



HAL
open science

Weierstrass representation of Lagrangian surfaces in four-dimensional space using spinors and quaternions

Frédéric Hélein, Pascal Romon

► **To cite this version:**

Frédéric Hélein, Pascal Romon. Weierstrass representation of Lagrangian surfaces in four-dimensional space using spinors and quaternions. *Commentarii Mathematici Helvetici*, 2000, 75 (4), pp.668-680. 10.1007/s000140050144 . hal-00858413

HAL Id: hal-00858413

<https://hal.science/hal-00858413>

Submitted on 5 Sep 2013

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Weierstrass representation of Lagrangian surfaces in four-dimensional space using spinors and quaternions

Frédéric Hélein and Pascal Romon

Abstract. We derive a Weierstrass-type formula for conformal Lagrangian immersions in Euclidean 4-space, and show that the data satisfies an equation similar to Dirac equation with complex potential. Alternatively this representation has a simple formulation using quaternions. We apply it to the Hamiltonian stationary case and construct all possible tori, thus obtaining a first approach to a moduli space in terms of a simple algebraic-geometric problem on the plane. We also classify Hamiltonian stationary Klein bottles and show they self-intersect.

Mathematics Subject Classification (2000). Primary 53C42, 53D12, Secondary 49Q10, 53A05.

Keywords. Lagrangian surfaces, Weierstrass representation, Dirac equation, minimal surfaces, variational problem with constraint.

Introduction

In this paper we revisit and generalize some aspects of the Weierstrass construction for Hamiltonian stationary Lagrangian surfaces which was given in [HR]. We are interested here in Lagrangian surfaces in $\mathbb{R}^4 \simeq \mathbb{C}^2$, equipped with the standard symplectic form, a priori without the assumption of being Hamiltonian stationary. In order to build a Weierstrass representation of these immersions, it is natural in a first step to consider the set of weakly conformal Lagrangian immersions of a Riemann surface: they are maps which coincide with a conformal immersion outside isolated points where the Jacobian matrix vanishes, and such that the pull-back of the symplectic form vanishes. In [HR], we analyzed weakly conformal Lagrangian immersions which are Hamiltonian stationary, i.e. critical points of the area functional with the requirements of (i) being Lagrangian and (ii) the only infinitesimal variations allowed are the one given by Hamiltonian vector fields (see [O1], [O2], [SW]). They enjoy a nice characterization using the canonical *Lagrangian angle map* defined over any Lagrangian surface and with values in the circle S^1 (it is actually a part of the classical Gauss map of the immersion). A precise definition is given in Section 1 below. A Lagrangian surface is Hamiltonian

stationary if and only if the Lagrangian angle map is a harmonic map from the surface to the circle. This leads to many nice properties which may be summarized by saying that these surfaces are solutions of a completely integrable system.

In the first Section, we show that the Hamiltonian stationary assumption may be removed and that we still have a Weierstrass type representation of *all* weakly conformal Lagrangian immersions. This is very similar to the Weierstrass representation for weakly conformal immersions in \mathbb{R}^3 due to B. G. Konopelchenko [Ko]. Some variants were proposed also in [Ke] and this representation has been studied by many authors [KoT1, KoT2], [B1, B2], [KuS], [T1, T2]. Actually we shall first present our representation using notations that make evident the similarities between the two theories, since they rely on a kind of Dirac equation.

In the second Section, we propose an equivalent representation using quaternions. The gain is not only formal, but it also unveils the quaternionic structure of the problem. In particular when we specialize back to Hamiltonian stationary Lagrangian immersions, we see immediately that the set of solutions has the structure of a vector space over the quaternions. Exploiting this structure leads to formulae equivalent to the one in [HR] but much simpler to handle.

In the last Section, we present computations using these formulae and we focus on immersed Klein bottles. We classify all such surfaces and show that none is embedded.

Acknowledgment

The Authors are pleased to thank Claude Viterbo for interesting discussions.

1. Weierstrass representation for Lagrangian surfaces in \mathbb{C}^2

Let (ϵ_1, ϵ_2) be the canonical basis of \mathbb{C}^2 over \mathbb{C} . We equip \mathbb{C}^2 with the Hermitian product

$$\langle v, w \rangle_H = v^1 \overline{w^1} + v^2 \overline{w^2},$$

so that, as a real four-dimensional space, \mathbb{C}^2 has the Euclidean scalar product $\langle \cdot, \cdot \rangle_E$ and the symplectic form ω given by

$$\langle v, w \rangle_H = \langle v, w \rangle_E - i\omega(v, w). \quad (1)$$

Let $\Omega \subset \mathbb{C}$ be a simply connected domain and $X : \Omega \rightarrow \mathbb{C}^2$ some conformal Lagrangian immersion. Letting $e^f := \left| \frac{\partial X}{\partial x} \right|^2 = \left| \frac{\partial X}{\partial y} \right|^2$, and $e_1 := e^{-f/2} \frac{\partial X}{\partial x}$, $e_2 := e^{-f/2} \frac{\partial X}{\partial y}$, we have

