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# Microlocal analysis of the generalized Radon transform over the level curves of CES-functions 

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#### Abstract

We show that the generalized Radon transform over the level curves of CES-functions in the positive quadrant is an integral Fourier operator satisfying the condition of microlocal regularity. We describe a method for reconstruction of singularities of a function from the singularities of its generalized Radon transform.


Keywords: generalized Radon transform, microlocal analysis, integral Fourier operator

## 1 Introduction

We consider the generalized Radon transform $R_{\alpha}, \alpha \in \mathbb{R} \backslash 0$, on the positive quadrant $X=\left\{\left(x_{1}, x_{2}\right): x_{1}>0, x_{2}>0\right\}$ which maps a sufficiently regular realvalued function $u$ on $X$ to the function $R_{\alpha} u$ on $P=\left\{\left(p_{1}, p_{2}\right): p_{1}>0, p_{2}>0\right\}$ defined as follows:

$$
\begin{equation*}
R_{\alpha} u(p)=\int_{X_{\alpha, p}} u(x) \omega_{\alpha, p} \tag{1.1}
\end{equation*}
$$

where $p=\left(p_{1}, p_{2}\right)$,

$$
\begin{gather*}
X_{\alpha, p}=\left\{\left(x_{1}, x_{2}\right) \in X: q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1\right\}  \tag{1.2}\\
q_{\alpha}\left(x_{1}, x_{2}\right)=\left(x_{1}^{\alpha}+x_{2}^{\alpha}\right)^{1 / \alpha}, \quad x_{1}, x_{2}>0 \tag{1.3}
\end{gather*}
$$

$\omega_{\alpha, x}$ is the Gelfand-Leray 1-form given by the interior product:

$$
\begin{equation*}
\left.\omega_{\alpha, p}=d_{x} q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)\right\lrcorner\left(d x_{1} \wedge d x_{2}\right) \tag{1.4}
\end{equation*}
$$

and orientation on $X_{\alpha, p}$ is given by the volume form $\left|\nabla_{x} q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)\right| \omega_{\alpha, p}$.
Recall that by definition $\omega_{\alpha, p}$ is the restriction to $X_{\alpha, p}$ of any 1-form $\widetilde{\omega}_{\alpha, p}$ on $X$ satisfying

$$
d_{x} q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right) \wedge \widetilde{\omega}_{\alpha, p}=d x_{1} \wedge d x_{2}
$$

The form $\omega_{\alpha, p}$ doesn't depend on the choice of $\widetilde{\omega}_{\alpha, p}$.
Transform 1.1 with $\alpha \leq 1$ is closely related to the profit function in the generalized model of pure industry which takes into account the substitution of production factors at the micro-level, see, e.g., Refs. [Sha1], [Sha2].

[^0]In this setting $q_{\alpha}$ is the unit cost function, $(1-\alpha)$ is the elasticity of substitution of production factors at the micro-level and $u$ has the meaning of density of distribution of production powers over technologies. In this context function $q_{\alpha}$ is called the constant elasticity of substitution function (CES-function).

The case $\alpha=1$ corresponds to production systems with no substitution of production factors at the microlevel. This assumption is not fulfilled in the majority of production systems experiencing the effects of standartization and globalization. In this case transform (1.1) is the classical Radon transform in $\mathbb{R}^{2}$ with limited data: only those straight lines that intersect both coordinate axes in the first (nonnegative) quadrant are considered. The properties of this transform were studied in [HS].

Passing $\alpha \rightarrow 0$ in (1.1) we obtain the transform $R_{0}$ that integrates function $u$ over the sets $x_{1} x_{2}=$ const. This case corresponds to production systems with the Cobb-Douglas production functions. Note that transform $R_{0}$ maps a function of two variables to a function of one variable (after an appropriate change of variables). We exclude this case from consideration.

We are mainly interested in the following problems for transform $R_{\alpha}$.
Problem 1 (Uniqueness). Find sufficient conditions for injectivity of transform $R_{\alpha}$ on a suitable space. Find examples of non-injectivity of transform $R_{\alpha}$.

Problem 2 (Characterization). Decribe the range of transform $R_{\alpha}$ on a suitable space.

Problem 3 (Inversion). Find a stable algorithm (or formula) for inversion of $R_{\alpha}$ on a suitable space. Obtain the stability estimates.

Problem 4 (Microlocal properties). Describe the propagation of singularities by transform $R_{\alpha}$.

By «suitable spaces» we understand the spaces which naturally arise in the above setting of the generalized model of pure industry, for example, the space of non-negative compactly supported continuous functions or more general spaces.

Transform $R_{\alpha}$ was introduced in Ref. [HS] in the case when $\alpha=1$. It was studied for the first time under the assumption that $\alpha>0$ in Ref. [Ag1]. In Ref. [Ag2] the more general transform was considered, where integration in 1.1) is over the level hypersurfaces of an arbitrary positively homogeneous function in positive orthant satisfying some regularity assumptions.

Problem 1 was considered in Ref. [Ag2]. In this work it was shown that transform $R_{\alpha}$ is injective on the subspace of non-negative functions (and even measures) growing not faster than exponents at infinity. Besides, it was shown that the ranges of transforms $R_{\alpha}$ and $R_{\beta}$ for $\alpha>0, \beta>0, \alpha \neq \beta$, on a subspace of functions (and even measures) with sufficient decay at infinity intersect only by zero function.

Problem 2 was studied in Ref. [Ag1]. In a subsequent work we will present results on Problem 2 in the case of more general integral transform over the level hypersurfaces of an arbitrary sufficiently regular positively homogeneous function.

Problem 3 was addressed in Ref. [Ag1] in the case of transform $R_{\alpha}$ and in Ref. [Ag2] in the case of more general integral transform.

Besides, Problems 1, 2, 3 for transform $R_{\alpha}$ were studied in Ref. [HS] in the case when $\alpha=1$.

In the present paper we study Problem 4. More precisely, we show that $R_{\alpha}$, $\alpha \in \mathbb{R} \backslash\{0,1\}$, is a Fourier integral operator satisfying the property of microlocal regularity and we propose a method for reconstruction of singularities, see Theorem 2.1 and Proposition 2.1 of Section 2.

We don't consider the case $\alpha=1$ for the following reason. On the one hand, our method of proof of microlocal regularity is based on a version of method of stationary phase presented in Section 4 which uses the fact that the linear function $S(x, \xi)=\xi_{1} x_{1}+\xi_{2} x_{2}$ at fixed $\xi_{1}, \xi_{2}$ with $\xi_{1} \xi_{2}>0$ attains the unique extremum $x^{*}(p, \xi)$ on $X_{\alpha, p}$ for any $p \in P$ when $\alpha \in \mathbb{R} \backslash\{0,1\}$ and this is not true when $\alpha=1$. On the other hand, restrictions in space prevent us from studying the microlocal properties of $R_{1}$ as an exceptional case in the present paper. Finally, our study of transform $R_{\alpha}$ is mainly motivated by the study of production systems with substitution of production factors at the microlevel and this case corresponds to $\alpha \neq 1$.

It is important to note that in many applications related with generalized Radon transforms we are interested in anomalies in distribution of a quantity described by function $u$ rather than in exact values of $u$. In this case the property of microlocal regularity allows us to estimate these anomalies via the singularities of $R_{\alpha} u$ without constructing the inverse operator $R_{\alpha}^{-1}$.

Besides, the knowledge of microlocal properties of operator $R_{\alpha}$ is very important if we are interested in reconstruction problem for this operator from incomplete data (or in presence of noise). In particular, even if the reconstruction is possible it may be not convenient for numerical computations if the generalized Radon transform has bad microlocal properties.

On the other hand, even if the generalized Radon transform is not injective, it is sometimes possible to construct a convenient pseudo-inverse operator if the generalized Radon transform has good microlocal properties. For related discussion, see, e.g., Ref. [Fa].

In addition, the property of microlocal regularity (in the case of analytic singularities) was used by some authors to estimate the support of function $u$ given the support of its generalized Radon transform, see, e.g., Refs. [BQ1], [BQ2], [Bo], [Qu2], [Qu3], [Kr].

Note that the history of microlocal approach to generalized Radon transforms goes back to Refs. [Gu], [GS].

Concerning the results given in literature on microlocal properties of generalized Radon transforms, see, e.g., Refs. [ABKQ], [Bo], [BQ1], [BQ2], [FLU], [FQ], [GU], [KLQ], [Qu2], [Qu3], [SU] and references therein.

## 2 Main results

To formulate main results we need to introduce some notations. For fixed $\alpha \in$ $\mathbb{R} \backslash 0, x \in X$ we define

$$
P_{\alpha, x}=\left\{\left(p_{1}, p_{2}\right) \in P: q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1\right\},
$$

with orientation given by the volume form $\left|\nabla_{p} q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)\right| \omega_{\alpha, x}$, where $\omega_{\alpha, x}=$ $\left.d_{p} q\left(p_{1} x_{1}, p_{2} x_{2}\right)\right\lrcorner\left(d p_{1} \wedge d p_{2}\right)$.

The dual transform $R_{\alpha}^{*}$ to $R_{\alpha}$ maps a sufficiently regular real-valued function $v$ on $P$ to the function $R_{\alpha}^{*} v$ on $X$ given by the formula

$$
\begin{equation*}
R_{\alpha}^{*} v(x)=\int_{P_{\alpha, x}} v(p) \omega_{\alpha, x} . \tag{2.1}
\end{equation*}
$$

Note that since $P \cong X$, in fact, transform $R_{\alpha}$ is self-dual.
Let $Z_{\alpha}$ be the following incidence relation between the points in $X$ and $P$ :

$$
Z_{\alpha} \xlongequal{\text { def }}\left\{\left(p_{1}, p_{2} ; x_{1}, x_{2}\right) \in P \times X: q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1\right\} .
$$

We consider $Z_{\alpha}$ as a submanifold of $P \times X$.
The total space of conormal bundle $N^{*} Z_{\alpha}$ of $Z_{\alpha}$ in $P \times X$ is given by the following formula:

$$
\begin{gather*}
N^{*} Z_{\alpha}=\left\{\left(p_{1}, p_{2} ; \lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j} ; x_{1}, x_{2} ; \lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j}\right) \in\right.  \tag{2.2}\\
\left.\quad \in T^{*} P \times T^{*} X \cong T^{*}(P \times X): q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1, \lambda \in \mathbb{R}\right\}
\end{gather*}
$$

We denote by $\dot{N}^{*} Z_{\alpha}$ the manifold $N^{*} Z_{\alpha}$ with zero section removed.
In a similar way, the total space of conormal bundle $N^{*} X_{\alpha, p}$ of $X_{\alpha, p}$ in $X$ is given by formula

$$
\begin{gather*}
N^{*} X_{\alpha, p}=\left\{\left(x_{1}, x_{2} ; \lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j}\right):\right.  \tag{2.3}\\
\left.\left(x_{1}, x_{2}\right) \in X, q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1, \lambda \in \mathbb{R}\right\}, \quad p \in P
\end{gather*}
$$

We define the canonical relation $C_{\alpha}$ to be the total space of the twisted conormal bundle of $Z_{\alpha}$ in $P \times X$ with zero section removed:

$$
\begin{gather*}
C_{\alpha} \xlongequal{\text { def }}\left(\dot{N}^{*} Z_{\alpha}\right)^{\prime}=\left\{(p, \eta d p ; x,-\xi d x) \in T^{*} P \times T^{*} X:\right.  \tag{2.4}\\
\left.(p, \eta d p, x, \xi d x) \in \dot{N}^{*} Z_{\alpha}\right\}
\end{gather*}
$$

where

$$
\begin{gathered}
p=\left(p_{1}, p_{2}\right), \eta=\left(\eta_{1}, \eta_{2}\right), x=\left(x_{1}, x_{2}\right), \xi=\left(\xi_{1}, \xi_{2}\right) \\
\eta d p=\eta_{1} d p_{1}+\eta_{2} d p_{2}, \quad \xi d x=\xi_{1} d x_{1}+\xi_{2} d x_{2}
\end{gathered}
$$

Theorem 2.1. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ be fixed. Then:

1. $R_{\alpha}$ is a Fourier integral operator associated with canonical relation $C_{\alpha}$. Hence $R_{\alpha}$ is the linear continuous operator from $C_{c}^{\infty}(X)$ to $C^{\infty}(P)$ and from $\mathscr{E}^{\prime}(X)$ to $\mathscr{D}^{\prime}(P)$, where $\mathscr{E}^{\prime}(X)$ denotes the space of compactly supported distributions from $\mathscr{D}^{\prime}(X)$;
2. (microlocal regularity) for any fixed $u \in \mathscr{E}^{\prime}(X)$ the condition $p \notin \operatorname{sing} \operatorname{supp} R_{\alpha} u$ is satisfied if and only if

$$
\begin{equation*}
W F(u) \cap N^{*} X_{\alpha, p}=\varnothing, \tag{2.5}
\end{equation*}
$$

where $W F$ denotes the wave front set and $N^{*} X_{\alpha, p}$ is defined in (2.3);
3. for any $u \in \mathscr{E}^{\prime}(X)$ if $(x, \xi d x) \in W F\left(R_{\alpha} u\right), \xi=\left(\xi_{1}, \xi_{2}\right)$, then $\xi_{1} \xi_{2}>0$.

Statement 2 of Theorem 2.1 tells us that if distribution $u \in \mathscr{E}^{\prime}(X)$ has a singularity at point $x \in X_{\alpha, p}$ which is conormal to curve $X_{\alpha, p}$, then distribution $R_{\alpha} u$ has a singularity at point $p$. Furthermore, all singularities of $R_{\alpha} u$ arise in this way.

Note that since the dual transform $R_{\alpha}^{*}$ defined in (2.1) is given by the same formula as transform $R_{\alpha}$ (after changing $x$ to $p$ and vice versa), Theorem 2.1 also holds for $R_{\alpha}^{*}$ if we replace $X$ by $P, X_{\alpha, p}$ by $P_{\alpha, x}$ and vice versa in its statement.

