# Volume mean operator and differentiation results associated to root systems 

Chaabane Rejeb

## To cite this version:

Chaabane Rejeb. Volume mean operator and differentiation results associated to root systems. 2017. hal-01436147

HAL Id: hal-01436147

## https://hal.science/hal-01436147

Preprint submitted on 16 Jan 2017

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Volume mean operator and differentiation results associated to root systems 

Chaabane REJEB*


#### Abstract

Let $R$ be a root system in $\mathbb{R}^{d}$ with Coxeter-Weyl group $W$ and let $k$ be a nonnegative multiplicity function on $R$. The generalized volume mean of a function $f \in$ $L_{l o c}^{1}\left(\mathbb{R}^{d}, m_{k}\right)$, with $m_{k}$ the measure given by $d m_{k}(x):=\omega_{k}(x) d x:=\prod_{\alpha \in R}|\langle\alpha, x\rangle|^{k(\alpha)} d x$, is defined by: $\forall x \in \mathbb{R}^{d}, \forall r>0, \quad M_{B}^{r}(f)(x):=\frac{1}{m_{k}[B(0, r)]} \int_{\mathbb{R}^{d}} f(y) h_{k}(r, x, y) \omega_{k}(y) d y$, where $h_{k}(r, x,$.$) is a compactly supported nonnegative explicit measurable function$ depending on $R$ and $k$. In this paper, we prove that for almost every $x \in \mathbb{R}^{d}$, $\lim _{r \rightarrow 0} M_{B}^{r}(f)(x)=f(x)$.


MSC (2010) primary: 42B25, 42B37, 43A32; secondary: 31B05, 33C52.
Key words: Generalized volume mean value operator, harmonic kernel, Dunkl-Laplace operator, Dunkl transform.

## 1 Introduction and statement of the result

We consider the Euclidean space $\mathbb{R}^{d}$ equipped with a reduced root system $R$ i.e. $R$ is a finite subset of $\mathbb{R}^{d} \backslash\{0\}$ such that for any $\alpha \in R, R \cap \mathbb{R} \alpha=\{ \pm \alpha\}$ et $\sigma_{\alpha}(R)=R$, where $\sigma_{\alpha}$ is the reflection with respect to the hyperplane $H_{\alpha}$ orthogonal to $\alpha$ (see [9] and [11]). Let us denote by $W$ the Coxeter-Weyl group generated by the reflections $\sigma_{\alpha}, \alpha \in R$ and by $k$ a multiplicity function defined on $R$ (i.e. $W$-invariant) which will be supposed nonnegative throughout this paper.
The Dunkl intertwining operator $V_{k}$, associated to the paire $(R, k)$, is the topological isomorphism of $\mathcal{C}^{\infty}\left(\mathbb{R}^{d}\right)$ onto itself given by

$$
\begin{equation*}
V_{k}(f)(x):=\int_{\mathbb{R}^{d}} f(y) d \mu_{x}^{k}(y), \quad x \in \mathbb{R}^{d}, \tag{1.1}
\end{equation*}
$$

where $\mu_{x}^{k}$ is a probability measure with compact support contained in the convex hull of $W \cdot x$, the orbit of $x$ under the $W$-action (see [4], [13], [14] et [17]). This operator satisfies

[^0]the following intertwining relation $\Delta_{k} V_{k}=V_{k} \Delta$, where $\Delta$ is the usual Laplacian and $\Delta_{k}$ is the Dunkl Laplacian acting on $C^{2}$-functions as follows
$$
\Delta_{k} f(x):=\Delta f(x)+2 \sum_{\alpha \in R_{+}} k(\alpha)\left(\frac{\langle\nabla f(x), \alpha\rangle}{\langle x, \alpha\rangle}-\frac{\|\alpha\|^{2}}{2} \frac{f(x)-f\left(\sigma_{\alpha} \cdot x\right)}{\langle x, \alpha\rangle^{2}}\right),
$$
with $R_{+}$a fixed positive subsystem of $R$.
In order to build a potential theory associated to reflection groups, a type volume mean operator has been introduced in [7] (see also [6]) as a crucial tool. In particular, it allowed us to characterize the notion of $\Delta_{k}$-harmonicity by the volume mean property (see [7] and [6] for more details).
The volume mean operator of $f \in \mathcal{C}\left(\mathbb{R}^{d}\right)$ has the following form
\[

$$
\begin{equation*}
\forall x \in \mathbb{R}^{d}, \forall r>0, \quad M_{B}^{r}(f)(x):=\frac{1}{m_{k}[B(0, r)]} \int_{\mathbb{R}^{d}} f(y) h_{k}(r, x, y) \omega_{k}(y) d y \tag{1.2}
\end{equation*}
$$

