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# Angles Between Euclidean Subspaces 

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#### Abstract

The angle between two subspaces of dimensions $p$ and $q$ in a Euclidean space is considered by using exterior algebra. Some properties of angles are obtained. The relation between such a higher dimensional angle and the usual principal angles is also given. And finally, an application to Grassmann manifolds is briefly discussed.


Mathematics Subject Classifications (1991): 51M05, 51M16, 51K05.
Key words: higher-dimensional angle; principal angles; Grassmann manifolds.
The trigonometry in a higher-dimensional Euclidean space has been studied by several authors. Döband [1] proved the generalized law of cosines, the Pythagorean theorem and the Heron formula for $n$-simplices in a Euclidean space by means of determinants. Eriksson [2] generalized the law of sines. S.-Y. T. Lin and Y.-F. Lin [3] gave a new approach of the $n$-dimensional Pythagorean theorem. And, Miao and Ben-Israel [4] established some new properties for the principal angles between subspaces in a Euclidean $n$-space. These principal angles have an important application in statistics to the canonical correlation theory of Hotelling [5].

In this paper we will consider the angle between two subspaces in an $n$ dimensional Euclidean space $E^{n}$, derive some new properties, find the relation between the higher dimensional angle and the principal angles of two subspaces, and briefly discuss an example of application to the geometry of Grassmann manifolds.

## 1. Preliminaries

For convenience, we will use exterior algebra for computations, it makes the results clear and the proofs simpler. In this section we briefly state some basic facts about exterior or Grassmann algebra which are needed in our paper; for details see, for example, Bourbaki [6, ch. 3], or Flanders [7, ch. 2].

Let $E^{n}$ be an $n$-dimensional real linear space endowed with a Euclidean inner product. For two vectors $a$ and $b$, denote by $a \cdot b$ their inner product.

The symbol $\wedge^{p} E^{n}$ denotes the linear space consisting of all linear combinations with real coefficients of wedges of $p$ vectors in $E^{n}, 1 \leq p \leq n$. Elements of $\wedge^{p} E^{n}$
are called $p$-vectors over $E^{n}$. A $p$-vector is said to be simple or decomposable, if it can be decomposed as a single wedge of $p$ vectors in $E^{n}$.

An induced product in $\wedge^{p} E^{n}$ can be naturally introduced as follows.
For a pair of $p$-vectors

$$
\alpha=a_{1} \wedge a_{2} \wedge \cdots \wedge a_{p}, \quad \beta=b_{1} \wedge b_{2} \wedge \cdots \wedge b_{p}
$$

define

$$
\langle\alpha, \beta\rangle=\operatorname{det}\left(a_{i} \cdot b_{j}\right)
$$

We can prove the following
LEMMA 1. The linear space $\wedge^{p} E^{n}$ endowed with $\langle$,$\rangle is a Euclidean space.$
Proof. Choosing in $E^{n}$ an orthonormal basis $\left\{e_{j}\right\}, j=1,2, \ldots, n$, we get in $\wedge^{p} E^{n}$ an induced orthonormal basis $\left\{E_{K}\right\}, K=1,2, \ldots,\binom{n}{p}$, where the $E_{K}$ 's are the wedges of $p$ different vectors $e_{j}$ (see Flanders [7, p. 14]). An arbitrary $p$-vector $\alpha$ can be decomposed as

$$
\alpha=\sum_{K} \lambda_{K} E_{K}
$$

where the $\lambda_{K}$ 's are real scalars. So

$$
\langle\alpha, \alpha\rangle=\sum_{K}\left(\lambda_{K}\right)^{2}
$$

Hence for any $\alpha \in \wedge^{p} E^{n},\langle\alpha, \alpha\rangle=0$ if and only if $\alpha=0$. Consequently $\langle$, defines a Euclidean inner product.

COROLLARY. For arbitrary $\alpha, \beta \in \wedge^{p} E^{n}$, we have

$$
\langle\alpha, \alpha\rangle\langle\beta, \beta\rangle \geq\langle\alpha, \beta\rangle^{2}
$$

where equality holds if and only if $\alpha$ differs from $\beta$ only in a scalar factor.
Remark. The length of a $p$-vector $\alpha$ is defined by

$$
|\alpha|=\sqrt{\langle\alpha, \alpha\rangle}
$$

$\alpha=0$ if and only if $|\alpha|=0$.

