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# The raising steps method. Application to the $L^{r}$ Hodge theory in a compact riemannian manifold. 

Eric Amar


#### Abstract

Let $X$ be a complete metric space and $\Omega$ a domain in $X$. The Raising Steps Method allows to get from local results on solutions $u$ of a linear equation $D u=\omega$ global ones in $\Omega$.

It was introduced in [1 to get good estimates on solutions of $\bar{\partial}$ equation in domains in a Stein manifold.

As a simple application we shall get a strong $L^{r}$ Hodge decomposition theorem for $p$-forms in a compact riemannian manifold without boundary, and then we retrieve this known result by an entirely different and simpler method.


## 1 Introduction.

This work proposes a way for passing from local to global: the raising steps method, RSM for short. I introduce it precisely to get $L^{r}-L^{s}$ estimates for solutions of the $\bar{\partial}$ equation in Stein manifold in [1]. See also [2] to have result in case of intersection of domains in Stein manifolds.

The aim is to generalise it to the case where the $\bar{\partial}$ operator is replaced by an abstract linear operator $D$ acting on a domain in a complete metric space.

We shall deal with the following situation: we have a complete metric space $X$ admitting partitions of unity (see condition (ii) below) and a measure $\mu$.

A domain of $X$ will be a connected open set $\Omega$ of $X$, relatively compact.
We are interested on solutions $u$ of a linear equation $D u=\omega$, in a domain $\Omega$. Precisely fix a threshold $s>1$. Suppose you have a global solution $u$ on $\Omega$ of $D u=\omega$ with estimates $L^{s}(\Omega) \rightarrow$ $L^{s}(\Omega)$. It may happen that we have a constrain:
$\exists K \subset L^{s^{\prime}}(\Omega)$ with $s^{\prime}$ the conjugate exponent for $s$, such that $\forall u:: D u \in L^{s}(\Omega), \forall h \in$ $K,\langle D u, h\rangle=0$.
In this case, in order for a solution of $D u=\omega$ to exist, we need to have $\omega \perp K$. With no constrain, we take $K=\{0\}$.

Very often this threshold will be $s=2$, since Hilbert spaces are usually more tractable.
Now suppose that we have, for $1 \leq r \leq s$, local solutions $u$ on $U \cap \Omega$ of $D u=\omega$ with estimates $L^{r}(\Omega) \rightarrow L^{t}(U \cap \Omega)$ with a strict increase of the regularity, for instance $\frac{1}{t}=\frac{1}{r}-\tau, \tau>0$ for any $r \leq s$, then the raising steps method gives a global solution $v$ of $D v=\omega$ which is essentially in $L^{t}(\Omega)$ if we start with a data $\omega$ in $L^{r}(\Omega)$.

In particular we prove:

Theorem 1.1. (Raising steps theorem) Under the assumptions above, there is a positive constant c such that for $1 \leq r \leq s$, if $\omega \in L^{r}(\Omega), \omega \perp K$, there is a $u \in L^{t}(\Omega)$ with $\frac{1}{t}=\frac{1}{r}-\tau$, such that $D u=\omega+\tilde{\omega}$, with $\tilde{\omega} \in L^{s}(\Omega), \tilde{\omega} \perp K$ and control of the norms.

From this theorem and the fact that there is a global solution $v \in L^{s}(\Omega)$ to $D v=\bar{\omega}$ we get that $u-v$ is the global solution we are searching for.

To illustrate the method, we shall apply it for the Poisson equation associated to the Hodge Laplacian in a compact riemannian boundary-less manifold $(M, g)$.
On $(M, g)$ we can define Sobolev spaces $W^{k, r}(\Omega)$ (see [8]) and if $M$ is compact these spaces are in fact independent of the metric. Moreover the Sobolev embeddings are true in this case and a chart diffeomorphism makes a correspondence between Sobolev spaces in $\mathbb{R}^{n}$ and Sobolev spaces in $M$.

Let $d$ be the exterior derivative on $M$ and $d^{*}$ its adjoint; we define the Hodge laplacian acting from $p$ differential forms to $p$ differential forms to be: $\Delta:=d d^{*}+d^{*} d$. Because $M$ is compact, we have that $\Delta$ is self adjoint. The Poisson equation on $M$ is, for a given $p$-form $\omega$ on $M$, to find a $p$-form $u$ on $M$ such that $\Delta u=\omega$.

Let $\mathcal{H}_{p}$ be the set of $p$-harmonic forms in $M$, i.e. $h \in \mathcal{H}_{p} \Longleftrightarrow h \in \mathcal{C}_{p}^{\infty}(M), \Delta h=0$. We have: $\forall h \in \mathcal{H}_{p},\langle\Delta u, h\rangle=\langle u, \Delta h\rangle=0$
hence, in order to solve $\Delta u=\omega$, we need to have $\omega \perp \mathcal{H}_{p}$.
We derive, from a solution of the Poisson equation we get by use of the RSM, a $L_{p}^{r}$ Hodge decomposition for $p$ differential forms on $M$.

We shall use, for the local results, the classical ones. Let $B$ be a ball in $\mathbb{R}^{n}$, then:

$$
\forall \gamma \in L^{r}(B), \exists u \in W^{2, r}(B):: \Delta_{\mathbb{R}} u=\gamma,\left\|v_{0}\right\|_{W^{2, r}(B)} \leq C\|\gamma\|_{L^{r}(B)}
$$

These non trivial estimates are coming from Gilbarg and Trudinger [6, Theorem 9.9, p. 230] and the constant $C=C(n, r)$ depends only on $n$ and $r$.

Then, together with the R.S.M., we get a solution of the Poisson equation for the Hodge laplacian.
Theorem 1.2. Let $M$ be a compact, $\mathcal{C}^{\infty}$ Riemannian manifold without boundary. For any $r, 1 \leq$ $r \leq n / 2$, if $g$ is a p-form in $L_{p}^{r}(M) \cap \mathcal{H}_{p}^{\perp}$ there is a p-form $v \in L^{t}(M)$ such that $\Delta v=g$ and $\|v\|_{L_{p}^{t}(M)} \leq c\|g\|_{L_{p}^{r}(M)}$ with $\frac{1}{t}=\frac{1}{r}-\frac{2}{n}$.
Moreover for any $r>1$ and any $p$ form $u$ solution of $\Delta u=g$, we have $u$ in $W_{p}^{2, r}(M)$.
From this result we deduce the $L^{r}$ Hodge decomposition of $p$-forms.
Theorem 1.3. Let $(M, g)$ be a compact riemannian manifold without boundary. We have the strong $L^{r}$ Hodge decomposition:
$\forall r, 1 \leq r<\infty, L_{p}^{r}(M)=\mathcal{H}_{p}^{r} \oplus \operatorname{Im} \Delta\left(W_{p}^{2, r}(M)\right)=\mathcal{H}_{p}^{r} \oplus \operatorname{Im} d\left(W_{p}^{1, r}(M)\right) \oplus \operatorname{Im} d^{*}\left(W_{p}^{1, r}(M)\right)$.
The case $r=2$ of this decomposition which gives us $s=2$ as a threshold, goes to Morrey in 1966 and essentially all results in the $L^{2}$ case we use here are coming from the basic work of Morrey [10].

This decomposition is an already known result of C. Scott [12] but proved here by an entirely different method. Critical to Scott's proof is a nice $L^{r}$ Gaffney's inequality which he proved and used to get the $L^{r}$ Hodge decomposition, the same way than Morrey [10] did with the $L^{2}$ Gaffney's inequality [5] to get the $L^{2}$ Hodge decomposition.