\]

where $m_{k}$ is the measure

$$
\begin{equation*}
d m_{k}(x):=\omega_{k}(x) d x:=\prod_{\alpha \in R_{+}}|\langle\alpha, x\rangle|^{2 k(\alpha)} d x \tag{1.3}
\end{equation*}
$$

and $h_{k}$ is the so-called harmonic kernel (its properties will be recalled in section 2) defined by

$$
\begin{equation*}
\forall r>0, \quad \forall x, y \in \mathbb{R}^{d}, \quad h_{k}(r, x, y)=\int_{\mathbb{R}^{d}} \mathbf{1}_{[0, r]}\left(\sqrt{\|x\|^{2}+\|y\|^{2}-2\langle x, z\rangle}\right) d \mu_{y}^{k}(z) . \tag{1.4}
\end{equation*}
$$

Note that if $k$ is the zero function, the measure $\mu_{x}^{k}$ is equal to $\delta_{x}$ the Dirac measure at $x$, the Dunkl Laplacian coincides with $\Delta$ and as $h_{k}(r, x, y)=\mathbf{1}_{[0, r]}(\|x-y\|)=\mathbf{1}_{B(x, r)}(y)$, the generalized volume operator is none other than the classical one.

According to [8], for $r$ and $x$ fixed and under the condition $k(\alpha)>0$ for all $\alpha \in R$, we have

$$
\begin{equation*}
\operatorname{supp} h_{k}(r, x, .)=B^{W}(x, r):=\cup_{g \in W} B(g \cdot x, r), \tag{1.5}
\end{equation*}
$$

where $B(\xi, a)$ is the closed Euclidean ball centered at $\xi$ and with radius $a>0$.
When the function $k$ vanishes, the support of the function $h_{k}(r, x,$.$) is contained in$ $B^{W}(x, r)$ (see [7]) and contains $B(x, r)$ (see [8]).
Our aim here is to prove the following result:
Theorem: Let $\Omega$ be a $W$-invariant open subset of $\mathbb{R}^{d}$ and let $f \in L_{l o c}^{1}\left(\Omega, m_{k}\right)$. Then for almost every $x \in \Omega$, we have

$$
\begin{equation*}
\lim _{r \downarrow 0^{+}} M_{B}^{r}(f)(x)=f(x) . \tag{1.6}
\end{equation*}
$$

Using (1.5), the volume mean of $f \in L_{l o c}^{1}\left(\Omega, m_{k}\right)$ is well defined at $(x, r)$ whenever $B(x, r) \subset \Omega$. Furthermore, by the formulas (1.3), we see that negligible sets for the

Lebesgue measure coincide with negligible sets for the measure $m_{k}$.
On other hand, an understood phenomena is that the relation (1.6) means that the function $h_{k}(r, x,),$.$x is fixed, concentrates only in the neighborhood of x$ when $r \rightarrow 0$ and not on other point $g x$ of the orbit $W . x$ as we can could think from (1.5).

## 2 Some basics from Dunkl analysis

In this section we will recall some results from Dunkl theory which will be useful for the sequel. These concern in particular the Dunkl transform, the Dunkl translation and the harmonic kernel.

### 2.1 The Dunkl transform and Dunkl's translation operators

- The Dunkl transform of a function $f \in L^{1}\left(\mathbb{R}^{d}, m_{k}\right)$ is defined by

$$
\begin{equation*}
\mathcal{F}_{k}(f)(\lambda):=\int_{\mathbb{R}^{d}} f(x) E_{k}(-i \lambda, x) \omega_{k}(x) d x, \quad \lambda \in \mathbb{R}^{d} \tag{2.1}
\end{equation*}
$$

where $E_{k}(x, y):=V_{k}\left(e^{\langle x,\rangle}\right)(y), \quad x, y \in \mathbb{R}^{d}$, is the Dunkl kernel which is analytically extendable to $\mathbb{C}^{d} \times \mathbb{C}^{d}$ and satisfies the following properties (see [3], [5], [10] and [14]): for all $x, y \in \mathbb{R}^{d}$, all $\lambda \in \mathbb{C}$ and all $g \in W$,

$$
\begin{equation*}
E_{k}(x, y)=E_{k}(y, x), \quad E_{k}(x, \lambda y)=E_{k}(\lambda x, y), \quad E_{k}(g x, g y)=E_{k}(x, y) . \tag{2.2}
\end{equation*}
$$