Theorem 2.1 is proved in Section 3. The proof of the "only if" part of statement 2 of Theorem 2.1 is based on Lemma 3.1 of Section 3 which is proved in Section 5.

In order to formulate the following result we need to introduce two notations.
For fixed $0<\delta<\frac{1}{2}$ chose any $\chi_{\delta} \in C^{\infty}(0,+\infty)$ such that

$$
\chi_{\delta}(t)= \begin{cases}0, & \text { if } t<\delta \text { or } t>\delta^{-1}  \tag{2.6}\\ 1, & \text { if } t \geq 2 \delta \text { and } t \leq \frac{1}{2} \delta^{-1}\end{cases}
$$

For fixed $\alpha \in \mathbb{R} \backslash\{0,1\}$ define $\gamma(\alpha)$ by formula

$$
\gamma(\alpha)= \begin{cases}1+\alpha^{-1}, & \alpha>1  \tag{2.7}\\ -1+3 \alpha^{-1}, & 0<\alpha<1 \\ 1-3 \alpha^{-1}, & \alpha<0\end{cases}
$$

Proposition 2.1 (reconstruction of singularities). Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<$ $\varepsilon<\frac{1}{2}$ be fixed. Define $\gamma(\alpha)$ by formula (2.7) and put $\delta=2^{-\frac{1}{\alpha}-1} \varepsilon^{\gamma(\alpha)}$. Then for any $u \in \mathscr{E}^{\prime}(X)$ such that

$$
\begin{equation*}
\operatorname{supp} u \subseteq\left\{\left(x_{1}, x_{2}\right) \in X: \varepsilon<x_{j}<\varepsilon^{-1}, j=1,2\right\} \tag{2.8}
\end{equation*}
$$

and for all $(x, \xi d x) \in T^{*} X, x=\left(x_{1}, x_{2}\right), \xi=\left(\xi_{1}, \xi_{2}\right)$, satisfying $\varepsilon<x_{j}<\varepsilon^{-1}$, $j=1,2, \varepsilon<\frac{\xi_{1}}{\xi_{2}}<\varepsilon^{-1}$, the following formula holds:

$$
\begin{equation*}
(x, \xi d x) \in W F(u) \text { if and only if }(x, \xi d x) \in W F\left(R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u\right) \tag{2.9}
\end{equation*}
$$

where $\chi_{\delta}^{j}$ denotes the operator of multiplication by $\chi_{\delta}\left(p_{j}\right), j=1,2$, and $\chi_{\delta}$ is defined in formula (2.6).

Proposition 2.1 is proved in Section 3. The proof is based on Lemma 3.1 of Section 3

Proposition 2.1 allows us to reconstruct singularities of $u$ given $R_{\alpha}^{*} u$ and $a$ priori information about bounds on support of $u$, by choosing an appropriate $\delta$ and applying operator $R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2}$ to $R_{\alpha} u$. For example, consider a function $u^{\mathrm{v}}$ on $X$ as in Fig. 1(a). Proposition 2.1 tells us that function $R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u^{\mathrm{v}}$, where $\alpha=0.5, \delta=0.01$, will have the singularities at same points and directions as function $u^{\mathrm{v}}$ (not taking corners in Fig. 1 (a) into account). Since $\Delta=\frac{\partial}{\partial x_{1}}+\frac{\partial}{\partial x_{2}}$ is elliptic on $X$ the function $\Delta R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u^{\mathrm{v}}$ will also have the same singularities as $u^{\mathrm{v}}$, see Fig. 1(b) (we apply $\Delta$ in order to make singularities more sharp).

It is important to note that it isn't possible in principle to reconstruct singularities of $u$ of type $(x, \xi d x), x \in X, \xi=\left(\xi_{1}, \xi_{2}\right)$ with $\xi_{1} \xi_{2} \leq 0$ since the wave front set of distribution of type $R_{\alpha}^{*} v, v \in \mathscr{E}^{\prime}(P)$, can't contain such points as follows from statement 3 of Theorem 2.1. Consider, for example, function $u^{\mathrm{i}}$ as in Fig. 1 (c). Function $\Delta R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u^{\mathrm{i}}$, where $\alpha=0.5, \delta=0.01$, in this case will have singularities only at corners in Fig. 1 (c), see Fig. 1 (d).

Remark 2.1. Note that replacing function $q_{\alpha}$ in formula (1.3) by the function of the same form but with $n \geq 3$ arguments, we could consider the generalized Radon transform over the level hypersurfaces of CES-function in dimension $n$.

The generalization of Theorem 2.1 and Proposition 2.1 to this case is straightforward. We consider the two-dimensional case in order to simplify the proofs.

Remark 2.2. In fact, statements 1,3 and the "if" part of statement 2 of Theorem 2.1 remain valid if we replace function $q_{\alpha}$ in definition (1.1) by much more general smooth function $q$. In particular, we could consider functions $q \in C^{\infty}(X)$ satisfying the following conditions:

Q1. $q(\lambda x)=\lambda q(x), x \in X, \lambda>0$,
Q2. $q(x), \partial_{1} q(x), \partial_{2} q(x)$ are positive for $x \in X$, where $\partial_{j} q=\partial q / \partial x_{j}, j=1,2$;
Q3. for any fixed $p \in P$ the map $\Phi_{q, p}: X_{q, p} \rightarrow(0,+\infty)$ defined by

$$
\begin{gather*}
\Phi_{q, p}(x)=\frac{x_{1} \partial_{1} q\left(p_{1} x_{1}, p_{2} x_{2}\right)}{x_{2} \partial_{2} q\left(p_{1} x_{1}, p_{2} x_{2}\right)} \\
X_{q, p}=\left\{\left(x_{1}, x_{2}\right) \in X: q\left(p_{1} x_{1}, p_{2} x_{2}\right)=1\right\} \tag{2.10}
\end{gather*}
$$

is bijective.
These conditions are satisfied, in particular, by functions $q_{\alpha}, \alpha \in \mathbb{R} \backslash 0$.
In the above interpretation of transform (1.1) in the setting of the generalized model of pure industry functions $q_{\alpha}, \alpha \leq 1$, correspond to unit cost functions for production systems with constant coefficient of elasticity of substitution of production factors whereas concave functions $q$ different from $q_{\alpha}, \alpha \leq 1$, and satisfying assumptions Q1, Q2 correspond to production systems with variable coefficient of elasticity of substitution.


Figure 1: (a) original function $u^{\mathrm{v}}$ equal to 1 in black domain and to 0 in white domain; (b) function $\Delta R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u^{\mathrm{v}}$, where $\alpha=0.5, \delta=0.01$; (c) original function $u^{\mathrm{i}}$ equal to 1 in black domain and to 0 in white domain; (d) function $\Delta R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u^{\mathrm{i}}$, where $\alpha=0.5, \delta=0.01$.

Let us sketch the proof of statements 1,2 ("if" part) and 3 of Theorem 2.1 in the case of smooth functions $q$ satisfying Q1, Q2, Q3, see also the proof of Theorem 2.1.

Denote by $R_{q}$ the generalized Radon transform defined by formula 1.1) using function $q$ instead of $q_{\alpha}$. Denote by $C_{q}$ the corresponding canonical relation.

The proof of statement 1 of Theorem 2.1 for this class of functions $q$ remains the same as for functions $q_{\alpha}$, see Section 3.

It follows from Q2 that for any set $M \subseteq T^{*} X$, if $(p, \eta d p) \in C_{q} \circ M, \eta=$ $\left(\eta_{1}, \eta_{2}\right)$, then $\eta_{1} \eta_{2}>0$, where

$$
\begin{equation*}
C_{q} \circ M \xlongequal{\text { def }}\left\{(p, \eta d p) \in T^{*} P: \exists(x, \xi d x) \in M:(p, \eta d p ; x, \xi d x) \in C_{q}\right\} \tag{2.11}
\end{equation*}
$$

This implies statement 3 of Theorem 2.1 if we take into account the inclusion $W F\left(R_{q} u\right) \subseteq C_{q} \circ W F(u), u \in \mathscr{E}^{\prime}(X)$.

It follows from assumptions Q1, Q2, Q3 that the canonical projection from $C_{q}$ to $T^{*} X$ is injective and that the following inclusion holds:

$$
\begin{equation*}
C_{q} \circ W F(u) \cap T_{p}^{*} P \subseteq C_{q} \circ \dot{N}^{*} X_{q, p} \tag{2.12}
\end{equation*}
$$

Using 2.12 we can obtain the "if" part of statement 2 of Theorem 2.1.
The "only if" part of statement 2 of Theorem 2.1 is the most difficult to prove. To generalize it to the case of smooth functions $q$ satisfying Q1, Q2, Q3 we need to obtain an analogue of Lemma 3.1 below. Restrictions in space and time prevent us from obtaining this analogue in the present paper. Nevertheless, we prove the main part of Lemma 3.1 (see also Lemma 4.1) for the general case of smooth functions $q$ satisfying Q1, Q2 to be able to use it in a subsequent paper.

Remark 2.3. It follows from definitions (1.1), 2.1) that:

1. even if $u$ is compactly supported in $X, v=R_{\alpha} u$ doesn't have compact support in general;
2. if $v$ is not compactly supported in $P$, the value of $R_{\alpha}^{*} v$ is not always defined.

Hence $R_{\alpha}^{*} R_{\alpha} u$ is not always defined for $u \in C_{c}^{\infty}(X)$.
In the Gelfand's approach to generalized Radon transforms via double fibrations (see, e.g., Ref. [GGS]) this corresponds to the fact that the canonical projection from $Z_{\alpha}$ to $X$ is not a proper map. Furthermore, this problem can't be resolved even by considering transform $R_{\alpha}$ on functions which have supports in some fixed compact subset of $X$.

Therefore, we are not able to deduce the "only if" part of statement 2 of Theorem 2.1 from the microlocal regularity properties of operator $R_{\alpha}^{*} R_{\alpha}$ as it can be done when the canonical projection from the incidence relation to the source space is a proper map and the double fibration corresponding to the generalized Radon transform satisfies the so-called Bolker assumption, see, e.g., Refs. [Gu], [GS], [Qu1] for more details.

## 3 Proof of Theorem 2.1 and Proposition 2.1

### 3.1 Approximation of $R_{\alpha}$ by proper Fourier integral operators

In this subsection we show that $R_{\alpha}$ is the Fourier integral operator associated with $C_{\alpha}$ and we formulate an auxilary lemma, which is crucial in the proof of the "only if" part of statement 2 of Theorem 2.1.

Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ be fixed. For any $u \in C_{c}^{\infty}(X)$ the following chain of equalities holds:

$$
\begin{gather*}
R_{\alpha} u(p)=\int_{X_{\alpha, p}} u(x) \omega_{\alpha, p}=\int_{\mathbb{R}} \delta(s-1) \int_{q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=s} u(x) \omega_{\alpha, p} d s \\
=\frac{1}{2 \pi} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{i \theta(s-1)} \int_{q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=s} u(x) \omega_{\alpha, p} d \theta d s  \tag{3.1}\\
=\frac{1}{2 \pi} \int_{\mathbb{R}} \int_{X} e^{i \phi_{\alpha}(p, x, \theta)} u(x) d x d \theta,
\end{gather*}
$$

where $p \in P$ and $\phi_{\alpha}(p, x, \theta)$ is the real phase function:

$$
\begin{equation*}
\phi_{\alpha}(p, x, \theta)=\theta\left(q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)-1\right), \quad p \in P, x \in X, \theta \in \mathbb{R} \backslash 0 \tag{3.2}
\end{equation*}
$$

It follows from (3.1), (3.2) that $R_{\alpha}$ is a Fourier integral operator associated with $C_{\alpha}$. Hence $R_{\alpha}$ is a linear continuous operator from $C_{c}^{\infty}(X)$ to $C^{\infty}(P)$ and from $\mathscr{E}^{\prime}(X)$ to $\mathscr{D}^{\prime}(P)$. Statement 1 of Theorem 2.1 is proved.

Formula (3.1) implies that $R_{\alpha}$ is not a proper operator. We are going to approximate $\overline{R_{\alpha}}$ by proper Fourier integral operators.

Let $0<\delta<\frac{1}{2}$ be fixed. Chose $\chi_{\delta} \in C^{\infty}(0,+\infty)$ as in 2.6) and $\tilde{\chi}_{\delta} \in C^{\infty}(\mathbb{R})$ such that

$$
\tilde{\chi}_{\delta}(t)= \begin{cases}1, & |t|<\frac{1}{2} \delta \\ 0, & |t|>\delta\end{cases}
$$

Put

$$
\begin{equation*}
æ_{\alpha, \delta}(p, x)=\chi_{\delta}\left(p_{1}\right) \chi_{\delta}\left(p_{2}\right) \chi_{\delta}\left(x_{1}\right) \chi_{\delta}\left(x_{2}\right) \tilde{\chi}_{\delta}\left(q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)-1\right), \tag{3.3}
\end{equation*}
$$

where $p=\left(p_{1}, p_{2}\right) \in P, x=\left(x_{1}, x_{2}\right) \in X$.
We define the Fourier integral operator $R_{\alpha, \delta}$ by the following formula:

$$
\begin{equation*}
R_{\alpha, \delta} u(p)=\frac{1}{2 \pi} \int_{\mathbb{R}} \int_{X} e^{i \phi_{\alpha}(p, x, \theta)} æ_{\alpha, \delta}(p, x) u(x) d x d \theta, \quad p \in P \tag{3.4}
\end{equation*}
$$

where $u \in C_{c}^{\infty}(X)$ and $\phi_{\alpha}$ is defined in (3.2).
In a similar way with formula (3.1) we can obtain that

$$
\begin{equation*}
R_{\alpha, \delta} u(p)=\int_{X_{\alpha, p}} æ_{\alpha, \delta}(p, x) u(x) \omega_{\alpha, p}, \quad p \in P \tag{3.5}
\end{equation*}
$$

In particular, the definition of $R_{\alpha, \delta}$ doesn't depend on the choice of function $\widetilde{\chi}_{\delta}$.
It follows from formula $\left(3.4\right.$ that the Schwartz kernel $K_{\alpha, \delta}$ of operator $R_{\alpha, \delta}$ is given by formula

$$
\begin{equation*}
K_{\alpha, \delta}(p, x)=\frac{1}{2 \pi} \int_{\mathbb{R}} e^{i \phi_{\alpha}(p, x, \theta)} æ_{\alpha, \delta}(p, x) d \theta \tag{3.6}
\end{equation*}
$$

Formulas (3.3), (3.6) imply that

$$
\begin{gather*}
\operatorname{supp} K_{\alpha, \delta} \subseteq\left\{\left(p_{1}, p_{2} ; x_{1}, x_{2}\right) \in P \times X:\right. \\
\left.q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right) \leq \delta, \quad \delta \leq x_{j} \leq \delta^{-1}, \delta \leq p_{j} \leq \delta^{-1}, j=1,2\right\} \tag{3.7}
\end{gather*}
$$

Hence, $K_{\alpha, \delta}$ is compact and $R_{\alpha, \delta}$ is a proper operator.
As a proper Fourier integral operator, $R_{\alpha, \delta}$ continuously maps $C_{c}^{\infty}(X)$ to $C_{c}^{\infty}(P)$ and $\mathscr{E}^{\prime}(X)$ to $\mathscr{E}^{\prime}(P)$. Note that the dual operator $R_{\alpha, \delta}^{*}$ is given by the same formula (3.4) (after changing $x$ to $p$ and vice versa). Hence, the composition $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a well-defined proper linear continuous operator on $C_{c}^{\infty}(X)$ and on $\mathscr{E}^{\prime}(X)$. We will show that, in fact, $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a pseudo-differential operator and we will compute its principal symbol.

