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# On the $\infty$-norm of the cubic form of complete hyperbolic affine hyperspheres 

Roland Hildebrand *

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#### Abstract

Let $M_{n} \subset \mathbb{R}^{n+1}$ be a complete hyperbolic affine hypersphere with mean curvature $H, H<0$, and let $C$ be its cubic form. We derive a differential inequality and an upper bound on the scalar function $\|C\|_{\infty}$ defined by the fiber-wise maximum of the value of $C$ on the unit sphere bundle of $M$. The bound is attained for the affine hyperspheres which are asymptotic to a simplicial cone.


## 1 Introduction

The subject of this paper are complete hyperbolic affine hyperspheres. The Calabi conjecture [2] states that every hyperbolic affine hypersphere $M$ which is complete (in the affine metric or in a metric induced by some Euclidean metric of the ambient affine space) is asymptotic to a regular (with nonempty interior and containing no lines) convex cone in the ambient space, with vertex in the center of $M$, and conversely, for every regular convex cone $K$ in the ambient space and every negative real number $H$ there exists a unique hyperbolic affine hypersphere with center in the vertex of $K$ and with mean curvature $H$ which is asymptotic to $K$. The conjecture has been proven by the efforts of many authors, a synthesis of the proof is given in [5, Section 2].

In [2, Lemma 5.2 , p.31] Calabi obtained a differential inequality on the maximal eigenvalue of the Ricci tensor on complete hyperbolic affine hyperspheres and proved that the Ricci curvature has to be non-positive [2, Theorem 5.1, p.31]. He also showed that this bound is sharp, by presenting an example of a complete hyperbolic affine hypersphere with flat affine metric, namely the one which is asymptotic to a simplicial cone [2, p.37]. Similar differential inequalities and bounds can be obtained for the Pick invariant [9, eq. (2.5)], [5, Cor. 2.6.5, p.128].

In this contribution we use the techniques of [2] to obtain a differential inequality (Theorem 3.1) and a bound (Corollary 4.1) on the function

$$
\begin{equation*}
\Upsilon(x)=\max _{\xi \in T_{x} M,\|\xi\|=1}(C(x))(\xi, \xi, \xi) \tag{1}
\end{equation*}
$$

on a complete hyperbolic affine hypersphere $M$, with $C$ being the cubic form. This function can be considered as the (point-wise) $\infty$-norm of the cubic form. The main motivation for studying this function lies in conic optimization, to which a link can be made as follows. An $n$-dimensional complete hyperbolic affine hypersphere $M$ with center in the origin of $\mathbb{R}^{n+1}$ is asymptotic to some regular convex cone $K \subset \mathbb{R}^{n+1}$. On the interior of $K$ define a logarithmically homogeneous convex function $F$ by the relation $F[\alpha M]=\{-\log \alpha\}$ for all $\alpha>0$ (cf. [6]). Then a bound on (1) translates into a bound on the self-concordance parameter [7, Sect. 2.3.3] of an appropriate multiple of $F$. We will elaborate on this relation in a subsequent publication (cf. also [4, Theorem 4.8]). Our bound on the cubic form is sharp, as we will demonstrate on the example of the affine hypersphere asymptotic to a simplicial cone (Proposition 5.1).

[^0]
## 2 Notations and preliminaries

Let us recall the definition of the cubic form and the expression for its Laplacian on affine hyperspheres. Let $M$ be an $n$-dimensional complete hyperbolic affine hypersphere with mean curvature $H<0, g$ the affine metric, $\nabla$ the Levi-Civita connection of the affine metric, and $\bar{\nabla}$ the affine connection induced by the ambient real affine space. The cubic form is defined as the covariant derivative $C=\bar{\nabla} g[8$, eq. (2.6), p.34; Theorem 3.3, p.42]. The difference tensor ${ }^{1}$ is defined as the difference $\bar{\nabla}-\nabla$ and equals $A=-\frac{1}{2} C[8$, Prop.4.1, p.50]. The difference tensor and hence the cubic form are symmetric in all three indices [2, pp.23-24]. The Ricci curvature of the affine metric and the Laplacian of $C$ with respect to the affine metric are given by [9, p.3]

