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Abstract

We investigate the problem of secure transmission over a two-user multi-input multi-output (MIMO) X-channel with noiseless local feedback and delayed channel state information (CSI) available at transmitters. The transmitters are equipped with M antennas each, and the receivers are equipped with N antennas each. For this model, we characterize the optimal sum secure degrees of freedom (SDoF) region. We show that, in presence of local feedback and delayed CSI, the sum SDoF region of the MIMO X-channel is *same* as the SDoF region of a two-user MIMO BC with $2M$ antennas at the transmitter and N antennas at each receiver. This result shows that, upon availability of feedback and delayed CSI, there is no performance loss in sum SDoF due to the distributed nature of the transmitters. Next, we show that this result also holds if only *global* feedback is conveyed to the transmitters. We also study the case in which only local feedback is provided to the transmitters, i.e., without CSI, and derive a lower bound on the sum SDoF for this model. Furthermore, we specialize our results to the case in which there are no security constraints. In particular, similar to the setting with security constraints, we show that the optimal sum degrees of freedom (sum DoF) region of the (M, M, N, N)-MIMO X-channel is same of

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the DoF region of a two-user MIMO BC with $2M$ antennas at the transmitter and N antennas at each receiver. We illustrate our results with some numerical examples.

I. Introduction

In modern era, there is a growing requirement for high data rates in wireless networks, in which multiple users communicate with each other over a shared medium. The information transmission by multiple users on a common channel raises an important issue of interference in networks. In existing literature on multi-user channels, such as [1], several interference alignment techniques have been proposed. Most of these techniques rely on the availability of perfect channel state information (CSI) at the transmitting nodes. However, because the wireless medium is characterized by its inherent randomness, such an assumption is rather idealistic and is difficult to obtain. In [2], Maddah-Ali and Tse study a multi-input single-output (MISO) broadcast channel with delayed CSI available at the transmitter, from a degrees of freedom (DoF) perspective. They show that delayed (or stale) CSI is useful, in the sense that it increases the DoF region in comparison to the same MISO setting without any CSI at the transmitter. The delayed CSI model of [2] has been extended to study a variety of models. These include the two-user MIMO BC [3], the three-user MIMO BC [3], [4], the two-user MIMO interference channel [5], [6], and the K-user single-input single-output (SISO) interference and X-channels [7].

In [8], Jafar and Shamai introduced a two-user X-channel model. The two-user X-channel consists of two transmitters and two receivers, with each transmitter sending two independent messages to both receivers. For this model, the authors establish bounds on the DoF region under the assumption of full CSI. In [9], Maleki *et. al.* study a two-user single-input single-output (SISO) X-channel with local feedback provided to the transmitters. They establish a lower bound on the allowed sum degrees of freedom (DoF). For MIMO X-channels, the setting with no CSI at the transmitters is studied in [10]; the setting with delayed CSI is studied [11]; and the setting with delayed CSI and noiseless output feedback is studied in [12], all from a degrees of freedom viewpoint. In all these works, a symmetric network topology is assumed, with each transmitter being equipped with M antennas and each receiver equipped with N antennas. In [11], it is assumed that each receiver knows the CSI of its own channel and also the past CSI of the channel to the other receiver. Also, the past CSI available at each receiver is provided to the corresponding transmitter over a noiseless link. For this model, the authors establish a lower bound on the total DoF. In [12], Tandon *et. al.* study a model which is similar to the one that is investigated in [11], but with additional noiseless local output feedback from the receivers to the transmitters. In particular, they show that the total DoF of this two-user MIMO X-channel with output feedback and delayed CSI is

the same as the sum DoF of a two-user broadcast channel with $2M$ transmit antennas, and N antennas at each receiver. For this model, the availability at each transmitter of output feedback together with delayed CSI help it reconstruct the information transmitted by the other transmitter. The reader may refer to [13]–[15] for some other related works.

In his seminal work [16], Wyner introduced a basic information-theoretic model to study security by exploiting the physical layer attributes of the channel. The model consists of a sender which transmits information to a legitimate receiver; and this information is meant to be kept secret from an external wiretapper that overhears the transmission. Wyner's basic setup has been extended to study the secrecy capacity of various multiuser channels, such as the broadcast channel [17], [18], the multi-antennas wiretap channel [19]–[22], the multiple access wiretap channel [23]–[27], the relay channel [28]–[30], the interference channel [31], [32] and X networks [33] (the reader may also refer to [34] for a review of many other related contributions). In [35], the authors study a K-user interference channel with security constraints, from a secure degrees of freedom (SDoF) perspective. Similar to the setting with no security constraints, the SDoF captures the way the spatial multiplexing gain, or secrecy capacity prelog or degrees of freedom, scales asymptotically with the logarithm of the signal-to-noise ratio (SNR). In [36], the authors study a K-user Gaussian multiaccess channel with an external eavesdropper, and derive a lower bound on the allowed sum SDoF under the assumption of perfect instantaneous CSI available at the transmitter and receivers. In [37], Yang *et al.* study secure transmission over a two-user MIMO BC with delayed CSI available at the transmitter. They provide an exact characterization of the SDoF region. The coding scheme of [37] can be seen as an appropriate extension of Maddah Ali-Tse scheme [2] to accommodate additional noise injection that accounts for security constraints.

In this paper, we consider a two-user MIMO X-channel in which each transmitter is equipped with M antennas, and each receiver is equipped with N antennas. Each transmitter sends information messages to both receivers. More precisely, Transmitter 1 wants to transmit messages W_{11} and W_{12} to Receiver 1 and Receiver 2, respectively. Similarly, Transmitter 2 wants to transmit messages W_{21} and W_{22} to Receiver 1 and Receiver 2, respectively. The transmission is subject to fast fading effects. Also, we make two assumptions, namely 1) each receiver is assumed to have perfect instantaneous knowledge of its channel coefficients (i.e., CSIR) as well as knowledge of the other receiver's channel coefficients with one unit delay, and 2) there is a noiseless output and CSI feedback from Receiver i, $i = 1, 2$, to Transmitter i. We will refer to such output feedback as being *local*, by opposition to *global* feedback which corresponds to each receiver feeding back its output to both transmitters. The considered model is shown in Figure 1. Furthermore, the messages that are destined to each receiver are meant to be kept

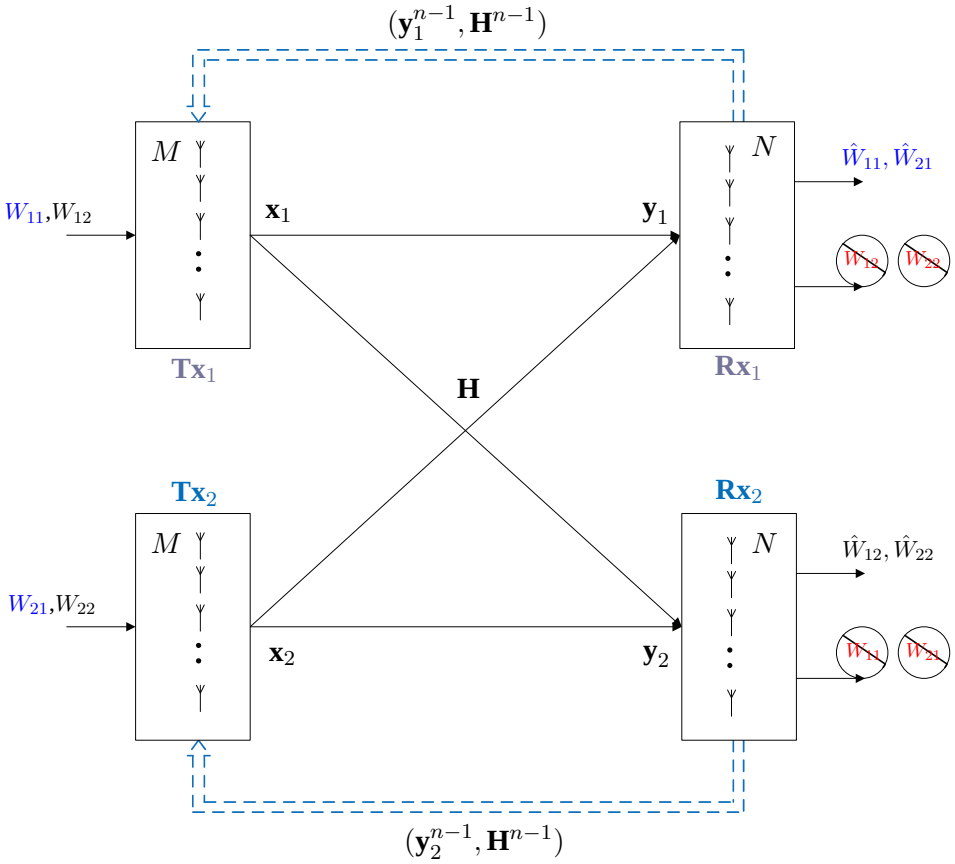

Fig. 1. MIMO X-channel with local feedback and delayed CSI with security constraints.

secret from the other receiver. That is, Receiver 2 wants to capture the pair (W_{11}, W_{21}) of messages that are intended for Receiver 1; and so, in addition to that it is a legitimate receiver of the pair (W_{12}, W_{22}), it also acts as an eavesdropper on the MIMO multiaccess channel to Receiver 1. Similarly, Receiver 1 wants to capture the pair (W_{12}, W_{22}) of messages that are intended for Receiver 2; and so, in addition to that it is a legitimate receiver of the pair (W_{11}, W_{21}), it also acts as an eavesdropper on the MIMO multiaccess channel to Receiver 2. The model that we study can be seen as being that of [12] but with security constraints imposed on the transmitted messages. We concentrate on the case of perfect secrecy, and focus on asymptotic behaviors, captured by the allowed secure degrees of freedom over this network model.

A. Contributions

The main contributions of this paper can be summarized as follows. First, we characterize the sum SDoF region of the two-user (M, M, N, N)–MIMO X-channel with local feedback and delayed CSI shown in Figure 1. We show that the sum SDoF region of this model is same as the SDoF region of a two-user MIMO broadcast channel with $2M$ transmit antennas and N antennas at each receiver in which delayed CSI is provided to the transmitter. This result shows that, for symmetric antennas configurations, the distributed nature of the transmitters does not cause any loss in terms of sum secure degrees of freedom. The result also emphasizes the usefulness of local output feedback when used in conjunction with delayed CSI in securing the transmission of messages in MIMO-X channels, by opposition to in MIMO broadcast channels. That is, for the two-user MIMO X-channel, not only local output feedback with delayed CSI does increase the DoF region as shown in [12], it also increases the *secure* DoF region of this network model. The coding scheme that we use for the proof of the direct part is based on an appropriate extension of that developed by Yang *et. al.* [37] in the context of secure transmission over a two-user MIMO BC with delayed CSI at the transmitter; and it demonstrates how each transmitter exploits optimally the available output feedback and delayed CSI.

Next, concentrating on the role of output feedback in the absence of CSI at the transmitters from a secrecy degrees of freedom viewpoint, we study two variations of the model of Figure 1. In the first model, the transmitters are completely ignorant of the CSI, but are provided with *global* output feedback. As we mentioned previously, this output feedback is assumed to be noiselessly and is provided by both receivers to both transmitters. In the second model, the transmitters are provided with only local feedback, i.e., the model of Figure 1 but with no delayed CSI at the transmitters.

For the model with global feedback at the transmitters, we show that the sum SDoF region is same as the sum SDoF region of the model with local feedback and delayed CSI available at the transmitters, i.e., the model of Figure 1. In other terms, the lack of CSI at the transmitters does not cause any loss in terms of sum SDoF as long as the transmitters are provided with global output feedback. In this case, each transmitter readily gets the side information or interference that is available at the unintended receiver by means of the global feedback; and, therefore, it can align it with the information that is destined to the intended receiver directly, with no need of any CSI.

For the model in which only local output feedback is provided to the transmitters, we establish an inner bound on the sum SDoF region. This inner bound is in general strictly smaller than that of the model of Figure 1; and, so, although its optimality is shown only in some specific cases, it gives insights

about the loss incurred by the lack of delayed CSI at the transmitters. This loss is caused by the fact that, unlike the coding schemes that we develop for the setting with local output feedback and delayed CSI at the transmitters and that with global feedback at the transmitters, for the model with only local feedback each transmitter can not learn the side information that is available at the unintended receiver and which is pivotal for the alignment of the interferences in such models.

Furthermore, we specialize our results to the case in which there are no security constraints. Similar to the setting with security constraints, we show that the optimal sum degrees of freedom (sum DoF) region of the (M, M, N, N)-MIMO X-channel is same of the DoF region of a two-user MIMO BC with $2M$ antennas at the transmitter and N antennas at each receiver. Finally, we illustrate our results with some numerical examples.

B. Outline and Notation

An outline of the remainder of this paper is as follows. Section II provides a formal description of the channel model that we consider, together with some useful definitions. Section III states the sum SDoF region of the two-user (M, M, N, N)-MIMO X-channel with local feedback and delayed CSI of Figure 1. In section IV, we provide the formal proof of the coding scheme that we use to establish the achievability result. In section V, we study the role of output feedback in the absence of CSI at the transmitters. In Section VI, we specialize the results to the setting with no security constraints; and, in Section VII, we illustrate our results through some numerical examples. Section VIII concludes the paper.

