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Backward Bifurcation and Control in Transmission Dynamics of Arboviral Diseases

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Abstract

In this paper, we derive and analyse a compartmental model for the control of arboviral diseases which takes into account an imperfect vaccine combined with individual protection and some vector control strategies already studied in the literature. After the formulation of the model, a qualitative study based on stability analysis and bifurcation theory reveals that the phenomenon of backward bifurcation may occur. The stable disease-free equilibrium of the model coexists with a stable endemic equilibrium when the reproduction number, R_0 , is less than unity. Using Lyapunov function theory, we prove that the trivial equilibrium is globally asymptotically stable; When the disease-induced death is not considered, or/and, when the standard incidence is replaced by the mass action incidence, the backward bifurcation does not occur. Under a certain condition, we establish the global asymptotic stability of the disease-free equilibrium of the full model. Through sensitivity analysis, we determine the relative importance of model parameters for disease transmission. Numerical simulations show that the combination of several control mechanisms would significantly reduce the spread of the disease, if we maintain the level of each control high, and this, over a long period.

Keywords: Compartmental model, Arboviral diseases, Vaccination, Vector control strategies, Stability, Backward bifurcation, Sensitivity analysis.

AMS Subject Classification (2010): 34D20, 34D23, 37N25, 92D30.

1 Introduction

Arboviral diseases are affections transmitted by hematophagous arthropods. There are currently 534 viruses registered in the International Catalog of Arboviruses and 25% of them have caused documented illness in human populations [1, 2, 3]. Examples of those kinds of diseases are Dengue, Yellow fever, Saint Louis fever, Encephalitis, West Nile fever and Chikungunya. A wide range of arbovirus diseases are transmitted by mosquito bites and constitute a public health emergency of international concern. According to WHO, Dengue, caused by any of four closely-related virus serotypes (DEN-1-4) of the genus Flavivirus, causes 50–100 million infections worldwide every year, and the majority of patients worldwide are children aged 9 to 16 years [4, 5, 6]. The dynamics of arboviral diseases like Dengue or Chikungunya are influenced by many factors such as human and mosquito behaviour, the virus itself, as well as the environment which directly or indirectly affects all the present mechanisms of control.

For all mentioned diseases, only yellow fever has a licensed vaccine. Nevertheless, considerable efforts are made to obtain the vaccines for other diseases. In the case of Dengue for

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example, the scientists of French laboratory SANOFI have conducted different trials in Latin America and Asia. Thus, a tetravalent vaccine could be quickly set up in the coming months. But in any case, it is clear that this vaccine will be imperfect. However, the trials in Latin America have shown that vaccine efficacy was 64.7%. Serotype-specific vaccine efficacy was 50.3% for serotype 1, 42.3% for serotype 2, 74.0% for serotype 3, and 77.7% for serotype 4 [7]. The trials in Asia have shown that efficacy was 30.2%, and differed by serotype [8].

Host-vector models for arboviral diseases transmission were proposed in [9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26] with the focus on the construction of the basic reproductive ratio and related stability analysis of the disease free and endemic equilibria. Some of these works in the literature focus on modeling the spread of arboviral diseases and its control using some mechanism of control like imperfect vaccines [19, 20, 26] and other control tools like individual protection and vector control strategies [9, 10, 15, 21, 23, 24].

In [15], Dumont and Chiroleu proposed a compartmental model to study the impact of vector control methods used to contain or stop the epidemic of Chikungunya of 2006 in Réunion island. Moulay et al. [23] study an optimal control based on protection and vector control strategies to fight against Chikungunya. In [20], Rodrigues et al. simulate an hypothetical vaccine as an extra protection to the human population against epidemics of Dengue, using the optimal control. In these models [15, 20, 23],

- (i) the population is constant,
- (ii) the disease-induced death in humans is not considered,
- (iii) the complete stage progression of development of vectors is not considered,
- (iv) none of the above mentioned models takes into account the combination of the mechanisms of control already studied in the literature, such as vaccination, individual protection and vector control strategies (destruction of breeding site, eggs and larvae reduction).

The aim of this work is to propose and study a arboviral disease control model which takes into account human immigration, disease-induced mortality in human communities, the complete stage structured model for vectors and a combination of human vaccination, individual protection and vector control strategies to fight against the spread of these kind of diseases.

We start with the formulation of the constant control model, which is an extension of the previous model developed in [26]. We include the complete stage progression of development of vectors, the waning vaccine, and four other continuous controls (individual protection, using adulticides, the mechanical control, Eggs and larvae reduction). We compute the net reproductive number \mathcal{N} , as well as the basic reproduction number, \mathcal{R}_0 , and investigate the existence and stability of equilibria. We prove that the trivial equilibrium is globally asymptotically stable whenever $\mathcal{N} < 1$. When $\mathcal{N} > 1$ and $\mathcal{R}_0 < 1$, we prove that the system exhibit the backward bifurcation phenomenon. The implication of this occurrence is that the classical epidemiological requirement for effective eradication of the disease, $\mathcal{R}_0 < 1$, is no longer sufficient, even though necessary. However considering two situations: the model without vaccination and the model with mass incidence rates, we prove that the disease-induced death and the standard incidence functions, respectively, are the main causes of the occurrence of backward bifurcation. We found that the disease-free equilibrium is globally asymptotically stable under certain condition. Through local and global sensitivity analysis, we determine the relative importance parameters of the model on the disease transmission. By using the pulse control technique in numerical simulations, we evaluate the impact of different controls combinations on the decrease of the spread of these diseases.

The paper is organized as follows. In Section 2 we present the transmission model and in Section 3 we carry out some analysis by determining important thresholds such as the net reproductive number \mathcal{N} and the basic reproduction number \mathcal{R}_0 , and different equilibria of the model. We then demonstrate the stability of equilibria and carry out bifurcation analysis. In section 4, both local and global sensitivity analysis are used to assess the important parameters in the spread of the diseases. Section 5 is devoted to numerical simulations and discussion. A conclusion rounds up the paper.

2 The formulation of the model

The model we propose here is an extension of the previous model studied in [26], and is based on the modelling approach given in [15, 16, 17, 18, 19, 23, 24]. It is assumed that the human and vector populations are divided into compartments described by time-dependent state variables. The compartments in which the populations are divided are the following ones:

–For humans, we consider susceptible (denoted by S_h), vaccinated (V_h), exposed (E_h), infectious (I_h) and resistant or immune (R_h); So that, $N_h = S_h + V_h + E_h + I_h + R_h$. Following Garba et al. [19] and Rodrigues et al. [20], we assume that the immunity, obtained by the vaccination process, is temporary. So, the immunity has the waning rate ω . The recruitment in human population is at the constant rate Λ_h , and newly recruited individuals enter the susceptible compartment S_h . Are concerned by recruitment people that are totally naive from the disease. Each individual human compartment goes out from the dynamics at natural mortality rates μ_h . The human susceptible population is decreased following infection, which can be acquired via effective contact with an exposed or infectious vector at a rate $\lambda_h = \frac{a\beta_{hv}(\eta_v E_v + I_v)}{N_h}$ [19] where a is the biting rate per susceptible vector, β_{hv} is the transmission probability from an infected vector (E_v or I_v) to a susceptible human (S_h). The probability that a vector chooses a particular human or other source of blood to bite can be assumed as $\frac{1}{N_h}$.

Thus, a human receives in average $a\frac{N_v}{N_h}$ bites per unit of times. Then, the infection rate per susceptible human is given $a\beta_{hv}\frac{N_v}{N_h}\frac{(\eta_v E_v + I_v)}{N_v}$. In expression of λ_h , the modification parameter $0 < \eta_v < 1$ accounts for the assumed reduction in transmissibility of exposed mosquitoes relative to infectious mosquitoes [19] (see the references therein for the specific sources). Latent humans (E_h) become infectious (I_h) at rate γ_h . Infectious humans recover at a constant rate, σ or dies as consequence of infection, at a disease-induced death rate δ . Immune humans retain their immunity for life.

– Following [23], the stage structured model is used to describe the vector population dynamics, which consists of three main stages: embryonic (E), larvae (L) and pupae (P). Even if eggs (E) and immature stages (L and P) are both aquatic, it is important to dissociate them because, for control point of view, drying the breeding sites does not kill eggs, but only larvae and pupae. Moreover, chemical interventions on the breeding sites has impact on the larvae population, but not on the eggs [23]. The number of laid eggs is assumed proportional to the number of females. The system of stage structured model of aquatic phase development of

vector is given by (see [23] for details)

$$\begin{cases} \dot{E} &= \mu_b \left(1 - \frac{E}{\Gamma_E}\right) (S_v + E_v + I_v) - (s + \mu_E)E \\ \dot{L} &= sE \left(1 - \frac{L}{\Gamma_L}\right) - (l + \mu_L)L \\ \dot{P} &= lL - (\theta + \mu_P)P \end{cases}$$

Unlike the authors of [23], we take into account the pupal stage in the development of the vector. This is justified by the fact that they do not feed during this transitional stage of development, as they transform from larvae to adults. So, the control mechanisms can not be applied to them.

A rate, θ , of pupae become female Adults. Each individual vector compartment goes out from the dynamics at natural mortality rates μ_v . The vector susceptible population is decreased following infection, which can be acquired via effective contact with an exposed or infectious human at a rate $\lambda_v = \frac{a\beta_{vh}(\eta_h E_h + I_h)}{N_h}$ [19] where β_{vh} is the probability of transmission of infection from an infectious human (E_h or I_h) to a susceptible vector (S_v). Latent vectors (E_v) become infectious (I_v) at rate γ_v . The modification parameter $0 \leq \eta_h < 1$ accounts for the relative infectiousness of exposed humans in relation to infectious humans. Here too, it is assumed that susceptible mosquitoes can acquire infection from exposed humans [12, 19, 26]. The vector population does not have an immune class, since it is assumed that their infectious period ends with their death [17].

Then, we add new terms in the model to assess the different control tools studied:

(i) α_1 represents the efforts made to protect human from mosquitoes bites. It mainly consists to the use of mosquito nets or wearing appropriate clothing [24]. Thus we modify the infection term as follows:

$$\lambda_h^c = (1 - \alpha_1)\lambda_h, \quad \text{and} \quad \lambda_v^c = (1 - \alpha_1)\lambda_v, \text{ with } 0 \leq \alpha_1 < 1; \quad (1)$$

(ii) η_1 and η_2 are eggs and larvae mortality rates induced by chemical intervention respectively,

(iii) c_m is the additional mortality rate due to the adulticide,

(iv) α_2 is the parameter associated with the efficacy of the mechanical control.

The above assumptions lead to the following non-linear system of ordinary differential equations

$$\begin{cases} \dot{S}_h &= \Lambda_h + \omega V_h - (\lambda_h^c + \xi + \mu_h) S_h \\ \dot{V}_h &= \xi S_h - [(1 - \epsilon)\lambda_h^c + \omega + \mu_h] V_h \\ \dot{E}_h &= \lambda_h^c [S_h + (1 - \epsilon)V_h] - (\mu_h + \gamma_h)E_h \\ \dot{I}_h &= \gamma_h E_h - (\mu_h + \delta + \sigma)I_h \\ \dot{R}_h &= \sigma I_h - \mu_h R_h \\ \dot{S}_v &= \theta P - \lambda_v^c S_v - (\mu_v + c_m)S_v \\ \dot{E}_v &= \lambda_v^c S_v - (\mu_v + \gamma_v + c_m)E_v \\ \dot{I}_v &= \gamma_v E_v - (\mu_v + c_m)I_v \\ \dot{E} &= \mu_b \left(1 - \frac{E}{\alpha_2 \Gamma_E}\right) (S_v + E_v + I_v) - (s + \mu_E + \eta_1)E \\ \dot{L} &= sE \left(1 - \frac{L}{\alpha_2 \Gamma_L}\right) - (l + \mu_L + \eta_2)L \\ \dot{P} &= lL - (\theta + \mu_P)P \end{cases} \quad (2)$$

144 It is important to note that no intervention measure is performed to kill the pupae for two
 145 reasons: the first reason is the fact that at this stage, no food is absorbed by the insect, so it
 146 is impossible to make her ingest a toxic substance; the second reason is the fact that products
 147 soluble in water deposits by contact are not selective mosquito nymphs and act on all the
 148 wildlife of the cottage.

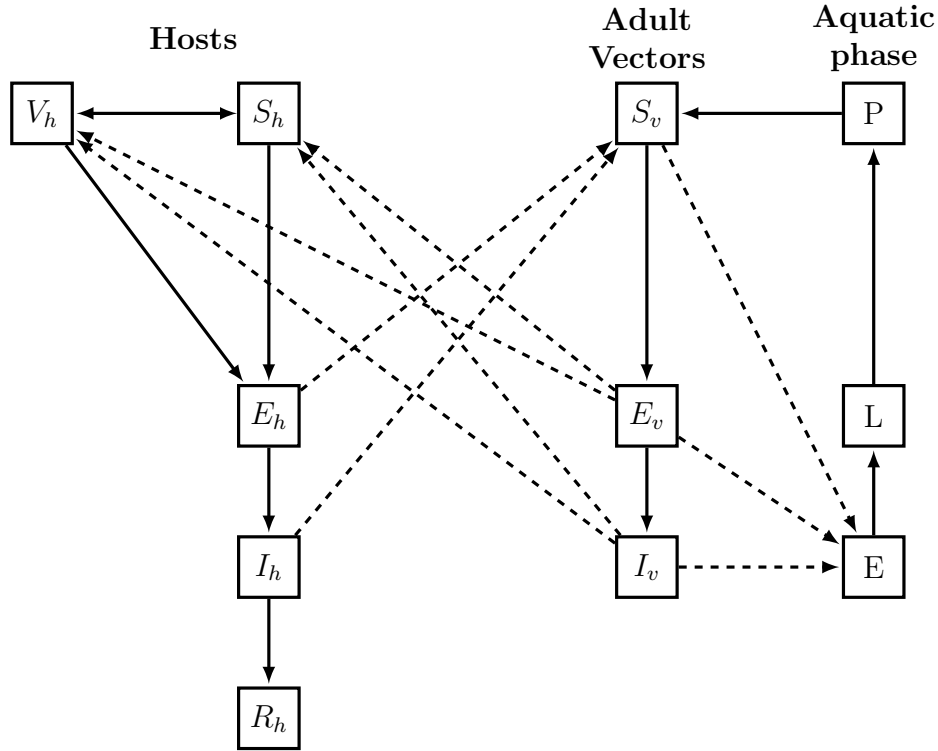


Figure 1: A compartmental model for the transmission dynamics of vector-borne diseases, which takes into account a waning vaccine and the complete phase of aquatic development of vector.

149 The description of state variables and parameters of model (2) are given in Tables 1–3.

Table 1: The state variables of model (2).

Humans		Vectors	
S_h :	Susceptible	E :	Eggs
V_h :	Vaccines	L :	Larvae
E_h :	Infected in latent stage	P :	Pupae
I_h :	Infectious	S_v :	Susceptible
R_h :	Resistant (immune)	E_v :	Infected in latent stage
		I_v :	Infectious

Table 2: Description and baseline values/range of parameters of model (2).

Par.	Description	Baseline value/range	Sources
Λ_h	Recruitment rate of humans	2.5 day^{-1}	[19]
μ_h	Natural mortality rate in humans	$\frac{\text{day}^{-1}}{(67 \times 365)}$	[19]
ξ	Vaccine coverage	Variable	
ω	Vaccine waning rate	Variable	
ϵ	The vaccine efficacy	Variable	
a	Average number of bites	1 day^{-1}	[9, 19]
β_{hv}	Probability of transmission of infection from an infectious human to a susceptible vector	$0.1, 0.75 \text{ day}^{-1}$	[9, 19]
γ_h	Progression rate from E_h to I_h	$[\frac{1}{15}, \frac{1}{3}] \text{ day}^{-1}$	[15, 27]
δ	Disease-induced death rate	10^{-3} day^{-1}	[19]
σ	Recovery rate for humans	0.1428 day^{-1}	[9, 19]
η_h, η_v	Modifications parameter	$[0, 1)$	[19]
μ_v	Natural mortality rate of vectors	$[\frac{1}{30}, \frac{1}{14}] \text{ day}^{-1}$	[9, 19]
γ_v	Progression rate from E_v to I_v	$[\frac{1}{21}, \frac{1}{2}] \text{ day}^{-1}$	[15, 27]
β_{vh}	Probability of transmission of infection from an infectious vector to a susceptible human	$0.1, 0.75 \text{ day}^{-1}$	[9, 19]
θ	Maturation rate from pupae to adult	0.08 day^{-1}	[15, 23, 24]
μ_b	Number of eggs at each deposit	6 day^{-1}	[15, 23, 24]
Γ_E	Carrying capacity for eggs	$10^3, 10^6$	[9, 23]
Γ_L	Carrying capacity for larvae	$5 \times 10^2, 5 \times 10^5$	[9, 23]
μ_E	Eggs death rate	0.2 or 0.4	[24]
μ_L	Larvae death rate	0.2 or 0.4	[24]
μ_P	Pupae death rate	0.4	Assumed

Table 3: Description and baseline values/range of parameters of model (2).

Par.	Description	Baseline value/range	Sources
s	Transfer rate from eggs to larvae	0.7 day^{-1}	[24]
l	Transfer rate from larvae to pupae	0.5 day^{-1}	[23]
η_1, η_2	Eggs and larvae mortality rates induced by chemical intervention	0.001, 0.3	[24]
α_1	Human protection rate	$[0, 1)$	
α_2	Efficacy of the mechanical control	$(0, 1]$	[15]
c_m	Adulticide killing rate	$[0, 0.8]$	[15]

2.1 Well posedness of the model

We now show that the system (2) is mathematically well defined and biologically feasible. We write

$$\begin{aligned} k_1 &:= \xi + \mu_h; \quad k_2 := \omega + \mu_h; \quad k_3 := \mu_h + \gamma_h; \quad k_4 := \mu_h + \delta + \sigma; \\ k_5 &:= s + \mu_E + \eta_1; \quad k_6 := l + \mu_L + \eta_2; \quad k_7 := \theta + \mu_P; \quad k_8 := \mu_v + c_m; \\ k_9 &:= \mu_v + \gamma_v + c_m; \quad K_E := \alpha_2 \Gamma_E; \quad K_L := \alpha_2 \Gamma_L; \quad \pi := 1 - \epsilon, \tau = a(1 - \alpha_1). \end{aligned} \quad (3)$$

System (2) can be rewritten in the following way

$$\frac{dX}{dt} = \mathbb{A}(X)X + F \quad (4)$$

with $X = (S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P)^T$, $\mathbb{A}(X) = \begin{pmatrix} A_1(X) & 0 \\ 0 & A_4(X) \end{pmatrix}$

with

$$A_1(X) = \begin{pmatrix} -\lambda_h^c - k_1 & \omega & 0 & 0 & 0 \\ \xi & -\pi\lambda_h^c - k_2 & 0 & 0 & 0 \\ \lambda_h & \pi\lambda_h & -k_3 & 0 & 0 \\ 0 & 0 & \gamma_h & -k_4 & 0 \\ 0 & 0 & 0 & \sigma & -\mu_h \end{pmatrix}$$

and

$$A_2(X) = \begin{pmatrix} -(\lambda_v^c + k_8) & 0 & 0 & 0 & 0 & \theta \\ \lambda_v & -k_9 & 0 & 0 & 0 & 0 \\ 0 & \gamma_v & -k_8 & 0 & 0 & 0 \\ A_{96} & A_{96} & A_{96} & -A_{97} & 0 & 0 \\ 0 & 0 & 0 & A_{109} & -A_{10} & 0 \\ 0 & 0 & 0 & 0 & l & -k_7 \end{pmatrix}$$

where $A_{96} = \mu_b \left(1 - \frac{E}{K_E}\right)$, $A_{97} = \left(\frac{\mu_b N_v}{K_E} + k_5\right)$, $A_{109} = s \left(1 - \frac{L}{K_L}\right)$ and $A_{10} = \frac{sE}{K_L} + k_6$;

and $F = (\Lambda_h, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0)^T$.

Note that $\mathbb{A}(X)$ is a Metzler matrix, i.e. a matrix such that off diagonal terms are non negative [28, 29], for all $X \in \mathbb{R}_+^{11}$. Thus, using the fact that $F \geq 0$, system (4) is positively invariant in \mathbb{R}_+^{11} , which means that any trajectory of the system starting from an initial state in the positive orthant \mathbb{R}_+^{11} , remains forever in \mathbb{R}_+^{11} . The right-hand side is Lipschitz continuous: there exists a unique maximal solution.

