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# Multi-revolution composition methods for highly oscillatory differential equations

Philippe Chartier<sup>1</sup>, Joseba Makazaga<sup>2</sup>, Ander Murua<sup>2</sup>, and Gilles Vilmart<sup>3</sup>

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## Abstract

We introduce a new class of multi-revolution composition methods (MRCM) for the approximation of the  $N^{\text{th}}$ -iterate of a given near-identity map. When applied to the numerical integration of highly oscillatory systems of differential equations, the technique benefits from the properties of standard composition methods: it is intrinsically geometric and well-suited for Hamiltonian or divergence-free equations for instance. We prove error estimates with error constants that are independent of the oscillatory frequency. Numerical experiments, in particular for the nonlinear Schrödinger equation, illustrate the theoretical results, as well as the efficiency and versatility of the methods.

**Keywords:** near-identity map, highly-oscillatory, averaging, differential equation, composition method, geometric integration, asymptotic preserving.

**MSC numbers:** 34K33, 37L05, 35Q55.

## 1 Introduction

In this paper, we are concerned with the approximation of the  $M$ -th iterates of a near-identity smooth map by compositions methods. More precisely, considering a smooth map  $(\varepsilon, y) \mapsto \varphi_\varepsilon(y)$  of the form

$$\varphi_\varepsilon(y) = y + \varepsilon\Theta_\varepsilon(y), \quad (1)$$

we wish to approximate the result of  $M = \mathcal{O}(1/\varepsilon)$  compositions of  $\varphi_\varepsilon$  with itself

$$\varphi_\varepsilon^M = \underbrace{\varphi_\varepsilon \circ \cdots \circ \varphi_\varepsilon}_{M \text{ times}} \quad (2)$$

with the aid of a method whose efficiency remains essentially independent of  $\varepsilon$ .

In order to motivate our composition methods, it will be useful to observe that  $\varphi_\varepsilon$  can be seen as one step with step-size  $\varepsilon$  of a first order integrator for the differential equation

$$\frac{dz(t)}{dt} = \Theta_0(z(t)), \quad (3)$$

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where  $\Theta_0(z) = \frac{d}{d\varepsilon}\varphi_\varepsilon(z)|_{\varepsilon=0}$ , and thus,  $\varphi_\varepsilon^M(y)$  may be interpreted as an approximation at  $t = M\varepsilon$  of the solution  $z(t)$  of (3) with initial condition

$$z(0) = y. \quad (4)$$

A standard error analysis shows that  $\varphi_\varepsilon^N(y) - z(N\varepsilon) = \mathcal{O}(\varepsilon H)$  as  $H = N\varepsilon \rightarrow 0$ , which makes clear that, for sufficiently small  $H = \varepsilon N$ ,  $\varphi_\varepsilon^N(y)$  could be approximated by one step  $\Psi_H(y) \approx z(H)$  of any  $p$ th order integrator applied to the initial value problem (3)–(4) within an error of size  $\mathcal{O}(H^{p+1} + \varepsilon H)$ . In particular,  $\varphi_H$  can be seen as a first order integrator for the ODE (3), and a second order integrator can be obtained as

$$\Psi_H(y) = \varphi_{H/2} \circ \varphi_{H/2}^*(y), \quad (5)$$

where  $\varphi_\varepsilon^* := \varphi_{-\varepsilon}^{-1}$  is the *adjoint map* of  $\varphi_\varepsilon$ . More generally, one could consider  $p$ th order compositions integrators of the form [21]

$$\Psi_H(y) := \varphi_{a_1 H} \circ \varphi_{b_1 H}^* \circ \cdots \circ \varphi_{a_s H} \circ \varphi_{b_s H}^*(y) \approx z(H) \quad (6)$$

with suitable coefficients  $a_i, b_i$  (see for instance [15, 22] for particular sets of coefficients chosen for different  $s$  and  $p$ ), that would provide an approximation

$$\Psi_H(y) = z(H) + \mathcal{O}(H^{p+1}) = \varphi_\varepsilon^N(y) + \mathcal{O}(H^{p+1} + \varepsilon H)$$

for  $H = N\varepsilon \leq H_0$ . However, the accuracy of the approximation is limited by the given value of the problem parameter  $\varepsilon$  being sufficiently small. Motivated by that, we generalize the approximation (6) by replacing the real numbers  $a_i, b_i$  ( $j = 1, \dots, s$ ) by appropriate coefficients  $\alpha_j(N), \beta_j(N)$  depending on  $N$ , chosen in such a way that  $\varphi_\varepsilon^N$  is approximated for sufficiently small  $H = N\varepsilon$  within an error of size  $\mathcal{O}(H^{p+1})$ , where the error constant is independent of  $N, H, \varepsilon$ . We will say that such a method

$$\Psi_{N,H}(y) := \varphi_{\alpha_1(N)H} \circ \varphi_{\beta_1(N)H}^* \circ \cdots \circ \varphi_{\alpha_s(N)H} \circ \varphi_{\beta_s(N)H}^*(y) \quad (7)$$

is an  $s$ -stage  $p$ th order *multi-revolution composition method* (MRCM) if

$$\Psi_{N,H}(y) = \varphi_\varepsilon^N(y) + \mathcal{O}(H^{p+1}), \quad \text{for } H = N\varepsilon \leq H_0. \quad (8)$$

For instance, we will see that the second order standard composition method (5) can be modified to give a second order MRCM (7) with  $s = 1$ ,  $\alpha_1(N) = (1 + N^{-1})/2$ , and  $\beta_1(N) = (1 - N^{-1})/2$ ,

$$\Psi_{N,H}(y) = \varphi_{\alpha_1(N)H} \circ \varphi_{\beta_1(N)H}^*(y) = \varphi_\varepsilon^N(y) + \mathcal{O}(H^3), \quad H = N\varepsilon.$$

It is interesting to observe that this second order MRCM reduces in the limit case  $N \rightarrow \infty$  to the standard composition method (5) (a second order integrator for the ODE (3)), which is consistent with the fact that  $\varphi_{H/N}^N$  converges to the  $H$ -flow of (3) as  $N \rightarrow \infty$ . More generally, any  $p$ th order MRCM (7), gives rise to a  $p$ th order standard composition method (6) with

$$a_i = \lim_{N \rightarrow \infty} \alpha_i(N), \quad b_i = \lim_{N \rightarrow \infty} \beta_i(N).$$

In practice, if one wants to approximately compute the map  $\varphi_\varepsilon^M$  for a given small value of  $\varepsilon$  and large positive integers  $M$  within a given error tolerance by means of a  $s$ -stage  $p$ th order MRCM (7), then one should choose a sufficiently small step-size  $H$  to achieve the required accuracy, and accordingly choose  $N$  as the integer part of  $H/\varepsilon$ , in order to approximate  $\varphi_\varepsilon^M(y)$ , for  $M = mN$ ,  $m = 1, 2, 3 \dots$ , as

$$\varphi_\varepsilon^{mN}(y) \approx \Psi_{N,H}(y)^m.$$

These approximations will be computed more efficiently than actually evaluating  $\varphi_\varepsilon^{mN}(y)$  if such a positive integer  $N$  is larger than  $2s$  (here we assume that the computational cost of computing  $\varphi_\varepsilon^* = \varphi_{-\varepsilon}^{-1}$  is similar to that of computing  $\varphi_\varepsilon$ ). Since the error of such approximation essentially depends on  $H$  but not on  $\varepsilon$ , for a prescribed accuracy (which determine  $H$ ), the computational cost may be reduced by a factor of  $N/(2s) \leq H/(2s\varepsilon)$ , which increases as  $\varepsilon$  decreases.

The main application we have in mind is the time integration of highly-oscillatory problems with a single harmonic frequency  $\omega = 2\pi/\varepsilon$ . In the numerical examples, we consider in particular problems of the form

$$\frac{d}{dt}y(t) = \frac{1}{\varepsilon}Ay(t) + f(y(t)), \quad 0 \leq t \leq T, \quad y(0) = y_0 \in \mathbb{R}^d, \quad (9)$$

where  $A$  is a  $d \times d$  skew-symmetric matrix with eigenvalues in  $2\pi i\mathbb{Z}$ , so that  $e^{tA}$  is 1-periodic in time, and where  $f : \mathbb{R}^d \rightarrow \mathbb{R}^d$  is a given nonlinear smooth function. In this situation, we shall consider  $\varphi_\varepsilon$  as the flow with time  $\varepsilon$  (the period of the unperturbed equation corresponding to  $f(y) \equiv 0$ ) of equation (9), or equivalently, the flow with time 1 of the system

$$\frac{d}{dt}y(t) = Ay(t) + \varepsilon f(y(t)).$$

It is well known [8, 9] that such a map  $\varphi_\varepsilon$  is a smooth near-identity map, and furthermore, that (3) is in this case the first order averaged equation, more precisely,

$$\Theta_0(z) = \left. \frac{d}{d\varepsilon}\varphi_\varepsilon(z) \right|_{\varepsilon=0} = \int_0^1 e^{-At} f(e^{At}z) dt.$$

The solution  $y(t)$  of the initial value problem (9) sampled at the times  $t = \varepsilon M$  will then be given by

$$y(\varepsilon M) = \varphi_\varepsilon^M(y_0),$$

and thus, for an appropriately chosen positive integer  $N$  (determined by accuracy requirements and the actual value of  $\varepsilon$ ), we may use a  $p$ th order MRCM (7) to compute the approximations

$$y_m = \Psi_{N,H}(y)^m \approx \varphi_\varepsilon^{mN}(y_0) = y(t_m), \quad \text{where } t_m = mH, \quad H = \varepsilon N.$$

The local error estimate (8) then leads by standard arguments to a global error estimate of the form

$$y_m - y(t_m) = \mathcal{O}(H^p), \quad \text{for } t_m = mH \leq T,$$

where the constant in the  $\mathcal{O}$ -term depends on  $T$  but is independent of  $\varepsilon$  and  $H$ .

One may wonder if the application of  $\Psi_{N,H}$  in (7) makes any sense for non-integer values of  $N$ . It can be shown that, in the case of the application of a  $p$ th order MRCM to highly oscillatory systems of the form (9),  $\Psi_{H/\varepsilon,H}(y_0)$  gives for arbitrary  $\varepsilon, H > 0$ , a  $p$ th order approximation to the  $H$ -flow of the  $p$ th order (stroboscopically) averaged equation of (9) (see [26] and the recent work [8]), which is a smooth ODE of the form

$$\frac{dz}{dt} = \Theta_0(z) + \varepsilon G_1(z) + \cdots + \varepsilon^{p-1} G_{p-1}(z), \quad z(0) = y_0 \quad (10)$$

whose solution  $z(t)$  satisfies

$$z(M\varepsilon) - y(M\varepsilon) = \mathcal{O}(\varepsilon^p), \quad \text{if } M\varepsilon \leq T,$$

for integer values of  $M$ . Indeed, it can be proven that, if a MRCM (7) is of order  $p$  (that is, (8) holds for integer values of  $N$ ), then, for arbitrary  $0 < \varepsilon < H \leq H_0$ ,

$$\Psi_{H/\varepsilon,H}(y_0) - z(H) = \mathcal{O}(H^{p+1}).$$

Notice that a similar statement can be made in the general case of an arbitrary smooth near-identity map, where  $\varphi_\varepsilon$  can be interpreted as a one-step integrator for the ODE (3), and (10) is the modified equation of (3) associated to  $\varphi_\varepsilon$  considered in backward error analysis of one step integrators [15, Chap. IX].

