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Enrica Masi, Olivier Simonin

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An algebraic-closure-based moment method for unsteady Eulerian modeling of non-isothermal particle-laden turbulent flows in very dilute regime and high Stokes number

E. Masi and O. Simonin

*Institut de Mécanique des Fluides de Toulouse, UMR CNRS/INPT/UPS 5502,
Allée Camille Soula, 31400 Toulouse, France, masi@imft.fr, simonin@imft.fr*

Abstract — An algebraic-closure-based moment method (ACBMM) is developed for unsteady Eulerian particle simulations coupled with direct numerical simulations (DNS) of non-isothermal fluid turbulent flows, in very dilute regime and for large Stokes numbers. It is based on a conditional statistical approach [1] which provides a local instantaneous characterization of the dynamic of the dispersed phase accounting for the effect of crossing between particle trajectories which occurs for large Stokes numbers.

1. Introduction

Particle-laden turbulent flows are encountered in several industrial applications and need to be modeled. In order to model the turbulence at industrial scales, Reynolds-averaged Navier-Stokes (RANS) methods or large-eddy simulations (LES) are usually used depending on the nature of the flow. The LES are particularly adequate for modeling unsteady turbulences of internal flows confined in complex geometries as, for instance, in combustion chambers of aero engines. For these two-phase flow applications, the entire mixture needs to be modeled and a question about the choice of the most appropriate method for modeling the particulate phase arises. In the literature, a method which has been extensively used over the years is the Eulerian-Lagrangian LES approach [2, 3]. According to this approach, the turbulence is resolved by means of the LES and the particle properties are obtained by using a Lagrangian method. So far, the Eulerian-Lagrangian LES approach has presented two major limits: the prohibitive computational cost of the numerical simulation when this method is used for real industrial applications; the difficulty to model the coupling between particles and turbulent fluid flow because of the small non-resolved scales of the turbulence [4, 5]. An alternative to the Eulerian-Lagrangian LES approach is the Eulerian-Eulerian LES approach. The latter implies that the particulate phase is described as a continuum medium at the same level as the turbulence so that a straightforward coupling between phases is possible in an Eulerian framework. This approach is considerably less expensive than a Lagrangian technique and thus suitable provided that a satisfactory level of accuracy is ensured. In the literature, several successfully models are available in the framework of the Eulerian-Eulerian RANS modeling [6, 7, 8, 9, 10]. In contrast, the Eulerian-Eulerian LES (or DNS, as direct numerical simulations) of dilute or very dilute highly inertial particle-laden turbulent flows are still a timely topic of research. Indeed, the existing DNS/LES Eulerian models [11, 12, 13, 14, 15, 16] have proven to be able to correctly predict the dispersed phase behaviour only for Stokes numbers smaller than the critical one ($St_K \ll 1$ based on the Kolmogorov timescale). In this work an appropriate model for predicting unsteady Eulerian particle simulations coupled with DNS of non-isothermal fluid turbulent flows in very dilute regime and for large Stokes numbers is proposed. It should be

considered as the starting point for developing the Eulerian-Eulerian LES approach [17].

2. Unsteady Eulerian Modeling

The algebraic-closure-based moment method (ACBMM) is based on a conditional statistical approach [1] which provides a local instantaneous characterization of the dynamic of the dispersed phase accounting for the effect of crossing between particle trajectories which occurs for large Stokes numbers. This phenomenon has a great impact on the thermal characterization of the dispersed phase as well. Indeed, the occurrence of crossing trajectories entails that particles convey information of their interactions with very distant, and independent, turbulent eddies, that is with different dynamic and thermal turbulent scales. This effect involves many different velocities and temperatures in the same volume of control, violating the assumption of the uniqueness of the particle velocity and temperature distributions. An extension of the statistical approach accounting for non-isothermal conditions may be found in Ref. [18]. Particle velocity and temperature are partitioned in two contributions: i) an Eulerian particle (velocity and temperature) field, referred to as mesoscopic field, which is spatially correlated and shared by all the particles and which accounts for correlations between particles and between particles and fluid; ii) a spatially-uncorrelated particle (velocity and temperature) contribution, referred to as random uncorrelated motion (RUM) contribution, associated with each particle and resulting from the chaotic behaviour of the particles. The RUM contribution is characterized in terms of Eulerian fields of particle velocity and temperature moments; the larger is the particle inertia the more important is the RUM. The proposed ACBMM computes low-order moments of the conditional probability density function (PDF) using a set of governing equations which are derived from the PDF kinetic equation in the general frame of the kinetic theory of dilute gases. It consists of a set of three equations describing the evolution of the mesoscopic particle number density \tilde{n}_p , the mesoscopic velocity $\tilde{u}_{p,i}$ and the mesoscopic temperature \tilde{T}_p , which needs to be closed by providing constitutive relations as algebraic closures. Neglecting gravity and radiant sources and assuming non-interacting and non-colliding spherical particles in translation, with a same diameter equal or smaller than the Kolmogorov lengthscale, a density much larger than that of the fluid, stationary inter-phase heat transfers and constant heat capacity, the set of Eulerian equations is [19, 18]

$$\frac{\partial \tilde{n}_p}{\partial t} + \frac{\partial \tilde{n}_p \tilde{u}_{p,i}}{\partial x_i} = 0, \quad (1)$$

