# Taking into account interaction between stereocenters in a graph kernel framework 

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#### Abstract

An important field of chemoinformatics consists in the prediction of molecule's properties, and within this field, graph kernels constitute a powerful framework thanks to their ability to combine a natural encoding of molecules by graphs, with classical statistical tools. Unfortunately some molecules encoded by a same graph and differing only by the three dimensional orientation of their atoms in space have different properties. Such molecules are called stereoisomers. These latter properties can not be predicted by usual graph methods. In this report, ordered graphs are introduced in order to represent those molecules. Then the stereoisomerism property of each atom of a molecule is encoded by a local ordered subgraph. Finally a graph of interactions between those local subgraphs is constructed.


Keywords: Graph kernel, Chemoinformatics, Stereoisomerism.

## 1 Introduction

The prediction of molecule's properties through Quantitative Structure Activity (resp. Property) Relationships are two active research subfields of chemoinformatics named QSAR and QSPR. Methods of those fields are based on the similarity principle: two structurally similar molecules should have similar properties.

One common method to predict chemical properties consists to design a vector of descriptors from a molecule and use statistical machine learning algorithms to predict molecule's properties. Such methods $[4,8]$, can use structural information, physical properties or biological activities in order to compute vectors of descriptors. However, such an approach requires to either select a random set of predefined descriptors (before a variable selection step) or to use an heuristic definition of appropriate descriptors by a chemical expert. In both cases, the transformation of the graph into a finite vector of features induces a loss of information.

Another approach consists to encode a molecule by a graph, and use it to predict properties. A molecular graph is a labeled simple graph $G=(V, E, \mu, \nu)$ representing a molecule. The unlabeled graph $(V, E)$ encodes the structure of the molecule, each node $v \in V$ encoding an atom and each edge $e=(v, w) \in E$
a bond between two atoms. The labelling function $\mu$ associates to each vertex $v \in V$ a label $\mu(v)$ encoding the nature of the atom and the function $\nu$ associates to each edge $e$ a type of bond $\nu(e)$ (single, double, triple or aromatic). Note that for the rest of this report, we denote the neighborhood of a vertex $v \in V$ by $N(v)$ :

$$
\forall v \in V, N(v)=\{u \in V \mid(v, u) \in E\}
$$

Note that $v$ does not belong to $N(v)$.
Several methods based on graph theory use this representation to predict molecular properties. One approach consists to search subgraphs with a large difference of frequencies between a set of positive and a set of negative examples [15]. Another approach consists to encode each class of molecules by a graph prototype and to measure the structural similarity between each prototype and an input molecule [2]. However, these methods can not be easily combined with machine learning algorithms. Conversely graph kernel methods can be coupled to machine learning algorithms provided that the kernel is definite positive. Let $\mathcal{G}$ be the set of all graphs. A definite positive kernel is a symmetric function $k: \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}$ such that:

$$
\sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} k\left(G_{i}, G_{j}\right) \geq 0 \text { where } n>0, G_{1}, \ldots, G_{n} \in \mathcal{G}, c_{1}, \ldots, c_{n} \in \mathbb{R}
$$

Such a definite positive kernel corresponds to a scalar product between two vectors $\psi(G)$ and $\psi\left(G^{\prime}\right)$ in an Hilbert space induced by the kernel.

A large family of graph kernel methods, associate a bag of patterns to each graph, and define the kernel value from a measure of similarity between those bags $[13,14,7]$. In [13] a graph kernel is defined as a measure of similarity between sets of walks extracted from each graph. But those walks are linear features and thus have limited expressiveness. An infinite set of tree patterns is used in [14] to define kernels. However, the similarity between two graphs is based on an implicit enumeration of their common tree patterns which does not allow to readily analyze the influence of a pattern on the prediction. Finally [7] is based on an explicit enumeration of patterns. All subtrees of a labeled graph up to size 6 , called treelets are enumerated.

However, some molecules may have a same molecular formula, a same molecular graph but a different relative positioning of their atoms. Such molecules are said to be stereoisomers. Different stereoisomers may be associated to different properties. However, usual graph kernels based on the molecular graph representation are not able to capture any dissimilarity between these molecules encoded by a same graph. From a more local point of view, an atom or two connected atoms are called stereocenters if a permutation of the positions of two atoms belonging to the union of their neighborhoods produces a different stereoisomer.

One example of stereocenter is an asymmetric carbon, which is a carbon atom with four different neighbors. We can represent each of its neighbors on a summit of a tetrahedron. If we permute two of the atoms, we obtain a different spatial configuration and hence an alternative stereoisomer (Figure 1a).

(a) Two different spatial configurations of the neighbors of a carbon

(b) Two different spatial configurations of two carbons linked by a double bond.

Fig. 1: Two types of stereocenters.

Two carbons, connected by a double bond, can also define stereoisomers (Figure 1b). Indeed, on the left side of Figure 1b fluorine (F) and iodine(I) atoms are located on the same side of the double bond while they are located on opposite sides on the stereoisomer represented on the right. In this case both carbon atoms of the double bond correspond to a stereocenter.

According to chemical experts [12], within molecules currently used in chemistry, $98 \%$ of stereocenters correspond either to asymmetric carbons (Figure 1a) or to couples of two carbons adjacent through a double bond (Figure 1b). We thus restrict the present report to such cases.

To distinguish those configurations, we introduce the two following subsets of the set of vertices $V$ of a molecular graph:

## Definition 1. Potential Asymmetric Carbons

Let us denote $V_{P A C}$ the subset of $V$ containing all vertices encoding atoms of carbon with four neighbors:

$$
V_{P A C}=\left\{v \in V \mid \mu(v)={ }^{\prime} C^{\prime} \text { and }|N(v)|=4\right\}
$$

Since being an atom with four neighbors is a necessary condition to define an asymmetric carbon, the set $V_{P A C}$ contains all vertices which may encode such atoms.

## Definition 2. Set of double-bonds connecting carbon atoms

The subset of $V$ containing all atoms of carbon which share a double bond with another carbon is noted $V_{D B}$ :

$$
V_{D B}=\left\{v \in V \mid \exists e(v, w) \in E, \nu(e)=2,\left(\begin{array}{c}
|N(v)|=|N(w)|=3 \\
\text { and } \\
\mu(v)=\mu(w)=C^{\prime}
\end{array}\right\}\right.
$$

An atom of carbon with two double bounds must have a degree equal to two. Hence, each vertex $v$ belonging to $V_{D B}$ is incident to a single double bound and we denote $n_{=}(v)$ the other carbon connected by this double bond. Note that $n_{=}(v) \in V_{D B}$.

Brown et al. [1] have proposed to incorporate this information through an extension of the tree-pattern kernel [14]. In this method, similarity between molecules are deduced from the number of common tree-patterns between two molecules. These patterns take into account the configuration around stereocenters. One drawback of this method is that, patterns which encode stereo information, and patterns which do not, are combined without any weighting in the final kernel value. So for a property only related to stereoisomerism, patterns that do not encode stereo information may be assimilated to noise which deteriorates the prediction. When several stereocenters are close to each other, one pattern may encode all of them. However the size of patterns are limited, so in some cases the influence of a permutation around stereocenters may not be detected by patterns containing them.

Intuitively, stereoisomerism property is related to the fact that permuting two neighbors of a stereocenter produces a different spatial configuration. If those two neighbors have a same label, the influence of the permutation should be searched beyond the direct neighborhood of this stereocenter. Based on this ascertainment, we have proposed in [11] to characterized locally a stereocenter by a subgraph, big enough to highlights the influence of each permutation of neighbors of this stereocenter. We then proposed a kernel based on those subgraphs.

One drawback of our previous approach is that each subgraph, and thus each stereocenter, are considered independently.

In the next section we present an encoding of molecules distinguishing stereoisomers, which was introduced in our previous report [9]. In Section 3 we present the construction of a subgraph, which allows to characterizes locally a stereocenter, introduced in [11]. Then in Section 4 we present a method which take into account interactions between the different subgraphs which characterize stereocenters. Finally, we demonstrate the validity of our kernel through experiments in Section 5.

## 2 Encoding of stereoisomers

The spatial configuration of the neighbors of each atom may be encoded through an ordering of its neighborhood. For example, considering the left part of Figure 1 a , and looking at the central carbon from the hydrogen atom $(\mathrm{H})$, the sequence of remaining neighbors of the carbon: $\mathrm{Cl}, \mathrm{Br}$ and F may be considered as lying on a plane and are encountered clockwise. Thus, this spatial configuration is encoded by the sequence $\mathrm{H}, \mathrm{Cl}, \mathrm{Br}, \mathrm{F}$ and the sequence $\mathrm{H}, \mathrm{Br}, \mathrm{Cl}, \mathrm{F}$ encodes the second configuration. The configuration around a double bond can also be encoded by ordered sequences. Considering the left part of Figure 1b and assuming a clockwise orientation with the plane embedding provided by this figure, we encounter F and Cl when turning around the carbon at the top of the molecule, and H and O for the carbon at the bottom. Thus this configuration may be encoded by both sequences $\mathrm{F}, \mathrm{Cl}$ and $\mathrm{H}, \mathrm{O}$ respectively for the top and bottom carbon atoms. Sequences $\mathrm{F}, \mathrm{Cl}$ and $\mathrm{O}, \mathrm{H}$ encode the second configuration.

