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Colette Johnen. Memory Efficient Self-Stabilizing k-Independant Dominating Set Construction. 2013. hal-00843995v1

# HAL Id: hal-00843995 https://hal.science/hal-00843995v1

Submitted on 12 Jul 2013 (v1), last revised 1 Oct 2013 (v2)

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## Memory efficient Self-Stabilizing k-Independent Dominating Set Construction\* Labri Technical Report RR-1473-13

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**Abstract.** We propose a memory efficient self-stabilizing protocol building k-independant dominating sets. A k-independant dominating set is a k-independant set and a k-dominating set. A set of nodes, I, is k-independent if the distance between any pair of nodes in I is at least k + 1. A set of nodes, D, is a k-dominating if every node is within distance k of a node of D.

Our algorithm, named SID, is silent; it converges under the unfair distributed scheduler (the weakest scheduling assumption). The built k-independent dominating sets contain at most  $\lfloor 2n/k + 2 \rfloor$  nodes, n being the network size.

The protocol SID is memory efficient : it requires only 2log((k+1)n+1) bits per node.

The correctness and the terminaison of the protocol  $\mathcal{SID}$  is proven.

keywords distributed computing, fault tolerance, self-stabilization, k-dominating set, k-independant set, k-independant dominating set

## 1 Introduction

The clustering of networks consists of partitioning network nodes into non-overlapping groups called clusters. Each cluster has a single head, called leader, that acts as local coordinator of the cluster, and eventually a set of standard nodes. In 1-hop clusters, the standard nodes are neighbor (at distance 1) of their leader. Clustering is found very attractive in infrastructure-less networks, like ad-hoc networks, since it limits the responsibility of network management only to leaders, and it allows the use of hierarchical routing. This is why numerous self-stabilizing 1-hop clustering protocols were proposed in the literature [9,10,8,11,13,14,15,16,19,20].

Silent self-stabilizing protocols building k-hops clustering set are proposed for k > 1. In k-hop clusters, the distance between a standard node and its leader is at most k [1,2,3,7]. The sets of cluster heads built by these

<sup>\*</sup> This work was partially supported by the ANR project Displexity.

protocols are not k-independant. The protocol of [1] is designed for k = 2. Routing tables are maintained by the cluster heads to store routing information to nodes both within and outside the cluster. The goal of the protocol in [2] is to build bounded size clusters (each cluster has at most *Cluster\_Max* nodes). bits per node. The protocol of [3] is designed for weighted edges networks; it requires at least O(k.log(n)) bits per node. The protocol of [7] requires at least 2(k + 1)log(n)

In [17,18], Larsson and Tsigas propose self-stabilizing (l,k)-clustering protocols under various assupptions. These protocols ensure, if possible, that each node has l cluster-heads at distance at most k.

**Related Works.** In [4], a silent self-stabilizing protocol extracting a minimal k-dominating set from any k-dominating set is proposed. A minimal k-dominating set has no proper subset which also a k-dominating set. The protocol requires at least O(k.log(n)) bits per node.

The paper [6] presents a silent self-stabilizing protocol building a small k-dominating set : the obtained dominating set contains at most  $\lceil n/k + 1 \rceil$ . The protocol of [6] requires O(log(n) + k.log(n/k)) bits per node. The protocol of [5] builds competitive k-dominating sets : the obtained dominating set contains at most  $1+\lfloor n-1/k+1 \rfloor$  nodes. The protocol of [5] requires O(log(n)) bits per node. These both protocols use the hierachical collateral composition of several silent self-stabilizing protocols whose a leader election protocol and a spanning tree construction rooted to the elected leader. So they requires more memory space than our protocol.

In [12], A fast silent self-stabilizing protocol building a k-independent dominating set is proposed the protocol requires (k + 1)log(n + 1) bits per node.

**Contribution.** In this paper, we consider the problem of computing a k-independent dominating set in a self-stabilizing manner in case where k > 1. A nodes set is k-independent dominating set (also called maximal k-independent set) if and only if this set is a k-independent set and a k-dominating set. A set of nodes, I is k-independent if the distance between any pair of I's nodes is at least k + 1. A set of nodes D is k-dominating if every node is within distance k of a node of D.

The presented protocol, named SID, is simple : no used of the hierachical collateral composition, no need of leader election process, neither the building of spanning tree. The protocol SID converges under the unfair distributed scheduler (the weakest scheduling assumption). The algorithm SID is silent. The protocol SID is memory efficient : it requires only 2log((k+1)n+1) bits per node.

