



HAL
open science

Spinors and isometric immersions of surfaces in 4-dimensional products

Julien Roth

► **To cite this version:**

Julien Roth. Spinors and isometric immersions of surfaces in 4-dimensional products. Bulletin of the Belgian Mathematical Society - Simon Stevin, 2014, 21 (4), pp.635-652. hal-00933532

HAL Id: hal-00933532

<https://hal.science/hal-00933532>

Submitted on 20 Jan 2014

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

SPINORS AND ISOMETRIC IMMERSIONS OF SURFACES IN 4-DIMENSIONAL PRODUCTS

JULIEN ROTH

ABSTRACT. We prove a spinorial characterization of surfaces isometrically immersed into the 4-dimensional product spaces $\mathbb{M}^3(c) \times \mathbb{R}$ and $\mathbb{M}^2(c) \times \mathbb{R}^2$, where $\mathbb{M}^n(c)$ is the n -dimensional real space form of curvature c .

1. INTRODUCTION

In [4], Friedrich gave a spinorial characterization of surfaces in Euclidean 3-space. Namely, he proved that the existence of a so-called generalized Killing spinor ψ on surface (M^2, g) , that is

$$\nabla_X \psi = A(X) \cdot \psi,$$

where A is a symmetric $(1, 1)$ -tensor, is equivalent to the Gauss and Codazzi equations and therefore to an isometric immersion of (M^2, g) into \mathbb{R}^3 with $-2A$ as shape operator. Later on, Morel generalized in [9] this result for surfaces of the sphere \mathbb{S}^3 and the hyperbolic space \mathbb{H}^3 and we give in [12] an analogue for 3-dimensional homogeneous manifolds with 4-dimensional isometry group, as well as for surfaces into pseudo-Riemannian space forms [6] and Lorentzian products [13]. In a more recent work [2], we studied with Bayard and Lawn the spinorial characterization of surfaces into 4-dimensional space forms. A similar result was proved by Bayard for spacelike surfaces into the 4-dimensional Minkowski space [1].

In this paper, we extend this spinorial characterization for surfaces in the product spaces $\mathbb{M}^3(c) \times \mathbb{R}$ and $\mathbb{M}^2(c) \times \mathbb{R}^2$, where $\mathbb{M}^n(c)$ is the n -dimensional real space form of constant sectional curvature $c \neq 0$.

First we characterize immersions of surfaces into these product spaces by the existence of special spinor fields satisfying an appropriate generalized Killing-type equation, that is an equation involving the spinorial connection (see Theorem 3.1). Then, we show that this equation is equivalent to the corresponding Dirac equation with an additional condition on the norm of the spinor field (see Proposition 4.1 and Corollary 4.2).

2. PRELIMINARIES

In this section of preliminaries, we will first recall some basics about surfaces into the product spaces $\mathbb{M}^2(c) \times \mathbb{R}^2$ and $\mathbb{M}^3(c) \times \mathbb{R}$. In particular, we will recall the compatibility equations assuring that a surface is isometrically immersed into one of these spaces. Then, we will give some facts about restrictions of spinors on a surface into a 4-dimensional space and deduce the particular spinor fields with which we will work in the sequel.

2010 *Mathematics Subject Classification.* 53C27, 53C42.

Key words and phrases. Surfaces, Dirac Operator, Isometric Immersions.

2.1. Compatibility equations. Let (M^2, g) be a Riemannian surface isometrically immersed into the product space $P = \mathbb{M}^2(c) \times \mathbb{R}^2$ or $\mathbb{M}^3(c) \times \mathbb{R}$, endowed with the product metric \tilde{g} . We denote by F product structure of P . The map $F : TP \rightarrow TP$ is defined by $F(X_1 + X_2) = X_1 - X_2$, where X_1 belongs to the first factor ($T\mathbb{M}^2(c)$ or $T\mathbb{M}^3(c)$) and X_2 belongs to the second factor ($T\mathbb{R}^2$ or $T\mathbb{R}$). Obviously, F satisfies

$$(1) \quad F^2 = Id \quad (\text{and } F \neq Id),$$

$$(2) \quad \tilde{g}(FX, Y) = \tilde{g}(X, FY),$$

$$(3) \quad \tilde{\nabla}F = 0.$$

Moreover, we recall that the curvature of (P, \tilde{g}) is given by

$$(4) \quad \begin{aligned} \tilde{R}(X, Y)Z &= \frac{c}{4} \left[\langle Y, Z \rangle X - \langle X, Z \rangle Y + \langle FY, Z \rangle FX - \langle FX, Z \rangle FY \right. \\ &\quad \left. + \langle Y, Z \rangle FX - \langle X, Z \rangle FY + \langle Y, FZ \rangle X - \langle X, FZ \rangle Y \right] \end{aligned}$$

This product structure F induces the existence of the following four operators

$$f : TM \rightarrow TM, \quad h : TM \rightarrow NM, \quad s : NM \rightarrow TM \quad \text{and} \quad t : NM \rightarrow NM$$

defined for any $X \in TM$ and $\xi \in NM$ by

$$(5) \quad FX = fX + hX \quad \text{and} \quad F\xi = s\xi + t\xi.$$

From Equations (1) and (2), f and t are symmetric and we have the following relations between these four operators

$$(6) \quad f^2X = X - shX,$$

$$(7) \quad t^2\xi = \xi - hs\xi,$$

$$(8) \quad fs\xi + st\xi = 0,$$

$$(9) \quad hfX + thX = 0,$$

$$(10) \quad \tilde{g}(hX, \xi) = \tilde{g}(X, s\xi),$$

for any $X \in \Gamma(TM)$ and $\xi \in \Gamma(NM)$. Moreover, from Equation (3), we have

$$(11) \quad (\nabla_X f)Y = S_{hY}X + s(B(X, Y)),$$

$$(12) \quad \nabla_X^\perp(hY) - h(\nabla_X Y) = t(B(X, Y)) - B(X, fY),$$

$$(13) \quad \nabla^\perp(t\xi) - t(\nabla_X^\perp \xi) = -B(s\xi, X) - h(S_\xi X),$$

$$(14) \quad \nabla_X(s\xi) - s(\nabla_X^\perp \xi) = -f(S_\xi X) + S_{t\xi}X,$$

where $B : TM \times TM \rightarrow NM$ is the second fundamental form and for any $\xi \in TM$, S_ξ is the Weingarten operator associated with ξ and defined by $\tilde{g}(S_\xi X, Y) = \tilde{g}(B(X, Y), \xi)$ for any vectors X, Y tangent to M .

Finally, from (4), we deduce that the Gauss, Codazzi and Ricci equations are respectively given by

$$(15) \quad \begin{aligned} R(X, Y)Z &= \frac{c}{4} \left[\langle Y, Z \rangle X - \langle X, Z \rangle Y + \langle fY, Z \rangle fX - \langle fX, Z \rangle fY \right. \\ &\quad \left. \langle Y, Z \rangle fX - \langle X, Z \rangle fY + \langle Y, fZ \rangle X - \langle X, fZ \rangle Y \right] \\ &\quad + S_{B(Y, Z)}X - S_{B(X, Z)}Y, \end{aligned}$$

$$(16) \quad (\nabla_X B)(Y, Z) - (\nabla_Y B)(X, Z) = \frac{c}{4} \left[\langle fY, Z \rangle hX - \langle fX, Z \rangle hY + \langle Y, Z \rangle hX - \langle X, Z \rangle hY \right],$$

$$(17) \quad R^\perp(X, Y)\xi = \frac{c}{4} \left[\langle hY, \xi \rangle hX - \langle hX, \xi \rangle hY \right] + B(S_\xi Y, X) - B(S_\xi X, Y).$$

Conversely, let (M^2, g) a Riemannian surface endowed with a rank 2 vector bundle E endowed with a metric and a compatible connection ∇^\perp . Assume that there exist some tensors f, h, s, t and B satisfying Equations (6)-(13) (note that (14) is not required since it is the dual equation of (12)) and the Gauss-Codazzi-Ricci equations (15)-(17). Moreover we define the operator $F : TM \oplus E \rightarrow TM \oplus E$ by relations (5). If in addition the operator F satisfy that the ranks of the maps $\frac{F+Id}{2}$ and $\frac{F-Id}{2}$ are 2 and 2 (*resp.* 3 and 1), then Kowalczyk [5] and De Lira-Tojeiro-Vitório [8] proved independently that there exists an isometric immersion from (M, g) into $\mathbb{M}^2(c) \times \mathbb{R}^2$ (*resp.* $\mathbb{M}^3(c) \times \mathbb{R}$) with E as normal bundle, B as second fundamental form and such that the product structure of $\mathbb{M}^2(c) \times \mathbb{R}^2$ (*resp.* $\mathbb{M}^3(c) \times \mathbb{R}$) coincide with F over M . Note that this was previously proven in a more abstract way by Piccione and Tausk [11].