We use the following notations throughout the paper. Boldface upper case letters, e.g., $\mathbf{X}$, denote matrices; boldface lower case letters, e.g., $\mathbf{x}$, denote vectors; and calligraphic letters designate alphabets, i.e., $\mathcal{X}$. For integers $i \leq j$, we use the notation $\mathbf{X}_i^j$ as a shorthand for $(\mathbf{X}_i, \ldots, \mathbf{X}_j)$. The notation $\text{diag}(\{\mathbf{H}[t]\}_t)$ denotes the block diagonal matrix with $\mathbf{H}[t]$ as diagonal elements for all t. The Gaussian distribution with mean μ and variance σ^2 is denoted by $\mathcal{N}(\mu, \sigma^2)$. Finally, throughout the paper, logarithms are taken to base 2, and the complement to unity of a scalar $u \in [0, 1]$ is denoted by $\bar{u}$, i.e., $\bar{u} = 1 - u$.

II. System Model and Definitions

We consider a two-user (M, M, N, N) X-channel, as shown in Figure 1. There are two transmitters and two receivers. Both transmitters send messages to both receivers. Transmitter 1 wants to transmit message $W_{11} \in \mathcal{W}_{11} = \{1, \ldots, 2^{nR_{11}(P)}\}$ to Receiver 1, and message $W_{12} \in \mathcal{W}_{12} = \{1, \ldots, 2^{nR_{12}(P)}\}$ to Receiver 2. Similarly, Transmitter 2 wants to transmit message $W_{21} \in \mathcal{W}_{21} = \{1, \ldots, 2^{nR_{21}(P)}\}$ to Receiver 1, and message $W_{22} \in \mathcal{W}_{22} = \{1, \ldots, 2^{nR_{22}(P)}\}$ to Receiver 2. The messages pair (W_{11}, W_{21})

that is intended to Receiver 1 is meant to be concealed from Receiver 2; and the messages pair (W_{21}, W_{22}) that is intended to Receiver 2 is meant to be concealed from Receiver 1.

We consider a fast fading model, and assume that each receiver knows the perfect instantaneous CSI along with the past CSI of the other receiver. Also, we assume that Receiver i, $i = 1, 2$, feeds back its channel output along with the delayed CSI to Transmitter i. The outputs received at Receiver 1 and Receiver 2 at each time instant are given by

$$\begin{aligned}\mathbf{y}_1[t] &= \mathbf{H}_{11}[t]\mathbf{x}_1[t] + \mathbf{H}_{12}[t]\mathbf{x}_2[t] + \mathbf{z}_1[t] \\ \mathbf{y}_2[t] &= \mathbf{H}_{21}[t]\mathbf{x}_1[t] + \mathbf{H}_{22}[t]\mathbf{x}_2[t] + \mathbf{z}_2[t], \;\; t = 1, \ldots, n\end{aligned} \tag{1}$$

where $\mathbf{x}_i \in \mathbb{C}^M$ is the input vector from Transmitter i, $i = 1, 2$, and $\mathbf{H}_{ji} \in \mathbb{C}^{N \times M}$ is the channel matrix connecting Transmitter i to Receiver j, $j = 1, 2$. We assume arbitrary stationary fading processes, such that $\mathbf{H}_{11}[t]$, $\mathbf{H}_{12}[t]$, $\mathbf{H}_{21}[t]$ and $\mathbf{H}_{22}[t]$ are mutually independent and change independently across time. The noise vectors $\mathbf{z}_j[t] \in \mathbb{C}^N$ are assumed to be independent and identically distributed (i.i.d.) white Gaussian, with $\mathbf{z}_j \sim \mathcal{CN}(\mathbf{0}, \mathbf{I}_N)$ for $j = 1, 2$. Furthermore, we consider average block power constraints on the transmitters inputs, as

$$\sum_{t=1}^{n} \mathbb{E}[\|\mathbf{x}_i[t]\|^2] \leq nP, \qquad \text{for} \;\; i \in \{1, 2\}. \tag{2}$$

For convenience, we let $\mathbf{H}[t] = \begin{bmatrix} \mathbf{H}_{11}[t] & \mathbf{H}_{12}[t] \\ \mathbf{H}_{21}[t] & \mathbf{H}_{22}[t] \end{bmatrix}$ designate the channel state matrix and $\mathbf{H}^{t-1} = \{\mathbf{H}[1], \ldots, \mathbf{H}[t-1]\}$ designate the collection of channel state matrices for the past $(t-1)$ symbols. For convenience, we set $\mathbf{H}^0 = \emptyset$. We assume that, at each time instant t, the channel state matrix $\mathbf{H}[t]$ is full rank almost surely. Also, we denote by $\mathbf{y}_j^{t-1} = \{\mathbf{y}_j[1], \ldots, \mathbf{y}_j[t-1]\}$ the collection of the outputs at Receiver j, $j = 1, 2$, over the past $(t-1)$ symbols. At each time instant t, the past states of the channel $\mathbf{H}^{t-1}$ are known to all terminals. However the instantaneous states $(\mathbf{H}_{11}[t], \mathbf{H}_{21}[t])$ are known only to Receiver 1, and the instantaneous states $(\mathbf{H}_{12}[t], \mathbf{H}_{22}[t])$ are known only to Receiver 2. Furthermore, at each time instant, Receiver 1 feeds back the output vector $\mathbf{y}_1^{t-1}$ to Transmitter 1, and Receiver 2 feeds back the output vector $\mathbf{y}_2^{t-1}$ to Transmitter 2.

Definition 1: A code for the Gaussian (M, M, N, N)–MIMO X-channel with local feedback and delayed CSI consists of two sequences of stochastic encoders at the transmitters,

$$\begin{aligned}\{\phi_{1t} \;\; : \;\; \mathcal{W}_{11} \times \mathcal{W}_{12} \times \mathcal{H}^{t-1} \times \mathcal{Y}_1^{N(t-1)} \longrightarrow \mathcal{X}_1^M\}_{t=1}^n \\ \{\phi_{2t} \;\; : \;\; \mathcal{W}_{21} \times \mathcal{W}_{22} \times \mathcal{H}^{t-1} \times \mathcal{Y}_2^{N(t-1)} \longrightarrow \mathcal{X}_2^M\}_{t=1}^n\end{aligned} \tag{3}$$

where the messages W_{11}, W_{12}, W_{21} and W_{22} are drawn uniformly over the sets $\mathcal{W}_{11}$, $\mathcal{W}_{12}$, $\mathcal{W}_{21}$ and $\mathcal{W}_{22}$, respectively; and four decoding functions at the receivers,

$$\begin{aligned}
\psi_{11} &: \mathcal{Y}_1^{Nn} \times \mathcal{H}^{n-1} \times \mathcal{H}_{11} \times \mathcal{H}_{12} \longrightarrow \hat{\mathcal{W}}_{11} \\
\psi_{21} &: \mathcal{Y}_1^{Nn} \times \mathcal{H}^{n-1} \times \mathcal{H}_{11} \times \mathcal{H}_{12} \longrightarrow \hat{\mathcal{W}}_{21} \\
\psi_{12} &: \mathcal{Y}_2^{Nn} \times \mathcal{H}^{n-1} \times \mathcal{H}_{21} \times \mathcal{H}_{22} \longrightarrow \hat{\mathcal{W}}_{12} \\
\psi_{22} &: \mathcal{Y}_2^{Nn} \times \mathcal{H}^{n-1} \times \mathcal{H}_{21} \times \mathcal{H}_{22} \longrightarrow \hat{\mathcal{W}}_{22}.
\end{aligned} \tag{4}$$

Definition 2: A rate quadruple $(R_{11}(P), R_{12}(P), R_{21}(P), R_{22}(P))$ is said to be achievable if there exists a sequence of codes such that,

$$\lim_{P\to\infty} \limsup_{n\to\infty} \Pr\{\hat{W}_{ij} \neq W_{ij} | W_{ij}\} = 0, \quad \text{for all } (i,j) \in \{1,2\}^2. \tag{5}$$

Definition 3: A SDoF quadruple $(d_{11}, d_{12}, d_{21}, d_{22})$ is said to be achievable if there exists a sequence of codes satisfying the following reliability conditions at both receivers,

$$\begin{aligned}
&\lim_{P\to\infty} \liminf_{n\to\infty} \frac{\log |\mathcal{W}_{ij}(n,P)|}{n \log P} \geq d_{ij}, \quad \text{for all } (i,j) \in \{1,2\}^2 \\
&\lim_{P\to\infty} \limsup_{n\to\infty} \Pr\{\hat{W}_{ij} \neq W_{ij} | W_{ij}\} = 0, \quad \text{for all } (i,j) \in \{1,2\}^2
\end{aligned} \tag{6}$$

as well as the perfect secrecy conditions

$$\begin{aligned}
\lim_{P\to\infty} \limsup_{n\to\infty} \frac{I(W_{12}, W_{22}; \mathbf{y}_1^n, \mathbf{H}^n)}{n \log P} &= 0 \\
\lim_{P\to\infty} \limsup_{n\to\infty} \frac{I(W_{11}, W_{21}; \mathbf{y}_2^n, \mathbf{H}^n)}{n \log P} &= 0.
\end{aligned} \tag{7}$$

Definition 4: We define the sum secure degrees of freedom region of the MIMO X-channel with local feedback and delayed CSI, which we denote by $\mathcal{C}_{\text{SDoF}}^{\text{sum}}$, as the set of all of all pairs $(d_{11}+d_{21}, d_{12}+d_{22})$ for all achievable non-negative quadruples $(d_{11}, d_{21}, d_{12}, d_{22})$. We also define the total (sum) secure degrees of freedom as $\text{SDoF}_{\text{total}}^{\text{d-CSI,F}} = \max_{(d_{11},d_{21},d_{12},d_{22})} d_{11} + d_{21} + d_{12} + d_{22}$.

III. Sum SDoF of (M, M, N, N)–MIMO X-channel with local feedback and delayed CSI

In this section we state our main result on the optimal sum SDoF region of the two-user MIMO X-channel with local feedback and delayed CSI. We illustrate our result by providing few examples which give insights into the proposed coding scheme.

For convenience we define the following quantity that we will use extensively in the sequel. Let, for given non-negative (M, N),

$$d_s(N,N,M) = \begin{cases} 0 & \text{if } \ M \leq N \\ \frac{NM(M-N)}{N^2+M(M-N)} & \text{if } \ N \leq M \leq 2N \\ \frac{2N}{3} & \text{if } \ M \geq 2N \end{cases} \tag{8}$$

The following theorem characterizes the sum SDoF region of the MIMO X-channel with local feedback and delayed CSI.

Theorem 1: The sum SDoF region $\mathcal{C}_{\text{SDoF}}^{\text{sum}}$ of the two-user (M, M, N, N)–MIMO X-channel with local feedback and delayed CSI is given by the set of all non-negative pairs $(d_{11}+d_{21}, d_{12}+d_{22})$ satisfying

$$\begin{aligned} \frac{d_{11}+d_{21}}{d_s(N,N,2M)} + \frac{d_{12}+d_{22}}{\min(2M,2N)} &\leq 1 \\ \frac{d_{11}+d_{21}}{\min(2M,2N)} + \frac{d_{12}+d_{22}}{d_s(N,N,2M)} &\leq 1 \end{aligned} \tag{9}$$

for $2M \geq N$; and $\mathcal{C}_{\text{SDoF}}^{\text{sum}} = \{(0,0)\}$ if $2M \leq N$.

Proof: The converse proof follows by allowing the transmitters to cooperate and then using the outer bound established in [37, Theorem 3] in the context of secure transmission over MIMO broadcast channels with delayed CSI at the transmitter, by taking $2M$ transmit antennas and N antennas at each receiver. Note that Theorem 3 of [37] continues to hold if one provides additional feedback from the receivers to the transmitter. The proof of achievability is given in Section IV. □

Remark 1: In the case in which $2M \geq N$, the sum SDoF region of Theorem 1 is characterized fully by the three corner points $(d_s(N,N,2M), 0)$, $(0, d_s(N,N,2M))$ and

$$(d_{11}+d_{21}, d_{12}+d_{22}) = \begin{cases} \left(\frac{N(2M-N)}{2M}, \frac{N(2M-N)}{2M}\right) & \text{if } \ N \leq 2M \leq 2N \\ \left(\frac{N}{2}, \frac{N}{2}\right) & \text{if } \ 2N \leq 2M \end{cases} \tag{10}$$

Remark 2: The sum SDoF region of Theorem 1 is same as the SDoF region of a two-user MIMO BC in which the transmitter is equipped with $2M$ antennas and each receiver is equipped with N antennas, and delayed CSI is provided to the transmitter [37, Theorem 3]. Therefore, Theorem 1 shows that there is no performance loss in terms of sum SDoF due to the distributed nature of the transmitters in the MIMO X-channel that we consider. Note that, in particular, this implies that, like the setting with no security constraints [12, Theorem 1], the total secure degrees of freedom, defined as in Definition 4 and

Case	$\text{SDoF}_{\text{total}}^{\text{d-CSI,F}}$	$\text{DoF}_{\text{total}}^{\text{d-CSI,F}}$ [12]	$\text{DoF}_{\text{total}}^{\text{n-CSI,nF}}$ [10]
$2M \leq N$	0	$2M$	$2M$
$N \leq 2M \leq 2N$	$\frac{N(2M-N)}{M}$	$\frac{4MN}{2M+N}$	N
$2N \leq 2M$	N	$\frac{4N}{3}$	N

TABLE I

TOTAL SDOF AND TOTAL DOF OF (M, M, N, N)–MIMO X-CHANNELS WITH DIFFERENT DEGREES OF OUTPUT FEEDBACK AND DELAYED CSI.

