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Experimental characterization and modeling of GFPP commingled yarns tensile behavior

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Abstract

3D fabrics of commingled yarns offer the possibility of a low-cost and fast manufacturing of complex shaped composite parts. Textile-reinforcement behavior during the forming processes is very important since the appearance of defects (for example wrinkles, yarn misalignment or breakage) can significantly affect the mechanical properties of the final part. Experimental characterization of the mechanical behavior of textile-reinforcements is expensive, time consuming and a large scattering of results is often observed. To overcome this, meso-scale modeling is an interesting method to study and understand the textile behavior at the unit cell level. To perform realistic simulations, an accurate modeling, and therefore knowledge of the yarn mechanical behavior is needed. In this paper, a simple protocol is proposed and validated in order to investigate the tensile behavior of commingled polypropylene/glass yarns. Influence of specimen length and strain rate are highlighted. A comparison of tensile behavior of yarns before and after weaving is carried out in order to evaluate the weaving damage effect. Finally, a model describing the commingled yarn behavior is proposed. The parameters of the model are defined. Their dependency to strain rate, specimen length and weaving damage are highlighted.

Keywords

Commingled yarns, experimental protocol, tensile behavior, weaving damage, specimen length, strain rate.

Introduction

There is a growing interest in automotive, aeronautic and leisure industries for the use of textile reinforced thermoplastic composites as lightweight and high performance structural components. Indeed, this kind of product offers interesting advantages compared to classical thermoset composites, especially recycling and the possibility to reshape the part by reheating¹⁻³. Thermoplastic matrices also offer advantages in terms of mechanical behavior, with better fracture toughness properties and easiest storage contrary to thermoset ones. However, the high viscosity of thermoplastic matrices is among the main drawbacks because it makes difficult the reinforcement impregnation. One solution can rely on the use of hybrid yarns where the reinforcement and thermoplastic fibers are mixed together⁴. Different technologies have been developed to produce such yarns that can then be used to produce highly drapeable fabrics². The final composite part is obtained by a thermoforming process, offering the possibility of low-cost and short time cycle manufacturing¹⁻³, which is an important criterion when selecting a manufacturing process in the automotive industry for example. For the production of thick parts, the use of 3D fabrics offers advantages like reducing handling of layers and therefore manufacturing times. 3D textile composites also offer mechanical advantages over classical 2D fabrics: they exhibit, thanks to the use of z-binder better delamination properties, impact and fatigue resistance than conventional composites⁵⁻⁷. Within this study, which is part of the European project 3D light-Trans, advantages of both technologies are combined in a 3D fabric of commingled yarns.

Manufacturing of the textile-reinforced composite parts requires the forming of the reinforcements into the desired shape. The fabric behavior during this forming process is very important since the appearance of defects (wrinkles, yarn misalignment) can affect the mechanical properties and quality of the final part⁸⁻¹⁰. Experimental studies have shown the good drapeability of commingled yarn made fabrics². But their potential is still poorly

understood and numerous choices of weaving architectures or yarns are possible, that is why further investigation of their properties is needed.

Experimental characterization of mechanical behavior of textile materials is difficult, and a large scattering of results is often observed¹¹. To avoid costly trial and error development, numerical approaches can be used. Numerical approaches at the micro¹² and meso¹³⁻¹⁶ scales have been developed to investigate the mechanical behavior and formability of woven fabrics. In meso-scale simulations, CAD models of the fabric unit cell where yarns are modeled as a continuum are used. For roving fabrics, yarns are considered as transversely isotropic material^{13,14,17} with null or roughly estimated lateral contraction during loading (zero longitudinal Poisson's ratio).

To perform realistic meso-scale simulations on fabrics made of commingled yarns, it is important to investigate and model accurately the mechanical behavior, and in particular the tensile behavior, of commingled yarns.

In this paper, a simple protocol to perform yarn tensile tests is proposed and validated. The tensile behavior of commingled polypropylene/glass yarns is then investigated. Influence of specimen length and strain rate are evaluated. Previous studies have shown the influence of weaving damage on the yarn mechanical behavior¹⁸. To consider the real mechanical behavior of yarns inside the fabric, a comparison of yarn tensile behavior before and after weaving (yarns extracted from the fabric) is carried out in order to analyze and quantify the effect of weaving damage. Based on these experimental results, a model describing the specific commingled yarns tensile behavior is proposed. Parameters of this model are identified, paving the way to meso-scale simulations on commingled yarns made fabrics.

Materials and methods

Materials

Different technologies have been developed for the production of hybrid yarns. Thermoplastic can be integrated in the yarn under different forms like powder, staple fibers or filaments. The first main objective when producing hybrid yarns is to obtain a good mixture of components that will lead to a good repartition of matrix and low porosity levels in the composite³. The second important point is that hybrid yarns must be usable in weaving looms to produce fabrics.

Commingling is one of the technologies used to produce hybrid yarns. It relies on the use of air jet texturizing machines⁴. The commingled yarn is obtained using reinforcement and matrix yarns as input. These yarns are opened and their filaments are mixed in the air nozzle. The use of overdelivery (delivery speed of input yarns more important than the take out speed of the commingled yarn) is necessary to perform the commingling. Still, the overdelivery value must be as low as possible especially for reinforcement fibers to avoid significant loss of orientation⁴. This manufacturing process is cost effective and provides a good mixture of matrix and reinforcement filaments in the yarn³. It enables producing yarns with different reinforcement and matrix materials and different fiber volume fraction. The obtained commingled yarns are flexible and can be woven, braided or knitted^{3,5,6}. However, the main drawbacks are that the commingling process can damage fibers and that high counts yarns cannot be produced effectively.

The commingled yarn structure is also highly influenced by the manufacturing process. The use of pressured air leads to the appearance of opened areas and nips (compact areas) along the yarn length (Figure 1). Different kinds of nip structures, corresponding to various repartitions of the reinforcement and matrix filaments, can be observed¹⁹⁻²¹. The types of nips,

their stability, the degree of interlacing (total length of nips divided by the yarn length), the commingling damage and the filaments distribution in the yarn are highly influenced by the chosen commingling parameters: speed, pressure, jet design and overdelivery values. Consequently, the tensile behavior of commingled yarns depends on properties of the used input yarns but also to a large extent on the yarn structure and therefore of the commingling process¹⁹⁻²¹. Investigation of commingled yarns tensile behavior is hence necessary since models developed and used for other types of yarns are not relevant.

Yarns used in this study were manufactured using a 300 tex E-glass fiber yarn (referred to as GF yarn in the following) and 3*32 tex polypropylene (PP) yarns. Overdelivery (OD) used was of 2% for GF and 5% for PP. More details concerning the commingling process can be found in the study of Fazeli et al.²². Yarns are similar to the ones studied by Torun et al.⁴ in terms of input yarn count and GF overdelivery. Final yarn count is approximately 410 tex for a glass fiber volume fraction $V_{GF} = 52\%$. Commingled yarns will be referred to as GFPP yarns in the following;

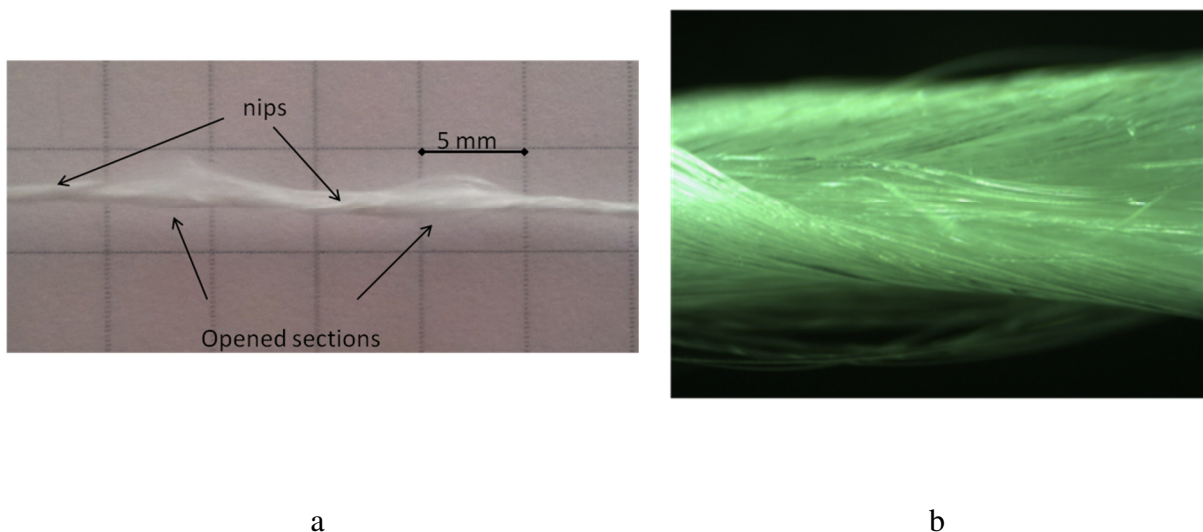


Fig. 1. Commingled yarn: a. Global structure; b. Nip detail

Compared to rovings with roughly rectangular cross section at the end of the yarn production process²³, the commingled yarn section is rather circular or elliptic^{19,24}. Yarn diameter can vary from less than 1 mm in the nips to more than 3 mm in opened areas (see Figure 1(a)). Using the input materials densities (2.54 for GF and 0.91 for PP) and the overdelivery value, the average material section in the GFPP yarns can be estimated to 0.23 mm². This value will be used to calculate yarn's stresses from measured forces in the following.

