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# The complexity of deciding whether a graph admits an orientation with fixed weak diameter 

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#### Abstract

An orientation of an undirected graph $G$ has weak diameter $k$ if, for every pair $\{u, v\}$ of vertices of $G$, there is a directed path with length at most $k$ joining $u$ and $v$ in either direction. We show that deciding whether a graph admits an orientation with weak diameter $k$ is NP-complete whenever $k \geq 2$.


Keywords: oriented graph, weak diameter, complexity

## 1. Introduction

Let $G$ be a simple undirected graph with vertex set $V(G)$ and edge set $E(G)$. By orienting every edge $u v$ of $G$, either from $u$ to $v$ or from $v$ to $u$, one obtains an orientation $\vec{G}$ of $G$. This oriented graph $\vec{G}$ has the same vertex set as $G$, i.e. $V(\vec{G})=V(G)$, and, for every edge $u v \in E(G)$, we have either $\overrightarrow{u v} \in E(\vec{G})$ or $\overrightarrow{v u} \in E(\vec{G})$ depending on the orientation assigned to $u v$.

The distance $\operatorname{dist}(G, u, v)$ from $u$ to $v$ in an undirected graph $G$ is the minimal length of a path joining $u$ and $v$. We refer to the maximum distance between two vertices of $G$ as its diameter, and denote it $\operatorname{diam}(G)$. These definitions can be naturally adapted to the context of oriented graphs. A $k$-dipath $\overrightarrow{v_{1} v_{2} \ldots v_{k+1}}$ of $\vec{G}$ is a sequence of $k+1$ distinct vertices such that $\overrightarrow{v_{i} v_{i+1}} \in E(\vec{G})$ for every $i \in\{1,2, \ldots, k\}$. The directed distance $\operatorname{dist}(\vec{G}, u, v)$ from $u$ to $v$ in $\vec{G}$ is the minimal length of a dipath starting from $u$ and ending at $v$. Note that, contrary to the undirected case, we may have $\operatorname{dist}(\vec{G}, u, v) \neq \operatorname{dist}(\vec{G}, v, u)$. Therefore, two definitions of the oriented diameter can be adopted.

[^0]Let $\operatorname{dist}_{w}(\vec{G}, u, v)$ and $\operatorname{dist}_{s}(\vec{G}, u, v)$ be $\min \{\operatorname{dist}(\vec{G}, u, v), \operatorname{dist}(\vec{G}, v, u)\}$ and $\max \{\operatorname{dist}(\vec{G}, u, v), \operatorname{dist}(\vec{G}, v, u)\}$, respectively. The weak diameter of $\vec{G}$, denoted $\operatorname{diam}_{w}(\vec{G})$, is the maximum value of $\operatorname{dist}_{w}(\vec{G}, u, v)$ taken over all pairs $\{u, v\}$ of vertices of $\vec{G}$. The strong diameter of $\vec{G}$, denoted $\operatorname{diam}_{s}(\vec{G})$, is the maximum value of $\operatorname{dist}_{s}(\vec{G}, u, v)$ taken over all pairs $\{u, v\}$ of vertices of $\vec{G}$.

An orientation of $G$ is $k$-weak (resp. $k$-strong) if it has weak (resp. strong) diameter at most $k$. We only deal with $k$-weak orientations in this paper, our motivations being mainly supported by the case $k=2$ which is related to some graph colouring notions as explained below. A proper $k$-colouring of $G$ is a partition of $V(G)$ into $k$ parts such that each colour class is a stable. The least number of colours used by a proper colouring of $G$ is referred to as the chromatic number of $G$, denoted $\chi(G)$. Clearly, we have $\chi(G)=|V(G)|$ if and only if $G$ is a complete graph.

Now consider similar notions but for oriented graphs. A proper oriented $k$ colouring of $\vec{G}$ is a partition of $V(\vec{G})$ into $k$ parts such that each colour class is a stable, and all arcs between two colour classes have the same direction. As usually, the least number of colours used by a proper oriented colouring of $\vec{G}$ is defined as the oriented chromatic number of $\vec{G}$, denoted $\chi_{o}(\vec{G})$. Contrary to the undirected case, an oriented graph whose oriented chromatic number is exactly its order is not necessarily a tournament. As an illustration of that claim, remark that $\chi_{o}\left(\overrightarrow{C_{5}}\right)=5$, where $\overrightarrow{C_{5}}$ is the circuit on 5 vertices.

