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RESEARCH LETTER

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Key Points:

- *T* phase arrivals at Ascension Island can be linked to a submarine eruption at Monowai, Kermadec Arc
- *T* phases must have traveled along the SOFAR channel and over a geodesic range of ~15,800 km
- Our results are confirmed by correlation with broadband seismic data and transmission loss modeling

Supporting Information:

- Supporting Information S1

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Ultra-long-range hydroacoustic observations of submarine volcanic activity at Monowai, Kermadec Arc

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Abstract Monowai is an active submarine volcanic center in the Kermadec Arc, Southwest Pacific Ocean. During May 2011, it erupted over a period of 5 days, with explosive activity directly linked to the generation of seismoacoustic *T* phases. We show, using cross-correlation and time-difference-of-arrival techniques, that the eruption is detected as far as Ascension Island, equatorial South Atlantic Ocean, where a bottom moored hydrophone array is operated as part of the International Monitoring System of the Comprehensive Nuclear-Test-Ban Treaty Organization. Hydroacoustic phases from the volcanic center must therefore have propagated through the Sound Fixing and Ranging channel in the South Pacific and South Atlantic Oceans, a source-receiver distance of ~15,800 km. We believe this to be the furthest documented range of a naturally occurring underwater signal above 1 Hz. Our findings, which are consistent with observations at regional broadband stations and long-range, acoustic parabolic equation modeling, have implications for submarine volcano monitoring.

1. Introduction

Estimations on the number of active volcanoes in the world's oceans range from hundreds to thousands, and only a few active sites have been studied in detail due to their inherent inaccessibility. Monowai Volcanic Centre at 25.89°S, 177.18°W in the northern Kermadec Arc comprises an active submarine stratovolcanic cone, a number of parasitic cones, and a flanking caldera with a small central dome [e.g., *Wormald et al.*, 2012; *Paulatto et al.*, 2014]. The center has a well-documented record of more than five decades of activity [e.g., *Davey*, 1980; *Talandier and Okal*, 1987], including discolored surface water, intermittent observations of changes of seafloor depth due to ongoing magmatic activity, large-scale sector collapses, and swarms of tertiary phase arrivals ("*T* phases") recorded at broadband seismic stations in the southwest Pacific region [*Wright et al.*, 2008; *Chadwick et al.*, 2008a]. Repeat swath bathymetric mapping has revealed the highly dynamic nature of Monowai cone, the summit of which has shallowed by ~67 m since 2004. Its most recent documented eruption was during 14 May to 1 June 2011, when significant morphological differences were observed aboard R/V SONNE (expedition SO215), including the development of a ~72 m high-summit cone and a flanking sector collapse of ~18 m [*Watts et al.*, 2012]. During this period, a 5 day long burst of *T* phases was recorded at broadband seismic stations on Rarotonga (Cook Islands), Papeete (Tahiti), and Marquesas Islands (Figure 1a), thereby directly linking seismoacoustic observations and changes in seafloor depth due to submarine volcanic activity for the first time. Apart from the Monowai Volcanic Centre, recent reports of *T* phases generated by submarine explosive volcanism along the wider Tonga-Kermadec area include West Mata, Hunga Ha'apai-Hunga, and Brothers Volcano [*Dziak et al.*, 2008; *Bohnenstiehl et al.*, 2014].

T phases are low-frequency sound waves that travel in the Sound Fixing and Ranging (SOFAR) channel, a distinct layer of low sound wave speed in the oceanic water column [*Tolstoy et al.*, 1949; *Ewing et al.*, 1951]. The SOFAR channel effectively serves as an acoustic waveguide for underwater signals of various origins, with the large majority generated by earthquakes at plate boundaries, for example, along subduction zones and mid-oceanic ridge crests [*Smith et al.*, 2002; *Graeber and Piserchia*, 2004]. During the transition from ocean to land, the seismoacoustic signal trapped in the deep sound channel can be converted effectively and thus becomes detectable by both ocean-moored hydrophones and land-based seismometers [*Stevens et al.*, 2001], often providing significant improvement in event detection and relocation where instrument coverage is poor [e.g., *Tolstoy and Bohnenstiehl*, 2005; *Ito et al.*, 2012].

