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# ON THE HOMOGENIZATION OF THE STOKES PROBLEM IN A PERFORATED DOMAIN 

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#### Abstract

In this paper we consider the Stokes equations on a bounded perforated domain completed with non-zero constant boundary conditions on the holes. We investigate configurations for which the holes are identical spheres and their number $N$ goes to infinity while their radius $1 / N$ tends to zero. We prove that, under the assumption that the holes do not concentrate in any box of size $1 / N^{1 / 3}$, the solution is well approximated asymptotically by solving a Stokes-Brinkman problem.


## 1. Introduction

In this paper we focus on the homogenization of the Stokes equations in a perforated domain with non-zero constant boundary conditions on the holes. Precisely, we assume that $\Omega$ is a smooth bounded domain in $\mathbb{R}^{3}$. Given $N \in \mathbb{N}$, we introduce $N$ centers $h_{1}^{N}, \ldots, h_{N}^{N}$ in $\Omega$ such that the $B_{i}^{N}=B\left(h_{i}^{N}, 1 / N\right)$ satisfy

$$
\begin{equation*}
B_{i}^{N} \Subset \Omega, \quad \overline{B_{i}^{N}} \cap \overline{B_{j}^{N}}=\emptyset, \quad \text { for } i \neq j \text { in }\{1, \ldots, N\} . \tag{A0}
\end{equation*}
$$

Given a $N$-uplet $\left(v_{i}^{N}\right)_{i=1, \ldots, N} \in\left(\mathbb{R}^{3}\right)^{N}$, it is classical that there exists a unique solution to

$$
\left\{\begin{align*}
-\Delta u+\nabla p & =0,  \tag{1}\\
\operatorname{div} u & =0,
\end{align*} \quad \text { on } \mathcal{F}^{N}:=\Omega \backslash \bigcup_{i=1}^{N} B_{i}^{N}\right.
$$

completed with boundary conditions

$$
\begin{cases}u=v_{i}^{N}, & \text { on } \partial B_{i}^{N},  \tag{2}\\ u=0, & \text { on } \partial \Omega .\end{cases}
$$

We are interested here in the behavior of this solution when $N$ goes to infinity and the asymptotics of the data $\left(h_{i}^{N}, v_{i}^{N}\right)_{i=1, \ldots, N}$ are given.

When the holes are distributed periodically, a major contribution in the analysis of this problem is due to G. Allaire [1]. In this reference, the author proves that there exists a critical value of the ratio between the size of the holes and their mutual distance for which there is a transition from the Stokes equations towards the Stokes-Brinkman equations. If the holes are "denser" the transition holds with a Darcy law while if the holes are "more dilute" we obtain again a Stokes problem asymptotically. This former result is an adaptation to the Stokes equations of a previous analysis on the Laplace equation in [3]. We refer the reader to [2, 5] for a review of equivalent results for other fluid models.

[^0]In [1], the Stokes equations are completed with vanishing boundary conditions while a volumic source term is added in the bulk. The problem with non-zero constant boundary conditions is introduced in [4] for the modeling of a thin spray in a highly viscous fluid. In this case, the holes represent droplets of another phase called "dispersed phase". This phase can be made of another fluid or small rigid spheres. The Stokes equations should then be completed with evolution equations for this dispersed phase yielding a time-evolution problem with moving holes. Computing the asymptotics of the stationary Stokes problem is then a tool for understanding the instantaneous response of the dispersed phase to the drag forces exerted by the flow on the droplets/spheres. We refer the reader to [4, 11] for more details on the modeling. In [4, the authors adapt the result of [1] on the derivation of the Stokes-Brinkman system. A comparable analysis with another purpose is provided in [10] when the dispersed phase is sufficiently dilute so that one recovers asymptotically the Stokes system. We emphasize that there is a significative new difficulty in introducing non-vanishing boundary conditions. Indeed, the boundary conditions on the holes may be highly oscillating (when jumping from one hole to another). Hence, if one were trying to solve this new system by lifting the boundary conditions, he would introduce a highly oscillating source term in the Stokes equations that is out of the scope of the analysis in [1].

The result in [4] is obtained under the assumption that the distance between two centers $h_{i}^{N}$ and $h_{j}^{N}$ is larger than $2 / N^{1 / 3}$. This assumption is quite restrictive and prevents from extension to a time-dependant problem or a random model (in the spirit of [12]). Furthermore, the proof in [4] relies heavily on explicit formulas for solutions to the Stokes equations in annuli and exterior domains. Considering holes with non-spherical shapes thus requires new tools. Our main motivation in this paper is to provide another approach that may help to overcome these two difficulties.

In order to consider the limit $N \rightarrow \infty$, we make now precise the different assumptions on the data of our Stokes problem (11)-(2). This includes:

- the positions of the centers $\left(h_{i}^{N}\right)_{i=1, \ldots, N}$,
- the velocities prescribed on the holes $\left(v_{i}^{N}\right)_{i=1, \ldots, N}$.

First, similarly to [4], we assume that:

$$
\begin{equation*}
\frac{1}{N} \sum_{i=1}^{N}\left|v_{i}^{N}\right|^{2} \text { is uniformly bounded. } \tag{A1}
\end{equation*}
$$

Second, we make precise the assumptions on the separation between the holes. This is the main point where our assumptions differ from [4]. It is nowadays classical that the properties of Stokes flows in domains with obstacles change drastically when the distance between obstacles decreases becoming comparable to their diameters (see [8]). We want to avoid this phenomenon in the pairwise as in the global interactions between holes through
the flow. We quantify this by introducing:

$$
\begin{aligned}
d_{\min }^{N} & =\min _{i=1, \ldots, N}\left\{\operatorname{dist}\left(h_{i}^{N}, \partial \Omega\right), \min _{j \neq i}\left|h_{i}^{N}-h_{j}^{N}\right|\right\} \\
M^{N} & =\sup _{x \in \Omega}\left\{\#\left\{i \in\{1, \ldots, N\} \text { s.t. } h_{i}^{N} \in \overline{B\left(x, 1 / N^{1 / 3}\right)}\right\}\right\} .
\end{aligned}
$$

We assume below that

$$
\begin{align*}
& \lim _{N \rightarrow \infty} N d_{\min }^{N}=+\infty  \tag{A2}\\
& \left(M^{N}\right)_{N \in \mathbb{N}} \text { is bounded. } \tag{A3}
\end{align*}
$$

We note that under these assumptions, we have that for $N$ sufficiently large the $\left(B_{i}^{N}\right)_{i=1, \ldots, N}$ are disjoint and do not intersect $\partial \Omega$. For $N$ large enough, assumption (A0) only fixes that the holes are inside $\Omega$. There exists then a unique pair $\left(u^{N}, p^{N}\right) \in H^{1}\left(\mathcal{F}^{N}\right) \times L^{2}\left(\mathcal{F}^{N}\right)$ solution to (11)-(2)) (see next section for more details). The pressure is unique up to an additive constant that we may fix by requiring that $p^{N}$ has mean 0 . It can be seen as the Lagrange multiplier of the divergence-free condition in (11). Hence, we focus on the convergence of the sequence $\left(u^{N}\right)_{N \in \mathbb{N}}$ and will not go into details on what happens to the pressure (in contrast with [1]). The $u^{N}$ are defined on different domains. In order to compute a limit for this sequence of vector-fields, we unify their domain of definition by extending $u^{N}$ with the values $v_{i}^{N}$ on $B_{i}^{N}$ for any $i=1, \ldots, N$. We still denote $u^{N}$ the extension for simplicity. This is now a sequence in $H_{0}^{1}(\Omega)$.

The final assumptions prescribe the asymptotics of the distribution $\left(h_{i}^{N}, v_{i}^{N}\right)_{i=1, \ldots, N}$. We introduce the empiric measure

$$
S_{N}=\frac{1}{N} \sum_{i=1}^{N} \delta_{h_{i}^{N}, v_{i}^{N}} \in \mathbb{P}\left(\mathbb{R}^{3} \times \mathbb{R}^{3}\right)
$$

and we assume:

$$
\begin{align*}
\int_{\mathbb{R}^{3}} S_{N}(\mathrm{~d} v) & \rightharpoonup \rho(x) \mathrm{d} x \text { weakly in the sense of measures on } \mathbb{R}^{3}  \tag{A4}\\
\int_{\mathbb{R}^{3}} v S_{N}(\mathrm{~d} v) & \rightharpoonup j(x) \mathrm{d} x \text { weakly in the sense of (vectorial-) measures on } \mathbb{R}^{3} . \tag{A5}
\end{align*}
$$

We recall that, by assumption (A0), the measure $S_{N}$ is supported in $\Omega \times \mathbb{R}^{3}$ so that, in the weak limit, $\rho \geqslant 0$ and $\rho$ and $j$ have support included in $\Omega$.

Our main result reads:
Theorem 1. Let $\left(v_{i}^{N}, h_{i}^{N}\right)_{i=1, \ldots, N}$ be a sequence of data satisfying (A0) for arbitrary $N \in \mathbb{N}$. Assume furthermore that (A1) -(A5) hold true with

$$
j \in L^{2}(\Omega), \quad \rho \in L^{\infty}(\Omega) .
$$

Then, the associated sequence of extended velocity-fields $\left(u^{N}\right)_{N \in \mathbb{N}}$ converges in $H_{0}^{1}(\Omega)-w$ to the unique velocity-field $\bar{u} \in H^{1}(\Omega)$ such that there exists a pressure $\bar{p} \in L^{2}(\Omega)$ for which $(\bar{u}, \bar{p})$ solves:

$$
\left\{\begin{align*}
-\Delta \bar{u}+\nabla \bar{p} & =6 \pi(j-\rho \bar{u}), \quad \text { on } \Omega,  \tag{3}\\
\operatorname{div} \bar{u} & =0,
\end{align*}\right.
$$

completed with boundary conditions

$$
\begin{equation*}
\bar{u}=0, \quad \text { on } \partial \Omega . \tag{4}
\end{equation*}
$$

We remark that, with the assumptions (A1) and (A3), we may extract a subsequence such that the first momentums of $S_{N}$ in $v$ converge to some $(\rho, j) \in L^{\infty}(\Omega) \times L^{2}(\Omega)$. Hence, assumptions (A4) and (A5) only fix that the whole sequence converges to the same density $\rho$ and momentum distribution $j$. For simplicity, we do not include a source term in (1) even if our result extends in a straightfoward way to this case (due to the linearity of the Stokes equations).

We emphasize that our result is not in contradiction with [1]. Indeed, in the periodic case, if the distance between holes is smaller than $1 / N^{1 / 3}$ we are in a case where [1] shows that the asymptotic problem is a Darcy law. But, in our case, if the holes were arranging periodically with distance constantly less than $1 / N^{1 / 3}$ in some part of the domain, there would exist one cube of size $1 / N^{1 / 3}$ in which the number of holes goes to infinity. This possibility is ruled out by assumption (A3). On the opposite, if the distance between holes is too often much larger than $1 / N^{1 / 3}$ in our framework, the asymptotic $\rho$ and $j$ vanish and we obtain again the Stokes equations in the limit as in [1]. We also remark that the results herein extend the previous results in [1] and [4]. Indeed, on the one hand, the assumptions in [4] are clearly more restrictive than (A2)-(A3). On the other hand, our assumptions allow the holes to be distributed periodically. In this case, we would have, with the terminology of [1], that " $a_{\varepsilon} "=1 / N$ and " $\varepsilon "=\left(\sigma_{\varepsilon}^{2} / N\right)^{1 / 3}$ and $" M_{0} "=6 \pi \mathbb{I}_{3}$. The case in which [1] derives the Stokes-Brinkman problem corresponds then to $j=0$ and $\sigma_{\varepsilon} \rightarrow \bar{\sigma} \in(0, \infty)$ when $N \rightarrow \infty$ (or equivalently $\varepsilon \rightarrow 0$ ). In that case, straightforward computations show that $\rho=\bar{\sigma}^{-2}$ and system (3)-(4) corresponds to the one derived in [1].

To conclude, one novelty of this paper is that we expect the two assumptions (A2)- (A3) are sufficiently general to tackle the time-evolution problem. Another novelty of the paper stems from the method of proof. We shall apply arguments that are not highly sensitive to the explicit value of solutions to the Stokes problem. The two main ingredients of the proof are the decrease of stokeslets (see (14)) and conservation arguments (see next subsection). In particular, we plan to consider more general shapes of holes and boundary conditions on holes in future works.
1.1. Outline of the proof. Our proof is based on a classical compactness argument: we first obtain uniform bounds on the sequence $u^{N}$ and then extract a subsequence such that, passing to the weak limit in the weak formulation for the $N$-problem, we obtain the weak formulation of the limit problem.

We first prove that the sequence $\left(u^{N}\right)_{N \in \mathbb{N}}$ is bounded in $H_{0}^{1}(\Omega)$. This part is obtained by applying a variational characterization of solutions to Stokes problems and relies upon assumptions (A1) and (A2) only. We may then extract a subsequence (that we do not relabel) converging to some $\bar{u}$ in $H_{0}^{1}(\Omega)$ (and strongly in any $L^{q}(\Omega)$ for $q \in[1,6[)$. In order to identify a system satisfied by $\bar{u}$ all that remains is devoted to the proof that:

$$
I_{w}:=\int_{\Omega} \nabla \bar{u}: \nabla w
$$

satisfies:

$$
I_{w}=6 \pi \int_{\Omega}(j(x)-\rho(x) \bar{u}(x)) \cdot w(x) \mathrm{d} x
$$

for arbitrary divergence-free $w \in C_{c}^{\infty}(\Omega)$. So, we fix a divergence-free $w \in C_{c}^{\infty}(\Omega)$ and we note that by construction, we have

$$
I_{w}=\lim _{N \rightarrow \infty} I_{w}^{N} \quad \text { with } \quad I_{w}^{N}=\int_{\Omega} \nabla u^{N}: \nabla w, \quad \forall N \in \mathbb{N} \text {. }
$$

We compute then $I_{w}^{N}$ by applying that $u^{N}$ is a solution to the Stokes problem (1)-(21). As the support of all the integrals $I_{w}^{N}$ is $\Omega$ and the support of $w$ is not adapted to the Stokes problem (11)-(2), this requires a special care. So, we introduce a covering $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ of $\operatorname{Supp}(w)$ with cubes of width $1 / N^{1 / 3}$ and we split

$$
I_{w}^{N}=\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w .
$$

Given $N$ and $\kappa$, we apply that there are not too many particles in $T_{\kappa}^{N}$ because of assumption (A5). This enables to localize the method of reflections [9, 10] and replace $w$ with

$$
\sum_{i \in \mathcal{I}_{\kappa}^{N}} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right),
$$

in the integral on $T_{\kappa}^{N}$. We denote here

- $\mathcal{I}_{\kappa}^{N}$ the subset of indices $i \in\{1, \ldots, N\}$ for which $h_{i}^{N} \in T_{\kappa}^{N}$,
- $\left(U^{N}[v](y), P^{N}[v](y)\right)$ the solution to the Stokes problem outside $B(0,1 / N)$ with boundary condition $U[v](y)=v$ on $\partial B(0,1 / N)$ and vanishing condition at infinity.
We obtain that

$$
\int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w \sim \sum_{i \in \mathcal{I}_{\kappa}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla\left[U^{N}\left[w\left(h_{i}^{N}\right)\right]\right]\left(x-h_{i}^{N}\right) .
$$

Then, we observe that the pair

$$
\left(U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right), P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)\right)
$$

is a solution to the Stokes problem outside $B_{i}^{N}$. Hence, we apply that $u^{N}$ is divergence-free, introduce the pressure and integrate by parts to obtain that:

$$
\begin{aligned}
\int_{T_{\hbar}^{N}} \nabla u^{N}: \nabla w \sim \sum_{i \in \mathcal{I}_{k}^{N}} \int_{\partial B_{i}^{N}}\left(\partial_{n} U^{N}[ \right. & \left.\left.w\left(h_{i}^{N}\right)\right]-P^{N}\left[w\left(h_{i}^{N}\right)\right] n\right) \cdot v_{i}^{N} \mathrm{~d} \sigma \\
& +\int_{\partial T_{\kappa}^{N}} \sum_{i \in \mathcal{I}_{k}^{N}}\left(\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]-P^{N}\left[w\left(h_{i}^{N}\right)\right] n\right) \cdot u^{N} \mathrm{~d} \sigma
\end{aligned}
$$

