

# A NEW STABILITY RESULT FOR THE WULFF SHAPE

Julien Roth

### ▶ To cite this version:

Julien Roth. A NEW STABILITY RESULT FOR THE WULFF SHAPE. 2017. hal-01228821v2

## HAL Id: hal-01228821 https://hal.science/hal-01228821v2

Preprint submitted on 22 Jun 2017 (v2), last revised 2 Mar 2018 (v4)

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

#### A NEW STABILITY RESULT FOR THE WULFF SHAPE

#### JULIEN ROTH

ABSTRACT. We prove that a closed convex hypersurface of a Euclidean space with almost constant anisotropic first and second mean curvatures is close (up to rescaling) to the Wulff shape.

#### 1. INTRODUCTION

Geodesic hyperspheres in Euclidean spaces can be characterized among closed hypersurfaces by various properties. In particular, it is well known that geodesic hyperspheres are the only totally geodesic closed connected hypersurfaces in Euclidean spaces. The question of the stability of this characterization has been intensively studied in the last years by many authors (see [5, 6, 7, 1] for instance). In the anisotropic setting, the so-called Wulf shape plays the role of geodesic spheres and can be characterized by similar results (see [3, 4] for instance. Analogously to shperes, the Wulff shape is, up to homotheties, the only closed convex hypersurfaces with vanishing traceless anisotropic second fundamental form. Very recently, De Rosa and Gioffrè [2] studied the stability of this characterization. Namely, he proved that if the traceless part of the anisotropic second fundamental form is sufficiently small, then the hypersurface is closed to the Wulff shape. The aim of the present note is to obtain a new stability result concerning the Wulff shape. Namely, we prove the following

**Theorem 1.1.** Let  $n \ge 2$  an integer,  $F : \mathbb{S}^n \longrightarrow \mathbb{R}$  be an elliptic integrand, h > 0, p > 1 and R > 0. Assume that  $V(M) = V(W_F)$  and that the extrinsic radius of M is smaller than R. Then, there exists  $\varepsilon_0(n, p, h, R, F) > 0$  such that if for  $\varepsilon \le \varepsilon_0$ , we have

- $|H^F h| < \varepsilon h$  and
- $|H_2^F h_2| < \varepsilon h^2$  for a constant  $h_2$ ,

then  $|h^2 - h_2| \leq A\varepsilon$ , for a positive constant A depending on n, h, R and F, and M is closed to the Wulff shape in the following sense. There exists a smooth parametrisation  $\psi : W_F \longrightarrow M$ , a vector  $c_0 \in \mathbb{R}^{n+1}$  and a constant K depending on n, p, h, R and F so that

$$\|\psi - \mathrm{Id} - c_0\|_{W^{2,p}(\mathcal{W})} \leq K\varepsilon^{\frac{p}{2}}$$

**Remark 1.2.** • Here V(M) is the volume of M for the induced metric g.

- An elliptic integrand is a function F satisfying (1) stated in the preliminaries section.
- We recall that the extrinsic radius of M is the radius of the smallest closed ball in ℝ<sup>n+1</sup> containing M.

<sup>2010</sup> Mathematics Subject Classification. 53C42,53A10.

Key words and phrases. Hypersurfaces, Anisotropic mean curvatures, Wulff Shape.

#### JULIEN ROTH

• Note that the right-hand sides in both pinching conditions of the theorem are respectively  $h\varepsilon$  and  $h^2\varepsilon$  for some homogeneity reasons, since for the Wulff shape, we have  $H_2^F = (H^F)^2$ . Equivalently, they can be replaced by  $\frac{\varepsilon}{R}$  and  $\frac{\varepsilon}{\sqrt{R}}$ .

#### 2. Preliminaries

Let  $F:\mathbb{S}^n\longrightarrow\mathbb{R}^{n+1}$  be a smooth function satisfying the following convexity assumption

(1) 
$$A_F = (\nabla dF + F \operatorname{Id}_{|T_x S^n})_x > 0,$$

for all  $x \in \mathbb{S}^n$ , where  $\nabla dF$  is the Hessian of F. Here, > 0 mean positive definite in the sense of quadratic forms. Now, we consider the following map

$$\begin{array}{rccc} \phi \, : \, \mathbb{S}^n & \longrightarrow & \mathbb{R}^{n+1} \\ & x & \longmapsto & F(x)x + (\mathrm{grad}_{|S^n}F)_x \end{array}$$

The image  $\mathcal{W}_F = \phi(\mathbb{S}^n)$  is called the Wulff shape of F and is a smooth hypersurface of  $\mathbb{R}^{n+1}$ . Moreover, by the condition (1),  $\mathcal{W}_F$  is convex. Note that if F = 1, the the Wulff shape is the sphere  $\mathbb{S}^n$ .

