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# $L^{p}$ ESTIMATES FOR DEGENERATE NON-LOCAL KOLMOGOROV OPERATORS 

L. HUANG, S. MENOZZI, AND E. PRIOLA

Abstract. Let $z=(x, y) \in \mathbb{R}^{d} \times \mathbb{R}^{N-d}$, with $1 \leq d<N$. We prove a priori estimates of the following type :

$$
\left\|\Delta_{x}^{\frac{\alpha}{2}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq c_{p}\left\|L_{x} v+\sum_{i, j=1}^{N} a_{i j} z_{i} \partial_{z_{j}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}, 1<p<\infty,
$$

for $v \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$, where $L_{x}$ is a non-local operator comparable with the $\mathbb{R}^{d}$-fractional Laplacian $\Delta_{x}^{\frac{\alpha}{2}}$ in terms of symbols, $\alpha \in(0,2)$. We require that when $L_{x}$ is replaced by the classical $\mathbb{R}^{d}$-Laplacian $\Delta_{x}$, i.e., in the limit local case $\alpha=2$, the operator $\Delta_{x}+\sum_{i, j=1}^{N} a_{i j} z_{i} \partial_{z_{j}}$ satisfy a weak type Hörmander condition with invariance by suitable dilations. Such estimates were only known for $\alpha=2$. This is one of the first results on $L^{p}$ estimates for degenerate non-local operators under Hörmander type conditions. We complete our result on $L^{p}$-regularity for $L_{x}+\sum_{i, j=1}^{N} a_{i j} z_{i} \partial_{z_{j}}$ by proving estimates like

$$
\left\|\Delta_{y_{i}}^{\frac{\alpha_{i}}{2}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq c_{p}\left\|L_{x} v+\sum_{i, j=1}^{N} a_{i j} z_{i} \partial_{z_{j}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)},
$$

involving fractional Laplacians in the degenerate directions $y_{i}$ (here $\alpha_{i} \in(0,1 \wedge \alpha)$ depends on $\alpha$ and on the numbers of commutators needed to obtain the $y_{i}$-direction). The last estimates are new even in the local limit case $\alpha=2$ which is also considered.

## 1. Introduction and Setting of the problem

We prove global $L^{p}$-estimates of Calderón-Zygmund type for degenerate non-local Kolmogorov operators (see (1.4) below) acting on regular functions defined on $\mathbb{R}^{N}$. This is one of the first results on $L^{p}$ estimates for degenerate non-local operators under Hörmander type conditions. To prove the result we combine analytic and probabilistic techniques. Our estimates allow to address corresponding martingale problems or to study related parabolic Cauchy problems with $L^{p}$ source terms.

In particular, we consider operators which are sums of a fractional like Laplacian acting only on some (non-degenerate) variables plus a first order linear term acting on all $N$ variables which satisfies a weak type Hörmander condition with invariance by suitable dilations (see, for instance examples (1.7), (1.8), (1.9) below). We obtain maximal $L^{p}$-regularity with respect to the Lebesgue measure both in the non-degenerate variables and in the remaining degenerate variables. In the degenerate variables our estimates are new even in the wellstudied limit local case when the fractional like Laplacian is replaced by the Laplacian. They are also related to well-known estimates by Bouchut Bou02 on transport kinetic equations involving only one commutator; our estimates depend on the number of commutators one needs to obtain the degenerate directions.

We stress that $L^{p}$ estimates for non-local non-degenerate Lévy type operators have been investigated for a long time also motivated by applications to martingale problems. Significant works in that direction are for instance Str75], Koc89, MP92, Hoh94, BK07, DK12, Zha13, [K16]. Such operators also naturally appear in Physical applications for the study of anomalous diffusions (see e.g. [BBM01]). However, the corresponding degenerate problems have been rarely addressed and our current work can be seen as a first step towards the understanding of regularizing properties, of hypoellipticity type, for degenerate non-local operators satisfying a weak type Hörmander condition.

To introduce our setting let $1 \leq d<N$ and consider first the following non-local operator on $\mathbb{R}^{d}$ :

$$
\begin{equation*}
L_{\sigma} \phi(x)=\int_{\mathbb{R}^{d}}\left(\phi(x+\sigma y)-\phi(x)-\nabla \phi(x) \cdot \sigma y \mathbb{I}_{|y| \leq 1}\right) \nu(d y), \quad x \in \mathbb{R}^{d} \tag{1.1}
\end{equation*}
$$

where $\mathbb{I}_{|y| \leq 1}$ is the indicator function of the unit ball, the function $\phi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$ (i.e., $\phi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ is infinitely differentiable with compact support) and the matrix $\sigma \in \mathbb{R}^{d} \otimes \mathbb{R}^{d}$ satisfies the non-degeneracy assumption:
(UE) There exists $\kappa \geq 1$ s.t. for all $x \in \mathbb{R}^{d}$,

$$
\kappa^{-1}|x|^{2} \leq\left\langle\sigma \sigma^{*} x, x\right\rangle \leq \kappa|x|^{2}
$$

where $|\cdot|$ denotes the Euclidean norm, $\langle\cdot, \cdot\rangle$ or $\cdot$ is the inner product and ${ }^{*}$ stands for the transpose; $\nu$ is a nondegenerate symmetric stable Lévy measure of order $\alpha \in(0,2)$. Precisely, writing $y=\rho s,(\rho, s) \in \mathbb{R}_{+} \times \mathbb{S}^{d-1}$, where $\mathbb{S}^{d-1}$ stands for the unit sphere of $\mathbb{R}^{d}$, the measure $\nu$ decomposes as:

$$
\begin{equation*}
\nu(d y)=\frac{\tilde{\mu}(d s) d \rho}{\rho^{1+\alpha}} \tag{1.2}
\end{equation*}
$$

where $\tilde{\mu}$ is a Borel finite measure on $\mathbb{S}^{d-1}$ which is the spherical part of $\nu$. If $\sigma=I_{d \times d}$ (identity matrix of $\mathbb{R}^{d}$ ) and $\tilde{\mu}$ is proportional to the surface measure then $L_{I_{d \times d}}$ coincides with the fractional Laplacian on $\mathbb{R}^{d}$ with symbol $-|\lambda|^{\alpha}$. The Lévy symbol associated with $L_{\sigma}$ is given by the Lévy-Khintchine formula

$$
\Psi(\lambda)=\int_{\mathbb{R}^{d}}\left(e^{i\left\langle\sigma^{*} \lambda, y\right\rangle}-1-i\left\langle\sigma^{*} \lambda, y\right\rangle \mathbb{I}_{|y| \leq 1}(y)\right) \nu(d y), \quad \lambda \in \mathbb{R}^{d}
$$

(see, for instance, Sat05, Jac05 and App09). From Theorem 14.10 in Sat05, we know that

$$
\Psi(\lambda)=-\int_{\mathbb{S}^{d}-1}\left|\left\langle\sigma^{*} \lambda, s\right\rangle\right|^{\alpha} \mu(d s)
$$

where $\mu=C_{\alpha, d} \tilde{\mu}$ for a positive constant $C_{\alpha, d}$. The spherical measure $\mu$ is called the spectral measure associated with $\nu$. We suppose that $\mu$ is non-degenerate in the sense of Wat07:
(ND) There exists $\eta \geq 1$ s.t. for all $\lambda \in \mathbb{R}^{d}$,

$$
\begin{equation*}
\eta^{-1}|\lambda|^{\alpha} \leq \int_{\mathbb{S}^{d-1}}|\langle\lambda, s\rangle|^{\alpha} \mu(d s) \leq \eta|\lambda|^{\alpha} . \tag{1.3}
\end{equation*}
$$

We now introduce our (complete) Kolmogorov operator in the following way. Let $\mathbf{x}=\left(\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}\right) \in \mathbb{R}^{N}$, $n \geq 1$, where each $\mathbf{x}_{i} \in \mathbb{R}^{d_{i}}$, with $d_{1}=d$,

$$
d_{1} \geq d_{2} \geq \ldots \geq d_{n}>0, \quad N=d_{1}+d_{2}+\ldots+d_{n}
$$

We define for a non-degenerate matrix $\sigma \in \mathbb{R}^{d} \otimes \mathbb{R}^{d}$ satisfying (UE) and $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ the following operator:

$$
\begin{equation*}
\mathcal{L}_{\sigma} \varphi(\mathbf{x})=\left\langle A \mathbf{x}, \nabla_{\mathbf{x}} \varphi(\mathbf{x})\right\rangle+L_{\sigma} \varphi(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^{N} \tag{1.4}
\end{equation*}
$$

where

$$
\begin{equation*}
L_{\sigma} \varphi(\mathrm{x})=\int_{\mathbb{R}^{d}}\left(\varphi(\mathrm{x}+B \sigma y)-\varphi(\mathrm{x})-\nabla_{\mathbf{x}_{1}} \varphi(\mathrm{x}) \cdot \sigma y \mathbb{I}_{|y| \leq 1}\right) \nu(d y)=\text { v.p. } \int_{\mathbb{R}^{d}}(\varphi(\mathrm{x}+B \sigma y)-\varphi(\mathrm{x})) \nu(d y), \tag{1.5}
\end{equation*}
$$

and $B=\left(\begin{array}{c}I_{d_{1} \times d} \\ 0_{d_{2} \times d} \\ \vdots \\ 0_{d_{n} \times d}\end{array}\right)$ is the embedding matrix from $\mathbb{R}^{d}$ into $\mathbb{R}^{N}$. Also, the matrix $A \in \mathbb{R}^{N} \otimes \mathbb{R}^{N}$ has the
following structure (cf. examples (1.7), (1.8) and (1.9)):

$$
A=\left(\begin{array}{ccccc}
0_{d \times d} & \ldots & \cdots & \cdots & 0_{d \times d_{n}}  \tag{1.6}\\
A_{2,1} & 0_{d_{2} \times d_{2}} & \cdots & \cdots & 0_{d_{2} \times d_{n}} \\
0_{d_{3} \times d} & A_{3,2} & \ddots & \ldots & 0_{d_{3} \times d_{n}} \\
0 & \ddots & \ddots & \ddots & \vdots \\
0_{d_{n} \times d} & \cdots & 0_{d_{n} \times d_{n-2}} & A_{n, n-1} & 0_{d_{n} \times d_{n}}
\end{array}\right)
$$

The only non-zero entries are the matrices $\left(A_{i, i-1}\right)_{i \in \llbracket 2, n \rrbracket} \rrbracket$. We require that $A_{i, i-1} \in \mathbb{R}^{d_{i}} \otimes \mathbb{R}^{d_{i-1}}$. Moreover we assume that $A$ satisfies the following non-degeneracy condition of Hörmander type:
(H) The $\left(A_{i, i-1}\right)_{i \in \llbracket 2, n \rrbracket}$ are non-degenerate (i.e., each $A_{i, i-1}$ has rank $\left.d_{i}\right)$.

[^0]According to LP94 (see also BCM96 and DM10) the previous conditions (UE) and (H) imply in the limit case $\alpha=2$, i.e., when $L_{\sigma}$ is a second order differential operator like $\frac{1}{2} \operatorname{Tr}\left(\sigma \sigma^{*} D_{\mathbf{x}_{1}}^{2}\right)$, the well-known Hörmander's hypoellipticity condition for $\mathcal{L}_{\sigma}$ involving $n-1$ commutators starting from $\sigma D_{\mathbf{x}_{1}}$ and $\left\langle A \mathbf{x}, \nabla_{\mathbf{x}} \cdot\right\rangle$ (cf. Hör67). Precisely, our conditions on the matrix $A$ are the same as in BCM96. Note that in the case $\alpha=2$ operators $\mathcal{L}_{\sigma}$ are also considered from the control theory point of view (see BZ09, RM16] and the references therein).

In our non-local framework, assuming additionally (ND), even though no general Hörmander theorem seems to hold (cf. [KT01]) the Markov semi-group associated with $\mathcal{L}_{\sigma}$ admits a smooth density, see e.g. [PZ09].

We say that assumption (A) holds when (UE), (ND) and (H) are in force. In the following, we denote by $C:=C((\mathbf{A})) \geq 1$ or $c:=c((\mathbf{A})) \geq 1$ a generic constant that might change from line to line and that depends on the parameters of assumption (A), namely on $\alpha \in(0,2)$, the non degeneracy constants $\kappa, \eta$ in (UE), (ND) as well as those of $(\mathbf{H})$ and the dimensions $\left(d_{i}\right)_{i \in \llbracket 1, n \rrbracket}$. Other specific dependences are explicitly specified. Let us shortly present some examples of operators satisfying the previous assumptions (A) with $\sigma$ equal to identity:

- A basic example is given by the following:

$$
\begin{equation*}
\mathcal{L}=\Delta_{\mathbf{x}_{1}}^{\frac{\alpha}{2}}+\mathbf{x}_{1} \cdot \nabla_{\mathbf{x}_{2}} \tag{1.7}
\end{equation*}
$$

where $\mathbf{x}=\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right) \in \mathbb{R}^{2 d}, d \geq 1$; this is the extension to the non-local fractional setting of the celebrated Kolmogorov example, see Kol34], that inspired Hörmander's hypoellipticity theory Hör67 in the diffusive case (in this case we have $N=2 d, n=2$ and $d_{1}=d_{2}=d$ ). From the probabilistic viewpoint, $\mathcal{L}$ corresponds to the generator of the couple formed by an isotropic stable process and its integral. Such processes might appear in kinetics/Hamiltonian dynamics when considering the joint distribution of the velocity-position of stable driven particles (see e.g. Tal02] in the diffusive case or CPKM05] for the non-local one in connection with the Richardson scaling law in turbulence). Non-local degenerate kinetic diffusion equations appear as well as diffusion limits of linearized Boltzmann equations when the equilibrium distribution function is a heavy-tailed distribution (see MMM08, Mel16 and Rad12).

- Consider now for $d^{*} \in \mathbb{N}$ :

$$
\begin{equation*}
\mathcal{L}=\Delta_{\mathbf{x}_{1}^{1}}^{\frac{\alpha}{2}}+\Delta_{\mathbf{x}_{1}^{2}}^{\frac{\alpha}{2}}+\mathbf{x}_{1}^{1} \cdot \nabla_{\mathbf{x}_{2}}+\mathbf{x}_{2} \cdot \nabla_{\mathbf{x}_{3}}, \tag{1.8}
\end{equation*}
$$

for $\mathbf{x}_{1}=\left(\mathbf{x}_{1}^{1}, \mathbf{x}_{1}^{2}\right) \in \mathbb{R}^{2 d^{*}}, \mathbf{x}=\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \mathbf{x}_{3}\right) \in \mathbb{R}^{4 d^{*}}$, i.e., $N=4 d^{*}, n=3, d_{1}=2 d^{*}$ and $d_{2}=d_{3}=d^{*}$. If $d^{*}=1$, the non-degenerate part of the above operator corresponds to the so-called cylindrical fractional Laplacian (in this case the Lévy measure $\nu$ is concentrated on $\left\{x_{1}^{1}=0\right\} \cup\left\{x_{1}^{2}=0\right\}$, cf. e.g. [BC06]).

- A natural generalization of the previous example consists in considering:

$$
\begin{equation*}
\mathcal{L}=L_{\sigma}+\mathbf{x}_{1}^{1} \cdot \nabla_{\mathbf{x}_{2}}+\mathbf{x}_{2} \cdot \nabla_{\mathbf{x}_{3}}, L_{\sigma} \phi(x)=\sum_{i=1}^{2} \mathrm{v} \cdot \mathrm{p} . \int_{\mathbb{R}^{d^{*}}}\left(\phi\left(x+\sigma_{i} z\right)-\phi(x)\right) \frac{d z}{|z|^{d^{*}+\alpha}}, \tag{1.9}
\end{equation*}
$$

$\phi \in C_{0}^{\infty}\left(\mathbb{R}^{2 d^{*}}\right), x \in \mathbb{R}^{2 d^{*}}, \sigma_{i} \in \mathbb{R}^{2 d *} \otimes \mathbb{R}^{d *}$ and $\sigma=\left(\sigma_{1} \sigma_{2}\right)$ verifies (UE). The non-degenerate part $L_{\sigma}$ of $\mathcal{L}$ corresponds to the generator of the $\mathbb{R}^{2 d^{*}}$-valued process $\mathbf{X}_{t}^{1}=\mathbf{x}_{1}+\sum_{i=1}^{2} \sigma_{i} Z_{t}^{i}$, where the $\left(Z^{i}\right)_{i \in \llbracket 1,2 \rrbracket}$ are two independent isotropic stable processes of dimension $\mathbb{R}^{d *}$. The full operator $\mathcal{L}$ is the generator of $\left(\mathbf{X}_{t}^{1}, \mathbf{X}_{t}^{2}, \mathbf{X}_{t}^{3}\right)=\left(\mathbf{X}_{t}^{1}, \int_{0}^{t} \mathbf{X}_{s}^{11} d s, \int_{0}^{t} \int_{0}^{s} \mathbf{X}_{u}^{11} d u d s\right)$ where for $u>0, \mathbf{X}_{u}^{11}$ denotes the first $d^{*}$ entries of $\mathbf{X}_{u}^{1}$. Such dynamics could arise in finance, if we for instance assume that $\mathbf{X}^{1}$ models the evolution of a $2 d^{*}$-dimensional asset, for which each component feels both noises $Z^{1}$ and $Z^{2}$ in $\mathbb{R}^{d^{*}}$ through the matrices $\sigma_{1}, \sigma_{2}$, but for which one would be interested in the distribution of the (iterated) averages of some marginals, in the framework of the associated Asian options, here $\left(\mathbf{X}^{2}, \mathbf{X}^{3}\right)$. We refer to BPV01] in the diffusive setting for details.

In the case $N=n d, n>2$, oscillator chains also naturally appear for the diffusive case in heat conduction models (see e.g. EPRB99 and DM10 for some related heat kernel estimates). The operators we consider here could also appear naturally in order to study anomalous diffusion phenomena within this framework.

To state our $L^{p}$ estimates, for all $i \in \llbracket 1, n \rrbracket$, we introduce the orthogonal projection $\pi_{i}: \mathbb{R}^{N} \rightarrow \mathbb{R}^{d_{i}}$, $\pi_{i}(\mathbf{x})=\mathbf{x}_{i}, \mathbf{x} \in \mathbb{R}^{N}$. Then we introduce the adjoint $B_{i}=\pi_{i}^{*}: \mathbb{R}^{d_{i}} \rightarrow \mathbb{R}^{N}$ (note that $B_{1}=B$ ) and define

$$
\begin{equation*}
\alpha_{i}:=\frac{\alpha}{(1+(i-1) \alpha)} ; \quad \text { clearly we have } \alpha_{1}=\alpha, \quad \alpha_{i} \in(0,1 \wedge \alpha), \quad i \in \llbracket 2, n \rrbracket . \tag{1.10}
\end{equation*}
$$

Theorem 1.1. Assume that (A) holds. Then, for $v \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ and $p \in(1,+\infty)$ there exists $c_{p}:=c_{p}((\mathbf{A}))$ s.t. for all $i \in \llbracket 1, n \rrbracket$ :

$$
\begin{equation*}
\left\|\Delta_{\mathbf{x}_{i}^{2}}^{\frac{\alpha_{i}}{i}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq c_{p}\left\|\mathcal{L}_{\sigma} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}, \tag{1.11}
\end{equation*}
$$

where in the above equation $\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}}$ denotes the $\mathbb{R}^{d_{i}}$-fractional Laplacian w.r.t. to the $\mathbf{x}_{i}$-variable, i.e.,

$$
\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} v(\mathbf{x})=v \cdot p \cdot \int_{\mathbb{R}^{d_{i}}}\left(v\left(\mathbf{x}+B_{i} z\right)-v(\mathbf{x})\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}
$$

The above result still holds in the diffusive limit case, i.e. when $\alpha=2$ and $L_{\sigma}=\frac{1}{2} \operatorname{Tr}\left(\sigma \sigma^{*} D_{\mathbf{x}_{1}}^{2}\right)$ is a second order non-degenerate differential operator in $\mathbf{x}_{1}$. This limit case is specifically addressed in Appendix below. The theorem is obtained as a consequence of an $L^{p}$-parabolic regularity result of independent interest (see Theorem 2.4). Let us comment separately the case $i=1$ (i.e., $\Delta_{\mathbf{x}_{1}}^{\frac{\alpha_{1}}{2}}=\Delta_{\mathbf{x}_{1}}^{\frac{\alpha}{2}}$ ) and $i=2, \ldots, n$.

The case $i=2, \ldots, n$ is new even if we consider the local case of $\alpha=2$. In that case, FL06] considers similar estimates for $p=2$ in non-isotropic fractional Sobolev spaces with respect to an invariant Gaussian measure assuming that the hypoelliptic Ornstein-Uhlenbeck operator $\mathcal{L}_{\sigma}$ admits such invariant measure. Also, in the special kinetic case (1.7), the $L^{p}$-estimate for $\Delta_{\mathbf{x}_{2}}^{\frac{\alpha}{1+\alpha}} v, \alpha \in(0,2]$ can be derived from Bouchut Bou02]. In this work general estimates on the degenerate variable are derived from the transport equation $\left(\partial_{t}+\mathbf{x}_{1} \cdot \nabla_{\mathbf{x}_{2}}\right) u=f$ assuming a priori regularity of $u$ in the non-degenerate variable (i.e. in the current setting an integrability condition on $\Delta_{\mathbf{x}_{1}}^{\frac{\alpha}{2}} u$ or more generally on $L_{\sigma} u$ with $L_{\sigma}$ as in (1.1)) and integrability conditions on $f$.

The approach we develop here, naturally based on the theory of singular integrals on homogeneous spaces (since we have dilation properties for the operator) allows to derive directly the estimates on all the variables exploiting somehow the regularizing properties of the underlying singular kernels. On the other hand, in light of our theorems, it seems a natural open problem to extend Bouchut's estimates to the more general transport equation

$$
\left(\partial_{t}+A \mathbf{x} \cdot \nabla_{\mathbf{x}}\right) u=f
$$

with $A$ as in (1.6), when more than one commutator is needed to span the space, assuming $\Delta_{\mathbf{x}_{1}}^{\frac{\alpha}{2}} u \in L^{p}$.
Our estimate (1.11) in the case $i=1$ can be viewed as a non-local extension of the results by BCLP10. Indeed, the quoted work concerns with estimates similar to (1.11) with $i=1$ for a diffusion operator, i.e. the limit case $\alpha=2$ when $\Delta_{\mathbf{x}_{1}}^{\frac{\alpha}{2}}$ corresponds to $\Delta_{\mathbf{x}_{1}}$ and $L_{\sigma}$ to a second order differential operator like $\operatorname{Tr}\left(\sigma \sigma^{*} D_{\mathbf{x}_{1}}^{2}\right)$. In this framework, the authors obtained estimates of the following type:

$$
\begin{equation*}
\left\|D_{\mathbf{x}_{1}}^{2} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq c_{p}\left(\left\|\mathcal{L}_{\sigma} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}+\|v\|_{L^{p}\left(\mathbb{R}^{N}\right)}\right) \tag{1.12}
\end{equation*}
$$

(here $D_{\mathbf{x}_{1}}^{2} v$ is the Hessian matrix of $v$ with respect to the $\mathbf{x}_{1}$-variable). Note that by the classical CalderónZygmund theory: $\left\|D_{\mathbf{x}_{1}}^{2} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq C_{p}\left\|\Delta_{\mathbf{x}_{1}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}$. Hence (1.11) for $i=1$ and $\alpha=2$ can be reformulated as

$$
\left\|D_{\mathbf{x}_{1}}^{2} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)} \leq c_{p}\left\|\mathcal{L}_{\sigma} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}
$$

Note that (1.12) has an extra term $\|v\|_{L^{p}\left(\mathbb{R}^{N}\right)}$ on the right-hand side. This is due to the fact that our structure of the matrix $A$ is more restrictive than in BCLP10] and FL06 (cf Remark 2.4). On the other hand, by our assumptions on $A$ we can use the theory of homogeneous spaces with the doubling property as in CW71.

In contrast with previous works (see in particular BCM96] and BCLP10), we do not use here an underlying Lie group structure. Another difference is that we are able to prove directly the important $L^{2}$-estimates (see Lemma 4.1). This is why in contrast with [BCM96] we can entirely rely on the Coifmann-Weiss setting [CW71].

Let us mention that results similar to Theorem 1.1 have been obtained in [CZ16] in the special kinetic case of (1.7). Their strategy is totally different and relies on the Fefferman and Stein approach [FS72] for the non-degenerate variable. The estimate for the degenerate one is then derived from Bouchut's estimates [Bou02].

We avoid here diagonal terms and time dependence in $A$ in (1.6) for simplicity (see the extensions discussed in Appendix A of the preliminary preprint version HMP16). With zero diagonal, considering non-degenerate time dependent coefficients in (1.6) would not change the analysis but make the notations in Section 2 below more awkward. Adding diagonal terms, even time-homogeneous, would lead to time dependent constants in our parabolic estimates of Theorem [2.4. Anyhow, introducing additional strictly super-diagonal elements in A breaks the homogeneity (see Section 2 and Appendix A of HMP16 for details). This seemingly small modification actually induces to consider estimates from harmonic analysis in non-doubling spaces developed in a rather abstract setting by [Bra10]. This is precisely the approach developed in [BCLP10]. Handling a general matrix $A$ in the current framework will concern further research. We finally point out that our approach also permits to recover the estimates of the non-degenerate case, i.e. when $n=1, N=d$ and $A=0$.

The article is organized as follows. We first discuss in Section 2 the appropriate homogeneous framework, depending on the index $\alpha \in(0,2]$, needed for our analysis. Importantly, we manage to express the fundamental
solution of $\partial_{t}-\mathcal{L}_{\sigma}$, in terms of the density at time $t>0$ of a non-degenerate stable process $\left(S_{t}\right)_{t \geq 0}$ on $\mathbb{R}^{N}$ rescaled according to the homogeneous scales (see Proposition [2.3) 2. We eventually state our second main result Theorem [2.4 which is the parabolic version of Theorem 1.1 , and actually permits to prove Theorem 1.1

We then describe in Section 3 the strategy of the proof of Theorem 2.4 relying on the theory of Coifman and Weiss (see Appendix C). Section 4 is dedicated to the key estimates ( $L^{2}$ bound and controls of the singular kernels) needed for the proof of our main results. This is the technical core of this paper. Rewriting the fundamental solution of $\partial_{t}-\mathcal{L}_{\sigma}$ in terms of the density of the rescaled stable process $\left(S_{t}\right)_{t \geq 0}$ allows to analyse the terms $\left(\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} v\right\|_{L^{p}\left(\mathbb{R}^{N}\right)}\right)_{i \in \llbracket 1, n \rrbracket}$, through singular integral analysis techniques that exploit the integrability properties of any non-degenerate stable density, no matter how singular the spectral measure is (see Lemma 4.3). We use in Section 5 the estimates of Section 4 in order to fit our specific framework following the strategy of Section 3. Some technical points are proved for the sake of completeness in Appendix A. The specific features associated with the limit local case $\alpha=2$ are discussed in Appendix B Finally, as indicated at the beginning of the introduction, we mention that possible applications of our estimates to well-posedness of martingale problems for operators like

$$
\mathcal{L}_{\sigma(\mathbf{x})} \varphi(\mathbf{x})=\left\langle A \mathbf{x}, \nabla_{\mathbf{x}} \varphi(\mathbf{x})\right\rangle+L_{\sigma(\mathbf{x})} \varphi(\mathbf{x})
$$

will be a subject of a future work (cf. Appendix A in HMP16 for preliminary results in this direction).