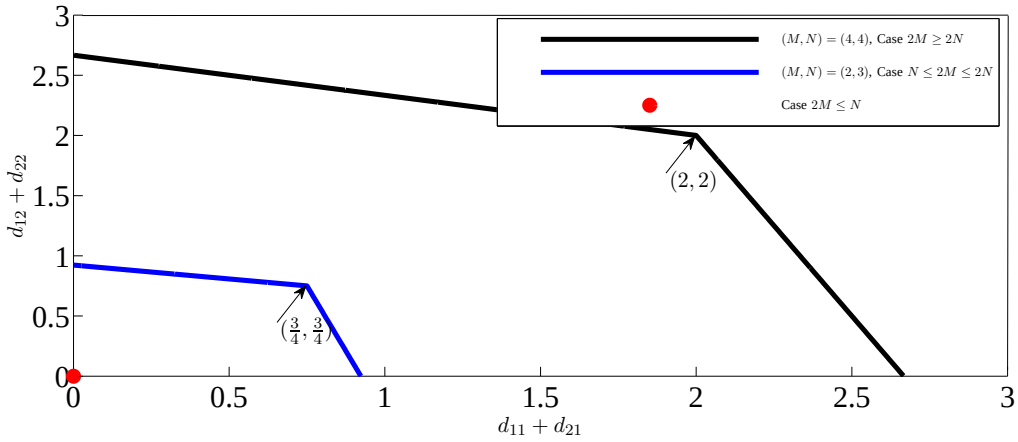

Fig. 2. Sum SDoF region of the (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI, for different antennas configurations.

given by

$$\text{SDoF}_{\text{total}}^{\text{d-CSI,F}} = \begin{cases} 0 & \text{if } \ 2M \leq N \\ \frac{N(2M-N)}{M} & \text{if } \ N \leq 2M \leq N \\ N & \text{if } \ 2M \geq 2N \end{cases} \tag{11}$$

is also preserved upon the availability of output feedback and delayed CSI at the transmitters, although the latters are distributed.

Figure 2 illustrates the optimal sum SDoF of the (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI as given in Theorem 1, for different values of the transmit- and receive antennas. Obviously, secure messages transmission is not possible if, accounting for the antennas available at both transmitters, there are less transmit antennas than receive antennas at each receiver, i.e., $2M \leq N$. Also,

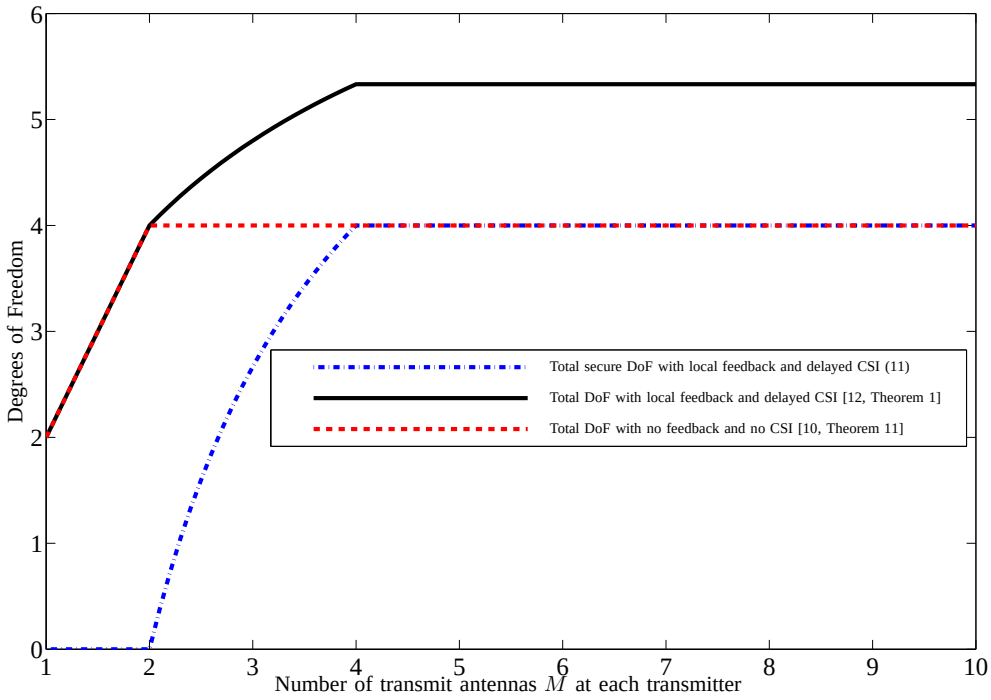

Fig. 3. Total secure degrees of freedom of the (M, M, N, N)-MIMO X-channel as a function of the number M of transmit antennas at each transmitter, for a fixed number $N = 4$ of receive antennas at each receiver.

the sum SDoF region increases with the pair (M, N) if $N \leq 2M \leq 2N$. For a given number N of receiver antennas at each receiver, the sum SDoF region no longer increases with the number of transmit-antennas M at each transmitter as long as $M \geq N$. This shows that, from a sum SDoF perspective, there is no gain from equipping the transmitters with more than N antennas each. A similar behavior is shown in Table III and Figure 3 from a total secure degrees of freedom viewpoint. Table III summarizes the optimal total SDoF of the (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI as given by (11), as well as the total DoF of the (M, M, N, N)–MIMO X-channel without security constraints, with local output feedback and delayed CSI at the transmitters [12, Theorem 1] and with no output feedback and no CSI at the transmitters [10, Theorem 11]. Figure 3 depicts the evolution of the total SDoF (11) as a function of the number of transmit antennas at each transmitter, for an example configuration in which each receiver is equipped with $N = 4$ antennas. It is interesting to note that for the case $M \geq N$ the total SDoF of the MIMO X-channel with local output feedback and delayed CSI is the same as the DoF of the MIMO X-channel with no feedback and no CSI at transmitters. Thus, providing the transmitters with local output feedback and delayed CSI can be interpreted as the price for secrecy in this case.

IV. Proof of Direct Part of Theorem 1

In this section, we provide a description of the coding scheme that we use for the proof of Theorem 1. This coding scheme can be seen as an extension, to the case of non-cooperative or distributed transmitters, of that established by Yang *et al.* [37] in the context of secure transmission over a two-user MIMO BC with delayed CSI provided to the transmitter.

In the case in which $2M \leq N$, every receiver has enough antennas to decode all of the information that is sent by the transmitters; and, so, secure transmission of messages is not possible. In the case in which $2M \geq N$,it is enough to prove that the corner points that are given in Remark 1 are achievable, since the entire region can then be achieved by time-sharing. The achievability of each of the two corner points $(d_s(N, N, 2M), 0)$ follows by the coding scheme of [37, Theorem 1], by having the transmitters sending information messages only to one receiver and the other receiver acting as an eavesdropper. In what follows, we show that the point given by (10) is achievable. We divide the analysis into two cases.

A. Case 1: $N \leq 2M \leq 2N$

The achievability in this case follows by a careful combination of Maddah Ali-Tse coding scheme [2] developed for the MIMO broadcast channel with additional noise injection. Also, as we already mentioned, it has connections with, and can be seen as an extension to the case of distributed transmitters of that developed by Yang *et. al.* [37] in the context of secure transmission over a two-user MIMO broadcast channel with delayed CSI at the transmitter. The scheme also extends Tandon *et. al.* [12] coding scheme about X-channels without security constraints to the setting with secrecy. The communication takes place in four phases. For simplicity of the analysis and, in accordance with the degrees of freedom framework, we ignore the additive noise impairment.

Phase 1: Injecting artificial noise

In the first phase, the communication takes place in $T_1 = N^2$ channel uses. Let $\mathbf{u}_1 = [u_1^1, \ldots, u_1^{MT_1}]^T$ and $\mathbf{u}_2 = [u_2^1, \ldots, u_2^{MT_1}]^T$ denote the artificial noises injected by Transmitter 1 and Transmitter 2 respectively. The channel outputs at Receiver 1 and Receiver 2 during this phase are given by

$$\mathbf{y}_1^{(1)} = \tilde{\mathbf{H}}_{11}^{(1)}\mathbf{u}_1 + \tilde{\mathbf{H}}_{12}^{(1)}\mathbf{u}_2 \tag{12}$$

$$\mathbf{y}_2^{(1)} = \tilde{\mathbf{H}}_{21}^{(1)}\mathbf{u}_1 + \tilde{\mathbf{H}}_{22}^{(1)}\mathbf{u}_2 \tag{13}$$

where $\tilde{\mathbf{H}}_{ji}^{(1)} = \text{diag}(\{\mathbf{H}_{ji}^{(1)}[t]\}_t) \in \mathbb{C}^{NT_1 \times MT_1}$, for $t = 1, \ldots, T_1$, $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(1)} \in \mathbb{C}^{NT_1}$ and $\mathbf{y}_2^{(1)} \in \mathbb{C}^{NT_1}$. During this phase, each receiver gets NT_1 linearly independent equations that relate $2MT_1$

$\mathbf{u}_1$- and $\mathbf{u}_2$-variables. At the end of this phase, the channel output at Receiver i, $i = 1, 2$, is fed back along with the past CSI to Transmitter i.

Phase 2: Fresh information for Receiver 1

In this phase, the communication takes place in $T_2 = N(2M - N)$ channel uses. Both transmitters transmit to Receiver 1 confidential messages that they want to conceal from Receiver 2. To this end, Transmitter 1 sends fresh information $\mathbf{v}_{11} = [v_{11}^1, \ldots, v_{11}^{MT_2}]^T$ along with a linear combination of the channel output $\mathbf{y}_1^{(1)}$ of Receiver 1 during the first phase; and Transmitter 2 sends only fresh information $\mathbf{v}_{21} = [v_{21}^1, \ldots, v_{21}^{MT_2}]^T$ intended for Receiver 1, i.e.,

$$\begin{aligned} \mathbf{x}_1 &= \mathbf{v}_{11} + \Theta_1 \mathbf{y}_1^{(1)} \\ \mathbf{x}_2 &= \mathbf{v}_{21} \end{aligned} \tag{14}$$

where $\Theta_1 \in \mathcal{C}^{MT_2 \times NT_1}$ is a matrix that is known at all nodes and whose choice will be specified below. The channel outputs at the receivers during this phase are given by

$$\mathbf{y}_1^{(2)} = \tilde{\mathbf{H}}_{11}^{(2)}(\mathbf{v}_{11} + \Theta_1 \mathbf{y}_1^{(1)}) + \tilde{\mathbf{H}}_{12}^{(2)} \mathbf{v}_{21} \tag{15a}$$

$$\mathbf{y}_2^{(2)} = \tilde{\mathbf{H}}_{21}^{(2)}(\mathbf{v}_{11} + \Theta_1 \mathbf{y}_1^{(1)}) + \tilde{\mathbf{H}}_{22}^{(2)} \mathbf{v}_{21} \tag{15b}$$

where $\tilde{\mathbf{H}}_{ji}^{(2)} = \text{diag}(\{\mathbf{H}_{ji}^{(2)}[t]\}_t) \in \mathbb{C}^{NT_2 \times MT_2}$, for $t = 1, \ldots, T_2$, $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(2)} \in \mathbb{C}^{NT_2}$ and $\mathbf{y}_2^{(2)} \in \mathbb{C}^{NT_2}$. At the end of this phase, the channel output at Receiver i, $i = 1, 2$, is fed back along with the delayed CSI to Transmitter i.

