

#### Combinatorial optimization with multiple resources and energy constraints

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Sandra Ulrich Ngu	énergétiques multiples (OREM) - PGMO project (2013-2015) - 1st year gueveu, Christian Artigues and Pierre Lopez
	gueveu, Unristian Artigues and Pierre Lopez
$T$ . $\Delta$	
	AAS-CNRS, Toulouse, France
ODEM project context and objectives	Conorio problem . Cohoduling with non reversible on erry
OREM project : context and objectives	Generic problem : Scheduling with non-reversible energy sources
<b>Context</b> ntegration of energy constraints in deterministic scheduling models, such as job-shop schedulin	ing or
rce-constrained project scheduling, yields a combinatorial optimization challenge. It follows that	
ature on this subject is sparse. Pre-existing studies involve multiple energy sources and general non-li ency functions, but generally no scheduling. All our previous work on scheduling under energy constra	-linear $-$ Set of time time periods $T$

efficiency functions, but generally no scheduling. All our previous work on scheduling under energy constraints considered linear (and even identical) energy efficiency functions, which oversimplifies the problem.

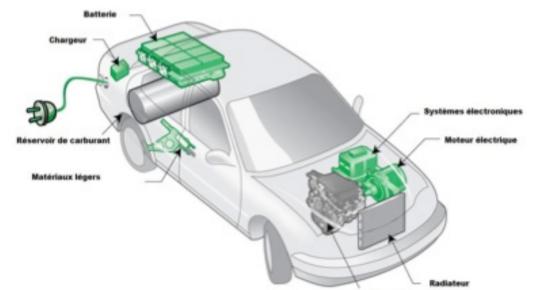
 $-b_i$ : constant instantaneous energy demand of activity i-Set of non-reversible energy sources S $-\rho^{s}$ : piecewise-linear efficiency function for source s (x-axis = cost, y-axis = demand and  $\rho^s(x) = 0, \forall x < 0, \forall s \in \mathcal{S}$ ).  $-a_{it}$ : constant term equal to 1 if  $t \in [r_i, d_i]$  and 0 otherwise

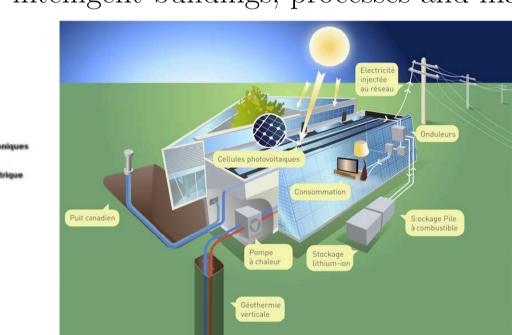
#### Objectives

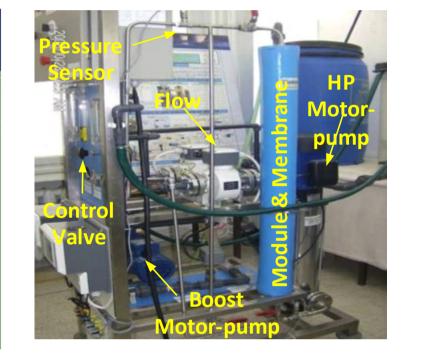
- -Address the (combinatorial) optimization challenge of integrating energy sources constraints (physical, technological and performance characteristics) in deterministic (scheduling) models.
- -Solve explicitly and in an integrated fashion the resulting energy resource allocation problems and energyconsuming activity scheduling problems with non linear energy efficiency functions.

