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# Comparison between continuous and localized methods to evaluate the flow rate through containment concrete structures

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**Abstract.** In this contribution, different techniques are compared to evaluate the gas flow rate through a representative section of a reinforced and prestressed concrete containment structure. A continuous approach is first applied which is based on the evaluation of the gas permeability as a function of the damage variable. The calculations show that the flow rate becomes significant only when the damage variable crosses the section. But in this situation, the continuous approach is no longer fully valid. That is why localized approaches, based on a fine description of the crack openings, are then investigated. A comparison between classical simplified laws (Poiseuille flow) and a more refined model which takes into account the evolution of the crack opening in the depth of the section enables to define the validity domain of the simplified laws and especially the definition of the associated “reference opening”.

**Keywords.** reinforced concrete, gas flow, permeability, crack

## 1. Introduction

The internal confinement vessel of nuclear power plants (1300 and 1450 MWe), combined with the external vessel and the ventilation and filtration of the capacity delimited by the two vessels, represent the third passive barrier for the environmental protection in case of accidents. Considering that there is no liner on the internal vessel and only concrete has to provide the air tightness, it is essential to estimate the associated potential leakage rate, especially during the integrity tests which are realized every ten years to check the effective ability of the containment building to protect the environment. As the transfer properties (permeability for example) are a direct function of the mechanical degradation (Picandet et al, 2001), it also supposes to correctly characterize the mechanical evolution of the reinforced prestressed concrete structure.

Concerning the mechanical behavior, many studies have been launched worldwide, especially to characterize the failure pressure, which corresponds to the maximum admissible pressure that the structure is able to support. For example, Hu and Lin (2006), Lee (2011) or Barbat et al (1998) performed the ultimate analysis of prestressed containment structures using shell or 3D elements. These computations are generally based on real industrial cases or on scaled experiments (one-sixth scale Sandia experiment (EPRI, 1989), one-third scale MAEVA mock-up (Granger et al, 2001) or one-fourth scale BARCOM tests (BARC, 2007)).

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In the situation in which information about the leakage rate is also required ((Granger et al, 2001) for example), two main techniques are generally used. In the first one, hydro (and/or hygro) thermo mechanical equations are solved. The transfer properties (gas and liquid permeability especially) are generally functions of the mechanical damage (damage – permeability law in (Gawin et al, 2003) or permeability as a function of the microcrack density in (Bary et al, 2008) for example). This technique, based on a continuous description of the mechanical problem, is known to be particularly representative until the damage variable becomes localized. At this stage, discrete approaches are preferred. The fluid flow inside localized cracks is then computed from the crack openings using Poiseuille’s law (Simon et al, 2007) among others. To bridge the gap between the two approaches, models are proposed to describe the evolution of the transfer property from a diffuse to a discrete regime (evolution of the permeability as a function of the crack width (Ozbolt et al, 2010) or relationship between permeability and damage that is consistent with the two situations (Pijaudier-Cabot et al, 2009)). These different contributions, among others, clearly show that techniques exist to evaluate fluid transfer through concrete structures. But their applications to containment buildings of nuclear power plants are rather rare. For integrity tests (increasing pressure inside the volume during one day), the relevance of the existing methods, and their predominance, may be questioned. What is the importance of the diffuse regime (Darcy’s law) compared to localized one (Poiseuille’s law)? Are engineering laws, based on average values of the crack openings, relevant compared to more sophisticated approaches which take into account the refined geometry of the cracks? To try to provide answers, different techniques are compared in this contribution on a simplified portion of a containment building, which corresponds to a section of the current wall. Starting from a given mechanical state (distribution of the damage variable and/or crack openings), continuous and localized approaches are applied to evaluate the associated leakage rates.

In a first part, the reference structure is presented and the mechanical computation is performed to obtain the initial states of damage. Then, a method to evaluate the fluid transfer using Darcy’s law is applied (Jason et al, 2007). Finally, localized laws are investigated, using two methods: simplified engineering equations (Poiseuille flow with average values of the crack openings) and a more refined approach that takes into account the geometry of the crack. Conclusions about the relevance of each method are finally provided.

## **2. Simulation of the mechanical behavior**

The fluid flow through concrete is directly influenced by the mechanical state, through the damage distribution or the crack opening. Its determination thus needs to know the reference mechanical state. This is defined in this section.

### **2.1. Description of the reference structure**

The studied structure is based on the experiment performed in (Hermann et al, 2009), whose principle is to represent the mechanical behavior of a Representative Structural Volume of a French containment building. The aim is to be as close as possible to an extraction of the current wall (Jason et al, 2010). The structure is under pressure loadings to simulate integrity tests (Figure 1). To simplify the simulation, only one section of the volume is considered in this contribution. The geometry of the tested specimen is presented in Figure 2 (top). It includes concrete and one tendon (which means steel duct, grout and steel tendon).

