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Rupture process of the Mw=7.9 2015 Gorkha earthquake (Nepal): insights into Himalayan megathrust segmentation

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Key points

- Uniform rupture velocity during peak moment release explains modest acceleration in Kathmandu
- High-frequency radiation occurred preferentially along the down-dip edge of the high slip patch
- The MHT is locked up-dip of the 2015 event, suggesting high level of seismic hazard toward the front

Abstract (149 words)

We investigate the rupture process of the 25 April 2015 Gorkha earthquake (Mw=7.9) using a kinematic joint inversion of teleseismic waves, strong-motion data, high-rate GPS, static GPS and SAR data. The rupture is found to be simple in terms of coseismic slip and even more in terms of rupture velocity, as both inversion results and a complementing back projection analysis show that the main slip patch broke unilaterally at a steady velocity of 3.1-3.3km/s. This feature likely contributes to the moderate peak ground acceleration (0.2g) observed in Kathmandu. The ~15km deep rupture occurs along the base of the coupled portion of the Main Himalayan Thrust, and does not break the area ranging from Kathmandu to the front. The limitation in length and width of the rupture cannot be identified in the pre-earthquake interseismic coupling distribution, and is therefore discussed in light of the structural architecture of the megathrust.

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Index Terms

- 7215 Earthquake source observations
- 7230 Seismicity and tectonics
- 1240 Satellite geodesy: results
- 1242 Seismic cycle related deformations
- 8170 Subduction zone processes

Keywords

earthquake, rupture process, kinematic inversion, Himalaya, interseismic coupling, back projection

1. Introduction

Central Nepal, including its capital Kathmandu, has been considerably damaged by the Gorkha earthquake of 25 April, 2015. The event resulted in more than 9,000 fatalities, mostly due to building collapse and induced landslides. Tectonically, the Gorkha earthquake is rooted in the core of the Main Himalayan Thrust (MHT) system, which accommodates the 18 mm/yr convergence between India and Tibet [Avouac and Tapponnier, 1993; Lavé and Avouac, 2000] (Figure 1). Geology, thermochronology and geomorphology suggest that the plate interface hosts several flats and ramps [e.g. Bollinger et al., 2004b; Herman et al., 2010], which makes the MHT more geometrically complex than most subduction megathrusts. However, geodetic and seismological studies indicate that the ~100km most frontal portion of the

MHT was fully locked and largely aseismic in the decades preceding the Gorkha earthquake. Therefore, the actual geometry of the MHT in the shallow seismogenic zone is difficult to determine from geodesy or seismology [e.g. Vergne et al., 2001].

Historical seismicity associated with the MHT is characterized by infrequent, large megathrust earthquakes that occasionally break the MHT up to its frontal expression along the Main Frontal Thrust (MFT) [Bilham et al., 2001]. Paleoseismology has provided evidence for earthquakes with magnitudes exceeding M8.5 associated with surface ruptures reaching the MFT [e.g., Sapkota et al., 2013] (Figure 1). However, historical records suggest that large, blind earthquakes do also take place, such as the 1833 earthquake (M7.3-7.7) that occurred near Kathmandu [Szeliga et al., 2010]. The significance of these blind earthquakes in releasing part of the interseismically-accumulated strain is of paramount importance for quantifying slip deficit of the MHT and for assessing associated seismic hazard.

The 2015 Mw7.9 Gorkha earthquake is the largest earthquake occurring on the MHT since the great 1934 Bihar-Nepal earthquake [Sapkota et al., 2013]. As the MHT appears to remain fully locked along most of its length [Ader et al., 2012], the Gorkha earthquake provides the first opportunity to bring to light the seismogenic characteristics of the MHT.

Using a combination of seismological and geodetic observations, we jointly constrain the static and kinematic characteristics of the Gorkha earthquake rupture. The features of the rupture model are related to the local seismic radiations recorded in Kathmandu and interpreted in the light of the broader context of pre-seismic strain accumulation and long-term architecture of the MHT.

2. Data and Methods

2.1. Broadband kinematic inversion of the rupture process

The Gorkha earthquake has been recorded by different types of geodetic and seismic sensors, including Synthetic Aperture Radar (SAR) and continuous GPS measurements, local ground motion and teleseismic data. For this large shallow continental earthquake, SAR data are particularly valuable to constrain the spatial distribution of final slip, while ground motion data control its temporal evolution.

The line-of-sight (LOS) component of static surface displacement is mapped using SAR data acquired by the C-band satellite Sentinel-1A of the European Space Agency and the L-band satellite ALOS-2 of the Japan Aerospace Agency (Tab. S1). Both ascending and descending geometries are used to constrain separately horizontal and vertical components of ground motion (Figure 2c). The short revisit time of the two platforms made it possible to isolate the coseismic displacement induced by the 12 May 2015 large aftershock (Mw7.3). Sentinel-1 data are processed using the interferometric SAR (InSAR) technique according to the method of Grandin [2015]. Unfortunately, interferometric coherence was insufficient to ensure correct phase unwrapping for the mainshock, due to the combination of large surface displacements, rough topography, vegetation and snow/ice cover, large perpendicular baselines and possibly pervasive landsliding. Alternatively, dense pixel tracking was computed, taking advantage of the fine range resolution of the platform (2.3m), yielding a theoretical accuracy of the order of 20cm in the LOS. The ALOS-2 InSAR data are from Lindsey et al. [2015].