$$\frac{\partial \tilde{n}_p \tilde{u}_{p,i}}{\partial t} + \frac{\partial \tilde{n}_p \tilde{u}_{p,i} \tilde{u}_{p,j}}{\partial x_j} = -\frac{\tilde{n}_p}{\tilde{\tau}_p} (\tilde{u}_{p,i} - u_{f,i}) - \frac{\partial \tilde{n}_p \delta R_{p,ij}}{\partial x_j}, \quad (2)$$

$$\frac{\partial \tilde{n}_p \tilde{T}_p}{\partial t} + \frac{\partial \tilde{n}_p \tilde{u}_{p,j} \tilde{T}_p}{\partial x_j} = -\frac{\tilde{n}_p}{\tilde{\tau}_\theta} (\tilde{T}_p - T_f) - \frac{\partial \tilde{n}_p \delta \Theta_{p,j}}{\partial x_j}, \quad (3)$$

where $u_{f,i}$ and T_f are the fluid velocity and temperature and $\tilde{\tau}_p = \langle (1/\tau_p) | \mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle^{-1}$ and $\tilde{\tau}_\theta = \langle (1/\tau_\theta) | \mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle^{-1}$ are the mesoscopic dynamic and thermal response times obtained by conditional ensemble averaging the particle response times

$$\tau_p = \frac{4\rho_p d_p}{3\rho_f C_D \|\mathbf{u}_p - \mathbf{u}_{f@p}\|}, \quad \tau_\theta = \frac{Pr \rho_p d_p^2 C_{pp}}{6Nu \mu_f C_{pf}}; \quad (4)$$

$\mathbf{u}_{f@p}$ is the fluid velocity at the particle location, Pr is the Prandtl number, μ_f and ν_f are the dynamic and kinematic fluid viscosity respectively, ρ_f is the density of the fluid, ρ_p and d_p are

the particle density and the particle diameter, and C_{pp}/C_{pf} is the particle-to-fluid heat capacity ratio. C_D and Nu are the corrected drag coefficient [20] and Nusselt number [21]

$$C_D = \frac{24}{Re_p}(1 + 0.15Re_p^{0.687}), \quad Nu = 2 + 0.552Re_p^{1/2}Pr^{1/3}, \quad (5)$$

formulated in terms of the particle Reynolds number, $Re_p = ||\mathbf{u}_p - \mathbf{u}_{f@p}||d_p/\nu_f$. The highest-order moment appearing in Eq. (2) is the second-order velocity moment referred to as RUM particle kinetic stress tensor (RUM-ST), $\delta R_{p,ij}(\mathbf{x}, t) = \langle \delta u_{p,i}(t)\delta u_{p,j}(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$. The highest-order unclosed moment in Eq. (3) is the velocity-temperature correlation $\delta \Theta_{p,i}(\mathbf{x}, t) = \langle \delta u_{p,i}(t)\delta T_p(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$ referred to as RUM particle heat flux (RUM-HF) for the sake of simplicity (although this term has no longer units of a heat flux since the particle mass and heat capacity were removed because constant quantities). The first term on the right hand side (r.h.s.) of Eq. (2) accounts for the effects of the drag force and the second term is the transport due to the RUM-ST. The first term on the r.h.s. of Eq. (3) represents the interphase heat exchanges and the second contribution is the transport of the mesoscopic temperature due to the RUM-HF. At the second order, the modeling leads to an equation for the RUM-ST [22]

$$\frac{\partial \tilde{n}_p \delta R_{p,ij}}{\partial t} + \frac{\partial \tilde{n}_p \delta R_{p,ij} \tilde{u}_{p,k}}{\partial x_k} = -2 \frac{\tilde{n}_p}{\tilde{\tau}_p} \delta R_{p,ij} - \tilde{n}_p \delta R_{p,jk} \frac{\partial \tilde{u}_{p,i}}{\partial x_k} - \tilde{n}_p \delta R_{p,ik} \frac{\partial \tilde{u}_{p,j}}{\partial x_k} - \frac{\partial}{\partial x_k} \tilde{n}_p \delta Q_{p,ijk}, \quad (6)$$

and an equation for the RUM-HF [23]

$$\begin{aligned} \frac{\partial}{\partial t} \tilde{n}_p \delta \Theta_{p,i} + \frac{\partial}{\partial x_j} \tilde{n}_p \tilde{u}_{p,j} \delta \Theta_{p,i} = & - \tilde{n}_p \left(\frac{1}{\tilde{\tau}_p} + \frac{1}{\tilde{\tau}_\theta} \right) \delta \Theta_{p,i} - \tilde{n}_p \delta \Theta_{p,j} \frac{\partial \tilde{u}_{p,i}}{\partial x_j} - \tilde{n}_p \delta R_{p,ij} \frac{\partial \tilde{T}_p}{\partial x_j} \\ & - \frac{\partial}{\partial x_j} \tilde{n}_p \delta \Delta_{p,ij}. \end{aligned} \quad (7)$$