In the case of a compact manifold with boundary, G. Schwarz [11] proved also a $L^{r}$ Gaffney's inequality to get the $L^{r}$ Hodge decomposition in that case, then he deduced of it a global $L^{r}$ solution for the equation $\Delta u=\omega$.

In the nice book by F.W. Warner [15], the author proved directly, without the use of Gaffney's inequality, a global $L^{2}$ solution for the equation $\Delta u=\omega$ in the case of a compact manifold without boundary. He deduced from it the $L^{2}$ Hodge decomposition.

Here we use the RSM plus the global $L^{2}$ solution for the equation $\Delta u=\omega$ given by Warner [15], to get a global $L^{r}$ solution for the equation $\Delta u=\omega$ and then recover the $L^{r}$ Hodge decomposition, without any Gaffney's inequalities. Hence we get a completely different proof of the known $L^{r}$ Hodge decomposition.

Many important applications of the $L^{2}$ Hodge decomposition in cohomology theory and algebraic geometry are in the book by C. Voisin [14.

So it may be interesting to have a short proof of this important Hodge decomposition in the $L^{r}$ case.

Finally, in the last section we prove, by use of the "double manifold" technique:
Theorem 1.4. Let $\Omega$ be a domain in the smooth complete riemannian manifold $M$ and $\omega \in L_{p}^{r}(\Omega)$, then there is a $p$-form $u \in W_{p}^{2, r}(\Omega)$, such that $\Delta u=\omega$ and $\|u\|_{W_{p}^{2, r}(\Omega)} \leq c(\Omega)\|\omega\|_{L_{p}^{r}(\Omega)}$.

And we make a short incursion in the domain of manifold with boundary:
Corollary 1.5. Let $M$ be a smooth compact riemannian manifold with smooth boundary $\partial M$. Let $\omega \in L_{p}^{r}(M)$. There is a $p$-form $u \in W_{p}^{2, r}(M)$, such that $\Delta u=\omega$ and $\|u\|_{W_{p}^{2, r}(M)} \leq c\|\omega\|_{L_{p}^{r}(M)}$.

Schwarz [11, Theorem 3.4.10, p. 137] proved a better theorem: you can prescribe the values of $u$ on the boundary. But again the proof here is much lighter.

## 2 The Raising Steps Method.

We shall deal with the following situation: we have a complete metric space $X$ admitting partitions of unity (see condition (ii) below) and a positive $\sigma$-finite measure $\mu$.

### 2.1 Assumptions on the linear operator $D$.

We shall denote $E^{p}(X)$ the set of $\mathbb{C}^{p}$ valued fonctions on $X$. This means that $\omega \in E^{p}(X) \Longleftrightarrow$ $\omega(x)=\left(\omega_{1}(x), \ldots, \omega_{p}(x)\right)$. We put a punctual norm on $\omega \in E^{p}(X),|\omega(x)|^{2}:=\sum_{j=1}^{p}\left|\omega_{j}(x)\right|^{2}$ and if $U$ is an open set in $X$, we consider the Lebesgue space $L_{p}^{r}(U)$ :

$$
\omega \in L_{p}^{r}(U) \Longleftrightarrow\|\omega\|_{L_{p}^{r}(U)}^{r}:=\int_{U}|\omega(x)|^{r} d \mu(x)<\infty .
$$

The space $L_{p}^{2}(U)$ is a Hilbert space with the scalar product $\left\langle\omega, \omega^{\prime}\right\rangle:=\int_{U}\left(\sum_{j=1}^{p} \omega_{j}(x) \bar{\omega}_{j}^{\prime}(x)\right) d \mu(x)$.
We are interested in solution of a linear equation $D u=\omega$, where $D=D_{p}$ is a linear operator acting on $E^{p}$.

In order to have $D u=\omega$, it may happen that we have a constrain: there is a subspace $K \subset L^{r^{\prime}}(\Omega)$ such that

$$
\forall h \in K, \forall u:: D u \in L^{r}(\Omega),\langle D u, h\rangle=0 \Longleftrightarrow D u \perp K
$$

The absence of constrain is done by setting $K=\{0\}$.
Now on the integer $p$ will be fixed so the explicit mention of the integer $p$ will be often omitted.
We shall make the following hypotheses.
Let $\Omega$ be a domain in $X$. There is a $\tau \geq \delta$ with $\frac{1}{t}=\frac{1}{r}-\tau$, and a positive constant $c_{l}$ such that:
(i) Local Existence with Increasing Regularity (LEIR): for any $x \in \bar{\Omega}$, there is a ball $B:=$ $B\left(x, R_{x}\right)$ such that if $\omega \in L_{p}^{r}(B)$, we can solve $D u_{x}=\omega$ in $B^{\prime}:=B\left(x, R_{x} / 2\right)$ with $L_{p}^{r}(B)-L_{p}^{t}\left(B^{\prime}\right)$ estimates, i.e. $\exists u_{x} \in L^{t}\left(B^{\prime}\right), D u_{x}=\omega$ in $B^{\prime}$ and $\left\|u_{x}\right\|_{L^{t}\left(B^{\prime}\right)} \leq c_{l}\|\omega\|_{L^{r}(B)}$.

It may append, in the case $X$ is a manifold, that we have a better regularity for the local existence:
(i') Sobolev regularity: if $\omega \in L_{p}^{r}(B)$, we can solve $D u_{x}=\omega$ in $B^{\prime}:=B\left(x, R_{x} / 2\right)$ with $L_{p}^{r}(B)-W_{p}^{\alpha, r}\left(B^{\prime}\right)$ estimates, i.e. $\exists u_{x} \in W_{p}^{\alpha, r}\left(B^{\prime}\right), D u_{x}=\omega$ in $B^{\prime}$ and $\left\|u_{x}\right\|_{W_{p}^{\alpha, r}\left(B^{\prime}\right)} \leq c_{l}\|\omega\|_{L^{r}(B)}$.

By compactness we can cover $\bar{\Omega}$ by a finite set of balls $\left\{B\left(x_{j}, R_{j} / 2\right)\right\}_{j=1, \ldots, N}$ of the previous form. Set $B_{j}:=B\left(x_{j}, R_{j}\right), B_{j}^{\prime}:=B\left(x_{j}, R_{j} / 2\right)$. Set $u_{j}$ the local solution of $D u_{j}=\omega$ with $\left\|u_{j}\right\|_{L^{t}\left(B_{j}^{\prime}\right)} \leq$ $c_{l}\|\omega\|_{L^{r}\left(B_{j}\right)}$.
(ii) Partition of unity: If $\left\{B_{j}^{\prime}\right\}_{j=1, \ldots, N}$ is a covering of $\bar{\Omega}$, then there is an associated set of functions $\left\{\chi_{j}\right\}_{j=1, \ldots, N}$ such that $\chi_{j}$ has compact support in $B_{j}^{\prime}, \forall j=1, \ldots, N, 0 \leq \chi_{j}(x) \leq 1$ and $\sum_{j=1}^{N} \chi_{j}(x)=1$ for $x \in \bar{\Omega}$.
(iii) Commutator condition: We set $\Delta_{j}=\Delta\left(\chi_{j}, u_{j}\right):=\chi_{j} D u_{j}-D\left(\chi_{j} u_{j}\right)$. There is a constant $\delta>0$ such that, with $\frac{1}{t}=\frac{1}{r}-\delta$, we have:

$$
\left\|\Delta_{j}\right\|_{L^{t}\left(B_{j}^{\prime}\right)} \leq c\left(\chi_{j}\right)\left(\|\omega\|_{L^{r}\left(B_{j}\right)}+\left\|u_{j}\right\|_{L^{r}\left(B_{j}\right)}\right)
$$