$$dX = e^{f/2}(e_1 dx + e_2 dy), \quad (2)$$

and (e_1, e_2) is necessarily the orthonormal basis of some Lagrangian plane in \mathbb{C}^2 . By (1) this condition amounts to $\langle e_1, e_2 \rangle_H = 0$. Hence, for all $(x, y) \in \Omega$, the components of $e_1(x, y)$ and $e_2(x, y)$ in the basis (ϵ_1, ϵ_2) form a matrix

$$e(x, y) = \begin{pmatrix} e_1^1 & e_2^1 \\ e_1^2 & e_2^2 \end{pmatrix} (x, y), \tag{3}$$

which belongs to $U(2)$. Decompose $e(x, y)$ as

$$e(x, y) = e^{i\beta/2} g, \tag{4}$$

where $\beta \in \mathbb{R}/2\pi\mathbb{Z}$ and $g \in SU(2)$. Notice that such a decomposition is not unique; the other possible one is $e(x, y) = e^{i(\beta+2\pi)/2}(-g)$. But since Ω is simply connected, we can construct smooth functions $\beta : \Omega \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ and $g : \Omega \rightarrow SU(2)$, such that (4) holds everywhere. The angle β is called the *Lagrangian angle function*, is characterized by $dz^1 \wedge dz^2(e_1, e_2) = e^{i\beta}$.

Let us focus on $(x, y) \mapsto e^{f(x,y)/2} g(x, y)$, a map with values in $\mathbb{R}_+ \cdot SU(2)$. We remark that $\mathbb{R}_+ \cdot SU(2)$ is isomorphic to the set of quaternions \mathbb{H} . Namely, letting

$$\mathbf{1} := \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, I := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, J := \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, K := \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix},$$

the map

$$\begin{aligned} \mathcal{H} : \quad & \mathbb{R}_+ \cdot SU(2) \mapsto \mathbb{H} \\ & t\mathbf{1} + xI + yJ + zK \mapsto t + xi + yj + zk \end{aligned}$$

is a field isomorphism¹. Using the fact that each quaternion ζ can be written in an unique way $\zeta = a + jb$, where $a, b \in \mathbb{C} \subset \mathbb{H}$, we shall define two functions $s_1, s_2 : \Omega \rightarrow \mathbb{C}$ such that

$$\mathcal{H} \left(e^{f(x,y)/2} g(x, y) \right) = s_1(x, y) + js_2(x, y) = s_1(x, y) + \overline{s_2}(x, y)j.$$

A computation shows that

$$e^{f(x,y)/2} g(x, y) = \begin{pmatrix} \operatorname{Re}(s_1) + i\operatorname{Re}(s_2) & -\operatorname{Im}(s_1) - i\operatorname{Im}(s_2) \\ \operatorname{Im}(s_1) - i\operatorname{Im}(s_2) & \operatorname{Re}(s_1) - i\operatorname{Re}(s_2) \end{pmatrix} (x, y).$$

¹ One could also use the more natural isomorphism $\tilde{\mathcal{H}} : \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} \mapsto a + jb$. Both isomorphisms are actually conjugate through $\mathcal{H}(\cdot) = \tau \tilde{\mathcal{H}} \tau^{-1}$, where $\tau := \frac{\sqrt{2}}{2}(i + j)$. But \mathcal{H} will be more suitable in the following.

We deduce from (2) and (4) that in the basis (ϵ_1, ϵ_2) ,

$$\begin{aligned}
 dX &= e^{i\beta/2} \left(\begin{pmatrix} \operatorname{Re}(s_1) + i\operatorname{Re}(s_2) \\ \operatorname{Im}(s_1) - i\operatorname{Im}(s_2) \end{pmatrix} dx \right. \\
 &\quad \left. + \begin{pmatrix} -\operatorname{Im}(s_1) - i\operatorname{Im}(s_2) \\ \operatorname{Re}(s_1) - i\operatorname{Re}(s_2) \end{pmatrix} dy \right) \\
 &= e^{i\beta/2} \left(\operatorname{Re} \left[\begin{pmatrix} s_1 \\ -is_1 \end{pmatrix} dz \right] + i\operatorname{Re} \left[\begin{pmatrix} s_2 \\ is_2 \end{pmatrix} dz \right] \right).
 \end{aligned} \tag{5}$$

We look for the necessary and sufficient conditions on (s_1, s_2) such that a solution of (5) exists on all simply-connected domain, i. e.

$$\begin{aligned}
 0 &= d \left(e^{i\beta/2} \operatorname{Re} \left[\begin{pmatrix} s_1 \\ -is_1 \end{pmatrix} dz \right] + i e^{i\beta/2} \operatorname{Re} \left[\begin{pmatrix} s_2 \\ is_2 \end{pmatrix} dz \right] \right) \\
 &= e^{i\beta/2} \begin{pmatrix} -\operatorname{Im} \left(\frac{\partial \bar{s}_2}{\partial z} - \frac{1}{2} \frac{\partial \beta}{\partial \bar{z}} s_1 \right) - i\operatorname{Im} \left(\frac{\partial s_1}{\partial \bar{z}} + \frac{1}{2} \frac{\partial \beta}{\partial z} \bar{s}_2 \right) \\ \operatorname{Re} \left(\frac{\partial \bar{s}_2}{\partial z} - \frac{1}{2} \frac{\partial \beta}{\partial \bar{z}} s_1 \right) + i\operatorname{Re} \left(\frac{\partial s_1}{\partial \bar{z}} + \frac{1}{2} \frac{\partial \beta}{\partial z} \bar{s}_2 \right) \end{pmatrix} dz \wedge d\bar{z}.
 \end{aligned} \tag{6}$$