By adding the first four equations of model system (2), it follows that

$$\dot{N}_h(t) = \Lambda_h - \mu_h N_h - \delta I_h \leq \Lambda_h - \mu_h N_h$$

So that

$$0 \leq N_h(t) \leq \frac{\Lambda_h}{\mu_h} + \left(N_h(0) - \frac{\Lambda_h}{\mu_h}\right) e^{-\mu_h t}$$

Thus, at $t \rightarrow \infty$, $0 \leq N_h(t) \leq \frac{\Lambda_h}{\mu_h}$.

By adding the equations in S_v , E_v and I_v of system (2), it follows that

$$\dot{N}_v(t) = \theta P - \mu_v N_v$$

So that

$$0 \leq N_v(t) = \frac{\theta P}{\mu_v} + \left(N_v(0) - \frac{\theta P}{\mu_v}\right) e^{-\mu_v t}$$

Thus, at $t \rightarrow \infty$, $0 \leq N_v(t) \leq \frac{\theta l K_L}{\mu_v k_7}$ since $P \leq \frac{l K_L}{k_7}$.

Therefore, all feasible solutions of model system (2) enter the region:

$$\mathcal{D} = \left\{ (S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P) \in \mathbb{R}_+^{11} : N_h \leq \frac{\Lambda_h}{\mu_h}; E \leq K_E; L \leq K_L; P \leq \frac{l K_L}{k_7}; N_v \leq \frac{\theta l K_L}{k_7 k_8} \right\}$$

3 Mathematical analysis

In this section, we focus on the qualitative analysis of our model. We determine the different equilibrium points which are governed by two epidemiological thresholds, the net reproductive number denoted by \mathcal{N} and the basic reproduction number denoted by \mathcal{R}_0 . Then, dependent of the values of these thresholds, we study the stability (local as well as global) of the different equilibrium points, and also we test the occurrence of the backward bifurcation phenomenon. These stability analysis are also done for the different corresponding models, to determine the causes of the occurrence of backward bifurcation phenomenon.

3.1 The disease-free equilibria and its stability

In the absence of disease in the both population (human and Adult vector), i.e. $\lambda_h^c = \lambda_v^c = 0$ (or $E_h = I_h = E_v = I_v = 0$), we obtain two equilibria without disease: the trivial equilibrium (equilibrium without vector and disease) $\mathcal{E}_0 = (S_h^0, V_h^0, 0, 0, 0, 0, 0, 0, 0, 0, 0)$ and the disease-free equilibrium (equilibrium with vector and without disease) $\mathcal{E}_1 = (S_h^0, V_h^0, 0, 0, 0, N_v^0, 0, 0, E, L, P)$ with

$$\begin{aligned} S_h^0 &= \frac{\Lambda_h k_2}{\mu_h (k_2 + \xi)}, \quad V_h^0 = \frac{\xi \Lambda_h}{\mu_h (k_2 + \xi)}, \quad N_v^0 = \frac{K_E K_L k_5 k_6 (\mathcal{N} - 1)}{\mu_b (K_E s + k_6 K_L)}, \\ P &= \frac{K_E K_L k_5 k_6 k_8 (\mathcal{N} - 1)}{\mu_b \theta (K_E s + k_6 K_L)}, \quad L = \frac{K_E K_L k_5 k_6 k_7 k_8 (\mathcal{N} - 1)}{\mu_b \theta l (K_E s + k_6 K_L)}, \\ E &= \frac{K_E K_L k_5 k_6 k_7 k_8 (\mathcal{N} - 1)}{s (\mu_b l K_L \theta + k_5 k_7 k_8 K_E)}. \end{aligned} \quad (5)$$

where \mathcal{N} is the net reproductive number [23, 30, 31] given by

$$\mathcal{N} = \frac{\mu_b \theta l s}{k_5 k_6 k_7 k_8} \quad (6)$$

3.1.1 Local stability of disease-free equilibria

The local asymptotic stability result of equilibria \mathcal{E}_0 and \mathcal{E}_1 is given in the following.

Theorem 1. Define the basic reproductive number [32, 33]

$$R_0 = \sqrt{\frac{a^2 (1 - \alpha_1)^2 \beta_{hv} \beta_{vh} \mu_h k_5 k_6 (\gamma_h + k_4 \eta_h) (\gamma_v + k_8 \eta_v) (\pi \xi + k_2) \alpha_2 \Gamma_E \Gamma_L (\mathcal{N} - 1)}{k_3 k_4 k_8 k_9 \mu_b \Lambda_h (\xi + k_2) (k_6 \Gamma_L + s \Gamma_E)}} \quad (7)$$

Then,

- (i) if $\mathcal{N} \leq 1$, the trivial equilibrium \mathcal{E}_0 is locally asymptotically stable in \mathcal{D} ;
- (ii) if $\mathcal{N} > 1$, the trivial equilibrium is unstable and the disease-free equilibrium \mathcal{E}_1 is locally asymptotically stable in \mathcal{D} whenever $\mathcal{R}_0 < 1$.

Proof. See [B](#). □

The basic reproduction number of a disease is the average number of secondary cases that one infectious individual produces during his infectious period in a totally susceptible population. The epidemiological implication of Theorem [1](#) is that, in general, when the basic reproduction number, \mathcal{R}_0 is less than unity, a small influx of infectious vectors into the community would not generate large outbreaks, and the disease dies out in time (since the DFE is LAS) [[19](#), [32](#), [33](#), [34](#)]. However, we show in the subsection [3.2](#) that the disease may still persist even when $\mathcal{R}_0 < 1$.

3.1.2 Global stability of the trivial equilibrium

The global stability of the trivial equilibrium is given by the following result:

Theorem 2. *If $\mathcal{N} \leq 1$, then \mathcal{E}_0 is globally asymptotically stable on \mathcal{D} .*

Proof. To prove the global asymptotic stability of the trivial disease-free equilibrium \mathcal{E}_0 , we use the direct Lyapunov method. To this aim, we set $Y = X - TE$ with $X = (S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P)^T$ and rewrite [\(2\)](#) in the following manner

$$\frac{dY}{dt} = \mathcal{B}(Y)Y.$$

The global asymptotic stability of \mathcal{E}_0 is achieved by considering the following Lyapunov function $\mathcal{L}(Y) = \langle g, Y \rangle$ where

$$g = \left(1, 1, 1, 1, 1, 1, 1, 1, \frac{k_8}{\mu_b}, \frac{k_5 k_8}{\mu_b s}, \frac{k_5 k_6 k_8}{\mu_b s l} \right).$$

See [C](#) for the details. □

3.1.3 Global stability of the disease-free equilibrium

We now turn to the global stability of the disease-free equilibrium \mathcal{E}_1 . we prove that the disease-free equilibrium \mathcal{E}_1 is globally asymptotically stable under a certain threshold condition. To this aim, we use a result obtained by Kamgang and Sallet [[35](#)], which is an extension of some results given in [[33](#)]. Using the property of DFE, it is possible to rewrite [\(2\)](#) in the following manner

$$\begin{cases} \dot{X}_S = \mathcal{A}_1(X)(X_S - X_{DFE}) + \mathcal{A}_{12}(X)X_I \\ \dot{X}_I = \mathcal{A}_2(X)X_I \end{cases} \quad (8)$$

where X_S is the vector representing the state of different compartments of non transmitting individuals $(S_h, V_h, R_h, S_v, E, L, P)$ and the vector X_I represents the state of compartments of different transmitting individuals (E_h, I_h, E_v, I_v) . Here, we have $X_S = (S_h, V_h, R_h, S_v, E, L, P)^T$, $X_I = (E_h, I_h, E_v, I_v)^T$, $X = (X_S, X_I)$ and $X_{DFE} := \mathcal{E}_1 = (S_h^0, V_h^0, 0, 0, 0, N_v^0, 0, 0, E, L, P)^T$,

$$\mathcal{A}_1(X) = \begin{pmatrix} \mathcal{A}_1^{(1)} & \mathcal{A}_1^{(2)} \\ \mathcal{A}_1^{(3)} & \mathcal{A}_1^{(4)} \end{pmatrix},$$

$$\begin{aligned}
\text{with } \mathcal{A}_1^{(1)}(X) &= \begin{pmatrix} -(\lambda_h^c + k_1) & \omega & 0 & 0 \\ \xi & -(\pi\lambda_h^c + k_2) & 0 & 0 \\ 0 & 0 & -\mu_h & 0 \\ 0 & 0 & 0 & -(\lambda_v^c + k_8) \end{pmatrix}, \\
\mathcal{A}_1^{(2)}(X) &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \theta \end{pmatrix}, \quad \mathcal{A}_1^{(3)}(X) = \begin{pmatrix} 0 & 0 & 0 & \mu_b \left(1 - \frac{E}{K_E}\right) \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\
\mathcal{A}_1^{(4)}(X) &= \begin{pmatrix} -\left(k_5 + \mu_b \frac{S_v^0}{K_E}\right) & 0 & 0 \\ s \left(1 - \frac{L}{K_L}\right) & -\left(k_6 + \frac{sE^*}{K_L}\right) & 0 \\ 0 & l & -k_7 \end{pmatrix}, \\
\mathcal{A}_{12}(X) &= \begin{pmatrix} 0 & 0 & -\frac{\tau\beta_{hv}\eta_v S_h^0}{N_h} & -\frac{\tau\beta_{hv} S_h^0}{N_h} & 0 & 0 & 0 \\ 0 & 0 & -\frac{\tau\beta_{hv}\eta_v \pi V_h^0}{N_h} & -\frac{\tau\beta_{hv} \pi V_h^0}{N_h} & 0 & 0 & 0 \\ 0 & \sigma & 0 & 0 & 0 & 0 & 0 \\ -\frac{\tau\beta_{vh}\eta_h S_v^0}{N_h} & -\frac{\tau\beta_{vh} S_v^0}{N_h} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \mu_b \left(1 - \frac{E}{K_E}\right) & \mu_b \left(1 - \frac{E}{K_E}\right) & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \\
\mathcal{A}_2(X) &= \begin{pmatrix} -k_3 & 0 & \frac{\tau\beta_{hv}\eta_v(S_h + \pi V_h)}{N_h} & \frac{\tau\beta_{hv}(S_h + \pi V_h)}{N_h} \\ \frac{\gamma_h}{N_h} & -k_4 & 0 & 0 \\ \frac{\tau\beta_{vh}\eta_h S_v}{N_h} & \frac{\tau\beta_{vh} S_v}{N_h} & -k_9 & 0 \\ 0 & 0 & \gamma_v & -k_8 \end{pmatrix}.
\end{aligned}$$

209 A direct computation shows that the eigenvalues of $\mathcal{A}_1(X)$ have negative real parts. Thus the
210 system $\dot{X}_S = \mathcal{A}_1(X)(X_S - X_{DFE})$ is globally asymptotically stable at X_{DFE} . Note also that
211 $\mathcal{A}_2(X)$ is a Metzler matrix.

212 We now consider the bounded set \mathcal{G} :

$$\begin{aligned}
\mathcal{G} &= \{(S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P) \in \mathbb{R}^{11} : S_h \leq N_h, V_h \leq N_h, E_h \leq N_h, \\
&I_h \leq N_h, R_h \leq N_h, \bar{N}_h = \Lambda_h/(\mu_h + \delta) \leq N_h \leq N_h^0 = \Lambda_h/\mu_h; \\
&E \leq K_E; L \leq K_L; P \leq \frac{lK_L}{k_7}; N_v \leq \frac{\theta lK_L}{k_7 k_8}\}
\end{aligned}$$

213 Let us recall the following theorem [35] (See [35] for a proof in a more general setting).

214 **Theorem 3.** Let $\mathcal{G} \subset \mathcal{U} = \mathbb{R}^7 \times \mathbb{R}^4$. The system (2) is of class C^1 , defined on \mathcal{U} . If

215 (1) \mathcal{G} is positively invariant relative to (8).

216 (2) The system $\dot{X}_S = \mathcal{A}_1(X)(X_S - X_{DFE})$ is Globally asymptotically stable at X_{DFE} .

217 (3) For any $x \in \mathcal{G}$, the matrix $\mathcal{A}_2(x)$ is Metzler irreducible.

218 (4) There exists a matrix $\bar{\mathcal{A}}_2$, which is an upper bound of the set

219 $\mathcal{M} = \{\mathcal{A}_2(x) \in \mathcal{M}_4(\mathbb{R}) : x \in \mathcal{G}\}$ with the property that if $\mathcal{A}_2 \in \mathcal{M}$, for any $\bar{x} \in \mathcal{G}$, such
220 that $\mathcal{A}_2(\bar{x}) = \bar{\mathcal{A}}_2$, then $\bar{x} \in \mathbb{R}^7 \times \{0\}$.

221 (5) The stability modulus of $\bar{\mathcal{A}}_2$, $\alpha(\mathcal{A}_2) = \max_{\lambda \in \text{sp}(\mathcal{A}_2)} \text{Re}(\lambda)$ satisfied $\alpha(\mathcal{A}_2) \leq 0$.

222 Then the DFE is GAS in \mathcal{G} .

For our model system (2), conditions (1–3) of the theorem 3 are satisfied. An upper bound of the set of matrices \mathcal{M} , which is the matrix $\bar{\mathcal{A}}_2$ is given by

$$\bar{\mathcal{A}}_2 = \begin{pmatrix} -k_3 & 0 & \frac{\tau\beta_{hv}\eta_v(S_h^0 + \pi V_h^0)}{\bar{N}_h} & \frac{\tau\beta_{hv}(S_h^0 + \pi V_h^0)}{\bar{N}_h} \\ \gamma_h & -k_4 & 0 & 0 \\ \frac{\tau\beta_{vh}\eta_h S_v^0}{\bar{N}_h} & \frac{\tau\beta_{vh} S_v^0}{\bar{N}_h} & -k_9 & 0 \\ 0 & 0 & \gamma_v & -k_8 \end{pmatrix},$$

223 where $\bar{N}_h = \frac{\Lambda_h}{(\mu_h + \delta)}$.

224 To check condition (5) in theorem 3, we will use the useful lemma [35] in A. To this aim,
225 let

$$226 \quad A = \begin{pmatrix} -k_3 & 0 \\ \gamma_h & -k_4 \end{pmatrix}, \quad B = \begin{pmatrix} \frac{\tau\beta_{hv}\eta_v(S_h^0 + \pi V_h^0)}{\bar{N}_h} & \frac{\tau\beta_{hv}(S_h^0 + \pi V_h^0)}{\bar{N}_h} \\ 0 & 0 \end{pmatrix},$$

$$227 \quad C = \begin{pmatrix} \frac{\tau\beta_{vh}\eta_h S_v^0}{\bar{N}_h} & \frac{\tau\beta_{vh} S_v^0}{\bar{N}_h} \\ 0 & 0 \end{pmatrix}, \quad D = \begin{pmatrix} -k_9 & 0 \\ \gamma_v & -k_8 \end{pmatrix}.$$

228 Clearly, A is a stable Metzler matrix. Then, after some computations, we obtain $D - CA^{-1}B$
229 is a stable Metzler matrix if and only if

$$\mathcal{R}_c < 1 \tag{9}$$

230 where

$$\mathcal{R}_c = \sqrt{\frac{a^2(1 - \alpha_1)^2\beta_{hv}\beta_{vh}k_5k_6(\gamma_h + k_4\eta_h)(\gamma_v + k_8\eta_v)K_EK_L(k_2 + \pi\xi)(\mathcal{N} - 1)(\mu_h + \delta)^2}{k_3k_4k_8k_9\mu_b(k_2 + \xi)(k_6K_L + K_Es)\Lambda_h}}}. \tag{10}$$

231

232 We claim the following result

233 **Theorem 4.** If $\mathcal{N} > 1$ and $\mathcal{R}_0 < \mathcal{R}_c < 1$, then the disease-free equilibrium \mathcal{E}_1 is globally
234 asymptotically stable in \mathcal{G} .

235 **Remark 1.** From (10), we have $\mathcal{R}_c = \frac{(\mu_h + \delta)}{\mu_h} \mathcal{R}_0 > \mathcal{R}_0$, showing that \mathcal{R}_c is not necessarily
236 an optimal threshold parameter.

237 **Remark 2.** Note that in the absence of disease-induced death, i.e. $\delta = 0$, we have $\mathcal{R}_c = \mathcal{R}_0$.
238 This suggests that the disease-induced death may be a cause of the occurrence of the backward
239 bifurcation phenomenon.

240 **Remark 3.** The above results show that if, at any time, through appropriate interventions (eg
241 the destruction of breeding sites, massive spraying, personal protection, vaccination,...), we are
242 able to reduce \mathcal{N} or \mathcal{R}_0 and \mathcal{R}_c less than 1 for a sufficiently long period, then, the disease may
243 disappear [15].

Theorem 4 means that for $\mathcal{R}_0 < \mathcal{R}_c < 1$, the DFE is the unique equilibrium (no co-existence with an endemic equilibrium). If $\mathcal{R}_c \leq \mathcal{R}_0 \leq 1$, then it is possible to have co-existence with endemic equilibria and thus, the occurrence of backward bifurcation phenomenon.

The backward bifurcation phenomenon, in epidemiological systems, indicate the possibility of existence of at least one endemic equilibrium when \mathcal{R}_0 is less than unity. Thus, the classical requirement of $\mathcal{R}_0 < 1$ is, although necessary, no longer sufficient for disease elimination [19, 36, 37, 38]. In some epidemiological models, it has been shown that the backward bifurcation phenomenon is caused by factors such as non-linear incidence (the infection force), disease-induced death and vaccine (perfect or not) [19, 38, 39, 40, 41, 42]. To confirm whether or not the backward bifurcation phenomenon occurs in this case, one could use the approach developed in [33, 41, 43], which is based on the general centre manifold theorem [44]. We will explore this method in the next section.

3.2 Endemic equilibria and bifurcation analysis

3.2.1 Existence of endemic equilibria

We turn now to the existence of endemic equilibria. Let us introduce the following quantity $R_1 = R_0^2|_{\delta=0}$. We prove the following result

Theorem 5. *We assume that $\mathcal{N} > 1$, then*

(i) *In the absence of disease-induced death in human population ($\delta = 0$), model system (2) have*

1. *an unique endemic equilibrium whenever $R_1 > 1$.*

2. *no endemic equilibrium otherwise.*

(ii) *In presence of disease-induced death in human population ($\delta > 0$), model system (2) could have*

3. *at least one endemic equilibrium whenever $\mathcal{R}_0 > 1$.*

4. *zero, one or more than one endemic equilibrium whenever $\mathcal{R}_0 < 1$.*

Proof. See D. □

Note that case 4 of Theorem 5 indicate the possibility of existence of at least one endemic equilibrium for $\mathcal{R}_0 < 1$ and hence the potential occurrence of a backward bifurcation phenomenon.

3.2.2 Backward bifurcation analysis

In the following, we use the centre manifold theory [21, 33, 41, 43] to explore the possibility of backward bifurcation in (2). To do so, a bifurcation parameter β_{hv}^* is chosen, by solving for β_{hv} from $\mathcal{R}_0 = 1$, giving

$$\beta_{hv}^* = \frac{k_3 k_4 k_8 k_9 \mu_b \Lambda_h (\xi + k_2) (k_6 K_L + s K_E)}{a^2 (1 - \alpha_1)^2 \beta_{vh} \mu_h k_5 k_6 (\gamma_h + k_4 \eta_h) (\gamma_v + k_8 \eta_v) (\pi \xi + k_2) K_E K_L (\mathcal{N} - 1)}. \quad (11)$$

Let $J_{\beta_{hv}^*}$ denotes the Jacobian of the system (2) evaluated at the DFE (\mathcal{E}_1) and with $\beta_{hv} = \beta_{hv}^*$. Thus,

$$J_{\beta_{hv}^*} = \begin{pmatrix} J_1 & J_2 \\ J_3 & J_4 \end{pmatrix}, \quad (12)$$

where

$$\begin{aligned}
J_1 &= \begin{pmatrix} -k_1 & \omega & 0 & 0 & 0 \\ \xi & -k_2 & 0 & 0 & 0 \\ 0 & 0 & -k_3 & 0 & 0 \\ 0 & 0 & \gamma_h & -k_4 & 0 \\ 0 & 0 & 0 & \sigma & -\mu_h \end{pmatrix}, \quad J_4 = \begin{pmatrix} -k_8 & 0 & 0 & 0 & 0 & \theta \\ 0 & -k_9 & 0 & 0 & 0 & 0 \\ 0 & \gamma_v & -k_8 & 0 & 0 & 0 \\ K_1 & K_1 & K_1 & -K_2 & 0 & 0 \\ 0 & 0 & 0 & K_3 & -K_4 & 0 \\ 0 & 0 & 0 & 0 & l & -k_7 \end{pmatrix}. \\
J_2 &= \begin{pmatrix} 0 & -\frac{\tau\beta_{hv}^*\eta_v S_h^0}{N_h^0} & -\frac{\tau\beta_{hv}^* S_h^0}{N_h^0} & 0 & 0 & 0 \\ 0 & -\frac{\tau\beta_{hv}^*\pi\eta_v V_h^0}{N_h^0} & -\frac{\tau\beta_{hv}^*\pi V_h^0}{N_h^0} & 0 & 0 & 0 \\ 0 & \frac{\tau\beta_{hv}^*\eta_v H^0}{N_h^0} & \frac{\tau\beta_{hv}^* H^0}{N_h^0} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \quad J_3 = \begin{pmatrix} 0 & 0 & -\frac{\tau\beta_{vh}\eta_h S_v^0}{N_h^0} & -\frac{\tau\beta_{vh} S_v^0}{N_h^0} & 0 \\ 0 & 0 & \frac{\tau\beta_{vh}\eta_h S_v^0}{N_h^0} & \frac{\tau\beta_{vh} S_v^0}{N_h^0} & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \\
\text{with } H^0 &= S_h^0 + \pi V_h^0, \quad K_1 = \mu_b \left(1 - \frac{E^*}{K_E}\right), \quad K_2 = k_5 + \frac{\mu_b}{K_E} S_v^0, \quad K_3 = s \left(1 - \frac{L^*}{K_L}\right), \text{ and} \\
K_4 &= \left(k_6 + \frac{sE^*}{K_L}\right).
\end{aligned}$$

Note that the system (2), with $\beta_{hv} = \beta_{hv}^*$, has a hyperbolic equilibrium point (i.e., the linearised system (2) has a simple eigenvalue with zero real part and all other eigenvalues have negative real part). Hence, the centre manifold theory [44, 45] can be used to analyse the dynamics of the model (2) near $\beta_{hv} = \beta_{hv}^*$. The technique in Castillo-Chavez and Song (2004) [43] entails finding the left and right eigenvectors of the linearised system above as follows.