$$
\begin{align*}
R_{i j} & =(n-1) H g_{i j}+\frac{1}{4} C_{i}^{r s} C_{j r s}  \tag{2}\\
\Delta C_{i j k} & =(n+1) H C_{i j k}+\frac{1}{4} C^{a b c}\left(C_{a b i} C_{c j k}+C_{a b j} C_{c k i}+C_{a b k} C_{c i j}\right)-\frac{1}{2} C_{i b}^{a} C_{j c}^{b} C_{k a}^{c} . \tag{3}
\end{align*}
$$

## 3 Differential inequality

Our purpose is to derive a differential inequality on the function $\Upsilon$ defined by (1) on $M$. Let $p \in M$ be an arbitrary point and let $\xi \in T_{p} M$ be a maximizer of the cubic form on the unit sphere in $T_{p} M$, $\Upsilon(p)=(C(p))(\xi, \xi, \xi),\|\xi\|=1$.

Transport $\xi$ from $p$ to a neighbourhood $U$ of $p$ along the geodesics through $p$ by means of the Levi-Civita connection to obtain a smooth unit length vector field on $U$. Then $\xi$ satisfies

$$
\begin{equation*}
\nabla \xi=0, \quad \Delta \xi=0 \tag{4}
\end{equation*}
$$

at $p$ [2, p.32], and $\bar{\Upsilon}=C_{i j k} \xi^{i} \xi^{j} \xi^{k} \leq \Upsilon$ on $U$, with equality attained at $p$. Define the symmetric second-order tensor $B=\bar{\nabla}_{\xi} g$ on $U$, in index form $B_{i j}=C_{i j k} \xi^{k}$. Note that $B$ is traceless by the apolarity condition $C_{i j}^{i}=0$ [8, Theorem 4.3, p.51], and that $B_{i j} \xi^{i} \xi^{j}=\bar{\Upsilon}$. Moreover, by [5, Lemma 2.2.3.19, p.106] we have at $p$ that $B_{i j} \xi^{i} \eta^{j}=0$ and $B_{i j} \eta^{i} \eta^{j} \leq \frac{1}{2} B_{i j} \xi^{i} \xi^{j} \leq \bar{\Upsilon}$ for every unit length vector $\eta$ which is orthogonal to $\xi$. It follows that $\xi$ is also a maximizer of $B(p)$ on the unit sphere in $T_{p} M$. In particular, at $p$ we have

$$
\begin{equation*}
B_{i j} \xi^{j}=\bar{\Upsilon} g_{i j} \xi^{j} \tag{5}
\end{equation*}
$$

as the first order optimality condition, and $\bar{\Upsilon}$ is the maximal eigenvalue of the matrix of $B(p)$ in any orthonormal basis of $T_{p} M$.

Let us now estimate the Laplacian of $\bar{\Upsilon}$. At $p$ we have by virtue of (3),(4), and (5)

$$
\begin{aligned}
\Delta \bar{\Upsilon} & =(\Delta C)_{i j k} \xi^{i} \xi^{j} \xi^{k}=(n+1) H \bar{\Upsilon}+\frac{3}{4} C^{a b c} C_{a b i} C_{c j k} \xi^{i} \xi^{j} \xi^{k}-\frac{1}{2} C_{i b}^{a} C_{j c}^{b} C_{k a}^{c} \xi^{i} \xi^{j} \xi^{k} \\
& =(n+1) H \bar{\Upsilon}+\frac{3}{4} C^{a b c} B_{a b} B_{c j} \xi^{j}-\frac{1}{2} B_{b}^{a} B_{c}^{b} B_{a}^{c}=(n+1) H \bar{\Upsilon}+\frac{3}{4} \bar{\Upsilon} B^{a b} B_{a b}-\frac{1}{2} B_{b}^{a} B_{c}^{b} B_{a}^{c} \\
& \geq(n+1) H \bar{\Upsilon}+\frac{n(n+1)}{4(n-1)^{2}} \bar{\Upsilon}^{3}
\end{aligned}
$$