Oriented cliques (or o-clique for short) were introduced as the analogues of cliques regarding proper oriented colouring. In other words, o-cliques are those oriented graphs whose oriented chromatic number is exactly their order. Ocliques have been mainly studied regarding the extremal theory point of view. The interested reader may refer to $[1,3,5,9]$ for interesting results regarding the size of o-cliques, and to [4, 7] for results on the maximum order of planar o-cliques.

The oriented chromatic number can also be defined for undirected graphs [8]. If $G$ is an undirected graph, then $\chi_{o}(G)$ is defined as

$$
\chi_{o}(G)=\max \left\{\chi_{o}(\vec{G}), \vec{G} \text { is an orientation of } G\right\}
$$

Hence, we have $\chi_{o}(G)=|V(G)|$ if and only if $G$ admits an orientation which is an o-clique. It follows from the definition that an oriented graph is an oclique if and only if it has weak diameter at most 2 [4]. Therefore, we get that $\chi_{o}(G)=|V(G)|$ if and only if $G$ admits a 2-weak orientation, and finding 2-weak orientations of graphs becomes of interest.

From the algorithmic point of view, the complexity of deciding whether an undirected graph admits a 2 -weak orientation was still unknown. Note that the analogous question for 2 -strong orientations was settled by Chvátal and Thomassen, who showed this problem to be NP-complete [2]. We here settle this question by studying the following decision problem.

Orientation with Weak Diameter $k-k$-OWD
Instance: A graph $G$.
Question: Does $G$ admit a $k$-weak orientation?
A graph admits a 1-weak orientation if and only if it is a complete graph. Therefore, 1-OWD is in P. In this work, we show the following.

Theorem 1. $k$-OWD is NP-complete for every $k \geq 2$.
Regarding our motivations above, we also deduce the following hardness result as an immediate corollary of the NP-completeness of 2-OWD.

Corollary 2. Deciding whether $\chi_{o}(G)=|V(G)|$ for an undirected graph $G$ is NP-complete.

## 2. Proof of Theorem 1

The problem $k$-OWD is in NP for every $k$ since one can, given an orientation $\vec{G}$ of $G$, check whether $\operatorname{diam}_{w}(\vec{G}) \leq k$. For this purpose, one just has to check, for every possible pair $\{u, v\}$ of distinct vertices of $G$, whether either $u$ and $v$ are adjacent, or there exist $k^{\prime} \leq k-1$ vertices $w_{1}, w_{2}, \ldots, w_{k^{\prime}}$ such that $\overrightarrow{u w_{1} w_{2} \ldots w_{k^{\prime}} v}$ or $\overrightarrow{v w_{1} w_{2} \ldots w_{k^{\prime}}} \vec{u}$ is a dipath of $\vec{G}$. This naive witness algorithm runs in polynomial time with respect to the order of $G$.

Let $k \geq 2$ be fixed. We show that $k$-OWD is NP-hard by reduction from the following problem, which is shown to be NP-complete in [6].
2-Vertex-Colouring of 3-Uniform Hypergraphs - 2COL Instance: A 3-uniform hypergraph $H$.
Question: Is $H 2$-colourable, i.e. can we colour each vertex of $H$ either blue or red so that each edge of $H$ has at least one blue and one red vertex?

Throughout this paper, we denote the vertices and edges of any hypergraph $H$ with order $n$ and size $m$ by $x_{1}, x_{2}, \ldots, x_{n}$ and $E_{1}, E_{2}, \ldots, E_{m}$, respectively. For every $i \in\{1,2, \ldots, n\}$, we further denote by $n_{i} \geq 1$ the number of distinct edges of $H$ which contain the vertex $x_{i}$. From a 3 -uniform hypergraph $H$, we produce a graph $G_{H}$ such that $H$ is 2 -colourable if and only if $G_{H}$ admits a $k$-weak orientation $\overrightarrow{G_{H}}$. This reduction is achieved in polynomial time regarding the size of $H$.

