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# Numerical simulation of quadratic BSDEs 

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#### Abstract

This article deals with the numerical approximation of Markovian backward stochastic differential equations (BSDEs) with generators of quadratic growth with respect to $z$ and bounded terminal conditions. We first study a slight modification of the classical dynamic programming equation arising from the time-discretization of BSDEs. By using a linearization argument and BMO martingales tools, we obtain a comparison theorem, a priori estimates and stability results for the solution of this scheme. Then we provide a control on the time-discretization error of order $\frac{1}{2}-\varepsilon$ for all $\varepsilon>0$. In the last part, we give a fully implementable algorithm for quadratic BSDEs based on quantization and illustrate our convergence results with numerical examples.


Key words: Backward stochastic differential equations; generator of quadratic growth; time discretization, numerical approximation.

MSC Classification (2000): 60H10, 65C30

[^0]
## 1 Introduction

In this paper, we are interested in the numerical approximation of solutions to a special class of backward stochastic differential equations (BSDEs for short in the sequel). Let us recall that solving a BSDE consists in finding an adapted couple $(Y, Z)$ satisfying the equation

$$
Y_{t}=\xi+\int_{t}^{T} f\left(s, Y_{s}, Z_{s}\right) d s-\int_{t}^{T} Z_{s} d W_{s}, \quad 0 \leqslant t \leqslant T
$$

where $W$ is a $d$-dimensional Brownian motion on a probability space $(\Omega, \mathcal{A}, \mathbb{P})$. We denote by $\left(\mathcal{F}_{t}\right)_{0 \leqslant t \leqslant T}$ the Brownian filtration. In there seminal paper [36], Pardoux and Peng provide the existence of a unique solution $(Y, Z)$ to this equation for a given square integrable terminal condition $\xi$ and a Lipschitz random driver $f$. Many extensions to this Lipschitz setting have been considered. In particular, the class of BSDE, with generators of quadratic growth with respect to the variable $z$, has received a lot of attention in recent years. These equations arise, by example, in the context of utility optimization problems with exponential utility functions, or alternatively in questions related to risk minimization for the entropic risk measure (see e.g. [39, 25, 34] among many other references). Existence and uniqueness of solution for such BSDEs has been first proved by Kobylanski [32]. Since then, many authors worked on this question. When the terminal condition is bounded, we refer to $[32,33,40,6]$, and, in the unbounded case, we refer to $[7,3,8,18,17]$.

We will focus here on the numerical approximation of the so-called 'quadratic BSDEs' in a Markovian setting namely

$$
\begin{align*}
X_{t} & =x+\int_{0}^{t} b\left(X_{s}\right) d s+\int_{0}^{t} \sigma\left(X_{s}\right) d W_{s}  \tag{1.1}\\
Y_{t} & =g\left(X_{T}\right)+\int_{t}^{T} f\left(X_{s}, Y_{s}, Z_{s}\right) d s-\int_{t}^{T} Z_{s} d W_{s} \tag{1.2}
\end{align*}
$$

Throughout this paper, we assume that the functions $b: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d \times d}, \sigma: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d \times d}$ are $K$-Lipschitz continuous functions and the function $g$ is a bounded $K$-Lipschitz continuous function, for a positive constant $K$. We also assume that the function $f: \mathbb{R}^{d} \times \mathbb{R} \times \mathbb{R}^{1 \times d} \rightarrow \mathbb{R}$ is a $K$-Lipschitz continuous function with respect to $x$ and $y$ i.e.

$$
\left|f\left(x_{1}, y_{1}, z\right)-f\left(x_{2}, y_{2}, z\right)\right| \leqslant K\left(\left|x_{1}-x_{2}\right|+\left|y_{1}-y_{2}\right|\right)
$$

for all $y_{1}, y_{2} \in \mathbb{R}, x_{1}, x_{2} \in \mathbb{R}^{d}$ and $z \in \mathbb{R}^{1 \times d}$, and a $L$-locally Lipschitz continuous
function with respect to $z$ : for all $x \in \mathbb{R}^{d}, y \in \mathbb{R}, z, z^{\prime} \in \mathbb{R}^{1 \times d}$,

$$
\left|f(x, y, z)-f\left(x, y, z^{\prime}\right)\right| \leqslant L\left(1+|z|+\left|z^{\prime}\right|\right)\left|z-z^{\prime}\right|
$$

where $L$ is a positive constant. Moreover $f$ is bounded with respect to $x$ : for all $x \in \mathbb{R}^{d}$, $y \in \mathbb{R}, z \in \mathbb{R}^{1 \times d}$,

$$
|f(x, y, z)| \leqslant L\left(1+|y|+|z|^{2}\right)
$$

Let us notice that all convergence results obtained in this paper do not need extra assumptions on $b, \sigma, f$ and $g$. Especially, we emphasize that no uniform ellipticity condition is necessary on $\sigma$.

### 1.1 Known results on the approximation of quadratic BSDEs

The design of efficient algorithms to solve BSDEs in any reasonable dimension has been intensively studied since the first work of Chevance [13], see e.g. [41, 4, 21, 10, 9] and the references therein. In all these articles, the driver $f$ of the BSDE is a Lipschitz function with respect to $z$ and this assumption plays a key role in the proofs.

Up to now, there have been few results on the time-discretization and numerical simulation of quadratic BSDEs. We review now all the techniques that allow to compute the solution of quadratic BSDEs, to the best of our knowledge. None of them provide a suitable complete answer to the approximation of the BSDE (1.2).

First of all, when the generator has a specific form (roughly speaking the generator is a sum of a purely quadratic term $z \mapsto C|z|^{2}$ and a Lipschitz function) it is possible to solve almost explicitly the quadratic BSDE by using an exponential transformation method, also called Cole-Hopf transform (see e.g. [27]).

It is also possible to solve some specific quadratic Markovian BSDEs by solving a fully coupled forward backward system, i.e. when $Y$ and $Z$ appear also in the coefficients of (1.1). This is the method used by Delarue and Menozzi in [15, 16] where they solved in particular the deterministic KPZ equation. But approximation results for fully coupled forward backward systems need strong assumptions on the regularity of coefficients and a uniform ellipticity assumption for $\sigma$. Moreover, their implementation is not straightforward (due to the coupling).

In some cases, one can also rely on 'classical' schemes for Lipschitz BSDEs in order to numerically solve quadratic BSDEs. Indeed, when the terminal condition $g$ is a bounded Lipschitz function and $\sigma$ is bounded then it is known that $Z$ is bounded by
a constant $M$ (see e.g. Theorem 3.6 in [38]). Since the generator $f$ is assumed to be locally Lipschitz with respect to $z$, one only needs to replace the generator $f$ by a new generator $\tilde{f}_{M}(., .,)=.f\left(., ., \varphi_{M}().\right)$ where $\varphi_{M}$ is the projection on the centered Euclidean ball of radius $M$. Then, one can easily show that these two BSDEs with generators $f$ and $\tilde{f}_{M}$ have the same solution. It is then possible to solve the second BSDE with Lipschitz driver $\tilde{f}_{M}$ to retrieve the solution to the quadratic BSDE. Let us remark that some exponential terms appear in the constant $M$ which lead to a new generator with possibly huge Lipschitz constant with respect to $z$ and may cause numerical difficulties, see citeBender-Steiner-12.

In the general case, $Z$ may be unbounded. Nevertheless, when $g$ is a bounded Lipschitz function and $\sigma$ is Lipschitz but not necessarily bounded the following non-uniform bound holds true

$$
\begin{equation*}
\left|Z_{t}\right| \leqslant C\left(1+\left|X_{t}\right|\right), \text { for all } t \leqslant T, \tag{1.3}
\end{equation*}
$$

see e.g. Theorem 3.6 in [38].
Now, replacing the generator $f$ with the Lipschitz generator $\tilde{f}_{M}$ we obtain a solution $\left(Y^{M}, Z^{M}\right)$ which is different from $(Y, Z)$. But it is possible to estimate the error between the two using the estimate on $Z$. The error is bounded by $\frac{C_{p}}{M^{p}}$ for every $p>1$, see [26, 38]. Once again, since the new generator $\tilde{f}_{M}$ is Lipschitz, we can easily apply classical numerical approximation schemes for Lipschitz BSDEs. Problems occur when one tries to obtain a rate of convergence for this technique. The classical (squared) error estimate for the discrete time approximation of Lipschitz BSDEs is $\frac{C}{n}$ with $n$ the number of time steps, but the constant $C$ depends strongly on the Lipschitz constant of $\tilde{f}_{M}$ with respect to $z$ and so it depends on $M$, see e.g. [41, 4]. In fact, one obtains an upper bound for the time discretization error (squared) of order $C e^{C M^{2}} n^{-1}$, the exponential term resulting from the use of Gronwall's inequality. Finally, an upper bound of the global error (squared) equals to

$$
\frac{C_{p}}{M^{p}}+\frac{C e^{C M^{2}}}{n}
$$

When $M$ increases, $n^{-1}$ will have to be small exponentially fast. The resulting rate of convergence turns out to be bad: setting $M=(\log n)^{1 / 2}$ the global error bound becomes $C_{p}(\log n)^{-p}$ which is not satisfactory.
To circumvent the above difficulties, one can impose a specific growth assumption on $\sigma$, leading to exponential moment control on $X$, in order to retrieve a better bound for the error between $(Y, Z)$ and $\left(Y^{M}, Z^{M}\right)$. In this case, the global error becomes
satisfactory, see Theorem 5.9 in [38]. Reasonable convergence rate can also be retrieved for unbounded locally Lipschitz terminal conditions, using estimates in the spirit of (1.3), but in the very restrictive case of constant $\sigma$, see Theorem 5.7 in [38]. Note that dealing with unbounded terminal condition is already a challenge for the theoretical study of (1.2).

In this paper, we focus on Lipschitz bounded terminal condition and unbounded Lipschitz $\sigma$. This allow to cover the case of models with great practical interest as geometric Brownian motion (Black-Scholes model). Using a similar truncation procedure as the one described above, we are able to obtain a bound on the time discretization error which does not depend on $M$. The global (squared) error bound is shown to be almost the classical one, that is to say $\frac{C_{\epsilon}}{n^{1-\epsilon}}$, for all $\epsilon>0$.
Let us conclude this review with the case of non-Lipschitz bounded terminal condition. In this case - even in the Lipschitz setting for the generator - new difficulties arise in the simulation of BSDEs, see e.g. [22]. In the quadratic case, when $\sigma$ is bounded, it is possible to use estimates of the form

$$
\left|Z_{t}\right| \leqslant \frac{C}{\sqrt{T-t}}, \quad \text { or } \quad\left|Z_{t}\right| \leqslant \frac{C}{(T-t)^{(1-\alpha) / 2}}
$$

if the terminal condition is $\alpha$-Hölder, see [14, 37]. Thanks to these estimates one can replace the generator $f$ by a Lipschitz generator such that the Lipschitz constant with respect to $z$ depends on time and blows up near the time $T$. The time discretization problem is addressed in [37] and the approximation of discretized BSDEs thanks to leastsquares regression is tackled in the paper [23]. In these two papers the time discretization grid is not uniform taking into account the estimates on $Z$. In particular, there are more points near the terminal time $T$ than near the initial time. We think that it would be very interesting to try to extend our results and techniques in the case of irregular terminal condition.

### 1.2 Main results of the paper

We now present in more depth our main results. As already mentioned, to tackle the problem of the numerical approximation of (1.2), we introduce a Lipschitz approximation of the driver $f: f_{N}(., .,)=.f\left(., ., \varphi_{N}().\right)$ and $\varphi_{N}$ is the projection on the centered Euclidean ball of radius $\rho N$ with $\rho>0$ chosen such that $f_{N}$ is $N$-Lipschitz with respect to $z$.
Given a grid $\pi=\left\{0=t_{0}<t_{1}<\ldots<t_{n}=T\right\}$ of the time interval [ $0, T$ ], we define $h_{i}=t_{i+1}-t_{i}$ the time step between times $t_{i}$ and $t_{i+1}$, and $h:=\max _{i} h_{i}$ assuming that
$h n \leqslant C$ and there exists $\theta \geqslant 1$ such that $h_{i} n^{\theta} \geqslant C>0$ for all $0 \leqslant i<n$. Here and in the sequel, $C$ is a positive constant, which may change from line to line but which does not depend on $n$. We denote it $C_{p}$ if it depends on an extra parameter $p$.

Definition 1.1. We denote $\left(Y_{i}^{\pi}, Z_{i}^{\pi}\right)_{0 \leqslant i \leqslant n}$ the solution of the BTZ1 -scheme satisfying (i) the terminal condition is $\left(Y_{n}^{\pi}, Z_{n}^{\pi}\right)=\left(g\left(X_{n}^{\pi}\right), 0\right)$,
(ii) for $i<n$, the transition from step $i+1$ to step $i$ is given by

$$
\left\{\begin{array}{l}
Y_{i}^{\pi}=\mathbb{E}_{t_{i}}\left[Y_{i+1}^{\pi}+h_{i} f_{N}\left(X_{i}^{\pi}, Y_{i}^{\pi}, Z_{i}^{\pi}\right)\right]  \tag{1.4}\\
Z_{i}^{\pi}=\mathbb{E}_{t_{i}}\left[Y_{i+1}^{\pi} H_{i}^{R}\right]
\end{array}\right.
$$

where $\mathbb{E}_{t}[\cdot]$ stands for $\mathbb{E}\left[\cdot \mid \mathcal{F}_{t}\right], 0 \leqslant t \leqslant T$.
The discrete-time process $\left(X_{i}^{\pi}\right)_{0 \leqslant i \leqslant n}$ is an approximation of $\left(X_{t}\right)_{t \in[0, T]}$ and we chose to work here with the Euler scheme:

The coefficients $\left(H_{i}^{R}\right)_{0 \leqslant i<n}$ are some $\mathbb{R}^{1 \times d}$ independent random vectors defined, given $R>0$, by

$$
\begin{equation*}
\left(H_{i}^{R}\right)^{\ell}=\frac{-R}{\sqrt{h_{i}}} \vee \frac{W_{t_{i+1}}^{\ell}-W_{t_{i}}^{\ell}}{h_{i}} \wedge \frac{R}{\sqrt{h_{i}}}, \quad 1 \leqslant \ell \leqslant d \tag{1.5}
\end{equation*}
$$

We observe that $\left(H_{i}^{R}\right)_{0 \leqslant i<n}$ satisfies

$$
\begin{equation*}
\mathbb{E}_{t_{i}}\left[H_{i}^{R}\right]=0, h_{i} \mathbb{E}_{t_{i}}\left[\left(H_{i}^{R}\right)^{\top} H_{i}^{R}\right]=h_{i} \mathbb{E}\left[\left(H_{i}^{R}\right)^{\top} H_{i}^{R}\right]=c_{i} I_{d \times d} \text { and } \frac{\lambda}{d} \leqslant c_{i} \leqslant \frac{\Lambda}{d}, \tag{1.6}
\end{equation*}
$$

where $\lambda, \Lambda$ are positive constants that do not depend on $R$, for $R$ big enough. Moreover, it is well known (see e.g. [31]) that, under the Lipschitz continuity assumption on $b$ and $\sigma$,

$$
\begin{equation*}
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|X_{i}^{\pi}\right|^{2 p}\right] \leqslant C_{p} \quad \text { and } \quad \max _{0 \leqslant i \leqslant n} \mathbb{E}\left[\sup _{t \in\left[t_{i}, t_{i+1}\right]}\left|X_{t}-X_{i}^{\pi}\right|^{2 p}\right] \leqslant C_{p} h^{p}, \quad p \geqslant 1 . \tag{1.7}
\end{equation*}
$$

Combining (1.6), (1.7) and the Lipschitz continuity property of $f_{N}$, an easy induction argument proves that $\left(Y^{\pi}, Z^{\pi}\right)$ are square integrable and thus conditional expectations involved at each step of the algorithm are well defined. Moreover, assuming $K h<1$ allows for the implicit definition of $Y_{i}^{\pi}, i<n$.

The first main result of the paper is the following theorem.

[^1]Theorem 1.1. Setting, for some $\alpha<1 / 2$,

$$
\begin{equation*}
N=n^{\alpha} \quad \text { and } \quad R=\log (n), \tag{1.8}
\end{equation*}
$$

we have, for all $\eta>0$,

$$
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}-Y_{i}^{\pi}\right|^{2}\right]+\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}-Z_{i}^{\pi}\right|^{2} d s\right] \leqslant C_{\alpha, \eta} h^{1-\eta} .
$$

The choice of $N$ and $R$ as specific functions of $n$ will be made clear in the following. The truncation procedure guarantees the stability of the scheme. Letting these constants grow with $n$ guarantees the convergence of the scheme. Obviously, a good balance between the two has to be found.
To obtain this Theorem, we first prove stability results for the scheme given in Definition 1.1. This is a priori not straightforward because the Lipschitz constants explode. In order to do this, we use a linearization argument leading to a comparison Theorem and rely on BMO martingales tools. We then study carefully the truncation error induced by the time-discretization. In particular, we have to revisit Zhang's path regularity result.

One has to observe that the above scheme is still a theoretical one since it assumes a perfect computation of the conditional expectations. In practice, these conditional expectations have to be estimated. Many methods can be used and Theorem 1.1 is a key step toward a complete convergence analysis.

In this paper, we chose to compute the conditional expectation using a Markovian quantization procedure which is now quite well known. We refer to [24, 35] for general results about quantization and [2] for application to American options pricing and to [15] for application to coupled forward-backward SDEs. We present in section 4 a fully implementable numerical scheme and prove the following upper bound for the convergence error:

$$
\left|Y_{0}-\hat{Y}_{0}^{\pi}\right| \leqslant C_{\eta} h^{\frac{1}{2}-\eta}, \quad \text { for all } \eta>0,
$$

with $\left(\hat{Y}^{\pi}, \hat{Z}^{\pi}\right)$ the solution of the scheme (1.1) where conditional expectations are replaced by implementable approximations. See Corollary 4.1 for a suitable choice of parameters.

