(y) \tau_{-x} \left( 1_{B(0,r)} \right) (y) \omega_k(y) dy \right|.$$

(see [16] and [1]). We notice that from (2.13) and (1.2), we have

$$M_k(|f|)(x) = \sup_{r>0} M_B^r(|f|)(x)$$

which justifies (3.2). Consequently,

$$\{f^* > t\} \subset \{M_k(|f|) + |f| > t\} \subset \{M_k(|f|) > t/2\} \cup \{|f| > t/2\}.$$

This implies that

$$m_k\{f^* > t\} \le m_k\{M_k(|f|) > t/2\} + m_k\{|f| > t/2\}.$$
(3.3)

From ([16] or [1]), there exists a constant  $C_1 > 0$  such that

$$m_k\{M_k(|f|) > t/2\} \le \frac{2C_1}{t} \|f\|_{L^1(\mathbb{R}^d, m_k)}$$
(3.4)

and from Markov's inequality, we have

$$m_k\{|f| > t/2\} \le \frac{2}{t} \|f\|_{L^1(\mathbb{R}^d, m_k)},\tag{3.5}$$

Then we deduce (3.1) from (3.3), (3.4) and (3.5) with  $C = 2C_1 + 2$ .

• Let  $\varepsilon > 0$  and let  $g \in \mathcal{D}(\mathbb{R}^d)$  such that  $||f - g||_{L^1(\mathbb{R}^d, m_k)} \leq \varepsilon$ . For every  $x \in \mathbb{R}^d$ , step 1 applied to the function  $y \mapsto |g(y) - g(x)|$  shows that  $g^*(x) = 0$ . This implies that  $(f - g)^* \leq f^* + g^* = f^*$ . Since  $f^* = (f - g + g)^* \leq (f - g)^* + g^* = (f - g)^*$ , we get  $f^* = (f - g)^*$ . Consequently, by (3.1) we obtain

$$m_k\{f^* > t\} = m_k\{(f - g)^* > t\} \le \frac{C}{t} \|f - g\|_{L^1(\mathbb{R}^d, m_k)} = \frac{C}{t}\varepsilon.$$

As  $\varepsilon > 0$  is arbitrary, this proves that

$$\forall t > 0, \quad m_k\{f^* > t\} = 0.$$

Finally, since

$$\{f^* > 0\} = \bigcup_{n \ge 1} \{f^* > 1/n\},\$$

we deduce that  $m_k\{f^* > 0\} = 0$ . That is  $f^* = 0$  a.e. as desired. **Step 3:** Let  $f \in L^1_{loc}(\mathbb{R}^d, m_k)$ . For every  $n \in \mathbb{N} \setminus \{0\}$ , the function  $f_n = f\mathbf{1}_{B(0,n)}$  is in  $L^1(\mathbb{R}^d, m_k)$ . By Step 2, we have  $f_n^*(x) = 0$  for all  $x \in \mathbb{R}^d \setminus E_n$ , where  $E_n$  is a measurable set such that  $m_k(E_n) = 0$ .

We will prove that  $\{f^* > 0\} \subset \bigcup_{n \ge 1} E_n$  which will imply the desired result. Let  $x \in \mathbb{R}^d$  such that  $f^*(x) > 0$ . There is an integer  $n = n_x \in \mathbb{N} \setminus \{0\}$  such that  $supp h_k(r, x, .) \subset B(0, n)$  for every  $r \le 1$ . This implies that  $f^*(x) = f_n^*(x) > 0$ . That is  $x \in E_n$ . This completes the proof.

Now, we will prove our result that we recall below

**Corollary 3.1** Let  $\Omega \subset \mathbb{R}^d$  be a W-invariant open set. If  $f \in L^1_{loc}(\Omega, m_k)$ , then (1.6) holds for almost every  $x \in \Omega$ .

