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Realizable high-order finite-volume schemes for the advection of moment sets of the particle size distribution

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Abstract

The accurate description and robust simulation at relatively low cost of a size polydisperse population of fine particles in a carrier fluid is still a major challenge for many applications. For this purpose, moment methods, derived from a population balance equation, represent a very interesting strategy. However, one of the major issues of such methods is the realizability: the numerical schemes have to ensure that the moment sets stay realizable, *i.e.* that an underlying distribution exists. This issue is all the more crucial that some moment vectors can be at the boundary of the moment space for practical applications, corresponding to a population of particles with only one or a few sizes. It is then investigated here for the advection operator, for which it is particularly significant. Then second order realizable kinetic finite volume schemes are designed, with two strategies for the fluxes evaluation based on the work of Kah et al. (J. Comput. Phys., 231:394-422, 2012) and of Vikas et al. (J. Comput. Phys., 230:5328-5352, 2011), which are here completely revisited, analyzed and compared in a Cartesian mesh context. For a potential easiest generalization to unstructured meshes, simplified but still realizable versions of these schemes are also developed. The high accuracy of all the schemes is then numerically checked on 1D and 2D test cases, with Cartesian meshes, and their robustness is shown, even when some moments vectors are at the boundary of the moment space.

Keywords: population balance equation, moment method, advection, realizable scheme, finite volume, kinetic scheme

1. Introduction

Populations of non-inertial particles in a carrier fluid are encountered in several kinds of applications (see [1] and references therein): soot in combustion applications, nanoparticles synthesis, microbubbles in biology processes, aerosol technology, ... Its evolution can be described by a population balance equation (PBE) [1, 2, 3, 4], which is a transport equation for the number density function (NDF) of the particles. This NDF depends on time, spatial location and one or several internal coordinates, which can for example describe the size of the particles. The PBE includes

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usually the spatial transport terms, describing for example advection and diffusion, and some localized source terms describing, at each spatial location, phenomena such as nucleation, aggregation, coagulation, breakup, growth or oxidation/dissolution. It is coupled with the equations, usually Navier-Stokes equations, describing the carrier fluid [5].

In this work, only one internal variable is considered, describing the size of the particles, assuming for example that they are spherical. In order to be able to describe the size polydispersion of the particles at a reasonable cost, the use of moment methods seems to be an interesting strategy (see for example [6, 7, 2]): only a finite set of moments of the NDF are then transported. It can also be hybridized with a discretization along the internal coordinate [8, 9, 10, 11, 12]. However, two major issues arise for moment methods. The first one is the closure of the moment equations essentially due to the source terms in the PBE. Several strategies were used: some of them provide a functional dependence of the unknown moments using the transported moment set, such as the interpolative closure (MOMIC) [13]. For the other ones, a NDF, or its corresponding measure, is reconstructed from the moment set, allowing evaluation of all the unclosed terms. This reconstruction can be for example the entropy maximization [14, 15, 16], a sum of Dirac delta function (quadrature method of moment, QMOM) [6] or a superposition of kernel density functions (kernel density element method, KDEM [17] or extended quadrature method of moment EQMOM [18, 19, 20]). The second major issue of moment methods is the realizability. Indeed, since the set of variables are the moments of a non-negative NDF (or, more rigorously, a positive measure) on \mathbb{R}_+ or a sub-interval of \mathbb{R}_+ , it belongs to a space strictly included in \mathbb{R}_+^N , where N is the number of moments [21, 22, 23]. This space is called the moment space. The numerical methods have to ensure that the variables stay in this moment space, *i.e.* that the moments stay realizable. This issue is not always considered, thus leading to unphysical results (*e.g.* invalid moment sets). Indeed, the classical schemes for high-order transport in physical space can lead to invalid moment sets [24, 25, 26], as well as for the source terms [11, 10], even if the closure itself ensures the realizability at the continuous level. This happens all the more easily when some moment sets are at the boundary of the moment space, thus corresponding to a sum of a few weighted Dirac delta functions, as obtained through nucleation. To circumvent this issue, some authors resort to moment correction algorithms [27, 24] based on a necessary but eventually not sufficient condition for realizability in order to obtain a valid moment set. The cost of the method then increases and the correction spoils the overall accuracy.

It is then very important to develop realizable schemes, *i.e.* schemes directly preserving the realizability of the moment set. Moreover, an operator splitting strategy, solving separately the spatial transport of both phases and the source terms was shown to be efficient and well adapted to industrial-oriented codes [28]. This allows us to deal separately with the spatial transport and the source terms. Concerning the source terms, realizable schemes were already developed for moment methods where the closure is based on a reconstruction of the NDF [11, 2, 10]. A realizable scheme was also provided for the diffusion operator in the case of QMOM [26, 2]. In this work, only advection then is considered. In practice, this operator, at least when using first order explicit finite volume methods, is usually much less costly than the potentially complex source term operator, composed of one ODEs system for each considered moment vector. So, it will be very interesting to minimize the number of degree of freedom by using a high order scheme for advection, as soon as its cost is not prohibitive.

A Lagrangian type of scheme has been developed [29]. The advection of the moments is then obtained through the advection of some numerical particles for which a moment vector is affected. The resulting scheme is then naturally realizable. However, it suffers from the same drawbacks as usual Lagrangian methods: the need of interpolation of the carrier phase properties, the non

easy coupling with this phase and the complexity in term of parallelization for high performance computing. Moreover, it could need a large number of numerical particles to converge, for which the eventually costly source terms operator has to be solved. That is why only Eulerian schemes are studied here. On the one hand, a second-order realizable kinetic finite volume method has been developed in a structured mesh context [30], when the support of the NDF is compact. It was recently applied in a context of a mesh refinement [31]. It is based on a kinetic evaluation of the fluxes thanks to the use of the analytical solution at the kinetic level and on a MUSCL type of reconstruction on the canonical moments, which define a one to one relation between the interior of the moment space and the interior of an hypercube. However, it was only applied for inertial particles and for a four moments method, the algebra being otherwise difficult. On the other hand, a pseudo-second-order realizable finite volume method [25] has been developed in structured and unstructured mesh contexts. Fluxes computation is then based on a reconstruction of the moments at the cell interfaces; it is obtained thank to the Gauss quadrature of the moments, just reconstructing the weights. However, it was reduced to an even number of moments and suffers from some accuracy reduction when the quadrature points evolve strongly. In this work, the last two schemes are completely revisited, generalizing them to any number of moments and allowing them to deal with the boundary of the moment space. They are also analyzed and compared. This is done for NDF of support included in $[0, +\infty)$, the case of a compact support being discussed in the appendix. Kinetic schemes are thus derived in a structured mesh context, first with a reconstruction on variables defining a one to one relation between the interior of the moment space and $(0, +\infty)^N$, where N is the number of moments in the set. Algorithms are then adapted to the case of the support included in $[0, +\infty)$ and generalized to any number of moments. The weight reconstruction is also considered, for an even or an odd number of moments, in a different way compared to [25], thus not being dependent of abscissas differences between the cells. Simplified schemes are then derived with the two kinds of reconstructions, the first one being modified for this case. It will be generalizable to unstructured meshes in a cell-centered context.

The paper is then organized as follows. In Section 2, the moment equations for the pure advection case are given, as well as the realizability constraints. Then, in Section 3, realizable finite volume kinetic schemes are provided and their orders of accuracy discussed. Some simplified version of these schemes are also given in Section 4, as well as the new constraint on the CFL to guarantee the realizability. Finally some verifications are given, considering systems with high numbers of moments, first for 1D configurations with steady or unsteady and compressible carrier phase velocity fields in Section 5 and for the 2D configuration of the Taylor-Green vortices in Section 6.

2. Moment transport equation and realizability

In this section, moment equations for the pure advection case are first recalled. Then, the space in which the moment vector lives is described, as well as the realizability conditions. This can be done directly, using the Hankel determinants. But some interesting tools are also introduced, defining a bijection between the interior of the moment space \mathcal{M}_N and $(0, +\infty)^N$.

2.1. Moment equations

Let us consider the NDF, denoted $f(t, x, \xi)$, of some cloud of small particles transported by a carrier fluid. The parameter ξ , which is the size of the particles, lives in the interval $[0, +\infty)$. The

case of a compact support is discussed in Appendix A. In the case of pure advection, the population balance equation (PBE) then reduces to:

$$\partial_t f + \partial_x (u f) = 0, \quad (1)$$

where u is the fluid velocity, assumed to be a regular function of (t, x) in what follows.

Instead of resolving directly this PBE, one considers a finite set of moments $(m_k)_{k \in \{0, 1, \dots, N\}}$ of the NDF, the k^{th} order moment m_k being defined by:

$$m_k(t, x) = \int_0^{+\infty} \xi^k f(t, x, \xi) d\xi. \quad (2)$$

These moments are the solution of the following system of equations, denoting $\mathbf{m}_N = (m_0, \dots, m_N)^t$:

$$\partial_t \mathbf{m}_N + \partial_x (u \mathbf{m}_N) = 0. \quad (3)$$

Let us remark that this system is closed, contrary to the often encountered systems in moment methods. However, it is usually only a part of a more complex problem for which some closure is needed and can be provided through the reconstruction of a NDF from the moments (see for example [6, 30, 19]). Moreover, the moment equations seem here independent from one another. In fact, they are coupled by the fact that the vector $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$ has to be a moment vector of a positive measure, *i.e.* has to stay in the moment space. This is the realizability condition, which is detailed in the next section.

2.2. Moment space: definition and first characterization

Let us denote \mathcal{P} the space of finite positive Borel measures on $(0, +\infty)$. And for $\mu \in \mathcal{P}$, let us denote $\mathbf{m}_N(\mu)$ the vector of moments of μ of order 0 to N , assuming that they are finite:

$$\mathbf{m}_N(\mu) = (m_0(\mu), \dots, m_N(\mu))^t, \quad m_k(\mu) = \int_0^{+\infty} x^k d\mu. \quad (4)$$

The moment vectors $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$ lives in the N th-moment space.

Definition 2.1. The N th-moment space \mathcal{M}_N on the interval $(0, \infty)$ is given by

$$\mathcal{M}_N = \{\mathbf{m}_N(\mu) \mid \mu \in \mathcal{P}\}.$$

If a moment vector \mathbf{m}_N belongs to this space, it is said to be *realizable* and one then defines

$$\mathcal{P}(\mathbf{m}_N) = \left\{ \mu \in \mathcal{P} \mid \mathbf{m}_N = \int_0^{+\infty} (1, x, \dots, x^N)^t d\mu \right\}.$$

If \mathbf{m}_N belongs to the interior of this space, it is said to be *strictly realizable*.

This N th-moment space is convex. To characterize it, one can introduce the Hankel determinants, defined by:

$$\underline{H}_{2n+d} = \begin{vmatrix} m_d & \dots & m_{n+d} \\ \vdots & & \vdots \\ m_{n+d} & \dots & m_{2n+d} \end{vmatrix}, \quad (5)$$

with $d = 0, 1; n \geq 0$. Indeed, one has the following proposition, for which a proof can be found in [21, 22, 23]:

Theorem 2.1. *The vector $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$ is strictly realizable if and only if*

$$\underline{H}_k > 0, \quad k \in \{0, 1, \dots, N\} \quad (6)$$

and if it belongs to the boundary of the moment space, then if there exists $k \leq N$ such that

$$\underline{H}_0 > 0, \dots, \underline{H}_{k-1} > 0, \underline{H}_k = 0, \dots, \underline{H}_N = 0. \quad (7)$$

In this last case, k is denoted $\mathcal{N}(\mathbf{m}_N)$ and $\mathcal{P}(\mathbf{m}_N)$ is a singleton: a sum of $\lfloor \frac{k+1}{2} \rfloor$ weighted Dirac delta functions¹.

Let us remark that if $\mathcal{N}(\mathbf{m}_N)$ is odd, then one of the Dirac delta functions is centered at 0. Moreover, (7) is not a sufficient condition for a moment to be on the boundary (and not outside) of the moment space: an additional condition is then needed [32, 33].

The moment space has a rather complex geometry, as explained in the next section. Moreover, the Hankel determinants provide algebraic relations to determine if a vector belongs to the moment space but this tool is not easy to use, since we do not want to compute all these determinants. But other quantities can be derived, linked with a one-to-one mapping of the interior of the moment space, thanks to the theory of orthogonal polynomials.

2.3. Orthogonal polynomials theory and new characterization of the moment space

Let \mathbb{P} be the space of real polynomials. For a positive finite Borel measure μ such that its moments are well defined and for p, q in \mathbb{P} , let us define the scalar product:

$$\langle p, q \rangle = \int_{\mathbb{R}} p(x)q(x)d\mu. \quad (8)$$

When considering a measure μ with infinite support, a sequence $(\pi_k)_{k \geq 0}$ of orthogonal polynomials relative to this scalar product ($\langle \pi_k, \pi_p \rangle = \delta_{k,p} \langle \pi_k, \pi_k \rangle$) satisfies the following three term recurrence relation, with $\pi_0 = 1$, $\pi_{-1} = 0$ and $\beta_k > 0$ [34]:

$$\pi_{k+1}(x) = (x - \alpha_k)\pi_k(x) - \beta_k\pi_{k-1}(x). \quad (9)$$

Conversely, if the sequence of polynomials satisfies (9) with $\beta_k > 0$ for all $k \in \mathbb{N}$, then there exists a measure μ on the real line for which the polynomials are orthogonal. Moreover, this measure is supported on $[0, +\infty)$ if and only if there exists a sequence $(\zeta_k)_{k \geq 1}$ of positive numbers such that the coefficients in the recurrence relation (9) satisfy $\alpha_0 = \zeta_1$ and for all $k \geq 1$ [35]:

$$\beta_k = \zeta_{2k-1}\zeta_{2k}, \quad \alpha_k = \zeta_{2k} + \zeta_{2k+1}. \quad (10)$$

And this measure is supported on $[0, 1]$ if and only if the coefficients ζ_k form a chain sequence, *i.e.* they can be decomposed as $\zeta_k = p_k(1 - p_{k-1})$, with $p_0 = 0$ and $p_k \in (0, 1)$ for $k \geq 0$ [36].

When considering a measure with finite support, the sequence of such orthogonal polynomials is finite and only a finite number of the ζ_k (or of the p_k) can be defined. These coefficients then allow to characterize the interior of the moment space in the case where the support is included in $[0, +\infty)$.

¹ $\lfloor r \rfloor$ denotes here the largest integer less than or equal to the real number r

Indeed, for a moment vector \mathbf{m}_N at the boundary of the moment space \mathcal{M}_N , corresponding to a measure with a finite support, one has $\zeta_{\mathcal{N}(\mathbf{m}_N)} = 0$ and the ζ_k for $k > \mathcal{N}(\mathbf{m}_N)$ are not defined.

