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	Pompidou		

Extended Source-Filter Model of Harmonic Instruments for Sound Synthesis, Transformation and Interpolation

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- based on 'playback' of prerecorded instrument sounds
- playback is triggered by some input device (MIDI Keyboard)

- Instrument characteristics are discretized
- synthesis sounds static
- no expressive control.





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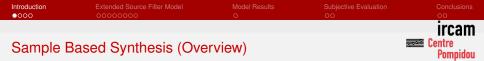
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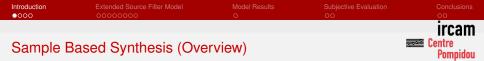
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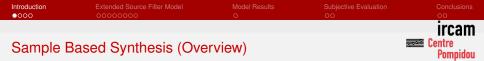




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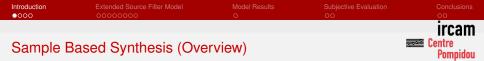




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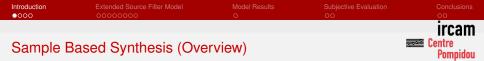




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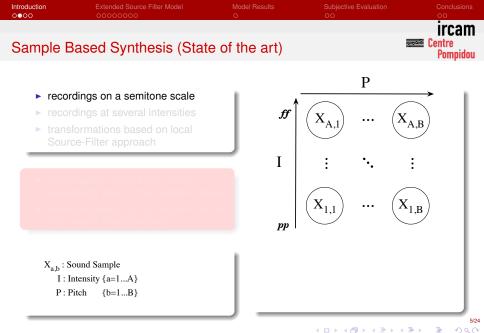


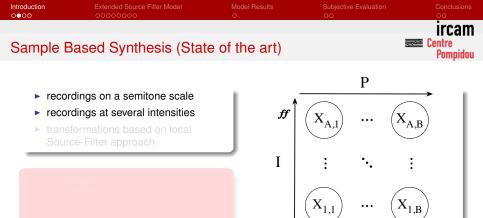


- recordings on a semitone scale
- recordings at several intensities
- transformations based on loca Source-Filter approach
- soundspace is does not contain knowledge about *intermediate* values
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instrument characteristics

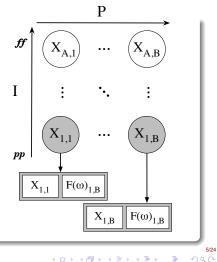
 $X_{a,b}$: Sound Sample I: Intensity {a=1...A} P: Pitch {b=1...B}



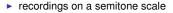
 transformations based on local Source-Filter approach

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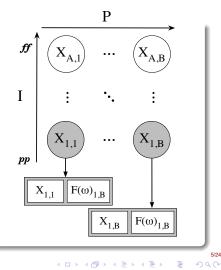




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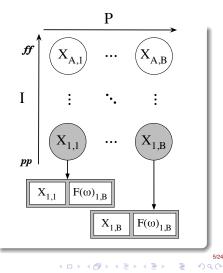
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- usage of State of the Art databases
- parametric model to describe the whole instrument sound characteristic along pitch / global intensity
- account for temporal evolution of a sound (ASR) denoted local Intensity
- separately treat harmonic and noise components
- model shall learn its parameters from the database

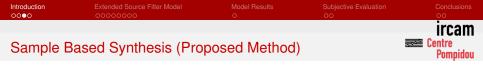
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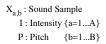
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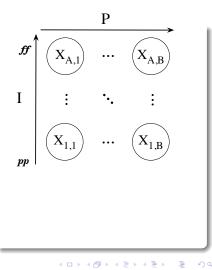


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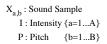


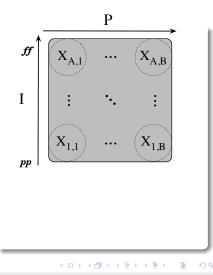
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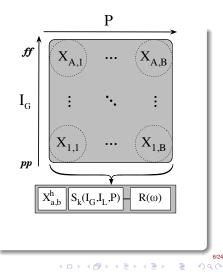


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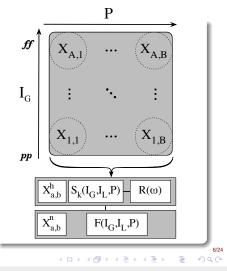