In order to formulate the following result we need to introduce the set $\Sigma_{\epsilon}$, $0<\epsilon<1$ :

$$
\begin{equation*}
\Sigma_{\epsilon}=\left\{\left(\xi_{1}, \xi_{2}\right) \in \mathbb{R}^{2}: \epsilon<\frac{\xi_{1}}{\xi_{2}}<\epsilon^{-1}\right\} \tag{3.8}
\end{equation*}
$$

Lemma 3.1. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<\delta<\frac{1}{2}$ be fixed. Then $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a classical proper pseudo-differential operator of order 1 on $X$ with principal symbol $\sigma^{P}(x, \xi d x),(x, \xi d x) \in T^{*} X$, given by formula

$$
\sigma_{\alpha, \delta}^{P}(x, \xi d x)=\left\{\begin{array}{l}
\frac{2 \pi}{|\alpha|} \exp \left(i(\pi / 4) \cdot \operatorname{sgn}(1-\alpha) \cdot\left(1-\operatorname{sgn} \xi_{1}\right)\right)\left(x_{1} x_{2}\right)^{-\frac{1}{\beta}} \times  \tag{3.9}\\
\quad \times\left|\xi_{1} \xi_{2}\right|^{-\frac{1}{\beta}}|\xi x|^{1-\frac{2}{\alpha}} æ_{\alpha, \delta}^{2}\left(p^{*}(x, \xi), x\right), \quad \text { if } \xi_{1} \xi_{2}>0 \\
0, \quad \text { otherwise },
\end{array}\right.
$$

where $x=\left(x_{1}, x_{2}\right), \xi=\left(\xi_{1}, \xi_{2}\right), p^{*}(x, \xi)=\left(p_{1}^{*}(x, \xi), p_{2}^{*}(x, \xi)\right), \xi x=\xi_{1} x_{1}+\xi_{2} x_{2}$, $1 / \alpha+1 / \beta=1$,

$$
\begin{equation*}
p_{j}^{*}(x, \xi)=|\xi x|^{-\frac{1}{\alpha}}\left|\xi_{j}\right|^{\frac{1}{\alpha}} x_{j}^{-\frac{1}{\beta}}, \quad j=1,2 . \tag{3.10}
\end{equation*}
$$

Besides, there exists $\epsilon=\epsilon(\alpha, \delta)>0$ such that the full symbol $\sigma_{\alpha, \delta}(x, \xi d x)$ of $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is zero for $x \in X, \xi \in \mathbb{R}^{2} \backslash\left(0 \cup \Sigma_{\epsilon} \cup-\Sigma_{\epsilon}\right)$.

For the definition of classical pseudo-differential operator see, e.g., Ref. [Shu], Definition 3.5.

The biggest part of the present paper is devoted to the proof of Lemma 3.1. In Section 4 we will present and prove a version of method of stationary phase and in Section 5 we will apply this method to prove Lemma 3.1 .

### 3.2 Final part of the proof of Theorem 2.1

We begin this subsection by proving a lemma which follows from Lemma 3.1 and which will be used in the proof of the "only if" part of statement 2 of Theorem 2.1. In the end of this subsection we prove statements 2,3 of Theorem 2.1.

We need to introduce some notations. For canonical relation $C_{\alpha}$ defined in (2.4) the transposed canonical relation $C_{\alpha}^{t}$ is defined by the following formula:

$$
\begin{align*}
& C_{\alpha}^{t} \xlongequal{\text { def }}\left\{(x, \xi d x, p, \eta d p) \in T^{*} X \times T^{*} P:(p, \eta d p, x, \xi d x) \in C_{\alpha}\right\}= \\
& =\left\{\left(x_{1}, x_{2} ; \lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j} ; p_{1}, p_{2} ;-\lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j}\right) \in\right.  \tag{3.11}\\
& \left.\in T^{*} X \times T^{*} P: q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1, \lambda \in \mathbb{R} \backslash 0\right\}
\end{align*}
$$

In a similar way with 2.11 , for a subset $M^{\prime} \subseteq T^{*} P$ we denote

$$
\begin{equation*}
C_{\alpha}^{t} \circ M^{\prime} \xlongequal{\text { def }}\left\{(x, \xi d x) \in T^{*} X: \exists(p, \eta d p) \in M^{\prime}:(x, \xi d x ; p, \eta d p) \in C_{\alpha}^{t}\right\} \tag{3.12}
\end{equation*}
$$

We also need to introduce the following sets:

$$
\begin{gather*}
\Sigma=\left\{\xi=\left(\xi_{1}, \xi_{2}\right) \in \mathbb{R}^{2}: \xi_{1}>0, \xi_{2}>0\right\} \\
T_{ \pm}^{*} X=\left\{(x, \xi d x) \in T^{*} X: \xi \in \pm \Sigma\right\}  \tag{3.13}\\
T_{ \pm}^{*} P=\left\{(p, \eta d p) \in T^{*} P: \eta \in \pm \Sigma\right\} \\
X_{\delta}=\left\{\left(x_{1}, x_{2}\right) \in X: \delta<x_{j}<\delta^{-1}, j=1,2\right\}, \quad 0<\delta<1  \tag{3.14}\\
P_{\delta}=\left\{\left(p_{1}, p_{2}\right) \in P: \delta<p_{j}<\delta^{-1}, j=1,2\right\}, \quad 0<\delta<1
\end{gather*}
$$

Lemma 3.2. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $u \in \mathscr{E}^{\prime}(X)$ be fixed. Then

$$
\begin{equation*}
W F(u) \cap\left(T_{+}^{*} X \cup T_{-}^{*} X\right) \subseteq C_{\alpha}^{t} \circ W F\left(R_{\alpha} u\right) \tag{3.15}
\end{equation*}
$$

Proof. Let $u \in \mathscr{E}^{\prime}(X)$ and $\left(x^{0}, \xi^{0} d x\right) \in W F(u)$ with $\xi^{0} \in \Sigma \cup(-\Sigma)$ be fixed. Lemma 3.2 will be proved if we show that

$$
\begin{equation*}
\left(x^{0}, \xi^{0} d x\right) \in C_{\alpha}^{t} \circ W F\left(R_{\alpha} u\right) \tag{3.16}
\end{equation*}
$$

Chose $0<\delta<\frac{1}{2}$ such that

$$
\begin{equation*}
\operatorname{supp} u \subseteq X_{2 \delta} \text { and } p^{*}\left(x^{0}, \xi^{0}\right) \in P_{2 \delta} \tag{3.17}
\end{equation*}
$$

where $p^{*}\left(x^{0}, \xi^{0}\right)=\left(p_{1}^{*}\left(x^{0}, \xi^{0}\right), p_{2}^{*}\left(x^{0}, \xi^{0}\right)\right)$ is defined in (3.10).
If follows from (3.3), 3.9), (3.17) that $æ_{\alpha, \delta}\left(p^{*}\left(x^{0}, \xi^{0}\right), x^{0}\right)=1$ and

$$
\begin{equation*}
\sigma_{\alpha, \delta}^{P}\left(x^{0}, \xi^{0} d x\right) \neq 0 \tag{3.18}
\end{equation*}
$$

Formula (3.18) implies that

$$
\begin{equation*}
\left(x^{0}, \xi^{0} d x\right) \in W F\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} u\right) \tag{3.19}
\end{equation*}
$$

Operator $R_{\alpha, \delta}^{*}$ is a Fourier integral operator associated with canonical relation $C_{\alpha}^{t}$ and the following inclusion holds:

$$
\begin{equation*}
W F\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} u\right) \subseteq C_{\alpha}^{t} \circ W F\left(R_{\alpha, \delta} u\right) \tag{3.20}
\end{equation*}
$$

It follows from formulas (2.6), (3.3), (3.5), (3.17) that

$$
\left(R_{\alpha, \delta} u\right)(p)=\chi_{\delta}\left(p_{1}\right) \chi_{\delta}\left(p_{2}\right)\left(R_{\alpha} u\right)(p), \quad p \in P
$$

Hence

$$
\begin{equation*}
W F\left(R_{\alpha, \delta} u\right) \subseteq W F\left(R_{\alpha} u\right) \tag{3.21}
\end{equation*}
$$

Formula (3.16) follows from (3.19), 3.20, (3.21). Lemma 3.2 is proved.
Proof of statements 2, 3 of Theorem 2.1. We denote by $\pi_{P}, \pi_{X}, \widetilde{\pi}_{P}, \widetilde{\pi}_{X}$ the canonical projections:


As above, the dot means that we exclude the zero section.
Note that the maps $\pi_{P}, \pi_{X}, \tilde{\pi}_{P}, \tilde{\pi}_{X}$ are injective. Consider, for example, the map $\pi_{P}$. By definition

$$
\begin{gather*}
\pi_{P}\left(p_{1}, p_{2} ; \lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j} ; x_{1}, x_{2} ;-\lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j}\right)  \tag{3.22}\\
=\left(p_{1}, p_{2} ; \lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j}\right)
\end{gather*}
$$

It follows from 3.22 that the value of $\pi_{P}(p, \eta d p, x, \xi d x)$ determines uniquely the ratio $x_{1} / x_{2}$. Since $x_{1}^{\alpha} p_{1}^{\alpha}+x_{2}^{\alpha} p_{2}^{\alpha}=1$, it also determines $x_{1}, x_{2}$. Hence, it also determines $\lambda$ and the map $\pi_{P}$ is injective.

The following formulas follow from $(2.2),(2.3),(2.4),(3.11):$

$$
\begin{align*}
\pi_{P} \circ \pi_{X}^{-1}(W F(u)) & \subseteq T_{+}^{*} P \cup T_{-}^{*} P  \tag{3.23}\\
\pi_{P} \circ \pi_{X}^{-1}\left(\dot{N}^{*} X_{\alpha, p}\right) & =T_{+, p}^{*} P \cup T_{-, p}^{*} P  \tag{3.24}\\
\widetilde{\pi}_{X} \circ \widetilde{\pi}_{P}^{-1}\left(T_{p}^{*} X \backslash 0\right) & =\dot{N}^{*} X_{\alpha, p} \tag{3.25}
\end{align*}
$$

where $p \in P, T_{ \pm}^{*} P$ is defined in (3.13) and $T_{ \pm . p}^{*}=T_{ \pm}^{*} P \cap T_{p}^{*} P$.
Besides, using definitions (2.4), (3.11), 2.11, (3.12) we obtain that

$$
\begin{align*}
\pi_{P} \circ \pi_{X}^{-1}(W F(u)) & =C_{\alpha} \circ W F(u),  \tag{3.26}\\
\widetilde{\pi}_{X} \circ \widetilde{\pi}_{P}^{-1}\left(W F\left(R_{\alpha} u\right)\right) & =C_{\alpha}^{t} \circ W F\left(R_{\alpha} u\right) . \tag{3.27}
\end{align*}
$$

Statement 3. Using (3.23), (3.26) and inclusion $W F\left(R_{\alpha} u\right) \subseteq C_{\alpha} \circ W F(u)$ we obtain that if $(x, \xi d x) \in W F\left(R_{\alpha} u\right), \xi=\left(\xi_{1}, \xi_{2}\right)$, then $\xi_{1} \xi_{2}>0$. Statement 3 of Theorem 2.1 is proved.

Statement 2: "if" part. Suppose that (2.5 holds. Using injectivity of $\pi_{P}$ we obtain that

$$
\pi_{P} \circ \pi_{X}^{-1}(W F(u)) \cap \pi_{P} \circ \pi_{X}^{-1}\left(\dot{N}^{*} X_{\alpha, p}\right)=\varnothing
$$

This formula together with formulas (3.23), (3.24), (3.26) imply that

$$
\begin{equation*}
C_{\alpha} \circ W F(u) \cap T_{p}^{*} P=\varnothing \tag{3.28}
\end{equation*}
$$

Using formula (3.28) and inclusion $W F\left(R_{\alpha} u\right) \subseteq C_{\alpha} \circ W F(u)$ we obtain that $p \notin \operatorname{sing} \operatorname{supp} R_{\alpha} u$.