## 2. Homogeneity Properties

The key point to establish the estimates in Theorem 1.1 consists in first considering the parabolic setting. To this end, we consider the evolution operator defined for $\psi \in C_{0}^{\infty}\left(\mathbb{R}^{1+N}\right)$ by:

$$
\begin{equation*}
\mathscr{L}_{\sigma} \psi(t, \mathbf{x}):=\left(\partial_{t}+\mathcal{L}_{\sigma}\right) \psi(t, \mathbf{x}),(t, \mathbf{x}) \in \mathbb{R}^{1+N} . \tag{2.1}
\end{equation*}
$$

The following proposition is fundamental and follows from the structure of $A$ and $L_{\sigma}$ under (A).
Proposition 2.1 (Invariance by dilation). Let (A) be in force and $u \in C_{0}^{\infty}\left(\mathbb{R}^{1+N}\right)$ solve the equation $\mathscr{L}_{\sigma} u(t, \mathbf{x})=0,(t, \mathbf{x}) \in \mathbb{R}^{1+N}$. Then, for any $\delta>0$, the function $u_{\delta}(t, \mathbf{x}):=u\left(\delta^{\alpha} t, \delta \mathbf{x}_{1}, \delta^{1+\alpha} \mathbf{x}_{2}, \cdots, \delta^{1+(n-1) \alpha} \mathbf{x}_{n}\right)$ also solves $\mathscr{L}_{\sigma} u_{\delta}(t, \mathbf{x})=0,(t, \mathbf{x}) \in \mathbb{R}^{1+N}$.
Proof. It is actually easily checked that:

$$
\mathscr{L}_{\sigma} u_{\delta}(t, \mathbf{x})=\left.\delta^{\alpha}\left(\mathscr{L}_{\sigma} u\left(\mathbf{z}_{\delta}\right)\right)\right|_{\mathbf{z}_{\delta}=\left(\delta^{\alpha} t, \delta \mathbf{x}_{1}, \delta^{1+\alpha} \mathbf{x}_{2}, \cdots, \delta^{1+(n-1) \alpha} \mathbf{x}_{n}\right)} .
$$

Since for all $\mathbf{z} \in \mathbb{R}^{1+N}, \mathscr{L}_{\sigma} u(\mathbf{z})=0$, the result follows.
The previous proposition leads us to define the following homogeneous norm (cf. [BCM96] or BCLP10]):
Definition 2.2 (Homogeneous Pseudo-Norm). Let $\alpha \in(0,2]$. We define for all $(t, \mathbf{x}) \in \mathbb{R}^{1+N}$ the pseudo-norm:

$$
\begin{equation*}
\rho(t, \mathbf{x})=|t|^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\mathbf{x}_{i}\right|^{\frac{1}{1+\alpha(i-1)}} . \tag{2.2}
\end{equation*}
$$

Remark 2.1. Let us observe that $\rho$ is not a norm because the homogeneity property fails, i.e. for $\delta>$ $0, \rho(\delta t, \delta \mathbf{x}) \neq \delta \rho(t, \mathbf{x})$. Actually, the homogeneity appears through the dilation operator of Proposition 2.1. Namely, for $\mathbf{z}=(t, \mathbf{x}) \in \mathbb{R}^{1+N}$ and $\mathbf{z}_{\delta}=\left(\delta^{\alpha} t, \delta \mathbf{x}_{1}, \delta^{1+\alpha} \mathbf{x}_{2}, \cdots, \delta^{1+(n-1) \alpha} \mathbf{x}_{n}\right)$ we indeed have: $\rho\left(\mathbf{z}_{\delta}\right)=\delta \rho(\mathbf{z})$.

The dilation operator can also be rewritten using the scale matrix $\mathbb{M}_{t}$ in (2.6). Namely, $\mathbf{z}_{\delta}=\left(\delta^{\alpha} t, \delta \mathbb{M}_{\delta \alpha} \mathbf{x}\right)$.
Remark 2.2 (Regularity of $\mathcal{L}_{\sigma} v$ ). If $v \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ it is not difficult to prove that $\mathcal{L}_{\sigma} v \in C^{\infty}\left(\mathbb{R}^{N}\right)$. Moreover, $\mathcal{L}_{\sigma} v$ and all its partial derivatives belong to $\cap_{p \in[1, \infty]} L^{p}\left(\mathbb{R}^{N}\right)$.

We only check that, when $p \in[1,+\infty), \mathcal{L}_{\sigma} v \in L^{p}\left(\mathbb{R}^{N}\right)$. Since $\left\langle A \mathbf{x}, \nabla_{\mathbf{x}} v\right\rangle \in L^{p}\left(\mathbb{R}^{N}\right)$ we concentrate on $L_{\sigma} v$ (see (1.5)). We can write

$$
\begin{gathered}
L_{\sigma} v=v_{1}+v_{2}, \quad v_{1}(\mathbf{x})=\int_{|y| \leq 1} \frac{\left(v(\mathbf{x}+B \sigma y)-v(\mathbf{x})-\nabla_{\mathbf{x}_{1}} v(\mathbf{x}) \cdot \sigma y\right)}{|y|^{2}}|y|^{2} \nu(d y), \\
v_{2}(\mathbf{x})=\int_{|y|>1}(v(\mathbf{x}+B \sigma y)-v(\mathbf{x})) \nu(d y), \quad \mathbf{x} \in \mathbb{R}^{N} .
\end{gathered}
$$

[^1]We easily obtain that $v_{1} \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$. Moreover, from the Hölder inequality and the Fubini theorem, we get

$$
\int_{\mathbb{R}^{N}}\left|v_{2}(\mathbf{x})\right|^{p} d \mathbf{x} \leq c \int_{|y|>1} \nu(d y) \int_{\mathbb{R}^{N}}|v(\mathbf{x}+B \sigma y)-v(\mathbf{x})|^{p} d \mathbf{x}<\infty
$$

We now study the homogeneous framework of the Ornstein-Uhlenbeck process $\left(\Lambda_{t}\right)_{t \geq 0}$ satisfying the stochastic differential equation (SDE):

$$
\begin{equation*}
d \Lambda_{t}=A \Lambda_{t} d t+B \sigma d Z_{t}, \quad \Lambda_{0}=\mathbf{x} \in \mathbb{R}^{N} \tag{2.3}
\end{equation*}
$$

where $B$ again stands for the embedding matrix from $\mathbb{R}^{d}$ (the space where the noise lives) into $\mathbb{R}^{N}$. Here $\left(Z_{t}\right)_{t \geq 0}$ is a stable $\mathbb{R}^{d}$-dimensional process with Lévy measure $\nu$ defined on some complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$. For a given starting point $\mathbf{x} \in \mathbb{R}^{N}$, the above dynamics explicit integrates and gives:

$$
\begin{equation*}
\Lambda_{t}^{\mathbf{x}}=\exp (t A) \mathbf{x}+\int_{0}^{t} \exp ((t-s) A) B \sigma d Z_{s} \tag{2.4}
\end{equation*}
$$

It is readily derived from [PZ09] that, for $t>0$ the random variable $\Lambda_{t}$ has a density $p_{\Lambda}(t, \mathbf{x}, \cdot)$ w.r.t. the Lebsegue measure of $\mathbb{R}^{N}$. Additionally, we derive in (2.8) of Proposition 2.3 below (similarly to Proposition 5.3 of HM16] which is stated in a more general time-dependent coefficients framework) that

$$
\begin{equation*}
p_{\Lambda}(t, \mathbf{x}, \mathbf{y})=\frac{1}{\operatorname{det}\left(\mathbb{M}_{t}\right)} p_{S}\left(t,\left(\mathbb{M}_{t}\right)^{-1}\left(e^{t A} \mathbf{x}-\mathbf{y}\right)\right), t>0 \tag{2.5}
\end{equation*}
$$

where the diagonal matrix

$$
\mathbb{M}_{t}=\left(\begin{array}{cccc}
I_{d \times d} & 0_{d \times d_{2}} & \cdots & 0_{d \times d_{n}}  \tag{2.6}\\
0_{d_{2} \times d} & t I_{d_{2} \times d_{2}} & 0 & \vdots \\
\vdots & \ddots & \ddots & \vdots \\
0_{d_{n} \times d} & \cdots & 0 & t^{n-1} I_{d_{n} \times d_{n}}
\end{array}\right)
$$

gives the multi-scale characteristics of the density of $\Lambda_{t}$ and $\left(S_{t}\right)_{t \geq 0}$ is a stable process in $\mathbb{R}^{N}$ whose Lévy measure $\nu_{S}$ though having a very singular spherical part, satisfies the non-degeneracy assumption (ND) in $\mathbb{R}^{N}$. From a more analytical viewpoint the entries of $t^{\frac{1}{\alpha}} \mathbb{M}_{t}$, which correspond to the typical scales of a stable process and its iterated integrals, provide the underlying homogeneous structure.

To prove our results we will often use the following rescaling identity

$$
\begin{equation*}
e^{r A}=\mathbb{M}_{r} e^{A} \mathbb{M}_{r}^{-1}, \quad r>0 \tag{2.7}
\end{equation*}
$$

and its adjoint form $e^{r A^{*}}=\mathbb{M}_{r}^{-1} e^{A^{*}} \mathbb{M}_{r}$. To get (2.7) we first check directly that $\mathbb{M}_{r} A \mathbb{M}_{r}^{-1}=r A, r>0$; then we have the assertion writing

$$
e^{r A}=I+r A+\frac{r^{2}}{2} A^{2}+\ldots=I+\mathbb{M}_{r} A \mathbb{M}_{r}^{-1}+\frac{1}{2} \mathbb{M}_{r} A \mathbb{M}_{r}^{-1} \mathbb{M}_{r} A \mathbb{M}_{r}^{-1}+\ldots
$$

The next result is crucial for our main estimates.
Proposition 2.3 (Density and Fundamental Solution). Under (A), the process $\left(\Lambda_{t}^{\mathbf{x}}\right)_{t \geq 0}$ defined in (2.3) has for all $t>0$ and starting point $\mathbf{x} \in \mathbb{R}^{N}$ a $C^{\infty}\left(\mathbb{R}^{N}\right)$-density $p_{\Lambda}(t, \mathbf{x}, \cdot)$ that writes for all $\mathbf{y} \in \mathbb{R}^{N}$ :

$$
\begin{array}{r}
p_{\Lambda}(t, \mathbf{x}, \mathbf{y})=  \tag{2.8}\\
\left.(2 \pi)^{N}\right) \\
\int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbb{M}_{t}^{-1}(\mathbf{y}-\exp (t A) \mathbf{x}), \mathbf{p}\right\rangle\right) \exp \left(-t \int_{\mathbb{S}^{N-1}}|\langle\mathbf{p}, \boldsymbol{\xi}\rangle|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) d \mathbf{p}
\end{array}
$$

where $\mathbb{M}_{t}$ is defined in (2.6) and $\mu_{S}$ is a symmetric spherical measure on $\mathbb{S}^{N-1}$ satisfying the non-degeneracy condition (ND) on $\mathbb{R}^{N}$ instead of $\mathbb{R}^{d}$.

The analytical counterpart of this expression is that the operator $\partial_{t}-\mathcal{L}_{\sigma}$ has a fundamental solution given by $p_{\Lambda} \in C^{\infty}\left(\mathbb{R}_{+}^{*} \times \mathbb{R}^{2 N}\right)$. Also, for every $u \in C_{0}^{\infty}\left(\mathbb{R}^{1+N}\right)$, the following representation formula holds:

$$
\begin{equation*}
u(t, \mathbf{x})=-\int_{t}^{\infty} d s \int_{\mathbb{R}^{N}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) \mathscr{L}_{\sigma} u(s, \mathbf{y}) d \mathbf{y}, \quad(t, \mathbf{x}) \in \mathbb{R}^{1+N} \tag{2.9}
\end{equation*}
$$

Remark 2.3 (A useful identity in law). Let $\left(S_{t}\right)_{t \geq 0}$ be a (unique in law) $\mathbb{R}^{N}$-valued symmetric $\alpha$-stable process with spectral measure $\mu_{S}$ defined on $(\Omega, \mathcal{F}, \mathbb{P})$, i.e.,

$$
\mathbb{E}\left[e^{i\left\langle\mathbf{p}, S_{t}\right\rangle}\right]=\exp \left(-t \int_{\mathbb{S}^{N}-1}|\langle\mathbf{p}, \boldsymbol{\xi}\rangle|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right), \quad t \geq 0, \mathbf{p} \in \mathbb{R}^{N}
$$

By the previous result we know that $S_{t}$ has a $C^{\infty}$-density $p_{S}(t, \cdot)$ for $t>0$. Note that $S_{t} \stackrel{\text { (law) }}{=} t^{\frac{1}{\alpha}} S_{1}$ which is equivalent to $p_{S}(t, \mathbf{x})=t^{-\frac{N}{\alpha}} p_{S}\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right), t>0, \mathbf{x} \in \mathbb{R}^{N}$. Moreover, (2.5) holds and is equivalent to (2.8). In a more probabilistic way, this means that for any fixed $t>0$ the following identity in law holds:

$$
\begin{equation*}
\Lambda_{t}^{\mathbf{x}} \stackrel{(\text { law })}{=} \exp (t A) \mathbf{x}+\mathbb{M}_{t} S_{t} \tag{2.10}
\end{equation*}
$$

Proof of Proposition 2.3. Let $t \geq 0$ be fixed. Observe first that for a given $m \in \mathbb{N}$ considering the associated uniform partition $\Pi^{m}:=\left\{\left(t_{i}:=\frac{i}{m} t\right)_{i \in \llbracket 0, m \rrbracket}\right\}$ of $[0, t]$ yields for all $\mathbf{p} \in \mathbb{R}^{N}$ :

$$
\begin{array}{r}
\mathbb{E}\left[\exp \left(i\left\langle\mathbf{p}, \sum_{i=0}^{m-1} \exp \left(\left(t-t_{i}\right) A\right) B \sigma\left(Z_{t_{i+1}}-Z_{t_{i}}\right)\right\rangle\right)\right] \\
=\exp \left(-\frac{1}{m} \sum_{i=0}^{m-1} \int_{\mathbb{S}^{d}-1}\left|\left\langle\sigma^{*} B^{*} \exp \left(\left(t-t_{i}\right) A^{*}\right) \mathbf{p}, \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s})\right)
\end{array}
$$

Thus, by the dominated convergence theorem, one gets from (2.4) that the characteristic function or Fourier transform of $\Lambda_{t}^{\mathbf{x}}$ writes for all $\mathbf{p} \in \mathbb{R}^{N}$ :

$$
\begin{align*}
\varphi_{\Lambda_{t}^{x}}(\mathbf{p}):= & \mathbb{E}\left(e^{i\left\langle\mathbf{p}, \Lambda_{t}^{\times}\right\rangle}\right)=\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-\int_{0}^{t} \int_{\mathbb{S}^{d-1}}\left|\left\langle\exp \left(u A^{*}\right) \mathbf{p}, B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d u\right) \\
& =\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-t \int_{0}^{1} \int_{\mathbb{S}^{d-1}}|\langle\mathbf{p}, \exp (v t A) B \sigma \mathbf{s}\rangle|^{\alpha} \mu(d \mathbf{s}) d v\right) \\
& =\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-t \int_{0}^{1} \int_{\mathbb{S}^{d-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \exp (v A) \mathbb{M}_{t}^{-1} B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d v\right)  \tag{2.11}\\
& =\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-t \int_{0}^{1} \int_{\mathbb{S}^{d-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \exp (v A) B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d v\right)
\end{align*}
$$

where we have used (2.7) and the fact that $\mathbb{M}_{t}^{-1} B \mathbf{y}=B \mathbf{y}$, for any $\mathbf{y} \in \mathbb{R}^{d}$. Introduce now the function

$$
\begin{array}{rlc}
f: \quad[0,1] \times \mathbb{S}^{d-1} & \longrightarrow & \mathbb{S}^{N-1} \\
(v, \mathbf{s}) & \longmapsto & \frac{\exp (v A) B \sigma \mathbf{s}}{|\exp (v A) B \sigma \mathbf{s}|}
\end{array}
$$

and on $[0,1] \times \mathbb{S}^{d-1}$ the measure: $m_{\alpha}(d v, d \mathbf{s})=|\exp (v A) B \sigma \mathbf{s}|^{\alpha} \mu(d \mathbf{s}) d v$. The Fourier transform in (2.11) thus rewrites:

$$
\varphi_{\Lambda_{t}^{x}}(\mathbf{p})=\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-t \int_{\mathbb{S}^{N-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \boldsymbol{\xi}\right\rangle\right|^{\alpha} \bar{\mu}(d \boldsymbol{\xi})\right)
$$

where $\bar{\mu}$ is the image of $m_{\alpha}$ by $f$. Introduce now the symmetrized version of $\bar{\mu}$, defining for all $A \in \mathcal{B}\left(\mathbb{S}^{N-1}\right)$ (Borel $\sigma$-field of $\mathbb{S}^{N-1}$ ): $\mu_{S}(A)=\frac{\bar{\mu}(A)+\bar{\mu}(-A)}{2}$. We get that

$$
\begin{equation*}
\varphi_{\Lambda_{t}^{\times}}(\mathbf{p})=\exp \left(i\langle\mathbf{p}, \exp (t A) \mathbf{x}\rangle-t \int_{\mathbb{S}^{N}-1}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \boldsymbol{\xi}\right\rangle\right|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) \tag{2.12}
\end{equation*}
$$

which indeed involves the exponent of a symmetric stable process $\left(S_{t}\right)_{t \geq 0}$ with spectral measure $\mu_{S}$ at point $\mathbb{M}_{t} \mathbf{p}$. Up to now we have just proved (2.10). On the other hand, it follows from (2.11) and (ND) that there exists $c:=c((\mathbf{A}))>0$ s.t.:

$$
\begin{equation*}
\int_{0}^{1} \int_{\mathbb{S}^{d-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \exp (v A) B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d v \geq c\left|\mathbb{M}_{t} \mathbf{p}\right|^{\alpha} \tag{2.13}
\end{equation*}
$$

The above result is algebraic. We refer to Lemma A. 1 or to HM16 for a complete proof. Thus, the mapping $\mathbf{p} \in \mathbb{R}^{N} \mapsto \varphi_{\Lambda_{t}^{x}}(\mathbf{p})$ is in $L^{1}\left(\mathbb{R}^{N}\right)$ so that (2.8) follows by inversion and a direct change of variable. The smoothness of $p_{\Lambda}$ readily follows from (2.8) and (2.13). It is then well known (see e.g. Dyn65), and it can as well be easily derived by direct computations, that $p_{\Lambda}$ is a fundamental solution of $\partial_{t}-\mathcal{L}_{\sigma}$ (note that $\left(\partial_{t}-\mathcal{L}_{\sigma}\right) p(\cdot, \cdot, \mathbf{y})=0$ on $(0,+\infty) \times \mathbb{R}^{N}$ for all $\mathbf{y} \in \mathbb{R}^{N}$ and $p(t, \mathbf{x}, \cdot) \longrightarrow \delta_{\mathbf{x}}(\cdot)$ as $\left.t \rightarrow 0^{+}\right)$.

Equation (2.9) can be easily obtained by using the Fourier transform taking into account that the symbol of $\mathcal{L}_{\sigma}$ is $\Psi(\lambda)$ (cf. Section 3.3.2 in App09). It can also be derived by Itô's formula applied to $\left(u\left(r+t, \Lambda_{r}^{\mathbf{x}}\right)\right)_{r \geq 0}$ (cf. Section 4.4 in App09). We have

$$
\mathbb{E}\left[u\left(r+t, \Lambda_{r}^{\mathbf{x}}\right)\right]=u(t, x)+\mathbb{E} \int_{0}^{r}\left(\partial_{t}+\mathcal{L}_{\sigma}\right) u\left(s+t, \Lambda_{s}^{\mathbf{x}}\right) d s
$$

Letting $r \rightarrow+\infty$ and changing variable we get (2.9).
Let $T>0$ be fixed and recall that $\mathscr{L}_{\sigma}=\partial_{t}+\mathcal{L}_{\sigma}$. Theorem 1.1 will actually be a consequence of the following estimates on the strip

$$
\mathcal{S}:=[-T, T] \times \mathbb{R}^{N}
$$

Theorem 2.4 (Parabolic $L^{p}$ estimates on the $\left.\operatorname{strip} \mathcal{S}\right)$. For $p \in(1,+\infty)$, there exists $C_{p}:=C_{p}((\mathbf{A})) \geq 1$ independent of $T>0$ s.t. for all $u \in C_{0}^{\infty}\left((-T, T) \times \mathbb{R}^{N}\right), i \in \llbracket 1, n \rrbracket$, we have:

$$
\begin{equation*}
\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} u\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\left\|\mathscr{L}_{\sigma} u\right\|_{L^{p}(\mathcal{S})} \tag{2.14}
\end{equation*}
$$

Proof of Theorem [1.1. To show that Theorem 2.4 implies Theorem 1.1 we introduce $\psi \in C_{0}^{\infty}(\mathbb{R})$ with support in $(-1,1)$ and such that $\psi(s)=1$ for $s \in[-1 / 2,1 / 2]$. If $v \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ we consider

$$
\begin{equation*}
u(t, \mathbf{x}):=v(\mathbf{x}) \psi\left(\frac{t}{T}\right), \quad(t, \mathbf{x}) \in(-T, T) \times \mathbb{R}^{N} \tag{2.15}
\end{equation*}
$$

Since $\mathscr{L}_{\sigma} u(t, \mathbf{x})=\psi(t / T) \mathcal{L}_{\sigma} v(\mathbf{x})+\frac{1}{T} v(\mathbf{x}) \psi^{\prime}(t / T)$ we find from Theorem 2.4 applied to $u$ :

$$
\begin{gathered}
\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} u\right\|_{L^{p}(\mathcal{S})}^{p}=\int_{-T}^{T}|\psi(t / T)|^{p} d t \int_{\mathbb{R}^{N}}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} v(\mathbf{x})\right|^{p} d \mathbf{x}=T \int_{-1}^{1}|\psi(s)|^{p} d s \int_{\mathbb{R}^{N}}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} v(\mathbf{x})\right|^{p} d \mathbf{x} \\
\leq C_{p}^{p} \int_{-T}^{T} \int_{\mathbb{R}^{N}}\left|\psi(t / T) \mathcal{L}_{\sigma} v(\mathbf{x})+\frac{1}{T} v(\mathbf{x}) \psi^{\prime}(t / T)\right|^{p} d \mathbf{x} d t=C_{p}^{p} T \int_{-1}^{1} \int_{\mathbb{R}^{N}}\left|\psi(s) \mathcal{L}_{\sigma} v(\mathbf{x})+\frac{1}{T} v(\mathbf{x}) \psi^{\prime}(s)\right|^{p} d \mathbf{x} d s .
\end{gathered}
$$

It follows that

$$
\int_{-1}^{1}|\psi(s)|^{p} d s \int_{\mathbb{R}^{N}}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} v(\mathbf{x})\right|^{p} d \mathbf{x} \leq C_{p}^{p} \int_{-1}^{1} \int_{\mathbb{R}^{N}}\left|\psi(s) \mathcal{L}_{\sigma} v(\mathbf{x})+\frac{1}{T} v(\mathbf{x}) \psi^{\prime}(s)\right|^{p} d \mathbf{x} d s
$$

passing to the limit as $T \rightarrow \infty$ by the Lebesgue convergence theorem we get the assertion since $\int_{-1}^{1}|\psi(s)|^{p} d s>0$.

Remark 2.4. The fact that in the previous theorem the constant $C_{p}$ is independent on $T$ agrees with the singular integral estimates given in Section 3 of [BCM96] for $\mathcal{L}_{\sigma}$ when $\alpha=2$. On the other hand, the parabolic estimates of Theorem 3 in BCLP10 when considered on the strip $\mathcal{S}:=[-T, T] \times \mathbb{R}^{N}$ have a constant depending on $T$ since a more general matrix $A$ is considered in that paper (indeed the exponential matrix $e^{t A}$ can growth exponentially in BCLP10]). This is why the elliptic estimate in Theorem 1 of BCLP10 (see (1.12)) contains an extra term $\|v\|_{L^{p}\left(\mathbb{R}^{N}\right)}$ which is not present in the right-hand side of our estimates (1.11).

## 3. Strategy of the proof of Theorem 2.4

To prove Theorem 2.4. thanks to the formula (2.9), we restrict to consider functions of the form

$$
\begin{equation*}
u(t, \mathbf{x})=G f(t, \mathbf{x})=\int_{t}^{T} d s \int_{\mathbb{R}^{N}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) f(s, \mathbf{y}) d \mathbf{y},(t, \mathbf{x}) \in \mathcal{S} \tag{3.1}
\end{equation*}
$$

We study (3.1) when $f$ belongs to the space of test functions

$$
\begin{align*}
& \mathscr{T}\left(\mathbb{R}^{1+N}\right):=\left\{f \in C^{\infty}\left(\mathbb{R}^{1+N}\right): \exists R>0, \forall t \notin[-R, R], f(t, \cdot)=0, \quad \forall t \in[-R, R]\right. \\
& \left.f \text { and all spatial derivatives } \partial_{\mathbf{x}}^{\mathbf{i}} f \in \bigcap_{p \in[1,+\infty]} L^{p}\left(\mathbb{R}^{1+N}\right), \text { for all multi-indices i }\right\} . \tag{3.2}
\end{align*}
$$

Note that, for any $u \in C_{0}^{\infty}\left(\mathbb{R}^{1+N}\right)$,

$$
\begin{equation*}
\left(\partial_{t}+\mathcal{L}_{\sigma}\right) u \in \mathscr{T}\left(\mathbb{R}^{1+N}\right) \tag{3.3}
\end{equation*}
$$

(cf. Remark (2.2). With the notations preceding (1.10), we write for all $i \in \llbracket 1, n \rrbracket, B_{i}=\left(\begin{array}{c}0_{d_{1} \times d_{i}} \\ \vdots \\ I_{d_{i} \times d_{i}} \\ \vdots \\ 0_{d_{n} \times d_{i}}\end{array}\right)$. Recalling the definition of $\mathbb{M}_{t}$ in (2.6), we then get from (2.5), for all $i \in \llbracket 1, n \rrbracket$ and $\alpha_{i}=\frac{\alpha}{1+\alpha(i-1)}$ :

$$
\begin{array}{r}
\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A}\left(\mathbf{x}+B_{i} z\right)-\mathbf{y}\right)\right)-p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)\right. \\
\left.-\nabla_{\mathbf{x}_{i}}\left(p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)\right) \cdot z \mathbb{I}_{|z| \leq 1}\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)+(s-t)^{-(i-1)} e^{A} B_{i} z\right)-p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)\right. \\
\left.\left.-\nabla p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) \cdot\left(\mathbb{M}_{s-t}^{-1} e^{(s-t) A}\right) B_{i} z \mathbb{I}_{|z| \leq 1}\right)\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}
\end{array}
$$

$\mathbf{x}, \mathbf{y} \in \mathbb{R}^{N}, s>t$, where we have used that $\mathbb{M}_{s-t}^{-1} e^{(s-t) A} B_{i} z=e^{A} \mathbb{M}_{s-t}^{-1} B_{i} z$ (see (2.7)) and the fact that

$$
\begin{equation*}
\mathbb{M}_{s-t}^{-1} B_{i} z=(s-t)^{-(i-1)} B_{i} z, \quad, r>0, z \in \mathbb{R}^{d} \tag{3.4}
\end{equation*}
$$

In the sequel we set

$$
\left(e^{A}\right)_{i}=e^{A} B_{i}
$$

Introduce now for $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ and for all $i \in \llbracket 1, n \rrbracket, s>t$ the operator:

$$
\begin{equation*}
\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} \varphi(\mathbf{x}):=\int_{\mathbb{R}^{d_{i}}}\left(\varphi\left(\mathbf{x}+(s-t)^{-(i-1)}\left(e^{A}\right)_{i} z\right)-\varphi(\mathbf{x})-(s-t)^{-(i-1)} \nabla \varphi(\mathbf{x}) \cdot\left(e^{A}\right)_{i} z \mathbb{I}_{|z| \leq 1}\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \tag{3.5}
\end{equation*}
$$

We insist here on the fact that, in (3.5), $\nabla$ stands for the full gradient on $\mathbb{R}^{N}$. We thus get the correspondence:

$$
\begin{align*}
p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) & \left.=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}(s-t, \cdot)\right)\left(\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) \\
\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) & =\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)}\left(\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}(s-t, \cdot)\right)\left(\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) \tag{3.6}
\end{align*}
$$

Equation (3.6) reflects in particular how the effect of a stable operator on the $i^{\text {th }}$-variable propagates to the next variables. This correspondence allows to develop specific computations related to the stable process ( $S_{t}$ ) having a singular spectral measure. Formula (3.6) is meaningful since, for any $s>t, p_{S}(s-t, \cdot) \in C^{\infty}\left(\mathbb{R}^{N}\right) \cap L^{1}\left(\mathbb{R}^{N}\right)$ (this is a consequence of (2.13)). Moreover all the partial derivatives of $p_{S}(s-t, \cdot) \in L^{1}\left(\mathbb{R}^{N}\right)$. Arguing as in Remark 2.2 one can prove that $\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}(s-t, \cdot) \in L^{1}\left(\mathbb{R}^{N}\right) \cap C^{\infty}\left(\mathbb{R}^{N}\right)$. This gives in particular that for $f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right)$ the function $\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G f(t, \mathbf{x})$ is pointwise defined for all $(t, \mathbf{x}) \in \mathcal{S}$.