SAR data are complemented by static offsets of the Nepal GPS Geodetic Network. Nine stations located less than 200km from the epicenter are considered in this study (Figure 2a and 3a).

Local ground motion data include five GPS stations from the same network, processed at high-rate (5Hz), complemented with the KATNP accelerometer in Kathmandu (Figure 2a). Near-fault displacement records (KKN4, NAST, KATNP) and farther ones (RMTE, SNDL, SYBC) are low-pass filtered at 0.1Hz and 0.05Hz, respectively, in order to account for the increasing inaccuracy of wave modeling with distance. A high-pass filter of 0.015Hz and 0.01Hz is applied to the KATNP displacement records and to the HRGPS data, respectively. We finally add the teleseismic body-wave P and SH records to this data set, for their ability to resolve the global temporal evolution of the earthquake. We use broad-band signals from the Federation of Digital Seismograph Networks (FDSN), with an azimuthal coverage avoiding locations

where radiation pattern predicts low amplitude waves. Both P and SH displacement waveforms are bandpass filtered between 0.005Hz and 0.125Hz.

This geodetic and seismic dataset is simultaneously inverted using the method of Delouis et al. [2002]. The model consists of a single fault segment, 153km long and 72km wide, subdivided into 136 subfaults measuring 9km along strike and dip, evenly distributed on the fault plane. The geometry of the fault is held fixed, controlled by its strike and dip angles (strike=285°, dip=7°), the epicentral location (84.75°E;28.24°N) provided by NSC (Nepal National Seismological Centre) and an hypocentral depth of 16km. These values have been previously optimized by a careful analysis of independent data types. In particular, the shallow dip is required both by SAR and teleseismic data and is in agreement with global analyses [e.g., GCMT, Ekström et al., 2012; SCARDEC, Vallée et al., 2011]. As for depth determination, when the rupture approaches the surface, teleseismic data require increasingly more seismic moment, while SAR data require increasingly less slip. As a consequence, shallower or deeper depths lead to discrepancies between teleseismic and SAR data.

To model the waveforms, the continuous rupture is approximated by a summation of point sources at the center of each subfault. For each point source, the local source time function is represented by two mutually overlapping isosceles triangular functions of duration equal to 6s. For each of the 136 subfaults, the parameters to be inverted are the slip onset time, the rake angle, and the amplitudes of the two triangular functions. A nonlinear inversion is performed using a simulated annealing optimization algorithm. Convergence criterion is based on the minimization of the root mean square (rms) data misfit, with optional smoothing constraints on the coseismic slip, rupture velocity and rake angle variations, used in order to penalize unnecessarily complex models. In particular, the smoothing constraint on the rupture velocity is implemented by penalizing models with large variations of the average rupture velocity (from the hypocenter to the considered subfault) between adjacent subfaults.

All synthetic data (seismograms and static offsets) are computed in the same stratified crustal model (Tab. S2). This model takes into account the deep Moho in Northern Nepal (48km) and the relatively low P-wave velocities (5.6km/s) at shallow depth indicated by several studies [e.g. Monsalve et al., 2006]. Results in terms of coseismic slip vary marginally

if using other crustal models due to the strong control provided by SAR data. Local synthetic seismograms (HRGPS and accelerometric data) and teleseismic P and SH displacements are computed using the discrete wave number method of Bouchon [1981] and the reciprocity approach of Bouchon [1976], respectively. Static displacements (for static GPS and SAR) are computed using the static Green functions approach of Wang et al. [2003].

2.2. High-Frequency source emissions from teleseismic back projection

The spatiotemporal history of high-frequency (HF) source emissions is determined by back projection of teleseismic P waves recorded at the Virtual European Broadband Seismic Network (VEBSN) [van Eck et al., 2004], at stations in Australia and Southeast Asia, and in Alaska (Figures 2d and S1). P-wave velocity records are filtered between 1.0 and 4.0Hz and back projected over a source grid of 350km along strike and 200km along dip, with an interval of 5km. Theoretical travel times are computed using a 1D global velocity model [Kennett et al., 1995]. Station corrections, accounting for deviations from the 1D model, are calculated by cross-correlation of the first-arrival P waveforms, preliminarily aligned according to the NSC hypocenter. For each grid node, we compute a normalized trace stack weighted by semblance [Vallée et al., 2008], and we search for peaks of the stack power, in space and time, using a local maximum filter (Figures S1 and S2). Finally, back projection peak times are corrected for the directivity effect, computed as the difference between the P-wave travel time from the given peak and the travel time from the hypocenter (for an average station location). More details on the back projection technique, which is related to the methods of Xu et al. [2009] and Ishii et al. [2005], can be found in Satriano et al. [2012] and Vallée and Satriano [2014].