## 2. Higher Dimensional Angle

Let $\alpha=a_{1} \wedge a_{2} \wedge \cdots \wedge a_{p}$ be a nonzero decomposable $p$-vector. Then $\alpha$ corresponds to a $p$-dimensional subspace $A^{p}$ of $E^{n}$ spanned by $a_{1}, a_{2}, \ldots, a_{p}$. Conversely, for
any basis of the vector subspace $A^{p}$, the wedge of basis vectors equals $k \alpha$, where $k$ is a nonzero real number.

Further, suppose that $1 \leq p \leq q<n$, and

$$
\begin{align*}
& \alpha=a_{1} \wedge a_{2} \wedge \cdots \wedge a_{p}  \tag{1}\\
& \beta=b_{1} \wedge b_{2} \wedge \cdots \wedge b_{q} \tag{2}
\end{align*}
$$

If $A$ and $B$ are the subspaces corresponding to $\alpha$ and $\beta$, respectively, and $B^{\perp}$ is the orthogonal complement of $B$ in $E^{n}$, then we have

$$
a_{j}=a_{j}^{H}+a_{j}^{V}
$$

where

$$
a_{j}^{H} \in B, \quad a_{j}^{V} \in B^{\perp}, \quad j=1,2, \ldots, p
$$

Put

$$
\begin{aligned}
\alpha_{H} & =a_{1}^{H} \wedge a_{2}^{H} \wedge \cdots \wedge a_{p}^{H}, \\
\alpha_{V} & =a_{1}^{V} \wedge a_{2}^{V} \wedge \cdots \wedge a_{p}^{V}, \\
\alpha_{M} & =\alpha-\alpha_{H}-\alpha_{V} .
\end{aligned}
$$

Then we have a decomposition

$$
\begin{equation*}
\alpha=\alpha_{H}+\alpha_{V}+\alpha_{M} \tag{3}
\end{equation*}
$$

where $\alpha_{H}, \alpha_{V}$ and $\alpha_{M}$ are called the horizontal, vertical and mixed parts, respectively, of $\alpha$. By direct computation, we get the following lemmas.

LEMMA 2. The decomposition (3) is invariant under transformations of basis in subspace A. Precisely, if in the linear subspace $A$ we choose another basis $\left\{a_{i}^{\prime}\right\}$, we have the corresponding $p$-vector $\alpha^{\prime}$ and projections $\alpha_{H}^{\prime}, \alpha_{V}^{\prime}$ and $\alpha_{M}^{\prime}$, and

$$
\alpha^{\prime}=k \alpha, \quad \alpha_{H}^{\prime}=k \alpha_{H}, \quad \alpha_{V}^{\prime}=k \alpha_{V}, \quad \alpha_{M}^{\prime}=k \alpha_{M}
$$

for some nonzero scalar $k$.
LEMMA 3. $\left\langle\alpha, \alpha_{H}\right\rangle \geq 0$, where equality holds if and only if $\alpha_{H}=0$.
LEMMA 4. $|\alpha|^{2}=\left|\alpha_{H}\right|^{2}+\left|\alpha_{V}\right|^{2}+\left|\alpha_{M}\right|^{2}$.

Proof. One easily verifies that

$$
\left\langle\alpha_{H}, \alpha_{V}\right\rangle=\left\langle\alpha_{H}, \alpha_{M}\right\rangle=\left\langle\alpha_{V}, \alpha_{M}\right\rangle=0 .
$$

DEFINITION. The angle $\theta$ between subspaces $A^{p}$ and $B^{q}, p \leq q$, is defined by

$$
\begin{equation*}
\theta=\arccos \frac{\left|\alpha_{H}\right|}{|\alpha|} . \tag{4}
\end{equation*}
$$

Remark 1. The concept of the $p$-dimensional angle defined above is a natural generalization of classical angles such as the angles between two lines, a line and a plane, and between two planes. By Lemma 4, it is clear that $\theta$ is real and satisfies

$$
0 \leq \theta \leq \pi / 2 ;
$$

further, $\theta=\pi / 2$ if and only if the subspace $A$ is orthogonal to $B$.
Remark 2. When $p=q$, formula (4) can be written as

$$
\theta=\arccos \frac{|\langle\alpha, \beta\rangle|}{|\alpha| \cdot|\beta|} .
$$

In this case, the $p$-dimensional angle $\theta$ between two decomposable $p$-vectors $\alpha$ and $\beta$ over $E^{n}$ is equal to the usual Euclidean angle between $\alpha$ and $\beta$ as two vectors in the induced Euclidean space $\wedge^{p} E^{n}$.

