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Scaling theory of the Anderson transition in random graphs: ergodicity and universality

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We study the Anderson transition on a generic model of random graphs with a tunable branching parameter $1 < K \le 2$, through a combination of large scale numerical simulations and finite-size scaling analysis. We find that a single Anderson transition separates a localized phase from an unusual delocalized phase which is ergodic at large scales but strongly non-ergodic at smaller scales. The critical regime is characterized by multifractal wavefunctions located on few branches of the graph. Two different scaling laws apply on both sides of the transition: a linear scaling as a function of the linear size of the system on the localized side, and an unusual volumic scaling on the delocalized side. The critical scalings and exponents are found to be independent of the branching parameter and should describe all infinite dimensional random graphs without boundary.

Ergodicity properties of quantum states are crucial to assess transport properties and thermalization processes in condensed matter systems. It is at the heart of the eigenstate thermalization hypothesis which has attracted enormous attention lately [1]. A paramount example of non-ergodicity is Anderson localization where the interplay between disorder and quantum interference leads to exponentially localized states [2]. In 3D, a critical value of disorder separates a localized from an ergodic delocalized phase. At the critical point eigenfunctions are multifractal, another non trivial example of non-ergodicity [3, 4]. Recently, those questions have been particularly highlighted in the problem of many-body localization [5– 9]. Because Fock space has locally a tree-like structure, the problem of Anderson localization on different types of graphs [10–15] has attracted a renewed activity [16– 25]. In particular, the existence of a delocalized phase with non-ergodic (multifractal) eigenfunctions in a broad range of disorder is debated [19–21, 23, 25].

The problem of non-ergodicity also arises in another context corresponding to glassy physics [26]. For directed polymers on the Bethe lattice [27], a glass transition occurs at low temperature, leading to a phase where the directed polymer explores few branches of the tree instead of the exponential number of branches at its disposal, a strongly non-ergodic behavior. As there is a mapping to directed polymer models in the Anderson-localized phase [10, 28–30], it has been recently proposed that this type of non-ergodicity is also relevant in the delocalized phase [18].

In this letter, we study the Anderson transition in a family of random graphs [31–33], where a tunable parameter p allows us to interpolate continuously between the 1D Anderson model and the random regular graph

model of infinite dimensionality. Our main tool is the single parameter scaling theory of localization [34]. It has been used as a crucial tool to interpret the numerical simulations of Anderson localization in finite dimensions [3, 35, 36] and to achieve the first experimental measurement of the critical exponent of the Anderson transition in 3D [37]. In our case, the infinite dimension of the graphs leads to highly non-trivial finite-size scaling properties: unusually, we find different scaling laws on each side of the transition. Our detailed analysis of extensive numerical simulations leads to the following scenario. A single Anderson transition is present which separates a localized phase from an ergodic delocalized phase. However a characteristic non-ergodicity volume Λ emerges in the latter phase. For scales below Λ , states are non-ergodic in the sense that they take significant values only on few branches, and display a multifractal behavior. For scales above Λ , this structure repeats itself and leads to large scale ergodicity. At the threshold, Λ diverges, and the behavior below Λ extends to the whole system. The critical behaviors do not depend on the graph parameter p, which strongly supports the universality of this scenario.

In order to describe the localization properties, we use two complementary approaches. First we derive recursive equations for the local Green function using a mapping to a tree [10], which we solve using the pool method from glassy physics [16, 28], and analyse the critical behavior by finite-size scaling. Second, we perform exact diagonalization of very large system sizes up to $N \approx 2.10^6$, and we extract the scaling properties of eigenfunction moments. We use the box-counting method in this new context of graphs of infinite dimensionality to perform a local analysis and to extract the non-ergodicity volume Λ unambiguously.

Random graph model.— We consider a 1D lattice of Nsites with periodic boundary conditions. Each site is connected to its nearest neighbors and |pN| shortcut links are added (|.| is the integer part). These shortcuts give an average distance between pairs of sites that increase logarithmically with N, so that the graph has an infinite dimensionality (see Supplemental Material and [38]). The system is described by an N-dimensional Hamiltonian $\overset{\circ}{H}=\sum_{i=1}^N\varepsilon_i|i\rangle\!\langle i|+\overset{\circ}{\sum}_{\langle i,j\rangle}|i\rangle\!\langle j|+\sum_{k=1}^{\lfloor pN\rfloor}(|i_k\rangle\!\langle j_k|+$ $|j_k\rangle\langle i_k|$ in the position basis $\{|i\rangle, 1\leq i\leq N\}$. The first term describes on-site disorder, with ε_i i.i.d. Gaussian random variables with zero mean and standard deviation W. The second term runs over nearest neighbors. The third term gives the long-range links that connect pairs (i_k, j_k) , randomly chosen such that $|i_k - j_k| > 1$. The case p = 0 is the usual 1D Anderson model. At finite p, our system is a random graph with mean connectivity K = 1 + 2p, allowing us to access a regime where $1 < K \le 2$.