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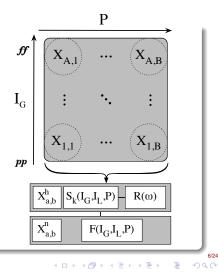
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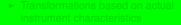


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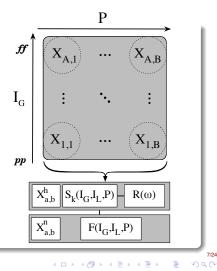






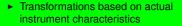
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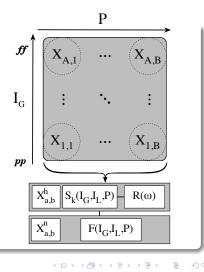
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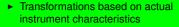
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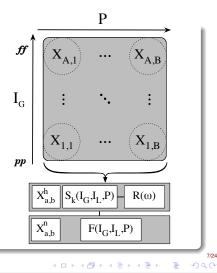
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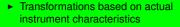
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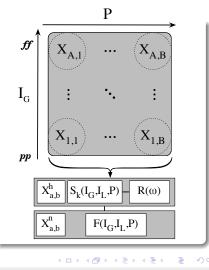
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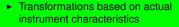
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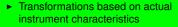
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Introduction

Extended Source Filter Model

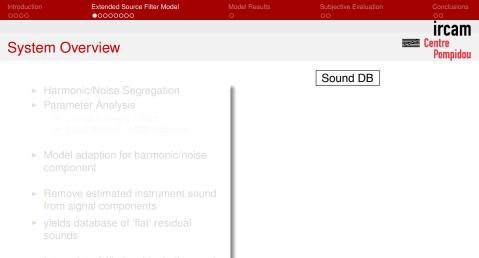
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- Interpolate 2 'flat' residuals (harmonic / noise separately)
- Apply any parameter change to estimate new envelopes to use on 'flat' residuals



- Harmonic/Noise Segregation
- Parameter Analysis
 - Global Intensity / Pitch
 - Local Intensity (ASR scheme)
- Model adaption for harmonic/noise component
- Remove estimated instrument sound from signal components
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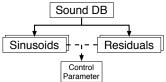


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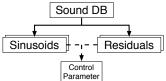


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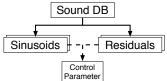


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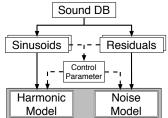
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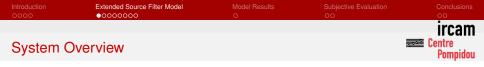


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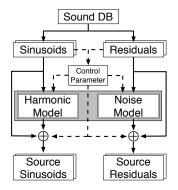


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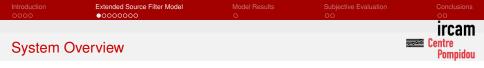


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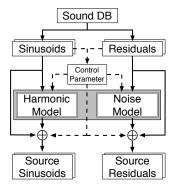


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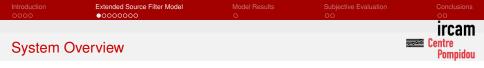


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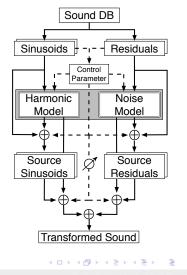


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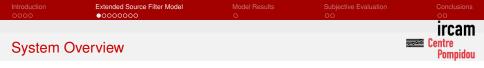
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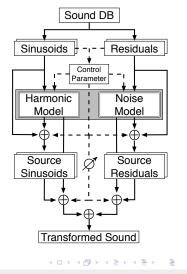
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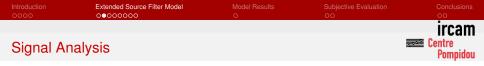
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Harmonics/Noise Segregation



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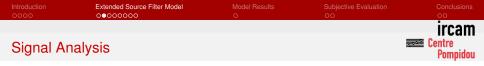
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Harmonics/Noise Segregation

 Partials are modeled as amplitude and frequency function per partial k over time n:

