

CHARACTERISTIC FUNCTIONS ON THE BOUNDARY OF A PLANAR DOMAIN NEED NOT BE TRACES OF LEAST GRADIENT FUNCTIONS

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CHARACTERISTIC FUNCTIONS ON THE BOUNDARY OF A PLANAR DOMAIN NEED NOT BE TRACES OF LEAST GRADIENT FUNCTIONS

MICKAËL DOSSANTOS

ABSTRACT. Given a smooth bounded planar domain, we construct a compact set on the boundary s.t. its characteristic function is not the trace of a least gradient function. This generalize the construction of Spradlin and Tamasan [ST14] on the disc.

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1. INTRODUCTION

We let Ω be a bounded C^2 domain of \mathbb{R}^2 . For a function $h \in L^1(\partial\Omega, \mathbb{R})$, the least gradient problem with boundary datum h is the problem:

(1)
$$\min\left\{\int_{\Omega} |Dw| \mid w \in BV(\Omega) \text{ and } \operatorname{tr}_{\partial\Omega} w = h\right\}.$$

In the above minimization problem, $BV(\Omega)$ is the space of functions of bounded variation. It is the space of functions $w \in L^1(\Omega)$ having a distributional gradient Dw which is a bounded Radon measure.

If the minimization problem (1) admits solutions, such minimal functions are called *functions of least gradient*. Sternberg, Williams and Ziemmer proved in [SWZ92] that if $h : \partial \Omega \to \mathbb{R}$ is a continuous map and if $\partial \Omega$ satisfies some geometric properties then Problem (1) admits a unique solution.

On the other hand, Spradlin and Tamasan [ST14] proved that, for the disc $\Omega = \{x \in \mathbb{R}^2 \mid |x| < 1\}$ [the disc satisfies the geometric hypotheses of [SWZ92]], we may find a function $h_0 \in L^1(\partial\Omega)$ which is not continuous

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s.t. Problem (1) has no solution. The function h_0 is the characteristic function of a Cantor set $\mathcal{K} \subset \mathbb{S}^1 = \{x \in \mathbb{R}^2 \mid |x| = 1\}$

The goal of this article is to extend the main result of [ST14] for a C^2 bounded open set $\Omega \subset \mathbb{R}^2$. We prove the following theorem:

Theorem 1. Let $\Omega \subset \mathbb{R}^2$ be a bounded C^2 open set. Then there is a measurable set $\mathcal{K} \subset \partial \Omega$ s.t. the minimization problem

(2)
$$\min\left\{\int_{\Omega} |Dw| \mid w \in BV(\Omega) \text{ and } \operatorname{tr}_{\partial\Omega} w = \mathbb{I}_{\mathcal{K}}\right\}$$

 $has \ no \ solution.$

The above theorem has been proved when $\Omega = \mathbb{D}$ is the unit disk in [ST14].

The calculations in [ST14] are specific to the case $\Omega = \mathbb{D}$. The proof of Theorem 1 relies on new arguments for the construction of the Cantor set \mathcal{K} and in the strategy of the proof.

2. Strategy of the proof

2.1. The model problem. We present the strategy developed to prove Theorem 1 by proving its adaptation for $\Omega =]0,1[^2$. Obviously this model case does not satisfy the hypothesis of regularity on Ω but it allows to make simple calculations.

We thus prove the following result:

Theorem 2. Let $\tilde{\mathcal{K}}$ be a fat Cantor set [e.g. a Smith-Volterra-Cantor set] supported in $\left[\frac{1}{4}, \frac{3}{4}\right]$, then letting $\mathcal{K} = \tilde{\mathcal{K}} \times \{0\}$, Problem (2) does not admit a solution.

This section is devoted to the proof of Theorem 2. The proof is done arguing by contradiction. We assume that there exists u_0 a solution of Problem (2). We obtain a contradiction in 3 Steps.

Step 1. Upper bound

Using a result in [Giu84] [Theorem 2.16 & Remark 2.17] we have

(3)
$$\min\left\{\int_{\Omega} |Dw| \mid w \in BV(\Omega) \text{ and } \operatorname{tr}_{\partial\Omega}w = h\right\} = \int_{\Omega} |Du_0| \le \|\mathbb{1}_{\mathcal{K}}\|_{L^1(\partial\Omega)} = |\mathcal{K}|$$

Here $|\mathcal{K}|$ is the length of \mathcal{K} .

Estimate (3) follows from Theorem 2.16 & Remark 2.17 in [Giu84]. By combining Theorem 2.16 & Remark 2.17 in [Giu84] we may prove that for all $\varepsilon > 0$ there exists a map $u_{\varepsilon} \in BV(\Omega)$ s.t.

$$\int_{\Omega} |Du_{\varepsilon}| \leq (1+\varepsilon) || \mathbb{1}_{\mathcal{K}} ||_{L^{1}(\partial\Omega)} \text{ and } \operatorname{tr}_{\partial\Omega} u_{\varepsilon} = \mathbb{1}_{\mathcal{K}}.$$

The proof of this argument is presented in [Giu84] in a special context ⁽¹⁾. The adaptation for Ω a C^2 set is presented Appendix C. An easy adaptation of the argument may be done for $\Omega =]0, 1[^2$.

Step 2. Saturation of (3) [see (6)] We fix $(u_n)_n \subset C^{\infty}(\Omega) \cap BV(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} u_n = \mathbb{1}_{\mathcal{K}}$ and $u_n \to u_0$ in BV-norm, *i.e.*,

$$u_n \xrightarrow{L^1} u_0$$
 and $\int_{\Omega} |\nabla u_n| \to \int_{\Omega} |Du_0|.$

The sequence is defined by convolution with u_0 and a Friedrichs mollifiers with compact support [see [Giu84]-Theorem 1.17].

We let also $B_{\infty} := \{(x, y) \in]0, 1[^2 | x \in \tilde{\mathcal{K}} \text{ and } y > 0\}$. The saturation of (3) consists in obtaining:

(4)
$$\int_{B_{\infty}} |\partial_2 u_n| \ge |\mathcal{K}|.$$

¹This result was initially proved by Gagliardo in [Gag57]. A short proof of "tr $W^{1,1} = L^1$ " may be found in [Mir15]. The key-point is here the quantitative form of the upper bound on $\int_{\Omega} |Du_{\varepsilon}|$ given by Remark 2.17 in [Giu84].

As observed by Mironescu, the key tool in the proof of (4) is Fubini Theorem combined with the Fundamental Theorem of calculus.

(5)
$$\int_{B_{\infty}} |\partial_2 u_n| = \int_0^1 \mathrm{d}x \int_0^1 |\partial_2 u_n| \mathbb{1}_{B_{\infty}} \mathrm{d}y$$
$$\geq \int_0^1 \mathrm{d}x \left| \int_0^1 \partial_2 u_n \mathbb{1}_{B_{\infty}} \mathrm{d}y \right|$$
$$= \int_0^1 \mathbb{1}_{\tilde{\mathcal{K}}}$$
(6)
$$= |\tilde{\mathcal{K}}| = |\mathcal{K}|.$$

Step 3. A transverse argument

In order to obtain a contradiction we are going to prove that [for sufficiently large n]

(7)
$$\int_{\Omega} |\nabla u_n| - \int_{B_{\infty}} |\partial_2 u_n| \ge \delta \text{ for some } \delta > 0 \text{ independent of } n$$

From the BV-convergence we have

$$\int_{\Omega} |Du_0| = \lim_{n} \int_{\Omega} |\nabla u_n|$$

=
$$\lim_{n} \int_{B_{\infty}} |\partial_2 u_n| + \left(\int_{\Omega} |\nabla u_n| - \int_{B_{\infty}} |\partial_2 u_n| \right)$$

[(6)&(7)] $\geq |\mathcal{K}| + \delta.$

The last estimate yields a contradiction with (3).

Thus it suffices to prove (7).

We make the following dichotomy: $u_0 \neq 0$ in $\Omega \setminus B_{\infty}$ or $u_0 \equiv 0$ in $\Omega \setminus B_{\infty}$.

If $u_0 \neq 0$ in $\Omega \setminus B_{\infty}$, since $\operatorname{tr}_{\partial\Omega\setminus\mathcal{K}}u_0 = 0$, then u_0 can not be a constant in $\Omega \setminus B_{\infty}$. Thus

$$\delta := \frac{1}{2} \int_{\Omega \backslash B_{\infty}} |Du_0| > 0$$

Therefore, for sufficiently large n,

$$\int_{\Omega} |\nabla u_n| - \int_{B_{\infty}} |\partial_2 u_n| \ge \int_{\Omega \setminus B_{\infty}} |\nabla u_n| \ge \delta$$

This prove Estimate (7).

We now assume that $u_0 \equiv 0$ in $\Omega \setminus B_{\infty}$. It is clear that we may fix $\frac{1}{4} < a < b < \frac{3}{4}$ and 0 < c < d < 1 s.t.

$$\delta' := \frac{1}{2} \int_{]a,b[\times]c,d[} |u_0| > 0 \text{ and } (\{a,b\}\times]0,1[) \cap B_{\infty} = \emptyset.$$

Noting that $u_0 \equiv 0$ in $\Omega \setminus B_{\infty}$ and that the sequence $(u_n)_n$ is obtained by the convolution of u with a C^{∞} -mollifier with compact support, it follows that for sufficiently large n we have $u_n \equiv 0$ in $\{a, b\} \times [c, d]$.

