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A highly anisotropic nonlinear elasticity model for vesicles. II. Derivation of the thin bilayer bending theory

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Benoit Merlet. A highly anisotropic nonlinear elasticity model for vesicles. II. Derivation of the thin bilayer bending theory. 2013. hal-00848552v2

HAL Id: hal-00848552

<https://hal.science/hal-00848552v2>

Preprint submitted on 2 Sep 2014

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Benoît Merlet

A highly anisotropic nonlinear elasticity model for vesicles

II. Derivation of the thin bilayer bending theory

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Abstract We study the thin-shell limit of the nonlinear elasticity model for vesicles introduced in part I. We consider vesicles of width $2\varepsilon \downarrow 0$ with elastic energy of order ε^3 . In this regime, we show that the limit model is a bending theory for generalized hypersurfaces — namely, co-dimension one oriented varifolds without boundary. Up to a positive factor, the limit functional is the Willmore energy. In the language of Γ -convergence, we establish a compactness result, a lower bound result and the matching upper bound in the smooth case.

Keywords Calculus of Variation · Γ -convergence · Willmore functional · Rigidity estimates · Non-linear elasticity · Lipid bilayers

Mathematics Subject Classification (2000) 49Q10 · 49Q15 · 74B20 · 74K25 · 74K25

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1 Introduction

In this article, we study the behavior as ε goes to 0 of the nonlinear elasticity model for vesicle membranes with finite thickness introduced in [11]. More precisely, we perform a Γ -limit analysis of the family of functionals $\mathcal{F}/\varepsilon^3$ where ε is the half-thickness of the membrane. The limit functional will be (up to a positive factor) the Willmore functional defined on generalized hypersurfaces. Let us recall that the Willmore energy of a smooth compact hypersurface without boundary $\Sigma \subset \mathbf{R}^d$ is defined as

$$\mathcal{W}(\Sigma) := \int_{\Sigma} h^2 d\mathcal{H}^{d-1},$$

where h is the mean curvature of Σ .

This second part strongly depends on the first part of the paper. Before stating the main results, we recall the model, set some notation and introduce complementary assumptions. For simplicity, we specialize the model presented in [11] by assuming $\mu = 0$ where μ is the parameter which accounts for the spontaneous curvature of the membrane. However, the general case is addressed in the last section.

1.1 An Eulerian nonlinear elasticity model

Let us fix an integer $d \geq 2$. Given $\varepsilon > 0$, a membrane of thickness 2ε in \mathbf{R}^d is modeled by a bounded open set $\Omega \subset \mathbf{R}^d$ and two mappings $\tau \in L^2(\mathbf{R}^d, \mathbf{R}^d)$ and $\sigma \in L^2(\Omega, \mathbf{R}^d)$. These objects are subjected to a set of constraints: first, we assume that τ is a gradient vector field, more precisely, there exists $t \in W_{loc}^{1,2}(\mathbf{R}^d) \cap C(\mathbf{R}^d, [-\varepsilon, \varepsilon])$ such that $\tau = \nabla t$. Moreover, we assume

$$\Omega = \{y \in \mathbf{R}^d : |t|(y) < \varepsilon\}.$$

To prevent membranes from escaping to infinity, we fix a large radius $R > 0$ and enforce

$$|y| > R \implies t(y) = +\varepsilon.$$

Eventually, we assume that $\nabla \cdot \sigma = 0$ in $\mathcal{D}'(\Omega)$. Outside the set Ω , we extend σ by 0,

$$\sigma(y) := 0 \quad \text{for every } y \in \mathbf{R}^d \setminus \Omega.$$

We denote by $\mathcal{A}_{\varepsilon}(R)$ the set of triplets (σ, τ, Ω) satisfying the above hypotheses and by $\mathcal{A}_{\varepsilon}$ the union $\cup_{R \uparrow \infty} \mathcal{A}_{\varepsilon}(R)$.

The material density at some point $x \in \Omega$ is defined as $\sigma(x) \cdot \tau(x)$ and the total quantity of material is,

$$\mathcal{Q}(\sigma, \tau) := \int_{\mathbf{R}^d} \sigma \cdot \tau.$$

The parameter 2ε should represent the thickness of the vesicle layer, hence the natural definition for the area of the membrane is $\mathcal{Q}(\sigma, \tau)/2\varepsilon$. Given a radius $R > 0$ and a $(d-1)$ -volume $S > 0$, we set

$$\mathcal{A}_{\varepsilon}(R, S) := \{(\sigma, \tau, \Omega) \in \mathcal{A}_{\varepsilon}(R) : \mathcal{Q}(\sigma, \tau) = 2S\varepsilon\}.$$

The elastic energy associated with a configuration $a = (\sigma, \tau, \Omega) \in \mathcal{A}_\varepsilon$ has the form

$$\mathcal{F}(a) := \int_{\Omega} f(\sigma(y), \tau(y)) dy,$$

where $f \in C(\mathbf{R}^d \times \mathbf{R}^d, \mathbf{R}_+)$ depends on the material. In our context, the stored-energy functions f of interest vanish on the sphere

$$\mathbb{S}^{d-1} := \{(e, e) : e \in \mathbb{S}^{d-1}\} \subset \mathbf{R}^d \times \mathbf{R}^d,$$

that is

$$f(\mathbb{S}^{d-1}) = \{0\}. \quad (1.1)$$

For the lower bound part of the Γ -limit analysis, we also require that f does not degenerate with respect to this constraint: we assume that the infimum of $f/d(\cdot, \mathbb{S}^{d-1})^2$ over $\mathbf{R}^d \times \mathbf{R}^d \setminus \mathbb{S}^{d-1}$ is positive. Equivalently, we assume

$$f \geq \kappa f_0, \quad \text{for some constant } \kappa > 0, \quad (1.2)$$

with $f_0(u, v) := |u - v|^2 + (|u| - 1)^2 + (|v| - 1)^2$, for every $u, v \in \mathbf{R}^d$.

The energy functional associated with this particular function is denoted by

$$\mathcal{F}_0(\sigma, \tau, \Omega) := \int_{\Omega} f_0(\sigma(y), \tau(y)) dy.$$

We study the Γ -limit as ε tends to 0 of the energy $\mathcal{F}/\varepsilon^3$ defined on the set $\mathcal{A}_\varepsilon(\mathbf{R}, S)$. For this we consider families $\{a_\varepsilon\}_{\varepsilon \in (0, 1]}$ (or sequences (a_{ε_k}) with $\varepsilon_k \downarrow 0$) of triplets $a_\varepsilon = (\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(\mathbf{R}, S)$ with energy of order of ε^3 :

$$\sup_{\varepsilon} \frac{\mathcal{F}(a_\varepsilon)}{\varepsilon^3} < \infty. \quad (1.3)$$

1.2 Continuity hypothesis

In the proofs, we need a uniform equicontinuity hypothesis which in general does not follow from (1.3) and might be only a technical assumption.

Hypothesis 1 *There exists a modulus of continuity ω (i.e. $\omega : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ is a non-decreasing concave continuous function such that $\omega(0) = 0$) such that*

$$\text{for every } \varepsilon \in (0, 1], \quad t_{(\varepsilon)} : y \in \mathbf{R}^d \mapsto \frac{t_\varepsilon}{\varepsilon}(\varepsilon y) \text{ is } \omega\text{-continuous.}$$

Remark 1.1 The energy bound $\mathcal{F}_0(\sigma, \nabla t, \Omega) < \infty$ is not sufficient for t being continuous. However, in the cases $d = 2$ and $d = 3$, if the stored energy function satisfies

$$f(\sigma, \tau) \geq \kappa' (|\tau| - 1)^p$$

for some $p > d$ and $\kappa' > 0$, then Hypothesis 1 is the consequence of the energy bound (1.3). Indeed, in this case,

$$\int_{(1/\varepsilon)\Omega_\varepsilon} (|\nabla t_{(\varepsilon)}| - 1)^p = \varepsilon^{3-d} \left(\frac{1}{\varepsilon^3} \int_{\Omega_\varepsilon} (|\nabla t_\varepsilon| - 1)^p \right) \leq \left(\sup_{\varepsilon} \frac{\mathcal{F}(a_\varepsilon)}{\varepsilon^3} \right) \frac{\varepsilon^{3-d}}{\kappa'}.$$

Consequently, the family $t_{(\varepsilon)}$ has uniformly bounded gradients in $L^p(\mathbf{R}^d)$ and, by Morrey embedding theorem, is uniformly equi-Hölder-continuous with Hölder exponent $1 - d/p$.

1.3 Compactness

Let us fix $R, S > 0$ and consider a family $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$, $a_\varepsilon = (\sigma_\varepsilon, \tau_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(R, S)$, satisfying Hypothesis 1 and

$$E_0 := \sup_{0 < \varepsilon \leq 1} \frac{\mathcal{F}_0(a_\varepsilon)}{\varepsilon^3} < +\infty. \quad (1.4)$$

Our strategy is to approximate the membrane described by the data a_ε by a smooth hypersurface $\Sigma_\varepsilon = \partial O_\varepsilon$ where O_ε is an open subset of B_R which is close in L^1 to $[t_\varepsilon \equiv -\varepsilon]$ — see Section 2, Proposition 2.1. We obtain uniform bounds on the $(d-1)$ -volume of Σ_ε and on the Willmore energy $\mathcal{W}(\Sigma_\varepsilon)$. Sets of finite perimeter seem reasonable limit objects for the family $\{O_\varepsilon\}$ as up to extraction, (O_ε) converges towards a set with finite perimeter O_0 . Unfortunately, we may lose large pieces of membrane in the limit process: two (or more) pieces of the hypersurface Σ_ε may coincide at the limit $\varepsilon \downarrow 0$, leading to $\mathcal{H}^{d-1}(\partial O_0) < S$. Moreover, if we consider the behavior of the Willmore energy, the limit surface $\Sigma_0 = \partial O_0$ may not have square integrable mean curvature, as cusps arise on the boundary of the cancelling pieces of hypersurface (see Figure 1.1). To keep track of these phenomena and prevent cancellation, we have to take into account multiplicity. We do this by considering hypersurfaces as $(d-1)$ -dimensional varifolds. Varifolds have been introduced as a generalization of manifolds by Almgren [2] for the study of Plateau's problem, (see also Allard [1] and the reference book by Simon [13]). More precisely, here we consider the set of *oriented* $(d-1)$ -varifolds as introduced by Hutchinson [9].

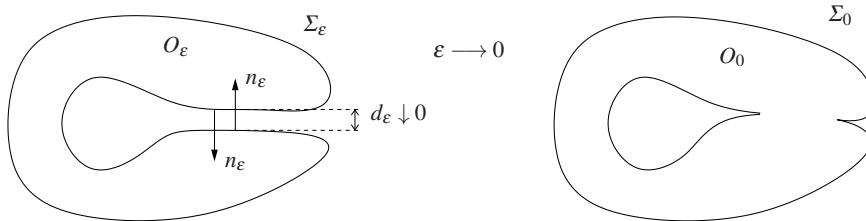


Fig. 1.1 Cancellation of boundaries with opposite orientations.

Definition 1.1

a) The space of oriented $(d-1)$ -varifolds in \mathbf{R}^d is the topological dual of $C_c(\mathbf{R}^d \times S^{d-1})$, that is the space $\mathcal{M}(\mathbf{R}^d \times S^{d-1})$ of Radon measures on $\mathbf{R}^d \times S^{d-1}$ endowed with the weak star topology of Radon measures.

b) To any oriented $(d-1)$ -varifold $\mathcal{V} \in \mathcal{M}(\mathbf{R}^d \times S^{d-1})$, we associate a distribution $\Lambda \mathcal{V} \in \mathcal{D}'(\mathbf{R}^d, \mathbf{R}^d)$ defined by

$$\langle \Lambda \mathcal{V}; \psi \rangle := \langle \mathcal{V}; (y, n) \mapsto \psi(y) \cdot n \rangle, \quad \text{for } \psi \in \mathcal{D}(\mathbf{R}^d, \mathbf{R}^d).$$

c) Given a smooth hypersurface Σ oriented by ν , we define the oriented $(d-1)$ -varifold $\mathcal{V} = \mathcal{V}(\Sigma, \nu)$ by

$$\langle \mathcal{V}; \varphi \rangle := \int_{\Sigma} \varphi(x, \nu(x)) d\mathcal{H}^{d-1}(x), \quad \text{for every } \varphi \in C_c(\mathbf{R}^d \times S^{d-1}).$$

Remark 1.2

a) Usually, oriented k -varifolds are defined as the Radon measures over $\mathbf{R}^d \times G^o(k, d)$, where $G^o(k, d)$ denotes the Grassmannian of oriented k -subspaces of \mathbf{R}^d . Here, we consider varifolds with co-dimension 1 and we can identify any $(d-1)$ -dimensional oriented subspace of \mathbf{R}^d with its positively oriented unit normal. This defines a smooth diffeomorphism $G^o(d-1, d) \xrightarrow{\sim} S^{d-1}$.

b) Similarly, in the literature (see e.g. [9]), one associates with any oriented k -varifold a k -current $\mathcal{C}\mathcal{V}$. Here, we choose not to treat currents explicitly. We identify simple $(d-1)$ vectors of the form $(-1)^{i+1} e^1 \wedge \dots \wedge e^{i-1} \wedge e^{i+1} \wedge \dots \wedge e^d$ with e_i . By duality, this identifies the $(d-1)$ -current $\mathcal{C}\mathcal{V}$ with $\Lambda \mathcal{V}$. In fact, in the present paper the boundary of $\mathcal{C}\mathcal{V}$ always vanishes. With our notation, this amounts to saying that $\Lambda \mathcal{V}$ satisfies the Poincaré conditions $\partial_i[\Lambda \mathcal{V}]_j = \partial_j[\Lambda \mathcal{V}]_i$ for $i, j \in \{1, \dots, d\}$ or equivalently that $\Lambda \mathcal{V}$ is a gradient.

In general the distribution $\Lambda \mathcal{V}$ carries strictly less information than the oriented varifold \mathcal{V} . For instance, if $\Sigma \neq \emptyset$ is a smooth compact hypersurface oriented by ν then $\mathcal{V} := \mathcal{V}(\Sigma, \nu) + \mathcal{V}(\Sigma, -\nu)$ does not vanish but $\Lambda \mathcal{V} \equiv 0$.

c) When Σ is the boundary of a smooth and bounded open set $O \subset \mathbf{R}^d$, with outward unit normal ν , then $\Lambda[\mathcal{V}(\Sigma, \nu)] = -\nabla \mathbf{1}_O$.

Our compactness result concerns varifolds constructed from elements of $\mathcal{A}_{\varepsilon}$.

Definition 1.2 Let us fix a cut-off function $\chi^* \in C_c^\infty(1/2, 2)$ satisfying $\chi^*(1) = 1$. For $\varepsilon \in (0, 1]$, we associate with any element $a = (\sigma, \nabla t, \Omega)$ of $\mathcal{A}_{\varepsilon}$ the oriented varifold,

$$\langle \mathcal{V}_{\varepsilon}^*(a); \varphi \rangle := \frac{1}{2\varepsilon} \int_{\Omega} \chi^*(|\nabla t|(y)) \varphi\left(y, \frac{\nabla t}{|\nabla t|}(y)\right) dy, \quad \forall \varphi \in C(\mathbf{R}^d \times S^{d-1}).$$

Definition 1.3 (Limit set)

The limit set $\mathcal{A}_0(R, S)$ in our Γ -convergence analysis is a set of oriented $(d-1)$ -varifolds. Namely, $\mathcal{V}_0 \in \mathcal{M}(\mathbf{R}^d \times S^{d-1})$ belongs to $\mathcal{A}_0(R, S)$ if there exists a sequence of smooth open sets $(O_k)_{k \geq 1} \subset B_R$ with outward unit normals ν_k and boundaries Σ_k such that

$$\begin{aligned} \sup_k \mathcal{V}(\Sigma_k) &< \infty, & \mathcal{H}^{d-1}(\Sigma_k) &\xrightarrow{k \uparrow \infty} S, \\ \text{and } \mathcal{V}(\Sigma_k, \nu_k) &\xrightarrow{k \uparrow \infty} \mathcal{V}_0 & \text{as Radon measures.} \end{aligned} \quad (1.5)$$

We postpone further definitions and statements about varifolds to Appendix D. Let us say however that the elements of $\mathcal{A}_0(R, S)$ are oriented integer rectifiable $(d-1)$ -varifolds (Definition D.1) which admit a L^2 -generalized mean curvature (Definition D.2). The definition of the Willmore energy extends to these objects as a lower semi-continuous functional on $\mathcal{A}_0(R, S)$.

Theorem 1.1

Let $R, S > 0$ and let $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$ be a family of configurations $a_\varepsilon = (\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(R, S)$ satisfying the energy bound (1.4) and Hypothesis 1. Then:

a) There exists a non-negative oriented $(d-1)$ -varifold \mathcal{V}_0 with total mass S such that, up to extraction,

$$\mathcal{V}_\varepsilon^*(a_\varepsilon) \xrightarrow{\varepsilon \downarrow 0} \mathcal{V}_0 \text{ as Radon measures.}$$

b) There exists a set of finite perimeter $O_0 \subset B_R$, such that

$$\nabla \mathbf{1}_{O_0} = -\Lambda \mathcal{V}_0, \quad \text{and} \quad T_\varepsilon := \frac{\varepsilon - t_\varepsilon}{2\varepsilon} \xrightarrow{\varepsilon \downarrow 0} \mathbf{1}_{O_0} \text{ weakly in } BV(\mathbf{R}^d).$$

c) Moreover, $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$ (hence \mathcal{V}_0 has finite generalized Willmore energy).

Remark 1.3

i. As a consequence of (b), if the interior domain $M_\varepsilon = [t_\varepsilon \equiv -\varepsilon]$ has prescribed volume or merely satisfies $\mathcal{H}^d(M_\varepsilon) \rightarrow V$, then $\mathcal{H}^d(O_0) = V$.

ii. The varifold \mathcal{V}_0 can be described by means of a $(d-1)$ -rectifiable set Σ_0 and multiplicity functions θ_0^\pm . The Willmore energy $\mathcal{W}(\mathcal{V}_0)$ has an explicit expression in terms of the generalized curvature of Σ_0 and θ_0^\pm (see Definition D.1, Definition D.2 and formula (D.9)).

1.4 Lower bound

For the lower bound, we make further assumptions on the stored energy function. Namely, we assume that

$$f \text{ is of class } C^2 \text{ in some neighborhood } \mathcal{N} \text{ of } \mathbb{S}^{d-1} \text{ in } \mathbf{R}^d \times \mathbf{R}^d, \quad (1.6)$$

and is isotropic in this neighborhood, that is

$$f(Q\sigma, Q\tau) = f(\sigma, \tau) \quad \forall Q \in \text{SO}(d), \forall (\sigma, \tau) \in \mathcal{N}. \quad (1.7)$$

This assumption parallels the frame indifference hypothesis in nonlinear elasticity.

Theorem 1.2 Let $R, S > 0$ and let $(a_{\varepsilon_k})_{\varepsilon_k \downarrow 0}$ with $a_{\varepsilon_k} \in \mathcal{A}_{\varepsilon_k}(R, S)$ be a sequence of configurations satisfying Hypothesis 1. Assume that there exists a $(d-1)$ -varifold \mathcal{V}_0 such that $\mathcal{V}_{\varepsilon_k}^*(a_{\varepsilon_k}) \rightarrow \mathcal{V}_0$ as Radon measures.

Then, for every $f \in C(\mathbf{R}^d \times \mathbf{R}^d, \mathbf{R}_+)$ satisfying (1.1), (1.2), (1.6) and (1.7), we have

$$c_0(f)\mathcal{W}(\mathcal{V}_0) \leq \liminf_{\varepsilon_k \downarrow 0} \frac{\mathcal{F}(a_{\varepsilon_k})}{\varepsilon_k^3},$$

where $c_0(f) > 0$ only depends on the Hessian matrix D^2f on \mathbb{S}^{d-1} . Namely,

$$c_0(f) := \frac{\det L}{3L_{2,2}} \quad \text{with} \quad L := \begin{pmatrix} \frac{\partial^2 f}{\partial \sigma_d^2} & \frac{\partial^2 f}{\partial \sigma_d \partial \tau_d} \\ \frac{\partial^2 f}{\partial \sigma_d \partial \tau_d} & \frac{\partial^2 f}{\partial \tau_d^2} \end{pmatrix} (e_d, e_d).$$

1.5 Upper bound in the smooth case

Theorem 1.3 *Let $f \in C(\mathbf{R}^d \times \mathbf{R}^d, \mathbf{R}_+)$ satisfying (1.1), (1.6) and (1.7) and let $O_0 \subset \mathbf{R}^d$ be a smooth bounded open subset with boundary Σ_0 and outward unit normal ν_0 . Let us define*

$$R := \sup\{|y| : y \in O_0\} + 1 \quad \text{and} \quad S := \mathcal{H}^{d-1}(\Sigma_0).$$

Then there exists a family $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$, $a_\varepsilon \in \mathcal{A}_\varepsilon(R, S)$, such that

$$\mathcal{V}_\varepsilon^*(a_\varepsilon) \xrightarrow{\varepsilon \downarrow 0} \mathcal{V}(\Sigma_0, \nu_0) \text{ as Radon measures and } c_0(f) \mathcal{W}(\Sigma_0) = \lim_{\varepsilon \downarrow 0} \frac{\mathcal{F}(a_\varepsilon)}{\varepsilon^3}.$$

Moreover, noting $a_\varepsilon = \{\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon\}$, the open sets Ω_ε and the vector fields σ_ε and ∇t_ε are uniformly smooth. In particular Hypothesis 1 holds.

We expect the above upper bound to hold true for any element of the limit set $\mathcal{A}_0(R, S)$ and not only for smooth compact oriented manifolds, however the construction of a recovery family in the general case is a seemingly difficult open problem, see Section 5.

1.6 Notation

We present here the main conventions adopted in this work. The reader will find a list of notation in lexicographic order at the end of the article

Throughout the paper, the letter C denotes a non-negative constant which is either a universal constant or only depends on the dimension d . For constants which also depend on other parameters, $\alpha_1, \dots, \alpha_k$, we write $C(\alpha_1, \dots, \alpha_k)$. As usual, the values of these constants may change from line to line. For constants which depend on the data introduced in the hypotheses (the dimension d , the prescribed $(d-1)$ -volume S , the modulus of continuity ω , the cut-off function χ^* or the energy upper bound E_0) but not on ε , we use the short hand C_ε and we write $C_\varepsilon(\alpha_1, \dots, \alpha_k)$ for constants also depending on other parameters. This convention extends to other objects which only depend on ω and d , namely: the modulus of continuity ω_ε^* of Lemma 2.3, the positive number δ_ε^* of Corollary 2.1 and the functions $\beta_{\varepsilon,1}^*$, $\beta_{\varepsilon,2}^*$, $\beta_{\varepsilon,3}^*$ introduced in Lemmas 2.4, 2.5, 2.6.

We write $B_r(y)$ to denote the open ball in \mathbf{R}^d with center y and radius $r > 0$ or simply B_r for $B_r(0)$.

The $(d-1)$ -dimensional unit sphere of \mathbf{R}^d is denoted by S^{d-1} .

The k -dimensional Hausdorff measure of a set $E \subset \mathbf{R}^d$ is denoted by $\mathcal{H}^k(E)$.

We often define the set of elements satisfying a property \mathcal{P} by $[\mathcal{P}]$. For instance $[t = \varepsilon]$ is the set $\{y \in \mathbf{R}^d : t(y) = \varepsilon\}$.

Most of the time, we use y or z to denote a generic element of \mathbf{R}^d whereas x is always a point on a hypersurface.

For $e \in S^{d-1}$, π_e denotes the orthogonal projection on the space $e^\perp = \{y \in \mathbf{R}^{d-1} : y \cdot e = 0\}$, that is $\pi_e(y) = y - (y \cdot e)e$.

We identify e_d^\perp with \mathbf{R}^{d-1} and for $y \in \mathbf{R}^d$, we write $y' = (y_1, \dots, y_{d-1}) = \pi_{e_d}y$, so that $y = (y', y_d)$.

Some objects introduced along the proofs are used in different and sometimes distant parts of the paper. These objects are singled out by means of a superscript star: ω_ε^* , U^* , etc. We have already met the cut-off function χ^* in Definition 1.2.

We use the prefix ‘‘I’’ to refer to a result of the first part of this article. For instance, Theorem 2.1 in [11] is referred as Theorem I.2.1.

1.7 Outline of the paper

In Section 2, we establish the compactness result Theorem 1.1. The main part of this section is devoted to the proof of Proposition 2.1 which contains the relevant constructions and estimates. In particular, we use the rigidity estimates of [11] to show that we can approximate the varifolds $\{\mathcal{V}^*(a_\varepsilon)\}_\varepsilon$ by oriented hypersurfaces $\{(\Sigma_\varepsilon, \nu_\varepsilon)\}_\varepsilon$ with uniformly bounded Willmore energy.

In Section 2.6, we establish Theorem 1.1 as a consequence of Proposition 2.1 and of Allard’s compactness theorem for integer rectifiable varifolds applied to the family of oriented hypersurfaces $\{(\Sigma_\varepsilon, \nu_\varepsilon)\}_\varepsilon$.

In Section 3, we build a recovery sequence in the smooth case, proving Theorem 1.3. We also describe there the general form of the Hessian matrix of our anisotropic stored energy functions on the set \mathbb{S}^{d-1} .

Section 4 is devoted to the proof of the lower bound of Theorem 1.2. In Section 4.1, we introduce an approximate mean curvature at the ε -level. At some point $x \in \Sigma_\varepsilon$, this approximate mean curvature only depends on the restriction of σ_ε to the ball $B_{\sqrt{2}\varepsilon}(x)$. We show that this approximate curvature is indeed an approximation of the mean curvature on Σ_ε in a weak sense. Again, the rigidity estimates are crucial in this step. In Section 4.2 we pass to the limit $\varepsilon \downarrow 0$ using lower semi-continuity of the Willmore energy. This reduces the lower bound problem to a relatively easy local optimization problem: minimize the local energy under prescribed approximate mean curvature.

In Section 5, we discuss the hypotheses and indicate possible generalizations and open problems. In particular, we consider the case of a material with spontaneous curvature $\mu \neq 0$ by substituting the condition $\nabla \cdot [(\rho(\mu t_\varepsilon))^{-1} \sigma_\varepsilon] \equiv 0$ for the condition $\nabla \cdot \sigma_\varepsilon \equiv 0$.

In Appendices A, B and C we prove some ancillary results stated in the main text. In Appendix D we introduce further material concerning varifolds. The aim

of the latter is to provide a better understanding of the limit set $\mathcal{A}_0(R, S)$ and to define the Willmore energy of generalized hypersurfaces.

2 Compactness: approximation by hypersurfaces, proof of Theorem 1.1

Let $R, S > 0$ and let us consider a family $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$ satisfying the hypotheses of Theorem 2.1. In this section, for every ε , we build a smooth open set O_ε with boundary Σ_ε and outward unit normal ν_ε such that O_ε is close in L^1 to $[t_\varepsilon \equiv -\varepsilon]$ and $\mathcal{V}(\Sigma_\varepsilon, \nu_\varepsilon)$ is close to $\mathcal{V}_\varepsilon^*(a_\varepsilon)$. The relevant uniform bounds and properties of these families are collected in Proposition 2.1 below whose proof occupies Sections 2.1 to 2.5. We deduce Theorem 1.1 from the proposition in Section 2.6.

Proposition 2.1

a) For every $\varepsilon \in (0, 1]$,

$$\left| \frac{1}{2\varepsilon} \mathcal{H}^d(\Omega_\varepsilon) - S \right| + \left| \frac{1}{2\varepsilon} \int_{\mathbf{R}^d} |\nabla t_\varepsilon| - S \right| + |\langle \mathcal{V}_\varepsilon^*(a_\varepsilon); 1 \rangle - S| \leq C_\varepsilon \varepsilon.$$

b) For every $\varepsilon \in (0, 1]$, there exists a smooth bounded open set $O_\varepsilon \subset B_{R+C\varepsilon}$ with outward unit normal ν_ε , such that, using the notation $\Sigma_\varepsilon := \partial O_\varepsilon$ and $M_\varepsilon := \{y \in \mathbf{R}^d : t_\varepsilon(y) = -\varepsilon\}$, we have

$$\|\mathbf{1}_{O_\varepsilon} - \mathbf{1}_{M_\varepsilon}\|_{L^1} \leq C_\varepsilon \varepsilon, \quad \mathcal{H}^{d-1}(\Sigma_\varepsilon) \leq C_\varepsilon, \quad \mathcal{W}(\Sigma_\varepsilon) \leq C_\varepsilon.$$

c) For every $\varphi \in C(\mathbf{R}^d \times \mathbf{R}^d)$ such that $\sup_{y,n} |\varphi(y, n)| / (1 + |n|^2) < \infty$, we have

$$\left| \frac{1}{2\varepsilon} \int_{\Omega_\varepsilon} \varphi(y, \nabla t_\varepsilon(y)) dy - \int_{\Sigma_\varepsilon} \varphi(x, \nu_\varepsilon(x)) d\mathcal{H}^{d-1}(x) \right| \xrightarrow{\varepsilon \downarrow 0} 0.$$

Except in the proof of part (c) of the proposition (Section 2.5), the parameter $\varepsilon \in (0, 1]$ is fixed. In this case, it is convenient to rescale the domain by a factor $1/\varepsilon$ by setting $\Omega_{(\varepsilon)} := \varepsilon^{-1} \Omega_\varepsilon$. We also define the rescaled data:

$$t_{(\varepsilon)}(y) := \varepsilon^{-1} t_\varepsilon(\varepsilon y), \quad \tau_{(\varepsilon)}(y) := \nabla t_\varepsilon(\varepsilon y), \quad \sigma_{(\varepsilon)}(y) := \sigma_\varepsilon(\varepsilon y) \quad \text{for } y \in \mathbf{R}^d.$$

With this notation, the function $t_{(\varepsilon)} \in C(\mathbf{R}^d, [-1, 1])$ is ω -continuous, we have $\nabla t_{(\varepsilon)} = \tau_{(\varepsilon)}$ and $\Omega_{(\varepsilon)} = \{y \in \mathbf{R}^d : |t_{(\varepsilon)}(y)| < 1\}$. The vector field $\sigma_{(\varepsilon)}$ is divergence free in $\Omega_{(\varepsilon)}$ and vanishes in $\mathbf{R}^d \setminus \Omega_{(\varepsilon)}$. We also have,

$$\begin{aligned} \mathcal{Q}(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}) &= \int_{\mathbf{R}^d} \sigma_{(\varepsilon)} \cdot \nabla t_{(\varepsilon)} = 2S/\varepsilon^{d-1}, \\ \text{and } \mathcal{F}_0(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}, \Omega_{(\varepsilon)}) &\leq E_0/\varepsilon^{d-3}. \end{aligned} \quad (2.1)$$

Part (a) is established in Section 2.1. In Section 2.2, we introduce the harmonic extension $u_{(\varepsilon)}$ of $t_{(\varepsilon)}$ in a subset of $\Omega_{(\varepsilon)}$ which contains $[|t_{(\varepsilon)}| < 4/5]$. The level sets of $u_{(\varepsilon)}$ are candidates for the hypersurface $\Sigma_{(\varepsilon)}$.