Statement 2: "only if" part. Suppose that $p \notin \operatorname{sing} \operatorname{supp} R_{\alpha} u$. Equivalently,

$$
\begin{equation*}
W F\left(R_{\alpha} u\right) \cap\left(T_{p}^{*} P \backslash 0\right)=\varnothing \tag{3.29}
\end{equation*}
$$

Using injectivity of $\widetilde{\pi}_{X}$ and formulas (3.25), (3.27) we obtain from (3.29) the following formula:

$$
\begin{equation*}
C_{\alpha}^{t} \circ W F\left(R_{\alpha} u\right) \cap \dot{N}^{*} X_{\alpha, p}=\varnothing \tag{3.30}
\end{equation*}
$$

Note that formula (2.3) implies that

$$
\begin{equation*}
\dot{N}^{*} X_{\alpha, p} \subseteq T_{+}^{*} X \cup T_{-}^{*} X \tag{3.31}
\end{equation*}
$$

Using inclusion (3.15) of Lemma 3.2 and formulas (3.30), (3.31), we obtain formula (2.5). Theorem 2.1] is proved.

### 3.3 Proof of Proposition 2.1

Let $u \in \mathscr{E}^{\prime}(X)$ and $(x, \xi d x) \in T^{*} X$ satisfying the conditions of Proposition 2.1 be fixed. It follows from the definition of $\delta$ and from 3.10 that

$$
\begin{equation*}
\sigma_{\alpha, \delta}^{P}(x, \xi d x) \neq 0 \tag{3.32}
\end{equation*}
$$

where $\sigma_{\alpha, \delta}^{P}$ is the symbol of operator $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ defined in 3.9.
"Only if" part. Suppose that $(x, \xi d x) \in W F(u)$. Then it follows from 3.32 that

$$
\begin{equation*}
(x, \xi d x) \in W F\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} u\right) \tag{3.33}
\end{equation*}
$$

Since $u$ satisfies 2.8 and $2 \delta<\varepsilon$, the following formula is valid:

$$
\begin{equation*}
R_{\alpha, \delta} u=\chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u \tag{3.34}
\end{equation*}
$$

Also note that

$$
\begin{equation*}
R_{\alpha, \delta}^{*}=\tilde{\chi}_{\delta}^{1} \tilde{\chi}_{\delta}^{2} R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} \tag{3.35}
\end{equation*}
$$

where $\tilde{\chi}_{\delta}^{j}$ is the operator of multiplication by $\chi_{\delta}\left(x_{j}\right), j=1,2$.
Formulas (3.34, (3.35) imply that

$$
W F\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} u\right) \subseteq W F\left(R_{\alpha}^{*}\left(\chi_{\delta}^{1}\right)^{2}\left(\chi_{\delta}^{2}\right)^{2} R_{\alpha} u\right)
$$

From this formula, taking into account that we can replace $\left(\chi_{\delta}^{j}\right)^{2}$ by $\chi_{\delta}^{j}, j=1$, 2 , and from formula 3.33 it follows that

$$
\begin{equation*}
(x, \xi d x) \in W F\left(R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u\right) \tag{3.36}
\end{equation*}
$$

"If" part. Suppose now that (3.36) holds. Then we have the following sequence of inclusions:

$$
\begin{gathered}
(x, \xi d x) \in W F\left(R_{\alpha}^{*} \chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u\right) \\
\subseteq C_{\alpha}^{t} \circ W F\left(\chi_{\delta}^{1} \chi_{\delta}^{2} R_{\alpha} u\right) \subseteq C_{\alpha}^{t} \circ W F\left(R_{\alpha} u\right) \\
\subseteq C_{\alpha}^{t} \circ C_{\alpha} \circ W F(u) \subseteq W F(u)
\end{gathered}
$$

since $R_{\alpha}^{*}$ is the Fourier integral operator associated with canonical relation $C_{\alpha}^{t}$ and the inclusion $C_{\alpha}^{t} \circ C_{\alpha} \subseteq \operatorname{diag}\left(T^{*} X \times T^{*} X\right)$ holds, where

$$
\begin{gather*}
\operatorname{diag}\left(T^{*} X \times T^{*} X\right) \xlongequal{\text { def }}\left\{(x, \xi d x, x, \xi d x) \in T^{*} X \times T^{*} X\right\},  \tag{3.37}\\
C_{\alpha}^{t} \circ C_{\alpha} \xlongequal{\text { def }}\left\{(y, \zeta d y, x, \xi d x) \in T^{*} X \times T^{*} X:\right.  \tag{3.38}\\
\left.\exists(p, \eta d p) \in T^{*} P:(y, \zeta d y, p, \eta d p) \in C_{\alpha}^{t},(p, \eta d p, x, \xi d x) \in C_{\alpha}\right\} .
\end{gather*}
$$

Proposition 2.1 is proved.

## 4 Method of stationary phase

In this section we formulate and prove a version of method of stationary phase which will be used in Section 5 in the proof of Lemma 3.1 .

We say that a subset $\widehat{\Sigma} \subseteq \mathbb{R}^{2} \backslash 0$ is conic if

$$
\left\{t \xi \in \mathbb{R}^{2}: t>0, \xi \in \widehat{\Sigma}\right\}=\widehat{\Sigma}
$$

Let $\widehat{\Sigma} \subseteq \mathbb{R}^{2} \backslash 0$ be an open conic set. We denote by $S^{\gamma}(X \times \widehat{\Sigma}), \gamma \in \mathbb{R}$, the set of functions $a \in C^{\infty}(X \times \widehat{\Sigma})$ satisfying the following property: for any compact $K \subset X \times \widehat{\Sigma}$ and for any $\alpha=\left(\alpha_{1}, \alpha_{2}\right), \beta=\left(\beta_{1}, \beta_{2}\right) \in \mathbb{Z}_{+}^{2}$ there exists such constant $C_{K}^{\alpha, \beta}>0$ that

$$
\left|D_{x}^{\alpha} D_{\xi}^{\beta} a(x, \xi)\right| \leq C_{K}^{\alpha, \beta}|\xi|^{\gamma-|\beta|}, \quad|\xi| \geq 1, \xi=t \widetilde{\xi}, t>0,(x, \widetilde{\xi}) \in K
$$

where

$$
D_{x}^{\alpha}=\frac{\partial^{|\alpha|}}{\partial x_{1}^{\alpha_{1}} \partial x_{2}^{\alpha_{2}}}, \quad D_{\xi}^{\beta}=\frac{\partial^{|\beta|}}{\partial \xi_{1}^{\beta_{1}} \partial \xi_{2}^{\beta_{2}}}
$$

and $|\alpha|=\alpha_{1}+\alpha_{2},|\beta|=\beta_{1}+\beta_{2}$.
The space $S^{\gamma}(P \times \widehat{\Sigma}), \gamma \in \mathbb{R}$, is defined in a similar way. We also put $S^{-\infty}(X \times \widehat{\Sigma})=\cap_{\gamma \in \mathbb{R}} S^{\gamma}(X \times \widehat{\Sigma})$ and $S^{-\infty}(P \times \widehat{\Sigma})=\cap_{\gamma \in \mathbb{R}} S^{\gamma}(P \times \widehat{\Sigma})$.

We will formulate and prove a version of method of stationary phase for the integrals of the following form:

$$
\begin{equation*}
I(p, \xi)=\int_{X_{q, p}} e^{i S(x, \xi)} f(x, \xi) \omega_{q, p} \tag{4.1}
\end{equation*}
$$

where $q \in C^{\infty}(X)$ satisfies Q1, Q2 of Remark 2.2, $X_{q, p}$ is defined in 2.10 with orientation given by the volume form $\left|\nabla_{x} q\left(p_{1} x_{1}, p_{2} x_{2}\right)\right| \omega_{q, p}$, where $\omega_{q, p}$ is the Gelfand-Leray form:

$$
\left.\omega_{q, p}=d_{x} q\left(p_{1} x_{1}, p_{2} x_{2}\right)\right\lrcorner\left(d x_{1} \wedge d x_{2}\right)
$$

and $S \in C^{\infty}(X \times \widehat{\Sigma})$ satisfies the following assumption:
S1. $S(x, \lambda \xi)=\lambda S(x, \xi), x \in X, \xi \in \widehat{\Sigma}, \lambda>0$.
Assumtion Q2 of Remark 2.2 implies that at fixed $p \in P$ the curve $X_{q, p}$ is the graph of $C^{\infty}$ function

$$
\begin{equation*}
x_{2}=x_{2}\left(x_{1}, p\right), \quad x_{1}^{-}(p)<x_{1}<x_{1}^{+}(p) \leq+\infty \tag{4.2}
\end{equation*}
$$

Put $\widetilde{S}(t, p, \xi)=S\left(\left(t, x_{2}(t, p)\right), \xi\right)$.
We suppose that $q$ and $S$ satisfy the following additional assumptions:
QS1. at fixed $p \in P, \xi \in \widehat{\Sigma}$ function $\widetilde{S}(\cdot, p, \xi)$ has the unique local extremum $x_{1}^{*}(p, \xi)$ on the interval $\left(x_{1}^{-}(p), x_{1}^{+}(p)\right)$ which is the unique zero of function $\widetilde{S}_{t}(\cdot, p, \xi)$; the map $x_{1}^{*}: X \times \widehat{\Sigma} \rightarrow(0,+\infty)$ is $C^{\infty}$ and open;

QS2. the second derivative $\widetilde{S}_{t t}\left(x_{1}^{*}(p, \xi), p, \xi\right)$ is nonzero and has the same sign for all $p \in P, \xi \in \widehat{\Sigma}$.
Lemma 4.1. Let $\widehat{\Sigma}$ be $\Sigma$ or $-\Sigma$. Let $q \in C^{\infty}(X)$ satisfy assumptions Q1, Q2 of Remark 2.2 and $S \in C^{\infty}(X \times \widehat{\Sigma})$ satisfy assumption $S 1$ above. Suppose also that $q, S$ satisfy assumptions QS1, QS2 defined above. Suppose that $f \in S^{m}(X \times \widehat{\Sigma})$, $m \in \mathbb{R}$, and $f(\cdot, \xi)$ has compact support in $X$ for any fixed $\xi \in \widehat{\Sigma}$. Then:

1. the following inclusion holds:

$$
\begin{equation*}
e^{-i S^{*}(p, \xi)} I(p, \xi) \in S^{m-\frac{1}{2}}(P \times \widehat{\Sigma}) \tag{4.3}
\end{equation*}
$$

where $I(p, \xi)$ is defined in 4.1), $S^{*}(p, \xi)=S\left(x^{*}(p, \xi), \xi\right), x^{*}(p, \xi)=$ $\left(x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)\right), x_{1}^{*}$ is defined in assumption QS1 above, $x_{2}^{*}(p, \xi)=$ $x_{2}\left(x_{1}^{*}(p, \xi), p\right)$;
2. if, in addition, function $f$ satisfies

$$
\begin{equation*}
f(x, \lambda \xi)=\lambda^{m} f(x, \xi), \quad x \in X, \xi \in \widehat{\Sigma}, \lambda>0 \tag{4.4}
\end{equation*}
$$

then there exist the unique functions $a_{j} \in C^{\infty}(P \times \widehat{\Sigma}), j \in \mathbb{N} \cup 0$, satisfying

$$
\begin{equation*}
a_{j}(p, \lambda \xi)=\lambda^{m-\frac{1}{2}-j} a_{j}(p, \xi), \quad p \in P, \xi \in \widehat{\Sigma}, \lambda>0, j \in \mathbb{N} \cup 0 \tag{4.5}
\end{equation*}
$$

and such that for any $N \in \mathbb{N} \cup 0$ the following formula is valid:

$$
\begin{equation*}
e^{-i S^{*}(p, \xi)} I(p, \xi)-\sum_{j=0}^{N} a_{j}(p, \xi)=r_{N}(p, \xi) \in S^{m-N-\frac{3}{2}}(P \times \widehat{\Sigma}) \tag{4.6}
\end{equation*}
$$

furthermore, the following formula is holds:

$$
\begin{align*}
a_{0}(p, \xi)= & (2 \pi)^{1 / 2} e^{i \pi / 4} f\left(x^{*}(p, \xi), \xi\right)\left(\widetilde{S}_{t t}\left(x_{1}^{*}(p, \xi), p, \xi\right)\right)^{-1 / 2} \times  \tag{4.7}\\
& \times p_{2}^{-1}\left(\partial_{2} q\left(p_{1} x_{1}^{*}(p, \xi), p_{2} x_{2}^{*}(p, \xi)\right)\right)^{-1}
\end{align*}
$$

Proof. We suppose that $\widehat{\Sigma}=\Sigma$ and

$$
\begin{equation*}
\widetilde{S}_{t t}\left(x_{1}^{*}(p, \xi), p, \xi\right)>0, \quad p \in P, \xi \in \Sigma \tag{4.8}
\end{equation*}
$$

The other three cases $\left(\widehat{\Sigma}=-\Sigma, \widetilde{S}_{t t}>0 ; \widehat{\Sigma}=\Sigma, \widetilde{S}_{t t}<0 ; \widehat{\Sigma}=-\Sigma, \widetilde{S}_{t t}<0\right)$ can be considered in a similar way.