Moreover the following inequality holds

$$
\begin{equation*}
\forall x, y \in \mathbb{R}^{d}, \quad\left|E_{k}(-i x, y)\right| \leq 1 . \tag{2.3}
\end{equation*}
$$

The Dunkl transform shares many properties with the usual Fourier transform (see [10], [14]). In particular, it is an isomorphism of $\mathcal{S}\left(\mathbb{R}^{d}\right)$ (the Schwartz space) onto itself and its inverse is given by

$$
\mathcal{F}_{k}^{-1}(f)(x)=c_{k}^{-2} \mathcal{F}_{k}(f)(-x)=c_{k}^{-2} \int_{\mathbb{R}^{d}} f(\lambda) E_{k}(i x, \lambda) \omega_{k}(\lambda) d \lambda, \quad x \in \mathbb{R}^{d}
$$

where $c_{k}$ is the Macdonald-Mehta constant (see [12]) given by

$$
\begin{equation*}
c_{k}:=\int_{\mathbb{R}^{d}} e^{-\frac{\|x\|^{2}}{2}} \omega_{k}(x) d x . \tag{2.4}
\end{equation*}
$$

Furthermore, the following Plancherel theorem holds: The transformation $c_{k}^{-1} \mathcal{F}_{k}$ extends uniquely to an isometric isomorphism of $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$ and we have the Plancherel formula:

$$
\begin{equation*}
\forall f \in L^{2}\left(\mathbb{R}^{d}, m_{k}\right), \quad\left\|c_{k}^{-1} \mathcal{F}_{k}(f)\right\|_{L^{2}\left(\mathbb{R}^{d}, m_{k}\right)}=\|f\|_{L^{2}\left(\mathbb{R}^{d}, m_{k}\right)} . \tag{2.5}
\end{equation*}
$$

- The Dunkl translation operators $\tau_{x}, x \in \mathbb{R}^{d}$, are defined on $\mathcal{C}^{\infty}\left(\mathbb{R}^{d}\right)$ by (see [18])

$$
\begin{equation*}
\forall y \in \mathbb{R}^{d}, \quad \tau_{x} f(y)=\int_{\mathbb{R}^{d}} V_{k} \circ T_{z} \circ V_{k}^{-1}(f)(y) d \mu_{x}(z), \tag{2.6}
\end{equation*}
$$

where $T_{x}$ is the classical translation operator given by $T_{x} f(y)=f(x+y)$.
The Dunkl translation operators have the following properties:

$$
\tau_{0} f=f, \quad \tau_{x} f(y)=\tau_{y} f(x), \quad \tau_{x}\left(\Delta_{k} f\right)=\Delta_{k}\left(\tau_{x} f\right), \quad \tau_{x} E_{k}(., z)(y)=E_{k}(x, z) E_{k}(y, z) .
$$

Note that if $f \in \mathcal{S}\left(\mathbb{R}^{d}\right)$, the function $\tau_{x} f \in \mathcal{S}\left(\mathbb{R}^{d}\right)$ and it can be defined by means of the Dunkl transform as follows (see [18]):

$$
\begin{equation*}
\tau_{x} f(y)=\mathcal{F}_{k}^{-1}\left[E_{k}(i x, .) \mathcal{F}_{k}(f)\right](y)=c_{k}^{-2} \int_{\mathbb{R}^{d}} \mathcal{F}_{k}(f)(\lambda) E_{k}(i x, \lambda) E_{k}(i y, \lambda) \omega_{k}(\lambda) d \lambda, \quad y \in \mathbb{R}^{d} . \tag{2.7}
\end{equation*}
$$

For $x \in \mathbb{R}^{d}$, the operator $\tau_{x}$ can be extended to the space $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$ as follows: Fix $f \in L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$. Since $\left|E_{k}(-i x, \xi)\right| \leq 1$, the function $\xi \mapsto E_{k}(i x, \xi) \mathcal{F}_{k}(f)(\xi)$ belongs to $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$. Hence, by Plancherel theorem, there exists a unique $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$-function denoted by $\tau_{x} f$ and called the $x$-Dunkl translate function of $f$ such that

$$
\begin{equation*}
\mathcal{F}_{k}\left(\tau_{x} f\right)(\xi)=E_{k}(i x, \xi) \mathcal{F}_{k}(f)(\xi) \tag{2.8}
\end{equation*}
$$

For more properties on Dunkl translation operators when they act on $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$ we can see ([16]).