We see that (6) is true if and only if

$$\begin{cases} \frac{\partial s_1}{\partial \bar{z}} = -\frac{1}{2} \frac{\partial \beta}{\partial z} \bar{s}_2 \\ \frac{\partial \bar{s}_2}{\partial z} = \frac{1}{2} \frac{\partial \beta}{\partial \bar{z}} s_1. \end{cases} \tag{7}$$

This system may be written using a kind of Dirac operator. Set

$$U := \frac{1}{2} \frac{\partial \beta}{\partial z}, \quad \phi := \begin{pmatrix} s_1 \\ \bar{s}_2 \end{pmatrix}, \quad \mathcal{D} := \begin{pmatrix} 0 & \frac{\partial}{\partial z} \\ -\frac{\partial}{\partial \bar{z}} & 0 \end{pmatrix},$$

then (7) is equivalent to the following

$$\mathcal{D}\phi = \begin{pmatrix} \bar{U} & 0 \\ 0 & U \end{pmatrix} \phi. \tag{8}$$

Conversely one may check directly that, for any smooth function $\beta : \Omega \rightarrow \mathbb{R}/2\pi\mathbb{Z}$, any solution $\phi = \begin{pmatrix} s_1 \\ \bar{s}_2 \end{pmatrix}$ of (8) produces a \mathbb{C}^2 -valued closed 1-form on Ω given by

$$\alpha := e^{i\beta/2} \left(\operatorname{Re} \left[\begin{pmatrix} s_1 \\ -is_1 \end{pmatrix} dz \right] + i\operatorname{Re} \left[\begin{pmatrix} s_2 \\ is_2 \end{pmatrix} dz \right] \right).$$

And if $\phi \neq 0$, any solution $X : \Omega \rightarrow \mathbb{C}^2$ of $dX = \alpha$ is a conformal Lagrangian immersion, with Lagrangian angle map β . Thus we obtain the following

Theorem 1. *Let $\Omega \subset \mathbb{C}$ be a simply connected domain. For any conformal Lagrangian immersion $X : \Omega \rightarrow \mathbb{C}^2$, there exist smooth functions $\beta : \Omega \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ and $\phi = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix} : \Omega \rightarrow \mathbb{C}^2 \setminus \{0\}$, determined by (5) and then ϕ is a solution of the Dirac equation (8). Conversely any never vanishing solution of (8) gives rise to a conformal Lagrangian immersion obtained by integrating (5).*

Remark that the case where ϕ vanishes on isolated points corresponds to weakly conformal immersions. All this construction can actually be understood in terms of a decomposition of the complexification of the Hermitian Galilee group of \mathbb{C}^2 , $U(2) \ltimes \mathbb{C}^2$ by an order fourth automorphism (see [HR] for details).

It is tempting to compare this result with the spinorial Weierstrass representation due to B. G. Konopelchenko [Ko] of surfaces in \mathbb{R}^3 (see also [KoT1, KoT2], [B1, B2], [KuS], [T1, T2]). Let $p : \Omega \rightarrow \mathbb{R}$ be a smooth function and $\phi = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix} : \Omega \rightarrow \mathbb{C}^2 \setminus \{0\}$ be a solution of the Dirac equation

$$\mathcal{D}\phi = \begin{pmatrix} p & 0 \\ 0 & p \end{pmatrix} \phi. \quad (9)$$

Then the following 1-form

$$\eta := \operatorname{Re} \begin{pmatrix} s_1^2 dz - \overline{s_2}^2 d\bar{z} \\ -i(s_1^2 dz - \overline{s_2}^2 d\bar{z}) \\ s_1 s_2 dz + \overline{s_1 s_2} d\bar{z} \end{pmatrix} \quad (10)$$

is closed and any solution $Y : \Omega \rightarrow \mathbb{R}^3$ of the equation $dY = \eta$ is a conformal immersion. Moreover the mean curvature of this surface satisfies

$$2p = H(|s_1|^2 + |s_2|^2)$$

and the pull-back metric is $(|s_1|^2 + |s_2|^2)^2 dz d\bar{z}$.

