Wireless service provider selection and bandwidth resource allocation in multi-tier HCNs
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Abstract—In this work, the inter-linked problems of wireless service provider (WSP) selection by users and bandwidth allocation by WSPs in multi-tier heterogeneous cellular networks (HCNs) are addressed. This paper employs the approach combining stochastic geometry and game theory to solve these problems. Particularly, the expected average achievable rate for each user is calculated by modeling the distributions of users and base stations (BSs) as independent homogeneous Poisson Point Process (PPP) and a hierarchical game framework is presented to investigate the interactions among users and WSPs. In this framework, the evolutionary game, non-cooperative game and multi-leader multi-follower Stackelberg game models are adopted to formulate the competition among users, competition among WSPs and interaction among users and WSPs, respectively. Moreover, for the formulated evolutionary game, the evolutionary equilibrium (EE) was investigated and its asymptotically stability was analyzed after deriving its closed form expression. Then, conditioned on the obtained EE, a non-cooperative spectrum bandwidth allocation game (N-BAG) has been formulated to investigate the bandwidth allocation of WSPs. The existence of Nash equilibrium (NE) for N-BAG has been proven and an offline algorithm to achieve the equilibrium state was proposed. Finally, simulation results verify the validity of the analysis and demonstrate that a unique NE would be achieved by the HCNs adopting the proposed scheme.

Index Terms—Heterogeneous cellular networks (HCNs), operator selection, bandwidth allocation, evolutionary game, evolutionary equilibrium (EE).

I. INTRODUCTION

A. Motivation

Heterogeneous cellular networks (HCNs) are regarded as a promising approach to cater for the increased demand of high-data-rate services and requirement of ubiquitous access. Augmenting an existing macro-cell covered by a large BS by deploying small coverage cellular networks with high density can potentially dramatically increase the network capacity without incurring a high operation cost [1]–[4]. In this light, the multi-tier HCN is a novel network structure for the future. Particularly, in contrast to the traditional pure macro cellular network, the HCN would consist of high power macro BSs (MBSs) as well as various classes of low power nodes, which may include micro BSs (often called eNBs), pico BSs (PBS), femto BSs (FBSs), and possibly future radiating elements [5].

While deploying such an HCN, it is essential to analyze the system-level performance and investigate the impact of different system parameters to obtain some design insights. Hence, analytically tractable models would be of great interest in this scenario. In contrast to the hexagonal grid model widely applied to evaluate traditional well-planned single-tier cellular networks, an alternate approach based on stochastic geometry was recently proposed, with which the transmitting nodes (e.g., BSs) are modeled as randomly located points through a Poisson point process (PPP) [5]. Compared to the femto-cells which may be randomly deployed, it seems somewhat counter-intuitive to model macro cellular networks as a PPP. However, the accuracy of this tractable model has been verified through empirical validation in recent works like [6]. To this end, based on such a tractable, yet reasonable assumption that BSs are distributed according to independent PPPs, the performance of HCNs can be efficiently studied.

This work studies the interactions between the users and the wireless service providers (WSPs) in an environment where HCNs are deployed by different WSPs. Each WSP determines the bandwidth allocation for each service while the users decide which WSP to subscribe to. Naturally, as each user and WSP are independent decision makers, this results in a situation best modeled through game theory.

B. Related works

The signal-to-interference-plus-noise-ratio (SINR) as well as other system key performance indexes (KPIs), e.g., coverage probability and throughput, have been analyzed in studies [7]–[9]. On top of such stochastic geometry based performance analysis, some efficient spectrum resource allocation strategy have been proposed for heterogeneous wireless networks with the dedicated-channel deployment [10]–[13]. Specifically, in [10], [11] a two-tier heterogeneous network was considered where the disjoint spectrum resources were allocated to different tiers to eliminate cross-tier interference and its optimal spectrum allocation strategy was investigated. Authors in [12] focused on the HCN consisting of macrocells and femtocells, and studied the optimal spectrum allocation strategy for both the open and closed access modes. Although only the specific case of two-tiers was studied, some analysis results obtained in [12] can also be generalized to multi-tier HCNs. The spectrum partition and user association were jointly studied for multi-tier HCNs in [13], where the cell range expansion scheme was adopted for load balancing. Besides these works, the service selection as well as bandwidth allocation for the two-tier femtocell network has also been studied from the economic perspective in [14].
In all the above mentioned works [10]–[14], they have the common point in that they only consider the case where there only exist one WSP deploying all the tiers of networks, i.e., a monopoly. However, in practice there are generally multiple WSPs coexisting, who would deploy their own individual HCNs and hence have to compete with each other to attract more users for higher revenue. As a mathematical tool for analyzing the the conflict and cooperation among autonomous agents, game theory [15] has been widely adopted to formulate and study the interactions among service operators [16]–[22]. Wherein, some of these works have also focused on the HCN based scenarios [20]–[22]. Nevertheless, the major differences between these studies and ours are two fold: (i) the type of HCN considered in [20]–[22] is different to that studied in ours and previous studies [7]–[13]. Specifically, different tiers have been deployed by different WSPs and each WSP only provides one service to users. Hence, their main concerns are spectrum leasing among different WSPs. Our work however jointly studies the WSP selection of users and spectrum allocation of WSPs. (ii) Beside game theory, the tools from stochastic geometry have also been applied in our work to study the behavior of users as well as WSPs. Compared with the pure game theory based methodology focusing on the deterministic model [20]–[22], the analysis combining game theory and stochastic geometry would provide more design insights to system designers or WSPs. A similar idea has also been adopted by recent reseraches [18] and [23], where the distributed power control and sub-channel selection have been addressed, respectively.

C. Contributions

In order to avoid the cross-tier interference in HCNs, a dedicated-channel deployment can be adopted, with which the orthogonal radio resource will be allocated to different tiers. Though this deployment is sub-optimal from the spectral efficiency standpoint, it is a relative simple approach that can be conveniently implemented in practice [24], [25]. In this case, how to properly split the precious but scarce spectrum bandwidth resources\(^1\) and allocate them to different tiers is one fundamental and important issue directly faced by the WSPs [24], [25]. With a better allocation strategy, the WSP can provide a better quality of service, attract more subscribers (i.e., gain a larger market share) and finally achieve higher revenue.

Here, we consider the scenario consisting of multiple HCNs deployed by different WSPs and each tier favored by a certain population of the users. We think this scenario is practical because, on one hand, competition among multiple WSPs is common in many countries, for instance, Sprint, Verizon as well as AT&T are coexisting in the US. On the other hand, the number of users in the market is large and may change, so from the system-level perspective, it is more sensible to treat them using a statistical method. Furthermore, while a stationary user will prefer to connect to a femto-cell nearby, a highly mobile user would connect to a macro-cell in order to avoid frequent handovers. Thus, on average the total population of users can be divided into parts that prefer each tier of the heterogenous network; each user can select the best WSP for any tier. Besides that, to attract more users and further obtain higher revenue, each WSP needs to decide how to allocate his own available spectrum resource to different tiers by fully considering both the behavior of users and other WSPs. For this reason, there are two levels of competitions and a cyclic dependency having to be addressed, i.e., the competition among users, the competition among WSPs, and the coupling between the behavior of populations of users and WSPs. This makes the spectrum resource partition problem nontrivial.

The main contributions of this work can be summarized as follows.

1) We systematically analyze the average achievable rate can be provided by WSPs with the stochastic geometry based approach. Moreover, we present a hierarchical game framework to investigate the interactions in the multi-tier HCNs. Particularly, in the lower level of the framework we formulate the WSP selection of users as an evolutionary game [27] and meanwhile, in the upper level the competition among different WSPs is modeled as a Non-cooperative spectrum Bandwidth Allocation Game (N-BAG). Additionally, the cyclic dependency between the users and WSPs is studied by applying the multi-leader multi-follower Stackelberg game theory. With the proposed framework, WSPs can capture the equilibrium of users and further guide the deployment of HCNs.