In Section 2.3 we state and prove some technical lemmas which follow from the weak rigidity estimates of [11]. These lemmas are designed for selecting the

“good” points where the data is sufficiently close to a zero energy limit state, as described in Theorem I.1.1. We also state there all the consequences of the strong rigidity estimates which are relevant to our purpose. Eventually, we bound the volume of “bad” regions. All these results are also used in the proof of the lower bound in Section 4.

In Section 2.4, we build the set $O_{(\varepsilon)}$ (and therefore the hypersurface $\Sigma_{(\varepsilon)}$) and we prove the estimates of part (b). Eventually, the convergence result (c) is established in Section 2.5.

To lighten notation, we drop all the subscripts (ε) and write t for $t_{(\varepsilon)}$, σ for $\sigma_{(\varepsilon)}$, Ω for $\Omega_{(\varepsilon)}$, *etc.* We come back to the unambiguous notation at the beginning of Section 2.5 when considering the limit $\varepsilon \downarrow 0$.

2.1 Proof of Proposition 2.1. a

For $-1 \leq \alpha_- < \alpha_+ \leq 1$, we set

$$\Omega_{\alpha_-}^{\alpha_+} := \left\{ y \in \mathbf{R}^d : \alpha_- < t(y) < \alpha_+ \right\} \subset \Omega.$$

Lemma 2.1 *Let $-1 \leq \alpha_- < \alpha_+ \leq 1$, we have*

$$\int_{\Omega_{\alpha_-}^{\alpha_+}} \nabla t \cdot \sigma = (\alpha_+ - \alpha_-)S/\varepsilon^{d-1}. \quad (2.2)$$

Moreover,

$$\left| \mathcal{H}^d(\Omega_{\alpha_-}^{\alpha_+}) - \frac{(\alpha_+ - \alpha_-)S}{\varepsilon^{d-1}} \right| \leq \frac{5}{2} \mathcal{F}_0(\sigma, \nabla t, \Omega_{\alpha_-}^{\alpha_+}) + 2 \sqrt{\frac{S \mathcal{F}_0(\sigma, \nabla t, \Omega_{\alpha_-}^{\alpha_+})}{\varepsilon^{d-1}}}, \quad (2.3)$$

and similarly,

$$\left| \int_{\Omega_{\alpha_-}^{\alpha_+}} |\nabla t| - \frac{(\alpha_+ - \alpha_-)S}{\varepsilon^{d-1}} \right| \leq 4 \mathcal{F}_0(\sigma, \nabla t, \Omega_{\alpha_-}^{\alpha_+}) + 4 \sqrt{\frac{S \mathcal{F}_0(\sigma, \nabla t, \Omega_{\alpha_-}^{\alpha_+})}{\varepsilon^{d-1}}}. \quad (2.4)$$

Before proving the lemma let us show that it implies Proposition 2.1.a. Applying (2.3) and (2.4) with $\alpha_{\pm} = \pm 1$, unscaling and taking into account (2.1), we obtain

$$\left| \frac{1}{2\varepsilon} \mathcal{H}^d(\Omega_{\varepsilon}) - S \right| + \left| \frac{1}{2\varepsilon} \int_{\mathbf{R}^d} |\nabla t_{\varepsilon}| - S \right| \leq C_{\sharp} \varepsilon. \quad (2.5)$$

Next, we have

$$\langle \mathcal{V}_{\varepsilon}^*(a_{\varepsilon}); 1 \rangle = \frac{1}{2\varepsilon} \int_{\Omega_{\varepsilon}} \chi^*(|\nabla t_{\varepsilon}|(y)) dy.$$

Since $|\chi^*(\tau) - 1| \leq C|\tau - 1|$, we get

$$\begin{aligned} |\langle \mathcal{V}_{\varepsilon}^*(a_{\varepsilon}); 1 \rangle - S| &\leq \frac{C}{2\varepsilon} \int_{\Omega_{\varepsilon}} ||\nabla t_{\varepsilon}| - 1| + \left| \frac{1}{2\varepsilon} \mathcal{H}^d(\Omega_{\varepsilon}) - S \right| \\ &\stackrel{(1.4),(2.5)}{\leq} C \sqrt{\mathcal{H}^d(\Omega_{\varepsilon})/2\varepsilon} \sqrt{E_0} \varepsilon + C_{\sharp} \varepsilon \stackrel{(2.5)}{\leq} C_{\sharp} \varepsilon. \end{aligned} \quad (2.6)$$

Proposition 2.1.a follows from (2.5),(2.6).

Proof (of Lemma 2.1) Let us first establish that for every smooth open set O such that

$$\{x \in \mathbf{R}^d : t(x) > -1\} \subset O \subset \{x \in \mathbf{R}^d : t(x) < 1\},$$

we have

$$\int_{\partial O} \sigma \cdot \nu = S/\varepsilon^{d-1}, \quad (2.7)$$

where ν denotes the outward unit normal on ∂O and $\sigma \cdot \nu$ is well defined in $H^{-1/2}(\partial O)$ as the trace on ∂O of the normal component of $\sigma \in H_{\text{div}}(\Omega) = \{\sigma' \in L^2(\Omega, \mathbf{R}^d) : \text{div } \sigma' \in L^2(\Omega)\}$.

Now, notice that the identity

$$\int_O \nabla \varphi \cdot \sigma = \int_{\partial O} \varphi \sigma \cdot \nu, \quad (2.8)$$

is valid for every $\varphi \in C^\infty(\overline{\Omega})$ such that $\varphi \equiv 0$ in the neighborhood of $[t = -1]$. In order to extend this formula to the case $\varphi = t + 1$, we introduce for $s \in (0, 1)$, the truncated function t_s defined as

$$t_s(y) := \begin{cases} t(y) & \text{if } |t(y)| \leq 1 - s, \\ \pm(1 - s) & \text{if } \pm t(y) > 1 - s. \end{cases}$$

By continuity of t , the function $\varphi_s := t_s + (1 - s) \in W^{1,2}(\Omega)$ vanishes in the neighborhood of $[t = -1]$. Consequently, φ_s belongs to the closure in $W^{1,2}$ of $\{\varphi \in C^\infty(\overline{\Omega}) : \text{supp } \varphi \cap [t \leq -1] = \emptyset\}$ and (2.8) is valid with $\varphi = \varphi_s$.

$$\int_O \nabla t_s \cdot \sigma = \int_{\partial O} (t_s + (1 - s)) \sigma \cdot \nu.$$

Letting $s \downarrow 0$, since $t_s \rightarrow t$ in $W_{loc}^{1,2}(\mathbf{R}^d)$, we obtain,

$$\int_O \nabla t \cdot \sigma = \int_{\partial O} (t + 1) \sigma \cdot \nu.$$

Similarly, integrating $\nabla(t_s - (1 - s)) \cdot \sigma$ on $\Omega \setminus \overline{O}$ and passing to the limit $s \downarrow 0$, we also get,

$$\int_{\Omega \setminus \overline{O}} \nabla t \cdot \sigma = \int_{\partial O} (-t + 1) \sigma \cdot \nu.$$

Summing these identities, we obtain $2 \int_{\partial O} \sigma \cdot \nu = \int_{\Omega} \nabla t \cdot \sigma$. By hypothesis, the value of the latter is $2S/\varepsilon^{d-1}$, so (2.7) holds true.

1/ Let us establish (2.2). By hypothesis, this identity is true for $(\alpha_-, \alpha_+) = (-1, 1)$. Let us first assume $-1 < \alpha_- < \alpha_+ < 1$ and let O be a smooth bounded open set such that

$$[t \leq \alpha_+] \subset O \subset [t < 1].$$

For instance, we may slightly mollify t and invoke Sard theorem to define O as a smooth sublevel set of the smooth approximation of t . Now let us introduce the truncated function,

$$\tilde{t}(y) := \begin{cases} t(y) & \text{if } \alpha_- \leq t(y) \leq \alpha_+, \\ \alpha_{\pm} & \text{if } \pm t(y) > \alpha_{\pm}. \end{cases}$$

As above, (2.8) is valid with $\varphi = \tilde{t} - \alpha_-$ and we have,

$$\int_{\Omega_{\alpha_-}^{\alpha_+}} \nabla t \cdot \sigma = \int_{\Omega_{\alpha_-}^{\alpha_+}} \nabla \tilde{t} \cdot \sigma = (\alpha_+ - \alpha_-) \int_{\partial O} \sigma \cdot \nu \stackrel{(2.7)}{=} (\alpha_+ - \alpha_-) S / \varepsilon^{d-1}.$$

Hence, identity (2.2) holds in the case $-1 < \alpha_- < \alpha_+ < 1$. The remaining cases follow by continuity of the integral.

2/ We are ready to establish (2.3). Let $-1 \leq \alpha_- < \alpha_+ \leq 1$. By (2.2), the left hand side of (2.3) is bounded by $\int_{\Omega_{\alpha_-}^{\alpha_+}} |1 - \nabla t \cdot \sigma|$.

To estimate this integral, we write

$$\begin{aligned} |1 - \nabla t \cdot \sigma| &= |(1 - |\nabla t|^2) + (1 - |\sigma|^2) + |\nabla t - \sigma|^2| / 2 \\ &\leq |1 - |\nabla t|| + |1 - |\sigma|| + [(1 - |\nabla t|)^2 + (1 - |\sigma|)^2 + |\nabla t - \sigma|^2] / 2. \end{aligned} \quad (2.9)$$

Integrating on $\Omega_{\alpha_-}^{\alpha_+}$ and using the Cauchy-Schwarz inequality, we obtain,

$$\left| X^2 - (\alpha^+ - \alpha^-) S / \varepsilon^{d-1} \right| \leq \sqrt{2F_0} X + F_0 / 2,$$

with the notation:

$$F_0 := \mathcal{F}_0(\sigma, \nabla t, \Omega_{\alpha_-}^{\alpha_+}), \quad X := \sqrt{\mathcal{H}^d(\Omega_{\alpha_-}^{\alpha_+})}.$$

In particular we have $X^2 - \sqrt{2F_0} X \leq 2S / \varepsilon^{d-1} + F_0 / 2$ which yields $X \leq (\sqrt{2F_0} + \sqrt{8S / \varepsilon^{d-1} + 2F_0}) / 2$. Substituting this in the right hand side of the above estimate, we obtain,

$$\left| X^2 - \frac{(\alpha^+ - \alpha^-) S}{\varepsilon^{d-1}} \right| \leq (3/2) F_0 + \sqrt{F_0^2 + 4F_0 S / \varepsilon^{d-1}} \leq (5/2) F_0 + 2\sqrt{F_0 S / \varepsilon^{d-1}},$$

that is (2.3).

Similarly, the left hand side of (2.4) is bounded by $\int_{\Omega_{\alpha_-}^{\alpha_+}} \|\nabla t - \nabla t \cdot \sigma\|$.

Writing $\|\nabla t - \nabla t \cdot \sigma\| \leq |1 - \nabla t \cdot \sigma| + \|\nabla t - 1\|$, we get $\int_{\Omega_{\alpha_-}^{\alpha_+}} \|\nabla t - \nabla t \cdot \sigma\| \leq \sqrt{5F_0} X + F_0 / 2$ which yields (2.4). \square

2.2 Construction of a harmonic extension of t_ε . Definition of Σ^s

Recall that ω is the modulus of continuity of Hypothesis 1. Let $\delta > 0$ be the largest number such that

$$\delta \leq 1/4, \quad \omega(\delta) \leq 1/10. \quad (2.10)$$

Then we define

$$\Omega'_{(\varepsilon)} := \left\{ y \in \mathbf{R}^d : |t_{(\varepsilon)}|(y) < 9/10 \right\}, \quad F'_{(\varepsilon)} := \mathbf{R}^d \setminus \Omega'_{(\varepsilon)},$$

and

$$O_{(\varepsilon),\delta} := \left\{ y \in \mathbf{R}^d : d(y, F'_{(\varepsilon)}) > \delta \right\}, \quad F_{(\varepsilon),\delta} := \overline{\bigcup_{y \in F'_{(\varepsilon)}} B_\delta(y)} = \mathbf{R}^d \setminus O_{(\varepsilon),\delta}.$$

Notice that $[|t| < 4/5] \subset O_{(\varepsilon),\delta}$ or equivalently, $t \geq 4/5$ in $F_{(\varepsilon),\delta}$. More precisely, for $y \in F'_{(\varepsilon)}$, we have $t \geq 4/5$ on $\overline{B_\delta(y)}$ if $t(y) \geq 9/10$ and $t \leq -4/5$ on $\overline{B_\delta(y)}$ if $t(y) \leq -9/10$.

We introduce the harmonic extension $u_{(\varepsilon)}$ of $t_{(\varepsilon)}$ in $O_{(\varepsilon),\delta}$. Its level sets are good candidates for the hypersurface $\Sigma_{(\varepsilon)} = (1/\varepsilon)\Sigma_\varepsilon$ of Proposition 2.1.b.

Definition 2.1 We set $u_\varepsilon(y) = \varepsilon u_{(\varepsilon)}(y/\varepsilon)$, where $u_{(\varepsilon)}$ is defined as

$$u_{(\varepsilon)} := \operatorname{argmin} \left\{ \int_{\mathbf{R}^d} |\nabla \varphi|^2 : \varphi \in W_{loc}^{1,2}(\mathbf{R}^d), \varphi \equiv t_{(\varepsilon)} \text{ a.e on } F_{(\varepsilon),\delta} \right\}.$$

Remark 2.1

a) The definition of $u_{(\varepsilon)}$ is valid since the feasible domain of the minimization problem contains at least $t_{(\varepsilon)}$.

b) We do not define $u_{(\varepsilon)}$ as the harmonic extension of $t_{(\varepsilon)}$ in $\Omega_{(\varepsilon)}$ for two reasons.

- First, in the sequel, we need u_ε to be equal to t_ε in a large part of Ω_ε . Thanks to the definition of $\Omega'_{(\varepsilon)}$, this property holds true in the set $[9/10 < |t_{(\varepsilon)}| < 1]$. When we will apply the rigidity estimates of [11] to $u_{(\varepsilon)}$ and $t_{(\varepsilon)}$ in domains intersecting $[9/10 < |t_{(\varepsilon)}| < 1]$, this will allow us to use the same averaged normal direction for both vector fields $\nabla u_\varepsilon, \nabla t_\varepsilon$.

- We also need $u_{(\varepsilon)}$ to be uniformly equicontinuous (independently of ε). For this, we define the harmonic extensions $u_{(\varepsilon)}$ in domains satisfying uniformly the exterior ball property. This is the reason for the introduction of the sets $O_{(\varepsilon),\delta}$ which have the exterior ball property with radius δ .

Definition 2.2

a) For $-1/2 < s < 1/2$, we set $\Sigma_\varepsilon^{s\varepsilon} := \varepsilon \Sigma_{(\varepsilon)}^s$ where $\Sigma_{(\varepsilon)}^s$ is the level set

$$\Sigma_{(\varepsilon)}^s := \{x \in O_{(\varepsilon),\delta} : u_{(\varepsilon)}(x) = s\}.$$

b) For every $z \in O_{(\varepsilon),\delta}$, we set

$$n_{(\varepsilon)}(z) := \begin{cases} \frac{\nabla u_{(\varepsilon)}}{|\nabla u_{(\varepsilon)}|}(z) & \text{if } \nabla u_{(\varepsilon)}(z) \neq 0, \\ e_d & \text{if } \nabla u_{(\varepsilon)}(z) = 0. \end{cases}$$

Remark 2.2

Since $u_{(\varepsilon)}$ is harmonic in the neighborhood of $\Sigma_{(\varepsilon)}^s$, this set is an analytic surface with unit normal $n_{(\varepsilon)}$ in the neighborhood of $\{x \in \Sigma_{(\varepsilon)}^s : \nabla u_{(\varepsilon)}(x) \neq 0\}$.

In the sequel, we drop again the subscripts (ε) : we note u for $u_{(\varepsilon)}$, O_δ for $O_{(\varepsilon),\delta}$, n for $n_{(\varepsilon)}$ and Σ^s for $\Sigma_{(\varepsilon)}^s$, etc. We first establish that ∇u is close to ∇t .

Lemma 2.2 *We have*

$$\int_{\mathbf{R}^d} |\nabla u - \sigma|^2 \leq E_0 \varepsilon^{3-d} \quad \text{and} \quad \int_{\mathbf{R}^d} |\nabla u - \nabla t|^2 \leq 4E_0 \varepsilon^{3-d}.$$

Proof Since σ is divergence free in O_δ , we easily check that u minimizes the functional

$$J(\varphi) := \int_{\mathbf{R}^d} |\nabla \varphi - \sigma|^2.$$

in $\{\varphi \in W_{loc}^{1,2}(\mathbf{R}^d) : \varphi \equiv t \text{ in } F_\delta\}$. Using $\varphi = t$, the energy bound (2.1) yields,

$$\int_{\mathbf{R}^d} |\nabla u - \sigma|^2 = J(u) \leq J(t) \leq E_0.$$

The second estimates then follows from (2.1) and the triangular inequality. \square

Let us notice that, by construction, $O_\delta \subset B_R$ satisfies the exterior ball property with radius δ . As a consequence, we can use the Perron method to obtain the existence of a function $\tilde{u} \in C(\overline{O_\delta})$ which is harmonic in O_δ and satisfies $\tilde{u} \equiv t$ on ∂O_δ — see e.g. [7] Theorem 2.14. By the maximum principle, we have $\tilde{u} = u$, hence u is continuous on $\overline{O_\delta}$. Thereafter we also need u to be uniformly continuous with a modulus of continuity that does not depend on ε . This is the content of the next lemma. We did not find the relevant precise statements in the literature. For the sake of completeness, we provide a proof in Appendix A.

Lemma 2.3 *There exists a modulus of continuity ω_ξ^* only depending on ω and d such that u is ω_ξ^* -continuous on \mathbf{R}^d .*

Recall that, in F_δ , we have $|t| \geq 4/5$, so as a consequence of the lemma, the level sets $\{\Sigma^s\}_{-1/2 < s < 1/2}$ lie at a positive distance from F_δ .

Corollary 2.1 *For $-1/2 < s < 1/2$, we have*

$$d(\Sigma^s, F_\delta) \geq \delta_\xi^*, \quad \text{with } \delta_\xi^* := \max\{r : \omega_\xi^*(r) \leq 2/5\}.$$

In particular, δ_ξ^ only depends on ω and d .*

2.3 Good cylinders. Bad balls

We use here the weak rigidity inequalities of [11] (Theorems I.2.2 and I.1.1) to show that t_ε and u_ε are close to some affine function in the neighborhood of points with small local energy. These results are gathered in Lemmas 2.4, 2.5 and 2.6 below whose proof is postponed to Appendix B. They allow us to select the *good* points where it is possible to carry out the computations and to derive the main estimates leading to the compactness (and lower bound) results. Then, in Lemma 2.7, we bound the volume of “bad” regions.

Definition 2.3 The local energy in an open set $O \subset \mathbf{R}^d$ is defined as

$$\mathcal{E}(O) := \int_{O \cap \Omega} f_0(\sigma, \nabla t) + |\nabla u - \nabla t|^2.$$

When O is the open ball $B_\lambda(y) \subset \mathbf{R}^d$, we use the short hand,

$$\mathcal{E}_\lambda(y) := \mathcal{E}(B_\lambda(y)) = \int_{\Omega \cap B_\lambda(y)} f_0(\sigma, \nabla t) + |\nabla u - \nabla t|^2.$$

We first show that if $z \in \Omega$ is such that $\mathcal{E}_3(z)$ is small enough, then $\Omega - z$ contains a cylinder of the following form.

Definition 2.4 For $\lambda > 0$ and $\bar{n} \in S^{d-1}$, $D'_\lambda(\bar{n})$ denotes the $(d-1)$ -ball,

$$\{y' \in \mathbf{R}^d : |y'| < \lambda, y' \cdot \bar{n} = 0\} = B_\lambda \cap \bar{n}^\perp.$$

For $\lambda > 1$, $\xi \in [0, 1)$ and $\bar{n} \in S^{d-1}$, $D_\lambda^\xi(\bar{n})$ denotes the finite cylinder

$$\{y' + s\bar{n} : y' \in D'_\lambda(\bar{n}), |s| < 1 - \xi\}.$$

Using rotation invariance, we often consider the case $\bar{n} = e_d$, for which we simply write D'_λ for $D'_\lambda(e_d)$ and D_λ^ξ for

$$D_\lambda^\xi(e_d) = \{y \in \mathbf{R}^d : |y_d| < 1 - \xi, \sum_{i < d} y_i^2 < \lambda^2\}.$$

Lemma 2.4 Let $\xi \in (0, 1/2)$, and $\eta > 0$. There exists $\beta = \beta_{\xi, 1}^*(\xi, \eta)$ such that if $z \in \mathbf{R}^d$ satisfies $|u(z)| \leq 1/2$ and $\mathcal{E}_3(z) \leq \beta$, then, $|\nabla u(z)| \geq 1/2$ and using the notation

$$z_0 := z - u(z)n(z), \quad D := z_0 + D_1^\xi(n(z)), \quad \varphi(y) = u(z) + (y - z) \cdot n(z),$$

we have,

(a) $\bar{D} \subset \Omega$ (see Figure 2.1) and

$$\|t - \varphi\|_{L^\infty(\bar{D})} + \|u - \varphi\|_{L^\infty(\bar{D})} + \|\nabla t - \nabla \varphi\|_{L^2(D)} + \|\sigma - \nabla \varphi\|_{L^2(D)} \leq \eta;$$

(b) there exists an analytic mapping $\Psi : D'_1(n(z)) \times (-1/2, 1/2) \rightarrow \mathbf{R}$ such that $\|\Psi\|_{C^2} \leq \eta$ and for every $s \in (-1/2, 1/2)$,

$$\Sigma^s \cap D = [z_0 + sn(z)] + \{y' + \Psi(y', s)n(z) ; y' \in D'_1(n(z))\}.$$

(c) As a consequence,

$$0 \leq \mathcal{H}^{d-1}(\Sigma^s \cap D) - \mathcal{H}^{d-1}(D'_1) \leq c_\xi^*(\eta),$$

with $c_\xi^*(\eta) \downarrow 0$ as $\eta \downarrow 0$.

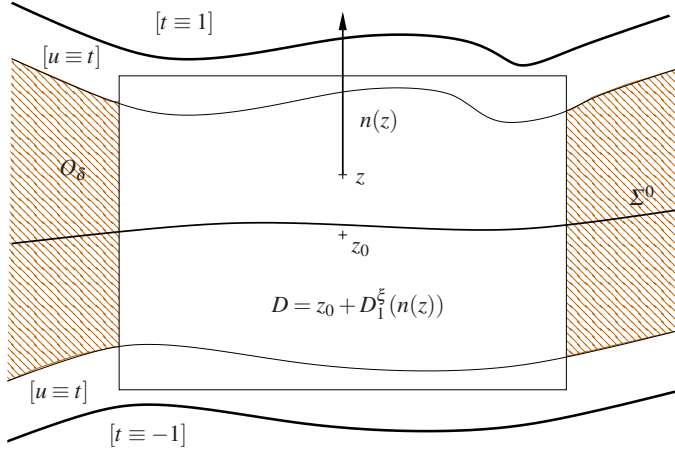


Fig. 2.1 Example of “good” cylinder in dimension $d = 2$.

When establishing the lower bound of Theorem 1.2 in Section 4, we apply the weak and strong rigidity inequalities in the cylindrical boxes of Lemma 2.4. It is convenient to gather the relevant estimates here.

Lemma 2.5 *Let $\xi \in (0, 1/4)$. There exists $\beta = \beta_{\sharp, 2}^*(\xi)$ such that if $x \in \Sigma^0$ satisfies $\mathcal{E}_3(x) \leq \beta$, then using the notation $n(x) = \bar{n}$ and*

$$D_{int} := x + D_{1-2\xi}^{2\xi}(\bar{n}) \subset D := x + D_1^\xi(\bar{n}),$$

we have:

(a) $\bar{D} \subset \Omega$;

(b)

$$|II|^4(x) + |h|^2(x) \leq C\mathcal{E}(D). \quad (2.11)$$

(c) *There exists a harmonic function $\psi: D_{int} \rightarrow \mathbf{R}$ satisfying $\nabla\psi(x) = 0$, $\bar{n} \cdot \nabla\psi \equiv 0$,*

$$\int_{D_{int}} |\nabla\psi|^2 \leq C(\xi)\sqrt{\mathcal{E}(D)}, \quad (2.12)$$

and such that

$$\int_{D_{int}} |\nabla u - \bar{n} - \nabla\psi|^2 + |\nabla t - \bar{n} - \nabla\psi|^2 + |\sigma - \bar{n} - \nabla\psi|^2 \leq C(\xi)\mathcal{E}(D). \quad (2.13)$$

In the sequel, we perform some changes in the order of integration for which we are led to consider the sets

$$\Gamma^\xi(z) := \{x \in \Sigma^0 : z \in x + D_1^\xi(n(x))\}.$$

The purpose of next lemma is to estimate the $(d - 1)$ -volumes of these sets.

Lemma 2.6 *Let $\xi \in (0, 1/2)$ and $\eta > 0$. There exists $\beta = \beta_{\xi,3}^*(\xi, \eta) > 0$ such that if $z \in \mathbf{R}^d$ satisfies*

$$|t(z)| \leq 1 - \xi \quad \text{and} \quad \mathcal{E}_3(z) \leq \beta,$$

then the function $x \in \Sigma^0 \mapsto |x - z|^2$ admits a unique minimizer $x \in \Sigma^0$ and we have $z = x + sn(x)$ with $|s - t(z)| < \eta$. Moreover, using the notation of Lemma 2.4,

$$\Gamma^\xi(z) = \{x + y + \Psi(y, 0)n(x) : y \in X\},$$

for some open subset X of $n(x)^\perp$ such that

$$D'_{1-\eta}(n(x)) \subset X \subset D'_{1+\eta}(n(x)).$$

In particular,

$$\left| \mathcal{H}^{d-1}(\Gamma^\xi(z)) - \mathcal{H}^{d-1}(D'_1) \right| \leq C\eta. \quad (2.14)$$

We now bound the total volume of points which do not satisfy the assumption $\mathcal{E}_3(x) < \beta$. Let us fix $\beta > 0$ and let us define the sets of good and bad points as

$$\mathcal{G}_\beta := \{x \in \mathbf{R}^d : \mathcal{E}_3(x) \leq \beta\}, \quad \mathcal{B}_\beta := \mathbf{R}^d \setminus \mathcal{G}_\beta.$$

Lemma 2.7 *There exists a finite number of disjoint balls $B_3(y_1), \dots, B_3(y_N) \subset \mathbf{R}^d$ such that*

$$\mathcal{B}_\beta \subset U_\beta := \bigcup_{i=1}^N B_9(y_i), \quad \text{with} \quad N \leq C_\# \varepsilon^{3-d} / \beta.$$

Proof Since the total energy $\mathcal{E}_{+\infty}(0)$ is bounded by $CE_0 \varepsilon^{3-d}$, the lemma classically follows from Vitali covering theorem. \square

As a consequence of the bound on N we have $\mathcal{H}^d(U_\beta) \leq C_\#(\beta) \varepsilon^{3-d}$ and more generally, for $\beta > 0, \lambda \geq 1$,

$$\mathcal{H}^d\left(\bigcup_{i=1}^N B_{9\lambda}(y_i)\right) \leq C_\#(\beta, \lambda) \varepsilon^{3-d}.$$

In the sequel, we use this inequality without further reference.

2.4 Definition and properties of the hypersurface Σ_ε . Proof of Proposition 2.1.b

Before beginning, let us sketch our construction of the hypersurface $\Sigma_{(\varepsilon)}$.

- *Step 0.* We introduce a bad set $U_{(\varepsilon)}^b$ of points with local energy larger than a fixed value $\beta > 0$. We also define the larger open set $U_{(\varepsilon)}^* := U_{(\varepsilon)}^b + B_9$ and the good set $G_{(\varepsilon)}^* := \mathbf{R}^d \setminus U_{(\varepsilon)}^*$.
- *Step 1.* Then, we define $\Sigma_{(\varepsilon)}$ in $G_{(\varepsilon)}^*$ as $\Sigma_{(\varepsilon)}^* := G_{(\varepsilon)}^* \cap \Sigma_{(\varepsilon)}^0 = G_{(\varepsilon)}^* \cap [u_{(\varepsilon)} \equiv 0]$.
- *Step 2.* Next, we use Corollary I.2.1 to find a level set $\Sigma_{(\varepsilon)}^b$ such that $\Sigma_{(\varepsilon)}^b \cap U_{(\varepsilon)}^b$

satisfies convenient bounds. We then set $\Sigma_{(\varepsilon)}^b := \Sigma_{(\varepsilon)}^{s^b} \cap U_{(\varepsilon)}^b$.

• *Step 3.* Eventually, we complete the construction of $\Sigma_{(\varepsilon)}^b \cup \Sigma_{(\varepsilon)}^*$ by adding a smooth hypersurface in the gap $U_{(\varepsilon)}^* \setminus U_{(\varepsilon)}^b$ with boundary $\partial \Sigma_{(\varepsilon)}^* \cup \partial \Sigma_{(\varepsilon)}^b \subset \partial U_{(\varepsilon)}^* \cup \partial U_{(\varepsilon)}^b$.

