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Analysis and Modelling of the Optimal Command for an **Ultrasound Pulse Inversion Imaging System**

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1. Introduction & Background

4. Optimal Command Modelling

A. Ultrasound Contrast Imaging

Injection of encapsulated microbubbles High nonlinear behavior Contrast-to-Tissue Ratio

$$CTR = rac{E_{microbulles}}{E_{tissu}}$$





$$\hat{x}(t) = G(t) \cdot \left[\sum_{k=1}^{M} \alpha_{1,k} \cos\left(2\pi k f t + \theta_{1,k}\right) + \sum_{k=1}^{N} \alpha_{2,k} \cos\left(2\pi \left(k - \frac{1}{2}\right) f t + \theta_{2,k}\right) \right],$$

Whole harmonic components and Half-whole harmonic components $G(t) \rightarrow \text{Gaussian apodization}; \Xi = [\alpha^T, \theta^T, f]^T$ A. Frequency optimization: Newton–Raphson method $f_{i+1} = f_i - \frac{MSE(f_i)(f_i - f_{i-1})}{MSE(f_i) - MSE(f_{i-1})}$

B. Amplitude and phase optimization for each iteration *i*

B. Pulse Inversion Ultrasound Imaging



Increasing CTR by odd harmonic extraction with the sum [Simpson, 1999] **C. Simulation**

BUBBLESIM [Hoff, 2001] for a 2.5 μ m microbubble; tissue \approx fat globules; transducer: 3 MHz - 90%

2. Analysis of Optimal Command for Pulse Inversion Imaging System

In a previous work [1], CTR was optimized by a Monte-Carlo method: $x^{\star}(t) = \arg \max (CTR(x(t))) \Rightarrow CTR = 31.62 \text{ dB}$

Algebraic expression

 $\mathbf{X} = \mathbf{\Psi} \boldsymbol{\vartheta},$ $\boldsymbol{\vartheta}^{T} = [\alpha_{1,1} \cos \theta_{1,1}, -\alpha_{1,1} \sin \theta_{1,1}, \dots, \alpha_{1,M} \cos \theta_{1,M}, -\alpha_{1,M} \sin \theta_{1,M}, \dots, \alpha_{1,M} \cos \theta_{1,M}, -\alpha_{1,M} \sin \theta_{1,M}, \dots]$ $\alpha_{2,1} \cos \theta_{2,1}, -\alpha_{2,1} \sin \theta_{2,1}, \dots, \alpha_{2,N} \cos \theta_{2,N}, -\alpha_{2,N} \sin \theta_{2,N}].$ $\boldsymbol{\Psi}^{T} = (\boldsymbol{\Psi}_{1}, \boldsymbol{\Psi}_{2}, \ldots, \boldsymbol{\Psi}_{T}),$ $\Psi_t = \left[G(t) \cos\left(2\pi ft\right), G(t) \cdot \sin\left(2\pi ft\right), \ldots, \right]$ $G(t) \cdot \cos(2\pi M f t), G(t) \cdot \sin(2\pi M f t),$ $G(t) \cdot \cos(\pi ft), G(t) \cdot \sin(\pi ft), \ldots,$ $G(t) \cdot \cos(2\pi (N - 1/2) ft)$, $G(t) \cdot \sin(2\pi (N - 1/2) ft)$ Least squares method $\boldsymbol{\vartheta} = (\boldsymbol{\Psi}^T \boldsymbol{\Psi})^{-1} \boldsymbol{\Psi}^T \boldsymbol{X}$

5. Mean Square Error





What are the properties of this optimal command ? o Nonlinear signal

[1] S. Ménigot and J.-M. Girault, "Random excitation by optimized pulse inversion in contrast harmonic imaging", in Acoustics 2012, pp. 2895–2900, April 2012.

6. CTR Performances Checking with the Synthetic Signals $\hat{x}(t)$



3. Objectives of Modelling

1. Modelling the optimal command $x^*(t)$ including nonlinear components



2. Finding model parameters Ξ by minimizing Mean Square Error $/ \tau$

$$\Xi^{\star} = \arg\min_{\Xi} \left(MSE \right) = \arg\min_{\Xi} \left(\sum_{t=0}^{\prime} \left[x(t) - \hat{x}(t) \right]^2 \right)$$

3. Building a synthetic signal $\hat{x}(t)$ 4. Checking CTR performances for the synthetic input signal $\hat{x}(t)$ [2] S. Ménigot, J.-M. Girault, I. Voicu and A. Novell, "Optimization of Contrast to Tissue Ratio by Frequency

Adaptation in Pulse Inversion Imaging", IEEE Trans. Ultrason., Ferroelectr., Freq. Control, in press, 2012.

7. Conclusions & Prospect

- Description of the optimal command
- Optimal command has harmonic and subharmonic components
- Prospect : transforming shape optimization in parameter optimization