It is worth stressing that MRCMs can be applied to more general highly-oscillatory problems with a single harmonic frequency. This is the case of any problem that, possibly after a change of variables, can be written into the form

$$\frac{d}{dt}z(t) = g(z(t), t/\varepsilon), \quad 0 \leq t \leq T, \quad z(0) = z_0 \in \mathbb{R}^d, \quad (11)$$

where  $g(z, \tau)$  is smooth in  $z$  and continuous and 1-periodic in  $\tau$ . For instance, (9) can be recast into the format (11) with  $g(z, \tau) = e^{-\tau A} f(e^{\tau A} z)$  by considering the change of variables  $y = e^{tA/\varepsilon} z$ . In this more general context,  $\varphi_\varepsilon$  will be such that for arbitrary  $z_0$ , the solution  $z(t)$  of (11) satisfies that  $z(1/\varepsilon) = \varphi_\varepsilon(z_0)$ .

Highly oscillatory problems of the form (9) are in particular obtained by appropriate discretization in space of several Hamiltonian partial differentiation equations, such as nonlinear versions of wave equation and Schrödinger equation. In Section 4 we present some numerical experiments of the application of MRCMs to numerically integrate a problem considered in [7] and originally analyzed by B. Grébert and C. Villegas-Blas in [14]. It consists of a nonlinear Schrödinger equation with a cubic nonlinearity  $|u|^2 u$  multiplied by an inciting term of the form  $2 \cos(2x)$  and may be stated on the one-dimensional torus as

$$\begin{aligned} i\partial_t u &= -\Delta u + 2\varepsilon \cos(2x)|u|^2 u, \quad t \geq 0, \quad u(t, \cdot) \in H^s(\mathbb{T}_{2\pi}) \\ u(0, x) &= \cos x + \sin x. \end{aligned} \quad (12)$$

The problem is known to have a unique global solution in all Sobolev spaces  $H^s(\mathbb{T}_{2\pi})$  for  $s \geq 0$ . A pseudospectral approximation of the form

$$u(t, x) \approx \sum_{k=-\ell}^{\ell} \xi_k(t) e^{ikx}$$

may be obtained by determining the approximate Fourier modes  $\xi_k(t)$  as the solution with appropriate initial values of a semidiscrete version of equation (12)

$$\frac{d}{dt}\xi_k = -ik^2\xi_k + \varepsilon f_k(\xi_{-\ell}, \dots, \xi_{-1}, \xi_0, \xi_1, \dots, \xi_\ell), \quad k = -\ell, \dots, -1, 0, 1, \dots, \ell. \quad (13)$$

Clearly, the system of ODEs (13) can be recast into the format (9) by rescaling time (that is, by rewriting the system in terms of the new time variable  $\hat{t} = \frac{\varepsilon}{2\pi}t$ ).

Typically, the maps  $\varphi_\mu$  and  $\varphi_\mu^*$  in (7) with  $\mu = \alpha_j(N)H$ ,  $\mu = \beta_j(N)H$  ( $j = 1, \dots, s$ ) can not be computed exactly. In the context of highly oscillatory systems, and in particular, for systems of the form (9), the actual (approximate) computation of  $\varphi_\mu$  can be carried out essentially as a black-box operation: In practice, one may use any available implementation of some numerical integrator to approximate the flow with time 1 of the ODE

$$\frac{d}{dt}y(t) = Ay(t) + \mu f(y(t)). \quad (14)$$

In particular,  $\varphi_\mu$  may be approximated by applying  $n$  steps of step-size  $h = 1/n$  of an appropriate splitting method to (14), where  $n$  is chosen so as to resolve one oscillation. Let  $\Phi_{\mu,h}(y)$  denote the approximation of  $\varphi_\mu$  obtained in this way with a  $q$ th order splitting method, then the following estimate

$$\Phi_{\mu,h}(y) - \varphi_\mu(y) = \mathcal{O}(\mu^r h^q) \quad (15)$$

will be guaranteed to hold with  $r = 1$ . It is worth remarking that more refined estimates of the form  $\mathcal{O}(\mu^{r_1} h^{q_1} + \dots + \mu^{r_\ell} h^{q_\ell})$  can be obtained for certain splitting methods [20].

In the most general framework, we shall assume that, if  $\varphi_\mu$  can not be computed exactly, then it is approximated by some computable map  $\Phi_{\mu,h}$  (depending on a small parameter  $h$  that controls the accuracy of the approximation) satisfying the error estimate (15) for some  $r \geq 0$  and  $q \geq 1$ . Observe that one can expect  $r \geq 1$  in the right-hand side of (15) if (as in the case of splitting methods for (14),)  $\Phi_{\mu,h}$  is constructed so that  $\Phi_{0,h}(y) = \varphi_0(y) = y$ .

In what follows, the method (7) where the involved maps  $\varphi_\mu$  and  $\varphi_\mu^*$  are assumed to be computed exactly, will be referred to as *semi-discrete multi-revolution composition methods*. We next define the following fully-discrete version, in the spirit of Heterogeneous multiscale methods (HMM) (see [1, 10, 11]) which combine the application of macro-steps of length  $H$  (to advance along the solution of (9)) with the application to (14) of some integrator with micro-steps of size  $h = 1/n$  (where  $n$  is chosen large enough to resolve each oscillation).

**Definition 1.1** (Fully-discrete multi-revolution composition methods). *Given two integers  $s \geq 1$  and  $N \geq 2s$ , and an approximation  $\Phi_{\varepsilon,h}$  of  $\varphi_\varepsilon$ , an  $s$ -stage fully-discrete MRCM is a composition of the form*

$$\Psi_{N,H,h}(y) = \Phi_{\alpha_1(N)H,h} \circ \Phi_{\beta_1(N)H,h}^* \circ \dots \circ \Phi_{\alpha_s(N)H,h} \circ \Phi_{\beta_s(N)H,h}^*(y) \simeq \varphi_\varepsilon^N(y), \quad (16)$$

where  $\Phi_{\varepsilon,h}^* := \Phi_{-\varepsilon,h}^{-1}$  is the adjoint map of  $\Phi_{\varepsilon,h}$ .

When solving a highly-oscillatory problem of the form (9) with standard numerical methods, stability and accuracy requirements induce a step-size restriction of the form  $h \leq C\varepsilon$  which renders the computation of a reasonably accurate solution more and more costly and

sometimes even untractable for small values of  $\varepsilon$ . In contrast, approximating  $\varphi_\varepsilon^N$  with method (16) and  $N\varepsilon = H$  allow to approximate the solution with a prescribed accuracy at a cost which does not grow for small values of  $\varepsilon$ .

The general idea of multi-revolution methods has been first considered in astronomy, where  $\varepsilon$ -perturbation of periodic systems are recurrent, and named as such since these methods approximate many *revolutions* ( $N$  periods of time) by only a few (in our approach,  $2s$  compositions then accounts for  $2s$  revolutions with different values of the perturbation parameter  $\varepsilon$ ). A class of multi-revolution Runge-Kutta type methods has then been studied in the context of oscillatory problems of the form (9) [3, 4, 2, 23, 25]. Closely related methods were considered in [18] and also in [5].

Actually, MRCM are *asymptotic preserving*, a notion introduced in the context of kinetic equations (see [17], and the recent works [19, 13]) and ensuring that a method is uniformly accurate for a large range of values of the parameter  $\varepsilon$  with a computational cost essentially independent of  $\varepsilon$ . This is a feature shared by the proposed classes of multi-revolution methods.

The methods introduced in this paper differ from existing other multi-revolution methods in that they are intrinsically geometric, since they solely use compositions of maps of the form  $\varphi_\mu$  and  $\varphi_\mu^{-1}$ , whose geometric properties are determined by equation (9). In particular, it is *symplectic* if (9) is *Hamiltonian*, *volume-preserving* if (9) is *divergence-free*, and shares the same invariants which are independent of  $\varepsilon$  as the flow of (9). This is also true in the fully-discrete version (16) provided that the micro-integrator  $\Phi_{\mu,h}$  used to approximate  $\varphi_\mu$  satisfy the required geometric properties.

Deriving general order conditions for (7) requires to compare the Taylor expansions of both sides of  $\Psi_{N,H}(y) \simeq \varphi_\varepsilon^N(y)$ . Although conceptually easy, the task is rendered very intricate by the enormous number of terms and redundant order conditions naturally arising. Explicit conditions for standard composition methods have been obtained in a systematic way in [24] by using the formalism of  $B_\infty$ -series and trees. In the situation we consider here, the map  $\varphi_\varepsilon$  is the flow with time  $\varepsilon$  of an ODE that depends on the parameter  $\varepsilon$ , and consequently does not obey a group law. The question of approximating  $\varphi_{\varepsilon/N}^N$  by a composition of the form (7) then makes perfect sense, and this article aims at analyzing the properties and order conditions of such methods.

The paper is organized as follows. In Section 2, we derive the order conditions of the multi-revolution composition methods and perform a global error analysis of the methods. Section 3 presents several methods of orders 2 and 4, and describes how they have been obtained. Section 4 is devoted to numerical experiments aimed at giving a numerical confirmation of the orders of convergence derived in Section 2 and to show the efficiency and versatility of the newly introduced methods.

## 2 Convergence analysis of MRCMs

In this section, we derive general order conditions for method (7) to approach  $\varphi_\varepsilon^N$ . There is a complete analogy with order conditions of standard composition methods, with the exception that the right-hand side of each condition is now depending on  $N$ . Prior to addressing the general case, observe that the simplest method  $\varphi_H \simeq \varphi_\varepsilon^N$  with  $H = N\varepsilon$ , corresponds to  $s = 1$ ,  $\alpha_1 = 1$  and  $\beta_1 = 0$ . As shown in introduction, we have that

$$\varphi_H(y) - z(H) = \mathcal{O}(H^2), \quad \varphi_\varepsilon^N(y) - z(H) = \mathcal{O}(\varepsilon H),$$

as  $H = \varepsilon N \rightarrow 0$ , where  $z(t)$  is the solution of the initial value problem (3)–(4). Hence,  $\varphi_H$  has, as an approximation to  $\varphi_{H/N}^N$ , (global) order 1 in the following sense

$$\|\varphi_H(y) - \varphi_\varepsilon^N(y)\| \leq CH^2 \text{ for all } 0 \leq H = N\varepsilon \leq H_0.$$

Constructing high-order compositions soon becomes rather intricate, not to say undoable, unless one uses an appropriate methodology. This is precisely the object of the paper [24] which gives order conditions for standard composition methods explicitly. We will hereafter follow the presentation of [15]. The starting point of this section is the Taylor series expansion<sup>1</sup>

$$\varphi_\varepsilon(y) = y + \varepsilon d_1(y) + \varepsilon^2 d_2(y) + \varepsilon^3 d_3(y) + \dots \quad (17)$$

of the smooth map (1).

