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## A lower bound on the barrier parameter of barriers on convex cones

Roland Hildebrand \*

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#### Abstract

Let  $K \subset \mathbb{R}^n$  be a regular convex cone, let  $e_1, \ldots, e_n \in \partial K$  be linearly independent points on the boundary of a compact affine section of the cone, and let  $x^* \in K^o$  be a point in the relative interior of this section. For  $k = 1, \ldots, n$ , let  $l_k$  be the line through the points  $e_k$  and  $x^*$ , let  $y_k$  be the intersection point of  $l_k$  with  $\partial K$  opposite to  $e_k$ , and let  $z_k$  be the intersection point of  $l_k$  with the linear subspace spanned by all points  $e_l$ ,  $l = 1, \ldots, n$  except  $e_k$ . We give a lower bound on the barrier parameter  $\nu$  of logarithmically homogeneous self-concordant barriers  $F : K^o \to \mathbb{R}$  on K in terms of the projective cross-ratios  $q_k = (e_k, x^*; y_k, z_k)$ . Previously known lower bounds by Nesterov and Nemirovski can be obtained from our result as a special case. As an application, we construct an optimal barrier for the epigraph of the  $|| \cdot ||_{\infty}$ -norm in  $\mathbb{R}^n$  and compute lower bounds on the barrier parameter for the power cone and the epigraph of the  $|| \cdot ||_{\infty}$ -norm in  $\mathbb{R}^2$ .

#### 1 Introduction

In modern convex optimization, interior point methods are the primary tool to solve conic programs. A central role in solution algorithms for conic programs over some regular (with nonempty interior, containing no lines) convex cone K is assigned to a smooth real-valued convex function  $F: K^o \to \mathbb{R}$  on the interior of the cone, the *barrier*. In order to be useful for optimization, the barrier has to satisfy certain properties [4, Section 2.3]. The second and third derivative have to satisfy the self-concordance relation

$$F'''(x)[h,h,h] \le 2(F''(x)[h,h])^{3/2} \qquad \forall \ x \in K^o, \ h \in T_x K^o,$$
(1)

with h running through the tangent space at x. The function F has to tend to infinity as its argument tends to the boundary of the cone,

$$\lim_{x \to \partial K} F(x) = +\infty,\tag{2}$$

and it has to satisfy the logarithmic homogeneity condition

$$F(\alpha x) = -\nu \log \alpha + F(x) \qquad \forall \ \alpha > 0, \ x \in K^o.$$
(3)

A smooth function  $F: K^o \to \mathbb{R}$  satisfying conditions (1,2,3) is called a *logarithmically homogeneous* self-concordant barrier for the cone K. The real constant  $\nu$  is called the *barrier parameter* of the barrier F.

The lower the barrier parameter of a barrier, the faster are the interior point algorithms based on this barrier. For conic optimization problems over a cone K, it is therefore desirable to have barriers on K with a barrier parameter as small as possible. We call a logarithmically homogeneous self-concordant barrier on K optimal if it has the lowest possible barrier parameter.

Optimality of a barrier F is proven by verifying properties (1,2,3) and showing that the barrier parameter  $\nu$  of F is equal to a lower bound  $\nu_*$  on this parameter for the given cone. For general cones, all lower bounds on the barrier parameter which are available today are based on a result of Nesterov

<sup>\*</sup>LJK, Université Grenoble 1 / CNRS, 51 rue des Mathématiques, BP53, 38041 Grenoble cedex 09, France (roland.hildebrand@imag.fr).

and Nemirovski [4, Sect. 2.3.4]. Namely, if for some boundary point  $z \in \partial K$  of the cone there exists a neighbourhood U of z and affine half-spaces  $A_1, \ldots, A_k \subset \mathbb{R}^n$  with  $z \in \partial A_j$ ,  $j = 1, \ldots, k$ , such that the normals to the half-spaces at z are linearly independent and the intersection  $U \cap K$  equals the intersection  $U \cap A_1 \cap \cdots \cap A_k^{-1}$ , then a lower bound on the barrier parameter of any self-concordant barrier on K is given by  $\nu_* = k$ . Based on this result, Güler and Tunçel proved that the minimum over the Carathéodory numbers of all points in the interior of K also is a lower bound on the barrier parameter [2, Prop. 4.1]. In this way, the standard barriers for the symmetric cones used in linear, conic quadratic, and semi-definite programming are shown to be optimal. Optimal barriers can be constructed also for general homogeneous cones, with the barrier parameter equal to the rank of the cone [2, Theorem 4.1].

In this contribution, we provide a new lower bound on the barrier parameter of barriers on a general cone (Theorems 4.4, 5.4). For *n*-dimensional cones, this lower bound is contained in the interval [2, n] (Corollary 3.2 and Theorem 5.7). From our result, a slightly stronger bound than that in [4, Sect. 2.3.4] follows as special case (Theorem 6.1). In contrast to the previously known bounds, our results are non-trivial also for "round" cones, i.e., cones with a smooth boundary. The bound is a function of the projective cross-ratio of geometric objects that are constructed from *n* boundary points of the cone in general position and an interior point. As an application, we compute lower bounds on the barrier parameter for the epigraph of the  $|| \cdot ||_{\infty}$ -norm (Corollary 6.2), the power cone (Corollary 7.1), and the epigraph of the  $|| \cdot ||_{p}$ -norm in  $\mathbb{R}^{2}$  (Corollary 7.2).

The remainder of the paper is structured as follows. In the next section we introduce the projective cross-ratio and consider some of its elementary properties. In Section 3 we prove an auxiliary result, which essentially applies to 2-dimensional cones. In Section 4 we deduce the lower bound on the barrier parameter of barriers on general cones and in the subsequent section we investigate its properties. In Section 6 we deduce the bounds in [4, Sect. 2.3.4] from our result, and in the last section we apply our results to the power cone and the epigraph of the  $|| \cdot ||_p$ -norm. Finally, in the appendix we construct an optimal barrier for the epigraph of the  $|| \cdot ||_{\infty}$ -norm.

#### 2 The projective cross-ratio

Let  $x_1, x_2, x_3, x_4 \in \mathbb{R} \cup \{\infty\}$  be four distinct points in the 1-point compactification of the real line. The *projective cross-ratio* of the quadruple  $(x_1, x_2, x_3, x_4)$  is defined as the number

$$(x_1, x_2; x_3, x_4) = \frac{(x_1 - x_3)(x_2 - x_4)}{(x_1 - x_4)(x_2 - x_3)} \in \mathbb{R},$$

where the differences containing the value  $\infty$  are cancelled in the event that one of the points in the quadruple is  $\infty$ . This function can be extended continuously to a  $(\mathbb{R} \cup \{\infty\})$ -valued function on the set of quadruples of points in  $\mathbb{R} \cup \{\infty\}$  of which no three coincide.

The projective cross-ratio is invariant under projective transformations of  $\mathbb{R} \cup \{\infty\}$ , and can hence also be considered as a  $(\mathbb{R} \cup \{\infty\})$ -valued function on quadruples of points on the real projective line  $\mathbb{R}P^1$ . Alternatively, it can be considered as a  $(\mathbb{R} \cup \{\infty\})$ -valued function on quadruples of 1-dimensional linear subspaces of  $\mathbb{R}^2$ , as the set of such subspaces is isomorphic to  $\mathbb{R}P^1$ .

As can be easily checked, the projective cross-ratio possesses the symmetry

$$(x_1, x_2; x_3, x_4) = \frac{1}{(x_2, x_1; x_3, x_4)},\tag{4}$$

with the values 0 and  $\infty$  being considered as reciprocal.

In the next two sections we consider the projective cross-ratio as defined on quadruples of coplanar lines through the origin, while in the example sections it will be more convenient to consider projective cross-ratios of quadruples of collinear points.

<sup>&</sup>lt;sup>1</sup>Actually, in [4, Prop. 2.3.6] it is required that K is polyhedral, but this is not used in the proof.

#### **3** 2-dimensional linear sections

In this section we prove an auxiliary result which essentially provides a construction of the optimal barrier on a 2-dimensional convex cone under the condition that the direction of the gradient of the barrier at some interior point of the cone is fixed to some value.

Let  $K \subset \mathbb{R}^n$ ,  $n \geq 2$ , be a regular convex cone,  $x^* \in K^o$  a point in the interior of K, l a line containing  $x^*$  and intersecting the boundary  $\partial K$  of the cone in the points e, y. Denote by L the 2dimensional linear hull of l and by  $l_{x^*}, l_e, l_y$  the 1-dimensional linear subspaces spanned by the vectors  $x^*, e, y$ , respectively. Let  $F : K^o \to \mathbb{R}$  be a logarithmically homogeneous self-concordant barrier on Kwith barrier parameter  $\nu$ , and define  $p^* = -F'(x^*)$ . Note that  $p^*$  is a linear functional on  $\mathbb{R}^n$ , located in the interior of the dual cone  $K^*$ . The kernel of  $p^*$  is an n-1-dimensional linear subspace  $L_{p^*} \subset \mathbb{R}^n$ , which intersects K in the origin. Denote the 1-dimensional intersection of  $L_{p^*}$  with the 2-dimensional subspace L by  $l_{p^*}$ . Then  $l_{x^*}, l_e, l_y, l_{p^*}$  are four mutually distinct coplanar lines, and we can define their projective cross-ratio  $r = (l_e, l_y; l_{x^*}, l_{p^*})$ . The arrangement of the lines implies that  $-\infty < r < 0$ .