Here the inequality follows from Corollary A. 2 in the Appendix. We obtain the following result.
Theorem 3.1. Let $M$ be an n-dimensional complete hyperbolic affine hypersphere with mean curvature $H<0$, and let $C$ be its cubic form. Then the function $\Upsilon(x)=\max _{\xi \in T_{x} M,\|\xi\|=1}(C(x))(\xi, \xi, \xi)$ satisfies the differential inequality $\Delta \Upsilon \geq(n+1) H \Upsilon+\frac{n(n+1)}{4(n-1)^{2}} \Upsilon^{3}$ weakly in the sense of [1, Def. 1, p.46].

[^1]
## 4 Bound

From Theorem 3.1 we might obtain a bound on the function (1) on a complete hyperbolic affine hypersphere. Namely, from [3, Cor. 1, p.857] ${ }^{2}$ it follows that $\Upsilon \leq \sqrt{-\frac{4 H(n-1)^{2}}{n}}=\frac{2(n-1) \sqrt{-H}}{\sqrt{n}}$. As in the case of the Pick invariant [5, Cor. 2.6.5, p.128], however, there exists a purely algebraic proof.

As in the preceding section, let $p \in M$ be an arbitrary point, let $\xi \in T_{p} M$ be a maximizer of the cubic form on the unit sphere in $T_{p} M$, and define the traceless symmetric second-order tensor $B=\bar{\nabla}_{\xi} C$ on $T_{p} M$. Let $\left\{\xi, \eta_{1}, \ldots, \eta_{n-1}\right\}$ be an orthonormal basis of $T_{p} M$, then we have

$$
\begin{aligned}
\Upsilon^{2}(p) & =\left(B_{i j} \xi^{i} \xi^{j}\right)^{2}=\left(-\sum_{k=1}^{n-1} B_{i j} \eta_{k}^{i} \eta_{k}^{j}\right)^{2} \leq(n-1) \sum_{k=1}^{n-1}\left(B_{i j} \eta_{k}^{i} \eta_{k}^{j}\right)^{2} \leq(n-1) \sum_{k=1}^{n-1} B_{i l} B_{j}^{l} \eta_{k}^{i} \eta_{k}^{j} \\
& =(n-1)\left(B_{i l} B^{l i}-B_{i l} B_{j}^{l} \xi^{i} \xi^{j}\right)=(n-1)\left(C_{i l j} C_{k}^{l i} \xi^{j} \xi^{k}-\Upsilon^{2}(p)\right) \\
& =4(n-1)\left(R_{j k}-(n-1) H g_{j k}\right) \xi^{j} \xi^{k}-(n-1) \Upsilon^{2}(p) \leq-4(n-1)^{2} H-(n-1) \Upsilon^{2}(p) .
\end{aligned}
$$

Here we used (5) and (2) in the last two equalities, respectively, and the non-positivity of the Ricci curvature [2, Theorem 5.1, p.31] in the last inequality. We obtain the following result.

Corollary 4.1. Let $M$ be an n-dimensional complete hyperbolic affine hypersphere with mean curvature $H<0$, and let $C$ be its cubic form. Then the function $\Upsilon(x)=\max _{\xi \in T_{x} M,\|\xi\|=1}(C(x))(\xi, \xi, \xi)$ satisfies the inequality $\Upsilon \leq \frac{2(n-1) \sqrt{-H}}{\sqrt{n}}$.

## 5 Affine hyperspheres asymptotic to a simplicial cone

In this section we show that the inequalities in Theorem 3.1 and Corollary 4.1 are saturated for the affine hyperspheres which are asymptotic to a simplicial cone.