Since Receiver 1 knows the CSI $(\tilde{\mathbf{H}}_{11}^{(2)}, \tilde{\mathbf{H}}_{12}^{(2)})$ and the channel output $\mathbf{y}_1^{(1)}$ from Phase 1, it subtracts out the contribution of $\mathbf{y}_1^{(1)}$ from the received signal $\mathbf{y}_1^{(2)}$ and, thus, obtains NT_2 linearly independent equations with $2MT_2$ $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-variables. Thus, Receiver 1 requires $(2M - N)T_2$ extra linearly independent equations to successfully decode the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it during this phase. Let $\tilde{\mathbf{y}}_2^{(2)} \in \mathbb{C}^{(2M-N)T_2}$ denote a set of $(2M - N)T_2$ such linearly independent equations, selected among the available NT_2 side information equations $\mathbf{y}_2^{(2)} \in \mathbb{C}^{NT_2}$ (recall that $2M - N \leq N$ in this case). If these equations can be conveyed to Receiver 1, they will suffice to help it decode the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols, since the latter already knows $\mathbf{y}_1^{(1)}$. These equations will be transmitted *jointly* by the two transmitters in Phase 4, and are learned as follows. Transmitter 2 learns $\mathbf{y}_2^{(2)}$, and so $\tilde{\mathbf{y}}_2^{(2)}$, directly by means of the output feedback from Receiver 2 at the end of this phase. Transmitter 1 learns $\mathbf{y}_2^{(2)}$, and so $\tilde{\mathbf{y}}_2^{(2)}$, by means of output as well as delayed CSI feedback from Receiver 1 at the end of Phase 2, as follows. First, Transmitter 1 utilizes the fed back output $\mathbf{y}_1^{(2)}$ to learn the $\mathbf{v}_{21}$-symbols that are transmitted by Transmitter 2 during this phase. This can be accomplished correctly since Transmitter 1, which already

knows $\mathbf{v}_{11}$ and $\mathbf{y}_1^{(1)}$, has also gotten the delayed CSI $(\tilde{\mathbf{H}}_{11}^{(2)}, \tilde{\mathbf{H}}_{12}^{(2)})$ and $M \leq N$. Next, Transmitter 1, which also knows the delayed CSI $(\tilde{\mathbf{H}}_{21}^{(2)}, \tilde{\mathbf{H}}_{22}^{(2)})$, reconstructs $\mathbf{y}_2^{(2)}$ as given by (15b).

Phase 3: Fresh information for Receiver 2

This phase is similar to Phase 2, with the roles of Transmitter 1 and Transmitter 2, as well as those of Receiver 1 and Receiver 2, being swapped. More specifically, the communication takes place in $T_2 = N(2M - N)$ channel uses. Fresh information is sent by both transmitters to Receiver 2, and is to be concealed from Receiver 1. Transmitter 1 transmits fresh information $\mathbf{v}_{12} = [v_{12}^1, \ldots, v_{12}^{MT_2}]^T$ to Receiver 2, and Transmitter 2 transmits $\mathbf{v}_{22} = [v_{22}^1, \ldots, v_{22}^{MT_2}]^T$ along with a linear combination of the channel output $\mathbf{y}_2^{(1)}$ at Receiver 2 during Phase 1, i.e.,

$$\begin{aligned} \mathbf{x}_1 &= \mathbf{v}_{12} \\ \mathbf{x}_2 &= \mathbf{v}_{22} + \Theta_2 \mathbf{y}_2^{(1)} \end{aligned} \tag{16}$$

where $\Theta_2 \in \mathcal{C}^{MT_2 \times NT_1}$ is matrix that is known at all nodes and whose choice will be specified below. The channel outputs during this phase are given by

$$\mathbf{y}_1^{(3)} = \tilde{\mathbf{H}}_{11}^{(3)} \mathbf{v}_{12} + \tilde{\mathbf{H}}_{12}^{(3)} (\mathbf{v}_{22} + \Theta_2 \mathbf{y}_2^{(1)}) \tag{17a}$$

$$\mathbf{y}_2^{(3)} = \tilde{\mathbf{H}}_{21}^{(3)} \mathbf{v}_{12} + \tilde{\mathbf{H}}_{22}^{(3)} (\mathbf{v}_{22} + \Theta_2 \mathbf{y}_2^{(1)}) \tag{17b}$$

where $\tilde{\mathbf{H}}_{ji}^{(3)} = \text{diag}(\{\mathbf{H}_{ji}^{(3)}[t]\}_t) \in \mathcal{C}^{NT_2 \times MT_2}$ for $t = 1, \ldots, T_2$, $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(3)} \in \mathbb{C}^{NT_2}$ and $\mathbf{y}_2^{(3)} \in \mathbb{C}^{NT_2}$. At the end of this phase, the channel output at Receiver i, $i = 1, 2$, is fed back along with the delayed CSI to Transmitter i.

Similar to Phase 2, at the end of Phase 3 since Receiver 2 knows the CSI $(\tilde{\mathbf{H}}_{21}^{(3)}, \tilde{\mathbf{H}}_{22}^{(3)})$ and the channel output $\mathbf{y}_2^{(1)}$ from Phase 1, it subtracts out the contribution of $\mathbf{y}_2^{(1)}$ from the received signal $\mathbf{y}_2^{(3)}$ and, thus, obtain NT_2 linearly independent equations with $2MT_2$ $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-variables. Thus, similar to Receiver 1 at the end of Phase 2, Receiver 2 requires $(2M-N)T_2$ extra linearly independent equations to successfully decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols that are intended to it during this phase. Let $\tilde{\mathbf{y}}_1^{(3)} \in \mathbb{C}^{(2M-N)T_2}$ denote a set of $(2M - N)T_2$ such linearly independent equations, selected among the available NT_2 side information equations $\mathbf{y}_1^{(3)} \in \mathbb{C}^{NT_2}$. If these equations can be conveyed to Receiver 2, they will suffice to help it decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols, since the latter already knows $\mathbf{y}_2^{(1)}$. These equations will be transmitted *jointly* by the two transmitters in Phase 4, and are learned as follows. Transmitter 1 learns $\mathbf{y}_1^{(3)}$, and so $\tilde{\mathbf{y}}_1^{(3)}$, directly by means of the output feedback from Receiver 1 at the end of this phase. Transmitter 2 learns $\mathbf{y}_1^{(3)}$, and so $\tilde{\mathbf{y}}_1^{(3)}$, by means of output as well as delayed CSI feedback from Receiver 2 at the end of Phase 3, as follows. First, Transmitter 2 utilizes the fed back output $\mathbf{y}_2^{(3)}$ to learn the

$\mathbf{v}_{12}$-symbols that are transmitted by Transmitter 1 during this phase. This can be accomplished correctly since Transmitter 2, which already knows $\mathbf{v}_{22}$ and $\mathbf{y}_2^{(1)}$, has also gotten the delayed CSI $(\tilde{\mathbf{H}}_{21}^{(3)}, \tilde{\mathbf{H}}_{22}^{(3)})$ and $M \leq N$. Next, Transmitter 2, which also knows the delayed CSI $(\tilde{\mathbf{H}}_{11}^{(3)}, \tilde{\mathbf{H}}_{12}^{(3)})$, reconstructs $\mathbf{y}_1^{(3)}$ as given by (17a).

Phase 4: Interference alignment and decoding

Recall that, at the end of Phase 3, Receiver 1 requires $(2M-N)T_2$ extra equations to successfully decode the sent $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols, and Receiver 2 requires $(2M-N)T_2$ extra equations to successfully decode the sent $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols. Also, recall that at the end of this third phase, *both* transmitters can reconstruct the side information, or interference, equations $\tilde{\mathbf{y}}_1^{(3)} \in \mathbb{C}^{(2M-N)T_2}$ and $\tilde{\mathbf{y}}_2^{(2)} \in \mathbb{C}^{(2M-N)T_2}$ that are required by both receivers. In this phase, both transmitters transmit these equations jointly, as follows. The communication takes place in $T_3 = (2M-N)^2$ channel uses. Let

$$I = \Phi_1[\underbrace{\tilde{\mathbf{y}}_2^{(2)}}_{(2M-N)T_2} \quad \underbrace{\phi}_{(2N-2M)T_2}]^T + \Phi_2[\underbrace{\tilde{\mathbf{y}}_1^{(3)}}_{(2M-N)T_2} \quad \underbrace{\phi}_{(2N-2M)T_2}]^T$$

where $\Phi_1 \in \mathcal{C}^{2MT_3 \times NT_2}$ and $\Phi_2 \in \mathcal{C}^{2MT_3 \times NT_2}$ are linear combination matrices that are assumed to be known to all the nodes. During this phase, the transmitters send

$$\mathbf{x}_1 = [I^1, \ldots, I^{MT_3}]$$
$$\mathbf{x}_2 = [I^{(M+1)T_3}, \ldots, I^{2MT_3}].$$

At the end of Phase 4, Receiver 1 gets NT_3 equations in $2NT_3$ variables. Since Receiver 1 knows $\mathbf{y}_1^{(3)}$ from Phase 3 as well as the CSI, it can subtract out the contribution of $\tilde{\mathbf{y}}_1^{(3)}$ from its received signal to get NT_3 equations in NT_3 variables. Thus, Receiver 1 can recover the $\tilde{\mathbf{y}}_2^{(2)} \in \mathbb{C}^{(2M-N)T_2}$ interference equations. Then, using the pair of output vectors $(\mathbf{y}_1^{(2)}, \tilde{\mathbf{y}}_2^{(2)})$, Receiver 1 first subtracts out the contribution of $\mathbf{y}_1^{(1)}$; and, then, it inverts the resulting $2MT_2$ linearly independent equations relating the sent $2MT_2$ $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols. Thus, Receiver 1 successfully decodes the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it. Receiver 2 performs similar operations to successfully decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols that are intended to it.

Security analysis

The analysis and algebra in this section are similar to those the in [37] in context of secure broadcasting of messages on a two-user MIMO broadcast channel with delayed CSI known at the transmitter.

At the end of Phase 4, the channel outputs at the receivers can be written as

$$\mathbf{y}_1 = \underbrace{\begin{bmatrix} \tilde{\mathbf{H}}_2 & \tilde{\mathbf{H}}_{11}^{(2)}\Theta_1 & \mathbf{0} \\ \tilde{\mathbf{H}}_4\Phi_1\tilde{\mathbf{G}}_2 & \tilde{\mathbf{H}}_4\Phi_1\tilde{\mathbf{H}}_{21}^{(2)}\Theta_1 & \tilde{\mathbf{H}}_4\Phi_2 \\ \mathbf{0} & \mathbf{I}_{NT_1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_{NT_2} \end{bmatrix}}_{\hat{\mathbf{H}} \in \mathbb{C}^{4M^2N \times 4M^2N}} \begin{bmatrix} \mathbf{v}_1 \\ \tilde{\mathbf{H}}_1\mathbf{u} \\ \tilde{\mathbf{H}}_3\mathbf{v}_2 + \tilde{\mathbf{H}}_{12}^{(3)}\Theta_2\tilde{\mathbf{G}}_1\mathbf{u} \end{bmatrix} \tag{18}$$

$$\mathbf{y}_2 = \underbrace{\begin{bmatrix} \mathbf{0} & \mathbf{I}_{NT_1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_{NT_2} \\ \tilde{\mathbf{G}}_3 & \tilde{\mathbf{H}}_{22}^{(3)}\Theta_2 & \mathbf{0} \\ \tilde{\mathbf{G}}_4\Phi_2\tilde{\mathbf{H}}_3 & \tilde{\mathbf{G}}_4\Phi_2\tilde{\mathbf{H}}_{12}^{(3)}\Theta_2 & \tilde{\mathbf{G}}_4\Phi_1 \end{bmatrix}}_{\hat{\mathbf{G}} \in \mathbb{C}^{4M^2N \times 4M^2N}} \begin{bmatrix} \mathbf{v}_2 \\ \tilde{\mathbf{G}}_1\mathbf{u} \\ \tilde{\mathbf{G}}_2\mathbf{v}_1 + \tilde{\mathbf{H}}_{21}^{(2)}\Theta_1\tilde{\mathbf{H}}_1\mathbf{u} \end{bmatrix} \tag{19}$$

where $\tilde{\mathbf{H}}_t = [\tilde{\mathbf{H}}_{11}^{(t)} \;\; \tilde{\mathbf{H}}_{12}^{(t)}]$, $\tilde{\mathbf{G}}_t = [\tilde{\mathbf{H}}_{21}^{(t)} \;\; \tilde{\mathbf{H}}_{22}^{(t)}]$, for $t = 1, \ldots, 4$, $\mathbf{u} = [\mathbf{u}_1^T \;\; \mathbf{u}_2^T]^T$, $\mathbf{v}_1 = [\mathbf{v}_{11}^T \;\; \mathbf{v}_{21}^T]^T$, and $\mathbf{v}_2 = [\mathbf{v}_{12}^T \;\; \mathbf{v}_{22}^T]^T$. The information rate to Receiver 1 is given by the mutual information $I(\mathbf{v}_1; \mathbf{y}_1)$, and can be evaluated as

$$\begin{aligned} I(\mathbf{v}_1; \mathbf{y}_1) &= I(\mathbf{v}_1, \tilde{\mathbf{H}}_1\mathbf{u}, \tilde{\mathbf{H}}_3\mathbf{v}_2 + \tilde{\mathbf{H}}_{12}^{(3)}\Theta_2\tilde{\mathbf{G}}_1\mathbf{u}; \mathbf{y}_1) \\ &\quad - I(\tilde{\mathbf{H}}_1\mathbf{u}, \tilde{\mathbf{H}}_3\mathbf{v}_2 + \tilde{\mathbf{H}}_{12}^{(3)}\Theta_2\tilde{\mathbf{G}}_1\mathbf{u}; \mathbf{y}_1 | \mathbf{v}_1) \\ &\overset{(a)}{=} \text{rank}(\hat{\mathbf{H}}).\log(2P) - \text{rank}\begin{pmatrix} \tilde{\mathbf{H}}_{11}^{(2)}\Theta_1 & \mathbf{0} \\ \tilde{\mathbf{H}}_4\Phi_1\tilde{\mathbf{H}}_{21}^{(2)}\Theta_1 & \tilde{\mathbf{H}}_4\Phi_2 \\ \mathbf{I}_{NT_1} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_{NT_2} \end{pmatrix}.\log(2P) \\ &\overset{(b)}{=} N(T_1+T_2).\log(2P) + \text{rank}\begin{pmatrix} \tilde{\mathbf{H}}_2 \\ \tilde{\mathbf{H}}_4\Phi_1\tilde{\mathbf{G}}_2 \end{pmatrix}.\log(2P) \\ &\quad - N(T_1+T_2).\log(2P) \\ &= \text{rank}\begin{pmatrix} \tilde{\mathbf{H}}_2 \\ \tilde{\mathbf{H}}_4\Phi_1\tilde{\mathbf{G}}_2 \end{pmatrix}.\log(2P) \\ &\overset{(c)}{=} 2MN(2M-N).\log(2P) \end{aligned} \tag{20}$$

where (a) follows from [37, Lemma 2]; (b) follows from the block diagonalization structure of $\hat{\mathbf{H}}$; and (c) follows by reasoning as in [37] for the selection of Φ_1 with appropriate rank such that the equality holds.

