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# A lower bound on the barrier parameter of barriers on convex cones 

Roland Hildebrand *

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#### Abstract

Let $K \subset \mathbb{R}^{n}$ be a regular convex cone, let $e_{1}, \ldots, e_{n} \in \partial K$ be linearly independent points on the boundary of a compact affine section of the cone, and let $x^{*} \in K^{o}$ be a point in the relative interior of this section. For $k=1, \ldots, n$, let $l_{k}$ be the line through the points $e_{k}$ and $x^{*}$, let $y_{k}$ be the intersection point of $l_{k}$ with $\partial K$ opposite to $e_{k}$, and let $z_{k}$ be the intersection point of $l_{k}$ with the linear subspace spanned by all points $e_{l}, l=1, \ldots, n$ except $e_{k}$. We give a lower bound on the barrier parameter $\nu$ of logarithmically homogeneous self-concordant barriers $F: K^{o} \rightarrow \mathbb{R}$ on $K$ in terms of the projective cross-ratios $q_{k}=\left(e_{k}, x^{*} ; y_{k}, z_{k}\right)$. Previously known lower bounds by Nesterov and Nemirovski can be obtained from our result as a special case. As an application, we construct an optimal barrier for the epigraph of the $\|\cdot\|_{\infty}$-norm in $\mathbb{R}^{n}$ and compute lower bounds on the barrier parameter for the power cone and the epigraph of the $\|\cdot\|_{p}$-norm in $\mathbb{R}^{2}$.


## 1 Introduction

In modern convex optimization, interior point methods are the primary tool to solve conic programs. A central role in solution algorithms for conic programs over some regular (with nonempty interior, containing no lines) convex cone $K$ is assigned to a smooth real-valued convex function $F: K^{o} \rightarrow \mathbb{R}$ on the interior of the cone, the barrier. In order to be useful for optimization, the barrier has to satisfy certain properties [4, Section 2.3]. The second and third derivative have to satisfy the self-concordance relation

$$
\begin{equation*}
F^{\prime \prime \prime}(x)[h, h, h] \leq 2\left(F^{\prime \prime}(x)[h, h]\right)^{3 / 2} \quad \forall x \in K^{o}, h \in T_{x} K^{o} \tag{1}
\end{equation*}
$$

with $h$ running through the tangent space at $x$. The function $F$ has to tend to infinity as its argument tends to the boundary of the cone,

$$
\begin{equation*}
\lim _{x \rightarrow \partial K} F(x)=+\infty \tag{2}
\end{equation*}
$$

and it has to satisfy the logarithmic homogeneity condition

$$
\begin{equation*}
F(\alpha x)=-\nu \log \alpha+F(x) \quad \forall \alpha>0, x \in K^{o} . \tag{3}
\end{equation*}
$$

A smooth function $F: K^{o} \rightarrow \mathbb{R}$ satisfying conditions $(1,2,3)$ is called a logarithmically homogeneous self-concordant barrier for the cone $K$. The real constant $\nu$ is called the barrier parameter of the barrier $F$.

The lower the barrier parameter of a barrier, the faster are the interior point algorithms based on this barrier. For conic optimization problems over a cone $K$, it is therefore desirable to have barriers on $K$ with a barrier parameter as small as possible. We call a logarithmically homogeneous self-concordant barrier on $K$ optimal if it has the lowest possible barrier parameter.

Optimality of a barrier $F$ is proven by verifying properties $(1,2,3)$ and showing that the barrier parameter $\nu$ of $F$ is equal to a lower bound $\nu_{*}$ on this parameter for the given cone. For general cones, all lower bounds on the barrier parameter which are available today are based on a result of Nesterov

[^0]and Nemirovski [4, Sect. 2.3.4]. Namely, if for some boundary point $z \in \partial K$ of the cone there exists a neighbourhood $U$ of $z$ and affine half-spaces $A_{1}, \ldots, A_{k} \subset \mathbb{R}^{n}$ with $z \in \partial A_{j}, j=1, \ldots, k$, such that the normals to the half-spaces at $z$ are linearly independent and the intersection $U \cap K$ equals the intersection $U \cap A_{1} \cap \cdots \cap A_{k}{ }^{1}$, then a lower bound on the barrier parameter of any self-concordant barrier on $K$ is given by $\nu_{*}=k$. Based on this result, Güler and Tunçel proved that the minimum over the Carathéodory numbers of all points in the interior of $K$ also is a lower bound on the barrier parameter [2, Prop. 4.1]. In this way, the standard barriers for the symmetric cones used in linear, conic quadratic, and semi-definite programming are shown to be optimal. Optimal barriers can be constructed also for general homogeneous cones, with the barrier parameter equal to the rank of the cone [2, Theorem 4.1].

In this contribution, we provide a new lower bound on the barrier parameter of barriers on a general cone (Theorems 4.4, 5.4). For $n$-dimensional cones, this lower bound is contained in the interval $[2, n]$ (Corollary 3.2 and Theorem 5.7). From our result, a slightly stronger bound than that in [4, Sect. 2.3.4] follows as special case (Theorem 6.1). In contrast to the previously known bounds, our results are non-trivial also for "round" cones, i.e., cones with a smooth boundary. The bound is a function of the projective cross-ratio of geometric objects that are constructed from $n$ boundary points of the cone in general position and an interior point. As an application, we compute lower bounds on the barrier parameter for the epigraph of the $\|\cdot\|_{\infty}$-norm (Corollary 6.2), the power cone (Corollary 7.1), and the epigraph of the $\|\cdot\|_{p}$-norm in $\mathbb{R}^{2}$ (Corollary 7.2).

The remainder of the paper is structured as follows. In the next section we introduce the projective cross-ratio and consider some of its elementary properties. In Section 3 we prove an auxiliary result, which essentially applies to 2 -dimensional cones. In Section 4 we deduce the lower bound on the barrier parameter of barriers on general cones and in the subsequent section we investigate its properties. In Section 6 we deduce the bounds in [4, Sect. 2.3.4] from our result, and in the last section we apply our results to the power cone and the epigraph of the $\|\cdot\|_{p}$-norm. Finally, in the appendix we construct an optimal barrier for the epigraph of the $\|\cdot\|_{\infty}$-norm.

## 2 The projective cross-ratio

Let $x_{1}, x_{2}, x_{3}, x_{4} \in \mathbb{R} \cup\{\infty\}$ be four distinct points in the 1-point compactification of the real line. The projective cross-ratio of the quadruple $\left(x_{1}, x_{2}, x_{3}, x_{4}\right)$ is defined as the number

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)=\frac{\left(x_{1}-x_{3}\right)\left(x_{2}-x_{4}\right)}{\left(x_{1}-x_{4}\right)\left(x_{2}-x_{3}\right)} \in \mathbb{R}
$$

where the differences containing the value $\infty$ are cancelled in the event that one of the points in the quadruple is $\infty$. This function can be extended continuously to a ( $\mathbb{R} \cup\{\infty\}$ )-valued function on the set of quadruples of points in $\mathbb{R} \cup\{\infty\}$ of which no three coincide.

The projective cross-ratio is invariant under projective transformations of $\mathbb{R} \cup\{\infty\}$, and can hence also be considered as a $(\mathbb{R} \cup\{\infty\})$-valued function on quadruples of points on the real projective line $\mathbb{R} P^{1}$. Alternatively, it can be considered as a $(\mathbb{R} \cup\{\infty\})$-valued function on quadruples of 1-dimensional linear subspaces of $\mathbb{R}^{2}$, as the set of such subspaces is isomorphic to $\mathbb{R} P^{1}$.

As can be easily checked, the projective cross-ratio possesses the symmetry

$$
\begin{equation*}
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)=\frac{1}{\left(x_{2}, x_{1} ; x_{3}, x_{4}\right)} \tag{4}
\end{equation*}
$$

with the values 0 and $\infty$ being considered as reciprocal.
In the next two sections we consider the projective cross-ratio as defined on quadruples of coplanar lines through the origin, while in the example sections it will be more convenient to consider projective cross-ratios of quadruples of collinear points.

[^1]
## 3 2-dimensional linear sections

In this section we prove an auxiliary result which essentially provides a construction of the optimal barrier on a 2-dimensional convex cone under the condition that the direction of the gradient of the barrier at some interior point of the cone is fixed to some value.

Let $K \subset \mathbb{R}^{n}, n \geq 2$, be a regular convex cone, $x^{*} \in K^{o}$ a point in the interior of $K, l$ a line containing $x^{*}$ and intersecting the boundary $\partial K$ of the cone in the points $e, y$. Denote by $L$ the 2dimensional linear hull of $l$ and by $l_{x^{*}}, l_{e}, l_{y}$ the 1-dimensional linear subspaces spanned by the vectors $x^{*}, e, y$, respectively. Let $F: K^{o} \rightarrow \mathbb{R}$ be a logarithmically homogeneous self-concordant barrier on $K$ with barrier parameter $\nu$, and define $p^{*}=-F^{\prime}\left(x^{*}\right)$. Note that $p^{*}$ is a linear functional on $\mathbb{R}^{n}$, located in the interior of the dual cone $K^{*}$. The kernel of $p^{*}$ is an $n$-1-dimensional linear subspace $L_{p^{*}} \subset \mathbb{R}^{n}$, which intersects $K$ in the origin. Denote the 1-dimensional intersection of $L_{p^{*}}$ with the 2-dimensional subspace $L$ by $l_{p^{*}}$. Then $l_{x^{*}}, l_{e}, l_{y}, l_{p^{*}}$ are four mutually distinct coplanar lines, and we can define their projective cross-ratio $r=\left(l_{e}, l_{y} ; l_{x^{*}}, l_{p^{*}}\right)$. The arrangement of the lines implies that $-\infty<r<0$.
Lemma 3.1. Assume above notations. Then $\nu$ is bounded from below by $\nu_{*}=\frac{2}{1+\frac{r+1}{r-1}}=1+$ $\max \left(-r,-r^{-1}\right)$.