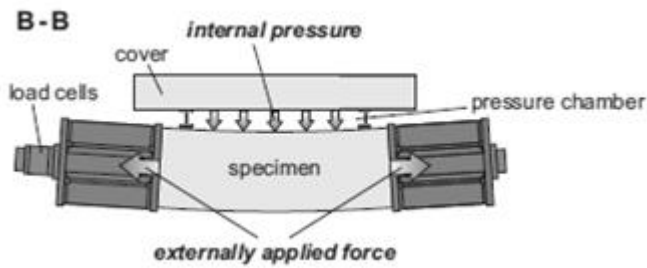


Figure 1. Description of the experiment on the Representative Structural Volume (from (Hermann et al, 2009))

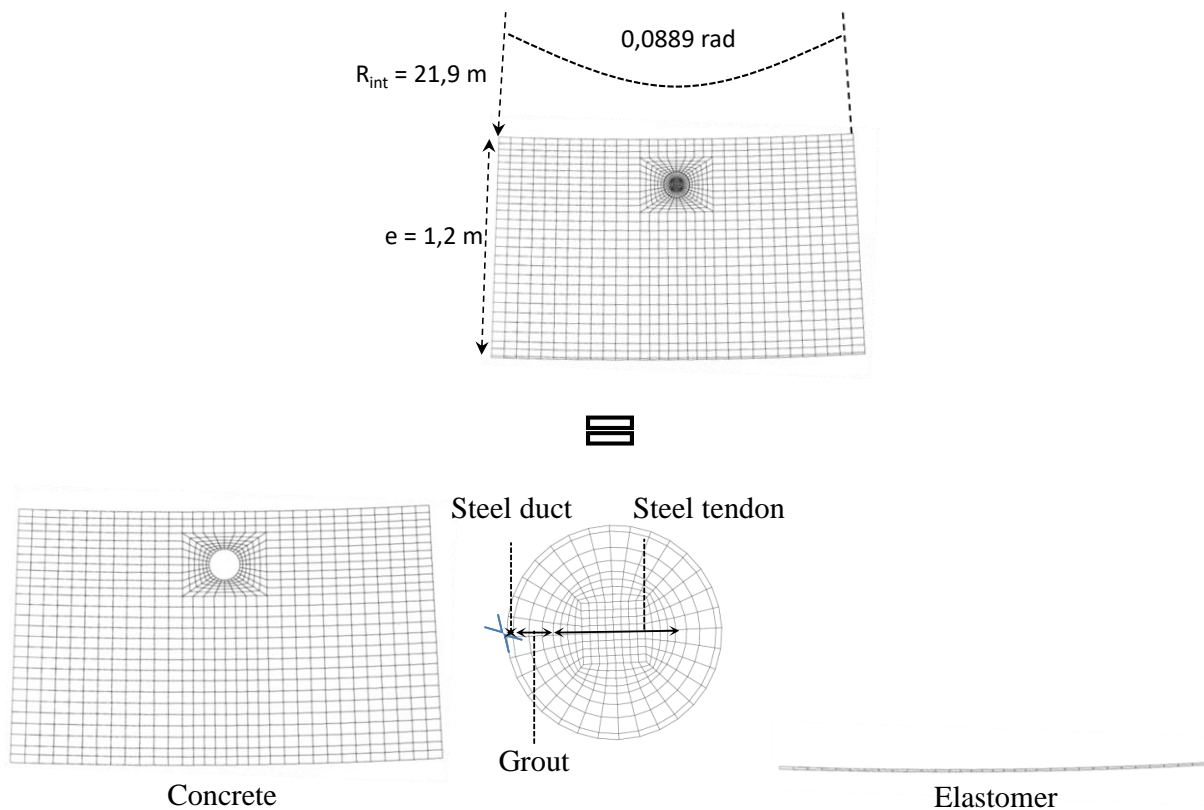


Figure 2. Description of the simulated structure.

The structure is supported on an elastomer which is also represented in the simulation (Figure 2 bottom). The material properties have been chosen to be as representative as possible to the experiment. For the boundary conditions (Figure 3), restrained displacements are considered at the bottom of the elastomer (zero displacement) while a perfect relation is supposed between the elastomer and the concrete, the steel duct and the concrete, the steel duct and the grout and the grout and the steel tendon (simplified hypothesis). For the loadings (Figure 3), an increasing internal pressure  $P_{int}$  is applied along the internal line to represent the integrity test loading. A constant compressive pressure ( $P_{pre} = 6.75 \text{ MPa}$ ) and a tensile pressure  $P_{pint}$ , proportional to the internal pressure, are applied on each lateral line. They model the effect of the horizontal prestress and the orthoradial effect of the internal pressure respectively:

$$P_{pint} = \frac{P_{int} \cdot R_{int}}{e}$$

The simulation (plane strain) is performed using the isotropic damage model developed in its initial form by Mazars (1984) and implemented in the finite element code Cast3M (2013). The law characterizes the mechanical degradation through an isotropic scalar damage variable ranging from 0 (safe material) to 1 (fully damaged material).

## 2.2. Mechanical simulation

The results of the mechanical simulation are presented in this section. Figure 4 gives the evolution of the orthoradial displacement of a point located on the internal line as a function of the applied internal pressure. For a zero pressure, the initial orthoradial displacement is positive (compression). This is due to the horizontal prestress which is applied before the internal pressure. With an increasing  $P_{int}$ , the orthoradial displacement decreases and gradually becomes negative (tension). Once the internal pressure has reached its maximum value  $P_{max}$ , a nonlinear regime appears. It can be associated with the development of the mechanical degradation.