Similarly, the information leaked to Receiver 2 can be bounded as

$$\begin{aligned}
I(\mathbf{v}_1;\mathbf{y}_2) &= I(\mathbf{v}_1;\mathbf{y}_2|\mathbf{v}_2) \\
&\leq I(\tilde{\mathbf{G}}_2\mathbf{v}_1;\mathbf{y}_2|\mathbf{v}_2) \\
&= I(\tilde{\mathbf{G}}_2\mathbf{v}_1,\mathbf{u};\mathbf{y}_2|\mathbf{v}_2) - I(\mathbf{u};\mathbf{y}_2|\tilde{\mathbf{G}}_2\mathbf{v}_1,\mathbf{v}_2) \\
&\leq I(\tilde{\mathbf{G}}_1\mathbf{u},\tilde{\mathbf{G}}_2\mathbf{v}_1+\tilde{\mathbf{H}}_{21}^{(2)}\Theta_1\tilde{\mathbf{H}}_1\mathbf{u};\mathbf{y}_2|\mathbf{v}_2) - I(\mathbf{u};\mathbf{y}_2|\tilde{\mathbf{G}}_2\mathbf{v}_1,\mathbf{v}_2) \\
&\overset{(a)}{=} \text{rank}\begin{pmatrix} \mathbf{I}_{NT_1} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_{NT_2} \\ \tilde{\mathbf{H}}_{22}^{(3)}\Theta_2 & \mathbf{0} \\ \tilde{\mathbf{G}}_4\Phi_2\tilde{\mathbf{H}}_{12}^{(3)}\Theta_2 & \tilde{\mathbf{G}}_4\Phi_1 \end{pmatrix}.\log(2P) \\
&\quad -\text{rank}\begin{pmatrix} \tilde{\mathbf{G}}_1 \\ \tilde{\mathbf{H}}_{21}^{(2)}\Theta_1\tilde{\mathbf{H}}_1 \\ \tilde{\mathbf{H}}_{22}^{(3)}\Theta_2\tilde{\mathbf{G}}_1 \\ \tilde{\mathbf{G}}_4\Phi_2\tilde{\mathbf{H}}_{12}^{(3)}\Theta_2\tilde{\mathbf{G}}_1+\tilde{\mathbf{G}}_4\Phi_1\tilde{\mathbf{H}}_{21}^{(2)}\Theta_1\tilde{\mathbf{H}}_1 \end{pmatrix}.\log(2P) \\
&= N(T_1+T_2).\log(2P) - \text{rank}\begin{pmatrix} \tilde{\mathbf{G}}_1 \\ \tilde{\mathbf{H}}_{21}^{(2)}\Theta_1\tilde{\mathbf{H}}_1 \end{pmatrix}.\log(2P) \\
&\overset{(b)}{=} 0
\end{aligned} \tag{21}$$

where (a) follows from [37, Lemma 2]; and (b) follows by choosing Θ_1 by reasoning similar to in [37]. Summarizing, the above shows that $2MN(2M-N)$ symbols are transmitted securely to Receiver 1 over a total of $4M^2$ time slots, thus yielding $d_{11}+d_{21} = N(2M-N)/2M$ sum SDoF at this receiver. Similar reasoning and algebra show that $2MN(2M-N)$ symbols are also transmitted securely to Receiver 2 over a total of $4M^2$ time slots, thus yielding $d_{12}+d_{22} = N(2M-N)/2M$ sum SDoF at this receiver.

B. Case 2: $2M \geq 2N$

In this case, it is sufficient that each transmitter utilizes only N antennas; and that Receiver i, $i = 1, 2$, feeds back only its output to transmitter i, i.e., no delayed CSI. The details of the coding scheme and proof

are similar to in Case 2, and are provided below for completeness. More specifically, the communication takes place in four phases, each composed of only one time slot.

Phase 1: Injecting artificial noise

In this phase, both transmitters inject artificial noise. Let $\mathbf{u}_1 = [u_1^1, \ldots, u_1^N]^T$ denote the artificial noise injected by Transmitter 1, and $\mathbf{u}_2 = [u_2^1, \ldots, u_2^N]^T$ denote the artificial noise injected by Transmitter 2. The channel outputs at the receivers during this phase are given by

$$\mathbf{y}_1^{(1)} = \mathbf{H}_{11}^{(1)}\mathbf{u}_1 + \mathbf{H}_{12}^{(1)}\mathbf{u}_2 \tag{22}$$

$$\mathbf{y}_2^{(1)} = \mathbf{H}_{21}^{(1)}\mathbf{u}_1 + \mathbf{H}_{22}^{(1)}\mathbf{u}_2 \tag{23}$$

where $\mathbf{H}_{ji}^{(1)} \in \mathbb{C}^{N\times N}$, for $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(1)} \in \mathbb{C}^N$ and $\mathbf{y}_2^{(1)} \in \mathbb{C}^N$. At the end of this phase, the output at Receiver i, $i = 1, 2$, is fed back to Transmitter i.

Phase 2: Fresh information for Receiver 1

In this phase, both transmitters transmit confidential messages to Receiver 1. These messages are meant to be concealed from Receiver 2. To this end, Transmitter 1 transmits fresh information $\mathbf{v}_{11} = [v_{11}^1, \ldots, v_{11}^N]^T$ along with a linear combination of the channel output at Receiver 1 during Phase 1, and Transmitter 2 transmits fresh information $\mathbf{v}_{21} = [v_{21}^1, \ldots, v_{21}^N]^T$ intended for Receiver 1, i.e.,

$$\mathbf{x}_1 = \mathbf{v}_{11} + \Theta_1\mathbf{y}_1^{(1)}$$

$$\mathbf{x}_2 = \mathbf{v}_{21}$$

where $\Theta_1 \in \mathcal{C}^{N\times N}$ is a matrix that is assumed to be known at all the nodes, and whose choice will be specified below. The channel outputs at the receivers during this phase are given by

$$\mathbf{y}_1^{(2)} = \mathbf{H}_{11}^{(2)}(\mathbf{v}_{11} + \Theta_1\mathbf{y}_1^{(1)}) + \mathbf{H}_{12}^{(2)}\mathbf{v}_{21} \tag{24}$$

$$\mathbf{y}_2^{(2)} = \mathbf{H}_{21}^{(2)}(\mathbf{v}_{11} + \Theta_1\mathbf{y}_1^{(1)}) + \mathbf{H}_{22}^{(2)}\mathbf{v}_{21} \tag{25}$$

where $\mathbf{H}_{ji}^{(2)} \in \mathbb{C}^{N\times N}$, for $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(2)} \in \mathbb{C}^N$ and $\mathbf{y}_2^{(2)} \in \mathbb{C}^N$. At the end of this phase, the channel output at Receiver i, $i = 1, 2$, is fed back to Transmitter i. Since Receiver 1 knows the CSI and the channel output $\mathbf{y}_1^{(1)}$ from Phase 1, it subtracts out the contribution of $\mathbf{y}_1^{(1)}$ from $\mathbf{y}_1^{(2)}$ and, thus, obtains N linearly independent equations that relates the $2N$ $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols. Thus, Receiver 1 requires N extra linearly independent equations to successfully decode the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it during this phase. These extra equations will be provided by transmitting $\mathbf{y}_2^{(2)}$ by Transmitter 2 in Phase 4. Transmitter 2 learns $\mathbf{y}_2^{(2)}$ directly by means of the output feedback from Receiver 2 at the end of this phase.

Phase 3: Fresh information for Receiver 2

This phase is similar to Phase 2, with the roles of Transmitter 1 and Transmitter 2, as well as those of Receiver 1 and Receiver 2, being swapped. The information messages are sent by both transmitters to Receiver 2, and are to be concealed from Receiver 1. More specifically, Transmitter 1 transmits fresh information $\mathbf{v}_{12} = [v_{12}^1, \ldots, v_{12}^N]^T$ to Receiver 2, and Transmitter 2 transmits $\mathbf{v}_{22} = [v_{22}^1, \ldots, v_{22}^N]^T$ along with a linear combination of the channel output received at Receiver 2 during Phase 1, i.e.,

$$\mathbf{x}_1 = \mathbf{v}_{12}$$

$$\mathbf{x}_2 = \mathbf{v}_{22} + \Theta_2 \mathbf{y}_2^{(1)}$$

where $\Theta_2 \in \mathcal{C}^{N\times N}$ is matrix that is known at all nodes and whose choice will be specified below. The channel outputs at the receivers during this phase are given by

$$\mathbf{y}_1^{(3)} = \mathbf{H}_{11}^{(3)}\mathbf{v}_{21} + \mathbf{H}_{12}^{(3)}(\mathbf{v}_{22} + \Theta_2\mathbf{y}_2^{(1)}) \tag{26}$$

$$\mathbf{y}_2^{(3)} = \mathbf{H}_{21}^{(3)}\mathbf{v}_{21} + \mathbf{H}_{22}^{(3)}(\mathbf{v}_{22} + \Theta_2\mathbf{y}_2^{(1)}) \tag{27}$$

where $\mathbf{H}_{ji}^{(3)} \in \mathbb{C}^{N\times N}$, for $i = 1, 2$, $j = 1, 2$, $\mathbf{y}_1^{(3)} \in \mathbb{C}^N$ and $\mathbf{y}_2^{(3)} \in \mathbb{C}^N$. At the end of this phase, the channel output at Receiver i, $i = 1, 2$, is fed back to Transmitter i. Since Receiver 1 knows the CSI and the channel output $\mathbf{y}_2^{(1)}$ from Phase 1, it subtracts out the contribution of $\mathbf{y}_2^{(1)}$ from $\mathbf{y}_2^{(3)}$ and, thus, obtains N linearly independent equations that relates the $2N$ $\mathbf{v}_{21}$- and $\mathbf{v}_{22}$-symbols. Thus, Receiver 1 requires N extra linearly independent equations to successfully decode the $\mathbf{v}_{21}$- and $\mathbf{v}_{22}$-symbols that are intended to it during this phase. These extra equations will be provided by transmitting $\mathbf{y}_1^{(3)}$ by Transmitter 1 in Phase 4. Transmitter 1 learns $\mathbf{y}_1^{(3)}$ directly by means of the output feedback from Receiver 1 at the end of this phase.

Phase 4: Interference alignment and decoding

Recall that, at the end of Phase 3, Receiver 1 knows $\mathbf{y}_1^{(3)}$ and requires $\mathbf{y}_2^{(2)}$; and Receiver 2 knows $\mathbf{y}_2^{(2)}$ and requires $\mathbf{y}_1^{(3)}$. Also, at the end of this phase, Transmitter 1 has learned $\mathbf{y}_1^{(3)}$ by means of output feedback from Receiver 1; and Transmitter 2 has learned $\mathbf{y}_2^{(2)}$ by means of output feedback from Receiver 2. The inputs by the two transmitters during Phase 4 are given by

$$\mathbf{x}_1 = \Phi_2\mathbf{y}_1^{(3)}$$

$$\mathbf{x}_2 = \Phi_1\mathbf{y}_2^{(2)}$$

where $\Phi_1 \in \mathcal{C}^{N\times N}$ and $\Phi_2 \in \mathcal{C}^{N\times N}$ are matrices that are assumed to be known by all the nodes. At the end of Phase 4, Receiver 1 gets N equations in $2N$ variables. Since Receiver 1 knows $\mathbf{y}_1^{(3)}$, as well as

the CSI, it can subtract out the side information, or interference, equations $\mathbf{y}_2^{(2)}$ that are seen at Receiver 2 during Phase 2. Then, using the pair of output vectors $(\mathbf{y}_1^{(2)}, \mathbf{y}_2^{(2)})$, Receiver 1 first subtracts out the contribution of $\mathbf{y}_1^{(1)}$; and, then, it inverts the resulting $2N$ linearly independent equations relating the sent $2N$ $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols. Thus, Receiver 1 successfully decodes the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it. Receiver 2 performs similar operations to successfully decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols that are intended to it.