Glassy physics approach.— We first use a recursive technique used to investigate localization on the Bethe lattice [10, 16, 27, 28, 39]. It is exact for a Cayley tree (which has no loop), but only an approximation in the case of a generic graph. For a regular tree graph with K+1 neighbors, the diagonal elements G_{ii} of the Green operator follow $G_{ii} = (\epsilon_i - E - \sum_{j=1}^K G_{jj})^{-1}$, where the sum runs over the K children j of node i [10]. The local tree-like structure of our random graph model is such that each parent node has either one or two children. This leads to three recursion equations which determine the probability distribution of G (see Supp. Mat.).

In order to probe the localization properties on the disordered graph, we use the belief propagation method (or pool method), which consists of sampling the distribution of G with a Monte-Carlo approach [16, 28]. For a fixed value of E, we start from an initial pool of M_{pool} complex values for the local variables G_{ii} , $1 \le i \le M_{\text{pool}}$ and calculate the next generation by applying the recursion relations. The important quantity is the typical value of the imaginary part Im G which goes to zero in the localized phase as $\langle \ln \text{Im} G \rangle \sim -M_g/\xi_l$ when the number of generations M_q tends to infinity, (here $\langle X \rangle$ denotes ensemble averaging) whereas in the delocalized phase $\langle \ln \operatorname{Im} G \rangle$ converges to a finite value. We observed that the localization length ξ_l diverges at the transition as $\xi_l \sim [W - W_c(M_{\text{pool}})]^{-\nu_l}$ with the critical exponent $\nu_l \approx 1$ and a critical disorder $W_c(M_{\rm pool})$ which depends on M_{pool} (see also [16, 28]). We determined $W_c(M_{\text{pool}})$ for values of $M_{\rm pool}$ up to 10^6 . The results, presented in the inset of Fig. 1, show that $W_c(M_{\text{pool}})$ converges to $W_c^{\infty} \approx 1.77 \text{ for } p = 0.06 \text{ as } M_{\text{pool}} \to \infty.$

Following [16, 40], we assume that $\langle \ln \text{Im} G \rangle$ follows a single parameter scaling law:

$$\langle \ln \operatorname{Im} G \rangle = -(M_a)^{\rho} \mathcal{F}_G(M_a/\xi) ,$$
 (1)

with the scaling parameter $\xi \sim |W - W_c(M_{\text{pool}})|^{-\nu}$ [41].

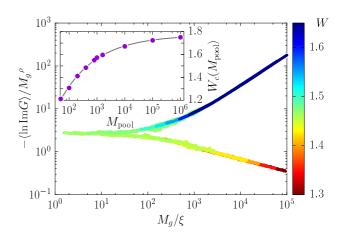


FIG. 1. Single parameter scaling of $\langle \ln {\rm Im} G \rangle$ versus number of generations M_g , for $M_{\rm pool} = 400$, M_g from $2M_{\rm pool}$ to 10^5 , p = 0.06 and $W \in [1.3, 1.65]$ (see color code). $\langle \ln {\rm Im} G \rangle \sim -M_g{}^\rho$ with $\rho \approx 0.28$ at $W = 1.46 \approx W_c(M_{\rm pool})$. Finite-size scaling of $-\langle \ln {\rm Im} G \rangle / M_g{}^\rho$ following Eq. (1). The scaling parameter ξ diverges at the threshold as $\xi \sim |W - W_c(M_{\rm pool})|^{-\nu}$, with $\nu \approx 1.4$ and $W_c(M_{\rm pool}) \approx 1.46$. Inset: Value of the critical disorder $W_c(M_{\rm pool})$ as a function of $M_{\rm pool}$. The line is a fit by $W_c(M_{\rm pool}) = W_c^\infty + A_0 \, M_{\rm pool}^{-\beta}$ with A_0 a constant, $W_c^\infty = 1.77$ and $\beta = 0.33$.