2.2. Spinors on surfaces of P . For details about the recalls of this section, the reader can refer to [3] for instance. Let (M^2, g) be an oriented Riemannian surface, with a given spin structure, and E an oriented and spin vector bundle of rank 2 on M . We consider the spinor bundle Σ over M twisted by E and defined by

$$\Sigma = \Sigma M \otimes \Sigma E,$$

where ΣM and ΣE are the spinor bundles of M and E respectively. We endow Σ with the spinorial connection ∇ defined by

$$\nabla = \nabla^{\Sigma M} \otimes Id_{\Sigma E} + Id_{\Sigma M} \otimes \nabla^{\Sigma E}.$$

We also define the Clifford product \cdot by

$$\begin{cases} X \cdot \varphi = (X \cdot_M \alpha) \otimes \bar{\sigma} & \text{if } X \in \Gamma(TM) \\ X \cdot \varphi = \alpha \otimes (X \cdot_E \sigma) & \text{if } X \in \Gamma(E) \end{cases}$$

for all $\varphi = \alpha \otimes \sigma \in \Sigma M \otimes \Sigma E$, where \cdot_M and \cdot_E denote the Clifford products on ΣM and on ΣE respectively and where $\bar{\sigma} = \sigma^+ - \sigma^-$ for the natural decomposition of $\Sigma E = \Sigma^+ E \oplus \Sigma^- E$. Here, $\Sigma^+ E$ and $\Sigma^- E$ are the eigensubbundles (for the eigenvalue 1 and -1) of ΣE for the action of the normal volume element $\omega_\perp = i\xi_1 \cdot_E \xi_2$, where $\{\xi_1, \xi_2\}$ is a local orthonormal frame of E . Note that $\Sigma^+ M$ and Σ^- are defined similarly by for the tangent volume element $\omega = ie_1 \cdot_M e_2$. We finally define the Dirac operator D on $\Gamma(\Sigma)$ by

$$D\varphi = e_1 \cdot \nabla_{e_1} \varphi + e_2 \cdot \nabla_{e_2} \varphi,$$

where $\{e_1, e_2\}$ is an orthonormal basis of TM .

We note that Σ is also naturally equipped with a hermitian scalar product $\langle \cdot, \cdot \rangle$ which is compatible to the connection ∇ , since so are ΣM and ΣE , and thus also with a compatible real scalar product $\Re \langle \cdot, \cdot \rangle$. We also note that the Clifford product \cdot of vectors belonging to $TM \oplus E$ is antihermitian with respect to this hermitian product. Finally, we stress that the four subbundles $\Sigma^{\pm\pm} := \Sigma^\pm M \otimes \Sigma^\pm E$ are orthogonal with respect to the hermitian product. We will also consider $\Sigma^+ = \Sigma^{++} \oplus \Sigma^{--}$ and $\Sigma^- = \Sigma^{+-} \oplus \Sigma^{-+}$. Throughout the paper we will assume that the hermitian product is \mathbb{C} -linear w.r.t. the first entry, and \mathbb{C} -antilinear w.r.t. the second entry.

Now, let (P, \tilde{g}) be a 4-dimensional spin manifold. It is a well-known fact that there

is an identification between the spinor bundle $\Sigma P|_M$ of P over M , and the spinor bundle of M twisted by the normal bundle $\Sigma := \Sigma M \otimes \Sigma E$. Moreover, we have the spinorial Gauss formula: for any $\varphi \in \Gamma(\Sigma)$ and any $X \in TM$,

$$(18) \quad \tilde{\nabla}_X \varphi = \nabla_X \varphi + \frac{1}{2} \sum_{j=1,2} e_j \cdot B(X, e_j) \cdot \varphi$$

where $\tilde{\nabla}$ is the spinorial connection of ΣP and ∇ is the spinorial connection of Σ defined as above and $\{e_1, e_2\}$ is a local orthonormal frame of TM . We will also use this notation and $\{\xi_1, \xi_2\}$ for a local orthonormal frame of E . Here \cdot is the Clifford product on P . From now on, we will take $P = \mathbb{M}^2(c) \times \mathbb{R}^2$ or $\mathbb{M}^3(c) \times \mathbb{R}$. By restriction of a parallel spinor of the Euclidean space \mathbb{R}^5 if $c > 0$ or the Lorentzian space $\mathbb{R}^{4,1}$ if $c < 0$, we obtain on P a spinor field φ satisfying

$$\begin{cases} \tilde{\nabla}_X \varphi = \alpha X \cdot \varphi & \text{if } X \in \Gamma(TM^2(c)) \text{ or } \Gamma(TM^3(c)), \\ \tilde{\nabla}_X \varphi = 0 & \text{if } X \in \Gamma(T\mathbb{R}^2) \text{ or } \Gamma(T\mathbb{R}(c)), \end{cases}$$

with $\alpha \in \mathbb{C}$ so that $4\alpha^2 = c$. In other words, for any $X \in \Gamma(TP)$, we have

$$\tilde{\nabla}_X \varphi = \frac{\alpha}{2} (X + FX) \cdot \varphi.$$

Hence, by the spinorial Gauss formula (18), the restriction of φ on M satisfies

$$(19) \quad \nabla_X \varphi = \frac{\alpha}{2} (X + fX + hX) \cdot \varphi + \eta(X) \cdot \varphi,$$

where $\eta(X) = -\frac{1}{2} \sum_{j=1}^2 e_j \cdot B(e_j, X)$.

3. MAIN RESULT

Now, we have the ingredients to state the the main result of this note.

Theorem 3.1. *Let $c \in \mathbb{R}$, $c \neq 0$ and $\alpha \in \mathbb{C}$ such that $4\alpha^2 = c$. Let (M^2, g) be an oriented Riemannian surface and E an oriented vector bundle of rank 2 over M with scalar product $\langle \cdot, \cdot \rangle_E$ and compatible connection ∇^E . We denote by $\Sigma = \Sigma M \otimes \Sigma E$ the twisted spinor bundle. Let $B : TM \times TM \rightarrow E$ a bilinear symmetric map and*

$$f : TM \rightarrow TM, h : TM \rightarrow E, s : E \rightarrow TM \text{ and } t : E \rightarrow E$$

satisfying Equations (6)-(13). Moreover we assume that the rank of the maps $\frac{F+Id}{2}$ and $\frac{F-Id}{2}$ is 2 and 2 (resp. 3 and 1), where $F : TM \oplus E \rightarrow TM \oplus E$ is defined from f, h, s and t by relations (5). Then, the two following statements are equivalent

- (1) *There exists an isometric immersion of (M^2, g) into $P = \mathbb{M}^2(c) \times \mathbb{R}^2$ (resp. $\mathbb{M}^3(c) \times \mathbb{R}$) with E as normal bundle and second fundamental form B such that over M the product structure is given by f, h, t and s .*
- (2) *There exists a spinor field φ in Σ satisfying for all $X \in \mathfrak{X}(M)$*

$$\nabla_X \varphi = \frac{\alpha}{2} (X + fX + hX) \cdot \varphi + \eta(X) \cdot \varphi,$$

such that φ^+ and φ^- never vanish.

