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POISSON SUSPENSIONS AND SUSHIS

ÉLISE JANVRESSE, EMMANUEL ROY AND THIERRY DE LA RUE

ABSTRACT. In this paper, we prove that ergodic point processes with moments of all orders, driven by particular infinite measure preserving transformations, have to be a superposition of shifted Poisson processes. This rigidity result has a lot of implications in terms of joining and disjointness for the corresponding Poisson suspension. In particular, we prove that its ergodic self-joinings are Poisson joinings, which provides an analog, in the Poissonian context, of the GAG property for Gaussian dynamical systems.

Suspensions de Poisson et SuShis

RÉSUMÉ. Dans cet article, nous démontrons qu'un processus ponctuel ergodique avec des moments de tous ordres, dirigé par une transformation préservant une mesure infinie qui vérifie certaines propriétés, est nécessairement une superposition de processus de Poisson décalés. Ce résultat de rigidité a de nombreuses implications en termes de couplages et de disjonction pour la suspension de Poisson associée. En particulier, nous démontrons que ses autocouplages ergodiques sont des couplages poissonniens, obtenant ainsi un analogue, dans le contexte poissonien, de la propriété GAG des systèmes dynamiques gaussiens.

1. INTRODUCTION

Central to probability theory are Gaussian and Poisson distributions. In ergodic theory, they both play a singular role through canonical constructions we briefly recall:

- Starting from a symmetric Borel measure σ on \mathbb{T} , there exists a unique centered stationary real-valued Gaussian process $\{X_n\}_{n \in \mathbb{Z}}$ whose coordinates admit σ as spectral measure, that is

$$\mathbb{E}[X_0 X_n] = \hat{\sigma}(n).$$

- Starting from a σ -finite dynamical system (X, \mathcal{A}, μ, T) , we can build the Poisson suspension $(X^*, \mathcal{A}^*, \mu^*, T_*)$, which is the canonical space $(X^*, \mathcal{A}^*, \mu^*)$ of the Poisson point process of intensity μ , enriched by the transformation

$$T_*(\xi) := \xi \circ T^{-1}$$

(see below for a precise definition).

A striking theorem due to Foias and Strătilă (see [9]) states that some measures σ on \mathbb{T} , if appearing as spectral measure of some ergodic stationary process, force

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the process to be Gaussian. This was considerably developed later (see [16] in particular) and lead to some remarkable results.

In this paper, we obtain a Poisson counterpart of Foiaş-Strătilă theorem. We prove that some ergodic infinite measure preserving transformation, taken as base system of an ergodic invariant point process with moments of all orders, force the latter to be a superposition of shifted Poisson point processes. In case of non-Abelian actions, we can even get rid of the superposition and obtain the Poisson process as only invariant point process.

Notations. For any set J , we denote by $\#J$ the cardinality of J . If φ is any measurable map from (X, \mathcal{A}) to (Y, \mathcal{B}) , and if m is a measure on (X, \mathcal{A}) , we denote by $\varphi_*(m)$ the pushforward measure of m by φ .

1.1. Random measures and point processes. Let X be a complete separable metric space and \mathcal{A} be its Borel σ -algebra. Define \tilde{X} to be the space of boundedly finite measures on (X, \mathcal{A}) . We refer to [5] for the topological properties of \tilde{X} . In particular, \tilde{X} can be turned into a complete separable metric space, and its Borel σ -algebra $\tilde{\mathcal{A}}$ is generated by the maps $\xi \in \tilde{X} \mapsto \xi(A) \in \mathbb{R}_+ \cup \{+\infty\}$ for bounded $A \in \mathcal{A}$.

Let $X^* \subset \tilde{X}$ be the subspace of simple counting measures, *i.e.* whose elements are of the form

$$\xi = \sum_{i \in I} \delta_{x_i},$$

where I is at most countable, and $x_i \neq x_j$ whenever $i \neq j$. Because we restrict ourselves to boundedly finite measures, any bounded subset $A \subset X$ contains finitely many points of the family $(x_i)_i$. Conversely, any countable family of points satisfying this property defines a measure $\xi \in X^*$ by the above formula. We define \mathcal{A}^* as the restriction to X^* of $\tilde{\mathcal{A}}$.

In the paper, we consider a boundedly finite measure μ on X and an invertible transformation T on X preserving μ . We assume that $\mu(X) = \infty$ and that (X, \mathcal{A}, μ, T) is conservative and ergodic. This implies in particular that μ is continuous.

Given the map T , for any σ -finite measure ξ , we define $T_*(\xi)$ as the pushforward measure of ξ by T . In particular, if $\xi = \sum_{i \in I} \delta_{x_i}$,

$$T_*(\xi) = \sum_{i \in I} \delta_{T(x_i)}.$$

Observe that, even if $\xi \in X^*$, $T_*(\xi)$ is not necessarily in X^* (the property of bounded finiteness may be lost by the action of T). Nevertheless, one can consider probability measures on X^* which are invariant by T_* . If m is such a probability measure, then it is in fact concentrated on the smaller space $\bigcap_{n \in \mathbb{Z}} T_*^{-n} X^*$, on which T_* is a bijective transformation. In particular, $T_*(\xi) \in X^*$ for m -almost all $\xi \in X^*$, and $(X^*, \mathcal{A}^*, m, T_*)$ is an invertible, probability preserving dynamical system. (The same remark holds if we replace X^* by \tilde{X} .)

For convenience, we set $\mathcal{A}_f := \{A \in \mathcal{A}, 0 < \mu(A) < +\infty\}$.

We call *point process on X* any random variable N defined on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$ taking values in (X^*, \mathcal{A}^*) . In this case, N can be viewed as a random set of points in X , and we will note $x \in N$ for the event $N(\{x\}) = 1$.

Definition 1.1. A T -point process N is a point process on X , defined on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$, such that

- for any set $A \in \mathcal{A}$, $N(A) = 0$ \mathbb{P} -a.s. whenever $\mu(A) = 0$;
- there exists a measure preserving invertible transformation S on $(\Omega, \mathcal{F}, \mathbb{P})$, such that for any set $A \in \mathcal{A}$, $N(A) \circ S = N(T^{-1}A)$.

In other words, N implements a factor relationship between the dynamical systems $(\Omega, \mathcal{F}, \mathbb{P}, S)$ and $(X^*, \mathcal{A}^*, m, T_*)$ where m is the pushforward measure of \mathbb{P} by N , and $N(A) = 0$ \mathbb{P} -a.s. whenever $\mu(A) = 0$.

Observe that the formula $A \in \mathcal{A} \mapsto \mathbb{E}[N(A)]$ defines a T -invariant measure which is absolutely continuous with respect to μ . It is called the *intensity* of N and as soon as it is σ -finite, by ergodicity of (X, \mathcal{A}, μ, T) , it is a multiple of μ :

$$\mathbb{E}[N(\cdot)] = \alpha \mu(\cdot)$$

for some $\alpha > 0$. In this case, we will say that N is *integrable*. More generally, we have:

Definition 1.2. A T -point process N on $(\Omega, \mathcal{F}, \mathbb{P}, S)$ is said to have moments of order $n \geq 1$ if, for all $A \in \mathcal{A}_f$, $\mathbb{E}[(N(A))^n] < +\infty$. In this case, for $k \leq n$, the formula

$$M_k^N(A_1 \times \cdots \times A_k) := \mathbb{E}[N(A_1) \times \cdots \times N(A_k)]$$

defines a boundedly finite $T \times \cdots \times T$ -invariant measure M_k^N on $(X^k, \mathcal{A}^{\otimes k})$ called the k -order moment measure.

A T -point process with moments of order 2 is said to be square integrable.

1.2. Poisson point process and SuShis. The most important T -point processes are Poisson point processes, let us recall their definition.

Definition 1.3. A random variable N with values in (X^*, \mathcal{A}^*) is a Poisson point process of intensity μ if for any $k \geq 1$, for any mutually disjoint sets $A_1, \dots, A_k \in \mathcal{A}_f$, the random variables $N(A_1), \dots, N(A_k)$ are independent and Poisson distributed with respective parameters $\mu(A_1), \dots, \mu(A_k)$.

Such a process always exists. Its distribution μ^* is uniquely determined and is called the *Poisson measure* of intensity μ . Since T preserves μ , one easily checks that T_* preserves μ^* .

Definition 1.4. The probability-preserving dynamical system $(X^*, \mathcal{A}^*, \mu^*, T_*)$ is called the Poisson suspension over the base (X, \mathcal{A}, μ, T) .

The basic result (see [22]) about Poisson suspensions states that $(X^*, \mathcal{A}^*, \mu^*, T_*)$ is ergodic (and then weakly mixing) if and only if there is no T -invariant set in \mathcal{A}_f . In particular this is the case if (X, \mathcal{A}, μ, T) is ergodic and μ infinite.

Defining N on the probability space $(X^*, \mathcal{A}^*, \mu^*)$ as the identity map provides an example of a T -point process, the underlying measure-preserving transformation being $S = T_*$ in this case.

More generally, we can define a class of T -point processes which are constructed from independent Poisson point processes.

Definition 1.5. Let $(N_i)_{i \in I}$ be a countable family of independent Poisson T -point processes of respective intensities $\alpha_i \mu$, defined on the same probability space

$(\Omega, \mathcal{F}, \mathbb{P})$. For each $i \in I$, consider a finite subset $J_i \subset \mathbb{Z}$, with

$$\sum_{i \in I} \alpha_i \#J_i < \infty.$$

Then, the process N defined by

$$N := \sum_{i \in I} \sum_{j \in J_i} T_*^j(N_i)$$

is a particular integrable T -point process called Superposition of Shifted Poisson Processes, which we abbreviate in SuShi.

Note that the aperiodicity of T ensures that the SuShi N is indeed a simple point process.

It is easy to see that a SuShi always admits a canonical decomposition, in which the subsets J_i are distinct, contained in \mathbb{Z}_+ , and $0 \in J_i$ for all i .

In general, a SuShi does not have moments of all orders (one can prove that, if $\sum_{i \in I} \alpha_i (\#J_i)^2 = \infty$, then there exists $A \in \mathcal{A}_f$ with $\mathbb{E}[N(A)^2] = \infty$.) However, if the numbers $\#J_i$, $i \in I$ are uniformly bounded, then moments of all orders exist for the SuShi.

1.3. Roadmap of the paper. The paper is organized as follows. Section 2 is devoted to general results about T -point processes, and their behaviour regarding T -orbits. In Section 2.1, we consider the following question: can a T -point process assign infinite mass to T -orbits? We show in Proposition 2.1 that, if a T -point process is square-integrable, then it almost surely gives finite mass to any T -orbit. We also explain how to construct a (non-square-integrable) T -point process which almost surely assigns mass 0 or ∞ to any T -orbit (Proposition 2.2). In Section 2.2, we describe a canonical decomposition of a T -point process assigning finite mass to T -orbits (Proposition 2.5), which is naturally related to the form taken by SuShis. In Section 2.3, we first provide a useful criterion to detect whether several T -point processes, defined on the same probability space, charge points in the same T -orbits (Lemma 2.6). Then we prove in Proposition 2.7 that any T -point process whose 2-order moment measure coincides with the one of a Poisson process is T -free, that is to say it almost surely charges at most one point in any T -orbit.

Section 3 presents the key rigidity results of the paper. At the beginning of this section, we introduce two additional properties of the infinite measure preserving dynamical system (X, \mathcal{A}, μ, T) , denoted by (P1) and (P2). The former simply says that any direct product of a finite number of copies of this system remains ergodic, and the latter is a strong restriction on the set of $T^{\times n}$ -invariant measures on X^n . As proved in [2, 12], there exists an infinite measure preserving version of the Chacon transformation satisfying these properties. Then we show that, under assumptions (P1) and (P2), T -point processes with moments of all orders are SuShis (Theorem 3.3). An important step for the proof of this result is the particular case where the T -point process is T -free: in this situation we prove that it has to be a Poisson process (Theorem 3.1). We also need a result ensuring the independence of Poisson T -point processes which do not charge the same T -orbits, provided by Proposition 3.2.

Section 4 deals with the consequences of the preceding results regarding self-joinings and factors of the Poisson suspension. We begin by recalling classical results on the L^2 structure of a Poisson suspension (Section 4.1), and presenting

the central notions of Poisson factors and Poisson joinings (Section 4.2). Then we prove that, if T satisfies (P1) and (P2), any ergodic infinite self-joining of the associated Poisson suspension is realized as a factor of a universal Poisson suspension (Theorem 4.7). In fact, the result even holds for an ergodic joining of a countable family of Poisson suspensions which are all of the form $T_*^{(\alpha)}$, where for each $\alpha > 0$, $T_*^{(\alpha)}$ denotes the Poisson suspension $(X_*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$. As a corollary, we get in Theorem 4.18 that such a Poisson suspension satisfies the \mathcal{PaP} property, which means that any ergodic self-joining of this system is Poisson. This \mathcal{PaP} property turns out to be, in the Poissonian context, the analog of the so-called GAG property for Gaussian stationary processes (see [16]). We also present in Section 4.4 some general properties of \mathcal{PaP} Poisson suspensions. In Section 4.5, we see how the suspensions $T_*^{(\alpha)}$ can be used to obtain a new kind of counterexample to the famous question of Furstenberg: if two ergodic dynamical systems are not disjoint, do they share a common factor? All counterexamples known so far have the property that one of the two non-disjoint systems shares a common factor with a distal extension of the other one. In Proposition 4.24, we show that, if $\alpha \neq \beta$, $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are two non-disjoint systems which are prime, but neither of them is a factor of a distal extension of the other one, answering negatively a question asked by Lemańczyk.

In Section 5, we present disjointness results for the Poisson suspension, still assuming (P1) and (P2), and a further technical assumption on T which is the existence of a measurable law of large number. (It is not clear whether, in general, (P1) and (P2) imply this existence, however these three properties are satisfied for the infinite Chacon transformation.) Under these assumptions, we prove in particular the following key result: if a dynamical system S is not disjoint from the Poisson suspension $(X_*, \mathcal{A}^*, \mu^*, T_*)$, then there exists $\alpha > 0$ such that $T_*^{(\alpha)}$ appears as a factor of S (Proposition 5.5). Applications of this result are developed in Section 5.2, where we prove that, under the same assumptions, the Poisson suspension is disjoint from any locally rank one dynamical system (Theorem 5.8), and from any standard Gaussian dynamical system (Theorem 5.12).