In order to encode this information in a graph, we have introduced in [9] ordered graphs:

## Definition 3. Ordered Graphs

An ordered graph $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ is a molecular graph $\widehat{G}$ and a function ord which maps each vertex $v$ belonging to a subset $V_{\text {ord }}$ of $V$ to an ordered list of its neighbors:

$$
\operatorname{ord}\left\{\begin{aligned}
V_{\text {ord }} & \rightarrow \\
v & V^{*} \\
v & \mapsto v_{1} \ldots v_{n}
\end{aligned}\right.
$$

where $N(v)=\left\{v_{1}, \ldots, v_{n}\right\}$ denotes the neighborhood of $v$.
$V_{\text {ord }}$ is defined as $V_{P A C} \cup V_{D B}$. The function ord is defined as follows for each vertex $v \in V_{\text {ord }}$ :

- If $v \in V_{P A C}$ :

We set randomly one of its neighbor $v_{1}$ at the first position. The three other neighbors of $v$ are ordered such that if we look at $v$ from $v_{1}$, the three remaining neighbors are ordered clockwise. One of the three orders (defined up to circular permutations) fulfilling this condition is chosen randomly (Figure 2a).

- If $v \in V_{D B}$ :

Let us consider $w=n_{=}(v)$ and the two neighborhoods $N(v)=\{w, a, b\}$ and $N(w)=\{v, c, d\}$. The order on the neighborhood of $v$ is set as $\operatorname{ord}(v)=$ $w, a, b$ and the order on $w$ 's neighborhood is set as $\operatorname{ord}(w)=v, c, d$, whereby $a, b, c, d$ are traversed clockwise when turning around the double bond for a given plane embedding (Figure 2b).
The set of ordered graph is denoted $\mathcal{O G}$.
Lemma 1. Let $G=\left(\widehat{G}=(V, E, \mu, \nu)\right.$,ord) and $G^{\prime}=\left(\widehat{G^{\prime}}=\left(V^{\prime}, E^{\prime}, \mu^{\prime}, \nu^{\prime}\right)\right.$,ord $\left.{ }^{\prime}\right)$ be two ordered graph such that it exists $f$ in $\operatorname{Isom}\left(\widehat{G}, \widehat{G^{\prime}}\right)$.

Then $f\left(V_{\text {ord }}\right)=V_{\text {ord }}^{\prime}$
Proof. By Definition $1, v \in V_{P A C} \Leftrightarrow \mu(v)={ }^{\prime} C^{\prime}$ and $|V(v)|=4$.
As $f$ is an isomorphism we have $\mu(v)={ }^{\prime} C^{\prime}$ and $|V(v)|=4 \Leftrightarrow \mu(f(v))=$ ${ }^{\prime} C^{\prime}$ and $|V(f(v))|=4$.

Then again by Definition $1, v \in V_{P A C} \Leftrightarrow f(v) \in V_{P A C}^{\prime}$.
By Definition 2, $v \in V_{D B} \Leftrightarrow \exists e(v, w) \in E, \nu(e)=2,|V(v)|=|V(w)|=3$, and $\mu(v)=\mu(w)={ }^{\prime} C^{\prime}$.

As $f$ is an isomorphism we have $\exists e(v, w) \in E, \nu(e)=2,|V(v)|=|V(w)|=$ 3 , and $\mu(v)=\mu(w)={ }^{\prime} C^{\prime} \Leftrightarrow \exists e^{\prime}(f(v), f(w)) \in E, \nu\left(e^{\prime}\right)=2,|V(f(v))|=$ $|V(f(w))|=3$, and $\mu(f(v))=\mu(f(w))={ }^{\prime} C^{\prime}$.

Then again by Definition 2, $v \in V_{D B} \Leftrightarrow f(v) \in V_{D B}^{\prime}$.
By Definition 3, we have $V_{o r d}=V_{P A C} \cup V_{D B}$, so $v \in V_{o r d} \Leftrightarrow f(v) \in V_{o r d}^{\prime}$.
Thus $f\left(V_{\text {ord }}\right)=V_{\text {ord }}^{\prime}$.

## Definition 4. Isomorphism between Ordered Graphs

Two ordered graphs $G$ and $G^{\prime}$ are isomorphic $\left(G \underset{o}{\simeq} G^{\prime}\right)$ if there exists an isomorphism $f$ between their respective molecular graphs $\widehat{G}$ and $\widehat{G^{\prime}}$ which respect the order around each vertex:

$$
\begin{aligned}
& G \underset{o}{\simeq} G^{\prime} \Leftrightarrow \exists f \in \operatorname{Isom}\left(\widehat{G}, \widehat{G^{\prime}}\right) \text { s.t. } \\
& \qquad \forall v \in V_{\text {ord }} \text { with } \operatorname{ord}(v)=v_{1} \ldots v_{n}, \text { ord }^{\prime}(f(v))=f\left(v_{1}\right) \ldots f\left(v_{n}\right)
\end{aligned}
$$

where $N(v)=\left\{v_{1}, \ldots, v_{n}\right\}$ denotes the neighborhood of $v$. Notice that by Lemma 1, if $v \in V_{\text {ord }}$ then $f(v) \in V_{\text {ord }}^{\prime}$, so ord ${ }^{\prime}(f(v))$ is always defined.

In this case, $f$ is called an ordered isomorphism between $G$ and $G^{\prime}$, and we denote $\operatorname{IsomOrd}\left(G, G^{\prime}\right) \subset \operatorname{Isom}\left(\widehat{G}, \widehat{G^{\prime}}\right)$ the set of ordered isomorphism between $G$ and $G^{\prime}$.

As we have to make some arbitrary choice to define an order (Definition 3), a spatial configuration of atoms may be encoded by several equivalent orders. We thus have introduced in [9] the notion of re-ordering function, which associates to each vertex of an ordered structured object a permutation on its neighborhood.

## Definition 5. Re-ordering functions

A re-ordering function $\sigma$ on an ordered graph $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$, associates to each vertex $v \in V_{\text {ord }}$ a permutation $\varphi_{v}$ on $\{1, \ldots,|N(v)|\}$.

$$
\sigma\left\{\begin{aligned}
V_{\text {ord }} & \rightarrow \\
v & \mapsto \varphi_{v} \in \Pi_{|N(v)|}
\end{aligned}\right.
$$

where $\Pi_{n}$ is the group of permutations of $n$ elements and $\mathcal{P}$ is the union of $\Pi_{n}$ for all $n \in \mathbb{N}$.

Application of a re-ordering function on an ordered graph provides a new ordered structured graph defined as follows:

## Definition 6. Re-ordered structured objects

Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ denotes an ordered graph, $\sigma(G)=\left(\widehat{G}, \operatorname{ord}_{\sigma}\right)$ is defined as the ordered graph obtained after applying the re-ordering function $\sigma$ on the ordered list of neighbours of each vertex:

$$
\forall v \in V_{\text {ord }} \text { s.t. }\left(\begin{array}{l}
\operatorname{ord}(v)=v_{1}, \ldots, v_{n} \\
\text { and } \\
\sigma(v)=\varphi_{v},
\end{array}\right) \operatorname{ord}_{\sigma}(v)=v_{\varphi_{v}(1)}, \ldots, v_{\varphi_{v}(n)}
$$

Re-ordering functions previously defined may apply any re-ordering on a structured object hence removing the notion of order on these objects. In order to obtain a useful notion of re-ordering, we define a set of specific re-ordering functions.

## Definition 7. Set of re-ordering functions

The set $\Sigma$ of re-ordering functions contains all the re-ordering functions $\sigma$ such that:

- For each $v$ in $V_{P A C}, \sigma(v)$ is an even permutation:

$$
\forall v \in V_{P A C}, \epsilon(\sigma(v))=1 .
$$

- For each $v$ in $V_{D B}, \sigma(v)$ and $\sigma\left(n_{=}(v)\right)$ have the same parity:

$$
\forall v \in V_{D B}, \epsilon(\sigma(v))=\epsilon\left(\sigma\left(n_{=}(v)\right)\right)
$$

where $\epsilon$ denotes the signature of a permutation.
With this set we can define a notion of equivalent orders, such that two identical molecules will be represented by ordered graphs of equivalent orders.


Fig. 2: Example of elements of $V_{P A C}$ and of $V_{D B}$ with their ordered list (top) and the ordered lists obtained using two permutations $\sigma$ and $\sigma^{\prime}$

## Definition 8. Equivalent orders

Let us consider two ordered graphs $G=(\widehat{G}, o r d)$ and $G^{\prime}=\left(\widehat{G^{\prime}}, o r d^{\prime}\right)$. These graphs are said to be equivalent $G \underset{\bar{\Sigma}}{\simeq} G^{\prime}$ according to the set of re-ordering functions $\Sigma$ if:

$$
\begin{equation*}
\exists \sigma \in \Sigma \text { s.t } \sigma(G) \underset{o}{\simeq} G^{\prime} \tag{1}
\end{equation*}
$$

In other word, we consider that two ordered graphs are equivalent if, up to a valid re-ordering $\sigma$ we can establish an ordered graph isomorphism $f$ between them. In that case the ordered isomorphism $f$ is called an equivalent ordered isomorphism through $\sigma$ between $G$ and $G^{\prime}$. We denote by IsomEqOrd $\left(G, G^{\prime}\right)$ the set of equivalent ordered isomorphism between $G$ and $G^{\prime}$ :

$$
\operatorname{IsomEqOrd}\left(G, G^{\prime}\right)=\bigcup_{\sigma \in \Sigma} \operatorname{IsomOrd}\left(\sigma(G), G^{\prime}\right)
$$

As the set defined in Definition 7 is a valid family of re-ordering functions [9], the relationships defined in Definition 8 is an equivalence relationship [9]. We have thus now a way to encode stereoisomers.