The proof of Lemma 4.1 consists of six steps.
Step 1: uniform Morse coordinate. Using integration by parts and taking into account that $\widetilde{S}_{t}\left(x_{1}^{*}(p, \xi), p, \xi\right)=0$ we obtain that at fixed $p \in P, \xi \in \Sigma$ for $x_{1}$ sufficiently close to $x_{1}^{*}(p, \xi)$ the following chain of equalities holds:

$$
\begin{gather*}
\widetilde{S}\left(x_{1}, p, \xi\right)-S^{*}(p, \xi) \\
=\int_{0}^{1}(1-\tau) \frac{d^{2}}{d \tau^{2}} \widetilde{S}\left(x_{1}^{*}(p, \xi)+\tau\left(x_{1}-x_{1}^{*}(p, \xi)\right), p, \xi\right) d \tau \\
=\left(x_{1}-x_{1}^{*}(p, \xi)\right)^{2} \int_{0}^{1}(1-\tau) \widetilde{S}_{t t}\left(x_{1}^{*}(p, \xi)+\tau\left(x_{1}-x_{1}^{*}(p, \xi), p, \xi\right) d \tau\right.  \tag{4.9}\\
=\frac{1}{2} z_{1}^{2}\left(x_{1}, p, \xi\right),
\end{gather*}
$$

where $z_{1}\left(x_{1}, p, \xi\right)$ is defined for $x_{1}$ sufficiently close to $x_{1}^{*}(p, \xi)$ :

$$
\begin{gather*}
z_{1}\left(x_{1}, p, \xi\right)=\sqrt{2}\left(x_{1}-x_{1}^{*}(p, \xi)\right) \times \\
\times\left(\int_{0}^{1}(1-\tau) \widetilde{S}_{t t}\left(x_{1}^{*}(p, \xi)+\tau\left(x_{1}-x_{1}^{*}(p, \xi)\right), p, \xi\right) d \tau\right)^{1 / 2} . \tag{4.10}
\end{gather*}
$$

Let $0<\epsilon<1$ be fixed. Define $s=x_{1}-x_{1}^{*}(p, \xi)$ for $x_{1} \in\left(x_{1}^{-}(p), x_{1}^{+}(p)\right)$.
Recall that the sets $\Sigma_{\epsilon}, P_{\epsilon}, \epsilon>0$, are defined in formulas (3.8), (3.14). Since $x_{1}^{*}$ is open and continuous, the set $x_{1}^{*}\left(P_{\epsilon} \times \Sigma_{\epsilon}\right)$ in an interval and $x_{1}^{*}\left(P_{\epsilon} \times \Sigma_{\epsilon}\right) \Subset$ $\left(x_{1}^{-}(p), x_{1}^{+}(p)\right)$.

Hence, for all $p \in P_{\epsilon}$ and $\xi \in \Sigma_{\epsilon}$ the range of variable $s$ contains an interval $\left(-\widetilde{\nu}_{\epsilon}, \widetilde{\nu}_{\epsilon}\right), \widetilde{\nu}_{\epsilon}>0$, not depending on $p, \xi$.

Fix $\widetilde{p} \in P$ and $\widetilde{\xi} \in \Sigma$. It follows from (4.8), 4.10) that

$$
\begin{equation*}
\frac{\partial z_{1}}{\partial x_{1}}\left(x_{1}^{*}(\widetilde{p}, \widetilde{\xi}), \widetilde{p}, \widetilde{\xi}\right)=\left(\widetilde{S}_{t t}\left(x_{1}^{*}(\widetilde{p}, \widetilde{\xi}), \widetilde{p}, \widetilde{\xi}\right)\right)^{1 / 2}>0 \tag{4.11}
\end{equation*}
$$

Since the derivatives $S_{t t}\left(x_{1}, p, \xi\right)$ and $\partial z_{1} / \partial x_{1}\left(x_{1}, p, \xi\right)$ are continuous w.r.t. $\left(x_{1}, p, \xi\right)$, there exist open neighborhood $U_{1}(\widetilde{p}, \widetilde{\xi})$ of point $0 \in \mathbb{R}$, open neighborhood $U_{2}(\widetilde{p}, \widetilde{\xi})$ of point $\widetilde{p} \in P$ and open conic neighborhood $U_{3}(\widetilde{p}, \widetilde{\xi})$ of point $\widetilde{\xi} \in \Sigma$ such that for any $(s, p, \xi) \in \Pi_{j=1}^{3} U_{j}(\widetilde{p}, \widetilde{\xi})$ function $z_{1}\left(x_{1}, p, \xi\right)$ is welldefined and the following inequality holds:

$$
\frac{\partial z_{1}}{\partial x_{1}}\left(s+x_{1}^{*}(p, \xi), p, \xi\right)>0
$$

The set $\bar{P}_{\epsilon}$ is compact and the set $\bar{\Sigma}_{\epsilon}$ is conically compact (i.e., it is conic and its intersection with the unit circle $S^{1}$ in $\mathbb{R}^{2}$ is compact). The system of sets $\Pi_{j=2}^{3} U_{j}(\widetilde{p}, \widetilde{\xi}), \widetilde{p} \in P, \widetilde{\xi} \in \Sigma$, is an open cover of $\bar{P}_{\epsilon} \times \bar{\Sigma}_{\epsilon}$. Let $\Pi_{j=2}^{3} U_{j}\left(\widetilde{p}^{k}, \widetilde{\xi} k\right)$, $k=1, \ldots, N_{1}$, be its finite subcover. Denote by $\left(-\nu_{\epsilon}, \nu_{\epsilon}\right)$ any symmetric with respect to zero interval contained in $\cap_{k=1}^{N_{1}} U_{1}\left(\widetilde{p}^{k}, \widetilde{\xi}^{k}\right)$. Then $z_{1}\left(x_{1}, p, \xi\right)$ is well-defined for $x_{1}-x_{1}^{*}(p, \xi) \in\left(-\nu_{\epsilon}, \nu_{\epsilon}\right), p \in \bar{P}_{\epsilon}, \xi \in \Sigma_{\epsilon}$ and

$$
\begin{equation*}
\frac{\partial z_{1}}{\partial x_{1}}\left(x_{1}, p, \xi\right)>0 \text { for } x_{1}-x_{1}^{*}(p, \xi) \in\left(-\nu_{\epsilon}, \nu_{\epsilon}\right), p \in P_{\epsilon}, \xi \in \Sigma_{\epsilon} \tag{4.12}
\end{equation*}
$$

Step 2: partition of unity. Fix $\widetilde{p} \in P_{\epsilon}, \widetilde{\xi} \in \Sigma_{\epsilon}$. Since $x_{1}^{*}$ is continuous, there exist an open neighborhood $\widetilde{P}(\widetilde{p})$ of $\widetilde{p}$ in $P_{\epsilon}$ and an open conic neighborhood $\widetilde{\Sigma}(\widetilde{\xi})$ of $\widetilde{\xi}$ in $\Sigma_{\epsilon}$ such that $\left|x_{1}^{*}(\widetilde{P}(\widetilde{p}) \times \widetilde{\Sigma}(\widetilde{\xi}))\right|<\frac{1}{2} \nu_{\epsilon}$.

The set $\bar{P}_{2 \epsilon}$ is compact and the set $\bar{\Sigma}_{2 \epsilon}$ is conically compact. The sets $\widetilde{P}(\widetilde{p}) \times \widetilde{\Sigma}(\widetilde{\xi}), \widetilde{p} \in P_{\epsilon}, \widetilde{\xi} \in \Sigma_{\epsilon}$, form an open cover of $\bar{P}_{2 \epsilon} \times \bar{\Sigma}_{2 \epsilon}$. Let $\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$, $k=1, \ldots, N_{2}$ be its finite subcover, so that

$$
\begin{equation*}
P_{2 \epsilon} \times \Sigma_{2 \epsilon} \subseteq \bigcup_{k=1}^{N_{2}}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right) \subseteq P_{\epsilon} \times \Sigma_{\epsilon} \tag{4.13}
\end{equation*}
$$

Denote $\left(x_{1, k}^{-}, x_{1, k}^{+}\right)=x_{1}^{*}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right), k=1, \ldots, N_{2}$. Then

$$
\begin{equation*}
x_{1, k}^{+}-x_{1, k}^{-}<\frac{1}{2} \nu_{\epsilon}, \quad k=1, \ldots, N_{2} . \tag{4.14}
\end{equation*}
$$

It follows from (4.12), 4.14 that

$$
\begin{equation*}
\frac{\partial z_{1}}{\partial x_{1}}\left(x_{1}, p, \xi\right)>0 \text { on }\left(x_{1, k}^{-}-\frac{1}{2} \nu_{\epsilon}, x_{1, k}^{+}+\frac{1}{2} \nu_{\epsilon}\right) \times \widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right) \tag{4.15}
\end{equation*}
$$

Fix $k \in\left\{1, \ldots, N_{2}\right\}$. Let $\varphi_{1}^{k} \in C^{\infty}(0,+\infty)$ satisfy $0 \leq \varphi_{1}^{k}\left(x_{1}\right) \leq 1, x_{1}>0$,

$$
\varphi_{1}^{k}\left(x_{1}\right)= \begin{cases}1, & \text { if } x_{1, k}^{-}-\frac{1}{8} \nu_{\epsilon}<x_{1}<x_{1, k}^{+}+\frac{1}{8} \nu_{\epsilon}  \tag{4.16}\\ 0, & \text { if } x_{1}<x_{1, k}^{-}-\frac{1}{4} \nu_{\epsilon} \text { or } x_{1}>x_{1, k}^{+}+\frac{1}{4} \nu_{\epsilon}\end{cases}
$$

We define $\varphi_{2}^{k}=1-\varphi_{1}^{k}$. Formula (4.16) implies that

$$
\begin{equation*}
\operatorname{dist}\left(\operatorname{supp} \varphi_{2}^{k}, x_{1}^{*}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right) \geq \frac{1}{8} \nu_{\epsilon}\right. \tag{4.17}
\end{equation*}
$$

At fixed $k \in\left\{1, \ldots, N_{2}\right\}, p \in P, \xi \in \Sigma$ we rewrite integral (4.1) in the following form:

$$
\begin{gather*}
I(p, \xi)=I_{1}^{k}(p, \xi)+I_{2}^{k}(p, \xi)  \tag{4.18}\\
I_{j}^{k}(p, \xi)=\int_{x_{1}^{-}(p)}^{x_{1}^{+}(p)} \frac{e^{i \widetilde{S}\left(x_{1}, p, \xi\right)} f\left(x_{1}, x_{2}\left(x_{1}, p\right), \xi\right) \varphi_{j}^{k}\left(x_{1}\right) d x_{1}}{p_{2} \partial_{2} q\left(p_{1} x_{1}, p_{2} x_{2}\left(x_{1}, p\right)\right)}, \quad j=1,2 \tag{4.19}
\end{gather*}
$$

where $\partial_{2} q\left(y_{1}, y_{2}\right)=\frac{\partial q}{\partial y_{2}}\left(y_{1}, y_{2}\right)$.
Step 3: integral $I_{1}^{k}(p, \xi)$. It follows from 4.15 that at fixed $p \in \widetilde{P}\left(\widetilde{p}^{k}\right)$, $\xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$ function $z_{1}(\cdot, p, \xi)$ on $\left(x_{1, k}^{-}-\frac{1}{2} \nu_{\epsilon}, x_{1, k}^{+}+\frac{1}{2} \nu_{\epsilon}\right)$ has the inverse $x_{1}(\cdot, p, \xi)$.

It follows from 4.9, 4.16, 4.19) that

$$
\begin{equation*}
I_{1}^{k}(p, \xi)=e^{i S^{*}(p, \xi)} \int_{-\infty}^{+\infty} e^{\frac{i}{2} z_{1}^{2}} g^{k}\left(z_{1}, p, \xi\right) d z_{1} \tag{4.20}
\end{equation*}
$$

where

$$
g^{k}\left(z_{1}, p, \xi\right)=\left\{\begin{array}{c}
f\left(x_{1}\left(z_{1}, p, \xi\right), x_{2}\left(z_{1}, p, \xi\right), \xi\right) \frac{\partial x_{1}}{\partial z_{1}}\left(z_{1}, p, \xi\right) \times  \tag{4.21}\\
\quad \times p_{2}^{-1}\left(\partial_{2} q\left(p_{1} x_{1}\left(z_{1}, p, \xi\right), p_{2} x_{2}\left(z_{1}, p, \xi\right)\right)\right)^{-1} \times \\
\quad \times \varphi_{1}^{k}\left(x_{1}\left(z_{1}, p, \xi\right)\right), \text { if } x_{1}\left(z_{1}, p, \xi\right) \in \operatorname{supp} \varphi_{1}^{k} \\
0, \\
\text { otherwise },
\end{array}\right.
$$

and $x_{2}\left(z_{1}, p, \xi\right)=x_{2}\left(x_{1}\left(z_{1}, p, \xi\right), p\right)$.
Define $\widetilde{z}_{1}\left(x_{1}, p, \xi\right)=|\xi|^{-\frac{1}{2}} z_{1}\left(x_{1}, p, \xi\right)$. It follows from assumption S1 and from formula 4.10) that $\widetilde{z}_{1}\left(x_{1}, p, \lambda \xi\right)=\widetilde{z}_{1}\left(x_{1}, p, \xi\right), x_{1} \in\left(x_{1, k}^{-}-\frac{1}{2} \nu_{\epsilon}, x_{1, k}^{+}+\frac{1}{2} \nu_{\epsilon}\right)$, $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \lambda>0$. Note that at fixed $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$ the inverse $\widetilde{x}_{1}(\cdot, p, \xi)$ of $\widetilde{z}_{1}(\cdot, x, \xi)$ on $\left(x_{1, k}^{-}-\frac{1}{2} \nu_{\epsilon}, x_{1, k}^{+}+\frac{1}{2} \nu_{\epsilon}\right)$ exists and the following formulas hold:

$$
\begin{align*}
x_{1}\left(z_{1}, p, \xi\right) & =\widetilde{x}_{1}\left(|\xi|^{-\frac{1}{2}} z_{1}, p, \xi\right)  \tag{4.22}\\
\widetilde{x}_{1}\left(\widetilde{z}_{1}, p, \lambda \xi\right) & =\widetilde{x}_{1}\left(\widetilde{z}_{1}, p, \xi\right), \quad \lambda>0 \tag{4.23}
\end{align*}
$$

for all $z_{1}$ (resp. $\left.\widetilde{z}_{1}\right)$ in the domain of definition of $x_{1}(\cdot, p, \xi)\left(\right.$ resp. $\widetilde{x}_{1}(\cdot, p, \xi)$ ), $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$.

It follows from assumption S1 and from formula 4.10 that the quantity $|\xi|^{-\frac{1}{2}} z_{1}\left(x_{1}, p, \xi\right)$ is uniformly bounded for $x_{1} \in \operatorname{supp} \varphi_{1}^{k}, p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$.

