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Global weak solutions for the Landau-Lifschitz Equation with Magnetostriction

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Abstract. In this paper we prove the global in time existence for weak solutions to a Landau-Lifschitz system with magnetostriction arising from ferromagnetism theory. We describe also the ω -limit set of a solution.

Keywords. Landau-Lifschitz equation, magnetostriction, weak solutions, ferromagnetism.

AMS classification. 35K55, 35Q55, 35Q74.

1 Modelization

The applications of ferromagnetic materials are more and more numerous: hard-disks, recording heads, ferromagnetic paints, etc. A general description of these materials is given by Landau-Lifschitz in [21] (see also [9], [18] and [24]). The ferromagnetic materials are spontaneously magnetized. Their magnetization is described by a vector field $m : \mathbb{R}^+ \times \Omega \longrightarrow \mathbb{R}^3$ call the magnetic moment, where we denote by Ω the ferromagnetic domain. We assume that the material satisfies the saturation constraint:

$$|m| = 1. \quad (1)$$

The following Landau-Lifschitz equation describes the behaviour of m :

$$\frac{\partial m}{\partial t} = -m \wedge H_e - m \wedge (m \wedge H_e). \quad (2)$$

In simplified models, the so called effective field H_e is given by

$$H_e = \Delta m + h_d(m),$$

where the demagnetizing field $h_d(m)$ is deduced from m by the static Maxwell equations together with the law of Faraday:

$$\begin{cases} \operatorname{div} (h_d(m) + \overline{m}) = 0 \text{ in } \mathbb{R}^3, \\ \operatorname{curl} h_d(m) = 0 \text{ in } \mathbb{R}^3. \end{cases}$$

In the previous system, \overline{m} is the extension of m by zero outside Ω .

Existence results for weak solutions of (2) can be found in [23] or [12]. Existence of strong solutions is investigate in [13], [14] or [15] and [11] for a more complete model.

In this paper, we investigate the coupling of magnetic and mechanical effects by studying the complete Landau-Lifschitz equation with magnetostriction. In the following two subsections, we give a complete description of the model. Our main results are stated in subsection 1.3. Roughly speaking, we establish a global existence results for the weak solutions of the Landau-Lifschitz equation with magnetostriction, are we describe the ω -limit set of a trajectory.

1.1 Landau-Lifschitz equation with magnetostriction

In the physical litterature (see [21]) or in numerical studies (see [5]), the model for a ferromagnetic body with magnetostriction is the following. The magnetic moment satisfies the Landau-Lifschitz equation:

$$\begin{cases} \frac{\partial m}{\partial t} = -m \wedge H_{eff} - m \wedge (m \wedge H_{eff}) \text{ on } \mathbb{R}^+ \times \Omega, \\ \text{with } H_{eff} = \Delta m + h_d(m) + \Psi(m) + (\lambda^{\mathbf{m}} : \sigma)m, \\ m(t=0) = m_0 \text{ in } \Omega, \\ \partial_{\mathbf{n}} m = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega, \end{cases} \quad (3)$$

where

- the initial data m_0 is supposed to be given in $H^1(\Omega; S^2)$,
- $h_d(m)$ is the demagnetizing field,
- Ψ is an anisotropic term. This term is the differential of a non negative quadratic form $\Phi : \mathbb{R}^3 \rightarrow \mathbb{R}$. Consequently it is a linear term,
- the magnetostriction field $h_{\mathbf{m}}$ links the magnetic moment m with the stress tensor σ . It's given by

$$h_{\mathbf{m}} = (\lambda^{\mathbf{m}} : \sigma)m,$$

where $\lambda^{\mathbf{m}}$ is a symmetric non negative 4-tensor and σ is the stress tensor. It is a 2-tensor (see below)

Remark 1 *The usual notations and definitions about tensor calculus are recalled in Subsection 1.2.1.*

In order to take into account the magnetostriction, the Landau-Lifschitz equation is coupled with the following wave equation:

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - \operatorname{div} \sigma = 0 \text{ on } \mathbb{R}^+ \times \Omega, \\ u(t=0) = u_0 \text{ in } \Omega, \\ \frac{\partial u}{\partial t}(t=0) = u_1 \text{ in } \Omega, \\ u(t, x) = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega, \end{cases} \quad (4)$$

where

- the stress tensor σ satisfies $\sigma = \lambda^{\mathbf{e}} : \varepsilon^{\mathbf{e}}$, where $\lambda^{\mathbf{e}}$ is a symmetric positive 4-tensor,
- the tensor $\varepsilon^{\mathbf{e}}$ is obtained from the deformation tensor $\varepsilon(u)$ and the magnetic tensor $\varepsilon^{\mathbf{m}}$ by

$$\varepsilon(u) = \varepsilon^{\mathbf{e}} + \varepsilon^{\mathbf{m}},$$

- the deformation tensor $\varepsilon(u)$ is defined by $\varepsilon(u)_{ij} = \frac{1}{2} \left(\frac{\partial u^i}{\partial x_j} + \frac{\partial u^j}{\partial x_i} \right)$
- $\varepsilon^{\mathbf{m}} = \lambda^{\mathbf{m}} : m \otimes m$, that is $\varepsilon_{ij}^{\mathbf{m}} = \sum_{ijkl} \lambda_{ijkl}^{\mathbf{m}} m^k m^l$,

The initial data u_0 is supposed to be in $H_0^1(\Omega; \mathbb{R}^3)$ and u_1 is supposed to be in $L^2(\Omega; \mathbb{R}^3)$.

We consider the Landau-Lifschitz-Gilbert form for the Landau-Lifschitz part of the system. In addition, we eliminate the variables σ , ε^m and ε^e so we deal with the following system coupling the Landau Lifschitz equation:

$$\begin{cases} \frac{\partial m}{\partial t} - m \wedge \frac{\partial m}{\partial t} = -2m \wedge H_{eff} \text{ on } \mathbb{R}^+ \times \Omega, \\ H_{eff} = \Delta m + h_d(m) + \Psi(m) + (\lambda^m : (\lambda^e : \varepsilon(u)))m - (\lambda^m : (\lambda^e : (\lambda^m : m \otimes m)))m, \end{cases} \quad (5)$$

together with the wave equation:

$$\frac{\partial^2 u}{\partial t^2} - \operatorname{div}(\lambda^e : \varepsilon(u)) = -\operatorname{div}(\lambda^e : (\lambda^m : m \otimes m)) \text{ on } \mathbb{R}^+ \times \Omega, \quad (6)$$

with the initial and boundary conditions:

$$\begin{cases} m(t=0) = m_0 \text{ in } \Omega, \\ u(t=0) = u_0 \text{ in } \Omega, \\ \frac{\partial u}{\partial t}(t=0) = u_1 \text{ in } \Omega, \\ \partial_{\mathbf{n}} m = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega, \\ u(t, x) = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega. \end{cases} \quad (7)$$

Remark 2 For regular enough solutions, the Landau-Lifschitz equation (3) is equivalent to the Landau-Lifschitz-Gilbert equation (5). This last formulation is more convenient to write a weak formulation and to establish a global existence theorem.

1.2 Structural properties

1.2.1 Tensor calculus

Let us recall notations and definitions about tensors:

- let λ be a 4-tensor $\lambda = (\lambda_{ijkl})$. We say that λ is symmetric if

$$\lambda_{ijkl} = \lambda_{jikl} = \lambda_{ijlk} = \lambda_{klij}.$$

- We say that a symmetric 4-tensor is positive if there exists a constant λ^* such that:

$$\forall \xi^{ij}, \sum_{ijkl} \lambda_{ijkl} \xi^{ij} \xi^{kl} \geq \lambda^* \sum_{ij} (\xi^{ij})^2$$

- If λ is a 4-tensor and ν is a two tensor, we denote by $\lambda : \nu$ the 2-tensor given by

$$(\lambda : \nu)_{ij} = \sum_{kl} \lambda_{ijkl} \nu_{kl}.$$

- If μ and ν are two 2-tensors, then $\mu : \nu$ is a scalar given by

$$\mu : \nu = \sum_{ij} \mu_{ij} \nu_{ij}.$$

- for $(\xi, \zeta) \in \mathbb{R}^3 \times \mathbb{R}^3$, then $\xi \otimes \zeta$ is the 2-tensor which entries are given by

$$(\xi \otimes \zeta)_{ij} = \xi^i \zeta^j.$$

We state now useful lemmas concerning tensors.