Within the study, yarns have been used to produce a 3D fabric. The weaving architecture of the fabric is shown in Figure 2. It is composed of five layers of yarns in the weft direction and four in the warp direction. Binding yarns are vertically oriented and interlock just 3 layers of weft yarns. The weaving density of fabric is 240 yarns / 10 cm for weft yarns and 200 yarns / 10 cm for both warp yarns and binding yarns. All yarns used in the fabric are the previously described GFPP yarns.

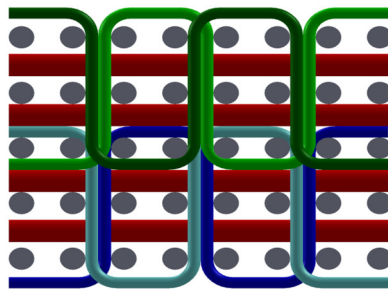


Fig. 2. Weaving architecture of the 3D fabric (grey: weft yarns, red: warp yarns, other colors: binders)

Yarn tensile testing

The goal of this section is to propose and validate a simple protocol to perform reliable yarn tensile tests in order to investigate the commingled yarn's behavior. To the authors' knowledge there are no specific standards for tensile testing of commingled yarns. However, the standard ISO 3341²⁵ giving recommendations for the determination of the breaking force

and elongation of textile glass yarns can be used as a basis. This standard is applied for rovings of less than 2000 tex. The use of 5mN/tex preload, 500 mm specimen length and 200 mm/min testing speed are recommended. During testing, samples must break at 10 mm away from the grips. Reproducibility of results must be investigated by performing at least 10 tests. In the literature, various specimen length and strain rates have been used. The results on different types of yarns have shown that they both can have significant effect on the measured modulus and breaking strength of yarns²⁶⁻²⁹. The goal of these tests is to estimate what will be the yarn behavior within the fabric. In this sense, it has been shown³⁰ that determining yarn's strength at short specimen length is more appropriate. Moreover, during forming, yarns will be subjected to various strain rate conditions. Experimental investigation of the influence of strain rate and specimen length on the commingled yarns tensile behavior is therefore required.

For this purpose, tests on commingled yarns were performed using a 500 mm specimen length and three different crosshead speeds of 5 mm/min (strain rate $\dot{\epsilon} = 1.67 \times 10^{-4} \text{ s}^{-1}$), 50 mm/min ($\dot{\epsilon} = 1.67 \times 10^{-3} \text{ s}^{-1}$) and 500 mm/min ($\dot{\epsilon} = 1.67 \times 10^{-2} \text{ s}^{-1}$) to investigate the strain rate effect. Tests were also performed with a 200 mm specimen length at same strain rates (*i.e* with testing speeds of 2, 20 and 200 mm/min) to evaluate the influence of specimen length on measured parameters. The $1.67 \times 10^{-4} \text{ s}^{-1}$ strain rate was chosen to investigate the quasi-static tensile behavior of yarns. The $1.67 \times 10^{-2} \text{ s}^{-1}$ strain rate corresponds to what could be observed in industrial conditions for composite parts manufacturing while the $1.67 \times 10^{-3} \text{ s}^{-1}$ strain rate was chosen as an intermediary value.

For the sake of simplicity, tests were performed using a universal testing machine (INSTRON 4507) with conventional jaws. Samples were prepared by fixing yarns between thin aluminum plates with glue. A uniform pressure was applied on the plates during at least 24 hours (time

of drying). Aluminum tabs were then directly fixed between the machine jaws for the testing. At least 10 tests were performed in each testing configuration and more when a significant scattering of tensile behavior between samples was highlighted. A 5mN/tex preload was used. When performing tensile tests it is not always possible to rely on displacement data given by the testing machine: when load is applied, machine components or other pieces like aluminum tabs or glue used to fix the samples can deform. As a consequence, displacement given by the machine is not the one to which the sample is subjected. This error can be significant if high loads are reached or if the sample's deformation is low. Another important issue is the clamping: bad clamping conditions can lead to the premature breaking of the samples near the clamping areas due to stress concentration phenomenon. To investigate these issues, optical measurements with marker tracking method were used. Figure 3 shows black markers 50, 100 and 150 mm spaced that were placed on 200 mm long yarn samples. These tests were performed on GF yarns (the 300 tex yarn used as an input for the manufacturing of commingled yarns), since it is not possible to use the marker tracking method with commingled yarns because of their particular structure described in the previous section.

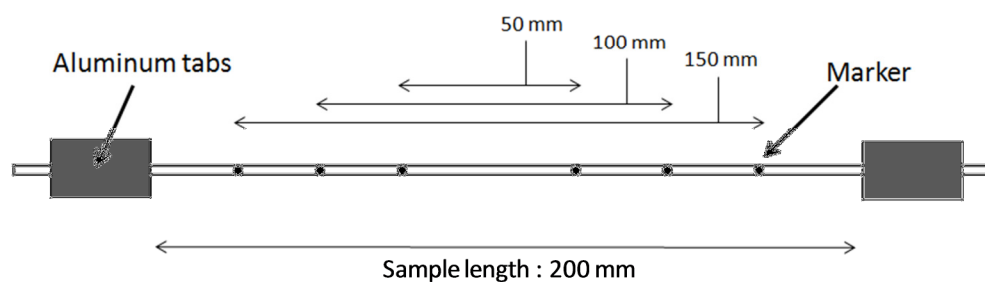


Fig. 3. Schematic representation of a yarn tensile sample with markers for optical acquisition

Positions of markers were registered during testing using a CCD camera (resolution 1280×1024 pixels) and deformations were calculated by the Deftac software³¹. In Figure 4 an example of stress-strain curves of a sample reconstructed using machine displacement and

optical measurements (100 mm spaced markers) shows the very good agreement between the two methods in the loading phase. Average Young’s modulus obtained on seven samples using the machine displacement and the 3 couples of markers in this linear phase are shown in Table 1.

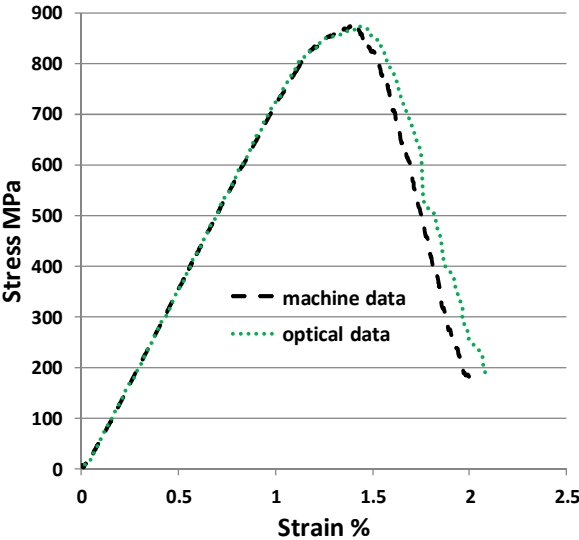


Fig. 4. Tensile curves of a GF yarn obtained using machine and optical measurements

Table 1. GF yarns Young’s modulus calculated by the different methods

	Modulus [GPa]
Optical 50 mm	73.8 ± 1.3
Optical 100 mm	73.5 ± 1.8
Optical 150 mm	73.3 ± 1.2
Machine	72.6 ± 0.6

Results of optical measurements show that the deformation is homogeneous along the yarn length during the loading, and a very good agreement (difference of less than 2%) between Young’s modulus calculated using the machine displacement and the marker tracking method is highlighted. Moreover, the linear behavior in the loading phase and the measured modulus of 73 GPa are in good agreement with the literature for E-glass rovings. These results show that the machine compliance is negligible for GF yarns and therefore that machine

displacement can be used directly to calculate yarn strain. Since GFPP yarns have a lower stiffness compared to GF yarns (as testing results will show in the next section), machine compliance can also be neglected with 200 mm long GFPP yarns, and, as displacements will increase with specimen length, machine displacement can also be used with the 500 mm long samples.

When fibers begin to break inside the yarn, markers progressively disappear and it becomes more difficult to obtain coherent optical measurements. This can be observed in Figure 4 when, after reaching the maximum load, optical and machine strain measurements start to mismatch. Still, observations on samples tend to show that deformation remains homogeneous along the yarn length during the breaking phase and that fiber breakages are not localized near the clamps but homogeneously distributed along the GF yarn length. Due to the more brittle breaking behavior of GFPP yarns, it is possible to observe directly where their breaking occurred (see Figure 5). In most cases, breaking is not localized near clamps, tending to prove that yarns don't break prematurely due to stress concentration phenomenon.



