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Towards a general framework for an observation and knowledge based model of occupant behaviour in office buildings

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Abstract

This paper proposes a new general approach based on Bayesian networks to model the human behaviour. This approach represents human behaviour with probabilistic cause-effect relations based not only on previous works, but also with conditional probabilities coming either from expert knowledge or deduced from observations. The approach has been used in the co-simulation of building physics and human behaviour in order to assess the CO₂ concentration in an office.

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Keywords: occupant behaviour, indoor air quality, bayesian network

1. Introduction

Most of the world standards for buildings take occupants into account by representative values and deterministic scenarios: number of occupants, predefined schedules, and responses to an exceeded threshold. Nevertheless, in low consumption buildings, the impact of occupant behaviour strongly influences energy consumption and indoor climate conditions. For instance, if air quality is poor, occupants may decide to open windows or doors, which may depend on other occupants' activities or wishes. Therefore it is important to take into account occupant behaviour when estimating energy consumption.

A high performance building should be efficient for a large diversity of use. Therefore, in building simulation it

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is necessary to simulate the physical aspects of the building with its appliances, and the behaviour of its reactive occupants i.e. those occupant behaviours affecting indoor conditions such as temperature or air quality. Numerical models usually take into account occupant behaviour based on presence and on different profiles for opening windows. However, this may be insufficient since some simulation software handles the occupant model and the windows model separately, potentially leading to a situation where the occupant is absent, but the window is opened. In addition, profiles rely on data collected from specific observations. This makes it difficult to adapt them to other buildings or homes. This paper proposes a design methodology based on a knowledge model of occupant behaviours similar to the models used in building physics. Occupants' behaviours are designed using an a priori knowledge of future occupants and observations of behaviour to tune some of the model's parameters. This model is then used for co-simulating physical and human aspects. The approach relies on Bayesian Networks (BN) and represents human behaviour by probabilistic cause-effect relations based on experts' knowledge, and conditional probabilities coming either from the latter analysed observations.

The approach is applied to the co-simulation of an office combining a behavioural model representing occupancy and actions on doors and windows, and a CO_2 physical models. The model of the human behaviour is tuned according to experimental data.

2. State of the art

In the scientific community of building physics, simulation programs are becoming more advanced and there has been much effort to improve the prediction accuracy by taking in account occupant behaviour. Studies have shown its importance for energy waste reduction in buildings [1]. Lee and his colleagues have explained the relation between behaviour and energy performance by using Energy Plus for simulating dynamic occupant behaviour [2].

In the literature, three kinds of approaches can be found: deterministic approaches based on predefined scenarios and behavioural rules; statistical approaches that rely on factual observations such as surveys; and social modelling approaches that model cognitive and deliberative behaviours. In a deterministic approach, behavioural rules such as "if the temperature exceeds $28^{\circ}C$ then open the window" may be designed. However some researchers believe that human behaviour is better represented by stochastic models [3]. [4] defend the idea that occupant behaviour corresponds to stochastic processes and not to deterministic ones: "there is no precise temperature at which everyone will open a window, but the higher the temperature, the higher the probability of opening the window". [5] studies the probability of opening and closing windows as a function of the indoor and the outdoor temperatures. The authors established a probability distribution of actions as a function of the indoor temperature. In 2009, inspired by previous works, [3] proposed a hybrid stochastic model for window opening based on three modelling approaches: logistic probability distributions, Markov chains and continuous-time random processes.

More recently, a new approach to social modelling has been proposed that is based on agents. Here computational agents, each having their own characteristics and behaviours, are used to model the occupants. [6] uses this approach to describe occupants' behaviour for energy management. The BRAHMS (Business Redesign Agent-Based Holistic Modelling System) platform was used to model each agent's cognitive behaviour. BRAHMS is based on activity theory and is able to model an occupant's (agent's) beliefs, desires and intentions (BDI). The BDI architecture allows occupant's cognitive, reactive and deliberative behaviours to be represented. [8] uses neural networks for the agents to learn their behaviours from recorded data to ensure their comfort. After a learning phase, agents know the actions that increase their comfort in different environmental conditions. In a recent study, [8] models various occupancy profiles by calibration to predict the use of fans, heating and windows.

The social modelling approach is able to capture the same level of complexity as Markov chain processes. Combined with field studies, the agent-based approach proposes cognitive and deliberative schemas that go beyond statistical approaches. However, the complexity of social modelling makes it difficult to be used by designers [9]: a more focused modelling approach, described in the following section, would be more helpful.