Consequently, from Lemma 3.2 in [ST14], we get [for sufficiently large n]

$$\int_{]a,b[\times]c,d[} |\partial_1 u_n| \geq \frac{2}{b-a} \int_{]a,b[\times]c,d[} |u_n| > \delta'.$$

Since $\int_{[a,b]\times]c,d[} |\partial_1 u_n| > \delta', \int_{[a,b]\times]c,d[} |\partial_2 u_n| \le 2|\mathcal{K}|$, by Lemma 3.3 in [ST14] we obtained:

$$\int_{]a,b[\times]c,d[} |\nabla u_n| \ge \int_{]a,b[\times]c,d[} |\partial_2 u_n| + \frac{{\delta'}^2}{4|\mathcal{K}| + {\delta'}}.$$

We thus get (7) with $\delta := \frac{\delta'^2}{4|\mathcal{K}| + \delta'}$.

2.2. Comments. To prove Theorem 1, we plan to follow the strategy presented above. The first main step in this strategy is the construction of a suitable Cantor set $\mathcal{K} \subset \partial \Omega$. Once \mathcal{K} is constructed we define B_{∞} by bending lines orthogonal to $\partial \Omega$.

The construction of \mathcal{K} is done Section 4 and B_{∞} is defined Section 5.

A second main step is to implementing the appropriate substitute of Fubini Theorem. This involves Coarea formula. The estimate we will device [the analog of (6) is done by Lemma 8] is obtained asymptotically by integration [via Coarea formula] along level sets of an appropriate function. The appropriate function is, roughly speaking, the projection on \mathcal{K} "along" connected components of B_{∞} .

The plan of this article is the following:

- In Section 3 we specify some notations and definitions.
- In Section 4 we present the construction of the set $\mathcal{K} \subset \partial \Omega$.
- In Section 5 we construct the fundamental tool in the proof of Theorem 1. The Cantor set \mathcal{K} is obtained by a standard iterative process. It is defined as the intersection of set $\mathcal{K}_N \subset \partial \Omega$: $\mathcal{K} = \bigcap_{N \geq 1} \mathcal{K}_N$. In Section 5, for $N \geq 1$, we construct a Lipschitz map Ψ_N defined in a subset of Ω with value in \mathcal{K}_N . The main difficulty in this construction is to get a map with a sharp control of its Lipschitz semi-norm (see Lemma 6).
- In Section 6 we state some properties on B_{∞} and Ψ_N : the topological interior of B_{∞} is empty and we give an upper bound for the Lipschitz semi-norm of Ψ_N (see Lemma 6).
- Section 7 is dedicated to the proof of Theorem 1.
- For the convenience of the reader, the proof of some results are postponed to appendices. In Appendix A we prove that the measure of the Cantor set \mathcal{K} is positive. Appendix B is dedicated to some technical results about the set B_{∞} . In Appendix C we sketch the proof of Giusti to get the analog of (3).

3. NOTATIONS, DEFINITIONS

The ambient space is the euclidean plan \mathbb{R}^2 . We let \mathcal{B}_{can} be the canonical basis of its direction space.

- a) The open ball centered at $A \in \mathbb{R}^2$ with radius r > 0 is denoted by B(A, r).
- b) A vector may be denoted by an arrow when it is defined with its extremities (*e.g.* \overrightarrow{AB}), it may be also denoted by a letter in bold font (*e.g.* **u**) or more simply by a gree letter in normal font (*e.g.* ν). We let also $|\mathbf{u}|$ be the usual euclidean norm of the vector **u**.
- c) For a vector \mathbf{u} we let \mathbf{u}^{\perp} be the direct orthogonal vector to \mathbf{u} , *i.e.*, if the coordinates of \mathbf{u} are (x_1, x_2) , then those of \mathbf{u}^{\perp} are $(-x_2, x_1)$.
- d) For $A, B \in \mathbb{R}^2$, the segment of extremities A and B is denoted by $[AB] = \{A + t\overrightarrow{AB} | t \in [0, 1]\}$ and $\operatorname{dist}(A, B) = |\overrightarrow{AB}|$ is the usual euclidean distance.
- e) For a set $U \subset \mathbb{R}^2$, the topological interior of U is denoted by \check{U} and its topological closure is \overline{U} .
- f) For $k \ge 1$, a C^k -curve is the range of a C^k injective map from]0,1[to \mathbb{R}^2 . Note that, in this article, C^k -curves are not closed sets of \mathbb{R}^2 .
- g) For Γ a C^1 -curve, $\mathscr{H}^1(\Gamma)$ is the 1-dimensional Hausdorff measure of Γ .
- h) For $k \ge 1$, a C^k -Jordan curve is the range of a C^k injective map from the unit circle \mathbb{S}^1 to \mathbb{R}^2 .
- i) For Γ a C^1 -curve or a C^1 -Jordan curve, $\mathscr{C} = [AB]$ is a chord of Γ when $A, B \in \overline{\Gamma}$ with $A \neq B$.
- j) If Γ is a C^1 -Jordan curve then, for $A, B \in \Gamma \& A \neq B$, the set $\Gamma \setminus \{A, B\}$ admits exactly two connected components: $\Gamma_1 \& \Gamma_2$. These connected components are C^1 -curves.

By smoothness of Γ , it is clear that there is $\eta_{\Gamma} > 0$ s.t. for $0 < \text{dist}(A, B) < \eta_{\Gamma}$ there exists THE smallest connected components: we have $\mathscr{H}^1(\Gamma_1) < \mathscr{H}^1(\Gamma_2)$ or $\mathscr{H}^1(\Gamma_2) < \mathscr{H}^1(\Gamma_1)$.

If $0 < \operatorname{dist}(A, B) < \eta_{\Gamma}$ we may define AB by:

(8)

$$AB$$
 is the closure of the smallest curve between Γ_1 and Γ_2

k) In this article $\Omega \subset \mathbb{R}^2$ is a C^2 bounded open set. By C^2 we mean that $\partial \Omega$ is of class C^2 :

- There exists a covering $\{U_1, ..., U_n\}$ of $\partial\Omega$ by open sets, $\partial\Omega \subset \bigcup_{i=1}^n U_i$,
- For all $i \in \{1, ..., n\}$ there is a C^2 diffeomorphism $\varphi_i : \overline{U_i} \to \overline{\mathbb{D}}$ s.t.

$$\varphi_i(U_i \cap \Omega) = \{(x_1, x_2) \in \mathbb{D} \mid x_2 > 0\}$$

$$\varphi_i(U_i \cap \partial \Omega) = \{(x_1, x_2) \in \mathbb{D} \mid x_2 = 0\}$$

4. Construction of the Cantor set \mathcal{K}

It is clear that, up to consider a connected component of Ω , in order to prove Theorem 1 we may assume that Ω is a connected set.

We fix $\Omega \subset \mathbb{R}^2$ be a bounded C^2 open connected set. The set $\mathcal{K} \subset \partial \Omega$ of Theorem 1 is a Cantor set. It is constructed by a recursive way.

4.1. First step: main hypotheses. From the regularity of Ω , there are $\ell + 1$ C²-open sets, $\omega_0, ..., \omega_\ell$, s.t. $\Omega = \omega_0 \setminus \overline{\omega_1 \cup \cdots \cup \omega_\ell}.$

- Moreover we may assume that:
 - ω_i is simply connected for $i = 0, ..., \ell$,
 - $\overline{\omega_i} \subset \omega_0$ for $i = 1, ..., \ell$,
 - $\overline{\omega_i} \cap \overline{\omega_j} = \emptyset$ for $1 \le i < j \le \ell$.

We let $\Gamma = \partial \omega_0$. The Cantor set \mathcal{K} is constructed in Γ . Note that Γ is a Jordan-curve. From the Gauss-Bonnet Theorem we get the existence of $M_0 \in \Gamma$ and $r_0 \in [0, 1]$ s.t. for $A, B \in B(M_0, r_0) \cap \Gamma$, the chord $[AB] \subset \overline{\Omega}$ and $[AB] \cap \partial\Omega = \{A, B\}$. Note that we may assume $2r_0 < \eta_{\Gamma}$ [η_{Γ} is defined in Section 3-j]

We fix $A, B \in B(M_0, r_0) \cap \Gamma$ s.t. $A \neq B$. We have:

- By the definition of M_0 and r_0 , the chord $\mathscr{C}_0 := [AB]$ is included in $\overline{\Omega}$.
- We let AB be the closure of the smallest part of Γ which is delimited by A, B (see (8)). Up to replace r_0 by a smaller value we may assume that AB is the graph of $f \in C^2([0,\eta], \mathbb{R}^+)$ in the orthonormal frame $\mathcal{R}_0 = (A, \mathbf{e}_1, \mathbf{e}_2)$ where $\mathbf{e}_1 = \overline{AB} / |\overline{AB}|$.
- The function f is strictly concave and f(x) > 0 for $x \in]0, \eta[$.

Key Claim. Note that the length of the chord [AB] is η and that for intervals $I, J \in [0, \eta]$, if $I \subset J$ then $< \|f_{\perp I}^{\prime\prime}\|_{L^{\infty}(J)}$ $(\mathbf{0})$ || *f''* ||

(9)
$$||J_{|I}||_{L^{\infty}(I)} \leq ||J_{|J}||$$

where $f_{|I|}$ is the restriction of f to I.

Thus, up to replace the chord $\mathscr{C}_0 = [AB]$ by a smaller chord of AB parallel to \mathscr{C}_0 , and up to restrict the function f (and up to add a suitable constant to f) we may assume that

(10)
$$0 < \eta < \min\left\{\frac{1}{2}; \frac{1}{16\|f''\|_{L^{\infty}([0,\eta])}^2}\right\}.$$

We may also assume that

- Letting D_0^+ be the bounded open set s.t. $\partial D_0^+ = [AB] \cup \widehat{AB}$ we have $\Pi_{\partial\Omega}$, the orthogonal projection on $\partial\Omega$, which is well defined and of class C^2 in D_0^+ .
- Once again by (9) we have

(11)
$$1 + 4 \|f''\|_{L^{\infty}}^2 \operatorname{diam}(D_0^+) < \frac{16}{9}$$

where diam $(D_0^+) = \sup\{\operatorname{dist}(M, N) \mid M, N \in D_0^+\}.$

4.2. Step 2: Iterative construction. We are now in position to construct the Cantor set \mathcal{K} as a subset of AB. The construction is iterative.

