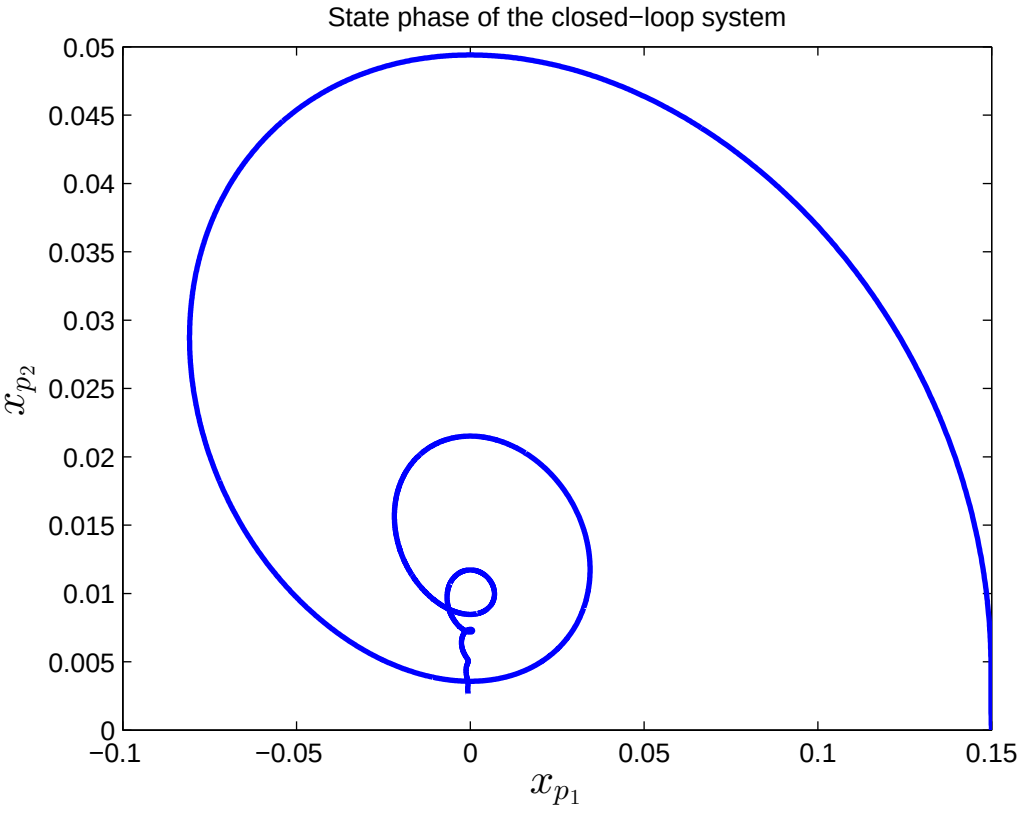
State phase of the closed−loop system
0.05
0.045
0.04
0.035
0.03
0.025
0.02
0.015
0.01
0.005
0
−0.1
−0.05
0
0.05
0.1
0.15
$x_{p_2}$
$x_{p_1}$