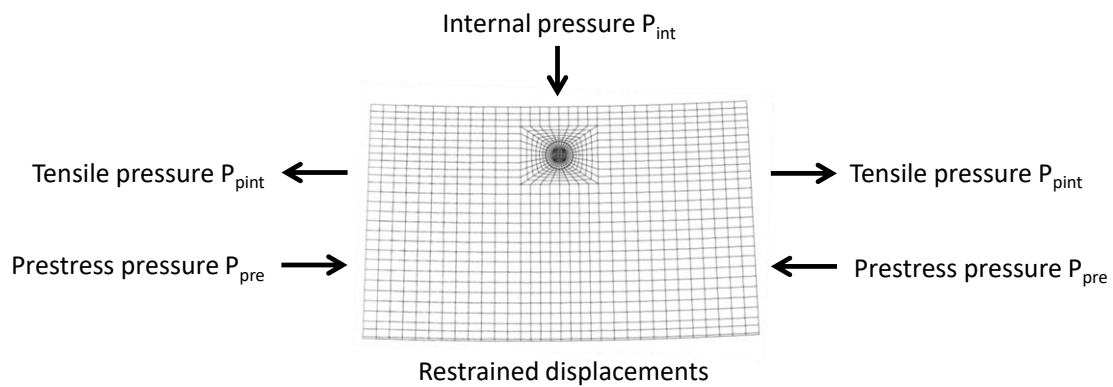


Figure 3. Boundary conditions and loadings

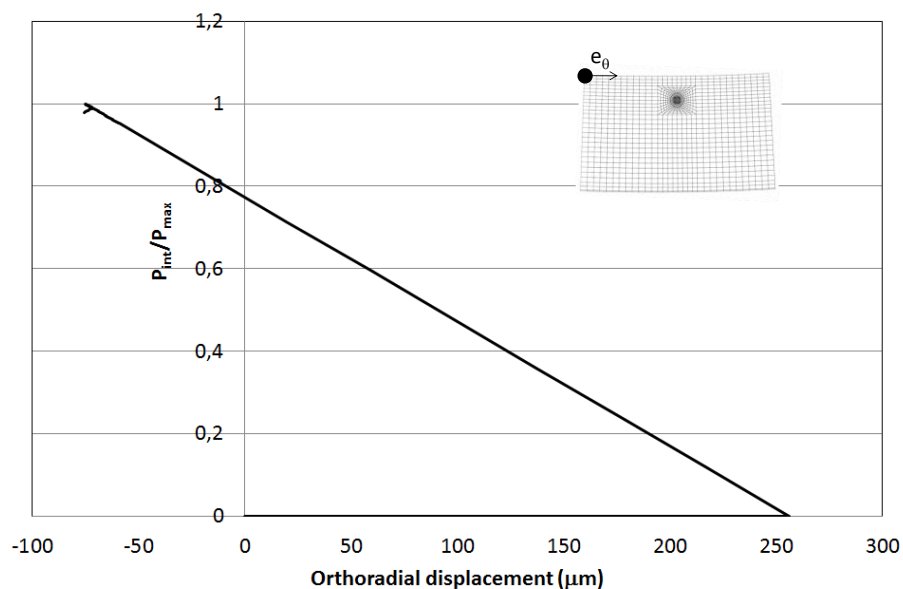
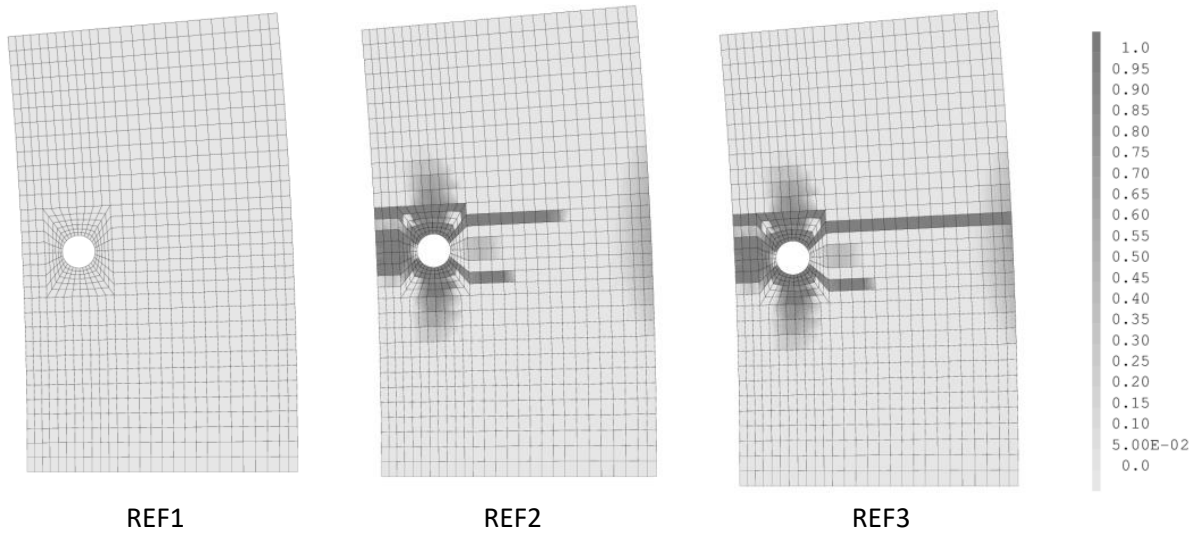


Figure 4. Pressure – displacement curve for the simulated structure



**Figure 5. Reference damage distributions obtained from the mechanical simulation**

Figure 5 gives the distribution of the damage at different loading steps. In the first case (named “REF1”), the damage variable is constant equal to zero and the response is still elastic. In the second case (beginning of the nonlinear phase), the damage develops from the vertical tendon which corresponds to a geometrical and a material heterogeneity in the volume (Jason et al, 2010). Finally, in “REF3” situation (end of the computation), damage is fully localized and crosses the section (from the inside to the outside of the volume).

### 3. Evaluation of the fluid flow through continuous approach

In each damaged situation (“REF1”, “REF2” or “REF3”), the flow rate can be estimated. In this section, it is calculated using Darcy’s law where the gas permeability is a direct function of the damage variable.