Denote by $I_{k}$ the $k \times k$ identity matrix, by $\mathbf{1}_{k} \in \mathbb{R}^{k}$ the all-ones vector, and by $e_{k} \in \mathbb{R}^{n}$ the $k$-th canonical basis vector. Let $K=\mathbb{R}_{+}^{n+1}$ be the nonnegative orthant, $H<0$ a negative real number, and let $M \subset K$ be the hyperbolic affine hypersphere with mean curvature $H$ which is asymptotic to $K$. It is well-known that $M$ is given by the equation $x_{0} \cdots x_{n}=c$ for some $c>0$. On the interior of $K$ we introduce the coordinates $y_{0}, \ldots, y_{n}$ by

$$
\left(\begin{array}{c}
y_{0} \\
\vdots \\
y_{n}
\end{array}\right)=\gamma U \log x=\gamma\left(\begin{array}{cc}
\frac{1}{\sqrt{n+1}} & \frac{1}{\sqrt{n+1}} \mathbf{1}_{n}^{T} \\
-\frac{1}{\sqrt{n+1}} \mathbf{1}_{n} & I_{n}+\frac{1}{n}\left(\frac{1}{\sqrt{n+1}}-1\right) \mathbf{1}_{n} \mathbf{1}_{n}^{T}
\end{array}\right)\left(\begin{array}{c}
\log x_{0} \\
\vdots \\
\log x_{n}
\end{array}\right)
$$

where $\gamma>0$ is a constant to be determined later. Then in the $y$-coordinates the surface $M$ is given by the equation $y_{0}=\frac{\gamma \log c}{\sqrt{n+1}}$. The remaining coordinates $y_{1}, \ldots, y_{n} \in \mathbb{R}$ define a global coordinate chart on $M$.

It is easily seen that the subgroup of unimodular diagonal automorphisms of $K$, which leaves $M$ invariant, acts by translations on $M$. The affine metric $g$ and the cubic form $C$ of $M$ have thus constant coefficients. The symmetric group $S_{n+1}$, which acts by permutations of the coordinates $x_{i}$ on $K$, has a unique fixed point $y^{0} \in M$ given by $y_{1}=\cdots=y_{n}=0$. Therefore $S_{n+1}$ acts on the tangent space $T_{y^{0}} M$, and both $g$ and $C$ have to be invariant under this action. It is not hard to check that the subgroup $S_{n} \subset S_{n+1}$ permuting the coordinates $x_{1}, \ldots, x_{n}$ on $K$ acts just by a corresponding permutation of the

[^2]$y$-coordinates. Therefore the coefficients $g_{i j}, C_{i j k}$ depend only on the number of distinct indices in the sets $\{i, j\}$ and $\{i, j, k\}$, respectively. Denote the latter number by $\theta_{i j k}$. The permutation $\sigma_{i} \in S_{n+1}$ exchanging the coordinates $x_{0}, x_{i}$ acts on $T_{y^{0}} M$ by the orthogonal transformation
$$
U_{i}=I-\left(\frac{1-\sqrt{n+1}}{n} \mathbf{1}_{n}-e_{i}\right)\left(\frac{1-\sqrt{n+1}}{n} \mathbf{1}_{n}-e_{i}\right)^{T}
$$

It is not difficult to check that the invariance of $g$ and $C$ with respect to the transformations given by $U_{i}$ determines these tensors up to a constant multiple. Namely, the matrix of the metric $g$ has to be proportional to the identity matrix, and the cubic form $C$ is given by

$$
C_{i j k}=\left\{\begin{array}{rlr}
-\alpha(n-1)(2+(n-2) \sqrt{n+1}), & \theta_{i j k}=1  \tag{6}\\
\alpha(2+(n-2) \sqrt{n+1}), & \theta_{i j k}=2 \\
\alpha(n+2-2 \sqrt{n+1}), & \theta_{i j k}=3
\end{array}\right.
$$