Additionally, by using Itô's formula (cf. the proof of Proposition 2.3) or Fourier analysis techniques it can be easily derived that for $f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right), G f$ solves the equation:

$$
\left\{\begin{array}{l}
\left(\partial_{t}+\mathcal{L}_{\sigma}\right) w(t, \mathbf{x})=-f(t, \mathbf{x}),(t, \mathbf{x}) \in \stackrel{\circ}{\mathcal{S}}  \tag{3.7}\\
w(T, \mathbf{x})=0
\end{array}\right.
$$

By (2.9) we know that $u=-G\left(\mathscr{L}_{\sigma} u\right)$ if $u \in C_{0}^{\infty}\left((-T, T) \times \mathbb{R}^{N}\right)$. Hence estimates (2.14) follows if we prove

$$
\begin{equation*}
\sum_{i=1}^{n}\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G f\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})}, \quad f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right) \tag{3.8}
\end{equation*}
$$

To prove estimate (3.8), we introduce for $i \in \llbracket 1, n \rrbracket$, the kernel $k_{i}((t, \mathbf{x}),(s, \mathbf{y})):=\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})$ so that:

$$
\begin{equation*}
K_{i} f(t, x):=\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G f(t, x)=\int_{t}^{T} d s \int_{\mathbb{R}^{N}} k_{i}((t, \mathbf{x}),(s, \mathbf{y})) f(s, \mathbf{y}) d \mathbf{y} \tag{3.9}
\end{equation*}
$$

The goal is to show $\sum_{i=1}^{n}\left\|K_{i} f\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})}$. But the kernels $\left(k_{i}\right)_{i \in \llbracket 1, n \rrbracket}$ are singular (see e.g. Lemma 4.3 below) and do not satisfy some a priori integrability conditions. We will establish (3.8) through uniform estimates on a truncated kernel in time and space. We need to introduce the following quasi-distance on $\mathcal{S}$.

Definition 3.1 (Quasi-distance on $\mathcal{S})$. $\operatorname{For}((t, \mathbf{x}),(s, \mathbf{y})) \in \mathcal{S}^{2}$, we introduce the quasi-distance:

$$
\begin{equation*}
d((t, \mathbf{x}),(s, \mathbf{y})):=\frac{1}{2}(\rho(t-s, \exp ((s-t) A) \mathbf{x}-\mathbf{y})+\rho(t-s, \mathbf{x}-\exp ((t-s) A) \mathbf{y})) \tag{3.10}
\end{equation*}
$$

where the homogeneous pseudo-norm $\rho$ has been defined in (2.2).
The above definition takes into account the transport of the first spatial point $\mathbf{x}$ by the matrix $e^{(s-t) A}$ (forward transport of the initial point) and the one of the second spatial point $\mathbf{y}$ by $e^{(t-s) A}$ (backward transport of the final point). By transport we actually intend here the action of the first order term in (1.4) (corresponding to the deterministic differential system $\left.\dot{\boldsymbol{\theta}}_{u}(\mathbf{z})=A \boldsymbol{\theta}_{u}(\mathbf{z}), \boldsymbol{\theta}_{0}(\mathbf{z})=\mathbf{z} \in \mathbb{R}^{N}\right)$ w.r.t. the considered associated times and points. Observe that the fact that $d$ is actually a quasi-distance, i.e. that it satisfies the quasitriangle inequality, is not obvious a priori. From the invariance by dilation of the operator $\mathscr{L}_{\sigma}$ established in Proposition 2.3 and the underlying group structure on $\mathbb{R}^{1+N}$ endowed with the composition law $(t, \mathbf{x}) \circ(\tau, \boldsymbol{\xi})=$ $\left(t+\tau, \boldsymbol{\xi}+e^{A \tau} \mathbf{x}\right)$, the quasi-triangle inequality can be derived similarly to [FP06] in the diffusive setting, see also [BCLP10]. In order to be self-contained, and to show that the quasi-distance property still holds without any underlying group structure, we anyhow provide a proof of this fact in Proposition C. 2 below.

Let us now introduce a non-singular Green kernel. We choose to truncate w.r.t. time. For $\varepsilon>0$ and a given $c_{0}>0$, we define for all $i \in \llbracket 1, n \rrbracket$ :

$$
\begin{align*}
k_{i, \varepsilon}((t, \mathbf{x}),(s, \mathbf{y})) & :=\mathbb{I}_{|s-t| \geq \varepsilon} \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) \\
& =\mathbb{I}_{|s-t| \geq \varepsilon} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}} \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})+\mathbb{I}_{|s-t| \geq \varepsilon} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y}))>c_{0}} \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) \\
& =: k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))+k_{i, \varepsilon}^{F}((t, \mathbf{x}),(s, \mathbf{y})) \tag{3.11}
\end{align*}
$$

$$
K_{i, \varepsilon} f(t, x):=\int_{t}^{T} d s \int_{\mathbb{R}^{N}} k_{i, \varepsilon}((t, \mathbf{x}),(s, \mathbf{y})) f(s, \mathbf{y}) d \mathbf{y}, \quad f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right)
$$

Accordingly, the operators $K_{i, \varepsilon}^{C} f(t, x)$ and $K_{i, \varepsilon}^{F} f(t, x)$ are obtained replacing $k_{i, \varepsilon}$ by $k_{i, \varepsilon}^{C}$ and $k_{i, \varepsilon}^{F}$ in (3.12). Observe that $K_{i, \varepsilon}^{C}$ (resp. $K_{i, \varepsilon}^{F}$ ) is concerned with the integrating points that are close (resp. far) from the initial point with respect to the underlying quasi-distance in (3.10). Similarly, we denote by $G_{\varepsilon} f(t, \mathbf{x})$ the quantity obtained replacing $t$ by $t+\varepsilon$ in (3.1). Since

$$
\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G_{\varepsilon} f\right\|_{L^{p}(\mathcal{S})}=\left\|K_{i, \varepsilon} f\right\|_{L^{p}(\mathcal{S})} \leq\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{p}(\mathcal{S})}+\left\|K_{i, \varepsilon}^{F} f\right\|_{L^{p}(\mathcal{S})}
$$

the result (3.8) will follow from weak convergence arguments, provided that the following lemma holds.
Lemma 3.2 (Key Lemma). There exists a constant $C_{p}>0$ independent of $\varepsilon>0$ and $T>0$ such that for all $f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right)$ :

$$
\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{p}(\mathcal{S})}+\left\|K_{i, \varepsilon}^{F} f\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})}
$$

We prove this estimate separately for $K_{i, \varepsilon}^{C} f$ and $K_{i, \varepsilon}^{F} f$ in Section 5 below. For the latter, a direct argument can be used whereas for $K_{i, \varepsilon}^{C} f$, some controls from singular integral theory are required. Precisely, we aim to use Theorem 2.4, Chapter III in CW71] (see TheoremC.1). The choice to split the kernel $k_{i, \varepsilon}$ into $k_{i, \varepsilon}^{C}+k_{i, \varepsilon}^{F}$ is then motivated by the fact that even though for all $\varepsilon>0, k_{\varepsilon} \in L^{1}(\mathcal{S})$ when integrating w.r.t. $d t d \mathbf{x}$ or $d s d \mathbf{y}$ we do not have that $k_{i, \varepsilon} \in L^{2}\left(\mathcal{S}^{2}\right)$ which is the assumption required in the quoted reference. This is what induces us to introduce a spatial truncation to get the joint integrability in all the variables.

## 4. Technical Lemmas

We now give two global results that will serve several times for the truncated kernel as well. These lemmas are the current technical core of the paper. Lemma 4.1 is a global $L^{2}$ bound on the singular kernel $\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G_{\varepsilon} f$ which is based on Fourier arguments and the representation formula in (2.8). Lemma 4.2 is a key tool to control singular kernels (see Appendix C in the framework of homogeneous spaces).

Lemma 4.1 (Global $L^{2}$ estimate). There exists a positive constant $C_{2}:=C_{2}((\mathbf{A}))$ such that, for all $\varepsilon>0$, $i \in \llbracket 1, n \rrbracket$, and for all $f \in L^{2}\left(\mathbb{R}^{1+N}\right)$,

$$
\left\|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} G_{\varepsilon} f\right\|_{L^{2}(\mathcal{S})} \leq C_{2}\|f\|_{L^{2}(\mathcal{S})}
$$

The constant $C_{2}$ does not depend on $T>0$ considered in the strip $\mathcal{S}$. Also, this estimate would hold under weaker assumptions than (ND). No symmetry would a priori be needed, a control similar to (1.3) for the realpart should be enough. It would also hold for a wider class of initial operators $L_{\sigma}$ including those associated with tempered or truncated stable processes. The result seems to be new even in the limit local case $\alpha=2$.

Lemma 4.2 (Deviation Controls). There exist constants $K:=K((\mathbf{A})), C:=C((\mathbf{A})) \geq 1$ s.t. for all $(\sigma, \boldsymbol{\xi}),(t, \mathbf{x}) \in \mathcal{S}$ the following control holds, for all $i \in \llbracket 1, n \rrbracket$ :

$$
\begin{equation*}
\int_{s \geq t \vee \sigma, \rho \geq K \gamma}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-\sigma, \boldsymbol{\xi}, \mathbf{y})\right| d \mathbf{y} d s \leq C \tag{4.1}
\end{equation*}
$$

where we have denoted $\rho:=\rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right), \gamma:=\rho\left(\sigma-t, e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)$.
4.1. Proof of Lemma 4.1. We start from the representation of the density obtained in Proposition 2.3 .

$$
\begin{aligned}
p_{\Lambda}(t, \mathbf{x}, \mathbf{y}) & =\frac{\operatorname{det}\left(\mathbb{M}_{t}^{-1}\right)}{(2 \pi)^{N}} \int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbb{M}_{t}^{-1}\left(\mathbf{y}-e^{t A} \mathbf{x}\right), \mathbf{p}\right\rangle\right) \exp \left(-t \int_{\mathbb{S}^{N-1}}|\langle\mathbf{p}, \boldsymbol{\xi}\rangle|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) d \mathbf{p} \\
& =\frac{1}{(2 \pi)^{N}} \int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbf{q}, \mathbf{x}-e^{-t A} \mathbf{y}\right\rangle\right) \exp \left(-t \int_{\mathbb{S}^{N-1}}\left|\left\langle\mathbb{M}_{t} e^{-t A^{*}} \mathbf{q}, \boldsymbol{\xi}\right\rangle\right|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) d \mathbf{q}
\end{aligned}
$$

recalling that the specific form of $A$ yields $\operatorname{det}\left(e^{t A^{*}}\right)=\operatorname{det}\left(e^{t A}\right)=1$. Let us fix $j \in \llbracket 1, n \rrbracket$ and prove the estimate for $\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f$. We can compute, for $f \in \mathscr{S}\left(\mathbb{R}^{1+N}\right)$ (Schwartz class of $\left.\mathbb{R}^{1+N}\right)$, the Fourier transform:

$$
\boldsymbol{\zeta} \in \mathbb{R}^{N} \mapsto \mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\int_{\mathbb{R}^{N}} e^{i\langle\zeta, \mathbf{x}\rangle} \Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f(t, \mathbf{x}) d \mathbf{x}, t \in[-T, T] .
$$

Indeed, from the comments after (3.6) and by the Young inequality we have that $\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f(t, \cdot) \in L^{1}\left(\mathbb{R}^{N}\right) \cap$ $L^{2}\left(\mathbb{R}^{N}\right), t \in[-T, T]$. For all $(t, \boldsymbol{\zeta}) \in \mathcal{S}$ with $t+\epsilon \leq T$ we get from the definition of $G_{\varepsilon} f$ following (3.12):

$$
\begin{aligned}
& \mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \mathcal{F}\left(G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{\mathbb{R}^{N}} \exp (-i\langle\boldsymbol{\zeta}, \mathbf{x}\rangle)\left(\int_{t+\varepsilon}^{T} \int_{\mathbb{R}^{N}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) f(s, \mathbf{y}) d \mathbf{y} d s\right) d \mathbf{x} \\
&=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{\mathbb{R}^{N}} \exp (-i\langle\boldsymbol{\zeta}, \mathbf{x}\rangle)\left(\int_{t+\varepsilon}^{T} \int_{\mathbb{R}^{N}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) f(s, \mathbf{y}) d \mathbf{y} d s\right) d \mathbf{x}
\end{aligned}
$$

using equation (2.5) for the last identity. Rewrite now

$$
\begin{gathered}
\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \mathbb{M}_{s-t}^{-1} e^{(s-t) A} \mathbf{x}\right\rangle\right) \\
\quad\left(\int_{t+\varepsilon}^{T} \int_{\mathbb{R}^{N}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) f(s, \mathbf{y}) d \mathbf{y} d s\right) d \mathbf{x}
\end{gathered}
$$

Using the Fubini theorem yields:

$$
\begin{array}{r}
\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t+\varepsilon}^{T} \int_{\mathbb{R}^{N}} \exp \left(-i\left\langle e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \mathbf{y}\right) f(s, \mathbf{y})\right. \\
\left(\int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right\rangle\right) \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right) d \mathbf{x}\right) d \mathbf{y} d s \\
=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}}\left(\int _ { t + \varepsilon } ^ { T } \int _ { \mathbb { R } ^ { N } } \operatorname { e x p } \left(-i\left\langle e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \mathbf{y}\right) f(s, \mathbf{y})\left(\int_{\mathbb{R}^{N}} \exp \left(-i\left\langle\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \tilde{\mathbf{x}}\right\rangle\right) p_{S}(s-t, \tilde{\mathbf{x}}) d \tilde{\mathbf{x}}\right) d \mathbf{y} d s,\right.\right.
\end{array}
$$

setting $\tilde{\mathbf{x}}=\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)$ and recalling that $\operatorname{det}\left(e^{(s-t) A}\right)=1$ for the last identity. We finally get

$$
\begin{array}{r}
\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t+\varepsilon}^{T} \mathcal{F}(f)\left(s, e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right) \mathcal{F}\left(p_{S}\right)\left(s-t, \mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right) d s \\
=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t+\varepsilon}^{T} \mathcal{F}(f)\left(s, e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right) \exp \left(-(s-t) \int_{\mathbb{S}^{N-1}}\left|\left\langle\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}, \boldsymbol{\xi}\right\rangle\right|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) d s,
\end{array}
$$

where $\left(\mathcal{F}(f)(s, \cdot), \mathcal{F}\left(p_{S}\right)(s-t, \cdot)\right.$ denote the Fourier transforms of $f(s, \cdot), p_{S}(s-t, \cdot)$.

Let us now compute $\left\|\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)\right\|_{L^{2}(\mathcal{S})}$. From the non degeneracy of $\mu_{S}$, we have:

$$
\begin{equation*}
\left|\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)(t, \boldsymbol{\zeta})\right| \leq C\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T}\left|\mathcal{F}(f)\left(s, e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right)\right| \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d s \tag{4.2}
\end{equation*}
$$

For the $L^{2}$ norm of $\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G f\right)$, using the Cauchy-Schwarz inequality, we obtain:

$$
\begin{array}{r}
\|\quad\| \mathcal{F}\left(\Delta_{-T}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right) \|_{L^{2}(\mathcal{S})}^{2} d t \int_{\mathbb{R}^{N}}\left(\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T}\left|\mathcal{F}(f)\left(s, e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right)\right|^{2} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d s\right) \\
\times\left(\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d s\right) d \boldsymbol{\zeta}
\end{array}
$$

Now formula (2.7) yields that: $e^{-(s-t) A^{*}}=\mathbb{M}_{s-t}^{-1} e^{-A^{*}} \mathbb{M}_{s-t}$, where $e^{-A^{*}}$ is non-degenerate. Thus, there exists $c=c(A)>0$ s.t. for all $T \geq s \geq t \geq-T, \zeta \in \mathbb{R}^{N}$ :

$$
\begin{array}{r}
(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha} \geq c(s-t)\left|\mathbb{M}_{s-t} \boldsymbol{\zeta}\right|^{\alpha} \geq c(s-t)^{1+\alpha(j-1)}\left|\boldsymbol{\zeta}_{j}\right|^{\alpha}, \text { and } \\
\leq C \int_{-T}^{T} d t \int_{\mathbb{R}^{N}}\left(\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T} \left\lvert\, \mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)\right. \|_{L^{2}(\mathcal{S})}^{2}\right. \\
\left.(4.3) \quad \Theta_{j}\left(t, T, \boldsymbol{\zeta}_{j}\right):=\left.\left(\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T} \exp \left(-C^{-1}(s-t)^{1+\alpha(j-1)}\left|\boldsymbol{\zeta}_{j}\right|^{\alpha}\right) d s\right)\right|^{2} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d s\right) \Theta_{j}\left(t, T, \boldsymbol{\zeta}_{j}\right) d \boldsymbol{\zeta}
\end{array}
$$

Let us prove that $\Theta_{j}\left(t, T, \boldsymbol{\zeta}_{j}\right)$ is bounded. Write for $\left|\boldsymbol{\zeta}_{j}\right| \neq 0$, changing variable, recalling that $\alpha_{j}=\frac{\alpha}{1+\alpha(j-1)}$ :

$$
\begin{aligned}
& \Theta_{j}\left(t, T, \boldsymbol{\zeta}_{j}\right) \leq\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{0}^{\infty} \exp \left(-C^{-1}\left[u\left|\boldsymbol{\zeta}_{j}\right|^{\frac{\alpha}{1+\alpha(j-1)}}\right]^{1+\alpha(j-1)}\right) d u \\
& \quad=\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \frac{1}{\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}}} \int_{0}^{\infty} \exp \left(-C^{-1} v^{1+\alpha(j-1)}\right) d v=C_{0}<\infty
\end{aligned}
$$

We eventually get from (4.3) by the Fubini theorem

$$
\begin{array}{r}
\| C \int_{-T}^{T} d t \int_{\mathbb{R}^{N}}\left(\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}} \int_{t}^{T} \left\lvert\, \mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)\right. \|_{L^{2}(\mathcal{S})}^{2}\right. \\
\left.\quad=\int_{-T}^{T} d s \int_{-T}^{s} d t \int_{\mathbb{R}^{N}}\left|\boldsymbol{\zeta}_{j}\right|^{\alpha_{j}}\left|\mathcal{F}(f)\left(s, e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right)\right|^{2} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d s\right) d \boldsymbol{\zeta} \\
\quad \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} e^{-(s-t) A^{*}} \boldsymbol{\zeta}\right|^{\alpha}\right) d \boldsymbol{\zeta}
\end{array}
$$

Setting $\mathbf{q}=e^{-(s-t) A^{*}} \boldsymbol{\zeta}$ in the space integral now yields:

$$
\begin{aligned}
\left\|\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)\right\|_{L^{2}(\mathcal{S})}^{2} & \leq C \int_{-T}^{T} d s \int_{-T}^{s} d t \int_{\mathbb{R}^{N}}\left|\left(e^{(s-t) A^{*}} \mathbf{q}\right)_{j}\right|^{\alpha_{j}}|\mathcal{F}(f)(s, \mathbf{q})|^{2} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} \mathbf{q}\right|^{\alpha}\right) d \mathbf{q} \\
& \leq C \int_{-T}^{T} d s \int_{\mathbb{R}^{N}}|\mathcal{F}(f)(s, \mathbf{q})|^{2} d \mathbf{q} \int_{-T}^{s}\left|\left(e^{(s-t) A^{*}} \mathbf{q}\right)_{j}\right|^{\alpha_{j}} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} \mathbf{q}\right|^{\alpha}\right) d t \\
& \leq C \int_{-T}^{T} d s \int_{\mathbb{R}^{N}}|\mathcal{F}(f)(s, \mathbf{q})|^{2} \bar{\Theta}_{j}(s, T, \mathbf{q}) d \mathbf{q}
\end{aligned}
$$

with $\bar{\Theta}_{j}(s, T, \mathbf{q})=\int_{-T}^{s}\left|\left(e^{(s-t) A^{*}} \mathbf{q}\right)_{j}\right|^{\alpha_{j}} \exp \left(-C^{-1}(s-t)\left|\mathbb{M}_{s-t} \mathbf{q}\right|^{\alpha}\right) d t$. Now indicating with $\mathbf{q}^{*}$ the row vector we have (see (2.7))

$$
\begin{array}{r}
\left|\left(e^{r A^{*}} \mathbf{q}\right)_{j}\right|=\left|B_{j}^{*} e^{r A^{*}}\left[\left(\mathbf{q}^{*}\right)^{*}\right]\right|=\left|\left(\mathbf{q}^{*} e^{r A} B_{j}\right)^{*}\right|=\left|\mathbf{q}^{*} e^{r A} B_{j}\right| \\
=\left|\mathbf{q}^{*} \mathbb{M}_{r} e^{A} \mathbb{M}_{r}^{-1} B_{j}\right|=r^{-(j-1)}\left|\mathbf{q}^{*} \mathbb{M}_{r} e^{A} B_{j}\right|=r^{-(j-1)}\left|\left[\mathbf{q}_{1}, r \mathbf{q}_{2}, \ldots, r^{n-1} \mathbf{q}_{n}\right]^{*} e^{A} B_{j}\right|  \tag{4.4}\\
\leq c r^{-(j-1)}\left(r^{j-1}\left|\mathbf{q}_{j}\right|+r^{j}\left|\mathbf{q}_{j+1}\right|+\ldots+r^{n-1}\left|\mathbf{q}_{n}\right|\right)=c \sum_{k=j}^{n} r^{k-j}\left|\mathbf{q}_{k}\right|, \quad r>0
\end{array}
$$

since $B_{j}=\left(\begin{array}{c}0_{d_{1} \times d_{j}} \\ \vdots \\ I_{d_{j} \times d_{j}} \\ \vdots \\ 0_{d_{n} \times d_{j}}\end{array}\right), e^{A} B_{j}=\left(e^{A}\right)_{j}=\left(\begin{array}{c}0_{d_{1} \times d_{j}} \\ \vdots \\ 0_{d_{j-1} \times d_{j}} \\ K_{j, j}(A) \\ \vdots \\ K_{n, j}(A)\end{array}\right)$ for some $K_{h, j}(A) \in \mathbb{R}^{d_{h}} \otimes \mathbb{R}^{d_{j}}, h=j, \ldots, n$. We get

$$
\begin{aligned}
\bar{\Theta}_{j}(s, T, \mathbf{q}) & \leq C \sum_{k=j}^{n} \int_{-T}^{s}\left|(s-t)^{(k-j)} \mathbf{q}_{k}\right|^{\alpha_{j}} \exp \left(-C^{-1}(s-t)^{1+\alpha(k-1)}\left|\mathbf{q}_{k}\right|^{\alpha}\right) d t \\
& \leq C \sum_{k=j}^{n} \int_{0}^{\infty} u^{(k-j) \alpha_{j}}\left|\mathbf{q}_{k}\right|^{\alpha_{j}} \exp \left(-C^{-1}\left[u \cdot\left|\mathbf{q}_{k}\right|^{\alpha_{k}}\right]^{1+\alpha(k-1)}\right) d u
\end{aligned}
$$

for $\left|\mathbf{q}_{k}\right| \neq 0$, recalling $\alpha_{k}=\frac{\alpha}{1+\alpha(k-1)}$. Setting $u \cdot\left|\mathbf{q}_{k}\right|^{\alpha_{k}}=v$ in each integral we find

$$
\bar{\Theta}_{j}(s, T, \mathbf{q}) \leq C \sum_{k=j}^{n}\left|\mathbf{q}_{k}\right|^{\alpha_{j}-\alpha_{k}-(k-j) \alpha_{j} \alpha_{k}} \int_{0}^{\infty} v^{(k-j) \alpha_{j}} \exp \left(-C^{-1}[v]^{1+\alpha(k-1)}\right) d v \leq n C_{1}<\infty
$$

since $\alpha_{j}-\alpha_{k}-(k-j) \alpha_{j} \alpha_{k}=0$, for any $j \leq k \leq n$. We eventually get:

$$
\left\|\mathcal{F}\left(\Delta_{\mathbf{x}_{j}}^{\frac{\alpha_{j}}{2}} G_{\varepsilon} f\right)\right\|_{L^{2}(\mathcal{S})}^{2} \leq C \int_{-T}^{T} \int_{\mathbb{R}^{N}}|\mathcal{F}(f)(s, \mathbf{q})|^{2} d \mathbf{q} d s=C\|\mathcal{F}(f)\|_{L^{2}(\mathcal{S})}^{2}
$$

The assertion now follows for $f \in \mathscr{S}\left(\mathbb{R}^{1+N}\right)$ from Plancherel's lemma. The result for $f \in L^{2}\left(\mathbb{R}^{1+N}\right)$ is derived by density.
4.2. Proof of Lemma 4.2. To establish Lemma 4.2, we will thoroughly exploit the important relation (2.5) for the marginals between the degenerate Ornstein-Uhlenbeck process $\Lambda^{\mathbf{x}}$ and the non degenerate $\mathbb{R}^{N}$-valued stable process $S$ introduced in Remark 2.3. Setting

$$
\begin{equation*}
\rho:=\rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right), \gamma:=\rho\left(\sigma-t, e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right) \tag{4.5}
\end{equation*}
$$

we focus for $i \in \llbracket 1, n \rrbracket$ on the quantities:

$$
\begin{align*}
I_{i} & :=\int_{s \geq t \vee \sigma, \rho \geq K \gamma}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{\mathbf{x}_{i}}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{\mathbf{x}_{i}}} p_{\Lambda}(s-\sigma, \boldsymbol{\xi}, \mathbf{y})\right| d \mathbf{y} d s \\
& =\int_{s \geq t \vee \sigma, \rho \geq K \gamma} \left\lvert\, \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)\right. \\
& \left.-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)} p_{S}\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right) \right\rvert\, d \mathbf{y} d s \tag{4.6}
\end{align*}
$$

(cf. Proposition 2.3 and equation (2.5) for the last identity). Recalling the important correspondence (3.6), the quantity $I_{i}$ in (4.6) then rewrites:

$$
\begin{align*}
& I_{i}=\int_{s \geq t \vee \sigma, \rho \geq K \gamma} \\
& \quad=\int_{\rho \geq K \gamma}\left|\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)}-\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-\sigma)}^{2}\right.}\right| d \mathbf{y} d s \\
&+\int_{s \geq t \vee \sigma, \rho \geq K \gamma}\left|\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)}-\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)}\right| d \mathbf{y} d s \\
& \quad(4.7) \tag{4.7}
\end{align*}
$$

Hence, to prove that $I_{i}$ is bounded we need to investigate the time and space sensitivities of $\Delta^{\frac{\alpha_{i}}{2}, A, i, \cdot} p_{S}$. This is the purpose of the next subsection.
4.2.1. Preliminary Estimates. We begin with the following result.

Lemma 4.3 (Bounds and Sensitivities of the Stable Singular Kernel). Let $\left(S_{t}\right)_{t \geq 0}$ be a symmetric $\alpha$-stable process in $\mathbb{R}^{N}$ with non degenerate Lévy measure $\nu_{S}$, i.e. its spectral measure $\mu_{S}$ satisfies that there exists $\eta \geq 1$ s.t. for all $\mathbf{p} \in \mathbb{R}^{N}$ :

$$
\eta^{-1}|\mathbf{p}|^{\alpha} \leq \int_{\mathbb{S}^{N}-1}|\langle\mathbf{p}, \mathbf{s}\rangle|^{\alpha} \mu_{S}(d \mathbf{s}) \leq \eta|\mathbf{p}|^{\alpha} .
$$

$\alpha \in(0,2)$. This condition amounts to say that $\left(S_{t}\right)_{t \geq 0}$ satisfies assumption (ND) in dimension $N$. In particular, this implies that for all $t>0, S_{t}$ has a smooth density that we denote by $p_{S}(t, \cdot)$ (cf. Remark (2.3).

There exists a family of probability densities $(q(t, \cdot))_{t>0}$ on $\mathbb{R}^{N}$ such that $q(t, \mathbf{x})=t^{-N / \alpha} q\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right), t>0$, $\mathbf{x} \in \mathbb{R}^{N}$, for all $\delta \in[0, \alpha)$, there exists a constant $C_{\delta}:=C_{\delta}((\mathbf{A}))>0$ s.t.

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} q(t, \mathbf{x})|\mathbf{x}|^{\delta} d \mathbf{x} \leq C_{\delta} t^{\frac{\delta}{\alpha}}, \quad t>0 \tag{4.8}
\end{equation*}
$$

and the following controls hold:
(i) There exists $C:=C((\mathbf{A}))$ s.t. for all $i \in \llbracket 1, n \rrbracket$ and $t>0, \mathbf{x} \in \mathbb{R}^{N}$ :

$$
\begin{equation*}
\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})\right| \leq \frac{C}{t} q(t, \mathbf{x}) \tag{4.9}
\end{equation*}
$$

(ii) For all $\beta \in(0,1]$, there exists $C:=C(\beta,(\mathbf{A}))$ s.t. for all $i \in \llbracket 1, n \rrbracket$ and $t>0,\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in \mathbb{R}^{2 N}$ :

$$
\begin{equation*}
\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left[q(t, \mathbf{x})+q\left(t, \mathbf{x}^{\prime}\right)\right] \tag{4.10}
\end{equation*}
$$

(iii) There exists $C:=C((\mathbf{A}))$ s.t. for all $i \in \llbracket 1, n \rrbracket$ and $t>0, \mathbf{x} \in \mathbb{R}^{N}$ :

$$
\begin{equation*}
\left|\partial_{t} \Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})\right| \leq \frac{C}{t^{2}} q(t, \mathbf{x}) \tag{4.11}
\end{equation*}
$$

Remark 4.1. From now on, for the family of stable densities $(q(t, \cdot))_{t>0}$, we also use the notation $q(\cdot):=q(1, \cdot)$, i.e. without any specified argument $q(\cdot)$ stands for the density $q$ at time 1 .