## 3. First Properties

Using the projection $\alpha_{H}$, we can easily generalize some well-known properties of usual angles to the higher dimensional case as follows.

THEOREM 1 (Reducibility). Let $A$ and $B$ be subspaces of $E^{n}$ with dimensions $p$ and $q$, respectively, where $1<p \leq q<n$. Suppose that $A \cap B \neq\{0\}$, and that the orthogonal complements of $A \cap B$ in $A$ and in $B$ are $A^{\prime}$ and $B^{\prime}$, respectively. Then the angle between $A$ and $B$ is equal to the angle between $A^{\prime}$ and $B^{\prime}$.
THEOREM 2 (Three cosines). Suppose that $1 \leq p<q<n, A^{p}$ and $B^{q}$ are subspaces of $E^{n}$ with dimensions $p$ and $q$, respectively, and $A^{p}$ is not orthogonal to $B^{q}$. Suppose $C^{p}$ is the projection of $A^{p}$ in $B^{q}$, and $D^{p}$ is an arbitrary $p$-dimensional subspace of $B^{q}$. Denote by $\theta^{\prime}, \theta$ and $\phi$ the angles between $A^{p}$ and $D^{p}, A^{p}$ and $B^{q}$, and $C^{p}$ and $D^{p}$, respectively. Then

$$
\cos \theta^{\prime}=\cos \theta \cos \phi
$$

Proof. Let $\alpha$ and $\delta$ be the $p$-vectors corresponding to $A^{p}$ and $D^{p}$, respectively. Denote by $\alpha_{H}, \alpha_{V}$ and $\alpha_{M}$ the horizontal, vertical and mixed parts, respectively, of $\alpha$ with respect to $B^{q}$. Then $\alpha_{H}$ corresponds to $C^{p}$, and we have

$$
\left\langle\alpha_{V}, \delta\right\rangle=\left\langle\alpha_{M}, \delta\right\rangle=0 .
$$

Hence

$$
\begin{aligned}
\cos \theta^{\prime} & =\frac{|\langle\alpha, \delta\rangle|}{|\alpha| \cdot|\delta|}=\frac{\left|\left\langle\alpha_{H}, \delta\right\rangle\right|}{|\alpha| \cdot|\delta|} \\
& =\frac{\left|\alpha_{H}\right|}{|\alpha|} \cdot \frac{\left|\left\langle\alpha_{H}, \delta\right\rangle\right|}{\left|\alpha_{H}\right| \cdot|\delta|} \\
& =\cos \theta \cos \phi .
\end{aligned}
$$

COROLLARY (Minimum). Suppose $A^{p}$ and $B^{q}$ are subspaces of $E^{n}$ with dimensions $p$ and $q$, respectively, $1 \leq p<q<n$. Then the angle $\theta$ between $A^{p}$ and $B^{q}$ equals the minimum of the angle between $A^{p}$ and an arbitrary $p$-dimensional subspace $D^{p}$ of $B^{q}$.

## 4. Further Properties

Now we consider some more interesting properties of higher dimensional angles.
THEOREM 3 (Triangle inequality). Let $A, B$ and $C$ be three different $p$ dimensional subspaces of $E^{n}, 1<p<n$. Denote by $\theta_{A B}, \theta_{A C}$ and $\theta_{B C}$ the angles between $A$ and $B, A$ and $C$, and $B$ and $C$, respectively. Then

$$
\begin{equation*}
\theta_{A B}+\theta_{B C} \geq \theta_{A C} \tag{5}
\end{equation*}
$$

Equality in (5) holds if and only if $\operatorname{dim}(A \cap B \cap C)=p-1$ and the 1 -dimensional orthogonal complements $A^{\prime}, B^{\prime}$ and $C^{\prime}$ of $A \cap B \cap C$ in $A, B$ and $C$, respectively, lie in one and the same plane and $B^{\prime}$ is placed in the smaller pair of vertical angles formed by $A^{\prime}$ and $C^{\prime}$.