We skip for conciseness that $\left(U^{N}, P^{N}\right)$ depend on $\left(x-h_{i}^{N}\right)$ in these last identities. It is classical by the Stokes law that:

$$
\int_{\partial B_{i}^{N}}\left(\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]-P^{N}\left[w\left(h_{i}^{N}\right)\right] n\right) \mathrm{d} \sigma=\frac{6 \pi}{N} w\left(h_{i}^{N}\right),
$$

and, by interpreting the Stokes system as the conservation of normal stress, that:

$$
\int_{\partial T_{\kappa}^{N}}\left(\partial_{n} U\left[w\left(h_{i}^{N}\right)\right]-P^{N}\left[w\left(h_{i}^{N}\right)\right] n\right) \mathrm{d} \sigma=-\frac{6 \pi}{N} w\left(h_{i}^{N}\right) .
$$

To take advantage of this last identity, we use that $T_{\kappa}^{N}$ has small width to replace $u^{N}$ by some mean value $\bar{u}_{\kappa}^{N}$ on $\partial T_{\kappa}^{N}$. Say for simplicity that:

$$
\begin{equation*}
\bar{u}_{\kappa}^{N}=\frac{1}{\left|T_{\kappa}^{N}\right|} \int_{T_{\kappa}^{N}} u^{N}(x) \mathrm{d} x \tag{5}
\end{equation*}
$$

and assume that replacing $u^{N}$ by $\bar{u}_{\kappa}^{N}$ induces a small error in the boundary integral. We obtain then that:

$$
\int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w \sim \sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-\sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N} .
$$

Summing over $\kappa$ yields:

$$
I_{w}^{N} \sim \sum_{i=1}^{N} \frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-\sum_{\kappa \in \mathcal{K}^{N}}\left[\sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right)\right] \cdot \bar{u}_{\kappa}^{N}
$$

The first term on the right-hand side converges by assumption (A3) to :

$$
6 \pi \int_{\Omega} j(x) \cdot w(x) \mathrm{d} x
$$

To compute the limit of the second term, we introduce:

$$
\sigma^{N}=6 \pi \sum_{\kappa \in \mathcal{K}^{N}}\left[\sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right)\right] \mathbf{1}_{T_{\kappa}^{N}}
$$

so that:

$$
\sum_{\kappa \in \mathcal{K}^{N}}\left[\sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right)\right] \cdot \bar{u}_{\kappa}^{N}=\int_{\Omega} \sigma^{N} \cdot u^{N}(x) \mathrm{d} x .
$$

For $w \in C_{c}^{\infty}(\Omega)$, we have that $\sigma^{N}$ is bounded in $L^{1}(\Omega)$ and, under assumption (A4), it converges to $\sigma(x)=\rho(x) w(x)$ in $\mathcal{D}^{\prime}(\Omega)$. However, this is not sufficient to compute the limit of this last term. Indeed we have strong convergence of the sequence $u^{N}$ in $L^{q}(\Omega)$ for $q<6$ only. Consequently, we need the supplementary assumption (A5) which entails that $\sigma^{N}$ is bounded in $L^{\infty}(\Omega)$. Now, $\sigma^{N}$ converges in $L^{q}(\Omega)-w$ for arbitrary $q \in(1, \infty)$ (up to the extraction of a subsequence) and combining this fact with the strong convergence of $u^{N}$ we obtain that:

$$
\lim _{N \rightarrow \infty} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}=\int_{\Omega} \rho(x) w(x) \cdot \bar{u}(x) \mathrm{d} x
$$

This would end the proof if we could actually define $\bar{u}_{\kappa}^{N}$ as in (5) and prove that it induces a small error by replacing $u^{N}$ with the mean $\bar{u}_{\kappa}^{N}$ on $\partial T_{\kappa}^{N}$. Unfortunately, for this, we need that the combination of stokeslets to which $u^{N}$ is multiplied is a solution to the Stokes equations on the set where the mean is taken (in particular we cannot choose $T_{\kappa}^{N}$ here contrary to what we have written in (5)). We also remark that, in order that the sum:

$$
\sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} \frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}
$$

corresponds to the multiplication with an $L^{1}$-bounded sequence $\left(\sigma^{N}\right)_{N \in \mathbb{N}}$, we not only need (A5) but also that the mean $\bar{u}_{\kappa}^{N}$ is taken on a set whose volume is of magnitude $1 / N$. To handle both technical difficulties simultaneously, we introduce a parameter $\delta$ (which will be large), we "delete" the particles in a $1 /\left(\delta N^{1 / 3}\right)$-neighborhood of $\partial T_{\kappa}^{N}$ and we construct $\bar{u}_{\kappa}^{N}$ as the mean of $u^{N}$ on the $1 /\left(2 \delta N^{1 / 3}\right)$-neighborhood of $\partial T_{\kappa}^{N}$ (inside $T_{\kappa}^{N}$ ). By a suitable choice of the covering $T_{\kappa}^{N}$ we prove that the cost of this deletion process is $O(1 / \sqrt{\delta})$. Hence, we obtain that:

$$
\left|I_{w}-6 \pi \int_{\Omega}(j(x)-\rho(x) \bar{u}(x)) \cdot w(x) \mathrm{d} x\right| \lesssim \frac{1}{\sqrt{\delta}}
$$

for arbitrary large $\delta$.
1.2. Notations. In the whole paper, for arbitrary $x \in \mathbb{R}^{3}$ and $r>0$, we denote $B_{\infty}(x, r)$ the open ball with center $x$ and radius $r$ for the $\ell^{\infty}$ norm. The classical euclidean balls are denoted $B(x, r)$. For $x \in \mathbb{R}^{3}$ and $0<\lambda_{1}<\lambda_{2}$ we also denote:

$$
A\left(x, \lambda_{1}, \lambda_{2}\right):=B_{\infty}\left(x, \lambda_{2}\right) \backslash \overline{B_{\infty}\left(x, \lambda_{1}\right)}
$$

The operator distance (between sets) is always computed with the $\ell^{\infty}$ norm. We will constantly use a truncation function associated to the parameter $N$. This truncation function is constructed in a classical way. We introduce $\chi \in C_{c}^{\infty}\left(\mathbb{R}^{3}\right)$ a truncation function such
that $\chi=1$ on $[-1,1]^{3}$ and $\chi=0$ outside $[-2,2]^{3}$. We denote $\chi^{N}=\chi(N \cdot)$ its rescaled versions. This truncation function satisfies :

- $\chi^{N}=1$ on $B_{\infty}(0,1 / N)$ and $\chi^{N}=0$ outside $B_{\infty}(0,2 / N)$,
- $\nabla \chi^{N}$ has support in $A(0,1 / N, 2 / N)$ and size $O(N)$.

When we truncate vector-fields with $\chi^{N}$ we shall create a priori non divergence-free vectorfields. To lift the divergence of these vector-fields, we use extensively the Bogovskii operator $\mathfrak{B}_{x, \lambda_{1}, \lambda_{2}}$ on the "cubic" annulus $A\left(x, \lambda_{1}, \lambda_{2}\right.$ ) (again $x \in \mathbb{R}^{3}$ and $0<\lambda_{1}<\lambda_{2}$ ). We recall that $w=\mathfrak{B}_{x, \lambda_{1}, \lambda_{2}}[f]$ is defined for arbitrary $f \in L^{2}\left(A\left(x, \lambda_{1}, \lambda_{2}\right)\right)$, whose mean vanishes, and yields an $H_{0}^{1}\left(A\left(x, \lambda_{1}, \lambda_{2}\right)\right)$ vector-field such that $\operatorname{div} w=f$. As the returned vector-field vanishes on $\partial A\left(x, \lambda_{1}, \lambda_{2}\right)$ we extend it tacitly by 0 to obtain an $H^{1}\left(\mathbb{R}^{3}\right)$ function.

For legibility we also make precise a few conventions. We have the following generic notations:

- $u$ is a velocity-field solution to a Stokes problem, with associated pressure $p$,
- $w$ is a test-function,
- $I$ is an integral while $\mathcal{I}$ is a set of indices,
- $T$ is a cube, depending on the width we shall use different exponants,
- $n$ denotes the outward normal to the open set under consideration.

We shall also use extensively the symbol $\lesssim$ to denote that we have an inequality with a non-significant constant. We mean that we denote $a \lesssim b$ when there exists a constant $C$, which is not relevant to our problem, such that $a \leqslant C b$. In most cases "not relevant" will mean that it does not depend on the parameters $N$ and/or $\delta$. If a more precise statement of this "non-relevance" is required we shall make it precise.

## 2. Analysis of the Stokes problem

In this section, we recall how is solved the Stokes problem:

$$
\left\{\begin{align*}
-\Delta u+\nabla p & =0,  \tag{6}\\
\operatorname{div} u & =0,
\end{align*} \quad \text { on } \mathcal{F},\right.
$$

completed with boundary conditions

$$
\begin{equation*}
u(x)=u_{*}, \quad \text { on } \partial \mathcal{F} \tag{7}
\end{equation*}
$$

for a lipschitz domain $\mathcal{F}$ and boundary condition $u_{*} \in H^{\frac{1}{2}}(\partial \mathcal{F})$. We consider the different cases: $\mathcal{F}$ is a bounded set, an exterior domain, or a perforated cube. In the second case, we complement the system with a vanishing condition at infinity.
2.1. Reminders on the Stokes problem in a bounded or an exterior domain. We first assume that $\mathcal{F}$ is a bounded domain with a lipschitz boundary $\partial \mathcal{F}$. In this setting, a standard way to solve the Stokes problem (6)-(77) is to work with a generalized formulation (see [7, Section 4]). For this, we introduce:

$$
D(\mathcal{F}):=\left\{u \in H^{1}(\mathcal{F}) \text { s.t. } \operatorname{div} u=0\right\}, \quad D_{0}(\mathcal{F}):=\left\{u \in H_{0}^{1}(\mathcal{F}) \text { s.t. } \operatorname{div} u=0\right\}
$$

By [7, Theorem III.4.1], we have that $D_{0}(\mathcal{F})$ is the closure for the $H_{0}^{1}(\Omega)$-norm of

$$
\mathcal{D}_{0}(\mathcal{F})=\left\{w \in C_{c}^{\infty}(\mathcal{F}) \text { s.t. } \operatorname{div} w=0\right\}
$$

We have then the following definition
Definition 2. Given $u_{*} \in H^{\frac{1}{2}}(\partial \mathcal{F})$, a vector-field $u \in D(\mathcal{F})$ is called generalized solution to (6) -(7) if

- $u=u_{*}$ on $\partial \mathcal{F}$ in the sense of traces,
- for arbitrary $w \in D_{0}(\mathcal{F})$, there holds:

$$
\begin{equation*}
\int_{\mathcal{F}} \nabla u: \nabla w=0 \tag{8}
\end{equation*}
$$

This generalized formulation is obtained assuming that we have a classical solution, multiplying (6) with arbitrary $w \in \mathcal{D}_{0}(\mathcal{F})$ and performing integration by parts. De Rham theory ensures that conversely, if one constructs a generalized solution then it is possible to find a pressure $p$ such that (6) holds in the sense of distributions. Standard arguments yield:

Theorem 3. Assume that the boundary of the fluid domain $\partial \mathcal{F}$ splits into $(N+1) \in \mathbb{N}$ lipschitz connected components $\Gamma_{0}, \Gamma_{1}, \ldots, \Gamma_{N}$. Given $u_{*} \in H^{\frac{1}{2}}(\partial \mathcal{F})$ satisfying

$$
\begin{equation*}
\int_{\Gamma_{i}} u_{*} \cdot n \mathrm{~d} \sigma=0, \quad \forall i \in\{0, \ldots, N\} \tag{9}
\end{equation*}
$$

then

- there exists a unique generalized solution u to (17)-(18);
- this generalized solution realizes

$$
\begin{equation*}
\inf \left\{\int_{\mathcal{F}}|\nabla u|^{2}, u \in D(\mathcal{F}) \text { s.t. } u_{\partial \mathcal{F}}=u_{*}\right\} . \tag{10}
\end{equation*}
$$

Proof. Existence and uniqueness of the generalized solution is a consequence of [7, Theorem IV.1.1]. A key argument in the proof of this reference is the property of traces that we state in the following lemma:
Lemma 4. For arbitrary $u_{*} \in H^{\frac{1}{2}}(\partial \mathcal{F})$ satisfying (9) there holds:

- there exists $u_{b d y} \in D(\mathcal{F})$ having trace $u_{*}$ on $\partial \mathcal{F}$,
- for arbitrary $u_{b d y} \in D(\mathcal{F})$ having trace $u_{*}$ on $\partial \mathcal{F}$ there holds

$$
\left\{u \in D(\mathcal{F}) \text { s.t. } u_{\left.\right|_{\partial \mathcal{F}}}=u_{*}\right\}=u_{b d y}+D_{0}(\mathcal{F}) .
$$

Then, given $u \in D(\mathcal{F})$ the generalized solution to (17)-(18) and $w \in D_{0}(\mathcal{F})$, the fundamental property (8) of $u$ entails that:

$$
\begin{aligned}
\int_{\mathcal{F}}|\nabla(u+w)|^{2} & =\int_{\mathcal{F}}|\nabla u|^{2}+2 \int_{\mathcal{F}} \nabla u: \nabla w+\int_{\mathcal{F}}|\nabla w|^{2}, \\
& =\int_{\mathcal{F}}|\nabla u|^{2}+\int_{\mathcal{F}}|\nabla w|^{2} .
\end{aligned}
$$

Consequently, the norm on the left-hand side is minimal if and only if $w=0$. Combining this remark with the above lemma yields that the generalized solution to (17)-(18) is the unique minimizer of (10) in $\left\{v \in D(\mathcal{F})\right.$ s.t. $\left.v_{\partial \mathcal{F}}=u_{*}\right\}$.

As mentioned previously, once it is proven that there exists a unique generalized solution $u$ to (6)-(77), it is possible to recover a pressure $p$ so that (6)-(7) holds in the sense of distributions. If the data are smooth (i.e. $\mathcal{F}$ has smooth boundaries and $u_{*}$ is smooth) one proves also that $(u, p) \in C^{\infty}(\overline{\mathcal{F}})$.

