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THE ADJACENCY MATRIX AND THE DISCRETE LAPLACIAN ACTING ON FORMS

HATEM BALOUDI, SYLVAIN GOLÉNIA, AND AREF JERIBI

ABSTRACT. We study the relationship between the adjacency matrix and the discrete Laplacian acting on 1-forms. We also prove that if the adjacency matrix is bounded from below it is not necessarily essentially self-adjoint. We discuss the question of essential self-adjointness and the notion of completeness.

1. INTRODUCTION

Given a simple graph, the adjacency matrix \mathcal{A} is unbounded from above if and only if the degree of the graph is unbounded. It is more complicated to characterize the fact that it is unbounded from below. In [Go] one gives an optimal and necessary. The examples provided in [Go] satisfy :

- 1) \mathcal{A} is not bounded from above,
- 2) \mathcal{A} is bounded from below,
- 3) \mathcal{A} is essentially self-adjoint.

In [Go], one asks the question. Can we have 1 and 2 without having 3? In Corollary 5.3 we answer positively to this question. Moreover, relying on different ideas than in [Go], we provide a large class of graphs satisfying 1 and 2. Our approach is based on establishing a link between the adjacency matrices and the discrete Laplacian Δ_1 acting on 1-forms.

The article is organized as follows: In Section 2, we present general definitions about graphs. Then we define five different types of discrete operator associated to a locally finite graphs (the adjacency matrix, two discrete Laplacians acting on vertices, two discrete Laplacians acting on edges). The link between these definitions is made in Section 3.2. In Section 4, we start with the question of unboundedness and give a upper bound on the infimum of the essential spectrum. In Section 5.1 we provide a counter example to essential self-adjointness for the Laplacian acting on 1-forms. In Section 5.2 we present the notion of χ -completeness which was introduced in [AnTo] and develop it through optimal examples. Then in Section 5.3 we confront this criterion to other type of approaches. Finally in Section 5.4 we provide a new criterion of essential self-adjointness for the adjacency matrix.

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2. GRAPH STRUCTURES

2.1. Generalities about graphs. We recall some standard definitions of graph theory. A *graph* is a triple $\mathcal{G} := (\mathcal{E}, \mathcal{V}, m)$, where \mathcal{V} is countable set (the *vertices*), $\mathcal{E} : \mathcal{V} \times \mathcal{V} \rightarrow \mathbb{R}_+$ (the *edges*) is symmetric, and $m : \mathcal{V} \rightarrow (0, \infty)$ is a weight. When $m = 1$, we simply write $\mathcal{G} = (\mathcal{E}, \mathcal{V})$. We say that \mathcal{G} is *simple* if $m = 1$ and $\mathcal{E} : \mathcal{V} \times \mathcal{V} \rightarrow \{0, 1\}$.

Given $x, y \in \mathcal{V}$, we say that x and y are *neighbors* if $\mathcal{E}(x, y) > 0$. We denote this relationship by $x \sim y$ and the set of neighbors of x by $\mathcal{N}_{\mathcal{G}}(x)$. We say there is a *loop* in $x \in \mathcal{V}$ if $\mathcal{E}(x, x) > 0$. A graph is *connected* if for all $x, y \in \mathcal{V}$, there exists a path γ joining x and y . Here, γ is a sequence $x_0, x_1, \dots, x_n \in \mathcal{V}$ such that $x = x_0$, $y = x_n$, and $x_j \sim x_{j+1}$ for all $0 \leq j \leq n-1$. In this case, we endow \mathcal{V} with the metric $\rho_{\mathcal{G}}$ defined by

$$(1) \quad \rho_{\mathcal{G}}(x, y) := \inf\{|\gamma|, \gamma \text{ is a path joining } x \text{ and } y\}.$$

A x -triangle given by (x, y, z, x) is different from the one given by (x, z, y, x) .

A graph \mathcal{G} is *locally finite* if $d_{\mathcal{G}}(x)$ is finite for all $x \in \mathcal{V}$. In the sequel, we assume that:

All graphs are locally finite, connected with no loops.

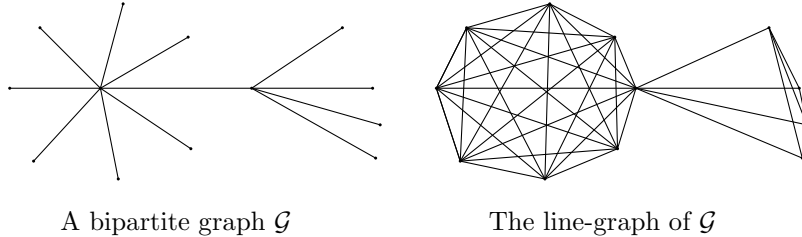
A graph $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ is *bi-partite* if there are \mathcal{V}_1 and \mathcal{V}_2 such that $\mathcal{V}_1 \cap \mathcal{V}_2 = \emptyset$, $\mathcal{V}_1 \cup \mathcal{V}_2 = \mathcal{V}$, and such that $\mathcal{E}(x, y) = 0$ for all $(x, y) \in \mathcal{V}_1^2 \cup \mathcal{V}_2^2$.

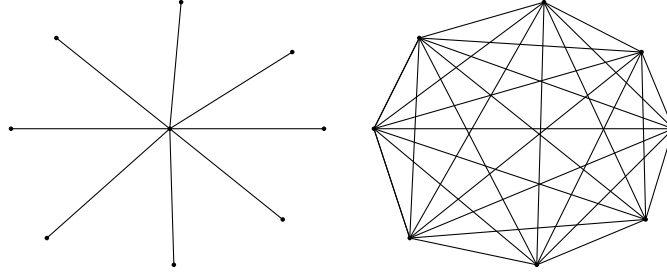
Definition 2.1. Given a graph $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$, we define the line graph of \mathcal{G} the graph $\tilde{\mathcal{G}} := (\tilde{\mathcal{E}}, \tilde{\mathcal{V}})$ where $\tilde{\mathcal{V}}$ is the set of edges of \mathcal{G} and

$$\tilde{\mathcal{E}}((x_0, y_0), (x, y)) = \frac{\sqrt{\mathcal{E}(x_0, y_0)\mathcal{E}(x, y)}}{m(x)} 1_{x=x_0} + \frac{\sqrt{\mathcal{E}(x_0, y_0)\mathcal{E}(x, y)}}{m(y)} 1_{y=y_0},$$

if $(x_0, y_0) \neq (x, y)$ and 0 otherwise.

The choice of the weight $\tilde{\mathcal{E}}$ seems a bit arbitrary but is motivated by Proposition 3.1. We stress that $\tilde{m} = 1$. Others choices can be made, e.g., [EvLa]. We refer to [Ha][Chapter 8] for a presentation of this class in the setting of simple graphs.



