# Universal associative geometry 

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# UNIVERSAL ASSOCIATIVE GEOMETRY 

WOLFGANG BERTRAM


#### Abstract

We generalize parts of the theory of associative geometries developed in BeKil0a, BeKi10b, Be12] in the framework of universal algebra: we prove that certain associoid structures, such as pregroupoids and principal equivalence relations, have a natural prolongation from a set $\Omega$ to the power set o $\Omega$. We reinvestigate the case of homogeneous pregroupoids (corresponding to the projective geometry of a group, see Be12] from the point of view of pairs of commuting principal equivalence relations. We use the ternary approach to groupoids developed by Kock Ko05, Ko07, and the torsors defined by our construction can be seen as a generalisation of the known groups of bisections of a groupoid.


## Contents

Introduction ..... 1

1. Composition of binary relations revisited ..... 5
2. Torsors and semi-torsors defined by (semi-)pregroupoids ..... 12
3. Structure of $\left(U_{a}, U_{b}\right)$ : canonical kernel, associative pair ..... 15
4. Commuting prev's: "affine picture", and distributivity ..... 19
5. The homogeneous case and dualitv ..... 21
Appendix A. The familily of associoids ..... 22
References ..... 30

## Introduction

0.1. Associativity and universal algebra. The associative law plays a special rôle in universal algebra: on the one hand, associative structures such as groups, groupoids, semigroups and associative algebras are objects studied by means of universal algebra, on the same level as, e.g., Lie- or Jordan algebraic structures (see [Co65]); but on the other hand, the associative law is foundational for the topic of universal algebra itself - coming in via composition of mappings and of binary relations, via lattices and set-theory (intersections and unions). Thus associativity belongs both to the "input" and to the "output" side of universal algebra.

In a likewise way, when developing with M. Kinyon the theory of associative geometries ([BeKi10a, BeKi10b, BeKi12 $]$ ), our first aim was to define a geometric object ("associative coquecigrue") corresponding to associative algebras in a similar way as Lie groups correspond to Lie algebras. However, in subsequent work [Be12],

[^0]it became more and more visible that much of this approach really belongs to methods of universal algebra, and thus there ought to be a universal geometric algebra of associativity. The aim of the present work is to explain what I mean by this. In a nutshell, it is a geometric language to describe the duality between the power set $\mathcal{P}(\Omega)$ of a set $\Omega$ and the set $\mathcal{E}(\Omega)$ of equivalence relations on $\Omega$, in analogy with the duality between a projective space $\mathbb{P}(W)$ and its dual projective space $\mathbb{P}\left(W^{*}\right)$. Indeed, when coming accross the following phrase ([Co65], p. 16): "the quotient sets of a given set $A$ are to some extent dual to the subsets of $A$, but this duality is not complete", I had the feeling that this remark is an important guidepost, and that it should be worth understanding where it leads, when following the path to its end.
0.2. Terminology. Before explaining our results, it will be useful to fix some terminology (see Appendix A for formal definitions). Motivated by BeKi10a, BeKi10b, and by work of Kock [Ko82, Ko87, Ko05, Ko07], we work with ternary and possibly partially defined product maps (which we often denote by $(x y z)$ or $[x y z]$ and Kock denotes in most papers by $x y^{-1} z$ ), so the most general structure of this kind is a semi-associoid, a set $M$ with a partially defined product map satisfying the identity of para-associativity
\[

$$
\begin{equation*}
(x y(z u v))=(x(u z y) v)=((x y z) u v) \tag{PA}
\end{equation*}
$$

\]

and which is called an associoid if it satisfies, moreover, the idempotent law

$$
\begin{equation*}
(x x y)=y, \quad(w z z)=w . \tag{IP}
\end{equation*}
$$

According to the nature of the domain $D \subset M^{3}$ of definition of the product map, the following more or less classical associative objects are defined, summarized by the following diagram of structures (categories, in fact) and their inclusions $\sqrt{1}$ :


Objects in the last line have everywhere defined products: $D=M^{3}$. A group is nothing but a torsor with some fixed base point $y$ (unit element) and product $x z=(x y z)$, and a groupoid is nothing but a pregroupoid with some fixed bisection (set of units). The notion of (left or right) prev is an abstract-algebraic version of the one of principal bundle, stripped off the usual topological conditions. The domain $D$ for (semi-) pregroupoids is defined in terms of two equivalence relations $a, b$, the fibers of the two projections "target" and "domain":

$$
\begin{equation*}
M / a \leftarrow M \rightarrow M / b \tag{0.1}
\end{equation*}
$$

[^1]whereas for left or right prev's, just one of the two projections suffices to define $D$.
0.3 . First stage: naked sets, and composition of binary relations. We fix a ground set $\Omega$ throughout this work. Duality between the power set $\mathcal{X}:=\mathcal{P}(\Omega)$ and the set of equivalence relations $\mathcal{X}^{\prime}:=\mathcal{E}(\Omega)$ means that $\mathcal{X}^{\prime}$ "structurizes" or "coordinizes" $\mathcal{X}$, and vice versa - but this duality is not complete! For instance,

- there is a natural remoteness or transversality relation for pairs $(x, a) \in$ $\mathcal{P}(\Omega) \times \mathcal{E}(\Omega)$ and for pairs $(a, b) \in \mathcal{E}(\Omega) \times \mathcal{E}(\Omega)$ - but not for pairs $(x, y)$ of subsets,
- we may compose relations (relational composition) - but we cannot "compose sets".
Our first result (Theorem (1.6) says that the second claim is not quite true: we can "compose sets", provided given a fixed pair $(a, b)$ of commuting equivalence relations. Statement and proof of this result are elementary and go back to the very definition of relational composition: start by observing that usual relational composition $x \circ y^{-1} \circ z$ of subsets $x, y, z \subset \Omega$ would be well-defined if there were given a direct product structure $\Omega=\Omega_{1} \times \Omega_{2}$, but it would of course depend on this direct product structure. Next, observe that a direct product structure on $\Omega$ can be described by two commuting transversal equivalence relations $a, b$, namely the fibers of the two projections $\mathrm{pr}_{1}, \mathrm{pr}_{2}$ (Lemma 1.2). Then rewrite the definition of relational composition $x y^{-1} z$ in terms of $x, a, y, b, z$; you get

$$
x y^{-1} z=(x y z)_{a b}^{\mathrm{bookk}}:=\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z:  \tag{0.2}\\
\omega \sim_{a} \zeta, \quad \eta \sim_{a} \xi, \quad \omega \sim_{b} \xi, \quad \eta \sim_{b} \zeta
\end{array}\right.\right\} .
$$

It is truly remarkable that the same formula still defines a para-associative ternary composition if $a, b$ commute but are no longer transversal, nor even everywhere defined: it suffices that $(a, b)$ be a pair of commuting equivalence relations "in" $\Omega$ to obtain a semitorsor structure on $\mathcal{P}(\Omega)$, which we call the book-keeping semitorsor because this structure underlies the stronger structures to be defined later. The definition of the set $(x y z)_{a b}^{\text {bookk }}$ may be described by the following "parallelogram figure"

where sets $x, y, z$ are indicated by circles, elements $\xi, \eta, \zeta$ by solid points inside these circles; a horizontal link indicates that the points are in relation $a$, and a vertical link that they are in relation $b$. This kind of presentation and of results can be extended to general $n$-ary composition, and in particular to binary composition; and it should also be possible to generalize it to a general categorical framework ("allegories", see [FS90] or Jo02] Section A3). We will not do this here, but we try to use from the very beginning assumptions and notations that are adapted to possible "allegorical" generalizations.
0.4. Second stage: pregroupoids and their (local) bisections. Now, our naked set will get dressed: we assume that its underwear is a semi-pregroupoid structure $(\Omega, a, b,[\quad])$. Then the preceding result generalizes in the following way (Theorem 2.1): the power set $\mathcal{P}(\Omega)$ becomes a semitorsor when equipped with the everywhere defined ternary law given by

$$
(x y z)_{a b}:=\left\{\begin{array}{l|c}
\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z: \\
\eta \sim_{a} \xi, \quad \eta \sim_{b} \zeta, \quad \omega=[\xi \eta \zeta]
\end{array}\right. \tag{0.3}
\end{array}\right\}
$$

and, moreover,
(1) with its natural equivalence relations $\mathbf{a}, \mathbf{b}$ induced by $a, b,\left(\mathcal{P}(\Omega),(\quad)_{a b}\right)$ becomes itself a semi-pregroupoid,
(2) the space $U_{a b}^{\mathrm{loc}}$ of local bisections of $(a, b)$ is a sub semi-pregroupoid of the preceding.
Now let us dress up our set $\Omega$ a bit more: assume it is a pregroupoid, that is, it satisfies moreover the idempotent law. This will not imply that $\left(\mathcal{P}(\Omega),()_{a b}\right)$ satisfies the idempotent law, but we have the following (Theorem [2.1): the set $U_{a b}^{\text {loc }}$ of local bisections becomes a pregroupoid, and the set $U_{a b}$ of global bisections becomes a torsor, as summarized by the following diagram:


These torsor and semi-torsor structures generalize some more classical objects: if the pregroupoid $\Omega$ is in fact a groupoid, then, as stated in CW99, p. 106, the set $2^{\Omega}$ carries a semigroup structure (corresponding to our semigroup $(x, z) \mapsto(x y z)_{a b}$, where $y$ is the bisection of units), having several interesting sub-semigroups, among them the sub-semigroup of local bisections and the group of bisections. The case of two transversal equivalence relations ( $a \top b$ ) leads right back to the case of a naked set with ordinary composition: indeed, the pair pregroupoid on $(E, F)=(\Omega / a, \Omega / b)$ is given by purely set-theoretic data, and the diagram above reduces to

```
semi-pregroupoid \((\mathcal{R}(E, F), \mathbf{a}, \mathbf{b}) \quad \supset\) pregroupoid of local bijections \(E \rightarrow F\)
    semi-torsor \(\mathcal{R}(E, F) \quad \supset \quad\) torsor of global bijections \(E \rightarrow F\)
```

where the space $\mathcal{R}(E, F)$ of binary relations is equipped with its "usual" ternary product $x y^{-1} z$. Thus one may say that pregroupoid-like structures on $\Omega$ extend, in a canonical way, to structures of the same kind on $\mathcal{P}(\Omega)$. Of course, this offers the possibility to repeat such constructions on the level of higher order structures $\mathcal{P}(\mathcal{P}(\Omega))$, and so on.
0.5 . Third stage: commuting principal equivalence relations. We continue to dress up our set by assuming that $(\Omega, a, b,[\quad])$ is a pair of commuting left and right prev's. Essentially, this means that the partially defined ternary map [ ] now lives on the union of $a \times \Omega$ ) and $\Omega \times b$, and not only on their intersection, as for pregroupoids. This has some nice additional consequences (Section (4): first of all, not only the space $U_{a b}$ of bisections, but also the spaces $U_{a}, U_{b}$ of sections of $a$, resp. of $b$, carry canonical group structures (which we denote by + , although they
need not be commutative), and $U_{a b}$ acts on these groups from both sides, such that one-sided distributivity laws hold. The whole structure thus resembles strongly to what one calls a near-ring (see Pi77). It is, then, possible to describe this object by quite explicit formulae (involving a canonical kernel, generalizing the Bergman operators, which in turn define the Bergman kernels appearing in the theory of bounded symmetric domains), making it amenable to methods borrowed from the theory of associative or Jordan algebras.
0.6 . Fourth stage: homogeneous pregroupoids. This is the royal dress: $\Omega$ is assumed to be a group, in which we fix two subgroups $A$ and $B$, inducing two commuting left and right prev's $a$ and $b$ whose fibers are right cosets of $A$ and left cosets of $B$ :

$$
\begin{equation*}
\Omega / B \leftarrow \Omega \rightarrow A \backslash \Omega \tag{0.4}
\end{equation*}
$$

In this case, the results described above are precisely those presented in [Be12]: writing $\Omega$ additively (but not assumed to be commutative), the ternary law is given by $[\xi \eta \zeta]=\xi-\eta+\zeta$, and so (0.3) becomes

$$
(x y z)_{a b}=\left\{\begin{array}{l|l}
\omega \in \Omega & \begin{array}{l}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z, \exists \alpha \in A, \exists \beta \in B: \\
\eta=\alpha+\xi, \quad \eta=\zeta+\beta, \quad \omega=\xi-\eta+\zeta
\end{array} \tag{0.5}
\end{array}\right\}
$$

The set $(x y z)_{a b}$ has been denoted by $\Gamma(x, a, y, b, z)$, and the three equations appearing here have been called the structure equations in [Be12]. Comparison with loc. cit. shows that many proofs are now greatly simplified, due to the conceptual approach, but, on the other hand, some results are specific to the group case, namely, the presence of additional symmetries or the possibility of certain anti-symmetries - these items are very important, and we are going to add some comments on this.
0.7. Further topics; duality. Once the viewpoint of groupoids and ternary products (pre-groupoids, prev's) is adopted, the results presented here are completely natural, or (what is more or less the same) "trivial": they are just an unfolding of logical consequences of definitions. However, taking this impression to be the whole story would mean to miss the main point of the present approach. Indeed, it seems as if there were some "quantization effect": the viewpoint presented here is "classical" and fits completely with general, possibly non-transitive, pregroupoids; however, the more the pregroupoid becomes homogeneous, by a sort of "quantization effect", the structure becomes richer and more rigid due to symmetries that were not present in the general case. Indeed, these symmetries are responsible for the particular "geometric flavor" of the theory - in particular, for the most important (in our opinion) feature: duality, and relating all this to exceptional structures (cf. [BeKi12]) and Jordan geometries (cf. [Be13]). This is indeed topic for further research; we say some words about this in the last section.