We turn to the exterior problem as developed in [7, Section 5]. We assume now that $\mathcal{F}=\mathbb{R}^{3} \backslash \overline{B^{a}}$ where $B^{a}=B(0,1 / a)$ and we consider the Stokes problem (6) with boundary condition

$$
\begin{equation*}
u=u_{*} \text { on } \partial B^{a}, \quad \lim _{|x| \rightarrow \infty} u(x)=0 \tag{11}
\end{equation*}
$$

for some $u_{*} \in H^{\frac{1}{2}}\left(\partial B^{a}\right)$. For the exterior problem, we keep the definition of generalized solution up to change a little the function spaces. We denote in this case:

- $\mathcal{D}(\mathcal{F})=\left\{w_{\left.\right|_{\mathcal{F}}}, w \in C_{c}^{\infty}\left(\mathbb{R}^{3}\right)\right.$ s.t. $\left.\operatorname{div} w=0\right\}$,
- $D(\mathcal{F})$ is the closure of $\mathcal{D}(\mathcal{F})$ for the norm:

$$
\|w\|_{D(\mathcal{F})}=\left(\int_{\mathcal{F}}|\nabla w|^{2}\right)^{\frac{1}{2}}
$$

We keep the definition of $\mathcal{D}_{0}(\mathcal{F})$ as in the bounded-domain case and we construct $D_{0}(\mathcal{F})$ as the closure of $\mathcal{D}_{0}(\mathcal{F})$ with respect to this latter homogeneous $H^{1}$-norm. We note that, in the exterior domain case, we still have that $D(\mathcal{F}) \subset W_{l o c}^{1,2}(\mathcal{F})$ (see [7, Lemma II.6.1]) so that we have a trace operator on $\partial B^{a}$ and an equivalent to Lemma 4 ,

As in the case of bounded domains, the Stokes problem (6)-(11) with boundary conditions $u_{*}$ prescribing no flux through $\partial B^{a}$ has a unique generalized solution (see [7, Theorem V.2.1], actually the no-flux assumption is not necessary for the exterior problem). Thus, this solution satisfies:

- $\nabla u \in L^{2}\left(\mathbb{R}^{3} \backslash \overline{B^{a}}\right)$,
- for any $w \in D_{0}\left(\mathbb{R}^{3} \backslash \overline{B^{a}}\right)$ there holds:

$$
\int_{\mathbb{R}^{3} \backslash \overline{B^{a}}} \nabla u: \nabla w=0 .
$$

Explicit formulas are provided when the boundary condition $u_{*}=v$ with $v \in \mathbb{R}^{3}$ constant (see [4, Section 6.2] for instance):

$$
\begin{align*}
& u(x)=U^{a}[v](x):=\frac{1}{4 a}\left(\frac{3}{|x|}+\frac{1}{a^{2}|x|^{3}}\right) v+\frac{3}{4 a}\left(\frac{1}{|x|}-\frac{1}{a^{2}|x|^{3}}\right) \frac{v \cdot x}{|x|^{2}} x  \tag{12}\\
& p(x)=P^{a}[v](x):=\frac{3}{2 a} \frac{v \cdot x}{|x|^{4}} x \tag{13}
\end{align*}
$$

We call this classical solution stokeslet in what follows. With these explicit formulas, we remark that:

$$
\begin{equation*}
\left|U^{a}[v](x)\right| \lesssim \frac{|v|}{a|x|}, \quad\left|\nabla U^{a}[v](x)\right|+\left|P^{a}[v](x)\right| \lesssim \frac{|v|}{a|x|^{2}}, \quad \forall x \in \mathbb{R}^{3} \backslash \overline{B_{a}}, \tag{14}
\end{equation*}
$$

and we recall that the force exerted by the flow on $\partial B^{a}$ reads:

$$
\begin{equation*}
\int_{\partial B_{a}}\left(\partial_{n} U^{a}[v]-P^{a}[v] n\right) \mathrm{d} \sigma=\frac{6 \pi}{a} v . \tag{15}
\end{equation*}
$$

For convenience, the stokeslet $U^{a}[v]$ is extended by $U^{a}[v]=v$ on $B^{a}$ in what follows.
2.2. Stokes problem in a perforated cube. In this last subsection, we fix $(N, M) \in$ $(\mathbb{N} \backslash\{0\})^{2}$, and a divergence-free $w \in C_{c}^{\infty}\left(\mathbb{R}^{3}\right)$. We denote $T^{N}$ an open cube of width $1 / N^{1 / 3}$ and $B_{i}^{N}=B\left(x_{i}, 1 / N\right) \subset T^{N}$ for $i=1, \ldots, M$. We assume further that there exists $d_{m}$ satisfying

$$
\begin{equation*}
\min _{i=1, \ldots, M}\left\{\operatorname{dist}\left(x_{i}, \partial T^{N}\right), \min _{j \neq i}\left(\left|x_{i}-x_{j}\right|\right)\right\} \geqslant d_{m}>\frac{4}{N} \tag{16}
\end{equation*}
$$

We consider the Stokes problem:

$$
\left\{\begin{align*}
-\Delta u+\nabla p & =0,  \tag{17}\\
\operatorname{div} u & =0,
\end{align*} \quad \text { on } \mathcal{F}=T^{N} \backslash \bigcup_{i=1}^{M} \overline{B_{i}^{N}}\right.
$$

completed with boundary conditions

$$
\left\{\begin{array}{lll}
u(x)=w(x), & & \text { on } B_{i}^{N}, \forall i=1, \ldots, M  \tag{18}\\
u(x)=0, & & \text { on } \partial T^{N}
\end{array}\right.
$$

Assumption (16) entails that the $B_{i}^{N}$ do not intersect and do not meet the boundary $\partial T^{N}$. So, the set $T^{N} \backslash \bigcup_{i=1}^{M} \overline{B_{i}^{N}}$ has a lipschitz boundary satisfying:

$$
\partial\left[T^{N} \backslash \bigcup_{i=1}^{M} \overline{B_{i}^{N}}\right]=\partial T^{N} \cup \bigcup_{i=1}^{M} \partial B_{i}^{N} .
$$

For any $i=1, \ldots, M$, direct computations show that:

$$
\int_{\partial B_{i}^{N}} w \cdot n \mathrm{~d} \sigma=\int_{B_{i}^{N}} \operatorname{div} w=0
$$

Hence, the problem (17)-(18) is solved by applying Theorem 3 and it admits a unique generalized solution $u \in H^{1}(\mathcal{F})$. We want to compare this solution with:

$$
u_{s}(x)=\sum_{i=1}^{M} U^{N}\left[w\left(x_{i}\right)\right]\left(x-x_{i}\right)
$$

where $U^{N}$ is the stokeslet as defined in (12). The main result of this subsection is:

Proposition 5. There exists a constant $K$ independent of $\left(N, M, d_{m}, w\right)$ for which:

$$
\left\|\left(u-u_{s}\right)\right\|_{L^{6}(\mathcal{F})}+\left\|\nabla\left(u-u_{s}\right)\right\|_{L^{2}(\mathcal{F})} \leqslant K\|w\|_{W^{1, \infty}\left(\mathbb{R}^{3}\right)} \sqrt{\frac{M}{N}}\left[\frac{1}{N}+\sqrt{\frac{M}{N d_{m}}}\right]
$$

Proof. We split the error term into two pieces. First, we reduce the boundary conditions of the Stokes problem (17)-(18) to constant boundary conditions. Then, we compare the solution to the Stokes problem with constant boundary conditions to the combination of stokeslets $u_{s}$. In the whole proof, the symbol $\lesssim$ is used when the implicit constant in our inequality does not depend on $N, M, d_{m}$ and $w$.

So, we introduce $u_{c}$ the unique generalized solution to the Stokes problem on $\mathcal{F}$ with boundary conditions:

$$
\begin{cases}u_{c}=w\left(x_{i}\right), & \text { on } B_{i}^{N}, \forall i=1, \ldots, M  \tag{19}\\ u_{c}=0, & \text { on } \partial T^{N}\end{cases}
$$

Again, existence and uniqueness of this velocity-field holds by applying Theorem 3. We split then:

$$
\begin{aligned}
\left\|\left(u-u_{s}\right)\right\|_{L^{6}(\mathcal{F})} & \leqslant\left\|\left(u-u_{c}\right)\right\|_{L^{6}(\mathcal{F})}+\left\|\left(u_{c}-u_{s}\right)\right\|_{L^{6}(\mathcal{F})}, \\
\left\|\nabla\left(u-u_{s}\right)\right\|_{L^{2}(\mathcal{F})} & \leqslant\left\|\nabla\left(u-u_{c}\right)\right\|_{L^{2}(\mathcal{F})}+\left\|\nabla\left(u_{c}-u_{s}\right)\right\|_{L^{2}(\mathcal{F})} .
\end{aligned}
$$

To control the first term on the right-hand sides, we note that $\left(u-u_{c}\right)$ is the unique generalized solution to the Stokes problem on $\mathcal{F}$ with boundary conditions:

$$
\left\{\begin{array}{lll}
\left(u-u_{c}\right)(x)=w(x)-w\left(x_{i}\right), & & \text { on } B_{i}^{N}, \forall i=1, \ldots, M, \\
\left(u-u_{c}\right)(x)=0, & & \text { on } \partial T^{N} .
\end{array}\right.
$$

Hence, by the variational characterization of Theorem 3. \| $\left\|\nabla\left(u-u_{c}\right)\right\|_{L^{2}(\mathcal{F})}$ realizes the minimum of $\|\nabla \tilde{w}\|_{L^{2}(\mathcal{F})}$ amongst

$$
\left\{\tilde{w} \in H^{1}(\mathcal{F}) \text { s.t. } \operatorname{div} \tilde{w}=0, \tilde{w}_{\left.\right|_{\partial T^{N}}}=0, \tilde{w}_{\left.\right|_{\partial B_{i}^{N}}}=w(\cdot)-w\left(x_{i}\right), \forall i=1, \ldots, M\right\} .
$$

We construct thus a suitable $\tilde{w}$ in this space. We set:

$$
\tilde{w}=\sum_{i=1}^{M} \tilde{w}_{i}
$$

with, for $i=1, \ldots, M$ :

$$
\tilde{w}_{i}=\left(\chi^{N}\left(\cdot-x_{i}\right)\left(w(\cdot)-w\left(x_{i}\right)\right)-\mathfrak{B}_{x_{i}, 1 / N, 2 / N}\left[x \mapsto\left(w(x)-w\left(x_{i}\right)\right) \cdot \nabla \chi^{N}\left(x-x_{i}\right)\right]\right) .
$$

We recall that $\chi^{N}$ is a chosen function that truncates between $B_{\infty}(0,1 / N)$ and $B_{\infty}(0,2 / N)$ and that we denote $\mathfrak{B}_{x_{i}, 1 / N, 2 / N}$ the Bogovskii operator on the annulus $A\left(x_{i}, 1 / N, 2 / N\right)$. The
properties of this operator are analyzed in Appendix A. The above vector-field $\tilde{w}_{i}$ is welldefined as, for $i=1, \ldots, M$, there holds:

$$
\begin{aligned}
\int_{A\left(x_{i}, 1 / N, 2 / N\right)}\left(w(x)-w\left(x_{i}\right)\right) \cdot & \nabla \chi^{N}\left(x-x_{i}\right) \mathrm{d} x \\
& =\int_{B_{\infty}\left(x_{i}, 2 / N\right) \backslash B_{\infty}\left(x_{i}, 1 / N\right)} \operatorname{div}\left(\chi^{N}\left(\cdot-x_{i}\right)\left(w(\cdot)-w\left(x_{i}\right)\right)\right) \\
& =\int_{\partial B_{\infty}\left(x_{i}, 1 / N\right)}\left(w(x)-w\left(x_{i}\right)\right) \cdot n \mathrm{~d} \sigma \\
& =\int_{B_{\infty}\left(x_{i}, 1 / N\right)} \operatorname{div}(w)=0
\end{aligned}
$$

and we can apply the Bogovskii operator to $x \mapsto\left(w(\cdot)-w\left(x_{i}\right)\right) \cdot \nabla \chi^{N}\left(\cdot-x_{i}\right)$ on the annulus $A\left(x_{i}, 1 / N, 2 / N\right)$. We note that $\tilde{w}_{i}$ has support in $B_{\infty}\left(x_{i}, 2 / N\right)$ so that, as $d_{m}>4 / N$, the $\tilde{w}_{i}$ have disjoint supports inside $T^{N}$. This yields that $\tilde{w}$ is indeed divergence-free and fits the required boudary conditions. Furthermore, there holds:

$$
\|\nabla \tilde{w}\|_{L^{2}(\mathcal{F})} \leqslant\left[\sum_{i=1}^{M}\left\|\nabla \tilde{w}_{i}\right\|_{L^{2}\left(B_{\infty}\left(x_{i}, 2 / N\right)\right)}^{2}\right]^{\frac{1}{2}}
$$

For $i \in\{1, \ldots, M\}$ we have by direct computations:

$$
\begin{aligned}
\left\|\nabla \chi^{N}\left(\cdot-x_{i}\right)\left(w(\cdot)-w\left(x_{i}\right)\right)\right\|_{L^{2}\left(B_{\infty}\left(x_{i}, 2 / N\right)\right)}^{2} & \lesssim \frac{\|w\|_{W^{1, \infty}}^{2}}{N^{3}}, \\
\left\|\chi^{N}\left(\cdot-x_{i}\right) \nabla\left(w(\cdot)-w\left(x_{i}\right)\right)\right\|_{L^{2}\left(B_{\infty}\left(x_{i}, 2 / N\right)\right)}^{2} & \lesssim \frac{\|w\|_{W^{1, \infty}}^{2}}{N^{3}},
\end{aligned}
$$

and, by applying Lemma 15 ,

$$
\begin{aligned}
&\left\|\nabla \mathfrak{B}_{x_{i}, 1 / N, 2 / N}\left[x \mapsto\left(w(x)-w\left(x_{i}\right)\right) \cdot \nabla \chi^{N}\left(x-x_{i}\right)\right]\right\|_{L^{2}\left(B_{\infty}\left(x_{i}, 2 / N\right)\right)}^{2} \\
& \lesssim\left\|x \mapsto\left(w(x)-w\left(x_{i}\right)\right) \cdot \nabla \chi^{N}\left(x-x_{i}\right)\right\|_{L^{2}\left(B_{\infty}\left(x_{i}, 2 / N\right)\right)}^{2} \\
& \lesssim \frac{\|w\|_{W^{1, \infty}}^{2}}{N^{3}} .
\end{aligned}
$$

Gathering all these inequalities in the computation of $\tilde{w}$ yields finally:

$$
\|\nabla \tilde{w}\|_{L^{2}(\mathcal{F})} \lesssim \sqrt{M} \frac{\|w\|_{W^{1, \infty}}}{N^{\frac{3}{2}}} .
$$

The variational characterization of generalized solutions to Stokes problems entails that we have the same bound for $\left(u-u_{c}\right)$. At this point, we argue that the straightforward extension of $u$ and $u_{c}$ (by $w$ and $w\left(x_{i}\right)$ on the $B_{i}^{N}$ respectively) satisfy $\left(u-u_{c}\right) \in H_{0}^{1}\left(T^{N}\right) \subset L^{6}\left(T^{N}\right)$
so that

$$
\begin{aligned}
\left\|u-u_{c}\right\|_{L^{6}(\mathcal{F})} & \leqslant\left\|u-u_{c}\right\|_{L^{6}\left(T^{N}\right)} \lesssim\left\|\nabla\left(u-u_{c}\right)\right\|_{L^{2}\left(T^{N}\right)} \\
& \lesssim\left(\left\|\nabla\left(u-u_{c}\right)\right\|_{L^{2}(\mathcal{F})}^{2}+M \frac{\|w\|_{W^{1, \infty}}^{2}}{N^{3}}\right)^{\frac{1}{2}} \\
& \lesssim \sqrt{M} \frac{\|w\|_{W^{1, \infty}}}{N^{\frac{3}{2}}}
\end{aligned}
$$

We emphasize that, by a scaling argument, the constant deriving from the embedding $H_{0}^{1}\left(T^{N}\right) \subset L^{6}\left(T^{N}\right)$ does not depend on $N$ so that it is not significant to our problem.

We turn to estimating $u_{c}-u_{s}$. Due to the linearity of the Stokes equations, we split

$$
u_{c}=\sum_{i=1}^{M} u_{c, i}
$$

where $u_{c, i}$ is the generalized solution to Stokes problem on $\mathcal{F}$ with boundary conditions:

$$
\begin{cases}u_{c, i}=w\left(x_{i}\right), & \\ \text { on } \partial B_{i}^{N}, \\ u_{c, i}=0, & \\ \text { on } \partial T^{N} \cup \bigcup_{j \neq i} \partial B_{j}^{N} .\end{cases}
$$

We have then

$$
\begin{equation*}
\left\|\nabla\left(u_{c}-u_{s}\right)\right\|_{L^{2}(\mathcal{F})} \leqslant \sum_{i=1}^{M}\left\|\nabla\left(u_{c, i}-U^{N}\left[w\left(x_{i}\right)\right]\left(\cdot-x_{i}\right)\right)\right\|_{L^{2}(\mathcal{F})} \tag{20}
\end{equation*}
$$

Similarly, we expand :

$$
u_{s}=\sum_{i=1}^{M} U_{i}, \text { where } U_{i}(x)=U^{N}\left[w\left(x_{i}\right)\right]\left(x-x_{i}\right), \quad \forall x \in \mathbb{R}^{3}
$$

For $i \in\{1, \ldots, M\}$ we extend $u_{c, i}$ by 0 on $\mathbb{R}^{3} \backslash T^{N}$ and $B_{j}^{N}$ for $j \neq i$. The extension we still denote by $u_{c, i}$ satisfies $u_{c, i} \in H^{1}\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$ and is divergence-free. In particular, we have $u_{c, i} \in D\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$. Consequently, $u_{c, i}-U_{i} \in D\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$ and:

$$
\begin{aligned}
\left\|\nabla\left(u_{c, i}-U_{i}\left(\cdot-x_{i}\right)\right)\right\|_{L^{2}(\mathcal{F})}^{2} & \leqslant \int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla u_{c, i}(x)-\nabla U_{i}(x)\right|^{2} \mathrm{~d} x \\
& \leqslant \int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla u_{c, i}\right|^{2}-2 \int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}} \nabla u_{c, i}: \nabla U_{i}+\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla U_{i}\right|^{2} .
\end{aligned}
$$