T phase seismicity is a key feature of the hydroacoustic waveform component of the International Monitoring System (IMS) which is maintained by the Comprehensive Nuclear-Test-Ban Treaty Organization (CTBTO).

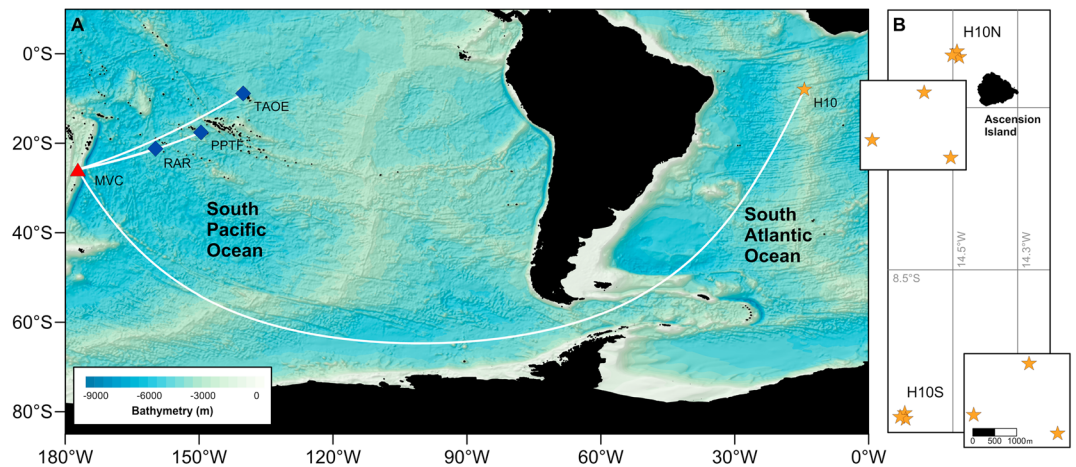


Figure 1. (a) Location map of Monowai Volcanic Centre (MVC, red triangle) and IMS station H10 (orange star). *T* phases of the May 2011 eruption were recorded at three regional broadband stations (blue diamonds) at Rarotonga (RAR), Papeete (PPTF), and Marquesas Islands (TAOE). The stations are located at 1847 km, 2991 km, and 4340 km distance from the volcano, respectively. Bathymetry is taken from the 2008 GEBCO grid. (b) Position map of the H10S and H10N hydrophone arrays near Ascension Island with insets for individual components. Geodesic distances between Monowai and the hydrophone arrays are 15,717 km (H10S) and 15,834 km (H10N).

Currently, a total of ten hydroacoustic receiver sites are in operation worldwide, six of which are hydrophone triplet arrays, typically deployed near the axis of the SOFAR channel [Okal, 2001]. In this study, we focus on recordings from IMS station H10 at Ascension Island, equatorial South Atlantic Ocean, of the five-day long explosive activity documented by Watts *et al.* [2012] at the Monowai Volcanic Centre, southwest Pacific Ocean (Figure 1).

2. Hydroacoustic Data and Direction-of-Arrival Calculations

IMS Station H10 consists of two tripartite arrays of bottom moored hydrophones located northwest and southwest of Ascension Island (Figure 1b). The triplets, H10N1-3 and H10S1-3, respectively, are positioned at approximately 875 m depth and equidistant interhydrophone spacing of 2 km. Acoustic measurements are made at 250 Hz sampling rate and transmitted in real time to the International Data Centre (IDC) in Vienna for routine processing and analyst review [Hanson *et al.*, 2001]. Following the onset of the eruption at Monowai Volcanic Centre on 17 May 2011, both H10 arrays recorded a high incidence of hydroacoustic *T* phases.

To determine the direction of arrival of these signals, we follow an approach previously introduced by Heaney *et al.* [2013] for the investigation of volcanogenic *T* phase arrivals associated with the 2010 eruption at Sarigan Seamount. Hydrophone recordings are corrected for instrument response and a mean and trend is removed. A two-pole band-pass filter with a low- and high-cutoff frequency of 4 Hz and 12 Hz, respectively, is applied to avoid noise contamination from either end of the spectrum, e.g., through ocean microseism, whale vocalization, or ship screw noise, and in general reflects the frequency range at which *T* phases would be expected to efficiently propagate within the SOFAR channel due to its inherent geometry [Hanson and Bowman, 2006].