#### 3.1. Description of the method

To calculate the fluid flow, the methodology from (Jason et al, 2007) is used. It is based on the resolution of the mass balance equations ((Bear, 1991) or (Mainguy et al, 2001)). It assumes that the gaseous phase does not contain vapor. This hypothesis fits to the case of integrity tests of containment facilities where dry air pressure is applied inside the concrete vessel. Moreover, no interaction between the air and the liquid phases is assumed.

Considering the gas transport, the associated mass balance equation is written as:

$$\frac{\partial}{\partial t} (\phi \rho_g (1 - S_l)) = -\nabla \cdot (\phi (1 - S_l) \rho_g v_g) \quad (1)$$

with  $\phi$  the material total porosity (ratio of pore volume to the total volume),  $S_l$  the degree of saturation (ratio of water volume to the pore volume),  $\rho_g$  the gas mass density and  $v_g$  the gas velocity.

$v_g$  is a function of the gas pressure  $P_g$  using Darcy law :

$$\phi(1 - S_l)v_g = -\frac{K_g}{\eta_g} \nabla(P_g) \quad (2)$$

where  $K_g$  is the gas permeability and  $\eta_g$  the gas dynamic viscosity.

Considering the gas as “ideal”, the hydraulic problem is finally driven by the equation:

$$(1 - S_l)\phi \frac{\partial P_g}{\partial t} = -\nabla \cdot (-\lambda_p(P_g) \nabla(P_g)) \quad (3)$$

with  $\lambda_p(P_g)$  the “diffusive” coefficient :

$$\lambda_p(P_g) = \frac{K_g}{\eta_g} P_g \quad (4)$$

From this equation, it is clear that the gas transfer is directly influenced by the value of the gas permeability. One of the crucial point is thus to determine the key parameters that influence the hydraulic conductivity. In this contribution, the evolution of the gas permeability is a function of the damage variable. It first follows the equation from (Jason et al, 2007):

$$\begin{aligned} K_g &= K_0 \text{ if } D < 0.035 \\ K_g &= K_0 \cdot 10^{8.67D - 0.3} \text{ if } D \geq 0.035 \end{aligned} \quad (5)$$

where  $K_0$  is the initial permeability.

Eq. (3) is solved and provides the gas pressure. From its distribution and the distribution of its gradient, Eq. (2) gives the apparent gas velocity. The flow rate is finally computed by integration along the outside line. The principle of the method is summarized in Figure 6.

### 3.2. Application to the reference structures

The method is applied to the structure described in section 2. The loading and the boundary conditions are given in Figure 7. The internal gas pressure is imposed following the chronology of the integrity tests. It supposes a linear increase from the atmospheric pressure  $P_{atm}$  to 0.53 MPa in 24 hours. The inside pressure is then constant for one other day. The total simulated time is thus 48 hours. The external pressure is kept constant equal to the atmospheric pressure.

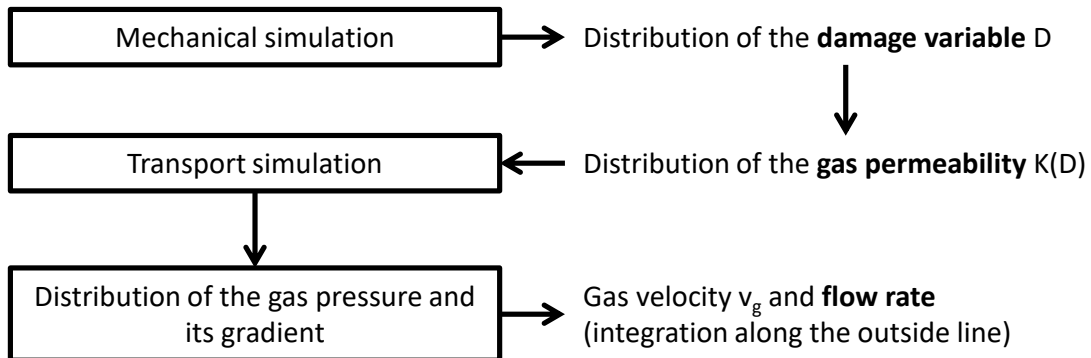


Figure 6. Principle of the calculation of the flow rate

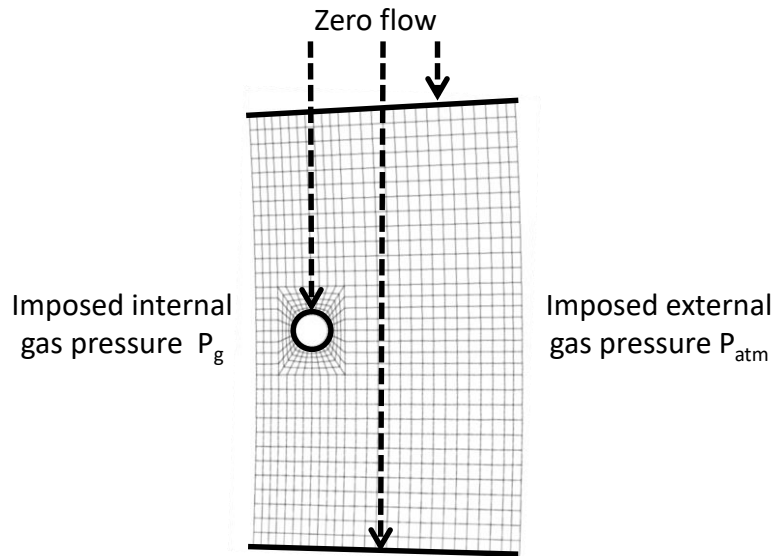


Figure 7. Description of the transport simulation

Variables	Symbol	Value
Degree of saturation	$S_l$	70 %
Material porosity	$\phi$	0.15
Dynamic viscosity	$\eta_g$	$186 \cdot 10^{-7} \text{ kg.m}^{-1}.\text{s}^{-1}$
Initial permeability	$K_0$	$10^{-19} \text{ m}^2$

Table 1. Parameters of the simulation.