A more geometrical point of view can also be considered [22]. For a vector \mathbf{m}_{k-1} in the interior of the moment space \mathcal{M}_{k-1} , let us then first define

$$m_k^-(\mathbf{m}_{k-1}) = \min_{\mu \in \mathcal{P}(\mathbf{m}_{k-1})} m_k(\mu), \quad m_k^+(\mathbf{m}_{k-1}) = \max_{\mu \in \mathcal{P}(\mathbf{m}_{k-1})} m_k(\mu), \quad (11)$$

as the lower and upper boundary of the admissible interval for the moment m_k of order k , the lower order moments \mathbf{m}_{k-1} being known. In what follows, only measures supported on $[0, +\infty)$ are considered. In this case, $m_k^+ = +\infty$ and m_k^- is finite, with $m_k - m_k^- = m_0 \prod_{i=1}^k \zeta_i$. Moreover, m_k^- strongly depends on \mathbf{m}_{k-1} , meaning that the interval where the k^{th} order moment lives strongly depends on the value of the lower order moments. Some examples are given in Appendix B.

Then, the strict realizability is characterized either by the positivity of the Hankel determinants or by the positivity of the ζ_k and induces a link between the moments. Several algorithms allow to compute efficiently the recursion coefficient α_k and β_k and then the ζ_k from the moments: Rutishauser's QD algorithm [37, 38], Gordon's PD algorithm [39, 40] and variation of an algorithm attributed to Chebyshev and given by Wheeler in [41]. Since this last one is said to be slightly more stable in practice [41] and since it will help us to prove some properties on the relation between the moments and the ζ_k , let us detail it.

2.4. Chebyshev algorithm for the computation of the ζ_k and reverse Chebyshev algorithm

Consider the matrix Z with elements $Z_{k,p} = \langle \pi_k x^p \rangle$, which must be zero if $k > p$ and which satisfy $Z_{-1,p} = 0$, $Z_{0,p} = m_p$ and, thanks to the orthogonal polynomials recursion formula:

$$Z_{k+1,p} = Z_{k,p+1} - \alpha_k Z_{k,p} - \beta_k Z_{k-1,p}. \quad (12)$$

Coefficients α_k, β_k are determined by:

$$\beta_0 = m_0, \quad \alpha_0 = \frac{m_1}{m_0}, \quad \forall k > 0 \quad \beta_k = \frac{Z_{k,k}}{Z_{k-1,k-1}}, \quad \alpha_k = \frac{Z_{k,k+1}}{Z_{k,k}} - \frac{Z_{k-1,k}}{Z_{k-1,k-1}}, \quad (13)$$

which results from $Z_{k+1,k-1} = 0 = Z_{k+1,k}$. Thus, if the $Z_{k,p}$ are known for each $k \leq n$ and $p \leq k$, then one can compute the α_n, β_n from (13) and then the $Z_{n+1,p}$ for $p = 0, \dots, n+1$ from (12).

In what follows, it will be also interesting to compute the moments $(m_k)_{k \in \{1, \dots, N\}}$ from the $(\zeta_k)_{k \in \{1, \dots, N\}}$ and from m_0 . It can be done by reversing the previous algorithm: the coefficients α_k and β_k are given by (10) and setting $Z_{0,0} = m_0$ and $Z_{k,k} = Z_{k-1,k-1} \beta_k$ for $k \in \{1, \dots, \lfloor \frac{N}{2} \rfloor\}$ and $Z_{0,1} = m_0 \zeta_1$ and $Z_{k,k+1} = Z_{k,k} \left(\alpha_k + \frac{Z_{k-1,k}}{Z_{k-1,k-1}} \right)$, for $k \in \{1, \dots, N - \lfloor \frac{N}{2} \rfloor - 1\}$, one computes, for $i \in \{2, \dots, N\}$ and $k \in \{0, \dots, \lfloor \frac{N-i}{2} \rfloor\}$:

$$Z_{k,k+i} = Z_{k+1,k+i-1} + \alpha_k Z_{k,k+i-1} + \beta_k Z_{k-1,k+i-1}. \quad (14)$$

Then $m_k = Z_{0,k}$. This allows to give an important property of the relation between the ζ_k and the moments.

Proposition 2.2. *The moment m_n can be written*

$$m_n = m_0 \left[\prod_{k=1}^n \zeta_k + P_n(\zeta_1, \dots, \zeta_{n-1}) \right],$$

where $P_n(\zeta_1, \dots, \zeta_{n-1})$ is a polynomial function of degree n .

Proof. The matrix Z is defined by $Z_{-1,p} = 0$, $Z_{0,p} = m_p$ and equations (12) and (13). Let us denote $Y = Z/m_0$. We will prove by recursion the more general property (\mathcal{P}_p) :

$$(\mathcal{P}_p) \quad Y_{k,k+p} = \prod_{i=1}^{2k+p} \zeta_i + P_{k,k+p}(\zeta_1, \dots, \zeta_{2k+p-1}) \text{ for } k \in \{0, \dots, \lfloor \frac{n-p}{2} \rfloor\}, \text{ where } P_{k,k+p} \text{ is a polynomial function of degree } 2k+p \text{ of } (\zeta_1, \dots, \zeta_{2k+p-1}).$$

First, one can remark that $Y_{-1,p} = 0$, $Y_{0,0} = 1$, and thanks to (13) and (10), $Y_{0,1} = \zeta_1$ and:

$$Y_{k,k} = \prod_{i=1}^k \beta_i = \prod_{i=1}^{2k} \zeta_i, \quad \frac{Y_{k,k+1}}{Y_{k,k}} = \sum_{i=0}^k \alpha_i = \sum_{i=1}^{2k+1} \zeta_i.$$

This prove (\mathcal{P}_0) and (\mathcal{P}_1) . Now, let us assume that (\mathcal{P}_j) is true for $j \in \{0, \dots, i\}$ and $i > 0$. The recursion formula (14) can be rewritten, with $p = k + i$:

$$Y_{k,k+i+1} = Y_{k+1,k+1+(i-1)} + (\zeta_{2k} + \zeta_{2k+1})Y_{k,k+i} + \zeta_{2k-1}\zeta_{2k}Y_{k-1,k-1+i+1}.$$

Since (\mathcal{P}_i) and (\mathcal{P}_{i-1}) are true and $Y_{-1,-1+i+1} = 0$, this shows that (\mathcal{P}_{i+1}) is true, the term $\prod_{n=1}^{2k+i+1} \zeta_n$ being in $Y_{k+1,k+1+(i-1)}$ and the rest being a polynomial function of degree $2k + i + 1$ of $(\zeta_1, \dots, \zeta_{2k+i})$. This concludes the proof. \square

Let us remark that the term $m_0 P_n(\zeta_1, \dots, \zeta_{n-1})$ corresponds to $m_k^-(\mathbf{m}_{k-1})$, since $m_n - m_n^-(\mathbf{m}_{n-1}) = m_0 \prod_{i=1}^n \zeta_i$, as shown in [22]. The polynomials P_n are given in Appendix C for $n = 1, \dots, 7$.

3. Realizable finite volume kinetic schemes

The major issue of the numerical scheme developed here is to ensure the realizability of the vector \mathbf{m}_N . Indeed, Wright [24] showed that independent transport of moments with algorithms of order greater than one in space can result in the generation of invalid moment sets.

Let us develop a realizable numerical scheme for the 1D configuration. A generalization on 2D or 3D problems is straightforward for Cartesian meshes thanks to the method of lines.

3.1. General form of the finite volume kinetic scheme

Let us introduce a discretization of the spatial domain into cells $[x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}]$ of center $x_j = \frac{x_{j-\frac{1}{2}} + x_{j+\frac{1}{2}}}{2}$ and of width $\Delta x = x_{j+\frac{1}{2}} - x_{j-\frac{1}{2}}$. A time discretization $t^0 = 0 < t^1 < \dots < t^n < \dots$ is also used, with the time steps $\Delta t^n = t^{n+1} - t^n$. The properties of the averaged value of the moments on a cell is used here to define a numerical scheme.

3.1.1. Equations on the averaged value of the moments over a cell

One defines the characteristics $X(t; s, y)$ as the solution of

$$\begin{cases} d_t X(t; s, y) = u(t, X(t; s, y)), \\ X(s; s, y) = y. \end{cases}$$

One also defines $J(t; s, y)$ the Jacobian matrix of $y \mapsto X(t; s, y)$, for fixed values of t and s .

Proposition 3.1. For $\mathbf{m}_N = (m_0, \dots, m_N)^t$ a moment vector solution of (3), the mean value of each moment of order k at time t^n , denoted $\bar{m}_{k,j}^n = \frac{1}{\Delta x} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_k(t^n, x) dx$, satisfies

$$\bar{m}_{k,j}^{n+1} = \bar{m}_{k,j}^n - \frac{\Delta t^n}{\Delta x} \left[\bar{F}_{k,j+\frac{1}{2}}^n - \bar{F}_{k,j-\frac{1}{2}}^n \right], \quad (15)$$

with

$$\bar{F}_{k,j+\frac{1}{2}}^n = \frac{1}{\Delta t^n} \int_{X(t^n; t^{n+1}, x_{j+\frac{1}{2}})}^{x_{j+\frac{1}{2}}} m_k(t^n, x) dx. \quad (16)$$

Proof. The k^{th} component of the solution of (3) between t^n and t^{n+1} is:

$$m_k(t^{n+1}, x) = m_k(t^n, X(t^n; t^{n+1}, x)) J(t^n; t^{n+1}, x).$$

Then, its averaged value can be written, using the change of variables $\xi = X(t^n; t^{n+1}, x)$:

$$\bar{m}_{k,j}^{n+1} = \frac{1}{\Delta x} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_k(t^n, X(t^n; t^{n+1}, x)) J(t^n; t^{n+1}, x) dx = \frac{1}{\Delta x} \int_{X(t^n; t^{n+1}, x_{j-\frac{1}{2}})}^{X(t^n; t^{n+1}, x_{j+\frac{1}{2}})} m_k(t^n, \xi) d\xi.$$

This concludes the proof. \square

This results allows us to develop a kinetic scheme.

3.1.2. Kinetic scheme

Let us denote $\mathbf{m}_j^n = (m_{0,j}^n, \dots, m_{N,j}^n)^t$ an approximation at time t^n of the averaged value of the moment vector over the cell j and $X_{j+\frac{1}{2}}$ an approximation of $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$. In what follows, the CFL like number defined by:

$$\text{CFL} = \max_{n,j} \left(u_{j,\max}^n \frac{\Delta t^n}{\Delta x} \right), \quad u_{j,\max}^n = \max \left\{ u(t, x), x \in [x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}], t \in [t^n, t^{n+1}] \right\} \quad (17)$$

is assumed to be smaller than one in such a way that $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$ is in the cell j or $j+1$. Moreover, the same property is assumed for $X_{j+\frac{1}{2}}$.

First, let us define the approximation of $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$ that will be used here. For a constant and uniform fluid velocity, the exact value is used

$$X_{j+\frac{1}{2}} = x_{j+\frac{1}{2}} - u \Delta t^n. \quad (18)$$

Otherwise, one need a good approximation of the velocity and a resolution of the ODE defining the characteristics with an at least second order of accuracy to obtain third order approximation of $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$. For a stationary fluid velocity, a linear reconstruction of this velocity is done inside the cell. In what follows, we will assume that the fluid velocity is known at the interfaces and its value inside the cell is given by a linear interpolation. This leads to:

$$X_{j+\frac{1}{2}} = x_{j+\frac{1}{2}} - \frac{u(x_{j+\frac{1}{2}})}{\delta} \left(1 - e^{-\delta \Delta t^n} \right), \quad (19)$$

where, denoting $\delta_j = \frac{u(x_{j+\frac{1}{2}}) - u(x_{j-\frac{1}{2}})}{\Delta x}$: $\delta = \delta_j$ if $u(x_{j+\frac{1}{2}}) \geq 0$ and $\delta = \delta_{j+1}$ if $u(x_{j+\frac{1}{2}}) < 0$. Let us remark that $X_{j+\frac{1}{2}} < x_{j+\frac{1}{2}}$ in the first case and $X_{j+\frac{1}{2}} > x_{j+\frac{1}{2}}$ in the second one. For an unstationary fluid velocity, a linear temporal and spatial interpolation of the fluid velocity can be used. Using an explicit second order Runge et Kutta method for the resolution of the ODEs defining the characteristics, one obtains:

$$X_{j+\frac{1}{2}} = x_{j+\frac{1}{2}} - \frac{\Delta t^n}{2} \left[(1 - \delta \Delta t^n) u(t^{n+1}, x_{j+\frac{1}{2}}) + u(t^n, x_{j+\frac{1}{2}}) \right], \quad (20)$$

where, denoting $\delta_j = \frac{u(t^n, x_{j+\frac{1}{2}}) - u(t^n, x_{j-\frac{1}{2}})}{\Delta x}$: $\delta = \delta_j$ if $u(t^{n+1}, x_{j+\frac{1}{2}}) \geq 0$ and $\delta = \delta_{j+1}$ if $u(t^{n+1}, x_{j+\frac{1}{2}}) < 0$. It leads to a third order approximation of $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$:

Lemma 3.2. *Let us assume that the CFL number is smaller than one and that the parameter $X_{j+\frac{1}{2}}$ is defined by (18), (19) or (20), depending of the effective dependence of $u(t, x)$ in t and x . Then $X_{j+\frac{1}{2}}$ is a third order approximation of $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$:*

$$X_{j+\frac{1}{2}} - X(t^n; t^{n+1}, x_{j+\frac{1}{2}}) = O(\Delta x^3).$$

Moreover, $X_{j+\frac{1}{2}} - X(t^n; t^{n+1}, x_{j+\frac{1}{2}}) - X_{j-\frac{1}{2}} - X(t^n; t^{n+1}, x_{j-\frac{1}{2}}) = O(\Delta x^4)$

Proof. A Taylor expansion for $X(t^n; t^{n+1}, x_{j+\frac{1}{2}})$ leads to:

$$\begin{aligned} X(t^n; t^{n+1}, x_{j+\frac{1}{2}}) &= x_{j+\frac{1}{2}} + \int_{t^{n+1}}^{t^n} u(t, X(t; t^{n+1}, x_{j+\frac{1}{2}})) dt \\ &= x_{j+\frac{1}{2}} - u(t^{n+1}, x_{j+\frac{1}{2}}) \Delta t^n + \frac{(\Delta t^n)^2}{2} \left[\partial_t u(t^{n+1}, x_{j+\frac{1}{2}}) + u(t^{n+1}, x_{j+\frac{1}{2}}) \partial_x u(t^{n+1}, x_{j+\frac{1}{2}}) \right] + O((\Delta t^n)^3). \end{aligned} \quad (21)$$

Formula (18) is exact for a constant fluid velocity and, since δ is a first order approximation of $\partial_x u(t^n, x_{j+\frac{1}{2}})$, the Taylor expansion of (19) in the case of a stationary fluid velocity and of (20) in the general case leads to the same zeroth, first and second order terms as in (21). Finally, the last results is shown from the same kind of developments, adding the third order term. \square

Following the property of the exact solution given in Proposition 3.1, the scheme that we consider here is given by the recursion formula:

$$\mathbf{m}_j^{n+1} = \mathbf{m}_j^n - \frac{\Delta t^n}{\Delta x} \left[\mathbf{F}_{j+\frac{1}{2}}^n - \mathbf{F}_{j-\frac{1}{2}}^n \right], \quad (22)$$

with

$$\mathbf{F}_{j+\frac{1}{2}}^n = \frac{1}{\Delta t^n} \int_{X_{j+\frac{1}{2}}}^{x_{j+\frac{1}{2}}} \mathbf{m}^n(x) dx, \quad (23)$$

the function $\mathbf{m}^n(x) = (m_0^n(x), \dots, m_N^n(x))^t$ being defined from the moments \mathbf{m}_j^n , in a way described in Section 3.2.