In order to sample correctly the distribution of ImG, values of M_{pool} as large as possible are usually considered, which entails typically $M_g \leq M_{\text{pool}}$ (see above). However our numerical results show that the scaling behavior (1) is valid but visible only for $M_g \gg M_{\text{pool}}$. Moreover, for a given initial pool, the fluctuations of $\langle \ln \operatorname{Im} G \rangle$ when M_q is varied can be extremely large (especially at criticality). In order to analyze the scaling behavior (1) we therefore considered values of M_{pool} from 50 to 800, M_g from $2M_{\rm pool}$ to 10^5 , and averaged additionally over 100 different realizations of the pool. The one-parameter scaling hypothesis (1) is confirmed by the data collapse shown in Fig. 1, which allows us to extract the scaling exponents $\nu \approx 1.4 \pm 0.2$ and $\rho \approx 0.28 \pm 0.07$, that do not depend on $M_{\rm pool}$. Therefore, in the delocalized phase, the typical value of ImG vanishes at the transition with an essential singularity $\lim_{M_a \to \infty} \langle \ln \operatorname{Im} G \rangle \sim -(W_c(M_{\text{pool}}) - W)^{\kappa}$ with $\kappa = \rho \nu \approx 0.39 \pm 0.16$ the critical exponent in the delocalized phase, compatible with the value 1/2 predicted analytically [14, 15]. Moreover, from $\nu_l = \nu(1-\rho)$ we recover the value $\nu_l \approx 1.0 \pm 0.2$ (see also [16]).

Scaling analysis of eigenfunction moments.— We now describe the results of our second approach. We performed exact diagonalizations of a large number of realizations of graphs with up to $N \sim 2 \times 10^6$ sites and obtained for each realization 16 eigenfunctions closest to the center of the band using the Jacobi-Davidson iterative method [42]. We performed a multifractal analysis of the eigenfunctions $|\psi\rangle$ by considering the scaling of average moments $\langle P_q \rangle = \langle \sum_{i=1}^N |\psi_i|^{2q} \rangle$ for real q as a function of N. For a d-dimensional system of linear size

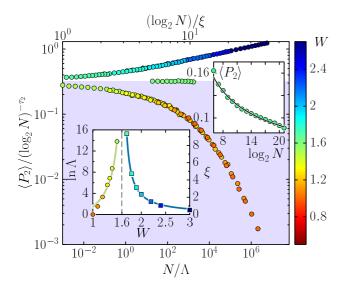


FIG. 2. Scaling of the moment $\langle P_2 \rangle$ with N for p=0.06 and $W \in [0.8,3]$. For $W > W_c$ (localized phase), linear scaling of $\langle P_2 \rangle / (\log_2 N)^{-\tau_2}$ following Eq. (2) with $\tau_2 = 0.42$. For $W < W_c$ (delocalized phase), volumic scaling following Eq. (3). Upper inset: The critical behavior of $\langle P_2 \rangle$ at $W=1.6 \approx W_c$ is very well fitted (black line) by $\langle P_2 \rangle = A_0(\log_2 N)^{-\tau_2}$ with A_0 a constant and $\tau_2 \approx 0.42$. Lower inset: correlation volume Λ (circles) and localization length ξ (squares) on both sides of the transition. Solid lines are the fits: $\ln \Lambda = A_1 + A_2(W_c - W)^{-\kappa}$ and $\xi = A_3(W - W_c)^{-\nu_l}$, with $W_c = 1.6$ (assigned value), yielding $\kappa \approx 0.46$ and $\nu_l \approx 1$.

L and volume $N = L^d$, multifractal eigenfunctions have $\langle P_q \rangle \sim L^{-\tau_q}$ at large L, or equivalently $\langle P_q \rangle \sim N^{-\chi_q}$ with $\chi_q = \tau_q/d$, defining non-trivial multifractal dimensions $D_q = \tau_q/(q-1)$. In the localized case $D_q = 0$ whereas for wavefunctions delocalized over the whole space $D_q = d$. Our graphs however correspond to a case of infinite dimensionality [43], where the system volume $N = V_q(d_N)$ is exponential in the linear size $d_N \sim \log_2 N$, the diameter of the system (see Supp. Mat.). Figure 2 shows that the critical behavior $\langle P_2 \rangle \sim (\log_2 N)^{-\tau_2} \sim d_N^{-\tau_2}$ indeed holds with $\tau_2 \approx 0.42$ for p = 0.06 and $W = 1.6 \approx W_c$ (upper right inset). One recovers the analytical predictions [4, 13, 15] that $\chi_q = 0$ at infinite dimensionality. Moreover, in the light of the analogy with directed polymers, eigenfunctions are localized on few branches in the localized phase. At criticality the localization length diverges to the system size d_N and one should observe multifractality at the level of few branches of the graph.

