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Rigorous Measurement of IP-level Neighborhood of Internet Core Routers

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Abstract—Many contributions use the degree distribution of IP-level internet topology. However, current knowledge of this property relies on biased and erroneous measurements, and so it is subject to much debate. We introduce here a new approach, dedicated to the core of the internet, which avoids the issues raised by classical measurements. It is based on the measurement of IP-level neighborhood of internet core routers, for which we design and implement a rigorous method. It consists in sending traceroute probes from many monitors distributed in the internet towards a given target router and carefully selecting the relevant information in collected data. Using simulations, we provide strong evidence of the accuracy of our approach. We then conduct real-world measurements illustrating the practical effectiveness of our method. This constitutes a significant step towards reliable knowledge of the IP-level degree distribution of the core of the internet.

I. INTRODUCTION

"A very general but largely ignored fact about Internet-related measurements is that what we can measure in an internet-like environment is typically not the same as what we really want to measure (or what we think we actually measure)."[1] This is particularly true for traceroute measurement of the topology. Maps are obtained by merging the paths obtained from a limited number of monitors to many targets. It has been shown that doing so leads to intrinsically biased views [2], [3], [4], [5], [6]. The classical assumption is that the bias on observed properties becomes less significant when the sample grows. However, the relevance of this assumption is far from trivial and it was even proved that it is false in some cases at least [7].

In addition, traceroute outputs themselves contain much erroneous information. This may be due to misconfigured routers, route dynamics, or circuit networks. Some of these errors are evidenced and discussed in [1], [8], [9], [10], [11]. Correcting such errors is extremely difficult in general, and often impossible. In particular, this is the case of erroneous links induced in tarceroute outputs by load-balancing on the network. The specificity of our approach allows us to tackle this problem.

We explore here a new approach for the measurement of the degree distribution of the IP-level topology of the core of the internet, which is one of its main properties. This approach does not rely anymore on the collection of a large sample obtained by merging traceroute outputs. Instead, we propose to select internet core routers, rigorously estimate their degrees, and infer the degree distribution from these. The success of this approach relies on our ability to get at least one interface of each IP-level neighbor of the router. Then, using anti-aliasing methods [12], [13], [8], [9], one may obtain the list of routers in the target neighborhood. It must be clear that the selection of internet core routers as well as anti-aliasing are non trivial issues. We do not address these problems here, which we consider as future work, and focus on the key point of our measurement approach: obtaining an interface of each neighbor of the target.

II. OUR APPROACH

The classical approach to estimate the degree distribution of IP-level internet topology consists in observing it on a map of this topology. Such maps are obtained by merging the outputs of many traceroute measurements (each such measurement being supposed to give an IP-level route, and so a path in the corresponding topology). The underlying assumptions are both that errors which may occur in traceroute measurements may be neglected, and that the degree distribution observed on large maps is similar to the actual one. However, the validity of both assumptions is far from established, and many results even seem to show that they are invalid: the measurement method in itself produces biased data [2], [3], [4], [5], [6], [7], and route dynamics and other internet features lead to many errors in observed routes [1], [8], [9], [10], [11].

The main objective of our approach is to get rid of the issues raised by the map construction. Instead, we focus on the measurement of the strict information needed to observe the property of interest. In our case, we aim at obtaining the exact degree of a given node of the internet. Doing so for many random nodes opens the way to rigorous inference of the actual degree distribution. Clearly, the more nodes we consider, the more precise the inference may be. However, even inference from a relatively small sample would lead to
significant improvement of the current situation, if the degrees in the sample are correctly measured.

In addition, our approach reveals other key advantages. First, it clarifies our understanding of the limitations of the measurement process. While [14] argue on the impact of adding sources or destinations in the classical approach, this impact is quite clear with our approach: adding sources increases the precision of our estimation of target degrees, and adding destinations increases the representativity of the sample of nodes used to infer the distribution.

Another benefit of our approach is that the operation of estimation of the degree of a given target, or a set of targets, is atomic: at the end of such an operation, we instantaneously get the desired degrees and we can conduct a new measurement on a different set of destinations. This is not possible with classical measurements which cannot merged only part of the collected traceroute outputs: the result is available only at the end of the measurement, which must last long in order to get a large enough sample of the graph.