3.1.3. Scheme properties

The properties of the scheme will depend on this reconstruction of the moments over the cells. We impose here the two following properties, assuming that \mathbf{m}_j^n is in the moment space \mathcal{M}_N :

- [P1] The averaged value of the reconstructed moment vector $\mathbf{m}^n(x)$ over each cell j is \mathbf{m}_j^n :

$$\frac{1}{\Delta x} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} \mathbf{m}^n(x) dx = \mathbf{m}_j^n.$$

- [P2] For each x , the vector $\mathbf{m}^n(x)$ is in the moment space \mathcal{M}_N .

For the accuracy, a third property is introduced:

- [P3] From an averaged moment vector $\bar{\mathbf{m}}_j = \frac{1}{\Delta x} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} \bar{\mathbf{m}}(x) dx$, the reconstruction $\mathbf{m}(x)$ is second order accurate: there exists a bounded Lipschitz function $\varphi_{\bar{\mathbf{m}}}$ such that

$$\mathbf{m}(x) = \bar{\mathbf{m}}(x) + \Delta x^2 \varphi_{\bar{\mathbf{m}}}(x).$$

This leads to the following theorem:

Theorem 3.3. *Let us assume that the CFL number is smaller than one. The finite volume scheme defined by (22,23) with the properties [P1] and [P2] of the moment reconstruction is realizable. With the additional property [P3] and using the value of $X_{j+\frac{1}{2}}$ defined by (18), (19) or (20), then a second order is obtained for the consistency error.*

Proof. The first property [P1], with the definition (23) of the fluxes implies:

$$\mathbf{m}_j^{n+1} = \frac{1}{\Delta x} \int_{X_{j-\frac{1}{2}}}^{X_{j+\frac{1}{2}}} \mathbf{m}^n(x) dx. \quad (24)$$

Since the characteristics cannot cross themselves, one has $X_{j-\frac{1}{2}} < X_{j+\frac{1}{2}}$. Then [P2] ensures that \mathbf{m}_j^{n+1} is in the moment space.

Moreover, from the exact solution $\mathbf{m} = (m_k)_{k \in \{0,1,\dots,N\}}$ of (3), the consistency error is defined by

$$\epsilon_j^n = \frac{\bar{\mathbf{m}}_j^{n+1} - \bar{\mathbf{m}}_j^n}{\Delta t^n} + \frac{\tilde{\mathbf{F}}_{j+\frac{1}{2}}^n - \tilde{\mathbf{F}}_{j-\frac{1}{2}}^n}{\Delta x},$$

where $\bar{\mathbf{m}}_j^{n+1} = (\bar{m}_{k,j}^{n+1})_{k \in \{0,1,\dots,N\}}$ is the exact averaged moment vector, $\bar{m}_{k,j}^n = \frac{1}{\Delta x} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_k(t^n, x) dx$,

and the flux vector $\tilde{\mathbf{F}}_{j+\frac{1}{2}}^n = \frac{1}{\Delta t^n} \int_{X_{j+\frac{1}{2}}}^{X_{j+\frac{1}{2}}} \bar{\mathbf{m}}^n(x) dx$ is defined with the reconstruction $\bar{\mathbf{m}}^n(x)$ obtained from the $\bar{\mathbf{m}}_j^n$. Thanks to Proposition 3.1, this can be written:

$$\epsilon_j^n = \frac{1}{\Delta t^n \Delta x} [I_1 + I_2],$$

with

$$I_1 = \int_{X_{j+\frac{1}{2}}}^{x_{j+\frac{1}{2}}} (\bar{\mathbf{m}}^n(x) - \mathbf{m}(t^n, x)) dx - \int_{X_{j-\frac{1}{2}}}^{x_{j-\frac{1}{2}}} (\bar{\mathbf{m}}^n(x) - \mathbf{m}(t^n, x)) dx$$

and

$$I_2 = \int_{X_{j+\frac{1}{2}}}^{X(t^n; t^{n+1}, x_{j+\frac{1}{2}})} \mathbf{m}(t^n, x) dx - \int_{X_{j-\frac{1}{2}}}^{X(t^n; t^{n+1}, x_{j-\frac{1}{2}})} \mathbf{m}(t^n, x) dx.$$

Thanks to [P3], the first term I_1 can be written:

$$\begin{aligned} I_1 &= \Delta x^2 \left[\int_{X_{j+\frac{1}{2}}}^{x_{j+\frac{1}{2}}} \varphi_{\mathbf{m}(t^n, \cdot)}(x) dx - \int_{X_{j-\frac{1}{2}}}^{x_{j-\frac{1}{2}}} \varphi_{\mathbf{m}(t^n, \cdot)}(x) dx \right] \\ &= \Delta x^2 \left[(x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}}) \varphi_{\mathbf{m}(t^n, \cdot)}(x_1) - (x_{j-\frac{1}{2}} - X_{j-\frac{1}{2}}) \varphi_{\mathbf{m}(t^n, \cdot)}(x_2) \right] \\ &= \Delta x^2 \left[(x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}}) (\varphi_{\mathbf{m}(t^n, \cdot)}(x_1) - \varphi_{\mathbf{m}(t^n, \cdot)}(x_2)) + (x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}} - x_{j-\frac{1}{2}} + X_{j-\frac{1}{2}}) \varphi_{\mathbf{m}(t^n, \cdot)}(x_2) \right], \end{aligned}$$

where x_1 is between $x_{j+\frac{1}{2}}$ and $X_{j+\frac{1}{2}}$ and x_2 is between $x_{j-\frac{1}{2}}$ and $X_{j-\frac{1}{2}}$. The term $x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}}$ is of order 1 and it is easy to see, using Taylor expansions, that $x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}} - x_{j-\frac{1}{2}} + X_{j-\frac{1}{2}}$ is of order 2. Then $I_1 = O(\Delta x^4)$. The second term I_2 can be written:

$$\begin{aligned} I_2 &= \mathbf{m}(t^n, X_{j+\frac{1}{2}}) \left[X(t^n; t^{n+1}, x_{j+\frac{1}{2}}) - X_{j+\frac{1}{2}} \right] - \mathbf{m}(t^n, X_{j-\frac{1}{2}}) \left[X(t^n; t^{n+1}, x_{j-\frac{1}{2}}) - X_{j-\frac{1}{2}} \right] + O(\Delta x^6) \\ &= \mathbf{m}(t^n, X_{j+\frac{1}{2}}) \left[X(t^n; t^{n+1}, x_{j+\frac{1}{2}}) - X_{j+\frac{1}{2}} - X(t^n; t^{n+1}, x_{j-\frac{1}{2}}) + X_{j-\frac{1}{2}} \right] + O(\Delta x^4). \end{aligned}$$

The result of Lemma 3.2 allows to conclude the proof. \square

3.2. Reconstruction of the moments in the cell and flux computation

To complete the scheme (22,23) a spatial reconstruction of the moments from their mean value is provided, verifying at least properties [P1] and [P2]. The constant reconstruction is the simplest, but leads to low order schemes. A MUSCL type of reconstruction is then envisioned but this cannot be done directly on the moments: this would inevitably lead to unrealizable moments $(m_0^n(x), \dots, m_N^n(x))^t$, due to the complex shape of the moment space [30]. Two kinds of reconstructions are then used here:

- a reconstruction on the variables $(\zeta_k)_{k \in \{1, \dots, N\}}$, which live in $[0, +\infty)$,
- a reconstruction on the weights of the quadrature corresponding to the moment vector.

Another kind of reconstruction could also be envisioned: a direct reconstruction at the level of a NDF, solution of the finite Stieljes moment problem, similarly to what was done in [42, 43] in the context of linear kinetic equations in slab geometry. In this context, the velocity of the advection depended on the internal variable ξ in such a way that the moment equations had to be closed; this was done through the entropy maximization reconstruction [44]. This kind of reconstruction can be applied in our context in a quite different way presented in Appendix E, using EQMOM [19, 10] instead of the entropy maximization, which is not really adapted to NDF defined on $[0, +\infty)$. However, it does not allow to deal with the boundary of the moment space and it induces a high supplementary cost related to the reconstruction (the computation time is then multiplied by at least 65 when using 5 moments, compared to the schemes described in this section).

3.2.1. The constant reconstruction based kinetic scheme

From the mean value $m_{k,j}^n$ of the moment in the cell, the first idea is to consider a constant value of the moments into the cell: $\mathbf{m}^n(x) = \mathbf{m}_j^n$ for $x \in]x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}[$. The flux can then be written:

$$\mathbf{F}_{j+\frac{1}{2}}^n = \frac{\mathbf{m}_j^n}{\Delta t^n} \left(x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}} \right)^+ - \frac{\mathbf{m}_{j+1}^n}{\Delta t^n} \left(X_{j+\frac{1}{2}} - x_{j+\frac{1}{2}} \right)^+$$

where $u^+ = \max\{0, u\}$. Its convergence with a first order of accuracy is easily shown with the value of $X_{j+\frac{1}{2}}$ defined by (18), (19) or (20).

3.2.2. The ζ reconstruction based kinetic scheme (ζ kinetic scheme)

For a fixed value of n , instead of reconstructing directly $\mathbf{m}^n(x)$, the corresponding $(\zeta_k(x))_{k \in \{1, \dots, N\}}$ as well as $m_0^n(x)$ are reconstructed. For m_0^n , a classical MUSCL type of reconstruction is used:

$$m_0^n(x) = m_{0,j}^n + D_{0,j}^n(x - x_j) \text{ for } x \in]x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}[.$$

For each k , a piecewise affine reconstruction $\zeta_k^n(x)$ is defined by:

$$\zeta_k^n(x) = \bar{\zeta}_{k,j}^n + D_{k,j}^n(x - x_j) \text{ for } x \in]x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}[.$$

Each $\bar{\zeta}_{k,j}^n$ is computed to ensure [P1]. Thanks to Proposition 2.2, this leads to:

$$\begin{aligned} \Delta x m_{k,j}^n &= \bar{\zeta}_{k,j}^n \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \prod_{i=1}^{k-1} \zeta_i^n(x) dx + D_{k,j}^n \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} (x - x_j) m_0^n(x) \prod_{i=1}^{k-1} \zeta_i^n(x) dx \\ &\quad + \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) P_k(\zeta_1^n(x), \dots, \zeta_{k-1}^n(x)) dx. \end{aligned}$$

Let us write $\bar{\zeta}_{k,j}^n = a_{k,j} + b_{k,j} D_{k,j}^n$, where $a_{k,j}$ and $b_{k,j}$ are defined by:

$$\begin{aligned} a_{k,j} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \prod_{i=1}^{k-1} \zeta_i^n(x) dx &= \Delta x m_{k,j}^n - \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) P_k(\zeta_1^n(x), \dots, \zeta_{k-1}^n(x)) dx, \\ b_{k,j} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \prod_{i=1}^{k-1} \zeta_i^n(x) dx &= - \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} (x - x_j) m_0^n(x) \prod_{i=1}^{k-1} \zeta_i^n(x) dx. \end{aligned}$$

Let us remark that $|b_{k,j}|$ is smaller than $\frac{\Delta x}{2}$. Moreover, thanks to the polynomial form of the functions, it can be shown that $a_{k,j} = \zeta_{k,j}^n + O(\Delta x^2)$ and $b_{k,j} = O(\Delta x^2)$. Numerically, the term $P_k(\zeta_1^n(x), \dots, \zeta_{k-1}^n(x))$ is computed either by using an analytical formula, for $k \leq 7$ (see Appendix C), or by using the reverse Chebyshev algorithm (see Section 2.4), setting $\zeta_k = 0$ and the integrals are computed using a Gauss-Legendre quadrature with $\lceil \frac{N}{2} \rceil + 1$ points.

For m_0 , a minmod limiter is used: $D_{0,j} = \minmod\left(\frac{m_{0,j+1}^n - m_{0,j}^n}{\Delta x}, \frac{m_{0,j}^n - m_{0,j-1}^n}{\Delta x}\right)$. Moreover, as in [45, 30], the slopes $D_{k,j}^n$ are such that $\zeta_k^n(x)$ stays between $\min\{\zeta_{k,j-1}^n, \zeta_{k,j}^n, \zeta_{k,j+1}^n\}$ and $\max\{\zeta_{k,j-1}^n, \zeta_{k,j}^n, \zeta_{k,j+1}^n\}$ in each cell j , as soon as it is the case for $a_{k,j}$. One can use [30]:

$$D_{k,j}^n = \begin{cases} \min\left(\frac{|\zeta_{k,j+1}^n - a_{k,j}|}{\Delta x + 2b_{k,j}}, \frac{|a_{k,j} - \zeta_{k,j-1}^n|}{\Delta x - 2b_{k,j}}, \frac{2a_{k,j}}{\Delta x - 2b_{k,j}}\right) & \text{if } \zeta_{k,j-1}^n < \zeta_{k,j}^n < \zeta_{k,j+1}^n, \\ -\min\left(\frac{|\zeta_{k,j+1}^n - a_{k,j}|}{\Delta x + 2b_{k,j}}, \frac{|a_{k,j} - \zeta_{k,j-1}^n|}{\Delta x - 2b_{k,j}}, \frac{2a_{k,j}}{\Delta x + 2b_{k,j}}\right) & \text{if } \zeta_{k,j-1}^n > \zeta_{k,j}^n > \zeta_{k,j+1}^n. \end{cases}$$

The last condition (in the min) ensures the non-negativity of the reconstruction, as soon as $a_{k,j}$ is non-negative. Unfortunately, $a_{k,j}$ can eventually be negative, meaning that, even with a constant reconstruction for $\zeta_k^n(x)$, one can obtain unrealizable moments. In this case, a correction has to be done on the slopes $D_{i,j}^n$, with $i < k$: they are reduced successively for $i = k_0, \dots, k-1$ where k_0 is the maximal value such that $a_{k,j}$ is positive if the $D_{i,j}^n$ were equal to zero for $i \in [k_0, k-1]$. For that, starting with $i = k_0$ till $i = k-1$, each $D_{i,j}^n$ is multiplied by 0.9 once or several times (at most 5 times here) and if it is not sufficient, it is set to zero. In the worst case, all slopes $D_{i,j}^n$ are then set to zero, for $i \geq 1$. But when needed, only one limitation is often sufficient. Some accuracy will then be locally lost, except on the 0^{th} order moment.

The fluxes can then be written, thanks to Proposition 2.2:

$$F_{k,j+\frac{1}{2}}^n = \frac{1}{\Delta t^n} \int_{X_{j+\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \left[\prod_{j=1}^k \zeta_j^n(x) + P_k(\zeta_1^n(x), \dots, \zeta_{k-1}^n(x)) \right] dx, \quad (25)$$

They are computed using a Gauss-Legendre quadrature with $\lceil \frac{N}{2} \rceil + 1$ points, since one has to integrate polynomial of degree at most $N+1$. The corresponding scheme is called ‘‘ ζ reconstruction based kinetic scheme’’, abbreviated to ‘‘ ζ kinetic scheme’’. Let us remark that the resolution of the equation on m_0 does not depend on the other moments, even if some corrections are needed for the positivity of the $a_{k,j}$. Moreover, the corresponding scheme is TVD for the constant velocity case. It is also easy to see that a maximum principle is obtained for $\zeta_1 = m_1/m_0$ in this case.