The highest-order moments appearing in Eqs. (6)-(7) are third-order RUM correlations defined by the conditional ensemble average as $\delta Q_{p,ijk}(\mathbf{x}, t) = \langle \delta u_{p,i}(t)\delta u_{p,j}(t)\delta u_{p,k}(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$ and $\delta \Delta_{p,ij}(\mathbf{x}, t) = \langle \delta u_{p,i}(t)\delta u_{p,j}(t)\delta T_p(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$. The first term on the r.h.s. of Eq. (6) represents the dissipation of the RUM-ST while second and third terms are productions by mesoscopic velocity gradients. The first term on the r.h.s. of Eq. (7) accounts for the dissipation of the RUM-HF due to heat and momentum transfers and second and third terms are productions by both mesoscopic velocity and temperature gradients. In the framework of the ACBMM approach proposed in this study, Eqs. (6) and (7) are not resolved but rather used for the development of the second-order moment closures. Preliminary two-dimensional Eulerian-Eulerian DNS using modeled RUM-ST in conjunction with resolved RUM-HF may be found in Ref. [24]. With the purpose of deriving algebraic closures, the equation of the evolution of the RUM kinetic energy ($\delta \theta_p(\mathbf{x}, t) = 0.5 \langle \delta u_{p,i}(t)\delta u_{p,i}(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$) and the RUM temperature variance ($\delta \theta_\theta(\mathbf{x}, t) = 0.5 \langle \delta T_p(t)\delta T_p(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$) are also written [19, 23]:

$$\frac{\partial \tilde{n}_p \delta \theta_p}{\partial t} + \frac{\partial \tilde{n}_p \delta \theta_p \tilde{u}_{p,m}}{\partial x_m} = -\tilde{n}_p \delta R_{p,nn} \frac{\partial \tilde{u}_{p,n}}{\partial x_m} - 2 \frac{\tilde{n}_p}{\tilde{\tau}_p} \delta \theta_p - \frac{1}{2} \frac{\partial}{\partial x_m} \tilde{n}_p \delta Q_{p,nnm}, \quad (8)$$

$$\frac{\partial \tilde{n}_p \delta \theta_\theta}{\partial t} + \frac{\partial \tilde{n}_p \delta \theta_\theta \tilde{u}_{p,m}}{\partial x_m} = -\tilde{n}_p \delta \Theta_{p,m} \frac{\partial \tilde{T}_p}{\partial x_m} - 2 \frac{\tilde{n}_p}{\tilde{\tau}_\theta} \delta \theta_\theta - \frac{1}{2} \frac{\partial}{\partial x_m} \tilde{n}_p \delta \Omega_{p,m}. \quad (9)$$

The last term in Eq. (9) is defined as $\delta \Omega_{p,m}(\mathbf{x}, t) = \langle \delta u_{p,m}(t)\delta T_p(t)\delta T_p(t)|\mathbf{x}_p(t) = \mathbf{x}; \mathcal{H}_f \rangle$. The ACBMM bases its efficiency and accuracy on the algebraic closures provided for modeling the RUM-ST and the RUM-HF; in this study, this concern is addressed.

3. Modeling The RUM Particle Kinetic Stress Tensor (RUM-ST)

The RUM stress tensor is composed of spherical and deviatoric contributions

$$\delta R_{p,ij} = \frac{1}{3}\delta R_{p,kk}\delta_{ij} + \delta R_{p,ij}^* = \frac{2}{3}\delta\theta_p\delta_{ij} + \delta R_{p,ij}^*. \quad (10)$$

The spherical part may be obtained by means of an additional transport equation [19, 25] while the deviatoric contribution needs to an algebraic closure. In this work the deviatoric RUM-ST is modeled by using a polynomial representation for tensor functions [23]. The polynomial representation is used in the framework of an assumption of equilibrium of the local anisotropy. Indeed, one of the most important finding of this study was to observe that the RUM-ST is a self-similar tensor which means that its temporal and spatial evolutions are related to that of its trace, involving equilibrium of anisotropy. Such an equilibrium leads to an algebraic stress model (ASM) which is an implicit and nonlinear system of equations referred to as 2 Φ ASM (by analogy with turbulence models, see, e.g. [26] and references cited in). It is obtained defining a local RUM anisotropy tensor as

$$b_{p,ij}^* = \frac{\delta R_{p,ij}}{2\delta\theta_p} - \frac{1}{3}\delta_{ij}. \quad (11)$$

Then the equilibrium involves

$$\frac{D}{Dt}b_{p,ij}^* = 0 \quad \text{with} \quad \frac{D}{Dt} = \frac{\partial}{\partial t} + \tilde{u}_{p,j}\frac{\partial}{\partial x_j}, \quad (12)$$

which using the definition (11) gives the relation

$$\frac{D}{Dt}\delta R_{p,ij} = \frac{\delta R_{p,ij}}{\delta\theta_p} \frac{D}{Dt}\delta\theta_p. \quad (13)$$

Injecting Eqs. (6) and (8) into Eq. (13), and assuming equality between left hand side (l.h.s.) and r.h.s. third-order correlations, the equation takes the form

$$\delta R_{p,ij} \left(-\frac{\delta R_{p,nm}}{2\delta\theta_p} \frac{\partial \tilde{u}_{p,n}}{\partial x_m} \right) = -\frac{1}{2}\delta R_{p,jk} \frac{\partial \tilde{u}_{p,i}}{\partial x_k} - \frac{1}{2}\delta R_{p,ik} \frac{\partial \tilde{u}_{p,j}}{\partial x_k}. \quad (14)$$