*Proof:* Let  $n \in \mathbb{N}$  large enough such that

$$\Omega_{\frac{1}{z}}:=\{x\in\Omega,\ dist(x,\partial\Omega)>1/n\}=\{x\in\Omega,\ B(x,1/n)\subset\Omega\}$$

is a nonempty set. For such n, we consider  $O_n := B_o(0, n) \cap \Omega_{\frac{1}{n}}$  and  $K_n = \overline{O_n}$ , where  $B_o(a, r)$  is the open ball centered at  $a \in \mathbb{R}^d$  and with radius r > 0.

As  $\Omega_{\frac{1}{n}}$  is W-invariant, we can see that  $O_n$  (resp.  $K_n$ ) is a W-invariant open (resp. W-invariant compact) subset of  $\Omega$ . Moreover, we have for every n large enough

$$K_n \subset O_{n+1} \subset K_{n+1}$$
 and  $\Omega = \bigcup_n K_n = \bigcup_n O_n$ .

Now, let  $f_n$  be the function given by  $f_n(x) = f(x)$  if  $x \in K_n$  and  $f_n(x) = 0$  if  $x \in \mathbb{R}^d \setminus K_n$ . Clearly  $f_n$  belongs to  $L^1_{loc}(\mathbb{R}^d, m_k)$  and by Theorem 3.1 we have  $f_n(x) = \lim_{r \to 0} M^r_B(f_n)(x)$  for almost every  $x \in \mathbb{R}^d$ .

Let

$$E_n := \left\{ x \in \mathbb{R}^d, \quad f_n(x) \neq \lim_{r \to 0} M_B^r(f_n)(x) \right\} \quad and \quad E := \left\{ x \in \Omega, \quad f(x) \neq \lim_{r \to 0} M_B^r(f)(x) \right\}.$$

Since  $f_n$  is continuous on the open set  $\mathbb{R}^d \setminus K_n$ , by (2.14) we deduce that  $E_n \subset K_n \subset \Omega$ . Let us now take  $x \in E$ . There exist R > 0 and  $N \in \mathbb{N}$  such that  $B(x, R) \subset O_N \subset K_{N+1} \subset \Omega$ . We will show that  $x \in E_{N+1}$ . As  $O_N$  and  $K_{N+1}$  are invariant under the action of the Coxeter-Weyl group W and thanks to the support property of the function  $h_k(r, x, .)$  we have

$$\forall r \in ]0, R], \quad supp \ h_k(r, x, .) \subset O_N \subset K_{N+1}.$$

But  $f = f_{N+1}$  on  $O_N$ . Therefore, if  $x \notin E_{N+1}$  i.e.  $f_{N+1}(x) = \lim_{r \to 0} M_B^r(f_{N+1})(x)$ , then  $f(x) = \lim_{r \to 0} M_B^r(f)(x)$  and  $x \notin E$ , a contradiction. Thus  $x \in E_{N+1}$ . This proves that  $E \subset \bigcup_n E_n$  and E is a negligible set as desired.  $\Box$ 

By taking f the characteristic function of a measurable set  $E \subset \mathbb{R}^d$ , we obtain

**Corollary 3.2** Let  $E \subset \mathbb{R}^d$  be a measurable set and  $x \in \mathbb{R}^d$ . Then for almost every  $x \in E$  we have

$$\frac{\|h_k(r, x, .)\|_{L^1(E, m_k)}}{\|h_k(r, x, .)\|_{L^1(\mathbb{R}^d, m_k)}} \longrightarrow 1 \quad as \quad r \to 0.$$

When k = 0, the previous result takes the following form: for almost every  $x \in E$  we have

$$\frac{m_0(E\cap B(x,r))}{m_0(B(x,r))}\longrightarrow 1 \quad \text{as} \quad r\to 0.$$

where  $m_0$  is the Lebesgue measure on  $\mathbb{R}^d$ . In this case, the point x is called of Lebesgue density of E (see [15]).

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