Proof: First, we remark that the fact that (1) implies (2) has been proved in the discussion of Section 2. The work consists in proving that (2) implies (1). The computations are in the same spirit as in [2], with some technical difficulties due to the terms arising from the product structure. We will emphasize on these differences. We have to compute the spinorial curvature of the particular spinor φ . For this, let us compute $\mathcal{R}(e_1, e_2)\varphi$, where

(e_1, e_2) is a local orthonormal frame of TM . We also denote by (e_3, e_4) a local orthonormal frame of E . Then, we have

$$\begin{aligned} \mathcal{R}(e_1, e_2)\varphi &= d^\nabla\eta(e_1, e_2) \cdot \varphi + (\eta(e_2) \cdot \eta(e_1) - \eta(e_1)\eta(e_2)) \cdot \varphi \\ &\quad - \frac{\alpha}{2} \left(\nabla_{e_2} e_1 + \nabla_{e_2}(fe_1) + \nabla_{e_2}^\perp(he_1) \right) \cdot \varphi \\ &\quad + \frac{\alpha}{2} \left(\nabla_{e_1} e_2 + \nabla_{e_1}(fe_2) + \nabla_{e_1}^\perp(he_2) \right) \cdot \varphi \\ &\quad + \frac{\alpha^2}{4} (e_2 + fe_2 + he_2) \cdot (e_1 + fe_1 + he_1) \cdot \varphi \\ &\quad - \frac{\alpha^2}{4} (e_1 + fe_1 + he_1) \cdot (e_2 + fe_2 + he_2) \cdot \varphi, \\ &\quad + \frac{\alpha}{2} \left(\eta(e_1) \cdot (e_2 + fe_2 + he_2) - (e_2 + fe_2 + he_2) \cdot \eta(e_1) \right) \cdot \varphi \\ &\quad - \frac{\alpha}{2} \left(\eta(e_2) \cdot (e_1 + fe_1 + he_1) - (e_1 + fe_1 + he_1) \cdot \eta(e_2) \right) \cdot \varphi \\ &\quad - \frac{\alpha}{2} ([e_1, e_2] + f[e_1, e_2] + h[e_1, e_2]) \cdot \varphi \end{aligned}$$

where we denote $d^\nabla\eta(X, Y) = \nabla_X(\eta(Y)) - \nabla_Y(\eta(X)) - \eta([X, Y])$. First, by a straightforward computation, we see that the term

$$\begin{aligned} &+ \frac{\alpha}{2} \left(\eta(e_1) \cdot (e_2 + fe_2 + he_2) - (e_2 + fe_2 + he_2) \cdot \eta(e_1) \right) \cdot \varphi \\ &- \frac{\alpha}{2} \left(\eta(e_2) \cdot (e_1 + fe_1 + he_1) - (e_1 + fe_1 + he_1) \cdot \eta(e_2) \right) \cdot \varphi \end{aligned}$$

vanishes. Moreover, by Equations (11) and (12) and the fact that the Levi-civita is torsion-free, the term

$$\begin{aligned} &\frac{\alpha}{2} \left(\nabla_{e_1} e_2 + \nabla_{e_1}(fe_2) + \nabla_{e_1}^\perp(he_2) \right) \cdot \varphi - \frac{\alpha}{2} \left(\nabla_{e_2} e_1 + \nabla_{e_2}(fe_1) + \nabla_{e_2}^\perp(he_1) \right) \cdot \varphi \\ &- \frac{\alpha}{2} ([e_1, e_2] + f[e_1, e_2] + h[e_1, e_2]) \cdot \varphi \end{aligned}$$

also vanishes. Hence, we get

$$\begin{aligned} \mathcal{R}(e_1, e_2)\varphi &= d^\nabla\eta(e_1, e_2) \cdot \varphi + (\eta(e_2) \cdot (e_1) - \eta(e_1)\eta(e_2)) \cdot \varphi \\ &\quad + \frac{\alpha^2}{2} \left(\langle fe_1, e_2 \rangle^2 - \langle fe_1, e_1 \rangle \langle fe_2, e_2 \rangle \right) e_1 \cdot e_2 \cdot \varphi \\ &\quad + \frac{\alpha^2}{2} \left(\langle he_2, e_3 \rangle \langle fe_1, e_4 \rangle - \langle he_1, e_3 \rangle \langle he_2, e_4 \rangle \right) e_3 \cdot e_4 \cdot \varphi \\ &\quad + \frac{\alpha^2}{2} \left(fe_2 \cdot he_1 - fe_1 \cdot he_2 - e_2 \cdot he_1 + e_1 \cdot he_2 \right) \cdot \varphi \end{aligned}$$

But, as computed in [2], we have

$$(20) \quad \mathcal{R}(e_1, e_2)\varphi = -\frac{1}{2}K e_1 \cdot e_2 \cdot \varphi - \frac{1}{2}K_N e_3 \cdot e_4 \cdot \varphi,$$

$$(21) \quad d^\nabla\eta(X, Y) = -\frac{1}{2} \sum_{j=1}^2 e_j \cdot \left((\bar{\nabla}_X B)(Y, e_j) - (\bar{\nabla}_Y B)(X, e_j) \right),$$

where $\bar{\nabla}$ stands for the natural connection on $T^*M \otimes T^*M \otimes E$, and

$$(22) \quad \begin{aligned} \eta(e_2) \cdot \eta(e_1) - \eta(e_1) \cdot \eta(e_2) &= \frac{1}{2} (|B(e_1, e_2)|^2 - \langle B(e_1, e_1), B(e_2, e_2) \rangle) e_1 \cdot e_2 \\ &\quad + \frac{1}{2} \langle (S_{e_3} \circ S_{e_4} - S_{e_4} \circ S_{e_3})(e_1, e_2) \rangle e_3 \cdot e_4. \end{aligned}$$

Therefore, we have

$$G \cdot \varphi + R \cdot \varphi + C \cdot \varphi = 0,$$

where G , R and C are the 2-forms defined by

$$G = \left[K + \langle B(e_1, e_1), B(e_2, e_2) \rangle - |B(e_1, e_2)| + \alpha^2 \left(1 - \langle f e_1, e_2 \rangle^2 + \langle f e_1, e_1 \rangle \langle f e_2, e_2 \rangle \right) \right] e_1 \cdot e_2,$$

where K is the Gauss curvature of (M, g) ,

$$R = \left[K_E + \langle (S_{e_3} \circ S_{e_4} - S_{e_4} \circ S_{e_3})(e_1), e_2 \rangle + \alpha^2 (\langle h e_1, e_3 \rangle \langle h e_2, e_4 \rangle - \langle h e_1, e_4 \rangle \langle f e_2, e_3 \rangle) \right] e_3 \cdot e_4,$$

where K_E is the curvature of the bundle E , and

$$C = 2d^\nabla \eta(e_1, e_2) + \alpha^2 (f e_2 \cdot h e_1 - f e_1 \cdot h e_2 + e_2 \cdot h e_1 - e_1 \cdot h e_2).$$

As proved in [2], if T is a 2-form such that $T \cdot \varphi = 0$ with φ^+ and φ^- nowhere vanishing, then $T = 0$. Moreover, since G belongs to $\Lambda^2 M \otimes 1$, R belongs to $1 \otimes \Lambda^2 E$ and C is of mixed type, that is, belongs to $TM \otimes E$, then each of these three parts are zero. But $G = 0$ is nothing else but

$$K + \langle B(e_1, e_1), B(e_2, e_2) \rangle - |B(e_1, e_2)| = -\frac{c}{4} \left(1 - \langle f e_1, e_2 \rangle^2 + \langle f e_1, e_1 \rangle \langle f e_2, e_2 \rangle \right),$$

that is the Gauss equation. Similarly, $R = 0$ is equivalent to

$$K_E + \langle (S_{e_3} \circ S_{e_4} - S_{e_4} \circ S_{e_3})(e_1), e_2 \rangle = -\frac{c}{4} (\langle h e_1, e_3 \rangle \langle h e_2, e_4 \rangle - \langle h e_1, e_4 \rangle \langle f e_2, e_3 \rangle),$$

