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Counting quadrant walks via Tutte’s invariant method (extended abstract)

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Abstract. In the 1970s, Tutte developed a clever algebraic approach, based on certain “invariants”, to solve a functional equation that arises in the enumeration of properly colored triangulations. The enumeration of plane lattice walks confined to the first quadrant is governed by similar equations, and has led in the past decade to a rich collection of attractive results dealing with the nature (algebraic, D-finite or not) of the associated generating function, depending on the set of allowed steps.

We first adapt Tutte’s approach to prove (or reprove) the algebraicity of all quadrant models known or conjectured to be algebraic (with one small exception). This includes Gessel’s famous model, and the first proof ever found for one model with weighted steps. To be applicable, the method requires the existence of two rational functions called *invariant* and *decoupling function* respectively. When they exist, algebraicity comes out (almost) automatically.

Then, we move to an analytic viewpoint which has already proved very powerful, leading in particular to integral expressions of the generating function in the non-D-finite cases, as well as to proofs of non-D-finiteness. We develop in this context a weaker notion of invariant. Now all quadrant models have invariants, and for those that have in addition a decoupling function, we obtain integral-free expressions of the generating function, and a proof that this series is differentially algebraic (that is, satisfies a non-linear differential equation).

Keywords: Lattice walks, enumeration, differentially algebraic functions, conformal mappings

1 Introduction

In the past decade, the enumeration of plane walks confined to the first quadrant has received a lot of attention, and given rise to many interesting methods and results. Given a set of steps $\mathcal{S} \subset \mathbb{Z}^2$ and a starting point (usually $(0, 0)$), the main question is to determine the generating function

$$Q(x, y; t) \equiv Q(x, y) = \sum_{i, j, n \geq 0} q(i, j; n) x^i y^j t^n,$$

where $q(i, j; n)$ is the number of n -step quadrant walks from $(0, 0)$ to (i, j) , taking their steps in \mathcal{S} . If one only considers walks with *small steps* (that is, $\mathcal{S} \subset \{-1, 0, 1\}^2$), there are 79 inherently different

step sets (also called *models*) and an expression of $Q(x, y)$, sometimes rather complex, is known in each case. Moreover, the *nature* of this series is also known: it is *D-finite* (that is, satisfies three linear differential equations, one in x , one in y , one in t , with polynomial coefficients) if and only if a certain group of rational transformations is finite. This happens in 23 cases. In exactly 4 of them, $Q(x, y)$ is even *algebraic*, that is, satisfies a polynomial equation with polynomial coefficients in x , y and t . This classification has been obtained by an attractive combination of approaches: algebraic [BM02, BMM10, Ges86, GZ92], computer-algebraic [BK10, KKZ09, KZ08], analytic [BKR13, Ras12, KR12], asymptotic [DW15, MR09].

The starting point of all of them is a functional equation satisfied by $Q(x, y)$, which is simple to establish, but often hard to solve. For instance, in the case of Kreweras' walks (steps $\nearrow, \leftarrow, \downarrow$), it reads

$$Q(x, y) = 1 + txyQ(x, y) + t \frac{Q(x, y) - Q(0, y)}{x} + t \frac{Q(x, y) - Q(x, 0)}{y}. \quad (1)$$

This is reminiscent of an equation written by Tutte in the 1970s when studying q -colored triangulations:

$$G(x, y) = xq(q-1)t^2 + \frac{xy}{qt}G(1, y)G(x, y) - x^2yt \frac{G(x, y) - G(1, y)}{x-1} + x \frac{G(x, y) - G(x, 0)}{y}. \quad (2)$$

Due to the quadratic term, this is in fact more complicated than (1). Tutte worked about a decade on this equation, and finally solved it, proving that the series $G(1, 0)$ is *differentially algebraic*, that is, satisfies a (non-linear) differential equation in t . One key step in his study was to prove that for certain (infinitely many) values of q , the series $G(x, y)$ is algebraic, using a certain notion of *invariant* [Tut95].

Could this notion bring something new to the classification of quadrant walks? This paper answers this question positively:

- We first adapt Tutte's approach to quadrant walks, and thus obtain *short and uniform proofs* of algebraicity for all algebraic models (with one small exception). This includes the shortest proof ever found for Gessel's famous model, and extends to models with weighted steps, for which algebraicity was sometimes still conjectural [KY14]. With our approach, a model with finite group is algebraic if and only if it admits a *decoupling function* (Sections 2 and 3).
- We then define a weaker notion of invariant, and use it to give an integral free expression of $Q(x, y)$ for models with infinite group that admit a decoupling function (Section 4). We have at the moment found 9 such models. This expression implies that $Q(x, y)$ is differentially algebraic in x , y and t (Section 5).

