



HAL
open science

Nonlocal Curvature Flows

Antonin Chambolle, Massimiliano Morini, Marcello Ponsiglione

► **To cite this version:**

Antonin Chambolle, Massimiliano Morini, Marcello Ponsiglione. Nonlocal Curvature Flows. *Archive for Rational Mechanics and Analysis*, 2015, 218 (3), pp.1263. 10.1007/s00205-015-0880-z. hal-01371387

HAL Id: hal-01371387

<https://hal.science/hal-01371387>

Submitted on 25 Sep 2016

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

NONLOCAL CURVATURE FLOWS

ANTONIN CHAMBOLLE, MASSIMILIANO MORINI, AND MARCELLO PONSIGLIONE

ABSTRACT. This paper aims at building a unified framework to deal with a wide class of local and nonlocal translation-invariant geometric flows. We introduce a class of nonlocal generalized mean curvatures and prove the existence and uniqueness for the level set formulation of the corresponding geometric flows.

We then introduce a class of generalized perimeters, whose first variation is an admissible generalized curvature. Within this class, we implement a minimizing movements scheme and we prove that it approximates the viscosity solution of the corresponding level set PDE.

We also describe several examples and applications. Besides recovering and presenting in a unified way existence, uniqueness, and approximation results for several geometric motions already studied and scattered in the literature, the theory developed in this paper allows us to establish also new results.

Keywords: Geometric evolution equations, Minimizing movements, Viscosity solutions.

2000 Mathematics Subject Classification: 53C44, 49M25, 35D40.

CONTENTS

1. Introduction	2
Acknowledgements	6
Part 1. Nonlocal Curvatures	7
2. Viscosity solutions: definition, properties, existence	7
2.1. Axioms of a nonlocal curvature	7
2.2. Viscosity solutions	7
2.3. Convergence of sets with uniform superjet	9
2.4. Semicontinuous extensions of κ	10
2.5. Equivalent definitions of the viscosity solutions	12
2.6. Existence of a viscosity solution	15
3. Uniqueness of viscosity solutions	18
3.1. Uniqueness for first-order flows	19
3.2. Uniqueness for second-order flows	21
Part 2. Variational Nonlocal Curvatures	27
4. Generalized perimeters and curvatures	27
4.1. Generalized perimeters	27
4.2. A weak notion of curvature	28
4.3. First variation of the perimeter	28
5. Examples of perimeters and their curvature	33
5.1. The Euclidean perimeter	33
5.2. The fractional mean curvature flow	33
5.3. General two body interaction perimeters	35
5.4. The flow generated by the regularized pre-Minkowski content	35

5.5. The shape flow generated by p -capacity	37
6. The minimizing movements approximation	40
6.1. The time-discrete scheme for bounded sets	40
6.2. The time discrete scheme for unbounded sets	43
6.3. The level-set approach	44
6.4. Convergence analysis	46
6.5. Perimeter descent	49
References	52

1. INTRODUCTION

In this paper we present a unified approach to deal with a large class of possibly nonlocal geometric flows; i.e., evolutions of sets $t \mapsto E(t)$ governed by a law of the form

$$(1.1) \quad V(x, t) = -\kappa(x, E(t)),$$

where $V(x, t)$ stands for the (outer) normal velocity of the boundary $\partial E(t)$ at x and the function $\kappa(\cdot, E)$ will be referred to as a *generalized curvature* of ∂E , in analogy with the classical theory.

If the function κ depends only on how ∂E looks around x , then the flow is local in nature. This is of course the case of the classical *mean curvature flow*, where $\kappa(\cdot, E)$ is nothing but the mean curvature of ∂E , i.e. the first variation of the standard perimeter functional at E . On the other hand, for some of the relevant flows that have been intensively studied in recent years the generalized curvature κ is truly nonlocal and depends on the global shape of the evolving set $E(t)$ itself. It happens for instance for *fractional mean curvature flows*, where the corresponding curvatures are defined as the first variation of the so-called *fractional perimeters*. Such flows represent the natural counterparts in the fractional framework (see [9], [10], [27], [37]) of the classical mean curvature motion. See also [3], [5], and [6] for other somewhat similar nonlocal evolutions, related to dislocation dynamics.

As already made clear by the aforementioned examples, a relevant class of curvatures is given by those that can be seen as the first variation of some *generalized perimeters*; we refer to such a class as *variational curvatures*. It is important to observe that when κ is variational, then (1.1) can be interpreted as the gradient flow of the corresponding perimeter, with respect to a suitable L^2 -Riemannian structure. In the case of the classical mean curvature flow, this observation underpins the *minimizing movements* algorithm implemented by Almgren-Taylor-Wang in their pioneering work [1] (see also [30]).

The strong formulation of the motion (1.1), which requires smoothness, faces the possible formation of singularities in finite time. Thus, the evolution can only be defined locally in time, which is clearly unsatisfactory from the applications point of view. On the other hand, Brakke [8] proposed a weak formulation for motion by mean curvature that resulted in deep regularity results but had the disadvantage of producing a lack of uniqueness. These uniqueness issues are often overcome by the more recent notion of *generalized motion* that is associated to the so-called *level set approach*. Such an approach is based on representing the evolving set as the zero super-level set of a function $u(x, t)$, which is defined for all times as viscosity solution to the (degenerate) parabolic partial differential equation

$$(1.2) \quad u_t(x, t) + |Du(x, t)|\kappa(x, \{y : u(y, t) > u(x, t)\}) = 0.$$

The level-set method was proposed in [32], analytically validated in [23] for the motion by mean curvature and in [20] for more general local motions. In the case of the classical mean curvature (and of several different local curvatures) viscosity

solutions to (1.2) with a prescribed initial datum are unique. Note also that (1.2) prescribes that all the super-level sets of u evolve according to (1.1).

The paper is divided into two parts: The main focus of Part 1 is to develop a general level set approach for the geometric motions (1.1), while Part 2 is aimed at implementing a general minimizing movements scheme à la Almgren-Taylor-Wang for a large class of variational curvature motions, and at exploring the connections between the two approaches. In carrying out the program of Part 1 and Part 2, we recover and present in a unified way existence, uniqueness, and approximation results for several geometric motions already studied and scattered in the literature, but we also establish new results (see the end of this Introduction).

We now describe the content of the paper in more details. In Part 1 we introduce the class of generalized curvatures we deal with and then we set up the viscosity theory for the corresponding generalized level set equation (1.2).

To be more specific, a generalized curvature κ is a function defined on the pairs (x, E) , where E is a C^2 -set¹ with compact boundary and $x \in \partial E$, and such that $\kappa(x, \cdot)$ is monotone non-increasing with respect to the inclusion between sets touching at x , and continuous with respect to C^2 -convergence of sets (for the precise definition of such a convergence see Subsection 2.1). We also assume the translation invariance, i.e., $\kappa(x, E) = \kappa(x + y, E + y)$ for all admissible pairs (x, E) and for all $y \in \mathbb{R}^N$.

In order to fully exploit the second order viscosity solutions formalism, we need to extend the definition of the right-hand side of (1.2) to non-smooth sets. This is achieved by considering suitable lower and upper semicontinuous envelopes κ_* and κ^* of κ that are then employed to define viscosity subsolutions and supersolutions, respectively. The domain of definition of the relaxed curvatures κ_* and κ^* is made up of the elements of the form (x, p, X, E) , where E is now any measurable set, $x \in \partial E$, and (p, X) belongs to the second order super-jet (as far as κ_* is concerned) or sub-jet (as far as κ^* is concerned) of E at x . By construction, κ_* and κ^* turn out to be lower and upper semicontinuous, respectively, with respect to the Hausdorff convergence of sets and a suitable notion of uniform convergence of super- and sub-jets (see Definition 2.7).

Remarkably, the above semicontinuity property is weaker than the semicontinuity with respect to the L^1 -convergence, which is one of the main hypotheses in the rather general approach developed in [33]. This significantly increases the class of admissible curvatures we can treat. For instance, the aforementioned fractional curvatures are not semicontinuous with respect to the L^1 -convergence and the corresponding L^1 -relaxation would be useless (equal to $-\infty$ for every closed set). Let us also notice that κ_* and κ^* are defined only on “geometrically meaningful” objects and this represents a further difference from [33], while the relaxation procedure used to define the semicontinuous envelopes of κ is reminiscent of the approach of Barles & Souganidis (see [7]) and of Cardaliaguet and co-authors (see [11, 12, 13, 14, 15]).

Section 2 is entirely devoted to setting up the viscosity formalism. The latter task being accomplished, a general existence theorem for the level set formulation of (1.1) and for the class of generalized translation invariant curvatures we specified before is easily obtained through an application of the Perron method (see Theorem 2.21).

The drawback of such a generality is that the classical strategy to prove the comparison principle and, in turn, the uniqueness of viscosity solutions may fail. Uniqueness is the main focus of Section 3, where we provide two different treatments, distinguishing between *first order* and *second order* geometric flows.

¹As is often the case in viscosity solution approaches, we may in fact assume that the curvature is *a priori* defined only for smoother sets, and will later on consider also stronger regularities.

Roughly speaking, we say that a geometric flow is of first order if the envelopes κ_* and κ^* do not depend on the second derivative variables (see condition (FO) at the beginning of Subsection 3.1). Fractional mean curvature motions and the *shape flow generated by the p -capacity* in \mathbb{R}^N are relevant examples of first order geometric motions, see below. Uniqueness for such motions follows from the Comparison Principle provided by Theorem 3.5. Let us mention that the main technical tool used in the first order uniqueness theory is represented by the well-known Ilmanen Interposition Lemma (see [26, 11, 12]).

The uniqueness theory for second order flows is harder and developed in Subsection 3.2. In order to understand the source of difficulty, notice that the semicontinuity properties of κ_* and κ^* are not sufficient to conclude that the subsolution and the supersolution inequalities extend to elements of the *closure* of the *parabolic* super- and sub-jets, respectively. This means that the usual machinery to establish uniqueness for second order equations, which is based on the celebrated Ishii's Lemma (see [21]), cannot be applied. Indeed, Ishii's Lemma states that if u is upper semicontinuous, v is lower semicontinuous, and $u - v$ attains a (local) maximum at (x, t) , then there exists at least one element belonging to both the *closure* of the parabolic super-jet of u and the *closure* of the parabolic sub-jet of v at (x, t) . Such a separating element is obtained through a limiting procedure, which involves regularizations via inf- and sup-convolutions, the Alexandrov theorem on the a.e. second order differentiability of semi-convex functions, and a perturbation argument due to Jensen ([21, Lemma A.3]). Since we lack the proper semicontinuity properties, we need to avoid "passing to the limit". Our proof of the second order Comparison Principle (see Theorem 3.8) still uses all the aforementioned tools but combines them with some new insight, allowing us to avoid the limiting procedure. The price we have to pay is a reinforced continuity assumption on κ (see beginning of Subsection 3.2), which is nevertheless satisfied by all the relevant examples we have in mind.

In Part 2 of the paper we take on a variational approach to geometric flows based on the minimizing movements. To this aim, we introduce a class of functionals referred to as *generalized perimeters*. More precisely, denoting by \mathfrak{M} the class of Lebesgue-measurable sets, we call a generalized perimeter any *translation invariant* set function $J : \mathfrak{M} \rightarrow [0, +\infty]$, which is insensitive to modifications on negligible sets, finite on C^2 -sets with compact boundary, lower semicontinuous with respect to L^1_{loc} -convergence, and satisfying the following *submodularity condition*: For any measurable sets $E, F \subset \mathbb{R}^N$,

$$(1.3) \quad J(E \cup F) + J(E \cap F) \leq J(E) + J(F) .$$

It turns out that the latter condition is a convexity condition in the following sense: Extend J to $L^1_{loc}(\mathbb{R}^N)$ by enforcing the *generalized coarea formula* (4.3)(see [37]); then, J is submodular if and only if the extended functional is convex (see [18]). A first important consequence of submodularity is that if J admits a first variation κ , then such a curvature is monotone. More in general, if J is smooth enough, then its first variation is an admissible generalized curvature.

As mentioned before, the main achievement of Part 2 is the implementation of a *generalized Almgren-Taylor-Wang minimizing movements scheme* to approximate geometric motions associated with variational generalized curvatures. We recall that, given an initial set E_0 and a time step $h > 0$, such a scheme provides a discrete-in-time evolution obtained by solving iteratively suitable incremental minimum problems. The energy to be minimized at each discrete time is the sum of the generalized perimeter and of a suitable dissipation that penalizes the L^2 -distance from the boundary of the set obtained at the previous step. It turns out, once again due to submodularity, that the discrete evolutions satisfy the comparison principle.

Adopting the point of view introduced in [17], we combine the minimizing movements scheme with the level set framework. More precisely, given an initial function u_0 , we let all its super-level sets evolve according to the discrete scheme. In light of the discrete comparison principle, the evolving sets are themselves the super-level sets of a discrete-in-time evolving function $u_h(\cdot, t)$.

We then study the limiting behavior of u_h as the time step $h \searrow 0$ and in one of the main results of this paper we establish the following general *consistency principle*: For all variational generalized curvatures the discrete evolutions u_h provided by the minimizing movements scheme converge (up to subsequences) to a viscosity solution of the level set equation. In particular, under the additional assumption that guarantees uniqueness, the whole sequence converges (to the unique viscosity solution). Let us mention that in the case of the mean curvature motion the consistency between the level set and the minimizing movements approach has been established in [17] (see also [22]). From the technical point of view, the convergence analysis combines several ingredients, among which we mention some careful estimates on the speed of propagation of the support of the initial function u_0 and a subgradient inequality involving the generalized curvature, which is crucial in obtaining the limiting sub(super)-solution property. The subgradient inequality is a consequence of the analysis developed in Subsection 4.3 (see (4.9)). Note that since we don't have a regularity theory for the minimizers of the incremental problems, all our argument are necessarily variational in nature.

A relevant consequence of our general consistency principle is that the generalized perimeter of the super-level sets for which no fattening occurs during the evolution is non-increasing in time (note that the no fattening condition is satisfied by almost all super-level sets). Moreover, we show that a suitable inner regularization of the generalized perimeter J , defined on open sets A as the $\inf - \liminf$ of J along sequences of open sets approximating A from the interior (see Definition 6.20), is always non-increasing in time (see Subsection 6.5).

We conclude this introduction by highlighting some relevant examples and applications of our general theory that are presented in the paper (see Section 5). Such examples are by no means exhaustive and serve indicating the scope of our theory:

- *Local motions*: The theory of local generalized mean curvature motions established in [20] fits into our theory as particular case.

- *Fractional mean curvatures motions*: As mentioned before, these are the first order geometric flows associated with the so-called fractional perimeters. Existence and uniqueness of viscosity solutions to the corresponding level set equation were already established in [27] and are recovered here. On the other hand, the convergence of the minimizing movements scheme provided by our theory is new for these motions and furnishes an approximation algorithm that is alternative to the threshold-dynamics-based one studied in [10].

- *Capacity flows*: Given $1 < p < N$, consider the generalized perimeter that coincides with the p -capacity in \mathbb{R}^N on bounded sets of class C^2 . It can be shown that the associated curvature $\kappa(x, E)$ is given by $|Dw_E(x)|^p$, where w_E denotes the *capacitary potential* of E . Thus, the associated geometric motion is somewhat related to the Hele-Shaw type flows studied in [13, 14, 15] (see also [11, 12]). Our general results yield existence, uniqueness, and approximation via minimizing movements also for this shape flow, which turns out to be of first order according to our terminology (see Subsection 5.5).

- *Second order nonlocal motions*: Our theory includes all the generalized curvatures treated in [33], that are in addition translation invariant. As already mentioned, compared to our approach the theory of [33] requires stronger continuity assumptions on the Hamiltonians and more restrictive growth conditions that rule out singular behavior of generalized curvatures along shrinking balls. As a further example, which is not covered by the theory developed in [33] while fitting into

ours, we mention here the generalized perimeter introduced in [2] in the framework of two-phase Image Segmentation. We will refer to it as *regularized pre-Minkowski content* of a set since it consists in a suitable regularization of the Lebesgue measure of the ρ -neighborhood of the essential boundary, for some fixed $\rho > 0$. The corresponding geometric motion was studied in [19]. In the latter work we computed the associated generalized curvature and proved convergence of the minimizing movements scheme to a viscosity solution of the level set equation, but we were unable to establish uniqueness. The theory of the present paper allows us to recover the existence and approximation results of [19] and, in addition, yields the uniqueness of the geometric motion.

A final remark regarding the translation invariance and the continuity assumptions on κ is in order. Concerning the former, we believe that it could be removed at the expense of some additional technical effort but within the main theoretical framework introduced in this paper. On the other hand, the continuity assumptions that guarantee the stability property and the comparison principle are of a more subtle and essential nature. They exclude from our theory some relevant irregular perimeters, as crystalline perimeters (that also would require a different specific viscosity level set formulation). It is not clear at the present which is (if any) the weakest continuity assumption on κ yielding the uniqueness of the geometric flow.

ACKNOWLEDGEMENTS

The first author is partially funded by the ANR grant “HJnet” ANR-12-BS01-0008-01, and would like to thank R. Monneau for helpful discussion. Part of this research was done during two stays at U. Parma, funded by the GNAMPA.

Part 1. Nonlocal Curvatures

In this part we introduce the class of generalized curvatures we deal with. Then, we introduce the notion of viscosity solutions for the level set equation of the geometric flow, and we prove the existence and uniqueness of the solution.

2. VISCOSITY SOLUTIONS: DEFINITION, PROPERTIES, EXISTENCE

We begin this section by introducing the class of generalized curvatures we will deal with.

2.1. Axioms of a nonlocal curvature. Let \mathfrak{C} be the class of subsets of \mathbb{R}^N , which can be obtained as the closure of an open set with compact $C^{\ell,\beta}$ boundary, and let \mathfrak{M} be the class of all measurable subsets of \mathbb{R}^N . Throughout the paper $\ell \geq 2$ and $\beta \in [0, 1]$ will be fixed, the reader may simply assume $\ell = 2, \beta = 0$.

In this part, we are given for every set $E \in \mathfrak{C}$ a function $x \mapsto \kappa(x, E) \in \mathbb{R}$ defined for $x \in \partial E$, and referred to as the ‘‘curvature’’ of the set E . This curvature will satisfy the following axioms:

- A) Monotonicity: If $E, F \in \mathfrak{C}$ with $E \subseteq F$, and if $x \in \partial F \cap \partial E$, then $\kappa(x, F) \leq \kappa(x, E)$;
- B) Translational invariance: for any $E \in \mathfrak{C}$, $x \in \partial E$, $y \in \mathbb{R}^N$, $\kappa(x, E) = \kappa(x + y, E + y)$;
- C) Continuity: If $E_n \rightarrow E$ in \mathfrak{C} and $x_n \in \partial E_n \rightarrow x \in \partial E$, then $\kappa(x_n, E_n) \rightarrow \kappa(x, E)$.

Here and throughout the paper, by $E_n \rightarrow E$ in \mathfrak{C} we mean that there exists a sequence of diffeomorphisms $\{\Phi_n\}$ converging to the identity in $C^{\ell,\beta}$, with $E_n = \Phi_n(E)$.

Axioms A), B) and C) are enough to prove the existence of a generalized solution of the geometric flow (1.1). By assumption C), for any $\rho > 0$ we can define the quantities

$$(2.1) \quad \bar{c}(\rho) := \max_{x \in \partial B_\rho} \max\{\kappa(x, B_\rho), -\kappa(x, \mathbb{R}^N \setminus B_\rho)\},$$

$$(2.2) \quad \underline{c}(\rho) := \min_{x \in \partial B_\rho} \min\{\kappa(x, B_\rho), -\kappa(x, \mathbb{R}^N \setminus B_\rho)\},$$

which are continuous functions of $\rho > 0$. Assumption D) below will guarantee that the curvature flow starting from a bounded set remains bounded at all times.

D) Curvature of the balls: There exists $K > 0$ such that

$$(2.3) \quad \underline{c}(\rho) > -K > -\infty.$$

Without assuming D) most of the results in this paper remain true, except that the flow starting from a given set with compact boundary will be defined possibly up to some time $T^* < +\infty$ where its boundary becomes unbounded and the framework of this paper cannot be applied anymore. The time T^* can be estimated from $\underline{c}(\rho)$. Observe that thanks to the monotonicity axiom A), the functions $\rho \mapsto \bar{c}(\rho)$ and $\rho \mapsto \underline{c}(\rho)$ are nonincreasing.

2.2. Viscosity solutions. Here we introduce the level set formulation of the geometric evolution problem $V = -\kappa$, where V represents the normal velocity of the boundary of the evolving sets $t \mapsto E_t$, and we give a proper notion of viscosity solution. We refer to [25] for a general introduction of this approach for local geometric evolution problems. The level set approach consists in solving the following parabolic Cauchy problem

$$(2.4) \quad \begin{cases} \partial_t u(x, t) + |Du(x, t)|\kappa(x, \{y : u(y, t) \geq u(x, t)\}) = 0 \\ u(0, \cdot) = u_0. \end{cases}$$

Here and in the following, D and D^2 stand for the spatial gradient and the spatial Hessian matrix, respectively. Notice that if the superlevel sets of u are not smooth, the meaning of (2.4) is unclear. For this reason, it is necessary to use a definition based on appropriate smooth test functions whose level sets curvatures are well defined. The appropriate setting is of course the framework of viscosity solutions. Let us first introduce a class of test functions appropriate for this problem.

As in [28] (see also [19]), we introduce a family \mathcal{F} of functions $f \in C^\infty([0, \infty))$, such that $f(0) = f'(0) = f''(0) = 0$, $f''(r) > 0$ for all r in a neighborhood of 0, f is constant in $[M, +\infty)$ for some $M > 0$ (depending on f), and

$$(2.5) \quad \lim_{\rho \rightarrow 0^+} f'(\rho) \bar{c}(\rho) = 0,$$

where $\bar{c}(\rho)$ is the function introduced in (2.1). We refer to [28, p. 229] for the proof that the family \mathcal{F} is not empty. Note that (2.5) (recall also (2.3)) implies

$$(2.6) \quad \lim_{\rho \rightarrow 0^+} f'(\rho) \bar{c}(f^{-1}(\rho)) = 0,$$

since $f^{-1}(\rho) > \rho$ for small values of ρ and \bar{c} is decreasing.

We fix $T > 0$ and look for geometric evolutions in the time interval $[0, T]$. Since we will consider the evolution of sets with compact boundaries, it is convenient to describe such evolving sets as level sets of functions that are spatially constant outside a compact set. For technical reasons it will be convenient to consider test functions that are also spatially constant outside a compact set, but with such a constant value possibly depending on time. More precisely, in the following, with a small abuse of language, we will say that a function $g : \mathbb{R}^N \times A \rightarrow \mathbb{R}$, with $A \subseteq [0, T]$, is constant outside a compact set if there exists a compact set $\mathcal{K} \subseteq \mathbb{R}^N$ such that $g(\cdot, t)$ is constant in $(\mathbb{R}^N \setminus \mathcal{K})$ for every $t \in A$ (with the constant possibly depending on t).

Definition 2.1. Let $\hat{z} = (\hat{x}, \hat{t}) \in \mathbb{R}^N \times (0, T)$ and let $A \subseteq (0, T)$ be any open interval containing \hat{t} . We will say that $\varphi \in C^0(\mathbb{R}^N \times \bar{A})$ is *admissible at the point* $\hat{z} = (\hat{x}, \hat{t})$ if it is of class C^2 in a neighborhood of \hat{z} , if it is constant out of a compact set, and, in case $D\varphi(\hat{z}) = 0$, the following holds: there exists $f \in \mathcal{F}$ and $\omega \in C^\infty([0, \infty))$ with $\omega'(0) = 0$, $\omega(r) > 0$ for $r \neq 0$ such that

$$|\varphi(x, t) - \varphi(\hat{z}) - \varphi_t(\hat{z})(t - \hat{t})| \leq f(|x - \hat{x}|) + \omega(|t - \hat{t}|)$$

for all (x, t) in $\mathbb{R}^N \times A$.

We are now ready to propose the definition of a viscosity sub and supersolution. The literature contains a multiplicity of formulations based on larger or smaller families of test functions. Ours and the equivalent definitions we will provide in Subsection 2.5 are variants of what can be found in a non-local setting in [6] or [33].

Definition 2.2. An upper semicontinuous function $u : \mathbb{R}^N \times [0, T] \rightarrow \mathbb{R}$ (in short $u \in USC(\mathbb{R}^N \times [0, T])$), constant outside a compact set, is a viscosity subsolution of the Cauchy problem (2.4) if $u(0, \cdot) \leq u_0$ and for all $z := (x, t) \in \mathbb{R}^N \times (0, T)$ and all C^∞ -test functions φ such that φ is admissible at z and $u - \varphi$ has a maximum at z (in the domain of definition of φ) the following holds:

- i) If $D\varphi(z) = 0$, then $\varphi_t(z) \leq 0$;
- ii) If the level set $\{\varphi(\cdot, t) = \varphi(z)\}$ is noncritical, then

$$\varphi_t(z) + |D\varphi(z)| \kappa(x, \{y : \varphi(y, t) \geq \varphi(z)\}) \leq 0.$$

A lower semicontinuous function u (in short $u \in LSC(\mathbb{R}^N \times [0, T])$), constant outside a compact set, is a viscosity supersolution of the Cauchy problem (2.4) if $u(0, \cdot) \geq u_0$ and for all $z \in \mathbb{R}^N \times (0, T)$ and all C^∞ -test functions φ such that φ is admissible at z and $u - \varphi$ has a minimum at z (in the domain of definition of φ) the following holds:

- i) If $D\varphi(z) = 0$, then $\varphi_t(z) \geq 0$;
- ii) If the level set $\{\varphi(\cdot, t) = \varphi(z)\}$ is noncritical, then

$$\varphi_t(z) + |D\varphi(z)| \kappa(x, \{y : \varphi(y, t) \geq \varphi(z)\}) \geq 0.$$

Finally, a function u is a viscosity solution of the Cauchy problem (2.4) if its upper semicontinuous envelope is a subsolution and its lower semicontinuous envelope is a supersolution of (2.4).

Remark 2.3. As it is standard in the theory of viscosity solutions, the maximum in Definition 2.2 of subsolutions can be assumed to be strict (and similarly for supersolutions). Indeed, assume for instance that u is a subsolution, $u - \varphi$ has a maximum at some (\bar{x}, \bar{t}) , with φ as in Definition 2.2. We now replace φ by

$$\varphi^s(x, t) := \varphi(x, t) + sf(|x - \bar{x}|) + |t - \bar{t}|^2,$$

where $s > 0$ is sufficiently small and $f \in \mathcal{F}$. Then the maximum of $u - \varphi^s$ at (\bar{x}, \bar{t}) is strict and we recover the subsolution inequality for φ by letting $s \rightarrow 0$ and using the continuity of κ .

Throughout the paper, we will use (with a small abuse of terminology) the terms subsolutions and supersolutions (omitting the locution “of the Cauchy problem (2.4)”) also for functions which do not satisfy the corresponding inequalities at time zero.

While Definition 2.2 is quite natural, it has the drawback that the family of possible test functions is too restrictive to be handy. As usual in the viscosity theory, we will introduce suitable lower and upper semicontinuous extensions of κ . This will allow to give definitions equivalent to Definition 2.2, based on less smooth test functions as in Definition 2.1 (see Definition 2.11), or on the notion of sub/superjets.

2.3. Convergence of sets with uniform superjet. We denote by $\mathbb{M}_{\text{sym}}^{N \times N}$ the set of $N \times N$ symmetric matrices.

Definition 2.4. Let $E \subseteq \mathbb{R}^N$, $x_0 \in \partial E$, $p \in \mathbb{R}^N$, and $X \in \mathbb{M}_{\text{sym}}^{N \times N}$. We say that (p, X) is in the superjet $\mathcal{J}_E^{2,+}(x_0)$ of E at x_0 if for every $\delta > 0$ there exists a neighborhood U_δ of x_0 such that

$$(2.7) \quad (x - x_0) \cdot p + \frac{1}{2}(X + \delta I)(x - x_0) \cdot (x - x_0) \geq 0$$

for every $x \in E \cap U_\delta$. Moreover, we say that (p, X) is in the subjet $\mathcal{J}_E^{2,-}(x_0)$ of E at x_0 if $(-p, -X)$ is in the superjet $\mathcal{J}_{\mathbb{R}^N \setminus E}^{2,+}(x_0)$ of $\mathbb{R}^N \setminus E$ at x_0 . Finally, we say that (p, X) is in the jet $\mathcal{J}_E^2(x_0)$ of E at x_0 if $(p, X) \in \mathcal{J}_E^{2,+}(x_0) \cap \mathcal{J}_E^{2,-}(x_0)$.

The above definition of sub and superjet of sets is consistent with the classical notion of sub and superjet of l.s.c and u.s.c. characteristic functions, respectively.

Remark 2.5. It can be checked that the condition $(p, X) \in \mathcal{J}_E^{2,+}(x_0)$ is equivalent to $(\lambda p, \lambda X + \mu p \otimes p) \in \mathcal{J}_E^{2,+}(x_0)$ for all $\lambda > 0$ and for all $\mu \in \mathbb{R}$. Thus, $(p, X) \in \mathcal{J}_E^{2,+}(x_0)$ if and only if $(\frac{p}{|p|}, \frac{1}{|p|}\pi_{p^\perp} X \pi_{p^\perp}) \in \mathcal{J}_E^{2,+}(x_0)$, where π_{p^\perp} denotes the projection operator on $p^\perp := \{v \in \mathbb{R}^N : p \cdot v = 0\}$. Note that if $E = \{u \geq u(x_0)\}$, with u of class C^2 and $Du \neq 0$ on ∂E , then, setting $p := Du(x_0)$ and $X := D^2u(x_0)$, $\frac{p}{|p|}$ is the inner normal to $\{u \geq u(x_0)\}$ at x_0 , while $\frac{1}{|p|}\pi_{p^\perp} X \pi_{p^\perp}$ represents the second fundamental form of $\partial\{u \geq u(x_0)\}$ at x_0 .

Let us introduce the notion of uniform superjet.