The similarity between the two algorithms is striking but not total, since the potentials $\begin{pmatrix} p & 0 \\ 0 & p \end{pmatrix}$ and $\begin{pmatrix} \overline{U} & 0 \\ 0 & U \end{pmatrix}$ generally differ. For an arbitrary function $U : \Omega \rightarrow \mathbb{C}$ and for a solution ϕ of

$$\mathcal{D}\phi = \begin{pmatrix} \overline{U} & 0 \\ 0 & U \end{pmatrix} \phi,$$

the relation (5), which gives rise to a map into \mathbb{C}^2 , makes sense only if U has the form $U = \frac{1}{2} \frac{\partial \beta}{\partial z}$, with β real valued. And the Konopelchenko ansatz integrates only if U is real. Thus there is an intersection case, where U is both real valued and

of the form $U = \frac{1}{2} \frac{\partial \beta}{\partial z}$, which is realized if and only if β is a real valued function of the variable x . An interesting subcase is when $\beta(x, y) = 4x \Leftrightarrow U = p = 1$. The corresponding surfaces in \mathbb{R}^3 have been studied by J. Richter [R] in his thesis where there are named *Dirac surfaces*. Another intrinsic difference between the two representations becomes obvious at the global level: in Konopelchenko’s case the quantities s_1, s_2 are spinors and the potential p is a density, while in the Lagrangian case they are all 1-forms (though with a similar sign twist).

2. Formulation using quaternions

We identify \mathbb{C}^2 with the set of quaternions \mathbb{H} using the real vector space isomorphism

$$\begin{aligned} \Phi : \quad \mathbb{C}^2 &\longrightarrow \mathbb{H} \\ z = \begin{pmatrix} z^1 \\ z^2 \end{pmatrix} &\longmapsto \tau(z^1 + jz^2)\tau^{-1}, \end{aligned}$$

where $\tau := \frac{\sqrt{2}}{2}(i + j)$ and $\mathbb{C} = \mathbb{R} + i\mathbb{R} \subset \mathbb{R} + i\mathbb{R} + j\mathbb{R} + k\mathbb{R} = \mathbb{H}$. Notice that $\Phi(\epsilon_1) = 1$ and $\Phi(\epsilon_2) = i$. Similarly we recall the field isomorphism already used in the previous section between $\mathbb{R}_+.SU(2)$ and \mathbb{H} ,

$$\begin{aligned} \mathcal{H} : \quad \mathbb{R}_+.SU(2) &\longrightarrow \mathbb{H} \\ \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} &\longmapsto \tau(a + jb)\tau^{-1}. \end{aligned}$$

Then a short computation shows that $\forall e^{i\theta} \in S^1 \subset \mathbb{C}, \forall R \in \mathbb{R}_+.SU(2)$ and $\forall z \in \mathbb{C}^2$,

$$\Phi(e^{i\theta} Rz) = \mathcal{H}(R)\Phi(z)e^{j\theta}. \tag{11}$$

Thus, if $X : \Omega \longrightarrow \mathbb{C}^2$ and we denote $dX = e^{(f+i\beta)/2} (g(\epsilon_1)dx + g(\epsilon_2)dy)$,

$$d(\Phi \circ X) = \mathcal{H} \left(e^{f/2} g \right) \left(\Phi(\epsilon_1)e^{j\beta/2} dx + \Phi(\epsilon_2)e^{j\beta/2} dy \right) = \mathcal{H} \left(e^{f/2} g \right) dz e^{j\beta/2},$$

where $dz := dx + idy$ is viewed as \mathbb{H} -valued². In the remainder of this section, we shall abuse notations and denote $X \simeq \Phi \circ X$ (X is then a map into \mathbb{H}) and we also set $h := \mathcal{H} (e^{f/2} g)$. Moreover in our computations, we shall assume that $\Omega \subset \mathbb{C} \subset \mathbb{H}$. Thus we define the Cauchy-Riemann operators $\partial z \setminus \partial, \partial \bar{z} \setminus \partial, \partial/\partial z$ and $\partial/\partial \bar{z}$, such that

$$dh = (\partial h/\partial z) dz + (\partial h/\partial \bar{z}) d\bar{z} = dz (\partial z \setminus \partial h) + d\bar{z} (\partial \bar{z} \setminus \partial h).$$

² The quaternionic notation may mislead the Reader into viewing $d(\Phi \circ X)$ as a (1,0)-form, since no $d\bar{z}$ term is present. That notion however is not valid, and we might introduce $d\bar{z}$ using the property $dz j = j d\bar{z}$.

Hence the compatibility condition for a solution X of $dX = hdz e^{j\beta/2}$ to exist is

$$\begin{aligned} 0 &= ((\partial h/\partial z) dz + (\partial h/\partial \bar{z}) d\bar{z}) \wedge dz e^{j\beta/2} - hdz \wedge d\beta \frac{j}{2} e^{j\beta/2} \\ &= \left((\partial h/\partial \bar{z}) - h \frac{\partial \beta}{\partial \bar{z}} \frac{j}{2} \right) d\bar{z} \wedge dz e^{j\beta/2}. \end{aligned} \quad (12)$$

(We shall constantly use the fact that if $u \in \mathbb{C} \subset \mathbb{H}$, $ju = \bar{u}j$ and $ku = \bar{u}k$. Here this is responsible for the signs in the formula, since $d\bar{z} \wedge dz = 2idx \wedge dy$.) Hence the compatibility condition writes

$$(\partial h/\partial \bar{z}) = h \frac{\partial \beta}{\partial \bar{z}} \frac{j}{2}. \quad (13)$$

If we let $h = s_1 + js_2$ and substitute in this equation, we see that s_1, s_2 are solutions of the system (7) or (8).

