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WSC-MAC : A Cooperative Mac Protocol for Wireless Sensors Network

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Abstract—This article develops a new Mac layer scheme (WSC-MAC) for Wireless Sensor Network (WSN) which improves the network reliability by using cooperative communication. Our work is focused on a way to define a relay node among the neighborhood of a node, efficiently and with only few signaling messages. We develop a solution based on an automatic forwarder selection and a link state evaluation in order to define the relay node. This automatic selection uses a group identifier uniformly spread in the network and ensures that only few nodes at the time will be chosen as relay. As the sensor nodes switch from active mode to the sleep one, we based our solution on the Long Preamble Emulation (LPE) Mac layer Algorithm which emulates the asynchronous MAC protocol proposed in [13]. Our simulations results show that WSC-MAC increases the overall reliability of the sensor network and adjusts to large variety of node density.

Index Terms - Wireless Sensor Network, MAC Protocol, Cooperative communications, Reliability

I. INTRODUCTION

The motivation of this paper is to fill the gap between cooperative communications technique developed for physical layer and an appropriate MAC layer scheme for Wireless Sensor Networks (WSN). The cooperative radio techniques, also known as Virtual Multiple Input Single Output (VMISO)[9], originate from works using diversity techniques with co-located multiple antennas. Instead of using multiple antennas to take advantage of the channel diversity, the cooperative communication uses multiple nodes equipped with a single antenna and distributed coding scheme to achieve similar gains. The cooperative communication scheme is also inherently a network solution. There are issues at multiple levels of the network stack to solve in order to reach the gain offered by the diversity. This paper mainly focus on finding a good tradeoff between the Mac layer issues and the physical layer performances. We develop a Mac layer scheme that use a distributed algorithm to select a relay node in an efficient way without extra overhead in signaling and processing. The reliability of the communications that use cooperation helps us to design an acknowledgment agnostic solution.

The paper is organized as follows. In section 2, we present the related work. In section 3, we introduce the design of our solution and the specific mechanisms we developed. In section 4, we present performance results and analysis. Finally we summarize our results paper and present some future works.

II. RELATED WORK

A new class of radio diversity techniques named cooperative communication from diversity techniques using co-located antennas has received lot of interests. Laneman et al. [9] and others [2, 6] have developed a set of cooperative communication scheme for distributed wireless network (ad hoc networks or sensors networks). Their respective works have paved the way for a lot of studies using cooperative transmission on a real Mac layer framework. Ji et al. [8] and Lin et al. [10] proposed different frameworks for Cooperative MAC protocol. These solutions are based on network-assisted diversity multiple access (NDMA). These authors present a novel throughput-efficient medium access scheme for WSN. This scheme enables a node to retrieve a packet from many previously received packets (MPR [15]).

Liu et al. proposed the first cooperative MAC protocol called “CoopMac” [11] based on the well known IEEE 802.11 protocol. They defined two alternative solutions CoopMAC I and CoopMAC II. In CoopMAC I, a new frame HTS (Helper ready To Send) is added to the IEEE 802.11, to inform others that an alternative node (a relay node) will help the sender to transmit more efficiently. Then, in CoopMAC II, HTS frame is not used; instead they used the RTS header to advise which node should act as a relay node.

Chou et al. [5] presented a solution to perform cooperative communication in distributed wireless networks. Authors claim that only one relay must participate in the cooperative transmission. They developed mechanisms, in order to select the relay node among its neighbors such as a busy tone and a special RTS (Relay-RTS). This RRTS is used with the classic RTS/CTS mechanism to inform the source and the relay node chosen.

Most of these solutions used extra messages in order to setup the cooperative process and select the relay node. In a WSN context, the resources are limited. The use of these signaling packets should be avoided to reduce the power-consumption.

III. COOPERATIVE COMMUNICATION DESIGN

Cooperative communications is a promising technique that would enhance the design of the wireless sensor networks. In this context, we have to face also new challenges that need to be solved in order to design a fully functional system. One

of these challenges is to find a way to select a relay node that will efficiently forward packets in a cooperative way, in order to reach an improvement on channel capacity. In the following section of this document, we present WSC-MAC, our solution based on an automatic forwarder selection and a Link-state evaluation that let our MAC layer defining some neighbors as relay node.