Proof. It is enough to find a suitable $q$ for each estimate (4.9), (4.10) and (4.11); summing up such densities one gets the required final $q$.

Let us first write for all $i \in \llbracket 1, n \rrbracket($ cf. (3.5)):

$$
\begin{array}{r}
\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})=\int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
=\int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right) \mathbb{I}_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
+\int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right) \mathbb{I}_{|z|>t^{\frac{1}{\alpha_{i}}}} \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
=: \Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})+\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}(t, \mathbf{x}) \tag{4.12}
\end{array}
$$

where $\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s}$ (resp. $\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l}$ ) corresponds to the small jumps (resp. to the large jumps) part of $\Delta^{\frac{\alpha_{i}}{2}, A, i, t}$.

Let us recall that, for a given fixed $t>0$, we can use an Itô-Lévy decomposition at the associated characteristic stable time scale (i.e. the truncation is performed at the threshold $t^{\frac{1}{\alpha}}$ ) to write $S_{t}:=M_{t}+N_{t}$ where $M_{t}$ and $N_{t}$ are independent random variables (we are considering a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ on which the process $S=\left(S_{s}\right)_{s \geq 0}$ is defined; $\mathbb{E}$ denotes the associated expectation). More precisely,

$$
\begin{equation*}
N_{s}=\int_{0}^{s} \int_{|x|>t^{\frac{1}{\alpha}}} x P(d u, d x), \quad M_{s}=S_{s}-N_{s}, \quad s \geq 0 \tag{4.13}
\end{equation*}
$$

where $P$ is the Poisson random measure associated with the process $S$; for the considered fixed $t>0, M_{t}$ and $N_{t}$ correspond to the small jumps part and large jumps part respectively. A similar decomposition has been already used in Wat07, Szt10 and HM16. It is useful to note that the cutting threshold in (4.13) precisely yields for the considered $t>0$ that:

$$
\begin{equation*}
N_{t} \stackrel{(\text { law })}{=} t^{\frac{1}{\alpha}} N_{1} \text { and } M_{t} \stackrel{(\text { law })}{=} t^{\frac{1}{\alpha}} M_{1} . \tag{4.14}
\end{equation*}
$$

To check the assertion about $N$ we start with

$$
\mathbb{E}\left[e^{i\left\langle\mathbf{p}, N_{t}\right\rangle}\right]=\exp \left(t \int_{\mathbb{S}^{N-1}} \int_{t^{\frac{1}{\alpha}}}^{\infty}(\cos (\langle\mathbf{p}, r \boldsymbol{\xi}\rangle)-1) \frac{d r}{r^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right), \mathbf{p} \in \mathbb{R}^{N}
$$

(see (1.2) and [Sat05). Changing variable $\frac{r}{t^{\frac{1}{\alpha}}}=s$ we get that $\mathbb{E}\left[e^{i\left(\mathbf{p}, N_{t}\right\rangle}\right]=\mathbb{E}\left[e^{i\left(\mathbf{p}, t^{\frac{1}{\alpha}} N_{1}\right\rangle}\right]$ for any $\mathbf{p} \in \mathbb{R}^{N}$ and this shows the assertion (similarly we get the statement for $M$ ). The density of $S_{t}$ then writes

$$
\begin{equation*}
p_{S}(t, \mathbf{x})=\int_{\mathbb{R}^{N}} p_{M}(t, \mathbf{x}-\boldsymbol{\xi}) P_{N_{t}}(d \boldsymbol{\xi}), \tag{4.15}
\end{equation*}
$$

where $p_{M}(t, \cdot)$ corresponds to the density of $M_{t}$ and $P_{N_{t}}$ stands for the law of $N_{t}$. From Lemma A. 2 (see as well Lemma B. 1 in H16]), $p_{M}(t, \cdot)$ belongs to the Schwartz class $\mathscr{S}\left(\mathbb{R}^{N}\right)$ and satisfies that for all $m \geq 1$ and all multi-index $\mathbf{i}=\left(i^{1}, \cdots, i^{N}\right) \in \mathbb{N}^{N},|\mathbf{i}|:=\sum_{j=1}^{N} i_{j} \leq 3$, there exists $C_{m, \mathbf{i}}$ s.t. for all $(t, \mathbf{x}) \in \mathbb{R}_{+}^{*} \times \mathbb{R}^{N}$ :

$$
\begin{equation*}
\left|\partial_{\mathbf{x}}^{\mathbf{i}} p_{M}(t, \mathbf{x})\right| \leq \frac{\bar{C}_{m, \mathbf{i}}}{t^{\frac{\mathbf{i}}{\alpha}}} p_{\bar{M}}(t, \mathbf{x}), \text { where } p_{\bar{M}}(t, \mathbf{x}):=\frac{C_{m}}{t^{\frac{N}{\alpha}}}\left(1+\frac{|\mathbf{x}|}{t^{\frac{1}{\alpha}}}\right)^{-m} \tag{4.16}
\end{equation*}
$$

where the above modification of the constant is performed in order that $p_{\bar{M}}(t, \cdot)$ be a probability density. Note that the asymptotic decay of $p_{\bar{M}}$ here depends on on the integer $m$ considered. For our analysis, recalling from Remark 2.3 and equation (2.5) that we are disintegrating the density of a non degenerate stable process in dimension $N$, and that we are led to investigate sensitivities, which involve for the small jumps derivatives up to order 2 or 3 (depending on $\alpha \in(0,1)$ or $\alpha \in[1,2)$ ), see e.g. (4.27) below, we can fix

$$
m:=N+4
$$

Let us emphasize that, to establish the indicated results, as opposed to HM16, we only focus on integrability properties and not on pointwise density estimates. Our global approach therefore consists in exploiting (4.13), (4.15) and (4.16). The various sensitivities will be expressed through derivatives of $p_{M}(t, \cdot)$, which also gives the corresponding time singularities. However, as for general stable processes, the integrability restrictions come from the large jumps (here $N_{t}$ ) and only depend on its index $\alpha$. A crucial point then consists in observing that the convolution $\int_{\mathbb{R}^{N}} p_{\bar{M}}(t, \mathbf{x}-\boldsymbol{\xi}) P_{N_{t}}(d \boldsymbol{\xi})$ actually corresponds to the density of the random variable

$$
\begin{equation*}
\bar{S}_{t}:=\bar{M}_{t}+N_{t}, \quad t>0 \tag{4.17}
\end{equation*}
$$

(where $\bar{M}_{t}$ has density $p_{\bar{M}}(t,$.$) and is independent of N_{t}$; to have such decomposition one can define each $\bar{S}_{t}$ on a product probability space). Then, the integrability properties of $\bar{M}_{t}+N_{t}$, and more generally of all random variables appearing below, come from those of $\bar{M}_{t}$ and $N_{t}$.

One can easily check that $p_{\bar{M}}(t, \mathbf{x})=t^{-\frac{N}{\alpha}} p_{\bar{M}}\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right), t>0, \mathbf{x} \in \mathbb{R}^{N}$. Hence

$$
\bar{M}_{t} \stackrel{\text { law) }}{=} t^{\frac{1}{\alpha}} \bar{M}_{1}, \quad N_{t} \stackrel{\text { (law) }}{=} t^{\frac{1}{\alpha}} N_{1} .
$$

By independence of $\bar{M}_{t}$ and $N_{t}$, using the Fourier transform, one can easily prove that

$$
\begin{equation*}
\bar{S}_{t} \stackrel{\text { law) }}{=} t^{\frac{1}{\alpha}} \bar{S}_{1} . \tag{4.18}
\end{equation*}
$$

Moreover, $\mathbb{E}\left[\left|\bar{S}_{t}\right|^{\delta}\right]=\mathbb{E}\left[\left|\bar{M}_{t}+N_{t}\right|^{\delta}\right] \leq C_{\delta} t^{\frac{\delta}{\alpha}}\left(\mathbb{E}\left[\left|\bar{M}_{1}\right|^{\delta}\right]+\mathbb{E}\left[\left|N_{1}\right|^{\delta}\right]\right) \leq C_{\delta} t^{\frac{\delta}{\alpha}}, \delta \in(0, \alpha)$. This shows that the density of $\bar{S}_{t}$ verifies (4.8). We now give the details of the computations in case (ii). This case contains the main difficulties, the other ones can be derived similarly. Write for all $t>0,\left(\mathrm{x}, \mathrm{x}^{\prime}\right) \in \mathbb{R}^{2 N}$ (cf. (4.12)):

$$
\begin{array}{r}
\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}\left(t, \mathbf{x}^{\prime}\right) \\
=\int_{|z| \geq t^{\frac{1}{\alpha_{i}}}}\left[p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right] \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
-\left(p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right) \int_{|z| \geq t^{\frac{1}{\alpha_{i}}}} \frac{d z}{|z|^{d_{i}+\alpha_{i}}}, \\
\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \\
\leq\left(\int_{|z| \geq t^{\frac{1}{\alpha_{i}}}}\left|p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right| \frac{d z}{|z|^{d_{i}+\alpha_{i}}}\right) \\
+\left(\frac{C}{t}\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|\right)=:\left(I_{i, 1}+I_{2}\right)\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right) \tag{4.19}
\end{array}
$$

Assume for a while that the following control holds. For all $\beta \in(0,1]$ there exists a constant $C:=C_{\beta}$ s.t. for all $t>0,\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in \mathbb{R}^{2 N}$,

$$
\begin{equation*}
\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \tag{4.20}
\end{equation*}
$$

where $p_{\bar{S}}(t, \cdot)$ stands for the density of $\bar{S}_{t}$ which verifies (4.8). From (4.19) and (4.20) we readily derive:

$$
\begin{equation*}
\left|I_{2}\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right)\right| \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \tag{4.21}
\end{equation*}
$$

Also, still from (4.19) and (4.20),

$$
\begin{aligned}
\left|I_{i, 1}\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right)\right| & \leq C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta} \int_{|z| \geq t^{\frac{1}{\alpha_{i}}}}\left(p_{\bar{S}}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
& =: \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta} \int_{\mathbb{R}^{d_{i}}}\left(p_{\bar{S}}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) f_{\Gamma^{i}}(t, z)(d z)
\end{aligned}
$$

setting $f_{\Gamma^{i}}(t, z):=t c_{\alpha_{i}, d_{i}} \mathbb{I}_{|z| \geq t^{\frac{1}{\alpha_{i}}}} \frac{1}{|z|^{d_{i}+\alpha_{i}}}$ with $c_{\alpha, d_{i}}>0$ s.t. $\int_{\mathbb{R}^{d_{i}}} f_{\Gamma^{i}}(t, z) d z=1$. Hence, $f_{\Gamma^{i}}(t, \cdot)$ is the density of an $\mathbb{R}^{d_{i}}$-valued random variable $\Gamma_{t}^{i}$. The above integrals can thus be seen as the densities, at point $\mathbf{x}$ and $\mathbf{x}^{\prime}$ respectively, of the random variable

$$
\begin{equation*}
\bar{S}_{t}^{i, 1}:=\bar{S}_{t}+t^{-(i-1)}\left(e^{A}\right)_{i} \Gamma_{t}^{i} \tag{4.22}
\end{equation*}
$$

where $\bar{S}_{t}$ is as in (4.17) and $\Gamma_{t}^{i}$ is independent of $\bar{S}_{t}$ and has density $f_{\Gamma^{i}}(t, \cdot)$. Note that

$$
f_{\Gamma^{i}}(t, z)=c_{\alpha_{i}, d_{i}} \frac{\mathbb{I}}{\frac{|z|}{\frac{1}{\alpha_{i}}} \geq 1}\left(\frac{|z|}{t^{\frac{1}{\alpha_{i}}}}\right)^{-d_{i}-\alpha_{i}} t^{-\frac{d_{i}}{\alpha_{i}}}=t^{-\frac{d_{i}}{\alpha_{i}}} f_{\Gamma^{i}}\left(1, \frac{z}{t^{\frac{1}{\alpha_{i}}}}\right) .
$$

If we set $\tilde{\Gamma}_{t}^{i}:=\left(t^{-(i-1)}\right) \Gamma_{t}^{i}$ and denote by $f_{\tilde{\Gamma}^{i}}(t, \cdot)$ its density, we find

$$
f_{\tilde{\Gamma}^{i}}(t, z)=t^{d_{i}(i-1)} f_{\Gamma^{i}}\left(t, z t^{i-1}\right)=t^{d_{i}(i-1)} t^{-\frac{d_{i}}{\alpha_{i}}} f_{\Gamma^{i}}\left(1, z t^{i-1} / t^{\frac{1}{\alpha_{i}}}\right):=\frac{1}{t^{d_{i}\left(-(i-1)+\frac{1}{\alpha_{i}}\right)}} f_{\Gamma^{i}}\left(1, \frac{z}{t^{-(i-1)+\frac{1}{\alpha_{i}}}}\right)
$$

$z \in \mathbb{R}^{d_{i}}$. Since $\alpha_{i}=\frac{\alpha}{1+\alpha(i-1)}$, we have

$$
f_{\tilde{\Gamma}^{i}}(t, z)=\frac{1}{t^{\frac{d_{i}}{\alpha}}} f_{\Gamma^{i}}\left(1, \frac{z}{t^{\frac{1}{\alpha}}}\right) .
$$

It follows that $\left(e^{A}\right)_{i} \tilde{\Gamma}_{t}^{i} \stackrel{\text { law) }}{=} t^{\frac{1}{\alpha}}\left(e^{A}\right)_{i} \tilde{\Gamma}_{1}^{i}$. Hence arguing as for (4.18) we find

$$
\begin{equation*}
\bar{S}_{t}^{i, 1}:=\bar{S}_{t}+t^{-(i-1)}\left(e^{A}\right)_{i} \Gamma_{t}^{i} \stackrel{(\text { law })}{=} t^{\frac{1}{\alpha}} \bar{S}_{1}^{i, 1} \tag{4.23}
\end{equation*}
$$

and, moreover, for any $\delta \in(0, \alpha)$,

$$
\begin{equation*}
\mathbb{E}\left[\left|\bar{S}_{t}^{i, 1}\right|^{\delta}\right] \leq C_{\delta}\left(\mathbb{E}\left[\left|\bar{S}_{t}\right|^{\delta}\right]+C_{A} t^{-(i-1) \delta} \mathbb{E}\left[\left|\Gamma_{t}^{i}\right|^{\delta}\right]\right) \leq C_{\delta, A} t^{\frac{\delta}{\alpha}} \tag{4.24}
\end{equation*}
$$

as required in (4.8). We finally obtain,

$$
\begin{equation*}
\left|I_{i, 1}\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right)\right| \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}^{i}, 1}(t, \mathbf{x})+p_{\bar{S}^{i}, 1}\left(t, \mathbf{x}^{\prime}\right)\right) \tag{4.25}
\end{equation*}
$$

The control for $\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|$ follows plugging (4.25) and (4.21) into (4.19) defining $q(t, \cdot):=\frac{1}{n+1}\left(\sum_{i=1}^{n} p_{\bar{S}^{i}, 1}+p_{\bar{S}}\right)(t, \cdot)$.

It remains to control the difference associated with the small jumps part. We first recall that for any $\alpha=\alpha_{1} \in(0,2)$, we have that for $i \in \llbracket 2, n \rrbracket, \alpha_{i} \in(0,1)$. Also, we consider first for simplicity the case $\alpha_{1}=\alpha \in(0,1)$. Write then, using also (4.15),

$$
\begin{aligned}
& \Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right) \\
= & \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}}\left[\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right)-\left(p_{S}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right)\right] \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
= & \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{\mathbb{R}^{N}} \int_{0}^{1} d \mu\left(\nabla p_{M}\left(t, \mathbf{x}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z-\boldsymbol{\xi}\right)-\nabla p_{M}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z-\boldsymbol{\xi}\right)\right) \cdot t^{-(i-1)}\left(e^{A}\right)_{i} z \\
& \times P_{N_{t}}(d \boldsymbol{\xi}) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}
\end{aligned}
$$

In the sequel we will use (4.16) with $|\mathbf{i}|=2$ and the following inequality

$$
\begin{equation*}
p_{\bar{M}}(t, \mathbf{y}+\boldsymbol{\zeta}) \leq C_{m} p_{\bar{M}}(t, \mathbf{y}), \quad \text { if }|\boldsymbol{\zeta}| \leq 2 t^{\frac{1}{\alpha}}, \quad t>0, \mathbf{y}, \boldsymbol{\zeta} \in \mathbb{R}^{N} \tag{4.26}
\end{equation*}
$$

for some $C_{m}>0$. This can be easily proved considering separately the cases $|\mathbf{y}| \leq 4 t^{\frac{1}{\alpha}}$ and $|\mathbf{y}|>4 t^{\frac{1}{\alpha}}$ (if $|\mathbf{y}|>4 t^{\frac{1}{\alpha}}$ one can use $\frac{|\mathbf{y}+\zeta|}{t^{\frac{1}{\alpha}}} \geq \frac{|\mathbf{y}|-|\zeta|}{t^{\frac{1}{\alpha}}} \geq \frac{|\mathbf{y}|}{2 t^{\frac{1}{\alpha}}} ;$ if $|\mathbf{y}| \leq 4 t^{\frac{1}{\alpha}}$ one can use $1 \geq \frac{|\mathbf{y}|}{4 t^{\frac{1}{\alpha}}}$ ).

We derive if $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{\alpha}}$ :

$$
\begin{array}{r}
\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \\
\leq C_{m} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{2}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{\mathbb{R}^{N}} \int_{0}^{1} d \mu \int_{0}^{1}\left[p_{\bar{M}}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z+\lambda\left(\mathbf{x}-\mathbf{x}^{\prime}\right)-\boldsymbol{\xi}\right)\right] d \lambda P_{N_{t}}(d \boldsymbol{\xi})|z| t^{-(i-1)} \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
\leq C_{m} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{2}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{\mathbb{R}^{N}} p_{\bar{M}}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right) P_{N_{t}}(d \boldsymbol{\xi}) t^{-(i-1)}|z| \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \leq \frac{C_{m}}{t} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}} p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)  \tag{4.27}\\
\leq \frac{C_{m}}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta} p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right) .
\end{array}
$$

The second inequality follows from (4.26) taking $\mathbf{y}=\mathbf{x}^{\prime}-\boldsymbol{\xi}, \boldsymbol{\zeta}=\mu t^{-(i-1)}\left(e^{A}\right)_{i} z+\lambda\left(\mathbf{x}-\mathbf{x}^{\prime}\right)$, using the fact that on the considered set, i.e. $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{\alpha}},|z| \leq t^{\frac{1}{\alpha_{i}}}$, since $\alpha_{i}=\frac{\alpha}{1+\alpha(i-1)}$, we have that $t^{-(i-1)}\left|\left(e^{A}\right)_{i} z\right|+\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq 2 t^{\frac{1}{\alpha}}$.
We have exploited as well that:

$$
t^{-(i-1)} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \frac{|z|}{|z|^{d_{i}+\alpha_{i}}} d z \leq C_{\alpha, i} t^{-(i-1)} t^{-1+\frac{1}{\alpha_{i}}}=C_{\alpha, i} t^{-1+\frac{1}{\alpha}}
$$

If now $\left|\mathrm{x}-\mathrm{x}^{\prime}\right|>t^{\frac{1}{\alpha}}$, we derive from (4.16) (using again (4.26) as before):

$$
\begin{array}{r}
\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \\
\leq \frac{C_{m}}{t^{\frac{1}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{\mathbb{R}^{N}} \int_{0}^{1}\left(p_{\bar{M}}\left(t, \mathbf{x}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z-\boldsymbol{\xi}\right)+p_{\bar{M}}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z-\boldsymbol{\xi}\right)\right) d \mu P_{N_{t}}(d \boldsymbol{\xi}) \\
\times t^{-(i-1)}|z|_{|z|^{d_{i}+\alpha_{i}}} \leq \frac{d z}{t^{\frac{1}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{\mathbb{R}^{N}} \int_{0}^{1}\left(p_{\bar{M}}(t, \mathbf{x}-\boldsymbol{\xi})+p_{\bar{M}}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right) d \mu P_{N_{t}}(d \boldsymbol{\xi}) t^{-(i-1)}|z| \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
\leq \frac{C_{m}}{t}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \leq \frac{C_{m}}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) . \tag{4.28}
\end{array}
$$

Equations (4.27) and (4.28) give the stated control for $\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|$. This gives (ii) for $\alpha \in(0,1)$. The control (i) can be obtained following the same lines, without handling differences of starting
points. To handle the small jumps in the remaining case $i=1, \alpha_{1}=\alpha \in[1,2)$, a second order Taylor expansion is needed in the previous computations. Write, in short:

$$
\begin{align*}
& \Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right) \\
= & \int_{|z| \leq t^{\frac{1}{\alpha}}}\left[\left(p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{1} z\right)-p_{S}(t, \mathbf{x})-\nabla p_{S}\left(t, \mathbf{x}^{\prime}\right) \cdot\left(e^{A}\right)_{1} z\right)\right. \\
& \left.-\left(p_{S}\left(t, \mathbf{x}^{\prime}+\left(e^{A}\right)_{1} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}\right)-\nabla p_{S}\left(t, \mathbf{x}^{\prime}\right) \cdot\left(e^{A}\right)_{1} z\right)\right] \frac{d z}{|z|^{d+\alpha}} \\
= & \int_{|z| \leq t^{\frac{1}{\alpha}}} \int_{\mathbb{R}^{N}} \int_{0}^{1} d \mu(1-\mu) \\
& \left\langle\left(D^{2} p_{M}\left(t, \mathbf{x}+\mu\left(e^{A}\right)_{1} z-\boldsymbol{\xi}\right)-D^{2} p_{M}\left(t, \mathbf{x}^{\prime}+\mu\left(e^{A}\right)_{1} z-\boldsymbol{\xi}\right)\right)\left(e^{A}\right)_{1} z,\left(e^{A}\right)_{1} z\right\rangle \times P_{N_{t}}(d \boldsymbol{\xi}) \frac{d z}{|z|^{d+\alpha}} \tag{4.29}
\end{align*}
$$

Now, if $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{\alpha}}$, similarly to (4.27):

$$
\begin{array}{r}
\left|\Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \\
\leq C_{m} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{3}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha}}} \int_{\mathbb{R}^{N}} p_{\bar{M}}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right) P_{N_{t}}(d \boldsymbol{\xi})|z|^{2} \frac{d z}{|z|^{d+\alpha}} \leq \frac{C_{m}}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta} p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right) . \tag{4.30}
\end{array}
$$

If now $\left|\mathrm{x}-\mathrm{x}^{\prime}\right|>t^{\frac{1}{\alpha}}$, we derive from (4.29), (4.16) (using again (4.26) as before):

$$
\begin{array}{r}
\left|\Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{1}}{2}, A, 1, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \\
\leq \frac{C_{m}}{t^{\frac{2}{\alpha}}} \int_{|z| \leq t^{\frac{1}{\alpha}}} \int_{\mathbb{R}^{N}} \int_{0}^{1}(1-\mu)\left(p_{\bar{M}}\left(t, \mathbf{x}+\mu\left(e^{A}\right)_{1} z-\boldsymbol{\xi}\right)+p_{\bar{M}}\left(t, \mathbf{x}^{\prime}+\mu\left(e^{A}\right)_{1} z-\boldsymbol{\xi}\right)\right) d \mu P_{N_{t}}(d \boldsymbol{\xi}) \\
\times|z|^{2} \frac{d z}{|z|^{d+\alpha}} \leq \frac{C_{m}}{t}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \leq \frac{C_{m}}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) . \tag{4.31}
\end{array}
$$

Equations (4.30) and (4.31) complete the proof of (ii), (i) for $\alpha \in[1,2)$.
Let us now deal with (iii). We consider for simplicity $\alpha \in(0,1)$. The case $\alpha \in[1,2)$ could be handled as above considering an additional first order term in the integral (see (4.29) ). Write, for $i \in \llbracket 1, n \rrbracket, t>0, \mathbf{x} \in \mathbb{R}^{N}$ :

$$
\begin{aligned}
\partial_{t} \Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})= & \partial_{t}\left(\frac{1}{t^{(i-1) \alpha_{i}}} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{i} \tilde{z}\right)-p_{S}(t, \mathbf{x})\right) \frac{d \tilde{z}}{|\tilde{z}|^{d_{i}+\alpha_{i}}}\right) \\
= & -\frac{\left(\alpha_{i}(i-1)\right)}{t^{(i-1) \alpha_{i}+1}} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{i} \tilde{z}\right)-p_{S}(t, \mathbf{x})\right) \frac{d \tilde{z}}{|\tilde{z}|^{d_{i}+\alpha_{i}}} \\
& +\frac{1}{t^{(i-1) \alpha_{i}}} \int_{\mathbb{R}^{d_{i}}}\left(\partial_{t} p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{i} \tilde{z}\right)-\partial_{t} p_{S}(t, \mathbf{x})\right) \frac{d \tilde{z}}{|\tilde{z}|^{d_{i}+\alpha_{i}}}=:\left(E_{i, 1}+E_{i, 2}\right)(t, \mathbf{x})
\end{aligned}
$$

Since, $E_{i, 1}(t, \mathbf{x})=\frac{\alpha_{i}(1-i)}{t} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}=\frac{\alpha_{i}(1-i)}{t} \Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})$, point (i) readily gives:

$$
\begin{equation*}
\left|E_{i, 1}(t, \mathbf{x})\right| \leq \frac{C}{t^{2}} q(t, \mathbf{x}) \tag{4.33}
\end{equation*}
$$

To investigate $E_{i, 2}(t, \mathbf{x})$ note that $\partial_{t} p_{S}(t, z)=L_{S} p_{S}(t, z), t>0, \mathbf{z} \in \mathbb{R}^{N}$ (see, for instance, Kol00), where $L_{S}$ is the generator of $S$, namely, for $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$,

$$
\begin{equation*}
L_{S} \varphi(\mathbf{x})=\int_{\mathbb{R}^{N}}(\varphi(\mathbf{x}+\mathbf{z})-\varphi(\mathbf{x})) \nu_{S}(d \mathbf{z})=\int_{0}^{+\infty} \frac{d r}{r^{1+\alpha}} \int_{\mathbb{S}^{N-1}}(\varphi(\mathbf{x}+r \boldsymbol{\xi})-\varphi(\mathbf{x})) \tilde{\mu}_{S}(d \boldsymbol{\xi}), \mathbf{x} \in \mathbb{R}^{N} \tag{4.34}
\end{equation*}
$$

where $\tilde{\mu}_{S}=\frac{\mu_{S}}{C_{\alpha, N}}$ for a positive constant $C_{\alpha, N}$. We then rewrite from the definition in (4.32) (see also the comments on $p_{S}$ after (3.6)):

$$
\begin{aligned}
E_{i, 2}(t, \mathbf{x}) & =\frac{1}{t^{(i-1) \alpha_{i}}} \int_{\mathbb{R}^{d_{i}}}\left(L_{S} p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{i} z\right)-L_{S} p_{S}(t, \mathbf{x})\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
& =L_{S}\left(\frac{1}{t^{(i-1) \alpha_{i}}} \int_{\mathbb{R}^{d_{i}}}\left(p_{S}\left(t, \mathbf{x}+\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}\right)=L_{S} \Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x}) \\
& =\int_{\mathbb{R}^{N}}\left(\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x}+\mathbf{z})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})\right) \nu_{S}(d \mathbf{z})
\end{aligned}
$$

using (4.34) for the last equality. The idea is now as above to introduce a cutting threshold at the characteristic time-scale $t^{\frac{1}{\alpha}}$ for the variable $\mathbf{z}$. Write:

$$
\begin{align*}
E_{i, 2}(t, \mathbf{x})= & \int_{|\mathbf{z}| \leq t^{\frac{1}{\alpha}}}\left(\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x}+\mathbf{z})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})\right) \nu_{S}(d \mathbf{z}) \\
& +\int_{|\mathbf{z}|>t^{\frac{1}{\alpha}}}\left(\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x}+\mathbf{z})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t} p_{S}(t, \mathbf{x})\right) \nu_{S}(d \mathbf{z}):=\left(E_{i, 21}+E_{i, 22}\right)(t, \mathbf{x}) \tag{4.35}
\end{align*}
$$