At last, Section 6 is a modest foray into the realm of non-abelian actions where our results take an even more radical form since the Poisson suspension is the one and only SuShi here.

2. GENERAL RESULTS ABOUT T -POINT PROCESSES AND T -ORBITS

2.1. Number of points in orbits. The purpose of this section is to prove that, provided that the T -point process N has moment of order 2, N almost surely gives finite measure to any T -orbit.

Proposition 2.1. *Let N be an integrable T -point process on $(\Omega, \mathcal{F}, \mathbb{P}, S)$, with intensity μ , and assume that, with positive probability, there exists some $x \in N(\omega)$ with*

$$N(\{T^k x : k \in \mathbb{Z}\}) = \infty.$$

Then, we can find $A \in \mathcal{A}_f$ such that

$$\mathbb{E}[N^2(A)] = \infty.$$

Proof. The first step is to prove that

$$(1) \quad \forall m, M > 0, \text{ there exists } A \subset X \text{ with } \mu(A) = m \text{ and } \mathbb{E}[N^2(A)] \geq M\mu(A).$$

The main tool for this proof will be the family of Palm probability measures $(\mathbb{P}_x)_{x \in X}$ associated with the point process N . For a detailed presentation of Palm measures, we refer the reader to [6], Chapter 13. Recall that for μ -almost each $x \in X$, \mathbb{P}_x is a probability measure on X^* which can be interpreted as the distribution of N conditioned on $x \in N$. For each measurable $U \subset X^*$, $x \mapsto \mathbb{P}_x(U)$ is measurable, and we have for each measurable $A \subset X$

$$\mathbb{E}[1_U(N)N(A)] = \int_A \mathbb{P}_x(U) d\mu(x).$$

More generally, if g is a positive measurable function on $X \times X^*$, and if we denote by $\mathbb{E}_x[\cdot]$ the expectation with respect to \mathbb{P}_x , we have

$$(2) \quad \mathbb{E} \left[\int_X g(x, N) dN(x) \right] = \int_X \mathbb{E}_x[g(x, \xi)] d\mu(x).$$

We claim that, for μ -almost all x ,

$$(3) \quad \mathbb{P}_{Tx} = (T_*)_* \mathbb{P}_x.$$

Indeed, as \mathbb{P} is S -invariant, for each measurable $U \subset X^*$ and each measurable $A \subset X$, we can write

$$\begin{aligned} \int_A \mathbb{P}_x(U) d\mu(x) &= \mathbb{E}[1_U(N)N(A)] \\ &= \mathbb{E}[(1_U(N)N(A)) \circ S] \\ &= \mathbb{E}[1_{T_*^{-1}U}(N)N(T^{-1}A)] \\ &= \int_{T^{-1}A} \mathbb{P}_x(T_*^{-1}U) d\mu(x). \end{aligned}$$

But on the other hand, using T -invariance of μ , we also have

$$\int_A \mathbb{P}_x(U) d\mu(x) = \int_{T^{-1}A} \mathbb{P}_{Tx}(U) d\mu(x).$$

This yields, for each measurable $U \subset X^*$, $\mathbb{P}_{Tx}(U) = \mathbb{P}_x(T_*^{-1}U)$, as claimed.

Now, for each $x \in X$, let us introduce the map $\varphi_x : X^* \rightarrow \{0, 1\}^{\mathbb{Z}}$ defined by

$$\varphi_x(\xi) := (1_\xi(T^k x))_{k \in \mathbb{Z}}.$$

Observe that

$$(4) \quad \varphi_{Tx} \circ T_* = \varphi_x.$$

Define also the probability measure ν_x on $\{0, 1\}^{\mathbb{Z}}$ as the pushforward measure of \mathbb{P}_x by φ_x . Using (3) and (4), we get, for μ -almost all $x \in X$

$$\nu_{Tx} = (\varphi_{Tx})_*(\mathbb{P}_{Tx}) = (\varphi_{Tx} \circ T_*)_*(\mathbb{P}_x) = (\varphi_x)_*(\mathbb{P}_x) = \nu_x.$$

By ergodicity of T , it follows that there exists a probability measure ν on $\{0, 1\}^{\mathbb{Z}}$ such that $\nu_x = \nu$ for μ -almost all $x \in X$.

Let us consider the following measurable function g defined on $X \times X^*$:

$$g(x, \xi) := \begin{cases} 1 & \text{if } \sum_{k \in \mathbb{Z}} \xi(T^k x) = \infty \\ 0 & \text{otherwise.} \end{cases}$$

The hypothesis made on the point process N yields

$$\mathbb{E} \left[\int_X g(x, N) dN(x) \right] > 0.$$

By (2), we get that for x in a subset of positive measure in X ,

$$\begin{aligned} 0 &< \mathbb{E}_x[g(x, \xi)] \\ &= \mathbb{P}_x \left(\sum_k \xi(T^k x) = \infty \right) \\ &= \mathbb{P}_x \left(\sum_k (\varphi_x(\xi))_k = \infty \right) \\ &= \nu \left(\left\{ \zeta \in \{0, 1\}^{\mathbb{Z}} : \sum_{k \in \mathbb{Z}} \zeta_k = \infty \right\} \right). \end{aligned}$$

It follows that

$$\int_{\{0,1\}^{\mathbb{Z}}} \sum_{k \in \mathbb{Z}} \zeta_k d\nu(\zeta) = \infty,$$

and we have

$$\int_{\{0,1\}^{\mathbb{Z}}} \sum_{k \in \mathbb{Z}_+} \zeta_k d\nu(\zeta) = \infty, \text{ or } \int_{\{0,1\}^{\mathbb{Z}}} \sum_{k \in \mathbb{Z}_-} \zeta_k d\nu(\zeta) = \infty.$$

Assume without loss of generality that the former case occurs. Then, for a given $M > 0$, there exists a large integer k_M such that

$$\int_{\{0,1\}^{\mathbb{Z}}} \sum_{0 \leq k \leq k_M} \zeta_k d\nu(\zeta) \geq 2M.$$

By Rokhlin's tower theorem ([1], Theorem 1.5.9), for any $m > 0$, there exist $B \subset X$, $\mu(B) = \frac{m}{2k_M+1}$, such that the sets $T^k B$, $-k_M \leq k \leq k_M$ are pairwise disjoint. Now set $A := \sqcup_{-k_M \leq k \leq k_M} T^k B$, so that $\mu(A) = m$, and $A_- := \sqcup_{-k_M \leq k \leq 0} T^k B$. Applying (2) with $g(x, \xi) = 1_A(x)\xi(A)$, we get

$$\mathbb{E}[N^2(A)] = \int_A \mathbb{E}_x[\xi(A)] d\mu(x) \geq \int_{A_-} \mathbb{E}_x[\xi(A)] d\mu(x).$$

But, for $x \in A_-$, $T^k(x) \in A$ for each $0 \leq k \leq k_M$, therefore

$$\mathbb{E}_x[\xi(A)] \geq \mathbb{E}_x \left[\sum_{0 \leq k \leq k_M} \xi(T^k x) \right] = \int_{\{0,1\}^{\mathbb{Z}}} \sum_{0 \leq k \leq k_M} \zeta_k d\nu(\zeta) \geq 2M.$$

Since $\mu(A_-) \geq \mu(A)/2$, we get (1).

To conclude the proof of the proposition, for each $\ell \geq 1$, applying (1), we find $A_\ell \subset X$ satisfying $\mu(A_\ell) = 1/\ell^2$ and $\mathbb{E}[N^2(A_\ell)] \geq \ell^3 \mu(A_\ell)$. Set $A := \bigcup_{\ell \geq 1} A_\ell$. Then $A \in \mathcal{A}_f$, but for each ℓ , $\mathbb{E}[N^2(A)] \geq \mathbb{E}[N^2(A_\ell)] \geq \ell$. \square

Without the finiteness of the second moment, we cannot conclude that the T -point process assigns finite mass to any T -orbit. Indeed, we have the following proposition.

Proposition 2.2. *For any ergodic conservative dynamical system (X, \mathcal{A}, μ, T) with $\mu(X) = \infty$, there exists a T -point process N with intensity μ such that, with probability 1, for any $x \in N(\omega)$,*

$$N(\{T^k x : k \in \mathbb{Z}\}) = \infty.$$

Proof. According to Corollary 5.3.4 in [1], there exists a conservative ergodic dynamical system (Y, \mathcal{B}, ν, R) such that the direct product $(X \times Y, \mathcal{A} \otimes \mathcal{B}, \mu \otimes \nu, T \times R)$ is totally dissipative. Therefore, there exists a wandering set $M \subset X \times Y$ such that the sets $(T \times R)^i M$, $i \in \mathbb{Z}$, are pairwise disjoint, and such that $X \times Y = \bigsqcup_{i \in \mathbb{Z}} (T \times R)^i M$.

Let η_0 be a Poisson process on M with intensity $\mu \otimes \nu|_M$, and consider, for any $i \in \mathbb{Z}$, $\eta_i := (T \times R)_*^i \eta_0$: this is a Poisson process on $(T \times R)^i M$ with intensity $\mu \otimes \nu|_{(T \times R)^i M}$. Then, set $\eta := \sum_{i \in \mathbb{Z}} \eta_i$, which is a point process on $X \times Y$ with intensity $\mu \otimes \nu$. We claim now that

$$(5) \quad \eta \text{ and } (T \times \text{Id})_* \eta \text{ have the same law.}$$

Indeed, set $\tilde{M} := (T \times \text{Id})M$, and partition this set into subsets $\tilde{M}_i := \tilde{M} \cap (T \times R)^i M$. Then, for all $i \in \mathbb{Z}$, consider $M_i := (T \times R)^{-i} \tilde{M}_i = (T \times R)^{-i} \tilde{M} \cap M$. But $T \times \text{Id}$ commutes with $T \times R$, therefore the subsets $(T \times R)^{-i} \tilde{M}$ also form a partition of $X \times Y$. It follows that the subsets M_i form a partition of M . Moreover, by definition of η ,

$$\eta|_{\tilde{M}_i} = (T \times R)_*^i \eta|_{M_i},$$

and since the point processes $\eta|_{M_i}$ are independent Poisson processes, $\tilde{\eta}_0 := \eta|_{\tilde{M}}$ is itself a Poisson process of intensity $\mu \otimes \nu|_{\tilde{M}}$. Starting from this Poisson process defined on \tilde{M} , we can in the same way construct the point process

$$\tilde{\eta} := \sum_{i \in \mathbb{Z}} (T \times R)_*^i \tilde{\eta}_0,$$

which has the same distribution as $(T \times \text{Id})_* \eta$. But on the other hand, we have $\tilde{\eta} = \eta$, because these two point processes coincide on \tilde{M} and both charge full orbits of $T \times R$. This proves (5).

Finally, let us fix a measurable subset $B \subset Y$ with $\nu(B) = 1$. Replacing if necessary B by $B \cap \{y \in Y : R^n y \in B \text{ for infinitely many integers } n\}$, which is still of measure 1, we can assume that any $y \in B$ returns infinitely often in B . Consider the point process on X defined by

$$\xi := (\pi_X)_* (\eta|_{X \times B}),$$

where $\pi_X : X \times Y \rightarrow X$ stands for the projection on the X coordinate. Then, the intensity of ξ is μ , and by (5), ξ and $T_* \xi$ have the same law. Now, for any $x \in \xi$, there exists $y \in B$ such that $(x, y) \in \eta \cap X \times B$. Then there exist infinitely many integers n such that $R^n y \in B$, hence such that $(T^n x, R^n y) \in \eta \cap X \times B$, and then $T^n x \in \xi$. We get the announced T -point process N by considering $N := \text{Id}$ on $\Omega := X^*$, equipped with the probability measure \mathbb{P} defined as the law of ξ , which is invariant by $S := T_*$. \square

2.2. Separating orbits. The next definition deals with the interactions between T -point processes.

Definition 2.3. Two T -point processes N_1 and N_2 defined on $(\Omega, \mathcal{F}, \mathbb{P}, S)$ are said to be (T) -dissociated if, for all $k \in \mathbb{Z}$, N_1 and $N_2 \circ S^k$ have no common points (\mathbb{P} -a.s.).

Of course, a T -point process is never dissociated with itself, however we have the following situation:

Definition 2.4. A T -point process N is called (T) -free if for all $k \in \mathbb{Z}^*$, N and $N \circ S^k$ have no common points (\mathbb{P} -a.s.).

Proposition 2.5. *Let N be a T -point process on $(\Omega, \mathcal{F}, \mathbb{P}, S)$, which almost-surely assigns finite mass to any T -orbit. Then there exist a finite or countable set I , a family $\{F_i\}_{i \in I}$ of finite subsets of \mathbb{Z}_+ , and a family $(N_{F_i})_{i \in I}$ of free T -point processes, measurable with respect to N and mutually dissociated, such that*

$$N = \sum_{i \in I} \left(\sum_{k \in F_i} N_{F_i} \circ S^k \right), \mathbb{P}\text{-a.s.}$$

Proof. For each non-empty subset $F \subset \mathbb{Z}_+$ that contains 0, we can form from N a T -point process N_F by keeping, for all $\omega \in \Omega$, points $x \in N(\omega)$ such that $T^k x \in N(\omega)$ for all $k \in F$ and $T^k x \notin N(\omega)$ for all $k \in \mathbb{Z} \setminus F$. By construction, N_F is a free T -point process, and N_F and $N_{F'}$ are dissociated whenever $F \neq F'$. Moreover, by hypothesis,

$$N = \sum_{F \subset \mathbb{Z}_+, 0 \in F, \#\mathbb{Z}_+ \setminus F < \infty} N_F, \mathbb{P}\text{-a.s.}$$

Removing all sets F such that N_F vanishes \mathbb{P} -a.s., we obtain the announced decomposition. \square

2.3. Detecting interactions within T -point processes. We already have introduced the moment measures of a point process N by considering the quantities

$$\mathbb{E}[N(A_1) \cdots N(A_n)]$$

for sets A_1, \dots, A_n in \mathcal{A} .