Proof. Let $K_{L}=K \cap L$ and let $F_{L}$ be the restriction of $F$ on the interior $K_{L}^{o}$ of $K_{L}$. Then $F_{L}$ is a selfconcordant barrier for the 2 -dimensional cone $K_{L}$ with the same barrier parameter $\nu$ as $K$. Moreover, the linear functional $p_{L}^{*}=-F_{L}^{\prime}\left(x^{*}\right)$ is the restriction of the linear functional $p^{*}$ on $L$, and hence its kernel coincides with $l_{p^{*}}$. The assertion of the lemma for the cone $K$ thus reduces to the assertion for the cone $K_{L}$.

In order to avoid unnecessary notations, we shall assume without restriction of generality that $n=2$ and hence $K=K_{L}$. Let $\gamma_{*}=\frac{\nu_{*}-2}{\sqrt{\nu_{*}-1}}=\frac{|r+1|}{\sqrt{-r}}$ and let $\lambda_{ \pm}^{*}=-\frac{\gamma_{*}}{2} \pm \sqrt{\frac{\gamma_{*}^{2}}{4}+1}$ be the roots of the quadratic equation $\lambda^{2}+\gamma_{*} \lambda-1=0$. Then $-r \gamma_{*}^{2}=(r+1)^{2}$ and hence $r=-\frac{\gamma_{*}^{2}+2}{2} \pm \gamma_{*} \sqrt{\frac{\gamma_{*}^{2}}{4}+1}=-\left(\lambda_{\mp}^{*}\right)^{2}$. Since $\gamma_{*} \geq 0$, we have $\lambda_{-}^{*} \leq-1$ and $0<\lambda_{+}^{*} \leq 1$. Therefore $r=-\left(\lambda_{-}^{*}\right)^{2}$ if $r \leq-1$ and $r=-\left(\lambda_{+}^{*}\right)^{2}$ if $r \geq-1$. Note that in the former case we have $\left(l_{y}, l_{e} ; l_{x^{*}}, l_{p^{*}}\right)=r^{-1}=-\left(\lambda_{+}^{*}\right)^{2}$ by (4).

Let us now introduce a coordinate system in $\mathbb{R}^{2}$ such that the lines $l_{x^{*}}, l_{p^{*}}$ are parallel to the basis vectors $(1,0)^{T},(0,1)^{T}$, respectively. Let further the lines $l_{e}, l_{y}$ be parallel to the vectors $\left(1, \lambda_{ \pm}^{*}\right)^{T}$, respectively, if $r \geq-1$, and to the vectors $\left(1, \lambda_{\mp}^{*}\right)^{T}$, respectively, if $r<-1$. This is always possible because

$$
\left(\lambda_{+}^{*}, \lambda_{-}^{*} ; 0, \infty\right)=\frac{\left(\lambda_{+}^{*}-0\right)\left(\lambda_{-}^{*}-\infty\right)}{\left(\lambda_{-}^{*}-0\right)\left(\lambda_{+}^{*}-\infty\right)}=\frac{\lambda_{+}^{*}}{\lambda_{-}^{*}}=-\left(\lambda_{+}^{*}\right)^{2}= \begin{cases}\left(l_{y}, l_{e} ; l_{x^{*}}, l_{p^{*}}\right), & r<-1 \\ \left(l_{e}, l_{y} ; l_{x^{*}}, l_{p^{*}}\right), & r \geq-1\end{cases}
$$

and the projective cross-ratio of a quadruple of distinct lines through the origin of a plane is the only invariant of the quadruple with respect to the general linear group of this plane. Let us further scale the coordinates by a homothety such that $x^{*}=(1,0)^{T}$. In this coordinate system the cone $K$ is given by the set $\left\{x=\left(x_{1}, x_{2}\right)^{T} \mid x_{1} \geq 0, \lambda_{-}^{*} x_{1} \leq x_{2} \leq \lambda_{+}^{*} x_{1}\right\}$, and $p^{*}=-F^{\prime}\left(x^{*}\right)=(\nu, 0)^{T}$ due to the identity $\left\langle p^{*}, x^{*}\right\rangle=\nu$ [4, eq. (2.3.13)].

Consider the 1-dimensional Lie group $A(t)=\exp (t \cdot a)=\left(\begin{array}{cc}1 & 0 \\ t & 1\end{array}\right)$ generated by the Lie algebra element $a=\left(\begin{array}{ll}0 & 0 \\ 1 & 0\end{array}\right)$. Let $x(t)=A(t) x^{*}=(1, t)^{T}$ and consider the scalar $f(t)=\nu^{-1} F(x(t))$. We shall now establish a differential inequality which is satisfied by the function $f(t)$. Formulas [4, eq. $(2.3 .12-14)]$ and its derivatives yield the relations $F^{\prime}(x)[x]=-\nu, F^{\prime \prime}(x)[x, \cdot]=-F^{\prime}(x), F^{\prime \prime \prime}(x)[x, \cdot, \cdot]=$ $-2 F^{\prime \prime}(x)$. At $x(t)=A(t) x^{*}$ we thus have

$$
\begin{gather*}
F^{\prime}=\nu A^{T}(-t)\binom{-1}{\alpha}, F^{\prime \prime}=\nu A^{T}(-t)\left(\begin{array}{cc}
1 & -\alpha \\
-\alpha & \beta
\end{array}\right) A(-t), \\
F^{\prime \prime \prime}[A(t) h, \cdot, \cdot]=-2 \nu A^{T}(-t)\left[\left(\begin{array}{cc}
1 & -\alpha \\
-\alpha & \beta
\end{array}\right) h_{1}+\left(\begin{array}{cc}
-\alpha & \beta \\
\beta & \mu
\end{array}\right) h_{2}\right] A(-t) \tag{5}
\end{gather*}
$$

for some $\alpha, \beta, \mu \in \mathbb{R}$. Here $\beta>\alpha^{2}$, because $F^{\prime \prime} \succ 0$, and $h=\left(h_{1}, h_{2}\right)^{T} \in \mathbb{R}^{2}$ is an arbitrary vector. Condition (1), applied to the vector $A(t) h$, then yields

$$
-h_{1}^{3}+3 \alpha h_{1}^{2} h_{2}-3 \beta h_{1} h_{2}^{2}-\mu h_{2}^{3} \leq \sqrt{\nu}\left(h_{1}^{2}-2 \alpha h_{1} h_{2}+\beta h_{2}^{2}\right)^{3 / 2}
$$

Setting $h=\left(\alpha-\sqrt{\frac{\beta-\alpha^{2}}{\nu-1}}, 1\right)^{T}$, we obtain after some calculations

$$
\begin{equation*}
-\left(\alpha^{3}+3 \alpha\left(\beta-\alpha^{2}\right)+\mu\right) \leq \gamma\left(\beta-\alpha^{2}\right)^{3 / 2} \tag{6}
\end{equation*}
$$

where $\gamma=\frac{\nu-2}{\sqrt{\nu-1}}$. Let us compute the derivatives of $f(t)$. By (5) and using the fact that $\dot{x}=(0,1)^{T}$ is constant, we have

$$
\dot{f}=\nu^{-1} F^{\prime}(x)[a x]=\alpha, \quad \ddot{f}=\nu^{-1} F^{\prime \prime}(x)[a x, a x]=\beta, \quad f^{(3)}=\nu^{-1} F^{\prime \prime \prime}(x)[a x, a x, a x]=-2 \mu .
$$

Inserting this into (6), we get

$$
\begin{equation*}
4 \dot{f}^{3}-6 \dot{f} \ddot{f}+f^{(3)} \leq 2 \gamma\left(\ddot{f}-\dot{f}^{2}\right)^{3 / 2} \tag{7}
\end{equation*}
$$

We would like to bound the function $f(t)$ by the solution of the differential equation which is obtained when one assumes equality in (7). This is accomplished by introducing the variables $q_{ \pm}=$ $-\frac{\sqrt{\vec{f}-\dot{f}^{2}}}{\lambda_{\mp}}-\dot{f}$, where $\lambda_{ \pm}=-\frac{\gamma}{2} \pm \sqrt{\frac{\gamma^{2}}{4}+1}$ are the roots of the quadratic equation $\lambda^{2}+\gamma \lambda-1=0$. These variables satisfy the relation $q_{+}>q_{-}$and $\dot{f}, \ddot{f}$ can be recovered from them by the formula

$$
\begin{equation*}
\dot{f}=-\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}} q_{-}+\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}} q_{+}, \quad \ddot{f}=\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}} q_{-}^{2}-\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}} q_{+}^{2} \tag{8}
\end{equation*}
$$

We have $\ddot{f}-\dot{f}^{2}=\frac{\left(q_{+}-q_{-}\right)^{2}}{\gamma^{2}+4}$, and hence $\left(\ddot{f}-\dot{f}^{2}\right)^{3 / 2}=\frac{\left(q_{+}-q_{-}\right)^{3}}{\left(\gamma^{2}+4\right)^{3 / 2}}$. A simple calculus then shows that $2 \gamma\left(\ddot{f}-\dot{f}^{2}\right)^{3 / 2}-4 \dot{f}^{3}+6 \dot{f} \ddot{f}=-\frac{2 \lambda_{+}}{\lambda_{+}-\lambda_{-}} q_{-}^{3}+\frac{2 \lambda_{-}}{\lambda_{+}-\lambda_{-}} q_{+}^{3}$ and hence by (7)

$$
\begin{equation*}
f^{(3)} \leq-\frac{2 \lambda_{+}}{\lambda_{+}-\lambda_{-}} q_{-}^{3}+\frac{2 \lambda_{-}}{\lambda_{+}-\lambda_{-}} q_{+}^{3} . \tag{9}
\end{equation*}
$$