Defining the mesoscopic particle rate-of-strain and vorticity tensors as, respectively,

$$S_{p,ij} = \frac{1}{2} \left(\frac{\partial \tilde{u}_{p,i}}{\partial x_j} + \frac{\partial \tilde{u}_{p,j}}{\partial x_i} \right), \quad \Omega_{p,ij} = \frac{1}{2} \left(\frac{\partial \tilde{u}_{p,i}}{\partial x_j} - \frac{\partial \tilde{u}_{p,j}}{\partial x_i} \right), \quad (15)$$

and using the decomposition of $S_{p,ij}$ in deviatoric and spherical contributions $S_{p,ij} = S_{p,ij}^* + \frac{1}{3}S_{p,kk}\delta_{ij}$ and the RUM anisotropy definition, Eq. (14) may be rearranged as

$$\begin{aligned} b_{p,ij}^* (-2b_{p,nm}^* S_{p,nm}^*) = & - \frac{2}{3}S_{p,ij}^* - \left(b_{p,ik}^* S_{p,kj}^* + S_{p,ik}^* b_{p,kj}^* - \frac{2}{3}b_{p,nm}^* S_{p,nm}^* \delta_{ij} \right) \\ & + (b_{p,ik}^* \Omega_{p,kj} - \Omega_{p,ik} b_{p,kj}^*), \end{aligned} \quad (16)$$

which represents the implicit nonlinear 2 Φ ASM model proposed for closing the RUM-ST. Explicit solutions are then provided using techniques well known in turbulence [27, 28, 29]. Hereinafter, bold notation denotes three-dimensional second-rank tensors, curly brackets $\{.\}$ represent the tensor trace and the asterisk means traceless tensor. The matrix multiplication is then

defined in a matrix notation as $\mathbf{C} = \mathbf{A}\mathbf{B} = A_{ik}B_{kj} = C_{ij}$ and $\mathbf{B}^2 = \mathbf{B}\mathbf{B}$. According to Pope [30], the anisotropy tensor may be expressed using a polynomial representation for tensor functions $\mathbf{b}^* = \sum_{\varsigma} G_{\varsigma} \mathbf{T}^{(\varsigma)}$ which represents the linear combination of a set of non-dimensional independent, symmetric and deviatoric second-order tensors $\mathbf{T}^{(\varsigma)}$, using scalar coefficients G_{ς} which are functions of the invariants of the dimensionless \mathbf{S}^+ and $\mathbf{\Omega}^+$. Using the Cayley-Hamilton theorem, Pope [30] showed that a set of ten ($\varsigma = 10$) tensors $\mathbf{T}^{(\varsigma)}$ is needed to form an integrity basis [31] in order to express every symmetric deviatoric three-dimensional second-order tensor formed by \mathbf{S}^+ and $\mathbf{\Omega}^+$; the problem then reduces to model the ten coefficients G_{ς} (see, e.g., Refs. [27, 29]). However, the integrity basis and coefficients associated with may be reduced if some approximations are introduced. Using a two-dimensional flow approximation (three tensor basis) Girimaji [28] developed a self-consistent solution technique in order to model the Reynolds stresses in turbulent flows. In this work, we will use the same technique applied to our 2Φ ASM model. The algebraic, implicit and nonlinear system for the dispersed phase is rewritten using the Girimaji's notation as

$$\mathbf{b}^* (L_1^0 - L_1^1 \{\mathbf{b}^* \mathbf{S}^+\}) = L_2 \mathbf{S}^+ + L_3 \left(\mathbf{b}^* \mathbf{S}^+ + \mathbf{S}^+ \mathbf{b}^* - \frac{2}{3} \{\mathbf{b}^* \mathbf{S}^+\} \mathbf{I} \right) - L_4 (\mathbf{b}^* \mathbf{\Omega}^+ - \mathbf{\Omega}^+ \mathbf{b}^*), \quad (17)$$

where $L_1^0 = 0$, $L_1^1 = 2$, $L_2 = -\frac{2}{3}$, $L_3 = -1$ and $L_4 = -1$, \mathbf{S}^+ and $\mathbf{\Omega}^+$ are dimensionless tensors by the quantity $II_S^{1/2} = \{\mathbf{S}^{*2}\}^{1/2}$ and \mathbf{I} is the identity matrix. According to Girimaji [28], the general representation of the anisotropy tensor under the two-dimensional approximation is

$$\mathbf{b}^* = \sum_{\varsigma=1}^3 G_{\varsigma} \mathbf{T}^{(\varsigma)} = G_1 \mathbf{S}^+ + G_2 (\mathbf{S}^+ \mathbf{\Omega}^+ - \mathbf{\Omega}^+ \mathbf{S}^+) + G_3 \left(\mathbf{S}^{+2} - \frac{1}{3} \{\mathbf{S}^{+2}\} \mathbf{I} \right), \quad (18)$$

where the three coefficients are functions of the two invariants $\eta_1 = \{\mathbf{S}^{+2}\}$ and $\eta_2 = \{\mathbf{\Omega}^{+2}\}$. Using Eq. (18) and the two-dimensional hypothesis, the contracted product $b_{p,ij}^* S_{p,ij}^+$ may be written as

$$b_{p,ij}^* S_{p,ij}^+ = G_1 S_{p,ij}^+ S_{p,ij}^+ = G_1 \eta_1. \quad (19)$$

Inserting equations (18) and (19) into the system (17) leads to

$$\begin{aligned} & [G_1 \mathbf{S}^+ + G_2 (\mathbf{S}^+ \mathbf{\Omega}^+ - \mathbf{\Omega}^+ \mathbf{S}^+) + G_3 (\mathbf{S}^{+2} - \frac{1}{3} \{\mathbf{S}^{+2}\} \mathbf{I})] (L_1^0 - \eta_1 L_1^1 G_1) = \\ & (L_2 + \frac{1}{3} \eta_1 L_3 G_3 - 2\eta_2 L_4 G_2) \mathbf{S}^+ + 2L_3 G_1 (\mathbf{S}^{+2} - \frac{1}{3} \{\mathbf{S}^{+2}\} \mathbf{I}) - L_4 G_1 (\mathbf{S}^+ \mathbf{\Omega}^+ - \mathbf{\Omega}^+ \mathbf{S}^+). \end{aligned} \quad (20)$$