The parameters of the simulation are summarized in Table 1. To simplify the resolution, a constant mean value of the saturation degree is chosen, in accordance with the values calculated in (Granger, 1995) or in (Jason et al, 2007). The initial permeability has been computed to include the effect of the saturation degree ((Jason et al, 2007) or (Monlouis-Bonnaire et al, 2003) for example).

To evaluate the impact of the mechanical degradation, the method is applied using each damage distribution obtained in Figure 5. It thus supposes three different simulations and three different values of the flow rate. Each value of the flow rate corresponds to one mechanical state (no damage ("REF1"), damage initiation ("REF2") and localized damage band ("REF 3")).

The distributions of the gas pressure are given in Figure 8 ( $t = 48\text{h}$ ). They clearly show the impact of the damage variable. On the undamaged structure, the "diffusion" of the pressure is very low, due to the low values of the permeability. On the contrary, with the development of the damage, the pressure inside the damaged zones quickly reaches the value of the internal pressure.

In cases "REF1" and "REF2", the permanent regime is not reached at the end of the computation ( $t=48$  hours). The diffusion of the pressure is limited due to the portion of the volume which remains undamaged (low values of the gas permeability). On the contrary, in "REF3" case, a more gradual distribution of the gas pressure is obtained along the reference line (Figure 9). The steady state is reached with a classical parabolic evolution.



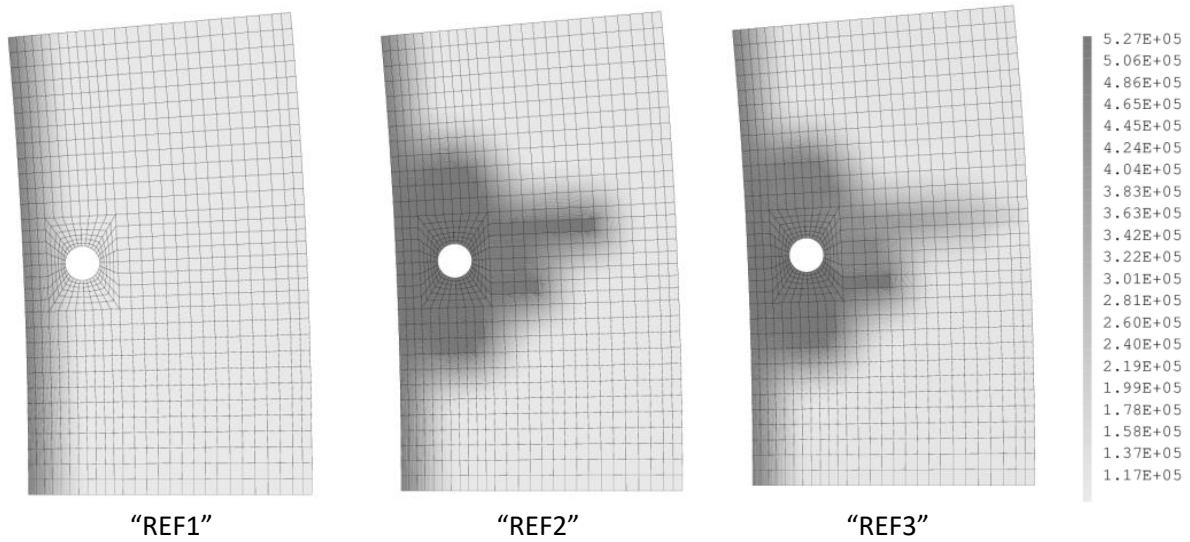


Figure 8. Distribution of the gas pressure obtained for each damage situation at the end of the transport simulation

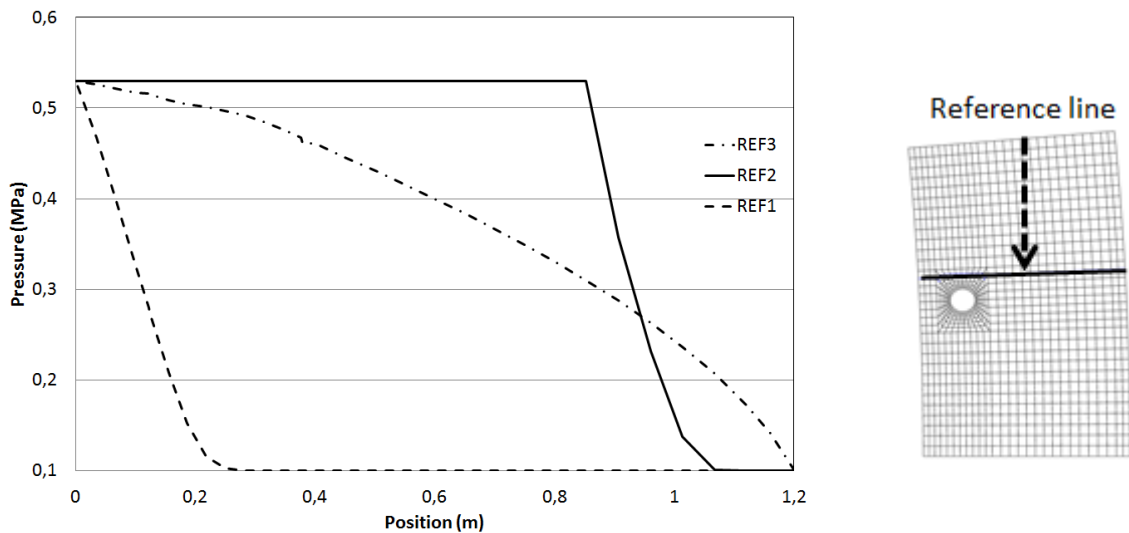


Figure 9. Evolutions of the gas pressure along the reference line (bold line on the right) for the three reference damage states