In Steps 1–3, we also control the volume and the Willmore energy of the respective pieces of hypersurface.

Step 0. Let us fix $\xi = \eta = 1/4$. With the notation of Corollary I.3.1, Lemma 2.4 and Lemma 2.7, we define,

$$\beta := \min(\beta_{\xi,1}^*(\xi, \eta), \beta_{\xi,2}^*(\xi)), \quad U^b := U_\beta = \bigcup_{i=1}^N B_\vartheta(y_i). \quad (2.15)$$

Let us recall that $N \leq C_\xi \varepsilon^{3-d}$. We also note

$$U^* := \bigcup_{i=1}^N B_{18}(y_i), \quad G^* := \mathbf{R}^d \setminus U^*.$$

Step 1. We set,

$$\Sigma^* := \Sigma^0 \cap G^*.$$

By Lemma 2.4, Σ^* is an analytic hypersurface. Moreover, $\Sigma^* \subset B_{R/\varepsilon}$ and its boundary lies on the spheres $\partial B_{18}(y_i)$.

Now, for every $x \in \Sigma^*$, we have by Corollary 2.1, $B_{\delta_\xi^*}(x) \subset O_\delta$ and applying Corollary I.3.1 with $\varphi = u$ in the ball $B_{\delta_\xi^*}(x)$, we obtain

$$|h|^2(x) \leq \frac{C}{\delta_\xi^{*(2+d)}} \int_{B_{\delta_\xi^*}(x)} (|\nabla u| - 1)^2,$$

where h denotes the mean curvature on Σ^* . Integrating on Σ^* , and using Fubini, we get

$$\int_{\Sigma^*} |h|^2 d\mathcal{H}^{d-1} \leq \frac{C}{\delta_\xi^{*(2+d)}} \int_{G^* + B_{\delta_\xi^*}} \mathcal{H}^{d-1}(B_{\delta_\xi^*}(y) \cap \Sigma^0) (|\nabla u|(y) - 1)^2 dy.$$

By Lemma 2.4.b, we have

$$\mathcal{H}^{d-1}(B_{\delta_\xi^*}(y) \cap \Sigma^0) \leq C \text{ for every } y \text{ such that } d(y, \Sigma^*) < \delta_\xi^*.$$

Hence,

$$\int_{\Sigma^*} |h|^2 d\mathcal{H}^{d-1} \leq \frac{C}{\delta_\xi^{*(2+d)}} \int_{\mathbf{R}^d} (|\nabla u|(y) - 1)^2 dy \leq C_\xi \varepsilon^{3-d}. \quad (2.16)$$

Similarly, using Lemma 2.4.b and Lemma 2.1, we obtain,

$$\mathcal{H}^{d-1}(\Sigma^*) \leq C \mathcal{H}^d(\Omega_{(\varepsilon)}) \leq C S \varepsilon^{1-d} + C_\xi \varepsilon^{2-d}. \quad (2.17)$$

Step 2. We now define the hypersurface Σ^* inside the balls $B_{18}(y_i)$. Let us first consider the union of interior balls $U^b = \cup B_9(y_i) \subset\subset U^*$. By Corollary 2.1, for any point $y \in \mathbf{R}^d$ such that $|u(y)| < 1/2$, we have $B_{\delta_\xi^*}(y) \subset O_\delta$, that is u is harmonic in $B_{\delta_\xi^*}(y)$. For such a point y , we can apply Corollary I.2.1.b to u in $B_{\delta_\xi^*}(y)$. We get

$$\int_{\mathbf{R}} \int_{\Sigma^s \cap B_{\delta_\xi^*/2}(y)} |II_s|^2 d\mathcal{H}^{d-1} ds \leq C(\delta_\xi^*) \int_{B_{\delta_\xi^*}(y)} \|\nabla u\| - 1,$$

where II_s denotes the second fundamental form on Σ^s . Applying Vitali covering theorem to a cover of $\{y \in U : |u(y)| < 1/2\}$ with balls of the form $B_{\delta_\xi^*/3}(y)$ and summing the estimates, we deduce,

$$\int_{-1/2}^{1/2} \int_{\Sigma^s \cap U} |II_s|^2 d\mathcal{H}^{d-1} ds \leq C(\delta_\xi^*) \int_{U^*} \|\nabla u\| - 1.$$

Next, by Cauchy-Schwarz inequality,

$$\int_{-1/2}^{1/2} \int_{\Sigma^s \cap U} |II_s|^2 d\mathcal{H}^{d-1} ds \leq C(\delta_\xi^*) \sqrt{\mathcal{H}^d(U^*)} \int_{\mathbf{R}^d} (|\nabla u| - 1)^2 \leq C_\xi \varepsilon^{3-d}.$$

On the other hand, by Corollary I.2.1.a, we have

$$\int_{\mathbf{R}} \mathcal{H}^{d-1}(\Sigma^s \cap U) ds \leq \mathcal{H}^d(U) + C_\xi \varepsilon^{3-d} \leq C_\xi \varepsilon^{3-d}.$$

Let us now introduce a small parameter $s_0 \in (0, 1/4)$ to be fixed later. From the above bounds, there exists $s^b \in [-s_0, s_0]$ such that $\Sigma^b := \Sigma^{s^b} \cap U^b$ is an analytic hypersurface satisfying

$$\mathcal{H}^{d-1}(\Sigma^b) + \int_{\Sigma^b} |II^b|^2 d\mathcal{H}^{d-1} \leq C_\xi \varepsilon^{3-d}/s_0. \quad (2.18)$$

Step 3. We have to build a hypersurface in $U^* \setminus U^b$ connecting Σ^* to Σ^b . For this, let us introduce a nonincreasing cut-off function $\chi \in C^\infty(\mathbf{R}_+)$ such that $\chi \equiv 1$ on $[0, 1]$, $\chi \equiv 0$ on $[3, +\infty)$ and $0 \geq \chi' \geq -1$. We also introduce a nondecreasing truncating function $T \in C^\infty(\mathbf{R}_+)$ such that $T(0) = 0$, $T \equiv 1$ on $[1, +\infty)$ and $0 \leq T' \leq 2$. We then set

$$\Sigma := \{x \in \mathbf{R}^d : u(x) - s^b \theta(x) = 0\} \quad \text{with} \quad \theta(y) := T \left(\sum_{i=1}^N \chi(d(y, B_9(y_i))) \right).$$

Since $\theta \equiv 1$ in U^b and $\theta \equiv 0$ in G^* , we obviously have $\Sigma \cap G^* = \Sigma^*$, $\Sigma \cap U^b = \Sigma^b$ and in fact $\Sigma = \Sigma^{s^b}$ in some neighborhood of $\overline{U^b}$, $\Sigma = \Sigma^0$ in some neighborhood of G^* . Notice that the balls $B_3(y_i)$ are disjoint. Hence, there exists $K \geq 0$, only depending on d such that the number $P(y)$ of non-zero elements in the sum which defines $\theta(y)$ is bounded by K .

Let us note $w(y) = u(y) - s^b \theta$ and let us fix $z \in \Sigma \cap [U^* \setminus U]$. We compute at point z ,

$$|\nabla w|(z) \geq |\nabla u|(z) - |s^b| |\nabla \theta|(z) \geq 1/2 - 2|s^b| P(z) \|\chi'\|_\infty \geq 1/2 - 2Ks_0.$$

Now, we fix

$$s_0 := 1/(8K),$$

so that

$$|\nabla w|(z) \geq 1/4.$$

Consequently, $\Sigma = w^{-1}(\{0\})$ is a smooth hypersurface.

Let us now estimate the $(d-1)$ -volume and the L^2 norm of the second fundamental form of $\Sigma \cap [U^* \setminus U]$. We consider again a point $z \in \Sigma \cap [U^* \setminus U]$. We have $|u(z)| \leq |s^b| \leq 1/4$ and by construction, $\mathcal{E}_3(z) \leq \beta_{\xi,1}^*(1/4, 1/4)$ so we can apply Lemma 2.4 at this point with $\xi = \eta = 1/4$. Assuming without loss of generality that $z = 0$, $n(z) = e_d$ and using the notation of Lemma 2.4.b we have for $y' \in D'_1$ and $-1/2 < s < 1/2$,

$$w(y' + se_d) = 0 \iff \Psi(y', s^b \theta(y' + se_d)) = s.$$

Now, let us set,

$$Z(y', s) := s - \Psi(y', s_* \theta(y' + se_d)), \quad \text{for } y' \in D'_1, -1/2 \leq s \leq 1/2.$$

We have $\pm Z(y', \pm 1/2) \geq 1/2 - \eta = 1/4 > 0$ and $\frac{d}{ds} Z(y', s) \geq 1 - \eta |s_0| \|\theta'\|_\infty \geq 15/16 > 0$, so for every $y' \in D'_1$, the equation $Z(y', s) = 0$ admits a unique solution $s = \zeta(y')$. In other words, $[D'_1 \times (-1/2, 1/2)e_d] \cap \Sigma$ is the graph of the mapping ζ . By regularity of Ψ and θ , we also have

$$\|\nabla \zeta\|_\infty \leq C, \quad \|D^2 \zeta\|_\infty \leq C.$$

We deduce the inequality

$$\mathcal{H}^{d-1}([D'_1 \times (-1/2, 1/2)e_d] \cap \Sigma) + \int_{[D'_1 \times (-1/2, 1/2)e_d] \cap \Sigma} |\mathbb{H}|^2 d\mathcal{H}^{d-1} \leq C.$$

Using Vitali covering theorem and the bound $\mathcal{H}^d(U^*) \leq C_\varepsilon \varepsilon^{3-d}$, we get,

$$\mathcal{H}^{d-1}(\Sigma \cap U^*) + \int_{\Sigma \cap U^*} |\mathbb{H}|^2 d\mathcal{H}^{d-1} \leq C_\varepsilon \varepsilon^{3-d}. \quad (2.19)$$

Taking into account (2.16), (2.17), (2.18) and (2.19), we have established

$$\mathcal{H}^{d-1}(\Sigma) \leq CS\varepsilon^{1-d} + C_\varepsilon, \quad \text{and } \mathcal{W}(\Sigma) \leq C_\varepsilon \varepsilon^{3-d}. \quad (2.20)$$

Eventually, we set $M := \{y \in \mathbf{R}^d : t(y) = -1\}$ and $O := \{y \in \mathbf{R}^d : w(y) = u(y) - s_* \theta(y) < 0\}$. We have $O \subset B_{R/\varepsilon}$ and $\partial O = \Sigma$. Moreover, taking into account Lemma 2.1 and the bound $\mathcal{H}^d(U^*) \leq C_\varepsilon \varepsilon^{3-d}$, we have

$$\|\mathbf{1}_O - \mathbf{1}_M\|_{L^1} \leq 2S\varepsilon^{1-d} + C_\varepsilon \varepsilon^{2-d}. \quad (2.21)$$

Putting back the subscripts (ε) , we note $\Sigma_{(\varepsilon)} := \Sigma$, $O_{(\varepsilon)} := O$, $M_{(\varepsilon)} := M$, $U_{(\varepsilon)}^* := U^*$ and $G_{(\varepsilon)}^* := G^*$. Returning to the original variables, we set $\Sigma_\varepsilon := (1/\varepsilon)\Sigma_{(\varepsilon)}$, $O_\varepsilon := (1/\varepsilon)O_{(\varepsilon)}$ and $M_\varepsilon := (1/\varepsilon)M_{(\varepsilon)}$. Unscaling the inequalities (2.20)(2.21), we obtain the estimates of Proposition 2.1.b.

Further conclusions. For later use, we remark here that

$$\mathcal{H}^{d-1}(B_1(y) \cap \Sigma_{(\varepsilon)}) \leq C, \quad \text{for every } y \in G^*. \quad (2.22)$$

Indeed, by construction, $B_1(y) \cap \Sigma_{(\varepsilon)} = B_1(y) \cap \Sigma_{(\varepsilon)}^0$ for every $y \in G_{(\varepsilon)}^*$ and we can apply Lemma 2.4.b to any point $z \in B_1(y) \cap \Sigma_{(\varepsilon)}$.

In the sequel, we consider bad sets which write, using the notation of Lemma 2.7, as $\mathcal{U}_{(\varepsilon)} = U_{(\varepsilon),\beta'}$. We deduce from Lemma 2.7 (2.19) and (2.22) that

$$\mathcal{H}^{d-1}\left(\Sigma_{(\varepsilon)} \cap \left(U_{(\varepsilon)}^* \cup \mathcal{U}_{(\varepsilon)}\right)\right) \leq C_\varepsilon(\beta')\varepsilon^{3-d}.$$

More generally, for $\lambda > 0$, we have

$$\mathcal{H}^{d-1}\left(\Sigma_{(\varepsilon)} \cap \left[\left(U_{(\varepsilon)}^* \cup \mathcal{U}_{(\varepsilon)}\right) + B_\lambda\right]\right) \leq C_\varepsilon(\beta', \lambda)\varepsilon^{3-d}. \quad (2.23)$$

2.5 Proof of Proposition 2.1.c

In the previous section, we have built the open sets O_ε and Σ_ε satisfying the estimates of Proposition 2.1.b. We now establish Proposition 2.1.c. Let $\varphi \in C(\mathbf{R}^d \times \mathbf{R}^d)$ such that $\sup[|\varphi(y, v)|/(1 + |v|^2)] < \infty$. In scaled variables, we have to prove that

$$\varepsilon^{d-1} \left| \frac{1}{2} \int_{\Omega_{(\varepsilon)}} \varphi(\varepsilon z, \nabla t_{(\varepsilon)}(z)) dz - \int_{\Sigma_{(\varepsilon)}} \varphi(\varepsilon x, \nu_{(\varepsilon)}(x)) d\mathcal{H}^{d-1}(x) \right| \xrightarrow{\varepsilon \downarrow 0} 0. \quad (2.24)$$

Proof (of (2.24))

Step 1. Mollification of φ

Let us introduce the quantities,

$$\mathcal{Q}_{(\varepsilon)}[\varphi] := \frac{1}{2} \int_{\Omega_{(\varepsilon)}} \varphi(\varepsilon z, \nabla t_{(\varepsilon)}(z)) dz, \quad \mathcal{Q}'_{(\varepsilon)}[\varphi] := \int_{\Sigma_{(\varepsilon)}} \varphi(\varepsilon x, \nu_{(\varepsilon)}(x)) d\mathcal{H}^{d-1}(x).$$

Let $\chi \in C_c^\infty(\mathbf{R}^d, [0, 1])$ be a cut-off function satisfying $\chi \equiv 1$ in B_2 and let us set $\varphi'(y, v) = \chi(v)\varphi(y, v)$. We obviously have $\mathcal{Q}'_{(\varepsilon)}[\varphi'] = \mathcal{Q}'_{(\varepsilon)}[\varphi]$. On the other hand, we compute

$$\varepsilon^{d-1} |\mathcal{Q}_{(\varepsilon)}[\varphi'] - \mathcal{Q}_{(\varepsilon)}[\varphi]| \leq \frac{\varepsilon^{d-1}}{2} \int_{\|\nabla t_{(\varepsilon)}\| > 2} |\varphi|(\varepsilon z, \nabla t_{(\varepsilon)}(z)) dz.$$

Since $|\varphi|(y, \nu) \leq C(\varphi)(|\nu| - 1)^2$ for $|\nu| > 2$, this leads to,

$$\varepsilon^{d-1} |Q_{(\varepsilon)}[\varphi' - \varphi]| \leq \frac{C(\varphi)\varepsilon^{d-1}}{2} \int_{\Omega_{(\varepsilon)}} (|\nabla t_{(\varepsilon)}| - 1)^2 \leq \frac{C(\varphi)E_0\varepsilon^2}{2} \xrightarrow{\varepsilon \downarrow 0} 0.$$

As a consequence, we may assume that φ is compactly supported in $B_{R+1} \times B_4$.

Let $\tilde{\varphi} \in C_c(\mathbf{R}^d \times \mathbf{R}^d)$, we deduce from the estimates of Proposition 2.1.b,

$$\begin{aligned} \varepsilon^{d-1} |Q_{(\varepsilon)}[\tilde{\varphi} - \varphi]| &\leq \varepsilon^{d-1} \mathcal{H}^d(\Omega_{(\varepsilon)}) \|\tilde{\varphi} - \varphi\|_\infty / 2 \leq C_\xi \|\tilde{\varphi} - \varphi\|_\infty, \\ \varepsilon^{d-1} |Q'_{(\varepsilon)}[\tilde{\varphi} - \varphi]| &\leq \varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma_{(\varepsilon)}) \|\tilde{\varphi} - \varphi\|_\infty \leq C_\xi \|\tilde{\varphi} - \varphi\|_\infty. \end{aligned}$$

Thus, by density, we may also assume that φ is smooth and compactly supported.

Step 2. Cut-off procedure.

From now on, we consider a fixed test function $\varphi \in \mathcal{D}(\mathbf{R}^d \times \mathbf{R}^d)$. In order to ease the estimate below, we perform partitions of \mathbf{R}^d into good sets and bad sets. Let us introduce a small parameter $\xi \in (0, 1/2)$ and let us set

$$\Omega_{(\varepsilon)}^{\xi/2} := \{z \in \Omega_{(\varepsilon)} : |t_{(\varepsilon)}|(z) < 1 - \xi/2\}.$$

By Lemma 2.4 and Lemma 2.5, there exists $\beta_a > 0$ only depending on ξ such that if $x \in \Sigma_{(\varepsilon)}^0$ satisfies $\mathcal{E}_{(\varepsilon),3}(x) < \beta_a$ then

$$x + D_1^\xi(n_{(\varepsilon)}(x)) \subset \Omega_{(\varepsilon)}^{\xi/2},$$

and we have the estimate,

$$\frac{1}{\mathcal{H}^d(D_1^0)} \int_{[x + D_1^\xi(n_{(\varepsilon)}(x))]} |\nabla t_{(\varepsilon)}(z) - n_{(\varepsilon)}(x)| dz \leq \xi. \quad (2.25)$$

Now, for $z \in \Omega_{(\varepsilon)}^{\xi/2}$, we set

$$q_{(\varepsilon)}^\xi(z) := \frac{1}{\mathcal{H}^d(D_1^0)} \int_{\Sigma_{(\varepsilon)}^0} \theta^\xi(z - x, n_{(\varepsilon)}(x)) d\mathcal{H}^{d-1}(x),$$

where for $\bar{n} \in S^{d-1}$, $y \mapsto \theta^\xi(y, \bar{n})$ denotes the characteristic function of $D_1^\xi(\bar{n})$.

By Lemma 2.6 there exists $\beta_b > 0$ only depending on ξ such that if $z \in \Omega_{(\varepsilon)}^{\xi/2}$ satisfies $\mathcal{E}_{(\varepsilon),3}(z) < \beta_b$, then

$$|q_{(\varepsilon)}^\xi(z) - 1| \leq \xi. \quad (2.26)$$

Let us set $\beta := \min(\beta_a, \beta_b)$ and let us define the bad sets

$$\mathcal{U}_{(\varepsilon),\xi} := \left[U_{(\varepsilon)}^* \cup U_{(\varepsilon),3,\beta} \right] + B_3 \subset \mathcal{U}'_{(\varepsilon),\xi} := \mathcal{U}_{(\varepsilon),\xi} + B_6,$$

and the corresponding good sets

$$\mathcal{G}_{(\varepsilon),\xi} := \mathbf{R}^d \setminus \mathcal{U}_{(\varepsilon),\xi} \quad \supset \quad \mathcal{G}'_{(\varepsilon),\xi} := \mathbf{R}^d \setminus \mathcal{U}'_{(\varepsilon),\xi}.$$

By Lemma 2.7, we have

$$\mathcal{H}^{d-1}(\mathcal{U}'_{(\varepsilon),\xi}) \leq C_{\sharp}(\xi) \varepsilon^{3-d}. \quad (2.27)$$

We now introduce a cut-off function $\chi_{(\varepsilon),\xi} \in C^\infty(\mathbf{R}^d, [0, 1])$ such that

$$\chi_{(\varepsilon),\xi} \equiv 1 \text{ on } \mathcal{G}'_{(\varepsilon),\xi}, \quad \chi_{(\varepsilon),\xi} \equiv 0 \text{ on } \mathcal{U}_{(\varepsilon),\xi}, \quad \|\nabla \chi_{(\varepsilon),\xi}\|_\infty \leq 1.$$

We set $\varphi_\xi(y, n) := \chi_{(\varepsilon),\xi}((1/\varepsilon)y)\varphi(y, n)$. Note the abuse of notation: although not explicitly indicated, φ_ξ depends on ε . We have,

$$\begin{aligned} \varepsilon^{d-1} |Q_{(\varepsilon)}[\varphi_\xi - \varphi]| &\leq \|\varphi\|_\infty \varepsilon^{d-1} \mathcal{H}^d(\mathcal{U}'_{(\varepsilon),\xi})/2 \stackrel{(2.27)}{\leq} C_{\sharp}(\varphi, \xi) \varepsilon^2, \\ \varepsilon^{d-1} |Q'_{(\varepsilon)}[\varphi_\xi - \varphi]| &\leq \|\varphi\|_\infty \varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma_{(\varepsilon)} \cap \mathcal{U}'_{(\varepsilon),\xi}) \stackrel{(2.23)}{\leq} C_{\sharp}(\varphi, \xi) \varepsilon^2. \end{aligned}$$

Therefore,

$$\varepsilon^{d-1} \left| \left\{ Q_{(\varepsilon)}[\varphi_\xi] - Q'_{(\varepsilon)}[\varphi_\xi] \right\} - \left\{ Q_{(\varepsilon)}[\varphi] - Q'_{(\varepsilon)}[\varphi] \right\} \right| \leq C_{\sharp}(\varphi, \xi) \varepsilon^2 \xrightarrow{\varepsilon \downarrow 0} 0.$$

As a consequence, we can substitute φ_ξ for φ in (2.24). The rest of the proof consists in establishing

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^{d-1} \left| Q_{(\varepsilon)}[\varphi_\xi] - Q'_{(\varepsilon)}[\varphi_\xi] \right| \leq C_{\sharp}(\varphi) \xi. \quad (2.28)$$

Since $\xi \in (0, 1/2)$ is arbitrary, this proves the desired convergence result (2.24).

Step 3. Proof of (2.28).

Let us enumerate the benefits of the cut-off procedure. Since φ_ξ is supported in $\mathcal{G}_{\varepsilon,\xi} \times \mathbf{R}^d$, we may substitute $\Sigma_{(\varepsilon)}^0$ for $\Sigma_{(\varepsilon)}$ in the definition of $Q'_{(\varepsilon)}[\varphi_\xi]$. Moreover (2.25) hold for any $x \in \Sigma_{(\varepsilon)}^0 \cap \mathcal{G}_{(\varepsilon),\xi}$ and (2.26) hold for any $z \in \Omega_{(\varepsilon)}^{\xi/2} \cap \mathcal{G}_{(\varepsilon),\xi}$. Eventually, φ_ξ satisfies

$$\|\varphi_\xi\|_\infty \leq \|\varphi\|_\infty, \quad \|\nabla_n \varphi_\xi\|_\infty \leq \|\nabla_n \varphi\|_\infty, \quad (2.29)$$

$$\|\nabla_x \varphi_\xi\|_{L^\infty(\mathcal{G}'_{\varepsilon,\xi} \times \mathbf{R}^d)} \leq \|\nabla_x \varphi\|_\infty, \quad \|\nabla_x \varphi_\xi\|_\infty \leq \varepsilon^{-1} \|\varphi\|_\infty + \|\nabla_x \varphi\|_\infty. \quad (2.30)$$

To lighten notation we write $Q_{(\varepsilon)}$ for $Q_{(\varepsilon)}[\varphi_{\varepsilon,\xi}]$ and $Q'_{(\varepsilon)}$ for $Q'_{(\varepsilon)}[\varphi_{\varepsilon,\xi}]$. With this notation, we have to show that

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^{d-1} \left| Q_{(\varepsilon)} - Q'_{(\varepsilon)} \right| \leq C_{\sharp}(\varphi) \xi.$$

For this, we introduce the intermediate quantities

$$Q_{(\varepsilon)}(\xi) := \frac{1}{2} \int_{\Omega_{(\varepsilon)}^{\xi/2}} \varphi_{\varepsilon, \xi}(\varepsilon z, \nabla t_{(\varepsilon)}(z)) dz,$$

and

$$Q'_{(\varepsilon)}(\xi) := \int_{\Sigma_{(\varepsilon)}^0} \left\{ \frac{1}{\mathcal{H}^d(D_1^0)} \int_{[x+D_1^{\xi}(n_{(\varepsilon)}(x))]} \varphi_{\varepsilon, \xi}(\varepsilon z, \nabla t_{(\varepsilon)}(z)) dz \right\} d\mathcal{H}^{d-1}(x).$$

We prove (2.28) by estimating successively $Q_{(\varepsilon)} - Q_{(\varepsilon)}(\xi)$, $Q_{(\varepsilon)}(\xi) - Q'_{(\varepsilon)}(\xi)$ and $Q'_{(\varepsilon)}(\xi) - Q'$. In these estimates, apart from the conclusions, we drop the subscripts (ε) .

Step 3.1. Estimating $Q_{(\varepsilon)} - Q_{(\varepsilon)}(\xi)$.

Using (2.3) in Lemma 2.1 with $(\alpha_-, \alpha_+) = (-1, -1 + \xi/2)$ and $(\alpha_-, \alpha_+) = (1 - \xi/2, 1)$, we obtain,

$$\begin{aligned} |Q - Q(\xi)| &\leq \frac{\|\varphi\|_{\infty}}{2} \mathcal{H}^d \left(\Omega^{-1, -1 + \xi/2} \cup \Omega^{1 - \xi/2, 1} \right) \\ &\leq \frac{\|\varphi\|_{\infty}}{2} \left(\frac{S\xi}{\varepsilon^{d-1}} + \frac{C_{\xi}(\xi)}{\varepsilon^{(d-1)/2}} \right). \end{aligned}$$

Hence,

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^{d-1} |Q_{(\varepsilon)} - Q_{(\varepsilon)}(\xi)| \leq \|\varphi\|_{\infty} S\xi/2. \quad (2.31)$$

Step 3.2. Estimating $Q_{(\varepsilon)}(\xi) - Q'_{(\varepsilon)}(\xi)$.

Changing the order of integration in the definition of $Q'(\xi)$, we obtain,

$$Q'(\xi) = \int_{\Omega^{\xi/2}} \varphi_{\varepsilon, \xi}(\varepsilon z, \nabla t(z)) q^{\xi}(z) dz,$$

Hence, by (2.26), we have,

$$|Q(\xi) - Q'(\xi)| \leq \|\varphi\|_{\infty} \mathcal{H}^d(\Omega) \xi \stackrel{(2.3)}{\leq} \left(\frac{S}{\varepsilon^{d-1}} + \frac{C_{\xi}}{\varepsilon^{(d-1)/2}} \right) \xi.$$

Again, this leads to

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^{d-1} |Q_{(\varepsilon)}(\xi) - Q'_{(\varepsilon)}(\xi)| \leq \|\varphi\|_{\infty} S\xi. \quad (2.32)$$

Step 3.3. Estimating $Q'(\xi) - Q'$.

We have

$$|Q'(\xi) - Q'| \leq \int_{\Sigma^0} q(x) d\mathcal{H}^{d-1}(x),$$

with

$$q(x) := \left| \varphi_\xi(\varepsilon x, n(x)) - \frac{1}{\mathcal{H}^d(D_1^0)} \int_{[x+D_1^\xi(n(x))]} \varphi_\xi(\varepsilon z, \nabla t(z)) dz \right|.$$

For $x \in \Sigma^0 \cap \mathcal{G}'_\xi$, we estimate $q(x)$ as follows.

$$\begin{aligned} q(x) &\leq |\varphi_\xi(\varepsilon x, n(x))| \left[1 - \mathcal{H}^d(D_1^\xi) / \mathcal{H}^d(D_1^0) \right] \\ &\quad + \frac{1}{\mathcal{H}^d(D_1^0)} \int_{[x+D_1^\xi(n(x))]} |\varphi_\xi(\varepsilon z, \nabla t(z)) - \varphi_\xi(\varepsilon x, n(x))| dz \\ &\leq 2 \|\varphi_\xi\|_\infty \xi \\ &\quad + \left[\sqrt{2} \|\nabla_x \varphi_\xi\|_{L^\infty(x+D_1^\xi(n(x)))} \varepsilon + \frac{\|\nabla_\tau \varphi_\xi\|_\infty}{\mathcal{H}^d(D_1^0)} \int_{[x+D_1^\xi(n(x))]} |\nabla t(z) - n(x)| dz \right] \\ &\stackrel{(2.25)}{\leq} (2 \|\varphi_\xi\|_\infty + \|\nabla_\tau \varphi_\xi\|_\infty) \xi + \sqrt{2} \|\nabla_x \varphi_\xi\|_{L^\infty(x+D_1^\xi(n(x)))} \varepsilon. \end{aligned}$$

Integrating over $\Sigma_0 \cap \mathcal{G}'_\xi$ and using (2.29), (2.30) we obtain,

$$\begin{aligned} &|Q'(\xi) - Q'| \\ &\leq 2 \|\varphi\|_{W^{1,\infty} \mathcal{H}^{d-1}(\Sigma)} (\xi + \varepsilon) + \sqrt{2} \|\varphi\|_\infty \mathcal{H}^{d-1} \left(\Sigma \cap [\mathcal{W}'_\xi + B_{\sqrt{2}}] \right) \\ &\stackrel{(2.20)(2.23)}{\leq} C_\varphi(\varphi) (\varepsilon^{d-1} \xi + \varepsilon^d). \end{aligned}$$

We conclude that

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^{d-1} |Q'_{(\varepsilon)}(\xi) - Q'_{(\varepsilon)}| \leq C_\varphi(\varphi) \xi. \quad (2.33)$$

Step 3.4. Conclusion.

Gathering (2.31)(2.32)(2.33), we have established (2.28). This proves (2.24). \square

2.6 Proof of Theorem 1.1

Let $R, S > 0$ and let us consider a family $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$ with $a_\varepsilon = (\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(R, S)$ satisfying the hypotheses of Theorem 1.1. In this case, the conclusions of Proposition 2.1 hold. We use the notation of the proposition.