3. Using Bayesian Networks as a general tool for human behaviour modelling

A Bayesian Network (BN) is a probabilistic causal model represented by a directed acyclic graph. Intuitively, it is both a knowledge model and an inference engine using conditional probabilities and evidence to deduce resulting probabilities. Causal relationships between variables are assigned probabilities and are represented in a graph. The observation of a variable does not automatically invoke the related effects but changes the probability of observing

them. Because of the causal representation, a BN is a human friendly way to represent complex behaviours that can be summarized by conditional probabilities. A Static BN (SBN) only concerns a single slice of time and is not appropriate for analyzing a system that changes over the time. A Dynamic BN (DBN) overcomes this problem by describing how variables influence each other over time based on a model derived from past data. A DBN represents the relations between variables at different time steps, some of these variables may not be directly observed.

Compared to a BN, Hidden Markov Models (HMM) rely on nodes that correspond to exclusive states. Nevertheless, the possible number of states for human behaviour is numerous. A BN is more general than HMM because each node stands for a variable (that could possibly be a state) corresponding to any fact, feeling, belief, desire orientation i.e. the basic concepts in social modelling. From a more technical point of view, [10] states that the accuracy of inferences done by DBNs is less sensitive than HMM using the same amount of observations. Unlike HMM, BNs offer an easy way to combine prior expert knowledge with conditional probabilities learnt from observations. This point significantly enhances the precision of user behaviour modelling because merely learning a statistic model from data is generally not rich enough for user activities recognition.

To build a BN, a causal graph and conditional probability tables have to be defined for each node and refined using expert knowledge or from observations. There are two approaches to design the structure of the causal graph. The first approach consists in learning the causality directly from data, if they exist; however due to poor data, the resulting causalities are often inconsistent with reality. The second approach, and the one used in this work, is based on designing a causal graph using expert knowledge about occupant cognition in different contexts and activities.

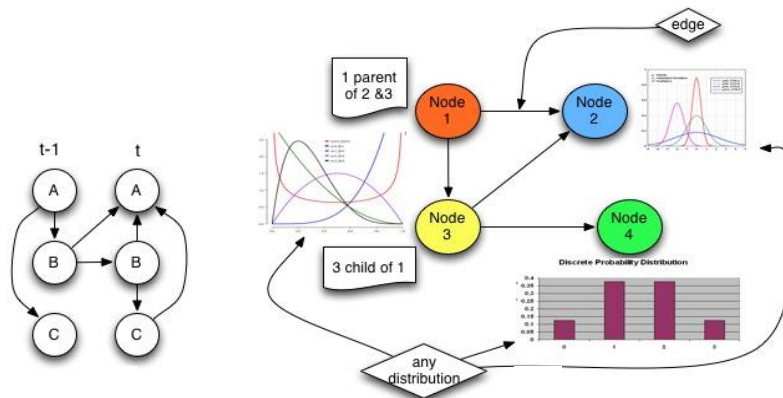


Fig.1 Elements of a Bayesian Network: (a) Dynamic BN (b) Different probability distributions

In BN modelling, any type of probability distribution function (PDF), e.g. uniform, normal, Poisson PDF (fig.1(b)), can be used with a directed edge between 2 nodes when discretized domain values exist for the input variable. However, nonlinear functions of variables cannot be represented. This work proposes the combination of a DBN with nonlinear functions, for instance, Fanger's SPMV model, to process output inferences.

4. Co-simulation mechanism

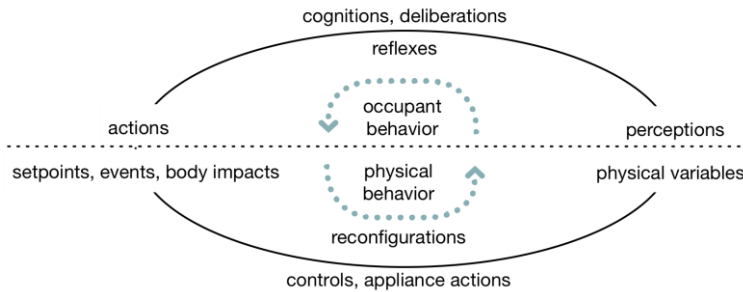


Fig.2 Elements of the model

According to [7], occupants control comfort via a loop summarized in fig.2. Therefore, the simulation is designed as a loop where the physical part (below the dotted line) plays the role of an orchestrator, even if the occupant part (above the dotted line) or an external component could also play this role. The occupant part contains step methods, which is a method that manages the question/response between the physical part and occupant one. Because of the time step, actions and perceptions are averaged. For instance, instead of considering the 2 natural states of 'opened' or 'closed' for a door, different states such as 'always closed', 'mostly closed', 'mostly opened' and 'always opened' are used. For example, if the time step is one hour, some times the door is not closed for the whole hour, it may be closed just 30% of the time step, for this case, it should be provided another door state like 'mostly opened'.