With our approach, repeating the atomic measurement operation, we can collect degrees of a set of targets as wide as desired, in order to infer the degree distribution. Moreover, as a round of measurement is short, it is not too sensitive to changes in the network topology. Indeed, these changes artificially increase the degree of affected nodes by making them appear adjacent both to their earlier neighbors and to their newer ones. On the opposite, because they require long observation periods, classical measurements are quite sensitive to these changes of the topology. At last, note that the time locality of our atomic measurement operation makes it possible to observe changes in the degree distribution along time, without suffer from changes of the topology.

In order to get the degree of a given router, called target, we launch ICMP traceroute probes from many monitors towards this target. The last hop of each traceroute gives in principle an interface (IP address) of an IP-level neighbor of the target. The key objective here is to ensure that we reach the target passing through all of its neighbors. See Figure 1 (left).

Classically, internet IP-level topology is divided into two parts: the core and the border. The core is defined as the network obtained by removing all trees attached to it (i.e. iteratively removing all nodes with only one link). The border is the union of these removed trees. Here, we focus on the degree distribution of the core of the internet. While the tree structure of the border simply carries traffic from end-hosts up to the core and from the core down to end-hosts, the core is the part of the network responsible for non-trivial routing. Having a precise knowledge of the structure of this part of the topology is crucial for many aspects, such as security and quality of service. Our method is precisely dedicated to the measurement of the degree distribution of this central part of the network.

Note that it is inappropriate to observe degrees of nodes in the border. Indeed, if the target is in a tree structure (see Figure 1 (right)), the routes coming from the monitors will arrive to \( t' \) from its higher level neighbor in the tree, namely node \( a \) in this case. Then, the degree of \( t' \) will be evaluated to one though it is much greater: it has many links to the end-hosts it provides traffic to, which we have no chance to reach with our monitors. Although, the rigorous measurement and knowledge of the border part of the network is also of prime interest, and it should be achieved using methods specifically designed for this goal.

Opposite to the case of a border node, if the target is in the core, we can expect to reach it passing through all of its neighbors (see Figure 1 (left)). The crucial point for this is that the set of monitors we use is numerous enough and distributed enough in the internet so that we arrive to the target coming from all directions. To this purpose, we use PlanetLab nodes [15]. PlanetLab provides a set of 952 machines made available to researchers by 483 institutions (mainly research labs) widely distributed in the world.

It must be clear that if the target has a low number of neighbors, say for instance 2 or 3, then we will certainly discover all of them with these monitors. On the contrary, we cannot observe more neighbors than the number of monitors, and more generally if the target has many neighbors we will certainly miss some. The key question then is to determine the limit between the two situations: how many monitors do we need compared to the degree of the target, or equivalently, given a number of monitors, up to what degrees are we able to capture the whole neighborhood? We explore these questions with simulations, in next section, and we obtain strong evidences of the fact that, up to a relatively large degree, our approach performs very well.

III. Simulations

In order to validate our approach, we construct an artificial graph, then select random nodes in it which will serve as monitors, and simulate traceroute measurements from these monitors to all other nodes (targets). In this way, we are able to observe the quality of the estimation of the degree of each possible target. We have to choose on which
graphs we should perform the simulations, and how to model traceroute measurements.

Following classical modeling approaches [2], [6], supported by empirical observations [6], we will assume that traceroute delivers a random shortest path. This makes the simulation simpler to run and interpret, while having limited impact on the results presented here.

As a first case of study, to keep simulations simple, we use here random graphs with Poisson degree distribution (see Figure 2). Clearly, it would be desirable to conduct simulations on other graph models closer to internet topology such as random powerlaw graphs or HOT models. This is one of the main perspectives of the simulation part of our work. Poisson graphs have two parameters: their size and their average degree. Clearly, we can difficulty consider graphs of a size similar to the actual internet. Instead, we use two graphs, with respectively one million and ten millions nodes, in order to investigate size effects. We conducted simulations with various average degrees. We only present the case with average degree 20, which is large compared to the assumed average degree of internet topology, and therefore should not favor our approach. The results with different average degrees are identical to those presented here.