Damage reference state	“REF1”	“REF2”	“REF3”
External flow rate ( $\text{m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$ )	$1.47 \cdot 10^{-23}$	$1.47 \cdot 10^{-9}$	$6.55 \cdot 10^{-2}$

Table 2. External flow rate computed at the end of the computation

The external flow rate is then computed using Eq. (2) (Table 2), per unit of height ( $\text{m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$ ). It shows that the flow rate is very low until the damage zone crosses the section. In cases “REF1” and “REF2”, the undamaged zone prevents the leakage. Even when interpolated to the whole containment structure (height equal to 60m and angular section equal to  $2\pi$ ), this external flow rate is significantly smaller than the admissible flow rate.

The flow rate obtained for “REF1” state can be easily compared to the permanent flow rate  $Q_{statio.}$ , using the equation (Picandet et al, 2001) :

$$Q_{statio.} = \frac{K_g}{2\eta_g} \frac{(P_{int}^2 - P_{atm}^2)}{eP_{atm}} l \quad (6)$$

where  $l$  is the radial length ( $0.0889 \cdot R_{int}$ ) (Figure 2). It comes  $Q_{statio.} = 1.18 \cdot 10^{-8} \text{ m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$ . This value is significantly higher than the simulated one. It confirms that the permanent regime is not reached at the end of the simulation.

It is clear from Eq. (2) that the choice for the damage-permeability law may influence the computed values of the flow rate (Davie et al, 2012). To investigate this effect and to corroborate the conclusions, two other relations are tested (Eq. (7) and Eq. (8) from (Picandet et al, 2001) and (Bary,1996) respectively)

$$K_g = K_0 \exp((\alpha D)^\gamma) \quad (7)$$

$$K_g = K_0 10^{\alpha D} \quad (8)$$

The parameters of the laws are given in Table 3. The three evolutions are presented in Figure 10. The differences are essentially observed for high values of the mechanical damage. Table 4 gives the computed external flow rates with the different permeability laws.

(Picandet et al, 2001)		(Bary, 1996)
$\alpha$	$\gamma$	$\alpha$
11.3	1.64	4

Table 3. Parameters for the permeability laws

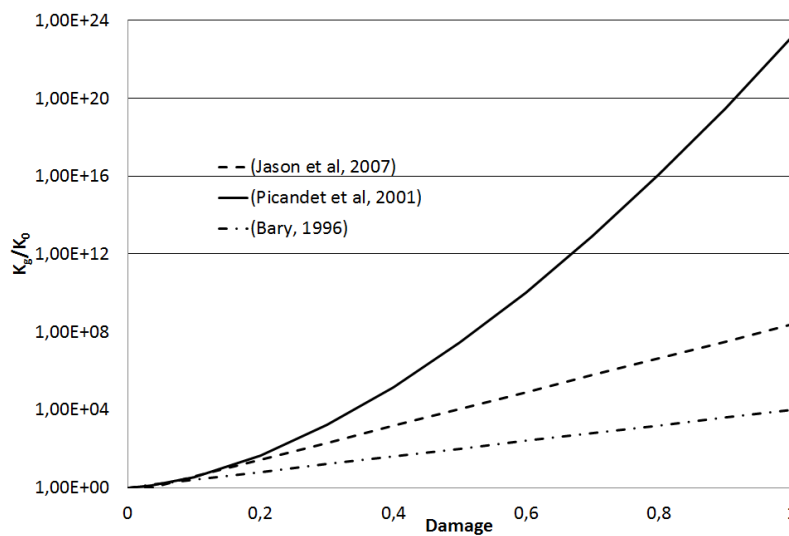


Figure 10. Damage-permeability laws

Permeability law	Case "REF1"	Case "REF2"	Case "REF3"
(Jason et al, 2007)	$1.47 \cdot 10^{-23}$	$1.47 \cdot 10^{-9}$	$6.55 \cdot 10^{-2}$
(Picandet et al, 2001)	$1.47 \cdot 10^{-23}$	$1.18 \cdot 10^{-9}$	0.167
(Bary, 1996)	$1.47 \cdot 10^{-23}$	$2.81 \cdot 10^{-10}$	$2.64 \cdot 10^{-6}$

Table 4. External flow rates (in  $\text{m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$ ) with different permeability laws

As previously mentioned, the flow rates in cases “REF1” and “REF2” are very low. In case “REF3”, the effect of the damage-permeability law is clearly underlined. It thus confirms the previous conclusions: the flow rate becomes significant only when the damage variable crosses the section. But in this situation, the proposed continuous approach is no longer fully valid. Moreover, as the permeability only depends on the damage variable, the flow rate reaches its maximum value once the damage is equal to one along the crossing line. As a consequence, it does not evolve any more after the permanent state, even if the crack opening increases. That is why in this case, localized methods are preferred.

#### 4. Evaluation of the fluid flow by localized approaches

Two methods based the definition of the crack openings are proposed. Only “REF3” case is considered as these approaches are only applicable when a discrete crack is developed through the section.