Fig. 5. GFPP yarn after breaking

Results of tensile tests performed on ten GF yarn samples in the same testing configuration (200 mm specimen length, 2 mm/min testing speed) are shown in Figure 6. A very good reproducibility of results in the loading part is highlighted with coefficients of variation of less than 3% for the measured moduli and breaking stress between the different samples.

These results show that the scattering that could be introduced by the testing protocol and manufacturing process of samples is low.

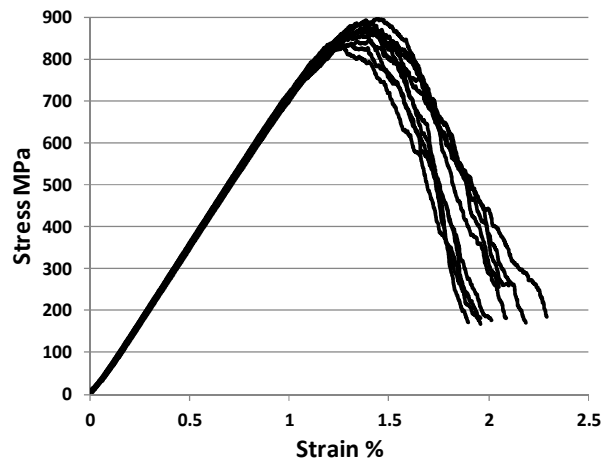
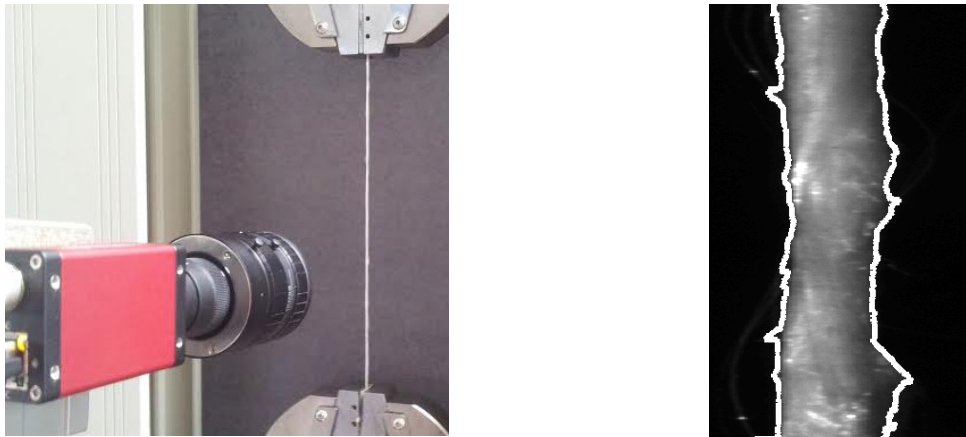


Fig. 6. Repeatability of GF tensile test

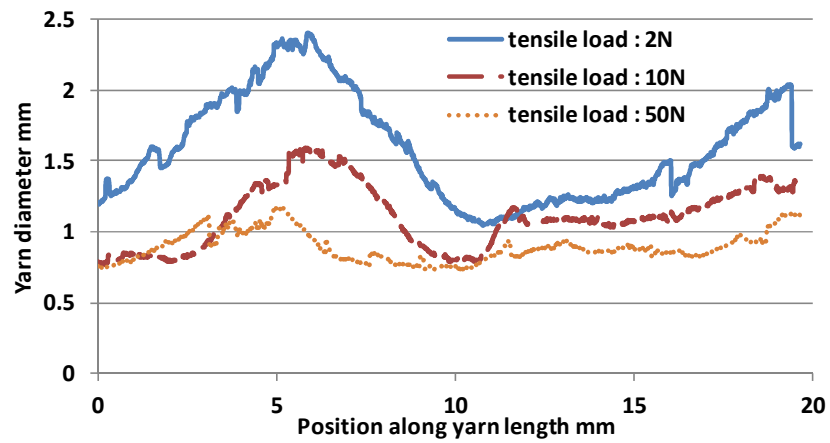
As mentioned, longitudinal Poisson's ratio considered in models describing roving tensile behavior are often roughly estimated or supposed null. In our case, because of the particular structure of commingled yarns it is interesting to see if modifications of the yarn structure under tensile loading conditions can be observed. To do so, pictures were registered using a camera (AVT manta, 2452*2048 pixels and 50 mm zoom lens) during tensile testing (see Figure 7(a)). Obtained images were analyzed using a Matlab program to detect the yarn contours (see Figure 7(b)) and highlight a possible yarn contraction in the transverse direction. An example of result showing the evolution of yarn diameter with increasing tensile load is shown in Figure 7(c).

The presented testing protocol gives, from the preparation of samples to the analysis of testing results, a simple and reliable method to characterize the GFPP yarns tensile behavior. Use of optical measurements and of a dedicated program for yarn contour detection also enables analyzing changes of yarn section during testing.



a

b



c

Fig. 7. a. Tensile testing of GFPP yarn with picture registration; b. Result of yarn contour detection; c. Evolution of yarn diameter with applied tensile load.

Experimental results

In this section, experimental results of tests performed on commingled yarns are presented. These results are discussed and interpreted in details in the section “modeling and discussion”.

Quasi-static tensile behavior of commingled yarns

Results presented are those obtained with the 200 mm specimen length and 2 mm/min testing speed. Figure 8(a) shows the typical quasi-static tensile behavior of a GFPP yarn. At the beginning of loading, a nonlinear behavior is observed. Yarn stiffness gradually increases and the behavior progressively becomes linear, ϵ_{NL} value corresponds to the strain for which behavior becomes linear. Little drops of force corresponding to the opening of unstable nips can be observed (see in black ellipsis in Figure 8(a)). Nips opening might also explain the yarn rotation that can be observed during testing. The behavior remains almost linear up to the brutal break of glass fibers, then the load is taken up by the PP²¹ (see Figure 8(b)).

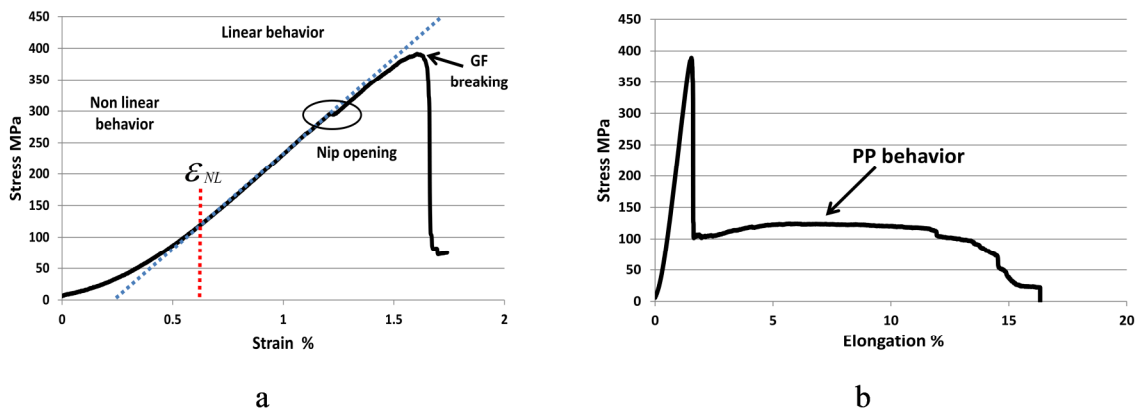


Fig. 8. GFPP tensile behavior: a. First part of tensile behavior and effect of the opening of an unstable nip; b. Global tensile behavior.

There is a significant scatter of tensile properties of GFPP yarns in terms of modulus and breaking strength (Figure 9(a)). The coefficient of variation is more than 10%. Average breaking stress is of 340 MPa corresponding to a breaking load close to 80 N. From preload to maximum strength value, the breaking strain is approximately 1.5%. Average Young's modulus (measured in the linear part of the stress-strain curves) is approximately 30 GPa. A

correlation appears to exist between the modulus of a particular yarn and its breaking strength (see Figure 9(b)); yarns with a higher modulus tending to break at higher loads. It can also be noticed that the ϵ_{NL} value seems to decrease with increasing modulus (see Figure 9(c)). The calculated Spearman's rho coefficients (assessing how well the relationship between two variables can be described using a monotonic function) for both couples of variables are respectively of 0.88 and -0.93. Linear regressions and coefficients of determination are also reported in the two figures.