Taking this into account and using formulas 4.22, 4.23 we obtain that at fixed $k \in\left\{1, \ldots, N_{2}\right\}$ for any $\alpha, \beta \in \mathbb{Z}_{+}^{2}$ there exist constants $C_{1, k}^{\alpha, \beta}>0$ such that the following inequalities hold:

$$
\begin{align*}
& \left|D_{p}^{\alpha} D_{\xi}^{\beta} x_{1}\left(z_{1}, p, \xi\right)\right|,\left|D_{p}^{\alpha} D_{\xi}^{\beta} x_{2}\left(z_{1}, p, \xi\right)\right|,\left|D_{p}^{\alpha} D_{\xi}^{\beta} \varphi_{1}^{k}\left(x_{1}\left(z_{1}, p, \xi\right)\right)\right| \\
& \quad\left|D_{p}^{\alpha} D_{\xi}^{\beta}\left(q\left(p_{1} x_{1}\left(z_{1}, p, \xi\right), p_{2} x_{2}\left(z_{1}, p, \xi\right)\right)\right)^{-1}\right| \leq C_{1, k}^{\alpha, \beta}|\xi|^{-|\beta|} \\
& \left|D_{p}^{\alpha} D_{\xi}^{\beta} \frac{\partial x_{1}}{\partial z_{1}}\left(z_{1}, x, \xi\right)\right| \leq C_{1, k}^{\alpha, \beta}|\xi|^{-|\beta|-\frac{1}{2}}  \tag{4.24}\\
& \left|D_{p}^{\alpha} D_{\xi}^{\beta} f\left(x_{1}\left(z_{1}, p, \xi\right), x_{2}\left(z_{1}, p, \xi\right), \xi\right)\right| \leq C_{1, k}^{\alpha, \beta}|\xi|^{m-|\beta|}
\end{align*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right),|\xi| \geq 1, z_{1} \in z_{1}\left(\operatorname{supp} \varphi_{1}^{k}, p, \xi\right)$.
Formulas 4.20, 4.21 and inequalities 4.24 imply that at fixed $k \in$ $\left\{1, \ldots, N_{2}\right\}$ for any $\alpha, \beta \in \mathbb{Z}_{+}^{2}$ there exist constants $C_{2, k}^{\alpha, \beta}>0, C_{3, k}^{\alpha, \beta}>0$ such that

$$
\begin{gather*}
\left|D_{p}^{\alpha} D_{\xi}^{\beta} g^{k}\left(z_{1}, p, \xi\right)\right| \leq C_{2, k}^{\alpha, \beta}|\xi|^{m-\frac{1}{2}-|\beta|}  \tag{4.25}\\
\left|D_{p}^{\alpha} D_{\xi}^{\beta}\left(e^{-i S^{*}(p, \xi)} I_{1}^{k}(p, \xi)\right)\right| \leq C_{3, k}^{\alpha, \beta}|\xi|^{m-\frac{1}{2}-|\beta|} \tag{4.26}
\end{gather*}
$$

where $z_{1} \in \mathbb{R}, p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right),|\xi| \geq 1$.
We need to introduce some notations. Let $\widetilde{P} \subseteq P$ be an open set and $\widetilde{\Sigma} \subseteq \Sigma$ be an open conic set. Let $\gamma \in \mathbb{R}$ be fixed. We denote by $\widetilde{S}^{\gamma}(\widetilde{P} \times \widetilde{\Sigma})$ the set of functions $a \in C^{\infty}(\widetilde{P} \times \widetilde{\Sigma})$ such that for any $\alpha, \beta \in \mathbb{Z}_{+}^{2}$ there exists a constant $\widetilde{C}^{\alpha, \beta}>0$ such that

$$
\begin{equation*}
\left|D_{p}^{\alpha} D_{\xi}^{\beta} a(p, \xi)\right| \leq \widetilde{C}^{\alpha, \beta}|\xi|^{\gamma-|\beta|}, \quad p \in \widetilde{P}, \xi \in \widetilde{\Sigma},|\xi| \geq 1 \tag{4.27}
\end{equation*}
$$

Besides, we denote $\widetilde{S}^{-\infty}(\widetilde{P} \times \widetilde{\Sigma})=\cap_{\gamma \in \mathbb{R}} \widetilde{S}^{\gamma}(\widetilde{P} \times \widetilde{\Sigma})$.
Note that we can rewrite formula 4.26 in the following form:

$$
\begin{equation*}
e^{-i S^{*}(p, \xi)} I_{1}^{k}(p, \xi) \in \widetilde{S}^{m-\frac{1}{2}}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right), \quad k=1, \ldots, N_{2} \tag{4.28}
\end{equation*}
$$

Step 4: functions $a_{j}(p, \xi)$. Throughout the Steps 4, 5 we suppose that 4.4 holds.

Using assumptions Q1, S1 and formulas (4.4, (4.19), 4.20 we obtain the identity

$$
\begin{equation*}
\int_{-\infty}^{+\infty} e^{\frac{i}{2} z_{1}^{2}} g^{k}\left(z_{1}, p, \lambda \xi\right) d z_{1}=\lambda^{m} \int_{-\infty}^{+\infty} e^{\frac{i}{2} \lambda z_{1}^{2}} g^{k}\left(z_{1}, p, \xi\right) d z_{1} \tag{4.29}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \lambda>0$.
Using the Plancherel identity we get

$$
\begin{equation*}
\int_{-\infty}^{+\infty} e^{\frac{i}{2} \lambda z_{1}^{2}} g^{k}\left(z_{1}, p, \xi\right) d z_{1}=(2 \pi \lambda)^{-\frac{1}{2}} e^{i \frac{\pi}{4}} \int_{-\infty}^{+\infty} e^{\frac{i t^{2}}{2 \lambda}} \widehat{g}^{k}(t, p, \xi) d t \tag{4.30}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \lambda>0$ and

$$
\widehat{g}^{k}(t, p, \xi)=\int_{-\infty}^{+\infty} e^{-i t z_{1}} g^{k}\left(z_{1}, p, \xi\right) d z_{1}
$$

Note that the following formula holds for $t \in \mathbb{R}, \lambda>0, N \in \mathbb{N} \cup 0$ :

$$
e^{\frac{i t^{2}}{2 \lambda}}=\sum_{j=0}^{N} \frac{1}{j!}\left(\frac{i t^{2}}{2 \lambda}\right)^{j}+\frac{1}{N!}\left(\frac{i t^{2}}{2}\right)^{N+1} \int_{0}^{1 / \lambda} e^{\frac{i}{2} s t^{2}}\left(\frac{1}{\lambda}-s\right)^{N} d s
$$

Hence, the following equality is valid:

$$
\begin{equation*}
\int_{-\infty}^{+\infty} e^{\frac{i t^{2}}{2 \lambda}} \widehat{g}^{k}(t, p, \xi) d t=\sum_{j=0}^{N} \frac{(2 i \lambda)^{-j}}{j!} \int_{-\infty}^{+\infty}(i t)^{2 j} \widehat{g}^{k}(t, p, \xi) d t+r_{N}^{k}(\lambda, p, \xi) \tag{4.31}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \lambda>0$ and

$$
\begin{equation*}
r_{N}^{k}(\lambda, p, \xi)=\int_{-\infty}^{+\infty} \int_{0}^{1 / \lambda} \frac{\left(i t^{2}\right)^{N+1}}{N!2^{N+1}} e^{\frac{i}{2} s t^{2}}\left(\frac{1}{\lambda}-s\right)^{N} \widehat{g}^{k}(t, p, \xi) d s d t \tag{4.32}
\end{equation*}
$$

Taking into account formulas 4.16, 4.21, we obtain the formula

$$
\begin{equation*}
\int_{-\infty}^{+\infty}(i t)^{2 j} \widehat{g}^{k}(t, p, \xi) d t=2 \pi \frac{\partial^{2 j} g}{\partial z_{1}^{2 j}}(0, p, \xi), \quad j=0, \ldots, N \tag{4.33}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)$,

$$
\begin{gather*}
g\left(z_{1}, p, \xi\right)=f\left(x_{1}\left(z_{1}, p, \xi\right), x_{2}\left(z_{1}, p, \xi\right), \xi\right) \frac{\partial x_{1}}{\partial z_{1}}\left(z_{1}, p, \xi\right) \times  \tag{4.34}\\
\times p_{2}^{-1}\left(\partial_{2} q\left(p_{1} x_{1}\left(z_{1}, p, \xi\right), p_{2} x_{2}\left(z_{1}, p, \xi\right)\right)\right)^{-1}
\end{gather*}
$$

Note that functions $x_{1}\left(z_{1}, p, \xi\right)$ (resp. $\left.\widetilde{x}_{1}\left(\widetilde{z}_{1}, p, \xi\right)\right), g\left(z_{1}, p, \xi\right)$ at fixed $p \in P$, $\xi \in \Sigma$ are defined, at least, for $z_{1}$ (resp. $\widetilde{z}_{1}$ ) in a small neighborhood of $0 \in \mathbb{R}$ and in this neighborhood formulas 4.22 , 4.23) hold. This is a consequence of (4.11), 4.34).

Formulas 4.22, 4.23 imply that

$$
\begin{equation*}
\frac{\partial^{s} x_{1}}{\partial z_{1}^{s}}(0, p, \lambda \xi)=\lambda^{-\frac{s}{2}} \frac{\partial^{s} x_{1}}{\partial z_{1}^{s}}(0, p, \xi), \quad \lambda>0 \tag{4.35}
\end{equation*}
$$

where $p \in P, \xi \in \Sigma, s \in \mathbb{N} \cup 0$. Using (4.4), 4.34, 4.35 we obtain the identity

$$
\begin{equation*}
\frac{\partial^{2 j} g}{\partial z_{1}^{2 j}}(0, p, \lambda \xi)=\lambda^{m-j-\frac{1}{2}} \frac{\partial^{2 j} g}{\partial z_{1}^{2 j}}(0, p, \xi), \quad \lambda>0, j \in \mathbb{N} \cup 0, \tag{4.36}
\end{equation*}
$$

where $p \in P, \xi \in \Sigma$.
Define

$$
\begin{equation*}
a_{j}(p, \xi)=\frac{(2 \pi)^{\frac{1}{2}}}{(2 i)^{j} j!} e^{i \frac{\pi}{4}} \frac{\partial^{2 j} g}{\partial z_{1}^{2 j}}(0, p, \xi), \quad j=0, \ldots, N \tag{4.37}
\end{equation*}
$$

where $p \in P, \xi \in \Sigma$.
It follows from (4.10), (4.11), (4.34, 4.36), 4.37) that $a_{j} \in C^{\infty}(P \times \Sigma)$, $j=0, \ldots, N$, and that formulas 4.5), 4.7) hold.

Step 5: function $r_{N}^{k}(\lambda, p, \xi)$. Using formulas 4.20, 4.29, (4.30), 4.31), (4.37), we obtain the following equalities:

$$
\begin{align*}
& e^{-i S^{*}(p, \lambda \xi)} I_{1}^{k}(p, \lambda \xi)-\sum_{j=0}^{N} a_{j}(p, \lambda \xi)=(2 \pi)^{-\frac{1}{2}} e^{i \frac{\pi}{4}} r_{N}^{k}(1, p, \lambda \xi)  \tag{4.38}\\
& e^{-i S^{*}(p, \lambda \xi)} I_{1}^{k}(p, \lambda \xi)-\sum_{j=0}^{N} \lambda^{m-\frac{1}{2}-j} a_{j}(p, \xi)  \tag{4.39}\\
& =(2 \pi)^{-\frac{1}{2}} \lambda^{m-\frac{1}{2}} e^{i \frac{\pi}{4}} r_{N}^{k}(\lambda, p, \xi)
\end{align*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \lambda>0, N \in \mathbb{N} \cup 0$.
Formulas 4.5, 4.38), 4.39 imply that

$$
\begin{equation*}
r_{N}^{k}(1, p, \xi)=|\xi|^{m-\frac{1}{2}} r_{N}^{k}\left(|\xi|, p,|\xi|^{-1} \xi\right), \tag{4.40}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), N \in \mathbb{N} \cup 0$.
Note that at fixed $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), \alpha, \beta \in \mathbb{Z}_{+}^{2}$ function $D_{p}^{\alpha} D_{\xi}^{\beta} g(\cdot, p, \xi)$ belongs to $C_{c}^{\infty}(\mathbb{R})$. Hence, its Fourier transform belongs to the Schwartz space and there exists such constant $C_{4, k}^{\alpha, \beta}>0$ that

$$
\begin{equation*}
\int_{-\infty}^{+\infty}|t|^{2(N+1)}\left|D_{p}^{\alpha} D_{\xi}^{\beta} \widehat{g}\left(t, p,|\xi|^{-1} \xi\right)\right| d t \leq C_{4, k}^{\alpha, \beta}|\xi|^{-|\beta|} \tag{4.41}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi^{k}}\right),|\xi| \geq 1$.
It follows from formulas 4.32, 4.40, (4.41) that
$r_{N}^{k}(1, p, \xi) \in \widetilde{S}^{m-N-\frac{3}{2}}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right), \quad k=1, \ldots, N_{2}, N \in \mathbb{N} \cup 0$.
Step 6: final part of the proof. Using formula (4.17), taking into account that $f(\cdot, \xi)$ has the compact support at fixed $\xi \in \Sigma$ and integrating by parts in (4.19) we obtain

$$
\begin{equation*}
I_{2}^{k}(p, \xi) \in \widetilde{S}^{-\infty}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right), \quad k=1, \ldots, N_{2} \tag{4.43}
\end{equation*}
$$

Formulas 4.18, 4.28, 4.43) imply that

$$
\begin{equation*}
e^{-i S^{*}(p, \xi)} I(p, \xi) \in \widetilde{S}^{m-\frac{1}{2}}\left(\widetilde{P}\left(\widetilde{p}^{k}\right) \times \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right)\right), \quad k=1, \ldots, N_{2} . \tag{4.44}
\end{equation*}
$$

Finally, using (4.13), 4.44) we get

$$
e^{-i S^{*}(p, \xi)} I(p, \xi) \in S^{m-\frac{1}{2}}\left(P_{2 \epsilon} \times \Sigma_{2 \epsilon}\right)
$$

Since we can chose $\epsilon$ arbitrarily small, we obtain 4.3).
Denote

$$
r_{N}(p, \xi)=e^{-i S^{*}(p, \xi)} I(p, \xi)-\sum_{j=0}^{N} a_{j}(p, \xi)
$$

where $p \in P, \xi \in \Sigma, N \in \mathbb{N} \cup 0$. It follows from formulas 4.18, 4.38) that

$$
\begin{equation*}
r_{N}(p, \xi)=e^{-i S^{*}(p, \xi)} I_{2}^{k}(p, \xi)+(2 \pi)^{-\frac{1}{2}} e^{i \frac{\pi}{4}} r_{N}^{k}(1, p, \xi) \tag{4.45}
\end{equation*}
$$

where $p \in \widetilde{P}\left(\widetilde{p}^{k}\right), \xi \in \widetilde{\Sigma}\left(\widetilde{\xi}^{k}\right), k=1, \ldots, N_{2}$ and $N \in \mathbb{N} \cup 0$.
Using formulas (4.13), (4.42), 4.43), (4.45) we obtain

$$
r_{N}(p, \xi) \in S^{m-N-\frac{3}{2}}\left(P_{2 \epsilon} \times \Sigma_{2 \epsilon}\right)
$$

Since $\epsilon$ can be chosen arbitrarily small, we get (4.6).
Uniqueness of functions $a_{j}, j \in \mathbb{N} \cup 0$, follows from uniqueness of asymptotic expansion 4.6 of function $e^{-i S^{*}(p, \xi)} I(p, \xi)$. Lemma 4.1 is proved.