The left eigenvector components of $J_{\beta_{hv}^*}$, which correspond to the uninfected states are zero (see Lemma 3 in [33]). Thus a non-zero components correspond to the infected states. It follows that the matrix $J_{\beta_{hv}^*}$ has a left eigenvector given by $\mathbf{v} = (v_1, v_2, \dots, v_{11})$, where

$$\begin{aligned}
v_1 &= v_2 = v_5 = v_6 = v_9 = v_{10} = v_{11} = 0; \quad v_3 = \frac{k_8 N_h^0}{a(1 - \alpha_1)\beta_{hv}^* H^0} v_8; \\
v_4 &= \frac{a(1 - \alpha_1)\beta_{vh} S_v^0 (\eta_v k_8 + \gamma_v)}{k_4 k_9 N_h^0} v_8, \quad v_7 = \frac{(\eta_v k_8 + \gamma_v)}{k_9} v_8, \quad v_8 = v_8 > 0.
\end{aligned}$$

The system (2) has a right eigenvector given by $\mathbf{w} = (w_1, w_2, \dots, w_{11})^T$, where

$$\begin{aligned}
w_{11} &> 0, \quad w_8 > 0, \\
w_{10} &= \frac{k_7}{l} w_{11}, \quad w_9 = \frac{K_1 \theta}{k_5 k_8} w_{11}, \quad w_7 = \frac{k_8}{\gamma_v} w_8, \quad w_6 = \frac{\theta}{k_8} w_{11} - \frac{k_9}{\gamma_v} w_8, \\
w_5 &= \frac{\gamma_h \sigma k_8 k_9 N_h^0}{a(1 - \alpha_1)\beta_{vh}\mu_h \gamma_v S_v^0 (\eta_h k_4 + \gamma_h)} w_8, \quad w_4 = \frac{\mu_h}{\sigma} w_5, \quad w_3 = \frac{k_4}{\gamma_h} w_4, \\
w_2 &= -\frac{a(1 - \alpha_1)\beta_{hv}^* (\eta_v k_8 + \gamma_v)}{\gamma_v N_h^0 (k_1 k_2 - \xi \omega)} (\xi S_h^0 + k_1 V_h^0) w_8, \\
w_1 &= \frac{\omega}{k_1} w_2 - \frac{a(1 - \alpha_1)\beta_{hv}^* S_h^0}{k_1 N_h^0} (\eta_v w_7 + w_8).
\end{aligned}$$

Theorem 4.1 in Castillo-Chavez and Song [43] is then applied to establish the existence of backward bifurcation in (2). To apply such a theorem, it is convenient to let f_k represent the right-hand side of the k^{th} equation of the system (2) and let x_k be the state variables whose derivative is given by the k^{th} equation for $k = 1, \dots, 11$. The local bifurcation analysis near the bifurcation point ($\beta_{hv} = \beta_{hv}^*$) is then determined by the signs of two associated constants, denoted by \mathcal{A}_1 and \mathcal{A}_2 , defined by

$$\mathcal{A}_1 = \sum_{k,i,j=1}^n v_k w_i w_j \frac{\partial^2 f_k(0,0)}{\partial x_i \partial x_j} \quad \text{and} \quad \mathcal{A}_2 = \sum_{k,i=1}^n v_k w_i \frac{\partial^2 f_k(0,0)}{\partial x_i \partial \phi} \quad (13)$$

with $\phi = \beta_{hv} - \beta_{hv}^*$. It is important to note that in $f_k(0, 0)$, the first zero corresponds to the disease-free equilibrium, \mathcal{E}_1 , for the system (2). Since $\beta_{hv} = \beta_{hv}^*$ is the bifurcation parameter, it follows from $\phi = \beta_{hv} - \beta_{hv}^*$ that $\phi = 0$ when $\beta_{hv} = \beta_{hv}^*$ which is the second component in $f_k(0, 0)$.

It follows then, after some algebraic manipulations, that

$$\mathcal{A}_1 = \Gamma_1 - \Gamma_2$$

with

$$\begin{aligned}\Gamma_1 &= \frac{a(1 - \alpha_1)\beta_{hv}^*(2V_h^0 w_1 + \pi S_h^0 w_2)}{(N_h^0)^2} (\eta_v w_7 + w_8) v_3 \\ &\quad + \frac{a(1 - \alpha_1)\beta_{vh} S_v^0}{N_h^0} \left[(\eta_h w_3 + w_4) \frac{1}{S_v^0} + \left(\eta_h w_3 + \frac{1}{S_v^0} w_4 \right) \right] w_6 v_7, \\ \Gamma_2 &= 2 \frac{a(1 - \alpha_1)\beta_{vh} S_v^0}{(N_h^0)^2} \left(\sum_{i=1}^5 w_i \right) (\eta_h w_3 + w_4) v_7 \\ &\quad + \frac{a(1 - \alpha_1)\beta_{hv}^*(S_h^0 + \pi V_h^0)(N_h^0 + 1)}{(N_h^0)^2} \left(\sum_{i=3}^5 w_i \right) (\eta_v w_7 + w_8) v_3,\end{aligned}$$

and

$$\mathcal{A}_2 = \frac{a(S_h^0 + \pi V_h^0)}{N_h^0} (\eta_v w_7 + w_8) v_3$$

Hence, the coefficient $\mathcal{A}_1 > 0$ if and only if

$$\Gamma_1 > \Gamma_2 \tag{14}$$

Note that the coefficient \mathcal{A}_2 is automatically positive. Thus, using Theorem 4.1 in [43], the following result is established.

Theorem 6. *The model (2) exhibits a backward bifurcation at $\mathcal{R}_0 = 1$ whenever the inequality (14) holds. If the reversed inequality holds, then the bifurcation at $\mathcal{R}_0 = 1$ is forward.*

The associated bifurcation diagrams are depicted in Figures 2 and 3. Parameter values used in figure 2 correspond to those in Table 4, except $\Lambda_h = 10$, $\epsilon = 1$, $\beta_{vh} = 0.8$, $\eta_h = 1$, $\eta_v = 1$, $\sigma = 0.01428$, $\delta = 1$, $\alpha_1 = 0.001$, $\alpha_2 = 1$, $c_m = 0.0001$, $\Gamma_E = 10^5$, $\Gamma_L = 50000$. In this case the conditions required by Theorem 6, are satisfied: $\mathcal{A}_1 = 0.0114 > 0$ and $\mathcal{A}_2 = 1.1393 > 0$.

Parameter values used in figure 3 correspond to those in Table 4, except $\Lambda_h = 10$, $\beta_{vh} = 0.8$, $\eta_h = \eta_v = 0 = \delta = c_m = \alpha_1 = 0$, $\alpha_2 = 1$, $\Gamma_E = 10^5$, $\Gamma_L = 50000$. We also have $\mathcal{A}_1 = -2.4223 < 0$ and $\mathcal{A}_2 = 0.8333 > 0$.

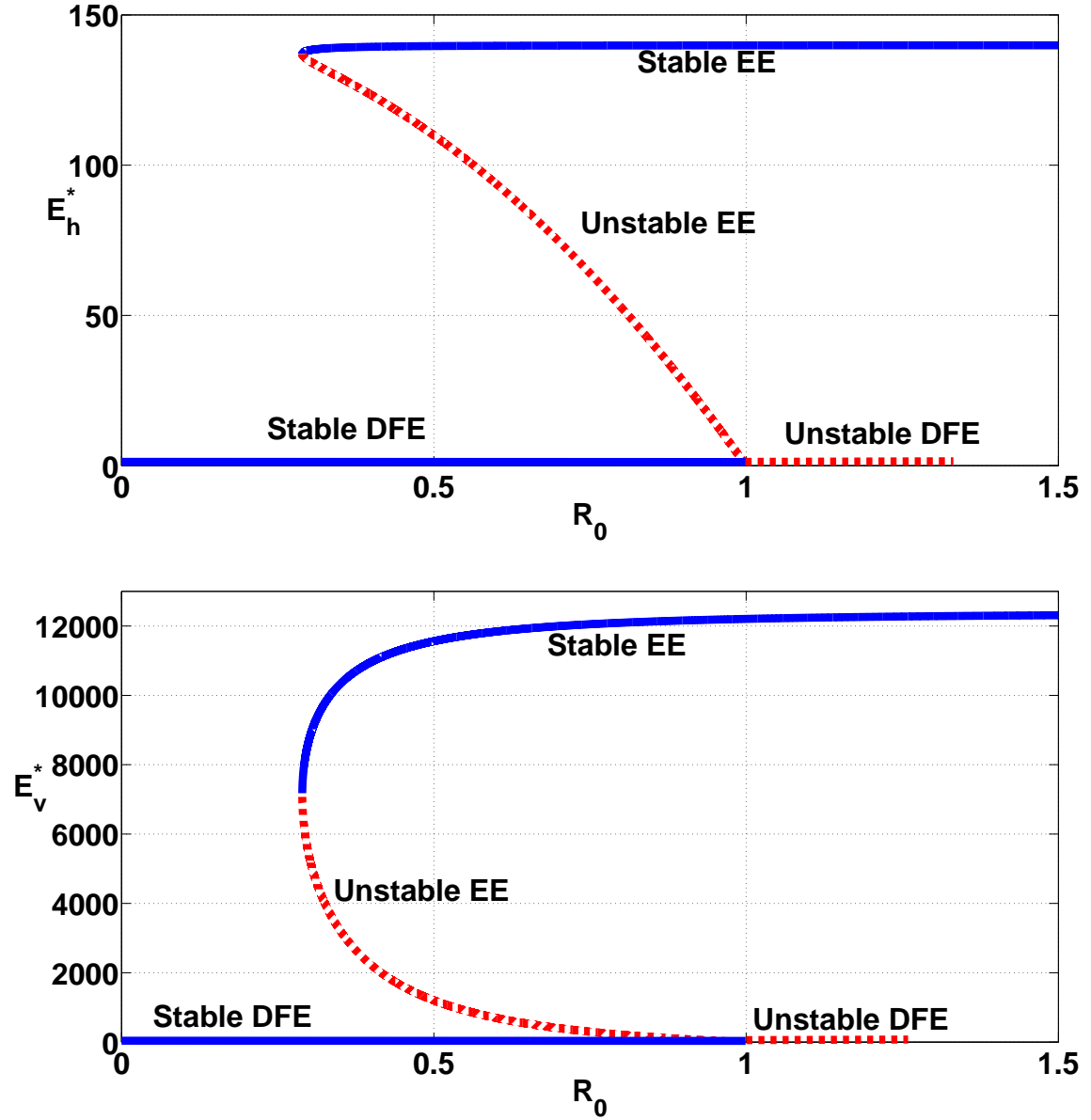


Figure 2: The backward bifurcation curves for model system (15) in the (\mathcal{R}_0, E_h^*) , and (\mathcal{R}_0, E_v^*) planes. The parameter β_{hv} is varied in the range $[0, 0.2810]$ to allow \mathcal{R}_0 to vary in the range $[0, 1.5]$. Two endemic equilibrium points coexist for values of \mathcal{R}_0 in the range $(0.2894, 1)$ (corresponding to the range $(0.0105, 0.1249)$ of β_{hv}). The notation EE and DFE stand for endemic equilibrium and disease-free equilibrium, respectively. Solid line represent stable equilibria and dash line stands for unstable equilibria.

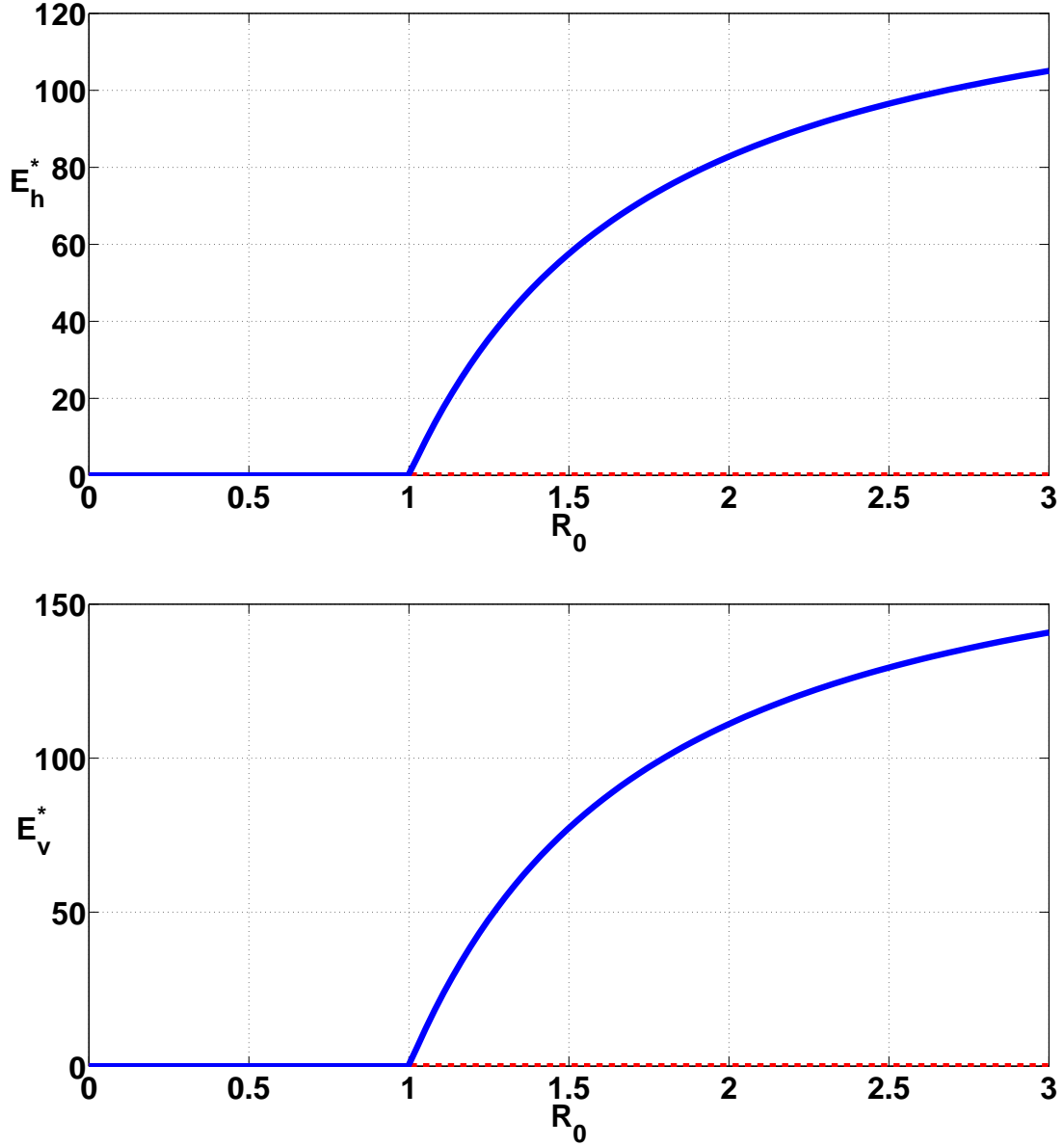


Figure 3: The forward bifurcation curves for model system (15) in the (\mathcal{R}_0, E_h^*) , and (\mathcal{R}_0, E_v^*) planes. Solid line represent stable equilibria and dash line stands for unstable disease-free equilibrium.

313 The occurrence of the backward bifurcation can be also seen in Figure 4. Here, \mathcal{R}_0 is less
314 than the transcritical bifurcation threshold ($\mathcal{R}_0 = 0.29 < 1$), but the solution of the model 2 can
315 approach either the endemic equilibrium point or the disease-free equilibrium point, depending
316 on the initial condition.

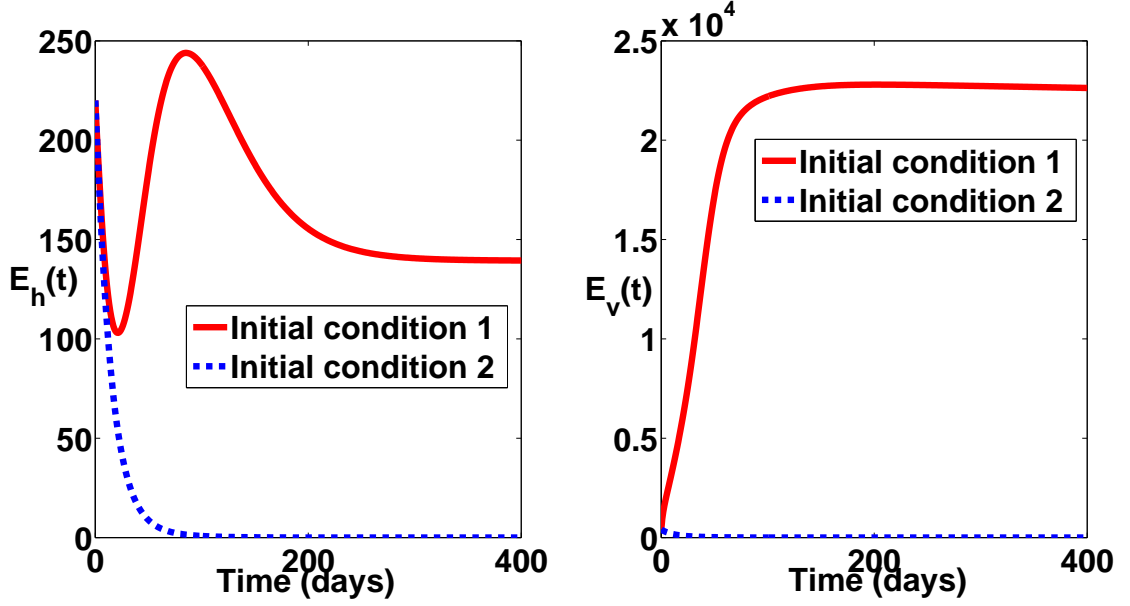


Figure 4: Solutions of model (2) of the number of infected humans, E_h , and the number of infected vectors, E_v , for parameter values given in the bifurcation diagram in Figure 2 with $\beta_{hv} = 0.0105$. So $\mathcal{R}_0 = 0.29 < 1$, for two different set of initial conditions. The first set of initial conditions (corresponding to the solid trajectory) is $S_h = 700$, $V_h = 10$, $E_h = 220$, $I_h = 100$, $R_h = 60$, $S_v = 3000$, $E_v = 400$, $I_v = 120$, $E = 10000$, $L = 5000$ and $P = 3000$. The second set of initial conditions (corresponding to the dotted trajectory) is $S_h = 489100$, $V_h = 10$, $E_h = 220$, $I_h = 100$, $R_h = 60$, $S_v = 3000$, $E_v = 400$, $I_v = 120$, $E = 10000$, $L = 5000$ and $P = 3000$. The solution for initial condition 1 approaches the locally asymptotically stable endemic equilibrium point, while the solution for initial condition 2 approaches the locally asymptotically stable DFE.

From theorem 5, item (i), it follows that the disease-induced death in human (δ) may be a cause of the occurrence of backward bifurcation phenomenon. In the following, we show that the backward bifurcation phenomenon is caused by the disease-induced death in human and/or the standard incidence functions (λ_h^c and λ_v^c).