### 2.2 The harmonic kernel

In this section we recall some results of [7].
Let $(r, x, y) \mapsto h_{k}(r, x, y)$ be the harmonic kernel defined by (1.4). It satisfies the following properties (see [7]):

1. For all $r>0$ and $x, y \in \mathbb{R}^{d}, 0 \leq h_{k}(r, x, y) \leq 1$.
2. For all fixed $x, y \in \mathbb{R}^{d}$, the function $r \longmapsto h_{k}(r, x, y)$ is right-continuous and non decreasing on $] 0,+\infty[$.
3. For all $r>0, x, y \in \mathbb{R}^{d}$ and $g \in W$, we have

$$
\begin{equation*}
h_{k}(r, x, y)=h_{k}(r, y, x) \quad \text { and } \quad h_{k}(r, g x, y)=h_{k}\left(r, x, g^{-1} y\right) . \tag{2.9}
\end{equation*}
$$

4. For all $r>0$ and $x \in \mathbb{R}^{d}$, we have

$$
\begin{equation*}
\left\|h_{k}(r, x, .)\right\|_{k, 1}:=\int_{\mathbb{R}^{d}} h_{k}(r, x, y) \omega_{k}(y) d y=m_{k}(B(0, r))=\frac{d_{k} r^{d+2 \gamma}}{d+2 \gamma}, \tag{2.10}
\end{equation*}
$$

where $d_{k}$ is the constant

$$
d_{k}:=\int_{S^{d-1}} \omega_{k}(\xi) d \sigma(\xi)=\frac{c_{k}}{2^{d / 2+\gamma-1} \Gamma(d / 2+\gamma)} .
$$

Here $d \sigma(\xi)$ is the surface measure of the unit sphere $S^{d-1}$ of $\mathbb{R}^{d}$ and $c_{k}$ is the Macdonald-Mehta constant (2.4).
5. The harmonic kernel satisfies the following geometric inequality: if $\|a-b\| \leq 2 r$ with $r>0$, then

$$
\forall \xi \in \mathbb{R}^{d}, \quad h_{k}(r, a, \xi) \leq h_{k}(4 r, b, \xi)
$$

(see [7], Lemma 4.1). In the classical case (i.e. $k=0$ ), this inequality says that if $\|a-b\| \leq 2 r$, then $B(a, r) \subset B(b, 4 r)$.
6. Let $r>0$ and $x \in \mathbb{R}^{d}$. Then the function $h_{k}(r, x,$.$) is upper semi-continuous on \mathbb{R}^{d}$.

Note that to prove the upper semi-continuity of $h_{k}(r, x,$.$) , with r>0$ and $x \in \mathbb{R}^{d}$, the authors of $[7]$ have constructed a decreasing sequence $\left(\varphi_{\varepsilon}\right) \subset \mathcal{D}\left(\mathbb{R}^{d}\right)$ of radial functions such that for every $\varepsilon>0,0 \leq \varphi_{\varepsilon} \leq 1, \varphi_{\varepsilon}=1$ on $B(0, r)$ and for all $y \in \mathbb{R}$

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \varphi_{\varepsilon}(y)=\mathbf{1}_{B(0, r)}(y), \quad h_{k}(r, x, y)=\lim _{\varepsilon \rightarrow 0} \tau_{-x} \varphi_{\varepsilon}(y), \tag{2.11}
\end{equation*}
$$

where $\tau_{x}$ is the $x$-Dunkl translation operator.
In order to prove our result, we will need two lemmata. But, at first, we start by the following remark:

Remark 2.1 Let $r>0$. The function $\mathbf{1}_{B(0, r)}$ is in $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$. For $x \in \mathbb{R}^{d}$, we can then define $\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)$ as being the $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$-function whose Dunkl transform is equal to

$$
\begin{equation*}
\mathcal{F}_{k}\left(\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)\right)(\xi)=E_{k}(-i x, \xi) \mathcal{F}_{k}\left(\boldsymbol{1}_{B(0, r)}\right)(\xi) . \tag{2.12}
\end{equation*}
$$

(see (2.8)). This $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$-function (which coincides also with $\mathbf{1}_{B(x, r)}$ when $k=0$ ) has been used formally in ([16] and [1]) for studying the $L^{p}\left(\mathbb{R}^{d}, m_{k}\right)$-boundedness of the Dunkl-Hardy-Littlewood maximal operator. In the next result, we will show that this function coincides almost everywhere with $h_{k}(r, x,$.$) . But, in contrast to the harmonic kernel, the$ $L^{2}$-definition (2.12) of the function $\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)$ does not give any precision neither on its support nor on some geometric properties like the geometric inequality mentioned above.