where $\alpha$ is a yet to be determined proportionality constant.
Let us choose $\gamma$ such that the matrix of $g$ is given by $I_{n}$. Contracting (2) with the metric and taking into account that $M$ is flat, we obtain $C^{\text {irs }} C_{\text {irs }}=-4 n(n-1) H$. Inserting the values for $C_{\text {irs }}$ from (6), we get $\alpha^{2} n^{5}(n-1)=-4 n(n-1) H$, yielding $\alpha= \pm \frac{2 \sqrt{-H}}{n^{2}}$ (it can be checked that the sign is positive). Hence on the unit length vector $\frac{1}{\sqrt{n}} \mathbf{1}_{n}$ the cubic form has the value $\frac{\alpha n^{3}(n-1)}{n^{3 / 2}}= \pm \frac{2(n-1) \sqrt{-H}}{\sqrt{n}}$, finally giving $\Upsilon \geq \frac{2(n-1) \sqrt{-H}}{\sqrt{n}}$. From Corollary 4.1 we can then conclude that $\Upsilon \equiv \frac{2(n-1) \sqrt{-H}}{\sqrt{n}}$ on $M$. By the affine equivalence of an arbitrary simplicial cone to the nonnegative orthant we obtain the following result.

Proposition 5.1. Let $M \subset \mathbb{R}^{n+1}$ be a complete hyperbolic affine hypersphere which is asymptotic to a simplicial cone. Then both the bound in Theorem 3.1 and in Corollary 4.1 are saturated.

In particular, this will allow us to show that the optimal self-concordance parameter of an arbitrary regular convex cone is not worse than the parameter of the standard barrier for the nonnegative orthant of the same dimension.

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## A Matrix lemma

In this section we provide an auxiliary inequality.
Lemma A.1. Let $n \geq 2$ and $\lambda_{1}, \ldots, \lambda_{n-1} \leq 1$ be such that $\sum_{i=1}^{n-1} \lambda_{i}=-1$. Then $\frac{3}{4} \sum_{i=1}^{n-1} \lambda_{i}^{2}-$ $\frac{1}{2} \sum_{i=1}^{n-1} \lambda_{i}^{3} \geq \frac{3 n-1}{4(n-1)^{2}}$.

Proof. Define $c_{i}=(n-1) \lambda_{i}+1$. Then $\sum_{i=1}^{n-1} c_{i}=0$ and $c_{i} \leq n$ for all $i$. It follows that $c_{i}^{3} \leq n c_{i}^{2}$ for all $i$. We then have

$$
\begin{aligned}
& \frac{3}{4} \sum_{i=1}^{n-1} \lambda_{i}^{2}-\frac{1}{2} \sum_{i=1}^{n-1} \lambda^{3}-\frac{3 n-1}{4(n-1)^{2}}=\frac{3}{4(n-1)^{2}} \sum_{i=1}^{n-1}\left(c_{i}-1\right)^{2}-\frac{1}{2(n-1)^{3}} \sum_{i=1}^{n-1}\left(c_{i}-1\right)^{3}-\frac{3 n-1}{4(n-1)^{2}} \\
& \quad=\left(\frac{3}{4(n-1)}+\frac{1}{2(n-1)^{2}}-\frac{3 n-1}{4(n-1)^{2}}\right)-\left(\frac{3}{2(n-1)^{2}}+\frac{3}{2(n-1)^{3}}\right) \sum_{i=1}^{n-1} c_{i} \\
& \quad+\left(\frac{3}{4(n-1)^{2}}+\frac{3}{2(n-1)^{3}}\right) \sum_{i=1}^{n-1} c_{i}^{2}-\frac{1}{2(n-1)^{3}} \sum_{i=1}^{n-1} c_{i}^{3} \\
& \quad \geq\left(\frac{3(n+1)}{4(n-1)^{3}}-\frac{n}{2(n-1)^{3}}\right) \sum_{i=1}^{n-1} c_{i}^{2}=\frac{n+3}{4(n-1)^{3}} \sum_{i=1}^{n-1} c_{i}^{2} \geq 0 .
\end{aligned}
$$

This completes the proof.
Corollary A.2. Let $B$ be a real symmetric $n \times n$ matrix with vanishing trace. Then $\frac{3}{4} \lambda_{\max }(B) \operatorname{tr} B^{2}-$ $\frac{1}{2} \operatorname{tr} B^{3} \geq \frac{n(n+1)}{4(n-1)^{2}} \lambda_{\text {max }}^{3}(B)$.