Hydrophone recordings were subdivided into 1 min long windows over a continuous period of 5 days between 06:00 UTC 17 May and 06:00 UTC 22 May 2011. Peak delay times Δt are calculated from pairwise, normalized cross-correlation of the windowed data. The angle of arrival θ , which represents the geodesic back azimuth along the great circle path between receiver and source, is then derived from the peak delay times between pairs of hydrophones positioned at distance d and averaged over the array. Since the spacing of the array elements (i, j) is multiple orders of magnitude smaller than the source-receiver distance, we can assume a planar wave front for a point source in the acoustic far field:

$$\theta_{ij}(\Delta t) = \cos^{-1} \left\{ \frac{c\Delta t}{d_{ij}} \right\} \quad (1)$$

where c is the propagation speed across the array. Geometric ambiguity of the inverse cosine function is resolved by an a priori estimation of both the signal source location and c , which can be inferred from local

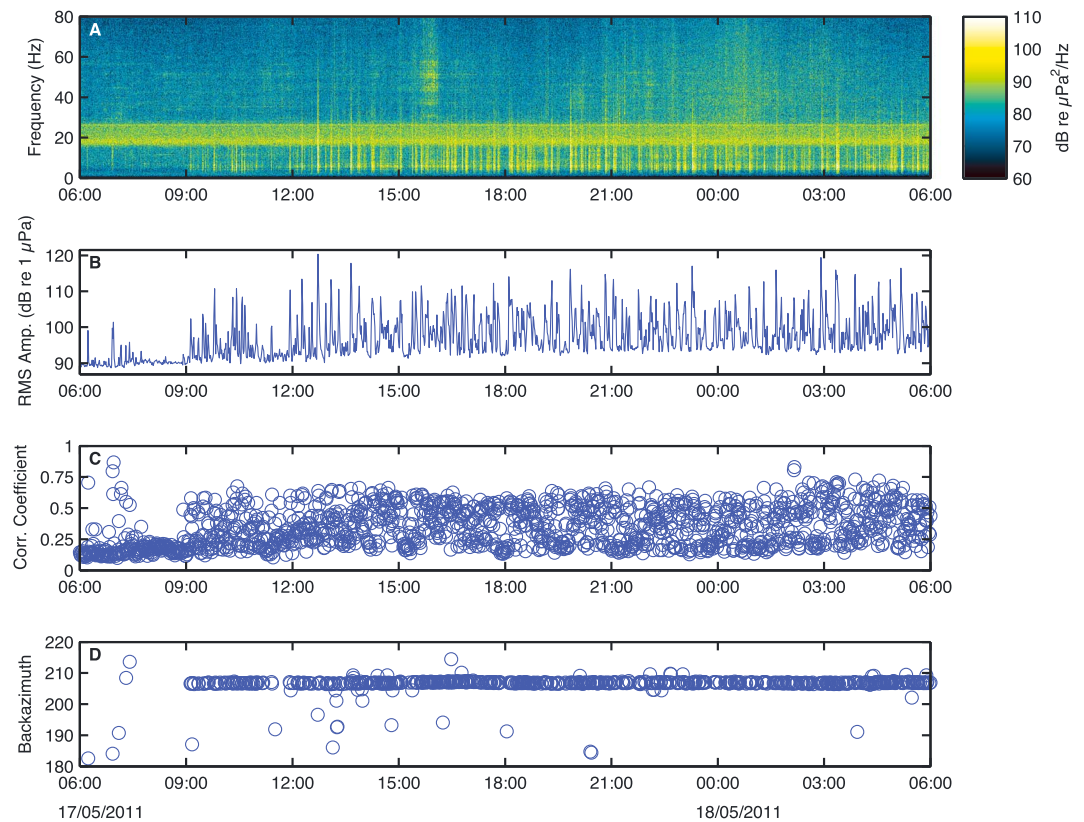


Figure 2. Twenty-four hours of data recorded at station H10S, beginning at 06:00 UTC 17 May 2011. (a) Single-receiver spectrogram of the H10S1 hydrophone data. A 2 Hz high-pass filter is applied to eliminate low-frequency noise; however, wide-band contamination is present between 18 and 26 Hz, possibly due to ship noise. (b) Root-mean-squared (RMS) amplitudes calculated over 1 min windows. The results of the time-difference-of-arrival processing are shown in the form of (c) correlation coefficients and (d) back azimuths averaged over the H10S array. Only time windows with an average coefficient ≥ 0.33 are used in the back azimuth calculation. The onset of the eruption at Monowai is recognizable in all four subfigures: Hydroacoustic phases, most distinguishable in the 2 to 20 Hz band, arrive