We first describe the core $G_{H}^{c}$ of $G_{H}$, i.e. the subgraph of $G_{H}$ from which the equivalence with $H$ follows. The subgraph $G_{H}^{c}$ does not have diameter $k$, but $G_{H}$ will be augmented later so that it has diameter $k$, and this without altering the equivalence. The core $G_{H}^{c}$ has the following vertices (see Figure 1). With each vertex $x_{i}$ of $H$, we associate $n_{i}+2$ vertices $u_{i}, u_{i}^{\prime}$, and $v_{i, j_{1}}, v_{i, j_{2}}, \ldots, v_{i, j_{n_{i}}}$ in $G_{H}^{c}$, where $j_{1}, j_{2}, \ldots, j_{n_{i}}$ are the distinct indices of the edges of $H$ which contain $x_{i}$. We now associate additional vertices in $G_{H}^{c}$ with each edge $E_{j}$ of $H$, where $j \in\{1,2, \ldots, m\}$. This association depends on the parity of $k$.

- If $k$ is even, then add two vertices $a_{j}$ and $a_{j}^{\prime}$ to $G_{H}^{c}$.


Figure 1: The core subgraph $G_{H}^{c}$ of $G_{H}$ obtained assuming $H$ has two edges $E_{1}=\left\{x_{1}, x_{2}, x_{3}\right\}$ and $E_{2}=\left\{x_{3}, x_{4}, x_{5}\right\}$.

- Otherwise, if $k$ is odd, then add two cycles $a_{j} b_{j} c_{j} a_{j}$ and $a_{j}^{\prime} b_{j}^{\prime} c_{j}^{\prime} a_{j}^{\prime}$ with length 3 to $G_{H}^{c}$.

We now link the vertices of $G_{H}^{c}$ by means of several vertex-disjoint paths. By "joining a pair of vertices $\{u, v\}$ by a path", we mean that we identify the endvertices of a new path with $u$ and $v$, respectively. Since this operation is used at most once for joining any pair $\{u, v\}$ of $G_{H}^{c}$, we use the notation $u P v$ to denote the resulting path (if any). First, join every pair $\left\{u_{i}, u_{i}^{\prime}\right\}$ by a path with length $\left\lfloor\frac{k}{2}\right\rfloor$. Then also join every pair $\left\{u_{i}^{\prime}, v_{i, j}\right\}$ by a path with length $\left\lceil\frac{k}{2}\right\rceil$. Now consider each edge $E_{j}=\left\{x_{i_{1}}, x_{i_{2}}, x_{i_{3}}\right\}$ of $H$, and add the following paths to $G_{H}^{c}$.

- If $k$ is even, join every pair of $\left\{v_{i_{1}, j}, v_{i_{2}, j}, v_{i_{3}, j}\right\} \times\left\{a_{j}, a_{j}^{\prime}\right\}$ by means of a path with length $\frac{k}{2}$.
- Otherwise, if $k$ is odd, then join every pair of $\left\{v_{i_{1}, j}\right\} \times\left\{a_{j}, a_{j}^{\prime}\right\},\left\{v_{i_{2}, j}\right\} \times$ $\left\{b_{j}, b_{j}^{\prime}\right\}$, and $\left\{v_{i_{3}, j}\right\} \times\left\{c_{j}, c_{j}^{\prime}\right\}$ by a path with length $\left\lfloor\frac{k}{2}\right\rfloor$.

Note that, by construction, exactly one pair $\left\{v_{i, j}, s\left(v_{i, j}\right)\right\}$ (resp. $\left.\left\{v_{i, j}, s^{\prime}\left(v_{i, j}\right)\right\}\right)$ was joined by a path with length $\left\lfloor\frac{k}{2}\right\rfloor$, where $s\left(v_{i, j}\right)$ (resp. $s^{\prime}\left(v_{i, j}\right)$ ) is a vertex of the form $a_{j}, b_{j}$ or $c_{j}$ (resp. $a_{j}^{\prime}, b_{j}^{\prime}$ or $\left.c_{j}^{\prime}\right)$. The notation $s\left(v_{i, j}\right)$ and $s^{\prime}\left(v_{i, j}\right)$ are used throughout this section. In particular, observe that if $k$ is even, then we have $s\left(v_{i_{1}, j}\right)=s\left(v_{i_{2}, j}\right)=s\left(v_{i_{3}, j}\right)=a_{j}$ for every edge $E_{j}=\left\{x_{i_{1}}, x_{i_{2}}, x_{i_{3}}\right\}$ of $H$. We analogously have $s^{\prime}\left(v_{i_{1}, j}\right)=s^{\prime}\left(v_{i_{2}, j}\right)=s^{\prime}\left(v_{i_{3}, j}\right)=a_{j}^{\prime}$.