We now introduce some basic tools in the study of quadrant walks with small steps. A simple step-by-step construction of these walks gives the following functional equation [BMM10]:

$$K(x, y)Q(x, y) = K(x, 0)Q(x, 0) + K(0, y)Q(0, y) - K(0, 0)Q(0, 0) - xy, \quad (3)$$

where

$$K(x, y) = xy \left(t \sum_{(i,j) \in \mathcal{S}} x^i y^j - 1 \right)$$

is called the *kernel* of the model. It is a polynomial of degree 2 in x and y , which we often write as

$$K(x, y) = \tilde{a}(y)x^2 + \tilde{b}(y)x + \tilde{c}(y) = a(x)y^2 + b(x)y + c(x). \quad (4)$$

We shall also denote

$$K(x, 0)Q(x, 0) = R(x) \quad \text{and} \quad K(0, y)Q(0, y) = S(y).$$

Note that $K(0, 0)Q(0, 0) = R(0) = S(0)$, so that the basic functional equation (3) reads

$$K(x, y)Q(x, y) = R(x) + S(y) - R(0) - xy. \quad (5)$$

Seen as polynomial in y , the kernel has two roots Y_0 and Y_1 , which are Laurent series in t with coefficients in $\mathbb{Q}(x)$. If the series $Q(x, Y_i)$ is well defined, setting $y = Y_i$ in (5) shows that

$$R(x) + S(Y_i) = xY_i + R(0). \quad (6)$$

If this holds for Y_0 and Y_1 , we have

$$S(Y_0) - xY_0 = S(Y_1) - xY_1. \quad (7)$$

The *group of the model*, denoted by $G(\mathcal{S})$, is generated by the following two rational transformations:

$$\Phi(x, y) = \left(\frac{\tilde{c}(y)}{\tilde{a}(y)} \frac{1}{x}, y \right) \quad \text{and} \quad \Psi(x, y) = \left(x, \frac{c(x)}{a(x)} \frac{1}{y} \right).$$

Both are involutions, thus $G(\mathcal{S})$ is a dihedral group, which, depending on the step set \mathcal{S} , is finite or not.

A step set \mathcal{S} is *singular* if each step $(i, j) \in \mathcal{S}$ satisfies $i + j \geq 0$.

Notation. For a ring R , we denote by $R[t]$ (resp. $R[[t]]$) the ring of polynomials (resp. formal power series) in t with coefficients in R . If R is a field, then $R(t)$ stands for the field of rational functions in t . This notation is generalized to several variables. For instance, the series $Q(x, y)$ belongs to $\mathbb{Q}[x, y][[t]]$.

2 A new solution of Gessel's model

This model, with steps $\rightarrow, \nearrow, \leftarrow, \swarrow$, appears as the most difficult model with a finite group. Around 2000, Ira Gessel conjectured that the number of $2n$ -step quadrant walks starting and ending at $(0, 0)$ was

$$g_{0,0}(2n) = 16^n \frac{(1/2)_n (5/6)_n}{(2)_n (5/3)_n},$$

where $(a)_n = a(a+1) \cdots (a+n-1)$ is the rising factorial. This conjecture was proved in 2009 by Kauers, Koutschan and Zeilberger [KKZ09]. A year later, Bostan and Kauers [BK10] proved that the three-variate series $Q(x, y; t)$ is not only D-finite, but even algebraic. Two other proofs of these results have been given [BKR13, BM15]. Here, we give yet another proof based on Tutte's idea of *invariants*.

The basic functional equation (5) holds with $K(x, y) = t(y + x^2y + x^2y^2 + 1) - xy$, $R(x) = tQ(x, 0)$, and $S(y) = t(1 + y)Q(0, y)$. It follows from $K(x, Y_0) = K(x, Y_1) = 0$ that

$$I(Y_0) = I(Y_1), \quad \text{with} \quad I(y) = \frac{1}{t(1+y)(1+1/y)} + t(1+y)(1+1/y). \quad (8)$$

We say that $I(y)$ is a (rational) y -invariant.

Let us now take $x = t + t^2(u + 1/u)$, where u is a new variable. Then it is easy to see that both Y_0 and Y_1 are Laurent series in t with coefficients in $\mathbb{Q}(u)$, and that $Q(x, Y_0)$ and $Q(x, Y_1)$ are well defined. Hence (7) holds. Moreover, the kernel equation $K(x, Y_i) = 0$ implies that

$$x(Y_0 - Y_1) = \frac{1}{t(1 + Y_1)} - \frac{1}{t(1 + Y_0)}, \quad (9)$$

so that we can rewrite (7) as

$$J(Y_0) = J(Y_1), \quad \text{with} \quad J(y) = S(y) + \frac{1}{t(1 + y)}.$$

This should be compared to (8). The connection between $I(y)$ and $J(y)$ will stem from the following lemma, the proof of which is elementary.

Lemma 1 *Let $F(y)$ be a Laurent series in t with coefficients in $\mathbb{Q}[y]$, of the form*

$$F(y) = \sum_{0 \leq j \leq n+n_0} a(j, n) y^j t^{2n}$$

for some $n_0 \geq 0$. Then for $x = t + t^2(u + 1/u)$, the series $F(Y_0)$ and $F(Y_1)$ are well defined Laurent series in t , with coefficients in $\mathbb{Q}(u)$. If they coincide, then $F(y)$ is in fact independent of y .