Potentials asymmetric carbons, and double bonds between carbons, are not necessarily stereocenters. For example if the label of vertex Br of Figure 1a is replaced by Cl , both left and right molecules of Figure 1a would be identical. In the same way, if the label of the vertex F in Figure 1b is replaced by Cl, the left and right molecules of this figure would also become identical. For those cases, any permutation in the ordered list of the carbons would lead to an equivalent ordered graph, i.e it exists an equivalent ordered isomorphism between the graph and a permuted graph :

## Definition 9. Set of Isomorphism of non-stereocenter

Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ be an ordered graph. Let $v \in V_{\text {ord }}$.
We denote by $\mathcal{F}_{G}^{v}$ the set of ordered isomorphism $f$ such that :

where $\tau_{i, j}^{v}$ is a re-ordering function equals to the identity on all vertices except $v$ for which it permutes the vertices of index $i$ and $j$ in $\operatorname{ord}(v)$.

We define a stereo vertex as a vertex for which any permutation of two of its neighbors produces a non-equivalent ordered graph:

## Definition 10. Stereo vertices

Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ be an ordered graph. A vertex $v \in V_{\text {ord }}$ is called a stereo vertex iff:

$$
\mathcal{F}_{G}^{v}=\varnothing
$$

We denotes $\mathcal{S V}(G)$ the set of stereo vertices of $G$.
Lemma 2. Let us consider a graph $\widehat{G}$ and one of its automorphism $f, f \in$ $\operatorname{Isom}(\widehat{G}, \widehat{G})$.
$\forall v \in V_{D B}$ s.t $f(v)=v$, we have $f\left(n_{=}(v)\right)=n_{=}(v)$.
Proof. Let $v \in V_{D B}$ with $f(v)=v$.
By Definition $2 \exists!w \in V$ s.t $e=(v, w) \in E$ with $\nu(e)=2$ and $w=n_{=}(v)$. Since $f$ is an isomorphism $(f(v), f(w))=(v, f(w)) \in E$ with $\nu((f(v), f(w)))=$ 2. By Definition 2, $w$ is the unique neighbor of $v$ incident to an edge with a label 2 , so we have $f(w)=w$.

Proposition 1. $v \in V_{D B}$ is a stereo vertex iff $n_{=}(v)$ is a stereo vertex.
Proof. We consider an ordered graph $G=(\widehat{G}=(V, E, \mu, \nu)$, ord $)$. Let us consider $v \in V_{D B}$. We denote $w=n_{=}(v) \in V_{D B}$.

Let us suppose that $v \notin \mathcal{S} \mathcal{V}(G)$.
Then $\mathcal{F}_{G}^{v} \neq \varnothing$ and so, $\exists(i, j) \in\{1,2,3\}^{2}$, with $i \neq j$,
$\exists f \in \operatorname{IsomEqOrd}\left(G, \tau_{i, j}^{v}(G)\right)$ with $f(v)=v$, where $\tau_{i, j}^{v}$ is a re-ordering function
equals to the identity on all vertices except $v$ for which it permutes the vertices of index $i$ and $j$ in $\operatorname{ord}(v)$.

As $f \in \operatorname{IsomEqOrd}\left(G, \tau_{i, j}^{v}(G)\right) \subset \operatorname{Isom}(\widehat{G}, \widehat{G})$, by Lemma 2 we have $f(w)=$ $w$.

We define $\sigma=\tau_{i^{\prime}, j^{\prime}}^{w} \circ \tau_{i, j}^{v}$ where $\left(i^{\prime}, j^{\prime}\right) \in\{1,2,3\}^{2}$ s.t $i^{\prime} \neq j^{\prime}$.
By Definition 7 and since $\epsilon(\sigma(v))=\epsilon\left(\tau_{i, j}^{v}\right)=-1$ and $\epsilon(\sigma(w))=\epsilon\left(\tau_{i^{\prime}, j^{\prime}}^{w}\right)=-1$, $\sigma$ is a valid re-ordering function.

By Definition $8, \exists \sigma^{\prime} \in \Sigma$ s.t $f$ is an ordered isomorphism between $\sigma^{\prime}(G)$ and $\tau_{i, j}^{v}(G)$. Thus, by [9](Lemma 1), $f$ is an ordered isomorphism between $\sigma \circ \sigma^{\prime}(G)$ and $\sigma \circ \tau_{i, j}^{v}(G)=\tau_{i^{\prime}, j^{\prime}}^{w}(G)$.

As the valid family of re-ordering function is a group [9] $\sigma \circ \sigma^{\prime} \in \Sigma$, and thus $f \in \operatorname{IsomEqOrd}\left(G, \tau_{i^{\prime}, j^{\prime}}^{w}(G)\right)$ with $f(w)=w$. So $\mathcal{F}_{G}^{w} \neq \varnothing$

So $v \notin \mathcal{S V}(G)$ implies that $w=n_{=}(v) \notin \mathcal{S V}(G)$.
Since $\forall u \in V_{D B}, n_{=}\left(n_{=}(u)\right)=u$, this last statement is equivalent to :

$$
n_{=}(u) \notin \mathcal{S} \mathcal{V}(G) \Rightarrow u \notin \mathcal{S} \mathcal{V}(G)
$$

The contrapositive of the above implication provides the expected implication. Furthermore, an additional use of the relationship $n_{=}\left(n_{=}(u)\right)=u$ provides the expected equivalence relationship.

As Proposition 1 shows, two carbons linked by a double bond are simultaneously stereo vertices or non-stereo vertices. So we have to consider their stereo property together. We thus introduce the following notations :

## Definition 11. Set of bounded Stereo vertices

For $s \in \mathcal{S V}(G)$ we define its set $\operatorname{kernel}(s)$ of bounded stereo vertices as :

$$
\operatorname{kernel}(s)=\left\{\begin{array}{l}
\{s\} \text { if } s \in V_{P A C} \\
\left\{s, n_{=}(s)\right\} \text { if } s \in V_{D B}
\end{array}\right.
$$

## Definition 12. Star of Stereo vertices

For $s \in \mathcal{S} \mathcal{V}(G)$ we define its set StereoStar(s):

$$
\text { StereoStar }(s)=\left\{\begin{array}{l}
N(s) \cup\{s\} \text { if } s \in V_{P A C} \\
N(s) \cup N\left(n_{=}(s)\right) \text { if } s \in V_{D B}
\end{array}\right.
$$

## Definition 13. Set of neighbours of Stereo vertices

For $s \in \mathcal{S} \mathcal{V}(G)$ we define its set of neighbour StereoStar* $^{*}(s)$ :

$$
\text { StereoStar }^{*}(s)=\left\{\begin{array}{l}
N(s) \text { if } s \in V_{P A C} \\
N(s) \cup N\left(n_{=}(s)-\left\{s, n_{=}(s)\right\} \text { if } s \in V_{D B}\right.
\end{array}\right.
$$

Note that StereoStar ${ }^{*}(s)=$ StereoStar $(s)-\operatorname{kernel}(s)$.

## 3 From a global to a local characterization of stereo information

Definition 10 is based on the whole graph $G$ to test if a vertex $v$ is a stereo vertex. However, given a stereo vertex $s$, one can observe that on some configurations, the removal of some vertices far from $s$ should not change its stereo property. In order to obtain a more local characterization of a stereo vertex, we should thus determine a vertex induced subgraph $H$ of $G$, including $s$, big enough to characterize the stereo property of $s$, but sufficiently small to encode only the relevant information characterizing the stereo vertex $s$. Such a subgraph is called a minimal stereo subgraph of $s$.

## Definition 14. Subgraph characterizing a Stereo vertex

Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ be an ordered graph. Let $S$ be a subgraph of $G$. We say that the stereo property of $s \in \mathcal{S} \mathcal{V}(G)$ is captured by $S$ if:

$$
\begin{aligned}
& - \text { StereoStar }(s) \subset S \\
& -\mathcal{F}_{S}^{s}=\varnothing
\end{aligned}
$$

Remark 1. With the same argument than for the proof of Proposition 1, we can show that if the stereo property of $s \in \mathcal{S} \mathcal{V}(G)$ is captured by $S$ and $s \in V_{D B}$ then the stereo property of $n_{=}(s)$ is captured by $S$.

Thus a couple of carbons linked by a double bond only needs one subgraph to characterizes both of them.