**Lemma 3.1.** Assume above notations. Then  $\nu$  is bounded from below by  $\nu_* = \frac{2}{1 + \frac{|r+1|}{r-1}} = 1 + \max(-r, -r^{-1}).$ 

*Proof.* Let  $K_L = K \cap L$  and let  $F_L$  be the restriction of F on the interior  $K_L^o$  of  $K_L$ . Then  $F_L$  is a selfconcordant barrier for the 2-dimensional cone  $K_L$  with the same barrier parameter  $\nu$  as K. Moreover, the linear functional  $p_L^* = -F'_L(x^*)$  is the restriction of the linear functional  $p^*$  on L, and hence its kernel coincides with  $l_{p^*}$ . The assertion of the lemma for the cone K thus reduces to the assertion for the cone  $K_L$ .

In order to avoid unnecessary notations, we shall assume without restriction of generality that n = 2and hence  $K = K_L$ . Let  $\gamma_* = \frac{\nu_* - 2}{\sqrt{\nu_* - 1}} = \frac{|r+1|}{\sqrt{-r}}$  and let  $\lambda_{\pm}^* = -\frac{\gamma_*}{2} \pm \sqrt{\frac{\gamma_*^2}{4}} + 1$  be the roots of the quadratic equation  $\lambda^2 + \gamma_* \lambda - 1 = 0$ . Then  $-r\gamma_*^2 = (r+1)^2$  and hence  $r = -\frac{\gamma_*^2 + 2}{2} \pm \gamma_* \sqrt{\frac{\gamma_*^2}{4}} + 1 = -(\lambda_{\pm}^*)^2$ . Since  $\gamma_* \ge 0$ , we have  $\lambda_{-}^* \le -1$  and  $0 < \lambda_{\pm}^* \le 1$ . Therefore  $r = -(\lambda_{-}^*)^2$  if  $r \le -1$  and  $r = -(\lambda_{\pm}^*)^2$  if  $r \ge -1$ . Note that in the former case we have  $(l_y, l_e; l_{x^*}, l_{p^*}) = r^{-1} = -(\lambda_{\pm}^*)^2$  by (4). Let us now introduce a coordinate system in  $\mathbb{R}^2$  such that the lines  $l_{x^*}, l_{p^*}$  are parallel to the

Let us now introduce a coordinate system in  $\mathbb{R}^2$  such that the lines  $l_{x^*}, l_{p^*}$  are parallel to the basis vectors  $(1,0)^T, (0,1)^T$ , respectively. Let further the lines  $l_e, l_y$  be parallel to the vectors  $(1, \lambda_{\pm}^*)^T$ , respectively, if  $r \geq -1$ , and to the vectors  $(1, \lambda_{\mp}^*)^T$ , respectively, if r < -1. This is always possible because

$$(\lambda_{+}^{*},\lambda_{-}^{*};0,\infty) = \frac{(\lambda_{+}^{*}-0)(\lambda_{-}^{*}-\infty)}{(\lambda_{-}^{*}-0)(\lambda_{+}^{*}-\infty)} = \frac{\lambda_{+}^{*}}{\lambda_{-}^{*}} = -(\lambda_{+}^{*})^{2} = \begin{cases} (l_{y},l_{e};l_{x^{*}},l_{p^{*}}), & r < -1; \\ (l_{e},l_{y};l_{x^{*}},l_{p^{*}}), & r \geq -1, \end{cases}$$

and the projective cross-ratio of a quadruple of distinct lines through the origin of a plane is the only invariant of the quadruple with respect to the general linear group of this plane. Let us further scale the coordinates by a homothety such that  $x^* = (1,0)^T$ . In this coordinate system the cone K is given by the set  $\{x = (x_1, x_2)^T | x_1 \ge 0, \lambda_-^* x_1 \le x_2 \le \lambda_+^* x_1\}$ , and  $p^* = -F'(x^*) = (\nu, 0)^T$  due to the identity  $\langle p^*, x^* \rangle = \nu$  [4, eq. (2.3.13)].

Consider the 1-dimensional Lie group  $A(t) = \exp(t \cdot a) = \begin{pmatrix} 1 & 0 \\ t & 1 \end{pmatrix}$  generated by the Lie algebra element  $a = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ . Let  $x(t) = A(t)x^* = (1,t)^T$  and consider the scalar  $f(t) = \nu^{-1}F(x(t))$ . We shall now establish a differential inequality which is satisfied by the function f(t). Formulas [4, eq. (2.3.12–14)] and its derivatives yield the relations  $F'(x)[x] = -\nu$ ,  $F''(x)[x, \cdot] = -F'(x)$ ,  $F'''(x)[x, \cdot, \cdot] = -2F''(x)$ . At  $x(t) = A(t)x^*$  we thus have

$$F' = \nu A^{T}(-t) \begin{pmatrix} -1 \\ \alpha \end{pmatrix}, \quad F'' = \nu A^{T}(-t) \begin{pmatrix} 1 & -\alpha \\ -\alpha & \beta \end{pmatrix} A(-t),$$
$$F'''[A(t)h, \cdot, \cdot] = -2\nu A^{T}(-t) \left[ \begin{pmatrix} 1 & -\alpha \\ -\alpha & \beta \end{pmatrix} h_{1} + \begin{pmatrix} -\alpha & \beta \\ \beta & \mu \end{pmatrix} h_{2} \right] A(-t)$$
(5)

for some  $\alpha, \beta, \mu \in \mathbb{R}$ . Here  $\beta > \alpha^2$ , because  $F'' \succ 0$ , and  $h = (h_1, h_2)^T \in \mathbb{R}^2$  is an arbitrary vector. Condition (1), applied to the vector A(t)h, then yields

$$-h_1^3 + 3\alpha h_1^2 h_2 - 3\beta h_1 h_2^2 - \mu h_2^3 \le \sqrt{\nu} (h_1^2 - 2\alpha h_1 h_2 + \beta h_2^2)^{3/2}$$

Setting  $h = (\alpha - \sqrt{\frac{\beta - \alpha^2}{\nu - 1}}, 1)^T$ , we obtain after some calculations

$$-(\alpha^3 + 3\alpha(\beta - \alpha^2) + \mu) \le \gamma(\beta - \alpha^2)^{3/2},\tag{6}$$

where  $\gamma = \frac{\nu - 2}{\sqrt{\nu - 1}}$ . Let us compute the derivatives of f(t). By (5) and using the fact that  $\dot{x} = (0, 1)^T$  is constant, we have

$$\dot{f} = \nu^{-1} F'(x)[ax] = \alpha, \quad \ddot{f} = \nu^{-1} F''(x)[ax, ax] = \beta, \quad f^{(3)} = \nu^{-1} F'''(x)[ax, ax, ax] = -2\mu.$$

Inserting this into (6), we get

$$4\dot{f}^3 - 6\dot{f}\ddot{f} + f^{(3)} \le 2\gamma(\ddot{f} - \dot{f}^2)^{3/2}.$$
(7)

We would like to bound the function f(t) by the solution of the differential equation which is obtained when one assumes equality in (7). This is accomplished by introducing the variables  $q_{\pm} = -\frac{\sqrt{\ddot{f}-\dot{f}^2}}{\lambda_{\mp}} - \dot{f}$ , where  $\lambda_{\pm} = -\frac{\gamma}{2} \pm \sqrt{\frac{\gamma^2}{4} + 1}$  are the roots of the quadratic equation  $\lambda^2 + \gamma \lambda - 1 = 0$ . These variables satisfy the relation  $q_+ > q_-$  and  $\dot{f}, \ddot{f}$  can be recovered from them by the formula

$$\dot{f} = -\frac{\lambda_+}{\lambda_+ - \lambda_-}q_- + \frac{\lambda_-}{\lambda_+ - \lambda_-}q_+, \qquad \ddot{f} = \frac{\lambda_+}{\lambda_+ - \lambda_-}q_-^2 - \frac{\lambda_-}{\lambda_+ - \lambda_-}q_+^2. \tag{8}$$