Lemma 1 *Let λ be a symmetric 4-tensor, let A be a symmetric two tensor, and let ξ_1 and ξ_2 in \mathbb{R}^3 . We have*

$$(\lambda : A)\xi_1 \cdot \xi_2 = A : (\lambda : \xi_1 \otimes \xi_2).$$

Proof: we prove this lemma by straightforward calculations.

We define \mathcal{Q} by

$$\mathcal{Q}(m) = (\lambda^e : (\lambda^m : m \otimes m)) : (\lambda^m : m \otimes m).$$

Lemma 2 *The map $\mathcal{Q} : \mathbb{R}^3 \rightarrow \mathbb{R}$ is \mathcal{C}^∞ and*

$$\nabla \mathcal{Q}(m) = 4(\lambda^m : (\lambda^e : (\lambda^m : m \otimes m)))m.$$

Proof: this lemma is a simple consequence of Lemma 1

Lemma 3 *Let λ be a symmetric positive 4-tensor, let A and B be two 2-tensors. Then*

$$(\lambda : A) : B \leq ((\lambda : A) : A)^{\frac{1}{2}} ((\lambda : B) : B)^{\frac{1}{2}}.$$

Proof: we consider $\chi : \{1, 2, 3\}^2 \rightarrow \{1, 2, \dots, 9\}$ a bijective map. Let $\Lambda \in \mathcal{M}_9(\mathbb{R})$ the matrix of entries $\Lambda_{\chi(i,j)\chi(k,l)} = \lambda_{ijkl}$. In the same way, we consider $\bar{A} \in \mathbb{R}^9$ such that $\bar{A}_{\chi(i,j)} = A_{ij}$, and $\bar{B} \in \mathbb{R}^9$ such that $\bar{B}_{\chi(i,j)} = B_{ij}$.

We have $(\lambda : A) : B = \Lambda \bar{A} \cdot \bar{B}$.

The matrix Λ is symmetric positive, by property of λ and we introduce $\Gamma \in \mathcal{M}_9(\mathbb{R})$ the square root of Λ . We have:

$$(\lambda : A) : B = \Gamma \bar{A} \cdot \Gamma \bar{B} \leq \|\Gamma \bar{A}\| \|\Gamma \bar{B}\|$$

by Cauchy Schwartz inequality. Now

$$\|\Gamma \bar{A}\|^2 = \Gamma \bar{A} \cdot \Gamma \bar{A} = \Lambda \bar{A} \cdot \bar{A} = (\lambda : A) : A,$$

and in the same way

$$\|\Gamma \bar{B}\|^2 = (\lambda : B) : B,$$

and the proof of Lemma 3 is complete.

1.2.2 Energy Formula

The calculations in this section are formal. They are valid for regular enough solutions.

First, taking the scalar product of (5) with m , we obtain that $\frac{\partial m}{\partial t} \cdot m = 0$, that is $\frac{\partial}{\partial t}(|m|^2) = 0$. Since the initial data satisfies $|m_0| = 1$, then for all time, m satisfies the saturation constraint $|m| = 1$.

The proof of the existence of solutions for (5)-(6)-(7) is built on energy estimates which are the consequence of algebraic properties. Formally, for regular enough functions, the following calculations hold:

On one hand, we take the inner product of (5) by $\frac{\partial m}{\partial t} - 2H_{eff}$, so that we obtain that

$$\int_{\Omega} \frac{\partial m}{\partial t} \cdot \left(\frac{\partial m}{\partial t} - 2H_{eff} \right) = 0.$$

From the first three terms of the effective field, we have:

- by integrations by parts:

$$\int_{\Omega} \Delta m \cdot \frac{\partial m}{\partial t} = -\frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla m|^2,$$

- since $-h_d$ is an orthogonal projector for the L^2 inner product,

$$\int_{\Omega} h_d(m) \cdot \frac{\partial m}{\partial t} = -\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^3} |h_d(m)|^2,$$

- since $\Psi = -\nabla\Phi$,

$$\int_{\Omega} \Psi(m) \cdot \frac{\partial m}{\partial t} = -\frac{1}{2} \frac{d}{dt} \int_{\Omega} \Phi(m).$$

For the magnetostriction terms, we first remark that by symmetry of the 4-tensor $\lambda^{\mathbf{m}}$ and by Lemma 2, we have

$$2 \int_{\Omega} (\lambda^{\mathbf{m}} : (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m))) m \cdot \frac{\partial m}{\partial t} = \frac{1}{2} \frac{d}{dt} \int_{\Omega} \mathcal{Q}(m)$$

where $\mathcal{Q}(m)$ is a non negative term of fourth order:

$$\mathcal{Q}(m) = (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)) : (\lambda^{\mathbf{m}} : m \otimes m).$$

In addition, by Lemma 1, we have

$$\begin{aligned} 2 \int_{\Omega} (\lambda^{\mathbf{m}} : (\lambda^{\mathbf{e}} : \varepsilon(u))) m \cdot \frac{\partial m}{\partial t} &= 2 \int_{\Omega} \varepsilon(u) : (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes \frac{\partial m}{\partial t})) \\ &= \int_{\Omega} \varepsilon(u) : \frac{\partial}{\partial t} (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)). \end{aligned}$$

So, from (5) we obtain that

$$\begin{aligned} &\int_{\Omega} \left| \frac{\partial m}{\partial t} \right|^2 + \frac{d}{dt} \left[\int_{\Omega} (|\nabla m|^2 + \Phi(m)) + \int_{\mathbb{R}^3} |h_d(m)|^2 + \frac{1}{2} \int_{\Omega} \mathcal{Q}(m) \right] \\ &- \int_{\Omega} \varepsilon(u) : \frac{\partial}{\partial t} (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)) = 0. \end{aligned} \tag{8}$$

On the other hand, we take the inner product of the second equation in (6) by $\frac{\partial u}{\partial t}$.

Using that $\lambda^{\mathbf{e}}$ is symmetric, and that $u = 0$ on $\partial\Omega$, we obtain after integration by parts that:

$$- \int_{\Omega} \operatorname{div} (\lambda^{\mathbf{e}} : \varepsilon(u)) \cdot \frac{\partial u}{\partial t} = \frac{1}{2} \frac{d}{dt} \int_{\Omega} (\lambda^{\mathbf{e}} : \varepsilon(u)) : \varepsilon(u).$$

Furthermore, by integration by parts,

$$\int_{\Omega} -\operatorname{div} (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)) \cdot \frac{\partial u}{\partial t} = \int_{\Omega} (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)) : \frac{\partial \varepsilon(u)}{\partial t}$$

by symmetry of $\lambda^{\mathbf{e}}$.

Hence we obtain from (6) that

$$\frac{1}{2} \frac{d}{dt} \left[\int_{\Omega} \left| \frac{\partial u}{\partial t} \right|^2 + \int_{\Omega} (\lambda^{\mathbf{e}} : \varepsilon(u)) : \varepsilon(u) \right] = \int_{\Omega} (\lambda^{\mathbf{e}} : (\lambda^{\mathbf{m}} : m \otimes m)) : \frac{\partial \varepsilon(u)}{\partial t}. \tag{9}$$

Adding up (8) and (9), we obtain the energy formula:

$$\frac{d}{dt} \mathcal{E}(t) + \int_{\Omega} \left| \frac{\partial m}{\partial t} \right|^2 = 0, \tag{10}$$

with

$$\begin{aligned}
\mathcal{E}(t) = & \int_{\Omega} [|\nabla m|^2 + |h_d(m)|^2 + \Phi(m)] \\
& + \frac{1}{2} \int_{\Omega} [(\lambda^e : (\lambda^m : m \otimes m)) : (\lambda^m : m \otimes m) - 2\varepsilon(u) : (\lambda^e : (\lambda^m : m \otimes m))] \\
& + \frac{1}{2} \int_{\Omega} [(\lambda^e : \varepsilon(u)) : \varepsilon(u) + \left| \frac{\partial u}{\partial t} \right|^2].
\end{aligned} \tag{11}$$

Remark 3 Because of the positiveness of λ^e , in the energy, $\mathcal{Q}(m)$ and $(\lambda^e : \varepsilon(u)) : \varepsilon(u)$ are positive. The bad sign term $-2\varepsilon(u) : (\lambda^e : (\lambda^m : m \otimes m))$ can be balanced by both good sign terms, since applying Lemma 3 with $\lambda = \lambda^e$, $A = \varepsilon$ and $B = \lambda^m : m \otimes m$, we have:

$$\varepsilon : (\lambda^e : (\lambda^m : m \otimes m)) \leq \mathcal{Q}(m)^{\frac{1}{2}} \cdot ((\lambda^e : \varepsilon) : \varepsilon)^{\frac{1}{2}}.$$

On the contrary, the part of the energy coming from the magnetostriction terms is non coercive since it does not control the term $\|\nabla u\|_{L^2(\Omega)}^2$ if we simply apply Young inequality to balance the bad sign term.