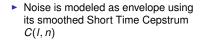
$$A(k,n) \mid f(k,n)$$

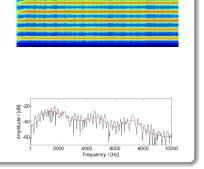


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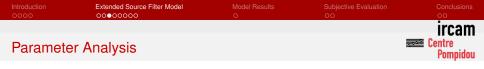
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Obtained from meta data provided by the Database

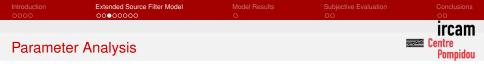
Local Intensity

- Local intensity reflects amplitude envelope over time: l_L(n).
- Threshold method to determine attack/release time frames n_A, n_B

Temporal Segmentation

Segmentation using an overlapping scheme to define n_s = {n_a, n_r}





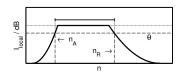
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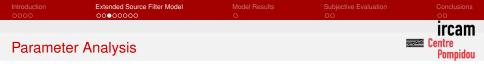
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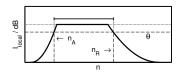
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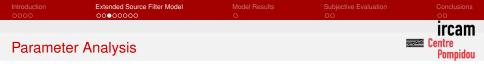
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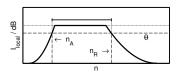
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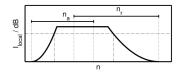
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- Threshold method to determine attack/release time frames n_A, n_R

Temporal Segmentation

Segmentation using an overlapping scheme to define n_s = {n_a, n_r}





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	Extended Source Filter Model		
Harmonic I	Vodel		ircam Eentre Pompidou

- function for each k depending on pitch m (MIDI) and both intensities I_G and I_L
- separate functions s for attack-sustain and sustain-release
- may refer to a vibrating string / air pipe

Features by frequency f

- invariant filter
- refers mainly to the instrument corpus

using log-domain values

Partial function

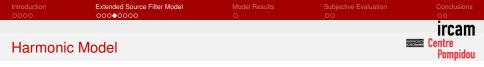
 $S^{k,s}(I_G, I_L, m)$

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12/24

Resonance filter





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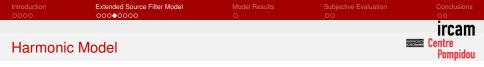
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Resonance filter



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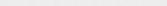
Henrik Hahn, Axel Böbel



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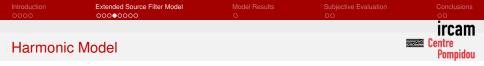
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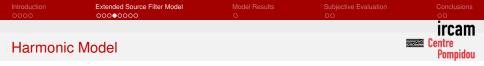
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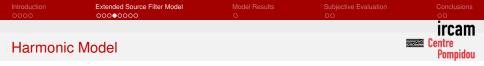
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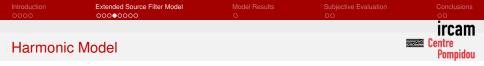
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Resonance filter *R*(*f*)





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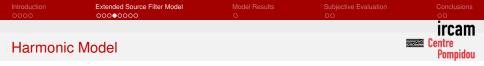
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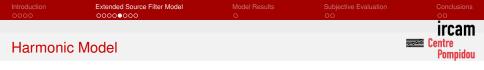
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Resonance filter *R*(*f*)



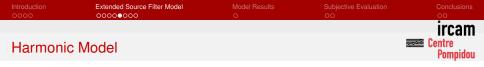
$\hat{A}^{k,s}(I_G,I_L,m,f(k,n)) = S^{k,s}(I_G,I_L,m) + R(f(k,n))$

Model of partial function using tensor-product B-splines:



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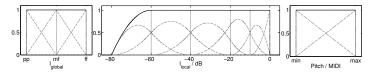
Henrik Hahn, Axel Röbel



$$\hat{A}^{k,s}(I_G, I_L, m, f(k, n)) = S^{k,s}(I_G, I_L, m) + R(f(k, n))$$

Model of partial function using tensor-product B-splines:

$$S^{k,s}(I_G, I_L, m) = \sum_{\rho,q,t}^{P,Q,T} B_{\rho}(I_G) B_q(I_L) B_t(m) \quad \cdot \quad \gamma_{\rho,q,t}^{k,s}$$