##### 4.1. Engineering practice

When localized cracks are observed, engineering laws are often used to evaluate the leakage rate through the concrete wall. The Poiseuille equation in infinite parallel plates is generally considered. It supposes a laminar flow inside concrete cracks ((Gelain and Vendel, 2008) for example):

$$\frac{Q}{\xi} = \frac{l}{24RT\eta_g\rho_0} \frac{(p_1^2 - p_2^2)}{e} w_r^3 \quad (9)$$

where  $Q$  is the volumetric flow rate,  $l$  the crack extent,  $R$  the mass perfect gas constant,  $T$  the gas temperature,  $p_1$  and  $p_2$  respectively the inside and outside gas pressures,  $e$  the crack length,  $w_r$  the reference crack opening,  $\mu$  the gas dynamic viscosity and  $\rho_0$  the mass density.

$\xi$  represents the effect of the tortuosity and of the roughness of the cracks. As its determination is still under discussion in the literature ((Picandet et al, 2001), (Suzuki et al, 1992) for example), with values ranging from 0.08 to 0.5, only the ratio  $\frac{Q}{\xi}$  will be studied in this contribution.

Eq. (9) depends on the crack openings which need to be computed from the damage distribution proposed in “REF3” situation. Using a damage model for concrete asks the question of how to characterize the crack discontinuity from a continuous description of the problem. To answer this question, the principle proposed by (Matallah et al. 2010) and successfully applied in (Jason et al, 2013) is used. It consists in defining a cracking strain  $\varepsilon_f$  from the distribution of the total strain  $\varepsilon$  and of the total stress  $\sigma$  following the equation:

$$\varepsilon_f = \varepsilon - \varepsilon_{el} \quad (12)$$

where

$$\varepsilon_{el} = \frac{1+\nu}{E} \sigma - \frac{\nu}{E} tr(\sigma)I \quad (13)$$

with  $E$  and  $\nu$  respectively the concrete Young modulus and Poisson ratio. “tr” stands for the trace operator and  $I$  is the identity matrix. With this technique, the cracking strain corresponds to the inelastic part of the total strain. From the distribution of the cracking strain, the crack opening is calculated by multiplying it by the length  $h_n$  of each concrete element in the direction  $n$  normal to the crack (computed from the direction of the strain localization bands)

$$w_n = (n^t \varepsilon_f n) \cdot h_n \quad (14)$$

This technique is applied to evaluate the flow rate in “REF3” case. The results are illustrated in Figure 11. A gradual increase of the crack opening from the inside to the outside of the surface is observed, underlining the role of the vertical tendon that initiates the crack but also “prevents” its opening.

Eq. (9) is applied to the reference line (Figure 11).  $p_1$  and  $p_2$  pressures are taken equal to 0.45 MPa (from the value obtained at  $x = 0.4$  m in Figure 9) and 0.1 MPa (atmospheric pressure at  $x = 1.2$  m) respectively. The temperature is equal to Eq. (9) supposes the definition of a “reference” crack opening. Different situations are considered in this contribution:  $w_r$  equal to the maximum crack opening along the line (251  $\mu\text{m}$ ) (case 1),  $w_r$  equal to the mean value of the crack opening along the line (183  $\mu\text{m}$ ) (case 2),  $w_r = \sqrt[3]{\frac{1}{i}}$  in which  $i$  is the mean value of  $\frac{1}{w^3}$  (152  $\mu\text{m}$ ) (case 3) and finally  $w_r$  equal to the minimum crack opening along the line (90  $\mu\text{m}$ ). Table 5 gives the values of the external flow rate obtained for each case, using the parameters provided in

Variables	Symbol	Value
Mass perfect gas constant	$R$	287.058 J.kg <sup>-1</sup> .K <sup>-1</sup>
Temperature	$T$	293 K
Dynamic viscosity	$\eta_g$	186 10 <sup>-7</sup> kg.m <sup>-1</sup> .s <sup>-1</sup>
Mass density	$\rho_0$	1.204 kg <sup>-1</sup> .m <sup>-3</sup>

Table 6. They are calculated per unit of height ( $l = 1\text{m}$ ). It shows clear differences in the results, depending on the importance given to the large openings compared to the small ones. In order to investigate the definition of the reference opening, this “engineering” method is compared to a more refined one in the next section.

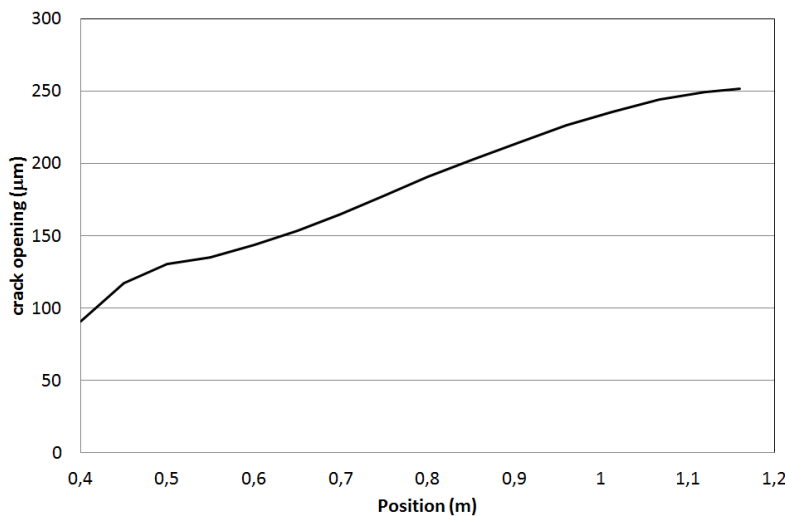


Figure 11. Crack opening along the localized reference line

Case 1	Case 2	Case 3	Case 4
$8.45 \cdot 10^{-2}$	$3.26 \cdot 10^{-2}$	$1.87 \cdot 10^{-2}$	$3.88 \cdot 10^{-3}$