## 2.1 Preliminaries: trees and $B_\infty$ series

In this subsection, we briefly recall the framework of  $B_\infty$ -series for the study of composition methods of the form

$$\varphi_{\alpha_s \varepsilon} \circ \varphi_{\beta_s \varepsilon}^* \circ \dots \circ \varphi_{\alpha_1 \varepsilon} \circ \varphi_{\beta_1 \varepsilon}^*(y) \quad (18)$$

originally developed for the numerical integration of equation (3) and yet completely relevant to the present situation. We thus define  $T_\infty$  as the set of rooted trees where each vertex bears a positive integer and we denote  $\textcircled{1}, \textcircled{2}, \textcircled{3}, \dots$  the trees with one vertex. Given  $\tau_1, \dots, \tau_m \in T_\infty$ , we write as

$$\tau = [\tau_1, \dots, \tau_m]_j \quad (19)$$

the tree obtained by attaching the  $m$  roots of  $\tau_1, \dots, \tau_m$  to a new root with label  $j$ . Incidentally, we define  $i(\tau) = j$  the label beard by its root,  $|\tau| = 1 + |\tau_1| + \dots + |\tau_m|$  its number of vertices,  $\|\tau\| = i(\tau) + \|\tau_1\| + \dots + \|\tau_m\|$  the sum of its labels<sup>2</sup> and  $\sigma(\tau) = \mu_1! \mu_2! \dots \sigma(\tau_1) \dots \sigma(\tau_m)$  its symmetry coefficient, where  $\mu_1, \mu_2, \dots$  count equal trees among  $\tau_1, \dots, \tau_m$ . Now, the  $B_\infty$ -series associated to a map  $a : T_\infty \cup \{\emptyset\} \rightarrow \mathbb{R}$  is the formal series

$$B_\infty(a, \varepsilon, y) = a(\emptyset)y + \sum_{\tau \in T_\infty} \frac{\varepsilon^{|\tau|}}{\sigma(\tau)} a(\tau) F(\tau)(y)$$

where the so-called “elementary differentials” are maps from  $\mathcal{U}$  to  $\mathbb{R}^d$  defined inductively by the relations

$$\begin{aligned} F(\textcircled{j})(y) &= d_j(y), \\ F([\tau_1, \dots, \tau_m]_j)(y) &= d_j^{(m)}(y)(F(\tau_1)(y), \dots, F(\tau_m)(y)). \end{aligned}$$

We immediately see that the Taylor expansion (17) of  $\varphi_\varepsilon$  can be considered as a  $B_\infty$ -series

$$\varphi_\varepsilon(y) = y + \varepsilon d_1(y) + \varepsilon^2 d_2(y) + \varepsilon^3 d_3(y) + \dots = B_\infty(e_1, \varepsilon, y)$$

<sup>1</sup>Notice that  $d_1(y) = \Theta_0(y)$ .

<sup>2</sup>By convention,  $|\emptyset| = \|\emptyset\| = 0$ .



with coefficients satisfying  $e_1(\tau) = 0$  for all  $\tau \in T_\infty$  with  $|\tau| > 1$  and  $e_1(\emptyset) = 1$ ,  $e_1(\textcircled{j}) = 1$  for all  $j \in \mathbb{N}^*$ . As immediate is the obtention of the coefficients of the B-series expansion of the exact solution  $z(\varepsilon)$  of (3)

$$B_\infty(e_\infty, \varepsilon, y) = z(\varepsilon)$$

with coefficients  $e_\infty(\tau)$  recursively defined<sup>3</sup> by

$$e_\infty(\emptyset) = 1, \quad e_\infty(\tau) = \frac{1}{|\tau|} e'_\infty(\tau) \text{ if } i(\tau) = 1, \text{ and } e_\infty(\tau) = 0 \text{ otherwise,} \quad (20)$$

where the prime stands for the following B-series operation: Given  $a : \mathcal{T}_\infty \rightarrow \mathbb{R}$ , the map  $a'$  is defined recursively by

$$a'(\textcircled{j}) = 1 \text{ and for all } \tau = [\tau_1, \dots, \tau_m]_j \in \mathcal{T}_\infty, \quad a'(\tau) = a(\tau_1) \cdots a(\tau_m).$$

We now quote the following fundamental result from [24]:

**Lemma 2.1.** *The following compositions are  $B_\infty$ -series*

$$\begin{aligned} \varphi_{\beta_k \varepsilon}^* \circ \cdots \circ \varphi_{\alpha_1 \varepsilon} \circ \varphi_{\beta_1 \varepsilon}^*(y) &= B_\infty(b_k, \varepsilon, y) \\ \varphi_{\alpha_k \varepsilon} \circ \varphi_{\beta_k \varepsilon}^* \circ \cdots \circ \varphi_{\alpha_1 \varepsilon} \circ \varphi_{\beta_1 \varepsilon}^*(y) &= B_\infty(a_k, \varepsilon, y) \end{aligned}$$

with coefficients given recursively for all  $T \in \mathcal{T}_\infty$  by  $a_k(\emptyset) = b_k(\emptyset) = 1$ ,  $a_0(\tau) = 0$  and

$$b_k(\tau) = a_{k-1}(\tau) - (-\beta_k)^{i(\tau)} b'_k(\tau) \text{ and } a_k(\tau) = b_k(\tau) + \alpha_k^{i(\tau)} b'_k(\tau).$$

In order to eliminate redundant order conditions, we finally fix as in [24] a total order relation  $<$  on  $T_\infty$  compatible with  $|\cdot|$ , i.e. such that  $u < v$  whenever  $|u| < |v|$ .

**Definition 2.2.** (Hall Set). *The Hall set corresponding to the order relation  $<$  is the subset  $H \subset T_\infty$  defined by*

- (i)  $\forall j \in \mathbb{N}, \textcircled{j} \in H$
- (ii)  $\tau \in H$  if and only if there exist  $u, v \in H, u > v$ , such that  $\tau = u \circ v$ .

**Theorem 2.3.** (Murua and Sanz-Serna [24]) *Consider  $B(a, \varepsilon, y)$  and  $B(b, \varepsilon, y)$  two  $B_\infty$ -series obtained as compositions of the form (18) and let  $p \geq 1$ . The following two statements are equivalent:*

- (i)  $\forall \tau \in T_\infty, \|\tau\| \leq p, a(\tau) = b(\tau)$ ,
- (ii)  $\forall \tau \in \mathcal{H}, \|\tau\| \leq p, a(\tau) = b(\tau)$ .

In the usual setting of composition methods, the previous theorem immediately gives the reduced number of order conditions for order  $p$  by comparing the  $B_\infty$ -series  $B_\infty(a, \varepsilon, y)$  obtained from (18) and  $B_\infty(e_\infty, \varepsilon, y)$ . In our context, we have to compare  $B_\infty(a, \varepsilon, y)$  with the  $B_\infty$ -series of  $\varphi_\varepsilon^N$ . This is the purpose of the next section.

Order 1:	①	$\sum_{k=1}^s (\alpha_k + \beta_k) = 1$
Order 2:	②	$\sum_{k=1}^s (\alpha_k^2 - \beta_k^2) = N^{-1}$
Order 3:	③	$\sum_{k=1}^s (\alpha_k^3 + \beta_k^3) = N^{-2}$
	① ②	$\sum_{k=1}^s (\alpha_k^2 - \beta_k^2) \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) = \frac{N^{-1} - N^{-2}}{2}$
Order 4:	④	$\sum_{k=1}^s (\alpha_k^4 - \beta_k^4) = N^{-3}$
	① ③	$\sum_{k=1}^s (\alpha_k^3 + \beta_k^3) \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) = \frac{N^{-2} - N^{-3}}{2}$
	① ① ②	$\sum_{k=1}^s (\alpha_k^2 - \beta_k^2) \left( \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) \right)^2 = \frac{N^{-1}(1 - N^{-1})(2 - N^{-1})}{6}$
Order 5:	⑤	$\sum_{k=1}^s (\alpha_k^5 + \beta_k^5) = N^{-4}$
	① ④	$\sum_{k=1}^s (\alpha_k^4 - \beta_k^4) \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) = \frac{N^{-3} - N^{-4}}{2}$
	② ③	$\sum_{k=1}^s (\alpha_k^3 + \beta_k^3) \sum_{\ell=1}^k (\alpha_\ell^2 - \beta_\ell^2) = \frac{N^{-3} - N^{-4}}{2}$
	① ②	$\sum_{k=1}^s (\alpha_k^2 - \beta_k^2) \left( \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) \right) \left( \sum_{\ell=1}^k (\alpha_\ell^2 - \beta_\ell^2) \right) = \frac{N^{-2}(1 - N^{-1})(2 - N^{-1})}{6}$
	① ① ① ②	$\sum_{k=1}^s (\alpha_k^2 - \beta_k^2) \left( \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) \right)^3 = \frac{N^{-1}(1 - N^{-1})^2}{4}$
	① ① ③	$\sum_{k=1}^s (\alpha_k^3 + \beta_k^3) \left( \sum_{\ell=1}^k (\alpha_\ell + \beta_\ell) \right)^2 = \frac{N^{-2}(1 - N^{-1})(2 - N^{-1})}{6}$

Table 1: Fifth-order conditions for MRCMs. The prime attached to a summation symbol indicates that the sum of  $\alpha_\ell^j$  is only from 1 to  $k - 1$  while the sum of  $\beta_\ell^j$  remains for 1 to  $k$

## 2.2 Semi-discrete error analysis

Observe that by taking  $\alpha_i = N^{-1}, \beta_i = 0, i = 1, \dots, N$  in (18) Lemma 2.1 immediately yields that the composition  $(\varphi_{\varepsilon/N})^N(y)$  is again a  $B_\infty$ -series

$$B_\infty(e_N, \varepsilon, y) \mathfrak{F} (\varphi_{\varepsilon/N})^N(y). \quad (21)$$

<sup>3</sup>Notice that  $e_\infty(\tau) = 0$  if at least one of its labels is different from 1.

Its coefficients  $e_N(\tau)$  can be computed by using the following lemma.

