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On diffeomorphism extension

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Abstract

We state and prove a result concerning the fact that a diffeomorphism can be "extended" in such a way that its image is \mathbb{R}^n .

Before stating the theorem, we introduce the following property :

Definition 1 (Conditions (C)) An open subset E of \mathbb{R}^m is said to verify condition (C) if there exist a C^1 function $\kappa : \mathbb{R}^m \to \mathbb{R}$, a bounded C^1 vector field χ , and a closed set K_0 contained in E such that:

- 1. $E = \{z \in \mathbb{R}^n, \kappa(z) < 0\}$
- 2. K_0 is globally attractive for χ
- 3. we have the following transversality assumption:

$$\frac{\partial \kappa}{\partial z}(z)\chi(z) < 0 \qquad \forall z \in \mathbb{R}^m : \ \kappa(z) = 0.$$

We now state the main theorem of this note :

Theorem 1 (Image extension) Let $\psi: \mathcal{D} \subset \mathbb{R}^m \to \psi(\mathcal{D}) \subset \mathbb{R}^m$ be a diffeomorphism. If $\psi(\mathcal{D})$ verifies condition (\mathcal{C}) or \mathcal{D} is C^2 -diffeomorphic to \mathbb{R}^m and ψ is C^2 , then for any compact set K in \mathcal{D} there exists a diffeomorphism $\psi_e : \mathcal{D} \to \mathbb{R}^m$ satisfying :

 $\psi_e(\mathcal{D}) = \mathbb{R}^m$, $\psi_e(z) = \psi(z) \quad \forall z \in K.$

The proof of this theorem, given in Section 2, relies on two preliminary lemmas presented in Section 1.

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[†]V. Andrieu vincent.andrieu@gmail.com is with LAGEP, CNRS, CPE, Université Lyon 1, France ¹If not replace χ by $\frac{\chi}{\sqrt{1+|\chi|^2}}$

1 Technical lemmas

1.1 Construction of a diffeomorphism from an open set to \mathbb{R}^m

In this section, we give sufficient conditions to build a diffeomorphism from \mathbb{R}^m to an open subset E which leaves $E_{\varepsilon} \subset E$ unchanged. This construction is made explicit in the proof.

The complementary, closure, interior and boundary of a set S are denoted S^c , \overline{S} , $\overset{\circ}{S}$ and ∂S , respectively, with $\partial S = \overline{S} \setminus \overset{\circ}{S}$.

The Hausdorff distance d_H between two sets A and B is defined by :

$$d_H(A,B) = \max\left\{\sup_{x_A \in A} \inf_{x_B \in B} |x_A - x_B|, \sup_{x \in A} \inf_{x_B \in B} |x_A - x_B|\right\}$$

With Z(z,t) we denote the (unique) solution, at time t, to $\dot{z} = \chi(z)$ going trough z at time 0.

Lemma 1 Let E be an open strict subset of \mathbb{R}^m verifying (\mathcal{C}) , with a C^s vector field χ . Then, for any strictly positive real number ε , there exists a C^s -diffeomorphism ϕ : $\mathbb{R}^m \to E$, such that, with

$$\Sigma = \bigcup_{t \in [0,\varepsilon]} Z(\partial E, t) \; ,$$

we have $\phi(z) = z$ for all $z \in E_{\varepsilon} = E \cap \Sigma^{\mathsf{c}}$ and $d_H(\partial E_{\varepsilon}, \partial E) \leq \varepsilon \sup_z |\chi(z)|$.

Proof: We start by establishing some properties.

- E is forward invariant by χ . This is a direct consequence of points 1 and 3 of the condition (\mathcal{C}) .

 $-\Sigma$ is closed. Take a sequence (z_k) of points in Σ converging to z^* . By definition, there exists a sequence (t_k) , such that :

$$t_k \in [0, \varepsilon]$$
 and $Z(z_k, -t_k) \in \partial E$ $\forall k \in \mathbb{N}$.