2) For the formulated evolutionary service selection game, we consider the evolutionary equilibrium (EE) as the solution, investigate the uniqueness and get the close form expression of the interior EE. Furthermore, we prove that the interior EE is also the evolutionary stable strategy (ESS) which is asymptotical stable, i.e., when ESS is achieved in the population, a small amount of invaders adopting other strategies instead of the ESS can finally be eliminated.

3) Simulation results show that, compared with the solution brought by other three approaches, when WSPs allocate their own spectrum resources by adopting our proposed strategy, an efficient and fair equilibrium solution can be achieved.

The outline of this paper is as follows. In Section II, the description of system model and formulation of the hierarchical game framework are given. Subsequently, Section III presents the evolutionary WSP selection game and studies its solutions. In Section IV, we present the N-BAG, analyze the existence of Nash equilibrium (NE), and develop an algorithm to obtain the NE for this game. Some numerical simulation results are presented and analyzed in Section V and finally, conclusions are drawn in Section VI.
II. SYSTEM MODEL AND THE HIERARCHICAL GAME FRAMEWORK

In this work, we consider an area of interest where a total of $K$ different service would be provided to users (e.g., the macrocell service, picocell service and femtocell service) by $N$ different WSPs having deployed $N$ different HCNs. Additionally, for each HCN $n$, there are $K_n$ tiers, each of which has the BSs of a particular class, such as macrocell BSs (MBSs) or picocell BSs (PBSs). Note that the BSs in different tiers may be differ among each other due to differences in the transmit power, coverage area and spatial density [7], [8]. An illustration of a 3-tier HCN is shown in Fig. 1, where there are three classes of BSs. Also note that the MBS has the largest coverage (i.e., highest transmit power) but the lowest density.

A. Network deployment model

For notational simplicity, we denote the set of WSPs as $\mathcal{N} = \{1, 2, \ldots, N\}$ and meanwhile, for each WSP $n$, we denote the set of the $K_n$ tiers of networks as $\mathcal{K}_n$. Without loss of generality, we consider that $\mathcal{K}_n \subseteq \mathcal{K} = \{1, 2, \ldots, K\}$, which means different WSPs may like to provide different services to users. For instance, some WSPs may provide macrocell service, picocell service and femtocell service, but some WSPs may only provide the macrocell service. Here, for each HCN $n$, we assume that the BSs in the $k$-th tier are spatially distributed as a two dimensional independent homogeneous Poisson Point Process (PPP) $\Psi_{n,k}$ of density $\lambda_{n,k}$ and transmit at power $P_{n,k}$ per unit of bandwidth, where $k \in \mathcal{K}_n$. Moreover, we consider that the potential users of each service $k$ are located according to a homogeneous PPP $\Psi^k$ with intensity $\lambda^k$ where $k \in \mathcal{K}$ [10]–[12]. The above assumption indicates that each service is associated to a certain user density. This is explained by the preferences of different kinds of users to different services. For example a highly mobile user population will prefer the macro-cell service in order to avoid regular hand-overs. Of course in practice, the same user can jump from one population set to another, but on an average the population of each set of user types can be assumed to be a constant.

HCNs are operating on the orthogonal spectrum and meanwhile, each WSP $n$ has to properly allocate the available spectrum bandwidth $B_n$ to different tiers, i.e., the WSP deployment framework is adopted [14], [25]. For the HCN operated by WSP $n$, we denote the spectrum bandwidth allocated to tier $k$ by $B_{n,k}$ and the spectrum allocation profile by $\mathbf{B}_n = (B_{n,1}, B_{n,2}, \cdots, B_{n,K_n})$. With the dedicated-channel deployment, there is no cross-tier interference in the HCN, only co-tier interference. In each HCN, the downlink transmission is considered and in the $k$-th tier network deployed by WSP $n$, the signal from each BS to each user experience path loss with the path loss exponent $\alpha_{n,k} > 2$. Rayleigh fading with average power of unity, as well as lognormal shadow fading with mean $\mu_{n,k}$ and standard deviation $\sigma_{n,k}$ in dB.

When providing services to users, let us denote the price charged by WSP $n$ for service $k$ as $C_{n,k}$ which is the fixed access fee having units $\$ per unit of time. We note that pricing for services should consider the combination of many complex factors in practice, e.g., the operation investment of WSPs, the management made by the government, the real consumption level of the concerning country, etc. For easy of exposition, we will set services prices as fixed and focus on the interaction between service selection and resource allocation in the following. On the other hand, each user in a certain population type, picks one out of the $N$ WSPs to get his service. Following previous studies [16], [17], [19], [21], we assume, for simplicity, that each user would churn from one provider to another without incurring any additional cost. In addition, each user is only able to transmit data through one provider to another without incurring any additional cost. In each HCN, the downlink transmission is considered and in the $k$-th tier network deployed by WSP $n$, the signal from each BS to each user experience path loss with the path loss exponent $\alpha_{n,k} > 2$. Rayleigh fading with average power of unity, as well as lognormal shadow fading with mean $\mu_{n,k}$ and standard deviation $\sigma_{n,k}$ in dB.

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III. WSP SELECTION EVOLUTIONARY GAME

When given the resource allocation profiles of WSPs $B = (B_1, B_2, \cdots, B_N)$ where $B_n = (B_{n,k})_{k \in K_n}$ and $B_{n,k} > 0$, $\forall n \in \mathcal{N}$, the expected transmission rate of each user is determined by which WSP he get service from and how many users selecting the same WSP as him. In this section, we formulate the users’ WSP selection behavior as an evolutionary game which is initially used in biology to study the evolution of animal populations, and then later applied in economics to model human behavior [27]. Recently, this mathematical tool has also been adopted to study engineering problems in wireless communications, see [28] and [29] for an example. The main advantage of this tool is that it can be efficient applied to study the dynamics of a large amount of users active for a long duration. Meanwhile, in contrast to some traditional game models [15], [20], [30], there is no requirement that each player in the game is fully rational or that he has global information on the other players. This is the primary motivation behind the use of the evolutionary game formulation in this context. Next, we will first analyze the expected average rate of each user with the stochastic geometry based approach and then present the formulation of the WSP selection game as well as the investigation of the solutions for the formulated game.

A. Expected average user rate

Since different HCNs and tiers operate on orthogonal spectrum bands, we can equally consider the $N$ multi-tier HCNs as $\sum_{n \in \mathcal{N}} K_n$ different single-tier cellular networks when analyzing the quality of provided services. For notational simplicity, we denote these equivalent one-tier cellular networks by set

$$ S = \{ (n, k) | n \in \mathcal{N}, k \in K_n \} \quad (1) $$

where the network with index $s = (n, k) \in S$ represents the $k$-th tier of cells deployed by WSP $n$. In this subsection, we would briefly call one tier of a HCN as one network.

In each network $s$, $\forall s \in S$, the expected achievable rate that can be offered by each cell $R_s$ can be computed by considering a typical user and using the stochastic geometry based approach. According to Slivnyak’s theorem [31], the typical user in each network can be arbitrarily chosen. Therefore, we consider the typical user located at the origin without loss of generality and furthermore, denote the position of the BS associated to the typical user as $y_s^0$. Then, the received power of the typical user from the BS in $y_s^0$ can be expressed as

$$ P \left( y_s^0 \right) = P_s h_s y_s^0 \| \psi_s \|^{-\alpha} = P_s h_s \left( \psi_s \right)^{-\alpha} y_s^0 \|^{-\alpha} \quad (2) $$

where $h_s^0$ and $\psi_s$ represent the effect of Rayleigh fading and that of shadow fading, respectively. Modeling the channel with shadow fading makes that the received power is not exponentially distributed and then, some important and useful conclusions drawn in previous studies, e.g., [6], [8], [32], can not be implemented. Fortunately, as pointed in the recent work of Dhillon and Andrews [33], the long-term shadowing effects can be interpreted as a random displacement of the location of the BS placed according to the original PPP. In this light, we have the following lemma by resorting to Lemma 1 presented in [33].