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## 1. Composition of binary relations Revisited

1.1. Binary relations: notation and terminology. Concerning binary relations, the following notation and terminology will be used in all of this work:
(1) $\Omega, \Omega^{\prime}, \Omega^{\prime \prime}$ sets considered to be fixed,
(2) $\mathcal{P}(\Omega)$ the power set (set of subsets) of a set $\Omega$,
(3) $\mathcal{R}\left(\Omega, \Omega^{\prime}\right):=\mathcal{P}\left(\Omega \times \Omega^{\prime}\right)$ set of binary relations between $\Omega$ and $\Omega^{\prime}$,
(4) graph of a mapping $f: \Omega \rightarrow \Omega^{\prime}: \operatorname{Graph}_{f}:=\{(f(\omega), \omega) \mid \omega \in \Omega\} \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ (and every single valued and everywhere defined relation is of this form),
(5) relational composition of $b \in \mathcal{R}\left(\Omega^{\prime \prime}, \Omega^{\prime}\right)$ with $a \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ :

$$
\begin{equation*}
b \circ a:=b a:=\left\{(\omega, \alpha) \in \Omega^{\prime \prime} \times \Omega \mid \exists \xi \in \Omega^{\prime}:(\omega, \xi) \in b,(\xi, \alpha) \in a\right\} \tag{1.1}
\end{equation*}
$$

(so that Graph ${ }_{g \circ f}=\operatorname{Graph}_{g} \circ \operatorname{Graph}_{f}$ ),
(6) inverse relation of $a \in \mathcal{R}\left(\Omega, \Omega^{\prime}\right)$ :

$$
\begin{equation*}
a^{-1}:=\{(\alpha, \omega) \mid(\omega, \alpha) \in a\} \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right), \tag{1.2}
\end{equation*}
$$

(7) domain of $a \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right): \operatorname{dom}(a)=\operatorname{pr}_{\Omega}(a)=\left\{\alpha \in \Omega \mid \exists \omega \in \Omega^{\prime}:(\omega, \alpha) \in a\right\}$,
(8) everywhere defined if $\operatorname{dom}(a)=\Omega$,
(9) image of $a \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right): \operatorname{im}(a)=\operatorname{pr}_{\Omega^{\prime}}(a)=\left\{\omega \in \Omega^{\prime} \mid \exists \alpha \in \Omega:(\omega, \alpha) \in a\right\}$,
(10) single valued if $(\alpha, \omega),\left(\alpha^{\prime}, \omega\right) \in a \Rightarrow \alpha=\alpha^{\prime}$,
(11) intersection of two relations $a, b \in \mathcal{R}\left(\Omega, \Omega^{\prime}\right): a \cap b$ (usual intersection of sets),
(12) natural order on $\mathcal{R}\left(\Omega, \Omega^{\prime}\right): a \leq b$ if $a \subset b$ (usual inclusion of sets),
(13) $\mathcal{R}(\Omega):=\mathcal{R}(\Omega, \Omega)$ set of endorelations on $\Omega$,
(14) for $x \in \mathcal{P}(\Omega)$ and $y \in \mathcal{P}\left(\Omega^{\prime}\right)$, we define the all-relation by

$$
\begin{equation*}
\mathbf{O}_{x, y}:=x \times y \in \mathcal{R}\left(\Omega, \Omega^{\prime}\right), \quad \mathbf{O}_{x}:=\mathbf{O}_{x, x}=x \times x \in \mathcal{R}(\Omega) \tag{1.3}
\end{equation*}
$$

(15) for $x \in \mathcal{P}(\Omega)$ we define the diagonal of $x$ by

$$
\begin{equation*}
\mathbf{I}_{x}:=\{(\xi, \xi) \mid \xi \in x\} \in \mathcal{R}(\Omega), \tag{1.4}
\end{equation*}
$$

(16) an endorelation $a \in \mathcal{R}(\Omega)$ is called:
transitive if $a^{2} \subset a$,
idempotent if $a^{2}=a$,
symmetric if $a=a^{-1}$,
image reflexive if $\mathbf{I}_{\mathrm{im}(a)} \subset a$ i.e, $(\omega, \eta) \in a \Rightarrow(\omega, \omega) \in a$,
domain reflexive if $\mathbf{I}_{\mathrm{dom}(a)} \subset a$ i.e, $(\omega, \eta) \in a \Rightarrow(\eta, \eta) \in a$,
reflexive if $\mathbf{I}_{\Omega} \subset a$, i.e., $(\omega, \omega) \in a$ for all $\omega \in \Omega$,
regular if $a a^{-1} a=a$,
equivalence relation on $\Omega$ if it is transitive, symmetric and reflexive,
equivalence relation in $\Omega$ if it is transitive and symmetric.
(17) $\mathcal{E}^{\text {loc }}(\Omega)$ set of equivalence relations in $\Omega$ (local equivalence relations),
(18) $\mathcal{E}(\Omega)$ set of equivalence relations on $\Omega$,
(19) if $a \in \mathcal{E}(\Omega)$, we write also $\xi \sim_{a} \eta$ instead of $(\xi, \eta) \in a$. The equivalence class of $\omega$ under $a$ is denoted by $[\omega]_{a}$, and the canonical projection by

$$
\begin{equation*}
\pi_{a}: \Omega \rightarrow \Omega / a, \quad \omega \mapsto[\omega]_{a} \tag{1.5}
\end{equation*}
$$

(20) image of $x \in \mathcal{P}(\Omega)$ under $a \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ :

$$
a x:=a(x):=\left\{\omega \in \Omega^{\prime} \mid \exists \xi \in x:(\omega, \xi) \in a\right\}=\operatorname{im}\left(a \circ \mathbf{I}_{x}\right)
$$

(21) inverse image of $x$ under $a: x a:=a^{-1} x=\operatorname{dom}\left(\mathbf{I}_{x} \circ a\right)$.

Note that, if $a$ is an equivalence relation in $\Omega$ (so $a=a^{-1}, a^{2} \subset a$ ), then for all $\xi \in \operatorname{dom}(a)$, we have $(\xi, \xi) \in a$ (proof: $\exists \eta \in \Omega:(\eta, \xi) \in a$, whence also $(\xi, \eta) \in a$ and $(\xi, \xi) \in a^{2} \subset a$ ), so $a$ is an equivalence relation on $\operatorname{dom}(a)$.
1.2. (Local) transversality of equivalence relations and sets. An equivalence relation $a$ on $\Omega$ and a subset $x$ of $\Omega$ are called transversal if $x$ is a set of representatives of $a$, i.e., $x$ contains exactly one element from each equivalence class of $a$. We then write $a \top x$ or $x \top a$. The set of all systems of representatives of $a$ will be denoted by

$$
\begin{equation*}
U_{a}:=a^{\top}:=\{x \in \mathcal{P}(\Omega) \mid a \top x\} . \tag{1.6}
\end{equation*}
$$

We say that $a$ and $x$ are locally transversal (notation $x T^{\text {loc }} a$ ) if $x$ intersects each equivalence class of $a$ at at most one element: $\xi, \xi^{\prime} \in x, \xi \sim_{a} \xi^{\prime} \Rightarrow \xi=\xi^{\prime}$. The set of sets that are locally transversal to $a$ will be denoted by

$$
\begin{equation*}
U_{a}^{\mathrm{loc}}:=\left\{x \in \mathcal{P}(\Omega) \mid a \top^{\mathrm{loc}} x\right\} . \tag{1.7}
\end{equation*}
$$

If $a, b$ are two equivalence relations on $\Omega$, the set of common systems of representatives, called the set of bisections of $(a, b)$, will be denoted by

$$
\begin{equation*}
U_{a b}:=a^{\top} \cap b^{\top}=\{x \in \mathcal{P}(\Omega) \mid a \top x, b \top x\} . \tag{1.8}
\end{equation*}
$$

Similarly, the set of local bisections is defined by

$$
\begin{equation*}
U_{a b}^{\mathrm{loc}}:=U_{a}^{\mathrm{loc}} \cap U_{b}^{\mathrm{loc}}=\left\{x \in \mathcal{P}(\Omega) \mid a \mathrm{~T}^{\mathrm{loc}} x, b \mathrm{~T}^{\mathrm{loc}} x\right\} \tag{1.9}
\end{equation*}
$$

To give an equivalent characterisation of (local) transversality, for any pair $(a, x) \in$ $\mathcal{E}(\Omega) \times \mathcal{P}(\Omega)$ define a relation, called generalized projection (into $x$ and along a):

$$
\begin{equation*}
P_{x}^{a}:=\mathbf{I}_{x} \circ a=\{(\xi, \eta) \mid \xi \in x,(\xi, \eta) \in a\} \in \mathcal{R}(\Omega) . \tag{1.10}
\end{equation*}
$$

The proof of the following lemma is obvious:
Lemma 1.1. $A$ set $x$ is locally transversal to an equivalence relation a if, and only if, the generalized projection $P_{x}^{a}$ is single-valued, and $a \top x$ iff $P_{x}^{a}$ is an operator, i.e., everywhere defined and single-valued.

Also, $x \top a$ iff $\left.\pi_{a}\right|_{x}: x \rightarrow \Omega / a$ is bijective, and then $P_{x}^{a}=\left(\left.\pi_{a}\right|_{x}\right)^{-1} \circ \pi_{a}$.
Remark 1.1. It can be shown that, for any pair $(a, x)$, the binary relation $P_{x}^{a}$ is idempotent, regular, and image-reflexive, and that, conversely, every image-reflexive idempotent regular binary relation is of this form. The domain-reflexive idempotent regular relations are then precisely those of the form $\left(P_{x}^{a}\right)^{-1}$. These facts will not be needed in the sequel, but may be useful for a further theory.
1.3. Transversality of equivalence relations. Two equivalence relations $a, b \in$ $\mathcal{E}(\Omega)$ will be called transversal (notation: $a \top b$ ) if each equivalence class of $a$ is a system of representatives of $b$, and vice versa. This is equivalent to requiring that

$$
\begin{equation*}
a \circ b=\mathbf{O}_{\Omega} \quad \text { and } \quad a \cap b=\mathbf{I}_{\Omega} \tag{1.11}
\end{equation*}
$$

Note that $\mathbf{O}_{\Omega}=\left(\mathbf{O}_{\Omega}\right)^{-1}$, hence the first condition implies $a b=\mathbf{O}_{\Omega}=b a$, hence $a$ and $b$ commute. For instance, if $\Omega$ is the direct product $\Omega_{1} \times \Omega_{2}$ of two sets and $a, b$ are the equivalence relations given by the fibers of the two projections $\mathrm{pr}_{i}: \Omega \rightarrow \Omega_{i}$,
then $a, b$ are transversal equivalence relations. To see that this example describes already the general situation, define, for any pair $(a, b) \in \mathcal{E}(\Omega)^{2}$, the canonical map

$$
\begin{equation*}
\pi_{(a, b)}:=\left(\pi_{a} \times \pi_{b}\right) \circ \Delta_{\Omega}: \Omega \rightarrow \Omega / a \times \Omega / b, \quad \omega \mapsto\left([\omega]_{a},[\omega]_{b}\right) \tag{1.12}
\end{equation*}
$$

Lemma 1.2. For any $(a, b) \in \mathcal{E}(\Omega)^{2}: a \top b$ if, and only if, $\pi_{(a, b)}$ is bijective. In this case, an inverse map of $\pi_{(a, b)}$ is given by

$$
\Omega / a \times \Omega / b \rightarrow \Omega, \quad\left([\xi]_{a},[\zeta]_{b}\right) \mapsto[\xi]_{a} \cap[\zeta]_{b}
$$

Summing up, the choice of a transversal pair of equivalence relations is equivalent to the choice of a direct product structure on the set $\Omega$, and thus $\mathcal{P}(\Omega)$ is identified with $\mathcal{R}(\Omega / b, \Omega / a)$.

Proof. The condition $a \circ b=\mathbf{O}_{\Omega}$ means that $[\xi]_{a} \cap[\zeta]_{b}$ is not empty, for any two $\xi, \zeta \in \Omega$. The condition $a \cap b=\mathbf{I}_{\Omega}$ means that $[\xi]_{a} \cap[\zeta]_{b}$ contains at most one element. Thus the map $\Omega / a \times \Omega / b \rightarrow \Omega, \omega \mapsto\left([\omega]_{a},[\omega]_{b}\right)$ is well-defined, and it is then clear that it is inverse to $\pi_{(a, b)}$.
Note that every set admits the trivial product structure $(a, b)=\left(\mathbf{O}_{\Omega}, \mathbf{I}_{\Omega}\right)$.
Definition 1.3. Let $a$ be an equivalence relation in $\Omega$. Then the following defines an equivalence relation a on $\mathcal{P}(\Omega)$, called induced by $a$ :

$$
x \sim_{\mathbf{a}} y \text { iff: } a \mathbf{I}_{x} a=a \mathbf{I}_{y} a \text { iff: } \forall \omega \in \Omega:\left(\exists \xi \in x: \xi \sim_{a} \omega\right) \Leftrightarrow\left(\exists \eta \in y: \eta \sim_{a} \omega\right)
$$

Then, in the situation of the preceding lemma, we have: $\operatorname{im}(x)=\operatorname{im}(y)$ iff $x \sim_{\mathbf{b}} y$, and $\operatorname{dom}(x)=\operatorname{dom}(y)$ iff $x \sim_{\mathbf{a}} y$.
1.4. Transversal triples. A triple ( $a, y, c$ ) with $a, c \in \mathcal{E}(\Omega)$ and $y \in \mathcal{P}(\Omega)$ is called a transversal triple if $a \top c, y \top a, y \top c$. From the preceding lemma, it follows that $\Omega$ carries a direct product structure, and then $y$ is the graph of a bijection $\Omega / a \rightarrow \Omega / b$, whence

Lemma 1.4. A transversal triple on $\Omega$ is the same as a product structure $\Omega \cong A \times A$.
A triple ( $a, b, c$ ) of equivalence relations is called transversal if $a \top b, b \top c, c \top a$. This situation is very special: if the triple is non-trivial, it corresponds precisely to the structure of a 3 -net on $\Omega$, and then each equivalence class of each of the three relations carries the structure of a loop, see [NS], p. 53/54.