In [2], Lakhina et al. investigated, using similar simulations, the performance of the classical method, consisting in merging paths obtained between a set of sources and a set of destinations. They generated random graphs with 100 000 nodes and average degree 15, having Poisson degree distribution, and merged random shortest paths obtained from 10 sources to 1 000 destinations. Their results show a striking fact: the observed degree distribution they obtained is not a Poisson distribution but rather looks like a powerlaw distribution. This fact was analytically proven in [3] in the case of a unique source. This shows that the observation of a set of destinations from a source is intrinsically biased toward heterogeneous distributions. This raises the question of knowing whether the degree distribution observed by classical methods reflects the degree distribution of the network or that of the measurement process.

Figure 2 shows degree distributions obtained for various numbers of monitors. As expected, it appears clearly that having a low number of monitors leads to erroneous estimations. More precisely, using 25 monitors, the average observed degree is lower than 15, while the actual one is 20. This is not surprising, as the number of monitors itself is close to the average degree. On the other hand, it is very interesting to note that even with a low number of monitors, the observed distribution is still Poisson. Though its parameters appears modified, our method qualitatively preserves the shape of the distribution. This is a major improvement compared to the classical approach.

When the number of monitors grows, the estimation rapidly becomes much better. With 200 monitors, the degree distribution is very well estimated, and there is no improvement when increasing this number. It is remarkable that even for the nodes with the largest degrees (30 and more), the observation is excellent. For both graphs, the observed maximal degree is only two units less than the original one (43 instead of 45 and 46 instead of 48), and 97% of nodes having degree at least 30 are estimated to have such a degree (89% for nodes of degree at least 35). It therefore seems that, at least for such degrees and for graphs of this size, having a few hundreds monitors (like in PlanetLab) is sufficient.

One may however argue that the internet is much larger than the graphs used here. But the simulations clearly show a striking fact: the graph size has little, if any, impact on the results. This fits the intuition that the key point is the target degree, not the graph size: as long as monitors are well distributed in the graph, the size has limited impact on our ability to reach the target by all its neighbors, provided that the number of these neighbors is reasonably small. We consider the formal analysis of this empirical observation as an interesting perspective, as well as the study of other classes of graphs, in particular some with very high degree nodes.

Finally, simulations presented here clearly show that our method is relevant and is free from the bias highlighted in [2], [3]. They also indicate that the method discovers all neighbors of nodes with a reasonable number of monitors when their degree is not too large. Then, the number of monitors available in PlanetLab should be sufficient in most cases. Further investigation in Section V shows that cases where they are not sufficient seem to be extremely rare.
IV. FAKE NEIGHBORS DETECTION

An important issue in traceroute measurements is the errors induced by dynamics in the routes [1], [10], [11]: if the route from a monitor to a target changes during a running of traceroute, then false links may be observed. One may guess that such events are quite rare, but because of the generalization of load-balancing they are actually very frequent, see [10], [11].

For example, in Figure 3 (left), there are different routes from monitor m to target t. Then, conducting a traceroute measurement from m to t, it may happen that the second packet (TTL=2) takes the upper route, while the third one (TTL=3) takes the bottom route. In this case, the output of traceroute is the route \( m-a_1-b_1-t \), which produces the false link \( b_1-t \). Similarly, in the case of Figure 3 (right), because of load-balancer \( a \), if the route changes during a traceroute measurement, it may produce route \( m-a-b_1-e_1-t \), or route \( m-a-d_1-c_1-t \), then delivering false link \( b_1-e_1 \) or \( d_1-c_1 \). The output of traceroute is a mix of all possible routes.

Nevertheless, there is a big difference between the two configurations depicted on Figure 3. In the left configuration, routes have different lengths and fake neighbors appear (that is, false links involving the target). On the opposite, in the right configuration, routes have the same length and we observe the actual neighbors of the target. This is a general fact: changes in the routes followed by packets have no impact on observed neighbors of the target as long as all routes have the same length. This is due to the fact that, in such cases, even though traceroute may mix the routes, every node will always appear at the same distance both from the monitor and from the target. In particular, nodes in penultimate position on a route are neighbors of \( t \), which is our only concern in the present context. Note that the possibility of distinguishing configurations producing fake neighbors takes advantage of the specificity of our approach, which concentrate on the last hop. It does not allow to avoid false links anywhere else along the routes.