The above series I and J do not satisfy the assumptions of the lemma, as their coefficients are *rational* in y with poles at $y = 0, -1$ (for I) and $y = -1$ (for J). Still, we can construct from them a series F satisfying the assumptions of the lemma. First, we eliminate the pole of I at 0 by forming the y -invariant $(J(y) - J(0))I(y)$. The coefficients of this series have a pole of order at most 3 at $y = -1$. By subtracting an appropriate series of the form $aJ(y)^3 + bJ(y)^2 + cJ(y)$, we obtain a series satisfying the assumptions of the lemma, which must thus be constant, equal for instance at its value at $y = -1$. In brief,

$$(J(y) - J(0))I(y) = aJ(y)^3 + bJ(y)^2 + cJ(y) + d \quad (10)$$

for some series a, b, c, d in t . Expanding this identity near $y = -1$ gives:

$$a = -t, \quad b = 2 + tS(0), \quad c = -S(0) + 2S'(-1) - t - 1/t,$$

and

$$d = tS(0) - 2S(0)S'(-1) - 3S'(-1)/t + S''(-1)/t + 1.$$

Replacing in (10) the series I and J by their expressions (in terms of t, y and $S(y)$) gives for $S(y)$ a cubic equation, involving three additional unknown series in t , namely $S(0), S'(-1)$ and $S''(-1)$. It is not hard to see that this equation defines a unique power series $S(y)$ in $\mathbb{Q}[y][[t]]$. In the terminology of [BMJ06], this is a *cubic equation in one catalytic variable y* . The solutions of such equations are always algebraic, and a procedure for solving them is given in [BMJ06]. Applying it shows in particular that $S(0), S'(-1)$ and $S''(-1)$ belong to the extension of $\mathbb{Q}(t)$ generated by the unique series $Z = 1 + O(t)$ satisfying $Z^2 = 1 + 256t^2Z^6/(Z^2 + 3)^3$. Due to lack of space, we do not give any details, but refer the reader to [BM15, Sec. 3.4], where an analogous equation satisfied by $R(x)$ is solved.

3 Extensions and obstructions

We now formalize the three main ingredients in the above solution of Gessel's model. The first one is clearly the rational invariant $I(y)$ given by (8).

Definition 2 A rational function $I(y) \in \mathbb{Q}(t, y)$ is said to be a y -invariant of a quadrant model \mathcal{S} if $I(Y_0) = I(Y_1)$ when Y_0 and Y_1 are the roots of the kernel, solved for y . We define x -invariants similarly.

Note that $I(Y_i) = (I(Y_0) + I(Y_1))/2$ must then be a rational function of x , since it is a symmetric function of Y_0 and Y_1 .

Lemma 3 If a model has a y -invariant $I_2(y)$, then it admits $I_1(x) := I_2(Y_0) = I_2(Y_1)$ as x -invariant. Moreover, $I_1(X_0) = I_1(X_1) = I_2(y)$.

Note that having invariants is just saying that $I_1(x) - I_2(y)$ vanishes on the curve $K(x, y) = 0$, which alludes to Hilbert's Nullstellensatz. In Gessel's case, $I_2(y)$ was the function $I(y)$ of (8), and we find $I_1(x) = -t/x^2 + 1/x + 2t + x - tx^2$.

Proposition 4 A quadrant model has rational invariants if and only if the associated group is finite.

Proof: A model with an infinite group cannot have rational invariants: the function $I_1(x)$ would take the same value for infinitely many values of x , which is not possible for a rational function. Conversely, each of the 23 models with a finite group admits rational invariants, listed in Appendix A. \square

In the next section, we introduce a weaker notion of (possibly irrational) invariants, which guarantees that any quadrant model now has a (weak) invariant. One key difference with the algebraic setting of the above section is that the new notion is analytic in nature.

The second ingredient of Section 2 was the identity (9), which we formalize as follows.

Definition 5 We say that a quadrant model is decoupled if there exist rational functions $F(x) \in \mathbb{Q}(x, t)$ and $G(y) \in \mathbb{Q}(y, t)$ such that, as soon as $K(x, y) = 0$, one has $xy = F(x) + G(y)$.

This is in fact equivalent to the (apparently weaker) identity $x(Y_0 - Y_1) = G(Y_0) - G(Y_1)$ (which was (9) in Gessel's case), and the functions F and G are related by $F(x) = xY_0 - G(Y_0) = xY_1 - G(Y_1)$ (and symmetrically). In Gessel's case, we had $G(y) = -1/(t(1+y))$, corresponding to $F(x) = -1/x + 1/t$.