Now, let  $(M^n, g)$  be a *n*-dimensional compact, connected, oriented manifold without boundary, isometrically immersed into by X into  $\mathbb{R}^{n+1}$ . We denote by  $\nu$  a normal unit vector field globally defined on M, that is, we have  $\nu : M \longrightarrow \mathbb{S}^n$ . We set  $S_F = A_F \circ d\nu$ , where  $A_F$  is defined in (1).  $S_F$  is called the F-Weingarten operator or anisotropic shape operator, and it eigenvalues are the anisotropic principal curvatures that we will denote  $\kappa_1, \kappa_2, \cdots, \kappa_n$ . Finally, for  $r \in \{1, \cdots, n\}$ , the r-th anisotropic mean curvature is defined by

$$H_r^F = \frac{1}{\binom{n}{r}} \sum_{i_1 < \dots < i_r} \kappa_{i_1} \cdots \kappa_{i_r}.$$

We also set  $H_0^F = 1$  for convenience. Note that if F = 1 then this is the definition of the classical *r*-th mean curvatures. Finally, we recall these integral forumlas proved by He and Li in [3] and which generalize the classical Hsiung-Minkowski formulas in the anisotropic setting.

(2) 
$$\int_{M} \left( F(\nu) H_{r-1}^{F} + H_{r}^{F} < X, \nu > \right) dv_{g} = 0,$$

Now, we have all the ingredients to prove Theorem 1.1.

#### 3. Proof of Theorem 1.1

We begin the proof of Theorem 1.1 by the following techincal lemma.

**Lemma 3.1.** Let  $(M^n, g)$  be a closed and convex Riemannian manifold, isometrically immersed into  $\mathbb{R}^{n+1}$  and assume that the extrinsic radius of M is smaller than R. Let h and  $h_2$  be two positive constants and  $\varepsilon \in (0, 1)$ . If the mean curvature and the scalar curvature satisfy

• 
$$|H^{F} - h| < \varepsilon h \text{ and }$$

• 
$$|H_2^F - h_2| < \varepsilon h^2$$
,

for some positive  $\varepsilon$ , then

$$\left|h^2 - h_2\right| \leqslant A\varepsilon,$$

where A is a positive constant depending on h, R and F.

 $\mathbf{2}$ 

*Proof.* The proof of this lemma is based on the Hisung-Minkowski formulas (2) for r = 1 and k = 2. Indeed, the Hisung-Minkowski formula for r = 2 is the following

(3) 
$$\int_{M} \left( H_2^F \langle X, \nu \rangle + F(\nu) H^F \right) dv_g = 0.$$

Then, we get

$$\begin{aligned} 0 &= \int_{M} \left( H_{2}^{F} \langle X, \nu \rangle + F(\nu)H \right) dv_{g} \\ &= \int_{M} \left( h_{2} \langle X, \nu \rangle + F(\nu)H \right) dv_{g} + \int_{M} (H_{2}^{F} - h_{2}) \langle X, \nu \rangle dv_{g} \\ &= \frac{h_{2}}{h} \int_{M} h \left\langle X, \nu \right\rangle + \int_{M} F(\nu)H^{F} dv_{g} + \int_{M} (H_{2} - h_{2}) \left\langle X, \nu \right\rangle dv_{g} \\ &= \frac{h_{2}}{h} \int_{M} H^{F} \left\langle X, \nu \right\rangle dv_{g} + \frac{h_{2}}{h} \int_{M} (h - H^{F}) \left\langle X, \nu \right\rangle dv_{g} + \int_{M} F(\nu)hdv_{g} + \int_{M} F(\nu)(H^{F} - h)dv_{g} \\ &+ \int_{M} (H_{2}^{F} - h_{2}) \left\langle X, \nu \right\rangle dv_{g} \end{aligned}$$