Security analysis

At the end of Phase 4, the channel outputs at the receivers are given by

$$\mathbf{y}_1 = \underbrace{\begin{bmatrix} \mathbf{H}_2 & \mathbf{H}_{11}^{(2)}\Theta_1 & \mathbf{0} \\ \mathbf{H}_{12}^{(4)}\Phi_1\mathbf{G}_2 & \mathbf{H}_{12}^{(4)}\Phi_1\mathbf{H}_{21}^{(2)}\Theta_1 & \mathbf{H}_{11}^{(4)}\Phi_2 \\ \mathbf{0} & \mathbf{I}_N & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_N \end{bmatrix}}_{\hat{\mathbf{H}} \in \mathbb{C}^{4N\times 4N}} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{H}_1\mathbf{u} \\ \mathbf{H}_3\mathbf{v}_2 + \mathbf{H}_{12}^{(3)}\Theta_2\mathbf{G}_1\mathbf{u} \end{bmatrix} \tag{28}$$

$$\mathbf{y}_2 = \underbrace{\begin{bmatrix} \mathbf{0} & \mathbf{I}_N & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_N \\ \mathbf{G}_3 & \mathbf{H}_{22}^{(3)}\Theta_2 & \mathbf{0} \\ \mathbf{H}_{21}^{(4)}\Phi_2\mathbf{H}_3 & \mathbf{H}_{21}^{(4)}\Phi_2\mathbf{H}_{12}^{(3)}\Theta_2 & \mathbf{H}_{22}^{(4)}\Phi_1 \end{bmatrix}}_{\hat{\mathbf{G}} \in \mathbb{C}^{4N\times 4N}} \begin{bmatrix} \mathbf{v}_2 \\ \mathbf{G}_1\mathbf{u} \\ \mathbf{G}_2\mathbf{v}_1 + \mathbf{H}_{21}^{(2)}\Theta_1\mathbf{H}_1\mathbf{u} \end{bmatrix} \tag{29}$$

where $\mathbf{H}_t = [\mathbf{H}_{11}^{(t)} \;\; \mathbf{H}_{12}^{(t)}]$, $\mathbf{G}_t = [\mathbf{H}_{21}^{(t)} \;\; \mathbf{H}_{22}^{(t)}]$, for $t = 1, \ldots, 3$, $\mathbf{u} = [\mathbf{u}_1^T \;\; \mathbf{u}_2^T]^T$, $\mathbf{v}_1 = [\mathbf{v}_{11}^T \;\; \mathbf{v}_{21}^T]^T$, and $\mathbf{v}_2 = [\mathbf{v}_{12}^T \;\; \mathbf{v}_{22}^T]^T$. Similar to in the analysis of the previous case, the information rate to Receiver 1 is given by the mutual information $I(\mathbf{v}_1; \mathbf{y}_1)$, and can be evaluated as

$$\begin{aligned} I(\mathbf{v}_1; \mathbf{y}_1) \;&=\; I(\mathbf{v}_1, \mathbf{H}_1\mathbf{u}, \mathbf{H}_3\mathbf{v}_2 + \mathbf{H}_{12}^{(3)}\Theta_2\mathbf{G}_1\mathbf{u}; \mathbf{y}_1) \\ &\quad - I(\mathbf{H}_1\mathbf{u}, \mathbf{H}_3\mathbf{v}_2 + \mathbf{H}_{12}^{(3)}\Theta_2\mathbf{G}_1\mathbf{u}; \mathbf{y}_1 | \mathbf{v}_1) \\ &\overset{(a)}{=} \text{rank}(\hat{\mathbf{H}}).\log(2P) - \text{rank}\begin{pmatrix} \mathbf{H}_{11}^{(2)}\Theta_1 & \mathbf{0} \\ \mathbf{H}_{12}^{(4)}\Phi_1\mathbf{H}_{21}^{(2)}\Theta_1 & \mathbf{H}_{11}^{(4)}\Phi_2 \\ \mathbf{I}_N & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_N \end{pmatrix}.\log(2P) \end{aligned}$$

$$\stackrel{(b)}{=} 2N.\log(2P) + \text{rank}\begin{pmatrix}\mathbf{H}_2\\ \mathbf{H}_{12}^{(4)}\Phi_1\mathbf{G}_2\end{pmatrix}.\log(2P) - 2N.\log(2P)$$

$$= \text{rank}\begin{pmatrix}\mathbf{H}_2\\ \mathbf{H}_{12}^{(4)}\Phi_1\mathbf{G}_2\end{pmatrix}.\log(2P)$$

$$\stackrel{(c)}{=} 2N.\log(2P) \tag{30}$$

where (a) follows from [37, Lemma 2]; (b) follows by using the block diagonalization structure of $\hat{\mathbf{H}}$; and (c) follows by reasoning as in [37] for the selection of Φ_1 with appropriate rank such that the equality holds.

Similarly, the information leaked to Receiver 2 can be bounded as

$$I(\mathbf{v}_1;\mathbf{y}_2) \leq I(\mathbf{G}_1\mathbf{u}, \mathbf{G}_2\mathbf{v}_1 + \mathbf{H}_{21}^{(2)}\Theta_1\mathbf{H}_1\mathbf{u};\mathbf{y}_2|\mathbf{v}_2) - I(\mathbf{u};\mathbf{y}_2|\mathbf{G}_2\mathbf{v}_1,\mathbf{v}_2)$$

$$\stackrel{(a)}{=} \text{rank}\begin{pmatrix}\mathbf{I}_N & \mathbf{0}\\ \mathbf{0} & \mathbf{I}_N\\ \mathbf{H}_{22}^{(3)}\Theta_2 & \mathbf{0}\\ \mathbf{H}_{21}^{(4)}\Phi_2\mathbf{H}_{12}^{(3)}\Theta_2 & \mathbf{H}_{22}^{(4)}\Phi_1\end{pmatrix}.\log(2P)$$

$$-\text{rank}\begin{pmatrix}\mathbf{G}_1\\ \mathbf{H}_{21}^{(2)}\Theta_1\mathbf{H}_1\\ \mathbf{H}_{22}^{(3)}\Theta_2\mathbf{G}_1\\ \mathbf{H}_{21}^{(4)}\Phi_2\mathbf{H}_{12}^{(3)}\Theta_2\mathbf{G}_1 + \mathbf{H}_{22}^{(4)}\Phi_1\mathbf{H}_{21}^{(2)}\Theta_1\mathbf{H}_1\end{pmatrix}.\log(2P)$$

$$= 2N.\log(2P) - \text{rank}\begin{pmatrix}\mathbf{G}_1\\ \mathbf{H}_{21}^{(2)}\Theta_1\mathbf{H}_1\end{pmatrix}.\log(2P)$$

$$\stackrel{(b)}{=} 0 \tag{31}$$

where (a) follows from [37, Lemma 2]; and (b) follows by choosing Θ_1 with the reasoning similar to [37].

Summarizing, the above shows that $2N$ symbols are transmitted securely to Receiver 1, over a total of 4 time slots, yielding $d_{11} + d_{21} = \frac{N}{2}$ sum SDoF. Similar analysis shows that the scheme also offers $d_{12} + d_{22} = \frac{N}{2}$ sum SDoF for Receiver 2.

This concludes the proof of the direct part of Theorem 1.

Remark 3: Investigating the coding scheme of Theorem 1, it can be seen that in the case in which $N \leq M$, local output feedback only suffices to achieve the optimum sum SDoF. That is, the transmitters exploit only the availability of local output feedback, and do not make use of the available delayed CSI.

V. SDoF of MIMO X-channel with Only Output Feedback

In this section, we focus on the two-user MIMO X-channel with only feedback available at transmitters. We study two special cases of availability of feedback at transmitters, 1) the case in which each receiver feeds back its channel output to both transmitters, to which we will refer as *global feedback*, and 2) the case in which Receiver i, $i = 1, 2$, feeds back its output only to Transmitter i, i.e., local feedback. In both cases, no CSI is provided to the transmitters.

A. MIMO X-channel with global feedback

As we mentioned previously, in this model the output at each receiver is fed back to both transmitters. The following remark sheds some light on the usefulness of such model in security-oriented contexts.

Remark 4: In realistic wiretap settings, it is not reasonable to assume the availability of any CSI on the eavesdropper channel at the transmitter side. This is because an eavesdropper is generally not willing to feed back information about its channel to the transmitter from which it wants to intercept the transmission. In an X-channel however, each receiver is not merely an eavesdropper for the information sent by the transmitters to the other receiver; it is also a legitimate receiver intended to get other information messages from the *same* transmitters. This holds since each transmitter sends information messages to both receivers, not to only one receiver as in interference channels. For example, Receiver 2 acts as an eavesdropper for the message W_{11} transmitted by Transmitter 1 to Receiver 1, but it also gets message W_{12} from Transmitter 1. Although it can possibly diminish its ability to capture message W_{11}, in its desire that Transmitter 1 learns better the channel so that it better transmits message W_{12}, Receiver 2 may find it useful to feed back information about the CSI on its channel to Transmitter 1, nonetheless. A similar observation holds for Receiver 1.

The following theorem provides the sum SDoF region of the MIMO X-channel with global feedback.

Theorem 2: The sum SDoF region of the two-user (M, M, N, N)–MIMO X-channel with global output feedback is given by that of Theorem 1.

Remark 5: The sum SDoF region of the MIMO X-channel with global feedback is same as the sum SDoF region of the MIMO X-channel with local feedback and delayed CSI. Investigating the coding scheme of the MIMO X-channel with local feedback and delayed CSI of Theorem 1, it can be seen that the

delayed CSI is utilized therein to provide each transmitter with the equations (or, side information) that are heard at the other receiver, which is unintended. With the availability of global feedback, this information is readily available at each transmitter; and, thus, there is no need for any CSI at the transmitters in order to achieve the same sum SDoF as that of Theorem 1.

Proof: The proof of the outer bound can be obtained by reasoning as follows. Let us denote the two-user MIMO X-channel with global feedback that we study as MIMO-X$^{(0)}$. Consider the MIMO-X channel obtained by assuming that, in addition to global feedback, i) delayed CSI is provided to both transmitters and that ii) these transmitters are allowed to cooperate. Denote the obtained MIMO-X channel as MIMO-X$^{(1)}$. Since the transmitters cooperate in MIMO-X$^{(1)}$, this model is in fact a MIMO BC with $2M$ antennas at the transmitter and N antennas at each receiver, with delayed CSI as well as output feedback given to the transmitter. Then, an outer bound on the SDoF of this MIMO-X$^{(1)}$ is given by [37, Theorem 3]. This holds because the result of [37, Theorem 3] continues to hold if one provides outputs feedback from the receivers to the transmitter in the two-user MIMO BC with delayed CSI that is considered in [37]. Next, since delayed CSI at the transmitters and cooperation can only increase the SDoF, it follows that the obtained outer bound is also an outer bound on the SDoF of MIMO-X$^{(0)}$. Thus, the region of Theorem 1 is an outer bound on the sum SDoF for the MIMO X-channel in which the transmitters are provided only with global feedback.

We now provide a brief outline of the coding scheme that we use to establish the sum SDoF region of Theorem 2. This coding scheme is very similar to that we use for the proof of Theorem 1, with the following (rather minor) differences. For the case in which $2M \leq N$ and that in which $2N \leq 2M$, the coding strategies are exactly same as those that we used for the proof of Theorem 1. For the case in which $N \leq 2M \leq 2N$, the first three phases are similar to those in the coding scheme of Theorem 1, but with, at the end of these phases, the receivers feeding back their outputs to both transmitters, instead of Receiver i, $i = 1, 2$, feeding back its output together with the delayed CSI to Transmitter i. Note that, during these phases, each transmitter learns the required side information equations *directly* from the global output feedback that it gets from the receivers (see Remark 5). Phase 4 and the decoding procedures are similar to those in the proof of Theorem 1. This concludes the proof of Theorem 2. □

B. MIMO X-channel with only local feedback

We now consider the case in which only local feedback is provided from the receivers to the receivers, i.e., Receiver i, $i = 1, 2$, feeds back its output to only Transmitter i.

For convenience we define the following quantity. Let, for given non-negative (M, N),

$$d_s^{\text{local}}(N,N,M) = \begin{cases} 0 & \text{if } \ M \leq N \\ \frac{M^2(M-N)}{2N^2+(M-N)(3M-N)} & \text{if } \ N \leq M \leq 2N \\ \frac{2N}{3} & \text{if } \ M \geq 2N \end{cases} \tag{32}$$

The following theorem provides an inner bound on the sum SDoF region of the two-user MIMO-X channel with local feedback.

Theorem 3: An inner bound on the sum SDoF region of the two-user (M, M, N, N)–MIMO X-channel with local feedback is given by the set of all non-negative pairs $(d_{11} + d_{21}, d_{12} + d_{22})$ satisfying

$$\begin{aligned} \frac{d_{11}+d_{21}}{d_s^{\text{local}}(N,N,2M)} + \frac{d_{12}+d_{22}}{\min(2M,2N)} &\leq 1 \\ \frac{d_{11}+d_{21}}{\min(2M,2N)} + \frac{d_{12}+d_{22}}{d_s^{\text{local}}(N,N,2M)} &\leq 1 \end{aligned} \tag{33}$$

for $2M \geq N$; and $\mathcal{C}_{\text{SDoF}}^{\text{sum}} = \{(0,0)\}$ if $2M \leq N$.