## Definition 15. Set of vertices inducing isomorphism

Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ be an ordered graph. Let $s$ be a stereo vertex. Let $H$ be a subgraph of $G$ that do not capture the stereo property of $s$ and such that StereoStar $(s) \subset H$.

By Definition $14, \mathcal{F}_{H}^{s}$ is not empty. Let $f \in \mathcal{F}_{H}^{s}$.
We define $\mathcal{E}_{f}^{H}$ as the set of vertices inducing the isomorphism $f$ in $H$ :

$$
\begin{array}{r}
\mathcal{E}_{f}^{H}=\left\{v \in V(H) \mid \exists p=\left(v_{0}, \ldots, v_{q}\right) \in H \text { with } v_{0} \in \operatorname{kernel}(s) \text { and } v_{q}=v\right. \\
\text { s.t. } \left.f\left(v_{1}\right) \neq v_{1}\right\} \tag{2}
\end{array}
$$

where $\left(v_{0}, \ldots, v_{q}\right)$ denotes a path in $H$ (Hence $\left.v_{0} \neq v_{1}\right)$.
Proposition 2. For $H$ and $f$ defined as in Definition $15, \mathcal{E}_{f}^{H}$ is not empty.
Proof. Let $G=(\widehat{G}=(V, E, \mu, \nu)$,ord $)$ be an ordered graph. Let $s$ be a stereo vertex. Let $H$ be a subgraph of $G$ that do not capture the stereo property of $s$ and such that StereoStar $(s) \subset H$.

Let us consider $f \in \mathcal{F}_{H}^{s}$.
By definition of equivalent ordered isomorphism, it exists $\sigma \in \Sigma$ such that $f$ is an ordered isomorphism between $H$ and $\sigma\left(\tau_{i, j}^{s}(H)\right)$.

- If $s \in V_{P A C}$ :

By definition of ordered isomorphisms, and since $f(s)=s$, we have:

$$
\forall l \in\{1, \ldots,|N(s)|\}, f\left(v_{l}\right)=v_{\sigma(s) \circ \tau_{i, j}^{s}(l)}
$$

with $\operatorname{ord}(s)=v_{1}, \ldots, v_{n}$.
As $\sigma(s)$ is an even permutation, $\sigma(s) \circ \tau_{i, j}^{s}$ is an odd one. Hence it exists $l$ in $\{1, \ldots,|N(s)|\}$ such that $l \neq \sigma(s) \circ \tau_{i, j}^{s}(l)$.
Thus $f\left(v_{l}\right) \neq v_{l}$, and $\mathcal{E}_{f}^{H}$ is not empty as it contain at least $v_{l}$.

- If $s \in V_{D B}$ :

Let us consider $w=n_{=}(s)$. Since $f \in \operatorname{IsomEqOrd}\left(H, \tau_{i, j}^{s}(H)\right) \subset \operatorname{Isom}(\widehat{H}, \widehat{H})$, by Lemma 2 we have $f(w)=w$.
We denote by $N(s)=\left\{s_{1}, s_{2}, w\right\}$ the neighbourhood of $s$ and $N(w)=$ $\left\{w_{1}, w_{2}, s\right\}$ the neighbourhood of $w$.
Let us suppose that $f\left(w_{1}\right)=w_{1}$.
As $f(s)=s$, we have $f\left(w_{2}\right)=w_{2}$ and since $f$ is an ordered isomorphism between $H$ and $\sigma\left(\tau_{i, j}^{s}(H)\right)$ we have $\sigma(w)=I d$ where $I d$ is the identity permutation. Thus $\epsilon(\sigma(s))=\epsilon(\sigma(w))=1$ and $\sigma(s) \circ \tau_{i, j}^{s}$ is odd.
Hence $f$ defines an odd permutation on the ordered neighbour of $s$ and $f(w)=w$, thus by definition of ordered isomorphisms, we have $f\left(s_{1}\right)=s_{2} \neq$ $s_{1}$.
Thus we have either $f\left(w_{1}\right) \neq w_{1}$ or $f\left(s_{1}\right) \neq s_{1}$, so $\mathcal{E}_{f}^{H}$ is not empty as it contains at least $w_{1}$ or $s_{1}$.

## Definition 16. Minimal stereo subgraph

Let $G=(\widehat{G}=(V, E, \mu, \nu)$, ord $)$ be an ordered graph. Let $s \in \mathcal{S} \mathcal{V}(G)$. We consider a sequence $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ of vertex induced subgraphs of $G$ defined such that:

$$
\begin{aligned}
& -V\left(H_{s}^{0}\right)=\operatorname{StereoStar}(s) \\
& -V\left(H_{s}^{k+1}\right)=V\left(H_{s}^{k}\right) \cup \bigcup_{f \in \mathcal{F}_{H_{s}^{k}}^{k}} N\left(\mathcal{E}_{f}^{H_{s}^{k}}\right)
\end{aligned}
$$

We define $S_{s}$ as:

$$
S_{s}=\lim _{k \rightarrow+\infty} H_{s}^{k}
$$

The vertex induced subgraph $S_{s}$ is called the minimal stereo subraph of $s$. We say that $s$ is the stereo vertex of $S_{s}$ (if $s \in V_{D B}$, the stereo vertex of $S_{s}$ is arbitrarily chosen between $s$ and $n_{=}(s)$ as they have a same role). We denote $\mathcal{H}(G)$ the set of minimal stereo subraphs of $G$. Figure 3 shows one exemple of minimal stereo subraph.

Proposition 3. The sequence $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ converges.


Fig. 3: An asymmetric carbon and its associated sequence $\left(H_{C}^{k}\right)_{k \in \mathbb{N}}$. Its minimal stereo subgraph is $S_{C}=H_{C}^{3}$.

Proof. As $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ is a sequence of vertex induced subgraphs of $G$, we know that $\forall k \in \mathbb{N} H_{s}^{k} \unlhd G$. The sequence is thus upper bounded.

By Definition 16, we have $\forall k \in \mathbb{N} V\left(H_{s}^{k+1}\right)=V\left(H_{s}^{k}\right) \cup \bigcup_{f \in \mathcal{F}_{H_{s}^{k}}} N\left(\mathcal{E}_{f}^{H_{s}^{k}}\right)$. Thus $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ is an increasing sequence.

As $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ is upper bounded and increasing, $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ converges.

Remark 2. $\left(H_{s}^{k}\right)_{k \in \mathbb{N}}$ is a sequence of vertex induced subgraphs of $G$, so it is a discrete sequence, and thus the limit is reached: $\exists n \in \mathbb{N}$ s.t $\forall k>n, H_{s}^{k}=S_{s}$.

Proposition 4. For any $k \in \mathbb{N}$ such that $V\left(H_{s}^{k}\right) \neq V\left(S_{s}\right)$, the stereo property of s is not captured by $H_{s}^{k}$.
Proof. We consider $k \in \mathbb{N}$ such that $V\left(H_{s}^{k}\right) \neq V\left(S_{s}\right)$.
As $H_{s}^{k+1}$ is only constructed from $H_{s}^{k}\left(V\left(H_{s}^{k+1}\right)=V\left(H_{s}^{k}\right) \cup \bigcup_{f \in \mathcal{F}_{H_{s}^{k}}} N\left(\mathcal{E}_{f}^{H_{s}^{k}}\right)\right)$, and $V\left(H_{s}^{k}\right) \neq V\left(S_{s}\right)$, we have $V\left(H_{s}^{k}\right) \neq V\left(H_{s}^{k+1}\right)$.

Thus $\bigcup_{f \in \mathcal{F}_{H_{s}^{k}}} N\left(\mathcal{E}_{f}^{k}\right) \neq \varnothing$. So it exists at least one $f \in \mathcal{F}_{H_{s}^{k}}$ such that $\mathcal{E}_{f}^{k} \neq \varnothing$ and thus $\mathcal{F}_{H_{s}^{k}} \neq \varnothing$.

Then by Definition 14 and 9 the stereo property of $s$ is not captured by $H_{s}^{k}$.

Lemma 3. Let $G=(\widehat{G}=(V, E, \mu, \nu)$, ord $)$ be an ordered graph. Let s be a stereo vertex. Let $H$ be a connected vertex induced subgraph of $G$ that do not capture the stereo property of $s$ and such that StereoStar $(s) \subset H$. Let $f \in \mathcal{F}_{H}^{s}$.

We denotes $c c_{1} \ldots c c_{n}$ the set of connected components obtained by removing kernel(s) from $H$.