Since $[0, \varepsilon]$ is compact, one can extract a subsequence $(t_{\sigma(k)})$ converging to t^* in $[0, \varepsilon]$, and by continuity of the function $(z, t) \mapsto Z(z, -t)$, $(Z(z_{\sigma(k)}, t_{\sigma(k)}))$ tends to $Z(z^*, -t^*)$ which is in ∂E , since ∂E is closed. Finally, because t^* is in $[0, \varepsilon]$, z^* is in Σ by definition.

 $-\Sigma$ is contained in cl(E). Since, E is forward invariant by χ , and so is cl(E) (see [4, Theorem 16.3]). This implies

$$\partial E \ \subset \ \Sigma = \bigcup_{t \in [0,\varepsilon]} Z(\partial E,t) \ \subset \ \mathsf{cl}(E) \ = \ E \cup \partial E \ .$$

At this point, it is useful to note that, because Σ is a closed subset of the open set E, we have $\Sigma \cap E = \Sigma \setminus \partial E$. This implies :

$$E \setminus E_{\varepsilon} = (E_{\varepsilon})^{\mathsf{c}} \cap E = (E^{\mathsf{c}} \cup \Sigma) \cap E = \Sigma \cap E = \Sigma \setminus \partial E, \tag{1}$$

and $E = E_{\varepsilon} \cup (\Sigma \setminus \partial E)$.

With all these properties at hand, we define now two functions t_z and θ_z . The assumptions of global attractiveness of the closed set K_0 contained in E open, of transversality of χ to ∂E ,

and the property of forward-invariance of E, imply that, for all z in E^{c} , there exists a unique non negative real number t_{z} satisfying:

$$\kappa(Z(z,t_z)) = 0 \iff Z(z,t_z) \in \partial E.$$

The same arguments in reverse time allow us to see that, for all z in Σ , t_z exists, is unique and in $[-\varepsilon, 0]$. This way, the function $z \to t_z$ is defined on $(E_{\varepsilon})^{\mathsf{c}}$. Next, for all z in $(E_{\varepsilon})^{\mathsf{c}}$, we define :

$$\theta_z = Z(z, t_z).$$

Thanks to the transversality assumption, the Implicit Function Theorem implies the functions $z \mapsto t_z$ and $z \mapsto \theta_z$ are C^s on $(E_{\varepsilon})^{\mathsf{c}}$.

Remark 1 κ having constant rank 1 in a neighborhood of ∂E , this set is a closed, regular submanifold of \mathbb{R}^m . The arguments above show that $z \mapsto (\theta_z, t_z)$ is a diffeomorphism between E^{c} and $\partial E \times [0, +\infty[$. Since ∂E is a deformation retract of E^{c} and the open unit ball is diffeomorphic to \mathbb{R}^m [?], if E were bounded, E^{c} could be seen as a h-cobordism between ∂E and the unit sphere \mathbb{S}^{m-1} and t_z as a Morse function with no critical point in E^{c} . See [5] for instance.

Now we evaluate t_z for z in $\partial \Sigma$. Let z be arbitrary in $\partial \Sigma$ and therefore in Σ which is closed. Assume its corresponding t_z is in $] - \varepsilon, 0[$. The Implicit Function Theorem shows that $z \mapsto t_z$ and $z \mapsto \theta_z$ are defined and continuous on a neighborhood of z. Therefore, there exists a strictly positive real number r satisfying

$$\forall y \in \mathcal{B}_r(z), \exists t_y \in] - \varepsilon, 0[: Z(y, t_y) \in \partial E.$$

This implies that the neighborhood $\mathcal{B}_r(z)$ of z is contained in Σ , in contradiction with the fact that z is on the boundary of Σ .

This shows that, for all z in $\partial \Sigma$, t_z is either 0 or $-\varepsilon$. We write this as $\partial \Sigma = \partial E \cup (\partial \Sigma)_i$, with the notation $(\partial \Sigma)_i = \{z \in \Sigma : t_z = -\varepsilon\}$.