We also obtain a $T^{\times n}$ -invariant measure on X^n by considering possibly different T -point processes N_1, \dots, N_n defined on the same probability space, and setting, for A_1, \dots, A_n in \mathcal{A}

$$M^{N_1, \dots, N_n}(A_1 \times \cdots \times A_n) := \mathbb{E}[N_1(A_1) \cdots N_n(A_n)].$$

If the point processes have moments of all orders, this measure is boundedly finite and captures some valuable information about the interactions between those processes. To illustrate this, the next lemma roughly says that if this measure contains a non trivial “diagonal” part, then it reflects the presence of points on some common orbit for some of the point processes involved.

Lemma 2.6. *Let N_1, \dots, N_n be n T -point processes defined on the ergodic system $(\Omega, \mathcal{F}, \mathbb{P}, S)$, having moments of all orders. Assume there exist a real number $c > 0$, integers $2 \leq j \leq n, k_2, \dots, k_j$, and a $T^{\times(n-j)}$ -invariant, σ -finite measure $\nu \neq 0$ such that, for any sets A_1, \dots, A_n in \mathcal{A}_f ,*

$$\mathbb{E}[N_1(A_1) \cdots N_n(A_n)] \geq c \mu(A_1 \cap T^{-k_2} A_2 \cap \cdots \cap T^{-k_j} A_j) \nu(A_{j+1} \times \cdots \times A_n).$$

Then, for any $A \in \mathcal{A}_f$,

$$\mathbb{P}(A \cap N_1 \cap T^{-k_2} N_2 \cap \cdots \cap T^{-k_j} N_j \neq \emptyset) > 0.$$

Proof. We can apply the ergodic theorem:

$$\begin{aligned} \frac{1}{N} \sum_{k=1}^N \mathbb{E}[N_1(A_1) \cdots N_j(A_j) (N_{j+1}(A_{j+1}) \cdots N_n(A_n)) \circ S^k] \\ \xrightarrow{N \rightarrow \infty} \mathbb{E}[N_1(A_1) \cdots N_j(A_j)] \mathbb{E}[N_{j+1}(A_{j+1}) \cdots N_n(A_n)]. \end{aligned}$$

But

$$\begin{aligned} & \mathbb{E} [N_1(A_1) \cdots N_j(A_j) (N_{j+1}(A_{j+1}) \cdots N_n(A_n)) \circ S^k] \\ &= \mathbb{E} [N_1(A_1) \cdots N_j(A_j) N_{j+1}(T^{-k}A_{j+1}) \cdots N_n(T^{-k}A_n)], \end{aligned}$$

therefore, as ν is $T^{\times(n-j)}$ -invariant,

$$\begin{aligned} & \mathbb{E} [N_1(A_1) \cdots N_j(A_j)] \mathbb{E} [N_{j+1}(A_{j+1}) \cdots N_n(A_n)] \\ & \geq c\mu(A_1 \cap T^{-k_2}A_2 \cap \cdots \cap T^{-k_j}A_j) \nu(A_{j+1} \times \cdots \times A_n). \end{aligned}$$

We claim that there exists some set $B \in \mathcal{A}_f$ so that $\mathbb{E} [N_{j+1}(B) \cdots N_n(B)] > 0$ and $\nu(B \times \cdots \times B) > 0$. Indeed, we first observe that, by ergodicity, we have $N_k(X) = \infty$ a.s. for all k . Thus, $N_{j+1}(X) \cdots N_n(X) = \infty$ a.s. Take some increasing sequence $(B_\ell)_{\ell \geq 1}$ in \mathcal{A}_f such that $X = \bigcup_{\ell \geq 1} B_\ell$. Then

$$\mathbb{E} [N_{j+1}(B_\ell) \cdots N_n(B_\ell)] \xrightarrow{\ell \rightarrow \infty} \infty,$$

thus $\mathbb{E} [N_{j+1}(B_\ell) \cdots N_n(B_\ell)] > 0$ for all large enough ℓ . By the same argument, we also have $\nu(B_\ell \times \cdots \times B_\ell) > 0$ for all large enough ℓ , and we can take $B = B_\ell$ for some large ℓ .

We now set

$$\alpha := \frac{\nu(B \times \cdots \times B)}{\mathbb{E} [N_{j+1}(B) \cdots N_n(B)]} > 0.$$

Then, we have for any A_1, \dots, A_j in \mathcal{A}_f ,

$$(6) \quad \mathbb{E} [N_1(A_1) \cdots N_j(A_j)] \geq c\alpha\mu(A_1 \cap T^{-k_2}A_2 \cap \cdots \cap T^{-j}A_j).$$

Let us consider now a generating sequence $\left((A_i^n)_{1 \leq i \leq p_n} \right)_{n \geq 1}$ of partitions of A : this means that this sequence of partitions of A is increasing, and that for any $x \neq y$ in A , there exists $n(x, y)$ such that, for any $n \geq n(x, y)$, x and y do not belong to the same atom of the partition $(A_i^n)_{1 \leq i \leq p_n}$. Observe that

$$\begin{aligned} & \sum_{i=1}^{p_n} N_1(A_i^n) N_2(T^{k_2}A_i^n) \cdots N_j(T^{k_j}A_i^n) \\ & \xrightarrow{n \rightarrow \infty} \# \{x \in N_1 \cap A : T^{k_2}x \in N_2, \dots, T^{k_j}x \in N_j\}. \end{aligned}$$

Moreover,

$$\begin{aligned} & \sum_{i=1}^{p_n} N_1(A_i^n) N_2(T^{k_2}A_i^n) \cdots N_j(T^{k_j}A_i^n) \\ & \leq N_1(A) N_2(T^{k_2}A) \cdots N_{j-1}(T^{k_{j-1}}A) \sum_{i=1}^{p_n} N_j(T^{k_j}A_i^n) \\ & = N_1(A) N_2(T^{k_2}A) \cdots N_{j-1}(T^{k_{j-1}}A) N_j(T^{k_j}A), \end{aligned}$$

which is integrable. So we can apply the dominated convergence theorem to get

$$\begin{aligned} & \mathbb{E} \left[\sum_{i=1}^{p_n} N_1(A_i^n) N_2(T^{k_2}A_i^n) \cdots N_j(T^{k_j}A_i^n) \right] \\ & \xrightarrow{n \rightarrow \infty} \mathbb{E} [\# \{x \in N_1 \cap A, T^{k_2}x \in N_2, \dots, T^{k_j}x \in N_j\}]. \end{aligned}$$

On the other hand, we have

$$\begin{aligned}
 & \mathbb{E} \left[\sum_{i=1}^{p_n} N_1(A_i^n) N_2(T^{k_2} A_i^n) \cdots N_j(T^{k_j} A_i^n) \right] \\
 &= \sum_{i=1}^{p_n} \mathbb{E} [N_1(A_i^n) N_2(T^{k_2} A_i^n) \cdots N_j(T^{k_j} A_i^n)] \\
 &\geq \sum_{i=1}^{p_n} c\alpha \mu(A_i^n \cap A_i^n \cap \cdots \cap A_i^n) \quad \text{by (6)} \\
 &= c\alpha \sum_{i=1}^{p_n} \mu(A_i^n) \\
 &= c\alpha \mu(A)
 \end{aligned}$$

Letting n go to ∞ , we get

$$\mathbb{E} [\# \{x \in N_1 \cap A, T^{k_2} x \in N_2, \dots, T^{k_j} x \in N_j\}] \geq c\alpha \mu(A),$$

which concludes the proof. \square

In the case where $N_1 = N_2 = N$, the following proposition shows that some particular form for M_2^N forces the T -point process to be free.

Proposition 2.7. *Let N be a square integrable T -point process, whose second order moment measure satisfies*

$$M_2^N(A_1 \times A_2) = \mu(A_1 \cap A_2) + \mu(A_1) \mu(A_2).$$

Then N is a free T -point process. In particular the Poisson process associated to the Poisson suspension $(X^, \mathcal{A}^*, \mu^*, T_*)$ is a free T -point process.*

Proof. Fix $k \neq 0$. Take a set $A \in \mathcal{A}_f$ such that $A \cap T^k A = \emptyset$ (such a set always exists) and $\left((A_i^n)_{1 \leq i \leq p_n} \right)_{n \geq 1}$ a generating sequence of partitions of A , satisfying $\mu(A_i^n) = \frac{\mu(A)}{p_n}$ for all $1 \leq i \leq p_n$. Then

$$\mathbb{E} \left[\sum_{i=1}^{p_n} N(A_i^n) N(T^k A_i^n) \right] \xrightarrow{n \rightarrow \infty} \mathbb{E} [\# \{x \in N \cap A : T^k x \in N\}].$$

But, as $A \cap T^k A = \emptyset$,

$$\begin{aligned}
 \mathbb{E} \left[\sum_{i=1}^{p_n} N(A_i^n) N(T^k A_i^n) \right] &= \sum_{i=1}^{p_n} M_2^N(A_i^n \times T^k A_i^n) \\
 &= \sum_{i=1}^{p_n} \mu(A_i^n)^2 = \frac{\mu(A)^2}{p_n} \xrightarrow{n \rightarrow \infty} 0.
 \end{aligned}$$

Therefore $\# \{x \in N \cap A : T^k x \in N\} = 0$ a.s. But this is also true if we replace A by $T^n A$ for any $n \in \mathbb{Z}$. As T is conservative ergodic, the set A is a sweep out set, which means that $\cup_{n \in \mathbb{Z}} T^n A = X$ a.e. and we get $\# \{x \in N, T^k x \in N\} = 0$ a.s. \square

3. GETTING SU_SHIS

For each $n \geq 1$, let us denote by \mathcal{P}_n the set of all partitions of $\{1, \dots, n\}$. Given $\pi \in \mathcal{P}_n$, and a family $\kappa = (k_i)_{1 \leq i \leq n}$ of integers, we can define a measure m_π^κ on X^n , by setting

$$m_\pi^\kappa(A_1 \times \dots \times A_n) := \prod_{P \in \pi} \mu \left(\bigcap_{i \in P} T^{-k_i} A_i \right).$$

When $\kappa = (0, \dots, 0)$, we simply note m_π instead of $m_\pi^{(0, \dots, 0)}$. When π is the partition into points, m_π^κ is the product measure $\mu^{\otimes n}$. When π is the trivial partition with a single atom, m_π corresponds to the n -diagonal measure, concentrated on $\Delta_n := \{(x, \dots, x) \in X^n : x \in X\}$.

Since μ is T -invariant, the measure m_π^κ is $T^{\times n}$ -invariant. Moreover, we can always, without changing the measure m_π^κ , shift the subfamilies $(k_i)_{i \in P}$ so that $k_i = 0$ whenever i is the smallest element of the atom P of π : we say in this case that κ is π -compatible.

The action of $T^{\times n}$ on the measure m_π^κ is isomorphic to

$$(X^{\#\pi}, \mathcal{A}^{\otimes \#\pi}, \mu^{\otimes \#\pi}, T^{\times \#\pi}).$$

From now on, we assume that T satisfies the following properties:

- (P1) For each $n \geq 1$, the product system $(X^n, \mathcal{A}^{\otimes n}, \mu^{\otimes n}, T^{\times n})$ is ergodic;
- (P2) For each $n \geq 1$, if σ is a boundedly finite, $T^{\times n}$ -invariant measure on X^n , whose marginals are absolutely continuous with respect to μ , then σ is conservative, and its ergodic components are all of the form m_π^κ for some $\pi \in \mathcal{P}_n$ and some π -compatible family κ .

An example of a transformation T satisfying both properties is given by the infinite Chacon transformation, introduced by Adams, Friedman and Silva in 1997 [2]: Property (P1) is proved in their article, whereas we prove in [12] that it satisfies Property (P2).

3.1. Free implies Poisson.

Theorem 3.1. *Assume that properties (P1) and (P2) hold for T . If N is a free T -point process with moments of all orders defined on an ergodic system $(\Omega, \mathcal{F}, \mathbb{P}, S)$, then it is Poisson.*

Proof. Let N be a free T -point process with moments of all orders. We can assume that μ is the intensity of N . In the first step of the proof, we want to show that the moment measures of any order of N coincide with those of a Poisson process of intensity μ (we recall that this latter point process is itself a free, ergodic, T -point process).

The n -order moment measure M_n^N satisfies the hypothesis of Property (P2), hence it has at most countably many ergodic components, of the form m_π^κ for some $\pi \in \mathcal{P}_n$ and some π -compatible family κ . By lemma 2.6 applied with $N_1 = \dots = N_n = N$, which is a free T -point process, we see that the contribution of any m_π^κ , where $\kappa \neq (0, \dots, 0)$, vanishes. Therefore, the ergodic decomposition of M_n^N writes

$$M_n^N = \sum_{\pi \in \mathcal{P}_n} c_\pi m_\pi.$$

We first point out that for each $n \geq 1$, the weight of the n -diagonal measure is 1 (this is valid for any point process of intensity μ). Indeed, using once again a set $A \in \mathcal{A}_f$, and $\left((A_i^\ell)_{1 \leq i \leq p_\ell} \right)_{\ell \geq 1}$ a generating sequence of partitions of A , we get

$$\begin{aligned} \sum_{i=1}^{p_\ell} M_n^N (A_i^\ell \times \cdots \times A_i^\ell) &= \mathbb{E} \left[\sum_{i=1}^{p_\ell} N(A_i^\ell) \cdots N(A_i^\ell) \right] \\ &\xrightarrow{\ell \rightarrow \infty} \mathbb{E} [N(A)] = \mu(A) = \mu(A \cap \cdots \cap A). \end{aligned}$$

On the other hand,

$$\begin{aligned} \sum_{i=1}^{p_\ell} M_n^N (A_i^\ell \times \cdots \times A_i^\ell) &= M_n^N \left(\bigsqcup_{i=1}^{p_\ell} A_i^\ell \times \cdots \times A_i^\ell \right) \\ &\xrightarrow{\ell \rightarrow \infty} M_n^N (\Delta_n \cap A \times \cdots \times A). \end{aligned}$$

Therefore $M_n^N (\Delta_n \cap A \times \cdots \times A) = \mu(A \cap \cdots \cap A)$, which implies, as claimed, that the weight of the n -diagonal measure is 1.