The goal of the construction is to get at Step $N \ge 0$ a collection of 2^N pairwise disjoint curves included in \overline{AB} [denoted by $\{K_1^N, ..., K_{2^N}^N\}$] and their chords [denoted by $\{\mathscr{C}_1^N, ..., \mathscr{C}_{2^N}^N\}$].

The idea is standard: at the step $N \ge 0$ we replace a curve Γ_0 included in AB by two curves included in Γ_0 (see Figure 1).

Initialization. We initialize the procedure by letting $K_1^0 := \widehat{AB}$ and $\mathscr{C}_1^0 = \mathscr{C}_0 = [AB]$.

At step $N \ge 0$ we have:

- A set of 2^N curves included in \widehat{AB} , $\{K_1^N, ..., K_{2^N}^N\}$. The curves K_k^N 's are mutually disjoints. We let
 $$\begin{split} \mathcal{K}_N &= \cup_{k=1}^{2^N} K_k^N. \\ \bullet \text{ A set of } 2^N \text{ chords}, \left\{ \mathscr{C}_1^N, ..., \mathscr{C}_{2^N}^N \right\} \text{ s.t. for } k=1, ..., 2^N, \, \mathscr{C}_k^N \text{ is the chord of } K_k^N. \end{split}$$

- (1) Note that since the \mathscr{C}_k^N 's are chords of \widehat{AB} and since in the frame $\mathcal{R}_0 = (A, \mathbf{e}_1, \mathbf{e}_2), \widehat{AB}$ is the graph of a function, none of the chords \mathscr{C}_k^N are vertical, *i.e.*, directed by \mathbf{e}_2 . Since the chords \mathscr{C}_k^N are not vertical, for $k \in \{1, ..., 2^N\}$, we may define $\nu_{\mathscr{C}_k^N}$ as the unit vector Remark 1.

 - orthogonal to \mathscr{C}_k^N s.t. $\nu_{\mathscr{C}_k^N} = \alpha \mathbf{e}_1 + \beta \mathbf{e}_2$ with $\beta > 0$. (2) Since the function $f \in C^2([0,\eta], \mathbb{R}^+)$ is strictly concave, considering a chord \mathscr{C}_k^N and a straight line D perpendicular to \mathscr{C}_k^N , the straight line D intersect K_k^N at exactly one points.

This fact may be easily checked by letting Γ^* be the range of \widehat{AB} with respect to the symmetry of axe [AB] and by noting that the compact set delimited by $AB \cup \Gamma^*$ is a strictly convex domain.

Heredity rules. From Step $N \ge 0$ to Step N + 1 we follow the following rules:

- (1) For each $k \in \{1, ..., 2^N\}$, we let η_k^N be the length of \mathscr{C}_k^N . Inside the chord \mathscr{C}_k^N we center a segment I_k^N of length $(\eta_k^N)^2$.
- (2) With the help of Remark 1.2, we may define two distinct points of K_k^N as the intersection of K_k^N with straight lines perpendicular to \mathscr{C}_k^N which pass by the extremities of I_k^N .
- (3) These intersection points are the extremities of a curve \tilde{K}_k^N included in K_k^N . We let K_{2k-1}^{N+1} and K_{2k}^{N+1} the connected components of $K_k^N \setminus \overline{\tilde{K}_k^N}$. We let also • \mathscr{C}_{2k-1}^{N+1} and \mathscr{C}_{2k}^{N+1} their chords; • $\mathcal{K}_{N+1} = \bigcup_{k=1}^{2^{N+1}} K_k^{N+1}$.

Notation 2. A natural terminology consists in defining the father and the sons of a chord or a curve:

- \$\mathcal{F}(\mathcal{C}_{2k-1}^{N+1}) = \mathcal{F}(\mathcal{C}_{2k}^{N+1}) = \mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{K}_{k}^{N}\$ is the father of the curves \$K_{2k-1}^{N+1}\$ and \$K_{2k}^{N+1}\$.
 \$\mathcal{S}(\mathcal{C}_{k}^{N}) = \{\mathcal{C}_{2k-1}^{N+1}, \mathcal{C}_{2k}^{N+1}\}\$ is the set of sons of the curve \$K_{k}^{N}\$, i.e., \$\mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{F}(K_{2k}^{N+1}) = \mathcal{K}_{k}^{N}\$.
 \$\mathcal{S}(K_{k}^{N}) = \{K_{2k-1}^{N+1}, K_{2k}^{N+1}\}\$ is the set of sons of the curve \$K_{k}^{N}\$, i.e., \$\mathcal{F}(K_{2k-1}^{N+1}) = \mathcal{F}(K_{2k}^{N+1}) = K_{k}^{N}\$.

The heredity step is represented in Figure 1.





FIGURE 1. Heredity

In Figure 2&3 the two first iterations of the process are represented.



FIGURE 2. First iteration of the process

FIGURE 3. Second iteration of the process

We now define the Cantor set (12)

$$\mathcal{K} = \bigcap_{N \ge 0} \overline{\mathcal{K}_N}.$$

The Cantor set \mathcal{K} is fat:

Proposition 3. We have $\mathscr{H}^1(\mathcal{K}) > 0$.

This proposition is proved in Appendix A.

5. CONSTRUCTION OF A SEQUENCE OF FUNCTIONS USED IN CONJUCTION WITH COAREA FORMULA

A key argument in the proof of Theorem 1 is the use of the coarea formula to calculate a lower bound for (2). The coarea formula is applied to a function adapted to the set \mathcal{K} .

For N = 0 we let

- D_0^+ be the compact set delimited by $K_0 = \widehat{AB}$ and $\mathscr{C}_1^0 := [AB]$ the chord of K_0 .
- We recall that we fixed a frame $\mathcal{R}_0 = (A, \mathbf{e}_1, \mathbf{e}_2)$ where $\mathbf{e}_1 = \overrightarrow{AB} / |\overrightarrow{AB}|$. For $\sigma = (\sigma_1, 0) \in \mathscr{C}_1^0$, we define:

 I_{σ} is the connected component of $\{(\sigma_1, t) \in \Omega \mid t \leq 0\}$ which contains σ . (13)

 $[I_{\sigma} \text{ is a vertical segment included in } \Omega].$

- $D_0^- = \bigcup_{\sigma \in \mathscr{C}_1^0} I_{\sigma}.$
- We now define the maps

$$\begin{array}{rcccc} \tilde{\Psi}_0: & D_0^- & \to & \mathscr{C}_1^0 \\ & x & \mapsto & \Pi_{\mathscr{C}_1^0}(x) \end{array}$$

and

$$\begin{array}{cccc} \Psi_0: & D_0^- \cup D_0^+ & \to & \mathscr{C}_1^0 \\ & x & \mapsto & \begin{cases} \Pi_{\partial\Omega}(x) & \text{if } x \in D_0^+ \\ \Pi_{\partial\Omega}[\tilde{\Psi}_0(x)] & \text{if } x \in D_0^- \end{cases} \end{array}$$

where $\Pi_{\partial\Omega}$ is the orthogonal projection on $\partial\Omega$ and $\Pi_{\mathscr{C}_1^0}$ is the orthogonal projection on \mathscr{C}_1^0 . Note that, in the frame \mathcal{R}_0 , for $x = (x_1, x_2) \in D_0^-$, we have $\prod_{\mathscr{C}_1^0} (x) = (x_1, 0)$.

For N = 1 and $k \in \{1, 2\}$ we let:

- D_k^1 be the compact set delimited by K_k^1 and \mathscr{C}_k^1 ; T_k^1 be the compact right-angled triangle (with its interior) having \mathscr{C}_k^1 as side adjacent to the right angle and whose hypothenuse is included in \mathscr{C}_1^0 ;
- H_k^1 be the hypothenuse of T_k^1 .

We now define $D_1^- = \tilde{\Psi}_0^{-1}(H_1^1 \cup H_2^1), T_1 = T_1^1 \cup T_2^1$ and $D_1^+ = D_1^1 \cup D_2^1$. We first consider the map

$$\begin{split} \tilde{\Psi}_1 : & T_1 \cup D_1^- \to \mathscr{C}_1^1 \cup \mathscr{C}_2^1 \\ & x \mapsto \begin{cases} \Pi_{\mathscr{C}_k^1}(x) & \text{if } x \in T_k^1 \\ \Pi_{\mathscr{C}_1^1}[\tilde{\Psi}_0(x)] & \text{if } x \in D_1^- \end{cases} \end{split}$$

In Appendix B [Proposition 12], it is proved that the triangles T_1^1 and T_2^1 are disjoint. Thus the map $\tilde{\Psi}_1$ is well defined

By projecting $\mathscr{C}_1^1 \cup \mathscr{C}_2^1$ on $\partial \Omega$ we get

$$\begin{split} \Psi_1 : & T_1 \cup D_1^- \cup D_1^+ & \to & \mathcal{K}_1 \\ & x & \mapsto & \begin{cases} \Pi_{\partial\Omega}(x) & \text{if } x \in D_1^+ \\ \Pi_{\partial\Omega}[\tilde{\Psi}_1(x)] & \text{if } x \in T_1 \cup D_1^- \end{cases} . \end{split}$$



FIGURE 4. The sets defined at Step N = 1 and the level line [in dash] of Ψ_1 associated to σ

For $N \geq 1$, we first construct $\tilde{\Psi}_{N+1}$ and then Ψ_{N+1} is obtained from $\tilde{\Psi}_{N+1}$ and $\Pi_{\partial\Omega}$. For $k \in \{1, ..., 2^{N+1}\}$, we let

- D_k^{N+1} be the compact set delimited by K_k^{N+1} and C_k^{N+1} [recall that C_k^{N+1} is the chord associated to K_k^{N+1}];
 T_k^{N+1} be the right-angled triangle (with its interior) having C_k^{N+1} as side adjacent to the right angle and whose hypothenuse is included in F(C_k^{N+1}). Here F(C_k^{N+1}) is the father of C_k^{N+1} (see Notation 2).
- 2); $H_k^{N+1} \subset \mathcal{F}(\mathscr{C}_k^{N+1})$ be the hypothenuse of T_k^{N+1} .