So which models are decoupled? Not all, at any rate: for any model that has a vertical symmetry, the series Y_i are symmetric in x and $1/x$, and so any expression of x of the form $(G(Y_0) - G(Y_1))/(Y_0 - Y_1)$ would be at the same time an expression of $1/x$. At the moment, we have found 13 decoupled models (Appendix B): 4 with a finite group (and these are, as one can expect from the algebraicity result of Section 2, those with an algebraic generating function), and 9 with an infinite group, shown in Figure 2.

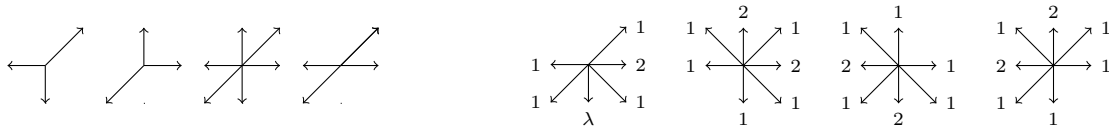


Fig. 1: Left: The four algebraic quadrant models (Kreweras, reversed Kreweras, double Kreweras, Gessel). Right: Four algebraic models with weights [KY14].

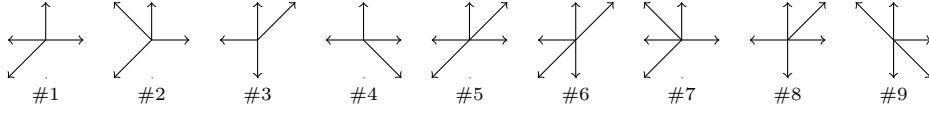


Fig. 2: Nine decoupled models with an infinite group.

The final ingredient is the “invariant Lemma” (Lemma 1). It admits analogues for the 4 algebraic models to the left of Figure 1, except for the second one, which we solve in a slightly different way in the next section.

Proposition 6 *The existence of rational invariants, decoupling functions and invariant lemma yields new and uniform proofs of the algebraicity of the 4 models of Figure 1, left, except the second. This extends to the 4 weighted models shown on Figure 1, right.*

For Gessel’s walks, this is the shortest known proof. For the rightmost weighted model, it is the first one.

Remark. In the finite group case, there exists a systematic procedure to construct the invariants and (when they exist) the decoupling functions, adapting [FIM99, Thm. 4.2.9 and Thm. 4.2.10] to our context. In the infinite group case, the 9 decoupling functions have been guessed-and-checked.

4 An analytic invariant method

We now move to an analytic world, and consider $Q(x, y)$ as a function of three complex variables, analytic in the polydisc $\{|x| < 1, |y| < 1, |t| < 1/|\mathcal{S}|\}$ (at least). This section borrows its notation and several results from the analytic approach of quadrant models [FIM99, Ras12]. The roots $Y_{0,1}$ of the kernel (now called *branches* of K) are given by

$$Y_{0,1}(x) = \frac{-b(x) \pm \sqrt{b(x)^2 - 4a(x)c(x)}}{2a(x)}, \quad (11)$$

where a, b and c are defined by (4). The discriminant $d(x) := b(x)^2 - 4a(x)c(x)$ has degree three or four, hence there are four branch points x_1, \dots, x_4 (depending on t), with $x_4 = \infty$ if $d(x)$ has degree three. We define symmetrically the branches $X_{0,1}$ and their four branch points y_ℓ .

Lemma 7 ([FIM99]) *Let $t \in (0, 1/|\mathcal{S}|)$. The x_ℓ ’s are real. Two branch points (say x_1 and x_2) are in the (open) unit disc, with $|x_1| \leq |x_2|$ and $x_2 > 0$. The other two (say x_3 and x_4) are outside the (closed) unit disc, with $|x_3| \leq |x_4|$ and $x_3 > 0$. The discriminant $d(x)$ is negative on (x_1, x_2) and (x_3, x_4) , where if $x_4 < 0$, (x_3, x_4) stands for $(x_3, \infty) \cup (-\infty, x_4)$.*

The branches $Y_{0,1}$ are meromorphic on $\mathbb{C} \setminus ([x_1, x_2] \cup [x_3, x_4])$. On the cuts $[x_1, x_2]$ and $[x_3, x_4]$, the two branches $Y_{0,1}$ still exist and are complex conjugate. A key object in our definition of weak invariants is the curve \mathcal{L} defined by

$$\mathcal{L} = Y_0([x_1, x_2]) \cup Y_1([x_1, x_2]) = \{y \in \mathbb{C} : K(x, y) = 0 \text{ and } x \in [x_1, x_2]\}. \quad (12)$$

By construction, it is symmetric with respect to the real axis. If \mathcal{L} is bounded (as for the models of Figure 2), we denote by $\mathcal{G}_{\mathcal{L}}$ the domain enclosed by \mathcal{L} . Otherwise, $\mathcal{G}_{\mathcal{L}}$ is the domain delimited by \mathcal{L} and containing the real point at $-\infty$. See Figure 3 for examples.