Definition 2.6. Let $E_n \subseteq \mathbb{R}^N$ and $x_0 \in \partial E_n$. We say that the (p_n, X_n) 's are in the superjet $\mathcal{J}_{E_n}^{2,+}(x_0)$ uniformly, if for every positive $\delta > 0$ there exists a neighborhood U_δ of x_0 (independent of n) such that for all $n \in N$

$$(2.8) \quad (x - x_0) \cdot p_n + \frac{1}{2}(X_n + \delta I)(x - x_0) \cdot (x - x_0) \geq 0 \text{ for every } x \in E_n \cap U_\delta.$$

In the following, given a set $E \subset \mathbb{R}^N$, $E^c := \mathbb{R}^N \setminus E$ denotes its complement. We also recall that a sequence of closed sets C_n converges to a closed set C in the Hausdorff metric ($C_n \xrightarrow{H} C$) if

$$\max \left\{ \sup_{x \in C_n} \text{dist}(x, C), \sup_{x \in C} \text{dist}(x, C_n) \right\} \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Definition 2.7. We say that (p_n, X_n, E_n) converge to (p, X, E) with uniform superjet at x_0 if $\overline{E_n} \rightarrow \overline{E}$ in the Hausdorff sense, the (p_n, X_n) 's are in the superjet $\mathcal{J}_{E_n}^{2,+}(x_0)$ uniformly and $(p_n, X_n) \rightarrow (p, X)$ as $n \rightarrow \infty$.

Moreover, we say that (p_n, X_n, E_n) converge to (p, X, E) with uniform subjet at x_0 if $(-p_n, -X_n, E_n^c)$ converge to $(-p, -X, E^c)$ with uniform superjet.

2.4. Semicontinuous extensions of κ . We now introduce two suitable lower and upper semicontinuous extensions of κ , which will be instrumental in developing the level set formulation of the geometric flow. This is reminiscent of the approach in [11, 12] for evolution of ‘‘tubes’’ by geometric motions (see also [13, 14, 15]). For every $F \subseteq \mathbb{R}^N$ with compact boundary and $(p, X) \in \mathcal{J}_F^{2,+}(x)$, we define

$$(2.9) \quad \kappa_*(x, p, X, F) := \sup \left\{ \kappa(x, E) : E \in \mathfrak{C}, E \supseteq F, (p, X) \in \mathcal{J}_E^{2,-}(x) \right\}$$

Analogously, for any $(p, X) \in \mathcal{J}_F^{2,-}(x)$ we set

$$(2.10) \quad \kappa^*(x, p, X, F) = \inf \left\{ \kappa(x, E) : E \in \mathfrak{C}, \mathring{E} \subseteq F, (p, X) \in \mathcal{J}_E^{2,+}(x) \right\}.$$

Here \mathring{E} denotes the interior of E . It is clear that κ_* only depends on the closure of F while κ^* depends on its interior, in practice the first one will be evaluated at superlevels of usc functions, while the second one at strict superlevels of lsc functions.

It follows from the monotonicity property A) that if $E \in \mathfrak{C}$ and $(p, X) \in \mathcal{J}_E^2(x)$, then $\kappa_*(x, p, X, E) = \kappa^*(x, p, X, E) = \kappa(x, E)$. Notice that the monotonicity of κ clearly extends to κ_* and κ^* . More precisely, $\kappa_*(x, p, X, E) \geq \kappa_*(x, p, X, F)$ (resp. $\kappa^*(x, p, X, E) \geq \kappa^*(x, p, X, F)$) whenever $E \subseteq F$ and $(p, X) \in \mathcal{J}_E^{2,+}(x) \cap \mathcal{J}_F^{2,+}(x)$ (resp. $(p, X) \in \mathcal{J}_E^{2,-}(x) \cap \mathcal{J}_F^{2,-}(x)$).

In the next Lemma we show that κ_* and κ^* are the l.s.c. and the u.s.c envelope of κ with respect to the convergence defined in Definition 2.7, respectively.

Lemma 2.8. *Let $F \subseteq \mathbb{R}^N$ with compact boundary. Then,*

$$\kappa_*(x, p, X, F) = \inf \liminf_n \kappa(x, E_n)$$

where the infimum is over all $(p_n, X_n, E_n) \rightarrow (p, X, F)$ with uniform superjet at x ;

$$\kappa^*(x, p, X, F) = \sup \limsup_n \kappa(x, E_n)$$

where the supremum is over all $(p_n, X_n, E_n) \rightarrow (p, X, F)$ with uniform subjet at x .

Proof. We will prove the statement only for κ_* , the other case being analogous. We start by showing that there exists a sequence (p, X_n, E_n) such that $(p, X_n, E_n) \rightarrow (p, X, F)$ with uniform superjet at x and $\kappa_*(x, p, X, F) = \lim_n \kappa(x, E_n)$. To this aim, recall that by definition of $\kappa_*(x, p, X, F)$ for every $n \in \mathbb{N}$ there exists a set $\tilde{E}_n \in \mathfrak{C}$, with $F \subseteq \tilde{E}_n$, $(p, X) \in \mathcal{J}_{\tilde{E}_n}^{2,-}(x)$ and $0 \leq \kappa_*(x, p, X, F) - \kappa(x, \tilde{E}_n) \leq \frac{1}{n}$. By the monotonicity of κ we may also assume that $\tilde{E}_n \rightarrow \overline{F}$ in the Hausdorff metric.

Moreover, by the continuity assumption C) we can suitably modify the sequence \tilde{E}_n so that, in addition to the previous properties, we have $(p, X + \delta_n I) \in \mathcal{J}_{\tilde{E}_n}^{2,-}(x)$, $\partial\tilde{E}_n \cap \partial F = \{x\}$ and $0 \leq \kappa_*(x, p, X, F) - \kappa(x, \tilde{E}_n) \leq \frac{2}{n}$ for some suitable $\delta_n \searrow 0$. Now we construct the sequence E_n according to the following inductive procedure. Assume that E_1, \dots, E_n have been defined with the following properties:

- 1) $F \subseteq E_n \subseteq E_{n-1} \subseteq \dots \subseteq E_1$,
- 2) $E_i \subseteq \tilde{E}_i$ for $i = 1, \dots, n$,
- 3) $\partial E_i \cap \partial F = \{x\}$ for every $i = 1, \dots, n$
- 4) $(p, X + \frac{\delta_i}{2} I) \in \mathcal{J}_{\tilde{E}_i}^2(x)$ for every $i = 1, \dots, n$.

Since

$$X + \frac{\delta_{n+1}}{2} I < X + \frac{\delta_n}{2} I, \quad X + \frac{\delta_{n+1}}{2} I < X + \delta_{n+1} I,$$

recalling that $(p, X + \frac{\delta_n}{2} I) \in \mathcal{J}_{E_n}^2(x)$ and $(p, X + \delta_{n+1} I) \in \mathcal{J}_{E_{n+1}}^{2,-}(x)$ we can easily construct $E_{n+1} \in \mathfrak{C}$ such that

$$(p, X + \frac{\delta_{n+1}}{2} I) \in \mathcal{J}_{E_{n+1}}^2(x), \quad F \subseteq E_{n+1} \subseteq \tilde{E}_{n+1}, \quad E_{n+1} \subseteq E_n, \quad \partial E_{n+1} \cap \partial F = \{x\}.$$

The sequence E_n just constructed still converges to \bar{F} in the sense of Hausdorff. Moreover, since E_n is monotone decreasing, we have $(p, X + \frac{\delta_n}{2} I, E_n) \rightarrow (p, X, F)$ with uniform superjet. Note also that since $(p, X) \in \mathcal{J}_{E_n}^{2,-}(x)$, by (2.9) we immediately have $\kappa_*(x, p, X, F) \geq \kappa(x, E_n)$ for all n . Finally, by the monotonicity of κ ,

$$\kappa_*(x, p, X, F) \geq \limsup_n \kappa(x, E_n) \geq \liminf_n \kappa(x, E_n) \geq \lim_n \kappa(x, \tilde{E}_n) = \kappa_*(x, p, X, F).$$

Now, let $(p_n, X_n, F_n) \rightarrow (p, X, F)$ with uniform superjet at x . Let $j \in \mathbb{N}$ and let E_j the set constructed above. Notice that for n large enough, F_n is contained in $x + R_n(E_j - x)$, where R_n is any rotation such that $R_n(p) = p_n$. By the monotonicity assumption A) and the continuity assumption C) on κ we deduce

$$(2.11) \quad \kappa(x, E_j) = \lim_n \kappa(x, x + R_n(E_j - x)) \leq \liminf_n \kappa(x, F_n).$$

We conclude that

$$\liminf_n \kappa(x, F_n) \geq \lim_j \kappa(x, E_j) = \kappa_*(x, p, X, F).$$

□

Lemma 2.9. *Let $\varphi_n, \varphi \in C^0(\mathbb{R}^N)$ be constant outside a compact set \mathcal{K} (independent of n). Assume that $\varphi_n \rightarrow \varphi$ uniformly and $\varphi_n \rightarrow \varphi$ in $C^2(B(x, \delta))$ for some $\delta > 0$ and $x \in \mathbb{R}^N$ with $D\varphi(x) \neq 0$. If $x_n \rightarrow x$, then*

$$(2.12) \quad \begin{aligned} \kappa_*(x, D\varphi(x), D^2\varphi(x), \{\varphi \geq \varphi(x)\}) \\ \leq \liminf_n \kappa_*(x_n, D\varphi_n(x_n), D^2\varphi_n(x_n), \{\varphi_n \geq \varphi_n(x_n)\}) \end{aligned}$$

and

$$(2.13) \quad \begin{aligned} \kappa^*(x, D\varphi(x), D^2\varphi(x), \{\varphi > \varphi(x)\}) \\ \geq \limsup_n \kappa^*(x_n, D\varphi_n(x_n), D^2\varphi_n(x_n), \{\varphi_n > \varphi_n(x_n)\}). \end{aligned}$$

Proof. Up to a subsequence, we can assume that $\mathcal{K}_n := x - x_n + \{\varphi_n \geq \varphi_n(x_n)\}$ converge in the sense of Hausdorff to some closed set $\tilde{\mathcal{K}}$ contained in $\mathcal{K} := \{\varphi \geq \varphi(x)\}$. Since $D\varphi(x) \neq 0$, then $(D\varphi_n(x_n), D^2\varphi_n(x_n), \mathcal{K}_n) \rightarrow (D\varphi(x), D^2\varphi(x), \tilde{\mathcal{K}})$

with uniform superjet at x . Thus, by Lemma 2.8 and the monotonicity of κ_* we may conclude

$$\begin{aligned} \kappa_*(x, D\varphi(x), D^2\varphi(x), \mathcal{K}) &\leq \kappa_*(D\varphi(x), D^2\varphi(x), \tilde{\mathcal{K}}) \\ &\leq \liminf_n \kappa_*(x, D\varphi_n(x_n), D^2\varphi_n(x_n), \mathcal{K}_n), \end{aligned}$$

which proves (2.12). The proof of (2.13) is identical. \square

Remark 2.10. In [33] a class of nonlocal Hamiltonians $H(x, p, X, F)$ that are lower semicontinuous with respect to the L^1 convergence of sets and the standard convergence of the other variables is considered. Notice that such Hamiltonians are also lower semicontinuous with respect to the convergence with uniform superjets introduced in Definition 2.7. Indeed, if $(p_n, X_n, F_n) \rightarrow (p, X, F)$ with uniform superjet at x , then one can show that $F_n \cup \bar{F} \rightarrow \bar{F}$ in L^1_{loc} . Thus,

$$H(x, p, X, \bar{F}) \leq \liminf_n H(x, p_n, X_n, F_n \cup \bar{F}) \leq \liminf_n H(x, p_n, X_n, F_n),$$

where the last inequality follows from the monotonicity assumption on H with respect to the set variable.

2.5. Equivalent definitions of the viscosity solutions. We now can give a second definition of viscosity solutions of (2.4). It is seemingly more restrictive than the previous Definition 2.2, but we will check later on that it is equivalent.

Definition 2.11. An upper semicontinuous function $u : \mathbb{R}^N \times [0, T] \rightarrow \mathbb{R}$, constant outside a compact set, is a viscosity subsolution of the Cauchy problem (2.4) if $u(0, \cdot) \leq u_0$, and for all $z := (x, t) \in \mathbb{R}^N \times (0, T)$ and all φ admissible at z , such that $u - \varphi$ has a maximum at z (in the domain of definition of φ) we have

- i) If $D\varphi(z) = 0$, then $\varphi_t(z) \leq 0$;
- ii) If $D\varphi(z) \neq 0$, then

$$(2.14) \quad \varphi_t(z) + |D\varphi(z)| \kappa_*(x, D\varphi(z), D^2\varphi(z), \{y : \varphi(y, t) \geq \varphi(z)\}) \leq 0.$$

The definition of viscosity supersolutions and of viscosity solutions are given accordingly in the obvious way.

I EXCHANGED THE ORDER OF THE LEMMA AND REMARKS!

Remark 2.12. As in Remark 2.3, the maximum in Definition 2.11 of subsolutions can be assumed to be strict (and similarly for supersolutions). Assume for instance that u is a subsolution, $u - \varphi$ has a maximum at some (\bar{x}, \bar{t}) , with φ admissible at (\bar{x}, \bar{t}) . We replace φ by

$$\varphi^s(x, t) := \varphi(x, t) + sf(|y - x|) + |t - s|^2,$$

with $s > 0$ and $f \in \mathcal{F}$. Then the maximum of $u - \varphi^s$ at (\bar{x}, \bar{t}) is strict. If $D\varphi(\bar{x}, \bar{t}) \neq 0$, we recover the inequality (2.14) for φ by letting $s \rightarrow 0$ and using the semicontinuity property of κ_* provided by Lemma 2.9. If $D\varphi(\bar{x}, \bar{t}) = 0$, we still have $D\varphi^s(\bar{x}, \bar{t}) = 0$, φ^s is admissible at (\bar{x}, \bar{t}) and $\varphi_t^s(\bar{x}, \bar{t}) = \varphi_t(\bar{x}, \bar{t})$.

Moreover, one can assume without loss of generality that φ is smooth. If $D\varphi(\bar{x}, \bar{t}) \neq 0$, this follows again by Lemma 2.9 and by standard mollification arguments. If $D\varphi(\bar{x}, \bar{t}) = 0$, since φ is admissible at z , there are $f \in \mathcal{F}$ and $\omega \in C^\infty(\mathbb{R})$ with $\omega'(0) = 0$ such that

$$|\varphi(x, t) - \varphi(\bar{x}, \bar{t}) - \varphi_t(x, t)(t - \bar{t})| \leq f(|x - \bar{x}|) + \omega(t - \bar{t}).$$

Then it is enough to replace φ by

$$\psi(x, t) := \varphi_t(z)(t - \bar{t}) + f(|x - \bar{x}|) + \omega(t - \bar{t}).$$

Finally, in view of Lemma 2.13 below, one can assume that the superlevel set of φ in Definition 2.11-ii) is not critical. We have shown, in particular, that Definitions 2.2 and 2.11 are equivalent.

Lemma 2.13. *Let $Q \in C^\infty(\mathbb{R}^N)$, $Q \geq 0$ with equality only for $x = 0$, Q convex in B_1 , and constant in $\mathbb{R}^N \setminus B_2$.*

Let $\varphi \in C^2(\mathbb{R}^N)$, and let \bar{x} be such that $D\varphi(\bar{x}) \neq 0$. For every $\eta \in \mathbb{R}$ set

$$\varphi^\eta(x) := \varphi(x) + \eta Q(x - \bar{x}).$$

Then, for almost every η small enough the $\varphi(\bar{x})$ -level set of φ^η is not critical.

Proof. Let $B(\bar{x}, \delta)$ be a neighborhood of \bar{x} where $D\varphi \neq 0$. Clearly in $B(\bar{x}, \delta)$ $D\varphi + \eta DQ(x - \bar{x}) \neq 0$ if η is small enough.

Then, in $\mathbb{R}^N \setminus \overline{B(\bar{x}, \delta/2)}$, we consider the C^∞ function

$$x \mapsto -\frac{\varphi(x) - \varphi(\bar{x})}{Q(x - \bar{x})},$$

and by Sard's theorem, we know that for a.e. $\eta > 0$, the level set η of this function is not critical. This means that for all $x \notin \overline{B(\bar{x}, \delta/2)}$ with $\varphi(x) + \eta Q(x - \bar{x}) = \varphi(\bar{x})$, one has

$$\begin{aligned} 0 &\neq \frac{1}{Q^2(x - \bar{x})} (-D\varphi(x)Q(x - \bar{x}) + DQ(x - \bar{x})(\varphi(x) - \varphi(\bar{x}))) \\ &= -\frac{1}{Q(x - \bar{x})} (D\varphi(x) + \eta DQ(x - \bar{x})), \end{aligned}$$

so that the $\varphi(\bar{x})$ -level set of φ^η is not critical. \square

We now introduce the notion of parabolic sub/superjets.

Definition 2.14. Let $u : \mathbb{R}^N \times (0, T) \rightarrow \mathbb{R}$ be upper semicontinuous at (x, t) . We say that $(a, p, X) \in \mathbb{R} \times \mathbb{R}^N \times \mathbb{M}_{sym}^{N \times N}$ is in the parabolic superjet $\mathcal{P}^{2,+}u(x, t)$ of u at (x, t) , if

$$u(y, s) \leq u(x, t) + a(s - t) + p \cdot (y - x) + \frac{1}{2}X(y - x) \cdot (y - x) + o(|t - s| + |x - y|^2)$$

for (y, s) in a neighborhood of (x, t) . If u is lower semicontinuous at (x, t) we can define the parabolic subjet $\mathcal{P}^{2,-}u(x, t)$ of u at (x, t) as $\mathcal{P}^{2,-}u(x, t) := -\mathcal{P}^{2,+}(-u)(x, t)$.

The next lemma provides another equivalent definition of viscosity solutions in terms of the superlevel sets of u and the corresponding parabolic jets.

Lemma 2.15. *Let u be a viscosity subsolution of (2.4) in the sense of Definition 2.11. Then, for all (x, t) in $\mathbb{R}^N \times (0, T)$, if $(a, p, X) \in \mathcal{P}^{2,+}u(x, t)$, and $p \neq 0$, then*

$$(2.15) \quad a + |p|\kappa_*(x, p, X, \{y : u(y, t) \geq u(x, t)\}) \leq 0.$$

A similar statement holds for supersolutions.

Proof of Lemma 2.15. By definition of parabolic subjets, given $\varepsilon > 0$, $\delta > 0$, there exists a neighborhood U of (x, t) in $\mathbb{R}^N \times (0, t]$ where

$$u(y, s) \leq u(x, t) + (a - \varepsilon)(s - t) + p \cdot (y - x) + \frac{1}{2}(X + \delta I)(y - x) \cdot (y - x)$$

with a strict inequality if $y \neq x$ or $s < t$. Let $p_{\varepsilon, \delta} : \mathbb{R}^N \times [0, T]$ be a continuous function such that

$$p_{\varepsilon, \delta}(y, s) = u(x, t) + (a - \varepsilon)(s - t) + p \cdot (y - x) + \frac{1}{2}(X + \delta I)(y - x) \cdot (y - x)$$

in U , $p_{\varepsilon, \delta} \geq u$ in $\mathbb{R}^N \times (0, t]$, with equality only on (x, t) , $p_{\varepsilon, \delta} \geq u + c$ in $(\mathbb{R}^N \times (0, t]) \setminus U$ for some $c > 0$, and $p_{\varepsilon, \delta}$ is constant (possibly depending on time) in $(\mathbb{R}^N \setminus \mathcal{K})$, where also u is constant. Consider a decreasing sequence ψ^k of smooth functions, such that ψ^k is constant in $(\mathbb{R}^N \setminus \mathcal{K})$, $\inf_k \psi^k = u$, and $\psi^k \geq u + 1/k$. Such a sequence exists because u is upper-semicontinuous. Let $\varphi^k := \min\{\psi^k, p_{\varepsilon, \delta}\}$, so that $\varphi^k > u$ in $\mathbb{R}^N \times (0, t]$, except at (x, t) where equality holds, and $\varphi^k = p_{\varepsilon, \delta}$ near (x, t) .

For any $n \in \mathbb{N}$ large enough, the function $(y, s) \mapsto u(y, s) - \varphi^k(y, s) - 1/[n(t-s)]$ attains a maximum at a point $z_n = (y_n, s_n) \in (0, t) \times \mathbb{R}^N$, where $z_n \rightarrow z = (x, t)$ as $n \rightarrow \infty$. Moreover, $D\varphi^k(z_n) = p + (X + \delta I)(y_n - x) \neq 0$ for n large.

Hence, by Definition 2.11 of a viscosity subsolution,

$$\begin{aligned} \varphi_t^k(z_n) + \frac{1}{n(t-s_n)^2} \\ + |D\varphi^k(z_n)| \kappa_*(y_n, D\varphi^k(z_n), D^2\varphi^k(z_n), \{\varphi^k(\cdot, s_n) \geq \varphi^k(z_n)\}) \leq 0. \end{aligned}$$

Since $\partial_t \varphi_t^k(z_n) = a - \varepsilon$ it follows that

$$a + |D\varphi^k(z_n)| \kappa_*(y_n, D\varphi^k(y_n, s_n), D^2\varphi^k(y_n, s_n), \{\varphi^k(\cdot, s_n) \geq \varphi^k(y_n, s_n)\}) \leq \varepsilon.$$

Letting $n \rightarrow \infty$ and invoking Lemma 2.9 we obtain

$$a + |D\varphi^k(x, t)| \kappa_*(x, D\varphi^k(x, t), D^2\varphi^k(x, t), \{\varphi^k(\cdot, t) \geq \varphi^k(x, t)\}) \leq \varepsilon,$$

that is

$$a + |p| \kappa_*(x, p, X + \delta I, \{\varphi^k(\cdot, t) \geq \varphi^k(x, t)\}) \leq \varepsilon.$$

Now, as $\{\varphi^k(\cdot, t) \geq \varphi^k(x, t)\}$ is a decreasing sequence converging to $\{u(\cdot, t) \geq u(x, t)\}$, we get that $(p, X + \delta I, \{\varphi^k(\cdot, t) \geq \varphi^k(x, t)\}) \rightarrow (p, X + \delta I, \{u(\cdot, t) \geq u(x, t)\})$ with uniform superjet, as $k \rightarrow \infty$. Therefore, by Lemma 2.8 we infer

$$a + |p| \kappa_*(x, p, X + \delta I, \{u(\cdot, t) \geq u(x, t)\}) \leq \varepsilon.$$

The conclusion follows by applying again Lemma 2.8, after observing that

$$(p, X + \delta I, \{u(\cdot, t) \geq u(x, t)\}) \rightarrow (p, X, \{u(\cdot, t) \geq u(x, t)\})$$

with uniform superjet, as $\delta \rightarrow 0$. \square

In the next lemma we show that equation (2.4) is satisfied in a suitable viscosity sense also for $t = T$. To this purpose, we notice that the notion of admissible test functions φ given in Definition 2.1 can be extended also at points $(\hat{x}, T) \in \mathbb{R}^N \times \{T\}$ without any change. This is a classical fact, we adapt here the proof in [28].

Lemma 2.16. *Let $u \in USC(\mathbb{R}^N \times [0, T])$ be a subsolution of (2.4). If φ is admissible at (\hat{x}, T) and $u - \varphi$ has a (one-sided w.r.t. time) maximum in $\mathbb{R}^N \times [0, T]$ at (\hat{x}, T) , then i) and ii) of Definition 2.11 are satisfied at (\hat{x}, T) . An analogous statement holds for supersolutions.*

Proof. First assume that $D\varphi(\hat{x}, T) \neq 0$. As usual, we can assume that the maximum is strict. For n large enough, the function $u(x, t) - \varphi(x, t) - 1/[n(T-t)]$ has a maximum at a point $z_n := (\hat{x}_n, t_n) \in \mathbb{R}^N \times (0, T)$ converging to $z := (\hat{x}, T)$ as $n \rightarrow \infty$. Since u is a subsolution in $\mathbb{R}^N \times (0, T)$, for n large enough we have

$$\varphi_t(z_n) + \frac{1}{n(T-t_n)^2} + |D\varphi(z_n)| \kappa_*(x_n, D\varphi(z_n), D^2\varphi(z_n), \{\varphi(\cdot, t_n) \geq \varphi(z_n)\}) \leq 0.$$

Letting $n \rightarrow \infty$, the conclusion follows from Lemma 2.9.

If now $D\varphi(z) = 0$, we follow the lines of [28, Proposition 1.3]. Since φ is admissible at z , there are $f \in \mathcal{F}$ and $\omega \in C^\infty(\mathbb{R})$ with $\omega'(0) = 0$ such that

$$|\varphi(x, t) - \varphi(z) - \varphi_t(z)(t - T)| \leq f(|x - \hat{x}|) + \omega(t - T).$$

Set

$$\begin{aligned} \psi(x, t) &= \varphi_t(z)(t - T) + 2f(|x - \hat{x}|) + 2\omega(t - T), \\ (2.16) \quad \psi_n(x, t) &= \psi(x, t) - \frac{1}{n(T-t)}. \end{aligned}$$

We have that $u - \psi$ has a strict maximum at z . Hence for n large enough $u - \psi_n$ has a maximum at $z_n = (\hat{x}_n, t_n) \in \mathbb{R}^N \times (0, T)$, with $z_n \rightarrow z$. As ψ_n is admissible at z_n and u is a subsolution, we have

$$(2.17) \quad \varphi_t(z) + \omega'(t_n - T) + 2f'(|\hat{x}_n - x|)\kappa_*(\hat{x}_n, D\psi_n(\hat{x}_n), D^2\psi_n(\hat{x}_n), \{\psi_n(\cdot, t_n) \geq \psi_n(z_n)\}) \leq 0$$

if $\hat{x}_n \neq x$, while $\varphi_t(z) + \omega'(t_n - T) \leq 0$ if $\hat{x}_n = x$. Note that $\{\psi_n(\cdot, t_n) \geq \psi_n(z_n)\} = \mathbb{R}^N \setminus B_{f^{-1}(|\hat{x}_n - x|)}(x)$. Letting $n \rightarrow \infty$, we get $\varphi_t(z) \leq 0$ thanks to (2.6). Hence, as claimed, u is a subsolution. \square

Remark 2.17. A similar reasoning shows that the alternative characterization of sub- and super-solutions provided by Lemma 2.15 holds also at points of the form (x, T) .

2.6. Existence of a viscosity solution. Let $u_0 : \mathbb{R}^N \mapsto \mathbb{R}$ be a continuous function, constant out of a compact set \mathcal{K} . The existence of a viscosity solution to the Cauchy problem (2.4) follows by standard arguments once the existence of at least one supersolution and a stability property for supersolutions are established. We start by establishing a comparison principle with classical subsolutions and super-solutions.

Lemma 2.18. *Let $T > 0$ be fixed and let $u \in USC(\mathbb{R}^N \times [0, T])$ be a subsolution of (2.4). Let $\varphi \in C^2(\mathbb{R}^N \times [0, T])$ be admissible at all points in the sense of Definition 2.1 and such that $\varphi(x, 0) \geq u_0(x)$ for all $x \in \mathbb{R}^N$,*

$$(2.18) \quad \varphi_t(x, t) + |D\varphi(x, t)|k_*(x, D\varphi(x, t), D^2\varphi(x, t), \{\varphi(\cdot, t) \geq \varphi(x, t)\}) \geq 0$$

for all $(x, t) \in \mathbb{R}^N \times [0, T]$, with $|D\varphi(x, t)| \neq 0$, and $\varphi_t(x, t) \geq 0$ if $|D\varphi(x, t)| = 0$. Then, $\varphi \geq u$ in $\mathbb{R}^N \times [0, T]$. An analogous comparison principle holds between viscosity supersolutions and classical subsolutions.

Proof. Assume toward a contradiction that there exists $\delta > 0$ and $(x, t) \in \mathbb{R}^N \times (0, T)$ such that $(u - \varphi)(x, t) > \delta t$. Then, setting $\varphi_\delta(x, t) := \varphi(x, t) + \delta t$, we have $\max_{\mathbb{R}^N \times [0, T]} u - \varphi_\delta > 0$. Let $z_\delta := (x_\delta, t_\delta)$ be a maximum point and note that necessarily $t_\delta > 0$. If $D\varphi_\delta(z_\delta) = 0$, recalling the definition of a subsolution we get the contradiction $\delta \leq (\varphi_\delta)_t(z_\delta) \leq 0$. If $D\varphi_\delta(z_\delta) \neq 0$, recalling again Definition 2.11 of subsolution we get

$$\varphi_t(z_\delta) + \delta + |D\varphi(z_\delta)|\kappa_*(x_\delta, D\varphi(z_\delta), D^2\varphi(z_\delta), \{\varphi(\cdot, t_\delta) \geq \varphi(z_\delta)\}) \leq 0,$$

which contradicts (2.18). The proof of the second part of the statement is completely analogous. \square

We now prove a useful confinement condition.