A. Automatic forwarder selection

Nodes in cooperative network are efficiently using broadcast property of the wireless medium to improve the communication between two nodes by sending a copy of the main communication on the same channel. To reach the trade off between gain brought by the cooperation and the overhead introduced, Fan et al. [7] and Moh et al.[12] show that the best cooperation happens in the case of a few nodes cooperation instead of a multiple-nodes cooperation pattern. Based on this observation we have developed an algorithm that enables the node that want to send a packet to pre-define a small set of relay nodes that will help to forward packets to the destination.

To select some possible relay nodes our algorithm introduces a new ID: a Group Identifier, which is embedded in the sensor. Each time a node want to send a packet, it should first draw a random number among the possible value of Group Identifier, put the result inside the packet header and sends it to the destination. After that, every nodes which listen to the packet on the channel has to check the group identifier included into the packet header. If the group identifier matches with their own predetermined Group Id, a node could become a relay for this communication. Otherwise, the packet will be dropped. As example in figure 1, Node S wants to send a packet to node D. The group identifier draw by the node S is 1, the node R and T which are in that group should now be considered to forwarding the packet.

To set up its own Group Identifier each node picks a random number uniformly distributed between 0 and A , the average number of neighbors in the network calculated as a function of the network size R and the number of nodes. We use group identifier to limit the relay node number of each communication. This identifier will be set up during the network deployment and will be tie to the network topology. In order to avoid any collision, two neighbor nodes must not have the same Group ID. A node may have two neighbors with the same group ID. the auto-configuration process should take into consideration the group ID of its neighbors when it determines its own group ID (cf. Algorithm 1). Algorithm 1 presents the process in order to determine the group identifier of each node. In our algorithm, A_{list} is a list of A available values for group identifier.

B. Link-State Evaluation

In the previous section, we established a distributed strategy to pick a possible relay node among the neighborhood of another node willing to send a packet. But in order to be efficient, the cooperation should occur if and only if the cooperative communication enhances performance of the transmission as

Input: A : average number of neighbors

Output: my_group_ID

```

create  $A\_list$  using  $A$ ;
 $my\_group\_ID = 0$ ;
while ( $my\_group\_ID = 0$ ) do
  listen the channel for a random period;
  if ( $a\ neighbor\ send\ a\ Group\_ID$ ) then
    |  $I\ should\ take\ off\ the\ Group\ Identifier\ of\ A\_list$ ;
    |  $A\_list = A\_list - Group\_ID$ ;
  else
    |  $I\ pick\ a\ random\ value\ among\ A\_list\ for$ 
    |  $my\_group\_ID$ ;
    if ( $A\_list \neq NULL$ ) then
      |  $my\_group\_ID = random(A\_list)$ ;
    else
      | create  $A\_list$  using  $A$ ;
      |  $my\_group\_ID = random(A\_list)$ ;
    end
    broadcast( $my\_group\_ID$ );
  end
end

```

Algorithm 1: Algorithm process on each node for drawing its own group identifier

well as the overall performance. So to know if our cooperative communication, will improve the communication, we design a link state algorithm. The Link State algorithm is running on each node that has been elected to act as a relay node during automatic forwarding selection process. This process will help the elected relay to determine if it should be involved into the relaying process. The relay node will estimate the channel quality of its link towards the destination and will compare it to the link quality from the source to the destination. For that, each node stores a Link_State table. This table contains the link quality it has with every neighbor. If the link quality is better than the link quality to the source, the cooperation is used. To estimate and process the channel quality the elected nodes will retrieve the RSSI (Receive Signal Strength

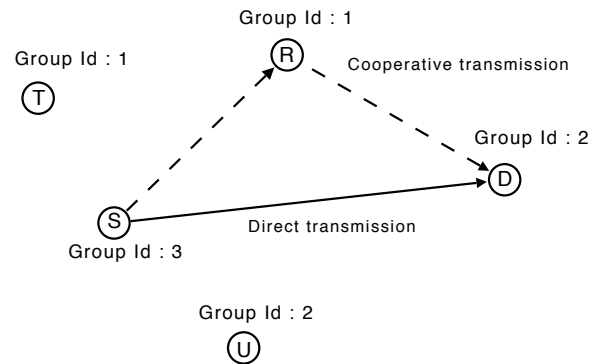


Fig. 1. Cooperative communication scenario

Indicator) from the physical layer. The RSSI measured by the 802.15.4 devices let the algorithm to get the link quality indication (LQI) of the channel.