We define the sets of indices :
$-\mathcal{I}=\left\{i \mid c c_{i} \cap \mathcal{E}_{f}^{H} \neq \varnothing\right\}$.
$-\mathcal{J}=\left\{j \mid c c_{j} \cap \mathcal{E}_{f}^{H}=\varnothing\right\}$.
We denote $c c_{\mathcal{I}}=\bigcup_{i \in \mathcal{I}} c c_{i}$ and $c c_{\mathcal{J}}=\bigcup_{j \in \mathcal{J}} c c_{j}$.
Then we have :

$$
\begin{equation*}
c c_{\mathcal{I}} \subset \mathcal{E}_{f}^{H} . \tag{3}
\end{equation*}
$$

$$
\begin{align*}
\forall j \in \mathcal{J}, c c_{j} \cap \text { StereoStar }^{*}(s) & \neq \varnothing \text { and } \\
\forall v & \in c c_{j} \cap \text { StereoStar }^{*}(s) \text { we have } f(v)=v . \tag{4}
\end{align*}
$$

Proof. We first show that:

$$
c c_{\mathcal{I}} \subset \mathcal{E}_{f}^{H}
$$

Let $i \in \mathcal{I}$. By definition of $\mathcal{I}$ we have $c c_{i} \cap \mathcal{E}_{f}^{H} \neq \varnothing$. We denote $u$ one vertex such that $u \in c c_{i}$ and $u \in \mathcal{E}_{f}^{H}$. By definition of $\mathcal{E}_{f}^{H}$, it exists a path $p_{u}=\left(u_{1}, \ldots, u_{q}\right) \in H$ with $u_{q}=u, u_{1} \in \operatorname{StereoStar}^{*}(s)$ and $f\left(u_{1}\right) \neq u_{1}$. As $c c_{i}$ is a connected component of $H-\operatorname{kernel}(s)$, we have that $p_{u} \in c c_{i}$ and so $u_{1} \in c c_{i}$.

As $c c_{i}$ is a connected component $\forall v \in c c_{i}, \exists p=\left(u_{1}, v_{1}, \ldots, v\right) \in c c_{i}$. So $v \in \mathcal{E}_{f}^{H}$ and $c c_{i} \subset \mathcal{E}_{f}^{H}$.

We now show that:

$$
\begin{aligned}
\forall j \in \mathcal{J}, c c_{j} \cap \text { StereoStar }^{*}(s) & \neq \varnothing \text { and } \\
& \forall v \in c_{j} \cap \operatorname{StereoStar}^{*}(s) \text { we have } f(v)=v .
\end{aligned}
$$

$H$ is connected, thus for each $u \in H, \exists p=\left(u_{0}, \ldots, u_{q}\right) \in H$ with $u_{q}=u$ and $u_{0} \in \operatorname{kernel}(s)$. So $\forall u \in c c_{j}, \exists p=\left(u_{1}, \ldots, u_{q}\right) \in c c_{j}$ with $u_{q}=u$ and $u_{1} \in$ StereoStar $^{*}(s)$. Hence $u_{1} \in c c_{j}$ and $c c_{j} \cap \operatorname{StereoStar}^{*}(s) \neq \varnothing$

Let us consider $v \in c c_{j} \cap$ StereoStar $^{*}(s)$, if we suppose that $f(v) \neq v$ then $v \in \mathcal{E}_{f}^{H}$ and thus $c c_{j} \cap \mathcal{E}_{f}^{H}=\varnothing$ is false. So $\forall v \in c c_{j}$ s.t $v \in \operatorname{StereoStar}^{*}(s)$ we have $f(v)=v$.

Remark 3. By definition of $c c_{\mathcal{I}}$ and $c c_{\mathcal{J}}$ we have:
$-V(H)=c c_{\mathcal{I}} \cup c c_{\mathcal{J}} \cup \operatorname{kernel}(s)$
$-V=V(G-H) \cup c c_{\mathcal{I}} \cup c c_{\mathcal{J}} \cup \operatorname{kernel}(s)$
Lemma 4. With the same hypothesis and notations than in Lemma 3 we have:

$$
f\left(c c_{\mathcal{I}}\right)=c c_{\mathcal{I}}
$$

Proof. Let $v \in c c_{i}$ with $i \in \mathcal{I}$.
Thus $\exists p=\left(v_{1}, \ldots, v_{q}\right) \in H$ with $v_{q}=v, v_{1} \in \operatorname{StereoStar}^{*}(s)$ and $f\left(v_{1}\right) \neq$ $v_{1}$. So the sequence $\left(f\left(v_{1}\right), \ldots, f\left(v_{q}\right)\right)$ is also a path of $H$.

We denote $\tilde{v_{1}}=f\left(v_{1}\right)$.
As $v_{1} \in \operatorname{StereoStar}^{*}(s), \tilde{v_{1}} \in \operatorname{StereoStar}^{*}(s)$. As $f\left(v_{1}\right) \neq v_{1}$ and $f$ is bijective, $f\left(\tilde{v_{1}}\right)=f\left(f\left(v_{1}\right)\right) \neq f\left(v_{1}\right)=\tilde{v_{1}}$.

In conclusion we have $\exists p^{\prime}=\left(\tilde{v_{1}}, \ldots, f\left(v_{q}\right)\right) \in H$ with $v_{q}=v, \tilde{v_{1}} \in \operatorname{StereoStar}^{*}(s)$ and $f\left(\tilde{v_{1}}\right) \neq \tilde{v_{1}}$, so $f(v) \in c c_{i^{\prime}}$ with $i^{\prime} \in \mathcal{I}$.

So $f\left(c c_{\mathcal{I}}\right) \subset c c_{\mathcal{I}}$.
As $f$ is bijective we have $\left|f\left(c c_{\mathcal{I}}\right)\right|=\left|c c_{\mathcal{I}}\right|$. So $f\left(c c_{\mathcal{I}}\right)=c c_{\mathcal{I}}$.

Lemma 5. Using the same hypothesis and notations than in Lemma 3, $\forall f \in \mathcal{F}_{H}^{s}$ we have $N\left(\mathcal{E}_{f}^{H}\right) \not \subset V(H)$.

Proof. Let us supposed $N\left(\mathcal{E}_{f}^{H}\right) \subset V(H)$.
To obtain a contradiction we will construct an equivalent ordered isomorphism between $G$ and $\tau_{i, j}^{s}(G)$. To prove that the function we will construct is an ordered isomorphism between $G$ and $\tau_{i, j}^{s}(G)$ we will need some properties about the $c c_{i}$ and $c c_{j}$ defined previously which are consequences of our assumption $N\left(\mathcal{E}_{f}^{H}\right) \subset V(H)$.

We need to prove that we have :

$$
\begin{array}{r}
\forall v \in V(G-H), \forall p=\left(v_{0}, \ldots, v_{q}\right) \text { with } v_{0}=v, v_{q} \in H \text { and } \operatorname{kernel}(s) \cap p=\varnothing \\
\text { we have } v_{q} \in c c_{\mathcal{J}} . \tag{5}
\end{array}
$$

Let us suppose that $\exists v \in V(G-H), \exists p=\left(v_{0}, \ldots, v_{q}\right)$ with $v_{0}=v, v_{q} \in H$ and $\operatorname{kernel}(s) \cap p=\varnothing$ such that $v_{q} \in c c_{i}$ with $i \in \mathcal{I}$.

Let us denote $v_{r} \in p$ with $r \in\{0, \ldots, q-1\}$ one vertex such that $v_{r} \notin V(H)$ and $v_{r+1} \in c c_{i}$. Such a vertex exists as $v_{0} \notin V(H)$ and $v_{q} \in c c_{i}$.

As $v_{r+1} \in c c_{i}, v_{r+1} \in \mathcal{E}_{f}^{H}$ by (3) of Lemma 3. Thus $v_{r} \in N\left(\mathcal{E}_{f}^{H}\right)$ and $v_{r} \notin$ $V(H)$. As we have supposed $N\left(\mathcal{E}_{f}^{H}\right) \subset V(H)$ we have a contradiction, so $v_{q} \in$ $c_{\mathcal{J}}$.

Equation (5) and Remark 3 implies that:

$$
\begin{gather*}
\forall v \in V(G-H), N(v) \subset V(G-H) \cup c c_{\mathcal{J}}  \tag{6}\\
\forall v \in c c_{\mathcal{J}}, N(v) \subset V(G-H) \cup c c_{\mathcal{J}} \cup \operatorname{kernel}(s)  \tag{7}\\
\forall v \in c c_{\mathcal{I}}, N(v) \subset c c_{\mathcal{I}} \cup \operatorname{kernel}(s) \tag{8}
\end{gather*}
$$

Let us now define a function $g$ such that:

$$
\forall v \in V, g(v)=\left\{\begin{array}{l}
f(v) \text { if } v \in c c_{\mathcal{I}} \\
v \text { if } v \in c c_{\mathcal{J}} \cup V(G-H) \\
v=f(v) \text { if } v \in \operatorname{kernel}(s)
\end{array}\right.
$$

We want to prove that $g \in \operatorname{IsomEqOrd}\left(G, \tau_{i, j}^{s}(G)\right)$.

First, we have to prove that $g$ is bijective.
By Lemma 4 we have $f\left(c c_{\mathcal{I}}\right)=c c_{\mathcal{I}}$ so $g\left(c c_{\mathcal{I}}\right)=c c_{\mathcal{I}}$.
We have $g_{\mid c c_{\mathcal{I}}}=f$ is bijective, $g_{\mid G-c c_{\mathcal{I}}}=I d$ is bijective and $g\left(c c_{\mathcal{I}}\right)=c c_{\mathcal{I}}$, so $g$ is bijective.

We now prove that $g \in \operatorname{Isom}(\widehat{G}, \widehat{G})=\operatorname{Isom}\left(\widehat{G}, \widehat{\tau_{i, j}^{s}(G)}\right)$.
Let $e=(u, v) \in E$ :

- If $u \in c c_{\mathcal{I}}$.