The rest of this paper is organised as follows. In Section 2 we introduce the linearization tool for discrete schemes and we obtain some very useful estimates on $\left(Y^{\pi}, Z^{\pi}\right)$ together with some stability results. Section 3 is devoted to the convergence analysis of the time discretization for quadratic BSDEs. In the last section we give a fully implementable scheme, we study its convergence error and we provide some numerical illustrations.

## 2 Preliminary results

First of all, let us recall that under the assumptions on the generator $f$ and the terminal condition $g$ given in the previous section, existence and uniqueness result holds for (1.1)-(1.2). Moreover, the solution is known to have the following properties, see e.g. $[32,5,1]$.

Proposition 2.1. The FBSDE (1.1)-(1.2) has a unique solution $(X, Y, Z) \in \mathcal{S}^{2} \times$ $\mathcal{S}^{\infty} \times \mathcal{M}^{2}$. Moreover, the martingale $\left(\int_{0}^{t} Z_{s} d W_{s}\right)_{t \in[0, T]}$ belongs to the space of BMO martingales. The $\mathcal{S}^{\infty}$ norm of $Y$ and the BMO norm of $\left(\int_{0}^{t} Z_{s} d W_{s}\right)_{t \in[0, T]}$ are bounded by a constant that depends only on $T,|g|_{\infty}$, and the constant that appears in the growth assumption on the generator $f$.

BMO martingales theory plays a key role for a priori estimates needed in our study. For details about the theory we refer the reader to [30]. We now recall the definition of a BMO martingale and introduce some notations. Let $\left(M_{t}\right)_{0 \leqslant t \leqslant T}$ be a martingale for the filtration $\left(\mathcal{G}_{t}\right)_{0 \leqslant t \leqslant T}$. We say that $M$ is a BMO martingale if it is a square integrable martingale such that

$$
\|M\|_{B M O(\mathcal{G})}^{2}:=\sup _{\tau} \mathbb{E}\left[\left|M_{T}-M_{\tau^{-}}\right|^{2} \mid \mathcal{G}_{\tau}\right]<+\infty
$$

where the supremum is taken over all stopping times $\tau \in[0, T]$.

### 2.1 Lipschitz approximation

We first recall a key result concerning the Lipschitz approximation of quadratic BSDEs. We introduce $\left(Y_{t}^{N}, Z_{t}^{N}\right)_{t \in[0, T]}$ the solution of the following BSDE

$$
\begin{equation*}
Y_{t}^{N}=g\left(X_{T}\right)+\int_{t}^{T} f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right) d s-\int_{t}^{T} Z_{s}^{N} d W_{s} \tag{2.1}
\end{equation*}
$$

recalling that $f_{N}(., .,)=.f\left(., ., \varphi_{N}().\right)$ and $\varphi_{N}$ is the projection on the centered Euclidean ball of radius $\rho N$ with $\rho>0$ chosen such that $f_{N}$ is $N$-Lipschitz with respect to $z$.
Remark 2.1. The results of Proposition 2.1 hold true for processes $\left(X, Y^{N}, Z^{N}\right)$. Importantly the $\mathcal{S}^{\infty}$ norm of $Y^{N}$ and the BMO norm of $\left(\int_{0}^{t} Z_{s}^{N} d W_{s}\right)_{t \in[0, T]}$ are bounded by a constant that does not depend on $N$.
Theorem 2.2. For all $q>0$ and $p \geqslant 1$, there exists a constant $C_{q, p}>0$ such that

$$
\mathbb{E}\left[\sup _{0 \leqslant t \leqslant T}\left|Y_{t}-Y_{t}^{N}\right|^{2 p}\right]+\mathbb{E}\left[\left(\int_{0}^{T}\left|Z_{s}-Z_{s}^{N}\right|^{2} d s\right)^{p}\right] \leqslant \frac{C_{q, p}}{N^{q}} .
$$

The proof of this theorem is given by Theorem 6.2 in [26] (see also Remark 5.5 in [38]).
Remark 2.2. The control of the above error in terms of any power of $N^{-1}$ legitimates the choice to set $N:=n^{\alpha}$ for some $\alpha>0$.

The above result is strongly linked with the following estimate on $Z$, and on $Z^{N}$, proved e.g., in [38], recalled here for later use.

Proposition 2.3. Under our standing assumptions, for all $t \in[0, T]$ and all $N>0$,

$$
\left|Z_{t}^{N}\right|+\left|Z_{t}\right| \leqslant C\left(1+\left|X_{t}\right|\right) .
$$

Importantly, $C$ does not depend on $N$.
We conclude this section by two technical Lemmas.
Lemma 2.1. Setting, for all $i<n$,

$$
\begin{equation*}
\bar{Z}_{i}^{N}:=\frac{1}{h_{i}} \mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} Z_{s}^{N} d s\right], \tag{2.2}
\end{equation*}
$$

then

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\bar{Z}_{j}^{N}\right|^{2}\right] \leqslant C \quad \text { and } \quad\left|\bar{Z}_{i}^{N}\right| \leqslant C\left(1+\mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|\right]\right) .
$$

Proof. 1. For the first claim, we observe that, for $i \leqslant j<n$,

$$
\mathbb{E}_{t_{i}}\left[\left|\bar{Z}_{j}^{N}\right|^{2}\right] \leqslant \frac{1}{h_{j}} \mathbb{E}_{t_{i}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}\right|^{2} \mathrm{~d} s\right] .
$$

Summing over $j$ the previous inequality and using Remark 2.1, we obtain

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\bar{Z}_{j}^{N}\right|^{2}\right] \leqslant \mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{T}\left|Z_{s}^{N}\right|^{2} d s\right] \leqslant\left\|\int_{0} Z_{s}^{N} d W_{s}\right\|_{B M O(\mathcal{F})} \leqslant C .
$$

2. For the second claim, we compute

$$
\left|\bar{Z}_{i}^{N}\right|=\frac{1}{h_{i}}\left|\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} Z_{s}^{N} d s\right]\right| \leqslant \mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|Z_{s}^{N}\right|\right] \leqslant C\left(1+\mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|\right]\right)
$$

where we used Proposition 2.3.

Lemma 2.2. We assume that $\alpha \leqslant 1 / 2$. Setting, for all $i<n$,

$$
\begin{equation*}
\tilde{Z}_{i}^{N}:=\mathbb{E}_{t_{i}}\left[Y_{t_{i+1}}^{N} \frac{\left(W_{t_{i+1}}-W_{t_{i}}\right)^{\top}}{h_{i}}\right] \tag{2.3}
\end{equation*}
$$

then

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\tilde{Z}_{j}^{N}\right|^{2}\right] \leqslant C \quad \text { and } \quad\left|\tilde{Z}_{i}^{N}\right| \leqslant C\left(1+\mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|^{4}\right]^{1 / 2}\right)
$$

Proof. 1. For the first claim, we observe that

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\tilde{Z}_{j}^{N}\right|^{2}\right] \leqslant 2 \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\bar{Z}_{j}^{N}\right|^{2}\right]+2 \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\bar{Z}_{j}^{N}-\tilde{Z}_{j}^{N}\right|^{2}\right] .
$$

The first term was already treated in Lemma 2.1. For the second term we compute, thanks to assumptions on $f_{N}$, Remark 2.1 and Cauchy-Schwarz inequality, for $i \leqslant j<n$,

$$
\begin{aligned}
h_{j} \mathbb{E}_{t_{i}}\left[\left|\bar{Z}_{j}^{N}-\tilde{Z}_{j}^{N}\right|^{2}\right] & =h_{j} \mathbb{E}_{t_{i}}\left[\left|\mathbb{E}_{t_{j}}\left[\int_{t_{j}}^{t_{j+1}} f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right) d s \frac{W_{t_{j+1}}-W_{t_{j}}}{h_{j}}\right]\right|^{2}\right] \\
& \leqslant h_{j} \mathbb{E}_{t_{i}}\left[\int_{t_{j}}^{t_{j+1}}\left|f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right)\right|^{2} d s\right] \\
& \leqslant C\left(h^{2}+\left(1+N^{2} h\right) \mathbb{E}_{t_{i}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}\right|^{2} d s\right]\right)
\end{aligned}
$$

Summing over $j$, we obtain

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1} h_{j}\left|\bar{Z}_{j}^{N}-\tilde{Z}_{j}^{N}\right|^{2}\right] \leqslant C\left(1+\left\|\int_{0} Z_{s}^{N} d W_{s}\right\|_{B M O(\mathcal{F})}^{2}\right) \leqslant C .
$$

2. For the second claim, once again we have

$$
\left|\tilde{Z}_{i}^{N}\right|^{2} \leqslant\left|\bar{Z}_{i}^{N}\right|+\left|\bar{Z}_{i}^{N}-\tilde{Z}_{i}^{N}\right| .
$$

The first term is treated thanks to Lemma 2.1 and Cauchy-Schwarz inequality. For the second term we compute, thanks to assumptions on $f_{N}$, Remark 2.1, Proposition 2.3 and Cauchy-Schwarz inequality,

$$
\begin{align*}
\left|\bar{Z}_{i}^{N}-\tilde{Z}_{i}^{N}\right| & \leqslant C \mathbb{E}_{t_{i}}\left[\left(1+\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|^{2}\right)\left(W_{t_{i+1}}-W_{t_{i}}\right)\right] \\
& \leqslant C h^{1 / 2}\left(1+\mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|^{4}\right]^{1 / 2}\right) . \tag{2.4}
\end{align*}
$$

### 2.2 Linearization of the BTZ scheme

Definition 2.1. We consider the solution $\left(Y_{i}, Z_{i}\right)_{0 \leqslant i \leqslant n}$ of the following BTZ scheme:
(i) the terminal condition is given by $Y_{n}=\xi$ for some $\xi \in L^{2}\left(\mathcal{F}_{T}\right)$ and $Z_{n}=0$;
(ii) for $0 \leqslant i<n$, the transition from step $i+1$ to step $i$ is given by

$$
\left\{\begin{array}{l}
Y_{i}=\mathbb{E}_{t_{i}}\left[Y_{i+1}+h_{i} F_{i}\left(Y_{i}, Z_{i}\right)\right] \\
Z_{i}=\mathbb{E}_{t_{i}}\left[Y_{i+1} H_{i}\right]
\end{array}\right.
$$

with $\left(H_{i}\right)_{0 \leqslant i<n}$ some $\mathbb{R}^{1 \times d}$ independent random vectors such that, for all $0 \leqslant i<n$, $H_{i}$ is $\mathcal{F}_{t_{i+1}}$ measurable, $\mathbb{E}_{t_{i}}\left[H_{i}\right]=0$,

$$
\begin{equation*}
c_{i} I_{d \times d}=h_{i} \mathbb{E}\left[H_{i}^{\top} H_{i}\right]=h_{i} \mathbb{E}_{t_{i}}\left[H_{i}^{\top} H_{i}\right] \tag{2.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\lambda}{d} \leqslant c_{i} \leqslant \frac{\Lambda}{d} \tag{2.6}
\end{equation*}
$$

where $\lambda, \Lambda$ are positive constants. Let us remark that (2.5) and (2.6) imply that

$$
\begin{equation*}
\lambda \leqslant h_{i} \mathbb{E}\left[\left|H_{i}\right|^{2}\right]=h_{i} \mathbb{E}_{t_{i}}\left[\left|H_{i}\right|^{2}\right] \leqslant \Lambda \tag{2.7}
\end{equation*}
$$

For the reader's convenience, we denote the above scheme by $\mathcal{E}\left[\left(F_{i}\right), \xi\right]$.
In the sequel, we use the following assumption on the coefficients of the scheme given in Definition 2.1.

## Assumption (H1)

(i) Functions $F_{i}: \Omega \times \mathbb{R} \times \mathbb{R}^{1 \times d} \rightarrow \mathbb{R}$ are $\mathcal{F}_{t_{i}} \otimes \mathcal{B}(\mathbb{R}) \otimes \mathcal{B}\left(\mathbb{R}^{d}\right)$-measurable. They satisfy for some positive constants $K_{y}$ and $K_{z}^{n}$ which do not depend on $i$ but $K_{z}^{n}$ may depend on $n$,

$$
\begin{aligned}
& \circ F_{i}(0,0) \in L^{2}\left(\mathcal{F}_{t_{i}}\right) \\
& \circ\left|F_{i}(y, z)-F_{i}\left(y^{\prime}, z^{\prime}\right)\right| \leqslant K_{y}\left|y-y^{\prime}\right|+K_{z}^{n}\left|z-z^{\prime}\right|
\end{aligned}
$$

(ii) For a given $\varepsilon \in] 0,1$ [ which does not depend on $n$, we have that

$$
h K_{y}<1-\varepsilon
$$

(iii) The following holds

$$
\left(\sup _{0 \leqslant i \leqslant n-1} h_{i}\left|H_{i}\right|\right) K_{z}^{n}<1
$$

Observe that (H1)(ii) guarantees the well-posedness of the scheme.
We now give a representation result for the difference of two BTZ scheme solutions. Let $\left(Y_{i}^{1}, Z_{i}^{1}\right)_{0 \leqslant i \leqslant n}$ be the solution of $\mathcal{E}\left[\left(F_{i}^{1}\right), \xi^{1}\right]$ and $\left(Y_{i}^{2}, Z_{i}^{2}\right)_{0 \leqslant i \leqslant n}$ be the solution of $\mathcal{E}\left[\left(F_{i}^{2}\right), \xi^{2}\right]$.
We denote $\delta Y_{i}=Y_{i}^{1}-Y_{i}^{2}, \delta Z_{i}=Z_{i}^{1}-Z_{i}^{2}$ and $\delta F_{i}=F_{i}^{1}\left(Y_{i}^{2}, Z_{i}^{2}\right)-F_{i}^{2}\left(Y_{i}^{2}, Z_{i}^{2}\right)$. Then, we have the following representation result.

Proposition 2.4 (Euler scheme linearization). Assume that $F^{1}$ satisfy (H1)(i)-(ii). Setting, for $0 \leqslant i \leqslant n$,

$$
E_{i}^{\pi}=\prod_{j=i}^{n-1}\left(1+h_{j} H_{j} \gamma_{j}\right) \text { and } B_{i}^{\pi}=\prod_{j=i}^{n-1}\left(1-h_{j} \beta_{j}\right)
$$

with

$$
\beta_{j}=\frac{F_{j}^{1}\left(Y_{j}^{1}, Z_{j}^{1}\right)-F_{j}^{1}\left(Y_{j}^{2}, Z_{j}^{1}\right)}{Y_{j}^{1}-Y_{j}^{2}} \mathbf{1}_{\left\{Y_{j}^{1}-Y_{j}^{2} \neq 0\right\}}
$$

and

$$
\gamma_{j}=\frac{F_{j}^{1}\left(Y_{j}^{2}, Z_{j}^{1}\right)-F_{j}^{1}\left(Y_{j}^{2}, Z_{j}^{2}\right)}{\left|Z_{j}^{1}-Z_{j}^{2}\right|^{2}}\left(Z_{j}^{1}-Z_{j}^{2}\right)^{\top} \mathbf{1}_{\left\{Z_{j}^{1}-Z_{j}^{2} \neq 0\right\}}
$$

then the following holds,

$$
\begin{equation*}
\delta Y_{i}=\mathbb{E}_{t_{i}}\left[E_{i}^{\pi}\left(B_{i}^{\pi}\right)^{-1}\left(\delta Y_{n}+\sum_{k=i}^{n-1} h_{k} B_{k+1}^{\pi} \delta F_{k}\right)\right] \tag{2.8}
\end{equation*}
$$

We used the convention $\prod_{j=n}^{n-1} \cdot=1$.

Proof of Proposition 2.4. For $0 \leqslant i \leqslant n$, we compute that

$$
\begin{equation*}
\delta Y_{i}=\mathbb{E}_{t_{i}}\left[\delta Y_{i+1}+h_{i} \beta_{i} \delta Y_{i}+h_{i} \delta Z_{i} \gamma_{i}+h_{i} \delta F_{i}\right] \tag{2.9}
\end{equation*}
$$

Observing that $\delta Z_{i}=\mathbb{E}_{t_{i}}\left[H_{i} \delta Y_{i+1}\right]$, we obtain

$$
\begin{aligned}
\delta Y_{i} & =\frac{1}{1-h_{i} \beta_{i}} \mathbb{E}_{t_{i}}\left[\left(1+h_{i} H_{i} \gamma_{i}\right) \delta Y_{i+1}+h_{i} \delta F_{i}\right] \\
& =\frac{1}{1-h_{i} \beta_{i}} \mathbb{E}_{t_{i}}\left[\left(1+h_{i} H_{i} \gamma_{i}\right)\left(\delta Y_{i+1}+h_{i} \delta F_{i}\right)\right]
\end{aligned}
$$

Under (H1)(ii), we observe that $1-h_{i} \beta_{i} \neq 0$ and the previous equality is well defined. Using an easy induction argument we obtain

$$
\delta Y_{i}=\mathbb{E}_{t_{i}}\left[E_{i}^{\pi}\left(B_{i}^{\pi}\right)^{-1}\left(\delta Y_{n}+\sum_{k=i}^{n-1} h_{k}\left(E_{k+1}^{\pi}\right)^{-1} B_{k+1}^{\pi} \delta F_{k}\right)\right]
$$

The proof is concluded using the tower property of conditional expectation and the fact that $\mathbb{E}_{t_{k+1}}\left[E_{k+1}^{\pi}\right]=1$.
The previous representation leads to the following comparison result for the BTZ scheme.
Corollary 2.5 (Comparison theorem). Assume that $F^{1}$ satisfies (H1). If

$$
Y_{n}^{1} \geqslant Y_{n}^{2} \quad \text { and } \quad F_{i}^{1}\left(Y_{i}^{2}, Z_{i}^{2}\right) \geqslant F_{i}^{2}\left(Y_{i}^{2}, Z_{i}^{2}\right), \quad 0 \leqslant i \leqslant n-1,
$$

then we have that

$$
Y_{i}^{1} \geqslant Y_{i}^{2}, \quad 0 \leqslant i \leqslant n .
$$

Proof of Corollary 2.5. We will use the BTZ scheme linearization given in Proposition 2.4. Since $\left|\beta_{i}\right| \leqslant K_{y}$ and $\left|\gamma_{i}\right| \leqslant K_{z}^{n}$, the condition $\left(\sup _{0 \leqslant i \leqslant n} h_{i}\left|H_{i}\right|\right) K_{z}^{n}<1$ combined with $h K_{y}<1$, implies that the coefficients $E_{i}^{\pi}, B_{i}^{\pi}$ are positive, for $i<n$. Moreover, we assume that

$$
Y_{n}^{1} \geqslant Y_{n}^{2} \quad \text { and } \quad F_{i}^{1}\left(Y_{i}^{2}, Z_{i}^{2}\right) \geqslant F_{i}^{2}\left(Y_{i}^{2}, Z_{i}^{2}\right), \quad 0 \leqslant i \leqslant n-1,
$$

so we have

$$
\delta Y_{n} \geqslant 0 \quad \text { and } \quad \delta F_{i} \geqslant 0, \quad 0 \leqslant i \leqslant n-1 .
$$

Thus, (2.8) gives us for all $0 \leqslant i \leqslant n$

$$
\delta Y_{i}=\mathbb{E}_{t_{i}}\left[E_{i}^{\pi}\left(B_{i}^{\pi}\right)^{-1}\left(\delta Y_{n}+\sum_{k=i}^{n-1} h_{k} B_{k+1}^{\pi} \delta F_{k}\right)\right] \geqslant 0 .
$$

Remark 2.3. (i) As for the classical comparison theorem, the previous result stays true if we replace the condition

$$
F^{1} \text { satisfies }(\mathbf{H} 1) \text { and } F_{i}^{1}\left(Y_{i}^{2}, Z_{i}^{2}\right) \geqslant F_{i}^{2}\left(Y_{i}^{2}, Z_{i}^{2}\right), \quad 0 \leqslant i \leqslant n-1,
$$

with

$$
F^{2} \text { satisfies (H1) and } F_{i}^{1}\left(Y_{i}^{1}, Z_{i}^{1}\right) \geqslant F_{i}^{2}\left(Y_{i}^{1}, Z_{i}^{1}\right), \quad 0 \leqslant i \leqslant n-1 .
$$

(ii) The comparison result for $\mathrm{BS} \Delta \mathrm{Es}$ is already proved in [12] but without using the scheme linearization.
(iii) The truncation of the generator is essential to make the comparison theorem hold: Example 4.1 in the paper [11] shows that comparison fails for quadratic $\mathrm{BS} \Delta \mathrm{Es}$ with bounded terminal condition.