We denote $T_{N+1} = \bigcup_{k=1}^{2^{N+1}} T_k^{N+1}, \ D_{N+1}^- = \tilde{\Psi}_N^{-1} \left(\bigcup_{k=1}^{2^{N+1}} H_k^{N+1} \right) \text{ and } D_{N+1}^+ = \bigcup_{k=1}^{2^{N+1}} D_k^{N+1}.$



FIGURE 5. Heredity. The bold lines correspond to the new iteration

Remark 4. It is easy to check that for $N \ge 0$:

- (1) $T_{N+1} \subset D_N^+$, (2) if $x \in \overset{\circ}{T_N}$ then $x \notin T_{N'}$ for $N' \ge N+1$ [here $T_0 = \emptyset$].

We now define

$$\tilde{\Psi}_{N+1}: T_{N+1} \cup D_{N+1}^{-} \to \qquad \qquad \cup_{k=1}^{2^{N+1}} \mathscr{C}_{k}^{N+1} \\
x \mapsto \begin{cases} \Pi_{\mathscr{C}_{k}^{N+1}}(x) & \text{if } x \in T_{k}^{N+1} \\ \Pi_{\mathscr{C}_{k}^{N+1}}[\tilde{\Psi}_{N}(x)] & \text{if } x \in \tilde{\Psi}_{N}^{-1}(\cup_{k=1}^{2^{N+1}} H_{k}^{N+1}) \end{cases}$$

In Appendix B [Proposition 12], it is proved that for $N \ge 1$, the triangles T_k^N for $k = 1, ..., 2^N$ are mutually disjoint. Thus the map $\tilde{\Psi}_{N+1}$ is well defined is $\tilde{\Psi}_N$ makes sense.

And, as in the Initialization Step, we get Ψ_{N+1} from $\tilde{\Psi}_{N+1}$ by projecting $\bigcup_{k=1}^{2^{N+1}} \mathscr{C}_k^{N+1}$ on $\partial\Omega$:

$$\begin{split} \Psi_{N+1} : \quad T_{N+1} \cup D_{N+1}^- \cup D_{N+1}^+ & \to \qquad \mathcal{K}_{N+1} \\ x & \mapsto \qquad \begin{cases} \Pi_{\partial\Omega}[\tilde{\Psi}_{N+1}(x)] & \text{if } x \in T_{N+1} \cup D_{N+1}^- \\ \Pi_{\partial\Omega}(x) & \text{if } x \in D_{N+1}^+ \end{cases} \end{split}$$

It is easy to see that $\Psi_{N+1}(T_{N+1} \cup D_{N+1}^- \cup D_{N+1}^+) = \mathcal{K}_{N+1}$.

6. Basic properties for B_{∞} and Ψ_N

We first state some fundamental claims on the sets $B_N = T_N \cup D_N^+ \cup D_N^-$. It is easy to check that for $N \ge 0$ we have $B_{N+1} \subset B_N$ and $\mathcal{K} \subset \partial B_N$. Therefore we may define

$$B_{\infty} = \bigcap_{N \ge 0} \overline{B_N}$$

which is compact and it satisfies $\mathcal{K} \subset \partial B_{\infty}$.

We are going to prove:

Lemma 5. The interior of B_{∞} is empty.

Proof of Lemma 5. From Proposition 12 in Appendix B combined with Hypothesis (10), we get two fundamental facts:

- (1) The triangles T_1^N , ..., $T_{2^{N+1}}^N$ are mutually disjoint.
- (2) We have:

(14)

$$\mathscr{H}^1(H^{N+1}_k) < rac{\mathscr{H}^1(\mathcal{F}(\mathscr{C}^N_k))}{2}$$

For a non empty set $A \subset \mathbb{R}^2$ we let

$$\operatorname{rad}(A) = \sup\{r \ge 0 \mid \exists x \in A \text{ s.t. } \overline{B(x,r)} \subset A\}.$$

Note that the topological interior of A is empty if and only if rad(A) = 0.

On the one hand, it is not difficult to check that

(15)
$$\operatorname{rad}(B_N) = \operatorname{rad}(B_N \cap D_N^-)$$

On the other hand, using (14) and the Incidence Theorem applied in a recursive way, we get that for $N \ge 1$:

(16)
$$\operatorname{rad}(B_{N+1} \cap D_{N+1}^{-}) \le \frac{\operatorname{rad}(B_N \cap D_N^{-})}{2}$$

Consequently, by combining (15)&(16) we get the existence of $C_0 > 1$ s.t.

(17)
$$\operatorname{rad}(B_N) \le \frac{C_0}{2^N}$$

Since $B_{\infty} = \bigcap_{N > 0} B_N$, from (17) we get that $rad(B_{\infty}) = 0$. The last estimate implies the expected result.

We now prove the key estimate for Ψ_N :

Lemma 6. The function Ψ_N is $(1 + o_N(1))$ -Lipschitz.

Proof. The functions $\tilde{\Psi}_N$ are obtained as compositions of orthogonal projections on straight lines and thus are 1-Lipschitz.

The projection $P_N := \prod_{\partial \Omega}$ defined in $\overline{D_N^+}$ is $(1 + o_N(1))$ -Lipschitz. The functions Ψ_N are either the composition of $\tilde{\Psi}_N$ with P_N or $\Psi_N = P_N$. Consequently Ψ_N is $(1 + o_N(1))$ -Lipschitz.

7. Proof of Theorem 1

We are now in position to prove Theorem 1. It is clear that we may assume that Ω is a connected set. The proof of Theorem 1 is done arguing by contradiction. We assume that there exists a map $u_0 \in BV(\Omega)$ which is a solution of (2).

7.1. Upper bound. The first step in the demonstration is

(18)
$$\int_{\Omega} |Du_0| \le \|\mathbf{1}_{\mathcal{K}}\|_{L^1(\partial\Omega)} = |\mathcal{K}|$$

Estimate (18) is obtained by proving that for all $\varepsilon > 0$ there is $u_{\varepsilon} \in W^{1,1}(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} u_{\varepsilon} = \mathbb{I}_{\mathcal{K}}$ and

(19)
$$\|\nabla u_{\varepsilon}\|_{L^{1}(\Omega)} \leq (1+\varepsilon)\|\operatorname{tr}_{\partial\Omega} u_{\varepsilon}\|_{L^{1}(\Omega)} = (1+\varepsilon)|\mathcal{K}|.$$

The last estimate is obtained by Theorem 2.16 & Remark 2.17 in [Giu84]. The proof of this result is done for special domains Ω . We sketch its adaptation for a C^2 domain in Appendix C.

With the help of (19), it suffices to use the minimality of u_0 to get (18).

7.2. Saturation of the upper bound. In order to have a contradiction we follow the strategy of Spradlin and Tamasan in [ST14]. We fix a sequence $(u_n)_n \subset C^{\infty}(\Omega)$ defined by the convolution of u_0 and a Friedrichs mollifiers [with compact support]. This sequence of functions is defined in [Giu84]-Theorem 1.17. It satisfies $u_n \xrightarrow{BV} u_0$ and $\operatorname{tr}_{\partial\Omega} u_n = \operatorname{tr}_{\partial\Omega} u_O$.

Here $u_n \xrightarrow{BV} u_0$ means $u_n \xrightarrow{L^1} u_0$ and $\int_{\Omega} |\nabla u_n| \to \int_{\Omega} |Du_0|$. For $x \in B_0$ we let

(20)
$$V_0(x) = \begin{cases} \nu_{\Pi_{\partial\Omega}(x)} & \text{if } x \in D_0^+ \\ (0,1) & \text{if } x \in D_0^- \end{cases}$$

and for $N \ge 0, x \in B_{N+1}$:

(21)
$$V_{N+1}(x) = \begin{cases} V_N(x) & \text{if } x \in B_N \setminus \mathring{T}^{N+1} \\ \nu_{\mathscr{C}_k^{N+1}} & \text{if } x \in \mathring{T}_k^{N+1} \end{cases}$$

where ν_{σ} is the normal outward of Ω in $\sigma \in \partial \Omega$ and $\nu_{\mathscr{C}^{N+1}_{\iota}}$ is defined in Remark 1.1.

We now prove the following lemma.