To compute the product term, we apply that $u_{c, i}$ and $U_{i}=U^{N}\left[w\left(x_{i}\right)\right]\left(\cdot-x_{i}\right)$ have the same trace on $\partial B_{i}^{N}$ and that $U_{i}$ is a generalized solution to the Stokes problem on $\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}$. So, integrals of the form $\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}} \nabla U_{i}: \nabla w$ (for $w \in D\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$ ) depend only on the trace of $w$ on $\partial B_{i}^{N}$. This entails that:

$$
\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}} \nabla u_{c, i}: \nabla U_{i}=\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla U_{i}\right|^{2},
$$

and we have:

$$
\begin{equation*}
\left\|\nabla\left(u_{c, i}-U^{N}\left(\cdot-x_{i}\right)\right)\right\|_{L^{2}(\mathcal{F})}^{2} \leqslant \int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla u_{c, i}\right|^{2}-\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla U_{i}\right|^{2} . \tag{21}
\end{equation*}
$$

To conclude, we find a bound from above for

$$
\int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\nabla u_{c, i}(x)\right|^{2} \mathrm{~d} x=\int_{\mathcal{F}}\left|\nabla u_{c, i}(x)\right|^{2} \mathrm{~d} x .
$$

As $u_{c, i}$ is a generalized solution to a Stokes problem on $\mathcal{F}$, this can be done by constructing a divergence-free $\bar{w}_{i}$ satisfying the same boundary condition as $u_{c, i}$. We define:

$$
\bar{w}_{i}=\chi_{d_{m} / 4}\left(\cdot-x_{i}\right) U_{i}-\mathfrak{B}_{x_{i}, d_{m} / 4, d_{m} / 2}\left[x \mapsto U_{i}(x) \cdot \nabla \chi_{d_{m} / 4}\left(x-x_{i}\right)\right]
$$

where $\chi_{d_{m} / 4}:=\chi^{4 / d_{m}}$ (with the family of truncation functions of the introduction) As previously, we have here a divergence-free function which satisfies the right boundary conditions because $\chi_{d_{m} / 4}\left(\cdot-x_{i}\right)=1$ on $B_{i}^{N}\left(\right.$ since $\left.d_{m} / 4>1 / N\right)$ and vanishes on all the other boundaries of $\partial \mathcal{F}$ (since the distance between one hole center and the other holes or $\partial T^{N}$ is larger than $\left.d_{m}-1 / N>d_{m} / 2\right)$. Again, similarly as in the computation of $\tilde{w}_{i}$ we apply the properties of the Bogovskii operator $\mathfrak{B}_{x_{i}, d_{m} / 4, d_{m} / 2}$ and there exists an absolute constant $K$ for which:

$$
\begin{aligned}
&\left\|\nabla \bar{w}_{i}\right\|_{L^{2}(\mathcal{F})}^{2} \leqslant \int_{\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}}\left|\chi_{d_{m} / 4}\left(\cdot-x_{i}\right) \nabla U_{i}\right|^{2} \\
&+K\left(\int_{A\left(x_{i}, d_{m} / 4, d_{m} / 2\right)}\left|\nabla U_{i}(x)\right|^{2}+\left|\nabla \chi_{d_{m} / 2}\left(x-x_{i}\right) \otimes U_{i}(x)\right|^{2} \mathrm{~d} x\right)
\end{aligned}
$$

As we have the same bound for $u_{c, i}$, we plug the right-hand side above in (21) and get:

$$
\begin{aligned}
\left\|\nabla\left(u_{c, i}-U_{i}\right)\right\|_{L^{2}(\mathcal{F})}^{2} \lesssim \int_{A\left(x_{i}, d_{m} / 4, d_{m} / 2\right)} \mid \nabla & \left.U_{i}(x)\right|^{2} \mathrm{~d} x \\
& +\int_{A\left(x_{i}, d_{m} / 4, d_{m} / 2\right)}\left|\nabla \chi_{d_{m} / 4}\left(x-x_{i}\right) \otimes U_{i}(x)\right|^{2} \mathrm{~d} x
\end{aligned}
$$

With the explicit decay properties for $U_{i}$ (see (141)) and $\nabla \chi_{d_{m} / 4}$ we derive:

$$
\int_{A\left(x_{i}, d_{m} / 4, d_{m} / 2\right)}\left(\left|\nabla U_{i}(x)\right|^{2}+\left|\nabla \chi_{d_{m} / 4}\left(x-x_{i}\right) \otimes U_{i}(x)\right|^{2}\right) \mathrm{d} x \lesssim \frac{\|w\|_{W^{1, \infty}}^{2}}{N^{2} d_{m}}
$$

Combining these bounds for $i=1, \ldots, M$ in (20) we get:

$$
\left\|\nabla\left(u_{c}-u_{s}\right)\right\|_{L^{2}(\mathcal{F})} \leqslant \frac{M\|w\|_{W^{1, \infty}}}{N \sqrt{d_{m}}}
$$

By similar arguments, we also have:

$$
\left\|u_{c}-u_{s}\right\|_{L^{6}(\mathcal{F})}=\left\|u_{c}-u_{s}\right\|_{L^{6}\left(T^{N}\right)} \leqslant \sum_{i=1}^{M}\left\|u_{c, i}-U_{i}\right\|_{L^{6}\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)} .
$$

As $u_{c, i}, U_{i} \in D\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$ and $u_{c, i}, U_{i}$ share the same value on $\partial B_{i}^{N}$, there holds $u_{c, i}-U_{i} \in$ $D_{0}\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)$ and we may use the classical inequality (see [7, (II.6.9)]):

$$
\left\|u_{c, i}-U_{i}\right\|_{L^{6}\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)} \lesssim\left\|\nabla u_{c, i}-\nabla U_{i}\right\|_{L^{2}\left(\mathbb{R}^{3} \backslash \overline{B_{i}^{N}}\right)}, \quad \forall i=1, \ldots, M
$$

(again the constant arising from this embedding does not depend on $N$ by a standard scaling argument). This yields again the bound:

$$
\left\|\left(u_{c}-u_{s}\right)\right\|_{L^{6}(\mathcal{F})} \leqslant \frac{M\|w\|_{W^{1, \infty}}}{N \sqrt{d_{m}}}
$$

and ends the proof of our proposition.

## 3. Proof of Theorem 1 - Uniform estimates

From now on, we fix a sequence of data $\left(v_{i}^{N}, h_{i}^{N}\right)_{i=1, \ldots, N}$ associated to $\left(B_{i}^{N}\right)_{i=1, \ldots, N}$ that satisfy (A0) for arbitrary $N \in \mathbb{N}$ and such that (A1)-(A5) hold true with

$$
j \in L^{2}(\Omega), \quad \rho \in L^{\infty}(\Omega)
$$

Because of assumption (AO), the existence result of the previous section applies so that there exists a unique generalized solution $u^{N} \in H^{1}\left(\mathcal{F}^{N}\right)$ to (11)-(2). In what follows, we extend implicitly $u^{N}$ by its boundary values on the $\partial B_{i}^{N}$ :

$$
u^{N}= \begin{cases}u^{N}, & \text { in } \mathcal{F}^{N}, \\ v_{i}^{N}, & \text { in } B_{i}^{N}, \text { for } i=1, \ldots, N .\end{cases}
$$

As the $B_{i}^{N}$ do not overlap and do not meet $\partial \Omega$, it is straightforward that these velocityfields yield a sequence in $H_{0}^{1}(\Omega)$ of divergence-free vector-fields. Moreover, we have the property:

$$
\left\|\nabla u^{N}\right\|_{L^{2}\left(\mathcal{F}^{N}\right)}=\left\|\nabla u^{N}\right\|_{L^{2}(\Omega)}
$$

Our target result reads:
Theorem 6. The sequence of extended generalized solutions $\left(u^{N}\right)_{N \in \mathbb{N}}$ converges weakly in $H_{0}^{1}(\Omega)$ to $\bar{u}$ satisfying
(B1) $\bar{u} \in H_{0}^{1}(\Omega)$,
(B2) $\operatorname{div} \bar{u}=0$ on $\Omega$,
(B3) for any divergence-free $w \in C_{c}^{\infty}(\Omega)$ we have:

$$
\begin{equation*}
\int_{\Omega} \nabla \bar{u}: \nabla w=6 \pi \int_{\Omega}[j-\rho \bar{u}] \cdot w . \tag{22}
\end{equation*}
$$

Theorem 1 is a corollary of this theorem as (B1)-(B2)-(B3) corresponds to the generalized formulation of the Stokes-Brinkman system (3)-(4). The remainder of the paper is devoted to the proof of this result. In this section, we prove that $u^{N}$ is bounded in $H_{0}^{1}(\Omega)$, extract
a subsequence weakly converging to some $\bar{u}$ and justify that it remains then to prove that $\bar{u}$ satisfies (B3). The two next sections are devoted to the computations of integrals:

$$
I_{w}=\int_{\Omega} \nabla \bar{u}: \nabla w
$$

for a fixed but arbitrary divergence-free $w \in C_{c}^{\infty}(\Omega)$.
So, we first compute uniform bounds on $u^{N}$ by applying the variational characterization of solutions to the Stokes problem (10). Given $N \in \mathbb{N}$, we set:

$$
v^{N}(x)=\sum_{i=1}^{N} \nabla \times\left(\frac{\chi^{N}\left(x-h_{i}^{N}\right)}{2} v_{i}^{N} \times\left(x-h_{i}^{N}\right)\right)=: \sum_{i=1}^{N} v_{i}(x) .
$$

Then, $v^{N} \in C_{c}^{\infty}\left(\mathbb{R}^{3}\right)$ is the curl of a smooth potential vector so that $\operatorname{div} v^{N}=0$. Because of assumption (A2), there exists a $N_{0} \in \mathbb{N}$ such that:

$$
N d_{\min }^{N}>4, \quad \forall N>N_{0}
$$

Let $N>N_{0}$ from now on. Because $\chi^{N}$ has support in $B_{\infty}(0,2 / N)$ we have that $\operatorname{Supp}_{i} \subset$ $B_{\infty}\left(h_{i}^{N}, 2 / N\right)$ and the $\left(v_{i}\right)_{i=1, \ldots, N}$ have disjoint supports. Because $\chi^{N}$ is 1 on $B(0,1 / N) \subset$ $B_{\infty}(0,1 / N)$ we derive further that, for $i \in\{1, \ldots, N\}$ :

$$
\begin{aligned}
& v_{i}(x)=0, \quad \text { on } \partial \mathcal{F}^{N} \cup \bigcup_{j \neq i} B_{j}^{N} \\
& v_{i}(x)=\nabla \times\left(\frac{1}{2} v_{i}^{N} \times\left(x-h_{i}^{N}\right)\right)=v_{i}^{N}, \quad \text { on } B_{i}^{N} .
\end{aligned}
$$

By combination, we obtain:

$$
\begin{aligned}
& v^{N}(x)=v_{i}^{N}, \quad \text { on } B_{i}^{N}, \quad \forall i=1, \ldots, N, \\
& v^{N}(x)=0, \quad \text { on } \partial \mathcal{F}^{N} .
\end{aligned}
$$

We have then by Theorem 3 that:

$$
\begin{equation*}
\left\|\nabla u^{N}\right\|_{L^{2}\left(\mathcal{F}^{N}\right)} \leqslant\left\|\nabla v^{N}\right\|_{L^{2}\left(\mathcal{F}^{N}\right)}=\left(\sum_{i=1}^{N}\left\|\nabla v_{i}\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}\right)^{\frac{1}{2}} \tag{23}
\end{equation*}
$$

For arbitrary $N \in \mathbb{N}$ and $i \in\{1, \ldots, N\}$, there holds:

$$
\begin{aligned}
\left|\nabla v_{i}(x)\right| & \lesssim\left|\nabla \chi^{N}\left(x-h_{i}^{N}\right)\right|\left|v_{i}^{N}\right|+\left|\nabla^{2} \chi^{N}\left(x-h_{i}^{N}\right)\right|\left|v_{i}^{N}\right|\left|x-h_{i}^{N}\right| \\
& \lesssim N\left(\left|\nabla \chi\left(N\left(x-h_{i}^{N}\right)\right)\right|+\left|\nabla^{2} \chi\left(N\left(x-h_{i}^{N}\right)\right)\right|\right)\left|v_{i}^{N}\right|
\end{aligned}
$$

Consequently, by a standard scaling argument:

$$
\int_{\mathbb{R}^{3}}\left|\nabla v_{i}(x)\right|^{2} \mathrm{~d} x \lesssim \frac{1}{N}\left(\int_{\mathbb{R}^{3}}|\nabla \chi(|y|)|^{2}+\left|\nabla^{2} \chi(|y|)\right|^{2} \mathrm{~d} y\right)\left|v_{i}^{N}\right|^{2}
$$

Then, for $N>N_{0}$, we combine the previous computation into:

$$
\left\|\nabla v^{N}\right\|_{L^{2}\left(\mathcal{F}^{N}\right)}^{2} \lesssim \frac{1}{N} \sum_{i=1}^{N}\left|v_{i}^{N}\right|^{2}
$$

Note that $\chi$ is fixed a priori so that all constants depending on $\chi$ may be considered as non-significant. Assumption (A1) then yields that there exists $\mathcal{E}^{\infty}<\infty$ so that:

$$
\begin{equation*}
\left(\frac{1}{N} \sum_{i=1}^{N}\left|v_{i}^{N}\right|^{2}\right)^{\frac{1}{2}} \leqslant \mathcal{E}^{\infty}, \quad \forall N>N_{0} \tag{24}
\end{equation*}
$$

By (23) the norm of $u^{N}$ in $H_{0}^{1}(\Omega)$ is also bounded by $\mathcal{E}^{\infty}$. We keep the symbol $\mathcal{E}^{\infty}$ to denote the above bound in what follows.

As $u^{N}$ is bounded in $H_{0}^{1}(\Omega)$, it is weakly-compact and we denote by $\bar{u}$ a cluster-point for the weak topology. It is straightforward that $\bar{u}$ satisfies $\operatorname{div} \bar{u}=0$ on $\Omega$. So $\bar{u}$ satisfies (B1) and (B2) of our theorem. The remainder of the proof consists in showing that it satisfies (B3) also. Indeed, we remark that $\rho$ is the density of a probability measure. Hence $\rho \geqslant 0$ on $\Omega$. By a simple energy estimate one may then show that, given $j \in L^{2}(\Omega)$, there exists at most one $\bar{u} \in H_{0}^{1}(\Omega)$ that satisfies simultaneously (B1)-(B2)-(B3). A direct corollary of this remark is that, if we prove that (B3) is satisfied by $\bar{u}$ we have uniqueness of the possible cluster point to the sequence $\left(u^{N}\right)_{N \in \mathbb{N}}$ and the whole sequence converges to this $\bar{u}$ in $H_{0}^{1}(\Omega)-w$.

## 4. Proof of Theorem 1 - Computations for finite $N$

From now on, we assume that $u^{N}$ converges weakly to $\bar{u}$ in $H_{0}^{1}(\Omega)$ (we do not relabel the subsequence for simplicity) and we fix a divergence-free $w \in C_{c}^{\infty}(\Omega)$. We aim to compute the scalar product:

$$
\int_{\Omega} \nabla \bar{u}: \nabla w .
$$

By definition, we have:

$$
\int_{\Omega} \nabla \bar{u}: \nabla w=\lim _{N \rightarrow \infty} I^{N} \text { with } I^{N}=\int_{\Omega} \nabla u^{N}: \nabla w, \quad \forall N \in \mathbb{N} .
$$

As classical, we want to apply the equation satisfied by $u^{N}$ in order to compute $I^{N}$ in a way that makes possible to use the assumption on the convergence of the empiric measures $S_{N}$. To do this, we fix an integer $\delta \geqslant 4$, we construct, for fixed $N$, a suitable test-function $w^{s}$ (depending actually on $\delta$ and $N$ ) so that

- we make an error of order $1 / \sqrt{\delta}$ by replacing $w$ with $w^{s}$ in $I^{N}$,
- replacing $w$ with $w^{s}$ in $I^{N}$ we prove that,

$$
\int_{\Omega} \nabla u^{N}: \nabla w^{s} \rightarrow 6 \pi \int_{\Omega}(j-\rho \bar{u}) \cdot w+\text { error },
$$

when $N \rightarrow \infty$, with an error of size $1 / \sqrt{\delta}$.