2.3. Interseismic strain accumulation

We also use surface displacement measurements acquired before the earthquake to quantify the spatial distribution of interseismic coupling on the plate interface (Figures S3 and S4). We update the solution of Grandin et al. [2012] by modeling deformation using a backslip approach with a dislocation embedded in an elastic half-space with depth-dependent rigidity [Vergne et al., 2001]. The fault has a constant dip of 7°, and coincides with the 2015 coseismic fault. Its strike varies

smoothly so as to follow the trace of the MFT. The interface is divided into 32 km (along-strike) by 10 km (along-dip) rectangular patches. Smoothing is achieved by Laplacian constraints introduced in the model covariance matrix. The smoothing intensity is controlled by a meta-parameter whose value is adjusted by a L-curve criterion approach. Bounds on the convergence rate between 0 and 18 mm/yr are implemented by means of sequential quadratic programming. Rake is fixed so that the azimuth of convergence is everywhere N10°E. The horizontal components of surface displacement are constrained using a compilation of GPS data from Bettinelli et al. [2006], Feldl and Bilham [2006], Socquet et al. [2006], Gan et al. [2007], Banerjee et al. [2008] and Ader et al. [2012]. Leveling data from Jackson and Bilham [1994] for the period 1977–1990 are also used for the vertical component.

3. Results and discussion

3.1. Rupture process and relations with strong motion generation

The source process shown in Figure 2 corresponds to a kinematic fault slip inversion giving similar weights to the four data types (SAR, GPS, local waveforms and teleseismic data), with small smoothing constraints on slip amplitude, rupture velocity and rake angle. Rupture velocity is here constrained to be between 2.1km/s and 3.3km/s (see Figure S5). As illustrated in the supplementary material (Figures S6 and S7), the retrieved source process is essentially the same when allowing for a wider range of possible rupture velocity and for a full relaxation of slip and rupture velocity smoothing constraints. The kinematic fault slip inversion and back projection reveal that the rupture propagated unilaterally from West to East over a distance of 120km (Figure 2a). Spatiotemporal distributions of coseismic slip and back projection peaks are in good agreement, at a time resolution of 10s (Figures 2b and 2d). At smaller time scales, the effect of crust-reflected phases (pP and sP) can affect the relative timing of back-projection peaks [Okuwaki et al., 2014; Yagi and Okuwaki, 2015], with however only minor distortion of the relative peak location as discussed, for instance, in Fan and Shearer [2015]. The obtained source time function (Figure 2e) shows that the total duration of the earthquake is close to 50s and its seismic moment is 7.7×10^{20} N.m ($M_w=7.86$). The rupture history shown in Figure 2b is in good agreement with all the data used in

the kinematic inversion (Figure 2c and 3). The dominant feature of the slip model is a 13-15km deep patch (slip larger than 4m and reaching 7m) whose rupture starts 10s after earthquake initiation, 25km southeast of the epicenter. This patch has a size of about 80km along strike and 25km along dip, an elongated aspect ratio very well constrained by the SAR data (Figure 2c). Aftershocks delineate the contours of this patch (Figure 2a), as a result of static stress transfer induced by the maximum slip gradients [e.g. Rietbrock et al., 2012]. Dynamic stress transfer can explain the larger number of aftershocks at the eastern termination of the rupture, as this area has experienced more dynamic stress due to the eastward rupture propagation. This area ruptured again on 12 May 2015 with an earthquake of Mw7.3 (Figure S8), that was itself followed by an abundant aftershock sequence.

Rupture speed inside the main slip patch is well constrained by seismic data and in particular by the three records close to Kathmandu (KATNP, KNAS, KKN4, see Figure 3b), and is stable around 3.1-3.3km/s (Figures 2b, S5 and S7). This finding is confirmed by back projection analysis. Inside this patch, the rake shows only small variations, with values ranging between 90° and 100° (Figure 2a). This simple rupture process (single patch breaking with the same mechanism at constant rupture velocity) is a feature which is little affected by the band-limited frequencies used in the inversion, as illustrated by the good waveform agreement at station KKN4 for frequencies up to 1Hz (Figure S9). Together with the fact that no high-frequency emission is recorded in the updip part of the rupture from back projection, this indicates that the rupture process was smooth as it passed North of Kathmandu, and likely explains the relatively low peak ground acceleration (PGA) recorded in the capital (KATNP site, located only 20km from the high slip patch, recorded a PGA of only 0.2g, a value well below ground motion predictions [Goda et al., 2015; Galetzka et al., 2015]). Indeed, abrupt changes of rupture velocity are theoretically known [Madariaga, 1977; Campillo, 1983; Sato, 1994] and have been observed [Vallée et al., 2008] to be the main origin of high frequency radiations. The smooth character of the main patch rupture is also in good agreement with the study of Denolle et al. [2015], indicating that the fall-off rate of the P teleseismic spectrum increases 15s after rupture initiation.