Lemma 7. When $N \to \infty$ we may define

(22)
$$V_{\infty}: \begin{array}{ccc} B_{\infty} & \to & \mathbb{R}^2 \\ x & \mapsto & \lim_{N \to \infty} V_N(x) \end{array}$$

Moreover, from the Dominated Convergence Theorem, we have:

(23)
$$V_N I\!\!I_{B_N} \to V_\infty I\!\!I_{B_\infty} \text{ in } L^1(\Omega)$$

Proof. Let $x \in B_{\infty}$. Then $x \in B_N$ for all $N \ge 1$. In order to prove that $V_{\infty}(x)$ is well defined it suffices to note that, from Remark 4.2, if $x \in \overset{\circ}{T}_{N_0}$ for some $N_0 \ge 1$, then $x \notin T_N$ for $N > N_0$. Consequently, there is a dichotomy:

• $x \in B_{\infty} \setminus \bigcup_{N \ge 1} \stackrel{\circ}{T_N},$ • $\exists! N_0 \ge 1 \text{ s.t. } x \in \stackrel{\circ}{T_{N_0}}.$

If $x \in B_{\infty} \setminus \bigcup_{N \ge 1} \overset{\circ}{T}_N$, then we have $V_N(x) = V_0(x)$ for all $N \ge 1$. Thus $\lim_{N \to \infty} V_N(x) = V_0(x)$. Otherwise there exists a unique $N_0 \ge 1$ s.t. $x \in \overset{\circ}{T}_{N_0}$. Therefore for all $N > N_0$ we have $V_N(x) = V_{N_0}(x)$. Consequently $\lim_{N \to \infty} V_N(x) = V_{N_0}(x)$.

This section is dedicated for the proof of the lemma:

Lemma 8. For all $w \in C^{\infty} \cap BV(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} w = I_{\mathcal{K}}$ we have

$$\int_{B_{\infty}\cap\Omega} |\nabla w \cdot V_{\infty}| \ge |\mathcal{K}|$$

where V_{∞} is the vectorial field defined in (22).

Remark 9. Since $|V_{\infty}(x)| = 1$ for $x \in B_{\infty}$, it is clear that Lemma 8 implies that for all n we have

$$\int_{B_{\infty}\cap\Omega} |\nabla u_n| \ge |\mathcal{K}|$$

Therefore, from the BV-convergence of u_n to u_0 we get

$$\int_{B_{\infty}\cap\Omega}|Du_0|\geq |\mathcal{K}|$$

Section 7.3 is dedicated to a sharper argument than above to get

$$\int_{B_{\infty}\cap\Omega} |\nabla u_n| \ge \int_{B_{\infty}\cap\Omega} |\nabla u_n \cdot V_{\infty}| + \delta$$

with $\delta > 0$ is independent of n. The last estimate will imply $\int_{B_{\infty}\cap\Omega} |Du_0| \geq |\mathcal{K}| + \delta$ which will be the contradiction in the argumentation.

Proof. We first get that for $w \in C^{\infty} \cap BV(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} w = \mathbb{I}_{\mathcal{K}}$ we have

(24)
$$\int_{B_N \cap \Omega} |\nabla w \cdot V_N| \ge \frac{|\mathcal{K}|}{|\Psi_N|^2_{\text{Lip}(B_N)}}$$

where

$$|\Psi_N|_{\text{Lip}(B_N)} = \sup\left\{\frac{|\Psi_N(x) - \Psi_N(x)|}{|x - y|} \,|\, x, y \in B_N, \, x \neq y\right\}$$

is the Lipischitz semi-norm of Ψ_N and V_N is the vectorial field defined in (20)&(21).

Once we get this estimate, we claim that for a fixed map $w \in C^{\infty} \cap BV(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} w = \mathbb{I}_{\mathcal{K}}$, from (23) and the Dominated Convergence Theorem, we have $\nabla w \cdot V_N \mathbb{1}_{B_N \cap \Omega} \to \nabla w \cdot V_\infty \mathbb{1}_{B_\infty \cap \Omega}$ in $L^1(\Omega)$.

Thus, with the help of Lemma 6 $[|\Psi_N|_{\text{Lip}(B_N)} = 1 + o_N(1)]$ we have

$$\int_{B_{\infty}\cap\Omega} |\nabla w \cdot V_{\infty}| \ge |\mathcal{K}|.$$

We thus prove (24). We fix $w \in C^{\infty} \cap BV(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} w = \mathrm{I}_{\mathcal{K}}$. Using the Coarea Formula we have

$$\begin{aligned} |\Psi_N|^2_{\operatorname{Lip}(\mathcal{B}_N)} \int_{B_N \cap \Omega} |\nabla w \cdot V_N| &\geq \int_{B_N \cap \Omega} |\operatorname{jac} \Psi_N| |\nabla w \cdot V_N| \\ &= \int_{\widehat{AB}} \mathrm{d}\sigma \int_{\Psi_N^{-1}(\{\sigma\}) \cap \Omega} |\nabla w \cdot V_N| \end{aligned}$$

Here $\Psi_N^{-1}(\{\sigma\})$ is a polygonal chain:

$$\Psi_N^{-1}(\{\sigma\}) = I_{\tilde{\sigma}} \cup I_{N,\sigma}^1 \cup \dots \cup I_{N,\sigma}^{N+1}$$

where

- $\tilde{\sigma}$ is s.t. $[AB] \cap \tilde{\Psi}_N^{-1}(\{\sigma\}) = \{\tilde{\sigma}\},$ $I_{\tilde{\sigma}}$ is defined in (13), for l = 1, ..., N we have $I_{N,\sigma}^l = \Psi_N^{-1}(\{\sigma\}) \cap T_{N+1-l},$ $I_{N,\sigma}^{N+1} = \Psi_N^{-1}(\{\sigma\}) \cap D_N^+.$

From the Fundamental Theorem of calculus and from the definition of V_N , denoting

- $I_{\tilde{\sigma}} = [\alpha_0, \alpha_1]$ (where $\alpha_0 \in \partial \Omega$ and $\alpha_1 = \tilde{\sigma}$),
- $I_{N,\sigma}^{l} = [\alpha_{l}, \alpha_{l+1}], l = 1, ..., N + 1 \text{ and } \alpha_{N+2} = \sigma,$

we have for a.e. $\sigma \in AB$:

$$\int_{[\alpha_l,\alpha_{l+1}]} |\nabla w \cdot V_N| \ge |w(\alpha_{l+1}) - w(\alpha_l)|.$$

Here we used a little abuse of notation writing for $l = 0 \& N + 2 w(\alpha_l)$ instead of $\operatorname{tr}_{\partial\Omega} w(\alpha_l)$.

Therefore for a.e $\sigma \in \mathcal{K}_N$ we have

$$\int_{\Psi_N^{-1}(\{\sigma\})\cap\Omega} |\nabla w \cdot V_N| \ge |\mathrm{tr}_{\partial\Omega} w(\sigma) - \mathrm{tr}_{\partial\Omega} w(\alpha_0)| = \mathrm{I}_{\mathcal{K}}(\sigma)$$

We may thus deduce that

$$|\Psi_N|^2_{\mathrm{Lip}(\mathbf{B}_N)} \int_{B_N \cap \Omega} |\nabla w \cdot V_N| \geq \int_{\widehat{AB}} \mathrm{I}_{\mathcal{K}} = |\mathcal{K}|.$$

The last estimate clearly implies (24) and it ends the proof of Lemma 8.

7.3. Transverse argument. We assumed that there exists a map u_0 which solves Problem (2).

- We make the following dichotomy:
 - $u_0 \not\equiv 0$ in $\Omega \setminus B_\infty$;
 - $u_0 \equiv 0$ in $\Omega \setminus B_\infty$.

We are going to prove that both cases give a contradiction.

7.3.1. The case $u_0 \neq 0$ in $\Omega \setminus B_{\infty}$. We assume that $\int_{\Omega \setminus B} |u_0| > 0$. In this case, since $(\operatorname{tr}_{\partial\Omega} u_0)|_{\partial\Omega \setminus \partial B_{\infty}} \equiv 0$, we have

$$\delta := \int_{\Omega \setminus B_{\infty}} |Du_0| > 0.$$

Recall that we fixed a sequence $(u_n)_n \subset C^{\infty} \cap BV(\Omega)$ s.t. $u_n \stackrel{BV}{\to} u_0 \& \operatorname{tr}_{\partial\Omega} u_n = \operatorname{tr}_{\partial\Omega} u_0$.

Therefore, for sufficiently large n, we have

$$\int_{\Omega \setminus B_{\infty}} |\nabla u_n| > \frac{\delta}{2}$$

Thus, from Lemma 8 we get [we use also $|V_{\infty}(x)| = 1$ for all $x \in B_{\infty}$]

$$\int_{\Omega} |\nabla u_n| \ge \int_{B_{\infty}} |\nabla u_n \cdot V_{\infty}| + \int_{\Omega \setminus B_{\infty}} |\nabla u_n| \ge |\mathcal{K}| + \frac{\delta}{2}.$$

This implies

$$\int_{\Omega} |Du_0| = \lim_n \int_{\Omega} |\nabla u_n| \ge |\mathcal{K}| + \frac{\delta}{2}$$

which is in contradiction with (18).

7.3.2. The case $u_0 \equiv 0$ in $\Omega \setminus B_{\infty}$. We first note that, since $\operatorname{tr}_{\partial D_0^+} u_0 \neq 0$, there exists a triangle $T_k^{N_0}$ s.t. $\int_{T_{k}^{N_{0}}} |u_{0}| > 0$. We fix such a triangle $T_{k}^{N_{0}}$ and we let α be its right-angle.

We let $\tilde{\mathcal{R}} = (\alpha, \tilde{\mathbf{e}}_1, \tilde{\mathbf{e}}_2)$ be the direct orthonormal frame centered in α where $\tilde{\mathbf{e}}_2 = \nu_{\mathscr{C}_k^{N_0}} [\nu_{\mathscr{C}_k^{N_0}}]$ is defined Remark 1.1], *i.e.*, the directions of the new frame are given by the side of the right-angle of $T_k^{N_0}$].

It is clear that for $N \ge N_0$ we have $V_N \equiv \tilde{\mathbf{e}}_2$ in $T_k^{N_0}$. By construction of B_{∞} , $T_k^{N_0} \cap B_{\infty}$ is a union of segments directed by \tilde{e}_2 , *i.e.* $\mathbb{1}_{B_{\infty}|T_k^{N_0}}(s,t)$ depends only on the first variable "s" in the frame $\tilde{\mathcal{R}}$.