Lemma 2.19. *Let $R, T > 0$ be fixed. There exists a constant $R' > R$ such that if $u \in USC(\mathbb{R}^N \times [0, T])$ is a subsolution of (2.4) with $u(x, 0) \leq C_0$ for $|x| \geq R$, then*

$$u(x, t) \leq C_0 \quad \text{for } |x| > R' \text{ and } t \in [0, T].$$

Analogously, if $u \in LSC(\mathbb{R}^N \times [0, T])$ is a supersolution of (2.4) with $u(x, 0) \geq C_0$ for $|x| \geq R$, then

$$u(x, t) \geq C_0 \quad \text{for } |x| > R' \text{ and } t \in [0, T].$$

Proof. We start by considering the case where u is a subsolution. We show only the first part, since the other statement is the same after a change of sign. Let $\psi \in C^\infty([0, +\infty))$ be such that $\psi'(0) = 0$, $\psi(s) \equiv C_0$ for $s \geq 2R$, ψ strictly decreasing in $[0, 2R]$, and $\psi(|x|) \geq u(x, 0)$ for all $x \in \mathbb{R}^N$. We now construct a test

function φ , by letting all the superlevel sets of $\psi(|\cdot|)$ expand with constant normal velocity equal to K , where K is the constant appearing in (2.3). Precisely, we set

$$(2.19) \quad \varphi(x, t) := \begin{cases} \psi(|x| - Kt) & \text{if } |x| \leq 2R + Kt, \\ C_0 & \text{otherwise.} \end{cases}$$

We can always assume that ψ is flat enough nearby the points where $\psi' = 0$, so that φ is admissible (see Definition 2.1). The lemma is proven (with $R' := 2R + KT$) once we show that $\varphi \geq u$. To this aim observe that $\varphi_t(x, t) = K|D\varphi(x, t)| \geq 0$ for all (x, t) and

$$0 = \varphi_t(x, t) - K|D\varphi(x, t)| \\ < \varphi_t(x, t) + |D\varphi(x, t)|\kappa_*(x, D\varphi(x, t), D^2\varphi(x, t), \{\varphi(\cdot, t) \geq \varphi(x, t)\})$$

whenever $|D\varphi(x, t)| \neq 0$. The conclusion follows from Lemma 2.18. \square

It is very easy to show that, as in the classical case, the maximum of two subsolutions is still a subsolution. In the following we show that the notion of subsolution is stable also with respect to taking upper relaxed limits.

Proposition 2.20. *Let $(u_n)_{n \geq 1}$ be a sequence of viscosity subsolutions such that $u_n = c_n$ in $(\mathbb{R}^N \setminus \mathcal{K}) \times [0, T)$, for some constant $c_n \in \mathbb{R}$ and some compact $\mathcal{K} \subseteq \mathbb{R}^N$. Let, for any $z = (x, t)$,*

$$(2.20) \quad u^*(z) = \lim_{r \downarrow 0} \sup \left\{ u_n(\zeta) : |z - \zeta| \leq r, n \geq \frac{1}{r} \right\}.$$

If $u^(z) < +\infty$ for all z , then u^* is a subsolution.*

Of course, a symmetric result holds for supersolutions.

Proof. Let $A \subset (0, T)$ be an open interval and let $\varphi : \mathbb{R}^N \times \bar{A} \rightarrow \mathbb{R}$ be an admissible test function at $z = (x, t)$ with $\varphi(\cdot, s) = C(s)$ in $(\mathbb{R}^N \setminus \tilde{\mathcal{K}}) \times \bar{A}$ for some compact set $\tilde{\mathcal{K}}$ and for all $s \in \bar{A}$, and such that $u - \varphi$ has a strict maximum at z . Assume first that $D\varphi(z) \neq 0$. Let z_n be a maximum point of $u_n - \varphi$ in $(\mathcal{K} \cup \tilde{\mathcal{K}}) \times \bar{A}$. By standard arguments it follows that $z_n \rightarrow z$. Since for every n

$$\varphi_t(z_n) + |D\varphi(z_n)|\kappa_*(x, D\varphi(z_n), D^2\varphi(z_n), \{y : \varphi(y, t) \geq \varphi(z_n)\}) \leq 0,$$

by Lemma 2.9 we conclude that

$$\varphi_t(z) + |D\varphi(z)|\kappa_*(x, D\varphi(z), D^2\varphi(z), \{y : \varphi(y, t) \geq \varphi(z)\}) \leq 0.$$

If now $D\varphi(z) = 0$, we follow the lines of [28, Proposition 1.3]. Since φ is admissible at z , there are $\delta > 0$, $f \in \mathcal{F}$ and $\omega \in C^\infty(\mathbb{R})$ with $\omega'(0) = 0$, $\omega(t) > 0$ for $t > 0$ such that

$$|\varphi(y, s) - \varphi(z) - \varphi_t(z)(s - t)| \leq f(|x - y|) + \omega(s - t)$$

for all $(y, s) \in \mathbb{R}^N \times A$. Set

$$(2.21) \quad \psi(y, s) = \varphi_t(z)(s - t) + 2f(|y - x|) + 2\omega(s - t).$$

Note that $u - \psi$ has a unique maximum at z in $\mathbb{R}^N \times A$. Let $z_n = (y_n, s_n)$ be a maximum point of $u_n - \psi$ in $\mathbb{R}^N \times \bar{A}$. Then $z_n \rightarrow z$. If $D\psi(z_n) = 0$, then $y_n = x$ and ψ_n is admissible at z_n thanks to (2.21). We deduce $\varphi_t(z) + \omega'(s_n - t) \leq 0$. Otherwise $y_n \neq x$, ψ is still admissible at z_n and we have

$$(2.22) \quad \varphi_t(z) + \omega'(s_n - t) \\ + 2f'(|y_n - x|)\kappa_*(y_n, D\psi_n(y_n), D^2\psi(y_n), \{\psi(\cdot, s_n) \geq \psi(z_n)\}) \leq 0.$$

Note that $\{\psi(\cdot, s_n) \geq \psi(z_n)\} = \mathbb{R}^N \setminus B_{f^{-1}(|y_n - x|)}(x)$. Letting $n \rightarrow \infty$, we get $\varphi_t(z) \leq 0$ thanks to (2.6). Hence, as claimed, u is a subsolution. \square

We now can state a general existence result:

Theorem 2.21. *Let $u_0 : \mathbb{R}^N \rightarrow \mathbb{R}$ be a uniformly continuous function with $u_0 = C_0$ for $|x| \geq R$. Let R' be the constant given by Lemma 2.19. Then, there exists a viscosity solution $u : \mathbb{R}^N \times [0, T] \rightarrow \mathbb{R}$ of (2.4) with $u = C_0$ for $|x| \geq R'$.*

Proof. We sketch the proof of this result which follows from classical arguments (see [21, 28]) and it is based on Perron's method. Let φ be the function defined in (2.19), and notice that it is a supersolution. Then, we can set

$$(2.23) \quad u(x, t) = \inf\{v(x, t) : v \text{ is a supersolution of the Cauchy problem (2.4)}\}.$$

The fact that u is bounded from below easily follows by using the smooth barrier $C_0 + \lambda(C_0 - \varphi)$ as in the proof Lemma 2.19. Let u^* , u_* be the upper and lower semicontinuous envelopes of u , respectively. The fact that u_* is a supersolution follows from Proposition 2.20, observing that for each point $z = (x, t)$ we may find a suitable sequence of supersolutions $(v_n)_{n \geq 1}$ such that

$$u_*(z) = \lim_{r \downarrow 0} \inf \left\{ v_n(\zeta) : |z - \zeta| \leq r, n \geq \frac{1}{r} \right\}.$$

We now prove that $u_*(\cdot, 0) \geq u_0$ and $u^*(\cdot, 0) \leq u_0$. We only show the first inequality, since the second one can be established in an analogous manner.

Fix $f \in \mathcal{F}$ and for every $\bar{x} \in \mathbb{R}^N$, $\delta, m, n > 0$ set

$$\varphi_{\bar{x}, \delta}^{m, n}(x, t) := -mf(|x - \bar{x}|) - \delta - nt.$$

We can choose f in such a way that $\varphi_{\bar{x}, \delta}^{m, n}$ is admissible at all points in the sense of Definition 2.1 for all $\delta, m, n > 0$. Notice that for every fixed δ , if m is large enough (independent of n) we have $\varphi_{\bar{x}, \delta}^{m, n} \leq u_0$. Moreover, for every δ, m , if $|D\varphi_{\bar{x}, \delta}^{m, n}(x, t)| \neq 0$ one has

$$|D\varphi_{\bar{x}, \delta}^{m, n}(x, t)|\kappa(x, \{y : \varphi_{\bar{x}, \delta}^{m, n}(y, t) \geq \varphi_{\bar{x}, \delta}^{m, n}(x, t)\}) \leq C,$$

with $C > 0$ depending only on m . This is due to the admissibility of $f(|\cdot - \bar{x}|)$. Thus, since $(\varphi_{\bar{x}, \delta}^{m, n})_t(x, t) = -n$, if n is large enough we have that

$$(2.24) \quad (\varphi_{\bar{x}, \delta}^{m, n})_t(x, t) + |D\varphi_{\bar{x}, \delta}^{m, n}(x, t)|\kappa(x, \{y : \varphi_{\bar{x}, \delta}^{m, n}(y, t) \geq \varphi_{\bar{x}, \delta}^{m, n}(x, t)\}) < 0$$

for all $(x, t) \in \mathbb{R}^N \times [0, T]$, with $|D\varphi(x, t)| \neq 0$. Therefore there exist $m(\delta), n(\delta) > 0$ such that

$$\varphi_{\bar{x}, \delta} := \varphi_{\bar{x}, \delta}^{m(\delta), n(\delta)}$$

satisfies (2.24) and $\varphi_{\bar{x}, \delta} \leq u_0$. By Lemma 2.18 we deduce that any supersolution of the Cauchy problem (2.4) is greater than or equal to any $\varphi_{\bar{x}, \delta}$. In turn, $u \geq \varphi_{\bar{x}, \delta}$ so that also $u_* \geq \varphi_{\bar{x}, \delta}$ for all $\bar{x} \in \mathbb{R}^N$, $\delta > 0$. By the very definition of $\varphi_{\bar{x}, \delta}$ and by the arbitrariness of δ we conclude that $u_*(\cdot, 0) \geq u_0$.

Since $u_*(x, 0) \geq u_0(x)$ and u_* is a supersolution, it follows from (2.23) that $u \leq u_*$ and thus, in fact,

$$(2.25) \quad u = u_*.$$

We now show that u^* is a subsolution. To this purpose we argue by contradiction, by assuming that either there exists a function φ as in Definition 2.2 and a point $\bar{z} = (\bar{x}, \bar{t})$ such that $u^* - \varphi$ has a strict maximum at \bar{z} , with $u^*(\bar{z}) = \varphi(\bar{z})$, $\{\varphi(\cdot, \bar{t}) = \varphi(\bar{x}, \bar{t})\}$ is not critical, and

$$\varphi_t(\bar{z}) + |D\varphi(\bar{z})|\kappa(\bar{x}, \{y : \varphi(y, \bar{t}) \geq \varphi(\bar{z})\}) > 0,$$

or there exists a test function φ and a point of strict maximum \bar{z} for $u^* - \varphi$ such that $u^*(\bar{z}) = \varphi(\bar{z})$, $D\varphi(\bar{z}) = 0$, φ is admissible at \bar{z} , and $\varphi_t(\bar{z}) > 0$.

We start by considering the first case. For all $\delta > 0$ sufficiently small set

$$u_\delta := \min\{u, \varphi - \delta\}.$$

Recalling (2.25), we have that u_δ is lower semicontinuous. Moreover, the set where $u \neq u_\delta$ is contained in any small ball $B_r(\bar{z})$, provided that δ is small enough. We fix such a small ball (and correspondingly δ) so that $B_r(\bar{z}) \subset \mathbb{R}^N \times (0, T)$, the level sets $\{y : \varphi(y, t) = \varphi(x, t)\}$ are not critical for all $(x, t) \in B_r(\bar{z})$, and

$$(2.26) \quad \varphi_t(x, t) + |D\varphi(x, t)| \kappa(x, \{y : \varphi(y, t) \geq \varphi(x, t)\}) > 0.$$

We claim that u_δ is a supersolution for (2.4). Indeed, clearly $u_\delta(\cdot, 0) \geq u_0$. Now let ψ be a test function as in Definition 2.2 and assume that $u_\delta - \psi$ attains a maximum at $z_\delta = (x_\delta, t_\delta)$. Assume first that $\{y : \psi(y, t_\delta) = \psi(z_\delta)\}$ is not critical. If $u_\delta(z_\delta) = u(z_\delta)$, then z_δ is also a maximum for $u - \psi$. Recalling that u is a supersolution, we infer

$$\psi_t(z_\delta) + |D\psi(z_\delta)| \kappa(x_\delta, \{y : \psi(y, t_\delta) \geq \psi(z_\delta)\}) \geq 0.$$

Otherwise $u_\delta(z_\delta) = \varphi(z_\delta) - \delta$ and thus $z_\delta \in B_r(\bar{z})$ and z_δ is a maximum point for $\varphi - \psi$. In particular, $\psi_t(z_\delta) = \varphi_t(z_\delta)$, $D\psi(z_\delta) = D\varphi(z_\delta)$, and $\{y : \psi(y, t_\delta) \geq \psi(z_\delta)\} \subseteq \{y : \varphi(y, t_\delta) \geq \varphi(z_\delta)\}$. Recalling (2.26) and the monotonicity of κ , we have

$$\begin{aligned} \psi_t(z_\delta) + |D\psi(z_\delta)| \kappa(x_\delta, \{y : \psi(y, t_\delta) \geq \psi(z_\delta)\}) \\ \geq \varphi_t(z_\delta) + |D\varphi(z_\delta)| \kappa(x_\delta, \{y : \varphi(y, t_\delta) \geq \varphi(z_\delta)\}) > 0. \end{aligned}$$

Note that if $D\psi(z_\delta) = 0$, then necessarily $u_\delta(z_\delta) = u(z_\delta)$, z_δ is a maximum point for $u - \psi$ and thus $\psi_t(z_\delta) \geq 0$, since u is a supersolution. This concludes the proof of the fact that u_δ is a supersolution. Let now $z_n \rightarrow \bar{z}$ be such that $u(z_n) \rightarrow u^*(\bar{z})$. Thus, for n large enough we have

$$u_\delta(z_n) \leq \varphi(z_n) - \delta < \varphi(\bar{z}) - \frac{\delta}{2} = u^*(\bar{z}) - \frac{\delta}{2} \leq u(z_n),$$

which contradicts the minimality of u .

To treat the case $D\varphi(\bar{z}) = 0$ one repeats the same construction, but with φ replaced by

$$\tilde{\varphi}(x, t) = \varphi(\bar{z}) + \varphi_t(\bar{z})(t - \bar{t}) + 2f(|x - \bar{x}|) + 2\omega(t - \bar{t}),$$

with f and ω chosen as in (2.21). \square

3. UNIQUENESS OF VISCOSITY SOLUTIONS

In this section we will prove that, under some additional assumptions, (2.4) admits a unique viscosity solution. In the first subsection, we consider *first order* geometric flows, corresponding to the case where the relaxed curvatures κ_* and κ^* depend only on the first order super-jet and sub-jet, respectively. Examples of relevant first-order flows are given in Section 5.

In the second subsection, we deal with truly second order flows, under an additional uniform continuity assumption on the nonlocal curvature κ .

Before entering the details of the uniqueness theory, it is convenient to give the following definition and state an auxiliary lemma.

Definition 3.1. We say that a set valued function $F : [0, T] \rightarrow \mathfrak{M}$ is a subsolution of the geometric flow (1.1) if $\chi_{F(t)}$ is a viscosity subsolution of (2.4) in the sense of Definition 2.11. The definition of supersolutions and solutions of the geometric flow are analogous.

Lemma 3.2. *Let u be a subsolution of (2.4). Then, for every $s \in \mathbb{R}$ the set function $t \rightarrow F(t) := \{u(\cdot, t) \geq s\}$ is a subsolution of the geometric flow (1.1), according with Definition 3.1. The analogous statement holds for supersolutions.*

The proof is classical and follows by approximating the Heavyside function as a supremum of smooth increasing functions H_n , so that $\chi_F(x, t) = \sup_n H_n(u(x, t) - s)$.

3.1. Uniqueness for first-order flows. Here we consider the case of curvatures, which generate a first order flow. Namely, we denote by $\mathfrak{C}^{1,1}$ the class of sets of \mathbb{R}^N , which are the closure of an open set of class $C^{1,1}$ with compact boundary, and we assume that the following property holds:

(FO): Let $\Sigma \in \mathfrak{C}^{1,1}$, let $x \in \partial\Sigma$, and let (p, X) and (p, Y) be elements of $\mathcal{J}_\Sigma^{2,+}(x)$ and $\mathcal{J}_\Sigma^{2,-}(x)$, respectively. Then,

$$(3.1) \quad \kappa_*(x, p, X, \Sigma) = \kappa^*(x, p, Y, \Sigma).$$

Note that the above assumption postulates that the semicontinuous extensions κ_* and κ^* are independent of the second derivative variables X and Y , at least on $C^{1,1}$ -sets. Under these circumstances, we may regard the common value of the quantities in (3.1) as an extension of the definition of curvature to sets of class $C^{1,1}$; i.e., for all $\Sigma \in \mathfrak{C}^{1,1}$ we may set

$$\begin{aligned} \kappa(x, \Sigma) &:= \kappa_*(x, p, X, \Sigma) = \kappa^*(x, p, Y, \Sigma) \\ &\text{for any } (p, X) \in \mathcal{J}_\Sigma^{2,+}(x) \text{ and } (p, Y) \in \mathcal{J}_\Sigma^{2,-}(x). \end{aligned}$$

In this situation, the problem becomes similar to the methodology developed in [12] by P. Cardaliaguet. In particular, as show the following Lemma 3.3, our extensions κ_* , κ^* correspond here precisely to the extensions h^\sharp , h^\flat found in eqn (6), (7) of [12] (with $h = -\kappa$). For completeness, and also because of slight differences (in particular, we have no sign restriction on our curvatures), we present here complete proofs of uniqueness, which rely as in [12] on Ilmanen's interposition lemma.

Lemma 3.3. *Assume that (FO) holds and let $F \in \mathfrak{M}$. Then, for any $(p, X) \in \mathcal{J}_F^{2,+}(x)$ we have*

$$(3.2) \quad \kappa_*(x, p, X, F) = \sup \{ \kappa(x, \Sigma) : \Sigma \in \mathfrak{C}^{1,1}, \\ F \subset \Sigma, x \in \partial\Sigma, \text{ and } p \perp \partial\Sigma \text{ at } x \}.$$

Analogously, for any $(p, Y) \in \mathcal{J}_F^{2,-}(x)$ we have

$$(3.3) \quad \kappa^*(x, p, Y, F) = \inf \{ \kappa(x, \Sigma) : \Sigma \in \mathfrak{C}^{1,1}, \\ \overset{\circ}{\Sigma} \subset F, x \in \partial\Sigma, \text{ and } p \perp \partial\Sigma \text{ at } x \}.$$

Proof. We only prove (3.2), the proof of (3.3) being analogous. Denote by $\underline{\kappa}(x, p, F)$ the quantity defined by the right-hand side of (3.2). Clearly, by definition of κ_* we immediately have that $\kappa_*(x, p, X, F) \leq \underline{\kappa}(x, p, F)$.

To prove the opposite inequality, fix $\varepsilon > 0$ and let Σ be a $C^{1,1}$ -set, admissible for the definition of $\underline{\kappa}(x, p, F)$, such that

$$(3.4) \quad \kappa(x, \Sigma) \geq \underline{\kappa}(x, p, F) - \varepsilon.$$

Moreover, let $A \in \mathfrak{C}$, admissible for the definition of $\kappa_*(x, p, X, \Sigma) = \kappa(x, \Sigma)$, such that

$$(3.5) \quad \kappa(x, A) \geq \kappa(x, \Sigma) - \varepsilon.$$

Since A is also admissible for F , we have

$$(3.6) \quad \kappa_*(x, p, X, F) \geq \kappa(x, A) \geq \kappa(x, \Sigma) - \varepsilon \geq \underline{\kappa}(x, p, F) - 2\varepsilon,$$

and the conclusion follows from the arbitrariness of ε . \square

We continue with the following lemma, which provides a crucial comparison property between κ_* and κ^* .

Lemma 3.4. *Assume that condition (FO) above holds and let F , G be a closed and an open set, respectively, with compact boundaries and such that $F \subset G$. Let $x \in \partial F$, $y \in \partial G$ satisfy*

$$(3.7) \quad |x - y| = \text{dist}(\partial F, \partial G).$$

Then, for all $(p, X) \in \mathcal{J}_F^{2,+}(x)$ and $(p, Y) \in \mathcal{J}_G^{2,-}(y)$, with $p := x - y$, we have

$$\kappa_*(x, p, X, F) \geq \kappa^*(y, p, Y, G).$$

Proof. Exploiting (3.7), we may apply the Ilmanen Interposition Lemma ([26]), to find a set $\Sigma \in \mathfrak{C}^{1,1}$ such that $F \subset \Sigma$, $\bar{\Sigma} \subset G$, and $[x, y] \cap \partial \Sigma = \{\hat{z}\}$, with \hat{z} satisfying

$$|x - \hat{z}| = \text{dist}(\partial F, \partial \Sigma) = |y - \hat{z}| = \text{dist}(\partial G, \partial \Sigma).$$

Here $[x, y]$ stands for the segment with endpoints x and y . In particular, $F \subset \Sigma + x - \hat{z}$ with $x \in \partial(\Sigma + x - \hat{z})$ and $p \perp \partial(\Sigma + x - \hat{z})$ at x . Analogously $\bar{\Sigma} + y - \hat{z} \subset G$, with $y \in \partial(\Sigma + y - \hat{z})$ and $p \perp \partial(\Sigma + y - \hat{z})$ at y . Recalling (3.2) and (3.3), we may conclude

$$\kappa_*(x, p, X, F) \geq \kappa(x, \Sigma + x - \hat{z}) = \kappa(x, \Sigma + y - \hat{z}) \geq \kappa^*(y, p, Y, G).$$

□

Uniqueness of viscosity solutions is a straightforward consequence of the following Comparison Principle, which is the main result of this subsection.

Theorem 3.5 (First Order Comparison Principle). *Assume that condition (FO) holds. Let $u \in USC(\mathbb{R}^N \times [0, T])$ and $v \in LSC(\mathbb{R}^N \times [0, T])$, both constant (spatially) out of a compact set, be a subsolution and a supersolution of (2.4), respectively. If $u(\cdot, 0) \leq v(\cdot, 0)$, then $u \leq v$ in $\mathbb{R}^N \times [0, T]$.*

Proof. Assume by contradiction that there exists $\bar{z} := (\bar{x}, \bar{t}) \in \mathbb{R}^N \times (0, T]$ such that $u(\bar{z}) - v(\bar{z}) > 0$. Let $f \in \mathcal{F}$, $\alpha, \varepsilon > 0$ and set

$$\Phi(x, t, y, s) := u(x, t) - v(y, s) - \alpha f(|x - y|) - \alpha(t - s)^2 - \varepsilon t - \varepsilon s.$$

Notice that Φ is u.s.c. Let $(\hat{x}, \hat{t}, \hat{y}, \hat{s}) \in \mathbb{R}^N \times [0, T] \times \mathbb{R}^N \times [0, T]$ be a maximum point of Φ . We may choose ε so small that the maximum is strictly positive. Moreover, as $\alpha \rightarrow \infty$ we clearly have $|\hat{x} - \hat{y}|, |\hat{s} - \hat{t}| \rightarrow 0$. Thus, since $\Phi(x, 0, x, 0) \leq 0$, we can choose α so large that \hat{s} and \hat{t} are strictly positive. We consider now two cases.

First case: $\hat{x} = \hat{y}$. Let

$$(3.8) \quad \varphi(x, t) := v(\hat{y}, \hat{s}) + \alpha f(|x - \hat{y}|) + \alpha(t - \hat{s})^2 + \varepsilon t + \varepsilon \hat{s}.$$

$$(3.9) \quad \psi(y, s) := u(\hat{x}, \hat{t}) - \alpha f(|\hat{x} - y|) - \alpha(\hat{t} - s)^2 - \varepsilon \hat{t} - \varepsilon s.$$

Since u is a subsolution and v is a supersolution we have

$$0 \geq \varphi_t(\hat{x}, \hat{t}) = 2\alpha(\hat{t} - \hat{s}) + \varepsilon, \quad 0 \leq \psi_t(\hat{y}, \hat{s}) = 2\alpha(\hat{t} - \hat{s}) - \varepsilon,$$

which yields a contradiction.

Second case: $\hat{x} \neq \hat{y}$. Note that

$$\left(2\alpha(\hat{t} - \hat{s}) + \varepsilon, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, X\right) \in \mathcal{P}^{2,+} u(\hat{x}, \hat{t}),$$

$$\left(2\alpha(\hat{t} - \hat{s}) - \varepsilon, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, -X\right) \in \mathcal{P}^{2,-} v(\hat{y}, \hat{s}),$$

where $\hat{p} := \hat{x} - \hat{y}$ and $X := D^2\varphi(\hat{x}, \hat{t})$, with φ defined in (3.8). Thus, by Lemma 2.15 and Remark 2.17, we have

$$(3.10) \quad \begin{aligned} 2\alpha(\hat{t} - \hat{s}) + \varepsilon + \kappa_* \left(\hat{x}, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, X, \{u(\cdot, \hat{t}) \geq u(\hat{x}, \hat{t})\} \right) &\leq 0, \\ 2\alpha(\hat{t} - \hat{s}) - \varepsilon + \kappa^* \left(\hat{y}, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, -X, \{v(\cdot, \hat{s}) > v(\hat{y}, \hat{s})\} \right) &\geq 0. \end{aligned}$$

Observe now that if $x \in \{u(\cdot, \hat{t}) \geq u(\hat{x}, \hat{t})\}$ and $|y - x| < |\hat{y} - \hat{x}|$, then

$$v(\hat{y}, \hat{s}) - v(y, \hat{s}) \leq u(\hat{x}, \hat{t}) - u(x, \hat{t}) + \alpha f(|x - y|) - \alpha f(|\hat{x} - \hat{y}|) < 0$$

so that $y \in \{v(\cdot, \hat{s}) > v(\hat{y}, \hat{s})\}$. In other words,

$$\{u(\cdot, \hat{t}) \geq u(\hat{x}, \hat{t})\} + B(0, |\hat{y} - \hat{x}|) \subset \{v(\cdot, \hat{s}) > v(\hat{y}, \hat{s})\},$$

which by Lemma 3.4 implies

$$\begin{aligned} \kappa_* \left(\hat{x}, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, X, \{u(\cdot, \hat{t}) \geq u(\hat{x}, \hat{t})\} \right) \\ \geq \kappa^* \left(\hat{y}, \alpha f'(|\hat{p}|) \frac{\hat{p}}{|\hat{p}|}, -X, \{v(\cdot, \hat{s}) > v(\hat{y}, \hat{s})\} \right). \end{aligned}$$

This inequality, combined with (3.10), easily leads to the contradiction $2\varepsilon \leq 0$. This concludes the proof of the theorem. \square

3.2. Uniqueness for second-order flows. Here we consider general second-order flows. In order to establish uniqueness we will need to assume the following reinforced continuity property, which replaces C) of Subsection 2.1:

C') Uniform continuity: Given $R > 0$, there exists a modulus of continuity ω_R such that the following holds. For all $E \in \mathfrak{C}$, $x \in \partial E$, such that E has both an internal and external ball condition of radius R at x , and for all $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ diffeomorphism of class $C^{\ell, \beta}$, with $\Phi(y) = y$ for $|y - x| \geq 1$, we have

$$|\kappa(x, E) - \kappa(\Phi(x), \Phi(E))| \leq \omega_R(\|\Phi - Id\|_{C^{\ell, \beta}}).$$

(We can observe that if Φ is a translation out of $B(x, 1)$, then the estimate still holds by translational invariance of the curvature.)

We now prove that the uniform continuity property stated in C') extends to κ_* and κ^* .

Lemma 3.6. *Assume that C') holds. Then, given $R > 0$, there exists a modulus of continuity ω_R such that the following holds. For all $F \in \mathfrak{M}$, $x \in \partial F$, with internal and external ball condition at x of radius R , any $(p, X) \in \mathcal{J}_F^{2, +}(x)$ with $p \neq 0$, $|X|/|p| \leq 1/R$, then for any $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ diffeomorphism of class $C^{\ell, \beta}$, we have*

$$\begin{aligned} |\kappa_*(x, p, X, F) - \kappa_*(\Phi(x), D(f \circ \Phi^{-1})(\Phi(x)), D^2(f \circ \Phi^{-1})(\Phi(x)), \Phi(F))| \\ \leq \omega_R(\|\Phi - Id\|_{C^{\ell, \beta}}) \end{aligned}$$

where $f(y) = (y - x) \cdot p + \frac{1}{2}X(y - x) \cdot (y - x)$. The same holds true for κ^* .

Proof. Let $E \in \mathfrak{C}$ with $E \supseteq F$ and $(p, X) \in \mathcal{J}_E^{2, -}(x)$. A first remark is that E has an inner ball condition at x of radius R , since it contains F . Given $R' < R$, and letting $B_{R'} = B(x - R'p/|p|, R')$ be the external ball of radius R' which touches ∂F at x (only), we observe that we may find a set $E' \in \mathfrak{C}$ such that $E' \subseteq E \setminus B_{R'}$ and $E' \supseteq F$, and still (since the ball $B_{R'}$ is also exterior and tangent to the set $\{f \geq 0\}$, thanks to the condition $|X|/|p| \leq 1/R$), $(p, X) \in \mathcal{J}_{E'}^{2, -}(x)$. By assumption A) one has $\kappa(x, E') \geq \kappa(x, E)$. By assumption C'),

$$\kappa(x, E') - \kappa(\Phi(x), \Phi(E')) \leq \omega_{R'}(\|\Phi - Id\|_{C^{\ell, \beta}}).$$

Since $\Phi(E') \in \mathfrak{C}$, $\Phi(E') \supseteq \Phi(F)$ and $(D(f \circ \Phi^{-1})(\Phi(x)), D^2(f \circ \Phi^{-1})(\Phi(x))) \in \mathcal{J}_{\Phi(E')}^{2,-}(\Phi(x))$, then

$$\begin{aligned} \kappa_*(\Phi(x), D(f \circ \Phi^{-1})(\Phi(x)), D^2(f \circ \Phi^{-1})(\Phi(x)), \Phi(F)) \\ \geq \kappa(\Phi(x), \Phi(E')) \geq \kappa(x, E') - \omega_{R'}(\|\Phi - Id\|_{C^{\ell,\beta}}) \\ \geq \kappa(x, E) - \omega_{R'}(\|\Phi - Id\|_{C^{\ell,\beta}}). \end{aligned}$$

Taking the the supremum over all suitable sets E , we deduce

$$\begin{aligned} \kappa_*(\Phi(x), D(f \circ \Phi^{-1})(\Phi(x)), D^2(f \circ \Phi^{-1})(\Phi(x)), \Phi(F)) \\ \geq \kappa_*(x, p, X, F) - \omega_{R'}(\|\Phi - Id\|_{C^{\ell,\beta}}). \end{aligned}$$

The other inequality in order to conclude the proof (possibly redefining slightly ω_R) follows analogously, swiching the role of E with $\Phi(E)$. \square

Now, if C' holds, we also deduce a natural comparison property for the curvatures κ_* , κ^* of sets included in one another with a unique contact point.