We now want to prove by induction that, for all $n \geq 1$, M_n^N is the n -order moment measure of a Poisson process of intensity μ . The property is of course satisfied for $n = 1$. Let us assume it is satisfied up to some $n \geq 1$, and let A_1, \dots, A_{n+1} be sets in \mathcal{A}_f . Pick a nonempty subset $K \subsetneq \{1, \dots, n+1\}$. By the ergodic theorem, we get

$$\begin{aligned} (7) \quad \frac{1}{\ell} \sum_{k=1}^{\ell} \mathbb{E} \left[\prod_{i \in K} N(A_i) \left(\prod_{i \in K^c} N(A_i) \circ S^k \right) \right] \\ \xrightarrow{\ell \rightarrow \infty} \mathbb{E} \left[\prod_{i \in K} N(A_i) \right] \mathbb{E} \left[\prod_{i \in K^c} N(A_i) \right] \\ = M_{\#K}^N \left(\prod_{i \in K} A_i \right) M_{(n+1-\#K)}^N \left(\prod_{i \in K^c} A_i \right). \end{aligned}$$

On the other hand,

$$\begin{aligned} (8) \quad \frac{1}{\ell} \sum_{k=1}^{\ell} \mathbb{E} \left[\prod_{i \in K} N(A_i) \left(\prod_{i \in K^c} N(A_i) \circ S^k \right) \right] \\ = \frac{1}{\ell} \sum_{k=1}^{\ell} M_{n+1}^N \left(T^{-\epsilon_k(1)} A_1 \times \cdots \times T^{-\epsilon_k(n)} A_n \right) \\ = \sum_{\pi \in \mathcal{P}_{n+1}} c_\pi \frac{1}{\ell} \sum_{k=1}^{\ell} m_\pi \left(T^{-\epsilon_k(1)} A_1 \times \cdots \times T^{-\epsilon_k(n+1)} A_{n+1} \right) \end{aligned}$$

where $\epsilon_k(i) := k$ if $i \in K$, and $\epsilon_k(i) := 0$ otherwise. Coming back to the definition of m_π , we write

$$m_\pi \left(T^{-\epsilon_k(1)} A_1 \times \cdots \times T^{-\epsilon_k(n+1)} A_{n+1} \right) = \prod_{P \in \pi} \mu \left(\bigcap_{i \in P} T^{-\epsilon_k(i)} A_i \right).$$

Observe that, if K is a union of atoms of π , we have for any $1 \leq k \leq \ell$

$$m_\pi \left(T^{-\epsilon_k(1)} A_1 \times \cdots \times T^{-\epsilon_k(n+1)} A_{n+1} \right) = m_\pi (A_1 \times \cdots \times A_{n+1}).$$

Otherwise, there exists an atom $P \in \pi$ containing indices $i \in K$ and $j \notin K$, hence with $\epsilon_k(i) = k$ and $\epsilon_k(j) = 0$. We get that for some constant C ,

$$m_\pi \left(T^{-\epsilon_k(1)} A_1 \times \cdots \times T^{-\epsilon_k(n+1)} A_{n+1} \right) \leq C \mu(A_j \cap T^{-k} A_i).$$

But, since T is an ergodic infinite-measure-preserving map,

$$\frac{1}{\ell} \sum_{k=1}^{\ell} \mu(A_j \cap T^{-k} A_i) \xrightarrow{\ell \rightarrow \infty} 0.$$

Defining \mathcal{P}_{n+1}^K as the set of partitions $\pi \in \mathcal{P}_{n+1}$ where K is a union of atoms of π , the above proves that the contribution of all partitions $\pi \in \mathcal{P}_{n+1} \setminus \mathcal{P}_{n+1}^K$ vanishes, and we get, using (7) and (8),

$$M_{\#K}^N \left(\prod_{i \in K} A_i \right) M_{(n+1-\#K)}^N \left(\prod_{i \in K^c} A_i \right) = \sum_{\pi \in \mathcal{P}_{n+1}^K} c_\pi m_\pi (A_1 \times \cdots \times A_{n+1}).$$

Since $\emptyset \neq K \subsetneq \{1, \dots, n+1\}$, the ergodic decompositions of $M_{\#K}^N$ and $M_{(n+1-\#K)}^N$ only involve the coefficients c_π , $\pi \in \mathcal{P}_1 \cup \cdots \cup \mathcal{P}_n$. Identifying the ergodic decompositions on both sides of the above equality, we see that all the coefficients c_π , $\pi \in \mathcal{P}_{n+1}^K$ are completely determined by coefficients corresponding to partitions in $\mathcal{P}_1 \cup \cdots \cup \mathcal{P}_n$. Moreover, the above argument is valid in particular when N is the Poisson process of intensity μ (which is free by Proposition 2.7). By letting K run through all strict subsets of $\{1, \dots, n+1\}$, and using the induction hypothesis, we identify all but one coefficients of the ergodic decomposition of M_{n+1}^N as those of the Poisson point process of intensity μ . The only coefficient that cannot be determined by this method is the one associated to the trivial partition of $\{1, \dots, n+1\}$ into a single atom. But this corresponds to the $(n+1)$ -diagonal measure, and we already know that this coefficient is 1.

We have proved the moment measures of any order of N are those of a Poisson point process of intensity μ . In the second step of the proof, it remains to show it is sufficient to identify this latter point process.

Let \mathcal{N} be a Poisson point process of intensity μ . The distribution of \mathcal{N} is completely determined by the quantities

$$\mathbb{E}[\exp(\alpha_1 \mathcal{N}(A_1) + \cdots + \alpha_k \mathcal{N}(A_k))]$$

for any $k \geq 1$ and any collection A_1, \dots, A_k of disjoint sets in \mathcal{A}_f and positive numbers $\alpha_1, \dots, \alpha_k$.

Let $Y := \alpha_1 \mathcal{N}(A_1) + \cdots + \alpha_k \mathcal{N}(A_k)$ be such a random variable, and set $Z := \alpha_1 N(A_1) + \cdots + \alpha_k N(A_k)$. Since the moment measures of N and \mathcal{N} coincide, we have for any $n \geq 1$,

$$(9) \quad \mathbb{E}[Y^n] = \mathbb{E}[Z^n].$$

The Laplace transform $\varphi(t) = \mathbb{E}[e^{-tY}]$ is analytic on \mathbb{R} , which implies that the series

$$\sum_{n=0}^{+\infty} \frac{|t|^n}{n!} \mathbb{E}[Y^n]$$

converges (to $\varphi(-|t|)$). But this, in turn, implies with (9) that the series

$$\sum_{n=0}^{+\infty} \frac{(-1)^n t^n}{n!} Z^n$$

converges in $L^1(\mathbb{P})$ to $\exp(-tZ)$. Therefore, the Laplace transform of Z is also $\varphi(t)$ and we obtain

$$\mathbb{E}[\exp(\alpha_1 \mathcal{N}(A_1) + \cdots + \alpha_k \mathcal{N}(A_k))] = \mathbb{E}[\exp(\alpha_1 N(A_1) + \cdots + \alpha_k N(A_k))]$$

which ends the proof. \square

3.2. Dissociation implies independence.

Proposition 3.2. *Assume that properties (P1) and (P2) hold for T . Let N_1, \dots, N_k be Poisson T -point processes, of respective intensity $\alpha_1 \mu, \dots, \alpha_k \mu$, defined on the same ergodic system $(\Omega, \mathcal{F}, \mathbb{P}, S)$. If these processes are mutually dissociated, then they are independent.*

Proof. Let n_1, \dots, n_k be positive numbers, $n := n_1 + \cdots + n_k$, and let $\{Q_1, \dots, Q_k\}$ be the partition of $\{1, \dots, n\}$ in subsets of consecutive integers of respective size n_1, \dots, n_k . For any $\{A_i\}_{1 \leq i \leq n}$ in \mathcal{A}_f , set

$$(10) \quad \sigma(A_1 \times \cdots \times A_n) := \mathbb{E} \left[\prod_{j=1}^k \prod_{i \in Q_j} N_j(A_i) \right].$$

This defines a $T^{\times n}$ -invariant measure σ on $(X^n, \mathcal{A}^{\otimes n})$, which satisfies the hypotheses of Property (P2). Hence σ has at most countably many ergodic components, of the form m_π^κ for some $\pi \in \mathcal{P}_n$ and some π -compatible family κ . By lemma 2.6, as the processes N_1, \dots, N_k are mutually dissociated, only partitions π refining the partition $\{Q_1, \dots, Q_k\}$ may appear in the ergodic decomposition of σ . Therefore, any ergodic component m_π^κ of σ has the form

$$m_\pi^\kappa(A_1 \times \cdots \times A_n) = \prod_{j=1}^k \nu_j \left(\prod_{i \in Q_j} A_i \right),$$

where each ν_j is a $T^{\times n_j}$ -invariant measure. In particular, any ergodic component of σ is invariant by the transformation $(x_1, \dots, x_n) \mapsto (y_1, \dots, y_n)$, where $y_i := Tx_i$ if $i \in Q_k$, and $y_i := x_i$ otherwise. It follows that σ itself is invariant by this transformation, hence the expression defining $\sigma(A_1 \times \cdots \times A_n)$ on the right-hand side of (10) is unchanged if we replace $N_k(A_i)$ by $N_k(T^{-1}A_i)$ for all $i \in Q_k$ simultaneously. Therefore, we can write for any $\{A_i\}_{1 \leq i \leq n}$ in \mathcal{A}_f and any $L \geq 1$

$$\begin{aligned} \mathbb{E} \left[\prod_{j=1}^k \prod_{i \in Q_j} N_j(A_i) \right] &= \frac{1}{L} \sum_{1 \leq \ell \leq L} \mathbb{E} \left[\left(\prod_{j=1}^{k-1} \prod_{i \in Q_j} N_j(A_i) \right) \prod_{i \in Q_k} N_k(T^{-\ell} A_i) \right] \\ &= \mathbb{E} \left[\left(\prod_{j=1}^{k-1} \prod_{i \in Q_j} N_j(A_i) \right) \left(\frac{1}{L} \sum_{1 \leq \ell \leq L} \prod_{i \in Q_k} N_k \circ S^\ell(A_i) \right) \right]. \end{aligned}$$

By the ergodic theorem, this converges as $L \rightarrow \infty$ to

$$\mathbb{E} \left[\prod_{j=1}^{k-1} \prod_{i \in Q_j} N_j(A_i) \right] \mathbb{E} \left[\prod_{i \in Q_k} N_k(A_i) \right].$$

A straightforward induction on k then yields the equality

$$\mathbb{E} \left[\prod_{j=1}^k \prod_{i \in Q_j} N_j(A_i) \right] = \prod_{j=1}^k \mathbb{E} \left[\prod_{i \in Q_j} N_j(A_i) \right],$$

and this is sufficient to obtain the independence between the Poisson processes. \square

Compiling the previous results, we now get the following structure theorem.

Theorem 3.3. *Assume that properties (P1) and (P2) hold for T . Let N be a T -point process with moments of all orders defined on an ergodic system $(\Omega, \mathcal{F}, \mathbb{P}, S)$. Then N is a SuShi.*

Proof. Since N is square integrable, Proposition 2.1 ensures that N almost surely gives a finite measure to any T -orbit. We can therefore apply Proposition 2.5 to write N as

$$N = \sum_{i \in I} \left(\sum_{k \in F_i} N_{F_i} \circ S^k \right), \mathbb{P}\text{-a.s.}$$

where I is countable, each F_i is a finite subset of \mathbb{Z} , and the T -point processes N_{F_i} are free and mutually dissociated. Then Proposition 2.7 proves that each N_{F_i} is a Poisson process, and Proposition 3.2 shows that they are independent. \square

4. APPLICATION TO THE STRUCTURE OF POISSON JOININGS

4.1. Notions on the L^2 structure of a Poisson suspension. There is a strong relationship between the L^2 -spaces of the suspension and the underlying space. Namely, $L^2(\mu^*)$ can be seen as the Fock space of $L^2(\mu)$ (see [18]), that is

$$L^2(\mu^*) \simeq \text{Fock}(L^2(\mu)) := \mathbb{C} \oplus L^2(\mu) \oplus L^2(\mu)^{\odot 2} \oplus \cdots \oplus L^2(\mu)^{\odot n} \oplus \cdots,$$

where $L^2(\mu)^{\odot n}$ stands for the n -order symmetric tensor power of $L^2(\mu)$, and the inner product given on $L^2(\mu)^{\odot n}$ is given by

$$\langle f^{\otimes n}, g^{\otimes n} \rangle_{\text{Fock}(L^2(\mu))} := \frac{1}{n!} \langle f, g \rangle^n.$$

This means there is a sequence $\{H^n\}_{n \geq 0}$ of so-called (*Poissonian*) *chaos* which are orthogonal subspaces inside $L^2(\mu^*)$, such that $L^2(\mu^*) = \overline{\bigoplus_{n \geq 0} H^n}$, and where, for each $n \geq 1$, H^n is identified to $L^2(\mu)^{\odot n}$ through multiple integrals (H^0 corresponds to constant functions, identified to \mathbb{C}). In this paper we only need to know what happens in the first chaos: H^1 is linearly spanned by functions $N(A) - \mu(A)$, for $A \in \mathcal{A}_f$, and $N(A) - \mu(A) \in H^1$ corresponds to $1_A \in L^2(\mu)$. We have the isometry relation

$$\left\langle N(A) - \mu(A), N(B) - \mu(B) \right\rangle_{L^2(\mu^*)} = \langle 1_A, 1_B \rangle_{L^2(\mu)}.$$

If φ is a linear operator from $L^2(\mu_1)$ to $L^2(\mu_2)$, of norm less than 1, then φ extends naturally to an operator $\tilde{\varphi}$, called the *exponential of φ* , from $\text{Fock}(L^2(\mu_1))$ to $\text{Fock}(L^2(\mu_2))$, by

$$\tilde{\varphi}(f^{\otimes n}) := \varphi(f) \otimes \cdots \otimes \varphi(f).$$

In particular, if U_T and U_{T^*} denote the unitary operators associated to T and T^* on their respective spaces, then, through the identification, we have

$$U_{T^*} = \widetilde{U_T}.$$

4.2. Poisson factors and Poisson joinings. There is a distinguished collection of factors within a Poisson suspension $(X^*, \mathcal{A}^*, \mu^*, T^*)$ that are also Poisson suspensions:

Definition 4.1 (Poisson factor). *Let $Y \subset X$ be a T -invariant set, and let $\mathcal{C} \subset \mathcal{A}|_Y$ be a σ -finite sub- σ -algebra of \mathcal{A} restricted to Y . Then the Poisson suspension $(Y^*, \mathcal{C}^*, \mu^*, T^*)$ is a natural factor of $(X^*, \mathcal{A}^*, \mu^*, T^*)$ via the factor map*

$$\xi \in X^* \longmapsto \xi|_{\mathcal{C}} \in Y^*.$$

Such a factor is called a Poisson factor of the suspension $(X^*, \mathcal{A}^*, \mu^*, T^*)$.