BNs are general tools for modelling human behaviour where the graph nodes could represent any element of a cognitive and deliberative model such as those proposed in [6]. These include perceptions, feelings, beliefs, desires depending on cognition and deliberations, intentions and actions. The occupant behaviour simulator is composed of a DBN editor, that uses the 'libpgm' library adapted to Python 3, and a library of existing DBNs representing elements of occupant behavioural models. It is thus possible to build the behaviour of occupants just as a home setting is built, taking into account the available knowledge about occupants and some assumptions, or reusing existing models. A composition tool is used to combine model elements. A scenario editor can generate inference for different times and dates. Databases of scenarios and results, as well as a result viewer, are available.

The proposed approach couples occupant behaviour with air quality energy performance calculation tools, which rely on dynamic energy calculation rather than on pure thermal calculation. Indeed, without energy calculations that take into account HVAC systems, the coupling with the occupant is less informative. The work is based on an existing tool from CSTB (Scientific and Technical Centre for Building, a French public organisation) named COMETH (CORE for Modelling Energy consumption and THERmal Comfort) that already includes models for a wide range of HVAC systems (mostly those modeled in the EPBD CEN set of standards). Coupling occupant behaviour with physical aspects is implemented by overriding the control modules with a consistent occupant module.

Specific critical aspects related to occupants' actions and air quality must be defined. Because the occupant models are coupled with physical models, the occupants' actions that must be modelled are constrained by the physical computations. These values are: a Boolean indicating whether the space is occupied or not; metabolic gains per thermal zone; activated appliances with corresponding gains per thermal zone; metabolic humidity gains per thermal zone; set point temperature; heating and cooling period if managed by the occupant; ratio of window opening; ratio of door opening. An occupant model must provide all of these values. Because actions and perceptions are averaged, transient states must be carefully designed. In addition, the physical simulation must provide the values that allow the occupant to make decisions and take actions. A minimal set of data, that can enrich the simulation, is the operative mean temperature, mean humidity and CO_2 concentration.

5. Application to door management and air quality in an office

The chosen office is non-mechanically ventilated and has sensors to capture data on: temperature, presence, CO_2 levels, door and window contacts, and humidity. Video recording equipment is also used to track occupants

movements and actions. The office can accommodate up to 4 persons, but in order to show the approach only one occupant and a visitor are modelled. The following actions of an office occupant have been derived from analysing video data. The occupant, a Professor, is not always in the office, but when he is, he works on his computer and usually remains seated. He often closes the door for privacy and welcomes visitors in his office. The DBN structure is shown in fig.3. The target node “Door Movement” is influenced by six variables, identified through video data, and represented by nodes. Each node has its own conditional probabilities. The domain values of the variables are represented by blue rectangles. The structure is dynamic because it uses the “past door movement” variable.

The aim of this model is to predict the rate of CO_2 concentrations in the office depending on the door opening. To design the model, sensor data were collected, and physical models of CO_2 generation [11] and flow calculations [12] were used. The equation (1) is based on mass balance considerations in a zone with a flow of air renewal.

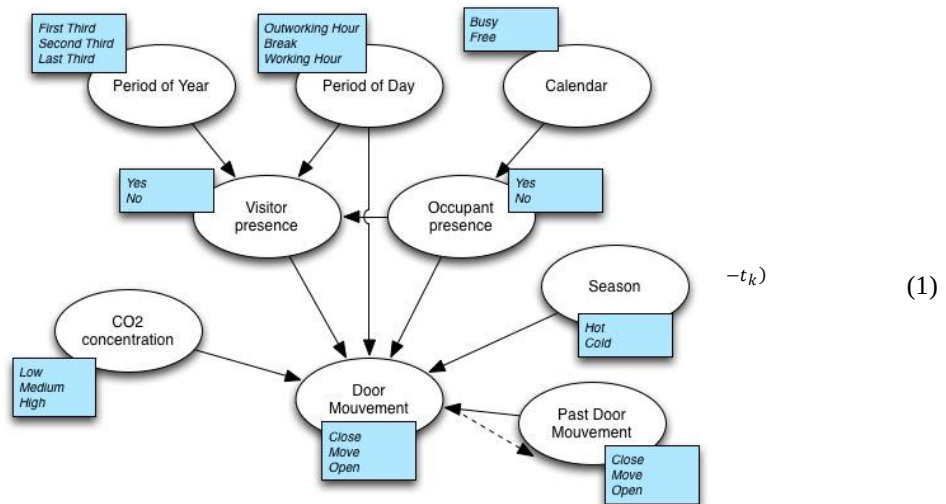


Fig.3 Element of the DBN structure

where $C(t)$ is the CO_2 concentration inside the building at time t , C_i is the initial concentration of CO_2 , V is the office volume, S is the generation rate of CO_2 from occupants exhaled air, which is a function of the volumetric rate of CO_2 [13]. Q_i and Q_o are the incoming or outgoing volumetric flow rate of renewed air. They are defined by equation (2) which calculates the airflow passing through a large opening between the corridor and the office.