3.2. The Gorkha earthquake in the context of the Himalayan collision zone

Slip distribution of the 2015 Gorkha earthquake is imaged to spread over an area of 120x35km parallel to the main trend of the mountain range ($\sim N110^\circ$) at a depth of ~ 15 km (Figure 2). The earthquake appears to have broken a portion of the MHT where coupling decreases from 100% (updip edge of the coseismic patch) to less than 25% (downdip edge) in less than 50km (Figures 4, S3 and S4). This coupling gradient is highlighted by a belt of earthquakes that spatially follows the front of the High Himalayan range, at a depth of ~ 15 km. This seismic belt likely reflects stress concentration around the transition to deep stable sliding [e.g. Bilham et al., 2001 ; Bollinger et al., 2004a]. Coseismic slip shows a rapid decrease in the downdip direction, consistent with the decreasing coupling limiting the propagation of the rupture to greater depths. The downdip edge of the rupture zone also coincides spatially with locations of high-frequency emission (Figure 2a), as also evidenced by Yagi and Okuwaki [2015] and by Fan and Shearer [2015]. These observations suggests strong similarities with the behavior of megathrust earthquakes, where high-frequency radiations originate from the base of the seismogenic domain [Lay et al., 2012]. This feature is interpreted as a possible effect of the variability with depth of frictional and stress heterogeneity along the fault interface. The particularity of this transition zone in the Himalaya is its coincidence with the inferred junction between the frontal flat and a deeper ramp dipping at a steeper angle [Cattin and Avouac, 2000] (Figure 4b). As the feedbacks between geometry and seismic potential of the interface are difficult to ascertain, this coincidence may equally point to either a geometric-structural and/or to a thermal-rheological control as the underlying cause of the coupling gradient at the scale of a seismic cycle.

In contrast, the updip limit of coseismic slip cannot be readily interpreted in terms of a local decrease of the coupling ratio, as argued elsewhere to justify the arrest of large subduction earthquakes and ultimately the segmentation of seismicity [e.g., Métois et al., 2012]. On the contrary, coupling appears to be maximal to the south of the main slip patch, up to the MFT (Figure 4a). A similar situation has been observed in the case of the 2007 Tocopilla earthquake (Chile), which has occurred along the downdip limit of a highly coupled segment of the Chile megathrust. Structural complexity within the overriding plate was invoked as a factor contributing to the updip arrest of the 2007 Tocopilla rupture [Béjar-Pizarro et al., 2010] and, more widely, to the geometry of the transition zone and segmentation of the Chile megathrust [Béjar-Pizarro et al., 2013; Armijo et al. 2015]. In Nepal, the updip limit of the 2015 rupture zone broadly corresponds, in map view, with

the southern limit of the antiform of Lesser Himalayan units observed all along Central Nepal Himalaya (Figure 1). This antiform is generally interpreted as resulting from stacking-up of slices of upper-crustal material of Indian affinity involving several generations of ramps and flats [e.g. Schelling and Arita, 1991; Bollinger et al., 2004b; Khanal and Robinson, 2013]. If correct, this accretionary model has given rise to a complex geometry of the MHT at the location of the 2015 Gorkha earthquake. This along-dip structural complexity may have played a role in impeding the propagation of the coseismic rupture toward the surface.

In the same line, lateral (east and west) limits of the coseismic slip are at odds with the first-order along-strike uniformity of interseismic strain accumulation in Central Nepal. In map view, the MHT appears to be fully locked between the High Himalayan Range and the trace of the MFT, approximately 100km to the south (Figure 4a). We note that the absence of large lateral variations in interseismic coupling cannot be explained by insufficient spatial sampling of GPS stations [Ader et al., 2012]. Alternatively, the along-strike extension of the 2015 earthquake broadly matches with a section exhibiting a relatively uniform structural surface expression between 84.5°E and 86.0°E (Figure 1). This section, which we refer to as the “Kathmandu segment”, is characterized by (1) a narrower Lesser Himalayan antiform with its culmination (green dashed line in Figure 1) located further toward the hinterland compared to other sections in Central Nepal, as attested by a northerly trace of the MCT, (2) a better preservation of the Higher Himalaya crystalline nappe, forming the broad Kathmandu klippe and (3) a rather uniform parallelism of the MFT and MBT, terminated by MBT reentrants at segment extremities. These features are likely indicative of lateral variations in the steepness, depth and/or stacking history of the MHT in the area.