As $\delta$ can be taken arbitrary large, this will yield the expected result.
We explain now the construction of $w^{s}$. The integer $\delta \geqslant 4$ is fixed in the remainder of this section. For a given $N \in \mathbb{N}$, applying the construction in Appendix B we obtain $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathbb{Z}^{3}}$ a covering of $\mathbb{R}^{3}$ with cubes of width $1 / N^{1 / 3}$ such that denoting:

$$
\mathcal{Z}_{\delta}^{N}:=\left\{i \in\{1, \ldots, N\} \text { s.t. } \operatorname{dist}\left(h_{i}^{N}, \bigcup_{\kappa \in \mathbb{Z}^{3}} \partial T_{\kappa}^{N}\right)<\frac{1}{\delta N^{1 / 3}}\right\}
$$

there holds:

$$
\begin{equation*}
\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left(1+\left|v_{i}^{N}\right|^{2}\right) \leqslant \frac{12}{\delta} \frac{1}{N} \sum_{i=1}^{N}\left(1+\left|v_{i}^{N}\right|^{2}\right) \leqslant \frac{12\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)}{\delta} \tag{25}
\end{equation*}
$$

Moreover, for $N \geqslant N_{w}$, for a $N_{w}$ depending only on $w$ and $\Omega$, keeping only the indices $\mathcal{K}^{N}$ such that $T_{\kappa}^{N}$ intersect $\operatorname{Supp}(w)$, we obtain a covering $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ of $\operatorname{Supp}(w)$ such that all the cubes are included in $\Omega$ (see the appendix for more details). We assume $N \geqslant N_{w}$ from now on. We emphasize that we do not make precise the set of indices $\mathcal{K}^{N}$. The only relevant property to our computations is that

$$
\begin{equation*}
\# \mathcal{K}^{N} \leqslant N|\Omega| . \tag{26}
\end{equation*}
$$

This inequality is derived by remarking that the $T_{\kappa}^{N}$ are disjoint cubes of volume $1 / N$ that are all included in $\Omega$. Associated to this covering, we introduce the following notations. For arbitrary $\kappa \in \mathcal{K}^{N}$, we set

$$
\mathcal{I}_{\kappa}^{N}:=\left\{i \in\{1, \ldots, N\} \text { s.t. } h_{i}^{N} \in T_{\kappa}^{N}\right\}, \quad M_{\kappa}^{N}:=\# \mathcal{I}_{\kappa}^{N},
$$

and $\mathcal{I}^{N}:=\bigcup_{\kappa \in \mathcal{K}^{N}} \mathcal{I}_{\kappa}^{N}$. Because of assumption (A3), there exists $M^{\infty} \in \mathbb{N}$ such that:

$$
\begin{equation*}
M_{\kappa}^{N} \leqslant M^{\infty}, \quad \forall \kappa \in \mathcal{K}^{N}, \quad \forall N \in \mathbb{N} \tag{27}
\end{equation*}
$$

In brief, the set of indices $\{1, \ldots, N\}$ contains the three important subsets:

- the subset $\mathcal{I}^{N}$ contains all the indices that are "activated" in our computations,
- the subset $\mathcal{Z}_{\delta}^{N}$ contains the indices that are close to boundaries of the partition,
- the subset $\{1, \ldots, N\} \backslash \mathcal{I}^{N}$ contains indices that are not activated.

We emphasize that $\mathcal{Z}_{\delta}^{N}$ contains indices that can be in both $\mathcal{I}^{N}$ and its complement.
We construct then $w^{s}$ piecewisely on the covering of $\operatorname{Supp}(w)$. Given $\kappa \in \mathcal{K}^{N}$, we set:

$$
\begin{equation*}
w_{\kappa}^{s}(x)=\sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right), \quad \forall x \in \mathbb{R}^{3}, \tag{28}
\end{equation*}
$$

and

$$
w^{s}=\sum_{\kappa \in \mathcal{K}^{N}} w_{\kappa}^{s} \mathbf{1}_{T_{\kappa}^{N}}
$$

We note that $w^{s} \notin H_{0}^{1}\left(\mathcal{F}^{N}\right)$ because of jumps at interfaces $\partial T_{\kappa}^{N}$. It will be sufficient for our purpose that $w^{s} \in H^{1}\left(\stackrel{\circ}{T}_{\kappa}^{N}\right)$ for arbitrary $\kappa \in \mathcal{K}^{N}$. In a cube $\stackrel{\circ}{\kappa}_{\kappa}^{N}$ the test function $w^{s}$ is thus a combination of stokeslets centered in the $h_{i}^{N}$ that are contained in the cell. We delete
from this combination the centers that are too close to $\partial T_{\kappa}^{N}$ (namely $1 /\left(\delta N^{1 / 3}\right)$ close to $\left.\partial T_{\kappa}^{N}\right)$. We proceed by proving that we make a small error by replacing $w$ with $w^{s}$ in $I^{N}$ :

Proposition 7. There exists $K \in(0, \infty)$ and $N_{\delta} \in \mathbb{N}$ depending only on $\delta$ and $w$ for which, given $N>N_{\delta}$, there holds:

$$
\begin{equation*}
\left|\int_{\Omega} \nabla u^{N}: \nabla w-\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w^{s}\right| \leqslant K\left(\frac{1}{\sqrt{\delta}}+\frac{1}{N^{\frac{1}{6}}}+\frac{1}{\sqrt{N d_{\min }}}\right) . \tag{29}
\end{equation*}
$$

Proof. We proceed in several steps by introducing different intermediate test-functions. In this proof, we use symbol $\lesssim$ to denote inequalities with constants that do not depend on $N$ and $\delta$.
First step: Construction of auxiliary test-functions. For arbitrary $\kappa \in \mathcal{K}^{N}$, we consider the Stokes problem on $\stackrel{\circ}{\kappa}_{N} \backslash \bigcup_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \overline{B_{i}^{N}}$ with boundary conditions:

$$
\begin{cases}u(x)=w(x), & \text { on } \partial B_{i}^{N} \text { for } i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N},  \tag{30}\\ u(x)=0, & \text { on } \partial T_{\kappa}^{N} .\end{cases}
$$

We note that this problem enters the framework of Section 2.2. Indeed, let denote:

$$
d_{m}^{\kappa}:=\min _{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left\{\operatorname{dist}\left(h_{i}^{N}, \partial T_{\kappa}^{N}\right), \min _{j \neq i}\left|h_{i}^{N}-h_{j}^{N}\right|\right\}
$$

Because we deleted the indices of $\mathcal{Z}_{\delta}^{N}$, we have that:

$$
d_{m}^{\kappa} \geqslant \min \left(d_{\min }^{N}, \frac{1}{\delta N^{\frac{1}{3}}}\right) .
$$

In particular, for $N$ sufficiently large depending only on $\delta\left(N>N_{\delta}=\max \left(N_{0},(4 \delta)^{3 / 2}\right)\right)$ the $d_{m}^{\kappa}$ satisfy assumption (16) uniformy in $\kappa \in \mathcal{K}^{N}$. We remark that making $N_{\delta}$ larger than $\delta^{3}$, we have also that, for $N>N_{\delta}$, there holds:

$$
\frac{1}{\delta N^{\frac{1}{3}}} \geqslant \frac{1}{N^{\frac{2}{3}}} .
$$

Consequently, we apply below that not only assumption (16) is satisfied, but also:

$$
\begin{equation*}
\frac{1}{N d_{m}^{k}} \leqslant \max \left(\frac{1}{N d_{\min }^{N}}, \frac{1}{N^{\frac{1}{3}}}\right), \quad \forall N>N_{\delta} . \tag{31}
\end{equation*}
$$

So, for $N>N_{\delta}$ the arguments developed in Section 2.2 entail that there exists a unique generalized solution to the Stokes problem on $\stackrel{\circ}{\kappa}_{N}^{N} \backslash \bigcup_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \overline{B_{i}^{N}}$ with boundary condition (30). We denote this solution by $\bar{w}_{\kappa}$. We keep notation $\bar{w}_{\kappa}$ to denote its extension to $\Omega$ (by $w$ on the holes and by 0 outside $\left.\stackrel{\circ}{T}_{\kappa}^{N}\right)$. As $\stackrel{\circ}{T}_{\kappa}^{N} \subset \Omega$, we obtain a divergence-free $\bar{w}_{\kappa} \in H_{0}^{1}(\Omega)$. We then add the $\bar{w}_{\kappa}$ into:

$$
\bar{w}=\sum_{\kappa \in \mathcal{K}^{N}} \bar{w}_{\kappa} .
$$

To summarize, this vector field satisfies:

- $\bar{w} \in H_{0}^{1}(\Omega)$,
- $\operatorname{div} \bar{w}=0$ on $\Omega$,
- $\bar{w}=w(x)$ on $B_{i}^{N}$ for all $i \in \mathcal{I}^{N} \backslash \mathcal{Z}_{\delta}^{N}$.

We correct now the value of $\bar{w}$ on the $B_{i}^{N}$ when $i \in \mathcal{Z}_{\delta}^{N} \cup\left(\{1, \ldots, N\} \backslash \mathcal{I}^{N}\right)$ in order that it fits the same boundary conditions as $w$ on $\mathcal{F}^{N}$. We set:

$$
\begin{aligned}
\tilde{w}= & \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left[\chi^{N}\left(\cdot-h_{i}^{N}\right) w-\mathfrak{B}_{h_{i}^{N}, 1 / N, 2 / N}\left[x \mapsto w(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right)\right]\right] \\
& +\prod_{i \in \mathcal{Z}_{\delta}^{N}}\left(1-\chi^{N}\left(\cdot-h_{i}^{N}\right)\right) \bar{w}+\sum_{i \in \mathcal{Z}_{\delta}^{N}} \mathfrak{B}_{h_{i}^{N}, 1 / N, 2 / N}\left[x \mapsto \bar{w}(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right)\right] .
\end{aligned}
$$

Briefly, one may interpret the construction of $\tilde{w}$ as follows. The sum on the first line creates a divergence-free lifiting of the boundary conditions prescribed by $w$ on the $\partial B_{i}^{N}$ for $i \in \mathcal{Z}_{\delta}^{N}$. On the second line is a divergence-free truncation of $\bar{w}$ that creates a vectorfield vanishing on $\cup_{i \in \mathcal{Z}_{\delta}^{N}} B_{i}^{N}$. We remark that this vector-field is well defined because, by similar computations as we did in the proof of Proposition 5, we have:
$\int_{A\left(h_{i}^{N}, 1 / N, 2 / N\right)} \bar{w}(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right) \mathrm{d} x=\int_{A\left(h_{i}^{N}, 1 / N, 2 / N\right)} w(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right) \mathrm{d} x=0, \quad \forall i \in \mathcal{Z}_{\delta}^{N}$.
Hence, we may apply the Bogovskii operator which lifts the divergence term in the brackets with a vector-field vanishing on the boundaries of $A\left(h_{i}^{N}, 1 / N, 2 / N\right)$ that we extend by 0 on $\mathbb{R}^{3} \backslash A\left(h_{i}^{N}, 1 / N, 2 / N\right)$. When $i \in\{1, \ldots, N\} \backslash\left(\mathcal{I}^{N} \cup \mathcal{Z}_{\delta}^{N}\right)$ we have that $h_{i}^{N}$ is in the $1 / \delta N^{1 / 3}$ core of the cube $T_{\kappa}^{N}$ that contains him. Moreover the index of this cube is not in $\mathcal{K}^{N}$. As $N>N_{\delta}$, we have then $B\left(h_{i}^{N}, 1 / N\right) \subset T_{\kappa}^{N}$ where there already holds that $\bar{w}(x)=w(x)=0$. Consequently, there is nothing to correct on these holes. This is the reason why they do not appear in the above construction.

Direct computations show that $\operatorname{div} \tilde{w}=0$ on $\Omega$. On the other hand, because $N>$ $N_{0}$, the family of balls $\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)_{i=1, \ldots, N}$ are disjoint and included in $\Omega$. Hence, the truncations that we perform in $\tilde{w}$ do not perturb the value of $\bar{w}$ neither on the $B_{i}^{N}$ for $i \in\{1, \ldots, N\} \backslash \mathcal{Z}_{\delta}^{N}$ nor on $\partial \Omega$. This remark entails that

- for $i \in \mathcal{I}^{N} \backslash \mathcal{Z}_{\delta}^{N}$ :

$$
\tilde{w}(x)=\bar{w}(x)=w(x), \quad \text { on } B_{i}^{N}
$$

- for $i \in \mathcal{Z}_{\delta}^{N}$ :

$$
\tilde{w}(x)=\chi^{N}\left(x-h_{i}^{N}\right) w(x)=w(x), \quad \text { on } B_{i}^{N}
$$

- for $i \in\{1, \ldots, N\} \backslash\left(\mathcal{I}^{N} \cup \mathcal{Z}_{\delta}^{N}\right)$ :

$$
\tilde{w}(x)=\bar{w}(x)=0=w(x), \quad \text { on } B_{i}^{N}
$$

- $w(x)=0$, on $\partial \Omega$.

Consequently, by restriction, there holds that $w-\tilde{w} \in H_{0}^{1}\left(\mathcal{F}^{N}\right)$ is divergence-free. As $u^{N}$ is a generalized solution to a Stokes problem on $\mathcal{F}^{N}$ we have thus:

$$
\int_{\mathcal{F}^{N}} \nabla u^{N}: \nabla(w-\tilde{w})=0
$$

We rewrite this identity as follows:

$$
\begin{equation*}
\int_{\Omega} \nabla u^{N}: \nabla w=\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w^{s}-E_{1}-E_{2} \tag{32}
\end{equation*}
$$

with :

$$
\begin{aligned}
& E_{1}=\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla\left(w_{\kappa}^{s}-\bar{w}_{\kappa}\right), \\
& E_{2}=\int_{\Omega} \nabla u^{N}: \nabla(\bar{w}-\tilde{w}) .
\end{aligned}
$$

Second step: Control of error term $E_{1}$. For arbitrary $\kappa \in \mathcal{K}^{N}$, we apply Proposition 5 to $\bar{w}_{\kappa}$ and its corresponding combination of stokeslets (namely, the restriction $w_{\kappa}^{s}$ of $w^{s}$ to $\left.\stackrel{\circ}{T}_{\kappa}^{N}\right)$. By construction, $d_{m}^{\kappa}$ satisfies the requirement $d_{m}^{\kappa}>4 / N$ for $N>N_{\delta}$. We have thus:

$$
\left\|\nabla\left(w_{\kappa}^{s}-\bar{w}_{\kappa}\right)\right\|_{L^{2}\left(T_{\kappa}^{N}\right)} \lesssim \sqrt{\frac{M_{\kappa}^{N}}{N}}\left(\frac{1}{N}+\sqrt{\frac{M_{\kappa}^{N}}{N d_{m}^{\kappa}}}\right)\|w\|_{W^{1, \infty}} .
$$

Note here that $\#\left(\mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}\right) \leqslant \# \mathcal{I}_{\kappa}^{N}=M_{\kappa}^{N}$. Consequently, introducing this last bound in the computation of $E_{1}$ and applying a standard Cauchy-Schwarz inequality together with (26)-(27) yields:

$$
\begin{aligned}
\left|E_{1}\right| & \lesssim \sum_{\kappa \in \mathcal{K}^{N}}\left\|\nabla u^{N}\right\|_{L^{2}\left(T_{\kappa}^{N}\right)} \sqrt{\frac{M_{\kappa}^{N}}{N}}\left(\frac{1}{N}+\sqrt{\frac{M_{\kappa}^{N}}{N d_{m}^{\kappa}}}\right)\|w\|_{W^{1, \infty}} \\
& \lesssim\left(\sum_{\kappa \in \mathcal{K}^{N}}\left\|\nabla u^{N}\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}^{2}\right)^{\frac{1}{2}} \sqrt{M^{\infty}}\left(\frac{1}{N}+\sqrt{\frac{M^{\infty}}{N d_{m}^{\kappa}}}\right)\|w\|_{W^{1, \infty}}
\end{aligned}
$$

Here, we note again that, by construction, the $T_{\kappa}^{N}$ are disjoint and included in $\Omega$ so that

$$
\left(\sum_{\kappa \in \mathcal{K}^{N}}\left\|\nabla u^{N}\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}^{2}\right)^{\frac{1}{2}} \leqslant\left\|\nabla u^{N}\right\|_{L^{2}(\Omega)}
$$

Applying the uniform bound for $u^{N}$ in $H_{0}^{1}(\Omega)$ we conclude then that:

$$
\left|E_{1}\right| \lesssim \mathcal{E}^{\infty}\left(\frac{\sqrt{M^{\infty}}}{N}+\frac{M^{\infty}}{\sqrt{N d_{m}^{\kappa}}}\right)\|w\|_{W^{1, \infty}}
$$

and, introducing (31), that:

$$
\begin{equation*}
\left|E_{1}\right| \lesssim \mathcal{E}^{\infty} M^{\infty}\left(\frac{1}{N^{\frac{1}{6}}}+\frac{1}{\sqrt{N d_{\min }^{N}}}\right)\|w\|_{W^{1, \infty}} \tag{33}
\end{equation*}
$$