A graph $K_{1,8}$ $\widetilde{K_{1,8}}$ is the complete graph K_8

As we see on this example, the line-graph is obtained by gluing together some complete graphs. This is not true in general. The classification of the line-graphs of a finite graph is well-known, see [Ha][Theorem 8.4].

We present the relationship between bipartite graphs and line graphs. We recall that C_n denotes the n -cycle graph, i.e., $\mathcal{V} := \mathbb{Z}/n\mathbb{Z}$, where $\mathcal{E}(x, y) = 1$ if and only if $|x - y| = 1$.

Proposition 2.2. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a bipartite graph. Then the two following assertions are equivalent:*

- 1) $\mathcal{G} \simeq \widetilde{\mathcal{G}}$,
- 2) $\mathcal{G} \in \{\mathbb{Z}, \mathbb{N}, C_{2n} : n \in \mathbb{N}\}$.

Proof. It clear that (2) \Rightarrow (1). Now, suppose that $\mathcal{G} \simeq \widetilde{\mathcal{G}}$. Then $\widetilde{\mathcal{G}}$ not contain x -triangles. If $d_{\mathcal{G}}(x) \geq 3$, for all $x \in \mathcal{V}$, then there exist a x -triangle of $\widetilde{\mathcal{G}}$. So, $d_{\mathcal{G}}(x) \leq 2 \forall x \in \mathcal{V}$. This proof is complete. \square

2.2. The adjacency matrix. Set $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ a weighted graph. We define the set of 0-cochains $\mathcal{C}(\mathcal{V}) := \{f : \mathcal{V} \rightarrow \mathbb{C}\}$. We denote by $\mathcal{C}^c(\mathcal{V})$ the 0-cochains with finite support in \mathcal{V} . We associate a Hilbert space to \mathcal{V} .

$$\ell^2(\mathcal{V}) := \left\{ f \in \mathcal{C}(\mathcal{V}) \text{ such that } \|f\|^2 := \sum_{x \in \mathcal{V}} m(x) |f(x)|^2 < \infty \right\}.$$

The associated scalar product is given by

$$\langle f, g \rangle := \sum_{x \in \mathcal{V}} m(x) \overline{f(x)} g(x), \text{ for } f, g \in \ell^2(\mathcal{V}).$$

We define the *adjacency matrix*:

$$\mathcal{A}_{\mathcal{G}}(f)(x) := \frac{1}{m(x)} \sum_{y \in \mathcal{V}} \mathcal{E}(x, y) f(y)$$

for $f \in \mathcal{C}^c(\mathcal{V})$. It is symmetric and thus closable. We denote its closure by the same symbol. We denote the *degree* by

$$\deg_{\mathcal{G}}(x) := \frac{1}{m(x)} \sum_{y \in \mathcal{V}} \mathcal{E}(x, y).$$

When $m = 1$, we have that $\mathcal{A}_{\mathcal{G}}$ is unbounded if and only it is unbounded from above and if and only if the degree is unbounded. The fact that $\mathcal{A}_{\mathcal{G}}$ is unbounded from

below or not is a delicate question, see [Go]. We refer to [GoSc] for the description of some self-adjoint extensions.

3. THE LAPLACIANS ACTING ON EDGES

3.1. The symmetric and anti-symmetric spaces. In the previous section we defined a Hilbert structure on the set of vertices. We can endow two different Hilbert structures on the set of edges. Both have their own interest.

Given a weighted graph $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$, the set of 1-cochains (or 1-forms) is given by:

$$\mathcal{C}_{\text{anti}}(\mathcal{E}) := \{f : \mathcal{V} \times \mathcal{V} \rightarrow \mathbb{C}, f(x, y) = -f(y, x) \text{ for all } x, y \in \mathcal{V}\},$$

where anti stands for anti-symmetric. This corresponds to fermionic statistics. Concerning bosonic statistics, we define:

$$\mathcal{C}_{\text{sym}}(\mathcal{E}) := \{f : \mathcal{V} \times \mathcal{V} \rightarrow \mathbb{C}, f(x, y) = f(y, x) \text{ for all } x, y \in \mathcal{V}\}.$$

The sets of functions with finite support are denoted by $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$ and $\mathcal{C}_{\text{sym}}^c(\mathcal{E})$, respectively.

We turn to the Hilbert structures.

$$\ell_{\text{anti}}^2(\mathcal{E}) := \left\{ f \in \mathcal{C}_{\text{anti}}(\mathcal{E}) \text{ such that } \|f\|^2 := \frac{1}{2} \sum_{x, y \in \mathcal{V}} \mathcal{E}(x, y) |f(x, y)|^2 < \infty \right\}$$

and

$$\ell_{\text{sym}}^2(\mathcal{E}) := \left\{ f \in \mathcal{C}_{\text{sym}}(\mathcal{E}) \text{ such that } \|f\|^2 := \frac{1}{2} \sum_{x, y \in \mathcal{V}} \mathcal{E}(x, y) |f(x, y)|^2 < \infty \right\}.$$

The associated scalar product is given by

$$\langle f, g \rangle := \frac{1}{2} \sum_{x, y \in \mathcal{V}} \mathcal{E}(x, y) \overline{f(x, y)} g(x, y),$$

when f and g are both in $\ell_{\text{anti}}^2(\mathcal{E})$ or in $\ell_{\text{sym}}^2(\mathcal{E})$.

We start by defining operator in the anti-symmetric case. The *difference operator* is defined as

$$d := d_{\text{anti}} : \mathcal{C}^c(\mathcal{V}) \longrightarrow \mathcal{C}_{\text{anti}}^c(\mathcal{E}), \quad d(f)(x, y) := f(y) - f(x).$$

The *coboundary operator* is the formal adjoint of d . We set:

$$d^* := d_{\text{anti}}^* : \mathcal{C}_{\text{anti}}^c(\mathcal{E}) \longrightarrow \mathcal{C}^c(\mathcal{V}), \quad d^*(f)(x) := \frac{1}{m(x)} \sum_{y \in \mathcal{V}} \mathcal{E}(y, x) f(y, x).$$

We denote by the same symbols their closures. The Gauß-Bonnet operator is defined on $\mathcal{C}^c(\mathcal{V}) \oplus \mathcal{C}_{\text{anti}}^c(\mathcal{E})$ by

$$D := d + d^* \cong \begin{pmatrix} 0 & d^* \\ d & 0 \end{pmatrix}.$$

This operator is motivated by geometry, see [AnTo]. It is also a Dirac-like operator. The associated Laplacian is defined as $\Delta := D^2 = \Delta_0 \oplus \Delta_1$ where Δ_0 is the discrete Laplacian acting on 0-forms given by

$$(2) \quad \Delta_0(f)(x) := (d^* d)(f)(x) = \frac{1}{m(x)} \sum_y \mathcal{E}(x, y) (f(x) - f(y)),$$

with $f \in \mathcal{C}^c(\mathcal{V})$, and where the discrete Laplacian acting on 1-forms is given by

$$(3) \quad \begin{aligned} \Delta_1(f)(x, y) &:= (dd^*)(f)(x, y) \\ &= \frac{1}{m(x)} \sum_{z \in \mathcal{V}} \mathcal{E}(x, z) f(x, z) + \frac{1}{m(y)} \sum_{z \in \mathcal{V}} \mathcal{E}(z, y) f(z, y), \end{aligned}$$

with $f \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$. Both operators are symmetric and thus closable. We denote the closure by Δ_0 (resp. Δ_1), its domain by $\mathcal{D}(\Delta_0)$ (resp. $\mathcal{D}(\Delta_1)$), and its adjoint by Δ_0^* (resp. Δ_1^*).