We have  $\ddot{f} - \dot{f}^2 = \frac{(q_+ - q_-)^2}{\gamma^2 + 4}$ , and hence  $(\ddot{f} - \dot{f}^2)^{3/2} = \frac{(q_+ - q_-)^3}{(\gamma^2 + 4)^{3/2}}$ . A simple calculus then shows that  $2\gamma(\ddot{f} - \dot{f}^2)^{3/2} - 4\dot{f}^3 + 6\dot{f}\ddot{f} = -\frac{2\lambda_+}{\lambda_+ - \lambda_-}q_-^3 + \frac{2\lambda_-}{\lambda_+ - \lambda_-}q_+^3$  and hence by (7)

$$f^{(3)} \leq -\frac{2\lambda_+}{\lambda_+ - \lambda_-} q_-^3 + \frac{2\lambda_-}{\lambda_+ - \lambda_-} q_+^3.$$
<sup>(9)</sup>

Recall that  $p^* = (\nu, 0)^T$  and hence  $\dot{f}(0) = 0$ . Hence by (8) we have

$$\lambda_{+}q_{-}(0) = \lambda_{-}q_{+}(0). \tag{10}$$

Differentiating the first relation in (8) with respect to t and expressing  $\ddot{f}$  by the second relation, we obtain

$$\frac{\lambda_{+}}{\lambda_{+} - \lambda_{-}} (q_{-}^{2} + \dot{q}_{-}) - \frac{\lambda_{-}}{\lambda_{+} - \lambda_{-}} (q_{+}^{2} + \dot{q}_{+}) = 0.$$
(11)

Differentiating the second relation in (8) and inserting into (9) yields the inequality

$$\frac{\lambda_{+}}{\lambda_{+} - \lambda_{-}} q_{-} (q_{-}^{2} + \dot{q}_{-}) - \frac{\lambda_{-}}{\lambda_{+} - \lambda_{-}} q_{+} (q_{+}^{2} + \dot{q}_{+}) \le 0.$$
(12)

Combining (11) with (12) yields

$$\frac{\lambda_+}{\lambda_+ - \lambda_-} (q_- - q_+)(q_-^2 + \dot{q}_-) \le 0, \quad \frac{\lambda_-}{\lambda_+ - \lambda_-} (q_- - q_+)(q_+^2 + \dot{q}_+) \le 0,$$

which by the relation  $q_+ > q_-$  gives

$$q_{-}^2 + \dot{q}_{-} \ge 0, \qquad q_{+}^2 + \dot{q}_{+} \le 0.$$
 (13)

The solution of the differential equation  $q^2 + \dot{q} = 0$  is given by  $q(t) = \frac{1}{t+q^{-1}(0)}$ . The differential inequalities (13) then yield the bounds

$$q_{-}(t) \ge \frac{1}{t + q_{-}^{-1}(0)}, \quad t \ge 0; \qquad q_{+}(t) \ge \frac{1}{t + q_{+}^{-1}(0)}, \quad t \le 0.$$
 (14)

By (10) and the condition  $q_+ > q_-$  we have  $q_-(0) < 0$  and  $q_+(0) > 0$ . Note that  $\lim_{t\to\lambda^*_+} f(t) = +\infty$ , hence by convexity of f we have  $\lim_{t\to\lambda^*_+} \dot{f}(t) = +\infty$  and  $\lim_{t\to\lambda^*_+} q_-(t) = -\infty$ . The right-hand side in the first relation in (14) tends to  $-\infty$  for  $t \to -q_-^{-1}(0)$ , and hence  $\lambda^*_+ \ge -q_-^{-1}(0)$ . Likewise,  $\lim_{t\to\lambda^*_-} f(t) = +\infty$ , hence  $\lim_{t\to\lambda^*_-} \dot{f}(t) = -\infty$  and  $\lim_{t\to\lambda^*_-} q_+(t) = +\infty$ . The right-hand side in the second relation in (14) tends to  $+\infty$  for  $t \to -q_+^{-1}(0)$ , and hence  $\lambda^*_- \ge -q_+^{-1}(0)$ .

We thus get  $\frac{\lambda_{+}^{*}}{\lambda_{+}} \ge -\frac{1}{\lambda_{+}q_{-}(0)}, -\frac{\lambda_{-}^{*}}{\lambda_{-}} \ge \frac{1}{\lambda_{-}q_{+}(0)}$ . Combining with (10), this yields  $\frac{\lambda_{+}^{*}}{\lambda_{+}} \ge \frac{\lambda_{-}^{*}}{\lambda_{-}}$ . Finally, inserting the values  $\lambda_{-} = -\sqrt{\nu - 1}, \lambda_{+} = \frac{1}{\sqrt{\nu - 1}}, \lambda_{-}^{*} = -\sqrt{\nu_{*} - 1}, \lambda_{+}^{*} = \frac{1}{\sqrt{\nu_{*} - 1}}$ , we arrive at the desired conclusion.

**Corollary 3.2.** Let  $K \subset \mathbb{R}^n$ ,  $n \geq 2$ , be a regular convex cone, and  $F : K^o \to \mathbb{R}$  a logarithmically homogeneous self-concordant barrier on K with barrier parameter  $\nu$ . Then  $\nu \geq 2$ .

If n = 2 and the bound on the barrier parameter given by Lemma 3.1 is saturated, then  $\lambda_{+}^{*} = \lambda_{+} = -q_{-}^{-1}(0)$  and  $\lambda_{-}^{*} = \lambda_{-} = -q_{+}^{-1}(0)$ . Inequalities (14) must be saturated too and  $\dot{f}(t) = -\frac{\lambda_{+}}{\lambda_{+} - \lambda_{-}} \frac{1}{t - \lambda_{+}} + \frac{\lambda_{-}}{\lambda_{+} - \lambda_{-}} \frac{1}{t - \lambda_{-}}$ . This can be integrated, yielding  $f(t) = -\frac{\lambda_{+}}{\lambda_{+} - \lambda_{-}} \log(t - \lambda_{+}) + \frac{\lambda_{-}}{\lambda_{+} - \lambda_{-}} \log(t - \lambda_{-}) + const$ , thus determining the barrier F up to an additive constant. It is not hard to check that F is invariant under the action of the Lie group  $\exp(t \cdot a)$  generated by the Lie algebra element  $a = \begin{pmatrix} 0 & 1 \\ 1 & -\gamma \end{pmatrix}$ . This group acts transitively on the set of rays constituting the interior of the cone K, and hence the expression  $\nu_{*}$  in Lemma 3.1 is independent of the choice of the interior point  $x^{*}$  in this case.

#### 4 Main result

In this section a lower bound on the barrier parameter  $\nu$  for a logarithmically homogeneous selfconcordant barrier  $F: K^o \to \mathbb{R}$  on a given regular convex cone  $K \subset \mathbb{R}^n$  is obtained from Lemma 3.1 by the following consideration. Let  $x^* \in K^o$  be an interior point of K, denote  $p^* = -F'(x^*)$ , and let  $L_1, \ldots, L_m$  be 2-dimensional linear subspaces containing  $x^*$ . For fixed  $p^*$  and for each  $i = 1, \ldots, m$ , application of Lemma 3.1 to the intersection  $K_{L_i} = L_i \cap K$  gives rise to a lower bound  $\nu_i^*(p^*)$  on  $\nu$ , and hence  $\nu \geq \max_{i=1,\ldots,m} \nu_i^*(p^*)$ . If m is smaller than the dimension n of the cone K, then for subspaces  $L_1, \ldots, L_m$  in general position  $p^*$  can be chosen such that  $\max_{i=1,\ldots,m} \nu_i^*(p^*) = 2$ , and no information is gained with respect to Corollary 3.2. If, however,  $m \geq n$ , then  $\min_{p^*} \max_{i=1,\ldots,m} \nu_i^*(p^*) > 2$  in general, except in the case that K is the Lorentz cone. The goal of this section is to solve the minimax problem  $\min_{p^*} \max_{i=1,\ldots,m} \nu_i^*(p^*)$  for the case m = n. We will work under the following assumption.

**Assumption 4.1.** Let  $K \subset \mathbb{R}^n$  be a regular convex cone, let  $x^* = (x_1^*, \ldots, x_n^*)^T \in K^o$ , and let  $L_1, \ldots, L_n \subset \mathbb{R}^n$  be 2-dimensional linear subspaces containing  $x^*$ . Assume that there exist linearly independent vectors  $e_i \in L_i \cap \partial K$ ,  $i = 1, \ldots, n$ , and let  $y_i \in L_i \cap \partial K$  be such that  $L_i = \text{span}\{e_i, y_i\}$ ,  $i = 1, \ldots, n$ . Let  $l_k$  be the line through the points  $e_k$  and  $y_k$ , and let  $z_k$  be the intersection point of  $l_k$  with the (n-1)-dimensional linear subspace  $\hat{L}_k$  spanned by all points  $e_l$ ,  $l = 1, \ldots, n$  except  $e_k$ . Let  $l_{e_k}, l_{y_k}, l_{z_k}$ , and  $l_{x^*}$  be the linear hulls of  $e_k, y_k, z_k$ , and  $x^*$ , respectively. Then for each  $k = 1, \ldots, n$  the 4 lines  $l_{e_k}, l_{y_k}, l_{z_k}, l_{x^*}$  are in  $L_k$  and hence coplanar, and no three of them are identical. Let  $q_k = [l_{e_k}, l_{x^*}; l_{y_k}, l_{z_k}]$  be their projective cross-ratio.