2.1. Hamiltonian stationary Lagrangian immersions

As proven in [HR], Hamiltonian stationary Lagrangian immersions are characterized in this framework by the additional condition that β is a harmonic function. Thus they may be constructed by first picking up some harmonic function β and second solving Equation (13), where $h : \Omega \rightarrow \mathbb{H}$ is the unknown function. It is then clear that the set of solutions of this equation is a quaternionic vector space (\mathbb{H} acting on the left).

Let us focus (as in [HR]) on the toric solutions. Since any torus is conformally equivalent to some \mathbb{C}/Γ , where $\Gamma := v_1\mathbb{Z} + v_2\mathbb{Z}$ is a lattice in \mathbb{C} , it amounts to looking for Γ -periodic Hamiltonian stationary Lagrangian immersions $X : \mathbb{C} \rightarrow \mathbb{H}$. Setting

$$dX = hdz e^{j\beta/2},$$

we are led to look for (a priori) 2Γ -periodic maps $h : \mathbb{C} \rightarrow \mathbb{H}$ and Γ -periodic maps $\beta : \mathbb{C} \rightarrow \mathbb{R}/2\pi\mathbb{Z}$, such that $he^{j\beta/2}$ is Γ -periodic, β is harmonic and h is a solution of (13). The only such β 's are of the form $\beta(z) = 2\pi\langle \beta_0, z - z_0 \rangle = \pi(\overline{\beta_0}(z - z_0) + \beta_0(\bar{z} - \bar{z}_0))$, with $\beta_0 \in \Gamma^*$, where Γ^* is the dual lattice to Γ . Without loss of generality we shall assume that $z_0 = 0$. The 2Γ -periodic maps $h : \mathbb{C} \rightarrow \mathbb{H}$ are of the form

$$h = \sum_{\gamma \in \frac{1}{2}\Gamma^*} \hat{h}_\gamma e^{i2\pi\langle \gamma, z \rangle},$$

where \hat{h}_γ are unique Fourier coefficients³ in \mathbb{H} . Now the equation (13) is written

³ Notice that we do not need here reality conditions on the Fourier coefficients \hat{h}_γ . A way to convince oneself that any 2Γ -periodic function $f : \mathbb{C} \rightarrow \mathbb{H}$ has such a unique Fourier decomposition is to set $f = f_1 + jf_2$, where f_1 and f_2 are complex valued and to Fourier decompose f_1 and f_2 .

as

$$\sum_{\gamma \in \frac{1}{2}\Gamma^*} \hat{h}_\gamma i\gamma e^{i2\pi\langle \gamma, z \rangle} = \sum_{\gamma \in \frac{1}{2}\Gamma^*} \hat{h}_{-\gamma} \frac{j\beta_0}{2} e^{i2\pi\langle \gamma, z \rangle},$$

which is satisfied if and only if

$$\hat{h}_\gamma = \hat{h}_{-\gamma} \frac{\beta_0 \gamma}{2|\gamma|^2} k, \quad \forall \gamma \in \frac{1}{2}\Gamma^*. \tag{14}$$

The relation (14) implies $\hat{h}_\gamma = \hat{h}_\gamma \frac{|\beta_0|^2}{4|\gamma|^2}$. Hence all \hat{h}_γ 's vanish except when $|\gamma| = \frac{|\beta_0|}{2}$, and then $\frac{\beta_0 \gamma}{2|\gamma|^2} k = \frac{2\gamma}{\beta_0} k$. Conversely, as shown in [HR], the map h yields after integration a Γ -periodic immersion if and only if the γ 's for which \hat{h}_γ does not vanish belong to

$$\Gamma_{\beta_0}^* := \left\{ \gamma \in \frac{\beta_0}{2} + \Gamma^*; |\gamma| = \frac{|\beta_0|}{2}, \gamma^2 \neq \frac{\beta_0^2}{4} \right\},$$

and the relation (14) is true. We can describe the solutions by considering a subset containing half of the relevant frequencies γ

$$\Gamma_{\beta_0,+}^* := \{ \gamma \in \Gamma_{\beta_0}^* / \text{Im}(\gamma\beta_0^{-1}) > 0 \},$$

and then, thanks to (14),

$$\begin{aligned} dX &= \sum_{\gamma \in \Gamma_{\beta_0,+}^*} \hat{h}_\gamma \left(e^{i2\pi\langle \gamma, z \rangle} - \frac{2\gamma}{\beta_0} k e^{-i2\pi\langle \gamma, z \rangle} \right) dz e^{j\pi\langle \beta_0, z \rangle} \\ &= \sum_{\gamma \in \Gamma_{\beta_0,+}^*} \hat{h}_\gamma e^{i2\pi\langle \gamma, z \rangle} \left(1 - \frac{2\gamma}{\beta_0} k \right) dz e^{j\pi\langle \beta_0, z \rangle}. \end{aligned}$$