Let us call $\mathcal{V}'_\varepsilon = \mathcal{V}(\Sigma_\varepsilon, n_\varepsilon)$ the oriented $(d-1)$ -varifold associated with $\Sigma_\varepsilon = \partial O_\varepsilon$ and let $\varphi \in C(\mathbf{R}^d \times S^{d-1})$. Proposition 2.1.c applied to the test function $\overline{\varphi}(y, v) = \varphi(y, v/|v|) \chi^*(|v|)$ reads

$$\langle \mathcal{V}'_\varepsilon^*(a_\varepsilon); \varphi \rangle - \langle \mathcal{V}'_\varepsilon; \overline{\varphi} \rangle \rightarrow 0 \text{ as } \varepsilon \downarrow 0.$$

Now, since $\chi^*(1) = 1$, we have $\langle \mathcal{V}'_\varepsilon; \overline{\varphi} \rangle = \langle \mathcal{V}'_\varepsilon; \varphi \rangle$ and we conclude that

$$\mathcal{V}'_\varepsilon(a_\varepsilon) - \mathcal{V}'_\varepsilon \rightarrow 0 \quad \text{weakly in } \mathcal{M}(\mathbf{R}^d \times S^{d-1}) \text{ as } \varepsilon \downarrow 0. \quad (2.34)$$

As a consequence, the compactness and limit properties of $\{\mathcal{V}'_\varepsilon\}$ transfer to the family $\{\mathcal{V}'_\varepsilon^*(a_\varepsilon)\}$ and it is sufficient to study the former.

The Radon measures $\{\mathcal{V}'_\varepsilon\}$ are non-negative and supported in $B_{R+C} \times S^{d-1}$. By the second estimate of Proposition 2.1.b, their total mass $\|\mathcal{V}'_\varepsilon\|(\mathbf{R}^d \times S^{d-1}) = \langle \mathcal{V}'_\varepsilon; 1 \rangle$ is uniformly bounded. Thus, there exists a (not relabelled) sequence $\varepsilon \downarrow 0$ and an oriented $(d-1)$ -varifold \mathcal{V}_0 such that up to extraction,

$$\mathcal{V}'_\varepsilon \rightarrow \mathcal{V}_0 \quad \text{in } \mathcal{M}(\mathbf{R}^d \times S^{d-1}) \text{ as } \varepsilon \downarrow 0.$$

The estimates of Proposition 2.1.b show that the sequence of varifolds $\mathcal{V}'_\varepsilon = \mathcal{V}(\Sigma_\varepsilon, \nu_\varepsilon)$ satisfies the requirements of (1.3). Therefore, $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$. This establishes parts (c) of the theorem.

We easily see that \mathcal{V}_0 is non-negative and compactly supported in $\overline{B_R} \times S^{d-1}$ and that its total mass is given by

$$\|\mathcal{V}_0\|(\mathbf{R}^d \times S^{d-1}) = \langle \mathcal{V}_0; 1 \rangle = \lim_{\varepsilon \downarrow 0} \langle \mathcal{V}'_\varepsilon; 1 \rangle \stackrel{(2.34)}{=} \lim_{\varepsilon \downarrow 0} \langle \mathcal{V}'_\varepsilon^*(a_\varepsilon); 1 \rangle = S.$$

The last identity follows from the second estimate of Proposition 2.1.a. Taking into account $\mathcal{V}'_\varepsilon^*(a_\varepsilon) - \mathcal{V}'_\varepsilon \rightarrow 0$, we have established part (a) of the theorem.

Next, let us study the compactness properties of the family $T_\varepsilon = (\varepsilon - t_\varepsilon)/2\varepsilon$. These functions are compactly supported in $\overline{B_R}$ and by Proposition 2.1.a the sequence (T_ε) is uniformly bounded in $BV(\mathbf{R}^d)$. Hence, up to a second extraction, we may assume that (T_ε) (weakly) converges in $BV(\mathbf{R}^d)$ towards a function $T \in BV(\mathbf{R}^d)$ which is compactly supported in $\overline{B_R}$. Moreover, by Proposition 2.1.a, $\mathcal{H}^d(\Omega_\varepsilon) \sim S\varepsilon$ and since $\{y \in \mathbf{R}^d : T_\varepsilon(y) \notin \{0, 1\}\} \subset \Omega_\varepsilon$, we have $T \in \{0, 1\}$ almost everywhere in \mathbf{R}^d . Therefore, there exists a set of finite perimeter $O_0 \subset \overline{B_R}$ such that

$$T_\varepsilon \rightarrow T = \mathbf{1}_{O_0} \quad \text{weakly in } BV(\mathbf{R}^d) \text{ as } \varepsilon \downarrow 0.$$

(For properties of BV functions and sets of finite perimeter, we refer to the books by Ambrosio, Fusco and Palara [3] or Evans and Gariepy [5]).

Now let us consider $\psi \in C_c(\mathbf{R}^d, \mathbf{R}^d)$ and let us apply Proposition 2.1.c with $\varphi(y, n) = \psi(y) \cdot n$. Passing to the limit $\varepsilon \downarrow 0$, we get

$$\int_{\mathbf{R}^d} \nabla \mathbf{1}_{O_0} \cdot \psi = -\langle \Lambda \mathcal{V}_0; \psi \rangle, \quad \text{for every } \psi \in C_c(\mathbf{R}^d, \mathbf{R}^d).$$

Hence, $\Lambda \mathcal{V}_0 = -\nabla \mathbf{1}_{O_0}$. This identity uniquely defines the limit $T = \mathbf{1}_{O_0}$, so the second extraction was not necessary.

This establishes part (b) and ends the proof of Theorem 1.1.

3 Construction of a recovery family in the smooth case. Proof of Theorem 1.3

We consider an energy $\mathcal{F}(\sigma, \tau) = \int_{\tau \neq 0} f(\sigma, \tau)$ with stored energy function $f \in C(\mathbf{R}^d \times, \mathbf{R}^d, \mathbf{R}_+)$. We assume that f satisfies (1.1) and (1.6), (1.7), namely: $f \equiv 0$ on the sphere $\mathbb{S}^{d-1} = \{(e, e) : e \in S^{d-1}\}$, f is of class C^2 in some neighborhood \mathcal{N} of \mathbb{S}^{d-1} in $\mathbf{R}^d \times \mathbf{R}^d$ and f is invariant under change of orthonormal coordinates in this neighborhood, i.e. $f(Qv_1, Qv_2) = f(v_1, v_2)$ for every $(v_1, v_2) \in \mathcal{N}$ and every (orientation preserving) $Q \in \text{SO}(d)$.

The symmetry assumption and the minimality of f on \mathbb{S}^{d-1} yield a special structure for the Hessian matrix of f on \mathbb{S}^{d-1} . This structure is described in the following lemma whose proof is postponed to Appendix C

Lemma 3.1 *Let $e \in S^{d-1}$ and $b_1, \dots, b_{d-1} \in S^{d-1}$ such that (b_1, \dots, b_{d-1}, e) is an orthonormal basis of \mathbf{R}^d . We define an orthonormal basis of $\mathbf{R}^d \times \mathbf{R}^d$ as*

$$\mathcal{B} = ((b_1, 0), \dots, (b_{d-1}, 0), (0, b_1), \dots, (0, b_{d-1}), (e, 0), (0, e)).$$

Then there exists $a \geq 0$ and a 2×2 non-negative symmetric matrix L which do not depend on e , such that, in the basis \mathcal{B} , the Hessian matrix of f at point (e, e) reads

$$D^2 f(e, e) = \begin{pmatrix} a\mathbf{I}_{d-1} & -a\mathbf{I}_{d-1} & 0 \\ -a\mathbf{I}_{d-1} & a\mathbf{I}_{d-1} & 0 \\ 0 & 0 & L \end{pmatrix}. \quad (3.1)$$

(\mathbf{I}_{d-1} denotes the identity matrix of size $(d-1) \times (d-1)$.)

Moreover, if (1.2) also holds ($f \geq \kappa f_0$ for some $\kappa > 0$), then a and L are positive.

Now let us establish Theorem 1.3. Let $O_0 \subset \mathbf{R}^d$ be a smooth bounded open subset of \mathbf{R}^d , let v_0 the outward unit normal to O_0 and let $\Sigma_0 := \partial O_0$.

We introduce the mapping

$$\psi : \Sigma_0 \times \mathbf{R} \rightarrow \mathbf{R}^d, \quad \psi(x, s) := x + s v_0(x).$$

There exists $\varepsilon_* > 0$ such that ψ is a smooth (and bi-Lipschitz) diffeomorphism from $\Sigma_0 \times (-\varepsilon_*, \varepsilon_*)$ onto its range Ω_* . The inverse mapping is given by $\Psi^{-1} = (\pi_0, Z)$ where π_0 is the orthogonal projection on Σ_0 and where $Z(y) := d(y, O_0) - d(y, \mathbf{R}^d \setminus O_0)$ is the signed distance function to Σ_0 .

Let us extend v_0 as a mapping $n_0 : \Omega_* \rightarrow S^{d-1}$ by $n_0(y) = v_0(\pi_0(y)) = \nabla Z(y)$.

We are going to build a quasi optimal family $\{a_\varepsilon\} = \{(\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon)\}$ such that σ_ε and ∇t_ε are the restrictions to Ω_ε of vector fields σ and ∇t defined on Ω_* .

For symmetry reasons, we look for vector fields σ and ∇t which are collinear to n_0 in Ω_* and equal to v_0 on Σ_0 . Under this ansatz the only possibility for the divergence free vector field $\sigma : \Omega_* \rightarrow \mathbf{R}^d$ is to set

$$\sigma(y) := (\det [\mathbf{I}_d + Z(y) D v_0(\pi_0(y))])^{-1} n_0(y) \quad \text{for every } y \in \Omega_*. \quad (3.2)$$

Let us check that σ is divergence free in Ω_* . Equivalently, we have to show that $\int_{\Omega_*} \nabla \varphi \cdot \sigma$ vanishes for every $\varphi \in \mathcal{D}(\Omega_*)$. We perform the change of variable

$y = \Psi(x, s)$. The Jacobian determinant of Ψ is $J_\Psi(x, s) = \det [\mathbf{I}_d + sDv_0(x)]$ and we indeed obtain,

$$\int_{\Omega_\star} \nabla \varphi(y) \cdot \sigma(y) dy = \int_{\Sigma_0} \left\{ \int_{-\varepsilon_\star}^{\varepsilon_\star} [v_0(x) \cdot \nabla] \varphi(x + sv_0(x)) ds \right\} d\mathcal{H}^{d-1}(x) = 0.$$

Then we set

$$t(y) := \left(1 + \frac{\alpha(\pi_0(y))}{2} Z(y) \right) Z(y),$$

where $\alpha \in C^1(\Sigma_0)$ has to be optimized. The function α being given, there exists $\varepsilon'_\star \in (0, \varepsilon_\star)$ such that $\Phi_\alpha : y \mapsto (\pi_0(y), t(y))$ is a smooth diffeomorphism from $\Sigma + B_{\varepsilon'_\star}$ onto its range. Expanding the inverse of Φ_α with respect to α around $\Phi_0^{-1} = \Psi$, we see that

$$\Phi_\alpha^{-1}(x, s) = x + \left(1 - \frac{\alpha(x)}{2} s + o(s) \right) sv_0(x),$$

with $o(s) \rightarrow 0$ uniformly in x as $s \rightarrow 0$. Moreover, lowering ε'_\star if necessary, we have for $\varepsilon \in (0, \varepsilon'_\star/2)$,

$$\Sigma_0 + B_{(1-o(\varepsilon))\varepsilon} \subset \Phi_\alpha^{-1}(\Sigma \times (-\varepsilon, \varepsilon)) \subset \Sigma_0 + B_{(1+o(\varepsilon))\varepsilon}. \quad (3.3)$$

Now, for $\varepsilon \in (0, \varepsilon'_\star/2)$ we set $\Omega_\varepsilon := \Phi_\alpha^{-1}(\Sigma \times (-\varepsilon, \varepsilon))$ and we define

$$t_\varepsilon(y) := t(y) \quad \text{for } y \in \overline{\Omega_\varepsilon}.$$

By construction, $\partial\Omega_\varepsilon$ splits into two disjoint components $\partial\Omega_\varepsilon^\pm$ with $\partial\Omega_\varepsilon^- \subset O_0$, $\partial\Omega_\varepsilon^+ \subset \mathbf{R}^d \setminus O_0$ and we have $\pm t_\varepsilon = \varepsilon$ on $\partial\Omega_\varepsilon^\pm$. We then extend t_ε by continuity as

$$t_\varepsilon := \begin{cases} -\varepsilon & \text{in } O_0 \setminus \Omega_\varepsilon, \\ \varepsilon & \text{in } \mathbf{R}^d \setminus [\Omega_\varepsilon \cup O_0]. \end{cases}$$

Eventually, we set

$$\sigma_\varepsilon(y) := \begin{cases} \sigma(y) & \text{if } y \in \Omega_\varepsilon, \\ 0 & \text{if } y \in \mathbf{R}^d \setminus \Omega_\varepsilon, \end{cases}$$

By construction, we have $a_\varepsilon := (\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(R + O(\varepsilon))$ where by definition, $R = \max\{|x|; x \in \Sigma_0\}$. Writing $y = \Psi(x, s)$, we compute the expansions

$$\begin{aligned} \sigma_\varepsilon(x + sv_0(x)) &= v_0(x) + sh_0(x)v_0(x) + O(s^2), \\ \nabla t_\varepsilon(x + sv_0(x)) &= v_0(x) + s\alpha(x)v_0(x) + O(s^2), \end{aligned} \quad (3.4)$$

where $h_0(x) = -\nabla \cdot n_0(x)$ is the scalar mean curvature of Σ_0 . Taking into account Lemma 3.1, we have for every $y = \Phi_\alpha^{-1}(x, s) \in \Omega_\varepsilon$,

$$f(\sigma_\varepsilon(y), \nabla t_\varepsilon(y)) = \frac{s^2}{2} (h_0(x), \alpha(x))^T L(h_0(x), \alpha(x)) + o(s^2).$$

Optimizing with respect to $\alpha(x)$, we get $\alpha(x) = -(L_{1,2}/L_{2,2})h_0(x)$ which yields

$$f(\sigma_\varepsilon(y), \nabla t_\varepsilon(y)) = h_0^2(x) \frac{\det L}{2L_{2,2}} s^2 + o(s^2).$$

Taking into account (3.3), the energy of a_ε then expands as

$$\mathcal{F}(a_\varepsilon) = \frac{\det L}{3L_{2,2}} \mathcal{W}(\Sigma_0) \varepsilon^3 + o(\varepsilon^3).$$

This is the expected expansion, however, the volume constraint is not exactly satisfied. We only have

$$\mathcal{Q}(\sigma_\varepsilon, \nabla t_\varepsilon) = \int_{\Omega_\varepsilon} \sigma \cdot \nabla t = 2\varepsilon \mathcal{H}^{d-1}(\Sigma_0) + O(\varepsilon^2).$$

We recover the exact constraint $\mathcal{Q}(\sigma'_\varepsilon, \nabla t'_\varepsilon) = 2\varepsilon \mathcal{H}^{d-1}(\Sigma_0)$ by substituting $a'_\varepsilon = (\sigma'_\varepsilon, \nabla t'_\varepsilon, \Omega'_\varepsilon)$ for a_ε with

$$\sigma'_\varepsilon(y) := \sigma_\varepsilon((1/\lambda_\varepsilon)y), \quad t'_\varepsilon(y) := \lambda_\varepsilon t_\varepsilon((1/\lambda_\varepsilon)y), \quad \Omega'_\varepsilon := \lambda_\varepsilon \Omega_\varepsilon,$$

where the magnification factor is defined as

$$\lambda_\varepsilon := \left[\frac{\mathcal{Q}(\sigma_\varepsilon, \nabla t_\varepsilon)}{2\varepsilon \mathcal{H}^{d-1}(\Sigma)} \right]^{1/d} = 1 + O(\varepsilon).$$

The convergence properties of $\{\mathcal{V}_\varepsilon^*(a'_\varepsilon)\}$ towards $\mathcal{V}(\Sigma_0, \nu_0)$ and of the sets $\{t'_\varepsilon = -\varepsilon\}$ towards O_0 are straightforward by construction. This ends the proof of Theorem 1.3.

4 Lower bound. Proof of Theorem 1.2

In this Section, we assume that the stored energy function f satisfies (1.1), (1.2) and (1.6), (1.7) and we consider an oriented $(d-1)$ -varifold \mathcal{V}_0 and a sequence $(a_{\varepsilon_k})_{k \geq 0}$ with $\varepsilon_k \downarrow 0$ such that $a_{\varepsilon_k} \in \mathcal{A}_{\varepsilon_k}(R, S)$ for some $R, S > 0$ and $\mathcal{V}_{\varepsilon_k}(a_{\varepsilon_k}) \rightarrow \mathcal{V}_0$ as $\varepsilon_k \downarrow 0$.

The lower bound result being obvious in the case $\liminf_k \mathcal{F}(a_{\varepsilon_k})/\varepsilon_k^3 = +\infty$, we assume without loss of generality, that there exists $E_0 > 0$ such that

$$\mathcal{F}_0(a_{\varepsilon_k}) \leq E_0 \varepsilon_k^3, \quad \text{for every } k \geq 0.$$

Consequently, the constructions and estimates of Proposition 2.1 and Theorem 1.1 apply to the sequence $\{a_{\varepsilon_k}\}$ and \mathcal{V}_0 . In particular $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$ and by Appendix D $\mathcal{V}_0 = \mathcal{V}(\Sigma_0, \nu_0, \theta_0^+, \theta_0^-)$ is an oriented integer rectifiable $(d-1)$ -varifold which admits a L^2 -generalized mean curvature. To lighten notation, we drop the subscripts k in the sequence ε_k . We use the notation of Section 2 for the objects constructed along the proof of Proposition 2.1: $u_\varepsilon, O_\varepsilon, \Sigma_\varepsilon, \nu_\varepsilon$ and the corresponding rescaled objects $u_{(\varepsilon)}, O_{(\varepsilon)}, \Sigma_{(\varepsilon)}, \nu_{(\varepsilon)}$, etc.

By lower semi-continuity of the Willmore energy (see (D.6)) we have

$$\mathcal{W}(\mathcal{V}_0) \leq \liminf_{\varepsilon \downarrow 0} \mathcal{W}(\Sigma_\varepsilon).$$

However, there is little hope for deducing the lower bound of Theorem 1.2 from this inequality. Indeed, the mean curvature h_ε of Σ_ε is loosely and non locally related to the data a_ε through the harmonic function u_ε . Remark that u_ε does not even depend on σ_ε . In short (and omitting cut-off issues) our strategy is the following.

i. In Section 4.1, we define an *approximate mean curvature* $\hat{h}_\varepsilon(x)$ as the dot product of σ_ε with a particular test function ζ compactly supported in $x + \varepsilon D_1^0(v(x))$. We also establish that \hat{h}_ε is indeed an approximation of h_ε in a weak sense. We deduce the inequality

$$\mathcal{W}(\mathcal{V}_0) \leq \liminf_{\varepsilon \downarrow 0} \int_{\Sigma_\varepsilon} |\hat{h}_\varepsilon|^2 d\mathcal{H}^{d-1}. \quad (4.1)$$

ii. In Section 4.2, we introduce local minimization problems of the form

$$c_{\zeta, \eta}(f) := \inf \left[\mathcal{F} \left(\sigma^\#, \nabla t^\#, D_{1-2\xi}^{2\xi}(e_d) \right) / |\hat{h}^\#|^2 \right], \quad (4.2)$$

where the infimum ranges over all admissible vector fields $\sigma^\#, \nabla t^\#$ with *approximate mean curvature* $\hat{h}^\# \in (-\eta, \eta) \setminus \{0\}$ at $x = 0$. With this notation, we deduce from (4.1)

$$c_{\zeta, \eta}(f) \mathcal{W}(\mathcal{V}_0) \leq \liminf_{\varepsilon \downarrow 0} \frac{1}{\varepsilon^3} \int_{\Sigma_\varepsilon \cap [|\hat{h}_\varepsilon| < \eta/\varepsilon]} \mathcal{F} \left(\sigma_\varepsilon, \nabla t_\varepsilon, x + \varepsilon D_{1-2\xi}^{2\xi}(v_\varepsilon(x)) \right) d\mathcal{H}^{d-1}(x).$$

We then show that the above integral is bounded by $[1 + s(\eta)] \mathcal{H}^{d-1}(D'_1) \mathcal{F}(a_\varepsilon)$ with $s(\eta) \rightarrow 0$ as $\eta \downarrow 0$ and get

$$c_{\zeta, \eta}(f) \mathcal{W}(\mathcal{V}_0) \leq [1 + s(\eta)] \mathcal{H}^{d-1}(D'_1) \liminf_{\varepsilon \downarrow 0} \frac{\mathcal{F}(a_\varepsilon)}{\varepsilon^3}.$$

We study the local problems (4.2) and establish

$$\liminf_{\eta \downarrow 0} c_{\zeta, \eta}(f) \geq \mathcal{H}^{d-1}(D'_1) c_{0, \zeta}(f),$$

where $c_{0, \zeta}(f)$ depends explicitly on f and on the test function ζ . Eventually, optimizing with respect to ζ we obtain $\sup_\zeta c_{0, \zeta}(f) = c_0(f)$ which yields the desired lower bound.

The above description leaves aside the following technical difficulties: 1/ we are only able to define the approximate mean curvature in a good set, so we need to perform a cut-off and control the volume of the bad set; 2/ we need also to control the $(d-1)$ -volumes of the sets $\Sigma_\varepsilon \cap [|\hat{h}_\varepsilon| \geq \eta/\varepsilon]$; 3/ for compactness issues we introduce a small parameter $\alpha > 0$ and (with obvious notation), we substitute

$$\mathcal{F} \left(\sigma^\#, \nabla t^\#, D_{1-2\xi}^{2\xi} \right) + \alpha \int_{B_3 \cap \Omega^\#} [f_0(\sigma^\#, \nabla t^\#) + |\nabla u^\# - \nabla t^\#|^2]$$

for $\mathcal{F}(\sigma^\#, \nabla t^\#, D_{1-2\xi}^{2\xi})$ in the local optimization problem.

4.1 Definition and properties of the approximate mean curvature.

We already know that σ_ε approximates ν_ε , so a naive way to build an approximation of the mean curvature on Σ_ε by means of the data $(\sigma_\varepsilon, \nabla t_\varepsilon)$ is to set $\hat{h}_\varepsilon(x) := \operatorname{div}_{\Sigma_\varepsilon} \sigma_\varepsilon(x)$. However, the regularity of σ_ε is too weak to provide a robust definition under sole energy bounds. The next idea consists in using a weak notion for the mean curvature where, thanks to integration by parts, the space derivatives on σ_ε are transferred to a test function. The relevant tool for this is the tangential Green formula.

Let us consider a smooth compact hypersurface $\Gamma \subset \mathbf{R}^d$ without boundary, with normal \mathbf{v} and mean curvature h . Let $X \in C^1(\Gamma, \mathbf{R}^d)$ of the form $X(x) = \varphi(x)\mathbf{v}(x)$ and let us extend it as a mapping $X \in C_c^1(\mathbf{R}^d, \mathbf{R}^d)$. For such a test vector field, the tangential Green formula (D.2) reads,

$$\int_{\Gamma} \varphi h \mathbf{v} \, d\mathcal{H}^{d-1} = - \int_{\Gamma} \nabla_{\Gamma} \varphi \, d\mathcal{H}^{d-1} \quad \text{for every } \varphi \in \mathcal{D}(\mathbf{R}^d). \quad (4.3)$$

Assume for simplicity that $0 \in \Gamma$ with $\mathbf{v}(0) = e_d$ and let us localize the above identity around 0. For this, we introduce a function of the form

$$\zeta(y', y_d) := \chi_{//}(|y'|) \chi_{\perp}(y_d),$$

with $\chi_{//}, \chi_{\perp} \in \mathcal{D}(\mathbf{R}, \mathbf{R}_+)$ even and such that $\chi_{\perp}(0) \int_{\mathbf{R}^{d-1}} \chi_{//}(|y'|) \, dy' = 1$. Using the test function $\varphi(y) = \eta^{1-d} \zeta((1/\eta)y)$ in (4.3), taking the scalar product with $\mathbf{v}(0) = e_d$ and sending η to 0, we obtain after some Taylor expansions,

$$h(0) = \lim_{\eta \downarrow 0} \frac{1}{\eta} \int_{\Gamma_{(\eta)}} \chi_{\perp}(z_d) \mathbf{v}_{(\eta)}(z) \cdot \nabla \chi_{//}(|z'|) \, d\mathcal{H}^{d-1}(z).$$

where $\Gamma_{(\eta)}$ is the hypersurface $(1/\eta)\Gamma$ and $\mathbf{v}_{(\eta)}(z) := \mathbf{v}(\eta z)$.

We mimic this formula for defining an approximate mean curvature on Σ_ε . For this, we choose $\eta = \varepsilon$ and we substitute the vector field $\sigma_{(\varepsilon)}$ for the outward unit normal $\mathbf{v}_{(\eta)} = \mathbf{v}_{(\varepsilon)}$. This substitution closely connects the approximate curvature to the data. We also thicken the domain of integration by substituting the cylinder $D_1^0 \subset \mathbf{R}^d$ for the piece of hypersurface $\Sigma_{(\varepsilon)} \cap \operatorname{supp} \zeta$. The precise construction is detailed below.

Definition 4.1 Let $\chi_{//}, \chi_{\perp} \in W^{1,\infty}(\mathbf{R}, \mathbf{R}_+)$ be two nonnegative, even cut-off functions which are compactly supported in $(-1, 1)$ and satisfy

$$\left(\int_{\mathbf{R}^{d-1}} \chi_{//}(|y'|) \, d\mathcal{H}^{d-1}(y') \right) \left(\int_{\mathbf{R}} \chi_{\perp}(s) \, ds \right) = 1.$$

We define a Lipschitz test function $\zeta \in W^{1,\infty}(\mathbf{R}^d \times S^{d-1}, \mathbf{R}_+)$, by setting

$$\zeta := \zeta_{//} \zeta_{\perp} \quad \text{with} \quad \zeta_{\perp}(y; \bar{n}) := \chi_{\perp}(y \cdot \bar{n}), \quad \zeta_{//}(y; \bar{n}) := \chi_{//}(|\pi_{\bar{n}} y|).$$

Notice that for $\bar{n} \in S^{d-1}$, the function $y \mapsto \zeta(y; \bar{n})$ is compactly supported in $D_1^0(\bar{n})$. In the sequel, we fix $\xi = \xi(\zeta) \in (0, 1/4)$ such that

$$\text{supp } \zeta(\cdot; \bar{n}) \subset D_{1-2\xi}^{2\xi}(\bar{n}) \quad \text{for } \bar{n} \in S^{d-1}.$$

Notice also that

$$\int_{\mathbf{R}^d} \zeta(y; \bar{n}) dy = 1.$$

Definition 4.2 Let us introduce a small parameter $\eta \in (0, \xi/2)$ and let us set

$$\beta_\eta := \min(\beta_{\xi,1}^*(\xi, \eta), \beta_{\xi,3}^*(\xi/2, \eta)), \quad (4.4)$$

where the functions $\beta_{\xi,1}^*$ and $\beta_{\xi,3}^*$ are given in Lemma 2.4 and Lemma 2.6. Using the notation of Lemma 2.7, we define the two bad sets (union of bad balls),

$$\mathcal{U}_{(\varepsilon),\eta} := \left[U_{(\varepsilon)}^* \cup U_{(\varepsilon),\beta_\eta} \right] + B_{\sqrt{2}} \subset \mathcal{U}'_{(\varepsilon),\eta} := \mathcal{U}_{(\varepsilon),\eta} + B_{\sqrt{2}},$$

and the corresponding good sets

$$\mathcal{G}_{(\varepsilon),\eta} := \mathbf{R}^d \setminus \mathcal{U}_{(\varepsilon),\eta}, \quad \supset \quad \mathcal{G}'_{(\varepsilon),\eta} := \mathbf{R}^d \setminus \mathcal{U}'_{(\varepsilon),\eta}.$$

Next, we define a cut-off function $\chi_{(\varepsilon),\eta} \in \mathcal{D}(\mathbf{R}^d, [0, 1])$ satisfying

$$\chi_{(\varepsilon),\eta} \equiv 1 \text{ on } \mathcal{G}'_{(\varepsilon),\eta}, \quad \chi_{(\varepsilon),\eta} \equiv 0 \text{ on } \mathcal{U}_{(\varepsilon),\eta}, \quad \|\nabla \chi_{(\varepsilon),\eta}\|_\infty \leq 1.$$

The approximate (scalar) mean curvature of Σ_ε at some point $x \in \Sigma_\varepsilon$ is defined as

$$\hat{h}_\varepsilon(x) := \frac{\chi_{(\varepsilon),\eta}(\varepsilon x)}{\varepsilon} \int_{\mathbf{R}^d} \sigma_\varepsilon(x + \varepsilon z) \cdot \pi_{\mathbf{v}_\varepsilon(x)} \nabla_y \zeta(z; \mathbf{v}_\varepsilon(x)) dz.$$

Eventually, the approximate mean curvature is defined as $\hat{H}_\varepsilon(x) := \hat{h}_\varepsilon(x) \mathbf{v}_\varepsilon(x)$.

Remark 4.1 To lighten the notation in the above definitions we did not emphasized the dependencies in ζ and η . Below, the main computations are carried out for a fixed test function ζ and a fixed parameter η . Only at the end, we send η to 0 and we optimize the lower bound with respect to ζ .

The next proposition states that \hat{h}_ε approximates h_ε , at least in a weak sense in $L^2(\Sigma_\varepsilon, \mathcal{H}^{d-1})$.

