



## Advanced approach to local magnetic field computation in magnetocaloric materials characterization

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## Quick reminder of Extraction Magnetometer

I. Intro

### Measure of magnetic moment project on Z



- Homogeneous material

$$m_{z}(H_{0}) = \int_{V_{sample}} \vec{M}(H) \cdot \vec{z} \, dV$$
[A.m<sup>2</sup>]

- isotropy on the material
- symetries on the sample

$$m_z(H_0)\,\vec{z} = \int_{V_{sample}} \vec{M}(H)\,dV$$

And  $M(H) \neq m_z(H)/V$  because heterogeneity of H and  $H \neq H_0$ 



I. Intro

### Difference between applied field H<sub>0</sub> and the internal field H



The gray volume feels :

- the applied field  $H_0$
- The field induce by the magnetization of its neighbours  $H_d$

$$H = H_0 + H_d$$



I. Intro

### Difference between applied field H<sub>0</sub> and the internal Field H



Helmholtz decomposition

 $H = H_0 + H_d$ 

Demagnetizing field respect

 $\begin{aligned} div(\mu_0 H_d(M) + M) &= 0\\ rot \ H_d(M) &= 0\\ H_d(M) \to 0 \ in \ \infty \end{aligned}$ 

We define  $H_d = -grad\phi_d$ 

$$\phi_d(M)(x) = \frac{1}{4\pi} \int_{\Omega} \frac{div M(y)}{|x-y|} dy + \frac{1}{4\pi} \int_{\partial \Omega} \frac{M(y).n(y)}{|x-y|}$$

Advanced approach in magnetocaloric materials characterization



I. Introduction of the demagnetizing field and the heterogeneity

**II. Demagnetizing Factor** 

**III.Formulation as an inverse Problem** 

**IV. Demagnetizing Factor as an inverse problem** 

**V.** Perspectives

## Demagnetizing Factor

I. Intro > II. Demag. Factor

### In elliptical shape

The magnetic field is constant inside the body

$$m_z(H_0) = \int_{V_{sample}} M(H) \, dV \qquad \qquad M(H) = m_z(H_0)/V$$

- The demagnetizing field can be write as  $H_d = -NM$  with N only function of the geometry
  - $H = H_0 + H_d$   $H = H_0 Nm_z(H_0)/V$   $H = f(H_0)$

$$M(H) = m_z(f^{-1}(H))/V$$

But experimentaly it is difficult to have elliptical shape



## Generalization of the demagnetizing Factor



I. Intro > II. Demag. Factor

### In general shape

1st The field is not constant inside the body

 $m_z(H_0) = \int_{V_{sample}} M(H) \, dV \qquad < M(H) > = m_z(H_0)/V$ 

• 2<sup>nd</sup> extention of the notion of demagnetizing field define as:  $\int_{V} H_{d} dv = -N_{m} \int_{V} M dv \qquad < H > = H_{0} - N_{m} < M(H) >$   $< H > \sim H_{0} - N_{m} M(<H>) \qquad < H > \sim f(H_{0})$ 

With N function of the geometry and M(H)

3<sup>rd</sup> approximation

$$M(H) \sim \langle M(H) \rangle = m_z(f^{-1}(\langle H \rangle))/V$$

Approximations are difficult to validate

## Test of the method



I. Intro > II. Demag. Factor

### Test the method based on numerical simulation



### Numerical setup

- Cylinder shape with radius 20 and high/2 = [5, 10, ..., 55]
- Generalized demagnetizing factor interpolated from D.X Chen table\* But it is difficult to choose with non linear material
- Magnetization curve give by arctan. model with  $J_s = 1.3 T$  and  $\mu_r = 10$

\*D.-X. Chen, J. A. Brug, et R. B. Goldfarb, « Demagnetizing factors for cylinders », *IEEE Transactions on Magnetics*, vol. 27, nº 4, p. 3601 - 3619, juill. 1991.

## Result of the simulation



I. Intro > II. Demag. Factor



A long sample improve the efficiency of the method

Because the demagnetizing field decrease

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## Inverse problem



#### I. Intro > II. Demag. Factor > III. Inv. formulation

### Scheme of the inverse problem and method of resolution



# How to parametrize the magnetic curve « an unknown curve »

With the previous test of the method we obtained anl error equal to zero with 3 parameters models because the magnetization is defined with the same model

# How to parametrize the magnetic curve for the inverse problem

I. Intro > II. Demag. Factor > III. Inv. formulation

## Generalized demagnetizing factor

### Parametric function

- Model with 3 parameters  $(l + \mu_0)H + \frac{2J_s}{\pi} arctg\left(\frac{\pi(\mu_r 1)\mu_0H}{2J_s}\right) 3$

### Parametric point (interpolated)

Linear, Cubic, Spline interpolation

Computation time • 12



Degree of freedom



Complexity

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### Prismatic sample in the magnetometer G2E I. Intro > II. Demag. Factor > III. Inv. Formulation > IV. Prismatic sample $\downarrow \downarrow \downarrow \downarrow \downarrow$ $H_0$ Gd prismatic sample 1x2x6 mm $H_0$ $\downarrow \downarrow \downarrow \downarrow \downarrow$ Orientation +++ Orientation ++ 0.01 283K orientation ++ b.008 283K orientation +++ 0.006



## Inversion based magnetometer mesurement



I. Intro > II. Demag. Factor > III. Inv. Formulation > IV. Prismatic sample



Demag. factor function of temperature for orientation ++ 0.31 Error on the magnetic moment



## V. Perspectives



I. Intro > II. Demag. Factor > III. Inv. Formulation > IV. Prismatic sample > V. Perspectives

### Method of comparaison

- Error on the magnetic moment
- B(H) should be the same for any shape
- $\Rightarrow$  Anistropie from process or Gd
- $\Rightarrow$  Use of cubic sample



### Now we use parametric function and interpolated point

- To have a best fit of the magnetization curve to reduce the error NOW less than 0.5% on the magnetic curve (2h for one curve)
- Try to have an error estimation on the magnetization curve

### Now we start to propagate the errors on Δs

 Propagate the error througth the Maxwell Relation to have an estimation on the errors on the Δs (intrinsec)





### **Thanks for your attention**

### **Question** ?



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