In [Wo], one proves that Δ_0 is essentially self-adjoint on $\mathcal{C}^c(\mathcal{V})$ when the graph is simple. The literature on the subject is large and refer to [Go2] for historical purposes. In [AnTo], they prove that D is essentially self-adjoint on $\mathcal{C}^c(\mathcal{V}) \oplus \mathcal{C}_{\text{anti}}^c(\mathcal{E})$ if and only if $\Delta_0 \oplus \Delta_1$ is essentially self-adjoint on $\mathcal{C}^c(\mathcal{V}) \oplus \mathcal{C}_{\text{anti}}^c(\mathcal{E})$. Moreover they provide a criterion based on the completeness of a metric. In Section 5.1 we provide a counter example to essential self-adjointness for the Laplacian acting on 1-forms. Then in Section 5.2 we discuss the notion of χ -completeness that was introduced in [AnTo]. This notion is related to the one of intrinsic metric, e.g., [HKMW] and references therein.

We turn to the symmetric choice. We set :

$$d_{\text{sym}} : \mathcal{C}^c(\mathcal{V}) \longrightarrow \mathcal{C}_{\text{sym}}^c(\mathcal{E}), \quad d_{\text{sym}}(f)(x, y) := f(y) + f(x).$$

It is interesting to note that d_{sym} is in fact the *incidence matrix* of \mathcal{G} . Indeed

$$d_{\text{sym}}(\delta_{x_0})(x, y) = \begin{cases} 1, & \text{if } x_0 \in \{x, y\}, \\ 0, & \text{otherwise.} \end{cases}$$

The formal adjoint of the incidence matrix is given by:

$$d_{\text{sym}}^* : \mathcal{C}_{\text{sym}}^c(\mathcal{E}) \longrightarrow \mathcal{C}^c(\mathcal{V}), \quad d_{\text{sym}}^*(f)(x) := \frac{1}{m(x)} \sum_{y \in \mathcal{V}} \mathcal{E}(y, x) f(y, x).$$

A direct computation gives that :

$$\Delta_{0, \text{sym}} f(x) := (d_{\text{sym}}^* d_{\text{sym}}) f(x) = \frac{1}{m(x)} \sum_y \mathcal{E}(x, y) (f(x) + f(y)),$$

for all $f \in \mathcal{C}^c(\mathcal{V})$ and

$$(4) \quad \begin{aligned} \Delta_{1, \text{sym}} f(x, y) &:= (d_{\text{sym}} d_{\text{sym}}^*) f(x, y) \\ &= \frac{1}{m(x)} \sum_{z \in \mathcal{V}} \mathcal{E}(x, z) f(x, z) + \frac{1}{m(y)} \sum_{z \in \mathcal{V}} \mathcal{E}(z, y) f(z, y), \end{aligned}$$

for all $f \in \mathcal{C}_{\text{sym}}^c(\mathcal{E})$.

We denote by the same symbol the closure of these operators. We turn to this central observation.

Proposition 3.1. *Set $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$. The operator $\Delta_{1, \text{sym}}$ is unitarily equivalent to*

$$\mathcal{A}_{\tilde{\mathcal{G}}} + V(\cdot, \cdot),$$

where

$$V(x, y) := \mathcal{E}(x, y) \left(\frac{1}{m(x)} + \frac{1}{m(y)} \right)$$

and $\tilde{\mathcal{G}}$ denotes the line-graph of \mathcal{G} , see Definition 2.1.

It is important to note that $\ell_{\text{sym}}^2(\mathcal{E})$ is a weighted space, whereas $\ell^2(\tilde{\mathcal{V}})$ is not one. This proposition is part of the folklore in the case of finite and unweighted graphs.

Proof. We set $U : \ell_{\text{sym}}^2(\mathcal{E}) \rightarrow \ell^2(\tilde{\mathcal{V}}, 1)$ as being the unitary transformation given by $Uf(x, y) := \sqrt{\mathcal{E}(x, y)}f(x, y)$. We have $(U\Delta_{1, \text{sym}}U^{-1})f(x, y) =$

$$\sum_{z \in \mathcal{V}} \left(\frac{\sqrt{\mathcal{E}(x, y)\mathcal{E}(x, z)}}{m(x)} f(x, z) + \frac{\sqrt{\mathcal{E}(x, y)\mathcal{E}(z, y)}}{m(y)} f(z, y) \right),$$

for all $f \in \mathcal{C}^c(\tilde{\mathcal{V}})$. Remembering the definition of the weights for a line-graph, we obtain the result. \square

Corollary 3.2. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a weighted graph. If*

$$c := \sup_{x, y \in \mathcal{V}} \mathcal{E}(x, y) \left(\frac{1}{m(x)} + \frac{1}{m(y)} \right) < \infty$$

then $\mathcal{A}_{\tilde{\mathcal{G}}} \geq -c$. In particular, $\mathcal{A}_{\tilde{\mathcal{G}}} \geq -2$ when \mathcal{G} is simple.

In the setting of simple graphs, in [Go], one gives a necessary condition for the semi-boundedness of the adjacency matrix. The *lower local complexity* of a graph \mathcal{G} is defined by

$$C_{\text{loc}}(\mathcal{G}) := \inf \bigcap \left\{ \overline{\left\{ \frac{N_{\mathcal{G}}(x)}{d_{\mathcal{G}}^2(x)}, x \in \mathcal{V} \text{ and } d_{\mathcal{G}}(x) \geq n \right\}}, n \in \mathbb{N} \right\},$$

where $N_{\mathcal{G}}(x) := \#\{x - \text{triangles}\}$. The *sub-lower local complexity* of a graph \mathcal{G} is defined by

$$C_{\text{loc}}^{\text{sub}}(\mathcal{G}) = \inf_{\{\mathcal{G}' \subset \mathcal{G}, \sup d_{\mathcal{G}'} = \infty\}} C_{\text{loc}}(\mathcal{G}'),$$

where \mathcal{G}' is a sub-graph of \mathcal{G} , i.e., \mathcal{G}' is a graph whose vertex set is a subset of that of \mathcal{G} , and whose adjacency relation is a subset of that of \mathcal{G} restricted to this subset.