3.3 The different causes of the backward bifurcation

To determine the different causes of the backward bifurcation phenomenon, we will consider, in this section, two variants of the model (2): the corresponding model without vaccination and the corresponding model with mass action incidence.

3.3.1 Analysis of the model without vaccination

The model without vaccination is given by

$$\begin{cases} \dot{S}_h &= \Lambda_h - (\lambda_h^c + \mu_h) S_h \\ \dot{E}_h &= \lambda_h^c S_h - (\mu_h + \gamma_h) E_h \\ \dot{I}_h &= \gamma_h E_h - (\mu_h + \delta + \sigma) I_h \\ \dot{R}_h &= \sigma I_h - \mu_h R_h \\ \dot{S}_v &= \theta P - \lambda_v^c S_v - (\mu_v + c_m) S_v \\ \dot{E}_v &= \lambda_v^c S_v - (\mu_v + \gamma_v + c_m) E_v \\ \dot{I}_v &= \gamma_v E_v - (\mu_v + c_m) I_v \\ \dot{E} &= \mu_b \left(1 - \frac{E}{\alpha_2 \Gamma_E}\right) (S_v + E_v + I_v) - (s + \mu_E + \eta_1) E \\ \dot{L} &= s E \left(1 - \frac{L}{\alpha_2 \Gamma_L}\right) - (l + \mu_L + \eta_2) L \\ \dot{P} &= l L - (\theta + \mu_P) P \end{cases} \quad (15)$$

where λ_h^c and λ_v^c are given at section 2. Model system (15) is defined in the positively-invariant set

$$\mathcal{D}_1 = \left\{ (S_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P) \in \mathbb{R}^{10} : N_h \leq \Lambda_h / \mu_h; E \leq K_E; L \leq K_L; P \leq \frac{l K_L}{k_7}; N_v \leq \frac{\theta l K_L}{k_7 k_8} \right\}.$$

Without loss of generality, we assume that $\mathcal{N} > 1$. The corresponding disease-free equilibria of model (15) are given by $\mathcal{E}_0^{nv} = (N_h^0, 0, 0, 0, 0, 0, 0, 0, 0, 0)$ and

$\mathcal{E}_1^{nv} = (N_h^0, 0, 0, 0, N_v^0, 0, 0, E, L, P)$ with $N_h^0 = \frac{\Lambda_h}{\mu_h}$ and N_v^0, E, L and P are the same, given by (5). The associated next generation matrices, F_1 and V_1 , are, respectively, given by

$$F_1 = \begin{pmatrix} 0 & 0 & \tau \beta_{hv} \eta_v & \tau \beta_{hv} \\ 0 & 0 & 0 & 0 \\ \frac{\tau \beta_{vh} \eta_v N_v^0}{N_h^0} & \frac{\tau \beta_{vh} N_v^0}{N_h^0} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } V_1 = \begin{pmatrix} k_3 & 0 & 0 & 0 \\ -\gamma_h & k_4 & 0 & 0 \\ 0 & 0 & k_9 & 0 \\ 0 & 0 & -\gamma_v & k_8 \end{pmatrix}.$$

It follows that the associated reproduction number for the model without vaccination, denoted by $\mathcal{R}_{nv} = \rho(F_1 V_1^{-1})$, is given by

$$\mathcal{R}_{nv} = \sqrt{\frac{a^2 (1 - \alpha_1)^2 \beta_{hv} \beta_{vh} (\gamma_h + k_4 \eta_h) (\gamma_v + k_8 \eta_v) N_v^0}{k_3 k_4 k_8 k_9 N_h^0}}. \quad (16)$$

Using Theorem 2 of [33], we establish the following result:

Theorem 7. *Assumed that $\mathcal{N} > 1$. For basic arboviral model without vaccination, given by (15), the corresponding disease-free equilibrium is LAS if $\mathcal{R}_{nv} < 1$, and unstable if $\mathcal{R}_{nv} > 1$.*

Existence of endemic equilibria Here, the existence of endemic equilibria of the model (15) will be explored. Let us set the following coefficients

$$\begin{aligned} \mathcal{R}_c &= \sqrt{\frac{\{2k_8(k_3 k_4 - \delta \gamma_h) + (\eta_h k_4 + \gamma_h) a \mu_h (1 - \alpha_1) \beta_{vh}\}}{k_3 k_4 k_8}}, \\ d_2 &= -k_9 \mu_b \Lambda_h (s K_E + k_6 K_L) (k_3 k_4 - \delta \gamma_h) ((\eta_h k_4 + \gamma_h) a \mu_h (1 - \alpha_1) \beta_{vh} \\ &\quad + (k_3 k_4 - \delta \gamma_h) k_8) < 0, \\ d_1 &= k_3^2 k_4^2 k_8 k_9 (s K_E + k_6 K_L) \mu_b \Lambda_h \mu_h (\mathcal{R}_{nv}^2 - R_c^2), \\ d_0 &= k_3^2 k_4^2 k_8 k_9 (s K_E + k_6 K_L) \mu_b \Lambda_h \mu_h^2 (\mathcal{R}_{nv}^2 - 1). \end{aligned} \quad (17)$$

We claim the following:

Theorem 8. *The arboviral diseases model without vaccination (15) has:*

- (i) a unique endemic equilibrium if $d_0 > 1 \Leftrightarrow \mathcal{R}_{nv} > 1$;
- (ii) a unique endemic equilibrium if $d_1 > 0$, and $d_0 = 0$ or $d_1^2 - 4d_2d_0 = 0$;
- (iii) two endemic equilibria if $d_0 < 0$ (i.e. $\mathcal{R}_{nv} < 1$), $d_1 > 0$ (i.e. $\mathcal{R}_{nv} > \mathcal{R}_c$) and $d_1^2 - 4d_2d_0 > 0$;
- (iv) no endemic equilibrium if $d_0 < 0$ (i.e. $\mathcal{R}_{nv} < 1$) and $\delta = 0$.
- (v) no endemic equilibrium otherwise.

Proof. Solving the equations in the model (15) in terms of $\lambda_h^{c,*}$ and $\lambda_v^{c,*}$, gives

$$S_h^* = \frac{\Lambda_h}{\mu_h + \lambda_h^{c,*}}, \quad E_h^* = \frac{\lambda_h^{c,*} S_h^*}{k_3}, \quad I_h^* = \frac{\gamma_h \lambda_h^{c,*} S_h^*}{k_3 k_4}, \quad R_h^* = \frac{\sigma \gamma_h \lambda_h^{c,*} S_h^*}{\mu_h k_3 k_4}, \quad (18)$$

and

$$\begin{aligned} S_v^* &= \frac{\theta P}{(\lambda_v^{c,*} + k_8)}, \quad E_v^* = \frac{\theta P \lambda_v^{c,*}}{k_9 (\lambda_v^{c,*} + k_8)}, \quad I_v^* = \frac{\gamma_v \theta P \lambda_v^{c,*}}{k_8 k_9 (\lambda_v^{c,*} + k_8)}, \\ E &= \frac{\mu_b \theta K_E P}{(k_5 k_8 K_E + \mu_b \theta P)}, \quad L = \frac{\mu_b \theta s K_E K_L P}{k_6 K_L (k_5 k_8 K_E + \mu_b \theta P) + s \mu_b \theta K_E P}, \end{aligned} \quad (19)$$

Substituting (18) and (19) into the expression of λ_h^* and λ_v^* and simplifying, shows that the nonzero equilibria of the model without vaccination satisfy the quadratic equation

$$d_2 (\lambda_h^{c,*})^2 + d_1 \lambda_h^{c,*} + d_0 = 0 \quad (20)$$

where d_i , $i = 0, 1, 2$, are given by (17).

Clearly, $d_2 < 0$ and $d_0 > 0$ (resp. $d_0 < 0$) if $\mathcal{R}_{nv} > 1$ (resp. $\mathcal{R}_{nv} < 1$). Thus Theorem 8 is established. \square

It is clear that cases (ii) and (iii) of theorem 8 indicates the possibility of backward bifurcation (where the locally-asymptotically stable DFE co-exists with a locally-asymptotically stable endemic equilibrium when $\mathcal{R}_{nv} < 1$) in the model without vaccination (15).

This is illustrated by simulating the model with the following set of parameter values (it should be stated that these parameters are chosen for illustrative purpose only, and may not necessarily be realistic epidemiologically): $\Lambda_h = 5$, $\beta_{hv} = 0.03$, $\eta_h = \eta_v = 1$, $\delta = 1$, $\sigma = 0.01$, $c_m = 0.1$, $\beta_{vh} = 0.4$, $\alpha_1 = 0.7$ and $\alpha_2 = 0.5$. All other parameters are as in Table 4. With this set of parameters, $\mathcal{R}_c = 0.0216 < 1$, $\mathcal{R}_{nv} = 0.2725 < 1$ (so that $\mathcal{R}_c < \mathcal{R}_{nv} < 1$). It follows: $d_2 = -0.0263 < 0$, $d_1 = 4.8763 \times 10^{-4}$ and $d_0 = -3.5031 \times 10^{-7}$, so that $d_1^2 - 4d_2d_0 = 2.0093 \times 10^{-7} > 0$. The resulting two endemic equilibria $\mathcal{E}^{nv} = (S_h^*, E_h^*, I_h^*, R_h^*, S_v^*, E_v^*, I_v^*, E, L, P)$, are: $\mathcal{E}_1^{nv} = (281, 70, 5, 1207, 5739, 182, 44, 22180, 10201, 9977)$ which is locally stable and $\mathcal{E}_2^{nv} = (6333, 67, 4, 1147, 5936, 37, 2, 22180, 10201, 9977)$ which is unstable.

The associated bifurcation diagram is depicted in figure 5. This clearly shows the co-existence of two locally-asymptotically stable equilibria when $\mathcal{R}_{nv} < 1$, confirming that the model without vaccination (15) undergoes the phenomenon of backward bifurcation too.

Thus, the following result is established.

Lemma 1. *The model without vaccination (15) undergoes backward bifurcation when Case (iii) of Theorem 8 holds.*

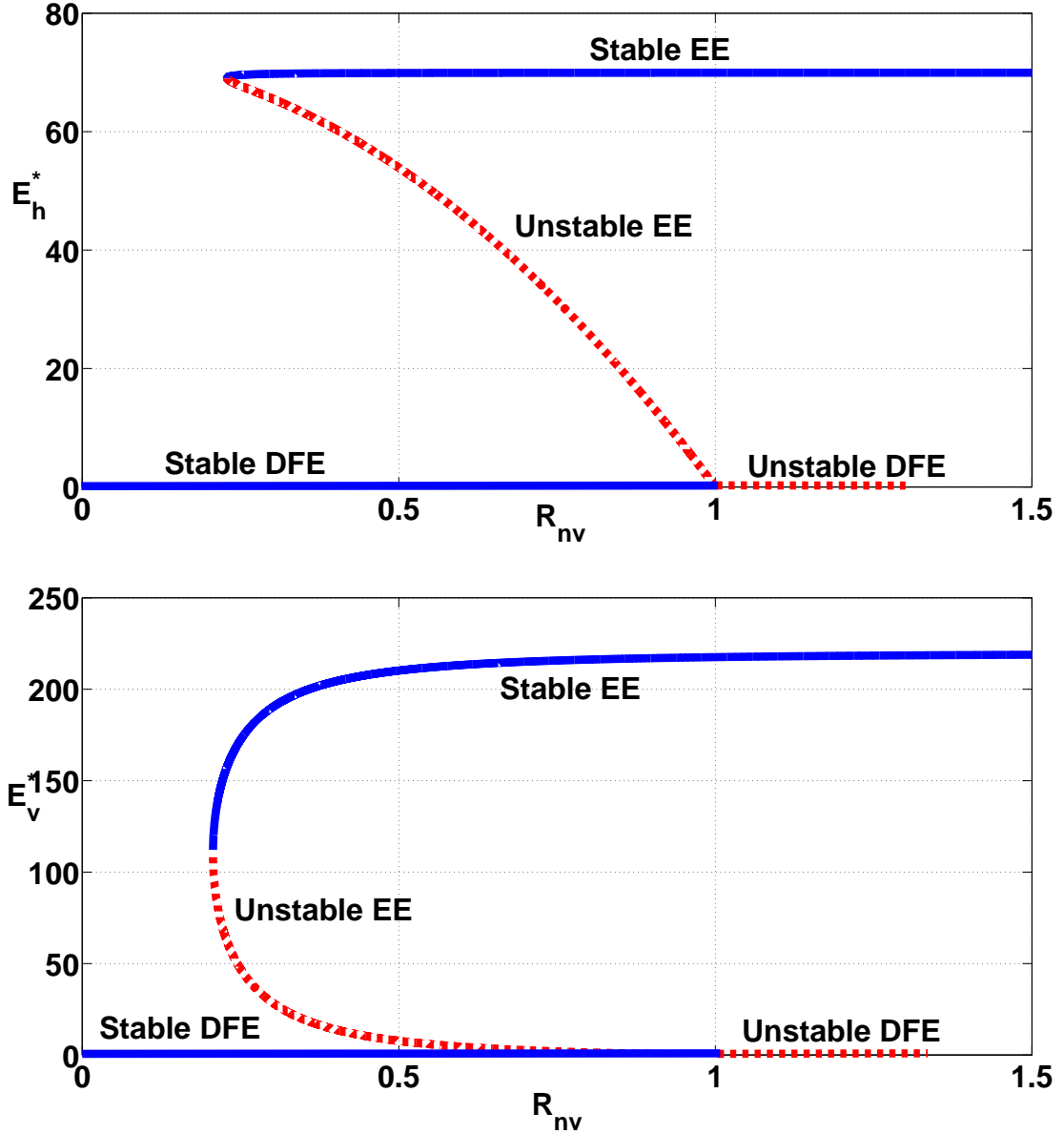


Figure 5: The backward bifurcation curves for model system (15) in the $(\mathcal{R}_{nv}, E_h^*)$, and $(\mathcal{R}_{nv}, E_v^*)$ planes. The parameter β_{hv} is varied in the range $[0, 0.9090]$ to allow \mathcal{R}_0 to vary in the range $[0, 1.5]$. Two endemic equilibrium points coexist for values of \mathcal{R}_0 in the range $(0.2286, 1)$ (corresponding to the range $(0.0211, 0.4040)$ of β_{hv}). The notation EE and DFE stand for endemic equilibrium and disease free equilibrium, respectively. Solid line represent stable equilibria and dash line stands for unstable equilibria.

Non-existence of endemic equilibria for $\mathcal{R}_{nv} < 1$ and $\delta = 0$ In this case, we have the following result.

Lemma 2. *The model (15) without disease-induced death ($\delta = 0$) has no endemic equilibrium when $\mathcal{R}_{nv, \delta=0} \leq 1$, and has a unique endemic equilibrium otherwise.*

Proof. Considering the model (15) without disease-induced death in human, and applying the same procedure, we obtain that the non-zero equilibria of the model without vaccination satisfy

the linear equation

$$p_1 \lambda_h^{c,*} + p_0 = 0,$$

where $p_1 = k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h (1 - \alpha_1) \beta_{vh} + k_3 (\mu_h + \sigma) k_8 k_9 K_{12} \mu_b \Lambda_h$ and
 $p_0 = -\mu_h k_3 k_4 k_8 k_9 K_{12} \mu_b \Lambda_h (\mathcal{R}_{nv,\delta=0}^2 - 1)$.

Clearly, $p_1 > 0$ and $p_0 \geq 0$ whenever $R_{nv,\delta=0} \leq 1$, so that $\lambda_h^{c,*} = -\frac{p_0}{p_1} \leq 0$. Therefore, the model (15) without disease-induced death in human, has no endemic equilibrium whenever $\mathcal{R}_{nv,\delta=0}^2 \leq 1$. \square

The above result suggests the impossibility of backward bifurcation in the model (15) without disease-induced death, since no endemic equilibrium exists when $\mathcal{R}_{nv,\delta=0} < 1$ (and backward bifurcation requires the presence of at least two endemic equilibria when $\mathcal{R}_{nv,\delta=0} < 1$) [19, 38]. To completely rule out backward bifurcation in model (15), we use the direct Lyapunov method to prove the global stability of the DFE.

Global stability of the DFE of (15) for $\delta = 0$ Define the positively-invariant and attracting region

$$\mathcal{D}_2 = \{(S_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P) \in \mathcal{D}_1 : S_h \leq N_h^0; S_v \leq N_v^0\}$$

We claim the following result.

Theorem 9. *The DFE, \mathcal{E}_1^{nv} , of model (15) without disease-induced death ($\delta = 0$), is globally asymptotically stable (GAS) in \mathcal{D}_2 if $\mathcal{R}_{nv,\delta=0} < 1$.*

Proof. Consider the Lyapunov function

$$\mathcal{G} = q_1 E_h + q_2 I_h + q_3 E_v + q_4 I_v.$$

where

$$q_1 = \frac{1}{k_3}; \quad q_3 = \frac{\zeta_1 S_h^0 (\gamma_v + k_8 \eta_v)}{k_3 k_8 k_9}, \quad q_2 = \frac{\zeta_1 S_h^0 (\gamma_v + k_8 \eta_v) \zeta_2 S_v^0}{k_3 k_8 k_4 k_9}, \quad q_4 = \frac{\zeta_1 S_h^0}{k_3 k_8}.$$

and we have set $\zeta_1 = \frac{\tau \mu_h \beta_{hv}}{\Lambda_h}$ and $\zeta_2 = \frac{\tau \mu_h \beta_{vh}}{\Lambda_h}$. The derivative of \mathcal{G} is given by

$$\begin{aligned} \dot{\mathcal{G}} &= q_1 \dot{E}_h + q_2 \dot{I}_h + q_3 \dot{E}_v + q_4 \dot{I}_v \\ &= q_1 (\lambda_h^c S_h - k_3 E_h) + q_2 (\gamma_h E_h - k_4 I_h) + q_3 (\lambda_v^c S_v - k_9 E_v) + q_4 (\gamma_v E_v - k_8 I_v) \\ &= q_1 \zeta_1 S_h (\eta_v E_v + I_v) - q_3 k_9 E_v + q_4 \gamma_v E_v - q_4 k_8 I_v \\ &\quad + q_3 \zeta_2 S_v (\eta_h E_h + I_h) - q_1 k_3 E_h + q_2 \gamma_h E_h - q_2 k_4 I_h \\ &= (q_1 \zeta_1 S_h \eta_v + q_4 \gamma_v - q_3 k_9) E_v + (q_1 \zeta_1 S_h - q_4 k_8) I_v \\ &\quad + (q_3 \zeta_2 S_v \eta_h + q_2 \gamma_h - q_1 k_3) E_h + (q_3 \zeta_2 S_v - q_2 k_4) I_h \\ &\leq (q_1 \zeta_1 S_h^0 \eta_v + q_4 \gamma_v - q_3 k_9) E_v + (q_1 \zeta_1 S_h^0 - q_4 k_8) I_v \\ &\quad + (q_3 \zeta_2 S_v^0 \eta_h + q_2 \gamma_h - q_1 k_3) E_h + (q_3 \zeta_2 S_v^0 - q_2 k_4) I_h, \text{ since } S_h \leq S_h^0, S_v \leq S_v^0 \end{aligned}$$

Replacing q_i , $i = 1, \dots, 4$, by their value gives after straightforward simplifications

$$\dot{\mathcal{G}} \leq (\mathcal{R}_{nv,\delta=0}^2 - 1) E_h$$

We have $\dot{\mathcal{G}} \leq 0$ if $R_{nv,\delta=0} \leq 1$, with $\dot{\mathcal{G}} = 0$ if $\mathcal{R}_{nv,\delta=0} = 1$ or $E_h = 0$. Whenever $E_h = 0$, we also have $I_h = 0$, $E_v = 0$ and $I_v = 0$. Substituting $E_h = I_h = E_v = I_v = 0$ in the first, fourth and

401 fifth equation of Eq. (15) with $\delta = 0$ gives $S_h(t) \rightarrow S_h^0 = N_h^0$, $R_h(t) \rightarrow 0$, and $S_v(t) \rightarrow S_v^0 = N_v^0$
 402 as $t \rightarrow \infty$. Thus

$$[S_h(t), E_h(t), I_h(t), R_h(t), S_v(t), E_v(t), I_v(t), E(t), L(t), P(t)] \rightarrow (N_h^0, 0, 0, 0, N_v^0, 0, 0, E, L, P)$$

as $t \rightarrow \infty$.