Remark 6: Obviously, the region of Theorem 1 is an outer bound on the sum SDoF region of the MIMO X-channel with local feedback. Also, it is easy to see that the inner bound of Theorem 3 is tight in the case in which $M \geq N$.

Remark 7: The main reason for which the SDoF of the MIMO X-channel with local feedback is smaller than that in Theorem 1 for the model with local feedback and delayed CSI can be explained as follows. Consider the Phase 4 in the coding scheme of Theorem 1 in Section IV-B. Each receiver requires $N(2M-N)(2M-N)$ extra equations to decode the symbols that are intended to it correctly. Given that there are more equations that need to be transmitted to both receivers than the number of available antennas at the transmitters, some of the equations need to be sent by both transmitters, i.e., some of the available antennas send sums of two equations, one intended for each receiver. Then, it can be seen easily that this is only possible if both transmitters know the ensemble of side information equations that they need to transmit, i.e., not only a subset of them corresponding to one receiver. In the coding scheme of Theorem 1, this is made possible by means of availability of both local output feedback and delayed CSI at the transmitters. Similarly, in the coding scheme of Theorem 2, this is made possible by means of availability of global feedback at the transmitters. For the model with only local feedback, however, this is not possible; and this explains the loss incurred in the sum SDoF region. More specifically, consider Phase 2 of the coding scheme of Theorem 1. Recall that, at the beginning of this phase, Transmitter 1 utilizes the fed back CSI $(\tilde{\mathbf{H}}_{11}^{(2)}, \tilde{\mathbf{H}}_{12}^{(2)})$ to learn the $\mathbf{v}_{21}$-symbols that are transmitted by Transmitter 2

during this phase; and then utilizes the fed back CSI $(\tilde{\mathbf{H}}_{21}^{(2)}, \tilde{\mathbf{H}}_{22}^{(2)})$ to reconstruct the side information output vector $\mathbf{y}_2^{(2)}$ that is required by Receiver 1 (given by (15b)). Also, Transmitter 2 performs similar operations to learn the side information output vector $\mathbf{y}_1^{(3)}$ that is required by Receiver 2 (given by (17a)). In the case of only local output feedback given to the transmitters, as we mentioned previously, this is not possible because of the lack of availability of CSI.

Proof: We now provide an outline of the coding scheme for the MIMO X-channel with local feedback.

For the case in which $2M \leq N$ and the case in which $N \leq M$, the achievability follows trivially by using the coding scheme of Theorem 1 (see Remark 3).

For the case in which $N \leq 2M \leq 2N$, the proof of achievability follows by a variation of the coding scheme of Theorem 1 that we outline briefly in what follows. The communication takes place in four phases.

Phase 1: The transmission scheme in this phase is similar to that in Phase 1 of the coding scheme of Theorem 1, but with at the end of this phase, Receiver i, $i = 1, 2$, feeding back only its output to Transmitter i, instead of feeding back its output together with the delayed CSI to Transmitter i.

Phase 2: The communication takes place in $T_2 = M(2M-N)$ channel uses. The transmission scheme is same as that of Phase 2 of the coding scheme of Theorem 1, with the following modifications. The inputs $(\mathbf{x}_1, \mathbf{x}_2)$ from the transmitters and outputs $(\mathbf{y}_1^{(2)}, \mathbf{y}_2^{(2)})$ at the receivers are again given by (14) and (15), respectively. At the end of these phases, Receiver i, $i = 1, 2$, feeds back its output to Transmitter i. At the end of this phase, Receiver 1 requires $(2M-N)T_2$ extra linearly independent equations to successfully decode the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it during this phase. Let $\tilde{\mathbf{y}}_2^{(2)} \in \mathbb{C}^{(2M-N)T_2}$ denote a set of $(2M-N)T_2$ such linearly independent equations, selected among the available NT_2 side information equations $\mathbf{y}_2^{(2)} \in \mathbb{C}^{NT_2}$ (recall that $2M - N \leq N$ in this case). If these equations can be conveyed to Receiver 1, they will suffice to help it decode the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols, since the latter already knows $\mathbf{y}_1^{(1)}$. These equations will be transmitted by (only) Transmitter 2 in Phase 4. Transmitter 2 learns $\mathbf{y}_2^{(2)}$, and so $\tilde{\mathbf{y}}_2^{(2)}$, directly by means of the output feedback from Receiver 2 at the end of this phase.

Phase 3: The communication takes place in $T_2 = M(2M-N)$ channel uses. The transmission scheme is same as that of Phase 3 of the coding scheme of Theorem 1, with the following modifications. The inputs $(\mathbf{x}_1, \mathbf{x}_2)$ from the transmitters and outputs $(\mathbf{y}_1^{(2)}, \mathbf{y}_2^{(2)})$ at the receivers are again given by (16) and (17), respectively. At the end of this phase, Receiver 2 requires $(2M-N)T_2$ extra linearly independent equations to successfully decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols that are intended to it during this phase. Let

$\tilde{\mathbf{y}}_1^{(3)} \in \mathbb{C}^{(2M-N)T_2}$ denote a set of $(2M-N)T_2$ such linearly independent equations, selected among the available NT_2 side information equations $\mathbf{y}_1^{(3)} \in \mathbb{C}^{NT_2}$ (recall that $2M-N \leq N$ in this case). These equations will be transmitted by (only) Transmitter 1 in Phase 4. Transmitter 1 learns $\mathbf{y}_1^{(3)}$, and so $\tilde{\mathbf{y}}_1^{(3)}$, directly by means of the output feedback from Receiver 1 at the end of this phase.

Phase 4: Recall that at the end of Phase 3, Receiver 1 requires the side information output vector $\tilde{\mathbf{y}}_2^{(2)}$, and Receiver 2 requires the side information output vector $\tilde{\mathbf{y}}_1^{(3)}$. In Phase 4, the communication takes place in $T_3 = (2M-N)(2M-N)$ channel uses. During this phase, Transmitter 1 transmits $\mathbf{x}_1 = \Phi_2 \mathbf{y}_1^{(3)}$ and Transmitter 2 transmits $\mathbf{x}_2 = \Phi_1 \mathbf{y}_2^{(2)}$, where $\Phi_1 \in \mathcal{C}^{MT_3 \times NT_2}$, and $\Phi_2 \in \mathcal{C}^{MT_3 \times NT_2}$, in T_3 channel uses.

Decoding: At the end of Phase 4, Receiver 1 gets NT_3 equations in $2MT_3$ variables. Since Receiver 1 knows $\mathbf{y}_1^{(3)}$ from Phase 3 as well as the CSI, it can subtract out the contribution of $\tilde{\mathbf{y}}_1^{(3)}$ from its received signal to obtain the side information output vector $\tilde{\mathbf{y}}_2^{(2)}$. Then, using the pair of output vectors $(\mathbf{y}_1^{(2)}, \tilde{\mathbf{y}}_2^{(2)})$, Receiver 1 first subtracts out the contribution of $\mathbf{y}_1^{(1)}$; and, then, it inverts the resulting $2MT_2$ linearly independent equations relating the sent $2MT_2$ $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols. Thus, Receiver 1 successfully decodes the $\mathbf{v}_{11}$- and $\mathbf{v}_{21}$-symbols that are intended to it. Receiver 2 performs similar operations to successfully decode the $\mathbf{v}_{12}$- and $\mathbf{v}_{22}$-symbols that are intended to it.

The analysis of the sum SDoF that is allowed by the described coding scheme can be obtained by proceeding as in the proof of Theorem 1, to show that $2M^2(2M-N)$ symbols are transmitted securely to Receiver 1 over a total of $T_1 + 2T_2 + T_3 = 2(4M^2 - 3MN + N^2)$ channel uses, thus yielding $d_{11} + d_{21} = M^2(2M-N)/(4M^2 - 3MN + N^2)$ sum SDoF at this receiver. Similar reasoning and algebra show that $d_{12} + d_{22} = M^2(2M-N)/(4M^2 - 3MN + N^2)$ sum SDoF for Receiver 2. This concludes the proof of Theorem 3. □

The analysis so far reflects the utility of both output feedback and delayed CSI that are provided to both transmitters in terms of secure degrees of freedom. However, the models that we have considered so far are *symmetric* in the sense that both transmitters see the same degree of output feedback and delayed CSI from the receivers. The relative importance of output feedback and delayed CSI depends on the studied configuration. In what follows, it will be shown that, in the symmetric model of Theorem 3 one can replace the local output feedback that is provided to one transmitter with delayed CSI given to the other transmitter without diminishing the achievable sum SDoF region.

Remark 8: Investigating closely the coding scheme of Theorem 3, it can be seen that the key ingredient in the achievability proof is that, at the end of the third phase, each of the side information output vector

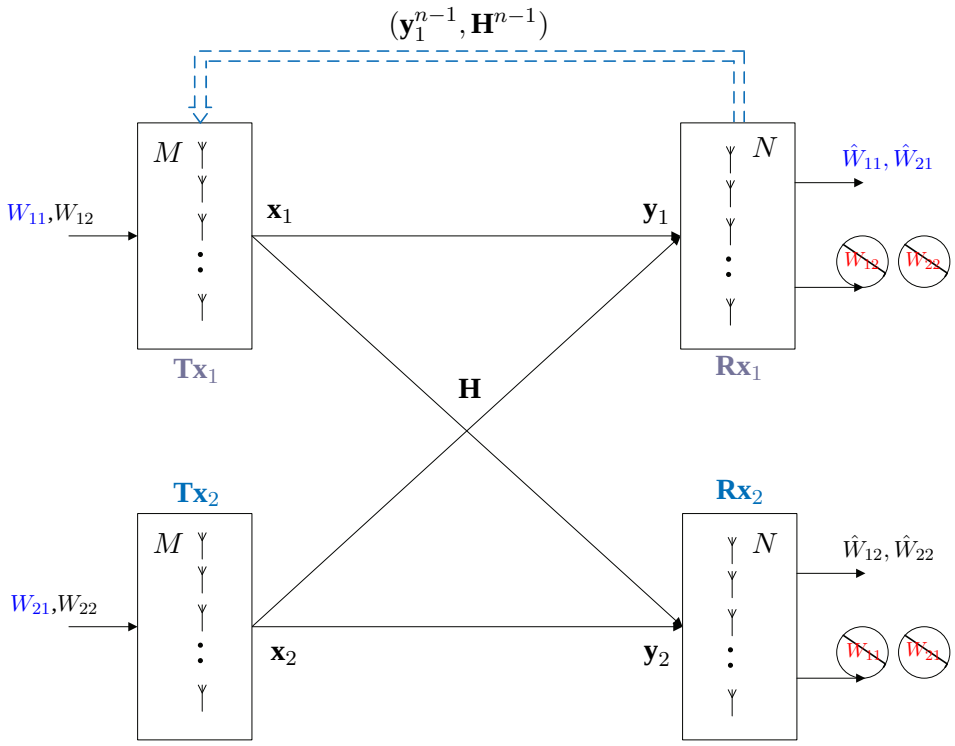

Fig. 4. MIMO X-channel with asymmetric local feedback and delayed CSI with security constraints.

$\tilde{\mathbf{y}}_2^{(2)}$ that is required by Receiver 1 to successfully decode the symbols that are intended to it and the side information output vector $\tilde{\mathbf{y}}_1^{(3)}$ that is required by Receiver 2 to successfully decode the symbols that are intended to it be learned by *exactly* one of the transmitters[1]. In the coding scheme of Theorem 3, the side information output vectors $\tilde{\mathbf{y}}_1^{(3)}$ and $\tilde{\mathbf{y}}_2^{(2)}$ are learned by distinct transmitters at the end of Phase 3. However, the above suggests that the lower bound of Theorem 3 will also remain achievable if these side information output vectors are both learned by the *same* transmitter. Figure 4 shows a variation model that is asymmetric in the sense that local output feedback and delayed CSI are provided only to Transmitter 1. In this model, by means of the output feedback and delayed CSI from Receiver 1, Transmitter 1 can learn *both* side information output vectors $(\tilde{\mathbf{y}}_1^{(3)}, \tilde{\mathbf{y}}_2^{(2)})$ (See the analysis of Phase 2 in the coding scheme of Theorem 1). Taking this into account, it is easy to show that the lower bound of Theorem 3 is also achievable for the model shown in Figure 4.

[1]By opposition, in the coding scheme of Theorem 1, both side information output vectors have been learned by both transmitters at the end of Phase 3, as we mentioned previously.

Proposition 1: For the model with local output feedback and delayed CSI provided only to Transmitter 1 shown in Figure 4, an inner bound on the sum SDoF region is given by Theorem 3.

VI. MIMO-X Channels Without Security Constraints

In this section, we consider an (M, M, N, N)-X channel *without* security constraints. We show that the main equivalences that we established in the previous sections continue to hold.