Lemma 1: For each network $s = (n, k) \in S$, by defining $z_s = (\psi_s)_{\Psi_s} y_s, \forall y_s \in \Psi_s$, we have a new point process $\Psi_s^{(c)} = \left\{ z_s = (\psi_s)_{\Psi_s} y_s, \forall y_s \in \Psi_s \right\}$. Furthermore, the new point process $\Psi_s^{(c)}$ is also a homogeneous PPP whose density is

$$ \lambda_s^{(c)} = \lambda_s E \left( \frac{1}{\psi_s} \right) $$

$$ = \lambda_s \exp \left( \frac{\ln 10 \mu_s}{5} + \frac{1}{2} \left( \frac{\ln 10 \sigma_s}{5} \right)^2 \right) \quad (3) $$
where $\mu_s$ and $\sigma_s$ are the mean and standard deviation of the shadow fading in network $s$, respectively.

Based on Lemma 1 we would consider the equivalent point process $\Psi_s^{(c)}$ instead of the original one $\Psi_s$ thereafter, when analyzing the expected achievable rate $\bar{R}_s$ in network $s$. Meanwhile, in this case it should be noted that the association based on the maximum received power is equal to the one based on minimum distance, i.e., each user will communicate with the closest BS in each networks $s$. For the new point process, let $z^s_0 \in \Psi_s^{(c)}$ denote the position of the BS associated to the typical user located at the origin and then, the SINR at the typical user can be equally expressed as

$$
\gamma_s = \frac{P_s h^s_0 \|z^s_0\|^{-\alpha_s}}{I_s + \sigma_s^2}
$$

$$= \sum_{z^s_1 \in \Psi_s^{(c)} \setminus \{z^s_0\}} \frac{P_s h^s_k \|z^s_1 - z^s_0\|^{-\alpha_k}}{I_s + \sigma_s^2}, \forall S = (n,k) \in S
$$

where $\Psi_s^{(c)} \setminus \{z^s_0\}$ denotes the set of the positions of BSs causing interference to the typical user, and $I_s$ denotes the cumulative interference. Furthermore, the expected achievable rate $\bar{R}_s$ is

$$\bar{R}_s = \mathbb{E}[B_s \log_2(1 + \gamma_s)] = B_s \bar{R}_s^0, \forall S = (n,k) \in S
$$

where $B_s = \frac{B_s}{\pi^2} \bar{R}_s^0 = \mathbb{E}[\ln(1 + \gamma_s)]$ and additionally, the expectation is taken over both the spatial PPP and the fading distribution. Since for a positive random variable $X$ the expectation can be calculated as $\mathbb{E}[X] = \int_{x>0} P(X > x)dx$, we have

$$\bar{R}_s^0 = \int_{r>0} e^{-\pi \lambda_s^{(c)} r^2} \mathbb{E} \left[ \frac{P_s h^s_0}{I_s + \sigma_s^2} \right] 2\pi \lambda_s^{(c)} rdr
$$

$$= \int_{r>0} e^{-\pi \lambda_s^{(c)} r^2} \int_{x>0} P \left[ \ln(1 + \frac{P_s h^s_0}{I_s + \sigma_s^2} - e^{-\alpha_s}) > x \right] dx 2\pi \lambda_s^{(c)} rdr$$

$$= \int_{r>0} e^{-\pi \lambda_s^{(c)} r^2} \int_{x>0} e^{-\alpha_s - \sigma^2 (e^x - 1)} L_I(x) dx 2\pi \lambda_s^{(c)} rdr$$

where (a) follows the fact that the probability density function (PDF) of the distance $\|z^s_2 - z^s_1\|$ is

$$f(r) = e^{-\lambda_s \pi r^2} 2\pi \lambda_s^{(c)} r$$

and (b) follows from the distribution that $h^s_0 \sim \exp(1)$. In addition, $L_I(\omega)$ is the Laplace transform of the PDF of the cumulative interference $I_s$. Recalling the assumptions on the channel model and the expression of $I_s$ in (4), we can get the expression of $L_I(\frac{\alpha_s}{P_s} (e^x - 1))$ as follows [6]

$$L_I(\frac{\alpha_s}{P_s} (e^x - 1)) = \exp \left( -\pi \lambda_s^{(c)} r^2 \int_{u>1} e^u - 1 + u^{\alpha_s/2} du \right)
$$

$$= \exp \left( -\pi \lambda_s^{(c)} r^2 (e^x - 1)^{2/\alpha_s} \int_{v>0} (e^v - 1) - 2/\alpha_s + 1 + v^{\alpha_s/2} dv \right).$$

3This expression is derived based on the assumption that, in each network, the typical user will associate with the closest BS. The detail can be found in [6].

Finally, combining Eq. (6) and (8), we would obtain the expression of the expected achievable rate in a cell of networks $s$, i.e., $\bar{R}_s$, when given the spectrum allocation profile of WSPs $B = (B_1, B_2, \ldots, B_N)$. Moreover, under the assumption that the orthogonal transmission is implemented in each cell, i.e., equal time (and/or frequency) slots are allocated to each user one after another in a round-robin manner, then for each network $s$ the expected average user rate in a cell can be expressed as [8]

$$\bar{R}_{s,u} = \frac{\bar{R}_s}{N_s} = \frac{B^0_s \bar{R}_s^0}{N_s}, N_s = x_s \lambda_s^{(c)} \forall S = (n,k) \in S
$$

where $N_s$ denotes the average number of users per cell in network $s$ and meanwhile, $x_s (s = (n,k))$ represents the probability that one user would get service $k$ from WSP $n$ or equally, the proportion of users choosing WSP $n$ in the population having the requirement of service $k$. In other words, $x_s$ can also be referred as the population share in the evolutionary game, which will be formally defined in following subsection.

### B. Evolutionary game formulation

For the WSP selection of users, the formulated evolutionary game can be formally depicted as follows:

- **Population**: Each set of users requesting one common service is referred to as a population. Hence, there are totally $K$ different populations which can be denoted by the set $\mathcal{K} = \{1, 2, \ldots, K\}$.

- **Strategy space**: For each user in the $k$-th population, he can decide to get the service from which WSP. Therefore, his strategy space can be depicted with the set $A_k = \mathcal{N}_k = \{n | n \in \mathcal{N}, k \in \mathcal{K}_n\}$.

- **Population state**: For an evolutionary game, the proportion of users choosing strategy $a_k \in A_k$, denoted by $x_{a_k}$, is referred to as the population share of strategy $a_k$. Moreover, in each population $k$, the population share of all strategies is termed as a population state, which can be denoted by the vector $x_k = (x_{a_k})_{a_k \in A_k}$. Obviously, we have $x_{a_k} \in [0, 1], \forall a_k \in A_k$, and $\sum_{a_k \in A_k} x_{a_k} = 1$.

Similarly, the population state of the whole $K$ populations can be expressed as $x = (x_1, x_2, \ldots, x_K)$.

- **Payoff function**: The payoff is used to quantify the satisfaction level or fitness of a user adopting a strategy when given the population state. Mathematically speaking, the payoff function of an individual player choosing strategy $a_k$ can be considered as a mapping $\pi_{a_k} : \mathbb{R} \rightarrow \mathbb{R}$. In this work, we depict the payoff function with the following logarithmic function

$$\pi_{a_k} = \ln \left( 1 + \frac{R_{a_k,k}}{C_{a_k,k}} \right) = \ln \left( 1 + \frac{\beta_{a_k,k} \bar{R}_s^0}{\bar{x}_{a_k}} \right)
$$

where $\beta_{a_k,k} = \frac{\lambda_{a_k,k} B_{a_k,k}}{\ln 2 \sigma_{a_k,k}}$. We note that, from the economic perspective, the logarithmic payoff function $\pi = \ln (1 + y)$ can capture both the user’s non-satiation,
i.e., $\frac{d\pi}{dy} > 0$, and risk aversion, i.e., $\frac{d^2\pi}{dy^2} < 0$, properties. Hence, such a function has been widely used in wireless resource allocation to evaluate satisfaction degree of an agent [13], [14]. It is worth noticing that although only the logarithmic function is considered here, the following analysis also holds when other monotonically increasing functions are adopted.