### 2.3 A priori estimates (in the quadratic case)

In this part we establish some a priori estimates for the solution of the BTZ scheme given by Definition 2.1 with quadratic generator. More precisely we show that classical a priori estimates for quadratic BSDEs stay true for the corresponding BTZ scheme under suitable conditions. We consider schemes with essentially bounded terminal condition $\xi$ and coefficients $F$ satisfying more restrictive assumptions.

## Assumption (H2)

(i) $\xi \in L^{\infty}\left(\mathcal{F}_{T}\right)$ and $\left(F_{i}\right)_{0 \leqslant i \leqslant n-1}$ satisfy (H1),
(ii) $F_{i}(0,0) \in L^{\infty}\left(\mathcal{F}_{t_{i}}\right)$ for all $0 \leqslant i \leqslant n-1$ and there exists a constant $\tilde{C}$ that does not depend on $n$ and such that

$$
\sup _{0 \leqslant i \leqslant n}\left|F_{i}(0,0)\right| \leqslant \tilde{C},
$$

(iii) there exist three positive constants $K_{y}, \tilde{L}$ and $\tilde{\Lambda}$ that do not depend on $n$ and such that

$$
\begin{equation*}
\left|F_{i}(y, z)\right| \leqslant K_{y}|y|+\tilde{L}|z|^{2}+\varsigma_{i} \quad \text { with } \mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n} h_{k}\left|\varsigma_{k}\right|\right] \leq \tilde{\Lambda} . \tag{2.10}
\end{equation*}
$$

The first key estimate is related to the uniform boundedness in $n$ of $\left(Y_{i}\right)_{0 \leqslant i \leqslant n}$.
Proposition 2.6. Assume (H2)(i)-(ii) holds true. Then,

$$
\left|Y_{i}\right| \leqslant\left(|\xi|_{\infty}+T \sup _{0 \leqslant i \leqslant n-1}\left|F_{i}(0,0)\right|_{\infty}\right) e^{C K_{y} / \varepsilon} \leqslant\left(|\xi|_{\infty}+T \tilde{C}\right) e^{C K_{y} / \varepsilon}
$$

Proof of Proposition 2.6. We introduce $\left(Y_{i}^{2}, Z_{i}^{2}\right)_{0 \leqslant i \leqslant n}$ the solution of the BTZ scheme $\mathcal{E}\left[\left(F_{i}^{2}\right),|\xi|_{\infty}\right]$ with $F_{i}^{2}(y, z)=\left|F_{i}(0,0)\right|_{\infty}+K_{y}|y|$. We observe that the terminal condition and the generator of this scheme are deterministic functions which implies that $Z_{i}^{2}=0$ for all $0 \leqslant i \leqslant n$. We are able to compare $F_{i}$ and $F_{i}^{2}$ under (H2)(i)-(ii):

$$
F_{i}\left(Y_{i}^{2}, Z_{i}^{2}\right)=F_{i}\left(Y_{i}^{2}, 0\right) \leqslant\left|F_{i}(0,0)\right|_{\infty}+K_{y}\left|Y_{i}^{2}\right|=F_{i}^{2}\left(Y_{i}^{2}, Z_{i}^{2}\right) .
$$

Since $\xi \leqslant|\xi|_{\infty}$ we can apply the comparison theorem given in Corollary 2.5:

$$
\begin{aligned}
Y_{i} & \leqslant Y_{i}^{2}=\frac{|\xi|_{\infty}}{\prod_{k=i}^{n-1}\left(1-h_{k} K_{y}\right)}+\sum_{j=i}^{n-1} \frac{h_{j}\left|F_{j}(0,0)\right|_{\infty}}{\prod_{k=i}^{j}\left(1-h_{k} K_{y}\right)} \\
& \leqslant|\xi|_{\infty}\left(1+\frac{h K_{y}}{\varepsilon}\right)^{n-i}+\sum_{j=i}^{n-1} h_{j}\left|F_{j}(0,0)\right|_{\infty}\left(1+\frac{h K_{y}}{\varepsilon}\right)^{j-i+1} \\
& \leqslant\left(|\xi|_{\infty}+T \sup _{0 \leqslant j \leqslant n-1}\left|F_{j}(0,0)\right|_{\infty}\right) e^{C K_{y} / \varepsilon} .
\end{aligned}
$$

Using similar arguments, we obtain that

$$
Y_{i} \geqslant\left(-|\xi|_{\infty}-T \sup _{0 \leqslant j \leqslant n-1}\left|F_{j}(0,0)\right|_{\infty}\right) e^{C K_{y} / \varepsilon}
$$

which concludes the proof.
The second estimate is related to $\left(Z_{i}\right)_{0 \leqslant i \leqslant n}$.
Proposition 2.7. Under (H2), we have that

$$
\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n-1} h_{k}\left|Z_{k}\right|^{2}\right] \leqslant C, \quad 0 \leqslant i \leqslant n-1 .
$$

Proof. Since (H2) holds, we can apply Proposition 2.6 and get

$$
\sup _{0 \leqslant i \leqslant n}\left|Y_{i}\right| \leqslant\left(|\xi|_{\infty}+T \tilde{C}\right) e^{C K_{y} / \varepsilon}:=m .
$$

We split the proof in two steps, depending on the value of $m$.

1. In this first step, we assume that

$$
\begin{equation*}
2 m \tilde{L} \leqslant \frac{d}{2 \Lambda} . \tag{2.11}
\end{equation*}
$$

We observe that the BTZ scheme can be rewritten

$$
Y_{i}=Y_{i+1}+h_{i} F_{i}\left(Y_{i}, Z_{i}\right)-h_{i} c_{i}^{-1} Z_{i} H_{i}^{\top}-\Delta M_{i},
$$

where $c_{i}$ is given by (2.5) and $\Delta M_{i}$ is an $\mathcal{F}_{t_{i+1}}$ random variable satisfying $\mathbb{E}_{t_{i}}\left[\Delta M_{i}\right]=0$, $\mathbb{E}_{t_{i}}\left[\left|\Delta M_{i}\right|^{2}\right]<\infty$ and $\mathbb{E}_{t_{i}}\left[\Delta M_{i} H_{i}\right]=0$. Using the identity $|y|^{2}=|x|^{2}+2 x(y-x)+\mid y-$ $\left.x\right|^{2}$, we obtain, setting $x=Y_{i}$ and $y=Y_{i+1}$,

$$
\begin{aligned}
\left|Y_{i+1}\right|^{2}= & \left|Y_{i}\right|^{2}+2 Y_{i}\left(-h_{i} F_{i}\left(Y_{i}, Z_{i}\right)+h_{i} c_{i}^{-1} Z_{i} H_{i}^{\top}+\Delta M_{i}\right) \\
& +\left|-h_{i} F_{i}\left(Y_{i}, Z_{i}\right)+h_{i} c_{i}^{-1} Z_{i} H_{i}^{\top}+\Delta M_{i}\right|^{2} .
\end{aligned}
$$

Taking the conditional expectation w.r.t. $\mathcal{F}_{t_{i}}$ in the previous equality, we obtain using (H2)(iii) and (2.5),

$$
\begin{aligned}
\mathbb{E}_{t_{i}}\left[\left|Y_{i+1}\right|^{2}\right] & \geqslant\left|Y_{i}\right|^{2}-2 Y_{i} h_{i} F_{i}\left(Y_{i}, Z_{i}\right)+\mathbb{E}_{t_{i}}\left[\left|h_{i} c_{i}^{-1} Z_{i} H_{i}^{\top}\right|^{2}\right] \\
& \geqslant\left|Y_{i}\right|^{2}-2 m h_{i}\left(K_{y} m+\tilde{L}\left|Z_{i}\right|^{2}+\left|s_{i}\right|\right)+h_{i}\left(c_{i}\right)^{-2} Z_{i} h_{i} \mathbb{E}_{t_{i}}\left[H_{i}^{\top} H_{i}\right] Z_{i}^{\top} \\
& \geqslant\left|Y_{i}\right|^{2}-2 m h_{i}\left(K_{y} m+\tilde{L}\left|Z_{i}\right|^{2}+\left|s_{i}\right|\right)+h_{i}\left(c_{i}\right)^{-1}\left|Z_{i}\right|^{2} \\
& \geqslant\left|Y_{i}\right|^{2}-2 m^{2} K_{y} h_{i}+\left(\frac{d}{\Lambda}-2 m \tilde{L}\right) h_{i}\left|Z_{i}\right|^{2}-2 m h_{i}\left|s_{i}\right| .
\end{aligned}
$$

Finally, an easy induction over $i$ allows to obtain

$$
\begin{aligned}
\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n-1} h_{k}\left|Z_{k}\right|^{2}\right] & \leqslant \frac{1}{d / \Lambda-2 m \tilde{L}}\left(\mathbb{E}_{t_{i}}\left[\left|Y_{n}\right|^{2}\right]-\left|Y_{i}\right|^{2}+2 m^{2} K_{y} T+2 m \tilde{\Lambda}\right) \\
& \leqslant \frac{2 m^{2}+2 m^{2} K_{y} T+2 m \tilde{\Lambda}}{d / \Lambda-2 m \tilde{L}}
\end{aligned}
$$

Since the previous bound does not depend on $n$, the result is proved in this special case. 2.a. To prove the result in the general case, we use similar arguments as in [40]: we cut $\xi$ and $\left(F_{i}(0,0)\right)$ in pieces small enough such that we are able to use step 1 . Let us set an integer $\kappa \in \mathbb{N}^{*}$ that does not depend on $n$ and such that

$$
\begin{equation*}
\frac{4 m \tilde{L}}{\kappa} \leqslant \frac{d}{2 \Lambda} \tag{2.12}
\end{equation*}
$$

For each $a \in\{1, \ldots, \kappa\}$, we denote $\left(Y_{i}^{a}, Z_{i}^{a}\right)_{0 \leqslant i \leqslant n}$ the solution of $\mathcal{E}\left[\left(\Phi_{i}^{a}\right), \xi^{a}\right]$ with $\xi^{a}=\frac{\xi}{\kappa}$ and

$$
\Phi_{i}^{a}(y, z)=F_{i}\left(y+\sum_{q=1}^{a-1} Y_{i}^{q}, z+\sum_{q=1}^{a-1} Z_{i}^{q}\right)-F_{i}\left(\sum_{q=1}^{a-1} Y_{i}^{q}, \sum_{q=1}^{a-1} Z_{i}^{q}\right)+\frac{F_{i}(0,0)}{\kappa} .
$$

We observe that

$$
\begin{equation*}
Y_{i}=\sum_{a=1}^{\kappa} Y_{i}^{a} \quad \text { and } \quad Z_{i}=\sum_{a=1}^{\kappa} Z_{i}^{a} \tag{2.13}
\end{equation*}
$$

Since (H2)(i)-(ii) holds true for ( $\Phi_{i}^{a}$ ) and $\xi^{a}$, we can apply Proposition 2.6 and remark that

$$
\begin{align*}
\sup _{0 \leqslant i \leqslant n}\left|Y_{i}^{a}\right| & \leqslant\left(\left|\xi^{a}\right|_{\infty}+\sup _{0 \leqslant i \leqslant n-1}\left|\Phi_{i}^{a}(0,0)\right|_{\infty} T\right) e^{C K_{y} / \varepsilon} \\
& \leqslant\left(\frac{|\xi|_{\infty}}{\kappa}+\frac{\sup _{0 \leqslant i \leqslant n-1}\left|F_{i}(0,0)\right|_{\infty}}{\kappa} T\right) e^{C K_{y} / \varepsilon} \\
& \leqslant \frac{m}{\kappa} \tag{2.14}
\end{align*}
$$

2.b. In this last step, we use an induction argument to show

$$
\begin{equation*}
\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n-1} h_{k}\left|Z_{k}^{a}\right|^{2}\right] \leqslant C, \quad 0 \leqslant i<n, \tag{2.15}
\end{equation*}
$$

for all $a \in\{1, \ldots, \kappa\}$. Combined with (2.13), this proves the proposition in the general case. We have proved in the first step that (2.15) is true for $a=1$. Now let us assume that it is true up to $a<\kappa$. Then we compute that

$$
\begin{aligned}
\left|\Phi_{i}^{a+1}(y, z)\right| & \leqslant\left|F_{i}\left(y+\sum_{q=1}^{a} Y_{i}^{q}, z+\sum_{q=1}^{a} Z_{i}^{q}\right)\right|+\left|F_{i}\left(\sum_{q=1}^{a} Y_{i}^{q}, \sum_{q=1}^{a} Z_{i}^{q}\right)\right|+\frac{\left|F_{i}(0,0)\right|}{\kappa} \\
& \leqslant K_{y}|y|+2 \tilde{L}|z|^{2}+\varsigma_{i}^{a}
\end{aligned}
$$

where $\varsigma_{i}^{a}=2 K_{y}\left|\sum_{q=1}^{a} Y_{i}^{q}\right|+3 \tilde{L}\left|\sum_{q=1}^{a} Z_{i}^{q}\right|^{2}+2\left|\zeta_{i}\right|+\left|F_{i}(0,0)\right|_{\infty} / \kappa$. Assumption (H2)(iii), bound (2.14) and the induction assumption yield that $\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n} h_{k}\left|\varsigma_{k}^{a}\right|\right] \leqslant C$ for all $0 \leqslant$ $i<n$. Then, we have that $\Phi^{a+1}$ satisfies assumption (H2) with $2 \tilde{L}$ instead of $\tilde{L}$ and $\varsigma^{a}$ instead of $\varsigma$. Since we have assumed that (2.12) holds true, then we can apply step 1 . to obtain

$$
\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n-1} h_{k}\left|Z_{k}^{a+1}\right|^{2}\right] \leqslant C, \quad 0 \leqslant i<n,
$$

which concludes the proof.
We conclude this section by applying previous results to the scheme given in Definition 1.1.

Corollary 2.8. Under assumptions of Theorem 1.1 the following holds true, for $n$ large enough,

$$
\sup _{0 \leqslant i \leqslant n}\left(\left|Y_{i}^{\pi}\right|+\mathbb{E}_{t_{i}}\left[\sum_{k=i}^{n-1}\left|Z_{i}^{\pi}\right|^{2} h_{i}\right]\right) \leqslant C .
$$

Proof. We simply observe that with our special choice of parameters $R$ and $N$, we have for $n$ large enough

$$
\left(\sup _{0 \leqslant i \leqslant n-1} h_{i}\left|H_{i}^{R}\right|\right) n^{\alpha} \leqslant \sqrt{h} \sqrt{d} R n^{\alpha} \leqslant \frac{C \sqrt{d} \log n}{n^{1 / 2-\alpha}} \leqslant 1,
$$

and that the generator of the scheme given in Definition 1.1 satisfies (H2) (with $K_{z}^{n}=$ $N:=n^{\alpha}$ ). The result follows then from a direct application of Proposition 2.6 and Proposition 2.7.

Remark 2.4. In a slightly different framework, Gobet and Turkedjiev have already obtained the Corollary 2.8 in [23] by direct calculations without using the linearization technique.

### 2.4 Scheme stability

In this part we will establish some bounds on the difference between two schemes. Firstly, we introduce a perturbed version of the scheme given in Definition 2.1.

Definition 2.2. (i) The terminal condition is given by $\tilde{Y}_{n}=\tilde{\xi}$ for some $\tilde{\xi} \in L^{\infty}\left(\mathcal{F}_{T}\right)$ and $\tilde{Z}_{n}=0$;
(ii) for $0 \leqslant i<n$

$$
\left\{\begin{array}{l}
\tilde{Y}_{i}=\mathbb{E}_{t_{i}}\left[\tilde{Y}_{i+1}+h_{i} F_{i}\left(\tilde{Y}_{i}, \tilde{Z}_{i}\right)\right]+\zeta_{i}^{Y} \\
\tilde{Z}_{i}=\mathbb{E}_{t_{i}}\left[\tilde{Y}_{i+1} H_{i}\right] .
\end{array}\right.
$$

Perturbations $\zeta_{i}^{Y}$ are $\mathcal{F}_{t_{i}}$-measurable and square integrable random variables. Moreover, we assume that

$$
\begin{equation*}
\sup _{0 \leqslant i<n} \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|\tilde{Z}_{j}\right|^{2} h_{j}\right]<C . \tag{2.16}
\end{equation*}
$$

### 2.4.1 Stability results for the $Y$ component

Setting $\delta Y_{i}:=Y_{i}-\tilde{Y}_{i}$ and $\delta Z_{i}:=Z_{i}-\tilde{Z}_{i}$, we obtain a key stability result for the $Y$ component.