## 5 Proof of Lemma 3.1

In this section we prove Lemma 3.1. The proof is divided into five lemmas.
Lemma 5.1. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<\delta<\frac{1}{2}$ be fixed. Then $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a proper pseudo-differential operator.

Proof. Note that the following statements are true:

1. $C_{\alpha}$ doesn't contain points of types $(p, 0, x, \xi d x),(p, \eta d p, x, 0)$ and $C_{\alpha}^{t}$ doesn't contain points of types $(x, 0, p, \eta d p),(x, \xi d x, p, 0)$;
2. the support of $K_{\alpha, \delta}$ (resp. $K_{\alpha, \delta}^{*}$ ) is compact in $P \times X$ (resp. $X \times P$ ), where $K_{\alpha, \delta}$ is the Schwartz kernel of $R_{\alpha, \delta}$ defined in (3.6) and $K_{\alpha, \delta}^{*}$ is the Schwartz kernel of $R_{\alpha, \delta}^{*}$, given by the same formula (3.6) after changing $p$ to $x$ and vice versa;
3. submanifolds $C_{\alpha}^{t} \times C_{\alpha}$ and $T^{*} X \times \operatorname{diag}\left(T^{*} P \times T^{*} P\right) \times T^{*} X$ (where diag is defined in (3.37)) of $T^{*} X \times T^{*} P \times T^{*} P \times T^{*} X$ intersect transversally.

Statement 3 can be proved in the following way. Note that

$$
\begin{gathered}
\left(C_{\alpha}^{t} \times C_{\alpha}\right) \cap\left(T^{*} X \times \operatorname{diag}\left(T^{*} P \times T^{*} P\right) \times T^{*} X\right)= \\
=\left\{\left(x, \lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j}, p,-\lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j}, p,-\lambda \sum_{j=1}^{2} x_{j}^{\alpha} p_{j}^{\alpha-1} d p_{j},\right.\right. \\
\left.\left.x, \lambda \sum_{j=1}^{2} p_{j}^{\alpha} x_{j}^{\alpha-1} d x_{j}\right): x \in X, p \in P, q_{\alpha}\left(p_{1} x_{1}, p_{2} x_{2}\right)=1, \lambda \in \mathbb{R} \backslash 0\right\} .
\end{gathered}
$$

It follows from this formula and from formulas $(2.2),(2.4),(3.11)$ that

$$
\begin{gathered}
\operatorname{dim}\left(C_{\alpha}^{t} \times C_{\alpha}\right)=8, \quad \operatorname{dim}\left(T^{*} X \times \operatorname{diag}\left(T^{*} P \times T^{*} P\right) \times T^{*} X\right)=12 \\
\quad \operatorname{dim}\left(\left(C_{\alpha}^{t} \times C_{\alpha}\right) \cap\left(T^{*} X \times \operatorname{diag}\left(T^{*} P \times T^{*} P\right) \times T^{*} X\right)\right)=4
\end{gathered}
$$

Hence, the dimension of sum of tangent spaces of $C_{\alpha}^{t} \times C_{\alpha}$ and of $T^{*} X \times$ $\operatorname{diag}\left(T^{*} P \times T^{*} P\right) \times T^{*} X$ in points of interection of these submanifolds is equal to dimension of $T^{*} X \times T^{*} P \times T^{*} P \times T^{*} X$. Statement 3 is proved.

It follows from statements $1,2,3$ above that $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a Fourier integral operator associated with canonical relation $C_{\alpha}^{t} \circ C_{\alpha} \subset \operatorname{diag}\left(T^{*} X \times T^{*} X\right)$ (see (3.38) and Ref. [Du], Theorem 2.4.1). Hence, $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is a pseudo-differential operator.

Operator $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is proper since operators $R_{\alpha, \delta}^{*}$ and $R_{\alpha, \delta}$ have compactly supported Schwartz kernels.

The remaining part of this subsection is devoted to computation of principal symbol of $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$.

We need to introduce some notations. Note that at fixed $p=\left(p_{1}, p_{2}\right) \in P$ the curve $X_{\alpha, p}$ is the graph of function

$$
\begin{gathered}
x_{2}=x_{2}\left(x_{1}, p\right) \xlongequal{\text { def }} p_{2}^{-1}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{1 / \alpha} \\
0<x_{1}<p_{1}^{-1}, \quad \text { if } \alpha>0 \\
p_{1}^{-1}<x_{1}<+\infty, \quad \text { if } \alpha<0
\end{gathered}
$$

Similarly, at fixed $x=\left(x_{1}, x_{2}\right) \in X$ the curve $P_{\alpha, x}$ is the graph of function

$$
\begin{gathered}
p_{2}=p_{2}\left(p_{1}, x\right) \xlongequal{\text { def }} x_{2}^{-1}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{1 / \alpha} \\
0<p_{1}<x_{1}^{-1}, \quad \text { if } \alpha>0 \\
x_{1}^{-1}<p_{1}<+\infty, \quad \text { if } \alpha<0
\end{gathered}
$$

Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $\xi=\left(\xi_{1}, \xi_{2}\right) \in \Sigma \cup(-\Sigma)$ be fixed, $1 / \alpha+1 / \beta=1$. Define

$$
\begin{align*}
& S(x, \xi)=\xi_{1} x_{1}+\xi_{2} x_{2}, \quad x=\left(x_{1}, x_{2}\right) \in X  \tag{5.1}\\
& U(p, \xi)=\left(\operatorname{sgn} \xi_{1}\right)\left(\left|\xi_{1}\right|^{\beta} p_{1}^{-\beta}+\left|\xi_{2}\right|^{\beta} p_{2}^{-\beta}\right)^{1 / \beta}, \quad p=\left(p_{1}, p_{2}\right) \in P \tag{5.2}
\end{align*}
$$

Restricting functions $S(x, \xi)$ and $U(p, \xi)$ to $X_{\alpha, p}$ and $P_{\alpha, x}$, respectively, we obtain the following functions:

$$
\begin{aligned}
& \widetilde{S}\left(x_{1}, p, \xi\right) \xlongequal{\text { def }} S\left(\left(x_{1}, x_{2}\left(x_{1}, p\right)\right), \xi\right) \\
& \quad=\xi_{1} x_{1}+\xi_{2} p_{2}^{-1}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{1 / \alpha} \\
& \widetilde{U}\left(p_{1}, x, \xi\right) \xlongequal{\text { def }} U\left(\left(p_{1}, p_{2}\left(p_{1}, x\right)\right), \xi\right)
\end{aligned}
$$

Lemma 5.2. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $\xi=\left(\xi_{1}, \xi_{2}\right) \in \Sigma \cup(-\Sigma)$ be fixed. Let $1 / \alpha+1 / \beta=1$. Then:

1. at fixed $p=\left(p_{1}, p_{2}\right) \in P$ function $S(\cdot, \xi)$ has the unique local extremum $\left(x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)\right)$ on $X_{\alpha, p}$ and the following formulas are valid:

$$
\begin{gather*}
x_{j}^{*}(p, \xi)=|U(p, \xi)|^{1-\beta}\left|\xi_{j}\right|^{\beta-1} p_{j}^{-\beta}, \quad j=1,2  \tag{5.3}\\
S\left(\left(x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)\right), \xi\right)=U(x, \xi)  \tag{5.4}\\
\widetilde{S}_{x_{1} x_{1}}\left(x_{1}^{*}(p, \xi), p, \xi\right)=(1-\alpha)|U(p, \xi)|^{2 \beta-1}\left(p_{1} p_{2}\right)^{\beta} \xi_{1}\left|\xi_{1}\right|^{1-\beta}\left|\xi_{2}\right|^{-\beta} \tag{5.5}
\end{gather*}
$$

2. at fixed $x=\left(x_{1}, x_{2}\right) \in X$ function $U(\cdot, \xi)$ has the unique local extremum on $P_{\alpha, x}$ given by formula (3.10) and the following formulas are valid:

$$
\begin{gather*}
U\left(\left(p_{1}^{*}(x, \xi), p_{2}^{*}(x, \xi)\right), \xi\right)=S(x, \xi)  \tag{5.6}\\
\widetilde{U}_{p_{1} p_{1}}\left(p_{1}^{*}(x, \xi), x, \xi\right)=\alpha \beta|S(x, \xi)|^{1+\frac{2}{\alpha}} x_{1}^{1+\frac{2}{\beta}} x_{2}^{-1}\left|\xi_{1}\right|^{1-\frac{2}{\alpha}} \xi_{2}^{-1} \tag{5.7}
\end{gather*}
$$

Proof. 1. Derivatives of function $\widetilde{S}(\cdot, p, \xi)$ are given by the following formulas:

$$
\begin{align*}
\widetilde{S}_{x_{1}}\left(x_{1}, p, \xi\right) & =\xi_{1}-\xi_{2} p_{1}^{\alpha} p_{2}^{-1} x_{1}^{\alpha-1}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{\frac{1}{\alpha}-1}, \\
\widetilde{S}_{x_{1} x_{1}}\left(x_{1}, p, \xi\right) & =(1-\alpha) p_{2}^{-1} \xi_{2}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{\frac{1}{\alpha}-2} p_{1}^{\alpha} x_{1}^{\alpha-2} . \tag{5.8}
\end{align*}
$$

Solving equation $\widetilde{S}_{x_{1}}\left(x_{1}, p, \xi\right)=0$ at fixed $p \in P, \xi \in \Sigma \cup(-\Sigma)$ for $x_{1}$, we find the unique point $x_{1}^{*}(p, \xi)$ given by (5.3).

Formula (5.4) follows from (5.3) and formula (5.5) follows from (5.3), (5.8).
2. Derivatives of function $\widetilde{U}(\cdot, x, \xi)$ are given by the following formulas:

$$
\begin{gather*}
\widetilde{U}_{p_{1}}\left(p_{1}, x, \xi\right)=-\left(\operatorname{sgn} \xi_{1}\right) p_{1}^{\alpha-1}\left|\widetilde{U}\left(p_{1}, x, \xi\right)\right|^{1-\beta} \times \\
\times\left(\left|\xi_{1}\right|^{\beta} p_{1}^{-\alpha \beta}-\left|\xi_{2}\right|^{\beta} x_{1}^{\alpha} x_{2}^{\beta}\left(1-p_{1}^{\alpha} x_{1}^{\alpha}\right)^{-\beta}\right), \\
\widetilde{U}_{p_{1} p_{1}}\left(p_{1}, x, \xi\right)=(1-\beta)\left(\widetilde{U}\left(p_{1}, x, \xi\right)\right)^{-1}\left(\widetilde{U}_{p_{1}}\left(p_{1}, x, \xi\right)\right)^{2}+ \\
+\alpha \beta\left(\operatorname{sgn} \xi_{1}\right) p_{1}^{\alpha-2}\left|\widetilde{U}\left(p_{1}, x, \xi\right)\right|^{1-\beta} \times  \tag{5.9}\\
\times\left(\left|\xi_{1}\right|^{\beta} p_{1}^{-\alpha \beta}+\left|\xi_{2}\right|^{\beta} p_{2}^{-\alpha(1+\beta)} x_{1}^{2 \alpha} x_{2}^{-2 \alpha} p_{1}^{\alpha}\right) .
\end{gather*}
$$

Solving equation $\widetilde{U}_{p_{1}}\left(p_{1}, x, \xi\right)=0$ at fixed $x \in X, \xi \in \Sigma \cup(-\Sigma)$ for $p_{1}$ we obtain the unique point $p_{1}^{*}(x, \xi)$ given by $(3.10)$.

Formula (5.6) follows from (3.10) and formula (5.7) follows from formulas (3.10), 5.9).