A pair $\{u, v\}$ of distinct vertices of $G_{H}^{c}$ is said representative whenever it matches one of the following forms.

1. $\left\{u_{i}, v_{i, j}\right\}$ where $i \in\{1,2, \ldots, n\}, j \in\{1,2, \ldots, m\}$, and $x_{i} \in E_{j}$.
2. $\left\{u_{i}^{\prime}, s\left(v_{i, j}\right)\right\}$ where $i \in\{1,2, \ldots, n\}, j \in\{1,2, \ldots, m\}$, and $x_{i} \in E_{j}$.
3. $\left\{v_{i_{1}, j}, v_{i_{2}, j}\right\}$ where $i_{1}, i_{2} \in\{1,2, \ldots, n\}, j \in\{1,2, \ldots, m\}$, and $x_{i_{1}}, x_{i_{2}} \in E_{j}$.

An orientation of $G_{H}^{c}$ is good if two vertices forming a representative pair are linked by a $k$-dipath in either direction. Note that, in this definition, there is no requirement on the oriented distance between two vertices which are at distance at least $k+1$. A representative pair is a pair of vertices which are not adjacent in $G_{H}$, and for which there are at most two paths with length at most $k$ joining it. All of these paths belong to $G_{H}^{c}$ so that the existence of a $k$-weak orientation of $G_{H}$ depends on the existence of a good orientation of $G_{H}^{c}$.

We prove below that we have an equivalence between finding a proper 2 -vertex-colouring of $H$ and a good orientation of $G_{H}^{c}$. The proof relies on the following claims.

Claim 1. Suppose the vertex $x_{i}$ belongs to the edges $E_{j_{1}}, E_{j_{2}}, \ldots, E_{j_{n_{i}}}$ of $H$. Then, in any good orientation $\overrightarrow{G_{H}^{c}}$ of $G_{H}^{c}, \overrightarrow{u_{i} P u_{i}^{\prime} P v_{i, j} P s\left(v_{i, j}\right.}$ is a dipath for every $j \in\left\{j_{1}, j_{2}, \ldots, j_{n_{i}}\right\}$, or $\overrightarrow{s\left(v_{i, j}\right) P v_{i, j} P u_{i}^{\prime} P u_{i}}$ is a dipath for every $j \in$ $\left\{j_{1}, j_{2}, \ldots, j_{n_{i}}\right\}$.

Proof. Note that because $u_{i} P u_{i}^{\prime} P \xrightarrow{v_{i, j_{1}}}$ is the only path with length at most $k$ joining $u_{i}$ and $v_{i, j_{1}}$ in $G_{H}^{c}$, either $\overrightarrow{u_{i} P u_{i}^{\prime} P v_{i, j_{1}}}$ or $\overrightarrow{v_{i, j_{1}} P u_{i}^{\prime} P u_{i}}$ must be a dipath of $\overrightarrow{G_{H}^{c}}$. Assume $\overrightarrow{u_{i} P u_{i}^{\prime} P v_{i, j_{1}}}$ is a dipath of $\overrightarrow{G_{H}^{c}}$. Since $\overrightarrow{u_{i} P u_{i}^{\prime}}$ is now a dipath of $\overrightarrow{G_{H}^{c}}, \overrightarrow{u_{i}^{\prime} P v_{i, j}}$ must also be a dipath for every $j \in\left\{j_{1}, j_{2}, \ldots, j_{n_{i}}\right\}$ since $u_{i} P u_{i}^{\prime} P v_{i, j}$ is the only path with length at most $k$ joining $u_{i}$ and $v_{i, j}$ in $G_{H}^{c}$.