3.2.3. The quadrature weights reconstruction based kinetic scheme (QW kinetic scheme)

Similarly to what was done in [25], the reconstruction is based here on the quadrature of the moment sets, but in a different way. Let us then define the quadratures weights $(w_{j,\alpha})_{\alpha \in \{1, \dots, p\}}$ and abscissas $(\xi_{j,\alpha})_{\alpha \in \{1, \dots, p\}}$ of the moment set $(m_{k,j}^n)_{k \in \{0, \dots, N\}}$, such that:

$$m_{k,j}^n = \sum_{\alpha=1}^p w_{j,\alpha} \xi_{j,\alpha}^k, \quad k \in \{0, \dots, N\},$$

with $p = \lceil \frac{N}{2} \rceil + 1$. If the number of moments is even, it is the classical Gauss quadrature with $N = 2p - 1$. Then, abscissas and weights are deduced from the eigenvalues and eigenvectors of the Jacobi matrix with coefficients α_k and $\sqrt{\beta_k}$ [46], where α_k and β_k are the coefficient of the three term recurrence relation (9). Otherwise, $N = 2(p - 1)$ and a Gauss-Radau quadrature is used, meaning that an abscissa is set to zero: $\xi_{j,1} = 0$. They are computed in the same way as for the classical Gauss quadrature, except that α_{p-1} is set to $-\beta_{p-1} \frac{\Pi_{p-1}(0)}{\Pi_p(0)}$ [46].

Like in [25], the reconstruction of the moments inside the cell j is done through a reconstruction of the weights:

$$m_k^n(x) = \sum_{\alpha=1}^p w_\alpha(x) \xi_{j,\alpha}^k, \quad w_\alpha(x) = w_{j,\alpha} + D_{\alpha,j}^n(x - x_j), \quad x \in [x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}].$$

The averaged value of $m_k^n(x)$ on the j^{th} cell is then automatically $m_{k,j}^n$. But to define the slopes, one uses here a quadrature of the neighbor cells with the same abscissas:

$$m_{k,j-1}^n = \sum_{\alpha=1}^p w_{j,\alpha}^- \xi_{j,\alpha}^k, \quad m_{k,j+1}^n = \sum_{\alpha=1}^p w_{j,\alpha}^+ \xi_{j,\alpha}^k, \quad k \in \{0, \dots, p-1\}. \quad (26)$$

The weights $(w_{j,\alpha}^-)_{\alpha \in \{1, \dots, p\}}$ and $(w_{j,\alpha}^+)_{\alpha \in \{1, \dots, p\}}$ are well defined since they are the solution of a linear system with a Vandermonde matrix of coefficients $\xi_{j,\alpha}$, which are distinct. If a regular initial condition is considered for (3) and if $(m_{k,j}^n)_{k \in \{0, \dots, N\}}$ is far from the boundary of the moment space, then these weights $(w_{j,\alpha}^-)_{\alpha \in \{1, \dots, p\}}$ and $(w_{j,\alpha}^+)_{\alpha \in \{1, \dots, p\}}$ are usually non-negative since the moment sets for $j-1$, j and $j+1$ are close to each other and the weights $w_{j,\alpha}$ are far from zero. But if it is not the case, the most negative $w_{j,\alpha}^+$ or $w_{j,\alpha}^-$ is set to zero and the corresponding linear system in (26) is solved for $k \in \{0, \dots, p-2\}$, thus eliminating the corresponding abscissa $\xi_{j,\alpha}$. This operation is reproduced till all the $w_{j,\alpha}^\pm$ are non-negative. At worst, only one abscissa will stay in (26). But for the distributions used in this paper, when needed, only one or two abscissas has to be eliminated when using 10 moments. One then defines the slopes by using a minmod limiter:

$$D_{\alpha,j}^n = \frac{1}{2} \left(\text{sgn}(w_{j,\alpha}^+ - w_{j,\alpha}) + \text{sgn}(w_{j,\alpha} - w_{j,\alpha}^-) \right) \min \left(\frac{|w_{j,\alpha}^+ - w_{j,\alpha}|}{\Delta x}, \frac{|w_{j,\alpha} - w_{j,\alpha}^-|}{\Delta x} \right).$$

The fluxes are then written:

$$\mathbf{F}_{j+\frac{1}{2}}^n = \frac{\sum_{\alpha=1}^p \left(w_{j,\alpha} + \frac{1}{2} D_{\alpha,j}^n (X_{j+\frac{1}{2}} - x_{j-\frac{1}{2}}) \right) \Xi_{j,\alpha}}{\Delta t^n} \left(x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}} \right)^+ - \frac{\sum_{\alpha=1}^p \left(w_{j+1,\alpha} - \frac{1}{2} D_{\alpha,j+1}^n (x_{j+\frac{3}{2}} - X_{j+\frac{1}{2}}) \right) \Xi_{j+1,\alpha}}{\Delta t^n} \left(X_{j+\frac{1}{2}} - x_{j+\frac{1}{2}} \right)^+.$$

with $\Xi_{j,\alpha} = (1, \xi_{j,\alpha}, \dots, \xi_{j,\alpha}^N)^T$. This scheme is called ‘‘quadrature weights (QW) reconstruction based kinetic scheme’’, abbreviated to ‘‘QW kinetic scheme’’. Let us remark that, since the limitation is done separately for each weight, the global reconstruction can not guarantee a maximum principle on any moments. One can however remark that the $\xi_{j,\alpha}$ are bounded by the maximal and minimal values of the abscissas corresponding to the initial moments. Indeed, the new moments \mathbf{m}_j^{n+1} correspond to a sum of weighted Dirac delta functions at $\xi_{j,\alpha}$ and $\xi_{j\pm 1,\alpha}$ with $\alpha = 1, \dots, p$. Then, the new abscissas are necessarily inbetween these values.

3.2.4. Dealing with the boundary of the moment space

Constant, ζ and QW reconstructions can be done for a moment vector at the boundary of the moment space. For the ζ reconstruction, the ζ_k for $k > \mathcal{N}(\mathbf{m}_{j,N}^n)$ are not defined but are set to zero. For the QW reconstruction, the value of p has just to be reduced to $\left\lfloor \frac{\mathcal{N}(\mathbf{m}_{j,N}^n)+1}{2} \right\rfloor$.

Numerically, the strict realizability is checked at each time step thanks to the ζ_k . Since they are deduced from the coefficients of the three term recurrence relation used for the computation of the quadrature thanks to (10), they are computed in any cases, with at worst a marginal increase of the cost. However, the computation of ζ_k can be ill-conditioned, especially if k is large and if a ζ_i is very small for $i < k$. A limit has then to be introduced: when $\zeta_k < \epsilon$, the corresponding moment vector is said to be at the boundary of the moment space and one sets $\zeta_i = 0$ for $i \geq k$. In practice, we used in this work $\epsilon = 10^{-7}$. The corresponding vector is then projected: the moments are computed from the new set of ζ_i .

4. A realizable simplified finite volume scheme

The accuracy of the kinetic schemes comes from the accuracy of the spatial reconstruction as well as the correct evaluation of the characteristics, to characterize the part of the cell containing

the particles that will be transferred to another one during the time step. For this last point, a generalization to multi-dimensional unstructured meshes is not evident. In this section, we then consider semi-discretized finite volume schemes of the form:

$$d_t \mathbf{m}_j(t) = -\frac{1}{\Delta x} \left[\mathbf{F}_{j+\frac{1}{2}}(t) - \mathbf{F}_{j-\frac{1}{2}}(t) \right], \quad \mathbf{F}_{j+\frac{1}{2}}(t) = u(t, x_{j+\frac{1}{2}}) \mathbf{m}_{j+\frac{1}{2}}(t), \quad (27)$$

where only the reconstructed value $\mathbf{m}_{j+\frac{1}{2}}(t)$ of the moment at the interface $x_{j+\frac{1}{2}}$ is considered.

The system (27) will then be solved thanks to a strong stability preserving (SSP) explicit Runge-Kutta method [47], a second order one here. It is a convex combination of Euler explicit time steps. The realizability then only have to be shown for the explicit Euler method:

$$\mathbf{m}_j^{n+1} = \mathbf{m}_j^n - \frac{\Delta t^n}{\Delta x} \left[\mathbf{F}_{j+\frac{1}{2}}^n - \mathbf{F}_{j-\frac{1}{2}}^n \right], \quad (28)$$

with $\mathbf{F}_{j+\frac{1}{2}}^n = u(t^n, x_{j+\frac{1}{2}}) \mathbf{m}_{j+\frac{1}{2}}^n$. Moreover, to deal with the boundary of the moment space, a numerical projection is also done after each of these Euler explicit time steps, as described in Section 3.2.4.

Two types of reconstruction are done to define the moment vector $\mathbf{m}_{j+\frac{1}{2}}$ at the interface, as for the kinetic scheme: a first one using the ζ_k variables and a second one using the weights of the quadrature. The realizability of the scheme is then shown in each case.

4.1. The ζ reconstruction based simplified scheme (ζ simplified scheme)

Here, the reconstruction is quite different from the one of Section 3.2.2 in order to be able to ensure the realizability with the explicit Euler method. Indeed, from the idea of Berthon [48], the cell j is split in three parts of size $\Delta x/3$ here, on which the reconstruction of the moment vector is constant. It is denoted \mathbf{m}_j^- for the left part, \mathbf{m}_j^* for the middle part and \mathbf{m}_j^+ for the right part, in such a way that:

$$\mathbf{m}_j^n = \frac{1}{3} (\mathbf{m}_j^- + \mathbf{m}_j^* + \mathbf{m}_j^+).$$

The values of the ζ_k corresponding to the moment vectors \mathbf{m}_j^n , \mathbf{m}_j^- , \mathbf{m}_j^* and \mathbf{m}_j^+ are denoted respectively $\zeta_{k,j}^n$, $\zeta_{k,j}^-$, $\zeta_{k,j}^*$ and $\zeta_{k,j}^+$.

The reconstruction is then done in the following way. For the left and right values, a classical MUSCL type of reconstruction is used:

$$m_0^\pm = m_{0,j}^n \pm D_{0,j}^n \frac{\Delta x}{2}, \quad \zeta_{k,j}^\pm = \zeta_{k,j}^n \pm D_{k,j}^n \frac{\Delta x}{2}, \quad k \in \{1, \dots, N\}, \quad (29)$$

with the minmod limiters:

$$D_{0,j}^n = \minmod \left(\frac{m_{0,j+1}^n - m_{0,j}^n}{\Delta x}, \frac{m_{0,j}^n - m_{0,j-1}^n}{\Delta x} \right), \quad (30)$$

$$D_{k,j}^n = \minmod \left(\frac{\zeta_{k,j+1}^n - \zeta_{k,j}^n}{\Delta x}, \frac{\zeta_{k,j}^n - \zeta_{k,j-1}^n}{\Delta x} \right). \quad (31)$$

Then, the values of \mathbf{m}_j^+ and \mathbf{m}_j^- can be computed. However, the vector \mathbf{m}_j^* , given by $3\mathbf{m}_j^n - \mathbf{m}_j^+ - \mathbf{m}_j^-$, is not necessarily realizable. In this case, some values of the $D_{k,j}^n$, for $k > 0$, have to

be reduced. To ensure the realizability of $(m_{0,j}^*, m_{1,j}^*)$, the following limitation on $D_{1,j}^n$ has to be added:

$$D_{0,j}^n D_{1,j}^n < \frac{2}{\Delta x^2} m_{1,j}^n.$$

For the higher order moments, it is harder to derive analytical formulas. Instead, if \mathbf{m}_j^* is not in the moment space, a correction has to be done on the slopes $D_{i,j}^n$, with $i < k$: they are reduced successively for $i = k_0, \dots, k-1$ where k_0 is the maximal value such that $(m_{0,j}^*, \dots, m_{k,j}^*)$ is realizable if the $D_{i,j}^n$ were equal to zero for $i \in [k_0, k-1]$. For that, starting with $i = k_0$ till $i = k-1$, each $D_{i,j}^n$ is divided by 2 or set to zero if it is not sufficient.

Once the reconstruction is done, the value of the fluxes is obtained by

$$\mathbf{F}_{j+\frac{1}{2}}^n = \max\{u(t^n, x_{j+\frac{1}{2}}), 0\} \mathbf{m}_j^+ + \min\{u(t^n, x_{j+\frac{1}{2}}), 0\} \mathbf{m}_{j+1}^-. \quad (32)$$

The corresponding scheme is called “ ζ reconstruction based simplified scheme”, abbreviated to “ ζ simplified scheme”. Under some limitation on the CFL number, it is realizable, as shown in the following theorem.

Theorem 4.1. *From realizable moment vectors $(\mathbf{m}_j^n)_j$, the equations (28,32) define a realizable moment vector \mathbf{m}_j^{n+1} if the CFL number is smaller than 1/3.*

Proof. The vector \mathbf{m}_j^{n+1} is given by:

$$\mathbf{m}_j^{n+1} = \mathbf{m}_j^n - \lambda_j \mathbf{m}_j^+ - \tilde{\mu}_{j-1} \mathbf{m}_j^- + \mu_j \mathbf{m}_{j+1}^- + \tilde{\lambda}_{j-1} \mathbf{m}_{j-1}^+,$$

where $\lambda_j = \frac{\Delta t^n}{\Delta x} \max\{u(t^n, x_{j+\frac{1}{2}}), 0\}$, $\mu_j = -\frac{\Delta t^n}{\Delta x} \min\{u(t^n, x_{j+\frac{1}{2}}), 0\}$, $\tilde{\lambda}_{j-1} = \frac{\Delta t^n}{\Delta x} \max\{u(t^n, x_{j-\frac{1}{2}}), 0\}$, $\tilde{\mu}_{j-1} = -\frac{\Delta t^n}{\Delta x} \min\{u(t^n, x_{j-\frac{1}{2}}), 0\}$ are coefficients between 0 and 1/3. The last two terms define some moment vectors and the rest can be written $(\frac{1}{3} - \lambda_j) \mathbf{m}_j^+ + (\frac{1}{3} - \tilde{\mu}_{j-1}) \mathbf{m}_j^- + \frac{1}{3} \mathbf{m}_j^*$ and is also realizable. \square

4.2. The quadrature weights reconstruction based simplified scheme (QW simplified scheme)

The same reconstruction of the weights is done here as for the kinetic scheme in Section 3.2.3. Using the same notation, the flux is then given by:

$$\begin{aligned} \mathbf{F}_{j+\frac{1}{2}}(t) = & \max\{u(t, x_{j+\frac{1}{2}}), 0\} \sum_{\alpha=1}^p \left(w_{j,\alpha} + \frac{\Delta x}{2} D_{\alpha,j}^n \right) \mathbf{\Xi}_{j,\alpha} \\ & + \min\{u(t, x_{j+\frac{1}{2}}), 0\} \sum_{\alpha=1}^p \left(w_{j+1,\alpha} - \frac{\Delta x}{2} D_{\alpha,j+1}^n \right) \mathbf{\Xi}_{j+1,\alpha}. \end{aligned} \quad (33)$$

The corresponding scheme is called “quadrature weights (QW) reconstruction based simplified scheme”, abbreviated to “QW simplified scheme” and is then realizable under some less restrictive limitation on the CFL number than for the ζ -simplified scheme.