We recall [Go, Theorem 1.1]:

Theorem 3.3. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a locally finite graph of unbounded class. Let $\hat{\mathcal{A}}_{\mathcal{G}}$ be a self-adjoint realization of the $\mathcal{A}_{\mathcal{G}}$. Suppose that \mathcal{E} is bounded. Then, one has:*

- 1) $\hat{\mathcal{A}}_{\mathcal{G}}$ is unbounded from above.
- 2) If $C_{\text{loc}}^{\text{sub}}(\mathcal{G}) = 0$, then $\hat{\mathcal{A}}_{\mathcal{G}}$ is unbounded from below.
- 3) For all $\varepsilon > 0$, there is a connected simple graph \mathcal{G} such that $C_{\text{loc}}(\mathcal{G}) \in (0, \varepsilon)$, $\mathcal{A}_{\mathcal{G}}$ is essentially self-adjoint on $\mathcal{C}^c(\mathcal{V})$ and is bounded from below.

The line-graph do not lead to the optimality that is obtained in third point. Indeed, by repeating the proof of [Go, Proposition 3.2] we obtain that given $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a locally finite simple bipartite graph, then

$$C_{\text{loc}}^{\text{sub}}(\tilde{\mathcal{G}}) > \frac{1}{10}.$$

3.2. Breaking symmetry. We have that (3) and (4) have the same expression. However they do not act on the same spaces. When \mathcal{G} is bi-partite, we shall prove that the two operators are unitarily equivalent.

We now fix an orientation of a graph $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$. For each edge there are two possible choices. For $x, y \in \mathcal{V}$ such that $\mathcal{E}(x, y) \neq 0$, we write $x \rightarrow y$ or $y \rightarrow x$, following the choice of the orientation.

Let $U : \ell_{\text{anti}}^2(\mathcal{E}) \rightarrow \ell_{\text{sym}}^2(\mathcal{E})$ be the unitary map given by

$$(Uf)(x, y) = \text{sign}(x, y)f(x, y), \quad \text{where } \text{sign}(x, y) := \begin{cases} 1, & \text{if } x \rightarrow y, \\ -1, & \text{if } y \rightarrow x. \end{cases}$$

Note that $(U^{-1}f)(x, y) = \text{sign}(x, y)f(x, y)$. Therefore, for $x_0, y_0 \in \mathcal{V}$ and $f \in \ell_{\text{sym}}^2(\mathcal{E})$ we have

$$(5) \quad \begin{aligned} U\Delta_1 U^{-1}f(x_0, y_0) &= \text{sign}(x_0, y_0) \left(\frac{1}{m(y_0)} \sum_{x \in \mathcal{V}} \mathcal{E}(x, y_0) \text{sign}(x, y_0) f(x, y_0) \right. \\ &\quad \left. + \frac{1}{m(x_0)} \sum_{y \in \mathcal{V}} \mathcal{E}(x_0, y) \text{sign}(x_0, y) f(x_0, y) \right). \end{aligned}$$

In order to take advantage of this transformation, one has to choose the orientation in a good way. We have :

Proposition 3.4. *Assume that $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ is a bi-partite weighted space, then Δ_1 and $\Delta_{1, \text{sym}}$ are unitarily equivalent. In particular, if we also have that \mathcal{G} is simple, Δ_1 is unitarily equivalent to $\mathcal{A}_{\tilde{\mathcal{G}}} + 2\text{id}$.*

Proof. We consider the bi-partite decomposition $\{\mathcal{V}_1, \mathcal{V}_2\}$ of the graph \mathcal{G} . For $x \in \mathcal{V}_1$ and $y \in \mathcal{V}_2$, we set $x \rightarrow y$. From (5), we see that all the products of the signs are being 1. This gives the first part. For the rest, apply Proposition 3.1. \square

Since the line-graph of \mathbb{Z} is itself and it is also bi-partite, we can make a different choice of orientation.

Example 3.5. *We consider on \mathbb{Z} the orientation $n \rightarrow n + 1$, for all $n \in \mathbb{Z}$.*



Note that $\tilde{\mathbb{Z}} \simeq \mathbb{Z}$. Moreover, we have:

$$(U\Delta_1 U^{-1})f(n, n+1) = 2f(n, n+1) - \mathcal{A}_{\tilde{\mathcal{G}}}f(n, n+1).$$

Therefore, Δ_1 and $2I - \mathcal{A}_{\tilde{\mathcal{G}}}$ are unitarily equivalent.

4. ON THE SPECTRAL PROPERTIES OF THE LAPLACIAN ACTING ON FORMS

We start with the question of unboundedness.

Proposition 4.1. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a weighted graph. Then Δ_1 is bounded if and only if $\Delta_{1, \text{sym}}$ is bounded if and only if Δ_0 is bounded if and only if*

$$\sup_{x \in \mathcal{V}} \deg_{\mathcal{G}}(x) < \infty.$$

Proof. The last equivalence is well-known, e.g., [KL2]. On one side we have

$$0 \leq \langle f, \Delta_0 f \rangle \leq \langle f, 2 \deg_{\mathcal{G}}(\cdot) f \rangle,$$

for all $f \in \mathcal{C}^c(\mathcal{V})$ and on the other side $\langle \delta_x, \Delta_0 \delta_x \rangle = \deg_{\mathcal{G}}(x)$. The same statements hold true for $\Delta_{0, \text{sym}}$.

We turn to Δ_1 . We denote by \mathcal{F} the Friedrichs extension.

$$\begin{aligned} \Delta_1 \text{ is bounded} &\Leftrightarrow \Delta_1^{\mathcal{F}} \text{ is bounded} \Leftrightarrow d^* \text{ is bounded} \\ &\Leftrightarrow d \text{ is bounded} \Leftrightarrow \Delta_0 \text{ is bounded.} \end{aligned}$$

The second equivalence comes from the fact that $\|(\Delta_1^{\mathcal{F}})^{1/2}f\| = \|d^*f\|$, for all $f \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$ and by construction of the Friedrichs extension (e.g., [ReSi]). The last one is of the same type. The equivalence with $\Delta_{1,\text{sym}}$ is similar. \square

Using the Persson's Lemma we give the following result:

Proposition 4.2. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be an infinite and $\Delta_1^{\mathcal{F}}$ be a Friedrichs extension of Δ_1 . Then*

$$\inf \sigma(\Delta_1^{\mathcal{F}}) \leq \inf_{x,y \in \mathcal{V}, x \sim y} \left(\frac{1}{m(x)} + \frac{1}{m(y)} \right) \mathcal{E}(x, y)$$

and

$$\inf \sigma_{\text{ess}}(\Delta_1^{\mathcal{F}}) \leq \inf_{K \subset \mathcal{E}, K \text{ finite}} \inf_{(x,y) \in K^c, x \sim y} \left(\frac{1}{m(x)} + \frac{1}{m(y)} \right) \mathcal{E}(x, y).$$

In particular, $\Delta_1^{\mathcal{F}}$ is not with compact resolvent when \mathcal{G} is simple and infinite.