Proof. Denote $N=\operatorname{dim} \wedge^{p} E^{n}$. Let $S^{N-1}$ be the unit hypersphere in $\wedge^{p} E^{n}$. Identifying opposite points of $S^{N-1}$, we obtain an elliptic space $\Sigma^{N-1}$. Three different $p$-dimensional subspaces $A, B$ and $C$ of $E^{n}$ correspond to three different points $A^{*}, B^{*}$ and $C^{*}$ in $\Sigma^{N-1}$. Then $\theta_{A B}, \theta_{B C}$ and $\theta_{A C}$ equal the distances between the points $A^{*}$ and $B^{*}, B^{*}$ and $C^{*}$, and $A^{*}$ and $C^{*}$, respectively. Since $\Sigma^{N-1}$ is a metric space (see, for example, Blumenthal [8]), inequality (5) is obtained.

For equality to hold in (5), it is necessary and sufficient that the point $B^{*}$ lies on the metric segment $A^{*} C^{*}$. So there exist nonzero scalars $h$ and $k$ such that

$$
\beta=h \alpha+k \gamma,
$$

where $\alpha, \beta$ and $\gamma$ are the decomposable $p$-vectors corresponding to the subspaces $A, B$ and $C$, respectively. Since $\beta$ is decomposable, we have

$$
\beta \wedge y=0, \quad y \in B,
$$

and hence

$$
\begin{equation*}
h \alpha \wedge y+k \gamma \wedge y=0, \quad y \in B \tag{6}
\end{equation*}
$$

## Denoting

$$
r=\operatorname{dim}(A \cap B \cap C)
$$

from $\beta=h \alpha+k \gamma$ we get

$$
\operatorname{dim}(A \cap C)=r
$$

Let $A^{\prime}, B^{\prime}$ and $C^{\prime}$ be the orthogonal complements of $A \cap B \cap C$ in $A, B$ and $C$, respectively. Then

$$
\begin{aligned}
& \operatorname{dim} A^{\prime}=\operatorname{dim} B^{\prime}=\operatorname{dim} C^{\prime}=p-r, \\
& A^{\prime} \cap C^{\prime}=A^{\prime} \cap B^{\prime}=B^{\prime} \cap C^{\prime}=\{0\} .
\end{aligned}
$$

Denote by $\alpha^{\prime}, \beta^{\prime}$ and $\gamma^{\prime}$ the $(p-r)$-vectors corresponding to $A^{\prime}, B^{\prime}$ and $C^{\prime}$, respectively. From (6) it follows that

$$
h \alpha^{\prime} \wedge y^{\prime}+k \gamma^{\prime} \wedge y^{\prime}=0, \quad y^{\prime} \in B^{\prime}
$$

One can choose a basis in $E^{n}$ (which is not orthogonal in general) such that

$$
\alpha^{\prime}=a e_{1} \wedge \cdots \wedge e_{p-r}, \quad \gamma^{\prime}=c e_{p-r+1} \wedge \cdots \wedge e_{2 p-2 r}
$$

where $a$ and $c$ are nonzero scalars. The vector $y^{\prime}$ can be decomposed as follows:

$$
y^{\prime}=\sum_{i=1}^{p-r} u_{i} e_{i}+\sum_{j=1}^{p-r} v_{j} e_{p-r+j}+\sum_{t=1}^{n-2 p+2 r} w_{t} e_{2 p-2 r+t} .
$$

So we obtain

$$
\begin{aligned}
& h a \sum_{j=1}^{p-r} v_{j} e_{1} \wedge \cdots \wedge e_{p-r} \wedge e_{p-r+j}+k c \sum_{i=1}^{p-r} u_{i} e_{p-r+1} \wedge \cdots \wedge e_{2 p-2 r} \wedge e_{i}+ \\
& \quad+h a \sum_{t=1}^{n-2 p+2 r} w_{t} e_{1} \wedge \cdots \wedge e_{p-r} \wedge e_{2 p-2 r+t}+ \\
& \quad+k c \sum_{t=1}^{n-2 p+2 r} w_{t} e_{p-r+1} \wedge \cdots \wedge e_{2 p-2 r} \wedge e_{2 p-2 r+t} \\
& =0 .
\end{aligned}
$$