Ultimately, the origin of these lateral variations may be partly attributed to lateral sweeping of the interface as heterogeneities within the upper crustal cover of the Indian plate, such as ridges or troughs in the Ganga Basin, are underthrust below the MHT [Bollinger et al., 2004b ; Denolle et al., 2015]. Modifications of the MHT geometry imparted by such variations in boundary conditions can be relatively immediate. However, the geomorphological expression of these modifications can be delayed due to the comparatively long response time of erosion processes, so that correlating the geological record and instantaneous deformation may not be straightforward [Grandin et al., 2012].

3.3. Implications for seismic hazards

The Gorkha earthquake provides a direct confirmation of the seismogenic potential of the MHT but also illustrates the great difficulty in anticipating along-dip and along-strike limits of future megathrust earthquakes based solely on the mapping of interseismic coupling. Even so, a first-order conclusion that can be drawn from the size and location of the 2015 Gorkha event is its failure to release a significant fraction of the tectonic strain previously accumulated within the MHT system in the broad Kathmandu area. With an average slip of $\sim 4\text{m}$, the earthquake has only accommodated approximately 200 years of local slip accumulation. The 2015 blind rupture could therefore be interpreted as the repetition of the 1833 earthquake [Bollinger et al., 2015] (Figure 1). However, the frontal part of the MHT, which was not activated by the earthquake, appeared to be fully locked before the event (Figure 4). The previous great earthquake in the area dates back to at least 1505 and probably to 1344, which represents more than 10m of slip accumulation. The updip arrest of the 2015 rupture does not preclude a seismogenic potential of the MHT at shallow depth, as exemplified by the updip progression of the earthquake sequence in the Mejillones peninsula area, in Chile, with a relatively deep M7.5 earthquake in 1987 followed by the shallower M8.1 Antofagasta earthquake in 1995 [Delouis et al., 1997].

Actually, static stress transfer induced by the 2015 Gorkha earthquake can only add to this worrying situation. It is currently impossible to exclude that the slip deficit remaining at shallow depths will be filled by continuous creep of the interface or by a relatively low-frequency, potentially less destructive continental analogue of the so-called tsunami earthquakes described in subduction settings [Lay et al., 2012]. Continued geodetic monitoring of the area in the coming years will provide a quantitative answer to these speculations. Nevertheless, except for the unlikely detection of a massive afterslip event taking place within the shallow part of the MHT, it is currently unsafe to discard a scenario whereby the frontal part of the megathrust will rupture during a great earthquake in the future. This scenario would be entirely in keeping with the conclusions previously drawn from geodetic, paleoseismological and historical inferences [e.g., Bilham et al., 2001]. Finally, even if only a fraction of the gap south of the 2015 rupture zone breaks in a future earthquake - resulting in an earthquake in the Mw7-to-8 magnitude range -, a realistic scenario with a rupture closer to Kathmandu and involving

more high frequency emissions, might still affect the city in a stronger way than the 2015 Gorkha earthquake.

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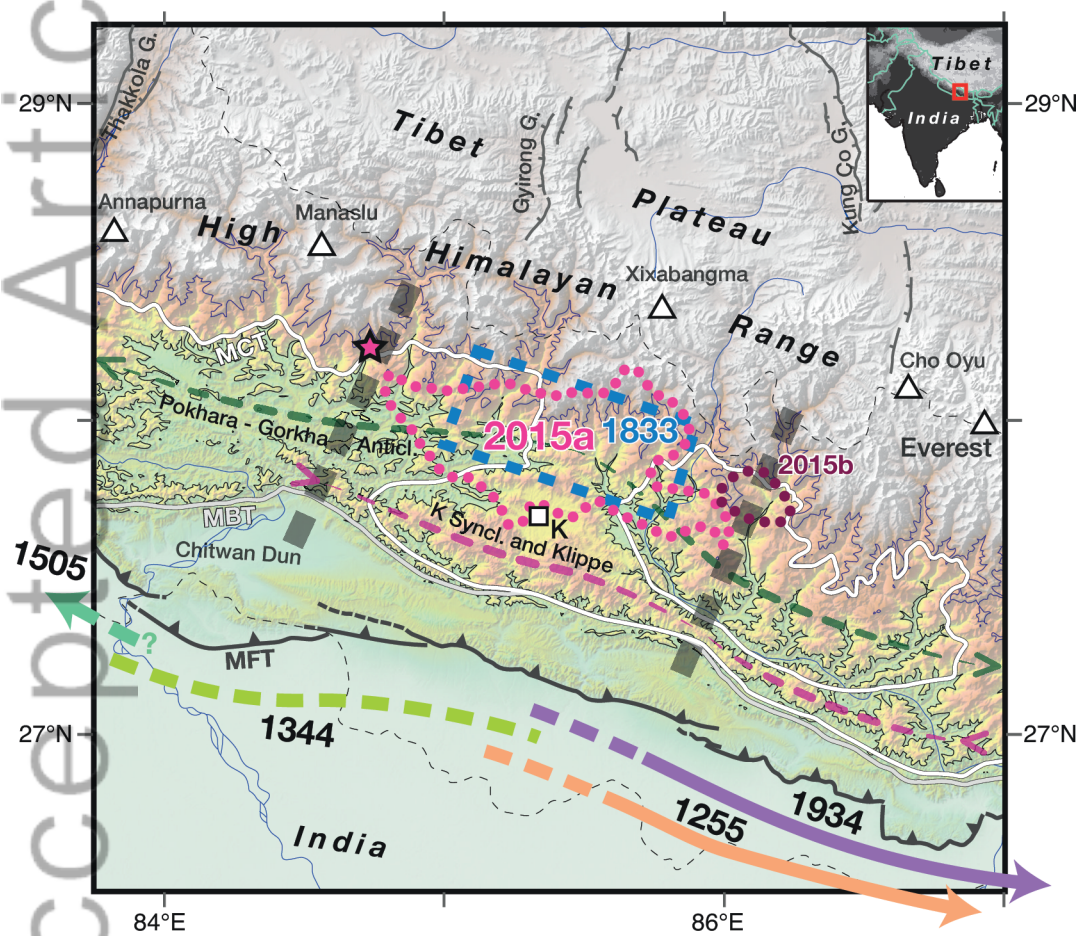
Figures