(iv) Global resolvability: We can solve $D w=\omega$ globally in $\Omega$ with $L^{s}-L^{s}$ estimates, i.e.
$\exists c_{g}>0, \exists w$ s.t. $D w=\omega$ in $\Omega$ and $\|w\|_{L^{s}(\Omega)} \leq c_{g}\|\omega\|_{L^{s}(\Omega)}$, provided that $\omega \perp K$.
It may append, in the case $X$ is a manifold, that we have a better regularity for the global existence:
(iv') Sobolev regularity: We can solve $D w=\omega$ globally in $\Omega$ with $L_{p}^{s}-W_{p}^{\alpha, s}$ estimates, i.e. $\exists c_{g}>0, \exists w$ s.t. $D w=\omega$ in $\Omega$ and $\|w\|_{W_{p}^{\alpha, s}(\Omega)} \leq c_{g}\|\omega\|_{L^{s}(\Omega)}$, provided that $\omega \perp K$.

Theorem 2.1. (Raising steps theorem) Under the assumptions (i), (ii), (iii), (iv) above, there is a positive constant $c_{f}$ such that for $1 \leq r \leq s$, if $\omega \in L^{r}(\Omega), \omega \perp K$ there is a $u=u_{s} \in L^{t}(\Omega)$ with $\frac{1}{t}=\frac{1}{r}-\tau$, such that $D u=\omega+\tilde{\omega}$, with $\tilde{\omega} \in L^{s}(\Omega), \tilde{\omega} \perp K$ and control of the norms.

If moreover we have ( $i^{\prime}$ ) then $u \in W_{p}^{\alpha, r}(\Omega)$ with control of the norm.
Proof. Let $r \leq s$ and $\omega \in L^{r}(\Omega), \omega \perp K$; we start with the covering $\left\{B_{j}^{\prime}\right\}_{j=1, \ldots, N}$ and the local solution $D u_{j}=\omega$ with $\frac{1}{t}=\frac{1}{r}-\tau, u_{j} \in L^{t}\left(B_{j}^{\prime}\right)$ given by hypothesis (i).
If ( $\mathrm{i}^{\prime}$ ) is true, then we have $u_{j} \in W_{p}^{\alpha, r}\left(B_{j}^{\prime}\right), D u_{j}=\omega$.
Let $\left\{\chi_{j}\right\}_{j=1, \ldots, N}$ be the partition of unity subordinate to $\left\{B_{j}^{\prime}\right\}_{j=1, \ldots, N}$ given by (ii). Because $0 \leq$ $\chi_{j}(x) \leq 1$ we have $\chi_{j} u_{j} \in L^{t}(\Omega)$ hence

$$
\begin{equation*}
\left\|\chi_{j} u_{j}\right\|_{L^{t}(\Omega)} \leq\left\|u_{j}\right\|_{L^{t}\left(B_{j}^{\prime}\right)} \leq c_{l}\|\omega\|_{L^{r}(\Omega)} \tag{2.1}
\end{equation*}
$$

Set $v_{0}:=\sum_{j=1}^{N} \chi_{j} u_{j}$. Then we have, setting now $\frac{1}{t_{0}}=\frac{1}{r}-\tau$ :

- $v_{0} \in L^{t_{0}}(\Omega)$ because $\chi_{j} u_{j} \in L^{t_{0}}(\Omega)$ for $j=1, \ldots, N$, and $\left\|v_{0}\right\|_{L^{t_{0}(\Omega)}} \leq c\|\omega\|_{L^{r}(\Omega)}$ with $c=N c_{l}$ by (2.1). If (i') is true, i.e. $X$ is a manifold, then we can choose $\chi_{j} \in \mathcal{D}\left(B_{j}^{\prime}\right)$, i.e. in the space of $\mathcal{C}^{\infty}$ functions of compact support in $B_{j}$, hence $\left\|\chi_{j} u_{j}\right\|_{W_{p}^{\alpha, r}(\Omega)} \leq c\left\|u_{j}\right\|_{W_{p}^{\alpha, r}\left(B_{j}^{\prime}\right)} \leq c_{l}\|\omega\|_{L^{r}(\Omega)}$. So
- $v_{0} \in W_{p}^{\alpha, r}(\Omega)$ with $\left\|v_{0}\right\|_{W_{p}^{\alpha, r}(\Omega)} \leq c\|\omega\|_{L^{r}(\Omega)}$.

We have

$$
\text { - } D v_{0}=\sum_{j=1}^{N} \chi_{j} D u_{j}+\sum_{j=1}^{N} \Delta\left(\chi_{j}, u_{j}\right)
$$

Setting $\omega_{1}(x):=\sum_{j=1}^{N} \Delta\left(\chi_{j}, u_{j}\right)(x)$, we get

$$
\forall x \in \Omega, \quad D v_{0}(x)=\sum_{j=1}^{N} \chi_{j}(x) \omega(x)+\sum_{j=1}^{N} \Delta\left(\chi_{j}, u_{j}\right)(x)=\omega(x)+\omega_{1}(x)
$$

By hypothesis (iii), $\Delta\left(\chi_{j}, u_{j}\right) \in L^{s_{0}}\left(B_{j}^{\prime}\right)$ with $\frac{1}{s_{0}}=\frac{1}{r}-\delta$, hence $\omega_{1} \in L^{s_{0}}(\Omega)$, with

$$
\begin{equation*}
\left\|\omega_{1}\right\|_{L^{s_{0}}(\Omega)} \leq G\|\omega\|_{L^{r}(\Omega)} \tag{2.2}
\end{equation*}
$$

and $G=c_{s l} N$.
The regularity of $\omega_{1}$ is higher by one step $\delta>0$ than that of $\omega$. Moreover

$$
\forall h \in K,\left\langle\omega_{1}, h\right\rangle=\langle\omega, h\rangle-\left\langle D v_{0}, h\right\rangle=0 \text { because }\langle\omega, h\rangle=0 \text { and }\left\langle D v_{0}, h\right\rangle=0
$$

If $s_{0} \geq s$ we notice that $\omega_{1} \in L^{s}(\Omega)$ because $L^{s_{0}}(\Omega) \subset L^{s}(\Omega)$ for $\Omega$ is relatively compact. So we are done by setting $u_{s}=v_{0}, \tilde{\omega}=\omega_{1}$.

If $s_{0}<s$ we proceed by induction: we set $t_{1}$ such that $\frac{1}{t_{1}}=\frac{1}{s_{0}}-\tau=\frac{1}{r}-\delta-\tau$, and we use the same covering $\left\{B_{j}^{\prime}\right\}_{j=1, \ldots, N}$ and the same partition of unity $\left\{\chi_{j}\right\}_{j=1, \ldots, N}$ and with $\omega_{1}$ in place of $\omega$, we get $\exists v_{1} \in L^{t_{1}}(\Omega), D v_{1}=\omega_{1}+\omega_{2}$ and, setting $s_{1}$ such that $\frac{1}{s_{1}}=\frac{1}{s_{0}}-\delta=\frac{1}{r}-2 \delta$, we have that the regularity of $\omega_{2}$ raises of 2 times $\delta$ from that of $\omega$.