Then, comparison between homogeneous l.h.s. and r.h.s. terms in Eq. (20) leads to explicit solutions for the unknown coefficients. In our particular case in which $L_1^0 = 0$, the coefficients G_2 and G_3 are directly obtained as follows

$$G_2 = \frac{L_4}{\eta_1 L_1^1}, \quad G_3 = -\frac{2L_3}{\eta_1 L_1^1}, \quad (21)$$

and G_1 reduces to the solution of a pure quadratic

$$G_1^2 = -\frac{1}{\eta_1 L_1^1} [L_2 + \frac{1}{3} \eta_1 L_3 G_3 - 2\eta_2 L_4 G_2]. \quad (22)$$

Eq. (22) with the "L" coefficients leads to $G_1 = \pm \sqrt{2\eta_1 + 2\eta_2/2\eta_1}$, which admits real solutions only for $\eta_1 + \eta_2 \geq 0$. Unfortunately, as η_1 and η_2 have positive and negative sign respectively,

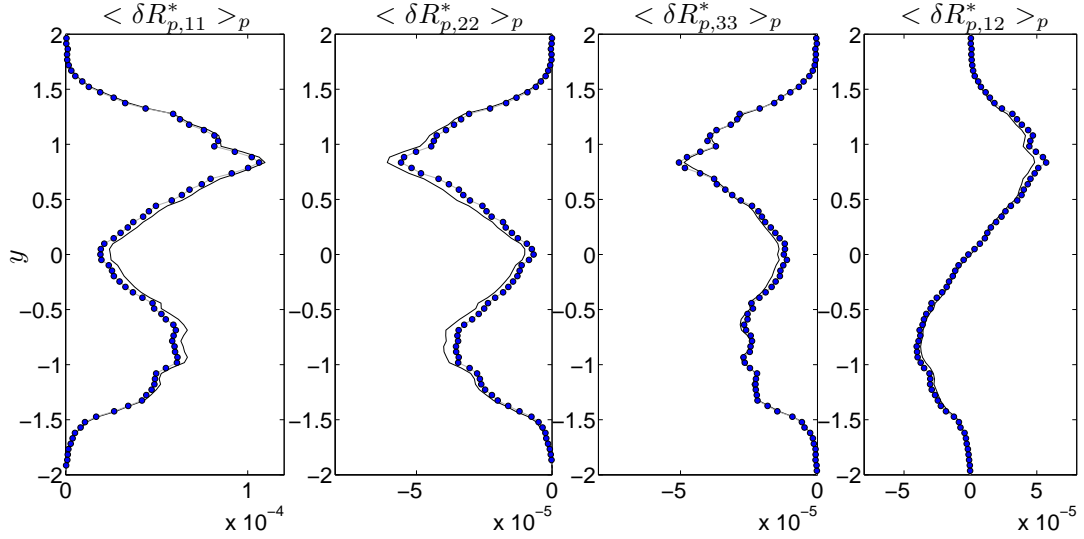


Figure 1: Profiles of actual (solid line) and modeled (line with symbols) mean deviatoric RUM stresses, at the time $t = 6.2T_{f@p}$.

real solutions are not ensured. In order to use this model, local negative values of the discriminant are set to zero. The legitimacy of such an approximation was investigated in Ref. [23]; it was observed that negative values correspond to small magnitudes of both the particle rate-of-strain and vorticity tensors justifying the approximation $G_1 = 0$. Concerning the sign of the coefficient G_1 , according to Eq. (19) and the definition of the normalized production of the RUM particle kinetic energy by shear ($-\{\mathbf{b}^* \mathbf{S}^*\}$, from Eq. (8)), in the simplest case it should be taken as negative. Negative sign for G_1 is obtained in turbulence, in the domain of applicability of an equilibrium assumption of anisotropy [28]. However, for the dispersed phase interacting with turbulent flows, it is usual to have reverse energy exchanges from the RUM to the mesoscopic contribution [17, 18] corresponding to a reverse sign of the first-order coefficient G_1 . In the special case in which the deviatoric RUM-ST and the deviatoric particle rate-of-strain are axisymmetric tensors (as reported in Refs. [23, 32]), assuming that the principal direction of the RUM-ST is aligned with the most extensive or compressive direction of the particle rate-of-strain, then the sign of the contracted product $b_{p,ij}^* S_{p,ij}^+$, which is the same of G_1 , is given by the sign of the third invariant of the particle rate-of-strain tensor defined as $\eta_3 = \{\mathbf{S}^{+3}\}$. In this case the solution becomes $G_1 = \text{sign}(\eta_3) \sqrt{2\eta_1 + 2\eta_2}/2\eta_1$. Injecting the coefficients G_1 , G_2 , G_3 into Eq. (18) leads to an explicit solution for the RUM anisotropy tensor and thus for the RUM-ST. Hereinafter, this model will be referred to as 2 Φ EASM. Results from preliminary isothermal Eulerian-Eulerian DNS using 2 Φ EASM may be found in Ref. [33].