1.3 Statement of the results

Definition 1 We say that (m, u) is a weak solution for (5)-(6)-(7) if

1. $m \in L^\infty(\mathbb{R}^+; H^1(\Omega; \mathbb{R}^3))$ satisfies the saturation constraint $|m(t, x)| = 1$ for almost every $(t, x) \in \mathbb{R}^+ \times \Omega$,
2. $\frac{\partial m}{\partial t} \in L^2(\mathbb{R}^+; L^2(\Omega; \mathbb{R}^3))$,
3. $m(0, \cdot) = m_0$ in the trace sense in $H^{\frac{1}{2}}(\Omega)$,
4. $u \in L^\infty(\mathbb{R}^+; H_0^1(\Omega; \mathbb{R}^3))$ and $\frac{\partial u}{\partial t} \in L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^3; \mathbb{R}^3))$,
5. $u(0, \cdot) = u_0$ in the trace sense in $H^{\frac{1}{2}}(\Omega)$,
6. for all $\chi \in C_c^\infty(\mathbb{R}^+; H^1(\Omega; \mathbb{R}^3))$

$$\begin{aligned}
\int_{\mathbb{R}^+ \times \Omega} \left(\frac{\partial m}{\partial t} - m \wedge \frac{\partial m}{\partial t} \right) \chi(t, x) dt dx = & 2 \int_{\mathbb{R}^+ \times \Omega} \sum_{i=1}^3 m \wedge \frac{\partial m}{\partial x_i} \cdot \frac{\partial \chi}{\partial x_i} - 2 \int_{\Omega} (h_d(m) + \Psi(m)) \cdot \chi \\
& - 2 \int_{\Omega} ((\lambda^m : (\lambda^e : \varepsilon(u)))m - (\lambda^m : (\lambda^e : (\lambda^m : m \otimes m)))m) \cdot \chi,
\end{aligned}$$

7. for all $\chi \in C_c^\infty(\mathbb{R}^+; H_0^1(\Omega; \mathbb{R}^3))$

$$\int_{\mathbb{R}^+ \times \Omega} \frac{\partial u}{\partial t} \cdot \frac{\partial \chi}{\partial t} - \int_{\mathbb{R}^+ \times \Omega} (\lambda^e : \varepsilon(u)) : \varepsilon(\chi) + \int_{\Omega} u_1 \chi(0, x) dx = - \int_{\mathbb{R}^+ \times \Omega} (\lambda^e : (\lambda^m : m \otimes m)) : \varepsilon(\chi),$$

8. for all $t \geq 0$, we have the following energy inequality:

$$\mathcal{E}(t) + \int_0^t \int_{\Omega} \left| \frac{\partial m}{\partial t} \right|^2 \leq \mathcal{E}(0)$$

where \mathcal{E} is defined by (11).

Remark 4 Since $m \in L^\infty(0, T; H^1(\Omega))$ and $\frac{\partial m}{\partial t} \in L^2(0, T; L^2(\Omega))$, then $m \in \mathcal{C}^0(0, T; H^{\frac{1}{2}}(\Omega))$ (see [22]) and $m \in \mathcal{C}^0(0, T; H_w^1(\Omega))$ (see [8] Lemma II.5.9). So the trace of m at $t = 0$ exists in $H^{\frac{1}{2}}(\Omega)$ for example. In the same way, $u \in \mathcal{C}^0(0, T; H^{\frac{1}{2}}(\Omega))$. Moreover, $u \in L^\infty(0, T; H_0^1(\Omega))$ so $\operatorname{div}(\lambda^e : \varepsilon(u))$ is in $L^\infty(0, T; H^{-1})$, and by the wave equation, $\frac{\partial^2 u}{\partial t^2} \in L^\infty(0, T; H^{-1}(\Omega))$. So $\frac{\partial u}{\partial t} \in \mathcal{C}^0(0, T; H^{-\frac{1}{2}}(\Omega)) \cap \mathcal{C}^0(0, T; L_w^2(\Omega))$. Hence the trace of $\frac{\partial u}{\partial t}$ at $t = 0$ as a sense in $H^{-\frac{1}{2}}(\Omega)$.

Our first theorem is an existence result for global in time weak solutions of the system (5)-(6)-(7).

Theorem 1 Let $m_0 \in H^1(\Omega; S^2)$, let $u_0 \in H_0^1(\Omega; \mathbb{R}^3)$ and $u_1 \in L^2(\Omega; \mathbb{R}^3)$. Then there exists a weak solution for (5)-(6)-(7).

Remark 5 The formal calculations of the previous section are not allowed for weak solutions. Therefore, the saturation constraint and the energy inequality are obtained by construction. We remark that we only obtain an inequality energy (and not an equality as in the formal calculations). This is usual for the weak solutions of the Landau-Lifschitz equations (see [2] and [12]).

Our second result describes the ω -limit set of a fixed solution fo (5)-(6)-(7).

Definition 2 Let m be a weak solution of (5)-(6)-(7) given by Theorem 1. Let $m_\infty \in H^1(\Omega)$. We say that m_∞ is in the ω -limit set of m if there exists a sequence of times $(t_n)_{n \in \mathbb{N}}$ such that t_n tends to $+\infty$ and $m(t_n)$ tends weakly to m_∞ in $H^1(\Omega)$ when n tends to $+\infty$.

Theorem 2 Let m be a weak solution of (5)-(6)-(7). Its ω -limit set is non empty, and if m_∞ is in the ω -limit set of m , then m_∞ satisfies the saturation constraint $|m_\infty| = 1$ and satisfies, for all test function $\xi \in H^1(\Omega; \mathbb{R}^3)$,

$$\begin{aligned} - \int_{\Omega} \sum_{i=1}^3 m_\infty \wedge \frac{\partial m_\infty}{\partial x_i} \cdot \frac{\partial \xi}{\partial x_i} + \int_{\Omega} \left(h_d(m_\infty) + \psi(m_\infty) + (\lambda^m : (\lambda^e : \varepsilon(u_\infty))) m_\infty \right) \cdot \xi \\ - \int_{\Omega} ((\lambda^m : (\lambda^e : (\lambda^m : m_\infty \otimes m_\infty))) m_\infty) \cdot \xi = 0. \end{aligned}$$

where u_∞ is deduced from m_∞ by:

$$\begin{cases} u_\infty \in H_0^1(\Omega), \\ \operatorname{div}(\lambda^e : \varepsilon(u_\infty)) = \operatorname{div}(\lambda^e : (\lambda^m : m_\infty \otimes m_\infty)) \text{ in } H^{-1}(\Omega). \end{cases}$$

The paper is organised as follows. In the following subsection, we recall the Aubin-Simon compactness lemma. Theorem 1 is proved in Sections 2 and 3. Theorem 2 is established in Section 4.

Our proof of Theorem 1 follows the method due to Alouges and Soyeur in [2] and generalized in [12] for the system coupling the Landau-Lifschitz with the Maxwell equations. First we study a penalized system in which the saturation constraint is relaxed and we take the limit when the penalization constant tends to zero. The new difficulty here is that the energy coming from the magnetostriction is non coercive (see Remark 3). The lack of coercivity is balanced by coupling the magnetostriction part with the penalization term (see Section 2.3).

Concerning the description of the ω -limit set, the key tool is taking averages for m and u on time intervals $[t_n - a, t_n + a]$, and performing the limit when n tends to $+\infty$ in a first step and when a tends to $+\infty$ in a second step. This method is used in [12] for a simpler model.

Remark 6 Ferromagnetism is a wide domain in Physics. In Mathematics, recent developments have been obtained from the numerical point of view (see [6], [7], [19], [20] for example). Asymptotic studies are done in [1], [4], [10], [17] for example. In particular, the description of wall structures is a very important and challenging question (see [10] and [16] and the references therein). The interested reader can also read [3] for a related model of ferroelectric materials.

1.4 Compactness lemma

By applying the Aubin-Simon lemma (see [8] Theorem II.5.16), we obtain:

Lemma 4 *We define W by*

$$W = \left\{ v \in L^\infty(0, T; H^1(\Omega)), \frac{\partial v}{\partial t} \in L^2(0, T; L^2(\Omega)) \right\}.$$

Then the injection of W in $L^\infty(0, T; L^4(\Omega))$ is compact.