**Lemma 2.4.** *For all  $N \in \mathbb{N}^*$ , the coefficients  $e_N(\tau)$  of the  $B_\infty$ -series in (21) satisfy*

$$\begin{aligned} \forall j \in \mathbb{N}^*, \quad e_N(\textcircled{j}) &= N^{1-j}, \\ \forall \tau = [\tau_1, \dots, \tau_n]_j \in \mathcal{T}_\infty, \quad N^{\|\tau\|} e_N(\tau) &= \sum_{k=1}^{N-1} k^{\|\tau_1\| + \dots + \|\tau_n\|} e'_k(\tau). \end{aligned}$$

*Proof.* With  $\alpha_i = 1$  and  $\beta_i = 0$ ,  $i = 1, \dots, N$ , Lemma 2.1 gives  $b_k(\tau) = a_{k-1}(\tau)$  and thus

$$a_N(\tau) = \sum_{k=1}^N a'_{k-1}(\tau) = \sum_{k=1}^{N-1} a'_k(\tau).$$

Using  $B_\infty(e_N, \varepsilon, y) = B_\infty(a_N, \varepsilon/N, y)$  yields  $a_N(\tau) = N^{\|\tau\|} e_N(\tau)$  and allows to conclude.  $\square$

We obtain for instance  $e_N(\textcircled{1}) = 1$ ,  $e_N(\textcircled{2}) = N^{-1}$  and

$$e_N\left(\textcircled{\textcircled{1}}\right) = \frac{1 - N^{-1}}{2}, \quad e_N\left(\textcircled{\textcircled{2}}\right) = \frac{N^{-1}(1 - N^{-1})}{2}, \quad e_N\left(\textcircled{\textcircled{1}} \textcircled{\textcircled{2}}\right) = \frac{N^{-1}(1 - N^{-1})(2 - N^{-1})}{6}.$$

Now, recalling that the map  $\varphi_\varepsilon$  can be interpreted as a consistent integrator for equation (3),  $(\varphi_{\varepsilon/N})^N(y_0)$  converges to its solution  $z(\varepsilon)$  for  $N \rightarrow \infty$  and it is thus expected that the coefficients  $e_N(\tau)$  converge to  $e_\infty(\tau)$  as  $N \rightarrow \infty$ . This is shown in next proposition.

**Proposition 2.5.** *The coefficients of the  $B_\infty$ -series (21) satisfy  $e_N(\tau) \rightarrow e_\infty(\tau)$  for  $N \rightarrow \infty$ . In particular, for  $N \rightarrow \infty$  the order conditions (24) coincide with the order conditions of standard composition methods (18) for the differential equation (3).*

*Proof.* The proof is made by induction on  $|\tau|$  and is a consequence of Lemma 2.4 and (20). The result is clear for trees with one vertex using  $e_N(\textcircled{j}) = N^{1-j}$ . Given a tree  $\tau = [\tau_1, \dots, \tau_n]_j \in \mathcal{T}_\infty$ , assume that the result is true for all tree  $u \in \mathcal{T}_\infty$  with  $|u| < |\tau|$ . By the induction assumption, we have  $e_k(\tau_1) \cdots e_k(\tau_n) \rightarrow e_\infty(\tau_1) \cdots e_\infty(\tau_n)$  for  $k \rightarrow \infty$ . Using the estimate  $\sum_{k=1}^{N-1} k^\ell \sim N^{\ell+1}/(\ell+1)$  for  $N \rightarrow \infty$  with  $\ell = \|\tau_1\| + \dots + \|\tau_n\|$ , we deduce using Lemma 2.4 that  $\lim_{n \rightarrow \infty} e_N(\tau) = e_\infty(\tau_1) \cdots e_\infty(\tau_n)/(\ell+1) = e_\infty(\tau)$  for  $j = 1$ , and  $\lim_{n \rightarrow \infty} e_N(\tau) = 0 = e_\infty(\tau)$  for  $j > 1$ , which concludes the proof.  $\square$

Consider now the  $B_\infty$ -series  $B_\infty(a, \varepsilon, y)$  associated to a semi-discrete MRCM of the form (7) with  $H = \varepsilon$ . Writing the order conditions now boils down to comparing the coefficients of  $B_\infty(a, \varepsilon, y)$  and  $B_\infty(e_N, \varepsilon, y)$  and estimating the remainder term. Next lemma provides estimates of the derivatives of  $\varphi_\varepsilon^N$  w.r.t.  $\varepsilon$ . In order to alleviate the presentation, let us denote for  $\rho > 0$ ,  $B_\rho(y_0) = \{y \in \mathbb{R}^d; \|y - y_0\| \leq \rho\}$ , and for a given function  $y \mapsto k(y)$  defined on  $B_\rho(y_0)$ ,

$$\|k\|_\rho := \sup_{y \in B_\rho(y_0)} \|k(y)\| \quad \text{and} \quad \|\partial_y^n k\|_\rho := \sup_{\substack{y \in B_\rho(y_0), \\ \|v_i\| = 1, i = 1, \dots, n}} \|\partial_y^n k_\varepsilon(y)(v_1, \dots, v_n)\|.$$

Note that if  $(y, \varepsilon) \mapsto \Theta_\varepsilon(y)$  in (1) is of class  $C^{p+1}$  with respect to  $(y, \varepsilon)$  on the compact set  $B_\rho(y_0) \times [-\varepsilon_0, \varepsilon_0]$ , then there exist positive constants  $K$  and  $L$  such that, for all  $|\varepsilon| \leq \varepsilon_0$

$$\begin{aligned} \|\partial_y \varphi_\varepsilon\|_\rho &\leq 1 + \varepsilon L, & \forall k = 2, \dots, p+1, & \quad \|\partial_y^k \varphi_\varepsilon\|_\rho \leq \varepsilon L, \\ \forall 0 \leq k+l \leq p+1, & \quad \|\partial_y^k \partial_\varepsilon^l \varphi_\varepsilon\|_\rho \leq K. \end{aligned}$$

**Lemma 2.6.** *Assume that  $(y, \varepsilon) \mapsto \Theta_\varepsilon(y)$  is defined and of class  $C^{p+1}$  with respect to  $(y, \varepsilon)$  on  $B_{2R}(y_0) \times [-\varepsilon_0, \varepsilon_0]$  for a given  $R > 0$  and a given  $\varepsilon_0 > 0$ . Then, there exists a constant  $H_0$  such that for all  $\varepsilon$  and  $N \geq 1$  with  $H = N\varepsilon \leq H_0$ ,*

$$\|\partial_\varepsilon^{p+1} \varphi_\varepsilon^N\|_R \leq CN^{p+1}, \quad \left\| \partial_H^{p+1} \varphi_{H/N}^N \right\|_R \leq C, \quad (22)$$

where  $C$  is independent of  $N$  and  $\varepsilon$ .

*Proof.* For  $\tilde{y}_0 \in B_R(y_0)$  and denoting  $M := \sup_{|\varepsilon| \leq \varepsilon_0} \|\Theta_\varepsilon\|_{2R}$ , we have

$$\|\varphi_\varepsilon^N(\tilde{y}_0) - y_0\| \leq \sum_{k=1}^N \|\varphi_\varepsilon^k(\tilde{y}_0) - \varphi_\varepsilon^{k-1}(\tilde{y}_0)\| + \|\tilde{y}_0 - y_0\| \leq R + N\varepsilon M$$

as long as the iterates  $\varphi_\varepsilon^i(\tilde{y}_0)$  and  $\varphi_\varepsilon^i(y_0)$  remain in  $B_{2R}(y_0)$  for  $0 \leq i \leq N$ . Hence, if  $N\varepsilon \leq H_0 := \min(R/M, \varepsilon_0)$  then  $\|\varphi_\varepsilon^k\|_R \leq 2R$  for all  $k = 0, \dots, N$ . Under this assumption, we now wish to prove by induction on  $n$ , that

$$\forall n = 1, \dots, p+1, \quad \|\partial_\varepsilon^n \varphi_\varepsilon^N\|_R \leq C_n N^n \quad (23)$$

for some constants  $C_n$  independent of  $N, \varepsilon$ . Now, given a smooth function  $g : B_{2R}(y_0) \rightarrow \mathbb{R}^d$  of class  $C^{p+1}$ , Faà di Bruno's formula reads

$$\partial_\varepsilon^k (g \circ \varphi_\varepsilon^N) = \sum_{\mathbf{m} \in \mathbb{N}^k, \sigma(\mathbf{m})=k} B_{\mathbf{m}} g^{(|\mathbf{m}|)} \circ \varphi_\varepsilon^N \left( (\partial_\varepsilon^1 \varphi_\varepsilon^N)^{m_1}, \dots, (\partial_\varepsilon^k \varphi_\varepsilon^N)^{m_k} \right)$$

where the sum is over all multi-indices  $\mathbf{m} = (m_1, \dots, m_k)$  of  $\mathbb{N}^k$  such that  $k = \sigma(\mathbf{m}) := \sum_{j=1}^k j m_j$  and where  $|\mathbf{m}|$  denotes  $m_1 + \dots + m_k$  and

$$B_{\mathbf{m}} = \frac{k!}{m_1! 1!^{m_1} \dots m_k! k!^{m_k}}.$$

We now use the differentiation formula

$$\partial_\varepsilon^n (\varphi_\varepsilon \circ \varphi_\varepsilon^N) = \sum_{k=0}^n \frac{n!}{k!(n-k)!} \partial_\varepsilon^k (\partial_\mu^{(n-k)} \varphi_\mu \circ \varphi_\varepsilon^N) \Big|_{\mu=\varepsilon}$$

and take  $g = \partial_\mu^{(n-k)} \varphi_\mu \Big|_{\mu=\varepsilon}$  in Faa di Bruno's formula. This yields

$$\partial_\varepsilon^n (\varphi_\varepsilon^{N+1}) = \sum_{\substack{0 \leq k \leq n, \\ \mathbf{m} \in \mathbb{N}^k, \sigma(\mathbf{m})=k}} \frac{n!}{k!(n-k)!} B_{\mathbf{m}} \left( \partial_y^{|\mathbf{m}|} \partial_\varepsilon^{n-k} \varphi_\varepsilon \right) \circ \varphi_\varepsilon^N \left( (\partial_\varepsilon^1 \varphi_\varepsilon^N)^{m_1}, \dots, (\partial_\varepsilon^n \varphi_\varepsilon^N)^{m_n} \right)$$

Hence, using the induction assumption, we get the estimates

$$\begin{aligned}
\|\partial_\varepsilon^n \varphi_\varepsilon^{N+1}\|_R &\leq \|\partial_\varepsilon^n \varphi_\varepsilon\|_{2R} + \sum_{\substack{1 \leq k \leq n-1, \\ \mathbf{m} \in \mathbb{N}^k, \sigma(\mathbf{m})=k}} \frac{n!}{k!(n-k)!} B_{\mathbf{m}} \|\partial_y^{|\mathbf{m}|} \partial_\varepsilon^{n-k} \varphi_\varepsilon\|_{2R} \prod_{j=1}^k \|\partial_\varepsilon^j \varphi_\varepsilon^N\|_R^{m_j} \\
&\quad + \sum_{\mathbf{m} \in \mathbb{N}^n, \sigma(\mathbf{m})=n, m_n=0} B_{\mathbf{m}} \|\partial_y^{|\mathbf{m}|} \varphi_\varepsilon\|_{2R} \prod_{j=1}^n \|\partial_\varepsilon^j \varphi_\varepsilon^N\|_R^{m_j} + \|\partial_y \varphi_\varepsilon\|_{2R} \|\partial_\varepsilon^n \varphi_\varepsilon^N\|_R \\
&\leq K + K\tilde{C}_n \sum_{k=1}^{n-1} N^k + \varepsilon n \hat{C}_n L N^n + (1 + \varepsilon L) \|\partial_\varepsilon^n \varphi_\varepsilon^N\|_R \\
&\leq nK\tilde{C}_n (N+1)^{n-1} + n\hat{C}_n L H_0 N^{n-1} + (1 + \varepsilon L) \|\partial_\varepsilon^n \varphi_\varepsilon^N\|_R \\
&\leq \bar{C}_n (N+1)^{n-1} + (1 + \varepsilon L) \|\partial_\varepsilon^n \varphi_\varepsilon^N\|_R
\end{aligned}$$

where the constants  $\tilde{C}_n$  and  $\hat{C}_n$  are defined as

$$\tilde{C}_n = \max_{k=1, \dots, n-1} \sum_{\substack{\mathbf{m} \in \mathbb{N}^k \\ \sigma(\mathbf{m})=k}} B_{\mathbf{m}} \prod_{j=1}^k C_j^{m_j} \quad \text{and} \quad \hat{C}_n = \sum_{\substack{\mathbf{m} \in \mathbb{N}^{n-1} \\ \sigma(\mathbf{m})=n}} B_{\mathbf{m}} \prod_{j=1}^{n-1} C_j^{m_j}$$

and  $\bar{C}_n = n \max(K, K\tilde{C}_n, \hat{C}_n L H_0)$ . Finally, using a standard discrete Gronwall lemma and  $H = N\varepsilon \leq H_0$  yields

$$\|\partial_\varepsilon^n (\varphi_\varepsilon^N)\|_R \leq \bar{C}_n \sum_{k=1}^N (1 + \varepsilon L)^{N-k} k^{n-1} \leq \bar{C}_n N^n e^{L\varepsilon N} \leq \bar{C}_n N^n e^{LH_0}$$

which allows to conclude the proof of the first estimate in (22) by choosing  $C_n = \bar{C}_n e^{LH_0}$  in (23). The second estimate is straightforwardly obtained through a change of variables.  $\square$

We may now state the main result for the local error of the semi-discrete MRCM (7).