Second step: Control of error term $E_{2}$. As for the second term, we replace $\tilde{w}$ by its explicit construction. We remark that because the supports of the $\left(\chi^{N}\left(\cdot-h_{i}^{N}\right)\right)_{i \in\{1, \ldots, N\}}$ are disjoint ( as $d_{\min }^{N}>4 / N$ for $N>N_{0}$ ) we have:

$$
1-\prod_{i \in \mathcal{Z}_{\delta}^{N}}\left(1-\chi^{N}\left(x-h_{i}^{N}\right)\right)=\sum_{i \in \mathcal{Z}_{\delta}^{N}} \chi^{N}\left(x-h_{i}^{N}\right), \quad \forall x \in \Omega .
$$

Consequently, we split:

$$
\begin{aligned}
\bar{w}-\tilde{w}= & \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left[\chi^{N}\left(\cdot-h_{i}^{N}\right) \bar{w}-\mathfrak{B}_{h_{i}^{N}, 1 / N, 2 / N}\left[x \mapsto \bar{w}(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right)\right]\right] \\
& -\sum_{i \in \mathcal{Z}_{\delta}^{N}}\left[\chi^{N}\left(\cdot-h_{i}^{N}\right) w-\mathfrak{B}_{h_{i}^{N}, 1 / N, 2 / N}\left[x \mapsto w(x) \cdot \nabla \chi^{N}\left(x-h_{i}^{N}\right)\right]\right] .
\end{aligned}
$$

By direct computations and application of Lemma 15 to the Bogovskii operator $\mathfrak{B}_{h_{i}^{N}, 1 / N, 2 / N}$, we find $E_{2}^{i} \in L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right), i \in \mathcal{Z}_{\delta}^{N}$, for which:

$$
\nabla(\bar{w}-\tilde{w})=\sum_{i \in \mathcal{Z}_{\delta}^{N}} E_{2}^{i} \mathbf{1}_{B_{\infty}\left(h_{i}^{N}, 2 / N\right)}
$$

and such that:

$$
\left\|E_{2}^{i}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} \lesssim \frac{1}{N}\|w\|_{W^{1, \infty}}^{2}+N^{2}\|\bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2}+\|\nabla \bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2}
$$

Introducing these bounds in the computation of $E_{2}$, and reproducing similar computations as for $E_{1}$, we derive:

$$
\begin{aligned}
\left|E_{2}\right| & \leqslant \sum_{i \in \mathcal{Z}_{\delta}^{N}} \int_{B_{\infty}\left(h_{i}^{N}, 2 / N\right)}\left|\nabla u^{N}\right|\left|E_{2}^{i}\right| \\
& \leqslant\left(\sum_{i \in \mathcal{Z}_{\delta}^{N}}\left\|\nabla u^{N}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2}\right)^{\frac{1}{2}}\left(\sum_{i \in \mathcal{Z}_{\delta}^{N}}\left\|E_{2}^{i}\right\|_{\left.L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)\right)}^{2}\right)^{\frac{1}{2}} \\
& \lesssim \mathcal{E}^{\infty}\left(\sum_{i \in \mathcal{Z}_{\delta}^{N}}\left\|E_{2}^{i}\right\|_{\left.L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)\right)}^{2}\right)^{\frac{1}{2}}
\end{aligned}
$$

where we applied again that the $\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)_{i \in \mathcal{Z}_{\delta}^{N}}$ are disjoint and cover a subset of $\Omega$. To complete the proof, it remains to compute:

$$
\begin{aligned}
& \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left\|E_{2}^{i}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} \\
& \qquad
\end{aligned}
$$

We recall that, by choice of the covering (see (251)), we have:

$$
\begin{equation*}
\sum_{i \in \mathcal{Z}_{\delta}^{N}} \frac{1}{N} \lesssim \frac{1}{\delta}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right) \tag{34}
\end{equation*}
$$

Consequently, there holds:

$$
\sum_{i \in \mathcal{Z}_{\delta}^{N}} \frac{1}{N}\|w\|_{W^{1, \infty}}^{2} \lesssim \frac{\|w\|_{W^{1, \infty}}^{2}}{\delta}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)
$$

To compute the terms depending on $\bar{w}$ we apply again Proposition 5 in order to write $\bar{w}=w^{s}+$ l.o.t. To this end, we remark that given $i \in \mathcal{Z}_{\delta}^{N}$ we have that $h_{i}^{N}$ is in the $1 /\left(\delta N^{1 / 3}\right)$-neighborhood of some $\partial T_{\kappa}^{N}$ then either $B_{\infty}\left(h_{i}^{N}, 2 / N\right) \subset T_{\kappa}^{N}$ or $B_{\infty}\left(h_{i}^{N}, 2 / N\right)$ intersects other cubes. In that second case, as the diameter of $B_{\infty}\left(h_{i}^{N}, 2 / N\right)$ is much smaller than the one of a cube $T_{\kappa}^{N}$, we have that $B_{\infty}\left(h_{i}^{N}, 2 / N\right)$ may intersect at most 2 "successive" cubes in the covering of $\mathbb{R}^{3}$, in all directions, and thus at most 8 cubes. Consequently:

$$
\begin{aligned}
\|\bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} & \leqslant 8 \sup _{\kappa \in \mathcal{K}^{N}}\left\|\bar{w}_{\kappa}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2} \\
\|\nabla \bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} & \leqslant 8 \sup _{\kappa \in \mathcal{K}^{N}}\left\|\nabla \bar{w}_{\kappa}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2}
\end{aligned}
$$

As $\bar{w}=0$ on any cube $T_{\kappa}^{N}$ whose index $\kappa \notin \mathcal{K}^{N}$, the corresponding indices $\kappa$ do not appear in these latter supremums. If $B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N} \neq \emptyset$ then we may introduce $w_{\kappa}^{s}$

$$
\begin{aligned}
\left\|\nabla \bar{w}_{\kappa}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2} & \lesssim\left\|\nabla\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}^{2}+\left\|\nabla w_{\kappa}^{s}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} \\
N^{2}\left\|\bar{w}_{\kappa}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2} & \lesssim N^{2}\left\|\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2}+N^{2}\left\|w_{\kappa}^{s}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} .
\end{aligned}
$$

We compute the terms involving $w_{\kappa}^{s}$ by using the explicit formula (28) and the expansion of stokeslet (14). Remarking that for $N>N_{0}$ the distance between $h_{j}^{N}$ and $B_{\infty}\left(h_{i}^{N}, 2 / N\right)$ is larger than $d_{\min }^{N} / 2$ (for arbitrary $j \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}$ ) and recalling that there are at most $M_{\kappa}^{N}$ indices in $\mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}$ we derive the bound:

$$
\left|w_{\kappa}^{s}(x)\right| \lesssim \frac{M_{\kappa}^{N}}{N d_{\min }^{N}}\|w\|_{W^{1, \infty}}, \quad\left|\nabla w_{\kappa}^{s}(x)\right| \lesssim \frac{M_{\kappa}^{N}}{N\left|d_{\min }^{N}\right|^{2}}\|w\|_{W^{1, \infty}}, \quad \forall x \in B_{\infty}\left(h_{i}^{N}, 2 / N\right)
$$

and consequently:

$$
\begin{aligned}
\left\|\nabla w_{\kappa}^{s}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} & \lesssim \frac{\left|M_{\kappa}^{N}\right|^{2}}{N^{5}\left|d_{m i n}^{N}\right|^{4}}\|w\|_{W^{1, \infty}}^{2} \lesssim \frac{\left|M^{\infty}\right|^{2}}{N}\|w\|_{W^{1, \infty}}^{2} \\
N^{2}\left\|w_{\kappa}^{s}\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)} & \lesssim \frac{\left|M_{\kappa}^{N}\right|^{2}}{N^{3}\left|d_{m i n}^{N}\right|^{N}}\|w\|_{W^{1, \infty}}^{2} \lesssim \frac{\left|M^{\infty}\right|^{2}}{N}\|w\|_{W^{1, \infty}}^{2}
\end{aligned}
$$

where we applied $N d_{m i n}^{N} \geqslant 4$ and (27). For the remainder terms, we apply again Proposition 5 yielding:

$$
\left\|\nabla\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}^{2} \lesssim \frac{M_{\kappa}^{N}}{N}\left(\frac{1}{N}+\sqrt{\frac{M_{\kappa}^{N}}{N d_{m}^{\kappa}}}\right)^{2}\|w\|_{W^{1, \infty}}^{2} \lesssim \frac{\left|M^{\infty}\right|^{2}}{N}\|w\|_{W^{1, \infty}}^{2}
$$

and, by combining Hölder inequality together with the bound in $L^{6}\left(T_{\kappa}^{N}\right)$ obtained in Proposition 5:

$$
\begin{aligned}
N^{2}\left\|\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2} & \leqslant N^{2}\left|B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right|^{\frac{2}{3}}\left\|\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{6}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right) \cap T_{\kappa}^{N}\right)}^{2} \\
& \lesssim\left\|\left(\bar{w}_{\kappa}-w_{\kappa}^{s}\right)\right\|_{L^{6}\left(T_{\kappa}^{N} \backslash \cup_{j \in \mathcal{I}_{\kappa}^{N} \backslash z_{\delta}^{N}}^{2} B_{j}^{N}\right)} \\
& \lesssim \frac{M_{\kappa}^{N}}{N}\left(\frac{1}{N}+\sqrt{\frac{M_{\kappa}^{N}}{N d_{m}^{k}}}\right)^{2}\|w\|_{W^{1, \infty}}^{2} \lesssim \frac{\left|M^{\infty}\right|^{2}}{N}\|w\|_{W^{1, \infty}}^{2} .
\end{aligned}
$$

Gathering these computations and applying (34), we obtain that for $N>N_{\delta}$ :

$$
\begin{aligned}
& \sum_{i \in \mathcal{Z}_{\delta}^{N}} \frac{1}{N}\|w\|_{W^{1, \infty}}^{2}+N^{2}\|\bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2}+\|\nabla \bar{w}\|_{L^{2}\left(B_{\infty}\left(h_{i}^{N}, 2 / N\right)\right)}^{2} \\
& \lesssim \frac{1}{\delta}\|w\|_{W^{1, \infty}}^{2}\left|M^{\infty}\right|^{2}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)
\end{aligned}
$$

so that:

$$
\begin{equation*}
\left|E_{2}\right| \lesssim \frac{M^{\infty}}{\sqrt{\delta}}\|w\|_{W^{1, \infty}}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)^{\frac{3}{2}} \tag{35}
\end{equation*}
$$

Combining (33) and (35) in (32), we obtain the expected result.

## 5. Proof of Theorem 1 - Asymptotics $N \rightarrow \infty$

In this section, we end the proof of Theorem 1 keeping the notations introduced in the previous section. A straightforward corollary of Proposition 7 reads:
Corollary 8. There exists $K \in(0, \infty)$ such that for arbitrary $\delta \geqslant 4$, there holds:

$$
\limsup _{N \rightarrow \infty}\left|\int_{\Omega} \nabla u^{N}: \nabla w-\sum_{\kappa \in \mathcal{I}^{N}} \int_{T_{\hbar}^{N}} \nabla u^{N}: \nabla w^{s}\right| \leqslant \frac{K}{\sqrt{\delta}}
$$

So in this section, we prove the following proposition:

Proposition 9. There exists $K \in(0, \infty)$ such that, for arbitrary $\delta \geqslant 4$, there holds:

$$
\limsup _{N \rightarrow \infty}\left|\sum_{\kappa \in \mathcal{I}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w^{s}-6 \pi \int_{\Omega}(j-\rho \bar{u}) \cdot w\right| \leqslant \frac{K}{\sqrt{\delta}} .
$$

This will end the proof of Theorem 1. Indeed, combining the above corollary and proposition, we obtain that there exists $K$ which does not depend on $\delta$ such that, for arbitrary $\delta \geqslant 4$ :

$$
\limsup _{N \rightarrow \infty}\left|\int_{\Omega} \nabla u^{N}: \nabla w-6 \pi \int_{\Omega}(j-\rho \bar{u}) \cdot w\right| \leqslant \frac{K}{\sqrt{\delta}} .
$$

As

$$
\lim _{N \rightarrow \infty} \int_{\Omega} \nabla u^{N}: \nabla w=\int_{\Omega} \nabla \bar{u}: \nabla w
$$

and $\delta$ can be made arbitrary large, this entails that

$$
\int_{\Omega} \nabla \bar{u}: \nabla w=6 \pi \int_{\Omega}(j-\rho \bar{u}) \cdot w
$$

and we obtain that $\bar{u}$ satisfies (B3).
We give now a proof of Proposition 9. From now on $\delta$ is fixed larger than 4 and we assume, with the conventions of the previous section, that:

$$
N \geqslant \max \left(N_{0}, N_{w}, N_{\delta}\right) .
$$

For such a $N$, we denote:

$$
\tilde{I}^{N}=\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w^{s}=\sum_{\kappa \in \mathcal{K}^{N}} \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w_{\kappa}^{s} .
$$

First, let fix $\kappa \in \mathcal{K}^{N}$ and simplify

$$
\tilde{I}_{\kappa}^{N}:=\int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w_{\kappa}^{s} .
$$

By definition, we have that:

$$
w_{\kappa}^{s}(x)=\sum_{i \in \mathcal{I}_{k}^{N} \backslash \mathcal{Z}_{\delta}^{N}} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right), \quad \forall x \in \mathbb{R}^{3}
$$

so that, introducing the associated pressures $x \mapsto P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)$, we obtain (recall that $u^{N}$ is divergence-free and constant on the $\left.B_{i}^{N}\right)$ :

$$
\begin{aligned}
\tilde{I}_{\kappa}^{N}= & \int_{T_{\kappa}^{N}} \nabla u^{N}: \nabla w_{\kappa}^{s}, \\
= & \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \int_{T_{\kappa}^{N} \backslash B_{i}^{N}} \nabla u^{N}(x):\left[\nabla U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) \mathbb{I}_{3}\right] \mathrm{d} x, \\
= & \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left(\int_{\partial B_{i}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot v_{i}^{N} \mathrm{~d} \sigma\right. \\
& \left.+\int_{\partial T_{\kappa}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot u^{N}(x) \mathrm{d} \sigma\right), \\
= & \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} I_{i, \text { int }}^{N}+I_{i, e x t}^{N},
\end{aligned}
$$

where, we denoted:

$$
\begin{aligned}
& I_{i, i n t}^{N}=\int_{\partial B_{i}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot v_{i}^{N} \mathrm{~d} \sigma, \\
& I_{i, e x t}^{N}:=\int_{\partial T_{\hbar}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot u^{N}(x) \mathrm{d} \sigma .
\end{aligned}
$$

Recalling that $\left(U^{N}, P^{N}\right)$ is the solution to the Stokes problem in the exterior of a ball of radius $1 / N$, and that $v_{i}^{N}$ is constant on $\partial B_{i}^{N}$, we have an explicit value for the interior integral whatever the value of the index $i$ (see (15)):

$$
I_{i, i n t}^{N}=\frac{6 \pi}{N} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}
$$

For the other term, we apply that the diameter of $T_{\kappa}^{N}$ is small so that we may approximate $u^{N}$ on $\partial T_{\kappa}^{N}$ by a constant. Namely, we choose:

$$
\bar{u}_{\kappa}^{N}=\frac{1}{\left|\left[T_{\kappa}^{N}\right]_{2 \delta}\right|} \int_{\left[T_{\kappa}^{N}\right]_{2 \delta}} u^{N}(x) \mathrm{d} x
$$

where $\left[T_{\kappa}^{N}\right]_{2 \delta}$ is the $1 /\left(2 \delta N^{1 / 3}\right)$ neighborhood of $\partial T_{\kappa}^{N}$ inside $\grave{T}_{\kappa}^{N}$. At this point, we remark that we have actually two notations for the same quantity. Indeed, a simple draw shows that introducing $x_{\kappa}^{N}$ the center of $T_{\kappa}^{N}$, we have:

$$
\stackrel{\circ}{T}_{\kappa}^{N}=B_{\infty}\left(x_{\kappa}^{N}, \frac{1}{2 N^{1 / 3}}\right) \quad \text { while } \quad\left[T_{\kappa}^{N}\right]_{2 \delta}=A\left(x_{\kappa}^{N}, \frac{1-1 / \delta}{2 N^{1 / 3}}, \frac{1}{2 N^{1 / 3}}\right) .
$$