403 It follows from the LaSalle's invariance principle [46, 47, 48] that every solution of (15) (when
 404 $\mathcal{R}_{nv, \delta=0} \leq 1$), with initial conditions in \mathcal{D}_2 converges to \mathcal{E}_1^{nv} , as $t \rightarrow \infty$. Hence, the DFE, \mathcal{E}_1^{nv} ,
 405 of model (15) without disease-induced death, is GAS in \mathcal{D}_2 if $\mathcal{R}_{nv, \delta=0} \leq 1$. \square

406 3.3.2 Analysis of the model with mass action incidence

407 Consider the model (2) with mass action incidence. Thus, the associated forces of infection, λ_h^c
 408 and λ_v^c , respectively, reduce to

$$\lambda_{mh} = C_h(\eta_v E_v + I_v) \quad \text{and} \quad \lambda_{mv} = C_v(\eta_h E_h + I_h), \quad (21)$$

where, $C_h = a(1 - \alpha_1)\beta_{hv}$ and $C_v = a(1 - \alpha_1)\beta_{vh}$. The resulting model (mass action model),
 obtained by using (21) in (2), has the same disease-free equilibria given by (5). Without lost
 of generality, we consider that $\mathcal{N} > 1$. The associated next generation matrices, F_m and V_m
 are given by

$$F_m = \begin{pmatrix} 0 & 0 & C_h \eta_v H^0 & C_h H^0 \\ 0 & 0 & 0 & 0 \\ C_v \eta_v S_v^0 & C_v S_v^0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad V_m = \begin{pmatrix} k_3 & 0 & 0 & 0 \\ -\gamma_h & k_4 & 0 & 0 \\ 0 & 0 & k_9 & 0 \\ 0 & 0 & -\gamma_v & k_8 \end{pmatrix},$$

409 where $H^0 = S_h^0 + \pi V_h^0$. It follows that the associated reproduction number for the mass action
 410 model, denoted by $\mathcal{R}_{0,m} = \rho(F_m V_m^{-1})$, is given by

$$\mathcal{R}_{0,m} = \sqrt{\mathcal{R}_{hv}^m \mathcal{R}_{vh}^m}, \quad (22)$$

411 where

$$\mathcal{R}_{hv}^m = \left(\frac{C_h \Lambda_h (\gamma_h + k_4 \eta_h) (\pi \xi + k_2)}{\mu_h k_3 k_4 (\xi + k_2)} \right) \quad \text{and} \quad \mathcal{R}_{vh}^m = \left(\frac{C_v (\gamma_v + k_8 \eta_v) \theta P}{k_8^2 k_9} \right).$$

413 Using Theorem 2 of [33], the following result is established:

414 **Theorem 10.** Assume that $\mathcal{N} > 1$. For the arboviral disease model with mass action incidence,
 415 given by (2) with (21), the DFE, \mathcal{E}_1 , is LAS if $\mathcal{R}_{0,m} < 1$, and unstable if $\mathcal{R}_{0,m} > 1$

416 **Existence of endemic equilibria** Solving the equations in the model (15) in terms of λ_{mh}^*
 417 and λ_{mv}^* , gives

$$\begin{aligned} S_{mh}^* &= \frac{\Lambda_h (\pi \lambda_{mh}^{c,*} + k_2)}{\lambda_{mh}^{c,*} (k_2 + \pi (k_1 + \lambda_{mh}^{c,*})) + k_1 k_2 - \omega \xi}, & V_{mh}^* &= \frac{\xi S_{mh}^*}{k_2 + \pi \lambda_{mh}^{c,*}}, \\ E_{mh}^* &= \frac{\lambda_{mh}^{c,*} S_{mh}^*}{k_3}, & I_{mh}^* &= \frac{\gamma_h \lambda_{mh}^{c,*} S_{mh}^*}{k_3 k_4}, & R_{mh}^* &= \frac{\sigma \gamma_h \lambda_{mh}^{c,*} S_{mh}^*}{\mu_h k_3 k_4}, \end{aligned} \quad (23)$$

418 and

$$S_{mv}^* = \frac{\theta P}{(\lambda_{mv}^{c,*} + k_8)}, \quad E_{mv}^* = \frac{\theta P \lambda_{mv}^{c,*}}{k_9 (\lambda_{mv}^{c,*} + k_8)}, \quad I_{mv}^* = \frac{\gamma_v \theta P \lambda_{mv}^{c,*}}{k_8 k_9 (\lambda_{mv}^{c,*} + k_8)}. \quad (24)$$

Substituting (23) and (24) into the expression of λ_{mh}^* and λ_{mv}^* and simplifying, shows that the nonzero equilibria of the model without vaccination satisfy the quadratic equation

$$e_2(\lambda_{mh}^{c,*})^2 + e_1\lambda_{mh}^{c,*} + e_0 = 0, \quad (25)$$

where e_i , $i = 0, 1, 2$, are given by

$$\begin{aligned} e_2 &= k_8 k_9 \pi [(\gamma_h + k_4 \eta_h) C_v \Lambda_h + k_3 k_4 k_8] \\ e_1 &= \frac{k_3 k_4 k_8^2 k_9 \kappa \pi}{(\pi \xi + k_2)} (\mathcal{R}_{cm}^2 - \mathcal{R}_{0,m}^2), \\ e_0 &= k_3 k_4 k_8^2 k_9 \kappa (1 - \mathcal{R}_{0,m}^2), \end{aligned}$$

with $\kappa = k_1 k_2 - \xi \omega > 0$ and

$$\mathcal{R}_{cm} = \sqrt{\frac{[(\gamma_h + k_4 \eta_h) (\pi \xi + k_2) \Lambda_h C_v + (k_1 \pi + k_2) k_3 k_4 k_8] (\pi \xi + k_2)}{k_3 k_4 k_8 \kappa \pi}}.$$

e_2 is always positive and e_0 is positive (resp. negative) whenever $R_{0,m}$ is less (resp. greater) than unity. Thus, the mass action model admits only one endemic equilibria whenever $\mathcal{R}_{0,m} > 1$.

Now, we consider the case $\mathcal{R}_{0,m} < 1$. The occurrence of backward bifurcation phenomenon depend of the sign of coefficient e_1 . The coefficient e_1 is always positive if and only if $R_{0,m} < \mathcal{R}_{cm}$. It follows that the disease-free equilibrium is the unique equilibrium when $\mathcal{N} > 1$ and $\mathcal{R}_{cm} < 1$. Now if $\mathcal{R}_{cm} < \mathcal{R}_{0,m} < 1$, then in addition to the DFE \mathcal{E}_1 , there exists two endemic equilibria whenever $\Delta_m = e_1^2 - 4e_2e_0 > 0$. However, $\mathcal{R}_{cm} < \mathcal{R}_{0,m} < 1 \Rightarrow \mathcal{R}_{cm} < 1 \Leftrightarrow \beta_{vh} < -\frac{k_3 k_4 k_8 (\xi \omega \pi + k_1 \pi^2 \xi + k_2 (\pi \xi + k_2))}{a(1 - \alpha_1) (\gamma_h + k_4 \eta_h) (\pi \xi + k_2) (\pi \xi + k_2) \Lambda_h} < 0$. Since all parameter of model are non-negative, we conclude that the condition $\mathcal{R}_{cm} < \mathcal{R}_{0,m} < 1$ does not hold. And thus, the model with mass-action incidence does not admit endemic equilibria for $\mathcal{R}_{cm} < 1$.

Global stability of the DFE for the model with mass action incidence Since the DFE of the model with mass action incidence is the unique equilibrium whenever the corresponding basic reproduction number $R_{0,m}$ is less than unity, it remains to show that the DFE is gas. To this aim, we use the direct Lyapunov method. Let us define the following positive constants:

$$p_1 = \frac{1}{k_3}, p_2 = \frac{C_h H^0 (\eta_v k_8 + \gamma_v)}{k_8 k_9} \frac{C_v S_v^0}{k_3 k_4}, p_3 = p_1 C_h H^0 \frac{(\eta_v k_8 + \gamma_v)}{k_8 k_9}, p_4 = \frac{C_h H^0}{k_3 k_8}.$$

Consider the Lyapunov function

$$\mathcal{L} = p_1 E_h + p_2 I_h + p_3 E_v + p_4 I_v.$$

The derivative of \mathcal{L} is given by

$$\begin{aligned} \dot{\mathcal{L}} &= p_1 \dot{E}_h + p_2 \dot{I}_h + p_3 \dot{E}_v + p_4 \dot{I}_v \\ &= (p_1 C_h \eta_v H + p_4 \gamma_v - p_3 k_9) E_v + (p_1 C_h H - p_4 k_8) I_v \\ &\quad + (p_3 C_v \eta_h S_v + p_2 \gamma_h - p_1 k_3) E_h + (p_3 C_v S_v - p_2 k_4) I_h \end{aligned}$$

Replacing p_i , $i = 1, \dots, 4$, by their respective term, and using the fact that $H = (S_h + \pi V_h) \leq H^0 = (S_h^0 + \pi V_h^0)$ and $S_v \leq N_v^0$ in

$$\mathcal{D}_3 = \left\{ (S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P) \in \mathcal{D} : N_h \leq \frac{\Lambda_h}{\mu_h}, S_v \leq N_v^0 = \theta P, E \leq K_E, L \leq K_L, P \leq \frac{l K_L}{k_7 k_8} \right\},$$

we obtain $\dot{\mathcal{L}} \leq (R_{0,m}^2 - 1) E_h$.

We have $\dot{\mathcal{L}} \leq 0$ if $R_{0,m} \leq 1$, with $\dot{\mathcal{L}} = 0$ if $R_{0,m} = 1$ or $E_h = 0$. Whenever $E_h = 0$, we also have $I_h = 0$, $E_v = 0$ and $I_v = 0$. Substituting $E_h = I_h = E_v = I_v = 0$ in the first, fourth and fifth equation of Eq. (15) with mass action incidence gives $S_h(t) \rightarrow S_h^0$, $V_h(t) \rightarrow V_h^0$, $R_h(t) \rightarrow 0$, and $S_v(t) \rightarrow S_v^0 = N_v^0$ as $t \rightarrow \infty$. Thus

$$\begin{aligned} & [S_h(t), V_h(t), E_h(t), I_h(t), R_h(t), S_v(t), E_v(t), I_v(t), E(t), L(t), P(t)] \\ & \rightarrow (S_h^0, V_h^0, 0, 0, 0, N_v^0, 0, 0, E, L, P) \quad \text{as } t \rightarrow \infty. \end{aligned}$$

It follows from the LaSalle's invariance principle [46, 47, 48], that every solution of (2) with mass action incidence, with initial conditions in \mathcal{D}_3 converges to the DFE, as $t \rightarrow \infty$. Hence, the DFE, \mathcal{E}_1 , of the model with mass action incidence, is GAS in \mathcal{D}_3 if $R_{0,m} \leq 1$.

Thus, we claim the following result.

Theorem 11. *The DFE, \mathcal{E}_1 , of the model (2) with mass action incidence, is globally asymptotically stable (GAS) in \mathcal{D}_3 if $R_{0,m} < 1$.*

Thus, the substitution of standard incidence with mass action incidence in the arboviral model (2) removes the backward bifurcation phenomenon of the model. It should be mentioned that a similar situation was reported by Garba *et al.* in [19] and by Sharomi *et al.* in [38].

We summarize the previous analysis of Subsection 3.3 as follows:

Lemma 3. *The main causes of occurrence of backward bifurcation phenomenon in models (2) and (15) are the disease-induced death and the standard incidence rates.*

4 Sensitivity analysis

As shown in the previous sections, model (2) may admit single or multiple steady states according to the value of the basic reproduction number \mathcal{R}_0 . In turn, \mathcal{R}_0 depends on the parameters of the model. The various uncertainties encountered in data collection and the estimated values leads us to evaluate the robustness of the model predictions with the parameter values and, in particular, to estimate the effect on \mathcal{R}_0 of varying single parameters. To this aim, we use sensitivity analysis and calculate the sensitivity indices of \mathcal{R}_0 to the parameters in the model using both local and global methods.

4.1 Local sensitivity analysis

The local sensitivity analysis, based on the *normalised sensitivity index* of \mathcal{R}_0 (see [49]), is given by

$$S_\Psi = \frac{\Psi}{\mathcal{R}_0} \frac{\partial \mathcal{R}_0}{\partial \Psi}$$

where Ψ denotes the generic parameter of (2).

This index indicates how sensitive \mathcal{R}_0 is to changes of parameter Ψ . Clearly, a positive (resp. negative) index indicates that an increase in the parameter value results in an increase (resp. decrease) in the \mathcal{R}_0 value [49].

For instance, the computation of the sensitivity index of \mathcal{R}_0 with respect to a is given by

$$S_a = \frac{a}{\mathcal{R}_0} \frac{\partial \mathcal{R}_0}{\partial a} = 1 > 0.$$

Table 4: Parameter values using to compute the sensitivity indices of \mathcal{R}_0 .

Parameter	value	Parameter	value	Parameter	value
c_m	0.01	s	0.7	β_{vh}	0.75
μ_b	6	η_2	0.3	Γ_E	10000
μ_P	0.4	μ_E	0.2	Γ_L	5000
θ	0.08	ϵ	0.61	α_2	0.5
l	0.5	Λ_h	2.5	μ_h	$\frac{1}{67 \times 365}$
a	1	β_{hv}	0.75	η_v	0.35
μ_v	$\frac{1}{30}$	μ_L	0.4	σ	0.1428
γ_h	$\frac{1}{14}$	η_h	0.35	γ_v	$\frac{1}{21}$
ξ	0.5	ω	0.05	η_1	0.001
δ	0.001	α_1	0.2		

Table 5: Sensitivity indices of \mathcal{R}_0 to parameters of model (2), evaluated at the baseline parameter values given in Table 4.

Parameter	Index	Parameter	Index	Parameter	Index
a	+1	σ	-0.2911	ξ	-0.0566
μ_v	-0.9190	c_m	-0.2757	ω	+0.0565
ϵ	-0.6223	α_1	-0.25	μ_E	-0.0171
s	+0.5172	η_h	+0.2067	δ	-0.0020
Λ_h	-0.5	γ_h	-0.2064	η_1	-0.0000858
$\beta_{hv}, \beta_{vh}, \Gamma_E, \Gamma_L, \alpha_2$	+0.5	η_v	+0.1207		
μ_h	+0.4996	γ_v	+0.1174		
μ_P	-0.4810	μ_L	-0.1026		
θ	+0.4810	μ_b	+0.0772		
l	+0.4489	η_2	-0.0770		

This shows that \mathcal{R}_0 is an increasing function of a and the parameter a has an influence on the spread of disease.

We tabulate the indices of the remaining parameters in Table 2 using parameter values on Table 4. The results, displayed in Table 5 and Figure 7a. The parameters are arranged from most sensitive to least. The model system (2) is most sensitive to a , the average number of mosquitoes bites, followed by μ_v , ϵ , s , Λ_h , β_{hv} , β_{vh} , Γ_E , Γ_L and α_2 . It is important to note that increasing (decreasing) a by 10% increases (decreases) \mathcal{R}_0 by 10%. However, increasing (decreasing) the parameters μ_v by 10% decreases (increases) \mathcal{R}_0 by 9.190%. The same reasoning can be done for other parameters.

4.2 Uncertainty and global sensitivity analysis

Local sensitivity analysis assesses the effects of individual parameters at particular points in parameter space without taking into account of the combined variability resulting from considering all input parameters simultaneously. Here, we perform a global sensitivity analysis to examine the model's response to parameter variation within a wider range in the parameter space.

Following the approach by Marino *et al.* [50] and Wu *et al.* [51], partial rank correlation

coefficients (PRCC) between the basic reproduction number \mathcal{R}_0 and each parameter are derived from 5,000 runs of the Latin hypercube sampling (LHS) method [52]. The parameters are assumed to be random variables with uniform distributions with its mean value listed in Table 4.

With these 5,000 runs of LHS, the derived distribution of \mathcal{R}_0 is given in Figure 6. This sampling shows that the mean of \mathcal{R}_0 is 2.0642 and the standard deviation is 2.6865. The probability that $\mathcal{R}_0 > 1$ is 54.86%. This implies that for the mean of parameter values given in Table 4, we may be confident that the model predicts a endemic state.

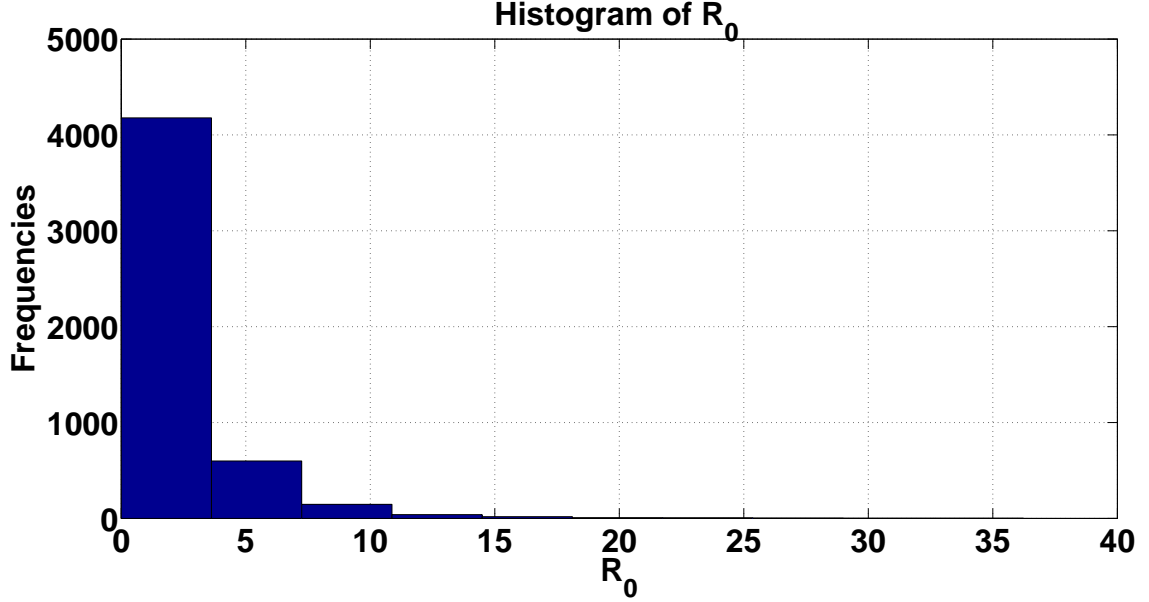


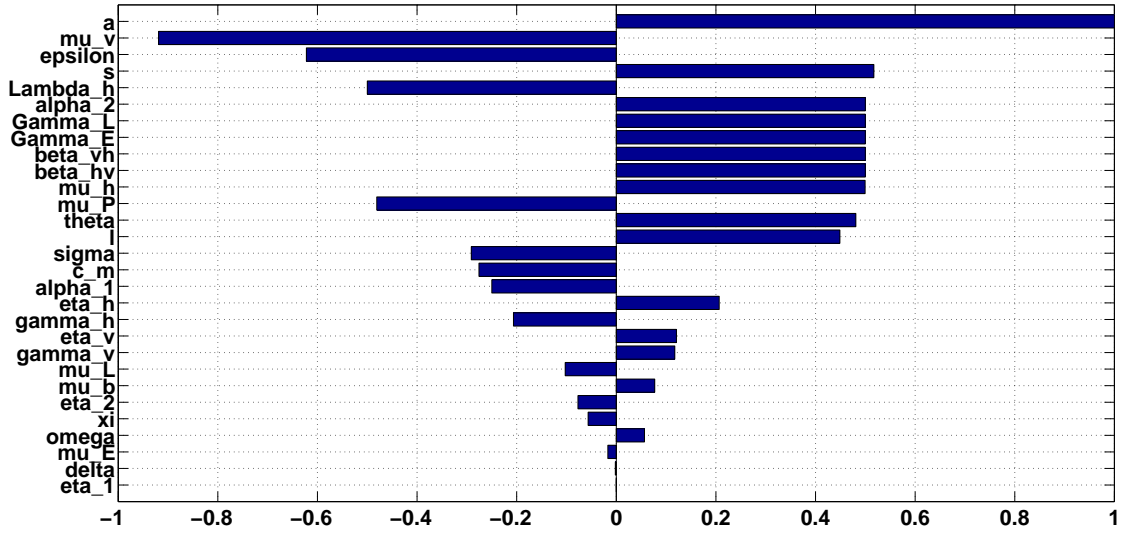
Figure 6: Sampling distribution of \mathcal{R}_0 from 5,000 runs of Latin hypercube sampling. The mean of \mathcal{R}_0 is 2.0642 and the standard deviation is 2.6865. Furthermore, $\mathbb{P}(\mathcal{R}_0 > 1) = 0.5486$.

We now use sensitivity analysis to analyse the influence of each parameter on the basic reproductive number. From the previously sampled parameter values, we compute the PRCC between \mathcal{R}_0 and each parameter of model (2). The parameters with large PRCC values (> 0.5 or < -0.5) statistically have the most influence [51]. The results, displayed in Table 6 and Figure 7 (b), show that the parameters α_1 , the human protection rate, has the highest influence on \mathcal{R}_0 . This suggests that individual protection may potentially be the most effective strategy to reduce \mathcal{R}_0 . The other parameter with an important effect are α_2 , β_{hv} , β_{vh} and θ .