Let $(Y_i, \mathcal{Y}_i, \rho_i, R_i)$, $i \in I$, be a finite or countable family of dynamical systems. We recall that a *joining* of these dynamical systems is a measure on $\prod_i Y_i$, invariant by the product transformation $\prod_i R_i : (y_i)_{i \in I} \mapsto (R_i y_i)_{i \in I}$, and whose marginal on each coordinate i is ρ_i .

Note that this definition is not restricted to probability measure preserving systems, but extends to the case where measures are σ -finite.

To a joining m of two systems $(Y_i, \mathcal{Y}_i, \rho_i, R_i)$, $i = 1, 2$, corresponds a Markov operator $\varphi : L^2(\rho_1) \rightarrow L^2(\rho_2)$, defined by

$$\forall A \in \mathcal{Y}_1, B \in \mathcal{Y}_2 \text{ with finite measure, } m(A \times B) := \int_B \varphi(1_A) d\rho_2.$$

A *self-joining of order n* is a joining of n identical copies of the same system.

The structure of Poisson suspensions allows to define a natural family of joinings which plays a central role in this work.

Definition 4.2 (Poisson joining). *Let $(X_i^*, \mathcal{A}_i^*, \mu_i^*, (T_i)_*)$, $i \in I$ be a finite or countable family of Poisson suspensions. Assume that $(Z^*, \mathcal{Z}^*, m^*, R^*)$ is some other Poisson suspension, that $(Z_i)_{i \in I}$ is a family of R -invariant subsets of Z , and that for each $i \in I$ we are given a measurable map $\pi_i : Z_i \rightarrow X_i$ such that*

- $(\pi_i)_*(m|_{Z_i}) = \mu_i$,
- $\pi_i \circ R = T_i \circ \pi_i$.

Let N be a Poisson R -point process of distribution m^* . Then the distribution of $\left((\pi_i)_*(N|_{Z_i}) \right)_{i \in I}$ is a joining of the Poisson suspensions $(X_i^*, \mathcal{A}_i^*, \mu_i^*, (T_i)_*)$, which we call a Poisson joining.

Let us recall the probabilistic notion of infinite divisibility, which is useful for the study of Poisson joinings. The addition of σ -finite measures on (X, \mathcal{A}) is measurable and well defined and so is the convolution of distributions on $(\tilde{X}, \tilde{\mathcal{A}})$: $m_1 * m_2$ is

the pushforward measure of $m_1 \otimes m_2$ by the application

$$\begin{aligned} (\tilde{X} \times \tilde{X}, \tilde{\mathcal{A}} \otimes \tilde{\mathcal{A}}) &\rightarrow (\tilde{X}, \tilde{\mathcal{A}}) \\ (\nu_1, \nu_2) &\mapsto \nu_1 + \nu_2 \end{aligned}$$

Definition 4.3 (Infinite divisibility). *A probability measure m on $(\tilde{X}, \tilde{\mathcal{A}})$ is said to be infinitely divisible if, for every $k \geq 2$, there exists a probability measure m_k such that*

$$m = (m_k)^{*k} := m_k * \cdots * m_k.$$

The distribution of a Poisson point process is easily seen to be infinitely divisible, as we have

$$\mu^* = \left(\left(\frac{1}{k} \mu \right)^* \right)^{*k},$$

which is the formula capturing the fact that the independent superposition of k Poisson point processes of intensities $\frac{1}{k}\mu$ is a Poisson point process of intensity μ .

Observe that a pair of measures $(\xi_1, \xi_2) \in \tilde{X}_1 \times \tilde{X}_2$ is naturally identified with a measure on the disjoint union $X_1 \sqcup X_2$. Therefore, a distribution on $\tilde{X}_1 \times \tilde{X}_2$ is itself identified to a distribution on $(X_1 \sqcup X_2)$, and we use this identification to define infinite divisibility of a joining of Poisson suspensions.

Poisson joinings of two Poisson suspensions were defined independently using Markov operators in [8], and infinite divisibility in [21], where both definitions were proved to be equivalent. Combining the results of these two papers, we get the following proposition.

Proposition 4.4. *Let γ be a joining of two Poisson suspensions. The following properties are equivalent:*

- (1) γ is a Poisson joining.
- (2) γ is infinitely divisible.
- (3) The Markov operator associated to γ is the exponential of a sub-Markov operator defined between the L^2 spaces of the bases.

In [8] and [21], Poisson joinings of two Poisson suspensions $(X_i^*, \mathcal{A}_i^*, \mu_i^*, (T_i)_*)$, $i = 1, 2$, are in fact characterized by the following structure, which is easily seen to fit our definition 4.2. Let us first fix two measures $\gamma_1 \leq \mu_1$ and $\gamma_2 \leq \mu_2$, respectively invariant by T_1 and T_2 . Then consider a joining $(X_1 \times X_2, \mathcal{A}_1 \otimes \mathcal{A}_2, m, T_1 \times T_2)$ of $(X_1, \mathcal{A}_1, \gamma_1, T_1)$ and $(X_2, \mathcal{A}_2, \gamma_2, T_2)$, and form the Poisson suspension

$$((X_1 \times X_2)^*, (\mathcal{A}_1 \otimes \mathcal{A}_2)^*, m^*, (T_1 \times T_2)_*).$$

Now we project the points of the Poisson process on $X_1 \times X_2$ of intensity m on both axes X_1 and X_2 , getting two Poisson processes with intensities γ_1 and γ_2 . This defines a factor map

$$\nu \in (X_1 \times X_2)^* \mapsto (\nu(\cdot \times X_2), \nu(X_1 \times \cdot)) \in X_1^* \times X_2^*,$$

and the factor we obtain is a joining $(X_1^* \times X_2^*, \mathcal{A}_1^* \otimes \mathcal{A}_2^*, \tilde{m}, (T_1)_* \times (T_2)_*)$ of the two Poisson suspensions $(X_1^*, \mathcal{A}_1^*, \gamma_1^*, (T_1)_*)$ and $(X_2^*, \mathcal{A}_2^*, \gamma_2^*, (T_2)_*)$. In order to adjust intensities when $\gamma_i < \mu_i$, we superpose on each side an independent Poisson process of intensity $\mu_i - \gamma_i$, $i = 1, 2$. Formally, we consider the direct product of the

three systems $(X_1^*, \mathcal{A}_1^*, (\mu_1 - \gamma_1)^*, (T_1)_*)$, $(X_1^* \times X_2^*, \mathcal{A}_1^* \otimes \mathcal{A}_2^*, \tilde{m}, (T_1)_* \times (T_2)_*)$ and $(X_2^*, \mathcal{A}_2^*, (\mu_2 - \gamma_2)^*, (T_2)_*)$, and form

$$(X_1^* \times X_2^*, \mathcal{A}_1^* \otimes \mathcal{A}_2^*, \hat{m}, (T_1)_* \times (T_2)_*)$$

through the factor map from $(X_1^* \times (X_1^* \times X_2^*) \times X_2^*)$ to $(X_1^* \times X_2^*)$ defined by

$$(\tilde{\nu}_1, (\nu_1, \nu_2), \tilde{\nu}_2) \mapsto (\tilde{\nu}_1 + \nu_1, \nu_2 + \tilde{\nu}_2).$$

Then \hat{m} is a Poisson joining of the two Poisson suspensions $(X_i^*, \mathcal{A}_i^*, \mu_i^*, (T_i)_*)$, $i = 1, 2$.

The sub-Markov operator mentioned in Proposition 4.4 corresponds to the joining m in the above description, which can also be seen as a *sub-joining* of $(X_1, \mathcal{A}_1, \mu_1, T_1)$ and $(X_2, \mathcal{A}_2, \mu_2, T_2)$.

Example 4.5. *The main situation that occurs in this paper is a Poisson self-joining of order 2 of $(X^*, \mathcal{A}^*, \mu^*, T_*)$ where*

$$m := \sum_{k \in \mathbb{Z}} a_k \Delta_{T^k}$$

with $a_k \geq 0$ and $\sum_{k \in \mathbb{Z}} a_k \leq 1$. If $a_k = 1$ for some k , the corresponding Poisson joining \hat{m} is the graph joining $\Delta_{(T^*)^k}$. If $\sum_{k \in \mathbb{Z}} a_k = 0$, then \hat{m} is the product joining. In the other cases, we get a combination of both.

4.3. Embedding joinings in a universal suspension.

Lemma 4.6. *Assume that properties (P1) and (P2) hold for T . Let $\{N_i\}_{i \in I}$ and N be Poisson T -point processes defined on the ergodic dynamical system $(\Omega, \mathcal{F}, \mathbb{P}, S)$, where I is at most countable and the $\{N_i\}_{i \in I}$ are independent.*

Then there exists a collection of (eventually vanishing) independent Poisson T -point processes $(N_\infty, \{N_{i,k}\}_{i \in I, k \in \mathbb{Z} \cup \infty})$, also defined on $(\Omega, \mathcal{F}, \mathbb{P})$, measurable with respect to $\sigma(N, \{N_i\}_{i \in I})$, such that

$$N_i = N_{i,\infty} + \sum_{k \in \mathbb{Z}} N_{i,k},$$

and

$$N = N_\infty + \sum_{i \in I} \sum_{k \in \mathbb{Z}} N_{i,k} \circ S^k.$$

Proof. For each i , we consider the pair (N, N_i) . For every $k \in \mathbb{Z}$, the points $x \in N_i(\omega)$ such that $T^k x \in N(\omega)$ define a point process $N_{i,k}$. By Proposition 2.7, N and the N_i are free. Hence, we obtain

$$\sum_{k \in \mathbb{Z}} N_{i,k} \leq N_i$$

and

$$\sum_{i \in I} \sum_{k \in \mathbb{Z}} N_{i,k} \circ S^k \leq N.$$

We define also $N_{i,\infty} := N_i - \sum_{k \in \mathbb{Z}} N_{i,k}$ and $N_\infty := N - \sum_{i \in I} \sum_{k \in \mathbb{Z}} N_{i,k} \circ S^k$. Then the processes $\{N_{i,k}\}_{i \in I, k \in \mathbb{Z} \cup \infty}$ and N_∞ are free and mutually dissociated T -point processes defined on the ergodic dynamical system $(\Omega, \mathcal{F}, \mathbb{P}, S)$. They are therefore independent Poisson T -point processes by Theorem 3.1 and Proposition 3.2. \square

Theorem 4.7. *Assume that properties (P1) and (P2) hold for T . Let $(\alpha_1, \alpha_2, \dots)$ be a finite or countable family of positive real numbers. Then any ergodic joining of the family of Poisson suspensions $(X^*, \mathcal{A}^*, (\alpha_i \mu)^*, T_*)$ is a Poisson joining, which can be obtained as a factor of the ergodic Poisson suspension*

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*),$$

where \mathcal{B} and λ respectively denote the Borel σ -algebra and the Lebesgue measure on \mathbb{R}_+ .

Proof. We only consider the case of a joining of a countably infinite family, the case of a finite family being covered by the same proof up to obvious changes in notations. Let $(\Omega, \mathcal{F}, \mathbb{P}, S) := (X^{*\mathbb{N}}, (\mathcal{A}^*)^{\otimes \mathbb{N}}, m, (T_*)^{\otimes \mathbb{N}})$ be an ergodic joining of the countable family of Poisson suspensions $(X^*, \mathcal{A}^*, (\alpha_i \mu)^*, T_*)$, $i \in \mathbb{N}$. For each $j \geq 1$, we define on this space the Poisson T -point processes of intensity $\alpha_j \mu$

$$N_j(\nu_1, \nu_2, \dots) := \nu_j.$$

Let \mathcal{N} be the Poisson point process with intensity $\mu \otimes \lambda$ on $X \times \mathbb{R}_+$. Observe first that, if $J \subset \mathbb{R}_+$ is an interval of length β , the random measure $\mathcal{N}(\cdot \times J)$ is a Poisson T -point process of intensity $\beta \mu$ (here the underlying transformation is $(T \times \text{Id})_*$). Moreover, if we take disjoint subintervals of \mathbb{R}_+ , the corresponding Poisson T -point processes obtained in this way are independent. In particular, $\tilde{N}_1 := \mathcal{N}(\cdot \times [0, \alpha_1])$ has the same distribution as N_1 . Observe also that \tilde{N}_1 can be written as $\pi_*(\mathcal{N}|_{Z_1})$, where $Z_1 := X \times [0, \alpha_1)$ and π is the projection on X .