So, we replace:

$$
\begin{aligned}
I_{i, e x t}^{N}= & \left.\int_{\partial T_{\kappa}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot \bar{u}_{\kappa}^{N} \mathrm{~d} \sigma\right) \\
& +\int_{\partial T_{\kappa}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \cdot\left(u^{N}(x)-\bar{u}_{\kappa}^{N}\right) \mathrm{d} \sigma
\end{aligned}
$$

For the first term on the right-hand side of this last identity, we apply that the flux through hypersurfaces of the normal stress tensor is conserved by solutions to the Stokes problem so that, applying (15), we have:

$$
\begin{aligned}
\int_{\partial T_{\kappa}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right](x\right. & \left.\left.\left.-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \mathrm{~d} \sigma\right) \\
& =-\int_{\partial B_{i}^{N}}\left\{\partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) n\right\} \mathrm{d} \sigma \\
& =-\frac{6 \pi}{N} w\left(h_{i}^{N}\right) .
\end{aligned}
$$

Finally, we obtain:

$$
\begin{equation*}
\tilde{I}_{\kappa}^{N}=\frac{6 \pi}{N} \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left(w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}\right)+E r r_{\kappa} \tag{36}
\end{equation*}
$$

with:

$$
\operatorname{Err}_{\kappa}=\int_{\partial T_{\kappa}^{N}}\left\{\sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \partial_{n} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right)-P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right) n\right\} \cdot\left(u^{N}-\bar{u}_{\kappa}^{N}\right) \mathrm{d} \sigma
$$

We control this error term with the following lemma:
Lemma 10. There exists a constant $C_{\delta}$ depending only on $\delta$ such that,

$$
\left|E r r_{\kappa}\right| \leqslant \frac{C_{\delta}}{N^{\frac{5}{6}}}\left\|\nabla u^{N}\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}, \quad \forall \kappa \in \mathcal{K}^{N}
$$

Proof. For $N>\max \left(N_{0}, N_{w}, N_{\delta}\right)$, we have that

$$
\left[T_{N}^{\kappa}\right]_{2 \delta} \subset T_{\kappa}^{N} \backslash \bigcup_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \overline{B_{i}^{N}}
$$

Indeed, $B_{i}^{N}=B\left(h_{i}^{N}, 1 / N\right)$ and, for $i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}$ we have that $h_{i}^{N}$ is $1 /\left(\delta N^{1 / 3}\right)$ far from $\partial T_{\kappa}^{N}$. These centers are thus $1 /\left(2 \delta N^{1 / 3}\right)$ far from $\left[T_{N}^{\kappa}\right]_{2 \delta}$ which is larger than $1 / N$ since $N>(4 \delta)^{3 / 2}$. In particular all the stokeslets in $w_{\kappa}^{s}$ satisfy:

$$
\left\{\begin{align*}
\Delta U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right)-\nabla P^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) & =0,  \tag{37}\\
\operatorname{div} U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(x-h_{i}^{N}\right) & =0,
\end{align*} \quad \text { on }\left[T_{N}^{\kappa}\right]_{2 \delta} .\right.
$$

Consequently, we split

$$
\partial\left[T_{N}^{\kappa}\right]_{2 \delta}=\partial T_{\kappa}^{N} \cup \partial T_{\kappa, \delta}^{N}
$$

where

$$
\partial T_{\kappa, \delta}^{N}=\left\{x \in T_{\kappa}^{N} \text { s.t. } \operatorname{dist}\left(x, \partial T_{\kappa}^{N}\right)=1 /\left(2 \delta N^{1 / 3}\right)\right\}
$$

We remark then that for any divergence-free $v \in H^{1}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)$ satisfying

$$
\begin{cases}v=u^{N}-\bar{u}_{\kappa}^{N}, & \\ \text { on } \partial T_{\kappa}^{N}, \\ v=0, & \\ \text { on } \partial T_{\kappa, \delta}^{N},\end{cases}
$$

integrating by parts $E r r_{\kappa}$ and applying (37), we have:

$$
E r r_{\kappa}=\int_{\left[T_{\kappa}^{N}\right]_{2 \delta}}\left\{\sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} \nabla U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right)\right\}: \nabla v
$$

so that:

$$
\begin{equation*}
\left|E r r_{\kappa}\right| \leqslant\left\{\sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left\|\nabla U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right)\right\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)}\right\}\|\nabla v\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} \tag{38}
\end{equation*}
$$

Let choose a suitable $v$ in order to apply this estimate. We recall that we introduced $x_{\kappa}^{N}$ the center of $T_{\kappa}^{N}$ and that we remarked that

$$
T_{\kappa}^{N}=B_{\infty}\left(x_{\kappa}^{N}, \frac{1}{2 N^{1 / 3}}\right), \quad\left[T_{\kappa}^{N}\right]_{2 \delta}=A\left(x_{\kappa}^{N}, \frac{(1-1 / \delta)}{2 N^{1 / 3}}, \frac{1}{2 N^{1 / 3}}\right)
$$

So, we introduce $\zeta_{\delta} \in C^{\infty}\left(\mathbb{R}^{3}\right)$ such that

$$
\zeta_{\delta}(x)=0 \text { in } B_{\infty}\left(0, \frac{1-1 / \delta}{2}\right) \quad \text { and } \quad \zeta_{\delta}(x)=1 \text { outside } B_{\infty}\left(0, \frac{1}{2}\right)
$$

and we set

$$
\begin{aligned}
v(x)=\zeta_{\delta}\left(N^{1 / 3}( \right. & \left.\left.x-x_{\kappa}^{N}\right)\right)\left(u^{N}(x)-\bar{u}_{\kappa}^{N}\right) \\
& \quad-\mathfrak{B}_{x_{\kappa}^{N},(1-1 / \delta) /\left(2 N^{1 / 3}\right), 1 /\left(2 N^{1 / 3}\right)}\left[x \mapsto\left(u^{N}(x)-\bar{u}_{\kappa}^{N}\right) \cdot \nabla\left[\zeta_{\delta}\left(N^{1 / 3}\left(x-x_{\kappa}^{N}\right)\right)\right]\right] .
\end{aligned}
$$

Again $v$ is well-defined as one shows by direct computations that the argument of the Bogovskii operator has mean zero on $A\left(x_{\kappa}^{N},(1-1 / \delta) /\left(2 N^{1 / 3}\right), 1 /\left(2 N^{1 / 3}\right)\right)$. Applying Lemma [15, we have then that there exists a constant $C_{\delta}$ depending only on $\delta$ for which:

$$
\|\nabla v\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} \leqslant C_{\delta}\left[\left\|\nabla u^{N}\right\|_{L^{2}\left(\left[T_{k}^{N}\right]_{2 \delta}\right)}+N^{\frac{1}{3}}\left\|u^{N}(x)-\bar{u}_{\kappa}^{N}\right\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)}\right] .
$$

Here we note that the $\bar{u}_{\kappa}^{N}$ is exactly the mean of $u^{N}$ on $\left[T_{\kappa}^{N}\right]_{2 \delta}$. Consequently, applying the Poincaré-Wirtinger inequality in the annulus $\left[T_{\kappa}^{N}\right]_{2 \delta}$ with the remark on the best constant as in Lemma 13 we obtain finally that:

$$
\begin{equation*}
\|\nabla v\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} \leqslant C_{\delta}\left\|\nabla u^{N}\right\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} \tag{39}
\end{equation*}
$$

As for the stokeslet, we make again the remark that for any $i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}$ the minimum distance between $h_{i}^{N}$ and $\left[T_{\kappa}^{N}\right]_{2 \delta}$ is larger than $1 /\left(2 \delta N^{1 / 3}\right)$. Hence, applying the expansion (14) of the stokeslet $U^{N}\left[w\left(h_{i}^{N}\right)\right]$ we obtain that

$$
\begin{aligned}
\left\|\nabla U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right)\right\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} & \leqslant\left(\int_{1 /\left(2 \delta N^{1 / 3}\right)}^{\infty} \frac{\mathrm{d} r}{N^{2} r^{2}}\right)^{\frac{1}{2}}\left|w\left(h_{i}^{N}\right)\right| \\
& \leqslant \frac{\sqrt{2 \delta}}{N^{\frac{5}{6}}}\left|w\left(h_{i}^{N}\right)\right|
\end{aligned}
$$

This entails that:

$$
\begin{equation*}
\sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left\|\nabla U^{N}\left[w\left(h_{i}^{N}\right)\right]\left(\cdot-h_{i}^{N}\right)\right\|_{L^{2}\left(\left[T_{\kappa}^{N}\right]_{2 \delta}\right)} \leqslant \frac{\sqrt{2 \delta} M_{\kappa}^{N}}{N^{\frac{5}{6}}}\|w\|_{L^{\infty}} \tag{40}
\end{equation*}
$$

Combining (39) and (40) in (38) yields the expected result.
Summing (36) over $\kappa$, we obtain that:

$$
\begin{align*}
\tilde{I}^{N} & =\frac{6 \pi}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}}\left(w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}\right)+\operatorname{Err} \\
& =\frac{6 \pi}{N} \sum_{i \in \mathcal{I}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-\frac{6 \pi}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}+E r r . \tag{41}
\end{align*}
$$

where

$$
E r r=\sum_{\kappa \in \mathcal{K}^{N}} E r r_{\kappa}
$$

Hence, applying Lemma 10, a Cauchy-Schwarz inequality and remarking again that the $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ form a partition of a subset of $\Omega$ with a number of elements satisfying (26), we have:

$$
\begin{equation*}
|E r r| \leqslant C_{\delta} \sum_{\kappa \in \mathcal{K}^{N}} \frac{\left\|\nabla u^{N}\right\|_{L^{2}\left(T_{\kappa}^{N}\right)}}{N^{5 / 6}} \leqslant \frac{C_{\delta}}{N^{\frac{1}{3}}}\left\|\nabla u^{N}\right\|_{L^{2}(\Omega)} \leqslant \frac{C_{\delta} \mathcal{E}^{\infty}}{N^{\frac{1}{3}}} \tag{42}
\end{equation*}
$$

So the asymptotics of $\tilde{I}^{N}$ is given by the two first terms on the right-hand side of (41). We make precise these asymptotics in the two following lemmas:
Lemma 11. There exists a constant $K$ independent of $\delta$ for which:

$$
\limsup _{N \rightarrow \infty}\left|\frac{6 \pi}{N} \sum_{i \in \mathcal{I}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-6 \pi \int_{\Omega} j(x) \cdot w(x) \mathrm{d} x\right| \leqslant \frac{K}{\delta}
$$

Proof. As $w \in C_{c}^{\infty}(\Omega)$ and $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ is a covering of $\operatorname{Supp}(w)$ we have by assumption (A5) that:

$$
\int_{\Omega} j(x) \cdot w(x) \mathrm{d} x=\lim _{N \rightarrow \infty} \sum_{i=1}^{N} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}=\lim _{N \rightarrow \infty} \sum_{i \in \mathcal{I}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}
$$

Hence, our proof reduces to find a uniform bound on

$$
\sum_{i \in \mathcal{I}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}-\sum_{i \in \mathcal{I}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}=\sum_{i \in \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N} .
$$

However, for large $N$, there holds:

$$
\left|\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}\right| \leqslant\left(\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left|v_{i}^{N}\right|^{2}\right)^{\frac{1}{2}}\left(\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left|w\left(h_{i}^{N}\right)\right|^{2}\right)^{\frac{1}{2}}
$$

Here, we apply (25) that has guided our choice for the covering $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ :

$$
\begin{aligned}
\left(\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left|v_{i}^{N}\right|^{2}\right) & \leqslant \frac{12}{\delta}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right) \\
\left(\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}}\left|w\left(h_{i}^{N}\right)\right|^{2}\right) & \leqslant \frac{12}{\delta}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)\|w\|_{L^{\infty}}^{2}
\end{aligned}
$$

Combining these two estimates, we obtain:

$$
\limsup _{N \rightarrow \infty}\left|\frac{1}{N} \sum_{i \in \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot v_{i}^{N}\right| \leqslant \frac{12}{\delta}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)\|w\|_{L^{\infty}}
$$

Lemma 12. There exists a constant $K$ independent of $\delta$ for which:

$$
\limsup _{N \rightarrow \infty}\left|\frac{6 \pi}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}-6 \pi \int_{\Omega} \rho(x) \bar{u}(x) \cdot w(x) \mathrm{d} x\right| \leqslant \frac{K}{\sqrt{\delta}}\|w\|_{L^{\infty}}
$$

Proof. As in the previous proof, let first complete the sum by reintroducing the $\mathcal{Z}_{\delta}^{N}$ indices:

$$
\begin{equation*}
\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N} \backslash \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}=\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}+\tilde{E} r r^{N} \tag{43}
\end{equation*}
$$

where:

$$
\tilde{E} r r^{N}=\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N} \cap \mathcal{Z}_{\delta}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N} .
$$

For the first term on the right-hand side of (43), we remark that:

$$
\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}=\left(1-\left(1-\frac{1}{\delta}\right)^{3}\right)^{-1} \sum_{\kappa \in \mathcal{K}^{N}} \int_{\left[T_{\kappa}^{N}\right]_{2 \delta}}\left(\sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right)\right) \cdot u^{N}
$$

So, we introduce:

$$
\sigma^{N}=\left(1-\left(1-\frac{1}{\delta}\right)^{3}\right)^{-1} \sum_{\kappa \in \mathcal{K}^{N}}\left(\sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right)\right) \mathbf{1}_{\left[T_{\kappa}^{N}\right]_{2 \delta}},
$$

for which:

$$
\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{u}_{\kappa}^{N}=\int_{\Omega} \sigma^{N}(x) \cdot u^{N}(x) \mathrm{d} x
$$

On the one-hand, we note that:

$$
\left\|\sigma^{N}\right\|_{L^{1}(\Omega)} \leqslant \frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} M_{\kappa}^{N}\|w\|_{L^{\infty}}
$$

where $\sum_{\kappa \in \mathcal{K}^{N}} M_{\kappa}^{N} \leqslant N$, so that:

$$
\left\|\sigma^{N}\right\|_{L^{1}(\Omega)} \leqslant\|w\|_{L^{\infty}}
$$

Complementarily, because of assumption ( $\overline{\mathrm{A} 3}$ ), we also have :

$$
\begin{aligned}
\left\|\sigma^{N}\right\|_{L^{\infty}(\Omega)} & \leqslant\left(1-\left(1-\frac{1}{\delta}\right)^{3}\right)^{-1} \sup _{\kappa \in \mathcal{K}^{N}} M_{\kappa}^{N}\|w\|_{L^{\infty}} \\
& \leqslant\left(1-\left(1-\frac{1}{\delta}\right)^{3}\right)^{-1} M^{\infty}\|w\|_{L^{\infty}}
\end{aligned}
$$

and $\sigma^{N}$ is bounded in all $L^{q}$-spaces.
On the other hand, for any $v \in C_{c}^{\infty}(\Omega)$ we have

$$
\int_{\Omega} \sigma^{N}(x) \cdot v(x) \mathrm{d} x=\frac{1}{N} \sum_{\kappa \in \mathcal{K}^{N}} \sum_{i \in \mathcal{I}_{\kappa}^{N}} w\left(h_{i}^{N}\right) \cdot \bar{v}_{\kappa}^{N}
$$

with

$$
\bar{v}_{\kappa}^{N}=\frac{1}{\left|\left[T_{N}^{\kappa}\right]_{2 \delta}\right|} \int_{\left[T_{N}^{\kappa}\right]_{2 \delta}} v(x) \mathrm{d} x
$$

We remark that, for any $i \in \mathcal{I}_{\kappa}^{N}, h_{i}^{N}$ is inside $T_{\kappa}^{N}$ whose diameter is $1 / N^{1 / 3}$. This entails:

$$
\left|\bar{v}_{\kappa}^{N}-v\left(h_{i}^{N}\right)\right| \lesssim \frac{1}{N^{1 / 3}}\|\nabla v\|_{L^{\infty}} .
$$

Gathering these identities for all indices $i$ in all the cubes $T_{\kappa}^{N}$, we infer :

$$
\left|\int_{\Omega} \sigma^{N}(x) \cdot v(x) \mathrm{d} x-\frac{1}{N} \sum_{i \in \mathcal{I}^{N}} w\left(h_{i}^{N}\right) \cdot v\left(h_{i}^{N}\right)\right| \lesssim \frac{1}{N^{1 / 3}}\|\nabla v\|_{L^{\infty}}\|w\|_{L^{\infty}} .
$$