We still have

$$
\forall h \in K,\left\langle\omega_{2}, h\right\rangle=\left\langle\omega_{1}, h\right\rangle-\left\langle D v_{1}, h\right\rangle=0
$$

so by induction, after a finite number $k$ of steps, we get a $s_{k} \geq s$. The linear combination $u:=$ $\sum_{j=0}^{k-1}(-1)^{j} v_{j}$ now gives $D u=\omega+(-1)^{k} \omega_{k}$ with $\omega_{k} \perp K$. And again we are done by setting $\tilde{\omega}=(-1)^{k} \omega_{k}$.

If (i') is true, then we have $v_{0} \in W^{\alpha, r}(\Omega)$ and $v_{1} \in W^{\alpha, s_{0}}(\Omega),\left\|v_{1}\right\|_{W^{\alpha, s_{0}}(\Omega)} \leq c\left\|\omega_{1}\right\|_{L^{s_{0}}(\Omega)}$. Hence by (2.2) we get $\left\|v_{1}\right\|_{W^{\alpha, s_{0}(\Omega)}} \leq c G\|\omega\|_{L^{r}(\Omega)}$.
A fortiori, $v_{1} \in W^{\alpha, r}(\Omega)$ because $r<s_{0}$ with the same control of the norm. Likewise we have $\forall j=1, \ldots, k,\left\|v_{j}\right\|_{W^{\alpha, r}(\Omega)} \leq c\|\omega\|_{L^{r}(\Omega)}$, hence the same control of the norm of $u$.
Corollary 2.2. Under the assumptions of the raising steps theorem and with the global assumption (iv), there is a constant $c_{f}>0$, such that for $r \leq s$, if $\omega \in L^{r}(\Omega), \omega \perp K$ there is a $v \in L^{t}(\Omega)$ with $t:=\min \left(s, t_{0}\right)$ and $\frac{1}{t_{0}}=\frac{1}{r}-\tau$, such that

$$
D v=\omega \text { and } v \in L^{t}(\Omega),\|v\|_{L^{t}(\Omega)} \leq c\|\omega\|_{L^{r}(\Omega)}
$$

If moreover ( $i^{\prime}$ ) and (iv') are true then we have $v \in W^{\alpha, r}(\Omega) \cap L^{t}(\Omega)$ with $\|v\|_{W^{\alpha, r}(\Omega)} \leq c\|\omega\|_{L^{r}(\Omega)}$.
Proof. By the raising steps Theorem 2.1] we have a $u \in L^{t_{0}}(\Omega)$ such that $D u=\omega+\tilde{\omega}$ with $\tilde{\omega} \in L^{s}(\Omega)$ and $\tilde{\omega} \perp K$; by hypothesis (iv) we can solve $D \tilde{v}=\tilde{\omega}$ with $\tilde{v} \in L^{s}(\Omega)$ so it remains to set $v:=u-\tilde{v}$ to get $v \in L^{t}(\Omega)$ and $D v=\omega$.

If moreover (i') is true then we have $u \in W^{\alpha, r}(\Omega)$. If (iv') is true then we can solve $D \tilde{v}=\tilde{\omega}$ with $\tilde{v} \in W^{\alpha, s}(\Omega)$. Hence, because $r \leq s$, with $v:=u-\tilde{v}$ we get $v \in W^{\alpha, r}(\Omega)$ and $D v=\omega$. The proof is complete.

## 3 Application to Poisson equation on a compact riemannian manifold.

### 3.1 Local existence with increasing regularity.

In order to have the local result, we choose a chart $\left(V, \varphi:=\left(x_{1}, \ldots, x_{n}\right)\right)$ so that $g_{i j}(y)=\delta_{i j}$ and $\varphi(V)=B$ where $B=B_{e}$ is an Euclidean ball centered at $\varphi(y)=0$ and $g_{i j}$ are the components of the metric tensor w.r.t. $\varphi$.

Because I was unable to find an easy proof of the following theorem in the literature, I reprove it for the reader's convenience.

Theorem 3.1. For any $y \in M$, there are open sets $W \subset \bar{W} \subset V \subset M, y \in W$, such that we have:

$$
\forall \omega \in L_{p}^{r}(W), \exists u \in W_{p}^{2, r}(W):: \Delta u=\omega, \quad\|u\|_{W^{2, r}(W)} \leq C\|\omega\|_{L^{r}(W)}
$$

Proof. Of course the operator $d$ on $p$-forms is local and so is $d^{*}$ as a first order differential operator. We start with a chart $(V, \varphi)$ of $M$ such that $\varphi(y)=0 \in \mathbb{R}^{n}$ and the metric tensor read in this chart at $y$ is the identity.

Then the Hodge laplacian $\Delta_{\varphi}$ read by $\varphi$ in a ball $B:=B(0, R) \subset \mathbb{R}^{n}$ is not so different from that of $\mathbb{R}^{n}$ in $B$ when acting on $p$-forms in $B$. We set $\Delta_{\varphi} \omega_{\varphi}=\Delta_{\mathbb{R}} \omega_{\varphi}+A \omega_{\varphi}$, where $\omega_{\varphi}$ is the $p$-form $\omega$ read in the chart $(V, \varphi)$ and $A$ is a matrix valued second order operator with $\mathcal{C}^{\infty}$ smooth coefficients such that $A: W^{2, r}(B) \rightarrow L^{r}(B)$ with, for a $R$ small enough $\|A v\|_{L^{r}(B)} \leq c\|v\|_{W^{2, r}(B)}$.

This is true because at the point $y \in V$ we are in the flat case and if $R$ is small enough, the difference $A:=\Delta_{\varphi}-\Delta_{\mathbb{R}}$ in operator norm $W^{2, r}(B) \rightarrow L^{r}(B)$ goes to 0 when $R$ goes to 0 , because $\varphi \in \mathcal{C}^{2}$ and the metric tensor $g$ is also $\mathcal{C}^{2}$.

We know that $\Delta_{\mathbb{R}}$ operates component-wise on the $p$-form $\gamma$, so we have

$$
\forall \gamma \in L_{p}^{r}(B), \exists v_{0} \in W_{p}^{2, r}(B):: \Delta_{\mathbb{R}} v_{0}=\gamma,\left\|v_{0}\right\|_{W^{2, r}(B)} \leq C\|\gamma\|_{L^{r}(B)}
$$

simply setting the component of $v_{0}$ to be the Newtonian potential of the corresponding component of $\gamma$ in $U$. This way $v_{0}$ is linear with respect to $\gamma$. These non trivial estimates are coming from Gilbarg and Trudinger [6, Thorem 9.9, p. 230] and the constant $C=C(n, r)$ depends only on $n$ and $r$.