Now we want to prove $\partial E_{\varepsilon} \subset (\partial \Sigma)_i$. To obtain this result, we start by showing :

$$\partial E_{\varepsilon} \cap \partial E = \emptyset \quad \text{and} \quad \partial E_{\varepsilon} \subset \partial \Sigma \;.$$

$$\tag{2}$$

Suppose the existence of z in $\partial E_{\varepsilon} \cap \partial E$. z being in ∂E , its corresponding t_z is 0. By the Implicit Function Theorem, there exists a strictly positive real number r such that,

$$\forall y \in \mathcal{B}_r(z) , \exists t_y \in \left] - \frac{\varepsilon}{2}, \frac{\varepsilon}{2} \right[: Z(y, t_y) \in \partial E$$

But, by definition, any y, for which there exists t_y in $\left[\frac{-\varepsilon}{2}, 0\right]$, is in Σ . If instead t_y is strictly positive, then necessarily y is in E^{c} , because E is forward-invariant by χ and a solution starting in E cannot reach ∂E in positive finite time. We have obtained : $\mathcal{B}_r(z) \subset \Sigma \cup E^{\mathsf{c}} = (E_{\varepsilon})^{\mathsf{c}}$. $\mathcal{B}_r(z)$ being a neighborhood of z, this contradicts the fact that z is in the boundary of E_{ε} .

At this point, we have proved that $\partial E_{\varepsilon} \cap \partial E = \emptyset$, and, because E_{ε} is contained in E, this implies $\partial E_{\varepsilon} \subset E$. With this, (2) will be established by proving that we have $\partial E_{\varepsilon} \subset \partial \Sigma$. Let z be arbitrary in ∂E_{ε} and therefore in E which is open. There exists a strictly positive real number r such that we have :

$$\mathcal{B}_r(z) \cap E_{\varepsilon} = \mathcal{B}_r(z) \cap (E \cap \Sigma^{\mathsf{c}}) \neq \emptyset , \ \mathcal{B}_r(z) \cap E_{\varepsilon}^{\mathsf{c}} = \mathcal{B}_r(z) \cap (E^{\mathsf{c}} \cup \Sigma) \neq \emptyset , \ \mathcal{B}_r(z) \subset E .$$

This implies $\mathcal{B}_r(z) \cap \Sigma^c \neq \emptyset$ and $\mathcal{B}_r(z) \cap \Sigma \neq \emptyset$ and therefore that z is in $\partial \Sigma$.

We have established $\partial E_{\varepsilon} \cap \partial E = \emptyset$, $\partial E_{\varepsilon} \subset \partial \Sigma$ and $\partial \Sigma = \partial E \cup (\partial \Sigma)_i$. This does imply :

$$\partial E_{\varepsilon} \subset (\partial \Sigma)_i = \{ z \in E : t_z = -\varepsilon \} .$$
 (3)

This allows us to extend by continuity the definition of t_z to \mathbb{R}^m by letting $t_z = -\varepsilon$ for all $z \in E_{\varepsilon}$.

Thanks to all these preparatory steps, we are finally ready to define a function $\phi : \mathbb{R}^m \to E$ as:

$$\phi(z) = \begin{cases} Z(z, t_z + \nu(t_z)), & \text{if } z \in (E_{\varepsilon})^c , \\ z, & \text{if } z \in E_{\varepsilon} , \end{cases}$$
(4)

where ν is an arbitrary C^s and strictly decreasing function defined on \mathbb{R} satisfying:

$$\nu(t) = -t \quad \forall t \leq -\varepsilon \quad , \qquad \lim_{t \to +\infty} \nu(t) = 0$$