Now, we use the Hsiung-Minkowski formula for r = 1, that is

(4) 
$$\int_{M} \left( H^{F} \langle X, \nu \rangle + F(\nu) \right) dv_{g} = 0,$$

to get

$$\begin{aligned} 0 &= -\frac{h_2}{h} \int_M F(\nu) dv_g + \frac{h_2}{h} \int_M (h - H^F) \langle X, \nu \rangle dv_g + \int_M F(\nu) h dv_g + \int_M F(\nu) (H^F - h) dv_g \\ &+ \int_M (H_2^F - h_2) \langle X, \nu \rangle dv_g \\ &= \left(h - \frac{h_2}{h}\right) \int_M F(\nu) dv_g + \frac{h_2}{h} \int_M (h - H^F) \langle X, \nu \rangle dv_g + \int_M F(\nu) (H^F - h) dv_g \\ &+ \int_M (H_2^F - h_2) \langle X, \nu \rangle dv_g \end{aligned}$$

Then, using both conditions  $|H^F - h| < \varepsilon h$  and  $|H_2^F - h_2| < \varepsilon h^2$ , we get

$$\left|h - \frac{h_2}{h}\right| \int_M F(\nu) dv_g \quad \leqslant \quad h_2 \varepsilon R V(M) + \varepsilon h \int_M F(\nu) dv_g + \varepsilon h^2 R V(M).$$

Using the fact that  $|H_2^F| \leq (H^F)^2$ , we deduce from the assumptions on h and  $h_2$  that

$$\begin{aligned} |h_2| &\leqslant |H_2^F| + h^2 \varepsilon \\ &\leqslant (H^F)^2 + h^2 \varepsilon \\ &\leqslant (h+h\varepsilon)^2 + h^2 \varepsilon \\ &\leqslant 5h^2 \end{aligned}$$

for  $\varepsilon < 1$ . Thus, we have

$$\begin{split} \left|h^2 - h_2\right| \int_M F(\nu) dv_g &\leqslant \quad \varepsilon h^2 \int_M F(\nu) dv_g + (h^3 + hh_2) RV(M) \varepsilon \\ &\leqslant \quad \varepsilon h^2 \int_M F(\nu) dv_g + 6h^3 RV(M) \varepsilon \end{split}$$

and we obtain

$$|h^2 - h_2| \leqslant \left(h^2 + \frac{6h^3R}{\inf(F)}\right)\varepsilon$$
  
$$\leqslant A(h, R, F)\varepsilon,$$

which gives the wanted assertion.

Now, using this lemma together with the result of De Rosa and Gioffrè, we can prove Theorem 1.1. We recall the main result of [1].

**Theorem 3.2** (De Rosa-Gioffrè [1]). Let n > 2,  $p \in (1,p)$  and  $F : \mathbb{S}^n \longrightarrow \mathbb{R}^+$ satisfying the convexity assumption (1). There exists a constant  $\delta_0 = \delta_0(n, p, F) > 0$ such that if  $\Sigma$  is closed convex hypersurface into  $\mathbb{R}^{n+1}$  satisfying

$$V(M) = V(\mathcal{W}_F) \quad and \quad \int_M \|S_F - H^F \mathrm{Id}\|^p dv_g \leq \delta$$

with  $\delta \leq \delta_0$  then there exists a smooth parametrisation  $\psi : \mathcal{W}_F \longrightarrow M$ , a vector  $c_0 \in \mathbb{R}^{n+1}$  and a constant C depending on n, p and F so that

$$\|\psi - \mathrm{Id} - c_0\|_{W^{2,p}(\mathcal{W})} \leq C\delta.$$

Now, if  $|H^F - h| < \varepsilon h$  and  $|H_2^F - h_2| < \varepsilon h^2$ , then from Lemma 3.1

$$\left|h^2 - h_2\right| \leqslant A\varepsilon,$$

with A a positive constant depending on h, R and F. Thus, we deduce that

$$\begin{split} (H^F)^2 - H_2^F &\leqslant |(H^F)^2 - h^2| + |h^2 - h_2| + |h_2 - H_2^F| \\ &\leqslant (|H^F| + h) \cdot |H^F - h| + A\varepsilon + h^2\varepsilon \\ &\leqslant (2h + h\varepsilon)h\varepsilon + A\varepsilon + h^2\varepsilon \\ &\leqslant A'\varepsilon, \end{split}$$