Theorem 4: The sum DoF region $\mathcal{C}_{\text{DoF}}^{\text{sum}}$ of the two-user (M, M, N, N)–MIMO X-channel with local feedback and delayed CSI is given by the set of all non-negative pairs $(d_{11} + d_{21}, d_{12} + d_{22})$ satisfying

$$\begin{aligned} \frac{d_{11} + d_{21}}{\min(2M, 2N)} + \frac{d_{12} + d_{22}}{\min(2M, N)} &\leq 1 \\ \frac{d_{11} + d_{21}}{\min(2M, N)} + \frac{d_{12} + d_{22}}{\min(2M, 2N)} &\leq 1. \end{aligned} \tag{34}$$

Proof: The converse proof follows immediately from the DoF region of a two-user MIMO BC with delayed CSIT [3, Theorem 2] in which the transmitter is equipped with $2M$ antennas et the receivers are equipped with M antennas each. The proof of the direct part follows by a coding scheme that can be obtained by specializing that of Theorem 1 to the setting without security constraints, and that we only outline briefly here. First, note that the region of Theorem 4 is fully characterized by the corner points $(\min(2M, N), 0)$, $(0, \min(2M, N))$ and the point P defined as the intersection of the lines defining the equations (34). It is not difficult to see that the corner points $(\min(2M, N), 0)$ and $(0, \min(2M, N))$ are achievable without feedback and without delayed CSI, as the system is equivalent to coding for a MIMO multiple access channel for which the achievability follows from straightforward results. We now outline the achievability of the point P. If $2M \leq N$, the point $P = (M, M)$ is clearly achievable. If $N \leq 2M \leq 2N$, the achievability of the point $P = (2NM/(2M+N), 2NM/(2M+N))$ can be obtained by modifying the coding scheme of Theorem 1, essentially by ignoring Phase 1. Note that, at the end of the transmission, $2MN(2M-N)$ symbols are sent to each receiver over $2T_2+T_4 = (2M-N)(2M+N)$, i.e., a sum DoF of $2MN/(2M+N)$ for each. In the case in which $2M \geq 2N$, one can use the coding scheme of the previous case with each transmitter utilizing only N antennas. □

Remark 9: The sum DoF region of Theorem 4 is same as the DoF region of a two-user MIMO BC in which the transmitter is equipped with $2M$ antennas and each receiver is equipped with N antennas, and delayed CSIT is provided to the transmitter [3, Theorem 2]. Thus, similar to Theorem 1, Theorem 4 shows that, in the context of no security constraints as well, the distributed nature of the transmitters in the MIMO X-model with a symmetric antenna configuration does not cause any loss in terms of sum

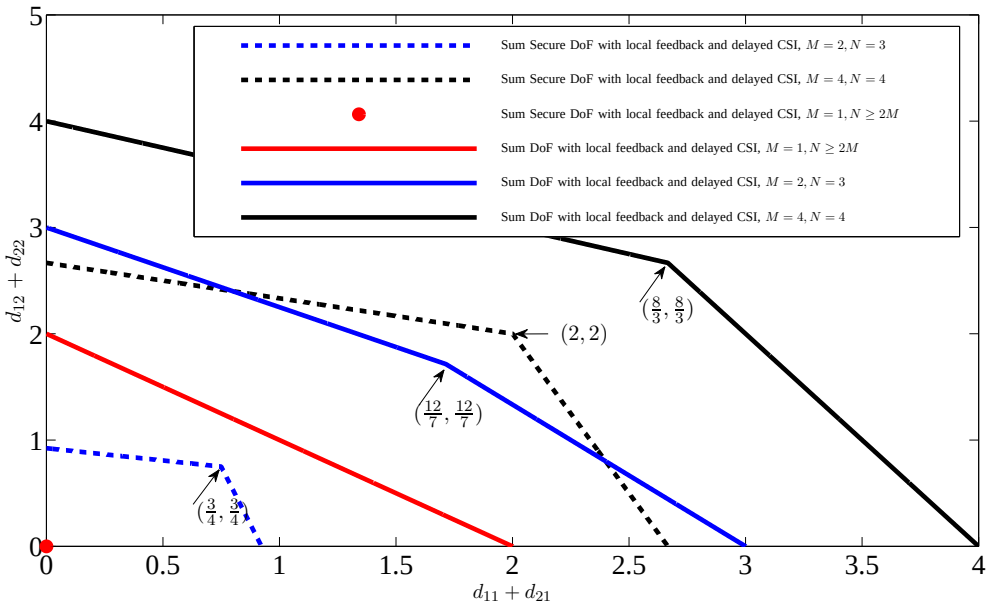

Fig. 5. Sum SDoF and sum DoF regions of the (M, M, N, N)-X channel with local output feedback and delayed CSI, for different antennas configurations.

degrees of freedom. This can be seen as a generalization of [12, Theorem 1] in which it is shown that the loss is zero from a total degrees of freedom perspective.

Remark 10: Like for the setting with secrecy constraints, it can be easily shown that the sum DoF of the (M, M, N, N)-MIMO X-channel with global output feedback is also given by that of Theorem 4.

VII. Numerical Examples

In this section, we illustrate the results of the previous sections (i.e., Theorems 1, 2, 3 and 4) through some numerical examples. We also include comparisons with some previously known results for the MIMO-X channel without security constraints and with different degrees of CSI and output feedback.

Figure 5 illustrates the optimal sum SDoF of the (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI given by Theorem 1, for different values of the transmit- and receive antennas. For comparison reasons, Figure 5 also shows the optimal DoF of the same model, i.e., (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI, but without security constraints, as given by Theorem 1. The gap that is visible in the figure illustrates the rate loss that is caused asymptotically, in the signal-to-noise ratio, in by imposing security constraints on the (M, M, N, N)-MIMO X-channel

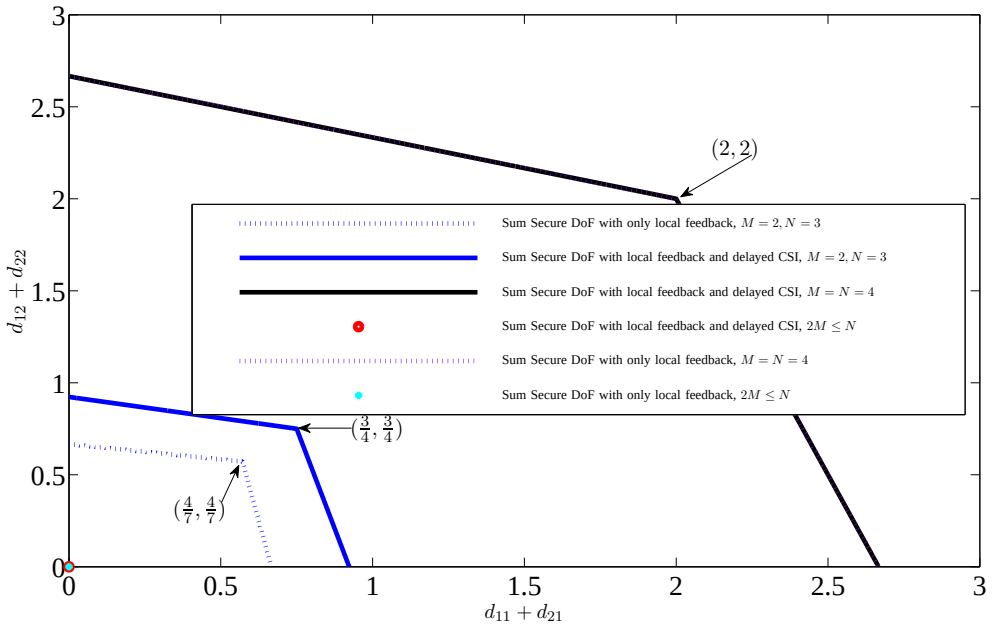

Fig. 6. Sum SDoF region of the (M, M, N, N)-X channel with different degrees of output feedback and delayed CSI, for some antennas configurations.

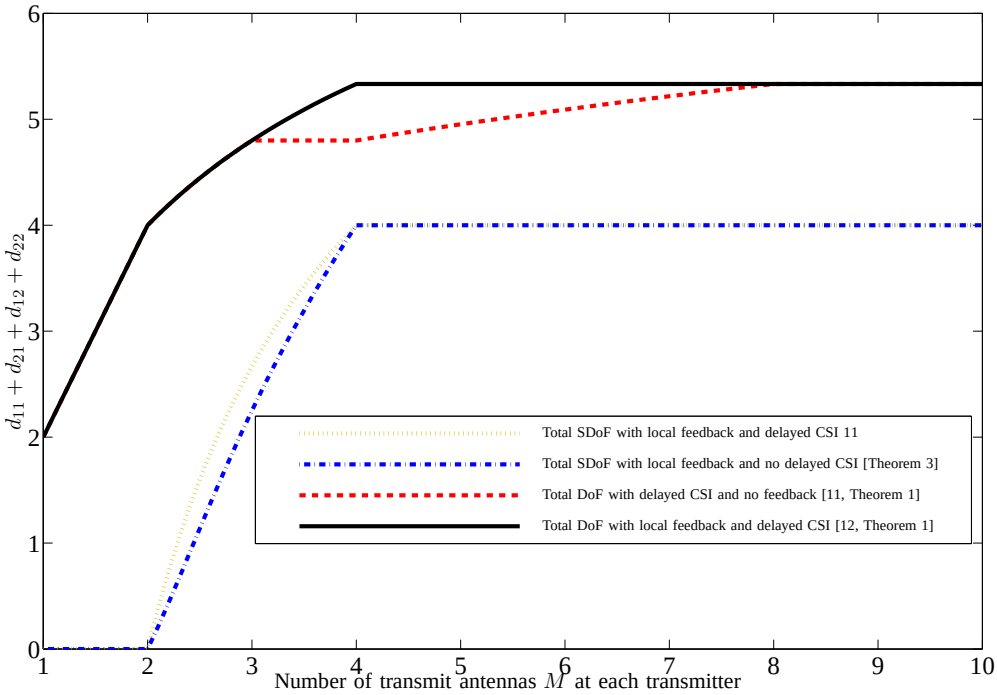

Fig. 7. Total secure degrees of freedom of the MIMO (M, M, N, N)-X channel, as a function of the number of transmit antennas M at each transmitter, for a fixed number $N = 4$ of receive antennas at each receiver.

with local output feedback and delayed CSI. Thus, it can be interpreted as the *price for secrecy* for the model that we study.

Figure 6 shows the inner bound of Theorem 3, for different antennas configurations. As we mentioned previously, although the optimality of the inner bound of Theorem 3 is still to be shown, the loss in terms of secure degrees of freedom that is visible in the figure for $N \leq 2M \leq 2N$ sheds light on the role and utility of providing delayed CSI to the transmitters from a secrecy viewpoint. For $M \geq N$, however, the lack of delayed CSI at the transmitters does not cause any loss in terms of secure degrees of freedom in comparison with the model with output and delayed CSI feedback of Theorem 1.

Figure 7 depicts the evolution of the total secure degrees of freedom of the (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI as function of the number of transmit-antennas M at each transmitter, for a given number of receive-antennas at each receiver $N = 4$. The figure also shows the total secure degrees of freedom with only local feedback provided to the transmitters (obtained from Theorem 3), as well as the total degrees of freedom without security constraints [12, Theorem 1] (which can also be obtained from Theorem 4). Furthermore, the figure also shows the sum DoF of the MIMO X-channel with only delayed CSI, no feedback and no security constraints [11].

VIII. Concluding Remarks

In this paper, we study the sum secure degrees of freedom (sum SDoF) region of a two-user multi-input multi-output X-channel with M antennas at each transmitter and N antennas at each receiver. We assume perfect CSIR, i.e., each receiver has perfect knowledge of its channel. In addition, all the terminals are assumed to know the past channel states of the channel; and there is a noiseless local output feedback at the transmitters, i.e., Receiver i, $i = 1, 2$, feeds back its past channel output to Transmitter i. For this MIMO X-channel with symmetric antennas configuration, we characterize the optimal sum SDoF region. We show that the sum SDoF region of this MIMO-X channel with local feedback and delayed CSI is *same* as the SDoF region of the two-user MIMO BC with $2M$ transmit antennas and N antennas at each receiver. The coding scheme that we use for the proof of the direct part follows through an appropriate extension of a coding scheme that is developed by Yang *et. al.* [37] in the context of secure transmission over MIMO broadcast channels. Furthermore, investigating the role of the delayed CSI at the transmitters, we also study two MIMO X-channel models with no CSI at the transmitters. In the first model, the transmitters have no knowledge of the CSI but are provided with noiseless output feedback from both receivers, i.e., *global* feedback. In the second model, the transmitters are provided by only local feedback. For the model with global output feedback, we show that the sum SDoF is the same

as that of the MIMO X-channel with local feedback and delayed CSI. For the model with only *local* output feedback, we establish an inner bound on the allowed sum SDoF region. Next, we specialize our results to the setting without security constraints, and show that the sum DoF region of an (M, M, N, N)-MIMO X-channel with local output feedback and delayed CSI provided to the transmitters is same as the DoF region of a two-user MIMO BC with $2M$ transmit antennas and N antennas at each receiver. The established results emphasize the usefulness of output feedback and delayed CSI at the transmitters for transmission over a two-user MIMO X-channel with and without security constraints.

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