Set $M_1 := N_1$, and $\tilde{M}_1 := \tilde{N}_1$. Now assume that, for some $n \geq 1$, we have found a finite or countable family $(M_i)_{i \in I}$ of independent Poisson T -point processes, measurable with respect to (N_1, \dots, N_n) , such that for $1 \leq j \leq n$,

$$(11) \quad N_j = \sum_{i \in I_j} M_i \circ S^{k(i,j)},$$

where $I_j \subset I$ and $k(i, j) \in \mathbb{Z}$. Let $\beta_i \geq 0$ be such that M_i has intensity $\beta_i \mu$. Assume also that we have a family $(J_i)_{i \in I}$ of disjoint subintervals of \mathbb{R}_+ of respective length β_i . Then, the family of T -point processes $\tilde{M}_i := \mathcal{N}(\cdot \times J_i)$ has the same distribution as $(M_i)_{i \in I}$, and the formula

$$\tilde{N}_j := \sum_{i \in I_j} \tilde{M}_i \circ ((T \times \text{Id})_*)^{k(i,j)}$$

yields a family $(\tilde{N}_1, \dots, \tilde{N}_n)$ of T -point processes defined on

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*),$$

which has the same distribution as (N_1, \dots, N_n) . Moreover, each \tilde{N}_j , $1 \leq j \leq n$ can be written as $(\pi_j)_*(\mathcal{N}|_{Z_j})$, where $Z_j := X \times \left(\bigcup_{i \in I_j} J_i\right)$, and π_j is $T^{k(i,j)} \circ \pi$ on $X \times J_i$.

By Lemma 4.6 applied to the collection (M_i) and N_{n+1} , we obtain a countable family of independent Poisson T -point processes $\{M_{i,k}\}_{i \in I, k \in \mathbb{Z} \cup \{\infty\}}$ and $N_{n+1, \infty}$, such that for each $i \in I$,

$$M_i = \sum_{k \in \mathbb{Z} \cup \{\infty\}} M_{i,k},$$

and

$$N_{n+1} = N_{n+1,\infty} + \sum_{i \in I} \sum_{k \in \mathbb{Z}} M_{i,k} \circ S^k.$$

In particular, any N_j , $1 \leq j \leq n+1$ can be reconstructed from the family $M_{i,k}$ and $N_{n+1,\infty}$ with a formula similar to (11). Each $M_{i,k}$ has intensity $\beta_{i,k}\mu$ for some $\beta_{i,k} \geq 0$, and

$$\beta_i = \sum_{k \in \mathbb{Z} \cup \{\infty\}} \beta_{i,k}.$$

We can therefore partition J_i into disjoint subintervals $J_{i,k}$ of respective length $\beta_{i,k}$. Let $\beta \geq 0$ be such that $N_{n+1,\infty}$ has intensity $\beta\mu$. We can then find an extra subinterval of \mathbb{R}_+ , disjoint from $\bigcup_{i \in I} J_i$, of length β . From this family of disjoint subintervals of \mathbb{R}_+ we can construct a family of independent Poisson T -point processes $(\tilde{M}_{i,k})$ and $\tilde{N}_{n+1,\infty}$. Then, setting

$$\tilde{N}_{n+1} := \tilde{N}_{n+1,\infty} + \sum_{i \in I} \sum_{k \in \mathbb{Z}} \tilde{M}_{i,k} \circ ((T \times \text{Id})_*)^k,$$

we get a family $(\tilde{N}_1, \dots, \tilde{N}_n, \tilde{N}_{n+1})$ of T -point processes which has the same distribution as $(N_1, \dots, N_n, N_{n+1})$.

By induction we get a family $(\tilde{N}_1, \tilde{N}_2, \dots)$, defined on

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*),$$

which has the same distribution as (N_1, N_2, \dots) . Moreover, each \tilde{N}_j can be written as $(\pi_j)_*(\mathcal{N}|_{Z_j})$, where Z_j is a $T \times \text{Id}$ -invariant subset of $X \times \mathbb{R}_+$, and $\pi_j : Z_j \rightarrow X$ satisfies the requirements of Definition 4.2. This ends the proof of the theorem. \square

4.4. The \mathcal{PaP} property. In [20], the natural question of the existence of Poisson suspensions with Poisson joinings as only ergodic self-joinings was addressed. This lead to the following definition:

Definition 4.8. *A Poisson suspension whose all ergodic self-joinings of order n (resp. countable ergodic self-joinings) are Poisson is said to be $\mathcal{PaP}(n)$ (resp. $\mathcal{PaP}(\infty)$ (from the French “Poisson à autocouplages Poissons”). $\mathcal{PaP}(2)$ will be shortened as \mathcal{PaP} .*

This notion is inspired by, and therefore closely related to, the so-called *GAG* property for Gaussian stationary processes (see [16]). Indeed *GAG* Gaussian stationary processes are the processes whose ergodic self-joinings remain Gaussian.

We first present some consequences of the \mathcal{PaP} property.

Proposition 4.9. *A Poisson suspension with the $\mathcal{PaP}(\infty)$ property has the so-called PID property (i.e. for any n , any self-joining of order n with pairwise independent coordinates is the product measure).*

Proof. Consider an n -order self-joining of a $\mathcal{PaP}(\infty)$ suspension with pairwise independence. With the notation of Definition 4.2, we obtain that any two coordinates of the self-joining are associated to pairwise disjoint sets $Z_i \subset Z$. But by elementary properties of Poisson point processes recalled in Definition 1.3, we obtain global independence. \square

Recall that the *centralizer* of an invertible measure-preserving transformation S is the set, denoted by $C(S)$, of all invertible measure-preserving transformations on the same space which commute with S .

Proposition 4.10. *Let $(X^*, \mathcal{A}^*, \mu^*, T_*)$ be a \mathcal{PaP} suspension and let $R \in C(T_*)$. Then there exists $S \in C(T)$ such that $R = S_*$. In particular $C(T_*) \simeq C(T)$.*

Proof. R induces an ergodic self-joining of the suspension which is Poisson thanks to the \mathcal{PaP} property. Therefore the associated Markov operator has the form $\tilde{\varphi}$ for some sub-Markov operator φ on $L^2(\mu)$ that commutes with T . But as $\tilde{\varphi}$ is an isometry, φ is also an isometry and is therefore induced by a measure preserving map S of (X, \mathcal{A}, μ) that commutes with T , i.e. an element of $C(T)$. By identification, $R = S_*$. \square

The next proposition is very similar to Theorem 2 in [19].

Proposition 4.11. *Let $(X^*, \mathcal{A}^*, \mu^*, T_*)$ be a \mathcal{PaP} suspension and $\mathcal{K} \subset \mathcal{A}^*$ a non-trivial factor. Then there exists a non-trivial Poisson factor contained in \mathcal{K} , that is, there exists a T -invariant set of positive measure $Y \subset X$ and a T -invariant σ -finite σ -algebra $\mathcal{C} \subset \mathcal{A}|_Y$ such that $\mathcal{C}^* \subset \mathcal{K}$.*

Proof. Let Φ be the conditional expectation corresponding to \mathcal{K} , which is the Markov operator associated to the relatively independent self-joining over \mathcal{K} . The ergodic decomposition of this joining allows to write Φ as an integral of indecomposable operators corresponding to ergodic self-joinings. By the \mathcal{PaP} property, these operators are of exponential form, i.e. we have:

$$\Phi = \int_{\mathcal{W}} \tilde{\Psi}_w \rho(dw)$$

for some probability space $(\mathcal{W}, \mathcal{B}, \rho)$. As each $\tilde{\Psi}_w$ preserves the first chaos, so does Φ . Moreover, if Φ vanishes on the first chaos, so does $\tilde{\Psi}_w$ for ρ -almost every $w \in \mathcal{W}$. But the only Markov operator of exponential form that vanishes on the first chaos is the projection on the constants. This means that Φ is also this projection, which corresponds to the conditional expectation on the trivial factor, yielding a contradiction. Thus Φ does not vanish on the first chaos and we can apply Proposition 1 in [19]: Φ induces on $L^2(\mu)$ a sub-Markov operator φ , and there exists a T -invariant set $Y \subset X$ such that φ restricted to $L^2(\mu|_Y)$ is a conditional expectation on a σ -finite factor $\mathcal{C} \subset \mathcal{A}|_Y$, and φ vanishes on $L^2(\mu|_{Y^c})$. Coming back to $L^2(\mu^*)$, Φ coincides with the exponential operator $\tilde{\varphi}$ on the first chaos. Therefore its image contains all the vectors of the form $N(A) - \mu(A)$, $A \in \mathcal{C}$ of finite measure. These vectors are therefore \mathcal{K} -measurable, thus $\mathcal{C}^* \subset \mathcal{K}$. \square

Corollary 4.12. *Let $(X^*, \mathcal{A}^*, \mu^*, T_*)$ be a \mathcal{PaP} suspension. If T is ergodic and has no non-trivial factor, then T_* is prime.*

Proposition 4.13. *Let $(X^*, \mathcal{A}^*, \mu^*, T_*)$ be a \mathcal{PaP} suspension and $\mathcal{K} \subset \mathcal{A}^*$ a factor, then T_* is relatively weakly mixing over \mathcal{K} if and only if \mathcal{K} is a Poisson factor.*

Proof. The fact that T_* is relatively weakly mixing over \mathcal{K} if it is a Poisson factor was remarked in [21]. To prove the converse, assume T_* is relatively weakly mixing over \mathcal{K} , this means that the relatively independent joining over \mathcal{K} is ergodic and therefore a Poisson joining thanks to the \mathcal{PaP} property. Then \mathcal{K} is Poisson thanks to Proposition 4.7 in [21]. \square

Lemańczyk in [7] introduced the notion of semi-simplicity:

Definition 4.14. *The probability preserving dynamical system $(\Omega, \mathcal{F}, \mathbb{P}, S)$ is semi-simple if any ergodic self-joining $(\Omega \times \Omega, \mathcal{F} \otimes \mathcal{F}, m, S \times S)$, is a relatively weakly mixing extension over $(\Omega, \mathcal{F}, \mathbb{P}, S)$ through the projection map.*

As an easy consequence of the preceding result, we get:

Corollary 4.15. *A \mathcal{PaP} suspension is semi-simple.*

Proposition 4.16. *Let $(X^*, \mathcal{A}^*, \mu^*, T_*)$ be a \mathcal{PaP} suspension and a factor \mathcal{K} generated by random variables of the form $N(A_i)$, $A_i \in \mathcal{A}_f$, $i \in I$. Then \mathcal{K} is a Poisson factor.*

Proof. If Φ is the conditional expectation corresponding to \mathcal{K} , then as in the proof of Proposition 4.11, it coincides on the first chaos with $\tilde{\varphi}$ for some conditional expectation on a σ -finite factor $\mathcal{C} \subset \mathcal{A} \mid_Y$, where Y is a T -invariant subset of X and $\mathcal{C}^* \subset \mathcal{C}$. Therefore, the random variables $N(A_i) - \mu(A_i)$ are in the image of both Φ and $\tilde{\varphi}$, and as such are \mathcal{C}^* -measurable. This implies that $\mathcal{K} \subset \mathcal{C}^*$ and therefore $\mathcal{K} = \mathcal{C}^*$. \square

Proposition 4.17. *A Poisson factor of a \mathcal{PaP} suspension is also \mathcal{PaP} .*

Proof. Let $(Y^*, \mathcal{B}^*, \nu^*, S_*)$ be a Poisson factor of a \mathcal{PaP} suspension $(X^*, \mathcal{A}^*, \mu^*, T_*)$. An ergodic self-joining of the former can be embedded into an ergodic self-joining of the latter, which is Poisson by hypothesis. Therefore, by definition of Poisson joinings, we get another suspension $(Z^*, \mathcal{Z}^*, \rho^*, R_*)$ in which the two copies of X^* are seen as Poisson factors. Since Poisson factors of Poisson factors are still Poisson factors, the two copies of Y^* are Poisson factors of Z^* , and we get the result. \square

Theorem 4.18. *Assume that properties (P1) and (P2) hold for T . Then the Poisson suspension $(X^*, \mathcal{A}^*, \mu^*, T_*)$ is $\mathcal{PaP}(\infty)$, prime, mildly mixing and its centralizer is reduced to the powers of T_* .*

Proof. By Theorem 4.7, the suspension is $\mathcal{PaP}(\infty)$. Primeness comes from Corollary 4.12, and the fact that properties (P1) and (P2) imply that T has no non-trivial factor (see [12]). The triviality of the centralizer of T follows also from properties (P1) and (P2) (see again [12]), then applying Proposition 4.10, we get that T_* commutes only with its powers. At last, a transformation is mildly mixing if it has no non-trivial rigid factor, which in the situation of a prime transformation reduces to the property that T_* is not rigid. This is the case, since a rigid transformation has an uncountable centralizer (see [13]). \square

We know from Proposition 5.1 in [12] that properties (P1) and (P2) imply the triviality of the centralizer of T . Hence, for $n \geq 2$, T^n never satisfies (P1) and (P2), even if T does. We can nevertheless obtain the \mathcal{PaP} property for T_*^n when T satisfies properties (P1) and (P2). This is a direct application of a lemma we borrow from [16].

Lemma 4.19. *Let R and S be two commuting ergodic automorphisms of the probability space $(\Omega, \mathcal{F}, \mathbb{P})$. Let $J_2^e(R)$ (resp. $J_2^e(S)$) be the set of ergodic self-joinings of R (resp. S) and let $F = \overline{\langle R \rangle}$ (resp. $G = \overline{\langle R, S \rangle}$) be the closure of the group generated by R (resp. R and S) inside $\text{Aut}(\Omega, \mathcal{F}, \mathbb{P})$. If G/F is compact and $J_2^e(S) \subset J_2^e(R)$, then $J_2^e(S) = J_2^e(R)$.*

Corollary 4.20. *If (X, \mathcal{A}, μ, T) satisfies properties (P1) and (P2) then for any $n \geq 2$, T_*^n has the same ergodic self-joinings as T_* . In particular, T_*^n is \mathcal{PaP} .*

Proof. First observe that T_*^n is an ergodic Poisson suspension. Indeed, T^n is a conservative infinite measure preserving automorphism of (X, \mathcal{A}, μ) without T^n -invariant set of finite measure: otherwise, if A satisfied $T^n A = A$ with $\mu(A) < +\infty$, then $\bigcup_{k=1}^n T^k A$ would be a T -invariant set of finite measure, which is impossible.