where A' is a positive constant depending only on h, R and F. On the other hand, we have

$$(H^F)^2 - H_2^F = \frac{1}{n^2(n-1)} \sum_{i,j=1}^n (\kappa_i - \kappa_j)^2,$$

so we get

$$\sum_{i,j=1}^{n} (\kappa_i - \kappa_j)^2 \leqslant A'' \varepsilon.$$

where  $A'' = n^2(n-1)A'$  is also a positive constant depending only on h, n, R and F. Hence, M has almost vanishing anisotropic second fundamental form. Indeed,

we have

$$|S_F - H^F \mathrm{Id}||_{\infty}^2 = \sum_{i=1}^n (k_i - H^F)^2$$
$$= \sum_{i=1}^n \left(\kappa_i - \frac{1}{n} \sum_{j=1}^n \kappa_j\right)^2$$
$$= \frac{1}{n} \sum_{i,j=1}^n (\kappa_i - \kappa_i)^2$$
$$\leqslant \frac{1}{n} A'' \varepsilon.$$

Finally, we fix p > 1 and set  $\varepsilon_0 = \inf \left\{ 1, \frac{n(\delta_0 V(\mathcal{W}_F))^{\frac{2}{p}}}{A''} \right\}$  where A'' is the constant defined above and  $\delta_0$  comes from Theorem 3.2. Note that  $\varepsilon_0$  depends on n, p, h, R and F. Now, let  $\varepsilon \leqslant \varepsilon_0$ . We set  $\delta = \frac{(A''\varepsilon)^{\frac{p}{2}}}{n^{\frac{p}{2}}V(\mathcal{W}_F)}$ . Since  $\varepsilon \leqslant \varepsilon_0$  and from the definiton of  $\delta$ , we have  $\delta \leqslant \delta_0$  and

$$\int_{M} \|S_F - H^F \mathrm{Id}\|^p dv_g \leqslant \|S_F - H^F \mathrm{Id}\|_{\infty} V(\mathcal{W}_F) \leqslant \delta.$$

Thus, since by assumption, we also have  $V(M) = V(\mathcal{W}_F)$ , we can apply Theorem 3.2 to obtain that there exists a smooth parametrisation  $\psi : \mathcal{W}_F \longrightarrow M$  a vector  $c_0 \in \mathbb{R}^{n+1}$  and a constant C depending on n, p, h, R and F so that

$$\|\psi - \mathrm{Id} - c_0\|_{W^{2,p}(\mathcal{W})} \leq C\delta = K\varepsilon^{\frac{p}{2}},$$

where  $K = \frac{(nA'')^{\frac{p}{2}}C}{V(\mathcal{W}_F)}$  is a positive constant depending only on n, p, h, R and F since A'' depends on n, h, R and  $F, V(\mathcal{W}_F)$  depends on n and F and C depends on n, p and F. This concludes the proof of Theorem 1.1.

#### References

- A. De Rosa & S. Gioffrè, Quantitative stability for anisotropic nearly umbilical hypersurfaces, arXiv:1705.09994.
- [2] S. Gioffrè, A W<sup>2,p</sup>-estimate for nearly umbilical hypersurfaces, arXiv:1612.08570.
- [3] Y. He & H. Li, Integral formula of Minkowski type and new characterization of the Wulff shape, Acta Math. Sinica, 24(4) (2008), 697-704.
- [4] L. Onat, Some characterizations of the Wulff shape, C. R. Math. Acad. Sci. Paris 348 (2010), no. 17-18, 997-1000.
- [5] D. Perez, On nearly umbilical hypersurfaces, Ph.D. thesis, Zuerich, 2011.
- [6] J. Roth, Rigidity results for geodesic spheres in space forms, Differential Geometry, Proceedings of the VIIIth International Colloquium in Differential Geometry, Santiago de Compostela (2009), 156-163, World Scientific.
- [7] J.Roth A remark on almost umbilical hypersurfaces, Arch. Math. (Brno), 49(1) (2013), 1-7.

LABORATOIRE D'ANALYSE ET DE MATHÉMATIQUES APPLIQUÉES, UNIVERSITÉ PARIS-EST, 5, BOULEVARD DESCARTES, CITÉ DESCARTES, 77454 MARNE-LA-VALLÉE CEDEX 2, FRANCE