Recall that $p^{*}=(\nu, 0)^{T}$ and hence $\dot{f}(0)=0$. Hence by (8) we have

$$
\begin{equation*}
\lambda_{+} q_{-}(0)=\lambda_{-} q_{+}(0) \tag{10}
\end{equation*}
$$

Differentiating the first relation in (8) with respect to $t$ and expressing $\ddot{f}$ by the second relation, we obtain

$$
\begin{equation*}
\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}}\left(q_{-}^{2}+\dot{q}_{-}\right)-\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}}\left(q_{+}^{2}+\dot{q}_{+}\right)=0 \tag{11}
\end{equation*}
$$

Differentiating the second relation in (8) and inserting into (9) yields the inequality

$$
\begin{equation*}
\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}} q_{-}\left(q_{-}^{2}+\dot{q}_{-}\right)-\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}} q_{+}\left(q_{+}^{2}+\dot{q}_{+}\right) \leq 0 \tag{12}
\end{equation*}
$$

Combining (11) with (12) yields

$$
\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}}\left(q_{-}-q_{+}\right)\left(q_{-}^{2}+\dot{q}_{-}\right) \leq 0, \quad \frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}}\left(q_{-}-q_{+}\right)\left(q_{+}^{2}+\dot{q}_{+}\right) \leq 0
$$

which by the relation $q_{+}>q_{-}$gives

$$
\begin{equation*}
q_{-}^{2}+\dot{q}_{-} \geq 0, \quad q_{+}^{2}+\dot{q}_{+} \leq 0 \tag{13}
\end{equation*}
$$

The solution of the differential equation $q^{2}+\dot{q}=0$ is given by $q(t)=\frac{1}{t+q^{-1}(0)}$. The differential inequalities (13) then yield the bounds

$$
\begin{equation*}
q_{-}(t) \geq \frac{1}{t+q_{-}^{-1}(0)}, \quad t \geq 0 ; \quad q_{+}(t) \geq \frac{1}{t+q_{+}^{-1}(0)}, \quad t \leq 0 \tag{14}
\end{equation*}
$$

By (10) and the condition $q_{+}>q_{-}$we have $q_{-}(0)<0$ and $q_{+}(0)>0$. Note that $\lim _{t \rightarrow \lambda_{+}^{*}} f(t)=+\infty$, hence by convexity of $f$ we have $\lim _{t \rightarrow \lambda_{+}^{*}} \dot{f}(t)=+\infty$ and $\lim _{t \rightarrow \lambda_{+}^{*}} q_{-}(t)=-\infty$. The right-hand side in the first relation in (14) tends to $-\infty$ for $t \rightarrow-q_{-}^{-1}(0)$, and hence $\lambda_{+}^{*} \geq-q_{-}^{-1}(0)$. Likewise, $\lim _{t \rightarrow \lambda_{-}^{*}} f(t)=+\infty$, hence $\lim _{t \rightarrow \lambda_{-}^{*}} \dot{f}(t)=-\infty$ and $\lim _{t \rightarrow \lambda_{-}^{*}} q_{+}(t)=+\infty$. The right-hand side in the second relation in (14) tends to $+\infty$ for $t \rightarrow-q_{+}^{-1}(0)$, and hence $\lambda_{-}^{*} \geq-q_{+}^{-1}(0)$.

We thus get $\frac{\lambda_{+}^{*}}{\lambda_{+}} \geq-\frac{1}{\lambda_{+} q_{-}(0)},-\frac{\lambda_{-}^{*}}{\lambda_{-}} \geq \frac{1}{\lambda_{-} q_{+}(0)}$. Combining with (10), this yields $\frac{\lambda_{+}^{*}}{\lambda_{+}} \geq \frac{\lambda_{-}^{*}}{\lambda_{-}}$. Finally, inserting the values $\lambda_{-}=-\sqrt{\nu-1}, \lambda_{+}=\frac{1}{\sqrt{\nu-1}}, \lambda_{-}^{*}=-\sqrt{\nu_{*}-1}, \lambda_{+}^{*}=\frac{1}{\sqrt{\nu_{*}-1}}$, we arrive at the desired conclusion.

Corollary 3.2. Let $K \subset \mathbb{R}^{n}$, $n \geq 2$, be a regular convex cone, and $F: K^{o} \rightarrow \mathbb{R}$ a logarithmically homogeneous self-concordant barrier on $K$ with barrier parameter $\nu$. Then $\nu \geq 2$.

If $n=2$ and the bound on the barrier parameter given by Lemma 3.1 is saturated, then $\lambda_{+}^{*}=\lambda_{+}=$ $-q_{-}^{-1}(0)$ and $\lambda_{-}^{*}=\lambda_{-}=-q_{+}^{-1}(0)$. Inequalities (14) must be saturated too and $\dot{f}(t)=-\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}} \frac{1}{t-\lambda_{+}}+$ $\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}} \frac{1}{t-\lambda_{-}}$. This can be integrated, yielding $f(t)=-\frac{\lambda_{+}}{\lambda_{+}-\lambda_{-}} \log \left(t-\lambda_{+}\right)+\frac{\lambda_{-}}{\lambda_{+}-\lambda_{-}} \log \left(t-\lambda_{-}\right)+$const, thus determining the barrier $F$ up to an additive constant. It is not hard to check that $F$ is invariant under the action of the Lie group $\exp (t \cdot a)$ generated by the Lie algebra element $a=\left(\begin{array}{cc}0 & 1 \\ 1 & -\gamma\end{array}\right)$. This group acts transitively on the set of rays constituting the interior of the cone $K$, and hence the expression $\nu_{*}$ in Lemma 3.1 is independent of the choice of the interior point $x^{*}$ in this case.

## 4 Main result

In this section a lower bound on the barrier parameter $\nu$ for a logarithmically homogeneous selfconcordant barrier $F: K^{o} \rightarrow \mathbb{R}$ on a given regular convex cone $K \subset \mathbb{R}^{n}$ is obtained from Lemma 3.1 by the following consideration. Let $x^{*} \in K^{o}$ be an interior point of $K$, denote $p^{*}=-F^{\prime}\left(x^{*}\right)$, and let $L_{1}, \ldots, L_{m}$ be 2-dimensional linear subspaces containing $x^{*}$. For fixed $p^{*}$ and for each $i=1, \ldots, m$, application of Lemma 3.1 to the intersection $K_{L_{i}}=L_{i} \cap K$ gives rise to a lower bound $\nu_{i}^{*}\left(p^{*}\right)$ on $\nu$, and hence $\nu \geq \max _{i=1, \ldots, m} \nu_{i}^{*}\left(p^{*}\right)$. If $m$ is smaller than the dimension $n$ of the cone $K$, then for subspaces $L_{1}, \ldots, L_{m}$ in general position $p^{*}$ can be chosen such that $\max _{i=1, \ldots, m} \nu_{i}^{*}\left(p^{*}\right)=2$, and no information is gained with respect to Corollary 3.2. If, however, $m \geq n$, then $\min _{p^{*}} \max _{i=1, \ldots, m} \nu_{i}^{*}\left(p^{*}\right)>2$ in general, except in the case that $K$ is the Lorentz cone. The goal of this section is to solve the minimax problem $\min _{p^{*}} \max _{i=1, \ldots, m} \nu_{i}^{*}\left(p^{*}\right)$ for the case $m=n$. We will work under the following assumption.
Assumption 4.1. Let $K \subset \mathbb{R}^{n}$ be a regular convex cone, let $x^{*}=\left(x_{1}^{*}, \ldots, x_{n}^{*}\right)^{T} \in K^{o}$, and let $L_{1}, \ldots, L_{n} \subset \mathbb{R}^{n}$ be 2-dimensional linear subspaces containing $x^{*}$. Assume that there exist linearly independent vectors $e_{i} \in L_{i} \cap \partial K, i=1, \ldots, n$, and let $y_{i} \in L_{i} \cap \partial K$ be such that $L_{i}=\operatorname{span}\left\{e_{i}, y_{i}\right\}$, $i=1, \ldots, n$. Let $l_{k}$ be the line through the points $e_{k}$ and $y_{k}$, and let $z_{k}$ be the intersection point of $l_{k}$ with the $(n-1)$-dimensional linear subspace $\hat{L}_{k}$ spanned by all points $e_{l}, l=1, \ldots, n$ except $e_{k}$. Let $l_{e_{k}}, l_{y_{k}}, l_{z_{k}}$, and $l_{x^{*}}$ be the linear hulls of $e_{k}, y_{k}, z_{k}$, and $x^{*}$, respectively. Then for each $k=1, \ldots, n$ the 4 lines $l_{e_{k}}, l_{y_{k}}, l_{z_{k}}, l_{x^{*}}$ are in $L_{k}$ and hence coplanar, and no three of them are identical. Let $q_{k}=\left[l_{e_{k}}, l_{x^{*}} ; l_{y_{k}}, l_{z_{k}}\right]$ be their projective cross-ratio.

Now let $F: K^{o} \rightarrow \mathbb{R}$ be a logarithmically homogeneous self-concordant barrier with parameter $\nu$, set $p^{*}=-F^{\prime}\left(x^{*}\right)$, and let $l_{p_{k}^{*}}$ be the 1-dimensional intersection of the plane $L_{k}$ with the kernel of the linear functional $p^{*}$. We shall express the projective cross-ratio $r_{k}=\left[l_{e_{k}}, l_{y_{k}} ; l_{x^{*}}, l_{p_{k}^{*}}\right]$, which determines the bound $\nu_{k}^{*}\left(p^{*}\right)$ from Lemma 3.1, in terms of the projective cross-ratios $q_{k}$ and the linear functional $p^{*}$.