As $C(T_*)$ is reduced to the powers of T_* , $\overline{\langle T_*^n \rangle} = \{T_*^{kn}, k \in \mathbb{Z}\}$ and $\overline{\langle T_*, T_*^n \rangle} = \{T_*^k, k \in \mathbb{Z}\}$, hence the quotient is finite.

To apply Lemma 4.19, it only remains to check that $J_2^e(T_*) \subset J_2^e(T_*^n)$. Of course, an ergodic self-joining of T_* is a self-joining of T_*^n , but we have to prove it is ergodic. By the \mathcal{PaP} property for T_* , an ergodic self-joining of T_* is Poisson, and thus it is a Poisson self-joining of T_*^n . But a Poisson self-joining of an ergodic suspension is itself ergodic, and therefore we have the desired inclusion $J_2^e(T_*) \subset J_2^e(T_*^n)$. \square

Proposition 4.21. *Assume that properties (P1) and (P2) hold for T . Then the Poisson suspension*

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*)$$

is \mathcal{PaP} .

Proof. We denote by \mathcal{N} the Poisson process of intensity $\mu \otimes \lambda$ on $X \times \mathbb{R}_+$. We approach this process by a sequence of Poisson processes discretized on the second coordinate. For each $n \geq 1$, we consider the application π_n defined on $X \times \mathbb{R}_+$ by

$$\pi_n(x, t) := (x, \lfloor 2^n t \rfloor 2^{-n}).$$

Then, we set $\mathcal{N}_n := (\pi_n)_*(\mathcal{N})$, which is a Poisson process on $X \times \mathbb{R}_+$, with intensity $\mu \otimes \left(\sum_{j \geq 0} 2^{-n} \delta_{j2^{-n}}\right)$. It is therefore concentrated on a countable union of disjoint copies of X , which are the sets $X \times \{j2^{-n}\}$, $j \geq 0$.

Now observe that the following convergence holds everywhere on $(X \times \mathbb{R}_+)_*$: for any continuous function $f : X \times \mathbb{R}_+ \rightarrow \mathbb{R}$, vanishing outside a bounded set,

$$\int f d\mathcal{N}_n \xrightarrow{n \rightarrow \infty} \int f d\mathcal{N}.$$

By the dominated convergence theorem,

$$\mathbb{E} \left[\exp \left(- \int f d\mathcal{N}_n \right) \right] \xrightarrow{n \rightarrow \infty} \mathbb{E} \left[\exp \left(- \int f d\mathcal{N} \right) \right].$$

This is enough to prove the weak convergence of the distribution of \mathcal{N}_n to the distribution of \mathcal{N} (see [6], Proposition 11.1.VIII).

Now consider an ergodic self-joining γ of

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*),$$

and denote by \mathcal{N} and $\overline{\mathcal{N}}$ the corresponding Poisson processes, with joint distribution γ . We set \mathcal{N}_n as above, and $\overline{\mathcal{N}}_n := (\pi_n)_*(\overline{\mathcal{N}})$. By the same arguments as above, we prove that the joint distribution γ_n of $(\mathcal{N}_n, \overline{\mathcal{N}}_n)$ converges weakly to γ . Note that γ_n is a self-joining of order 2 of the Poisson suspension of intensity $\mu \otimes \left(\sum_{j \geq 0} 2^{-n} \delta_{j2^{-n}}\right)$, but it can also be interpreted as an infinite ergodic self-joining of the Poisson suspension $(X^*, \mathcal{A}^*, (2^{-n}\mu)^*, T_*)$. As such, by Theorem 4.7, it is a Poisson joining. Then by Proposition 4.4, γ_n is infinitely divisible. By

Proposition 11.2.II in [6], infinite divisibility is closed under weak convergence of distributions, hence γ is also infinitely divisible. We conclude by Proposition 4.4 that γ is a Poisson joining. \square

Remark 4.22. *In fact it is possible to strengthen the above proposition by proving that the considered Poisson suspension is $\mathcal{PaP}(\infty)$, and moreover that all its finite or countable ergodic self-joinings are factors of itself.*

Applying Propositions 4.16 and 4.17, we get the following result.

Corollary 4.23. *The factors corresponding to countable self-joinings in Theorem 4.7 are actually \mathcal{PaP} Poisson factors.*

4.5. Non-disjointness, factors and distal extension. Furstenberg, when introducing joinings and disjointness in [10], asked whether two non-disjoint systems always possess a non-trivial common factor. In [23], this was shown to be false by Rudolph. However, all counterexamples to Furstenberg's question known so far have the property that one of the two non-disjoint system is a factor of a distal extension of the other one. (For definition and properties of distal extensions, we refer *e.g.* to [11], Chapter 10.) This led Lemańczyk to ask whether the latter property always holds for two non-disjoint systems [15]. Actually, our Poisson suspensions provide a new counterexample to Furstenberg's question, which also answer Lemańczyk's question negatively. Recall that, for any $\alpha > 0$, we denote by $T_*^{(\alpha)}$ the Poisson suspension $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$.

Proposition 4.24. *Assume that properties (P1) and (P2) hold for T . Then for any $\alpha \neq \beta$, $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are prime and not disjoint. However, $T_*^{(\alpha)}$ is never a factor of a distal extension of $T_*^{(\beta)}$.*

Lemma 4.25. *If $\alpha \neq \beta$, $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are not isomorphic.*

Proof. Assume that $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are isomorphic. Then there exists an ergodic joining of these systems which is supported on the graph of an isomorphism. In this joining, we can find two Poisson T -point processes N_α and N_β , of respective intensity $\alpha\mu$ and $\beta\mu$, each of them generating the whole σ -algebra. Then, by Lemma 4.6, there exist independent Poisson T -point processes N_α^∞ , N_β^∞ and N_α^k , $k \in \mathbb{Z}$, which are all measurable with respect to N_β (and also with respect to N_α), such that

$$N_\alpha = N_\alpha^\infty + \sum_{k \in \mathbb{Z}} N_\alpha^k,$$

and

$$N_\beta = N_\beta^\infty + \sum_{k \in \mathbb{Z}} T_*^k(N_\alpha^k).$$

Then N_α^∞ is both measurable with respect to N_β , and independent of it because it is independent of the family $(N_\beta^\infty, N_\alpha^k, k \in \mathbb{Z})$. It follows that $N_\alpha^\infty = 0$ a.s. For the same reason, $N_\beta^\infty = 0$ a.s., and we get that the intensities of N_α and N_β coincide, *i.e.* $\alpha = \beta$. \square

Proof of Proposition 4.24. We already know from Theorem 4.18 that the Poisson suspensions $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are prime. Let us see why they are not disjoint. Assume without loss of generality that $0 < \alpha \leq \beta$. In the direct product of $T_*^{(\alpha)}$ and $T_*^{(\beta-\alpha)}$, we have two independent Poisson T -point processes N_α and $N_{\beta-\alpha}$, of

respective intensities $\alpha\mu$ and $(\beta - \alpha)\mu$. Then $N_\alpha + N_{\beta-\alpha}$ is a Poisson T -point process of intensity $\beta\mu$, which is not independent of N_α . Hence the distribution of $(N_\alpha, N_\alpha + N_{\beta-\alpha})$ is a joining of $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ which is not the product measure.

Now, assume there exists an ergodic map S such that $S \rightarrow T_*^{(\beta)}$ is a distal extension and $T_*^{(\alpha)}$ is a factor of S . Then $T_*^{(\beta)} \vee T_*^{(\alpha)}$ appears as an ergodic joining and a factor of S . By Proposition 4.23, the joining is also a $\mathcal{P}a\mathcal{P}$ suspension. Then $T_*^{(\beta)}$ is a Poisson factor of $T_*^{(\beta)} \vee T_*^{(\alpha)}$ and as such the extension $T_*^{(\beta)} \vee T_*^{(\alpha)} \rightarrow T_*^{(\beta)}$ is relatively weakly mixing by Proposition 4.13. Therefore we have the following sequence of extensions

$$S \rightarrow T_*^{(\beta)} \vee T_*^{(\alpha)} \rightarrow T_*^{(\beta)}$$

But, as the extension $S \rightarrow T_*^{(\beta)}$ is distal, $T_*^{(\beta)} \vee T_*^{(\alpha)} \rightarrow T_*^{(\beta)}$ cannot be relatively weakly mixing unless it is an isomorphism (see Proposition 10.14 in [11]). Then this implies that $T_*^{(\alpha)}$ is a factor of $T_*^{(\beta)}$. Since the latter is prime by Theorem 4.18, $T_*^{(\alpha)}$ and $T_*^{(\beta)}$ are isomorphic. But by Lemma 4.25, this happens only if $\alpha = \beta$. \square

5. DISJOINTNESS RESULTS

5.1. General results.

Definition 5.1. A measurable law of large numbers for a conservative, ergodic, measure preserving dynamical system (X, \mathcal{A}, μ, T) is a measurable function $L : \{0, 1\}^{\mathbb{N}} \rightarrow [0, \infty]$ such that for all $B \in \mathcal{A}$, for μ -almost every $x \in X$,

$$L(1_B(x), 1_B(Tx), \dots) = \mu(B).$$

Lemma 5.2. Let (X, \mathcal{A}, μ, T) be a conservative, ergodic, measure preserving dynamical system, and assume that it admits a measurable law of large numbers. Let \mathcal{L} be a σ -finite factor of the product dynamical system

$$(X \times \mathbb{R}_+, \mathcal{A} \otimes \mathcal{B}, \mu \otimes \lambda, T \times \text{Id}).$$

Then there exists $C \subset \mathbb{R}_+$ with $0 < \lambda(C) < \infty$, such that $X \times C \in \mathcal{L}$.

Proof. Since \mathcal{L} is σ -finite, there exists $B \in \mathcal{L}$ such that $0 < \mu \otimes \lambda(B) < \infty$. For each $t \in \mathbb{R}_+$, let us consider

$$B_t := \{x \in X : (x, t) \in B\}.$$

Denote by L a measurable law of large numbers for (X, \mathcal{A}, μ, T) . Then, for $\mu \otimes \lambda$ -almost every $(x, t) \in X \times \mathbb{R}_+$, we have

$$L\left(\left(1_B(T^k x, t)\right)_{k \geq 0}\right) = \mu(B_t).$$

This ensures that the map $(x, t) \mapsto \mu(B_t)$ is \mathcal{L} -measurable. In particular, for any $\varepsilon > 0$, the set $\{(x, t) : \mu(B_t) \geq \varepsilon\}$ is \mathcal{L} -measurable. This set is of the form $X \times C$ for $C \subset \mathbb{R}_+$. We have

$$\infty > \mu \otimes \lambda(B) = \int_{\mathbb{R}_+} \mu(B_t) d\lambda(t) \geq \varepsilon \lambda(C),$$

and choosing ε small enough, we have $\lambda(C) > 0$. \square

Definition 5.3. A conservative, ergodic, measure preserving dynamical system (X, \mathcal{A}, μ, T) is rationally ergodic if there exists a set $B \in \mathcal{A}$, $0 < \mu(B) < \infty$, and a constant $M > 0$ such that, for any $n \geq 1$,

$$\int_B \left(\sum_{0 \leq j \leq n-1} 1_{B(T^j x)} \right)^2 d\mu(x) \leq M \left(\int_B \sum_{0 \leq j \leq n-1} 1_{B(T^j x)} d\mu(x) \right)^2.$$

According to Theorem 3.3.1 in [1], a measurable law of large numbers exists for T as soon as T is rationally ergodic, which is the case of Chacon infinite transformation (see [4]). Observe however that properties (P1) and (P2) alone imply the existence of a law of large numbers, but it happens that the question of its measurability remains open without rational ergodicity.

The following proposition applies therefore to the case of the Poisson suspension over Chacon infinite transformation.

Proposition 5.4. Assume that properties (P1) and (P2) hold for T , and that T admits a measurable law of large numbers. If a system (Y, \mathcal{B}, ν, S) is not disjoint from some n -order ergodic self-joining of $(X^*, \mathcal{A}^*, \mu^*, T_*)$, then it possesses $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ as a factor, for some $\alpha > 0$.

Proof. From a result of [16], if (Y, \mathcal{Y}, ν, S) is not disjoint from an ergodic n -order self-joining of $(X^*, \mathcal{A}^*, \mu^*, T_*)$, then it possesses a common non trivial factor with a countably infinite self-joining of it. However, an ergodic countably infinite self-joining of this n -order self-joining is nothing else than an ergodic countably infinite self-joining of $(X^*, \mathcal{A}^*, \mu^*, T_*)$. This common factor is therefore a factor of $((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*)$ by Theorem 4.7. Since the latter suspension is $\mathcal{P}a\mathcal{P}$ by Proposition 4.21, this factor itself contains a Poisson factor of $(\mathcal{A} \otimes \mathcal{B})^*$ by Proposition 4.11. Therefore there exists a $(T \times \text{Id})$ -invariant subset $L \subset X \times \mathbb{R}_+$ and a σ -finite factor \mathcal{L} of the restricted system such that we have the following factor relationship:

$$\begin{array}{c} (Y, \mathcal{Y}, \nu, S) \\ \downarrow \\ (L^*, \mathcal{L}^*, (\mu \otimes \lambda)|_L^*, (T \times \text{Id})_*). \end{array}$$

Using Lemma 5.2, we get the existence of $C \subset \mathbb{R}_+$, with $0 < \lambda(C) < \infty$, such that $X \times C \in \mathcal{L}$. Passing if necessary to another factor, we can therefore assume that L is of the form $X \times C$, with $0 < \lambda(C) < \infty$.