B-Spline functions for $B_p(I_G)$, $B_q(I_L)$, $B_t(m)$

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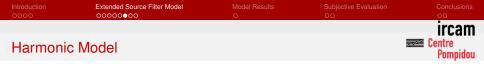
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model of resonance filter using one-dimensional B-splines



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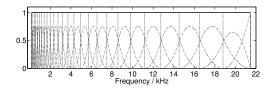
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$$\hat{A}^{k,s}(I_G, I_L, m, f(k, n)) = S^{k,s}(I_G, I_L, m) + R(f(k, n))$$

model of resonance filter using one-dimensional B-splines

$$R(f(k,n)) = \sum_{v}^{V} B_{v}(f(k,n)) \cdot \lambda_{v}$$

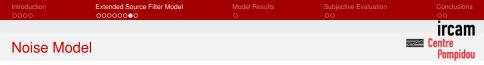




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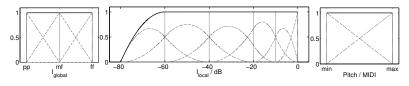
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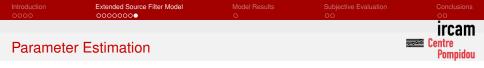
Cepstral coefficients are described using a single tensor-product B-spline model:

$$\hat{C}^{k,s}(I_G, I_L, m) = \sum_{p,q,t}^{P,Q,T} B_p(I_G) B_q(I_L) B_t(m) \quad \cdot \quad \delta_{p,q,t}^{k,s}$$



B-Spline functions for $B_p(I_G)$, $B_q(I_L)$, $B_t(m)$

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Iterative method using Conjugate Gradient

$$\mathcal{O}_{h} = \frac{1}{2} \sum_{s=1}^{2} \sum_{k,n_{s}}^{K,N_{s}} |A(k,n_{s}) - \hat{A}^{k,s}(I_{G},I_{L}(n_{s}),m,f(k,n))|^{2}$$

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$$\mathcal{O}_n = \frac{1}{2} \sum_{s=1}^{2} \sum_{l,n_s}^{L,N_s} |C(l,n_s) - \hat{C}^{k,s}(l_G,l_L(n_s),m)|^2$$

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	Model Results	
		ircam Ecentre Pompidou

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Model Results

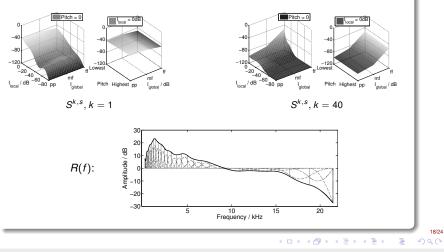
Subjective Evaluation

Conclusions

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	Subjective Evaluation	
		ircam Ecentre Pompidou

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Extended Source Filter Model

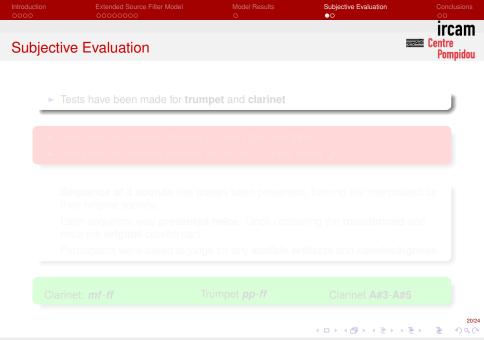
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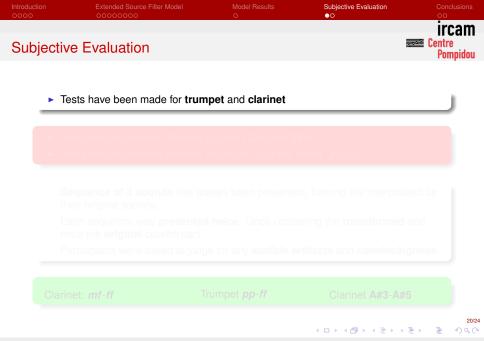
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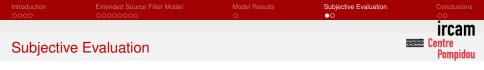
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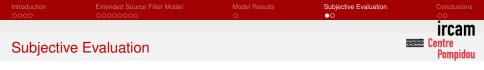
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- Tests have been made for trumpet and clarinet
- Interpolation between different pitches (12st and 24st)
- Interpolation between different intensities (pp-mf, mf-ff, pp-ff)