That is the Ricci equation. Finally $C = 0$, gives the Codazzi equations. Indeed, since

$$d^\nabla \eta(X, Y) = -\frac{1}{2} \sum_{j=1}^2 e_j \cdot \left((\nabla_X B)(Y, e_j) - (\nabla_Y B)(X, e_j) \right).$$

Thus, from $C = 0$, we deduce for $j = 1, 2$

$$(23) \quad \begin{aligned} (\nabla_{e_1} B)(e_2, e_j) - (\nabla_{e_2} B)(e_1, e_j) &= \frac{c}{4} \left[\langle f e_2, e_j \rangle h e_1 - \langle f e_1, e_j \rangle h e_2 \right. \\ &\quad \left. + \langle e_2, e_j \rangle h e_1 - \langle e_1, e_j \rangle h e_2 \right], \end{aligned}$$

which are the Coazzi equations. Since in addition, we have assumed Equations (6)-(12), by the theorem of Kowalczyk and De Lira-Tojeiro-Vitório, we get that (M^2, g) is isometrically immersed into P with B as second fundamental form and f, h, s and t coming from the product structure F of P . This concludes the proof. \square

Remark 3.2. *Note that in the proof, we only use Equations (11) and (12) in the computations. The other Equations (6)-(10) and (13)-(13) are only needed to apply the theorem of Kowalczyk and De Lira-Tojeiro-Vitóri, as well as the hypothesis on the rank of the maps $\frac{F+Id}{2}$ and $\frac{F-Id}{2}$.*

4. THE DIRAC EQUATION

Let φ be a spinor field satisfying Equation (19), then it satisfies the following Dirac equation

$$(24) \quad D\varphi = \vec{H} \cdot \varphi - \frac{\alpha}{2} \left[(2 + \text{tr}(f))\varphi - \beta \cdot \varphi \right],$$

where β is the 2-form defined by $\beta = \sum_{i=1,2} e_i \cdot h e_i = \sum_{i,j=1}^2 h_{ij} e_i \cdot \xi_j$, where $h_{i,j} = \langle h e_i, \xi_j \rangle$.

As in [2], we will show that this equation with an appropriate condition on the norm of both φ^+ and φ^- is equivalent to Equation (19), where the tensor B is expressed in terms on the

spinor field φ and such that $\text{tr}(B) = 2\vec{H}$. Moreover, from Equation (19) we deduce the following conditions on the derivatives of $|\varphi^+|^2$ and $|\varphi^-|^2$. Indeed, after decomposition onto Σ^+ and Σ^- , (19) becomes

$$\nabla_X \varphi^\pm = \frac{\alpha}{2} (X + fX + hX) \cdot \varphi^\mp + \eta(X) \cdot \varphi^\pm.$$

From this we deduce that

$$(25) \quad X(|\varphi^\pm|^2) = \Re \langle \alpha(X + fX + hX) \cdot \varphi^\mp, \varphi^\pm \rangle$$

Now, let φ a spinor field solution of the Dirac equation (24) with φ^+ and φ^- nowhere vanishing and satisfying the norm condition (25), we set for any vector fields X and Y tangent to M and $\xi \in E$

$$(26) \quad \langle B^+(X, Y), \xi \rangle = \frac{1}{2|\varphi^+|^2} \left[\frac{\alpha}{2} \langle (X \cdot fY + Y \cdot fX) \cdot \varphi^- + (X \cdot hY + Y \cdot hX) \cdot \varphi^-, \xi \cdot \varphi^+ \rangle + \langle X \cdot \nabla_Y \varphi^+ + \alpha \langle X, Y \rangle \varphi^-, \xi \cdot \varphi^+ \rangle \right],$$

and

$$(27) \quad \langle B^-(X, Y), \xi \rangle = \frac{1}{2|\varphi^-|^2} \left[\frac{\alpha}{2} \langle (X \cdot jY + Y \cdot jX) \cdot \varphi^+ + (X \cdot hY + Y \cdot hX) \cdot \varphi^+, \xi \cdot \varphi^- \rangle + \langle X \cdot \nabla_Y \varphi^- + \alpha \langle X, Y \rangle \varphi^+, \xi \cdot \varphi^- \rangle \right].$$

Finally, we set $B = B^+ + B^-$. Then, we have the following

Proposition 4.1. *Let $\varphi \in \Gamma(\Sigma)$ satisfying the Dirac equation (24)*

$$D\varphi = \vec{H} \cdot \varphi - \frac{\alpha}{2} [(2 + \text{tr}(f))\varphi - \beta \cdot \varphi]$$

such that

$$X(|\varphi^\pm|^2) = \Re \langle \alpha(X + fX + hX) \cdot \varphi^\mp, \varphi^\pm \rangle$$

then φ is solution of Equation (19)

$$\nabla_X \varphi = \frac{\alpha}{2} (X + fX + hX) \cdot \varphi + \eta(X) \cdot \varphi,$$

where η is defined by $\eta(X) = -\frac{1}{2} \sum_{j=1}^2 e_j \cdot B(e_j, X)$.

For the sake of clarity, the proof of this proposition will be given in the next section. Now, combining this proposition with Theorem 3.1, we get the following corollary.

Corollary 4.2. *Let $c \in \mathbb{R}$, $c \neq 0$ and $\alpha \in \mathbb{C}$ such that $4\alpha^2 = c$. Let (M^2, g) be an oriented Riemannian surface and E an oriented vector bundle of rank 2 over M with scalar product $\langle \cdot, \cdot \rangle_E$ and compatible connection ∇^E . We denote by $\Sigma = \Sigma M \otimes \Sigma E$ the twisted spinor bundle. Let f, h, s and s be some maps*

$$f : TM \longrightarrow TM, \quad h : TM \longrightarrow E, \quad s : E \longrightarrow TM \quad \text{and} \quad t : E \longrightarrow E$$

satisfying Equations (6)-(10). Moreover we assume that the rank of the maps $\frac{F+Id}{2}$ and $\frac{F-Id}{2}$ are 2 and 2 (resp. 3 and 1), where $F : TM \oplus E \longrightarrow TM \oplus E$ is defined by relations (5). Then, the two following statements are equivalent

- (1) *There exists an isometric immersion of (M^2, g) into $\mathbb{M}^2(c) \times \mathbb{R}^2$ (resp. $\mathbb{M}^3(c) \times \mathbb{R}$) with E as normal bundle and mean curvature \vec{H} such that over M the product structure is given by f, h, t and s .*
- (2) *There exists a spinor field φ in Σ solution of the Dirac equation*

$$D\varphi = \vec{H} \cdot \varphi - \frac{\alpha}{2} \left[(2 + \text{tr}(f))\varphi - \beta \cdot \varphi \right]$$

such that φ^+ and φ^- never vanish, satisfy the norm condition (25) and such that the maps f, h, s, t and the tensor B defined by (26) and (27) satisfy relations (11)-(13).