Figure 1. Tectonic and paleoseismological background of the 2015 Gorkha earthquake. Thick dashed arrows indicate lateral extension of surface rupture of past great earthquakes. Location of the 1833 earthquake (in blue) is from Bollinger et al. [2015]. The pink and brown dotted lines show the area of significant slip ($>2\text{m}$) of the 25 April 2015 Gorkha earthquake mainshock and the 12 May 2015 aftershock, respectively [this study]. Epicenter of the mainshock reported by NSC is indicated by the pink star. Green and purple dashed lines show the location and along-strike tapering of the Pokhara-Gorkha anticline and Kathmandu synclinal, respectively. Thick grey lines delimit the inferred Kathmandu segment. The 1000 m and 3000 m elevation contours are represented by thin black lines. White triangles indicate peaks with elevation higher than 8,000 m. Normal faults are indicated by grey barbed lines. MFT : Main Frontal Thrust; MBT : Main Boundary Thrust; MCT : Main Central Thrust; K : Kathmandu.

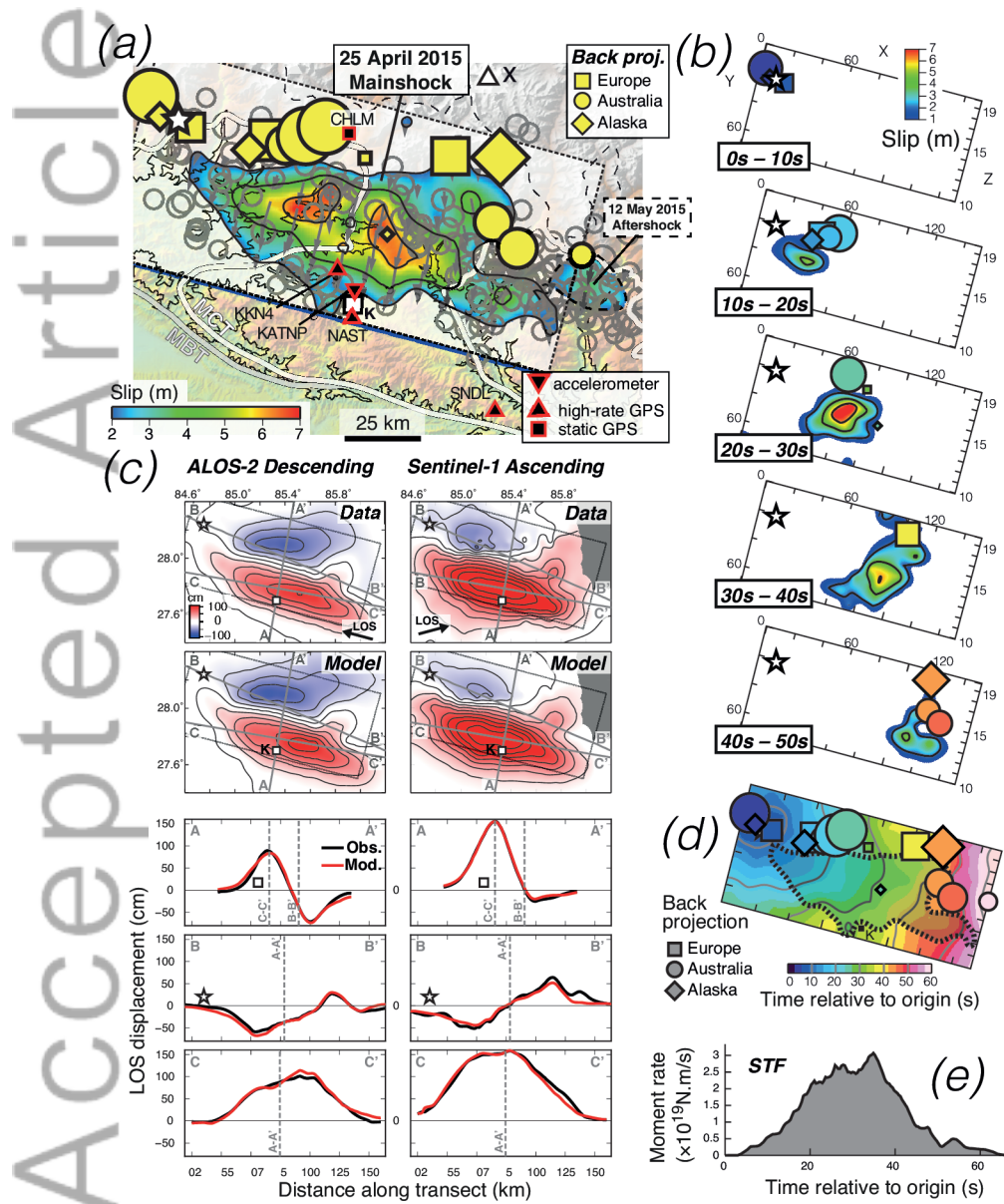
Figure 2. Rupture process of the Gorkha earthquake. (a) Slip distribution with 2 m slip contours. Grey dashed line delineates the surface projection of the modeled fault. Grey arrows show the direction of slip. Yellow symbols are back projection peaks, with their size proportional to the relative stack power. Grey circles are $M>4.5$ aftershocks reported by Adhikari et al. (2015) until 8 June 2015. White star is NSC hypocenter. White square indicates location of Kathmandu city. Red symbols show the location of the closest stations used in this study. Slip model of the 12 May aftershock constrained by inversion of InSAR data (Figure S8) is indicated by a dashed contour. (b) Snapshots of slip distribution as a function of time deduced from kinematic inversion. Squares and circles indicate location of back projection peaks for every time frame. (c) Observed and modeled surface displacement from ALOS-2 descending InSAR (left) and Sentinel-1 ascending range pixel tracking (right). The black arrow indicates line-of-sight (LOS) direction. A positive sign indicates motion toward the satellite, whereas negative sign corresponds to motion away from the satellite. The bottom panels show transects across the observed and modeled surface displacement fields at locations shown by the grey lines in the maps. (d) Back projection (BP) peaks (1.0 - 4.0 Hz) superimposed on isochrones of kinematic inversion relative to hypocentral time. The dashed line shows the 2m slip contour. (e) Source time function (STF) from kinematic inversion.