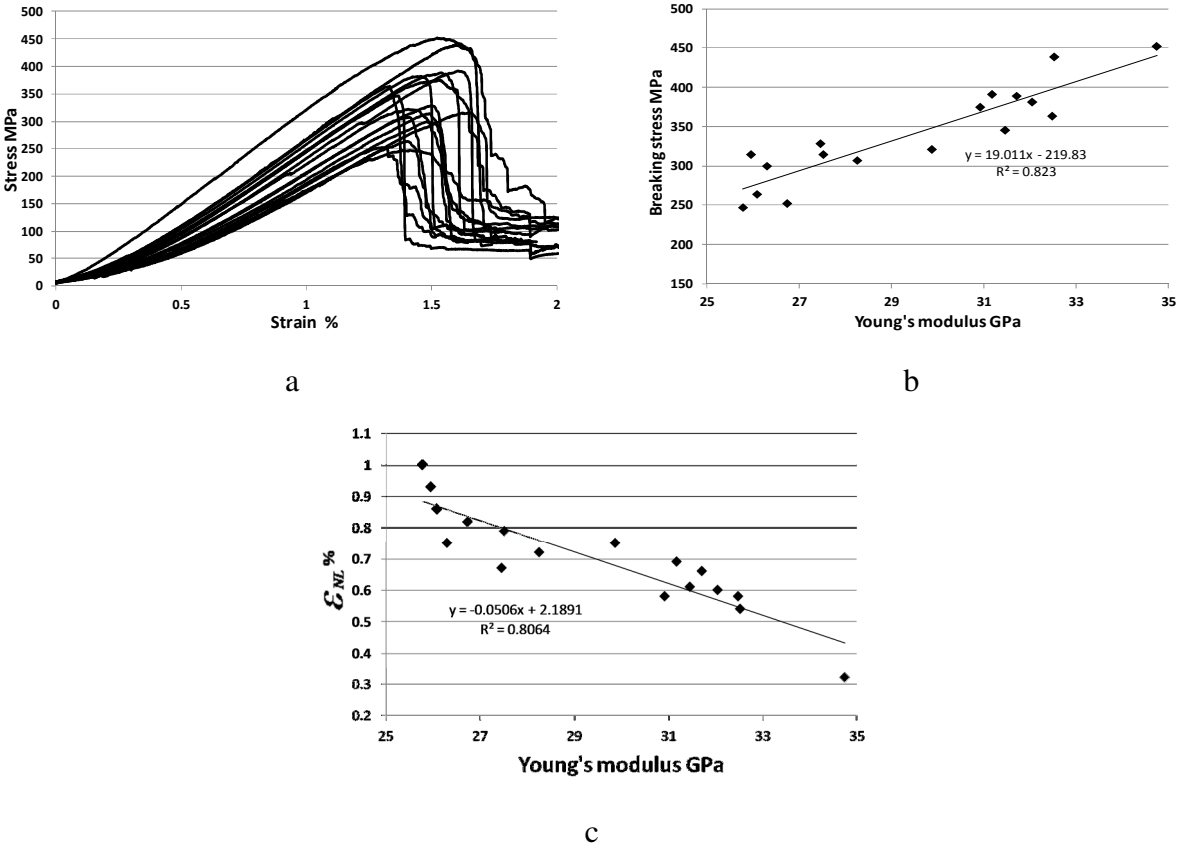


Fig. 9. a. Scattering of GFPP yarns tensile behavior; b. Breaking stress-Young's modulus correlation; c. Size of nonlinear behavior (ϵ_{NL} value) -Young's modulus correlation

Pictures showing the evolution of yarn aspect with increasing applied tensile load are displayed in Figure 10. A reduction of yarn diameter can be observed. The Evolution of yarn's diameter in the nips and opened areas highlighted in Figure 10 are plotted in Figure 11, superposed with yarn tensile behavior. It can be observed that the yarn diameter tends to

become homogenized when load increases. Decrease of yarn diameter is particularly significant during the initial nonlinear behavior phase in the opened area. When behavior becomes linear, the yarn diameter keeps decreasing but much more slowly.

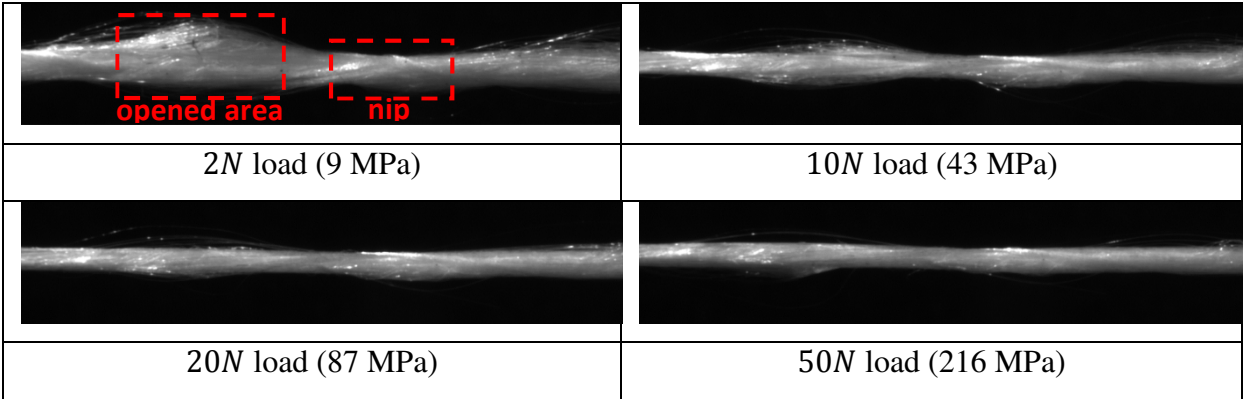


Fig. 10. Evolution of yarn aspect with increasing load

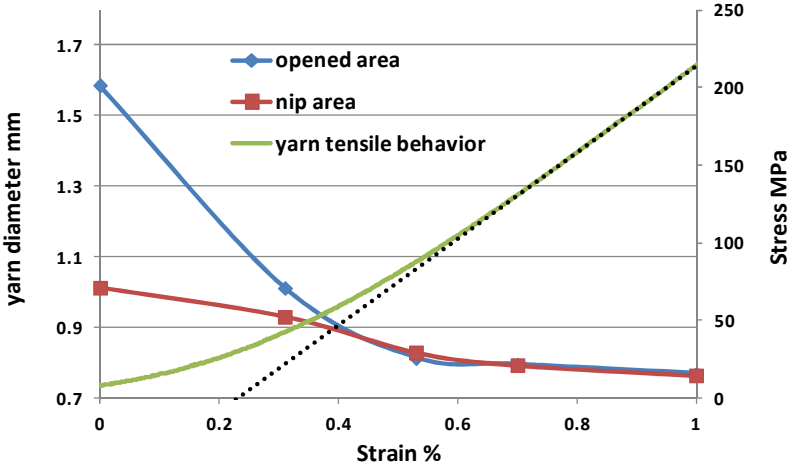


Fig. 11. Decrease of yarn diameter in nips and opened areas superposed with yarn tensile behavior

Effects of strain rate and specimen length

Average values and standard deviation of measured moduli, breaking strength and strain of GFPP samples for the two specimen lengths and the three strain rates are shown in Table 2.

For comparison results obtained for GF yarns in the same testing configurations are also reported. Average GFPP tensile curves for the 200 mm specimen length at the 3 strain rates are shown in Figure 12. The first parts of the stress-strain curves are almost superposed. A pronounced increase of breaking strength with strain rate is highlighted. For the two specimen lengths, the average breaking strength at $1.67 \times 10^{-2} \text{ s}^{-1}$ is more than 60% higher than the one measured at $1.67 \times 10^{-4} \text{ s}^{-1}$ (Table 2). For GF yarns this increase is only of 20%. For the $1.67 \times 10^{-4} \text{ s}^{-1}$ strain rate, influence of specimen length on breaking strength appears to be quite similar for GF and GFPP yarns, average breaking strength being approximately 6% higher with the 200 mm specimen length compared to the 500 mm specimen length. This difference remains the same for the three strain rates in the case of GF yarns but seems to increase slightly with strain rate for GFPP (13% difference at $1.67 \times 10^{-2} \text{ s}^{-1}$ strain rate). Young's modulus of GFPP yarns is close to 30 GPa. It increases slightly with strain rate and decrease slightly with specimen length. For GF yarns it remains approximately the same in all testing configurations. With high strain rates, a progressive decrease of stiffness of GFPP yarns is observed before yarn break. In some cases, load is not taken up by PP fibers after the breaking of glass fibers (total break of the yarns), this was mainly observed for the 500 mm specimen length at high strain rates.

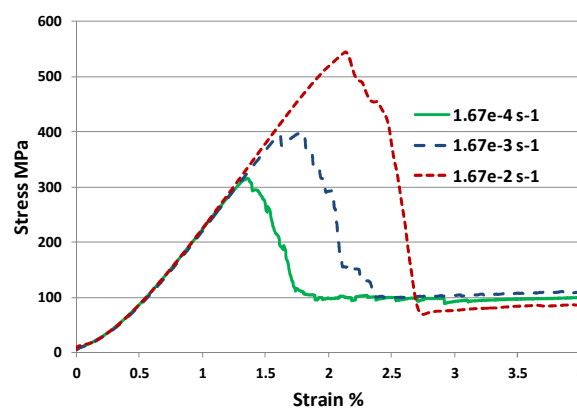


Fig. 12. Average stress-strain curves of GFPP yarns for the 3 strain rates (200 mm gauge length)

Table 2. Results in all testing configurations for GF and GFPP yarns.