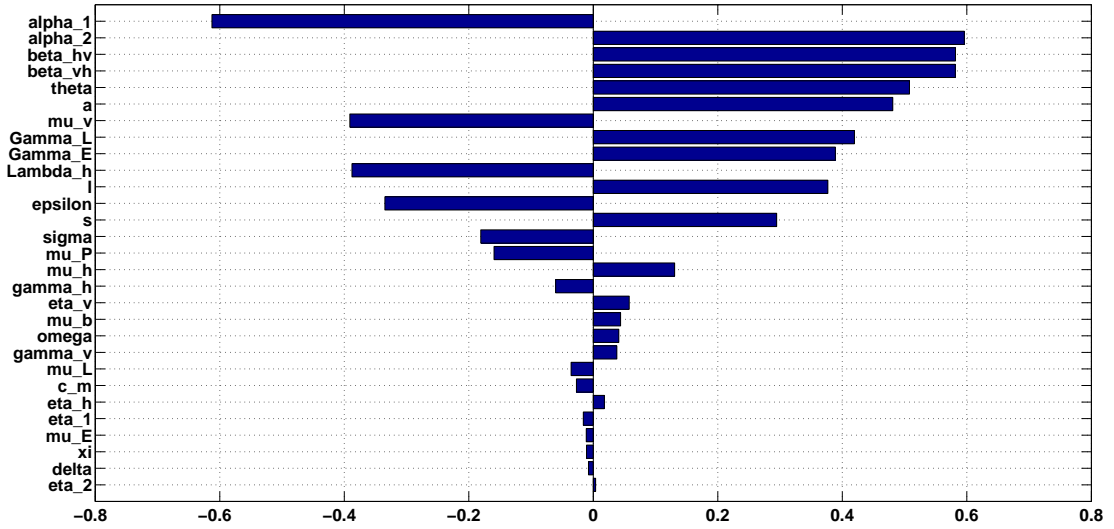
We note that the order of the most important parameters for \mathcal{R}_0 from the local sensitivity analysis does not match that of the global sensitivity analysis, showing that the local results are not robust.

Table 6: Partial Rank Correlation Coefficients between \mathcal{R}_0 and each parameters of model (2).

Para- meter	Correlation Coefficients	Para- meter	Correlation Coefficients	Para meter	Correlation Coefficients
α_1	-0.6125	l	0.3767	γ_v	0.0378
α_2	0.5960	ϵ	-0.3348	μ_L	-0.0357
β_{hv}	0.5817	s	0.2945	c_m	-0.0271
β_{vh}	0.5815	σ	-0.1808	η_h	0.0178
θ	0.5078	μ_P	-0.1594	η_1	-0.0161
a	0.4810	μ_h	0.1306	μ_E	-0.0113
μ_v	-0.3911	γ_h	-0.0605	ξ	-0.0109
Γ_L	0.4195	η_v	0.0578	δ	-0.0077
Γ_E	0.3888	μ_b	0.0439	η_2	0.0037
Λ_h	-0.3876	ω	0.0410		



(a) Local sensitivity indices for \mathcal{R}_0



(b) Partial rank correlation coefficients for \mathcal{R}_0

Figure 7: Local (a) and global (b) sensitivity indices for \mathcal{R}_0 against model parameters show that the local sensitivity results are not robust: the order of the most important parameters for \mathcal{R}_0 from the local sensitivity analysis not match those from the global sensitivity analysis.

5 Numerical simulations and discussions

In the previous model [26], we have shown that the use of a vaccine with efficacy of about 60%, was to be accompanied by other control measurements such as means of personal protection (Information in relation to the damage caused by these diseases, spanning wearing clothes during hours of vector activity, use of repellents), vector control (combining the use of adulticide to kill adult vectors, chemical control with use of larvicide to kill the eggs and larvae, and mechanical control to reduce the number of breeding sites at least near inhabited areas) [15]. Here, we investigate and compare numerical results, with the different scenario. We use the

514 following initial state variables $S_h(0) = 700$, $V_h(0) = 10$, $E_h(0) = 220$, $I_h(0) = 100$, $R_h(0) = 60$,
515 $S_v(0) = 3000$, $E_v(0) = 400$, $I_v(0) = 120$, $E(0) = 10000$, $L = 5000$, $P = 3000$.

516 **5.1 Strategy A: Vaccination combined with individual protection** 517 **only**

518 In this strategy, we consider the model (2) without vector control. we set $\alpha_2 = 1$ and $c_m = \eta_1 =$
519 $\eta_2 = 0$ and vary the parameter related to individual protection, namely α_1 , between 0 and 0.8.
520 The values of other parameters are given in Table 4. Figure 8 shows that the increase of the
521 individual protection level, permit to reduce the total number of infected humans, and the total
522 number of infected vectors, but has no impact on the populations of eggs and larvae. However,
523 from this figure, it is clear that, this reduction is significant if the level of protection must turn
524 around 80% at least, and this, over a long period. Thus, continuous education campaigns of
525 people, on how to protect themselves individually, are important in the fight against the spread
526 of arboviral diseases.

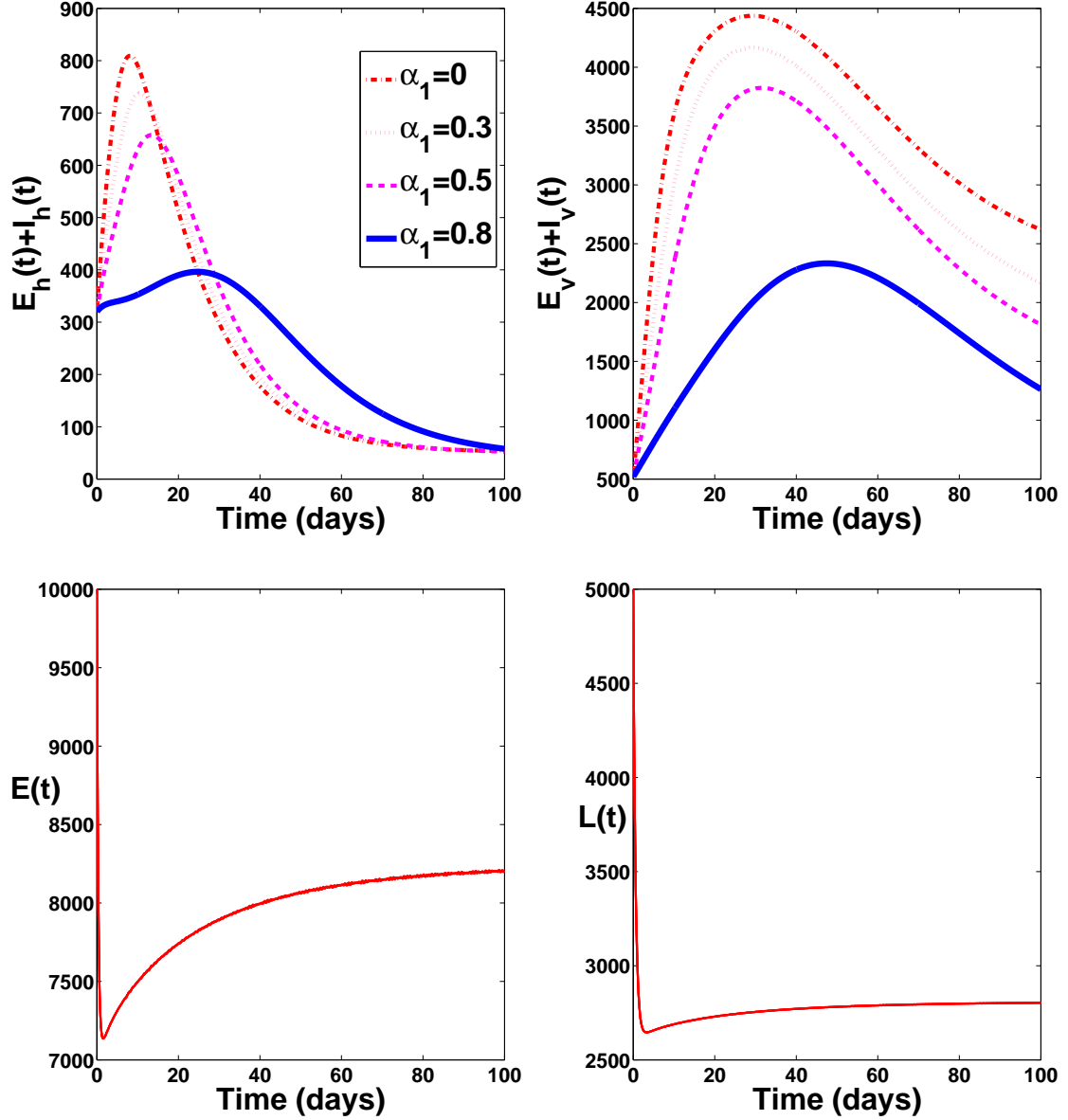


Figure 8: Simulations results showing how the total number of infected humans and the total number of infected vectors decrease when the individual protection increase. All others parameters values are in Table 4.

5.2 Strategy B: Vaccination combined with adulticide

Nowadays, Deltamethrin is the most used insecticide for impregnation of bednets, because it is a highly effective compound on mosquitoes at of very low doses [53]. However, when sprayed in an open environment, Deltamethrin seems to be effective only during a couple of hours [15, 54, 55]. Also, its use over a long period and continuously, leads to strong resistance of the wild populations of *Aedes aegypti*, for example [53]. The mortality of the mosquitoes after spraying varied between 20% and 80%. To be more realistic, we will consider the technique called "pulse control" (the control is not continuous in time order is effective only one day every T days) [15]. To this aims, we consider that spraying is carried out once a week, and this, for 100 days. We set $\alpha_1 = \eta_1 = \eta_2 = 0$ and $\alpha_2 = 1$.

Simulation result on figure 9 show that a mortality rate induced by the use of larvicide, c_m , greater than 60% has a significant impact on the decrease of the total number of infected humans and vectors, and on the decrease of eggs and larvae.

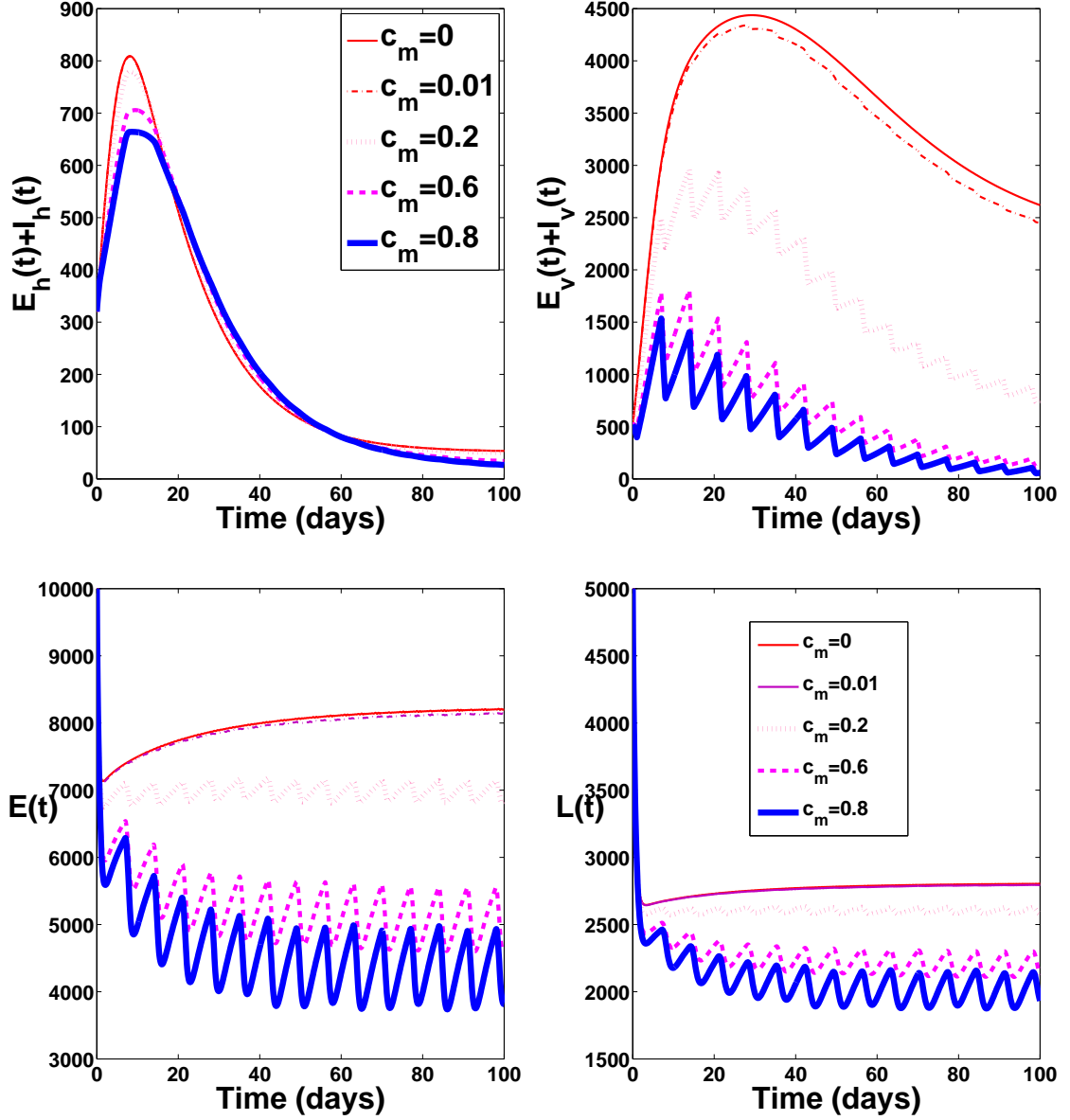


Figure 9: Simulations results showing how the total number of infected vectors, eggs and larvae populations decrease when the aldulticide control parameter c_m increase. All others parameters values are in Table 4.

5.3 Strategy C: Vaccination combined with larvicide

Since the efficacy and the duration of a larvicide (*Bti*=*Bacillus thuringiensis* var. *israelensis*) strongly depend on several factors like water quality, exposure, and even the type of breeding sites, we thus consider, to be more realistic, that the duration can vary between a couple of days and two weeks [15, 56]. We consider that the larvicide spraying happens once every 15 days, and this, on a period of 100 days. We set $\alpha_1 = c_m = 0$ and $\alpha_2 = 1$.

546 The figure 10 shows that the use of larvicide has no significant impact on the decrease of
547 total number of infected humans and vectors, as well as on the number of eggs and larvae. This
548 can be justified by the fact that the use of conventional larvicides requires certain constraints
549 on their use: they can not be used continuously, their duration of action decreases with time. In
550 addition, eggs of certain populations of vectors such as *Aedes albopictus*, come into prolonged
551 hibernation when conditions in the breeding sites are not conducive to their good growth (this
552 is justified by the control rate value $\eta_1 = 0.001$). Also, the pupae do not consume anything,
553 until reaching the mature stage.

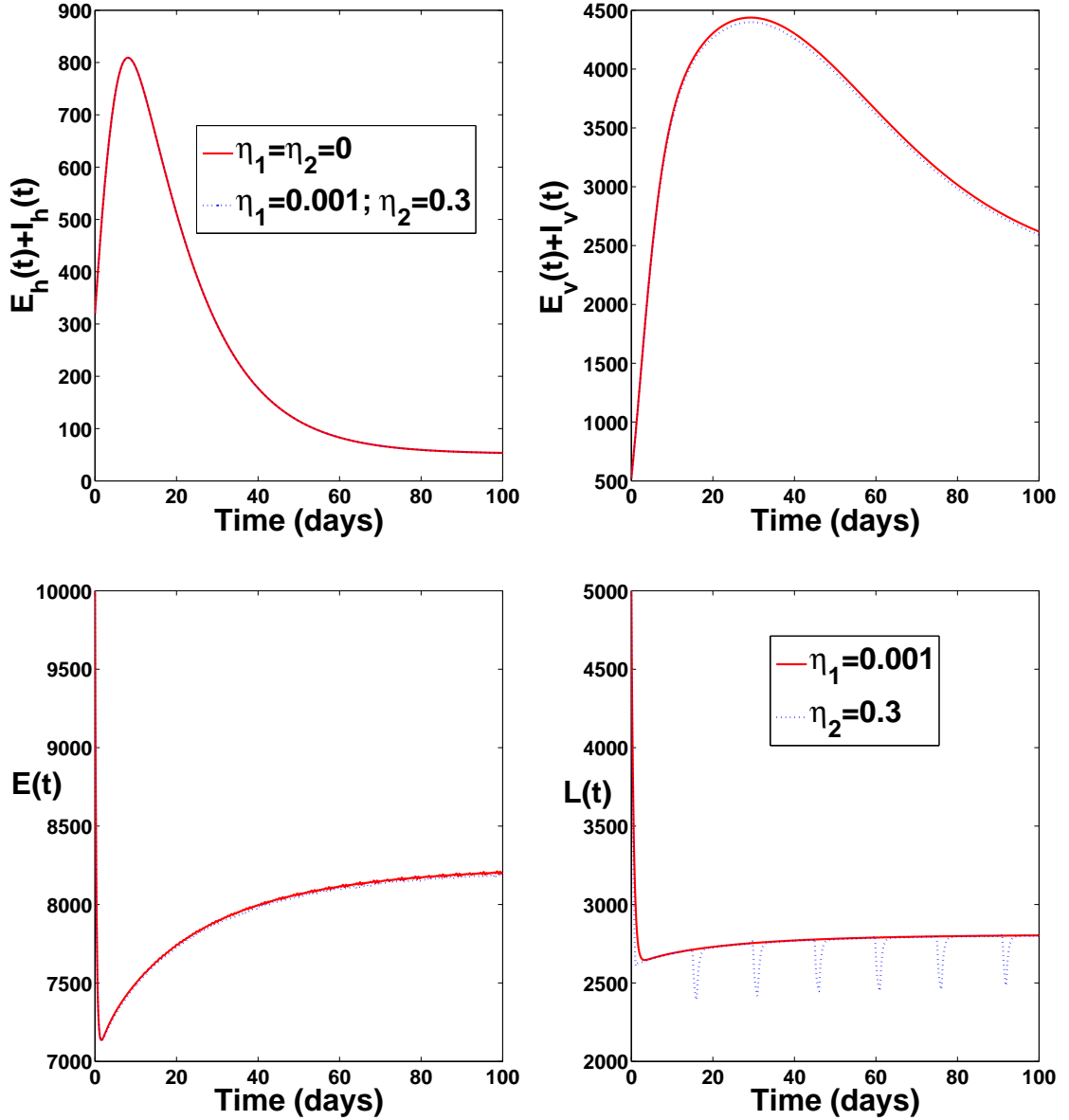


Figure 10: Simulations results showing how the total number of infected humans, the total number of infected vectors, and the eggs and larvae populations decrease with the larvicide control associated parameters η_1 and η_2 . All others parameters values are in Table 4.

5.4 Strategy D: Vaccination combined with mechanical control

The effectiveness of this type of control depends largely on awareness campaigns of local people in the sense that, to reduce the proliferation of vectors, people should always destroy, and systematically, potential breeding sites. Thus, we consider that this type of control can be achieved by local populations, and this, every daily. We set $\alpha_1 = c_m = 0 = \eta_1 = \eta_2$.

The figure 11 shows that this type of control is appropriate in the fight against the proliferation of vectors. This can only be possible by that by the multiplication of local populations awareness campaigns.