Theorem 4.2. *From realizable moment vectors $(\mathbf{m}_j^n)_j$, the equations (28,33) define a realizable moment vector \mathbf{m}_j^{n+1} if the CFL number is smaller than 1/2.*

Proof. The vector \mathbf{m}_j^{n+1} can be written:

$$\begin{aligned} \mathbf{m}_j^{n+1} = & \sum_{\alpha=1}^p \left[w_{j,\alpha} - \lambda_j \left(w_{j,\alpha} + \frac{\Delta x}{2} D_{\alpha,j}^n \right) - \tilde{\mu}_{j-1} \left(w_{j,\alpha} - \frac{\Delta x}{2} D_{\alpha,j}^n \right) \right] \Xi_{j,\alpha} \\ & + \mu_j \sum_{\alpha=1}^p \left(w_{j+1,\alpha} - \frac{\Delta x}{2} D_{\alpha,j+1}^n \right) \Xi_{j+1,\alpha} + \tilde{\lambda}_{j-1} \sum_{\alpha=1}^p \left(w_{j-1,\alpha} + \frac{\Delta x}{2} D_{\alpha,j-1}^n \right) \Xi_{j-1,\alpha}, \end{aligned}$$

with the same definition of λ_j , μ_j , $\tilde{\lambda}_{j-1}$ and $\tilde{\mu}_{j-1}$ as in the proof of Theorem 4.1 but now belonging to $[0, 1/2]$. The only thing to check is the non-negativity of the weights in the first summation. If $w_{j,\alpha}$ is zero, then $D_{\alpha,j}^n = 0$ and this term is zero. Otherwise, $w_{j,\alpha}$ is positive and this term can be written:

$$w_{j,\alpha} \left[1 - \left(1 + \frac{\Delta x}{2w_{j,\alpha}} D_{\alpha,j}^n \right) \lambda_j - \left(1 - \frac{\Delta x}{2w_{j,\alpha}} D_{\alpha,j}^n \right) \tilde{\mu}_{j-1} \right],$$

which is non-negative, since necessarily $|D_{\alpha,j}^n| \leq \frac{2w_{j,\alpha}}{\Delta x}$ and λ_j and $\tilde{\mu}_{j-1}$ are smaller than 1/2. \square

5. Verification: comparisons with analytical solution in 1D configurations

Two configurations are studied here for which analytical solutions are available. For the first one, moments are transported by a constant fluid velocity in a periodic domain, whereas for the second one, moments are transported by an unsteady and compressible fluid velocity. In both cases, three initial conditions can be considered, defined either from the NDF or from the ζ_k : a regular one with moments in the interior of the moment space, an oscillating one where the ζ_k oscillate at different frequencies to test the robustness of the methods and a multi-modal one, reaching the boundary of the moment space and typical of what can be obtained in physical systems where nucleation and aggregation occur. These initial conditions are first described before comparing the results of our schemes to the analytical solution in both test cases. Then, the schemes are tested in 1D configurations with a constant or a compressible fluid velocity, considering a high number of moments, equal to 10 unless mentioned otherwise.

5.1. Initial moments

5.1.1. Regular initial NDF

A regular initial condition is defined through the following beta-NDF:

$$f_0(\xi, x) = 16x^2(1-x)^2 \frac{\xi^{\lambda(x)}(1-\xi)^{\mu(x)}}{\beta(\lambda(x), \mu(x))},$$

with

$$\lambda(x) = \frac{7}{2} + \frac{3}{2} \sin(2\pi x), \quad \mu(x) = \frac{7}{2} - \frac{3}{2} \cos(2\pi x)$$

and the initial moments are defined by $m_k^0(x) = \int_0^1 \xi^k f_0(\xi, x) d\xi$. These moments for $k \leq 6$, as well as the corresponding ζ_k are plotted in Fig. 1. They are regular and periodic.

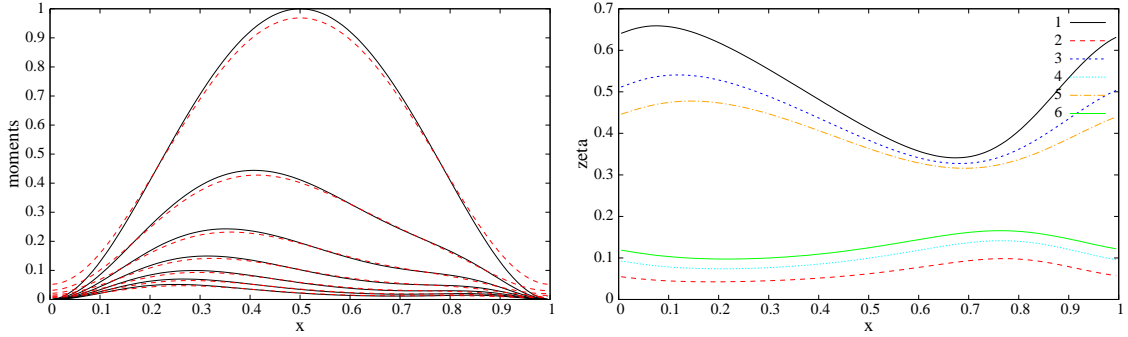


Figure 1: Constant fluid velocity test case with the regular initial solution; Right: space evolution of the moments of order 0 to 6 (top to bottom lines) for the exact initial solution (solid black lines) and for the simulation with the first order kinetic scheme at time $t = 2$ (red dashed lines). Left: initial values of the ζ_k , $k \in \{1, \dots, 6\}$.

5.1.2. Oscillating initial ζ_k

An initial solution can be also defined from a choice of the ζ_k and of m_0 . Here, oscillating functions are used for ζ_k , with a frequency increasing with k , whereas m_0 is a polynomial function:

$$\zeta_k^0(x) = \frac{x}{2} \left[1.01 + \cos\left(\frac{\pi k}{2} x\right) \right], \quad m_0^0(x) = 16x^2(1-x)^2. \quad (34)$$

This allows to recover all the initial moments, which are in the interior of the moment space, but quite close to the boundary at some points.

5.1.3. Multi-modal initial NDF

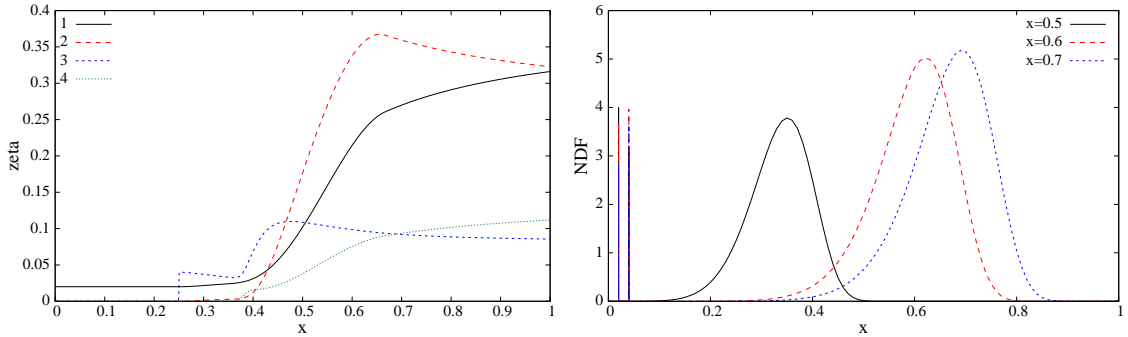


Figure 2: Left: ζ_k for $k=1,2,3,4$ as functions of the spatial location x . Right: initial distribution $f_0(\xi, x)$ as function of ξ for $x = 0.5$, $x = 0.6$ and $x = 0.7$ (for the Dirac delta functions, the absolute value of the heights of the scaled weights is arbitrary).

To test the ability of the methods to deal with the boundary of the moment space and the transition with the interior of this space, another initial distribution is introduced. It is detailed in Appendix D and the corresponding moments are regular (C^2) functions of x . Then, the distribution is only one Dirac delta function at $\xi = \xi_1 = 0.02$ for $x \in [0, \frac{1}{4}]$, in such a way that only ζ_1 is not zero, as seen in Fig. 2(left). It represents a distribution obtained through nucleation. For $x \in [\frac{1}{4}, \frac{1}{3}]$,

it is a sum of two Dirac delta functions at $\xi = \xi_1$ and $\xi = 2\xi_1$ and ζ_2 and ζ_3 are positive, with a discontinuity at $x = \frac{1}{3}$ for ζ_2 . The second peak represents particles obtained by aggregation of two initial nuclei. A continuous Rosin-Rammmler distribution is added for the rest of the domain, in such a way that the moments are then in the interior of the moment space. The obtained distribution is plotted in Fig. 2(right) for three different positions. Moreover, the corresponding moments are plotted in Fig. 7.

5.2. Results with a constant fluid velocity

To test the different schemes, let us first consider a case with a constant velocity. With no restriction, one assumes $u = 1$. Moreover, we consider the spatial domain $[0, 1]$ with periodic boundary conditions. The analytical solution at time $t = 2$ or $t = 5$ is then equal to the initial condition.

5.2.1. Numerical accuracy in a regular case

When considering the regular initial NDF, simulations are done with the three kinetic schemes on uniform meshes with a CFL number equal to 0.8 and are compared with the analytical solution at the final time $t = 2$. First, using a 100 points spatial discretization, the moments of order 0 to 6 obtained at the final time with the first order scheme are plotted in Fig. 1(left), showing its numerical diffusion whereas the other kinetic schemes lead to very precise results (not shown here).

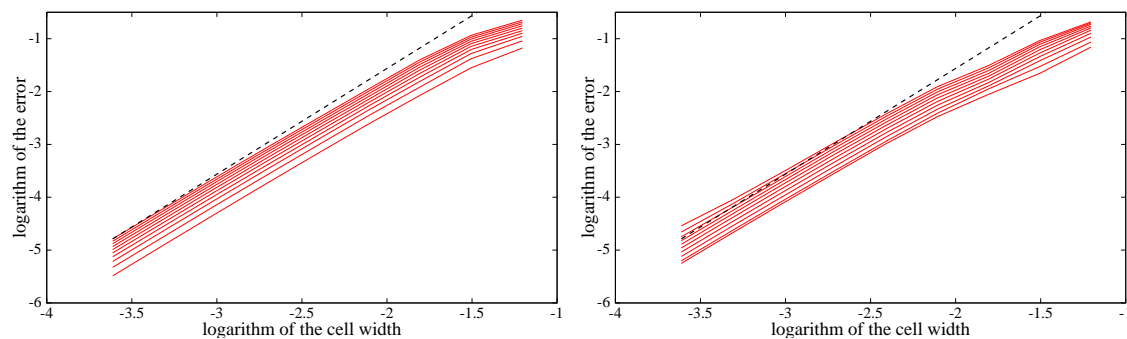


Figure 3: Constant fluid velocity test case with the regular initial NDF: L_1 norm of the error on the moments of order 0 to 9 (solid red lines, bottom to top) with the ζ kinetic scheme (left) and the QW kinetic scheme (right) for a CFL equal to 0.8. The same line of slope 2 is represented by black dashed lines on the two figures.

To evaluate more precisely the accuracy of the methods, the L_1 norm of the errors, divided by the L_1 norm of the corresponding moments, are plotted as a function of the cell width in Fig. 3, using from 16 to 4096 cells. Both the methods are numerically almost second order accurate: the order is about 1.93 for all moments with the ζ kinetic scheme and 1.91 for the moments of order 0 to 5 with the QW kinetic scheme. Moreover, the ζ kinetic scheme does not introduce any dependance on the number of considered moments in this case where no corrections are needed on the slope to ensure the positivity of the $a_{k,j}$. On the contrary, for the QW kinetic scheme, the number of considered moments has an influence on the accuracy on all moments. It can be seen in Fig. 4, where the same normalized L_1 norm of the errors are plotted when using 6 and 5 moments with this scheme. Moreover for half of the highest order moments, the order of accuracy degenerates to 1 when a fine enough mesh is used (this degenerescence did not yet really appear for the finest mesh used in the case with 10 moments). It can be explained by the fact that for the weight

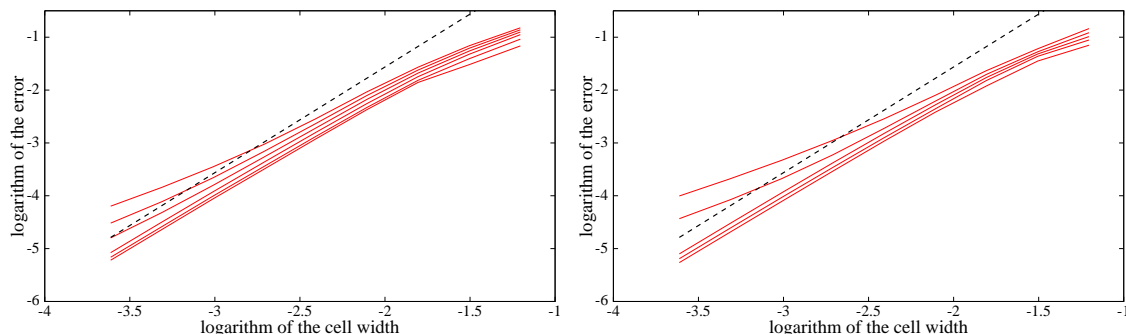


Figure 4: Constant fluid velocity test case with the regular initial solution: L_1 norm of the error on the moments of order 0 to N (solid red lines, bottom to top) with the QW kinetic scheme for a CFL equal to 0.8 and for $N = 5$ (left) and $N = 4$ (right). The same line of slope 2 is represented by black dashed lines on the two figures.

reconstruction, only half of the smallest order moments are considered in the neighboring cells. Let us also remark that, for this case, no abscissa is eliminated to ensure the positivity of the weights of the reconstruction.

When considering the simplified schemes, the CFL number is set to 0.3. The behavior of the schemes are similar (and not represented here): both the methods are also numerically almost second order accurate: the order is about 1.93 for all moments with the ζ simplified scheme and about 1.9 for the moments of order 0 to 6 with the QW simplified scheme. They are also compared

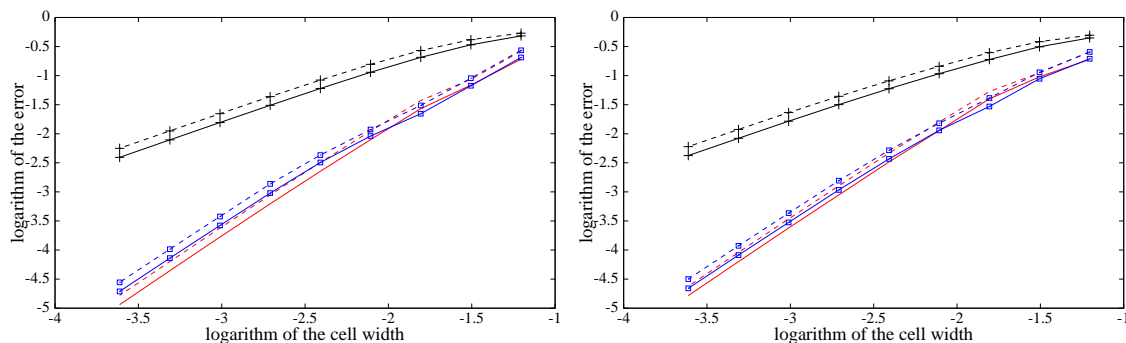


Figure 5: Constant fluid velocity test case with the regular initial NDF: L_1 norm of the error on the moments of order 0 (left) and 1 (right) with the kinetic (solid lines) of the simplified (dashed lines) schemes for a CFL equal to 0.3, using the constant (black +), the ζ (red) or the QW (blue \square) reconstruction.

to the kinetic schemes, using the same CFL equal to 0.3. The errors on the moments of order 0 and 1 are then plotted in Fig. 5. One can first remark that the accuracy of the kinetic schemes is smaller than for a CFL equal to 0.8, with more than half an order of magnitude for the difference. It can be checked in this case that the results for the simplified schemes are very little sensitive to the CFL number. Moreover, the accuracy obtained with the non-constant reconstructions of the moments are much higher than with the constant reconstruction, allowing to reduce drastically the number of cells needed for a given accuracy (about a factor 10 on the cell number for an error of 1%). This is an important point for more complex problems where a quite costly ODE system has to be solved on each cell for the resolution of the source terms. Moreover, the ζ reconstruction gives

the best results for most of the discretizations.