Similarly, since, for every $j \in\left\{j_{1}, j_{2}, \ldots, j_{n_{i}}\right\}$, the only path with length at most $k$ joining $u_{i}^{\prime}$ and $s\left(v_{i, j}\right)$ in $G_{H}^{c}$ is $u_{i}^{\prime} P v_{i, j} P s\left(v_{i, j}\right)$, and $\overrightarrow{u_{i}^{\prime} P v_{i, j}}$ is a dipath of $\overrightarrow{G_{H}^{c}}$, then $\overrightarrow{v_{i, j} P s\left(v_{i, j}\right)}$ has to be a dipath of $\overrightarrow{G_{H}^{c}}$. Thus, $\overrightarrow{u_{i} P u_{i}^{\prime} P v_{i, j} P s\left(v_{i, j}\right)}$ belongs to $\overrightarrow{G_{H}^{c}}$ for every $j \in\left\{j_{1}, j_{2}, \ldots, j_{n_{i}}\right\}$ assuming that $\xrightarrow[u_{i} P u_{i}^{\prime} P v_{i, j_{1}}]{\text { belongs }}$ to the orientation. The claim follows analogously from the assumption that $\overrightarrow{v_{i, j_{1}} P u_{i}^{\prime} P u_{i}}$ is a dipath of $\overrightarrow{G_{H}^{c}}$.

Claim 2. Suppose $k$ is even, and $E_{j}=\left\{x_{i_{1}}, x_{i_{2}}, x_{i_{3}}\right\}$ is an edge of $H$. Then, in any good orientation $\overrightarrow{G_{H}^{c}}$ of $G_{H}^{c}$, either $\overrightarrow{v_{i, j} P s\left(v_{i, j}\right)}$ or $\overrightarrow{s\left(v_{i, j}\right) P v_{i, j}}$ is a dipath for every $i \in\left\{i_{1}, i_{2}, i_{3}\right\}$. Furthermore, these three dipaths cannot be all directed from or towards the $s\left(v_{i, j}\right)$ 's.

Proof. Recall that $s\left(v_{i_{1}, j}\right)=s\left(v_{i_{2}, j}\right)=s\left(v_{i_{3}, j}\right)=a_{j}$ and $s^{\prime}\left(v_{i_{1}, j}\right)=s^{\prime}\left(v_{i_{2}, j}\right)=$ $s^{\prime}\left(v_{i_{3}, j}\right)=a_{j}^{\prime}$ when $k$ is even. Note further that there are only two paths with length at most $k$ joining any two of $v_{i_{1}, j}, v_{i_{2}, j}$, and $v_{i_{3}, j}$. These include $a_{j}$ and $a_{j}^{\prime}$, respectively. If the statement of the claim is not fulfilled, then there is no $k$-dipath of $\overrightarrow{G_{H}^{c}}$ joining any two of $v_{i_{1}, j}, v_{i_{2}, j}$, and $v_{i_{3}, j}$ including $a_{j}$. So there must be three $k$-dipaths joining these vertices including $a_{j}^{\prime}$, but this is impossible.

Claim 3. Suppose $k$ is odd, and $E_{j}=\left\{x_{i_{1}}, x_{i_{2}}, x_{i_{3}}\right\}$ is an edge of $H$. Then, in any good orientation $\overrightarrow{G_{H}^{c}}$ of $G_{H}^{c}$, either $\overrightarrow{v_{i, j} P s\left(v_{i, j}\right)}$ or $\overrightarrow{s\left(v_{i, j}\right) P v_{i, j}}$ is a dipath for every $i \in\left\{i_{1}, i_{2}, i_{3}\right\}$. Besides these three dipaths cannot be all directed from or towards the $s\left(v_{i, j}\right)$ 's.