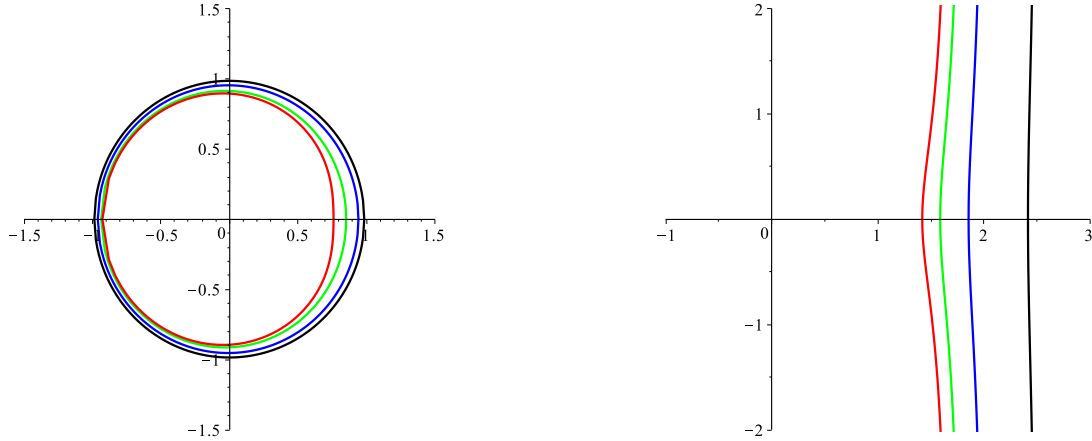


Fig. 3: The curves \mathcal{L} for the models #3 (for $t = 0.03, 0.1, 0.2$ and 0.25 , as one moves closer to the origin) and for the reverse Kreweras model ($t = 0.2, 0.25, 0.28$ and 0.33 , from right to left).

The function $S(y) = K(0, y)Q(0, y)$ is analytic in $\mathcal{G}_{\mathcal{L}}$ (by [Ras12, Thm. 5]) and bounded on $\mathcal{G}_{\mathcal{L}} \cup \mathcal{L}$ (this follows from (6) when $x \in [x_1, x_2]$). Moreover, Eq. (11) of [Ras12] tells us that, for $x \in [x_1, x_2]$,

$$S(Y_0) - xY_0 = S(Y_1) - xY_1. \quad (13)$$

4.1 Weak invariants

Definition 8 A function $I(y) \equiv I(y; t)$ is a weak invariant of a quadrant model \mathcal{S} if for $t \in (0, 1/|\mathcal{S}|)$:

- it is meromorphic in the domain $\mathcal{G}_{\mathcal{L}}$, and admits finite limit values on the curve \mathcal{L} ;
- for any $y \in \mathcal{L}$, we have $I(y) = I(\bar{y})$.

The second condition is indeed a weak form of the invariant condition $I(Y_0) = I(Y_1)$, because two conjugate points y and \bar{y} of the curve \mathcal{L} are the (complex conjugate) roots of $K(x, y) = 0$ for some $x \in [x_1, x_2]$. Hence, if the model admits a rational invariant $I(y)$ in the sense of Definition 2, then I is also a weak invariant. However, the above definition is less demanding, and it turns out that every quadrant model admits a weak invariant, which we now describe (in the non-singular case).

This invariant, traditionally denoted $w(y)$ (or even $\tilde{w}(y)$) in the analytic approach to quadrant problems [FIM99, Ras12], is in addition injective in $\mathcal{G}_{\mathcal{L}}$. In analytic terms, this third condition makes it a *conformal gluing function* for the domain $\mathcal{G}_{\mathcal{L}}$. Explicit expressions of conformal gluing functions are known in a number of cases (when the domain is an ellipse, a polygon, etc.). In our case the bounding curve \mathcal{L} is a quartic curve [FIM99, Thm. 5.3.3 (i)], and w can be expressed in terms of Weierstrass' elliptic functions (see [FIM99, Sec. 5.5.2.1] or [Ras12, Thm. 6]):

$$w(y; t) \equiv w(y) = \wp_{1,3} \left(-\frac{\omega_1 + \omega_2}{2} + \wp_{1,2}^{-1}(f(y)) \right), \quad (14)$$

where the various ingredients are as follows. First, $f(y)$ is a simple rational function of y whose coefficients are algebraic functions of t :

$$f(y) = \begin{cases} \frac{\tilde{d}''(y_4)}{6} + \frac{\tilde{d}'(y_4)}{y - y_4} & \text{if } y_4 \neq \infty, \\ \frac{\tilde{d}''(0)}{6} + \frac{\tilde{d}'''(0)y}{6} & \text{if } y_4 = \infty, \end{cases}$$

where the y_ℓ 's are the branch points of the functions $X_{0,1}$, and $\tilde{d}(y)$ is the counterpart of the discriminant $d(x)$ for the variable y (so that $\tilde{d}(y_4) = 0$). Then, $\wp_{1,2}$ (resp. $\wp_{1,3}$) is Weierstrass' elliptic function with periods (ω_1, ω_2) (resp. (ω_1, ω_3)), where

$$\omega_1 = i \int_{x_1}^{x_2} \frac{dx}{\sqrt{-d(x)}}, \quad \omega_2 = \int_{x_2}^{x_3} \frac{dx}{\sqrt{d(x)}}, \quad \omega_3 = \int_{Y(x_1)}^{x_1} \frac{dx}{\sqrt{d(x)}}. \quad (15)$$

Note that $\omega_1 \in i\mathbb{R}_+$ and $\omega_2, \omega_3 \in \mathbb{R}_+$.