4. Modeling The RUM Particle Heat Flux (RUM-HF)

In a similar way, the RUM-HF is modeled assuming similarity between the evolution of the RUM heat flux and that of the square root correlation between the RUM kinetic energy ($\delta\theta_p$) and the RUM temperature variance ($\delta\theta_\theta$), which involves the equilibrium of the normalized heat flux. This assumption may be written as

$$\frac{D}{Dt} \frac{\delta\Theta_{p,i}}{\sqrt{\delta\theta_p \delta\theta_\theta}} = 0 \quad (23)$$

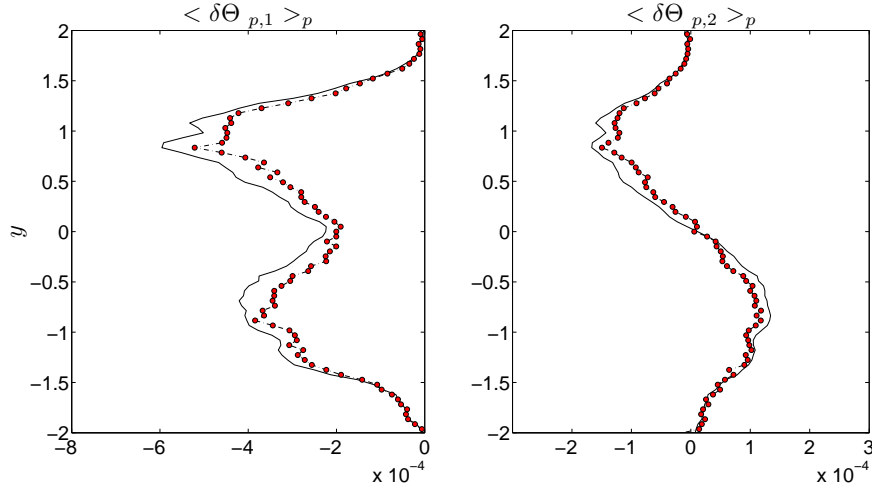


Figure 2: Profiles of actual (solid line) and modeled (line with symbols) mean streamwise and normalwise RUM-HF components, at the time $t = 6.2T_{f@p}$.

which developed leads to

$$\frac{1}{\sqrt{\delta\theta_p\delta\theta_\theta}} \frac{D}{Dt} \delta\Theta_{p,i} = \frac{1}{2} \frac{\delta\Theta_{p,i}}{\sqrt{\delta\theta_p\delta\theta_\theta}} \frac{1}{\delta\theta_p} \frac{D}{Dt} \delta\theta_p + \frac{1}{2} \frac{\delta\Theta_{p,i}}{\sqrt{\delta\theta_p\delta\theta_\theta}} \frac{1}{\delta\theta_\theta} \frac{D}{Dt} \delta\theta_\theta. \quad (24)$$

Then injecting Eqs. (7), (8) and (9) into Eq. (24) and assuming equality between l.h.s. and r.h.s. diffusion terms, the equation takes the form

$$\frac{\delta\Theta_{p,i}}{\sqrt{\delta\theta_p\delta\theta_\theta}} \left(-\frac{1}{2} \frac{\delta\Theta_{p,l}}{\delta\theta_\theta} \frac{\partial \tilde{T}_p}{\partial x_l} - \frac{1}{2} \frac{\delta R_{p,kl}}{\delta\theta_p} \frac{\partial \tilde{u}_{p,k}}{\partial x_l} \right) = -\frac{\delta R_{p,il}}{\sqrt{\delta\theta_p\delta\theta_\theta}} \frac{\partial \tilde{T}_p}{\partial x_l} - \frac{\delta\Theta_{p,l}}{\sqrt{\delta\theta_p\delta\theta_\theta}} \frac{\partial \tilde{u}_{p,i}}{\partial x_l}, \quad (25)$$

which may be rearranged as follows

$$\delta H_{p,i} \left(-\frac{1}{2} \delta H_{p,l} \tilde{K}_{p,l} - b_{p,kl}^* S_{p,kl}^* \right) = -2 \left(b_{p,il}^* + \frac{1}{3} \delta_{il} \right) \tilde{K}_{p,l} - (S_{p,il}^* + \Omega_{p,il}) \delta H_{p,l}, \quad (26)$$

by defining the quantities

$$\delta H_{p,i} = \frac{\delta\Theta_{p,i}}{\sqrt{\delta\theta_p\delta\theta_\theta}}, \quad \tilde{K}_{p,i} = \sqrt{\frac{\delta\theta_p}{\delta\theta_\theta}} \frac{\partial \tilde{T}_p}{\partial x_i}. \quad (27)$$

A fully dimensionless system may be obtained using non-dimensionalized quantities $\tilde{K}_{p,i}$, $S_{p,ij}^*$ and $\Omega_{p,ij}$ by the same inverse timescale, then referred to as $\tilde{K}_{p,i}^+$, $S_{p,ij}^+$ and $\Omega_{p,ij}^+$. Eq. (26) is an implicit and nonlinear particle algebraic heat flux model (AHFM), referred to as 2Φ AHFM (by analogy with turbulence models). Explicit self-consistent solutions, 2Φ EAHFM, are then provided using a technique suggested for turbulent heat flux by Wikström *et al.* [34] and by introducing a regularization procedure for ensuring non-singular solutions during the process of matrix inversion. Eq. (26) was indeed rearranged in a similar way that the analogous equation of Wikström *et al.* [34] in order to straightforwardly apply their technique to our 2Φ AHFM. Using the same notation as in Ref. [34], we define the scalar quantity into the parentheses on the l.h.s. of Eq. (26) as

$$N_\theta = -\frac{1}{2} \delta H_{p,l} \tilde{K}_{p,l}^+ - b_{p,kl}^* S_{p,kl}^+. \quad (28)$$