Proof. Similarly as for previous Claim 2, if the statement of the claim is not fulfilled by $\overrightarrow{G_{H}^{c}}$, then there is no dipath with length at most $k$ joining any two of $v_{i_{1}, j}, v_{i_{2}, j}$, and $v_{i_{3}, j}$ including the $s\left(v_{i, j}\right)$ 's. Then there cannot be three $k$ dipaths, including the $s^{\prime}\left(v_{i, j}\right)$ 's, joining every pair of these vertices, and this no matter how the paths $v_{i_{1}, j} s^{\prime}\left(v_{i_{1}, j}\right), v_{i_{2}, j} s^{\prime}\left(v_{i_{2}, j}\right)$ and $v_{i_{3}, j} s^{\prime}\left(v_{i_{3}, j}\right)$ are oriented, and how the edges of the cycles $a_{j} b_{j} c_{j} a_{j}$ and $a_{j}^{\prime} b_{j}^{\prime} c_{j}^{\prime} a_{j}^{\prime}$ are oriented.

Regarding previous Claims 2 and 3, remark that if two of the dipaths obtained by orienting the paths $v_{i_{1}, j} P s\left(v_{i_{1}, j}\right), v_{i_{2}, j} P s\left(v_{i_{2}, j}\right)$ and $v_{i_{3}, j} P s\left(v_{i_{3}, j}\right)$ have the same direction, i.e. from or towards the $s\left(v_{i, j}\right)$ 's while the third one is oriented in the opposite direction, then we can obtain three $k$-dipaths joining any two of $v_{i_{1}, j}, v_{i_{2}, j}$, and $v_{i_{3}, j}$. Suppose e.g. that $\overrightarrow{v_{i_{1}, j} P s\left(v_{i_{1}, j}\right)}, \overrightarrow{v_{i_{2}, j} P s\left(v_{i_{2}, j}\right)}$ and $\overrightarrow{s\left(v_{i_{3}, j}\right) P v_{i_{3}, j}}$ are dipaths of $\overrightarrow{G_{H}^{c}}$. So far, note that there are two $k$-dipaths starting from $v_{i_{1}, j}$ and $v_{i_{2}, j}$, respectively, and ending at $v_{i_{3}, j}$ (when $k$ is odd, these are obtained by adding $\overrightarrow{s\left(v_{i_{1}, j}\right) s\left(v_{i_{3}, j}\right)}$ and $\overrightarrow{s\left(v_{i_{2}, j}\right) s\left(v_{i_{3}, j}\right)}$ to $\left.E\left(\overrightarrow{G_{H}^{c}}\right)\right)$. The last $k$-dipath starting from $v_{i_{1}, j}$ and ending at $v_{i_{2}, j}$ can be obtained e.g. by orienting the edges of $G_{H}^{c}$ in such a way that $\overrightarrow{v_{i_{1}, j} P s^{\prime}\left(v_{i_{1}, j}\right)}$ and $\overrightarrow{s^{\prime}\left(v_{i_{2}, j}\right) P v_{i_{2}, j}}$ are dipaths, and $\overrightarrow{s^{\prime}\left(v_{i_{1}, j}\right) s^{\prime}\left(v_{i_{2}, j}\right)}$ is an arc when $k$ is odd.

According to Claims 1, 2 and 3, we have an equivalence between finding a proper 2-vertex-colouring of $H$ and a good orientation of $G_{H}^{c}$. Indeed, assume that having the dipath $\overrightarrow{u_{i} P u_{i}^{\prime}}$ (resp. $\overrightarrow{u_{i}^{\prime} P u_{i}}$ ) in an orientation of $G_{H}^{c}$ simulates that the vertex $x_{i}$ of $H$ is coloured blue (resp. red), and that having the dipath $\overrightarrow{v_{i, j} P s\left(v_{i, j}\right)}$ (resp. $\left.\overrightarrow{s\left(v_{i, j}\right) P v_{i, j}}\right)$ simulates the fact that the vertex $x_{i}$ is counted as a blue (resp. red) vertex in $E_{j}$. Claim 1 reflects the fact that if $x_{i}$ is coloured, say, blue by a proper 2 -vertex-colouring of $H$, then $x_{i}$ counts as a blue vertex in every edge which contains it. Claims 2 and 3 depict the fact that all vertices from a single edge of $H$ cannot have the same colour. Thus, from a proper 2-vertex-colouring of $H$ we can deduce a good orientation of $G_{H}^{c}$, and vice-versa.