# Applications and challenge

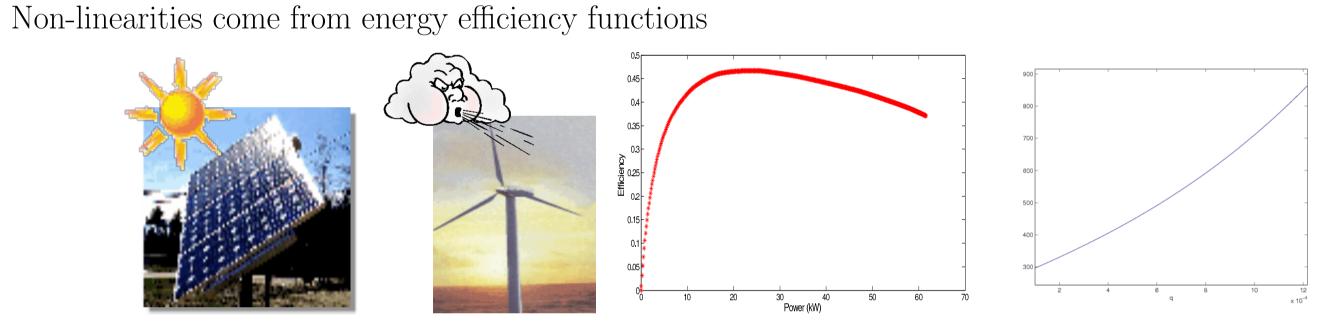
#### Applications Scheduling for hybrid electric vehicles, intelligent buildings, processes and manufacturing

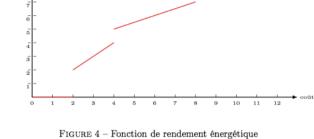






## Challenge

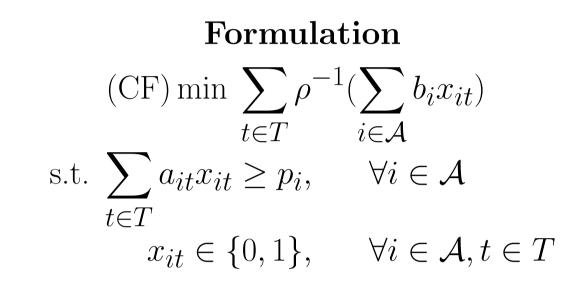




## Decision variables

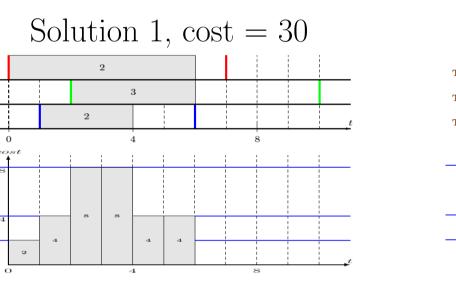
 $-x_{it}$ : binary, = 1 iff activity *i* is ongoing at time period *t* 

 $-r_i, d_i, p_i$ : release date, due date, duration of activity i



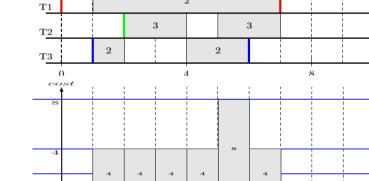
#### Complexity and equivalence between single and multiple sources

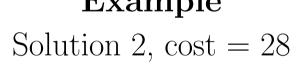
-**Theorem 1** The problem is NP hard by reduction from discrete bin packing -Theorem 2 For any problem with multiple sources, there is an equivalent single source problem