### 1.5. Composition revisited.

Theorem 1.5. Assume that $(a, b)$ is a transversal pair of equivalence relations on $\Omega$, and let us identify $\Omega$ with $\Omega / b \times \Omega / a$ via $\pi_{(a, b)}$. Then $\mathcal{P}(\Omega)$ is identified with $\mathcal{R}(\Omega / a, \Omega / b)$. Therefore, for all $x, y, z \in \mathcal{P}(\Omega)$, we may speak of the ternary composition $x y^{-1} z \in \mathcal{P}(\Omega)$.
(1) The set $x y^{-1} z \subset \Omega$ is given by the formula

$$
(x y z)_{a b}:=\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z: \\
\omega \sim_{a} \zeta, \quad \eta \sim_{a} \xi, \quad \omega \sim_{b} \xi, \quad \eta \sim_{b} \zeta
\end{array}\right.\right\} .
$$

It follows that $\mathcal{P}(\Omega)$ with ternary law $(x, y, z) \mapsto(x y z)_{a b}$ is a semitorsor.
(2) The set of bisections $U_{a b}$ defined by (1.8) is stable under the ternary product, and it forms a torsor, isomorphic to the torsor of bijective mappings $\Omega / a \rightarrow$ $\Omega / b$ with its usual torsor structure $f g^{-1} h$. In other words, if $(a, y, b)$ is a transversal triple, then $\left(U_{a b}, y\right)$ is a group, isomorphic to the group of bijections of $\Omega / a$.
(3) The set of local bisections $U_{a b}^{\mathrm{loc}}$ is a pregroupoid when equipped with the induced equivalence relations ( $\mathbf{a}, \mathbf{b}$ ) and the partially defined ternary map ( ) ab. It is isomorphic to the pregroupoid ("pseudogroup") of locally defined bijections between $\Omega / a$ and $\Omega / b$.
Proof. (1) According to the lemma, we may assume that $\Omega=\Omega_{1} \times \Omega_{2}$ and that $a, b$ are given by the two projections: $\omega \sim_{b} \eta$ iff $\omega_{1}=\eta_{1}$, and $\omega \sim_{a} \eta$ iff $\omega_{2}=\eta_{2}$. Applying twice the definition of relational composition, we get

$$
\begin{aligned}
x \circ y^{-1} \circ z & =\left\{\omega=\left(\alpha^{\prime}, \beta^{\prime}\right) \in \Omega \left\lvert\, \begin{array}{c}
\exists\left(\alpha^{\prime \prime}, \beta^{\prime \prime}\right) \in y: \\
\left(\alpha^{\prime}, \beta^{\prime \prime}\right) \in x, \quad\left(\alpha^{\prime \prime}, \beta^{\prime}\right) \in z
\end{array}\right.\right\} \\
& =\left\{\omega=\left(\alpha^{\prime}, \beta^{\prime}\right) \in \Omega \left\lvert\, \begin{array}{c}
\exists \eta=\left(\alpha^{\prime \prime}, \beta^{\prime \prime}\right) \in y, \exists \xi \in x, \exists \zeta \in z: \\
\xi_{1}=\alpha^{\prime}=\omega_{1}, \quad \xi_{2}=\beta^{\prime \prime}=\eta_{2}, \\
\eta_{1}=\alpha^{\prime \prime}=\zeta_{1}, \quad \zeta_{2}=\beta^{\prime}=\omega_{2}
\end{array}\right.\right\} \\
& =\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \eta \in y, \exists \xi \in x, \exists \zeta \in z: \\
\xi_{1}=\omega_{1}, \quad \xi_{2}=\eta_{2}, \quad \eta_{1}=\zeta_{1}, \quad \zeta_{2}=\omega_{2}
\end{array}\right.\right\}
\end{aligned}
$$

which corresponds to the formula claimed. Since, for any two sets $E, F$, the set $\mathcal{R}(F, E)$ with $(x y z)=x y^{-1} x$ is a semitorsor, $\Omega$ with the ternary product just defined, is, by transport of structure, also a semitorsor.
(2) Graphs of bijective mappings are precisely the $x \in \mathcal{R}(F, E)$ that are transversal to the equivalence relations given by the two projections; and they form a torsor with respect to the ternary law $f g^{-1} h$. (Recall that the empty set is also a torsor; of course, $U_{a b}$ is empty iff $\Omega / a$ and $\Omega / b$ are not equinumerous.)
(3) This follows from Definition 1.3 and the remark following the definition.

Recall that the definition of the set $(x y z)_{a b}$ may be described by the parallelogram figure given in the introduction. For the abstract, set-theoretic context such diagrams are quite helpful (see proof of the following theorem); however, in the main case of application, the sets $x, y, z$ are themselves objects having the shape of a "line", as in the following figure:


The dotted line is the set $(x y z)$, when $x, y, z$ are secant lines as in the drawing. Indeed, when $x, y, z$ are graphs of linear functions, with respect to the coordinate axes given by the two grey lines, then the graph of $x y^{-1} z$ is constructed exactly is indicated by the scheme.
1.6. The book-keeping semitorsor structures on $\mathcal{P}(\Omega)$. Now we drop the transversality assumption on $(a, b)$ from the preceding theorem:
Theorem 1.6 (The book-keeping semitorsor). Assume ( $a, b$ ) is a pair of commuting equivalence relations in $\Omega$, that is, $a, b \in \mathcal{E}^{\text {loc }}(\Omega)$ and $a b=b a$. For a triple $(x, y, z)$ of subsets of $\Omega$, define a subset

$$
(x y z):=(x y z)_{a b}^{\text {bookk }}:=\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z: \\
\omega \sim_{a} \zeta, \quad \eta \sim_{a} \xi, \quad \omega \sim_{b} \xi, \quad \eta \sim_{b} \zeta
\end{array}\right.\right\} .
$$

Equivalently, $(x y z)_{a b}^{\mathrm{bookk}}$ can be described as direct image of one of the sets $x, y, z$ under a binary relation, by one of the following equivalent formulae

$$
\begin{aligned}
(x y z)_{a b}^{\text {bookk }} & =\left(b \mathbf{I}_{x} a \cap a \mathbf{I}_{z} b\right)(y) \\
& =\left(b \cap a \mathbf{I}_{z} b \mathbf{I}_{y} a\right)(x) \\
& =\left(a \cap b \mathbf{I}_{x} a \mathbf{I}_{y} b\right)(z)
\end{aligned}
$$

(1) The law $(x, y, z) \mapsto(x y z)$ is a para-associative ternary product on $\mathcal{P}(\Omega)$, and hence $\mathcal{P}(\Omega)$ with this law is a semitorsor.
(2) With respect to the induced equivalence relations, $\left(\mathcal{P}(\Omega), \mathbf{a}, \mathbf{b},()_{a b}\right)$ is a semi-pregroupoid (Definition A.5).
(3) The whole structure satisfies the symmetry law

$$
(x y z)_{b a}^{\mathrm{bookk}}=(z y x)_{a b}^{\mathrm{bookk}} \text {. }
$$

Proof. Equivalence of the four formulae for $(x y z)_{a b}$ given in the theorem follows directly from the definition of relational composition and direct image of sets.
(1) We prove by direct computation that $(x y(r s t))=(x(s r y) t)$. First,

$$
\begin{aligned}
& (x y(r s t))=\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in(r s t): \\
\omega \sim_{a} \zeta, \quad \eta \sim_{a} \xi, \quad \omega \sim_{b} \xi, \quad \eta \sim_{b} \zeta
\end{array}\right.\right\} \\
& =\left\{\begin{array}{ccc}
\omega \in \Omega \left\lvert\, \begin{array}{ccc}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in \Omega, \exists \rho \in r, \exists \sigma \in s, \exists \tau \in t: \\
\omega \sim_{a} \zeta, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \\
\zeta \sim_{a} \tau, & \sigma \sim_{a} \rho, & \zeta \sim_{b} \rho, \\
& \tau \sim_{b} \sigma
\end{array}\right.
\end{array}\right\} \\
& =\left\{\begin{array}{ccc}
\omega \in \Omega & \begin{array}{ccc}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in \Omega, \exists \rho \in r, \exists \sigma \in s, \exists \tau \in t: \\
\omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \\
& \zeta \sim_{b} \tau, & \sigma \sim_{a} \rho, \\
& \zeta \sim_{b} \rho, & \tau \sim_{b} \sigma
\end{array}
\end{array}\right\}
\end{aligned}
$$

The condition $\exists \zeta \in \Omega: \zeta \sim_{a} \tau, \zeta \sim_{b} \rho$ can be eliminated: note first that this condition is equivalent to saying that $(\tau, \rho) \in a b$. But according to the condition $\rho \sim_{a} \sigma, \sigma \sim_{b} \tau$, we have $(\tau, \rho) \in b a$. Because of $b a=a b$, the latter condition implies the former, which thus can be dropped in the description of the set. Thus

$$
(x y(r s t))=\left\{\begin{array}{llll} 
& & \begin{array}{lll}
\exists \xi \in x, \exists \eta \in y, \exists \rho \in r, \exists \sigma \in s, \exists \tau \in t: \\
\omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \\
& \sigma \sim_{a} \rho, & \tau \sim_{b} \sigma
\end{array}
\end{array}\right\}
$$

The preceding computations may be visualized by the following diagrams. In the last diagram, the solid point in the middle has been eliminated. Note that transitivity and symmetry of $a$ and $b$ have been used several times.


Now compute

$$
\left.\begin{array}{rl}
(x(s r y) t) & =\left\{\omega \in \Omega \left\lvert\, \begin{array}{r}
\exists \xi \in x, \exists \zeta \in(s r y), \exists \tau \in t: \\
\omega \sim_{a} \tau, \quad \zeta \sim_{a} \xi, \quad \omega \sim_{b} \xi, \quad \tau \sim_{b} \zeta
\end{array}\right.\right\} \\
& =\left\{\begin{array}{rlll}
\exists \xi \in x, \exists \zeta \in \Omega, \exists \tau \in t, \exists \sigma \in s, \eta \in y, \exists \rho \in r: \\
\omega \sim_{a} \tau, & \zeta \sim_{a} \xi, & \omega \sim_{b} \xi, & \tau \sim_{b} \zeta \\
\eta \sim_{a} \zeta, & \eta \sim_{b} \rho, & \rho \sim_{a} \sigma, \quad \sigma \sim_{b} \zeta
\end{array}\right\} \\
& =\left\{\begin{array}{rlll}
\exists \xi \in x, \exists \zeta \in \Omega, \exists \tau \in t, \exists \sigma \in s, \eta \in y, \exists \rho \in r: \\
\omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, & \tau \sim_{b} \sigma \\
\eta \sim_{a} \zeta, & \eta \sim_{b} \rho, & \rho \sim_{a} \sigma, & \sigma \sim_{b} \zeta
\end{array}\right\}
\end{array}\right\}
$$

Eliminate as above the condition $\exists \zeta \in \Omega: \zeta \sim_{a} \eta, \eta \sim_{b} \sigma$ (using $a b=b a$ ) to get

$$
(x(s r y) t)=\left\{\begin{array}{lll}
\omega \in \Omega \left\lvert\, \begin{array}{lll}
\exists \xi \in x, \exists \tau \in t, \exists \sigma \in s, \eta \in y, \exists \rho \in r: \\
\omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \\
& \eta \sim_{b} \rho, & \rho \sim_{a} \sigma
\end{array}\right.
\end{array}\right\}
$$

agreeing with the preceding. The following diagram visualizes the computation.


The last diagram is obviously equivalent to the final diagram in the preceding figure. Similarly, it is seen that $((x y r) s t)=(x(s r y) t)$. This proves para-associativity.
(2) The compatibility of the equivalence relations $\mathbf{a}$ and $\mathbf{b}$ with the ternary law, as required by item $(\mathrm{C})$ in Definition A.5, follows directly from the definitions, and (3) follows directly from the formula defining $(x y z)_{a b}^{\text {bookk }}$.

We call the semi-torsor and semi-pregroupoid structure defined above the bookkeeping semi-torsor (semi-pregroupoid) structure on ( $\Omega, a, b$ ), because it underlies
all of the more structured ternary products to be defined in the sequel, and it formalizes the necessary book-keeping for these structures to be well-defined.

Example 1.1. If $a=b$, writing $\pi: \Omega \rightarrow \Omega / a$, one gets from the theorem

$$
(x y z)_{a a}=\pi^{-1}(\pi(x) \cap \pi(y) \cap \pi(z))=a(x) \cap a(y) \cap a(z),
$$

which is indeed a commutative and para-associative operation on $\mathcal{P}(\Omega)$. Thus settheoretic intersection appears as a sort of contraction of composition of relations. However, if $x, y, z$ are transversal to $a$, then $a(x)=\Omega$, etc., so $(x y z)_{a}=\Omega$, so the ternary product is rather degenerate.