The last statement really differs from the situation case of Δ_0 . Indeed, in the case of a simple sparse graph (a planar graph for instance), one has that $\mathcal{D}(\Delta_0^{1/2}) = \mathcal{D}(\deg_G^{1/2}(\cdot))$, see [BGK] and also [Go2]. In particular we have that Δ_0 is with compact resolvent if and only if $\lim_{|x| \rightarrow \infty} \deg_G(x) = \infty$.

Proof. Let $x_0, y_0 \in \mathcal{V}$ such that $\mathcal{E}(x_0, y_0) \neq 0$. Then,

$$\left\langle \frac{\delta_{x_0, y_0} - \delta_{y_0, x_0}}{\sqrt{\mathcal{E}(x_0, y_0)}}, \Delta_1^{\mathcal{F}} \left(\frac{\delta_{x_0, y_0} - \delta_{y_0, x_0}}{\sqrt{\mathcal{E}(x_0, y_0)}} \right) \right\rangle = \left(\frac{1}{m(x_0)} + \frac{1}{m(y_0)} \right) \mathcal{E}(x_0, y_0).$$

Recalling

$$(6) \quad \left\| \frac{\delta_{x_0, y_0} - \delta_{y_0, x_0}}{\sqrt{\mathcal{E}(x_0, y_0)}} \right\| = 1.$$

and the Persson's Lemma, e.g., [KL2][Proposition 18], the result follows. \square

Remark 4.3. *The same result holds true for the operator $\Delta_{1,\text{sym}}$ by changing the $-$ into $+$ in (6).*

5. ESSENTIAL SELF-ADJOINTNESS

From now on, we concentrate on the analysis of Δ_1 . The results for $\Delta_{1,\text{sym}}$ are the same and the proofs need only minor changes.

5.1. A counter example. First it is important to notice that unlike Δ_0 , Δ_1 , define as the closure of (3), is not necessarily self-adjoint on simple graphs.

Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be radial simple tree. We denote the origin by ν and the spheres by $\mathcal{S}_n := \{x \in \mathcal{V}, \rho_{\mathcal{G}}(\nu, x) = n\}$. Let $\text{off}(n) := |\mathcal{S}_{n+1}|/|\mathcal{S}_n|$ be the *offspring* of the n -th generation.

Theorem 5.1. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a radial simple tree. Suppose that*

$$(7) \quad n \mapsto \frac{\text{off}^2(n)}{\text{off}(n+1)} \in \ell^1(\mathbb{N}).$$

Then, Δ_1 does not essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$ and the deficiency indices are infinite.

Proof. Set $f \in \ell_{\text{anti}}^2(\mathcal{E}) \setminus \{0\}$ such that $f \in \ker(\Delta_1^* + i)$ and such that f is constant on $\mathcal{S}_n \times \mathcal{S}_{n+1}$. We denote the constant value by C_n . So, we have the following equation

$$(\text{off}(n) + 1 + i)C_n - C_{n+1}\text{off}(n+1) - C_{n-1} = 0.$$

Therefore,

$$\begin{aligned} \|f|_{\mathcal{S}_{n+1} \times \mathcal{S}_{n+2}}\|^2 &= |C_{n+1}|^2 \prod_{i=0}^{n+1} \text{off}(i) \\ &\leq 2 \frac{|\text{off}(n) + 1 - i|^2}{\text{off}^2(n+1)} \prod_{i=0}^{n+1} \text{off}(i) |C_n|^2 + 2 \frac{1}{\text{off}^2(n+1)} \prod_{i=0}^{n+1} \text{off}(i) |C_{n-1}|^2. \\ &= 2 \frac{|\text{off}(n) + 1 - i|^2}{\text{off}(n+1)} \|f|_{\mathcal{S}_n \times \mathcal{S}_{n+1}}\|^2 + 2 \frac{\text{off}(n)}{\text{off}(n+1)} \|f|_{\mathcal{S}_{n-1} \times \mathcal{S}_n}\|^2. \end{aligned}$$

Since $\frac{\text{off}^2(n)}{\text{off}(n+1)}$ tends to 0 as n goes to infinity, we get by induction:

$$C := \sup_{n \in \mathbb{N}} \|f|_{\mathcal{S}_n \times \mathcal{S}_{n+1}}\|^2 < \infty.$$

Then, we have

$$\|f|_{\mathcal{S}_{n+1} \times \mathcal{S}_{n+2}}\|^2 \leq 2C \left(\frac{|\text{off}(n) + 1 - i|^2}{\text{off}(n+1)} + \frac{\text{off}(n)}{\text{off}(n+1)} \right).$$

By (7), we conclude that $f \in \ell^2(\mathcal{E})$ and that $\dim \ker(\Delta_1^* + i) \geq 1$. Using [ReSi, Theorem X.36] we derive that Δ_1 is not essentially self-adjoint.

Finally, since the deficiency indices are stable under bounded perturbation, by cutting off the graph large enough, we reproduce the same proof with an arbitrary large number of identical and disjoint trees, we see that $\dim \ker(\Delta_1^* + i) = \infty$. \square

Remark 5.2. *For the adjacency matrix, we are able to construct an example of simple graph where the deficiency indices are equal to 1, see [GoSc2]. The case of Δ_1 is more complicated and we were not able to find an example where the deficiency indices are finite. We leave this question open.*

We can answer a problem which was left open in [GoSc].

Corollary 5.3. *There exists a locally finite simple graph $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ such that $\mathcal{A}_{\mathcal{G}}$ is bounded from below by -2 and such that $\mathcal{A}_{\mathcal{G}}$ is not essentially self-adjoint on $\mathcal{C}^c(\mathcal{V})$.*

Proof. Combine Theorem 5.1 with Proposition 3.4. \square

5.2. Completeness. We first recall a criterion obtained in [AnTo]. They introduce the following definition (see references therein for historical purposes).