from 09:00 UTC onward, accompanied by a positive shift in RMS amplitude of almost 20 dB re $1 \mu\text{Pa}$. Correlation values between hydrophones increase significantly at the same time, resulting in the distinct stabilization of the angle of arrival to within a degree of the predicted back azimuth to Monowai at 205.5° .

water column data and is fixed at 1492 m/s for the H10 station (Figure S1 in the supporting information). Only time windows with an average correlation coefficient ≥ 0.33 are used in (1) to eliminate weakly correlated background noise.

3. Observations at the Ascension Island Array

Our calculations show that volcanic activity at the Monowai Volcanic Centre stabilizes back azimuths over an approximately 5 day long period, representing a persistent source of acoustic energy at both arrays of the Ascension Island station.

The onset of the eruption at 09:00 UTC on 17 May is clearly recognizable in the spectrogram of hydroacoustic measurements, shown for the southern array in Figure 2a. Here one of the most striking features is a continuous, low-level noise band in the 18–25 Hz range, which we attribute to ship traffic in the area. *T* phases are most notable in the 2–20 Hz range, with lengths of tens of seconds up to several minutes and average acoustic intensities of 100 to 110 dB re $1 \mu\text{Pa}^2/\text{Hz}$. Maximum levels of 125 dB re $1 \mu\text{Pa}^2/\text{Hz}$ are reached during minute-long bursts of broadband, high-frequency energy, ranging up to 40 Hz and more. These arrivals occur predominantly during the first 48 h of the eruption at rates of up to 10 per hour, most likely representing explosions at the magma-water interface [e.g., Chadwick *et al.*, 2008b]. With the beginning of the eruption, peak RMS values increase by almost 20 dB compared to preeruptive background levels (Figure 2b).