If $r<p-1$, then $p-r \geq 2$, we will get

$$
h v_{j}=k u_{i}=h w_{t}=k w_{t}=0
$$

for all $i, j$ and $t$. But $y^{\prime} \neq 0$ and $A^{\prime} \cap B^{\prime}=B^{\prime} \cap C^{\prime}=\{0\}$, so we must have $h=k=0$, which is impossible by assumption. Therefore we get

$$
\operatorname{dim}(A \cap B \cap C)=p-1
$$

Consequently, by Theorem $1, \theta_{A B}, \theta_{A C}$ and $\theta_{B C}$ are equal to the angles between $A^{\prime}$ and $B^{\prime}, A^{\prime}$ and $C^{\prime}$, and $B^{\prime}$ and $C^{\prime}$, where $A^{\prime}, B^{\prime}$ and $C^{\prime}$ are the 1-dimensional orthogonal complements of $A \cap B \cap C$ in $A, B$ and $C$, respectively. The rest of the proof is trivial.

THEOREM 4 (Complement). Suppose $A^{p}$ and $B^{q}$ are subspaces of $E^{n}$ with dimensions $p$ and $q$, respectively, $1 \leq p<q<n, p \leq n-q, B^{\perp}$ the orthogonal complement of $B$ in $E^{n}$. Denote by $\theta$ and $\theta^{\perp}$ the angles between $A$ and $B$ and between $A$ and $B^{\perp}$, respectively. Then

$$
\begin{equation*}
\cos ^{2} \theta+\cos ^{2} \theta^{\perp} \leq 1, \tag{7}
\end{equation*}
$$

where equality holds if and only if either $p=1$ or $\theta \theta^{\perp}=0(p>1)$.
Proof. Inequality (7) follows from decomposition (3) and Lemma 4. Equality in (7) holds if and only if

$$
\alpha_{M}=0 .
$$

This occurs if and only if either $p=1$, or $p>1$ and $\alpha=\alpha_{H}$ or $\alpha=\alpha_{V}$.
Theorems 3 and 4 show some of the differences between the cases of higher and lower dimensions.

## 5. Principal Angles

Let $A^{p}$ and $B^{q}$ be subspaces of $E^{n}$ with dimensions $p$ and $q$, respectively, $1 \leq p \leq$ $q<n$. The principal angles between $A^{p}$ and $B^{q}, 0 \leq \theta_{1} \leq \theta_{2} \leq \cdots \leq \theta_{p} \leq \pi / 2$, are given by

$$
\begin{aligned}
\cos \theta_{i} & =\frac{a_{i} \cdot b_{i}}{\left|a_{i}\right|\left|b_{i}\right|} \\
& =\max \left\{\frac{a \cdot b}{|a||b|}: a \perp a_{m}, b \perp b_{m}, m=1,2, \ldots, i-1\right\},
\end{aligned}
$$

where $a \in A^{p}, b \in B^{q}$ (see Miao and Ben-Israel [4, p. 81]).
The following theorem gives a simple relation between the higher dimensional angle $\theta$ and the principal angles $\theta_{1}, \theta_{2}, \ldots, \theta_{p}$.

THEOREM 5. Suppose the angle between $A^{p}$ and $B^{q}$ is $\theta$, and the principal angles between them are $\theta_{1}, \theta_{2}, \ldots, \theta_{p}$. Then

$$
\cos \theta=\cos \theta_{1} \cos \theta_{2} \cdots \cos \theta_{p}
$$

Proof. By normalization, all these $a_{i}$ 's and $b_{i}$ 's can be assumed to be unit vectors. Put $\alpha=a_{1} \wedge a_{2} \wedge \cdots \wedge a_{p}$, then $\alpha$ is the $p$-vector corresponding to subspace $A^{p}$, and $\langle\alpha, \alpha\rangle=1$. Noting that

$$
a_{i}^{H}=b_{i} \cos \theta_{i}, \quad i=1,2, \ldots, p,
$$

we get

$$
\alpha_{H}=\cos \theta_{1} \cos \theta_{2} \cdots \cos \theta_{p} b_{1} \wedge b_{2} \wedge \cdots \wedge b_{p}
$$

Therefore

$$
\begin{aligned}
\cos \theta & =\left|\alpha_{H}\right| \\
& =\cos \theta_{1} \cos \theta_{2} \cdots \cos \theta_{p} .
\end{aligned}
$$

Remark. The product of cosines of principal angles between subspaces $L$ and $M$ was denoted by $\cos \{L, M\}$ only as a symbol in [4]. Now, Theorem 5 shows that this symbol $\cos \{L, M\}$ is really the cosine of an angle.

