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An algorithm which generates linear extensions for a non-simply-laced d-complete poset with uniform probability

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Abstract. The purpose of this paper is to present an algorithm which generates linear extensions for a non-simplylaced d-complete poset with uniform probability.

Résumé. Le but de ce papier est présenter un algorithme qui produit des extensions linéaires pour une non-simplylaced d-complete poset avec probabilité constante.

Keywords: d-complete posets, algorithm, linear extension, uniform generation

1 Introduction

In [7](Theorem 4.2), J. Stembridge classified irreducible minuscule elements of Kac-Moody Weyl group over a root system Φ into three classes below:

- \bullet Φ is simply-laced,
- \bullet Φ has the form 0 $\overline{O \cup_{1} O}$ \cdots $\overline{O \cup_{1} O}$ (namely, of type *B*), or • Φ has the form $\begin{array}{cc} 0 & \to & 0 \\ -m & -2 & -1 \end{array}$ $\overline{0 \quad 1}$ (we say *type* F_m , for simplicity).

In [5][6], the author and S. Okamura constracted an algorithm which generates reduced decompositions for a given minuscule element of simply-laced Weyl group with uniform probability. The algorithm in [6] is described in terms of graphs. Simply-laced minuscule elements are described as certain simple acyclic di-graphs. The transitive-closure of the graph is called a d-complete poset. Then, the reduced decompositions are identified with linear extensions of the graph. This algorithm gives a proof of the hook formula [1] for the number of reduced decompositions of a minuscule element in simply-laced case.

In this paper, we present an algorithm (algorithm A) in terms of graphs (See Section 2 for details). This algorithm is a generalization of an algorithm in [5][6]. We define a certain acyclic multi-di-graph corresponding to a minuscule element of type B (resp. type F_m) in Section 3 (resp. Section 4). Our

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main result (Theorem 5.1) is that the algorithm A generates linear extensions for a minuscule element of type B and F_m with uniform probability. More precisely, the probability the algorithm A generates linear extension L of a graph S is given by:

$$
\frac{\prod_{v \in S} (1 + \# \text{H}_S(v)^+)}{\# S!},\tag{1.1}
$$

where $H_S(v)^+$ is a certain subset of S (See Section 2 for detail). This (1.1) is independent from the choice of L . Hence, we get the hook formula for the number of linear extensions of a given shape S of type B and F_m . Namely, the number of linear extensions of a shape S is given by:

$$
\frac{\#S!}{\prod_{v\in S} (1+\#H_S(v)^+)}.
$$

In section 6, we give a Lie theoretical description of shape of type B and F_m .

2 An algorithm for a graph Γ

Let $\Gamma = (\Gamma; A, \rho, i)$ be a finite acyclic multi-di-graph, where A denotes the set of arrows of Γ, i(a) the sink of $a \in A$, and $o(a)$ the source of $a \in A$.

Definition 2.1 *Put* $d := \# \Gamma$. A bijection $L : \{1, \dots, d\} \longrightarrow \Gamma$ is said to be a linear extension of Γ if:

$$
L(k) = o(a) \text{ and } i(a) = L(l) \text{ implies } k > l, \quad k, l \in \{1, \cdots, d\}, \quad a \in A.
$$

The set of linear extensions of Γ *is denoted by* $\mathcal{L}(\Gamma)$ *.*

For a given $v \in \Gamma$, we define a set $H_{\Gamma}(v)^+$ by:

$$
H_{\Gamma}(v)^{+} := \{ a \in A(\Gamma) \mid v = o(a) \}.
$$

For a given Γ, we call the following algorithm the *algorithm* A *for* Γ:

GNW1. Set $i := 0$ and set $\Gamma_0 := \Gamma$.

- GNW2. (Now Γ_i has $d i$ nodes.) Set $j := 1$ and pick a node $v_1 \in \Gamma_i$ with the probability $1/(d i)$.
- GNW3. If $\#H_{\Gamma_i}(v_j)^+ \neq 0$, pick an arrow $a_{j+1} \in H_{\Gamma_i}(v_j)^+$ with the probability $1/\#H_{\Gamma_i}(v_j)^+$. If not, go to GNW5.

GNW4. Set $v_{j+1} := i(a_j)$. Set $j := j + 1$ and return to GNW3.

GNW5. (Now $\#H_{\Gamma_i}(v_j)^+=0$.) Set $L(i+1) := v_j$ and set $\Gamma_{i+1} := \Gamma_i \setminus v_j$ (the graph deleted v_j from Γ_i).

GNW6. Set $i := i + 1$. If $i < d$, return to GNW2; if $i = d$, terminate.

We note that the algorithm A stops in finite time since Γ is acyclic. By the definition of the algorithm A for Γ, the map $L : i \mapsto L(i)$ generated above is a linear extension of Γ. We denote by $\text{Prob}_{\Gamma}(L)$ the probability we get $L \in \mathcal{L}(\Gamma)$ by the algorithm A.