In section 2, we establish that any k-independent sets contain at most  $\lfloor 2n/k + 2 \rfloor$  nodes, n being the network size. So the protocol of [12] and the protocol SID have the same upper bound on the size of built k independent dominating sets :  $\lfloor 2n/k + 2 \rfloor$  nodes.

**Paper outline.** The rest of the paper is organised as follows. In section 2, communication and computation models are defined. The protocol SID is presented in section 3. In the section 4, the correctness of the SID protocol is proven. The terminaison of the SID protocol is established in the section 5.

## 2 Model and Concepts

A distributed system S is an undirected graph G = (V, E) where vertex set V is the set of nodes and edge set E is the set of communication links. A link  $(u, v) \in E$  if and only if u and v can directly communicate (links are bidirectional); so, u and v are neighbors. We note by  $N_v$  the set of v's neighbors:  $N_v = \{u \in V \mid (u, v) \in E\}$ . The distance between the nodes u and v is denoted dist(u, v). k-neigborhood $(v) = \{u \in V \mid dist(u, v) \in [1, k]\}$ .

Furthermore, at every node v in the network is assigned an identifier, denoted  $id_v$ . Two distinct nodes have different identifier. It is possible to order the identifiant values. The symbol  $\perp$  denotes a value smaller than any identifiant value in the network.

Each node v maintains a set of shared variables such that v can read its own variables and those of its neighbors, but it can modify only its variables. The *state* of a node is defined by the values of its local variables. The union of states of all nodes determines the *configuration* of the system. Let **var** be a shared variable,  $var(v)_c$  is the value of **var** for the node u in the configuration c. The program of each node is a set of rules. Each rule has the form:  $Rule_i :< Guard_i > \longrightarrow < Action_i >$ . The guard of a v's rule is a boolean expression involving the state of the node v, and those of its neighbors. The action of a v's rule updates v's state. A rule can be executed only if it is enabled, i.e., its guard evaluates to true. A node is said to be enabled if at least one of its rules is enabled. In a *terminal configuration*, no node is enabled.

During a computation step  $c_i \to c_{i+1}$ , one or several enabled nodes perform an enabled action and the system reaches the configuration  $c_{i+1}$  from  $c_i$ . A computation e is a sequence of configurations  $e = c_0, c_1, ..., c_i, ...,$ where  $c_{i+1}$  is reached from  $c_i$  by one computation step:  $\forall i \ge 0, c_i \to c_{i+1}$ . We say that a computation e is maximal if it is infinite, or if it reaches a terminal configuration. We note by C the set of all possible configurations, and by  $\mathcal{E}$  the set of all maximal computations. The set of maximal computations starting from a particular configuration  $c \in C$  is denoted  $\mathcal{E}_c$ .  $\mathcal{E}_A$  denotes the set of all maximal computations where the initial configuration belongs to the set of configurations  $A \subset C$ .

**Definition 1 (Attractor).** Let  $B_1$  and  $B_2$  be subsets of C.  $B_2$  is an attractor from  $B_1$ , if and only if the following conditions hold:

- Convergence:  $\forall c \in B_1$ , If  $(\mathcal{E}_c = \emptyset)$  then  $c \in B_2$  $\forall e \in \mathcal{E}_{B_1}(e = c_1, c_2, ...), \exists i \ge 1, c_i \in B_2;$
- Closure:  $\forall e \in \mathcal{E}_{B_2}(e = c_1, ...), \forall i \ge 1 : c_i \in B_2.$

**Definition 2 (Self-stabilization).** A distributed system S is self-stabilizing if and only if there exists a non-empty set  $\mathcal{L} \subseteq \mathcal{C}$ , called set of legitimate configurations, such that the following conditions hold:

- $\mathcal{L}$  is an attractor from  $\mathcal{C}$ ;
- Configurations of  $\mathcal{L}$  match the specification problem.

A self-stabilizing protocol is *silent* if all maximal computations are finite.

**Stabilization time.** We use the *round* notion to measure the time complexity. The first round of a computation  $e = c_1, ..., c_j, ...$  is the minimal prefix  $e_1 = c_1, ..., c_j$ , such that every enabled node in  $c_1$  either executes a rule or it is neutralized during a computation step of  $e_1$ . A node v is *neutralized* during a computation step  $cs \ c_i \rightarrow c_{i+1}$ , if v is enabled in  $c_i$  and disabled in  $c_{i+1}$ , but it did not execute any action during cs.