Example 1.2. If $a=\mathbf{I}_{\Omega}$ and $b$ any equivalence relation, one gets

$$
(x y z)_{a b}=\pi^{-1}(\pi(x \cap y \cap z))=b(x \cap y \cap z),
$$

again a commutative and para-associative operation on $\mathcal{P}(\Omega)$. More generally, if $a \subset b$, the operation $(x y z)_{a b}$ can be described by multiple intersections of sets. Similar remarks can be made if $a=\mathbf{O}_{\Omega}$.

Remark 1.2. More generally, binary, or general $n$-ary, composition may be described in a similar way as an $n$-ary operation on $\mathcal{P}(\Omega)$ depending on the choice of several (commuting) equivalence relations, in such a way that the resulting product remains associative even if the equivalence relations are not transversal; if all equivalence relations are the same, or some are reduced to the identity relation, the associative operation reduces to multiple intersections, in a similar way as in the examples described above. However, the ternary composition $x y^{-1} z$ seems to be the most interesting among these operations.

## 2. Torsors and semi-Torsors defined by (SEmi-)Pregroupoids

In this section we assume that $(\Omega, a, b,[\quad])$ is a semi-pregroupoid. We will show that this structure carries over to $(\mathcal{P}(\Omega), \mathbf{a}, \mathbf{b})$; and if $(\Omega, a, b,[\quad])$ is a pregroupoid, then this carries over to $\left(U_{a b}^{\mathrm{loc}}, \mathbf{a}, \mathbf{b}\right)$ :
Theorem 2.1 (Associative geometry of a (semi-)pregroupoid). Assume ( $\Omega, a, b,[\quad]$ ) is a semi-pregroupoid. For $(x, y, z) \in \mathcal{P}(\Omega)^{3}$ let

$$
(x y z)_{a b}:=\Gamma(x, a, y, b, z):=\left\{\omega \in \Omega \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z: \\
\eta \sim_{a} \xi, \quad \eta \sim_{b} \zeta, \quad \omega=[\xi \eta \zeta]
\end{array}\right.\right\} .
$$

(1) The law $(x, y, z) \mapsto(x y z)_{a b}$ defines a semitorsor structure on $\mathcal{P}(\Omega)$.
(2) With respect to the induced equivalence relations, $\left(\mathcal{P}(\Omega), \mathbf{a}, \mathbf{b},()_{a b}\right)$ is a semi-pregroupoid.
(3) The set $U_{a b}^{\mathrm{loc}}$ of local bisections of $(a, b)$ is stable under the ternary product $(x y z)_{a b}$, and becomes a semitorsor with respect to this product. When equipped with the equivalence relations $(\mathbf{a}, \mathbf{b})$, it becomes a semi-pregroupoid.
(4) The set $U_{a b}$ of bisections of $(a, b)$ is stable under the ternary product $(x y z)_{a b}$ and becomes a semitorsor with respect to this product.
(5) If $a$ Tb, the law ()$_{a b}$ coincides with the one considered in Theorem 1.5 , Assume, moreover, that ( $\Omega, a, b,[\quad])$ is a pregroupoid. Then the semi-pregroupoid $U_{a b}^{\mathrm{loc}}$ defined above is also a pregroupoid, and the semitorsor $U_{a b}$ is a torsor.

Proof. (1) We prove the para-associative law $(x y(r s t))=(x(s r y) t)$. Note first that, by the defining property (C) of a semi-pregroupoid, with notation from the theorem, the missing two book-keeping conditions $\omega \sim_{a} \zeta$ and $\omega \sim_{b} \xi$ also hold, so that we have in fact

Therefore the first computation from the proof of Theorem 1.6 shows that

$$
(x y(r s t))=\left\{\begin{array}{cccc}
\exists \xi \in x, \exists \eta \in y, \exists \rho \in r, \exists \sigma \in s, \exists \tau \in t: & \\
\omega \in \Omega \mid \omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \quad \eta \sim_{b} \rho, \quad \sigma \sim_{a} \rho, & \tau \sim_{b} \sigma \\
\omega=[\xi \eta[\rho \sigma \tau]]
\end{array}\right\}
$$

On the other hand, the second computation from the proof of Theorem 1.6 yields

$$
(x(\operatorname{sry}) t)=\left\{\begin{array}{rlrl}
\exists \xi \in x, \exists \tau \in t, \exists \sigma \in s, \eta \in y, \exists \rho \in r: & \\
\omega \in \Omega \mid \omega \sim_{a} \tau, & \eta \sim_{a} \xi, & \omega \sim_{b} \xi, \quad \tau \sim_{b} \sigma \quad \eta \sim_{b} \rho, \quad \rho \sim_{a} \sigma \\
\omega=[\xi[\sigma \rho \eta] \tau]
\end{array}\right\}
$$

By the para-associative law for [ ], we have equality of both sets (and it becomes obvious from the proof why we call the first four conditions "book-keeping conditions"). (Note: the condition $a b=b a$ is not stated as assumption in the theorem since it is a consequence of the other assumptions, see Lemma A.6.)
(2) Assume $x \sim_{\mathbf{a}} y$ and $y \sim_{\mathbf{b}} z$ and let us show that $(x y z) \sim_{\mathbf{a}} z$, that is, every element of $(x y z)$ is $a$-related to an element of $z$, and conversely. The first statement follows directly from the fact that $\omega=[\xi \eta \zeta] \sim_{a} \zeta$ (defining property of a semipregroupoid). In order to prove the converse, let $\zeta \in z$. By assumption, there are $\eta \in y$ and $\xi \in x$ such that $\eta \sim_{b} \zeta$ and $\xi \sim_{a} \eta$, thus $\omega:=[\xi \eta \zeta]$ is an element of $(x y z)$, and $\omega \sim_{a} \zeta$, as seen above. In the same way it is seen that $(x y z) \sim_{\mathbf{b}} x$.
(3) Assume $x, y, z$ are local bisections, and let us show that $(x y z)_{a b}$ is again a local bisection. Let $\omega=[\xi \eta \zeta]$ and $\omega^{\prime}=\left[\xi^{\prime} \eta^{\prime} \zeta^{\prime}\right] \in(x y z)_{a b}$ such that $\omega \sim_{a} \omega^{\prime}$ (with $\xi, \xi^{\prime}$, etc, satisfying the conditions from (2.1). Among these conditions are $\omega \sim_{a} \xi$, $\omega^{\prime} \sim_{a} \xi^{\prime}$; from transitivity of $a$, we get $\xi \sim_{a} \xi^{\prime}$, whence $\xi=\xi^{\prime}$ since $x$ is a local bisection. This implies $\eta \sim_{b} \xi=\xi^{\prime} \sim_{b} \eta^{\prime}$, whence $\eta=\eta^{\prime}$ since $y$ is a local bisection, and in the same way, $\zeta=\zeta^{\prime}$, whence $\omega=\omega^{\prime}$, showing that $(x y z)_{a b}$ is a local section of $a$. In the same way we see that it is a local section of $b$, whence $(x y z)_{a b} \in U_{a b}^{\text {loc }}$. Thus $U_{a b}^{\text {loc }}$ is stable under the product and hence forms a sub-semitorsor of $\mathcal{P}(\Omega)$ and a sub-semi-pregroupoid of ( $\mathcal{P}(\Omega), \alpha, \beta$ ).
(4) Since $U_{a b}=\left\{x \in U_{a b}^{\text {loc }} \mid x \sim_{\alpha} \Omega\right\}$, the statement follows from (3).
(5) Assume that $a \top b$. Then $(\Omega, a, b,[\quad])$ is isomorphic to a pair pregroupoid, see example A.4, that is, the equivalence relations $(a, b)$ determine the algebraic ternary law $[x y z]$ entirely; therefore we are back in the purely set-theoretic setting of the preceding chapter.

Now assume $\Omega$ is a pregroupoid. All that remains is to prove is the idempotent law for $U_{a b}^{\text {loc }}$. Let us show that $(x x z)_{a b}=z$ if $x \sim_{\mathbf{b}} z$. Indeed, if $\omega=[\xi \eta \zeta]$ with $\xi, \eta \in x$, then from $\xi \sim_{\eta} \eta$ we get $\xi=\eta$ (since $x$ is a local section), whence
$\omega=[\xi \xi \zeta]=\zeta \in z$, thus $(x x z)_{a b} \subset z$. To prove the other inclusion, we have to use that, by assumption, $x \sim_{\mathbf{b}} z$ : for every $\zeta \in z$, there is $\xi \in x$ with $\xi \sim_{\beta} z$, whence $\zeta=[\xi \xi \zeta] \in(x y z)_{a b}$, whence $z \subset(x x z)_{a b}$. Similarly, if $x \sim_{\mathbf{a}} z$, we get $(x z z)_{a b}=x$. This proves the idempotent law for $U_{a b}^{\text {loc }}$ and at the same time for $U_{a b}$.
Example 2.1. Singletons (sets with one element) are special local bisections, and restricted to the set of singletons, the induced relations ( $\mathbf{a}, \mathbf{b}$ ) are just $(a, b)$, and the law ()$_{a b}$ reduces to [ ]. In this sense, the original pregroupoid $\Omega$ is a subpregroupoid of $U_{a b}^{\text {loc }}$. Its union with $\emptyset$ is a semi-torsor (this generalizes the observation, groing back to Baer, that a groupoid can be completed by $\emptyset$ into a semigroup, see [CW99] and [Ba29]).

The sets $U_{a}, U_{b}$ of sections in a pregroupoid $(\Omega, a, b,[\quad])$ do in general not carry a group structure. However, in the following cases there is such a structure:
Corollary 2.2. Assume that ( $\Omega, a,[\quad]$ ) is an assocoid that is either
(1) $a$ torsor-bundle, i.e., a pregroupoid with $a=b$, or
(2) $a$ (left) principal equivalence relation (prev), i.e. a pregroupoid with $(a, b)=$ $(a, \Omega)$ (cf. Appendix A.4), or
(3) $a$ (right) prev, i.e., a pregroupoid with $(a, b)=(\Omega, a)$.

In all three cases, the space of sections of a carries a natural torsor structure, which can equivalently be described as the space of sections $s: B \rightarrow \Omega$ of the canonical projection $\pi: \Omega \rightarrow B$ with"pointwise product"

$$
\begin{equation*}
(r s t)(b):=[r(b) s(b) t(b)], \tag{2.2}
\end{equation*}
$$

or as the set $U_{a}$ with ternary product given by

$$
(x y z)_{a}=\left\{\begin{array}{l|c}
\omega \in \Omega & \begin{array}{c}
\exists \xi \in x, \exists \eta \in y, \exists \zeta \in z: \\
\eta \sim_{a} \xi, \quad \eta \sim_{a} \zeta, \quad \omega=[\xi \eta \zeta]_{a}
\end{array}
\end{array}\right\}
$$

Moreover, the last formula defines a semitorsor structure on all of $\mathcal{P}(\Omega)$, and a pregroupoid structure on $(\mathcal{P}(\Omega), \mathbf{a})$, and in cases (2) and (3), $\left(U_{a}^{\text {loc }}, \mathbf{a},()_{a}\right)$ is then a again a prev.

Proof. A pregroupoid with $a=b$ is the same as a torsorbundle over $\Omega / a$, and then a bisection is the same as a section of $a$, i.e., $U_{a}=U_{a} a$. The equivalence of both descriptions is immediate. Thus, in this case, the result follows immeditely from the preceding theorem (and it also clear from the first description).

If $b=\Omega$, then $(\Omega, a,[])$ is a (left) principal equivalence relation (prev). By restriction of the domain of definition of [ ], it is then also a torsorbundle, and hence in this case also the space of sections $U_{a}=U_{a a}$ carries a torsor structure (but then the product ()$_{a a}$ is not to be confused with the product ( $)_{a \Omega}$, which is uninteresting) . The final statement also follows directly from the preceding theorem.

Remark 2.1. The semitorsor law on $\mathcal{P}(\Omega)$ defined in the corollary has the following interpretation: it is the "pointwise semitorsor loi of sets" - recall first that, for any group $(G,+)$, the power set $\mathcal{P}(G)$ becomes a semigroup with law $A+B=\{a+b \mid$ $a \in A, b \in B\}$; likewise, for any torsor $G$, the power set $\mathcal{P}(G)$ becomes a semitorsor with "pointwise product". Now, in the setting of the corollary, fix some equivalence
class [ $o$ ] of $a$ and let $x_{o}:=x \cap[o]$, etc. Then the formula given in the theorem says that $(x y z)_{a} \cap[o]$ is empty if one of the sets $x_{o}, y_{o}, z_{o}$ is empty, and given by the "pointwise set product" $\left[x_{o} y_{o} ; z_{o}\right]$ in the torsor $[o]$ else.

Example 2.2 (Case of a group.). See section 5. Note that, in this case, a subtelety shows up: one subgroup $A$ of $\Omega$ defines two equivalence relations $a$ (right relation) and $b=: \hat{a}$ (left) relation, which commute. Thus $(\Omega, a, \hat{a},[\quad])$ is a pregroupoid, giving rise to a torsor $U_{a \hat{a}}$, which corresponds to the "balanced torsor $U_{a a}$ " from [Be12]. On the other hand, since $a$ and $\hat{a}$ are prev's in their own right, we may also define the torsors $U_{a}$ and $U_{\hat{a}}$, corresponding to the unbalanced torsors from [Be12]. Thus one subgroup defines three different torsors (they coincide if $\Omega$ is abelian).