An algorithm which generates linear extensions for a non-simply-laced d-complete poset with uniform probability 657

3 Shapes of type B

We denote by $\mathbb N$ the set of non-negative integers. We define a set $\mathbb B$ by:

$$
\mathbb{B} := \{ (i, j) \in \mathbb{N} \times \mathbb{N} \mid i \leq j \}.
$$

The set $\mathbb B$ is depicted in FIGURE 3.1. We equip the $\mathbb B$ with the partial order:

$$
(i, j) \leq (i', j') \iff i \geq i' \text{ and } j \geq j'.
$$

Fig. 3.1: The set $\mathbb B$

Definition 3.1 *Let* S *be a finite order filter of* B*. We induce to* S *a graph structure by:*

$$
(i,j) \rightarrow (i',j') \quad \text{if and only if} \quad \left\{ \begin{array}{c} \text{``}i = j \text{ and } i' = i, j' > j \text{''}, \\ \text{``}i < j \text{ and } i' = i, j' > j \text{''}, \\ \text{``}i < j \text{ and } i' > i, j' = j \text{''}, \\ \text{or } \text{``}i < j \text{ and } i' = j, j' > i \text{''}, \\ (i,j) \rightrightarrows (i',j') \quad \text{if and only if} \quad \text{``}i < j \text{ and } i' = j' = j \text{''}, \end{array} \right.
$$

and there exists no other adjacency relation. Here, $v \to v'$ means there exists exactly one arrow from v *to* v' , and $v \rightrightarrows v'$ there exists exactly two arrows from v to v' . A graph S is called a shape of type B. See *FIGURE* 3.2 *for examples of* $H_S(v)^+$ *.*

Fig. 3.2: $H_S(u)^+$, $H_S(v)^+$, and $H_S(w)^+$.

Remark 3.2 *A shape of type* B *as poset is order-isomorphic to a shifted shape. Shifted shapes are also realized as d-complete posets over a root system of type* D*. The graph-structure of shapes of type* D *is described in [6] and compatible with notion of hooks (or called bars) of shifted shapes. The algorithm* A *depends not only on poset-structure but on graph-structure. Hence, we do not consider shapes of type* B *as shifted shapes.*

658 *Kento Nakada*

4 Shapes of type F_m ($m \ge 2$).

We denote by $\mathbb Z$ the set of integers. Let m be an integer greater than or equal to 2. We define a set $\mathbb F_m$ by:

$$
\mathbb{F}_m := \left\{ (i, j) \in \mathbb{N} \times \mathbb{Z} \middle| \begin{array}{l} i = 0 \text{ and } j \ge -m, \\ i = 1 \text{ and } j \ge 0, \text{ or} \\ 2 \le i \le m \text{ and } j = 0 \end{array} \right\}
$$

For example, the set \mathbb{F}_3 is depicted in FIGURE 4.1. We equip the \mathbb{F}_m with the partial order:

$$
(i,j) \le (i',j') \iff i \ge i' \text{ and } j \ge j'.
$$

Fig. 4.1: The set \mathbb{F}_3

Definition 4.1 Let S be a finite order filter of \mathbb{F}_m . We induce to S a graph structure by:

$$
(i,j) \rightarrow (i',j') \quad \text{if and only if} \quad \begin{cases} \begin{array}{c} \text{``i = 0, j \le -1 and } i' \neq -j, j' > j'', \\ \text{``i = 0, j = 0, and j' > 0'',} \\ \text{``i = 1, j = 0, and i' = 1, j' > 0'',} \\ \text{``i = 1, j = 0, and i' > 1, j' = 0'',} \\ \text{``i = 2, j = 0, and i' > i, j' = 0'',} \\ \text{``i \ge 2, j = 0, and i' > i, j' = 0'',} \\ \text{``j \ge 1 and i' = i, j' > j'',} \\ \text{or "j \ge 1 and i' > i, j' = j'',} \end{array} \\ (i,j) \Rightarrow (i',j') \quad \text{if and only if} \quad \text{``i = 0, j = 0, and 0 < i', j' = 0'',} \end{cases}
$$

and there exists no other adjacency relation. A graph S *is called a* shape of type Fm*. See FIGURE 4.2 for examples of* $H_S(v)^+$.

An algorithm which generates linear extensions for a non-simply-laced d-complete poset with uniform probability 659

5 Main result

Now, we can state the main theorem:

Theorem 5.1 Let S be a shape of type B or type F_m for some $m \geq 2$. Let $L \in \mathcal{L}(S)$. Then the algorithm A *for* S *generates* L *with the probability*

$$
Prob_S(L) = \frac{\prod_{v \in S} (1 + \# H_S(v)^+)}{\# S!}.
$$
\n(5.1)

.

Since the right hand side of (5.1) is independent from the choice of $L \in \mathcal{L}(S)$, we have: **Corollary 5.2** Let S be a shape of type B or type F_m for some $m \geq 2$. Then we have:

$$
\#\mathcal{L}(S) = \frac{\#S!}{\prod_{v \in S} (1 + \#H_S(v)^+)}
$$

6 Lie theoretical description of main result and Remarks

In this section, we fix a (not necessary simply-laced) Kac-Moody Lie algebra g with a simple root system $\Pi = \{ \alpha_i \mid \in I \}$. For all undefined terminology in this section, we refer the reader to [2] [3].