Now let  $F: K^o \to \mathbb{R}$  be a logarithmically homogeneous self-concordant barrier with parameter  $\nu$ , set  $p^* = -F'(x^*)$ , and let  $l_{p_k^*}$  be the 1-dimensional intersection of the plane  $L_k$  with the kernel of the linear functional  $p^*$ . We shall express the projective cross-ratio  $r_k = [l_{e_k}, l_{y_k}; l_{x^*}, l_{p_k^*}]$ , which determines the bound  $\nu_k^*(p^*)$  from Lemma 3.1, in terms of the projective cross-ratios  $q_k$  and the linear functional  $p^*$ .

Introduce a coordinate system in  $\mathbb{R}^n$  with basis vectors equal to  $e_k$ . Let  $p_k^*$  be the elements of  $p^*$  in these coordinates. Note that  $p^*$  is in the interior of the dual cone  $K^*$ , and hence  $\langle p^*, e_k \rangle = p_k^* > 0$  for all  $k = 1, \ldots, n$ .

In each of the planes  $L_k$ , consider the affine line  $\tilde{l}_k$  through  $x^*$  which is parallel to  $l_{e_k}$ . Introduce a real parameter  $\lambda$  on  $\tilde{l}_k$ , putting the number  $\lambda$  in correspondence with the point  $x^* + \lambda e_k$ . Then the intersection point of  $\tilde{l}_k$  with  $l_{e_k}$  is the infinitely remote point and can be assigned the parameter  $\lambda = +\infty$ . The intersection point of  $\tilde{l}_k$  with  $l_{x^*}$  has parameter value  $\lambda = 0$ . The coordinate vector of the intersection point of  $\tilde{l}_k$  with  $l_{z_k}$  has a zero at its k-th entry and thus has parameter value  $\lambda = -x_k^*$ . Let  $\lambda_k$  be the parameter value corresponding to the intersection point of  $\tilde{l}_k$  with  $l_{y_k}$ . Since the segment of  $\tilde{l}_k$  corresponding to the parameter values  $\lambda \in [0, \infty)$  lies in the interior of K, we have  $\lambda_k < 0$ . Finally, the intersection point of  $\tilde{l}_k$  with  $l_{p_k^*}$  is given by the equation  $\langle p^*, x^* + \lambda e_k \rangle = 0$ , which yields the value  $\hat{\lambda}_k = -\frac{\langle p^*, x^* \rangle}{p_k^*}$  for the parameter of this intersection point. Note that  $\hat{\lambda}_k < \lambda_k$ , because  $p^*$  has to be positive on  $y_k$ . We then obtain the projective cross-ratios

$$q_k = [l_{e_k}, l_{x^*}; l_{y_k}, l_{z_k}] = \frac{(\infty - \lambda_k)(0 - (-x_k^*))}{(\infty - (-x_k^*))(0 - \lambda_k)} = -\frac{x_k^*}{\lambda_k},$$
(15)

$$r_{k} = [l_{e_{k}}, l_{y_{k}}; l_{x^{*}}, l_{p_{k}^{*}}] = \frac{(\infty - 0)(\lambda_{k} - \hat{\lambda}_{k})}{(\infty - \hat{\lambda}_{k})(\lambda_{k} - 0)} = 1 - \frac{\hat{\lambda}_{k}}{\lambda_{k}} = 1 + \frac{\langle p^{*}, x^{*} \rangle}{p_{k}^{*} \lambda_{k}},$$
(16)

from which we get

1

$$\frac{r_k + 1}{r_k - 1} = 1 + \frac{2p_k^* \lambda_k}{\langle p^*, x^* \rangle}.$$
(17)

**Lemma 4.2.** The relation  $\sum_{k:q_k>0} q_k > 1$  holds.

*Proof.* Let  $I_{+} = \{k \mid q_k > 0\}$  and  $Q_{+} = \sum_{k \in I_{+}} q_k$ .

If  $I_+ = \emptyset$ , then  $x^*$  is in the nonpositive orthant by (15). Thus  $-x^*$  is also in K as a linear combination of the basis vectors  $e_k$  with nonnegative coefficients. This contradicts the regularity of K.

Hence  $I_+ \neq \emptyset$ . For every  $k, x^* + \lambda_k e_k$  is a positive multiple of  $y_k$  and hence equals a nonzero vector in  $\partial K$ . Consider the point  $s = \sum_{k \in I_+} q_k(x^* + \lambda_k e_k) = (Q_+ - 1)x^* + (x^* - \sum_{k \in I_+} x_k^* e_k)$ , where the second relation comes from (15). As a linear combination of nonzero elements in K, with positive coefficients, the point s is also a nonzero vector in K. The vector  $x^* - \sum_{k \in I_+} x_k^* e_k$  has only nonpositive components and is hence in -K. It follows that  $(Q_+ - 1)x^* = s - (x^* - \sum_{k \in I_+} x_k^* e_k)$  is a nonzero vector in K, which implies  $Q_+ > 1$  and proves the lemma.

By Lemma 3.1, the barrier parameter  $\nu$  of the barrier F is bounded from below by the expression  $\max_{k=1,\dots,n} \frac{2}{1-\left|\frac{r_k+1}{r_k-1}\right|}$ . This bound still depends on the negative gradient  $p^*$  of F at  $x^*$ . A lower bound on the barrier parameter of an arbitrary logarithmically homogeneous self-concordant barrier on K is then given by

$$\nu_* = \min_{p^*} \max_k \frac{2}{1 - \left|\frac{r_k + 1}{r_k - 1}\right|} = \frac{2}{1 - \min_{p^*} \max_k \left|\frac{r_k + 1}{r_k - 1}\right|},\tag{18}$$

where  $p^*$  is subject to the constraints  $\langle p^*, e_k \rangle > 0$ ,  $\langle p^*, y_k \rangle > 0$  for all k = 1, ..., n. By (17) this transforms into

$$\nu_* = \frac{2}{1 - \min_{p^*} \max_k \left| 1 + \frac{2p_k^* \lambda_k}{\langle p^*, x^* \rangle} \right|},\tag{19}$$

where the components of  $p^*$  have to satisfy the requirements  $p_k^* > 0$  and  $-\frac{\langle p^*, x^* \rangle}{p_k^*} = \hat{\lambda}_k < \lambda_k$ . Equivalently,  $0 < \frac{p_k^*}{\langle p^*, x^* \rangle} < -\frac{1}{\lambda_k}$ .

Introduce variables  $\alpha_k = 1 + \frac{2p_k^*\lambda_k}{\langle p^*, x^* \rangle} \in (-1, 1)$ . These variables have to satisfy the additional requirement  $\sum_{k=1}^n \frac{\alpha_k - 1}{2\lambda_k} x_k^* = 1$ , which by (15) is equivalent to  $\sum_{k=1}^n \frac{1 - \alpha_k}{2} q_k = 1$ . We shall now solve the minimax problem

$$\min\left\{\max_{k} |\alpha_{k}| \ \left| \ \alpha_{k} \in (-1,1), \ \sum_{k=1}^{n} \frac{1-\alpha_{k}}{2} q_{k} = 1 \right. \right\}.$$
(20)

**Lemma 4.3.** The value of problem (20) is given by  $\frac{\left|\sum_{k} q_{k}-2\right|}{\sum_{k} |q_{k}|} < 1.$ 

*Proof.* First note that  $\sum_{k} |q_k| \ge \sum_{k} q_k$  and hence  $\sum_{k} q_k - 2 < \sum_{k} |q_k|$ . On the other hand, by Lemma 4.2 we have  $\sum_{k} (q_k + |q_k|) > 2$  and hence  $2 - \sum_{k} q_k < \sum_{k} |q_k|$ . It follows that  $\frac{|\sum_{k} q_k - 2|}{\sum_{k} |q_k|} \in [0, 1)$ . It is easily checked that this value is attained by the solution  $\alpha_k = \alpha_k^* = \frac{\sum_{k} q_k - 2}{\sum_{k} |q_k|} \operatorname{sgn} q_k \in (-1, 1)$ .

On the other hand, every feasible vector  $\alpha = (\alpha_1, \dots, \alpha_n)^T$  has to satisfy the constraint  $\sum_k \alpha_k q_k = \sum_k q_k - 2$ . It follows that  $(\max_k |\alpha_k|) \sum_k |q_k| \ge \sum_k |\alpha_k| |q_k| \ge |\sum_k q_k - 2|$ , which yields  $\max_k |\alpha_k| \ge \frac{|\sum_k q_k - 2|}{\sum_k |q_k|}$  and thus proves optimality of the solution  $\alpha_k = \alpha_k^*$ .