Proposition 2.9. Assume that assumption (H1) holds true. Then, for all $0 \leqslant i \leqslant n$,

$$
\left|\delta Y_{i}\right| \leqslant C \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\left|\delta Y_{n}\right|+\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y}\right|\right]
$$

where

$$
\frac{\mathrm{d} \mathbb{Q}^{\pi}}{\mathrm{d} \mathbb{Q}}=E_{0}^{\pi}=\prod_{j=0}^{n-1}\left(1+h_{j} H_{j} \gamma_{j}\right)
$$

and

$$
\begin{equation*}
\gamma_{j}=\frac{F_{j}\left(\tilde{Y}_{j}, Z_{j}\right)-F_{j}\left(\tilde{Y}_{j}, \tilde{Z}_{j}\right)}{\left|Z_{j}-\tilde{Z}_{j}\right|^{2}}\left(Z_{j}-\tilde{Z}_{j}\right)^{\top} \mathbf{1}_{\left\{Z_{j}-\tilde{Z}_{j} \neq 0\right\}} \tag{2.17}
\end{equation*}
$$

Proof. Using the Euler scheme linearization given in Proposition 2.4 and observing $\delta F_{k}=\frac{-\zeta_{k}^{Y}}{h_{k}}$, it follows from (2.8) that

$$
\left|\delta Y_{i}\right| \leqslant \mathbb{E}_{t_{i}}\left[\left|E_{i}^{\pi}\right|\left|B_{i}^{\pi}\right|^{-1}\left(\left|\delta Y_{n}\right|+\sum_{k=i}^{n-1}\left|B_{k+1}^{\pi}\right|\left|\zeta_{k}^{Y}\right|\right)\right] .
$$

Moreover,

$$
\left|B_{i}^{\pi}\right|^{-1}\left|B_{k+1}^{\pi}\right| \leqslant\left(\frac{1}{1-h K_{y}}\right)^{k+1-i} \leqslant\left(1+\frac{h K_{y}}{\varepsilon}\right)^{k+1-i} \leqslant e^{\frac{C K_{y}}{\varepsilon}}
$$

leading to

$$
\left|\delta Y_{i}\right| \leqslant C \mathbb{E}_{t_{i}}\left[\left|E_{i}^{\pi}\right|\left(\left|\delta Y_{n}\right|+\sum_{k=i}^{n-1}\left|\zeta_{k}^{Y}\right|\right)\right]
$$

Under (H1)(iii), we get that $E_{i}^{\pi}>0$ for all $0 \leqslant i \leqslant n$ and then

$$
\left(\prod_{j=0}^{k}\left(1+h_{j} H_{j} \gamma_{j}\right)\right)_{0 \leqslant k \leqslant n}
$$

is a positive martingale with expectation equal to 1 . The measure $\mathbb{Q}^{\pi}$ is thus a probability measure.

### 2.4.2 Estimates on $\mathbb{Q}^{\pi}$

In order to retrieve nice estimates on the probability measure $\mathbb{Q}^{\pi}$, we need to introduce a new assumption.

## Assumption (H3)

(i) (H2) holds true and $\left(\sup _{0 \leqslant i \leqslant n-1} h_{i}\left|H_{i}\right|\right) K_{z}^{n}<1-\varepsilon$ with $\varepsilon$ a constant that does not depend on $n$,
(ii) $F_{i}$ are $\tilde{L}$-locally Lipschitz functions with respect to $z: \forall y \in \mathbb{R}, \forall z, z^{\prime} \in \mathbb{R}^{1 \times d}$, $\forall 0 \leqslant i \leqslant n-1$,

$$
\left|F_{i}(y, z)-F_{i}\left(y, z^{\prime}\right)\right| \leqslant \tilde{L}\left(1+|z|+\left|z^{\prime}\right|\right)\left|z-z^{\prime}\right|
$$

with $\tilde{L}$ a constant that does not depend on $n$.
Proposition 2.10. Assume that $(\mathbf{H} 3)$ holds true. Then $M_{t}:=\sum_{t_{i} \leqslant t} h_{i} \gamma_{i} H_{i}$, with $\left(\gamma_{i}\right)_{0 \leqslant i \leqslant n-1}$ given by (2.17), is a BMO martingale for the discontinuous filtration $\mathcal{F}^{n}$ defined by $\mathcal{F}_{t}^{n}:=\mathcal{F}_{t_{i}}$ when $t_{i} \leqslant t<t_{i+1}$. Moreover, there exists a constant $C$ that does not depend on $n$ such that

$$
\|M\|_{B M O\left(\mathcal{F}^{n}\right)} \leqslant C
$$

Proof. We have to show that there exists a constant $C$ that does not depend on $n$ such that, for all stopping time $S \leqslant T$,

$$
\mathbb{E}\left[\left|M_{T}-M_{S^{-}}\right|^{2} \mid \mathcal{F}_{S}\right] \leqslant C
$$

Thanks to remark (76.4) in chapter VII of [19], we know that it is sufficient to show that for all $0 \leqslant i<n$,

$$
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|h_{j} H_{j} \gamma_{j}\right|^{2}\right] \leqslant C
$$

To prove this point we use the fact that $F_{i}$ is a $\tilde{L}$-locally Lipschitz function with respect to $z$ and (2.7):

$$
\begin{aligned}
\mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|h_{j} H_{j} \gamma_{j}\right|^{2}\right] & \leqslant 3 \tilde{L}^{2}+3 \tilde{L}^{2} \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|h_{j} H_{j}\right|^{2}\left|\tilde{Z}_{j}\right|^{2}\right]+3 \tilde{L}^{2} \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|h_{j} H_{j}\right|^{2}\left|Z_{j}\right|^{2}\right] \\
& \leqslant 3 \tilde{L}^{2}+3 \tilde{L}^{2} \Lambda \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|\tilde{Z}_{j}\right|^{2} h_{j}\right]+3 \tilde{L}^{2} \Lambda \mathbb{E}_{t_{i}}\left[\sum_{j=i}^{n-1}\left|Z_{j}\right|^{2} h_{j}\right]
\end{aligned}
$$

The proof is concluded combining (2.16) with Proposition 2.7.
Since $M$ is a BMO martingale, we retrieve some strong properties for this process.
Proposition 2.11. Assume that (H3) holds true. Then, the Doléans-Dade exponential $E_{t}:=\prod_{t_{j} \leqslant t}\left(1+h_{j} H_{j} \gamma_{j}\right)$ is a uniformly integrable martingale for the filtration $\mathcal{F}^{n}$ satisfying the "reverse Hölder inequality"

$$
\mathbb{E}_{t}\left[\frac{E_{T}^{p^{*}}}{E_{t}^{p^{*}}}\right] \leqslant C, \quad 0 \leqslant t \leqslant T
$$

for some $p^{*}>1$ and $C>0$ that depend only on $\|M\|_{B M O\left(\mathcal{F}^{n}\right)}$ and $\varepsilon$. In particular, we can choose them independently of $n$. As a direct corollary, we have that $M$ is a $L^{p^{*}}$ bounded martingale.

Proof. The first theorem in [29] states that $\left(E_{t}\right)_{0 \leqslant t \leqslant 1}$ is a uniformly integrable martingale satisfying the "reverse Hölder inequality" for some $p^{*}>1$. We just have to check that we can choose $C$ and $p^{*}$ that only depend on $\|M\|_{B M O\left(\mathcal{F}^{n}\right)}$ and $\varepsilon$. Firstly, thanks to Theorem 2 in [28] we know that there exist positive constants $a$ and $K$ such that

$$
\begin{equation*}
\mathbb{E}_{\tau}\left[\left(\frac{E_{T}}{E_{\tau}}\right)^{a}\right] \leqslant K \tag{2.18}
\end{equation*}
$$

for any stopping time $\tau$. By checking carefully the proof of this theorem, we remark that $a$ is chosen such that

$$
k_{a}:=\frac{4 a^{2}+a}{\varepsilon^{2}}<\frac{1}{\|M\|_{B M O\left(\mathcal{F}^{n}\right)}}
$$

and then $K$ is set

$$
K:=\frac{1}{1-k_{a}\|M\|_{B M O\left(\mathcal{F}^{n}\right)}^{2}} .
$$

To conclude we use Lemma 3 in [29] that says that if $M$ satisfies (2.18), then it satisfies a "reverse Hölder inequality". By checking carefully the proof of this lemma we can see that constants $C$ and $p^{*}$ in the "reverse Hölder inequality" are only obtained thanks to $a, K$ and $\varepsilon$.

Combining the previous proposition with Proposition 2.9, we obtain, using Hölder's inequality, the following result.

Corollary 2.1. Assume that (H3) holds true. Then there exist constants $C>0$ and $q^{*}>1$ that do not depend on $n$ and such that, for all $0 \leqslant i \leqslant n$,

$$
\left|\delta Y_{i}\right| \leqslant C\left(\mathbb{E}_{t_{i}}\left[\left|\delta Y_{n}\right|^{q^{*}}\right]^{\frac{1}{q^{*}}}+\mathbb{E}_{t_{i}}\left[\left(\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y}\right|\right)^{q^{*}}\right]^{\frac{1}{q^{*}}}\right) .
$$

$q^{*}$ is the conjugate exponent of $p^{*}$ given in Proposition 2.11.

Remark 2.5. If $\zeta_{i}^{Y}=\zeta_{i}^{Y, 1}+\zeta_{i}^{Y, 2}$, it is easy to see that one may just apply the Corollary 2.1 on the first part of the perturbation:

$$
\left|\delta Y_{i}\right| \leq C\left(\mathbb{E}_{t_{i}}\left[\left|\delta Y_{n}\right|^{q^{*}}\right]^{\frac{1}{q^{*}}}+\mathbb{E}_{t_{i}}\left[\left(\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y, 1}\right|\right)^{q^{*}}\right]^{\frac{1}{q^{*}}}+\mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y, 2}\right|\right]\right), \quad 0 \leqslant i \leqslant n .
$$

### 2.4.3 Stability result for the $Z$ component

Proposition 2.12. Assume that (H3) holds true. Then,

$$
\mathbb{E}\left[\sum_{i=0}^{n-1} h_{i}\left|\delta Z_{i}\right|^{2}\right] \leqslant C\left(\mathbb{E}\left[\left|\delta Y_{n}\right|^{2}\right]+\mathbb{E}\left[\sum_{i=0}^{n-1} \frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}\right]+\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1}\left|\delta Y_{i}\right|^{4}\right]^{1 / 2}\right) .
$$

Proof. 1. As in the proof of Proposition 2.7, we first observe that equation (2.9) can be rewritten

$$
\delta Y_{i}=\delta Y_{i+1}+h_{i} \beta_{i} \delta Y_{i}+h_{i} \delta Z_{i} \gamma_{i}+\zeta_{i}^{Y}-h_{i} c_{i}^{-1} \delta Z_{i} H_{i}^{\top}-\delta \Delta M_{i}
$$

where $\delta \Delta M_{i}$ is an $\mathcal{F}_{t_{i+1}}$ random variable satisfying $\mathbb{E}_{t_{i}}\left[\delta \Delta M_{i}\right]=0, \mathbb{E}_{t_{i}}\left[\left|\delta \Delta M_{i}\right|^{2}\right]<\infty$ and $\mathbb{E}_{t_{i}}\left[\delta \Delta M_{i} H_{i}\right]=0$. Using the identity $|y|^{2}=|x|^{2}+2 x(y-x)+|y-x|^{2}$ and taking
the conditional expectation, we compute, setting $x=\delta Y_{i}$ and $y=\delta Y_{i+1}$,

$$
\begin{aligned}
\mathbb{E}_{t_{i}}\left[\left|\delta Y_{i+1}\right|^{2}\right] \geqslant & \left|\delta Y_{i}\right|^{2}-2\left|\delta Y_{i}\right|^{2} h_{i} \beta_{i}-2 h_{i} \delta Y_{i} \delta Z_{i} \gamma_{i} \\
& -2 \delta Y_{i} \zeta_{i}^{Y}+c_{i}^{-1} h_{i} \delta Z_{i} c_{i}^{-1} h_{i} \mathbb{E}_{t_{i}}\left[H_{i}^{\top} H_{i}\right] \delta Z_{i}^{\top} .
\end{aligned}
$$

It follows from (2.5) and (2.6) applied to the previous inequality that

$$
\left|\delta Y_{i}\right|^{2}+\frac{d}{\Lambda} h_{i}\left|\delta Z_{i}\right|^{2} \leqslant \mathbb{E}_{t_{i}}\left[\left|\delta Y_{i+1}\right|^{2}\right]+2 \delta Y_{i} \zeta_{i}^{Y}+2 h_{i} \delta Y_{i} \delta Z_{i} \gamma_{i}+2\left|\delta Y_{i}\right|^{2} h_{i} \beta_{i}
$$

and Young inequality leads to

$$
\left|\delta Y_{i}\right|^{2}+\frac{d}{2 \Lambda} h_{i}\left|\delta Z_{i}\right|^{2} \leqslant \mathbb{E}_{t_{i}}\left[\left|\delta Y_{i+1}\right|^{2}\right]+h_{i}\left(1+2 K_{y}+\frac{2 \Lambda\left|\gamma_{i}\right|^{2}}{d}\right)\left|\delta Y_{i}\right|^{2}+\frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}
$$

Summing over $i$ the previous inequality, we obtain

$$
\mathbb{E}\left[\sum_{i=0}^{n-1} h_{i}\left|\delta Z_{i}\right|^{2}\right] \leqslant C \mathbb{E}\left[\left|\delta Y_{n}\right|^{2}\right]+C \mathbb{E}\left[\sum_{i=0}^{n-1} h_{i}\left(1+\left|\gamma_{i}\right|^{2}\right)\left|\delta Y_{i}\right|^{2}\right]+C \mathbb{E}\left[\sum_{i=0}^{n-1} \frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}\right]
$$

Applying Hölder inequality, we get

$$
\begin{aligned}
\mathbb{E}\left[\sum_{i=0}^{n-1} h_{i}\left|\delta Z_{i}\right|^{2}\right] \leqslant & C \mathbb{E}\left[\left|\delta Y_{n}\right|^{2}\right]+C \mathbb{E}\left[\sum_{i=0}^{n-1} \frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}\right] \\
& +C \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1}\left|\delta Y_{i}\right|^{4}\right]^{1 / 2} \mathbb{E}\left[\left(1+\sum_{i=0}^{n-1}\left|\gamma_{i}\right|^{2} h_{i}\right)^{2}\right]^{1 / 2} .
\end{aligned}
$$

To conclude the proof, we just have to show that

$$
\mathbb{E}\left[\left(\sum_{i=0}^{n-1} h_{i}\left|\gamma_{i}\right|^{2}\right)^{2}\right] \leqslant C
$$

Using Burkholder-Davis-Gundy inequality for the discrete martingale $\left(\sum_{i=0}^{j} h_{i} H_{i} \gamma_{i}\right)_{0 \leqslant j \leqslant n}$, the previous inequality holds true if we have

$$
\mathbb{E}\left[\left(\sup _{0 \leqslant j \leqslant n-1} \sum_{i=0}^{j} h_{i} H_{i} \gamma_{i}\right)^{4}\right] \leqslant C .
$$

Thanks to Proposition 2.10 we know that $M_{t}=\sum_{t_{i} \leqslant t} h_{i} H_{i} \gamma_{i}$ is a BMO martingale with a BMO norm that does not depend on $n$. To conclude the proof, we use an energy
inequality or the John-Nirenberg inequality, see e.g. Theorem 109 and inequality (109.5) in the chapter VI of [19], and obtain

$$
\mathbb{E}\left[\left(\sup _{0 \leqslant j \leqslant n-1} \sum_{i=0}^{j} h_{i} H_{i} \gamma_{i}\right)^{4}\right] \leqslant C
$$

with $C$ that depends only on $\|M\|_{B M O\left(\mathcal{F}^{n}\right)}$.

## 3 Convergence analysis of the discrete-time approximation

The aim of this part is to study the error between the solution $(Y, Z)$ of the BSDE (1.2) and $\left(Y^{\pi}, Z^{\pi}\right)$ the solution of the BTZ scheme given in Definition 1.1, recalling (1.8). Thanks to Theorem 2.2 we know that we just have to estimate the error between $\left(Y^{N}, Z^{N}\right)$ and $\left(Y^{\pi}, Z^{\pi}\right)$.
Let us first observe that we can apply the results of the previous section to $\left(Y^{\pi}, Z^{\pi}\right)$.
Lemma 3.1. Under same assumptions than Theorem 1.1, the scheme given in Definition 1.1 satisfies (H3).

Proof. With our special choice of parameters $R$ and $N$, there exists $\varepsilon>0$ such that for $n$ big enough we have $K_{f, y} h \leqslant \frac{C K_{f, y}}{n}<1-\varepsilon$. Moreover, we have also for $n$ large enough

$$
\left(\sup _{0 \leqslant i \leqslant n-1} h_{i}\left|H_{i}^{R}\right|\right) n^{\alpha} \leqslant \sqrt{h} R n^{\alpha} \leqslant \frac{\sqrt{C} \log n}{n^{1 / 2-\alpha}} \leqslant 1-\varepsilon .
$$

### 3.1 Expression of the perturbing error

We first observe that $\left(Y^{N}, Z^{N}\right)$ can be rewritten as a perturbed BTZ scheme. Namely, setting $\tilde{\mathrm{Y}}_{i}:=Y_{t_{i}}^{N}$, for all $i \leqslant n$, we have

$$
\left\{\begin{array}{l}
\tilde{\mathrm{Y}}_{i}=\mathbb{E}_{t_{i}}\left[\tilde{\mathrm{Y}}_{i+1}+h_{i} f_{N}\left(X_{i}^{\pi}, \tilde{\mathrm{Y}}_{i}, \tilde{\mathrm{Z}}_{i}\right)\right]+\zeta_{i}^{Y}  \tag{3.1}\\
\tilde{\mathrm{Z}}_{i}=\mathbb{E}_{t_{i}}\left[\tilde{\mathrm{Y}}_{i+1} H_{i}^{R}\right],
\end{array}\right.
$$

with

$$
\begin{equation*}
\zeta_{i}^{Y}=\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \tilde{Z}_{i}\right) d s\right] \tag{3.2}
\end{equation*}
$$

The following lemma will allow us to use the results of the last section.