Table 5. Flow rates in  $\text{m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$  for the different values of the reference crack opening

Variables	Symbol	Value
Mass perfect gas constant	$R$	$287.058 \text{ J} \cdot \text{kg}^{-1} \cdot \text{K}^{-1}$
Temperature	$T$	293 K
Dynamic viscosity	$\eta_g$	$186 \cdot 10^{-7} \text{ kg} \cdot \text{m}^{-1} \cdot \text{s}^{-1}$
Mass density	$\rho_0$	$1.204 \text{ kg}^{-1} \cdot \text{m}^{-3}$

Table 6. Parameters for the flow rate calculation

#### 4.2. Refined approach

As the definition of the “reference” crack opening is essential in the definition of the fluid flow, a refined technique is now proposed. This approach is based on the work from (Simon et al, 2007) and (Caroli et al, 1995). The model was initially developed to evaluate the leakage of an air steam mixture through a traversing crack taking into account condensation and the evolution of the crack opening along the channel axis. In this contribution, it is applied to the simplified configuration where only dry air is considered, to be in accordance with the hypothesis chosen in the previous section (Figure 12). The main equations are the balance equations in the permanent state:

$$\frac{\partial q}{\partial x} = 0$$

$$\frac{\partial qu}{\partial x} = -e \frac{\partial P}{\partial x} - f \frac{\rho u^2}{4} \quad (9)$$

where  $x$  is the channel axis coordinate,  $q$  the total mass flow rate per extent length unit,  $u$  the mean velocity,  $f$  the friction factor,  $P$  the total pressure,  $e$  the crack opening and  $\rho$  the density.

The friction factor is computed using the following equation

$$f = \text{Max}\left(\frac{96}{\text{Re}}; f_c\right) \quad (10)$$

where  $\text{Re}$  is the Reynolds number.  $f = \frac{96}{\text{Re}}$  corresponds to the laminar flow condition. For turbulent flow, the Colebrook formula is used:

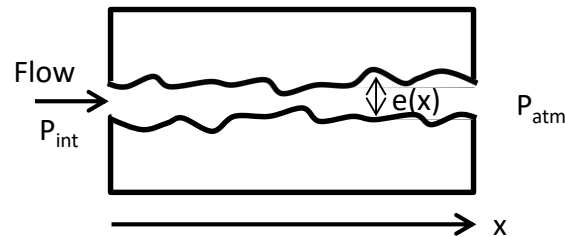
$$\frac{1}{\sqrt{f_c}} = -2 \log\left(\frac{\lambda}{3.7} + \frac{2.51}{\text{Re} \sqrt{f}}\right)$$

where  $\lambda$  is the relative roughness of the channel surface

$$\lambda = \frac{\varepsilon}{2e}$$

with  $\varepsilon$  the crack roughness.

Compared to the previous approach, the refined model enables to take into account the evolution of the crack opening along the damaged line. It also takes into account the effect of the crack roughness.



**Figure 12. Configuration for the fluid flow calculation**

Following the recommendations from (Simon et al, 2007), the crack roughness is chosen equal to 100  $\mu\text{m}$  to be of the same order of magnitude as the crack opening. The flow rate is computed using the same boundary conditions as the “engineering” calculation.

A value of  $9.30 \cdot 10^{-3} \text{ m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$  is obtained. Compared to the engineering laws, it means that:

- the values calculated with the simplified engineering laws have the good order of magnitude
- the small crack openings have the most important influence, as the closer values are obtained with “case 3” and “case 4” definition.
- the engineering laws are conservative (except if the minimum value of the crack opening is chosen) as they give overestimated values of the flow rate. It can be explained by the crack roughness which is taken into account through the friction coefficient in the refined approach and which has a direct influence on the computed flow rate.

To underline this last point, the flow rate is also computed considering a zero roughness for the crack channel. The computed value ( $2.24 \cdot 10^{-2} \text{ m}^3 \cdot \text{s}^{-1} \cdot \text{m}^{-1}$ ) is very close to the one obtained in case 3 with the simplified Poiseuille law (Table 3). It first confirms the influence of the small crack openings compared to the larger ones. It also illustrates the pertinence of case 3 definition for the reference opening, compared to the minimum opening (case 4). Finally, it shows the effect of the crack roughness on the flow rate (flow rate divided by 2 for the chosen parameters).

## 5. Conclusions

In this contribution, different techniques were applied to evaluate the flow rate through concrete structures in the conditions of integrity test loadings. With the continuous approach, based on a damage – permeability law, the low permeability prevents any significant leakage in the undamaged zones. The flow rate thus becomes significant only when the damage variable crosses the section. But in this situation, the continuous approach is no longer fully valid.

In this case, localized approaches based on the evaluation of the crack openings were applied. A comparison with a refined model shows that the classical engineering laws (Poiseuille flow) are valid

if the reference crack opening is chosen to take into account the effect of the small openings especially. An appropriate definition is also proposed. It supposes to know the evolution of the crack opening in the depth of the structure, which may be difficult in an experimental situation.

Finally, as the flow rate in containment buildings is directly influenced by the cracks, it supposes to simulate every effect which influences their apparition (steel-concrete bound for example (Casanova et al, 2012)) but also to precisely predict the local crack properties (influence of the roughness in the friction factor when using the refined approach but also of the tortuosity which directly influences the value of  $\xi$  in Poiseuille law). These points will be further investigated in a next study.

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