Hence we get from point (i) (see also (4.34)):

$$
\begin{array}{r}
\left|E_{i, 22}(t, \mathbf{x})\right| \leq \frac{C}{t} \int_{|\mathbf{z}|>t^{\frac{1}{\alpha}}}(q(t, \mathbf{x}+\mathbf{z})+q(t, \mathbf{x})) \nu_{S}(d \mathbf{z}) \\
=\frac{C}{t} \int_{t^{\frac{1}{\alpha}}}^{+\infty} \frac{d r}{r^{1+\alpha}} \int_{\mathbb{S}^{N-1}}(q(t, \mathbf{x}+r \boldsymbol{\xi})+q(t, \mathbf{x})) \tilde{\mu}_{S}(d \boldsymbol{\xi})=\frac{C}{t^{2}} \int_{1}^{+\infty} \frac{d s}{s^{1+\alpha}} \int_{\mathbb{S}^{N-1}}\left(q\left(t, \mathbf{x}+s t^{\frac{1}{\alpha}} \boldsymbol{\xi}\right)+q(t, \mathbf{x})\right) \tilde{\mu}_{S}(d \boldsymbol{\xi}) \\
=\frac{C}{t^{2}} \int_{1}^{+\infty} \frac{d s}{s^{1+\alpha}} \int_{\mathbb{S}^{N-1}} q\left(t, \mathbf{x}+s t^{\frac{1}{\alpha}} \boldsymbol{\xi}\right) \tilde{\mu}_{S}(d \boldsymbol{\xi})+\frac{C}{t^{2}} q(t, \mathbf{x}), t>0, \mathbf{x} \in \mathbb{R}^{N}
\end{array}
$$

Define the density $\bar{q}(t, \cdot)$ :

$$
\bar{q}(t, \mathbf{x}):=C_{1} \int_{1}^{+\infty} \frac{d s}{s^{1+\alpha}} \int_{\mathbb{S}^{N-1}} q\left(t, \mathbf{x}+s t^{\frac{1}{\alpha}} \boldsymbol{\xi}\right) \tilde{\mu}_{S}(d \boldsymbol{\xi}), \quad t>0, \mathbf{x} \in \mathbb{R}^{N}
$$

We derive:

$$
\begin{equation*}
\left|E_{i, 22}(t, \mathbf{x})\right| \leq \frac{C}{t^{2}}(\bar{q}(t, \mathbf{x})+q(t, \mathbf{x})) \tag{4.36}
\end{equation*}
$$

By the properties of $q$ we deduce $\bar{q}(t, \mathbf{x})=t^{-\frac{N}{\alpha}} \bar{q}\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right)$. Moreover, by using the Fubini theorem, we can check (4.8) when $q$ is replaced by $\bar{q}$. For $E_{i, 21}(t, \mathbf{x})$ we use point (ii) in the diagonal regime, for $\mathbf{x}^{\prime}=\mathbf{x}+\mathbf{z}$, so that $\left|\mathbf{x}^{\prime}-\mathbf{x}\right| \leq t^{\frac{1}{\alpha}}$, taking $\beta=1$. We get, arguing as before (recall that $\alpha \in(0,1)$ ), writing $\nu_{S}(d \mathbf{z})=\frac{d r}{r^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})$ :

$$
\begin{aligned}
& \left|E_{i, 21}(t, \mathbf{x})\right| \leq \frac{C}{t} \int_{|\mathbf{z}| \leq t^{\frac{1}{\alpha}}}(q(t, \mathbf{x}+\mathbf{z})+q(t, \mathbf{x})) \frac{|\mathbf{z}|}{t^{\frac{1}{\alpha}}} \nu_{S}(d \mathbf{z}) \\
& \quad=\frac{C}{t^{2}} \int_{0}^{1} \frac{d s}{s^{\alpha}} \int_{\mathbb{S}^{N}-1}\left(q\left(t, \mathbf{x}+s t^{\frac{1}{\alpha}} \boldsymbol{\xi}\right)+q(t, \mathbf{x})\right) \tilde{\mu}_{S}(d \boldsymbol{\xi})
\end{aligned}
$$

changing also variable $s=r t^{-\frac{1}{\alpha}}$ to get the last integral. Defining the density $\tilde{q}(t, \cdot)$ :

$$
\tilde{q}(t, \mathbf{x}):=C \int_{0}^{1} \frac{d s}{s^{\alpha}} \int_{\mathbb{S}^{N-1}} q\left(t, \mathbf{x}+s t^{\frac{1}{\alpha}} \boldsymbol{\xi}\right) \tilde{\mu}_{S}(d \boldsymbol{\xi}), \quad t>0, \mathbf{x} \in \mathbb{R}^{N}
$$

we note that $\tilde{q}(t, \mathbf{x})=t^{-\frac{N}{\alpha}} \tilde{q}\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right)$; we have (4.8) when $q$ is replaced by $\tilde{q}$. Finally

$$
\left|E_{i, 2}(t, \mathbf{x})\right| \leq \frac{C}{t^{2}}(q(t, \mathbf{x})+\bar{q}(t, \mathbf{x})+\tilde{q}(t, \mathbf{x}))
$$

Plugging this last control and (4.33) into (4.32) gives the statement up to a modification of $q$.

Proof of estimate (4.20). By independence, see equation (4.15), we can write:

$$
p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)=\int_{\mathbb{R}^{N}}\left(p_{M}(t, \mathbf{x}-\boldsymbol{\xi})-p_{M}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right) P_{N_{t}}(d \boldsymbol{\xi})
$$

Now, since $p_{M}$ is smooth, we can use Taylor formula to expand:

$$
\int_{\mathbb{R}^{N}}\left(p_{M}(t, \mathbf{x}-\boldsymbol{\xi})-p_{M}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right) P_{N_{t}}(d \boldsymbol{\xi})=\int_{\mathbb{R}^{N}} \int_{0}^{1} \nabla_{\mathbf{x}} p_{M}\left(t, \lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}\right) \cdot\left(\mathbf{x}-\mathbf{x}^{\prime}\right) d \lambda P_{N_{t}}(d \boldsymbol{\xi})
$$

Equation (4.16) now yields that, for a given $m \in \mathbb{N}$, there exists a constant $C_{m}$ s.t. for all $t>0,\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in \mathbb{R}^{2 N}$ :

$$
\left|\nabla_{\mathbf{x}} p_{M}\left(t, \lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right| \leq C_{m} \frac{1}{t^{\frac{1}{\alpha}}} t^{-\frac{N}{\alpha}}\left(1+\frac{\left|\lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}\right|}{t^{\frac{1}{\alpha}}}\right)^{-m}=\frac{\bar{C}_{m}}{t^{\frac{1}{\alpha}}} p_{\bar{M}}\left(t, \lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)
$$

We thus derive:

$$
\begin{equation*}
\left|\int_{\mathbb{R}^{N}}\left(p_{M}(t, \mathbf{x}-\boldsymbol{\xi})-p_{M}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right) P_{N_{t}}(d \boldsymbol{\xi})\right| \leq \int_{\mathbb{R}^{N}} C_{m} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}} \int_{0}^{1} p_{\bar{M}}\left(t, \lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}\right) d \lambda P_{N_{t}}(d \boldsymbol{\xi}) \tag{4.37}
\end{equation*}
$$

Rewrite: $\lambda \mathbf{x}+(1-\lambda) \mathbf{x}^{\prime}-\boldsymbol{\xi}=\lambda(\mathbf{x}-\boldsymbol{\xi})+(1-\lambda)\left(\mathbf{x}^{\prime}-\boldsymbol{\xi}\right)$. Observe as well from (4.16) that $p_{\bar{M}}(t, \cdot)$ is convex. Consequently, we can bound:

$$
p_{\bar{M}}\left(t, \lambda(\mathbf{x}-\boldsymbol{\xi})+(1-\lambda)\left(\mathbf{x}^{\prime}-\boldsymbol{\xi}\right)\right) \leq \lambda p_{\bar{M}}(t, \mathbf{x}-\boldsymbol{\xi})+(1-\lambda) p_{\bar{M}}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)
$$

Plugging the above control in (4.37), we obtain:

$$
\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq \frac{C_{m}}{2} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right)
$$

recalling that we defined $p_{\bar{S}}(t, \cdot)$ as the convolution between $p_{\bar{M}}(t, \cdot)$ and the law of $N_{t}$ (see (4.17)). The above control readily gives (4.20) if $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{\alpha}}$. Indeed, in that case $\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}} \leq\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}$ for all $\beta \in(0,1]$. On the other hand, if $\left|\mathbf{x}-\mathbf{x}^{\prime}\right|>t^{\frac{1}{\alpha}}$, we can again derive from (4.16) with $\mathbf{i}=\mathbf{0}$

$$
\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq p_{S}(t, \mathbf{x})+p_{S}\left(t, \mathbf{x}^{\prime}\right) \leq C\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \leq C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{\alpha}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right)
$$

for all $\beta \in(0,1]$. This completes the proof of (4.20).
We now state a crucial result to deal with the estimation of the singularities in (4.7) (see also Remark 4.1).
Lemma 4.4 (Integration of the singularities). For all $\delta>0, \kappa \geq 0$ sufficiently small, there exists $C:=$ $C((\mathbf{A}), \delta, \kappa)>0$ such that for all $\gamma>0$ and given $(t, \sigma) \in[-T, T]^{2}$, with $|t-\sigma| \leq \gamma^{\alpha}$, defining for $s \geq t \vee \sigma$ :

$$
\rho_{s}(\mathbf{z}):=|s-t|^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{\frac{1}{1+\alpha(i-1)}}|u(s)|^{\frac{1}{\alpha}},
$$

where $u(s)=u_{\lambda}(s)=\lambda(s-t)+(1-\lambda)(s-\sigma)$ for any fixed $\lambda \in[0,1]$, we have for $K$ large enough:

$$
\begin{equation*}
\gamma^{\delta \alpha} \int_{s \geq t \vee \sigma, \rho_{s}(\mathbf{z}) \geq K \gamma} \frac{1}{|u(s)|^{1+\delta}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s \leq C \tag{4.38}
\end{equation*}
$$

Proof. Let us define:

$$
\begin{equation*}
I=\gamma^{\delta \alpha} \int_{s \geq t \vee \sigma, \rho_{s}(\mathbf{z}) \geq K \gamma} \frac{1}{|u(s)|^{1+\delta}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s \tag{4.39}
\end{equation*}
$$

We introduce the following partition for a fixed $c_{0}>0$ :

$$
I=\gamma^{\delta \alpha} \int_{s \geq t \vee \sigma, \rho_{s}(\mathbf{z}) \geq K \gamma,\left\{|u(s)|>c_{0} \gamma^{\alpha}\right\} \cup\left\{|u(s)| \leq c_{0} \gamma^{\alpha}\right\}} \frac{1}{|u(s)|^{1+\delta}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s .=: I_{1}+I_{2}
$$

For $I_{1}$ we readily derive, integrating the function $|\mathbf{z}|^{\kappa} q(\mathbf{z})$ in space, that:

$$
\begin{equation*}
I_{1} \leq \gamma^{\delta \alpha} \int_{\rho_{s}(\mathbf{z}) \geq K \gamma,|u(s)|>c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1+\delta}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s \leq C \gamma^{\delta \alpha}\left\{-\left.\frac{1}{r^{\delta}}\right|_{c_{0} \gamma^{\alpha}} ^{+\infty}\right\} \leq C \tag{4.40}
\end{equation*}
$$

We now turn to $I_{2}$. Observe that with the definition $\rho_{s}(\mathbf{z})$, when $|u(s)| \leq c_{0} \gamma^{\alpha}$ and $\rho_{s}(\mathbf{z}) \geq K \gamma$, since $|t-\sigma| \leq \gamma^{\alpha}$, we have $|s-t| \leq|u(s)|+|t-\sigma| \leq\left(c_{0}+1\right) \gamma^{\alpha}$ (consider the cases $t>\sigma$ and $\left.t \leq \sigma\right)$ and

$$
\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{\frac{1}{1+\alpha(i-1)}}|u(s)|^{\frac{1}{\alpha}} \geq\left(K-\left(1+c_{0}\right)^{\frac{1}{\alpha}}\right) \gamma=: \tilde{K} \gamma
$$

where $\tilde{K}>0$ when $K$ is large enough. Hence,

$$
\left\{\rho_{s}(\mathbf{z})>K \gamma,|u(s)| \leq c_{0} \gamma^{\alpha}\right\} \subset\left\{\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{\frac{1}{1+\alpha(i-1)}}|u(s)|^{\frac{1}{\alpha}} \geq \tilde{K} \gamma,|u(s)| \leq c_{0} \gamma^{\alpha}\right\}
$$

We then get:

$$
\begin{equation*}
I_{2} \leq \gamma^{\delta \alpha} \int_{\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{\frac{1}{1+\alpha(i-1)}}|u(s)|^{\frac{1}{\alpha}} \geq \tilde{K} \gamma,|u(s)| \leq c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1+\delta}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s \tag{4.41}
\end{equation*}
$$

Thus, for all $s, \mathbf{z}$, there exists $i_{0}$ such that:

$$
\left|\mathbf{z}_{i_{0}}\right| \geq\left(\frac{\tilde{K}}{n}\right)^{\alpha\left(i_{0}-1\right)+1} \frac{\gamma^{1+\alpha\left(i_{0}-1\right)}}{|u(s)|^{i_{0}-1+\frac{1}{\alpha}}}
$$

Consequently for $\eta_{j} \in(0, \alpha)$, we derive:

$$
\begin{aligned}
I_{2} & \leq C \gamma^{\delta \alpha} \int_{\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{1+\alpha(i-1)}|u(s)|^{\frac{1}{\alpha}} \geq \tilde{K} \gamma,|u(s)| \leq c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1+\delta}} \sum_{j=1}^{n}\left(\frac{\left|\mathbf{z}_{j}\right||u(s)|^{j-1+\frac{1}{\alpha}}}{\gamma^{1+\alpha(j-1)}}\right)^{\eta_{j}}|\mathbf{z}|^{\kappa} q(\mathbf{z}) d \mathbf{z} d s \\
& \leq C \sum_{j=1}^{n} \gamma^{\delta \alpha-\eta_{j}(1+\alpha(j-1))} \int_{|u(s)| \leq c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1+\delta-\eta_{j}\left(j-1+\frac{1}{\alpha}\right)}} d s \int_{\mathbb{R}^{N}}|\mathbf{z}|^{\eta_{j}+\kappa} q(\mathbf{z}) d \mathbf{z} .
\end{aligned}
$$

Choosing for all $j \in \llbracket 1, n \rrbracket, \eta_{j}+\kappa<\alpha$, we can integrate in space, i.e. $\int|\mathbf{z}|^{\eta_{j}+\kappa} q(\mathbf{z}) d \mathbf{z} \leq C$. Thus,

$$
I_{2} \leq C \sum_{j=1}^{n} \gamma^{\delta \alpha-\eta_{j}(1+\alpha(j-1))} \int_{|u(s)| \leq c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1+\delta-\eta_{j}\left(j-1+\frac{1}{\alpha}\right)}} d s \leq C
$$

where for the last inequality, we choose for all $j \in \llbracket 1, n \rrbracket, \eta_{j}=\eta$ such that:

$$
\eta>\delta \alpha \geq \frac{\alpha \delta}{\alpha(j-1)+1} \Rightarrow \delta-\eta_{j}\left(j-1+\frac{1}{\alpha}\right)<0 .
$$

We point out that the constraints on $\kappa, \delta$ and $\eta$ summarize in $\kappa+\eta<\alpha$ and $\alpha \delta<\eta$, and can be fulfilled for $\kappa$ and $\delta$ small enough.

Remark 4.2. Importantly, it can be derived from the previous proof that the term $I_{2} \leq C$ even if $\delta=0$. Indeed, in this case, we handle:

$$
\begin{equation*}
I_{2} \leq C \sum_{j=1}^{n} \gamma^{-\eta_{j}(1+\alpha(j-1))} \int_{|u(s)| \leq c_{0} \gamma^{\alpha}} \frac{1}{|u(s)|^{1-\eta_{j}\left(j-1+\frac{1}{\alpha}\right)}} d s \leq C \tag{4.42}
\end{equation*}
$$

4.2.2. Proof of the deviation Lemma 4.2: Boundedness of the terms in 4.7). We are now in position to complete the proof of Lemma 4.2 It suffices to establish that the terms $I_{i, T}$ and $I_{i, S}$ in (4.7), which respectively correspond to the time and space sensitivities, are bounded.

The purpose of the computations is then to derive that the initial integration domain $\{\rho>K \gamma\}$ can be expressed as or is included in a domain of the form $\left\{\rho_{s}(\mathbf{z})>K \gamma\right\}$, for a possibly different $K$, using the notations introduced in Lemma 4.4. This latter lemma is here the crucial tool to handle the singularities.

- Control of $\left(I_{i, S}\right)_{i \in \llbracket 1, n \rrbracket}$ in 4.7). From Lemma 4.3 and the notations introduced in (4.5):

$$
\begin{align*}
& I_{i, S} \leq I_{S}:=C \int_{s \geq \sigma \vee t, \rho>K \gamma} \frac{1}{(s-\sigma)}\left(\frac{\left|\mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-e^{(s-\sigma)} \boldsymbol{\xi}\right)\right|}{(s-\sigma)^{\frac{1}{\alpha}}}\right)^{\beta} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)}\left(q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)\right. \\
& \left.(4.43)+q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right)\right) d \mathbf{y} d s \tag{4.43}
\end{align*}
$$

We can rewrite, using also (2.7),

$$
\begin{aligned}
\left|\mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-e^{(s-\sigma) A} \boldsymbol{\xi}\right)\right| & =\left|\left(\mathbb{M}_{s-\sigma}^{-1} e^{(s-\sigma) A} \mathbb{M}_{s-\sigma}\right) \mathbb{M}_{s-\sigma}^{-1}\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)\right| \\
& =\left|e^{A} \mathbb{M}_{s-\sigma}^{-1}\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)\right| \leq C\left|\mathbb{M}_{s-\sigma}^{-1}\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)\right|
\end{aligned}
$$

so that recalling from (4.5), $\rho:=\rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)$ and $\gamma:=\rho\left(\sigma-t, e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)$ :

$$
\begin{align*}
I_{S} \leq & C \int_{s \geq \sigma \vee t, \rho>K \gamma} \sum_{i=1}^{n}\left(\frac{\left|\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)_{i}\right|}{(s-\sigma)^{i-1+\frac{1}{\alpha}}}\right)^{\beta} \frac{1}{(s-\sigma)} \\
& \times \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)}\left(q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)+q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right)\right) d \mathbf{y} d s \\
\leq & C \sum_{i=1}^{n} \gamma(\alpha(i-1)+1) \beta \int_{s \geq \sigma \vee t} \frac{1}{(s-\sigma)^{\beta\left(i-1+\frac{1}{\alpha}\right)+1}} \int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>K \gamma} \\
& \times \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)}\left(q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)+q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right)\right) d \mathbf{y} d s=: I_{S}^{1}+I_{S}^{2} \tag{4.44}
\end{align*}
$$

Let us first deal with $I_{S}^{1}$ and set for a fixed $s$,

$$
\begin{equation*}
\mathbf{z}_{1}=(s-\sigma)^{-\frac{1}{\alpha}} \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) \tag{4.45}
\end{equation*}
$$

Observe that, in the variable $\mathbf{z}_{1}$, we have for all $i \in \llbracket 1, n \rrbracket$ :

$$
\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)_{i}=\mathbf{z}_{1, i}(s-\sigma)^{\frac{1}{\alpha}+(i-1)}=\mathbf{z}_{1, i}(s-\sigma)^{\frac{1+\alpha(i-1)}{\alpha}} \Rightarrow\left|\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)_{i}\right|^{\frac{1}{\alpha(i-1)+1}}=\left|\mathbf{z}_{1, i}\right|^{\frac{1}{\alpha(i-1)+1}}(s-\sigma)^{\frac{1}{\alpha}}
$$

In other words, the component $(s-\sigma)^{\frac{1}{\alpha}}$ factorizes by homogeneity for all components (see also Remark 2.1). From the definition of $\rho$ in (4.5) we thus obtain:

$$
\rho=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\mathbf{z}_{1, i}\right|^{\frac{1}{1+\alpha(i-1)}}(s-\sigma)^{\frac{1}{\alpha}}=: \rho_{s}\left(\mathbf{z}_{1}\right)
$$

introduced in Lemma 4.4 taking $u(s)=(s-\sigma)$. Recalling the scaling property $q(t, \mathbf{x})=\frac{1}{t^{\frac{N}{\alpha}}} q\left(1, \frac{\mathbf{x}}{t^{\frac{1}{\alpha}}}\right)$ and using the previous change of variable in the spatial integral, we get

$$
I_{S}^{1} \leq C \sum_{i=1}^{n} \gamma^{(\alpha(i-1)+1) \beta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\mathbf{z}_{1}\right)>K \gamma} \frac{1}{(s-\sigma)^{\beta\left(i-1+\frac{1}{\alpha}\right)+1}} q\left(\mathbf{z}_{1}\right) d \mathbf{z}_{1} d s
$$

Each term in the above summation can thus be controlled thanks to Lemma 4.4 taking for the $i^{\text {th }}$ term, $\delta=\beta\left(i-1+\frac{1}{\alpha}\right), \kappa=0$. Let us now control $I_{S}^{2}$ in (4.44).

$$
\begin{aligned}
I_{S}^{2}= & C \sum_{i=1}^{n} \gamma^{(\alpha(i-1)+1) \beta} \int_{s \geq \sigma \vee t,\left\{|s-\sigma|>\gamma^{\alpha}\right\} \cup\left\{|s-\sigma| \leq \gamma^{\alpha}\right\}} \frac{1}{(s-\sigma)^{\beta\left(i-1+\frac{1}{\alpha}\right)+1}} \\
& \times\left(\int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>K \gamma} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)} q\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right) d \mathbf{y}\right) d s=: I_{S}^{21}+I_{S}^{22}
\end{aligned}
$$

For $I_{S}^{21}$ we readily get the bound writing $\mathbb{I}_{\rho>K \gamma} \leq 1$ and integrating in $\mathbf{y}$ over $\mathbb{R}^{N}$ and in $s$ over $\left\{|s-\sigma|>\gamma^{\alpha}\right\}$. To analyze $I_{S}^{22}$, we first set $\mathbf{z}_{2}=(s-\sigma)^{-\frac{1}{\alpha}} \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)$. Recall as well from (4.5) that

$$
\begin{align*}
\rho & \leq|t-s|^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left(\left|\left(\mathbf{y}-e^{(s-\sigma) A} \boldsymbol{\xi}\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}+\left|\left(e^{(s-\sigma) A}\left(\boldsymbol{\xi}-e^{(\sigma-t) A} \mathbf{x}\right)\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}\right) \\
& \leq \rho_{s}\left(\mathbf{z}_{2}\right)+\sum_{i=1}^{n}\left|\left(e^{(s-\sigma) A}\left(\boldsymbol{\xi}-e^{(\sigma-t) A} \mathbf{x}\right)\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}, \tag{4.46}
\end{align*}
$$

using again the notations of Lemma 4.4 with $u(s)=(s-\sigma)$ for the last inequality. Observe now that arguing as in (4.4) we have, for any $\mathbf{q} \in \mathbb{R}^{N}, r>0, i \in \llbracket 1, n \rrbracket$,

$$
\begin{array}{r}
\left|\left(e^{r A} \mathbf{q}\right)_{i}\right|=\left|B_{i}^{*} e^{r A}\left[\left(\mathbf{q}^{*}\right)^{*}\right]\right|=\left|\left(\mathbf{q}^{*} e^{r A^{*}} B_{i}\right)^{*}\right|=\left|\mathbf{q}^{*} e^{r A^{*}} B_{i}\right|=\left|\mathbf{q}^{*} \mathbb{M}_{r}^{-1} e^{A^{*}} \mathbb{M}_{r} B_{i}\right| \\
=r^{(i-1)}\left|\mathbf{q}^{*} \mathbb{M}_{r}^{-1} e^{A^{*}} B_{i}\right|=r^{(i-1)}\left|\left[\mathbf{q}_{1}, r^{-1} \mathbf{q}_{2}, \ldots, r^{-(n-1)} \mathbf{q}_{n}\right]^{*} e^{A^{*}} B_{i}\right|=c \sum_{k=1}^{i} r^{i-k}\left|\mathbf{q}_{k}\right| \tag{4.47}
\end{array}
$$

By (4.47), we get for all $i \in \llbracket 1, n \rrbracket$ :

$$
\left|\left(e^{(s-\sigma) A}\left(\boldsymbol{\xi}-e^{(\sigma-t) A} \mathbf{x}\right)\right)_{i}\right| \leq C \sum_{j=1}^{i}|s-\sigma|^{i-j}\left|\left(\boldsymbol{\xi}-e^{(\sigma-t) A} \mathbf{x}\right)_{j}\right| \leq C \sum_{j=1}^{i} \gamma^{\alpha(i-j)} \gamma^{\alpha(j-1)+1} \leq C \gamma^{\alpha(i-1)+1}
$$

recalling that $|s-\sigma| \leq \gamma^{\alpha}$ for $I_{S}^{22}$ and $\gamma=\rho\left(|t-\sigma|, \boldsymbol{\xi}-e^{(\sigma-t) A} \mathbf{x}\right)$, with $\rho(\cdot, \cdot)$ defined in (2.2), for the last inequality. We thus get from (4.46):

$$
\rho \leq \rho_{s}\left(\mathbf{z}_{2}\right)+C \gamma .
$$

Hence, $\left\{\rho>K \gamma,|s-\sigma| \leq \gamma^{\alpha}\right\} \subset\left\{\rho_{s}\left(\mathbf{z}_{2}\right)>(K-C) \gamma\right\}$, so that

$$
I_{S}^{22} \leq C \sum_{i=1}^{n} \gamma^{(\alpha(i-1)+1) \beta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\mathbf{z}_{2}\right)>(K-C) \gamma} \frac{1}{(s-\sigma)^{\beta\left(i-1+\frac{1}{\alpha}\right)+1}} q\left(\mathbf{z}_{2}\right) d \mathbf{z}_{2} d s
$$

which is again controlled by Lemma 4.4 taking the same arguments as for $I_{S}^{1}$ for $K$ large enough. The statement for $I_{S}$ follows from (4.44) and the previous controls.

- Control of $\left(I_{i, T}\right)_{i \in \llbracket 1, n \rrbracket}$ in 4.7). For the analysis, we need to exploit the relative position of $t, \sigma \leq s$. We can assume w.l.o.g. that $t<\sigma \leq s$. Note that, if $t=\sigma$, then for all $i \in \llbracket 1, n \rrbracket, I_{i, T}=0$ (no time sensitivity). Set for a fixed $s$,

$$
\begin{equation*}
\mathbf{z}_{3}=\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) \tag{4.48}
\end{equation*}
$$

Recall as well from (4.5) that:

$$
\begin{equation*}
\rho=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)_{i}\right|^{\frac{1}{\alpha(i-1)+1}}=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|(s-t)^{i-1}\left(\mathbf{z}_{3}\right)_{i}\right|^{\frac{1}{\alpha(i-1)+1}}=\rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right), \tag{4.49}
\end{equation*}
$$

with the notation of Lemma 4.4 with $u(s)=s-t$. We now split for $i \in \llbracket 1, n \rrbracket$ the terms in the following way:

$$
\begin{aligned}
& =\int_{s \geq \sigma \vee t, \rho>K \gamma}\left|\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)}-\frac{\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)}\right| d \mathbf{y} d s \\
& =\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{z_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \left.\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbf{z}_{3}\right)-\frac{\operatorname{det}\left(\mathbb{M}_{s-t}\right)}{\operatorname{det}\left(\mathbb{M}_{s-\sigma}\right)} \Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbb{M}_{s-\sigma}^{-1} \mathbb{M}_{s-t} \mathbf{z}_{3}\right) \right\rvert\, d \mathbf{z}_{3} d s \\
& \leq \int_{s \geq \sigma \vee t, \rho_{s}\left(\frac{z_{3}}{(s-t)^{\frac{T}{\alpha}}}\right)>K \gamma}\left|\Delta^{\Delta_{i}^{2}, A, i, s-t} p_{S}\left(s-t, \mathbf{z}_{3}\right)-\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbf{z}_{3}\right)\right| d \mathbf{z}_{3} d s \\
& +\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{z_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbf{Z}_{3}\right)-\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \left.\mathbb{M}_{\left.\frac{s-t}{s-\sigma} \mathbf{Z}_{3}\right)} \right\rvert\, d \mathbf{Z}_{3} d s\right. \\
& +\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{z_{3}}{(s-t) \frac{T}{\alpha}}\right)>K \gamma \left\lvert\,\left(1-\operatorname{det} \mathbb{M}_{\frac{s-t}{s-\sigma}}\right) \Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \left.\mathbb{M}_{\left.\frac{s-t}{s-\sigma} \mathbf{Z}_{3}\right)} \right\rvert\, d \mathbf{z}_{3} d s=: I_{i, T}^{1}+I_{i, T}^{2}+I_{i, T}^{3} .\right.\right.
\end{aligned}
$$

- Control of $I_{i, T}^{3}$.