5. PROOF OF PROPOSITION 4.1

First, we decompose the Dirac equation (24) on the four spinor subbundles $\Sigma^{++}, \Sigma^{--}, \Sigma^{+-}$ and Σ^{-+} . We get the following four equations

$$\begin{cases} D\varphi^{--} = \vec{H} \cdot \varphi^{++} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{+-} + \frac{\alpha}{2}\beta \cdot \varphi^{-+}, \\ D\varphi^{++} = \vec{H} \cdot \varphi^{--} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{-+} + \frac{\alpha}{2}\beta \cdot \varphi^{+-}, \\ D\varphi^{+-} = \vec{H} \cdot \varphi^{-+} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{--} + \frac{\alpha}{2}\beta \cdot \varphi^{++}, \\ D\varphi^{-+} = \vec{H} \cdot \varphi^{+-} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{++} + \frac{\alpha}{2}\beta \cdot \varphi^{--}. \end{cases}$$

Now, we fix a point $p \in M$, and consider e_3 a unit vector in E_p so that the mean curvature vector is given by $\vec{H} = |\vec{H}|e_3$ at p . We complete e_3 by e_4 to get a positively oriented and orthonormal frame of E_p . First, we assume that $\varphi^{--}, \varphi^{++}, \varphi^{+-}$ and φ^{-+} do not vanish at p . It is easy to see that

$$\left\{ e_1 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|} \right\}$$

is an orthonormal frame of Σ^{++} for the real scalar product $\Re \langle \cdot, \cdot \rangle$. Indeed, we have

$$\begin{aligned} \Re \langle e_1 \cdot e_3 \cdot \varphi^{--}, e_2 \cdot e_3 \cdot \varphi^{--} \rangle &= \Re \langle \varphi^{--}, e_3 \cdot e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= \Re (i|\varphi^{--}|^2) = 0. \end{aligned}$$

Of course, by the same argument,

$$\begin{aligned} &\left\{ e_1 \cdot e_3 \cdot \frac{\varphi^{++}}{|\varphi^{++}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{++}}{|\varphi^{++}|} \right\}, \\ &\left\{ e_1 \cdot e_3 \cdot \frac{\varphi^{-+}}{|\varphi^{-+}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{-+}}{|\varphi^{-+}|} \right\}, \\ &\left\{ e_1 \cdot e_3 \cdot \frac{\varphi^{+-}}{|\varphi^{+-}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{+-}}{|\varphi^{+-}|} \right\} \end{aligned}$$

are orthonormal frames of Σ^{--}, Σ^{+-} and Σ^{-+} respectively. We define the following bilinear forms

$$\begin{aligned} F_{++}(X, Y) &= \Re \langle \nabla_X \varphi^{++}, Y \cdot e_3 \cdot \varphi^{--} \rangle, \\ F_{--}(X, Y) &= \Re \langle \nabla_X \varphi^{--}, Y \cdot e_3 \cdot \varphi^{++} \rangle, \\ F_{+-}(X, Y) &= \Re \langle \nabla_X \varphi^{+-}, Y \cdot e_3 \cdot \varphi^{-+} \rangle, \\ F_{-+}(X, Y) &= \Re \langle \nabla_X \varphi^{-+}, Y \cdot e_3 \cdot \varphi^{+-} \rangle, \end{aligned}$$

and

$$\begin{aligned} B_{++}(X, Y) &= -\frac{1}{2} \Re \langle \alpha(X + fX) \cdot \varphi^{-+} + ahX \cdot \varphi^{+-}, Y \cdot e_3 \cdot \varphi^{--} \rangle, \\ B_{--}(X, Y) &= -\frac{1}{2} \Re \langle \alpha(X + fX) \cdot \varphi^{+-} + ahX \cdot \varphi^{-+}, Y \cdot e_3 \cdot \varphi^{++} \rangle, \\ B_{+-}(X, Y) &= -\frac{1}{2} \Re \langle \alpha(X + fX) \cdot \varphi^{++} + ahX \cdot \varphi^{--}, Y \cdot e_3 \cdot \varphi^{+-} \rangle, \end{aligned}$$

$$B_{-+}(X, Y) = -\frac{1}{2}\Re\langle \alpha(X + fX) \cdot \varphi^{--} + \alpha hX \cdot \varphi^{++}, Y \cdot e_3 \cdot \varphi^{-+} \rangle.$$

We have this first lemma:

Lemma 5.1. *We have*

$$\begin{aligned} (1) \quad \text{tr}(F_{++}) &= -|\vec{H}| |\varphi^{--}|^2 + \frac{1}{2}\Re\langle \alpha(2 + \text{tr}(f))\varphi^{-+} + \alpha\beta \cdot \varphi^{+-}, e_3 \cdot \varphi^{--} \rangle, \\ (2) \quad \text{tr}(F_{--}) &= -|\vec{H}| |\varphi^{++}|^2 + \frac{1}{2}\Re\langle \alpha(2 + \text{tr}(f))\varphi^{+-} + \alpha\beta \cdot \varphi^{-+}, e_3 \cdot \varphi^{++} \rangle, \\ (3) \quad \text{tr}(F_{+-}) &= -|\vec{H}| |\varphi^{-+}|^2 + \frac{1}{2}\Re\langle \alpha(2 + \text{tr}(f))\varphi^{++} + \alpha\beta \cdot \varphi^{--}, e_3 \cdot \varphi^{-+} \rangle, \\ (4) \quad \text{tr}(F_{-+}) &= -|\vec{H}| |\varphi^{+-}|^2 + \frac{1}{2}\Re\langle \alpha(2 + \text{tr}(f))\varphi^{--} + \alpha\beta \cdot \varphi^{++}, e_3 \cdot \varphi^{+-} \rangle, \end{aligned}$$

Proof: We only compute the trace of F_{++} , the computations for the three others forms F_{--} , F_{+-} and F_{-+} are the same. We have

$$\begin{aligned} \text{tr}(F_{++}) &= F_{++}(e_1, e_1) + F_{++}(e_2, e_2) \\ &= \Re\langle \nabla_{e_1}\varphi^{++}, e_1 \cdot e_3 \cdot \varphi^{--} \rangle + \Re\langle \nabla_{e_2}\varphi^{++}, e_2 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= -\Re\langle e_1 \cdot \nabla_{e_1}\varphi^{++}, e_3 \cdot \varphi^{--} \rangle - \Re\langle e_2 \cdot \nabla_{e_2}\varphi^{++}, e_3 \cdot \varphi^{--} \rangle \\ &= -\Re\langle D\varphi^{++}, e_3 \cdot \varphi^{--} \rangle \end{aligned}$$

Since $D\varphi^{++} = \vec{H} \cdot \varphi^{--} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{-+} + \frac{\alpha}{2}\beta \cdot \varphi^{+-}$, we get

$$\begin{aligned} \text{tr}(F_{++}) &= -\Re\langle \vec{H} \cdot \varphi^{--} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{-+} + \frac{\alpha}{2}\beta \cdot \varphi^{+-}, e_3 \cdot \varphi^{--} \rangle \\ &= -\Re\langle |H|e_3 \cdot \varphi^{--}, e_3 \cdot \varphi^{--} \rangle + \Re\langle \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{-+} - \frac{\alpha}{2}\beta \cdot \varphi^{+-}, e_3 \cdot \varphi^{--} \rangle \\ &= -|\vec{H}| |\varphi^{--}|^2 + \frac{1}{2}\Re\langle \alpha(2 + \text{tr}(f))\varphi^{-+} + \alpha\beta \cdot \varphi^{+-}, e_3 \cdot \varphi^{--} \rangle \end{aligned}$$

This concludes the proof. \square

Now, we have this second lemma which gives the defect of symmetry:

Lemma 5.2. *We have*

$$\begin{aligned} (1) \quad F_{++}(e_1, e_2) &= F_{++}(e_2, e_1) - \frac{1}{2}\Re\langle (2 + \text{tr}(f))\varphi^{-+} - \alpha\beta \cdot \varphi^{+-}, e_4 \cdot \varphi^{--} \rangle, \\ (2) \quad F_{--}(e_1, e_2) &= F_{--}(e_2, e_1) - \frac{1}{2}\Re\langle (2 + \text{tr}(f))\varphi^{+-} - \alpha\beta \cdot \varphi^{-+}, e_4 \cdot \varphi^{++} \rangle, \\ (3) \quad F_{+-}(e_1, e_2) &= F_{+-}(e_2, e_1) + \frac{1}{2}\Re\langle (2 + \text{tr}(f))\varphi^{++} - \alpha\beta \cdot \varphi^{--}, e_4 \cdot \varphi^{+-} \rangle, \\ (4) \quad F_{-+}(e_1, e_2) &= F_{-+}(e_2, e_1) + \frac{1}{2}\Re\langle (2 + \text{tr}(f))\varphi^{--} - \alpha\beta \cdot \varphi^{++}, e_4 \cdot \varphi^{-+} \rangle. \end{aligned}$$