Since $\int_{T_k^{N_0}} |u_0| > 0$, in the frame $\tilde{\mathcal{R}}$, we may find $a, b, c, d \in \mathbb{R}$ s.t., considering the rectangle (whose sides are parallel to the direction of \mathcal{R})

$$\mathcal{P} := \{ \alpha + s\tilde{\mathbf{e}}_1 + t\tilde{\mathbf{e}}_2 \, | \, (s,t) \in [a,b] \times [c,d] \} \subset T_k^{N_0}$$

we have

$$\int_{\mathcal{P}} |u_0| > 0.$$

Since from Lemma 5 the set B_{∞} has an empty interior [and that $\mathbb{I}_{B_{\infty}|_{T}^{N_{0}}}(s,t)$ depends only on the first variable in the frame $\tilde{\mathcal{R}}$], we may find a', b' s.t.

• $[a',b'] \times [c,d] \subset [a,b] \times [c,d],$ • $S \cap B_{\infty} = \emptyset$ with $S := \{\alpha + s\tilde{\mathbf{e}}_1 + t\tilde{\mathbf{e}}_2 \mid (s,t) \in \{a',b'\} \times [c,d]\}$ • $\delta := \int_{\mathcal{P}'} |u_0| > 0$ with $\mathcal{P}' := \{\alpha + s\tilde{\mathbf{e}}_1 + t\tilde{\mathbf{e}}_2 \mid (s,t) \in [a',b'] \times [c,d]\}.$

Moreover, since B_{∞} is a compact set, we may find an open neighborhood of S which do not intersect B_{∞} .

Noting that $u \equiv 0$ in $\Omega \setminus B_{\infty}$ and that the sequence $(u_n)_n$ is obtained by the convolution of u_0 with a C^{∞} -mollifier with compact support, it follows that for sufficiently large n we have

- $u_n \equiv 0$ in S_1
- $\int_{\mathcal{D}'} |u_n| > \frac{\delta}{2}.$

Consequently, from Lemma 3.2 in [ST14], we get [for sufficiently large n]

$$\int_{\mathcal{P}'} |\partial_{\tilde{\mathbf{e}}_1} u_n| \ge \frac{2}{b' - a'} \int_{\mathcal{P}'} |u_n| > \frac{\delta}{b' - a'} =: \delta'.$$

Therefore $\int_{\mathcal{P}'} |\partial_{\tilde{\mathbf{e}}_1} u_n| > \delta', \int_{\mathcal{P}'} |\partial_{\tilde{\mathbf{e}}_2} u_n| \le 2|\mathcal{K}|$ and then by Lemma 3.3 in [ST14] we obtain:

$$\int_{\mathcal{P}'} |\nabla u_n| \ge \int_{\mathcal{P}'} |\partial_{\tilde{\mathbf{e}}_2} u_n| + \frac{\delta'^2}{4|\mathcal{K}| + \delta'}$$

Thus, from Lemma 8, for sufficiently large n:

$$\int_{\Omega} |\nabla u_n| \ge |\mathcal{K}| + \frac{{\delta'}^2}{4|\mathcal{K}| + {\delta'}} - o_n(1).$$

From the convergence in BV-norm of u_n to u_0 we have

$$\int_{\Omega} |Du_0| \ge |\mathcal{K}| + \frac{{\delta'}^2}{4|\mathcal{K}| + {\delta'}}.$$

Clearly this last assertion contradicts (18) and ends the proof of Theorem 1.

APPENDICES

Appendix A. Results related with the Cantor set \mathcal{K}

A.1. Two preliminary results. We first prove a standard result which states that the length of a *small* chords is a good approximation for the length of a curve.

Lemma 10. Let $0 < \eta < 1$ and let $f \in C^2([0,\eta], \mathbb{R}^+)$. We fix an orthonormal frame and we denote C_f the graph of f in the orthonormal frame. Let $A = (a, f(a)), B = (b, f(b)) \in C_f$ (with $0 \le a < b \le \eta$) and let $\mathscr{C} = [AB]$ be the chord of C_f joining A and B. We denote \widehat{AB} the arc of C_f with extremities A and B. We have

$$\mathscr{H}^{1}(\mathscr{C}) \leq \mathscr{H}^{1}(\widehat{AB}) \leq \mathscr{H}^{1}(\mathscr{C}) \left\{ 1 + (b-a) \|f''\|_{L^{\infty}} [2\|f'\|_{L^{\infty}} + \|f''\|_{L^{\infty}} (b-a)] \right\}.$$

Proof. The estimate $\mathscr{H}^1(\mathscr{C}) \leq \mathscr{H}^1(\widehat{AB})$ is standard, we thus prove the second inequality.

On the one hand

$$\mathscr{H}^{1}(\mathscr{C}) = \sqrt{(a-b)^{2} + [f(a) - f(b)]^{2}} = (b-a)\sqrt{1 + \left(\frac{f(a) - f(b)}{a-b}\right)^{2}}.$$

On the other hand

$$\mathscr{H}^1(\widehat{AB}) = \int_a^b \sqrt{1 + f'^2}.$$

With the help of the Mean Value Theorem, there is $c \in]a, b[$ s.t.

$$\frac{f(a) - f(b)}{a - b} = f'(c).$$

Applying once again the Mean Value Theorem [to f'], for $x \in [a, b]$ there is c_x between c and x s.t.

$$f'(x) = f'(c) + f''(c_x)(x - c).$$

Consequently for $x \in [a, b]$ we have:

$$\begin{split} \sqrt{1+f'(x)^2} &= \sqrt{1+[f'(c)+f''(c_x)(x-c)]^2} \\ &= \sqrt{1+f'(c)^2}\sqrt{1+\frac{2f'(c)f''(c_x)(x-c)+f''(c_x)^2(x-c)^2}{1+f'(c)^2}} \\ &\leq \sqrt{1+\left(\frac{f(a)-f(b)}{a-b}\right)^2} \left[1+2\|f'\|_{L^{\infty}}\|f''\|_{L^{\infty}}(b-a)+\|f''\|_{L^{\infty}}^2(b-a)^2\right]. \end{split}$$

Thus we have

$$\begin{aligned} \mathscr{H}^{1}(\widehat{AB}) &= \int_{a}^{b} \sqrt{1 + f'(x)^{2}} \, \mathrm{d}x \\ &\leq (b-a) \sqrt{1 + \left(\frac{f(a) - f(b)}{a - b}\right)^{2}} \left[1 + 2\|f'\|_{L^{\infty}}\|f''\|_{L^{\infty}}(b-a) + \|f''\|_{L^{\infty}}^{2}(b-a)^{2}\right] \\ &= \mathscr{H}^{1}(\mathscr{C}) \left\{1 + (b-a)\|f''\|_{L^{\infty}} [2\|f'\|_{L^{\infty}} + \|f''\|_{L^{\infty}}(b-a)]\right\}. \end{aligned}$$

We now state another technical lemma which give an upper bound for the height of the curve w.r.t. its chord.

Lemma 11. Let $0 \le a < b \le \eta$, $f \in C^2([0,\eta], \mathbb{R}^+)$ be a strictly concave function and let C_f be the graph of f in an orthonormal frame. Let A = (a, f(a)) and B = (b, f(b)) be two points of C_f .

For $C \in [AB]$ we denote by \tilde{C} the intersection point of C_f with the line orthogonal to [AB] passing by C [from Remark 1.2, \tilde{C} is well defined].

We have

$$\mathscr{H}^1([C\tilde{C}]) \le (b-a)^2 \|f''\|_{L^{\infty}}.$$

Proof. We first note that if we let \tilde{x} be the abscissa of \tilde{C} and if we let P be the point of [AB] having \tilde{x} for abscissa, then $\mathscr{H}^1([P\tilde{C}]) \geq \mathscr{H}^1([C\tilde{C}])$ since the triangle $CP\tilde{C}$ is right-angled in C.

From the Mean Value Theorem, there exist C(~)

•
$$c_x \in]a, \tilde{x}[$$
 s.t. $f'(c_x) = \frac{f(\tilde{x}) - f(a)}{\tilde{x} - a}$
• $c \in]a, b[$ s.t. $f'(c) = \frac{f(b) - f(a)}{b - a}$
• \tilde{c} between c and c_x s.t. $f''(\tilde{c}) = \frac{f'(c_x) - f'(c)}{c_x - c}$

Moreover

$$\mathcal{H}^{1}([P\tilde{C}]) = \left| f(\tilde{x}) - \left[(\tilde{x} - a) \frac{f(b) - f(a)}{b - a} + f(a) \right] \right|$$

$$= |\tilde{x} - a| \left| \frac{f(\tilde{x}) - f(a)}{\tilde{x} - a} - \frac{f(b) - f(a)}{b - a} \right|$$

$$= |\tilde{x} - a| |f'(c_{x}) - f'(c)|$$

$$= |\tilde{x} - a| |c_{x} - c| |f''(\tilde{c})|$$

$$\leq (b - a)^{2} ||f''||_{L^{\infty}}$$

which gives the result.

A.2. Proof of Proposition 12. We prove that

(25)
$$\liminf_{N \to \infty} \mathscr{H}^1(\mathcal{K}_N) > 0.$$

Step 1. We prove that $\max_{k=1,...,2^N} \mathscr{H}^1(\mathscr{C}_k^N) \leq \left(\frac{2}{3}\right)^N$ For $N \geq 1$ we let $\{K_k^N \mid k = 1,...,2^N\}$ be the set of the connected components of \mathcal{K}_N . We let \mathscr{C}_k^N be the chord of K_k^N and we define $\mu_N = \max_{k=1,...,2^N} \mathscr{H}^1(\mathscr{C}_k^N)$. Note that by (10) we have $\mu_0 < 1$.