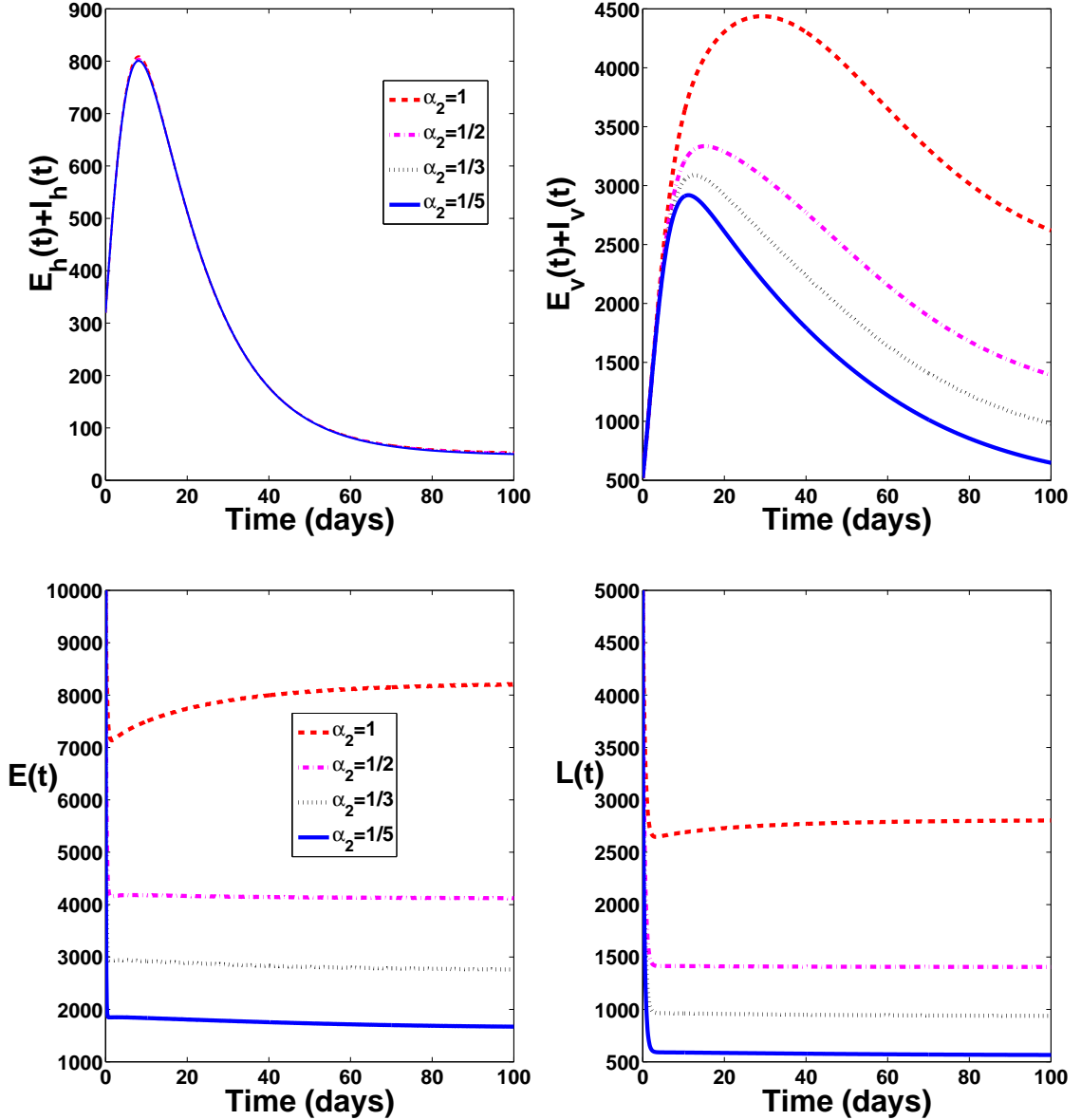


Figure 11: Simulations results showing how the total number of infected vectors, eggs and larvae populations decrease with the mechanical control associated parameter α_2 . All others parameters values are in Table 4.

5.5 Strategy E: Combining vaccination, individual protection and aduicide

In this strategy, we consider the model (2) without larvicide and mechanical control. we set $\alpha_2 = 1$ and $\eta_1 = \eta_2 = 0$ and vary the parameter related to individual protection and the use of aduicide, namely α_1 and c_m , respectively, between 0 and 0.8. The values of other parameters are given in Table 4. Figure 12 shows that the use of the combination of these controls decreases significantly the total number of infected humans, infected vectors as well as the number of eggs and larvae, when its associated rates, namely α_1 and c_m , are greater than 0.3 and 0.2, respectively.

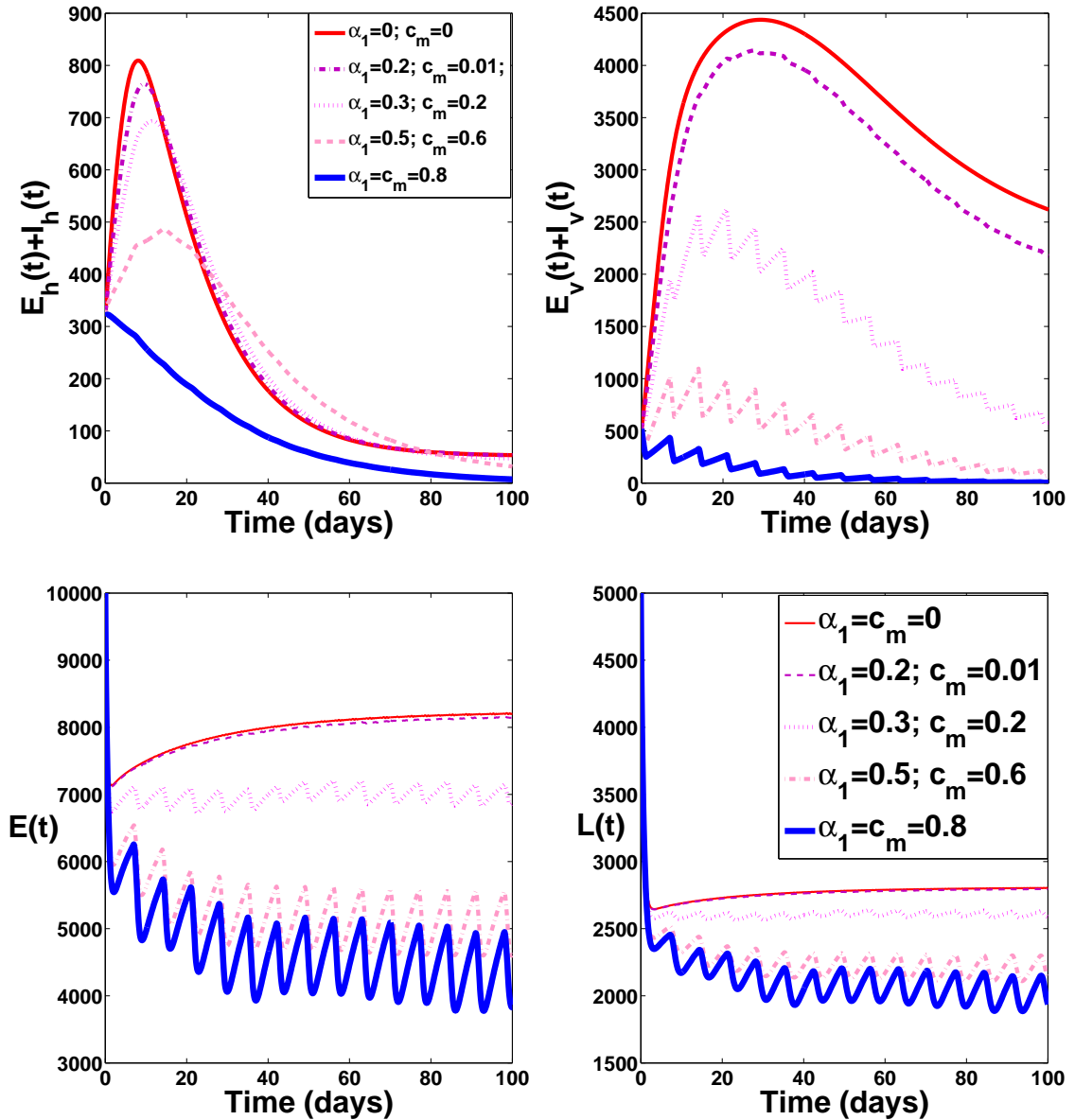


Figure 12: Simulations results showing the advantage that we have to combine vaccination, individual protection and aduicide.

5.6 Strategy F: Combining vaccination, individual protection and mechanical control

Like for strategy E, the simulations results on figure 13 show that the combined use of these three types of controls has a positive impact in the vector control.

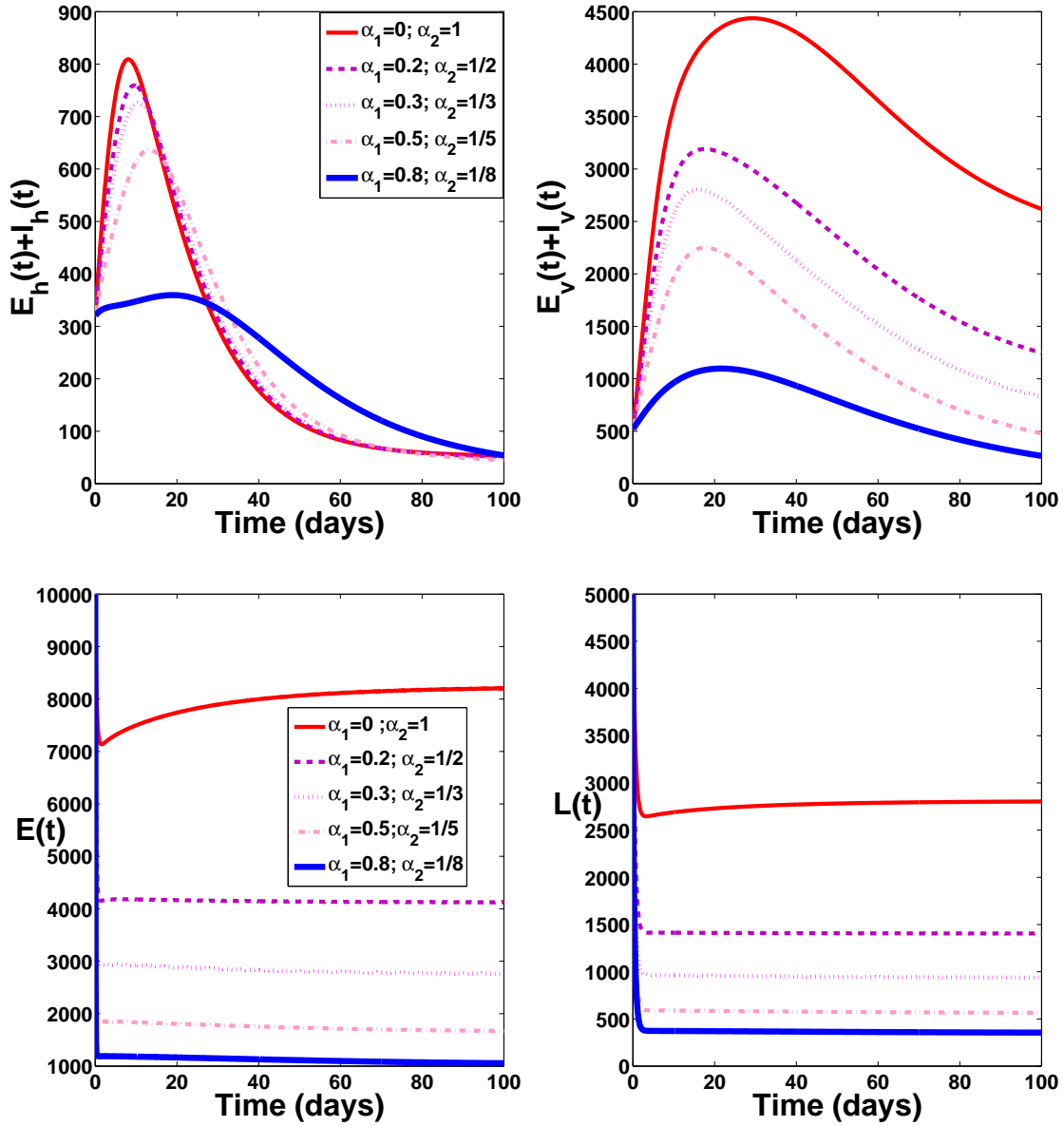


Figure 13: Simulations results showing the advantage that we have to combine vaccination, individual protection and mechanical control.

6 Conclusion

In this paper, we derived and analysed a deterministic model for the transmission of arboviral diseases with non linear form of infection and complete stage structured model for vectors, which takes into account a vaccination with waning immunity, individual protection and vector control strategies.

We begin by calculated the net reproductive number \mathcal{N} and the basic reproduction number, \mathcal{R}_0 , and investigated the existence and stability of equilibria. The stability analysis reveals that for $\mathcal{N} \leq 1$, the trivial equilibrium is globally asymptotically stable. When $\mathcal{N} > 1$ and $\mathcal{R}_0 < 1$, the disease-free equilibrium is locally asymptotically stable. Under certain condition, the disease-free equilibrium is also globally asymptotically stable. We found that the model exhibits backward bifurcation. The epidemiological implication of this phenomenon is that for effective eradication and control of diseases, \mathcal{R}_0 should be less than a critical values less than one. Thus, we proved, that the disease-induced death is the principal cause of the backward bifurcation phenomenon, in the full model and the corresponding model without vaccination. However, the substitution of standard incidence with mass action incidence removes the backward bifurcation phenomenon.

We proved that the model admits at least one endemic equilibrium, and only one endemic equilibrium point in the model without disease-induced death, and in the model with mass action incidences, whenever the basic reproduction number is great than unity.

Using parameters value of Chikungunya and Dengue fever, we calculated the sensitivity indices of the basic reproduction number, \mathcal{R}_0 , to the parameters in the model using both local and global methods. Local sensitivity analysis showed that the model system is most sensitive to a , the average number of mosquitoes bites, followed by μ_v , the natural mortality rate of vectors. Considering that all input parameters vary simultaneously, we use the Latin Hypercube Sampling (LHS) to estimate statistically the mean value of the basic reproduction number. The result showed that the model is in an endemic state, since the mean of \mathcal{R}_0 is 2.0642, which is greater than unity. Then, using global sensitivity analysis, we computed the Partial Rank Correlation Coefficients between \mathcal{R}_0 and each parameter of the model. Unlike the local sensitivity analysis, the global analysis showed that the parameters α_1 , the human protection rate, has the highest influence on \mathcal{R}_0 . The other parameter with an important effect are α_2 , the efficacy of the mechanical control, β_{hv} , the probability of transmission of infection from an infectious vector to a susceptible human, β_{vh} , the probability of transmission of infection from an infectious human to a susceptible vector, and θ , the maturation rate from pupae to adult vectors. This showed that the order of the most important parameters for \mathcal{R}_0 from the local sensitivity analysis not match those from the global sensitivity analysis. So, the local sensitivity results are not robust.

To assess the impact of combination of different controls, we conduct several simulations, using the called "pulse control" technique. According to the numerical results, we conclude that the use of an imperfect vaccine with low efficiency combined with high individual protection and good vector control strategy (reduction of breeding sites by local populations action, chemical action using adulticides and larvicides), can effectively reduce the transmission of the pathogen and the proliferation of vector populations. However, due to lack of resources to implement these control mechanisms, developing countries should focus on the education of the local populations. Because, unlike diseases such as malaria whose breeding sites of *Anopheles* mosquitoes are known, those of arboviruses (old tires, flower pots, vases and other hollow...) are smaller and unknown for many local populations, which favour the development of vectors.

Thus, pending the development of a high efficacy vaccine and long-acting, individual protection and the various vector control methods are effective ways to combat the arboviruses, for developing countries. In addition, the realization of the combination of these controls may be too expensive, because it means that, for constant controls, we must keep them at levels high, and this, for a long time. Thus it is important to know what happens when, instead of the constant controls, we use time dependent controls, in optimal control theory. This represents a perspective of this work.

Acknowledgement

The first author (H. A) thanks the Direction of UIT of Ngaoundere for their financial assistance in the context of research missions in 2015.

A Useful result.

We use the following result, which is the characterization of Metzler matrices, to compute the threshold \mathcal{R}_c , obtained at Eq. (10).

Lemma 4 ([35]). *Let M be a square Metzler matrix written in block form $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with A and D square matrices. M is Metzler stable if and only if matrices A and $D - CA^{-1}B$ are Metzler stable.*

B Proof of Theorem 1.

The Jacobian matrix of f at the Trivial equilibrium is given by

$$Df(\mathcal{E}_0) = \begin{pmatrix} Df_1 & Df_2 \\ Df_3 & Df_4 \end{pmatrix}. \quad (26)$$

where

$$Df_1 = \begin{pmatrix} -k_1 & \omega & 0 & 0 & 0 & 0 \\ \xi & -k_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & -k_3 & 0 & 0 & 0 \\ 0 & 0 & \gamma_h & -k_4 & 0 & 0 \\ 0 & 0 & 0 & \sigma & -\mu_h & 0 \\ 0 & 0 & 0 & 0 & 0 & -k_8 \end{pmatrix}, \quad Df_3 = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \mu_b \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix},$$

$$Df_2 = \begin{pmatrix} -\frac{a(1-\alpha_1)\beta_{hv}\eta_v S_h^0}{N_h^0} & -\frac{a(1-\alpha_1)\beta_{hv}S_h^0}{N_h^0} & 0 & 0 & 0 \\ -\frac{a(1-\alpha_1)\beta_{hv}\pi\eta_v V_h^0}{N_h^0} & -\frac{a(1-\alpha_1)\beta_{hv}\pi V_h^0}{N_h^0} & 0 & 0 & 0 \\ \frac{a(1-\alpha_1)\beta_{hv}\eta_v H^0}{N_h^0} & \frac{a(1-\alpha_1)\beta_{hv}H^0}{N_h^0} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \theta \end{pmatrix},$$

$$Df_4 = \begin{pmatrix} -k_9 & 0 & 0 & 0 & 0 \\ \gamma_v & -k_8 & 0 & 0 & 0 \\ \mu_b & \mu_b & -k_5 & 0 & 0 \\ 0 & 0 & s & -k_6 & 0 \\ 0 & 0 & 0 & l & -k_7 \end{pmatrix}, \quad \text{and } H^0 = S_h^0 + \pi V_h^0.$$

The characteristic polynomial of $Df(\mathcal{E}_0)$ is given by:

$$P(\lambda) = -(\lambda + k_3)(\lambda + k_4)(\lambda + k_8)(\lambda + k_9)(\lambda + \mu_h)\phi_1(\lambda)\phi_2(\lambda)$$

where

$\phi_1(\lambda) = \lambda^2 + (k_2 + k_1)\lambda + \mu_h(k_2 + \xi)$ and $\phi_2(\lambda) = \lambda^4 + A_1\lambda^3 + A_2\lambda^2 + A_3\lambda + A_4$. we have set

$$A_1 = k_5 + k_6 + k_7 + k_8, \quad A_2 = k_8(k_5 + k_6 + k_7) + k_7(k_5 + k_6) + k_5k_6, \\ A_3 = k_5k_6k_7 + k_8(k_5k_6 + k_7(k_5 + k_6)), \quad A_4 = k_5k_6k_7k_8(1 - \mathcal{N}).$$

The roots of $P(\lambda)$ are $\lambda_1 = -\mu_h$, $\lambda_1 = -k_1$, $\lambda_2 = -k_3$, $\lambda_3 = -k_4$, $\lambda_4 = -k_8$, $\lambda_4 = -k_9$, and the others roots are the roots of $\phi_1(\lambda)$ and $\phi_2(\lambda)$. The real part of roots of $\phi_1(\lambda)$ are negative. Since $\mathcal{N} < 1$, it is clear that all coefficients of $\phi_2(\lambda)$ are always positive. Now we just have to verify that the Routh–Hurwitz criterion holds for polynomial $\phi_2(\lambda)$. To this aim, setting

$$H_1 = A_1, H_2 = \begin{vmatrix} A_1 & 1 \\ A_3 & A_2 \end{vmatrix}, H_3 = \begin{vmatrix} A_1 & 1 & 0 \\ A_3 & A_2 & A_1 \\ 0 & A_4 & A_3 \end{vmatrix}, H_4 = \begin{vmatrix} A_1 & 1 & 0 & 0 \\ A_3 & A_2 & A_1 & 1 \\ 0 & A_4 & A_3 & A_2 \\ 0 & 0 & 0 & A_4 \end{vmatrix} = A_4 H_3.$$

The Routh–Hurwitz criterion of stability of the trivial equilibrium \mathcal{E}^0 is given by

$$\begin{cases} H_1 > 0 \\ H_2 > 0 \\ H_3 > 0 \\ H_4 > 0 \end{cases} \Leftrightarrow \begin{cases} H_1 > 0 \\ H_2 > 0 \\ H_3 > 0 \\ A_4 > 0 \end{cases} \quad (27)$$

We have $H_1 = A_1 = k_5 + k_6 + k_7 + k_8 > 0$,

$$\begin{aligned} H_2 &= A_1 A_2 - A_3 \\ &= (k_7 + k_6 + k_5) k_8^2 + (k_7^2 + (2k_6 + 2k_5) k_7 + k_6^2 + 2k_5 k_6 + k_5^2) k_8 \\ &\quad + (k_6 + k_5) k_7^2 + (k_6^2 + 2k_5 k_6 + k_5^2) k_7 + k_5 k_6^2 + k_5^2 k_6 \end{aligned}$$

653

$$\begin{aligned} H_3 &= A_1 A_2 A_3 - A_1^2 A_4 - A_3^2 \\ &= (k_6 + k_5) (k_7^2 + (k_6 + k_5) k_7 + k_5 k_6) k_8^3 \\ &\quad + (\mu_b l s \theta + (k_6 + k_5) k_7^3 + 2(k_6 + k_5)^2 k_7^2 + (k_6^3 + 4k_5 k_6^2 + 4k_5^2 k_6 + k_5^3) k_7 + k_5 k_6^3 + 2k_5^2 k_6^2 + k_5^3 k_6) k_8^2 \\ &\quad + [(2k_7 + 2k_6 + 2k_5) \mu_b l s \theta + (k_6^2 + 2k_5 k_6 + k_5^2) k_7^3 + (k_6^3 + 4k_5 k_6^2 + 4k_5^2 k_6 + k_5^3) k_7^2 \\ &\quad + (2k_5 k_6^3 + 4k_5^2 k_6^2 + 2k_5^3 k_6) k_7 + k_5^2 k_6^3 + k_5^3 k_6^2] k_8 + (k_7^2 + (2k_6 + 2k_5) k_7 + k_6^2 + 2k_5 k_6 + k_5^2) \mu_b l s \theta \\ &\quad + (k_5 k_6^2 + k_5^2 k_6) k_7^3 + (k_5 k_6^3 + 2k_5^2 k_6^2 + k_5^3 k_6) k_7^2 + (k_5^2 k_6^3 + k_5^3 k_6^2) k_7 \end{aligned}$$

We always have $H_1 > 0$, $H_2 > 0$, $H_3 > 0$ and $H_4 > 0$ if $\mathcal{N} < 1$. Thus, the trivial equilibrium \mathcal{E}_0 is locally asymptotically stable whenever $\mathcal{N} < 1$.