We have $g(u)=f(u)$ and $v \in c c_{\mathcal{I}}$ or $v \in \operatorname{kernel}(s)$ by (8). In both cases we have $g(v)=f(v)$. As $f \in \operatorname{IsomEqOrd}\left(H, \tau_{i, j}^{s}(H)\right),(g(u), g(v))=$ $(f(u), f(v)) \in E$.

- If $u \in c c_{\mathcal{J}}$ or $u \in V(G-H)$.

We have $g(u)=u$ and $v \in V(G-H), v \in c c_{\mathcal{J}}$ or $v \in \operatorname{kernel}(s)$ by (6) and (7). In each case we have $g(v)=v$. Thus $(g(u), g(v))=(u, v) \in E$.

- If $u \in \operatorname{kernel}(s)$.

We have $g(u)=f(u)$ and $v \in \operatorname{StereoStar}^{*}(s)$ or $v \in \operatorname{kernel}(s)$. If $v \in c c_{\mathcal{I}}$, then $f(v)=g(v)$. However if $v \in c c_{\mathcal{J}}$, then $g(v)=v$. But by (4) of Lemma 3 we have $v=f(v)$, so $g(v)=v=f(v)$. Finally if $v \in \operatorname{kernel}(s), g(v)=v=$ $f(v)$.
So, in each case we have $g(v)=f(v)$. As $f \in \operatorname{IsomEqOrd}\left(H, \tau_{i, j}^{s}(H)\right)$, $(g(u), g(v))=(f(u), f(v)) \in E$.

In each case we have either $(g(u), g(v))=(f(u), f(v))$ or $(g(u), g(v))=(u, v)$, thus:

$$
\begin{align*}
& e=(u, v) \in E \Rightarrow \\
& e^{\prime}=(g(u), g(v)) \in E, \nu(e)=\nu\left(e^{\prime}\right), \mu(g(u))=\mu(u) \text { and } \mu(g(v))=\mu(v) \tag{9}
\end{align*}
$$

We define $\tilde{g}$ such that:

$$
\tilde{g}\left\{\begin{aligned}
V \times V & \rightarrow V \times V \\
(u, v) & \rightarrow(g(u), g(v))
\end{aligned}\right.
$$

As $g$ is bijective, $\tilde{g}$ is bijective.
By (9) we have $\tilde{g}(E) \subset E$, and as $\tilde{g}$ is bijective we have $\tilde{g}(E)=E$.
So $\forall(u, v) \in V \times V$, such that $\tilde{g}(u, v)=(g(u), g(v)) \in E$ we have $(u, v) \in E$. With (9) we can conclude that:

$$
\begin{align*}
& e=(g(u), g(v)) \\
& \quad \in E \Rightarrow  \tag{10}\\
& \quad e^{\prime}=(u, v) \in E, \nu(e)=\nu\left(e^{\prime}\right), \mu(g(u))=\mu(u) \text { and } \mu(g(v))=\mu(v) .
\end{align*}
$$

By (9) and (10) we have $g \in \operatorname{Isom}(\widehat{G}, \widehat{G})=\operatorname{Isom}\left(\widehat{G}, \widehat{\tau_{i, j}^{s}(G)}\right)$.
We finally have to prove that $\exists \sigma \in \Sigma$ such that $g \in \operatorname{IsomOrd}\left(\sigma(G), \tau_{i, j}^{s}(G)\right)$. $f \in \operatorname{IsomEqOrd}\left(H, \tau_{i, j}^{s}(H)\right)$ so by Definition $8 \exists \sigma \in \Sigma, \sigma(H) \underset{o}{\simeq} \tau_{i, j}^{s}(H)$.

We denote $\sigma^{\prime}$ the re-ordering function such that:

$$
\forall v \in V_{o r d}, \sigma^{\prime}(v)=\left\{\begin{array}{l}
\sigma(v) \text { if } v \in c c_{\mathcal{I}} \cup \operatorname{kernel}(s) \\
I d_{n} \text { if } v \in c c_{\mathcal{J}} \cup V(G-H)
\end{array}\right.
$$

where $I d_{n}$ is the identity permutation of $n$ elements and $n$ is the degree of $v$.
Let $v \in V_{P A C}$.
If $v \in \operatorname{kernel}(s) \cup c c_{\mathcal{I}}$ then $\sigma^{\prime}(v)=\sigma(v) . \sigma \in \Sigma$ so by Definition $7 \sigma(v)$ is even.
If $v \in V(G-H) \cup c c_{\mathcal{J}}$ then $\sigma^{\prime}(v)=I d_{n}$. The identity is even, so $\forall v \in V_{P A C}$, $\sigma^{\prime}(v)$ is even.

Let $v \in V_{D B}$.

- By Definition $11 v \in \operatorname{kernel}(s)$ iff $n_{=}(v) \in \operatorname{kernel}(s)$.

So, if $v \in \operatorname{kernel}(s)$, then $\sigma^{\prime}(v)=\sigma(v)$ and $\sigma^{\prime}\left(n_{=}(v)\right)=\sigma\left(n_{=}(v)\right)$.
$\sigma \in \Sigma$ so by Definition $7 \sigma(v)$ and $\sigma\left(n_{=}(v)\right)$ have a same parity.

- If $v \in c c_{\mathcal{I}}$ then by (8) $n_{=}(v) \in c c_{\mathcal{I}} \cup \operatorname{kernel}(s)$.

As $n_{=}(v) \in \operatorname{kernel}(s)$ iff $v \in \operatorname{kernel}(s)$ (Definition 11) and $v \in c c_{\mathcal{I}}, n_{=}(v) \notin$ $\operatorname{kernel}(s)$ and so $n_{=}(v) \in c c_{\mathcal{I}}$.
Thus $\sigma^{\prime}(v)=\sigma(v)$ and $\sigma^{\prime}\left(n_{=}(v)\right)=\sigma\left(n_{=}(v)\right)$.
$\sigma \in \Sigma$ so by Definition $7 \sigma(v)$ and $\sigma\left(n_{=}(v)\right)$ have a same parity.

- Finally if $v \in V(G-H) \cup c c_{\mathcal{J}}$ then by (6) and (7) $n_{=}(v) \in V(G-H) \cup$ $c_{\mathcal{J}} \cup \operatorname{kernel}(s)$.
As $n_{=}(v) \in \operatorname{kernel}(s)$ iff $v \in \operatorname{kernel}(s)$ (Definition 11) and $v \in V(G-H) \cup$ $c c_{\mathcal{J}}, n_{=}(v) \notin \operatorname{kernel}(s)$ and so $n_{=}(v) \in V(G-H) \cup c c_{\mathcal{J}}$.
So $\sigma^{\prime}(v)=I d_{n}$ and $\sigma^{\prime}\left(n_{=}(v)\right)=I d_{n}$ have a same parity.
Using Definition 7, we deduce from the previous considerations that $\sigma^{\prime} \in \Sigma$.
Let us now show that $g \in \operatorname{IsomOrd}\left(\sigma^{\prime}(G), \tau_{i, j}^{s}(G)\right)$. We denote by ord ${ }^{\prime}$ the order in $\tau_{i, j}^{s}(G)$. We stress here that $\forall v \in V_{\text {ord }}-\{s\}$, ord ${ }^{\prime}(v)=\operatorname{ord}(v)$.

Let $v \in V_{\text {ord }}$ with $\operatorname{ord}_{\sigma^{\prime}}(v)=v_{1}, \ldots, v_{n}$ :

- If $v \in c c_{\mathcal{I}}$.

We have $g(v)=f(v)$. We know that $\sigma(H) \simeq \tau_{i, j}^{s}(H)$ and $v \in H$, so $\operatorname{ord}^{\prime}(g(v))=\operatorname{ord}^{\prime}(f(v))=f\left(v_{1}\right), \ldots, f\left(v_{n}\right)$.
By (8) we know that $\forall k \in\{1, \ldots, n\}$ we have $v_{k} \in c_{c_{\mathcal{I}}}$ or $v_{k} \in \operatorname{kernel}(s)$. In both cases we have $f\left(v_{k}\right)=g\left(v_{k}\right)$ and thus $\operatorname{ord}^{\prime}(g(v))=g\left(v_{1}\right), \ldots, g\left(v_{n}\right)$.

- If $v \in c c_{\mathcal{J}}$ or $v \in V(G-H)$.

We have $g(v)=v$. So $\operatorname{ord}^{\prime}(g(v))=\operatorname{ord}^{\prime}(v)$. As $v \in V_{\text {ord }}-\{s\}$, $\operatorname{ord}^{\prime}(v)=$ $\operatorname{ord}(v)$, and thus $\operatorname{ord}^{\prime}(g(v))=\operatorname{ord}(v)$. As $\sigma^{\prime}(v)=I d_{n}$, we have $\operatorname{ord}(v)=$ $\operatorname{ord}_{\sigma^{\prime}}(v)=v_{1}, \ldots, v_{n}$. So $\operatorname{ord}^{\prime}(g(v))=v_{1}, \ldots, v_{n}$.
By (7) and (8) we know that $\forall k \in\{1, \ldots, n\}$ we have $v_{k} \in V(G-H), v_{k} \in$ $c c_{\mathcal{J}}$ or $v_{k} \in \operatorname{kernel}(s)$. So $v_{k}=g\left(v_{k}\right)$ and thus $\operatorname{ord}^{\prime}(g(v))=g\left(v_{1}\right), \ldots, g\left(v_{n}\right)$.