5.2.2. Verification in extreme cases

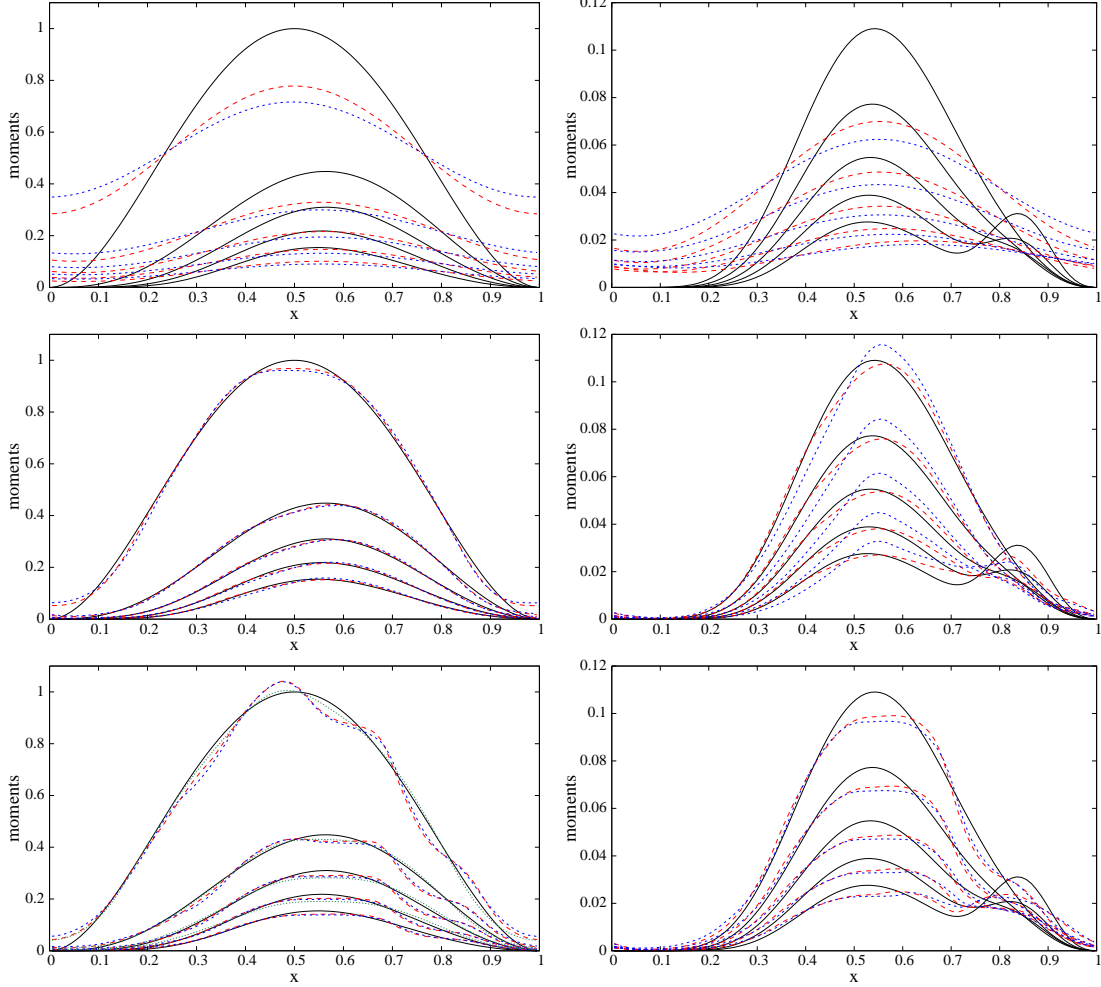


Figure 6: Constant fluid velocity test case with the oscillating initial ζ_k : space evolution of the moments of order 0 to 4 (left, top to bottom lines) and of order 5 to 8 (right, top to bottom lines for $x < 0.7$) at time $t = 5$ for the exact solution (solid black lines) and for the simulation with the constant reconstruction (top), with the ζ reconstruction (middle) and the QW reconstruction (bottom) for the kinetic scheme (red dashed line or green dots for QW with 4 moments) and the simplified scheme (blue dotted lines) with 100 points and a CFL equal to 0.3.

Let us consider more challenging test cases. The final time, $t = 5$, is larger here to amplify the phenomena. The oscillating initial ζ_k is first considered. One can see that the ζ schemes, using 100 points and a CFL number equal to 0.3, give accurate results on the moments of order 0 to 4 (see Fig. 6 middle). However, for the highest order moments, the maximum principle is no more respected and the error is larger than for the first order moments but still smaller than with the other reconstructions, at least for the kinetic scheme. With the QW schemes using 10 moments

and the same discretization (Fig. 6 bottom), the results are a little bit less good: the maximum principle is no more respected for the first order moments with some kind of oscillations around the analytical solution. However, these oscillations do not blow up and the accuracy is still better than with the first order scheme, for which the numerical diffusion flatten a lot the results (Fig. 6 top). Moreover, the accuracy of the QW schemes for the first order moments is improved by the use of a smaller number of moments.

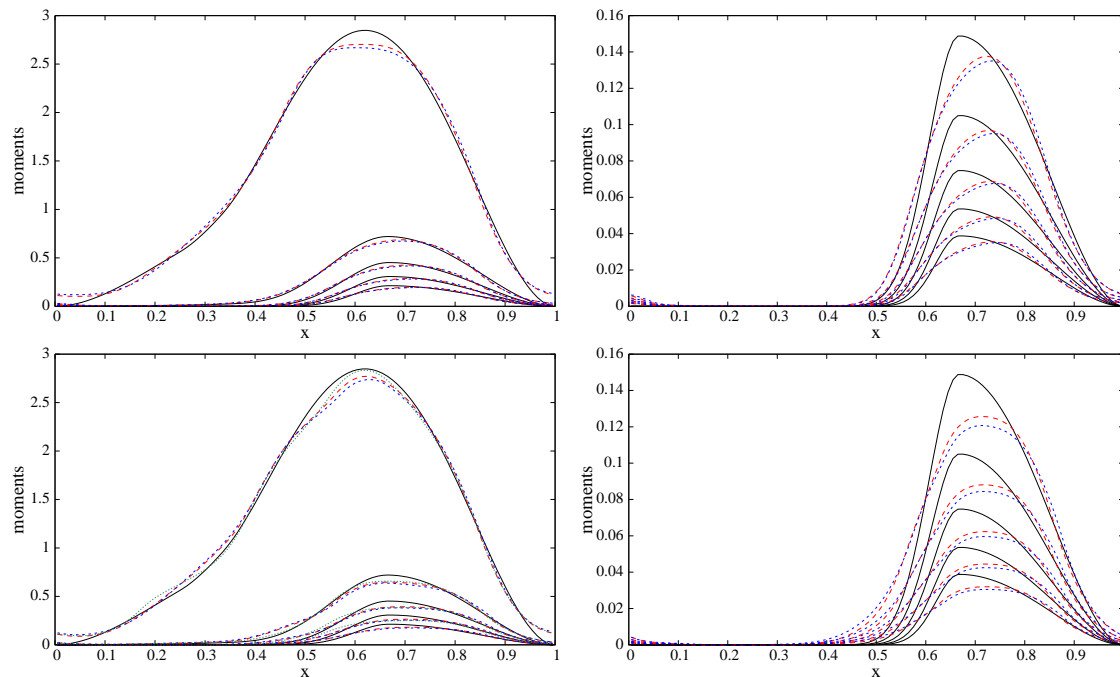


Figure 7: Constant fluid velocity test case with the multi-modal initial NDF: space evolution of the moments of order 0 to 4 (left, top to bottom lines) and of order 5 to 8 (right, top to bottom lines) at time $t = 5$ for the exact solution (solid black lines) and for the simulation with the ζ reconstruction (top) and the QW reconstruction (bottom) for the kinetic scheme (red dashed line or green dots for QW with 4 moments) and the simplified scheme (blue dotted lines) with 100 points and a CFL equal to 0.3.

Computations were done also with the multi-modal initial NDF, representing a more realistic NDF. The analytical solution as well as the solution computed with the ζ and QW schemes with 100 points and a CFL number equal to 0.3 are represented in Fig. 7. Both schemes do not encounter any problem simulating this test case, even if the moment vector is at the boundary of the moment space in some part of the domain. Moreover, in this more realistic case, the maximum principles are respected and the ζ reconstruction gives the most accurate results when using 10 moments, but the use of only 4 moments allow to improve the accuracy for the QW schemes. As it will be shown for the unsteady case, the difference of accuracy on the zeroth and first order moments is higher between the ζ and QW reconstructions when a finer discretization is used for simulations with 10 moments. However all methods are still always much more accurate than the schemes using a constant reconstruction.

5.3. Results with an unsteady and compressible fluid velocity

An unsteady fluid velocity u and the corresponding characteristics are given, for $x \in [0, 1]$ by:

$$u(t, x) = \frac{1-x}{1+t}, \quad X(t; s, x) = 1 + \frac{x-1}{1+t-s}.$$

The analytical solution is given by:

$$\mathbf{m}_N(t, x) = (1+t)\mathbf{m}_N^0(1+(x-1)(1+t)).$$

For the simulations, we use $N = 9$ and the final time is $t = 1$.

5.3.1. Numerical accuracy

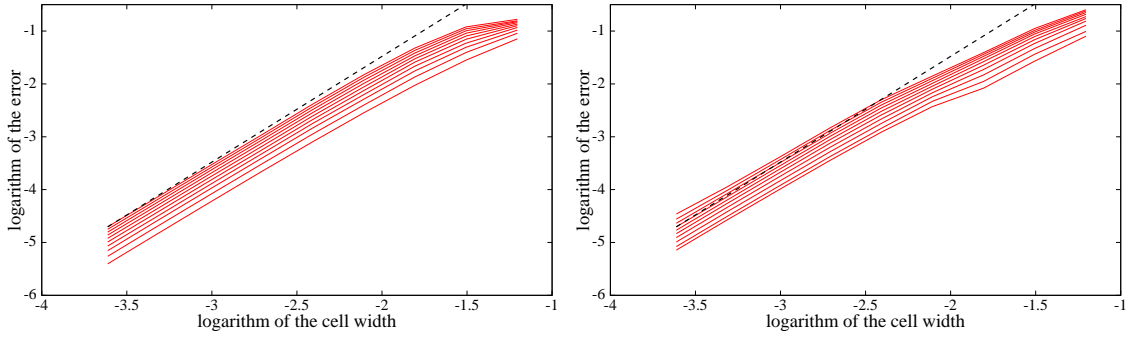


Figure 8: Unsteady fluid velocity test case with the regular initial NDF: L_1 norm of the error on the moments of order 0 to 9 (solid red lines, bottom to top) with the ζ kinetic scheme (left) and the QW kinetic scheme (right) for a CFL equal to 0.8. The same line of slope 2 is represented by black dashed lines on the two figures.

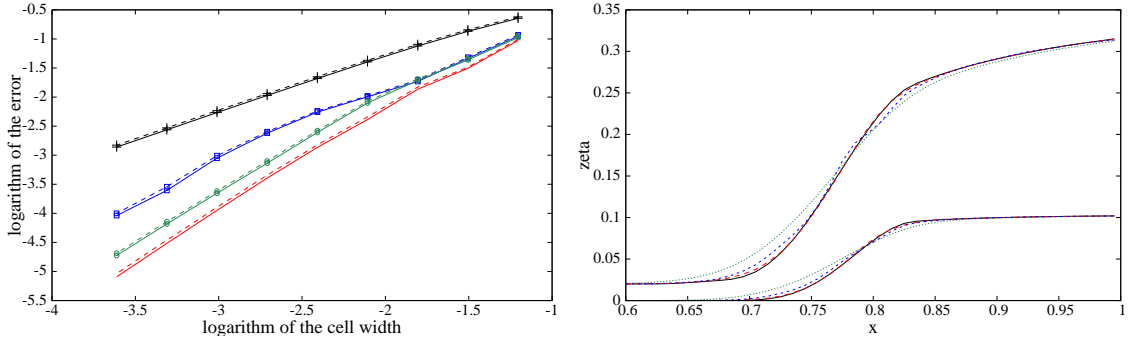


Figure 9: Unsteady fluid velocity test case with the multi-modal initial NDF. Left: L_1 norm of the error on the moments of order 0 with the kinetic (solid lines) of the simplified (dashed lines) schemes for a CFL equal to 0.3, using the constant (black +), the ζ (red) or the QW (blue \square when $N = 9$ and green \circ when $N = 3$) reconstruction. Right: space evolution of the mean value ζ_1 (top curves) and the variance $\zeta_1 \zeta_2$ (bottom curves) of the NDF at time $t = 1$ for the exact solution (solid black lines) and for the simulation with the kinetic scheme and a CFL equal to 0.8, using the constant reconstruction (dashed red lines), the ζ reconstruction (blue dashed line) and the QW reconstruction (dotted green line), with 100 points.

N	3	4	5	6	7	8	9
1 st order kinetic scheme	1.0	1.1	1.1	1.2	1.3	1.3	1.3
ζ kinetic scheme	2.7	3.1	3.4	3.8	4.1	5.3	6.6
QW kinetic scheme	2.4	2.9	2.8	3.3	3.4	3.9	4.0
1 st order simplified scheme	1.4	1.5	1.5	1.6	1.7	1.7	1.8
ζ simplified scheme	3.3	3.4	3.5	3.8	3.9	4.2	4.4
QW simplified scheme	4.4	5.1	5.0	6.0	6.2	7.4	7.5

Table 1: Unsteady fluid velocity test case with the multi-modal initial NDF: normalized computational time for a CFL number equal to 0.3.

The same kind of simulations are done in the unsteady case as with the stationary one. For the ζ and QW kinetic schemes and the regular initial NDF, the errors on the moments are shown in Fig. 8. The numerical order of accuracy is about 1.93 when using the ζ reconstruction and about 1.91 for the moments of order 0 to 5, when using the QW reconstruction. Moreover, in this case, the influence of the CFL is much smaller than with the constant fluid velocity, probably due to the interpolation error of the fluid velocity in the case of the kinetic schemes. All methods then give similar results compared to the constant fluid velocity test case, the ζ reconstruction based schemes being still a little bit more accurate.