So we get $\Delta_{\mathbb{R}} v_{0}+A v_{0}=\gamma+\gamma_{1}$, with

$$
\gamma_{1}=A v_{0} \Rightarrow\left\|\gamma_{1}\right\|_{L^{r}(B)} \leq c\left\|v_{0}\right\|_{W^{2, r}(B)} \leq c C\|\gamma\|_{L^{r}(B)}
$$

We solve again

$$
\exists v_{1} \in W_{p}^{2, r}(B):: \Delta_{\mathbb{R}} v_{1}=\gamma_{1},\left\|v_{1}\right\|_{W^{2, r}(B)} \leq C\left\|\gamma_{1}\right\|_{L^{r}(B)}=C^{2} c\|\gamma\|_{L^{r}(B)}
$$

and we set

$$
\gamma_{2}:=A v_{1} \Rightarrow\left\|\gamma_{2}\right\|_{L^{r}(B)} \leq c\left\|v_{1}\right\|_{W^{2, r}(B)} \leq C\left\|\gamma_{1}\right\|_{L^{r}(B)} \leq C^{2} c^{2}\|\gamma\|_{L^{r}(B)}
$$

And by induction:

$$
\forall k \in \mathbb{N}, \quad \gamma_{k}:=A v_{k-1} \Rightarrow\left\|\gamma_{k}\right\|_{L^{r}(B)} \leq c\left\|v_{k-1}\right\|_{W^{2, r}(B)} \leq C\left\|\gamma_{k-1}\right\|_{L^{r}(B)} \leq C^{k} c^{k}\|\gamma\|_{L^{r}(B)}
$$

and

$$
\exists v_{k} \in W_{p}^{2, r}(B):: \Delta_{\mathbb{R}} v_{k}=\gamma_{k},\left\|v_{k}\right\|_{W^{2, r}(B)} \leq C\left\|\gamma_{k}\right\|_{L^{r}(B)} \leq C^{k+1} c^{k}\|\gamma\|_{L^{r}(B)} .
$$

Now we set $v:=\sum_{j \in \mathbb{N}}(-1)^{j} v_{j}$. This series converges in norm $W^{2, r}(B)$, provided that we choose the radius of the ball $B$ small enough to have $c C^{2}<1$, and we get:

$$
\Delta_{\varphi} v=\Delta_{\mathbb{R}} v+A v=\sum_{j \in \mathbb{N}}(-1)^{j}\left(\Delta_{\mathbb{R}} v_{j}+A v_{j}\right)=\gamma
$$

the last series converging in $L^{r}(B)$.
In fact every step is linear and we get that $v$ is linear in $\gamma$.
Going back to the manifold $M$ with $\gamma:=\omega_{\varphi}$ and setting $u_{\varphi}:=v, W:=\varphi^{-1}(B)$, we get the right estimates:

$$
\exists u \in W^{2, r}(W):: \Delta u=\omega \text { in } W,\|u\|_{W^{2, r}(W)} \leq C\|\omega\|_{L^{r}(W)},
$$

because the Sobolev spaces for $B$ go to the analogous Sobolev spaces for $W$ in $M$.
Now the next corollary is precisely the result we are searching for.
Corollary 3.2. For any $y \in M$, there are open sets $V, W \Subset V, y \in W$, such that we have for $r \leq 2$ :
$\forall \omega \in L_{p}^{r}(V), \exists u \in W^{2, r}(W) \cap L_{p}^{t}(W):: \Delta u=\omega,\|u\|_{W^{2, r}(W)} \leq C\|\omega\|_{L^{r}(V)},\|u\|_{L_{p}^{t}(W)} \leq C\|\omega\|_{L_{p}^{r}(V)}$ with $\frac{1}{t}=\frac{1}{r}-\frac{2}{n}$, and $\nabla u \in W_{p}^{1, r}(W)$.

Proof. The Theorem 3.1 gives $u \in W^{2, r}(W)$ such that $\Delta u=\omega,\|u\|_{W^{2, r}(W)} \leq C\|\omega\|_{L^{r}(V)}$, hence we get that $\nabla u \in W_{p}^{1, r}(W)$ with the same control: $\|\nabla u\|_{W^{1, r}(W)} \leq C\|\omega\|_{L^{r}(V)}$.

For the first statement it remains to apply the Sobolev embedding theorems which are true here.

So we are in a special case of the previous section with $D:=\Delta$ and, because $\Delta$ is essentially self adjoint, we have here $K:=\mathcal{H}_{p}(M)$ where $\mathcal{H}_{p}(M)$ is the space of $\mathcal{C}^{\infty}$ harmonic $p$-forms in $M$.

We shall need the following lemma.
Lemma 3.3. Let $\Delta_{\varphi}$ be a second order elliptic matrix operator with $\mathcal{C}^{\infty}$ coefficients operating on $p$ forms $v$ defined in $U \subset \mathbb{R}^{n}$. Let $B:=B(0, R)$ a ball in $\mathbb{R}^{n}, B^{\prime}:=B(0, R / 2)$ and suppose that $B \Subset U$. Then we have an interior estimate: there are constants $c_{1}, c_{2}$ depending only on $n=\operatorname{dim}_{\mathbb{R}} M, r$ and the $\mathcal{C}^{1}$ norm of the coefficients of $\Delta_{\varphi}$ in $\bar{B}$ such that

$$
\begin{equation*}
\forall v \in W_{p}^{2, r}(B),\|v\|_{W^{2, r}\left(B^{\prime}\right)} \leq c_{1}\|v\|_{L^{r}(B)}+c_{2}\left\|\Delta_{\varphi} v\right\|_{L^{r}(B)} \tag{3.3}
\end{equation*}
$$

Proof. For a 0 -form this lemma is exactly [6, Theorem 9.11].
For $p$-forms we cannot avoid the use of deep results on elliptic systems of equations.
Let $v$ be a $p$-form in $B \subset \mathbb{R}^{n}$. We use the interior estimates in [10, §6.2, Thm 6.2.6]. In our context, second-order elliptic system, and with our notations, with $r>1$, we get:

$$
\exists C>0, \forall v \in W_{p}^{2, r}(B),\|v\|_{W^{2, r}\left(B^{\prime}\right)} \leq c_{1} R^{-2}\|v\|_{L^{r}(B)}+c_{2}\left\|\Delta_{\varphi} v\right\|_{L^{r}(B)}
$$

already including the dependence in $R$.
The constants $c_{1}, c_{2}$ depend only on $r, n:=\operatorname{dim} M$ and the bounds and moduli of continuity of all the coefficients of the matrix $\Delta_{\varphi}$. (In [10], p. 213: the constant depends only on $E$ and on $E^{\prime}$.)

In particular, if $\Delta_{\varphi}$ has its coefficients near those of $\Delta_{\mathbb{R}}$ in the $\mathcal{C}^{1}$ norm, then the constants $c_{1}, c_{2}$ are near the ones obtained for $\Delta_{\mathbb{R}}$.

Now we deduce from it local interior regularity for the laplacian on a smooth compact manifold without boundary.