Introduce a coordinate system in $\mathbb{R}^{n}$ with basis vectors equal to $e_{k}$. Let $p_{k}^{*}$ be the elements of $p^{*}$ in these coordinates. Note that $p^{*}$ is in the interior of the dual cone $K^{*}$, and hence $\left\langle p^{*}, e_{k}\right\rangle=p_{k}^{*}>0$ for all $k=1, \ldots, n$.

In each of the planes $L_{k}$, consider the affine line $\tilde{l}_{k}$ through $x^{*}$ which is parallel to $l_{e_{k}}$. Introduce a real parameter $\lambda$ on $\tilde{l}_{k}$, putting the number $\lambda$ in correspondence with the point $x^{*}+\lambda e_{k}$. Then the intersection point of $\tilde{l}_{k}$ with $l_{e_{k}}$ is the infinitely remote point and can be assigned the parameter
$\lambda=+\infty$. The intersection point of $\tilde{l}_{k}$ with $l_{x^{*}}$ has parameter value $\lambda=0$. The coordinate vector of the intersection point of $\tilde{l}_{k}$ with $l_{z_{k}}$ has a zero at its $k$-th entry and thus has parameter value $\lambda=-x_{k}^{*}$. Let $\tilde{l}_{k}$ be the parameter value corresponding to the intersection point of $\tilde{l}_{k}$ with $l_{y_{k}}$. Since the segment of $\tilde{l}_{k}$ corresponding to the parameter values $\lambda \in[0, \infty)$ lies in the interior of $K$, we have $\lambda_{k}<0$. Finally, the intersection point of $\tilde{l}_{k}$ with $l_{p_{k}^{*}}$ is given by the equation $\left\langle p^{*}, x^{*}+\lambda e_{k}\right\rangle=0$, which yields the value $\hat{\lambda}_{k}=-\frac{\left\langle p^{*}, x^{*}\right\rangle}{p_{k}^{*}}$ for the parameter of this intersection point. Note that $\hat{\lambda}_{k}<\lambda_{k}$, because $p^{*}$ has to be positive on $y_{k}$. We then obtain the projective cross-ratios

$$
\begin{align*}
& q_{k}=\left[l_{e_{k}}, l_{x^{*}} ; l_{y_{k}}, l_{z_{k}}\right]=\frac{\left(\infty-\lambda_{k}\right)\left(0-\left(-x_{k}^{*}\right)\right)}{\left(\infty-\left(-x_{k}^{*}\right)\right)\left(0-\lambda_{k}\right)}=-\frac{x_{k}^{*}}{\lambda_{k}},  \tag{15}\\
& r_{k}=\left[l_{e_{k}}, l_{y_{k}} ; l_{x^{*}}, l_{p_{k}^{*}}\right]=\frac{(\infty-0)\left(\lambda_{k}-\hat{\lambda}_{k}\right)}{\left(\infty-\hat{\lambda}_{k}\right)\left(\lambda_{k}-0\right)}=1-\frac{\hat{\lambda}_{k}}{\lambda_{k}}=1+\frac{\left\langle p^{*}, x^{*}\right\rangle}{p_{k}^{*} \lambda_{k}}, \tag{16}
\end{align*}
$$

from which we get

$$
\begin{equation*}
\frac{r_{k}+1}{r_{k}-1}=1+\frac{2 p_{k}^{*} \lambda_{k}}{\left\langle p^{*}, x^{*}\right\rangle} \tag{17}
\end{equation*}
$$

Lemma 4.2. The relation $\sum_{k: q_{k}>0} q_{k}>1$ holds.
Proof. Let $I_{+}=\left\{k \mid q_{k}>0\right\}$ and $Q_{+}=\sum_{k \in I_{+}} q_{k}$.
If $I_{+}=\emptyset$, then $x^{*}$ is in the nonpositive orthant by (15). Thus $-x^{*}$ is also in $K$ as a linear combination of the basis vectors $e_{k}$ with nonnegative coefficients. This contradicts the regularity of $K$.

Hence $I_{+} \neq \emptyset$. For every $k, x^{*}+\lambda_{k} e_{k}$ is a positive multiple of $y_{k}$ and hence equals a nonzero vector in $\partial K$. Consider the point $s=\sum_{k \in I_{+}} q_{k}\left(x^{*}+\lambda_{k} e_{k}\right)=\left(Q_{+}-1\right) x^{*}+\left(x^{*}-\sum_{k \in I_{+}} x_{k}^{*} e_{k}\right)$, where the second relation comes from (15). As a linear combination of nonzero elements in $K$, with positive coefficients, the point $s$ is also a nonzero vector in $K$. The vector $x^{*}-\sum_{k \in I_{+}} x_{k}^{*} e_{k}$ has only nonpositive components and is hence in $-K$. It follows that $\left(Q_{+}-1\right) x^{*}=s-\left(x^{*}-\sum_{k \in I_{+}} x_{k}^{*} e_{k}\right)$ is a nonzero vector in $K$, which implies $Q_{+}>1$ and proves the lemma.

By Lemma 3.1, the barrier parameter $\nu$ of the barrier $F$ is bounded from below by the expression $\max _{k=1, \ldots, n} \frac{2}{\left.1-\frac{r_{k}+1}{r_{k}-1} \right\rvert\,}$. This bound still depends on the negative gradient $p^{*}$ of $F$ at $x^{*}$. A lower bound on the barrier parameter of an arbitrary logarithmically homogeneous self-concordant barrier on $K$ is then given by

$$
\begin{equation*}
\nu_{*}=\min _{p^{*}} \max _{k} \frac{2}{1-\left|\frac{r_{k}+1}{r_{k}-1}\right|}=\frac{2}{1-\min _{p^{*}} \max _{k}\left|\frac{r_{k}+1}{r_{k}-1}\right|}, \tag{18}
\end{equation*}
$$

where $p^{*}$ is subject to the constraints $\left\langle p^{*}, e_{k}\right\rangle>0,\left\langle p^{*}, y_{k}\right\rangle>0$ for all $k=1, \ldots, n$. By (17) this transforms into

$$
\begin{equation*}
\nu_{*}=\frac{2}{1-\min _{p^{*}} \max _{k}\left|1+\frac{2 p_{k}^{*} \lambda_{k}}{\left\langle p^{*}, x^{*}\right\rangle}\right|}, \tag{19}
\end{equation*}
$$

where the components of $p^{*}$ have to satisfy the requirements $p_{k}^{*}>0$ and $-\frac{\left\langle p^{*}, x^{*}\right\rangle}{p_{k}^{*}}=\hat{\lambda}_{k}<\lambda_{k}$. Equivalently, $0<\frac{p_{k}^{*}}{\left\langle p^{*}, x^{*}\right\rangle}<-\frac{1}{\lambda_{k}}$.

Introduce variables $\alpha_{k}=1+\frac{2 p_{k}^{*} \lambda_{k}}{\left\langle p^{*}, x^{*}\right\rangle} \in(-1,1)$. These variables have to satisfy the additional requirement $\sum_{k=1}^{n} \frac{\alpha_{k}-1}{2 \lambda_{k}} x_{k}^{*}=1$, which by (15) is equivalent to $\sum_{k=1}^{n} \frac{1-\alpha_{k}}{2} q_{k}=1$. We shall now solve the minimax problem

$$
\begin{equation*}
\min \left\{\max _{k}\left|\alpha_{k}\right| \mid \alpha_{k} \in(-1,1), \sum_{k=1}^{n} \frac{1-\alpha_{k}}{2} q_{k}=1\right\} \tag{20}
\end{equation*}
$$

Lemma 4.3. The value of problem (20) is given by $\frac{\left|\sum_{k} q_{k}-2\right|}{\sum_{k}\left|q_{k}\right|}<1$.

Proof. First note that $\sum_{k}\left|q_{k}\right| \geq \sum_{k} q_{k}$ and hence $\sum_{k} q_{k}-2<\sum_{k}\left|q_{k}\right|$. On the other hand, by Lemma 4.2 we have $\sum_{k}\left(q_{k}+\left|q_{k}\right|\right)>2$ and hence $2-\sum_{k} q_{k}<\sum_{k}\left|q_{k}\right|$. It follows that $\frac{\left|\sum_{k} q_{k}-2\right|}{\sum_{k}\left|q_{k}\right|} \in[0,1)$. It is easily checked that this value is attained by the solution $\alpha_{k}=\alpha_{k}^{*}=\frac{\sum_{l} q_{l}-2}{\sum_{l}\left|q_{l}\right|} \operatorname{sgn} q_{k} \in(-1,1)$.

On the other hand, every feasible vector $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right)^{T}$ has to satisfy the constraint $\sum_{k} \alpha_{k} q_{k}=$ $\sum_{k} q_{k}-2$. It follows that $\left(\max _{k}\left|\alpha_{k}\right|\right) \sum_{k}\left|q_{k}\right| \geq \sum_{k}\left|\alpha_{k}\right|\left|q_{k}\right| \geq\left|\sum_{k} q_{k}-2\right|$, which yields $\max _{k}\left|\alpha_{k}\right| \geq$ $\frac{\left|\sum_{k} q_{k}-2\right|}{\sum_{k}\left|q_{k}\right|}$ and thus proves optimality of the solution $\alpha_{k}=\alpha_{k}^{*}$.