The system (26) may then be solved by inverting the matrix

$$A_{p,ij} = N_\theta \delta_{ij} + S_{p,ij}^+ + \Omega_{p,ij}^+, \quad (29)$$

obtaining the explicit solutions

$$\delta H_{p,i} = -2A_{p,ij}^{-1} \left(b_{p,jl}^* + \frac{1}{3}\delta_{jl} \right) \tilde{K}_{p,l}^+. \quad (30)$$

According to the Cayley-Hamilton theorem, an analytic expression for \mathbf{A}^{-1} may be written (see, e.g., Ref. [35]) and the operation of matrix inversion is ensured provided that \mathbf{A} admits real non-zero eigenvalues so to avoid the occurrence of singularities when its determinant (denominator of the analytical solution) vanishes. The technique of Wikström *et al.* [34] involves injecting the relation of the flux (Eq. 30 in our case) into the definition of N_θ (Eq. 28 in our case), replacing \mathbf{A}^{-1} by its analytical expression. For fully three-dimensional flows, this leads to a fourth-order polynomial in N_θ difficult to handle. An alternative is to resolve a third-order polynomial corresponding to a two-dimensional flow approximation and then using the solution for three-dimensional flows as well [34]. Assuming two-dimensional flows (but using three-dimensional tensors) the analytic expression for the inverse of the matrix is

$$\mathbf{A}^{-1} = \frac{N_\theta \mathbf{I} - (\mathbf{S}^+ + \mathbf{\Omega}^+)}{N_\theta^2 - \frac{1}{2}(\eta_1 + \eta_2)}. \quad (31)$$

Injecting Eq. (31) into Eq. (30) and the latter into the definition (28) the following third-order polynomial is obtained

$$2N_\theta^3 + 2\{\mathbf{b}^* \mathbf{S}^+\} N_\theta^2 - (Q_1 + R_1) N_\theta - \{\mathbf{b}^* \mathbf{S}^+\} Q_1 + R_2 = 0, \quad (32)$$

where $Q_1 = \eta_1 + \eta_2$ and the terms R_1 and R_2 are, respectively,

$$\begin{aligned} R_1 &= 2 \left\{ \left(b_{p,il}^* + \frac{1}{3}\delta_{il} \right) \tilde{K}_{p,l}^+ \tilde{K}_{p,i}^+ \right\} \\ R_2 &= 2 \left\{ (S_{p,ij}^+ + \Omega_{p,ij}^+) \left(b_{p,jl}^* + \frac{1}{3}\delta_{jl} \right) \tilde{K}_{p,l}^+ \tilde{K}_{p,i}^+ \right\}. \end{aligned} \quad (33)$$

A unique real solution is then ensured using transcendental functions as in Ref. [34]. At this point, we need to address the concern of stable solutions by ensuring the determinant of the matrix does not vanish and singularities do not occur. From the *a priori* analysis, we observed that the determinant is mainly positive and that negative values correspond to small magnitudes of it. In order to avoid singular solutions the determinant should not change its sign and the following condition should be satisfied

$$\det(\mathbf{A}) = N_\theta^2 - \frac{1}{2}(\eta_1 + \eta_2) > 0 \quad (34)$$

while, in general, it is not. Solutions proposed in Ref. [34] for turbulent flows do not apply to the dispersed phase and a regularization procedure is therefore necessary. The reciprocal of the determinant is re-written as follows

$$\det(\mathbf{A})^{-1} = \frac{1}{N_\theta^2 - \frac{1}{2}(\eta_1 + \eta_2)} = \frac{2/(2N_\theta^2)}{1 - \eta^2/(2N_\theta^2) + \xi^2/(2N_\theta^2)} = \frac{2/(2N_\theta^2)}{1 + \xi^2/(2N_\theta^2) - x^2} \quad (35)$$

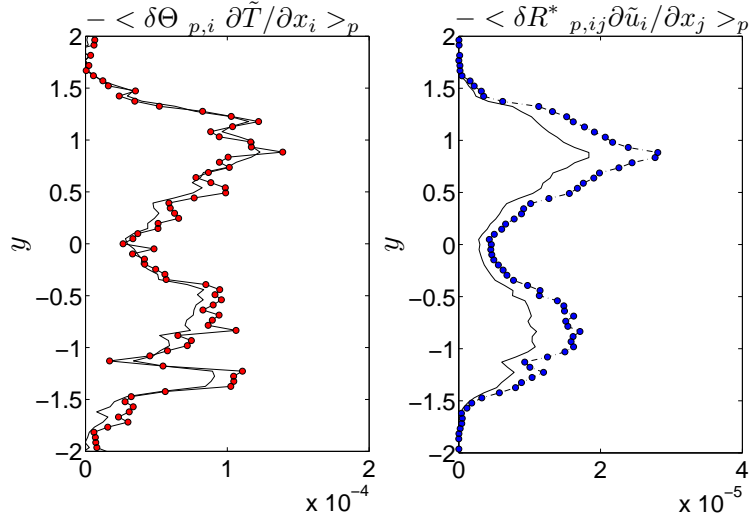


Figure 3: Mean profiles of actual (solid line) and modeled (line with symbols) RUM temperature variance production (left) and RUM kinetic energy production (right), at the time $t = 6.2T_{f@p}$.

where $\eta = \sqrt{\eta_1}$, $\xi = \sqrt{-\eta_2}$ and $x^2 = \eta^2/(2N_\theta^2)$. Then, using the first order MacLaurin series of the function $1/(1+x^2)$ we write $x^2 \approx 1 - 1/(1+x^2)$ which inserted into Eq. (35) leads to

$$\det(\mathbf{A})^{-1} = \frac{2(2N_\theta^2 + \eta^2)}{(2N_\theta^2)^2 + \xi^2(2N_\theta^2 + \eta^2)}. \quad (36)$$

The stability is thus ensured as the denominator of Eq. (36) never vanishes for N_θ and ξ^2 or $\eta^2 \neq 0$. The same regularization procedure was used by Gatski and Speziale [27] for modeling the Reynolds stress tensor in the framework of the EASM approach. Hereinafter, explicit regularized solutions for the RUM-HF will be referred to as 2 Φ EAHFM.