## 6. Grassmann Manifolds

The set of all $p$-dimensional subspaces of $E^{n}$ with suitable topology forms a Grassmann manifold $G(p, n-p)$. The theory of angles between subspaces of $E^{n}$ is closely connected with the geometry of Grassmann manifolds. In this way, several theorems of distance geometry can be used to obtain the corresponding results of differential geometry.

For example, by normalization, we can restrict $p$-vectors to have unit lengths. All these unit $p$-vectors form a hypersphere $S^{N-1}$ of $\wedge^{p} E^{n}$, where $N=\operatorname{dim} \wedge^{p} E^{n}=$ $\binom{n}{p}$. Denote by $G$ the submanifold of $S^{N-1}$ consisting of points corresponding to decomposable unit $p$-vectors. Then $G$ is the isometrically immersed image of the Grassmann manifold $G(p, n-p)$ into $S^{N-1}$. Research on geometric properties of $G$ is an interesting topic in differential geometry (see, for example, W. H. Chen [9], who pointed out that $G$ is an algebraic submanifold). In order to obtain the immersed equations for $G$ into $S^{N-1}$, we choose an orthonormal basis $\left\{e_{j}\right\}$ in $E^{n}$, and then get an induced orthonormal basis $\left\{E_{K}\right\}$ in $\wedge^{p} E^{n}$, where

$$
E_{K}=e_{i_{1}} \wedge e_{i_{2}} \wedge \cdots \wedge e_{i_{p}}, \quad 1 \leq i_{1}<i_{2}<\cdots<i_{p} \leq n .
$$

Therefore a unit $p$-vector $\alpha$ can be represented as

$$
\alpha=\sum_{K} \lambda_{K} E_{K}, \quad \sum_{K}\left(\lambda_{K}\right)^{2}=1,
$$

where

$$
\lambda_{K}=u_{i_{1} i_{2} \cdots i_{p}}, \quad 1 \leq i_{1}<i_{2}<\cdots<i_{p} \leq n .
$$

The quantities $\lambda_{K}$ are the usual Cartesian coordinates in the induced Euclidean space $E^{N}$ or $\Lambda^{p} E^{n}$, and the $u_{i_{1} i_{2} \cdots i_{p}}$ 's are called Grassmann coordinates of $\alpha$; they will change sign if any two subscripts are interchanged. Our immersed equations are just the conditions for a $p$-vector to be simple, which are known as Plücker equations and can be written out explicitly as follows:

$$
\sum_{j=1}^{p}(-1)^{j+1} u_{a_{j} b_{2} \cdots b_{p}} u_{b_{1} a_{1} \cdots \hat{a}_{j} \cdots a_{p}}=u_{a_{1} a_{2} \cdots a_{p}} u_{b_{1} b_{2} \cdots b_{p}}
$$

where subscripts $\left\{a_{1}, a_{2}, \ldots, a_{p}\right\}$ and $\left\{b_{1}, b_{2}, \ldots, b_{p}\right\}$ are two arbitrary arrangements of $\{1,2, \ldots, p\}$, and $\hat{a}_{j}$ means that $a_{j}$ is omitted. (See Jiang [10, p. 84]; for some particular cases also see Cartan [11, pp. 18-20]).

On the other hand, according to Menger, a subset of a metric space is called (metrically) convex provided it contains for each two of its points at least one between-point (see Blumenthal [8, p. 41]). Now from Theorem 3 and its proof we infer the following result.
THEOREM 6. The Grassmann manifold $G(p, n-p)$ as a submanifold of a sphere is a metric space. When $n>3$ and $p>1$, it is not metrically convex.

Theorem 6 shows another difference between higher and lower dimensions.

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