The image of ϕ is contained in E since we have $E_{\varepsilon} \subset E$ and :

$$\begin{array}{rcl} t_z \ + \ \nu(t_z) \ > \ t_z & \forall z \in E_{\varepsilon}^{\mathsf{c}} \ , \\ & Z(z,t_z) \ \in \ \partial E \ , \\ Z(z,t) \ \in \ E & \forall (z,t) \in \partial E \times \mathbb{R}_{>0} \ . \end{array}$$

The continuity of the functions $(z,t) \in \mathbb{R}^m \times \mathbb{R} \mapsto Z(z,t) \in \mathbb{R}$ and $z \in E_{\varepsilon}^{\mathsf{c}} \mapsto t_z \in [-\varepsilon, +\infty[$ implies that this function ϕ is continuous at least on $\mathbb{R}^m \setminus \partial E_{\varepsilon}$. Also, for any z in ∂E_{ε} , t_z is defined and equal to $-\varepsilon$ (see (3)). So, for any strictly positive real number η , there exists a real number r such that :

$$\begin{aligned} |t_y + \varepsilon| &\leq \eta & \forall y \in \mathcal{B}_r(z) ,\\ \nu(t_y) + \varepsilon &\leq \eta & \forall y \in \mathcal{B}_r(z) ,\\ \phi(y) &= y & \forall y \in \mathcal{B}_r(z) \cap E_\varepsilon ,\\ \phi(y) &= Z(y, t_y + \nu(t_y)) & \forall y \in \mathcal{B}_r(z) \cap E_\varepsilon^c . \end{aligned}$$

Since we have :

$$\phi(z) = Z(z, t_z + \nu(t_z)) = Z(z, -\varepsilon + \nu(-\varepsilon)) = z ,$$

we conclude that ϕ is also continuous at z.

By differentiating, we obtain :

- at any interior point z of $(E_{\varepsilon})^{\mathsf{c}}$

$$\frac{\partial \phi}{\partial z}(z) = \frac{\partial Z}{\partial z}(z, t_z + \nu(t_z)) + \chi(Z(z, t_z + \nu(t_z)))\frac{\partial t_z}{\partial z}(z)(1 + \nu'(t_z)) = \frac{\partial \phi}{\partial z}(z)(1 + \nu'(t_z))$$

- at any z in E_{ε} (which is open) $\frac{\partial \phi}{\partial z}(z) = I$. Also, for any z in ∂E_{ε} , we have :

$$\frac{\partial Z}{\partial z}(z,t_z+\nu(t_z)) + \chi(Z(z,t_z+\nu(t_z)))\frac{\partial t_z}{\partial z}(z)(1+\nu'(t_z)) = \frac{\partial Z}{\partial z}(z,0) + \chi(Z(z,0))\frac{\partial t_z}{\partial z}(z)(1-1) ,$$

= I.

This implies that ϕ is C^1 on \mathbb{R}^m .

We now show that ϕ is invertible. Let y be arbitrary in $E \cap E_{\varepsilon}^{\mathsf{c}} = E \cap \Sigma$. There exists t_y in $[-\varepsilon, 0]$. The function ν being strictly monotonic, $\nu^{-1}(t_y)$ exists and is in $[-\varepsilon, +\infty]$. This allows us to define properly ϕ^{-1} as :

$$\phi^{-1}(y) = \begin{cases} Z(y, t_y - \nu^{-1}(-t_y)), & \text{if } y \in E \setminus E_{\varepsilon} \\ y, & \text{if } y \in E_{\varepsilon} \end{cases}$$
(5)

This function is an inverse of ϕ as can be seen be reverting the flow induced by χ when needed. Also, with the same arguments as before, we can prove that it is C^1 .

This implies that ϕ is a diffeomorphism from \mathbb{R}^m to E.

Besides, the functions $z \mapsto Z(z,t)$ for t > 0, $z \mapsto t_z$ and ν being C^s , ϕ is C^s at any interior point of $(E_{\varepsilon})^{\mathsf{c}}$. By continuity of $\nu^{(r)}$ for $r \leq s$, it can be verified that ϕ is also C^s on the boundary ∂E_{ε} . So, ϕ is a C^s -diffeomorphism from \mathbb{R}^m to E.