We assume the net reproductive number $\mathcal{N} > 1$. Following the procedure and the notation in [33], we may obtain the basic reproduction number \mathcal{R}_0 as the dominant eigenvalue of the *next-generation matrix* [32, 33]. Observe that model (2) has four infected populations, namely E_h , I_h , E_v , I_v . It follows that the matrices F and V defined in [33], which take into account the new infection terms and remaining transfer terms, respectively, are given by

$$F = \begin{pmatrix} 0 & 0 & \frac{\tau \beta_{hv} \eta_v H^0}{N_h^0} & \frac{\tau \beta_{hv} H^0}{N_h^0} \\ 0 & 0 & 0 & 0 \\ \frac{\tau \beta_{vh} \eta_v S_v^0}{N_h^0} & \frac{\tau \beta_{vh} S_v^0}{N_h^0} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \text{ and } V = \begin{pmatrix} k_3 & 0 & 0 & 0 \\ -\gamma_h & k_4 & 0 & 0 \\ 0 & 0 & k_9 & 0 \\ 0 & 0 & -\gamma_v & k_8 \end{pmatrix}, \text{ with}$$

$\tau = a(1 - \alpha_1)$. The dominant eigenvalue of the next-generation matrix FV^{-1} is given by (7). The local stability of the disease-free equilibrium \mathcal{E}_1 is a direct consequence of Theorem 2 of [33]. This ends the proof.

C Proof of Theorem 2.

Setting $Y = X - TE$ with $X = (S_h, V_h, E_h, I_h, R_h, S_v, E_v, I_v, E, L, P)^T$, $H^0 = (S_h^0 + \pi V_h^0)$, $A_{99} = \left(k_5 + \mu_b \frac{S_v + E_v + I_v}{K_E}\right)$, and $A_{10} = \left(k_6 + s \frac{E}{K_L}\right)$. we can rewrite (2) in the following

$$\frac{dY}{dt} = \mathcal{B}(Y)Y \quad (28)$$

669 where $\mathcal{B}(Y) = \begin{pmatrix} A(Y) & B(Y) \\ C(Y) & D(Y) \end{pmatrix}$, with

$$\begin{aligned} 670 \quad A(Y) &= \begin{pmatrix} -(\lambda_h^c + k_1) & \omega & 0 & 0 & 0 & 0 \\ \xi & -(\pi\lambda_h^c + k_2) & 0 & 0 & 0 & 0 \\ \lambda_h^c & \pi\lambda_h^c & -k_3 & 0 & 0 & 0 \\ 0 & 0 & \gamma_h & -k_4 & 0 & 0 \\ 0 & 0 & 0 & \sigma & -\mu_h & 0 \end{pmatrix}, \\ 671 \quad B(Y) &= \begin{pmatrix} -\frac{a(1-\alpha_1)\beta_{hv}\eta_v S_h^0}{N_h} & -\frac{a(1-\alpha_1)\beta_{hv}S_h^0}{N_h} & 0 & 0 & 0 \\ -\frac{a(1-\alpha_1)\beta_{hv}\eta_v\pi V_h^0}{N_h} & -\frac{a(1-\alpha_1)\beta_{hv}\pi V_h^0}{N_h} & 0 & 0 & 0 \\ \frac{a(1-\alpha_1)\beta_{hv}\eta_v H^0}{N_h} & \frac{a(1-\alpha_1)\beta_{hv}H^0}{N_h} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \\ 672 \quad C(Y) &= \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & -(\lambda_v^c + k_8) \\ 0 & 0 & 0 & 0 & 0 & \lambda_v^c \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \mu_b \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \quad D(Y) = \begin{pmatrix} 0 & 0 & 0 & 0 & \theta \\ -k_9 & 0 & 0 & 0 & 0 \\ \gamma_v & -k_8 & 0 & 0 & 0 \\ \mu_b & \mu_b & -A_{99} & 0 & 0 \\ 0 & 0 & s & -A_{10} & 0 \\ 0 & 0 & 0 & l & -k_7 \end{pmatrix}. \end{aligned}$$

673 It is clear that $Y = (0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0)$ is the only equilibrium. Then it suffices to con-
 674 sider the following Lyapunov function $\mathcal{L}(Y) = \langle g, Y \rangle$ where $g = \left(1, 1, 1, 1, 1, 1, 1, \frac{k_8}{\mu_b}, \frac{k_5 k_8}{\mu_b s}, \frac{k_5 k_6 k_8}{\mu_b sl}\right)$.
 675 Straightforward computations lead that

$$\begin{aligned} \dot{\mathcal{L}}(Y) &= \langle g, \dot{Y} \rangle \stackrel{\text{def}}{=} \langle g, \mathcal{B}(Y)Y \rangle \\ &= -\mu_h Y_1 - \mu_h Y_2 - \mu_h Y_3 - (\mu_h + \delta)Y_4 - \mu_h Y_5 \\ &\quad - \frac{k_8}{K_E}(Y_6 + Y_7 + Y_8) - \frac{k_5 k_8}{\mu_b K_L} Y_9 Y_{10} + \theta \left(1 - \frac{1}{\mathcal{N}}\right) Y_{11} \end{aligned}$$

676 We have $\dot{\mathcal{L}}(Y) < 0$ if $\mathcal{N} \leq 1$ and $\dot{\mathcal{L}}(Y) = 0$ if $Y_i = 0$, $i = 1, 2, \dots, 11$ (i.e $S_h = S_h^0$, $V_h = V_h^0$
 677 and $E_h = I_h = R_h = S_v = E_v = I_v = E = L = P = 0$). Moreover, the maximal invariant
 678 set contained in $\{\mathcal{L} | \dot{\mathcal{L}}(Y) = 0\}$ is $(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0)$. Thus, from Lyapunov theory, we
 679 deduce that $(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0)$ and thus, \mathcal{E}_0 , is GAS if and only if $\mathcal{N} \leq 1$.

680 D Proof of Theorem 5.

681 In order to determine the existence of endemic equilibria, i. e. equilibria with all positive
 682 components, say

$$\mathcal{E}^{**} = (S_h^*, V_h^*, E_h^*, I_h^*, R_h^*, S_v^*, E_v^*, I_v^*, E, L, P),$$

683 we have to look for the solution of the algebraic system of equations obtained by equating the
 684 right sides of system (2) to zero. In this way we consider two case:

685 **(i) Special case: Absence of disease-induced death in human ($\delta = 0$)** Note that in the
 686 absence of disease-induced death in human population, we have $N_h^* = N_h^0 = \Lambda_h / \mu_h$. Let

$$\lambda_h^{c,*} = \frac{a(1 - \alpha_1)\beta_{hv}(\eta_v E_v^* + I_v^*)}{N_h^*}, \quad \lambda_v^{c,*} = \frac{a(1 - \alpha_1)\beta_{vh}(\eta_h E_h^* + I_h^*)}{N_h^*} \quad (29)$$

687 be the forces of infection of humans and vectors at steady state, respectively. Solving the
 688 equations in (2) at steady state gives

$$\begin{aligned} S_h^* &= \frac{\Lambda_h(\pi\lambda_h^{c,*} + k_2)}{\mu_h(k_2 + \xi) + \lambda_h^{c,*}(\pi\lambda_h^{c,*} + \pi k_1 + k_2)}, \quad V_h^* = \frac{\xi S_h^*}{(\pi\lambda_h^{c,*} + k_2)}, \\ E_h^* &= \frac{\lambda_h^{c,*}(S_h^* + \pi V_h^*)}{k_3}, \quad I_h^* = \frac{\gamma_h \lambda_h^{c,*}(S_h^* + \pi V_h^*)}{k_3 k_4}, \quad R_h^* = \frac{\sigma \gamma_h \lambda_h^{c,*}(S_h^* + \pi V_h^*)}{\mu_h k_3 k_4}, \end{aligned} \quad (30)$$

689 and

$$\begin{aligned} S_v^* &= \frac{\theta P}{(\lambda_v^{c,*} + k_8)}, \quad E_v^* = \frac{\theta P \lambda_v^{c,*}}{k_9(\lambda_v^{c,*} + k_8)}, \quad I_v^* = \frac{\gamma_v \theta P \lambda_v^{c,*}}{k_8 k_9(\lambda_v^{c,*} + k_8)}, \\ E &= \frac{\mu_b \theta K_E P}{(k_5 k_8 K_E + \mu_b \theta P)}, \quad L = \frac{\mu_b \theta s K_E K_L P}{k_6 K_L (k_5 k_8 K_E + \mu_b \theta P) + s \mu_b \theta K_E P}, \end{aligned} \quad (31)$$

690 where P is solution of the following equation

$$f(P) = -k_7 P [\mu_b \theta (s K_E + k_6 K_L) P + k_5 k_6 k_8 K_E K_L (\mathcal{N} - 1)] = 0 \quad (32)$$

691 A direct resolution of the above equation give $P = 0$ or $P = \frac{k_5 k_6 k_8 K_E K_L (\mathcal{N} - 1)}{\mu_b \theta (s K_E + k_6 K_L)}$.

692 Note that $P = 0$ corresponds to the trivial equilibrium \mathcal{E}_0 . Now we consider $P > 0$ i.e.
 693 $\mathcal{N} > 1$. Replacing (30) and (31) in (29) give

$$\lambda_h^{c,*} = \frac{a(1 - \alpha_1)\beta_{hv}\mu_h}{\Lambda_h} \left(\eta_v \frac{\theta P \lambda_v^*}{k_9(\lambda_v^* + k_8)} + \frac{\gamma_v \theta P \lambda_v^*}{k_8 k_9(\lambda_v^* + k_8)} \right) \quad (33)$$

694

$$\lambda_v^{c,*} = \frac{a(1 - \alpha_1)\beta_{vh}\mu_h}{\Lambda_h} \left(\eta_h \frac{\lambda_h^*(S_h^* + \pi V_h^*)}{k_3} + \frac{\gamma_h \lambda_h^*(S_h^* + \pi V_h^*)}{k_3 k_4} \right) \quad (34)$$

695 Substuting (34) in (33) give

$$(k_6 K_L + s K_E) \lambda_h^* [a_2 (\lambda_h^*)^2 + a_1 \lambda_h^* + a_0] = 0 \quad (35)$$

696 where a_2 , a_1 and a_0 are given by

$$\begin{aligned} R_b &= \frac{(\pi\xi + k_2)}{\pi(\xi + k_2)} \left(\frac{(k_1\pi + k_2)}{\mu_h} + \frac{a(1 - \alpha_1)\beta_{vh}(\gamma_h + k_4\eta_h)(\pi\xi + k_2)}{k_3 k_4 k_8} \right), \\ a_2 &= (a(1 - \alpha_1)\beta_{vh}\mu_h(\gamma_h + k_4\eta_h) + k_3 k_4 k_8) k_9 \mu_b \Lambda_h \pi, \\ a_1 &= \frac{k_3 k_4 k_8 k_9 \mu_b \Lambda_h (\xi + k_2) \mu_h \pi}{(\pi\xi + k_2)} (R_b - R_1), \\ a_0 &= \mu_h k_3 k_4 k_8 k_9 \mu_b \Lambda_h (\xi + k_2) (1 - R_1). \end{aligned} \quad (36)$$

697 The trivial solution $\lambda_h^* = 0$ of (35) corresponds to the disease-free equilibrium \mathcal{E}_1 . Now, we
 698 just look the equilibria when $\lambda_h^* > 0$. Note that coefficient a_2 is always positive and a_0 is less
 699 (resp. greater) than unity if and only if $R_1 > 1$ (resp. $R_1 < 1$). Thus model system (2),
 700 in absence of disease-induced death in human population ($\delta = 0$), admits only one endemic
 701 equilibrium whenever $\mathcal{R}_0 > 1$. Since the sign of coefficient a_1 depend of the value of parameter,

we investigate the possibility of occurrence of backward bifurcation phenomenon when $\mathcal{R}_0 < 1$. Furthermore, consider the inequality

$$R_1 \leq R_b. \quad (37)$$

Since a_2 is always positive and a_0 is always positive whenever $\mathcal{R}_0 < 1$, then, the occurrence of backward bifurcation phenomenon depend of the sign of coefficient a_1 . The coefficient a_1 is always positive if and only if condition (37) holds (i.e $R_1 < R_b$). It follows that the disease-free equilibrium is the unique equilibrium when $\mathcal{N} > 1$ and $\mathcal{R}_0 < 1$. Now if $R_b < R_1 < 1$, then in addition to the DFE \mathcal{E}_1 , there exists two endemic equilibria whenever $\Delta = a_1^2 - 4a_2a_0 > 0$. However, $R_b < R_1 < 1 \Rightarrow R_b < 1 \Leftrightarrow \beta_{vh} < -\frac{[\pi^2\xi^2 + (\mu_h\pi^2 + (2\omega + \mu_h)\pi)\xi + (\omega + \mu_h)^2]k_3k_4k_8}{a(1 - \alpha_1)\mu_h(\pi\xi + k_2)^2(\gamma_h + k_4\eta_h)} < 0$. Since all parameter of model (2) are nonnegative, we conclude that the condition $R_b < R_1 < 1$ does not hold. And thus, the backward bifurcation never occurs in the absence of disease-induced death in human.

(ii) Presence of disease induced death in human ($\delta \neq 0$)

In this case, we have $N_h^* = \frac{\Lambda_h - \delta I_h^*}{\mu_h}$. Applying the same procedure as case (i), we obtain that λ_h^* at steady state is solution of the following equation

$$f(\lambda_h^*) = \lambda_h^* [c_4(\lambda_h^*)^4 + c_3(\lambda_h^*)^3 + c_2(\lambda_h^*)^2 + c_1\lambda_h^* + c_0] = 0, \quad (38)$$

where

$$c_4 = -\pi^2 k_9 K_{12} \mu_b \Lambda_h (k_3 k_4 - \delta \gamma_h) (k_{10} a \mu_h (1 - \alpha_1) \beta_{vh} + k_8 (k_3 k_4 - \delta \gamma_h)),$$

$$\begin{aligned} c_3 = & \pi (k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1)^2 \beta_{hv} n \pi \beta_{vh} K_E K_L + 2k_9 k_{10} K_{12} a \mu_b \delta \Lambda_h \mu_h \gamma_h \pi (1 - \alpha_1) \beta_{vh} \xi \\ & - k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \pi (1 - \alpha_1) \beta_{vh} \xi - 2k_8 k_9 K_{12} \mu_b \delta^2 \Lambda_h \gamma_h^2 \pi \xi + 2k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \pi \xi \\ & - k_1 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \pi (1 - \alpha_1) \beta_{vh} + 2k_2 k_9 k_{10} K_{12} a \mu_b \delta \Lambda_h \mu_h \gamma_h (1 - \alpha_1) \beta_{vh} \\ & - 2k_2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h (1 - \alpha_1) \beta_{vh} + 2k_1 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \pi - 2k_1 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \pi \\ & - 2k_2 k_8 k_9 K_{12} \mu_b \delta^2 \Lambda_h \gamma_h^2 + 4k_2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h - 2k_2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h), \end{aligned}$$

$$\begin{aligned} c_2 = & k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1)^2 \beta_{hv} n \pi^2 \beta_{vh} \xi K_E K_L \\ & + k_1 k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1)^2 \beta_{hv} n \pi^2 \beta_{vh} K_E K_L \\ & + 2k_2 k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1)^2 \beta_{hv} n \pi \beta_{vh} K_E K_L + k_9 k_{10} K_{12} a \mu_b \delta \Lambda_h \mu_h \gamma_h \pi^2 (1 - \alpha_1) \beta_{vh} \xi^2 \\ & - k_8 k_9 K_{12} \mu_b \delta^2 \Lambda_h \gamma_h^2 \pi^2 \xi^2 - k_1 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \pi^2 (1 - \alpha_1) \beta_{vh} \xi \\ & + k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \omega \pi (1 - \alpha_1) \beta_{vh} \xi + 2k_2 k_9 k_{10} K_{12} a \mu_b \delta \Lambda_h \mu_h \gamma_h \pi (1 - \alpha_1) \beta_{vh} \xi \\ & - k_2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \pi (1 - \alpha_1) \beta_{vh} \xi + 2k_1 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \pi^2 \xi \\ & - 2k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \omega \pi \xi + 2k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \omega \pi \xi - 2k_2 k_8 k_9 K_{12} \mu_b \delta^2 \Lambda_h \gamma_h^2 \pi \xi \\ & + 2k_2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \pi \xi - 2k_1 k_2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h (1 - \alpha_1) \pi \beta_{vh} \\ & + k_2^2 k_9 k_{10} K_{12} a \mu_b \delta \Lambda_h \mu_h \gamma_h (1 - \alpha_1) \beta_{vh} - k_2^2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h (1 - \alpha_1) \beta_{vh} \\ & - k_1^2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \pi^2 + 4k_1 k_2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \pi - 4k_1 k_2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \pi \\ & - k_2^2 k_8 k_9 K_{12} \mu_b \delta^2 \Lambda_h \gamma_h^2 + 2k_2^2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h - k_2^2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h, \end{aligned}$$

$$\begin{aligned} c_1 = & ((k_1 k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1) \beta_{hv} n \pi^2 + k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1)^2 \beta_{hv} n (k_2 - \omega) \pi) \beta_{vh} \xi \\ & + (2k_1 k_2 k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1) \beta_{hv} n \pi + k_2^2 k_3 k_4 k_5 k_6 k_{10} k_{11} a^2 \mu_h^2 (1 - \alpha_1) \beta_{hv} n) (1 - \alpha_1) \beta_{vh}) K_E K_L \\ & + (k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \omega \pi (1 - \alpha_1) \beta_{vh} - 2k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h \omega \pi) \xi^2 \\ & + ((k_2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \omega - k_1 k_2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h \pi) (1 - \alpha_1) \beta_{vh} \\ & + (2k_1 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \omega + 2k_1 k_2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h) \pi \\ & + (2k_2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h - 2k_2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h) \omega) \xi \\ & - k_1 k_2^2 k_3 k_4 k_9 k_{10} K_{12} a \mu_b \Lambda_h \mu_h (1 - \alpha_1) \beta_{vh} - 2k_1^2 k_2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \pi \\ & + 2k_1 k_2^2 k_3 k_4 k_8 k_9 K_{12} \mu_b \delta \Lambda_h \gamma_h - 2k_1 k_2^2 k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h, \end{aligned}$$

$$c_0 = k_3^2 k_4^2 k_8 k_9 K_{12} \mu_b \Lambda_h \mu_h^2 (k_2 + \xi)^2 (R_0^2 - 1),$$

with $k_{10} = \gamma_h + \eta_h k_4$, $k_{11} = \gamma_v + \eta_v k_8$, $K_{12} = (sK_E + k_6 K_L)$ and $n = \mathcal{N} - 1$. Notes that c_4 is always negative and c_0 is positive (resp. negative) if \mathcal{R}_0 is greater (resp. less) than the unity. It follows, depending of the sign of coefficients c_3 , c_2 and c_1 , that the model system (2) admits at least one endemic equilibrium whenever $\mathcal{R}_0 > 1$ and the phenomenon of backward (resp. forward) bifurcation can occur when $\mathcal{R}_0 < 1$ (resp. $\mathcal{R}_0 > 1$). This ends the proof.

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