## 3. Structure of $\left(U_{a}, U_{b}\right)$ : Canonical kernel, associative pair

We continue to assume that $(\Omega, a, b,[\quad])$ is a (semi-)pregroupoid. In the special case of an associative geometry in the sense of [BeKi10a, there is an associated tangent object of the geometry, comparable to the Lie algebra of a Lie group: this tangent object is an associative pair. In the present, much more general, context, the pair of sets $\left(U_{a}, U_{b}\right)$ plays a similar rôle. Understanding the structure of ( $U_{a}, U_{b}$ ) comprises the study of the torsor $U_{a b}=U_{a} \cap U_{b}$. Again, in the framework of BeKi10a], the structure of the group $\left(U_{a b}, y\right)$ is quite well understood using a morphism $U_{a b} \rightarrow \operatorname{Bij}(y)$, called the canonical kernel. Part of this generalizes to the present context.

### 3.1. Generalized associative pairs.

Definition 3.1. $A$ (generalized) associative pair is a pair of sets $\left(U^{+}, U^{-}\right)$together with two ternary maps

$$
U^{ \pm} \times U^{\mp} \times U^{ \pm} \rightarrow U^{ \pm}, \quad(x, y, z) \mapsto\langle x y z\rangle^{ \pm}
$$

satisfying the para-associative law

$$
\left\langle x y\langle u v w\rangle^{ \pm}\right\rangle^{ \pm}=\left\langle x\langle v u y\rangle^{\mp} w\right\rangle^{ \pm}=\left\langle\langle x y u\rangle^{ \pm} v w\right\rangle^{ \pm} .
$$

The adjective "generalized" will only be used in contexts where there could be confusion with "usual" asociative pairs (as defined in [Lo75]; cf. [BeKi10a]), namely when $U^{ \pm}$are modules over a ring $\mathbb{K}$, where the "usual" definition requires the ternary product to be $\mathbb{K}$-trilinear.

Example 3.1. Every torsor $G$ with $U^{+}=G=U^{-}$and $\left\rangle^{+}=(\quad)=\langle \rangle^{-}\right.$is an associative pair.

Example 3.2. Let $E, F$ be sets and $\left(U^{+}, U^{-}\right)=(\operatorname{Map}(E, F), \operatorname{Map}(F, E))$ and

$$
\begin{aligned}
\operatorname{Map}(E, F) \times \operatorname{Map}(F, E) \times \operatorname{Map}(E, F) \rightarrow \operatorname{Map}(E, F), & (f, g, h) \mapsto f g h, \\
\operatorname{Map}(F, E) \times \operatorname{Map}(E, F) \times \operatorname{Map}(F, E) \rightarrow \operatorname{Map}(F, E), & (f, g, h) \mapsto h g f .
\end{aligned}
$$

This is an associative pair. If $E, F$ happen to be $\mathbb{K}$-modules, the ternay products are linear in only one of the arguments!

Theorem 3.2. For any pregroupoid $(\Omega, a, b,[\quad])$, the pair $\left(U^{+}, U^{-}\right):=\left(U_{a}, U_{b}\right)$ is an associative pair with product given by ()$_{a b}$ : the maps

$$
\begin{array}{ll}
U_{a} \times U_{b} \times U_{a} \rightarrow U_{a}, & (x, y, z) \mapsto\langle x y z\rangle^{+}:=(x y z)_{a b} \\
U_{b} \times U_{a} \times U_{b} \rightarrow U_{b}, & (x, y, z) \mapsto\langle x y z\rangle^{-}:=(x y z)_{a b}
\end{array}
$$

are well-defined and para-associative.
Proof. Note first that this statement is stronger than the result above saying that $U_{a} \cap U_{b}$ is stable under the ternary product. We will give a proof by using an operator calculus, which may have some interest in its own right. Let us define, for any $x, z \in \mathcal{R}(\Omega)$, the following binary relation

$$
\begin{aligned}
M_{x a b z} & :=\left\{(\omega, \eta) \in \Omega^{2} \left\lvert\, \begin{array}{c}
\exists \xi \in x, \exists \zeta \in z: \\
\eta \sim_{a} \xi, \\
\eta \sim_{b} \zeta, \quad \omega=[\xi \eta \zeta]
\end{array}\right.\right\} \\
& =\left\{(\omega, \eta) \in \Omega^{2} \left\lvert\, \begin{array}{c}
\exists \xi, \zeta \in \Omega: \\
(\xi, \eta) \in P_{x}^{a}, \\
(\zeta, \eta) \in P_{z}^{b}, \quad \omega=[\xi \eta \zeta]
\end{array}\right.\right\} .
\end{aligned}
$$

Then it follows directly from the definitions that, for any $y \in \mathcal{P}(\Omega)$,

$$
\begin{equation*}
(x y z)_{a b}=M_{x a b z}(y) \tag{3.1}
\end{equation*}
$$

Now, if $a \top x$ and $b \top z$, then $\xi=P_{x}^{a}(\eta)$ and $\zeta=P_{z}^{b}(\eta)$ exist and are uniquely determined, for all $\eta \in \Omega$, and hence

$$
\omega=\left[P_{x}^{a}(\eta) \eta P_{z}^{b}(\eta)\right]
$$

also exists and is uniquely determined, which means that $M_{x a b z}$ is a mapping. Similar arguments apply for left- and right multiplications. Let us summarize:

Lemma 3.3. Define operators on $\Omega$ as follows:
(1) if $x \top a, z \top b: \quad M_{x a b z}: \Omega \rightarrow \Omega, \quad \eta \mapsto\left[P_{x}^{a}(\eta) \eta P_{z}^{b}(\eta)\right]$
(2) if $x \top a, y \top b: \quad L_{x a y b}: \Omega \rightarrow \Omega, \quad \zeta \mapsto\left[P_{x}^{a} P_{y}^{b}(\zeta) P_{y}^{b}(\zeta) \zeta\right]$
(3) if $y \top a, z \top b: \quad R_{z b y a}: \Omega \rightarrow \Omega, \quad \xi \mapsto\left[\xi P_{y}^{a}(\xi) P_{z}^{b} P_{y}^{a}(\xi)\right]$

Then we have, under the respective transversality conditions,

$$
(x y z)_{a b}=L_{x a y b}(z), \quad(x y z)_{a b}=M_{x a y z}(y), \quad(x y z)_{a b}=R_{z b y a}(x),
$$

and the operators satisfy, whenever the suitable transversality conditions hold, the "semitorsor relations":

$$
R_{a u b z} L_{x a v b}=M_{x a b z} M_{u a b v}=L_{x a v b} R_{a u b z}, \quad L_{x a y b} L_{u a v b}=L_{L_{x a y b}(u) a v b}
$$

Proof. The "semitorsor relations" are simply the translation of the para-associative law of the semitorsor defined by $(a, b)$ in the language of left-, right- and middle translations (justified by the fact that, applied to singletons, these operators must satisfy para-associativity, by Theorem (2.1).

With some care, the operator $M_{x a b z}$ may be written in argument-free notation:

$$
M_{x a b z}=\left[P_{x}^{a}, \mathrm{id}_{\Omega}, P_{z}^{b}\right]
$$

which is close to the formula $M_{x a b z}=P_{x}^{a}-\mathrm{id}+P_{z}^{b}$ from BeKi10a.
Lemma 3.4. For all $x \in U_{a b}$, we have $L_{x a x b}=\mathrm{id}_{\Omega}$ and $R_{x b x a}=\mathrm{id}_{\Omega}$.

Proof. Directly from the definition of the projection operators one sees that, if $x \in U_{a b}$, then $P_{x}^{a} \circ P_{x}^{b}=P_{x}^{b}$, whence

$$
L_{x a x b}(\zeta)=\left[P_{x}^{a} P_{x}^{b}(\zeta) P_{x}^{b}(\zeta) \zeta\right]=\left[P_{x}^{b}(\zeta) P_{x}^{b}(\zeta) \zeta\right]=\zeta
$$

and similarly for right multiplication operators.
Lemma 3.5. For all $x, y \in U_{a b}$, the operator $L_{x a y b}$ is invertible with inverse $L_{y a x b}$, and $R_{x b y a}$ is invertible with inverse $R_{y b x a}$.
Proof. The semitorsor relation from Lemma 3.3 and the preceding lemma imply

$$
L_{x a y b} L_{y a x b}=L_{(x y y)_{a b} a x b}=L_{x a x b}=\mathrm{id}_{\Omega},
$$

whence the claim for the $L$-operator. Similarly for the $R$-operator.
Lemma 3.6. (1) If $x \top a, y \top b$, then $L_{x a y b} \in \operatorname{Aut}_{1}(a)$, i.e., it preserves all equivalence classes of $a, c f$. Def. A.11.
(2) If $y \top a$, $z \top b$, then $R_{z b y a} \in \operatorname{Aut}_{1}(b)$.

Proof. (1) For any $\zeta \in \Omega$, the element $\omega=L_{x a y b}(\zeta)=\left[P_{x}^{a} P_{y}^{b}(\zeta) P_{y}^{b}(\zeta) \zeta\right]$ belongs to the same $a$-equivalence class as $\zeta$, by the defining property (C) of a pregroupoid. Similarly for (2).

Now we prove the theorem: let $x, z \in U_{a}$ and $y \in U_{b}$. Since $g:=L_{\text {xayb }}$ is a bijection of $\Omega$ preserving each equivalence class of $a$, the image $g(z)$ contains again exactly one element from each equivalence class of $a$, i.e., $g(z) \top a$, that is, $(x y z)_{a b} \top a$. Thus the first of the two maps is well-defined, and so is the second.

Example 3.3. Assume $a \top b$. Then with $E:=\Omega / b, F:=\Omega / a$ we get the associative pair from Example 3.2.
Remark 3.1. On could define "associative pair-oids" and then state and prove an "oid"-version of the preceding result, but we will not spell out this here.
3.2. Automorphisms, and self-distributivity. A morphism of a partially defined ternary product map is a map preserving domains of definition and commuting with the algebraic product maps, and the automorphism group of a (semi-) pregroupoid is then denoted by $\operatorname{Aut}(\Omega)=\operatorname{Aut}(\Omega, D,[\quad])$. Note that an automorphism $g \in \operatorname{Aut}(\Omega)$ need not preserve the equivalence relations $a, b$ individually, but only the set $D=\Omega \times{ }_{a} \Omega \times{ }_{b} \Omega$. Thus we end up with several kinds of automorphism groups: besides $\operatorname{Aut}(\Omega)$, there are also

$$
\begin{array}{cl}
\operatorname{Aut}(\Omega, a)=\operatorname{Aut}(\Omega) \cap \operatorname{Aut}(a), & \operatorname{Aut}(\Omega, b)=\operatorname{Aut}(\Omega) \cap \operatorname{Aut}(b), \\
\operatorname{Aut}_{1}(\Omega, a)=\operatorname{Aut}(\Omega) \cap \operatorname{Aut}_{1}(a), & \operatorname{Aut}_{1}(\Omega, b)=\operatorname{Aut}(\Omega) \cap \operatorname{Aut}_{1}(b) .
\end{array}
$$

Lemma 3.7. Under the assumptions of Lemma 3.6: $L_{x a y b}$ permutes equivalence classes of $b$, that is, $L_{x a y b} \in \operatorname{Aut}(b)$, and $R_{z b y a}$ permutes equivalence classes of a, that is, $R_{z b y a} \in \operatorname{Aut}(a)$.
Proof. Assume $\zeta \sim_{b} \zeta^{\prime}$. It follows that $P_{y}^{b}(\zeta)=P_{y}^{b}\left(\zeta^{\prime}\right)$, and therefore

$$
\begin{aligned}
L_{x a y b}(\zeta)=\left[P_{x}^{a} P_{y}^{b}(\zeta) P_{y}^{b}(\zeta) \zeta\right] \sim_{b} P_{x}^{a} P_{y}^{b}(\zeta) & =P_{x}^{a} P_{y}^{b}\left(\zeta^{\prime}\right) \\
\sim_{b}\left[P_{x}^{a} P_{y}^{b}\left(\zeta^{\prime}\right) P_{y}^{b}\left(\zeta^{\prime}\right) \zeta^{\prime}\right] & =L_{x a y b}\left(\zeta^{\prime}\right)
\end{aligned}
$$

whence $L_{x a y b} \in \operatorname{Aut}(b)$. Similarly, $R_{z b y a} \in \operatorname{Aut}(a)$.

Theorem 3.8. The left- and right multiplication operators $L_{\text {xayb }}$ and $R_{z b y a}$ defined in lemma 3.3 (under the transversality conditions given there) are automorphisms of ()$_{a b}$, which corresponds to the "self-distributivity" identities

$$
\begin{aligned}
\left(x y(u v w)_{a b}\right)_{a b} & =\left((x y u)_{a b}(x y v)_{a b}(x y w)_{a b}\right)_{a b}, \\
\left((u v w)_{a b} y z\right)_{a b} & =\left((u y z)_{a b}(v y z)_{a b}(w y z)_{a b}\right)_{a b} .
\end{aligned}
$$

It follows that left- and right multiplicaiton operators belong to the group $\operatorname{Aut}(\Omega, a) \cap$ $\operatorname{Aut}(\Omega, b)$.

Proof. The self-distributivity identities hold in any associoid, cf. equation (A.1). Next, recall (example 2.1) that the union of the set of all singletons with $\emptyset$ forms a sub-semitorsor of the semitorsor of local bisections, and thus the self-distributive identies hold with respect to singletons $u, v, w$, which means that left and right translations act by automorphisms of [ ], i.e., they belong to Aut ( $\Omega$, [ ]). As seen in the preceding lemma, they belong also to $\operatorname{Aut}(a) \cap \operatorname{Aut}(b)$.