Definition 5.4. *The graph $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ is χ -complete if there exists a increasing sequence of finite set $(\mathcal{O}_n)_n$ such that $\mathcal{V} = \cup_n \mathcal{O}_n$ and there exist related functions χ_n satisfying the following three conditions:*

- 1) $\chi_n \in \mathcal{C}^c(\mathcal{V})$, $0 \leq \chi_n \leq 1$,
- 2) $\chi_n(x) = 1$ if $x \in \mathcal{O}_n$,
- 3) $\exists C > 0$, $\forall n \in \mathbb{N}$, $x \in \mathcal{V}$, such that

$$\frac{1}{m(x)} \sum_y \mathcal{E}(x, y) |\chi_n(x) - \chi_n(y)|^2 \leq C.$$

The result of [AnTo], can be reformulate as follows:

Theorem 5.5. *Take $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ to be χ -complete. Then Δ_1 is essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$.*

Remark 5.6. *The converse is an open problem. The aim of the next sections is to tackle it.*

5.2.1. A sharp example. Theorem 5.5 is abstract and may be difficult to check in concrete settings. In [AnTo], they provide only one example. Moreover, they do not give a concrete way to prove that a graph is not χ -complete. To start-off we provide a sharp example.

Proposition 5.7. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a locally finite simple tree, endowed with an origin such that $\text{off}(n) := \text{off}(x)$ for all $x \in \mathcal{S}_n$. Then the graph \mathcal{G} is χ -complete is and only if*

$$\sum_{n=1}^{\infty} \frac{1}{\sqrt{\text{off}(n)}} = \infty.$$

Example 5.8. *Set $\alpha > 0$. Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a locally finite simple tree, endowed with an origin such that $\text{off}(x) = \lfloor n^\alpha \rfloor$ for all $x \in \mathcal{S}_n$. Then the graph \mathcal{G} is χ -complete is and only if $\alpha \leq 2$.*

Proof. Suppose that the series converges and that \mathcal{G} is χ -complete. Let $(\chi_n)_{n \in \mathbb{N}}$ be as in the definition. Using 3), we get:

$$|\chi_n(m) - \chi_n(m+1)| \leq \frac{\sqrt{C}}{\sqrt{\text{off}(m)}}.$$

Moreover, by convergence of the series, there is $N \in \mathbb{N}$ such that

$$\sum_{k=N}^{\infty} \frac{1}{\sqrt{\lfloor n^\alpha \rfloor}} < \frac{1}{2\sqrt{C}}.$$

Then, by 2), there is $n_0 \in \mathbb{N}$ such that $\chi_{n_0}(x) = 1$ for all $|x| \leq N$. Since χ_{n_0} is with finite support, there is $M \in \mathbb{N}$ such that $\chi_{n_0}(x) = 0$ for all $|x| \geq N+M$. Therefore,

$$\begin{aligned} 1 &= |\chi_{n_0}(N) - \chi_{n_0}(N+M)| \\ &\leq |\chi_{n_0}(N) - \chi_{n_0}(N+1)| + \dots + |\chi_{n_0}(N+M-1) - \chi_{n_0}(N+M)| \\ &\leq \sqrt{C} \sum_{n=N}^{N+M-1} \frac{1}{\sqrt{\lfloor n^\alpha \rfloor}} < \frac{1}{2}. \end{aligned}$$

Contradiction. Therefore if the series converges, then \mathcal{G} is not χ -complete.

Suppose now that the series diverges. Set

$$\chi_n(x) := \begin{cases} 1, & \text{if } |x| \leq n, \\ \max\left(0, 1 - \sum_{k=n}^{|x|-1} \frac{1}{\sqrt{\text{off}(k)}}\right), & \text{if } |x| > n. \end{cases}$$

Since the series diverges, χ_n is with compact support and satisfies the definition of χ -completeness. \square

5.2.2. 1-dimensional decomposition. We now strengthen the previous example and follow ideas of [BG].

Definition 5.9. A 1-dimensional decomposition of the graph $\mathcal{G} := (\mathcal{V}, \mathcal{E})$ is a family of finite sets $(S_n)_{n \geq 0}$ which forms a partition of \mathcal{V} , that is $\mathcal{V} = \sqcup_{n \geq 0} S_n$, and such that for all $x \in S_n, y \in S_m$,

$$\mathcal{E}(x, y) > 0 \implies |n - m| \leq 1.$$

Given such a 1-dimensional decomposition, we write $|x| := n$ if $x \in S_n$. We also write $B_N := \cup_{0 \leq i \leq N} S_i$.

We stress that S_0 is not asked to be a single point.

Example 5.10. Typical examples of such a 1-dimensional decomposition are given by level sets of the graph distance function to a finite set S_0 that is

$$(8) \quad S_n := \{x \in \mathcal{V}, \rho_{\mathcal{G}}(x, S_0) = n\},$$

where the graph distance function $\rho_{\mathcal{G}}$ is defined by (1). Note that for a general 1-dimensional decomposition, one has solely $\rho_{\mathcal{G}}(x, S_0) \geq n$, for $x \in S_n$.

We define the inner boundary of S_n by

$$S_n^- := \{x \in S_n, \exists y \in S_{n-1}, \mathcal{E}(x, y) > 0\}$$

and the outer boundary by

$$S_n^+ := \{x \in S_n, \exists y \in S_{n+1}, \mathcal{E}(x, y) > 0\}.$$

We now divide the degree with respect to the 1-dimensional decomposition. Given $x \in S_n$, we set

$$\deg_{\pm}(x) := \frac{1}{m(x)} \sum_{y \in S_{n \pm 1}} \mathcal{E}(x, y), \quad \deg_0(x) := \frac{1}{m(x)} \sum_{y \in S_n} \mathcal{E}(x, y),$$

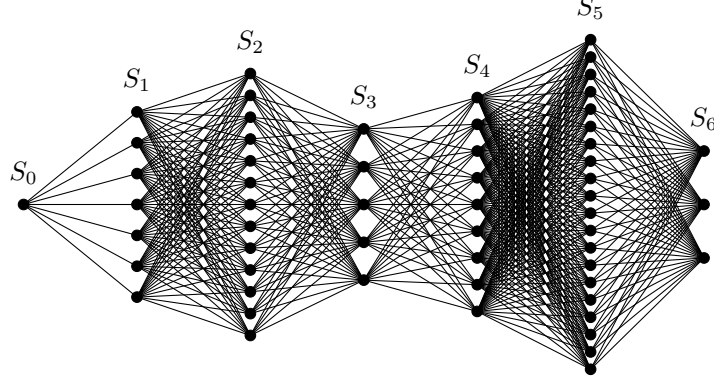
with the convention that $S_{-1} = \emptyset$. Note that $\deg = \deg_+ + \deg_- + \deg_0$ is independent of the choice of a 1-dimensional decomposition.

We now give a criterion of essential self-adjointness.