Lemma 3.4. Let $(M, g)$ be a riemannian manifold. For $x \in M, R>0$, we take a geodesic ball $B(x, R)$ such that, read in a chart $(V, \varphi), B(x, R) \Subset V$, the metric tensor at the center is the identity.
We have a local Calderon Zygmund inequality on the manifold M. For any $r>1$, there are constants $c_{1}, c_{2}$ depending only on $n=\operatorname{dim}_{\mathbb{R}} M, r$ and $R$, such that:

$$
\forall u \in W^{2, r}(B(x, R)),\|u\|_{W^{2, r}(B(x, R / 2))} \leq c_{1}\|u\|_{L^{r}(B(x, R))}+c_{2}\|\Delta u\|_{L^{r}(B(x, R))}
$$

Proof. We transcribe the problem in $\mathbb{R}^{n}$ by use of a coordinates path $(V, \varphi)$ exactly the same way we did to prove Theorem 3.1. The Hodge laplacian is the second order elliptic matrix operator $\Delta_{\varphi}$ with $\mathcal{C}^{\infty}$ coefficients operating in $\varphi(V) \subset \mathbb{R}^{n}$. By the choice of a $R$ small enough we can apply Lemma 3.3, to the euclidean balls $B^{\prime}:=B_{e}\left(0, R_{e}^{\prime}\right) \subset \varphi(B(x, R / 2)), B:=B_{e}\left(0, R_{e}\right) \subset \varphi(B(x, R))$ and we get, with $u_{\varphi}$ the $p$-form $u$ read in the chart $(V, \varphi)$,

$$
\left\|u_{\varphi}\right\|_{W^{2, r}\left(B^{\prime}\right)} \leq c_{1} R^{-2}\left\|u_{\varphi}\right\|_{L^{r}(B)}+c_{2}\left\|\Delta_{\varphi} u_{\varphi}\right\|_{L^{r}(B)}
$$

The Lebesgue measure on $U$ and the canonical measure $d v_{g}$ on $B(x, R)$ are equivalent; so the Lebesgue estimates and the Sobolev estimates up to order 2 on $U$ are valid in $B(x, R)$ up to a constant.

So passing back to $M$, we get, with $A:=\varphi^{-1}(B), A^{\prime}:=\varphi^{-1}\left(B^{\prime}\right)$

$$
\left.\|u\|_{W^{2, r}\left(A^{\prime}\right)} \leq c_{1}\|u\|_{L^{r}(A)}+c_{2}\|\Delta u\|_{L^{r}(A)}\right) .
$$

So taking a smaller ball centered at $x$ we end the proof of the lemma.
Theorem 3.5. Let $M$ be a compact $\mathcal{C}^{\infty}$ Riemannian manifold without boundary. We have:
$\forall \omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}(M)^{\perp}, r \in\left(1, \frac{n}{2}\right) ; \exists u \in L_{p}^{s}(M):: \Delta u=\omega$,
with $\frac{1}{s}=\frac{1}{r}-\frac{2}{n}$. Moreover $u \in W^{2, r}(M),\|u\|_{W^{2, r}(M)} \leq c\|\omega\|_{L^{r}(M)}$.
Proof. First by duality we get the range $r>2$. For this we shall proceed as we did in [1], using an avatar of the Serre duality [13]. We take $t$ as in corollary [2.2,

Let $g \in L_{p}^{t^{\prime}}(M) \cap \mathcal{H}_{p}(M)^{\perp}$, we want to solve $\Delta v=g$, with $t^{\prime}>2$ and $t^{\prime}$ conjugate to $t$. We know by the previous part that, with $r \leq 2$,

$$
\begin{equation*}
\forall \omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}(M)^{\perp}, \exists u \in L_{p}^{t}(M), \Delta u=\omega,\|u\|_{L^{t}(M)} \leq c\|\omega\|_{L^{r}(M)} \tag{3.4}
\end{equation*}
$$

Consider the linear form

$$
\forall \omega \in L_{p}^{r}(M), \quad \mathcal{L}(\omega):=\langle u, g\rangle
$$

where $u$ is a solution of (3.4); in order for $\mathcal{L}(\omega)$ to be well defined, we need that if $u^{\prime}$ is another solution of $\Delta u^{\prime}=\omega$, then $\left\langle u-u^{\prime}, g\right\rangle=0$; hence we need that $g$ must be "orthogonal" to $p$-forms $\varphi$ such that $\Delta \varphi=0$ which is precisely our assumption.

Hence we have that $\mathcal{L}(f)$ is well defined and linear; moreover

$$
|\mathcal{L}(f)| \leq\|u\|_{L^{t}(M)}\|g\|_{L^{t^{\prime}(M)}} \leq c\|\omega\|_{L^{r}(M)}\|g\|_{L^{t^{\prime}(M)}} .
$$

So this linear form is continuous on $\omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}(M)^{\perp}$. By the Hahn Banach Theorem there is a form $v \in L_{p}^{r^{\prime}}(M)$ such that:
$\forall \omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}(M)^{\perp}, \mathcal{L}(\omega)=\langle\omega, v\rangle=\langle u, g\rangle$.
But $\omega=\Delta u$, so we have, because $\Delta$ is essentially self adjoint and $M$ is compact, $\langle\omega, v\rangle=\langle\Delta u, v\rangle=$ $\langle u, \Delta v\rangle=\langle u, g\rangle$, for any $u \in L_{p}^{t}(M):: \Delta u \in L_{p}^{r}(M)$. In particular for $u \in \mathcal{C}_{p}^{\infty}(M)$. Now the hypothesis (iii) gives that $\Delta v=g$ in $L_{p}^{t^{\prime}}(M)$, with $v \in L_{p}^{r^{\prime}}(M)$. So we get:

$$
\forall g \in L_{p}^{t^{\prime}}(M) \cap \mathcal{H}_{p}(M)^{\perp}, \exists v \in L_{p}^{r^{\prime}}(M), \Delta v=g
$$

It remains to prove the moreover. The condition (i') is true by the local existence Theorem 3.1, The condition (iv') is true in the case of the Hodge Laplacian on a compact boundary-less manifold by Morrey's results for $L^{2}(M)$, so we are done for $r \leq 2$.

For $r>2$, Lemma 3.4 gives us by compactness that there is a smaller $R>0$ and bigger constants $c_{1}, c_{2}$ such that:

$$
\begin{equation*}
\forall x \in M,\|u\|_{W^{2, r}(B(x, R / 2))} \leq c_{1}\|u\|_{L^{r}(B(x, R))}+c_{2}\|\Delta u\|_{L^{r}(B(x, R))} . \tag{3.5}
\end{equation*}
$$

We take for $u$ our global solution in $L_{p}^{r}(M)$. We have that $\Delta u=\omega \in L_{p}^{r}(M)$ hence we can apply the estimate (3.5) to $u$ :

$$
\forall x \in M,\|u\|_{W^{2, r}(B(x, R / 2))} \leq c_{1}\|u\|_{L^{r}(B(x, R))}+c_{2}\|\Delta u\|_{L^{r}(B(x, R))} \leq C\|\omega\|_{L^{r}(M)}
$$

Now it remains to cover $M$ with a finite set of balls of the type $B(x, R / 2)$ to end the proof.

### 3.2 The $L^{r}$ Hodge decomposition.

In order to deduce the Hodge decomposition from the existence of a good solution to the Poisson equation, we shall need a little bit more material.

### 3.2.1 Basic facts.

Let $\mathcal{H}_{p}^{2}$ be the set of harmonic $p$-forms in $L^{2}(M)$, i.e. $p$-form $\omega$ such that $\Delta \omega=0$, which is equivalent here to $d \omega=d^{*} \omega=0$.