Proof: As for the proof of the previous lemma, we only give the details for F_{++} . We have

$$\begin{aligned} F_{++}(e_1, e_2) &= \Re\langle \nabla_{e_1}\varphi^{++}, e_2 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= \Re\langle e_1 \cdot \nabla_{e_1}\varphi^{++}, e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= \Re\langle \vec{H} \cdot \varphi^{--} - \frac{\alpha}{2}(2 + \text{tr}(f))\varphi^{-+} + \frac{\alpha}{2}\beta \cdot \varphi^{+-} - e_2 \cdot \nabla_{e_2}\varphi^{++}, e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle. \end{aligned}$$

The first term is

$$\begin{aligned} \Re\langle \vec{H} \cdot \varphi^{--}, e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle &= -\Re\langle e_3 \cdot \vec{H} \cdot \varphi^{--}, e_1 \cdot e_2 \cdot \varphi^{--} \rangle \\ &= \Re\langle \vec{H} \cdot e_3 \cdot \varphi^{--}, i\varphi^{--} \rangle \\ &= -\Re\langle i|\vec{H}| |\varphi^{--}|^2 \rangle = 0, \end{aligned}$$

where we have use that $ie_1 \cdot e_2 \cdot \varphi^{--} = -\varphi^{--}$, that is, $e_1 \cdot e_2 \cdot \varphi^{--} = i\varphi^{--}$ and $\bar{H} = |H|e_3$. Moreover, we have

$$\begin{aligned} -\Re \langle e_2 \cdot \nabla_{e_2} \varphi^{++}, e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle &= \Re \langle \nabla_{e_2} \varphi^{++}, e_2 \cdot e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= \Re \langle \nabla_{e_2} \varphi^{++}, e_1 \cdot e_3 \cdot \varphi^{--} \rangle \\ &= F_{++}(e_2, e_1). \end{aligned}$$

Finally, since $\varphi^{--} \in \Sigma^+$, we have $\omega_4 \cdot \varphi^{--} = \varphi^{--}$, which implies $e_1 \cdot e_2 \cdot e_3 \cdot \varphi^{--} = -e_4 \cdot \varphi^{--}$ and we get

$$F_{++}(e_1, e_2) = F_{++}(e_2, e_1) - \frac{1}{2} \Re \langle \alpha(2 + \text{tr}(f))\varphi^{-+} - \alpha\beta \cdot \varphi^{+-}, e_4 \cdot \varphi^{--} \rangle.$$

The proof is similar for the three other forms. \square

By analogous computations, we also get the following lemmas. We do not give the proof which is similar to the two previous ones.

Lemma 5.3. *We have*

$$\begin{aligned} (1) \quad \text{tr}(B_{++}) &= -\frac{1}{2} \Re \langle \alpha(2 + \text{tr}(f))\varphi^{-+} + \alpha\beta \cdot \varphi^{+-}, e_3 \cdot \varphi^{--} \rangle, \\ (2) \quad \text{tr}(B_{--}) &= -\frac{1}{2} \Re \langle \alpha(2 + \text{tr}(f))\varphi^{+-} + \alpha\beta \cdot \varphi^{-+}, e_3 \cdot \varphi^{++} \rangle, \\ (3) \quad \text{tr}(B_{+-}) &= -\frac{1}{2} \Re \langle \alpha(2 + \text{tr}(f))\varphi^{++} + \alpha\beta \cdot \varphi^{--}, e_3 \cdot \varphi^{-+} \rangle, \\ (4) \quad \text{tr}(B_{-+}) &= -\frac{1}{2} \Re \langle \alpha(2 + \text{tr}(f))\varphi^{--} + \alpha\beta \cdot \varphi^{++}, e_3 \cdot \varphi^{+-} \rangle. \end{aligned}$$

Lemma 5.4. *We have*

$$\begin{aligned} (1) \quad B_{++}(e_1, e_2) &= B_{++}(e_2, e_1) + \frac{1}{2} \Re \langle (2 + \text{tr}(f))\varphi^{-+} - \alpha\beta \cdot \varphi^{+-}, e_4 \cdot \varphi^{--} \rangle, \\ (2) \quad B_{--}(e_1, e_2) &= B_{--}(e_2, e_1) + \frac{1}{2} \Re \langle (2 + \text{tr}(f))\varphi^{+-} - \alpha\beta \cdot \varphi^{-+}, e_4 \cdot \varphi^{++} \rangle, \\ (3) \quad B_{+-}(e_1, e_2) &= B_{+-}(e_2, e_1) - \frac{1}{2} \Re \langle (2 + \text{tr}(f))\varphi^{++} - \alpha\beta \cdot \varphi^{--}, e_4 \cdot \varphi^{+-} \rangle, \\ (4) \quad B_{-+}(e_1, e_2) &= B_{-+}(e_2, e_1) - \frac{1}{2} \Re \langle (2 + \text{tr}(f))\varphi^{--} - \alpha\beta \cdot \varphi^{++}, e_4 \cdot \varphi^{+-} \rangle. \end{aligned}$$

Now, we set

$$\begin{cases} A_{++} := F_{++} + B_{++}, \\ A_{--} := F_{--} + B_{--}, \\ A_{+-} := F_{+-} + B_{+-}, \\ A_{-+} := F_{-+} + B_{-+}, \end{cases}$$

and

$$F_+ = \frac{A_{++}}{|\varphi^{--}|^2} - \frac{A_{--}}{|\varphi^{++}|^2} \quad \text{and} \quad F_- = \frac{A_{+-}}{|\varphi^{-+}|^2} - \frac{A_{-+}}{|\varphi^{+-}|^2}.$$

From the last four lemmas we deduce immediately that F_+ and F_- are symmetric and trace-free. Moreover, by a direct computation using the conditions (25) on the norms of φ^+ and φ^- , we get the following lemma:

Lemma 5.5. *The symmetric operators F^+ and F^- of TM associated to the bilinear forms F_+ and F_- , defined by*

$$F^+(X) = F_+(X, e_1)e_1 + F_+(X, e_2)e_2 \quad \text{and} \quad F^-(X) = F_-(X, e_1)e_1 + F_-(X, e_2)e_2$$

for all $X \in TM$, satisfy

$$\begin{aligned} (1) \quad \Re \langle F^+(X) \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle &= 0, \\ (2) \quad \Re \langle F^-(X) \cdot e_3 \cdot \varphi^{-+}, \varphi^{+-} \rangle &= 0. \end{aligned}$$

Proof. First, we have

$$A_{++}(X, Y) = \Re \langle \nabla_X \varphi^{++} - \alpha(X + fX) \cdot \varphi^{-+} + \alpha hX \cdot \varphi^{+-}, Y \cdot e_3 \cdot \varphi^{--} \rangle,$$

Since $(e_1 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|})$ is an orthonormal frame of Σ^{++} , we have

$$\begin{aligned} & \Re \langle \nabla_X \varphi^{++} - \frac{\alpha}{2}(X + fX) \cdot \varphi^{-+} + \frac{\alpha}{2}hX \cdot \varphi^{+-}, \varphi^{++} \rangle \\ = & \frac{A_{++}}{|\varphi^{--}|^2}(X, e_1) \Re \langle e_1 \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle + \frac{A_{++}}{|\varphi^{--}|^2}(X, e_2) \Re \langle e_2 \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle. \end{aligned}$$