**Theorem 2.7.** *Consider a semi-discrete MRCM (7) and assume further that its coefficients  $\alpha_i(N)$ ,  $\beta_i(N)$ ,  $i = 1, \dots, s$  are bounded with respect to  $N$  for all  $N \geq N_0$  and satisfy*

$$a(\tau) = e_N(\tau), \quad \text{for all } \tau \in \mathcal{H} \text{ with } \|\tau\| \leq p, \quad (24)$$

for a given order  $p \geq 1$ . Then, for all  $H \leq H_0$ ,  $N \geq N_0$ ,

$$\|\Psi_{N,H} - (\varphi_\varepsilon)^N\|_R \leq C H^{p+1}$$

where  $H = N\varepsilon$  and the constant  $C$  is independent of  $N, \varepsilon$ .

*Proof.* Consider the two  $B_\infty$ -series  $B_\infty(a, H, y)$  and  $B_\infty(e_N, H, y)$  associated respectively to the semi-discrete MRCM (7) and to  $\varphi_{H/N}^N(y)$  in (21). It follows from Theorem 2.3 that these  $B_\infty$ -series formally coincide up to order  $H^p$ . A Taylor expansion of  $\Psi_H(y) - (\varphi_{H/N}^N)^N(y)$  with integral remainder thus leads to

$$\Psi_{N,H}(y) - (\varphi_{H/N}^N)^N(y) = \int_0^H \frac{1}{p!} (H-s)^p \frac{\partial^{p+1} \Psi_s}{\partial s^{p+1}}(y) ds - \int_0^H \frac{1}{p!} (H-s)^p \frac{\partial^{p+1} \varphi_{s/N}^N}{\partial s^{p+1}}(y) ds.$$

The derivative  $\frac{\partial^{p+1}\varphi_{s/N}^N}{\partial s^{p+1}}$  is bounded by Lemma 2.6. Given that coefficients  $\alpha_j, \beta_j$  are uniformly bounded with respect to  $N$ ,  $\frac{\partial^{p+1}\Psi_s}{\partial s^{p+1}}$  is bounded as well. We conclude using  $(\varphi_{H/N})^N(y) = (\varphi_\varepsilon)^N(y)$ .  $\square$

We report in Table 1 order conditions up to order 5 as derived above. Note that Lemma 2.4 implies (by induction) that the value of  $N^{\|\tau\|}e_N(\tau)$  is independent of the labels of the nodes of a given tree  $\tau \in \mathcal{T}_\infty$ . This explains why similar right-hand sides  $e_N(\tau)$  are obtained for trees where only labels differ. An immediate consequence of Proposition 2.5 is the following remark.

**Remark 2.8.** *Notice that for  $N \rightarrow \infty$ , the order conditions (24) reduce to the classical order conditions of standard composition methods (18) for the approximation of the flow of (3).*

### 2.3 Fully-discrete error analysis

In this subsection, we derive convergence estimates for fully-discrete MRCMs (16). We highlight once again that this is essential in view of applications because the exact computation of the map  $\varphi_\varepsilon$  is not available in general and has to be approximated by a map  $\Phi_{h,\varepsilon}$ .

**Theorem 2.9.** *Assume that the hypotheses of Theorem 2.7 are fulfilled. Consider a fully-discrete MRCM (16) where the basic map  $\Phi_{h,\varepsilon}$  is assumed to satisfy the accuracy estimate (15) for given  $q$  and  $r$ . Then*

$$\|\Psi_{N,H,h} - (\varphi_\varepsilon)^N\|_R \leq C(H^{p+1} + H^r h^q)$$

where  $H = N\varepsilon$ ,  $h \leq \varepsilon$  and the constant  $C$  is independent of  $N, \varepsilon, H, h$ .

As a consequence of Theorem 2.9, by standard arguments in the convergence analysis of one-step integrators, one gets a global error estimate for the numerical approximations  $y_m = \Psi_{N,H,h}(y_{m-1})$  of problem (9) of the form

$$y_m - y(mH) = \mathcal{O}(H^p + H^{r-1}h^q) \quad \text{for } mH \leq T.$$

For the proof of Theorem 2.9, we recall the following classical discrete Gronwall estimate.

**Lemma 2.10.** *Let  $(\phi_j, \psi_j), j = 1, \dots, k$ , be  $k$  couples of maps satisfying for  $\rho, \nu > 0$*

$$\|\phi_j(y) - \psi_j(y)\| \leq \rho, \quad \|\phi_j(y_1) - \phi_j(y_2)\| \leq (1 + \nu)\|y_1 - y_2\|,$$

for all  $j = 1, \dots, k$  and all  $y, y_1, y_2$ . Then,

$$\|\phi_k \circ \dots \circ \phi_1(y) - \psi_k \circ \dots \circ \psi_1(y)\| \leq e^{\nu k} k \rho.$$

*Proof.* Let  $a_j = \phi_k \circ \dots \circ \phi_{k-j+1}$ ,  $b_j = \psi_j \circ \dots \circ \psi_1$ . We have

$$\begin{aligned} a_k(y) - b_k(y) &= \sum_{j=0}^{k-1} a_{k-j-1} \circ \phi_{j+1} \circ b_j(y) - a_{k-j-1} \circ \psi_j \circ b_j(y) \\ \|a_k(y) - b_k(y)\| &\leq \sum_{j=0}^{k-1} (1 + \nu)^{k-j-1} \|\phi_{j+1} \circ b_j(y) - \psi_{j+1} \circ b_j(y)\| \leq k e^{\nu k} \rho \end{aligned}$$

where we used the estimate  $\sum_{j=0}^{k-1} (1 + \nu)^{k-j-1} \leq \sum_{j=0}^{k-1} e^{\frac{j}{k}\nu k} \leq k \int_0^1 e^{\nu kt} dt \leq k e^{\nu k}$ .  $\square$

*Proof of Theorem 2.9.* We use the estimate

$$\|\Psi_{N,H,h} - (\varphi_\varepsilon)^N\|_R \leq \|\Psi_{N,H,h} - \Psi_{N,H}\|_R + \|\Psi_{N,H} - (\varphi_\varepsilon)^N\|_R$$

From Theorem 2.7, we have  $\|\Psi_{N,H} - (\varphi_\varepsilon)^N\|_R \leq CH^{p+1}$ . The next estimate

$$\|\Psi_{N,H,h} - \Psi_{N,H}\|_R \leq CH^r h^q$$

is a consequence of Lemma 2.10 with  $k = 2s$ ,  $\rho = CH^r h^q$  (using (15) with  $\varepsilon$  replaced by  $\alpha_j(N)H$  and  $\beta_j(N)H$ ),  $\nu = \mathcal{O}(\varepsilon)$  being a Lipsitz constant for the near-identity map  $\varphi_\varepsilon$ , and  $\phi_{2j-1} = \varphi_{\alpha_j(N)H}$ ,  $\phi_{2j} = \varphi_{\beta_j(N)H}^*$ ,  $\psi_{2j-1} = \Phi_{h,\alpha_j(N)H}$ ,  $\psi_{2j} = \Phi_{h,\beta_j(N)H}^*$ .  $\square$

### 3 Effective construction of MRCMs

The simplest method of order 1 is obtained simplify for  $s = 1$ ,  $\alpha_1 = 1$ ,  $\beta_1 = 0$  in (18),

$$\varphi_H(y) = \varphi_\varepsilon^N(y) + \mathcal{O}(H^2).$$

For order 2, there exist a unique solution with  $s = 1$ , given by  $\alpha_1 = (1 + N^{-1})/2$  and  $\beta_1 = (1 - N^{-1})/2$ ,

$$\varphi_{\alpha_1 H} \circ \varphi_{-\beta_1 H}^{-1}(y) = \varphi_{(H+\varepsilon)/2} \circ \varphi_{-(H-\varepsilon)/2}^{-1}(y) = \varphi_\varepsilon^N(y) + \mathcal{O}(H^3).$$

For order 3, there do not exist real solutions with  $s = 2$ . We directly consider order 4, for which there are 7 order conditions to be satisfied. It turns out that there exists a family of solutions with  $s = 3$ , i.e. with only 6 free parameters  $\alpha_j, \beta_j$ . We consider the following solution for  $N = \infty$  given by with

$$\alpha_1 = \beta_1 = \alpha_3 = \beta_3 = \frac{1}{4 - 2 \cdot 2^{1/3}}, \quad \alpha_2 = \beta_2 = \frac{1}{2} - 2\alpha_1.$$

The idea is then to set  $\delta = 1/N$  and to search for continuous function  $\alpha_j(\delta^{-1}), \beta_j(\delta^{-1})$  defined for  $\delta \in [0, N_0^{-1}]$  and which coincide with the above coefficients for  $\delta = 0$ . This calculation is made by a continuation method.

However, it is known that for standard composition methods ( $N = \infty$ ), the composition methods with minimal number of compositions are not the most efficient in general. We thus increment the parameter  $s$  and construct a family of MRCMs of order  $p = 4$  with  $s = 4$  where we choose to minimize the sum of the squares of the coefficients. This yields the following optimization problem with constraints: find  $\delta \mapsto (\alpha_i(\delta^{-1}), \beta_i(\delta^{-1})), i = 1, \dots, s$  minimizing  $\sum_{k=1}^s (\alpha_k(\delta^{-1})^2 + \beta_k(\delta^{-1})^2)$  and fulfilling the order conditions up to order  $p$ . This is done using a standard optimization package. For a practical implementation, we consider a set of  $K = 33$  Chebyshev points  $\delta_k, k = 1, \dots, K$  sampling the interval  $[0, N_0^{-1}]$  and for which we compute the corresponding coefficients  $\alpha_k(\delta_k^{-1}), \beta_k(\delta_k^{-1}), k = 1, \dots, k$ . This calculation is made once for all and stored. We then use Chebyshev interpolation to recover the coefficients  $\alpha_i, \beta_i$  for any value of  $\delta = 1/N \in [0, N_0^{-1}]$ . The number  $K$  of sample points has been chosen to guaranty that the Chebyshev interpolation error is smaller than the machine precision.