Lemma 3.2. The perturbed scheme $\left(\tilde{\mathrm{Y}}_{i}, \tilde{\mathrm{Z}}_{i}\right)_{i \leqslant n}$ satisfies, for all $0 \leqslant k \leqslant n-1$,

$$
\mathbb{E}_{t_{k}}\left[\sum_{i=k}^{n-1}\left|\tilde{\mathrm{Z}}_{i}\right|^{2} h_{i}\right] \leqslant C .
$$

Proof. Observe that,

$$
\begin{equation*}
\mathbb{E}_{t_{k}}\left[\sum_{i=k}^{n-1} h_{i}\left|\tilde{Z}_{i}\right|^{2}\right] \leqslant C\left(\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\tilde{Z}_{i}-\tilde{Z}_{i}^{N}\right|^{2} h_{i}\right]+\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\tilde{Z}_{i}^{N}\right|^{2} h_{i}\right]\right) \tag{3.3}
\end{equation*}
$$

where

$$
\tilde{Z}_{i}^{N}:=\mathbb{E}_{t_{i}}\left[Y_{t_{i+1}}^{N} \frac{\Delta W_{i}}{h_{i}}\right] .
$$

Applying Lemma 2.2, we obtain

$$
\begin{equation*}
\mathbb{E}_{t_{k}}\left[\sum_{i=k}^{n-1} h_{i}\left|\tilde{\mathrm{Z}}_{i}\right|^{2}\right] \leqslant C\left(1+\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\tilde{\mathrm{Z}}_{i}-\tilde{Z}_{i}^{N}\right|^{2} h_{i}\right]\right) . \tag{3.4}
\end{equation*}
$$

Moreover, we compute

$$
\begin{aligned}
\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\tilde{\mathrm{Z}}_{i}-\tilde{Z}_{i}^{N}\right|^{2} h_{i}\right] & =\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\mathbb{E}_{t_{i}}\left[\left(Y_{t_{i+1}}^{N}-Y_{t_{i}}^{N}\right)\left(H_{i}^{R}-\frac{\Delta W_{i}}{h_{i}}\right)\right]\right|^{2} h_{i}\right] \\
& \leqslant C \sum_{i \geqslant k} \mathbb{E}_{t_{k}}\left[\left|Y_{t_{i+1}}^{N}-Y_{t_{i}}^{N}\right|^{2}\right]
\end{aligned}
$$

where we used Cauchy-Schwartz inequality, recalling (2.7) .
We then compute, thanks to assumptions on $f_{N}$ and Remark 2.1,

$$
\begin{aligned}
\mathbb{E}_{t_{k}}\left[\left|Y_{t_{i+1}}^{N}-Y_{t_{i}}^{N}\right|^{2}\right] & \leqslant C\left(h_{i} \mathbb{E}_{t_{k}}\left[\int_{t_{i}}^{t_{i+1}}\left|f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right)\right|^{2} \mathrm{~d} s\right]+\mathbb{E}_{t_{k}}\left[\int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}\right|^{2} \mathrm{~d} s\right]\right) \\
& \leqslant C\left(h^{2}+\left(1+N^{2} h\right) \mathbb{E}_{t_{k}}\left[\int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}\right|^{2} \mathrm{~d} s\right]\right) .
\end{aligned}
$$

Summing over $i$, recalling Remark 2.1, we obtain

$$
\begin{equation*}
\mathbb{E}_{t_{k}}\left[\sum_{i \geqslant k}\left|\tilde{\mathrm{Z}}_{i}-\tilde{Z}_{i}^{N}\right|^{2} h_{i}\right] \leqslant C\left(1+\left\|\int_{0} Z_{s}^{N} d W_{s}\right\|_{B M O(\mathcal{F})}^{2}\right) \leqslant C . \tag{3.5}
\end{equation*}
$$

The proof is concluded combining the above inequality with (3.4).

### 3.2 Regularity

In the followings, we need regularity results on $\left(X, Y^{N}, Z^{N}\right)$. The specificity here is that we need the estimates under the probability measure $\mathbb{P}$ and $\mathbb{Q}^{\pi}$. The first result deals with the path regularity of $Y$ under the probability measure $\mathbb{P}$. It is a mere generalization of Theorem 5.5 in [26].

Proposition 3.1. (Y-part) For all $p \leqslant 1$, we have

$$
\begin{equation*}
\mathbb{E}\left[\sup _{0 \leqslant j \leqslant n-1} \sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Y_{s}^{N}-Y_{t_{j}}^{N}\right|^{2 p}\right] \leqslant C_{p} h^{p} . \tag{3.6}
\end{equation*}
$$

The second result is a slight modification of the well-known Zhang's path regularity theorem, whose proof is postponed to the Appendix.

Proposition 3.2. ( $Z$-part) For all $p \geqslant 1$ and $\eta>0$, we have

$$
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right] \leqslant C_{\eta, p} h^{p(1+\eta)} .
$$

Let us remark that the previous proposition stays true when we replace $\mathbb{Q}^{\pi}$ by $\mathbb{P}$ : it is a mere generalization of Theorem 5.6 in [26].

### 3.3 Discretization error for the $Y$-component

Proposition 3.3. There exists $q^{*}>1$ and, for all $\eta>0$ and $p \geqslant 1$, there exist constants $C_{p}$ and $C_{\eta, p}$ such that

$$
\begin{aligned}
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}-Y_{i}^{\pi}\right|^{2 p}\right] \leqslant & C_{\eta, p} h^{p(1-\eta)}+C_{p} \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{t_{j}}-X_{j}^{\pi}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \\
& +C_{p} \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{4 p}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2 p}\right) .
\end{aligned}
$$

Before giving the proof, let us emphasize that $q^{*}$ is the exponent given by Corollary 2.1 and so it is the conjugate exponent of $p^{*}$ given by Proposition 2.11.
Proof. The proof is divided in several steps.

1. We first observe that

$$
\begin{equation*}
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}-Y_{i}^{\pi}\right|^{2 p}\right] \leqslant C_{p}\left(\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}-Y_{t_{i}}^{N}\right|^{2 p}\right]+\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}^{N}-Y_{i}^{\pi}\right|^{2 p}\right]\right) \tag{3.7}
\end{equation*}
$$

To bound the first term in the right-hand side of the above equation, we apply Theorem 2.2 and get:

$$
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}-Y_{t_{i}}^{N}\right|^{2 p}\right] \leqslant C_{p} h^{p}
$$

recalling (1.8).
2. To control the error between the solution $Y^{N}$ and the scheme $Y^{\pi}$, we will combine the stability results proved in the previous section with a careful analysis of the perturbation error $\left(\zeta_{i}^{Y}\right)_{0 \leqslant i<n}$ given by (3.2). We first observe that

$$
\begin{aligned}
\zeta_{i}^{Y}= & \mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{s}, Y_{s}^{N}, Z_{s}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{s}^{N}, Z_{s}^{N}\right) d s\right] \\
& +\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{i}^{\pi}, Y_{s}^{N}, Z_{s}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, Z_{s}^{N}\right) d s\right] \\
& +\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, Z_{s}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \bar{Z}_{i}^{N}\right) d s\right] \\
& +\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \bar{Z}_{i}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \tilde{Z}_{i}^{N}\right) d s\right] \\
& +\mathbb{E}_{t_{i}}\left[\int_{t_{i}}^{t_{i+1}} f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \tilde{Z}_{i}^{N}\right)-f_{N}\left(X_{i}^{\pi}, Y_{t_{i}}^{N}, \tilde{Z}_{i}\right) d s\right] \\
:= & \zeta_{i}^{Y, x}+\zeta_{i}^{Y, y}+\zeta_{i}^{Y, \bar{z}}+\zeta_{i}^{Y, \tilde{z}}+\zeta_{i}^{Y, w},
\end{aligned}
$$

recalling (2.2).
Using Lemma 3.1 and Lemma 3.2, we apply Proposition 2.9 and Corollary 2.1 (see also Remark 2.5) to obtain

$$
\begin{aligned}
\left|Y_{t_{i}}^{N}-Y_{i}^{\pi}\right| \leqslant & C \mathbb{E}_{t_{i}}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, x}\right|\right)^{q^{*}}\right]^{1 / q^{*}}+C \mathbb{E}_{t_{i}}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, y}\right|\right)^{q^{*}}\right]^{1 / q^{*}} \\
& +C \mathbb{E}_{t_{i}}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, w}\right|\right)^{q^{*}}\right]^{1 / q^{*}}+C \mathbb{E}_{t_{i}}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, \tilde{z}}\right|^{q^{*}}\right]^{1 / q^{*}}\right. \\
& +C \mathbb{E}_{t_{i}}\left[\left|Y_{t_{n}}^{N}-Y_{n}^{\pi}\right|^{q^{*}}\right]^{1 / q^{*}}+C \mathbb{E}_{t_{i}}\left[\left\{\prod_{j=i}^{n-1}\left(1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}\right)\right\}\left\{\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y, \bar{z}}\right|\right\}\right]
\end{aligned}
$$

A convexity inequality and Doob maximal inequality allow us to write, for all $p \geqslant 1$,

$$
\begin{equation*}
\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n}\left|Y_{t_{i}}^{N}-Y_{i}^{\pi}\right|^{2 p}\right] \leqslant C\left(\mathcal{E}_{p}^{x}+\mathcal{E}_{p}^{y}+\mathcal{E}_{p}^{w}+\mathcal{E}_{p}^{\tilde{z}}+\mathcal{E}_{p}^{\bar{z}}\right) \tag{3.8}
\end{equation*}
$$

with

$$
\mathcal{E}_{p}^{x}:=\mathbb{E}\left[\left|Y_{t_{n}}^{N}-Y_{n}^{\pi}\right|^{2 p q^{*}}\right]^{1 / q^{*}}+C \mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, x}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}}
$$

coming from the approximation of $X$ by $X^{\pi}$ in the terminal condition and the generator,

$$
\mathcal{E}_{p}^{y}:=\mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, y}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}}
$$

coming from the approximation of $Y^{N}$ by $\sum_{i=0}^{n-1} Y_{t_{i}}^{N} \mathbf{1}_{t_{i} \leqslant t<t_{i+1}}$ in the generator,

$$
\mathcal{E}_{p}^{w}:=\mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, w}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}}
$$

coming from the approximation of $\Delta W_{i}$ by $h_{i} H_{i}$,

$$
\mathcal{E}_{p}^{\tilde{z}}:=\mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, \tilde{z}}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}}
$$

coming from the approximation of $\sum_{i=0}^{n-1} \bar{Z}_{i}^{N} \mathbf{1}_{t_{i} \leqslant t<t_{i+1}}$ by $\sum_{i=0}^{n-1} \tilde{Z}_{i}^{N} \mathbf{1}_{t_{i} \leqslant t<t_{i+1}}$ in the generator, and finally

$$
\mathcal{E}_{p}^{\bar{z}}:=n^{p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left|\zeta_{j}^{Y, \bar{z}}\right|^{2}\right]^{p}\right]
$$

due to the approximation of $Z^{N}$ by $\sum_{i=0}^{n-1} \bar{Z}_{i}^{N} \mathbf{1}_{t_{i} \leqslant t<t_{i+1}}$ in the generator.
We will now bound these five terms.
2.a. Since $g$ is Lipschitz continuous, we have

$$
\begin{equation*}
\mathbb{E}\left[\left|Y_{t_{n}}^{N}-Y_{n}^{\pi}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \leqslant C_{p} \mathbb{E}\left[\left|X_{n}^{\pi}-X_{T}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \tag{3.9}
\end{equation*}
$$

Similarly, since $f_{N}$ is Lipschitz-continuous in its $x$-variable,

$$
\begin{align*}
\mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, x}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}} & \leqslant C_{p} \sup _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\left(\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|X_{s}-X_{j}^{\pi}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}} \\
\leqslant & C_{p} \sup _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|X_{s}-X_{t_{j}}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \\
& +C_{p} \sup _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\left|X_{t_{j}}-X_{j}^{\pi}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \tag{3.10}
\end{align*}
$$

Classical result on the path regularity of SDE's solutions yields

$$
\begin{equation*}
\sup _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|X_{s}-X_{t_{j}}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \leqslant C_{p} h^{p} . \tag{3.11}
\end{equation*}
$$

Combining (3.9)-(3.10)-(3.11), we obtain

$$
\begin{equation*}
\mathcal{E}_{p}^{x} \leqslant C_{p} h^{p}+C_{p} \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{t_{j}}-X_{j}^{\pi}\right|^{2 p q^{*}}\right]^{1 / q^{*}} \tag{3.12}
\end{equation*}
$$

2.b. We easily compute that

$$
\mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, y}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}} \leqslant C_{p} \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n-1} \sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Y_{s}^{N}-Y_{t_{j}}^{N}\right|^{2 p q^{*}}\right]^{1 / q^{*}}
$$

Applying inequality (3.6), this leads to

$$
\begin{equation*}
\mathcal{E}_{p}^{y} \leqslant C_{p} h^{p} \tag{3.13}
\end{equation*}
$$

2.c. Using (H3)(ii) and Remark 2.1 we have

$$
\begin{aligned}
\left|\zeta_{j}^{Y, w}\right| & \leqslant C h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|+\left|\tilde{Z}_{j}\right|\right)\left|\tilde{Z}_{j}^{N}-\tilde{Z}_{j}\right| \\
& \leqslant C h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|\right)\left(\left|\tilde{Z}_{j}^{N}-\tilde{Z}_{j}\right|^{2}+\left|\tilde{Z}_{j}^{N}-\tilde{Z}_{j}\right|\right) \\
& \leqslant C h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|\right)\left(\mathbb{E}_{t_{j}}\left[\left|Y_{t_{j+1}}^{N}\right|\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}+\mathbb{E}_{t_{j}}\left[\left|Y_{t_{j+1}}^{N}\right|\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]\right) \\
& \leqslant C h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|\right)\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]\right),
\end{aligned}
$$

and thus, we obtain

$$
\begin{aligned}
& \mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}^{Y, w}\right|\right)^{2 p q^{*}}\right]^{1 / q^{*}} \\
\leqslant & C_{p} \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]\right)^{2 p}\left(1+\mathbb{E}\left[\max _{0 \leqslant i \leqslant n-1}\left|\tilde{Z}_{i}^{N}\right|^{2 p q^{*}}\right]^{1 / q^{*}}\right) .
\end{aligned}
$$

Using Lemma 2.2, we compute

$$
\begin{aligned}
\mathbb{E}\left[\max _{0 \leqslant i \leqslant n-1}\left|\tilde{Z}_{i}^{N}\right|^{2 p q^{*}}\right]^{1 / q^{*}} & \leqslant C_{p}\left(1+\mathbb{E}\left[\max _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{\mid}\right]^{p q^{*}}\right]^{1 / q^{*}}\right) \\
& \leqslant C_{p}\left(1+\mathbb{E}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{4 p q^{*}}\right]^{1 / q^{*}}\right) \\
& \leqslant C_{p}
\end{aligned}
$$

where we used the Doob maximal inequality. Finally, we obtain

$$
\begin{equation*}
\mathcal{E}_{p}^{w} \leqslant C_{p} \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{4 p}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2 p}\right) \tag{3.14}
\end{equation*}
$$

2.d. Using (H3)(ii), (2.4), Lemma 2.1 and Lemma 2.2, we have

$$
\begin{aligned}
\left|\zeta_{j}^{Y, \tilde{z}}\right| & \leqslant C h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|+\left|\bar{Z}_{j}^{N}\right|\right)\left|\tilde{Z}_{j}^{N}-\bar{Z}_{j}^{N}\right| \\
& \leqslant C h^{1 / 2} h_{j}\left(1+\left|\tilde{Z}_{j}^{N}\right|+\left|\bar{Z}_{j}^{N}\right|\right)\left(1+\mathbb{E}_{t_{j}}\left[\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|X_{s}\right|^{4}\right]^{1 / 2}\right) \\
& \leqslant C h^{1 / 2} h_{j}\left(1+\mathbb{E}_{t_{j}}\left[\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|X_{s}\right|^{4}\right]\right) .
\end{aligned}
$$

Then by same arguments than in part 2.c we obtain

$$
\begin{equation*}
\mathcal{E}_{p}^{\tilde{z}} \leqslant C_{p} h^{p} . \tag{3.15}
\end{equation*}
$$

2.e. The last term is the more involved. Since the functions $f$ and $f_{N}$ are locally Lipschitz with respect to $z$, compute $\left|\zeta_{j}^{Y, \bar{z}}\right|$ :

$$
\left|\zeta_{j}^{Y, \bar{z}}\right| \leqslant C \mathbb{E}_{t_{j}}\left[\left(1+\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Z_{s}^{N}\right|+\left|\bar{Z}_{j}^{N}\right|\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right| d s\right]
$$

and so,

$$
\begin{equation*}
\left|\zeta_{j}^{Y, \bar{z}}\right|^{2} \leqslant C h_{j} \mathbb{E}_{t_{j}}\left[\left(1+\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Z_{s}^{N}\right|^{2}+\left|\bar{Z}_{j}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right] . \tag{3.16}
\end{equation*}
$$