- If $v \in \operatorname{kernel}(s)$.

We have $g(v)=f(v)$. We know that $\sigma(H) \underset{o}{\simeq} \tau_{i, j}^{s}(H)$ and $v \in H$, so $\operatorname{ord}^{\prime}(g(v))=\operatorname{ord}^{\prime}(f(v))=f\left(v_{1}\right), \ldots, f\left(v_{n}\right)$.
Let $k \in\{1, \ldots, n\}$. If $v_{k} \in c_{c_{\mathcal{I}}}$, then $f\left(v_{k}\right)=g\left(v_{k}\right)$. However if $v_{k} \in c_{\mathcal{J}}$, then $g\left(v_{k}\right)=v_{k}$. But by (4) we have $v_{k}=f\left(v_{k}\right)$, so $g\left(v_{k}\right)=v_{k}=f\left(v_{k}\right)$. Thus ord $^{\prime}(g(v))=g\left(v_{1}\right), \ldots, g\left(v_{n}\right)$

In each case we have $\operatorname{ord}^{\prime}(g(v))=g\left(v_{1}\right), \ldots, g\left(v_{n}\right)$, so $\sigma^{\prime}(G) \underset{o}{\simeq} \tau_{i, j}^{s}(G)$.
Thus $g \in \operatorname{IsomEqOrd}\left(G, \tau_{i, j}^{s}(G)\right)$ and $g(s)=s$. This is not possible since $s \in \mathcal{S V}(G)$, thus $N\left(\mathcal{E}_{f}^{H}\right) \not \subset V(H)$.

Theorem 1. The stereo property of $s$ is captured by $S_{s}$.
Proof. We denote $n \in \mathbb{N}$ an integer such that $H_{s}^{n}=S_{s}$ (Remark 2).
The sequence is initialized by $V\left(H_{s}^{0}\right)=\operatorname{StereoStar}(s)$. As the sequence is increasing we have $V\left(H_{s}^{0}\right) \subset V\left(H_{s}^{n}\right)$, so the first condition of Definition 14 is true.

We thus have to prove that $\mathcal{F}_{H_{s}^{n}}^{s}=\varnothing$.
Let us suppose that $\exists(i, j) \in\{1, \ldots,|N(s)|\}^{2}$ with $i \neq j$, $\exists f \in \operatorname{IsomEqOrd}\left(H_{s}^{n}, \tau_{i, j}^{s}\left(H_{s}^{n}\right)\right)$ with $f(s)=s$.

Thus by Lemma 5 we have $N\left(\mathcal{E}_{f}^{H_{s}^{n}}\right) \not \subset V\left(H_{s}^{n}\right)$. So $V\left(H_{s}^{n+1}\right)=V\left(H_{s}^{n}\right) \cup$ $\bigcup_{f \in \mathcal{F}_{H_{s}^{k}}^{k}} N\left(\mathcal{E}_{f}^{H_{s}^{k}}\right) \neq V\left(H_{s}^{n}\right)$.

This is in contradiction with the fact that $H_{s}^{n}=S_{s}=\lim _{k \rightarrow+\infty} H_{s}^{k}$, so the stereo property of s is captured by $H_{s}^{n}=S_{s}$.

Thus for each stereo vertex we can construct its minimal stereo subgraph to characterize it. We consider two stereo vertices as similar if they have a same minimal stereo subgraphs, and to test it efficiently, we transform our minimal stereo subgraphs $S$ into codes $c_{S}$ thanks to the method described in [17].

## 4 Interactions between stereo vertices

In the previous section we have defined a way to construct an oriented subgraph which characterizes a stereocenter. We may use the set of subgraphs, associated to each stereocenter of a molecule, to compare molecules. However two stereocenter may not have the same influence on a property if they are close from each other or far from each other in a molecule. In the same way, two same minimal stereo subgraph may not have a same influence on a property if they have different surroundings. We now propose to construct some new graphs, based on the set of minimal stereo subgraphs, to encode more information about those subgraphs.

### 4.1 Graphs of interaction

To represent the interactions between stereo vertices we define different functions of interactions, which encode different degrees of information about the interactions between stereo vertices:

## Definition 17. Functions of interactions

Let $G=\left(G_{m}=(V, E, \mu, \nu)\right.$,ord $)$ an ordered graph and $\mathcal{H}(G)$ its set of minimal stereo subgraphs.

Functions of interactions are defined according to a sequence of conditions $\left(c_{0}, \ldots, c_{n}\right)$. These conditions are increasingly constraining:

$$
\forall i \in\{1, \ldots, n-1\} c_{i+1} \Rightarrow c_{i} \text { and } c_{0}=\neg c_{1}
$$

Let $H_{1}$ and $H_{2}$ be two minimal stereo subgraphs, such that $s_{1}$ is the stereo vertex of $H_{1}$ and $s_{2}$ is the stereo vertex of $H_{2}$. The value $F\left(H_{1}, H_{2}\right)$ is obtained by taking the maximum index $j$ of conditions $c_{j}$ which represents the strongest interaction between $H_{1}$ and $H_{2}$ :

$$
F\left(H_{1}, H_{2}\right)=\max \left\{j \in\{0, \ldots, n\} \mid c_{j}\right\}
$$

We consider 4 sequences of conditions defining 4 functions of interactions $F_{i}$
$-F_{1}$ is defined by using $\left\{\begin{array}{l}c_{1}: H_{1} \bigcap H_{2} \neq \emptyset \\ c_{2}: \text { kernel }\left(s_{1}\right) \subset H_{2} \\ c_{3}: \text { StereoStar }\left(s_{1}\right) \subset H_{2} \\ c_{4}: H_{1} \subset H_{2}\end{array}\right.$
$-F_{2}$ is defined by using $\left\{\begin{array}{l}c_{1}: H_{1} \bigcap H_{2} \neq \emptyset \\ c_{2}: \text { StereoStar }\left(s_{1}\right) \subset H_{2} \\ c_{3}: H_{1} \subset H_{2}\end{array}\right.$
$-F_{3}$ is defined by using $\left\{\begin{array}{l}c_{1}: \text { kernel }\left(s_{1}\right) \subset H_{2} \\ c_{2}: \operatorname{StereoStar}\left(s_{1}\right) \subset H_{2} \\ c_{3}: H_{1} \subset H_{2}\end{array}\right.$
$-F_{4}$ is defined by using $\left\{\begin{array}{l}c_{1}: \text { StereoStar }\left(s_{1}\right) \subset H_{2} \\ c_{2}: H_{1} \subset H_{2}\end{array}\right.$
Note that the $F_{i}$ is not symmetric.
We define thanks to those functions, 4 graphs of interactions $G_{i}$ where each vertex $v \in V_{i}$ represent a minimal stereo subgraph and each edge encode the interaction between two minimal stereo subgraphs.

## Definition 18. Directed Graph of interactions

A directed graph of interactions $G_{i}=\left(V_{i}, A_{i}, \mu_{i}, \nu_{i}\right)$ is a graph constructed from an ordered graph $G=\left(G_{m}=(V, E, \mu, \nu)\right.$,ord $)$ such that:

- $\forall u \in V_{i}, \exists!H(u) \in \mathcal{H}(G)$.
$-\forall u \in V_{i}, \mu_{i}(u)=c_{H(u)}$, where $c_{H}$ is the code defined in [17] (Section 3).
$-\exists a=\left(u_{1}, u_{2}\right) \in A_{i} \Longleftrightarrow F_{i}\left(H\left(u_{1}\right), H\left(u_{2}\right)\right) \neq 0$.
$-\forall a=\left(u_{1}, u_{2}\right) \in A_{i}, \nu_{i}(a)=F_{i}\left(H\left(u_{1}\right), H\left(u_{2}\right)\right.$.
where $F_{i}$ is one of the function defined in Definition 17.

As very few nodes have the same label in the directed graph of interactions, the direction of edges does not provide a lot of information. We thus define undirected graphs of interactions, which encode not a lot less infromation than directed graphs of interactions, but which is simpler.

## Definition 19. Graph of interactions

A graph of interactions $G_{i}=\left(V_{i}, E_{i}, \mu_{i}, \nu_{i}\right)$ is a graph constructed from an ordered graph $G=\left(G_{m}=(V, E, \mu, \nu)\right.$,ord $)$ such that:
$-\forall u \in V_{i}, \exists!H(u) \in \mathcal{H}(G)$.
$-\forall u \in V_{i}, \mu_{i}(u)=c_{H(u)}$, where $c_{H}$ is the code defined in [17] (Section 3).
$-\exists e=\left(u_{1}, u_{2}\right) \in E_{i} \Longleftrightarrow F_{i}\left(H\left(u_{1}\right), H\left(u_{2}\right)\right) \neq 0$ or $F_{i}\left(H\left(u_{2}\right), H\left(u_{1}\right)\right) \neq 0$.
$-\forall e=\left(u_{1}, u_{2}\right) \in E_{i}, \nu_{i}(e)=\min \left(F_{i}\left(H\left(u_{1}\right), H\left(u_{2}\right)\right), F_{i}\left(H\left(u_{2}\right), H\left(u_{1}\right)\right)\right) \odot$ $\max \left(F_{i}\left(H\left(u_{1}\right), H\left(u_{2}\right)\right), F_{i}\left(H\left(u_{2}\right), H\left(u_{1}\right)\right)\right)$.
where $\odot$ denotes the concatenation and $F_{i}$ is one of the function defined in Definition 17.