Let  $e_2$  be the suffix of e such that  $e = e_1e_2$ . The second round of e is the first round of  $e_2$ , and so on.

The stabilization time is the number of disjoint rounds of a computation reaching a legitimate configuration from any initial one.

**Lemma 1.** The size of a k-independent set is at most  $max(\lfloor 2n/k + 2 \rfloor, 1)$ .

*Proof.* Let I be a k-independent set such that |I| > 1. Let v be a node of I. We denote by closer(v) the set of nodes closer to v than any other node of I.

Notice that  $\bigcup_{v \in I} \operatorname{closer}(v) \subset V$  and  $\operatorname{closer}(v) \cap \operatorname{closer}(u) = \emptyset, \forall (u, v) \in I^2$ . Let u be the closest node of v that belongs to I. The first  $\lfloor k + 2/2 \rfloor$  nodes in the path from v to u are closer to v than any other nodes of I. So,  $\operatorname{closer}(v)$  contains at least  $\lfloor k + 2/2 \rfloor$  nodes. We conclude that  $|I| \leq \lfloor 2n/k + 2 \rfloor$ .

The protocol SID build k-independent sets. So, the obtained k-independent dominating set contains at most |2n/k+2| nodes.

## 3 The protocol $\mathcal{SID}$

In the following subsection, we gives the notation used by the protocol SID.

#### 3.1 *k*-augmentedID type

**Definition 3.** *k*-augmentedID type An *k*-augmentedID value, *a*, *is an* uplet (d, x) such that *d* is integer with  $0 \le d \le k$ , and *x* is a node identifiant. Let a = (d, x) be *k*-augmentedID value. We note a.dist = *d* and a.id = *x* 

Let v be a node of V,  $id_v^+$  it the k-augmentedID value associated to v :  $(0, id_v)$ .

Definition 4. Two total order relations on k-augmentedID  $\cup \bot$ 

dom is defined as follow: dom(a, b) = a if
b=⊥, a.id < b.id or a.id = b.id ∧ a.dist < b.dist</li>
min is defined as follow: min(a, b) = a if
b=⊥, a.dist < b.dist or a.dist = b.dist ∧ a.id < b.id</li>

The k-augmented value a1 dominates the k-augmented value a2 iff dom(a1, a2) = a1. The k-augmented value a1 is larger than the k-augmented value a2 iff min(a1, a2) = a2.

**Definition 5.** The operation +1 on k-augmentedID  $\cup \perp$  is defined as follow : a+1 = a if  $a = \perp$  or if a.dist = k otherwise a+1 = (a.dist+1, a.id)

#### 3.2 Code of the protocol $\mathcal{SID}$

A node v is said to be a head if firstHead $(v) = id_v^+$ ; otherwise it is an ordinary node. The heads set built by the protocol SID (defined in protocol 1) is a k-independent dominating set.

## **Protocol 1** : the Protocol SID on the node v

#### Shared variables

- firstHead $(v) \in k$ -augmentedID
- $secondHead(v) \in k$ -augmentedID  $\cup \bot$

#### Internal variables

- k-augmentedIdSet $(v) = \{a + 1 \in k \text{-augmentedID}\}$
- $a = \texttt{firstHead}(u) \lor a = \texttt{secondHead}(u) \ with \ u \in N_v \land a.dist < k \land a.id \neq id_v \}$
- SecondAugmentedIdSet $(v) = \{a \in \texttt{augmentedIdSet} \mid a.id \neq \texttt{firstHead}(v).id\}$

#### Macro

- headUpdate(v) : firstHead $(v) := id_v^+$ ; secondHead $(v) := \bot$ ;
- ordinaryUpdate(v) :

firstHead(v) := min(augmentedIdSet(v));secondHead(v) := min(SecondAugmentedIdSet(v) \cup {⊥});

## Predicates

- $\text{Head}(v) \equiv \text{firstHead}(v) = id_v^+$
- toResign(v)  $\equiv id_v^+ \neq dom(\texttt{augmentedIdSet}(v) \cup \{id_v^+\})$
- $\bullet \; \texttt{toElect}(v) \equiv \texttt{augmentedIdSet}(v) = \emptyset$
- $headToUpdate(v) \equiv secondHead(v) \neq \perp$
- ordinaryToUpdate(v)  $\equiv$

```
\texttt{firstHead}(v) \neq min(\texttt{augmentedIdSet}(v)) \lor \\ \texttt{secondHead}(v) \neq min(\texttt{SecondAugmentedIdSet}(v) \cup \{\bot\})
```