The classical $L^{2}$ theory of Morrey [10] gives, on a compact manifold $M$ without boundary:

$$
\begin{aligned}
& \mathcal{H}_{p}:=\mathcal{H}_{p}^{2} \subset \mathcal{C}^{\infty}(M)[\text { [10], (vi) p. 296] } \\
& \operatorname{dim}_{\mathbb{R}} \mathcal{H}_{p}<\infty \text { [ [10], Theorem7.3.1]. }
\end{aligned}
$$

This gives the existence of a linear projection from $L_{p}^{r}(M) \rightarrow \mathcal{H}_{p}$ :

$$
\forall v \in L_{p}^{r}(M), H(v):=\sum_{j=1}^{N}\left\langle v, e_{j}\right\rangle e_{j}
$$

where $\left\{e_{j}\right\}_{j=1, \ldots, N}$ is an orthonormal basis for $\mathcal{H}_{p}$. This is meaningful because $v \in L_{p}^{r}(M)$ can be integrated against $e_{j} \in \mathcal{H}_{p} \subset \mathcal{C}^{\infty}(M)$. Moreover we have $v-H(v) \in L_{p}^{r}(M) \cap \mathcal{H}_{p}^{\perp}$ in the sense that $\forall h \in \mathcal{H}_{p},\langle v-H(v), h\rangle=0$; it suffices to test on $h:=e_{k}$. We get

$$
\left\langle v-H(v), e_{k}\right\rangle=\left\langle v, e_{k}\right\rangle-\left\langle\sum_{j=1}^{N}\left\langle v, e_{j}\right\rangle e_{j}, e_{k}\right\rangle=\left\langle v, e_{k}\right\rangle-\left\langle v, e_{k}\right\rangle=0
$$

Let $v \in L_{p}^{r}(M)$. Set $h:=H(v) \in \mathcal{H}_{p}$, and $\omega:=v-h$. We have that $\forall k \in \mathcal{H}_{p},\langle\omega, k\rangle=$ $\langle v-H(v), k\rangle=0$. Hence we can solve $\Delta u=\omega$ with $u \in W_{p}^{2, r}(M) \cap L_{p}^{s}(M)$. So we get $v=h+\Delta u$ which means:

$$
L_{p}^{r}(M)=\mathcal{H}_{p}^{r} \oplus \operatorname{Im} \Delta\left(W_{p}^{2, r}(M)\right)
$$

We have a direct decomposition because if $\omega \in \mathcal{H}_{p} \cap \operatorname{Im} \Delta\left(W_{p}^{2, r}(M)\right)$, then $\omega \in \mathcal{C}^{\infty}(M)$ and

$$
\omega=\Delta u \Rightarrow \forall k \in \mathcal{H}_{p}, \quad\langle\omega, k\rangle=0
$$

so choosing $k=\omega \in \mathcal{H}_{p}$ we get $\langle\omega, \omega\rangle=0$ hence $\omega=0$.
Now we are in position to prove:
Theorem 3.6. If $(M, g)$ is a compact riemannian manifold without boundary; we have the strong $L^{r}$ Hodge decomposition:

$$
\forall r, 1 \leq r<\infty, L_{p}^{r}(M)=\mathcal{H}_{p}^{r} \oplus \operatorname{Im} d\left(W_{p}^{1, r}(M)\right) \oplus \operatorname{Im} d^{*}\left(W_{p}^{1, r}(M)\right)
$$

Proof. We already have

$$
L_{p}^{r}(M)=\mathcal{H}_{p}^{r} \oplus \operatorname{Im} \Delta\left(W_{p}^{2, r}(M)\right)
$$

where $\oplus$ means uniqueness of the decomposition.
So: $\forall \omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}^{r \perp}, \exists u \in W_{p}^{2, r}(M):: \Delta u=\omega$.
From $\Delta=d d^{*}+d^{*} d$ we get $\omega=d\left(d^{*} u\right)+d^{*}(d u)$ with $d u \in W_{p}^{1, r}(M)$ and $d^{*} u \in W_{p}^{1, r}(M)$, so

$$
\forall \omega \in L_{p}^{r}(M) \cap \mathcal{H}_{p}^{r \perp}, \exists \alpha \in W_{p-1}^{1, r}(M), \exists \beta \in W_{p+1}^{1, r}(M):: \omega=\alpha+\beta
$$

simply setting $\alpha=d\left(d^{*} u\right), \beta=d^{*}(d u)$, which gives $\alpha \in d\left(W_{p-1}^{1, r}(M)\right)$ and $\beta \in d^{*}\left(W_{p+1}^{1, r}(M)\right)$ and this proves the existence.

The uniqueness is given by Lemma 6.3 in [12] and I copy this simple (but nice) proof here for the reader's convenience.

Suppose that $\alpha \in W_{p-1}^{1, r}(M), \beta \in W_{p+1}^{1, r}(M), h \in \mathcal{H}_{p}$ satisfy $d \alpha+d^{*} \beta+h=0$.
Let $\varphi \in \mathcal{C}_{p}^{\infty}(M)$, because of the classical $\mathcal{C}^{\infty}$-Hodge decomposition, there are $\eta \in \mathcal{C}_{p-1}^{\infty}(M), \omega \in$ $\mathcal{C}_{p+1}^{\infty}(M)$ and $\tau \in \mathcal{H}_{p}$ satisfying $\varphi=d \eta+d^{*} \omega+\tau$.
Notice that $\left\langle d^{*} \beta, d \eta\right\rangle=\left\langle\beta, d^{2} \eta\right\rangle=\langle\beta, 0\rangle=0$ and $\langle h, d \eta\rangle=\left\langle d^{*} h, \eta\right\rangle=0$, by the duality between $d$ and $d^{*}$. Linearity then gives

$$
\begin{equation*}
\langle d \alpha, d \eta\rangle=\left\langle d \alpha+d^{*} \beta+h, d \eta\right\rangle=\langle 0, d \eta\rangle=0 \tag{3.6}
\end{equation*}
$$

Finally we have

$$
\begin{aligned}
\langle d \alpha, \varphi\rangle= & \langle d \alpha, d \eta\rangle+\left\langle d \alpha, d^{*} \omega\right\rangle+\langle d \alpha, \tau\rangle \\
& =0+\left\langle\alpha, d^{* 2} \omega\right\rangle+\langle\alpha, d \tau\rangle \text { by }(3.6) \\
& =\langle\alpha, 0\rangle+\langle\alpha, 0\rangle \text { because } d^{* 2}=0 \text { and } \tau \in \mathcal{H}_{p} \\
& =0 .
\end{aligned}
$$

Since $\mathcal{C}_{p}^{\infty}(M)$ is dense in $L_{p}^{r^{\prime}}(M), r^{\prime}$ being the conjugate exponent of $r$, and $\varphi$ is arbitrary, we see that $d \alpha=0$. Analogously, we see that $d^{*} \beta=0$ and it follows that $h=0$.

## 4 Case of $\Omega$ a domain in $M$.

Let $\Omega$ be a domain in a $\mathcal{C}^{\infty}$ smooth complete riemannian manifold $M$, compact or non compact; we want to show how the results in case of a compact boundary-less manifold apply to this case.

A classical way to get rid of a "annoying boundary" of a manifold is to use its "double". For instance: Duff [4], Hörmander [9, p. 257]. Here we copy the following construction from [7, Appendix $B]$.

Let $N$ be a relatively compact domain of $M$ such that $\partial N$ is a smooth hypersurface and $\bar{\Omega} \subset N$. The "Riemannian double" $D:=D(N)$ of $N$, obtained by gluing two copies of $N$ along $\partial N$, is a compact Riemannian manifold without boundary. Moreover, by its very construction, it is always possible to assume that $D$ contains an isometric copy of the original domain $N$, hence of the original $\Omega$. We shall also write $\Omega$ for its isometric copy to ease notations.