Proposition 4.1 *Let \hat{h}_ε be given by Definition 4.2:*

a) *We have the following uniform bound in ε ,*

$$\int_{\Sigma_\varepsilon} |\hat{h}_\varepsilon|^2 d\mathcal{H}^{d-1} \leq C_\xi(\zeta, \eta).$$

b) *Moreover, for every $\varphi \in C(\mathbf{R}^d)$,*

$$\int_{\Sigma_\varepsilon} \varphi [\hat{h}_\varepsilon - h_\varepsilon] \mathbf{v}_\varepsilon d\mathcal{H}^{d-1} \xrightarrow{\varepsilon \downarrow 0} 0.$$

Proof Let us fix $\varepsilon \in (0, 1]$ and for $x \in \Sigma_{(\varepsilon)}$, let us set

$$\hat{h}_{(\varepsilon)}(x) := \varepsilon \hat{h}_{\varepsilon}(\varepsilon x).$$

We now drop the subscripts (ε) : we write $\Sigma = \Sigma_{(\varepsilon)}$, $U^* = U_{(\varepsilon)}^*$, $\chi_{\eta} = \chi_{(\varepsilon), \eta}$, etc.

In rescaled variables, we have for $x \in \Sigma$,

$$\hat{h}(x) = \chi_{\eta}(x) \int_{\mathbf{R}^d} \sigma(x+y) \cdot (\zeta_{\perp} \nabla_y \zeta_{\parallel})(y; v(x)) dy. \quad (4.5)$$

Recall that in the above integral we can reduce the domain of integration to $D_{1-2\xi}^{2\xi}(v(x))$.

We start with a few remarks. Let us consider the piece of hypersurface,

$$\Gamma_{\eta} := \Sigma \cap \text{supp } \chi_{\eta}.$$

By definition of χ_{η} , we have $\text{supp } \chi_{\eta} + B_{\sqrt{2}} \subset U^*$ so that $\Sigma \cap (\text{supp } \chi_{\eta} + B_{\sqrt{2}}) \subset \Sigma^0$. In particular, $\Gamma_{\eta} \subset \Sigma_0$ and $v(x) = n(x)$ on Γ_{η} .

By definition of β_{η} , Lemma 2.4 and Lemma 2.5 apply to any point of Γ_{η} . Following the notation of these lemmas, we define for every $x \in \Gamma_{\eta}$,

$$D_{\text{int}}(x) := x + D_{1-2\xi}^{2\xi}(n(x)) \subset D(x) := x + D_{1-\xi}^{\xi}(n(x)) \subset \Omega.$$

The inequalities (2.11) and (2.13) apply at x and moreover, $\Sigma \cap D(x) = \Sigma^0 \cap D(x)$. Eventually, since $\eta < \xi/2$, Lemma 2.4 implies $|t| \leq 1 - \xi/2$ in $D(x)$; so Lemma 2.6 apply to any element $y \in D(x)$, $x \in \Gamma_{\eta}$.

(a) We have to estimate the quantity

$$\int_{\Sigma_{\varepsilon}} \hat{h}_{\varepsilon}^2 d\mathcal{H}^{d-1} = \varepsilon^{d-3} \int_{\Gamma_{\eta}} \hat{h}^2 d\mathcal{H}^{d-1}.$$

Let $x \in \Gamma_{\eta}$ and let ψ_x be the harmonic function provided by Lemma 2.5.c. Since $\nabla \psi_x = \pi_{n(x)} \nabla \psi_x$ and ψ_x is harmonic, we have

$$\int_{\mathbf{R}^d} \nabla \psi_x(y) \cdot \nabla_y \zeta_{\parallel}(y; n(x)) \zeta_{\perp}(y; n(x)) dy = \int_{\mathbf{R}^d} \nabla \psi_x(y) \cdot \nabla_y \zeta(y; n(x)) dy = 0.$$

This identity and $n(x) \cdot \nabla_y \zeta(y; n(x))_{\parallel} \equiv 0$ allow us to rewrite (4.5) as

$$\hat{h}(x) = \chi_{\eta}(x) \int_{\mathbf{R}^d} [\sigma(x+y) - n(x) - \nabla \psi_x(x+y)] \cdot (\zeta_{\perp} \nabla_y \zeta_{\parallel})(y; n(x)) dy.$$

Then (2.13) and the Cauchy-Schwarz inequality yield $|\hat{h}|^2(x) \leq C(\zeta) \mathcal{E}(D(x))$. Integrating on Γ_{η} and using Fubini, we obtain

$$\int_{\Gamma_{\eta}} |\hat{h}|^2 d\mathcal{H}^{d-1} \leq C(\zeta) \int_{\Omega^{1-\xi/2}} [f_0(\sigma, \nabla t) + |\nabla u - \nabla t|^2](y) q^{\xi}(y) dy,$$

with the notation $\Omega^{1-\xi/2} := [|t| < 1 - \xi/2]$ and

$$q^{\xi}(y) := \int_{\Gamma_{\eta}} \theta^{\xi}(y-x, n(x)) d\mathcal{H}^{d-1}(x).$$

where $\theta^{\xi}(\cdot, n(x))$ is the characteristic function of $D_{1-\xi}^{\xi}(n(x))$.

By inequality (2.14) of Lemma 2.6, we have $|q^{\xi}(y)| \leq C(\eta)$. Hence,

$$\varepsilon^{d-3} \int_{\Gamma_{\eta}} |\hat{h}|^2 d\mathcal{H}^{d-1} \leq C(\zeta) \varepsilon^{d-3} \int_{\Omega} [f_0(\sigma, \nabla t) + |\nabla u - \nabla t|^2] \stackrel{(\text{Lemma 2.2})}{\leq} C_{\xi}(\zeta).$$

This establishes Proposition 4.1.a.

(b) Let $\varphi \in C(\mathbf{R}^d)$. In scaled variables we have to bound the vector $\hat{Q}_{(\varepsilon)}[\varphi] - Q_{(\varepsilon)}[\varphi] \in \mathbf{R}^d$, with

$$\begin{aligned} \hat{Q}_{(\varepsilon)}[\varphi] &:= \varepsilon^{d-2} \int_{\Sigma_{(\varepsilon)}} \varphi(\varepsilon x) \hat{h}_{(\varepsilon)}(x) n_{(\varepsilon)}(x) d\mathcal{H}^{d-1}(x), \\ Q_{(\varepsilon)}[\varphi] &:= \varepsilon^{d-2} \int_{\Sigma_{(\varepsilon)}} \varphi(\varepsilon x) h_{(\varepsilon)}(x) n_{(\varepsilon)}(x) d\mathcal{H}^{d-1}(x). \end{aligned}$$

The scaling factors ε^{d-2} come from $\mathcal{H}^{d-1}(\Sigma_{\varepsilon}) = \varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma_{(\varepsilon)})$ and $h_{\varepsilon}(x) = \varepsilon^{-1} h_{(\varepsilon)}(\varepsilon^{-1}x)$.

Let us drop again the subscripts (ε) . Recall that $\Sigma \subset B_{R/\varepsilon}$, so we can assume that φ is compactly supported. We can in fact assume that φ is Lipschitz continuous by density of $W^{1,\infty}(\overline{B_{R/\varepsilon}})$ in $C(\overline{B_{R/\varepsilon}})$. Indeed, $\varphi \mapsto (Q - \hat{Q})[\varphi]$ is linear and by part (a) and the bounds of Proposition 2.1.b,

$$\begin{aligned} |(\hat{Q} - Q)[\varphi]| &\leq \|\varphi\|_{\infty} \sqrt{2\varepsilon^{d-3} \int_{\Sigma} |\hat{h}|^2 + |h|^2 d\mathcal{H}^{d-1}} \sqrt{\varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma)} \\ &\leq C_{\xi}(\zeta, \eta) \|\varphi\|_{\infty}. \end{aligned}$$

Now, we claim that we can somehow assume that φ is supported in \mathcal{G}'_{η} . Let us introduce a cut-off function $\chi'_{\eta} \in \mathcal{D}(\mathbf{R}^d, [0, 1])$ satisfying

$$\chi'_{\eta} \equiv 1 \text{ on } \mathcal{G}''_{\eta}, \quad \chi'_{\eta} \equiv 0 \text{ on } \mathcal{U}'_{\eta}, \quad \|\nabla \chi'_{\eta}\|_{\infty} \leq 1.$$

with the larger bad set and smaller good set:

$$\mathcal{U}''_{\eta} := \mathcal{U}'_{\eta} + B_{\sqrt{2}}, \quad \mathcal{G}''_{\eta} := \mathbf{R}^d \setminus \mathcal{U}''_{\eta}.$$

We then define

$$\varphi_{\eta}(y) := \chi'_{\eta}((1/\varepsilon)y) \varphi(y).$$

Since $|\varphi_{\eta} - \varphi|$ is supported in \mathcal{U}''_{η} and bounded by $\|\varphi\|_{\infty}$, we have, proceeding as above and using (2.23):

$$\begin{aligned} |(\hat{Q} - Q)[\varphi_{\eta} - \varphi]| &\leq \sqrt{2\varepsilon^{d-3} \int_{\Sigma} |\hat{h}|^2 + |h|^2 d\mathcal{H}^{d-1}} \sqrt{\varepsilon^{d-3} \mathcal{H}^{d-1}(\Sigma \cap \mathcal{U}''_{\eta})} \|\varphi\|_{\infty} \varepsilon \\ &\leq C_{\xi}(\zeta, \eta) \|\varphi\|_{\infty} \varepsilon \xrightarrow{\varepsilon \downarrow 0} 0. \end{aligned}$$

Therefore, we may and do substitute φ_η for φ and assume $\varphi \in W^{1,\infty}(\mathbf{R}^d)$ in the proof of (b). Remark that albeit not explicitly written, φ_η depends on ε . Let us summarize the properties of φ_η :

$$\|\varphi_\eta\|_\infty \leq \|\varphi\|_\infty, \quad \text{supp } \varphi_\eta \subset \mathcal{G}'_\eta, \quad (4.6)$$

$$\|\nabla \varphi_\eta\|_{L^\infty(\mathcal{G}''_\eta)} \leq \|\nabla \varphi\|_\infty, \quad \|\nabla \varphi_\eta\|_{L^\infty(\mathcal{U}''_\eta)} \leq \varepsilon^{-1} \|\varphi\|_\infty + \|\nabla \varphi\|_\infty. \quad (4.7)$$

In particular $\chi_\eta \equiv 1$ on the support of φ_η and we can drop the factor χ_η and replace Σ by $\Gamma_\eta \subset \Sigma_0$ in the definitions of $Q_{(\varepsilon)}[\varphi_\eta]$ and $\hat{Q}_{(\varepsilon)}[\varphi_\eta]$.

In the sequel we write Q and \hat{Q} for $Q[\varphi_\eta]$ and $\hat{Q}[\varphi_\eta]$. Using formula (4.5), we rewrite \hat{Q} as an integral over $(x, y) \in \Sigma \times \mathbf{R}^d$. Then, performing the change of variables $z = x + y \in \mathbf{R}^d$, $x \in \Gamma_\eta$ and using Fubini, we obtain, for $i = 1, \dots, d-1$,

$$\hat{Q}_i = \varepsilon^{d-2} \int_{\mathbf{R}^d} \sigma(z) \cdot \hat{q}_i(z) dz,$$

with the notation $\hat{Q} = (\hat{Q}_1, \dots, \hat{Q}_d)$ and

$$\hat{q}_i(z) := \int_{\Gamma_\eta} \varphi_\eta(\varepsilon x) n_i(x) [\zeta_\perp \nabla_y \zeta_{//}] (z-x; n(x)) d\mathcal{H}^{d-1}(x). \quad (4.8)$$

Here $n_i(x)$ denotes the i -th component of $n(x)$.

Next, having in mind the identities $\pi_{\bar{n}} \nabla_y \zeta_{//}(y; \bar{n}) = \nabla_y \zeta_{//}(y; \bar{n})$ and $\pi_{\bar{n}} \nabla_y \zeta_\perp(y; \bar{n}) = 0$, we compute the expansion,

$$\begin{aligned} \pi_{n(x)} \nabla_x \left[\varphi_\eta(\varepsilon x) \zeta(z-x; n(x)) n_i(x) \right] \\ = a_i(x, z) + b_i(x, z) + \varphi_\eta(\varepsilon x) \pi_{n(x)} c_i(x, z), \end{aligned} \quad (4.9)$$

where:

- a. The term $a_i(x, z)$ involves the gradient of the function $y \mapsto \zeta(y; \bar{n})$,

$$a_i(x, z) := -\varphi_\eta(\varepsilon x) n_i(x) [\zeta_\perp \nabla_y \zeta_{//}] (z-x; n(x)).$$

Remark that $a_i(x, z)$ is the negative of the integrand in (4.8).

- b. The term $b_i(x, z)$ involves the gradient of $x \mapsto \varphi_\eta(\varepsilon x)$.

$$b_i(x, z) := \varepsilon \zeta(z-x; n(x)) n_i(x) \pi_{n(x)} \nabla \varphi_\eta(\varepsilon x).$$

- c. The last term $c_i(x, z)$ involves the gradient of $n(x)$. It can be written on the following form,

$$c_i(x, z) = \sum_{k=1}^d \frac{\partial [\zeta(z-x; \bar{n}) \bar{n}_i]}{\partial \bar{n}_k} \Big|_{\bar{n}=n(x)} \nabla n_k(x) = \sum_{j=1}^d c_{i,j}(x; z) \nabla n_j(x). \quad (4.10)$$

We have $\text{supp}[c_{i,j}(\cdot; z)] \subset D_{\sqrt{2}}(z)$ and $\|c_{i,j}\|_\infty \leq C(\zeta)$.

Integrating (4.9) on Γ_η and applying the Green formula (4.3) to the left hand side, we get,

$$\begin{aligned}\hat{q}_i(z) &= - \int_{\Gamma_\eta} a_i(x, z) d\mathcal{H}^{d-1}(z) \\ &= \int_{\Gamma_\eta} \varphi_\eta(\varepsilon x) \zeta(z-x; n(x)) n_i(x) h(x) n(x) d\mathcal{H}^{d-1}(x) \\ &\quad + \int_{\Gamma_\eta} b_i(x, z) d\mathcal{H}^{d-1}(x) + \int_{\Gamma_\eta} \varphi_\eta(\varepsilon x) \pi_{n(x)} c_i(x, z) d\mathcal{H}^{d-1}(x).\end{aligned}$$

Taking the dot product with $\sigma(z) = n(x) + [\sigma(z) - n(x)]$, integrating in $z \in \mathbf{R}^d$ and changing back the variables of integration to $y = z - x, x = x$, we obtain,

$$\hat{Q}_i = \hat{Q}_{i,1} + \hat{Q}_{i,2} + \hat{Q}_{i,3} + \hat{Q}_{i,4},$$

with

$$\begin{aligned}\hat{Q}_{i,1} &:= \varepsilon^{d-2} \int_{\Gamma_\eta} \left[\int_{\mathbf{R}^d} \zeta(\cdot; n(x)) \right] h(x) \varphi_\eta(\varepsilon x) n_i(x) d\mathcal{H}^{d-1}(x) \\ \hat{Q}_{i,2} &:= \varepsilon^{d-2} \int_{\Gamma_\eta} \left[\int_{\mathbf{R}^d} \zeta(\cdot; n(x)) (\sigma(x+\cdot) - n(x)) \right] \cdot n(x) h(x) \varphi_\eta(\varepsilon x) n_i(x) d\mathcal{H}^{d-1}(x) \\ \hat{Q}_{i,3} &:= \varepsilon^{d-1} \int_{\Gamma_\eta} \left[\int_{\mathbf{R}^d} \zeta(\cdot; n(x)) \sigma(x+\cdot) \right]^T \pi_{n(x)} \nabla \varphi_\eta(\varepsilon x) d\mathcal{H}^{d-1}(x) \\ \hat{Q}_{i,4} &:= \varepsilon^{d-2} \sum_{j=1}^d \int_{\Gamma_\eta} \left[\int_{\mathbf{R}^d} c_{i,j}(x, x+\cdot) \sigma(x+\cdot) \right]^T \pi_{n(x)} \nabla n_j(x) \varphi_\eta(\varepsilon x) d\mathcal{H}^{d-1}(x).\end{aligned}$$

Let us consider $\hat{Q}_{i,1}$. By definition of ζ , the term into brackets is equal to 1. Therefore,

$$\hat{Q}_{i,1} = Q_i. \quad (4.11)$$

We have to establish that the three remaining terms go to 0 as $\varepsilon \downarrow 0$.

Let us fix a point $x \in \Gamma_\eta$. The harmonic function ψ_x given by Lemma 2.5.c applied in $x + D_{1-\xi}^\xi(n(x))$ satisfies $\nabla \psi_x(x) = 0$ and $n(x) \cdot \nabla \psi_x \equiv 0$. In particular, we can substitute $[\sigma(x+\cdot) - n(x) - \nabla \psi_x(x+\cdot)]$ for $[\sigma(x+\cdot) - n(x)]$ in the definition of $\hat{Q}_{i,2}$. Using (2.13) and the Cauchy-Schwarz inequality, we compute

$$\begin{aligned}|\hat{Q}_{i,2}| &\leq C(\xi) \|\varphi\|_\infty \varepsilon^{d-2} \int_{\Gamma_\eta} \sqrt{\mathcal{E}(B_{\sqrt{2}}(x))} |h|(x) d\mathcal{H}^{d-1}(x) \\ &\leq C(\xi) \|\varphi\|_\infty \varepsilon \sqrt{\varepsilon^{d-3} \mathcal{W}(\Sigma)} \sqrt{\varepsilon^{d-3} \int_{\Gamma_\eta} \mathcal{E}(B_{\sqrt{2}}(x)) d\mathcal{H}^{d-1}(x)}.\end{aligned}$$

Using Fubini and taking into account Lemma 2.2, we obtain

$$|\hat{Q}_{i,2}| \leq C(\xi, \eta) \|\varphi\|_\infty \varepsilon \sqrt{\varepsilon^{d-3} \mathcal{W}(\Sigma)} \sqrt{\varepsilon^{d-3} \int_{\Omega} f_0(\sigma, \nabla t)}.$$

Unscaling, we get

$$|\hat{Q}_{i,2}| \leq C(\xi, \eta) \|\varphi\|_\infty \sqrt{\mathcal{W}(\Sigma_\varepsilon)} \sqrt{E_0} \varepsilon \xrightarrow{\varepsilon \downarrow 0} 0. \quad (4.12)$$

Next, we consider $\hat{Q}_{i,3}$. We first notice that $n(x) \cdot \pi_{n(x)} \equiv 0$ so that we can substitute $[\sigma(x + \cdot) - n(x)]$ for $\sigma(x + \cdot)$ in the integral into brackets. Now, since $n(x) \cdot \nabla \psi_x \equiv 0$ and $\zeta(\cdot; n(x))$ is radially symmetric with respect to the direction $n(x)$, the mean value property yields

$$\int_{\mathbf{R}^d} \zeta(y; n(x)) \nabla \psi_x(x+y) dy = \nabla \psi_x(x) = 0. \quad (4.13)$$

Therefore, we can substitute $[\sigma(x + \cdot) - n(x) - \nabla \psi_x(x + \cdot)]$ for $\sigma(x + \cdot)$ in the definition of $\hat{Q}_{i,3}$. Proceeding as above, we obtain

$$\begin{aligned} |\hat{Q}_{i,3}| &\leq C(\xi) \sqrt{\varepsilon^{d-3} \int_{\Omega} f_0(\sigma, \nabla t)} \sqrt{\varepsilon^{d-1} \int_{\Sigma} |\nabla \varphi_\eta|^2 d\mathcal{H}^{d-1}} \varepsilon \\ &\leq C_{\xi}(\xi) \left(\|\nabla \varphi_\eta\|_{L^\infty(\Sigma \cap \mathcal{G}_\eta'')} + \|\nabla \varphi_\eta\|_\infty \sqrt{\varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma \cap \mathcal{U}_\eta'')} \right) \varepsilon \\ &\stackrel{(2.23)}{\leq} C_{\xi}(\xi) \left(\|\nabla \varphi_\eta\|_{L^\infty(\Sigma \cap \mathcal{G}_\eta'')} + \|\nabla \varphi_\eta\|_\infty \varepsilon \right) \varepsilon \\ &\stackrel{(4.6)(4.7)}{\leq} C_{\xi}(\xi) \|\varphi\|_{W^{1,\infty}} \varepsilon \xrightarrow{\varepsilon \downarrow 0} 0. \end{aligned} \quad (4.14)$$

For the last term, we can obviously substitute $[\sigma(x + \cdot) - n(x)]$ for $\sigma(x + \cdot)$ but we can still also substitute $[\sigma(x + \cdot) - n(x) - \nabla \psi_x(x + \cdot)]$ as in fact

$$\begin{aligned} \int_{\mathbf{R}^d} \sum_{j=1}^d c_{i,j}(x, x+y) \nabla \psi_x^T(x+y) \pi_{n(x)} \nabla n_j(x) dy \\ = \int_{\mathbf{R}^d} \nabla \psi_x(x+y) \cdot \pi_{n(x)} c_i(x, x+y) dy = 0. \end{aligned} \quad (4.15)$$

To see this, we have to go back to the definition (4.10) of c_i . Without loss of generality, we assume that $x = 0$ and $n(x) = e_d$. By (4.10), we have for $1 \leq i \leq d-1$,

$$c_i(0, z) = \zeta(z; e_d) \nabla n_i(0) \stackrel{(4.13)}{\xrightarrow{}} \int_{\mathbf{R}^d} \nabla \psi_0(z) \cdot \pi_{e_d} c_i(0, z) = 0.$$

For $i = d$, we have

$$c_d(0, z) = \sum_{k=1}^{d-1} \frac{\partial[\zeta(z; \bar{n})]}{\partial \bar{n}_k} \Big|_{\bar{n} = e_d} \nabla n_k(0).$$

Writing $z = (z', z_d)$ and taking into account the relations

$$\zeta((z', z_d); e_d) = \zeta((z', -z_d); e_d), \quad \zeta(Rz; R\bar{n}) = \zeta(z; \bar{n}) \quad \text{for every } R \in \text{SO}(d),$$

we have using rotations in the plane (e_k, e_d) ,

$$\frac{\partial \zeta}{\partial \bar{n}_k}((z', z_d); \bar{n}) \Big|_{\bar{n} = e_d} + \frac{\partial \zeta}{\partial \bar{n}_k}((z', -z_d); \bar{n}) \Big|_{\bar{n} = e_d} = 0, \quad \text{for } k = 1, \dots, d-1.$$

Hence, since $\nabla \psi_0(z', z_d)$ does not depend on z_d , we have

$$\int_{\mathbf{R}^d} \nabla \psi_0(z) \cdot \pi_{e_d} c_d(0, z) = 0.$$

Therefore, (4.15) holds.

Substituting $[\sigma(x + \cdot) - n(x) - \nabla \psi_x(x + \cdot)]$ for $\sigma(x + \cdot)$ in the definition of $\hat{Q}_{i,4}$ and using (2.11) to bound $|\nabla n|(x) = |H|(x)$ and (2.13) as above, we deduce

$$\begin{aligned} |\hat{Q}_{i,4}| &\leq C(\xi) \|\varphi\|_\infty \varepsilon^{d-2} \int_{\Gamma_\eta} \left[\mathcal{E}(B_{\sqrt{2}}(x)) \right]^{3/4} d\mathcal{H}^{d-1}(x) \\ &\stackrel{\text{(Hölder)}}{\leq} C(\xi) \|\varphi\|_\infty \left[\varepsilon^{d-3} \int_{\Gamma_\eta} \mathcal{E}(B_{\sqrt{2}}(x)) d\mathcal{H}^{d-1}(x) \right]^{3/4} \left[\varepsilon^{d-1} \mathcal{H}^{d-1}(\Sigma) \right]^{1/4} \sqrt{\varepsilon} \\ &= C_\xi(\xi) \|\varphi\|_\infty \sqrt{\varepsilon} \xrightarrow{\varepsilon \downarrow 0} 0. \end{aligned} \quad (4.16)$$

Proposition 4.1.b then follows from (4.11),(4.12),(4.14) and (4.16). \square

4.2 Passage to the limit $\varepsilon \downarrow 0$, computation of the lower bound

Proceeding in the same way as to obtain the lower semicontinuity of \mathcal{W} (see (D.8)), we deduce from Proposition 4.1 that

$$\mathcal{W}(\psi_0) = \int_{\Sigma_0} (\theta_0^+ + \theta_0^-) |H_0|^2 d\mathcal{H}^{d-1} \leq \liminf_{\varepsilon \downarrow 0} \int_{\Sigma_\varepsilon} |\hat{h}_\varepsilon|^2 d\mathcal{H}^{d-1}. \quad (4.17)$$

By definition of \hat{h}_ε , we can replace the domain of integration by $\Gamma_{\varepsilon, \eta} := \varepsilon \Gamma_{(\varepsilon), \eta}$ in the last integral.

Let us recall the definition of the local energy at some point $x \in \Gamma_{(\varepsilon), \eta}$,

$$\mathcal{E}_{(\varepsilon)}(x) := \int_{B_3(x) \cap \Omega_\varepsilon} [f_0(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}) + |\nabla u_{(\varepsilon)} - \nabla t_{(\varepsilon)}|^2].$$

We introduce another local energy. Let $\alpha > 0$ be a small parameter, we set,

$$\mathcal{F}_{(\varepsilon), \alpha}(x) := \int_{x + D_{1-2\xi}^{2\xi}(n_{(\varepsilon)}(x))} f(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}) + \alpha \mathcal{E}_{(\varepsilon)}(x).$$

Remark 4.2 We add the term $\alpha \mathcal{E}_{(\varepsilon)}$ for compactness reasons. This term controls oscillations of ∇u and thus of Σ^0 .

We then consider local optimization problems associated with this local energy. By frame invariance, we only have to consider the case $x = 0$ and $n(x) = e_d$.

Definition 4.3 Let ζ , $\xi = \xi(\zeta)$, $\alpha > 0$ and $\eta \in (0, \xi/2)$ as above. We set

$$c_{\zeta, \eta, \alpha}(f) := \frac{1}{\mathcal{H}^{d-1}(D'_1)} \inf \left\{ \frac{\mathcal{F}_\alpha^\#(a^\#)}{|\hat{h}^\#|^2(a^\#)} : a^\# \in \mathcal{S}_\eta^\#, \hat{h}^\#(a^\#) \neq 0 \right\},$$

where:

(i) $\mathcal{S}_\eta^\#$ is the set of quadruplets $a^\# = (\sigma^\#, t^\#, u^\#, \Sigma^\#)$ with:

$$\sigma^\# \in L^2(B_3, \mathbf{R}^d), \quad t^\#, u^\# \in W^{1,2}(B_3, [-1, 1]), \quad \Gamma^\# \subset D_1^{1/2}(e_d),$$

such that:

- $t^\#$ is ω -continuous, $u^\#$ is ω_ε^* -continuous, $u^\# = t^\#$ in $\{|t^\#| \geq 9/10\}$,
- the vector field $\sigma^\#$ is divergence free in $\mathcal{D}'(\{|t^\#| < 1\})$,
- $u^\#$ is harmonic and $|\nabla u^\#| \geq 1/2$ in $D_1^{1/2}(e_d)$,
- $\Gamma^\#$ is the hypersurface:

$$\Gamma^\# = [u^\# = 0] \cap D_1^{1/2}(e_d),$$

and moreover, $0 \in \Gamma^\#$ and $\nabla u^\# / |\nabla u^\#|(0) = e_d$,

- we have the energy bound (see (4.4))

$$\int_{B_\lambda \cap \Omega^\#} (f_0(\sigma^\#, \nabla t^\#) + |\nabla u^\# - \nabla t^\#|^2) \leq \beta_\eta.$$

(ii) The local energy $\mathcal{F}_\alpha^\#(a^\#)$ is modeled on $\mathcal{F}_{(\varepsilon), \alpha}$:

$$\mathcal{F}_\alpha^\#(a^\#) := \int_{D_{1-2\xi}^{2\xi}} f(\sigma^\#, \nabla t^\#) + \alpha \mathcal{E}^\#(a^\#),$$

with

$$\mathcal{E}^\#(a^\#) := \int_{B_3 \cap \{|t^\#| < 1\}} [f_0(\sigma^\#, \nabla t^\#) + |\nabla u^\# - \nabla t^\#|^2].$$

(iii) The approximate curvature $\hat{h}^\#(a^\#)$ is defined as (compare to (4.5)):

$$\hat{h}^\#(a^\#) := \int_{\mathbf{R}^d} \sigma^\# \cdot (\zeta_\perp \nabla_y \zeta_\parallel)(y; e_d) dy. \quad (4.18)$$

The parameter $\eta \in (0, \xi/2)$ being fixed, according to the above definition we have for every $x \in \Gamma_{(\varepsilon), \eta}$, $\varepsilon \in (0, 1]$:

$$|\hat{h}_{(\varepsilon)}|^2(x) \leq \frac{1}{c_{\zeta, \eta, \alpha}(f)} \frac{1}{\mathcal{H}^{d-1}(D'_1)} \mathcal{F}_{(\varepsilon), \alpha}(x). \quad (4.19)$$

Using this inequality in (4.17), we obtain

$$\begin{aligned} & c_{\zeta, \eta, \alpha}(f) \mathcal{W}(\mathcal{V}_0) \\ & \leq \frac{1}{\mathcal{H}^{d-1}(D'_1)} \liminf_{\varepsilon \downarrow 0} \varepsilon^{d-3} \int_{\Gamma_{(\varepsilon), \eta}} \mathcal{F}_{(\varepsilon), \alpha}(x) d\mathcal{H}^{d-1}(x). \end{aligned} \quad (4.20)$$

Let us consider the integral in the right hand side. Replacing $\mathcal{F}_{(\varepsilon),\alpha}(x)$ by its definition, applying Fubini and taking into account Lemma 2.4, we get

$$\begin{aligned} \int_{\Gamma_{(\varepsilon),\eta}} \mathcal{F}_{(\varepsilon),\alpha}(x) d\mathcal{H}^{d-1}(x) &\leq \int_{\Omega_{(\varepsilon)}^{\xi/2}} f(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}) q_{(\varepsilon)} \\ &\quad + \alpha \int_{\Omega_{(\varepsilon)}} [f_0(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}) + |\nabla u_{(\varepsilon)} - \nabla t_{(\varepsilon)}|^2] q'_{(\varepsilon)}. \end{aligned}$$

with $\Omega_{(\varepsilon)}^{\xi/2} = [|t_{(\varepsilon)}|(y) < 1 - \xi/2]$,

$$q_{(\varepsilon)}(y) := \mathcal{H}^{d-1} \left(\left\{ x \in \Gamma_{(\varepsilon),\eta} : y \in x + D_{1-2\xi}^{2\xi}(n(x)) \right\} \right).$$

and $q'_{(\varepsilon)}(y) = \mathcal{H}^{d-1}(\Sigma_{(\varepsilon)}^0 \cap B_3(y))$.