Lemma 2.1 Let $r>0$ and $x \in \mathbb{R}^{d}$. Then, for almost every $y \in \mathbb{R}^{d}$, we have

$$
\begin{equation*}
h_{k}(r, x, y)=\tau_{-x}\left(\boldsymbol{1}_{B(0, r)}\right)(y) . \tag{2.13}
\end{equation*}
$$

Proof: We consider the sequence $\left(\varphi_{\varepsilon}\right)$ as in (2.11). By the monotone convergence theorem, we can see that $\tau_{-x} \varphi_{\varepsilon} \longrightarrow h_{k}(r, x,$.$) in L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$.
On the other hand, since $\mathbf{1}_{B(0, r)} \in L_{k}^{2}\left(\mathbb{R}^{d}\right)$, we have

$$
\begin{aligned}
\left\|\tau_{-x} \varphi_{\varepsilon}-\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)\right\|_{L_{k}^{2}\left(\mathbb{R}^{d}\right)} & =c_{k}^{-1}\left\|\mathcal{F}_{k}\left[\tau_{-x} \varphi_{\varepsilon}\right]-\mathcal{F}_{k}\left[\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)\right]\right\|_{L_{k}^{2}\left(\mathbb{R}^{d}\right)} \\
& =c_{k}^{-1}\left\|E_{k}(-i x, .) \mathcal{F}_{k}\left[\varphi_{\varepsilon}\right]-E_{k}(-i x, .) \mathcal{F}_{k}\left[\mathbf{1}_{B(0, r)}\right]\right\|_{L_{k}^{2}\left(\mathbb{R}^{d}\right)} \\
& \leq c_{k}^{-1}\left\|\mathcal{F}_{k}\left[\varphi_{\varepsilon}\right]-\mathcal{F}_{k}\left[\mathbf{1}_{B(0, r)}\right]\right\|_{L_{k}^{2}\left(\mathbb{R}^{d}\right)} \\
& =\left\|\varphi_{\varepsilon}-\mathbf{1}_{B(0, r)}\right\|_{L_{k}^{2}\left(\mathbb{R}^{d}\right)} \longrightarrow 0 \quad \text { as } \quad \varepsilon \rightarrow 0
\end{aligned}
$$

where we have used Plancherel formula (2.5) for Dunkl's transform in the first and the last lines, the relations (2.7) and (2.12) in the second line, the inequality $\left|E_{k}(-i x, \xi)\right| \leq 1$ in the third line and the monotone convergence theorem in the last line.
Thus, we get $\left(\tau_{-x} \varphi_{\varepsilon}\right)$ converges also to $\tau_{-x}\left(\mathbf{1}_{B(0, r)}\right)$ in $L^{2}\left(\mathbb{R}^{d}, m_{k}\right)$. This proves the desired equality.

Our second lemma, proved in [7], says that
Lemma 2.2 Let $x \in \mathbb{R}^{d}$. Then the family of probability measures

$$
d \eta_{x, r}^{k}(y)=\frac{1}{m_{k}[B(0, r)]} h_{k}(r, x, y) \omega_{k}(y) d y
$$

is an approximation of the Dirac measure $\delta_{x}$ as $r \longrightarrow 0$. More precisely

1. For all $\alpha>0, \lim _{r \rightarrow 0} \int_{\|x-y\|>\alpha} d \eta_{x, r}^{k}(y)=0$.
2. Let $\Omega \subset \mathbb{R}^{d}$ be a $W$-invariant open set, $f$ a locally bounded measurable function defined on $\Omega$ and $x \in \Omega$. If $f$ is continuous at $x$, then

$$
\begin{equation*}
\lim _{r \rightarrow 0} \int_{\mathbb{R}^{d}} f(y) d \eta_{x, r}^{k}=\lim _{r \rightarrow 0} M_{B}^{r}(f)(x)=f(x) \tag{2.14}
\end{equation*}
$$

## 3 Proof of the result

Firstly, we will show the result when the $W$-invariant open set $\Omega$ is the whole space $\mathbb{R}^{d}$.
Theorem 3.1 Let $f \in L_{\text {loc }}^{1}\left(\mathbb{R}^{d}, m_{k}\right)$. Then, for almost every $x \in \mathbb{R}^{d}$, the relation (1.6) holds.