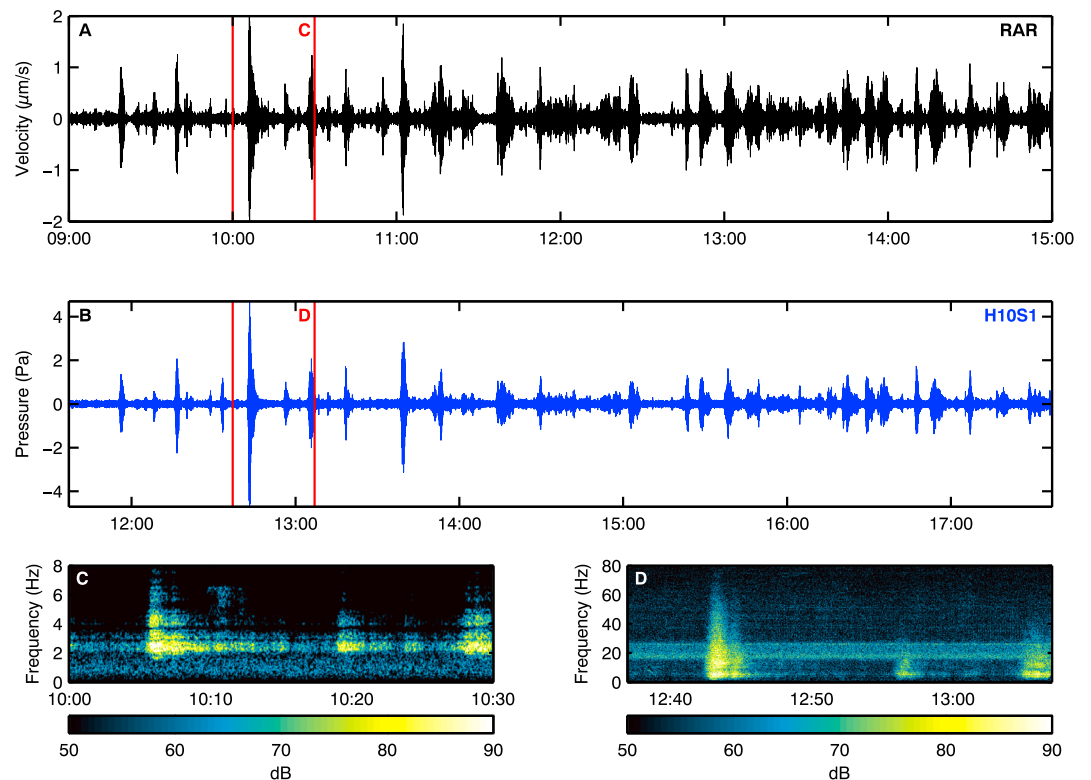


Figure 3. Traces of the (a) RAR vertical seismometer component and (b) hydrophone H10S1. The data are recorded at 20 Hz sampling rate at RAR and 250 Hz at H10S1, band-pass filtered at 2–6 Hz and 4–12 Hz, respectively, and show arrivals during 6 h long periods on 17 May 2011. Traces are aligned for an offset of 156 min and 12 s, the nominal travel time difference between the two receivers for a presumed signal source at Monowai. Vertical red lines delimit the time range of 30 min spectrograms of land-recorded *T* phases and corresponding arrivals at H10S1 as shown in Figures 3c and 3d. (c and d) The dB scale is normalized for better comparability and does not reflect absolute physical quantities. Spectral data are high-pass filtered at 2 Hz. There is a striking visual coherence between the signal envelopes in Figures 3a and 3b and relative frequency distributions of the individual bursts in Figures 3c and 3d, respectively.

Average correlation coefficients of the windowed hydrophone data rise sharply, scattering between 0.25 and 0.8 from 17 May 09:00 UTC onward (Figure 2c). The angle of arrival simultaneously stabilizes around $206.5 \pm 0.2^\circ$ during the first 24 h of the eruption, which closely matches the predicted geodesic back azimuth to Monowai, and clearly indicates a signal source between IMS Station H10 and the volcanic center (Figure 2d).

The end of the eruptive episode occurs around 13:00 UTC on 23 May, when calculated back azimuths become more scattered, before cross-correlation coefficients drop beneath the detection threshold of 0.33 at 16:00 UTC (Figure S2). There are several pauses in activity over the course of the 5 days, ranging from tens of minutes up to a 6 h long break in activity on 21 May. The high incidence of *T* phase arrivals and their codas result in a quasi-continuous character of the signal, adding up to an acoustic signature which is best described as low-level, volcano-seismic tremor interspersed with explosive activity [see, e.g., Fox *et al.*, 2001].

4. Combining Hydroacoustic and Broadband Seismic Data

In order to confirm the azimuthal constraints of the direction-of-arrival calculations, we relate acoustic and seismic measurements in both the near field and far field in an effort to unambiguously identify volcanic activity at the Monowai Volcanic Centre as the primary signal source. *T* phase arrivals associated with the May 2011 eruption were detected at three seismic broadband stations at Rarotonga (RAR), Papeete (PPTF), and Marquesas Islands (TAOE) in the Pacific Ocean (Figure 1). However, both PPTF and TAOE seismic data are affected by high ambient noise levels during the time of the eruption, preventing the application of common relocation techniques for individual *T* phase events [e.g., Williams *et al.*, 2006]. Instead, we exploit relative