We first prove that for $N \ge 0$ we have

$$\mu_{N+1} \le \frac{2}{3}\mu_N$$

With the help of a standard recursive argument, we may prove that (26) implies [because $\mu_0 < 1$]

(27)
$$\mu_N \le \left(\frac{2}{3}\right)^N$$

In order to get (26), we prove that for $N \geq 1$ and K_k^N a connected component of \mathcal{K}_N and \mathscr{C}_k^N its chord, we have

(28)
$$\mathscr{H}^{1}[\mathscr{C}] \leq \frac{2\mathscr{H}^{1}(\mathscr{C}_{k}^{N})}{3} \text{ for } \mathscr{C} \in \mathcal{S}(\mathscr{C}_{k}^{N})$$

[see Notations 2 for $\mathcal{S}(\cdot)$, the set of sons of a chord].

Let $N \ge 1$, for $k \in \{1, ..., 2^N\}$ we let K_k^N be a connected component of \mathcal{K}_N . We let $K_{2k-1}^{N+1}, K_{2k}^{N+1} \in \mathcal{S}(K_k^N)$ be the curve obtained from K_k^N in the heredity step. For $\tilde{k} \in \{2k-1, 2k\}$, we let $\mathscr{C}_{\tilde{k}}^{N+1}$ be the chord of $K_{\tilde{k}}^{N+1}$. In the frame \mathcal{R}_0 , we may define four points of Γ , $(a_1, f(a_1)), (b_1, f(b_1)), (a_2, f(a_2)), (b_2, f(b_2))$, with $0 < a_1 < 1$

 $b_1 < a_2 < b_2 < \eta$ s.t.:

- the extremities of K^{N+1}_{2k-1} are (a₁, f(a₁))&(b₁, f(b₁));
 the extremities of K^{N+1}_{2k} are (a₂, f(a₂))&(b₂, f(b₂));
 the extremities of K^N_k are (a₁, f(a₁))&(b₂, f(b₂)).

In the frame \mathcal{R}_0 we let also $(\alpha_1, \beta_1), (\alpha_2, \beta_2)$ be the coordinates of the points of \mathscr{C}_k^N s.t. for $l \in \{1, 2\}$, the triangles whose vertices are $\{(a_l, f(a_l)); (b_l, f(b_l)); (\alpha_l, \beta_l)\}$ are right angled in (α_l, β_l) .

We denote

• \mathcal{I}_1 the segment $[(b_1, f(b_1)); (\alpha_1, \beta_1)];$ • \mathcal{I}_2 the segment $[(a_2, f(a_2)); (\alpha_2, \beta_2)].$ From the construction of $K_{2k-1}^{N+1} \& K_{2k}^{N+1}$ and from Pythagore theorem we have for l = 1, 2

$$\mathscr{H}^{1}(\mathscr{C}^{N+1}_{2k-2+l})^{2} = \mathscr{H}^{1}(\mathcal{I}_{l})^{2} + \left(\frac{\mathscr{H}^{1}(\mathscr{C}^{N}_{k}) - \mathscr{H}^{1}(\mathscr{C}^{N}_{k})^{2}}{2}\right)^{2}.$$

Using Lemma 11 we get that

$$\mathscr{H}^1(\mathcal{I}_l) \le (b_2 - a_1)^2 \|f''\|_{L^{\infty}}.$$

On the other hand we have obviously $b_2 - a_1 \leq \mathscr{H}^1(\mathscr{C}_k^N)$. Consequently we get

$$\begin{aligned} \mathscr{H}^1(\mathscr{C}^{N+1}_{2k-2+l})^2 &\leq \mathscr{H}^1(\mathscr{C}^N_k)^4 \|f''\|_{L^{\infty}}^2 + \left(\frac{\mathscr{H}^1(\mathscr{C}^N_k) - \mathscr{H}^1(\mathscr{C}^N_k)^2}{2}\right)^2 \\ &\leq \mathscr{H}^1(\mathscr{C}^N_k)^4 \|f''\|_{L^{\infty}}^2 + \frac{\mathscr{H}^1(\mathscr{C}^N_k)^2}{4}. \end{aligned}$$

Therefore

$$\mathscr{H}^{1}(\mathscr{C}^{N+1}_{2k-2+l}) \leq \frac{\mathscr{H}^{1}(\mathscr{C}^{N}_{k})}{2} \sqrt{1+4} \|f''\|_{L^{\infty}}^{2} \mathscr{H}^{1}(\mathscr{C}^{N}_{k})^{2},$$

thus using (11) we get

$$\mathscr{H}^1(\mathscr{C}^{N+1}_{2k-2+l}) \le \frac{2\mathscr{H}^1(\mathscr{C}^N_k)}{3}.$$

The last estimate gives (28) and thus (27) holds.

Step 2. We prove that
$$\liminf_{N\to\infty}\sum_{k=1}^{2^N}\mathscr{H}^1(\mathscr{C}_k^N)>0$$

For $N\geq 1$, we let

$$c_N = \sum_{k=1}^{2^N} \mathscr{H}^1(\mathscr{C}_k^N)$$

The main ingredient in this step consists in noting that, a son of \mathscr{C}_k^N is an hypothenuse of a right angled triangle which admits a side with length $\frac{\mathscr{H}^1(\mathscr{C}_k^N) - \mathscr{H}^1(\mathscr{C}_k^N)^2}{2}$.

Consequently we have

$$\mathscr{H}^{1}(\mathscr{C}^{N+1}_{2k-1}) + \mathscr{H}^{1}(\mathscr{C}^{N+1}_{2k}) \geq \mathscr{H}^{1}(\mathscr{C}^{N}_{k}) - \mathscr{H}^{1}(\mathscr{C}^{N}_{k})^{2}$$

Thus, summing the previous inequality for $k = 1, ..., 2^N$ we get

$$c_{N+1} = \sum_{k=1}^{2^N} \mathscr{H}^1(\mathscr{C}_{2k-1}^{N+1}) + \mathscr{H}^1(\mathscr{C}_{2k}^{N+1})$$

$$\geq \sum_{k=1}^{2^N} \mathscr{H}^1(\mathscr{C}_k^N)[1 - \mathscr{H}^1(\mathscr{C}_k^N)]$$

$$\geq c_N(1 - \mu_N)$$

$$\geq c_N\left[1 - \left(\frac{2}{3}\right)^N\right].$$

By a standard recursive argument we obtain for $N \ge 2$

$$c_N \geq c_1 \prod_{k=1}^{N-1} \left[1 - \left(\frac{2}{3}\right)^k \right]$$
$$= c_1 \times \exp\left[\sum_{k=1}^{N-1} \ln\left[1 - \left(\frac{2}{3}\right)^k \right] \right].$$

It is clear that $\liminf_N \sum_{l=1}^{N-1} \ln \left[1 - \left(\frac{2}{3}\right)^k\right] > -\infty$, thus $\liminf_N c_N > 0$.

Step 3. We prove (25).

Since for K_k^N , a connected component of \mathcal{K}_N , and \mathscr{C}_k^N its chord, we have $\mathscr{H}^1(\mathcal{K}_k^N) \geq \mathscr{H}^1(\mathscr{C}_k^N)$, from Step 2 we get (25).

Appendix B. Results related with the set B_{∞}

In this section we use the notations of Section 4.

Proposition 12. Let $\gamma \subset \widehat{AB}$ be a curve and let \mathscr{C} be its chord. We let γ_1, γ_2 be the curves included in γ obtained by the heredity construction represented Figure 1 [section 4.2]. For l = 1, 2, we denote also by \mathscr{C}_l the chord of γ_l and by T_l the right-angled triangle having \mathscr{C}_l as side of the right-angle and having its hypothenuse included in \mathscr{C} .

If $\mathscr{H}^1(\mathscr{C}) < (4\|f''\|_{L^{\infty}}^2)^{-2}$, then the hypothenuses of the triangles T_1 and T_2 have their length strictly lower than $\frac{\mathscr{H}^1(\mathscr{C})}{2}$. And in particular the triangles T_1 and T_2 are disjoint.

Proof. We model the statement by denoting M and Q the extremities of γ and N and P are points s.t.:

- M, N are the extremities of γ_1
- P, Q are the extremities of γ_2 .

We denote $\delta = \mathscr{H}^1([MQ])$.

We fix an orthonormal frame $\tilde{\mathcal{R}}$ with the origin in M, with the x-axe (MQ) and s.t. N, P, Q have respectively for coordinates $(x_1, y_1), (x_2, y_2)$ and $(x_3, 0)$ where $0 < x_1 < x_2 < x_3$ and $y_1, y_2 > 0$.

By construction we have

$$x_1 = \frac{\delta - \delta^2}{2}, x_2 = \frac{\delta + \delta^2}{2}$$
 and $x_3 = \delta$.

Moreover, from Lemma 11 we have [recall that AB is the graph of a function f in an other orthonormal frame]:

$$0 < y_1, y_2 \le \delta^2 ||f''||_{L^{\infty}}.$$



FIGURE 6. Modelisation of the situation

From these points, in Section 4.2, we defined two right-angled triangles having their hypothenuses included in the x-axes.