2 Penalized system

We consider for $\eta > 0$ the following penalized system:

$$\left\{ \begin{array}{l} \frac{\partial m^\eta}{\partial t} + m^\eta \wedge \frac{\partial m^\eta}{\partial t} - 2H_{eff}^\eta + \frac{1}{\eta}(|m^\eta|^2 - 1)m^\eta = 0 \text{ on } \mathbb{R}^+ \times \Omega, \\ H_{eff}^\eta = \Delta m^\eta + h_d(m^\eta) + \Psi(m^\eta) + (\lambda^m : (\lambda^e : \varepsilon(u^\eta)))m^\eta - (\lambda^m : (\lambda^e : (\lambda^m : m^\eta \otimes m^\eta)))m^\eta \\ \frac{\partial^2 u^\eta}{\partial t^2} - \operatorname{div}(\lambda^e : \varepsilon(u^\eta)) = -\operatorname{div}(\lambda^e : (\lambda^m : m^\eta \otimes m^\eta)) \text{ on } \mathbb{R}^+ \times \Omega, \\ m^\eta(t=0) = m_0 \\ u^\eta(t=0) = u_0 \\ \frac{\partial u^\eta}{\partial t}(t=0) = u_1 \\ \partial_{\mathbf{n}} m^\eta = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega \\ u^\eta(t, x) = 0 \text{ on } \mathbb{R}^+ \times \partial\Omega \end{array} \right. \quad (12)$$

Claim : there exists a weak global in time solution for (12).

In this section, $\eta > 0$ is fixed.

2.1 First step: Galerkin approximation

For m , we use an Galerkin basis (e_1, e_2, \dots) of eigenvectors of $-\Delta$ with homogeneous Neumann conditions at the boundary.

$$\left\{ \begin{array}{l} -\Delta e_i = \alpha_i e_i \text{ in } \Omega, \\ \partial_{\mathbf{n}} e_i = 0 \text{ on } \partial\Omega. \end{array} \right.$$

We denote by $V_N = \operatorname{span}(e_1, \dots, e_N)$ and by P_N the orthogonal projection map onto V_N .

For u , we use the Galerkin basis (f_1, f_2, \dots) of eigenvectors of $-\operatorname{div}(\lambda^e : \varepsilon)$ with homogeneous Dirichlet conditions at the boundary:

$$\left\{ \begin{array}{l} -\operatorname{div}(\lambda^e : \varepsilon(f_j)) = \beta_j f_j \text{ in } \Omega, \\ f_j = 0 \text{ on } \partial\Omega. \end{array} \right.$$

We denote by $W_N = \operatorname{span}(f_1, \dots, f_N)$ and by Π_N the orthogonal projection map onto W_N .

We consider for a fixed N the solution $(m_N^\eta, u_N^\eta) : \mathbb{R}_t^+ \rightarrow V_N \times W_N$ of the o.d.e. approximation:

$$\left\{ \begin{array}{l}
\frac{\partial m_N^\eta}{\partial t} + P_N(m_N^\eta \wedge \frac{\partial m_N^\eta}{\partial t}) - 2P_N(H_{eff}^N) + \frac{1}{\eta}P_N(|m_N^\eta|^2 - 1)m_N^\eta = 0 \text{ on } \mathbb{R}^+, \\
H_{eff}^N = \Delta m_N^\eta + h_d(m_N^\eta) + \Psi(m_N^\eta) + (\lambda^m : (\lambda^e : \varepsilon(u_N^\eta)))m_N^\eta - (\lambda^m : (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)))m_N^\eta, \\
\frac{\partial^2 u_N^\eta}{\partial t^2} - \operatorname{div}(\lambda^e : \varepsilon(u_N^\eta)) = -\Pi_N(\operatorname{div}(\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta))) \text{ on } \mathbb{R}^+, \\
m_N^\eta(t=0) = P_N(m_0), \\
u_N^\eta(t=0) = \Pi_N(u_0), \\
\frac{\partial u_N^\eta}{\partial t}(t=0) = \Pi_N(u_1),
\end{array} \right. \quad (13)$$

In order to apply the Cauchy-Lipschitz theorem for this system, we remark that the operator $G^N(m_N)$ defined for $m_N \in V_N$ by

$$G^N(m_N) : \begin{array}{ccc} V_N & \longrightarrow & V_N \\ w & \mapsto & w + P_N(m_N \wedge w) \end{array}$$

is invertible. Indeed, for a fixed $m_N \in V_N$, the operator $G^N(m_N)$ is linear on the finite dimensional space V_N . Its kernel is reduced to zero: if $G^N(m_N)(w) = 0$, then $w = 0$. Indeed, taking the inner product in $L^2(\Omega)$ with $w \in V_N$, we obtain

$$\begin{aligned}
0 &= \int_{\Omega} G^N(m_N)(w) \cdot w \\
&= \int_{\Omega} |w|^2 + \int_{\Omega} P_N(m_N \wedge w) \cdot w \\
&= \int_{\Omega} |w|^2 + \int_{\Omega} (m_N \wedge w) \cdot w \\
&\quad \text{since } P_N \text{ is selfadjoint and since } w \in V_N \\
&= \int_{\Omega} |w|^2
\end{aligned}$$

So, inverting this operator, the first equation can be written as

$$\frac{\partial m_N^\eta}{\partial t} = F(m_N^\eta, u_N^\eta),$$

which is an ordinary differential equation. Then by the Cauchy-Lipschitz theorem, there exists a unique solution for (13) which maximal existence time is denoted by T_N .

2.2 Energy estimate on the Galerkin approximation

On one hand, we take the inner product of the second equation in (13) by $\frac{\partial u_N^\eta}{\partial t}$.

Using that λ^e is symmetric, and that $u = 0$ on $\partial\Omega$, we have:

$$-\int_{\Omega} \operatorname{div}(\lambda^e : \varepsilon(u_N^\eta)) \cdot \frac{\partial u_N^\eta}{\partial t} = \frac{1}{2} \frac{d}{dt} \int_{\Omega} (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta).$$

Furthermore, as $\frac{\partial u_N^\eta}{\partial t}$ belongs to W_N , one obtains

$$\begin{aligned} \int_{\Omega} -\Pi_N \left(\operatorname{div} (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) \right) \cdot \frac{\partial u_N^\eta}{\partial t} &= \int_{\Omega} -\operatorname{div} (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) \cdot \frac{\partial u_N^\eta}{\partial t} \\ &= \int_{\Omega} (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) : \frac{\partial \varepsilon(u_N^\eta)}{\partial t} \end{aligned}$$

by symmetry of λ^e .

Hence we obtain that

$$\frac{1}{2} \frac{d}{dt} \left(\int_{\Omega} \left| \frac{\partial u_N^\eta}{\partial t} \right|^2 + \int_{\Omega} (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) \right) = \int_{\Omega} (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) : \frac{\partial \varepsilon(u_N^\eta)}{\partial t}. \quad (14)$$

On the other hand we take the inner product of the first equation in (13) by $\frac{\partial m_N^\eta}{\partial t}$. Since $\frac{\partial m_N^\eta}{\partial t}$ is in V_N (so that we can remove P_N) we get

$$\begin{aligned} &\int_{\Omega} \left| \frac{\partial m_N^\eta}{\partial t} \right|^2 + \frac{d}{dt} \int_{\Omega} \left(|\nabla m_N^\eta|^2 + \Phi(m_N^\eta) + \frac{1}{2\eta} (|m_N^\eta|^2 - 1)^2 \right) + \frac{d}{dt} \int_{\mathbb{R}^3} |h_d(m_N^\eta)|^2 \\ &- 2 \int_{\Omega} (\lambda^m : (\lambda^e : \varepsilon(u_N^\eta))) m_N^\eta \cdot \frac{\partial m_N^\eta}{\partial t} + 2 \int_{\Omega} (\lambda^m : (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta))) m_N^\eta \cdot \frac{\partial m_N^\eta}{\partial t} = 0. \end{aligned}$$

As in the formal case, we remark that by symmetry of the 4-tensor λ^m , we have

$$2 \int_{\Omega} (\lambda^m : (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta))) m_N^\eta \cdot \frac{\partial m_N^\eta}{\partial t} = \frac{1}{2} \frac{d}{dt} \int_{\Omega} \mathcal{Q}(m_N^\eta)$$

with

$$\mathcal{Q}(m) = (\lambda^e : (\lambda^m : m \otimes m)) : (\lambda^m : m \otimes m).$$