It is known that the function $w(y)$ given by (14) is meromorphic in $\mathcal{G}_{\mathcal{L}}$, with a unique pole at y_2 . It is an algebraic function of y and t for the 23 models with a finite group, see [Ras12, Thm. 2 and Thm. 3]. It is even rational unless \mathcal{S} is one of the 4 algebraic models. It is then a rational invariant, in the sense of Definition 2. In the infinite group case, $w(y)$ is not algebraic, nor even D-finite w.r.t. to y , see [Ras12, Thm. 2]. However, we will prove in Proposition 12 that it is differentially algebraic in y and t .

4.2 The analytic invariant lemma — Application to quadrant walks

We now come with an analytic counterpart of Lemma 1.

Lemma 9 *Let \mathcal{S} be a non-singular quadrant model and $I(y)$ a weak invariant for this model. If I has no pole in $\mathcal{G}_{\mathcal{L}}$ (and, in the case of a non-bounded curve \mathcal{L} , if I is bounded at ∞), it is independent of y .*

This is proved in [Lit00, Ch. 3], more precisely in Lemma 1 for the bounded case, and in Lemma 2 for the unbounded case.

Let \mathcal{S} be a quadrant model that is decoupled, in the sense of Definition 5. In particular,

$$x(Y_0 - Y_1) = G(Y_0) - G(Y_1)$$

for some rational function G . Assume that G has no pole on \mathcal{L} . Then, by combining (13) with the analytic properties of S , we see that

$$I(y) := S(y) - G(y)$$

is a weak invariant in the sense of Definition 8. Since S is analytic in $\mathcal{G}_{\mathcal{L}}$, the poles of $I(y)$ lying in $\mathcal{G}_{\mathcal{L}}$ must be poles of $G(y)$. Let us denote them p_1, \dots, p_ℓ , and assume they are different from the pole y_2 of w . Then there exists a function of the form

$$r(y) = \sum_{i=1}^{\ell} \sum_{e=1}^{m_i} \frac{\alpha_{e,i}}{(w(y) - w(p_i))^e}$$

such that $I(y) - r(y)$ has no pole in $\mathcal{G}_{\mathcal{L}}$ and is bounded there — and is still a weak invariant. Applying Lemma 9 tells us that this function is independent of y . Let us examine two examples.

Example: Model #3 of Figure 2. This is a decoupled model, with $G(y) = -y - 1/y$. Hence $I(y) = S(y) + y + 1/y = tyQ(0, y) + y + 1/y$ is a weak invariant, with a single pole in $\mathcal{G}_{\mathcal{L}}$, placed at $y = 0$ and having residue 1 (the curve $\mathcal{G}_{\mathcal{L}}$ is shown in Figure 3, left). Thus $I(y)$ differs from $\frac{w'(0)}{w(y)-w(0)}$ by a constant, and a series expansion at $y = 0$ gives

$$tQ(0, y) = \frac{1}{y} \left(\frac{w''(0)}{2w'(0)} + \frac{w'(0)}{w(y) - w(0)} - y - \frac{1}{y} \right).$$

□

This extends to all models of Figure 2. The curve \mathcal{L} is bounded in each case.

Corollary 10 *For any of the 9 models of Figure 2, the series $tQ(0, y)$ admits a rational expression in terms of $y, w(y), w(0), w'(0), w''(0), w(-1), w'(-1), w''(-1), w(\pm i), w(\pm j)$, with $j = e^{2i\pi/3}$.*

Example: the reversed Kreweras model. Recall that this model was left unsolved in Section 3. The associated curve \mathcal{L} is unbounded (Figure 3, right). This is again a decoupled model, and a decoupling function is $G(y) = -1/y$ (Table 3). Accordingly, $I(y) = S(y) + 1/y = tQ(0, y) + 1/y$ is a weak invariant, with a single pole in $\mathcal{G}_{\mathcal{L}}$, placed at $y = 0$ and having residue 1. Further, it follows from (6) that I is bounded at ∞ . Thus $I(y)$ differs from $\frac{w'(0)}{w(y)-w(0)}$ by a constant, and a series expansion at $y = 0$ gives

$$tQ(0, y) = -\frac{1}{y} + \frac{w'(0)}{w(y) - w(0)} + tQ(0, 0) + \frac{w''(0)}{2w'(0)}.$$