Inserting the optimal value of (20) into (19), we obtain the following theorem.
Theorem 4.4. Under Assumption 4.1, the barrier parameter $\nu$ of any logarithmically homogeneous self-concordant barrier $F$ on the cone $K$ is bounded from below by the quantity

$$
\nu_{*}=\frac{2}{1-\frac{\left|\sum_{k} q_{k}-2\right|}{\sum_{k}\left|q_{k}\right|}} .
$$

## 5 Properties of the lower bound

In this section we will consider the bound given by Theorem 4.4 in more detail.
Lemma 5.1. Assume the conditions of Assumption 4.1. Let $I \subset\{1, \ldots, n\}$ be such that the vectors in the set $\left\{y_{k} \mid k \in I\right\} \cup\left\{e_{k} \mid k \notin I\right\}$ are linearly independent. Then the bound in Theorem 4.4 is invariant under an interchange of the points $e_{k}$ and $y_{k}$ for all $k \in I$.
Proof. The exchange of $y_{k}$ and $e_{k}$ leaves the subspace $L_{k}$ and the line $l_{p_{k}^{*}}$ invariant and hence by (4) leads to the transformation $r_{k} \mapsto r_{k}^{-1}$ in (16). This in turn leads to the transformation $\frac{r_{k}+1}{r_{k}-1} \mapsto-\frac{r_{k}+1}{r_{k}-1}$. The set of constraints $\left\langle p^{*}, e_{k}\right\rangle>0,\left\langle p^{*}, y_{k}\right\rangle>0$ is also left invariant, and hence by (18) the value of $\nu_{*}$ is left unchanged.

Remark 5.2. The assertion of Lemma 5.1 cannot be easily inferred directly from the explicit expression of the bound $\nu_{*}$ in Theorem 4.4, because the exchange of $e_{k}$ and $y_{k}$ for one index $k$ changes the lines $l_{z_{l}}$ for all $l \neq k$ and hence all projective cross-ratios $q_{l}$ in (15) are changed.

Lemma 5.3. Assume the conditions of Assumption 4.1. There exists a subset $I \subset\{1, \ldots, n\}$ of indices with complement $\bar{I}$ such that the set $\left\{e_{k} \mid k \in \bar{I}\right\} \cup\left\{y_{k} \mid k \in I\right\}$ is linearly independent, and $x^{*}$ is a linear combination of the vectors in this set with nonnegative coefficients.

Proof. The assertion of the lemma will follow from the statement that we can render all entries of $x^{*}$ nonnegative by exchanging the vectors $e_{k}$ and $y_{k}$ for a number of indices $k$ and adapting the coordinate system accordingly. Let us prove this statement.

Suppose there exists an index $k$ such that $x_{k}^{*}<0$. Recall that $z_{k}$ is the unique point on $l_{k}$ situated in the linear subspace $\hat{L}_{k}$ spanned by all $e_{l}$ except $e_{k}$. Therefore, linear dependence of the vectors $e_{1}, \ldots, e_{k-1}, y_{k}, e_{k+1}, \ldots, e_{n}$ is equivalent to the relation $z_{k}=y_{k}$. Since $x_{k}^{*}<0$, the line $l_{x^{*}}$ intersects $l_{k}$ in a point opposite to $e_{k}$ with respect to $z_{k}$. But $y_{k}$ is opposite to $e_{k}$ with respect to $l_{x^{*}}$ in $L_{k}$, hence $z_{k} \neq y_{k}$. This proves that we can exchange the roles of $e_{k}$ and $y_{k}$ without violating the condition of linear independence of the points $e_{l}$.

Assume without restriction of generality that $x^{*}$ is situated on the line segment between $e_{k}$ and $y_{k}$. This is equivalent to multiplication of $x^{*}$ by a positive constant and does not change the signs of the entries $x_{k}^{*}$. We have the explicit expression $z_{k}=\frac{x^{*}-x_{k}^{*} e_{k}}{1-x_{k}^{*}}$, deriving from the condition that $z_{k}$ is the affine combination of $e_{k}$ and $x^{*}$ whose $k$-th entry vanishes. On the other hand, we have $y_{k}=\frac{x^{*}+\lambda_{k} e_{k}}{1+\lambda_{k}}$, deriving from the condition that $y_{k}$ is the affine combination of $e_{k}$ and $x^{*}$ which is a multiple of $x^{*}+\lambda_{k} e_{k}$. It follows that

$$
\begin{equation*}
x^{*}=\frac{x_{k}^{*}\left(1+\lambda_{k}\right)}{\lambda_{k}+x_{k}^{*}} y_{k}+\frac{\lambda_{k}\left(1-x_{k}^{*}\right)}{\lambda_{k}+x_{k}^{*}} z_{k}=\frac{x_{k}^{*}\left(1+\lambda_{k}\right)}{\lambda_{k}+x_{k}^{*}} y_{k}+\frac{\lambda_{k}}{\lambda_{k}+x_{k}^{*}}\left(x^{*}-x_{k}^{*} e_{k}\right) . \tag{21}
\end{equation*}
$$

Note that $x^{*}-x_{k}^{*} e_{k}$ is a linear combination of the points $e_{1}, \ldots, e_{k-1}, e_{k+1}, \ldots, e_{n}$, with coefficients being equal to the corresponding entries of $x^{*}$. From (21) it then follows that the coefficients $\tilde{x}_{l}^{*}$ of $x^{*}$, when expressed as a linear combination of the vectors $e_{1}, \ldots, e_{k-1}, y_{k}, e_{k+1}, \ldots, e_{n}$, are given by

$$
\tilde{x}_{k}^{*}=\frac{x_{k}^{*}\left(1+\lambda_{k}\right)}{\lambda_{k}+x_{k}^{*}}, \quad \tilde{x}_{l}^{*}=\frac{\lambda_{k}}{\lambda_{k}+x_{k}^{*}} x_{l}^{*}, l \neq k .
$$

Since $x^{*}$ is situated between $y_{k}$ and $z_{k}$ on the line $l_{k}$ and is different from these points, we have by (21) that $\frac{x_{k}^{*}\left(1+\lambda_{k}\right)}{\lambda_{k}+x_{k}^{*}}>0, \frac{\lambda_{k}\left(1-x_{k}^{*}\right)}{\lambda_{k}+x_{k}^{*}}>0$, and hence also $\frac{\lambda_{k}}{\lambda_{k}+x_{k}^{*}}>0$. Therefore the sign of $\tilde{x}_{l}^{*}$ equals that of $x_{l}^{*}$ for $l \neq k$, while $\tilde{x}_{k}^{*}$ is positive.

As a consequence, exchanging $e_{k}$ and $y_{k}$ has lead to a decrease in the number of negative entries of $x^{*}$ by one. Repeating this process, we can eliminate all negative entries of $x^{*}$.

Theorem 5.4. In addition to Assumption 4.1, suppose that $x^{*}$ is contained in the simplicial cone generated by the vectors $e_{k}$. Then the lower bound in Theorem 4.4 is given by

$$
\nu_{*}=\left\{\begin{array}{cl}
\frac{\sum_{k} q_{k}}{\sum_{k} q_{k}-1}, & \sum_{k} q_{k} \leq 2  \tag{22}\\
\sum_{k} q_{k}, & \sum_{k} q_{k} \geq 2
\end{array}\right.
$$

Proof. Choose a coordinate system in $\mathbb{R}^{n}$ with basis vectors $e_{k}, k=1, \ldots, n$. Then by assumption of the theorem all entries of $x^{*}$ are nonnegative, and by (15) all projective cross-ratios $q_{k}$ are nonnegative. Then the bound in Theorem 4.4 simplifies to (22).

We now consider the situation when $q_{k}=0$ for some $k$. In this case $x^{*}=z_{k}$ is contained in the $(n-1)$-dimensional linear subspace $\hat{L}_{k} \subset \mathbb{R}^{n}$ spanned by all $e_{l}$ except $e_{k}$. For every $l \neq k$, since both $e_{l}, x^{*}$ are in $\hat{L}_{k}$, we also have $y_{l} \in \hat{L}_{k}$. We can then apply the construction of the previous section to the $n-12$-dimensional subspaces $L_{1}, \ldots, L_{k-1}, L_{k+1}, \ldots, L_{n}$ of the $n-1$-dimensional cone $\tilde{K}=$ $K \cap \hat{L}_{k}$. Since all $q_{l}, l \neq k$, retain their values in the lower-dimensional space, and $\sum_{l=1}^{n} q_{l}=\sum_{l \neq k} q_{l}$, $\sum_{l=1}^{n}\left|q_{l}\right|=\sum_{l \neq k}\left|q_{l}\right|$ by $q_{k}=0$, Theorem 4.4 will yield the same bound $\nu_{*}$ for the cone $\tilde{K}$ as it has for the cone $K$. In other words, in the case $q_{k}=0$ the bound given by Theorem 4.4 for the cone $K$ is essentially a consequence of a similar bound for the cone $\tilde{K}$, which is a linear section of $K$ with codimension 1.

Lemma 5.5. Assume the conditions of Theorem 5.4. Then for all $k=1, \ldots, n$ we have $q_{k} \leq 1$, and for all index sets $I \subset\{1, \ldots, n\}$ of cardinality $n-1$ we have $\sum_{k \in I} q_{k} \geq 1$.
Proof. Assume the notations of the previous section. Since the simplicial cone $K_{S}$ generated by the vectors $e_{k}$ is contained in $K$, the interval $I_{S}=l_{k} \cap K_{S}$ is contained in the interval $I_{K}=l_{k} \cap K$ for every $k=1, \ldots, n$. Note that $y_{k}$ is the endpoint of $I_{K}$ opposite to $e_{k}$, while $z_{k}$ is the endpoint of $I_{S}$ opposite to $e_{k}$. Hence $y_{k}$ is situated on $l_{k}$ opposite to $e_{k}$ with respect to $z_{k}$ (but it may coincide with $z_{k}$ ). Recall that the parameter of the intersection point of $l_{e_{k}}$ with $\tilde{l}_{k}$ was $\lambda=+\infty_{2}$ the intersection point of $l_{z_{k}}$ with $\tilde{l}_{k}$ had parameter $\lambda=-x_{k}^{*}$, and the intersection point of $l_{y_{k}}$ with $\tilde{l}_{k}$ had parameter $\lambda=\lambda_{k}$. Therefore $\lambda_{k} \leq-x_{k}^{*}$, which by (15) yields $q_{k} \leq 1$.