Similarly,

$$\begin{aligned} & \Re \langle \nabla_X \varphi^{--} - \frac{\alpha}{2}(X + fX) \cdot \varphi^{+-} + \frac{\alpha}{2}hX \cdot \varphi^{-+}, \varphi^{--} \rangle \\ = & \frac{A_{--}}{|\varphi^{++}|^2}(X, e_1) \Re \langle e_1 \cdot e_3 \cdot \varphi^{++}, \varphi^{--} \rangle + \frac{A_{--}}{|\varphi^{++}|^2}(X, e_2) \Re \langle e_2 \cdot e_3 \cdot \varphi^{++}, \varphi^{--} \rangle \\ = & -\frac{A_{--}}{|\varphi^{++}|^2}(X, e_1) \Re \langle e_1 \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle - \frac{A_{--}}{|\varphi^{++}|^2}(X, e_2) \Re \langle e_2 \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle. \end{aligned}$$

Summing these two formulas imply that

$$\Re \langle F^+(X) \cdot e_3 \cdot \varphi^{--}, \varphi^{++} \rangle = \Re \langle \nabla_X \varphi^+ - \frac{\alpha}{2}(X + fX) \cdot \varphi^- + \frac{\alpha}{2}hX \cdot \varphi^-, \varphi^+ \rangle.$$

By the condition (25) on the derivative of the norm of φ^+ , this last expression is zero. The proof of the second relation is similar. \square

Hence, the operators F^+ and F^- are of rank at most ≤ 1 . Since they are symmetric and trace-free, they vanish identically.

Using again that $(e_1 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|}, e_2 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|})$ is an orthonormal frame of Σ^{++} , we have

$$\nabla_X \varphi^{++} = F_{++}(X, e_1)e_1 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|} + F_{++}(X, e_2)e_2 \cdot e_3 \cdot \frac{\varphi^{--}}{|\varphi^{--}|}.$$

Since $F_{++} = A_{++} - B_{++}$ and denoting by A^{++} and B^{++} the operators of TM associated to A_{++} and B_{++} and defined by

$$A^{++}(X) = A_{++}(X, e_1)e_1 + A_{++}(X, e_2)e_2, \quad B^{++}(X) = B_{++}(X, e_1)e_1 + B_{++}(X, e_2)e_2,$$

we get

$$(28) \quad \nabla_X \varphi^{++} = \frac{1}{|\varphi^{--}|^2} [A^{++}(X) \cdot e_3 \cdot \varphi^{--} - B^{++}(X) \cdot e_3 \cdot \varphi^{--}].$$

Similarly, we denote by A^{--} and B^{--} the operators of TM associated to A_{--} and B_{--} . Thus, we have

$$(29) \quad \nabla_X \varphi^{--} = \frac{1}{|\varphi^{++}|^2} [A^{--}(X) \cdot e_3 \cdot \varphi^{++} - B^{--}(X) \cdot e_3 \cdot \varphi^{++}].$$

Moreover, we easily get

$$B^{++}(X) \cdot e_3 \cdot \varphi^{--} = -\frac{1}{2}|\varphi^{--}|^2 \left(\alpha(X + fX) \cdot \varphi^{-+} + \alpha hX \cdot \varphi^{+-} \right)$$

and

$$B^{--}(X) \cdot e_3 \cdot \varphi^{++} = -\frac{1}{2}|\varphi^{++}|^2 \left(\alpha(X + fX) \cdot \varphi^{+-} + \alpha hX \cdot \varphi^{-+} \right).$$

Hence,

$$\begin{aligned} \nabla_X \varphi^+ &= \frac{1}{|\varphi^{--}|^2} A^{++}(X) \cdot e_3 \cdot \varphi^{--} + \frac{\alpha}{2}(X + fX) \cdot \varphi^{-+} + \frac{\alpha}{2}hX \cdot \varphi^{+-} \\ &+ \frac{1}{|\varphi^{++}|^2} A^{--}(X) \cdot e_3 \cdot \varphi^{++} + \frac{\alpha}{2}(X + fX) \cdot \varphi^{+-} + \frac{\alpha}{2}hX \cdot \varphi^{-+}. \end{aligned}$$

Now, we set $A^+ = A^{++} + A^{--}$. From the definition of A^{++} and A^{--} and since $F^+ = 0$, we have $\frac{A^{++}}{|\varphi^{--}|^2} = \frac{A^{--}}{|\varphi^{++}|^2}$. Bearing in mind that $|\varphi^+|^2 = |\varphi^{++}|^2 + |\varphi^{--}|^2$, we get finally

$$(30) \quad \frac{A^+}{|\varphi^+|^2} = \frac{A^{++}}{|\varphi^{--}|^2} = \frac{A^{--}}{|\varphi^{++}|^2}.$$

So, we have

$$(31) \quad \nabla_X \varphi^+ = \frac{1}{|\varphi^+|^2} A^+(X) \cdot e_3 \cdot \varphi^+ + \alpha(X + fX + hX) \cdot \varphi^-.$$

Analogously, we set A^{+-} and A^{-+} the operators of TM associated to A_{+-} and A_{-+} , and we denote $A^- = A^{+-} + A^{-+}$. Using the fact that $F^- = 0$ we get

$$(32) \quad \begin{aligned} \nabla_X \varphi^- &= \frac{1}{|\varphi^{+-}|^2} A^{+-}(X) \cdot e_3 \cdot \varphi^{+-} + \alpha(X + fX) \cdot \varphi^{++} + \alpha hX \cdot \varphi^{--} \\ &\quad + \frac{1}{|\varphi^{-+}|^2} A^{-+}(X) \cdot e_3 \cdot \varphi^{-+} + \frac{\alpha}{2}(X + fX) \cdot \varphi^{--} + \frac{\alpha}{2} hX \cdot \varphi^{++} \\ &= \frac{1}{|\varphi^-|^2} A^-(X) \cdot e_3 \cdot \varphi^- + \frac{\alpha}{2}(X + fX + hX) \cdot \varphi^+. \end{aligned}$$

We now observe that formulas (31) and (32) also hold if φ^{++} or φ^{--} , (resp. φ^{+-} or φ^{-+}) vanishes at p : indeed, assuming for instance that $\varphi^{++}(p) = 0$, and thus that $\varphi^{--}(p) \neq 0$ since $\varphi^+(p) \neq 0$, equation (28) holds, and, from the norm condition in (25), we have

$$\Re \left\langle \nabla_X \varphi^{--} - \frac{\alpha}{2}(X + fX) \cdot \varphi^{+-} + \frac{\alpha}{2} hX \cdot \varphi^{-+}, \varphi^{--} \right\rangle = 0.$$

Since $\left(\frac{\varphi^{--}}{|\varphi^{--}|}, i \frac{\varphi^{--}}{|\varphi^{--}|} \right)$ is an orthonormal basis of Σ^{--} , we deduce that

$$\nabla_X \varphi^{--} - \frac{\alpha}{2}(X + fX) \cdot \varphi^{+-} + \frac{\alpha}{2} hX \cdot \varphi^{-+} = i\delta(X) \frac{\varphi^{--}}{|\varphi^{--}|}$$

for some real 1-form δ . Moreover, since $\varphi^{++} = 0$ at p , we have

$$D\varphi^{--} + \alpha(2 + \text{tr}(f))\varphi^{+-} + \alpha\beta \cdot \varphi^{-+} = 0,$$

which implies

$$(\delta(e_1)e_1 + \delta(e_2)e_2) \cdot \frac{\varphi^{--}}{|\varphi^{--}|} = 0,$$

and thus that $\delta = 0$. We thus get $\nabla_X \varphi^{--} = \frac{\alpha}{2}(X + fX) \cdot \varphi^{+-} + \frac{\alpha}{2} hX \cdot \varphi^{-+}$ instead of (29), which, together with (28), easily implies (31).