**Remark 3.1.** Notice that multi-revolution composition methods with complex coefficients can also be considered (see [6, 16] in the context of standard composition methods). For instance, the fourth order conditions to achieve order 3 for a multi-revolution composition method have a complex solution for  $s = 2$ , given for all  $N \geq 2$  by:

$$\alpha_1(N) = \overline{\alpha_2(N)} = \frac{1}{4} + \frac{1}{2N} + i\frac{\sqrt{3-12/N^2}}{12}, \quad \beta_1(N) = \overline{\beta_2(N)} = \frac{1}{4} - \frac{1}{2N} + i\frac{\sqrt{3-12/N^2}}{12}.$$

## 4 Numerical experiments

The aim of this part is to obtain a numerical confirmation of the orders of convergence given above and to demonstrate the efficiency of MRCMs. The first problem, which is a modification of the Fermi-Pasta-Ulam problem [12], is directly of the form (9) and serves classically in the literature as a test problem to measure the error behavior of the various

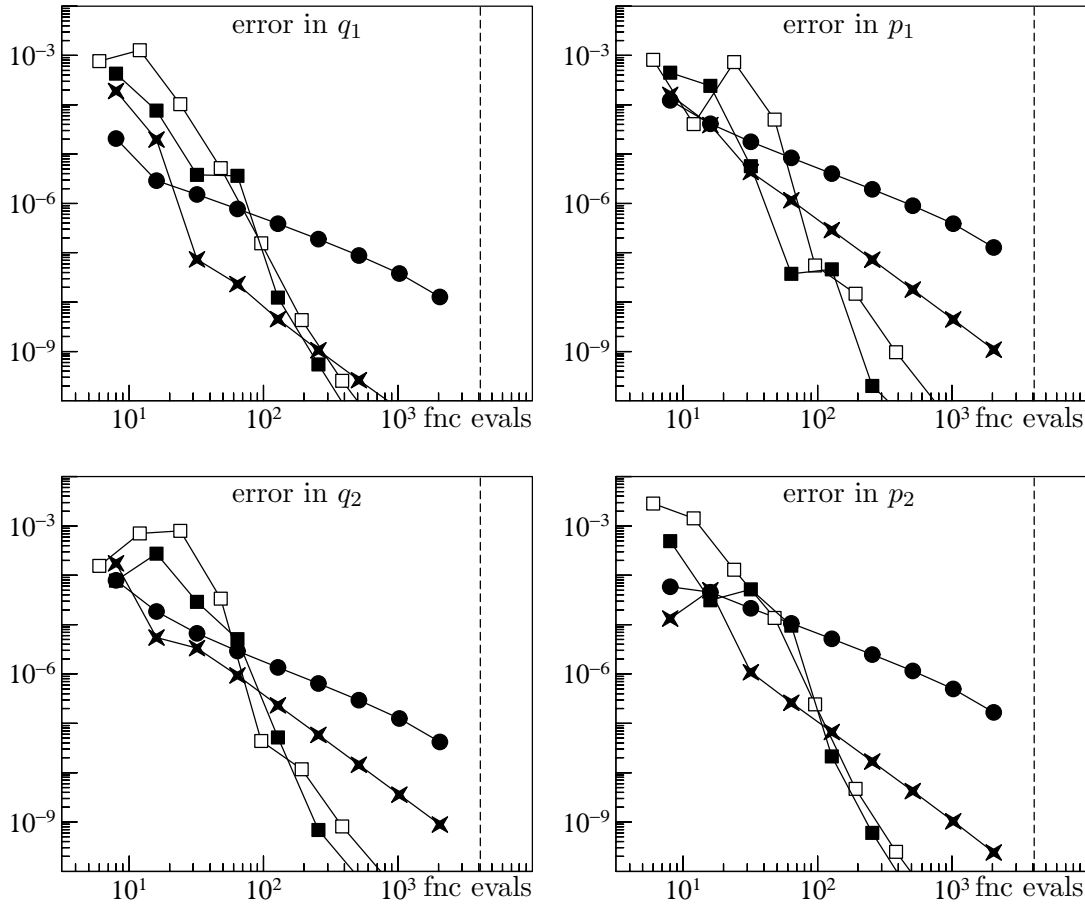


Figure 1: Problem (25) with  $\eta = 2^{-12}$  and initial conditions (27). Errors of multi-revolution composition methods at time  $t = 2\pi$  as functions of the number of evaluations of  $\varphi_\mu$  (for many values of the parameter  $N$ ). Methods of orders 1 (circles), 2 (stars), 4 ( $s = 3$  with white squares), 4 ( $s = 4$  with black squares).



methods for integrating single-frequency highly oscillatory systems. The second test problem is borrowed from the PDE literature and requires to be discretized with a spectral method: we aim with this example at illustrating the qualitative properties of MRCMs.

#### 4.1 A Fermi-Pasta-Ulam like problem

In this subsection, we consider a problem taken from [15], which is a single-frequency modification of the Fermi-Pasta-Ulam problem often used to test methods for highly-oscillatory problem. Its Hamiltonian function is given by

$$E_\eta(p, q) = \frac{1}{2} \sum_{i=1}^6 p_i^2 + \frac{1}{2\eta^2} \sum_{i=4}^6 q_i^2 + V(q), \quad (25)$$

with the quartic interaction potential

$$V(q) = \frac{1}{4}((q_1 - q_4)^4 + (q_2 - q_5 - q_1 - q_4)^4 + (q_3 - q_6 - q_2 - q_5)^4 + (q_3 + q_6)^4),$$

where  $\eta > 0$  is a small parameter.

In order to apply our MRCMs to that problem, we first rewrite the original Hamiltonian system into the format (9): we consider the family of Hamiltonian systems depending on the parameters  $\varepsilon, \eta > 0$  given as

$$H_{\varepsilon, \eta}(p, q) = \frac{2\pi}{\varepsilon} F_\eta(p, q) + 2\pi S(p, q), \quad (26)$$

where

$$F_\eta(p, q) = \frac{\eta}{2} \sum_{i=4}^6 p_i^2 + \frac{1}{2\eta} \sum_{i=4}^6 q_i^2 \quad \text{and} \quad S(p, q) = \frac{1}{2} \sum_{i=1}^3 p_i^2 + V(q).$$

Obviously, the original Hamiltonian system is recovered by considering  $\varepsilon = 2\pi\eta$ , that is

$$E_\eta(p, q) = H_{2\pi\eta, \eta}(p, q).$$

One can readily check that, for each fixed value of  $\eta$ , the family of Hamiltonian systems corresponding to the Hamiltonian functions (26) are of the form (9), with a  $12 \times 12$  matrix  $A$  having  $2\pi i$ ,  $-2\pi i$ , and 0 as the only eigenvalues. For a given value of  $\eta > 0$ , we consider the family of near-to-identity maps  $\varphi_\varepsilon$  defined as the flow with time  $\varepsilon$  of the Hamiltonian system associated to the Hamiltonian function (26). Then, the solutions  $y(t) = (p(t), q(t))$  of the original Hamiltonian problem at times  $t = 2\pi\eta M$  for integer values of  $M$  are such that  $y(2\pi\eta M) = \varphi_{2\pi\eta}^M(y(0))$ . Hence, the solution  $y(t) = (p(t), q(t))$  with a given initial value  $y(0) = y_0$  can be approximated at multiples  $t_m = mH$  of  $H = 2\pi\eta N$  as  $y(t_m) \approx \Psi_{H, h}^m(y_0)$ , where  $\Psi_{H, h}$  is a fully-discrete MRCM (16) based on some computable approximation  $\Phi_{\mu, h}$  of  $\varphi_\mu$ .

Recall that  $\varphi_\mu$  is the flow with time 1 associated to the Hamiltonian function  $\mu H_{\mu, \eta}(p, q)$ , so that a convenient choice of  $\Phi_{\mu, h}$  may be the composition of  $n$  steps of step-size  $h = 1/n$  of a splitting method applied to the splitting into fast and slow contributions

$$2\pi F_\eta(p, q; \eta) + 2\pi\mu S(p, q)$$

of the Hamiltonian  $\mu H_{\mu,\eta}(p, q)$  (so that each period of the fast term are covered with  $n$  steps of the splitting method). In all the numerical experiments we present for that example, we have considered the second order Strang splitting method iterated  $n$  times with constant stepsize  $h = 1/n$  for the definition of the basic map  $\Phi_{\varepsilon,h}$  in the fully-discrete MRCMs (16).

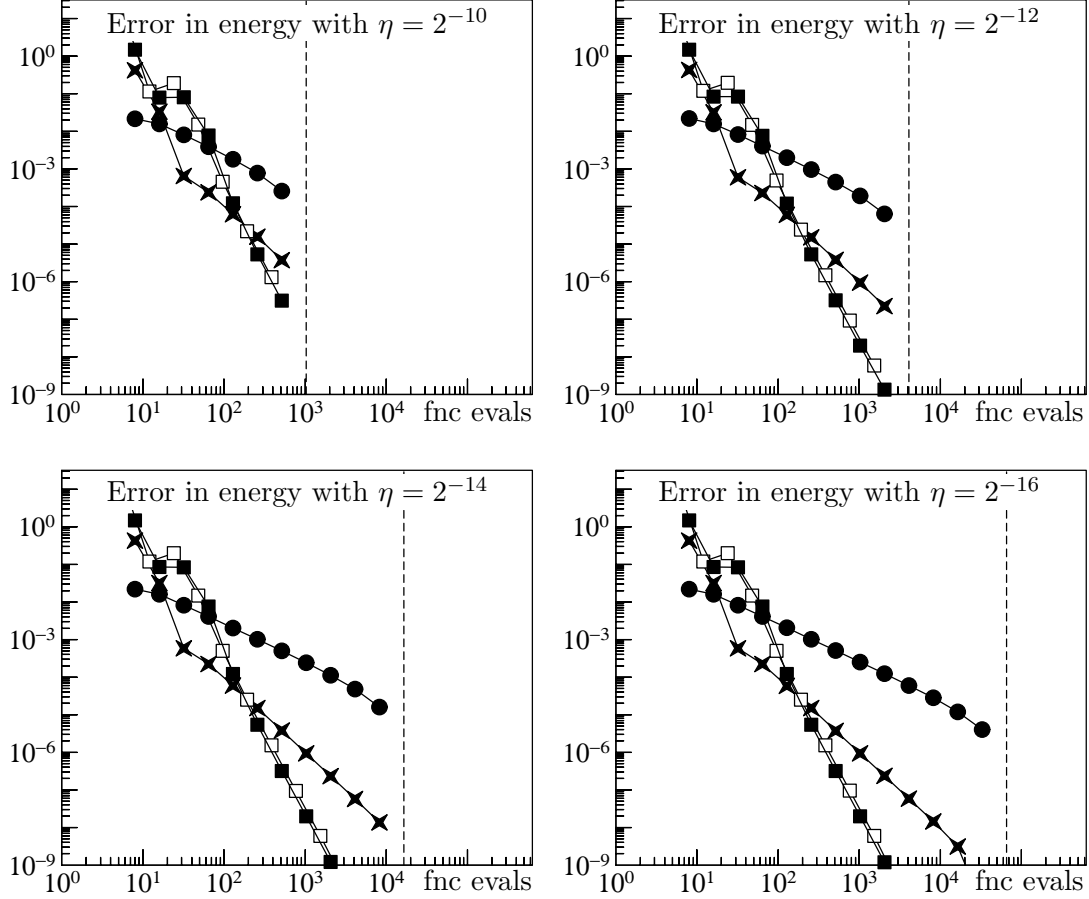


Figure 2: Problem (25) for different values of  $\eta$  and initial conditions (27). Errors in energy at time  $t = 2\pi$  versus number of evaluations of  $\varphi_\mu$ . Methods of orders 1 (circles), 2 (stars), 4 ( $s = 3$  with white squares), 4 ( $s = 4$  with black squares).