The following one-parameter scaling hypothesis should naturally follow:

$$\langle P_q \rangle = d_N^{-\tau_q} \mathcal{F}_{\text{lin}}(d_N/\xi) .$$
 (2)

It is consistent with the scaling theory for both the Anderson transition in finite dimension [44] and the glassy physics approach detailed above. A careful finite-size scaling analysis of our data shows that (2) yields a very

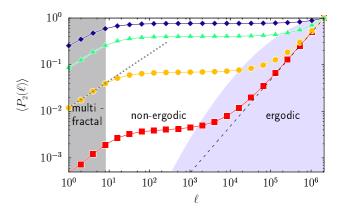


FIG. 3. $\langle P_2 \rangle$ versus the box volume ℓ for $N=2^{21}$ with p=0.06 and W=1.0 (\square), 1.3 (\circ), 1.6 (\triangle), 2.4 (\diamond). The gray shaded area on the left delimits the small $\ell < 1/2p$ multifractal behavior (the dotted line has slope 0.53). The lightblue shaded area on the right delimits the large scale $\ell \gg \lambda$ ergodic behavior (the dashed line has slope 1).

good data collapse on the localized side of the transition, see Fig. 2, upper branch in the main panel. The scaling parameter $\xi \sim \xi_l$ the localization length diverges as $\xi \propto (W - W_c)^{-\nu_l}$ near the transition, with $\nu_l \approx 1. \pm 0.1$ (in agreement with the value found by our first glassy physics approach).

However, in the delocalized phase, small but systematic deviations are observed (see Supp. Mat.). This leads us to propose a different scaling in this phase. Indeed, the linear scaling (2) of the moments with d_N rescaled by the length ξ is not the only possibility: the system volume N could instead be rescaled by a characteristic volume Λ (correlation volume):

$$\langle P_q \rangle = d_N^{-\tau_q} \mathcal{F}_{\text{vol}}(N/\Lambda).$$
 (3)

Both scaling hypotheses (2) and (3) are strictly equivalent in finite dimension, but lead to very different behaviors for a graph of infinite dimensionality. In the first linear scaling picture (2), the delocalized states consist of the repetition of linear critical structures of size ξ and the moments behave as $\langle P_q \rangle \approx \xi^{-\tau_q} N^{-(q-1)/\xi}$. It is reminiscent of the non-ergodic behavior discussed in [19–21, 23]. In the second volumic scaling picture (3), a delocalized state consists of N/Λ volumic critical structures of size Λ , and moments behave as $\langle P_q \rangle \approx \left(\frac{\Lambda}{N}\right)^{q-1} \left(1 - \tau_q \frac{\xi}{dN}\right)$ (see Supp. Mat.). This is consistent with previous analytical results [14, 15]. The finite size scaling shown in Fig. 2 clearly indicates that the volumic scaling (3) puts all the curves onto a single scaling function in the delocalized phase $W < W_c$, with correlation volume diverging exponentially at the transition as $\ln \Lambda \approx (W_c - W)^{-\kappa}$, $\kappa \approx 0.46 \pm 0.1$ (similar to the value obtained with our glassy physics approach and to the analytical prediction $\kappa = 1/2 [14, 15]$).

Non-ergodicity volume.— In order to probe the local

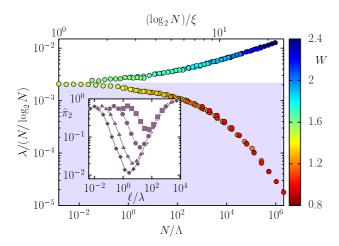


FIG. 4. Scaling behavior of the non-ergodicity volume λ with $N=2^{10}$ to $2^{21},\ p=0.06$ and $W\in[0.8,2.4]$. At the threshold $W=W_c\approx 1.6,\ \lambda\sim N/\log_2N$. In the localized phase, the data collapse is excellent when plotted as a function of $(\log_2N)/\xi$ (linear scaling, see text). In the delocalized regime, a volumic scaling as function of N/Λ makes the curves collapse. Inset: Determination of the non-ergodicity volume λ through the rescaling of $\tilde{\pi}_2(\ell)$ data (see text) as a function of ℓ/λ in the large scale $\ell\gg\lambda$ ergodic regime, for W=1.6 and $N=2^{10}$ (\square), 2^{14} (\bigcirc), 2^{18} (\triangle) and 2^{21} (\bigcirc).

properties of localization in our system, we use the boxcounting method, which consists of investigating the scaling properties of moments of coarse-grained wavefunctions. Dividing the system of N sites into boxes of ℓ consecutive sites along the lattice (i.e. not following the longrange links) and defining a measure $\mu_k = \sum_{i \in \text{box } k} |\psi_i|^2$ of each box, moments are defined as $P_q(\ell) = \sum_k \mu_k^q$. For a multifractal state, they are expected to scale as $\langle P_q(\ell) \rangle \sim \ell^{\pi_q}$ at large N with nontrivial π_q [45]. In the localized case $\pi_q = 0$ whereas for a wavefunction delocalized over the whole system $\pi_q = q - 1$. Figure 3 displays the moments $\langle P_2(\ell) \rangle$ as a function of ℓ for different W, and shows that three distinct regimes can be identified. At scales below the mean distance 1/(2p) between two long-range links, all moments have a power-law behavior with $\pi_2 \approx 0.53$, independently of W. The value of π_2 is close to $\tau_2 \approx 0.42$ found above and measures the critical multifractality on few branches. At intermediate scales, the moments follow a plateau characteristic of a strongly non-ergodic behavior. Beyond a certain characteristic scale λ which depends on W and N, the moments are linear in ℓ , which corresponds to an ergodic behavior. In the localized case $\lambda \sim N$, so that there is no ergodic behavior, while in the delocalized case, λ saturates to a finite value (see below), and states are ergodic at scales above λ , non-ergodic below: we therefore call λ the nonergodicity volume. One can extract λ from a rescaling of the local slopes $\tilde{\pi}_q(\ell) \equiv \frac{d \ln \langle P_q(\ell) \rangle}{d \ln \ell}$ [45] in the ergodic regime $\ell \gg \lambda$ (see inset of Fig. 4).