We note that in dynamic evolutionary game theory, as shown above, the population share of each strategy $x_a$ can be interpreted as the current proportion of individuals in the corresponding population using the pure strategy $a$. Meanwhile, the population state $x$ also can be interpreted as a mixed strategy for the corresponding symmetric normal form game and in this case, the population share $x_a \in x$ represents the probability that each individual player uses the pure strategy $a$ [27]. In addition, these two representations of the population state are coincident when the number of players is large.

C. Replicator dynamic

To depict the dynamically learning behavior of users, the replicator dynamic is adopted in this paper, which can be expressed as follows:

$$
\dot{x}_a = \delta x_a (\pi_a (x_a) - \bar{\pi} (x_a))
$$

$$
= \delta x_a \left( \pi_a - \sum_{a_k \in A_k} x_{a_k} \bar{\pi}_{a_k} (x_k) \right), \forall k \in K
$$

(12)

where $\delta > 0$ is the rate of strategy adaption and $\bar{\pi} (x)$ is the average payoff in the population. Under this dynamic in each population, the percentage growth rate of the population share of each strategy is proportional to the excess of the strategy’s payoff over the population’s average payoff. This dynamic could be interpreted biologically as a model of natural selection, and economically as a model of imitation [27]. As shown in the above equation, the dynamics of service selection can be described with $K$ first-order differential equations. Hence, in order to investigate the equilibrium behaviour of users, we consider the solution of this evolutionary dynamic as the fixed point of the differential equations, which is termed as the evolutionary equilibrium (EE) represented by $x^*$. When the population state of the game is at $EE$, then no user would like to change his strategy.

Based on the support, the EE can be mainly divided into two classes, i.e., the boundary EE and interior EE. Particularly, let us consider a EE $x^*$ and denote its support as $supp (x^*) = \{ (a_k, k) | a_k \in A_k, k \in K, x_{a_k}^* > 0, x_{a_k}^* \in \mathbb{R}^+ \}$. If $supp (x^*) = (A_k, k)_{k \in K}$ we say $x^*$ is an interior EE. Otherwise, we term it as a boundary EE. Generally, the class of the achieved EE for each replicator dynamic is determined by the initial state $x(0)$, i.e., $supp (x(0)) = supp (x^*)$. In the concerned problem, we note for the applied replicator dynamic the boundary EE is not stable since any small perturbation will make the system deviate from this boundary state. Hence, in the rest of this paper, we just focus on the interior EE. Furthermore, we have the following theorem.

Theorem 1: For the replicator dynamic shown in Eq. (12), the formulated WSP selection game has an unique interior EE state. Let us denote this EE by $x^*$, and then, each element $x_{a_k}^*$ in $x^*$ can be expressed as

$$
x_{a_k}^* = \frac{\eta_{a_k} B_{a_k} \lambda_{a_k}^*}{\sum_{a_k \in A_k} \eta_{a_k} B_{a_k}}, \forall a_k \in A_k, \forall k \in K
$$

(13)

where $\eta_{a_k, k} = \frac{\lambda_{a_k, k} R_{a_k}}{C_{a_k} R_{a_k}}$. Intuitively, $\eta_{a_k, k}$ can be seen as the cost performance per unit bandwidth of the $k$-th service provided by WSP $a_k$.

Proof: The proof is given in Appendix A. □

Remark 1: From an economic perspective, elements in $x^*$ denote the expected long-term equilibrium of market shares of different services. For instance, the expected market share of each WSP $n$ can be represented as $\frac{\sum_{k \in K, a_k \in N_k, a_k = n} x_{a_k}^*}{\sum_{k \in K, a_k \in N_k} x_{a_k}^*}$.

Therefore, with such statistical results, WSPs can get some insights about the effect of bandwidth allocation on users’ WSP selection and further, appropriately deploy the HCNs.

Besides EE, for an evolutionary game the evolutionary stable strategy (ESS) is another important solution standing for a refinement of NE with interesting features [34]. Particularly, if the NE is reached, no player is willing to unilaterally change his own strategy under the condition that no other players will deviate from the NE. While, if the ESS is archived, then no player would like to adopt another strategy even if there is a small group of players irrationally deviate from the ESS. Next, we formally give the definition of ESS [27].

Definition 1: ESS: We term $\bar{x}$ as an ESS, if for any different population state (or mixed strategy) $x \neq \bar{x}$, there exists some $\varepsilon_x \in (0, 1)$ that for all $x \in (0, \varepsilon_x)$, we have

$$
\bar{\pi} (\bar{x}, (1 - \varepsilon) \bar{x} + \varepsilon x) > \bar{\pi} (x, (1 - \varepsilon) \bar{x} + \varepsilon x)
$$

where $\bar{\pi} (\bar{x}, (1 - \varepsilon) \bar{x} + \varepsilon x)$ and $\bar{\pi} (x, (1 - \varepsilon) \bar{x} + \varepsilon x)$ denote the expected payoff of the group of users having the state (or adopting the mixed strategy) $\bar{x}$ and $x$ given the current population state $(1 - \varepsilon) \bar{x} + \varepsilon x$, respectively.

One intuitive interpretation of the above definition is that if the ESS is achieved in a population, a small amount of invaders adopting other strategy instead of ESS would achieve a lower expected payoff than the incumbent does. To see more interpretations of this definition, the readers are encouraged to see [27] and [35]. For our formulated evolutionary game and the adopted replicator dynamic, an interior ESS is also an asymptotically stable state, which means that it is stable and attracting (Theorem 2.7.1 in [27]). Hence, such a state can be finally reached via evolutionary process with an initial point in some open neighborhood of the asymptotically stable state. The detailed definition about asymptotically stability can be found in Definition 2.5.2 in [27]. Unfortunately, in general there is no guarantee that every EE would be aligned with an ESS. In other words, there is no guarantee that the fixed point of a replicator dynamic is also asymptotically stable.

However, for the interior EE obtained in Theorem 1, we have the following theorem.

Theorem 2: The unique interior EE $x^*$ obtained in Theorem 1 is an ESS and hence, is asymptotically stable for the adopted replicator dynamic.
Proof: This theorem can be proved with the similar method applied in the proof of Theorem 2 of [21] and in that of Theorem 3 of [29]. However, we still present the proof in Appendix B for completeness.

Remark 2: It should be noted that for our concerned WSP selection game, the reason resulting in the mutation from the equilibrium state EE can be intuitively interpreted from many perspectives. On one hand, if we suppose that the formulated game operates in EE \( x^* \) and at that moment, there are some users joining or leaving the market. Then, the evolution state may deviate from the EE, i.e., the mutation is introduced for the equilibrium state. On the other hand, the mutation may also be introduced at some moment when parts of users have accidentally made an irrational decision due to some reasons. Fortunately, as shown in the above theorem, the effect of such a mutation would be eliminated and the EE would be reached again. These comments will be illustrated with simulation results shown in Section VI.

IV. SPECTRUM BANDWIDTH ALLOCATION GAME

In order to obtain a higher market share and revenue, a WSP must properly allocate the available spectrum. Since the spectrum allocation profile may not be frequently adjusted, each WSP should make his decision based on the equilibrium state of the service selection of users, i.e., the EE.\(^4\) Hence, we define the payoff function for the WSP as follows

\[
U_n(B_n, B_{-n}) = \sum_{k \in K_n} U_{n,k} = \sum_{k \in K_n} \lambda_k^* x_{n,k}^* C_{n,k} \tag{14}
\]

where \( B_{-n} = (B_1, \cdots, B_{n-1}, B_{n+1}, \cdots, B_N) \) denotes bandwidth allocation profiles of WSPs other than WSP \( n \).