Lemma 5.3. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<\delta<\frac{1}{2}$ be fixed. Then:

1. there exists $\delta^{\prime}=\delta^{\prime}(\alpha, \delta)>0$ such that for any $u \in C^{\infty}(X)$

$$
\left(R_{\alpha, \delta} e^{i S(\cdot, \xi)} u\right)(p) \in S^{-\infty}\left(P \times\left(\mathbb{R}^{2} \backslash\left(0 \cup \Sigma_{\delta^{\prime}} \cup-\Sigma_{\delta^{\prime}}\right)\right)\right),
$$

where $S$ is defined in (5.1), $\Sigma_{\delta^{\prime}}$ is defined in (3.8);
2. there exists $\delta^{\prime \prime}=\delta^{\prime \prime}(\alpha, \delta)>0$ such that for any $v \in C^{\infty}(P)$

$$
\left(R_{\alpha, \delta}^{*} e^{i U(\cdot, \xi)} v\right)(x) \in S^{-\infty}\left(X \times\left(\mathbb{R}^{2} \backslash\left(0 \cup \Sigma_{\delta^{\prime \prime}} \cup-\Sigma_{\delta^{\prime \prime}}\right)\right)\right),
$$

where $U$ is defined in (5.2), $\Sigma_{\delta^{\prime \prime}}$ is defined in (3.8).
Proof. 1. It follows from (3.5) that it is sufficient to show that there exists $\delta^{\prime}=\delta^{\prime}(\alpha, \delta)>0$ such that function $S(\cdot, \xi)$ defined in (5.1) at fixed $\xi \in \mathbb{R}^{2} \backslash(0 \cup$ $\left.\Sigma_{\delta^{\prime}} \cup-\Sigma_{\delta^{\prime}}\right)$ doesn't have local extrema on $X_{\alpha, p} \cap \operatorname{supp} æ_{\alpha, \delta}$ for all $p \in P$.

Note that $S(\cdot, \xi)$ at fixed $\xi \in \mathbb{R}^{2} \backslash(0 \cup \Sigma \cup-\Sigma)$ doesn't have local extrema on curve $X_{\alpha, p}$ for all $p \in P$.

It follows from definition (3.3) that

$$
\begin{equation*}
æ_{\alpha, \delta}(p, x)=0, \text { if } p \notin P_{\delta} \text { or } x \notin X_{\delta}, \tag{5.10}
\end{equation*}
$$

where $X_{\delta}, P_{\delta}$ are defined in formula (3.14).

Using Lemma 5.2 (1) we obtain that at fixed $p \in P, \xi \in \Sigma \cup(-\Sigma)$ function $S(\cdot, \xi)$ has the unique local extremum $\left(x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)\right)$ on $X_{\alpha, p}$ given by formula (5.3). It follows from formula (5.3) that there exists such $\delta^{\prime}=\delta^{\prime}(\alpha, \delta)>0$ that for any $p \in P_{\delta / 2}, \xi=\left(\xi_{1}, \xi_{2}\right) \in \Sigma \cup(-\Sigma)$ such that $\xi_{1} / \xi_{2} \leq \delta^{\prime}$ or $\xi_{2} / \xi_{1} \leq \delta^{\prime}$, we have $x^{*}(p, \xi) \notin X_{\delta / 2}$.

Hence, using (5.10) we obtain that if $p \in P, \xi \in\left(\Sigma \backslash \Sigma_{\delta}\right) \cup\left((-\Sigma) \backslash\left(-\Sigma_{\delta}\right)\right)$, then $x^{*}(p, \xi) \notin X_{\alpha, p} \cap \operatorname{supp} æ_{\alpha, \delta}$. The first statement of Lemma 5.3 is proved.
2. The second statement can be proved in a similar way.

Lemma 5.4. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<\delta<\frac{1}{2}$ be fixed. Let $1 / \alpha+1 / \beta=1$. Then there exist the unique functions $a_{j} \in C^{\infty}\left(P \times \mathbb{R}^{2} \backslash 0\right), j \in \mathbb{N} \cup 0$, satisfying

$$
\begin{equation*}
a_{j}(p, \lambda \xi)=\lambda^{-j-\frac{1}{2}} a_{j}(p, \xi), \quad p \in P, \xi \in \mathbb{R}^{2} \backslash 0, \lambda>0 \tag{5.11}
\end{equation*}
$$

and such that the following formula holds:

$$
\begin{equation*}
e^{-i U(p, \xi)}\left(R_{\alpha, \delta} e^{i S(\cdot, \xi)}\right)(p)-\sum_{j=0}^{N} a_{j}(p, \xi) \in S^{-N-\frac{3}{2}}\left(P \times \mathbb{R}^{2} \backslash 0\right) \tag{5.12}
\end{equation*}
$$

where $N \in \mathbb{N} \cup 0, S$ is defined in (5.1), $U$ is defined in (5.2).
Furthermore, the following formula holds:

$$
\begin{gather*}
a_{0}(p, \xi)=(2 \pi)^{\frac{1}{2}}|1-\alpha|^{-\frac{1}{2}} \exp (i(\pi / 4) \cdot \operatorname{sgn}(1-\alpha)) \times \\
\times\left(p_{1} p_{2}\right)^{-\frac{\beta}{2}}\left|\xi_{1} \xi_{2}\right|^{\frac{\beta}{2}-1}|U(p, \xi)|^{\frac{3}{2}-\beta} æ_{\alpha, \delta}\left(p,\left(x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)\right)\right), \tag{5.13}
\end{gather*}
$$

where $p \in P, \xi \in \Sigma \cup(-\Sigma) ; x_{1}^{*}(p, \xi), x_{2}^{*}(p, \xi)$ are defined in 5.3.
Proof. We will prove this lemma using Lemma 4.1 of Section 4.
Note that function $q_{\alpha}$ satisfies assumptions Q1, Q2 of Remark 2.2 and function $S$ defined in (5.1) satisfies assumption S1 of Section 4 with $\Sigma=\Sigma$ and $\widehat{\Sigma}=-\Sigma$. It follows from Lemma 5.2 (1) that functions $q_{\alpha}, S$ satisfy assumptions QS1, QS2 of Section 4 .

Using formulas (5.3), 5.5 of Lemma 5.2 we also obtain the following equality:

$$
\begin{gather*}
\left|\widetilde{S}_{x_{1} x_{1}}\left(x_{1}^{*}(p, \xi), p, \xi\right)\right|^{\frac{1}{2}} \partial_{2} q_{\alpha}\left(p_{1} x_{1}^{*}(p, \xi), p_{2} x_{2}^{*}(p, \xi)\right)= \\
\quad=|1-\alpha|^{\frac{1}{2}}\left(p_{1} p_{2}\right)^{\frac{\beta}{2}}\left|\xi_{1} \xi_{2}\right|^{1-\frac{\beta}{2}}|U(p, \xi)|^{\beta-\frac{3}{2}} \tag{5.14}
\end{gather*}
$$

where $p \in P, \xi \in \Sigma \cup(-\Sigma)$.
Now Lemma 5.4 follows from Lemmas 4.15 .3 (1) if we take into account that asymptotic expansions are unique.

The following lemma finishes the proof of Lemma 3.1.
Lemma 5.5. Let $\alpha \in \mathbb{R} \backslash\{0,1\}$ and $0<\delta<\frac{1}{2}$ be fixed. Let $1 / \alpha+1 / \beta=1$. Then there exist the unique functions $b_{m} \in C^{\infty}\left(X \times \mathbb{R}^{2} \backslash 0\right), m \in \mathbb{N} \cup 0$, satisfying

$$
\begin{equation*}
b_{m}(x, \lambda \xi)=\lambda^{-m-1} b_{m}(x, \xi), \quad x \in X, \xi \in \mathbb{R}^{2} \backslash 0, \lambda>0 \tag{5.15}
\end{equation*}
$$

and such that the following formula is valid:

$$
\begin{equation*}
e^{-i \xi x}\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} e^{i S(\cdot, \xi)}\right)(x)-\sum_{m=0}^{N} b_{m}(x, \xi) \in S^{-N-2}\left(X \times \mathbb{R}^{2} \backslash 0\right) \tag{5.16}
\end{equation*}
$$

where $N \in \mathbb{N} \cup 0, S$ is defined in 5.1.

## Furthermore,

$$
\begin{align*}
& b_{0}(x, \xi)=2 \pi|\alpha|^{-1} \exp \left(i(\pi / 4) \cdot \operatorname{sgn}(1-\alpha) \cdot\left(1-\operatorname{sgn} \xi_{1}\right)\right) \times \\
& \quad \times\left(x_{1} x_{2}\right)^{-\frac{1}{\beta}}\left|\xi_{1} \xi_{2}\right|^{-\frac{1}{\beta}}|\xi x|^{1-\frac{2}{\alpha}} æ_{\alpha, \delta}^{2}\left(\left(p_{1}^{*}(x, \xi), p_{2}^{*}(x, \xi)\right), x\right), \tag{5.17}
\end{align*}
$$

where $x \in X, \xi \in \Sigma \cup(-\Sigma) ; p_{1}^{*}(x, \xi), p_{2}^{*}(x, \xi)$ are defined in 3.10.
Besides, there exists $\epsilon=\epsilon(\alpha, \delta)>0$ such that $b_{m}(x, \xi)=0$ for $x \in X$, $\xi \in \mathbb{R}^{2} \backslash\left(0 \cup \Sigma_{\epsilon} \cup-\Sigma_{\epsilon}\right), m \geq 0$, where $\Sigma_{\epsilon}$ is defined by formula (3.8).

Proof. Using Lemma 5.4 we obtain the expansion:

$$
\begin{equation*}
e^{-i U(p, \xi)}\left(R_{\alpha, \delta} e^{i S(\cdot, \xi)}\right)(p)=\sum_{j=0}^{N} a_{j}(p, \xi)+r_{N}(p, \xi) \tag{5.18}
\end{equation*}
$$

where $p \in P, \xi \in \mathbb{R}^{2} \backslash 0, r_{N} \in S^{-N-\frac{3}{2}}\left(P \times \mathbb{R}^{2} \backslash 0\right), N \in \mathbb{N} \cup 0$.
Note that function $q_{\alpha}$ satisfies assumptions Q1, Q2 of Remark 2.2 and function $U$ defined in (5.2) satisfies assumption S1 of Section 4 with $\Sigma=\Sigma$ and $\widehat{\Sigma}=-\Sigma$. It follows from Lemma 5.2 (2) that functions $q_{\alpha}, U$ also satisfy assumptions QS1, QS2 of Section 4 .

Using formulas (3.10), (5.7) we also obtain the following formula:

$$
\begin{gather*}
\left|\widetilde{U}_{p_{1} p_{1}}\left(p_{1}^{*}(x, \xi), x, \xi\right)\right|^{\frac{1}{2}} \partial_{2} q_{\alpha}\left(p_{1}^{*}(x, \xi) x_{1}, p_{2}^{*}(x, \xi) x_{2}\right)= \\
=|\alpha \beta|^{\frac{1}{2}}\left(x_{1} x_{2}\right)^{\frac{1}{2}+\frac{1}{\beta}}\left|\xi_{1} \xi_{2}\right|^{\frac{1}{2}-\frac{1}{\alpha}}|\xi x|^{\frac{2}{\alpha}-\frac{1}{2}}, \tag{5.19}
\end{gather*}
$$

where $x \in X, \xi \in \Sigma \cup(-\Sigma) ; p_{1}^{*}(x, \xi), p_{2}^{*}(x, \xi)$ are defined in (3.10).
Using Lemmas 4.1 5.3 (2) we obtain that there exist the unique functions $b_{j, k} \in C^{\infty}\left(X \times \mathbb{R}^{2} \backslash 0\right), j, k \in \mathbb{N} \cup 0$, satisfying

$$
\begin{equation*}
b_{j, k}(x, \lambda \xi)=\lambda^{-j-k-1} b_{j, k}(x, \xi), \quad x \in X, \xi \in \mathbb{R}^{2} \backslash 0, \lambda>0 \tag{5.20}
\end{equation*}
$$

and such that the following formula holds:

$$
\begin{equation*}
e^{-i \xi x} R_{\alpha, \delta}^{*}\left(e^{i U(\cdot, \xi)} a_{j}(\cdot, \xi)\right)(x)-\sum_{k=0}^{M} b_{j, k}(x, \xi) \in S^{-j-M-2}\left(X \times \mathbb{R}^{2} \backslash 0\right), \tag{5.21}
\end{equation*}
$$

where $j, M \in \mathbb{N} \cup 0$. Furthermore, it follows from Lemma 5.3 (2) that there exists $\epsilon=\delta^{\prime \prime}(\alpha, \delta)>0$ such that $b_{j, k}(x, \xi)=0$ if $x \in X, \xi \in \mathbb{R}^{d} \backslash\left(0 \cup \Sigma_{\epsilon} \cup-\Sigma_{\epsilon}\right)$ for all $j, k \in \mathbb{N} \cup 0$.

Besides, denoting $b_{0}=b_{0,0}$ we obtain (5.17).
Taking into account that $r_{N} \in S^{-N-\frac{3}{2}}\left(P \times \mathbb{R}^{2} \backslash 0\right)$ and using Lemmas 4.1. 5.3 (2), we obtain that

$$
\begin{equation*}
e^{-i \xi x} R_{\alpha, \delta}^{*}\left(e^{i U(\cdot, \xi)} r_{N}(\cdot, \xi)\right)(x) \in S^{-N-2}\left(X \times \mathbb{R}^{2} \backslash 0\right) \tag{5.22}
\end{equation*}
$$

Denote $b_{m}=\sum_{j+k=m} b_{j, k}, m \in \mathbb{N}$. Now Lemma 5.5 follows from (5.18), (5.20), (5.21), (5.22) if we take into account that asymptotic expansions are unique.

Lemmas 5.1, 5.5 imply the statement of Lemma 3.1 if we take into account that the full symbol of $R_{\alpha, \delta}^{*} R_{\alpha, \delta}$ is given by formula

$$
\sigma_{\alpha, \delta}(x, \xi d x)=e^{-i \xi x}\left(R_{\alpha, \delta}^{*} R_{\alpha, \delta} e^{i S(\cdot, \xi)}\right)(x)
$$

and the principal symbol $\sigma_{\alpha, \delta}^{P}(x, \xi d x)$ is the term of top degree in the asymptotic expansion of $\sigma_{\alpha, \delta}(x, \xi d x)$,

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