## Rules

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\begin{split} \mathbf{RE}(v) &: \neg \texttt{Head}(v) v \wedge \texttt{toElect}(v) \longrightarrow \texttt{headUpdate}(v); \\ \mathbf{RU}(v) &: \neg \texttt{Head}(v) \wedge \neg \texttt{toElect}(v) \wedge \texttt{ordinaryToUpdate}(v) \longrightarrow \texttt{ordinaryUpdate}(v); \\ \mathbf{RR}(v) &: \texttt{Head}(v) \wedge \texttt{toResign}(v) \longrightarrow \texttt{ordinaryUpdate}(v); \\ \mathbf{RC}(v) &: \texttt{Head}(v) \wedge \neg \texttt{toResign}(v) \wedge \texttt{headToUpdate}(v) \longrightarrow \texttt{headUpdate}(v); \end{split}
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The variable firstHead(v) contains the identifiant of the closest head to v (with its distance to v).

The variable secondHead(v) contains the identifiant of the second closest head to v (with its distance to v) inside its k-neighborhood. If a node v does not have two heads in its k-neighborhood then secondHead(v) is set to  $\bot$ . The execution of the rules **RU** or the rules **RC** updates the two variables firstHead(v), and secondHead(v) without changing the status of v (i.e. v stays ordinary or head).

The variable augmentedIdSet(v) contains some heads in the k-neighborhood of v. (i.e.  $(d, id_u) \in$ augmentedIdSet(v) indicates that u is a head at distance d of v). If the k's neighborhood of v does not contain any head then augmentedIdSet(v) is empty. Notice that in this case, toElect(v) is verified. So, if v is an ordinary node then v will become a head (the rule **RE** is enabled). Therefore, the heads set is a k-dominating set, in a terminal configuration.

If toResign(v) is verified then v has in its k-neighborhood a head u having a smaller identifiant than v's identifiant (i.e.  $id_v > id_u$ ). In this case, if v is a head, it is enabled. So, the set of heads is a k-independent set, in any terminal configuration.

The proof of the protocol  $\mathcal{SID}$  has two parts.

- In the section 4, we prove that a terminal configuration of SID protocol is legitimate : the set of heads is a k-independent dominating set.
- In the section 5, we prove that all maximal computations under any unfair distributed scheduler are finite by *reductio ad absurdam* arguments.

## 4 Correctness of the protocol $\mathcal{SID}$

In this section, we prove that all terminal configuration of SID protocol are legitimate : the set of heads is a k-independent dominating set.

**Definition 6.** The property OrdinaryPr(i) defined for all  $i \in [1, k]$  has two parts :

- for all ordinary node v, firstHead $(v) = (i, id_u)$  if and only if u is the closest head to v and i is the distance between u and v.

- for all node v, secondHead $(v) = (i, id_u)$  if and only if u is the second closest head to v and i is the distance between u and v.

**Observation 1** In a terminal configuration,

- An ordinary node v does not verify OrdinaryToUpdate(v);
- A head v does not verify HeadToUpdate(v);
- if v is an ordinary node then firstHead(v).dist > 0;
- if  $secondHead(v) \neq \perp$  then secondHead(v).dist > 0;
- if secondHead(v)  $\neq \perp$  then secondHead(v).dist  $\geq$  firstHead(v).dist.

**Lemma 2.** In a terminal configuration of protocol SID, the property OrdinaryPr(1) is verified.

Proof.

Let v be an ordinary node, in a terminal configuration of protocol SID.  $(1, x) \in \texttt{augmentedIdSet}(v)$  if and only if v has a neighbor u such that firstHead(u) = (0, x) in c. According to observation 1, u is a head; so  $x = id_u$ .

Notice that  $\forall a \in \texttt{augmentedIdSet}(v)$ , we have a.dist > 0, in c.

As firstHead(v) = min(augmentedIdSet(v)), if v has a head at distance 1 then firstHead $(v) = (1, id_u)$  with u being the head in v's neighborhood having the smallest identifiant. otherwise firstHead $(v).dist \neq 1$ .