In addition, by Lemma 1, we have

$$\begin{aligned} 2 \int_{\Omega} (\lambda^m : (\lambda^e : \varepsilon(u_N^\eta))) m_N^\eta \cdot \frac{\partial m_N^\eta}{\partial t} &= 2 \int_{\Omega} \varepsilon(u_N^\eta) : (\lambda^e : (\lambda^m : m_N^\eta \otimes \frac{\partial m_N^\eta}{\partial t})) \\ &= \int_{\Omega} \varepsilon(u_N^\eta) : \frac{\partial}{\partial t} (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)). \end{aligned}$$

The previous three formulae together with (14) yield

$$\int_{\Omega} \left| \frac{\partial m_N^\eta}{\partial t} \right|^2 + \frac{d}{dt} \mathcal{E}_N^\eta + \frac{1}{2\eta} \frac{d}{dt} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 = 0$$

where

$$\begin{aligned} \mathcal{E}_N^\eta(t) &= \int_{\Omega} (|\nabla m_N^\eta|^2 + \Phi(m_N^\eta)) + \int_{\mathbb{R}^3} |h_d(m_N^\eta)|^2 \\ &+ \frac{1}{2} \int_{\Omega} \left(\mathcal{Q}(m_N^\eta) - 2\varepsilon(u_N^\eta) : (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) + \left| \frac{\partial u_N^\eta}{\partial t} \right|^2 + (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) \right). \end{aligned}$$

We integrate this inequality with respect to time and we obtain: for all $T < T_N$,

$$\mathcal{E}_N^\eta(T) + \frac{1}{2\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 + \int_0^T \int_{\Omega} \left| \frac{\partial m_N^\eta}{\partial t} \right|^2 = \mathcal{E}_N^\eta(0) + \frac{1}{2\eta} \int_{\Omega} (|P_N(m_0)|^2 - 1)^2. \quad (15)$$

By Lemma 3, we obtain that the energy is positive, but if we use a simple Young inequality to absorb the bad sign term with the good sign terms given by the lemma, then we loose the control for the L^2

norm of ∇u_N^η . To avoid this problem, we will absorb at this step the bad sign term using a part of the penalization term as it is explained below. With Lemma 3, there exists C such that

$$\varepsilon(u_N^\eta) : (\lambda^e : (\lambda^m : m_N^\eta \otimes m_N^\eta)) \leq \frac{1}{4}(\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) + C\|m_N^\eta\|_{L^4}^4.$$

Inequality (15) together with the claim give a uniform bound on m_N^η and u_N^η since

$$\begin{aligned} \mathcal{E}_N^\eta + \frac{1}{2\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 \geq & \|\nabla m_N^\eta\|_{L^2(\Omega)}^2 + \frac{1}{2} \left\| \frac{\partial u_N^\eta}{\partial t} \right\|_{L^2(\Omega)}^2 + \frac{1}{4} \int_{\Omega} (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) \\ & + \frac{1}{2} \int_{\Omega} \mathcal{Q}(m_N^\eta) + \frac{1}{2\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 - C\|m_N^\eta\|_{L^4(\Omega)}^4. \end{aligned}$$

Now we remark that $(|\xi|^2 - 1)^2 \geq \frac{1}{2}|\xi|^4 - 1$ so

$$C\|m_N^\eta\|_{L^4(\Omega)}^4 \leq 2C \int_{\Omega} (|m_N^\eta|^2 - 1)^2 + 2C\text{meas}(\Omega),$$

and if η is so that $2C \leq \frac{1}{4\eta}$, we obtain that

$$\frac{1}{4\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 - C\|m_N^\eta\|_{L^4}^4 \geq -2C\text{meas}(\Omega).$$

So if η is small enough, we obtain that

$$\begin{aligned} \mathcal{E}_N^\eta + \frac{1}{2\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 \geq & \|\nabla m_N^\eta\|_{L^2(\Omega)}^2 + \frac{1}{2} \left\| \frac{\partial u_N^\eta}{\partial t} \right\|_{L^2(\Omega)}^2 + \frac{1}{4} \int_{\Omega} (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) \\ & + \frac{1}{2} \int_{\Omega} \mathcal{Q}(m_N^\eta) + \frac{1}{4\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 - 2C\text{meas}(\Omega). \end{aligned} \tag{16}$$

Remark 7 *The previous trick to absorb the bad sign term will be re-used in Part 3.*

2.3 Limit in the Galerkin Approximation

From (16) together with the energy estimate (15), we obtain that for η small enough

$$\begin{aligned} \|\nabla m_N^\eta\|_{L^2(\Omega)}^2 + \frac{1}{2} \left\| \frac{\partial u_N^\eta}{\partial t} \right\|_{L^2(\Omega)}^2 + \frac{1}{4} \int_{\Omega} (\lambda^e : \varepsilon(u_N^\eta)) : \varepsilon(u_N^\eta) + \frac{1}{2} \int_{\Omega} \mathcal{Q}(m_N^\eta) + \frac{1}{4\eta} \int_{\Omega} (|m_N^\eta|^2 - 1)^2 \\ \leq 2C\text{meas}(\Omega) + \mathcal{E}_N^\eta(0) + \frac{1}{2\eta} \int_{\Omega} (|P_N(m_0)|^2 - 1)^2. \end{aligned} \tag{17}$$

Claim: *the right hand side of (17) is bounded uniformly with respect to N .*

Proof of the claim: using Lemma 3, using that $|\mathcal{Q}(m)| \leq K|m|^4$ and the Sobolev embedding $H^1(\Omega) \subset L^4(\Omega)$, we get:

$$\mathcal{E}_N^\eta(0) \leq C\|P_N(m_0)\|_{H^1(\Omega)}^2 + \|\Pi_N(u_1)\|_{L^2(\Omega)}^2 + C \int_{\Omega} (\lambda^e : \mathcal{E}(\Pi_N(u_0))) : \varepsilon(\Pi_N(u_0)).$$

Since P_N and Π_N are orthogonal projection maps in L^2 , we have:

$$\|P_N(m_0)\|_{L^2(\Omega)} \leq \|m_0\|_{L^2(\Omega)} \text{ and } \|\Pi_N(u_1)\|_{L^2(\Omega)} \leq \|u_1\|_{L^2(\Omega)}.$$

Furthermore,

$$\begin{aligned}
\|\nabla P_N(m_0)\|_{L^2(\Omega)}^2 &= - \int_{\Omega} \Delta P_N(m_0) \cdot P_N(m_0) \\
&= - \int_{\Omega} \Delta P_N(m_0) \cdot m_0 \\
&\quad \text{since } V_N \text{ is stable by } P_N \\
&= \int_{\Omega} \nabla P_N(m_0) \cdot \nabla m_0 \\
&\leq \|\nabla P_N(m_0)\|_{L^2(\Omega)} \|\nabla m_0\|_{L^2(\Omega)}.
\end{aligned}$$

So,

$$\|\nabla P_N(m_0)\|_{L^2(\Omega)} \leq \|\nabla m_0\|_{L^2(\Omega)}. \quad (18)$$

In the same way,

$$\begin{aligned}
\int_{\Omega} (\lambda^e : \varepsilon(\Pi_N(u_0))) : \varepsilon(\Pi_N(u_0)) &= - \int_{\Omega} \operatorname{div} (\lambda^e : \varepsilon(\Pi_N(u_0))) \Pi_N(u_0) \\
&= - \int_{\Omega} \operatorname{div} (\lambda^e : \varepsilon(\Pi_N(u_0))) u_0 \\
&\quad \text{since } W_N \text{ is stable by } \operatorname{div} (\lambda^e : \varepsilon) \\
&= \int_{\Omega} (\lambda^e : \varepsilon(\Pi_N(u_0))) \varepsilon(u_0) \\
&\leq \left(\int_{\Omega} (\lambda^e : \varepsilon(\Pi_N(u_0))) \varepsilon(\Pi_N(u_0)) \right)^{\frac{1}{2}} \left(\int_{\Omega} (\lambda^e : \varepsilon(u_0)) \varepsilon(u_0) \right)^{\frac{1}{2}} \\
&\quad \text{from Lemma 3.}
\end{aligned}$$

So,

$$\int_{\Omega} (\lambda^e : \varepsilon(\Pi_N(u_0))) \varepsilon(\Pi_N(u_0)) \leq \int_{\Omega} (\lambda^e : \varepsilon(u_0)) \varepsilon(u_0). \quad (19)$$

We remark now that

$$\begin{aligned}
\frac{1}{2\eta} \int_{\Omega} (|P_N(m_0)|^2 - 1)^2 &\leq \frac{1}{\eta} \left(1 + \|P_N(m_0)\|_{L^4(\Omega)}^4 \right) \\
&\leq C(1 + \|m_0\|_{H^1(\Omega)}^4) \\
&\quad \text{by Sobolev embeddings.}
\end{aligned} \quad (20)$$

Inequalities (18), (19) and (20) yield that the right hand side of (17) is bounded uniformly with respect to N and the proof of the claim is complete (we remark that at this step, the bound for the right hand side term depends on η).