Lemma 3.7. *Assume C' holds. Let $x \in \mathbb{R}^N$, $F, G \in \mathfrak{M}$ with $F \subset G \cup \{x\}$ and $\partial F \cap \partial G = \{x\}$. Let $(p, X) \in \mathcal{J}_F^{2,+}(x)$, $(p, Y) \in \mathcal{J}_G^{2,-}(x)$, with $X \leq Y$. Then,*

$$\kappa_*(x, p, X, F) \geq \kappa^*(x, p, Y, G).$$

Proof. First we observe that if $X < Y$ then one may find X', Y' with $X < X' < Y' < Y$ so that near the contact point x , F lies inside the set $\{\langle p, y - x \rangle + \langle X'(y - x), y - x \rangle / 2 \geq 0\}$ while G contains $\{\langle p, y - x \rangle + \langle Y'(y - x), y - x \rangle / 2 > 0\}$. Then, since x is the unique contact point of ∂F and ∂G , one can build a set $E \in \mathfrak{C}$ with jet (p, X') at x and $F \subseteq E$, $\overset{\circ}{E} \subseteq G$. It follows, by definition, that

$$\kappa_*(x, p, X, F) \geq \kappa(x, E) \geq \kappa^*(x, p, Y, G).$$

Now, if $X \not\leq Y$, we let $F' = F \cup B$ where $B = B(x + Rp/|p|, R)$ with $R < |p|/|X|$ small enough so that x remains the unique point in $\partial F' \cap \partial G$. This new set has both an internal and external ball condition of radius R at x , and one still has $(x, p, X) \in \mathcal{J}_{F'}^{2,+}(x)$, moreover since $F \subset F'$, $\kappa_*(x, p, X, F) \geq \kappa_*(x, p, X, F')$. We can find a diffeomorphism of the form $\Phi_\varepsilon(y) = y + \varepsilon\eta(y)p$ where $\eta : \mathbb{R}^d \rightarrow [0, 1]$ is a smooth function with support in a neighborhood of x , with $\eta(x) = 0$ and $D^2\eta(x) = I$, such that the set $\Phi_\varepsilon(F')$ still has x as unique contact point with ∂G . Lemma 3.6 ensures that $\kappa_*(x, p, X, F') \geq \kappa_*(x, p, X_\varepsilon, \Phi_\varepsilon(F')) - \omega_R(\varepsilon\|\eta\|_{C^{\ell,\beta}}|p|)$, where $X_\varepsilon = X - \varepsilon|p|^2I$. Since $X_\varepsilon < Y$, one has $\kappa_*(x, p, X_\varepsilon, \Phi_\varepsilon(F')) \geq \kappa^*(x, p, Y, G)$, hence

$$\kappa_*(x, p, X, F) \geq \kappa^*(x, p, Y, G) - \omega_R(\varepsilon\|\eta\|_{C^{\ell,\beta}}|p|)$$

and sending ε to zero we recover the thesis of the Lemma. \square

As in the previous subsection, uniqueness of viscosity solutions is a straightforward consequence of the following Comparison Principle, which is the main result of this subsection.

Theorem 3.8 (Second Order Comparison Principle). *Assume C' holds. Let $u \in USC(\mathbb{R}^N \times [0, T])$ and $v \in LSC(\mathbb{R}^N \times [0, T])$, both constant (spatially) out of a compact set, be a subsolution and a supersolution of (2.4), respectively. If $u(\cdot, 0) \leq v(\cdot, 0)$, then $u \leq v$ in $\mathbb{R}^N \times [0, T]$.*

Proof. Without loss of generality we can assume $u(\cdot, 0) < v(\cdot, 0)$. Assume by contradiction that there exists $a \in \mathbb{R}$ and $t \in (0, T]$ such that $F(t) := \{u(\cdot, t) \geq a\}$ is not contained in $G(t) := \{v(\cdot, t) > a\}$.

Notice that, since $u(\cdot, 0) < v(\cdot, 0)$, we have $F(0) \subset G(0)$. A first remark is that we can assume, without loss of generality, that the sets $F(t)$ satisfy an internal ball condition with some fixed radius $r > 0$, at all time, while $G(t)$ satisfy an external

ball condition with same radius. Indeed, we can always replace F and G with, respectively, the sets

$$F(t) + \overline{B(0, r)} = \bigcup_{|z| \leq r} (z + F(t)) \quad \text{and} \quad \{x : B(x, r) \subset G(t)\}$$

for some $r > 0$, which are still, respectively, a sub and a super-solution of (1.1); moreover if r is small enough, the inclusion $F(0) \subset G(0)$ is preserved.

Let $f \in \mathcal{F} \cap C^{\ell, \beta}$, and let

$$(3.11) \quad u_F^\lambda(x, t) := \max_{\xi \in \mathbb{R}^N, \tau \in [t-T, t]} \chi_{F(t-\tau)}(x - \xi) - \lambda(f(|\xi|) + \tau^2),$$

$$(3.12) \quad v_G^\lambda(x, t) := \min_{\xi \in \mathbb{R}^N, \tau \in [t-T, t]} \chi_{G(t-\tau)}(x - \xi) + \lambda(f(|\xi|) + \tau^2)$$

Since $F(0) \subset G(0)$, for λ large enough $u_F^\lambda(\cdot, 0) \leq v_G^\lambda(\cdot, 0)$. Then, the function

$$\Phi(x, t, y, s) := u_F^\lambda(x, t) - v_G^\lambda(y, s) - \varepsilon(t + s) - \lambda(f(|x - y|) + |t - s|^2)$$

is semiconvex, and for $\varepsilon > 0$ small and λ large enough admits a positive maximum at some $(x_0, t_0, y_0, s_0) \in \mathbb{R}^N \times [0, T] \times \mathbb{R}^N \times [0, T]$ with $t_0, s_0 > 0$.

First case: $x_0 = y_0$. Let

$$\varphi(x, t) := v_G^\lambda(y_0, s_0) + \lambda f(|x - y_0|) + \lambda(t - s_0)^2 + \varepsilon t + \varepsilon s_0.$$

$$\psi(y, s) := u_F^\lambda(x_0, t_0) - \lambda f(|x_0 - y|) - \lambda(t_0 - s)^2 - \varepsilon t_0 - \varepsilon s.$$

We observe that by construction, u_F^λ is a subsolution and v_G^λ is a supersolution on $\mathbb{R}^N \times [2/\sqrt{\lambda}, T]$ (we need $t \geq 2/\sqrt{\lambda}$ to ensure that the max in (3.11) is not reached at $\tau = t$, observe though that if λ is large enough one will have $t_0, s_0 > 2/\sqrt{\lambda}$). Hence, we have

$$0 \geq \varphi_t(x_0, t_0) = 2\lambda(t_0 - s_0) + \varepsilon, \quad 0 \leq \psi_t(y_0, s_0) = 2\lambda(t_0 - s_0) - \varepsilon,$$

which yield a contradiction.

Second case: $x_0 \neq y_0$. We can always assume (choosing λ large enough) that $f(|x_0 - y_0|) < 1$. Moreover, we have

$$(3.13) \quad u_F^\lambda(x_0, t_0) < 1.$$

Indeed, observe that $u_F^\lambda(x, t) = 1$ if and only if $x \in F(t)$, that $Du_F^\lambda(x, t) = 0$ on $F(t)$, and $Du_F^\lambda(x_0, t_0) = D_x f(|x_0 - y_0|) \neq 0$. Thus, x_0 can not belong to $F(t_0)$.

Let $q : [0, +\infty] \rightarrow [0, 1]$ be a smooth, nondecreasing, function with $q(r) = r^4$ for $r < 1/2$ and $q(r) = 1$ for $r > 3/2$. For $\rho > 0$, let then

$$\Phi_\rho(x, t, y, s) := \Phi(x, t, y, s) - \rho[q(|x - x_0|) + q(|y - y_0|) + q(|t - t_0|) + q(|s - s_0|)],$$

so that (x_0, t_0, y_0, s_0) is a strict maximum of Φ_ρ . Let $\eta : \mathbb{R}^N \rightarrow \mathbb{R}$ be a smooth cut-off function, with compact support and equal to one in a neighborhood U of the origin. For every $\Delta := (\zeta_u, h_u, \zeta_v, h_v) \in \mathbb{R}^N \times \mathbb{R} \times \mathbb{R}^N \times \mathbb{R}$, the function

$$\Phi_\rho(x, t, y, s) - \left(\eta(x - x_0)(\xi_u, h_u) \cdot (x, t) + \eta(y - y_0)(\xi_v, h_v) \cdot (y, s) \right)$$

is maximized at some $(x_\Delta, t_\Delta, y_\Delta, s_\Delta)$ such that

$$(x_\Delta, t_\Delta, y_\Delta, s_\Delta) \rightarrow (x_0, t_0, y_0, s_0) \quad \text{as } |\Delta| \rightarrow 0.$$

Thus, by Jensen's Lemma [21, Lemma A.3], we may assume that for every $\delta > 0$ sufficiently small there exists $\Delta_{\rho, \delta} := (\zeta_u^{\rho, \delta}, h_u^{\rho, \delta}, \zeta_v^{\rho, \delta}, h_v^{\rho, \delta})$, with $|\Delta_{\rho, \delta}| \leq \delta$, such that the function

$$\begin{aligned} \Phi_{\rho, \delta}(x, t, y, s) := & \Phi_\rho(x, t, y, s) \\ & - \left(\eta(x - x_0)(\xi_u^{\rho, \delta}, h_u^{\rho, \delta}) \cdot (x, t) + \eta(y - y_0)(\xi_v^{\rho, \delta}, h_v^{\rho, \delta}) \cdot (y, s) \right) \end{aligned}$$

attains a maximum at some $z_{\rho,\delta} := (x_{\rho,\delta}, t_{\rho,\delta}, y_{\rho,\delta}, s_{\rho,\delta})$ where $\Phi_{\delta,\rho}$ is twice differentiable and such that $x_{\rho,\delta} - x_0, y_{\rho,\delta} - y_0 \in U$ and $t_{\rho,\delta}, s_{\rho,\delta} > 0$. Moreover,

$$(3.14) \quad z_{\rho,\delta} \rightarrow (x_0, t_0, y_0, s_0) \quad \text{as } \delta \rightarrow 0.$$

Notice that since Φ_ρ is twice differentiable at $z_{\rho,\delta}$ it follows that also u_F^λ and v_G^λ are twice differentiable at $(x_{\rho,\delta}, t_{\rho,\delta})$ and $(y_{\rho,\delta}, s_{\rho,\delta})$, respectively.

Let $\tau_u^{\rho,\delta}, \tau_v^{\rho,\delta} \in \mathbb{R}$ be the maximizing τ 's in (3.11), (3.12) corresponding to the points $(x_{\rho,\delta}, t_{\rho,\delta}), (y_{\rho,\delta}, s_{\rho,\delta})$, respectively. Set

$$(3.15) \quad \tilde{u}_F(x, t) := \max_{\xi \in \mathbb{R}^N} \left\{ \chi_{F(t-\tau_u^{\rho,\delta})}(x - \xi) - \lambda f(|\xi|) \right\} - \lambda (\tau_u^{\rho,\delta})^2$$

$$(3.16) \quad \tilde{v}_G(y, s) := \min_{\xi \in \mathbb{R}^N} \left\{ \chi_{G(s-\tau_v^{\rho,\delta})}(y - \xi) + \lambda f(|\xi|) \right\} + \lambda (\tau_v^{\rho,\delta})^2.$$

Observe that by construction,

$$(3.17) \quad \begin{aligned} u_F^\lambda &\geq \tilde{u}_F, & v_G^\lambda &\leq \tilde{v}_G, \\ u_F^\lambda(x_{\rho,\delta}, t_{\rho,\delta}) &= \tilde{u}_F(x_{\rho,\delta}, t_{\rho,\delta}), & v_G^\lambda(y_{\rho,\delta}, s_{\rho,\delta}) &= \tilde{v}_G(y_{\rho,\delta}, s_{\rho,\delta}). \end{aligned}$$

Set now

$$\begin{aligned} \hat{u}_F(x, t) &:= \tilde{u}_F(x, t) - \rho q(|x - x_{\rho,\delta}|) \\ &\quad - \rho[q(|x - x_0|) + q(|t - t_0|)] - \eta(x - x_0)(\xi_u^{\rho,\delta}, h_u^{\rho,\delta}) \cdot (x, t), \end{aligned}$$

$$\begin{aligned} \hat{v}_G(y, s) &:= \tilde{v}_G(y, s) + \rho q(|y - y_{\rho,\delta}|) \\ &\quad + \rho[q(|y - y_0|) + q(|s - s_0|)] + \eta(y - y_0)(\xi_v^{\rho,\delta}, h_v^{\rho,\delta}) \cdot (y, s). \end{aligned}$$

Then by construction, the function

$$\hat{u}_F(x, t) - \hat{v}_G(y, s) - \varepsilon(t + s) - \lambda(f(|x - y|) + |t - s|^2).$$

has its maximum at $z_{\rho,\delta}$, which is now strict with respect to the spatial variables. Hence if we set

$$\hat{F}_{\rho,\delta}(t) := \{\hat{u}_F(\cdot, t) \geq \hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta})\}, \quad \hat{G}_{\rho,\delta}(s) := \{\hat{v}_G(\cdot, s) > \hat{v}_G(y_{\rho,\delta}, s_{\rho,\delta})\}.$$

we have $\hat{F}_{\rho,\delta}(t_{\rho,\delta}) \subseteq \hat{G}_{\rho,\delta}(s_{\rho,\delta})$ and moreover $(x_{\rho,\delta}, y_{\rho,\delta})$ is the only pair of minimal distance in $\partial \hat{F}_{\rho,\delta}(t_{\rho,\delta}) \times \partial \hat{G}_{\rho,\delta}(s_{\rho,\delta})$. In addition, we observe that at the maximum point, $|D\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta})| \approx |D\tilde{u}_F(x_{\rho,\delta}, t_{\rho,\delta})| = |Du_F^\lambda(x_{\rho,\delta}, t_{\rho,\delta})| \approx \lambda f'(|x_{\rho,\delta} - y_{\rho,\delta}|) \approx \lambda f'(|x_0 - y_0|) \neq 0$ up to perturbations which go to zero as $\rho, \delta \rightarrow 0$, and that the function \hat{u}_F is semiconvex, hence $\hat{F}_{\rho,\delta}(t_{\rho,\delta})$ has an interior ball condition at $x_{\rho,\delta}$ with a radius independent on ρ and δ , if small enough. In the same way, $\hat{G}_{\rho,\delta}(s_{\rho,\delta})$ has an exterior ball condition at $y_{\rho,\delta}$. In turns, $\hat{F}_{\rho,\delta}(t_{\rho,\delta})$ and $\hat{G}_{\rho,\delta}(s_{\rho,\delta})$ satisfy both and internal and external ball condition.

Set

$$\check{\Phi}_{\rho,\delta}(x, t, y, s) := \Phi_{\rho,\delta}(x, t, y, s) + \lambda(f(|x - y|) + |t - s|^2)$$

and

$$(3.18) \quad (\check{a}_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta}) := (\partial_t \check{\Phi}_{\rho,\delta}(z_{\rho,\delta}), D_x \check{\Phi}_{\rho,\delta}(z_{\rho,\delta}), D_x^2 \check{\Phi}_{\rho,\delta}(z_{\rho,\delta})),$$

$$(3.19) \quad (\check{b}_{\rho,\delta}, \check{q}_{\rho,\delta}, \check{Y}_{\rho,\delta}) := (\partial_s \check{\Phi}_{\rho,\delta}(z_{\rho,\delta}), D_y \check{\Phi}_{\rho,\delta}(z_{\rho,\delta}), D_y^2 \check{\Phi}_{\rho,\delta}(z_{\rho,\delta})).$$

Then, recalling (3.17), we observe that the superjet $(\check{a}_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta})$ of

$$u_F^\lambda(x, t) - \rho[q(|x - x_0|) + q(|t - t_0|)] - \eta(x - x_0)(\xi_u^{\rho,\delta}, h_u^{\rho,\delta}) \cdot (x, t)$$

at $(x_{\rho,\delta}, t_{\rho,\delta})$ is also a superjet for $\hat{u}_F(x, t)$ at the same point, hence, also, for the function $\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta}) \chi_{\hat{F}_{\rho,\delta}}$ (since $\hat{u}_F(x, t) \geq \hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta}) \chi_{\hat{F}_{\rho,\delta}(t)}(x)$). Hence, we have

$$(3.20) \quad (\check{a}_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta}) \in \mathcal{P}_{\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta}) \chi_{\hat{F}_{\rho,\delta}}}^{2,+}(x_{\rho,\delta}, t_{\rho,\delta})$$

and analogously,

$$(\check{b}_{\rho,\delta}, \check{q}_{\rho,\delta}, \check{Y}_{\rho,\delta}) \in \mathcal{P}_{\check{v}_G(y_{\rho,\delta}, s_{\rho,\delta})\chi_{\hat{G}_{\rho,\delta}}}^{2,-}(y_{\rho,\delta}, s_{\rho,\delta}).$$

Since $D_z \Phi_{\rho,\delta}(z_{\rho,\delta}) = 0$, we deduce

$$(3.21) \quad \check{a}_{\rho,\delta} - \check{b}_{\rho,\delta} = 2\varepsilon, \quad \check{p}_{\rho,\delta} = \check{q}_{\rho,\delta}.$$

Moreover, since $D_{x,y}^2 \Phi_{\rho,\delta}(z_{\rho,\delta}) \leq 0$, one can check that

$$(3.22) \quad \check{X}_{\rho,\delta} \leq \check{Y}_{\rho,\delta}.$$

By construction, $\check{\Phi}_{\rho,\delta}$ is also semiconvex, so that $\check{X}_{\rho,\delta} \geq -cI$, $\check{Y}_{\rho,\delta} \leq cI$ for a constant c depending on λ .

Let

$$c_{\rho,\delta}(x, t) := \tilde{u}_F(x, t) + (\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta}) - \hat{u}_F(x, t)).$$

Notice that, as $\delta \rightarrow 0$, $\rho \rightarrow 0$, we have $c_{\rho,\delta} \rightarrow u_F^\lambda(x_0, t_0)$ uniformly. In view of (3.13) we can thus assume that $c_{\rho,\delta} < 1$. Observe also that $c_{\rho,\delta}$ is smooth and constant away from a neighborhood of (x_0, t_0) , and it converges also in $C^{\ell,\beta}$.

We have $\hat{F}_{\rho,\delta}(t) = \{x : \tilde{u}_F(x, t) \geq c_{\rho,\delta}(x, t)\}$. Thus, by the definition of \tilde{u}_F , we have that $x \in \hat{F}_{\rho,\delta}(t)$ if and only if there exists $\xi \in \mathbb{R}^N$ such that $x \in \xi + F(t - \tau_u^{\rho,\delta})$, with

$$\chi_{\xi + F(t - \tau_u^{\rho,\delta})}(x) - \lambda f(|\xi|) = 1 - \lambda f(|\xi|) \geq c_{\rho,\delta}(x, t),$$

i.e.,

$$(3.23) \quad \hat{F}_{\rho,\delta}(t) = \left\{ x : x \in \xi + F(t - \tau_u^{\rho,\delta}) \right. \\ \left. \text{for some } \xi \in \mathbb{R}^N \text{ with } |\xi| \leq f^{-1} \left(\frac{1 - c_{\rho,\delta}(x, t)}{\lambda} \right) \right\}.$$

For ρ, δ small enough, $x_{\rho,\delta} \notin F(t_{\rho,\delta} - \tau_u^{\rho,\delta})$ and we can introduce $w_{\rho,\delta} \neq 0$ such that $x_{\rho,\delta} + w_{\rho,\delta}$ is a projection of $x_{\rho,\delta}$ on $F(t_{\rho,\delta} - \tau_u^{\rho,\delta})$. Precisely, one has that $c_{\rho,\delta}(x_{\rho,\delta}, t_{\rho,\delta}) = u_F^\lambda(x_{\rho,\delta}, t_{\rho,\delta})$, $\xi = -w_{\rho,\delta}$ reaches the max in (3.11) (for $x = x_{\rho,\delta}$), and $|w_{\rho,\delta}| = f^{-1}((1 - c_{\rho,\delta}(x_{\rho,\delta}, t_{\rho,\delta}))/\lambda)$. We then set

$$\Psi_{\rho,\delta}(x) := x - f^{-1} \left(\frac{1 - c_{\rho,\delta}(x, t_{\rho,\delta})}{\lambda} \right) \frac{w_{\rho,\delta}}{|w_{\rho,\delta}|} + w_{\rho,\delta}$$

which is a $C^{\ell,\beta}$ diffeomorphism (being $c_{\rho,\delta}$ bounded away from 1), which is a constant (small) translation out of a neighborhood of x_0 , and converges $C^{\ell,\beta}$ to the identity as $\delta \rightarrow 0$ and $\rho \rightarrow 0$. Observe that $\Psi_{\rho,\delta}(x_{\rho,\delta}) = x_{\rho,\delta}$. Then, we let

$$(3.24) \quad \check{F}_{\rho,\delta}(t) := \Psi_{\rho,\delta}(F(t - \tau_u^{\rho,\delta}) - w_{\rho,\delta}).$$

By construction, $\check{F}_{\rho,\delta}(t_{\rho,\delta}) \subseteq \hat{F}_{\rho,\delta}(t_{\rho,\delta})$ and $x_{\rho,\delta} \in \partial \check{F}_{\rho,\delta}(t_{\rho,\delta}) \cap \partial \hat{F}_{\rho,\delta}(t_{\rho,\delta})$. Moreover, we recall that $\hat{F}_{\rho,\delta}(t_{\rho,\delta})$ has an internal ball condition at $x_{\rho,\delta}$ while $\hat{G}_{\rho,\delta}(s_{\rho,\delta})$ satisfies an external ball condition at $y_{\rho,\delta}$, with radius bounded away from 0 uniformly with respect to ρ and δ sufficiently small. Thus, recalling that $\hat{F}_{\rho,\delta}(t_{\rho,\delta}) + (y_{\rho,\delta} - x_{\rho,\delta}) \subseteq \hat{G}_{\rho,\delta}(s_{\rho,\delta})$ (being $y_{\rho,\delta}$ the only contact point), we have that $\check{F}_{\rho,\delta}(t_{\rho,\delta})$, and in turn $\check{F}_{\rho,\delta}(t_{\rho,\delta})$ satisfies a uniform external ball condition in $x_{\rho,\delta}$. In addition, since we have assumed that $F(t)$ had a uniform internal ball condition for some radius $r > 0$, the same holds for $\check{F}_{\rho,\delta}(t_{\rho,\delta})$ with a smaller radius.

Notice that $\|\Psi_{\rho,\delta} - I\|_{C^{\ell,\beta}} \rightarrow 0$ as $\rho, \delta \rightarrow 0$. Set

$$(p_{\rho,\delta}, X_{\rho,\delta}) := \left(D_x(\check{\Phi}_{\rho,\delta}(\cdot, t_{\rho,\delta}, y_{\rho,\delta}, s_{\rho,\delta})) \circ \Psi_{\rho,\delta}(x_\delta), \right. \\ \left. D_x^2(\check{\Phi}_{\rho,\delta}(\cdot, t_{\rho,\delta}, y_{\rho,\delta}, s_{\rho,\delta})) \circ \Psi_{\rho,\delta}(x_\delta) \right),$$

By construction (see (3.20)), we have

$$(\check{\alpha}_{\rho,\delta}, p_{\rho,\delta}, X_{\rho,\delta}) \in \mathcal{P}_{\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta})\chi_{F(t-\tau_u^{\rho,\delta})}}^{2,+}(x_{\rho,\delta} + w_{\rho,\delta})$$

Since $\hat{u}_F(x_{\rho,\delta}, t_{\rho,\delta})\chi_{F(t-\tau_u^{\rho,\delta})}$ is a subsolution, we have

$$(3.25) \quad \check{\alpha}_{\rho,\delta} + |p_{\rho,\delta}|\kappa_*(x_{\rho,\delta} + w_{\rho,\delta}, p_{\rho,\delta}, X_{\rho,\delta}, F(t_{\rho,\delta} - \tau_u^{\rho,\delta})) \leq 0.$$

Note that

$$p_{\rho,\delta} \rightarrow Du_F^\lambda(x_0, t_0) \neq 0,$$

as $\rho, \delta \rightarrow 0$, and thus $|p_{\rho,\delta}|$ is bounded away from zero for ρ and δ sufficiently small. Since also $\check{X}_{\rho,\delta}$ and hence $X_{\rho,\delta}$ is bounded, we can invoke Lemma 3.6 and deduce that

$$(3.26) \quad \check{\alpha}_{\rho,\delta} + |\check{p}_{\rho,\delta}|\kappa_*(x_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta}, \check{F}_{\rho,\delta}(t_{\rho,\delta})) \leq \omega(\rho, \delta),$$

where $\omega(\rho, \delta) \rightarrow 0$ as $\rho, \delta \rightarrow 0$.

Analogously, we also have

$$(3.27) \quad \check{\alpha}_{\rho,\delta} - 2\varepsilon + |\check{p}_{\rho,\delta}|\kappa^*(y_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{Y}_{\rho,\delta}, \check{G}_{\rho,\delta}(s_{\rho,\delta})) \geq \omega(\rho, \delta)$$

for a suitable set $\check{G}_{\rho,\delta}(s_{\rho,\delta})$ such that $\hat{F}(t_{\rho,\delta}) + (y_{\rho,\delta} - x_{\rho,\delta}) \subseteq \check{G}_{\rho,\delta}(s_{\rho,\delta})$ and $\partial(\check{F}_{\rho,\delta}(t_{\rho,\delta}) + (y_{\rho,\delta} - x_{\rho,\delta})) \cap \partial\check{G}_{\rho,\delta}(s_{\rho,\delta}) = \{y_{\rho,\delta}\}$. By (3.22) and Lemma 3.7 we get

$$\kappa_*(x_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta}, \check{F}_{\rho,\delta}(t_{\rho,\delta})) \geq \kappa^*(y_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{Y}_{\rho,\delta}, \check{G}_{\rho,\delta}(s_{\rho,\delta})),$$

and thus, in particular,

$$\check{\alpha}_{\rho,\delta} - 2\varepsilon + |\check{p}_{\rho,\delta}|\kappa_*(x_{\rho,\delta}, \check{p}_{\rho,\delta}, \check{X}_{\rho,\delta}, \check{F}_{\rho,\delta}(t_{\rho,\delta})) \geq 2\omega(\rho, \delta),$$

which, together (3.26) gives $\varepsilon \leq \omega(\rho, \delta)$. This is a contradiction for ρ, δ sufficiently small. \square

Remark 3.9. By the uniqueness property stated in Theorem 3.5 and Theorem 3.8, we deduce that the evolution of open and closed superlevel sets is intrinsic in the following sense. Let $u^0, \tilde{u}^0 : \mathbb{R}^N \rightarrow \mathbb{R}$ be two initial conditions such that $\{u^0(\cdot) > 0\} = \{\tilde{u}^0(\cdot) > 0\}$. Then, denoting by u and \tilde{u} the corresponding geometric evolutions we have

$$\{u(\cdot, t) > 0\} = \{\tilde{u}(\cdot, t) > 0\} \quad \text{for all } t \in [0, t]$$

(and the same identity holds for the closed superlevels). Indeed, for any $\lambda \geq 0$ set

$$\begin{aligned} A_\lambda(t) &:= \{u(\cdot, t) > \lambda\}, & \tilde{A}_\lambda(t) &:= \{\tilde{u}(\cdot, t) > \lambda\}, \\ C_\lambda(t) &:= \{u(\cdot, t) \geq \lambda\}, & \tilde{C}_\lambda(t) &:= \{\tilde{u}(\cdot, t) \geq \lambda\}, \end{aligned}$$

In view of Lemma 3.2 and of Theorems 3.5 and 3.8, we have that for every $\lambda > 0$

$$\tilde{C}_\lambda(t) \subseteq A_0(t), \quad C_\lambda(t) \subseteq \tilde{A}_0(t).$$

Thus, we conclude

$$\tilde{A}_0(t) = \bigcup_{\lambda > 0} \tilde{C}_\lambda(t) \subseteq A_0(t), \quad A_0(t) = \bigcup_{\lambda > 0} C_\lambda(t) \subseteq \tilde{A}_0(t).$$

Part 2. Variational Nonlocal Curvatures

In this part we further assume the nonlocal curvature to be *variational*; that is, we assume that κ is the *first variation* of a suitable *generalized perimeter*. The second part of the paper is organized as follows. In Section 4 we introduce a suitable class of translation invariant generalized perimeters J and we give a rather weak notion of curvature as a first variation of the perimeter functional with respect to measurable perturbations of the set shrinking to a point x of the boundary. We also show how some of the structural assumptions of J translate into properties of the curvature κ .

In Subsection 4.3 we study how the weak notion of curvature compares to more standard ones. Section 5 is devoted to showing some relevant examples of variational nonlocal curvatures that fit in our abstract framework. Finally, Section 6 contains the main result of this part, namely the fact that the minimizing movement scheme applied to J converges to the associated nonlocal curvature flow.

4. GENERALIZED PERIMETERS AND CURVATURES

We begin this section by introducing the class of generalized (possibly nonlocal) perimeters we will be dealing with.