To prove this theorem, we will use the weak- $L^{1}\left(\mathbb{R}^{d}, m_{k}\right)$ estimates of the Dunkl-HardyLittlewood maximal function (see [1] and [16]). This idea has been taken from the classical case (see [15]).
Proof: Step 1: Suppose that $f$ is a continuous function on $\mathbb{R}^{d}$. In this case, the result follows immediately from the relation (2.14).
Step 2: We will prove the result when $f \in L^{1}\left(\mathbb{R}^{d}, m_{k}\right)$. To do this, it suffices to show that

$$
f^{*}(x):=\lim \sup _{r \rightarrow 0} M_{B}^{r}(|f-f(x)|)(x)=0
$$

for almost every $x \in \mathbb{R}^{d}$.

- At first, we claim that there exists a constant $C>0$ such that

$$
\begin{equation*}
\forall t>0, \quad m_{k}\left\{f^{*}>t\right\}:=m_{k}\left\{x \in \mathbb{R}^{d}, \quad f^{*}(x)>t\right\} \leq \frac{C}{t}\|f\|_{L_{k}^{1}\left(\mathbb{R}^{d}\right)} . \tag{3.1}
\end{equation*}
$$

Indeed, we have

$$
\begin{equation*}
f^{*}(x) \leq \sup _{r>0} M_{B}^{r}(|f-f(x)|)(x) \leq M_{k}(|f|)(x)+|f(x)|, \tag{3.2}
\end{equation*}
$$

where $M_{k}(g)$ is the maximal function of $g \in L^{1}\left(\mathbb{R}^{d}, m_{k}\right)$ defined by

$$
M_{k}(g)(x):=\sup _{r>0} \frac{1}{m_{k}(B(0, r))}\left|\int_{\mathbb{R}^{d}} g(y) \tau_{-x}\left(1_{B(0, r)}\right)(y) \omega_{k}(y) d y\right|
$$

(see [16] and [1]). We notice that from (2.13) and (1.2), we have

$$
M_{k}(|f|)(x)=\sup _{r>0} M_{B}^{r}(|f|)(x),
$$

which justifies (3.2). Consequently,

$$
\left\{f^{*}>t\right\} \subset\left\{M_{k}(|f|)+|f|>t\right\} \subset\left\{M_{k}(|f|)>t / 2\right\} \cup\{|f|>t / 2\} .
$$

This implies that

$$
\begin{equation*}
m_{k}\left\{f^{*}>t\right\} \leq m_{k}\left\{M_{k}(|f|)>t / 2\right\}+m_{k}\{|f|>t / 2\} . \tag{3.3}
\end{equation*}
$$

From ([16] or [1]), there exists a constant $C_{1}>0$ such that

$$
\begin{equation*}
m_{k}\left\{M_{k}(|f|)>t / 2\right\} \leq \frac{2 C_{1}}{t}\|f\|_{L^{1}\left(\mathbb{R}^{d}, m_{k}\right)} \tag{3.4}
\end{equation*}
$$

and from Markov's inequality, we have

$$
\begin{equation*}
m_{k}\{|f|>t / 2\} \leq \frac{2}{t}\|f\|_{L^{1}\left(\mathbb{R}^{d}, m_{k}\right)}, \tag{3.5}
\end{equation*}
$$

Then we deduce (3.1) from (3.3), (3.4) and (3.5) with $C=2 C_{1}+2$.

- Let $\varepsilon>0$ and let $g \in \mathcal{D}\left(\mathbb{R}^{d}\right)$ such that $\|f-g\|_{L^{1}\left(\mathbb{R}^{d}, m_{k}\right)} \leq \varepsilon$. For every $x \in \mathbb{R}^{d}$, step 1 applied to the function $y \longmapsto|g(y)-g(x)|$ shows that $g^{*}(x)=0$. This implies that $(f-g)^{*} \leq f^{*}+g^{*}=f^{*}$. Since $f^{*}=(f-g+g)^{*} \leq(f-g)^{*}+g^{*}=(f-g)^{*}$, we get $f^{*}=(f-g)^{*}$. Consequently, by (3.1) we obtain

$$
m_{k}\left\{f^{*}>t\right\}=m_{k}\left\{(f-g)^{*}>t\right\} \leq \frac{C}{t}\|f-g\|_{L^{1}\left(\mathbb{R}^{d}, m_{k}\right)}=\frac{C}{t} \varepsilon .
$$