Let us remark that in the previous bound, the term inside the conditional expectation
is a $\mathcal{F}_{t_{j+1}-\text {-measurable random variable, so we have }}$

$$
\begin{aligned}
& \mathbb{E}_{t_{j}}\left[\left(1+\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Z_{s}^{N}\right|^{2}+\left|\bar{Z}_{j}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right] \\
= & \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\frac{1}{1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}}\left(1+\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Z_{s}^{N}\right|^{2}+\left|\bar{Z}_{j}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right] \\
\leqslant & \frac{1}{\varepsilon} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left(1+\sup _{t_{j} \leqslant s \leqslant t_{j+1}}\left|Z_{s}^{N}\right|^{2}+\left|\bar{Z}_{j}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right] \\
\leqslant & \frac{1}{\varepsilon} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left(1+\sup _{0 \leqslant s \leqslant T}\left|Z_{s}^{N}\right|^{2}+\max _{0 \leqslant i \leqslant n-1}\left|\bar{Z}_{i}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right]
\end{aligned}
$$

since $1 /\left(1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}\right) \leqslant 1 / \varepsilon$ under (H3). Then (3.16) becomes

$$
\begin{equation*}
\left|\zeta_{j}^{Y, \bar{z}}\right|^{2} \leqslant C h_{j} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left(1+\sup _{0 \leqslant s \leqslant T}\left|Z_{s}^{N}\right|^{2}+\max _{0 \leqslant i \leqslant n-1}\left|\bar{Z}_{i}^{N}\right|^{2}\right) \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right] . \tag{3.17}
\end{equation*}
$$

Thanks to Proposition 2.3 and Lemma 2.1 we can simplify the first part of our estimate:

$$
\sup _{0 \leqslant s \leqslant T}\left|Z_{s}^{N}\right| \leqslant C\left(1+\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|\right)
$$

and
$\max _{0 \leqslant i \leqslant n-1}\left|\bar{Z}_{i}^{N}\right| \leqslant C\left(1+\max _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\sup _{t_{i} \leqslant s \leqslant t_{i+1}}\left|X_{s}\right|\right]\right) \leqslant C\left(1+\max _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|\right]\right)$.
Inserting these two bounds into (3.17) we obtain
$\mathcal{E}_{p}^{\bar{z}} \leqslant C \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\left(1+\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]\right) \sum_{j=i}^{n-1} \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right]^{p}\right]$,
and, using Hölder inequality and a convexity inequality, we get for any $\eta>0$

$$
\begin{align*}
\mathcal{E}_{p}^{\bar{z}} \leqslant & C_{\eta, p}\left(1+\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{1+\eta}{\eta}}\right]^{p}\right]^{\frac{\eta}{1+\eta}}\right) \\
& \times \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\left(\sum_{j=i}^{n-1} \int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right]^{\frac{1}{1+\eta}} \\
\leqslant & C_{\eta, p} h^{-\frac{p \eta}{1+\eta}}\left(1+\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{1+\eta}{\eta}}\right]^{p}\right]^{\frac{\eta}{1+\eta}}\right) \\
& {\left[\mathbb{E}^{\left.\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right]^{\frac{1}{1+\eta}}}\right.} \tag{3.18}
\end{align*}
$$

We can easily upper bound the first part of the last estimate. Indeed, thanks to Proposition 2.11 we are able to use once again Hölder inequality with $p^{*}$ and $q^{*}$ :

$$
\begin{aligned}
& \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{1+\eta}{\eta}}\right]^{p}\right]^{\frac{\eta}{1+\eta}} \\
& \leqslant \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\prod_{j=i}^{n-1}\left(1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}\right)^{p^{*}}\right]^{p / p^{*}} \mathbb{E}_{t_{i}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{q^{*}(1+\eta)}{\eta}}\right]^{p / q^{*}}\right]^{\frac{\eta}{1+\eta}} \\
& \leqslant C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{q^{*}(1+\eta)}{\eta}}\right]^{p / q^{*}}\right]^{\frac{\eta}{1+\eta}} \\
& \leqslant C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{q^{*}(1+\eta)}{\eta}}\right]^{2 p}\right]^{\frac{\eta}{2 q^{*}(1+\eta)}} .
\end{aligned}
$$

To conclude now we just have to use Doob maximal inequality and classical estimates on $X$ to obtain

$$
\begin{aligned}
& \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\max _{0 \leqslant j \leqslant n} \mathbb{E}_{t_{j}}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{2}\right]^{\frac{q^{*}(1+\eta)}{\eta}}\right]^{2 p}\right]^{\frac{\eta}{2 q^{*}(1+\eta)}} \\
\leqslant & C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant s \leqslant T}\left|X_{s}\right|^{\frac{2 p q^{*}(1+\eta)}{\eta}}\right]^{\frac{\eta}{2 q^{*}(1+\eta)}} \leqslant C_{\eta, p}
\end{aligned}
$$

Finally (3.18) becomes

$$
\begin{equation*}
\mathcal{E}_{p}^{\bar{z}} \leqslant C_{\eta, p} h^{-\frac{p \eta}{1+\eta}} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right]^{\frac{1}{1+\eta}} \tag{3.19}
\end{equation*}
$$

Applying Proposition 3.2, we deduce from the last inequality

$$
\begin{equation*}
\mathcal{E}_{p}^{\bar{z}} \leqslant C_{\eta, p} h^{\frac{p}{1+\eta}}=C_{\eta, p} h^{p(1-\tilde{\eta})} \tag{3.20}
\end{equation*}
$$

with $\tilde{\eta}=1-1 /(1+\eta)$. Since $(3.20)$ is true for all $\eta>0$, then it is true for all $\tilde{\eta}>0$ and then we can replace $\tilde{\eta}$ by $\eta$.
3. Inserting estimates (3.12)-(3.13)-(3.14)-(3.20) in (3.8) concludes the proof of the proposition.

### 3.4 Discretization error for the $Z$-component

Proposition 3.4. There exists $q^{*}>1$ (the same as in Proposition 3.3) such that for all $\eta>0$,
$\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}-Z_{i}^{\pi}\right|^{2} d s\right] \leqslant C_{\eta} h^{1-\eta}+C \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{t_{j}}-X_{j}^{\pi}\right|^{4 q^{*}}\right]^{1 /\left(2 q^{*}\right)}$

$$
+C \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{4}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}\right)
$$

Proof. The proof is divided in several steps.

1. Firstly, thanks to Theorem 2.2 we know that we just have to estimate the error between $Z^{N}$ and $Z^{\pi}$. We then observe
$\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}-Z_{i}^{\pi}\right|^{2} d s\right] \leqslant 4 \mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}-\bar{Z}_{i}^{N}\right|^{2} d s\right]+4 \mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\bar{Z}_{i}^{N}-\tilde{Z}_{i}^{N}\right|^{2} d s\right]$

$$
+4 \mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{Z}_{i}^{N}-\tilde{\mathrm{Z}}_{i}\right|^{2} d s\right]+4 \mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{\mathrm{Z}}_{i}-Z_{i}^{\pi}\right|^{2} d s\right]
$$

Applying Theorem 5.6 in [26] we obtain

$$
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}-\bar{Z}_{i}^{N}\right|^{2} d s\right] \leqslant C h
$$

Moreover, by using (2.4) and classical estimates en $X$, we directly have that

$$
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\bar{Z}_{s}^{N}-\tilde{Z}_{i}^{N}\right|^{2} d s\right] \leqslant C h
$$

Finally, by using the fact that $Y^{N}$ is bounded uniformly in $n$ (see Remark 2.1) we easily compute that

$$
\begin{aligned}
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{Z}_{i}^{N}-\tilde{Z}_{i}\right|^{2} d s\right] & \leqslant \mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}} \mathbb{E}_{t_{i}}\left[\left|Y_{t_{i+1}}^{N}\right|\left|H_{i}^{R}-\frac{\Delta W_{i}}{h_{i}}\right|\right]^{2} d s\right] \\
& \leqslant C \max _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2} .
\end{aligned}
$$

Thus we conclude that

$$
\begin{aligned}
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|Z_{s}^{N}-Z_{i}^{\pi}\right|^{2} d s\right] & \leqslant C h+C \max _{0 \leqslant j \leqslant n-1} \mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2} \\
& +\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{\mathrm{Z}}_{i}-Z_{i}^{\pi}\right|^{2} d s\right]
\end{aligned}
$$

2. Applying the stability results of Proposition 2.12 , we obtain

$$
\begin{array}{r}
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{\mathrm{Z}}_{i}-Z_{i}^{\pi}\right|^{2} d s\right] \leqslant C \mathbb{E}\left[\left|Y_{t_{n}}^{N}-Y_{n}^{\pi}\right|^{2}\right]+C \mathbb{E}\left[\sum_{i=0}^{n-1} \frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}\right] \\
+C \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1}\left|Y_{t_{i}}^{N}-Y_{i}^{\pi}\right|^{4}\right]^{1 / 2} \tag{3.21}
\end{array}
$$

Using the same arguments as in proof of Proposition 3.3 with the simpler setting $p=1$ and $\mathbb{Q}^{\pi}=\mathbb{P}$ (these arguments also require to show Proposition 3.2 with $\mathbb{Q}^{\pi}=\mathbb{P}$ ), one retrieves that

$$
\begin{aligned}
\mathbb{E}\left[\left|Y_{t_{n}}^{N}-Y_{n}^{\pi}\right|^{2}\right]+\mathbb{E}\left[\sum_{i=0}^{n-1} \frac{\left|\zeta_{i}^{Y}\right|^{2}}{h_{i}}\right] \leqslant & C_{\eta} h^{1-\eta}+C \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{t_{j}}-X_{j}^{\pi}\right|^{2}\right] \\
& +C \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{4}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}\right)
\end{aligned}
$$

Plugging the last inequality in equation (3.21) and applying Proposition 3.3, with $p=2$, we obtain

$$
\begin{aligned}
\mathbb{E}\left[\sum_{i=0}^{n-1} \int_{t_{i}}^{t_{i+1}}\left|\tilde{\mathrm{Z}}_{i}-Z_{i}^{\pi}\right|^{2} d s\right] & \leqslant C_{\eta} h^{1-\eta}+C \mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{t_{j}}-X_{j}^{n}\right|^{4 q^{*}}\right]^{\frac{1}{2 q^{*}}} \\
& +C \max _{0 \leqslant j \leqslant n-1}\left(\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{4}+\mathbb{E}\left[\left|H_{j}^{R}-\frac{\Delta W_{j}}{h_{j}}\right|\right]^{2}\right)
\end{aligned}
$$

Combining this last inequality with step 1 concludes the proof of the proposition.

### 3.5 Proof of Theorem 1.1

We have to combine Proposition 3.3 with $p=1$, Proposition 3.4 with classical estimates on the Euler scheme for SDE, recall (1.7), and classical results about Gaussian distribution tails. Indeed, we compute that

$$
\begin{align*}
\mathbb{E}\left[\left|H_{i}^{R}-\frac{\Delta W_{i}}{h_{i}}\right|\right] & \leqslant \mathbb{E}\left[\left|H_{i}^{R}-\frac{\Delta W_{i}}{h_{i}}\right|^{2}\right]^{1 / 2} \leqslant\left(\frac{2 d}{h_{i}} \int_{R}^{+\infty} x^{2} \frac{e^{-x^{2} / 2}}{\sqrt{2 \pi}} d x\right)^{1 / 2} \\
& \leqslant C\left(\frac{R e^{-R^{2} / 2}}{h_{i}}\right)^{1 / 2} \leqslant C\left(\frac{\log n}{e^{\frac{1}{2}(\log n)^{2}-\theta \log n}}\right)^{1 / 2} \leqslant \frac{C}{n} \tag{3.22}
\end{align*}
$$

## 4 Numerical scheme

### 4.1 Definition and convergence

In this part, we propose a fully implementable numerical scheme based on a Markovian quantization method, see e.g. [24, 35] for general results about quantization and to $[2,15]$ for a setting related to ours. To this end, given $\delta>0$ and $\kappa \in \mathbb{N}^{*}$, we consider the bounded lattice grid:

$$
\Gamma=\left\{x \in \delta \mathbb{Z}^{d}| | x^{j} \mid \leqslant \kappa \delta, 1 \leqslant j \leqslant d\right\} .
$$

Observe that there are $(2 \kappa)^{d}+1$ points in $\Gamma$. We then introduce a projection operator $\Pi$ on the grid $\Gamma$ centered in $X_{0}$ given by, for $x \in R^{d}$,

$$
(\Pi[x])^{j}= \begin{cases}\delta\left\lfloor\delta^{-1}\left(x^{j}-X_{0}^{j}\right)+\frac{1}{2}\right\rfloor+X_{0}^{j}, & \text { if }\left|x^{j}-X_{0}^{j}\right| \leqslant \kappa \delta, \\ \kappa \delta, & \text { if } x^{j}-X_{0}^{j}>\kappa \delta, \\ -\kappa \delta, & \text { if } x^{j}-X_{0}^{j}<\kappa \delta .\end{cases}
$$

To compute the conditionnal expectation appearing in the scheme given in Definition 1.1, we use an optimal quantization of Gaussian random variables $\left(\Delta W_{i}\right)$. These random variables are approximated by a sequence of centered random variables $\left(\Delta \widehat{W}_{i}=\right.$ $\left.\sqrt{h_{i}} G_{M}\left(\frac{\Delta W_{i}}{\sqrt{h_{i}}}\right)\right)$ with discrete support. Here, $G_{M}$ denotes the projection operator on the optimal quantization grid for the standard gaussian distribution with $M$ points in the support, see [24, 35] for details ${ }^{2}$. Moreover, it is shown in [24] that

$$
\begin{equation*}
\mathbb{E}\left[\left|\Delta W_{i}-\Delta \widehat{W}_{i}\right|^{p}\right]^{\frac{1}{p}} \leqslant C_{p, d} \sqrt{h} M^{-\frac{1}{d}} . \tag{4.1}
\end{equation*}
$$

[^2]In this context, we introduce the following discrete/truncated version of the Euler scheme,

$$
\left\{\begin{array}{l}
\widehat{X}_{0}^{\pi}=X_{0}  \tag{4.2}\\
\widehat{X}_{i+1}^{\pi}=\Pi\left[\widehat{X}_{i}^{\pi}+h_{i} b\left(\widehat{X}_{i}^{\pi}\right)+\sigma\left(\widehat{X}_{i}^{\pi}\right) \Delta \widehat{W}_{i}\right] .
\end{array}\right.
$$

We observe that $\widehat{X}^{\pi}$ is a markovian process living on $\Gamma$ and satisfying $\left|\widehat{X}_{i}^{\pi}\right| \leqslant C\left(\left|X_{0}\right|+\right.$ $\kappa \delta$ ), for all $i \leqslant n$.

We then adapt the scheme given in Definition 1.1 to this framework.
Definition 4.1. We denote $\left(\widehat{Y}^{\pi}, \widehat{Z}^{\pi}\right)_{0 \leqslant i \leqslant n}$ the solution of the BTZ-scheme satisfying
(i) The terminal condition is $\left(\widehat{Y}_{n}^{\pi}, \widehat{Z}_{n}^{\pi}\right)=\left(g\left(\widehat{X}_{n}^{\pi}\right), 0\right)$
(ii) for $i<n$, the transition from step $i+1$ to step $i$ is given by

$$
\left\{\begin{array}{l}
\widehat{Y}_{i}^{\pi}=\mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi}+h_{i} f_{N}\left(\widehat{X}_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \widehat{Z}_{i}^{\pi}\right)\right]  \tag{4.3}\\
\widehat{Z}_{i}^{\pi}=\mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi} \widehat{H}_{i}^{R}\right]
\end{array}\right.
$$

The coefficients $\left(\widehat{H}_{i}^{R}\right)$ are defined, given $R>0$, by

$$
\begin{equation*}
\left(\widehat{H}_{i}^{R}\right)^{\ell}=\frac{-R}{\sqrt{h_{i}}} \vee \frac{\left(\Delta \widehat{W}_{i}\right)^{\ell}}{h_{i}} \wedge \frac{R}{\sqrt{h_{i}}}, \quad 1 \leqslant \ell \leqslant d \tag{4.4}
\end{equation*}
$$

The parameters $R$ and $N$ are chosen as in (1.8).
Proposition 4.1. $\left(\widehat{Y}^{\pi}, \widehat{Z}^{\pi}\right)$ is a Markovian process. More precisely, for all $i \in\{0, \ldots, n\}$, there exist two functions $u^{\pi}\left(t_{i},.\right): \Gamma \rightarrow \mathbb{R}$ and $v^{\pi}\left(t_{i},.\right): \Gamma \rightarrow \mathbb{R}^{1 \times d}$ such that

$$
\widehat{Y}^{\pi}=u^{\pi}\left(t_{i}, \widehat{X}_{i}^{\pi}\right) \quad \text { and } \quad \widehat{Z}_{i}^{\pi}=v^{\pi}\left(t_{i}, \widehat{X}_{i}^{\pi}\right)
$$

These functions can be computed on the grid by the following backward induction: for all $i \in\{0, \ldots, n\}$ and $x \in \Gamma$,

$$
\left\{\begin{align*}
v^{\pi}\left(t_{i}, x\right)= & \mathbb{E}\left[u^{\pi}\left(t_{i+1}, \Pi_{\delta}\left(x+h b(x)+\sqrt{h} \sigma(x) G_{M}(U)\right)\right) \frac{G_{M}^{R}(U)}{\sqrt{h_{i}}}\right]  \tag{4.5}\\
u^{\pi}\left(t_{i}, x\right)= & \mathbb{E}\left[u^{\pi}\left(t_{i+1}, \Pi_{\delta}\left(x+h_{i} b(x)+\sqrt{h_{i}} \sigma(x) G_{M}(U)\right)\right)\right] \\
& +h f_{N}\left(t_{i}, x, u^{\pi}\left(t_{i}, x\right), v^{\pi}\left(t_{i}, x\right)\right), \quad \text { for } i<n
\end{align*}\right.
$$

with $U \sim \mathcal{N}(0,1)$ and $\left(G_{M}^{R}(.)\right)^{\ell}=-R \vee\left(G_{M}(.)\right)^{\ell} \wedge R$, for $\ell \in\{1, \ldots, d\}$.
The terminal condition is given by $u^{\pi}\left(t_{n}, x\right)=g(x)$ and $v^{\pi}\left(t_{n}, x\right)=0$.
Remark 4.1. Observe that the above scheme is implicit in $u^{\pi}\left(t_{i}, x\right)$. We then use a Picard iteration to compute this term in practice, the error is very small because $h K_{y} \ll 1$ and we do not study it here.