4.1. Generalized perimeters. We will say that a functional $J : \mathfrak{M} \rightarrow [0, +\infty]$ is a generalized perimeter if it satisfies the following properties:

- i) $J(E) < +\infty$ for every $E \in \mathfrak{C}$;
- ii) $J(\emptyset) = J(\mathbb{R}^N) = 0$;
- iii) $J(E) = J(E')$ if $|E \Delta E'| = 0$;
- iv) J is L^1_{loc} -l.s.c.: if $|(E_n \Delta E) \cap B_R| \rightarrow 0$ for every $R > 0$, then

$$J(E) \leq \liminf_n J(E_n);$$

- v) J is submodular: For any $E, F \in \mathfrak{M}$,

$$(4.1) \quad J(E \cup F) + J(E \cap F) \leq J(E) + J(F);$$

- vi) J is translational invariant:

$$(4.2) \quad J(x + E) = J(E) \quad \text{for all } E \in \mathfrak{M}, x \in \mathbb{R}^N.$$

We can extend the functional J to $L^1_{loc}(\mathbb{R}^N)$ enforcing the following *generalized co-area formula*:

$$(4.3) \quad J(u) := \int_{-\infty}^{+\infty} J(\{u > s\}) ds \quad \text{for every } u \in L^1_{loc}(\mathbb{R}^N).$$

It can be shown that, under the assumptions above, J is a convex l.s.c. functional in $L^1_{loc}(\mathbb{R}^N)$ (see [18]).

Observe that the following holds true:

Lemma 4.1. *Let $u \in L^1_{loc}(\mathbb{R}^N)$ and ρ be a nonnegative and compactly supported mollifier, and let $\rho_\varepsilon(x) := \rho(x/\varepsilon)/\varepsilon^N$ for $\varepsilon > 0$ small. Then for all ε ,*

$$(4.4) \quad J(\rho_\varepsilon * u) \leq J(u).$$

Moreover, $\lim_{\varepsilon \rightarrow 0} J(\rho_\varepsilon * u) = J(u)$.

Proof. The first statement follows from the convexity of J , by approximating $\rho_\varepsilon * u$ by appropriate finite convex combinations and then passing to the limit thanks to the lower semicontinuity assumption iv). The last statement is then an immediate consequence of (4.4) and once again of assumption iv). \square

4.2. A weak notion of curvature. We introduce here a definition of the curvature of sets relative to the generalized perimeter J which will be useful for studying the geometric “gradient flow” of J . It is based on a sort of local subdifferentiability property. We will show in Subsection 4.3 that it is implied by more standard definitions based on global variations of the boundaries of smooth sets.

Definition 4.2. Let $E \in \mathfrak{C}$ and $x \in \partial E$. We set

$$(4.5) \quad \kappa^+(x, E) := \inf \left\{ \liminf_n \frac{J(E \cup W_n) - J(E)}{|W_n \setminus E|} : \overline{W}_n \xrightarrow{\mathcal{H}} \{x\}, |W_n \setminus E| > 0 \right\}$$

and

$$(4.6) \quad \kappa^-(x, E) := \sup \left\{ \limsup_n \frac{J(E) - J(E \setminus W_n)}{|W_n \cap E|} : \overline{W}_n \xrightarrow{\mathcal{H}} \{x\}, |W_n \cap E| > 0 \right\}.$$

We say that $\kappa(x, E)$ is the curvature of E at x (associated with the perimeter J) if $\kappa^+(x, E) = \kappa^-(x, E) =: \kappa(x, E) \in \mathbb{R}$.

Notice that if $J(E) = J(\mathbb{R}^N \setminus E)$ it follows that $\kappa^+(x, E) = -\kappa^-(x, \mathbb{R}^N \setminus E)$, and therefore $\kappa(x, E) = -\kappa(x, \mathbb{R}^N \setminus E)$ (whenever it exists).

Standing Assumptions of Part 2. *Throughout Part 2 we assume that the curvature exists for all sets in \mathfrak{C} , i.e.,*

$$\kappa(x, E) := \kappa^+(x, E) = \kappa^-(x, E) \in \mathbb{R} \text{ for all } E \in \mathfrak{C} \text{ and all } x \in \partial E,$$

and that

$$\kappa \text{ satisfies axiom C) of Subsection 2.1.}$$

The translational invariance B) follows naturally from the translational invariance of the perimeter J . The monotonicity property A) stated in Subsection 2.1 is a consequence of the submodularity assumption (4.1), as shown in the next lemma.

Lemma 4.3. *Let $E, F \in \mathfrak{C}$ with $E \subseteq F$, and assume that $x \in \partial F \cap \partial E$: then $\kappa(x, F) \leq \kappa(x, E)$.*

Proof. First, we observe that we can find sets F_n which converge to F in \mathfrak{C} , with $F_n \supseteq F$ and $\{x\} = \partial E \cap \partial F_n$. In particular, $\kappa(x, F_n) \rightarrow \kappa(x, F)$. Then, let ν be the (outer) normal vector to E and (all of the) F_n at x , and for $\varepsilon > 0$ small let $E^\varepsilon = E + \varepsilon\nu$. Let $W^\varepsilon = E^\varepsilon \setminus \overset{\circ}{F}_n$, and observe that $W^\varepsilon \xrightarrow{\mathcal{H}} \{x\}$ as $\varepsilon \rightarrow 0$, and $|W^\varepsilon| > 0$ if $\varepsilon > 0$ (small). Thanks to (4.1) (applied to E^ε and F_n) and (4.2), we have

$$J(F_n \cup W^\varepsilon) - J(F_n) \leq J(E^\varepsilon) - J((E^\varepsilon) \setminus W^\varepsilon) = J(E) - J(E \setminus (W^\varepsilon - \varepsilon\nu)).$$

Then, by the very definition of κ we deduce $\kappa(x, F_n) \leq \kappa(x, E)$. The conclusion follows noticing that, by the continuity property C), $\kappa(x, F_n) \rightarrow \kappa(x, F)$. \square

4.3. First variation of the perimeter. Let J be a generalized perimeter. In this subsection we compare the weak notion of curvature given in Definition 4.2 with the more standard one based on the *first variation* of the perimeter functional. The latter is in turn related to *shape derivatives*, a notion which dates back to Hadamard, extensively studied in particular in [31].

Definition 4.4. We say that $\kappa(x, E)$, defined for $E \in \mathfrak{C}$ and $x \in \partial E$, is the first variation of the perimeter J if for every $E \in \mathfrak{C}$, and any one-parameter family of diffeomorphisms $(\Phi_\varepsilon)_\varepsilon$ of class $C^{\ell, \beta}$ both in x and in ε with $\Phi_0(x) = x$, we have

$$(4.7) \quad \frac{d}{d\varepsilon} J(\Phi_\varepsilon(E)) \Big|_{\varepsilon=0} = \int_{\partial E} \kappa(x, E) \psi(x) \cdot \nu_E(x) d\mathcal{H}^{N-1}(x),$$

where $\psi(x) := \frac{\partial \Phi_\varepsilon}{\partial \varepsilon}(x) \Big|_{\varepsilon=0}$ and $\nu_E(x)$ is the $C^{\ell-1, \beta}$ outer normal to the set E at x .

We will show that if such a $\kappa(x, E)$ is continuous with respect to $C^{\ell, \beta}$ perturbations of the sets E , then it is also a curvature in the sense of Definition 4.2. We start with the following intermediate result.

Proposition 4.5. *Let $\kappa(x, E)$ be a function defined for all $E \in \mathfrak{C}$ and $x \in \partial E$, and assume that it satisfies the continuity property C). Then $\kappa(x, E)$ is a first variation of J in the sense of Definition 4.4 if and only if for any $\varphi \in C_c^{\ell, \beta}(\mathbb{R}^N)$, and any $t_1 < t_2$ such that $D\varphi \neq 0$ in the set $\{t_1 \leq \varphi \leq t_2\}$, one has*

$$(4.8) \quad J(\{\varphi \geq t_1\}) = J(\{\varphi \geq t_2\}) + \int_{\{t_1 < \varphi < t_2\}} \kappa(x, \{\varphi \geq \varphi(x)\}) dx.$$

Moreover, in this case, one also has that for any set $W \in \mathfrak{M}$ such that $\{\varphi \geq t_2\} \subset W \subset \{\varphi \geq t_1\}$,

$$(4.9) \quad J(W) \geq J(\{\varphi \geq t_2\}) + \int_{W \setminus \{\varphi \geq t_2\}} \kappa(x, \{\varphi \geq \varphi(x)\}) dx.$$

Observe that in both integrals, the argument $\kappa(x, \{\varphi \geq \varphi(x)\})$ is a continuous function of x , thanks to assumption C).

Proof. Consider the function $f(s) := J(\{\varphi \geq s\})$, for $t_1 < s < t_2$. We claim that if κ is a first variation of J , then

$$(4.10) \quad f'(s) = - \int_{\partial\{f \geq s\}} \frac{\kappa(x, \{\varphi \geq s\})}{|D\varphi(x)|} d\mathcal{H}^{N-1}(x)$$

for all $s \in (t_1, t_2)$. To this aim, given $s \in (t_1, t_2)$ with $t_1 < s < t_2$, we need to find a family of $C^{\ell, \beta}$ diffeomorphisms which transport $\{\varphi \geq s\}$ on $\{\varphi \geq s + \varepsilon\}$ and compute its derivative at $\varepsilon = 0$.

If φ were smooth (at least $C^{\ell+1, \beta}$), a simple way would be to consider a smooth vector field $V(x)$ which is zero in $\{\varphi \geq t_2\} \cup \{\varphi \leq t_1\}$ and equal to $D\varphi/|D\varphi|^2$ in a neighborhood of $\{\varphi = s\}$. We would then let $\Phi_\varepsilon(x)$ defined for all x by

$$\begin{cases} \frac{d\Phi_\varepsilon(x)}{d\varepsilon} = V(\Phi_\varepsilon(x)) & \varepsilon > 0, \\ \Phi_0(x) = x. \end{cases}$$

In this case for ε small, we would have that $\varphi(x) = s$ implies $\varphi(\Phi_\varepsilon(x)) = s + \varepsilon$, since clearly $d(\varphi(\Phi_\varepsilon(x)))/d\varepsilon = D\varphi(\Phi_\varepsilon(x)) \cdot V(\Phi_\varepsilon(x)) = 1$ for such x and ε . Then, (4.10) would follow from (4.7). However, if φ is merely $C^{\ell, \beta}$, this construction builds only a $C^{\ell-1, \beta}$ diffeomorphism.

In general the situation is a bit more complex, however it is clear that such a diffeomorphism exists. A relatively simple construction consists in smoothing φ with a smooth mollifier in order to find a C^∞ set \tilde{E} such that for all ε small enough (here both positive and nonpositive), the surfaces $\partial\{\varphi \geq s + \varepsilon\}$ are represented as $C^{\ell, \beta}$ graphs over $\partial\tilde{E}$:

$$\partial\{\varphi \geq s + \varepsilon\} = \left\{ x + h_\varepsilon(x)\nu_{\tilde{E}}(x) : x \in \partial\tilde{E} \right\}.$$

By the implicit function theorem, h_ε exists and is $C^{\ell, \beta}$ (in both ε and x) for ε near 0. Moreover, since $\varphi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x)) = s + \varepsilon$, one checks that for any ε small and $x \in \partial\tilde{E}$,

$$\frac{\partial h_\varepsilon(x)}{\partial \varepsilon} = \frac{1}{D\varphi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x)) \cdot \nu_{\tilde{E}}(x)}.$$

The diffeomorphism $\Phi_\varepsilon(x)$ is then simply defined, in a neighborhood of the surface $\partial\tilde{E}$, by

$$(4.11) \quad \Phi_\varepsilon(x) = x + (h_\varepsilon(\pi_{\partial\tilde{E}}(x)) - h_0(\pi_{\partial\tilde{E}}(x)))\nu_{\tilde{E}}(\pi_{\partial\tilde{E}}(x)),$$

where $\pi_{\partial\tilde{E}}$ denotes the orthogonal projection onto $\partial\tilde{E}$, which is well-defined and smooth in a sufficiently small neighborhood of the surface.

Then, one has that for $x \in \partial\{\varphi \geq s\}$ (which is the graph of h_0)

$$\psi(x) := \lim_{\varepsilon \rightarrow 0} \frac{\Phi_\varepsilon(x) - x}{\varepsilon} = \frac{\partial h_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} (\pi_{\partial \tilde{E}}(x)) \nu_{\tilde{E}}(\pi_{\partial \tilde{E}}(x)) = \frac{\nu_{\tilde{E}}(\pi_{\partial \tilde{E}}(x))}{D\varphi(x) \cdot \nu_{\tilde{E}}(\pi_{\partial \tilde{E}}(x))}$$

and, in turn,

$$\psi(x) \cdot \nu_{\partial\{\varphi \geq s\}}(x) = -\psi(x) \cdot \frac{D\varphi}{|D\varphi|}(x) = -\frac{1}{|D\varphi(x)|}.$$

Hence (4.7) yields

$$(4.12) \quad \lim_{\varepsilon \rightarrow 0} \frac{J(\{\varphi \geq s + \varepsilon\}) - J(\{\varphi \geq s\})}{\varepsilon} \\ = \lim_{\varepsilon \rightarrow 0} \frac{J(\Phi_\varepsilon(\{\varphi \geq s\})) - J(\{\varphi \geq s\})}{\varepsilon} = - \int_{\partial\{\varphi \geq s\}} \frac{\kappa(x, \{\varphi \geq s\})}{|D\varphi(x)|} d\mathcal{H}^{N-1}(x),$$

which shows (4.10). Equation (4.8) follows from (4.10) and the co-area formula for BV functions.

Conversely, assume now that (4.8) holds for all $\varphi \in C_c^{\ell, \beta}(\mathbb{R}^N)$ and $t_1 < t_2$ such that $D\varphi \neq 0$ in the set $\{t_1 \leq \varphi \leq t_2\}$. We consider a family of diffeomorphism Φ_ε as in Definition 4.4. We start by showing that (4.7) holds. Write E as $E = \{\varphi \geq \frac{1}{2}\}$ for a suitable $\varphi \in C^{\ell, \beta}(\mathbb{R}^N)$, constant out of a compact set and with $D\varphi \neq 0$ in $\{0 \leq \varphi \leq 1\}$. Since $\Phi_\varepsilon(E) \Delta E$ is contained in the $M\varepsilon$ -neighborhood $(\partial E)_{M\varepsilon}$ of ∂E for some $M > 0$, if $\varepsilon > 0$ is sufficiently small we may find a diffeomorphism $\tilde{\Phi}_\varepsilon$ such that $\tilde{\Phi}_\varepsilon = Id$ outside $(\partial E)_{2M\varepsilon}$ (and in particular out of $\{|\varphi - 1/2| \leq 1/4\}$), $\tilde{\Phi}_\varepsilon(E) = \Phi_\varepsilon(E)$, and $\|\tilde{\Phi}_\varepsilon - Id\|_{C^{\ell, \beta}} \rightarrow 0$ as $\varepsilon \rightarrow 0$. In particular, by construction $J(\Phi_\varepsilon(E)) = J(\tilde{\Phi}_\varepsilon(E))$. Since $\Phi_\varepsilon(E) = \tilde{\Phi}_\varepsilon(E) = \{\varphi \circ \tilde{\Phi}_\varepsilon^{-1} \geq \frac{1}{2}\}$ and $\{\varphi \circ \tilde{\Phi}_\varepsilon^{-1} \geq 1\} = \{\varphi \geq 1\}$, by (4.8) we have

$$J(\Phi_\varepsilon(E)) - J(\{\varphi \geq 1\}) \\ = \int_{\tilde{\Phi}_\varepsilon(E) \setminus \{\varphi \geq 1\}} k(x, E_{\varphi \circ \tilde{\Phi}_\varepsilon^{-1}}(x)) dx \\ = \int_{(\partial E)_{2M\varepsilon} \cap \tilde{\Phi}_\varepsilon(E)} (k(x, E_{\varphi \circ \tilde{\Phi}_\varepsilon^{-1}}(x)) - \kappa(x, E_{\varphi(x)})) dx + \int_{\tilde{\Phi}_\varepsilon(E) \setminus \{\varphi \geq 1\}} k(x, E_{\varphi(x)}) dx \\ \leq \int_{(\partial E)_{2M\varepsilon}} |k(x, E_{\varphi \circ \tilde{\Phi}_\varepsilon^{-1}}(x)) - \kappa(x, E_{\varphi(x)})| dx + \int_{\Phi_\varepsilon(E) \setminus \{\varphi \geq 1\}} k(x, E_{\varphi(x)}) dx.$$

Since $\|k(x, E_{\varphi \circ \tilde{\Phi}_\varepsilon^{-1}}(x)) - \kappa(x, E_{\varphi(x)})\|_{L^\infty((\partial E)_{2M\varepsilon})} \rightarrow 0$ as $\varepsilon \rightarrow 0$, thanks to Assumption C), we have that

$$\int_{(\partial E)_{2M\varepsilon}} |k(x, E_{\varphi \circ \tilde{\Phi}_\varepsilon^{-1}}(x)) - \kappa(x, E_{\varphi(x)})| dx = o(\varepsilon).$$

Therefore

$$\frac{d}{d\varepsilon} J(\Phi_\varepsilon(E)) \Big|_{\varepsilon=0} = \frac{d}{d\varepsilon} \left(\int_{\Phi_\varepsilon(E) \setminus \{\varphi \geq 1\}} k(x, E_{\varphi(x)}) dx \right) \Big|_{\varepsilon=0} \\ = \int_{\partial E} k(x, E_{\varphi(x)}) \psi(x) \cdot \nu_E(x) d\mathcal{H}^{N-1}.$$

It now remains to prove (4.9). We first consider a $C^{\ell, \beta}$ function ψ such that $\psi - \varphi$ is compactly supported in $\{t_1 < \varphi < t_2\}$. In particular if $\varepsilon > 0$ is small enough, $\{t_1 < \varphi + \varepsilon(\psi - \varphi) < t_2\} = \{t_1 < \varphi < t_2\}$. We also introduce $\tilde{\varphi} := t_1 \vee (\varphi \wedge t_2)$ and $\tilde{\psi}(x) := \psi(x)$ if $t_1 < \varphi < t_2$, $\tilde{\psi}(x) = \tilde{\varphi}(x) \in \{t_1, t_2\}$ else. Observe that thanks to (4.3),

$$(4.13) \quad J(\tilde{\varphi}) = \int_{t_1}^{t_2} J(\{\varphi \geq s\}) ds$$

(which is finite thanks to (4.8)), so that (for ε small)

$$\frac{J(\tilde{\varphi} + \varepsilon(\tilde{\psi} - \tilde{\varphi})) - J(\tilde{\varphi})}{\varepsilon} = \int_{t_1}^{t_2} \frac{J(\{\varphi + \varepsilon(\psi - \varphi) \geq s\}) - J(\{\varphi \geq s\})}{\varepsilon} ds.$$

Again, for a fixed $s \in (t_1, t_2)$, one can find a family of $C^{\ell, \beta}$ -diffeomorphisms $(\Phi_\varepsilon)_{\varepsilon > 0}$ which transform $\{\varphi > s\}$ into $\{\varphi + \varepsilon(\psi - \varphi) > s\}$. One proceeds as before, but now the implicit function theorem is applied to the function

$$(x, \varepsilon, h) \mapsto (1 - \varepsilon)\varphi(x + h\nu_{\tilde{E}}(x)) + \varepsilon\psi(x + h\nu_{\tilde{E}}(x)) - s.$$

for $x \in \partial\tilde{E}$, ε small enough and h in a suitable neighborhood of 0. The diffeomorphisms are defined as in (4.11), and we can compute again the derivative of h_ε with respect to ε , for $x \in \partial\tilde{E}$:

$$\frac{\partial h_\varepsilon(x)}{\partial \varepsilon} = \frac{\varphi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x)) - \psi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x))}{((1 - \varepsilon)D\varphi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x)) + \varepsilon(D\psi(x + h_\varepsilon(x)\nu_{\tilde{E}}(x)))) \cdot \nu_{\tilde{E}}(x)}.$$

Hence, at $\varepsilon = 0$, for $x \in \partial\{\varphi \geq s\}$ we have

$$\frac{\partial h_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} (\pi_{\tilde{E}}(x)) = \frac{\varphi(x) - \psi(x)}{D\varphi(x) \cdot \nu_{\tilde{E}}(\pi_{\tilde{E}}(x))}.$$

In turn,

$$\psi(x) = \lim_{\varepsilon \rightarrow 0} \frac{\Phi_\varepsilon(x) - x}{\varepsilon} = \frac{\partial h_\varepsilon}{\partial \varepsilon} \Big|_{\varepsilon=0} (\pi_{\partial\tilde{E}}(x))\nu_{\tilde{E}}(\pi_{\partial\tilde{E}}(x)) = \frac{(\varphi(x) - \psi(x))\nu_{\tilde{E}}(\pi_{\partial\tilde{E}}(x))}{D\varphi(x) \cdot \nu_{\tilde{E}}(\pi_{\tilde{E}}(x))}$$

and

$$\psi(x) \cdot \nu_{\partial\{\varphi \geq s\}}(x) = \frac{\psi(x) - \varphi(x)}{|D\varphi(x)|}.$$

Using (4.7), we infer

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \frac{J(\{\varphi + \varepsilon(\psi - \varphi) \geq s\}) - J(\{\varphi \geq s\})}{\varepsilon} \\ = \int_{\partial\{\varphi \geq s\}} \frac{\psi(x) - \varphi(x)}{|D\varphi(x)|} \kappa(x, E_{\varphi(x)}) d\mathcal{H}^{N-1}(x). \end{aligned}$$

Notice that more generally, if ε is small enough, one obtains that

$$\begin{aligned} \lim_{\varepsilon' \rightarrow \varepsilon} \frac{J(\{\varphi + \varepsilon'(\psi - \varphi) \geq s\}) - J(\{\varphi + \varepsilon(\psi - \varphi) \geq s\})}{\varepsilon' - \varepsilon} \\ = \int_{\partial\{\varphi + \varepsilon(\psi - \varphi) \geq s\}} \frac{\psi(x) - \varphi(x)}{|(1 - \varepsilon)D\varphi(x) + \varepsilon D\psi(x)|} \kappa(x, \{\varphi + \varepsilon(\psi - \varphi) \geq s\}) d\mathcal{H}^{N-1}(x). \end{aligned}$$

Denoting $E_{s, \varepsilon}$ the sets $\{\varphi + \varepsilon(\psi - \varphi) \geq s\}$ and observing that they are continuous in \mathfrak{C} as ε varies, we see that, thanks to assumption C), this derivative is continuous with respect to ε (small) and in particular,

$$(4.14) \quad \begin{aligned} \frac{J(\{\varphi + \varepsilon(\psi - \varphi) \geq s\}) - J(\{\varphi \geq s\})}{\varepsilon} \\ = \frac{1}{\varepsilon} \int_0^\varepsilon \int_{\partial E_{s, t}} \frac{\psi(x) - \varphi(x)}{|(1 - t)D\varphi(x) + tD\psi(x)|} \kappa(x, E_{s, t}) d\mathcal{H}^{N-1}(x) dt \end{aligned}$$

Another observation is that the range of the ε for which this is true can be taken to be the same for all $s \in [t_1, t_2]$, since it depends on C^2 bounds for the boundaries $\partial\{\varphi \geq s\}$ (more precisely, on their largest curvature) and for ψ . Hence, if ε is small

enough, integrating (4.14) for s between t_1 and t_2 and using the co-area formula for BV functions, we obtain that

$$\begin{aligned} & \frac{J(\tilde{\varphi} + \varepsilon(\tilde{\psi} - \tilde{\varphi})) - J(\tilde{\varphi})}{\varepsilon} \\ &= \int_{\{t_1 < \varphi < t_2\}} (\psi(x) - \varphi(x)) \left(\frac{1}{\varepsilon} \int_0^\varepsilon \kappa(x, E_{(1-t)\varphi(x)+t\psi(x),t}) dt \right) dx \end{aligned}$$

In the limit, using the continuity assumption C) of κ again, we conclude that

$$\lim_{\varepsilon \rightarrow 0} \frac{J(\tilde{\varphi} + \varepsilon(\tilde{\psi} - \tilde{\varphi})) - J(\tilde{\varphi})}{\varepsilon} = \int_{\{t_1 < \varphi < t_2\}} (\psi(x) - \varphi(x)) \kappa(x, E_{\varphi(x)}) dx.$$

The convexity of J in turn implies that $J(\tilde{\varphi} + \varepsilon(\tilde{\psi} - \tilde{\varphi})) - J(\tilde{\varphi}) \leq \varepsilon(J(\tilde{\psi}) - J(\tilde{\varphi}))$ and it follows

$$(4.15) \quad J(\tilde{\psi}) \geq J(\tilde{\varphi}) + \int_{\{t_1 < \varphi < t_2\}} (\psi(x) - \varphi(x)) \kappa(x, E_{\varphi(x)}) dx.$$

Finally, notice that if $\psi - \varphi$ only vanishes on $\{\varphi \leq t_1\} \cup \{\varphi \geq t_2\}$, instead of having compact support in $\{t_1 < \varphi < t_2\}$, then (4.15) still holds, since by our assumptions one can find $t'_1 < t_1$, $t'_2 > t_2$ such that $|\nabla\varphi| > 0$ in $\{t'_1 < \varphi < t'_2\}$.

Consider now W as in Proposition 4.5. Without loss of generality (possibly replacing t_1 with a smaller value and t_2 with a larger value) we may assume that $\partial W \subset \{s_1 < \varphi < s_2\}$, where $t_1 < s_1 < s_2 < t_2$. Introducing a mollifier as in Lemma 4.1, we can approximate $\psi = t_1 + (t_2 - t_1)\chi_W$ with a sequence of smooth functions ψ_n such that $\psi_n - \varphi$ is supported in $\{t_1 \leq \varphi \leq t_2\}$, and $\lim_n J(\psi_n) = J(\psi) = (t_2 - t_1)J(W)$.

It follows from (4.15) that

$$J(\psi_n) \geq J(\tilde{\varphi}) + \int_{\{t_1 < \varphi < t_2\}} (\psi_n(x) - \varphi(x)) \kappa(x, E_{\varphi(x)}) dx,$$

and in the limit we obtain that

$$(t_2 - t_1)J(W) \geq J(\tilde{\varphi}) + \int_{\{t_1 < \varphi < t_2\}} (\psi(x) - \varphi(x)) \kappa(x, E_{\varphi(x)}) dx,$$

where we recall that $\psi = t_1 + (t_2 - t_1)\chi_W$. We can conclude using (4.8) and (4.13), or observing that this inequality also implies that

$$(t_2 - t_1)J(W) \geq J(g_n(\varphi)) + \int_{\{t_1 < \varphi < t_2\}} (\psi(x) - g_n(\varphi(x))) \kappa(x, E_{\varphi(x)}) dx.$$

where $g_n : \mathbb{R} \rightarrow [0, 1]$ is a smooth, nondecreasing approximation of $t_1 + (t_2 - t_1)\chi_{\{t \geq t_2\}}$. Passing to the limit, we obtain (4.9). \square

Corollary 4.6. *Let κ be a first variation of J in the sense of Definition 4.4, and assume it satisfies assumption C). Then, it is also the curvature in the sense of Definition 4.2.*

Proof. We need to prove that (4.5) and (4.6) hold with $\kappa^+ = \kappa^- = \kappa$. To this purpose, fix $x \in \partial E$ and let $\{W_n\} \subset \mathfrak{M}$ with $|W_n \cap E| > 0$ and $\overline{W_n} \xrightarrow{\mathcal{H}} \{x\}$.

We can as before assume that E is the level set $1/2$ of a $C^{\ell, \beta}$ function φ , constant out of a compact set, such that $D\varphi \neq 0$ in $\{0 \leq \varphi \leq 1\}$. Since

$$J(E) = J(\{\varphi \geq 1\}) + \int_{\{1/2 < \varphi < 1\}} \kappa(x, E_{\varphi(x)}) dx$$

and

$$J(E \setminus W_n) \geq J(\{\varphi \geq 1\}) + \int_{(E \setminus W_n) \setminus \{\varphi \geq 1\}} \kappa(x, E_{\varphi(x)}) dx,$$

by (4.8) and (4.9) respectively, it follows that

$$J(E) - J(E \setminus W_n) \leq \int_{W_n \cap E} \kappa(x, E_{\varphi(x)}) dx$$

for n sufficiently large. Dividing both sides by $|W_n \cap E|$ and letting $n \rightarrow \infty$, using also the continuity property of κ we conclude $\kappa^- \leq \kappa$. The opposite inequality easily follows by (4.7), choosing a sequence η_n of smooth cut-off functions whose support concentrates around x and which are 1 in a neighborhood of x , defining $\Phi_{\varepsilon,n} : y \mapsto y - \varepsilon \eta_n(y) \nu_E(x)$, and setting $W_n := \Phi_{\varepsilon,n}(E) \setminus E$, where ε_n is chosen through a standard diagonal argument. The proof that $\kappa^+ = \kappa$ is analogous. \square

5. EXAMPLES OF PERIMETERS AND THEIR CURVATURE

In this part we present some examples of generalized perimeters and corresponding curvatures that fit into our theory. We will consider here, unless otherwise stated, that $\ell = 2$, $\beta = 0$.

5.1. The Euclidean perimeter. Let J be the Euclidean perimeter. More precisely, let J be its lower semi-continuous extension to measurable sets introduced by Caccioppoli and De Giorgi. Then, J satisfies all the assumptions i)-vi). Moreover, let κ be the standard Euclidean curvature, i.e., the sum of the principal curvatures of ∂E at x . It is standard that it is the first variation of the perimeter in the sense of Definition 4.4, hence by Propositions 4.5 we deduce that the Euclidean curvature κ is also the curvature of J in the sense of Definition 4.2.

Clearly, the Euclidean perimeter is also uniformly continuous with respect to C^2 inner variations of sets, namely it satisfies the continuity assumption C'). More in general, any local curvature $\kappa(x, E)$ that depends continuously on the normal and on the second fundamental form of E at x fits with our theory. For such local and possibly anisotropic curvatures, we recover the well known existence and uniqueness of a viscosity solution to the geometric flows.

5.2. The fractional mean curvature flow. Fix $\alpha \in (0, \frac{1}{2})$. We consider the fractional perimeter defined as

$$J(E) := (1 - \alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} \frac{|\chi_E(x) - \chi_E(y)|}{|x - y|^{N+2\alpha}} dx dy,$$

for all $E \in \mathfrak{M}$. Notice that $J(E) < +\infty$ if and only if $\chi_E \in H^\alpha(\mathbb{R}^N)$. In this case, $J(E) = [\chi_E]_{H^\alpha}^2$, where $[\chi_E]_{H^\alpha}$ denotes the Gagliardo seminorm of χ_E in the fractional Sobolev space $H^\alpha(\mathbb{R}^N)$.