#### Example

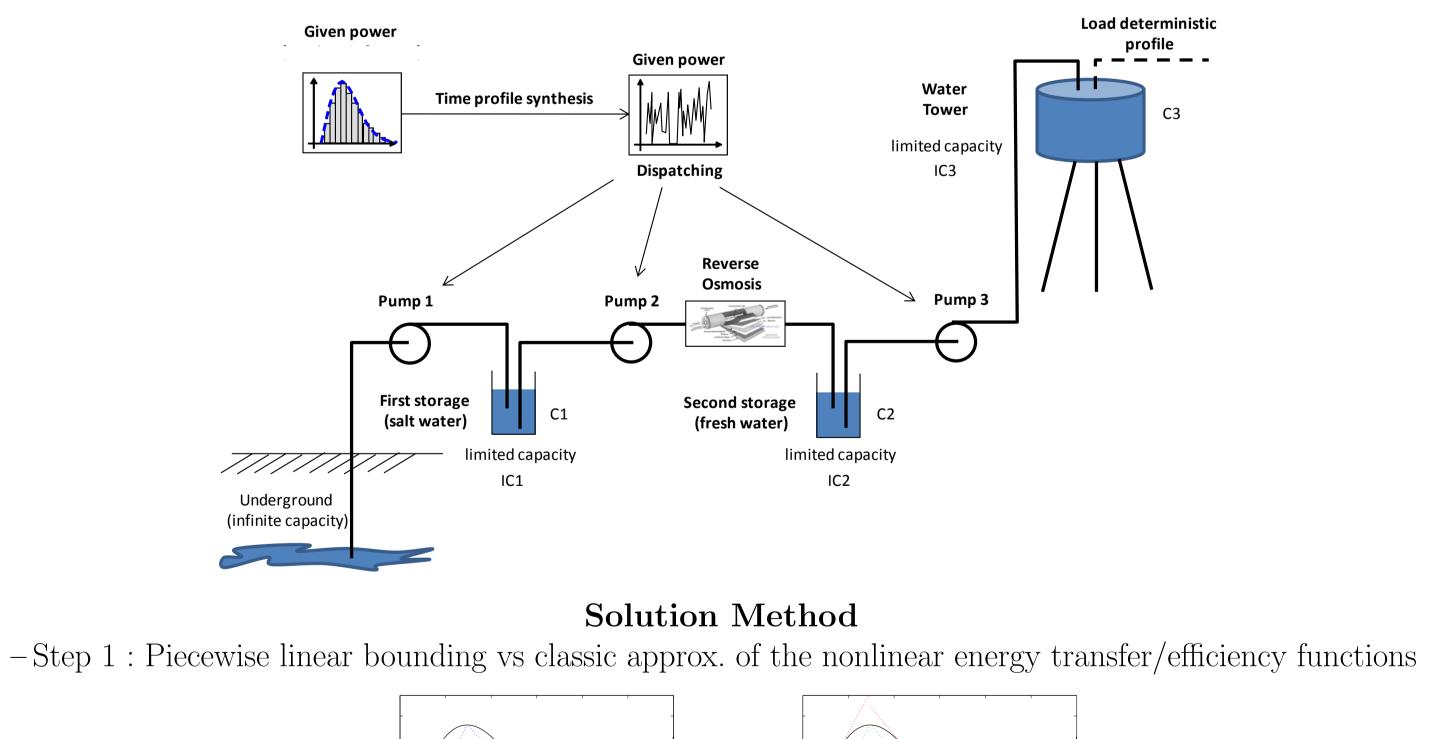
# Solution 3, $\cos t = 26$ 3





Piecewise linear bounding procedures for the optimal management of water pumping and desalination processes

Proof of concept on a water pumping and desalination system [CLAIO 2014, IFORS 2014]



# Dantzig-Wolfe decomposition and Branch&Price Method

Extended formulation based on feasible subsets of activities

-Set of activity sets executable in parallel  $\mathcal{L}$  (at any given time period  $\overline{L}_t$ ) -Set of activities belonging to set l: demand  $b_l$ , cost  $c_l$ , time window  $[R_l, D_l]$  $-a_{il}$ : binary constant term equal to 1 iff *i* belongs to set *l* -Variable  $y_{lt}$ : binary, = 1 iff activity set l is being executed at time t

#### The linear relaxation of the master problem

 $(LRMP)\min \sum_{t\in T}\sum_{l\in \overline{L}_t}c_l y_{lt}$ The resulting dual (DLMRP) is :  $\begin{aligned} x_{it} &- \sum_{l \in \overline{L}_t} a_{il} y_{lt} = 0, \ \forall i \in A, t \in T \\ \sum_{l \in \overline{L}} \sum_{t=R_l}^{D_l - 1} a_{il} y_{lt} \geq p_i, \qquad \forall i \in A \end{aligned}$  $-\sum_{l\in\overline{L}_t}y_{lt}\geq -1,\qquad\forall t\in T$  $x_{it} \le 1 \ \forall i \in A, t \in T$  $y_{lt} \ge 0 \ \forall t \in T, l \in \overline{L}_t$  $x_{it} \ge 0 \ \forall i \in A, t \in T$ 