5. A Priori Analysis

An evaluation of the ACBMM by assessing the proposed algebraic closures is given by an *a priori* analysis using particle Eulerian fields which are extracted from a Eulerian-Lagrangian DNS of a temporal particle-laden non-isothermal turbulent planar jet. The numerical simulation corresponds to the dispersion of a cold particle-laden jet into a hot homogeneous isotropic decaying turbulence [36]. The simulation domain is a cube of length size $L_{box} = 2\pi L_{ref}$ and mesh 128^3 cells. The initial gas velocity has hyperbolic-tangent profile supplemented with statistically homogeneous and isotropic velocity fluctuations [37]. The initial gas temperature has hyperbolic-tangent mean profile and zero fluctuations. As we assume very dilute regime, collisions and turbulence modulation are not accounted for. Within the slab, of width $d = 0.25L_{box}$, 13 millions of solid particles are randomly embedded at the same mean velocity and temperature as the carrier flow and zero fluctuations. The simulation corresponds to a Stokes number $St \sim 1$ computed over a characteristic timescale of the turbulence seen by the particles representing an estimate of the integral Lagrangian timescale T^L in mean-sheared flows [38]. The Reynolds number based on the energetic lengthscale is $Re_{Le} \sim 73$. The initial set of dimensionless parameters is: kinematics viscosity $\nu_f = 1.82e-4u_{ref}L_{ref}$, turbulent kinetic energy $q_f^2 = 3.37e-4u_{ref}^2$, dissipation $\epsilon_f = 3.78e-5u_{ref}^3/L_{ref}$, jet mean velocity $U_f = 0.15u_{ref}$, jet rms velocity $u'_f = 0.015u_{ref}$, particle diameter $d_p/\Delta_x = 0.01$. The particle Eulerian database is obtained from the Eulerian-Lagrangian DNS using the projection procedure

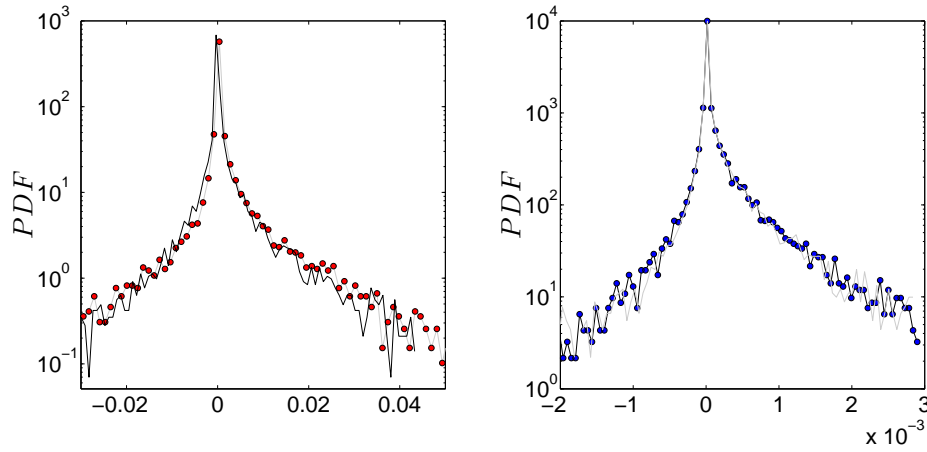


Figure 4: *PDF of actual (solid line) and modeled (symbols) productions of RUM temperature variance (left) and RUM kinetic energy (right), at the periphery of the jet, at $t = 6.2T_{f@p}$.*

detailed in Ref. [25]. The evaluation of the accuracy of the models is performed at tensor/vector level by assessed each component of the RUM-ST and the RUM-HF against the actual quantity provided by the particle Eulerian database. Moreover, an assessment at scalar level is also given. Figure 1 shows the mean profiles of the RUM-ST components as predicted by 2Φ EASM compared with the actual stresses. Modeled, by 2Φ EAHFM, and actual mean profiles of the RUM-HF components are depicted in Figure 2. For both the second-order moments, results at tensor/vector level are very satisfactory. At scalar level, the scalar quantities investigated are the productions of the RUM kinetic energy and the RUM temperature variance (first terms on the r.h.s. of Eqs. (8) and (9), respectively). Figure 3 shows the mean profiles of the two productions. In Figure 4, their PDFs evaluated at the periphery of the jet are depicted. They are computed by multiplying the local value of each modeled production by the actual-to-modeled magnitude ratio; in this way, only the shape of the PDFs is investigated [22]. Figure 3 shows that the two productions are successfully predicted, even if the RUM kinetic energy production is somewhat overestimated. Figure 4 shows that both the models are able to match the shape of the actual PDF and to reproduce reverse energy exchanges. Globally, results show that models compare very well with the Eulerian-Lagrangian DNS and properly reproduce all crucial trends of the computation. The proposed algebraic closures enable the ACBMM to correctly predict unsteady non-isothermal particle-laden turbulent flows, in dilute regime, for large Stokes number as well.

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