According to the predicate OrdinaryToUpdate(v), if v has several heads at distance 1 then  $secondHead(v) = (1, id_u)$  with u being the head in v's neighborhood having the second smallest identifiant. Otherwise, secondHead(v).dist is larger than 1.

**Lemma 3.** Let i be a positive integer smaller than k. In a terminal configuration of protocol SID, if the properties OrdinaryPr(j) are verified for all  $j \in [1, i]$  then the property OrdinaryPr(i + 1) is verified.

*Proof.* Let us assume that the properties  $\operatorname{OrdinaryPr}(j)$  are verified for all  $j \in [1, i]$  in any terminal configuration of protocol  $\mathcal{SID}$ . In a terminal configuration  $c, (j, x) \in \operatorname{augmentedIdSet}(v)$  iff v has a neighbor u such that  $\operatorname{firstHead}(u) = (j - 1, x)$ , or  $\operatorname{secondHead}(u) = (j - 1, x)$ . If j = 1 then u is a head in c, according to Observation 1. If  $1 < j \leq i + 1$  then x is the identifiant of a head in c at distance j - 1 of u, according to the properties  $\operatorname{OrdinaryPr}(j-1)$ . So x is the identifiant of a head at distance at most j of v, in c.

Let v' be the closest head to v and d' the distance from v' to v in the terminal configuration c. Assume that  $0 < d' \le i + 1$ . in c, we have the two following properties.

- if  $(l, id) \in \texttt{augmentedIdSet}(v)$  then  $l \ge d'$ ; and
- if  $(d', id) \in \texttt{augmentedIdSet}(v)$  then  $id \geq id_{v'}$ . In c, v has a neighbor u at distance d' 1 to v'. In c, the node v' is the closest head of u; so  $\texttt{firstHead}(u) = (d' 1, id_{v'})$ .

We conclude that  $firstHead(v) = (d', id_{v'})$ , in c.

Assume that the network has several heads. Let v" be the second closest head to v and d" the distance from v" to v, in a terminal configuration c. v has a neighbor u at distance d" -1 to v" in c. (we have d" > 0). v" is the first or second closest head to u, in c. Assume that d"  $\leq i + 1$ . According to the properties  $\operatorname{OrdinaryPr}(i)$ ,  $\operatorname{firstHead}(u) = (d$ "  $-1, id_{v}$ ")  $\lor$  $\operatorname{secondHead}(u) = (d$ "  $-1, id_{v}$ "), in c. So (d",  $id_{v}$ ")  $\in$  augmentedIdSet(v), in c. In c, we have the two following properties.

- if  $(l, id) \in \texttt{augmentedIdSet}(v)$  then  $l \ge d$ " or (l, id) = firstHead(v). - if  $(d^{"}, id) \in \texttt{augmentedIdSet}(v)$  then  $id \ge id_{v}$ " or id = firstHead(v).id.

We conclude that  $secondHead(v) = (d^{"}, id_{v^{"}}).$ 

The following corollary is a direct result of lemmas 2 and 3. It establishes that the set of heads is a k-dominating set.

**Corollary 1.** Let v be a ordinary node, in a terminal configuration of protocol SID, named c. firstHead(v).id is the closest head to v; their distance is firstHead(v).dist  $\leq k$ . If secondHead(v) = $\perp$  then v has a single head in its k-neigborhood otherwise secondHead(v).id is the second closest head to v; their distance is secondHead(v).dist.

The following theorem establishes that the set of heads is a k-independant set.

**Theorem 1.** Let v be a head, in a terminal configuration of protocol SID, named c. v has not head in its k-neighborhood.

*Proof.* We will prove that if a head has another head in its k-neighborhood then the configuration c is not terminal.

Let *wrongHeadSet* the set of heads having one or several heads in their *k*-neigborhood. Assume that *wrongHeadSet* is not empty. We denoted by

v1 the node of wrongHeadSet having the largest identifiant. We denoted v2, the closest head to v1 and d the distance between v1 and v2. We have  $0 < d \le k$ . The node v1 has a neighbor u at distance d-1 of v2. The node v2 is the first or the second closest head to u. According to corollary 1, we have  $(d, id_{v2}) \in \texttt{augmentedIdSet}(v1)$ . v1 is enabled because v1 satisfied the predicate toResign(v1).

## 5 Termination of the protocol $\mathcal{SID}$

In this section, we prove that all maximal computations of protocol SID under any unfair distributed scheduler are finite by *reductio ad absurdam* arguments.