The data shown in Fig. 4 can be described by a linear

scaling $\frac{\lambda}{N/\log_2 N} = \mathcal{G}_{\mathrm{lin}}\left(\frac{\log_2 N}{\xi}\right)$ in the localized regime, with $\xi \sim \xi_l$ the localization length, and by a volumic scaling $\frac{\lambda}{N/\log_2 N} = \mathcal{G}_{\mathrm{vol}}\left(\frac{N}{\Lambda}\right)$ in the delocalized regime. At the threshold, the critical behavior $\lambda \sim N/\log_2 N$ shows that wavefunctions are located on single branches of $\log_2 N$ sites. This confirms the description of the critical behavior as multifractal on few branches, an extension of the glassy non-ergodic character of the localized phase when ξ diverges. Moreover, the volumic scaling shows that in the limit $N \gg \Lambda$ the non-ergodicity volume λ saturates to the correlation volume Λ (see Supp. Mat.), which therefore can be interpreted as the non-ergodicity volume in the thermodynamic limit. This implies that the delocalized phase is ergodic in the limit of large $N \gg \Lambda$.

For other values of q, we have checked that the scaling properties are the same for $q \geq 1$ whereas for q < 1 the volumic behavior of the delocalized phase extends to the critical and localized regimes. This is to be expected [15, 17, 46, 47]: for q < 1 all small values of the wavefunction, even outside the few localization branches, contribute to the moment.

Universality.— We checked the universality of our results by considering different values of the graph parameter from p=0.01 to p=0.49 (see Supp. Mat.), which changes the average branching parameter K=1+2p considerably. Our data show that the critical scalings are insensitive to the value of p. Moreover, the critical exponents have universal values $\kappa \approx 0.5$ and $\nu_l \approx 1$.

Conclusion. — Our study strongly supports the following picture for the Anderson transition on infinite dimensional random graphs of any branching K without boundary: A single transition separates a localized phase from an ergodic delocalized phase. In the delocalized phase, the non-ergodicity volume Λ marks the threshold between a non-ergodic behavior reminiscent of glassy physics at small scales and an ergodic behavior at large scales. At the transition, Λ diverges, so that the behavior below Λ extends to the whole system. This highlights a new type of strong non-ergodicity with multifractality restricted to few branches. To detect such features has required the use of state of the art exact diagonalizations of very large size systems, along with a highly non-trivial finite-size scaling analysis. In particular, the ergodic character of the delocalized phase is controlled by the unusual volumic scaling in this phase, different from the linear scaling which applies in the localized phase and to the whole transition in the Cayley tree as found in our glassy physics approach, where boundary effects are important and the delocalized phase is believed to be non-ergodic [17, 21, 23, 25]. It will be very interesting to study the consequences of the unusual features we found on the dynamics of such systems and to see whether the non-trivial scaling laws we observed apply to other models, for example in many-body localization where non-ergodicity is a crucial issue.

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Supplemental material to "Scaling theory of the Anderson transition in random graphs: ergodicity and universality"

Topological properties of the random graph model

In this Section we want to assess the topological properties of the random graphs considered in our model more in details. In particular random graphs often refer to Erdös-Renyi random graphs, i.e. graphs having N vertices and (p+1)N links which are chosen with a uniform probability over the set of all such graphs. In this Section it will be explained that, while the set of random graphs considered here is a subset of the set of Erdös-Renyi random graphs, they share several generic features of those graphs. This strengthens the idea that our model for graphs posesses generic properties. We also want to stress that our random graph model coincides with the model of Random Regular Graphs (RRG) at the limit p=0.5.