Definition 6.1 An integral weight λ is said to be pre-dominant if:

$$
\langle \lambda, \, \beta^{\vee} \rangle \ge -1 \quad \text{ for each } \beta^{\vee} \in \Phi^{\vee}_+,
$$

where $\Phi _{+}^{\vee }$ denotes the set of positive real coroots. The set of pre-dominant integral weights is denoted by $P_{\geq -1}$ *. For* $\lambda \in P_{\geq -1}$ *, we define the set* D(λ)^{*V} by*:</sup>

$$
D(\lambda)^\vee:=\left\{\left.\beta^\vee\in\Phi_+^\vee\right|\left\langle\lambda,\,\beta^\vee\right\rangle=-1\right.\right\}.
$$

The set $D(\lambda)^{\vee}$ *is called the shape of* λ *. If* $\#D(\lambda)^{\vee} < \infty$ *, then* λ *is called finite.*

Proposition 6.2 (see [4]) Let $\lambda \in P_{\geq -1}$ be finite and $\beta^{\vee}, \gamma^{\vee} \in D(\lambda)^{\vee}$ *satisfy* $\beta^{\vee} > \gamma^{\vee}$ *in the ordinary order of coroots. Then we have:*

$$
\langle \beta, \, \gamma^{\vee} \rangle = 0, 1, \text{ or } 2.
$$

By proposition 6.2, we introduce graph-structure into $D(\lambda)^{\vee}$ by:

$$
\beta^{\vee} \to \gamma^{\vee} \Leftrightarrow \beta^{\vee} > \gamma^{\vee} \text{ and } \langle \beta, \gamma^{\vee} \rangle = 1.
$$

$$
\beta^{\vee} \rightrightarrows \gamma^{\vee} \Leftrightarrow \beta^{\vee} > \gamma^{\vee} \text{ and } \langle \beta, \gamma^{\vee} \rangle = 2.
$$

If $\beta^{\vee} \not> \gamma^{\vee}$, or $\beta^{\vee} > \gamma^{\vee}$ and $\langle \beta, \gamma^{\vee} \rangle = 0$, then no arrows from β^{\vee} to γ^{\vee} exist. Thus, we get a finite acyclic multi-di-graph $D(\lambda)^{\vee}$ for a finite $\lambda \in P_{\geq -1}$.

Remark 6.3 *The finite pre-dominant integral weights* λ *are identified with the minuscule elements* w [4]*.* And, we have $D(\lambda)^{\vee} = \{ \beta^{\vee} \in \Phi^{\vee}_+ \mid w^{-1}(\beta^{\vee}) < 0 \}$. Furthermore, the linear extensions of $D(\lambda)^{\vee}$ are *identified with the reduced decompositions of* w *[4] by the following one-to-one correspondence:*

$$
Red(w) \ni (s_{i_1}, s_{i_2}, \cdots, s_{i_d}) \longleftrightarrow L \in \mathcal{L}(D(\lambda)^{\vee}), \quad L(k) = s_{i_1} \cdots s_{i_{k-1}} (\alpha_{i_k})^{\vee} \in D(\lambda)^{\vee} \ (k = 1, \cdots d),
$$

where $\text{Red}(w)$ *denotes the set of reduced decompositions of* w, $d = \ell(w)$ *the length of* w.

6.1 Case of type B

Suppose that the underlying Dynkin diagram is of type B :

$$
\underset{0}{\circ} \underset{1}{\circ} \underset{2}{\circ} \cdots \underset{2}{\circ} \underset{0}{\circ} \cdots
$$

Let $W = \langle s_0, s_1, s_2, \cdots \rangle$ be the Weyl group. Let Λ_0 be the 0-th fundamental weight. Then each $\lambda \in W\Lambda_0$ is a finite pre-dominant integral weight. And, $D(\lambda)^{\vee}$ is graph-isomorphic with some shape of type B defined in section 3.

Remark 6.4 Let $W_0 := \langle s_1, s_2, \dots \rangle$ be a maximal parabolic subgroup of W, which is the Weyl group of *type* A*. Then a minimal coset representative* w *in* W/W⁰ *is called a Lagrangian Grassmannian element.*

Let $\lambda \in W\Lambda_0$. Then the corresponding minuscule element w in remark 6.3 is a Lagrangian Grass*mannian element. Our result gives the number of reduced decompositions of Lagrangian Grassmannian element* w*.*

6.2 Case of type F_m $(m > 2)$

Let $m \in \mathbb{Z}$ be greater than or equal to 2. Suppose that the underlying Dynkin diagram is of type F_m :

❡ ❡ ❡ ❡ −m −2 −1 ❡ ❡ ❡ ❡ 0 1

Let $W = \langle s_{-m}, \dots, s_{-2}, s_{-1}, s_0, s_1, \dots \rangle$ be the Weyl group. Let Λ_{-m} be the $(-m)$ -th fundamental weight. Then each $\lambda \in P_{\geq -1} \cap W\Lambda_{-m}$ is a finite pre-dominant integral weight. And, D(λ)^{*V*} is graphisomorphic with some shape of type F_m defined in section 4.

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