Lemma 3.9. Let $g \in \operatorname{Aut}(\Omega, a) \cap \operatorname{Aut}(\Omega, b)$. Then $g$ is an automorphism of the ternary product $\left.(\quad)_{a b}: g(x y z)_{a b}=(g(x) g(y) g(z))_{a b}\right)_{a b}$.
Proof. The proof is by a straightforward change of variables, $\xi^{\prime}=g^{-1}(\xi)$, etc., using that $\xi \sim_{a} \eta$ iff $\xi^{\prime} \sim_{a} \eta^{\prime}$ (since $g$ permutes equivalence classes of $a$ ).

Remark 3.2. In a similar way, the middle multiplication operators $M_{x a b z}$ preserve the domain of definition $D$ and exchange $x$ and $z$, hence they should be qualified as antiautomorphisms. However, since they exchange also $a$ and $b$, in [BeKi10b], they are qualified as automorphisms of the structure map $\Gamma$. The true challenge, then, is to find antiautomorphisms in the sense defined in loc. cit.

Remark 3.3. For $L$ - and $R$-relations that are not invertible operators, the selfdistributivity identity has to be replaced by structurality, as defined in BeKi10a.
3.3. Canonical kernel, and structure of $U_{a b}$. The following definition and lemma are purely set-theoretic:

Definition 3.10. For $x \in U_{b}, y \in U_{a}$, the canonical kernel is the map defined by

$$
B_{y}^{a, x, b}:=B_{y}^{a x b}: y \rightarrow y, \quad \eta \mapsto P_{y}^{a} \circ P_{x}^{b}(\eta)
$$

Lemma 3.11. Assume $a \top y \top b \top x$. Then: $B_{y}^{a x b}: y \rightarrow y$ is bijective iff $a \top x$. If this is the case, then we have $\left(B_{y}^{a x b}\right)^{-1}=B_{y}^{b a x}$.
Proof. From $y \top b \top x$ it follows that $\left.P_{x}^{b}\right|_{y}: y \rightarrow x$ is bijective. Therefore $B_{y}^{a x b}$ is bijective iff $\left.P_{y}^{a}\right|_{x}: x \rightarrow y$ is bijective, and this in turn is equivalent to saying that $a \top x$. If this holds, then, for all $\eta \in y$, we have $B_{y}^{b x a} B_{y}^{a x b}(\eta)=P_{y}^{b} P_{x}^{a} P_{y}^{a} P_{x}^{b}(\eta)=$ $P_{y}^{b} P_{x}^{a} P_{x}^{b}(\eta)=P_{y}^{b} P_{x}^{b}(\eta)=P_{y}^{b}(\eta)=\eta$.
Theorem 3.12. The group $\left(U_{a b}, y\right)$ has a natural action on the set $y$, given by

$$
U_{a b} \times y \rightarrow y, \quad(x, \eta) \mapsto B_{y}^{a, x, b}(\eta)
$$

Thus $B_{y}^{a,(x y z), b}=B_{y}^{a, x, b} \circ B_{y}^{a, z, b}$ and $\left(B_{y}^{a x b}\right)^{-1}=B_{y}^{a x^{-1} b}=B_{y}^{a(y x y) b}$.

Proof. Since $U_{a b}$ acts, as shown in the preceding section, on $\Omega$ by left translations via $(x, \zeta) \mapsto L_{x a y b}(\zeta)$, it acts naturally on the tautological bundle of $\mathcal{P}(\Omega)$, which is the set defined by $M:=\{(z, \zeta) \mid z \in \mathcal{P}(\Omega), \zeta \in z\}$ (the fiber over the "point" $z$ is the set of elements of $z$ ). Similarly, $U_{a b}$ acts also by right translations, commuting with the left action, and hence there is also an action by conjugation,

$$
g \cdot(z, \zeta)=\left(L_{x a y b} R_{y a x b}(z), L_{x a y b} R_{y a x b}(\zeta)\right) .
$$

The fiber over the neutral element $y$ is stable under the conjugation action, and thus we see that $U_{a b}$ acts on the set $y$ via $\eta \mapsto L_{x a y b} R_{y a x b}(\eta)=R_{y a x b} L_{x a y b}(\eta)$. But

$$
L_{x a y b}(\eta)=\left[P_{x}^{a} P_{y}^{b}(\eta), P_{y}^{b}(\eta) ; \eta\right]_{a}=\left[P_{x}^{a}(\eta), \eta ; \eta\right]=P_{x}^{a}(\eta),
$$

and similarly, for $\xi:=P_{x}^{a}(\eta)$, we get $R_{y a x b}(\xi)=P_{y}^{b}(\xi)$ and thus

$$
R_{y a x b} L_{x a y b}(\eta)=R_{y a x b}(\xi)=P_{y}^{b}(\xi)=P_{y}^{b} P_{x}^{a}(\eta)=B_{y}^{a, x, b}(\eta)
$$

whence the claim.
In the framework of associative geometries BeKil0a, more can be said about this action (image, kernel, possible splittings). In a certain sense, the general situation should be a sort of amalgamation of the following two extremal cases:

Example 3.4. If $a \top b$ and $y \in U_{a b}$, then the morphism $\left(U_{a b}, y\right) \rightarrow\left(\operatorname{Bij}(y), \mathrm{id}_{y}\right)$ is an isomorphism.
Example 3.5. If $a=b$, then $B_{y}^{a x a}=\mathrm{id}_{y}$, for all $x \in U_{a b}$, so the morphism is trivial.

## 4. Commuting prev's: "AFFine picture", and distributivity

4.1. Affine picture. Assume $(\Omega, a,[\quad])$ is a (left) prev. Then $U_{a}$ carries a torsor structure (Corollary (2.2), but we have more: the structure of a prev is considerably stronger than the one of a torsor bundle, since all fibers are isomorphic to the model torsor $G^{a}=\left\{\lambda_{\xi, \eta}^{a} \mid(\xi, \eta) \in a\right\}$ of left translations (cf. Appendix A.4). This permits us to define a sort of coordinates on $U_{a}$, in a similar way as affine parts of projective spaces are defined (so we call it an "affine picture" even in our general situation):

Lemma 4.1. Assume $(\Omega, a,[\quad])$ is a left prev, and fix a section $y \in U_{a}$ (one may call it "zero section"). Then the map

$$
\operatorname{Map}\left(y, G^{a}\right) \rightarrow U_{a}, \quad f \mapsto z:=\{f(\eta) \cdot \eta \mid \eta \in y\}
$$

is bijective, with inverse map

$$
U_{a} \rightarrow \operatorname{Map}\left(y, G^{a}\right), \quad z \mapsto f=\left(\eta \mapsto \lambda_{P_{z}^{a}(\eta), \eta}^{a}\right) .
$$

It intertwines the group structure on $\left(U_{a}, y\right)$ with the natural "pointwise" group structure of $\operatorname{Map}\left(y, G^{a}\right)$.

The proof is straightforward. Note also that the prev-structure permits to identify a section $y \in U_{a}$ with an equivalence relation whose equivalence classes are the sets $g . y$ for $g \in G^{a}$ (lines parallel to $y$, in the following illustration). In the following, to be in keeping with [Be12, BeKi10a, we write the group law of $\left(U_{a}, o\right)$, for some origin $o$, additively $x+z:=(x o z)_{a}$ (which need not be commutative), so that $(u v w)_{a}=u-v+w$.
4.2. Case of two commuting prev's. From now on, assume that $(\Omega, a, b,[\quad])$ is an associoid given by two commuting principal equivalence relations (prev's) (Appendix A.5). This structure is stronger than the one of a pregroupoid: there are three para-associative laws defined on $\mathcal{P}(\Omega)$, denoted by ()$_{a b},()_{a}$ and ()$_{b}$, and one may ask how these maps interact. We will show that they are related by a certain distributive law, by using the following description of the product $(x y z)_{a b}$ in the "affine picture":

Theorem 4.2. Let $(a, b)$ be two commuting prev's on $\Omega$, and fix a bisection $y \in U_{a b}$, considered as zero section in $U_{a}$, write $u+v:=(u y v)$ for the group law in $U_{a}$ and $x \cdot z:=(x y z)$ for $x, z \in U_{a}$. Then, identifying $U_{a}$ with $\operatorname{Map}\left(y, G^{a}\right)$ as above, we have, for all $x, z \in \operatorname{Map}\left(y, G^{a}\right)$,

$$
x \cdot z=x \circ B_{y}^{b z a}+z .
$$

Proof. The theorem and its proof follow closely the corresponding result in the group case ( $[\overline{\mathrm{Be} 12}]$, Th. 8.1; cf. figure below). The element of $\operatorname{Map}\left(y, G^{a}\right)$ corresponding to $x \cdot z$ is

$$
y \rightarrow G^{a}, \eta \mapsto \lambda_{\omega, \eta}^{a}, \quad \text { where } \omega=P_{x \cdot z}^{a}(\eta)
$$

Let $\zeta:=P_{z}^{a}(\eta)$. Then $\omega=\left[P_{x}^{a} P_{y}^{b}(\zeta) P_{y}^{b}(\zeta) \zeta\right]$ : this element belongs to $x \cdot z$ and is $a$-related to $\zeta$ and to $\eta$. Thus, letting $\eta^{\prime}:=P_{y}^{b}(\zeta)=P_{y}^{b} P_{z}^{a}(\eta)=B_{y}^{b z a}(\eta), \xi:=$ $P_{x}^{a}\left(\eta^{\prime}\right)=P_{x}^{a} P_{y}^{b}(\zeta)=P_{x}^{a} B_{y}^{b z a}(\eta)$, we have $\omega=\left[\xi \eta^{\prime} \zeta\right]$. Then we have $\lambda_{\omega, \zeta}^{a}=\lambda_{\xi, \eta^{\prime}}^{a}$, so

$$
\lambda_{\omega, \eta}^{a}=\lambda_{\omega, \zeta}^{a} \circ \lambda_{\zeta, \eta}^{a}=\lambda_{\zeta, \eta^{\prime}}^{a} \circ \lambda_{\zeta, \eta}^{a}=\lambda_{P_{x}^{a} B_{y}^{b z a}(\eta), B_{y}^{a z b}(\eta)}^{a} \circ \lambda_{\zeta, \eta}^{a},
$$

which, written additively, corresponds to the formula given in the claim.
Recall from [Be12] that the formula given in the theorem is the non-linear generalization of bilinear formulae from associative and Jordan algebraic setting. The proof gives in fact an algorithm permitting to draw (using dynamical geometry software, such as geogebra) the curve $x \cdot z$ as a function of $\eta$, as in the following illustration:


Theorem 4.3. Assume $a$ is a left prev and $b$ a right prev on $\Omega$ commuting with $a$. Then we have the following "right distributive law": for all $x, y \in U_{a b}$ and $u, v, w \in U_{b}$,

$$
\left((u v w)_{a} y z\right)_{a b}=\left((u y z)_{a b}(v y z)_{a b}(w y z)_{a b}\right)_{a},
$$

which can also be written, with notation introduced above,

$$
((u-v+w) y z)_{a b}=(u y z)_{a b}-(v y z)_{a b}+(w y z)_{a b} .
$$

In other words, right multiplications operators $R_{z b y a}$ from $U_{a b}$ are automorphisms of the torsor $U_{a}$. Similarly, left multiplications from $U_{a b}$ are automorphisms of the torsor $U_{b}$.

Proof. By the preceding result

$$
\begin{aligned}
(u-v+w) \cdot z & =(u-v+w) \circ B_{y}^{b z a}+z \\
& =\left(u \circ B_{y}^{b z a}+z\right)-\left(v \circ B_{y}^{b z a}+z\right)+\left(w \circ B_{y}^{b z a}+z\right) \\
& =(u \cdot z)-(v \cdot z)+(w \cdot z)
\end{aligned}
$$

(see [Be12], Th. 8.3, for the - similar - proof in the group case).
Note that, in general, $U_{a}$ will not be left-distributive with respect to ()$_{a b}$. In this respect, this structure resembles the one of a near-ring, cf. [Pi77] (cf. [Be12]).