By inequality (2.14) of Lemma 2.6, we have $q_{(\varepsilon)}(y) \leq \mathcal{H}^{d-1}(D'_1)(1+s(\eta))$ with $s(\eta) \rightarrow 0$ as $\eta \downarrow 0$. On the other hand, thanks to (2.22), we have $q'_{(\varepsilon)} \leq C_{\mathcal{F}}$. Hence,

$$\begin{aligned} \frac{1}{\mathcal{H}^{d-1}(D'_1)} \int_{\Gamma_{(\varepsilon),\eta}} \mathcal{F}_{(\varepsilon),\alpha}(x) d\mathcal{H}^{d-1}(x) \\ \leq (1+s(\eta)) \mathcal{F}(\sigma_{(\varepsilon)}, \nabla t_{(\varepsilon)}, \Omega_{(\varepsilon)}) + C_{\mathcal{F}} \alpha. \end{aligned}$$

Putting this estimate in (4.20), unscaling and sending η to 0 and then α to 0, we end with

$$\left[\liminf_{\alpha \downarrow 0} \liminf_{\eta \downarrow 0} c_{\zeta,\eta,\alpha}(f) \right] \mathcal{W}(\mathcal{V}_0) \leq \liminf_{\varepsilon \downarrow 0} \frac{\mathcal{F}(\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon)}{\varepsilon^3}.$$

Theorem 1.2 then follows from the next lemma which states the required lower bound for the local optimization problems.

Lemma 4.1 (Local optimization)

(a) For every $\alpha > 0$, there holds:

$$\liminf_{\eta \downarrow 0} c_{\zeta,\eta,\alpha}(f) \geq c_{0,\zeta}(f) := \frac{\det L}{2L_{2,2}} \left(\mathcal{H}^{d-1}(D'_1) \int_{D'_1} |\partial_{y_d} \zeta|^2(y; e_d) dy \right)^{-1},$$

where L is the 2×2 matrix defined in Lemma 3.1.

(b) There exists a sequence of admissible functions $(\zeta_k) \subset W^{1,\infty}(\mathbf{R}^d \times S^{d-1}, \mathbf{R}_+)$ (i.e. ζ_k complies to the constraints of Definition 4.1) such that

$$c_{0,\zeta_k}(f) \xrightarrow{k \uparrow \infty} c_0(f) = \frac{\det L}{3L_{2,2}}.$$

Proof Let us fix $\alpha > 0$ and let ζ be as in Definition 4.1. We first establish (a). For this, we consider a minimizing sequence $a_k^\# = (\sigma_k^\#, \nabla t_k^\#, \nabla u_k^\#, \Sigma_k^\#) \subset \mathcal{S}_{\eta_k}^\#$ such that $\eta_k \downarrow 0$, $\hat{h}_\zeta^\#(a_k^\#) \neq 0$ and

$$\lim_{k \uparrow \infty} \frac{\mathcal{F}_\alpha^\#(a_k^\#)}{|\hat{h}_\zeta^\#(a_k^\#)|^2} = \mathcal{H}^{d-1}(D'_1) \liminf_{\eta \downarrow 0} c_{\zeta,\eta,\alpha}(f).$$

Using the reflection symmetry with respect to the hyperplane e_d^\perp , we assume without loss of generality that $\hat{h}_\zeta^\#(a_k^\#) > 0$.

We start by proving that $c_{\zeta,\eta,\alpha}(f)$ is uniformly bounded with respect to η . Lemmas 2.4 and 2.5 have been stated for the quadruplets

$$\left(\sigma_{(\varepsilon)}, t_{(\varepsilon)}, u_{(\varepsilon)}, \Sigma_{(\varepsilon)}^0 \right)$$

but by definition of the sets $\mathcal{S}_\eta^\#$ they obviously also apply to the elements of the sequence $(a_k^\#)$ at point $x = 0$. In particular, $\sigma_k^\# \rightarrow e_d$ in $L^2(D_{1-\xi}^{2\xi})$, which implies $\hat{h}_\zeta^\#(a_k^\#) \rightarrow 0$.

Now let $\hbar \in (0, 1]$ and let us define $a^\# := (\sigma^\#, t^\#, u^\#, \Sigma^\#)$, as

$$\sigma^\#(y) = e_d + \hbar \left(\frac{1}{d-1} y' - y_d e_d \right), \quad t^\#(y) = u^\#(y) = y_d, \quad \Sigma^\# = D_1'.$$

We easily check that $\hat{h}_\zeta^\#(a^\#) = \hbar$, that $a^\# \in \mathcal{S}_\eta^\#$ for $\eta \in (0, \eta_0)$ for some $\eta_0 > 0$ depending on \hbar and that

$$\mathcal{F}_\alpha^\#(a^\#) \leq C(f) \hbar^2 = C(f) |\hat{h}_\zeta^\#(a^\#)|^2.$$

Therefore, $c_{\zeta,\eta,\alpha}(f) \leq C(f) / \mathcal{H}^{d-1}(S^{d-1})$. Since $(a_k^\#)$ is a minimizing sequence, we can restrict to $\mathcal{F}_\alpha^\#(a_k^\#) \leq C(f) |\hat{h}_\zeta^\#(a_k^\#)|^2$.

Using the notation $\tilde{h}_k := \hat{h}_\zeta^\#(a_k^\#)$, we now assume

$$\mathcal{F}_\alpha^\#(a_k^\#) \leq C(f) |\tilde{h}_k|^2 \xrightarrow{k \uparrow \infty} 0. \quad (4.21)$$

Let us call $\psi_k^\#$ the harmonic function given by Lemma 2.5.c applied to $a_k^\#$ and let us set $\psi_k^b := (1/\sqrt{\tilde{h}_k}) \psi_k^\#$. We define a vector field σ_k^b and a function t_k^b on $D_{1-2\xi}^{2\xi}$ by

$$\sigma_k^\# = e_d + \sqrt{\tilde{h}_k} \nabla \psi_k^b + \tilde{h}_k \sigma_k^b, \quad \nabla t_k^\# = e_d + \sqrt{\tilde{h}_k} \nabla \psi_k^b + \tilde{h}_k \nabla t_k^b. \quad (4.22)$$

(To fix the the constant, we assume $\int_{D_{1-2\xi}^{2\xi}} t_k^b = 0$)

Using (4.21) in the estimates of Lemma 2.5.c, we have

$$\|\nabla \psi_k^b\|_{L^2(D_{1-3\xi/2}^0)}^2 + \|\sigma_k^b\|_{L^2(D_{1-2\xi}^{2\xi})}^2 + \|\nabla t_k^b\|_{L^2(D_{1-2\xi}^{2\xi})}^2 \leq C(f, \alpha, \xi). \quad (4.23)$$

Hence, up to extraction of a subsequence, there exist two functions

$$\psi_\infty^b, t_\infty^b \in W^{1,2}(D_{1-2\xi}^{2\xi})$$

and a vector field $\sigma_\infty^b \in L^2(D_{1-2\xi}^{2\xi}, \mathbf{R}^d)$ such that ψ_∞^b is harmonic, $\partial_d \psi_\infty^b \equiv 0$, σ_∞^b is divergence free and

$$\nabla \psi_k^b \xrightarrow{k \uparrow \infty} \nabla \psi_\infty^b \quad \text{in } C^\infty(\overline{D_{1-2\xi}^0}), \quad (4.24)$$

$$\sigma_k^b \xrightarrow{k \uparrow \infty} \sigma_\infty^b, \quad \nabla t_k^b \xrightarrow{k \uparrow \infty} \nabla t_\infty^b \quad \text{weakly in } L^2(D_{1-2\xi}^{2\xi}). \quad (4.25)$$

To study the asymptotic behavior of $\mathcal{F}_\xi^\#(a_k^\#)$, we are going to use (4.22) and a Taylor expansion of f . The latter requires point-wise bounds. First, by (4.24), there exists a constant $K > 0$ such that

$$\sup_{D_{1-2\xi}^0} |\nabla \psi_k^b| \leq K.$$

We do not have pointwise bounds on the sequence $(\sigma_k^b, \nabla t_k^b)$ and we are led to reduce the domains of definition of these functions.

For this, let us introduce a small parameter $\rho > 0$. By the preceding estimate, for k large enough, say $k \geq k_0(\rho)$, there holds

$$\sqrt{\hbar_k} |\nabla \psi_k^b| < \rho \quad \text{on } D_{1-2\xi}^0.$$

Now, for $k \geq 0$, we set

$$S_{\rho,k} := \left\{ y \in D_{1-2\xi}^{2\xi} : |(\sigma_k^b(y), \nabla t_k^b(y))| < \rho / |\hbar_k| \right\}.$$

Notice, for later use, that since (σ_k^b) and (∇t_k^b) are bounded in $L^2(D_{1-2\xi}^{2\xi})$ and $\hbar_k \rightarrow 0$, we have

$$\mathcal{H}^{d-1}(D_{1-2\xi}^{2\xi} \setminus S_{\rho,k}) \xrightarrow{k \uparrow \infty} 0. \quad (4.26)$$

Since f is of class C^2 in some neighborhood of \mathbb{S}^{d-1} , there exists $\rho_0 > 0$ and a sublinear modulus of continuity $\omega_f(r) \xrightarrow{r \downarrow 0} 0$ such that for $\sigma', \tau', \sigma'', \tau'' \in B_{\rho_0}(e_d)$, we have

$$|D^2 f(\sigma'', \tau'') - D^2 f(\sigma', \tau')| \leq \omega_f(|(\sigma'' - \sigma', \tau'' - \tau')|). \quad (4.27)$$

Let us now assume $\rho \in (0, \rho_0/2)$ and let us fix for a moment $k \geq k_0(\rho)$ and $y \in S_k$ so that by construction, we have $\sigma_k^\#(y), \nabla t_k^\#(y) \in B_{\rho_0}(e_d)$. We set

$$m := e_d + \sqrt{\hbar_k} \nabla \psi_k^b(y), \quad n := m/|m|,$$

(we also have $n \in B_{\rho_0}(e_d)$). Let us also introduce the pairs of vectors,

$$M := (m, m), \quad N := (n, n), \quad \text{and} \quad Q := \hbar_k \left(\sigma_k^b(y), \nabla t_k^b(y) \right),$$

We estimate $f(\sigma_k^\#(y), \nabla t_k^\#(y))$ from below by using (4.22) and a Taylor expansion of f at N . Taking into account $f(N) = 0$, $Df(N) = 0$ and (4.27), we obtain

$$\begin{aligned} f(\sigma_k^\#(y), \nabla t_k^\#(y)) &= f(N + (M - N + Q)) \\ &\geq \frac{1}{2} (M - N + Q)^T D^2 f(N) (M - N + Q) - \frac{1}{2} \omega_f(2\rho) |M - N + Q|^2. \end{aligned}$$

We rewrite the quadratic term as

$$D^2 f(N) = D^2(f(e_d, e_d)) + [D^2 f(N) - D^2(f(e_d, e_d))].$$

Since, $|n - e_d| < \rho$, this leads to

$$\begin{aligned} & f(\sigma_k^\#(y), \nabla t_k^\#(y)) \\ & \geq \frac{1}{2} (M - N + Q)^T D^2 f(e_d, e_d) (M - N + Q) - \omega_f(2\rho) |M - N + Q|^2. \end{aligned} \quad (4.28)$$

Now performing a Taylor expansion of $m - n$, we get

$$m - n = \frac{\hbar_k}{2} |\nabla \psi_k^b|^2(y) e_d + O(|\hbar_k|^{3/2} K^3).$$

Hence, setting

$$\mathbf{v}_k^b := \sigma_k^b + \frac{|\nabla \psi_k^b|^2}{2} e_d, \quad \boldsymbol{\tau}_k^b := \nabla t_k^b + \frac{|\nabla \psi_k^b|^2}{2} e_d,$$

we obtain,

$$M - N + Q = \hbar_k \left(\mathbf{v}_k^b, \boldsymbol{\tau}_k^b \right) + O(|\hbar_k|^{3/2} K^3).$$

Substituting this expansion in (4.28), dividing by $(\hbar_k)^2$ and integrating on $S_{\rho,k}$, we get

$$\begin{aligned} \frac{1}{|\hbar_k|^2} \mathcal{F}_\zeta^\#(a_k^\#) & \geq \frac{1}{2} \int_{S_{\rho,k}} \left(\mathbf{v}_k^b(y), \boldsymbol{\tau}_k^b(y) \right)^T D^2 f(e_d, e_d) \left(\mathbf{v}_k^b(y), \boldsymbol{\tau}_k^b(y) \right) \\ & \quad - 2\omega_f(2\rho) \left(2C(K) \mathcal{H}^{d-1}(D'_1) + C(\alpha, \xi) \right), \end{aligned} \quad (4.29)$$

where we have used (4.23) to bound the remainder.

Let $\chi_{\rho,k}$ be the characteristic function of $S_{\rho,k}$. We deduce from (4.24) (4.25) and (4.26), that

$$\begin{aligned} \left(\chi_{\rho,k} \mathbf{v}_k^b, \chi_{\rho,k} \boldsymbol{\tau}_k^b \right) & \xrightarrow{k \uparrow \infty} \left(\mathbf{v}_\infty^b, \boldsymbol{\tau}_\infty^b \right) := \left(\sigma_\infty^b + \frac{|\nabla \psi_\infty^b|^2}{2} e_d, \nabla t_\infty^b + \frac{|\nabla \psi_\infty^b|^2}{2} e_d \right) \\ & \text{weakly in } L^2(D_{1-2\xi}^{2\xi}). \end{aligned}$$

By positivity of $D^2 f(e_d, e_d)$, the functional

$$W \in L^2(D_{1-2\xi}^{2\xi}) \mapsto \int_O W^T D^2 f(e_d, e_d) W$$

is lower semicontinuous with respect to the topology of weak convergence in L^2 . Therefore, sending k to $+\infty$ in (4.29), then sending η to 0 and taking into account the fact that $\rho > 0$ is arbitrary, we end with

$$\mathcal{H}^{d-1}(D'_1) \left[\liminf_{\eta \downarrow 0} c_{\zeta, \eta, \alpha} \right] \geq \frac{1}{2} \int_{D_{1-2\xi}^{2\xi}} (\mathbf{v}_\infty^b, \boldsymbol{\tau}_\infty^b)^T D^2 f(e_d, e_d) (\mathbf{v}_\infty^b, \boldsymbol{\tau}_\infty^b).$$

We simplify further the right hand side by using the structure of $D^2f(e_d, e_d)$ described in Lemma 3.1. Calling $p = (v_{\infty, d}^b, \tau_{\infty, d}^b)$ the last components of the vector fields $v_{\infty}^b, \tau_{\infty}^b$, we obtain,

$$\mathcal{H}^{d-1}(D'_1) \left[\liminf_{\eta \downarrow 0} c_{\zeta, \eta, \alpha} \right] \geq \frac{1}{2} \int_{D_{1-2\xi}^{2\xi}} p^T L p. \quad (4.30)$$

where the positive symmetric 2×2 matrix L is defined by (3.1).

Now we pass to the limit in the affine constraint. Putting the expansion (4.22) of $\sigma_k^\#$ in the definition of $\tilde{h}_k = h_\zeta^\#(a_k^\#)$ and using the facts that $\psi_k^\#$ is harmonic and does not depend on y_d , we deduce from the constraint (4.18),

$$\int_{\mathbf{R}^d} \sigma_k^b \cdot (\zeta_\perp \nabla_y \zeta_{//}) (y; e_d) dy = 1.$$

Passing to the limit $k \uparrow \infty$, σ_∞^b satisfies the constraint

$$\int_{\mathbf{R}^d} \sigma_\infty^b \cdot (\zeta_\perp \nabla_y \zeta_{//}) (y; e_d) dy = 1. \quad (4.31)$$

Since $\nabla \cdot \sigma_\infty^b \equiv 0$ and ζ is compactly supported, this amounts to

$$\int_{\mathbf{R}^d} \sigma_{\infty, d}^b(y) \partial_{y_d} \zeta (y; e_d) dy = -1.$$

Now, since $p_1 = \sigma_{\infty, d}^b + |\nabla \psi_\infty^b|^2/2$ and $\nabla \psi_\infty^b$ does not depend on y_d , we also have

$$\int_{\mathbf{R}^d} p_1(y) \partial_{y_d} \zeta (y; e_d) dy = -1. \quad (4.32)$$

Eventually, we have to optimize the right hand side of (4.30) with respect to the elements $p \in L^2(D_{1-2\xi}^\xi, \mathbf{R}^2)$ satisfying the constraint (4.32). Since L is positive definite, the minimizer exists and is unique. The Euler-Lagrange equations lead to $p_{opt} = \lambda \partial_{y_d} \zeta(\cdot; e_d) L^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, where the Lagrange multiplier

$$\lambda = \frac{\det L}{L_{2,2} \|\partial_{y_d} \zeta(\cdot; e_d)\|_{L^2(D_1^0)}^2}$$

is fixed by the constraint. The minimal energy is $\lambda/2$. Together with (4.30), this leads to

$$\mathcal{H}^{d-1}(D'_1) \left[\liminf_{\eta \downarrow 0} c_{\zeta, \eta, \alpha} \right] \geq \frac{\det L}{2L_{2,2} \|\partial_{y_d} \zeta(\cdot; e_d)\|_{L^2(D_1^0)}^2},$$

and (a) is proved.

(b) We now optimize in ζ . We are looking for the largest possible lower bound so the smallest possible $\|\partial_{y_d}\zeta\|_{L^2(D_1^0(e_d))}^2$. Minimizing this quantity under the constraints $\int_{D_1^0(e_d)} \zeta = 1$, $\partial_{y_d}\zeta \in L^2(D_1^0(e_d))$ and $\zeta = 0$ on $\{y \in \partial D_1^0(e_d) : y_d = \pm 1\}$, we obtain as unique minimizer

$$\zeta_0(y) = \frac{3}{4\mathcal{H}^{d-1}(D_1^0)} (1 - y_d^2) \quad \text{with} \quad \mathcal{H}^{d-1}(D_1^0) \int_{D_1^0(e_d)} |\partial_{y_d}\zeta_0|^2 = \frac{3}{2}.$$

As required, we have $c_{0,\zeta_0}(f) = (\det L)/(3L_{2,2})$ and ζ_{opt} is a product of smooth functions depending on tangential and thickness coordinates respectively. However, we can not use ζ_0 in Definition 4.1 because it is not compactly supported in $D_1^0(e_d)$. Anyway, we can approximate ζ_0 by a sequence of compactly supported function $(\zeta_j) \subset W^{1,\infty}(D_1^0(e_d) \times S^{d-1})$ that comply to the requirements of Definition 4.1. For example:

$$\zeta_j(R(y', y_d); R e_d) := \zeta_j((y', y_d); e_d) := \frac{j+1}{j} \frac{\theta_j(y')}{\|\theta_j\|_{L^1(D_1^0)}} \zeta_0\left(y', \frac{j+1}{j} y_d\right),$$

with $\theta_j \in \mathcal{D}(D_1^0, [0, 1])$ satisfying $\theta_j(y') = 1$ for $|y'| \leq 1 - 2/j$. For such a sequence, we have $c_{0,\zeta_j}(f) \rightarrow (\det L)/(3L_{2,2})$ as $j \uparrow \infty$ which establishes part (b) of the lemma. \square

5 Concluding remarks

Before addressing the case of membranes with non-zero spontaneous curvature, let us discuss the hypotheses of our main results.

Upper-bound in the general case.

To complete the Γ -limit analysis, we should extend the construction of a recovery family of Theorem 1.3 to any data $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$. Namely, we should prove that given $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$ there exists a family $\{a_\varepsilon\}_{0 < \varepsilon \leq 1}$, with $a_\varepsilon \in \mathcal{A}_\varepsilon(R, S)$ such that $\mathcal{V}_\varepsilon^*(a_\varepsilon) \rightarrow \mathcal{V}_0$ and $\mathcal{F}(a_\varepsilon)/\varepsilon^3 \rightarrow \mathcal{W}(\Sigma_0)$ as $\varepsilon \downarrow 0$. A natural way for this would be to answer positively the following question.

Question 5.1 Let $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$. Does there exist a sequence of smooth open sets $(O_k) \subset B_R$ with outward unit normal ν_k and boundary Σ_k such that (1.5) holds and furthermore,

$$\mathcal{W}(\Sigma_k) \xrightarrow{k \uparrow \infty} \mathcal{W}(\mathcal{V}_0) ?$$

As described in Section 2.6, the elements of \mathcal{A}_0 are oriented rectifiable $(d-1)$ -varifolds with a generalized mean curvature in L^2 . To our knowledge the best regularity result established for varifolds with a generalized mean curvature is due to A. Menne [10] who established their C^2 -rectifiability (see also R. Schätzle [12] and references therein). In this context, giving a positive answer to Question 5.1 seems a difficult task.

The uniform continuity hypothesis.

We would like to get rid of the uniform continuity hypothesis on $x \mapsto \varepsilon^{-1}t_\varepsilon(\varepsilon x)$ (Hypothesis 1) and establish the compactness result under sole energy bounds.

We could try to relax the hypothesis by approximating the functions

$$t_\varepsilon \in W_{loc}^{1,2}(\mathbf{R}^d, [-\varepsilon, \varepsilon])$$

by Lipschitz continuous functions \hat{t}_ε as in the Appendix of [6] — see also Evans and Gariepy [5], Section 6.6.3, Theorem 3. In doing this, we should also substitute $\hat{\Omega}_\varepsilon = \{|\hat{t}_\varepsilon| < \varepsilon\}$ for the domain Ω_ε and find a vector field $\hat{\sigma}_\varepsilon$ which approximates σ_ε and is divergence free in $\hat{\Omega}_\varepsilon$. The fact that the topologies of Ω_ε and $\hat{\Omega}_\varepsilon$ could be different is an obstacle for such construction. For instance, if $\sigma = x/|x|^d$ in $B_1 \setminus \overline{B_\rho}$ then we can not extend σ as a divergence free vector field in B_1 . As a conclusion, we leave the relaxation of the uniform continuity hypothesis as an open problem.

The confining hypothesis.

We would also like to weaken the confining hypothesis: $[t_\varepsilon \equiv \varepsilon]$ in the complement of B_R . This hypothesis is only needed to prevent Σ_ε from escaping to infinity when passing to the limit $\varepsilon \downarrow 0$. This is feasible, at least for $d = 2$ and $d = 3$.

In dimension $d = 2$, the bad sets introduced in the compactness step are empty for ε small enough: indeed, the number of bad balls in Lemma 2.7 satisfies $N \leq C_\varepsilon(\beta)\varepsilon$. Therefore, for ε small enough $\Sigma_\varepsilon = [u_\varepsilon = 0]$ is a finite union of non-intersecting analytic Jordan curves. Their total length and their elastic energy $\mathcal{W}(\Sigma_\varepsilon)$ is uniformly bounded. Substituting the condition “ $t_\varepsilon \equiv \varepsilon$ in the neighborhood of infinity” for the confining assumption, we can track the different connected components by using finitely many translations and obtain at the limit a finite number of $W^{1,2}$ -Jordan curves with total mass S .

In dimension $d = 3$, the number of bad balls is only uniformly bounded: $N \leq C_\varepsilon(\beta)$. However, the number of connected components of Σ_ε is uniformly bounded. Indeed, the Willmore energy of each component is bounded from below by 4π . Moreover, according to a result of Simon [14], Lemma 1.1 for every connected component Σ_ε^i we have

$$\text{diam}(\Sigma_\varepsilon^i) \leq C \sqrt{\mathcal{H}^{d-1}(\Sigma_\varepsilon^i) \mathcal{W}(\Sigma_\varepsilon^i)} \quad (\leq C_\varepsilon).$$

Hence, considering separately each connected component and using translations, we can assume that each connected component satisfies the confining assumption.

5.1 The case of a material with non vanishing spontaneous curvature

The model introduced in [11] is more general than the one we have considered so far. In Sections I.1.3, I.1.4, the divergence free condition is relaxed to

$$\nabla \cdot \left[\frac{\sigma_\varepsilon}{\rho(\mu t_\varepsilon)} \right] = 0 \quad \text{in } \mathcal{D}'(\Omega_\varepsilon), \quad (5.1)$$

where ρ is a smooth positive function satisfying $\rho(0) = 1$ and $\rho'(0) = -1$ and $\mu \in \mathbf{R}$ is a given value of the spontaneous curvature. As expected in [11], the results of the present paper extend to this case. More precisely, we claim that if we substitute for the Willmore functional, the following energy introduced by Helfrich [8],

$$\mathcal{W}_\mu(\Sigma) := \int_\Sigma |h - \mu|^2 d\mathcal{H}^{d-1},$$

then Theorems 1.1, 1.2 and 1.3 generalize to this setting without further changes.

Let us describe the modifications to be made in the proofs. We first consider the construction of the recovery family of Theorem 1.3. In this proof, we have to change the definition of σ_ε by adding the factor $\rho(\mu t(y))$ in the right hand side of (3.2) so that, by construction, $\nabla \cdot [1/\rho(\mu t)\sigma] \equiv 0$ in Ω_ε for $0 < \varepsilon < \varepsilon'_*/2$. Taking into account $\rho(0) = 1$, $\rho'(0) = -1$, the Taylor expansion (3.4) is changed to

$$\sigma_\varepsilon(x + s\nu_0(x)) = \nu_0(x) + s[h_0(x) - \mu]\nu_0(x) + O(s^2).$$

This amounts to substitute $h_0 - \mu$ for the mean curvature h_0 . As claimed, we get,

$$c_0(f)\mathcal{W}_\mu(\Sigma_0) = \lim_{\varepsilon \downarrow 0} \frac{\mathcal{F}(a_\varepsilon)}{\varepsilon^3}.$$

Let us now consider $R, S > 0$ and a family $a_\varepsilon = (\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon)$ satisfying the hypotheses of Theorem 1.1 except that we substitute (5.1) for the divergence free condition on σ_ε . The (obvious) key idea is to set

$$\sigma_\varepsilon^\mu := [1/\rho(\mu t_\varepsilon)]\sigma_\varepsilon,$$

and to consider the configurations $a_\varepsilon^\mu := (\sigma_\varepsilon^\mu, \nabla t_\varepsilon, \Omega_\varepsilon)$. By construction, we have $a_\varepsilon^\mu \in \mathcal{A}_\varepsilon(R)$. Let us introduce the notation

$$Q_\varepsilon^\mu := \mathcal{Q}(\sigma_\varepsilon^\mu, \nabla t_\varepsilon)/(2\varepsilon), \quad F_\varepsilon^\mu := \mathcal{F}_0(a_\varepsilon^\mu)/\varepsilon^3.$$

We claim that $\{a_\varepsilon^\mu\}$ satisfies the hypotheses of the theorem except that the constraint on the quantity of material only holds at the limit. More precisely, we have:

$$F_\varepsilon^\mu \leq C_\sharp, \quad |Q_\varepsilon^\mu - S| \leq C_\sharp \varepsilon. \quad (5.2)$$

Proof (of (5.2)) First, since by hypothesis $\mathcal{Q}(\sigma_\varepsilon, \nabla t_\varepsilon) = 2S\varepsilon$, we have

$$Q_\varepsilon^\mu - S = \frac{1}{2\varepsilon} \int_{\Omega_\varepsilon} (1/\rho(\mu t_\varepsilon) - 1) \sigma_\varepsilon \cdot \nabla t_\varepsilon.$$

From $\rho(\mu t_\varepsilon) = 1 + O(\varepsilon)$ and using the inequality $|1 - \sigma_\varepsilon \cdot \nabla t_\varepsilon| \leq 2(f_0(\sigma_\varepsilon, \nabla t_\varepsilon) + \sqrt{f_0(\sigma_\varepsilon, \nabla t_\varepsilon)})$ (see (2.9)) we deduce,

$$|Q_\varepsilon^\mu - S| \leq C_\sharp \left[\mathcal{F}_0(a_\varepsilon) + \mathcal{H}^d(\Omega_\varepsilon) \right] \leq C_\sharp(\varepsilon^3 + \varepsilon Q'_\varepsilon), \quad (5.3)$$

where we have introduced the quantity $Q'_\varepsilon := \mathcal{H}^d(\Omega_\varepsilon)/(2\varepsilon)$. Similarly,

$$F_\varepsilon^\mu \leq C_\sharp \left(\mathcal{F}_0(a_\varepsilon)/\varepsilon^3 + \mathcal{H}^d(\Omega_\varepsilon)/\varepsilon \right) \leq C_\sharp(1 + Q'_\varepsilon). \quad (5.4)$$

Next, from the estimate (2.3) of Lemma 2.1, we also have

$$|Q'_\varepsilon - Q_\varepsilon^\mu| \leq C_\# \varepsilon^2 \left[F_\varepsilon^\mu + \sqrt{F_\varepsilon^\mu Q'_\varepsilon} \right]. \quad (5.5)$$

Combining (5.3) and (5.5) we first deduce $Q'_\varepsilon \leq S + C_\# \varepsilon^3 (1 + F_\varepsilon^\mu)$. With (5.4), this leads to $F_\varepsilon^\mu \leq C_\#$ and $Q'_\varepsilon \leq S + C_\# \varepsilon^3$. Returning to (5.3) we obtain (5.2). \square

With minor adjustments in the proof, we see that $\{a_\varepsilon^\mu\}$ satisfies the conclusion of Theorem 1.1 and owing to $\sigma_\varepsilon = (1 + O(\varepsilon))\sigma_\varepsilon^\mu$, the same convergence properties hold for the initial family $\{a_\varepsilon\}$.