We have integrated the problem for different values of  $\eta$  with initial conditions

$$q(0) = (1, 0, 0, \eta, 0, 0)^T, \quad p(0) = (1, 0, 0, 1, 0, 0)^T \quad (27)$$

with the fully-discrete versions of the MRCMs obtained in Section (3) over  $\eta^{-2}$  periods of the stiff springs (that is, for a time interval of length  $T = 2\pi\eta^{-1}$ ). We compute the errors in positions and momenta by comparing the results with a “reference solution” computed very accurately using the Deuffhard method (see e.g. [15]) with a very small constant step size. In Figure 1, the global errors at time  $t = 2\pi$  for the components  $q_1, q_2, p_1, p_2$  versus the number of evaluations of the map  $\varphi_\mu$  (computed with a high accuracy) are displayed for the case  $\eta = 2^{-12}$ . We consider the semi-discrete MRCMs of orders 1, 2, 4 for many values of

the parameter  $N$ . We observe the expected lines of slope 1,2,4. Notice that the MRCM of order 4 with  $s = 4$  (black squares) has a better accuracy compared to the one with minimum value  $s = 3$  (white squares), as predicted in Section 3. The vertical dotted lines indicate the cost “fnc evals” =  $N$  of the naive computation  $\varphi_\eta^N$ , for which the computational advantage of MRCMs vanishes.

Analogously, in Figure 2, the error in energy is displayed for the cases  $\eta = 2^{-j}$  for  $j = 10, 12, 14, 16$ . This numerical experiment illustrates the uniform accuracy and robustness with respect to the oscillatory parameter of MRCMs.

In Figure 3, the error in energy of the approximation obtained with the fully-discrete MRCM of order 4 ( $s = 4$ ) versus the number of evaluations of  $\Phi_{\varepsilon,h}$  is displayed for different values of the micro-step  $h = 1/n$  where  $n$  is the number of steps of the Strang splitting for evaluating  $\Phi_{\varepsilon,h}$ . Here, the vertical dotted lines in all figures corresponds to  $N = \eta^{-1}$  evaluations per macro-step which corresponds to effectively computing  $\varphi_\varepsilon^N$  (or  $\Phi_{\mu,h}^N$ ) instead of applying an  $s$ -stage MRCM requiring  $2s$  evaluations of the basic map  $\Phi_{\mu,h} \approx \varphi_\mu$ . This experiment illustrates that simultaneous refinements of the macro and micro stepsizes  $H, h$  is needed for fully-discrete MRCMs to converge, as predicted by Theorem 2.9.

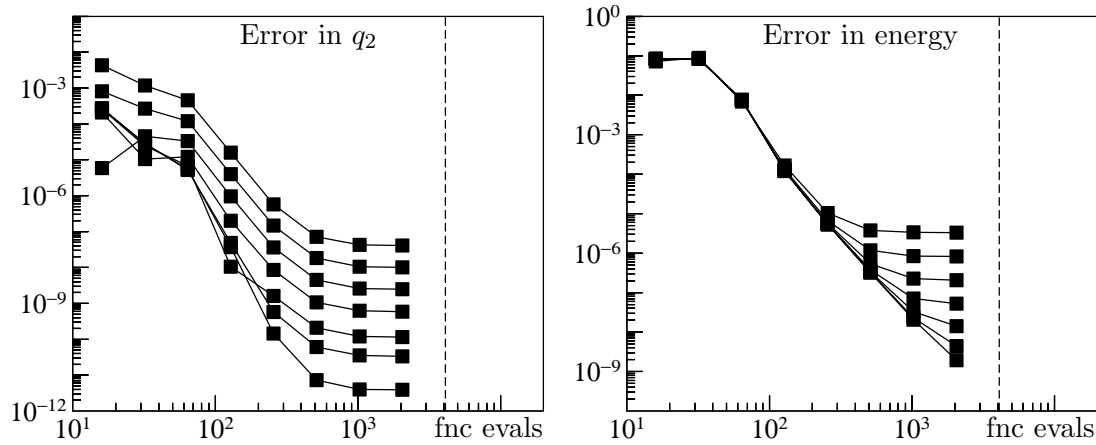


Figure 3: Multi-revolution method of order 4 ( $s = 4$ ) for the Hamiltonian (25) with  $\eta = 2^{-12}$ . Error in energy in the multi-revolution approximation versus number of evaluations of  $\Phi_{\varepsilon,h}$  approximating  $\varphi_\varepsilon$  (final time  $t = 2\pi$ ). The lines correspond respectively to  $h = 1/n = 2^{-j-1}$ ,  $j = 1, \dots, 7$  (from top to bottom).

Finally, in Figure 4, we plot, for  $\eta = 2^{-12}$ , the evolutions of the stiff spring energies

$$I_j = \frac{1}{2}p_{3+j}^2 + \frac{1}{2\eta^2}q_{3+j}^2, j = 1, 2, 3,$$

the adiabatic invariant  $I = I_1 + I_2 + I_3$  and the energy  $E_\eta(p, q) - 0.7\eta$  on a time interval of length  $T = 2\pi\eta^{-1}$  for  $\eta = 2^{-12}$ . We observe excellent energy conservation and energy exchanges for the MRCM methods of orders 1, 2, 4 compared to the reference solution. This reference solution is computed with the standard Deuffhard method with constant step size  $h = \eta$ , totalizing about  $1.1 \cdot 10^8$  steps (recall that a stepsize  $h$  comparable to the oscillatory period is needed for standard highly oscillatory integrators). In comparison, notice that

the total number of micro steps (Strang splitting) for each of the considered MRCMs is  $2snT\eta^{-1}N^{-1} \simeq 1.0 \cdot 10^6$ , which is identical in all cases due to the chosen parameters  $N, n$  and the stage number  $s$  of the MRCMs. What is striking in this experiment is that the multi-revolution composition approach yields satisfactory solutions with a computational cost reduced by two orders of magnitude compared to the standard reference integrator.

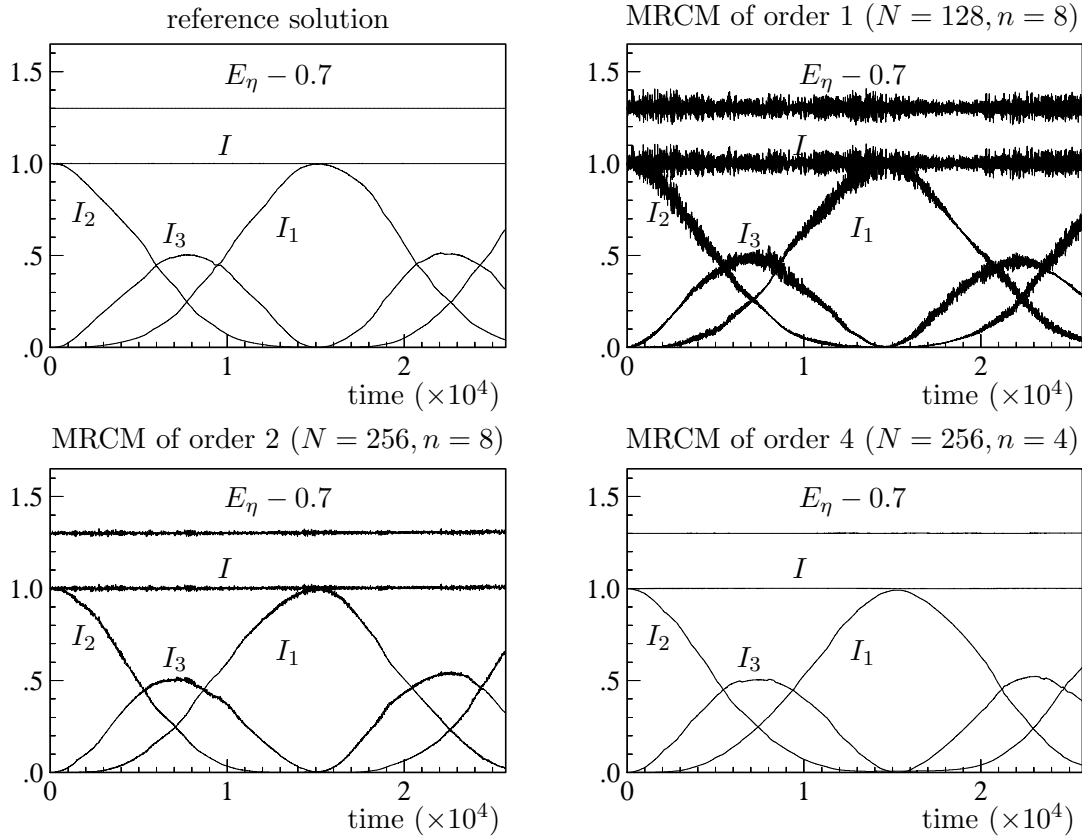


Figure 4: FPU-like problem (25) with  $\eta = 2^{-12}$ . Energy exchanges on the time interval  $(0, 2\pi\eta^{-1})$ . Multi-revolution methods of orders 1, 2, 4. Reference solution computed with constant stepsize  $h = \eta$  by the standard Deuffhard method.

**Remark 4.1.** We have applied our MRCMs to the Hamiltonian  $E_\eta(p, q)$  in (25), by considering for each value of  $\eta$ , a system of the form (9) that reduces to the original problem when  $\varepsilon = 2\pi\eta$ . This way, all the considerations made in the introduction for the application of MRCMs to systems of the form (9) apply directly to that case. Note that the considered family of near-to-identity  $\varphi_\varepsilon$  is different (although we do not reflect it in the notation) for each particular value of  $\eta$ .