As example in Fig.1, nodes R and T , once elected by S (by checking the Group Identifier embedded in the packet) should consider forwarding the packet from S . Node R checks the LQI of its link to D in its Link_State table and computes the capacity of this link based on average SNR (Signal Noise Interferences Ratio). Then, it decides if it will forward the packet from S . Our solution does not provide any guarantees on the fact that only one node at the time would act as relay per communication, but the number of relay per communication is close to one if the automatic forwarder process is well configured.

To design our link state evaluation algorithm and the LQI, we essentially based our work on both the characteristics of the wireless sensor network physical layer used in the IEEE 802.15.4 standard [1] to retrieve the bit error rate and Space-Time-Coded Cooperative Diversity scheme defined by Laneman et al. [9]. Given that, the relay node is able to characterize the transmission quality between two-neighbor nodes with and without its cooperation. Considering the Maximum Ratio Combining Diversity [3], the SNR of the diversity combiner is the sum of the SNR of each transmission. Then, we can determine the bit error rate of a cooperative transmission. For the capacity of the channel in cooperative transmission mode, we sum the mutual information and obtain Eqn.1 where W is the bandwidth as defined in IEEE 802.15.4 [1], SNR_{rd} is the SNR between the relay and the destination and SNR_{sd} is the SNR between the source and the destination. Derived from Eqn.1 and the information stored by the relay node (LQI), the relay is now able to decide wether or not it will forward the packet. The forwarding process could be triggered by a couple of criteria like the capacity of the channel or the transmission error rate. Algorithm 2 summarizes the processes that occur during the reception of a packet by a random node into the network.

$$Capa_{coop} = W * \frac{1}{2} [\log(1 + SNR_{rd}) + \log(1 + SNR_{sd})] \quad (1)$$

C. MAC layer protocol details for WSN using cooperative communication

We based WSC-MAC on a CSMA-like MAC layer adapted for WSN [13], where the duty cycle has been reduced as much as possible to lower the overall energy consumption. To reduce consumption from idle-listening, a well known technique consists of using a preamble in order to inform the other nodes that a packet will be sent [4, 13]. For our purpose to initiate the cooperative communication the sleep phase could be a problem, because some of neighbors could be involved in the relaying process. Nodes who hear a preamble should process the algorithms described previously with the intention of participating to the cooperative process. In Fig.2, we present a frame sending sequence of our protocol. Node S

used a preamble for the synchronization with its neighbors then, the cooperative communications occurs in two steps: the first is the transmission of the packet from the source to the destination, then all nodes hearing the message should check if they have to consider forwarding it. In the second step, using the Space-Time-Coded Cooperative Diversity, the packet must be sent by the source and the relay at the same time.

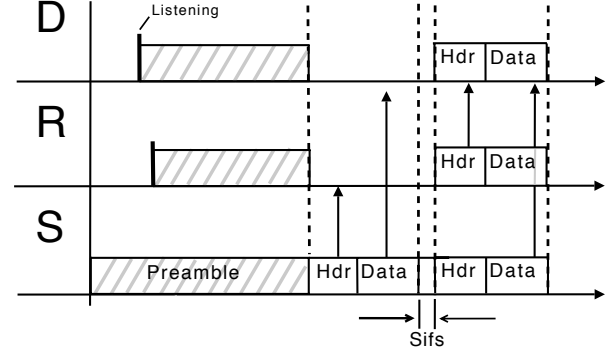


Fig. 2. Frame sending sequence between a source S , a relay R and a destination D

IV. PERFORMANCE RESULTS AND ANALYSIS

This section presents simulation results showing the behavior of a simulated wireless sensor network taking advantage of cooperative communications. To quantify the performance of our proposed cooperative communication scheme, we have developed a network simulator with Matlab [14].