It remains to determine $Q(0, 0)$. Using the case $i = 0$ of (6) and the x/y symmetry, we find that

$$0 = \frac{w'(0)}{w(x) - w(0)} + \frac{w'(0)}{w(Y_0) - w(0)} - \frac{1}{x} - \frac{1}{Y_0} - xY_0 + tQ(0, 0) + 2\frac{w''(0)}{2w'(0)}.$$

Specializing for instance at $x = 1$ gives an expression of $tQ(0, 0)$. The algebraicity of $Q(0, y)$ (and hence that of $Q(x, y)$ by (3)) is a consequence of this, since applying the analytic invariant lemma to the rational invariant $I_2(y) = \frac{t}{y^2} - \frac{1}{y} - ty$ shows that $w(y)$ is algebraic in y and t , via the solution of an equation with one catalytic variable [BMJ06]. □

5 Differential algebraicity

As recalled in the introduction, quadrant walks have a D-finite generating function if and only if the associated group is finite — we can now say, if and only if they admit a rational invariant (Proposition 4). Still, one outcome of our analytic invariant approach is that *non-linear* differential equations hold for a number of models with an infinite group.

Theorem 11 *For any of the 9 models of Figure 2, the generating function $Q(x, y; t)$ is differentially algebraic (or D-algebraic) in x, y, t . By this, we mean that it satisfies three (non-linear) differential equations with coefficients in \mathbb{Q} : one in x , one in y and one in t .*

The proof builds on Corollary 10 and on the following result, which holds for any non-singular model.

Proposition 12 *The conformal gluing function $w(y; t)$ defined by (14) is D-algebraic in y and t .*

Proof: (sketched). There are three main steps in the proof:

- We first consider the Weierstrass function $\wp(\omega)$ as a function of ω , but also as a function of its periods ω_1 and ω_2 or, alternatively, of the values g_2 and g_3 (also called *invariants* in the elliptic terminology!) defined by

$$g_k(\omega_1, \omega_2) = \sum_{(i,j) \in \mathbb{Z}^2 \setminus \{(0,0)\}} \frac{1}{(i\omega_1 + j\omega_2)^{2k}}.$$

Using some differentiations formulæ borrowed from [AS64], we prove that \wp is DA in ω , g_2 and g_3 .

- Then, we prove that when ω_1, ω_2 are either the functions $\omega_1(t), \omega_2(t)$ given by (15), or the functions $\omega_1(t), \omega_3(t)$ (still given by (15)), then the functions g_2 and g_3 are DA in t . This follows from their expression as modular forms [WW62], and from the fact that modular forms satisfy differential equations [Zag91].
- We conclude using closure properties of D-algebraic functions. \square

6 Further results and final comments

Tutte's invariants offer a new approach of quadrant walks, and we are faced with many open problems, mainly related to the notion of decoupling functions.

- We still need to determine the exact applicability of our approach: which models admit a decoupling function? For a model with finite group, the existence of a decoupling function implies algebraicity. Hence we have found all decoupling functions for walks with finite group. But what about the 51 non-singular models with an infinite group? We have found 9 with a decoupling function and (although not explained in this abstract) we also know that 36 have no decoupling function (this includes for instance the model with jumps $\downarrow, \swarrow, \leftarrow, \nearrow$). This leaves 6 more models which might have decoupling functions.
- We have not considered the 5 singular models. But they do admit weak invariants (though not given by (14)) and this raises the question of finding decoupling functions for them.
- Our results on the nature of $Q(x, y)$ can be summarized as follows:

	Existence of decoupling functions	No decoupling function
Finite group	Algebraic	D-finite
Infinite group	Differentially algebraic	?

Could it be that infinite group models without decoupling function have a non-differentially algebraic generating function?

- Can we obtain explicit differential equations in the D-algebraic cases? One possible approach would be to mimic Tutte's solution of (2): he first found a non-linear differential equation valid for infinitely many values of q (for which $G(1, 0)$ is in fact algebraic), and then concluded by a continuity argument. In our context, this would mean introducing weights so as to obtain algebraic models converging to a D-algebraic one.

- Another aspect, to be explored in the long version of this extended abstract, is the influence of the starting point on the nature of the generating function. As examples, Gessel's and Kreweras' models starting from $(0, 1)$ do not admit decoupling functions, which implies their transcendence.

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A Rational invariants for finite groups

Recall from [BMM10] that there are 23 models with a finite group. First come 16 models with a vertical symmetry, for which $K(x, y) = (1 + x^2)\tilde{a}(y) + x\tilde{b}(y)$. Hence for a pair (x, y) that cancels the kernel, we have $x + \frac{1}{x} = -\frac{\tilde{b}(y)}{\tilde{a}(y)}$. A possible choice of invariants is thus:

$$I_1(x) = x + \frac{1}{x}, \quad I_2(y) = -\frac{\tilde{b}(y)}{\tilde{a}(y)}.$$

We are left with 7 models. We can restrict the discussion to 3 since the invariants of two models differing by a symmetry of the square are related. As these symmetries are generated by the reflection in the first diagonal and the reflection in a vertical, we just need to consider these two cases.