In addition, \( \eta_{n,k} = \frac{\lambda_k}{C_{n,k}} \), and \( \varphi_{n,k} = \frac{\lambda_k^* \eta_{n,k} C_{n,k}}{\nu_{n,k}} \), \( \forall k \in K_n, \forall n \in N \). We also impose the constraint \( B_{n,k} \geq b \) on each WSP’s bandwidth allocation strategy, where \( b > 0 \) is a positive constant.\(^5\)

As shown in Eq. (14), the payoff of each WSP is determined by both its own bandwidth allocation profile and those of other WSPs. In contrast to the study in the previous section, we assume that each WSP is fully capable of acquiring all the information on HCNs deployed by its competitors (i.e., other operators) [17]–[20], [36], e.g., the BSs densities and transmit powers. Conditioned on this, we can formulate the problem as a Non-cooperative spectrum Bandwidth Allocation Game (N-BAG) and hereafter, the terms WSP and player would be used interchangeably in this section.

\(^4\)This consideration is mainly because in practice, each operator usually makes a long-term decision instead of changing his decision frequently [36].

\(^5\)This \( b \) can be interpreted as a minimum bandwidth allocation required in order to deploy a certain service: \( b = 0 \) leads to a potentially undefined payoff function when \( B_{n,k} = 0 \), \( \forall n \) for any \( k \). So from a mathematical point of view this constraint keeps the function continuous and easier to handle. Note, this extra constraint will be finally removed when designing the spectrum allocation algorithm at the end of this section.

Definition 2: N-BAG: This game can be represented by the tuple

\[
G = \Gamma(N, (\mathbb{B}_n)_{n \in N}, (U_n)_{n \in N}) \tag{15}
\]

Here, \( N \) denotes the set of players which is identical to the WSP set. For each player \( n \), its strategy space \( \mathbb{B}_n \) is defined as the set of available spectrum bandwidth allocation profiles

\[
\mathbb{B}_n = \left\{ B_n \mid B_n = (B_{n,k})_{k \in K_n}, B_{n,k} > b, \sum_{k \in K_n} B_{n,k} = B_n \right\} \tag{16}
\]

Based on Eq. (14), when given a strategy profile

\[
(B_n)_{n \in N} = (B_1, B_2, \cdots, B_N) \in (\mathbb{B}_n)_{n \in N} \tag{17}
\]

the payoff function of each player \( n, n \in N \), can be expressed as

\[
U_n(B_n, B_{-n}) = \sum_{k \in K_n} \frac{\varphi_{n,k} B_{n,k}}{\chi_{n,k}(B_{-n}) + \eta_{n,k} B_{m,k}} \tag{18}
\]

where the term \( \chi_{n,k}(B_{-n}) = \sum_{m \in N_k, m \neq n} \eta_{m,k} B_{m,k} \) depicts the interference caused to player \( n \) from other players.

For a non-cooperative game, NE is the standard solution standing for the equilibrium state, under which no player can unilaterally improve its own payoff by choosing a different strategy [15]. Accordingly, we have the following theorem about the existence of NE for N-BAG.

Theorem 3: For our formulated non-cooperative game N-BAG, there always admits at least one NE under which no WSP would like to unilaterally change his own bandwidth allocation strategy. Furthermore, when given other WSPs’ strategy profile \( B_{-n} \), the best response of WSP \( n, B_n^* = (B_{n,k})_{k \in K_n} \), is unique and can be expressed as

\[
B_n^* = \max \left\{ b \left\{ \frac{\lambda_k^* C_{n,k} \chi_{n,k}(B_{-n})}{\nu_{n,k} \eta_{n,k}} - \frac{\chi_{n,k}(B_{-n})}{\eta_{n,k}} \right\} \right\} \tag{19}
\]

where

\[
\sum_{k \in K_n} \max \left\{ b \left\{ \frac{\lambda_k^* C_{n,k} \chi_{n,k}(B_{-n})}{\nu_{n,k} \eta_{n,k}} - \frac{\chi_{n,k}(B_{-n})}{\eta_{n,k}} \right\} = B_n. \tag{20}
\]

\( \)Proof: The proof is given in C.

Based on the above, an iterative algorithm has been developed to obtain the NE of N-BAG, which is shown in Algorithm 1. Particularly, at the beginning of this algorithm, the starting point will be initialized based on the available bandwidth of each WSP, i.e., \( \sum_{k \in K_n} B_n = B_n, \forall n \in N \). After that, the algorithm goes into a loop. At each iteration \( t \), each WSP \( n \) calculates the optimal Lagrange multiplier \( \nu_n^* \) with (20) and then, updates the best response \( B_n(t) \) by applying (19). Then, the loop will stop when the relative difference of the two optimal solutions obtained after the consecutive iterations (i.e., \( (B_n(t-1))_{n \in N} \) and \( (B_n(t))_{n \in N} \)) is small.
Algorithm 1: Computation of NE \((B^*_n)_{n \in \mathcal{N}}\).

1: **Initialization:** For \(\forall n \in \mathcal{N}\), initialize the starting point \(B_{n,k}(0)\) satisfying \(\sum_{k \in K_n} B_{n,k} = B_n\) and set \(t = 0\).

2: **repeat**

3: \(\text{Set } t = t + 1 \text{ and } B_n(t) = B_n(t - 1).\)

4: for \(n = 1 \text{ to } N \text{ users do}\)

5: Calculate the optimal Lagrange multiplier \(\nu^*_n\) with Eq. (20) and then, update the best response \(B_n(t)\) by applying Eq. (19).

6: **end for**

7: **until** the stop criterion shown in Eq. (21) is satisfied.

8: **For** \(B_{n,k}(t)\) being equal to \(b\) set its value (i.e., \(B_{n,k}(t)\)) and the corresponding payoff \(U_{n,k}(t)\) to 0, \(\forall k \in K_n, \forall n \in \mathcal{N}\).

9: **Set** \(B^*_n = B_n(t)\) and \(U^*_n = \sum_{n \in \mathcal{N}} U_{n,k}(t), \forall n \in \mathcal{N}\). enough. Mathematically speaking, the stopping criterion of Algorithm 1 can be expressed as

\[
\left\| (B_n(t))_{n \in \mathcal{N}} - (B_n(t - 1))_{n \in \mathcal{N}} \right\| < \varepsilon \tag{21}
\]

where \(\| \cdot \|\) denotes a proper vector norm and \(\varepsilon\) is a small positive constant. Finally, the effects the added constraint that \(B_{n,k} \geq b\) would be eliminated with the step in line 8 of the proposed algorithm.

**Remark 3:** It should be noted that given the initial point \((B_n(0))_{n \in \mathcal{N}}\), Algorithm 1 will converge to the unique solution NE \((B^*_n)_{n \in \mathcal{N}}\). Meanwhile, when the initial point changes, the finally achieved solution may be different unless the NE of N-BAG is unique. However based on our extensive simulation results, we conjecture that the NE is unique and hence, the algorithm will converge to the same point irrespective of the starting allocation chosen.

**Remark 4:** From a mathematical perspective, note that this game and the corresponding IWF algorithm proposed is indeed quite similar to the well known IWFA for power allocation [37]. However, a significant difference that makes the problem harder to prove uniqueness of the NE is that, the water level in each service \(k\) for this work are different unlike the uniform water level over channels seen in [37].

Here, we note that the developed algorithm is an offline algorithm. In addition, since we assume that each WSP can acquire the related information of the co-players, this algorithm can be independently implemented by each WSP and will convergence to an NE when given the initial point. Hence, with the finally obtained solution, no WSP has the incentive to deviate from this strategy, i.e., the equilibrium state is achieved. On the other hand, it is worth noting that this algorithm can also be implemented by some neutral institution [38] and the achieved NE based strategy would be informed to each WSP independently, i.e., providing a centralized bandwidth allocation scheme. Due to the fact that each WSP knows he cannot unilaterally improve his own revenue by choosing a strategy different from that suggested by the neutral institution, these suggested strategies will be adopted by these rational WSPs, eventually.