We can integrate explicitly this equation and we obtain

$$X(z) = X_0 + \sum_{\gamma \in \Gamma_{\beta_0,+}^*} \hat{h}_\gamma X_\gamma(z),$$

where $X_0, \hat{h}_\gamma \in \mathbb{H}$ are constants and

$$X_\gamma(z) = e^{i2\pi\langle \gamma, z \rangle} \frac{\beta_0 + 2\gamma k}{2\pi \text{Im}(\gamma\beta_0)} e^{j\pi\langle \beta_0, z \rangle}. \tag{15}$$

Hence, given β_0 , the set of doubly periodic Hamiltonian stationary Lagrangian weakly conformal maps having a Lagrangian angle function $2\pi\langle \beta_0, z \rangle$ is a quaternionic vector space of dimension $1 + \text{Card}(\Gamma_{\beta_0,+}^*)$ over \mathbb{H} .

3. Construction of immersed Hamiltonian stationary Lagrangian Klein bottles

We depict an abstract Klein bottle \mathcal{K} as the complex plane \mathbb{C} quotiented by the following (renormalized) group action: $z \mapsto z + i\tau$ and $z \mapsto \bar{z} + 1$ where τ is a real number. Iterating the second relation, we get $z \mapsto z + 2$, hence the torus $\mathbf{T} = \mathbb{C}/\Gamma$, where $\Gamma = 2\mathbb{Z} \oplus i\tau\mathbb{Z}$, is a rectangular orientable double cover of \mathcal{K} . We can now use the formalism in the previous section and characterize the immersed Klein bottles as giving rise to particular cases of immersed tori.

Theorem 2. *There exist Lagrangian Hamiltonian stationary Klein bottles; they are never embedded.*

The proof proceeds in three steps.

Step 1: The Lagrangian angle.

The dual lattice Γ^* is $\frac{1}{2}\mathbb{Z} \oplus \frac{i}{\tau}\mathbb{Z}$, and β_0 belongs to Γ^* so $\beta_0 = \frac{m}{2} + i\frac{n}{\tau}$ for some integers m, n . Since $z \mapsto \bar{z} + 1$ reverses orientation of the tangent plane, we need $\beta(\bar{z} + 1) \equiv \beta(z) + \pi \pmod{2\pi}$.

$$\begin{aligned} \beta(\bar{z} + 1) &= 2\pi\langle \beta_0, \bar{z} + 1 \rangle = \pi \left(m(x + 1) - \frac{2n}{\tau}y \right) \\ &= \beta(z) + m\pi - \frac{4n\pi y}{\tau} \end{aligned}$$

which imposes $n = 0$ and m odd. Finally $\beta(z) = m\pi x$.

Step 2: The basis vectors.

Take $\gamma = \frac{a\tau + i4b}{4\tau} \in \Gamma_{\beta_0,+}^*$ (recall that $\Gamma_{\beta_0,+}^* \subset \frac{\beta_0}{2} + \Gamma^*$ so a is odd, b is a positive integer) and $|\gamma| = |\frac{\beta_0}{2}|$ reads

$$(a^2 - m^2)\tau^2 + 16b^2 = 0. \tag{16}$$

We associate two linked frequencies γ and $\gamma' = \bar{\gamma}$ to write $\hat{h}_\gamma X_\gamma + \hat{h}_{\bar{\gamma}} X_{\bar{\gamma}} =: \hat{h}_\gamma Y_\gamma$, where

$$\begin{aligned} Y_\gamma(z) &= X_\gamma(z) + i^{m+a} \frac{a\tau + 4bi}{m\tau} X_{\gamma'} \\ &= \frac{1}{2\pi bm} \left(m\tau e^{\frac{i\pi}{2}(ax + \frac{4by}{\tau})} + (a\tau + 4bi)ke^{-\frac{i\pi}{2}(ax + \frac{4by}{\tau})} \right. \\ &\quad \left. - i^{m+a} \frac{a\tau + 4bi}{m\tau} \left(m\tau e^{\frac{i\pi}{2}(ax - \frac{4by}{\tau})} + (a\tau - 4bi)ke^{-\frac{i\pi}{2}(ax - \frac{4by}{\tau})} \right) \right) e^{j\pi\langle \beta_0, z \rangle} \\ &= \frac{1}{2\pi bm} \left(m\tau e^{\frac{i\pi}{2}(ax + \frac{4by}{\tau})} + (a\tau + 4bi)ke^{-\frac{i\pi}{2}(ax + \frac{4by}{\tau})} \right) \end{aligned}$$

$$\begin{aligned}
& -i^{m+a} \left((a\tau + 4bi)e^{\frac{i\pi}{2}(ax - \frac{4by}{\tau})} + m\tau k e^{-\frac{i\pi}{2}(ax - \frac{4by}{\tau})} \right) e^{j\pi \langle \beta_0, z \rangle} \\
&= \frac{e^{\frac{i\pi ax}{2}}}{2\pi bm} \left(e^{\frac{i2\pi by}{\tau}} (m\tau + (a\tau + 4bi)k) \right. \\
&\quad \left. - i^{m+a} e^{-\frac{i2\pi by}{\tau}} (m\tau - (a\tau + 4bi)k) \right) e^{\frac{j\pi mx}{2}} \\
&= \frac{1}{2\pi bm} \left(e^{\frac{i2\pi by}{\tau}} Y'(x) + e^{-\frac{i2\pi by}{\tau}} Y''(x) \right)
\end{aligned}$$