Lemma 13 *Take a model \mathcal{S} with kernel $K(x, y)$ and its diagonal reflection $\tilde{\mathcal{S}}$, with kernel $\tilde{K}(x, y) = K(y, x)$. Then $\tilde{\mathcal{S}}$ admits invariants if and only if \mathcal{S} does, and in this case a possible choice is $\tilde{I}_1 = I_2$ and $\tilde{I}_2 = I_1$. A similar statement holds for the vertical reflection $\overline{\mathcal{S}}$, with kernel $\overline{K}(x, y) = x^2K(1/x, y)$. A possible choice is in this case $\overline{I}_1(x) = I_1(1/x)$ and $\overline{I}_2 = I_2$.*

We can now complete our list of rational invariants: Table 1 gives for the 7 remaining models a pair (I_1, I_2) satisfying the conditions of Lemma 3. Finally, Table 2 gives invariants for the four weighted models of Figure 1.

B Decoupled models

As discussed in Section 3, we have found 4 decoupled models among those with a finite group (and 4 more if we include the weighted models of Figure 1), and 9 with an infinite group. In Tables 3 and 4 we give the corresponding functions F and G , first for the models of Figure 1, then for those of Figure 2.

I_1	$\frac{t}{x^2} - \frac{1}{x} - tx$	$\frac{t}{x^2} - \frac{1}{x} - tx$	$tx^2 - x - \frac{t}{x}$	$tx - \frac{t}{x} + \frac{1+2t}{1+\frac{1}{x}}$	$\frac{t}{x} - tx - \frac{1+2t}{1+x}$	$x + \frac{1}{x} - tx^2 - \frac{t}{x^2}$
I_2	$ty^2 - y - \frac{t}{y}$	$\frac{t}{y^2} - \frac{1}{y} - ty$	$ty^2 - y - \frac{t}{y}$	$\frac{t}{y} - ty - \frac{1+2t}{1+y}$	$\frac{t}{y} - ty - \frac{1+2t}{1+y}$	$y + \frac{1}{y} - ty^2 - \frac{t}{y^2}$

Tab. 1: Rational invariants for models with a finite group: models with no vertical symmetry.

I_1	$\frac{t}{x^2} - \frac{1}{x} - x(1 + \lambda t)$	$\frac{t^2}{x^2} - \frac{(1+2t)t}{x} - (3t + 1)tx - \frac{(1+3t)(4t+1)}{x+1} + \frac{(3t+1)^2}{(x+1)^2}$	see Lemma 13 and the previous example
I_2	$t^2y + \frac{1+\lambda t}{y+1} - \left(\frac{1+\lambda t}{y+1}\right)^2$	$\frac{t^2}{y^2} - \frac{(1+2t)t}{y} - (3t + 1)ty - \frac{(1+3t)(4t+1)}{y+1} + \frac{(3t+1)^2}{(y+1)^2}$	

Tab. 2: Rational invariants for weighted models.

Model						
F	$-\frac{1}{x}$	$-\frac{1}{x}$	$-x - \frac{1}{x}$	$-x + \frac{1}{x} - \frac{1+3t}{t(1+x)}$	$-x^2 + x(1 + \frac{1}{t}) + \frac{3+\frac{1}{t}}{x}$	$-x - \frac{1+3t}{t(1+x)}$
G	$-\frac{1}{y}$	$-\frac{1}{t(1+y)}$	$-\frac{1+\lambda t}{t(1+y)}$	$-y + \frac{1}{y} - \frac{1+3t}{t(1+y)}$	$-y^2 + y(1 + \frac{1}{t}) + \frac{3+\frac{1}{t}}{y}$	$-y - \frac{1}{y}$

Tab. 3: Decoupling functions for algebraic models.

Model							
F	$-x^2 + \frac{x}{t}$	$-x^2 + \frac{x}{t}$	$-\frac{1}{x}$	$\frac{1}{x^2} - \frac{1}{xt} - x$	$-\frac{1}{x}$	$-\frac{1+t}{t(x+1)}$	$-x^2 + \frac{x}{t}$
G	$-\frac{1}{y}$	$-y - \frac{1}{y}$	$-y - \frac{1}{y}$	$-y^2 + \frac{y}{t} + \frac{1}{y}$	$-\frac{1+t}{t(y+1)} - y$	$-\frac{1}{y}$	$-y - \frac{1}{y}$

$-\frac{1}{x} - x$	$\frac{(t+1)^2}{(x+1)^2 t^2} - \frac{2t^2 + 3t + 1}{(x+1)t^2} - \frac{1}{x} - x$
$-\frac{1}{y} - y$	$-\frac{1}{y^2} + \frac{1}{ty} + \frac{(t+1)y}{t} - y^2$

Tab. 4: Decoupling functions for nine infinite group models.