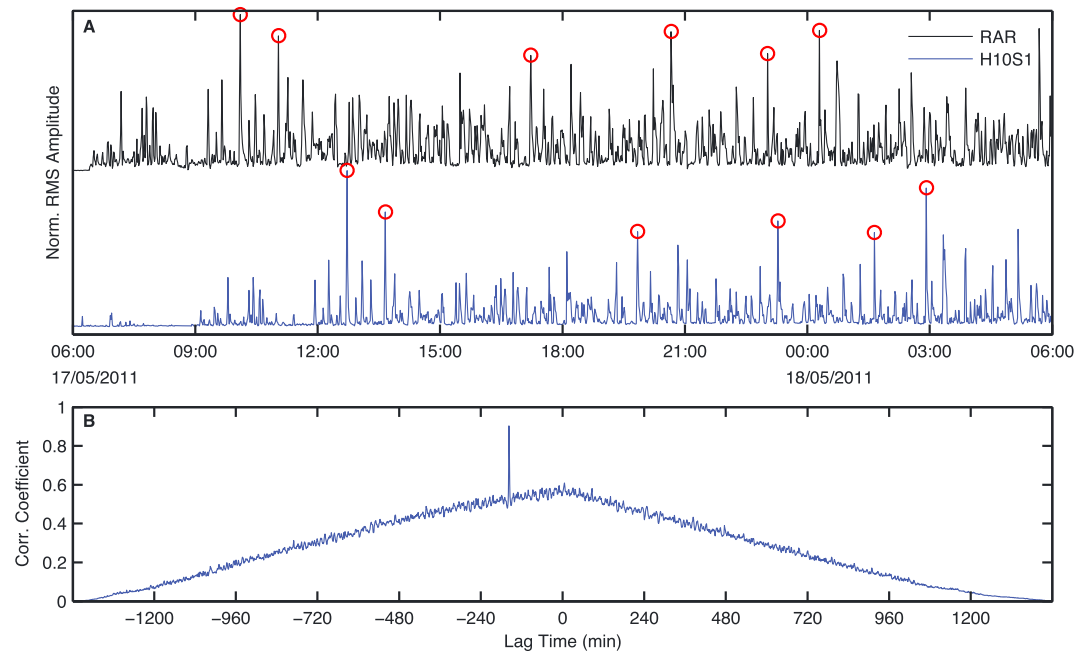


Figure 4. (a) Normalized RMS amplitudes at the RAR seismic station (vertical component) and the H10S1 hydrophone, calculated for 1 min windows between 06:00 UTC 17 May and 06:00 UTC 18 May. The data are band-pass filtered at 2–6 Hz and 4–12 Hz, respectively. Red circles highlight corresponding RMS peaks for clarity. (b) Cross-correlation results of data in Figure 4a. The distinct 0.92 peak marks the maximum coefficient of this 24 h period. The corresponding delay time is -157 min, indicating that the signal arrives 2 h and 37 min earlier at the Rarotonga seismometer relative to the Ascension Island hydrophone.

travel time differences between the proximal RAR station and a single, distal H10 hydrophone element for our calculations.

Assuming a signal source at Monowai and a constant axial propagation speed of 1475 ± 3 m/s, a reasonable estimate for the sound speed average along the geodesic path between the volcano and Ascension Island [Munk and Forbes, 1989], nominal arrival time offsets between these two receiving stations are estimated at 156 min 43 ± 21 s. Stacking the traces according to this offset (Figures 3a and 3b) reveals a striking visual coherence between the signals, precisely aligning higher-amplitude phases and periods of quiescence. Individual *T* phase events appear similar in both time and frequency domains (Figures 3c and 3d). This is despite the possibility that higher frequencies tend to be lost during the ocean-land conversion process at the RAR station [Stevens *et al.*, 2001].

In a further step to remove any ambiguity regarding the source, envelope functions are calculated from normalized RMS amplitudes for the H10S1 hydrophone and the vertical component of RAR station. There is a notable visual coherence between the two signals (Figure 4a), and cross-correlation of the envelope functions from RAR and H10S1 shows a high degree of correlation (Figure 4b). Twenty-four hour time windows were chosen for cross-correlation as this is approximately 10 times the expected delay time between the two stations. The highest cross-correlation coefficient of the eruption is observed during the first 24 h window, with a cross-correlation coefficient of 0.92 at a lag of 157 ± 1 min (Figure 4b). The high level of correlation is attributed to the large number of high-amplitude, coherent arrivals during this time. This calculation is in agreement with the calculated delay time assumed in Figure 3 (156 min 43 ± 21 s) and confirms our initial assumption of a common signal source at Monowai.