As $\varepsilon>0$ is arbitrary, this proves that

$$
\forall t>0, \quad m_{k}\left\{f^{*}>t\right\}=0 .
$$

Finally, since

$$
\left\{f^{*}>0\right\}=\cup_{n \geq 1}\left\{f^{*}>1 / n\right\},
$$

we deduce that $m_{k}\left\{f^{*}>0\right\}=0$. That is $f^{*}=0$ a.e. as desired.
Step 3: Let $f \in L_{l o c}^{1}\left(\mathbb{R}^{d}, m_{k}\right)$. For every $n \in \mathbb{N} \backslash\{0\}$, the function $f_{n}=f \mathbf{1}_{B(0, n)}$ is in $L^{1}\left(\mathbb{R}^{d}, m_{k}\right)$. By Step 2, we have $f_{n}{ }^{*}(x)=0$ for all $x \in \mathbb{R}^{d} \backslash E_{n}$, where $E_{n}$ is a measurable set such that $m_{k}\left(E_{n}\right)=0$.
We will prove that $\left\{f^{*}>0\right\} \subset \cup_{n \geq 1} E_{n}$ which will imply the desired result.
Let $x \in \mathbb{R}^{d}$ such that $f^{*}(x)>0$. There is an integer $n=n_{x} \in \mathbb{N} \backslash\{0\}$ such that $\operatorname{supp} h_{k}(r, x,.) \subset B(0, n)$ for every $r \leq 1$. This implies that $f^{*}(x)=f_{n}{ }^{*}(x)>0$. That is $x \in E_{n}$. This completes the proof.

Now, we will prove our result that we recall below

Corollary 3.1 Let $\Omega \subset \mathbb{R}^{d}$ be a $W$-invariant open set. If $f \in L_{l o c}^{1}\left(\Omega, m_{k}\right)$, then (1.6) holds for almost every $x \in \Omega$.

Proof: Let $n \in \mathbb{N}$ large enough such that

$$
\Omega_{\frac{1}{n}}:=\{x \in \Omega, \quad \operatorname{dist}(x, \partial \Omega)>1 / n\}=\{x \in \Omega, \quad B(x, 1 / n) \subset \Omega\}
$$

is a nonempty set. For such $n$, we consider $O_{n}:=B_{o}(0, n) \cap \Omega_{\frac{1}{n}}$ and $K_{n}=\overline{O_{n}}$, where $B_{o}(a, r)$ is the open ball centered at $a \in \mathbb{R}^{d}$ and with radius $r>0$.
As $\Omega_{\frac{1}{n}}$ is $W$-invariant, we can see that $O_{n}\left(\right.$ resp. $\left.K_{n}\right)$ is a $W$-invariant open (resp. $W$ invariant compact) subset of $\Omega$. Moreover, we have for every $n$ large enough

$$
K_{n} \subset O_{n+1} \subset K_{n+1} \quad \text { and } \quad \Omega=\cup_{n} K_{n}=\cup_{n} O_{n}
$$

Now, let $f_{n}$ be the function given by $f_{n}(x)=f(x)$ if $x \in K_{n}$ and $f_{n}(x)=0$ if $x \in \mathbb{R}^{d} \backslash K_{n}$. Clearly $f_{n}$ belongs to $L_{l o c}^{1}\left(\mathbb{R}^{d}, m_{k}\right)$ and by Theorem 3.1 we have $f_{n}(x)=\lim _{r \rightarrow 0} M_{B}^{r}\left(f_{n}\right)(x)$ for almost every $x \in \mathbb{R}^{d}$.
Let
$E_{n}:=\left\{x \in \mathbb{R}^{d}, \quad f_{n}(x) \neq \lim _{r \rightarrow 0} M_{B}^{r}\left(f_{n}\right)(x)\right\} \quad$ and $\quad E:=\left\{x \in \Omega, \quad f(x) \neq \lim _{r \rightarrow 0} M_{B}^{r}(f)(x)\right\}$.
Since $f_{n}$ is continuous on the open set $\mathbb{R}^{d} \backslash K_{n}$, by (2.14) we deduce that $E_{n} \subset K_{n} \subset \Omega$. Let us now take $x \in E$. There exist $R>0$ and $N \in \mathbb{N}$ such that $B(x, R) \subset O_{N} \subset K_{N+1} \subset \Omega$. We will show that $x \in E_{N+1}$. As $O_{N}$ and $K_{N+1}$ are invariant under the action of the Coxeter-Weyl group $W$ and thanks to the support property of the function $h_{k}(r, x,$.$) we$ have

$$
\forall r \in] 0, R], \quad \operatorname{supp} h_{k}(r, x, .) \subset O_{N} \subset K_{N+1}
$$