Let e be a maximal computation starting from a configuration, named c0. In a configuration c reached by e, for all node v, firstHead $(v)_c.id$  is either the identifiant of an node or this value appears in the initial configuration (i.e. there is a node u, such that firstHead $(v)_c.id =$  firstHead $(u)_{c0}.id \lor$  firstHead $(v)_c.id =$  secondHead $(u)_{c0}.id$ ). So, the value taken by a variable firstHead in e belongs to a bounded set. Similary we prove also that the value taken by a variable secondHead in e belongs to a bounded set.

#### 5.1 RR and RE rules

Along any computation, a node performs at most one time the rule **RC**.

Assume that a or several nodes perform infinitely often the action **RE** or the action **RR**. Between two consecutive actions **RE** by a node u, this node has performed on time the action **RR**. So a node u that infinitely often perform the action **RE** or the action **RR** changes its status infinitely often. We name  $u^+$  the node the smallest identifiant among nodes that changes their status infinitely often. e has a suffix e1 where only nodes having a identifiant larger than  $id_{u^+}$  changes their status (i.e. to perform the action **RE** or the action **RR**).

As the set of value taken by firstHead $(u^+)$  is bounded; along e1, infinitely often after the action  $\mathbf{RR}(u^+)$ , firstHead $(u^+)$  has the same value, denoted (l + 1, id). Notice that  $id < id_{u^+}$  and 0 < l < k. So  $u^+$ has a neighbor  $u_l$  such that, infinitely often before the action  $\mathbf{RR}(u^+)$ ,  $u_l$  verfies firstHead $(u_l) = (l, id)$  or secondHead $(u_l) = (l, id)$ . At time, where  $u^+$  becomes head, we have **augmentedIdSet** $(u^+) = \emptyset$ . So, the values of  $u_l$  variables are infinitely often larger than (l, id): So  $u_l$  gives infinitely often to one of its variables the value (l, id), but also gives a larger value to the same variable.

Assume that l > 0. At time where  $u_l$  gives the value (l, id) to one of its variable :  $u_l$  has a neigbor  $u_{l-1}$ , having the value (l-1, id). At time where  $u_l$  gives a larger value than (l, id) to the same variable :  $u_{l-1}$  has a larger value than (l-1, id). We conclude that there is a series of l + 1 nodes :  $u_l, u_{l-1}, ... u_0$  such that  $u_i$  has infinitely often has the value (i, id) and infinitely often does not have this value along e1.

Along e1,  $u_0$  performs infinitely often the action **RR** and the action **RE**. We have  $id = id_{u_0} < id_{u^+}$ : there is a contradiction.

So e has a suffix, named e2, in which the only rule performed is **RU**.

#### 5.2 RU rule

Assume that a node or several nodes changing infinitely often their value firstHead or their value secondHead along e2. We named  $min^+$  the smallest value infinitely often allocates to the variable firstHead or to the variable secondHead of one of these nodes. Let e3 be the suffix of e2 in which no variable firstHead and no variable secondHead gets a value smaller than  $min^+$ . Along e3, infinitely often, a node, named  $u^+$ , performs **RU** action to set the value  $min^+$  to its variable firstHead or its variable secondHead; and infinitely often,  $u^+$  performs **RU** action to set the value  $min^+$ .

Let  $c \to c'$  be a computation step of e3 where  $u^+$  performs **RU** action to set a value larger than  $min^+$  to its variable firstHead or to its variable secondHead. In c,  $min^+$  is smaller than  $min(\texttt{augmentedIdSet}(u^+))$  or  $min^+$  is smaller than  $min(\texttt{SecondAugmentedIdSet}(u^+))$ . This property stays verified along  $e3 : u^+$  never sets the value  $min^+$  to its variable firstHead (resp. to its variable secondHead). There is a contradiction.

We have established that  $e^2$  has a suffix  $e^4$  where no rule is executed. A terminal configuration is reached.

## 6 Conclusion

A simple and silent self-stabilizing protocols building k-independent dominating sets is presented. The obtained k-independent dominating set contains at most  $\lfloor 2n/k+2 \rfloor$  nodes. The protocol converges under the unfair distributed scheduler (the weakest scheduling assumption). The protocol is memory efficient : it requires only 2log(n+1)(k+1)) bits per node.

The computation of the convergence time of the protocol  $\mathcal{SID}$  is opened question.

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