Theorem 4.1. For all $r>0$ and $\eta>0$, the following holds

$$
\left|Y_{0}-\widehat{Y}_{0}^{\pi}\right| \leqslant C_{\eta} h^{\frac{1}{2}-\eta}+C_{r} n(\kappa \delta)^{-r}+C\left(\delta n+n^{\alpha+\frac{1}{2}} M^{-\frac{1}{d}}\right)
$$

From the above theorem we straightforwardly deduce the following corollary.
Corollary 4.1. Setting $\delta=n^{-\frac{3}{2}}, \kappa=n^{\frac{3}{2}+\tilde{\eta}}$ and $M=n^{(1+\alpha) d}$, we obtain

$$
\left|Y_{0}-\widehat{Y}_{0}^{\pi}\right| \leqslant C_{\alpha, \eta, \tilde{\eta}} h^{\frac{1}{2}-\eta}
$$

for all $\eta>0, \tilde{\eta}>0$ and $0<\alpha<\frac{1}{2}$.

## Proof of Theorem 4.1

1. Error on Y: We first observe that

$$
\left|Y_{0}-\widehat{Y}_{0}^{\pi}\right| \leqslant\left|Y_{0}-Y_{0}^{\pi}\right|+\left|Y_{0}^{\pi}-\widehat{Y}_{0}^{\pi}\right|
$$

Applying Theorem 1.1, we obtain

$$
\left|Y_{0}-\widehat{Y}_{0}^{\pi}\right| \leqslant C_{\eta} h^{\frac{1}{2}-\eta}+\left|Y_{0}^{\pi}-\widehat{Y}_{0}^{\pi}\right|
$$

For the second term, we simply rewrite $\left(\widehat{Y}^{\pi}, \widehat{Z}^{\pi}\right)$ as a perturbation of the scheme given in Definition 1.1, namely

$$
\widehat{Y}_{i}^{\pi}=\mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi}+h_{i} f_{N}\left(X_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi} H_{i}^{R}\right]\right)+\zeta_{i}^{Y}\right]
$$

with

$$
\zeta_{i}^{Y}:=h_{i}\left(f_{N}\left(\widehat{X}_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \widehat{Z}_{i}^{\pi}\right)-f_{N}\left(X_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi} H_{i}^{R}\right]\right)\right)
$$

Applying Proposition 2.7 for the two schemes and the Corollary 2.1, we obtain for some $q>1$,

$$
\begin{equation*}
\left|Y_{0}^{\pi}-\widehat{Y}_{0}^{\pi}\right| \leqslant C\left(\mathbb{E}\left[\left|X_{n}^{\pi}-\widehat{X}_{n}^{\pi}\right|^{q}\right]^{\frac{1}{q}}+\mathbb{E}\left[\left(\sum_{i=0}^{n-1}\left|\zeta_{i}^{Y, x}\right|\right)^{q}\right]^{\frac{1}{q}}+\mathbb{E}\left[\left(\sum_{i=0}^{n-1}\left|\zeta_{i}^{Y, z}\right|\right)^{q}\right]^{\frac{1}{q}}\right) \tag{4.6}
\end{equation*}
$$

where

$$
\begin{aligned}
\zeta_{i}^{Y, x} & :=h_{i}\left(f_{N}\left(\widehat{X}_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \widehat{Z}_{i}^{\pi}\right)-f_{N}\left(X_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \widehat{Z}_{i}^{\pi}\right)\right) \\
\zeta_{i}^{Y, z} & :=h_{i}\left(f_{N}\left(X_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \widehat{Z}_{i}^{\pi}\right)-f_{N}\left(X_{i}^{\pi}, \widehat{Y}_{i}^{\pi}, \mathbb{E}_{t_{i}}\left[\widehat{Y}_{i+1}^{\pi} H_{i}^{R}\right]\right)\right) .
\end{aligned}
$$

We easily compute that

$$
\begin{equation*}
\mathbb{E}\left[\left(\sum_{i=0}^{n-1}\left|\zeta_{i}^{Y, x}\right|\right)^{q}\right]^{\frac{1}{q}} \leqslant C \mathbb{E}\left[\sup _{i}\left|X_{i}^{\pi}-\widehat{X}_{i}^{\pi}\right|^{q}\right]^{\frac{1}{q}} \tag{4.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbb{E}\left[\left(\sum_{i=0}^{n-1}\left|\zeta_{i}^{Y, z}\right|\right)^{q}\right]^{\frac{1}{q}} \leqslant C n^{\alpha} \sup _{i} \mathbb{E}\left[\left|H_{i}^{R}-\widehat{H}_{i}^{R}\right|^{q}\right]^{\frac{1}{q}} \tag{4.8}
\end{equation*}
$$

From (4.1), it follows that

$$
\mathbb{E}\left[\left|H_{i}^{R}-\widehat{H}_{i}^{R}\right|^{q}\right]^{\frac{1}{q}} \leqslant C n^{\frac{1}{2}} M^{-\frac{1}{d}}
$$

Combining the above estimations with (4.6), we obtain

$$
\begin{equation*}
\left|Y_{0}^{\pi}-\widehat{Y}_{0}^{\pi}\right| \leqslant C\left(\mathbb{E}\left[\sup _{i}\left|X_{i}^{\pi}-\widehat{X}_{i}^{\pi}\right|^{q}\right]^{\frac{1}{q}}+n^{\alpha+\frac{1}{2}} M^{-\frac{1}{d}}\right) \tag{4.9}
\end{equation*}
$$

2. We now study the first term in the right hand side of the above equation, namely the error on the forward component.
Let $\tilde{X}^{\pi}$ denote the Euler scheme for $X$ where we replace $\Delta W_{i}$ by $\Delta \widehat{W}_{i}$, i.e.

$$
\tilde{X}_{i+1}^{\pi}=\tilde{X}_{i}^{\pi}+h_{i} b\left(\tilde{X}_{i}^{\pi}\right)+\sigma\left(\tilde{X}_{i}^{\pi}\right) \Delta \widehat{W}_{i}
$$

We then split the error into two terms:

$$
\mathbb{E}\left[\sup _{i}\left|X_{i}^{\pi}-\widehat{X}_{i}^{\pi}\right|^{q}\right]^{\frac{1}{q}} \leqslant C\left(\mathbb{E}\left[\sup _{i}\left|X_{i}^{\pi}-\tilde{X}_{i}^{\pi}\right|^{2 q}\right]^{\frac{1}{2 q}}+\mathbb{E}\left[\sup _{i}\left|\tilde{X}_{i}^{\pi}-\widehat{X}_{i}^{\pi}\right|^{2 q}\right]^{\frac{1}{2 q}}\right)
$$

2.a We now write $\tilde{X}^{\pi}$ as a pertubation of $X^{\pi}$, namely:

$$
\tilde{X}_{i+1}^{\pi}=\tilde{X}_{i}^{\pi}+h_{i} b\left(\tilde{X}_{i}^{\pi}\right)+\sigma\left(\tilde{X}_{i}^{\pi}\right) \Delta W_{i}+\zeta_{i}^{\tilde{X}}
$$

with

$$
\zeta_{i}^{\tilde{X}}=\sigma\left(\tilde{X}_{i}^{\pi}\right)\left(\Delta \widehat{W}_{i}-\Delta W_{i}\right)
$$

Applying Lemma A.1, we obtain

$$
\mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|X_{j}^{\pi}-\tilde{X}_{j}^{\pi}\right|^{2 q}\right]^{1 / 2 q} \leqslant C \mathbb{E}\left[\left(\sum_{j=0}^{n}\left|\zeta_{j}^{\tilde{X}}\right|\right)^{2 q}\right]^{1 / 2 q}
$$

Moreover, we compute

$$
\mathbb{E}\left[\left(\sum_{j=0}^{n}\left|\zeta_{j}^{\tilde{X}}\right|\right)^{2 q}\right] \leqslant n^{2 q-1} \sum_{j=0}^{n} \mathbb{E}\left[\left|\zeta_{j}^{\tilde{X}}\right|^{2 q}\right] \leqslant C n^{q} M^{-\frac{2 q}{d}}
$$

since

$$
\begin{aligned}
\mathbb{E}\left[\left|\zeta_{j}^{\tilde{X}}\right|^{2 q}\right] & \leqslant C \mathbb{E}\left[\left(1+\left|\tilde{X}_{j}^{\pi}\right|\right)^{4 q}\right]^{\frac{1}{2}} \mathbb{E}\left[\left|\Delta \widehat{W}_{j}-\Delta W_{j}\right|^{4 q}\right]^{\frac{1}{2}} \\
& \leqslant C h^{q} M^{-\frac{2 q}{d}}
\end{aligned}
$$

Combining the above estimation, we obtain

$$
\mathbb{E}\left[\sup _{i}\left|X_{i}^{\pi}-\tilde{X}_{i}^{\pi}\right|^{2 q}\right]^{\frac{1}{2 q}} \leqslant C \sqrt{n} M^{-\frac{1}{d}}
$$

2.b We now write $\widehat{X}^{\pi}$ as a pertubation of $\tilde{X}^{\pi}$, namely:

$$
\widehat{X}_{i+1}^{\pi}=\widehat{X}_{i}^{\pi}+h_{i} b\left(\widehat{X}_{i}^{\pi}\right)+\sigma\left(\widehat{X}_{i}^{\pi}\right) \Delta \widehat{W}_{i}+\zeta_{i}^{\widehat{X}}
$$

with

$$
\zeta_{i}^{\widehat{X}}=\Pi_{X_{0}}\left[\Gamma_{i+1}\right]-\Gamma_{i+1} \quad \text { and } \quad \Gamma_{i+1}:=\widehat{X}_{i}^{\pi}+h_{i} b\left(\widehat{X}_{i}^{\pi}\right)+\sigma\left(\widehat{X}_{i}^{\pi}\right) \Delta \widehat{W}_{i} .
$$

Applying Lemma A.1, we get

$$
\mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|\tilde{X}_{j}^{\pi}-\widehat{X}_{j}^{\pi}\right|^{2 q}\right]^{1 / 2 q} \leqslant C \mathbb{E}\left[\left(\sum_{j=0}^{n}\left|\zeta_{j}^{\widehat{X}}\right|\right)^{2 q}\right]^{1 / 2 q}
$$

From the definition of the projection operator, we have that, for all $r>1$,

$$
\left|\zeta_{j}^{\widehat{X}}\right| \leqslant \delta+\left|\Gamma_{i+1}\right| \mathbf{1}_{\left\{\left|\Gamma_{i+1}\right|>\kappa \delta\right\}} \leqslant \delta+\frac{\left|\Gamma_{i+1}\right|^{r+1}}{(\kappa \delta)^{r}}
$$

which leads to

$$
\mathbb{E}\left[\sup _{0 \leqslant j \leqslant n}\left|\tilde{X}_{j}^{\pi}-\widehat{X}_{j}^{\pi}\right|^{2 q}\right]^{1 / 2 q} \leqslant C n\left(\delta+\frac{1}{(\kappa \delta)^{r}} \mathbb{E}\left[\sup _{i}\left|\Gamma_{i}\right|^{2 q(r+1)}\right]^{\frac{1}{2 q}}\right)
$$

The proof for this step is concluded observing that $\mathbb{E}\left[\sup _{i}\left|\Gamma_{i}\right|^{2 q(r+1)}\right]^{\frac{1}{2 q}} \leqslant C_{r}$.
3. The proof is concluded by inserting the above estimate in (4.9).

### 4.2 A numerical example

We illustrate in this part the convergence of the algorithm given in Definition 4.1. To this end, we consider the following quadratic Markovian BSDE with $d=1$ :

$$
\left\{\begin{array}{rl}
X_{t} & =X_{0}+\int_{0}^{t} \nu X_{s} \mathrm{~d} W_{s} \\
Y_{t} & =g\left(X_{1}\right)+\int_{t}^{1} \frac{a}{2} Z_{s}^{2} \mathrm{~d} s-\int_{t}^{1} Z_{s} \mathrm{~d} W_{s}
\end{array} \quad, \quad 0 \leqslant t \leqslant 1,\right.
$$

where $\nu, a$ and $X_{0}$ are given real positive parameters and $g$ is a bounded Lipschitz function.

Applying Ito's formula, one can show that the solution is given by

$$
Y_{t}=\frac{1}{a} \log \left(\mathbb{E}_{t}\left[\exp \left(a g\left(X_{1}\right)\right)\right]\right), \quad t \leqslant 1 .
$$

For any given $g, \nu$ and $a$, it is possible to estimate the solution $Y_{0}$ at time 0 using an approximation of the Gaussian distribution at time $T=1$, since $X_{1}=X_{0} e^{-\frac{\nu^{2}}{2}+\nu W_{1}}$.

### 4.2.1 Convergence

For our numerical illustration, $g$ is given by

$$
g: x \mapsto 3 \sin ^{2}(x),
$$

and we set $\nu=1, X_{0}=1$.
Given $n$ the number of time steps in the approximation grid, we consider

$$
N(n)=n^{\frac{1}{4}} \text { and } R(n)=\log (n),
$$

recalling (1.8). We will refer to the scheme given in Definition 4.1 with this set of parameters ( $N, R$ ) as the 'optimal truncation' scheme.

The following graph show the convergence of the algorithm for time step varying from 5 to 50 . In the simulation, we fixed $M$ to be large enough ( $M=100$ ), so that the error in the space discretization can be neglected in the analysis.

The expected convergence rate should be between 0.5 , that is to say the minimal rate proved in this paper, and 1 the general optimal rate for the Euler scheme, see e.g. [20, 10]. We found a rate 0.7 which then seems reasonable. Note that all the convergence rate estimated below are also in the predicted range.

Figure 1: Empirical convergence of the scheme given in Definition 4.1

### 4.2.2 Truncature

In this section, we illustrate qualitatively the importance of the truncation procedure. When $a=1$, we observed in the last section that the scheme given in Definition 4.1 is converging nicely. It appears that for this specific choice of parameters $\nu, g$ and $a$, the usual BTZ-scheme, referred to as 'no truncation' scheme, is also converging, as shown in Figure 2.
But, when $a$ becomes bigger, the usual BTZ-scheme becomes unstable. On Figure 3, we plot, for $a=4$ and $a=5$, the usual BTZ-scheme ('no truncation'), the 'optimal truncation' scheme and the scheme given in Definition 4.1 with an a priori fixed truncation $R$, referred to as the 'wrong truncation' scheme.
We first observe that the 'wrong truncation' scheme is stable but not converging, as expected.
The case of the usual BTZ-scheme is more interesting. First, let us mention that we plot a truncated error which explains the flat alignment of some points. looking carefully at

Figure 2: Empirical convergence of the optimal truncation scheme and the BTZ-scheme
both graphs, we see that some points seems to be missing. This is because the numerical algorithm failed to return a real number ( $N a N$ value instead). Both graphs show that the scheme is not stable. But in the case $a=4$, it manages to be stabilised when the number of time step is big enough ( $h$ small enough). We are not able to explain yet this behavior. The detailed study of the numerical stability (or instability) of the BTZ-scheme is outside the scope of this paper. These questions will be addressed in a forthcoming paper.
Finally, we observe that the 'optimal truncation' scheme is converging nicely, even for these large values of $a$.

Figure 3: Comparison of schemes' convergence

## A Appendix

## A. 1 Proof of Proposition 3.2

We have to study the quantity

$$
A:=\mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\top}}\left[\sum_{j=i}^{n-1}\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right],
$$

and show that $A \leqslant h^{p(1+\eta)}$. This is a slight modification of the well-known Zhang path regularity theorem, the main difference coming from the change of probability. To retrieve this result, we will mainly adapt the usual proof. In particular, we need to use a classical representation for $Z$ based on the differentiability of $\left(X, Y^{N}, Z^{N}\right)$ with respect to $x$ (for the proof see e.g. $[26,5]$ ).