V. SIMULATION RESULTS

To validate the effectiveness of our theoretical analysis, simulations are conducted and the corresponding results are presented in this section. We consider the region where totally \(K = 3\) different services would be provided to users by HCNs, i.e., macrocell service, picocell service and femtocell service, which are labeled by 1, 2, and 3, respectively. Accordingly, the three populations of users are respectively denoted by P1, P2, and P3. Unless specified otherwise, the simulation parameters are adopted as listed in Table I.

**A. EE and ESS for users’ WSP selection**

In this subsection, we illustrate the dynamics of user behavior. There exist three different WSPs each of which offers all the three services to users. We label these WSPs as WSP 1, WSP 2 and WSP 3 and meanwhile, set the densities of BSs deployed by them as \((\lambda_{1,1}, \lambda_{1,2}, \lambda_{1,3}) = (3, 15, 40), (\lambda_{2,1}, \lambda_{2,2}, \lambda_{2,3}) = (2, 40, 30)\) and \((\lambda_{3,1}, \lambda_{3,2}, \lambda_{3,3}) = (1, 10, 60)\). Intuitively, this setting means that the three WSPs respectively have their own appealing service. To see the dynamics of users, we conduct the simulation in a region with 1000 km² and equally, consisting of 20000, 60000, and 100000 users in P1, P2 and P3, respectively. Here, we consider that each WSP would equally allocate the available bandwidth to each tier. During the initialization of this simulation, users in each population would randomly select the available WSPs. After that, they will adopt the pairwise proportional imitation during the evolutionary progress, which means that each user would randomly select an opponent and imitates the opponent only if the opponent’s payoff is higher than his own with probability proportional to the payoff difference [35]. The dynamics of population state and payoff achieved by each user are shown in Fig. 3 and Fig. 4, respectively.

From these two figures, we can see that the EE of formulated evolutionary game can be achieved less than 30 iterations. Meanwhile, as shown in Theorem 2, when this equilibrium state is achieved in each population, all the users will obtain the same payoff no matter getting the service from which WSP. In other words, from the perspective of payoff achieved by each user, the load among WSPs is balanced when EE is reached. In order to further show the asymptotic stability of the EE, we suppose that at the moment that the evolutionary time is 40, in each population there are 20 percent of the users selecting WSP 1 and WSP 2 decide to churn to WSP 3, for example, due to the inaccuracy of obtained information, i.e., the mutation occurs. It can be seen that the payoff achieved by the user selecting WSP 3 is reduced due to the fact that the mutation demolish the load balance among WSPs. However, since the EE is asymptotically stable, the equilibrium state EE would be finally reached again. For this reason, from the long term perspective, it seems plausible for each WSP to evaluate the market and investigate the deployment of his own HCN based on this stable state of users’ behavior.

\(^6\) All the density related parameters have the same units in this section, i.e., the number of BSs or users per km². Hereafter, the units will be omitted for convenience.
TABLE I
DEFAULT SIMULATION PARAMETERS

<table>
<thead>
<tr>
<th>Parameter and description</th>
<th>value</th>
</tr>
</thead>
<tbody>
<tr>
<td>The number of services (the number of user populations), $K$</td>
<td>3</td>
</tr>
<tr>
<td>The number of WSPs, $N$</td>
<td>3</td>
</tr>
<tr>
<td>The available bandwidth for WSP $n$, $\forall n \in \mathcal{N}$</td>
<td>10 MHz</td>
</tr>
<tr>
<td>The densities of users, ${\lambda_1^n, \lambda_2^n, \lambda_3^n}$</td>
<td>$[20, 60, 100]$ per km$^2$</td>
</tr>
<tr>
<td>The transmit power of BS, ${P_{n,1}, P_{n,2}, P_{n,3}}$, $\forall n \in \mathcal{N}$</td>
<td>$[46, 35, 20]$ dBm per 10 MHz</td>
</tr>
<tr>
<td>The price of service, ${C_{n,1}, C_{n,2}, C_{n,3}}$, $\forall n \in \mathcal{N}$</td>
<td>${1, 0.5, 0.2}$</td>
</tr>
<tr>
<td>The AWGN power density, $N_0$</td>
<td>-174 dBm/Hz</td>
</tr>
<tr>
<td>The path-loss exponent, $\alpha$, $\forall k \in \mathcal{K}$, $\forall n \in \mathcal{N}$</td>
<td>4</td>
</tr>
<tr>
<td>The shadow fading mean, ${\mu_{n,1}, \mu_{n,2}, \mu_{n,3}}$, $\forall n \in \mathcal{N}$</td>
<td>${1, 4, 8}$ dB</td>
</tr>
<tr>
<td>The shadow fading standard deviation, $\sigma_{n,k}$, $\forall k \in \mathcal{K}$, $\forall n \in \mathcal{N}$</td>
<td>8 dB</td>
</tr>
<tr>
<td>The required upper accuracy of Algorithm 1, $\varepsilon$</td>
<td>$10^{-3}$</td>
</tr>
</tbody>
</table>

![Fig. 3. The dynamic of population state in the population P1, P2 and P3. To illustrate the asymptotic stability of the EE, the mutation is added in each population at the moment that the evolutionary time is 40.](image)

![Fig. 4. The dynamic of payoff obtained by each user in the population P1, P2 and P3. To illustrate the asymptotic stability of the EE, the mutation is added in each population at the moment that the evolutionary time is 40.](image)

**B. Convergence of Algorithm 1**

In this subsection the convergence of our proposed algorithm, i.e., Algorithm 1, is illustrated by simulations. Here, the required relative accuracy $\varepsilon$ (in Eq. (21)) and the added bandwidth allocation constraint $b$ (in Eq. (32)) are set to $10^{-3}$ and $10^{-5}$ MHz, respectively. Moreover, the densities of BSs are set to the same value as in Section VI-A. To show the uniqueness of NE for the formulated game N-BAG, we run the simulation with 10000 independent realizations of the initial point in our algorithm and for clearly exposition, present 200 results in Fig. 5.\textsuperscript{7} Here, the bandwidth allocation profile at iteration 0 denotes the starting point of the algorithm. As illustrated in the figure, the equilibrium state of N-BAG can be reached after a few iterations, i.e., about 5 iterations. Moreover, we can see that the same strategy would be finally adopted by each individual WSP which does not depend on the initial point. In other words, the NE of the game is unique. Besides that, we notice that for WSP 1, 2 and 3, in order to achieve a higher payoff, they have allocated the most bandwidth to macrocell service, picocell service and...

\textsuperscript{7}Although we have not shown all the 10000 simulation results here, we note that the remain results have shown the same convergence behavior.
C. Performance evaluation

At the beginning of this subsection, we want to show the effects of BSs’ densities on the bandwidth allocation of the WSP. For easy of exposition, we consider two WSPs (WSP 1 and WSP 2) each of which would provide two services (macrocell service and picocell service) to two populations of users (P1 and P2). Here, we suppose that the densities of users in the two populations and those of BSs deployed by WSP 1 are fixed, which are set as \((\lambda_1^1, \lambda_2^1) = (20, 60)\) and \((\lambda_1^2, \lambda_2^2) = (2, 20)\), respectively, while the densities of MBSs and PBSs deployed by WSP 2 (i.e., \(\lambda_2^1\) and \(\lambda_2^2\) vary. According to the changes of \(\lambda_2^1\) and \(\lambda_2^2\), the bandwidth allocated to the macrocell service by WSP 2, \(B_{2,1}\), and his achieved payoff, \(U_2\), are illustrated in Fig. 6 and 7, respectively. In these figures, \(\lambda_2^1\) varies from 1 to 5 and meanwhile \(\lambda_2^2\) varies form 5 to 60. Since \(B_{2,1} + B_{2,2} = B_2\) which is a constant, the results about \(B_{2,2}\) are omitted here for the sake of brevity.