The first reason why the considered random graphs are generic, is that they have infinite dimension. The dimension refers here to the Hausdorff dimension of a graph. First one defines a distance between two vertices i and j as the number of vertices of a shortest path connecting i and j. Then one can compute the mean pair distance \bar{l} as the average distance between any pair of vertices of the graph. Another quantity of interest for our study is the diameter, or the linear size, of our graph. It is denoted by d_N and is defined as the largest distance between any pair of vertices of the graph. The Hausdorff dimension of the graph is evaluated by taking a sequence of graphs with increasing number of vertices N. The variation of \bar{l} as a function of N leads to the definition of the Hausdorff dimension d_H , see e.g. [S2]:

$$\bar{l} \sim N^{1/d_{\rm H}}, \ N \to \infty \ .$$
 (S1)

Erdös-Renyi random graphs have infinite dimension as the mean pair distance grows like $\bar{l} \sim \ln N$ for large N. We checked that this is also the case for our model of random graphs whenever p is positive. More precisely for p=0.49 we found numerically an asymptotic form $\bar{l} \approx 1.44 \ln N$, which agrees with the prediction $\bar{l} \sim \ln N$ for 3-regular graphs in RRG. Such a scaling for the mean pair distance also means that the diameter grows logarithmically as a function of N for large graphs. This is illustrated for three different values of p in Fig. S1. In particular for p=0.49 the best fit is close to the prediction $d_N \sim \ln N$ for 3-regular graphs in RRG (see [S1]).

The second common feature between our graphs and Erdös-Renyi random graphs is the clustering coefficient. It is defined as the probability that two given neighbors of a fixed vertex are themselves connected by a link. An important

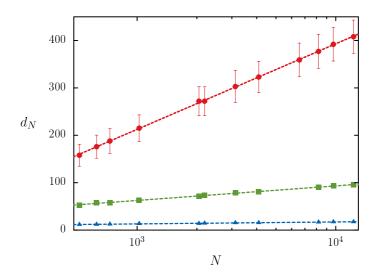


FIG. S1. (Color online) Diameter d_N of our random graph model as a function of the total number N of vertices. For each value of N, 10000 random graphs were sampled. The values reported here are the center of a Gaussian fit of the distribution of their diameter. Red circles: numerical data for p=0.01. Red dashed line: Logarithmic fit, $d_N \sim 78 \ln(0.015N)$. Green squares: numerical data for p=0.06. Green dashed line: Logarithmic fit, $d_N \sim 13 \ln(0.10N)$. Blue triangles: numerical data for p=0.49. Blue dashed line: Logarithmic fit, $d_N \sim 1.8 \ln(1.5N)$.

property of Erdös-Renyi random graphs is that, when the vertex number N increases, the clustering coefficient grows like N^{-1} [S2]. For our model of random graphs, it was found numerically that the clustering coefficient obeys the following law, for any p:

$$C(N,p) \simeq \frac{3}{N}p(1-p) , \qquad (S2)$$

which agrees with the scaling for Erdös-Renyi random graphs.

Another common point with Erdös-Renyi random graphs is that the graphs considered in our study locally look like a tree. More precisely the number of small loops is independent of the number of vertices [S2].

Furthermore, as we have checked that \bar{l} quickly decreases as a function of p, our model of random graphs shares also the main features of smallworld networks [S3].

Recursion equations

For a regular tree graph with K+1 neighbors, the recursion equation is obtained by considering the Green operator $G(E) = (M-E\mathbb{I})^{-1}$ of the adjacency matrix M of the network with some vertex m removed. If i is a child node of m, the diagonal entry $G_{ii}(E)$ of the Green function can be expanded (see e.g. [S4]) as $G_{ii} = (M_{ii} - E - \sum_{j=1}^{K} G_{jj})^{-1}$, where the sum runs over the neighbors j of node i other than m. As the tree is self-similar, the G_{jj} and G_{ii} all have the same probability distribution P(G). Moreover, the G_{jj} are independent and also are independent of the random variables $M_{ii} = \epsilon_i$, so that at a fixed value of the energy E the above relation determines a functional equation for the probability P(G).

In order to obtain a similar recursion relation for our random graph model, we consider the local tree-like structure of the graph. The tree is such that each parent node has either one or two children, with probability respectively 1-2p and 2p. Following the cavity method [S5], we consider a graph where some parent node (say m) has been removed. Each child node i is the root of a tree which can be of three different types: either i has one remaining neighbor (case A), or two neighbors connected by two nearest-neighbor links (case B), or two neighbors connected by one nearest-neighbor and one long-range link (case C). We thus have to distinguish between three types A_i , B_i and C_i , of local random variables $\tilde{G}_{ii}(E)$, corresponding to the three possible local patterns. We introduce a fourth type G of random variable G_i , equal to A_i with probability 1-2p and to B_i with probability 2p. Local pattern of type A are those where node i has a single child j, which can itself be of type A or B (note that type C is excluded since the link between i and j is of nearest-neighbor type). That is, the child is of type G. In case B, node i has a neighbor of type C and a neighbor of type G. In case C, the two children are of type G. The analog of the recursion equation on the regular tree now takes the form of three recursion relations

$$A_i = \frac{1}{\epsilon_i - E - G_j},\tag{S3}$$

$$B_i = \frac{1}{\epsilon_i - E - G_{j_1} - C_{j_2}},\tag{S4}$$

$$C_i = \frac{1}{\epsilon_i - E - G_{j_1} - G_{j_2}},\tag{S5}$$

together with the condition

$$G_i = \begin{vmatrix} A_i & \text{with probability } 1 - 2p \\ B_i & \text{with probability } 2p \end{vmatrix} . \tag{S6}$$