We now augment $G_{H}$ with additional vertices so that there is a path with length at most $k$ joining every two non-adjacent vertices of $G_{H}^{c}$ that do not form


Figure 2: The gadgets $G_{u}$ and $G_{v}$ obtained for a pair $\{u, v\}$ which is not representative.
a representative pair. This is done in such a way that there is an orientation of the edges of $E\left(G_{H}\right)-E\left(G_{H}^{c}\right)$ so that every two vertices of $G_{H}$ that do not form a representative pair are joined by a dipath with length at most $k$. In this way, the existence of a $k$-weak orientation of $G_{H}$ only relies on the existence of a good orientation of $G_{H}^{c}$.

The augmentation consists in associating a gadget $G_{v}$ with each vertex $v$ of $G_{H}^{c}$, and then connecting all the resulting gadgets in such a way there is a path with length at most $k$ between any two vertices from different gadgets $G_{u}$ and $G_{v}$. In the case where $\{u, v\}$ is not a representative pair, we add a shortcut between $G_{u}$ and $G_{v}$, i.e. an alternative shorter path for joining two vertices of $G_{u}$ and $G_{v}$. This is done in such a way that every vertex $u^{\prime}$ of $G_{u}$ is at distance at most $k$ from any vertex $v^{\prime}$ of $G_{v}$, unless $u^{\prime}=u, v^{\prime}=v$ and $\{u, v\}$ is a representative pair. However, in the situation where $\{u, v\}$ is not representative, there is a path with length $k$ joining $u$ and $v$ that uses the shortcut between $G_{u}$ and $G_{v}$.

Set $x=\left\lfloor\frac{k}{2}\right\rfloor$. For every $i \in\{1,2, \ldots, x\}$, add two new vertices $s_{v}^{i}$ and $p_{v}^{i}$ to $G_{v}$. These two vertices form the $i^{\text {th }}$ level of $G_{v}$, and are said to be $i$-vertices. Next, for every $i \in\{1,2, \ldots, x-1\}$, add all possible edges between the $i$ - and $(i+1)$-vertices of $G_{v}$ so that two consecutive levels of $G_{v}$ form a clique on 4 vertices. Finally, add an edge between $v$ and every 1-vertex of $G_{v}$.

We finish the construction of $G_{H}$ by adding some connection between the gadgets. We distinguish two cases depending on the parity of $k$.

- If $k$ is even, then we turn the subgraph induced by all $x$-vertices of $G_{H}$ into a clique. Next, for every pair $\{u, v\}$ of vertices of $G_{H}^{c}$ which is not representative, add a shortcut vertex $e_{u, v}$ to the clique constructed just before. Finally, add every edge between $e_{u, v}$ and the vertices from the $(x-1)^{t h}$ levels of $G_{u}$ and $G_{v}$ if $k \geq 4$, or the edges $u e_{u, v}$ and $e_{u, v} v$ when $k=2$.
- Otherwise, if $k$ is odd, then add a new vertex $z$ to $G_{H}$, and add all possible edges between $z$ and $x$-vertices. For every pair $\{u, v\}$ of $G_{H}^{c}$ that is not
representative, also add the shortcut edges $s_{u}^{x} p_{v}^{x}$ and $p_{u}^{x} s_{v}^{x}$ to $G_{H}$.
This construction is illustrated in Figure 2 for $k=6$ and $k=7$. Note that no new path with length at most $k$ between two vertices composing a representative pair of $G_{H}$ arose from the modifications. Therefore, the equivalence between finding a proper 2-vertex-colouring of $H$ and a good orientation of $G_{H}^{c}$ is preserved. We finally show that there is an orientation of the edges we just added so that every pair of vertices of $G_{H}$ which is not representative is joined by a $k$-dipath in either direction.