Since the work in [9], this nonlocal perimeter has attracted much attention; we refer the interested reader to [37]. It is easy to check that J satisfies all the properties i)-vi), so that it fits with our notion of generalized perimeters. Here we only note that for $u \in L^1_{loc}(\mathbb{R}^N)$ we have

$$\begin{aligned} & \int_{-\infty}^{+\infty} (1 - \alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} \frac{|\chi_{\{u>s\}}(x) - \chi_{\{u>s\}}(y)|}{|x - y|^{N+2\alpha}} dx dy ds \\ &= (1 - \alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} \int_{-\infty}^{+\infty} \frac{|\chi_{\{u>s\}}(x) - \chi_{\{u>s\}}(y)|}{|x - y|^{N+2\alpha}} ds dx dy \\ &= (1 - \alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} \frac{|u(x) - u(y)|}{|x - y|^{N+2\alpha}} dx dy. \end{aligned}$$

We have shown, in particular, that the extension of J by the generalized coarea formula (4.3) is convex and thus J is submodular.

A notion of curvature corresponding to J has been introduced in [10], [27]: let

$$\rho(x) := 1/|x|^{N+2\alpha}, \quad \rho_\delta(x) = (1 - \chi_{B(0,\delta)}(x))\rho(x).$$

Then, for every $E \in \mathfrak{C}$ set

$$\begin{aligned}\kappa_\delta(x, E) &= -2(1 - \alpha) \int_{\mathbb{R}^N} (\chi_E(y) - \chi_{\mathbb{R}^N \setminus E}(y)) \rho_\delta(x - y) dy, \\ \kappa(x, E) &:= \lim_{\delta \rightarrow 0} \kappa_\delta(x, E).\end{aligned}$$

The curvature κ is well defined for all smooth sets, it is the first variation of the perimeter J and it is continuous with respect to C^2 convergence. By Proposition 4.5 we deduce that κ satisfies (4.8) and (4.9). In particular, κ is the curvature of J according with Definition 4.2.

Indeed $\kappa(x, E)$ is well defined for any set which satisfies an internal and external ball condition at x (see [27], [10]). In particular, κ is well defined for any $E \in \mathfrak{C}^{1,1}$. This suggests that κ is a first order curvature. Let us show that this is the case.

Proposition 5.1. *Let $\Sigma \in \mathfrak{C}^{1,1}$, let $x \in \partial\Sigma$, and let (p, X) and (p, Y) be elements of $\mathcal{J}_\Sigma^{2,+}(x)$ and $\mathcal{J}_\Sigma^{2,-}(x)$, respectively. Then,*

$$(5.1) \quad \kappa_*(x, p, X, \Sigma) = \kappa^*(x, p, Y, \Sigma) = \kappa(x, \Sigma).$$

In particular, the curvature κ satisfies the first order curvature assumption (FO).

Proof. By Lemma 2.8 there exists a sequence $(p_n, X_n, E_n) \rightarrow (p, X, \Sigma)$ with uniform superjet at x , with $E_n \in \mathfrak{C}$, such that

$$(5.2) \quad \kappa(x, E_n) \rightarrow \kappa_*(x, p, X, \Sigma).$$

Moreover, we can always assume that $E_n \rightarrow E$ in L^1 (see Remark 2.10). Since $\Sigma \in \mathfrak{C}^{1,1}$, there exists $r > 0$ such that $B_r(x + r \frac{p}{|p|}) \subset \Sigma$. Set

$$\tilde{E}_n := E_n \cup B_r(x + r \frac{p_n}{|p_n|}).$$

Clearly, (p_n, X_n, \tilde{E}_n) still converge to (p, X, Σ) with uniform superjet at x . By the lower semicontinuity and monotonicity properties of κ we have

$$(5.3) \quad \kappa_*(x, p, X, \Sigma) \leq \liminf_n \kappa(x, \tilde{E}_n) \leq \liminf_n \kappa(x, E_n) = \kappa_*(x, p, X, \Sigma).$$

Moreover, since $\tilde{E}_n \rightarrow \Sigma$ in L^1 and \tilde{E}_n satisfy a uniform internal and external ball condition at x , it is easy to see (see for instance [27]) that $\kappa(x, \tilde{E}_n) \rightarrow \kappa(x, E)$, which together with (5.3) proves that $\kappa_*(x, p, X, \Sigma) = \kappa(x, \Sigma)$. The proof for $\kappa^*(x, p, Y, \Sigma)$ is identical. \square

Once proved that κ is a first order curvature, in view of Theorem 3.5 we recover the existence and uniqueness of a viscosity solution to the geometric flow, already proved in [27]. Instead, the convergence of the corresponding minimizing movement scheme studied in Section 6 is completely new for this class of nonlocal perimeters and furnishes an approximation algorithm which is alternative to the threshold-dynamics-based one studied in [10].

Remark 5.2. It can be proved that in fact κ satisfies also the uniform continuity assumption C'). Thus, uniqueness could also be deduced from the second order theory of Subsection 3.2, but of course the ‘‘first order’’ point of view is more convenient and straightforward in this case. Notice however that the second order theory will also yield existence and uniqueness for a geometric flow along any combination (sum) of this curvature and another second-order curvature, such as the classical Euclidean curvature.

We conclude this part giving a self contained proof of (4.8) and (4.9), which, in view of Proposition 4.6, yield that κ is the first variation of J .

Let

$$J_\delta(E) := (1 - \alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} |\chi_E(x) - \chi_E(y)| \rho_\delta(x - y) dx dy.$$

We will first show that J_δ, κ_δ satisfy (4.8) and (4.9). Let W be a bounded measurable set. Then,

$$\begin{aligned}
(5.4) \quad & \int_W \kappa_\delta(x, E_{\varphi(x)}) dx \\
&= -2(1-\alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} \chi_W(x) (\chi_{E_{\varphi(x)}}(y) - \chi_{\mathbb{R}^N \setminus E_{\varphi(x)}}(y)) \rho_\delta(x-y) dy dx \\
&= -(1-\alpha) \int_{\mathbb{R}^N \times \mathbb{R}^N} (\chi_W(x) - \chi_W(y)) (\chi_{E_{\varphi(x)}}(y) - \chi_{\mathbb{R}^N \setminus E_{\varphi(x)}}(y)) \rho_\delta(x-y) dy dx \\
&\leq \int_{\mathbb{R}^N \times \mathbb{R}^N} |\chi_W(x) - \chi_W(y)| \rho_\delta(x-y) dy dx,
\end{aligned}$$

with equality if and only if $W = E_s$ for some $s \in (0, 1)$.

On the other hand, it is easy to show that, as $\delta \rightarrow 0$, the following limits hold:

- i) For every $E \in \mathfrak{M}$, $J_\delta(E) \rightarrow J(E)$,
- ii) Let $\varphi : \mathbb{R}^N \rightarrow (0, 1)$ be such that $E_s := \{\varphi \geq s\}$ are bounded and belong to \mathfrak{C} for every $s \in (0, 1)$ and $D^2\varphi$ is negative definite on $\{\varphi = 1\}$. Then, $\kappa_\delta(x, E_{\varphi(x)}) \rightarrow \kappa(x, E_{\varphi(x)})$ in $L^1_{loc}(\mathbb{R}^N)$.

This implies that also J, κ satisfies (4.9) and (4.8).

5.3. General two body interaction perimeters. More in general one may consider a class of integral nonlocal perimeters of the form (see [6, 27])

$$(5.5) \quad J_K(E) := \int_E \int_{\mathbb{R}^N \setminus E} K(x-y) dx dy,$$

where the (possibly singular) nonnegative kernel K satisfies:

- (i) $K \in L^1(\mathbb{R}^N \setminus B(0, \delta))$ for all $\delta > 0$;
- (ii) for all $r > 0$ and $e \in \mathbb{S}^{N-1}$ we have that $K \in L^1(\{z \in \mathbb{R}^N : r|z \cdot e| \leq |z - (z \cdot e)e|^2\})$.

The associated nonlocal curvature

$$\kappa(x, E) := -2 \int_{\mathbb{R}^N} (\chi_E(y) - \chi_{\mathbb{R}^N \setminus E}(y)) K(x-y) dy$$

is well defined in the principal value sense provided that E satisfies both an inner and an outer ball condition at the point $x \in \partial E$. One can check that also these curvatures are covered by both the first order and second order theories of generalized curvatures.

5.4. The flow generated by the regularized pre-Minkowski content. Let $\rho > 0$ be fixed, and consider the measure of the ρ -neighborhood of the boundary of E , i.e.,

$$(5.6) \quad \mathcal{M}_\rho(E) := |(\partial E)_\rho| = |(\cup_{x \in \partial E} B_\rho(x))|.$$

We refer to M_ρ as the *pre-Minkowski content* of ∂E , since as $\rho \rightarrow 0$, $|(\partial E)_\rho|/2\rho$ approximates the Minkowski content, which coincides with the standard perimeter on smooth sets.

An issue with definition (5.6) is that it depends on the choice of the representative within the Lebesgue equivalence class of the set E . For this reason, one may introduce the following variant:

$$(5.7) \quad J_\rho(E) = \frac{1}{2\rho} \int_{\mathbb{R}^N} \text{osc}_{B(x, \rho)}(\chi_E) dx$$

where $\text{osc}_A(u)$ denotes the *essential oscillation* of the measurable function u over a measurable set A , defined by $\text{osc}_A(u) = \text{ess sup}_A u - \text{ess inf}_A u$. One checks that $J_\rho(E)$ coincides with the measure of the ρ -neighborhood of the essential boundary

of E . Moreover, $J_\rho(E) = \inf\{\mathcal{M}_\rho(E') : |E\Delta E'| = 0\}$, where $E\Delta E'$ denotes the symmetric difference $(E \setminus E') \cup (E' \setminus E)$.

In [19] we have proved that the functional (5.7) is a generalized perimeter, we have introduced the corresponding curvature, and studied the geometric flow. Let us introduce a notion of curvature corresponding to J_ρ ; let $E \in \mathfrak{C}$, and denote by $\nu_E(x)$ the outer normal unit vector to ∂E at x .

For $x \in \partial E$, set

$$(5.8) \quad \kappa_\rho(x, E) = \kappa_\rho^{out}(x, E) + \kappa_\rho^{in}(x, E),$$

where

$$(5.9) \quad \kappa_\rho^{out}(x, E) = \begin{cases} \frac{1}{2\rho} \det(I + \rho D\nu_E(x)) & \text{if } \text{dist}(x + \rho\nu_E(x), E) = \rho, \\ 0 & \text{otherwise,} \end{cases}$$

$$(5.10) \quad \kappa_\rho^{in}(x, E) = \begin{cases} -\frac{1}{2\rho} \det(I - \rho D\nu_E(x)) & \text{if } \text{dist}(x - \rho\nu_E(x), E^c) = \rho, \\ 0 & \text{otherwise.} \end{cases}$$

These quantities correspond to the variation of the volume of the strips $\{0 < d_E < \rho\}$ (for κ_ρ^{out}) and $\{-\rho < d_E < 0\}$ (for κ_ρ^{in}) when the boundary is infinitesimally modified at x , and their sum is a natural candidate for the curvature associated to the energy \mathcal{E}_ρ . Indeed, in [19] we have proved that $\kappa_\rho(x, E)$ is the first variation of J_ρ (in the classical sense (4.7)) whenever $E \in \mathfrak{C}$ is such that the points at distance ρ from ∂E admit a unique projection on ∂E (indeed such condition can be weakened a little). In order to have a well defined curvature for all $E \in \mathfrak{C}$, one can consider the following regularization of J_ρ :

$$J^f(E) = \int_{\mathbb{R}^N} f(d_E(x)) dx = \int_0^\rho (-2sf'(s))J_s(E) ds,$$

where d_E is the signed distance from ∂E and $f : \mathbb{R} \rightarrow \mathbb{R}_+$ is even, smooth and decreasing in \mathbb{R}_+ , with support in $[-\rho, \rho]$. Such a regularization was considered also in [2] for numerical purposes.

The corresponding curvature κ_f is

$$(5.11) \quad \kappa_f(x, E) = \kappa_f^{out}(x, E) + \kappa_f^{in}(x, E),$$

where

$$\kappa_f^{out}(x, E) = \int_0^\rho (-2sf'(s))\kappa_s^{out}(x, E) ds, \quad \kappa_f^{in}(x, E) = \int_0^\rho (-2sf'(s))\kappa_s^{in}(x, E) ds.$$

Let r^{in} be the maximal $r \in [0, \rho]$ such that E satisfies the internal ball condition with radius r at x , and let r^{out} be defined analogously. Clearly, r^{in} , r^{out} and the second fundamental form at x are uniformly continuous with respect to smooth inner variations. We immediately deduce that κ_f satisfies the uniform continuity assumption C').

In [19] we have proved that $\kappa_f(x, E)$ is the curvature corresponding to J^f , according to both Definitions 4.4 and 4.2, and we have studied the corresponding curvature flow through the minimizing movements method. As a consequence of the analysis of this paper, namely by the Comparison Principle provided by Theorem 3.8, we get the new result that such a geometric evolution is indeed unique.

5.5. The shape flow generated by p -capacity. In this subsection we show that the shape flow of *bounded sets* generated by the p -capacity fits into our general framework. Notice that the case $p = 2$ yields an evolution that is similar to the Hele-Shaw type flow considered in [13].

To this aim, given $1 < p < N$, we consider the following *relaxed p -capacity* of a set $E \in \mathfrak{M}$ defined by

$$(5.12) \quad \mathfrak{C}ap_p(E) := \inf \left\{ \int_{\mathbb{R}^N} |Dw|^p dx : w \in K^p \text{ and } w \geq 1 \text{ a.e. in } E \right\},$$

where K^p stands for the subspace of functions w of $L^{p^*}(\mathbb{R}^N)$ such that $Dw \in L^p(\mathbb{R}^N)$. Note that the above definition departs from the standard one in which the condition $w \geq 1$ a.e. in E is replaced by $E \subset \{w \geq 1\}$. It may be thought as a sort of L^1 -lower semicontinuous envelope of the standard p -capacity, having the property of being insensitive to negligible sets and thus independent of the Lebesgue representative of E . Clearly the two definitions coincide on open sets and it is not difficult to check that they also agree on all closed sets F such that $F = \overline{\overset{\circ}{F}}$, with $|\partial F| = 0$, in particular on all sets in \mathfrak{C} .

Formula (5.12) does not provide yet a generalized perimeter. Indeed, $\mathfrak{C}ap_p(\mathbb{R}^N) = +\infty$ and, more in general, if $E \in \mathfrak{C}$, then $\mathfrak{C}ap_p(E) < +\infty$ if and only if $\mathfrak{C}ap_p(\mathbb{R}^N \setminus E) = +\infty$. Thus, the requirements i) and ii) stated at the beginning of Subsection 4.1 are not fulfilled. On the other hand, properties iii) and vi) are evident, the lower-semicontinuity iv) follows in a standard way, while the submodularity property v) can be proven as in the case of the standard capacity (see [24, Theorem 2-(vii) of Section 4.7]). Since our focus will be on the evolution of bounded sets, we will build a generalized perimeter J_p , by enforcing the following properties:

- a) $J_p(E) = \mathfrak{C}ap_p(E)$ for all bounded sets $E \in \mathfrak{M}$;
- b) $J_p(E) = J_p(\mathbb{R}^N \setminus E)$ for all $E \in \mathfrak{M}$.

This is achieved by setting

$$(5.13) \quad J_p(E) := \min\{\mathfrak{C}ap_p(E), \mathfrak{C}ap_p(\mathbb{R}^N \setminus E)\}$$

for all $E \in \mathfrak{M}$. It follows immediately from the definition and from the properties of $\mathfrak{C}ap_p(\cdot)$ recalled above that J_p satisfies i)–iv) of Subsection 4.1 and the translation invariance vi). It only remains to check the submodularity property v). To this aim, let us consider the case of two sets $E, F \in \mathfrak{M}$ such that $\mathfrak{C}ap_p(E) < +\infty$ and $\mathfrak{C}ap_p(\mathbb{R}^N \setminus F) < +\infty$. As $\mathfrak{C}ap_p(\mathbb{R}^N \setminus E) = \mathfrak{C}ap_p(F) = +\infty$, we have $J_p(E) = \mathfrak{C}ap_p(E)$ and $J_p(F) = \mathfrak{C}ap_p(\mathbb{R}^N \setminus F)$. Moreover, since $\mathfrak{C}ap_p(E \cap F) \leq \mathfrak{C}ap_p(E)$, we also have $J_p(E \cap F) = \mathfrak{C}ap_p(E \cap F)$, while the fact that $\mathfrak{C}ap_p(E \cup F) \geq \mathfrak{C}ap_p(F) = +\infty$ implies $J_p(E \cup F) = \mathfrak{C}ap_p(\mathbb{R}^N \setminus (E \cup F))$. Thus, in this case the submodularity inequality is equivalent to

$$\mathfrak{C}ap_p(\mathbb{R}^N \setminus (E \cup F)) + \mathfrak{C}ap_p(E \cap F) \leq \mathfrak{C}ap_p(E) + \mathfrak{C}ap_p(\mathbb{R}^N \setminus F),$$

which is obviously true since $\mathfrak{C}ap_p(\mathbb{R}^N \setminus (E \cup F)) \leq \mathfrak{C}ap_p(\mathbb{R}^N \setminus F)$ and $\mathfrak{C}ap_p(E \cap F) \leq \mathfrak{C}ap_p(E)$ by the non-decreasing monotonicity of the set function $\mathfrak{C}ap_p(\cdot)$. Since all the remaining cases are either trivial or reduce the submodularity of $\mathfrak{C}ap_p(\cdot)$, also property v) is established for J_p , which is therefore a generalized perimeter.

By a standard application of the Direct Method of the Calculus of Variations one may also check the existence of a *unique capacity potential* w_E associated with any set E , i.e., of a unique solution to the problem (5.12), whenever $\mathfrak{C}ap_p(E) < +\infty$. The Euler-Lagrange conditions for (5.12) easily yield that w_E is super p -harmonic in \mathbb{R}^N , in fact it is determined as the unique solution $w_E \in K^p$ to

$$(5.14) \quad \begin{cases} - \int_{\mathbb{R}^N} |Dw_E|^{p-2} Dw_E D\varphi dx \geq 0 & \text{for all } \varphi \in K^p, \text{ with } \varphi \geq 0 \text{ a.e. on } E. \\ w_E = 1 & \text{a.e. in } E. \end{cases}$$

Denoting by $E^{(0)}$ the set of points with vanishing density with respect to E , it follows in particular that w_E is p -harmonic in the interior of $E^{(0)}$.

In order to identify the nonlocal curvature corresponding to $J_p(\cdot)$, we exploit the theory developed in Subsection 4.3. Let $E \in \mathfrak{C}$ and bounded, and let $(\Phi_\varepsilon)_\varepsilon$ be a one-parameter family of diffeomorphisms from \mathbb{R}^N onto itself of class C^2 both in ε and x and such that $\Phi_0(x) = x$ for all $x \in \mathbb{R}^N$. Denote $\psi(x) := \frac{\partial \Phi_\varepsilon(x)}{\partial \varepsilon} \Big|_{\varepsilon=0}$. Then by the Hadamard formulae (see for instance [34]) one has

$$(5.15) \quad \begin{aligned} \frac{d}{d\varepsilon} J_p(\Phi_\varepsilon(E)) \Big|_{\varepsilon=0} &= \frac{d}{d\varepsilon} \mathfrak{C}ap_p(\Phi_\varepsilon(E)) \Big|_{\varepsilon=0} = \frac{d}{d\varepsilon} \int_{\mathbb{R}^N \setminus \Phi_\varepsilon(E)} |Dw_{\Phi_\varepsilon(E)}|^p dx \Big|_{\varepsilon=0} \\ &= \int_{\partial E} |Dw_E|^p(x) \psi(x) \cdot \nu_E(x) d\mathcal{H}^{N-1}(x), \end{aligned}$$

where, as usual, ν_E denotes the outer unit normal to E . Motivated by the above formula and recalling that $J_p(E) = \mathfrak{C}ap_p(\mathbb{R}^N \setminus E)$ for $E \in \mathfrak{C}$ and unbounded, for every $E \in \mathfrak{C}$ and $x \in \partial E$ we set

$$(5.16) \quad \kappa_p(x, E) := \begin{cases} |Dw_E(x)|^p = \left| \frac{\partial w_E}{\partial \nu}(x) \right|^p & \text{if } E \text{ is bounded,} \\ -|Dw_{\mathbb{R}^N \setminus E}(x)|^p = - \left| \frac{\partial w_{\mathbb{R}^N \setminus E}}{\partial \nu}(x) \right|^p & \text{if } E \text{ is unbounded.} \end{cases}$$

Recalling that w_E is p -harmonic on E^c and satisfies the Dirichlet condition $w_E = 1$ on ∂E , the well-established regularity theory for the p -Laplacian (see for instance [29]) yields that w_E is of class $C^{1,\alpha}$ up to the boundary for all $\alpha \in (0, 1)$, with the $C^{0,\alpha}$ -norm of Dw_E depending only on its L^p -norm and the $C^{0,\alpha}$ -norm of ∂E . In fact, whenever $E_n \rightarrow E$ in $C^{1,\alpha}$ and $x \in \partial E \cap \partial E_n$ we have

$$(5.17) \quad \frac{\partial w_{E_n}}{\partial \nu}(x) \rightarrow \frac{\partial w_E}{\partial \nu}(x)$$

as $n \rightarrow \infty$. In particular, it follows that the nonlocal curvature κ_p defined in (5.16) satisfies the continuity property C) of Subsection 2.1.

In turn, by Corollary 4.6 the set function (5.16) is the curvature associated with J_p in the sense of Definition 4.2. Lemma 4.3 now implies that the monotonicity property A) stated in Subsection 2.1 holds for κ_p .

Since the translation invariance of κ_p is evident, we have shown that (5.16) satisfies axioms A), B), and C) of Subsection 2.1. We recall that these axioms are enough to guarantee the convergence (up to subsequences) of the minimizing movements scheme studied in Section 6 to a viscosity solution of the corresponding level set equation.

It remains to investigate the uniqueness. Instead of establishing the reinforced continuity property C'), we check that the nonlocal perimeter J_p generates a ‘‘first-order’’ flow and we apply the theory of Subsection 3.1. To this aim, denote by $(\kappa_p)_*$ and $(\kappa_p)^*$ the lower and the upper semicontinuous extensions of κ_p provided by formulas (2.9) and (2.10), respectively. Note that, as a straightforward consequence of the definition and of (2.10), we have

$$(5.18) \quad (\kappa_p)_*(x, p, X, E) = -(\kappa_p)^*(x, -p, -X, \mathbb{R}^N \setminus E)$$

for $E \in \mathfrak{M}$, $x \in \partial E$, and $(p, X) \in \mathcal{J}_E^{2,+}(x)$.

We are now in a position to prove that condition (FO) of Subsection 3.1 is satisfied. Uniqueness will then follow by applying the Comparison Principle provided by Theorem 3.5.

Lemma 5.3. *Let $\Sigma \subset \mathbb{R}^N$ belong to $\mathfrak{C}^{1,1}$. Let $x \in \partial\Sigma$ and let (p, X) and (p, Y) be elements of $\mathcal{J}_\Sigma^{2,+}(x)$ and $\mathcal{J}_\Sigma^{2,-}(x)$, respectively. Then,*

$$(\kappa_p)_*(x, p, X, \Sigma) = (\kappa_p)^*(x, p, Y, \Sigma).$$

Proof. In light of (5.18), it is enough to consider the case of a bounded set Σ of class $C^{1,1}$. Let w_Σ be the associated capacity potential. The conclusion of the lemma will be achieved by showing that

$$(5.19) \quad (\kappa_p)_*(x, p, X, \Sigma) = \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p = (\kappa_p)^*(x, p, Y, \Sigma).$$

To this aim, let $E \supseteq \Sigma$ be a bounded set of \mathfrak{C} admissible for the Definition 2.9 of $(\kappa_p)_*(x, p, X, \Sigma)$, and let w_E be the corresponding capacity potential. Recall that by (5.14), we have that w_E is super p -harmonic in $\mathbb{R}^N \setminus \Sigma$, while w_Σ is p -harmonic in the same set. Since $w_E = w_\Sigma = 1$ on $\partial\Sigma$, by the Maximum Principle we infer that $1 \geq w_E \geq w_\Sigma$ in $\mathbb{R}^N \setminus \Sigma$. In turn,

$$\kappa_p(x, E) = \left| \frac{\partial w_E}{\partial \nu}(x) \right|^p \leq \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p$$

and therefore we may conclude that

$$(5.20) \quad (\kappa_p)_*(x, p, X, \Sigma) \leq \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p.$$

To show the opposite inequality, fix $\delta > 0$ and construct a sequence of sets $(\Sigma_n)_n \subset \mathfrak{C}^{1,1}$ with the following properties:

- i) $\Sigma \subset \overset{\circ}{\Sigma}_n \cup \{x\}$, with $\partial\Sigma_n \cap \partial\Sigma = \{x\}$;
- ii) $(p, X + \delta I) \in \mathcal{J}_{\Sigma_n}^2(x)$ for all $n \in \mathbb{N}$;
- iii) $\Sigma_n \rightarrow \Sigma$ in the $C^{1,\alpha}$ -sense, for all $\alpha \in (0, 1)$.

Such a sequence can be constructed in many different ways: one possibility is to consider the $\frac{1}{n}$ -level sets of the signed distance function from Σ and modify them in the proximity to x in order to fulfill conditions i) and ii). By (5.17), for any given small $\varepsilon > 0$ we may fix \bar{n} such that

$$(5.21) \quad \left| \frac{\partial w_{\Sigma_{\bar{n}}}}{\partial \nu}(x) \right|^p \geq \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p - \varepsilon.$$

Recall now that from the proof of Lemma 2.8, we may construct a decreasing sequence of sets $(E_n)_n \subset \mathfrak{C}$ such that

- a) $E_n \searrow \Sigma$ in the Hausdorff sense;
- b) $(p, X + \delta_n I) \in \mathcal{J}_{E_n}^2(x)$ for some $\delta_n \searrow 0$;
- c) $\kappa_p(x, E_n) = \left| \frac{\partial w_{E_n}}{\partial \nu}(x) \right|^p \rightarrow (\kappa_p)_*(x, p, X, \Sigma)$.

Taking into account i) and ii) above, it follows from a) and b) that $E_n \subset \Sigma_{\bar{n}}$ for n large enough. For all such n 's, by the Maximum Principle as in the first part of the proof, we have

$$\left| \frac{\partial w_{E_n}}{\partial \nu}(x) \right|^p \geq \left| \frac{\partial w_{\Sigma_{\bar{n}}}}{\partial \nu}(x) \right|^p \geq \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p - \varepsilon,$$

where in the last inequality we have used (5.21). By c), passing to the limit in the left-hand side of the above formula and by the arbitrariness of ε , we deduce

$$(\kappa_p)_*(x, p, X, \Sigma) \geq \left| \frac{\partial w_\Sigma}{\partial \nu}(x) \right|^p,$$

which, together with (5.20), establishes the first equality in (5.19). The second equality can be proven in a completely analogous fashion. \square

6. THE MINIMIZING MOVEMENTS APPROXIMATION

In this section we implement the minimizing movements scheme to solve and approximate the nonlocal κ -curvature flow, in the spirit of [1, 30]. We extend the approach of [17] (see also [19]) to our general framework.

6.1. The time-discrete scheme for bounded sets. We start by introducing the incremental minimum problem. To this purpose, given a bounded set $E \neq \emptyset$, we let

$$(6.1) \quad d_E(x) = \text{dist}(x, E) - \text{dist}(x, \mathbb{R}^N \setminus E)$$

be the signed distance function to ∂E . Fix a time step $h > 0$ and consider the problem

$$(6.2) \quad \min \left\{ J(F) + \frac{1}{h} \int_F d_E(x) dx : F \in \mathfrak{M} \right\}.$$

Note that

$$\int_F d_E(x) dx - \int_E d_E(x) dx = \int_{E \Delta F} \text{dist}(x, \partial E) dx$$

so that (6.2) is equivalent to

$$\min \left\{ J(F) + \frac{1}{h} \int_{E \Delta F} \text{dist}(x, \partial E) dx : F \in \mathfrak{M} \right\}.$$

Proposition 6.1. *The problem (6.2) admits a minimal and a maximal solution.*

Proof. Since the functional J extended to L^1_{loc} according to (4.3) is convex, it is easy to check that the minimization problem

$$(6.3) \quad \min_{u \in L^\infty(\mathbb{R}^N; [0,1])} J(u) + \frac{1}{h} \int_{\mathbb{R}^N} u(x) d_E(x) dx$$

admits a solution. Then, observe that

$$(6.4) \quad J(u) + \frac{1}{h} \int_{\mathbb{R}^N} u(x) d_E(x) dx = \int_0^1 \left(J(\{u > s\}) + \frac{1}{h} \int_{\{u > s\}} d_E(x) dx \right) ds,$$

from which we easily deduces that for a.e. $s \in [0, 1]$, $\{u > s\}$ is a solution to (6.2). Let now E_1 and E_2 be two solutions to (6.2). Then again by (6.4) their characteristic functions and in turn, by convexity, $\frac{1}{2}(\chi_{E_1} + \chi_{E_2})$ are solutions to (6.3). Since almost all their superlevel sets are solutions to (6.2), we deduce, in particular, that $E_1 \cap E_2$ and $E_1 \cup E_2$ are solutions to (6.2). Finally let E_n be a sequence of solutions to (6.2) such that

$$|E_n| \rightarrow m := \inf\{|E| : E \text{ is a solution to (6.2)}\}.$$

Then, $F_k := \cap_{n=1}^k E_n$ is a decreasing sequence of solutions such that $|F_k| \rightarrow m$. Thus, by semicontinuity, their L^1 -limit $E := \cap_{n=1}^\infty E_n$ is the minimal solution. The existence of a maximal solution can be proven analogously. \square

For any bounded set $E \neq \emptyset$ we let $T_h^+ E$ and $T_h^- E$ denote the maximal and the minimal solution of (6.2), respectively. We also set $T_h^\pm \emptyset := \emptyset$. We will mainly use minimal solutions, and write $T_h E := T_h^- E$. This choice corresponds to consider open superlevels in our level set approach (see Proposition 6.12). It is convenient to fix a precise representative for $T_h^\pm E$. To this purpose, we will identify any measurable set with the representative given by the set of Lebesgue points of the characteristic function.