Let us prove the second part by contradiction. Suppose there exists a subset $I \subset\{1, \ldots, n\}$ of $n-1$ indices such that $\sum_{k \in I} q_{k}<1$. For $l \in I$, define $a_{l}=\frac{q_{l}}{1-\sum_{k \in I} q_{k}} \geq 0$. We then have

$$
x^{*}+\sum_{l \in I} a_{l}\left(1+\lambda_{l}\right) y_{l}=x^{*}+\sum_{l \in I} \frac{q_{l}}{1-\sum_{k \in I} q_{k}}\left(x^{*}+\lambda_{l} e_{l}\right)=\frac{1}{1-\sum_{k \in I} q_{k}}\left(x^{*}-\sum_{l \in I} x_{l}^{*} e_{l}\right)
$$

where for the second equality we used (15). The leftmost side is the sum of an interior point of $K$ and boundary points of $K$ and is hence also an interior point of $K$. On the other hand, the rightmost side is proportional to $e_{\hat{k}}$, where $\hat{k}$ is the index missing in $I$, and is hence a boundary point of $K$. This leads to a contradiction, thus proving the lemma.

Corollary 5.6. Assume the conditions of Theorem 5.4. Then the bound given in Theorem 4.4 satisfies $\nu_{*} \leq n$. The equality $\nu_{*}=n$ holds if and only if $K$ is either a simplicial cone with generators $e_{1}, \ldots, e_{n}$, or a simplicial cone with generators $y_{1}, \ldots, y_{n}$.

Proof. By (22) the first assertion of the corollary is equivalent to the inequalities

$$
\frac{n}{n-1} \leq \sum_{k} q_{k} \leq n
$$

These can be obtained by summing the inequalities $q_{k} \leq 1, \sum_{k \in I} q_{k} \geq 1$ from Lemma 5.5 over all indices $k$ or all index sets $I$ of cardinality $n-1$, respectively.

Assume now that $\nu_{*}=n$. By (22) we then have either $\sum_{k} q_{k}=\frac{n}{n-1}$ or $\sum_{k} q_{k}=n$.
Let us consider the first case. By Lemma 5.5 we have $q_{k}=\frac{1}{n-1}$ for all $k$, and hence $\lambda_{k}=-(n-1) x_{k}^{*}$. Note that $y_{k}$ is a positive multiple of the point $x^{*}+\lambda_{k} e_{k}$, hence $y_{k}=\beta_{k}\left(x^{*}-(n-1) x_{k}^{*} e_{k}\right), \beta_{k}>0$ for all $k$. Let $\hat{k} \in\{1, \ldots, n\}$ and $I=\{1, \ldots, n\} \backslash\{\hat{k}\}$. Then we have

$$
\sum_{k \in I} \beta_{k}^{-1} y_{k}=\sum_{k \in I}\left(x^{*}-(n-1) x_{k}^{*} e_{k}\right)=(n-1) x_{\hat{k}}^{*} e_{\hat{k}}
$$

and $e_{\hat{k}}$ is contained in the relative interior of the convex cone generated by the set $\left\{y_{k} \mid k \in I\right\}$. But $e_{\hat{k}} \in \partial K$, which implies that this cone is entirely contained in $\partial K$. Repeating this argument for all $\hat{k}$, we see that the boundary of the simplicial cone generated by the $y_{k}$ is contained in $\partial K$. On the other hand, $\sum_{k=1}^{n} \beta_{k}^{-1} y_{k}=\sum_{k=1}^{n}\left(x^{*}-(n-1) x_{k}^{*} e_{k}\right)=x^{*} \in K^{o}$, which implies that the points $y_{k}$ are linearly independent and that $K$ equals the cone generated by the $y_{k}$.

We now pass to the case $\sum_{k} q_{k}=n$. By Lemma 5.5 we have $q_{k}=1$ for all $k$. This is equivalent to the relations $y_{k}=z_{k}$, and $y_{k}$ is contained in the cone generated by the set $\left\{e_{l} \mid l \neq k\right\}$ for all $k$. Moreover, it follows that $z_{k} \in \partial K$ and hence $z_{k} \neq x^{*}$, which implies $x_{k}^{*}>0$ for all $k$. By $\lambda_{k}=-x_{k}^{*}$ we then have that $y_{k}$ is a positive multiple of $x^{*}-x_{k}^{*} e_{k}=\sum_{l \neq k} x_{l}^{*} e_{l}$, and $y_{k}$ is in the relative interior of the cone generated by the set $\left\{e_{l} \mid l \neq k\right\}$. As in the previous paragraph, this whole cone must then be in $\partial K$ for all $k$, and $\partial K$ contains the boundary of the simplicial cone generated by the $e_{k}$. Thus $K$ equals this simplicial cone. This proves one direction of the equivalence asserted in the second part of the corollary.

Let us prove the opposite direction. Assume that $K$ is a simplicial cone generated by either the vectors $e_{k}$ or the vectors $y_{k}$. By possibly exchanging the roles of $e_{k}$ and $y_{k}$ for all $k$, we by virtue of Lemma 5.1 can assume that $K$ is generated by the $e_{k}$. The line $l_{k}$ intersects $\partial K$ in $e_{k}$ and in the face opposite to $e_{k}$, which implies that the second intersection point $y_{k}$ coincides with $z_{k}$. But then $\lambda_{k}=-x_{k}^{*}$ and $q_{k}=1$ for all $k$, which by (22) yields the assertion to be proven.

Theorem 5.7. Assume the conditions of Assumption 4.1. The lower bound $\nu_{*}$ given in Theorem 4.4 cannot exceed the dimension $n$ of the cone $K$. The equality $\nu_{*}=n$ holds if and only if $K$ is a simplicial cone with generators $\tilde{e}_{1}, \ldots, \tilde{e}_{n}$ such that $\tilde{e}_{k} \in\left\{e_{k}, y_{k}\right\}$ for every $k=1, \ldots, n$.

Proof. The theorem is a consequence of Lemmas 5.1, 5.3, and Corollary 5.6.

## 6 Relation with Nesterovs and Nemirovskis bound

In this section we deduce the lower bound of Nesterov and Nemirovski, applied to convex cones, from our result. Proposition 2.3.6 in [4] states that if $C \subset \mathbb{R}^{n}$ is a convex polytope and $e_{n} \in \partial C$ is a boundary point belonging to exactly $k(n-1)$-dimensional faces of $C$, such that the normal vectors to these faces are linearly independent, then $k$ is a lower bound on the barrier parameter of any selfconcordant barrier on $C$. We are interested in the situation when $C$ is a cone and prove the following slightly stronger result for this case.

Theorem 6.1. Let $K \subset \mathbb{R}^{n}$, $n \geq 3$, be a regular polyhedral convex cone, let $e_{k+1} \in \partial K$ be a nonzero boundary point belonging to exactly $k(n-1)$-dimensional faces of $K, 2 \leq k \leq n-1$, such that the normals to these faces are linearly independent. Then $\nu_{*}=k+1$ is a lower bound on the barrier parameter of any logarithmically homogeneous self-concordant barrier on $K$.

Proof. By an appropriate choice of coordinates, we can assume that $e_{k+1}=(1,0, \ldots, 0)^{T}$, the set $\left\{x=\left(x_{0}, \ldots, x_{n-1}\right)^{T} \in K \mid x_{0}=1\right\}$ is a compact section of $K$, and there exists a neighbourhood $U$ of $e_{k+1}$ such that $x \in U \cap K$ if and only if $x \in U$ and $x_{j} \leq 0, j=1, \ldots, k$. Let us further assume without restriction of generality that $k=n-1$, otherwise we replace the cone $K$ by the ( $k+1$ )-dimensional intersection $K \cap L$, where $L \subset \mathbb{R}^{n}$ is the ( $k+1$ )-dimensional linear subspace determined by the equations $x_{k+1}=\cdots=x_{n-1}=0$.

Set $x^{*}=(1,-\varepsilon, \ldots,-\varepsilon)^{T}, e_{j}=(1,-\varepsilon, \ldots,-\varepsilon, 0,-\varepsilon, \ldots,-\varepsilon)^{T}, j=1, \ldots, n-1$, where the zero is located at position $j$. For small enough $\varepsilon>0$ we then have $x^{*} \in K^{o}, e_{j} \in \partial K, j=1, \ldots, n$. Let further $l_{j}$ be the line through $x^{*}$ and $e_{j}$ and let $y_{j}$ be the intersection point of $l_{j}$ with $\partial K$ opposite to $e_{j}, j=1, \ldots, n$. We then have $y_{j}=\left(1,-\varepsilon, \ldots,-\varepsilon,-\alpha_{j},-\varepsilon, \ldots,-\varepsilon\right)^{T}$ for $j=1, \ldots, n-1$, $y_{n}=\left(1,-\alpha_{n}, \ldots,-\alpha_{n}\right)^{T}$, and $\lim _{\varepsilon \rightarrow 0} \alpha_{j}>0$ for all $j=1, \ldots, n$. For $i \in\{1, \ldots, n\}$, denote by $\hat{L}_{i} \subset \mathbb{R}^{n}$ the $(n-1)$-dimensional linear subspace spanned by all $e_{j}$ except $e_{i}$, and let $z_{i}$ be the intersection point of $\hat{L}_{i}$ with the line $l_{i}$. It is not hard to check that $z_{i}=\left(1,-\varepsilon, \ldots,-\varepsilon,-\beta_{i},-\varepsilon, \ldots,-\varepsilon\right)^{T}, i=1, \ldots, n-1$, $z_{n}=\left(1,-\beta_{n}, \ldots,-\beta_{n}\right)^{T}$ with $\beta_{i}=\varepsilon \frac{n-2}{n-3}, i=1, \ldots, n-1$, and $\beta_{n}=\varepsilon \frac{n-2}{n-1}$. For $n=3$ the line $l_{i}$ does not intersect $L_{i}, i=1,2$, and we set $\beta_{1}=\beta_{2}=\infty$ in this case.