Figure 4 show all graphs of interactions we can construct from an ordered graph by taking the four different functions of interactions.

The first graph $G_{1}$ is constructed by taking 4 different types of interaction. However we may suppose that some of those type of interaction are less relevant than the other.

Indeed, a vertex $s_{1}$ is a stereo vertex because of the relative positioning of its neighbour. So we may suppose that, if a stereo vertex is present in a stereo subgraph $\left(\operatorname{kernel}\left(s_{1}\right) \subset H_{2}\right)$, but not its neighbourhood $\left(\operatorname{StereoStar}\left(s_{1}\right) \not \subset H_{2}\right)$, the stereo vertex may have a similar influence in $H_{2}$ than a non-stereo vertex. $G_{2}$ is thus constructed without taking $\operatorname{kernel}\left(s_{1}\right) \subset H_{2}$ as a type of interaction.

We also may suppose that an intersection between two minimal stereo subgraphs may not be a sufficiently relevant information. Thus the graph $G_{3}$ is constructed with 3 different type of interaction, by considering that two stereo vertex are related if we have at least $\operatorname{kernel}\left(s_{1}\right) \subset H_{2}$ or $\operatorname{kernel}\left(s_{2}\right) \subset H_{1}$.

Finally $G_{4}$ is constructed by taking the two previous assumptions together.
As graphs of interaction are graphs without order, we may apply any graph kernel (for the experiment in Section 5 we apply the treelet kernel [7]) to measure their similarity.

## 5 Experiments

We have tested our method on two datasets. For both of them we use the same protocol, a nested cross-validation, to choose the parameter and estimate the performance. The outer cross-validation is a leave-one-out procedure, used to compute an error for each molecule of the dataset. For each fold, we use another leave-one-out procedure on the remaining molecules, to compute a validation error. We use standard SVM method $[5,6]$ for classification and regression of molecules.

(a) An ordered graph and its minimal stereo subgraphs

(b) $G_{1}$

(d) $G_{3}$
(c) $G_{2}$

$H_{1} \frac{{ }_{02}}{} H_{2} \quad$| $H_{4}$ |
| :---: |
|  |
| $H_{3}$ |

(e) $G_{4}$

Fig. 4: One ordered graph and its different graph of interactions, obtained by taking different function of interactions.

Table 1: Averages values of numbers of vertices $(\overline{|V|})$, edges $(\overline{|E|})$, different labels $\left(\overline{\left|\mathcal{L}_{V}\right|}, \overline{\mathcal{L}_{E} \mid}\right)$, and mean degree $(\bar{d})$ of graph of interactions.

|  | V\| | \|E| | $\left\|\mathcal{L}_{V}\right\|$ | $\underline{\mathcal{L}_{E} \mid}$ | $\bar{d}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Graph 1 | 5 | 7 | 4.5 | 3 | 2.8 |
| Graph 2 | 5 | 7 | 4.5 | 3 | 2.8 |
| Graph 3 | 5 | 2 | 4.5 | 2 | 0.8 |
| Graph 4 | 5 | 1 | 4.5 | 1 | 0.4 |

(a) ACE dataset

|  | $\mid$ | $\|V\|$ | $\overline{V \mid} \mid$ | $\left\|\overline{\mathcal{L}_{V} \mid}\right\|$ | $\left\|\mathcal{L}_{E}\right\|$ |
| :--- | :--- | :--- | :--- | :--- | :---: |
| $\bar{d}$ |  |  |  |  |  |
| Graph 1 | 8.55 | 17.4 | 8.38 | 5.71 | 4.07 |
| Graph 2 | 8.55 | 17.4 | 8.38 | 3.71 | 4.07 |
| Graph 3 | 8.55 | 11.3 | 8.38 | 4.71 | 2.62 |
| Graph 4 | 8.55 | 6.14 | 8.38 | 2.71 | 1.43 |

(b) Vitamin dataset

Our first experiment is based on a dataset composed of all the stereoisomers of the perindoprilate [3]. As this molecule has 5 stereocenters, the dataset is composed of $2^{5}=32$ molecules. In this dataset, we try to predict if a molecule inhibit the angiotensin-converting enzyme (ACE). Basic statisistics about the graphs of interactions $G_{i}=\left(V_{i}, E_{i}, \mu_{i}, \nu_{i}\right)$ deduced from this dataset is displayed in Table 2a.

Table 2: Classification of the ACE inhibitory activity of perindopirilates stereoisomers

| Method | Accuracy |
| :--- | :---: |
| Brown [1] | 96.875 |
| Stereo Kernel [11] | 87.5 |
| Stereo + Extended subgraphs [10] | 96.875 |
| Graph of interaction 1 | 93.75 |
| Graph of interaction 2 | 93.75 |
| Graph of interaction 3 | 93.75 |
| Graph of interaction 4 | 84.375 |
| Graph of interaction 1 with MKL | $\mathbf{1 0 0}$ |
| Graph of interaction 2 with MKL | $\mathbf{1 0 0}$ |
| Graph of interaction 3 with MKL | 87.5 |
| Graph of interaction 4 with MKL | 90.625 |

For this first experiment we have not included results of method which do not include stereoisomerism information [14, 7]. Indeed all molecules of the dataset are stereoisomers of each other, so those methods cannot differentiate any molecule of this dataset and are consequently unable to predict the considered property. Moreover, information not related to stereoisomerism included in kernel [1] consists of the same patterns for all molecules. This leads to add a constant shift to all values of the kernel and hence does not deteriorate the prediction for this dataset. In this dataset two stereocenters have a same minimal stereo subgraph, but different surrounding. The stereo kernel [11] and one of the graph of interactions $\left(G_{4}\right)$, can not differentiate those two stereocenters, which
have different influence on the property, this explains why other method ( $[1,10]$ and the three other graphs of interactions) obtain a better accuracy. However, for our graphs of interactions, treelet of size one have a negative effect on the classification, this explains why we do not obtain better results than [1, 10]. By using a multiple kernel learning algorithm [16], we can learn a weight for each treelet, that allow us to discard treelet of size 1 and to obtain the best results with the first and second graph of interactions. The third graph of interactions have very few edges and a low degree (Table 2a) which explains why the treelet kernel with multiple kernel learning obtains poor results with this graph.

The second dataset is a dataset of synthetic vitamin D derivatives, used in [1]. This dataset is composed of 69 molecules, with an average of 9 stereocenters per molecule. This dataset is associated to a regression problem, which consists in predicting the biological activities of each molecules. As for the previous dataset, statistics about the graphs of interactions deduced from this dataset can be found in Table 2b.

Table 3: Prediction of the biological activity of synthetic vitamin D derivatives.

| Method | RMSE |
| :--- | :---: |
| 1 - Tree patterns Kernel [14] | 0.251 |
| 2 - Treelet Kernel [7] | 0.271 |
| 3 - Brown [1] | 0.184 |
| 4 - Stereo Kernel [11] | 0.194 |
| 5 - Stereo + Extended subgraphs [10] | 0.180 |
| 6 - Graph of interaction 1 | 0.177 |
| 7 - Graph of interaction 2 | 0.177 |
| 8 - Graph of interaction 3 | $\mathbf{0 . 1 6 9}$ |
| 9 - Graph of interaction 4 | 0.172 |

Methods which do not encode stereoisomerism information [14, 7] obtain poor results as we can see in Table 3 (lines 1-2). The adaptation of the tree pattern kernel to stereoisomerism [1] and our previous kernels [11,10] (lines 3-5) improves the results over the two previous methods hence showing the insight of adding stereoisomerism information. Taking into account relationships between minimal stereo subgraphs (lines 6-9) allows us to obtain better results than our previous method [10].

## 6 Conclusion

The study and the definition of new stereoisomers constitutes an important subfield of chemistry and thus a major challenge in chemoinformatics. Indeed, stereoisomers of some common drugs may be considered as violent poisons. For example, a molecule called thalidomide was sold in the late fifties as an anti nausea for pregnant women. However, it turns out that one of the stereoisomer
of this molecule could cause fetal malformation. Up to now, only few methods have proposed pattern recognition methods taking explicitly into account stereoisomerism.

We have presented previously a graph kernel based on an explicit enumeration of all the stereo subgraphs of a molecule. Each stereo subgraph is associated to a stereo vertex and encodes the part of the graph which provides the stereo property to this vertex. In this report we have proposed an extension of this previous methods which consists in construct a new graph, where each nodes represent a stereo subgraph and each edge encode the interaction between stereo subgraphs. This graph allows us to take into account relationships between stereo subgraphs. The relevance of this approach is demonstrated by our experiments on two datasets.

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