Figure 3. Comparison of observed and modeled (a) GPS displacements, (b) high-rate GPS and accelerometric records and (c) teleseismic records. In the three subfigures, data are in black and synthetics in red. In (c) the text shown for each seismogram has the format: name of the station, type of the wave, maximum amplitude in microns, and azimuth to the North in degrees.

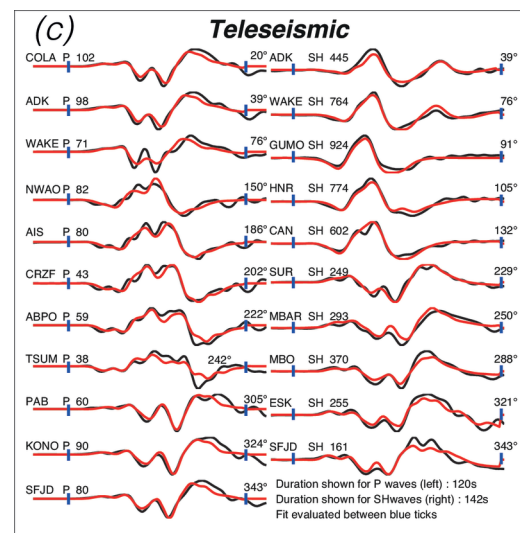
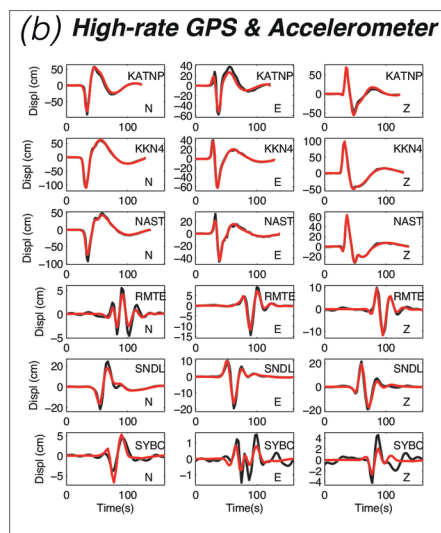
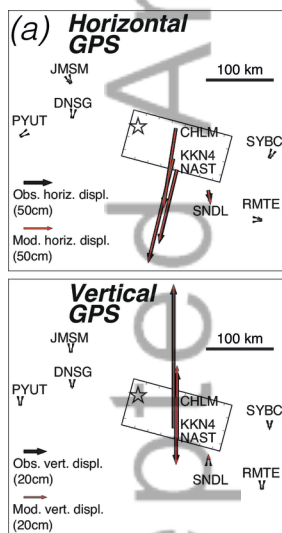
Figure 4. (a) Interseismic coupling distribution on the Main Himalayan Thrust (MHT) deduced from GPS (green circles) and leveling (white circles) [this study]. Slip contours of the 2015 Gorkha earthquake (25 April) and its main aftershock (12 May) are indicated by pink and brown lines, respectively [this study]. The NSC hypocenter of the mainshock is shown by the pink star. Blue circles show the seismicity recorded by the Nepalese network for the period 1995-2003 [Rajure et al., 2013]. (b) Superimposition of interseismic coupling model and seismicity (dashed black box in (a)) and geological cross-section of Bollinger et al., 2004b (transect A-A'). Pink arrow indicates along-dip extension of the 2015 Gorkha earthquake [this study]. Histograms show distribution of 1995-2003 seismicity.