The probability distributions for each type of random variable follow a set of functional equations that can be directly inferred from Eqs. (S3)–(S6).

Scaling analysis

Deviations to the linear scaling hypothesis in the delocalized regime

Here we show the results of finite-size scaling of the moment $\langle P_2 \rangle$ for p = 0.06 following the linear scaling hypothesis (2) in the delocalized regime $W < W_c \approx 1.6$. In Fig. S2, the best rescaling of the data when the linear size of the

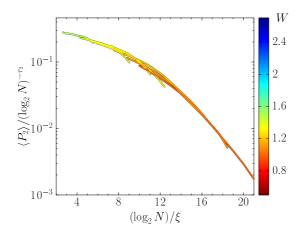


FIG. S2. Deviations to the linear scaling hypothesis (2) for the moment $\langle P_2 \rangle$ in the delocalized regime $W < W_c \approx 1.6$ for p = 0.06. The best rescaling of the data as a function of $(\log_2 N)/\xi$ shows small but systematic deviations. The data are represented by lines of different colors according to W.

graph $d_N \sim \log_2 N$ is rescaled by the scaling parameter ξ is shown. Small but systematic deviations are observed (data have been represented with lines to better see these deviations). Clearly, the lines corresponding to different values of the disorder strength do not have the right curvature to be put on each other via such a rescaling. On the contrary, we recall that the linear scaling hypothesis (2) is fully consistent with our data in the localized regime $W > W_c$ (see Fig. 2).

Asymptotic behaviors in the delocalized phase

The linear scaling hypothesis (2) predicts a non-ergodic delocalized phase in the sense of [S6, S7] which has its origin in the glassy non-ergodicity of the localized phase. Following the scaling law hypothesis (2), a delocalized state is built from critical structures of size ξ . As a critical structure consists of few branches, a delocalized state is to follow these branches for ξ steps, then to make connections to K branches, then follow the K branches for ξ steps that perform each K connections, etc. One thus sees that the number of critical structures constituting a delocalized state is $V_g(d_N/\xi)$ where $V_g(X)$ is the volume of a graph of size X. Therefore, the asymptotic behavior of P_q in the delocalized regime should be: $\langle P_q \rangle \sim \xi^{-\tau_q}/V_g(d_N/\xi)^{q-1}$ where the number $V_g(d_N/\xi)$ appears on the denominator due to normalization. Because the volume $V_g(X)$ of graphs of infinite dimensionality scales exponentially with the linear size X, and using $V_g(d_N) = N$,

$$\langle P_q \rangle \approx \xi^{-\tau_q} N^{-(q-1)/\xi}$$
 (S7)

in the delocalized phase, $d_N \gg \xi$. This behavior corresponds to the following asymptotic dependence of the scaling function \mathcal{F}_{lin} (see (2)):

$$\mathcal{F}_{\text{lin}}(X) \sim \frac{X^{\tau_q}}{[V_q(X)]^{q-1}}, \text{ for } X \to \infty, W < W_c.$$
 (S8)

In the volumic scaling hypothesis (3), the scaling parameter $\Lambda(W)$ plays the role of the correlation volume, and the scaling function is expressed as the ratio of the two characteristic volumes instead of the ratio of the characteristic linear sizes. In this case, a critical structure is an hypercube, and the number of such structures in a delocalized state is N/Λ . Therefore, the leading asymptotic behavior of P_q when $N \gg \Lambda$ is

$$\langle P_q \rangle \approx \left(\frac{\Lambda}{N}\right)^{q-1}$$
 (S9)

In order to compensate the term $d_N^{-\tau_q}$ in (3), the scaling function \mathcal{F}_{vol} should have the following asymptotic behavior:

$$\mathcal{F}_{\text{vol}}(X) \sim \frac{\left[V_g^{-1}(X)\right]^{\tau_q}}{X^{q-1}}, \text{ for } X \to \infty, W < W_c.$$
 (S10)