Gauge length [mm]		200			500		
Testing speed [mm/min]		2	20	200	5	50	500
Strain rate [s^{-1}]		1.67×10^{-4}	1.67×10^{-3}	1.67×10^{-2}	1.67×10^{-4}	1.67×10^{-3}	1.67×10^{-2}
GF	Young's modulus [GPa]	73.6 ± 0.9	73.1 ± 1.0	73.9 ± 1.1	73.9 ± 1.6	74.1 ± 1.5	72.9 ± 2.1
GFPP		29.3 ± 2.9	30.5 ± 2.1	30.8 ± 1.9	28.6 ± 1.9	29.4 ± 2.0	30.6 ± 1.1
GF	Breaking strain [%] (strain 0 at preload)	1.35 ± 0.06	1.54 ± 0.03	1.61 ± 0.05	1.24 ± 0.06	1.39 ± 0.03	1.51 ± 0.03
GFPP		1.47 ± 0.10	1.92 ± 0.18	2.40 ± 0.17	1.42 ± 0.12	1.80 ± 0.14	2.47 ± 0.22
GF	Breaking stress [MPa]	852 ± 22	948 ± 22	1024 ± 32	819 ± 29	901 ± 20	968 ± 16
GFPP		340 ± 60	455 ± 51	589 ± 33	319 ± 48	408 ± 51	514 ± 43
GF	Breaking load [N]	102.2 ± 2.6	113.8 ± 2.6	122.9 ± 3.8	96.7 ± 3.4	106.4 ± 2.3	114.2 ± 1.9
GFPP		78.6 ± 13.8	105.0 ± 11.7	136.0 ± 7.6	73.7 ± 11.2	96.6 ± 11.7	118.7 ± 9.9

Torun⁴ performed tensile tests on quite similar yarns with a 500 mm specimen length and a 25 mm/min testing speed. Results show a modulus of less than 20 GPa and a breaking force of approximately 45 N. These values are quite low compared with our results. Origin of these differences could come from the different commingling process of yarns or from the different tensile testing protocol.

Figure 13 presents the evolution of breaking strength for the two specimen lengths as a function of the strain rate logarithm for GF and GFPP. Breaking load of GFPP yarns is of the same order of magnitude as GF one. Still it can be observed that for quasi-static loading conditions, GFPP yarn's breaking load is lower than GF ones but becomes greater at high strain rates.

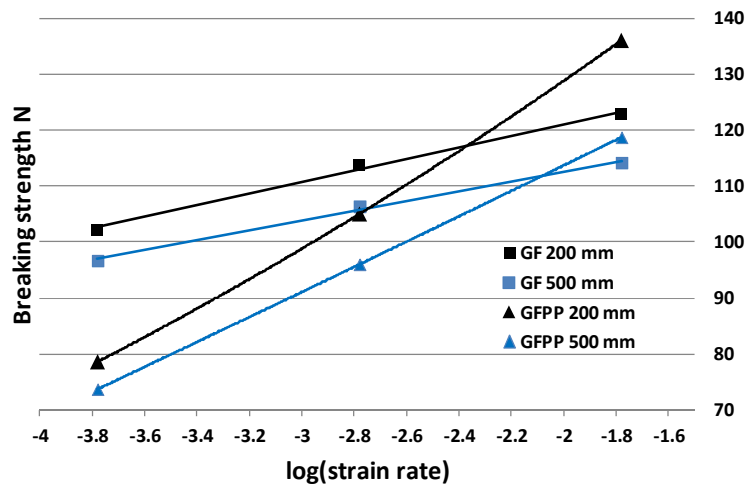


Fig. 13. Influence of strain rate and gauge length on the breaking load of GF and GFPP yarns

Influence of weaving damage

Lee et al.¹⁸ have investigated the weaving damage effect on tensile behavior of glass yarns during 3D fabrics weaving. Tensile tests performed on glass yarns after the different weaving steps have shown that their stiffness remains almost unchanged while their tensile strength can be decreased by up to 30% at the end of the process. This damaging can play a significant role in the possible breaking of yarns during forming process. Damage is mainly attributed to the abrasion between yarns and weaving machine components during the different weaving steps. In our case, as mentioned above, the structure and tensile behavior of commingled yarns are different when compared to rovings. It is therefore interesting to compare the weaving damage effect on commingled yarns with the results of Lee et al. To do so, weft, warp and binding yarns have been extracted from 3D fabric presented in Figure 2 and tested (specimen length of 200 mm and testing speed of 2 mm/min). Table 3 gives the measured moduli, breaking strengths and strains for the 3 groups of yarns and their variations compared to values obtained for yarns before weaving. The average tensile curves of yarns are compared in Figure 14.

[Insert Table 3]

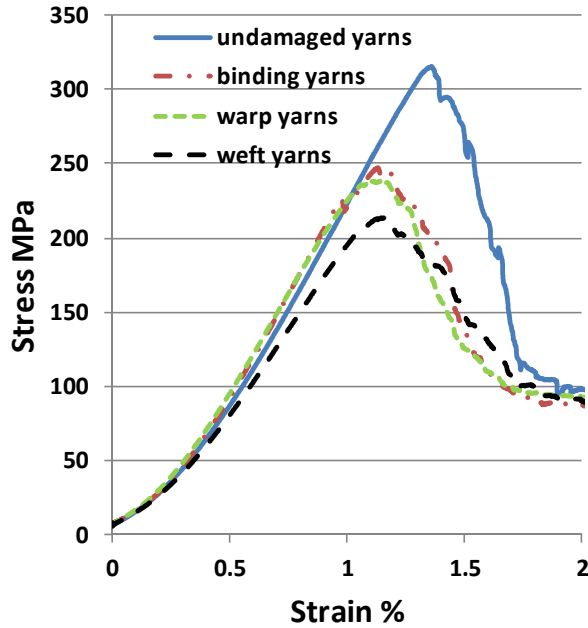


Fig. 14. Average tensile behavior of damaged and undamaged GFPP yarns

Table 3. Mechanical parameters of damaged yarns and comparison with undamaged yarns values in parenthesis

	Breaking strain [%]	Breaking strength [N]	Breaking stress [MPa]	Modulus [GPa]
Binding yarns	1.24 \pm 0.15 (-16 %)	66.9 \pm 8.7 (-15 %)	290 \pm 38 (-15 %)	29.4 \pm 2.7 (+ 1 %)
Warp yarns	1.21 \pm 0.13 (-17 %)	61.4 \pm 8.1 (-22 %)	266 \pm 35 (-22 %)	28.2 \pm 2.0 (- 3 %)
Weft yarns	1.31 \pm 0.15 (-11 %)	56.3 \pm 20.9 (-28 %)	244 \pm 90 (-28 %)	24.2 \pm 8.3 (- 17 %)

A decrease of breaking strength is observed for the three groups of yarns. Results show that weft yarns are the most damaged, with a decrease of 28% of breaking strength and also a decrease of 17% of modulus. A more significant scattering of weft yarn's breaking strength and modulus is also observed. Damage seems to vary significantly from one yarn to the other. In this sense, observations on weft yarns show that on some samples a non-negligible number of fibers are broken. It has been shown¹⁸ that fibers can be broken during the weft-insertion

stage when yarns pass through a guide. This damaging can explain the decreased breaking strength and modulus observed on weft yarns.

The modulus of warp and binding yarns is not modified; they are similarly damaged by the weaving process, with a decrease of breaking strength of respectively 15 and 22%. Their average tensile behavior is very similar (Figure 14).

As apparent from Figure 14, the initial nonlinear behavior (ϵ_{NL} value) is less pronounced for warp and binding yarns as compared to undamaged yarns. During the weaving process, warp and binding yarns pass through a tensioning device to provide adequate tension for the shedding stage¹⁸. They are therefore subjected to several tensioning cycles. To a lesser extent, during the insertion stage, weft yarns can also be subjected to tension. It is in this sense interesting to investigate the tensile behavior of GFPP yarns under cyclic loading. For this purpose, cyclic loading tests have been performed on undamaged yarns (testing configuration 200 mm, 2 mm/min), and an example of result is shown in Figure 15.

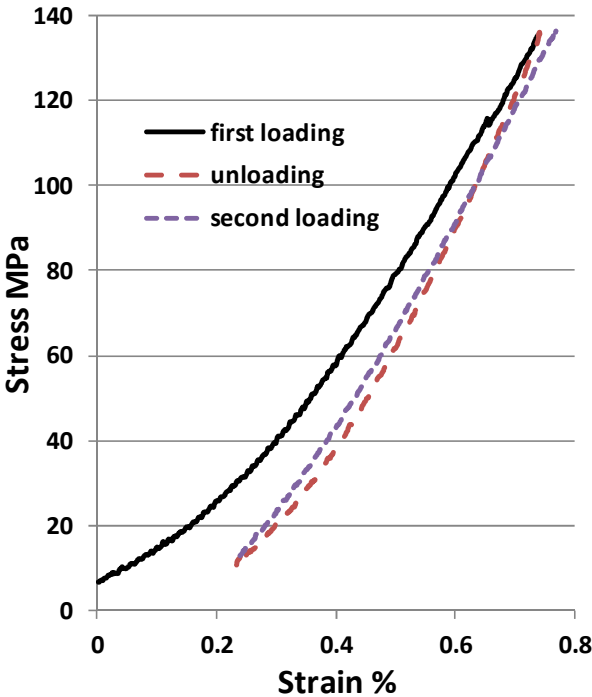


Fig. 15. Cyclic testing of a GFPP yarn

After the first loading cycle, a permanent deformation is highlighted. The nonlinear phase of the second loading is reduced compared to the one of the first loading and Young's modulus observed during the second loading also appears slightly more important. An increase of Young's modulus of up to 10% after few loading cycles is observed: on the testing result example presented in Figure 16, the maximum modulus reached during the first loading is 26.7 GPa, it increases in the next two loadings to stabilize at a value of 29.3 GPa. This phenomenon can be attributed to the progressive alignment of fibers along the loading direction by the first loadings. If a high number of cycles are performed, it can lead to the premature breaking of the yarn (see Figure 16). A possible explanation could be that damage by inter-fiber friction occurs in the yarn because of the fiber interlacing and complex stress repartition in the nip areas.