Our simulator implements cooperative communication model previously defined in [9] in addition to our proposed algorithm (cf. Algorithm 2). Each plot point is the average calculated with all data coming from all the possible communication into a network of 100 nodes over 450 runs (30 simulation for 15 different topologies) with a 95% confidence interval. For the sake of clarity we have summarized the simulations settings in Table I.

Packet delivery ratio: We decided to highlight different aspect of our proposed solution as function of the network density, because the performance of our MAC layer proposal will rely on the probability that a cooperative communication could be found to improve the overall performance. The probability that a node could be used as relay is closely tied to the network density. In Fig.3 we show the PDR (Packet Delivery Ratio) as function of the network density and we observe an improvement of an order of 10% when the network is sparse. Meaning that in the case of a very dense network WSC-MAC does not give any improvement, because there is always a link to deliver packets with a high probability of success due to the close distance between nodes.

Reliability: In figure 4, we show a comparison between two different retransmission schemes using the cooperative communication: ACK and NACK. As a result, we observe that the NACK scheme used with cooperative communication outperforms the others by a 66% order of magnitude and 55% in the two different cases of figure.

```

Input: Packet PktI
Output: Packet PktI
receiving a packet;
if ( $PktI.MAC\_Address = my\ address$ ) then
  if ( $packet\ is\ corrupted$ ) then
    | wait until a next one;
  else
    |  $packet\ is\ good$ ;
    | delivery to upper layer;
    | go back to sleep mode;
  end
else
  if ( $PktI.Group\_Id \neq 0$ ) AND
  ( $PktI.Group\_Id = my\ Group\_Id$ ) then
    if ( $PktI.Link\_Quality > Link-$ 
     $table.(PktI.MAC\_Address.Link\_State)$ )
    then
      | Our link quality until destination is less good
      | than source ones;
      | Drop packet;
    else
      | wait SIFS time;
      |  $PktI.Group\_Id = 0$ ;
      | Sending PktI;
    end
  else
    | Drop PktI ;
  end
  go back to sleep mode;
end

```

Algorithm 2: Algorithm process on each neighbor receiving a packet

TABLE I
SUMMARY OF SIMULATION PARAMETERS

Parameter	Value
Simulations Parameters	
Number of nodes	100
Nodes density (nodes/m ²)	0,01 - 0,25
number of topologies	15
number of iterations	30
MAC/PHY Parameters	
Typical Transmission Range (meters)	35
Attenuation factor	3
Pathloss Model	Free Space
Physical Model	802.15.4
Receiver Sensitivity (dbm)	-90
Packet size (bits)	200
Acknowledgment size (ACK/NACK) (bits)	40

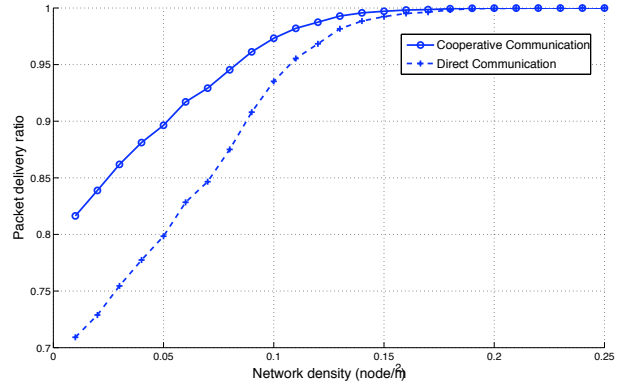


Fig. 3. Packet delivery ratio as function of the nodes density

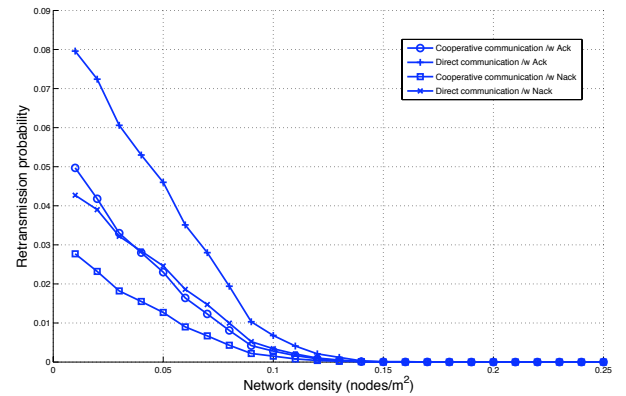


Fig. 4. Retransmissions probability (with ACK and NACK) as function of the nodes density