Therefore we obtain for η small enough an uniform bound for the following quantities:

- $\frac{\partial m_N^\eta}{\partial t}$ in $L^2(0, T_N; L^2(\Omega))$,
- ∇m_N^η in $L^\infty(0, T_N; L^2(\Omega))$,
- m_N^η in $L^\infty(0, T_N; L^4(\Omega))$,
- ∇u_N^η in $L^\infty(0, T_N; L^2(\Omega))$,
- $\varepsilon(u_N^\eta)$ in $L^\infty(0, T_N; L^2(\Omega))$.

This proves first that $T_N = +\infty$. In addition, since the bounds do not depend on N , we can assume by a diagonal extraction process that for all T , we have the following weak limits:

- $m_N^\eta \rightharpoonup m^\eta$ in $L^\infty(0, T; H^1(\Omega))$ weak *
- $m_N^\eta \longrightarrow m^\eta$ in $L^\infty(0, T; L^4(\Omega))$ strong (with Lemma 4),
- $\frac{\partial m_N^\eta}{\partial t} \rightharpoonup \frac{\partial m^\eta}{\partial t}$ in $L^2(0, T; L^2(\Omega))$ weak,
- $u_N^\eta \rightharpoonup u^\eta$ in $L^\infty(0, T; H^1(\Omega))$ weak *,
- $\frac{\partial u_N^\eta}{\partial t} \rightharpoonup \frac{\partial u^\eta}{\partial t}$ in $L^\infty(0, T; L^2(\Omega))$ weak *.

So we can take the limit on the variational formulation of the Galerkin approximation (13) and in the energy formula (15) by convexity arguments.

Therefore we obtain for a fixed η small enough that there exists (m^η, u^η) weak solution of (12) and satisfying the energy formula for all T :

$$\mathcal{E}^\eta(T) + \frac{1}{2\eta} \int_\Omega (|m^\eta|^2 - 1)^2 + \int_0^T \int_\Omega \left| \frac{\partial m^\eta}{\partial t} \right|^2 = \mathcal{E}^\eta(0). \quad (21)$$

where

$$\begin{aligned} \mathcal{E}^\eta(t) = & \int_\Omega \left(|\nabla m^\eta|^2 + \Phi(m^\eta) + \frac{1}{2} \mathcal{Q}(m^\eta) - \varepsilon(u^\eta) : (\lambda^e : (\lambda^m : m^\eta \otimes m^\eta)) \right) \\ & + \int_{\mathbb{R}^3} |h_d(m^\eta)|^2 + \frac{1}{2} \int_\Omega \left(\left| \frac{\partial u^\eta}{\partial t} \right|^2 + (\lambda^e : \varepsilon(u^\eta)) : \varepsilon(u^\eta) \right). \end{aligned}$$

Remark 8 *Since the initial data m_0 satisfies $|m_0| = 1$ a.e., the right hand side of the energy estimate does not depend on η since the penalization term vanishes at $t = 0$. This is a crucial point to obtain uniform bound when η tends to zero in the following section.*

3 Weak solutions for Landau-Lifschitz equation with magnetostriction

We take the limit in the penalized system when η tends to zero. From the energy estimate (21) and from Remark 8, using the same arguments as in the previous section, we obtain that the following quantities are uniformly bounded with respect to η :

- $\frac{\partial m^\eta}{\partial t}$ is bounded in $L^2(\mathbb{R}^+; L^2(\Omega))$,
- ∇m^η is bounded in $L^\infty(\mathbb{R}^+; L^2(\Omega))$,
- m^η is bounded in $L^\infty(\mathbb{R}^+; L^4(\Omega))$,
- ∇u^η is bounded in $L^\infty(\mathbb{R}^+; L^2(\Omega))$,
- $\varepsilon(u^\eta)$ is bounded in $L^\infty(\mathbb{R}^+; L^2(\Omega))$.

With this bound, using the diagonal extraction process, we obtain that there exists (m, u) such that for all T ,

- $m^\eta \rightharpoonup m$ in $L^\infty(0, T; H^1(\Omega))$ weak *,
- $m^\eta \longrightarrow m$ in $L^\infty(0, T; L^4(\Omega))$ strong (with Lemma 4),

- $\frac{\partial m^\eta}{\partial t} \rightharpoonup \frac{\partial m}{\partial t}$ in $L^2(0, T; L^2(\Omega))$ weak,
- $u^\eta \rightharpoonup u$ in $L^\infty(0, T; H^1(\Omega))$ weak $*$,
- $\frac{\partial u^\eta}{\partial t} \rightharpoonup \frac{\partial m}{\partial t}$ in $L^\infty(0, T; L^2(\Omega))$ weak $*$.

Using (21), $\int_\Omega (|m^\eta|^2 - 1)^2$ tends to zero and since $m^\eta \rightarrow m$ in $L^\infty(0, T; L^4(\Omega))$ strong, we obtain that

$$|m| = 1 \text{ a.e.}$$

In addition, using convexity or strong convergence arguments, taking the limit when η tends to zero in (21) that for all T ,

$$\mathcal{E}(T) + \int_0^T \int_\Omega \left| \frac{\partial m}{\partial t} \right|^2 \leq \mathcal{E}(0). \quad (22)$$

where

$$\begin{aligned} \mathcal{E}(t) = & \int_\Omega \left(|\nabla m|^2 + \Phi(m) + \frac{1}{2} \mathcal{Q}(m) - \varepsilon(u) : (\lambda^e : (\lambda^m : m \otimes m)) + \frac{1}{2} (\lambda^e : \varepsilon(u)) : \varepsilon(u) \right) \\ & + \int_{\mathbb{R}^3} |h_d(m)|^2 + \frac{1}{2} \int_\Omega \left| \frac{\partial u}{\partial t} \right|^2. \end{aligned}$$

In order to obtain that the weak limit m satisfies the Landau-Lifschitz equation, as in [2] and in [12], we consider $\chi \in \mathcal{C}_c^\infty(\mathbb{R}^+; \mathcal{C}^\infty(\Omega))$ compactly supported in $[0, T[$, and we take the test function $(t, x) \mapsto m^\eta(t, x) \wedge \chi(t, x)$ in the weak formulation for the first equation of (12).

We obtain then that:

$$\begin{aligned} \int_0^T \int_\Omega \left(\frac{\partial m^\eta}{\partial t} + m^\eta \wedge \frac{\partial m^\eta}{\partial t} \right) \cdot m^\eta \wedge \chi &= -2 \int_0^T \int_\Omega \sum_{i=1}^3 \frac{\partial m^\eta}{\partial x_i} \cdot \frac{\partial}{\partial x_i} (m^\eta \wedge \chi) \\ + 2 \int_0^T \int_\Omega (h_d(m^\eta) + \Psi(m^\eta) + (\lambda^m : (\lambda^e : \varepsilon(u^\eta))) m^\eta - (\lambda^m : (\lambda^e : (\lambda^m : m^\eta \otimes m^\eta))) m^\eta) &\cdot (m^\eta \wedge \chi). \end{aligned} \quad (23)$$

From algebraic calculations, we have:

$$\begin{aligned} \int_0^T \int_\Omega \left(\frac{\partial m^\eta}{\partial t} + m^\eta \wedge \frac{\partial m^\eta}{\partial t} \right) \cdot m^\eta \wedge \chi &= \int_0^T \int_\Omega \left(\frac{\partial m^\eta}{\partial t} - m^\eta \wedge \frac{\partial m^\eta}{\partial t} \right) \cdot \chi \\ &+ \int_0^T \int_\Omega (|m^\eta|^2 - 1) \frac{\partial m^\eta}{\partial t} \cdot \chi - \int_0^T \int_\Omega (m^\eta \cdot \frac{\partial m^\eta}{\partial t}) (m^\eta \cdot \chi). \end{aligned}$$