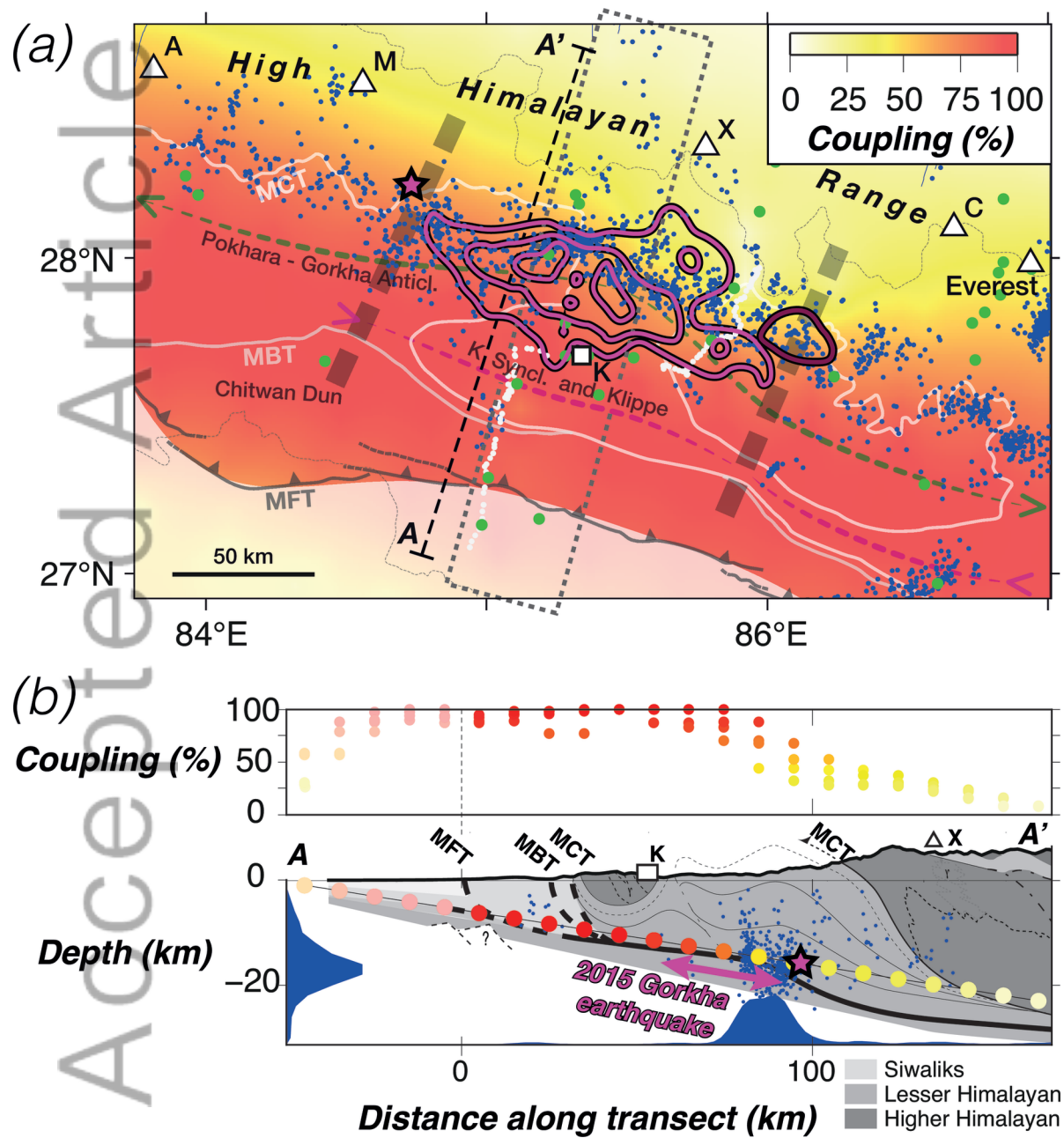
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