with

$$\begin{aligned}
Y'(x) &= e^{\frac{i\pi ax}{2}} (m\tau + (a\tau + 4bi)k) e^{\frac{j\pi mx}{2}} \\
&= e^{\frac{i\pi ax}{2}} (m\tau + (a\tau + 4bi)k) \frac{e^{\frac{i\pi mx}{2}}(1-k) + e^{-\frac{i\pi mx}{2}}(1+k)}{2} \\
&= \frac{e^{\frac{i\pi}{2}(a+m)x}}{2} ((m-a)\tau - 4bi)(1-k) \\
&\quad + \frac{e^{\frac{i\pi}{2}(a-m)x}}{2} ((m+a)\tau + 4bi)(1+k).
\end{aligned}$$

Similarly

$$\begin{aligned}
Y''(x) &= i^{m+a} \left(\frac{e^{\frac{i\pi}{2}(a+m)x}}{2} ((m-a)\tau - 4bi)(1-k) \right. \\
&\quad \left. - \frac{e^{\frac{i\pi}{2}(a-m)x}}{2} ((m+a)\tau + 4bi)(1+k) \right).
\end{aligned}$$

Finally

$$\begin{aligned}
Y_\gamma(z) &= \frac{1}{4\pi bm} \left(\left(e^{\frac{i2\pi by}{\tau}} + i^{m+a} e^{-\frac{i2\pi by}{\tau}} \right) e^{\frac{i\pi}{2}(a+m)x} ((m-a)\tau - 4bi)(1-k) \right. \\
&\quad \left. + \left(e^{\frac{i2\pi by}{\tau}} - i^{m+a} e^{-\frac{i2\pi by}{\tau}} \right) e^{\frac{i\pi}{2}(a+m)x} ((m+a)\tau + 4bi)(1+k) \right).
\end{aligned}$$

If $m + a \equiv 0 \pmod{4}$,

$$\begin{aligned}
Y_\gamma &= \frac{1}{2\pi bm} \left(\cos \frac{2\pi by}{\tau} e^{\frac{i\pi}{2}(a+m)x} ((m-a)\tau - 4bi)(1-k) \right. \\
&\quad \left. + i \sin \frac{2\pi by}{\tau} e^{\frac{i\pi}{2}(a-m)x} ((m+a)\tau + 4bi)(1+k) \right),
\end{aligned}$$

while $m + a \equiv 2 \pmod 4$ gives a similar expression for Y_γ where only \cos and $i \sin$ are exchanged. We may sum up saying that Y_γ has the form

$$Z_{p,q,b}(x, y) = \cos \frac{2\pi by}{\tau} e^{2ip\pi x} C_1 + i \sin \frac{2\pi by}{\tau} e^{iq\pi x} C_2,$$

where

- if $m + a \equiv 0 \pmod 4$, $(p, q) = (\frac{a+m}{2}, \frac{a-m}{2})$ and

$$\begin{cases} C_1 = -\frac{q\tau + i2b}{\pi bm}(1 - k) \\ C_2 = \frac{p\tau + i2b}{\pi bm}(1 + k) \end{cases}$$

- if $m + a \equiv 2 \pmod 4$, $(p, q) = (\frac{a-m}{2}, \frac{a+m}{2})$ and

$$\begin{cases} C_1 = \frac{q\tau + i2b}{\pi bm}(1 + k) \\ C_2 = -\frac{p\tau + i2b}{\pi bm}(1 - k) \end{cases}.$$

Notice that in both cases $p \equiv 0 \pmod 2$ and $q \equiv 1 \pmod 2$. We conclude with the following property, obvious on the form above

$$Z_{p,q,b}(x + \frac{k}{2p}, \ell\tau/2) = (-1)^{k+\ell b} Z_{p,q,b}(x, 0).$$

Step 3: Self-intersections.

Consider a Klein bottle, hence a \mathbb{H} -linear combination of terms Z_{p_i, q_i, b_i} . The condition (16) implies

$$b_i^2 p_j q_j = b_j^2 p_i q_i. \tag{17}$$

Assume some optimal vertical periodicity; in particular the b_i 's are not all even (otherwise we change the lattice Γ). Now

$$Z_{p_i, q_i, b_i}(x + \frac{1}{2}, \ell_i\tau/2) = (-1)^{p_i + \ell_i b_i} Z_{p_i, q_i, b_i}(x, 0).$$

We claim that there exist an integer ℓ such that

$$p_i + \ell b_i \equiv 0 \pmod 2. \tag{18}$$

Assume – up to reindexing – that $b_1 \equiv 1$ (all equivalences are taken mod 2) then $\ell \equiv p_1$ works. If for some i , $b_i \equiv 1$ then (17) implies $p_i \equiv p_1$ and equation (18) holds. If on the contrary $b_i \equiv 0$, then $p_i \equiv 0$ necessarily, and (18) holds again.