Proposition A.1. Suppose that $b, \sigma, f$ and $g$ are twice differentiable functions with respect to $x, y$, and $z$. Then for all $r \geqslant 2$ the process $\left(X, Y^{N}, Z^{N}\right)$, solution of the
system (1.1)-(2.1) belongs to $\mathcal{S}^{r} \times \mathcal{S}^{r} \times \mathcal{M}^{r}$ with norms bounded by constants that do not depend on $N$. Moreover, $\left(X, Y^{N}, Z^{N}\right)$ is continuously differentiable with respect to the initial point $x$ of the forward component. The derivative of $X$ satisfies

$$
\nabla X_{t}=I+\int_{0}^{t} \nabla b\left(X_{s}\right) \nabla X_{s} d s+\int_{0}^{t} \nabla \sigma\left(X_{s}\right) \nabla X_{s} d W_{s}
$$

while the derivatives of $\left(Y^{N}, Z^{N}\right)$ satisfy the linear BSDE

$$
\begin{aligned}
\nabla Y_{t}^{N}= & \nabla g\left(X_{T}\right) \nabla X_{T}-\int_{t}^{T} \nabla Z_{s}^{N} d W_{s}+\int_{t}^{T} \nabla_{x} f_{N}\left(s, X_{s}, Y_{s}^{N}, Z_{s}^{N}\right) \nabla X_{s} \\
& +\nabla_{y} f_{N}\left(s, X_{s}, Y_{s}^{N}, Z_{s}^{N}\right) \nabla Y_{s}^{N}+\nabla_{z} f_{N}\left(s, X_{s}, Y_{s}^{N}, Z_{s}^{N}\right) \nabla Z_{s}^{N} d s
\end{aligned}
$$

The process $\left(\nabla X, \nabla Y^{N}, \nabla Z^{N}\right)$ belongs to $\mathcal{S}^{r} \times \mathcal{S}^{r} \times \mathcal{M}^{r}$ with norms bounded by constants that do not depend on $N$. Finally we have a continuous representation of $Z^{N}$ given by

$$
Z_{t}^{N}=\nabla Y_{t}^{N}\left(\nabla X_{t}\right)^{-1} \sigma\left(X_{t}\right)
$$

We assume that $b, \sigma, f, \rho_{N}$ and $g$ are sufficiently smooth functions and thus we can apply Proposition A.1. When this is not the case, the result follows from standard approximation and stability results for quadratic BSDEs.
Working with the continuous version of $Z^{N}$ we can consider $Z_{t_{i}}^{N}$ for all $0 \leqslant i<n$. We have,

$$
\begin{aligned}
\left|Z_{s}^{N}-\bar{Z}_{j}^{N}\right|^{2} & \leqslant 2\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2}+2\left|Z_{t_{j}}^{N}-\bar{Z}_{j}^{N}\right|^{2} \\
& \leqslant 2\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2}+2 \frac{1}{h_{j}} \mathbb{E}_{t_{j}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{u}^{N}-Z_{t_{j}}^{N}\right|^{2} d u\right] \\
& \leqslant 2\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2}+\frac{2}{\varepsilon} \frac{1}{h_{j}} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{u}^{N}-Z_{t_{j}}^{N}\right|^{2} d u\right]
\end{aligned}
$$

because $1 /\left|1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}\right| \leqslant 1 / \varepsilon$ thanks to assumption $(\mathbf{H} 3)$. Inserting the previous estimate into the quantity $A$ we get, by applying Hölder inequality and classical properties
of the conditional expectation,

$$
\begin{align*}
A \leqslant & C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2} d s\right)^{1+\eta}\right]^{p}\right] \\
& +C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left(\mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2} d s\right]\right)^{1+\eta}\right]^{p}\right] \\
\leqslant & C_{\eta, p} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left(\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2} d s\right)^{1+\eta}\right]\right]^{p}\right] \\
\leqslant & C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right|^{2(1+\eta)} d s\right]\right]^{p}\right] . \tag{A.1}
\end{align*}
$$

Then we use the continuous representation of $Z^{N}$ given by Proposition A.1.

$$
\begin{aligned}
\left|Z_{s}^{N}-Z_{t_{j}}^{N}\right| \leqslant & \left|\nabla Y_{s}^{N}\left(\nabla X_{s}\right)^{-1}\left(\sigma\left(X_{s}\right)-\sigma\left(X_{t_{j}}\right)\right)\right| \\
& +\left|\nabla Y_{s}^{N}\left(\left(\nabla X_{s}\right)^{-1}-\left(\nabla X_{t_{j}}\right)^{-1}\right) \sigma\left(X_{t_{j}}\right)\right| \\
& +\left|\left(\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}\right)\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right| \\
:= & B_{j}^{1}+B_{j}^{2}+B_{j}^{3} .
\end{aligned}
$$

Then, inserting this into (A.1), we have

$$
\begin{aligned}
A \leqslant & C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{\mathbb{Q}_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{\mathbb{Q}_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|B_{j}^{1}\right|^{2(1+\eta)} d s\right]\right]^{p}\right] \\
& \left.+C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|B_{j}^{2}\right|^{2(1+\eta)} d s\right]\right]^{p}\right]\right] \\
& \left.+C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|B_{j}^{3}\right|^{2(1+\eta)} d s\right]\right]^{p}\right]\right] \\
:= & A_{1}+A_{2}+A_{3} .
\end{aligned}
$$

We now work on the first term. Thanks to Proposition 2.11 we know that $d \mathbb{Q}^{\pi} / d \mathbb{P}$ satisfies the reverse Hölder inequality and then

$$
\begin{aligned}
A_{1} & \leqslant C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=0}^{n-1} \int_{t_{j}}^{t_{j+1}}\left|B_{j}^{1}\right|^{2(1+\eta)} d s\right]^{p}\right] \\
& \leqslant C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}\left[\left(\sum_{j=0}^{n-1} \int_{t_{j}}^{t_{j+1}}\left|B_{j}^{1}\right|^{2(1+\eta)} d s\right)^{q^{*}}\right]^{2 p}\right]^{1 /\left(2 q^{*}\right)} .
\end{aligned}
$$

Applying Doob maximal inequality yields

$$
A_{1} \leqslant C_{\eta, p} h^{p \eta_{\mathbb{E}}}\left[\left(\sum_{j=0}^{n-1} \int_{t_{j}}^{t_{j+1}}\left|B_{j}^{1}\right|^{2(1+\eta)} d s\right)^{2 p q^{*}}\right]^{1 /\left(2 q^{*}\right)}
$$

and, thanks to Hölder inequality and a convexity inequality, we get

$$
A_{1} \leqslant C_{\eta, p} h^{p \eta}\left(\sum_{j=0}^{n-1} \int_{t_{j}}^{t_{j+1}} \mathbb{E}\left[\left|B_{j}^{1}\right|^{4 p q^{*}(1+\eta)}\right] d s\right)^{1 /\left(2 q^{*}\right)}
$$

Thanks to the Lipschitz regularity assumption on $\sigma$, Proposition A.1, a classical estimate on $(\nabla X)^{-1}$ and the estimate (3.11), we obtain

$$
\begin{aligned}
& \mathbb{E}\left[\left|B_{j}^{1}\right|^{4 p q^{*}(1+\eta)}\right] \\
\leqslant & \mathbb{E}\left[\sup _{0 \leqslant u \leqslant T}\left|\nabla Y_{u}^{N}\left(\nabla X_{u}\right)^{-1}\right|^{4 p q^{*}(1+\eta)}\left(\sup _{t_{j} \leqslant u \leqslant t_{j+1}}\left|X_{u}-X_{t_{j}}\right|\right)^{4 p q^{*}(1+\eta)}\right] \\
\leqslant & \mathbb{E}\left[\sup _{0 \leqslant u \leqslant T}\left|\nabla Y_{u}^{N}\left(\nabla X_{u}\right)^{-1}\right|^{4 p q^{*}(1+\eta)}\left(\sup _{t_{j} \leqslant u \leqslant t_{j+1}}\left|X_{u}-X_{t_{j}}\right|\right)^{4 p q^{*}(1+\eta)}\right] \\
\leqslant & \mathbb{E}\left[\sup _{0 \leqslant u \leqslant T}\left|\nabla Y_{u}^{N}\left(\nabla X_{u}\right)^{-1}\right|^{8 p q^{*}(1+\eta)}\right]^{1 / 2} \mathbb{E}\left[\sup _{t_{j} \leqslant u \leqslant t_{j+1}}\left|X_{u}-X_{t_{j}}\right|^{8 p q^{*}(1+\eta)}\right]^{1 / 2} \\
\leqslant & C_{\eta, p} h^{2 p q^{*}(1+\eta)} .
\end{aligned}
$$

Finally we have

$$
A_{1} \leqslant C_{\eta, p} h^{p(1+2 \eta)}
$$

with a constant $C$ that does not depend on $N$. By the same type of arguments we can easily show that

$$
A_{2} \leqslant C_{\eta, p} h^{p(1+2 \eta)}
$$

To handle the last term $A_{3}$ one needs to proceed with more care. Since $\left|1+h_{j} H_{j}^{R} \gamma_{j}^{N, n}\right| \leqslant$
$1 / \varepsilon$, we have that

$$
\begin{aligned}
& A_{3} \\
& \leqslant C_{\eta, p} h^{p \eta} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\int_{t_{j}}^{t_{j+1}}\left|\left(\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}\right)\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)} d s\right]\right]^{p}\right] \\
& \leqslant \\
& \quad C_{\eta, p} h^{p \eta} \mathbb{E}\left[\operatorname { s u p } _ { 0 \leqslant i \leqslant n - 1 } \mathbb { E } _ { t _ { i } } ^ { \mathbb { Q } ^ { \pi } } \left[\sum_{j=i}^{n-1}\left|\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)}\right.\right. \\
& \left.\left.\quad \times \int_{t_{j}}^{t_{j+1}} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left|\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}\right|^{2(1+\eta)}\right] d s\right]^{p}\right] \\
& \leqslant \\
& \quad C_{\eta, p} h^{p \eta} \mathbb{E}\left[\operatorname { s u p } _ { 0 \leqslant i \leqslant n - 1 } \mathbb { E } _ { t _ { i } } ^ { \mathbb { Q } ^ { \pi } } \left[\sum_{j=i}^{n-1}\left|\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)}\right.\right. \\
& \left.\left.\quad \times \int_{t_{j}}^{t_{j+1}} \mathbb{E}_{t_{j}}\left[\left|\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}\right|^{2(1+\eta)}\right] d s\right]^{p}\right] .
\end{aligned}
$$

Writing the BSDE for the difference $\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}$ for $t_{j} \leqslant s \leqslant t_{j+1}$ and using the conditional Burkholder Davis Gundy inequality, we have, with $\Theta_{r}^{N}:=\left(X_{r}, Y_{r}^{N}, Z_{r}^{N}\right)$,

$$
\begin{aligned}
& \mathbb{E}_{t_{j}}\left[\left|\nabla Y_{s}^{N}-\nabla Y_{t_{j}}^{N}\right|^{2(1+\eta)}\right] \\
\leqslant & C_{\eta} \mathbb{E}_{t_{j}}\left[\left|\int_{t_{j}}^{s}\left\langle\nabla f_{N}\left(r, \Theta_{r}^{N}\right), \nabla \Theta_{r}^{N}\right\rangle d r\right|^{2(1+\eta)}+\left|\int_{t_{j}}^{s} \nabla Z_{r}^{N} d W_{r}\right|^{2(1+\eta)}\right] \\
\leqslant & C_{\eta} \mathbb{E}_{t_{j}}\left[\left(\int_{t_{j}}^{t_{j+1}}\left|\nabla f_{N}\left(r, \Theta_{r}^{N}\right)\right|\left|\nabla \Theta_{r}^{N}\right| d r\right)^{2(1+\eta)}+\left(\int_{t_{j}}^{t_{j+1}}\left|\nabla Z_{r}^{N}\right|^{2} d r\right)^{1+\eta}\right] .
\end{aligned}
$$

For the reader's convenience, we define the sum of the integrals inside the conditional expectation by $I_{\left[t_{j}, t_{j+1}\right]}$. Inserting the previous inequality into our last bound on $A_{3}$ and
using again the fact that $\left|1+h_{j} H_{j} \gamma_{j}^{N, n}\right| \leqslant 1 / \varepsilon$, we obtain

$$
\begin{aligned}
A_{3} & \leqslant C_{\eta, p} h^{p(1+\eta)} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}\left[\left|\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)} I_{\left[t_{j}, t_{j+1}\right]}\right]\right]^{p}\right] \\
& \leqslant C_{\eta, p} h^{p(1+\eta)} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1} \mathbb{E}_{t_{j}}^{\mathbb{Q}^{\pi}}\left[\left|\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)} I_{\left[t_{j}, t_{j+1}\right]}\right]\right]^{p}\right] \\
\leqslant & { }_{\eta, p} C h^{p(1+\eta)} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sum_{j=i}^{n-1}\left|\left(\nabla X_{t_{j}}\right)^{-1} \sigma\left(X_{t_{j}}\right)\right|^{2(1+\eta)} I_{\left[t_{j}, t_{j+1}\right]}\right]^{p}\right] \\
\leqslant & C_{\eta, p} h^{p(1+\eta)} \mathbb{E}\left[\sup _{0 \leqslant i \leqslant n-1} \mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}\left[\sup _{0 \leqslant t \leqslant T}\left|\left(\nabla X_{t}\right)^{-1} \sigma\left(X_{t}\right)\right|^{2(1+\eta)} \sum_{j=i}^{n-1} I_{\left[t_{j}, t_{j+1}\right]}\right]^{p}\right] \\
\leqslant & C_{\eta, p} h^{p(1+\eta)} \mathbb{E}\left[\operatorname { s u p } _ { 0 \leqslant i \leqslant n - 1 } \mathbb { E } _ { t _ { i } } ^ { \mathbb { Q } ^ { \pi } } \left[\sup _{0 \leqslant t \leqslant T}\left|\left(\nabla X_{t}\right)^{-1} \sigma\left(X_{t}\right)\right|^{2(1+\eta)}\right.\right. \\
& \left.\left.\times\left\{\left(\int_{0}^{T}\left|\nabla f_{N}\left(r, \Theta_{r}\right)\right|\left|\nabla \Theta_{r}\right| d r\right)^{2(1+\eta)}+\left(\int_{0}^{T}\left|\nabla Z_{r}^{N}\right|^{2} d r\right)^{1+\eta}\right\}\right]^{p}\right]
\end{aligned}
$$

Once again, thanks to Proposition 2.11 we know that $d \mathbb{Q}^{\pi} / d \mathbb{P}$ satisfies a reverse Hölder inequality and so we can get rid of the conditional expectation $\mathbb{E}_{t_{i}}^{\mathbb{Q}^{\pi}}$. Moreover we can get rid of the supremum by using the Doob maximal inequality. Finally, combining growth assumptions on $f$ (true for $f_{N}$ ), and estimates given by Proposition A.1, we obtain

$$
A_{3} \leqslant C_{\eta, p} h^{p(1+\eta)}
$$

Collecting now the estimates on $A_{1}, A_{2}$ and $A_{3}$ we obtain that $A \leqslant C_{\eta, p} h^{p(1+\eta)}$. Since this estimate is true for all $\eta>0$, the result is proved by taking $\eta:=\frac{\tilde{\eta}}{1-\tilde{\eta}}$.

## A. 2 Stability result for the Euler Scheme of an SDE

Lemma A.1. Let us consider $q \geqslant 1$ and two forward schemes $\left(X_{i}\right)_{0 \leqslant i \leqslant n}$ and $\left(\tilde{X}_{i}\right)_{0 \leqslant i \leqslant n}$ given by

$$
\begin{aligned}
X_{i+1} & =X_{i}+h_{i} b\left(X_{i}\right)+\sigma\left(X_{i}\right) \sqrt{h_{i}} N_{i} \\
\tilde{X}_{i+1} & =\tilde{X}_{i}+h_{i} b\left(\tilde{X}_{i}\right)+\sigma\left(\tilde{X}_{i}\right) \sqrt{h_{i}} N_{i}+\zeta_{i}
\end{aligned}
$$

with $\left(\zeta_{i}\right)_{0 \leqslant i<n}$ some random variables in $L^{2 q}$ and $\left(N_{i}\right)_{0 \leqslant i<n}$ some independant and centered random variables in $L^{2 q}$ such that $N_{i}$ is $\mathcal{F}_{t_{i}}$ measurable for all $0 \leqslant i<n$ and $\mathbb{E}_{t_{i}}\left[N_{i}^{2}\right]=\mathbb{E}\left[N_{i}^{2}\right] \leqslant C$ with $C$ that does not depend on $n$. Then, we have the following
stability result:

$$
\mathbb{E}\left[\sup _{0 \leqslant k \leqslant n}\left|X_{k}-\tilde{X}_{k}\right|^{2 q}\right] \leqslant C_{q}\left|X_{0}-\tilde{X}_{0}\right|^{2 q}+C_{q} \mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}\right|\right)^{2 q}\right]
$$

Proof. By considering the difference between the two schemes, we have

$$
X_{i}-\tilde{X}_{i}=X_{0}-\tilde{X}_{0}+\sum_{j=0}^{i-1} h_{j}\left[b\left(X_{j}\right)-b\left(\tilde{X}_{j}\right)\right]+\sum_{j=0}^{i-1} \sqrt{h_{j}}\left[\sigma\left(X_{j}\right)-\sigma\left(\tilde{X}_{j}\right)\right] N_{j}+\sum_{j=0}^{i-1} \zeta_{j}
$$

and

$$
\begin{aligned}
\mathbb{E}\left[\sup _{0 \leqslant k \leqslant i}\left|X_{k}-\tilde{X}_{k}\right|^{2 q}\right] \leqslant & C_{q}\left|X_{0}-\tilde{X}_{0}\right|^{2 q}+C_{q} \mathbb{E}\left[\left(\sum_{j=0}^{i-1}\left|\zeta_{j}\right|\right)^{2 q}\right] \\
& +C_{q} \mathbb{E}\left[\sup _{0 \leqslant k \leqslant i}\left|\sum_{j=0}^{k-1} h_{j}\left[b\left(X_{j}\right)-b\left(\tilde{X}_{j}\right)\right]\right|^{2 q}\right] \\
& +C_{q} \mathbb{E}\left[\sup _{0 \leqslant k \leqslant i}\left|\sum_{j=0}^{k-1} \sqrt{h_{j}}\left[\sigma\left(X_{j}\right)-\sigma\left(\tilde{X}_{j}\right)\right] N_{j}\right|^{2 q}\right]
\end{aligned}
$$

Recalling that $b$ and $\sigma$ are Lipschitz and by using a convexity inequality and the Burkholder-Davis-Gundy inequality, we obtain

$$
\begin{aligned}
\mathbb{E}\left[\sup _{0 \leqslant k \leqslant i}\left|X_{k}-\tilde{X}_{k}\right|^{2 q}\right] \leqslant & C_{q}\left|X_{0}-\tilde{X}_{0}\right|^{2 q}+C_{q} \mathbb{E}\left[\left(\sum_{j=0}^{i-1}\left|\zeta_{j}\right|\right)^{2 q}\right] \\
& +C_{q} \sum_{j=0}^{i-1} h_{j} \mathbb{E}\left[\sup _{0 \leqslant k \leqslant j}\left|X_{k}-\tilde{X}_{k}\right|^{2 q}\right] \\
& +C_{q} \mathbb{E}\left[\left(\sum_{j=0}^{i-1} h_{j}\left|X_{j}-\tilde{X}_{j}\right|^{2}\right)^{q}\right] \\
\leqslant & C_{q}\left|X_{0}-\tilde{X}_{0}\right|^{2 q}+C_{q} \mathbb{E}\left[\left(\sum_{j=0}^{n-1}\left|\zeta_{j}\right|\right)^{2 q}\right] \\
& +C_{q} \sum_{j=0}^{i-1} h_{j} \mathbb{E}\left[\sup _{0 \leqslant k \leqslant j}\left|X_{k}-\tilde{X}_{k}\right|^{2 q}\right] .
\end{aligned}
$$

The proof is concluding by a direct application of the discrete Gronwall's Lemma.

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[^1]:    ${ }^{1}$ Bouchard-Touzi-Zhang, the first authors to consider this scheme, see $[41,4]$.

[^2]:    ${ }^{2}$ The grids can be dowloaded from the website: http://www.quantize.maths-fi.com/.