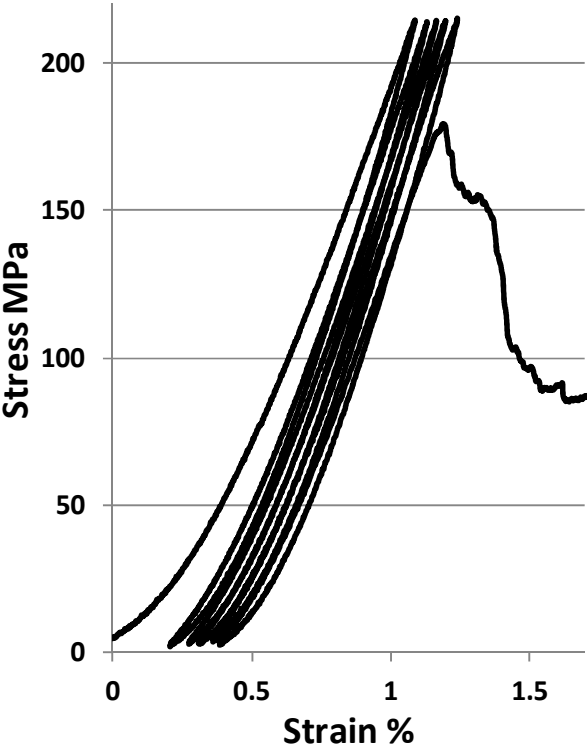


Fig. 16. Premature breaking after multiple cyclic loadings

During the weaving process, two effects have therefore to be considered. The first one is abrasion between yarns and weaving machine components leading to fiber damage and fiber breakage (observed for weft yarns) that can explain the decrease of yarn's breaking strength and stiffness. On the other hand, tensioning of yarns during the weaving process can lead to a smaller initial nonlinear behavior, an increase of modulus and a decrease of breaking strength. This mechanism can explain the smaller initial nonlinear behavior of warp and binding yarns. Still, no increase of their Young's modulus was observed (Table 3), maybe because loads experienced by these yarns during the weaving process are less significant than those used for cyclic testing. The possible increase of modulus can also have been compensated by fiber breakage caused by abrasion with components like for weft yarns. Both fiber damage and breakage due to abrasion with machine components and multiple tensioning of yarns during weaving can explain the breaking strength decrease of warp and binding yarns.

Weaving induces a significant decrease of yarn's breaking strength and also a stiffness decrease for weft yarns. This can lead to yarn breakage during the forming process and decreased mechanical properties of the final composite parts. An accurate knowledge of tensile stresses to which yarns are subjected during weaving, and an investigation of their tensile properties after each weaving step would help to better understand the effects of weaving. One solution to avoid fiber damage could rely in the use of hybrid yarns where matrix filaments are placed around the reinforcement fibers to protect them from abrasion. On the other hand, due to the poor mixture of filaments in such yarns, the impregnation of reinforcement fibers by matrix could be more difficult⁴.

The main consequences of these results is that, even if only just one type of yarn is used to weave the fabric, due to the non-equivalent weaving damage effect on warp, binding and weft yarns, their tensile behavior once inside the woven fabric will not be the same. It is therefore

important to perform tensile tests on yarns extracted from the fabrics to estimate the influence of weaving in order to take into account this aspect in models describing the yarn tensile behavior.

Modeling and discussion

The goal of this part is to propose a model to describe correctly the GFPP stress-strain tensile behavior and to identify the influence of specimen length, strain rate and weaving damage on parameters of this model. Few results can be found in the literature concerning this topic. Torun⁴ has proposed a model to estimate Young's modulus of commingled yarns, still there are not known results to describe the whole stress-strain behavior.

First goal is to explain the initial nonlinear behavior of commingled yarns. Main contribution to the yarn's tensile behavior can be attributed to GF fibers; their modulus being much higher than PP fibers modulus. As detailed in section 2.a, the commingled yarn structure is composed of nips and opened areas. In opened areas, some fibers are initially almost straight, while others are buckled. Different mechanisms can explain the initial nonlinear behavior. Torun⁴, made the assumption that all GF overdelivery is consumed in nips and therefore that glass fibers are straight in opened areas, whereas PP overdelivery is consumed in both nips and opened areas. It can be supposed that initially, it is not quite true and that glass fibers can be slightly buckled in opened areas. Moreover, a fiber buckled in a particular opened area can possibly be straight in another opened area, as schematized in Figure 17. If a fiber starts to undergo significant tension in a particular portion of its length (where the fiber is straight) but is not loaded in another one (where the fiber is buckled), it can be supposed that the fiber could move relatively to the others to equilibrate the carried load on its whole length. Of course this mechanism will be strongly linked to the intermingling of fibers in nips and to the

friction between fibers. Moreover, structure of the commingled yarn in nips is supposed similar to the one observed in twisted yarns⁴. Results presented by Chudoba²⁷ tend to show that once twisted, yarns have a more extended initial nonlinear behavior than untwisted. This can be attributed to the reorganization of the twisted yarn structure when subjected to tensile loading (decrease of yarn section and increase of yarn packing factor). Cyclic testing results highlighting a permanent deformation after the first loading and a significant decrease of nonlinear behavior in the next loadings tend to confirm these phenomena of reorganization of the yarn structure.

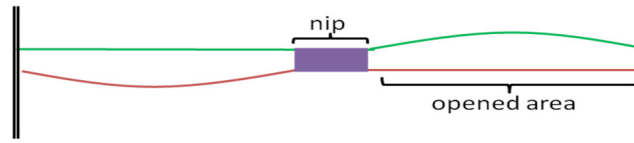


Fig. 17. Simplified representation of the yarn structure

A model describing the influence of delayed activation of fibers in the case of rovings has been proposed and validated by Chudoba³². The slack of filament i being noted θ_i , when a roving of length L is subjected to a displacement u the deformation of fiber i can be written³²:

$$\varepsilon_i = \frac{e - \theta_i}{1 + \theta_i} \quad (1)$$

With $e = \frac{u}{L}$ the yarn deformation. Assuming a linear-elastic and brittle response of fibers of modulus E and a large number of fibers in the roving, the stress-strain behavior can be expressed by:

$$\sigma_\theta(e) = E \int_\theta \frac{e - \theta}{1 + \theta} dG_\theta(\theta) \quad (2)$$

With $G_\theta(\theta)$ the cumulative density of delayed activation that can be extracted from experimental results by constructing the normalized derivative of the stress-strain curve.

It is interesting to see if this model can also describe the tensile behavior of commingled yarns since the different reorganization mechanisms of yarn structure presented above can be supposed to act like as slack of fibers. To do so, it is necessary to evaluate the cumulative density $G_\theta(\theta)$ in the case of commingled yarns. It is clear that predicting the shape of this curve from direct analyze of the very disordered GFPP yarn structure is a very difficult issue. For the sake of simplicity, a predefined shape of curve is proposed and fitted on the experimental curve. Modulus of the commingled yarn is referred to as E_{GFPP} . Evaluation of this parameter will be discussed in the next paragraph.

The simplest model can be formulated by supposing a uniform activation density:

$$G_\theta(\theta) = \frac{\theta}{\theta_{max}} 1_{[0, \theta_{max}[}(\theta) + 1_{[\theta_{max}, \infty[}(\theta) \quad (3)$$

$$\text{With } 1_{[a, b[}(\theta) = \begin{cases} 1 & \text{if } a \leq \theta < b \\ 0 & \text{else} \end{cases}$$

The stress-strain tensile behavior can then simply be expressed as³²

$$\sigma_\theta(e) \approx \frac{E_{GFPP}}{\theta_{max}} [(e + 1) \ln(1 + e) - e] \quad 0 \leq e \leq \theta_{max} \quad (4)$$

$$\sigma_\theta(e) \approx \frac{E_{GFPP}}{\theta_{max}} [(e + 1) \ln(1 + \theta_{max}) - \theta_{max}] \quad e \geq \theta_{max} \quad (5)$$

In Figure 18 the cumulative density of delayed activation obtained from the average experimental curve in configuration 200 mm-2 mm/min for undamaged yarns is shown. From an initial value close to 0.3 at the preload state, cumulative density increases quite linearly up to 0.8 and then more slowly to finally stabilize. Experimental values are shifted so that they fit with the uniform activation density model.

