

- - - Tuned torque constraint
 Tuned torque rate constraint
 — Tuned dynamic constraint
 $=\min(\text{torque}, \text{torque rate})$

- - - Torque constraint from actuators
 Torque rate constraint from actuators
 — Dynamic constraint from actuators' capabilities
 $=\min(\text{torque}, \text{torque rate})$