Then, our method to detect pairs \( m, t \) likely to produce fake neighbors is to send several probes and examine the length of produced routes. This raises the question of bounding the probability that there exist routes of different lengths that we did not detect, depending on the number of probes we sent. We did not address the question in its whole generality. Nevertheless, it is worth studying the case where there are exactly two routes of lengths \( l_1 \) and \( l_2 \) with \( l_1 < l_2 \), having equal probability to be followed by traceroute packets. When a packet with TTL=\( l_1 \) is sent to target \( t \), it follows one of the two routes. If it follows the shortest one, it arrives to \( t \) and the route of length \( l_1 \) is discovered. If the packet follows the longest route, it does not reach \( t \) and traceroute outputs a route of length greater than \( l_1 \). It follows that the probability that \( n \) probes give only routes of the same length is bounded by \( 2 \times (1/2)^n \). In this case at least, it decreases exponentially with the number of probes, and only few probes should be necessary in order to detect the existence of two different route lengths.

V. SAMPLE MEASUREMENT

In this section, we show how to implement our method and we give the result of a measurement conducted on a random set of targets. This must not been considered as an estimation of the degree distribution of any set of routers of internet. Indeed, as we mentioned previously, we did not implement any anti-aliasing technique nor any selection method for routers in the core of internet. These issues are key perspective and we let them for future work. The goal of this section is to demonstrate the practical effectiveness of our method and to show how we can clean obtained data without loosing information.

A. Measurement setup

As we already mentioned, we used PlanetLab nodes as monitors for our measurement. Although these machines may not be uniformly distributed in the internet, we will assume that they are dispersed enough for our purpose. One may argue that this is not the case because planetlab nodes lies mainly on academic networks. But still, destinations we choose are not on such networks and these networks have many connections to others all over the world. As shown by simulations, the critical point of comparison is between this number of outgoing connections and the degree of target routers. Nevertheless, clearly, widening the set of monitors we use by integrating other sets, more widely distributed or larger, is one of our main perspectives, see Section VI.

Notice that some PlanetLab monitors may not be suitable for our needs. For instance, they may experience frequent shutdowns, or have poor internet connectivity. They may even filter ICMP (or belong to a network which does so). As managing these issues before the measurement is very difficult and subject to errors, we used all the monitors during our measurement, and discarded those which provided irrelevant data afterwards.

To construct our list of targets, we randomly sampled 250,000 distinct 32 bit integers (IP-addresses), and sent an ICMP ECHO REQUEST to each of them. We recorded the 10,000 first addresses which answered to this request. Again, note that our selected target are not necessarily in the core of the internet. This does not matter as we do not intend to get an estimation of the degree distribution, but we are only interested in illustrating our method.

Finally, we ran our measurement from the 5th to the 6th of July 2009 as follows. For each monitor, we shuffled the
target list, obtained a few hours before, and generated a shell script that sends a traceroute every second to each of the targets, in the given shuffled order. This loop is repeated 10 times by each monitor, following its own shuffled order. Once all the scripts have been generated, we sent each of them to the corresponding monitor. Then, we sent a start command to every monitor. The measurement ended about 30 hours later, once 90% monitors that had successfully received and started the script had terminated (some never terminate, mostly due to shutdowns or errors unrelated to the script itself). The raw output was then retrieved and analyzed locally.

### B. Irrelevant monitors and targets

The first step of our filtering process, which aims at obtaining reliable (and complete) data, consists in discarding monitors and targets that have irrelevant behavior with regard to our goal.

We say that a traceroute is valid if it reaches its target. As our targets are supposed to answer to ICMP ECHO REQUEST, and as we use ICMP traceroute, all traceroutes should in principle be valid. However, it may happen that the monitor is unable to conduct the measurement (for instance if it has no ICMP capabilities) and, more importantly, a target may be unreachable at some time during the measurement. In our case, we obtained 36,928,702 valid traceroutes from 544 monitors to 10,000 targets (not all monitors and targets produce the same number of valid traceroutes) and examined their repartition among monitors and targets.

![Fig. 4. Cumulative distribution of the number of valid traceroutes per monitor.](image)

Monitors from which we obtain a low number of valid traceroutes should be discarded. First because they make the number of monitors used in our inference larger than it actually is, and because they may parasite the following of the filtering process. The distribution of the number of valid traceroutes for each monitor (Figure 4) shows that only 68 monitors out of 544 (~12%) obtained less than 71,783 valid traceroutes out of 77,316 (~92%), which is the maximum number of valid traceroutes collected by a monitor. We then discarded these 68 monitors and kept only the data from the remaining 476 for the following. According to Section III, this should not make us loose any data.