Since $m^\eta \rightarrow m$ in $L^\infty(0, T; L^4(\Omega))$ strong and $\frac{\partial m^\eta}{\partial t} \rightharpoonup \frac{\partial m}{\partial t}$ in $L^2(0, T; L^2(\Omega))$ weak, we obtain that

$$\begin{aligned} \int_0^T \int_\Omega \left(\frac{\partial m^\eta}{\partial t} + m^\eta \wedge \frac{\partial m^\eta}{\partial t} \right) \cdot m^\eta \wedge \chi &\longrightarrow \int_0^T \int_\Omega \left(\frac{\partial m}{\partial t} - m \wedge \frac{\partial m}{\partial t} \right) \cdot \chi \\ &+ \int_0^T \int_\Omega (|m|^2 - 1) \frac{\partial m}{\partial t} \cdot \chi - \int_0^T \int_\Omega (m \cdot \frac{\partial m}{\partial t}) (m \cdot \chi). \end{aligned}$$

As $|m| = 1$, we obtain that $m \cdot \frac{\partial m}{\partial t} = 0$, and so

$$\int_0^T \int_\Omega \left(\frac{\partial m^\eta}{\partial t} + m^\eta \wedge \frac{\partial m^\eta}{\partial t} \right) \cdot m^\eta \wedge \chi \longrightarrow \int_0^T \int_\Omega \left(\frac{\partial m}{\partial t} - m \wedge \frac{\partial m}{\partial t} \right) \cdot \chi.$$

By the same kind of arguments, we take the limit in the right hand side of (23) and we obtain that

$$\begin{aligned} \int_{\mathbb{R}^+ \times \Omega} \left(\frac{\partial m}{\partial t} - m \wedge \frac{\partial m}{\partial t} \right) \chi(t, x) dt dx &= 2 \int_{\mathbb{R}^+ \times \Omega} \sum_{i=1}^3 m \wedge \frac{\partial m}{\partial x_i} \cdot \frac{\partial \chi}{\partial x_i} - 2 \int_{\Omega} (h_d(m) + \Psi(m)) \cdot \chi \\ &\quad - 2 \int_{\Omega} ((\lambda^m : (\lambda^e : \varepsilon(u)))m - (\lambda^m : (\lambda^e : (\lambda^m : m \otimes m)))m) \cdot \chi, \end{aligned}$$

By standart arguments, we pass to the limit in the wave equation, and we obtain that (m, u) satisfies (5)-(6)-(7).

So we have proved the existence of a global in time weak solution of (5)-(6)-(7) satisfying the saturation constraint (1) and the energy estimate (22) and such that

- $m \in L^\infty(\mathbb{R}^+; H^1(\Omega)),$
- $\frac{\partial m}{\partial t} \in L^2(\mathbb{R}^+; L^2(\Omega)),$
- $u \in L^\infty(\mathbb{R}^+; H^1(\Omega)),$
- $\frac{\partial u}{\partial t} \in L^\infty(\mathbb{R}^+; L^2(\Omega)).$

4 ω limit set

We fix a weak solution of (5)-(6)-(7) satisfying the previous conditions, so its ω -limit set is non empty, that is we can consider m_∞ such that there exists a sequence $(t_n)_n$ with $t_n \rightarrow +\infty$ and such that $m(t_n) \rightharpoonup m_\infty$ in $H^1(\Omega)$ weakly and in $L^p(\Omega)$ strong for all $p < 6$ by Sobolev theorems.

For a fixed $a > 0$, we define $V^n(s, x) = m(t_n + s, x)$, defined on $] - a, a[\times \Omega$ with values in S^2 .

In the spirit of [12], we begin by performing the limit when t_n tends to $+\infty$ for a fixed value of a . Using that $\frac{\partial m}{\partial t}$ is in $L^2(\mathbb{R}^+; L^2(\Omega))$, we obtain by this way the limit equation satisfied by m_∞ . This equation contains a terms U_∞ coming from u . In order to obtain the limit equation satisfied by U_∞ , in a second step, we take the limit in the wave equation when a tends to $+\infty$.

4.1 Limit when n tends to $+\infty$

We remark that

$$\frac{1}{2a} \int_{-a}^a \int_{\Omega} |V^n(s, x) - m(t_n, x)|^2 dx ds \leq \frac{1}{2a} \int_{s=-a}^a \int_{x \in \Omega} \left| \int_{\tau=t_n}^s \frac{\partial m}{\partial t}(\tau, x) d\tau \right|^2 dx ds \leq a \int_{t_n-a}^{+\infty} \int_{\Omega} \left| \frac{\partial m}{\partial t} \right|^2, \quad (24)$$

so extracting a subsequence if necessary, $V^n \rightarrow m_\infty$ in $L^2([-a, a]; L^2(\Omega))$ strongly and almost everywhere, and by the bounds for the gradient, $V^n \rightharpoonup m_\infty$ in $L^\infty([-a, a]; H^1(\Omega))$ weak *.

In the same way, we define $U^n(s, x) = u(t_n + s, x)$. Let us introduce for $a > 1$ the map $\rho_a \in C^\infty(\mathbb{R}; \mathbb{R})$ such that

$$\begin{cases} \rho_a(s) = 0 \text{ out of } [-a, a], \\ \rho_a(s) = 1 \text{ on } [-a+1, a-1], \\ 0 \leq \rho_a \leq 1, \\ |\rho'_a(s)| \leq 2. \end{cases}$$

We set

$$U_a^n = \frac{1}{2a} \int_{-a}^a u(t_n + s, x) \rho_a(s) ds.$$

By the estimates on u , there exists a constant C such that for all n and all a , $\|U_a^n\|_{H^1(\Omega)} \leq C$.

Let $\xi \in H^1(\Omega)$ be a test function. In the weak formulation of (5) with the test function $\frac{1}{2a}\rho_a(t-t_n)\xi(x)$, and we obtain that:

$$\frac{1}{2a} \int_{-a}^a \int_{\Omega} \left(\frac{\partial V^n}{\partial t} - V^n \wedge \frac{\partial V^n}{\partial t} \right) \rho_a(s) \xi(x) ds dx = T_1 + \dots + T_4$$

where

$$T_1 = \frac{1}{a} \int_{-a}^a \int_{\Omega} \sum_i V^n \wedge \frac{\partial V^n}{\partial x_i} \cdot \frac{\partial \xi}{\partial x_i} \rho_a(s) ds dx,$$

$$T_2 = -\frac{1}{a} \int_{-a}^a \int_{\Omega} V^n \wedge (h_d(V^n) + \psi(V^n)) \cdot \xi(x) \rho_a(s) ds dx$$

$$T_3 = -\frac{1}{a} \int_{-a}^a \int_{\Omega} V^n \wedge (\lambda^m : (\lambda^e : (\varepsilon(U^n))) V^n) \cdot \xi(x) \rho_a(s) ds dx,$$

$$T_4 = \frac{1}{a} \int_{-a}^a \int_{\Omega} V^n \wedge ((\lambda^m : (\lambda^e : (\lambda^m : V^n \otimes V^n))) V^n) \xi(x) \cdot \xi(x) \rho_a(s) ds dx.$$

The left hand side term tends to zero when n tends to $+\infty$, since

$$\left| \frac{1}{2a} \int_{-a}^a \int_{\Omega} \left(\frac{\partial V^n}{\partial t} - V^n \wedge \frac{\partial V^n}{\partial t} \right) \rho_a(s) \xi(x) ds dx \right| \leq \frac{2}{\sqrt{2a}} \left(\int_{[t_n-a, +\infty]} \int_{\Omega} \left| \frac{\partial m}{\partial t} \right|^2 \right)^{\frac{1}{2}} \|\xi\|_{L^2(\Omega)}.$$

We denote by

$$\overline{\rho_a} = \frac{1}{2a} \int_{-a}^a \rho_a(s) ds.$$

From (24), we obtain that,

$$T_1 \longrightarrow 2\overline{\rho_a} \int_{\Omega} \sum_{i=1}^3 m_{\infty} \wedge \frac{\partial m_{\infty}}{\partial x_i} \cdot \frac{\partial \xi}{\partial x_i} dx \text{ when } n \text{ tends to } +\infty.$$