The difference between the two kinds of reconstructions is higher when considering the multi-modal initial NDF (see Fig. 9 left), this difference being reduced when considering only 4 moments with the QW reconstruction based schemes. In any cases, the accuracy stays much higher than with the constant reconstruction. In Fig. 9(right), it can be seen that the ζ and QW kinetic schemes well capture the mean value of the distribution (corresponding to ζ_1), as well as its variance (corresponding to $\zeta_1\zeta_2$) with only 100 cells. The corresponding plot for the simplified scheme is very similar and not shown here.

5.3.2. Computational time

In the case of the multi-modal initial NDF, the computational time of the different schemes with the use of several numbers of moments are given in Table 1, when using a CFL number equal to 0.3 for all methods. This case is chosen since it is representative of physical cases and induces a fair comparison of the methods: some corrections of the slopes are needed for the ζ schemes as well as some abscissa eliminations for a few points for the QW schemes.

It shows that the computational time for the high order schemes is about 2.5 to 3 times higher than for the corresponding first order scheme, for the same discretization, except for the simplified QW scheme and for the ζ kinetic scheme with $N \geq 7$ where it is about 4 to 5 times higher. Indeed, when considering the ζ kinetic scheme, no analytical formulas are used for the computation of the very high order moments from the ζ_k and the reverse Chebychev algorithm is then used, thus increasing the cost. Moreover, for the simplified schemes, the computational times are larger due to the use of the second order SSP Runge-Kutta method, thus needing two reconstructions per time step. However, the ζ simplified scheme is still competitive, at least for the same CFL, due to the very simple reconstruction. But the CFL cannot be increased beyond 1/3, whereas the global computational time of the other methods can be decreased by an increasing of the CFL number. When considering a global problem, including source terms, the time step can however have to be limited by the coupling characteristic time between the operators [49, 28].

Finally, due to the possible reduction of the number of cells, the cost of the schemes developed here is lower than the one of the first order scheme for the same accuracy. Moreover, the number of degrees of freedom being then reduced, it implies a reduction of the global cost of the complete problem with source terms.

6. Results with 2D, steady and incompressible fluid velocity

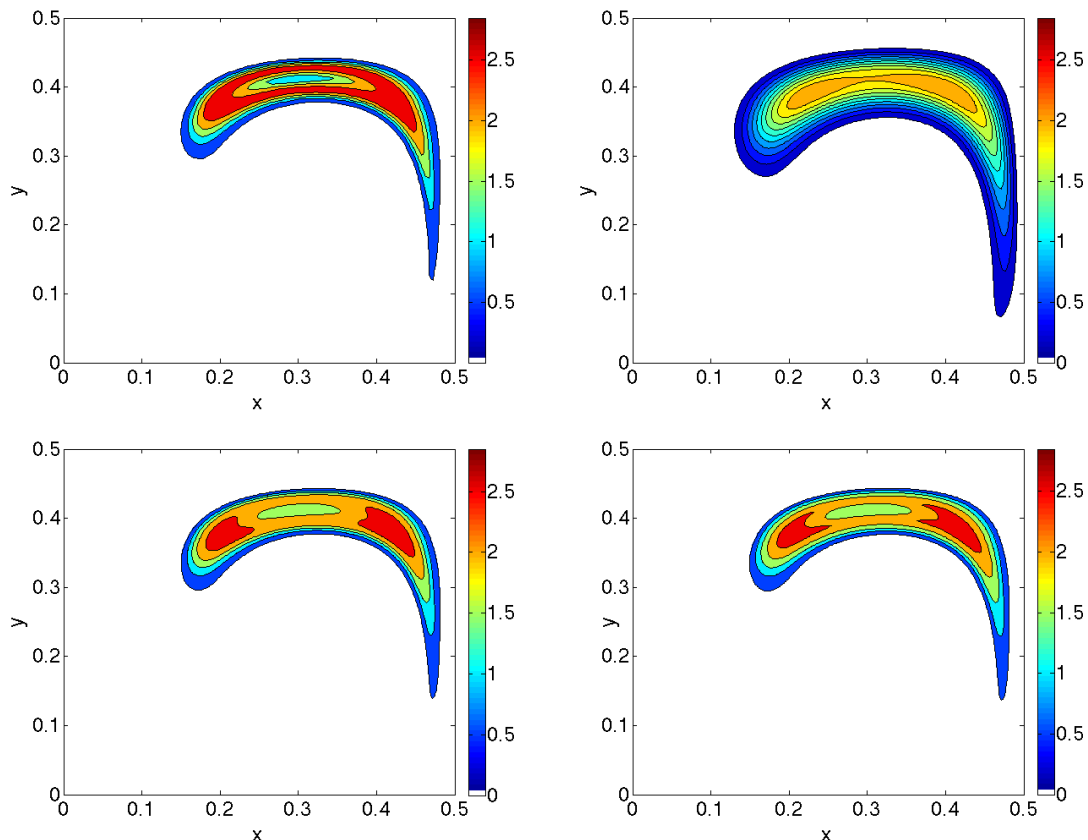


Figure 10: 2D test case: moment m_0 for the reference solution (top left), for the simulations on a 200×200 uniform mesh with a CFL number equal to 0.3, using the first order kinetic scheme (top right), the ζ kinetic scheme (bottom left) and the QW kinetic scheme (bottom right).

Let us consider a 2D configuration of particles in a vortex. The unsteady fluid velocity is then defined for $x \in [0, 1/2]$ and $y \in [0, 1/2]$ by:

$$u_x(t, x, y) = \sin(2\pi x) \cos(2\pi y), \quad u_y(t, x, y) = -\cos(2\pi x) \sin(2\pi y).$$

Let us introduce the distance r to the point $(1/8, 1/8)$. A population of particles is initially present in the vortex, in a disc defined by $r < 1/8$. Its distribution is given by $f_0(\xi, 1 - 8r)$, where f_0 corresponds to the multi-modal NDF defined by (D.1), with a weight $w_3(x)$ now being equal to 1

for $x \in [2/3, 1]$. This population is then transported by the fluid till the time $t = 0.8$. Due to the incompressibility of the fluid phase, the value of the moments are conserved along the characteristics. A reference solution is then computed by solving reverse characteristics from each position, using a high order ODE solver with time step adaptation. For example, the zeroth order moments obtained with this method is given in Fig. 10(top left).

Simulations are done for moments of order 0 to 9, using a 200×200 uniform discretization and a CFL number equal to 0.3. To solve the 2D problem, a dimensional splitting is used: a 1D scheme is used alternatively on one-dimensional problems in the x and y directions. To obtain a second order of accuracy with this splitting method but using the same CFL number for each operator, steps of length Δt are used on each problem, but alternating the order of these steps in alternate time steps [50].

Since the kinetic and the simplified schemes give very similar results, only the results with the kinetic scheme are presented here. The zeroth order moment is plotted in Fig. 10. One can see the good level of accuracy of the ζ and QW kinetic schemes, especially compared to the first order scheme.

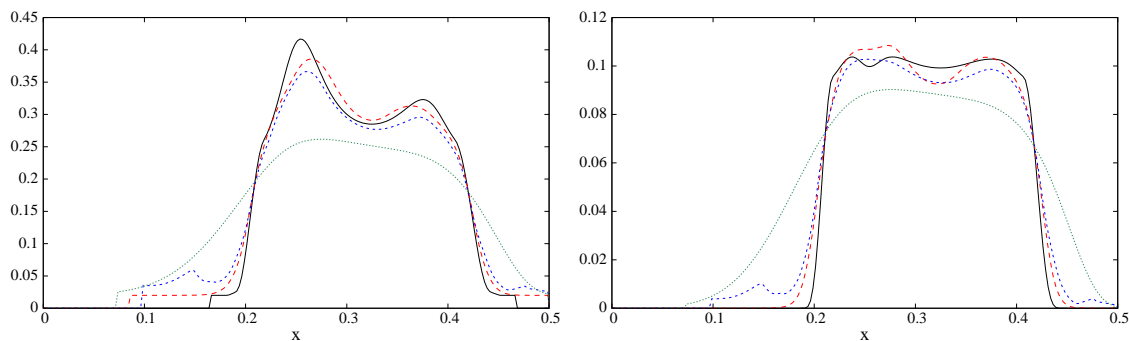


Figure 11: 2D test case: mean value (left) and variance (right) of the distribution as a function of x at $y = 0.4$ for the reference solution (black solid line), for the simulations on a 200×200 uniform mesh and a CFL number equal to 0.3, with the first order kinetic scheme (green dots), with the ζ kinetic scheme (red dashed line) and with the QW kinetic scheme (blue dotted line)

For going further in the comparisons, the mean value of the distribution, *i.e.* m_1/m_0 and its variance, *i.e.* $\zeta_1\zeta_2$ are plotted in Fig. 11 as functions of x at $y = 0.4$. The high numerical diffusion of the first order scheme is still remarkable, whereas the ζ and QW kinetic schemes allow to capture accurately these quantities.

7. Conclusion

In this paper, we have provided four realizable accurate finite volume schemes for the transport of moments by a given velocity field, in Cartesian mesh context: for the ones, the flux computation is based on a follow-up of the characteristics (kinetic schemes) and for the other, it is based on the value of the moments at the interface (simplified schemes). In any case, a spatial reconstruction of the moments is needed and done by reconstructing variables that only have to be non-negative: either the corresponding ζ_k variables or the weights of the corresponding quadrature. Unlike previous developed realizable Eulerian schemes, they are able to deal with moments vectors of all sizes, at least till 10 moments, possibly at the boundary of the moment space, which can occur in practical

applications. The verifications have been done on various test cases, 1D and 2D, with steady or unsteady and compressible or incompressible fluid velocities. The developed schemes then showed their high accuracy, compared to the first order scheme, and their second order of accuracy for all moments in the case of the ζ reconstruction and for half the lowest order ones for the QW reconstruction. The kinetic schemes are more accurate than the simplified scheme, especially due to the fact that a higher CFL number can be used. But their generalization to unstructured meshes seems less easy than for the simplified schemes. Moreover, the ζ reconstruction leads to slightly better accuracy than the QW one in most cases. And the accuracy on the QW schemes is much more sensitive to the number of considered moments and can eventually decrease when this number increases. Finally, for a given accuracy, the cost of all the developed schemes is usually lower than the one of the first order scheme. And since they all allow a high reduction of the number of degrees of freedom, the global cost of the complete problem with source terms can be drastically reduced by using these schemes, compared to the first order ones, thus showing the great interest of such kind of schemes. Moreover, we are studying an implementation of a simplified scheme in the open-source computational fluid dynamics toolbox OpenFOAM as part of the Open-QBMM project [51, 52].

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Appendix A. Case of a compact support

Let us consider here the case where the support of the NDF is included in a known compact interval of the form $[0, \xi_{\max}]$. The moments are then denoted m_k and the corresponding “dimensionless” moments are $\tilde{m}_k = \frac{m_k}{\xi_{\max}^{k+1}}$. They correspond to moments on the support $[0, 1]$ and

are obtained through the change of variables $\xi \mapsto \frac{\xi}{\xi_{\max}}$. Then, a second kind of Hankel determinant has to be defined:

$$\overline{H}_{2n+d} = \begin{vmatrix} \tilde{m}_{1-d} - \tilde{m}_{2-d} & \dots & \tilde{m}_n - \tilde{m}_{n+1} \\ \vdots & \vdots & \vdots \\ \tilde{m}_n - \tilde{m}_{n+1} & \dots & \tilde{m}_{2n-1+d} - \tilde{m}_{2n+d} \end{vmatrix},$$

with $d = 0, 1; n \geq 0$. Similarly to the case with support in $[0, +\infty)$, one has the following characterization of the moment space [22]: the vector $\mathbf{m}_N = (m_1, \dots, m_N)^t$ is realizable (*i.e.* in the moment space) if and only if

$$\underline{H}_k \geq 0 \text{ and } \overline{H}_k \geq 0, \quad k \in \{0, 1, \dots, N\}.$$

Moreover, it is strictly realizable (*i.e.* in the interior of the moment space) if and only if these Hankel determinants are positive.

From the ζ_k corresponding to the moments m_k (then the ζ_k/ξ_{\max} correspond to the \tilde{m}_k), one can defined the canonical moments p_k by $\zeta_k = \xi_{\max} p_k (1 - p_{k-1})$. Their geometrical interpretation

can be given from the m_k^- and m_k^+ , which are now in $[0, m_0 \xi_{\max}^k]$ [22]:

$$p_k = \frac{m_k - m_k^-(\mathbf{m}_{k-1})}{m_k^+(\mathbf{m}_{k-1}) - m_k^-(\mathbf{m}_{k-1})}. \quad (\text{A.1})$$

If $m_k(\mu)$ is equal to $m_k^+(\mathbf{m}_{k-1})$ or $m_k^-(\mathbf{m}_{k-1})$ for $\mu \in \mathcal{P}(\mathbf{m}_{k-1})$, (*i.e.* p_k is 0 or 1), the measure μ is a sum of weighted Dirac distributions and \mathbf{m}_k belongs to the boundary of the moment space.

In this case of compact support, the QW schemes can be applied without any change. However, the ζ -schemes have to be adapted: the reconstruction has then to be done on the canonical moments to ensure the realizability for the corresponding support. In the case of the reconstruction for the kinetic scheme, the reconstructed ζ_k used for the flux computation in (25) are then $\zeta_k^n(x) = \xi_{\max} p_k^n(x)(1 - p_{k-1}^n(x))$ where $p_k^n(x) = \bar{p}_{k,j}^n + D_{k,j}^n(x - x_j)$ on the j^{th} cell and $\bar{p}_{k,j}^n = a_{k,j} + b_{k,j} D_{k,j}^n$. The coefficients $a_{k,j}$ and $b_{k,j}$ are now given by:

$$a_{k,j} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \xi_{\max}^k \prod_{i=1}^{k-1} p_i^n(x)(1-p_i^n(x)) dx = \Delta x m_{k,j}^n - \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) P_k(\zeta_1^n(x), \dots, \zeta_{k-1}^n(x)) dx,$$

$$b_{k,j} \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} m_0^n(x) \xi_{\max}^k \prod_{i=1}^{k-1} p_i^n(x)(1-p_i^n(x)) dx = - \int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} (x - x_j) m_0^n(x) \xi_{\max}^k \prod_{i=1}^{k-1} p_i^n(x)(1-p_i^n(x)) dx.$$

The same kind of slope limiters and corrections are used as for the ζ kinetic scheme. For the simplified scheme, the reconstructed ζ_k are $\zeta_{k,j}^\pm = \xi_{\max} p_{k,j}^\pm (1 - p_{k-1,j}^\pm)$ with $p_{k,j}^\pm = p_{k,j}^n \pm \frac{D_{k,j}^n}{2}$, the slope $D_{k,j}^n$ being obtained through a minmod limitation from the $p_{k,i}^n$. The values of the fluxes are then given by (32). Let us remark that the corresponding schemes can be used in the more general case of a support in $[0, +\infty)$ by using for ξ_{\max} the largest value of the abscissas obtained by a quadrature on each moment set at time t^n . Moreover, this value can only decrease with the transport schemes and the moments are then always bounded.