But $f=f_{N+1}$ on $O_{N}$. Therefore, if $x \notin E_{N+1}$ i.e. $f_{N+1}(x)=\lim _{r \rightarrow 0} M_{B}^{r}\left(f_{N+1}\right)(x)$, then $f(x)=\lim _{r \rightarrow 0} M_{B}^{r}(f)(x)$ and $x \notin E$, a contradiction.
Thus $x \in E_{N+1}$. This proves that $E \subset \cup_{n} E_{n}$ and $E$ is a negligible set as desired.
By taking $f$ the characteristic function of a measurable set $E \subset \mathbb{R}^{d}$, we obtain
Corollary 3.2 Let $E \subset \mathbb{R}^{d}$ be a measurable set and $x \in \mathbb{R}^{d}$. Then for almost every $x \in E$ we have

$$
\frac{\left\|h_{k}(r, x, .)\right\|_{L^{1}\left(E, m_{k}\right)}}{\left\|h_{k}(r, x, .)\right\|_{L^{1}\left(\mathbb{R}^{d}, m_{k}\right)}} \longrightarrow 1 \quad \text { as } \quad r \rightarrow 0
$$

When $k=0$, the previous result takes the following form: for almost every $x \in E$ we have

$$
\frac{m_{0}(E \cap B(x, r))}{m_{0}(B(x, r))} \longrightarrow 1 \quad \text { as } \quad r \rightarrow 0
$$

where $m_{0}$ is the Lebesgue measure on $\mathbb{R}^{d}$. In this case, the point $x$ is called of Lebesgue density of $E$ (see [15]).

## References

[1] L. Deleaval. Two results on the Dunkl maximal function. Studia Mathematica, 203, (2011), 47-68.
[2] C. F. Dunkl. Differential-difference operators associated to reflection groups. Trans. Amer. Math. Soc., 311, (1989), 167-183.
[3] C. F. Dunkl. Integral kernels with reflection group invariance. Canad. J. Math., 43, (1991), 123-183.
[4] C. F. Dunkl. Hankel transforms associated to finite reflection groups. Contemp. Math., 138, (1992), 123-138.
[5] C. F. Dunkl and Y. Xu. Orthogonal Polynomials of Several variables. Cambridge Univ. Press (2001).
[6] L. Gallardo and C. Rejeb. Propriétés de moyenne pour les fonctions harmoniques et polyharmoniques au sens de Dunkl. C. R. Acad. Sci. Paris, Volume 353, Issue 2, (2015), 105-109 .
[7] L. Gallardo and C. Rejeb. A new mean value property for harmonic functions relative to the Dunkl-Laplacian operator and applications. Trans. Amer. Math. Soc., 368 (2016), 3727-3753.
[8] L. Gallardo and C. Rejeb. Support properties of the intertwining and the mean value operators in Dunkl's analysis. Submitted. hal-01331693
[9] J. E. Humphreys. Reflection groups and Coxeter groups. Cambridge Studies in Advanced Mathematics 29, Cambridge University Press, (1990).
[10] M. F. de Jeu. The Dunkl transform. Invent. Math., 113, (1993), 147-162.
[11] R. Kane. Reflection Groups and Invariant Theory. CMS Books in Mathematics. Springer-Verlag, New York, (2001).
[12] E. M. Opdam. Dunkl operators, Bessel functions and the discriminant of a finite Coxeter group. Compositio Math. 85 (1993), no. 3, 333-373.
[13] M. Rösler. Positivity of Dunkl's intertwining operator. Duke Math. J., 98, (1999), 445-463.
[14] M. Rösler. Dunkl Operators: Theory and Applications. Lecture Notes in Math., vol.1817, Springer Verlag (2003), 93-136.
[15] E. M. Stein and R. Shakarchi. Real Analysis: Measure Theory, Integration and Hilbert Spaces. Princeton University Press, (2005).
[16] S. Thangavelu and Y. Xu. Convolution operator and maximal function for Dunkl transform. J. Anal. Math. Vol. 97, (2005), 25-56.
[17] K. Trimèche. The Dunkl intertwining operator on spaces of functions and distributions and integral representation of its dual. Integ. Transf. and Spec. Funct., 12(4), (2001), 394-374.
[18] K. Trimèche. Paley-Wiener theorem for the Dunkl transform and Dunkl translation operators. Integ. Transf. and Spec. Func. 13, (2002), 17-38.


[^0]:    *Université de Tunis El Manar, Faculté des Sciences de Tunis, Laboratoire d'Analyse Mathématiques et Applications LR11ES11, 2092 El Manar I, Tunis, Tunisie and Laboratoire de Mathématiques et Physique Théorique CNRS-UMR 7350, Université de Tours, Campus de Grandmont, 37200 Tours, FRANCE; Email: chaabane.rejeb@gmail.com