Moreover, since ψ is linear and since h_d maps continuously $l^2(\Omega)$ in $L^2(\mathbb{R}^3)$, we have

$$T_2 \longrightarrow -2\overline{\rho_a} \int_{\Omega} m_{\infty} \wedge (h_d(m_{\infty}) + \psi(m_{\infty})) \xi(x) dx,$$

where

Concerning T_4 , we denote by $F(X_1, X_2, X_3, X_4) = X_1 \wedge (\lambda^m : (\lambda^e : (\lambda^m : X_2 \otimes X_3)) X_4)$, so that

$$T_4 = \frac{1}{a} \int_{-a}^a \int_{\Omega} F(V^n, V^n, V^n, V^n) \cdot \xi(x) \rho_a(s) ds dx.$$

By linearity we write T_4 on the following way:

$$\begin{aligned} T_4 &= \frac{1}{a} \int_{-a}^a \int_{\Omega} F(V^n - m_{\infty}, V^n, V^n, V^n) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad + \frac{1}{a} \int_{-a}^a \int_{\Omega} F(m_{\infty}, V^n - m_{\infty}, V^n, V^n) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad + \frac{1}{a} \int_{-a}^a \int_{\Omega} F(m_{\infty}, m_{\infty}, V^n - m_{\infty}, V^n) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad + \frac{1}{a} \int_{-a}^a \int_{\Omega} F(m_{\infty}, m_{\infty}, m_{\infty}, V^n - m_{\infty}) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad + 2\overline{\rho_a} \int_{\Omega} F(m_{\infty}, m_{\infty}, m_{\infty}, m_{\infty}) \cdot \xi(x) dx. \end{aligned}$$

Since V^n and m_∞ are bounded by 1 in L^∞ , and since $V_n \rightarrow m_\infty$ in L^2 strong, we obtain that

$$T_4 \rightarrow 2\overline{\rho_a} \int_{\Omega} F(m_\infty, m_\infty, m_\infty, m_\infty) \cdot \xi(x) dx.$$

Concerning T_3 , we denote by $G(X_1, X_2, Y) = X_1 \wedge (\lambda^m : (\lambda^e : Y)X_2)$, so that

$$T_3 = -\frac{1}{a} \int_{-a}^a \int_{\Omega} G(V^n, V^n, \varepsilon(U^n)) \cdot \xi(x) \rho_a(s) ds dx.$$

We have, in the spirit of the previous calculations,

$$\begin{aligned} T_3 &= -\frac{1}{a} \int_{-a}^a \int_{\Omega} G(V^n - m_\infty, V^n, \varepsilon(U^n)) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad -\frac{1}{a} \int_{-a}^a \int_{\Omega} G(m_\infty, V^n - m_\infty, \varepsilon(U^n)) \cdot \xi(x) \rho_a(s) ds dx \\ &\quad -\frac{1}{a} \int_{-a}^a \int_{\Omega} G(m_\infty, m_\infty, \varepsilon(U^n)) \cdot \xi(x) \rho_a(s) ds dx. \end{aligned}$$

The first two terms of the right hand side tend to zero when n tends to $+\infty$, since $\varepsilon(U^n)$ is bounded in $L^\infty(\mathbb{R}^+; L^2(\Omega))$, V^n and m_∞ are bounded by 1 in L^∞ , and since $V_n \rightarrow m_\infty$ in L^2 strong.

The last term reads:

$$-\frac{1}{a} \int_{-a}^a \int_{\Omega} G(m_\infty, m_\infty, \varepsilon(U^n)) \cdot \xi(x) \rho_a(s) ds dx = \int_{\Omega} G(m_\infty, m_\infty, \varepsilon(U_a)) \cdot \xi(x) dx$$

so since U_a^n is bounded in $H^1(\Omega)$ uniformly with respect to n and a , extracting a subsequence, there exists a subsequence such that $U_a^n \rightharpoonup U_a$ in $H^1(\Omega)$ weak. Therefore,

$$T_3 \rightarrow \int_{\Omega} G(m_\infty, m_\infty, \varepsilon(U_a)) \cdot \xi(x) dx \text{ when } n \rightarrow +\infty.$$

At this step, we have proved that for all $a > 1$, m_∞ satisfies:

$$\begin{aligned} \int_{\Omega} \sum_{i=1}^3 m_\infty \wedge \frac{\partial m_\infty}{\partial x_i} \cdot \frac{\partial \xi}{\partial x_i} dx - \int_{\Omega} m_\infty \wedge \left(h_d(m_\infty) + \psi(m_\infty) + F(m_\infty, m_\infty, m_\infty, m_\infty) \right) \xi(x) dx \\ + \frac{1}{\overline{\rho_a}} \int_{\Omega} G(m_\infty, m_\infty, \varepsilon(U_a)) \cdot \xi(x) dx = 0. \end{aligned}$$

We take now the limit of this equation when a tends to $+\infty$.

First, $\overline{\rho_a}$ tends to 1. in addition, U_a is uniformly bounded, so we can extract a subsequence such that $U_a \rightharpoonup U_\infty$ in $H^1(\Omega)$ weakly when a tends to $+\infty$. Let us precise the equation satisfied by U_∞ .

We write the weak formulation of (6) taking the test function : $\xi(x) \rho_a(t_n + s)$. We obtain that:

$$\begin{aligned} -\frac{1}{2a} \int_{-a}^a \int_{\Omega} \frac{\partial U^n}{\partial t} \rho'_a(s) \xi(x) dx ds + \frac{1}{2a} \int_{-a}^a \int_{\Omega} (\lambda^e : \varepsilon(U^n)) : \varepsilon(\xi) \rho_a(s) dx ds \\ = \frac{1}{2a} \int_{-a}^a \int_{\Omega} (\lambda^e : (\lambda^m : V^n \otimes V^n)) : \varepsilon(\xi) \rho_a(s) dx ds. \end{aligned}$$

When n tends to $+\infty$, the right hand side term tends to

$$\overline{\rho_a} \int_{\Omega} (\lambda^e : (\lambda^m : m_\infty \otimes m_\infty)) : \varepsilon(\xi) dx$$

The second term satisfies:

$$\frac{1}{2a} \int_{-a}^a \int_{\Omega} (\lambda^e : \varepsilon(U^n)) : \varepsilon(\xi) \rho_a(s) ds dx = \int_{\Omega} (\lambda^e : \varepsilon(U_a^n)) : \varepsilon(\xi) dx$$

so it tends to $\int_{\Omega} (\lambda^e : \varepsilon(U_a)) : \varepsilon(\xi) dx$ when n tends to $+\infty$, and after when a tends to $+\infty$, the limit is $\int_{\Omega} (\lambda^e : \varepsilon(U_{\infty})) : \varepsilon(\xi) dx$.

Concerning the first left hand side term, we estimate it on the following way:

$$\begin{aligned} \left| \frac{1}{2a} \int_{-a}^a \int_{\Omega} \frac{\partial U^n}{\partial t} \rho'_a(s) \xi(x) dx ds \right| &\leq \frac{1}{2a} \int_{[-a, -a+1] \cup [a-1, a]} \int_{\Omega} \left| \frac{\partial U^n}{\partial t} \right| |\rho'_a(s)| |\xi(x)| dx ds \\ &\leq \frac{1}{a} 4 \|\xi\|_{L^2} \left\| \frac{\partial u}{\partial t} \right\|_{L^{\infty}(\mathbb{R}^+; L^2(\Omega))}, \end{aligned}$$

so when n tends to $+\infty$ and after when a tends to $+\infty$, this term tends to zero.

Hence, U_{∞} satisfies:

$$\int_{\Omega} (\lambda^e : \varepsilon(U_{\infty})) : \varepsilon(\xi) dx = \int_{\Omega} (\lambda^e : (\lambda^m : m_{\infty} \otimes m_{\infty})) : \varepsilon(\xi) dx.$$

We have proved that if m_{∞} is in the ω -limit set of a trajectory m , then it satisfies in the weak sense the following system:

$$m_{\infty} \wedge \left(\Delta m_{\infty} + h_d(m_{\infty}) + \psi(m_{\infty}) + (\lambda^m : (\lambda^e : \varepsilon(u_{\infty}))) m_{\infty} - (\lambda^m : (\lambda^e : (\lambda^m : m_{\infty} \otimes m_{\infty}))) m_{\infty} \right) = 0,$$

where u_{∞} is deduced from m_{∞} by:

$$\begin{cases} u_{\infty} \in H_0^1(\Omega), \\ \operatorname{div} (\lambda^e : \varepsilon(u_{\infty})) = \operatorname{div} (\lambda^e : (\lambda^m : m_{\infty} \otimes m_{\infty})) \text{ in } \Omega. \end{cases}$$

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