Finally, we note that, for any point z_{ε} in ∂E_{ε} , there exists a point z in ∂E satisfying :

$$|z_{\varepsilon} - z| = \left| \int_{0}^{\varepsilon} \chi(Z(z, s)) ds \right| \leq \varepsilon \sup_{\zeta} |\chi(\zeta)|$$

And conversely, for any z in ∂E , there exist z_{ε} in ∂E_{ε} satisfying :

$$|z_{\varepsilon} - z| = \left| \int_{0}^{\varepsilon} \chi(Z(z,s)) ds \right| \leq \varepsilon \sup_{\zeta} |\chi(\zeta)|$$

It follows that

$$d_H(\partial E_{\varepsilon}, \partial E) \leq \varepsilon \sup_{\zeta} |\chi(\zeta)| \tag{6}$$

and ε may be chosen as small as needed.

Two direct consequences of Lemma 1 are :

Corollary 1 Let $\psi : E \to \psi(E)$ be a diffeomorphism, with E satisfying (C). For any ε strictly positive, there exist an open subset E_{ε} of E and a diffeomorphism $\psi_e \colon \mathbb{R}^m \to \psi(E)$ satisfying :

$$d_H(\partial E_{\varepsilon}, \partial E) \leq \varepsilon ,$$

$$\psi_e(z) = \psi(z) \quad \forall z \in E_{\varepsilon}$$

Proof: With ϕ given by Lemma 1, we pick $\psi_e = \psi \circ \phi$.

Corollary 2 Let $\psi : E \to \psi(E)$ be a diffeomorphism, with $\psi(E)$ satisfying (C). For any ε strictly positive, there exist an open subset $\psi(E)_{\varepsilon}$ of $\psi(E)$ and a diffeomorphism $\psi_e \colon E \to \mathbb{R}^n$ satisfying :

$$d_H(\partial \left(\psi(E)_{\varepsilon}\right), \partial \psi(E)) \leq \varepsilon ,$$

$$\psi_e(z) = \psi(z) \quad \forall z \in \psi^{-1} \left(\psi(E)_{\varepsilon}\right) .$$

Proof: With ϕ given by Lemma 1 from \mathbb{R}^n to $\psi(E)$, we pick $\psi_e = \phi^{-1} \circ \psi$.

Remark 2 In Corollary 2, ψ being a diffeomorphism on an open set E, we know that the image of any compact subset K of E is a compact subset of $\psi(E)$ which is also open by Brouwer's invariance theorem. Therefore, with (6), we can find ε such that $\psi(K) \subset (\psi(E))_{\varepsilon}$ and thus, $\psi_e(z) = \psi(z)$ for all x in K.

1.2 Diffeomorphism extension from a ball

Let R > 0. We denote \mathcal{B}_R the open ball in \mathbb{R}^n of radius R and centered at 0.

Lemma 2 Consider a C^2 diffeomorphism $\psi : \mathcal{B}_R \to \psi(\mathcal{B}_R) \subset \mathbb{R}^n$. For any ε strictly positive, there exists a diffeomorphism $\psi_e : \mathbb{R}^n \to \mathbb{R}^n$ such that $\psi_e(x) = \psi(x)$ for all x in $cl(\mathcal{B}_{R-\varepsilon})$.