Define an arbitrary ordering $\sigma=\left(v_{1}, v_{2}, \ldots, v_{\left|V\left(G_{H}^{c}\right)\right|}\right)$ over all vertices of $G_{H}^{c}$, and consider the following partial orientation. First, for every vertex $v$ of $G_{H}^{c}$, let $\overrightarrow{v s_{v}^{1}}$ and $\overrightarrow{p_{v}^{1} v}$ be arcs. Then, for every level $i \in\{1,2, \ldots, x\}$ of $G_{v}$, let $\overrightarrow{p_{v}^{i} s_{v}^{i}}$ be an arc. Next, for every $i \in\{1,2, \ldots, x-1\}$, add the $\operatorname{arcs} \overrightarrow{s_{v}^{i} s_{v}^{i+1}}$, $\overrightarrow{p_{v}^{i+1} p_{v}^{i}}, \overrightarrow{p_{v}^{i} s_{v}^{i+1}}$ and $\overrightarrow{p_{v}^{i+1} s_{v}^{i}}$ to the partial orientation. The partial orientation is completed depending on the parity of $k$.

- If $k$ is even, then, for every shortcut vertex $e$ of $G_{H}$, add the $\operatorname{arcs} \overrightarrow{s_{v}^{x} e}$ and $\overrightarrow{e p_{v}^{x}}$. Next, for every $i<j$ consider $\overrightarrow{s_{v_{i}}^{x} s_{v_{j}}^{x}}, \overrightarrow{s_{v_{i}}^{x} p_{v_{j}}^{x}}, \overrightarrow{p_{v_{i}}^{x} s_{v_{j}}^{x}}$ and $\overrightarrow{p_{v_{i}}^{x} p_{v_{j}}^{x}}$ as arcs of the partial orientation. Additionally, if $\left\{v_{i}, v_{j}\right\}$ is not a representative pair, then let $\overrightarrow{s_{v_{j}}^{x-1} e_{v_{i}, v_{j}}}, \overrightarrow{e_{v_{i}, v_{j}} p_{v_{i}}^{x-1}}, \overrightarrow{s_{v_{i}}^{x-1} e_{v_{i}, v_{j}}}$, and $\overrightarrow{e_{v_{i}, v_{j}} p_{v_{j}}^{x-1}}$ be arcs if $k \geq 4$, or $\overrightarrow{v_{i} e_{v_{i}, v_{j}}}$ and $\overrightarrow{e_{v_{i}, v_{j}} v_{j}}$ be arcs when $k=2$.
- If $k$ is odd, then let $\overrightarrow{s_{v_{i}}^{x} z}$ and $\overrightarrow{z p_{v_{i}}^{x}}$ be arcs. Finally, if $\left\{v_{i}, v_{j}\right\}$ is not representative, then let $\overrightarrow{s_{v_{i}}^{x} p_{v_{j}}^{x}}$ and $\overrightarrow{s_{v_{j}}^{x} p_{v_{i}}^{x}}$ be arcs.
Note that, under the partial orientation given above, any vertex $u^{\prime}$ from a gadget $G_{u}$ can directly "access" the upper or lower level of $G_{u}$. Besides, there is a dipath with length at most $k$ joining $u^{\prime}$ and any vertex $v^{\prime}$ from another gadget $G_{v}$, unless $u^{\prime}=u, v^{\prime}=v$, and $\{u, v\}$ is a representative pair. Such a path typically goes up across $G_{u}$, then exits $G_{u}$ to enter $G_{v}$ (either directly from the $x^{t h}$ levels or via $z$ ), and finally goes down across $G_{v}$. Because the gadgets have $x=\left\lfloor\frac{k}{2}\right\rfloor$ levels, the length of such a path does not exceed $k$. Finally observe that if $\{u, v\}$ is representative, then there is no path with length at most $k$ joining $u$ and $v$ going across the gadgets. On the contrary, if $\{u, v\}$ is not a representative pair, then there is a path with length exactly $k$ joining $u$ and $v$. This path necessarily includes the shortcut between $G_{u}$ and $G_{v}$, i.e. the vertex $e_{u, v}$ if $k$ is even or an edge linking the $x^{t h}$ levels of $G_{u}$ and $G_{v}$ otherwise.

Hence, $G_{H}$ admits a $k$-weak orientation if and only if $G_{H}^{c}$ admits a good orientation. Besides, $G_{H}^{c}$ admits a good orientation if and only if $H$ is 2-colourable. By transitivity, we get that $G_{H}$ admits a $k$-weak orientation if and only if $H$ is 2 -colourable, and thus that $k$-OWD is NP-complete.

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