The projective cross-ratios (15) are then given by

$$
\begin{gathered}
q_{j}=\left[0,-\varepsilon ;-\alpha_{j},-\varepsilon \frac{n-2}{n-3}\right]=\frac{\alpha_{j}}{(n-2)\left(\alpha_{j}-\varepsilon\right)}, \quad j=1, \ldots, n-1 \\
q_{n}=\left[0,-\varepsilon ;-\alpha_{n},-\varepsilon \frac{n-2}{n-1}\right]=\frac{-\alpha_{n}}{(n-2)\left(\alpha_{n}-\varepsilon\right)} .
\end{gathered}
$$

Theorem 4.4 then yields the lower bound

$$
\nu_{*}=\frac{2}{1-\frac{\left|\left(\sum_{j=1}^{n-1} \frac{\alpha_{j}}{\alpha_{j}-\varepsilon}\right)-\frac{\alpha_{n}}{\alpha_{n}-\varepsilon}-2(n-2)\right|}{\sum_{j=1}^{n} \frac{\alpha_{j}}{\alpha_{j}-\varepsilon}}}
$$

on the barrier parameter of any logarithmically homogeneous self-concordant barrier on $K$. The relation $\lim _{\varepsilon \rightarrow 0} \nu_{*}=n$ completes the proof.

Corollary 6.2. Let $n \geq 3$. The epigraph of the $\|\cdot\|_{\infty}$-norm in $\mathbb{R}^{n-1}$,

$$
\begin{equation*}
K_{n, \infty}=\left\{\left(x_{0}, \ldots, x_{n-1}\right)^{T}\left|x_{0} \geq\left|x_{k}\right| \forall k=1, \ldots, n-1\right\} \subset \mathbb{R}^{n}\right. \tag{23}
\end{equation*}
$$

cannot have a logarithmically homogeneous self-concordant barrier with barrier parameter less than $\nu_{*}=n$.

An optimal barrier for the cone $K_{n, \infty}$ is given by

$$
\begin{equation*}
F\left(x_{0}, \ldots, x_{n-1}\right)=-\sum_{k=1}^{n-1} \log \left(x_{0}^{2}-x_{k}^{2}\right)+(n-2) \log x_{0} \tag{24}
\end{equation*}
$$

For a proof see the appendix.
Note that since every convex quadrangle is projectively equivalent to a square, the barrier (24) for $n=3$ yields an optimal barrier also for an arbitrary regular polyhedral cone $K \subset \mathbb{R}^{3}$ which is generated by 4 extreme rays.

## 7 Further examples

### 7.1 Power cone

The power cone is a 3 -dimensional regular convex cone defined by

$$
\begin{equation*}
K_{p}=\left\{(u, v, w)^{T}\left|u \geq 0, v \geq 0, u^{1 / p} v^{1 / q} \geq|w|\right\}\right. \tag{25}
\end{equation*}
$$

where $p \in(2, \infty)$ is a parameter and $\frac{1}{p}+\frac{1}{q}=1$. In [3] Nesterov proposed a logarithmically homogeneous self-concordant barrier with barrier parameter $\nu=4$ for this cone. In [1] a logarithmically homogeneous
self-concordant barrier with barrier parameter $\nu=3$ was proposed and a logarithmically homogeneous function with homogeneity parameter $\nu=3-\frac{2}{p}$ was conjectured to be self-concordant. We shall now give a lower bound on the barrier parameter of any logarithmically homogeneous self-concordant barrier on $K_{p}$.

Consider the compact section $D=\left\{(u, v, w)^{T} \in K_{p} \mid u+v=1\right\}$ of $K_{p}$. Introducing the variable $\rho=u-v \in[-1,1]$, we can parameterize $D$ by $(\rho, w)^{T}$. Inserting the relations $u=\frac{1+\rho}{2}, v=\frac{1-\rho}{2}$ into the inequality defining the cone $K_{p}$, we see that $D$ is given by the set $\left\{(\rho, w)^{T}| | \rho \mid \leq 1,(1+\rho)^{1 / p}(1-\rho)^{1 / q} \geq\right.$ $2|w|\}$.

Let now $\gamma>0$ be the unique positive root of the transcendent equation

$$
\begin{equation*}
q\left(1+\gamma^{-1 / q}\right)=p\left(1+\gamma^{-1 / p}\right) \tag{26}
\end{equation*}
$$

Choose $\rho_{2}, \rho_{3} \in(-1,1)$ such that $\rho_{2}<\rho_{3}$ and $\gamma=\frac{\left(1-\rho_{3}\right)\left(1+\rho_{2}\right)}{\left(1+\rho_{3}\right)\left(1-\rho_{2}\right)}$. Then $\rho_{3}$ can be expressed as a function of $\rho_{2}$ by $\rho_{3}=\frac{1+\rho_{2}-\gamma\left(1-\rho_{2}\right)}{1+\rho_{2}+\gamma\left(1-\rho_{2}\right)}$. Define further $w_{k}=\frac{1}{2}\left(1+\rho_{k}\right)^{1 / p}\left(1-\rho_{k}\right)^{1 / q}, k=2,3$.

Set $e_{1}=(1,0)^{T}, y_{1}=(-1,0)^{T}, e_{2}=\left(\rho_{2}, w_{2}\right)^{T}, y_{2}=\left(\rho_{3},-w_{3}\right)^{T}, e_{3}=\left(\rho_{2},-w_{2}\right)^{T}, y_{3}=\left(\rho_{3}, w_{3}\right)^{T}$. All these 6 points are located on the boundary of $D$, and the lines $l_{k}$ through $e_{k}, y_{k}, k=1,2,3$, intersect in the common point $x^{*}=\left(\frac{\rho_{2} w_{3}+\rho_{3} w_{2}}{w_{2}+w_{3}}, 0\right)^{T}$, which lies in the interior of the triangle formed by the $e_{k}$. The line $l_{1}$ intersects the line through $e_{2}, e_{3}$ in the point $z_{1}=\left(\rho_{2}, 0\right)^{T}$, while $l_{3}$ intersects the line through $e_{1}, e_{2}$ in the point

$$
z_{3}=\frac{1}{\left(1-\rho_{2}\right)\left(w_{2}+w_{3}\right)+w_{2}\left(\rho_{3}-\rho_{2}\right)}\binom{\rho_{2} w_{3}\left(1-\rho_{2}\right)+w_{2}\left(2 \rho_{3}-\rho_{2} \rho_{3}-\rho_{2}\right)}{w_{2}\left(w_{2}\left(1-\rho_{3}\right)+w_{3}\left(1-\rho_{2}\right)\right)} .
$$

From this we readily compute the projective cross-ratios

$$
\begin{align*}
q_{1} & =\frac{2 w_{2}\left(\rho_{3}-\rho_{2}\right)}{\left(1-\rho_{2}\right)\left(w_{2}\left(1+\rho_{3}\right)+w_{3}\left(1+\rho_{2}\right)\right)}  \tag{27}\\
q_{2}=q_{3} & =\frac{w_{2}\left(1-\rho_{3}\right)+w_{3}\left(1-\rho_{2}\right)}{2 w_{3}\left(1-\rho_{2}\right)} \tag{28}
\end{align*}
$$

and hence

$$
\sum_{k=1}^{3} q_{k}-1=\frac{w_{2}\left(1+\rho_{3}\right)\left(w_{2}\left(1-\rho_{3}\right)+w_{3}\left(1-\rho_{2}\right)\right)}{w_{3}\left(1-\rho_{2}\right)\left(w_{2}\left(1+\rho_{3}\right)+w_{3}\left(1+\rho_{2}\right)\right)}=\frac{1+\gamma^{1 / p}}{1+\gamma^{1 / q}}>1
$$

By (22) we then obtain

$$
\begin{equation*}
\nu_{*}=q_{1}+q_{2}+q_{3}=1+\frac{1+\gamma^{1 / p}}{1+\gamma^{1 / q}} \tag{29}
\end{equation*}
$$

Corollary 7.1. Let $K_{p} \subset \mathbb{R}^{3}$ be the power cone given by (25) with parameter $p \geq(2,+\infty)$. If $F$ is a logarithmically homogeneous self-concordant barrier on $K_{p}$, then its barrier parameter satisfies the inequality $\nu \geq 1+\frac{1+\gamma^{1 / p}}{1+\gamma^{1 / q}}$, where $\gamma$ is given by (26) and $\frac{1}{p}+\frac{1}{q}=1$.

In Fig. 1 the lower bound $\nu_{*}$ as a function of $p$ is depicted along with the barrier parameters of the barriers proposed in [3] and [1] ${ }^{2}$.

### 7.2 Epigraph of the $\|\cdot\|_{p}$ norm

Next we consider the epigraph of the $\|\cdot\|_{p}$-norm in $\mathbb{R}^{2}$ for $1 \leq p \leq \infty$, i.e., the 3-dimensional cone

$$
\begin{equation*}
K_{3, p}=\left\{\left(x_{0}, x_{1}, x_{2}\right)^{T} \mid x_{0} \geq\left(\left|x_{1}\right|^{p}+\left|x_{2}\right|^{p}\right)^{1 / p}\right\} \tag{30}
\end{equation*}
$$

In [3] Nesterov proposed a method to construct a logarithmically homogeneous self-concordant barrier with barrier parameter $\nu=2 \tilde{\nu}$ for this cone if a logarithmically homogeneous self-concordant barrier for the corresponding power cone $K_{p}$ is available which has barrier parameter $\tilde{\nu}$. In [1] the universal barrier [4, Sect. 2.5] for $K_{3, p}$ was computed and a barrier parameter $\nu=\frac{3 p}{p+1}(p \geq 2)$ for this barrier

[^2]Values of the self-concordance parameter


Figure 1: Barrier parameters of barriers for the power cone and lower bound
was conjectured on the basis of randomized numerical experiments. We shall now give a lower bound on the barrier parameter for any logarithmically homogeneous self-concordant barrier on $K_{3, p}$.