This is not however the only way to use MRCMs for the numerical integration of that Hamiltonian problem. For instance, the near-to-identity map  $\varphi_\varepsilon$  could simply be defined as the flow with time  $2\pi\varepsilon$  of the Hamiltonian function  $E_\varepsilon(p, q)$ , in which case the convergence theory in Section 2 would also apply. This approach may seem attractive because the map  $\varphi_\varepsilon$  becomes symmetric with respect to  $\varepsilon$  (i.e.  $\varphi_\varepsilon \circ \varphi_{-\varepsilon}(y) = y$ ) which would simplify considerably the order conditions (similarly to the case of standard composition methods based on a symmetric

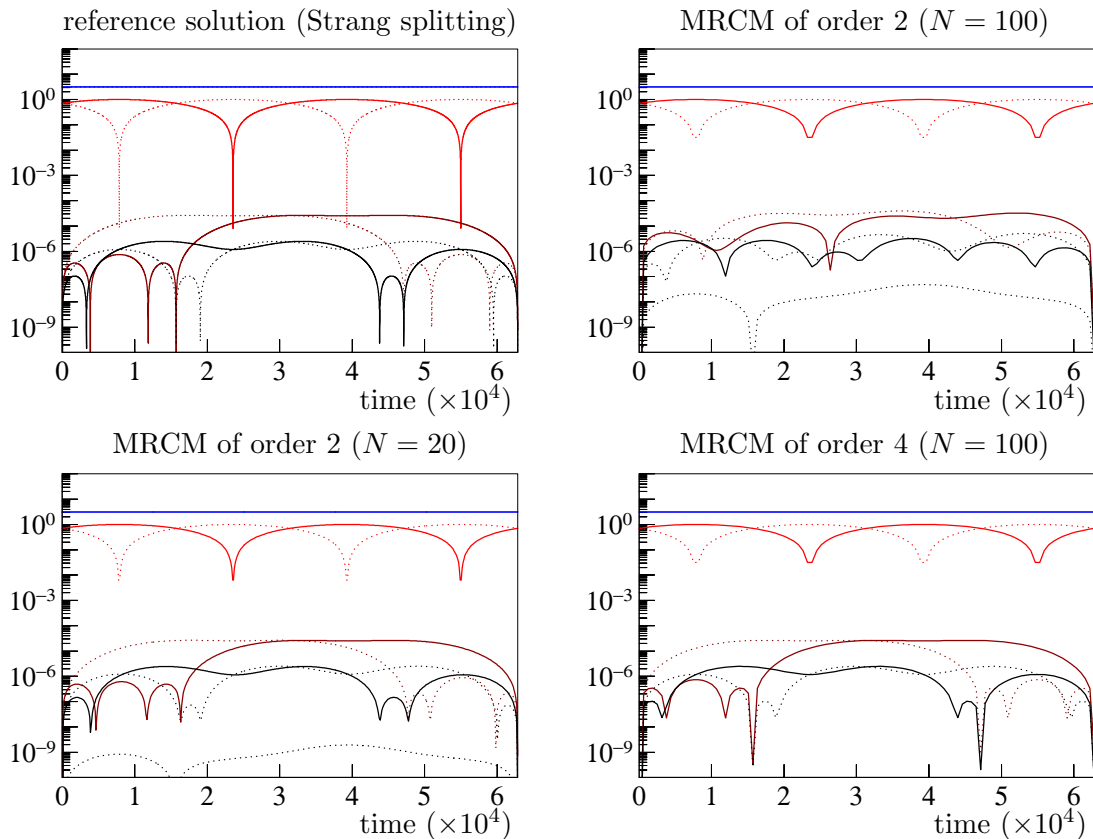


Figure 5: Nonlinear Schrödinger problem (12) with  $\varepsilon = 10^{-4}$  on the time interval  $(0, 2\pi\varepsilon^{-1})$ . Plot of the actions  $|\xi_j(t)|$ , for  $j = 1, 3, 5$  (solid lines) and for  $j = -1, -3, -5$  (dotted lines) with colors red ( $|j| = 1$ ), brown ( $|j| = 3$ ), black ( $|j| = 5$ ). The micro steps size is  $h = 2\pi/n$  with  $n = 100$ .

basic integrator). However, our numerical tests applied to (25) and similar to Fermi-Pasta-Ulam like problems indicate poor performances of the derived methods on time intervals of size  $\mathcal{O}(\varepsilon^{-1})$ . This seems to be related to the fact that the first order averaged ODE (3) corresponding to that particular choice of  $\varphi_\varepsilon$  has unbounded solutions.

## 4.2 Application to the cubic nonlinear Schrödinger equation

In what follows, we consider the nonlinear Schrödinger problem (12) considered in [7] and originally analyzed by B. Grébert and C. Villegas-Blas in [14]. The following nonlinear phenomenon is analysed in [14] and restated in the following Theorem.

**Theorem 4.2.** Consider the Fourier expansion  $u(t, x) = \sum_{k \in \mathbb{Z}} \xi_k(t) e^{ikx}$  of the solution of (12). For all  $\varepsilon$  small enough, one has for all  $|t| \leq \varepsilon^{-9/8}$  the following estimates:

$$\begin{aligned} |\xi_1(t)|^2 &= \frac{1 + \sin(2\varepsilon t)}{2} + \mathcal{O}(\varepsilon^{1/8}), \\ |\xi_{-1}(t)|^2 &= \frac{1 - \sin(2\varepsilon t)}{2} + \mathcal{O}(\varepsilon^{1/8}). \end{aligned}$$

These estimates imply that the energy remains essentially concentrated in Fourier modes  $+1$  and  $-1$  and that modes  $+1$  and  $-1$  exchange their energy periodically (with period  $\pi/\varepsilon$ ). This effect is named “beating effect” in [14]. Another interesting part of the dynamics of this system concerns the modes  $3$  and  $-3$  whose energies scale like  $\varepsilon^2$  and may be regarded for this reason as a “finer” component of the dynamics.

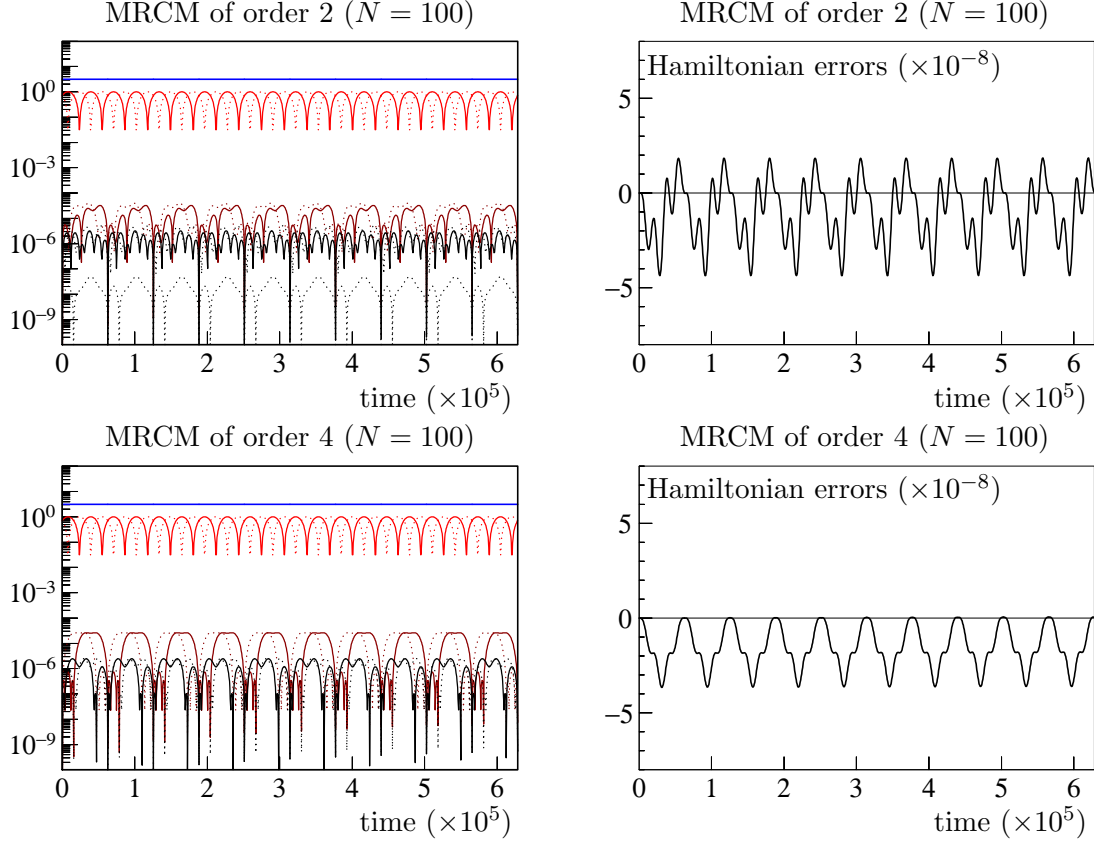


Figure 6: Nonlinear Schrödinger problem (12) with  $\varepsilon = 10^{-4}$  on the time interval  $(0, 20\pi\varepsilon^{-1})$ . Left pictures: actions  $|\xi_j(t)|$ , for  $j = 1, 3, 5$  (solid lines) and for  $j = -1, -3, -5$  (dotted lines) with colors red ( $|j| = 1$ ), brown ( $|j| = 3$ ), black ( $|j| = 5$ ). Right pictures: corresponding Hamiltonian errors. The micro stepsize is  $h = 2\pi/n$  with  $n = 100$ .

We have applied our MRCMs to (12) as indicated in Section 1, using the Strang splitting method with step size  $h = 2\pi/100$  as the micro-integrator  $\Phi_{\mu,h}$ . All MRCMs capture the beating effect whereas only methods of order 2 with moderate  $N$  and of order 4 with possibly larger  $N$  provide satisfactory approximation of modes  $+3$  and  $-3$ . These facts can be clearly observed in Figure 5 which have been obtained by simulating equation (12) on the time interval  $(0, 2\pi\varepsilon^{-1})$  with composition methods of orders 2 ( $s = 1$ ) and 4 ( $s = 4$ ): we have represented in logarithmic scale the modes  $|\xi_j|$  for  $j = \pm 1, \pm 3, \pm 5, \pm 7$  (notice that the even modes  $\xi_{2j}, j \geq 0$  are zero). Here, we consider a spectral Fourier discretization with modes  $\xi_j, j = -64, \dots, 64$ . Modes  $\pm 1$  are of order  $\mathcal{O}(1)$  and the beating effect is well-reproduced by all methods. The energy (thick blue line at the top) is well conserved again by all methods. Modes  $\pm 3$  are of order  $\mathcal{O}(\varepsilon)$ , i.e.  $|\xi_{\pm 3}|^2 = \mathcal{O}(\varepsilon^2)$ , and are well-captured for the second-

order MRCM with moderate values of  $N$  or with the fourth-order MRCM with  $N = 100$ . Although we do not give here theoretical error estimates for PDEs, the qualitative behavior of the dynamics of equation (12) is clearly well reproduced for a computational cost that is significantly smaller as compared to Strang splitting by its own. Here, for  $\varepsilon = 10^{-4}$ , the cost is reduced by a factor 10 for the second-order MRCM and by a factor 16 for the fourth-order MRCM. In Figure 6, we further investigate the behavior of the methods on a time interval ten times larger. We observe that the beating effect is still well captured (left pictures, while an excellent energy conservation (without drift) can be observed (right pictures).

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