Observe now that the dynamical system $(L, \mathcal{A} \otimes \mathcal{B}|_C, \mu \otimes \lambda|_C, T \times \text{Id})$ admits both systems $(L, \mathcal{L}, \mu \otimes \lambda|_C, T \times \text{Id})$ and $(X, \mathcal{A}, \lambda(C)\mu, T)$ as factors. It therefore defines a joining of these systems, and by Proposition 5.5 in [12], $(X, \mathcal{A}, \lambda(C)\mu, T)$ is a factor of $(L, \mathcal{L}, \mu \otimes \lambda|_C, T \times \text{Id})$.

Passing to Poisson suspensions and going up the chain of factors up to (Y, \mathcal{Y}, ν, S) , we obtain our result. \square

Proposition 5.5. Assume that properties (P1) and (P2) hold for T , and that T admits a measurable law of large numbers. If a system (Y, \mathcal{Y}, ν, S) is disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$, then it is disjoint from $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ for any $\alpha > 0$.

Proof. Assume (Y, \mathcal{Y}, ν, S) is disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$, but that there exists $\alpha > 0$ such that it is not disjoint from $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$. Thanks to Proposition 5.4, there exists $\beta > 0$ such that $(X^*, \mathcal{A}^*, (\beta\mu)^*, T_*)$ is a factor of (Y, \mathcal{Y}, ν, S) (and $\beta \neq 1$ by assumption). This means that there exists a Poisson T -point process N_1 of intensity $\beta\mu$ defined on (Y, \mathcal{Y}, ν, S) .

If $\beta < 1$, let us consider the direct product

$$(Y \times X^*, \mathcal{Y} \otimes \mathcal{A}^*, \nu \otimes ((1 - \beta)\mu)^*, S \times T_*).$$

In this product, there exists a Poisson T -point process N_2 of intensity $(1 - \beta)\mu$ independent of the whole system (Y, \mathcal{Y}, ν, S) . In particular, N_1 and N_2 are independent, thus $N_1 + N_2$ defines a Poisson T -point process of intensity μ , which is independent of (Y, \mathcal{Y}, ν, S) by disjointness. This is absurd, as this would imply that N_1 and $N_1 + N_2$ are independent. This is obviously false, since $N_1 \leq N_1 + N_2$.

If $\beta > 1$, observe that $(X^*, \mathcal{A}^*, (\beta\mu)^*, T_*)$ is both a factor of (Y, \mathcal{Y}, ν, S) and of the direct product

$$(X^* \times X^*, \mathcal{A}^* \otimes \mathcal{A}^*, \mu^* \otimes ((\beta - 1)\mu)^*, T_* \times T_*).$$

In this product, we have two Poisson T -point processes N_3 and N_4 of respective intensities μ and $(\beta - 1)\mu$, such that $N_3 + N_4$ is a Poisson T -point process of intensity $\beta\mu$ that corresponds to the factor $(X^*, \mathcal{A}^*, (\beta\mu)^*, T_*)$. We can then form the relatively independent joining of (Y, \mathcal{Y}, ν, S) and this direct product over $(X^*, \mathcal{A}^*, (\beta\mu)^*, T_*)$. In this scheme, we have $N_1 = N_3 + N_4$ almost surely, hence $N_3 + N_4$ is measurable with respect to the σ -algebra \mathcal{Y} . But N_3 is independent of \mathcal{Y} by disjointness, leading to the same contradiction that N_3 is independent of $N_3 + N_4$. \square

Proposition 5.6. *Assume that properties (P1) and (P2) hold for T , and that T admits a measurable law of large numbers. If a system (Y, \mathcal{Y}, ν, S) is disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$, then it is disjoint from any self-joining (of any order) of this Poisson suspension.*

Proof. If there exists a self-joining of $(X^*, \mathcal{A}^*, \mu^*, T_*)$ not disjoint from (Y, \mathcal{Y}, ν, S) , then, by Proposition 5.4, (Y, \mathcal{Y}, ν, S) possesses $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ as a factor, for some $\alpha > 0$. However, by Proposition 5.5, this implies that (Y, \mathcal{Y}, ν, S) is not disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$. \square

Corollary 5.7. *Assume that properties (P1) and (P2) hold for T , and that T admits a measurable law of large numbers. A system (Y, \mathcal{Y}, ν, S) is disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$ if and only if it is disjoint from*

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*).$$

Proof. First observe that we can view

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*)$$

as the inverse limit of the direct products

$$\left((X^*)^{2^{2n}}, (\mathcal{A}^*)^{\otimes 2^{2n}}, \left(\left(\frac{1}{2^n} \mu \right)^* \right)^{\otimes 2^{2n}}, (T_*)^{\times 2^{2n}} \right)$$

as n tends to infinity. Assume that (Y, \mathcal{Y}, ν, S) is disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$. Then by Proposition 5.5, it is disjoint from $(X^*, \mathcal{A}^*, (\frac{1}{2^n} \mu)^*, T_*)$, and by Proposition 5.6, it is also disjoint from any self-joining of this system. Then, passing to the inverse limit, we conclude that it is also disjoint from

$$((X \times \mathbb{R}_+)^*, (\mathcal{A} \otimes \mathcal{B})^*, (\mu \otimes \lambda)^*, (T \times \text{Id})_*).$$

The converse is obvious since the above system admits $(X^*, \mathcal{A}^*, \mu^*, T_*)$ as a factor. \square

5.2. Disjointness from classical classes of dynamical systems. There already exist general disjointness results that concern Poisson suspensions: it is proved in [17] that Poisson suspensions are disjoint from transformations that enjoy the *joining primeness property*, such as distally simple transformations. We can nevertheless obtain stronger disjointness results for the suspensions we are interested in.

Theorem 5.8. *If T satisfies properties (P1) and (P2), and admits a measurable law of large numbers, then $(X^*, \mathcal{A}^*, \mu^*, T_*)$ is disjoint from any rank one transformation.*

Proof. If a rank one transformation is not disjoint from $(X^*, \mathcal{A}^*, \mu^*, T_*)$, then by Proposition 5.4 it possesses $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ as a factor for some $\alpha > 0$. But a factor of a rank one transformation is also of rank one.

On the other hand, $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ is mildly mixing thanks to Theorem 4.18, and we know from Proposition 11 in [19] that a non-rigid Poisson suspension is not of rank one. \square

Remark 5.9. *According to Ryzhikov [24], a non-rigid Poisson suspension is in fact not even of local rank one. Thus the above theorem extends to local rank one transformations.*

We now turn to disjointness from Gaussian dynamical system, about which we first recall a few facts. A dynamical system $(\Omega, \mathcal{F}, \mathbb{P}, S)$ is said to be *standard Gaussian* if there exists some measurable function f of zero mean defined on Ω such that $X_n := f \circ S^n$ defines a Gaussian stationary process that generates \mathcal{F} . Up to measurable isomorphism, such a dynamical system is completely identified by the spectral measure σ of f on \mathbb{T} :

$$\langle X_0, X_n \rangle_{L^2(\mathbb{P})} = \widehat{\sigma}(n).$$

As in the Poisson case, $L^2(\mathbb{P})$ admits a Fock space representation

$$L^2(\mathbb{P}) \simeq \mathbb{C} \oplus L^2(\sigma) \oplus L^2(\sigma)^{\odot 2} \oplus \dots \oplus L^2(\sigma)^{\odot n} \oplus \dots$$

Therefore, $L^2(\mathbb{P})$ admits a decomposition into (Gaussian) chaos $\{C_n\}_{n \geq 0}$ and the maximal spectral type of U_S on C_n is σ^{*n} . (For a detailed presentation of the spectral analysis of Gaussian dynamical systems, we refer *e.g.* to [3], Chapter 14.)

A particularly interesting situation for us arises when a Gaussian system (or a Poisson suspension) has simple spectrum. Indeed, it then enjoys the following property, presented in the form of a proposition which can be found in a more general form in [14]:

Proposition 5.10. *If a standard Gaussian dynamical system (resp. a Poisson suspension) has simple spectrum, then for any pair m_1, m_2 of continuous measures*

on \mathbb{T} , the spectral measure σ of the Gaussian process (resp. the maximal spectral type of the base of the suspension) satisfies $\sigma \perp m_1 * m_2$.

As an application, we get the following result which will be useful for our purposes:

Proposition 5.11. *A Poisson suspension is never a factor of a standard Gaussian dynamical system with simple spectrum.*

Proof. Assume that (Y, \mathcal{B}, ν, S) is a standard Gaussian with simple spectrum, and that it admits the Poisson suspension $(Z^*, \mathcal{C}^*, \rho^*, R_*)$ as a factor. Let η be the spectral measure of the generating Gaussian process, and let σ be the maximal spectral type of $(Z, \mathcal{C}, \rho, R)$, which is also the maximal spectral type of the action of U_{R^*} on the first Poissonian chaos of the suspension. Since R^* has simple spectrum (as a factor of the simple spectrum system S) Proposition 5.10 applies to σ . Now, take $f \neq 0$ in the first Poissonian chaos of the suspension: its spectral measure is absolutely continuous with respect to σ , and by Proposition 5.10, it is singular with respect to η^{*n} for any $n \geq 2$. Identifying $L^2(\rho^*)$ with a subspace of $L^2(\nu)$, we conclude that f has to be in the first Gaussian chaos of $L^2(\nu)$. But this is impossible, because the first Gaussian chaos contains exclusively (complex) Gaussian random variables, whereas the first Poissonian chaos of a suspension contains no such variables, the zero vector aside (see e.g. [21]). \square

Now we can state and prove the following result on disjointness between our Poisson suspensions and standard Gaussian dynamical systems:

Theorem 5.12. *If T satisfies properties (P1) and (P2), and admits a measurable law of large numbers, then $(X^*, \mathcal{A}^*, \mu^*, T_*)$ is disjoint from any standard Gaussian system.*

Proof. Let (Y, \mathcal{B}, ν, S) a standard Gaussian, and assume it is not disjoint from $(X, \mathcal{A}^*, \mu^*, T_*)$. Applying Proposition 5.4, we get the existence of a factor sub- σ -algebra $\mathcal{C} \subset \mathcal{B}$ such that the action of S on \mathcal{C} is isomorphic to $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ for some $\alpha > 0$. As in the proof of Proposition 17 in [16], there exists $S' \in C(S)$ which is a standard Gaussian system with simple spectrum. Set $\mathcal{C}' := \bigvee_{n \in \mathbb{Z}} S'^{-n} \mathcal{C}$, then \mathcal{C}' is a factor σ -algebra of S' . Observe that for any $n \in \mathbb{Z}$, $S'^{-n} \mathcal{C}$ is also a factor σ -algebra of S , and that the action of S on $S'^{-n} \mathcal{C}$ is also isomorphic to $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$. It follows that the action of S on $\bigvee_{n \in \mathbb{Z}} S'^{-n} \mathcal{C}$ defines an ergodic countable self-joining of $(X^*, \mathcal{A}^*, (\alpha\mu)^*, T_*)$ and, as such, is isomorphic to a \mathcal{PaP} suspension $(Z^*, \mathcal{Z}^*, \rho^*, T_*^\infty)$ by Corollary 4.23. It follows that $S'_{|\mathcal{C}'}$ can be considered as an element of $C(T_*^\infty)$, but since the suspension is \mathcal{PaP} , from Proposition 4.10, $S'_{|\mathcal{C}'} = R_*$ for some automorphism R of (Z, \mathcal{Z}, ρ) commuting with T^∞ . Then we get the Poisson suspension R^* as a factor of the standard Gaussian dynamical system S' which has simple spectrum, and this contradicts Proposition 5.11. \square

6. NON-ABELIAN GROUP ACTIONS

So far we have only considered \mathbb{Z} -actions of a single transformation. Assume now that we are given a measure preserving action $T := (T_g)_{g \in G}$ of a countable discrete group G on (X, \mathcal{A}, μ) . Taking advantage of the possibility of non-commutativity we can strengthen property (P2): if T contains an element T_{g_1} satisfying properties (P1) and (P2) and a transformation T_{g_2} that does not commute with any $T_{g_1}^n$, $n \neq 0$, then the action satisfies

(P2') For each $n \geq 1$, if σ is a boundedly finite, $T^{\times n}$ -invariant measure on X^n , whose marginals are absolutely continuous with respect to μ , then σ is conservative, and its ergodic components are all of the form m_π for some $\pi \in \mathcal{P}_n$.

This allows to obtain:

Theorem 6.1. *If T contains an element T_{g_1} satisfying properties (P1) and (P2) and a transformation T_{g_2} that does not commute with any $T_{g_1}^n$, $n \neq 0$, then an ergodic T -point process with moments of all orders is a Poisson point process of intensity $\alpha\mu$ for some $\alpha > 0$.*

Proof. The proof is a straightforward adaptation of Theorem 3.1 for T_{g_1} , with the noteworthy difference that the point process does not need to be assumed T_{g_1} -free. Indeed, the T -free assumption in Theorem 3.1 was requested to ensure that, in the ergodic decomposition of the moment measures, the contribution of non trivial m_π^κ ($\kappa \neq (0, \dots, 0)$) vanishes. But by property (P2'), no other measures than the trivial ones can appear, and the result follows. \square

As a consequence we get a “unique ergodicity” statement which might be not new, however we have not been able to find any reference.

Corollary 6.2. *The only distribution on (X^*, \mathcal{A}^*) with moments of all orders and intensity μ which is invariant by every transformation T_* , $T \in \text{Aut}(X, \mathcal{A}, \mu)$, is μ^* .*

7. CONCLUSION

Our work raises several questions, among which a natural one is the following: is it possible to obtain the same results, assuming only moments of order 2 for the point process? We can also ask ourselves whether we could obtain similar results with the base transformation T having uncountably many ergodic self-joinings (for example with an uncountable centralizer)? This would require very different techniques, as our proofs strongly rely on the fact that T possesses a countable set of ergodic self-joinings. More generally, it would be interesting to know if the $\mathcal{P}a\mathcal{P}$ property is widespread among Poisson suspensions, or if it is a rare feature.

At last, we want to mention that a subsequent paper will deal with the general case where random measures are no longer assumed to be simple point processes (*i.e.* with randomly weighted particles or even with a continuous part).

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