Proof. If $\lambda_{\max }(B)=0$, then $B=0$ and the assertion of the corollary is evident.
Suppose now that $\lambda_{\max }(B)>0$. Let $\lambda_{1} \leq \lambda_{2} \leq \cdots \leq \lambda_{n-1} \leq \lambda_{n}=1$ be the eigenvalues of the matrix $\tilde{B}=\frac{B}{\lambda_{\max (B)}}$ in increasing order. Then $\sum_{i=1}^{n-1} \lambda_{i}=-1$ and $\lambda_{i} \leq 1$ for all $i$. We then have

$$
\begin{aligned}
& \frac{3}{4} \lambda_{\max }(B) \operatorname{tr} B^{2}-\frac{1}{2} \operatorname{tr} B^{3}-\frac{n(n+1)}{4(n-1)^{2}} \lambda_{\max }^{3}(B)=\lambda_{\max }^{3}(B)\left(\frac{3}{4} \operatorname{tr} \tilde{B}^{2}-\frac{1}{2} \operatorname{tr} \tilde{B}^{3}-\frac{n(n+1)}{4(n-1)^{2}}\right) \\
& \quad=\lambda_{\max }^{3}(B)\left[\frac{3}{4}\left(1+\sum_{i=1}^{n-1} \lambda_{i}^{2}\right)-\frac{1}{2}\left(1+\sum_{i=1}^{n-1} \lambda_{i}^{3}\right)-\frac{n(n+1)}{4(n-1)^{2}}\right] \geq 0
\end{aligned}
$$

where the inequality comes from the preceding lemma.


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[^1]:    ${ }^{1}$ Sometimes, such as in [2], the difference tensor is called cubic form, which can lead to serious confusions and apparently resulted in a missing factor of 2 in [3, Cor. 2, p.857] for the bound on the Pick invariant.

[^2]:    ${ }^{2}$ Obviously, in the formulation of this Corollary it should read $d_{1}>0, d_{2}<0$, and $u \leq \sqrt{-d_{2} / d_{1}}$, otherwise the assertion of the Corollary can be disproved simply by choosing $u$ to be an appropriate constant. The proof of the Corollary contains several flaws, e.g., it assumes that a lower bound on the Ricci curvature implies an upper bound on the quantity $r \Delta r$, where $r$ is the distance function from some point $p[3, \mathrm{p} .856]$. Consider the unit ball in $\mathbb{R}^{n}$ equipped with the hyperbolic geometry given by the metric $g(x)=\frac{\left(1-R^{2}\right) I+x x^{T}}{\left(1-R^{2}\right)^{2}}$ in matrix form, where $R=\sqrt{x^{T} x}$ is the Euclidean distance from the centre and $I$ the identity matrix. The geodesic distance function from the centre is then given by $r=\frac{1}{2} \log \frac{1+R}{1-R}$, and $\Delta r=\frac{n-1}{R}$. Hence $r \Delta r$ tends to $+\infty$ as $R \rightarrow 1$. It is, however, straightforward to write down a correct proof of the Corollary, e.g., by setting $f=\left(a^{2}-r^{2}\right) u$ [3, p.856]. With the choice $f=\left(1+\cos \frac{\pi r^{2}}{a^{2}}\right) u$ one can handle also differential inequalities of the form $\Delta \psi \geq d_{1} u^{2}+d_{2} u$.