Lemma 6.2. *If $E \subseteq E'$, then $T_h^\pm E \subseteq T_h^\pm E'$.*

Proof. The proof is classical and we just sketch it. We first assume that $E \subset\subset E'$, so that $d_E > d_{E'}$ everywhere. We compare the energy (6.2) of $T_h^\pm E$ with the one of $T_h^\pm E \cap T_h^\pm E'$, and the energy (6.2) (with E replaced by E') of $T_h^\pm E'$ with the one of $T_h^\pm E \cup T_h^\pm E'$. We sum both inequalities and use (4.1) to deduce that $T_h^\pm E \subseteq T_h^\pm E'$.

Now we conclude the proof by a perturbation argument. For $\varepsilon > 0$ let F_ε be the minimal solution of (6.2) with d_E replaced by $d_E + \varepsilon$. Arguing as before, we deduce that F_ε are increasing in ε and $F_\varepsilon \subseteq T_h^- E'$. Therefore $F_\varepsilon \rightarrow F_0 := \cup_\varepsilon F_\varepsilon$ in L^1_{loc} . By lower semicontinuity it follows that F_0 is a solution, and thus $T_h^- E \subseteq F_0 \subseteq T_h^- E'$. The inclusion $T_h^+ E \subseteq T_h^+ E'$ can be proven similarly. \square

Remark 6.3. Let f be a measurable function such that $f^- := -f \wedge 0 \in L^1(\mathbb{R}^N)$. Then one can argue as in Proposition 6.1 to prove that the minimum problem

$$\min \left\{ J(F) + \int_F f \, dx : F \in \mathfrak{M} \right\}$$

admits a *minimal* and a *maximal* solution, denoted by E_f^- and E_f^+ respectively. Moreover, arguing exactly as in the proof of Lemma 6.2, one can show that if f_1, f_2 are measurable functions with $f_1^-, f_2^- \in L^1(\mathbb{R}^N)$ and $f_1 \leq f_2$ a.e., then

$$E_{f_2}^\pm \subseteq E_{f_1}^\pm.$$

Lemma 6.4. *If $E + B_R \subseteq E'$, then $(T_h^\pm E) + B_R \subseteq T_h^\pm E'$.*

Proof. By Lemma 6.2 for every $z \in B_R$ we have $T_h^\pm(E+z) \subseteq T_h^\pm E'$. By translation invariance we conclude

$$(T_h^\pm E) + B_R = \bigcup_{z \in B_R} (T_h^\pm E) + z = \bigcup_{z \in B_R} T_h^\pm(E+z) \subseteq T_h^\pm E'.$$

\square

Lemma 6.5. *For any $R > 0$ we have $T_h^\pm(B_R) \subseteq B_{CR}$, where C depends only on the dimension N .*

Proof. By Lemma 6.4 we have

$$(6.5) \quad T_h^\pm(B_R) + B_R \subseteq T_h^\pm(B_{2R}).$$

Let $c > 1$, and assume there exists $x \in T_h^\pm(B_R) \setminus B_{cR}$. Since in particular $x \in T_h^\pm(B_R)$, by (6.5) we have $B(x, R) \subseteq T_h^\pm(B_{2R})$. Hence

$$\begin{aligned} 0 &> J(T_h^\pm(B_{2R})) + \frac{1}{h} \int_{T_h^\pm(B_{2R})} |y| - 2R \, dy \\ &\geq \frac{1}{h} \left(\int_{B(x,R)} |y| - 2R \, dy + \int_{T_h^\pm(B_{2R}) \setminus B(x,R)} |y| - 2R \, dy \right) \\ &\geq \frac{1}{h} \left(\int_{B(x,R)} |y| - 2R \, dy + \int_{B_{2R}} |y| - 2R \, dy \right) \\ &\geq \frac{1}{h} \left(\int_{B_R} (c-2)R - |y| \, dy + \int_{B_{2R}} |y| - 2R \, dy \right) \end{aligned}$$

which is positive if c is large enough (depending only on the dimension), a contradiction. \square

Next lemma provides a more refined estimate.

Lemma 6.6. *Let $C > 1$ be such that the statement of Lemma 6.5 holds, and let \underline{c}, \bar{c} be as in (2.2). Then, the following holds.*

- i) *Let $R > 0$. Then, for every $h > 0$ such that $R - h\underline{c}(CR) > 0$ we have $T_h^\pm B_R \subseteq B_{R-h\underline{c}(CR)}$.*

- ii) Let $R_0 > 0$ and $\sigma > 1$ be fixed. Then, for $h > 0$ small enough (depending on R_0 and σ), we have $T_h^\pm B_R \supseteq B_{R-h\bar{c}(R/\sigma)}$ for all $R \geq R_0$.

Proof. First, we know from the previous result that $T_h^\pm B_R \subseteq B_{CR}$.

Proof of i). We can always assume $T_h^\pm B_R \neq \emptyset$. Let $\bar{\rho} = \sup\{\rho \in [0, CR] : |T_h^\pm B_R \setminus B_\rho| > 0\}$. Let $\bar{x} \in \partial B_{\bar{\rho}}$ such that $|T_h^\pm B_R \cap B(\bar{x}, \varepsilon)| > 0$ for any $\varepsilon > 0$, and let $\rho > \bar{\rho}$. Let $\tau \in \mathbb{R}^N$ be such that $B(-\tau, \rho) \supset B_{\bar{\rho}}$ and $\partial B(-\tau, \rho)$ is tangent to $\partial B_{\bar{\rho}}$ at \bar{x} ; i.e., $\tau = (\rho/\bar{\rho} - 1)\bar{x}$.

We let for $\varepsilon > 0$ small $B^\varepsilon = B(-(1+\varepsilon)\tau, \rho)$ and $W^\varepsilon = T_h^\pm B_R \setminus B^\varepsilon$. Notice that by construction W^ε has positive measure and converges to \bar{x} in the Hausdorff sense as $\varepsilon \rightarrow 0$. By submodularity we have

$$(6.6) \quad J(B^\varepsilon \cap T_h^\pm B_R) + J(B^\varepsilon \cup T_h^\pm B_R) \leq J(B^\varepsilon) + J(T_h^\pm B_R).$$

By (6.6) and using the minimality of $T_h^\pm B_R$ we have

$$\begin{aligned} J(B(-\tau, \rho) \cup (W^\varepsilon + \varepsilon\tau)) - J(B(-\tau, \rho)) &= J(B^\varepsilon \cup W^\varepsilon) - J(B^\varepsilon) \\ &\leq J(T_h^\pm B_R) - J(B^\varepsilon \cap T_h^\pm B_R) \leq -\frac{1}{h} \int_{W^\varepsilon} |x| - R \, dx. \end{aligned}$$

Dividing the previous inequality by $|W^\varepsilon|$ and passing to the limit as $\varepsilon \rightarrow 0$, in view of the very definition (4.5) of κ we get

$$\kappa(B(-\tau, \rho)) \leq \frac{1}{h}(R - |\bar{x}|) = \frac{1}{h}(R - \bar{\rho}).$$

Recalling the definition of \underline{c} and the fact that it is a continuous decreasing function, we deduce the thesis by sending $\rho \rightarrow \bar{\rho}$.

Proof of ii). Assume x_0 is such that

$$\bar{\rho} = \max\{\rho > 0 : |B(x_0, \rho) \setminus T_h^\pm B_R| = 0\} \in]0, 2CR].$$

As in the proof of i), we can find $\bar{x} \in \partial B(x_0, \bar{\rho})$ such that $|B(\bar{x}, \varepsilon) \setminus T_h^\pm B_R| > 0$ for any $\varepsilon > 0$, we fix $\rho < \bar{\rho}$ and set $\tau = (1 - \rho/\bar{\rho})(\bar{x} - x_0)$, so that $\{\bar{x}\} = \partial B(x_0, \bar{\rho}) \cap \partial B(x_0 + \tau, \rho)$. We let $B^\varepsilon = B(x_0 + (1+\varepsilon)\tau, \rho)$ and define $W^\varepsilon = B^\varepsilon \setminus T_h^\pm B_R$. By submodularity we have

$$J(B^\varepsilon \cap T_h^\pm B_R) + J(B^\varepsilon \cup T_h^\pm B_R) \leq J(B^\varepsilon) + J(T_h^\pm B_R).$$

Using the minimality of $T_h^\pm(B_R)$ we deduce

$$J(B^\varepsilon \setminus W^\varepsilon) - J(B^\varepsilon) \leq J(T_h^\pm B_R) - J(B^\varepsilon \cup T_h^\pm B_R) \leq \frac{1}{h} \int_{W^\varepsilon} |x| - R \, dx.$$

Dividing the previous inequality by $|W^\varepsilon|$ and passing to the limit as $\varepsilon \rightarrow 0$, in view of the very definition of κ (4.6) we get

$$-\kappa(\bar{x}, B^\varepsilon) \leq \frac{1}{h}(|\bar{x}| - R).$$

It follows that $|\bar{x}| \geq R - h\bar{c}(\bar{\rho})$.

Now, let C be the constant of Lemma 6.5, and choose h so small that

$$J(B_{R_0/8C}) + \frac{1}{h} \int_{B_{R_0/8C}} |x| - \frac{R}{4C} \, dx \leq J(B_{R_0/8C}) - \frac{R_0}{8Ch} |B_{R_0/(8C)}| < 0,$$

so that $T_h^\pm B_{R/4C} \neq \emptyset$. Note that $B_{R/4C} + B_{3R/4} \subseteq B_R$. Thus, by Lemma 6.4 $T_h^\pm(B_{R/4C}) + B_{3R/4} \subseteq T_h^\pm B_R$. In particular, if $x_0 \in T_h^\pm B_{R/(4C)}$ it follows that $B(x_0, \frac{3R}{4}) \subseteq T_h^\pm B_R$. By the first part of the proof of ii), we find that $B(x_0, |\bar{x} - x_0|) \subseteq T_h^\pm B_R$ for some \bar{x} with $|\bar{x}| \geq R - h\bar{c}(3R/4)$. Hence, recalling also that, thanks to Lemma 6.5 $x_0 \in T_h^\pm B_{R/(4C)} \subseteq B_{R/4}$, we obtain that $B_{R/4} \subseteq T_h^\pm B_R$, provided that h is small enough. We can now use again the previous analysis with $x_0 = 0$, $\bar{\rho} \geq R/4$ and we deduce that if h is small enough, $B_{R-h\bar{c}(R/4)} \subseteq T_h^\pm B_R$.

Applying once again the first part of the proof with $x_0 = 0$ and $\bar{\rho} \geq R - h\bar{c}(R/4)$ we conclude that, if h is small enough, $B_{R-h\bar{c}(R/\sigma)} \subseteq B_{R-h\bar{c}(R-h\bar{c}(R/4))} \subseteq T_h^\pm B_R$. \square

6.2. The time discrete scheme for unbounded sets. Here we show how to extend the time discrete scheme to the case of unbounded sets with bounded complement. To this purpose, we introduce the perimeter \tilde{J} defined as

$$\tilde{J}(E) := J(\mathbb{R}^N \setminus E) \quad \text{for all } E \in \mathfrak{M}.$$

Note that \tilde{J} satisfies all the structural assumptions of generalized perimeters. Let $\tilde{\kappa}$ be the corresponding curvature. Then, it is easy to see that $\tilde{\kappa}(x, E) = -\kappa(x, \mathbb{R}^N \setminus E)$, and thus

$$(6.7) \quad \begin{aligned} \max_{x \in \partial B_\rho} \max\{\tilde{\kappa}(x, B_\rho), -\tilde{\kappa}(x, \mathbb{R}^N \setminus B_\rho)\} &= \bar{c}(\rho) \\ \min_{x \in \partial B_\rho} \min\{\tilde{\kappa}(x, B_\rho), -\tilde{\kappa}(x, \mathbb{R}^N \setminus B_\rho)\} &= \underline{c}(\rho), \end{aligned}$$

where $\bar{c}(\rho)$, $\underline{c}(\rho)$ are the functions defined in (2.1) and (2.2).

For every bounded set F we denote by $\tilde{T}_h^\pm(F)$ the maximal and the minimal solution to problem (6.2), according to Proposition 6.1 with J replaced by \tilde{J} . Finally, for every $E \subseteq \mathbb{R}^N$ such that $F := \mathbb{R}^N \setminus E$ is bounded we set

$$(6.8) \quad T_h^\pm E := \mathbb{R}^N \setminus \tilde{T}_h^\mp(\mathbb{R}^N \setminus E).$$

As in the case of bounded sets, we let $T_h E := T_h^- E$.

Taking into account also (6.7), one can easily check that Lemmas 6.5 and 6.6 translate into the following statements:

Lemma 6.7. *For any $R > 0$ we have $\mathbb{R}^N \setminus B_{CR} \subseteq T_h^\pm(\mathbb{R}^N \setminus B_R)$, where C depends only on the dimension N .*

Lemma 6.8. *Let $C > 1$ be such that the statement of Lemma 6.5 holds, and let \underline{c} , \bar{c} be as in (2.2). Then, the following holds:*

- i) *Let $R > 0$. Then, $\mathbb{R}^N \setminus B_{R-h\underline{c}(CR)} \subseteq T_h^\pm(\mathbb{R}^N \setminus B_R)$ for every $h > 0$ such that $R - h\underline{c}(CR) > 0$;*
- ii) *Let $R_0 > 0$ and $\sigma > 1$ be fixed. Then, for $h > 0$ small enough (depending on R_0 and σ), we have $T_h^\pm(\mathbb{R}^N \setminus B_R) \subseteq \mathbb{R}^N \setminus B_{R-h\bar{c}(R/\sigma)}$ for all $R \geq R_0$.*

Remark 6.9. A consequence of Lemmas 6.5, 6.7 is that $T_h B_R \subseteq B_{R+hK}$ and $\mathbb{R}^N \setminus B_{R+hK} \subseteq T_h(\mathbb{R}^N \setminus B_R)$ for any $h > 0$ and any $R > 0$, where K is defined in (2.3). In particular, iterating these estimates, we deduce that $T_h^{[t/h]} B_R \subseteq B_{R+tK}$ and $\mathbb{R}^N \setminus B_{R+tK} \subseteq T_h^{[t/h]}(\mathbb{R}^N \setminus B_R)$. In the limit as $h \rightarrow 0$, we will get an estimate for the extinction time of balls in the superlevels of our level set function (see Proposition 6.15).

Note now that by Lemma 6.2 (applied to \tilde{J} in place of J) and (6.8) if E_1, E_2 are unbounded sets with compact boundary, then

$$E_1 \subseteq E_2 \implies T_h^\pm E_1 \subseteq T_h^\pm E_2.$$

It remains to consider the case of E_1 bounded and E_2 unbounded.

Lemma 6.10. *Let $E_1 \in \mathfrak{M}$ be bounded and let $E_2 \in \mathfrak{M}$ be unbounded, with compact boundary, and such that $E_1 \subseteq E_2$. Then, $T_h^\pm E_1 \subseteq T_h^\pm E_2$.*

Proof. Choose $R > 0$ so large that $E_1, \mathbb{R}^N \setminus E_2 \subseteq B_R$ and note that by Lemmas 6.2 and 6.5 (applied to \tilde{J} in place of J) we get

$$(6.9) \quad \mathbb{R}^N \setminus T_h^+ E_2 = \tilde{T}^-(\mathbb{R}^N \setminus E_2) \subseteq \tilde{T}^- B_R \subseteq B_{CR}$$

for some $C > 0$ depending only on N . Recall that $\tilde{T}_h^-(\mathbb{R}^N \setminus E_2)$ is the minimal solution of

$$\min \left\{ J(\mathbb{R}^N \setminus F) + \frac{1}{h} \int_F d_{\mathbb{R}^N \setminus E_2} dx : F \in \mathfrak{M} \right\}.$$

Considering the change of variable $\tilde{F} := \mathbb{R}^N \setminus F$ and using that $d_{\mathbb{R}^N \setminus E_2} = -d_{E_2}$, we easily infer that $T_h^+ E_2 = \mathbb{R}^N \setminus \tilde{T}_h^-(\mathbb{R}^N \setminus E_2)$ is the maximal solution of

$$\begin{aligned} & \min \left\{ J(\tilde{F}) - \frac{1}{h} \int_{\mathbb{R}^N \setminus \tilde{F}} d_{E_2} dx : \tilde{F} \in \mathfrak{M} \right\} \\ &= \min \left\{ J(\tilde{F}) + \frac{1}{h} \int_{B_{CR}} d_{E_2} dx - \frac{1}{h} \int_{\mathbb{R}^N \setminus \tilde{F}} d_{E_2} dx : \tilde{F} \in \mathfrak{M} \right\} - \frac{1}{h} \int_{B_{CR}} d_{E_2} dx. \end{aligned}$$

Note now that

$$\int_{\tilde{F}} d_{E_2} \chi_{B_{CR}} dx = \int_{B_{CR}} d_{E_2} dx - \int_{\mathbb{R}^N \setminus \tilde{F}} d_{E_2} dx$$

for every \tilde{F} with $\mathbb{R}^N \setminus \tilde{F} \subseteq B_{CR}$. It follows, also by (6.9), that $T_h^+ E_2$ is the maximal solution of

$$(6.10) \quad \min \left\{ J(\tilde{F}) + \frac{1}{h} \int_{\tilde{F}} d_{E_2} \chi_{B_{CR}} dx : \tilde{F} \in \mathfrak{M}, \mathbb{R}^N \setminus \tilde{F} \subseteq B_{CR} \right\}.$$

By the same reasoning, one can show that $T_h^- E_2$ is the minimal solution of (6.10). Observing that $d_{E_2} \chi_{B_{CR}} \leq d_{E_1}$ and that $T_h^\pm E_1 \cup T_h^\pm E_2$, $T_h^\pm E_1 \cap T_h^\pm E_2$ are admissible competitors for (6.10), one can argue exactly as in the proof of Lemma 6.2 to conclude that $T_h^\pm E_1 \subseteq T_h^\pm E_2$. \square

6.3. The level-set approach. Given any bounded uniformly continuous function $u : \mathbb{R}^N \rightarrow \mathbb{R}$, constant outside a compact set, we introduce a transformation of u which is defined by applying T_h to all the superlevel sets of u . This is standard and has been done in a similar geometric setting in many papers (see [16, 22]).

To this purpose, notice that all the superlevels of u are either bounded or with bounded complement, and that for any couple of levels $s > s' \in \mathbb{R}$ we have $\{u > s\} \subseteq \{u > s'\}$. Thus, in view of Lemma 6.2 we have $T_h\{u > s\} \subseteq T_h\{u > s'\}$.

Let $\omega : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ an increasing, continuous modulus of continuity for u . Since

$$\{u > s\} + B_{\omega^{-1}(s-s')} \subseteq \{u > s'\},$$

by Lemma 6.4 we deduce that

$$T_h\{u > s\} + B_{\omega^{-1}(s-s')} \subseteq T_h\{u > s'\}.$$

It follows that the sets $T_h\{u > s\}$ are themselves the level sets $\{v > s\}$ of a uniformly continuous function $v := T_h u$, with the same modulus of continuity. More precisely, we set $T_h u(x) := \sup\{\lambda \in \mathbb{R} : x \in T_h\{u > \lambda\}\}$. Notice that, by Lemmas 6.5 and 6.7, also $T_h u$ is constant out of a compact set. Moreover, if $u \geq u'$, then $T_h u \geq T_h u'$. In the two following propositions, equality between sets must be understood up to negligible sets.

Proposition 6.11. *For every $\lambda \in \mathbb{R}$ we have*

$$T_h(\{u > \lambda\}) = T_h^-(\{u > \lambda\}) = \{T_h u > \lambda\}.$$

Analogously,

$$T_h^+(\{u \geq \lambda\}) = \{T_h u \geq \lambda\}.$$

Proof. For every $\delta \geq 0$ set

$$E_\delta := T_h(\{u > \lambda + \delta\}), \quad A_\delta := \{T_h u > \lambda + \delta\}.$$

We have to prove that $E_0 = A_0$. First, notice that by the very definition of $T_h u$, for every $\delta \geq 0$

$$(6.11) \quad A_\delta \subseteq E_\delta$$

so that in particular $A_0 \subseteq E_0$. To prove the reverse inclusion, observe that

$$(6.12) \quad d_{\{u > \lambda + \delta\}} \rightarrow d_{\{u > \lambda\}}$$

uniformly as $\delta \rightarrow 0$. Moreover, $A_\delta \nearrow A_0$ in L^1_{loc} as $\delta \rightarrow 0$. By (6.12) and by the lower semicontinuity of J , it easily follows that A_0 is a solution of (6.2) with E replaced by $\{u > \lambda\}$ (or of (6.10) in the unbounded case, with E_2 replaced by $\{u > \lambda\}$). Moreover, by (6.11) it is the minimal one, i.e., it coincides with E_0 . The similar proof of the second statement is left to the interested reader. \square

Given a continuous function u^0 constant outside of a bounded set, define

$$(6.13) \quad u_h(x, t) = T_h^{[t/h]}(u_0)(x)$$

for every $h > 0$, $t \geq 0$, where $[\cdot]$ denotes the integer part.

Proposition 6.11 applied to $u_h(\cdot, (k-1)h)$ yields the following:

Proposition 6.12. *For every $h, k > 0$ and for every $\lambda \in \mathbb{R}$ we have*

$$T_h^-(\{u_h(\cdot, (k-1)h) > \lambda\}) = \{u_h(\cdot, kh) > \lambda\}$$

and

$$T_h^+(\{u_h(\cdot, (k-1)h) \geq \lambda\}) = \{u_h(\cdot, kh) \geq \lambda\}.$$

We have seen that for all t , $u_h(\cdot, t)$ is uniformly continuous (with the same modulus ω as u^0). Let us now study the regularity in time of this function.

Lemma 6.13. *For any $\varepsilon > 0$, there exists $\tau > 0$ and $h_0 > 0$ (depending on ε) such that for all $|t - t'| \leq \tau$ and $h \leq h_0$ we have $|u_h(\cdot, t) - u_h(\cdot, t')| < \varepsilon$.*

Proof. Let $\varepsilon > 0$ and let $R_0 := \omega^{-1}(\varepsilon/2)/2$. Since ω is a modulus of continuity for u_h it readily follows that for every x

$$(6.14) \quad B(x, \omega^{-1}(\varepsilon/2)) \subseteq \{u_h(\cdot, t) > u_h(x, t) - \varepsilon\}.$$

We only treat the case where $\{u_h(\cdot, t) > u_h(x, t) - \varepsilon\}$ is bounded, the other being analogous. Let $\tau := R_0/\bar{c}(R_0/4)$. By part ii) of Lemma 6.6, and using that \bar{c} is a monotone decreasing function, there exists h_0 depending on R_0 such that

$$(6.15) \quad B(x, R_0) \subseteq B(x, \omega^{-1}(\varepsilon/2) - nh\bar{c}(R_0/4)) \subseteq T_h^n B(x, \omega^{-1}(\varepsilon/2))$$

as long as $\omega^{-1}(\varepsilon/2) - nh\bar{c}(R_0/4) \geq R_0$, i.e., as long as $nh \leq \tau$.

Now, let $t' > t$ such that $t' - t \leq \tau$, and let $n := [(t' - t)/h]$. Since $nh \leq \tau$, by (6.14), (6.15), Lemma 6.2, and Proposition 6.12 we have

$$\begin{aligned} \{u_h(\cdot, t') > u_h(x, t') - \varepsilon\} &= \{u_h(\cdot, t + nh) > u_h(x, t) - \varepsilon\} = \\ T_h^n \{u_h(\cdot, t) > u_h(x, t) - \varepsilon\} &\supseteq T_h^n B(x, \omega^{-1}(\varepsilon/2)) \supseteq B(x, R_0). \end{aligned}$$

In particular, $u_h(x, t') > u_h(x, t) - \varepsilon$. In order to show

$$u_h(x, t') < u_h(x, t) + \varepsilon$$

we proceed in a similar way. Precisely, we observe that

$$B(x, \omega^{-1}(\varepsilon/2)) \subseteq \{u_h(\cdot, t) < u_h(x, t) + \varepsilon\},$$

that is,

$$\{u_h(\cdot, t) \geq u_h(x, t) + \varepsilon\} \subseteq \mathbb{R}^N \setminus B(x, \omega^{-1}(\varepsilon/2)).$$

We then proceed as in the first part of the proof, but now using Lemma 6.7 instead of Lemma 6.5 and Lemma 6.10 instead of Lemma 6.2. \square

6.4. Convergence analysis. In this subsection we show that any limit of the discrete evolutions is a viscosity solution. Recalling Lemma 6.13 and the uniform continuity in space of u_h , by a straightforward variant of Ascoli-Arzelà's Theorem we deduce the precompactness of u_h . Moreover, in view of Remark 6.9 we deduce also that the limit u is constant out of a compact set. Summarizing, the following proposition holds.

Proposition 6.14. *Let $T > 0$. Up to a subsequence, u_h converges uniformly on $\mathbb{R}^N \times [0, T]$ as $h \rightarrow 0$ to a function $u(x, t)$, which is bounded and uniformly continuous, and constant out of a compact set.*

For every $r > 0$, set

$$(6.16) \quad \hat{c}(r) := \max\{1, \bar{c}(r)\}.$$

Given $r_0 > 0$, let $r(t)$ be the solution of the following ODE

$$(6.17) \quad \begin{cases} \dot{r}(t) = -\hat{c}(r(t)); \\ r(0) = r_0 \end{cases}$$

Notice that (6.17) admits a unique solution $r(t)$ until some extinction time $T^*(r_0)$ with $r(T^*) = 0$.

Proposition 6.15. *Let $u(x, t)$ be the function given by Proposition 6.14, let $\lambda \in \mathbb{R}$, and let $B(x_0, r_0) \subset \{u(\cdot, t_0) > \lambda\}$. Then, $B(x_0, r(t-t_0)) \subset \{u(\cdot, t) > \lambda\}$ for every $t \leq T^*(r_0) + t_0$, where $r(t)$ is the solution of the ODE (6.17) and $T^*(r_0)$ is its extinction time. The same statement holds by replacing the superlevel of u with its sublevel.*

Proof. We only treat the case of $\{u(\cdot, t) > \lambda\}$ bounded, since the other one is analogous. By assumption, if $R_0 < r_0$, for h small enough $B(x_0, R_0) \subset \{u_h(\cdot, t_0) > \lambda\}$. Let $\sigma > 1$ and R_0 be defined recursively by $R_{n+1} = R_n - h\bar{c}(R_n/\sigma)$. By Lemmas 6.2, 6.6, and 6.12 one has that $B(x_0, R_{[(t-t_0)/h]+1}) \subset \{u_h(\cdot, t) > \lambda\}$ for $t \geq t_0$, as long as $R_{[(t-t_0)/h]+1} > 0$. Let also r_σ be the unique solution of $\dot{r}_\sigma(t) = -\hat{c}(r_\sigma(t)/\sigma)$ with initial value $r_\sigma(0) = R_0$. One observes that if $r_\sigma(nh) \leq R_n$, then

$$\begin{aligned} r_\sigma((n+1)h) &\leq R_n - \int_{nh}^{(n+1)h} \hat{c}\left(\frac{r_\sigma(s)}{\sigma}\right) ds \\ &\leq R_n - \int_{nh}^{(n+1)h} \hat{c}\left(\frac{R_n}{\sigma}\right) ds \leq R_n - \int_{nh}^{(n+1)h} \bar{c}\left(\frac{R_n}{\sigma}\right) ds = R_{n+1} \end{aligned}$$

since \hat{c} is nondecreasing. As a consequence, $B(x_0, r_\sigma(h[(t-t_0)/h]+h)) \subset \{u_h(\cdot, t) > \lambda\}$ for $t \geq t_0$ as long as the radius is positive. We conclude sending $h \rightarrow 0$, then $R_0 \rightarrow r_0$ and $\sigma \rightarrow 1$. The proof of the last part of the proposition is very similar. One observes that by Lemmas 6.10, 6.8, and 6.12, we have (with the same definition of R_n) $\{u_h(\cdot, t) > \lambda\} \subset \mathbb{R}^N \setminus B(x_0, R_{[(t-t_0)/h]+1})$, that is $B(x_0, R_{[(t-t_0)/h]+1}) \subset \{u_h(\cdot, t) \leq \lambda\}$ for $t \geq t_0$, as long as $R_{[(t-t_0)/h]+1} > 0$. The conclusion then follows as before. \square

We are now in a position to state and prove the main result of this section.

Theorem 6.16. *The function u provided by Proposition 6.14 is a viscosity solution of the Cauchy problem (2.4) in the sense of Definition 2.11.*

Remark 6.17. We observe that this holds under assumptions C) and D) on the curvature. If in addition C') holds, then the limit flow is unique and one also deduces that the whole family $(u_h)_{h>0}$ converges uniformly as $h \rightarrow 0$.

Proof. We denote by u_{h_k} a subsequence of u_h converging to u . Let us prove that u is a subsolution (the proof that it is a supersolution is identical). Let $(\bar{x}, \bar{t}) \in$

$\mathbb{R}^N \times (0, T)$. Let φ be a $C^{\ell, \beta}$ admissible test function at (\bar{x}, \bar{t}) , and assume that (\bar{x}, \bar{t}) is a maximum point of $u - \varphi$. We need to show that

$$(6.18) \quad \frac{\partial \varphi}{\partial t}(\bar{x}, \bar{t}) + |D\varphi(\bar{x}, \bar{t})| \kappa_*(\bar{x}, D\varphi(\bar{x}, \bar{t}), D^2\varphi(\bar{x}, \bar{t}), \{\varphi(\cdot, \bar{t}) \geq \varphi(\bar{x}, \bar{t})\}) \leq 0.$$

Step 1. Let us first assume that $D\varphi(\bar{x}, \bar{t}) \neq 0$. By Remark 2.12 we can assume that this is a strict maximum point and that φ is smooth.