Inserting the optimal value of (20) into (19), we obtain the following theorem.

**Theorem 4.4.** Under Assumption 4.1, the barrier parameter  $\nu$  of any logarithmically homogeneous self-concordant barrier F on the cone K is bounded from below by the quantity

$$\nu_* = \frac{2}{1 - \frac{|\sum_k q_k - 2|}{\sum_k |q_k|}}.$$

#### 5 Properties of the lower bound

In this section we will consider the bound given by Theorem 4.4 in more detail.

**Lemma 5.1.** Assume the conditions of Assumption 4.1. Let  $I \subset \{1, ..., n\}$  be such that the vectors in the set  $\{y_k | k \in I\} \cup \{e_k | k \notin I\}$  are linearly independent. Then the bound in Theorem 4.4 is invariant under an interchange of the points  $e_k$  and  $y_k$  for all  $k \in I$ .

Proof. The exchange of  $y_k$  and  $e_k$  leaves the subspace  $L_k$  and the line  $l_{p_k^*}$  invariant and hence by (4) leads to the transformation  $r_k \mapsto r_k^{-1}$  in (16). This in turn leads to the transformation  $\frac{r_k+1}{r_k-1} \mapsto -\frac{r_k+1}{r_k-1}$ . The set of constraints  $\langle p^*, e_k \rangle > 0$ ,  $\langle p^*, y_k \rangle > 0$  is also left invariant, and hence by (18) the value of  $\nu_*$  is left unchanged.

Remark 5.2. The assertion of Lemma 5.1 cannot be easily inferred directly from the explicit expression of the bound  $\nu_*$  in Theorem 4.4, because the exchange of  $e_k$  and  $y_k$  for one index k changes the lines  $l_{z_l}$  for all  $l \neq k$  and hence all projective cross-ratios  $q_l$  in (15) are changed.

**Lemma 5.3.** Assume the conditions of Assumption 4.1. There exists a subset  $I \subset \{1, ..., n\}$  of indices with complement  $\overline{I}$  such that the set  $\{e_k | k \in \overline{I}\} \cup \{y_k | k \in I\}$  is linearly independent, and  $x^*$  is a linear combination of the vectors in this set with nonnegative coefficients.

*Proof.* The assertion of the lemma will follow from the statement that we can render all entries of  $x^*$  nonnegative by exchanging the vectors  $e_k$  and  $y_k$  for a number of indices k and adapting the coordinate system accordingly. Let us prove this statement.

Suppose there exists an index k such that  $x_k^* < 0$ . Recall that  $z_k$  is the unique point on  $l_k$  situated in the linear subspace  $\hat{L}_k$  spanned by all  $e_l$  except  $e_k$ . Therefore, linear dependence of the vectors  $e_1, \ldots, e_{k-1}, y_k, e_{k+1}, \ldots, e_n$  is equivalent to the relation  $z_k = y_k$ . Since  $x_k^* < 0$ , the line  $l_{x^*}$  intersects  $l_k$  in a point opposite to  $e_k$  with respect to  $z_k$ . But  $y_k$  is opposite to  $e_k$  with respect to  $l_{x^*}$  in  $L_k$ , hence  $z_k \neq y_k$ . This proves that we can exchange the roles of  $e_k$  and  $y_k$  without violating the condition of linear independence of the points  $e_l$ .

Assume without restriction of generality that  $x^*$  is situated on the line segment between  $e_k$  and  $y_k$ . This is equivalent to multiplication of  $x^*$  by a positive constant and does not change the signs of the entries  $x_k^*$ . We have the explicit expression  $z_k = \frac{x^* - x_k^* e_k}{1 - x_k^*}$ , deriving from the condition that  $z_k$  is the affine combination of  $e_k$  and  $x^*$  whose k-th entry vanishes. On the other hand, we have  $y_k = \frac{x^* + \lambda_k e_k}{1 + \lambda_k}$ , deriving from the condition that  $y_k$  is the affine combination of  $e_k$  and  $x^*$  which is a multiple of  $x^* + \lambda_k e_k$ . It follows that

$$x^{*} = \frac{x_{k}^{*}(1+\lambda_{k})}{\lambda_{k}+x_{k}^{*}}y_{k} + \frac{\lambda_{k}(1-x_{k}^{*})}{\lambda_{k}+x_{k}^{*}}z_{k} = \frac{x_{k}^{*}(1+\lambda_{k})}{\lambda_{k}+x_{k}^{*}}y_{k} + \frac{\lambda_{k}}{\lambda_{k}+x_{k}^{*}}(x^{*}-x_{k}^{*}e_{k}).$$
(21)

Note that  $x^* - x_k^* e_k$  is a linear combination of the points  $e_1, \ldots, e_{k-1}, e_{k+1}, \ldots, e_n$ , with coefficients being equal to the corresponding entries of  $x^*$ . From (21) it then follows that the coefficients  $\tilde{x}_l^*$  of  $x^*$ , when expressed as a linear combination of the vectors  $e_1, \ldots, e_{k-1}, y_k, e_{k+1}, \ldots, e_n$ , are given by

$$\tilde{x}_k^* = \frac{x_k^*(1+\lambda_k)}{\lambda_k + x_k^*}, \qquad \tilde{x}_l^* = \frac{\lambda_k}{\lambda_k + x_k^*} x_l^*, \ l \neq k.$$

Since  $x^*$  is situated between  $y_k$  and  $z_k$  on the line  $l_k$  and is different from these points, we have by (21) that  $\frac{x_k^*(1+\lambda_k)}{\lambda_k+x_k^*} > 0$ ,  $\frac{\lambda_k(1-x_k^*)}{\lambda_k+x_k^*} > 0$ , and hence also  $\frac{\lambda_k}{\lambda_k+x_k^*} > 0$ . Therefore the sign of  $\tilde{x}_l^*$  equals that of  $x_l^*$  for  $l \neq k$ , while  $\tilde{x}_k^*$  is positive.

As a consequence, exchanging  $e_k$  and  $y_k$  has lead to a decrease in the number of negative entries of  $x^*$  by one. Repeating this process, we can eliminate all negative entries of  $x^*$ .

**Theorem 5.4.** In addition to Assumption 4.1, suppose that  $x^*$  is contained in the simplicial cone generated by the vectors  $e_k$ . Then the lower bound in Theorem 4.4 is given by

$$\nu_* = \begin{cases} \frac{\sum_k q_k}{\sum_k q_{k-1}}, & \sum_k q_k \le 2;\\ \sum_k q_k, & \sum_k q_k \ge 2. \end{cases}$$
(22)

*Proof.* Choose a coordinate system in  $\mathbb{R}^n$  with basis vectors  $e_k$ ,  $k = 1, \ldots, n$ . Then by assumption of the theorem all entries of  $x^*$  are nonnegative, and by (15) all projective cross-ratios  $q_k$  are nonnegative. Then the bound in Theorem 4.4 simplifies to (22).

We now consider the situation when  $q_k = 0$  for some k. In this case  $x^* = z_k$  is contained in the (n-1)-dimensional linear subspace  $\hat{L}_k \subset \mathbb{R}^n$  spanned by all  $e_l$  except  $e_k$ . For every  $l \neq k$ , since both  $e_l, x^*$  are in  $\hat{L}_k$ , we also have  $y_l \in \hat{L}_k$ . We can then apply the construction of the previous section to the n-1 2-dimensional subspaces  $L_1, \ldots, L_{k-1}, L_{k+1}, \ldots, L_n$  of the n-1-dimensional cone  $\tilde{K} = K \cap \hat{L}_k$ . Since all  $q_l, l \neq k$ , retain their values in the lower-dimensional space, and  $\sum_{l=1}^n q_l = \sum_{l \neq k} q_l$ ,  $\sum_{l=1}^n |q_l| = \sum_{l \neq k} |q_l|$  by  $q_k = 0$ , Theorem 4.4 will yield the same bound  $\nu_*$  for the cone  $\tilde{K}$  as it has for the cone K. In other words, in the case  $q_k = 0$  the bound given by Theorem 4.4 for the cone K is essentially a consequence of a similar bound for the cone  $\tilde{K}$ , which is a linear section of K with codimension 1.

**Lemma 5.5.** Assume the conditions of Theorem 5.4. Then for all k = 1, ..., n we have  $q_k \leq 1$ , and for all index sets  $I \subset \{1, ..., n\}$  of cardinality n - 1 we have  $\sum_{k \in I} q_k \geq 1$ .