Proof: Without loss of generality we may assume that $\psi(0) = 0$. Consider the mapping $\varphi : \mathcal{B}_R \times [0,1] \to \mathbb{R}^n$ defined as

$$\varphi(x,t) = \left(\frac{\partial\psi}{\partial x}(0)\right)^{-1} \frac{\psi(xt)}{t} , \ \varphi(x,0) = x .$$

Note that for all t the mapping $\varphi_t(x) = \varphi(x, t)$ is a diffeomorphism from \mathcal{B}_R toward $\varphi_t(\mathcal{B}_R)$. Indeed, given x_a and x_b such that $\varphi(x_a, t) = \varphi(x_b, t)$ it yields $\psi(x_a t) = \psi(x_b t)$. Note that the couple $(x_a t, x_b t)$ is in \mathcal{B}_R . The mapping ψ being injective on this set, it yields $x_a = x_b$. Moreover,

$$\frac{\partial \varphi_t}{\partial x}(x) = \left(\frac{\partial \psi}{\partial x}(0)\right)^{-1} \frac{\partial \psi}{\partial x}(xt) , \ t > 0 \ , \ \frac{\partial \varphi_0}{\partial x}(x) = \mathrm{Id}$$

Hence, this mapping is full rank in \mathcal{B}_R . Consequently, for all t in [0, 1], this mapping is a diffeomorphism \mathcal{B}_R toward $\varphi_t(\mathcal{B}_R)$. Consequently, for all t in [0, 1] we can introduce φ_t^{-1} its inverse map.

Note moreover that

$$\overline{\varphi(x,t)} = \frac{\partial \varphi}{\partial t}(x,t) = \left(\frac{\partial \psi}{\partial x}(0)\right)^{-1} \rho(x,t)$$

where ρ is the function given as

$$\rho(x,t) = \frac{1}{t^2} \left[\frac{\partial \psi}{\partial x}(xt)xt - \psi(xt) \right] , \ \rho(x,0) = \frac{1}{2}x' \left(\frac{\partial^2 \psi}{\partial x \partial x}(0) \right) x$$

The mapping ψ being C^2 , and $\psi(0) = 0$ it yields,

$$\psi(xt) = \frac{\partial \psi}{\partial x}(0)xt + x'\left(\frac{\partial^2 \psi}{\partial x \partial x}(0)\right)x\frac{t^2}{2} + o(t^2)$$

and,

$$\lim_{t \to 0} \frac{\frac{\partial \psi}{\partial x}(xt)x - \frac{\partial \psi}{\partial x}(0)x}{t} = x' \left(\frac{\partial^2 \psi}{\partial x \partial x}(0)\right) x$$

Hence, the function ρ is well defined and locally Lipschitz. Consequently, $\varphi(x, t)$ is (the unique) solution of the time varying system defined for (z, t) in $\varphi_t(\mathcal{B}_R) \times [0, 1]$ as

$$\dot{z} = \left(\frac{\partial \psi}{\partial x}(0)\right)^{-1} \rho\left(\varphi_t^{-1}(z), t\right)$$

This time varying system can be extended to \mathbb{R}^n as

$$\dot{z} = \begin{cases} 0, \ z \notin \varphi_t \left(\mathcal{B}_R \right) \\ \chi \left(\varphi_t^{-1}(z) \right) \left(\frac{\partial \psi}{\partial x}(0) \right)^{-1} \rho \left(\varphi_t^{-1}(z), t \right) \ , \ z \in \varphi_t \left(\mathcal{B}_R \right) \end{cases}$$
(7)

where $\chi : \mathbb{R}^n \to \mathbb{R}^+$ is a C^1 function such that

$$\chi(x) = \begin{cases} 0 , x \notin \mathcal{B}_R \\ 1 , x \in \mathcal{B}_{R-\varepsilon} \end{cases}$$

Notice that the vector field is zero outside $S = \bigcup_{\substack{z \in \mathcal{B}_R \\ t \in [0,1]}} \varphi_t(z)$, which is a compact set. Indeed, if

it is not, one can construct (x_n) and (t_n) , such that for all $n \in \mathbb{N}$,

$$\frac{|\psi(x_n t_n)|}{t_n} \ge n$$

Since $cl(\mathcal{B}_R)$ is compact, we extract $x_{\sigma(n)}t_{\sigma(n)}$ tending towards $x^* \in cl(\mathcal{B}_R)$. Necessarily, $t_{\sigma(n)}$ tends to 0 and $x^* = 0$ since (x_n) is bounded. But this is impossible because, $\frac{\psi(x_n t_n)}{t_n}$ is equivalent to $\frac{\partial \psi}{\partial x}(0)x_n$ around zero.