From Fig. 6 it is seen that the densities of MBSs and PBSs have a significant effect on WSP 2’s bandwidth allocation strategy even for the case consisting of two WSPs. More specifically, two observations can be made. On one hand, when given the density of PBS, \(\lambda_2^2\), the bandwidth allocated to macrocell service, \(B_{1,2}\), first increases with respect to the density of MBS \(\lambda_2^1\) and then decreases. Additionally, the threshold is around \(\lambda_2^1 = 2\) which equals to the density of MBSs deployed by WSP 1. The reason is that when \(\lambda_2^1\) is small, in order to attract more users in population P1 and increase his own payoff, WSP 2 has to allocate more bandwidth to macrocell service to improve the competitiveness. However, when \(\lambda_2^1 > \lambda_1^1\) the macrocell service offered by WSP 2 can provide users higher expected achievable rate per bandwidth, i.e., \(R_{2,1}^2 > R_{1,1}^1\). As shown in Theorem 1, this further means that WSP 2 may attract more users in P1 than WSP 1 dose, even WSP 2 allocates less bandwidth to this service. Hence, he can allocate more bandwidth to the second service to further improve the payoff. On the other hand, it is shown that when given \(\lambda_2^1, B_{1,2}\) would first decrease and then increase when \(\lambda_2^2\) gradually becomes larger. The reason resulting in this performance is similar to the one previously stated. Besides that, it is not surprising that the divide in this case appears near to the point that \(\lambda_2^2 = 0\), which is equal to \(\lambda_1^2\). Here we should note that these results are different to those illustrated in [13], where it is shown that the spectrum allocated to some service \(s\) is monotonic increasing with respect to the density.
of the corresponding BSs $\lambda_u$. This difference is mainly caused by the competition among WSPs.

To see the trend of the obtained payoff $U_2$, we can refer to Fig. 7. It should be noted that, in contrast to $B_{2,1}$, the payoff $U_2$ is monotonically increasing with respect to both $\lambda_{2,1}$ and $\lambda_{2,2}$. The reasons can be explained as follows. When deploying more BSs, the WSP will have a higher competitiveness in the market and hence, can attract more users to further improve its own payoff. Additionally, another reason for the monotonically increasing of $U_2$ is due to the fact that the cost for BSs deployment is not taken into account. Otherwise, the trend of $U_2$ would probably first increase and then decrease, since the upper bound of the revenue could be obtained by WSP 2 in the market is fixed, i.e., $\lambda_1^3 C_{2,1} + \lambda_2^3 C_{2,2}$, which appears that when every user chooses to get service from WSP 2.

Finally, we want to compare our algorithm with other three bandwidth allocation schemes which are presented as follows.

- Uniform distribution (UD): With this approach each WSP would equally divide the available bandwidth into sub-bands and allocated them to different tiers.
- Proportion to density of BSs (PDBS): With this approach each WSP would allocate the available bandwidth to each tier based on the density of BSs, i.e.,
  \[ B_{n,k} : B_n,l = \lambda_{n,k} : \lambda_{n,l}, \forall k, l \in \mathcal{K}_n, \forall n \in \mathcal{N}. \]  
  \[ (22) \]
- Proportion to density of users (PDU): With this approach each WSP would allocate the available bandwidth to each tier based on the density of potential users in each population, i.e.,
  \[ B_{n,k} : B_n,l = \lambda_n^u : \lambda_n^l, \forall k, l \in \mathcal{K}_n, \forall n \in \mathcal{N}. \]  
  \[ (23) \]

We note that this scheme is similar to the one proposed in [13], which focuses on the single WSP scenario.

Here, we consider there are three WSPs, each of which deploys a 3-tier HCN with the BS density as $\lambda_{1,k} = 2\lambda_{2,k} = 4\lambda_{3,k}$, where $(\lambda_{3,1}, \lambda_{3,2}, \lambda_{3,3}) = (0.5, 5, 10)$. In addition, the available bandwidth of the three WSPs are set as $(B_1, B_2, B_3) = (20, 10, 5)$ MHz, which means that the bandwidth obtained by each WPS is not the same and may sometimes happen in some practical cases. Based on the different deployment of HCNs, we consider that the price charged by WSPs are also different: $(C_{1,1}, C_{1,2}, C_{1,3}) = (2, 0.8, 0.4), (C_{2,1}, C_{2,2}, C_{2,3}) = (0.8, 0.3, 0.1)$, and $(C_{2,1}, C_{2,2}, C_{2,3}) = (0.3, 0.05, 0.01)$. We evaluate the performance of these schemes in terms of the sum payoff $U = \sum_{n \in \mathcal{N}} U_n$ and Jain’s fairness index, i.e.,

\[ J = \left( \sum_{n \in \mathcal{N}} U_n \right)^2 / \left( N \sum_{n \in \mathcal{N}} (U_n)^2 \right) \]

which are illustrated in Fig. 8 and 9, respectively. While $\lambda_n^u$ varies from 60 to 150 during the simulation, the density of users in P1 and P2 are set according to Table I, i.e., $\lambda_1^u = 20$ and $\lambda_2^u = 60$.

From Fig. 8 we can see that, compared with other three schemes, our proposed algorithm can bring the highest sum payoff to WSPs. For instance, when $\lambda_3^u = 150$ our algorithm yields a performance advantage around 11.8% relative to the scheme PDBS, i.e., from 66.01 to 73.77. The main reason for this improvement mainly lies into the fact that, by formulating the bandwidth allocation problem as a game, the rational WSPs could intelligently allocate the available bandwidth into different tiers fully considering the effects caused by the competition from other WSPs. In addition we can find that the sum payoff achieved by the scheme UD and that by PDU is the same. To explain this, it should be noted that when implementing these two strategies, the ratio of provided bandwidth from different WSPs is the same for a given service, i.e., $B_{1,k} : B_{2,k} : B_{3,k} = 4 : 2 : 1, \forall k \in \mathcal{K}$. Recalling Eq. (14), this further means that a particular WSP $n$ will obtain the same payoff when adopting UD and PDU. To see the fairness we can refer to Fig. 9, which shows that our proposed approach is the fairest one among these four schemes. This is mainly due to the fact both the rationality and individual interest of each WSP can be well considered by resorting to the game theory based formulation. Meanwhile, it is not surprising to see that UD and PDU also have the same performance. The reason is the same as previously described. As a consequence, the simulation results illustrated in these two figures demonstrate that, compared with the scheme UD, PDBS and PDU, the equilibrium solution achieved by Algorithm 1 is efficient as well as fair.
VI. CONCLUSIONS

The users’ wireless service provider (WSP) selection as well as WSPs’ bandwidth allocation in multi-tier heterogeneous cellular networks (HCNs) has been investigated by adopting the approach combining stochastic geometry and game theory. To be more specific, after analyzing the expected average rate for users, the WSP selection of users has been formulated as an evolutionary game. Then, a closed form expression for the EE (which denotes the state of user behavior at equilibrium) and its asymptotic stability has been proven. Based on this analysis, the bandwidth allocation of WSPs as a non-cooperative game has been formulated and the existence of Nash equilibrium (NE) has been proven. Here, an algorithm used to achieve the NE has also been developed. Simulation results have shown the effects of the BSs’ as well as users’ densities on the WSP’s bandwidth allocation decision. In addition, it has also been demonstrated by simulation that, compared with other schemes, an efficient and fair solution would be obtained by implementing our proposed algorithm.

APPENDIX A

PROOF OF THEOREM 1

Proof: Substituting Eq. (11) into Eq. (12), we can equally transform the replicator dynamics of the formulated evolutionary service selection game as Eq. (24). Based on Eq. (24), we note that to get the EE $x^*$ we should make sure that $\dot{x}_{a_k}^* = 0$, $\forall a_k \in A_k, \forall k \in K$. Meanwhile, recalling that $x_{a_k}^* > 0$ ($\forall a_k \in A_k, \forall k \in K$) and $\sum_{a_k \in A_k} x_{a_k} = 1$, we have

$$x_{a_k}^* = \frac{\beta_{a_k,k} \sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}}{\sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}} \forall a_k, \forall \bar{k} \in A_k$$

and

$$\sum_{a_k \in A_k} \frac{\beta_{a_k,k} \sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}}{\sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}} = 1$$

Further, we can get the expression of the EE as

$$x_{a_k}^* = \frac{\sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}}{\sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}} \sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}$$

where $\forall a_k \in A_k, \forall k \in K$.