We shall need the following difficult result by N. Aronszajn, A. Krzywicki and J. Szarski 3], a strong continuation property, which says that if, for any compact set $K \subset M$, the $p$-form $\omega$ satisfies the following inequality

$$
\begin{equation*}
\langle d \omega, d \omega\rangle+\left\langle d^{*} \omega, d^{*} \omega\right\rangle \leq C(K)\langle\omega, \omega\rangle \tag{4.7}
\end{equation*}
$$

uniformly on $K$, then if $\omega$ is zero to infinite order at a point $x_{0} \in M$, we have that $\omega \equiv 0$. The regularity conditions on $\omega$ are to be $L^{2}(M)$ with strong $L^{2}$ derivatives. The $p$-form $\omega$ must vanish at $x_{0}$ with all derivatives in " $L^{1}$ mean", which is also much weaker than the usual notion.
We shall apply it to the compact manifold $D$ and with a $\mathcal{C}^{\infty}$ harmonic $p$-form $h$, hence which satisfies inequality (4.7), and which is zero on an open non void set, which also implies a zero of infinite order.

The main lemma of this section is:
Lemma 4.1. Let $\omega \in L_{p}^{r}(\Omega)$, then we can extend it to $\omega^{\prime} \in L_{p}^{r}(D)$ such that: $\forall h \in \mathcal{H}_{p}(D),\left\langle\omega^{\prime}, h\right\rangle_{D}=$ 0 .

Proof. Recall that $\mathcal{H}_{p}(D)$ is the vector space of harmonic $p$-form in $D$, it is of finite dimension $K_{p}$ and $\mathcal{H}_{p}(D) \subset \mathcal{C}^{\infty}(D)$.

Make an orthonormal basis $\left\{e_{1}, \ldots, e_{K_{p}}\right\}$ of $\mathcal{H}_{p}(D)$ with respect to $L_{p}^{2}(D)$, by the Gram-Schmidt procedure. We get $\left\langle e_{j}, e_{k}\right\rangle_{D}:=\int_{D} e_{j} e_{k} d V=\delta_{j k}$.
Set $\lambda_{j}:=\left\langle\omega \mathbb{1}_{\Omega}, e_{j}\right\rangle=\left\langle\omega, e_{j} \mathbb{1}_{\Omega}\right\rangle, j=1, \ldots, K_{p}$, which makes sense since $e_{j} \in \mathcal{C}^{\infty}(D) \Rightarrow e_{j} \in L^{\infty}(D)$, because $D$ is compact.

We shall see that the system $\left\{e_{k} \mathbb{1}_{D \backslash \Omega}\right\}_{k=1, \ldots, K_{p}}$ is a free one. Suppose this is not the case, then it will exist $\gamma_{1}, \ldots, \gamma_{K_{p}}$, not all zero, such that $\sum_{k=1}^{K_{p}} \gamma_{k} e_{k} 1_{D \backslash \Omega}=0$ in $D \backslash \Omega$. But the function $h:=\sum_{k=1}^{K_{p}} \gamma_{k} e_{k}$ is in $\mathcal{H}_{p}(D)$ so if $h$ is zero in $D \backslash \Omega$ which is non void, then $h \equiv 0$ in $D$ by the N . Aronszajn, A. Krzywicki and J. Szarski [3] result. This is not possible because the $e_{k}$ make a basis for $\mathcal{H}_{p}(D)$. So the system $\left\{e_{k} \mathbb{1}_{D \backslash \Omega}\right\}_{k=1, \ldots, K_{p}}$ is a free one.

We set $\gamma_{j k}:=\left\langle e_{k} \mathbb{1}_{D \backslash \Omega}, e_{j} \mathbb{1}_{D \backslash \Omega}\right\rangle$ hence we have that $\operatorname{det}\left\{\gamma_{j k}\right\} \neq 0$. So we can solve the linear system to get $\left\{\mu_{k}\right\}$ such that

$$
\begin{equation*}
\forall j=1, \ldots, K_{p}, \sum_{k=1}^{K_{p}} \mu_{k}\left\langle e_{k} 1_{D \backslash \Omega}, e_{j}\right\rangle=\lambda_{j} \tag{4.8}
\end{equation*}
$$

We put $\omega^{\prime \prime}:=\sum_{j=1}^{K_{p}} \mu_{j} e_{j} \mathbb{1}_{D \backslash \Omega}$ and $\omega^{\prime}:=\omega \mathbb{1}_{\Omega}-\omega^{\prime \prime} \mathbb{1}_{D \backslash \Omega}=\omega-\omega^{\prime \prime}$. From (4.8) we get

$$
\forall j=1, \ldots, K_{p},\left\langle\omega^{\prime}, e_{j}\right\rangle_{D}=\left\langle\omega, e_{j}\right\rangle-\left\langle\omega^{\prime \prime}, e_{j}\right\rangle=\lambda_{j}-\sum_{k=1}^{K_{p}} \mu_{k}\left\langle e_{k} \mathbb{1}_{D \backslash \Omega}, e_{j}\right\rangle=0
$$

So the $p$-form $\omega^{\prime}$ is orthogonal to $\mathcal{H}_{p}$. Moreover $\omega_{\mid \Omega}^{\prime}=\omega$ and clearly $\omega^{\prime \prime} \in L_{p}^{r}(D)$ being a finite combination of $e_{j} \mathbb{1}_{D \backslash \Omega}$, so $\omega^{\prime} \in L_{p}^{r}(D)$ because $\omega$ itself is in $L_{p}^{r}(D)$. The proof is complete.

Now let $\omega \in L^{r}(\Omega)$ and see $\Omega$ as a subset of $D$; then extend $\omega$ as $\omega^{\prime}$ to $D$ by Lemma 4.1.

By the results on the compact manifold $D$, because $\omega^{\prime} \perp \mathcal{H}_{p}(D)$, we get that there exists $u^{\prime} \in$ $W_{p}^{2, r}(D), u^{\prime} \perp \mathcal{H}_{p}(D)$, such that $\Delta u^{\prime}=\omega^{\prime}$; hence if $u$ is the restriction of $u^{\prime}$ to $\Omega$ we get $u \in$ $W_{p}^{2, r}(\Omega), \Delta u=\omega$ in $\Omega$.
Hence we proved
Theorem 4.2. Let $\Omega$ be a domain in the smooth complete riemannian manifold $M$ and $\omega \in L_{p}^{r}(\Omega)$, then there is a p-form $u \in W_{p}^{2, r}(\Omega)$, such that $\Delta u=\omega$ and $\|u\|_{W_{p}^{2, r}(\Omega)} \leq c(\Omega)\|\omega\|_{L_{p}^{r}(\Omega)}$.

As for domains in $\mathbb{R}^{n}$, there is no constrain for solving the Poisson equation in this case.
Corollary 4.3. (Of the proof) Let $M$ be a smooth compact riemannian manifold with smooth boundary $\partial M$. Let $\omega \in L_{p}^{r}(M)$. There is a form $u \in W_{p}^{2, r}(M)$, such that $\Delta u=\omega$ and $\|u\|_{W_{p}^{2, r}(M)} \leq$ $c\|\omega\|_{L_{p}^{r}(M)}$.

Proof. We can build the "double manifold" $D:=D(M)$ which is compact without boundary. Copying the proof of Theorem4.2 we extend the form $\omega$ defined on $M$, viewed as a subset in $D$, to a form $\omega^{\prime}$ in $L_{p}^{r}(D)$ orthogonal to $\mathcal{H}_{p}(D)$ so there is a $u^{\prime}:: \Delta u^{\prime}=\omega^{\prime}$ in $D$. We just take $u:=u_{\mid M}^{\prime}$ to finish the proof.

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