Eventually, let us show that under the above assumptions, the conclusion of Theorem 1.2 (lower bound) holds with \mathscr{W}_μ in place of \mathscr{W} . We have two choices. Either we go further with a_ε^μ as main unknown and consider the stored energy function $f_\mu(s, \sigma, \tau) := f(\rho(\mu s)\sigma, \tau)$ or we come back to the initial unknown σ_ε . In the first case, we substitute σ_ε^μ for σ_ε in the definition of the approximate mean curvature, that is for $x \in \Sigma_\varepsilon$, we set

$$\hat{h}_\varepsilon(x) := \frac{\chi_{(\varepsilon), \eta}(\varepsilon x)}{\varepsilon} \int_{\mathbf{R}^d} \sigma_\varepsilon^\mu(x + \varepsilon z) \cdot \pi_{\mathbf{v}_\varepsilon(x)} \nabla_y \zeta(z; \mathbf{v}_\varepsilon(x)) dz. \quad (5.6)$$

With this definition, Proposition 4.1 still holds. In particular, \hat{h}_ε weakly approximates h_ε . Then, we define the energy of a_ε^μ as

$$\mathscr{F}_\mu(t_\varepsilon, \sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) := \int_{\Omega_\varepsilon} f_\mu(\sigma_\varepsilon^\mu, \nabla t_\varepsilon) = \int_{\Omega_\varepsilon} f(\sigma_\varepsilon, \nabla t_\varepsilon) = \mathscr{F}(\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon).$$

We are led to study a new class of local problems associated with the energy density functions f_μ which depends on the additional variable s . This point of view is interesting as it opens the way to other alternative models. However, for the sake of brevity, we continue with the second method.

We still build the family of hypersurfaces $\{\Sigma_\varepsilon\}$ and related objects from the family $\{a_\varepsilon^\mu\}$. We also define the approximate mean curvature by (5.6). Then, we want to define an approximation of $h - \mu$. Let us try

$$\begin{aligned} \hat{h}'_\varepsilon(x) &:= \frac{\chi_{(\varepsilon), \eta}(\varepsilon x)}{\varepsilon} \int_{\mathbf{R}^d} \sigma_\varepsilon(x + \varepsilon z) \cdot \pi_{\mathbf{v}_\varepsilon(x)} \nabla_y \zeta(z; \mathbf{v}_\varepsilon(x)) dz, \\ &= \frac{\chi_{(\varepsilon), \eta}(\varepsilon x)}{\varepsilon} \int_{\mathbf{R}^d} [\sigma_\varepsilon(x + \varepsilon z) - \mathbf{v}_\varepsilon(x)] \cdot \pi_{\mathbf{v}_\varepsilon(x)} \nabla_y \zeta(z; \mathbf{v}_\varepsilon(x)) dz \end{aligned} \quad (5.7)$$

which corresponds to the original definition of \hat{h} in the case $\mu = 0$. As already mentioned, the function \hat{h}_ε is an approximation of h_ε . Now for $x \in \Sigma_\varepsilon$, we have

$$\begin{aligned} \hat{h}'_\varepsilon(x) - \hat{h}_\varepsilon(x) &= \chi_{(\varepsilon), \eta}(\varepsilon x) \int_{\mathbf{R}^d} q_\varepsilon(x, z) [\sigma_\varepsilon(x + \varepsilon z) - \mathbf{v}_\varepsilon(x)] \cdot (\zeta_\perp \nabla_y \zeta_{//})(z; \mathbf{v}_\varepsilon(x)) dz, \end{aligned}$$

with $q_\varepsilon(x, z) := [\rho(\mu t_\varepsilon(x + \varepsilon z)) - 1]/\varepsilon$. Integrating by parts, we have,

$$\begin{aligned} & \hat{h}'_\varepsilon(x) - \hat{h}_\varepsilon(x) \\ &= -\chi_{(\varepsilon), \eta}(\varepsilon x) \int_{\mathbf{R}^d} \nabla_z [q_\varepsilon(x, z) \zeta_\perp(z; \mathbf{v}_\varepsilon(x))] \cdot [\sigma_\varepsilon^\mu(x + \varepsilon z) - \mathbf{v}_\varepsilon(x)] \zeta_{//}(z; \mathbf{v}_\varepsilon(x)) dz. \end{aligned}$$

Now from $|\nabla_z [q_\varepsilon(x, z) \zeta_\perp(z; \mathbf{v}_\varepsilon(x))]| \leq C(1 + |\nabla t_\varepsilon|(x + \varepsilon z))$, we deduce,

$$|\hat{h}'_\varepsilon(x) - \hat{h}_\varepsilon(x)| \leq C\chi_{(\varepsilon), \eta}(\varepsilon x) \left[[\mathcal{E}_3(x/\varepsilon)]^{1/2} + [\mathcal{E}_3(x/\varepsilon)]^{1/4} \right].$$

Integrating on Σ_ε , we deduce,

$$\int_{\Sigma_\varepsilon} |\hat{h}'_\varepsilon(x) - \hat{h}_\varepsilon(x)| \leq C_\xi(\varepsilon + \varepsilon^{1/2}) \xrightarrow{\varepsilon \downarrow 0} 0.$$

We conclude that \hat{h}'_ε is also a weak approximation of h_ε and not of $h_\varepsilon - \mu$.

Let us now give a relevant definition of a weak approximation of $h_\varepsilon - \mu$. For $x \in \Sigma_\varepsilon$, we set

$$\hat{h}_\varepsilon^\mu(x) := -\frac{\chi_{(\varepsilon), \eta}(\varepsilon x)}{\varepsilon} \int_{\mathbf{R}^d} \sigma_\varepsilon(x + \varepsilon z) \cdot \nabla_y \zeta_\perp(z; \mathbf{v}_\varepsilon(x)) \zeta_{//}(z; \mathbf{v}_\varepsilon(x)) dz.$$

When $\mu = 0$, we see (by integrating by parts) that this definition is the same as the definitions (5.6) or (5.7). In the general situation, an integration by parts leads to

$$\hat{h}_\varepsilon^\mu(x) - \hat{h}'_\varepsilon(x) = \chi_{(\varepsilon), \eta}(\varepsilon x) \int_{\mathbf{R}^d} \nabla_z \cdot \left[\frac{\sigma_\varepsilon(x + \varepsilon z)}{\varepsilon} \right] \zeta(z; \mathbf{v}_\varepsilon(x)) dz$$

Form the constraint 5.1 we have

$$\begin{aligned} \nabla_z \cdot \left[\frac{\sigma_\varepsilon(x + \varepsilon z)}{\varepsilon} \right] &= \mu \rho'(\mu t_\varepsilon) [\nabla t_\varepsilon \cdot \sigma_\varepsilon](x + \varepsilon z) \\ &= -\mu + \mu [1 - \nabla t_\varepsilon \cdot \sigma_\varepsilon](x + \varepsilon z) + O(\varepsilon) |\nabla t_\varepsilon \cdot \sigma_\varepsilon|(x + \varepsilon z). \end{aligned}$$

Therefore,

$$|\hat{h}_\varepsilon^\mu(x) - \hat{h}'_\varepsilon(x) - \mu| \leq C(\xi) \left(\sqrt{\mathcal{E}_3(x/\varepsilon)} + \mathcal{E}_3(x/\varepsilon) + \varepsilon \right),$$

and \hat{h}_ε^μ is a weak approximation of $h_\varepsilon - \mu$ in the sense of Proposition 4.1.

Now we can continue the proof of Theorem 1.2 by substituting \hat{h}_ε^μ for \hat{h}_ε and by performing the respective substitution in the definition of the local problem, *i.e.* replacing \hat{h}^\sharp by $\hat{h}^{\mu, \sharp}$ in Definition 4.3 with (4.18) replaced by

$$\hat{h}^{\mu, \sharp}(a^\sharp) := - \int_{\mathbf{R}^d} \sigma^\sharp \cdot (\zeta_{//} \nabla_y \zeta_\perp)(y; e_d) dy.$$

Then, in place of the identity (4.31), we have

$$\int_{\mathbf{R}^d} \sigma_\infty^b \cdot (\zeta_{//} \nabla_y \zeta_\perp)(y; e_d) dy = -1,$$

which yields, as before, the constraint (4.32) for the 2-dimensional final optimisation problem. No further changes are required.

Eventually, in order to pass the limit in $\mathcal{W}_\mu(\Sigma_\varepsilon)$ as $\varepsilon \downarrow 0$, we need to extend the definition of \mathcal{W}_μ as a lower semi-continuous functional defined on the set of oriented $(d-1)$ varifolds which admit a L^2 generalized mean curvature. With the notation of Appendix D, this is achieved by setting

$$\mathcal{W}_\mu(\mathcal{V}) := \mathcal{W}(\mathcal{V}) - 2\mu \langle \mathcal{V}; (x, n) \mapsto H(x) \cdot n \rangle + \mu^2 \langle \mathcal{V}; 1 \rangle. \quad (5.8)$$

With this definition, we have (compare (D.7))

$$\sqrt{\mathcal{W}_\mu(\mathcal{V})} = \|H - \mu n\|_{L^2(\mathbf{R}^d, \mathcal{V})} = \sup \langle \mathcal{V}; X \cdot (H - \mu n) \rangle,$$

where the supremum is taken over $\{X \in C_c^1(\mathbf{R}^d \times S^{d-1}); \|X\|_{L^2(\mathbf{R}^d, \mathcal{V})} \leq 1\}$. We deduce that the functional \mathcal{W}_μ is lower semicontinuous with respect to the convergence of measures. For the elements of \mathcal{A}_0 , we can write (compare (D.9)),

$$\mathcal{W}_\mu(\mathcal{V}_0) = \int_{\Sigma_0} |H_0 - \mu \nu_0|^2 (\theta_0^+ + \theta_0^-) d\mathcal{H}^{d-1}.$$

As a conclusion, substituting (5.8) for the generalized Willmore functional, Theorem 1.2 extends to the case $\mu \neq 0$.

A Proof of Lemma 2.3

let us rephrase the lemma.

Lemma A.1 *Let $t \in W_{loc}^{1,2}(\mathbf{R}^d)$, let O be a bounded open subset of \mathbf{R}^d and let u be the variational harmonic extension of t in O . We assume that there exists $\delta > 0$ and a (concave) modulus of continuity ω such that O has the exterior ball property with radius δ and that t is ω -continuous with values into $[-1, 1]$. Then there exists a modulus of continuity ω^* only depending on d, δ and ω such that u is ω^* -continuous in \mathbf{R}^d .*

Proof We start by regularizing the boundary data t and the domain. For $0 < \eta \leq \delta/2$, we set $t'_\eta := t \star \rho_\eta$ where $\rho_\eta = \eta^{-d} \rho(\cdot/\eta)$ is a standard non-negative mollifier, compactly supported in B_η . We also set $O'_\eta = O + B_\eta \supset O$.

Writing $t'_\eta(y) - t'_\eta(z) = \int [t(y-x) - t(z-x)] d\rho_\eta(x) \leq \int \omega(y-z) d\rho_\eta = \omega(y-z)$, we see that the functions $\{t'_\eta\}_{0 < \eta < \delta/2}$ are ω -continuous. They are also uniformly bounded in $W_{loc}^{1,2}(\mathbf{R}^d)$ and satisfy $-1 \leq t'_\eta \leq 1$.

By construction, the domain O'_η satisfies the exterior ball condition for balls with radii $\delta/2$ and the interior ball condition for balls with radii η . In particular $\partial O'_\eta$ has $C^{1,1}$ regularity and O'_η is a bounded Lipschitz domain.

Let u'_η be the variational harmonic extension of t'_η in O'_η , defined as

$$u'_\eta := \operatorname{argmin} \left\{ \int_{B_{R/\varepsilon}} |\nabla \varphi|^2 : \varphi \in W_{loc}^{1,2}(\mathbf{R}^d), \varphi \equiv t'_\eta \text{ a.e on } \mathbf{R}^d \setminus O'_\eta \right\}.$$

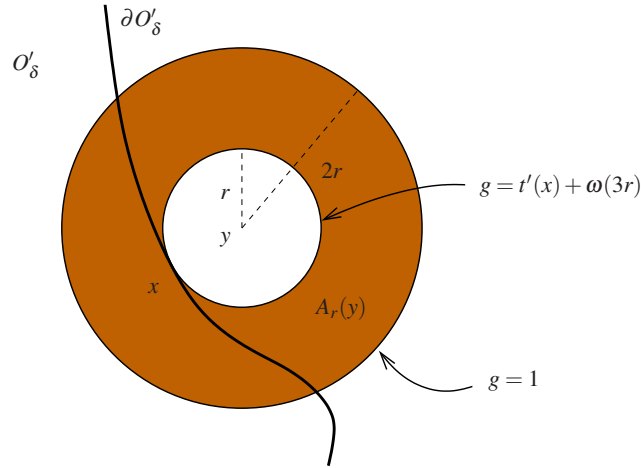


Fig. A.1 The barrier function g .

By classical elliptic regularity theory, u'_η is of class C^1 in $\overline{O'_\eta}$ and $u'_\eta \equiv t'_\eta$ on $\partial O'_\eta$. We claim that

$$\exists \text{ a modulus of continuity } \omega' = \omega'(\omega, \delta, d) \text{ such that } u'_\eta \in C_{\omega'}(\overline{O'_{\delta, \eta}}). \quad (\text{A.1})$$

Assuming the claim, there exists a function $u' \in W^{1,2}(B_{R/\varepsilon})$ such that, up to extraction, $u'_\eta \rightarrow u'$ as $\eta \downarrow 0$. Moreover, u' is harmonic in O , is ω' -continuous in \overline{O} and $u' \equiv t$ in $\mathbf{R}^d \setminus \overline{O}$. Hence $u = u'$ and u is ω' -continuous in \overline{O} . Since $u = t$ is ω -continuous in $\mathbf{R}^d \setminus \overline{O}$, we conclude that u is $(\omega + \omega')$ -continuous in \mathbf{R}^d and the lemma is proved.

Let us now establish (A.1). We fix $\eta \in (0, \delta/2]$ and drop the subscripts η .

Step 1 (interior estimate) First, by the maximum principle, we have in any case $|u'(y) - u'(z)| \leq 2$. Now, let $r \in (0, 1/2]$ and $B_r(x) \subset O'$. By harmonic regularity we have $|\nabla u| \leq C/r$ in $B_{r/2}(x)$. So $|u'(y) - u'(z)| \leq C\sqrt{|y-z|}$ for every $y, z \in B_{r/2}(x)$.

From this estimate, we conclude that we only have to establish that for any $x \in \partial O'$, $u'(z) \rightarrow u'(x)$ as $z \in O'_\delta \rightarrow x$ with a convergence rate that only depends on ω , δ and d .

Step 2 (continuity up to the boundary) Let us fix $x \in \partial O'_\delta$ and let $r \in (0, \delta/2]$.

By hypothesis, there exists a ball $B_r(y) \subset \mathbf{R}^d \setminus \overline{O'}$ such that $x \in \partial B_r(y)$.

As a barrier, we consider the harmonic function g defined on the ring $A_r(y) := B_{2r}(y) \setminus \overline{B_r}(y)$ and satisfying the boundary conditions $g \equiv t'(x) + \omega(3r)$ on $\partial B_r(y)$ and $g \equiv 1$ on $\partial B_{2r}(y)$ (see Figure A.1).

We claim that $g \geq u'$ in $A_r(y) \cap O'_\delta$. Indeed, $g - u'$ is harmonic on this set, so by the maximum principle it is sufficient to check the inequality on $\partial(A_r(y) \cap O')$. This boundary splits into:

$$\partial(A_r(y) \cap O') = (\partial B_{2r}(y) \cap \overline{O'}) \cup (\overline{A_r(y)} \cap \partial O').$$

On the first part, we have $g - u' = 1 - u' \geq 0$. On the second part $u' = t'$ on $\partial O'$, so, $g(z) - u'(z) = t'(x) + \omega(3r) - t'(z) \geq \omega(3r) - \omega(|x - z|) \geq 0$ since $|x - z| \leq 3r$ and t' is ω -continuous. Hence, $g \geq u'$ in $A_r(y) \cap O'$.

An explicit computation gives

$$g(z) = t'(x) + \omega(3r) + (1 - t'(x) - \omega(3r)) \frac{G(1) - G(|z - y|/r)}{G(1) - G(2)},$$

where $z \mapsto G(|z|)$ denotes a radially symmetric decreasing multiple of the fundamental solution of the Laplacian ($G(s) = -\ln s$ if $d = 2$ and $G(s) = s^{2-d}$ for $d \geq 3$). Hence, for every $x \in \partial O'$, $r \in (0, \delta/2)$ and $z \in O' \cap B_r(x)$, we have

$$u'(z) - t'(x) \leq g(z) - t'(x) \leq \omega(3r) + 2 \frac{G(1) - G(|z - y|/r)}{G(1) - G(2)}.$$

Substituting $-t'$ for t and $-u'$ for u , we obtain the corresponding result with opposite signs. We conclude that for every $x \in \partial O'$, $r \in (0, \delta/2)$ and $z \in O' \cap B_r(x)$,

$$|u'(z) - t'(x)| \leq \omega(3r) + 2 \frac{G(1) - G(|z - y|/r)}{G(1) - G(2)}.$$

In particular, for $x \in \partial O'$ and $z \in O'$, such that $|z - x| \leq \delta^2$, we can choose $r = \sqrt{|x - z|}$. In this case,

$$\frac{|z - y|}{r} \leq \frac{|x - y|}{r} + \frac{|z - x|}{r} = 1 + \sqrt{|z - x|}.$$

This leads to,

$$|u'(z) - t'(x)| \leq \omega(3\sqrt{|x - z|}) + 2 \frac{G(1) - G(1 + \sqrt{|z - x|})}{G(1) - G(2)} \underset{|z-x| \downarrow 0}{\rightarrow} 0.$$

This establishes the claim (A.1). \square

B Proofs of Lemmas 2.4, 2.5 and 2.6

B.1 proof of Lemma 2.4

(a) Without loss of generality, we assume $z = 0$ and $\xi \in (0, 1/20)$. Let $\eta > 0$. We establish by contradiction that (a) holds for $\beta > 0$ small enough.

If (a) were not true for any value of $\beta > 0$, there would exist two sequences $(a_k), (a'_k)$ with $a_k = (\sigma_k, \nabla t_k, O_k)$, $a'_k = (\sigma_k, \nabla u_k, O'_k)$ such that:

- (i) (a_k) and (a'_k) both satisfy the hypotheses of Theorem I.1.1 with $O = B_3$. In particular, (u_k) and (t_k) are uniformly equicontinuous.
- (ii) Either $|\nabla u_k|(0) < 1/2$;
or $|\nabla u_k|(0) \geq 1/2$ and using the notation

$$\bar{n}_k := \nabla u_k / |\nabla u_k|(0), \quad D_k := -u_k(0)\bar{n}_k + D_1^\xi(\bar{n}_k), \quad \varphi_k(y) = u_k(0) - z \cdot \bar{n}_k,$$

we have either:

- $D_k \not\subset O_k \cap O'_k$;
- or $D_k \subset O_k \cap O'_k$ and

$$\|t_k - \varphi_k\|_{L^\infty(\overline{D}_k)} + \|u_k - \varphi_k\|_{L^\infty(\overline{D}_k)} + \|\nabla t_k - \nabla \varphi_k\|_{L^2(D_k)} > \eta; \quad (\text{B.1})$$

(iii) Moreover, $|u_k|(0) \leq 1/2$ and setting $\tilde{F}_k := [|t_k| \geq 9/10] + \overline{B_\delta}$, we have (taking into account (2.10)) $u_k \equiv t_k$ on \tilde{F}_k and u_k is harmonic in $B_3 \setminus \tilde{F}_k$.

First, up to extraction, we may assume that both $(t_k(0))_k$ and $(u_k(0))_k$ converge towards respectively s and s' with $|s| \leq 9/10$ and $|s'| \leq 1/2$. By Theorem I.1.1 there exists $\bar{n}, \bar{n}' \in S^{d-1}$ such that

$$t_k \xrightarrow{k \uparrow \infty} \varphi \text{ on } C_{loc}(O_\star), \quad u_k \xrightarrow{k \uparrow \infty} \varphi' \text{ on } C_{loc}(O'_\star),$$

with $\varphi(y) := s + \bar{n} \cdot y$, $\varphi'(y) := s' + \bar{n}' \cdot y$, $O_\star = B_2 \cap [|\varphi| < 1]$, $O'_\star = B_2 \cap [|\varphi'| < 1]$.

Now, for any $k \geq 1$, u_k is harmonic in B_{δ_ξ} . By harmonic regularity, we see that $\nabla u_k(0) \rightarrow \nabla \varphi'(0) = \bar{n}'$. In particular, for k large enough, there holds

$$|\nabla u_k|(0) \geq 1/2.$$

Next, considering the segment $I = \{y + (r-s)\bar{n} : -1 < r < 1\} \subset O'_\star$, and the mapping $p : (-1, 1) \rightarrow I$ defined by $p(r) = y + (r-s)\bar{n}$, we have $u_k \circ p \rightarrow Id_{(-1,1)}$ as $k \uparrow \infty$.

In particular, for k large enough $|u_k| > 9/10$ on $p(19/20, 1)$ which implies $t_k \equiv u_k$ on $p(19/20, 1)$.

Passing to the limit we conclude that $\bar{n} = \bar{n}'$, $s = s'$ and $\varphi = \varphi'$. By uniform equicontinuity of the sequence (t_k) , and convergence of (t_k) towards φ' on O'_\star we then see that

$$\tilde{D}_k := -u_k(0)\bar{n}_k + D_{1+\xi}^{\xi/2}(\bar{n}_k) \subset [|t_k| < 1 - \xi/2], \quad \text{for } k \text{ large enough.}$$

We already know that the L^∞ norms in (B.1) converge to 0.

Applying the weak rigidity inequality of Theorem I.2.2 to t_k in $\tilde{D}_k \supset D_k$ we see that the $W^{1,2}$ -seminorms also converge to 0 which contradicts (B.1). This proves (a).

(b) Part (b) follows from (a), the harmonicity of u in the domain $[u < 4/5]$ and the implicit function theorem. However, we use below a fixed point method (somehow reproving the implicit function theorem).

We assume $\mathcal{E}_3(z) \leq \beta_a(\xi, \eta')$ where $\beta_a(\xi, \eta)$ denotes the positive constant provided by part (a) and where $\eta' \in (0, \eta)$ will be fixed later. As above we assume $\xi < 1/20$, we also assume without loss of generality $z_0 = 0$ and $n(z) = e_d$ so that $\varphi(y) = y_d$ and $D = D_1^\xi$.

We have to show that there exists an analytic function $\Psi : D'_1 \times (-1/2, 1/2) \rightarrow \mathbf{R}$ with $\|\Psi\|_{C^2} \leq \eta$ such that for every $(y, s) \in D_1^\xi \times (-1/2, 1/2)$, there holds

$$u(y) - s = 0 \iff y_d - s = \Psi(y', s). \quad (\text{B.2})$$

Step 1. Let us first notice that we can restrict the problem to a domain in which u is harmonic. Indeed, from part (a) we have for every $y \in D_1^\xi \setminus D_1^{3/8}$ and $|s| < 1/2$

$$|u(y) - s| \geq |\varphi(y) - s| - |u(y) - \varphi(y)| > 1/8 - \|u - \varphi\|_{L^\infty(D_1^\xi)} \geq 1/8 - \eta'.$$

Assuming $\eta' \leq 1/8$, the left hand side of (B.2) can only hold if $y \in D_1^{3/8}$. Now in this set, we have

$$|u(y)| \leq 5/8 + \|u - \varphi\|_{L^\infty(D_1^\xi)} \leq 5/8 + \eta' \leq 3/4.$$

Since u is harmonic in $[|u| < 4/5]$, we see that, by ω_ξ^* -continuity, u is harmonic in $D_1^{3/8} + B_\rho$ for some $\rho > 0$ only depending on ω_ξ^* . Also notice that for the same reason we may assume

$$\|u - \varphi\|_{L^\infty(D_1^{3/8} + B_\rho)} \leq 2\eta'. \quad (\text{B.3})$$

In summary, we only have to establish (B.2) for $(y, s) \in D_1^{3/8} \times (-1/2, 1/2)$ and we can assume that u is harmonic in $D_1^{3/8} + B_\rho$ and satisfies (B.3).

Step 2. Noting, $z_d = y_d - s$ and $\theta(y', s, z_d) := [u - \varphi](y', z_d + s)$, (B.2) rewrites as the fixed point problem

$$z_d = -\theta(y', s, z_d) \iff z_d = \Psi(y', s), \quad (\text{B.4})$$

in the convex domain $Q := \{(y', s, z_d) : y' \in D_1', |s| < 1/2, |z_d + s| < 5/8\}$. Now by (B.3) θ maps Q into $[-2\eta', 2\eta']$ and by harmonic regularity we have

$$\|D^k \theta\|_{L^\infty(Q)} \leq C(k)\eta'/\rho^k. \quad (\text{B.5})$$

Assuming $C(1)\eta'/\rho \leq 1/2$, we have in particular

$$\|\partial_{z_d} \theta\|_{L^\infty(Q)} \leq 1/2. \quad (\text{B.6})$$

Therefore applying Picard's iteration to (B.4), we obtain for every $(y', s) \in D_1^{1/2}$ the existence of a unique $z_d =: \Psi(y', s)$ satisfying (B.4). Moreover, we deduce from (B.5) that Ψ is smooth with

$$\|D^k \Psi\|_{L^\infty(D_1^{1/2})} \leq C(k)\eta'/\rho^k \quad \text{for } k \geq 0.$$

Hence assuming $\eta' > 0$ small enough we have, $\|\Psi\|_{C^2} \leq \eta$. Eventually, using again (B.6), we can apply the analytic implicit function theorem to $\Phi(y', s, z_d) := z_d + \theta(y', s, z_d)$ in the neighborhood of each point $(y', s, \Psi(y', s))$. We deduce that Ψ is analytic which ends the proof of (b).

(c) This point easily follows from (b).

B.2 proof of Lemma 2.5

Part (a) is a direct consequence of the preceding lemma. Part (b) follows from Corollary I.3.1 and the harmonicity of u in $B_{\delta_\xi^*}$.

Let us establish part (c). Without loss of generality, we assume $x = 0$ and $\xi \in (0, 1/20)$. We apply Theorem I.2.2 to the function u in the cylinder $D_{\text{int}} \subset D$ and in $B_{\delta_\xi^*} \subset D$. There exists $e'_*, e_* \in S^{d-1}$ such that

$$\begin{aligned} \int_{D_{\text{int}}} |\nabla u - e'_*|^2 &\leq C(\xi) \sqrt{\mathcal{E}(D)}, \\ \int_{B_{\delta_\xi^*}} |\nabla u - e_*|^2 &\leq C(\delta_\xi^*) \sqrt{\mathcal{E}(D)}. \end{aligned} \quad (\text{B.7})$$

In particular, we have $|e_* - e'_*|^2 \leq C(\xi, \delta_\xi^*) \sqrt{\mathcal{E}(D)}$. Moreover since u is harmonic in $B_{\delta_\xi^*}$, we see that by the mean value property we can choose $e_* = n(0) =: \bar{n}$ — as in the proof of Corollary I.3.1. Inequality (B.7) then implies

$$\int_{D_{\text{int}}} |\nabla u - \bar{n}|^2 \leq C(\xi, \delta_\xi^*) \sqrt{\mathcal{E}(D)}. \quad (\text{B.8})$$

Now, let us apply Theorem I.3.1 to u in $D_{\text{int}} \subset D$. There exists a harmonic function $\psi_1 \in L^2(D_{\text{int}})$ such that $\bar{n} \cdot \nabla \psi_1 \equiv 0$ and

$$\int_{D_{\text{int}}} |\nabla u - \bar{n} - \nabla \psi_1|^2 \leq C(\xi, \delta_\xi^*) \mathcal{E}(D). \quad (\text{B.9})$$

Now, notice that by orthogonality, we have

$$|\nabla \psi_1|^2(0) + |\nabla u(0) - \bar{n}|^2 = |\nabla u(0) - \nabla \psi_1(0) - \bar{n}|^2 \stackrel{(\text{B.9})}{\leq} C(\xi, \delta_\xi^*) \mathcal{E}(D).$$

In particular,

$$|\nabla \psi_1|^2(0) \leq C(\xi, \delta_\xi^*) \mathcal{E}(D). \quad (\text{B.10})$$

Eventually, setting $\psi(y) := \psi_1(y) - y \cdot \nabla \psi_1(0)$, the function ψ is harmonic in D_{int} , it satisfies $\bar{n} \cdot \nabla \psi \equiv 0$ and (2.13) holds thanks to (B.9) and (B.10). Inequality (2.12) then follows from (2.13) and (B.8).

B.3 proof of Lemma 2.6

We can prove the lemma by arguing by contradiction as in the proof of Lemma 2.4. The only difference is that we have to take into account all the connected components of $\{y : \lim_{k \rightarrow \infty} u_k(y) \in (-1, 1)\}$ (see Figure I.1.4). Details are left to the reader.

C Proof of Lemma 3.1

We assume that f satisfies (1.1) and (1.6), (1.7). Writing $D^2f(e, e)$ in the basis,

$$\mathcal{B} = ((b_1, 0), \dots, (b_{d-1}, 0), (0, b_1), \dots, (0, b_{d-1}), (e, 0), (0, e)),$$

we have

$$D^2f(e, e) = \begin{pmatrix} A & B & M_1 \\ B^T & C & M_2 \\ M_1^T & M_2^T & L \end{pmatrix}, \quad (\text{C.1})$$

where A, B, C, M_1, M_2, L are real matrices, $A, B, C \in \mathcal{M}_{d-1, d-1}(\mathbf{R})$, $M_1, M_2 \in \mathcal{M}_{d-1, 2}(\mathbf{R})$, $L \in \mathcal{M}_{2, 2}(\mathbf{R})$ and A, C and L are symmetric.