Our observations are equivalent for both the H10S and H10N hydrophone array, located at great circle distances of 15,717 and 15,834 km respectively from Monowai. These are, to our current knowledge, the longest ranges ever reported for any naturally occurring underwater phenomena and are only superseded by the artificial source-receiver paths achieved during the Heard Island Feasibility Test [Munk *et al.*, 1994]. The significant coherence observed between the seismic and hydrophone recordings further suggest that the overall seismoacoustic structure of the eruption is conserved in the *T* phase signal, even over extremely long

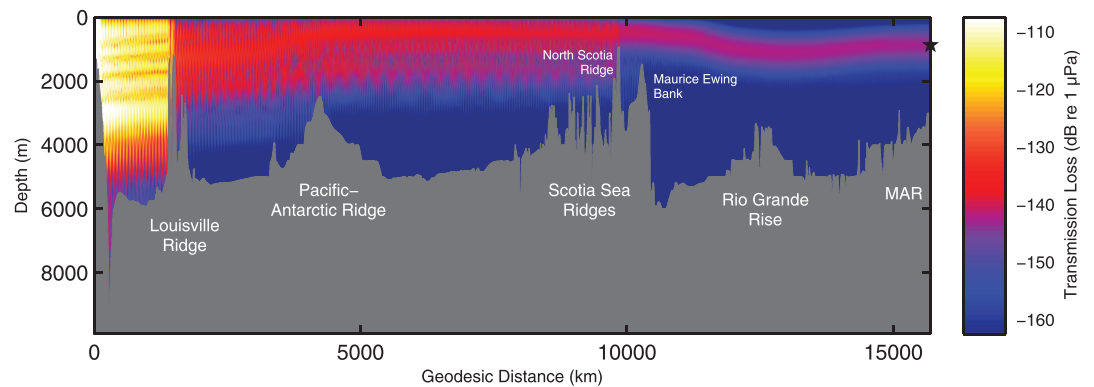


Figure 5. Two dimensional parabolic equation model (RAM, [Collins, 1993]) for a source-receiver path between Monowai Seamount and H10S. The model assumes an 8 Hz source at 60 m depth, corresponding to the dominant frequency of hydroacoustic arrivals and the bathymetry of the volcano. Apart from the Louisville and North Scotia Ridge, located at km 1,500 and km 9,500 along the profile respectively, ray paths along the SOFAR channel axis experience little obstruction and appear to be limited only by the sea surface in southern latitudes. Transmission loss for a receiver (black star) at 875 m depth is estimated to be $\sim 145\text{--}150$ dB re $1 \mu\text{Pa}$. Bottom properties are set to 1,700 m/s for sound speed, with attenuation parameters of 0.3 and 3.5 dB/m/kHz at 100 and 300 m below the seafloor respectively [Kibblewhite, 1989]. Bathymetry is taken from the 2008 GEBCO grid, sampled at 100 m intervals. Water column data is taken from the 2001 World Ocean Atlas, with sound speed profiles calculated every kilometre according to [Mackenzie, 1981].

distances and propagation through different media. Nonetheless, it is important to note that seismoacoustic activity associated with the May 2011 eruption at Monowai was not detected at further sites in the southern Pacific or Atlantic Ocean, including two broadband stations located on Ascension Island itself. This illustrates, at least for the case of volcanic activity at the Monowai Volcanic Centre, the advantage of a sensitive, acoustically “quiet” hydrophone array over single-element, land-based instruments.

Our approach holds true for further eruptions at the Monowai Volcanic Centre. On 1 January 2013, a swath mapping campaign of the SO225 expedition aboard R/V *SONNE* had to be aborted due to a sudden increase in volcanic activity, including observations of surface-reflected shockwaves in the audible range, pumice rafts, and discolored water [Werner *et al.*, 2013]. A preliminary screening of the Ascension Island hydrophone data reveals persistent high-energy arrivals from a back azimuth of 205.5° for this time period, which in overall frequency content, spatial and temporal distribution strongly resembles our observations of the May 2011 eruption.

5. Investigation of Potential Bathymetric Blockage and Transmission Loss Modeling

Long-distance hydroacoustic propagation can be affected by bathymetric obstruction and range-dependent sound speed variations [Blum and Cohen, 1971]. Furthermore, the existence of a deep sound channel is not facilitated at southern latitudes, where water masses at critical depths are dominated by the temperature regime of the Antarctic Circumpolar Current (ACC) [Denham and Kibblewhite, 1970]. Using a range-dependent adiabatic equation model (RAM) [Collins, 1993], we therefore investigate the source-receiver path by calculating the full sound field over the geodesic profile between Monowai and the Ascension Island hydrophones (Figure 5).