Advantage is that in addition to E_{GFPP} value, only one parameter (θ_{max}) needs to be identified. But the experimental curve is not perfectly described, especially when the

cumulative density come close to 1 as seen in Figure 18. Still, the experimental and modeled stress-strain curves (identified value $\theta_{max} = 0.008$) are in quite good agreement (Figure 19). Of course it is possible to better describe the cumulative density activation using for example piecewise linear function³².

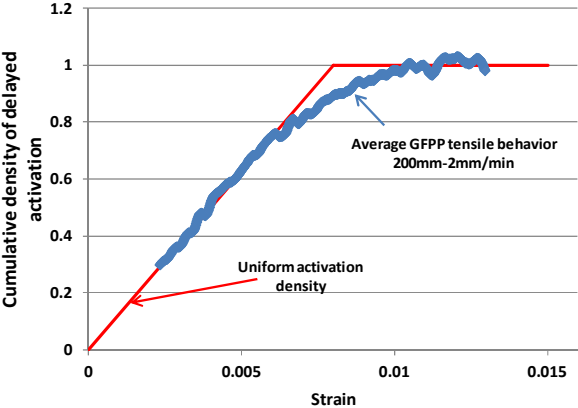


Fig. 18. Cumulative density of delayed activation

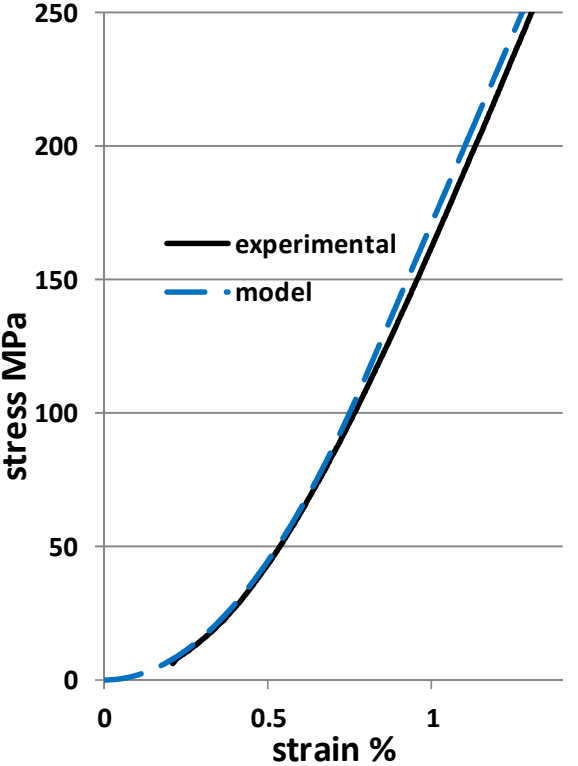


Fig. 19. Model/experimental result comparison.

As mentioned above, initial nonlinear behavior is only slightly influenced by both specimen length and strain rate. Parameters identified on one testing configuration can be used on other testing configuration just taking into account the slight variations of E_{GFPP} value with strain rate and specimen length. Using Equation 3, initial value of the cumulative density of activation is supposed null and therefore, the initial slope of the stress-strain curve is also null. It seems appropriate to model results presented in section 3.b (tensile behavior of yarns obtained after the commingling process) but a non-null initial modulus should be considered for yarns that have been subjected to previous cyclic loadings and therefore possibly to yarns after the weaving process.

A simple rule of mixture can give an estimation of the Young modulus E_{GFPP} of a GFPP yarn in which all fibers would be parallel and perfectly aligned along the yarn direction. With a modulus of 73 GPa for GF as identified with tensile tests and a modulus of 1.5 GPa for PP (according to literature); given volume fraction values of GF and PP, the maximum modulus $E_{max} \approx 38$ GPa could be expected for such yarns. Actually, even if it can be supposed that after the nonlinear behavior phase glass fibers are straight and aligned following the yarn direction in opened areas, they remain intermingled in nips areas. E_{GFPP} is therefore less than E_{max} , as shown by experimental results highlighting an average modulus of 30 GPa (see Table 2).

Torun⁴ has proposed a model to estimate Young modulus of commingled yarns. The corresponding mechanical model is schematized in Figure 20.

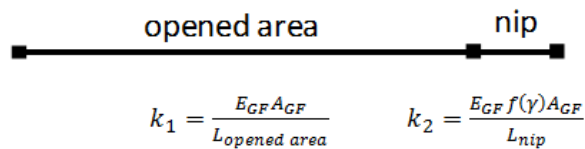


Fig. 20. Mechanical model of GFPP yarn

In this model, assumption is made that glass fibers are straight in opened areas and structure of the commingled yarn in nip areas is supposed similar to the one observed in twisted yarns. Influence of PP on the behavior is neglected. The total length of the yarn is:

$$L = L_{\text{opened area}} + L_{\text{nip}} = (1 - x)L + xL \quad (6)$$

With x the degree of interlacing.

In nips, twisting of fibers is taken into account by introducing a function $f(\gamma)$ (with γ the twist angle) which describes the loss of modulus due to twisting. A_{GF} is the glass fiber material section in the yarn. Stiffness k of the commingled yarn is deduced using $\frac{1}{k} = \frac{1}{k_1} + \frac{1}{k_2}$ and its Young's modulus is $E_{GFPP} = \frac{kL}{A}$ with A the total material section in the yarn.

Therefore, the final expression of the Young modulus is:

$$E_{GFPP} \approx \frac{E_{\max}}{1+x\left(\frac{1}{f(\gamma)}-1\right)} \quad (7)$$

γ angle is obtained with⁴

$$\gamma = \cos^{-1}\left(\frac{1}{1+\frac{OD_{GF}}{x}}\right) \quad (8)$$

In the study of Torun⁴, assumption is made that all GF overdelivery has been consumed in nips. But, as discussed earlier, part of the GF overdelivery can also be consumed in opened area. Only the part consumed in nips, which will be noted $OD_{GF \text{ nip}}$ should be taken into account in Equation 8. Torun⁴ used $f(\gamma) = \cos^2(\gamma)$ and obtained a value of E_{GFPP} only slightly lower than E_{\max} . The difference between experimental results and value obtained using the model is explained by the influence of commingling damage. But, in our case, observations on yarns after the commingling process (Figure 1(b)) have shown that only a

small number of fibers appeared to be broken. Moreover, small modifications of the model could lead to a better approximation of the modulus:

-Especially for high twist angles, the \cos^2 model can underestimate significantly the influence of twist³³.

-In twisted yarns, the twist angle θ of a fiber depends on its radial position³³: $\tan(\theta) = \frac{2\pi r}{h}$, with r the radial position of the fiber in the yarn and h the yarn length for one turn. Models like the \cos^2 one are applied with angle α corresponding to the twist angle of fibers at the most outer layer (surface twist angle) of the twisted yarns. This angle is given by $\tan(\alpha) = \frac{2\pi R}{h}$, with R the yarn radius. The average fiber twist angle θ_{mean} in the yarn is therefore less than α and is given by³⁴:

$$\theta_{mean} = \alpha + \frac{\alpha}{\tan^2 \alpha} - \frac{1}{\tan \alpha} \quad (9)$$

Angle γ calculated with Equation 8 corresponds in fact to the average twist angle of fibers due to overdelivery i.e. to the θ_{mean} value. Angle used in Equation 7 shouldn't therefore be γ but rather angle α calculated using Equation 9 with $\theta_{mean} = \gamma$.

Main difficulty comes from an accurate evaluation of parameters used in the model. Calculation were made using $x = 0.1$ and $OD_{GF\ nip} = 1.5\%$. An average twist angle of 30° is obtained with Equation 8, corresponding to a surface twist angle $\alpha \approx 42^\circ$. Few experimental results investigating the decrease of modulus with such high angles are available, still extrapolating average results presented by Rao³³, value $f(\alpha) \approx 0.3$ can be estimated. Using Equation 7 a value of $E_{GFPP} \approx 31\ GPa$ is obtained giving a good estimation of the commingled yarns modulus.

From hypothesis of this model it can be supposed that scattering of GFPP yarn's properties shown in Figure 9(a) can be explained by the variability of yarn structure due to the commingling process: the number, length and types of nips along the yarn length can vary from one sample to the other leading to variations of χ and $OD_{GF\ nip}$ values, and as a consequence to a scattering of size of the initial nonlinear behavior and modulus.

The decrease of yarn section in opened areas during loading can be attributed to the alignment of fibers along the yarn as they start to take load. In nips, twist of fibers will also leads to a decrease of yarn section³⁵, which is experimentally confirmed in Figure 11. Results presented in Figure 11 can be used to estimate the average decrease of yarn section but further work would be necessary to investigate more precisely transverse behavior in nips and opened areas. In meso-scale models, where yarns are modeled as a continuum, this transverse behavior should be taken into account by considering a non-null longitudinal Poisson's ratio.