If the maximum is strict, then by standard methods we can find $(x_k, t_k) \rightarrow (\bar{x}, \bar{t})$ such that $u_{h_k} - \varphi$ has a maximum at (x_k, t_k) . Moreover, for k large enough, $D\varphi(x_k, t_k) \neq 0$. We have that for all (x, t) ,

$$(6.19) \quad u_{h_k}(x, t) \leq \varphi(x, t) + c_k$$

where $c_k := [u_{h_k}(x_k, t_k) - \varphi(x_k, t_k)]$, with equality if $(x, t) = (x_k, t_k)$.

Let $\eta > 0$ and set

$$(6.20) \quad \varphi_{h_k}^\eta(x) = \varphi(x, t_k) + c_k + \frac{\eta}{2} Q(x - x_k),$$

where Q is as in Lemma 2.13 and $Q(z) = |z|^2$ for $|z|$ sufficiently small. Then, for all $x \in \mathbb{R}^N$,

$$u_{h_k}(x, t_k) \leq \varphi_{h_k}^\eta(x)$$

with equality *if and only if* $x = x_k$. We set $l_k := u_{h_k}(x_k, t_k) = \varphi_{h_k}^\eta(x_k)$.

By Lemma 2.13, we can assume that η is such that the superlevel sets $\{\varphi_{h_k}^\eta \geq l_k\}$ are not critical for all k . Let $\varepsilon > 0$ and set

$$W_\varepsilon := \{x \in \mathbb{R}^N : u_{h_k}(x, t_k) \geq l_k - \varepsilon\} \setminus \{x \in \mathbb{R}^N : \varphi_{h_k}^\eta(x) \geq l_k\}.$$

It is easy to see that for $\varepsilon > 0$ sufficiently small $|W_\varepsilon| > 0$, and converges to $\{x_k\}$ in the Hausdorff sense as $\varepsilon \rightarrow 0$. Now, if $\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\}$ is bounded, by minimality we have

$$(6.21) \quad \begin{aligned} J(\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\}) &+ \frac{1}{h_k} \int_{\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\}} d_{\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\}}(x) dx \\ &\leq J(\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cap \{\varphi_{h_k}^\eta \geq l_k\}) \\ &+ \frac{1}{h_k} \int_{\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cap \{\varphi_{h_k}^\eta \geq l_k\}} d_{\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\}}(x) dx. \end{aligned}$$

Adding to both sides the term $J(\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cup \{\varphi_{h_k}^\eta \geq l_k\})$ and using (4.1), we obtain

$$J(\{\varphi_{h_k}^\eta \geq l_k\} \cup W_\varepsilon) - J(\{\varphi_{h_k}^\eta \geq l_k\}) + \frac{1}{h_k} \int_{W_\varepsilon} d_{\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\}}(x) dx \leq 0.$$

By (6.19), $\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\} \subseteq \{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}$, so that we also have

$$(6.22) \quad \begin{aligned} J(\{\varphi_{h_k}^\eta \geq l_k\} \cup W_\varepsilon) - J(\{\varphi_{h_k}^\eta \geq l_k\}) \\ + \frac{1}{h_k} \int_{W_\varepsilon} d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(x) dx \leq 0. \end{aligned}$$

If instead $\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\}$ is unbounded, then inequality (6.21) must be replaced by

$$\begin{aligned} J(\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\}) &+ \frac{1}{h_k} \int_{\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cap B_R} d_{\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\}}(x) dx \\ &\leq J(\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cap \{\varphi_{h_k}^\eta \geq l_k\}) \\ &+ \frac{1}{h_k} \int_{\{u_{h_k}(\cdot, t_k) \geq l_k - \varepsilon\} \cap \{\varphi_{h_k}^\eta \geq l_k\} \cap B_R} d_{\{u_{h_k}(\cdot, t_k - h_k) \geq l_k - \varepsilon\}}(x) dx, \end{aligned}$$

for R sufficiently large, see (6.10). Then, arguing as before, one obtains again (6.22).

Notice that for $z \in W_\varepsilon$ we have

$$(6.23) \quad l_k - \varepsilon < \varphi(z, t_k) + c_k + \frac{\eta}{2}Q(z - x_k) < l_k.$$

Since, in turn, $\varphi(z, t_k) + c_k \geq l_k - \varepsilon$ it follows that $\frac{\eta}{2}Q(z - x_k) < \varepsilon$ and thus, for ε small enough,

$$(6.24) \quad W_\varepsilon \subseteq B_{C\sqrt{\varepsilon}}(x_k).$$

Moreover, for every $z \in W_\varepsilon$

$$(6.25) \quad \varphi(z, t_k - h_k) = \varphi(z, t_k) - h_k \partial_t \varphi(z, t_k) + h_k^2 \int_0^1 (1-s) \partial_{tt}^2 \varphi(z, t_k - sh_k) ds.$$

Let y be a point of minimal distance from z such that $\varphi(y, t_k - h_k) = l_k - c_k - \varepsilon$. Then, $|z - y| = |d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(z)|$, and

$$(6.26) \quad (z - y) \cdot D\varphi(y, t_k - h_k) = \pm |z - y| |D\varphi(y, t_k - h_k)|,$$

with a '+' if $\varphi(z, t_k - h_k) > l_k - c_k - \varepsilon$ and a '-' else, so that the sign is opposite to the sign of $d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(z)$. Hence,

$$(6.27) \quad \begin{aligned} \varphi(z, t_k - h_k) &= \varphi(y, t_k - h_k) + (z - y) \cdot D\varphi(y, t_k - h_k) \\ &+ \int_0^1 (1-s) (D^2\varphi(y + s(z-y), t_k - h_k)(z-y)) \cdot (z-y) ds \\ &= l_k - c_k - \varepsilon - d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(z) |D\varphi(y, t_k - h_k)| \\ &+ \int_0^1 (1-s) (D^2\varphi(y + s(z-y), t_k - h_k)(z-y)) \cdot (z-y) ds. \end{aligned}$$

By (6.23) we deduce in particular $\varphi(x, t_k) + c_k < l_k$, i.e.,

$$(6.28) \quad -\varphi(x, t_k) \geq c_k - l_k.$$

Combining (6.28), (6.25), and (6.27), we deduce

$$\begin{aligned} &d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(z) |D\varphi(y, t_k - h_k)| \\ &\geq -\varepsilon + h_k \partial_t \varphi(z, t_k) - h_k^2 \int_0^1 (1-s) \partial_{tt}^2 \varphi(z, t_k - sh_k) ds \\ &+ \int_0^1 (1-s) (D^2\varphi(y + s(z-y), t_k - h_k)(z-y)) \cdot (z-y) ds. \end{aligned}$$

Note that, in view of (6.23), $|\varphi(z, t_k) - \varphi(y, t_k)| \leq \varepsilon + Ch_k = O(h_k)$, provided that $\varepsilon \ll h_k$ are small enough. In turn, by (6.26) as $|D\varphi(y, t_k - h_k)|$ is bounded away from zero, we have $|z - y| = O(h_k)$ and, using also (6.24), we deduce

$$(6.29) \quad \begin{aligned} \frac{1}{h_k} d_{\{\varphi(\cdot, t_k - h_k) \geq l_k - c_k - \varepsilon\}}(z) &\geq \frac{\partial_t \varphi(z, t_k) - \frac{\varepsilon}{h_k} + O(h_k)}{|D\varphi(y, t_k - h_k)|} \\ &= \frac{\partial_t \varphi(x_k, t_k) + O(\sqrt{\varepsilon}) - \frac{\varepsilon}{h_k} + O(h_k)}{|D\varphi(x_k, t_k)| + O(\sqrt{\varepsilon}) + O(h_k)}. \end{aligned}$$

We now focus on the term

$$J(\{\varphi_{h_k}^\eta \geq l_k\} \cup W_\varepsilon) - J(\{\varphi_{h_k}^\eta \geq l_k\})$$

of inequality (6.22). Thanks to (4.5), if ε is small enough we know that

$$(6.30) \quad \begin{aligned} &J(\{\varphi_{h_k}^\eta \geq l_k\} \cup W_\varepsilon) - J(\{\varphi_{h_k}^\eta \geq l_k\}) \\ &\geq |W_\varepsilon| (\kappa(x_k, \{\varphi_{h_k}^\eta \geq \varphi_{h_k}^\eta(x_k)\}) - o_\varepsilon(1)), \end{aligned}$$

recalling that $\varphi_{h_k}^\eta(x_k)$ is not a critical value of $\varphi_{h_k}^\eta$.

Using therefore (6.22), (6.29) and (6.30), dividing by $|W_\varepsilon|$ and sending $\varepsilon \rightarrow 0$, we deduce that (for a.e. $\eta > 0$ small)

$$\frac{\partial_t \varphi(x_k, t_k) + O(h_k)}{|D\varphi(x_k, t_k)| + O(h_k)} + \kappa(x_k, \{\varphi_{h_k}^\eta \geq \varphi_{h_k}^\eta(x_k)\}) \leq 0.$$

Letting simultaneously $\eta \rightarrow 0$ and $k \rightarrow \infty$ and using Lemma 2.9 we deduce (6.18).

Step 2. Now we consider the case $D\varphi(\bar{z}) = 0$ and we show that $\varphi_t(\bar{z}) \leq 0$. Let ψ_n be defined as in (2.16) and let $z_n = (x_n, t_n)$ be a sequence of maximizers of $u - \psi_n$, such that $x_n \rightarrow \bar{x}$ and $t_n \rightarrow \bar{t}^-$. If $x_n \neq \bar{x}$ for a (not relabeled) subsequence, then (for large n) $D\psi_n(x_n, t_n) \neq 0$ and (6.18) holds for ψ_n at z_n . Passing to the limit and using the properties of f (where f is the function appearing in (2.16)), we deduce that $\frac{\partial \varphi}{\partial t}(\bar{z}) \leq 0$ (see (2.17) for the details).

We therefore assume that $z_n = (\bar{x}, t_n)$ for all n sufficiently large. Set $b_n := \bar{t} - t_n$ and set

$$(6.31) \quad r_n := f^{-1}(a_n b_n),$$

where $a_n \rightarrow 0$ is chosen so that the extinction time $T^*(r_n)$ of the solution of (6.17) with r_0 replaced by r_n , satisfies $T^*(r_n) \geq 2b_n$ for n large enough. To show that such a choice for a_n is possible, set

$$g(t) = \sup_{0 \leq s \leq t} \hat{c}(f^{-1}(s))f'(f^{-1}(s)),$$

and notice that $g(t) \leq \hat{c}(t)$ for t small, it is non decreasing in t , and $g(t) \rightarrow 0$ as $t \rightarrow 0$ thanks to (2.6). We have

$$(6.32) \quad \begin{aligned} \frac{T^*(r_n)}{b_n} &\geq \frac{1}{b_n} \int_{r_n/2}^{r_n} \frac{1}{\hat{c}(r)} = \frac{1}{b_n} \int_{f^{-1}(a_n b_n/2)}^{f^{-1}(a_n b_n)} \frac{1}{\hat{c}(r)} \\ &= \frac{a_n}{2} \int_{a_n b_n/2}^{a_n b_n} \frac{1}{\hat{c}(f^{-1}(s))f'(f^{-1}(s))} ds \geq \frac{a_n}{2} \frac{1}{g(b_n)} = 2. \end{aligned}$$

where the last equality holds if we choose $a_n = 4g(b_n) \rightarrow 0$.

By definition of ψ_n , we have that

$$\begin{aligned} B(\bar{x}, r_n) &\subset \{\psi_n(\cdot, t_n) \leq \psi_n(\bar{x}, t_n) + 2f(r_n)\} \\ &\subset \{u(\cdot, t_n) \leq u(\bar{x}, t_n) + 2f(r_n)\}. \end{aligned}$$

Note that the last inclusion follows from the maximality of $u - \psi_n$ at z_n and the fact that $u(z_n) = \psi_n(z_n)$. By (6.32) and Proposition 6.15,

$$\bar{x} \in \{u(\cdot, \bar{t}) \leq u(\bar{x}, t_n) + 2f(r_n)\}.$$

Thus, using also the maximality of $u - \varphi$ at \bar{z} , and recalling (6.31), we have

$$\frac{\varphi(\bar{x}, t_n) - \varphi(\bar{z})}{-b_n} \leq \frac{u(\bar{x}, t_n) - u(\bar{x}, \bar{t})}{-b_n} \leq \frac{2f(r_n)}{-b_n} = -2a_n.$$

Passing to the limit, we conclude that $\partial_t \varphi(\bar{z}) \leq 0$. \square

6.5. Perimeter descent. In this part we address the problem of the perimeter descent for variational curvature flows. The results refer to any viscosity solution $u : \mathbb{R}^N \times [0, T] \rightarrow \mathbb{R}$ to (2.4), where k is the first variation of a generalized perimeter in the sense of Definition 4.4. Throughout this subsection we also assume that the additional conditions stated in Subsection 3.1 and 3.2 hold, so that such a solution is unique and coincides with the one built through the minimizing movements.

First, we generalize to our setting a fact that is well known in the context of the mean curvature flow: whenever there is no fattening, the perimeter decreases in time.

Proposition 6.18. *Let $0 \leq t_1 \leq t_2 \leq T$, let $\lambda \in \mathbb{R}$ and assume that $|\{u(\cdot, t_2) = \lambda\}| = 0$. Then,*

$$J(\{u(\cdot, t_2) > \lambda\}) \leq J(\{u(\cdot, t_1) > \lambda\}).$$

Proof. Set $\tilde{u}^0 := d_{\{u(\cdot, t_1) > \lambda\}}$, and let $\tilde{u} : [0, T - t_1] \rightarrow \mathbb{R}$ be the viscosity solution of (2.4) with initial condition \tilde{u}^0 . By Remark 3.9, we get

$$\{\tilde{u}(\cdot, t) > \lambda\} = \{u(\cdot, t + t_1) > \lambda\}$$

for every $t \in [0, T - t_1]$. Let now \tilde{u}_h be the approximate solution defined in (6.13). Then, by Proposition 6.12 we have

$$J(\{\tilde{u}_h(\cdot, t_2 - t_1) > \lambda\}) \leq J(\{\tilde{u}_h(\cdot, 0) > \lambda\}).$$

Since $\tilde{u}_h \rightarrow \tilde{u}$ pointwise (indeed, uniformly) and since

$$|\{\tilde{u}(\cdot, t_2 - t_1) = \lambda\}| = |\{u(\cdot, t_2) = \lambda\}| = 0,$$

we easily deduce that

$$\{\tilde{u}_h(\cdot, t_2 - t_1) > \lambda\} \rightarrow \{\tilde{u}(\cdot, t_2 - t_1) > \lambda\} = \{u(\cdot, t_2) > \lambda\}$$

in measure, as $h \rightarrow \infty$. By the lower semicontinuity of J we conclude

$$(6.33) \quad J(\{u(\cdot, t_2) > \lambda\}) \leq \liminf_h J(\{\tilde{u}_h(\cdot, t_2 - t_1) > \lambda\}) \\ \leq J(\{\tilde{u}_h(\cdot, 0) > \lambda\}) = J(\{u(\cdot, t_1) > \lambda\}).$$

□

Remark 6.19. A natural issue is to understand under which circumstances the assumption of Proposition 6.18 is satisfied. To our knowledge, there is no general result in this direction, not even for the canonical mean curvature flow. On the other hand, if the initial set E^0 is starshaped, one can build u^0 such that all its superlevels are homothetic to E^0 . In view of the homogeneity properties of the mean curvature and of the geometric evolution equation (2.4), all the superlevels evolve staying homothetic to each other. As a consequence, superlevels are never flat, and in turn the perimeter decreases along the flow. This is the case whenever a generalized curvature is homogeneous with respect to dilations, i.e. there exists $\alpha > 0$ such that $\kappa(x, lE) = l^{-\alpha} \kappa(x, E)$ for every $l > 0$ and $E \in \mathfrak{C}$. For the mean curvature flow (and in fact for more general local evolutions), this was already observed and used in [4, 35, 36].

Finally, we introduce a relaxed perimeter, defined on open sets, that always decreases along the flow.

Definition 6.20. For every open set $A \subset \mathbb{R}^N$ with compact boundary set $\tilde{J}(A) := \inf \liminf J(A_n)$ where the infimum is taken among all sequences of open sets A_n with $\bar{A}_n \in \mathfrak{C}$, $\bar{A}_n \subset A$ and $\mathbb{R}^N \setminus A_n \rightarrow \mathbb{R}^N \setminus A$ in the Hausdorff sense.

Remark 6.21. By the lower semicontinuity property of J , we have $\tilde{J}(A) \geq J(A)$ for every open set A with compact boundary. The converse inequality is in general false. For instance let J be the standard perimeter and let $A := B_1 \setminus \{xy = 0\}$. Then, $J(A) = J(B_1)$, while it is easy to see that $\tilde{J}(A) = J(B) + 4$. It is well known (see [23]) that if $u^0 = d_A$, then the level-set $\{u(\cdot, t) = 0\}$ is fat for every positive time. Moreover,

$$\lim_{t \rightarrow 0} J(\{u(\cdot, t) > 0\}) = \tilde{J}(A).$$

In particular, the perimeter J (instantaneously) increases along the geometric flow. The example somewhat motivates Definition 6.20. As we will see, the relaxed perimeter \tilde{J} instead is always non increasing.

Remark 6.22. Clearly, in Definition 6.20 we can always assume that, whenever A is bounded, A_n are compactly contained in A_{n+1} for every n (and a similar condition for unbounded sets). Moreover, we can remove the regularity assumption on A_n without affecting the notion of \tilde{J} . Indeed, let \hat{J} be defined as in Definition 6.20, but without the requirement of the $C^{\ell,\beta}$ -regularity. Clearly $\hat{J} \leq \tilde{J}$. To prove the converse inequality, consider an optimal sequence of open sets \hat{A}_n such that $J(\hat{A}_n) \rightarrow \hat{J}(A)$. It is enough to regularize each A_n in order to have an optimal sequence \tilde{A}_n for \tilde{J} . This can be easily done in view of Lemma 4.1. The details are left to the reader.

We now state and prove a simple lemma that clarifies the role of Definition 6.20 in the viscosity approach to geometric flows.

Lemma 6.23. *Let $A \subset \mathbb{R}^N$ be an open set with compact boundary, and let $\bar{A}_n \in \mathfrak{C}$ with $\bar{A}_n \subseteq A_{n+1} \subseteq \bar{A}_{n+1} \subseteq A$ for every n , and $\cup_{n=1}^{\infty} \bar{A}_n = A$.*

Then, there exists a one-Lipschitz function u_A and a sequence $\lambda_n \rightarrow 0$ such that

- 1) $A = \{u_A > 0\}$;
- 2) $A_n = \{u_A > \lambda_n\}$;
- 3) $u_A = d_{A_n} + \lambda_n$ in a neighborhood of ∂A_n .

Proof. For every $n \in \mathbb{N}$ we set

$$\lambda_n := \sum_{i=n}^{+\infty} \text{dist}(\partial A_i, \partial A_{i+1}).$$

We now define the function u_A by setting for every $i \in \mathbb{N}$:

$$u_A|_{A_{i+1} \setminus A_i} = \begin{cases} d_{A_i} + \lambda_i & \text{in } \{0 \leq d_{A_i} \leq \text{dist}(\partial A_i, \partial A_{i+1})/2\}, \\ d_{A_{i+1}} + \lambda_{i+1} & \text{in } \{-\text{dist}(\partial A_i, \partial A_{i+1})/2 \leq d_{A_{i+1}} \leq 0\}, \\ \frac{\lambda_i + \lambda_{i+1}}{2} & \text{elsewhere in } A_{i+1} \setminus A_i. \end{cases}$$

It is now easy to check that the function u_A has all the required properties. \square

Proposition 6.24. *The relaxed perimeter \tilde{J} decreases along the geometric flow. More precisely, for every $\lambda \in \mathbb{R}$ the function $t \rightarrow \tilde{J}(\{u(\cdot, t) > \lambda\})$ is not increasing.*

Proof. To easy notations, we will assume $\lambda = 0$. Let $0 \leq t_1 \leq t_2 \leq T$. We have to prove that

$$\tilde{J}(\{u(\cdot, t_2) > 0\}) \leq \tilde{J}(\{u(\cdot, t_1) > 0\}).$$

Let (A_n) be an optimal sequence for Definition 6.20 with $A := \{u(\cdot, t_1) > 0\}$. Clearly, we may assume that $\bar{A}_n \subset A_{n+1}$ for every n . Moreover, let λ_n, u_A be as in Lemma 6.23. By property 3) of Lemma 6.23, we have that the function $\lambda \mapsto \{u_A > \lambda\}$ is continuous from a neighborhood of each λ_n to \mathfrak{C} . In particular, the function $\lambda \mapsto J(\{u_A(\cdot) > \lambda\})$ is continuous at each λ_n . Notice that all except countably many levels of u_A have null measure. Therefore, there exists a sequence $\tilde{\lambda}_n \rightarrow 0$ such that

- i) $|\{u_A(\cdot) = \tilde{\lambda}_n\}| = 0$ for every n ;
- ii) $J(\{u_A(\cdot) > \tilde{\lambda}_n\}) \rightarrow \tilde{J}(A)$ as $n \rightarrow \infty$.

Let $\tilde{u} : [0, T - t_1] \rightarrow \mathbb{R}$ be the solution to (2.4) with initial condition u_A . By Proposition 6.18 we have

$$J(\{\tilde{u}(\cdot, t_2 - t_1) > \tilde{\lambda}_n\}) \leq J(\{\tilde{u}(\cdot, 0) > \tilde{\lambda}_n\}).$$

Letting $n \rightarrow \infty$, by ii) and by the very definition of \tilde{J} we get

$$\tilde{J}(\{u(\cdot, t_2) > 0\}) = \tilde{J}(\{\tilde{u}(\cdot, t_2 - t_1) > 0\}) \leq \tilde{J}(\{\tilde{u}(\cdot, 0) > 0\}) = \tilde{J}(\{u(\cdot, t_1) > 0\}),$$

where the first equality follows by Remark 3.9.

□

REFERENCES

- [1] F. Almgren, J. E. Taylor, and L.-H. Wang. Curvature-driven flows: a variational approach. *SIAM J. Control Optim.*, 31(2):387–438, 1993.
- [2] M. Barchiesi, S. H. Kang, T. M. Le, M. Morini, and M. Ponsiglione. A variational model for infinite perimeter segmentations based on Lipschitz level set functions: denoising while keeping finely oscillatory boundaries. *Multiscale Model. Simul.*, 8(5):1715–1741, 2010.
- [3] G. Barles, P. Cardaliaguet, O. Ley, and R. Monneau. Global existence results and uniqueness for dislocation equations. *SIAM J. Math. Anal.*, 40(1):44–69, 2008.
- [4] G. Barles, H. M. Soner, and P. E. Souganidis. Front propagation and phase field theory. *SIAM J. Control Optim.*, 31(2):439–469, 1993.
- [5] Guy Barles, Pierre Cardaliaguet, Olivier Ley, and Aurélien Monteillet. Uniqueness results for nonlocal Hamilton-Jacobi equations. *J. Funct. Anal.*, 257(5):1261–1287, 2009.
- [6] Guy Barles and Cyril Imbert. Second-order elliptic integro-differential equations: viscosity solutions’ theory revisited. *Ann. Inst. H. Poincaré Anal. Non Linéaire*, 25(3):567–585, 2008.
- [7] Guy Barles and Panagiotis E. Souganidis. A new approach to front propagation problems: theory and applications. *Arch. Rational Mech. Anal.*, 141(3):237–296, 1998.
- [8] Kenneth A. Brakke. *The motion of a surface by its mean curvature*, volume 20 of *Mathematical Notes*. Princeton University Press, Princeton, N.J., 1978.
- [9] L. Caffarelli, J.-M. Roquejoffre, and O. Savin. Nonlocal minimal surfaces. *Comm. Pure Appl. Math.*, 63(9):1111–1144, 2010.
- [10] L. A. Caffarelli and P. E. Souganidis. Convergence of nonlocal threshold dynamics approximations to front propagation. *Arch. Ration. Mech. Anal.*, 195(1):1–23, 2010.
- [11] P. Cardaliaguet. On front propagation problems with nonlocal terms. *Adv. Differential Equations*, 5(1-3):213–268, 2000.
- [12] P. Cardaliaguet. Front propagation problems with nonlocal terms. II. *J. Math. Anal. Appl.*, 260(2):572–601, 2001.
- [13] P. Cardaliaguet and O. Ley. Some flows in shape optimization. *Arch. Ration. Mech. Anal.*, 183(1):21–58, 2007.
- [14] P. Cardaliaguet and O. Ley. On the energy of a flow arising in shape optimization. *Interfaces Free Bound.*, 10(2):223–243, 2008.
- [15] P. Cardaliaguet and E. Rouy. Viscosity solutions of increasing flows of sets. Application of the Hele-Shaw problem for power-law fluids. *SIAM J. Math. Anal.*, 38(1):143–165, 2006.
- [16] A. Chambolle and M. Novaga. Implicit time discretization of the mean curvature flow with a discontinuous forcing term. *Interfaces Free Bound.*, 10(3):283–300, 2008.
- [17] Antonin Chambolle. An algorithm for mean curvature motion. *Interfaces Free Bound.*, 6(2):195–218, 2004.
- [18] Antonin Chambolle, Alessandro Giacomini, and Luca Lussardi. Continuous limits of discrete perimeters. *M2AN Math. Model. Numer. Anal.*, 44(2):207–230, 2010.
- [19] Antonin Chambolle, Massimiliano Morini, and Marcello Ponsiglione. A nonlocal mean curvature flow and its semi-implicit time-discrete approximation. *SIAM J. Math. Anal.*, 44(6):4048–4077, 2012.
- [20] Yun Gang Chen, Yoshikazu Giga, and Shun’ichi Goto. Uniqueness and existence of viscosity solutions of generalized mean curvature flow equations. *J. Differential Geom.*, 33(3):749–786, 1991.
- [21] M. G. Crandall, H. Ishii, and P.-L. Lions. User’s guide to viscosity solutions of second order partial differential equations. *Bull. Amer. Math. Soc. (N.S.)*, 27(1):1–67, 1992.
- [22] Tokuhiko Eto, Yoshikazu Giga, and Katsuyuki Ishii. An area-minimizing scheme for anisotropic mean-curvature flow. *Adv. Differential Equations*, 17(11-12):1031–1084, 2012.
- [23] L. C. Evans and J. Spruck. Motion of level sets by mean curvature. I. *J. Differential Geom.*, 33(3):635–681, 1991.
- [24] Lawrence C. Evans and Ronald F. Gariepy. *Measure theory and fine properties of functions*. Studies in Advanced Mathematics. CRC Press, Boca Raton, FL, 1992.
- [25] Yoshikazu Giga. *Surface evolution equations*, volume 99 of *Monographs in Mathematics*. Birkhäuser Verlag, Basel, 2006. A level set approach.
- [26] Tom Ilmanen. The level-set flow on a manifold. In *Differential geometry: partial differential equations on manifolds (Los Angeles, CA, 1990)*, volume 54 of *Proc. Sympos. Pure Math.*, pages 193–204. Amer. Math. Soc., Providence, RI, 1993.
- [27] C. Imbert. Level set approach for fractional mean curvature flows. *Interfaces Free Bound.*, 11(1):153–176, 2009.
- [28] H. Ishii and P. Souganidis. Generalized motion of noncompact hypersurfaces with velocity having arbitrary growth on the curvature tensor. *Tohoku Math. J. (2)*, 47(2):227–250, 1995.

- [29] Gary M. Lieberman. Boundary regularity for solutions of degenerate elliptic equations. *Nonlinear Anal.*, 12(11):1203–1219, 1988.
- [30] S. Luckhaus and T. Sturzenhecker. Implicit time discretization for the mean curvature flow equation. *Calc. Var. Partial Differential Equations*, 3(2):253–271, 1995.
- [31] F. Murat and J. Simon. Sur le contrôle par un domaine géométrique. Technical Report 76-015, Laboratoire d'Analyse Numérique, Univ. Paris 6, 1976. (*now Lab. Jacques-Louis Lions, Université Pierre et Marie Curie, Paris*).
- [32] Stanley Osher and James A. Sethian. Fronts propagating with curvature-dependent speed: algorithms based on Hamilton-Jacobi formulations. *J. Comput. Phys.*, 79(1):12–49, 1988.
- [33] D. Slepčev. Approximation schemes for propagation of fronts with nonlocal velocities and Neumann boundary conditions. *Nonlinear Anal.*, 52(1):79–115, 2003.
- [34] Jan Sokółowski and Jean-Paul Zolésio. *Introduction to shape optimization*, volume 16 of *Springer Series in Computational Mathematics*. Springer-Verlag, Berlin, 1992. Shape sensitivity analysis.
- [35] H. M. Soner and P. E. Souganidis. Singularities and uniqueness of cylindrically symmetric surfaces moving by mean curvature. *Comm. Partial Differential Equations*, 18(5-6):859–894, 1993.
- [36] Halil Mete Soner. Motion of a set by the curvature of its boundary. *J. Differential Equations*, 101(2):313–372, 1993.
- [37] Enrico Valdinoci. A fractional framework for perimeters and phase transitions. *Milan J. Math.*, 81(1):1–23, 2013.

(Antonin Chambolle) CMAP, ECOLE POLYTECHNIQUE, CNRS, FRANCE
E-mail address, A. Chambolle: antonin.chambolle@cmap.polytechnique.fr

(Massimiliano Morini) DIP. DI MATEMATICA, UNIV. PARMA, ITALY
E-mail address, M. Morini: massimiliano.morini@unipr.it

(Marcello Ponsiglione) DIP. DI MATEMATICA, UNIV. ROMA-I “LA SAPIENZA”, ROMA, ITALY
E-mail address, M. Ponsiglione: ponsigli@mat.uniroma1.it