Consequently, assumption (A4) implies that:

$$
\lim _{N \rightarrow \infty} \int_{\Omega} \sigma^{N}(x) \cdot v(x) \mathrm{d} x=\int_{\Omega} \rho(x) w(x) \cdot v(x) \mathrm{d} x
$$

and $\sigma^{N} \rightharpoonup \rho w$ weakly in $L^{q}(\Omega)$ for arbitrary $q \in(1, \infty)$. Combining then the weak convergence of $\sigma^{N}$ in $L^{2}(\Omega)$ and the strong convergence of $u^{N}$ in $L^{2}(\Omega)$ (up to the extraction of a subsequence), we have:

$$
\lim _{N \rightarrow \infty} \int_{\Omega} \sigma^{N} \cdot u^{N}=\int_{\Omega} \rho w \cdot \bar{u}
$$

As for the remainder term, we introduce:

$$
\tilde{\sigma}^{N}=\left(1-\left(1-\frac{1}{\delta}\right)^{3}\right)^{-1} \sum_{\kappa \in \mathcal{K}^{N}}\left(\sum_{i \in \mathcal{I}_{\kappa}^{N} \cap \mathcal{Z}_{\delta}^{N}}\left|w\left(h_{i}^{N}\right)\right|\right) \mathbf{1}_{\left[T_{\kappa}^{N}\right]_{2 \delta}} .
$$

so that:

$$
\left|\tilde{E} r r^{N}\right| \leqslant \int_{\Omega} \tilde{\sigma}^{N}(x)\left|u^{N}(x)\right| \mathrm{d} x
$$

With similar arguments as in the previous computations, we have, applying (25):

$$
\left\|\tilde{\sigma}^{N}\right\|_{L^{1}(\Omega)} \leqslant \frac{1}{N} \# \mathcal{Z}_{\delta}^{N}\|w\|_{L^{\infty}} \leqslant \frac{1}{\delta}\|w\|_{L^{\infty}}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)
$$

Furthermore, we have:

$$
\left\|\tilde{\sigma}^{N}\right\|_{L^{\infty}(\Omega)} \lesssim \delta M^{\infty}\|w\|_{L^{\infty}}
$$

Consequently, by interpolation, we obtain:

$$
\left\|\tilde{\sigma}^{N}\right\|_{L^{4 / 3}(\Omega)} \lesssim \frac{\left|M^{\infty}\right|^{1 / 4}}{\sqrt{\delta}}\|w\|_{L^{\infty}}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)^{\frac{3}{4}}
$$

As $u^{N}$ is bounded in $L^{4}(\Omega)$ by sobolev embedding, this yields that:

$$
\left|\tilde{E} r r^{N}\right| \lesssim \frac{\left|M^{\infty}\right|^{1 / 4}}{\sqrt{\delta}}\|w\|_{L^{\infty}}\left(1+\left|\mathcal{E}^{\infty}\right|^{2}\right)^{\frac{7}{4}}, \quad \forall N \in \mathbb{N}
$$

and there exists a constant $K$ depending only on $\mathcal{E}^{\infty}, M^{\infty}$ and $\|w\|_{L^{\infty}}$ for which:

$$
\limsup _{N \rightarrow \infty}\left|\tilde{E} r r^{N}\right| \leqslant \frac{K}{\sqrt{\delta}}
$$

This ends the proof.

## Appendix A. Auxiliary technical lemmas

We recall here several standard lemmas that help in the above proofs.
First, we recall the Poincaré-Wirtinger inequality [7, Theorem II.5.4] which states that for arbitrary lipschitz domain $\mathcal{F}$, there holds:

$$
\left\|u-\frac{1}{|\mathcal{F}|} \int_{\mathcal{F}} u(x) \mathrm{d} x\right\|_{L^{2}(\mathcal{F})} \leqslant C_{P W}\|\nabla u\|_{L^{2}(\mathcal{F})}
$$

We extensively use this inequality when $\mathcal{F}$ is an annulus. In this case, a standard scaling argument entails the following remark on the constant $C_{P W}$ :

Lemma 13. Given $(x, \lambda, a) \in \mathbb{R}^{3} \times(0, \infty) \times(0,1)$ there exists a constant $C_{a}$ depending only on a (and expecially not on $(x, \lambda)$ ) for which :

$$
\left\|u-\frac{1}{|A(x, a \lambda, \lambda)|} \int_{A(x, a \lambda, \lambda)} u(x) \mathrm{d} x\right\|_{L^{2}(A(x, a \lambda, \lambda))} \leqslant C_{a} \lambda\|\nabla u\|_{L^{2}(A(x, a \lambda, \lambda))}
$$

Second, we focus on the properties of the Bogovskii operators $\mathfrak{B}$. This means we are interested in solving the divergence problem:

$$
\begin{equation*}
\operatorname{div} v=f, \quad \text { on } \mathcal{F}, \tag{44}
\end{equation*}
$$

whose data is $f$ and unknown is $v$. We recall the result due to M.E. Bogovskii (see [7, Theorem III.3.1]):

Lemma 14. Let $\mathcal{F}$ be a lipschitz bounded domain in $\mathbb{R}^{3}$. Given $f \in L^{2}(\mathcal{F})$ such that

$$
\int_{\mathcal{F}} f(x) \mathrm{d} x=0
$$

there exists a solution $v:=\mathfrak{B}_{\mathcal{F}}[f] \in H_{0}^{1}(\mathcal{F})$ to (44) such that

$$
\|\nabla v\|_{L^{2}(\mathcal{F})} \leqslant C\|f\|_{L^{2}(\mathcal{F})}
$$

with a constant $C$ depending only on $\mathcal{F}$.
In the case of annuli, the above result yields the following lemma by a standard scaling argument:

Lemma 15. Let $(x, \lambda, a) \in \mathbb{R}^{3} \times(0, \infty) \times(0,1)$. Given $f \in L^{2}(A(x, a \lambda, \lambda))$ such that

$$
\int_{\mathcal{F}} f(x) \mathrm{d} x=0
$$

there exists a solution $v:=\mathfrak{B}_{x, a \lambda, \lambda}[f] \in H_{0}^{1}(A(x, a \lambda, \lambda))$ to (44) such that

$$
\|\nabla v\|_{L^{2}(A(x, a \lambda, \lambda))} \leqslant C_{a}\|f\|_{L^{2}(A(x, a \lambda, \lambda))}
$$

with a constant $C_{a}$ depending only on a (and especially neither on $f$ nor on $(x, \lambda)$ ).

## Appendix B. Proof of a covering lemma

This appendix is devoted to the construction of coverings that are adapted to the empiric measures $S_{N}$. We prove the following general lemma:

Lemma 16. Let $(N, d) \in\left[\mathbb{N}^{*}\right]^{2}, d \geqslant 2$, and $\mu \in \mathcal{M}_{+}\left(\mathbb{R}^{3}\right)$ a positive bounded measure. There exists $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathbb{Z}^{3}}$ a covering of $\mathbb{R}^{3}$ with disjoint cubes of width $1 / N^{1 / 3}$ such that denoting

$$
\mathcal{C}_{d}^{N}:=\left\{x \in \mathbb{R}^{3} \text { s.t. } \operatorname{dist}\left(x, \bigcup_{\kappa \in \mathbb{Z}^{3}} \partial T_{\kappa}^{N}\right)<\frac{1}{(d+1) N^{1 / 3}}\right\}
$$

there holds

$$
\begin{equation*}
\mu\left(\mathcal{C}_{d}^{N}\right) \leqslant \frac{6}{d} \mu\left(\mathbb{R}^{3}\right) \tag{45}
\end{equation*}
$$

In Section 4, we apply the previous lemma with $N \in \mathbb{N}^{*}, d=\delta-1$ and

$$
\mu:=\frac{1}{N} \sum_{i=1}^{N}\left(1+\left|v_{i}^{N}\right|^{2}\right) \delta_{h_{i}^{N}},
$$

to obtain a covering $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathbb{Z}^{3}}$ satisfying (25). Assuming then $N \geqslant\left[\operatorname{dist}\left(S u p p w, \mathbb{R}^{3} \backslash\right.\right.$ $\Omega) / 4]^{-3}$, we obtain that the subcovering $\left(T_{\kappa}^{N}\right)_{\kappa \in \mathcal{K}^{N}}$ containing only the cubes that intersect $\operatorname{Supp}(w)$ is made of cubes $T_{\kappa}^{N}$ that are included in the $1 / N^{1 / 3}$ neighborhood of $\operatorname{Supp}(w)$ (as $T_{\kappa}^{N}$ has diameter $1 / N^{1 / 3}$ ). By direct computations, we obtain then that, for $\kappa \in \mathcal{K}^{N}$, the distance between $T_{\kappa}^{N}$ and $\mathbb{R}^{3} \backslash \Omega$ is strictly positive so that $T_{\kappa}^{N} \subset \Omega$.

Proof. By a standard scaling argument, it suffices to prove the result for $N=1$. Let $d \geqslant 2$. First, for arbitrary $k=\left(k_{1}, k_{2}, k_{3}\right) \in \mathbb{Z}^{3}$ we set:

$$
\tilde{T}_{k}=\left[\frac{k_{1}}{d}, \frac{k_{1}+1}{d}\left[\times\left[\frac{k_{2}}{d}, \frac{k_{2}+1}{d}\left[\times\left[\frac{k_{3}}{d}, \frac{k_{3}+1}{d}[\right.\right.\right.\right.\right.
$$

These cubes with tildas and index $k$ are cubes of width $1 / d$. We call them "small cubes." It is straightforward that $\left(\tilde{T}_{k}\right)_{k \in \mathbb{Z}^{3}}$ forms a partition of $\mathbb{R}^{3}$. For arbitrary

$$
\kappa=\left(k_{1}, k_{2}, k_{3}\right)+\{0, \ldots, d-1\}^{3},
$$

we set then:

$$
T_{\kappa}=\bigcup_{k \in \kappa} \tilde{T}_{k}=\left[\frac{k_{1}}{d}, \frac{k_{1}}{d}+1\left[\times\left[\frac{k_{2}}{d}, \frac{k_{2}}{d}+1\left[\times\left[\frac{k_{3}}{d}, \frac{k_{3}}{d}+1[.\right.\right.\right.\right.\right.
$$

These cubes without tildas and with index $\kappa$ are cubes of width 1 . We call them "large cubes". We introduce then the $1 / d$-neighborhood of the boundary of this large cube:

$$
\left[T_{\kappa}\right]_{d}:=\bigcup_{k \in \partial \kappa} \tilde{T}_{k}
$$

where

$$
\begin{aligned}
\partial \kappa= & \left\{k \in\left\{k_{1}, k_{1}+d-1\right\} \times\left\{k_{2}, \ldots, k_{2}+d-1\right\} \times\left\{k_{3}, \ldots, k_{3}+d-1\right\}\right\} \\
& \cup\left\{k \in\left\{k_{1}, \ldots, k_{1}+d-1\right\} \times\left\{k_{2}, k_{2}+d-1\right\} \times\left\{k_{3}, \ldots, k_{3}+d-1\right\}\right\} \\
& \cup\left\{k \in\left\{k_{1}, \ldots, k_{1}+d-1\right\} \times\left\{k_{2}, \ldots, k_{2}+d-1\right\} \times\left\{k_{3}, k_{3}+d-1\right\}\right\}
\end{aligned}
$$

(which means taking the small cubes whose indices are in the boundary of $\kappa$ ). We remark that we may split $\left[T_{k}\right]_{d}$ into 6 subsets corresponding to the top, bottom, left, right, front and back faces of the cube $T_{\kappa}$. For instance, the bottom face of $\left[T_{\kappa}\right]_{d}$ reads:

$$
\bigcup_{k \in\left\{k_{1}, \ldots, k_{1}+d-1\right\} \times\left\{k_{2}, \ldots, k_{2}+d-1\right\} \times\left\{k_{3}\right\}} \tilde{T}_{k}
$$

For arbitrary $k^{\ell}=\ell(1,1,1)$, with $\ell \in\{0, \ldots, d-1\}$ we also denote

$$
\mathcal{K}_{\ell}=\left\{\kappa=\left(k^{\ell}+\pi+\{0, \ldots, d-1\}^{3}\right), \quad \pi \in d \mathbb{Z}^{3}\right\}
$$

We emphasize that $\mathcal{K}_{\ell}$ is a set made of sets (corresponding to large cubes). Any set $\mathcal{K}_{\ell}$ corresponds to a partition of $\mathbb{Z}^{3}$ and then to a covering of $\mathbb{R}^{3}$ with disjoint large cubes.

Given $\ell \in\{0, \ldots, d-1\}$ we consider now

$$
\mathcal{C}_{d}^{\ell}=\left\{x \in \mathbb{R}^{3} \text { s.t. } \operatorname{dist}\left(x, \bigcup_{\kappa \in \mathcal{K}_{\ell}} \partial T_{\kappa}\right)<\frac{1}{(d+1) N^{1 / 3}}\right\} .
$$

We remark that, for fixed $\ell$ there holds:

$$
\mathcal{C}_{d}^{\ell} \subset \bigcup_{\kappa \in \mathcal{K}_{\ell}}\left[T_{\kappa}\right]_{d}
$$

We denote $\partial \mathcal{K}_{l}$ the set of indices $k$ such that $\tilde{T}_{k}$ contributes to this $1 / d$-neigborhood. Setting $\partial \mathcal{K}_{l}=\bigcup\left\{\partial \kappa, \kappa \in \mathcal{K}_{\ell}\right\}$, we have thus:

$$
\mathcal{C}_{d}^{\ell} \subset \bigcup_{k \in \partial \mathcal{K}_{l}} \tilde{T}_{k}
$$

We can decompose this union of small cubes by regrouping together the cubes that belong to left / right / top /bottom / front / back faces of large cubes. For instance, the indices $k$ of small cubes belonging to bottom faces of large cubes satisfy

$$
k \in \mathbb{Z}^{2} \times\{\ell+d \mathbb{Z}\} .
$$

For two different $\ell$ and $\ell^{\prime}$ in $\{0, \ldots, d-1\}$ the same index $k$ cannot belong to the bottom faces of two different cubes in the coverings $\mathcal{K}_{\ell}$ and $\mathcal{K}_{\ell^{\prime}}$ of $\mathbb{R}^{3}$. We have the same properties for top / right / left / front / back faces. Consequently, in the family of coverings $\left(\mathcal{K}_{\ell}\right)_{\ell \in\{0, \ldots, d-1\}}$ one small cube $\tilde{T}_{k}^{N}$ belongs at most once to a top / bottom / right / left / front / back face of a large cube so that:

$$
\begin{equation*}
\text { any } k \in \mathbb{Z}^{3} \text { belongs to at most } 6 \text { different } \partial \mathcal{K}_{l} . \tag{46}
\end{equation*}
$$

Let now introduce the measure $\mu$. For any $k \in \mathbb{Z}^{3}$, we denote:

$$
\tilde{\mu}_{k}=\mu\left(\tilde{T}_{k}\right)
$$

and we consider the sum:

$$
\text { Rem }:=\sum_{\ell \in\{0, \ldots, d-1\}} \mu\left(\mathcal{C}_{d}^{\ell}\right) .
$$

With the previous definitions, we have:

$$
R e m \leqslant \sum_{\ell \in\{0, \ldots, d-1\}} \sum_{k \in \partial \mathcal{K}_{\ell}} \tilde{\mu}_{k} .
$$

Because of (46), we have then that any $k \in \mathbb{Z}^{3}$ appears at most 6 times in this sum. Consequently:

$$
R e m \leqslant 6 \sum_{k \in \mathbb{Z}^{3}} \tilde{\mu}_{k} \leqslant 6 \mu\left(\mathbb{R}^{3}\right) .
$$

The measure $\mu$ being positive, this implies that one of the terms in the sum defining Rem is less than $R e m / d$. In other words, there exists at least one $\ell^{0} \in\{0, \ldots, d-1\}$ such that:

$$
\mu\left(\mathcal{C}_{d}^{\ell^{0}}\right) \leqslant \frac{6}{d} \mu\left(\mathbb{R}^{3}\right) .
$$

The covering $\left(T_{\kappa}\right)_{\kappa \in \mathcal{K}_{\ell 0}}$ is then made of disjoint cubes of width 1 satisfying (45). We have obtained the required covering of $\mathbb{R}^{3}$.

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