Theorem 5.11. Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a weighted graph and $(S_n)_{n \geq 0}$ be a 1-dimensional decomposition. Assume that

$$\sum_{n=1}^{\infty} \frac{1}{\sqrt{a_n^+ + a_{n+1}^-}} = \infty,$$

where $a_n^{\pm} := \sup_{x \in S_n^{\pm}} \deg_{\pm}(x)$. Then \mathcal{G} is χ -complete and in particular, Δ_1 is essentially self-adjoint on $C_{\text{anti}}^c(\mathcal{E})$.

FIGURE 1. An antitree with spheres S_0, \dots, S_6 of sizes 1, 7, 13, 5, 9, 20, 3.

Proof. It is enough to check the hypothesis of Theorem 5.5. We set

$$\chi_n(x) := \begin{cases} 1, & \text{if } |x| \leq n, \\ \max \left(0, 1 - \sum_{k=n}^{|x|-1} \frac{1}{\sqrt{a_k^+ + a_{k+1}^-}} \right), & \text{if } |x| > n. \end{cases}$$

Since the series diverges, χ_n is with compact support. Note that χ_n is constant on S_n . If $x \in S_m$ with $m > n$, we have :

$$\begin{aligned} \frac{1}{m(x)} \sum_{y \in S_{m+1}} \mathcal{E}(x, y) |\chi_n(x) - \chi_n(y)|^2 &\leq \deg_+(x) \frac{1}{a_m^+ + a_{m+1}^-}. \\ \frac{1}{m(x)} \sum_{y \in S_m} \mathcal{E}(x, y) |\chi_n(x) - \chi_n(y)|^2 &= 0 \\ \frac{1}{m(x)} \sum_{y \in S_{m-1}} \mathcal{E}(x, y) |\chi_n(x) - \chi_n(y)|^2 &\leq \deg_-(x) \frac{1}{a_{m-1}^+ + a_m^-}. \end{aligned}$$

It satisfies the definition of χ -completeness. \square

5.2.3. Application to the class of antitrees. We focus on antitrees, see also [Wo2] and [BK]. The *sphere* of radius $n \in \mathbb{N}$ around a vertex $v \in \mathcal{V}$ is the set $S_n(v) := \{w \in \mathcal{V}, \rho_{\mathcal{G}}(v, w) = n\}$. A graph is an *antitree*, if there exists a vertex $v \in \mathcal{V}$ such that for all other vertices $w \in \mathcal{V} \setminus \{v\}$

$$\mathcal{N}_{\mathcal{G}}(w) = S_{n-1}(v) \cup S_{n+1}(v),$$

where $n = \rho_{\mathcal{G}}(v, w) \geq 1$. See Figure 1 for an example. The distinguished vertex v is the *root* of the antitree. Antitrees are bipartite and enjoy radial symmetry.

Proposition 5.12. *Let $\mathcal{G} : (\mathcal{E}, \mathcal{V})$ be a simple antitree whose root is v . Set $s_n := \#S_n(v)$. Assume that*

$$\sum_{n \in \mathbb{N}} \frac{1}{\sqrt{s_n + s_{n+1}}} = \infty$$

then \mathcal{G} is χ -complete and in particular, Δ_1 is essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$.

Proof. Use Theorem 5.11 with $S_n := S_n(v)$. \square

5.3. Other approaches. We present some techniques that ensure essential self-adjointness.

Theorem 5.13. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a locally finite graph. Set*

$$\mathcal{M}(x, y) := 1 + \sum_{z \in \mathcal{V}} \left(\frac{1}{m(x)} \mathcal{E}(x, z) + \frac{1}{m(y)} \mathcal{E}(z, y) \right).$$

Suppose that

$$\sup_{x, y \in \mathcal{V}} \sum_{z \in \mathcal{V}} \frac{1}{m(x)} \mathcal{E}(x, z) |\mathcal{M}(x, y) - \mathcal{M}(x, z)|^2 < \infty.$$

Then Δ_1 is essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$.

Proof. Take $f \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$. We have

$$\begin{aligned} \|\Delta_1 f\|^2 &\leq \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \left(\frac{1}{m^2(x)} \left| \sum_{z \in \mathcal{V}} \mathcal{E}(x, z) f(x, z) \right|^2 \right. \\ &\quad \left. + \frac{1}{m^2(y)} \left| \sum_{z \in \mathcal{V}} \mathcal{E}(z, y) f(z, y) \right|^2 \right) \\ &= 2 \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \frac{1}{m^2(x)} \left| \sum_{z \in \mathcal{V}} \mathcal{E}(x, z) f(x, z) \right|^2 \\ &\leq 2 \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \frac{1}{m^2(x)} \left(\sum_{t \in \mathcal{V}} \mathcal{E}(x, t) \right) \left(\sum_{z \in \mathcal{V}} \mathcal{E}(x, z) |f(x, z)|^2 \right) \\ &= 2 \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \left| \frac{1}{m(x)} \left(\sum_{z \in \mathcal{V}} \mathcal{E}(x, z) \right) f(x, y) \right|^2 \leq 2 \|\mathcal{M}(\cdot, \cdot) f\|^2. \end{aligned}$$

Moreover, noting that $Mc(x, y) = Mc(y, x)$ and that $f(x, y) = -f(y, x)$ we get:

$$\begin{aligned} 2|\langle f, [\Delta_1, \mathcal{M}(\cdot, \cdot)] f \rangle| &\leq \|f\|^2 + \\ &\quad \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \left(\sum_{z \in \mathcal{V}} \frac{1}{m(x)} \mathcal{E}(x, z) |\mathcal{M}(x, z) - \mathcal{M}(x, y)| |f(x, z)| \right)^2 \\ &\leq \|\mathcal{M}(\cdot, \cdot)^{\frac{1}{2}} f\|^2 + \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \frac{1}{m(x)} \left(\sum_{t \in \mathcal{V}} \mathcal{E}(x, t) \right) \times \\ &\quad \left(\sum_{z \in \mathcal{V}} \mathcal{E}(x, z) \frac{1}{m(x)} |\mathcal{M}(x, z) - \mathcal{M}(x, y)|^2 |f(x, z)|^2 \right) \\ &= \|\mathcal{M}(\cdot, \cdot)^{\frac{1}{2}} f\|^2 + \sum_{(x, y) \in \mathcal{V}^2} \mathcal{E}(x, y) \sum_{t \in \mathcal{V}} \frac{1}{m(x)} \mathcal{E}(x, t) \\ &\quad \underbrace{\sum_{z \in \mathcal{V}} \mathcal{E}(x, z) \frac{1}{m(x)} |\mathcal{M}(x, y) - \mathcal{M}(x, z)|^2 |f(x, z)|^2}_{\leq C} \\ &\leq (1 + 2C) \|\mathcal{M}(\cdot, \cdot)^{\frac{1}{2}} f\|^2. \end{aligned}$$

Applying [ReSi, Theorem X.37], the result follows. \square

Example 5.14. Take $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ to be a simple radial tree such that

$$\sup_{n \in \mathbb{N}} |\text{off}(n) - \text{off}(n+2)| < \infty,$$

then Δ_1 is essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$.