Let us first handle the contribution $I_{i, T}^{3}$ which is the most unusual and which specifically appears in the degenerate framework. From equation (4.9) in Lemma 4.3 we have for all $i \in \llbracket 1, n \rrbracket$ :

$$
I_{i, T}^{3} \leq C \int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{z_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \frac{1}{(s-\sigma)^{2}} q\left(s-\sigma, \mathbb{M}_{\left.\frac{s-t}{s-\sigma} \mathbf{Z}_{3}\right) \mid}\left|1-\left(\frac{s-t}{s-\sigma}\right)^{r}\right| d \mathbf{z}_{3} d s=: I_{T}^{3},\right.
$$

where $r:=\sum_{j=1}^{n}(j-1) d_{j}=N-d_{1}$. Observe now that:

$$
\left|1-\left(\frac{s-t}{s-\sigma}\right)^{r}\right|=\frac{r(\sigma-t) \int_{0}^{1}(s-\sigma+\lambda(\sigma-t))^{r-1} d \lambda}{(s-\sigma)^{r}} \leq r \frac{(\sigma-t)(s-t)^{r-1}}{(s-\sigma)^{r}}
$$

recalling that for all $\lambda \in[0,1], s-\sigma+\lambda(\sigma-t) \leq s-t$ for the last inequality. Set now from (4.48),

$$
\hat{\mathbf{z}}_{3}:=(s-\sigma)^{-\frac{1}{\alpha}} \mathbb{M}_{\frac{s-t}{}} \mathbf{Z}_{3}=(s-\sigma)^{-\frac{1}{\alpha}} \mathbb{M}_{s-\sigma}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) .
$$

Recalling (4.49), we obtain with the notation of Lemma 4.4 and $u(s)=s-\sigma$ :

$$
\rho=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)_{i}\right|^{\frac{1}{\alpha(i-1)+1}}=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\hat{\mathbf{z}}_{3, i}\right|^{\frac{1}{\alpha(i-1)+1}}(s-\sigma)^{\frac{1}{\alpha}}=: \rho_{s}\left(\hat{\mathbf{z}}_{3}\right) .
$$

Hence, since $d \mathbf{z}_{3}=(s-\sigma)^{\frac{N}{\alpha}}\left(\frac{s-\sigma}{s-t}\right)^{r} d \hat{\mathbf{z}}_{3}$,

$$
\begin{aligned}
I_{T}^{3} & \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)} q\left(\hat{\mathbf{z}}_{3}\right)\left(\frac{s-\sigma}{s-t}\right)^{r} \frac{(\sigma-t)(s-t)^{r-1}}{(s-\sigma)^{r}} d \hat{\mathbf{z}}_{3} d s \\
& \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)} q\left(\hat{\mathbf{z}}_{3}\right) \frac{\sigma-t}{s-t} d \hat{\mathbf{z}}_{3} d s .
\end{aligned}
$$

Our previous choice $t<\sigma \leq s$ then yields $(\sigma-t) \leq(s-t), s-\sigma \leq(s-t)$ and therefore for some $\delta \in(0, \alpha)$ : $I_{T}^{3} \leq C(\sigma-t)^{\delta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)(s-t)^{\delta}} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s \leq C(\sigma-t)^{\delta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)^{1+\delta}} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}} d s$.
Hence, Lemma 4.4 applied with the current $\delta, \kappa=0$ yields $I_{T}^{3} \leq C$.

- Control of $I_{i, T}^{2}$.

Using Lemma 4.3 we bound:

$$
\begin{equation*}
I_{i, T}^{2}=\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma ~\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbf{z}_{3}\right)-\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbb{M}_{\frac{s-t}{s-\sigma}} \mathbf{z}_{3}\right)\right| d \mathbf{z}_{3} d s \tag{4.50}
\end{equation*}
$$

$\leq C \int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{z_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \frac{1}{(s-\sigma)^{1+\frac{\beta}{\alpha}}}\left\|I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}\right\|^{\beta}\left|\mathbf{Z}_{3}\right|^{\beta}\left(q\left(s-\sigma, \mathbf{z}_{3}\right)+q\left(s-\sigma, \mathbb{M}_{\frac{s-t}{s-\sigma}} \mathbf{Z}_{3}\right)\right) d \mathbf{z}_{3} d s=: I_{T}^{2}$,
where $\left\|I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}\right\|$ indicates the operator norm of $I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}$. For the first term in the second line of (4.50), we set $\overline{\mathbf{z}}_{3}=(s-\sigma)^{-\frac{1}{\alpha}} \mathbf{Z}_{3}$ for $\mathbf{z}_{3}$ as in (4.48). In this variable we have from (4.49) that

$$
\begin{equation*}
\rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\overline{\mathbf{z}}_{3, i}(s-\sigma)^{\frac{1}{\alpha}}(s-t)^{i-1}\right|^{\frac{1}{1+\alpha(i-1)}}=: \bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right) . \tag{4.51}
\end{equation*}
$$

Changing variable in the second term of the second line of (4.50) to $\hat{\mathbf{z}}_{3}=(s-\sigma)^{-\frac{1}{\alpha}} \mathbb{M}_{\frac{s-t}{s}} \mathbf{Z}_{3}$, as in $I_{T, 3}$, we recall from (4.49) that (note that $\left.(s-\sigma)^{\frac{\alpha(\alpha i-1)+1}{\alpha(\alpha(i-1)+1)}}=(s-\sigma)^{\frac{1}{\alpha}}\right)$

$$
\rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)=(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\hat{\mathbf{z}}_{3, i}\right|^{\frac{1}{1+\alpha(i-1)}}(s-\sigma)^{\frac{1}{\alpha}}=\rho_{s}\left(\hat{\mathbf{z}}_{3}\right),
$$

with the notations of Lemma 4.4 with $u(s)=(s-\sigma)$. Recalling now that $s-t \geq s-\sigma$, so that $\operatorname{det}\left(\mathbb{M}_{\frac{s-\sigma}{s-t}}\right) \leq 1$ and $\left\|\mathbb{M}_{\frac{s-\sigma}{s-t}}\right\| \leq c$, we derive:

$$
\begin{aligned}
I_{T}^{2} \leq & C\left(\int_{s \geq \sigma \vee t, \bar{p}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)}\left\|I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}\right\|^{\beta}\left|\overline{\mathbf{z}}_{3}\right|^{\beta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s\right. \\
& \left.+\int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)}\left\|I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}\right\|^{\beta}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s\right) .
\end{aligned}
$$

Observe now that

$$
\left\|I_{N \times N}-\mathbb{M}_{\frac{s-t}{s-\sigma}}\right\| \leq C\left|1-\left(\frac{s-t}{s-\sigma}\right)^{n-1}\right| \leq C \frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}} .
$$

We thus get

$$
\begin{array}{r}
\quad I_{T}^{2} \leq C\left(\int_{s \geq \sigma \vee t, \bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)}\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta}\left|\overline{\mathbf{z}}_{3}\right|^{\beta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s\right. \\
\left.+\int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)}\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s\right)=: I_{T}^{21}+I_{T}^{22} .
\end{array}
$$

Let us first deal with $I_{T}^{22}$ which already has the good form to apply Lemma 4.4 since it involves $\rho_{s}\left(\hat{\mathbf{z}}_{3}\right)$ and not $\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)$. Precisely,

$$
\begin{aligned}
I_{T}^{22} & \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma,\left\{s-\sigma \leq \frac{1}{2}(s-t)\right\} \cup\left\{s-\sigma>\frac{1}{2}(s-t)\right\}} \frac{1}{(s-\sigma)}\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s \\
& =: I_{T}^{221}+I_{T}^{222} .
\end{aligned}
$$

For the second contribution, since $s-\sigma>\frac{1}{2}(s-t)$ we can bound the ratio: $\frac{(s-t)^{n-2}}{(s-\sigma)^{n-1}} \leq C \frac{1}{s-\sigma}$ so that:

$$
\begin{aligned}
I_{T}^{222} & \leq \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma, s-\sigma>\frac{1}{2}(s-t)}|t-\sigma|^{\beta} \frac{1}{(s-\sigma)^{\beta+1}}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s \\
& \leq \gamma^{\alpha \beta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)^{\beta+1}}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s .
\end{aligned}
$$

We conclude $I_{T}^{222} \leq C$ using Lemma 4.4 with $\delta=\kappa=\beta$ (choosing $\beta$ small enough and $K$ large enough). We now turn to $I_{T}^{221}$. We can bound

$$
\begin{equation*}
\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta} \leq\left(\frac{|t-\sigma|}{|s-t|}\right)^{\beta} \frac{|s-t|^{(n-1) \beta}}{(s-\sigma)^{(n-1) \beta}} \leq C \frac{\gamma^{\alpha(n-1) \beta}}{(s-\sigma)^{(n-1) \beta}} \tag{4.52}
\end{equation*}
$$

recalling that since $s-\sigma \leq \frac{1}{2}(s-t)$ then $s-t \leq 2(\sigma-t) \leq 2 \gamma^{\alpha}$ (moreover, $|t-\sigma| \leq|s-t|$ ). Thus, we obtain:

$$
\begin{aligned}
I_{T}^{221} & \leq \gamma^{\alpha(n-1) \beta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma, s-\sigma \leq \frac{1}{2}(s-t)} \frac{1}{(s-\sigma)^{1+(n-1) \beta}}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s \\
& \leq \gamma^{\alpha(n-1) \beta} \int_{s \geq \sigma \vee t, \rho_{s}\left(\hat{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{(s-\sigma)^{1+(n-1) \beta}\left|\hat{\mathbf{z}}_{3}\right|^{\beta} q\left(\hat{\mathbf{z}}_{3}\right) d \hat{\mathbf{z}}_{3} d s},
\end{aligned}
$$

where we are once again in position to apply Lemma 4.4 with $\delta=(n-1) \beta, \kappa=\beta$. The control $I_{T}^{22} \leq C$ follows. Let us now turn to $I_{T}^{21}$ and write:

$$
\begin{aligned}
I_{T}^{21} & \leq C \int_{s \geq \sigma \vee t, \bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma,\left\{s-\sigma \leq \frac{1}{2}(s-t)\right\} \cup\left\{s-\sigma>\frac{1}{2}(s-t)\right\}} \frac{1}{(s-\sigma)}\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta}\left|\overline{\mathbf{z}}_{3}\right|^{\beta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s \\
& =: I_{T}^{211}+I_{T}^{212} .
\end{aligned}
$$

For $I_{T}^{212}$, it is easily seen from the definition of $\bar{\rho}_{s}$ in (4.51) that on the considered integration set: $\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right) \leq$ $2 \rho_{s}\left(\overline{\mathbf{z}}_{3}\right)$ with $u(s)=s-\sigma$ in the notation of Lemma 4.4. Thus,

$$
I_{T}^{212} \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\overline{\mathbf{z}}_{3}\right)>\frac{K}{2} \gamma} \frac{1}{(s-\sigma)}\left(\frac{|t-\sigma||s-t|^{n-2}}{|s-\sigma|^{n-1}}\right)^{\beta}\left|\overline{\mathbf{z}}_{3}\right|^{\beta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s
$$

This term can then, up to choosing $K$ large enough, be treated as $I_{T}^{22}$. For $I_{T}^{211}$ we again use (4.52) to get:

$$
I_{T}^{211} \leq C \gamma^{\alpha(n-1) \beta} \int_{s \geq \sigma \vee t, \bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma, s-\sigma \leq \frac{1}{2}(s-t)} \frac{1}{(s-\sigma)^{1+(n-1) \beta}}\left|\overline{\mathbf{z}}_{3}\right|^{\beta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s
$$

On the considered set, since $s-t \leq s-\sigma+\sigma-t \leq 2 \gamma^{\alpha}$, we have $\sum_{i=1}^{n}\left(\left|\overline{\mathbf{z}}_{3, i}\right| \frac{(s-\sigma)^{\frac{1}{\alpha}}(s-t)^{i-1}}{\gamma^{1+\alpha(i-1)}}\right)^{\frac{1}{1+\alpha(i-1)}} \geq K-2^{1 / \alpha}$; now for $K$ large enough s.t. $\frac{K-2^{1 / \alpha}}{n} \geq 1$, we find

$$
\left\{\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma, s-\sigma \leq \frac{1}{2}(s-t)\right\} \subset\left\{\sum_{i=1}^{n}\left|\overline{\mathbf{z}}_{3, i}\right| \frac{(s-\sigma)^{\frac{1}{\alpha}}(s-t)^{i-1}}{\gamma^{1+\alpha(i-1)}} \geq \frac{K-2^{1 / \alpha}}{n}, s-\sigma \leq \frac{1}{2}(s-t)\right\}=: A\left(\overline{\mathbf{z}}_{3}\right)
$$

Also, again from $s-t \leq 2 \gamma^{\alpha}, A\left(\overline{\mathbf{z}}_{3}\right) \subset\left\{\sum_{i=1}^{n}\left|\overline{\mathbf{z}}_{3, i}\right| 2^{i-1} \frac{(s-\sigma)^{1 / \alpha}}{\gamma} \geq \frac{K-2^{\frac{1}{\alpha}}}{n}, s-\sigma \leq \gamma^{\alpha}\right\}=B\left(\overline{\mathbf{z}}_{3}\right)$. On $B\left(\overline{\mathbf{z}}_{3}\right)$ we have $\gamma \leq \tilde{C}\left|\overline{\mathbf{z}}_{3}\right|(s-\sigma)^{\frac{1}{\alpha}}$. Choosing $\beta \in(0,1], \theta>0$ s.t. $(n-1) \beta-\frac{\theta}{\alpha}<0$ and $\beta+\theta<\alpha$ we get:

$$
\begin{equation*}
I_{T}^{211} \leq C \gamma^{\alpha(n-1) \beta-\theta} \int_{\left\{0 \leq s-\sigma \leq \gamma^{\alpha}\right\}} \frac{1}{(s-\sigma)^{1+(n-1) \beta-\frac{\theta}{\alpha}}} \int_{\mathbb{R}^{N}}\left|\overline{\mathbf{z}}_{3}\right|^{\beta+\theta} q\left(\overline{\mathbf{z}}_{3}\right) d \overline{\mathbf{z}}_{3} d s \leq C \tag{4.53}
\end{equation*}
$$

- Control of $I_{i, T}^{1}$.

Finally, let us deal with $\left(I_{i, T}^{1}\right)_{i \in \llbracket 1, n \rrbracket}$. Write

$$
\begin{aligned}
I_{i, T}^{1} & =\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma \\
& \left|\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbf{z}_{3}\right)-\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbf{z}_{3}\right)\right| d \mathbf{z}_{3} d s \\
& \leq \int_{s \geq \sigma \vee t, \rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma,\left\{\sigma \leq \frac{s+t}{2}\right\} \cup\left\{\sigma>\frac{s+t}{2}\right\}}\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}\left(s-t, \mathbf{z}_{3}\right)-\Delta^{\frac{\alpha_{i}}{2}, A, i, s-\sigma} p_{S}\left(s-\sigma, \mathbf{z}_{3}\right)\right| d \mathbf{z}_{3} d s \\
& =: \quad I_{i, T}^{11}+I_{i, T}^{12}
\end{aligned}
$$

From equation (4.11) in Lemma 4.3, introducing for all $\lambda \in[0,1], u_{\lambda}(s):=\lambda(s-t)+(1-\lambda)(s-\sigma)$, we derive:

$$
\begin{aligned}
& I_{i, T}^{11}=\int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \sigma \leq \frac{s+t}{2} \\
& \left.\int_{0}^{1}\left|\partial_{t} \Delta^{\frac{\alpha_{i}}{2}, A, i, u_{\lambda}(s)} p_{S}\left(u_{\lambda}(s), \mathbf{z}_{3}\right)\right| t-\sigma \right\rvert\, d \lambda d \mathbf{z}_{3} d s \\
& \leq C \int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \sigma \leq \frac{s+t}{2} \\
& \int_{0}^{1} \frac{|t-\sigma|}{\left|u_{\lambda}(s)\right|^{2}} q\left(u_{\lambda}(s), \mathbf{z}_{3}\right) d \lambda d \mathbf{z}_{3} d s=: I_{T}^{11}
\end{aligned}
$$

Changing variable: $\tilde{\mathbf{z}}_{3}=\left[u_{\lambda}(s)\right]^{-\frac{1}{\alpha}} \mathbf{z}_{3}$ and using as before $q(t, \mathbf{x})=t^{-\frac{N}{\alpha}} q\left(1, t^{-\frac{1}{\alpha}} \mathbf{x}\right)$, we find

$$
I_{T}^{11} \leq C \int_{s \geq \sigma \vee t, \rho_{s}}\left(\frac{\tilde{\mathbf{z}}_{3}\left[u_{\lambda}(s)\right]}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \sigma \leq \frac{s+t}{2} \int_{0}^{1} \frac{|t-\sigma|}{\left|u_{\lambda}(s)\right|^{2}} q\left(\tilde{\mathbf{z}}_{3}\right) d \lambda d \tilde{\mathbf{z}}_{3} d s
$$

Since $u_{\lambda}(s) \leq s-t, \lambda \in[0,1]$, we have that $\rho_{s}\left(\frac{\tilde{\mathbf{z}}_{3}\left[u_{\lambda}(s)\right]^{\frac{1}{\alpha}}}{(s-t)^{\frac{1}{\alpha}}}\right) \leq \rho_{s}\left(\tilde{\mathbf{z}}_{3}\right)$ and we get

$$
I_{T}^{11} \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\tilde{\mathbf{z}}_{3}\right)>K \gamma, \sigma \leq \frac{s+t}{2}} \int_{0}^{1} \frac{|t-\sigma|}{\left|u_{\lambda}(s)\right|^{2}} q\left(\tilde{\mathbf{z}}_{3}\right) d \lambda d \tilde{\mathbf{z}}_{3} d s
$$

Observe now that on $\left\{\sigma \leq \frac{s+t}{2}\right\}$, we have $(s-t)=\lambda(s-t)+(1-\lambda)(s-t) \leq 2 u_{\lambda}(s)$. Hence

$$
\frac{|t-\sigma|}{\left|u_{\lambda}(s)\right|}=\frac{|t-\sigma|}{|\lambda(s-t)+(1-\lambda)(s-\sigma)|} \leq 2, \quad \lambda \in[0,1] .
$$

Hence, for all $\beta \in(0,1]$,

$$
\begin{aligned}
I_{T}^{11} & \leq C \int_{s \geq \sigma \vee t, \rho_{s}\left(\tilde{\mathbf{z}}_{3}\right)>K \gamma, \sigma \leq \frac{s+t}{2}} \int_{0}^{1} \frac{1}{\left|u_{\lambda}(s)\right|}\left(\frac{|t-\sigma|}{\left|u_{\lambda}(s)\right|}\right)^{\beta} q\left(\tilde{\mathbf{z}}_{3}\right) d \lambda d \tilde{\mathbf{z}}_{3} d s \\
& \leq C \gamma^{\alpha \beta} \int_{0}^{1} d \lambda \int_{s \geq \sigma \vee t, \rho_{s}\left(\tilde{\mathbf{z}}_{3}\right)>K \gamma} \frac{1}{\left|u_{\lambda}(s)\right|^{1+\beta}} q\left(\tilde{\mathbf{z}}_{3}\right) d \tilde{\mathbf{z}}_{3} d s
\end{aligned}
$$

We again conclude from Lemma 4.4 taking $\delta=\beta, \kappa=0$. This gives $I_{T}^{11} \leq C$.
For $I_{i, T}^{12}$, let us emphasize that on $\left\{\sigma>\frac{s+t}{2}\right\}$ we have $s-\sigma \leq \sigma-t \leq \gamma^{\alpha}$. Thus, on the considered set we also have $s-t \leq 2 \gamma^{\alpha}$. In this case, the Taylor expansion is not useful, we directly use the estimate (4.9) of Lemma 4.3 on $\Delta^{\frac{\alpha_{i}}{2}, A, i, \cdot} p_{S}$. We write, for all $i \in \llbracket 1, n \rrbracket$ :

$$
\begin{aligned}
I_{i, T}^{12} \leq & C\left(\int_{s \geq \sigma \vee t, \rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \sigma>\frac{s+t}{2}} \frac{1}{s-\sigma} q\left(s-\sigma, \mathbf{z}_{3}\right) d \mathbf{z}_{3} d s\right. \\
& \left.+\int_{s \geq \sigma \vee t, \rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, \sigma>\frac{s+t}{2}} \frac{1}{s-t} q\left(s-t, \mathbf{z}_{3}\right) d \mathbf{z}_{3} d s\right)=: I_{T}^{121}+I_{T}^{122}
\end{aligned}
$$

For $I_{T}^{122}$, we change variable to $\check{\mathbf{z}}_{3}:=\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}$; recalling Lemma 4.4 with $u(s)=s-t$ we have $\left\{\rho_{s}\left(\check{\mathbf{z}}_{3}\right)>K \gamma\right\}$ $=:\left\{(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\check{\mathbf{z}}_{3, i}\right|^{\frac{1}{1+\alpha(i-1)}}(s-t)^{\frac{1}{\alpha}}>K \gamma\right\}$; hence

$$
\begin{array}{r}
I_{T}^{122} \leq \int_{s \geq \sigma \vee t, \rho_{s}\left(\check{\mathbf{z}}_{3}\right)>K \gamma,|s-t| \leq c \gamma^{\alpha}} \frac{C}{s-t} q\left(\check{\mathbf{z}}_{3}\right) d \check{\mathbf{z}}_{3} d s \\
\leq \int_{\sum_{i=1}^{n}\left|\check{\mathbf{z}}_{3, i}\right|^{\alpha(i-1)+1}|s-t|^{\frac{1}{\alpha}}>\left(K-c^{1 / \alpha}\right) \gamma,|s-t| \leq c \gamma^{\alpha}} \frac{1}{|s-t|} q\left(\check{\mathbf{z}}_{3}\right) d \check{\mathbf{z}}_{3} d s
\end{array}
$$

which is exactly equation (4.41) with $\kappa=\delta=0$. From Remark (4.2), this yields $I_{T}^{122} \leq C$.
For $I_{T}^{121}$, we again change variable to $\overline{\mathbf{z}}_{3}:=\frac{\mathbf{z}_{3}}{(s-\sigma)^{\frac{1}{\alpha}}}$ as in $I_{T}^{21}$. This yields from (4.49) that

$$
\left\{\rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma\right\}=\left\{(s-t)^{\frac{1}{\alpha}}+\sum_{i=1}^{n}\left|\overline{\mathbf{z}}_{3, i}(s-\sigma)^{\frac{1}{\alpha}}(s-t)^{i-1}\right|^{\frac{1}{\alpha(i-1)+1}}>K \gamma\right\}=:\left\{\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma\right\}
$$

with $\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)$ as in 4.51). Since $\left\{\rho_{s}\left(\frac{\mathbf{z}_{3}}{(s-t)^{\frac{1}{\alpha}}}\right)>K \gamma, 2 \sigma>s+t\right\} \subset\left\{\bar{\rho}_{s}\left(\overline{\mathbf{z}}_{3}\right)>K \gamma,|s-\sigma| \leq \frac{1}{2}(s-t)\right\}$. Proceeding as for $I_{T}^{211}$, we arrive at (4.53) with $\beta=0$. We eventually get $I_{T}^{1} \leq C$ which completes the proof.

## 5. Proof of the Key Lemma 3.2

We split the analysis for the two terms involved in Lemma 3.2. Roughly speaking, for the $\left(K_{i, \varepsilon}^{F} f\right)_{i \in \llbracket 1, n \rrbracket}$ there are no singularity and we derive the required boundedness rather directly. On the other hand, the $\left(K_{i, \varepsilon}^{C} f\right)_{i \in \llbracket 1, n \rrbracket}$ need to be analysed much more carefully.
5.1. Proof of the estimate on $\left(K_{i, \varepsilon}^{F} f\right)_{i \in \llbracket 1, n \rrbracket}$. In this section, we prove the following estimate. For a given $p \in(1, \infty)$, we have that there exists a constant $C_{p}$ such that for all $i \in \llbracket 1, n \rrbracket$ and all $f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right)$ :

$$
\begin{equation*}
\left\|K_{i, \varepsilon}^{F} f\right\|_{L^{p}(\mathcal{S})}^{p} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})}^{p} . \tag{5.1}
\end{equation*}
$$

We first write that for $i \in \llbracket 1, n \rrbracket$ :

$$
\begin{aligned}
& \left\|K_{i, \varepsilon}^{F} f\right\|_{L^{p}(\mathcal{S})}^{p}=\int_{\mathcal{S}}\left|K_{i, \varepsilon}^{F} f(t, \mathbf{x})\right|^{p} d t d \mathbf{x}=\int_{\mathcal{S}}\left|\int_{t}^{T} \int_{\mathbb{R}^{N}} \mathbb{I}_{d(t, \mathbf{x}),(s, \mathbf{y}))>c_{0}} \mathbb{I}_{|s-t|>\varepsilon} \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{i}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) f(s, \mathbf{y}) d \mathbf{y} d s\right|^{p} d \mathbf{x} d t \\
& \leq \int_{\mathcal{S}}\left(\int_{t}^{T} \int_{\mathbb{R}^{N}} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y}))>c_{0}} \frac{1}{s-t} \operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right)|f(s, \mathbf{y})| d \mathbf{y} d s\right)^{p} d \mathbf{x} d t,
\end{aligned}
$$

where to get the last inequality, we discarded the time indicator and applied equation (4.11) from Lemma 4.3 to estimate the fractional derivative (recalling the correspondence between $\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s, t, \mathbf{x}, \mathbf{y})$ and $\Delta^{\frac{\alpha_{i}}{2}, A, i, s-t} p_{S}(s-$ $\left.t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)$; see (3.6) ). Now, let us introduce $r>1$ such that $\frac{1}{r}+\frac{1}{p}=1$. Write

$$
\begin{array}{r}
\frac{\operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1}}{s-t} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right)|f(s, \mathbf{y})| \\
=\left[\frac{\operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1}}{s-t} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right)\right]^{\frac{1}{r}}\left[\frac{\operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1}}{s-t} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right)\right]^{\frac{1}{p}}|f(s, \mathbf{y})| .
\end{array}
$$

To proceed we recall the following important equivalence result: There exists $\kappa:=\kappa((\mathbf{A})) \geq 1$ s.t. for all $((t, \mathbf{x}),(s, \mathbf{y})) \in \mathcal{S}^{2}:$

$$
\begin{equation*}
\kappa^{-1} \rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) \leq d((t, \mathbf{x}),(s, \mathbf{y})) \leq \kappa \rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) \tag{5.2}
\end{equation*}
$$

This equivalence can be deduced from (C.16) established in the proof of Proposition C.2 below. Setting $\rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right):=\rho$ the Hölder inequality yields:

$$
\begin{aligned}
\left\|K_{i, \varepsilon}^{F} f\right\|_{L^{p}(\mathcal{S})}^{p} \leq & \int_{\mathcal{S}}\left(\int_{t}^{T} \int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>\frac{c_{0}}{C}} \frac{1}{s-t} \operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s\right)^{\frac{p}{r}} \\
& \times\left(\int_{t}^{T} \int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>\frac{c_{0}}{C}} \frac{1}{s-t} \operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right)|f(s, \mathbf{y})|^{p} d \mathbf{y} d s\right) d \mathbf{x} d t,
\end{aligned}
$$

for $C:=C((\mathbf{A})) \geq 1$. Now, set $\mathbf{z}=\frac{\mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)}{|s-t|^{1 / \alpha}}$; as in (4.49) $\rho=\rho_{s}(\mathbf{z})$. By the Fubini theorem, setting $\tilde{c}_{0}:=\frac{c_{0}}{C}$, we get

$$
\begin{align*}
& \int_{t}^{T} \int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>\tilde{c}_{0}} \frac{1}{s-t} \operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s \leq \int_{\rho_{s}(\mathbf{z})>\tilde{c}_{0}} \frac{1}{|s-t|} q(\mathbf{z}) d \mathbf{z} d s \leq C  \tag{5.3}\\
& \int_{-T}^{s} \int_{\mathbb{R}^{N}} \mathbb{I}_{\rho>\tilde{c}_{0}} \frac{1}{s-t} \operatorname{det}\left(\mathbb{M}_{s-t}\right)^{-1} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{x} d t \leq \int_{\rho_{t}(\mathbf{z})>\tilde{c}_{0}} \frac{1}{|s-t|} q(\mathbf{z}) d \mathbf{z} d t \leq C
\end{align*}
$$

with the notations of Lemma 4.4 taking $u(s)=s-t$ for the first integral and $u(t)=s-t$ for the second (see also the next remark).