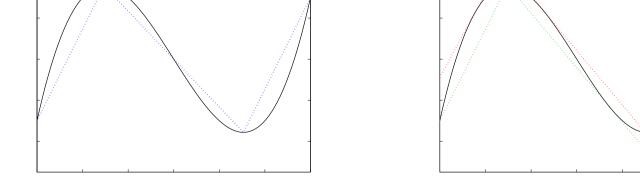
 $\max \sum_{i \in A} p_i u_i - \sum_{t \in T} v_t + \sum_{i \in A} \sum_{t \in T} z_{it}$ 

 $\sum_{i \in A} a_{il}(u_i - w_{it}) - v_t \le c_l, \ \forall t \in T, l \in \overline{L}_t$  $w_{it} + z_{it} \le 0, \ \forall i \in A, t \in T$  $w_{it} \in \mathbb{R}, \ \forall i \in A, t \in T$  $u_i \ge 0, \qquad \forall i \in A$  $v_t \ge 0, \qquad \forall t \in T$ 

Therefore, the reduced cost of a column  $y_{lt}$  is :  $c_l - \sum_{i \in A} a_{il}(u_i) - v_t$ 

#### Two column generation schemes

all dual values  $u_i, v_t, w_{it}$  ( best time t' ( a predefined time t' )



### -Step 2 : Reformulation of the problem into two mixed integer problems (<u>MILP</u> and $\overline{\text{MILP}}$ ) - the problem is originally a MINLP -using the pair of bounding functions previously defined

Number of sectors per tolerance value								
		Pump 1		(Pump 2+RO)		Pump 3		
	$\epsilon$	$\overline{n_{p_1}}$	$n_{p_1}$	$\overline{n_{p_2}}$	$n_{p_2}$	$\overline{n_{p_3}}$	$n_{p_3}$	
	5%	2	2	11	21	3	2	
	1%	5	5	21	29	8	5	
	0.5%	8	7	35	62	13	7	
	0.3%	10	9	43	74	17	9	

Results									
Lower and upper bound obtained									
		MIL	<u>'</u> P	MILP			Gap	opt	
	$\epsilon$	UB	S	LB	S	UB*	%		
	5%	20580	4	19740	15	_	4.25	no	
	1%	20100	15	19920	140	-	0.9	no	
	0.5%	20040	178	19980	117	_	0.3	no	
	0.3%	20040	64	19980	321	19980	0.0	yes	

SP1 :	all dual values $u_i, v_t,$ problem data $a_{it}, b_i,$	$\left. \begin{array}{c} w_{it} \\ \rho^{-1} \end{array} \right\} \rightarrow \begin{array}{c} \phi^{0} & \phi^{0} \\ \phi^{0} & \phi^{0} \end{array} \rightarrow \left\{ \begin{array}{c} \phi^{0} & \phi^{0} \\ \phi^{0} & \phi^{0} \end{array} \right\}$	best time $l'$ SP2 : related problem	dual values $u_i, w_{it'}$ $\rightarrow \overset{\circ}{\longrightarrow} \rightarrow \langle a_{it}, b_i, \rho^{-1} \rangle$	best task set <i>l'</i>
			Results		
			Extended Model	Compact Model	
		<b>T</b>	Branch & Price	Black Box Solver	
	#Opt/# Ratio	Instances avg (min, max)	<b>261</b> /288 <b>99.81%</b> (77.47 %, 100%)	5/288 84.21 % (57.85 %, 99.99 %)	
	Time Nbnodes	avg (min, max) avg (min, max)		$\frac{1034 \text{ s} (7 \text{ s}, 1927 \text{ s})}{2174044 (57157, 13470373)}$	