Therefore, the maximal solutions to this system are defined (at least) in [0, 1] for all initial conditions, and through backward integration, we obtain that $\varphi(\mathbb{R}^n, 1) = \mathbb{R}^n$.

We finally consider

$$\psi_e(x) = \frac{\partial \psi}{\partial x}(0)Z(x,1)$$

where Z(x, 1) is the solution of the system (7) evaluated at time 1 and initiated from x at time 0. This mapping being a linear transformation of a (time varying) flow, it is a diffeomorphism, and $\psi_e(\mathbb{R}^n) = \mathbb{R}^n$. Note moreover that for all $x \in \mathcal{B}_{R-\varepsilon}$, we have

$$\psi_e(x) = \frac{\partial \psi}{\partial x}(0)\varphi(x,1) = \psi(x)$$
.

2 Proof of Theorem 1

Consider a diffeomorphism $\psi: \mathcal{D} \to \psi(\mathcal{D}) \subsetneq \mathbb{R}^m$. We want to extend the image of ψ to \mathbb{R}^m , i-e find a diffeomorphism $\psi_e: \mathcal{D} \to \mathbb{R}^m$ such that:

-
$$\psi_e(\mathcal{D}) = \mathbb{R}^m$$

- $\psi_e(z) = \psi(z)$ for all z in $K \subset \mathcal{D}$, where K is any compact subset of \mathcal{D} .

Let us successively study the following two cases :

- First case: ψ(D) satisfies (C) The result follows directly from Corollary 2 and Remark
 2. In practice, the reader may find an explicit construction of such an extension in the proof of Lemma 1.
- Second case: \mathcal{D} is C^2 -diffeomorphic to \mathbb{R}^m and ψ is C^2 :

Let $\phi_1 : \mathcal{D} \to \mathbb{R}^m$ denote the corresponding diffeomorphism. Let R_1 be a strictly positive real number such that the open ball $\mathcal{B}_{R_1}(0)$ contains $\phi_1(K)$. Let R_2 be a real number strictly larger than R_1 . With Lemma 1 again, and since $\mathcal{B}_{R_2}(0)$ verifies condition (\mathcal{C}) , there exists of C^2 -diffeomorphism $\phi_2 : \mathcal{B}_{R_2}(0) \to \mathbb{R}^m$ satisfying

$$\phi_2(z) = z \qquad \forall z \in \mathcal{B}_{R_1}(0) \; .$$

At this point, we have obtained a C^2 -diffeomorphism $\phi = \phi_2^{-1} \circ \phi_1 : \mathcal{D} \to \mathcal{B}_{R_2}(0)$. Consider $\lambda = \psi \circ \phi^{-1} : \mathcal{B}_{R_2}(0) \to \psi(\mathcal{D})$. According to Lemma 2, we can extend λ to $\lambda_e : \mathbb{R}^m \to \mathbb{R}^m$ such that $\lambda_e = \psi \circ \phi^{-1}$ on $\mathcal{B}_{R_1}(0)$. Finally, consider $\psi_e = \lambda_e \circ \phi_1 : \mathcal{D} \to \mathbb{R}^m$. Since, by construction of ϕ_2 , $\phi = \phi_1$ on $\phi_1^{-1}(\mathcal{B}_{R_1}(0))$ which contains K, we have $\psi_e = \psi$ on K.

Remark 3 Note that the second construction is more complex than the first one, for it contains several extensions and in particular that of Lemma 2 which is difficult to implement. For this reason, one may prefer applying the first case whenever it is possible.

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