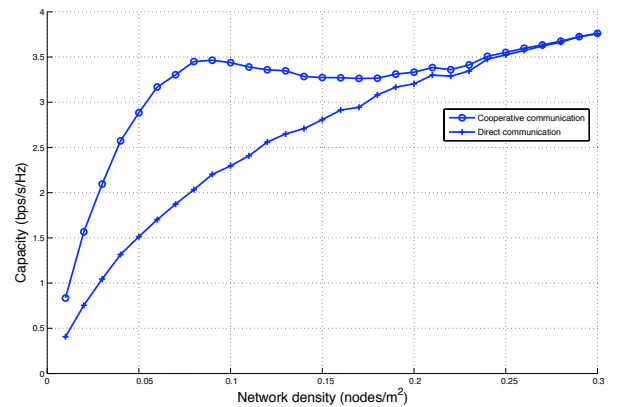


Fig. 5. Capacity as function of the nodes density

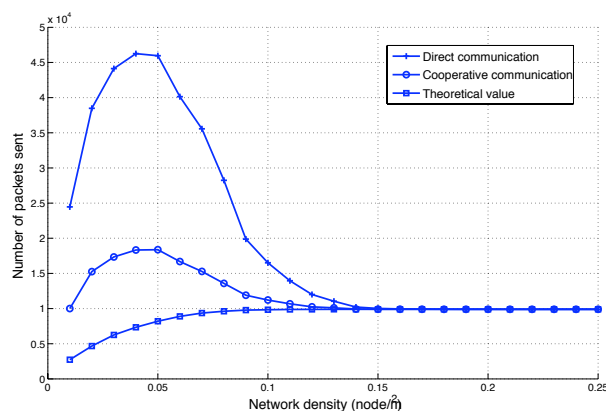


Fig. 6. Comparison of the number of packets sent and the theoretical value as function of the nodes density

Network capacity: Figure 5 shows us the average channel capacity as function of the density. We observe that the capacity reaches its maximum when the network density is close to 0.08 node/m^2 . Note that the cooperative capacity is far beyond the real sensor nodes capacity but this gives information about possible performances of WSC-MAC [6].

Figure 6 shows the number of packet exchanged by nodes into the network, including the retransmissions for three different nodes behaviors: nodes use direct communication only; nodes use our proposed communication pattern and algorithms; and in the last case, we plot the number of transmission in case of a perfect environment (direct communication with no loss, no retransmission, etc).

In a sparse topology, the direct communications use a lot of bandwidth. There are a lot of lost packets and so there are a lot of retransmissions. Using cooperative communications, the number of packets sent is lower, and so, bandwidth is saved.

Our simulations show that WSC-MAC enhances the packet delivery ratio and the reliability of the network in the case of a sparse network (lower than 0.10 nodes/m^2). The acknowledgment traffic is also reduced by our solution. The capacity using WSC-MAC is far beyond the real sensor nodes capacity it points out that some research need to be done in adaptive modulation dedicated to sensors networks.

V. CONCLUSION AND FUTURE WORK

In this paper, a new cooperative MAC protocol tailored for WSN is proposed. In order to fulfill the set of constraints imposed by the cooperative communication scheme and the wireless sensors scheme we have developed an algorithm allowing the automatic selection of the forwarder node (relay node) which use only few message exchanges during the network setup phase. To optimize the selection of the relay node algorithm we use a cross-layer design to fetch information from the physical layer. Our simulations show that the proposed solutions brought enhancements (packet delivery ratio) and reliability to the network in the case of a sparse network. Nevertheless in case of a very dense network, the use

of cooperation techniques do not bring any enhancements and even will have a negative impact on the performances. This is due to the fact that most of wireless links in the network are good enough to carry traffic with very few loss provoked by interferences coming from others transmitting node. This issue is not balancing the overload of a cooperative communication. This concern lead us toward fact that any MAC layer scheme that are exploiting cooperative communication should be used in adaptive way, in order to be efficient in any case. In our future works we will focus on optimizing the group identifier decision process with the aim of finding an even more efficient selection of a relay nodes also well suited for sensor networks.

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