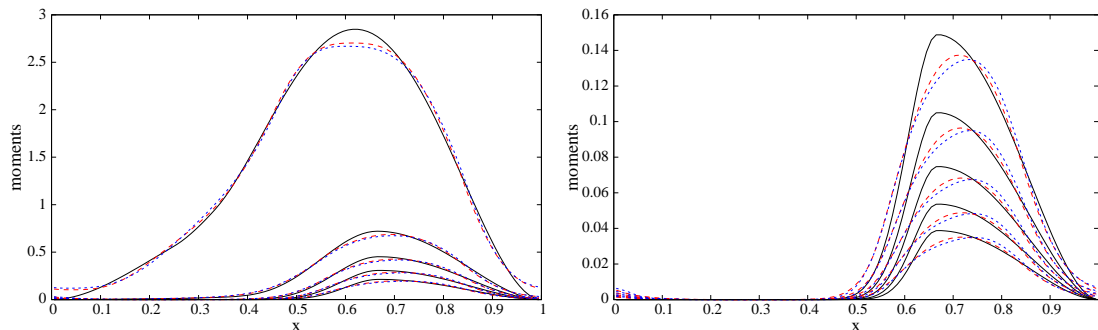


Figure A.12: Constant fluid velocity test case with the multi-modal initial NDF: space evolution of the moments of order 0 to 4 (left, top to bottom lines) and of order 5 to 8 (right, top to bottom lines) at time $t = 5$ for the exact solution (solid black lines) and for the simulation with the canonical moments reconstruction for the kinetic scheme (red dashed lines) and the simplified scheme (blue dotted lines) with 100 points and a CFL equal to 0.3.

These schemes are used in the constant fluid velocity test case with the multi-modal initial NDF. The 10 moments obtained by the simulation with 100 cells are plotted in Fig. A.12. It shows a similar accuracy compared to the ζ schemes.

Appendix B. Examples of realizability constraints for moments on $[0, +\infty)$

The first constraints (6) for the strict realizability of a moment vector $(m_0, m_1, \dots)^t$ can be written, making appear the values of $m_k^-(\mathbf{m}_{k-1})$: $m_0 > 0$, $m_1 > 0$,

$$m_2 > \frac{m_1^2}{m_0}, \quad m_3 > \frac{m_2^2}{m_1}, \quad m_4 > \frac{m_0 m_3^2 - 2m_1 m_2 m_3 + m_2^3}{m_2 m_0 - m_1^2}, \dots$$

Appendix C. Moments as functions of the ζ_k

The moments can be written from the ζ_k : $m_k = m_0 \left[P_k(\zeta_1, \dots, \zeta_{k-1}) + \prod_{j=1}^k \zeta_j \right]$, as shown in Proposition 2.2. The first polynomial functions P_k are given by:

$$\begin{aligned} P_1 &= 0, \\ P_2(\zeta_1) &= \zeta_1^2, \\ P_k(\zeta_1, \dots, \zeta_{k-1}) &= \zeta_1 \left[(\zeta_1 + \zeta_2)^{k-1} + \zeta_2 \zeta_3 Q_k(\zeta_1, \dots, \zeta_{k-1}) \right], \quad k \geq 3, \end{aligned}$$

with

$$\begin{aligned} Q_3(\zeta_1, \zeta_2) &= 0, \\ Q_4(\zeta_1, \zeta_2, \zeta_3) &= 2(\zeta_1 + \zeta_2) + \zeta_3, \\ Q_5(\zeta_1, \dots, \zeta_4) &= 3(\zeta_1 + \zeta_2)^2 + 2(\zeta_1 + \zeta_2)(\zeta_3 + \zeta_4) + (\zeta_3 + \zeta_4)^2 + \zeta_2 \zeta_3, \\ Q_6(\zeta_1, \dots, \zeta_5) &= 4(\zeta_1 + \zeta_2)^3 + 2(\zeta_1 + \zeta_2)(\zeta_3 + \zeta_4)^2 + (\zeta_3 + \zeta_4)^3 + 2\zeta_2 \zeta_3(\zeta_3 + \zeta_4) \\ &\quad + 2\zeta_4 \zeta_5(\zeta_1 + \zeta_2 + \zeta_3 + \zeta_4) + \zeta_4 \zeta_5^2 + 3\zeta_3(\zeta_1 + \zeta_2)(\zeta_1 + 2\zeta_2) \\ &\quad + 3\zeta_4(\zeta_1 + \zeta_2)^2, \\ Q_7(\zeta_1, \dots, \zeta_6) &= 5(\zeta_1 + \zeta_2)^4 + 2(\zeta_1 + \zeta_2)(\zeta_3 + \zeta_4)^3 + (\zeta_3 + \zeta_4)^4 \\ &\quad + 3\zeta_2 \zeta_3(\zeta_3 + \zeta_4)^2 + 2\zeta_4 \zeta_5 \zeta_6(\zeta_1 + \zeta_2 + \zeta_3 + \zeta_4 + \zeta_5) + \zeta_4 \zeta_5 \zeta_6^2 \\ &\quad + 6\zeta_3 \zeta_4(\zeta_1 + \zeta_2)(\zeta_1 + 2\zeta_2) + 3\zeta_4 \zeta_5(\zeta_1 + \zeta_2)^2 + 4(\zeta_1 + \zeta_2)^3 \zeta_4 \\ &\quad + 2(\zeta_1 + \zeta_2)^2(2\zeta_1 + 5\zeta_2)\zeta_3 + 3\zeta_4 \zeta_5(\zeta_3 + \zeta_4)^2 \\ &\quad + 4(\zeta_1 + \zeta_2)(\zeta_3 + \zeta_4)\zeta_4 \zeta_5 + \zeta_3^2(10\zeta_2^2 + 12\zeta_1 \zeta_2 + 3\zeta_1^2) \\ &\quad + 3(\zeta_1 + \zeta_2)^2 \zeta_4^2 + 2\zeta_4 \zeta_5^2(\zeta_1 + \zeta_2 + \zeta_3) + \zeta_4 \zeta_5^3 + 3\zeta_4^2 \zeta_5^2 + 2\zeta_2 \zeta_3 \zeta_4 \zeta_5. \end{aligned}$$

Appendix D. Multi-modal initial NDF

The multi-modal NDF is defined by:

$$f_0(\xi, x) = w_1(x)\delta_{\xi_1}(\xi) + w_2(x)\delta_{2\xi_1}(\xi) + w_3(x)R(x, \lambda(x), k(x)), \quad (\text{D.1})$$

with $\xi_1 = 0.02$ and where R is the Rosin-Rammler pdf:

$$R(\xi, \lambda, k) = \frac{k}{\lambda} \left(\frac{x}{\lambda} \right)^{k-1} \exp \left(- \left(\frac{x}{\lambda} \right)^k \right).$$

The weights w_1 , w_2 and w_3 are regular (C^2) and fourth order polynomial by part functions. They are plotted in Fig. D.13(left). The parameters λ and k of the Rosin-Rammler pdf are regular (C^2) and third order polynomials by parts functions plotted in Fig. D.13(right).

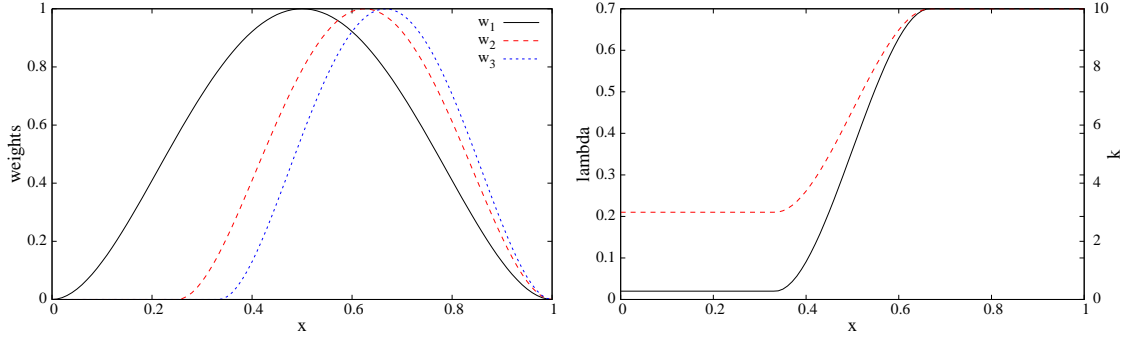


Figure D.13: Left: weights w_1 , w_2 and w_3 as functions of the spatial location x . Right: functions $\lambda(x)$ (black solid line) and $k(x)$ (red dashed line).

Appendix E. Reconstruction at the level of the NDF

Another way to reconstruct the moments $\mathbf{m}^n(x)$ is to consider a spatial reconstruction at the NDF level [42, 43]. Let us then reconstruct a NDF f_j^n from the moment set $(m_{k,j}^n)_{k \in \{0, \dots, N\}}$, using EQMOM or entropy maximization and let us define

$$f^n(x, \xi) = f_j^n(\xi) + D_j^n(\xi)(x - x_j), \quad x \in [x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}].$$

The slope is defined thanks to a minmod limiter:

$$D_j^n(\xi) = \frac{1}{2} \left(\text{sgn}(f_{j+1}^n(\xi) - f_j^n(\xi)) + \text{sgn}(f_j^n(\xi) - f_{j-1}^n(\xi)) \right) \min \left(\frac{|f_{j+1}^n(\xi) - f_j^n(\xi)|}{\Delta x}, \frac{|f_j^n(\xi) - f_{j-1}^n(\xi)|}{\Delta x} \right)$$

and the reconstructed moments for the kinetic scheme are then $m_k^n(x) = \int_0^{+\infty} \xi^k f^n(x, \xi) d\xi$. Practically, a quadrature on the ξ variable is used to compute the fluxes. But here, to ensure the [P1] property, this quadrature has to correspond to the measure $f_j(\xi) d\xi$, *i.e.*

$$m_{k,j}^n = \int_0^{+\infty} \xi^k f_j(\xi) d\xi = \sum_{\alpha=1}^{N_q} \bar{w}_{\alpha,j} \xi_{\alpha,j}^k = \sum_{\alpha=1}^{N_q} w_{\alpha,j} \xi_{\alpha,j}^k f_j^n(\xi_{\alpha,j}), \quad k \in \{0, \dots, N\},$$

where we define $w_{\alpha,j} = \bar{w}_{\alpha,j}/f_j^n(\xi_{\alpha,j})$, since $f_j^n(\xi_{\alpha,j})$ cannot be zero. In the case of EQMOM reconstruction, the weights $\bar{w}_{\alpha,j}$ and abscissas $\xi_{\alpha,j}$ can correspond to the secondary quadrature [19, 10]. This then leads to:

$$m_k^n(x) = \int_0^{+\infty} \xi^k [f_j^n(\xi) + D_j^n(\xi)(x - x_j)] d\xi = \sum_{\alpha=1}^{N_q} w_{\alpha,j} \xi_{\alpha,j}^k (f_j^n(\xi_{\alpha,j}) + D_j^n(\xi_{\alpha,j})(x - x_j)).$$

The corresponding kinetic scheme is then realizable and the flux are written:

$$\begin{aligned} \mathbf{F}_{j+\frac{1}{2}}^n &= \frac{1}{\Delta t^n} \sum_{\alpha=1}^{N_q} \left(w_{j,\alpha} f_j^n(\xi_{\alpha,j}) + \frac{D_{\alpha,j}^n}{2} (X_{j+\frac{1}{2}} - x_{j-\frac{1}{2}}) \right) \Xi_{j,\alpha} \left(x_{j+\frac{1}{2}} - X_{j+\frac{1}{2}} \right)^+ \\ &\quad - \frac{1}{\Delta t^n} \sum_{\alpha=1}^{N_q} \left(w_{j+1,\alpha} f_j^n(\xi_{\alpha,j+1}) - \frac{D_{\alpha,j+1}^n}{2} (x_{j+\frac{3}{2}} - X_{j+\frac{1}{2}}) \right) \Xi_{j+1,\alpha} \left(X_{j+\frac{1}{2}} - x_{j+\frac{1}{2}} \right)^+. \end{aligned} \quad (\text{E.1})$$

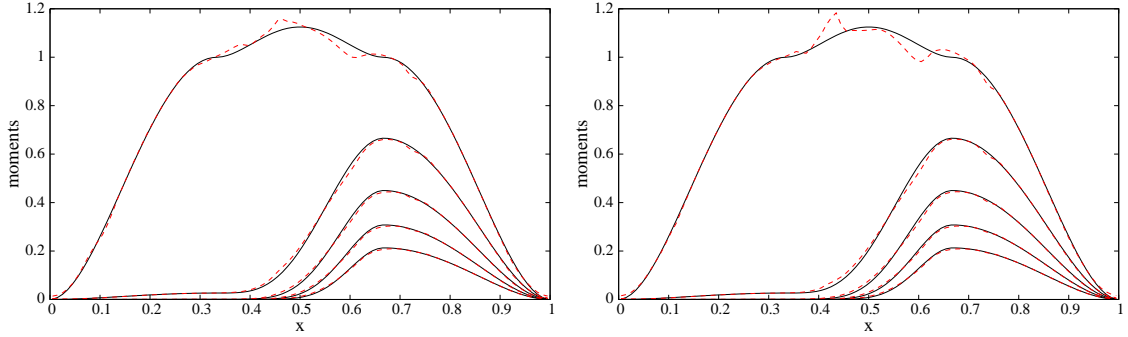


Figure E.14: Constant fluid velocity test case with a multi-modal initial NDF: space evolution of the moments of order 0 to 6 (top to bottom) at time $t = 1$ for the exact solution (solid black lines) and for the simulation with the kinetic scheme using a reconstruction of the NDF with the gamma-EQMOM (left, red dashed lines) and the log-normal-EQMOM (right, red dashed lines) with 100 cells and a CFL equal to 0.8.

However, there are three drawbacks for this kind of scheme. First, it depends on the choice of the NDF reconstruction, since several reconstructions are possible, and it also adds the cost of the reconstruction itself, which is not negligible. However, such kind of reconstruction is usually needed for the other operators present in the complete physical problem. The second and more problematic drawback comes from the impossibility to deal with the boundary of the moment space with this kind of method. Finally, the maximum principle on the moments may not be preserved. This can be illustrated on a multi-modal but regular initial NDF:

$$f_0(\xi, x) = 9x^2(2 - 3x)^2 \mathbb{1}_{[0, 2/3]}(x) R(\xi, \lambda_1, k_1) + 9(3x - 1)^2(1 - x)^2 \mathbb{1}_{[1/3, 1]}(x) R(\xi, \lambda(x), k(x)),$$

where R is the Rosin-Rammler pdf and with $\lambda_1 = 0.03$, $k_1 = 2$. The parameters $\lambda(x)$ and $k(x)$ are plotted in Fig. D.13(right). Here, both the gamma and the log-normal EQMOM reconstructions [19, 20, 10] are used to compute fluxes defined by (E.1). The result of the simulations for 5 moments with the corresponding kinetic scheme with 100 cells and a CFL number equal to 0.8 are plotted in Fig. E.14. The maximal principle is not respected for the zeroth order moment and the results depend on the reconstruction, with a slightly better behavior here when using the gamma-EQMOM.

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