Similarly, targets for which we obtain no valid traceroute, or only few, should be discarded: we have too limited information on them. This is probably due to target shutdowns or network failures. We will assume that there is no correlation between this and the target degree. We first removed the 605 targets obtaining no valid traceroute (this may be due to the fact that the target are no longer connected at the time of the measurement), and we plotted the distribution of the number of valid traceroutes per target (Figure 5). It shows that 2314 targets out of 9395 remaining ones (~25%) obtained less than 3502 valid traceroutes out of 4760 (~74%). In the sequel, we do not consider them anymore and we go on with the 7081 remaining targets. Note that, necessarily, these remaining targets have been observed by at least 350 different monitors (since a monitor produces at most 10 valid traceroutes per destination).

C. Fake neighbors correction

At this point, only traceroutes from 476 monitors to 7,081 targets remain. Thanks to the 10 repetitions of traceroute between each pair of monitor and target, we can now filter the part of data that may contain erroneous neighbors. We showed in Section IV that this mistrustful data comes from the pairs for which all valid traceroutes have different lengths. Fortunately, about 75% of them produced constant-length routes. In order to remove the others from our data, we plotted the distribution of the number of monitors that produced all its traceroutes of the same length per target (see Figure 6). It turns out that only 980 targets out of 7,081 (~14%) have less than 350 monitors producing constant-length routes. Then, we discarded all mistrustful pairs and kept only the 6,101 targets still observed by enough monitors afterwards. Again, we make the assumption that having routes of different lengths is independent from target degree.

D. Results

The distribution of the number of neighbor interfaces\(^2\) observed for each target in our sample measurement is given in Figure 7. Let us insist on the fact that this is not an estimation of any degree distribution: neighbor routers may be counted

\(^2\)Traceroutes producing a star in last but one position do not give any neighbor interface of the target in the considered topology, and therefore do not contribute to the distribution.
Fig. 6. Cumulative distribution of the number of targets per monitor reached by constant-length routes. A point with coordinate \((x, y)\) means that exactly \(y\) targets obtained all traceroutes with the same length from \(x\) monitors or less.

![Cumulative distribution graph](image)

Fig. 7. Final distribution of the number of neighboring interfaces per target.

![Final distribution graph](image)

several times as we do not recognize different interfaces of a same router, and the sample contains targets in the border of the topology (for which we miss some neighbors).

Notice however that most targets have a low number of neighbor interfaces, which is in accordance with domain knowledge, but that none of them has a very high degree. Indeed, although our method would underestimate the degrees of such nodes, simulations show that their order of magnitude would not change. But the largest value observed in our measurement is 57, which is itself an upper bound of the number of neighbor routers (remind that several interfaces may belong to a same router). This means that there was no high-degree node in our random sample of 10,000 nodes, and that such nodes are therefore very rare (much rarer than expected in a power-law distribution). As a consequence, our method is appropriate for observation of the vast majority of nodes.

VI. CONCLUSION AND PERSPECTIVES.

We presented a method to obtain an interface of each neighbor of a router in the core of the internet. This constitutes an important step towards precise estimation of the degree distribution of the IP-level router topology, which is our main perspective. It now relies on anti-aliasing techniques, thus increasing significantly the importance of this problem, and on selection of targets from which to infer the global degree distribution. Indeed, randomly selecting interfaces does not lead to random routers selection as the sampling is biased by the number of interfaces attached to routers. Correction of this bias is necessary.

Our work also raises several key questions which may be tackled formally. In particular, one may formally establish the results we obtain here with simulations, such as the fact that our approach succeeds in discovering all neighbors of targets, or the limited impact of the size of the underlying graph, which we empirically observe here.

Another direction for improving our results is to increase the number of involved monitors, in order to obtain more reliable measurements for high-degree nodes (we have seen that this would not improve results for low-degree nodes). To that purpose, one may use looking glasses, i.e., websites providing the possibility to run traceroute measurements from them (more than one thousand such sites are currently available), as well as monitors from the DIMES project, which counts approximately one thousand machines. Notice that these monitors and those of PlanetLab may be used all together, and that their number increases rapidly.

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