Proof. Assume the notations of the previous section. Since the simplicial cone  $K_S$  generated by the vectors  $e_k$  is contained in K, the interval  $I_S = l_k \cap K_S$  is contained in the interval  $I_K = l_k \cap K$  for every  $k = 1, \ldots, n$ . Note that  $y_k$  is the endpoint of  $I_K$  opposite to  $e_k$ , while  $z_k$  is the endpoint of  $I_S$  opposite to  $e_k$ . Hence  $y_k$  is situated on  $l_k$  opposite to  $e_k$  with respect to  $z_k$  (but it may coincide with  $z_k$ ). Recall that the parameter of the intersection point of  $l_{e_k}$  with  $\tilde{l}_k$  was  $\lambda = +\infty$ , the intersection point of  $l_{z_k}$  with  $\tilde{l}_k$  had parameter  $\lambda = -x_k^*$ , and the intersection point of  $l_{y_k}$  with  $\tilde{l}_k$  had parameter  $\lambda = \lambda_k$ . Therefore  $\lambda_k \leq -x_k^*$ , which by (15) yields  $q_k \leq 1$ .

Let us prove the second part by contradiction. Suppose there exists a subset  $I \subset \{1, \ldots, n\}$  of n-1 indices such that  $\sum_{k \in I} q_k < 1$ . For  $l \in I$ , define  $a_l = \frac{q_l}{1 - \sum_{k \in I} q_k} \ge 0$ . We then have

$$x^* + \sum_{l \in I} a_l (1 + \lambda_l) y_l = x^* + \sum_{l \in I} \frac{q_l}{1 - \sum_{k \in I} q_k} (x^* + \lambda_l e_l) = \frac{1}{1 - \sum_{k \in I} q_k} \left( x^* - \sum_{l \in I} x_l^* e_l \right),$$

where for the second equality we used (15). The leftmost side is the sum of an interior point of K and boundary points of K and is hence also an interior point of K. On the other hand, the rightmost side is proportional to  $e_{\hat{k}}$ , where  $\hat{k}$  is the index missing in I, and is hence a boundary point of K. This leads to a contradiction, thus proving the lemma.

**Corollary 5.6.** Assume the conditions of Theorem 5.4. Then the bound given in Theorem 4.4 satisfies  $\nu_* \leq n$ . The equality  $\nu_* = n$  holds if and only if K is either a simplicial cone with generators  $e_1, \ldots, e_n$ , or a simplicial cone with generators  $y_1, \ldots, y_n$ .

*Proof.* By (22) the first assertion of the corollary is equivalent to the inequalities

$$\frac{n}{n-1} \le \sum_{k} q_k \le n.$$

These can be obtained by summing the inequalities  $q_k \leq 1$ ,  $\sum_{k \in I} q_k \geq 1$  from Lemma 5.5 over all indices k or all index sets I of cardinality n-1, respectively.

Assume now that  $\nu_* = n$ . By (22) we then have either  $\sum_k q_k = \frac{n}{n-1}$  or  $\sum_k q_k = n$ .

Let us consider the first case. By Lemma 5.5 we have  $q_k = \frac{1}{n-1}$  for all k, and hence  $\lambda_k = -(n-1)x_k^*$ . Note that  $y_k$  is a positive multiple of the point  $x^* + \lambda_k e_k$ , hence  $y_k = \beta_k (x^* - (n-1)x_k^* e_k)$ ,  $\beta_k > 0$  for all k. Let  $\hat{k} \in \{1, \ldots, n\}$  and  $I = \{1, \ldots, n\} \setminus \{\hat{k}\}$ . Then we have

$$\sum_{k \in I} \beta_k^{-1} y_k = \sum_{k \in I} (x^* - (n-1)x_k^* e_k) = (n-1)x_{\hat{k}}^* e_{\hat{k}},$$

and  $e_{\hat{k}}$  is contained in the relative interior of the convex cone generated by the set  $\{y_k | k \in I\}$ . But  $e_{\hat{k}} \in \partial K$ , which implies that this cone is entirely contained in  $\partial K$ . Repeating this argument for all  $\hat{k}$ , we see that the boundary of the simplicial cone generated by the  $y_k$  is contained in  $\partial K$ . On the other hand,  $\sum_{k=1}^{n} \beta_k^{-1} y_k = \sum_{k=1}^{n} (x^* - (n-1)x_k^* e_k) = x^* \in K^o$ , which implies that the points  $y_k$  are linearly independent and that K equals the cone generated by the  $y_k$ .

We now pass to the case  $\sum_k q_k = n$ . By Lemma 5.5 we have  $q_k = 1$  for all k. This is equivalent to the relations  $y_k = z_k$ , and  $y_k$  is contained in the cone generated by the set  $\{e_l \mid l \neq k\}$  for all k. Moreover, it follows that  $z_k \in \partial K$  and hence  $z_k \neq x^*$ , which implies  $x_k^* > 0$  for all k. By  $\lambda_k = -x_k^*$ we then have that  $y_k$  is a positive multiple of  $x^* - x_k^* e_k = \sum_{l \neq k} x_l^* e_l$ , and  $y_k$  is in the relative interior of the cone generated by the set  $\{e_l \mid l \neq k\}$ . As in the previous paragraph, this whole cone must then be in  $\partial K$  for all k, and  $\partial K$  contains the boundary of the simplicial cone generated by the  $e_k$ . Thus K equals this simplicial cone. This proves one direction of the equivalence asserted in the second part of the corollary.

Let us prove the opposite direction. Assume that K is a simplicial cone generated by either the vectors  $e_k$  or the vectors  $y_k$ . By possibly exchanging the roles of  $e_k$  and  $y_k$  for all k, we by virtue of Lemma 5.1 can assume that K is generated by the  $e_k$ . The line  $l_k$  intersects  $\partial K$  in  $e_k$  and in the face opposite to  $e_k$ , which implies that the second intersection point  $y_k$  coincides with  $z_k$ . But then  $\lambda_k = -x_k^*$  and  $q_k = 1$  for all k, which by (22) yields the assertion to be proven.

**Theorem 5.7.** Assume the conditions of Assumption 4.1. The lower bound  $\nu_*$  given in Theorem 4.4 cannot exceed the dimension n of the cone K. The equality  $\nu_* = n$  holds if and only if K is a simplicial cone with generators  $\tilde{e}_1, \ldots, \tilde{e}_n$  such that  $\tilde{e}_k \in \{e_k, y_k\}$  for every  $k = 1, \ldots, n$ .

*Proof.* The theorem is a consequence of Lemmas 5.1, 5.3, and Corollary 5.6.

#### 6 Relation with Nesterovs and Nemirovskis bound

In this section we deduce the lower bound of Nesterov and Nemirovski, applied to convex cones, from our result. Proposition 2.3.6 in [4] states that if  $C \subset \mathbb{R}^n$  is a convex polytope and  $e_n \in \partial C$  is a boundary point belonging to exactly k (n-1)-dimensional faces of C, such that the normal vectors to these faces are linearly independent, then k is a lower bound on the barrier parameter of any selfconcordant barrier on C. We are interested in the situation when C is a cone and prove the following slightly stronger result for this case.

**Theorem 6.1.** Let  $K \subset \mathbb{R}^n$ ,  $n \geq 3$ , be a regular polyhedral convex cone, let  $e_{k+1} \in \partial K$  be a nonzero boundary point belonging to exactly k (n-1)-dimensional faces of K,  $2 \leq k \leq n-1$ , such that the normals to these faces are linearly independent. Then  $\nu_* = k + 1$  is a lower bound on the barrier parameter of any logarithmically homogeneous self-concordant barrier on K.

*Proof.* By an appropriate choice of coordinates, we can assume that  $e_{k+1} = (1, 0, ..., 0)^T$ , the set  $\{x = (x_0, ..., x_{n-1})^T \in K \mid x_0 = 1\}$  is a compact section of K, and there exists a neighbourhood U of  $e_{k+1}$  such that  $x \in U \cap K$  if and only if  $x \in U$  and  $x_j \leq 0, j = 1, ..., k$ . Let us further assume without restriction of generality that k = n - 1, otherwise we replace the cone K by the (k + 1)-dimensional intersection  $K \cap L$ , where  $L \subset \mathbb{R}^n$  is the (k+1)-dimensional linear subspace determined by the equations  $x_{k+1} = \cdots = x_{n-1} = 0$ .