## 5. The homogeneous case, and duality

5.1. The group case. Assume $(\Omega,+)$ is a group and $A, B$ are two subgroups of $\Omega$. Then $(\Omega, a, b,[\quad])$ as defined in example A. 6 is a pregroupoid, coming from two commuting prev's $(a, b)$. Thus all of the preceding results apply (see Be12] for more details). The description of the set $(x y z)_{a b}$ from Theorem 2.1 can be rewritten as in Equation (0.5). The system of three equations given in (0.5),

$$
\begin{equation*}
\eta=\alpha+\xi, \quad \eta=\zeta+\beta, \quad \omega=\xi-\eta+\zeta \tag{5.1}
\end{equation*}
$$

is called the structure equations. As a specific feature of the group case, the structure equations can be rewritten in various equivalent ways, see [Be12], Lemma 2.3. The form given in (5.1) is closest to the interpretation used in this work; but there are other forms suggesting other interpretations, invoquing some sign changes (recorded by the "sign-vectors" listed in section 9 of [Be12]). One may distinguish two different guises of the structure equations, having a quite different flavor:
5.2. Duality, and antiautomorphisms. On the one hand, there is a number of ways to rewrite (5.1) in the form of 3 equations, two of them invoking 3 variables and the last one invoking 4 variables. These equations all "have the same shape", up to the possible sign changes (collected by the sign-vectors), and thus take account of a high degree of symmetry in the group case, including the possibility of antiautomorphisms - recall from [BeKi10b] that, for abelian groups $(\Omega,+)$, orthocomplementation maps are indeed antiautomorphisms in this sense (and so far these are the only examples of antiautomorphisms we know of).
5.3. Triangle configurations. The structure equations can also be rewritten as systems of three equations, each of them invoking 3 variables, e.g.,

$$
\left\{\begin{array}{c}
\eta=\alpha+\xi  \tag{5.2}\\
\beta=-\omega+\xi \\
\zeta= \\
\zeta=\alpha+\omega
\end{array}\right\} \quad\left\{\begin{array}{l}
\alpha=\eta-\xi \\
\zeta= \\
\omega=\eta-\beta \\
\omega=
\end{array}\right\} \quad\left\{\begin{array}{l}
\alpha=\beta-\omega \\
\xi=\omega+\beta \\
\eta=\zeta+\beta
\end{array}\right\}
$$

This form of the equations suggests an entirely different interpretation of the system: the variables appearing just once shall correspond to equivalence relations (given by cosets) and those appearing twice correspond to sets whose elements are in the respective relation. Thus we deal with three relations. Graphically, we have triangles, instead of parallelograms. Neglecting the sign changes, the following figures would then correspond to the three systems from (5.2):


Unlike the interpretation invoking parallelograms, these triangle configurations do not need at all the underlying group or pregroupoid structure of $\Omega$ : they make sense on a "naked set". Thus such interpretation seems even more basic than the preceding one. Indeed, whereas for usual mappings there is essentially just one "type of commuting triangles", for binary relations the term "commuting triangle" may have several different meanings, and it looks as if the structure equations were related to this. To our knowledge, such questions have so far only been investigated from the point of view of computer science, see e.g., the "diagram chase for relations", [ES04]. It would certainly be worth investigating this from a more theoretical and algebraic point of view.

## Appendix A. The familily of associoids

We assume that the reader is familiar with the most important binary associative structures: (semi-)groups, monoids, groupoids, algebras. In this appendix we give definitions and fix terminology concerning related ternary associative structures. Since their laws need not be defined everywhere, we use the suffix -oid, and call associoids the most general family of such structures. They arise naturally in various contexts, but often are are not recognized as such (e.g., principal bundles are rarely seen as ternary algebraic structures).

## A.1. Associoids and semi-associoids.

Definition A.1. Let $M$ be a set. A partially defined ternary product on $M$ is a map, defined on some non-empty subset $D \subset M^{3}$ (called domain of $\mu$ ),

$$
\mu: D \rightarrow M, \quad(x, y, z) \mapsto \mu(x, y, z)
$$

According to context, we use other notation for $\mu(x, y, z)$, such as $(x y z)$ or $[x y z]$.

Definition A.2. A semi-associoid is a set $M$ together with a partially defined ternary product $(x y z)=\mu(x, y, z)$ on $M$ satisfying the para-associative law:

$$
\begin{equation*}
(x y(z u v))=(x(u z y) v)=((x y z) u v) \tag{PA}
\end{equation*}
$$

that is, if all terms on one side of the equation are defined, then so are those on the other sides, and we have equality. For instance, if $(z, u, v) \in D$ and $(x, y,(z u v)) \in$ $D$, then $(u, z, y) \in D$ and $(x,(u z y), y) \in D$, and the first equality holds, and so on. An associoid is a semi-associoid satisfying the idempotent law:

$$
\begin{equation*}
(x x y)=y, \quad(w z z)=w \tag{IP}
\end{equation*}
$$

whenever $(x, x, y) \in D$ and $(w, z, z) \in D$.
Lemma A.3. The associoid axioms $(P A) \wedge(I P)$ are equivalent to $(C h) \wedge(I P)$ :
(Ch) left Chasles relation: $(x y(y u v))=(x u v)$, and right Chasles relation: $((x y z) z v)=(x y v)$;
(IP) idempotency: $(x x y)=y=(y x x)$
Proof. (IP) $\wedge(\mathrm{Ch})$ implies (PA): $(x y(u v w))=((x y u) u(u v w))=((x y u) v w)$, and conversly (IP) $\wedge(\mathrm{PA})$ implies (Ch) by taking $y=z$.
In his work Ko82, Ko05, Ko07], Kock uses (IP) ("unit law") $\wedge(\mathrm{Ch})(" c a n c e l l a t i o n$ law") as basic axioms; note, however, that the lemma does not carry over to semiassocioids. There is a number of other useful identities valid in general associoids, most of them well-known for torsors (see below), for instance,

$$
\begin{equation*}
(x y(u v w))=((x y u) v w)=((x y u)(y x(x y v)) w)=((x y u)(x y v)(x y w)) \tag{A.1}
\end{equation*}
$$

which, in case the product is defined everywhere, means that left translations $\ell_{x y}$ are endomorphisms. Similarly, right translations satisfy the endomorphism property.
A.2. Torsors and semitorsors. This is the case of everywhere defined products:

Definition A.4. A semitorsor is a semi-associoid with an everywhere defined ternary product map (often denoted by $G^{3} \rightarrow G,(x, y, z) \mapsto(x y z)$ ), and a torsor is a semitorsor satisfying the idempotent law. ${ }^{2}$

Fixing the middle element $y$ in a torsor $G$, we get a group law $x z:=(x y z)$ with neutral element $y$ and inversion $x^{-1}=(y x y)$, and every group is obtained in this way; thus torsors are for groups what affine spaces are for vector spaces. Similarly, semitorsors give rise to semigroups, but the converse is more involved. Two kinds of examples will play a basic role in this work:
Example A. 1 (Relation semitorsors and mapping torsors). The set $M:=\mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ of binary relations between $\Omega$ and $\Omega^{\prime}$ is a semitorsor: the everywhere defined ternary product $[R S T]:=R S^{-1} T$ is para-associative, by associativity of binary composition and involutivity of reversion. Likewise, the set $\operatorname{Bij}(X, Y)$ of bijections between two sets $X$ and $Y$, with the law $(x y z)=x y^{-1} z$, is a torsor.
Example A. 2 (Torsors of sections). The set of sections of a principal bundle is a torsor, see cor. 2.2.

[^2]In every semitorsor, we introduce left-, right- and middle multiplication operators

$$
\begin{equation*}
\ell_{x, y}(z)=(x y z)=r_{z, y}(x)=m_{x, z}(y) \tag{A.2}
\end{equation*}
$$

These are everywhere defined operators $\ell_{x, y}: M \rightarrow M$, etc., and all defining identitities may be rewritten in terms of these operators. In particular, the left Chasles relation reads $\ell_{a b} \ell_{b c}=\ell_{a c}$, and the right Chasles relation becomes the "transplantation formula"

$$
\begin{equation*}
\ell_{x y}=\ell_{(x y z) z} \tag{A.3}
\end{equation*}
$$

See appendices of BeKi10a, Be13] for some more remarks on general (semi)torsors.
A.3. Pregroupoids and semi-pregroupoids. From now on, the domain of definition $D \subset M^{3}$ of the ternary product will depend on the choice of a pair of equivalence relations $(a, b)$ on $M$. We symbolize this situation by


Consider the following four sets

$$
\begin{align*}
M \times_{a} M \times M & =a \times M=\left\{(x, y, z) \in M^{3} \mid x \sim_{a} y\right\} \\
M \times M \times_{b} M & =M \times b=\left\{(x, y, z) \in M^{3} \mid y \sim_{b} z\right\} \\
M \times_{a} M \times_{b} M & =(a \times M) \cap(M \times b) \\
& =\left\{(x, y, z) \in M^{3} \mid x \sim_{a} y \text { and } y \sim_{b} z\right\} \\
(a \times M) \cup(M \times b) & =\left\{(x, y, z) \in M^{3} \mid x \sim_{a} y \text { or } y \sim_{b} z\right\} . \tag{A.5}
\end{align*}
$$

Definition A.5. A semi-pregroupoid is given by a set $M$ together with a pair $(a, b)$ of equivalence relations on $M$ and a para-associative ternary multiplication

$$
M \times_{a} M \times_{b} M \rightarrow M, \quad(x, y, z) \mapsto[x y z]
$$

such that, for all $(x, y, z) \in M \times_{a} M \times_{b} M$,

$$
\begin{equation*}
[x y z] \sim_{a} z, \quad[x y z] \sim_{b} x \tag{C}
\end{equation*}
$$

If, moreover, the multiplication satisfies the idempotent law, then $M$ is called a pregroupoid $\sqrt[3]{ }$

Note that Condition (C) ensures that our requirement on the domain $D$ from Definition A. 1 is fulfilled.

Lemma A.6. If $(M, a, b,[\quad])$ is a semi-pregroupoid, then $a$ and $b$ commute as relations: $a b=b a$.

Proof. Let $(x z) \in a b$, so there is $y \in M$ with $(x, y) \in a,(y, z) \in b$. Thus $w:=[x y z]$ is defined, and by $(\mathrm{C})$, we have $(x, w) \in b,(w, z) \in a$, showing that $(x, z) \in b a$.

The condition $a b=b a$ may be seen as a sort of "integrability condition" - indeed, it is well-known (and easy to prove) that $a$ and $b$ commute iff the new relation $a b$ is again an equivalence relation.

[^3]Example A. 3 (The relation semi-pregroupoid). Let $M:=\mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ be the set of binary relations between $\Omega$ and $\Omega^{\prime}$. For two relations $R, S \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right)$ write

$$
R \sim_{a} S: \Leftrightarrow \operatorname{dom}(R)=\operatorname{dom}(S), \quad R \sim_{b} S: \Leftrightarrow \operatorname{im}(R)=\operatorname{im}(S) .
$$

The para-associative law for the ternary product $[R S T]:=R S^{-1} T$ is always satisfied (example A. 1 above). Moreover, it follows directly from definitions that its restriction to $(a \times M) \cap(M \times b)$ satisfies condition (C). The idempotent law is not satisfied.

Example A. 4 (Pair semi-pregroupoid). Assume $M=E \times F, a, b$ the equivalence relations given by fibers of $\mathrm{pr}_{1}, \mathrm{pr}_{2}$, so

$$
M \times_{a} M \times_{b} M=\left\{(x, y, z) \in M^{3} \mid x_{1}=y_{1}, y_{2}=z_{2}\right\}
$$

and then the algebraic law is already completely determined by Condition (C):

$$
[x y z]=\left(z_{1}, x_{2}\right) .
$$

Put differently: whenever $a \top b$, there is just one possible semi-pregroupoid structure on ( $M, a, b$ ) (which is in fact a pregroupoid structure). It generalizes the pair groupoid (case $E=F$, cf. CW99]), and we will use the same term. As for the case of groupoids, for any (semi-) pregroupoid, the canonical map

$$
M \rightarrow M / a \times M / b, \quad x \mapsto\left([x]_{a},[x]_{b}\right)
$$

is a morphism of (semi-) pregroupoids onto a pair groupoid (see [CW99], 13.2).
Example A. 5 (Pseudogroup of local bijections). Let $M$ be the set of locally defined bijections between $\Omega$ and $\Omega^{\prime}$, that is,

$$
M=\left\{R \in \mathcal{R}\left(\Omega^{\prime}, \Omega\right) \mid \forall x \in \operatorname{dom}(R): \exists!y \in \operatorname{im}(R):(y, x) \in R\right\}
$$

Then $M$ is sub-semi-pregroupoid of the one given in the preceding example, and it satisfies the idempotent law, hence is a pregroupoid. In a context of manifolds and smooth maps, it corresponds to what one calls a pseudogroup of local diffeomorphisms.

Example A. 6 (Homogeneous pregroupoids). Let $G$ be a group (not assumed commutative, but written additively) and $A, B$ two subgroups of $G$. Define the right equivalence relation $x \sim_{a} y$ iff $A+x=A+y$ (so equivalence classes are right cosets of $A$ ), and the left equivalence relation $x \sim_{b} y$ iff $x+B=y+B$ (so equivalence classes are left cosets of $B$ ), and let $[x y z]=x-y+z$ (which is the usual torsor law of $G$, and thus is para-associative and idempotent). Then $(G, a, b,[])$ is a pregroupoid which we denote by

$$
\begin{equation*}
G / B \leftarrow G \rightarrow A \backslash G \tag{A.6}
\end{equation*}
$$

Indeed, the compatibilty condition $(\mathrm{C})$ is easily checked. One should note that the structure of $(G, A, B,[\quad])$ is in fact much richer: it is a pregroupoid with a certain additional structure, which is witnessed by the term "homogeneous". (A homogeneous pregroupoid is transitive in the obvious sense, see subsection A.7, and a transitive pregroupoid is a quotient of some $(G, A, B)$, where $G$ is a, in general not uniquely determined, group coming from transitive structure.) Note also that
this pregroupoid structure does in general not come from a groupoid structure: the quotient sets $G / B$ and $A \backslash G$ need not be isomorphic as sets.