Each sequence was presented twice. Once containing the transformed and once the original counterpart

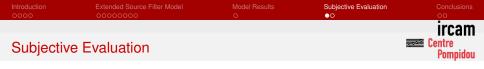




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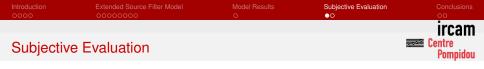




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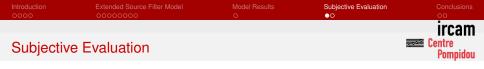




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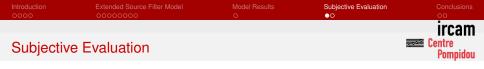




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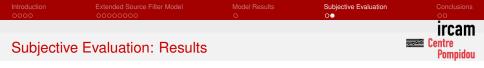




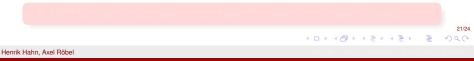
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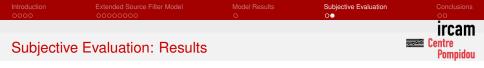
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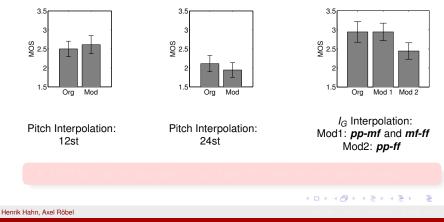


- Measured the Mean Opinion Score for both instruments at once
- Org represents original samples, Mod1 and Mod2 represent synthesized ones.

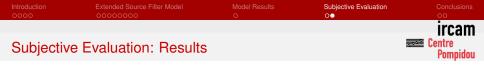




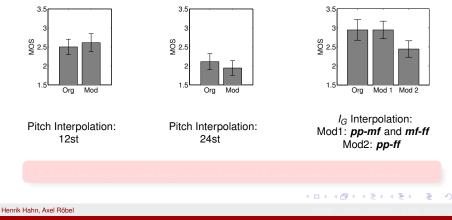
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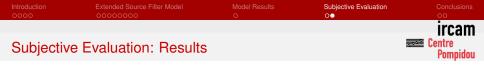
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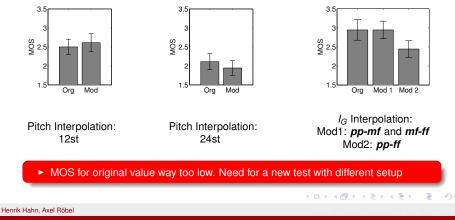
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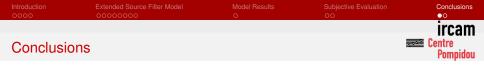
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- A parametric model for harmonic instruments
- A model which separately represents harmonic and noise components utilizing tensor-product B-splines
- An harmonic model separately representing features by partial index and frequency
- An objective function to estimate model parameters iteratively
- A subjective evaluation showing promising results

More instruments need to be adressed (Strings, Piano, Guitar, ...

A subjective evaluation needs to be repeated with a different setup.

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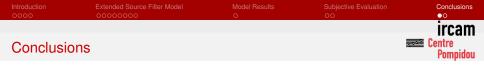
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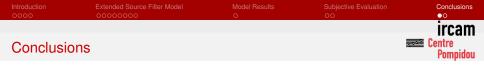
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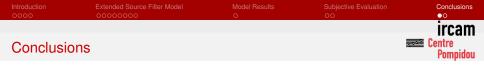
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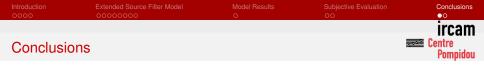
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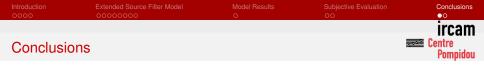
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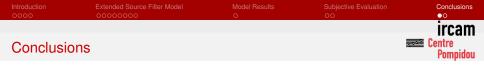
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Thanks for listening



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