Let us consider the action of rotations with axis e : for every $Q \in \text{SO}(d-1)$ and every $x, y \in e^\perp = \mathbf{R}^{d-1} \subset \mathbf{R}^d$, we have $f((e+Qx), (e+Qy)) = f((e+x), (e+y))$, which yields,

$$D^2f(e, e) = \begin{pmatrix} Q^T A Q & Q^T B Q & M_1 Q \\ Q^T B^T Q & Q^T C Q & M_2 Q \\ (M_1 Q)^T & (M_2 Q)^T & L \end{pmatrix} \quad \text{for every } Q \in \text{SO}(d-1).$$

Identifying this expression with (C.1), we see that $M_1 = M_2 = 0$ and that for $K = A, B, C$ we have

$$Q^T K Q = K \quad \text{for every } Q \in \text{SO}(d-1), \quad (\text{C.2})$$

Let us split B into its symmetric and skew-symmetric parts: $B = B_{\text{sy}} + B_{\text{sk}}$, so that (C.2) also holds for $K = B_{\text{sy}}$ and $K = B_{\text{sk}}$. Since A, B_{sy} and C are symmetric, hence diagonal in some orthonormal basis, this implies that these operators are diagonal in any orthonormal basis. Hence, there exists $a, b, c \in \mathbf{R}$ such that

$$A = a\mathbf{I}_{d-1}, \quad B_{\text{sy}} = b\mathbf{I}_{d-1}, \quad C = c\mathbf{I}_{d-1}.$$

At this point, in the basis \mathcal{B} , $D^2f(e, e)$ writes

$$D^2f(e, e) = \begin{pmatrix} a\mathbf{I}_{d-1} & b\mathbf{I}_{d-1} + B_{\text{sk}} & 0 \\ b\mathbf{I}_{d-1} - B_{\text{sk}} & c\mathbf{I}_{d-1} & 0 \\ 0 & 0 & L \end{pmatrix}.$$

Now, for a fixed $z \in S^{d-1} \cap e^\perp$, we observe that $d((e, e) + r(z, z), S^{d-1}) = O(r^2)$. Since f is minimal on S^{d-1} , we have $f((e, e) + r(z, z)) = O(r^4)$ and the second order derivative of $r \mapsto f((e, e) + r(z, z))$ vanishes at $r = 0$. From the last expression for $D^2f(e, e)$, this second order derivative is equal to $a|z|^2 + b|z|^2 + z^T B_{\text{sk}} z + b|z|^2 - z^T B_{\text{sk}} z + c|z|^2 = a + 2b + c$. Hence

$$b = -(a + c)/2.$$

Next, the space $T = \text{span}\{(e, 0), (0, e)\}^\perp$ is stable under the action of the symmetric operator $D^2f(e, e)$. Since this operator is non-negative, for every $v \in T$

we have $v^T D^2 f(e, e) v \geq 0$. Choosing $v = (z, \lambda z')$ with $z, z' \in e^\perp$, this inequality reads

$$c|z'|^2 \lambda^2 + 2(bz \cdot z' + z^T B_{sk} z') \lambda + a|z|^2 \geq 0 \quad \text{for every } \lambda \in \mathbf{R}. \quad (\text{C.3})$$

Choosing $z = z' \in S^{d-1} \cap e^\perp$, the term $z^T B_{sk} z'$ vanishes and we end up with the condition $c\lambda^2 + 2b\lambda + a \geq 0$ for every $\lambda \in \mathbf{R}$. This leads to $b^2 \leq ac$ which together with the identity $b = -(a+c)/2$ yields

$$a = c = -b.$$

Let us now establish that $B_{sk} = 0$. Since $B_{sk} \in \mathcal{M}_{d-1, d-1}(\mathbf{R})$ is skew-symmetric, we have $B_{sk} = 0$ if $d = 2$. Now, we assume $d \geq 3$ and we apply (C.3) with $\lambda = 1$, $z \in S^{d-1} \cap e^\perp$ and $z' = z + ry$ for some $y \in e^\perp \cap z^\perp$. We deduce $z^T B_{sk} y = O(r)$. Hence, $z^T B_{sk} y = 0$ for every $y \in e^\perp \cap z^\perp$ which yields the conclusion:

$$B_{sk} = 0.$$

We have established that $D^2 f(e, e)$ has the form stated in the lemma. The non-negativity of a and L follow from that of $D^2 f(e, e)$. Eventually, assuming $f \geq \kappa f_0$ for some $\kappa > 0$, we obtain $D^2 f(e, e) \geq \kappa D^2 f_0(e, e)$ which easily yields $a > 0$ and L positive definite.

D Oriented varifolds with L^2 -generalized mean curvature

We gather here well known facts about oriented integer varifolds. In particular, we extend the Willmore functional to the elements of \mathcal{A}_0 .

Let us first introduce a suitable generalization of Definition 1.1.b extending the notion of hypersurface.

Definition D.1 (oriented integer rectifiable $(d-1)$ -varifolds)

a) Given:

- i. a $(d-1)$ rectifiable set $\Sigma \subset \mathbf{R}^d$, that is:
 - $\mathcal{H}^{d-1}(\Sigma) < \infty$ and Σ is \mathcal{H}^{d-1} -measurable,
 - there exists a countable set of Lipschitz continuous functions $L_k : \mathbf{R}^{d-1} \rightarrow \mathbf{R}^d$, such that $\mathcal{H}^{d-1}(\Sigma \setminus \cup_k L_k(\mathbf{R}^{d-1})) = 0$;
- ii. a measurable unit normal \mathbf{v} , that is $\mathbf{v} : \Sigma \rightarrow S^{d-1}$ is \mathcal{H}^{d-1} -measurable and for almost every $x_0 \in \Sigma$ and every $\varphi \in C_c(\mathbf{R}^d)$, there holds:

$$\lambda^{d-1} \int_{\Sigma} \varphi(\lambda(\cdot - x_0)) d\mathcal{H}^{d-1} \xrightarrow{\lambda \uparrow \infty} \theta(x_0) \int_{\mathbf{v}^\perp(x_0)} \varphi d\mathcal{H}^{d-1}.$$

- iii. two positive integer valued \mathcal{H}^{d-1} -integrable functions $\theta^-, \theta^+ : \Sigma \rightarrow \mathbf{N} \setminus \{0\}$.

We define the oriented $(d-1)$ -varifold $\mathcal{V} = \mathcal{V}(\Sigma, \nu, \theta^+, \theta^-)$ as

$$\langle \mathcal{V}; \varphi \rangle := \int_{\Sigma} \{ \theta^+(x) \varphi(x, \nu(x)) + \theta^-(x) \varphi(x, -\nu(x)) \} d\mathcal{H}^{d-1}(x).$$

b) The set of all such oriented *integer rectifiable* $(d-1)$ -varifolds is denoted by \mathbf{IV}^o . In the sequel, we only write *integer varifold* for oriented integer rectifiable $(d-1)$ -varifold. We also introduce the set

$$\mathbf{IV}_0^o := \left\{ \mathcal{V} \in \mathbf{IV}^o : \Lambda \mathcal{V} = \nabla U \text{ for some } U \in \mathcal{D}'(\mathbf{R}^d) \right\}.$$

Equivalently, this set is formed by integer varifolds whose associated current has vanishing boundary (see Remark 1.2.b).

Remark D.1

i. The total mass of $\mathcal{V} = \mathcal{V}(\Sigma, \nu, \theta^+, \theta^-)$ is $\langle \nu; \mathbf{1} \rangle = \int_{\Sigma} (\theta^+ + \theta^-) d\mathcal{H}^{d-1}$ and $\Lambda \mathcal{V} = (\theta^+ - \theta^-) \nu \mathcal{H}^{d-1} \llcorner \Sigma$.

ii. The functions θ^+, θ^- account for multiplicity: the above formula means that the generalized surface pass at point $x \in \Sigma$, θ^+ times with orientation $\nu(x)$ and $\theta^-(x)$ times with opposite orientation.

iii. By continuity of the mapping $\Lambda : \mathcal{M}(\mathbf{R}^d \times S^{d-1}) \rightarrow \mathcal{D}'(\mathbf{R}^d)^d$, the space $\{ \mathcal{V} \in \mathcal{M}(\mathbf{R}^d \times S^{d-1}) : \Lambda \mathcal{V} \equiv 0 \}$ is closed in $\mathcal{M}(\mathbf{R}^d \times S^{d-1})$.

Another important tool in the context of area minimization is the *first variation* $\delta \mathcal{V}(X)$ of a $(d-1)$ -varifold. If $\mathcal{V} = \mathcal{V}(\Sigma, \nu)$ is the oriented $(d-1)$ varifold associated with a smooth hypersurface $\Sigma = \partial O$, this quantity describes the initial rate of change of the total mass of \mathcal{V} under the flow generated by $X \in \mathcal{D}(\mathbf{R}^d, \mathbf{R}^d)$. It is defined as

$$\delta \mathcal{V}(X) := \int_{\Sigma} \operatorname{div}_{\Sigma} X d\mathcal{H}^{d-1}, \quad (\text{D.1})$$

Recall that for every $x \in \Sigma$, if (e_1, \dots, e_{d-1}) denotes an orthonormal basis of $\nu(x)^{\perp}$, we have

$$\operatorname{div}_{\Sigma} X(x) = \sum_{i=1}^{d-1} e_i^T \nabla X(x) e_i.$$

The right hand side of (D.1) naturally extends as a linear continuous functional defined on the space of $(d-1)$ -varifolds: for every $\mathcal{V} \in \mathcal{M}(\mathbf{R}^d \times S^{d-1})$, we set

$$\delta \mathcal{V}(X) := \langle \mathcal{V}; (y, n) \mapsto \operatorname{div}_{n^{\perp}} X(y) \rangle, \quad \text{for every } X \in \mathcal{D}(\mathbf{R}^d, \mathbf{R}^d).$$

In general, $\delta \mathcal{V}$ is a distribution of $\mathcal{D}'(\mathbf{R}^d)^d$. However, if $\Sigma \subset \mathbf{R}^d$ is a smooth $(d-1)$ -submanifold with tangent hyperplane $\nu^{\perp}(x)$, then the first variation of $\mathcal{V} = \mathcal{V}(\Sigma, \nu)$ can be related to the vectorial mean curvature $H : \Sigma \rightarrow \mathbf{R}^d$ defined as $H = h\nu = (-\nabla \cdot \nu)\nu$. The vector field H only depends on the local geometry of Σ : it does not depend on the local orientation $\pm \nu$. With this notation, the tangential Green formula reads,

$$-\int_{\Sigma} H \cdot X d\mathcal{H}^{d-1} = \int_{\Sigma} \operatorname{div}_{\Sigma} X d\mathcal{H}^{d-1} \text{ for every } X \in \mathcal{D}(\mathbf{R}^d, \mathbf{R}^d). \quad (\text{D.2})$$

In particular, the first variation of \mathcal{V} is a measure given by

$$\delta\mathcal{V}(X) = - \int_{\Sigma} H \cdot X d\mathcal{H}^{d-1}. \quad (\text{D.3})$$

Now let $R, S > 0$ and let us consider an element $\mathcal{V}_0 \in \mathcal{A}_0(R, S)$ and an associated sequence of varifolds $\mathcal{V}_k = \mathcal{V}(\Sigma_k, \nu_k)$ complying to (1.5). The estimates of (1.5) and the Cauchy-Schwarz inequality easily imply

$$|\delta\mathcal{V}_k(X)| \leq K\|X\|_{\infty} \text{ for every } X \in \mathcal{D}(\mathbf{R}^d, \mathbf{R}^d),$$

for some constant $K \geq 0$. By the Riesz representation theorem, this implies $\delta\mathcal{V}_k \in \mathcal{M}(\mathbf{R}^d)^d$ for any $k \geq 1$ with the uniform bound

$$\|\delta\mathcal{V}_k\|(\mathbf{R}^d) \leq K. \quad (\text{D.4})$$

We can now state a compactness result due to Hutchinson [9]. It extends Allard's compactness theorem for (non-oriented) integer varifolds [1] to oriented integer varifolds.

Theorem D.1 ([9] **Theorem 3.1.**¹) *Let $K > 0$ and let E_K be the set of varifolds $\mathcal{V} \in \mathbf{IV}_0^o$ such that $\delta\mathcal{V}$ is a Radon measure of $\mathcal{M}(\mathbf{R}^d)^d$ and*

$$\|\mathcal{V}\|(\mathbf{R}^d \times S^{d-1}) + \|\delta\mathcal{V}\|(\mathbf{R}^d) \leq K.$$

Then E_K is compact in $\mathcal{M}(\mathbf{R}^d \times S^{d-1})$.

We can apply this result to the sequence (\mathcal{V}_k) and deduce,

$$\mathcal{V}_0 = \mathcal{V}(\Sigma_0, n_0, \theta_0^+, \theta_0^-) \in \mathbf{IV}_0^o. \quad (\text{D.5})$$

We now have to prove that \mathcal{V}_0 admits a L^2 -generalized mean curvature. Let us introduce this notion.

Definition D.2 (*L^2 -generalized mean curvature. Willmore energy of a varifold*)

a) Let $\mathcal{V} \in \mathcal{M}(\mathbf{R}^d \times S^{d-1})$ and let $\pi\mathcal{V} \in \mathcal{M}(\mathbf{R}^d)$ be the pushforward of \mathcal{V} by the mapping $(y, n) \in \mathbf{R}^d \times S^{d-1} \mapsto y \in \mathbf{R}^d$, that is $[\pi\mathcal{V}](E) = \mathcal{V}(E \times S^{d-1})$ for every Borel set $E \subset \mathbf{R}^d$.

We say that \mathcal{V} admits a L^2 -generalized curvature, if there exists $K \geq 0$ such that

$$\delta\mathcal{V}(X) \leq K\|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V})} \text{ for every } X \in C_c^1(\mathbf{R}^d)^d.$$

Since $\pi\mathcal{V}$ is a Radon measure, it is regular and the space $C_c^1(\mathbf{R}^d)^d$ is dense in $L^2(\mathbf{R}^d, \pi\mathcal{V})^d$. Consequently, if we assume the above bound, we can apply the (Hilbert space) Riesz representation theorem to deduce the existence of a $\pi\mathcal{V}$ -measurable mapping $H : \text{supp}(\pi\mathcal{V}) \rightarrow \mathbf{R}^d$, such that

$$\delta\mathcal{V}(X) = - \int_{\mathbf{R}^d} H \cdot X d[\pi\mathcal{V}] \text{ for every } X \in C_c^1(\mathbf{R}^d)^d.$$

¹ We only use the special case of oriented integer varifolds *without* boundary

This formula extends (D.3) and we will say that H is the (L^2) -generalized (vectorial) mean curvature of \mathcal{V} .

b) If $\mathcal{V} \in \mathcal{M}(\mathbf{R}^d \times \mathcal{S}^{d-1})$ admits a L^2 -generalized mean curvature H , we define its Willmore energy as

$$\mathcal{W}(\mathcal{V}) := \int_{\mathbf{R}^d} |H|^2 d[\pi\mathcal{V}].$$

If \mathcal{V} does not admit a L^2 -generalized mean curvature, we set $\mathcal{W}(\mathcal{V}) = +\infty$.

Remark D.2

a) Of course if $\mathcal{V} = \mathcal{V}(\Sigma, \nu)$, where Σ is a smooth compact surface oriented by ν , then it admits a generalized vectorial mean curvature which matches the usual definition $H = -(\operatorname{div}_\Sigma \nu)\nu$. Moreover, $[\pi\mathcal{V}] = \mathcal{H}^{d-1} \llcorner \Sigma$ so $\mathcal{W}(\mathcal{V}(\Sigma, \nu)) = \mathcal{W}(\Sigma)$.

b) For $\mathcal{V} = \mathcal{V}(\Sigma, \nu, \theta^+, \theta^-) \in \mathbf{IV}^o$, then $[\pi\mathcal{V}] = (\theta^+ + \theta^-)\mathcal{H}^{d-1} \llcorner \Sigma$. If \mathcal{V} admits a L^2 -generalized mean curvature $H : \Sigma \rightarrow \mathbf{R}^d$, then H is \mathcal{H}^{d-1} -measurable and we have,

$$\mathcal{W}(\mathcal{V}) = \int_{\Sigma} |H|^2 (\theta^+ + \theta^-) d\mathcal{H}^{d-1}.$$

c) If a rectifiable varifold $\mathcal{V} = \mathcal{V}(\Sigma, \nu, \theta^+, \theta^-)$ admits a generalized mean curvature H , then H is $[\pi\mathcal{V}]$ -almost everywhere collinear to ν (see K. Brakke [4]).

It is easily seen that the extension of the Willmore energy defined above is lower semi-continuous with respect to the convergence of Radon measures. Indeed, let $(\mathcal{V}_k) \subset \mathcal{M}(\mathbf{R}^d \times \mathcal{S}^{d-1})$ converging to \mathcal{V} and assume without loss of generality that $\liminf W(\mathcal{V}_k) < \infty$. Using the Cauchy-Schwarz inequality, we have, with obvious notation: for every $X \in C_c^1(\mathbf{R}^d)^d$,

$$\delta \mathcal{V}_k(X) = \langle \pi\mathcal{V}_k; H_k \cdot X \rangle \leq \sqrt{\mathcal{W}(\mathcal{V}_k)} \|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V}_k)} = \sqrt{\mathcal{W}(\mathcal{V}_k)} \sqrt{\langle \pi\mathcal{V}_k; |X|^2 \rangle}.$$

By the convergence $\mathcal{V}_k \rightarrow \mathcal{V}$ as $k \uparrow \infty$, the left hand side converges towards $\delta \mathcal{V}(X)$ and $\|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V}_k)} \rightarrow \|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V})}$. So,

$$\delta \mathcal{V}(X) \leq \sqrt{\liminf \mathcal{W}(\mathcal{V}_k)} \|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V})} \quad (\text{D.6})$$

Hence, \mathcal{V} admits a L^2 -generalized vectorial mean curvature $H \in L^2(\mathbf{R}^d, \pi\mathcal{V})^d$. Now, by density of $C_c^1(\mathbf{R}^d)^d$ in $L^2(\mathbf{R}^d, \pi\mathcal{V})^d$, we have

$$\sqrt{\mathcal{W}(\mathcal{V})} = \|H\|_{L^2(\mathbf{R}^d, \pi\mathcal{V})} = \sup \langle \mathcal{V}; X \cdot H \rangle = \sup \delta \mathcal{V}(X), \quad (\text{D.7})$$

where the suprema are taken over all $X \in C_c^1(\mathbf{R}^d)$ such that $\|X\|_{L^2(\mathbf{R}^d, \pi\mathcal{V})} \leq 1$. With (D.6), this yields

$$\mathcal{W}(\mathcal{V}) \leq \liminf_{k \uparrow \infty} \mathcal{W}(\mathcal{V}_k), \quad (\text{D.8})$$

as claimed.

In our context, if $\mathcal{V}_0 \in \mathcal{A}_0$, then it is the limit of a sequence $\mathcal{V}_k = \mathcal{V}(\Sigma_k, \nu_k)$ of smooth oriented integer varifolds with uniformly bounded Willmore energy.

We conclude that $\mathcal{V}_0 = \mathcal{V}(\Sigma_0, v_0, \theta_0^+, \theta_0^-) \in \mathbf{IV}_0^o$ admits a L^2 -generalized mean curvature H_0 , the formula of Remark D.2.b provides a more explicit expression for $\mathcal{W}(\mathcal{V}_0)$:

$$\mathcal{W}(\mathcal{V}_0) = \int_{\Sigma_0} |H_0|^2 (\theta_0^+ + \theta_0^-) d\mathcal{H}^{d-1}. \quad (\text{D.9})$$

Acknowledgements The author thanks the referee for his careful reading of the manuscript and his helpful suggestions concerning the presentation of this paper. The author is grateful to Olivier Pantz for suggesting this research subject and to Simon Masnou for helpful indications on Phase Field models and Varifolds. The author has been partially supported by the Agence National de la Recherche, through the project: ANR-12-BS01-0014-01 Geometrya.

Index of notation

\cdot^*	the superscript \star indicates an ancillary object used in several sections		
G_ε^*	18 (Sec.2.4)	good set in the construction of Σ_ε	
U_ε^*	18 (Sec.2.4)	bad set in the construction of Σ_ε	
$\beta_{\xi,1}^*(\xi, \eta)$	15 (Lem.2.4)	bound on the energy of “good” balls	
$\beta_{\xi,2}^*(\xi)$	16 (Lem.2.5)	bound on the energy of “good” balls	
$\beta_{\xi,3}^*(\xi, \eta)$	17 (Lem.2.6)	bound on the energy of “good” balls	
δ_ξ^*	14 (Cor.2.1)	positive constant, $d(\Sigma_\varepsilon^s, F_{(\varepsilon),\delta}) \geq \delta_\xi^*$ for $s \in (-1/2, 1/2)$	
Σ_ε^*	18 (Sec.2.4)	defined as $\Sigma_\varepsilon^0 \cap G_\varepsilon^*$, good part of Σ_ε	
χ^*	4 (Def.1.1)	(non-negative) cut-off function, $\chi^*(1) = 1$, $\text{supp } \chi^* \subset (1/2, 2)$	
ω_ξ^*	14 (Lem.2.3)	a common modulus of continuity for the functions $u_{(\varepsilon)}$	
$[\mathcal{P}]$	7 (Sec.1.6)	set of elements satisfying the property \mathcal{P}	
e^\perp	7 (Sec.1.6)	the hyperplane of \mathbf{R}^d orthogonal to $e \in S^{d-1}$	
y'	7 (Sec.1.6)	the vector $(y_1, \dots, y_{d-1}) \in \mathbf{R}^{d-1}$, $y \in \mathbf{R}^d$	
$\cdot_{(\varepsilon)}$	the subscript (ε) indicates a rescaled object, in order of appearance:		
$t_{(\varepsilon)}, \Omega_{(\varepsilon)}$	9 (Sec.2)	$\Sigma_{(\varepsilon)}^*$ 18 (Sec. 2.4)	$\mathcal{U}'_{(\varepsilon),\eta}, \mathcal{G}'_{(\varepsilon),\eta}$ 32 (Def. 4.2)
$\Omega'_{(\varepsilon)}, F'_{(\varepsilon)}$	12 (Sec.2.2)	$\Sigma_{(\varepsilon)}$ 17 (Sec. 2.4)	$\mathcal{X}_{(\varepsilon),\eta}$ 32 (Def. 4.2)
$O_{(\varepsilon),\delta}, F_{(\varepsilon),\delta}$	12 (Sec.2.2)	$\mathcal{U}_{(\varepsilon),\xi}, \mathcal{G}_{(\varepsilon),\xi}$ 22(Sec. 2.5)	$\hat{h}_{(\varepsilon)}$ 33 (Sec. 4.1)
$u_{(\varepsilon)}$	13 (Def.2.1)	$\mathcal{U}'_{(\varepsilon),\xi}, \mathcal{G}'_{(\varepsilon),\xi}$ 22(Sec. 2.5)	$\mathcal{U}''_{(\varepsilon),\eta}, \mathcal{G}''_{(\varepsilon),\eta}$ 34 (Sec. 4.1)
$\Sigma_{(\varepsilon)}^s, n_{(\varepsilon)}$	13 (Def.2.2)	$\mathcal{X}_{(\varepsilon),\xi}$ 23 (Sec. 2.5)	$\mathcal{X}'_{(\varepsilon),\eta}$ 34 (Sec. 4.1)
$U_{(\varepsilon)}^*, G_{(\varepsilon)}^*$	18 (Sec. 2.4)	$\mathcal{U}_{(\varepsilon),\eta}, \mathcal{G}_{(\varepsilon),\eta}$ 32 (Def. 4.2)	
\mathcal{A}_ε	2	set of admissible configurations	
$\mathcal{A}_\varepsilon(R)$	2	set of admissible configurations supported in B_R	
$\mathcal{A}_\varepsilon(R, S)$	2	configurations of $\mathcal{A}_\varepsilon(R)$ with total mass $2\varepsilon S$	
$\mathcal{A}_0(R, S)$	5 (Def.1.3)	limit set, subset of $\mathcal{M}(\mathbf{R}^d \times S^{d-1})$	
a	3	triplet (σ, τ, Ω) , a generic configuration of \mathcal{A}_ε	
a_ε	6 (Thm.1.1), 6 (Thm.1.2)	triplet $(\sigma_\varepsilon, \nabla t_\varepsilon, \Omega_\varepsilon) \in \mathcal{A}_\varepsilon(R, S)$	
$B_r(y)$	7 (Sec.1.6)	open ball with center y and radius r in \mathbf{R}^d , $B_r = B_r(0)$	
$C(\alpha_1, \dots, \alpha_k)$	7 (Sec.1.6)	a (non-negative) constant only depending on the dimension d and on the parameters $\alpha_1, \dots, \alpha_k$	

$C_\varepsilon(\alpha_1, \dots, \alpha_k)$	7 (Sec.1.6) a constant only depending on the parameters $\alpha_1, \dots, \alpha_k$ and on the data introduced in the hypotheses (d, R, S, ω, χ^* or E_0) but not on ε
$c_0(f)$	6 (Thm.1.2) positive number depending on the Hessian matrix of f
$c_{\xi, \eta, \alpha}(f)$	39 (Def.4.3) minimum value of the local optimization problem
$D'_\lambda(\bar{n})$	15 (Def.2.4) a $(d-1)$ -ball in \bar{n}^\perp with center 0 and radius λ , $D'_\lambda = D'_\lambda(e_d)$
$D_\lambda^\xi(\bar{n})$	15 (Def.2.4) cylinder with basis $D'_\lambda(\bar{n})$ and width $2(1-\xi)$, $D_\lambda^\xi = D_\lambda^\xi(e_d)$
d	dimension of the ambient space, $d \geq 2$
$d(A, B)$	the (euclidian) distance between the point (or set) A and the set B
$\mathcal{E}_{(\varepsilon), \mathcal{E}_{(\varepsilon), \lambda}}$	15 (Def.2.3) local energy
$\mathcal{E}^\#(a^\#)$	39 (Def.4.3) part of the energy of a local configuration $a^\#$
E_0	4 (Eq.1.4) bound on the energy $\mathcal{F}_0(a_\varepsilon)/\varepsilon^3$
(e_1, \dots, e_d)	standard basis of \mathbf{R}^d
$\mathcal{F}(a)$	3 (Sec.1.1) elastic energy of a configuration a
$\mathcal{F}_0(a)$	3 (Sec.1.1) energy of the configuration a with the stored energy function f_0
$\mathcal{F}_{(\varepsilon), \alpha}$	38 (Sec.4.2) local energy
$\mathcal{F}_\alpha^\#(a^\#)$	39 (Def.4.3) energy of a local configuration $a^\#$
f	3 (Eq.1.2) stored energy function
f_0	3 (Eq.1.2) archetype of a non-degenerate stored energy function
$\mathcal{H}^k(E)$	7 (Sec.1.6) k -dimensional Hausdorff measure of the set $E \subset \mathbf{R}^d$
h_ε	mean curvature of the hypersurface Σ_ε
\hat{h}_ε	32 (Def.4.2) approximate mean curvature of the hypersurface Σ_ε
$\hat{h}^\#(a^\#)$	39 (Def.4.3, Eq.5.7) approximate curvature of the local configuration $a^\#$
L	6 (Thm.1.2) 2×2 matrix extracted from $D^2 f(e_d, e_d)$
$\mathcal{M}(\mathbf{R}^d \times S^{d-1})$	4 (Def.1.1) space of Radon measures over $\mathbf{R}^d \times S^{d-1}$
M_ε	9 (Prop.2.1) the set $[t_\varepsilon < \varepsilon]$
\mathcal{N}	6 (Eq.1.6), 6 (Eq.1.7) a neighbourhood of the identity matrix in $\mathbf{R}^{d \times d}$
n_ε	13 (Def.2.2) $\nabla u_\varepsilon/ \nabla u_\varepsilon $ whenever it makes sense
O_ε	9 (Prop.2.1) smooth open set approximating $M_\varepsilon = [t_\varepsilon < 0]$
$\mathcal{Q}(\sigma, \tau)$	2 quantity of material
S^{d-1}	7 (Sec.1.6) $(d-1)$ -dimensional unit sphere of \mathbf{R}^d
\mathcal{S}^{d-1}	3 the set of zeros of the stored energy functions — a $(d-1)$ -dimensional unit sphere embedded in $\mathbf{R}^d \times \mathbf{R}^d$
R	2, 5 (Def.1.3), 6 (Th.1.1), 6 (Th.1.2) confining radius in the definition of $\mathcal{A}_\varepsilon(R)$ and $\mathcal{A}_\varepsilon(R, S)$
S	2, 5 (Def.1.3), 6 (Th.1.1), 6 (Th.1.2) “area” of the configurations of $\mathcal{A}_\varepsilon(R, S)$ and of the elements of $\mathcal{A}_0(R, S)$
T_ε	6 (Thm.1.1), 6 (Thm.1.2) approximate characteristic function of $[t_\varepsilon < 0]$, defined as $T_\varepsilon := (\varepsilon - t_\varepsilon)/2\varepsilon$
u_ε	13 (Def.2.1) harmonic extension of t_ε
\mathcal{V}	4 (Def.1.1) a generic oriented $(d-1)$ -varifold
$\mathcal{V}(\Sigma, \nu)$	4 (Def.1.1) varifold associated with the oriented hypersurface (Σ, ν)
$\mathcal{V}_\varepsilon^*(a)$	5 (Def.1.2) varifold associated with the configuration a
\mathcal{V}_0	6 (Thm.1.1), 6 (Thm.1.2) limit varifold
$\mathcal{W}(\Sigma)$	2 Willmore energy of the hypersurface Σ
$W_{loc}^{1,2}(\mathbf{R}^d)$	Sobolev space of functions with locally square integrable derivatives, endowed with its standard topology

$\zeta, \zeta_{//}, \zeta_{\perp}$	31 (Def.4.1)	test functions for the definition of \hat{h}_{ε}
κ	3 (Eq.1.2)	positive constant introduced in the hypothesis $f \geq \kappa f_0$
$\Lambda \mathcal{V}$	4 (Def.1.1)	distribution associated with the oriented $(d-1)$ -varifold \mathcal{V}
ν_{ε}	9 (Prop.2.1)	outward unit normal to $\Sigma_{\varepsilon} = \partial O_{\varepsilon}$
π_e	7 (Sec.1.6)	the projection onto the hyperplane orthogonal to $e \in S^{d-1}$
Σ_{ε}	9 (Prop.2.1), 17 (Sec.2.4)	smooth hypersurface, the boundary of O_{ε}
Σ_{ε}^s	13 (Def.2.2)	level sets of u_{ε}
$\chi_{\varepsilon, \xi}$	23 (Sec.2.5)	cut-off function in the proof of Prop. 2.1.c
$\chi_{\varepsilon, \eta}$	32 (Def.4.2)	cut-off function for the definition of \hat{h}_{ε}
$\chi'_{\varepsilon, \eta}$	34 (Sec.4.1)	cut-off function in the proof of Prop. 4.1
ω	3 (Hyp.1)	a common modulus of continuity for the functions $t_{(\varepsilon)}$

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