Remark 5.1. Note that in (5.3), $\tilde{c}_{0}$ is a fixed constant. This allows to get rid of the singularity. Indeed, as in Lemma 4.4 either $|s-t| \geq \frac{\tilde{c}_{0}}{2}$ and there is no singularity, or there exists $i \in \llbracket 1, n \rrbracket$ such that $\left|\mathbf{z}_{i}\right|^{\frac{1}{\alpha(i-1)+1}}(s-t)^{\frac{1}{\alpha}} \geq$ $\frac{\tilde{c}_{0}}{2 n}$. By the arguments of the proof of Lemma [4.4 see also Remark 4.2] we get the estimates of (5.3).
5.2. Proof of the estimate on the $\left(K_{i, \varepsilon}^{C} f\right)_{i \in \llbracket 1, n \rrbracket}$. In this section, we prove the following estimate for all $i \in \llbracket 1, n \rrbracket, p \in(1, \infty)$ :

$$
\begin{equation*}
\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})} \tag{5.4}
\end{equation*}
$$

The idea is to rely first on Theorem C.1 to derive the estimate for $p \in(1,2]$. To this purpose we use that $(\mathcal{S}, d, \mu)$, where $\mu$ is the Lebesgue measure and $d$ is defined in (3.10), can be viewed as a homogeneous space (cf. Proposition C.2).

Then, to extend the estimate for all $p>2$ we use a duality argument. Let us recall that by definition of $K_{i, \varepsilon}^{C} f$, the kernel:

$$
k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))=\mathbb{I}_{|s-t| \geq \varepsilon} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}} \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})
$$

is in $L^{2}(\mathcal{S} \times \mathcal{S})$, thanks to the truncations. The crucial points are an $L^{2}$ estimate and a deviation lemma.
Lemma 5.1 ( $L^{2}$ estimate for the truncated kernel). There exists $C_{2, T}>0$ such that for all $i \in \llbracket 1, n \rrbracket$ :

$$
\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{2}(\mathcal{S})} \leq C_{2}\|f\|_{L^{2}(\mathcal{S})}, \quad f \in \mathscr{T}\left(\mathbb{R}^{1+N}\right)
$$

Proof. We have:

$$
\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{2}(\mathcal{S})}^{2}=\int_{\mathcal{S}}\left|K_{i, \varepsilon}^{C} f(t, x)\right|^{2} d \mathbf{x} d t \leq \int_{\mathcal{S}}\left|K_{i, \varepsilon} f(t, x)\right|^{2} d \mathbf{x} d t+\int_{\mathcal{S}}\left|K_{i, \varepsilon}^{F} f(t, x)\right|^{2} d \mathbf{x} d t
$$

We now use Lemma 4.1 to control the first contribution and (5.1) for the second.
Lemma 5.2 (Deviation Controls for the truncated kernel). There exist constants $K:=K((\mathbf{A})), C:=C((\mathbf{A}) \geq$ 1 s.t. for all $i \in \llbracket 1, n \rrbracket, \varepsilon>0$ and $(t, \mathbf{x}),(\sigma, \boldsymbol{\xi}) \in \mathcal{S}$, the following control holds:

$$
\begin{equation*}
\int_{\mathcal{S} \cap\{d((t, \mathbf{x}),(s, \mathbf{y})) \geq K d((t, \mathbf{x}),(\sigma, \boldsymbol{\xi}))\}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s \leq C \tag{5.5}
\end{equation*}
$$

Proof. We will rely on the global deviation Lemma 4.2. We write:

$$
\begin{aligned}
& \int_{\mathcal{S} \cap\{d((t, \mathbf{x}),(s, \mathbf{y})) \geq K d((t, \mathbf{x}),(\sigma, \boldsymbol{\xi}))\}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s \\
\leq & \int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y})) \leq c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s \\
& +\int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))>c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s \\
\text { j) } & +\int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y}))>c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y})) \leq c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s=: T_{1}+T_{2}+T_{3},
\end{aligned}
$$

where we used the equivalence (5.2) implicitly modifying $K$; here $\rho=\rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)$ and $\gamma:=\rho(\sigma-$ $\left.t, e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)$ as in (4.5). The second and third integrals $T_{2}, T_{3}$ are dealt similarly. For $T_{1}$, the difference with Lemma 4.2 is the time indicator and the spatial localization.

Control of $T_{1}$ in (5.6). For this term, we split according to the relative position of $s-t$ and $s-\sigma$. We write:

$$
\begin{aligned}
& \int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y})) \leq c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))-k_{i, \varepsilon}^{C}((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))\right| d \mathbf{y} d s \\
\leq & \int_{(s-t) \wedge(s-\sigma) \geq \varepsilon, \rho \geq K \gamma}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-\sigma, \boldsymbol{\xi}, \mathbf{y})\right| d \mathbf{y} d s \\
& +\int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})\right| d \mathbf{y} d s+\int_{\rho \geq K \gamma} \mathbb{I}_{s-t<\varepsilon, s-\sigma \geq \varepsilon}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-\sigma, \boldsymbol{\xi}, \mathbf{y})\right| d \mathbf{y} d s
\end{aligned}
$$

Since $\{(s-t) \wedge(s-\sigma) \geq \varepsilon\} \subset\{s \geq t \vee \sigma\}$, the first contribution above is dealt directly with Lemma 4.2 The following two are dealt similarly, and we focus on the first one. By (3.6) and (4.9) of Lemma 4.3 we get:

$$
\begin{array}{r}
\int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})\right| d \mathbf{y} d s \\
\leq \int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon} \frac{C}{s-t} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s
\end{array}
$$

We now discuss according to the position of $\gamma$ relatively to $\varepsilon$.

- Assume first that $\varepsilon \leq \gamma^{\alpha}$. In this case, we can write

$$
\begin{equation*}
|s-t| \leq|s-\sigma|+|\sigma-t| \leq \varepsilon+\gamma^{\alpha} \leq 2 \gamma^{\alpha} \tag{5.7}
\end{equation*}
$$

Consequently, we write for all $\beta>0:\left(\frac{2 \gamma^{\alpha}}{s-t}\right)^{\beta} \geq 1$, and changing variables to $\mathbf{z}=(s-t)^{-\frac{1}{\alpha}} \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)$ in the last integral leads to:

$$
\int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma \leq \varepsilon}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})\right| d \mathbf{y} d s \leq C \int_{\rho_{s}(\mathbf{z}) \geq K \gamma} \frac{\gamma^{\alpha \beta}}{(s-t)^{1+\beta}} q(\mathbf{z}) d \mathbf{z} d s
$$

and we conclude with Lemma 4.4, taking $u(s)=s-t$.

- Assume now that $\varepsilon>\gamma^{\alpha}$. In this case we write directly

$$
\begin{aligned}
& \int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon} \frac{1}{s-t} \frac{1}{\operatorname{det} \mathbb{M}_{s-t}} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s \\
\leq & \frac{1}{\varepsilon} \int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon} \frac{1}{\operatorname{det} \mathbb{M}_{s-t}} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s
\end{aligned}
$$

Also, since $\varepsilon>\gamma^{\alpha}$, using (5.7) we actually have $|s-t| \leq 2 \varepsilon$, so that:
$\int_{\rho \geq K \gamma} \mathbb{I}_{s-t \geq \varepsilon, s-\sigma<\varepsilon}\left|\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})\right| d \mathbf{y} d s \leq \frac{C}{\varepsilon} \int_{|s-t| \leq 2 \varepsilon} \frac{1}{\operatorname{det} \mathbb{M}_{s-t}} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s \leq C$.
Control of $T_{2}, T_{3}$ in (5.6). We focus on $T_{2}$ for which $d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))>c_{0}$. The term $T_{3}$ could be handled similarly. We have:

$$
T_{2}=\int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))>c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))\right| d \mathbf{y} d s
$$

Using the quasi triangle inequality (C.12) below, we have:

$$
c_{0} \geq d((t, \mathbf{x}),(s, \mathbf{y})) \geq \frac{d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))}{\Lambda}-d((\sigma, \boldsymbol{\xi}),(t, \mathbf{x})) \geq \frac{c_{0}}{\Lambda}-\gamma \kappa
$$

exploiting as well (5.2) for the last inequality. We now split according to the relative position of $\gamma$ and $c_{0}$.

- Assume first that $\gamma \leq \frac{c_{0}}{2 \Lambda \kappa}$. In this case, we get $\frac{c_{0}}{\Lambda}-\gamma \kappa \geq \frac{c_{0}}{2 \Lambda}$, and we are left with the integral:

$$
\begin{aligned}
& \int_{\rho \geq K \gamma, d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}, d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))>c_{0}}\left|k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y}))\right| d \mathbf{y} d s \\
\leq & C \int_{\rho \geq \frac{c_{0}}{2 \Lambda}} \frac{1}{s-t} \frac{1}{\operatorname{det} \mathbb{M}_{s-t}} q\left(s-t, \mathbb{M}_{s-t}^{-1}\left(\mathbf{y}-e^{(s-t) A} \mathbf{x}\right)\right) d \mathbf{y} d s \leq C \int_{\rho_{s}(\mathbf{z}) \geq \frac{c_{0}}{2 \Lambda}} \frac{1}{s-t} q(\mathbf{z}) d \mathbf{z} d s
\end{aligned}
$$

$\mathbf{z}=\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)(s-t)^{-1 / \alpha}$, bounding the fractional derivative with estimate 4.9). We are thus exactly in the same position as in Remark 5.1 that allows to control the above integral.

- Suppose now that $\gamma>\frac{c_{0}}{2 \Lambda}$. In this case, we readily get: $\rho \geq K \gamma \geq \frac{K c_{0}}{2 \Lambda}$ and the corresponding integral can be bounded similarly.

Recalling that by construction, for all $i \in \llbracket 1, n \rrbracket, k_{i, \varepsilon}^{C} \in L^{2}(\mathcal{S} \times \mathcal{S})$, estimate (5.4) now follows from Lemmas 5.1, 5.2 and Theorem C.1 below for $p \in(1,2]$ since from PropositionC.2 $(\mathcal{S}, d, \mu)$ can be viewed as a homogeneous space. Estimate (5.4) for $p \in(2,+\infty)$ can then be derived by duality as follows. Let $p \in(2,+\infty)$ be given and consider $g \in L^{r}(\mathcal{S})$ with $r>1, \frac{1}{r}+\frac{1}{p}=1$. Then, for all $i \in \llbracket 1, n \rrbracket$ and $f \in L^{p}(\mathcal{S})$,

$$
\begin{aligned}
\int_{\mathcal{S}} K_{i, \varepsilon}^{C} f(t, \mathbf{x}) g(t, \mathbf{x}) d \mathbf{x} d t & =\int_{-T}^{T} \int_{\mathbb{R}^{N}}\left(\int_{t}^{T} \int_{\mathbb{R}^{N}} k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y})) f(s, \mathbf{y}) d \mathbf{y} d s\right) g(t, \mathbf{x}) d \mathbf{x} d t \\
& =\int_{-T}^{T} \int_{\mathbb{R}^{N}}\left(\int_{-T}^{s} \int_{\mathbb{R}^{N}} k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y})) g(t, \mathbf{x}) d \mathbf{x} d t\right) f(s, \mathbf{y}) d \mathbf{y} d s \\
& =: \int_{-T}^{T} \int_{\mathbb{R}^{N}} \bar{K}_{i, \varepsilon}^{C} g(s, \mathbf{y}) f(s, \mathbf{y}) d \mathbf{y} d s,
\end{aligned}
$$

where $\bar{K}_{i, \varepsilon}^{C}$ is the adjoint of $K_{i, \varepsilon}^{C}$. Recall that $k_{i, \varepsilon}^{C}((t, \mathbf{x}),(s, \mathbf{y})):=\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y}) \mathbb{I}_{|s-t| \geq \varepsilon} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}}$; see (3.11). From (3.6), using that

$$
\mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)=\mathbb{M}_{s-t}^{-1} \mathbb{M}_{s-t} e^{A} \mathbb{M}_{s-t}^{-1}\left(\mathbf{x}-e^{-(s-t) A} \mathbf{y}\right)
$$

see the scaling property (2.7), we find

$$
p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{S}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)\right)=: \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right)
$$

with $\tilde{S}_{r}=e^{-A} S_{r}, r \geq 0$, where the symmetric $\mathbb{R}^{N}$-valued, $\alpha$-stable process $S$ is defined in Remark 2.3. We get:

$$
\begin{array}{r}
\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} p_{\Lambda}(s-t, \mathbf{x}, \mathbf{y})=\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right) \\
=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \text { v.p. } \int_{\mathbb{R}^{d} d_{i}}\left(p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}+B_{i} z\right)\right)-p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right)\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
=\frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \text { v.p. } \int_{\mathbb{R}^{d_{i}}}\left(p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)+(s-t)^{-(i-1)} B_{i} z\right)\right) \\
\left.-p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right)\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}= \\
: \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \bar{\Delta}^{\frac{\alpha_{i}}{2}, i, s-t} p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right),
\end{array}
$$

where for $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ and for all $i \in \llbracket 1, n \rrbracket, s>t$ the operator:

$$
\begin{equation*}
\bar{\Delta}^{\frac{\alpha_{i}}{2}, i, s-t} \varphi(\mathbf{x}):=\int_{\mathbb{R}^{d_{i}}}\left(\varphi\left(\mathbf{x}+(s-t)^{-(i-1)} B_{i} z\right)-\varphi(\mathbf{x})-(s-t)^{-(i-1)} \nabla \varphi(\mathbf{x}) \cdot B_{i} z \mathbb{I}_{|z| \leq 1}\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \tag{5.8}
\end{equation*}
$$

where $\nabla$ again stands for the full gradient on $\mathbb{R}^{N}$. We thus conclude that

$$
\begin{aligned}
\bar{K}_{i, \varepsilon}^{C} g(s, \mathbf{y}) & =\int_{-T}^{s} \int_{\mathbb{R}^{N}} \frac{1}{\operatorname{det}\left(\mathbb{M}_{s-t}\right)} \bar{\Delta}^{\frac{\alpha_{i}}{2}, i, s-t} p_{\tilde{S}}\left(s-t, \mathbb{M}_{s-t}^{-1}\left(e^{-(s-t) A} \mathbf{y}-\mathbf{x}\right)\right) \mathbb{I}_{|s-t| \geq \varepsilon} \mathbb{I}_{d((t, \mathbf{x}),(s, \mathbf{y})) \leq c_{0}} g(t, \mathbf{x}) d \mathbf{x} d t \\
& =: \int_{-T}^{s} \int_{\mathbb{R}^{N}} \bar{k}_{i, \varepsilon}^{C}((s, \mathbf{y}),(t, \mathbf{x})) g(t, \mathbf{x}) d \mathbf{x} d t
\end{aligned}
$$

We derive similarly to the previous computations that for all $r \in(1,2]$, there exists $C_{r}$, s.t. for all $g \in L^{r}(\mathcal{S})$, $\left\|\bar{K}_{i, \varepsilon}^{C} g\right\|_{L^{r}(\mathcal{S})} \leq C_{r}\|g\|_{L^{r}(\mathcal{S})}$. The control $\left\|K_{i, \varepsilon}^{C} f\right\|_{L^{p}(\mathcal{S})} \leq C_{p}\|f\|_{L^{p}(\mathcal{S})}$ follows now by duality. Lemma 3.2 eventually readily derives for such $p$ from (5.1) and (5.4).

## Appendix A. Auxiliary Technical Results

Here we give the proof of some technical results for the sake of completeness. We first prove estimate (2.13).
Lemma A.1. There exists a constant $c:=c((\mathbf{A}))>0$, such that for all $t \in[-T, T]$, and all $\mathbf{p} \in \mathbb{R}^{N}$ :

$$
\int_{0}^{1} \int_{\mathbb{S}^{d-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \exp (v A) B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d v \geq c\left|\mathbb{M}_{t} \mathbf{p}\right|^{\alpha}
$$

Proof. Thanks to (ND), we have:

$$
\int_{0}^{1} \int_{\mathbb{S}^{d-1}}\left|\left\langle\mathbb{M}_{t} \mathbf{p}, \exp (v A) B \sigma \mathbf{s}\right\rangle\right|^{\alpha} \mu(d \mathbf{s}) d v \geq c\left|\mathbb{M}_{t} \mathbf{p}\right|^{\alpha} \int_{0}^{1}\left|(\exp (v A) B \sigma)^{*} \frac{\mathbb{M}_{t} \mathbf{p}}{\left|\mathbb{M}_{t} \mathbf{p}\right|}\right|^{\alpha} d v
$$

Defining $\bar{C}:=\inf _{\boldsymbol{\theta} \in \mathbb{S}^{N-1}} \int_{0}^{1}\left|(\exp (v A) B \sigma)^{*} \boldsymbol{\theta}\right|^{\alpha} d v$, it thus actually suffices to prove that $\bar{C}>0$. By continuity of the involved functions and compactness of $\mathbb{S}^{N-1}$, the infimum is actually a minimum. We need to show that this quantity is not zero. Arguing as in PZ09] page 49, we can use the fact that assumptions (UE) and (H) imply the rank condition

$$
\begin{equation*}
\operatorname{Rank}\left[B \sigma, A B \sigma, \ldots, A^{N-1} B \sigma\right]=N \tag{A.1}
\end{equation*}
$$

Here $\left[B \sigma, A B \sigma, \ldots, A^{N-1} B \sigma\right]$ denotes the $N \times N d$ matrix, formed by the matrices $B \sigma, \ldots, A^{N-1} B \sigma$.
Set $M=\sup \left\{\left|(B \sigma)^{*} e^{v A^{*}} \boldsymbol{\theta}\right|: v \in[0,1],|\boldsymbol{\theta}| \in \mathbb{S}^{N-1}\right\}+1$. since $\left|\frac{(B \sigma)^{*} e^{s A^{*}} \boldsymbol{\theta}}{M}\right| \leq 1, s \in[0,1]$, we get

$$
\int_{0}^{1}\left|(B \sigma)^{*} e^{v A^{*}} \boldsymbol{\theta}\right|^{\alpha} d v=M^{\alpha} \int_{0}^{1}\left|\frac{(B \sigma)^{*} e^{v A^{*}} \boldsymbol{\theta}}{M}\right|^{\alpha} d v \geq M^{\alpha} \int_{0}^{1}\left|\frac{(B \sigma)^{*} e^{v A^{*}} \boldsymbol{\theta}}{M}\right|^{2} d v
$$

Let us recall that the rank condition (A.1) implies (actually the two conditions are equivalent) the existence of $C_{1}>0$ such that, for any $u \in \mathbb{R}^{N}, \int_{0}^{1}\left|(B \sigma)^{*} e^{v A^{*}} u\right|^{2} d v \geq C_{1}|u|^{2}$ (see e.g. [PZ09; an alternative proof of this fact can be done following [HM16] (see page 33 in HMP16). This completes the proof.

We now turn to the estimate (4.16) for the derivative of the density $p_{M}$.
Lemma A. 2 (Derivative of the density of the small jumps part.). For all $m \geq 1$ and all multi-indices $\mathbf{i}=$ $\left(i_{1}, \cdots, i_{N}\right) \in \mathbb{N}^{N},|\mathbf{i}|:=\sum_{j=1}^{N}\left|i_{j}\right| \leq 3$, there exists $C_{m, \mathbf{i}}$ s.t. for all $(t, \mathbf{x}) \in \mathbb{R}_{+}^{*} \times \mathbb{R}^{N}$ :

$$
\left|\partial_{\mathbf{x}}^{\mathbf{i}} p_{M}(t, \mathbf{x})\right| \leq \frac{C_{m, \mathbf{i}}}{t^{\frac{N+|\mathbf{i}|}{\alpha}}}\left(1+\frac{|\mathbf{x}|}{t^{\frac{1}{\alpha}}}\right)^{-m}
$$

Proof. Below, similarly to (1.2), we decompose the Lévy measure $\nu_{S}$ of $S$ as

$$
\nu_{S}(D)=\int_{\mathbb{S}^{N-1}} \tilde{\mu}_{S}(d \boldsymbol{\xi}) \int_{0}^{\infty} \mathbb{I}_{D}(r \boldsymbol{\xi}) \frac{d r}{r^{1+\alpha}}, \quad D \in \mathcal{B}\left(\mathbb{R}^{N}\right)
$$

According to (4.13), expressing $p_{M}(t, \mathbf{x})$ as an inverse Fourier transform, for all multi-indices $\mathbf{i}=\left(i^{1}, \cdots, i^{N}\right) \in$ $\mathbb{N}^{N},|\mathbf{i}|:=\sum_{j=1}^{N}\left|i_{j}\right| \leq 3$, we have by the Lévy-Khintchine formula (recall that $\nu_{S}$ is symmetric):

$$
\partial_{\mathbf{x}}^{\mathbf{i}} p_{M}(t, \mathbf{x})=\frac{1}{(2 \pi)^{N}} \int_{\mathbb{R}^{N}} e^{-i\langle\mathbf{p}, \mathbf{x}\rangle}(-i \mathbf{p})^{\mathbf{i}} \exp \left(t \int_{\mathbb{S}^{N-1}} \int_{0}^{\infty}(\cos (\langle\mathbf{p}, r \boldsymbol{\xi}\rangle)-1) \mathbb{I}_{\left\{r \leq t^{\frac{1}{\alpha}}\right\}} \frac{d r}{r^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right) d \mathbf{p}
$$

(recall that we have the term $\cos (\langle\mathbf{p}, r \boldsymbol{\xi}\rangle)-1$ since $\nu_{S}$ is symmetric). Changing variables in $t^{\frac{1}{\alpha}} \mathbf{p}=\mathbf{q}$ yields:

$$
\begin{array}{r}
\partial_{\mathbf{x}}^{\mathbf{i}} p_{M}(t, \mathbf{x})=\frac{t^{-\frac{N+|\mathbf{i}|}{\alpha}}}{(2 \pi)^{N}} \int_{\mathbb{R}^{N}} e^{-i\left\langle\mathbf{q}, \frac{\mathbf{x}}{t^{\frac{1}{\alpha}}}\right\rangle} \\
\cdot(-i \mathbf{q})^{\mathbf{i}} \exp \left(t \int_{\mathbb{S}^{N-1}} \int_{0}^{\infty}\left(\cos \left(\left\langle\mathbf{q}, \frac{r \boldsymbol{\xi}}{t^{\frac{1}{\alpha}}}\right\rangle\right)-1\right) \mathbb{I}_{\left\{r \leq t^{\frac{1}{\alpha}}\right\}} \frac{d r}{r^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right) d \mathbf{q}
\end{array}
$$

Observe that changing variables to $\rho=r t^{-\frac{1}{\alpha}}$, we have:

$$
\begin{aligned}
& \mathbf{q}^{\mathbf{i}} \exp \left(t \int_{\mathbb{S}^{N-1}} \int_{0}^{\infty}\left(\cos \left(\left\langle\mathbf{q}, \frac{r \boldsymbol{\xi}}{t^{\frac{1}{\alpha}}}\right\rangle\right)-1\right) \mathbb{I}_{\left\{r \leq t^{\frac{1}{\alpha}}\right\}} \frac{d r}{r^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right) \\
= & \mathbf{q}^{\mathbf{i}} \exp \left(-\int_{\mathbb{S}^{N-1}} \int_{0}^{\infty}(1-\cos \langle\mathbf{q}, \rho \boldsymbol{\xi}\rangle) \mathbb{I}_{\{\rho \leq 1\}} \frac{d \rho}{\rho^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right)=: \hat{f}(\mathbf{q}) .
\end{aligned}
$$

It is not difficult to differentiate under the integral sign and get that $\hat{f}$ is infinitely differentiable as a function of $\mathbf{q}$ (cf. Theorem 3.7.13 in Jac05). Besides, we can bound the truncated measure by the complete one, up to a multiplicative constant. Since $\mathbb{I}_{\{\rho \leq 1\}}=1-\mathbb{I}_{\{\rho>1\}}$, we obtain

$$
\begin{aligned}
|\hat{f}(\mathbf{q})| & \leq\left|\mathbf{q}^{\mathbf{i}}\right| \exp \left(\frac{2}{\alpha} \tilde{\mu}_{S}\left(\mathbb{S}^{N-1}\right)\right) \exp \left(-\int_{\mathbb{S}^{N-1}} \int_{0}^{\infty}(1-\cos \langle\mathbf{q}, \rho \boldsymbol{\xi}\rangle) \frac{d \rho}{\rho^{1+\alpha}} \tilde{\mu}_{S}(d \boldsymbol{\xi})\right) \\
& \leq C|\mathbf{q}|^{[\mathbf{i} \mid} \exp \left(-\int_{\mathbb{S}^{N-1}}|\langle\mathbf{q}, \boldsymbol{\xi}\rangle|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right) \leq C|\mathbf{q}|^{|\mathbf{i}|} e^{-c^{-1}|\mathbf{q}|^{\alpha}},
\end{aligned}
$$

using that the spectral measure $\mu_{S}$ satisfies the non-degeneracy condition (ND) for the last inequality. Thus, $\hat{f}$ belongs the Schwartz space $\mathscr{S}\left(\mathbb{R}^{N}\right)$. Denoting by $f$ its Fourier transform, we have:

$$
\forall m \geq 0, \exists C_{m} \geq 1, \forall \mathbf{z} \in \mathbb{R}^{N},|f(\mathbf{z})| \leq C_{m}(1+|\mathbf{z}|)^{-m}
$$

Now since $\left|\partial_{\mathbf{x}}^{\mathbf{i}} p_{M}(t, \mathbf{x})\right|=t^{-\frac{N+|\mathbf{i}|}{\alpha}}\left|f\left(\frac{\mathbf{x}}{t^{\frac{1}{\alpha}}}\right)\right|$, the announced bound follows.
Appendix B. $L^{p}$ estimates for the local case $\alpha=2$
We focus here on the case $\alpha=2$, i.e. $L_{\sigma}=\frac{1}{2} \operatorname{Tr}\left(\sigma \sigma^{*} D_{\mathbf{x}_{1}}^{2}\right)$. In this simpler case our main results of Theorems 1.1 and 2.14 continue to hold. Let us consider parabolic estimates in Theorem 2.14. We only show how to prove the result following our previous arguments.

We first note that the case $\alpha_{1}=\alpha=2$ follows by BCM96] and BCLP10. On the other hand we concentrate on the new case when $i \in \llbracket 2, n \rrbracket$. We start as in Section 2 for $t>0$ :

$$
\Lambda_{t}^{\mathbf{x}}=e^{t A} \mathbf{x}+\int_{0}^{t} e^{(t-s) A} B \sigma d W_{s}
$$

where $W=\left(W_{t}\right)$ is a $d$-dimensional Wiener process. Here we use an alternative approach to obtain an analogous of (2.10) (this more probabilistic approach could be also used in stable case of Section 2).
By the independence of increments of the Wiener process, the Fourier transform shows that

$$
\begin{equation*}
\Lambda_{t}^{\mathbf{x}} \stackrel{(\text { law })}{=} e^{t A} \mathbf{x}+\int_{0}^{t} e^{s A} B \sigma d W_{s} \tag{B.2}
\end{equation*}
$$

Using that $e^{r t A}=\mathbb{M}_{t} e^{r A} \mathbb{M}_{t}^{-1}$ (see (2.7)) and the fact that $\mathbb{M}_{t}^{-1} B \sigma=B \sigma$ we obtain

$$
\begin{aligned}
J_{t}=\int_{0}^{t} e^{s A} B \sigma d W_{s} \stackrel{(\text { law })}{=} t^{1 / 2} & \int_{0}^{1} e^{r t A} B \sigma d W_{r}=t^{1 / 2} \mathbb{M}_{t} \int_{0}^{1} e^{r A} B \sigma d W_{r}=\mathbb{M}_{t} S_{t} \\
& \text { with } S_{t}=t^{1 / 2} \int_{0}^{1} e^{r A} B \sigma d W_{r} \stackrel{(\text { law })}{=} \mathbf{K} \mathbf{W}_{\mathbf{t}}, \quad t \geq 0
\end{aligned}
$$

where $\mathbf{K}$ is an $N \times N$ square root of the non degenerate matrix $\boldsymbol{\Gamma}=\int_{0}^{1} e^{A s} B \sigma \sigma^{*} B^{*} e^{A^{*} s} d s$ (the non degeneracy follows by our assumptions on $\sigma$ and $A$ ), i.e. $\boldsymbol{\Gamma}=\mathbf{K K}^{*}$, and $\left(\mathbf{W}_{\mathbf{t}}\right)$ is a standard $N$-dimensional Wiener process.