This example can be reached by Theorem 5.5, however for weighted graphs the hypotheses do not seem to fully overlap from one side or from the other.

We now give a more powerful way to check that Δ_1 is essentially self-adjoint. It seems that this approach is new in the setting of graphs.

Theorem 5.15. Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a weighted graph. Fix $x_0 \in \mathcal{V}$ and set $B_n := \{x \in \mathcal{V}, \rho_{\mathcal{G}}(x_0, x) \leq n\}$. If

$$(9) \quad \sum_{n=1}^{\infty} \left(\prod_{i \leq n} \sup_{x \in B_i} (\deg_{\mathcal{G}}(x)) \right)^{-1/2n} = \infty$$

then Δ_1 is essentially self-adjoint on $\mathcal{C}_{\text{anti}}^c(\mathcal{E})$.

Proof. Since Δ_1 is non-negative, by [MaMc] or [Nu], it is enough to prove that for all $f \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$:

$$\sum_{n=0}^{\infty} \|\Delta_1^n f\|^{-1/2n} = \infty.$$

Set $f \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$. There is n_0 such that $\text{supp } f \subset B_{n_0}^2$, where $B_{n_0}^2 := B_{n_0} \times B_{n_0}$. Note that $\text{supp } (\Delta_1)^n f \subset B_{n_0+n}^2$. Therefore

$$\begin{aligned} \|(\Delta_1)^{n+1} f\| &\leq \|1_{B_{n_0+n+1}^2} \Delta_1 1_{B_{n_0+n+1}^2}\| \cdot \|(\Delta_1)^n f\| \\ &\leq \sup_{x \in B_{n_0+n+1}} \deg_{\mathcal{G}}(x) \cdot \|(\Delta_1)^n f\| \end{aligned}$$

since, for all $g \in \mathcal{C}_{\text{anti}}^c(\mathcal{E})$ and $k \in \mathbb{N}$, we have:

$$\begin{aligned} 0 &\leq \langle 1_{B_k^2} g, \Delta_1 1_{B_k^2} g \rangle = \sum_x \frac{1}{m(x)} \left| \sum_y \mathcal{E}(x, y) 1_{B_k^2}(x, y) g(x, y) \right|^2 \\ &\leq \sum_x \frac{1}{m(x)} \left(\sum_y \mathcal{E}(x, y) \right) \sum_z \mathcal{E}(x, z) |1_{B_k^2}(x, z) g(x, z)|^2 \\ &\leq \sup_{x \in B_k} \deg(x) \cdot \|1_{B_k^2} g\|^2. \end{aligned}$$

This concludes the proof. \square

Remark 5.16. The example of Proposition 5.7 is also covered by Theorem 5.15.

Remark 5.17. A computation shows that the condition (9) is equivalent to

$$\sum_{n=1}^{\infty} \frac{1}{\sqrt{\sup_{x \in B_n} (\deg_{\mathcal{G}}(x))}} = \infty,$$

when $\sup_{x \in B_n} (\deg_{\mathcal{G}}(x))$ is equivalent to $n^\alpha \ln^\beta(n)$, as n goes to infinity.

5.4. The case of the Adjacency matrix. We take the opportunity to apply this technique for the adjacency matrix. This improves the results obtained in [GoSc].

Theorem 5.18. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V}, m)$ be a weighted graph. Fix $x_0 \in \mathcal{V}$ and set $B_n := \{x \in \mathcal{V}, \rho_{\mathcal{G}}(x_0, x) \leq n\}$. If*

$$(10) \quad \sum_{n=1}^{\infty} \left(\prod_{i \leq n} \sup_{x \in B_i} (\deg_{\mathcal{G}}(x)) \right)^{-1/n} = \infty$$

then $\mathcal{A}_{\mathcal{G}}$ is essentially self-adjoint on $\mathcal{C}^c(\mathcal{V})$.

Proof. Since $\mathcal{A}_{\mathcal{G}}$ is not necessary non-negative, by [MaMc] or [Nu], it is enough to prove that for all $f \in \mathcal{C}^c(\mathcal{V})$

$$\sum_{n=0}^{\infty} \|\mathcal{A}_{\mathcal{G}}^n f\|^{-1/n} = \infty.$$

Set $f \in \mathcal{C}^c(\mathcal{V})$. There is n_0 such that $\text{supp } f \subset B_{n_0}$. Note that $\text{supp } \mathcal{A}_{\mathcal{G}}^n f \subset B_{n_0+n}$. Therefore

$$\begin{aligned} \|\mathcal{A}_{\mathcal{G}}^{n+1} f\| &\leq \|1_{B_{n_0+n+1}} \mathcal{A}_{\mathcal{G}} 1_{B_{n_0+n+1}}\| \cdot \|\mathcal{A}_{\mathcal{G}}^n f\| \\ &\leq \sup_{x \in B_{n_0+n+1}} \deg_{\mathcal{G}}(x) \cdot \|\mathcal{A}_{\mathcal{G}}^n f\| \end{aligned}$$

since, for all $g \in \mathcal{C}^c(\mathcal{V})$, we have $|\langle g, \mathcal{A}_{\mathcal{G}} g \rangle| \leq \langle g, \deg_{\mathcal{G}}(\cdot) g \rangle$. \square

Corollary 5.19. *Let $\mathcal{G} = (\mathcal{E}, \mathcal{V})$ be a radial simple tree, endowed with an origin such that $\text{off}(n) := \text{off}(x)$ for all $x \in \mathcal{S}_n$. Assume that*

$$\sum_{n=1}^{\infty} \frac{1}{\text{off}(n)} = \infty.$$

Then $\mathcal{A}_{\mathcal{G}}$ is essentially self-adjoint.

Remark 5.20. *Note that the condition (10) is not optimal for the question of self-adjointness in the case of a radial simple tree, see [GoSc]/[Proposition 1.2] but is optimal in the case of anti-trees, see [GoSc2].*

To finish denote by $\tilde{\mathcal{G}}$ the line graph of a bipartite graph \mathcal{G} . Then, thanks to Proposition 3.1, all the criteria of Sections 5.2 and 5.3 implies that $\mathcal{A}_{\tilde{\mathcal{G}}}$ is essentially self-adjoint on $\mathcal{C}^c(\tilde{\mathcal{V}})$.

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