No models that could allow estimating the commingled yarn's breaking strength and failure mechanisms have been found in the literature, but results and models are available for twisted yarns³³ and rovings³⁶⁻³⁸. Results on twisted yarns show that, depending on the material, a low yarn twist leads to an increase of breaking strength compared to an untwisted yarn, the maximum strength being reached for angles close to 7° . This effect can be attributed to the fragmentation process i.e. a fiber can break in the yarn but its fragments will continue to carry load³⁵. When the angle is more important, typically more than 15° , yarn's breaking strength decreases compared to the one of untwisted yarns. Twist angle calculated in nip areas using the model described above is greater than 15° . Therefore, neglecting the influence of PP, in quasi-static loading conditions, GFPP yarns should break in the nip areas with a lower breaking force than the GF roving one. In this sense, results presented in Figure 9(b) show

that yarns with an important modulus (so with a smaller number of nips or an average twist angle in nips less than the average) are also those that have the highest breaking strength in quasi-static loading conditions. Presence of nips results in the fact that deformation is not homogeneous along the yarn length. Considering again the mechanical model described in Figure 20, and using the same values of $f(\alpha)$ and x , if the commingled yarn is subjected to a displacement speed \dot{u} , displacement speeds in the opened areas (subscript 1) and in nips (subscript 2) are:

$$\dot{u}_1 = \frac{\dot{u}k_2}{k_1+k_2} \approx 0.73\dot{u} \quad (10)$$

and

$$\dot{u}_2 = \frac{\dot{u}k_1}{k_1+k_2} \approx 0.27\dot{u} \quad (11)$$

Corresponding yarn's strain rates in these zones are therefore:

$$\dot{\epsilon}_1 = \frac{\dot{u}_1}{L_1} \approx \frac{0.67\dot{u}}{0.9L} \approx 0.81\dot{\epsilon} \quad (12)$$

and

$$\dot{\epsilon}_2 = \frac{\dot{u}_2}{L_2} \approx \frac{0.27\dot{u}}{0.1L} \approx 2.7\dot{\epsilon} \quad (13)$$

In opened areas, as fibers are straight, fiber's strain rate will be $\dot{\epsilon}_1 = \dot{\epsilon}_1 = 0.81\dot{\epsilon}$. In nips, strain rate for a fiber with twist angle θ will be $\dot{\epsilon}_2(\theta) = \dot{\epsilon}_2 \cos^2(\theta)$ ³³. Using the average twist angle value of 30° calculated above, average fiber's strain rate $\dot{\epsilon}_2 \approx 2\dot{\epsilon}$ is obtained in nips. Therefore, when $\dot{\epsilon}$ is increased, breaking strength of GFPP increases more rapidly than the one of GF, because, in nips areas where the GFPP yarn is the weakest, the local fiber's strain rate is more important than the global strain rate to which is subjected the yarn. When high strain rates are reached, yarn could start to break preferentially in opened areas, where strain

rate is lower than in nips areas. As there is no twist in opened areas, fragmentation process can possibly explain that the breaking force of GFPP becomes even greater than the one of GF at high strain rates. The presence of PP could also play a role.

The model described above allows a good description of commingled yarn's tensile behavior up to linear-behavior part. In quasi-static loading conditions, it is possible in first approximation to describe the full stress-strain curve of a particular GFPP yarn using the previously proposed model and assuming a brittle failure of the yarn (see Figure 21(a)), load being then taken up by PP. Still, the stress-strain curve peak is not well described and this model is not adapted for high strain rates where a progressive loss of linearity can be observed before yarn breaking.

It has been shown³⁶⁻³⁸ that roving's tensile behavior can be described in first approximation using Weibull model by:

$$\sigma(e) = Ee \times \exp^{-L\left(\frac{e}{e_0}\right)^m} \quad (14)$$

Where L is the roving length, E is the fiber modulus and e_0 and m are respectively the scale and shape parameters of the Weibull distribution. This expression is obtained under the weakest link hypothesis based on the assumption that failure of fibers is due to the presence of defects. With increasing fiber length L , the probability of presence of severe defects along the fiber increases, leading to a decrease of its breaking stress.

It can be shown that, slightly modifying this model, it is possible to reproduce the average GFPP yarn's stress-strain tensile curve. The following expression is proposed:

$$\sigma(e) \approx \sigma_\theta(e) \exp^{-L\left(\frac{e}{e_0}\right)^m} + \sigma_{PP} \left(1 - \exp^{-L\left(\frac{e}{e_0}\right)^m}\right) \quad (15)$$

Where $\sigma_{\theta}(e)$ is the previously identified model which describes stress-strain curve up to the linear behavior. The second part of the equation describes the fact that load is taken up by PP fibers when a GFPP yarn breaks. e_0 and m are linked to the breaking strain and to the scattering of tensile properties of GFPP yarns. Parameters have been identified on results obtained for undamaged yarns in testing configuration 200 mm - 2 mm/min $\sigma_{PP} = 100$ MPa, $e_0 = 0.0164$ and $m = 17$) and allow a correct description of the full stress-strain behavior as illustrated in Figure 21(b).

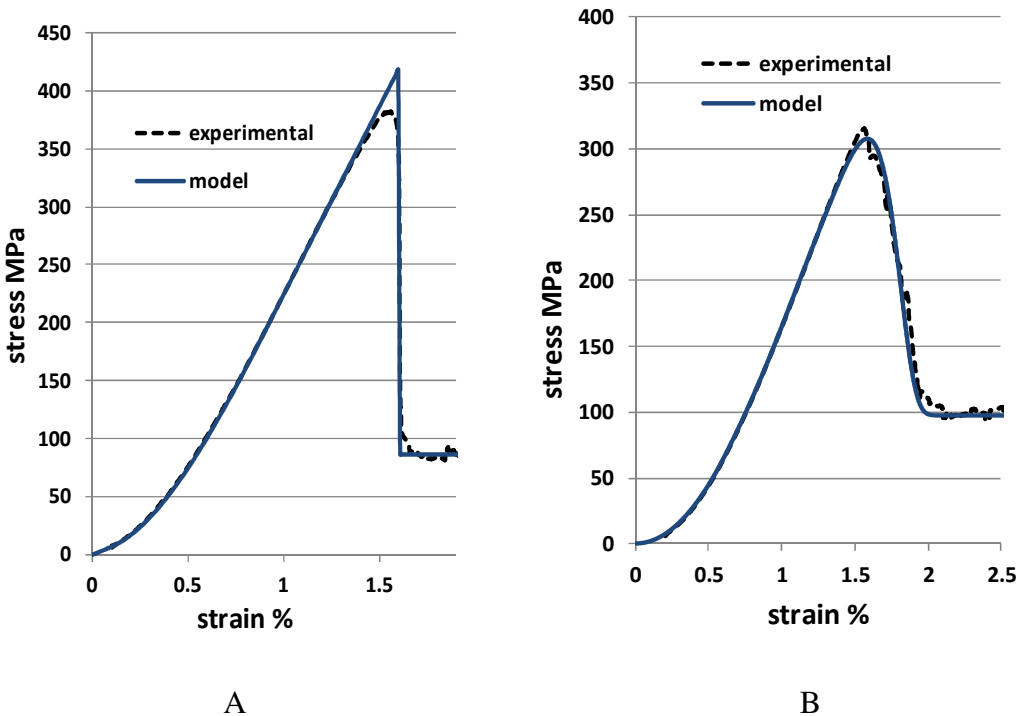


Fig. 21. Model/experimental results comparison: a. Quasi-static behavior of a GFPP yarn; b. Average tensile behavior, undamaged yarns 200 mm-2 mm/min

Assuming that e_0 and m do not depend on L , the model explains the decrease of breaking strength of approximately 7% between 200 mm and 500 mm specimen lengths, which is in good agreement with experimental results obtained in quasi-static loading conditions. Of course e_0 value will increase with strain rate and the values of e_0 and m will decrease for yarns damaged by the weaving process since it leads to a decrease of tensile strength and a

more significant scattering of yarn's tensile properties. Further work is necessary to identify behavior of yarns once inside the fabric and particularly length L that would have to be considered in this case.

Conclusion

In this paper, a simple protocol to perform yarn tensile tests is proposed and validated. Results obtained on commingled GFPP yarns highlight a nonlinear behavior. Influence of both specimen length and strain rate on the yarn's tensile behavior are investigated. A significant increase of breaking strength with increasing strain rate is observed. Young modulus of GFPP yarns is close to 30 GPa. It increases slightly with strain rate and decrease slightly with specimen length. Tests performed on yarns extracted from a 3D fabric show the influence of weaving on the stress-strain behavior of yarns: a significant decrease of breaking strength for yarns in both weft and warp direction is highlighted. Weft yarns were found to be the most damaged with also a decrease of Young modulus of 17%. The extent of nonlinear behavior is slightly reduced on yarns extracted from the fabric compared to undamaged yarns. This can be attributed to realignment of fibers within the yarns induced by cyclic tensile loadings experienced by yarns during weaving. Using experimental results and taking into account the particular structure of commingled yarns, a model is proposed to describe the GFPP yarn's tensile behavior. After identification of few parameters physically meaningful, the model allows describing accurately the full stress-strain curve. Dependency of model parameters to loading rate, specimen length and weaving damage is highlighted. Further work remains necessary to identify the internal characteristic length relative to the behavior of yarns inside the fabric and to investigate more precisely the transverse behavior of commingled yarns.

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