In order to reflect the prevailing frequency content of the *T* phase arrivals observed at H10S, we assume an 8 Hz source, placed at 60 m below sea level which is in accord with the most recent estimates of summit depth at Monowai [Watts *et al.*, 2012]. The nominal great circle distance is $\sim 15,717$ km for the southern triplet array. Potential obstructions along the acoustic ray path include the Louisville Ridge as well as the Pacific-Antarctic Ridge, the Scotia Sea Ridges, the Maurice Ewing Bank, the eastern Rio Grande Rise, and the southern Mid-Atlantic Ridge.

Our modeling shows that the most severe transmission loss occurs near the Louisville Ridge seamount chain, where the crest of one of the seamounts in the chain intersects the SOFAR channel axis and the signal is partially blocked, resulting in an average reduction of 20 to 25 dB re $1 \mu\text{Pa}$. A similar effect would be expected for the area around the North Scotia Ridge and Maurice Ewing Bank, where seafloor depths are shallowest along

the profile. However, the RAM model predicts that acoustic phases partially propagate as surface reflected waves south of the 60°S parallel, thereby evading bathymetric obstruction and reducing the average effect of acoustic blockage to ~10 dB re 1 μ Pa. This upward shift of the axis of the SOFAR channel is facilitated by the temperature anomaly of the ACC, which dilutes vertical sound speed gradients in the upper layers and subsequently raises the minimum velocity zone to shallower depths of up to 300 m and less (e.g., *Northrop and Colborn* [1974] and *de Groot-Hedlin et al.* [2009]; see also Figure S3). Similar effects of range-dependent temperature variations on high-latitude acoustic propagation have been previously observed by *Chapp et al.* [2005], enabling long-distance detection of iceberg-generated tremor in the southern Indian Ocean.

Overall transmission loss along the wider sound channel axis varies between –110 and –150 dB re 1 μ Pa. Transmission loss at the receiver depth of 875 m at full distance averages around 145–150 dB re 1 μ Pa. This implies maximum source levels of ~275–280 dB re 1 μ P at Monowai, which is comparable to amplitudes of explosive activity reported at NW-Rota 1 or West Mata volcano by *Chadwick et al.* [2008b] and *Dziak et al.* [2015]. Derived source levels correspond to seismic events with body wave magnitudes of $m_b \leq 4.0$ [*Fox et al.*, 2001], a size which appears typical for submarine explosion-type systems [e.g., *Dziak et al.*, 1996] but generally is too small to be detected by conventional methods in remote regions by a sparse global network.

6. Summary

Acoustic phases associated with a 5 day long episode of submarine volcanic activity at the Monowai Volcanic Centre were detected on CTBTO hydrophone installations at Ascension Island, Mid-Atlantic Ocean. The geodesic source-receiver path of approximately 15,800 km is, to our knowledge, the longest ranging, naturally occurring hydroacoustic signal above 1 Hz ever observed in the world's oceans. Our observations are consistent with the timing of *T* phase arrivals at the Rarotonga broadband seismic station for a source at Monowai. They are also consistent with the results of two-dimensional adiabatic mode calculations based on the RAM Parabolic Equation which suggest that hydroacoustic signals partially travel as surface reflected phases at shallow depths in the southern oceans, thereby avoiding significant acoustic blockage by topographic obstacles during the transition from Pacific to Atlantic waters. Our findings highlight the exceptional capabilities of the International Monitoring System of the CTBTO and its potential for remotely detecting further episodes of submarine volcanic activity and therefore better understanding the dynamics of the seafloor, both at Monowai and elsewhere, in the future.

Acknowledgments

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Erratum

In the originally published version of this article, the mooring depth of the H10 hydrophone arrays at Ascension Island was erroneously quoted as 1700 m below sea level. The correct depth of the tripartite arrays is in fact 875 m below sea level, and in direct vicinity of the SOFAR channel axis in the region. In addition, an error due to which the cylindrical spreading term had been omitted from the transmission loss model was corrected in the latest version. These oversights did not affect our direction-of-arrival calculations, but required corrections to our estimates of peak acoustic source levels and body wave magnitudes. Figures 5 and S1 were amended accordingly. The authors would like to thank Albert Brouwer (CTBTO) for his help with recalculating the instrument depths from the virtual Data Exploitation Centre (vDEC). All corrections have since been made, and the present version may be considered the authoritative version of record.