We conclude that $Z_{p_i, q_i, b_i}(x + \frac{1}{2}, \ell\tau/2) = Z_{p_i, q_i, b_i}(x, 0)$ for any i ; the same holds for any linear combination. So the Klein bottle is not embedded. Notice that one may construct Klein bottles having only that self-intersection, and no other, but not on a square lattice.

An example. Taking $\tau = 1$ and $a = 3$, $b = 1$, $m = 5$, we obtain:

$$Y_\gamma = \frac{1 - i2}{5\pi} \left(\cos 2\pi y e^{i4\pi x} (1 - k) - \sin 2\pi y e^{-i\pi x} (1 + k) \right).$$

References

- [B1] A.I. Bobenko, *Surfaces in terms of 2 by 2 matrices. Old and new integrable systems*, in Harmonic Maps and Integrable Systems, Vieweg, Aspects of Mathematics **E23** (1994), p. 83-127.
- [B2] A.I. Bobenko, *Exploring Surfaces through Methods from the Theory of Integrable Systems. Lectures on the Bonnet Problem*, Lectures given at the School on Differential Geometry (April 1999), ICTP Trieste.
- [CM] B.-Y. Chen, J.-M. Morvan, Deformations of isotropic submanifolds in Kähler manifolds, *J. of Geometry and Physics* **13** (1994), 79-104.
- [CU] I. Castro, F. Urbano, Examples of unstable Hamiltonian-minimal Lagrangian tori in \mathbb{C}^2 , *Compositio Mathematica* **111** (1998), 1-14.
- [HL] R. Harvey, H. B. Lawson, Calibrated geometries, *Acta Mathematica* **148** (1982), 47-157.
- [HR] F. Hélein, P. Romon, Hamiltonian stationary Lagrangian surfaces in \mathbb{C}^2 , preprint CMLA 1999, submitted to *Comm. Analysis Geo.*
- [Ke] K. Kenmotsu, Weierstrass formula for surfaces, *Math. Ann.* **245** (1986), 89-99.
- [Ko] B. G. Konopelchenko, Induced surfaces and their integrable dynamics, *Studies in Appl. Math.* **96** No.1 (1996), 9-51.
- [KoT1] B. G. Konopelchenko, I. Taimanov, Constant curvature surfaces via integrable dynamical system, *J. Phys. A, Math. Gen.* **29** No.6 (1996), 1261-2165.
- [KoT2] B. G. Konopelchenko, I. Taimanov, Generalized Weierstrass formulae, soliton equations and Willmore surfaces I. Tori of revolution and the mKdV equation, preprint.
- [KuS] R. Kusner, N. Schmitt, The spinor representation of minimal surfaces, GANG preprint (1996).
- [O1] Y.G. Oh, Second variation and stabilities of minimal Lagrangian submanifolds in Kähler manifolds, *Invent. Math.* **101** (1990), 501-519.
- [O2] Y.G. Oh, Volume minimization of Lagrangian submanifolds under Hamiltonian deformations, *Math. Z.* **212** (1993), 175-192.
- [R] J. Richter, Conformal Maps of a Riemannian Surface into the Space of Quaternions, PhD thesis, Technische Universität Berlin, 1997.
- [SW] R. Schoen, J. Wolfson, *Minimizing volume among Lagrangian submanifolds*, in Differential equations: La Pietra 1996 (Florence), 181-199, Proc. Sympos. Pure Math., 65, Amer. Math. Soc., Providence, RI (1999).
- [T1] I. A. Taimanov, The Weierstrass representation of closed surfaces in \mathbb{R}^3 , *Funktsional. Anal. i Prilozhen.* **32** no. 4 (1998), 49-62; translation in *Funct. Anal. Appl.* **32** no. 4 (1998), 258-267.
- [T2] I. A. Taimanov, The Weierstrass representation of spheres in \mathbb{R}^3 , the Willmore number and soliton sphere, preprint 302 SFB 288 (1997) and *Tr. Mat. Inst. Steklova* **225** (1999), Solitony Geom. Topol. na Perekrest., 339-361.
- [V] C. Viterbo, Metric and isoperimetric problems in symplectic geometry, *J. Amer. Math. Soc.* **13** no. 2 (2000), 411-431 (electronic).
- [W] J. Wolfson, Minimal Lagrangian diffeomorphisms and the Monge-Ampère equations, *J. Differential Geometry* **46** (1997), 335-373.

Frédéric Hélein
Institut Universitaire de France
CMLA, ENS de Cachan
61 avenue du Président Wilson
F-94235 Cachan Cedex
France
e-mail: helein@cmla.ens-cachan.fr

Pascal Romon
CMLA, ENS de Cachan
61 avenue du Président Wilson
F-94235 Cachan Cedex
France
and
Université de Marne-la-Vallée
5, boulevard Descartes
Champs sur Marne
F-77454 Marne-la-Vallée Cedex 2
France
e-mail: romon@cmla.ens-cachan.fr

(Received: January 25, 2000)