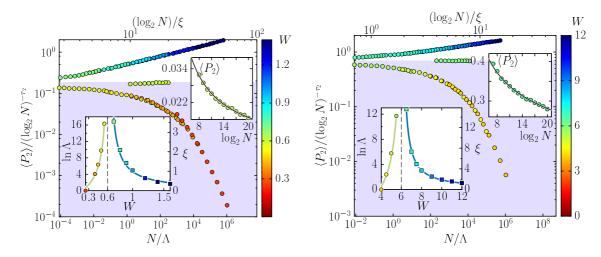


FIG. S3. Scaling of the moment $\langle P_2 \rangle$ for the graph model with N for two values of p. (Left panel) $p=0.01, W \in [0.25, 1.6]$. At $W=0.6\approx W_c$, the behavior of $\langle P_2 \rangle$ is well fitted by $\langle P_2 \rangle = A_0(\log_2 N)^{-\tau_2}$ with A_0 a constant and $\tau_2=0.69$ (upper inset). In the main panel, the value $\tau_2=0.8$ was considered because it provides the best global scaling. In the localized regime, a linear scaling (2) as a function of $(\log_2 N)/\xi$ gives a very good collapse of all the curves for different disorder strengths $W>W_c$. In the delocalized regime, the rescaling of the volume N by the correlation volume Λ (3) puts all the data onto each other. Lower inset: correlation volume Λ (circles) and localization length ξ (squares) on both sides of the transition. Solid lines are the fits: $\log_2 \Lambda = A_1 + A_2(W_c - W)^{-\kappa}$ and $\xi = A_3(W - W_c)^{-\nu_l}$, with $W_c = 0.6$ (assigned value), yielding $\kappa = 0.48$ and $\nu_l = 0.96$. (Right Panel) p = 0.49, $W \in [3, 12]$. At $W = 6 \approx W_c$, $\langle P_2 \rangle \sim (\log_2 N)^{-\tau_2}$ with $\tau_2 \approx 0.306$ (upper inset). In the main panel the value $\tau_2 = 0.3$ gives the best global scaling. The same scaling procedure as for p = 0.01 and 0.06 has been followed here. Lower inset: Solid lines are the fits: $\log_2 \Lambda = A_4 + A_5(W_c - W)^{-\kappa}$ and $\xi = A_6(W - W_c)^{-\nu_l}$, with $W_c = 6$ and $\kappa = 0.5$ (assigned values), yielding $\nu_l = 1.0$.

This leads to the following more precise asymptotic behavior:

$$\langle P_q \rangle \approx \left(\frac{\Lambda}{N}\right)^{q-1} \left(1 - \tau_q \frac{\xi}{d_N}\right) .$$
 (S11)

This is precisely what is predicted by the analytical theory [S8]: $P_2 \approx C/N$ with $\ln C \propto (W_c - W)^{-\kappa}$ close to the threshold, and κ the critical exponent in the delocalized phase. The corrections in the parenthesis are negligible in the limit $d_N \gg \xi$.

Finally, the volumic scaling hypothesis for the non-ergodicity volume $\lambda(N, W)$

$$\frac{\lambda}{N/d_N} = \mathcal{G}_{\text{vol}}\left(\frac{N}{\Lambda}\right) , \qquad (S12)$$

with $d_N \sim \log_2 N$, implies the following asymptotic behavior:

$$\mathcal{G}_{\text{vol}}(X) \sim \frac{\left[V_g^{-1}(X)\right]}{X}, \text{ for } X \to \infty, W < W_c.$$
 (S13)

Because $V_g^{-1}(N/\Lambda) = d_N - \xi$, in the limit of large system volume $N \gg \Lambda$:

$$\lambda \approx \frac{N}{d_N} \frac{\Lambda}{N} (d_N - \xi) = \Lambda \left(1 - \frac{\xi}{d_N} \right) . \tag{S14}$$

Therefore, in the delocalized phase, the non-ergodicity volume λ saturates to the correlation volume in the thermodynamic limit.

Universality versus a change of the graph parameter p

Here we present the results of the same scaling analysis represented in Fig. 2 for two distinct values of the graph parameter, p = 0.01 and p = 0.49. The same critical scalings and critical exponents are observed in Fig. S3: the linear

scaling law (2) where the linear system size $d_N \sim \log_2 N$ is rescaled by the scaling parameter ξ describes the data in the localized regime $W > W_c$ while a volumic scaling law (3) as a function of the ratio of the system volume N and the correlation volume Λ holds in the delocalized regime. As in the case p = 0.06 shown in the paper (see Fig. 2), the scaling parameter $\xi \sim \xi_l$ (localization length) diverges at the transition point as $\xi \sim (W - W_c)^{-\nu_l}$ with $\nu_l \approx 1$, while the correlation volume Λ diverges exponentially as $\ln \Lambda \sim (W_c - W)^{-\kappa}$ with the critical exponent $\kappa \approx 0.5$.

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