The first triangle admits for vertices the origin (0,0), (x_1, y_1) and a point of the x-axis $(x_4, 0)$. This triangle is right angled in (x_1, y_1) . In the frame $\tilde{\mathcal{R}}$, one of the side of the right-angle is included in the line parametrized by the cartesian equation y = ax. Since $\delta \leq 1/2$

$$|a| = \left|\frac{y_1}{x_1}\right| \le \frac{2\delta^2 \|f''\|_{L^{\infty}}}{\delta - \delta^2} \le 4\|f''\|_{L^{\infty}}\delta.$$

The second triangle admits for vertices (x_2, y_2) , $(x_3, 0)$ and a point of the x-axes $(x_5, 0)$. This triangle is right-angled in (x_2, y_2) . In the frame $\tilde{\mathcal{R}}$, one of the side of the right-angle is included in the line parametrized by the cartesian equation $y = \alpha x + \beta$ where

$$|\alpha| = \left|\frac{y_2}{x_2 - x_3}\right| \le \frac{2\delta^2 ||f''||_{L^{\infty}}}{\delta - \delta^2} \le 4||f''||_{L^{\infty}}\delta.$$

The proof of the proposition consists in obtaining

$$x_4 < \frac{x_3}{2}$$
 and $x_3 - x_5 < \frac{x_3}{2}$

We get the first estimate. With the help of Pythagore Theorem we have

$$x_1^2 + y_1^2 + (x_1 - x_4)^2 + y_1^2 = x_4^2$$

By noting that $y_1 = ax_1$ we have

$$x_4 = (1 + a^2)x_1.$$

Thus:

$$\begin{aligned} x_4 < \frac{x_3}{2} &\iff (1+a^2)\frac{\delta-\delta^2}{2} < \frac{\delta}{2} \\ &\iff (1+16\|f''\|_{L^{\infty}}^2\delta^2)(1-\delta) < 1 \\ &\iff \delta - \delta^2 < \frac{1}{16\|f''\|_{L^{\infty}}^2} \\ &\iff \delta < \frac{1}{16\|f''\|_{L^{\infty}}^2}. \end{aligned}$$

Following the same strategy we get that if $\delta < \frac{1}{16\|f''\|_{L^{\infty}}^2}$ then $x_3 - x_5 < \frac{x_3}{2}$.

APPENDIX C. ADAPTATION OF A RESULT OF GIUSTI IN [Giu84]

In this appendix we present briefly the proof of Theorem 2.16&Remark 2.17 in [Giu84]. The argument we present below follows the proof of Theorem 2.15 in [Giu84].

Proposition 13. Let $\Omega \subset \mathbb{R}^n$ be a bounded open set of class C^2 and let $h \in L^1(\partial \Omega)$. For all $\varepsilon > 0$ there exists $u_{\varepsilon} \in W^{1,1}(\Omega)$ s.t. $\operatorname{tr}_{\partial\Omega} u_{\varepsilon} = h$ and

$$\|u_{\varepsilon}\|_{W^{1,1}(\Omega)} := \|u_{\varepsilon}\|_{L^{1}(\Omega)} + \|\nabla u_{\varepsilon}\|_{L^{1}(\Omega)} \le (1+\varepsilon)\|h\|_{L^{1}(\Omega)}.$$

Proof. We sketch the proof of Proposition 13. Let $h \in L^1(\partial \Omega)$ and let $\varepsilon > 0$ be sufficiently small s.t.

$$(1+\varepsilon^2)^2+\varepsilon^2+\varepsilon^4<1+rac{\varepsilon}{2} ext{ and } (1+\varepsilon^2)\varepsilon^2<rac{\varepsilon}{2}.$$

Step 1. We may consider $\eta > 0$ sufficiently small s.t. in $\Omega_{\eta} := \{x \in \Omega \mid \operatorname{dist}(x, \partial \Omega) < \eta\}$ we have: (1) The function

(1) The function (1)

$$\begin{array}{rccc} d: & \Omega_{\eta} & \to &]0, \eta[\\ & x & \mapsto & \operatorname{dist}(x, \partial\Omega) \end{array}$$

is of class C^2 and satisfy $|\nabla d| \ge 1/2$.

(2) The orthogonal projection on $\partial\Omega$, $\Pi_{\partial\Omega}$, is Lipschitz.

We now fix a sequence $(h_k)_k \subset C^{\infty}(\partial\Omega)$ s.t. $h_k \xrightarrow{L^1} h$. We may assume that (up to replace the first term and to consider an extraction):

- (1) $h_0 \equiv 0$
- (2) $\sum_{k\geq 0} \|h_{k+1} h_k\|_{L^1} \le (1+\varepsilon^2) \|h\|_{L^1}.$

And finally we fix a decreasing sequence $(t_k)_k \subset \mathbb{R}^*_+$ s.t.

(1) $t_0 < \min(\eta, \varepsilon^2)$ is sufficiently small s.t.

- $4t_0 \max(1; \|\nabla \Pi_{\partial \Omega}\|_{L^{\infty}}) \times \max(1, \sup_k \|h_k\|_{L^1}) < \min(\varepsilon^2, \varepsilon^2 \|h\|_{L^1}),$
- for $\varphi \in L^1(\partial \Omega)$ we have for $s \in]0, t_0[$

$$\int_{d^{-1}(\{s\})} |\varphi \circ \Pi_{\partial\Omega}(x)| \le (1+\varepsilon^2) \int_{\partial\Omega} |\varphi(x)|.$$

(2) For
$$k \ge 1$$
 we have $t_k \le \frac{t_0 \|h\|_{L^1}}{2^k (1 + \|\nabla h_k\|_{L^\infty} + \|\nabla h_{k+1}\|_{L^\infty})}$.

Step 2. We define

$$\begin{aligned} u_{\varepsilon} : & \Omega & \to \\ x & \mapsto & \begin{cases} \frac{d(x) - t_{k+1}}{t_k - t_{k+1}} h_k \circ \Pi_{\partial\Omega}(x) + \frac{t_k - d(x)}{t_k - t_{k+1}} h_{k+1} \circ \Pi_{\partial\Omega}(x) & \text{if } d(x) \in [t_{k+1}, t_k[\ . \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

We may easily check that u_{ε} is locally Lipschitz and thus weakly differentiable.

From the coarea formula and a standard change of variable we have

$$\begin{split} u_{\varepsilon} \|_{L^{1}} &\leq 2 \int_{\{d \leq t_{0}\}} |u_{\varepsilon}| |\nabla d| \mathrm{d}x \\ &= 2 \int_{0}^{t_{0}} \int_{d^{-1}(\{s\})}^{t_{0}} |u_{\varepsilon}| \mathrm{d}x \\ &\leq 2 \sum_{k \geq 0} \int_{t_{k+1}}^{t_{k}} \mathrm{d}s \int_{d^{-1}(\{s\})} |u_{\varepsilon}| \mathrm{d}x \\ &\leq 2 \sum_{k \geq 0} \int_{t_{k+1}}^{t_{k}} \mathrm{d}s \int_{d^{-1}(\{s\})} [|h_{k} \circ \Pi_{\partial\Omega}(x)| + |h_{k+1} \circ \Pi_{\partial\Omega}(x)|] \mathrm{d}x \\ &\leq 2(1+\varepsilon^{2}) \sum_{k \geq 0} \int_{t_{k+1}}^{t_{k}} \mathrm{d}s \int_{\partial\Omega} [|h_{k}(x)| + |h_{k+1}(x)|] \mathrm{d}x \\ &\leq 2(1+\varepsilon^{2}) \sum_{k \geq 0} (t_{k} - t_{k+1}) (||h_{k}||_{L^{1}} + ||h_{k+1}||_{L^{1}}) \\ &\leq 4(1+\varepsilon^{2}) t_{0} \sup_{k} ||h_{k}||_{L^{1}} \\ &\leq (1+\varepsilon^{2})\varepsilon^{2} ||h||_{L^{1}} \\ &\leq \frac{\varepsilon}{2} ||h||_{L^{1}}. \end{split}$$

We now estimate $\|\nabla u_{\varepsilon}\|_{L^1}$. It is easy to check that if $d(x) \in [t_{k+1}, t_k]$ then we have

$$|\nabla u_{\varepsilon}(x)| \leq |\nabla d(x)| \left[\frac{|h_k \circ \Pi_{\partial\Omega}(x) - h_{k+1} \circ \Pi_{\partial\Omega}(x)|}{t_k - t_{k+1}} + 2\|\nabla \Pi_{\partial\Omega}\|_{L^{\infty}} \left[|\nabla h_k| \circ \Pi_{\partial\Omega}(x) + |\nabla h_{k+1}| \circ \Pi_{\partial\Omega}(x) \right] \right].$$

Consequently we get

$$\begin{aligned} \|\nabla u_{\varepsilon}\|_{L^{1}} &\leq (1+\varepsilon^{2}) \sum_{k\geq 0} \left\{ \int_{t_{k+1}}^{t_{k}} \frac{\|h_{k+1} - h_{k}\|_{L^{1}}}{t_{k} - t_{k+1}} + 2\|\nabla \Pi_{\partial\Omega}\|_{L^{\infty}} (t_{k} - t_{k+1}) (\|\nabla h_{k+1}\|_{L^{1}} + \|\nabla h_{k}\|_{L^{1}}) \right\} \\ &\leq (1+\varepsilon^{2}) [(1+\varepsilon^{2})\|h\|_{L^{1}} + 2\|\nabla \Pi_{\partial\Omega}\|_{L^{\infty}} t_{0}\|h\|_{L^{1}}] \\ &\leq (1+\varepsilon^{2}) [(1+\varepsilon^{2}) + \varepsilon^{2}]\|h\|_{L^{1}} \\ &\leq (1+\varepsilon/2)\|h\|_{L^{1}}. \end{aligned}$$

Consequently $u_{\varepsilon} \in W^{1,1}(\Omega)$ and $\|u_{\varepsilon}\|_{W^{1,1}} \leq (1+\varepsilon)\|h\|_{L^1}$.

In order to end the proof it suffices to check that $\operatorname{tr}_{\partial\Omega}(u_{\varepsilon}) = h$. The justification of this property follows the argument of Lemma 2.4 in [Giu84].

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