$$Q_{i,o}(z_1, z_2) = \frac{2}{3\rho} \epsilon CL \sqrt{2\rho|\Delta\rho|g} (|HN - z_1|^{3/2} - |HN - z_2|^{3/2}) \quad (2)$$

where $Q_{i,o}$ is the incoming or outgoing air flow, $\epsilon = \Delta T / |\Delta T|$, ρ is the air density (dependent on the corridor and office air densities), g is gravity, HN neutral plan (when the pressure difference between two areas is 0), $z_{1,2}$ are the heights of the opening that can be HN , low or high height depending on the temperatures.

To illustrate the approach, two working calendar days, in the first third of the year (months 1-4), of the occupant's activity are considered (fig.4).

Hour	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
Working day calendar 1	Out of working time							free	free	busy	busy	free	Lunch	busy	busy	busy	free	free	free	free	Out of working time			
Working day calendar 2	Out of working time							busy	busy	busy	busy	busy	Lunch	busy	busy	busy	free	free	busy	busy	Out of working time			

Fig.4 Activities for two calendar working days

Each working day calendar has been generated by co-simulation 100 times yielding the results in fig.5. These

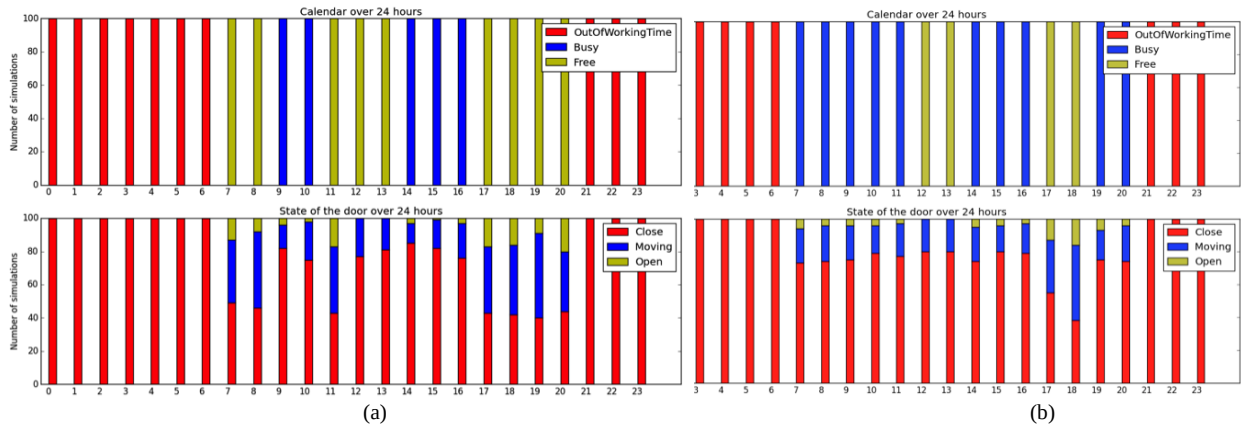


Fig.5 Simulations with the (a) first (b) second working day calendar

results show that the door is less used when the occupant is busy and even less during lunch, meaning that the occupant has lunch outside. This can be seen by comparing the two free times shown in green in fig.5(b) where at 5pm the door is used more often than during the lunch break. Fig.5 clearly shows that the proposed DBN can handle the differences between two same inputs (here free) but with different activities (lunch break and free for some reason). The results are different and illustrate the real aim of the activity.

6. Conclusion

A new approach based on a hybrid DBN has been proposed to model human behaviour. Causal representation eases the modelling process, as it is a natural way of thinking about human behaviour. Furthermore, a probabilistic modelling approach provides a relevant level of representing human behaviour, which becomes very complex at a finer level. Human behaviour can then be designed step-by-step, just like the physical part of a building system, taking into account the knowledge about future occupants and possible assumptions about their behaviours. This approach has the advantage of being intuitive, like cause-effect human reasoning. It also takes into account both the knowledge model and the probability distribution functions, which is missing in other approaches.

This approach has been illustrated in the co-simulation of CO₂ concentration with human behaviour in an office. It will be extended by adding more occupants and performing co-simulations with dynamic energy simulation software.

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