The structure of (2.8) in Proposition 2.3 still holds in the limit case, replacing $\exp \left(-t \int_{\mathbb{S}^{N-1}}|\langle\mathbf{p}, \boldsymbol{\xi}\rangle|^{\alpha} \mu_{S}(d \boldsymbol{\xi})\right)$ with $\exp \left(-\frac{t}{2}\langle\Gamma \mathbf{p}, \mathbf{p}\rangle\right)$. Observe as well that we can enter the previous framework constructing a symmetric measure $\mu_{S}$ on $\mathbb{S}^{N-1}$ s.t. $\int_{\mathbb{S}^{N-1}} \mathbf{p}^{*} \boldsymbol{\theta} \boldsymbol{\theta}^{*} \mathbf{p} \mu_{S}(d \boldsymbol{\theta})=\int_{\mathbb{S}^{N-1}}|\langle\mathbf{p}, \boldsymbol{\theta}\rangle|^{2} \mu_{S}(d \boldsymbol{\theta})=\frac{\langle\Gamma \mathbf{p}, \mathbf{p}\rangle}{2}$. Denoting by $\mathbf{K}_{i}$ the $i^{\text {th }}$ column of $\mathbf{K}$, one can take $\mu_{S}=\frac{1}{4} \sum_{i=1}^{N}\left|\mathbf{K}_{i}\right|\left(\delta_{\frac{\mathbf{K}_{i}}{\left|\mathbf{K}_{i}\right|}}+\delta_{-\frac{\mathbf{K}_{i}}{\left|\mathbf{K}_{i}\right|}}\right)$, where $\delta_{\mathbf{u}}$ stands for the Dirac mass at point $\mathbf{u}$.

The Fourier argument of Lemma 4.1 still apply and the $L^{2}$ control stated therein remains valid. Observe that, to investigate the $L^{p}$ case for $p \neq 2$, we clearly need to consider the quasi-distance in (3.10) with $\alpha=2$.

For Lemma 4.2 the case $i=1$ involves the local operator $\Delta_{\mathbf{x}_{1}}$. Such deviations results have been proved in this framework by Bramanti et al. BCM96] (see Proposition 3.4 therein). We thus focus on the new contributions associated with $i \in \llbracket 2, n \rrbracket$, which involve the operators $\left(\Delta_{\mathbf{x}_{i}}^{\frac{1}{1+2(i-1)}}\right)_{i \in \llbracket 2, n \rrbracket}$. For those contributions, the proof of Lemma 4.2 remains the same provided we prove the key controls of Lemmas 4.3 and 4.4 We present below a proof of Lemma 4.3 for $\alpha=2$. With this result, Lemma 4.4 still holds for $\alpha=2$ with the same proof. The final derivation of the main results of Theorems 1.1 and 2.4 is then the same as in Section 2 and Sections 3 r5 respectively.

Proof of Lemma 4.3 for $\alpha=2$ and $i \in \llbracket 2, n \rrbracket$. Observe indeed that for such indexes the correspondence (3.6) still holds. The main difference with the case $\alpha \in(0,2)$ that we considered before is that we do not use the previous decomposition (4.15), which splits for $\alpha \in(0,2)$ the small and large jumps, but directly exploit the Gaussian character of $p_{S}(t, \cdot)$.

Let us prove point (ii). With the notations of (4.12), i.e. $\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}, i, A, t, l} p_{S}(t, \cdot), \Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}, i, A, t, s} p_{S}(t, \cdot)$ corresponding respectively to the large and small jumps part in the operator, we rewrite for all $t>0,\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in \mathbb{R}^{2 N}$ :

$$
=\left(\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}, i, A, t, l} p_{S}(t, \mathbf{x})-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}, i, A, t, l} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right)+\left(\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{\frac{\alpha_{i}}{2}}, i, i, A, t, t, s} p_{S}(t, \mathbf{x})-\Delta_{\mathbf{x}_{i}}^{\frac{\alpha_{i}}{2}, i, A, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right) .
$$

Similarly to 4.19),

$$
\begin{array}{r}
\leq\left(\int_{|z| \geq t^{\frac{1}{\alpha_{i}}}}\left|p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right| \frac{d z}{|z|^{d_{i}+\alpha_{i}}}\right) \\
+\left(\frac{C}{t}\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|\right)=:\left(I_{i, 1}+I_{2}\right)\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right) \tag{B.3}
\end{array}
$$

In the current Gaussian case, a control similar to the previous 4.20) also holds. Precisely, for all $t>0,\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in$ $\mathbb{R}^{2 N}, \beta \in(0,1]:$

- If $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \geq t^{\frac{1}{2}}$, then $\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta}\left(p_{S}(t, \mathbf{x})+p_{S}\left(t, \mathbf{x}^{\prime}\right)\right)$.
- If $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{2}}$, then usual computations yield (using also $(a-b)^{2} \geq \frac{a^{2}}{2}-b^{2}$ ):

$$
\begin{aligned}
\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| & \leq \int_{0}^{1}\left|\nabla p_{S}\left(t, \mathbf{x}^{\prime}+\lambda\left(\mathbf{x}-\mathbf{x}^{\prime}\right)\right)\right|\left|\mathbf{x}-\mathbf{x}^{\prime}\right| d \lambda \leq C \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1+N}{2}}} \exp \left(-\frac{c}{t}\left(\frac{1}{2}\left|\mathbf{x}^{\prime}\right|^{2}-\left|\mathbf{x}-\mathbf{x}^{\prime}\right|^{2}\right)\right) \\
& \leq C\left|\mathbf{x}-\mathbf{x}^{\prime}\right|^{\beta} t^{-\frac{\beta}{2}} g_{c}\left(t, \mathbf{x}^{\prime}\right)
\end{aligned}
$$

where $C \geq 1,0<c \leq 1$, and the Gaussian density

$$
g_{c}(t, \mathbf{z}):=\frac{c^{\frac{N}{2}}}{(2 \pi t)^{\frac{N}{2}}} \exp \left(-c \frac{|\mathbf{z}|^{2}}{2 t}\right)=p_{\bar{S}}(t, \mathbf{z}), \quad t>0, \mathbf{z} \in \mathbb{R}^{N},
$$

verifies: $\left|\partial_{\mathbf{x}}^{\mathbf{i}} p_{S}(t, \mathbf{x})\right| \leq \bar{C}_{\mathbf{i}} t^{-\frac{1 \mathbf{i}}{2}} g_{c}(t, \mathbf{x})$, for all $\mathbf{i}=\left(i^{1}, \cdots, i^{N}\right) \in \mathbb{N}^{N},|\mathbf{i}|:=\sum_{j=1}^{N} i_{j} \leq 2, t>0, \mathbf{x} \in \mathbb{R}^{N}$.
Hence, by symmetry we derive:

$$
\begin{equation*}
\left|p_{S}(t, \mathbf{x})-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right| \leq C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta}\left(g_{c}(t, \mathbf{x})+g_{c}\left(t, \mathbf{x}^{\prime}\right)\right)=: C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \tag{B.4}
\end{equation*}
$$

From (B.4) and (B.3) we get:

$$
\begin{align*}
\left|I_{i, 1}\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right)\right| & \leq C\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta} \int_{|z| \geq t^{\frac{1}{\alpha_{i}}}}\left(p_{\bar{S}}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) \frac{d z}{|z|^{d_{i}+\alpha_{i}}}  \tag{B.5}\\
& =: \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta} \int_{\mathbb{R}^{d_{i}}}\left(p_{\bar{S}}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) f_{\Gamma^{i}}(t, z)(d z),
\end{align*}
$$

setting $f_{\Gamma^{i}}(t, z):=t c_{\alpha, d_{i}} \mathbb{I}_{|z| \geq t^{\frac{1}{\alpha_{i}}}} \frac{1}{|z|^{d_{i}+\alpha_{i}}}$ with $c_{\alpha, d_{i}}>0$ s.t. $\int_{\mathbb{R}^{d_{i}}} f_{\Gamma^{i}}(t, z) d z=1$. Hence, $f_{\Gamma^{i}}(t, \cdot)$ is the density
 respectively, of the random variable

$$
\begin{equation*}
\bar{S}_{t}^{i, 1}:=\bar{S}_{t}+t^{-(i-1)}\left(e^{A}\right)_{i} \Gamma_{t}^{i} \tag{B.6}
\end{equation*}
$$

where $\bar{S}_{t}=c_{1} \mathbf{W}_{\mathbf{t}}$ has density $p_{\bar{S}}(t, \cdot)$ (the process $\left(\bar{S}_{t}\right)_{t \geq 0}$ is proportional to a standard $N$-dimensional Wiener process $\mathbf{W})$ and $\Gamma_{t}^{i}$ is independent of $\bar{S}_{t}$ and has density $f_{\Gamma^{i}}(t, \cdot)$. We finally obtain,

$$
\begin{equation*}
\left|I_{i, 1}\left(t, \mathbf{x}, \mathbf{x}^{\prime}\right)\right| \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta}\left(p_{\bar{S}^{i}, 1}(t, \mathbf{x})+p_{\bar{S}^{i}, 1}\left(t, \mathbf{x}^{\prime}\right)\right) . \tag{B.7}
\end{equation*}
$$

From the definition of $\alpha_{i}=\frac{2}{1+2(i-1)}$ and (B.6), one can check that $\bar{S}_{t}^{i, 1} \stackrel{(\text { law }}{=} t^{\frac{1}{2}} \bar{S}_{1}^{i, 1}$ and similarly to (4.24) that the density $p_{\bar{S} i, 1}(t, \cdot)$ of the random variable $\bar{S}_{t}^{i, 1}$ satisfies (4.8). Here, the integrability constraint is still given by $\Gamma_{t}^{i}$, there are no constraints on $\bar{S}_{t}$ which is Gaussian. The controls for $\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, l} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|$ follows plugging (B.7) and (B.5) into (B.3) defining $q(t, \cdot):=\frac{1}{n+1}\left(\sum_{i=1}^{n} p_{\overline{S^{i}, 1}}+p_{\bar{S}}\right)(t, \cdot)$.

It remains to control the difference associated with the small jumps part. Write

$$
\begin{align*}
& \Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)  \tag{B.8}\\
= & \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}}\left[\left(p_{S}\left(t, \mathbf{x}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}(t, \mathbf{x})\right)-\left(p_{S}\left(t, \mathbf{x}^{\prime}+t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-p_{S}\left(t, \mathbf{x}^{\prime}\right)\right)\right] \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
= & \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{0}^{1} d \mu\left(\nabla p_{S}\left(t, \mathbf{x}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z\right)-\nabla p_{S}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) \cdot t^{-(i-1)}\left(e^{A}\right)_{i} z \frac{d z}{|z|^{d_{i}+\alpha_{i}}},
\end{align*}
$$

Usual Gaussian calculations then give that, if $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{2}}$ :

$$
\begin{array}{r}
\leq C \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{0}^{1} d \mu \int_{0}^{1} d \lambda g_{c}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z+\lambda\left(\mathbf{x}-\mathbf{x}^{\prime}\right)\right)|z| t^{-(i-1)} \frac{d z}{|z|^{d_{i}+\alpha_{i}}}  \tag{B.9}\\
\leq C \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t} g_{c}\left(t, \mathbf{x}^{\prime}\right) \int_{|z| \leq t^{\frac{\alpha_{i}}{\alpha_{i}}}} t^{-(i-1)}|z| \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \leq \frac{C}{t} \frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}} p_{\bar{S}}(t, \mathbf{x}) \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta} p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right) .
\end{array}
$$

We recall here that the second inequality follows from the fact that on the considered set, i.e. $\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq t^{\frac{1}{2}}$, $|z| \leq t^{\frac{1}{\alpha_{i}}}$, since $\alpha_{i}=\frac{2}{1+(i-1) 2}$, we have that $t^{-(i-1)}\left|\left(e^{A}\right)_{i} z\right|+\left|\mathbf{x}-\mathbf{x}^{\prime}\right| \leq C t^{\frac{1}{2}}$. Hence, there exists $C>0$ s.t. for all $(\lambda, \mu) \in[0,1]^{2}$,

$$
g_{c}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z+\lambda\left(\mathbf{x}-\mathbf{x}^{\prime}\right)-\boldsymbol{\xi}\right) \leq C g_{c}\left(t, \mathbf{x}^{\prime}-\boldsymbol{\xi}\right)
$$

up to a modification of $c$ (cf. (4.26) for a similar estimate). We have exploited as well that:

$$
t^{-(i-1)} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \frac{|z|}{|z|^{d_{i}+\alpha_{i}}} d z \leq C_{\alpha, i} t^{-(i-1)} t^{-1+\frac{1}{\alpha_{i}}}=C_{\alpha, i} t^{-1+\frac{1}{2}}
$$

If now $\left|\mathbf{x}-\mathbf{x}^{\prime}\right|>t^{\frac{1}{\alpha}}$, we derive from (B.8):

$$
\begin{array}{r}
\leq \frac{C}{t^{\frac{1}{2}}} \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} \int_{0}^{1} d \mu\left(p_{S}\left(t, \mathbf{x}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z\right)+p_{S}\left(t, \mathbf{x}^{\prime}+\mu t^{-(i-1)}\left(e^{A}\right)_{i} z\right)\right) \\
\times t^{-(i-1)}|z| \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \leq \frac{C}{t^{\frac{1}{2}}}\left(g_{c}(t, \mathbf{x})+g_{c}\left(t, \mathbf{x}^{\prime}\right)\right) \int_{|z| \leq t^{\frac{1}{\alpha_{i}}}} t^{-(i-1)}|z| \frac{d z}{|z|^{d_{i}+\alpha_{i}}} \\
\leq \frac{C}{t}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right) \leq \frac{C}{t}\left(\frac{\left|\mathbf{x}-\mathbf{x}^{\prime}\right|}{t^{\frac{1}{2}}}\right)^{\beta}\left(p_{\bar{S}}(t, \mathbf{x})+p_{\bar{S}}\left(t, \mathbf{x}^{\prime}\right)\right)
\end{array}
$$

Equations (B.9) and (B.10) give the stated control for $\left|\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}(t, \mathbf{x})-\Delta^{\frac{\alpha_{i}}{2}, A, i, t, s} p_{S}\left(t, \mathbf{x}^{\prime}\right)\right|$. This completes the proof of (ii) for $\alpha=2$. The controls (i) and (iii) are obtained following the lines of the proof of Lemma 4.3 with the above modifications.

## Appendix C. Singular integrals in homogeneous spaces

C.1. The main result. We recall here the basic Coifmann-Weiss theorem on singular integrals (see CW71). Let $X$ be a set. A function $d: X \times X \rightarrow \mathbb{R}_{+}$is called a quasi-distance if it satisfies :

1) $d(x, y)>0$ if and only if $x \neq y$;
2) $d(x, y)=d(y, x)$, for $x, y \in X$;
3) there exists $C>0$ such that $d(x, z) \leq C(d(x, y)+d(y, z))$, for $x, y, z \in X$.

We also introduce related balls $B(x, r)=\{y \in X: d(y, x)<r\}, x \in X, r>0$, which form a complete system of neighbourhoods of $X$, so that $X$ is a Hausdorff space. We require that balls are open sets in this topology.

A homogeneous space is a triple $(X, d, \mu)$ where $d$ is a quasi-distance and $\mu$ is a Borel measure such that there exists $A>0$ for which

$$
\begin{equation*}
0<\mu(B(x, 2 r)) \leq A \mu(B(x, r))<\infty, \quad x \in X, \quad r>0 \tag{C.11}
\end{equation*}
$$

Theorem C.1. [Coifman-Weiss] Let $(X, d, \mu)$ be a homogeneous space. Let $k(x, y) \in L^{2}(X \times X, \mu \otimes \mu)$ and consider the operator $K: L^{2}(X, \mu) \rightarrow L^{2}(X, \mu), K f(x)=\int_{X} k(x, y) f(y) \mu(d y), f \in L^{2}(X, \mu)$. Assume that

H1) There exists $C_{1}>0$ such that $\|K f\|_{L^{2}} \leq C_{1}\|f\|_{L^{2}}$, for any $f \in L^{2}(X, \mu)$.
H2) There exists $C_{2}, C_{3}>0$ such that, for any $y, y_{0} \in X$,

$$
\int_{d\left(x, y_{0}\right)>C_{2} d\left(y, y_{0}\right)}\left|k(x, y)-k\left(x, y_{0}\right)\right| \mu(d x) \leq C_{3}
$$

Then, for any $p \in(1,2]$ there exists $A_{p}$ (depending on $\left.p, C_{i}, i=1,2,3\right)$ such that for $f \in L^{2} \cap L^{p}$ one has:

$$
\|K f\|_{L^{p}} \leq A_{p}\|f\|_{L^{p}}
$$

Moreover, there exists $A_{1}>0$, such that $\mu(x \in X:|K f(x)|>\alpha) \leq \frac{A_{1}}{\alpha}\|f\|_{L^{1}}, \alpha>0, f \in L^{1} \cap L^{2}$.
C.2. The $\operatorname{Strip} \mathcal{S}$ viewed as a Homogeneous space. We eventually need the following topological result. Similar results can be found in [BCM96] and FP06.
Proposition C.2. Let $d$ be as in (3.10) with $\alpha \in(0,2]$. Then $d$ is a quasi-distance on $\mathcal{S}$, i.e. $d(t, \mathbf{x}),(s, \mathbf{y}))=$ 0 if and only if $(t, \mathbf{x})=(s, \mathbf{y})$, d is symmetric and moreover there exists $C=C((\mathbf{A}))>0$, s.t. for all $(t, \mathbf{x}),(\sigma, \boldsymbol{\xi}),(s, \mathbf{y}) \in \mathcal{S}^{3}:$

$$
\begin{equation*}
d((t, \mathbf{x}),(s, \mathbf{y})) \leq C(d((t, \mathbf{x}),(\sigma, \boldsymbol{\xi}))+d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y}))) \tag{C.12}
\end{equation*}
$$

Also, $(\mathcal{S}, d, \mu)$ where $\mu$ is the Lebesgue measure is a homogeneous space.

Proof. Let us first deal with the quasi-triangle inequality. Introduce for $\mathbf{z} \in \mathbb{R}^{N}$ :

$$
\rho_{\mathrm{Sp}}(\mathbf{z})=\sum_{i=1}^{n}\left|\mathbf{z}_{i}\right|^{\frac{1}{1+\alpha(i-1)}},
$$

which corresponds to the spatial contribution in the definition of $\rho$ in (2.2). For $(t, \mathbf{x}),(\sigma, \boldsymbol{\xi}),(s, \mathbf{y}) \in \mathcal{S}^{3}$ write:

$$
\begin{align*}
d((t, \mathbf{x}),(s, \mathbf{y})) \leq & \frac{1}{2}\left(2|t-s|^{\frac{1}{\alpha}}+\rho_{\mathrm{Sp}}\left(e^{(s-t) A} \mathbf{x}-e^{(s-\sigma) A} \boldsymbol{\xi}\right)+\rho_{\mathrm{Sp}}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right. \\
& \left.+\rho_{\mathrm{Sp}}\left(\mathbf{x}-e^{(t-\sigma) A} \boldsymbol{\xi}\right)+\rho_{\mathrm{Sp}}\left(e^{(t-\sigma) A} \boldsymbol{\xi}-e^{(t-s) A} \mathbf{y}\right)\right) \tag{C.13}
\end{align*}
$$

In the sequel consider $r, u \in \mathbb{R}, \mathbf{x}, \boldsymbol{\xi} \in \mathbb{R}^{N}$. There exists $C=C(A)>0$ such that

$$
\begin{equation*}
\rho_{\mathrm{Sp}}\left(e^{(r+u) A} \mathbf{x}-e^{r A} \boldsymbol{\xi}\right) \leq C\left(\rho_{\mathrm{Sp}}\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)+|r|^{\frac{1}{\alpha}}\right)=C \rho\left(r, e^{u A} \mathbf{x}-\boldsymbol{\xi}\right) \tag{C.14}
\end{equation*}
$$

Indeed, observe that (using the structure of the matrix $e^{t A}$, as established in 4.47) ):

$$
\begin{array}{r}
\rho_{\mathrm{Sp}}\left(e^{(r+u) A} \mathbf{x}-e^{r A} \boldsymbol{\xi}\right)=\rho_{\mathrm{Sp}}\left(e^{r A}\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)\right)=\sum_{i=1}^{n}\left|\left(e^{r A}\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}} \\
\leq C \sum_{i=1}^{n}\left(\sum_{j=1}^{i}|r|^{i-j}\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{j}\right|\right)^{\frac{1}{1+\alpha(i-1)}} \leq C \sum_{i=1}^{n} \sum_{j=1}^{i}|r|^{\frac{i-j}{\alpha(i-1)+1}}\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{j}\right|^{\frac{1}{1+\alpha(i-1)}} \\
\leq C \sum_{i=1}^{n}\left(\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}+\sum_{j=1}^{i-1}|r|^{\frac{i-j}{1+\alpha(i-1)}}\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{j}\right|^{\frac{1}{1+\alpha(i-1)}}\right)
\end{array}
$$

with the convention that $\sum_{j=1}^{0}=0$. For each entry in the sum over $j$ we now use the Young inequality with exponents, $q_{j}=\frac{1+\alpha(i-1)}{1+\alpha(j-1)}>1, p_{j}=\left(1-\frac{1+\alpha(j-1)}{1+\alpha(i-1)}\right)^{-1}=\left(\alpha \frac{i-j}{1+\alpha(i-1)}\right)^{-1}=\frac{1}{\alpha} \frac{1+\alpha(i-1)}{i-j}$. Hence:

$$
\begin{aligned}
\rho_{\mathrm{Sp}}\left(e^{(r+u) A} \mathbf{x}-e^{r A} \boldsymbol{\xi}\right) \leq & C \sum_{i=1}^{n}\left(\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}+\sum_{j=1}^{i-1}\left[\frac{|r|^{\frac{1}{\alpha}}}{p_{j}}+\frac{\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{j}\right|^{\frac{1}{1+\alpha(j-1)}}}{q_{j}}\right]\right) \\
& \leq C\left(\sum_{i=1}^{n}\left|\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)_{i}\right|^{\frac{1}{1+\alpha(i-1)}}+|r|^{\frac{1}{\alpha}}\right)=C\left(\rho_{\mathrm{Sp}}\left(e^{u A} \mathbf{x}-\boldsymbol{\xi}\right)+|r|^{\frac{1}{\alpha}}\right)
\end{aligned}
$$

By (C.14) we derive $\rho_{\mathrm{Sp}}\left(e^{(s-t) A} \mathbf{x}-e^{(s-\sigma) A} \boldsymbol{\xi}\right) \leq C\left(\rho_{\mathrm{Sp}}\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)+|s-\sigma|^{\frac{1}{\alpha}}\right)$, with $r=s-\sigma$ and $u=\sigma-t$.
Similarly, one get: $\rho_{\mathrm{Sp}}\left(e^{(t-\sigma) A}\left(\boldsymbol{\xi}-e^{(\sigma-s) A} \mathbf{y}\right)\right) \leq C\left(|t-\sigma|^{\frac{1}{\alpha}}+\rho_{\mathrm{Sp}}\left(\boldsymbol{\xi}-e^{(\sigma-s) A} \mathbf{y}\right)\right)$. We obtain in (C.13):

$$
\begin{aligned}
d((t, \mathbf{x}),(s, \mathbf{y})) \leq & C\left(|t-\sigma|^{\frac{1}{\alpha}}+|s-\sigma|^{\frac{1}{\alpha}}+\rho_{\mathrm{Sp}}\left(e^{(\sigma-t) A} \mathbf{x}-\boldsymbol{\xi}\right)+\rho_{\mathrm{Sp}}\left(e^{(s-\sigma) A} \boldsymbol{\xi}-\mathbf{y}\right)\right. \\
& \left.+\rho_{\mathrm{Sp}}\left(\mathbf{x}-e^{(t-\sigma) A} \boldsymbol{\xi}\right)+\rho_{\mathrm{Sp}}\left(\boldsymbol{\xi}-e^{(\sigma-s) A} \mathbf{y}\right)\right) \leq C(d((t, \mathbf{x}),(\sigma, \boldsymbol{\xi}))+d((\sigma, \boldsymbol{\xi}),(s, \mathbf{y})))
\end{aligned}
$$

This proves (C.12).
Let us now define the $d$-balls and check the doubling property. Namely, for a point $(t, \mathbf{x}) \in \mathcal{S}$ and a given $\delta$, we introduce: $B((t, \mathbf{x}), \delta):=\{(s, \mathbf{y}) \in \mathcal{S}: d((t, \mathbf{x}),(s, \mathbf{y}))<\delta\}$. From the above definition, (3.10) and the invariance of the Lebesgue measure $|\cdot|$ by translation, recalling as well that for all $r \in \mathbb{R}, \operatorname{det}\left(e^{r A}\right)=1$, we obtain that there exists $c:=c((\mathbf{A}))>0$ s.t. for all $\delta>0,(t, \mathbf{x}) \in \mathcal{S}$,

$$
\begin{equation*}
|B((t, \mathbf{x}), \delta)| \leq c \delta^{\alpha+\sum_{i=1}^{n} d_{i}(1+(i-1) \alpha)}=c \delta^{\alpha+N+\sum_{i=1}^{n} d_{i}(i-1) \alpha} \tag{C.15}
\end{equation*}
$$

Assume now that the following control holds: there exists $\kappa:=\kappa((\mathbf{A}))>1$ s.t. for all $((t, \mathbf{x}),(s, \mathbf{y})) \in \mathcal{S}^{2}$

$$
\begin{equation*}
\kappa^{-1} \rho\left(s-t, \mathbf{x}-e^{(t-s) A} \mathbf{y}\right) \leq \rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right) \leq \kappa \rho\left(s-t, \mathbf{x}-e^{(t-s) A} \mathbf{y}\right) \tag{C.16}
\end{equation*}
$$

Equation (C.16) means that we have equivalence of the contributions associated with the forward and backward flows for the homogeneous pseudo-norm $\rho$. Then, introducing

$$
\bar{B}((t, \mathbf{x}), \delta):=\left\{(s, \mathbf{y}) \in \mathcal{S}: \rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)<\frac{2 \delta}{1+\kappa}\right\}
$$

we have that $\bar{B}((t, \mathbf{x}), \delta) \subset B((t, \mathbf{x}), \delta)$. Indeed, for all $(s, \mathbf{y}) \in \bar{B}((t, \mathbf{x}), \delta)$,

$$
\begin{aligned}
d((t, \mathbf{x}),(s, \mathbf{y})) & =\frac{1}{2}\left(\rho\left(t-s, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)+\rho\left(t-s, \mathbf{x}-e^{(t-s) A} \mathbf{y}\right)\right) \\
& \leq \frac{1}{2}(1+\kappa) \rho\left(s-t, e^{(s-t) A} \mathbf{x}-\mathbf{y}\right)<\delta
\end{aligned}
$$

using (C.16) for the penultimate inequality. Since we also have, up to a modification of $c$ in (C.15), that for all $(t, \mathbf{x}) \in \mathcal{S}, \delta>0,|\bar{B}((t, \mathbf{x}), \delta)| \geq c^{-1} \delta^{\alpha+N+\sum_{i=1}^{n} d_{i}(i-1) \alpha}$, we finally get:

$$
c^{-1} \delta^{\alpha+N+\sum_{i=1}^{n} d_{i}(i-1) \alpha} \leq|B((t, \mathbf{x}), \delta)| \leq c \delta^{\alpha+N+\sum_{i=1}^{n} d_{i}(i-1) \alpha}
$$

which gives the doubling property of the $d$-balls in $\mathcal{S}$.
It only remains to prove (C.16). It is enough to prove that there exists $C>0$ s.t., for any $r \in \mathbb{R}, \mathbf{x}, \boldsymbol{\xi} \in \mathbb{R}^{N}$,

$$
\begin{equation*}
\rho\left(r, \mathbf{x}-e^{r A} \boldsymbol{\xi}\right) \leq C \rho\left(r, e^{-r A} \mathbf{x}-\boldsymbol{\xi}\right) \tag{C.17}
\end{equation*}
$$

This follows easily from (C.14) with $u=-r$.

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[^0]:    ${ }^{1}$ We use from now on the notation $\llbracket \cdot, \cdot \rrbracket$ for integer intervals.

[^1]:    ${ }^{2}$ The stable process $S$ is non-degenerate in the sense that its spectral measure $\mu_{S}$ satisfies 1.3 on $\mathbb{R}^{N}$. However, we point out that $\mu_{S}$ can be very singular w.r.t. to the surface measure of $\mathbb{S}^{N-1}$.