Set  $x^* = (1, -\varepsilon, \dots, -\varepsilon)^T$ ,  $e_j = (1, -\varepsilon, \dots, -\varepsilon, 0, -\varepsilon, \dots, -\varepsilon)^T$ ,  $j = 1, \dots, n-1$ , where the zero is located at position j. For small enough  $\varepsilon > 0$  we then have  $x^* \in K^o$ ,  $e_j \in \partial K$ ,  $j = 1, \dots, n$ . Let further  $l_j$  be the line through  $x^*$  and  $e_j$  and let  $y_j$  be the intersection point of  $l_j$  with  $\partial K$ opposite to  $e_j$ ,  $j = 1, \dots, n$ . We then have  $y_j = (1, -\varepsilon, \dots, -\varepsilon, -\alpha_j, -\varepsilon, \dots, -\varepsilon)^T$  for  $j = 1, \dots, n-1$ ,  $y_n = (1, -\alpha_n, \dots, -\alpha_n)^T$ , and  $\lim_{\varepsilon \to 0} \alpha_j > 0$  for all  $j = 1, \dots, n$ . For  $i \in \{1, \dots, n\}$ , denote by  $\hat{L}_i \subset \mathbb{R}^n$ the (n-1)-dimensional linear subspace spanned by all  $e_j$  except  $e_i$ , and let  $z_i$  be the intersection point of  $\hat{L}_i$  with the line  $l_i$ . It is not hard to check that  $z_i = (1, -\varepsilon, \dots, -\varepsilon, -\beta_i, -\varepsilon, \dots, -\varepsilon)^T$ ,  $i = 1, \dots, n-1$ ,  $z_n = (1, -\beta_n, \dots, -\beta_n)^T$  with  $\beta_i = \varepsilon \frac{n-2}{n-3}$ ,  $i = 1, \dots, n-1$ , and  $\beta_n = \varepsilon \frac{n-2}{n-1}$ . For n = 3 the line  $l_i$  does not intersect  $L_i$ , i = 1, 2, and we set  $\beta_1 = \beta_2 = \infty$  in this case.

The projective cross-ratios (15) are then given by

$$q_j = [0, -\varepsilon; -\alpha_j, -\varepsilon \frac{n-2}{n-3}] = \frac{\alpha_j}{(n-2)(\alpha_j - \varepsilon)}, \quad j = 1, \dots, n-1;$$
$$q_n = [0, -\varepsilon; -\alpha_n, -\varepsilon \frac{n-2}{n-1}] = \frac{-\alpha_n}{(n-2)(\alpha_n - \varepsilon)}.$$

Theorem 4.4 then yields the lower bound

$$\nu_* = \frac{2}{1 - \frac{|(\sum_{j=1}^{n-1} \frac{\alpha_j}{\alpha_j - \varepsilon}) - \frac{\alpha_n}{\alpha_n - \varepsilon} - 2(n-2)|}{\sum_{j=1}^n \frac{\alpha_j}{\alpha_j - \varepsilon}}}$$

on the barrier parameter of any logarithmically homogeneous self-concordant barrier on K. The relation  $\lim_{\varepsilon \to 0} \nu_* = n$  completes the proof.

**Corollary 6.2.** Let  $n \geq 3$ . The epigraph of the  $|| \cdot ||_{\infty}$ -norm in  $\mathbb{R}^{n-1}$ ,

$$K_{n,\infty} = \{ (x_0, \dots, x_{n-1})^T \mid x_0 \ge |x_k| \ \forall \ k = 1, \dots, n-1 \} \subset \mathbb{R}^n,$$
(23)

cannot have a logarithmically homogeneous self-concordant barrier with barrier parameter less than  $\nu_* = n$ .

An optimal barrier for the cone  $K_{n,\infty}$  is given by

$$F(x_0, \dots, x_{n-1}) = -\sum_{k=1}^{n-1} \log(x_0^2 - x_k^2) + (n-2)\log x_0.$$
(24)

For a proof see the appendix.

Note that since every convex quadrangle is projectively equivalent to a square, the barrier (24) for n = 3 yields an optimal barrier also for an arbitrary regular polyhedral cone  $K \subset \mathbb{R}^3$  which is generated by 4 extreme rays.

#### 7 Further examples

#### 7.1 Power cone

The power cone is a 3-dimensional regular convex cone defined by

$$K_p = \{ (u, v, w)^T \mid u \ge 0, \ v \ge 0, \ u^{1/p} v^{1/q} \ge |w| \},$$
(25)

where  $p \in (2, \infty)$  is a parameter and  $\frac{1}{p} + \frac{1}{q} = 1$ . In [3] Nesterov proposed a logarithmically homogeneous self-concordant barrier with barrier parameter  $\nu = 4$  for this cone. In [1] a logarithmically homogeneous

self-concordant barrier with barrier parameter  $\nu = 3$  was proposed and a logarithmically homogeneous function with homogeneity parameter  $\nu = 3 - \frac{2}{p}$  was conjectured to be self-concordant. We shall now give a lower bound on the barrier parameter of any logarithmically homogeneous self-concordant barrier on  $K_p$ .

Consider the compact section  $D = \{(u, v, w)^T \in K_p \mid u + v = 1\}$  of  $K_p$ . Introducing the variable  $\rho = u - v \in [-1, 1]$ , we can parameterize D by  $(\rho, w)^T$ . Inserting the relations  $u = \frac{1+\rho}{2}$ ,  $v = \frac{1-\rho}{2}$  into the inequality defining the cone  $K_p$ , we see that D is given by the set  $\{(\rho, w)^T \mid |\rho| \leq 1, (1+\rho)^{1/p} (1-\rho)^{1/q} \geq 0\}$ 2|w|.

Let now  $\gamma > 0$  be the unique positive root of the transcendent equation

$$q(1+\gamma^{-1/q}) = p(1+\gamma^{-1/p}).$$
(26)

Choose  $\rho_2, \rho_3 \in (-1, 1)$  such that  $\rho_2 < \rho_3$  and  $\gamma = \frac{(1-\rho_3)(1+\rho_2)}{(1+\rho_3)(1-\rho_2)}$ . Then  $\rho_3$  can be expressed as a function of  $\rho_2$  by  $\rho_3 = \frac{1+\rho_2-\gamma(1-\rho_2)}{1+\rho_2+\gamma(1-\rho_2)}$ . Define further  $w_k = \frac{1}{2}(1+\rho_k)^{1/p}(1-\rho_k)^{1/q}$ , k = 2, 3. Set  $e_1 = (1,0)^T$ ,  $y_1 = (-1,0)^T$ ,  $e_2 = (\rho_2, w_2)^T$ ,  $y_2 = (\rho_3, -w_3)^T$ ,  $e_3 = (\rho_2, -w_2)^T$ ,  $y_3 = (\rho_3, w_3)^T$ . All these 6 points are located on the boundary of D, and the lines  $l_k$  through  $e_k, y_k, k = 1, 2, 3$ , intersect

in the common point  $x^* = (\frac{\rho_2 w_3 + \rho_3 w_2}{w_2 + w_3}, 0)^T$ , which lies in the interior of the triangle formed by the  $e_k$ . The line  $l_1$  intersects the line through  $e_2, e_3$  in the point  $z_1 = (\rho_2, 0)^T$ , while  $l_3$  intersects the line through  $e_1, e_2$  in the point

$$z_{3} = \frac{1}{(1-\rho_{2})(w_{2}+w_{3})+w_{2}(\rho_{3}-\rho_{2})} \begin{pmatrix} \rho_{2}w_{3}(1-\rho_{2})+w_{2}(2\rho_{3}-\rho_{2}\rho_{3}-\rho_{2})\\ w_{2}(w_{2}(1-\rho_{3})+w_{3}(1-\rho_{2})) \end{pmatrix}$$

From this we readily compute the projective cross-ratios

q

$$q_1 = \frac{2w_2(\rho_3 - \rho_2)}{(1 - \rho_2)(w_2(1 + \rho_3) + w_3(1 + \rho_2))},$$
(27)

$$_{2} = q_{3} = \frac{w_{2}(1-\rho_{3}) + w_{3}(1-\rho_{2})}{2w_{3}(1-\rho_{2})},$$
(28)

and hence

$$\sum_{k=1}^{3} q_k - 1 = \frac{w_2(1+\rho_3)(w_2(1-\rho_3)+w_3(1-\rho_2))}{w_3(1-\rho_2)(w_2(1+\rho_3)+w_3(1+\rho_2))} = \frac{1+\gamma^{1/p}}{1+\gamma^{1/q}} > 1.$$

By (22) we then obtain

$$\nu_* = q_1 + q_2 + q_3 = 1 + \frac{1 + \gamma^{1/p}}{1 + \gamma^{1/q}}.$$
(29)

**Corollary 7.1.** Let  $K_p \subset \mathbb{R}^3$  be the power cone given by (25) with parameter  $p \geq (2, +\infty)$ . If F is a logarithmically homogeneous self-concordant barrier on  $K_p$ , then its barrier parameter satisfies the inequality  $\nu \ge 1 + \frac{1+\gamma^{1/p}}{1+\gamma^{1/q}}$ , where  $\gamma$  is given by (26) and  $\frac{1}{p} + \frac{1}{q} = 1$ . In Fig. 1 the lower bound  $\nu_*$  as a function of p is depicted along with the barrier parameters of the

barriers proposed in [3] and  $[1]^2$ 

#### 7.2Epigraph of the $|| \cdot ||_p$ norm

Next we consider the epigraph of the  $|| \cdot ||_p$ -norm in  $\mathbb{R}^2$  for  $1 \le p \le \infty$ , i.e., the 3-dimensional cone

$$K_{3,p} = \{ (x_0, x_1, x_2)^T \, | \, x_0 \ge (|x_1|^p + |x_2|^p)^{1/p} \}.$$
(30)

In [3] Nesterov proposed a method to construct a logarithmically homogeneous self-concordant barrier with barrier parameter  $\nu = 2\tilde{\nu}$  for this cone if a logarithmically homogeneous self-concordant barrier for the corresponding power cone  $K_p$  is available which has barrier parameter  $\tilde{\nu}$ . In [1] the universal barrier [4, Sect. 2.5] for  $K_{3,p}$  was computed and a barrier parameter  $\nu = \frac{3p}{p+1}$   $(p \ge 2)$  for this barrier

<sup>&</sup>lt;sup>2</sup>As noted by an anonymous referee, expression (29) can be rewritten as  $2 + (1 - q/p)\gamma^{1/p}$ .