For $p=2, K_{3, p}$ is the 3 -dimensional Lorentz cone, whose optimal barrier parameter is 2 . For $p=1$ and $p=\infty K_{3, p}$ is a polyhedral cone with 4 extreme rays. This case was considered in the previous section, where it was established that the optimal barrier parameter equals 3 .

Let us consider the case $2<p<\infty$. Let $\gamma \in(0,1)$ be the unique solution of the equation $\left(1-\frac{2}{p}\right) \gamma^{1-1 / p}+\left(1-\frac{1}{p}\right) \gamma^{1-2 / p}-\frac{1}{p}=0$. Note that this definition coincides with (26). For $\delta \in(0,1)$, set

$$
\begin{equation*}
\rho_{2}=1-\delta, \quad \rho_{3}=1-\gamma \delta, \quad w_{2}=\left(1-\rho_{2}^{p}\right)^{1 / p}, \quad w_{3}=\left(1-\rho_{3}^{p}\right)^{1 / p} \tag{31}
\end{equation*}
$$

Consider the compact section $D=\left\{(\rho, w)^{T} \mid(1, \rho, w)^{T} \in K_{3, p}\right\}$ of the cone $K_{3, p}$ and let $e_{1}, e_{2}, e_{3} \in \partial D$, $x^{*} \in D^{o}$ be as in the previous subsection. Then the projective cross-ratios $q_{k}$ will be given by the same formulas (27), and

$$
\begin{equation*}
q_{1}+q_{2}+q_{3}=2+\frac{w_{2}^{2}\left(1-\rho_{3}^{2}\right)-w_{3}^{2}\left(1-\rho_{2}^{2}\right)}{w_{3}\left(1-\rho_{2}\right)\left(w_{3}\left(1+\rho_{2}\right)+w_{2}\left(1+\rho_{3}\right)\right)} . \tag{32}
\end{equation*}
$$

Now note that $\frac{1-x^{2}}{\left(1-x^{p}\right)^{2 / p}}$ is a strictly monotonely decreasing function for $x \in(0,1)$, hence $\frac{1-\rho_{3}^{2}}{w_{3}^{2}}<\frac{1-\rho_{2}^{2}}{w_{2}^{2}}$ and $q_{1}+q_{2}+q_{3}<2$. By (22) we then get the lower bound
$\nu_{*}=\frac{q_{1}+q_{2}+q_{3}}{q_{1}+q_{2}+q_{3}-1}=2+\frac{w_{3}^{2}\left(1-\rho_{2}^{2}\right)-w_{2}^{2}\left(1-\rho_{3}^{2}\right)}{w_{2}\left(1+\rho_{3}\right)\left[w_{3}\left(1-\rho_{2}\right)+w_{2}\left(1-\rho_{3}\right)\right]}=2+\frac{\left(w_{3} / w_{2}\right)^{2}(2-\delta)-\gamma(2-\gamma \delta)}{(2-\gamma \delta)\left(w_{3} / w_{2}+\gamma\right)}$.
We have

$$
\begin{equation*}
\lim _{\delta \rightarrow 0} \frac{w_{3}}{w_{2}}=\left(\lim _{\delta \rightarrow 0} \frac{1-(1-\gamma \delta)^{p}}{1-(1-\delta)^{p}}\right)^{1 / p}=\left(\lim _{\delta \rightarrow 0} \frac{\gamma(1-\gamma \delta)^{p-1}}{(1-\delta)^{p-1}}\right)^{1 / p}=\gamma^{1 / p} \tag{33}
\end{equation*}
$$

and therefore

$$
\lim _{\delta \rightarrow 0} \nu_{*}=2+\frac{\gamma^{2 / p}-\gamma}{\gamma^{1 / p}+\gamma}=2+\frac{\gamma^{1 / p}-\gamma^{1-1 / p}}{1+\gamma^{1-1 / p}}
$$

which, remarkably, coincides with (29).
Let us now consider the case $1<p<2$. Let $\gamma \in(0,1)$ be the unique solution of the equation $\left(\frac{2}{p}-1\right) \gamma^{1 / p}+\frac{1}{p} \gamma^{2 / p-1}-\left(1-\frac{1}{p}\right)=0$. For $\delta \in(0,1)$, define $\rho_{2}, \rho_{3}, w_{2}, w_{3}$ by (31) and let $e_{1}, e_{2}, e_{3} \in \partial D$, $x^{*} \in D^{o}$ be again as in the previous subsection. Then we again obtain (32), but $\frac{1-x^{2}}{\left(1-x^{p}\right)^{2 / p}}$ is now a strictly monotonely increasing function for $x \in(0,1)$. Hence $\frac{1-\rho_{3}^{2}}{w_{3}^{2}}>\frac{1-\rho_{2}^{2}}{w_{2}^{2}}$ and $q_{1}+q_{2}+q_{3}>2$. By (22) we then get the lower bound

$$
\nu_{*}=q_{1}+q_{2}+q_{3}=2+\frac{\left(w_{2} / w_{3}\right)^{2}(2-\gamma \delta) \gamma-(2-\delta)}{(2-\delta)+w_{2} / w_{3}(2-\gamma \delta)} .
$$

As in (33) we get $\lim _{\delta \rightarrow 0} \frac{w_{2}}{w_{3}}=\gamma^{-1 / p}$, which yields

$$
\lim _{\delta \rightarrow 0} \nu_{*}=2+\frac{\gamma^{1-2 / p}-1}{1+\gamma^{-1 / p}}=2+\frac{\gamma^{1-1 / p}-\gamma^{1 / p}}{1+\gamma^{1 / p}}
$$

Note that this again coincides with (29), but with $p$ and $q$ interchanged.
Combining these results, we get the following lower bound.
Corollary 7.2. Let $K_{3, p} \subset \mathbb{R}^{3}$ be the epigraph of the $\|\cdot\|_{p}$-norm given by (30) with parameter $p \in[1, \infty]$. Set $c=\min \left(\frac{1}{p}, 1-\frac{1}{p}\right) \in\left[0, \frac{1}{2}\right]$ and let $\gamma \in[0,1)$ be a solution of the equation $(1-2 c) \gamma^{1-c}+$ $(1-c) \gamma^{1-2 c}-c=0$. If $F$ is a logarithmically homogeneous self-concordant barrier on $K_{3, p}$, then its barrier parameter satisfies the inequality $\nu \geq 1+\frac{1+\gamma^{c}}{1+\gamma^{1-c}}$.

As already noted, as functions of $p$ the lower bounds given in Corollaries 7.1 and 7.2 coincide.
Remark 7.3. The choices of the points $e_{k}$ and $x^{*}$ in Subsections 7.1 and 7.2 are optimal, i.e., the bounds in Corollaries 7.1 and 7.2 are the best possible which can be obtained with our method.

## References

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## A Self-concordance of function (24)

In this section it is proven that the function $F$ given by (24) is a self-concordant barrier for the cone $K_{n, \infty}$ defined in (23). The proof is due to an anonymous reviewer. It replaces the much more complicated proof from the first version of the paper.

Consider the positive orthant $\mathbb{R}_{+}^{n-1}$ with its optimal barrier $F_{\mathbb{R}_{+}^{n-1}}(y)=-\sum_{k=1}^{n-1} \log y_{k}$. As a homogeneous cone, it has rank $n-1$. From this cone we construct [2, Sect. 3] (see also [4, pp. 165166]) a homogeneous cone of rank $n$ and dimension $2 n-1$,

$$
S C\left(\mathbb{R}_{+}^{n-1}, B\right)=\left\{\left(y, x, x_{0}\right) \in \mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R} \mid x_{0} \geq 0, x_{0} y-B(x) \in \mathbb{R}_{+}^{n-1}\right\}
$$

where $B: \mathbb{R}^{n-1} \rightarrow \mathbb{R}_{+}^{n-1}$ is a symmetric vector-valued bilinear form given by $B(x)=\left(x_{1}^{2}, \ldots, x_{n-1}^{2}\right)^{T}$. An optimal barrier for the cone $S C\left(\mathbb{R}_{+}^{n-1}, B\right)$ with barrier parameter $n$ is given by [2, Theorem 4.1]

$$
F_{S C\left(\mathbb{R}_{+}^{n-1}, B\right)}\left(y, x, x_{0}\right)=F_{\mathbb{R}_{+}^{n-1}}\left(y-x_{0}^{-1} B(x)\right)-\log x_{0}=-\sum_{k=1}^{n-1} \log \left(x_{0} y_{k}-x_{k}^{2}\right)+(n-2) \log x_{0}
$$

Now the intersection of the cone $S C\left(\mathbb{R}_{+}^{n-1}, B\right)$ with the linear subspace given by $x_{0}=y_{1}=\cdots=y_{n-1}$ is isomorphic to the cone $K_{n, \infty}$, and the restriction of the barrier $F_{S C\left(\mathbb{R}_{+}^{n-1}, B\right)}$ to this intersection induces the function $F$ on $K_{n, \infty}$. This proves that $F$ is actually a self-concordant barrier.


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[^1]:    ${ }^{1}$ Actually, in [4, Prop. 2.3.6] it is required that $K$ is polyhedral, but this is not used in the proof.

[^2]:    ${ }^{2}$ As noted by an anonymous referee, expression (29) can be rewritten as $2+(1-q / p) \gamma^{1 / p}$.