Then, replacing the term $\sum_{a_k' \in A_k} \beta_{a_k',k} \sum_{a_k'' \in A_k} \beta_{a_k'',k} x_{a_k''}$ by $\eta_{a_k,k}$, we can draw the conclusion shown in Theorem 1.

APPENDIX B

PROOF OF THEOREM 2

Proof: Based on the folk theorem of an evolutionary game, any strict NE corresponds to an ESS [27]. Meanwhile, it is obvious that the solution in Eq. (13) is an equilibrium for the evolution dynamics in Eq. (12), since there is no player who would change his own strategy, i.e., $\dot{x}_s = 0$ for any $s \in S$. Hence, we will prove this theorem by showing the equilibrium $x^*$ is a strict NE. Considering the evolution game operates in EE $x^*$, the payoff obtained by a user selecting service $s$ is

$$\pi_s(x^*) = \ln \left(1 + \frac{\beta_s R^0_s}{\xi_s^2}\right)$$

(31)

as shown in Eq. (11)). In addition, we have $\pi_s(x^*) = \pi_l(x^*)$, $\forall s, l \in S$. Now, suppose that some user (or users) deviates (or deviate) the strategy from $s$ to $l$ where $s \neq l$, and then the population state becomes

$$\bar{x} = (x_1^*, \ldots, x_s^* - \xi, \ldots, x_l^* + \xi, \ldots, x_{|S|}^*)$$

where the constant $\xi > 0$ is determined by the number of users deviating the strategy. In addition, with the deviation from strategy $s$ to $l$, the payoff of the user becomes

$$\pi_l(\bar{x}) = \ln \left(1 + \frac{\beta_l R^0_l}{\xi_l + \xi}\right) < \ln \left(1 + \frac{\beta_s R^0_s}{\xi_s}\right) = \pi_s(x^*)$$

(32)

It follows that $\pi_s(x^*) > \pi_l(\bar{x})$ and further means that the deviating from the equilibrium state will lower the payoff of the user, which satisfies the definition of the strict NE.

Now, the proof is completed.

APPENDIX C

PROOF OF THEOREM 3

Proof: First, we will prove the existence of NE for the formulated game N-BAG. After some algebraic computations we can transform the payoff of WSP $n$ as

$$U_n(B_n, B_{-n}) = \tau_n - \sum_{k \in K_n} \frac{\lambda_k C_{nk} \chi_{nk}(B_{-n})}{\chi_{nk}(B_{-n}) + \eta_{nk} B_{nk}}$$

(33)

where $\tau_n = \sum_{k \in K_n} \frac{x_{nk}}{\eta_{nk}} = \sum_{k \in K_n} \lambda_k C_{nk,k}$. It is easy to prove that the $n$-th player’s payoff $U_n$ is concave over his strategy set $B_n$ for each fixed $B_{-n}$ and meanwhile, the strategy space $(B_n)_{n \in N}$ is a closed and bounded convex set [39]. Therefore, we can know that $G$ is a concave game which always admits at least one NE [40]. We note that this proposition can be proved through three steps. First, when given a strategy profile, it can be proved that the best response of each player is compact and convex which is due to the continuity and concavity of the payoff function. Then, it can be proved that the best response function $\Omega : (B_n)_{n \in N} \rightarrow (B_n)_{n \in N}$ is upper semi-continuous. Finally, by applying Kakutani fixed point theorem, it can be proved that there exists a fixed point $\Omega((B^*_n)_{n \in N}) = (B^*_n)_{n \in N}$. To be more specific, this fixed point $(B^*_n)_{n \in N}$ is a NE for the considered concave game.

Next, we will derive the expression of the best response of WSP $n$ when given the strategy profile of other WSPs $B_{-n}$. In this case, for each player $n$, selecting the strategy maximizing his own payoff is equivalent to solving the following optimal spectrum allocation problem

$$P : \min_{B_n} \sum_{k \in K_n} \frac{\lambda_k C_{nk} \chi_{nk}(B_{-n})}{\chi_{nk}(B_{-n}) + \eta_{nk} B_{nk}}$$

s.t. $B_{nk} \geq b, \forall k \in K_n$, $\sum_{k \in K_n} B_{nk} = B_n$, which is a convex problem. For problem $P$, the lagrangian
\[ \hat{x}_{ak} = \delta x_{ak} \left( \ln \left( 1 + \frac{\beta_{ak,k} R_{ak,k,u}}{x_{ak}} \right) - \sum_{a'_k \in A_k} x_{a'_k} \ln \left( 1 + \frac{\beta_{a'_k,k} R_{a'_k,k,u}}{x_{a'_k}} \right) \right), \forall a_k \in \mathcal{A}_k, \forall k \in \mathcal{N} \]  

(24)

function can be written as

\[ L_n = \sum_{k \in K_n} \frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{(\chi_{n,k}(B_n) + \eta_{n,k}B_n)^2} - \theta_{n,k} + v_n = 0, \]

\[ B_{n,k} \geq b, \sum_{k \in K_n} B_{n,k} = B_n, \]

\[ \theta_{n,k} \geq 0, \theta_{n,k}(B_{n,k} - b) = 0, \forall k \in \mathcal{N}_k. \]

(35)

Since problem \( P \) is a convex problem, the optimal variable \( B^*_n = \left( B^*_{n,k} \right)_{k \in K_n} \) can be achieved by solving the KKT conditions (35), which could be further transformed as

\[ v_n \geq \frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)\eta_{n,k}}{(\chi_{n,k}(B_n) + \eta_{n,k}B_n)^2} = \frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{\chi_{n,k}(B_n)}, \]

the first three conditions in Eq. (36) only hold when

\[ B_{n,k} = \sqrt{\frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{v_n \eta_{n,k}}} \geq \frac{\chi_{n,k}(B_n)}{\eta_{n,k}} \geq b. \]

(37)

or

\[ B_{n,k} = b \sqrt{\frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{v_n \eta_{n,k}} - \frac{\chi_{n,k}(B_n)}{\eta_{n,k}}} < b. \]

(38)

On the other hand, if \( v_n \geq \lambda^k_n C_{n,k} \chi_{n,k}(B_n)\eta_{n,k} \chi_{n,k}(B_n)), then \( B_{n,k} > b > 0 \) and the second condition in Eq. (36) can not be satisfied simultaneously, which further means \( B_{n,k} \) can only equal to \( b \). To this end, the optimal solution \( B^*_n = \left( B^*_{n,k} \right)_{k \in K_n} \) can be expressed as

\[ B^*_{n,k} = \max \left\{ b, \sqrt{\frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{v_n \eta_{n,k}}} - \frac{\chi_{n,k}(B_n)}{\eta_{n,k}} \right\}. \]

Meanwhile, recalling the constraint that \( \sum_{k \in K_n} B_{n,k} = B_n \), we can get the optimal Lagrange multiplier \( v_n \) by solving

\[ \sum_{k \in K_n} \max \left\{ b, \sqrt{\frac{\lambda^k_n C_{n,k} \chi_{n,k}(B_n)}{v_n \eta_{n,k}}} - \frac{\chi_{n,k}(B_n)}{\eta_{n,k}} \right\} = B_n. \]

Finally, we will prove the uniqueness of \( B^*_n \) when given \( B_{n-} \). It should be noted that the left side of the above equation is a piece-wise-linear increasing function of \( \frac{1}{\chi_{n,k}(B_n)} \), hence the solution of this equation is unique when given \( B_{n-} \), which further means that the solution shown in Eq. (19) is also unique in the same case, i.e., given \( B_{n-} \).

Now, we complete the proof.

\[ \square \]

**REFERENCES**