Example A.7. If $a=b$, then a pregroupoid ( $\Omega, a, a,[\quad]$ ) is the same thing as a torsor bundle over $\Omega / a$. A torsor bundle together with some fixed section is a group bundle. In particular, vector bundles are a special kind of associoids.
A.4. Principal equivalence relations (prev's). This is an algebraic concept corresponding to the one of principal bundle:

Definition A.7. A (left) principal equivalence relation (abbreviated: (left) prev) ( $M, a,[\quad]$ ) is an associoid ( $M, D,[\quad]$ ) with domain $D=a \times M$ given by an equivalence relation $a$ on $M$ and such that

$$
\forall(x, y) \in a, \forall z \in M: \quad([x y z], z) \in a
$$

In other words, it is a pregroupoid defined by $(a, b)$ with $b=\mathbf{O}_{M}$. Similarly, a right principal equivalence relation on a set $M$ is an associoid with domain $M \times b$, that is, a pregroupoid with $a=\mathbf{O}_{M}$. (4)

The good thing about left prev's is that the left translation operators $\lambda_{x y}^{a}: z \mapsto[x y z]$ are everywhere defined. We often write $[x y ; z]_{a}:=[x t z]$ and view a left prev as an equivalence relation $a$ together with a "left action map"

$$
\lambda^{a}: a \times M \rightarrow M, \quad((\xi, \eta), \zeta) \mapsto \lambda_{\xi \eta}^{a}(\zeta)=:[\xi \eta ; \zeta]_{a}
$$

such that
(1) $\lambda_{x y}^{a}$ preserves each $a$-equivalence class, that is, $a \circ \lambda_{x y}^{a}=a=\lambda_{x y}^{a} \circ a$ under relational composition,
(2) for all $(x, y) \in a$ and $(v, w) \in a$, we have

$$
\begin{aligned}
& \lambda_{x x}^{a}=\operatorname{id}_{\Omega}, \lambda_{x y}^{a}(y)=x \\
& \lambda_{x y} \circ \lambda_{v w}=\lambda_{[x y v], w}=\lambda_{x,[w v y]}
\end{aligned}
$$

which imply Chasles' relation $\lambda_{x y} \circ \lambda_{y z}=\lambda_{x z}$ and $\left(\lambda_{x y}\right)^{-1}=\lambda_{y x}$ as well as

$$
\begin{equation*}
\lambda_{x y}^{a}=\lambda_{u, \lambda_{x y}^{a}(u)}^{a} . \tag{A.7}
\end{equation*}
$$

Since each equivalence class of $a$ is a torsor, it follows that the left translation group

$$
\begin{equation*}
G:=G^{a}:=\left\{\lambda_{x y}^{a} \mid(x, y) \in a\right\} \tag{A.8}
\end{equation*}
$$

acts simply transitively on each $a$-class. Thus $\left(M, G^{a}, M / a\right)$ is an "abstract principal bundle".

Lemma A.8. There is a bijection between left prev's (M, a, [ $]_{a}$ ) on $M$ and (abstract) left principal bundles $(P, G, B)$ with total space $P=M$.

Proof. One direction is explained above; conversely, given $(P, G, B)$, let $a$ be the fiber relation of the canonical projection $P \rightarrow B$ and define, for $(x, y) \in a$ and $z \in P,[x y ; z]:=\lambda_{x y}(z)$, where $g:=\lambda_{x y} \in G$ is the unique element such that $g(y)=x$.

[^4]Similarly, a right prev on $M$ is an equivalence relation $b \in \mathcal{E}_{\Omega}(M)$ together with a "right action map" satisfying the para-associative and idempotent laws,

$$
\rho^{b}: \Omega \times b \rightarrow \Omega, \quad(x,(y, z)) \mapsto \rho_{z y}^{b}(x)=:[x ; y z]_{b}
$$

Example A. 8 (The homogeneous pregroupoid revisited). Let $\Omega=G$ and $A, B, a, b$ as in example A.6. Then $G \rightarrow G / B$ and $G \rightarrow A \backslash G$ are principal bundles, corresponding to left- and right prevs given by $[x y ; z]_{a}=x-y+z=[x ; y z]_{b}$.

## A.5. Commuting left and right prev's.

Definition A.9. A pair $(a, b)$ of commuting left and right prev's is an associoid given by a pair $(a, b)$ of equivalence relations on $M$ and the ternary product $[x y z]$ defined on the domain

$$
D_{a, b}:=(a \times M) \cup(M \times b)
$$

such that

$$
\forall(x, y) \in a, \forall z \in M: \quad[x y z] \sim_{a} z, \quad \forall x \in M, \forall(y, z) \in b: \quad[x y z] \sim_{b} x
$$

In other words, $\left(M, a,[x y ; z]_{a}\right)$ is a left prev and $\left(M, b,[x ; y z]_{b}\right)$ a right prev such that the natural compatibility conditions given below are satisfied.

Since $(a \times M) \cap(M \times b) \subset(a \times M) \cup(M \times b)$, it is clear that a pair of commuting prev's defines, by restriction of the product map to a smaller domain, a pregroupoid (but not every pregroupoid is of this form). The definition may be stated equivalently: a pair of commuting prev's is given by a left prev $a$ and a right prev $b$ on $\Omega$ that are compatible in the sense that

$$
(x, y) \in a,(y, z) \in b \quad \Rightarrow \quad[x y ; z]_{a}=[x ; y z]_{b},
$$

and which, moreover, commute in the sense that

$$
\forall(x, y) \in a,(w, z) \in b: \quad \lambda_{x y}^{a} \circ \rho_{u v}^{b}=\rho_{u v}^{b} \circ \lambda_{x y}^{a}
$$

The last condition can be rewritten $\left[x y ;[v ; w z]_{b}\right]_{a}=\left[[x y ; v]_{a} ; w z\right]_{b}$, for all $v \in \Omega$. By compatibility, it implies, if moreover $v \sim_{a} w$ and $v \sim_{b} y$,

$$
\left[x y ;[v ; w z]_{b}\right]_{a}=\left[x[w ; v y]_{b} ; z\right]_{a}=\left[x[w ; v y]_{b} ; z\right]_{a}
$$

Lemma A.10. If $(a, b)$ is a pair of commuting left and right prev's, then $a$ and $b$ commute as relations: $a b=b a$, and left translation operators $\lambda_{x y}^{a}$ permute equivalence classes of $b$, and vice versa:

$$
x \sim_{a} y, u \sim_{b} v \quad \Rightarrow \quad[x y ; u]_{a} \sim_{b}[x y ; v]_{a} \text { and }[x ; u v]_{b} \sim_{a}[y ; u v]_{b}
$$

Proof. That $a b=b a$ has been seen above (Lemma A.6). The other claim follows from $\lambda_{x y}^{a}(v)=\lambda_{x y}^{a} \rho_{v u}^{b}(u)=\rho_{v u}^{b} \lambda_{x y}^{a}(u) \sim_{b} \lambda_{x y}^{a}(u)$.
Definition A.11. The automorphism group of an equivalence relation $a$ is the group permuting equivalence classes of $a$ :

$$
\operatorname{Aut}(a)=\{g \in \operatorname{Bij}(M) \mid g \circ a=a \circ g\}
$$

(so that the induced map $[g]: M / a \rightarrow M / a$ is well-defined), and the group of strict automorphisms of $a$ is the group preserving each equivalence class of $a$ :

$$
\operatorname{Aut}_{1}(a)=\{g \in \operatorname{Bij}(M) \mid g \circ a=a=a \circ g\}
$$

(so that the induced map is $\mathrm{id}_{M / a}$ ).
Thus by the lemma we have $\lambda_{x y}^{a} \in \operatorname{Aut}_{1}(a) \cap \operatorname{Aut}(b)$ and $\rho_{u v}^{b} \in \operatorname{Aut}_{1}(b) \cap \operatorname{Aut}(a)$.
Example A. 9 (Homogeneous pregrouids). Let $A, B$ be two subgroups of a group $\Omega$. Then the left prev $b$ defined by $B$ commutes with the right prev $a$ defined by $A$. Note that $a b=b a$ then is again an equivalence relation (its equivalence classes are the double cosets $A \backslash \Omega / B$ ), but it is not a prev.
A.6. From pregroupoids to groupoids: back and forth. A groupoid is a pregroupoid $(M, a, b)$ such that $M / a$ and $M / b$ are isomorphic and having a distinguished set of units and an inversion map, and the whole object is encoded by a binary partially defined operation, rather than by a ternary one. It is a remarkable fact that such a structure arises simply by distinguishing an arbitrary bisection in a pregroupoid, which defines the set of units. The following lemma is contained in the work of Johnstone Jo91, although it is not formally stated there. 5

Definition A.12. A bisection of a pregroupoid $(M, a, b)$ is a bisection of $(a, b)$, i.e., an element of $U_{a b}$, and $a$ local bisection is an element of $U_{a b}^{\mathrm{loc}}$ (cf. eqn. (1.9)).

In general, a pregroupoid does not admit bisections (since $M / a$ and $M / b$ need not be equinumerous). For a fixed bisection $s$, and for any $g \in M$, we let $a_{g}:=[g]_{a} \cap s$ and $b_{g}:=[g]_{b} \cap s$. Then we define the inverse of $g$ (with respect to $s$ ) by

$$
\begin{equation*}
g^{-1}:=\left[a_{g} g b_{g}\right], \tag{A.9}
\end{equation*}
$$

and, if $b_{g}=a_{h}$, then we define the (binary) composition of $g$ and $h$ by

$$
\begin{equation*}
g \circ h:=\left[g b_{g} h\right]=\left[g a_{h} h\right] . \tag{A.10}
\end{equation*}
$$

Lemma A.13. Let $(M, a, b)$ be a pregroupoid with a distinguished bisection $s$. Then $M$ with inversion and partially defined binary composition as above becomes a groupoid with set of units s. Conversely, every groupoid arises in this way from a pregroupoid. Thus groupoids are the same as as pregroupoids $(M, a, b)$, together with some fixed bisection s, representing the set of units.

Proof. $f(g h)=\left[f a_{f}\left[g a_{h} h\right]\right]=\left[\left[f a_{f} g\right] a_{h} h\right]=(f g) h$ follows immediately from paraassociativity, $g a_{g}=\left[g a_{a} a_{g}\right]=g$ and $b_{g} g=\left[b_{g} b_{g} g\right]=g$ from idempotency, and $g \circ g^{-1}=\left[g a_{g}\left[a_{g} g b_{g}\right]\right]=\left[\left[g a_{g} a_{g}\right] g b_{g}\right]=\left[g g b_{g}\right]=b_{g}$ and $g^{-1} \circ g=a_{g}$ from paraassociativity and idempotency.

In chapter 2 of the present work, the lemma appears as special case of more general results. Here is an illustration, following Cannas da Silva and Weinstein CW99. We prefer to draw $s$ as a curved line, instead of a straight one, in order to stress that, in principle, any bisection can serve as set of units. Note that $\left(x, y^{-1}, z, x y z\right)$ forms a parallelogram, and given $x, y^{-1}, z$, the last vertex does not depend on the bisection $s$ :

[^5]

Summing up, just as for torsors and groups, working with a ternary map has the advantage of using a single map, containing both inversion and the binary multiplications. For instance, categorical definitions are greatly simplyfied by viewing groups and groupoids as defined by ternary maps, and adding a unit element, respectively a bisection, as structure. Obviously, there is a forgetful functor forgetting this additional structure. For general pregroupoids, Kock has constructed an adjoint functor to this forgetful functor, see [Ko87, Ko05, Ko07].
A.7. On transitive pregroupoids. It is well-known that general groupoids can be decomposed into a disjoint union of transitive groupoids (see [CW99, Ma05]). For pregroupoids, the analog is as follows.

Definition A.14. Let ( $M, a, b,[\mathrm{l})$ be a pregroupoid. Recall (Lemma A.6) that the relations $a, b$ commute, and hence $c:=a b$ is again an equivalence relation on $M$. The quivalence classes of $c$ are called the connected components of (M, a,b,[ ]). We say that the pregroupoid is transitive if it has just one equivalence class. In other terms, the morphism onto the pair pregroupoid

$$
M \rightarrow M / a \times M / b, \quad x \mapsto\left([x]_{a},[x]_{b}\right)
$$

(see Example A.4) is surjective.
It is now obvious that every pregroupoid can be decomposed into a disjoint union of transitive pregroupoids. Moreover, any transitive pregroupoid can be decomposed, in a non-canonical way, after fixing a base point $\left([x]_{a},[z]_{b}\right) \in M / a \times M / b$, as a product

$$
\begin{equation*}
M \cong H \times(M / a \times M / b), \tag{A.11}
\end{equation*}
$$

where, $H:=[x]_{a} \cap[y]_{b}$ is a torsor with product $x y^{-1} z$, considered as a pregroupoid over a point (see [Br87], p. 119 for this item, in the case of groupoids). Next, since the group $L:=\operatorname{Bij}(E) \times \operatorname{Bij}(F)$ acts transitively by automorphisms of the pair pregroupoid on $E \times F$, by putting things together, it can be shown that every transitive pregroupoid is a quotient of a homogeneous pregroupoid $(G, G / A, B \backslash G)$ (example A.6, but of course the group $L$ is chosen much too big for everydaylifesituations). Finally, if the pregroupoid does not admit bisections, by using Kock's construction, we may pass to an even bigger transitive enveloping groupoid.

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[^1]:    ${ }^{1}$ There is a serious problem of terminology: for most of these objects, there is no universally accepted term, und we are well-aware that the terminology we use here may be unsatisfying. We hope that, in a not too distant future, the mathematical community will agree on a better terminology, once the importance of ternary product structures is more widely recognized.

[^2]:    ${ }^{2}$ Other terms used in the literature instead of "torsor" are groud, heap, pregroup, herd or principal homogeneous space.

[^3]:    ${ }^{3}$ This terminology is due to Kock, see Ko05, Ko07]. Johnstone uses herdoid, see Jo91].

[^4]:    ${ }^{4}$ Once more, there may be conflicts of terminology: what is called "torseur" in DG70 corresponds to what we would call a "prev in the category of schemes".

[^5]:    ${ }^{5}$ loc. cit., p. 103: "Conversely, given a herdoid for which $A$ and $B$ happen to coincide, any choice of simultaneous splitting for $\alpha$ and $\beta$ (if such a thing exists) equips it with a groupoid structure."