Figure 1: Barrier parameters of barriers for the power cone and lower bound

was conjectured on the basis of randomized numerical experiments. We shall now give a lower bound on the barrier parameter for any logarithmically homogeneous self-concordant barrier on  $K_{3,p}$ .

For p = 2,  $K_{3,p}$  is the 3-dimensional Lorentz cone, whose optimal barrier parameter is 2. For p = 1 and  $p = \infty K_{3,p}$  is a polyhedral cone with 4 extreme rays. This case was considered in the previous section, where it was established that the optimal barrier parameter equals 3.

Let us consider the case  $2 . Let <math>\gamma \in (0,1)$  be the unique solution of the equation  $(1-\frac{2}{p})\gamma^{1-1/p} + (1-\frac{1}{p})\gamma^{1-2/p} - \frac{1}{p} = 0$ . Note that this definition coincides with (26). For  $\delta \in (0,1)$ , set

$$\rho_2 = 1 - \delta, \quad \rho_3 = 1 - \gamma \delta, \quad w_2 = (1 - \rho_2^p)^{1/p}, \quad w_3 = (1 - \rho_3^p)^{1/p}.$$
(31)

Consider the compact section  $D = \{(\rho, w)^T \mid (1, \rho, w)^T \in K_{3,p}\}$  of the cone  $K_{3,p}$  and let  $e_1, e_2, e_3 \in \partial D$ ,  $x^* \in D^o$  be as in the previous subsection. Then the projective cross-ratios  $q_k$  will be given by the same formulas (27), and

$$q_1 + q_2 + q_3 = 2 + \frac{w_2^2(1 - \rho_3^2) - w_3^2(1 - \rho_2^2)}{w_3(1 - \rho_2)(w_3(1 + \rho_2) + w_2(1 + \rho_3))}.$$
(32)

Now note that  $\frac{1-x^2}{(1-x^p)^{2/p}}$  is a strictly monotonely decreasing function for  $x \in (0,1)$ , hence  $\frac{1-\rho_3^2}{w_3^2} < \frac{1-\rho_2^2}{w_2^2}$  and  $q_1 + q_2 + q_3 < 2$ . By (22) we then get the lower bound

$$\nu_* = \frac{q_1 + q_2 + q_3}{q_1 + q_2 + q_3 - 1} = 2 + \frac{w_3^2(1 - \rho_2^2) - w_2^2(1 - \rho_3^2)}{w_2(1 + \rho_3)[w_3(1 - \rho_2) + w_2(1 - \rho_3)]} = 2 + \frac{(w_3/w_2)^2(2 - \delta) - \gamma(2 - \gamma\delta)}{(2 - \gamma\delta)(w_3/w_2 + \gamma)}.$$

We have

$$\lim_{\delta \to 0} \frac{w_3}{w_2} = \left(\lim_{\delta \to 0} \frac{1 - (1 - \gamma \delta)^p}{1 - (1 - \delta)^p}\right)^{1/p} = \left(\lim_{\delta \to 0} \frac{\gamma (1 - \gamma \delta)^{p-1}}{(1 - \delta)^{p-1}}\right)^{1/p} = \gamma^{1/p},\tag{33}$$

and therefore

$$\lim_{\delta \to 0} \nu_* = 2 + \frac{\gamma^{2/p} - \gamma}{\gamma^{1/p} + \gamma} = 2 + \frac{\gamma^{1/p} - \gamma^{1-1/p}}{1 + \gamma^{1-1/p}},$$

which, remarkably, coincides with (29).

Let us now consider the case  $1 . Let <math>\gamma \in (0,1)$  be the unique solution of the equation  $(\frac{2}{p}-1)\gamma^{1/p} + \frac{1}{p}\gamma^{2/p-1} - (1-\frac{1}{p}) = 0$ . For  $\delta \in (0,1)$ , define  $\rho_2, \rho_3, w_2, w_3$  by (31) and let  $e_1, e_2, e_3 \in \partial D$ ,  $x^* \in D^o$  be again as in the previous subsection. Then we again obtain (32), but  $\frac{1-x^2}{(1-x^p)^{2/p}}$  is now a strictly monotonely increasing function for  $x \in (0,1)$ . Hence  $\frac{1-\rho_3^2}{w_3^2} > \frac{1-\rho_2^2}{w_2^2}$  and  $q_1 + q_2 + q_3 > 2$ . By (22) we then get the lower bound

$$\nu_* = q_1 + q_2 + q_3 = 2 + \frac{(w_2/w_3)^2(2 - \gamma\delta)\gamma - (2 - \delta)}{(2 - \delta) + w_2/w_3(2 - \gamma\delta)}.$$

As in (33) we get  $\lim_{\delta \to 0} \frac{w_2}{w_3} = \gamma^{-1/p}$ , which yields

$$\lim_{\delta \to 0} \nu_* = 2 + \frac{\gamma^{1-2/p} - 1}{1 + \gamma^{-1/p}} = 2 + \frac{\gamma^{1-1/p} - \gamma^{1/p}}{1 + \gamma^{1/p}}.$$

Note that this again coincides with (29), but with p and q interchanged.

Combining these results, we get the following lower bound.

**Corollary 7.2.** Let  $K_{3,p} \subset \mathbb{R}^3$  be the epigraph of the  $|| \cdot ||_p$ -norm given by (30) with parameter  $p \in [1, \infty]$ . Set  $c = \min(\frac{1}{p}, 1 - \frac{1}{p}) \in [0, \frac{1}{2}]$  and let  $\gamma \in [0, 1)$  be a solution of the equation  $(1 - 2c)\gamma^{1-c} + (1 - c)\gamma^{1-2c} - c = 0$ . If F is a logarithmically homogeneous self-concordant barrier on  $K_{3,p}$ , then its barrier parameter satisfies the inequality  $\nu \geq 1 + \frac{1+\gamma^c}{1+\gamma^{1-c}}$ .

As already noted, as functions of p the lower bounds given in Corollaries 7.1 and 7.2 coincide.

*Remark* 7.3. The choices of the points  $e_k$  and  $x^*$  in Subsections 7.1 and 7.2 are optimal, i.e., the bounds in Corollaries 7.1 and 7.2 are the best possible which can be obtained with our method.

#### References

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### A Self-concordance of function (24)

In this section it is proven that the function F given by (24) is a self-concordant barrier for the cone  $K_{n,\infty}$  defined in (23). The proof is due to an anonymous reviewer. It replaces the much more complicated proof from the first version of the paper.

Consider the positive orthant  $\mathbb{R}^{n-1}_+$  with its optimal barrier  $F_{\mathbb{R}^{n-1}_+}(y) = -\sum_{k=1}^{n-1} \log y_k$ . As a homogeneous cone, it has rank n-1. From this cone we construct [2, Sect. 3] (see also [4, pp. 165–166]) a homogeneous cone of rank n and dimension 2n-1,

$$SC(\mathbb{R}^{n-1}_+, B) = \left\{ (y, x, x_0) \in \mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R} \, | \, x_0 \ge 0, \, \, x_0 y - B(x) \in \mathbb{R}^{n-1}_+ \right\}$$

where  $B : \mathbb{R}^{n-1} \to \mathbb{R}^{n-1}_+$  is a symmetric vector-valued bilinear form given by  $B(x) = (x_1^2, \dots, x_{n-1}^2)^T$ . An optimal barrier for the cone  $SC(\mathbb{R}^{n-1}_+, B)$  with barrier parameter *n* is given by [2, Theorem 4.1]

$$F_{SC(\mathbb{R}^{n-1}_+,B)}(y,x,x_0) = F_{\mathbb{R}^{n-1}_+}\left(y - x_0^{-1}B(x)\right) - \log x_0 = -\sum_{k=1}^{n-1}\log(x_0y_k - x_k^2) + (n-2)\log x_0.$$

Now the intersection of the cone  $SC(\mathbb{R}^{n-1}_+, B)$  with the linear subspace given by  $x_0 = y_1 = \cdots = y_{n-1}$  is isomorphic to the cone  $K_{n,\infty}$ , and the restriction of the barrier  $F_{SC(\mathbb{R}^{n-1}_+,B)}$  to this intersection induces the function F on  $K_{n,\infty}$ . This proves that F is actually a self-concordant barrier.