Now, we set

$$\eta^+(X) = \left(\frac{1}{|\varphi^+|^2} A^+(X) \cdot e_3 \right)^+ \quad \text{and} \quad \eta^-(X) = \left(\frac{1}{|\varphi^-|^2} A^-(X) \cdot e_3 \right)^-$$

where, if σ belongs to $Cl^0(TM \oplus E)$, we denote by $\sigma^+ := \frac{1+\omega_4}{2} \cdot \sigma$ and by $\sigma^- := \frac{1-\omega_4}{2} \cdot \sigma$ the parts of σ acting on Σ^+ and on Σ^- only, *i.e.*, such that

$$\sigma^+ \cdot \varphi = \sigma \cdot \varphi^+ \in \Sigma^+ \quad \text{and} \quad \sigma^- \cdot \varphi = \sigma \cdot \varphi^- \in \Sigma^-.$$

Setting $\eta = \eta^+ + \eta^-$ we thus get

$$\nabla_X \varphi = \eta(X) \cdot \varphi + \frac{\alpha}{2}(X + fX + hX) \cdot \varphi,$$

as claimed in Proposition 4.1.

Now, we will compute B explicitly. For this, we set $A_+(X, Y) := \langle A^+(X), Y \rangle$ and $A_-(X, Y) := \langle A^-(X), Y \rangle$. Then, the form η is given by

$$\begin{aligned} \eta(X) &= \frac{1}{2|\varphi^+|^2} [A_+(X, e_1)(e_1 \cdot e_3 - e_2 \cdot e_4) + A_+(X, e_2)(e_2 \cdot e_3 + e_1 \cdot e_4)] \\ &\quad + \frac{1}{2|\varphi^-|^2} [A_-(X, e_1)(e_1 \cdot e_3 + e_2 \cdot e_4) + A_-(X, e_2)(e_2 \cdot e_3 - e_1 \cdot e_4)] \end{aligned}$$

with

$$A_+(X, Y) = \Re e \left\langle \nabla_X \varphi^+ - \frac{\alpha}{2}(X + fX + hX) \cdot \varphi^-, Y \cdot e_3 \cdot \varphi^+ \right\rangle$$

and

$$A_-(X, Y) = \Re e \left\langle \nabla_X \varphi^- - \frac{\alpha}{2}(X + fX + hX) \cdot \varphi^+, Y \cdot e_3 \cdot \varphi^- \right\rangle.$$

Moreover, we see easily by direct computations that for any vectors X and Y tangent to M ,

$$B(X, Y) := X \cdot \eta(Y) - \eta(Y) \cdot X$$

is a vector belonging to E which is such that

$$\begin{aligned} \langle B(X, Y), \xi \rangle &= \frac{1}{|\varphi^+|^2} \Re e \langle X \cdot \nabla_Y \varphi^+ - \alpha(X + fX + hX) \cdot Y \cdot \varphi^-, \xi \cdot \varphi^+ \rangle \\ &\quad + \frac{1}{|\varphi^-|^2} \Re e \langle X \cdot \nabla_Y \varphi^- - \alpha(X + fX + hX) \cdot Y \cdot \varphi^+, \xi \cdot \varphi^- \rangle \end{aligned}$$

for all $\xi \in E$.

Lemma 5.6. *The operator B defined above is symmetric in X and Y .*

Proof: The proof is analogous to the symmetry of A_{++} proven above and uses the Dirac equations

$$D\varphi^+ = \vec{H} \cdot \varphi^+ - \alpha \left[(2 + \text{tr}(f))\varphi^- - \beta \cdot \varphi^- \right]$$

and

$$D\varphi^- = \vec{H} \cdot \varphi^- - \alpha \left[(2 + \text{tr}(f))\varphi^+ - \beta \cdot \varphi^+ \right].$$

□

Now, computing

$$\langle \overline{B(X, Y)}, \xi \rangle = \frac{1}{2} (\langle B(X, Y), \xi \rangle + \langle B(Y, X), \xi \rangle)$$

we finally obtain that B is given in the discussion of Section 4.

Since $B(e_j, X) = e_j \cdot \eta(X) - \eta(X) \cdot e_j$, we obtain

$$(33) \quad \sum_{j=1,2} e_j \cdot B(e_j, X) = -2\eta(X) - \sum_{j=1,2} e_j \cdot \eta(X) \cdot e_j.$$

Writing $\eta(X)$ in the form $\sum_{k=1,2} e_k \cdot \eta_k$ for some vectors η_k belonging to E , we easily get

that $\sum_{j=1,2} e_j \cdot \eta(X) \cdot e_j = 0$. Indeed, we have

$$\begin{aligned} \sum_{j=1,2} e_j \cdot \eta(X) \cdot e_j &= \sum_{j=1,2} e_j \cdot \left(\sum_{k=1,2} e_k \cdot \eta_k \right) \cdot e_j \\ &= e_1 \cdot (e_1 \cdot \eta_1 + e_2 \cdot \eta_2) \cdot e_1 + e_2 \cdot (e_1 \cdot \eta_1 + e_2 \cdot \eta_2) \cdot e_2 \\ &= -\eta_1 \cdot e_1 - e_2 \cdot \eta_2 - e_1 \cdot \eta_1 - \eta_2 \cdot e_2 \\ &= e_1 \cdot \eta_1 + \eta_2 \cdot e_2 - e_1 \cdot \eta_1 - \eta_2 \cdot e_2 \\ &= 0 \end{aligned}$$

Thus, from (33), we get

$$\eta(X) = -\frac{1}{2} \sum_{j=1,2} e_j \cdot B(e_j, X).$$

The last claim in Proposition 4.1 is now proved. \square

REFERENCES

- [1] P. Bayard, *On the spinorial representation of spacelike surfaces into 4-dimensional Minkowski space*, J. Geom. Phys., in press.
- [2] P. Bayard, M.A. Lawn & J. Roth, *Spinorial representation of surfaces in four-dimensional Space Forms*, Ann. Glob. Anal. Geom., in press.
- [3] C. Bär, *Extrinsic bounds for eigenvalues of the Dirac operator*, Ann. Glob. Anal. Geom., 16 (1998) 573-596.
- [4] T. Friedrich, *On the spinor representation of surfaces in Euclidean 3-space*, J. Geom. Phys. (1998), 143-157.
- [5] D. Kowalczyk, *Isometric immersions into products of space forms*, Geom. Dedicata 151 (2011), 1-8.
- [6] M.A. Lawn & J. Roth, *Spinorial characterization of surfaces in pseudo-Riemannian space forms*, Math. Phys. Anal. and Geom. **14** (2011) no. 3, 185-195.
- [7] M.A. Lawn & J. Roth, *Isometric immersions of hypersurfaces into 4-dimensional manifolds via spinors*, Diff. Geom. Appl. **28** (2) (2010), 205-219
- [8] J.H. De Lira, R. Tojeiro & F. Vitório, *A Bonnet theorem for isometric immersions into products of space forms* Arch. Math. (Basel) **95** (5) (2010), 469-479
- [9] B. Morel, *Surfaces in \mathbb{S}^3 and \mathbb{H}^3 via spinors*, Actes du séminaire de théorie spectrale, Institut Fourier, Grenoble, 23 (2005), 9-22.
- [10] R. Nakad & J. Roth, *Hypersurfaces of Spin^c Manifolds and Lawson Correspondence*, Ann. Glob. Anal. Geom. 42 (3) (2012), 421-442 .
- [11] P. Piccione and D.V. Tausk, *An existence theorem for G-structure preserving affine immersions*, Indiana Univ. Math. J. 57 (3) (2008), 1431-1465.
- [12] J. Roth, *Spinorial characterization of surfaces into 3-dimensional homogeneous manifolds*, J. Geom. Phys. 60 (2010), 1045-106.
- [13] J. Roth, *Isometric immersion into Lorentzian products*, Int. J. Geom. Method. Mod. Phys, 8 (2011) no.6, 1-22.

(J. Roth) LAMA, UNIVERSITÉ PARIS-EST MARNE-LA-VALLÉE, CITÉ DESCARTES, CHAMPS SUR MARNE, 77454 MARNE-LA-VALLÉE CEDEX 2, FRANCE

E-mail address: julien.roth@univ-mlv.fr